

US00RE45905E

(19) **United States**  
(12) **Reissued Patent**  
**Ikeda et al.**

(10) **Patent Number:** **US RE45,905 E**  
(45) **Date of Reissued Patent:** **Mar. 1, 2016**

(54) **VIDEO GAME SYSTEM WITH WIRELESS MODULAR HANDHELD CONTROLLER**

(71) Applicant: **Nintendo Co., Ltd.**, Kyoto (JP)

(72) Inventors: **Akio Ikeda**, Kyoto (JP); **Kuniaki Ito**, Kyoto (JP); **Ryoji Kuroda**, Kyoto (JP); **Genyo Takeda**, Kyoto (JP); **Masahiro Urata**, Kyoto (JP)

(73) Assignee: **Nintendo Co., Ltd.**, Kyoto (JP)

(21) Appl. No.: **14/092,481**

(22) Filed: **Nov. 27, 2013**

**Related U.S. Patent Documents**

Reissue of:

(64) Patent No.: **8,430,753**  
Issued: **Apr. 30, 2013**  
Appl. No.: **13/071,008**  
Filed: **Mar. 24, 2011**

U.S. Applications:

(63) Continuation of application No. 11/532,328, filed on Sep. 15, 2006, now Pat. No. 7,927,216.

(60) Provisional application No. 60/716,937, filed on Sep. 15, 2005.

(51) **Int. Cl.**  
**A63F 13/20** (2014.01)  
**A63F 13/22** (2014.01)

(52) **U.S. Cl.**  
CPC ..... **A63F 13/20** (2014.09); **A63F 13/22** (2014.09)

(58) **Field of Classification Search**  
CPC ..... **A63F 13/02**; **A63F 13/10**; **A63F 13/20**; **A63F 13/218**; **A63F 13/22**; **A63F 13/23**; **A63F 13/235**; **A63F 13/24**; **A63F 13/245**; **A63F 2300/10**; **A63F 2300/1006**; **A63F 2300/1018**; **A63F 2300/105**; **A63F 2300/1056**  
USPC ..... **463/36**, **37**, **38**, **39**  
See application file for complete search history.

(56) **References Cited**

**U.S. PATENT DOCUMENTS**

3,454,920 A 7/1969 Mehr  
3,474,241 A 10/1969 Kuipers  
D220,268 S 3/1971 Kliewer  
3,660,648 A 5/1972 Kuipers  
3,973,257 A 8/1976 Rowe  
4,009,619 A 3/1977 Snyman

(Continued)

**FOREIGN PATENT DOCUMENTS**

CN 1338961 3/2002  
CN 1559644 1/2005

(Continued)

**OTHER PUBLICATIONS**

Office Action in related U.S. Appl. No. 14/694.783 dated Sep. 21, 2015.

(Continued)

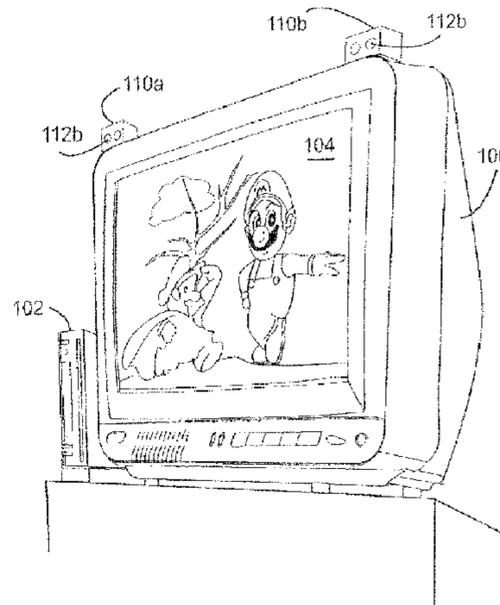
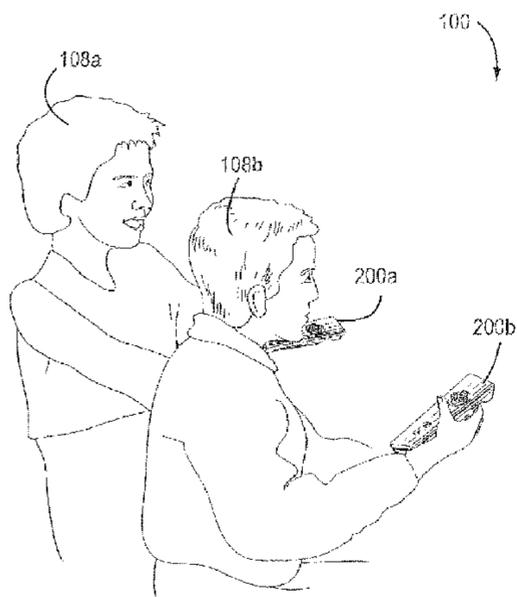
*Primary Examiner* — James S McCellan

(74) *Attorney, Agent, or Firm* — Nixon & Vanderhye P.C.

(57) **ABSTRACT**

A home entertainment system for video games and other applications includes a main unit and handheld controllers. The handheld controllers sense their own motion by detecting illumination emitted by emitters positioned at either side of a display. The controllers can be plugged into expansion units that customize the overall control interface for particular applications including but not limited to legacy video games.

**42 Claims, 27 Drawing Sheets**



(56)

## References Cited

## U.S. PATENT DOCUMENTS

4,038,876 A	8/1977	Morris	5,359,348 A	10/1994	Pilcher et al.
4,166,406 A	9/1979	Maughmer	5,363,120 A	11/1994	Drumm
4,240,638 A	12/1980	Morrison et al.	5,369,580 A	11/1994	Monji et al.
4,287,765 A	9/1981	Kreft	H1383 H	12/1994	Kaplan et al.
4,303,978 A	12/1981	Shaw et al.	5,369,889 A	12/1994	Callaghan
4,318,245 A	3/1982	Stowell et al.	5,373,857 A	12/1994	Hirabayashi et al.
4,321,678 A	3/1982	Krogmann	5,396,265 A	3/1995	Ulrich et al.
4,337,948 A	7/1982	Breslow	5,421,590 A	6/1995	Robbins
4,342,985 A	8/1982	Desjardins	5,430,435 A	7/1995	Hoch et al.
4,402,250 A	9/1983	Baasch	D360,903 S	8/1995	Barr et al.
4,425,488 A	1/1984	Moskin	5,440,326 A	8/1995	Quinn
4,443,866 A	4/1984	Burgiss, Sr.	5,453,758 A	9/1995	Sato
4,450,325 A	5/1984	Luque	D362,870 S	10/1995	Oikawa
4,503,299 A	3/1985	Henrard	5,459,489 A	10/1995	Redford
4,514,600 A	4/1985	Lentz	5,469,194 A	11/1995	Clark et al.
4,514,798 A	4/1985	Lesche	5,481,957 A	1/1996	Paley et al.
4,540,176 A	9/1985	Baer	5,484,355 A	1/1996	King, II et al.
4,546,551 A	10/1985	Franks	5,485,171 A	1/1996	Copper et al.
4,558,604 A	12/1985	Auer	5,490,058 A	2/1996	Yamasaki et al.
4,561,299 A	12/1985	Orlando et al.	5,502,486 A	3/1996	Ueda et al.
4,578,674 A	3/1986	Baker et al.	5,506,605 A	4/1996	Paley
4,623,930 A	11/1986	Oshima et al.	5,512,892 A	4/1996	Corballis et al.
4,672,374 A	6/1987	Desjardins	5,517,183 A	5/1996	Bozeman, Jr.
4,739,128 A	4/1988	Grisham	5,523,800 A	6/1996	Dudek
4,761,540 A	8/1988	McGeorge	5,526,022 A	6/1996	Donahue et al.
4,787,051 A	11/1988	Olson	5,528,265 A	6/1996	Harrison
4,816,810 A	3/1989	Moore	5,531,443 A	7/1996	Cruz
4,839,838 A	6/1989	LaBiche et al.	5,541,860 A	7/1996	Takei et al.
4,849,655 A	7/1989	Bennett	5,551,701 A	9/1996	Bouton et al.
4,851,685 A	7/1989	Dubgen	5,554,033 A	9/1996	Bizzi
4,862,165 A	8/1989	Gart	5,554,980 A	9/1996	Hashimoto et al.
4,914,598 A	4/1990	Krogmann et al.	5,561,543 A	10/1996	Ogawa
4,918,293 A	4/1990	McGeorge	5,563,628 A	10/1996	Stroop
4,957,291 A	9/1990	Miffitt et al.	5,569,085 A	10/1996	Hashimoto et al.
4,961,369 A	10/1990	McGill	D375,326 S	11/1996	Yokoi et al.
4,969,647 A	11/1990	Mical et al.	5,573,011 A	11/1996	Felsing
4,988,981 A	1/1991	Zimmerman et al.	5,574,479 A	11/1996	Odell
4,994,795 A	2/1991	MacKenzie	5,579,025 A	11/1996	Itoh
5,045,843 A	9/1991	Hansen	D376,826 S	12/1996	Ashida
D320,624 S	10/1991	Taylor	5,587,558 A	12/1996	Matsushima
5,059,958 A	10/1991	Jacobs et al.	5,594,465 A	1/1997	Poulachon
5,062,696 A	11/1991	Oshima et al.	5,598,187 A	1/1997	Ide et al.
5,068,645 A	11/1991	Drumm	5,602,569 A	2/1997	Kato
D322,242 S	12/1991	Cordell	5,603,658 A	2/1997	Cohen
D325,225 S	4/1992	Adhida	5,605,505 A	2/1997	Han
5,124,938 A	6/1992	Algrain	5,606,343 A	2/1997	Tsuboyama et al.
5,128,671 A	7/1992	Thomas, Jr.	5,611,731 A	3/1997	Bouton et al.
D328,463 S	8/1992	King et al.	5,615,132 A	3/1997	Horton et al.
5,136,222 A	8/1992	Yamamoto	5,621,459 A	4/1997	Ueda et al.
5,138,154 A	8/1992	Hotelling	5,624,117 A	4/1997	Ohkubo et al.
D331,058 S	11/1992	Morales	5,627,565 A	5/1997	Morishita et al.
5,175,481 A	12/1992	Kanno	D379,832 S	6/1997	Ashida
5,178,477 A	1/1993	Gambaro	5,640,152 A	6/1997	Copper
5,181,181 A	1/1993	Glynn	5,641,288 A	6/1997	Zaenglein, Jr.
5,192,082 A	3/1993	Inoue et al.	5,643,087 A	7/1997	Marcus et al.
5,202,844 A	4/1993	Kamio et al.	5,645,077 A	7/1997	Foxlin et al.
5,207,426 A	5/1993	Inoue et al.	5,645,277 A	7/1997	Cheng
D338,242 S	8/1993	Cordell	5,666,138 A	9/1997	Culver
D340,042 S	10/1993	Copper et al.	5,667,220 A	9/1997	Cheng
5,259,626 A	11/1993	Ho	5,670,845 A	9/1997	Grant et al.
5,262,777 A	11/1993	Low et al.	5,670,988 A	9/1997	Tickle
D342,256 S	12/1993	Payne	5,676,673 A	10/1997	Ferre et al.
5,280,744 A	1/1994	DeCarlo et al.	5,679,004 A	10/1997	McGowan et al.
D345,164 S	3/1994	Grae	5,682,181 A	10/1997	Nguyen et al.
5,296,871 A	3/1994	Paley	5,698,784 A	12/1997	Hotelling et al.
5,307,325 A	4/1994	Scheiber	5,701,131 A	12/1997	Kuga
5,317,394 A	5/1994	Hale et al.	5,702,305 A	12/1997	Norman et al.
5,329,276 A	7/1994	Hirabayashi	5,703,623 A	12/1997	Hall et al.
5,332,322 A	7/1994	Gambaro	5,724,106 A	3/1998	Autry et al.
5,339,095 A	8/1994	Redford	5,726,675 A	3/1998	Inoue
D350,736 S	9/1994	Takahashi et al.	5,734,371 A	3/1998	Kaplan
D350,782 S	9/1994	Barr	5,734,373 A	3/1998	Rosenberg et al.
D351,430 S	10/1994	Barr	5,734,807 A	3/1998	Sumi
5,357,267 A	10/1994	Inoue	D393,884 S	4/1998	Hayami
5,359,321 A	10/1994	Ribic	5,736,970 A	4/1998	Bozeman, Jr.
			5,739,811 A	4/1998	Rosenberg et al.
			5,741,182 A	4/1998	Lipps et al.
			5,742,331 A	4/1998	Uomori et al.
			5,745,226 A	4/1998	Gigioli, Jr.

(56)

References Cited

U.S. PATENT DOCUMENTS

D394,264 S	5/1998	Sakamoto et al.	6,059,576 A	5/2000	Brann
5,746,602 A	5/1998	Kikinis	6,069,594 A	5/2000	Barnes et al.
5,751,273 A	5/1998	Cohen	6,072,467 A	6/2000	Walker
5,752,880 A	5/1998	Gabai et al.	6,072,470 A	6/2000	Ishigaki ..... 345/158
5,757,354 A	5/1998	Kawamura	6,075,575 A	6/2000	Schein et al.
5,757,360 A	5/1998	Nitta et al.	6,081,819 A	6/2000	Ogino
D395,464 S	6/1998	Shiibashi et al.	6,084,315 A	7/2000	Schmitt
5,764,224 A	6/1998	Lilja et al.	6,084,577 A	7/2000	Sato et al.
5,769,719 A	6/1998	Hsu	6,087,950 A	7/2000	Capan
5,771,038 A	6/1998	Wang	D429,718 S	8/2000	Rudolph
D396,468 S	7/1998	Schindler et al.	6,110,039 A	8/2000	Oh
5,785,317 A	7/1998	Sasaki	6,115,028 A	9/2000	Balakrishnan
D397,162 S	8/1998	Yokoi et al.	6,137,457 A	10/2000	Tokuhashi et al.
5,794,081 A	8/1998	Itoh et al.	D433,381 S	11/2000	Talesfore
5,796,354 A	8/1998	Cartabiano et al.	6,146,278 A	11/2000	Kobayashi
5,807,284 A	9/1998	Foxlin	6,148,100 A	11/2000	Anderson et al.
5,819,206 A	10/1998	Horton	6,155,926 A	12/2000	Miyamoto et al.
5,820,462 A	10/1998	Yokoi et al.	6,160,405 A	12/2000	Needle et al.
5,822,713 A	10/1998	Profeta	6,160,540 A	12/2000	Fishkin et al.
5,825,350 A	10/1998	Case, Jr. et al.	6,162,191 A	12/2000	Foxlin
D400,885 S	11/1998	Goto	6,164,808 A	12/2000	Shibata et al.
5,831,553 A	11/1998	Lenssen et al.	6,171,190 B1	1/2001	Thanasack et al.
5,835,077 A	11/1998	Dao	6,176,837 B1	1/2001	Foxlin
5,835,156 A	11/1998	Blonstein et al.	6,181,329 B1	1/2001	Stork et al.
5,841,409 A	11/1998	Ishibashi et al.	6,183,365 B1	2/2001	Tomomura et al.
D402,328 S	12/1998	Ashida	6,184,862 B1	2/2001	Leiper
5,847,854 A	12/1998	Benson, Jr.	6,184,863 B1	2/2001	Sibert et al.
5,850,624 A	12/1998	Gard et al.	6,186,896 B1	2/2001	Takeda et al.
5,854,622 A	12/1998	Brannon	6,191,774 B1	2/2001	Schena et al.
D405,071 S	2/1999	Gambaro	6,198,295 B1	3/2001	Hill
5,867,146 A	2/1999	Kim et al.	6,198,470 B1	3/2001	Agam et al.
5,874,941 A	2/1999	Yamada	6,198,471 B1	3/2001	Cook
5,875,257 A	2/1999	Marrin et al.	6,200,219 B1	3/2001	Rudell et al.
D407,071 S	3/1999	Keating	6,200,253 B1	3/2001	Nishiumi et al.
D407,761 S	4/1999	Barr	6,201,554 B1	3/2001	Lands
5,897,437 A	4/1999	Nishiumi et al.	6,211,861 B1	4/2001	Rosenberg et al.
5,898,421 A	4/1999	Quinn	6,217,450 B1	4/2001	Meredith
5,900,867 A	5/1999	Schindler et al.	6,217,478 B1	4/2001	Vohmann et al.
5,902,968 A	5/1999	Sato et al.	D442,998 S	5/2001	Ashida
D410,909 S	6/1999	Tickle	6,225,987 B1	5/2001	Matsuda
5,912,612 A	6/1999	DeVolpi	6,226,534 B1	5/2001	Aizawa
5,919,149 A	7/1999	Allum	6,238,291 B1	5/2001	Fujimoto et al.
5,923,317 A	7/1999	Sayler et al. .... 345/156	6,239,726 B1	5/2001	Saida
5,926,780 A	7/1999	Fox et al.	6,239,806 B1	5/2001	Nishiumi et al.
5,929,782 A	7/1999	Stark et al.	6,241,611 B1	6/2001	Takeda et al.
D412,940 S	8/1999	Kato	6,243,658 B1	6/2001	Raby
5,947,868 A	9/1999	Dugan	6,244,987 B1	6/2001	Ohsuga et al.
5,955,713 A	9/1999	Titus et al.	6,245,014 B1	6/2001	Brainard, II
5,955,988 A	9/1999	Blonstein et al.	6,264,558 B1	7/2001	Nishiumi et al.
5,956,035 A	9/1999	Sciammarella et al.	6,273,819 B1	8/2001	Strauss et al.
5,967,898 A	10/1999	Takasaka et al.	6,280,327 B1	8/2001	Leifer et al.
5,973,757 A	10/1999	Aubuchon et al.	6,287,198 B1	9/2001	McCauley
5,982,352 A	11/1999	Pryor	6,297,751 B1	10/2001	Fadavi-Ardekani
5,982,356 A	11/1999	Akiyama	6,301,534 B1	10/2001	McDermott, Jr. et al.
5,984,548 A *	11/1999	Willner et al. .... 400/472	6,304,250 B1	10/2001	Yang et al.
5,984,785 A	11/1999	Takeda	6,315,673 B1	11/2001	Kopera et al.
5,986,644 A	11/1999	Herder et al.	6,323,614 B1	11/2001	Palazzolo et al.
5,991,085 A	11/1999	Rallison et al.	6,323,654 B1	11/2001	Needle et al.
5,999,168 A	12/1999	Rosenberg et al.	6,325,718 B1	12/2001	Nishiumi et al.
6,002,394 A	12/1999	Schein et al.	6,331,841 B1	12/2001	Tokuhashi et al.
D419,199 S	1/2000	Cordell et al.	6,331,856 B1	12/2001	Van Hook et al.
D419,200 S	1/2000	Ashida	6,337,954 B1	1/2002	Soshi et al.
6,010,406 A	1/2000	Kajikawa et al.	6,346,046 B2	2/2002	Miyamoto et al.
6,011,526 A	1/2000	Toyoshima et al.	6,347,998 B1	2/2002	Yoshitomi et al.
6,012,980 A	1/2000	Yoshida et al.	6,361,507 B1	3/2002	Foxlin
6,013,007 A	1/2000	Root et al.	D456,410 S	4/2002	Ashida
6,016,144 A	1/2000	Blonstein et al.	6,369,794 B1	4/2002	Sakurai et al.
6,019,680 A	2/2000	Cheng	6,375,572 B1	4/2002	Masuyama et al.
6,020,876 A	2/2000	Rosenberg et al.	6,377,793 B1	4/2002	Jenkins
6,037,882 A	3/2000	Levy	6,377,906 B1	4/2002	Rowe
6,044,297 A	3/2000	Sheldon et al.	D456,854 S	5/2002	Ashida
6,049,823 A	4/2000	Hwang	6,383,079 B1	5/2002	Takeda et al.
6,052,083 A	4/2000	Wilson	6,392,613 B1	5/2002	Goto
6,057,788 A	5/2000	Cummings	6,394,904 B1	5/2002	Stalker
6,058,342 A	5/2000	Orbach et al.	D458,972 S	6/2002	Ashida
			6,400,480 B1	6/2002	Thomas
			6,400,996 B1	6/2002	Hoffberg et al.
			6,409,687 B1	6/2002	Foxlin
			D459,727 S	7/2002	Ashida

(56)

## References Cited

## U.S. PATENT DOCUMENTS

D460,787	S	7/2002	Nishikawa	6,752,719	B2	6/2004	Himoto et al.
6,415,223	B1	7/2002	Lin et al.	6,753,849	B1	6/2004	Curran et al.
6,421,056	B1	7/2002	Nishiumi et al.	6,753,888	B2	6/2004	Kamiwada et al.
6,424,333	B1	7/2002	Tremblay	6,757,068	B2	6/2004	Foxlin
6,426,719	B1	7/2002	Nagareda et al.	6,757,446	B1	6/2004	Li et al.
6,426,741	B1	7/2002	Goldsmith et al.	6,761,637	B2	7/2004	Weston et al.
D462,683	S	9/2002	Ashida	6,765,553	B1	7/2004	Odamura
6,452,494	B1	9/2002	Harrison	D495,336	S	8/2004	Andre et al.
6,456,276	B1	9/2002	Park	6,786,877	B2	9/2004	Foxlin
D464,053	S	10/2002	Zicoello	6,796,177	B2	9/2004	Mori
D464,950	S	10/2002	Fraquelli	6,811,489	B1	11/2004	Shimizu et al.
6,466,198	B1	10/2002	Feinstein	6,811,491	B1	11/2004	Levenberg et al.
6,466,831	B1	10/2002	Shibata et al.	6,812,881	B1	11/2004	Mullaly et al.
6,473,070	B2	10/2002	Mishra et al.	6,813,525	B2	11/2004	Reid et al.
6,473,713	B1	10/2002	McCall et al.	6,813,584	B2	11/2004	Zhou et al.
6,474,159	B1	11/2002	Foxlin et al.	6,816,151	B2	11/2004	Dellinger
6,484,080	B2	11/2002	Breed	6,821,204	B2	11/2004	Aonuma et al.
6,492,981	B1	12/2002	Stork et al.	6,821,206	B1	11/2004	Ishida et al.
6,496,122	B2	12/2002	Sampsell	6,836,705	B2	12/2004	Hellmann et al.
6,518,952	B1	2/2003	Leiper	6,836,751	B2	12/2004	Paxton et al.
6,530,838	B2	3/2003	Ha	6,836,971	B1	1/2005	Wan
6,538,675	B2	3/2003	Aratani et al.	6,842,991	B2	1/2005	Levi et al.
D473,942	S	4/2003	Motoki et al.	6,850,221	B1	2/2005	Tickle
6,540,607	B2	4/2003	Mokris et al.	6,850,844	B1	2/2005	Walters et al.
6,540,611	B1	4/2003	Nagata	6,852,032	B2	2/2005	Ishino
6,544,124	B2	4/2003	Ireland et al.	6,856,327	B2	2/2005	Choi
6,544,126	B2	4/2003	Sawano et al.	D502,468	S	3/2005	Knight et al.
6,545,661	B1	4/2003	Goschy et al.	6,868,738	B2	3/2005	Moscip et al.
6,554,781	B1	4/2003	Carter et al.	6,872,139	B2	3/2005	Sato et al.
D474,763	S	5/2003	Tozaki et al.	6,873,406	B1	3/2005	Hines et al.
6,565,444	B2	5/2003	Nagata et al.	D503,750	S	4/2005	Kit et al.
6,567,536	B2	5/2003	McNitt et al.	D504,677	S	5/2005	Kaminski et al.
6,572,108	B1	6/2003	Bristow	D505,424	S	5/2005	Ashida et al.
6,577,350	B1	6/2003	Proehl et al.	6,897,845	B2	5/2005	Ozawa
6,582,299	B1	6/2003	Matsuyama et al.	6,897,854	B2	5/2005	Cho et al.
6,582,380	B2	6/2003	Kazlausky et al.	6,906,700	B1	6/2005	Armstrong
6,585,596	B1	7/2003	Leifer et al.	6,908,388	B2	6/2005	Shimizu et al.
6,590,536	B1	7/2003	Walton	6,922,632	B2	7/2005	Foxlin
6,591,677	B2	7/2003	Rothuff	6,925,410	B2	8/2005	Narayanan
6,597,342	B1	7/2003	Haruta	6,929,543	B1	8/2005	Ueshima et al.
6,597,443	B2	7/2003	Boman	6,929,548	B2	8/2005	Wang
6,599,194	B1	7/2003	Smith et al.	6,933,861	B2	8/2005	Wang
6,605,038	B1	8/2003	Teller et al.	6,933,923	B2	8/2005	Feinstein
6,608,563	B2	8/2003	Weston et al.	6,954,980	B2	10/2005	Song
6,609,977	B1	8/2003	Shimizu et al.	6,955,606	B2	10/2005	Taho et al.
6,616,607	B2	9/2003	Hashimoto et al.	6,956,564	B1	10/2005	Williams
6,628,257	B1	9/2003	Oka et al.	6,967,566	B2	11/2005	Weston et al.
6,634,949	B1	10/2003	Briggs et al.	6,982,697	B2	1/2006	Wilson et al.
6,636,826	B1	10/2003	Abe et al.	6,984,208	B2	1/2006	Zheng
6,650,029	B1	11/2003	Johnston	6,990,639	B2	1/2006	Wilson
6,650,313	B2	11/2003	Levine et al.	6,993,206	B2	1/2006	Ishino
6,650,345	B1	11/2003	Saito et al.	6,993,451	B2	1/2006	Chang et al.
6,654,001	B1	11/2003	Su	6,995,748	B2	2/2006	Gordon et al.
6,672,962	B1	1/2004	Ozaki et al.	6,998,966	B2	2/2006	Pedersen et al.
6,676,520	B2	1/2004	Nishiumi	7,000,469	B2	2/2006	Foxlin et al.
6,677,990	B1	1/2004	Kawahara	7,002,591	B1	2/2006	Leather et al.
6,681,629	B2	1/2004	Foxlin et al.	7,031,875	B2	4/2006	Ellenby et al.
6,682,351	B1	1/2004	Abraham-Fuchs et al.	7,066,781	B2	6/2006	Weston
6,684,062	B1	1/2004	Gosior et al.	D524,298	S	7/2006	Hedderich et al.
D486,145	S	2/2004	Kaminski et al.	7,081,051	B2	7/2006	Himoto et al.
6,686,954	B1	2/2004	Kitaguchi et al.	7,090,582	B2	8/2006	Danieli et al.
6,692,170	B2	2/2004	Abir	7,098,891	B1	8/2006	Pryor
6,693,622	B1	2/2004	Shahoian et al.	7,098,894	B2	8/2006	Yang et al.
6,712,692	B2	3/2004	Basson et al.	7,102,616	B1	9/2006	Sleator
6,717,573	B1	4/2004	Shahoian et al.	7,107,168	B2	9/2006	Oystol et al.
6,718,280	B2	4/2004	Hermann	7,113,776	B2	9/2006	Miner
6,725,173	B2	4/2004	An et al.	D531,228	S	10/2006	Ashida et al.
D489,361	S	5/2004	Mori et al.	7,115,032	B2	10/2006	Cantu et al.
6,736,009	B1	5/2004	Schwabe	7,126,584	B1	10/2006	Nishiumi et al.
D491,924	S	6/2004	Kaminski et al.	7,127,370	B2	10/2006	Kelly et al.
D492,285	S	6/2004	Ombao et al.	D531,585	S	11/2006	Weitgasser et al.
6,743,104	B1	6/2004	Ota et al.	7,133,026	B2	11/2006	Horie et al.
6,747,632	B2	6/2004	Howard	7,136,674	B2	11/2006	Yoshie et al.
6,747,690	B2	6/2004	Mølgaard	7,139,983	B2	11/2006	Kelts
6,749,432	B2	6/2004	French et al.	7,140,962	B2	11/2006	Okuda et al.
				7,142,191	B2	11/2006	Idesawa et al.
				7,149,627	B2	12/2006	Ockerse et al.
				7,154,475	B2	12/2006	Crew
				7,155,604	B2	12/2006	Kawai

(56)

References Cited

U.S. PATENT DOCUMENTS

7,158,118	B2	1/2007	Liberty	2003/0195041	A1	10/2003	McCauley
7,173,604	B2	2/2007	Marvit et al.	2003/0204361	A1	10/2003	Townsend et al.
7,176,919	B2	2/2007	Drebin et al.	2003/0216176	A1	11/2003	Shimizu et al.
7,182,691	B1	2/2007	Schena	2003/0222851	A1	12/2003	Lai et al.
7,183,480	B2	2/2007	Nishitani et al.	2004/0028258	A1	2/2004	Naimark et al.
7,184,059	B1	2/2007	Fouladi et al.	2004/0034289	A1	2/2004	Teller et al.
D543,246	S	5/2007	Ashida et al.	2004/0048666	A1	3/2004	Bagley
7,220,220	B2	5/2007	Stubbs et al.	2004/0070564	A1	4/2004	Dawson
7,225,101	B2	5/2007	Usuda et al.	2004/0075650	A1	4/2004	Paul et al.
7,231,063	B2	6/2007	Naimark et al.	2004/0095317	A1	5/2004	Zhang et al.
7,233,316	B2	6/2007	Smith et al.	2004/0134341	A1	7/2004	Sandoz et al.
7,236,156	B2	6/2007	Liberty et al.	2004/0140954	A1	7/2004	Faeth
7,239,301	B2	7/2007	Liberty et al.	2004/0143413	A1	7/2004	Oystol et al.
7,261,690	B2	8/2007	Teller et al.	2004/0147317	A1	7/2004	Ito et al.
7,262,760	B2	8/2007	Liberty	2004/0152515	A1	8/2004	Wegmuller et al.
D556,201	S	11/2007	Ashida et al.	2004/0193413	A1	9/2004	Wilson et al.
7,292,151	B2	11/2007	Ferguson et al.	2004/0203638	A1	10/2004	Chan
7,301,527	B2	11/2007	Marvit	2004/0204240	A1	10/2004	Barney
7,301,648	B2	11/2007	Foxlin	2004/0218104	A1	11/2004	Smith et al.
D556,760	S	12/2007	Ashida et al.	2004/0222969	A1	11/2004	Buchenrieder
D559,847	S	1/2008	Ashida et al.	2004/0227725	A1	11/2004	Calarco et al.
D561,178	S	2/2008	Azuma	2004/0229692	A1*	11/2004	Breving ..... 463/36
7,335,134	B1	2/2008	LaVelle	2004/0229693	A1	11/2004	Lind et al.
D563,948	S	3/2008	d'Hore	2004/0239626	A1	12/2004	Noguera
D567,243	S	4/2008	Ashida et al.	2004/0252109	A1	12/2004	Trent et al.
7,359,121	B2	4/2008	French et al.	2004/0254020	A1	12/2004	Dragusin
RE40,324	E	5/2008	Crawford	2004/0259651	A1	12/2004	Storek
7,379,566	B2	5/2008	Hildreth	2004/0268393	A1	12/2004	Hunleth et al.
7,395,181	B2	7/2008	Foxlin	2005/0017454	A1	1/2005	Endo et al.
7,414,611	B2	8/2008	Liberty	2005/0020369	A1	1/2005	Davis et al.
7,445,550	B2	11/2008	Barney et al.	2005/0032582	A1	2/2005	Mahajan
7,488,231	B2	2/2009	Weston	2005/0047621	A1	3/2005	Cranfill
7,500,917	B2	3/2009	Barney et al.	2005/0054457	A1	3/2005	Eyestone et al.
7,510,477	B2	3/2009	Argentar	2005/0070359	A1	3/2005	Rodriquez et al.
7,568,289	B2	8/2009	Burlingham et al.	2005/0076161	A1	4/2005	Albanna et al.
7,582,016	B2	9/2009	Suzuki	2005/0085298	A1	4/2005	Woolston
7,614,958	B2	11/2009	Weston et al.	2005/0107160	A1	5/2005	Cheng et al.
7,663,509	B2	2/2010	Shen	2005/0125826	A1	6/2005	Hunleth et al.
7,774,155	B2	8/2010	Sato et al.	2005/0130739	A1	6/2005	Argentar
7,775,882	B2	8/2010	Kawamura et al.	2005/0134555	A1	6/2005	Liao
7,796,116	B2	9/2010	Salsman	2005/0143173	A1	6/2005	Barney et al.
7,877,224	B2	1/2011	Ohta	2005/0170889	A1	8/2005	Lum et al.
7,905,782	B2	3/2011	Sawano et al.	2005/0172734	A1	8/2005	Alsio
7,927,216	B2	4/2011	Ikeda et al.	2005/0174324	A1	8/2005	Liberty et al.
7,931,535	B2	4/2011	Ikeda et al.	2005/0176485	A1	8/2005	Ueshima
7,942,245	B2	5/2011	Shimizu et al.	2005/0179644	A1	8/2005	Alsio
2001/0008847	A1	7/2001	Miyamoto et al.	2005/0210419	A1	9/2005	Kela
2001/0010514	A1	8/2001	Ishino	2005/0212749	A1	9/2005	Marvit
2001/0015123	A1	8/2001	Nishitani et al.	2005/0212750	A1	9/2005	Marvit
2001/0024973	A1	9/2001	Meredith	2005/0212751	A1	9/2005	Marvit
2001/0031662	A1	10/2001	Larian	2005/0212752	A1	9/2005	Marvit
2001/0045938	A1*	11/2001	Willner et al. .... 345/156	2005/0212753	A1	9/2005	Marvit
2001/0049302	A1	12/2001	Hagiwara	2005/0212754	A1	9/2005	Marvit
2002/0024500	A1	2/2002	Howard	2005/0212755	A1	9/2005	Marvit
2002/0024675	A1	2/2002	Foxlin	2005/0212756	A1	9/2005	Marvit
2002/0028071	A1	3/2002	Mølgaard	2005/0212757	A1	9/2005	Marvit
2002/0072418	A1	6/2002	Masuyama et al.	2005/0212758	A1	9/2005	Marvit
2002/0075335	A1	6/2002	Rekimoto	2005/0212759	A1	9/2005	Marvit
2002/0098887	A1	7/2002	Himoto et al.	2005/0212760	A1	9/2005	Marvit
2002/0103026	A1	8/2002	Himoto et al.	2005/0212764	A1	9/2005	Toba
2002/0107069	A1	8/2002	Ishino	2005/0212767	A1	9/2005	Marvit et al.
2002/0126026	A1	9/2002	Lee	2005/0215295	A1	9/2005	Arneson
2002/0137567	A1	9/2002	Cheng	2005/0215322	A1	9/2005	Himoto et al.
2002/0140745	A1	10/2002	Ellenby et al.	2005/0217525	A1	10/2005	McClure
2002/0158843	A1	10/2002	Levine et al.	2005/0233808	A1	10/2005	Himoto et al.
2002/0183961	A1	12/2002	French et al.	2005/0239548	A1	10/2005	Ueshima et al.
2003/0038778	A1	2/2003	Noguera et al.	2005/0243061	A1	11/2005	Liberty et al.
2003/0052860	A1	3/2003	Park et al.	2005/0243062	A1	11/2005	Liberty
2003/0057808	A1	3/2003	Lee et al.	2005/0253806	A1	11/2005	Liberty et al.
2003/0063068	A1	4/2003	Anton et al.	2005/0256675	A1	11/2005	Kurata
2003/0069077	A1	4/2003	Korienek	2006/0028446	A1	2/2006	Liberty et al.
2003/0083131	A1*	5/2003	Armstrong ..... 463/37	2006/0030385	A1	2/2006	Barney et al.
2003/0107551	A1	6/2003	Dunker	2006/0046849	A1	3/2006	Kovacs
2003/0144056	A1	7/2003	Leifer et al.	2006/0052109	A1*	3/2006	Ashman et al. .... 455/440
2003/0193572	A1	10/2003	Wilson et al.	2006/0092133	A1	5/2006	Touma et al.
				2006/0094502	A1	5/2006	Katayama et al.
				2006/0122474	A1	6/2006	Teller et al.
				2006/0123146	A1	6/2006	Wu et al.
				2006/0146021	A1*	7/2006	Voto et al. .... 345/161

