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(54) **APPARATUS AND METHOD FOR ROTATING THE DISPLAY ORIENTATION OF A CAPTURED IMAGE**

(75) Inventor: **Eric C. Anderson**, Gardnerville, NV (US)

(73) Assignee: **Apple Inc.**, Cupertino, CA (US)

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Appl. No.: **08/588,210**
Filed: **Jan. 19, 1996**

U.S. Applications:

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(51) **Int. Cl.**

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H04N 9/83 (2006.01)
H04N 5/235 (2006.01)
G09G 5/00 (2006.01)
G06K 9/32 (2006.01)

(52) **U.S. Cl.** **348/272**; 348/208.2; 348/208.3; 348/222.1; 345/656; 382/296

(58) **Field of Classification Search** 702/151, 702/154; 348/208.2, 208.3, 272, 222.1; 345/656; 382/296

See application file for complete search history.

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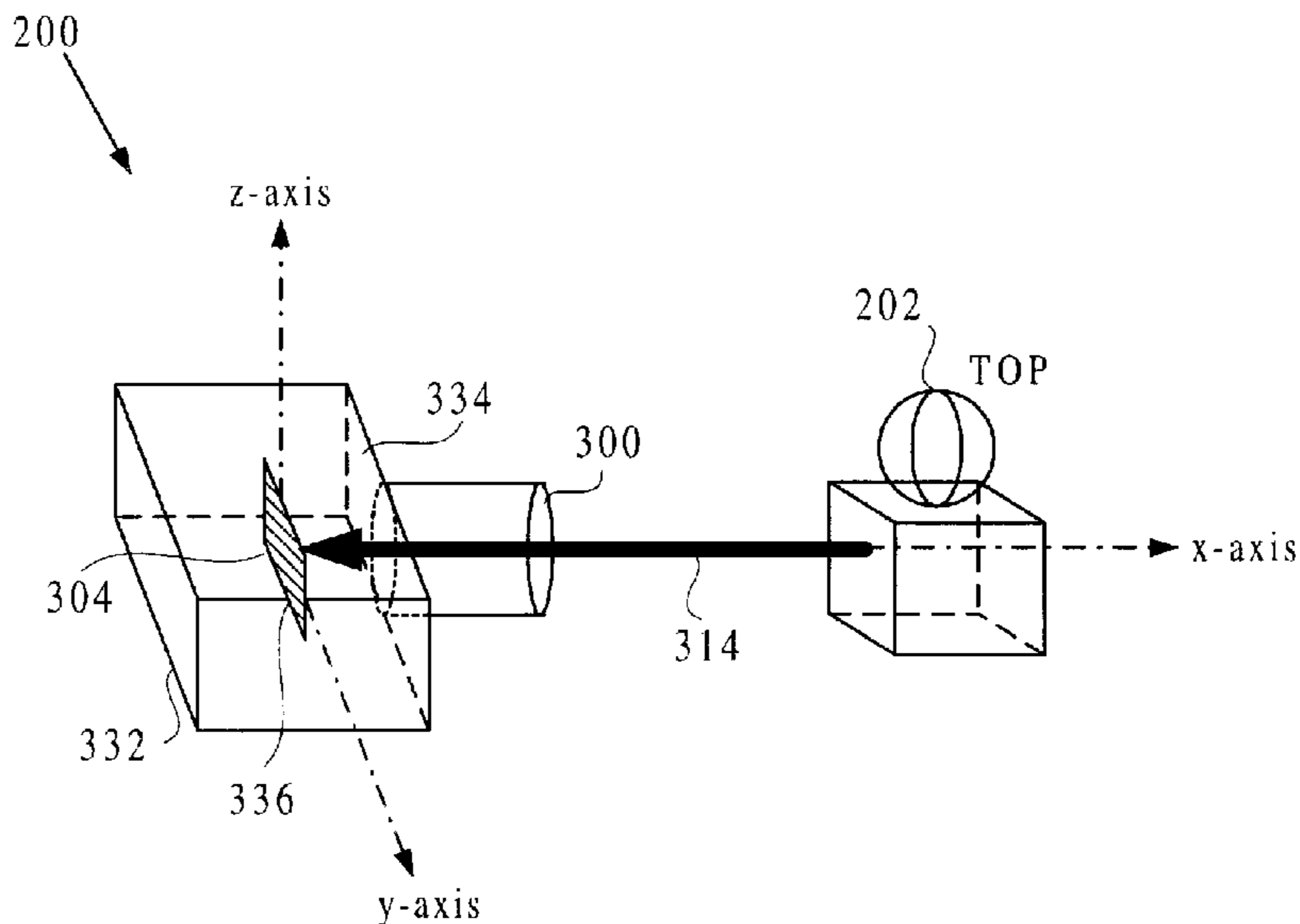
Primary Examiner — Jason Whipkey

(74) *Attorney, Agent, or Firm* — Fenwick & West LLP

(57) **ABSTRACT**

The apparatus of the present invention preferably comprises an image sensor, an orientation sensor, a memory and a processing unit. The image sensor is used for generating captured image data. The orientation sensor is coupled to the image sensor, and is used for generating signals relating to the position of the image sensor. The memory, has an auto-rotate unit comprising program instructions for transforming the captured image data into rotated image data in response to the orientation sensor signals. The processing unit, executes program instructions stored in the memory, and is coupled to the image sensor, the orientation sensor and the memory. The method of the present invention preferably comprises the steps of: generating image data representative of an object with an image sensor; identifying an orientation of the image sensor relative to the object during the generating step; and selectively transferring the image data to an image processing unit in response to the identifying step.

2 Claims, 17 Drawing Sheets



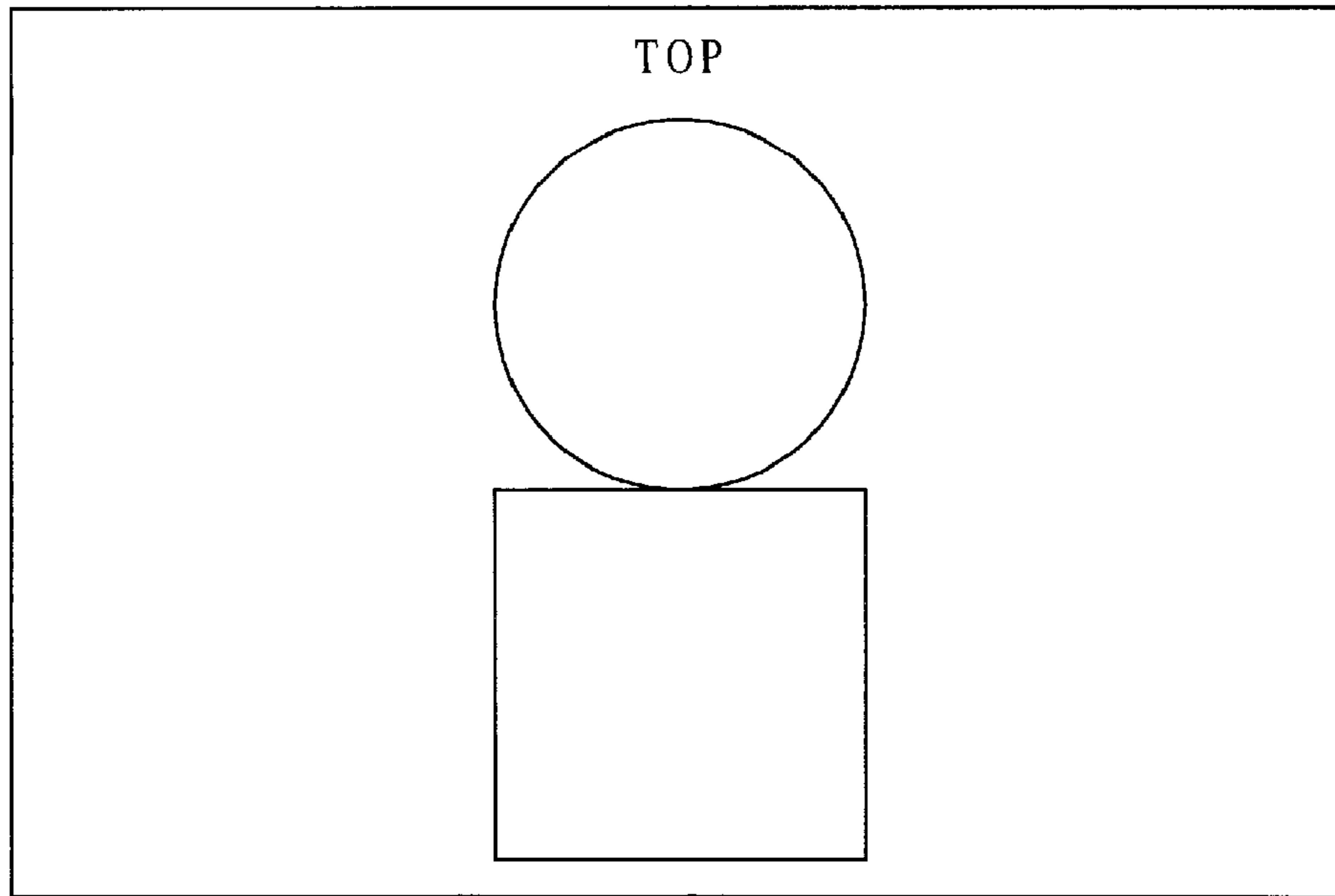


Fig. 1A (Prior Art)

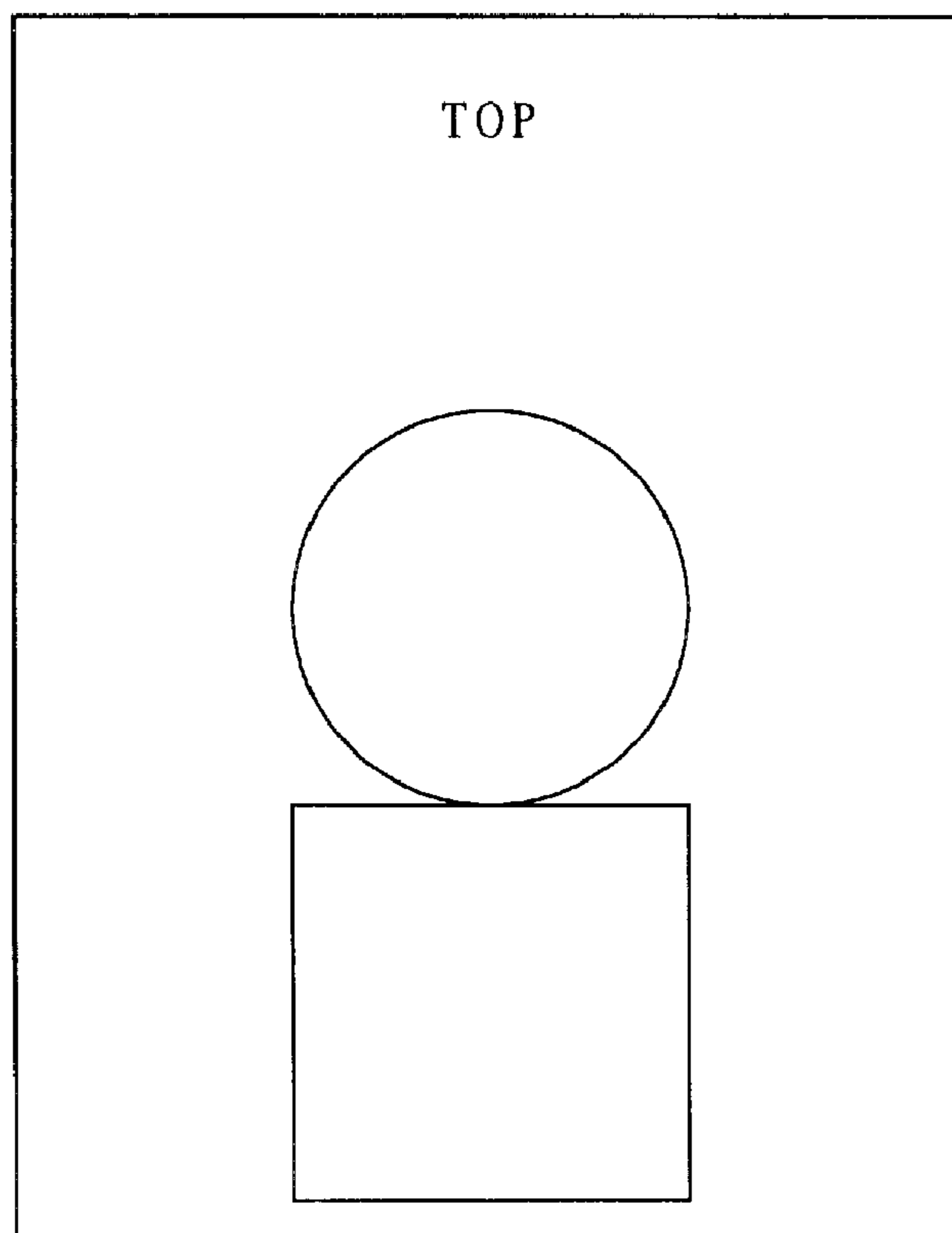


Fig. 1B (Prior Art)

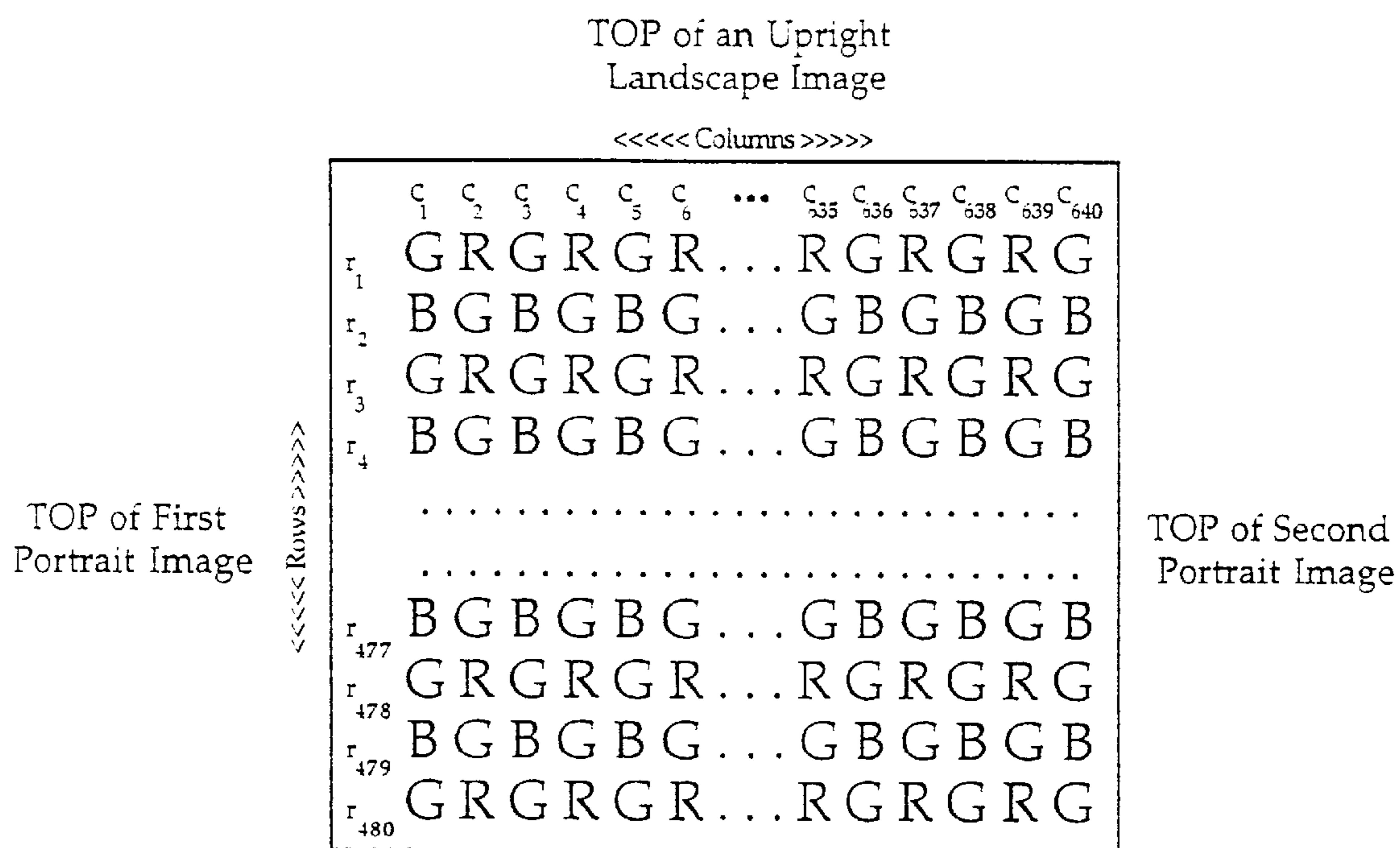


Fig. 1C (Prior Art)