(56)

References Cited

U.S. PATENT DOCUMENTS

2006/0148563	A1	7/2006	Yang	JP	3-059619	11/1991
2006/0152487	A1	7/2006	Grunnet-Jepsen et al.	JP	04-287888	10/1992
2006/0152488	A1	7/2006	Salsman et al.	JP	5-056191	7/1993
2006/0152489	A1	7/2006	Sweetser et al.	JP	2-901476	12/1993
2006/0154726	A1	7/2006	Weston et al.	JP	6-507758	2/1994
2006/0178212	A1	8/2006	Penzias	JP	3-262677	5/1994
2006/0205507	A1	9/2006	Ho	JP	6-154422	6/1994
2006/0231794	A1	10/2006	Sakaguchi et al.	JP	03-000028	7/1994
2006/0252477	A1	11/2006	Zalewski et al.	JP	6-190144	7/1994
2006/0256081	A1	11/2006	Zalewski et al.	JP	6-198075	7/1994
2006/0258452	A1	11/2006	Hsu	JP	3-194841	10/1994
2006/0264258	A1	11/2006	Zalewski et al.	JP	06-77387	10/1994
2006/0264260	A1	11/2006	Zalewski et al.	JP	3-273531	11/1994
2006/0282873	A1	12/2006	Zalewski et al.	JP	6-308879	11/1994
2006/0287086	A1	12/2006	Zalewski et al.	JP	3-228845	1/1995
2006/0287087	A1	12/2006	Zalewski et al.	JP	7-28591	1/1995
2007/0015588	A1	1/2007	Matsumoto et al.	JP	7-44315	2/1995
2007/0021208	A1	1/2007	Mao et al.	JP	7044315	2/1995
2007/0049374	A1	3/2007	Ikeda et al.	JP	7-107573	4/1995
2007/0050597	A1	3/2007	Ikeda et al.	JP	07-22312	5/1995
2007/0052177	A1	3/2007	Ikeda et al.	JP	7-115690	5/1995
2007/0060391	A1	3/2007	Ikeda et al.	JP	7-146123	6/1995
2007/0066394	A1	3/2007	Ikeda et al.	JP	517482	6/1995
2007/0066396	A1	3/2007	Weston et al.	JP	7-200142	8/1995
2007/0072680	A1	3/2007	Ikeda et al.	JP	07-262797	10/1995
2007/0091084	A1	4/2007	Ueshima et al.	JP	7-302148	11/1995
2007/0093291	A1	4/2007	Hulvey	JP	07-318332	12/1995
2007/0159362	A1	7/2007	Shen	JP	8-071252	3/1996
2007/0173705	A1	7/2007	Teller et al.	JP	8-095704	4/1996
2007/0252815	A1	11/2007	Kuo et al.	JP	8-106352	4/1996
2007/0265075	A1	11/2007	Zalewski	JP	08-111144	4/1996
2007/0265076	A1	11/2007	Lin et al.	JP	11-114223	4/1996
2007/0265088	A1	11/2007	Nakada et al.	JP	8-114415	5/1996
2008/0014835	A1	1/2008	Weston et al.	JP	8-122070	5/1996
2008/0015017	A1	1/2008	Ashida et al.	JP	8-152959	6/1996
2008/0039202	A1	2/2008	Sawano et al.	JP	8-211993	8/1996
2008/0121782	A1	5/2008	Hotelling et al.	JP	08-221187	8/1996
2008/0273011	A1	11/2008	Lin	JP	8-305355	11/1996
2008/0278445	A1	11/2008	Sweetser et al.	JP	83-35136	12/1996
2008/0280660	A1	11/2008	Ueshima et al.	JP	9-230997	9/1997
2009/0005166	A1	1/2009	Sato	JP	9-274534	10/1997
2009/0051653	A1	2/2009	Barney et al.	JP	09-319510	12/1997
2009/0124165	A1	5/2009	Weston	JP	10-021000	1/1998
2009/0156309	A1	6/2009	Weston et al.	JP	10-033831	2/1998

FOREIGN PATENT DOCUMENTS

DE	3930581	3/1991		JP	2000-270237	9/2000
DE	19701344	7/1997		JP	2000-308756	11/2000
DE	19701374	7/1997		JP	2001-038052	2/2001
DE	19648487	6/1998		JP	30-78268	4/2001
DE	19814254	10/1998		JP	2001-104643	4/2001
DE	19937307	2/2000		JP	03-080103	6/2001
DE	10029173	1/2002		JP	2001-175412	6/2001
DE	10241392	5/2003		JP	2001-251324	9/2001
DE	10219198	11/2003		JP	2001-306245	11/2001
EP	1 524 334	3/1977		JP	2002-062981	2/2002
EP	0 835 676	4/1998		JP	2002-082751	3/2002
EP	0 848 226	6/1998		JP	2002-091692	3/2002
EP	0 852 961	7/1998		JP	2002-153673	5/2002
EP	1 062 994	12/2000		JP	2002-202843	7/2002
EP	1 279 425	1/2003		JP	2002-224444	8/2002
EP	1 293 237	3/2003		JP	2002-232549	8/2002
EP	0993845	12/2005		JP	2002-233665	8/2002
GB	1524334	9/1978		JP	2002-298145	10/2002
GB	2 244 546	5/1990		JP	2003-053038	2/2003
GB	2284478	6/1995		JP	34-22383	4/2003
GB	2307133	5/1997		JP	2003-208263	7/2003
GB	2316482	2/1998		JP	2003208260 A	7/2003
GB	2319374	5/1998		JP	2003-236246	8/2003
JP	60-077231	5/1985		JP	2003-325974	11/2003
JP	62-14527	1/1987		JP	2004-062774	2/2004
JP	03-74434	7/1991		JP	2004-313429	11/2004
JP	03-08103	8/1991		JP	2004-313492	11/2004
				JP	2004-313492	11/2004
				JP	2005-21458	1/2005
				JP	2005-040493	2/2005
				JP	2005-063230	3/2005

(56)

## References Cited

## FOREIGN PATENT DOCUMENTS

JP	2003-140823	4/2006
JP	2006-113019	4/2006
JP	2002-136694	6/2006
JP	2006-136694	6/2006
JP	2006-216569	4/2007
JP	2007-083024	4/2007
JP	2007-283134	11/2007
NL	9300171	8/1994
RU	2125853	2/1999
RU	2126161	2/1999
RU	2141738	11/1999
WO	94/02931	2/1994
WO	96/05766	2/1996
WO	97/09101	3/1997
WO	97/12337	4/1997
WO	97/17598	5/1997
WO	97/28864	8/1997
WO	97/32641	9/1997
WO	98/11528	3/1998
WO	99/58214	11/1999
WO	00/33168	6/2000
WO	00/35345	6/2000
WO	00/47108	8/2000
WO	00/63874	10/2000
WO	01/87426	11/2001
WO	01/91042	11/2001
WO	02/17054	2/2002
WO	02/34345	5/2002
WO	03/015005	2/2003
WO	03/107260	6/2003
WO	03/088147	10/2003
WO	2004/039055	5/2004
WO	2004/051391	6/2004

## OTHER PUBLICATIONS

European Examination Report issued in EP Application No. 10176870.3 on Aug. 9, 2011.

You et al., Fusion of Vision and Gyro Tracking for Robust Augmented Reality Registration, Proceedings of the Virtual Reality 2001 Conference, 2001, 1-8.

Office Action issued in U.S. Appl. No. 12/285,812 on Nov. 9, 2011. English Abstract for Japanese Patent No. JP10021000, published Jan. 23, 1998.

English Abstract for Japanese Patent No. JP11053994, published Feb. 26, 1999.

English Abstract for Japanese Patent No. JP11099284, published Apr. 13, 1999.

English Abstract for Japanese Patent No. JP2001038052, published Feb. 13, 2001.

English Abstract for Japanese Patent No. JP2002224444, published Aug. 13, 2002.

English Abstract for Japanese Patent No. JP2006136694, published Jun. 1, 2006.

English Abstract for Japanese Patent No. WO9732641, published Sep. 12, 1997.

Acar, "Robust Micromachined Vibratory Gyroscopes" Dissertation (Dec. 2004).

Acar, et al., "Experimental evaluation and comparative analysis of commercial variable-capacitance MEMS accelerometers," *Journal of Micromechanics and Microengineering*, vol. 13 (1), pp. 634-645 (May 2003).

Achenbach, "Golf's New Measuring Stick," *Golfweek*, Jun. 11, 2005, 1 page.

Act Labs: Miacomet Background, 1 page, May 1999, [http://www.act-labs.com/realfeel\\_background/htm](http://www.act-labs.com/realfeel_background/htm).

AirPad Controller Manual (AirPad Corp. 2000).

Airpad Motion Reflex Controller for Sony Playstation-Physical Product (AirPad Corp.2000).

Algrain, "Estimation of 3-D Angular Motion Using Gyroscopes and Linear Accelerometers," *IEEE Transactions on Aerospace and Electronics Systems*, vol. 27, No. 6, pp. 910-920 (Nov. 1991).

Algrain, et al., "Accelerometers Based Line-of-Sight Stabilization Approach for Pointing and Tracking System," *Second IEEE Conference on Control Applications*, vol. 1, Issue 13-16 pp. 159-163 (Sep. 1993).

Algrain, et al., "Interlaced Kalman Filtering of 3-D Angular Motion Based on Euler's Nonlinear Equations," vol. 30, No. 1 (Jan. 1994).

Allen, et al., "A General Method for Comparing the Expected Performance of Tracking and Motion Capture Systems," {VRST} '05: Proceedings of the ACM symposium on Virtual reality software and technology, pp. 201-210 (Nov. 2005).

Allen, et al., "Tracking Beyond 15 minutes of Thought," SIGGRAPH 2001 Course 11 (Course Pack) from Computer Graphics (2001).

Alves, "Extended Kalman filtering applied to a full accelerometer strapdown inertial measurement unit," M.S. Thesis Massachusetts Institute of Technology. Dept. of Aeronautics and Astronautics, Santiago (1992).

Analog Devices Data Sheet, "MicroConvertor®, Multichannel 12-Bit ADC with Embedded Flash MCU, ADuC812" (2013) ([http://www.analog.com/static/imported-files/data\\_sheets/ADUC812.pdf](http://www.analog.com/static/imported-files/data_sheets/ADUC812.pdf)) 60 pages.

Analog Devices "ADXL202E Low-Cost  $\pm 2$  g Dual-Axis Accelerometers with Duty Cycle Output" (Data Sheet), Rev. A (2000).

Analog Devices "ADXL330 Small, Low Power, 3-Axis  $\pm 2$  g iMEMS Accelerometer" (Data Sheet), Rev. PrA (2005).

Analog Devices "ADXL50 Single Axis Accelerometer" (Data Sheet), <http://www.analog.com/en/obsolete/adxl50/products/product.html> (Mar. 1996).

Analog Devices "ADXL50 Monolithic Accelerometer with Signal Conditioning" Datasheet (1996).

Analog Devices "ADXRS150  $\pm 150^\circ/\text{s}$  Single Chip Yaw Rate Gyro with Signal Conditioning" (Data Sheet), Rev. B (2004).

Analog Devices "ADXRS401  $\pm 75^\circ/\text{s}$  Single Chip Yaw Rate Gyro with Signal Conditioning" (Data Sheet), Rev. O (2004).

Ang, et al., "Design and Implementation of Active Error Cancelling in Hand-held Microsurgical Instrument," Proceedings of the 2001 IEEE/RSJ International Conference on Intelligent Robots and Systems, vol. 2, (Oct. 2001).

Ang, et al., "Design of All-Accelerometer Inertial Measurement Unit for Tremor Sensing in Hand-held Microsurgical Instrument," Proceedings of the 2003 IEEE International Conference on Robotics & Automation (Sep. 2003).

Apstolyuk, Vladislav, "Theory and design of micromechanical vibratory gyroscopes," MEMS/NEMS Handbook, Springer, 2006, vol. 1, pp. 173-195 (2006).

Arcanatech, "IMP User's Guide" (1994).

Arcanatech, IMP (Photos) (1994).

Ascension Technology, The Bird 6D Input Devices (specification) (1998).

"ASCII Grip One Handed Controller," *One Switch—ASCII Grip One Handed Playstation Controller*, <http://www.oneswitch.org.uk/1/ascii/grip.htm>, Jul. 11, 2008, pp. 1-2.

"ASCII Grip" One-Handed Controller The Ultimate One-Handed Controller Designed for the Playstation Game Console (ASCII Entertainment 1997).

"ASCII/Sammy Grip V2," *One Switch-Accessible Gaming Shop—ASCII Grip V2*, <http://www.oneswitch.org.uk/1/AGS/AGS-onehand/ascii-grip-v2.html>, Jul. 10, 2008, pp. 1-2.

ASCII, picture of one-handed controller, 2 pages (Feb. 6, 2006).

Ashida et al., entitled "Game Controller," U.S. Appl. No. 11/790,780, filed Apr. 27, 2007, pending.

"At-home fishin!" 1 page, Dec. 1996-1999.

Ator, "Image-Velocity with Parallel-slit Reticles," *Journal of the Optical Society of America* (Dec. 1963).

Azarbayejani, et al., "Real-Time 3-D Tracking of the Human Body," Proceedings of IMAGE'COM 96(1996).

Azarbayejani, et al., "Visually Controlled Graphics," *IEEE Transactions on Pattern Analysis and Machine Intelligence*, vol. 15, No. 6, pp. 602-605 (Jun. 1993).

Azuma et al., "Improving Static and Dynamic Registration in an Optical See-Through HMD," *International Conference on Computer Graphics and Interactive Techniques Proceedings of the 21st annual conference on computer graphics and interactive techniques*, pp. 197-204 (1994).

(56)

## References Cited

## OTHER PUBLICATIONS

- Azuma et al., "Making Augmented Reality Work Outdoors Requires Hybrid Tracking," Proceedings of the International Workshop on Augmented Reality, San Francisco, CA, Nov. 1, 1998, Bellevue, Washington, pp. 219-224 (1999).
- Azuma, "Predictive Tracking for Augmented Reality," Ph.D. Dissertation, University of North Carolina at Chapel Hill (1995).
- Azuma, et al., "A Frequency-Domain Analysis of Head-Motion Prediction," Proceedings of SIGGRAPH '94, pp. 401-408 (1995).
- Azuma, et al., "A motion-stabilized outdoor augmented reality system." Proceedings of IEEE Virtual Reality '99, Houston, TX (Mar. 1999).
- Bachmann et al., "Inertial and Magnetic Posture Tracking for Inserting Humans into Networked Virtual Environments," Virtual Reality Software and Technology archive, Proceedings of the ACM Symposium on Virtual Reality Software and Technology, Baniff, Alberta, Canada, pp. 9-16 (2001).
- Bachmann et al., "Orientation Tracking for Humans and Robots Using Inertial Sensors" (CIRA '99), Naval Postgraduate School, Monterey, CA (1999).
- Bachmann, "Inertial and Magnetic Angle Tracking of Limb Segments for Inserting Humans into Synthetic Environments," Dissertation, Naval Postgraduate School, Monterey, CA (Dec. 2000).
- Baker et al., "Active Multimodal Control of a Floppy Telescope Structure," Proc. SPIE, vol. 4825, 74 (Mar. 2003).
- Balakrishnan, "The Rockin' Mouse: Integral 3D Manipulation on a Plane," CHI '97, Univ. Toronto, (1997).
- Ballagas, et al., Jan, "iStuff: A Physical User Interface Toolkit for Ubiquitous Computer Environments," Proceedings of the SIGCHI Conference on Human Factors in Computing systems, vol. 5, No. 1, at 537-544 (ACM) (Apr. 5-10, 2003).
- Baraff, "An Introduction to Physically Based Modeling," SIGGRAPH 97 Course Notes (1997).
- Bass Fishing "Legends of the Lake", Radica 2 pages, 2002.
- Baudisch, et al., "Soap: a pointing device that works in mid-air" Proc. UIST (2006).
- BBN Report, "Virtual Environment Technology for Training (VETT)," The Virtual Environment and Teloperator Research Consortium (VETREC) (Mar. 1992).
- Behringer, "Improving Registration Precision Through Visual Horizon Silhouette Matching," Proceedings of the international workshop on Augmented reality: placing artificial objects in real scenes: placing artificial objects in real scenes, Bellevue, Washington, United States pp. 225-232 (1999).
- Behringer, "Registration for Outdoor Augmented Reality Applications Using Computer Vision Techniques and Hybrid Sensors," Virtual Reality, 1999 Proceedings., IEEE Computer Society, 244-261 (1999).
- Bei, "BEI Gyrochip™ QRS11 Data Sheet," BEI Systron Donner Inertial Division, BEI Technologies, Inc., (Sep. 1998).
- Benbasat, "An Inertial Measurement Unit for User Interfaces," Massachusetts Institute of Technology Dissertation, (Sep. 2000).
- Benbasat, et al., "An Inertial Measurement Framework for Gesture Recognition and Applications," Gesture and Sign Language in Human-Computer Interaction, International Gesture Workshop, GW 2001, London UK, 2001 Proceedings, LNAI 2298, at 9-20, I. Wachsmuth and T. Sowa (eds.) Springer-Verlag Berlin Heidelberg (2001, 2002).
- Beuter, A., Publications University of Quebec at Montreal, <http://www.er.uqam.ca/nobel/r11040/publicat.htm> (Aug. 2007).
- BGM-109 Tomahawk, [http://en.wikipedia.org/wiki/BGM-109\\_Tomahawk](http://en.wikipedia.org/wiki/BGM-109_Tomahawk), Wikipedia, Jan. 2009.
- Bhatnagar, "Position trackers for Head Mounted Display systems: A survey" (Technical Report), University of North Carolina at Chapel Hill (Mar. 1993).
- Bianchi, "A Tailless Mouse, New cordless Computer Mouse Invented by ArcanaTech." Inc. Article (Jun. 1992).
- Bishop, "The Self-Tracker: A Smart Optical Sensor on Silicon," Ph.D. Dissertation, Univ. of North Carolina at Chapel Hill (1984).
- Bishop, et al., "Grids Progress Meeting" (Slides), University of North Carolina at Chapel Hill, NC (1998).
- Bishop, et al., Self-Tracker: Tracking for Hybrid Environments without Infrastructure (1996).
- Bloomberg: Nintendo Announces Wireless GBA Link, Sep. 2003, 2 pages.
- Bona, et al., "Optimum Reset of Ship's Inertial Navigation System," IEEE Transactions on Aerospace and Electronics Systems (1965).
- Borenstein, et al., "Where am I? Sensors and Methods for Mobile Robot Positioning" (1996).
- Boser, "3-Axis Accelerometer with Differential Sense Electronics," <http://www.eecs.berkeley.edu/~boser/pdf/3axis.pdf> (1997).
- Boser, "Accelerometer Design Example: Analog Devices XL-05/5," <http://www.eecs.berkeley.edu/~boser/pdf/x105.pdf> (1996).
- Bowman et al., *3D User Interfaces: Theory and Practice*, Addison-Wesley, Inc., (2005).
- Bowman, et al., "An Introduction to 3-D User Interface Design," MIT Presence, vol. 10, No. 1 pp. 96-108 (2001).
- Briefs (New & Improved) (Brief Article), PC Magazine, Oct. 26, 1993.
- Britton et al., "Making Nested rotations Convenient for the User," ACM SIGGRAPH Computer Graphics, vol. 12, Issue 3, pp. 222-227 (Aug. 1978).
- Britton, "A Methodology for the Ergonomic Design of Interactive Computer Graphic Systems, and its Application to Crystallography" (UNC Thesis) (1997).
- Brownell, Richard: Review of Peripheral-GameCube-G3 Wireless Controller, GAF, Jul. 17, 2003, 2 pages.
- Buchanan, Levi: "Happy Birthday, Rumble Pak," IGN.com, Apr. 3, 2008, 2 pages.
- Business Wire, "Feature/Virtual reality glasses that interface to Sega channel," Time Warner, TCI: project announced concurrent with COMDEX (Nov. 1994).
- Business Wire, "Free-space'Tilt' Game Controller for Sony Playstation Uses Scenix Chip; SX Series IC Processes Spatial Data in Real Time for On-Screen" (Dec. 1999).
- Business Wire, "InterSense Inc. Launches InertiaCube2—The World's Smallest Precision Orientation Sensor With Serial Interface" (Aug. 14, 2001).
- Business Wire, "Logitech Magellan 3D Controller," Logitech (Apr. 1997).
- Business Wire, "Mind Path Introduces Gyropoint RF Wireless Remote" (Jan. 2000).
- Business Wire, "Pegasus' Wireless PenCell Writes on Thin Air with ART's Handwriting Recognition Solutions," Business Editors/High Tech Writers Telecom Israel 2000 Hall 29, Booth 19-20 (Nov. 2000).
- Business Wire, "RPI ships low-cost HMD Plus 3D Mouse and VR PC graphics card system for CES" (Jan. 1995).
- Buxton, Bill, "Human input/output devices," In M. Katz (ed.), Technology Forecast: 1995, Menlo Park, C.A.: Price Waterhouse World Firm Technology Center, 49-65 (1994).
- Buxton, Bill, A Directory of Sources for Input Technologies, <http://www.billbuxton.com/InputSources.html>, Apr. 2001 (last update 2008).
- Buxton et al., "A Study in Two-Handed Input," ACM CHI '86 Proceedings (1986).
- Byte, "Imp Coexists With Your Mouse," What's New, Arcana Tec (Jan. 1994).
- Canaday, R67-26 "The Lincoln Wand," IEEE Transactions on Electronic Computers, vol. EC-16, No. 2, p. 240 (Apr. 1967).
- Caruso et al., "New Perspective on Magnetic Field Sensing," Sensors Magazine (Dec. 1998).
- Caruso et al., "Vehicle Detection and Compass Applications using AMR Magnetic Sensors," Honeywell (May 1999).
- Caruso, "Application of Magnetoresistive Sensors in Navigation Systems," Sensors and Actuators, SAE SP-1220, pp. 15-21 (Feb. 1997).
- Caruso, "Applications of Magnetic Sensors for Low Cost Compass Systems," Honeywell, SSEC, <http://www.ssec.honeywell.com/magnetic/datasheets/lowcost.pdf> (May 1999).
- Chatfield, "Fundamentals of High Accuracy Inertial Navigation," vol. 174 Progress in Astronautics and Aeronautics, American Institute of Aeronautics and Astronautics, Inc. (1997).

(56)

## References Cited

## OTHER PUBLICATIONS

- Cheng, "Direct interaction with large-scale display systems using infrared laser tracking devices," ACM International Conference Proceeding Series; vol. 142 (2003).
- Cho, et al., "Magic Wand: A Hand-Drawn Gesture Input Device in 3-D Space with Inertial Sensors," Proceedings of the 9th Intl Workshop on Frontiers in Handwriting Recognition (IWFHR-9 2004), IEEE (2004).
- CNET News.com, [http://news.com.com/2300-1043\\_3-6070295-2.html?tag=ne.gall.pg](http://news.com.com/2300-1043_3-6070295-2.html?tag=ne.gall.pg), "Nintendo Wii Swings Into Action," May 25, 2006, 1pg.
- "Coleco Vision: Super Action™ Controller Set," [www.vintagecomputing.com/wp-content/images/retroscan/coleco\\_sac\\_1\\_large.jpg](http://www.vintagecomputing.com/wp-content/images/retroscan/coleco_sac_1_large.jpg). (Sep. 2006).
- Computer Mouse (Wikipedia) (Jul. 5, 2005).
- "Controllers-Atari Space Age Joystick," *Atari Age: Have You Played Atari Today?* [www.atariage.com/controller\\_page.html?SystemID=2600&ControllerID=12](http://www.atariage.com/controller_page.html?SystemID=2600&ControllerID=12). (Sep. 2006).
- "Controllers-Booster Grip," *Atari Age: Have You Played Atari Today?* [www.atariage.com/controller\\_page.html?SystemID=2600&ControllerID=18](http://www.atariage.com/controller_page.html?SystemID=2600&ControllerID=18). (Sep. 2006).
- Computergram, "RPI Entertainment Pods Improve Virtual Experience" (1995).
- Cooke, et al., "NPSNET: flight simulation dynamic modeling using quaternions," *Presence*, vol. 1, No. 4, pp. 404-420, MIT Press (1992/1994).
- Crossan, A. et al.: A General Purpose Control-Based Trajectory Playback for Force-Feedback Systems, University of Glasgow, Dept. Computing Science, 4 pages (Feb. 2008).
- CSIDC Winners—Tablet-PC Classroom System Wins Design Competition, IEEE Computer Society Press, vol. 36, Issue 8, pp. 15-18, IEEE Computer Society (Aug. 2003).
- Cutrone, "Hot products: Gyration GyroPoint Desk, GyroPoint Pro gyroscope-controlled wired and wireless mice" (Computer Reseller News) (Dec. 1995).
- Cutts, "A Hybrid Image/Inertial System for Wide-Area Tracking" (Internal to UNC-CH Computer Science) (Jun. 1999).
- Cyberglove/Cyberforce, Immersion, Cyberforce CyberGlove Systems "Immersion Ships New Wireless CyberGlove(R) II Hand Motion-Capture Glove; Animators, Designers, and Researchers Gain Enhanced Efficiency and Realism for Animation, Digital Prototyping and Virtual Reality Projects," *Business Wire*, Dec. 7, 2005.
- Deruyck, et al. "An Electromagnetic Position Sensor," Polhemus Navigation Sciences, Inc., Burlington, VT (Nov. 1973).
- Dichtburn, "Camera in Direct3D" *Toymaker*, Mar. 5, 2005, 5 pages, <http://web.archive.org/web/20050206032104/http://toymaker.info/games/html/camera.html>.
- Donelson, et al., "Spatial Management of Information" (1978).
- Eißele, "Orientation as an additional User Interface in Mixed-Reality Environments," 1. workshop Erweiterte und Virtuelle Realität, pp. 79-90. GI-Fachgruppe AR/VR (2007).
- Electro-Plankton Weblog, <http://www.tranism.com/weblog/2005/09/>, "This is the Revolution, Nintendo Style," Sep. 15, 2005, 2 pgs.
- "Electronic Plastic: BANDAI—Power Fishing", "Power Fishing Company: BANDAI", 1984, 1 page, <http://www.handhelden.com/Bandai/PowerFishing.html>.
- Emura, et al., "Sensor Fusion Based Measurement of Human Head Motion," 3rd IEEE International Workshop on Robot and Human Communication (Jul. 1994).
- Ewalt, David M., "Nintendo's Wii is a Revolution," *Review*, *Forbes.com* (Nov. 13, 2006).
- Fielder, Lauren: "E3 2001: Nintendo unleashes GameCube software, a new Miyamoto game, and more," *GameSpot*, May 16, 2001, 2 pages, <http://www.gamespot.com/downloads/2761390>.
- Ferrin, "Survey of Helmet Tracking Technologies," *Proc. SPIE* vol. 1456, p. 86-94 (Apr. 1991).
- Fishing Games: The Evolution of Virtual Fishing Games and related Video Games/Computer Games, 15 pages, 2003.
- Foley et al., "Computer Graphics: Principles and Practice," Second Edition, 1990.
- Foremski, T. "Remote Control Mouse Aims at Interactive TV", *Electronics Weekly*, Mar. 9, 1994.
- Foxlin et al., "An Inertial Head-Orientation Tracker with Automatic Drift Compensation for Use with HMD's," Proceedings of the conference on Virtual reality software and technology, Singapore, Singapore, pp. 159-173 (1994).
- Foxlin et al., "Minitaure 6-DOF Inertial System for Tracking HMDs," *SPIE* vol. 3362 (Apr. 1998).
- Foxlin et al., "Miniaturization Calibration & Accuracy Evaluation of a Hybrid Self-Tracker," The Second IEEE and ACM International Symposium on Mixed and Augmented Reality, pp. 151-160 (2003).
- Foxlin et al., "WearTrack: A Self-Referenced Head and Hand Tracker for Wearable Computers and Portable VR," International Symposium on Wearable Computers (ISWC 2000), Oct. 16-18, 2000, Atlanta, GA.
- Foxlin, "FlightTracker: A Novel Optical/Inertial Tracker for Cockpit Enhanced Vision, Symposium on Mixed and Augmented Reality," Proceedings of the 3rd IEEE/ACM International Symposium on Mixed and Augmented Reality, pp. 212-221 (Nov. 2004).
- Foxlin, "Generalized architecture for simultaneous localization, auto-calibration, and map-building," IEEE/RSJ Conf. on Intelligent Robots and Systems, Lausanne, Switzerland (Oct. 2002).
- Foxlin, "Head-tracking Relative to a Moving Vehicle or Simulator Platform Using Differential Inertial Sensors," *InterSense, Inc., Presented: Helmet and Head-Mounted Displays V, SPIE* vol. 4021, AeroSense Symposium, Orlando FL, Apr. 24-25, 2000.
- Foxlin, "Inertial Head Tracker Sensor Fusion by a Complementary Separate-bias Kalman Filter," Proceedings of the IEEE 1996 Virtual Reality Annual International Symposium, pp. 185-194, 267 (1996).
- Foxlin, "Inertial Head-Tracking," MS Thesis, Massachusetts Institute of Technology, Dept. of Electrical Engineering and Computer Science (Sep. 1993).
- Foxlin, "Motion Tracking Requirements and Technologies," Chapter 7, from *Handbook of Virtual Environment Technology*, Stanney Kay, Ed. (2002).
- Foxlin, "Pedestrian Tracking with Shoe-Mounted Inertial Sensors," *IEEE Computer Graphics and Applications*, vol. 25, No. 6, pp. 38-46 (Nov. 2005).
- Foxlin, et al., "Constellation: A Wide-Range Wireless Motion-Tracking System for Augmented Reality and Virtual Set Applications," *ACM SIGGRAPH*, pp. 372-378 (1998).
- Foxlin, et al., "VIS-Tracker: A Wearable Vision-Inertial Self-Tracker," *IEEE Computer Society* (2003).
- Frankie, "E3 2002: Roll O Rama", *IGN: Roll-o-Rama Preview*, . 3 pages. E3 Demo of Kirby game ("Roll O Rama"), <http://cube.ign.com/objects/482/482164.html>, (May 23, 2002).
- Freiburg Center for Data Analysis and Modeling—Publications, <http://www.fdm.uni-freiburg.de/cms/publications/publications/> (Aug. 2007).
- Friedmann, et al., "Device Synchronization Using an Optimal Linear Filter," *SI3D '92: Proceedings of the 1992 symposium on Interactive 3D graphics*, pp. 57-62 (1992).
- Friedmann, et al., "Synchronization in virtual realities," *MIT Presence*, vol. 1, No. 1, pp. 139-144 (1992).
- Fröhlich, "The Yo Yo: An interaction device combining elastic and isotonic control," at <http://www.uni-weimar.de/cms/medien/vr/research/hci/3d-handheld-interaction/the-yoyo-a-handheld-device-combining-elastic-and-isotonic-input.html> (2003).
- FrontSide Field Test, "Get This!", *Golf Magazine*, Jun. 2005, p. 36.
- Fuchs, "Inertial Head-Tracking," *Massachusetts Institute of Technology*, Sep. 1993.
- Furniss, Maureen, "Motion Capture," *MoCap MIT* (Dec. 1999) 12 pages.
- "Game Controller" *Wikipedia*, Aug. 2010, 8 pages, [http://en.wikipedia.org/w/index.php?title=Game\\_controller&oldid=21390758](http://en.wikipedia.org/w/index.php?title=Game_controller&oldid=21390758).
- "Game Controller" *Wikipedia*, Jan. 5, 2005.
- GameCubicle, Jim—New Contributor, Nintendo WaveBird Control, [http://www.gamecubicle.com/news-nintendo\\_gamecube\\_wavebird\\_controller.htm](http://www.gamecubicle.com/news-nintendo_gamecube_wavebird_controller.htm), May 14, 2002.
- Geen et al.: "MEMS Angular Rate-Sensing Gyroscope" pp. 1-3 (2003).

(56)

## References Cited

## OTHER PUBLICATIONS

- Gelmis, J.: "Ready to Play, The Future Way", Jul. 23, 1996, Buffalo News.
- "Get Bass", Videogame by Sega, The International Arcade Museum and the KLOV, 1998, 4 pages.
- "Glove-based input interfaces", Cyberglove/Cyberforce, Jun. 1991, 12 pages <http://www.angelfire.com/ca7/mellott124/glove1.htm>.
- Goschy, "Midway Velocity Controller" (youtube video <http://www.youtube.com/watch?v=wjLhSrSxFNw>) (Sep. 8, 2007).
- Grewal et al., "Global Positioning Systems, Inertial Navigation and Integration," 2001.
- Grimm et al., "Real-Time Hybrid Pose Estimation from Vision and Inertial Data," Proceedings, First Canadian Conference on Computer and Robot Vision, pp. 480-486 (2004).
- Gyration, Inc., GyroRemote and Mobile RF Keyboard User Manual, Saratoga, CA 24 pages, [www.theater.stevejenkins.com/docs/Gyration\\_Keyboard\\_Manual](http://www.theater.stevejenkins.com/docs/Gyration_Keyboard_Manual) (Mar. 9, 2011).
- Gyration, Inc. GyroRemote GP240-01 Professional Series, copyrighted 2003, [www.gyration.com](http://www.gyration.com).
- Gyration Ultra Cordless Optical Mouse, Setting Up Ultra Mouse, Gyration Quick Start Card part No. DL00071-0001 Rev. A. Gyration, Inc. (Jun. 2003).
- Gyration Ultra Cordless Optical Mouse, User Manual, 1-15, Gyration, Inc. Saratoga, CA (2003).
- Gyration, "Gyration GP110 Ultra Cordless Optical Mouse Data Sheet," <http://www.gyration.com/descriptions/document/GP110-SPEC-EN.pdf> (2002).
- Gyration, "Gyration GP110 Ultra Cordless Optical Mouse User Manual," <http://www.gyration.com/descriptions/document/GP110-MANUAL-EN.pdf> (2002).
- Gyration, "Gyration MicroGyro 100 Developer Kit Data Sheet," <http://web.archive.org/web/19980708122611/www.gyration.com/html/devkit.html> (Jul. 1998).
- Gyration, "Gyration Ultra Cordless Optical Mouse," photos (2002). Hamilton Institute, <http://www.dcs.gla.ac.uk/about/rod/>, R. Murray-Smith (Aug. 2007).
- Harada, et al., "Portable Absolute Orientation Estimation Device with Wireless Network under Accelerated Situation" Proceedings, 2004 IEEE International Conference on Robotics and Automation, vol. 2, Issue, Apr. 26-May 1, 2004, pp. 1412-1417 vol. 2 (Apr. 2004).
- Harada, et al., "Portable orientation estimation device based on accelerometers, magnetometers and gyroscope sensors for sensor network," Proceedings of IEEE International Conference on Multisensor Fusion and Integration for Intelligent Systems, MFI2003, pp. 191-196 (Jul. 2003).
- Hartley, Matt, "why is the Nintendo Wii So Successful?", Smarthouse—The Lifestyle Technology Guide Website (Sep. 12, 2007).
- Haykin, et al., "Adaptive Tracking of Linear Time-Variant Systems by Extended RLS Algorithms, IEEE Transactions on Signal Processing," vol. 45, No. 5 (May 1997).
- Heath, "Virtual Reali Resource Guide AI Expert," v9 n5 p. 32(14) (May 1994).
- Hinckley, Ken, "Haptic Issues for Virtual Manipulation," Thesis (Dec. 1996).
- Hinckley, "Synchronous Gestures for Multiple Persons and Computer", CHI Letters vol. 5 No. 2 (ACM 2003) & Proceedings of the 16th Annual ACM UIST 2003 Symposium on User Interface Software & Technology, at 149-58 (UIST '03 Vancouver BC Canada) (ACM) (Nov. 2003).
- Hinckley, et al., "Sensing Techniques for Mobile Interaction," Proceedings of the 13th Annual ACM Symposium on User Interface Software and Technology (San Diego, Cal.), ACM UIST 2000 & Technology, CHI Letters 2 (2), at 91-100 (ACM) (2000).
- Hinckley, Ken, et al., "The VideoMouse: A Camera-Based Multi-Degree-of-Freedom Input Device," CHI Letters vol. 1, 1, UIST '99, Asheville, NC, pp. 103-112 (1999).
- Hinckley, et al., "A Survey of Design Issues in Spatial Input," Proceedings of the ACM Symposium on User Interface Software and Technology (1994).
- Hinckley et al. Stitching: pen gestures that span multiple displays, 2004.
- Hinckley et al.: Synchronous gestures for multiple persons and computers, 2003.
- Hogue, "MARVIN: A Mobile Automatic Realtime Visual and Inertial tracking system," Master's Thesis, York University (2003).
- Hogue, et al., "An optical-inertial tracking system for fully-enclosed VR displays," Proceedings of the 1st Canadian Conference on Computer and Robot Vision, pp. 22-29 (May 2004).
- Holden, Maureen K., et al.: Use of Virtual Environments in Motor Learning and Rehabilitation Department of Brain and Cognitive Sciences, Handbook of Virtual Environments: Design, Implementation, and Applications, Chap. 49, pp. 999-1026, Stanney (ed), Lawrence Erlbaum Associates 2002.
- Holloway, Richard Lee, "Registration Errors in Augmented Reality Systems," Ph.D. Dissertation, University of North Carolina at Chapel Hill (1995).
- House, Matthew, Product Description: Hot Wheels Stunt Track Driver, Hot Wheels (Jan. 2000).
- Hudson Soft, "Brochure of Toukon Road Brave Warrior, Brave Spirits" (1998).
- Hudson Soft—Screen Shot of Brave Spirits (1998).
- Immersion CyberGlove product, Immersion Corporation, 1990, <http://www.cyberglovesystem.com>.
- Inman, "Cheap sensors could capture your every move," <http://technology.newscientist.com/article/dn12963-cheap-sensors-could-capture-your-every-move.html> (Nov. 2007).
- InterSense, "InterSense InertiaCube2 Devices," (Specification) (image) (2001).
- InterSense, "InterSense InertiaCube2 Manual for Serial Port Model" (2001).
- InterSense, InterSense IS 900 Technical Overview—Motion Tracking System, 1999.
- InterSense, "InterSense IS-1200 FlightTracker Prototype Demonstration" (Video) (Nov. 2004).
- InterSense, "InterSense IS-1200 InertiaHawk Datasheet" (2009).
- InterSense, "InterSense IS-1200 VisTracker Datasheet" (2007).
- InterSense, "InterSense IS-1200 VisTracker Devices," (image) (2007).
- InterSense, "InterSense IS-900 Micro Trax™ Datasheet" (2007).
- InterSense, "InterSense IS-900 Systems Datasheet" (2007).
- InterSense, "InterSense MicroTrax Demo Reel," [http://www.youtube.com/watch?v=O2F4fu\\_CISo](http://www.youtube.com/watch?v=O2F4fu_CISo) (2007).
- InterSense, "IS-900 Precision Motion Trackers" [www.isense.com](http://www.isense.com) May 16, 2003.
- InterSense, "InterSense Motion Trackers" [www.isense.com](http://www.isense.com) Mar. 12, 1998.
- InterSense, "InterSense Inc., The New Standard in Motion Tracking" [www.isense.com](http://www.isense.com) Mar. 27, 2004.
- InterSense, "IS-900 Precision Motion Trackers" [www.isense.com](http://www.isense.com) Sep. 10, 2002.
- InterSense, "IS-900 Product Technology Brief," [http://www.intersense.com/uploadedFiles/Products/White\\_Papers/IS900\\_Tech\\_Overview\\_Enhanced.pdf](http://www.intersense.com/uploadedFiles/Products/White_Papers/IS900_Tech_Overview_Enhanced.pdf) (1999).
- InterSense, Inc., "Comparison of InterSense IS-900 System and Optical Systems," [http://www.intersense.com/uploadedFiles/Products/White\\_Papers/Comparison%20of%20InterSense%20IS-900%20System%20and%20Optical%20Systems.pdf](http://www.intersense.com/uploadedFiles/Products/White_Papers/Comparison%20of%20InterSense%20IS-900%20System%20and%20Optical%20Systems.pdf) (Jul. 12, 2004).
- Izumori et al, High School Algebra: Geometry (1986) (高等学校の代数・幾何 改訂版).
- Jacob, "Human-Computer Interaction—Input Devices" <http://www.cs.tufts.edu/~jacob/papers/surveys.html>, "Human-Computer Interaction: Input Devices," ACM Computing Surveys, vol. 28, No. 1, pp. 177-179 (Mar. 1996).
- Jakubowski, et al., "Increasing Effectiveness of Human Hand Tremor Separation Process by Using Higher-Order Statistics," Measurement Science Review, vol. 1 (2001).
- Jakubowski, et al., "Higher Order Statistics and Neural Network for Tremor Recognition," IEEE Transactions on Biomedical Engineering, vol. 49, No. 2 (Feb. 2002).

(56)

## References Cited

## OTHER PUBLICATIONS

- Ji, H.: "Study on the Infrared Remote-Control Lamp-Gesture Device", *Yingyong Jiguang/Applied Laser Technology*, v. 17, n. 5, p. 225-227, Oct. 1997 Language: Chinese—Abstract only.
- Jian, et al., "Adaptive Noise Cancellation," Rice University, <http://www.ece.rice.edu/about.klwang/elec434/elec434.htm>, (Aug. 2007).
- Jiang, "Capacitive position-sensing interface for micromachined inertial sensors," Dissertation at Univ. of Cal. Berkeley (2003).
- Ju, et al., "The Challenges of Designing a User Interface for Consumer Interactive Television Consumer Electronics Digest of Technical Papers.," IEEE 1994 International Conference on Volume , Issue , Jun. 21-23, 1994 pp. 114-115 (Jun. 1994).
- Kalawsky, "The Science of Virtual Reality and Virtual Environments," 1993.
- Keir, et al., "Gesture-recognition with Non-referenced Tracking," IEEE Symposium on 3D User Interfaces, pp. 151-158 (Mar. 25-26, 2006).
- Kennedy, P.J., "Hand-Held Data Input Device," IBM Technical Disclosure Bulletin, vol. 26, No. 11, pp. 5826-5827 (Apr. 1984).
- Kessler, et al., "The Simple Virtual Environment Library" (MIT Presence) (2000).
- Kindratenko, "A Comparison of the Accuracy of an Electromagnetic and a Hybrid Ultrasound-Inertia Position Tracking System," MIT Presence, vol. 10, No. 6, Dec. 2001, 657-663 (2001).
- Klein et al., "Tightly Integrated Sensor Fusion for Robust Visual Tracking," *British Machine Vision Computing*, vol. 22, No. 10, pp. 769-776 (2004).
- Kohler, "Triumph of the Wii: How Fun Won Out in the Console Wars," [www.wired.com/print/gaming/hardware/news/2007/06/wii](http://www.wired.com/print/gaming/hardware/news/2007/06/wii). (Jun. 2007).
- Kohlhase, "NASA Report, The Voyager Neptune Travel guide," Jet Propulsion Laboratory Publication 89-24, excerpt (Jun. 1989).
- Krumm, et al., "How a Smart Environment Can Use Perception," *Ubicomp 2001* (Sep. 2001).
- Kuipers, Jack B., "SPASYN—An Electromagnetic Relative Position and Orientation Tracking System," *IEEE Transactions on Instrumentation and Measurement*, vol. 29, No. 4, pp. 462-466 (Dec. 1980).
- Kunz, Andreas M. et al., "Design and Construction of a New Haptic Interface," *Proceedings of DETC '00, ASME 2000 Design Engineering Technical Conferences and Computers and Information in Engineering Conference*, Baltimore, Maryland (Sep. 10-13, 2000).
- La Scala, et al., "Design of an Extended Kalman Filter Frequency Tracker," *IEEE Transactions on Signal Processing*, vol. 44, No. 3 (Mar. 1996).
- Larimer et al., "VEWL: A Framework for building a Windowing Interface in a Virtual Environment," in *Proc. of IFIP TC13 Int. Conf. on Human-Computer Interaction Interact'2003* (Zürich, [http://people.cs.vt.edu/~bowman/papers/VEWL\\_final.pdf](http://people.cs.vt.edu/~bowman/papers/VEWL_final.pdf)) (2003).
- Laughlin, et al., "Inertial Angular Rate Sensors: Theory and Applications," *Sensors Magazine* (Oct. 1992).
- Lee et al., "Tilta-Pointer: the Free-Space Pointing Device," Princeton COS 436 Project, <http://www.milyhuang.com/cos436/project/soecs.html> (2004).
- Lee, et al., "Innovative Estimation Method with Measurement Likelihood for all-Accelerometer Type Inertial Navigation Systems," vol. 38, No. 1 (Jan. 2002).
- Lee, et al., "Two-Dimensional Position Detection System with MEMS Accelerometer for Mouse Applications" *Design Automation Conference, 2001. Proceedings, 2001* pp. 852-857 (Jun. 2001).
- Leganchuk et al., "Manual and Cognitive Benefits of Two-Handed Input: An Experimental Study," *ACM Transactions on Computer-Human Interaction*, vol. 5, No. 4, pp. 326-359 (Dec. 1998).
- Leonard, "Computer Pointer Controls 3D Images in Free Space," *Electronics Design*, pp. 160, 162, 165, (Nov. 1991).
- Liang, et al., "On Temporal-Spatial Realism in the Virtual Reality Environment," *ACM 1991 Symposium on User Interface Software and Technology* (Nov. 1991).
- Link, "Field-Qualified Silicon Accelerometers From 1 Milli g to 200,000 g," *Sensors* (Mar. 1993).
- Liu, et al., "Enhanced Fisher Linear Discriminant Models for Face Recognition," *Proc. 14. sup.th International Conference on Pattern Recognition*, Queensland, Australia (Aug. 1998).
- Lobo et al., "Vision and Inertial Sensor Cooperation Using Gravity as a Vertical Reference," *IEEE Trans. on Pattern Analysis and Machine Intelligence*, vol. 25, No. 12, pp. 1597-1608 (Dec. 2003).
- Logitech, *Logitech 2D/6D Mouse Devices Specification* (1991).
- Logitech, "Logitech 2D/6D Mouse Technical Reference Manual" (1991).
- Logitech, Inc., "3D Mouse & Head Tracker Technical Reference Manual" (1992).
- Logitech WingMan Cordless Rumblepad, Logitech, Press Release Sep. 2, 2001, 2 pages.
- Louderback, Jim, "Nintendo Wii," *Reviews by PC Magazine*, (Nov. 13, 2006).
- "LPC2104/2105/2106, Single-chip 32-bit microcontrollers; 128 kB ISP/IAP Flash with 64 kB/32 kB/ 16 KB RAM", Phillips, Dec. 22, 2004; 32 pages.
- Luinge, *Inertial sensing of human movement*, Thesis, University of Twente (2002).
- Luinge, et al., "Estimation of orientation with gyroscopes and accelerometers," *Proceedings of the First Joint BMES/EMBS Conference*, 1999., vol. 2, p. 844 (Oct. 1999).
- Luthi, P. et al., "Low Cost Inertial Navigation System," and translation (2000).
- MacKenzie et al., "A two-ball mouse affords three degrees of freedom," *Extended Abstracts of the CHI '97 Conference on Human Factors in Computing Systems*, pp. 303-304. New York: ACM (1997).
- MacKinlay, "Rapid Controlled Movement Through a Virtual 3D Workspace," *ACM SIGGRAPH Computer Graphics archive* vol. 24, No. 4, pp. 171-176 (Aug. 1990).
- MacLean, "Designing with Haptice Feedback", *Proceedings of IEEE Robotics and Automation (ICRA '2000)*, at 783-88 (Apr. 22-28, 2000).
- MacLean, Karen, *Publications and patents, bibliography* (Nov. 2006).
- Maggioni, C., "A novel gestural input device for virtual reality", *IEEE Virtual Reality Annual International Symposium*, 118-24, 1993.
- Markey et al., "The Mechanics of Inertial Position and Heading Indication," *Massachusetts Institute of Technology*, 1961.
- Marti et al., "Biopsy navigator: a smart haptic interface for interventional radiological gestures", *International Congress Series*, vol. 1256, Jun. 2003, 6 pages.
- Marrin, "Possibilities for the Digital Baton as a General-Purpose Gestural Interface", *Late-Breaking/Short Talks. CHI 97*, Mar. 22-27, 1997 (pp. 311-312).
- Marrin, Teresa et al.: "The Digital Baton: a Versatile Performance Instrument" (1997).
- Marrin, Teresa: "Toward an Understanding of Musical Gesture: Mapping Expressive Intention with the Digital Baton" (1996).
- Maslah, "Measuring the Allocation of Control in 6 Degree of Freedom Huma-Computer Interaction Tasks," *Proceedings of the SIGCHI conference on Human factors in computing systems*, pp. 25-32 (2001).
- Maybeck, "Stochastic Models, Estimation and Control," vol. 1, *Mathematics in Science and Engineering*, vol. 141 (1979).
- "MEMS enable smart golf clubs" *Small Times—MEMS enable smart golf clubs*, Jan. 6, 2005, 2 pages.
- Merians, Alam S. et al.: "Virtual Reality-Augmented Rehabilitation for Patients Following Stroke," *Physical Therapy*, vol. 82, No. 9 (Sep. 2002).
- Merrill, "FlexGesture: A sensor-rich real-time adaptive gesture and affordance learning platform for electronics music control," Thesis, *Massachusetts Institute of Technology* (Jun. 2004).
- Meyer et al., "A Survey of Position Tracker," vol. 1, Issue 2, pp. 173-200, MIT Presence, (1992).
- Microsoft Research Corp., "XWand Device" (image) (Apr. 2009).
- Miles, "New pads lack control," *The Times*, Dec. 6, 1999.
- Mizell, "Using Gravity to Estimate Accelerometer Orientation," *IEEE Computer Society* (2003).

(56)

## References Cited

## OTHER PUBLICATIONS

- Morgan, C.; "Still chained to the overhead projector instead of the podium? (TV Interactive Corp's LaserMouse Remote Pro infrared mouse) (Clipboard)(Brief Article) (Product Announcement)", *Government Computer News*, Jun. 13, 1994.
- Morris, "Accelerometry—a technique for the measurement of human body movements," *J Biomechanics* 6: 729-736 (1973).
- Moser, "Low Budget Inertial Navigation Platform (2000)," [www.tmoser.ch/typo3/11.0.html](http://www.tmoser.ch/typo3/11.0.html), Oct. 2008.
- Mulder, "How to Build an Instrumental Glove Based on the Powerglove Flex Sensors," *PCVR* 16, pp. 10-14 (1994).
- Mulder, "Human movement tracking technology," School of Kinesiology, Simon Fraser University (Jul. 1994).
- Myers, et al., "Interacting at a Distance: Measuring the Performance of Laser Pointers and Other Devices," *CHI 2002*, (Apr. 2002).
- N.I.C.E., "The N.I.C.E. Project" (video), (1997) <http://www.niceproject.com/>.
- Naimark, et al., "Circular Data Matrix Fiducial System and Robust Image Processing for a Wearable Vision-Inertial Self-Tracker," *Proceedings. International Symposium on Mixed and Augmented Reality, ISMAR* (2002).
- Naimark, et al., "Encoded LED System for Optical Trackers," *Fourth IEEE and ACM International Symposium on Mixed and Augmented Reality*, pp. 150-153 (2005).
- Navarrete, et al., "Eigenspace-based Recognition of Faces: Comparisons and a new approach," *Image Analysis and Processing* (2001).
- Newswire PR, "Five New Realities to Carry Gyration's Gyropoint Point and Gyropoint Pro" (1996).
- Newswire PR, "Three-Axis MEMS-based Accelerometer From STMicroelectronics Targets Handheld terminals," *STMicro* (Feb. 2003).
- Nichols, "Geospatial Registration of Information for Dismounted Soldiers (GRIDS)," *Contractor's Progress, Status, and Management Report (Milestone 3 Report to DARPA ETO)* (Oct. 1998).
- Nintendo, G3 Wireless Controller (Pelican) (2001).
- Nintendo, Game Boy Advance SP System (2003).
- Nintendo, GameBoy Color (1998).
- Nintendo Game Boy, *Consumer Information and Precautions Booklet*, Nintendo, Jul. 31, 1969.
- Nintendo, GameCube Controller (2001).
- Nintendo, GameCube System and Controller (2001).
- Nintendo, NES Controller (1984).
- Nintendo, NES Duck Hunt Game (1984).
- Nintendo, NES System and Controllers (1984).
- Nintendo, NES Zapper Guns (1984).
- Nintendo, Nintendo 64 Controller (1996).
- Nintendo, Nintendo 64 System (N64) (1996).
- Nintendo, Nintendo 64 System and Controllers (1996).
- Nintendo, Nintendo Entertainment System (NES) (1984).
- Nintendo, Nintendo Game Boy Advance (2001).
- Nintendo, Nintendo Game Boy Advance System (2001).
- Nintendo, Nintendo Game Boy Advance Wireless Adapter (Sep. 26, 2003).
- Nintendo, Nintendo Game Boy Color Cartridge with Built-In Rumble (Jun. 28, 2009).
- Nintendo, Nintendo GameBoy Color System (1998).
- Nintendo, Nintendo GameBoy System (1989).
- Nintendo, Nintendo GameCube System (2001).
- Nintendo, Nintendo N64 Controller with Rumble Pack (1996-1997).
- Nintendo, Nintendo N64 Rumble Packs (1996-1997).
- Nintendo, Nintendo Super NES (SNES) (1991).
- Nintendo, Nintendo: Kirby Tilt & Tumble game, packaging and user manual (Aug. 2000-2001).
- Nintendo, Nintendo: WarioWare: Twisted tame, sackatint and user manual (2004-2005).
- Nintendo, Pokeman Pinball (1998).
- Nintendo, SNES Superscope (1991).
- Nintendo, SNES System & Controllers (1991).
- Nintendo, Wavebird Wireless Controllers (May 2002).
- Nintendo, Wavebird Controller, Nintendo, Jun. 2010 Wikipedia Article, <http://en.wikipedia.org/wiki/WaveBird>.
- Nintendo, Nintendo Entertainment System Consumer Information and Precautions Booklet, Nintendo of America, Inc. 1992.
- Nintendo, Nintendo Entertainment System Instruction Nintendo of America, Inc. 1992.
- Nintendo, Nintendo Entertainment System Booth 2002.
- Nintendo, Nintendo Entertainment System Layout, May 9, 2002.
- Nintendo, Nintendo Feature: History of Pokeman Part 2, Official Nintendo Magazine May 17, 2009, <http://www.officialnintendomagazine.co.uk/article.php?id=8576>.
- Nishiyama, "A Nonlinear Filter for Estimating a Sinusoidal Signal and its Parameters in White Noise: On the Case of a Single Sinusoid," *IEEE Transactions on Signal Processing*, vol. 45, No. 4 (Apr. 1997).
- Nishiyama, "Robust Estimation of a Single Complex Sinusoid in White Noise-H.infin, Filtering Approach," *IEEE Transactions on Signal Processing*, vol. 47, No. 10 (Oct. 1999).
- Odell, "An Optical Pointer for Infrared Remote Controllers," *Proceedings of International Conference on Consumer Electronics* (1995).
- Odell, Transcript of Testimony, Investigation No. 337-TA-658, Before the United States International Trade Commission, vol. IV, redacted (May 14, 2009).
- Ogawa et al., "Wii are the Elite," *GameSpot* web site (Feb. 5, 2008).
- Ojeda, et al., "No GPS? No Problem!" University of Michigan Development Award-Winning Personal Dead-Reackoning (PDR) System for Walking Users, [http://www.engin.umich.edu/research/mrl/urpr/In\\_Press/P135.pdf](http://www.engin.umich.edu/research/mrl/urpr/In_Press/P135.pdf) (post 2004).
- OLPC, "One Laptop Per Child," [wiki.laptop.org/go/One\\_Laptop\\_per\\_Child](http://wiki.laptop.org/go/One_Laptop_per_Child) (May 2009).
- Omelyan, "On the numerical integration of motion for rigid polatomics: The modified quaternion approach" *Computers in Physics*, vol. 12 No. 1, pp. 97-103 (1998).
- Ovaska, "Angular Acceleration Measurement: A Review," *Instrumentation and Measurement Technology Conference, Conference Proceedings. IEEE*, vol. 2 (Oct. 1998).
- PAD-Controller and Memory I/F in Playstation (Apr. 17, 1995; Jan. 12, 2002).
- Pai, et al., "The Tango: A Tangible Tangoreceptive Whole-Hand Interface," *Proceedings of World Haptics and IEEE Eurohaptics Conference, Symposium on Haptic Interfaces for Virtual Environment and Teleoperator Systems* (2005).
- Paley, W. Bradford, "Interaction in 3D Graphics," *SIGGRAPH Computer Graphics Newsletter, Cricket input device* (Nov. 1998).
- Paradiso, et al., "Interactive Therapy with Instrumented Footwear," *CHI 2004*, Apr. 24-29, 2004, Vienna, Austria (2004).
- Paradiso, Joseph A., "The Brain Opera Technology: New Instruments and Gestural Sensors for Musical Interaction and Performance" (Nov. 1998) ("Brain Opera Article").
- Park, Adaptive control strategies for MEMS gyroscopes (Dissertation), Univ. Cal. Berkley (2000).
- PC World, "The 20 Most Innovative Products of the Year" (Dec. 27, 2006).
- Perry Simon: "Nintendo to Launch Wireless Game Boy Adaptor," *Digital Lifestyles*, Sep. 26, 2003 <http://digital-lifestyles.info/2003/09/26/nintendo-to-launch-wireless-game-boy-adaptor/>.
- Pham, Hubert "Pointing in Intelligent Environments with WorldCursor," *Proceedings of Internet 2003*, Andrew Wilson (2003).
- Phillips, "Forward/Up Directional Incompatibilities During Cursor Placement Within Graphical User Interfaces," *Ergonomics, informaworld.com* (May 2005).
- Phillips, "On the Right Track: A unique optical tracking system gives users greater freedom to explore virtual worlds" (Apr. 2000).
- Photographs of prior art ASCII Grip V2 Controller, (ASCII/Sammy Grip V2 One Switch-Accessible Gaming Shop-ASCII Grip V2, <http://www.oneswitch.org.uk/1/AGS/AGS-onehand/ascii-grip-v2.html>, Jul. 10, 2008, pp. 1-2.).
- Pierce et al., "Image Plane Interaction Techniques in 3D Immersive Environments," *Proceedings of the 1997 symposium on Interactive 3D graphics*, [portal.acm.org](http://portal.acm.org) (1997).
- Pilcher, "AirMouse Remote Controls," *IEEE Conference on Consumer Electronics* (1992).

(56)

## References Cited

## OTHER PUBLICATIONS

- Pique, "Semantics of Interactive Rotations," *Interactive 3D Graphics, Proceedings of the 1986 workshop on Interactive 3D graphics*, pp. 259-269 (Oct. 1986).
- Piyabongkarn, "Development of a MEMS Gyroscope for Absolute Angle Measurement," *IEEE Transactions on Control Systems Technology*, vol. 13, Issue 2, pp. 185-195 (Mar. 2005).
- Piyabongkarn, "Development of a MEMS Gyroscope for Absolute Angle Measurement," *Dissertation, Univ. Minnesota* (Nov. 2004).
- Pokeman Pinball Game, 1999, *Wikipedia Article*, [http://www.en.wikipedia.org/wiki/Pok%C3%A9mon\\_Pinball](http://www.en.wikipedia.org/wiki/Pok%C3%A9mon_Pinball).
- Polhemus, "Polhemus 3Space FASTRAK devices" (image) (2000).
- Polhemus: "FASTRACK, The Fast and Easy Digital Tracker" copyrighted 2001, Coldiester, Vermont 2 pages.
- PowerGlove product Program Guide, Mattel, 1989.
- PowerGlove product, Mattel, 1989 *Wikipedia Article*.
- PowerGlove product, Instructions, Mattel, 1989.
- Pryor et al., "A Reusable Software Architecture for Manual Controller Integration," *IEEE conf. on Robotics and Automation, Univ of Texas* (Apr. 1997).
- Raab et al., "Magnetic Position and Orientation Tracking System," *IEEE Transactions on Aerospace and Electronics Systems*, vol. AES-15, No. 5, pp. 709-718 (Sep. 1979).
- Raethjen, et al., "Tremors Analysis in Two Normal Cohorts," *Clinical Neurophysiology* 115 (2004).
- Rebo, "Helmet-Mounted virtual environment display system," *Thesis, AirForce Institute of Technology, Defense Technical Information Center* (Dec. 1988).
- Rebo, et al., "Helmet-Mounted Virtual Environment Display System," *Proc. SPIE* vol. 1116, pp. 80-84 (Sep. 1989).
- Regan, "Smart Golf Clubs", *The Baltimore Sun*. Jun. 17, 2005, 1 page.
- Rekimoto, "Tilting Operations for Small Screen Interface," *Proceedings of the 9th Annual ACM Symposium on User Interface Software and Technology*, pp. 167-168 (1996).
- Reunert, "Fiber-Optic Gyroscopes: Principles and Applications," *Sensors*, (Aug. 1993).
- Ribo, et al., "Hybrid Tracking for Outdoor Augmented Reality Applications," *IEEE Computer Graphics and Applications*, vol. 22, No. 6, pp. 54-63 (Nov./Dec. 2002).
- Riviere, Cameron Testimony, Trial Day 5, In the Matter of Certain Video Game Machines and Related Three-Dimensional Pointing Devices, ITC Investigation No. 337-TA-658 (May 15, 2009).
- Riviere, C., Robotics Institute, <http://www.ri.cmu.edu/people/riviere.sub--cameron.html> [http://www.ri.cmu.edu/person.html?type=publications&person\\_id=248](http://www.ri.cmu.edu/person.html?type=publications&person_id=248) (Aug. 2007).
- Riviere, et al., "Adaptive Canceling of Physiological Tremor for Improved Precision in Micorsurgery," *IEEE Transactions on Biomedical Engineering*, vol. 45, No. 7 (Jul. 1998).
- Riviere, et al., "Toward Active Tremor Canceling in Handheld Microsurgical Instruments," *IEEE Transactions on Robotics and Automation*, vol. 19, No. 5 (Oct. 2003).
- Roberts, "The Lincoln Wand," *AFIPS Conference Proceedings, MIT Lincoln Laboratory* (1966).
- Robinett et al., "Implementation of Flying, Scaling, and Grabbing in Virtual Worlds," *ACM Symposium* (1992).
- Robinett et al., "The Visual Display Transformation for Virtual Reality," *University of North Carolina at Chapel Hill* (1994).
- Robotics Research Group, "Robot Design: Robot Manual Controller Design," *The University of Texas of Austin*, May 2009.
- Roetenberg, "Inertial and magnetic sensing of human motion," *Thesis* (2006).
- Roetenberg, et al., "Inertial and Magnetic Sensing of Human Movement Near Ferromagnetic Materials," *Proceedings. The Second IEEE and ACM International Symposium on Mixed and Augmented Reality* (Mar. 2003).
- Rolland, et al., "A Survey of Tracking Technology for Virtual Environments," *University of Central Florida, Center for Research and Education in Optics Lasers (CREOL)* (2001).
- Sakai, et al., "Optical Spatial Filter Sensor for Ground Speed," *Optical Review*, vol. 2, No. 1 pp. 65-67 (1994).
- Satterfield, Shane, E3 2002: Nintendo announces new GameCube games, *GameSpot*, May 21, 2002, [http://www.gamespot.com/gamecube/action/rollarama/new.html?sid=2866974&com\\_act\\_convert&om\\_clk=nesfeatures&tag=newsfeatures%Btitle%3B](http://www.gamespot.com/gamecube/action/rollarama/new.html?sid=2866974&com_act_convert&om_clk=nesfeatures&tag=newsfeatures%Btitle%3B).
- Savage, Paul G., "Advances in Strapdown Inertial Systems," *Lecture Series Advisory Group for Aerospace Research and Development Neuilly-Sur-Seine (France)* (1984).
- Sawada et al., "A Wearable Attitude-Measurement System Using a Fiberoptic Gyroscope" *Massachusetts Institute of Technology*, vol. 11, No., Apr. 2002, pp. 109-118.
- Saxena et al., "In Use Parameter Estimation of Inertial Sensors by Detecting Multilevel Quasi-Static States," *Lecture Notes in Computer Science, 2005—Berlin: Springer-Verlag*, (Apr. 2004).
- Sayed, "A Framework for Stae-Space Estimation with Uncertain Models," *IEEE Transactions on Automatic Control*, vol. 46, No. 7 (Jul. 2001).
- Sayed, *UCLA Adaptive Systems Laboratory—Home Page, UCLA*, <http://asl.ee.ucla.edu/index.php?option=com.sub.--frontpage&Itemid=1> (Aug. 2007).
- Schmorrow et al., "The PSI Handbook of Virtual Environments for Training and Education," vol. 1, 2009.
- Schofield, Jack et al., Coming up for airpad, *The Guardian* (Feb. 2000).
- Sega/Sports Sciences, Inc., "Batter Up, It's a Hit," *Instruction Manual, Optional Equipment Manual* (1994).
- Sega/Sports Sciences, Inc., "Batter Up, It's a Hit," *Photos of baseball ball* (1994).
- Selectech, "AirMouse Remote Control System Model AM-1 User's Guide," *Colchester, VT* (Sep. 24, 1991).
- Selectech, "AirMouse Remote Controls, AirMouse Remote Control Warranty" (1991).
- Selectech, "Changing Driver Versions on CDTV/AMIGA" (Oct. 17, 1991).
- Selectech, "Selectech AirMouse Remote Controls, Model # AM-R1," *photographs* (1991).
- Selectech, *Facsimile Transmission from Rossner to Monastiero, Airmouse Remote Controls, Colchester, VT* (Mar. 25, 1992).
- Selectech, *Selectech AirMOuse Devices* (image) (1991).
- Selectech, *Software, "AirMouse for DOS and Windows IBM & Compatibles," "AirMouse Remote Control B0100EN-C, Amiga Driver, CDTV Driver, Version: 1.00," "AirMouse Remote Control B0100EM-C.1, Apple Macintosh Serial Driver Version: 1.00(1.01B)," "AirMouse Remote Control B0100EL-B/3.05 DOS Driver Versions: 3.0 Windows Driver Version 1.00," AirMouse Remote Control MS-DOS Driver Version: 3.00/3.05, Windows 3.0 Driver Version: 1.00* (1991).
- "Self-Contained, Free Standing "Fishing Rod" Fishing Games," *Miacomet and Interact Announce Agreement to Launch Line of Reel Feel™ Sport Controllers, Press Release, May 13, 1999, 4 pages*.
- Seoul National Univ., "EMMU System"—*Seoul National Univ Power Point Presentation, www.computer.org/portal/cms\_docs\_ieeeecs/ieeecs/education/cside/CSIDC03Presentations/SNU.ppt* (2003).
- Serial Communication* (Wikipedia) (Jul. 2, 2005).
- Shoemake, Ken, *Quaternions, UPenn, Online* (Oct. 2006).
- Simon, et al., "The Yo Yo: A Handheld Combining Elastic and Isotonic Input," <http://www.uni-weimar.de/cms/fileadmin/medien/vr/documents/publications/TheYoYo-Interacts2003-Talk.pdf> (2003).
- Simon, et al., "The Yo Yo: A Handheld Device Combining Elastic and Isotonic Input," *Human-computer Interaction—INTERACT'03*, pp. 303-310 (2003).
- Smartswing internal drawing, 1 page (2004).
- Smartswing, *Training Aid, Apr. 2005, Austin, Texas*.
- SmartSwing: "Register to be notified when Smartswing products are available for purchase," 3 pages, May 2004, retrieved May 19, 2009, <http://web.archive.org/web/20040426182437/www.smartswing-golf.com/>.
- SmartSwing: "SmartSwing: Intellegent Golf Clubs that Build a BetterSwing," 2 pages, 2004 retrieved May 19, 2009, <http://web.archive.org/web/20040728221951/http://www.smartswinggolf...>