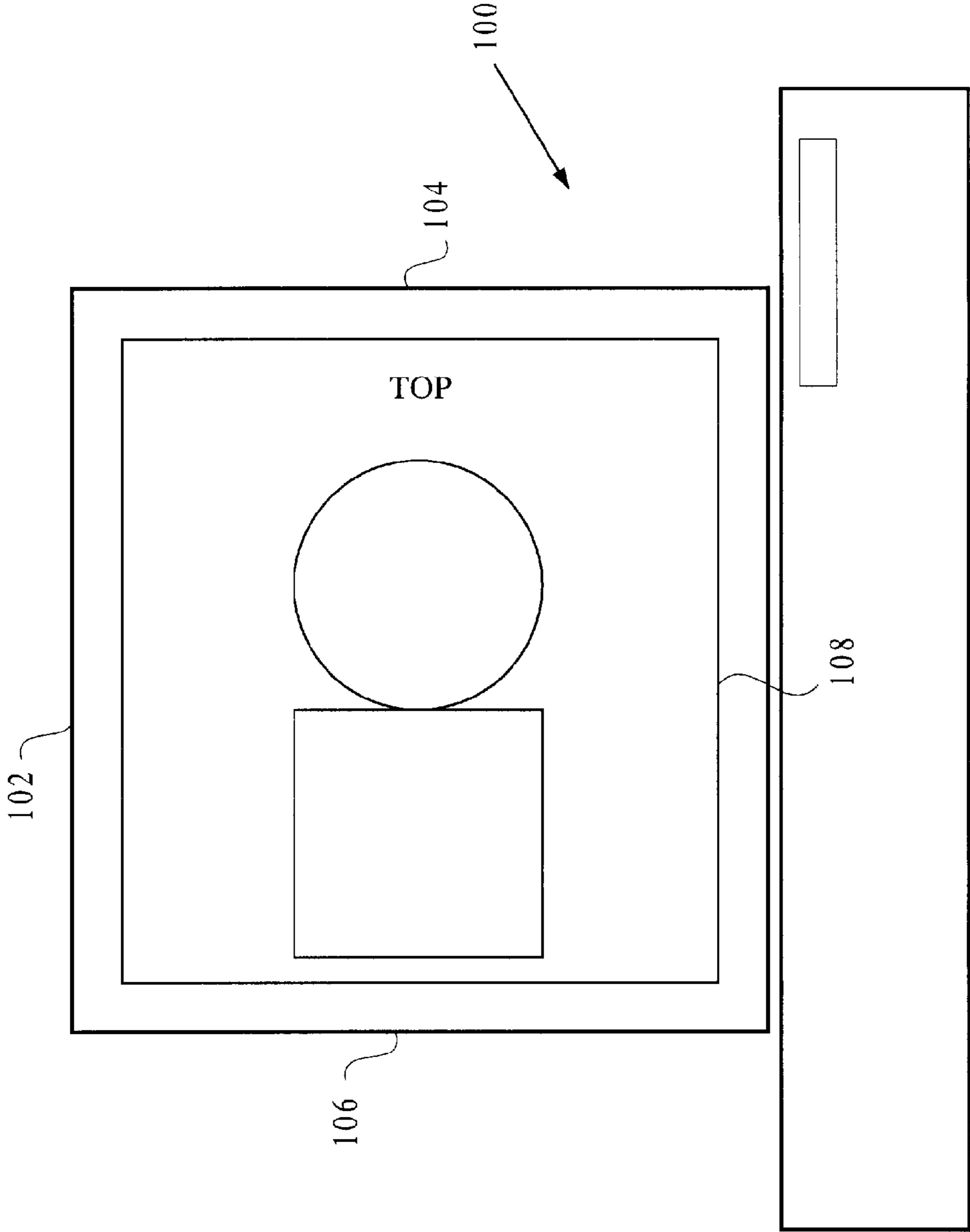


Fig. 1D (Prior Art)

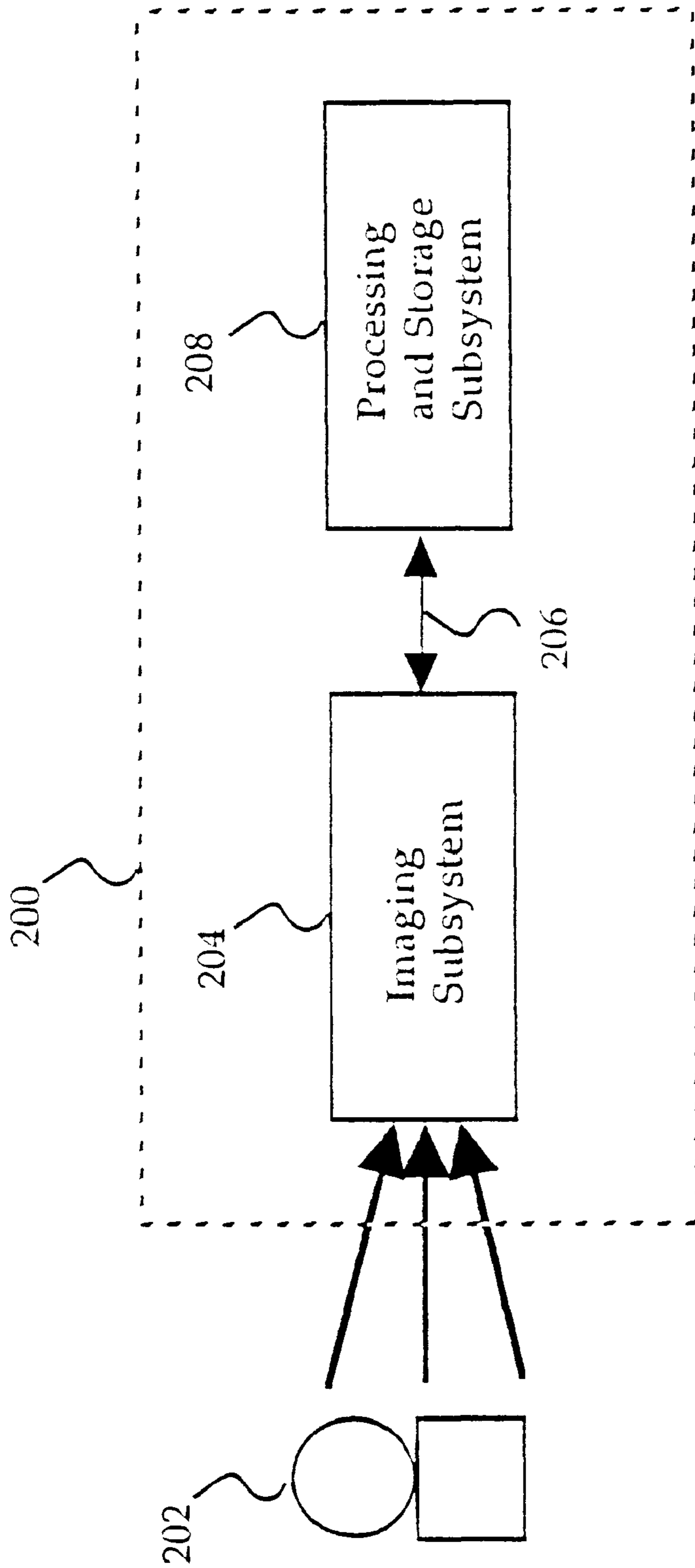


Fig. 2

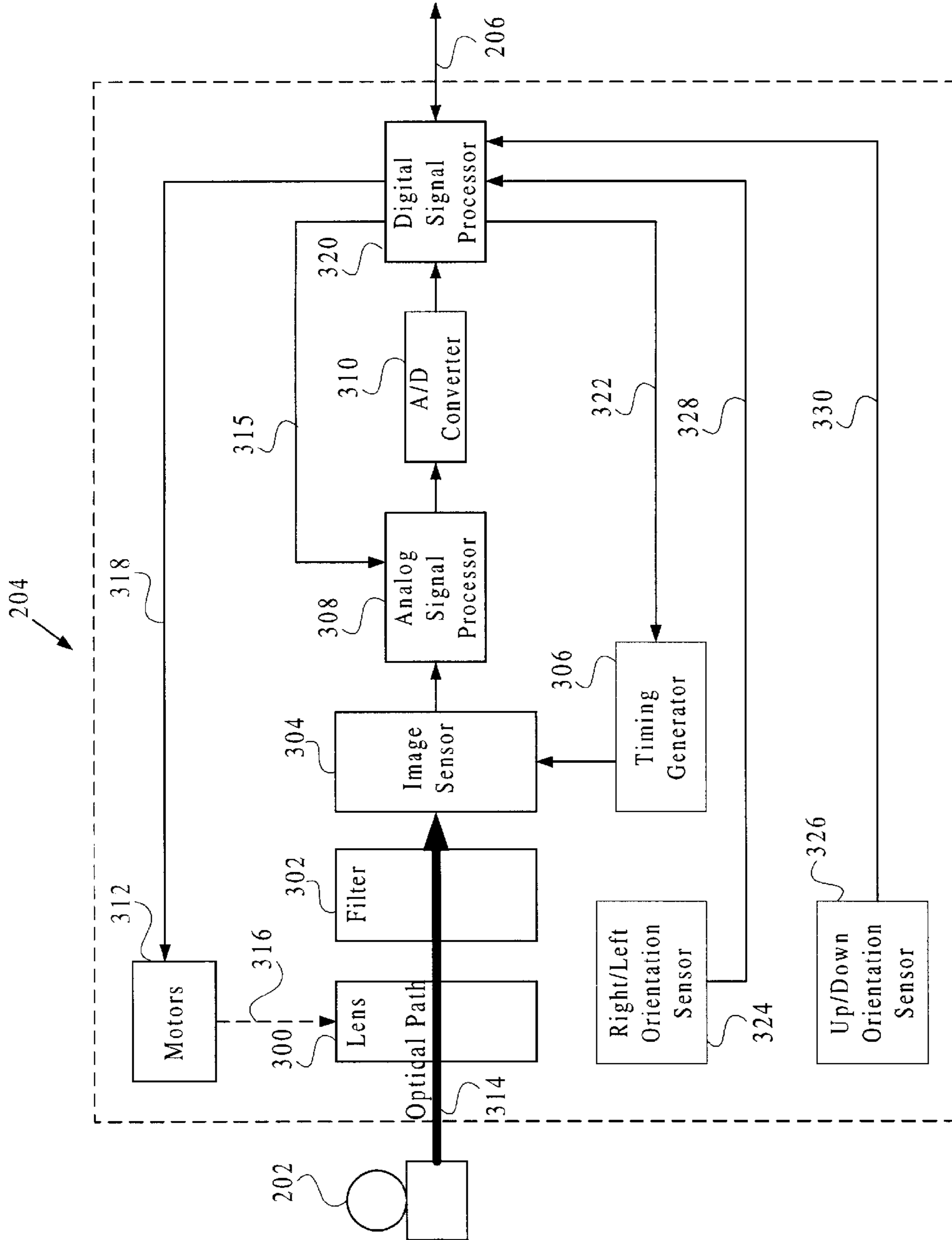


Fig. 3A

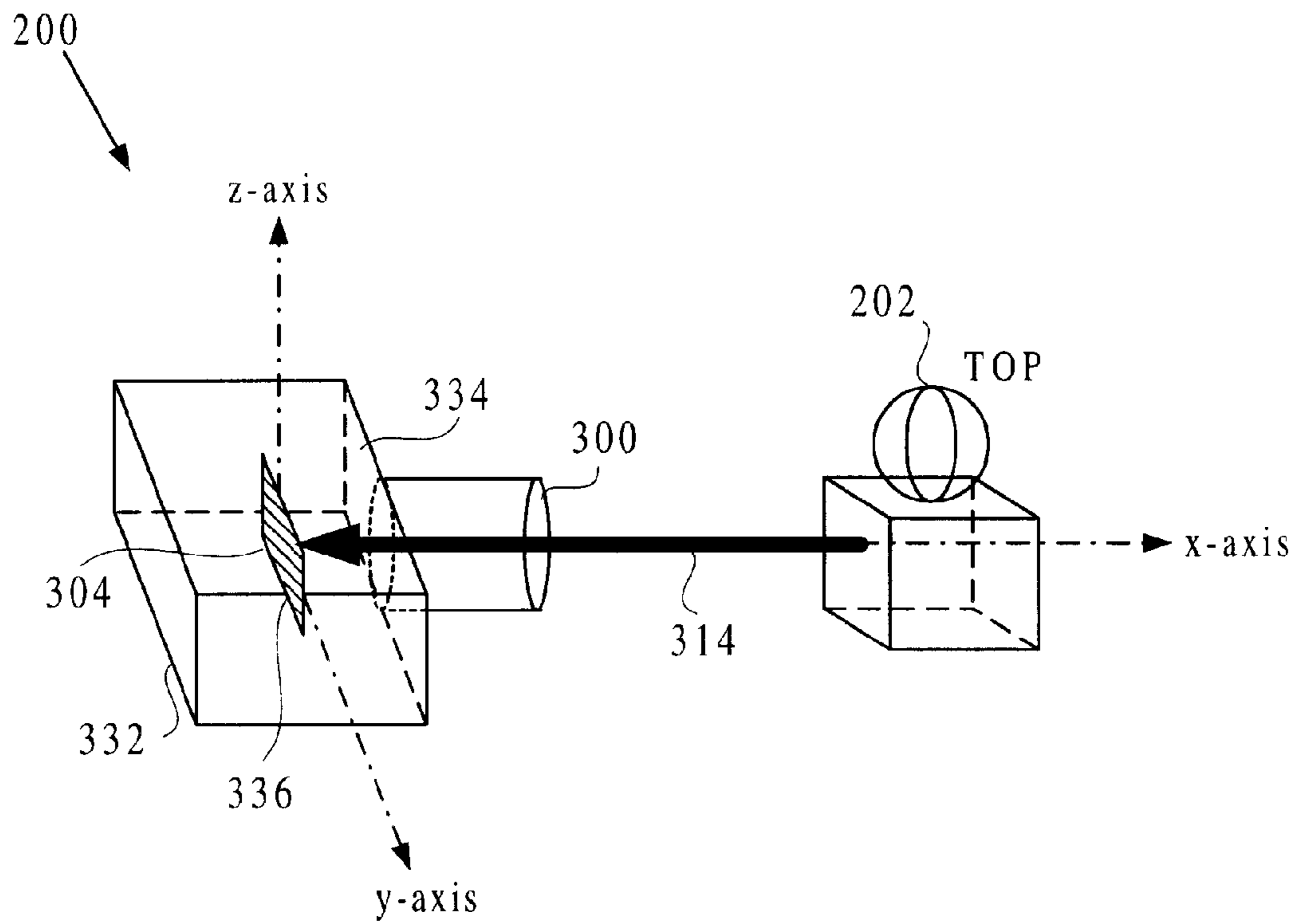


Fig. 3B

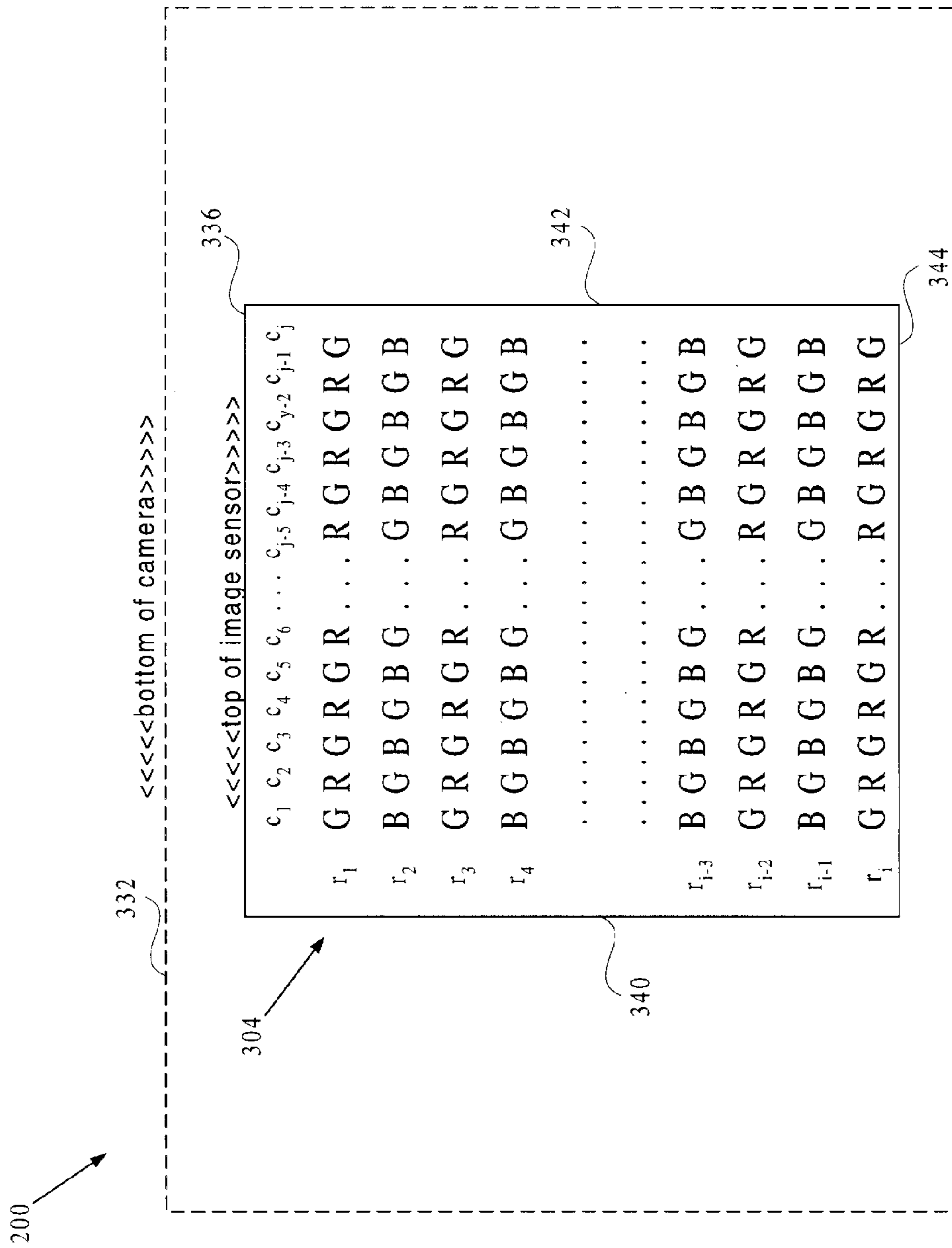


Fig. 3C

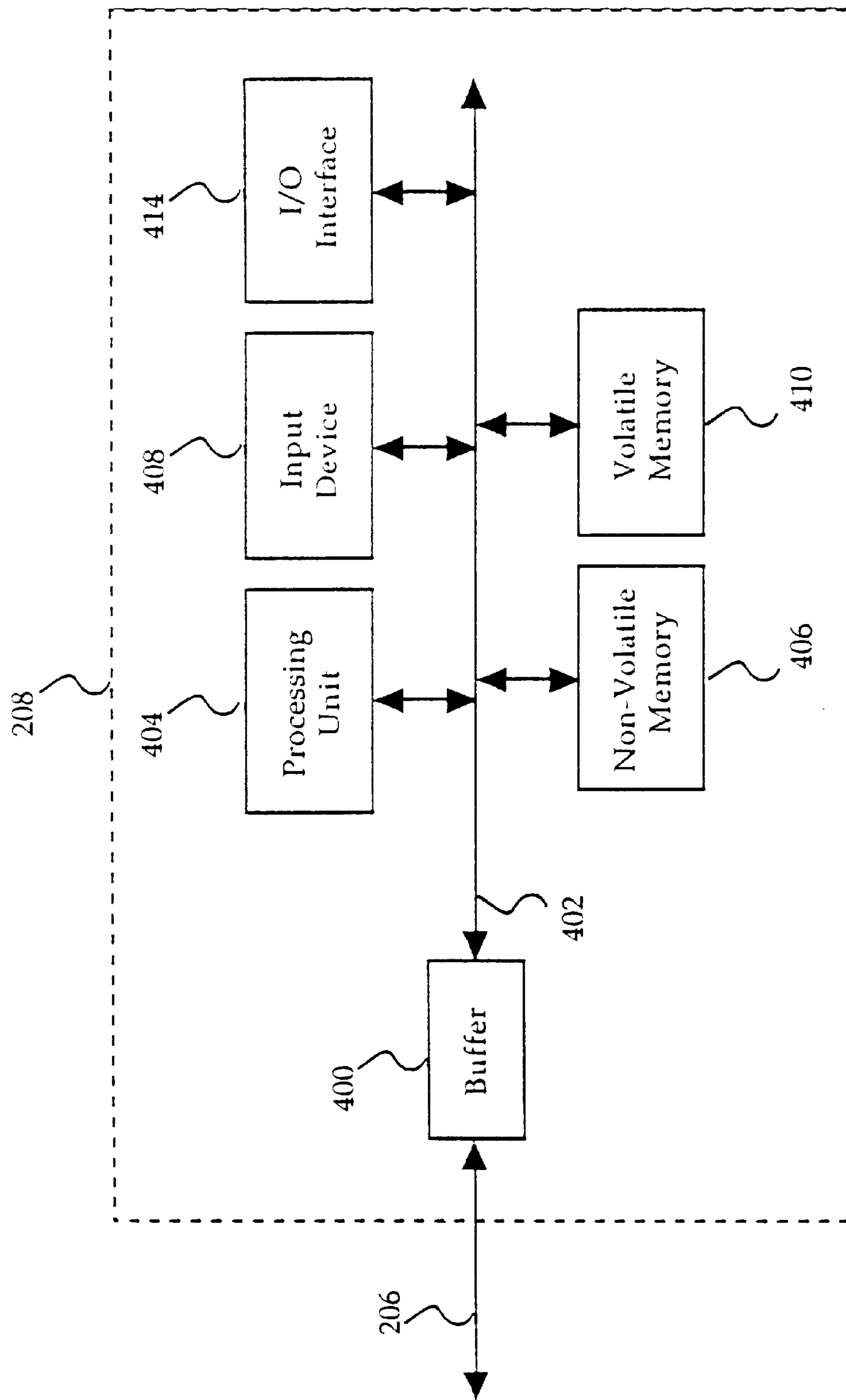


Fig. 4A

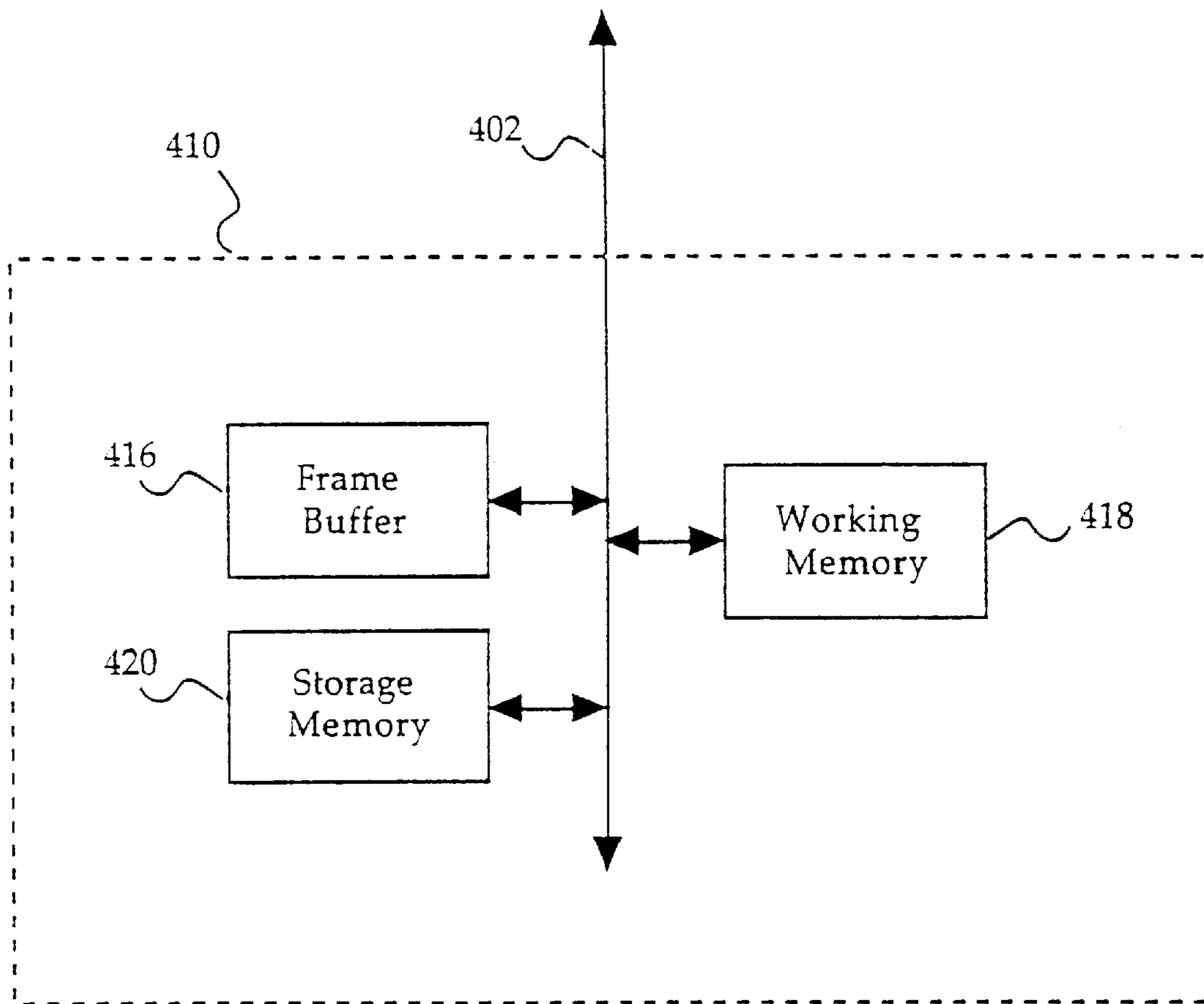


Fig. 4B

417
↓

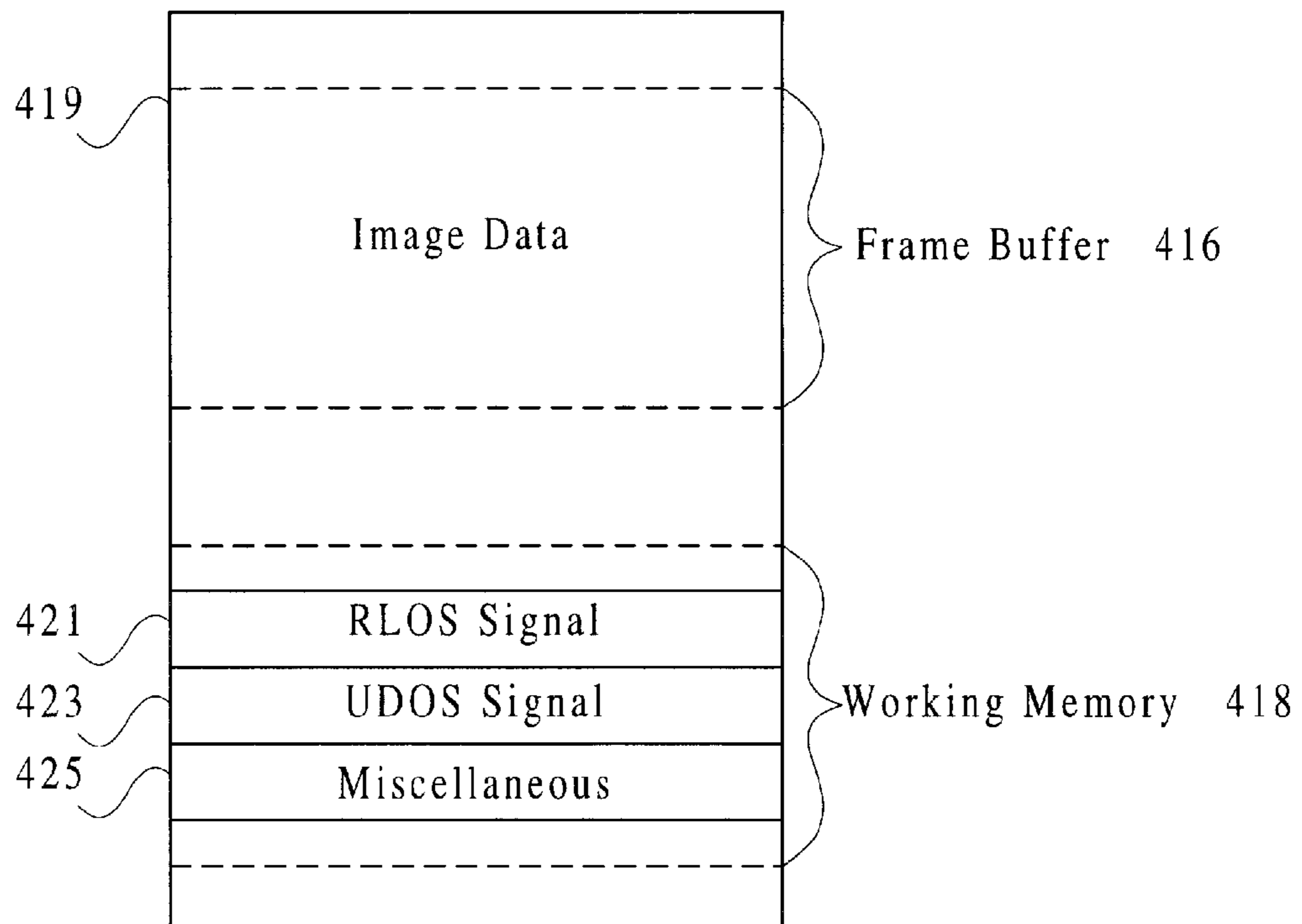


Fig. 4C

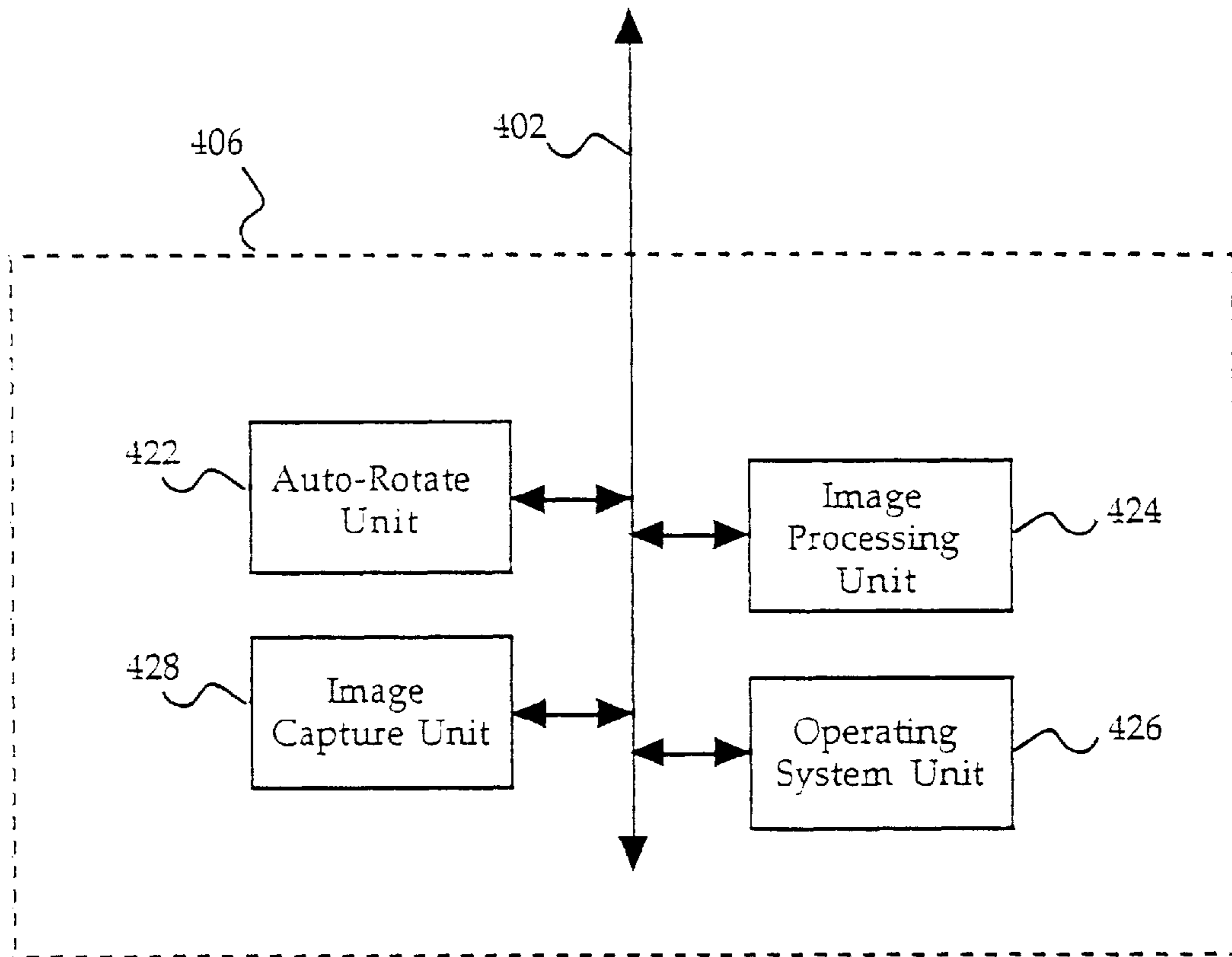


Fig. 4D

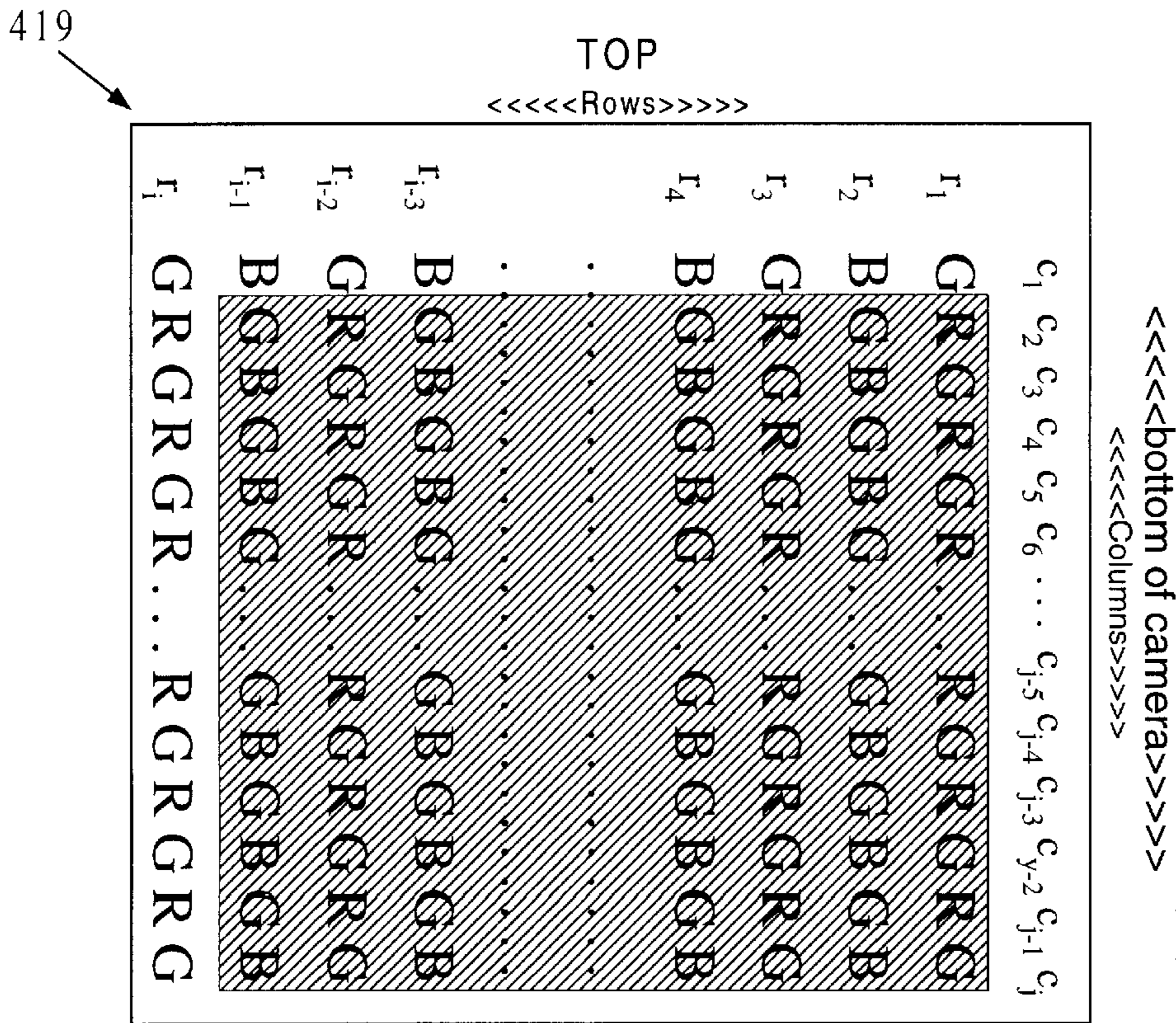


Fig. 5A

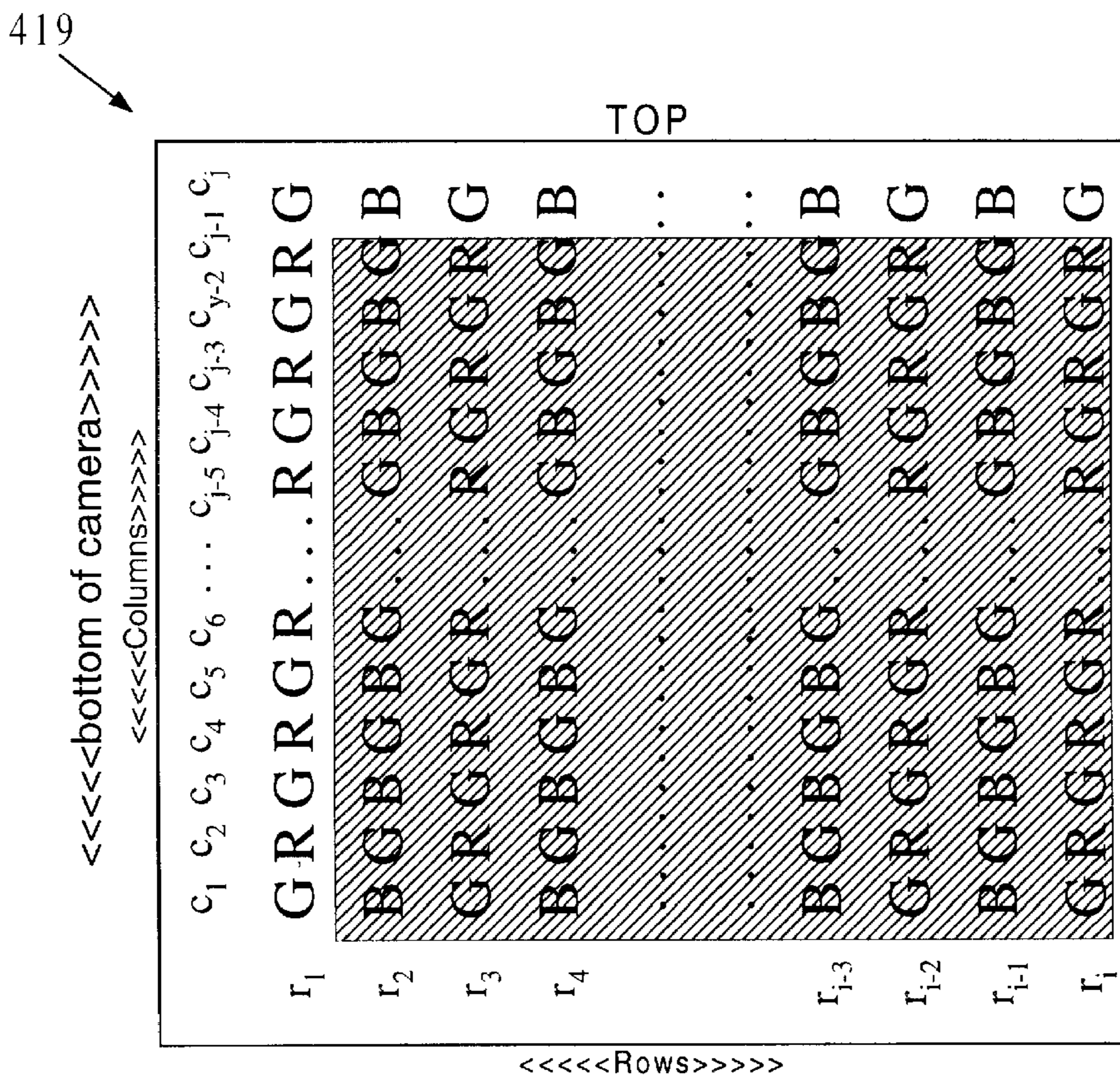


Fig. 5B

419
↘

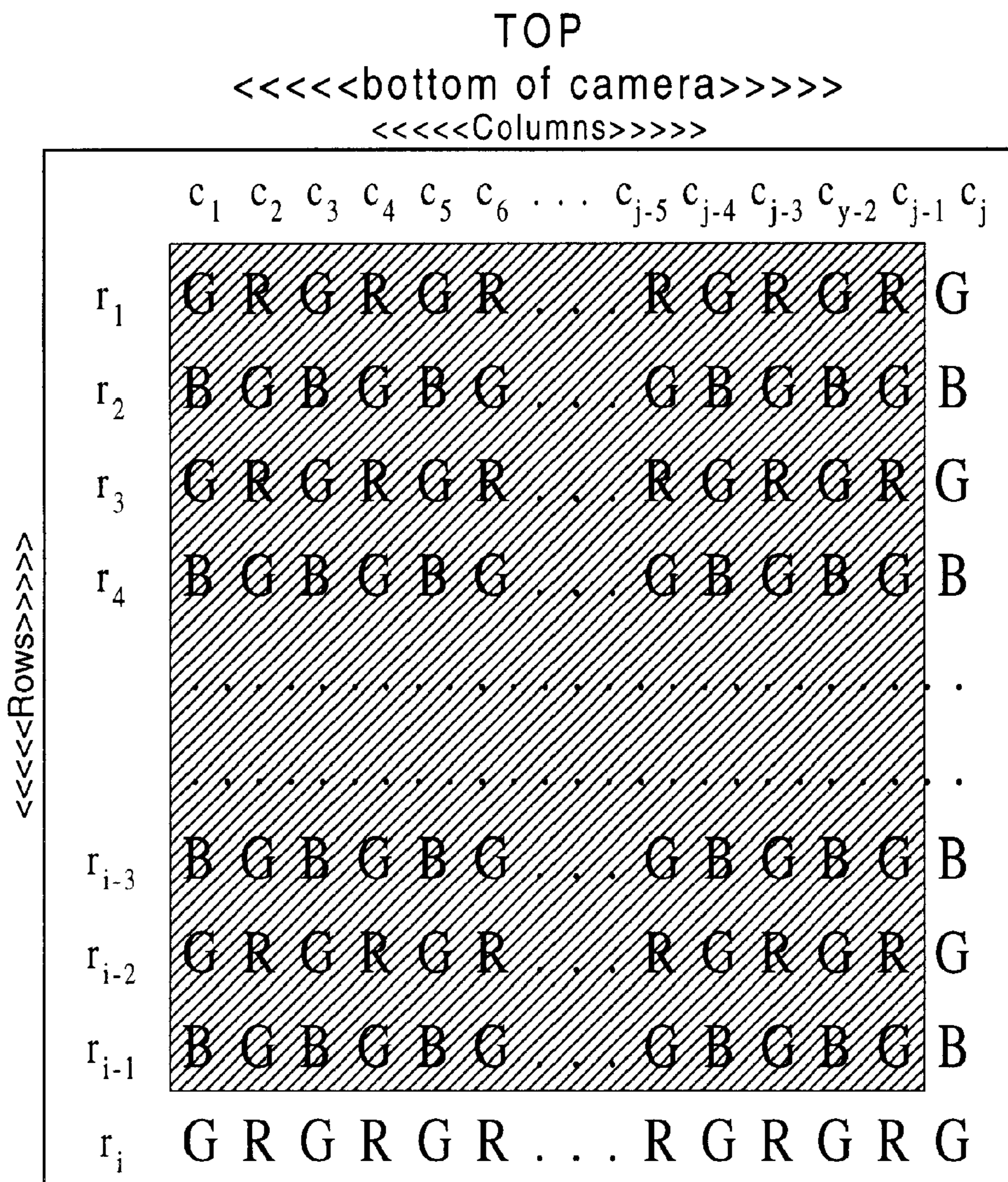


Fig. 5C

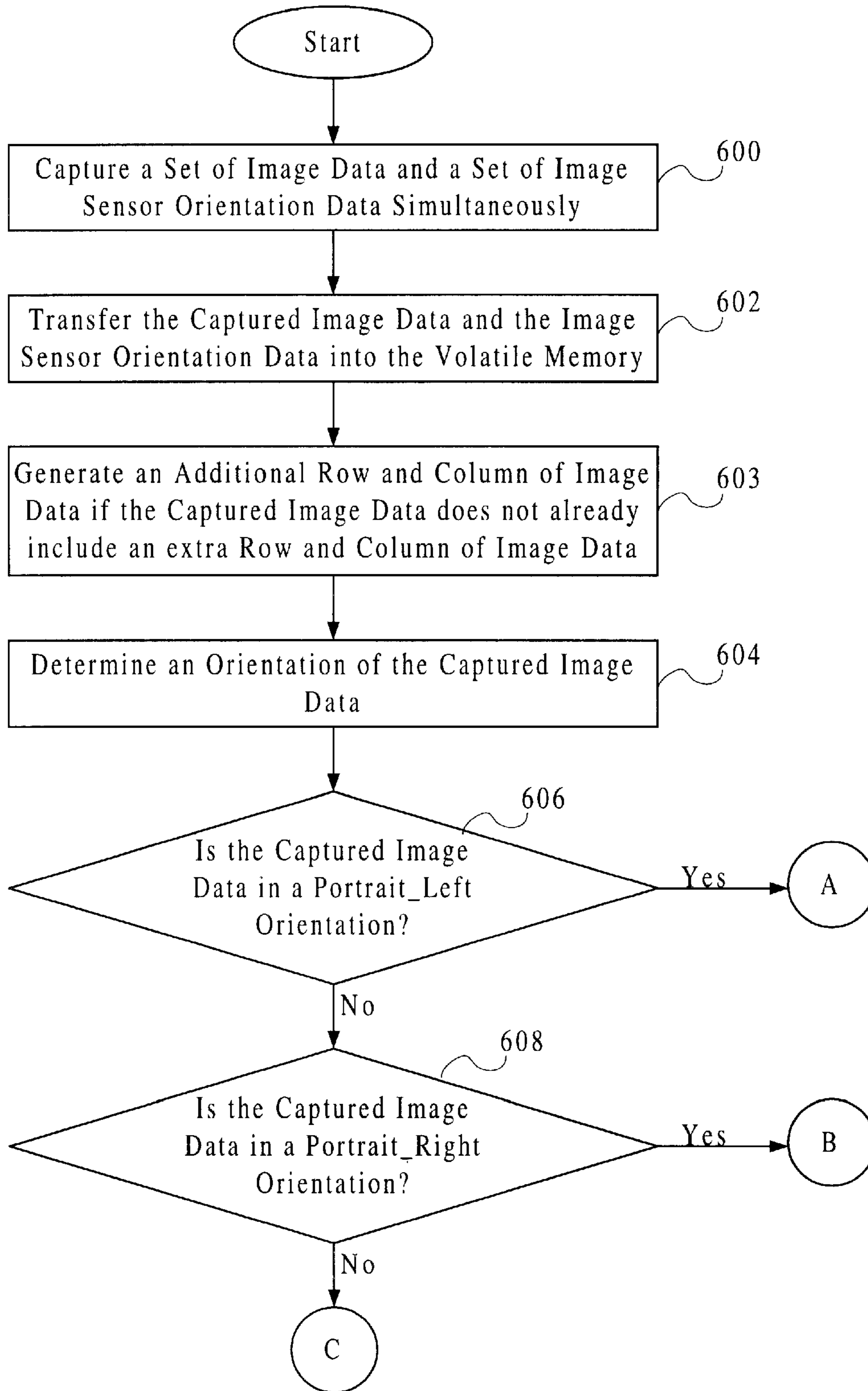


Fig. 6A

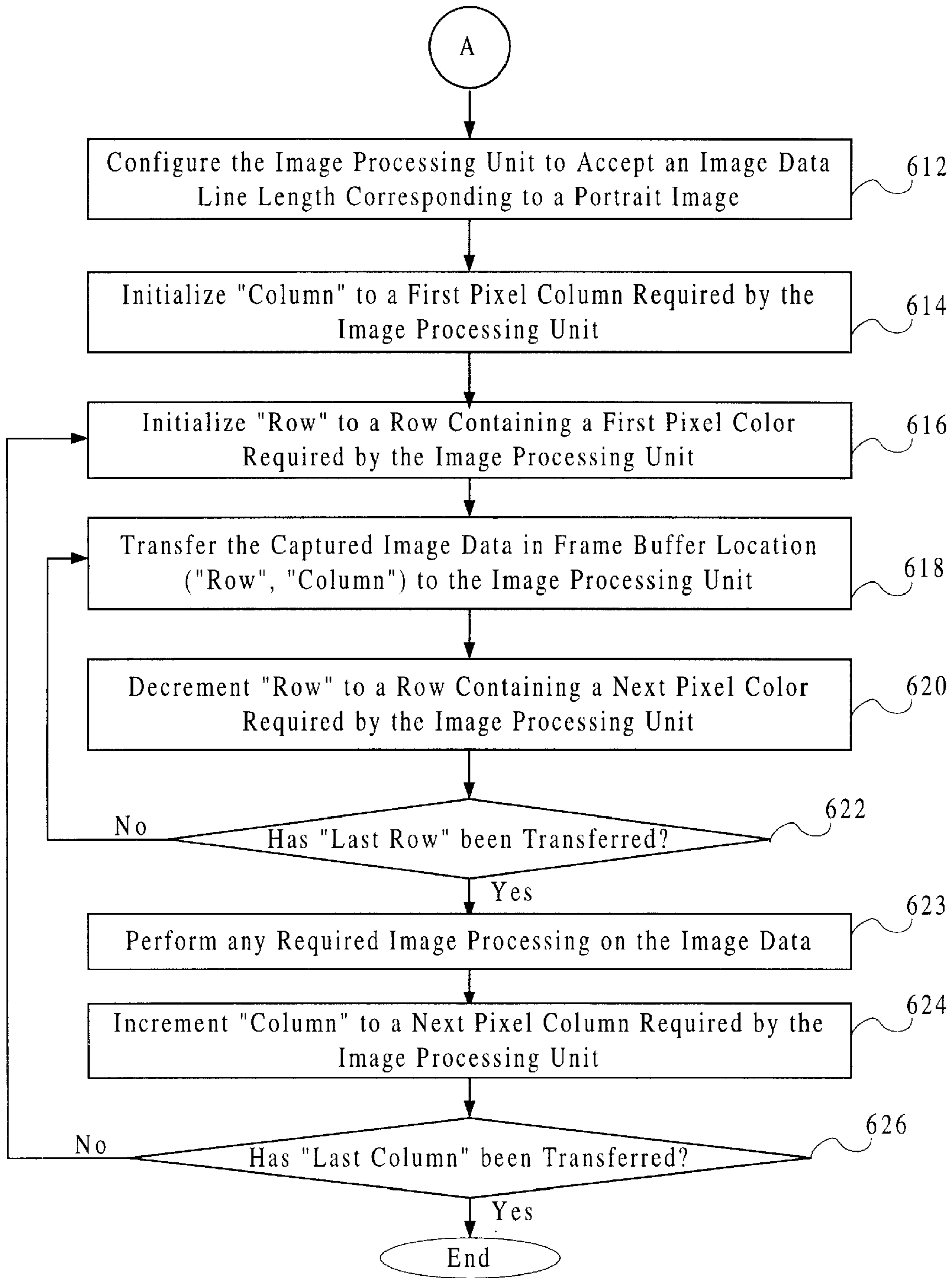


Fig. 6B

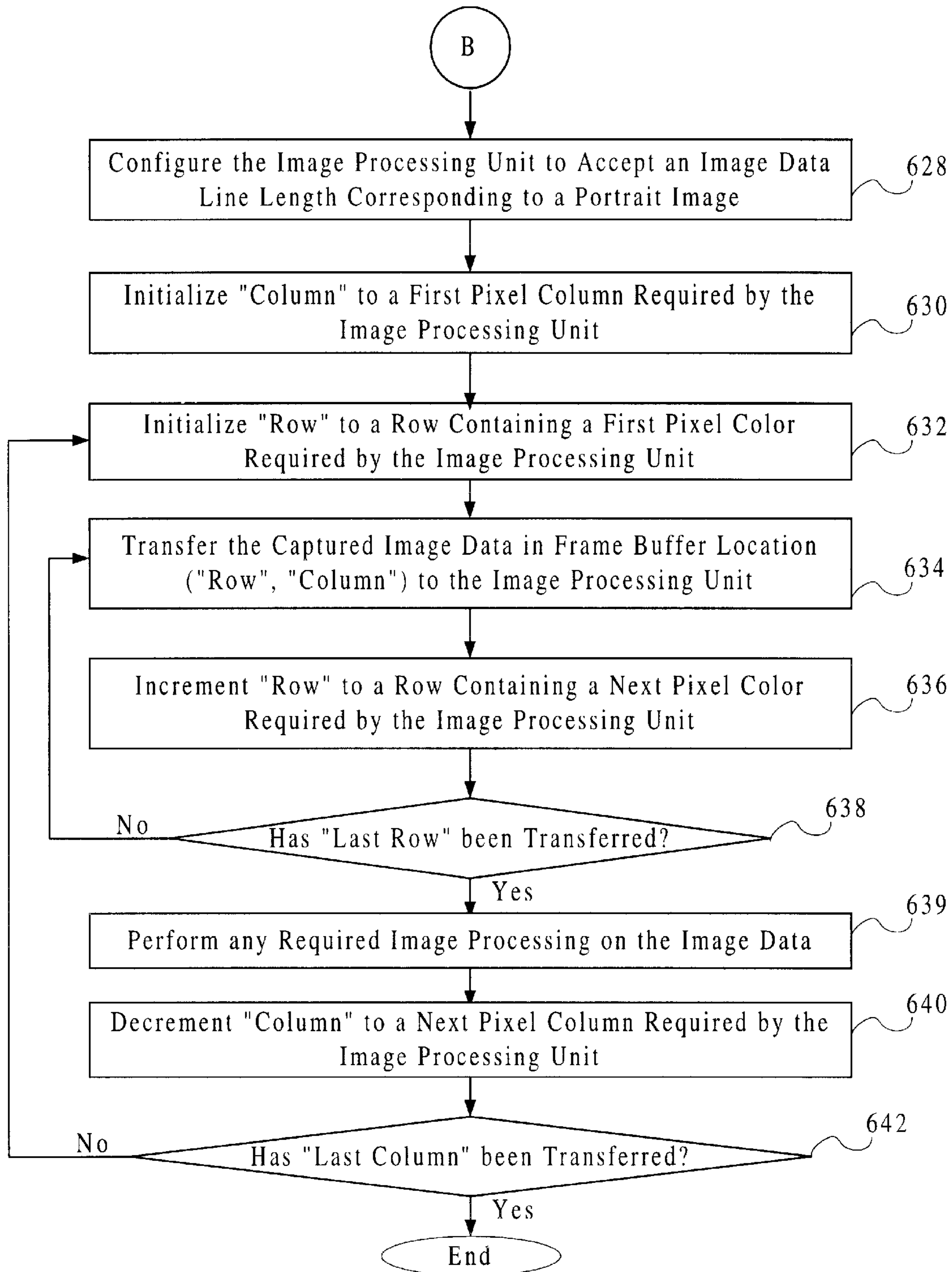


Fig. 6C

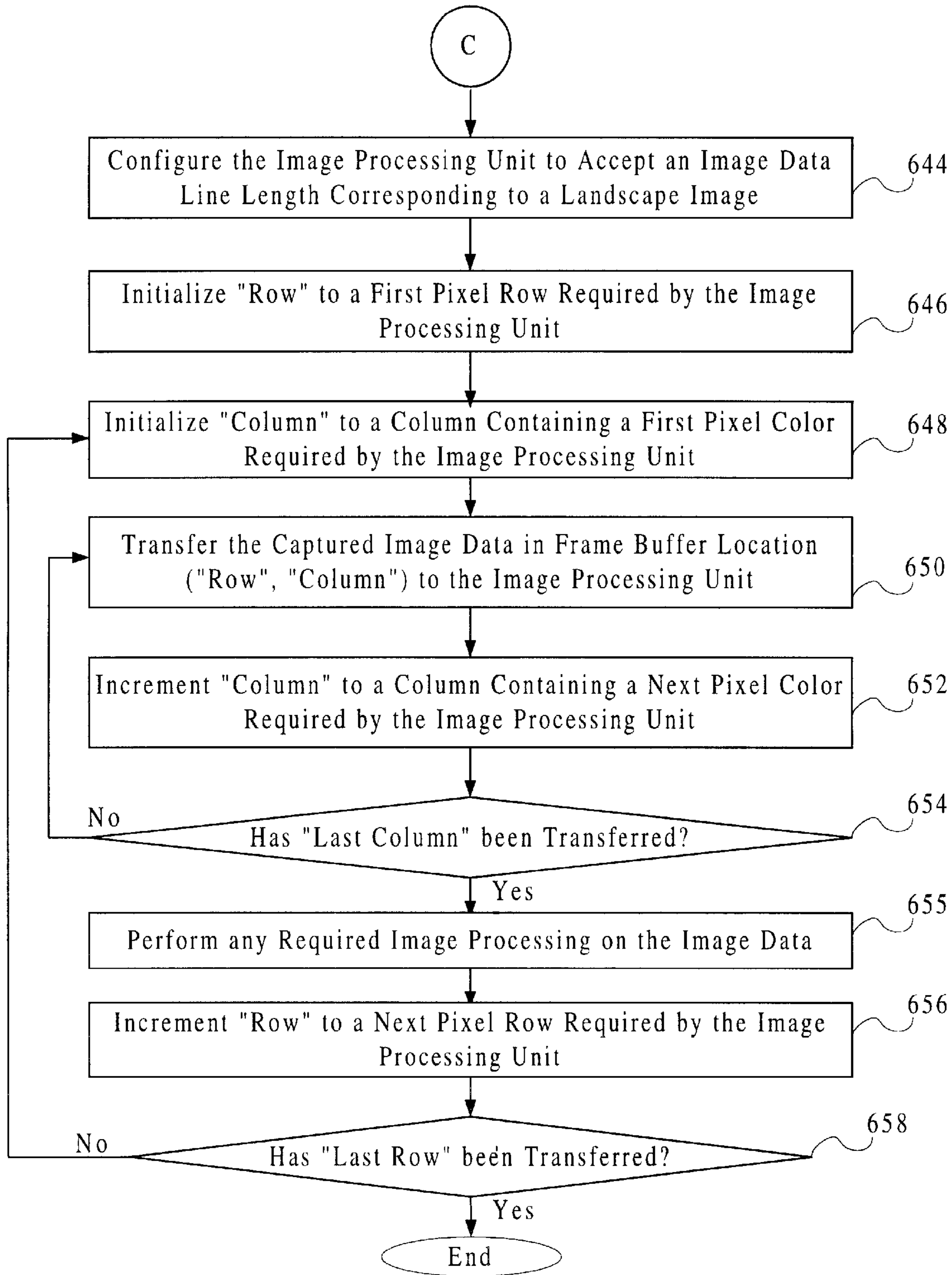


Fig. 6D

**APPARATUS AND METHOD FOR ROTATING
THE DISPLAY ORIENTATION OF A
CAPTURED IMAGE**

Matter enclosed in heavy brackets [] appears in the original patent but forms no part of this reissue specification; matter printed in italics indicates the additions made by reissue.

Notice: More than one reissue application has been filed for the reissue of U.S. Pat. No. 6,011,585. This reissue application is a continuation of U.S. Pat. No. RE41,088 (application Ser. No. 11/206,279), which is a reissue of U.S. Pat. No. RE38,896 (application Ser. No. 10/040,249).

This application relates to co-pending U.S. patent application Ser. No. 08/355,031, entitled A System and Method For Generating a Contrast Overlay as a Focus Assist for An Imaging Device, filed on Dec. 13, 1994, by inventor Eric C. Anderson; and U.S. patent application Ser. No. 08/384,012, entitled Apparatus and Method for Camera Image and Orientation Capture, filed on Feb. 6, 1995, by inventor Scott Fullam. The subject matter of the two applications described above is hereby incorporated by reference. These related applications are commonly assigned to Apple Computer, Inc.

BACKGROUND OF THE INVENTION

1. Field of the Invention

The present invention relates generally to an apparatus and method for orienting an image. More particularly, the present invention is an apparatus and method for rotating a captured image to an orientation corresponding to an imaging subsystem's orientation at the time in which the image was captured.

2. Description of the Background Art