(56)

## References Cited

## OTHER PUBLICATIONS

- SmartSwing: "The SmartSwing Learning System Overview," 3 pages, 2004, retrieved May 19, 2009, <http://web.archive.org/web/20040810142134/http://www.smartswinggolf.com/t...>
- SmartSwing: "The SmartSwing Product," 3 pages, 2004, retrieved May 19, 2009, <http://web.archive.org/web/20040032004628/http://www.smartswinggolf.com/...>
- SmartSwing: The SmartSwing Product Technical Product: Technical Information, 1 page, 2004, retrieved May 19, 2009, <http://web.archive.org/web/200400403205906/http://www.smartswinggolf.com/...>
- SmartSwing, Letter from the CEO—pp. 1-3, May 2009.
- SmartSwing: The SmartSwing Learning System: How it Works, 3 pages, 2004, retrieved May 19, 2009, <http://web.archive.org/web/20040403213108/http://www.smartswinggolf.com/>.
- Smith, "Gyrevolution: Orienting the Digital Era," [http://www.gyration.com/images/pdfs/Gyration\\_White\\_Paper.pdf](http://www.gyration.com/images/pdfs/Gyration_White_Paper.pdf) (2007).
- Sorenson, et al., "The Minnesota Scanner: A Prototype Sensor for Three-Dimensional Tracking of Moving Body Segments," *IEEE Transactions on Robotics and Animation* (Aug. 1989).
- Sourceforge.com, "ARToolkit API Documentation" (SourceForge web pages) (2004-2006).
- Stovall, "Basic Inertial Navigation," NAWCWPNS TM 8128, Navigation and Data Link Section, Systems Integration Branch (Sep. 1997).
- Sulic, "Logitech Wingman Cordless Rumblepad Review", Review at IGN, 4 pages, Jan. 14, 2002.
- "Superfamicom Grip controller by ASCII," [http://superfami.com/sfc\\_grip.html](http://superfami.com/sfc_grip.html), Jul. 10, 2008, pp. 1-2.
- Sutherland, "A Head-Mounted Three Dimensional Display," AFIPS '68 (Fall, part I): Proceedings of the Dec. 9-11, 1968, fall joint computer conference, part I, pp. 757-764 (Dec. 1968).
- Sutherland, Ivan E., "Sketchpad: A Man-Machine Graphical Communication System," AFIPS '63 (Spring): Proceedings of the May 21-23, 1963, Spring Joint Computer Conference, pp. 329-346 (May 1963).
- Sweetster, "A Quaternion Algebra Tool Set," <http://world.std.com/%7Esweetser/quaternions/intro/tools/tools.html> (Jun. 2005).
- Swisher "How Science Can Improve Your Golf Game, Your Club is Watching" *The Wall Street Journal*, Apr. 18, 2005, 1 page.
- Templeman, James N., "Virtual Locomotion: Walking in Place through Virtual Environments," *Presence*, vol. 8 No. 6, pp. 598-617, Dec. 1999.
- Thinkoptics, Thinkoptics Wavit devices (image) (2007).
- Timmer, "Data Analysis and Modeling Dynamic Processes in the Life Sciences," Freiburg Center for Data Analysis and Modeling, <http://webber.physik.uni-freiburg.de/about/jeti/> (Aug. 2007).
- Timmer, "Modeling Noisy Time Series: Physiological Tremor," *International Journal of Bifurcation and Chaos*, vol. 8, No. 7 (1998).
- Timmer et al., "Pathological Tremors: Deterministic Chaos or Non-linear Stochastic Oscillators?" *Chaos*, vol. 10, No. 1 (Mar. 2000).
- Timmer, et al., "Characteristics of Hand Tremor Time Series," *Biological Cybernetics*, vol. 70 (1993).
- Timmer, et al., Cross-Spectral Analysis of Physiological Tremor and Muscle Activity: I Theory and Application to unsynchronized electromyogram, vol. 78 (1998).
- Timmer, et al., Cross-Spectral Analysis of Physiological Tremor and Muscle Activity: II Application to Synchronized Electromyogram, *Biological Cybernetics*, vol. 78 (1998).
- Timmer, et al., "Cross-Spectral Analysis of Tremor Time Series," *International Journal of Bifurcation and Chaos*, vol. 10, No. 11 (2000).
- Titterton et al., "Strapdown Inertial Navigation Technology," pp. 1-56 and pp. 292-321 (May 1997).
- Traq 3D (Trazer) Product, [http://www.exergamefitness.com/traq\\_3d.htm](http://www.exergamefitness.com/traq_3d.htm), <http://www.traq3d.com/> (1997).
- Traq 3D, "Healthcare" 1 pages, <http://www.traq3d.com/Healthcare/Healthcare.aspx>, 1997.
- Translation of the brief of System Com 99 of Oct. 27, 2010 and original German text.
- Translation of Exhibit B-B01: Cancellation Request of BigBen of Oct. 15, 2010 against German utility model 20 2006 020 818 (UM1) (Oct. 15, 2010) and original German text.
- Translation of Exhibit B-C01: Cancellation Request of BigBen of Oct. 15, 2010 against German utility model 20 2006 020 819 (UM2) (Oct. 15, 2010) and original German text.
- Translation of Exhibit B-D01: Cancellation Request of BigBen of Oct. 15, 2010 against German utility model 20 2006 020 820 (UM3) (Oct. 15, 2010) and original German text.
- Translation of Opposition Brief of BigBen of Sep. 2, 2010 Against European Patent No. EP 1854518.
- Transmission Mode (Apr. 22, 1999).
- Ulanoff, Lance, "Nintendo's Wii is the Best Product Ever," *PC Magazine* (Jun. 21, 2007).
- UNC Computer Science Department, "News & Notes from Sitterson Hall," UNC Computer Science, Department Newsletter, Issue 24, Spring 1999, (Apr. 1999).
- Univ. Illinois at Chicago, "CAVE—A Virtual Reality Theater," <http://www.youtube.com/watch?v=Sf6bJjwSCE> 1993.
- Univ. Wash., "ARToolkit" (U. Wash. web pages) (1999).
- Urban, "BAA 96-37 Proposer Information," DARPA/ETO (1996).
- US Dynamics Corp, "Spinning Mass Mechanical Gyroscopes" (Aug. 2006).
- US Dynamics Corp, "The Concept of 'Rate' (more particularly, angular rate pertaining to rate gyroscopes) (rate gyro explanation)," (Aug. 2006).
- US Dynamics Corp, "US Dynamics Model 475 Series Rate Gyroscope Technical Brief—brief discussion on rate gyroscope basics, operation, and uses, and a dissection of the model by major component" (Dec. 2005).
- US Dynamics Corp, "US Dynamics Rate Gyroscope Interface Brief (rate gyro IO)" (Aug. 2006).
- VTi, Mindflux-VTi CyberTouch, 1996, <http://www.mindflux.com.au/products/vti/cybertouch.html>.
- Van Den Bogard, "Using linear filters for real-time smoothing of rotational data in virtual reality application," <http://www.science.uva.nl/research/ias/alumni/m.sc.theses/theses/RobvandenBogard.pdf> (Aug. 2004).
- Van Laerhoven, et al., "Using an Autonomous Cube for Basic Navigation and Input," Proceedings of the 5th International Conference on Multimodal interfaces, Vancouver, British Columbia, Canada, pp. 203-210 (2003).
- Van Rheeden, et al., "Noise Effects on Centroid Tracker Aim Point Estimation," *IEEE Trans. on Aerospace and Electronic Systems*, vol. 24, No. 2, pp. 177-185 (Mar. 1988).
- Vaz, et al., "An Adaptive Estimation of Periodic Signals Using a Fourier Linear Combiner," *IEEE Transactions on Signal Processing* vol. 42, Issue 1, pp. 1-10 (Jan. 1994).
- Verplaetse, "Inertial Proprioceptive Devices: Self-Motion Sensing Toys and Tools," *IBM Systems Journal* (Sep. 1996).
- Verplaetse, "Inertial-Optical Motion-Estimating Camera for Electronic Cinematography," Masters of Science Thesis, MIT, (1997).
- Villoria, Gerald, Hand on Roll-O-Rama Game Cube, Game Spot, May 29, 2002, [http://www.gamespot.com/gamecube/action/rollorama/news.html?sid=2868421&com\\_act=convert&om\\_clk=newsfeatures&tag=newsfeatures;title;l&m](http://www.gamespot.com/gamecube/action/rollorama/news.html?sid=2868421&com_act=convert&om_clk=newsfeatures&tag=newsfeatures;title;l&m).
- Virtual Fishing, Operational Manual, 2 pages, Tiger Electronics, Inc., 1998.
- Virtual Technologies, Inc., Cyberglove brochure, Palo Alto, CA, [www.virtex.com](http://www.virtex.com). (1999).
- Vorozcovs, et al., "The Hedgehog: A Novel Optical Tracking Method for Spatially Immersive Displays," *MIT Presence*, vol. 15, No. 1, pp. 108-121 (2006).
- VR Solutions, "IS-1200", [www.vrs.com.au/motion-tracking/intersense/is-1200.html](http://www.vrs.com.au/motion-tracking/intersense/is-1200.html) 2 pages (May 2009).
- Wang, et al., "Tracking a Head-Mounted Display in a Room-Sized Environment with Head-Mounted Cameras," *SPIE 1990 Technical Symposium on Optical Engineering and Photonics in Aerospace Sensing*, vol. 1290, pp. 47-57 (1990).
- Ward, et al., "A Demonstrated Optical Tracker With Scalable Work Area for Head-Mounted Display Systems," Symposium on Interac-

(56)

## References Cited

## OTHER PUBLICATIONS

tive 3D Graphics, Proceedings of the 1992 Symposium on Interactive 3D Graphics, pp. 43-52, ACM Press, Cambridge, MA (1992).

Watt, *3D Computer Graphics*, "Three-Dimensional Geometry in Computer Graphics," pp. 1-22 Addison-Wesley (1999).

Welch et al., HiBall Devices (image) (2002-2006).

Welch et al., Motion Tracking: No Silver Bullet, but a Respectable Arsenal IEEE Computer Graphics and Applications, vol. 22, No. 6, pp. 24-38 (Nov. 2002).

Welch, "Hybrid Self-Tracker: An Inertial/Optical Hybrid Three-Dimensional Tracking System," Tech. Report TR95-048, Dissertation Proposal, Univ. of North Carolina at Chapel Hill, Dept. Computer Science, Chapel Hill, N.C. (1995).

Welch, "Hawkeye Zooms in on Mac Screens with Wireless Infrared Penlight Pointer," MacWeek (May 1993).

Welch, et al., "Complementary Tracking and Two-Handed Interaction for Remote 3D Medical Consultation with a PDA," Proceedings of Trends and Issues in Tracking for Virtual Environments, Workshop at the IEEE Virtual Reality 2007 Conference (Mar. 2007).

Welch, et al., "High-Performance Wide-Area Optical Tracking: The HiBall Tracking System," MIT Presence: Teleoperators & Virtual Environments (2001).

Welch, et al., "SCAAT: Incremental Tracking with Incomplete Information," Computer Graphics, SIGGRAPH 97 Conference Proceedings, pp. 333-344 (Aug. 1997).

Welch, et al., "Source Code for HiBall+Inertial device," UNC-CH Computer Science (Jun. 1998).

Welch, et al., "The HiBall Tracker: High-Performance Wide-Area Tracking for Virtual and Augmented Environments," ACM SIGGRAPH, Addison-Wesley (1999).

Welch, et al., "The High-Performance Wide-Area Optical Tracking : The HiBall Tracking System," MIT Presence, Presence, vol. 10, No. 1 (Feb. 2001).

Welch, et al., "Tracking for Training in Virtual Environments: Estimating the Pose of People and Devices for Simulation and Assessment," [J. Cohn, D. Environments for Training and Education: Developments for the Military and Beyond, Chap.1, pp. 23-47] (2008).

Widrow, et al., "Fundamental relations Between the LMS Algorithm and the DFT," IEEE Transactions on Circuits and Systems, vol. 34, No. CAS-7, (Jul. 1987).

Wiley, M.: "Nintendo Wavebird Review," US, Jun. 11, 2002, 21 pages.

Williams, et al., "Physical Presence: Palettes in Virtual Spaces," Society of Photo-Optical Instrumentation Engineers (SPIE) Conference Series, vol. 3639, No. 374-384 (May 1999).

Williams, Robert L. et al., "Implementation and Evaluation of a Haptic Playback System," vol. 3 No. 3, Haptics-e (2004).

Williams, Robert L. et al., "The Virtual Haptic Back Project," Presented at the Image 2003 Conference, Scottsdale, Arizona (Jul. 14-18, 2003).

Wilson, "Wireless User Interface Devices for Connected Intelligent Environments," Ubicomp 2003 Workshop (2003).

Wilson, "WorldCursor: Pointing in Intelligent Environments with the World Cursor," UIST '03 Companion (Nov. 2003).

Wilson, "XWand: UI for Intelligent Environments," <http://research.microsoft.com/en-us/um/people/awilson/wand/default.htm> (Apr. 2004).

Wilson, et al., "Demonstration of the XWand Interface for Intelligent Space," UIST '02 Companion, pp. 37-38 (Oct. 2002).

Wilson, et al., "Gesture Recognition Using the Xwand," [ri.cmu.edu](http://ri.cmu.edu) (2004).

Wilson, et al., "Xwand: UI for Intelligent Space," CHI 2003, Proceedings of the SIGCHI conference on Human factors in computing systems, pp. 545-552 (Apr. 2003).

Wilson, Research page, biography available at <http://research.microsoft.com/en-us/um/people/awilson/?0sr=a>, Microsoft Corp. (2009).

Wilson, Transcript of Testimony Investigation No. 337-TA-658, Before the United States International Trade Commission, vol. V (May 15, 2009).

Wilson, XWand video, <http://research.microsoft.com/~awilson/wand/wand%20video%20768k.WMV> (Mar. 2002).

Wired Glove, Wikipedia Article, 4 pages, [http://en.wikipedia.org/wiki/Wired\\_glove](http://en.wikipedia.org/wiki/Wired_glove), (Nov. 18, 2010).

Wireless (Wikipedia) (Aug. 12, 2005).

Wormell, "Unified Camera, Content and Talent Tracking in Digital Television and Movie Production," InterSense, Inc. & Mark Read, Hypercube Media Concepts, Inc. Presented: NAB 2000, Las Vegas, NV, Apr. 8-13, 2000.

Wormell, et al., "Advancements in 3D Interactive Devices for Virtual Environments," ACM International Conference Proceeding Series; vol. 39 (2003).

Office Action issued in Taiwanese Patent Appl. No. 1002112610 on Dec. 14, 2001.

Office Action/Search Report issued in Taiwanese Patent Appl. No. 1002112610 on Dec. 14, 2011.

Worringham, et al., "Directional Stimulus-Response Compatibility: A Test of Three Alternative Principles," Ergonomics, vol. 41, Issue 6, pp. 864-880 (Jun. 1998).

[www.3rdtech.com](http://www.3rdtech.com) (2000-2006).

Yang, et al., "Implementation and Evaluation of 'Just Follow Me': An Immersive, VR-Based Motion-Training System," MIT Presence: Teleoperators and Virtual Environments, vol. 11 No. 3, at 304-23 (MIT Press) (Jun. 2002).

You, et al., "Hybrid Inertial and Vision Tracking for Augmented Reality Registration," <http://graphics.usc.edu/cgit/pdf/papers/Vr1999.PDF> (1999).

You, et al., "Orientation Tracking for Outdoor Augmented Reality Registration," IEEE Computer Graphics and Applications, IEEE, vol. 19, No. 6, pp. 36-42 (Nov. 1999).

Youngblut, et al., "Review of Virtual Environment Interface Technology," Institute for Defense Analyses (Jul. 1996).

Yun, et al., "Recent Developments in Silicon Microaccelerometers," Sensors, University of California at Berkeley (Oct. 1992).

Zhai, "Human Performance in Six Degree of Freedom Input Control," Thesis, University of Toronto (1995).

Zhai, "User Performance in Relation to 3D Input Device Design", Computer Graphics 32(4), Nov. 1998, 15 pages.

Zhou, et al., "A survey—Human Movement Tracking and Stroke Rehabilitation," Technical Report: CSM-420, ISSN 1744-8050, Dept. of Computer Sciences, University of Essex, UK (Dec. 8, 2004).

Zhu, et al., "A Real-Time Articulated Human Motion Tracking Using Tri-Axis Inertial/Magnetic Sensors Package," IEEE Transactions on Neural Systems and Rehabilitation Engineering, vol. 12, No. 2 (Jun. 2004).

European Search Report for Application No. EP 07 11 2880, Oct. 18, 2007.

European Search Report for Application No. EP 10178309.0 Apr. 2, 2011.

Office Action issued in related Chinese patent application 200610111559.7 (Sep. 18, 2009).

Office Action issued in related Japanese patent application 2006-216569 (Oct. 20, 2009).

Office Action issued in corresponding Japanese patent application 2007-203785 (Oct. 27, 2008).

Office Action issued in corresponding Japanese patent application 2008-2566858 (Sep. 9, 2010).

Office Action issued in corresponding Japanese patent application 2005-249265 (Apr. 21, 2011).

U.S. Appl. No. 11/745,842, filed May 8, 2007.

U.S. Appl. No. 11/404,871, filed Apr. 17, 2006.

U.S. Appl. No. 11/404,844, filed Apr. 17, 2006.

U.S. Appl. No. 11/790,780, filed Apr. 27, 2007.

U.S. Appl. No. 12/889,863, filed Sep. 24, 2010.

U.S. Appl. No. 13/028,648, filed Feb. 16, 2011.

U.S. Appl. No. 13/071,008, filed Mar. 24, 2011.

U.S. Appl. No. 13/071,028, filed Mar. 24, 2011.

\* cited by examiner

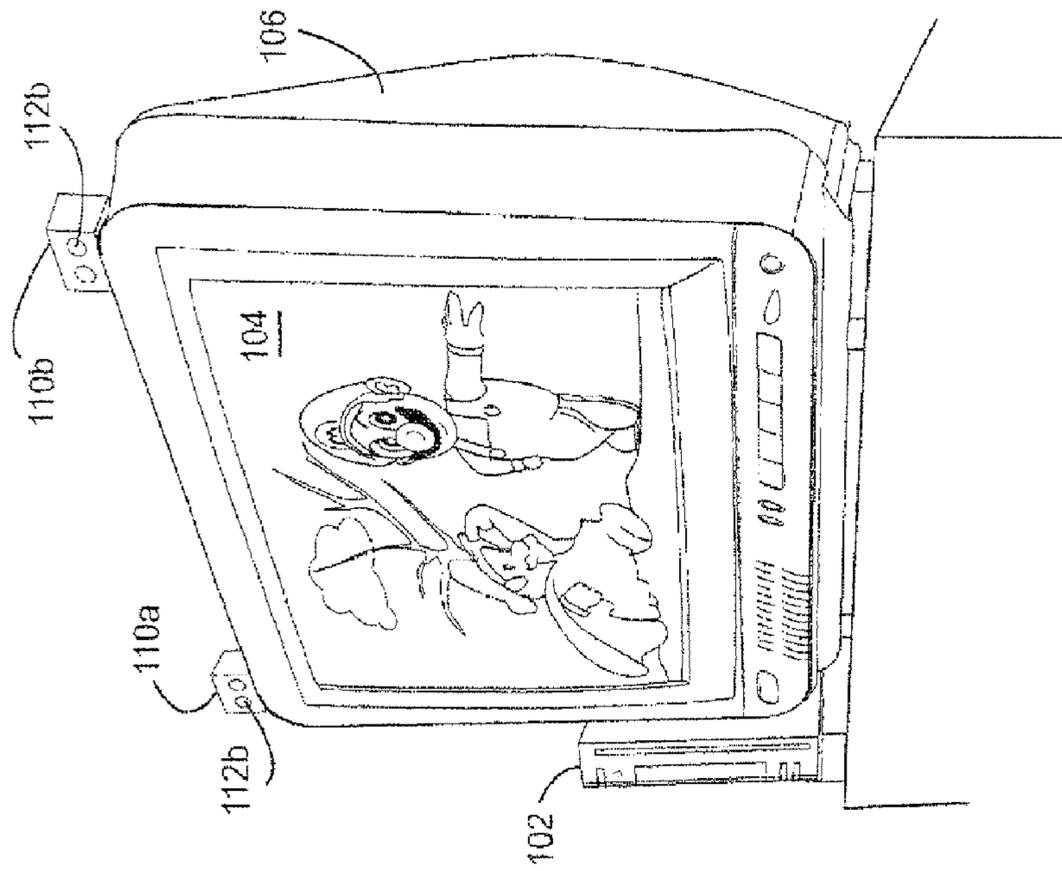
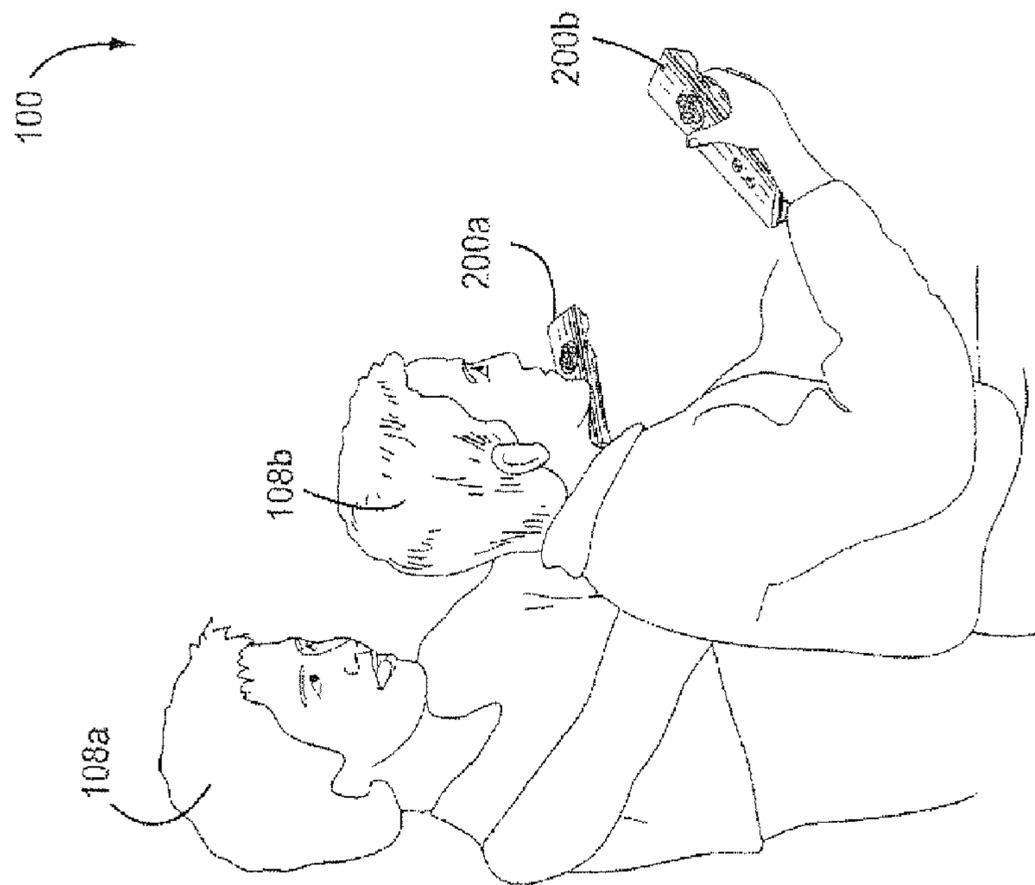


Fig. 1



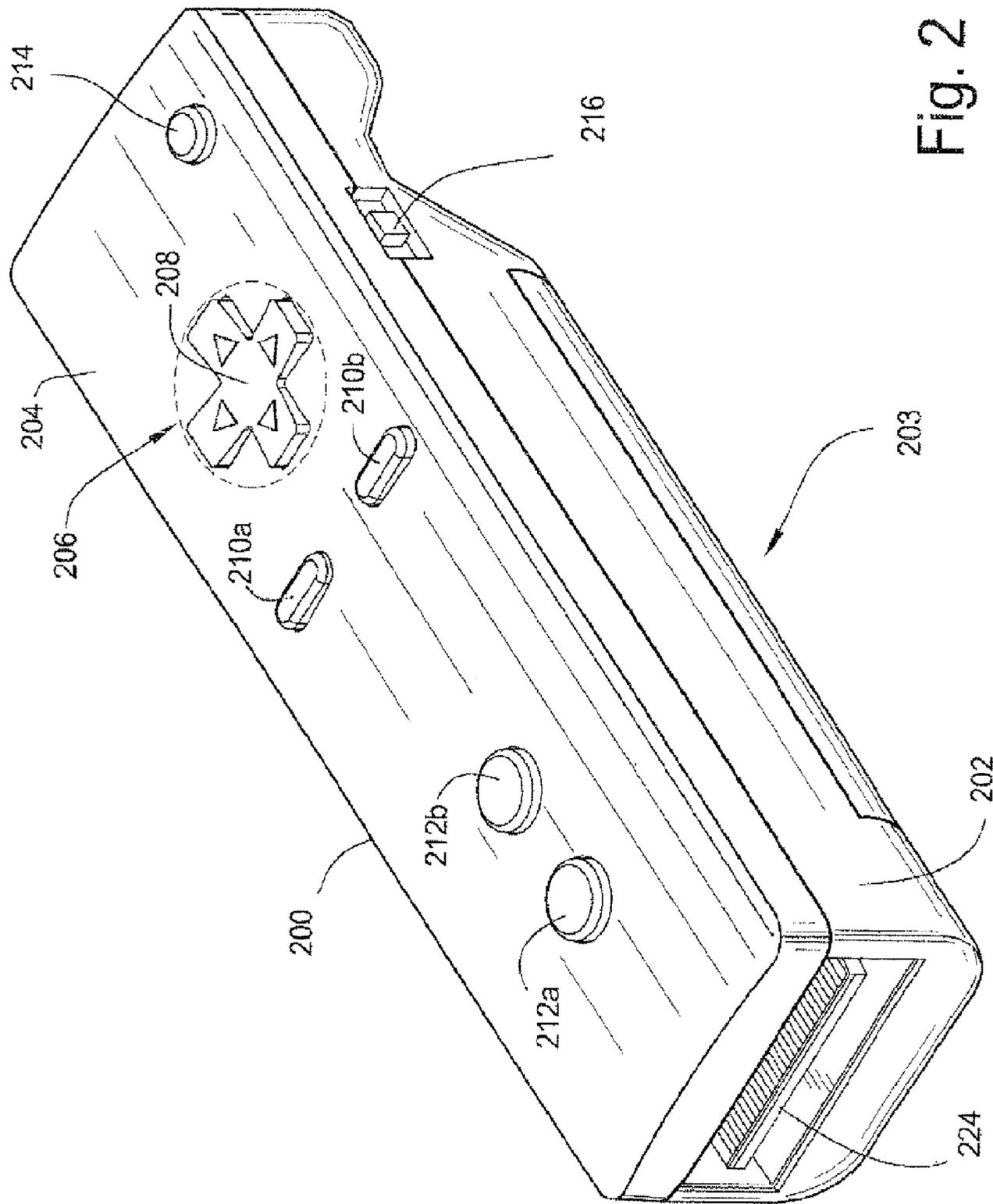


Fig. 2

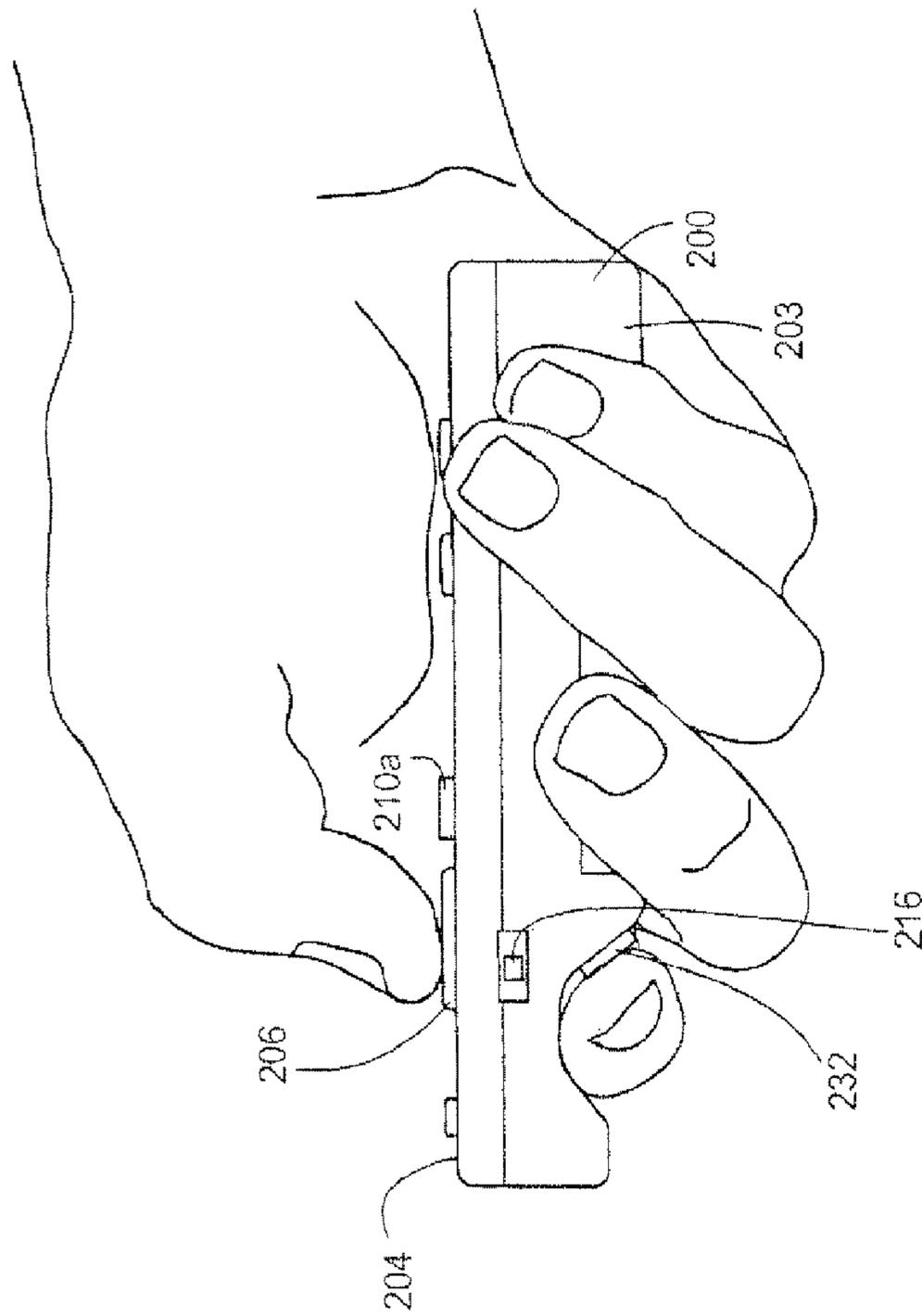


Fig. 2A

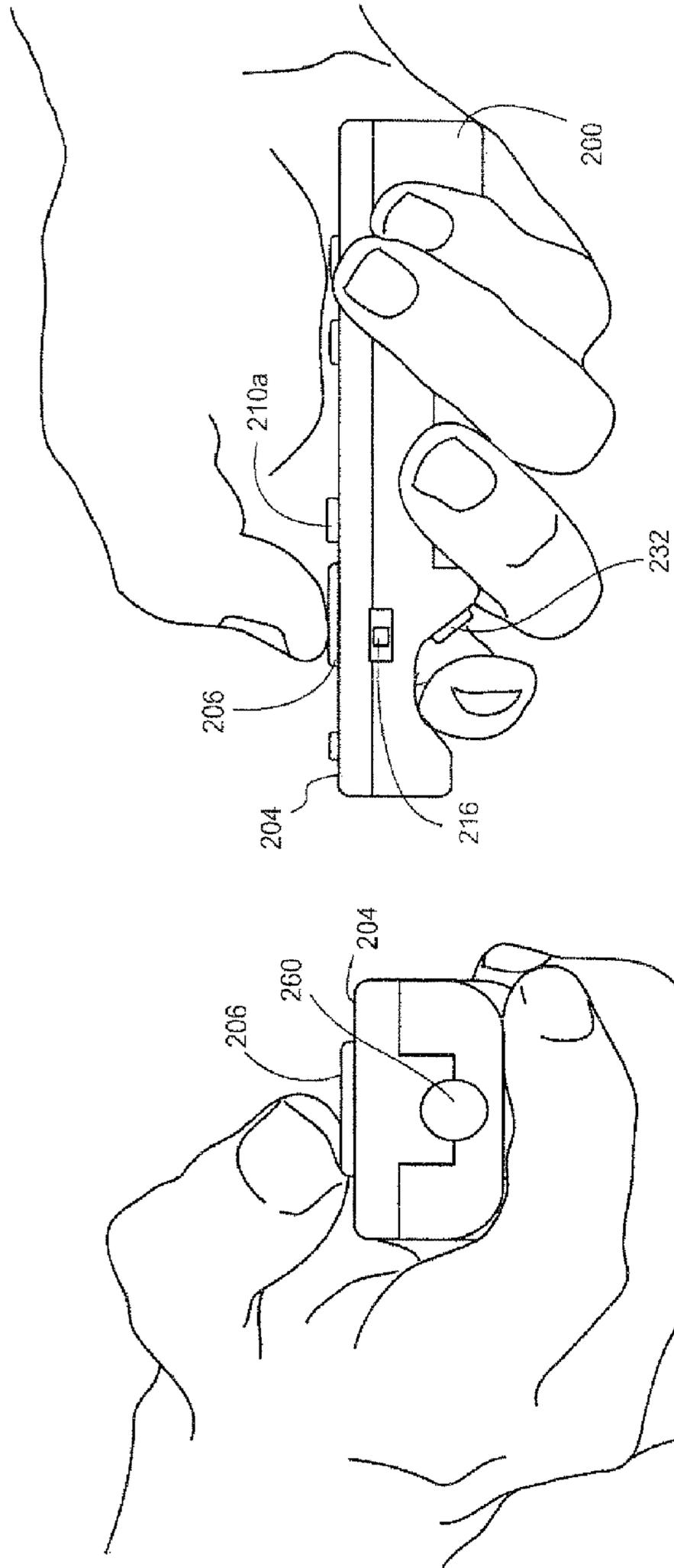


Fig. 2C

Fig. 2B

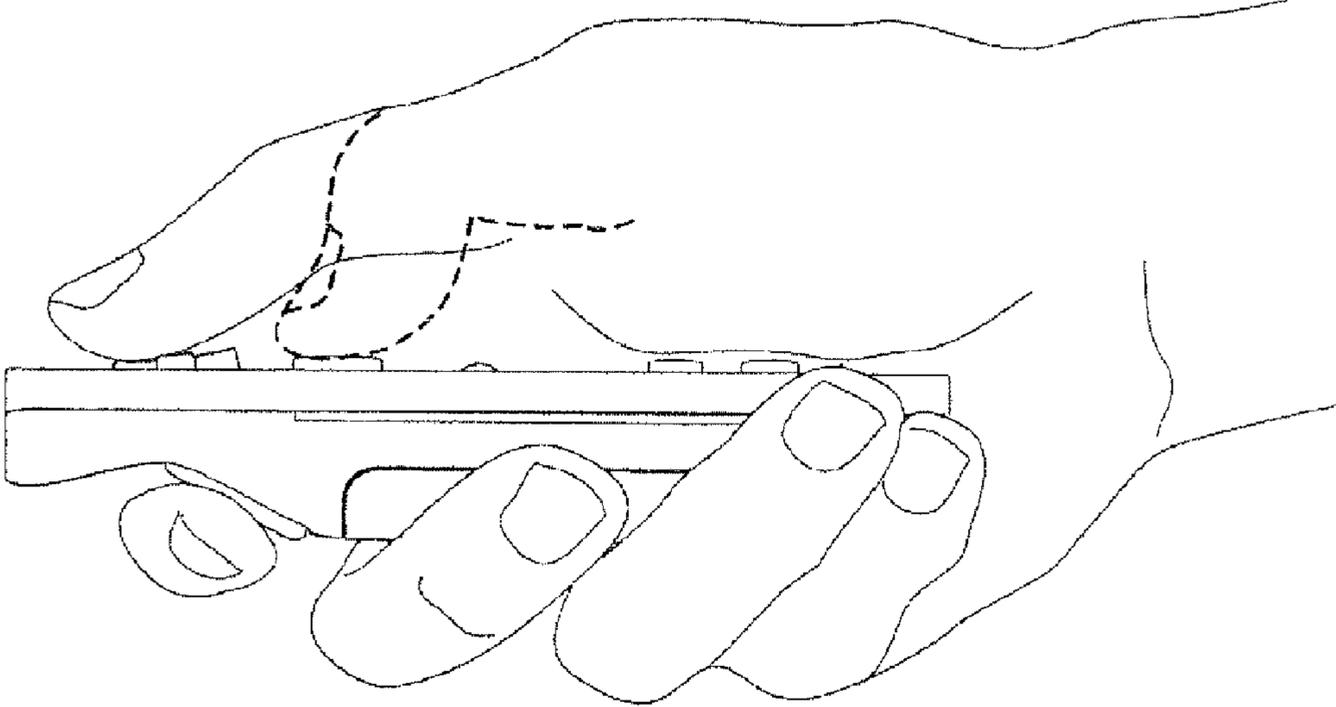


Fig. 2D

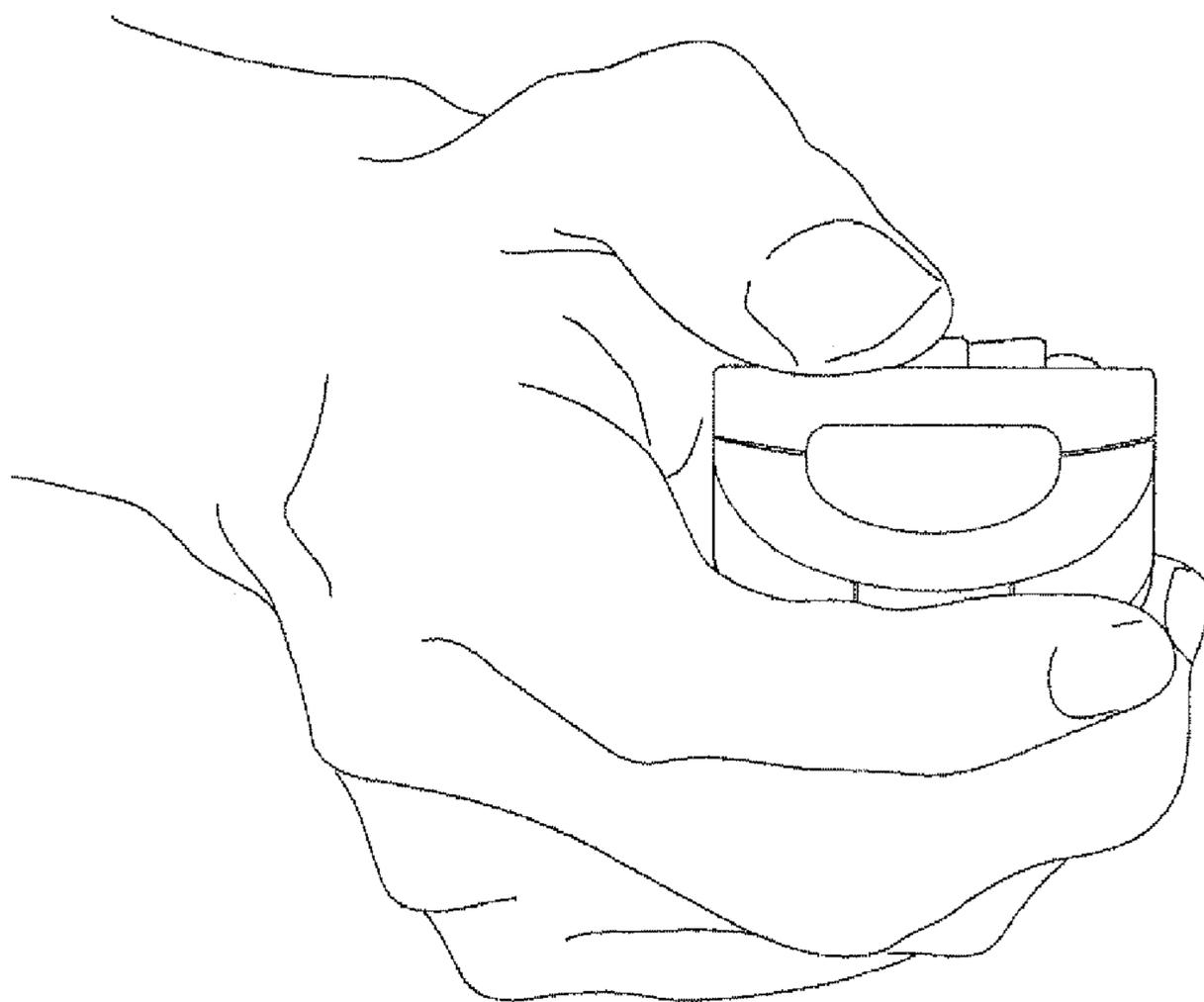


Fig. 2E

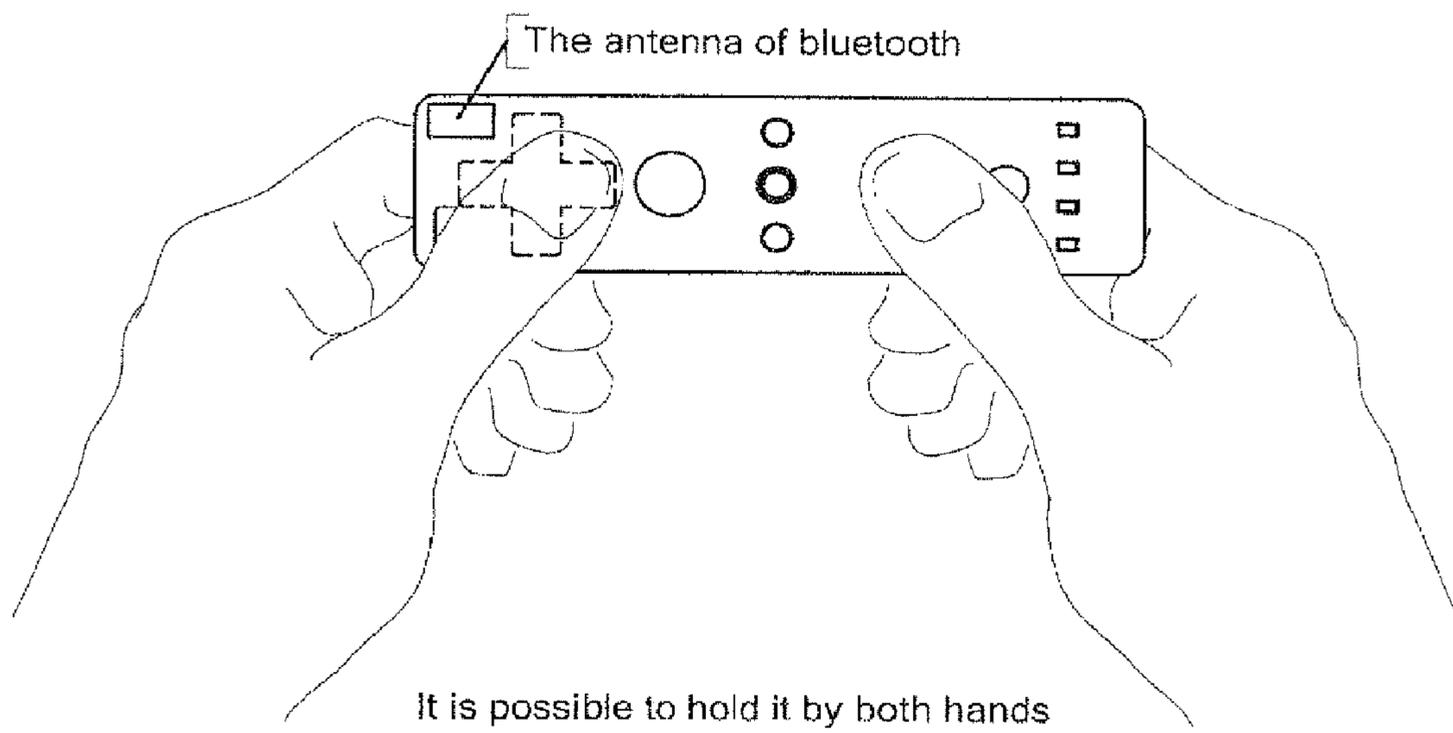


Fig. 2F

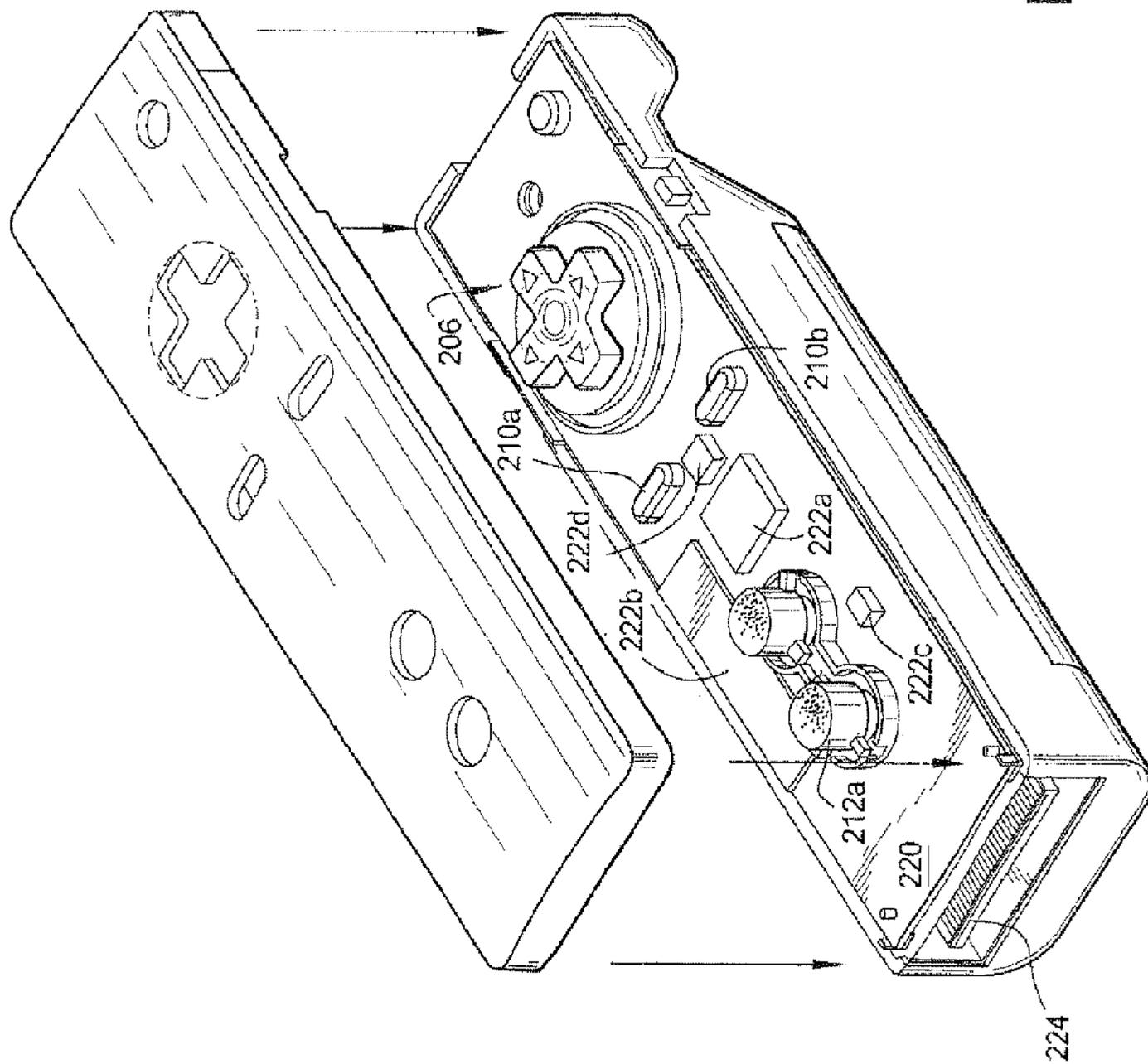


Fig. 3

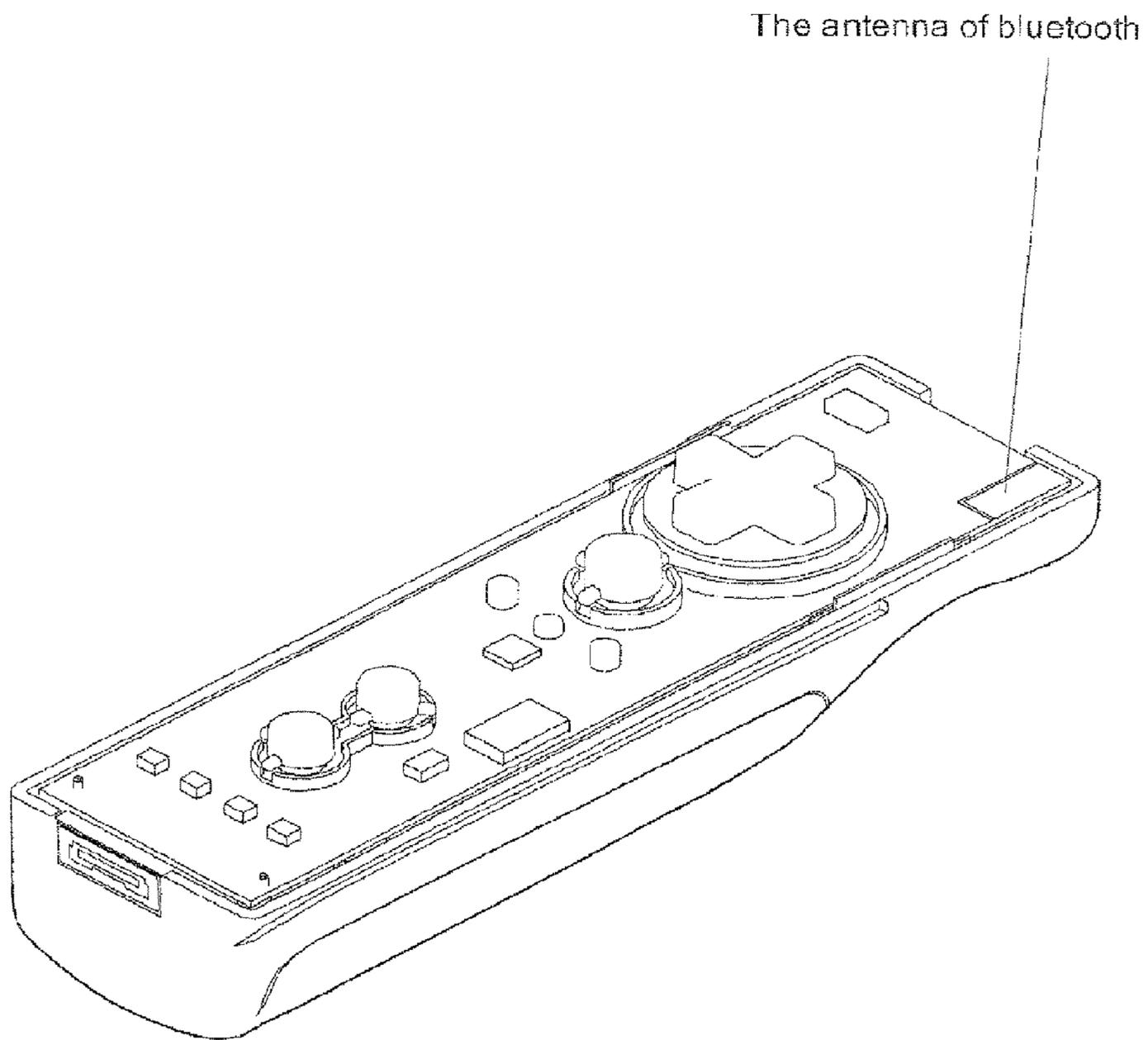


Fig. 3A

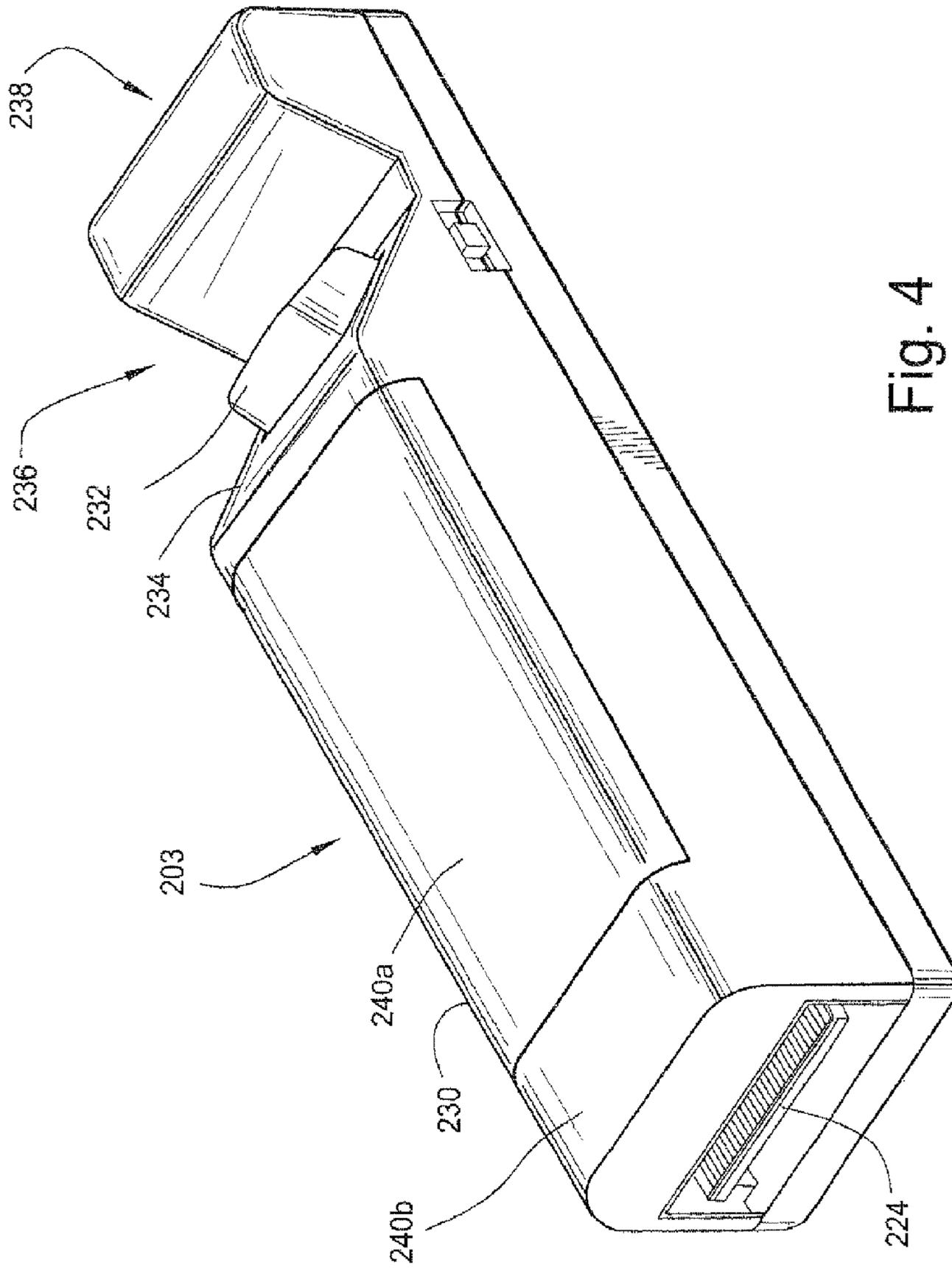
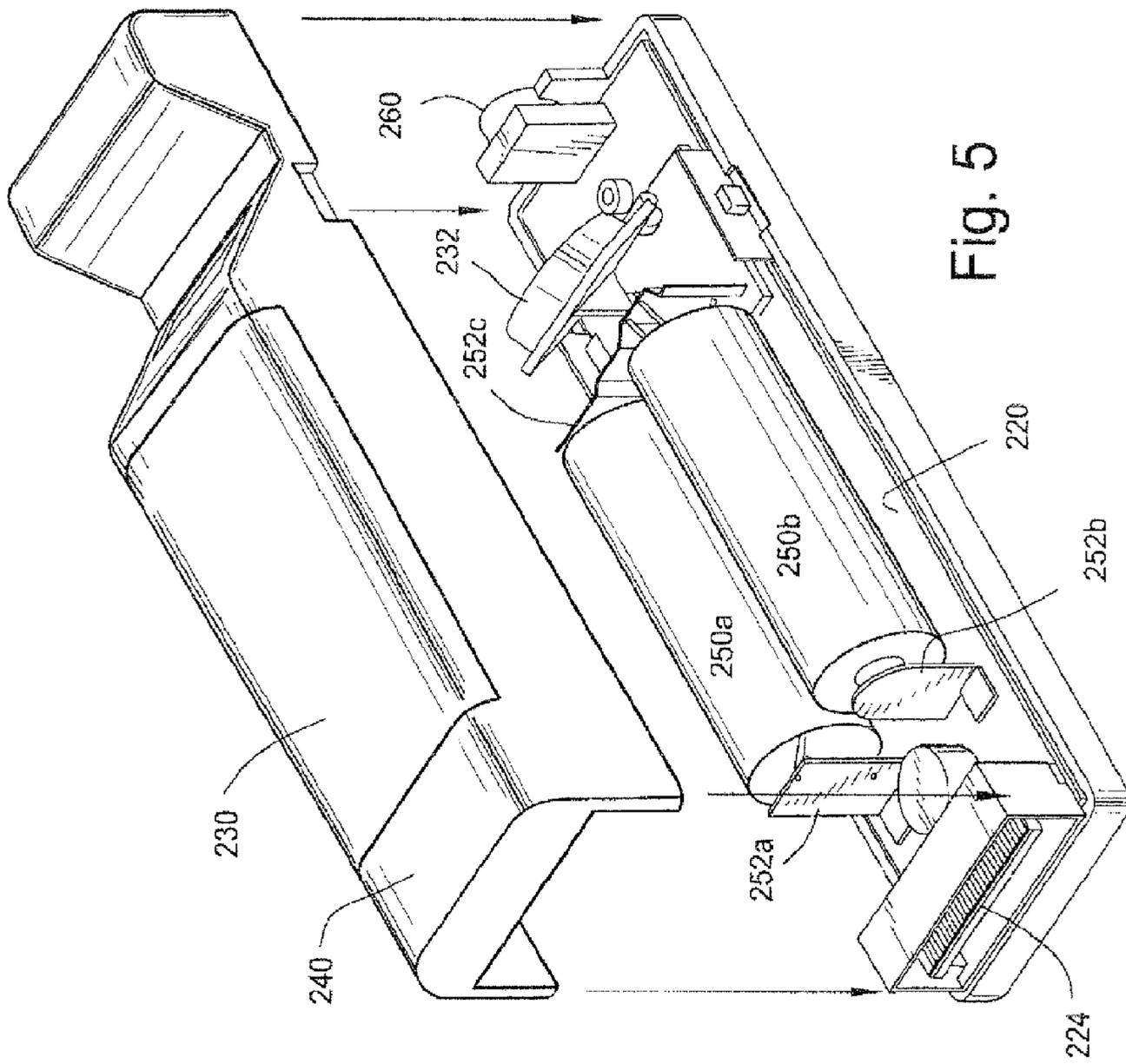