When a digital camera captures an image of an object, the camera's frame of reference with respect to the object produces a desired image orientation. Two conventional image orientations exist, namely, a landscape orientation and a portrait orientation. Referring now to FIG. 1A, a prior art graphical representation of an object in a landscape orientation is shown, in which the image's width is greater than its height. Referring also now to FIG. 1B, a prior art graphical representation of the object in a portrait orientation is shown, in which the image's height is greater than its width.

In a digital camera, an image sensor is comprised of light-sensitive devices, such as charge-coupled devices (CCD), that convert an optical image into a set of electrical signals. Referring now to FIG. 1C, a prior art image sensor is shown having a 480 row by 640 column matrix of light collecting pixels. The image sensor is orientated within a body of the digital camera so that a first row of pixels (i.e. row r_1) corresponds to the bottom of an upright and level digital camera. This image sensor orientation is required since as an optical image passes through a conventional camera lens it is inverted. The image sensor in a color digital camera typically consists of an array of green (G), red (R) and blue (B) pixels. Alternative embodiments include sensors detecting cyan, magenta, yellow and green as is typically used in video cameras. Other image sensor configurations are also used. The pixels that comprise the image sensor are arranged into various patterns or formats. A common image sensor format is called a Bayer pattern. The Bayer pattern format is defined as a pixel pattern comprised of 50% green-light responsive pixels, 25% red-light responsive pixels and 25% blue-light responsive pixels

arranged in alternating rows of "GRGRGR" and "BGBGBG," as shown in FIG. 1C. Throughout this specification, "G" means "green," "R" means "red," and "B" means "blue."