Fig. 4



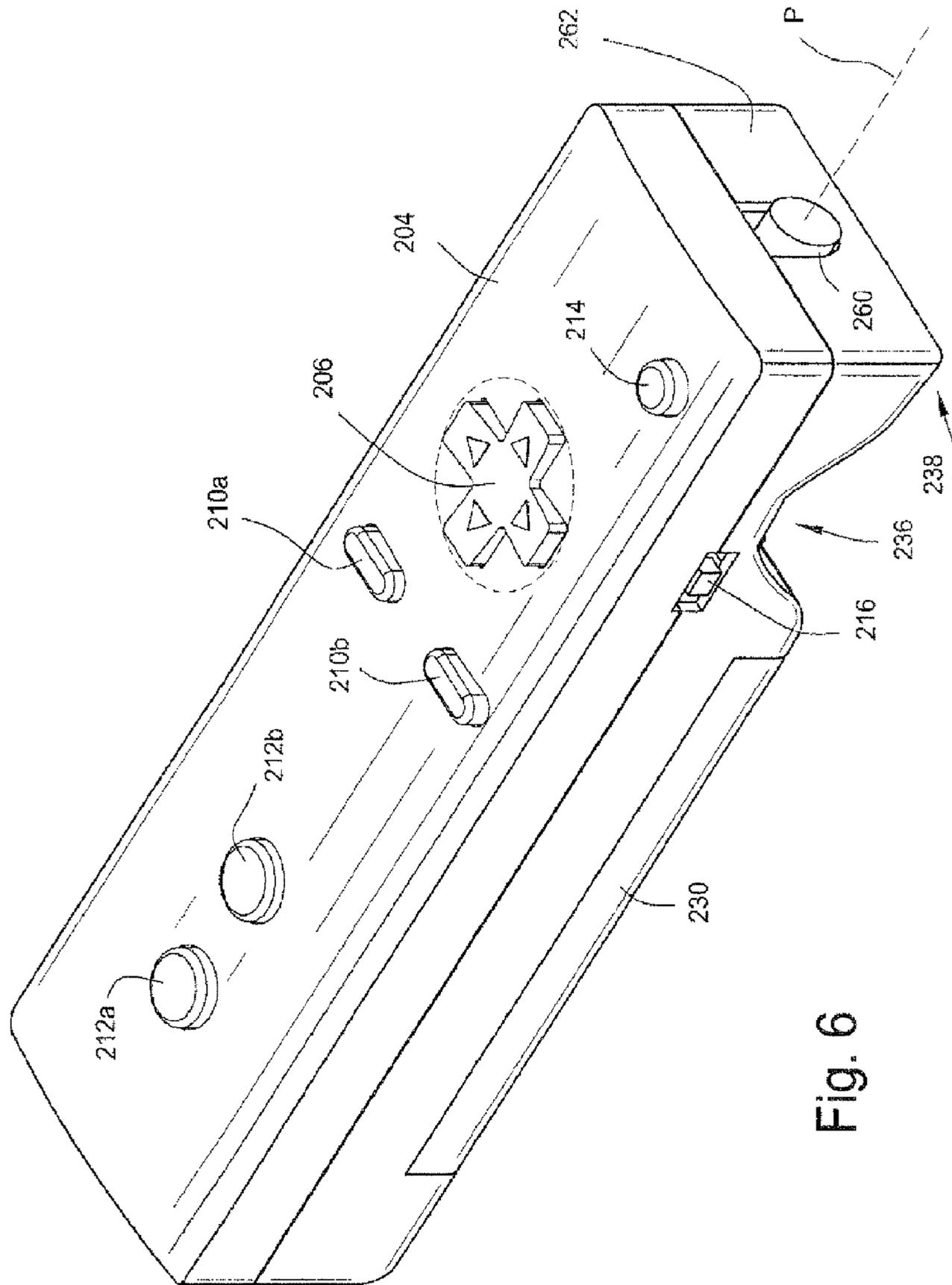


Fig. 6

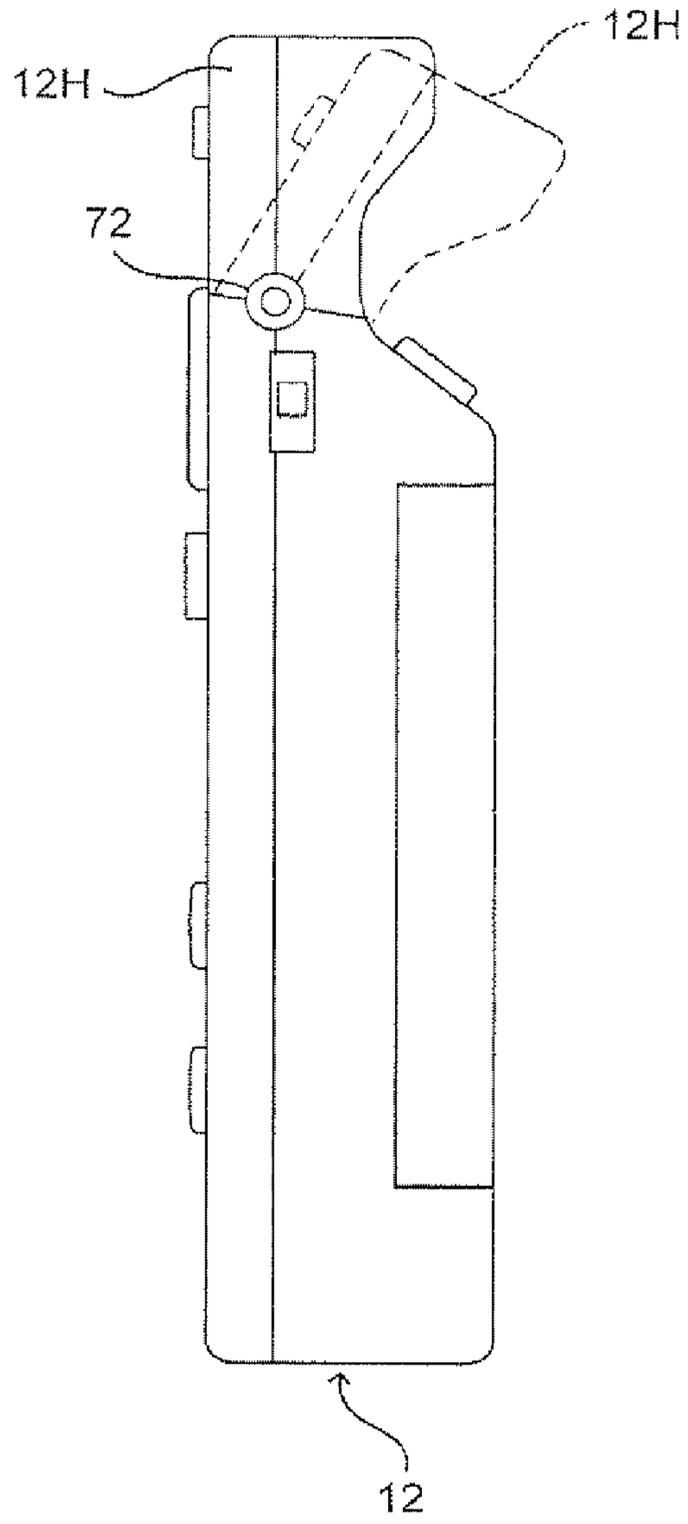
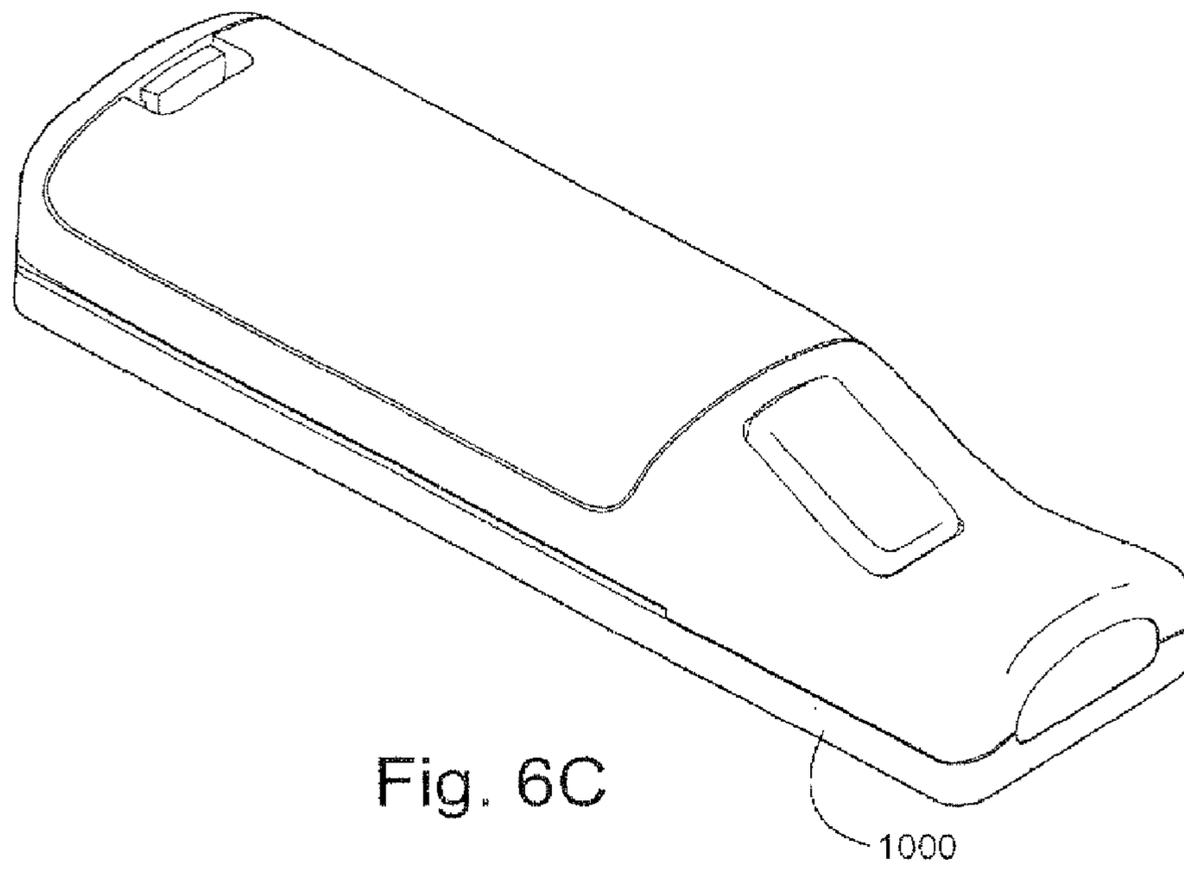
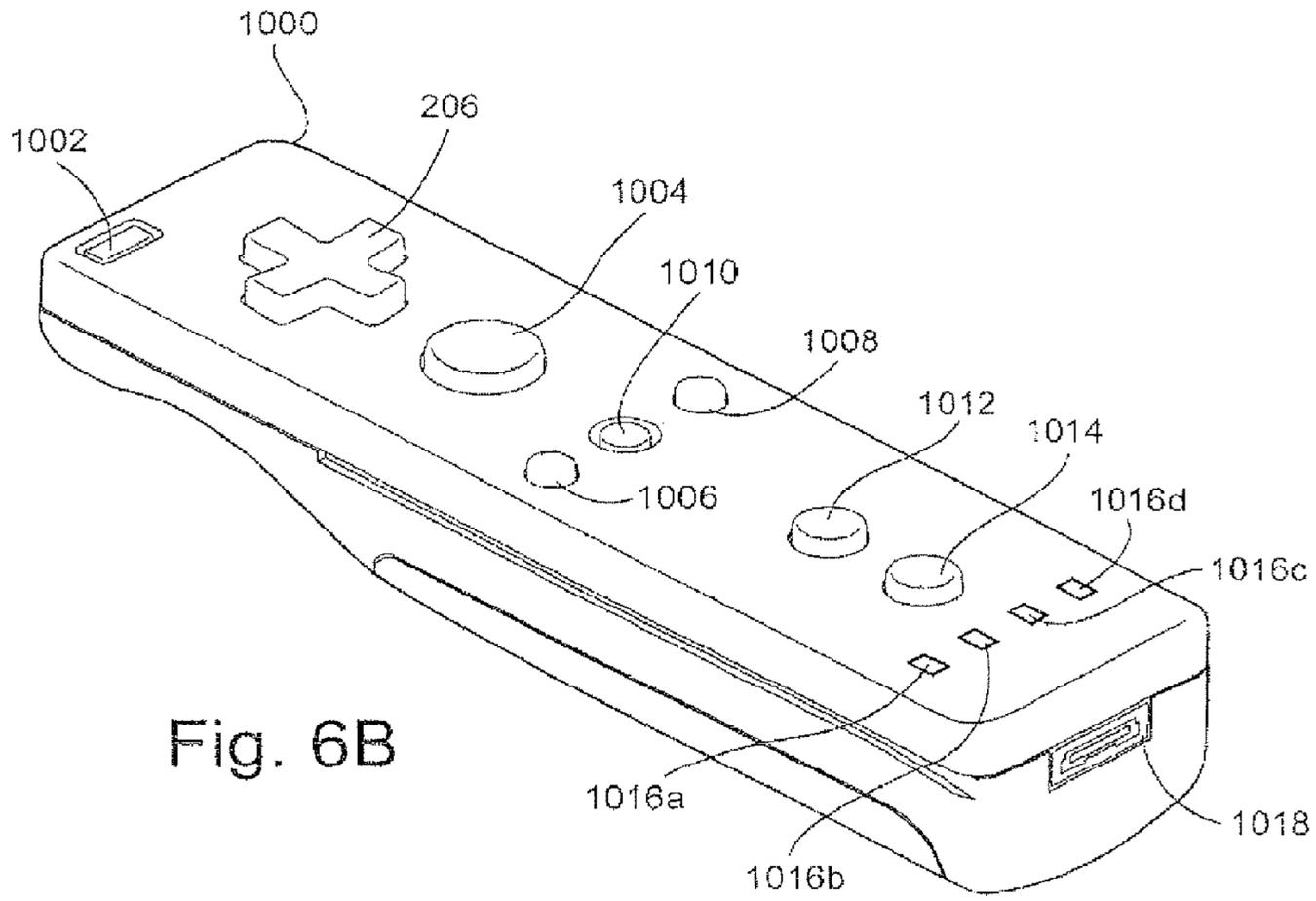