Once an image is captured by the digital camera, a set of pixel signals corresponding to the image received by the pixels is processed by an image processing algorithm. Image processing routines are conventionally designed to process pixel signals line-by-line, conforming to a specific and unchanging pixel pattern format. Thus, image sensors manufactured with the Bayer pixel pattern format will be coupled to image processing routines specifically designed to accept pixel signals in alternating sequences of "GRGRGR" and "BGBGBG." Due to possible imperfections in the outer rows and columns of pixels that make up the image sensor, conventional digital cameras sometimes have image sensors large enough so that one or more lines of pixels at the sides of the image sensor can be ignored.

Referring now to FIG. 1D, a prior art graphical representation is shown of the object as captured in the portrait orientation and output upon an image display 100. The image display 100 is typically a conventional stand-alone, personal computer CRT having a top 102, a right side 104, a left side 106 and a bottom 108.

As previously described, the image processing routines within digital cameras are conventionally designed to process pixel signals on a line-by-line basis according to only one pixel pattern format. Thus, conventional digital cameras process images as if they were always in a landscape format. In the presentation of the landscape image of FIG. 1A upon the image display, the "TOP" (i.e. "top portion") of the landscape image would correspond to the top 102 of the FIG. 1D image display 100. Such an orientation for landscape images on the image display 100 is quite natural and is acceptable for ease of viewing the image. However, the presentation of the portrait image of FIG. 1B upon the image display results in the "TOP" of the portrait image corresponding to either the right side 104 or the left side 106 of the image display 100, depending on how the user had rotated the digital camera. FIG. 1D explicitly shows the case where the "TOP" of the portrait image corresponds to the right side 104 of the image display 100. This "sideways" orientation for portrait images on the image display 100 is unacceptable and unnatural. This undesirable by-product of conventional digital cameras requires that the user rotate portrait images so that they are presented in a more natural and upright viewing angle on the image display 100. It should be noted that this problem also exists for digitized images from conventional film cameras. Traditional rotation methods also have the disadvantage of requiring two blocks of memory to rotate a stored image.

What is needed is an apparatus and method that efficiently and automatically rotates a stored photographic image to correspond to the orientation in which the photographic image was captured.

SUMMARY OF THE INVENTION

The present invention is an apparatus and method for rotating the display orientation of a captured image. The apparatus of the present invention preferably comprises an image sensor, an orientation sensor, a memory and a processing unit. The image sensor is used for capturing image data. The orientation sensor is coupled to the image sensor, and is used for generating a portrait signal if the image sensor is positioned in a portrait orientation relative to the object. The memory, has an auto-rotate unit comprising program instructions for transforming the captured image data into rotated image data in response to the portrait signal. The processing unit, is used for

executing program instructions stored in the memory, and is coupled to the image sensor, the orientation sensor and the memory.

The method of the present invention preferably comprises the steps of: generating image data representative of an object with an image sensor; identifying an orientation of the image sensor relative to the object during the generating step; and selectively transferring the image data to an image processing unit in response to the identifying step.

BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1A, is a prior art graphical representation of an object in a landscape orientation;

FIG. 1B, is a prior art graphical representation of the object in a portrait orientation;

FIG. 1C, is a prior art 480 row by 640 column image sensor;

FIG. 1D, is a prior art graphical representation of the object as captured in the portrait orientation and output upon an image display;

FIG. 2, is a block diagram of a preferred embodiment of an apparatus for rotating the display orientation of a captured image;

FIG. 3A, is a block diagram of a preferred embodiment of an imaging subsystem of the present invention;

FIG. 3B, is a first graphical representation of a preferred embodiment of an image sensor disposed within the present invention;

FIG. 3C, is a second graphical representation of a preferred embodiment of the image sensor within the present invention;

FIG. 4A, is a block diagram of a preferred embodiment of a processing and storage subsystem of the present invention;

FIG. 4B, is a block diagram of a preferred embodiment of a volatile memory within the processing and storage subsystem;

FIG. 4C, is a block diagram of a preferred embodiment of a frame buffer data structure within a frame buffer;

FIG. 4D, is a block diagram of the preferred embodiment of a non-volatile memory within the processing and storage subsystem;

FIG. 5A, is a graphical representation of a preferred embodiment of portrait_left image data within the frame buffer data structure;

FIG. 5B, is a graphical representation of a preferred embodiment of portrait_right image data within the frame buffer data structure;

FIG. 5C, is a graphical representation of a preferred embodiment of landscape image data within the frame buffer data structure; and

FIGS. 6A, 6B, 6C and 6D, are a flowchart of a preferred method for rotating the display orientation of a captured image.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

The present invention is an apparatus and method for rotating the display orientation of a captured image.

Referring now to FIG. 2, a block diagram is shown illustrating a camera 200 for rotating a display orientation of a captured image. In the preferred embodiment, the camera 200 is a digital camera, such as a QuickTake 150, by Apple Computer of Cupertino, Calif. The camera 200 preferably comprises an imaging subsystem 204, a bus 206 and a processing and storage subsystem 208. Reflected light from an object 202 is conventionally captured by the imaging subsystem 204 via a button press or some other action. The captured image

data is transferred over the bus 206 to the processing and storage subsystem 208, which stores the data in internal memory. The bus 206 also passes various status and control signals between the imaging subsystem 204 and the processing and storage subsystem 208, as will be further discussed below.

Referring now to FIG. 3A, a block diagram is shown illustrating the imaging subsystem 204 of the present invention. The imaging subsystem 204 preferably comprises a lens 300 having an iris, an optical filter 302, an image sensor 304, a timing generator 306, an analog signal processor (ASP) 308, an analog-to-digital (A/D) converter 310, a digital signal processor (DSP) 320, a right/left orientation sensor (RLOS) 324, an up/down orientation sensor (UDOS) 326 and one or more motors 312. U.S. patent application Ser. No. 08/355,031, entitled A System and Method For Generating a Contrast Overlay as a Focus Assist For An Imaging Device, filed on Dec. 13, 1994 is incorporated herein by reference and provides a detailed discussion of the preferred elements in the imaging subsystem 204, with the exception of the RLOS 324 and the UDOS 326. U.S. patent application Ser. No. 08/384,012, entitled Apparatus and Method for Camera image and Orientation Capture, filed on Feb. 6, 1995 is incorporated herein by reference and provides a detailed discussion of various embodiments of the RLOS 324 and the UDOS 326, which are further discussed below. Briefly, the imaging subsystem 204 captures an image of the object 202 via light impacting the image sensor 304 along an optical path 314. The image sensor 304 in turn generates a set of pixel signals representative of the captured image data. After being processed by the ASP 308, the A/D converter 310 and the DSP 320; the captured image data passes over the bus 206 to the processing and storage subsystem 208. The functions performed by the DSP 320 may alternatively be performed in the processing and storage subsystem 208.

Referring now to FIG. 3B, a graphical representation is shown illustrating the image sensor 304 disposed within the camera 200. FIG. 3B shows the camera 200 maintained in a landscape orientation while directly facing the object 202. The image sensor 304 has a front 338 and a top 336, which are juxtaposed with a front 334 and a bottom 332 of the camera 200 respectively. The front side 338 of the image sensor 304 comprises light-sensitive pixels, which capture an image received along the optical path 314 and through the lens 300 mounted upon the camera 200. It should be noted that the image recorded by the image sensor 304 is inverted relative to the object by the lens 300. The front 338 of the image sensor 304 preferably forms a planar surface as shown in perspective in FIG. 3B. When the image sensor 304 is oriented as shown in FIG. 3B, a landscape image of the object 202 is captured. When the camera 200 is rotated either 90° clockwise or 90° counterclockwise about the x-axis, a portrait image of the object 202 is captured.

Referring now to FIG. 3C, a graphical representation is shown illustrating the image sensor 304, which has the top 336, a right side 342, a left side 340 and a bottom 344. The image sensor 304 is comprised of a plurality of pixels arranged in an i-row by j-column array. In the preferred embodiment, the pixels are arranged in a Bayer pattern format. Alternatively the present invention may be applied to image sensors of various sizes and image processing routines designed to process pixel signals arranged in patterns or formats different from the Bayer pattern.

As stated above, the RLOS 324 (i.e. the right/left orientation sensor) and the UDOS 326 (i.e. the up/down orientation sensor) are disposed within the imaging subsystem 204. Both the RLOS 324 and the UDOS 326 are physically coupled to

the image sensor **304** and electrically coupled to the DSP **320**. The RLOS **324** monitors whether the camera **200** is in a landscape orientation or a portrait orientation. If the camera **200** is in a portrait orientation, the RLOS **324** identifies whether the camera **200** has been rotated clockwise or counter-clockwise, as viewed from the rear of the camera **200**. In response to such camera **200** rotation, the RLOS **324** generates and transmits either a landscape signal, a portrait_left signal or a portrait_right signal to the DSP **320**. More specifically, if the camera **200** is held in the landscape orientation shown in FIGS. 1A and 3B, the RLOS **324** generates the landscape signal, since the top **336** of the image sensor **304** corresponds to the "TOP" of the object **202**. However, if the camera **200** is rotated 90° clockwise about the x-axis, as viewed from the rear of the camera **200** shown in FIG. 3B, the RLOS **324** generates the portrait_right signal, since now the right side **342** of the image sensor **304** corresponds to the "TOP" of the object **202**. And, if the camera **200** is rotated 90° counter-clockwise about the x-axis, as viewed from the rear of the camera **200**, the RLOS **324** generates the portrait_left signal, since now the left side **340** of the image sensor **304** corresponds to the "TOP" of the object **202**.

The UDOS **326** monitors whether the camera **200** is in either a level orientation or an off-level orientation. In response to a movement of the camera **200**, the UDOS **324** generates and transmits either a level signal or an off-level signal to the DSP **320**. Specifically, if the camera **200** is held in the landscape orientation shown in FIG. 3B, the UDOS **324** generates the level signal, since the front **334** of the camera **200** directly faces the object **202**. If the camera **200** is rotated more than 45° clockwise or counter-clockwise about the y-axis, shown in FIG. 3B, the UDOS **324** preferably generates the off-level signal, since the front **334** of the camera **200** now points either above or below the x-y plane. Alternative embodiments of the present invention can change the specific measure of rotation necessary to generate the off-level signal from 45° to any number from 0° to 180°.

Both the RLOS **324** and UDOS **326** sensors are preferably identical in their structure and function. Their placement relative to the image sensor **304** determines whether the signal generated by the orientation sensor is one of the RLOS **324** signals or the UDOS **326** signals. The DSP **320** receives both the RLOS **324** and the UDOS **326** signals and transmits them to the processing and storage subsystem **208** over the bus **206**. While the preferred embodiment of the present invention incorporates the orientation sensors **324**, **326**, those skilled in the art will recognize that the orientation sensors **324**, **326** are not required to practice the present invention, if the processing and storage subsystem **208** prompts the photographer for the camera's **200** orientation at the time an image is captured. Alternatively, an embodiment using only the RLOS **324** enables practicing of the present invention, but this alternative embodiment results in loss of the off-level signal. However, such an embodiment using only the RLOS **324** is still useful for most applications requiring only landscape and portrait orientation using an approximately level camera **200**. A further alternative embodiment includes an RLOS **324** which only generates the landscape, portrait_left, or portrait_right signals if the camera **200** is within a predetermined level range.

Referring now to FIG. 4A, a block diagram is shown illustrating the processing and storage subsystem **208** of the present invention. The processing and storage subsystem **208** comprises a buffer **400**, a processing unit **404**, a non-volatile memory **406**, an input device **408**, a volatile memory **410** and an I/O interface **414**, coupled together via an internal bus **402**. In the preferred embodiment, the processing and storage sub-

system **208** is conventionally embedded as part of the camera **200**. Alternatively, the processing and storage subsystem **208** may be a desktop type computer.

The buffer **400** is preferably a first-in, first-out buffer for temporarily holding the captured image data and the imaging subsystem **204** control signals passed between the DSP **320** and the processing and storage subsystem **208**. The buffer **400** has data lines that are coupled to both the bus **206** and the internal bus **402**. The processing unit **404** executes programming instructions stored in the non-volatile memory **406** and the volatile memory **410** to perform various operations. The non-volatile memory **406** stores a set of computer readable program instructions for controlling how the processing unit **404** accesses, transforms and outputs the image data, as described in detail below with reference to FIG. 4D. While the non-volatile memory **406** is preferably a Read Only Memory (ROM), alternatively the non-volatile memory **406** could be replaced with a functionally equivalent computer useable medium such as: a compact disk and drive; a floppy disk and drive; or a memory card. Additional details on the function and operation of both the non-volatile memory **406** and the volatile memory **410** are provided below with reference to FIGS. 4B and 4D.

The input device **408** is preferably a series of control buttons, responsive to user inputs, which generates signals that are translated by the processing unit **404** into control signals to adjust the focus and other operating parameters of the imaging subsystem **204**. As mentioned above, while the preferred embodiment of the camera **200** incorporates the RLOS **324** and UDOS **326**, an alternative embodiment of the present invention prompts the user to manually input, via the input device **408**, the imaging subsystem's **204** orientation at the time the captured image data was generated. Other alternative embodiments incorporating the automatic RLOS **324** and UDOS **326** sensors could provide for an override function that instructs the processing and storage subsystem **208** to ignore the orientation signals generated by the RLOS **324** and UDOS **326** sensors, enabling the user to retain full manual control over the final orientation of the captured image data on the image display **100**. The I/O Interface **414** is coupled to the internal bus **402** and has an external port connector for coupling the processing and storage subsystem **208** with a host computer (not shown) for downloading image data stored in the volatile memory **410** and thus freeing up room in the volatile memory **410** for additional sets of processed image data. In the second and alternative embodiment discussed above where the processing and storage subsystem **208** is a desktop type computer, the input device **408** will also include a keyboard and mouse type controller.

Referring now to FIG. 4B, a block diagram is shown illustrating a volatile memory **410** within the processing and storage subsystem **208**. The volatile memory **410** contains a frame buffer **416**, working memory **418** and storage memory **420** coupled to the internal bus **402**. The volatile memory **410** is preferably a Random Access Memory (RAM).

The frame buffer **416** is preferably comprised of a dedicated space of contiguous memory comprising an i-row by j-column area for storing image data. There is preferably a constant one-to-one correspondence between the pixels comprising the image sensor **304** array and the storage locations within the frame buffer **416** area. Alternatively, the pixel signals from the image sensor **304** array could be stored within the frame buffer **416** in a non-contiguous (i.e. scattered) memory format, as is commonly known in the art. In the preferred embodiment, i and j are set equivalent to the size of the image sensor **304**. Since the preferred image sensor **304** is a 481 by 641 array, i is set to 481 and j is set to 641. In

alternative embodiments where the image sensor **304** is only a 480 by 640 array, the frame buffer **416** will still preferably be a 481 by 641 array since, as is discussed below, an extra row and column is generated by the processing and storage subsystem **208**.

The working memory **418** preferably provides a temporary space for storing data received from the input device **408** and for data generated by the processing unit **404**. The working memory **418** also contains additional memory for storing the RLOS **324** and UDOS **326** signals at the time the image data was captured by the image sensor **304**; and additional information conventionally associated with the capture process, such as exposure and focus settings, time and date, statistical data, and the presence of any defective pixels, rows or columns within the image sensor **304**.

The storage memory **420** preferably provides space for storing multiple sets of image data, until the images are off-loaded from the camera **200** via the I/O interface **414**. The storage memory **420** sets a maximum image data holding capacity of the camera **200**. Alternatively, additional memory cards could also be coupled to the internal bus **402**, providing even more image data storage capability. Such an additional memory card could be a non-volatile flash memory card.

Referring now to FIG. **4C**, a block diagram is shown illustrating a memory map of a volatile memory data structure **417** within the volatile memory **410**. The volatile memory data structure **417** comprises an image data field **419** for storing the captured image data, an RLOS signal data field **421** for storing the RLOS **324** signal, an UDOS signal data field **423** for storing the UDOS **326** signal and a miscellaneous data field **425** for storing the exposure and focus settings, time and date, statistical data, and the presence of any defective image sensor **304** pixels, rows or columns. The interactions of each of all these data fields **419**, **421**, **423**, **425** with the camera **200** is described in detail below.

Referring now to FIG. **4D**, a block diagram is shown illustrating the non-volatile memory **406** within the processing and storage subsystem **208**. The non-volatile memory **406** comprises an auto-rotate unit **422**, an image processing unit **424**, an image capture unit **428** and an operating system unit **426**.

The image capture unit **428** controls the imaging subsystem's **204** focus and aperture settings; captures the image data; routes the image data into the frame buffer **416**; routes the exposure and focus settings, time and date, statistical data, and the presence of any defective image sensor **304** pixels, rows or columns into the miscellaneous data field **425**; generates additional rows and columns of image data within the frame buffer **416** if required; monitors the RLOS **324** and UDOS **326**; and sets the RLOS signal **421** data field and the UDOS signal **423** data field based on the RLOS **324** and UDOS **326** outputs. In the preferred embodiment the image capture unit **428** corrects any pixel defects within the image sensor **304** using the information stored in the miscellaneous data field **425** before passing the image data to the auto-rotate unit **422**. In an alternative embodiment, image processing unit **424** corrects any pixel defects within the image sensor **304** using the information stored in the miscellaneous data field **425** after receiving the image data from the auto-rotate unit **422**. In this alternative embodiment, the defective image sensor **304** pixel information must also be rotated by the auto-rotate unit **422** in the same manner as for the image data, described below.

The image capture unit **428** preferably is designed in two embodiments, a hardware embodiment and a software embodiment; however, the hardware embodiment is preferred.

Hardware Embodiment

In the hardware embodiment, the image sensor **304** is comprised of at least one more extra row and column than the image processing unit **424** is designed to process. Thus, if the image processing unit **424** is designed to process a 480 by 640 pixel signal array, then the image sensor **304** must be at least a 481 by 641 pixel array (i.e. "i" is 481 and "j" is 641 in FIG. **3C**). The discussion that follows on the auto-rotate unit **422** makes clear when and why the additional row and column is required.