Fig. 6A



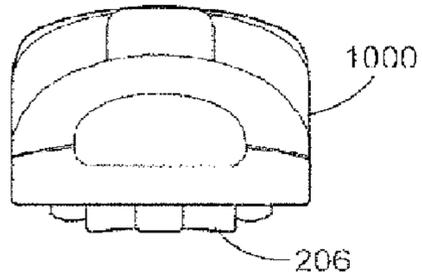


Fig. 6G

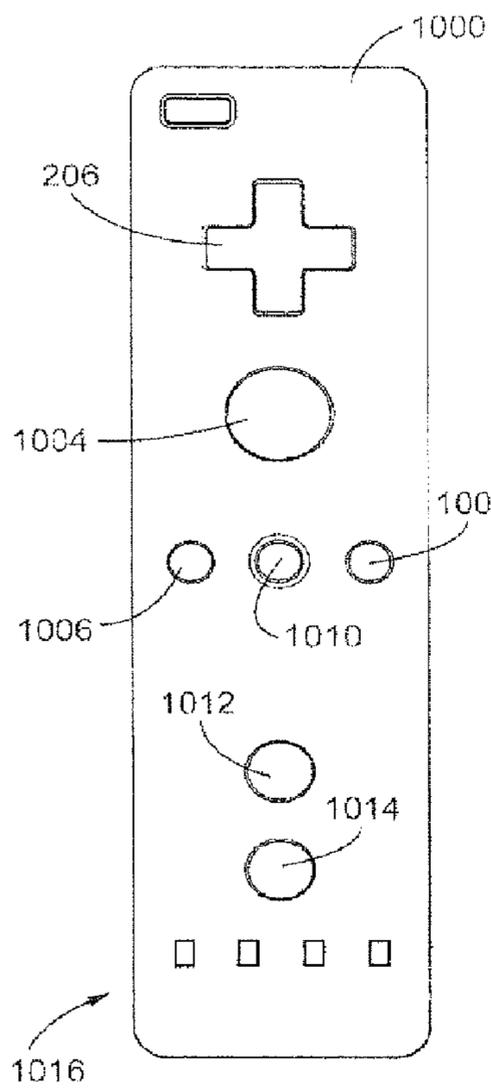


Fig. 6D

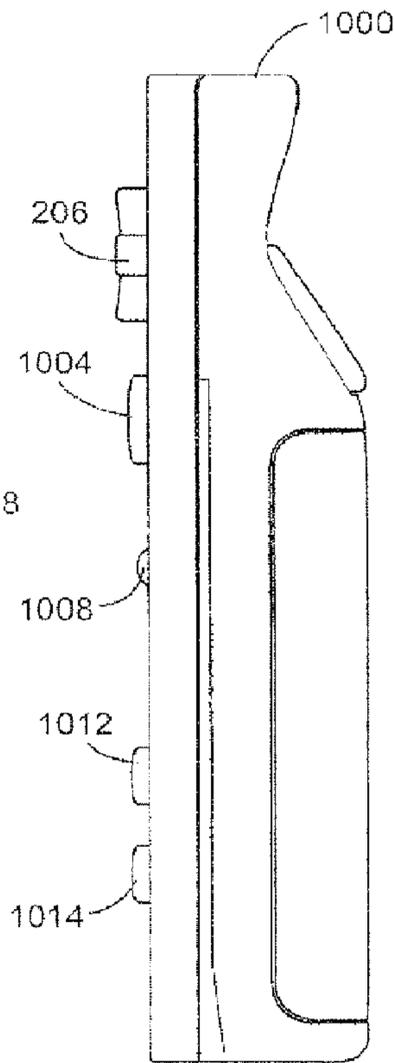


Fig. 6E

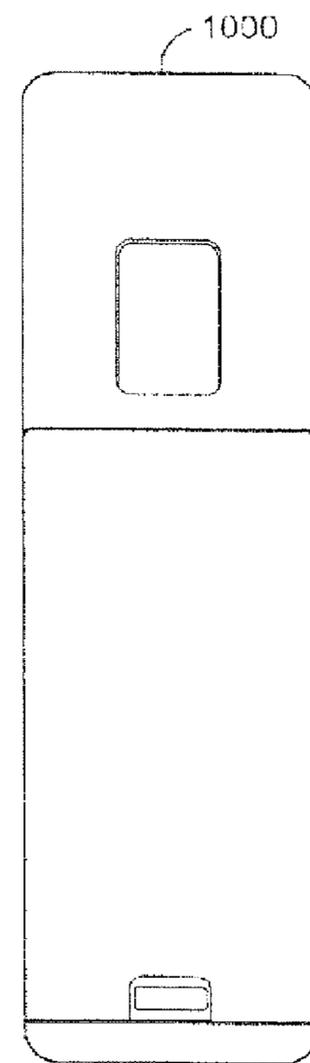


Fig. 6F

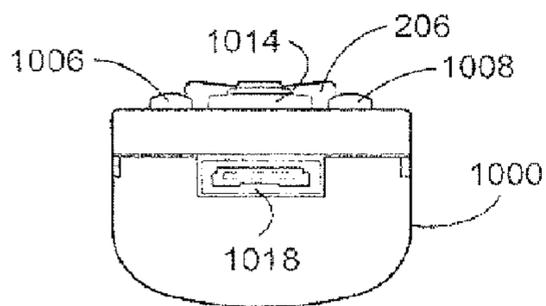


Fig. 6H

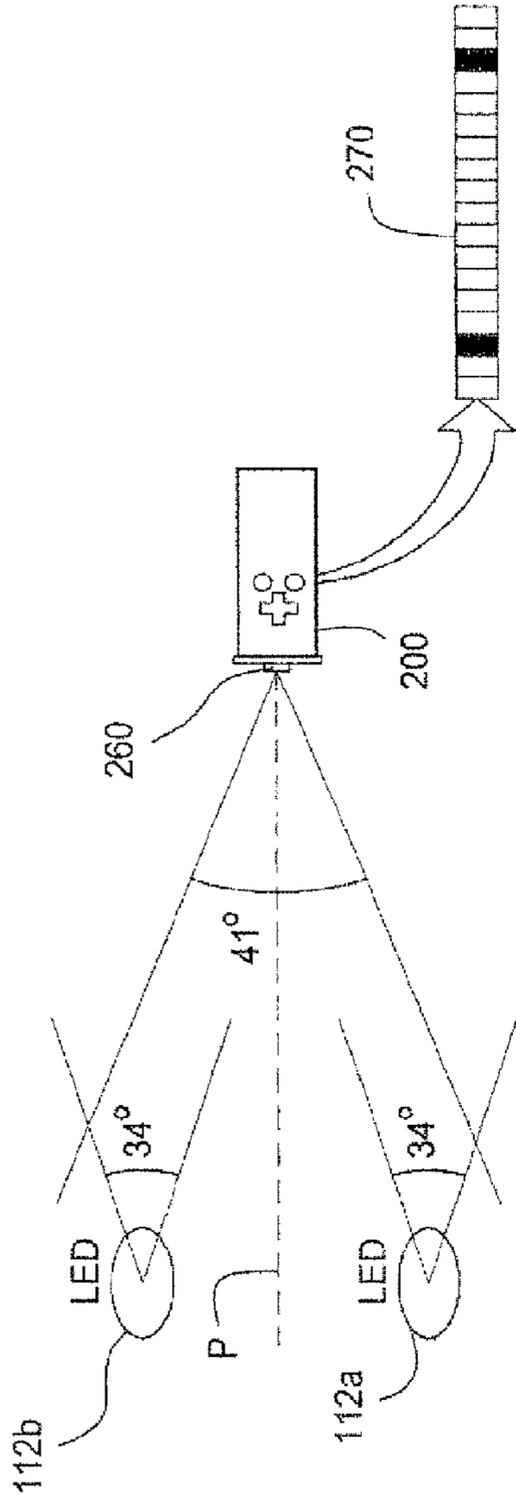


Fig. 7A

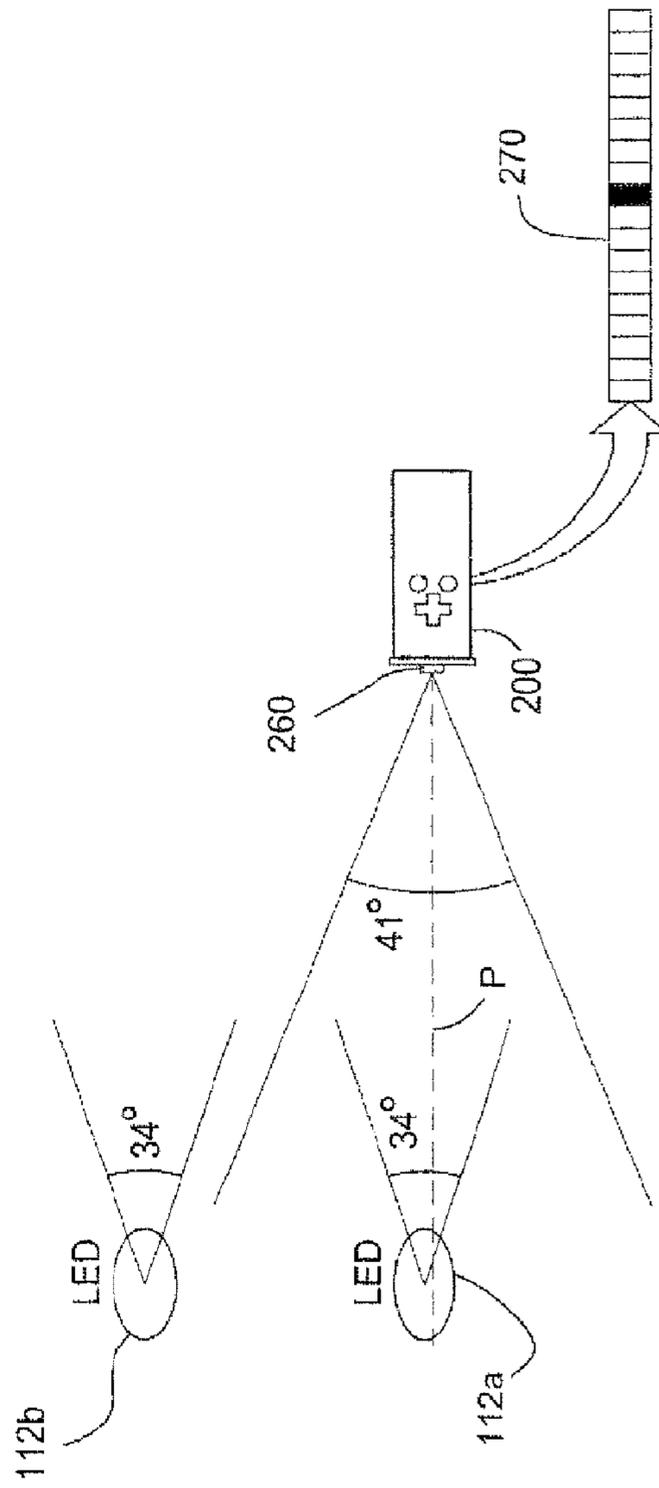


Fig. 7B

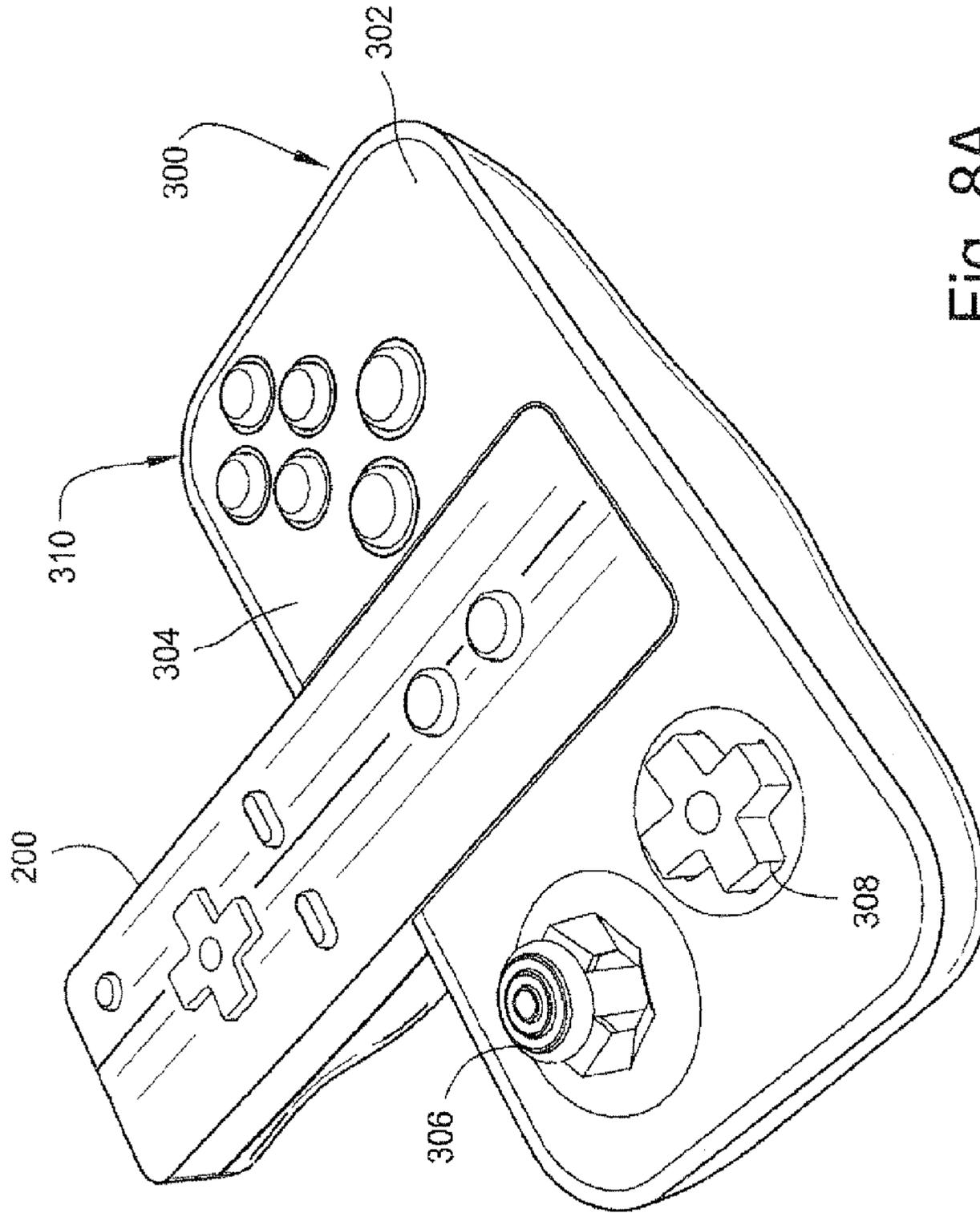


Fig. 8A

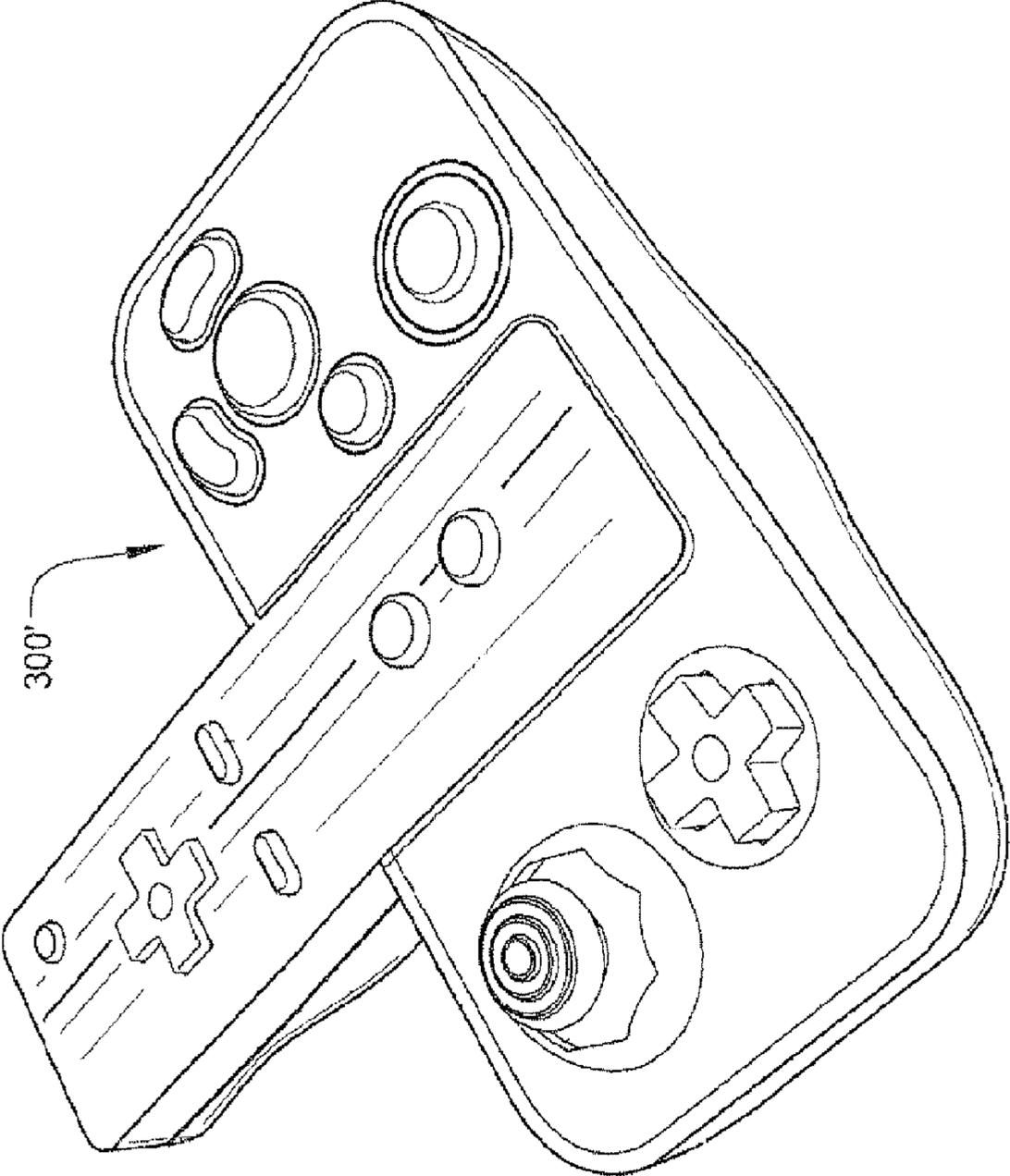


Fig. 8B

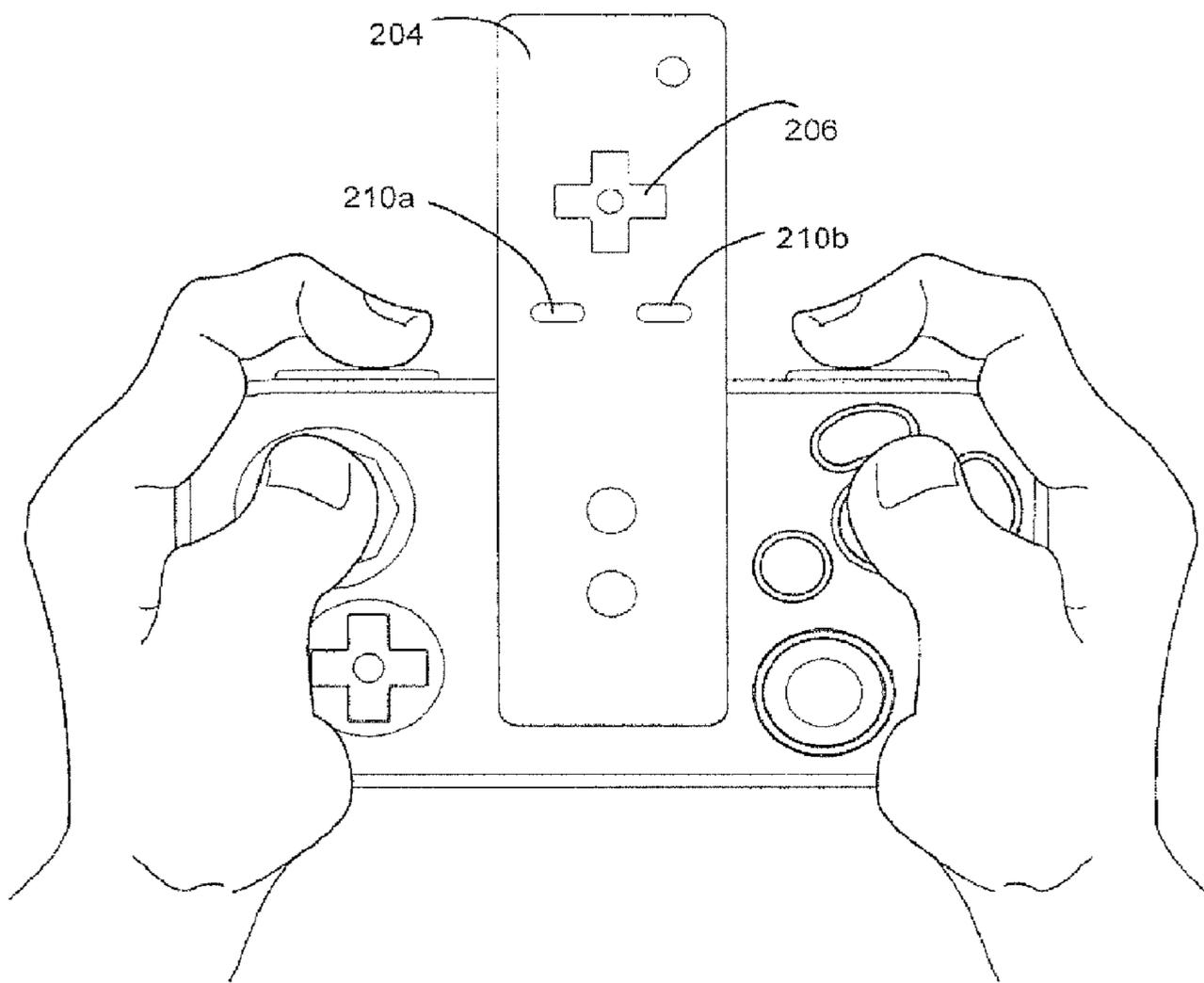


Fig. 8B-1

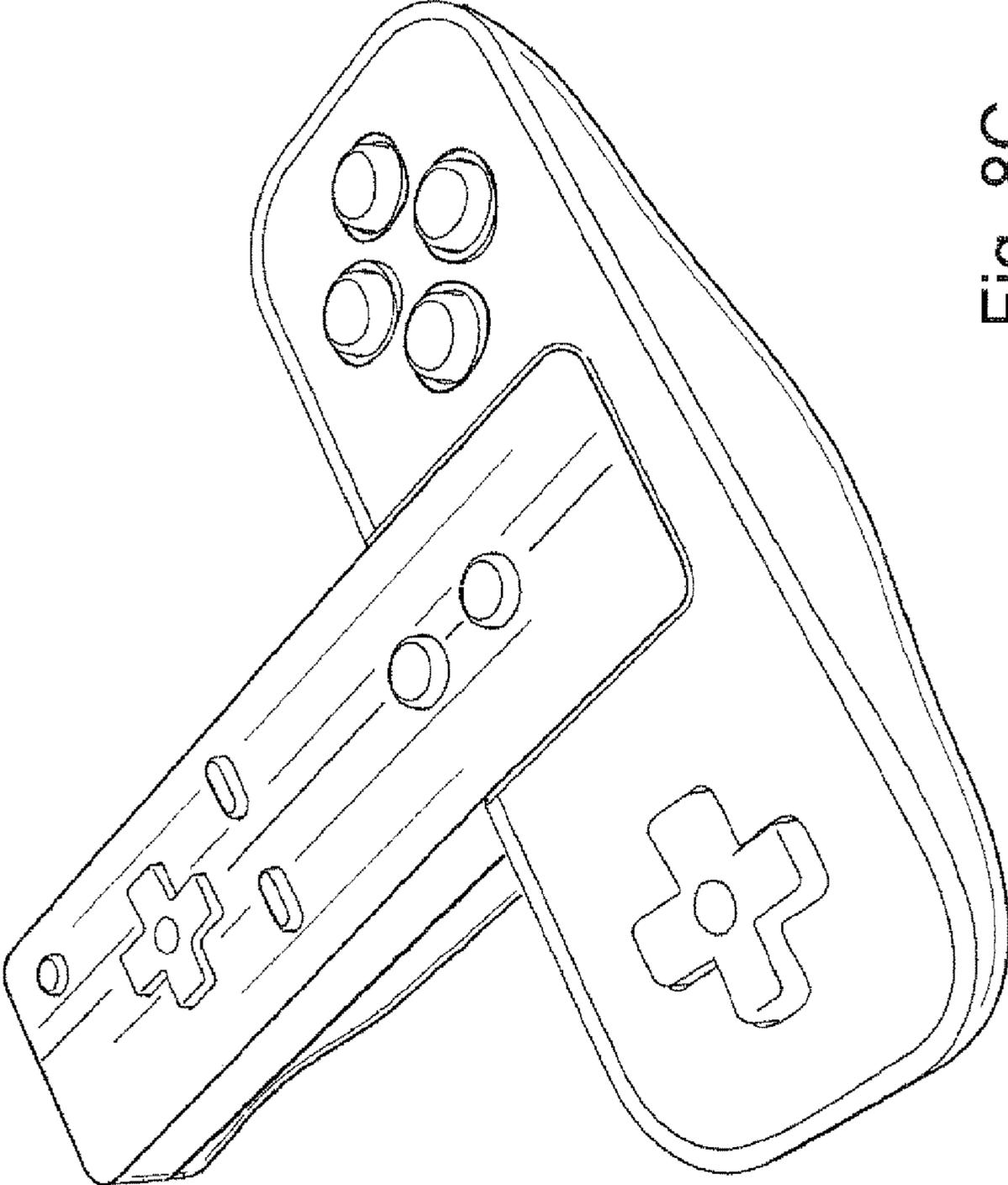


Fig. 8C

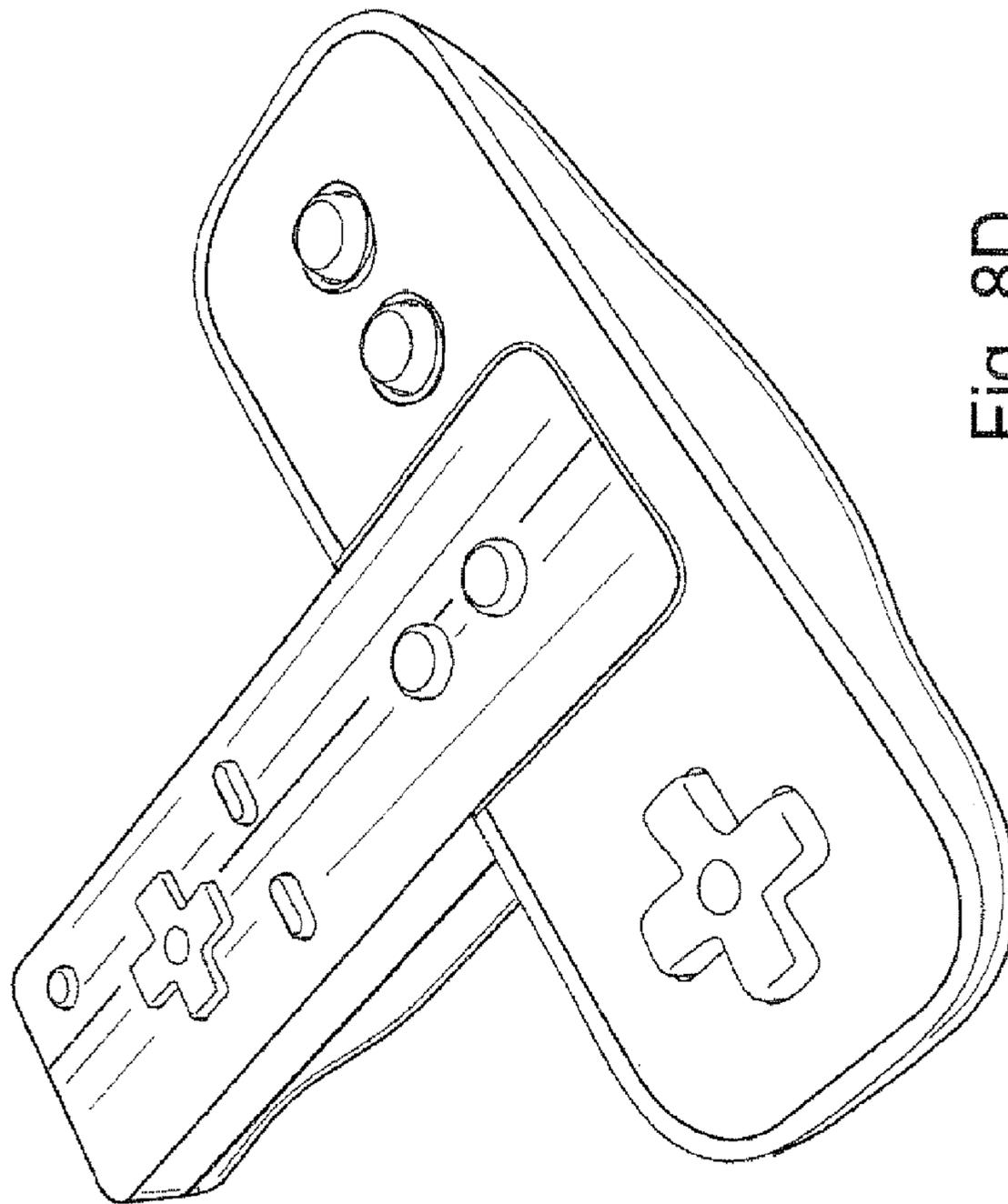


Fig. 8D

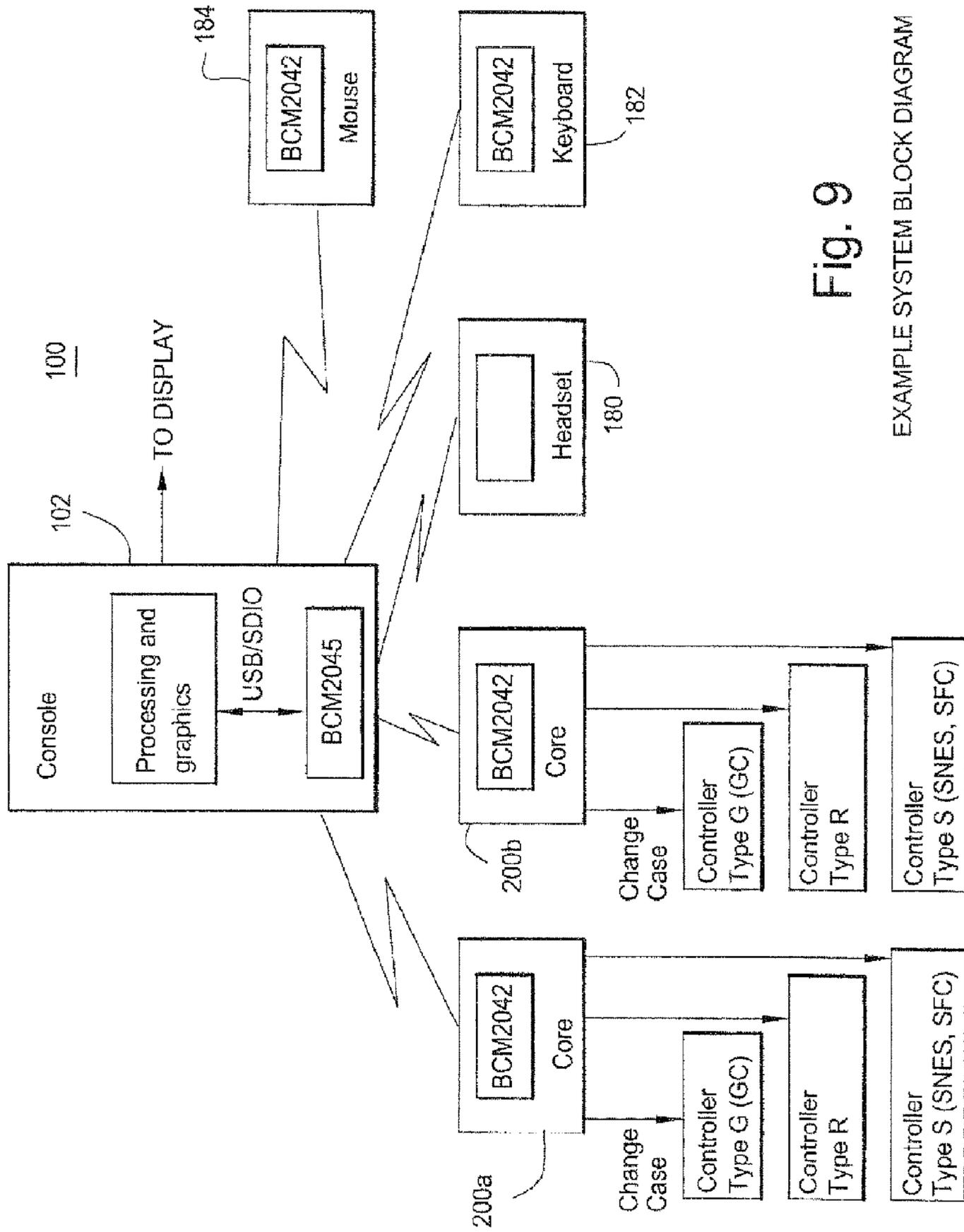


Fig. 9

EXAMPLE SYSTEM BLOCK DIAGRAM

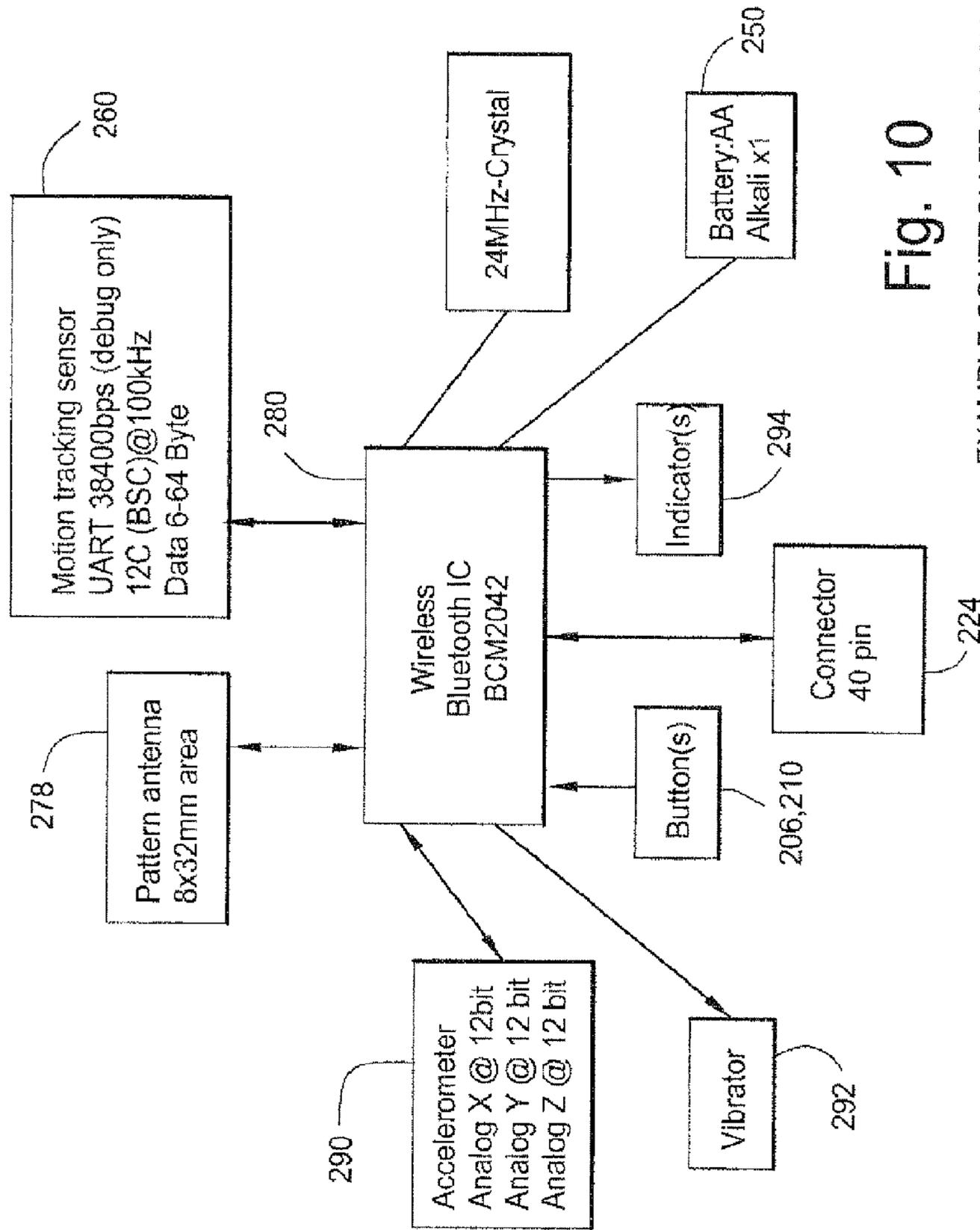


Fig. 10

EXAMPLE CONTROLLER BLOCK DIAGRAM

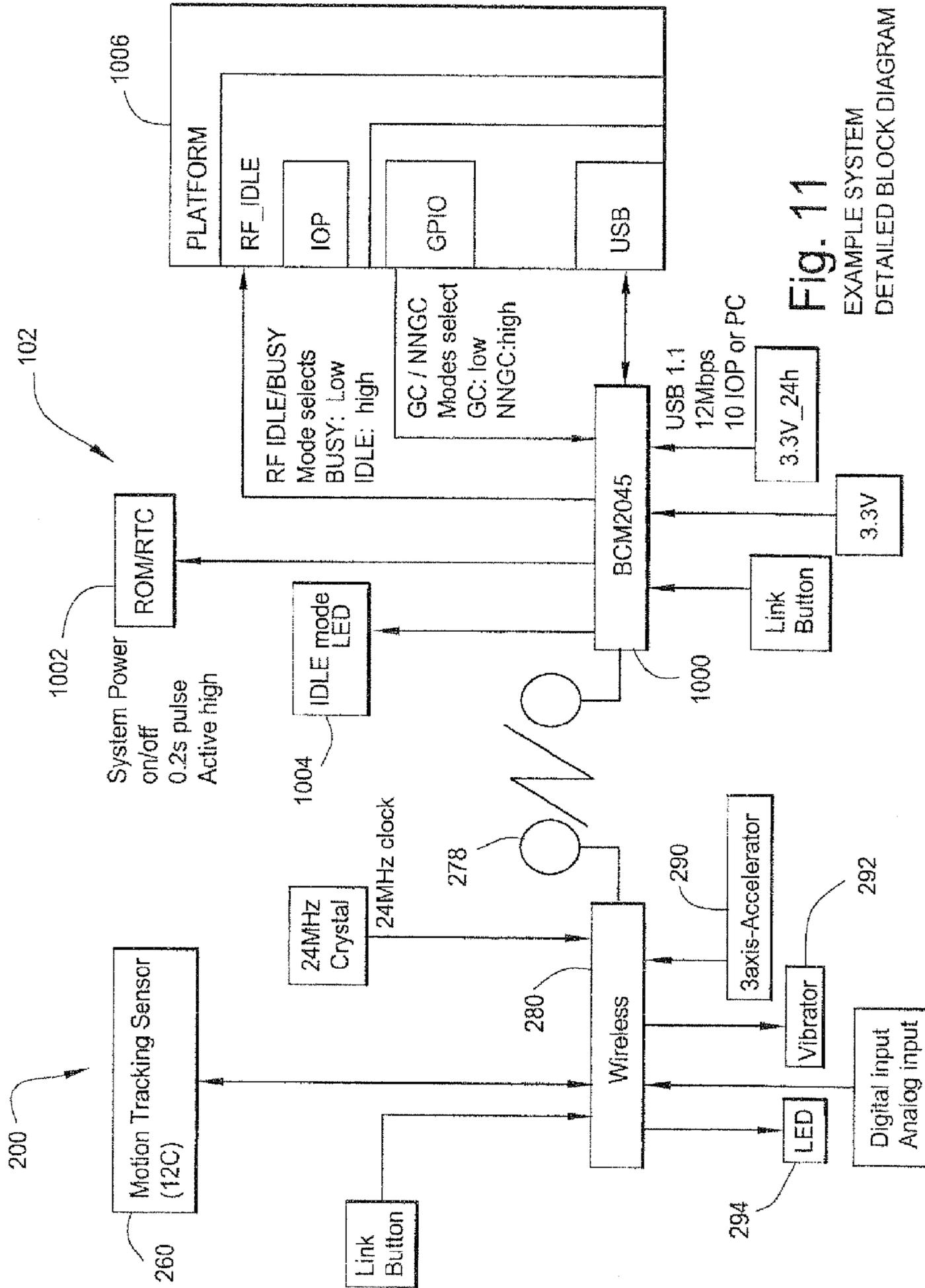


Fig. 11  
EXAMPLE SYSTEM  
DETAILED BLOCK DIAGRAM

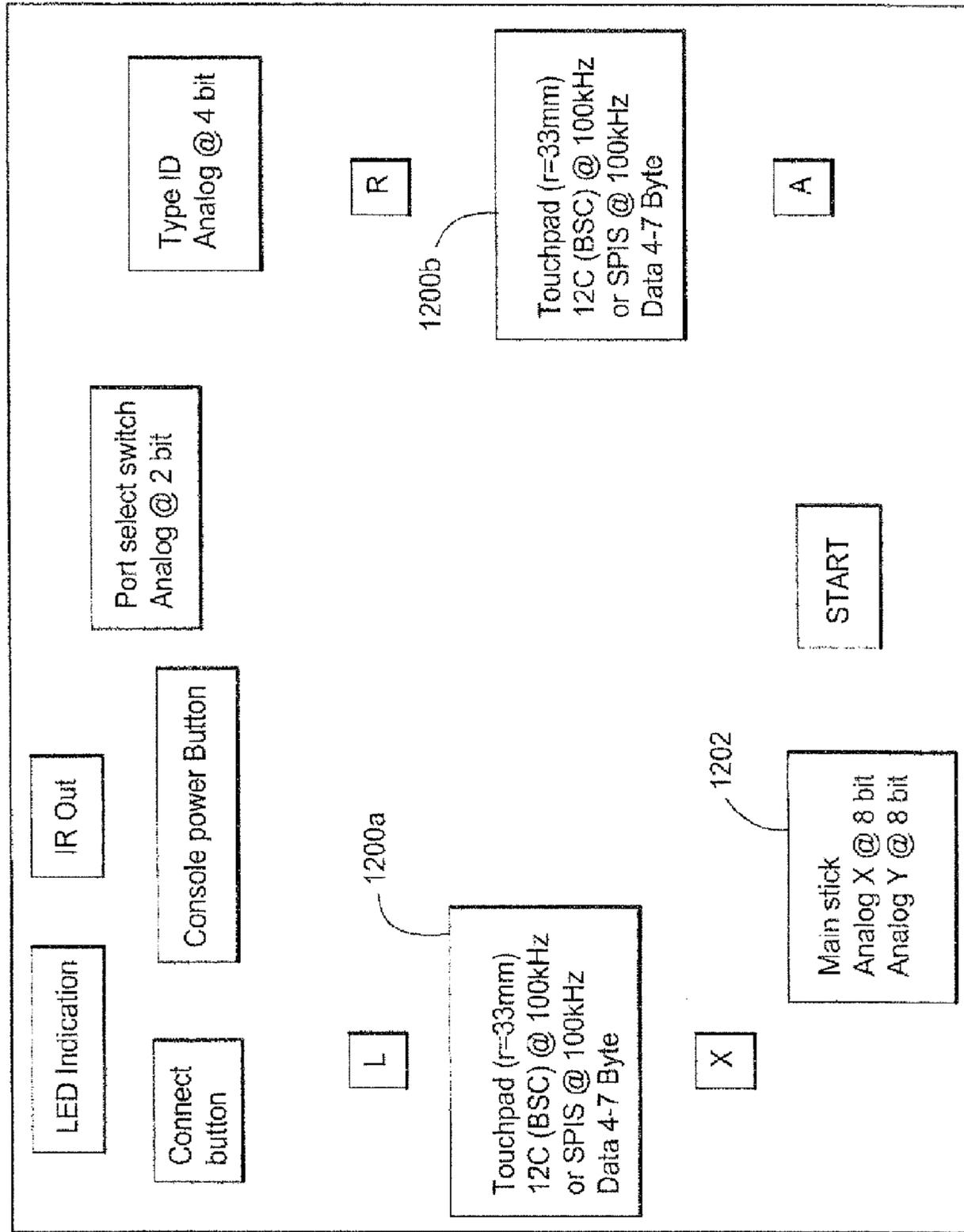


Fig. 12A EXAMPLE EXPANSION UNIT

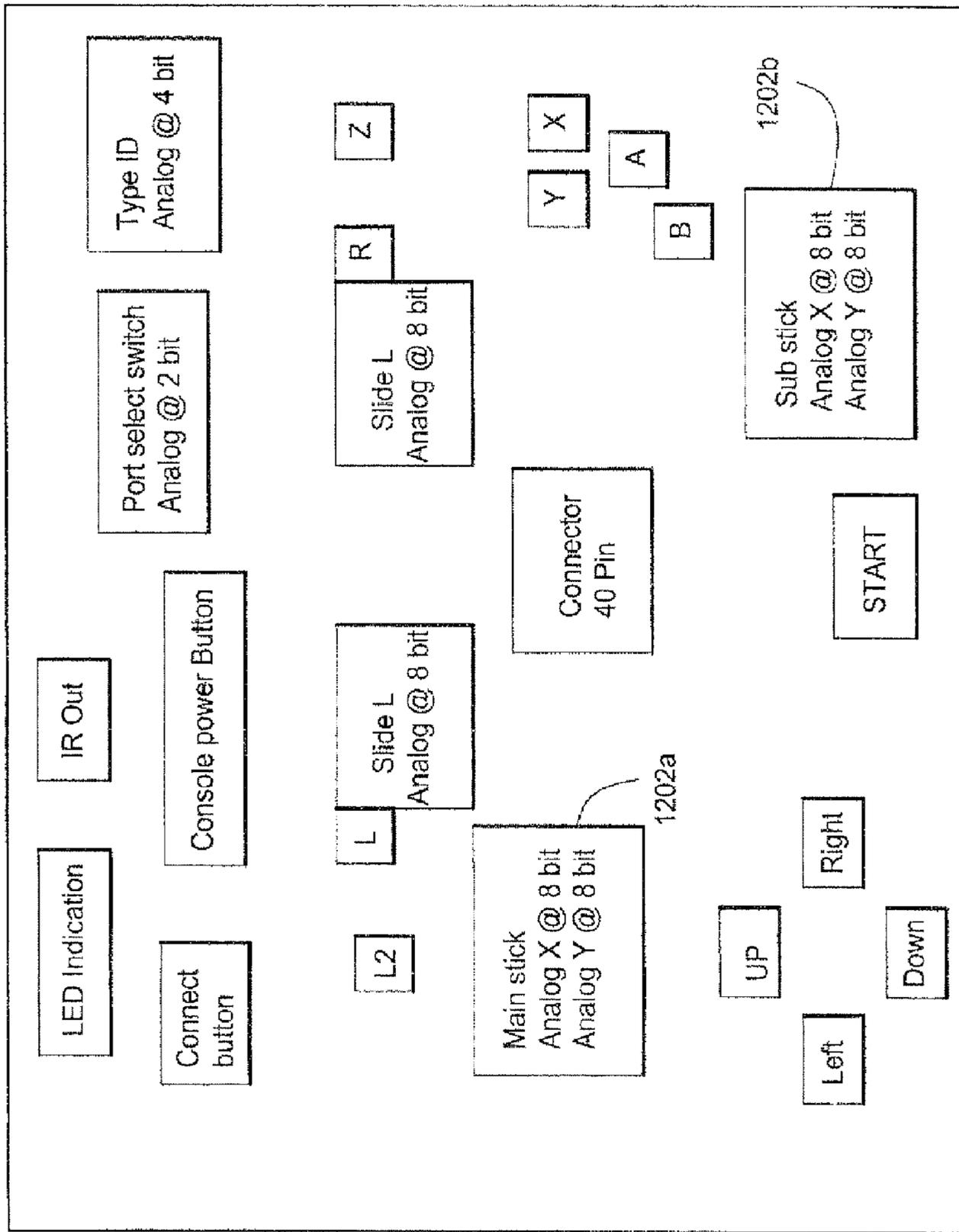


Fig. 12B EXAMPLE EXPANSION UNIT

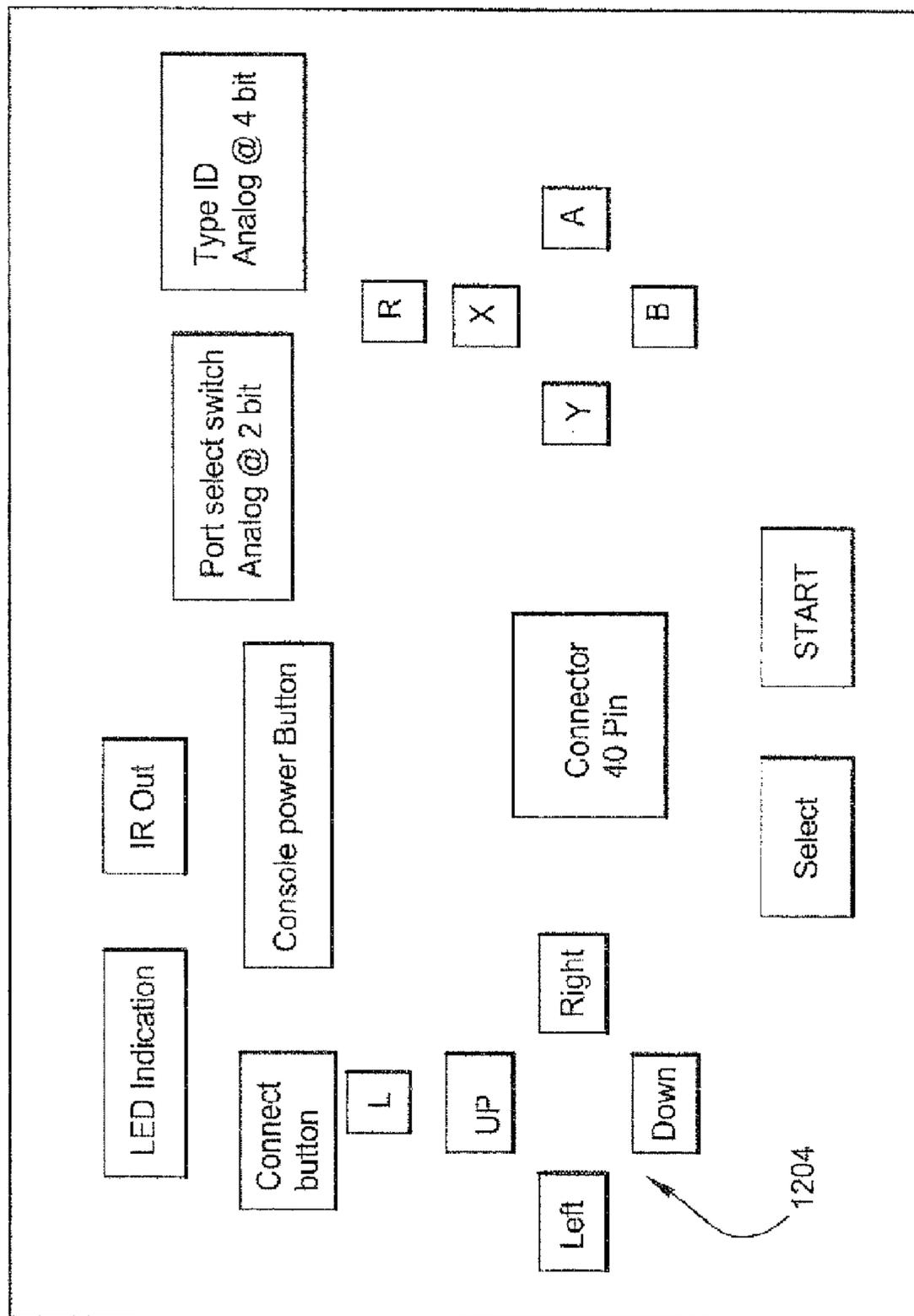


Fig. 12C

EXAMPLE EXPANSION UNIT

## VIDEO GAME SYSTEM WITH WIRELESS MODULAR HANDHELD CONTROLLER

**Matter enclosed in heavy brackets [ ] appears in the original patent but forms no part of this reissue specification; matter printed in italics indicates the additions made by reissue; a claim printed with strikethrough indicates that the claim was canceled, disclaimed, or held invalid by a prior post-patent action or proceeding.**

*This application is a reissue of U.S. Pat. No. 8,430,753, for which more than one reissue application has been filed, namely application Ser. No. 14/694,783 filed on Apr. 23, 2015 which is also a reissue of U.S. Pat. No. 8,430,753.*

### CROSS-REFERENCES TO RELATED APPLICATIONS

This application is a reissue of U.S. application Ser. No. 13/071,088 (now U.S. Pat. No. 8,430,753), filed Mar. 24, 2011, which is a continuation of U.S. application Ser. No. 11/532,328, filed Sep. 15, 2006, which claims priority from provisional application No. 60/716,937, filed on Sep. 15, 2005. This application is also related to U.S. application Ser. No. 11/446,187, filed on Jun. 5, 2006; and U.S. application Ser. No. 11/446,188, filed on Jun. 5, 2006, the disclosures of which are incorporated herein by reference.

### FIELD

The technology herein relates to consumer electronics, and more particularly to video game and entertainment systems. In still more detail, the technology herein relates to a home video game system including a modular remote wireless handheld control device with capabilities including position sensing.

### BACKGROUND AND SUMMARY

Computer graphics technology has come a long way since video games were first developed. Relatively inexpensive 3D graphics engines now provide nearly photo-realistic interactive game play on home video game and personal computer hardware platforms costing only a few hundred dollars.

Most game players demand great graphics, but the core of video game play is the man-machine interface—the interaction between the (human) game player and the gaming platform. Video games are fun and exciting to play because the game player can interact with the game and affect or control the gaming events and outcome. Since the essence of an enjoyable video game play experience relates to the way the user interacts with the game and the game playing system, user input details tend to be important to the success and marketability of home video game play systems.

One aspect of the video game user interface relates to how the user controls the position of one or more objects on the display. Much work has been done on this user interface aspect in the past. For example, the first Magnavox Odyssey home video game systems provided detachable handheld controllers with knobs that allowed the game player to control the horizontal and vertical positioning of objects on the screen. Pong®, another early home video game system, had a very simple user interface providing controls the players manipulated to control the positioning of paddles on the screen. Nintendo's Game and Watch® early handheld video

game systems used a “cross-switch” as described in Nintendo's U.S. Pat. No. 4,687,200 to control the position of objects on the screen. These were relatively simple yet effective user interfaces.

In recent years, video game system handheld controllers have tended to become increasingly more complicated and more capable. Video game platforms offered by Nintendo and others have provided joysticks, cross-switches or other user-manipulable controls as a means for allowing the user to control game play in a variety of simple and sophisticated ways. Many handheld controllers provide multiple joysticks as well an array of trigger buttons, additional control buttons, memory ports, and other features. Rumble or vibration effects are now common, as are wireless capabilities. Home video game manufacturers supply a variety of user input devices, and game accessory manufacturers often provide an even wider array of input device options. For example, some in the past have also tried to develop a video game handheld controller that senses the orientation of the handheld controller itself to control object position on the display. See U.S. Pat. No. 5,059,958 assigned to the present assignee.

One challenge that some have confronted in the past relates to cross-platform video game play. Generally, most video game system manufacturers differentiate new gaming systems from other or previous ones by providing unique user interface features including for example handheld controller configurations. Video games for play on different home video game platforms may therefore use different handheld controller configurations. While it may be possible in some cases to “remap” the user controls from one interface configuration to another so a game for one platform can be controlled using a different input control interface, such remapping may be less than optimal and/or change the game play experience in significant ways. For example, playing a game using a four-active-position cross-switch to control the movement of the main character on the screen may be quite a different experience for the user as compared with using an analog or digital joystick offering many different directional positions.

Furthermore, most video game platforms in the past have provided a single basic user interface that is used for all games playable on the platform. Even though different video games may provide quite different game play, video game developers have become skilled at using the common set of user input controls provided by the platform to control various different games. For example, most games developed to run on the Nintendo GameCube home video game system make use of the same handheld controller inputs comprising two joysticks, trigger switches and additional miscellaneous controls. Some games allocate different controls to different functions. For example, in one game, the left-hand joystick might navigate a 2D map view of a battlefield whereas in another game that same control might be used to allow the user to adjust virtual camera position or direction within a three-dimensional world.

The technology herein advances home video game user interfaces in ways not previously envisioned, to provide a more flexible and satisfying user experience across an ever increasing and divergent range of video games and other applications.

One illustrative non-limiting exemplary aspect of the technology herein provides for positioning video game objects on the screen in response to the position of a handheld controller relative to the display. Rather than moving a joystick or cross-switch, the user simply moves the entire handheld controller. The motion of the controller is sensed and used to control the position of objects or other parameters in connection with video game play.

Another exemplary non-limiting illustrative aspect of the technology herein provides a handheld controller with a modular design. The basic controller functionality including wireless connectivity, vibration generation, position sensing, orientation sensing and other features are provided within a core or basic handheld controller unit. This core unit can control many or most videogame input functions and play most games. However, for enhanced input functionality, the core unit can be plugged into an expansion controller assembly providing additional controls, inputs and other functionality. As one example, the core unit can be plugged into a first accessory expansion unit providing touch pads when it is desired to play videogames requiring touch pad input. The same core unit can be plugged into a different expansion unit providing joysticks and other input devices to play videogames designed for joystick inputs. The same core controller can be plugged into a still additional expansion unit when the player wishes to interact with a videogame system using a simpler control interface providing a cross-switch and additional input buttons. In one exemplary illustrative non-limiting implementation, some of the accessory units are designed to mimic earlier or different videogame platforms to allow the videogame system to match user interactivity experiences provided by such other systems.

#### BRIEF DESCRIPTION OF THE DRAWINGS

These and other features and advantages will be better and more completely understood by referring to the following detailed description of exemplary illustrative non-limiting implementations in conjunction with the drawings, of which:

FIG. 1 shows an exemplary illustrative videogame system being operated in a typical home game playing environment;

FIG. 2 shows an exemplary illustrative non-limiting implementation of a handheld videogame controller;

FIGS. 2A-2E show different views of the FIG. 2 implementation being grasped by the hand;

FIG. 2F shows exemplary two-handed operation;

FIGS. 3 and 3A show exemplary illustrative variations of the FIG. 2 controller with a top plate removed;

FIG. 4 shows a bottom view of the FIG. 2 controller;

FIG. 5 shows a bottom view of the FIG. 2 controller with bottom cover removed;

FIG. 6 shows a side and front perspective view of the exemplary FIG. 2 controller;

FIG. 6A shows an additional exemplary view of the FIG. 2 controller including a head pivot or tilt feature;

FIGS. 6B-6H show different views of an alternative exemplary illustrative non-limiting handheld controller implementation;

FIGS. 7A and 7B show different views of the FIG. 2 controller when used to detect position relative to light emitters;

FIGS. 8A, 8B, 8B-1, 8C and 8D show exemplary illustrative non-limiting expansion controller units into which the FIG. 2 core unit may be removably disposed and interconnected;

FIG. 9 shows an exemplary illustrative non-limiting block diagram implementation of the FIG. 1 system;

FIG. 10 shows an overall block diagram of the FIG. 2 controller;

FIG. 11 is an exemplary illustrative non-limiting block diagram of an overall system; and

FIGS. 12A-12C show exemplary illustrative non-limiting block diagrams of different expansion unit controller configurations.

#### DETAILED DESCRIPTION

Example Overall Exemplary Illustrative Non-Limiting System

FIG. 1 shows an illustrative, exemplary non-limiting implementation of a video game system 100. System 100 includes a main unit 102 sometimes also called a "console." Main unit 102 executes applications including video game software, and generates images for display on the display 104 of a conventional home color television set or other display device 106. Main unit 102 also generates sound for reproduction by TV set 106. People 108 can interact with the video game play to control or affect the images and the progression of the game or other application.

Main unit 102 in the exemplary illustrative non-limiting implementation can be used to play a variety of different games including driving games, adventure games, flying games, fighting games, and almost any other type of game one might think of. The video game software that main unit 102 executes may be delivered on bulk storage devices such as optical disks, semiconductor memory devices or the like, it may be down loaded into the main unit over a network, or it may be provided to the main unit in any other desired manner. Main unit 102 may also be capable of performing applications in addition to video games (e.g., movie playback, email, web browsing, or any other application one can imagine). A security system built into main unit 102 may ensure that only authorized or authentic applications are executed.

FIG. 1 shows people ("video game players") 108a, 108b interacting with main unit 102 to play a video game. While two players 108 are shown, any number of players may interact with the main unit 102 at any given time. In the exemplary illustrative non-limiting implementation shown, each video game player 108 holds and operates a wireless handheld control unit ("controller") 200. The players 108 operate these controllers 200 to generate input signals. The controllers 200 communicate their input signals wirelessly to main unit 102. Such wireless communications can be by any convenient wireless method such as radio transmission, infrared, ultraviolet, ultrasonic or any other desired technique. Wireless peripherals could include Bluetooth, 802.11 (WiFi), HiperLAN/1, HiperLAN/2, HomeRF, VWB, WiMax or other. In other implementations, cords or cables could be used to connect controllers 200 to main unit 102.