Software Embodiment

The software embodiment is required when the image sensor **304** lacks any additional rows and columns beyond those that the image processing unit **424** is designed to process. For Bayer pattern image processing, the image capture unit **428** must generate an additional row and column of image data. (For non-Bayer pattern image data, a straightforward rotation is performed as is described below and an additional row and column is not required.) Thus, for example, if the image sensor **304** is comprised of a 480 by 640 pixel array and the image processing unit **424** is designed to process a 480 by 640 array, then the image capture unit **428** must generate an additional row and column of pixels. In the preferred software embodiment, the additional row generated corresponds to row r_i (i.e. GRGRGR) in FIG. **3C** and the additional column generated corresponds to column c_j (i.e. GBGBGB) in FIG. **3C**. The additional row and column may be generated in any number of ways, including: setting the additional pixels to black; creating a duplicate of a nearby line of pixels with the same pixel pattern (i.e. two pixel lines over); generating a duplicate of the nearest color (i.e. G's would be copied from one pixel line over while R's or B's would be copied from two pixel lines over); setting the pixel values based on a filtering algorithm which looks at a number of nearby pixels; or setting the additional row and column of pixels randomly.

The auto-rotate unit **422** transforms the captured image data into the rotated image data for further processing by the image processing unit **424**. The image processing unit **424** receives the rotated image data from the auto-rotate unit **422** and transforms it into processed image data, ready for saving in the storage memory **420**. The operating system unit **426** is coupled to the internal bus **402** and preferably comprises a conventional set of program instructions for controlling the configuration and usage of the computer's **208** hardware resources. The operations performed by the auto-rotate unit **422** and the image processing unit **424** are described in more detail below.

Referring now to FIGS. **5A**, **5B** and **5C**, a graphical representation is shown in FIG. **5A** illustrating portrait_left image data within the frame buffer **416**; a graphical representation is shown in FIG. **5B** illustrating portrait_right image data within the frame buffer **416**; and a graphical representation is shown in FIG. **5C** illustrating landscape image data within the frame buffer **416**. FIGS. **5A**, **5B** and **5C** all show the same image data **419** within the frame buffer data structure **417** filled with different sets of captured image data and graphically positioned in the orientation in which the camera **200** was held at the time the captured image data was generated. As will be discussed in detail below, the shaded areas represent a subset of pixel signals within the image data field **419** that the auto-rotate unit **422** selects to be sent to the image processing unit **424** as the rotated image data.

The auto-rotate unit **422** preferably comprises program instructions stored in the non-volatile memory **406** that are executed by the processing unit **404**. The auto-rotate unit **422** controls the flow of data between the frame buffer **416** and the image processing unit **424**. First, the auto-rotation unit **422**

accesses the RLOS signal 421 data field and UDOS signal 423 data field from the frame buffer data structure 417; and, based on this orientation data, selects either a portrait_left spooling routine, a portrait_right spooling routine or a landscape spooling routine. The spooling routines select-out and feed the captured image data stored in the image data field 419 to the image processing unit 424. "Spooling" is here defined as a routine for transferring data from one unit or device to a second unit or device. It is through these spooling routines that the auto-rotate unit 422 transforms the captured image data into the rotated image data. While the effect of the auto-rotate unit 422 is only described below with reference to the captured image data, some of the additional information stored in the working memory 418 (such as the location of any defective pixels, rows or columns within the image sensor 304) will also be rotated, as described above. This additional information is then used by the image processing unit 424. Alternatively, a defective pixel correction algorithm can be applied to the image data prior to rotation of the image data. Each of the different spooling routines are described in detail below.

First, the auto-rotate unit 422 determines the image sensor's 304 orientation at the time the image was captured, by accessing the RLOS signal 421 and UDOS signal 423 data fields. Next, if the RLOS signal 421 data field contains a portrait_left signal and the UDOS signal 423 data field contains a level signal, the auto-rotate unit 422 selects the portrait_left spooling routine. However, if the RLOS signal 421 data field contains a portrait_right signal and the UDOS signal 423 data field contains a level signal, the auto-rotate unit 422 selects the portrait_right spooling routine. Lastly, if the RLOS signal 421 data field contains a landscape signal and the UDOS signal 423 data field contains a level signal, or whenever the UDOS signal 423 data field contains an off-level signal, regardless of what the RLOS signal 421 data field contains, the auto-rotate unit 422 selects the landscape spooling routine. Each of the three spooling routines within the auto-rotate unit 422 are now discussed below.

If the portrait_left spooling routine is selected, the auto-rotate unit 422 interprets the captured image data within the image data field 419 as shown in FIG. 5A. FIG. 5A shows an i-row by j-column set of captured image data in a portrait_left orientation. As shown, the "TOP" of the portrait_left orientation corresponds to column c_2 . Note that the "row" and "column" designations defined for the image sensor 304 in FIG. 3C are retained for clarity in FIGS. 5A, 5B and 5C even though the camera has been rotated into the portrait_left orientation. Conventional image processing units are designed to receive image data in a constant pixel pattern format. Using the Bayer pattern format (assumed for the purposes of this discussion) the image processing unit 424 must receive the image data from the image data field 419 starting with a "GRGRGR" line and followed by a "BGB-GBG" line, in an alternating line-by-line pattern. Therefore, a subset of the image data field 419 is selected by the portrait_left spooling routine, as shown by the shaded gray area in FIG. 5A, to be sent to the image processing unit 424. The shaded area of FIG. 5A is defined from rows r_1 to r_{i-1} , and from columns c_2 to c_j . The total array size of the shaded area is therefore comprised of $i-1$ number of rows and $j-1$ number of columns. Next, the portrait_left spooling routine defines the shaded area of c_2 as the top line of the rotated image data and configures the image processing unit 424 to accept a line length of $i-1$ pixels. The portrait_left spooling routine first transfers the pixel signal in the image data field 419 location (r_{i-1}, c_2) to the image processing unit 424. Decrementing the row number by one, the portrait_left spooling routine next

transfers the pixel signal at location (r_{i-2}, c_2) to the image processing unit 424, and so on until pixel (r_1, c_2) has been transferred. The portrait_left spooling routine then increments the column by one to c_3 and resets the row to r_{i-1} in preparation for spooling the next line of pixel signals (having a length of $i-1$) to the image processing unit 424, in the same manner as the first line (having a length of $i-1$) was spooled. The portrait_left spooling routine continues to increment the column number and spool the next line of pixel signals (having a length of $i-1$) to the image processing unit 424 until column c_j has been spooled. The pixel signals within either row r_i or column c_1 are not sent to the image processing unit 424 since the image processing unit 424 is preferably designed to process only an $i-1$ by $j-1$ array of pixel signals. As a result of this spooling sequence, the entire set of pixel signals representing a portrait_left image has been transferred to the image processing unit 424. Furthermore, due to this specific spooling sequence, the portrait left image will be displayed on the image display 100 so that the "TOP" of the portrait_left image corresponds to the top 102 of the image display 100.

If the portrait_right spooling routine is selected, the auto-rotate unit 422 interprets the captured image data within the image data field 419 as shown in FIG. 5B. FIG. 5B shows an i-row by j-column set of captured image data in a portrait_right orientation. As shown, the "TOP" of the portrait_right orientation corresponds to column c_{j-1} . A subset of the image data field 419 is selected by the portrait_right spooling routine, as shown by the shaded gray area in FIG. 5B, to be sent to the image processing unit 424. The shaded area of FIG. 5B is defined from rows r_2 to r_i , and from columns c_1 to c_{j-1} . The total array size of the shaded area is therefore comprised of $i-1$ number of rows and $j-1$ number of columns. Next, the portrait_right spooling routine defines the shaded area of c_{j-1} as the top line of the rotated image data and configures the image processing unit 424 for a line length of $i-1$ pixels. The portrait_right spooling routine first transfers the pixel signal in the image data field 419 location (r_2, c_{j-1}) to the image processing unit 424. Incrementing the row number by one, the portrait_right spooling routine next transfers the pixel signal at location (r_3, c_{j-1}) to the image processing unit 424, and so on until pixel (r_i, c_{j-1}) has been transferred. The portrait_right spooling routine then decrements the column by one to c_{j-2} and resets the row to r_2 in preparation for spooling the next line of pixel signals (having a length of $i-1$) to the image processing unit 424, in the same manner as the first line (having a length of $i-1$) was spooled. The portrait_right spooling routine continues to decrement the column number and spool the next line of pixel signals (having a length of $i-1$) to the image processing unit 424 until column c_1 has been spooled. Thus, the entire set of pixel signals representing a portrait_right image has been transferred to the image processing unit 424. As a result of this specific spooling sequence, the portrait_right image will be displayed on the image display 100 so that the "TOP" of the portrait_right image corresponds to the top 102 of the image display 100.

If the landscape spooling routine is selected, the auto-rotate unit 422 interprets the captured image data within the image data field 419 as shown in FIG. 5C. FIG. 5C shows an i-row by j-column set of captured image data in a landscape orientation. As shown, the "TOP" of the landscape orientation corresponds to r_1 . A subset of the image data field 419 is selected by the landscape spooling routine, as shown by the shaded gray area in FIG. 5C, to be sent to the image processing unit 424. The shaded area of FIG. 5C is defined from rows r_1 to r_{i-1} , and from columns c_1 to c_{j-1} . The total array size of the shaded area is therefore comprised of $i-1$ number of rows

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and $j-1$ number of columns. Next, the landscape spooling routine defines the shaded area of r_1 as the top line of the rotated image data and configures the image processing unit 424 for a line length of $j-1$ pixels. Alternatively, the shaded gray area representing the rotated image data could be positioned over different sets of pixel signals within the image data field 419, again subject to the constraint that the top line begin with the "GRGRGR" pattern. The landscape spooling routine first transfers the pixel signal in the image data field 419 location (r_1, c_1) to the image processing unit 424. Incrementing the column number by one, the landscape spooling routine next transfers the pixel signal at location (r_1, c_2) to the image processing unit 424, and so on until pixel (r_1, c_{j-1}) has been transferred. The landscape spooling routine then increments the row by one to r_2 and resets the column to c_1 in preparation for spooling the next line of pixel signals (having a length of $j-1$) to the image processing unit 424, in the same manner as the first line (having a length of $j-1$) was spooled. The landscape spooling routine continues to increment the row number and spool the next line of pixel signals (having a length of $j-1$) to the image processing unit 424 until row r_{i-1} has been spooled. Thus, the entire set of pixel signals representing a landscape image has been transferred to the image processing unit 424. As a result of this specific spooling sequence, the landscape image will be displayed on the image display 100 so that the "TOP" of the landscape image corresponds to the top 102 of the image display 100.

Also as introduced above, the image processing unit 424 preferably comprises program instructions stored in the non-volatile memory 406 that are executed using the processing unit 404. The image processing unit 424 receives the rotated image data from the auto-rotate unit 422, performs conventional image processing operations (such as white balancing, reconstruction, color correction, gamma correction, sharpening and compression) on the rotated image data; generates processed image data; and either saves the processed image data to the storage memory 420 or outputs it to a host computer (not shown) via the I/O interface 414. As was discussed above, the image processing unit 424 is preferably implemented such that it must receive all the image data spooled from the frame buffer 416 starting with a "GRGRGR" line followed by a "BGBGBG" line in an alternating line-by-line pattern. This is the image processing unit's 424 design limitation which drives the auto-rotate unit's 422 particular pixel selection routines described above. Alternatively, a different image processing unit 424 could be implemented which requires that the image data be spooled from the frame buffer 416 starting with a "GBGBGB" line followed by a "RGRGRG" line or any combination of the Bayer pattern.

Those skilled in the art will also recognize that alternate embodiments of the present invention that do not use the Bayer pattern may still use the teachings of present invention to rotate their image data. In such alternative embodiments the auto-rotate unit 422 performs a straightforward rotation of the image data since such alternative image processing units 424 may accept pixel signals in any orientation. Thus for the straightforward rotation where the shaded gray area of FIG. 5C represents the image data, the portrait_left spooling routine would start with pixel signal (r_{i-1}, c_1) , spool column c_1 , increment the column to c_2 , spool column c_2 and so on; the portrait_right spooling routine would start with pixel signal (r_1, c_{j-1}) , spool column c_{j-1} , decrement the column to c_{j-2} , spool column c_{j-2} and so on; and the landscape spooling routine would start with pixel signal (r_1, c_1) , spool row r_1 , increment the row to r_2 , spool row r_2 and so on. In all three cases above, the extra or provided row r_i and extra or provided column c_j would not be transferred.

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Referring now to FIGS. 6A, 6B, 6C and 6D, a flowchart of a preferred method for rotating the display orientation of a captured image is shown. The method begins in FIG. 6A with step 600 where the image capture unit 428 captures a set of image data and a set of image sensor 304 orientation data approximately simultaneously. The RLOS 421 and UDOS 423 orientation signals are recorded when the image data capture occurs in order to insure that the orientation sensor information accurately reflects the actual position of the image sensor 304. In step 602, the image capture unit 428 transfers the captured image data and the image sensor 304 orientation data into the volatile memory 410. In Step 603, the image capture unit 428 generates an additional row and column of image data if the captured image data does not already include an extra row and column of image data. In Step 604, the auto-rotate unit 422 determines the orientation of the captured image data. If in step 606 the captured image data is in a portrait_left orientation, the method proceeds to step 612, otherwise the method continues to step 608. If in step 608 the captured image data is in a portrait_right orientation, the method proceeds to step 628, otherwise the method proceeds to step 644.

In step 612 of FIG. 6B, the auto-rotate unit 422 configures the image processing unit 424 to accept an image data line length corresponding to a portrait_left image. In step 614, the auto-rotation unit 422 initializes a variable named "column" stored in the working memory 418 to a first pixel column (i.e. to column c_2), within the image data field 419, required by the image processing unit 424. In step 616, the auto-rotation unit 422 initializes a variable named "row" stored in the working memory 418 to a row (i.e. to row r_{i-1}) within the image data field 419 containing a first pixel color required by the image processing unit 424. Next, in step 618, the auto-rotate unit 422 transfers the captured image data in the image data field 419 location (r_{row}, c_{column}) to the image processing unit 424. In step 620, the auto-rotate unit 422 decrements "row" to a row containing a next pixel color required by the image processing unit 424. In step 622, if "last row" has been transferred, the method proceeds to step 623, otherwise the method returns to step 618. In the preferred embodiment "last row" is " r_1 " as shown in FIG. 5A. When "last row" has been transferred in step 622, an entire line of portrait_left image data has been transferred to the image processing unit 424. In step 623 the image processing unit 424 performs any required image processing on the transferred image data. Step 624 then increments "column" to a next pixel column required by the image processing unit 424. Finally, if in step 626 "last column" has not yet been transferred the method returns to step 616, otherwise the method ends. In the preferred embodiment "last column" is " c_j ," as shown in FIG. 5A.

In step 628 of FIG. 6C, the auto-rotate unit 422 configures the image processing unit 424 to accept an image data line length corresponding to a portrait_right image. In step 630, the auto-rotation unit 422 initializes a variable named "column" stored in the working memory 418 to a first pixel column (i.e. to column c_{j-1}), within the image data field 419, required by the image processing unit 424. In step 632, the auto-rotation unit 422 initializes a variable named "row" stored in the working memory 418 to a row (i.e. to row r_2) within the image data field 419 containing a first pixel color required by the image processing unit 424. Next, in step 634, the auto-rotate unit 422 transfers the captured image data in the image data field 419 location (r_{row}, c_{column}) to the image processing unit 424. In step 636, the auto-rotate unit 422 increments "row" to a row containing a next pixel color required by the image processing unit 424. In step 638, if "last row" has been transferred, the method proceeds to step 639,

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otherwise the method returns to step 634. In the preferred embodiment “last row” is “ r_i ,” as shown in FIG. 5B. When “last row” has been transferred in step 638, an entire line of portrait_right image data has been transferred to the image processing unit 424. In step 639 the image processing unit 424 performs any required image processing on the transferred image data. Step 640 then decrements “column” to a next pixel column required by the image processing unit 424. Finally, if in step 642 “last column” has not yet been transferred the method returns to step 632, otherwise the method ends. In the preferred embodiment “last column” is “ c_1 ,” as shown in FIG. 5B.

In step 644 of FIG. 6D, the auto-rotate unit 422 configures the image processing unit 424 to accept an image data line length corresponding to a landscape image. In step 646, the auto-rotation unit 422 initializes a variable named “row” stored in the working memory 418 to a first pixel row (i.e. to row r_1), within the image data field 419, required by the image processing unit 424. In step 648, the auto-rotation unit 422 initializes a variable named “column” stored in the working memory 418 to a column (i.e. to column c_1) within the image data field 419 containing a first pixel color required by the image processing unit 424. Next, in step 650, the auto-rotate unit 422 transfers the captured image data in the image data field 419 location (r_{row}, c_{column}) to the image processing unit 424. In step 652, the auto-rotate unit 422 increments “column” to a column containing a next pixel color required by the image processing unit 424. In step 654, if “last column” has been transferred, the method proceeds to step 655, otherwise the method returns to step 650. In the preferred embodiment “last column” is “ c_{j-1} ,” as shown in FIG. 5C. When “last column” has been transferred in step 654, an entire line of landscape image data has been transferred to the image processing unit 424. In step 655 the image processing unit 424 performs any required image processing on the transferred image data. Step 656 then increments “row” to a next pixel row required by the image processing unit 424. Finally, if in step 658 “last row” has not yet been transferred the method returns to step 648, otherwise the method ends. In the preferred embodiment “last row” is “ r_{i-1} ,” as shown in FIG. 5C.