In the exemplary illustrative non-limiting implementation of system 100 shown, players 108 operate handheld controllers 200 in various ways to provide input signals to main unit 102. For example, players 108 may depress buttons or otherwise manipulate other controls on controllers 200 to generate certain input signals. The effect of such control manipulations in the exemplary illustrative non-limiting implementation depends, at least in part, on the particular software that main unit 102 is executing. For example, depressing a certain button may provide a "start game" or "pause game" in some contexts, and may provide different functions (e.g., "jump character") in other contexts.

In the illustrative exemplary non-limiting implementation shown, controllers 200 have internal capabilities for detecting position and/or orientation. In the exemplary illustrative non-limiting implementation, players may change the orientation or position of controllers 200 to generate input signals. Controllers 200 may sense position and/or orientation and report that information to main unit 102. Main unit 102 may use that information to control or affect video game play or other functionality.

In one exemplary illustrative non-limiting implementation, each handheld controller 200 may include an internal posi-

tion, attitude or orientation sensor that can sense the position, attitude and/or orientation of the controller relative to the earth's gravitational force. Such a sensor may for example comprise a 3-axis accelerometer that can sense orientation (or changes in orientation) of the controller **200** relative to the direction of earth's gravitational pull. The output of such a sensor may be reported to main unit **102** and used for example to control motion of a character displayed on display **104**.

In addition, the exemplary illustrative non-limiting implementation of system **100** shown in FIG. **1** includes wireless emitters **110a**, **110b**. These wireless emitters **110** may be placed on each side of display **104** in alignment with the edges of the screen. The wireless emitters **110** may for example each comprise one or more light emitting diodes or other devices **112** that emit infrared or other electromagnetic or other radiation.

In one exemplary illustrative non-limiting implementation, the energy that emitters **110** emit has a wavelength or other characteristic that allows the radiation to be readily distinguished from ambient radiation. In the exemplary illustrative non-limiting implementation, handheld controllers **200** each detect the radiation emitted by emitters **110** and generate signals indicative of the controller's relative position and/or movement. Multiple controllers **200** can sense the same emitted radiation and generate different signals depending on the position or movement of that particular controller. Controllers **200** report the relative position and/or movement signal to main unit **102**. Main unit **102** may take any appropriate action in response to such signals such as, for example, moving, rotating or otherwise changing a game character or other object or background on the display **104**, scrolling a screen, selecting a different game function, or taking other actions.

In the exemplary illustrative implementation shown, the emitters **110** are added or retro-fitted onto a conventional color television set **106** by for example using an adhesive to attach the emitters onto the top housing of the television set on the extreme left and right of the housing in alignment with the edges of display **104**. In this exemplary illustrative non-limiting implementation, emitters **110** can be connected to main unit **102** by cables or wires run behind the television set **106**. In other implementations, emitters **110** could be built-in to television set **106** or mounted separately (e.g., on a set top box or otherwise). In still other implementations, emitters **110** could possibly be replaced with small reflective surfaces attached by adhesive to corners of display **104**, and controllers **200** could emit electromagnetic radiation and receive reflections from the reflective surfaces (e.g., whose angle of incidence is equal to angle of reflectance). In still other implementations, controllers **200** could emit electromagnetic radiations and units **110** could include sensors that sense the emitted radiation. Other implementations are possible.

Example Illustrative Non-Limiting Handheld Controller Design

FIG. **2** shows a perspective view of an exemplary illustrative non-limiting implementation of controller **200**. Controller **200** provides a housing **202** that is graspable by one hand (see FIGS. **2A**, **2B**, **2C**). Controller **200** in the exemplary illustrative non-limiting implementation is compact and has a solid rugged feel to it. It can be dropped onto a hard surface without breaking. Portions of its housing **202** are curved to fit comfortably into the hand (see FIGS. **2A**, **2B**, **2C**).

As shown in FIG. **2A**, the thumb can be positioned to operate controls on a top control surface **204** while the fingers are comfortably wrapped around the controller's bottom surface **203**. The digits of the hand (including the thumb) can operate the different controls arrayed on a top control surface **204** and elsewhere on the controller without fatigue and with-

out wasted or undue motion. The controller **200** is small and lightweight enough to be comfortably held and supported for long periods of time without fatigue. Controller **200** is dimensioned to exactly and comfortably fit the average hand—not too small, not too big. The controls are arranged such that the controller **200** can be operated equally easily by the right hand or the left hand.

The controller housing **202** provides a top control surface **204** providing an array of controls depressible with the digits (fingers and/or thumbs) of the user's hand. In one illustrative non-limiting implementation, the user may operate a direction switch **206** with a thumb or forefinger to indicate a direction in two dimensions. In the illustrative non-limiting exemplary implementation shown, the directional switch **206** may comprise a switch surface **208** that can be rocked in different directions to provide different direction signals. The simplest form of such a directional switch **206** may comprise a so-called "cross switch" (a switch in the shape of a cross) that can be rocked in four different directions to provide four different, mutually exclusive direction signals (i.e., up, down, left, right). A somewhat more flexible form of a directional switch **208** may comprise a circular switch surface **208** that can be rocked in any of a number of different directions to provide corresponding different control signals indicating for example twelve, sixteen or more different directions. Other directional switch configurations could be used to provide a much higher number of directional inputs approaching, equaling or exceeding the number of signals from an analog or digital joystick. A touch or "joy" pad, a pointing stick, a trackball, or other input device could be used instead of or in addition to a switch. If a joystick were used, it could likely be operated in a direction-indicating mode as opposed to a "drag displacement" mode. Other arrangements could include touch sensitive display(s) or other types of displays.

Top control surface **204** in the exemplary illustrative non-limiting implementation also provides a pair of thumb-operated control switches **210a**, **210b**. These control switches **210a**, **210b** can be oriented as shown, or they could each be rotated say 45 degrees so as to be angularly displayed from one another in order to expose more surface area to a thumb positioned to operate either control switches **210** or directional switch **206**. Control switches **210a**, **210b** could be used to actuate a variety of game or other functions including for example "start" and "select" functions.

Top control surface **204** may also provide an additional push button **214** operated by the thumb for other functionality selection. A slide switch **216** on the side of housing **202** may be operated to provide on/off or other functionality. Depending on requirements, a slide switch **216** could be located on either or both side surfaces of the exemplary controller **200**.

Top control surface **204** in the exemplary illustrative non-limiting implementation further provides two additional controls **212a**, **212b** that may comprise indicator lamps or lights. Alternatively, such controls **212** could comprise additional operable controls such as push button switches, so-called "pointing stick" type input devices, or other input devices. These controls **212** may be relatively dormant or little used (while not being subject to accidental operation) when the controller **200** is operated in the hand positions shown in FIGS. **2A**, **2B**, **2C**, **2D**, **2E**, **2F**. However, another way of using controller **200** is to hold the controller in one hand (or place it on a flat surface such a table) and operate its controls with the forefinger and other fingers of the other hand. In such an alternate operating mode, the forefinger could be used to operate controls **212a**, **212b** if they are activatable input devices as opposed to indicators. FIG. **2D** for example shows that in one exemplary illustrative implementation, the user

may move his or her thumb forward or backward to access different controls. FIG. 2D shows the ability to move the thumb side to side to provide different control actuations. FIG. 2F shows an exemplary illustrative non-limiting implementation whereby the user can hold the handheld controller in both hands and operate it with both left thumb and right thumb simultaneously.

FIG. 3 shows an exploded view of controller 200 with a top plate 204 removed to reveal a printed circuit board 220. Metallic pathways (not shown) and associated solder or other electrical interconnections may be used to electrically interconnect components via PC board 220. Various components including integrated circuit chips 222 (e.g., a wireless RF “Bluetooth” or other communications device, an accelerometer and other components) may be mounted to the printed circuit board 220. The printed circuit board 220 may also serve as a mounting surface for the directional switch 206, controls 210, 212, etc. The printed circuit board 220 in one exemplary illustrative non-limiting implementation provides a rugged fiberglass structure used to both mount and electrically interconnect components of controller 200. The same or different printed circuit board 220 may provide an edge or other connector 224 for use in electrically connecting controller 200 to other devices (to be described below). FIG. 3A shows a different exemplary illustrative non-limiting implementation with a different exemplary non-limiting control layout. Further configurations are also possible.

FIG. 4 shows a bottom view of an exemplary illustrative non-limiting implementation of controller 200. The bottom view reveals an access plate 230 for installing one or more small conventional removable/replaceable battery cells (see FIG. 5). FIG. 4 also shows an additional “trigger” type switch 232 operable by the forefinger when the controller is held in the hand (see FIG. 2A, 2C). “Trigger” switch 232 may for example sense pressure to provide a variable input signal that depends on how much pressure the user’s forefinger is exerting on the switch. Such a variable-pressure “trigger” switch 232 can be used in a video game to fire weapons, control the speed of a vehicle in a driving or space game, or provide other functionality.

In the exemplary illustrative non-limiting exemplary implementation shown, the trigger switch 232 is disposed on an angular surface 234 of the bottom surface 240 of controller 200 within a V-shaped depression 236 located near the front distal end 238. This V-shaped depression 236 is dimensioned to comfortably provide a resting and grasping slot for the forefinger (see FIG. 2C) which may be slightly rotated and pulled toward the user between a resting position (see FIG. 2C) and an actuation position (see FIG. 2A). With the middle, ring and pinkie fingers wrapped around and grasping the curved center 240c and rear 240r portions of the controller’s bottom surface 203 and the forefinger comfortably engaged within the v-shaped depression 236, the user feels quite comfortable holding and operating controller 200 with one hand and positioning and aiming it precisely in desired directions.

FIG. 5 shows an exploded view of controller 200 with the lower housing portion 240 removed to expose internal components such as removably replaceable batteries 250 and associated holders/contacts 252, and trigger switch 232. While two batteries 250 are shown in FIG. 5, any number of batteries (e.g., one, three, etc.) can be used depending on weight, power and other requirements. Note that to replace batteries 250, the user would not usually remove the lower housing 240 but rather would simply remove the access plate 230. In other configurations, the controller 200 might be rechargeable and batteries 250 could be of the nickel-cadmium or other type that do not require routine replacement. In

such exemplary configuration, the controller 200 could be placed into a charging station to recharge the batteries 250 instead of expecting the user to replace the batteries. While FIG. 5 shows a separate edge connector 224, it is possible that the edge connector could be formed by a distal edge of the printed circuit board 220.

FIGS. 6B-6H show an additional exemplary non-limiting illustrative implementation of a handheld controller with a different control configuration. A power button 1002 may be used to activate power on the main unit 102. A control pad 206 provides directional input. An A button 1004 can be operated by the thumb instead of the control pad 206 to provide a momentary on-off control (e.g., to make a character jump, etc.). Select and start buttons 1006, 1008 may be provided for example to start game play, select menu options, etc. A menu button 1010 (which may be recessed to avoid accidental depression) may be provided to display or select menu/home functions. X and Y buttons may be used to provide additional directional or other control. Light emitting diodes or other indicators 1016a-d may be used to indicate various states of operation (e.g., for example to designate which controller number in a multi-controller environment the current controller is assigned). A connector 1018 is provided to connect the controller to external devices. FIG. 6C shows an underneath side perspective view, FIG. 6D shows a top plan view, FIG. 6E shows a side plan view, FIG. 6F shows a bottom plan view, FIG. 6G shows a front plan view, and FIG. 6H shows a rear plan view.

#### Example Illustrative Non-Limiting Optical Pointing Device Motion Detection

FIG. 6 shows a front perspective view of controller 200 illustrating an additional sensing component 260 also shown in FIG. 5. Sensor 260 in the exemplary illustrative non-limiting implementation is disposed on the “nose” or front surface 262 of controller 200 so that it points forward, looking down a pointing axis P. The direction of pointing axis P changes as the user changes the orientation of controller 200. It is possible to provide a pivot mechanism (see FIG. 6A) to allow the user to pivot the nose portion up and down to provide better ergonomics (e.g., the user could be sitting on the floor below the level of the emitters 112 and still be able to point directly forward, with the sensor 260 axis P being aimed upwardly).

Sensing component 260 in the exemplary illustrative non-limiting implementation comprises an infrared-sensitive CCD type image sensor. Sensor 260 may comprise a one-dimensional line sensor or it could comprise a 2D sensor such as for example a low resolution monochrome CCD or other camera. Motion tracking sensor 260 may include a lens and a closely coupled digital signal processor to process incoming images and reduce the amount of information that needs to be conveyed to main unit 102. In one exemplary non-limiting implementation, motion tracking sensor 260 may include a 128 pixel by 96 pixel relatively low resolution monochrome camera, a digital signal processor and a focusing lens. More than one such sensor could be used if desired.

In the exemplary illustrative non-limiting implementation, sensor 260 gives controller 200 optical pointing capabilities. For example, movement of the controller 200 can be detected (e.g., by the controller itself) and used to control what is being displayed on display 104. Such control could include for example scrolling of the screen, rotation or other reorientation of display objects in response to rotation/reorientation of controller 200, and other responsive interactive displays. Such control may provide a better moment arm as compared to a joystick.

In the exemplary illustrative non-limiting implementation, sensor **260** is designed and configured to sense the emitters **110** shown in FIG. 1. FIGS. 7A, 7B show that sensor **260** has a certain well defined field of view (FOV) symmetrical with the sensor pointing axis P. For example, the sensor **260** may have a field of view of about 20.5 degrees on each or every side of pointing axis P (this particular field of view angle is a design choice; other choices are possible in other configurations). Such well defined field of view provides an acute triangularly shaped (or cone-shaped for 2D sensor configurations) viewing area that sensor **260** can “see”—with the base of the triangle increasing in length as distance from the controller **200** increases. Sensor **260** also has a well defined sensitivity such that it can only “see” IR emissions above a certain range of intensity. Emitters **112** are designed in the exemplary illustrative non-limiting to provide sufficient output power and beam spreading consistent with the sensitivity of sensor **260** such that sensor can “see” the emitters at ranges consistent with how video game players arrange themselves in a room relative to a television set **106** (taking into account that a player may sometimes sit close to the television when playing by himself, that players may be sitting on the floor, standing, sitting on chairs or couches or other furniture, etc.).

In more detail, FIG. 7A shows that in the exemplary illustrative non-limiting implementation, the overall field of view of sensor **260** is wider than the typical separation of emitters **112** and is also wider than beam width of each emitter **112**. In one exemplary illustrative non-limiting implementation, the ratio of the beam spreading angle (e.g., 34 degrees) of the beams emitted by emitters **112** to the field of view (e.g., 41 degrees) of sensor **260** may be approximately 0.82 (other ratios are possible). Plural emitters **112** can be used at each emission point to provide a wider beam (horizontal field of view) than might otherwise be available from only a single emitter, or a lens or other optics can be used to achieve desired beam width.

At an average distance from controller **200** to television set **106** and associated emitters **112** and assuming a maximum television screen size (and thus a maximum physical separation between the emitters), such a ratio may maximize the displacement of two radiation “dots” or points appearing on the CCD sensor array **270** that sensor **260** comprises. Referring to FIG. 7A for example, when the central axis of sensor **260** is directed centrally between displaced emitters **112** (note that in one exemplary illustrative non-limiting implementation, the emitters are disposed on either side of the television display and are therefore relatively far apart relative to the resolution of the image being generated), the CCD array **270** that sensor **260** defines will register maximal illumination at two points near the ends of the sensor array. This provides a higher degree of resolution when the sensor **260**’s central axis P is displaced relative to the center of separation of the emitters **112** (see FIG. 7B) even when using a relatively low resolution CCD imaging array (e.g., a 128-cell long sensor array). Note that while a linear array **270** is illustrated in FIGS. 7A, 7B for sake of convenience, a rectangular array could be used instead.

In the illustrative, exemplary non-limiting implementation shown, it is unnecessary to modulate or synchronize emitters **112** in the exemplary illustrative non-limiting implementation, although it may be desirable to power down the emitters when not in use to conserve power usage. In other arrangements, however, synchronous detection, modulation and other techniques could be used.

The exemplary illustrative non-limiting implementation of controller **200** and/or main unit **102** includes software or hardware functionality to determine the position of controller

**200** relative to emitters **112**, in response to the illumination maxima sensed by sensor **260**. In one example illustrative non-limiting implementation, controller **200** includes an onboard processor coupled to the sensor **260** that interprets the currently detected illumination pattern, correlates it with previous sensed illumination patterns, and derives a current position. In another example illustrative non-limiting implementation, controller **200** may simply report the sensed pattern to main unit **102** which then performs the needed processing to detect motion of controller **200**. The sensor could be affixed to the human operating the system to provide additional control.

Since it may not be desirable to require end users of system **100** to measure and program in the precise distance between the emitters **112** and since television sets vary in dimension from small screens to very large screens, controller **200** does not attempt to calculate or derive exact positional or distance information. Rather, controller **200** may determine movement changes in relative position or distance by analyzing changes in the illumination pattern “seen” by CCD array **270**.

It may be possible to ask the user to initially point the controller **200** at the center of the television screen **104** and press a button, so as to establish a calibration point (e.g., see FIG. 7A)—or the game player may be encouraged to point to the center of the screen by displaying an object at the center of the screen and asking the user to “aim” at the object and depress the trigger switch. Alternatively, to maximize user friendliness, the system can be self-calibrating or require no calibration at all.

Differences in the illumination pattern that CCD array **270** observes relative to previously sensed patterns (see e.g., FIG. 7B) can be used to determine or estimate movement (change in position) relative to previous position in three dimensions. Even though the CCD array **270** illumination shown in the FIG. 7B scenario is ambiguous (it could be obtained by aiming directly at emitter **112a** or at emitter **112b**), recording and analyzing illumination patterns on a relatively frequent periodic or other basis (e.g., 200 times per second) allows the controller to continually keep track of where it is relative to the emitters **112** and previous controller positions. The distance between the illumination points of emitters **112** and CCD array **270** can be used to estimate relative distance from the emitters. Generally, game players can be assumed to be standing directly in front of the television set and perpendicular to the plane of display **106**. However, scenarios in which controller **200** is aimed “off axis” such that its central axis P intersects the plane of emitters **112** at an angle other than perpendicular can also be detected by determining the decreased separation of the two maximum illumination points on the CCD array **270** relative to an earlier detected separation. Care must be taken however since changes in separation can be attributed to changed distance from the emitters **112** as opposed to off-axis. Simpler mathematics can be used for the motion and relative position detection if one assumes that the player is aiming the sensor axis P directly at the display **104** so the axis perpendicularly intersects the plane of the display.

Software algorithms of conventional design can ascertain position of controller **200** relative to emitters **112** and to each logical or actual edge of the display screen **104**. If desired, controller **200** may further include an internal conventional 3-axis accelerometer that detects the earth’s gravitational forces in three dimensions and may thus be used as an inclinometer. Such inclination (orientation) information in three axis can be used to provide further inputs to the relative position-detecting algorithm, to provide rough (x, y, z) position information in three dimensions. Such relative position

information (or signals from which it can be derived) can be wirelessly communicated to main unit 102 and used to control the position of displayed objects on the screen.

Example Modular Control Interface Controller Expansion

FIGS. 8A-8D illustrate an additional feature of the exemplary illustrative non-limiting implementation of controller 200. In accordance with this additional feature, the controller 200 may be used as the “core” of a modular, larger handheld controller unit by connecting the controller 200 to an additional expansion unit 300. Core controller 200 may “ride piggyback” on an expansion unit 300 to easily and flexibly provide additional control interface functionality that can be changed by simply unplugging the controller from one expansion unit and plugging it in to another expansion unit.

FIG. 8A shows one exemplary illustrative non-limiting such additional expansion unit 300 including a housing 302 having a control surface 304 providing an array of additional controls including for example a joystick 306, a cross-switch 308 and various push-button controls 310. Expansion unit 300 includes a depression such that when the rear portion of controller 200 is inserted into the depression, the resulting combined unit provides an overall planar T-shaped control surface that combines the expansion unit 300 control surface with the controller 200 control surface in a flush and continuous manner. In such case, the user may grasp the expansion unit 300 with two hands and may operate the controls of controller 200 (see FIG. 8B-1) or controls on the expansion unit 300. Expansion unit 300 thus effectively converts the controller 200 designed to be held in a single hand into a two-handed controller while also supplying additional controls.

FIG. 8B shows a further expansion unit 300' having a somewhat different control configuration. FIGS. 8C and 8D show additional non-limiting illustrative example expansion units.

As shown in FIG. 8B-1, expansion units 300 may provide all of the controls that the user would operate to control a video game when controller 200 is plugged into the additional unit. This provides a high degree of flexibility, since any number of additional units 300 of any desired configuration can be provided. Such additional units 300 can be manufactured relatively inexpensively since they can rely on controller 200 for power, processing, wireless communications and all other core functions. In the exemplary illustrative non-limiting implementation, controller edge connector 224 exposes sufficient connections and a sufficiently flexible interface such that an expansion unit 300 of virtually any desirable description can be compatibly used.

One possible motivation for manufacturing expansion units 300 is to provide control interface compatibility with other video game platforms including for example legacy platforms such as the Nintendo Entertainment System, the Super Nintendo Entertainment System, the Nintendo 64, the Nintendo GameCube System, and the Nintendo Game Boy, Game Boy Advance and Nintendo DS systems. An expansion unit 300 providing a control interface similar or identical to for the example the Super Nintendo Entertainment System could be made available for playing Super Nintendo Entertainment System games on system 100. This would eliminate the desire to reprogram or rework Super Nintendo Entertainment System games for use with the newer or different interface provided by controller 200.

Another possible, more general motivation for additional expansion units 300 is to provide customized control interfaces for particular games or other applications. For example, it would be possible to develop a unit 300 with a steering wheel for driving games, a unit with a keyboard for text entry

applications, a unit with one or multiple touch pads for touch screen style games, etc. Any desired control configuration is possible and can be flexibly accommodated.

Still another possible application would be to use expansion units 300 to give different players of a multi-player game different capabilities. For example, one game player might use controller 200 “as is” without any expansion, another game player might use the expansion configuration shown in FIG. 12A, yet another game player might use the expansion configuration shown in FIG. 12B, etc. One could imagine a military battle game for example in which game players playing the role of tank drivers use an expansion unit that resembles the controls of a tank, game players playing the role of artillerymen use an expansion unit that resembles controls of heavy artillery, and a game player playing the role of a commanding general uses an expansion unit that provides more general controls to locate infantry, artillery and tanks on the field.

Example Illustrative Non-Limiting Block Diagrams

FIG. 9 shows a block diagram of an exemplary illustrative implementation of system 100. As described above, system 100 includes a main unit 102 and one or several controllers 200a, 200b, 200c, etc. Each controller 200 may be connected to any of additional expansion units 300 or may be used by itself, depending on the application. Additional wireless peripherals to system 100 may include a headset unit 180 for voice chat and other applications, a keyboard unit 182, a mouse or other pointing device 184, and other peripheral input and/or output units.

FIG. 10 is a block diagram of an exemplary illustrative non-limiting implementation of controller 200. In the example shown, controller 200 may comprise a wireless connectivity chip 280 that communicates bidirectionally with main unit 102 via a pattern antenna 278. Wireless communications chip 280 may be based on the Bluetooth standard but customized to provide low latency. In the example shown here, most or all processing is performed by the main unit 102, and controller 200 acts more like a telemetry device to relay sensed information back to the main unit 102. Such sensed inputs may include a motion tracking sensor 260, an accelerometer 290, and various buttons 206, 210, etc. as described above. Output devices included with or within controller 200 may include a vibrational transducer 292 and various indicators 294.

FIG. 11 shows an overall exemplary illustrative non-limiting system block diagram showing a portion of main unit 102 that communicates with controller 200. Such exemplary illustrative non-limiting main unit 102 portion may include for example a wireless controller 1000, a ROM/Real Time Clock 1002, an idle mode indicator 1004, a processor 1006 and various power supplies. Link buttons may be provided on each side of the communications link to provide manual input for synchronization/training/searching.

FIGS. 12A, 12B and 12C show different exemplary block diagram configurations for different expansion units 300. The FIG. 12A example includes dual touch pads 1200 and a joystick 1202 for touch screen compatible gaming; the FIG. 12B example includes two joysticks 1202 and other controls for games requiring two different joysticks (e.g., Nintendo GameCube legacy games); and the FIG. 12C example includes a cross-switch 1204 and other controls for more limited user interface type games (e.g., Nintendo Entertainment System legacy games).

Each expansion unit may be programmed with a 4-bit or other length “type” ID to permit controller 200 to detect which type of expansion unit is being used. Main unit 102 can adapt user interactivity based at least in part on the “type” ID.

## 13

While the technology herein has been described in connection with exemplary illustrative non-limiting implementations, the invention is not to be limited by the disclosure. The invention is intended to be defined by the claims and to cover all corresponding and equivalent arrangements whether or not specifically disclosed herein.

We claim:

1. A wireless handheld remote controller configured to be held in one hand, comprising:

a housing including an upper surface and a lower surface; at least one digit operable detector disposed on the upper surface;

at least one depressible trigger disposed on said lower surface;

an inertial sensor mounted in the housing;

a two dimensional radiation detector;

a processor that processes an output of the radiation detector and determines an illumination pattern;

a wireless transceiver that transmits information based on signals generated by the inertial sensor and the processor; and

an output device operatively coupled to the transceiver.

2. The controller of claim 1 wherein the radiation detector is disposed, at least in part, at a front portion of the housing.

3. The controller of claim 1, wherein the radiation detector comprises a two dimensional camera.

4. The controller of claim 1, wherein the radiation detector comprises:

a two dimensional radiation sensor array; and

an infrared filter that is mounted on the housing in front of the two dimensional radiation sensor array such that only infrared light passing through the filter is received by the radiation sensor array.

5. The controller of claim 1, wherein the radiation detector generates frames of two dimensional image data, and wherein the processor determines an illumination pattern for each frame of image data.

6. The controller of claim 5, wherein each illumination pattern comprises X and Y coordinates for illuminated objects appearing within a frame of image data.

7. The controller of claim 5, wherein each illumination pattern comprises X and Y coordinates for illuminated objects appearing within a frame of image data that have an intensity that rises above a predetermined threshold value.

8. The controller of claim 5, wherein each illumination pattern comprises X and Y coordinates for illuminated objects appearing within a frame of image data that emit infrared radiation having an intensity that rises above a predetermined threshold value.

9. The controller of claim 5, wherein the wireless transceiver transmits information regarding the illumination patterns for frames of image data.

10. The controller of claim 9, wherein the inertial sensor comprises an accelerometer.

11. The controller of claim 10, wherein the accelerometer is a three axis accelerometer that senses linear acceleration in each of three mutually perpendicular axes, and wherein the inertial sensor outputs three linear acceleration values corresponding to the three mutually perpendicular axes multiple times every second.

12. The controller of claim 11, wherein the wireless transceiver also transmits a set of the three acceleration values multiple times every second.

13. The controller of claim 1, wherein the inertial sensor comprises an accelerometer.

14. The controller of claim 13, wherein the accelerometer is a three axis accelerometer that senses linear acceleration in

## 14

each of three mutually perpendicular axes, and wherein the inertial sensor outputs three linear acceleration values corresponding to the three mutually perpendicular axes multiple times every second.

15. The controller of claim 14, wherein the wireless transceiver transmits a set of the three acceleration values multiple times every second.

[16. The controller of claim 1, wherein the output device comprises a speaker, and wherein the speaker outputs sounds based on a signal received by the wireless transceiver.]

17. The controller of claim 1, wherein the output device comprises a vibration module that causes the housing to vibrate based on a signal received by the wireless transceiver.

18. The controller of claim 1, wherein the output device comprises at least one indicator light that is selectively illuminated based on a signal received by the wireless transceiver.

19. The controller of claim 1, wherein the output device comprises an array of indicator lights that are selectively illuminated based on a signal received by the wireless transceiver.

20. The controller of claim 1, wherein the at least one digit operable detector comprises at least one depressible button disposed on the upper surface of the housing.

21. *A handheld electronic device, comprising:*

*a housing configured to be held by both hands of a user for providing input to a processor, wherein the housing includes a top surface, a bottom surface, and a further surface extending between the top surface and the bottom surface;*

*a touch-sensitive input panel arranged at a surface of the housing and configured to receive touch input; and a first input device and a second input device arranged at the top surface on a first side from the lateral center of the top surface, the first and second input devices being operable with a thumb of the user to provide directional inputs to the processor,*

*wherein one of the first input device or the second input device includes a directional switch input device and the other includes an inclinable stick input device, and wherein the top surface comprises a proximal portion closer to the body of the user when the user holds the housing in two hands, the first input device is arranged between the second input device and the proximal portion.*

22. *The handheld electronic device according to claim 21, further comprising a third input device arranged at the top surface on a second side that is opposite the first side from the lateral center of the top surface.*

23. *The handheld electronic device according to claim 22, wherein the third input device includes at least four control buttons in a cross-shaped arrangement.*

24. *The handheld electronic device according to claim 22, wherein the third input device includes an inclinable stick input device.*

25. *The handheld electronic device according to claim 24, wherein the first input device includes a directional switch input device, and wherein the first input device and the third input device are positioned symmetrically on opposite sides of the lateral center of the top surface.*

26. *The handheld electronic device according to claim 22, further comprising a fourth input device arranged at the left side of the further surface and a fifth input device arranged at the right side of the further surface, wherein the fourth input device is operable with a finger of the user's left hand and the fifth input device is operable with a finger of the user's right*

15

hand when the user holds the housing with both hands to provide input to the processor.

27. The handheld electronic device according to claim 22, further comprising at least one fourth input device on a surface of the housing other than the top surface, the at least one fourth input device configured to generate an analog signal based upon a level of user input.

28. The handheld electronic device according to claim 27, wherein the at least one fourth input device is further configured to vary the analog signal based upon how much pressure is exerted on the at least one fourth input device by a finger of the user.

29. The handheld electronic device according to claim 22, further comprising a fourth input device arranged at a lateral center of the top surface, the fourth input device being a button switch.

30. The handheld electronic device according to claim 29, wherein the button switch is recessed in relation to the top surface.

31. The handheld electronic device according to claim 30, wherein the fourth input device is configured to generate an input signal to cause a MENU or HOME operation.

32. The handheld electronic device according to claim 22, wherein a recessed button switch is arranged at a lateral center of the top surface, and wherein one of the first input device or the second input device and a second inclinable stick input device are arranged symmetrically on opposite sides of the lateral center of the top surface.

33. The handheld electronic device according to claim 21, further comprising at least one wireless antenna, wherein the handheld electronic device is configured to communicate with a console device using a wireless protocol over the wireless antenna.

34. The handheld electronic device according to claim 33, wherein the wireless protocol is based upon the Bluetooth protocol standard.

35. The handheld electronic device according to claim 21, further comprising a vibration generator configured to vibrate the housing in response to a signal received via a wireless communication interface.

36. The handheld electronic device according to claim 21, further comprising at least one image sensor.

37. The handheld electronic device according to claim 36, further comprising a focusing lens associated with the image sensor.

38. The handheld electronic device according to claim 21, further comprising at least one inertial sensor.

39. A handheld electronic device, comprising:

a housing configured to be held by both hands of a user for providing input to a processor, wherein the housing includes a top surface, a bottom surface, and a further surface extending between the top surface and the bottom surface;

a touch-sensitive input panel arranged at a surface of the housing and configured to receive touch input; and a first input device and a second input device arranged at the top surface on a first side from the lateral center of the top surface, the first and second input devices being operable with a thumb of the user to provide directional inputs to the processor;

the handheld electronic device further comprising at least one light indication devices arranged on the housing and configured to indicate an identification of the handheld electronic device, wherein the identification uniquely identifies the handheld electronic device among a plurality of controllers communicating with a particular console device.

16

40. A handheld electronic device, comprising:

a housing configured to be held by both hands of a user for providing input to a processor, wherein the housing includes a top surface, a bottom surface, and a further surface extending between the top surface and the bottom surface;

a touch-sensitive input panel arranged at a surface of the housing and configured to receive touch input; and

a first input device and a second input device arranged at the top surface on a first side from the lateral center of the top surface, the first and second input devices being operable with a thumb of the user to provide directional inputs to the processor;

the handheld electronic device further comprising additional input devices arranged at locations of the top surface, wherein the additional input devices are configured, respectively, to cause a start operation, to cause a select operation, and to cause processing to return to a predetermined configuration.

41. A handheld electronic device, comprising:

a housing configured to be held by both hands of a user for providing input to a processor, wherein the housing includes a top surface, a bottom surface, and a further surface extending between the top surface and the bottom surface;

a touch-sensitive input panel arranged at a surface of the housing and configured to receive touch input; and

a first input device and a second input device arranged at the top surface on a first side from the lateral center of the top surface, the first and second input devices being operable with a thumb of the user to provide directional inputs to the processor;

wherein the touch-sensitive input panel includes a touch screen, and wherein

the handheld electronic device further comprises another touch-sensitive input panel.

42. A handheld electronic device, comprising:

a housing configured to be held by both hands of a user for providing input to a processor, wherein the housing includes a top surface, a bottom surface, and a further surface extending between the top surface and the bottom surface;

a touch-sensitive input panel arranged at a surface of the housing and configured to receive touch input; and

a first input device and a second input device arranged at the top surface on a first side from the lateral center of the top surface, the first and second input devices being operable with a thumb of the user to provide directional inputs to the processor;

wherein one of the first input device or the second input device includes a directional switch input device and the other includes an analog directional input device, and wherein the top surface comprises a proximal portion closer to the body of the user when the user holds the housing in two hands, the first input device is arranged between the second input device and the proximal portion.

43. A handheld electronic device, comprising:

a housing configured to be held by both hands of a user for providing input to a processor, wherein the housing includes a top surface, a bottom surface, and a further surface extending between the top surface and the bottom surface;

a touch-sensitive input panel arranged at a surface of the housing and configured to receive touch input; and

a first input device and a second input device arranged at the top surface on a first side from the lateral center of

*the top surface, the first and second input devices being operable with a thumb of the user to provide directional inputs to the processor,*  
*wherein one of the first input device or the second input device includes a directional switch input device and the* 5  
*other includes an analog directional input device, and*  
*wherein the first input device is disposed at a first position on the housing top surface and the second input device is*  
*disposed next to the first input device at a second position on the housing top surface, the second position* 10  
*being closer to the body of the user than the first position*  
*when the housing is held by both hands of the user.*

\* \* \* \* \*