While the present invention has been described with reference to certain preferred embodiments, those skilled in the art will recognize that various modifications may be provided. For instance, while the preferred embodiment of the present invention selects and processes the captured image data as a rectangular array, alternate embodiments could select and process the image data as an array of tiles rather than lines. Furthermore, by transferring the pixels signals to the image processing unit 424 in a different order, a mirror image or an upside-down image of the captured image data can be presented on the image display 100. Lastly, while the preferred embodiment is implemented in software, those skilled in the art would readily recognize that a hardware equivalent implementation would also be acceptable. These and other variations upon and modifications to the preferred embodiment are provided for by the present invention which is limited only by the following claims.

What is claimed is:

[1. An apparatus for rotating a display orientation of captured image data representative of an object, the apparatus comprising:

- an image sensor, for generating said captured image data;
- an orientation sensor coupled to said image sensor, for generating a signal corresponding to the position of the image sensor relative to said object;
- a memory, having an auto-rotate unit comprising program instructions for selectively transforming said captured

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image data into rotated image data in response to said position signal, said memory coupled to said image sensor and to said orientation sensor; and
 an image processing unit coupled to said memory for executing program instructions stored in said memory; wherein (a) said image processing unit processes an i -by- j array of said captured image data and said image sensor generates an $i+1$ -by- $j+1$ array of said image data, or (b) an image capture unit generates an additional row and column of pixels for said captured image data from said image sensor.]

[2. The apparatus of claim 1, wherein the memory further comprises:

an image processing unit comprising program instructions for transforming one from a group consisting of captured image data and portrait image data, into processed image data.]

[3. The apparatus of claim 1, wherein: the signal is a portrait_left signal if the image sensor is rotated clockwise from a landscape orientation relative to the object, and the signal is a portrait_right signal if the image sensor is rotated counter-clockwise from the landscape orientation relative to the object; and

the auto-rotate unit comprises program instructions for transforming the captured image data into portrait_left image data in response to the portrait_left signal and into portrait_right image data in response to the portrait_right signal.]

[4. The apparatus of claim 1, wherein:

the signal is a landscape signal if the image sensor is positioned in a level orientation relative to the object; and

the auto-rotate unit comprises program instructions for transforming the captured image data into landscape image data in response to the landscape signal.]

[5. The apparatus of claim 3, wherein:

the image sensor has a top, a bottom, a right side and a left side;

the auto-rotate unit program instructions transform the captured image data into the portrait_left image data by transferring a prior portrait_left line of image data which starts further toward the bottom of the image sensor and ends further toward the top of the image sensor, then transferring a subsequent portrait_left line of image data, located closer to the right side of the image sensor than the prior portrait_left line of image data, and also starting further toward the bottom of the image sensor and ending further toward the top of the image sensor; and

the auto-rotate unit program instructions transform the captured image data into the portrait_right image data by transferring a prior portrait_right line of image data which starts further toward the top of the image sensor and ends further toward the bottom of the image sensor, then transferring a subsequent portrait_right line of image data, located closer to the left side of the image sensor than the prior portrait_right line of image data, and also starting further toward the top of the image sensor and ending further toward the bottom of the image sensor.]

[6. The apparatus of claim 4, wherein:

the image sensor has a top, a bottom, a right side and a left side; and

the auto-rotate unit program instructions transform the captured image data into the landscape image data by transferring a prior landscape line of image data which starts further toward the left side of the image sensor and

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ends further toward the right side of the image sensor, then transferring a subsequent landscape line of image data, located closer to the bottom of the image sensor than the prior landscape line of image data, and also starting further toward the left side of the image sensor and ending further toward the right side of the image sensor.]

[7. The apparatus of claim 3, wherein:

the portrait_left signal is generated by the orientation sensor if the image sensor is rotated approximately 45° clockwise from the level orientation, and the portrait_right signal is generated by the orientation sensor if the imaging subsystem is rotated approximately 45° counter-clockwise from the level orientation.]

[8. The apparatus of claim 5, wherein:

the prior portrait_left line of image data and the prior portrait_right line of image data comprise a “green, red, green, red” pixel pattern; and the subsequent portrait_left line of image data and the subsequent portrait_right line of image data comprise a “blue, green, blue, green” pixel pattern.]

[9. An apparatus for rotating a display orientation of multicolor captured image data having an i-by-j pixel matrix with a pattern representative of an object, comprising:

an image sensor, for generating the multicolor captured image data;

an input device, for generating a portrait_left signal in response to a first user selection, a portrait_right signal in response to a second user selection, and a landscape signal in response to a third user selection;

a memory, having:

an auto-rotate unit comprising program instructions for selectively transforming the multicolor captured image data into portrait_left image data in response to the portrait-left signal, portrait_right image data in response to the portrait_right signal, and landscape image data in response to the landscape signal; and an image processing unit comprising program instructions for transforming the portrait_left image data, the portrait_right image data and the landscape image data into processed image data; and

a processing unit, coupled to the image sensor, to the input device, and to the memory, for executing program instructions stored in the memory;

wherein said image processing unit changes the number of pixel rows and pixel columns of the multicolor captured image data such that, from a defined referenced viewpoint, the portrait left image data, the portrait right image data, and the landscape image data, each includes the an (i-1)-by-(j-1) pixel matrix having said pattern.]

[10. The apparatus of claim 9, wherein the image processing unit has a first line length for processing the portrait_left image data and the portrait_right image data and a second line length for processing the landscape image data.]

[11. A method for rotating a display orientation of image data representative of an object, comprising the steps of:

generating image data with an image sensor;

identifying an orientation of the image sensor relative to the object at a time substantially simultaneous with the generating step, where said identifying is performed by an orientation sensor; and

selectively transferring data to an image processing unit in response to the identifying step;

wherein said image processing unit rotates said display orientation of said image data and (a) said image processing unit processes an i-by-j array of said captured image data and said image sensor generates an i+1-by-

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j+1 array of said image data, or (b) an image capture unit generates an additional row and column of pixels for said captured image data from said image sensor.]

[12. The method of claim 11, further comprising the step of:

generating an additional row and column of image data.]

[13. The method of claim 11, further comprising the step of correcting defects within the image data caused by defects within the image sensor.]

[14. The method of claim 11, wherein the image sensor comprises a top, a right side and a left side, wherein the image comprises a “top portion,” and wherein the step of identifying an orientation further comprises the steps of:

identifying a portrait_left orientation, if the left side of the image sensor corresponds to the “top portion” of the object;

identifying a portrait_right orientation, if the right side of the image sensor corresponds to the “top portion” of the object; and

identifying a landscape orientation, if the top of the image sensor corresponds to the “top portion” of the object.]

[15. The method of claim 11, wherein the step of identifying an orientation further comprises the steps of:

identifying a portrait_left orientation, in response to a user selection of the portrait_left orientation on an input device;

identifying a portrait_right orientation, in response to a user selection of the portrait_right orientation on the input device; and

identifying a landscape orientation, in response to a user selection of the landscape orientation on the input device.]

[16. The method of claim 11, wherein the orientation is a portrait_left orientation, wherein the image data is comprised of an array of pixel colors ordered in rows and columns, and wherein the step of selectively transferring comprises the steps of:

initializing a column variable to a first column of pixel colors required by the image processing unit;

initializing a row variable to a row containing a first pixel color required by the image processing unit;

transferring pixel color at an array location defined by the row variable and the column variable to and the image processing unit;

decrementing the row variable to a row containing a next pixel color required by the image processing unit;

returning to the transferring step, if a row containing a last pixel color has not been transferred;

incrementing the column variable to a next column of pixel colors required by the image processing unit; and

returning to the initializing a row variable step, if a last column of pixel colors has not been transferred.]

[17. The method of claim 16, wherein the image data is replaced by defective image sensor information, further comprising the step of repeating the steps of claim 16.]

[18. The method of claim 16, further comprises the steps of:

configuring the image processing unit to accept an image data line length corresponding to the portrait_left orientation; and

performing image processing on a line of transferred image data.]

[19. The method of claim 11, wherein the orientation is a portrait_right orientation, wherein the image data is comprised of an array of pixel colors ordered in rows and columns, and wherein the step of selectively transferring comprises the steps of:

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initializing a column variable to a first column of pixel colors required by the image processing unit;
 initializing a row variable to a row containing a first pixel color required by the image processing unit;
 transferring pixel color at an array location defined by the row variable and the column variable, to the image processing unit;
 incrementing the row variable to a row containing a next pixel color required by the image processing unit;
 returning to the transferring step, if a row containing a last pixel color has not been transferred;
 decrementing the column variable to a next column of pixel colors required by the image processing unit; and
 returning to the initializing a row variable step, if a last column of pixel colors has not been transferred.]

[20. The method of claim 11, wherein the orientation is a landscape orientation, wherein the image data is comprised of an array of pixel colors ordered in rows and columns, and wherein the step of selectively transferring further comprises the steps of:

initializing a row variable to a first row of pixel colors required by the image processing unit;
 initializing a column variable to a column containing a first pixel color required by the image processing unit;
 transferring pixel color at an array location defined by the row variable and the column variable, to the image processing unit;
 incrementing the column variable to a column containing a next pixel color required by the image processing unit;
 returning to the transferring step, if a column containing a last color pixel has not been transferred;
 incrementing the row variable to a next row of pixel colors required by the image processing unit; and
 returning to the initializing a column variable step, if a last row of pixel colors has not been transferred.]

[21. An apparatus for rotating a display orientation of multicolor image data having an i -by- j pixel matrix with a pattern representative of an object, comprising:

means for generating multicolor image data with an image sensor;
 orientation sensor means for identifying an orientation of said image sensor relative to said object at a time substantially simultaneous with said generating said multicolor image data; and
 means for selectively transferring said multicolor image data to an image processing unit in response to said means for identifying;
 wherein said image processing unit rotates said display orientation of said multicolor image data for providing rotated multicolor image data, and changes the number of pixel rows and pixel columns of said multicolor image data such that, from a defined referenced viewpoint, said rotated multicolor image data includes having an $(i-1)$ -by- $(j-1)$ pixel matrix said pattern.]

[22. The apparatus of claim 21, further comprising means for generating an additional row and column of image data.]

[23. The apparatus of claim 21, further comprising means for correcting defects within the image data caused by defects within the image sensor.]

[24. The apparatus of claim 21, wherein the image sensor comprises a top, a right side and a left side, wherein the image comprises a “top portion,” and wherein the means for identifying an orientation further comprises:

means for identifying a portrait_left orientation, if the left side of the image sensor corresponds to the “top portion” of the object;

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means for identifying a portrait_right orientation, if the right side of the image sensor corresponds to the “top portion” of the object; and
 means for identifying a landscape orientation, if the top of the image sensor corresponds to the “top portion” of the object.]

[25. The apparatus of claim 21, wherein the orientation is a portrait_left orientation, wherein the image data is comprised of an array of pixel colors ordered in rows and columns, and wherein the means for selectively transferring comprises:

means for initializing a column variable to a first column of pixel colors required by the image processing unit;
 means for initializing a row variable to a row containing a first pixel color required by the image processing unit;
 means for transferring pixel color at an array location, defined by the row variable and the column variable, to the image processing unit;
 means for decrementing the row variable to a row containing a next pixel color required by the image processing unit;
 means for returning to the means for transferring, if a row containing a last pixel color has not been transferred;
 means for incrementing the column variable to a next column of pixel colors required by the image processing unit; and
 means for returning to the means for initializing a row variable, if a last column of pixel colors has not been transferred.]

[26. The apparatus of claim 21, wherein the orientation is a portrait_right orientation, wherein the image data is comprised of an array of pixel colors ordered in rows and columns, and wherein the means for selectively transferring comprises:

means for initializing a column variable to a first column of pixel colors required by the image processing unit;
 means for initializing a row variable to a row containing a first pixel color required by the image processing unit;
 means for transferring pixel color at an array location, defined by the row variable and the column variable, to the image processing unit;
 means for incrementing the row variable to a row containing a next pixel color required by the image processing unit;
 means for returning to the means for transferring, if a row containing a last pixel color has not been transferred;
 means for decrementing the column variable to a next column of pixel colors required by the image processing unit; and
 means for returning to the means for initializing a row variable, if a last column of pixel colors has not been transferred.]

[27. The apparatus of claim 21, wherein the orientation is a landscape orientation, wherein the image data is comprised of an array of pixel colors ordered in rows and columns, and wherein the means for selectively transferring comprises:

means for initializing a row variable to a first row of pixel colors required by the image processing unit;
 means for initializing a column variable to a column containing a first pixel color required by the image processing unit;
 means for transferring pixel color at an array location, defined by the row variable and the column variable, to the image processing unit;
 means for incrementing the column variable to a column containing a next pixel color required by the image processing unit;

means for returning to the means for transferring, if a column containing a last color pixel has not been transferred;

means for incrementing the row variable to a next row of pixel colors required by the image processing unit; and

means for returning to the means for initializing a column variable, if a last row of pixel colors has not been transferred.]

[28. A computer useable medium embodying computer readable program code for causing a computer to rotate a display orientation of multicolor image data having an i -by- j pixel matrix with a pattern representative of an object, by performing steps comprising:

generating said multicolor image data with an image sensor;

identifying an orientation of the image sensor relative to the object at a time substantially simultaneous with the generating step, wherein said identifying of said orientation is performed with an orientation sensor; and

selectively transferring image data to an image processing unit in response to the identifying step,

wherein said image processing unit rotates said display orientation of said multicolor image data for providing rotated multicolor image data, and changes the number of pixel rows and pixel columns of said multicolor image data such that, from a defined referenced viewpoint, said rotated multicolor image data includes having an $(i-1)$ -by- $(j-1)$ pixel matrix said pattern.]

[29. The computer useable medium of claim 28, further comprising program code for generating an additional row and column of image data.]

[30. The computer useable medium of claim 28, further comprising program code for correcting defects within the image data caused by defects within the image sensor.]

[31. The computer useable medium of claim 28, wherein the image sensor comprises a top, a right side and a left side, wherein the image comprises a "top portion," and wherein the program code for performing the step of identifying an orientation further comprises program code for:

identifying a portrait_left orientation, if the left side of the image sensor corresponds to the "top portion" of the object;

identifying a portrait_right orientation, if the right side of the image sensor corresponds to the "top portion" of the object; and

identifying a landscape orientation, if the top of the image sensor corresponds to the "top portion" of the object.]

[32. The computer useable medium of claim 28, wherein the orientation is a portrait_left orientation, wherein the image data is comprised of an array of pixel colors ordered in rows and columns, and wherein the program code for performing the step of selectively transferring comprises program code for:

initializing a column variable to a first column of pixel colors required by the image processing unit;

initializing a row variable to a row containing a first pixel color required by the image processing unit;

transferring pixel color at an array location, defined by the row variable and the column variable, to the image processing unit;

decrementing the row variable to a row containing a next pixel color required by the image processing unit;

returning to the transferring step, if a row containing a last pixel color has not been transferred;

incrementing the column variable to a next column of pixel colors required by the image processing unit; and

returning to the initializing a row variable step, if a last column of pixel colors has not been transferred.]

[33. The computer useable medium of claim 28, wherein the orientation is a portrait_right orientation, wherein the image data is comprised of an array of pixel colors ordered in rows and columns, and wherein the program code for performing the step of selectively transferring comprises program code for:

initializing a column variable to a first column of pixel colors required by the image processing unit;

initializing a row variable to a row containing a first pixel color required by the image processing unit;

transferring pixel color at an array location, defined by the row variable and the column variable, to the image processing unit;

incrementing the row variable to a row containing a next pixel color required by the image processing unit;

returning to the transferring step, if a row containing a last pixel color has not been transferred;

decrementing the column variable to a next column of pixel colors required by the image processing unit; and

returning to the initializing a row variable step, if a last column of pixel colors has not been transferred.]

[34. The computer useable medium of claim 28, wherein the orientation is a landscape orientation, wherein the image data is comprised of an array of pixel colors ordered in rows and columns, and wherein the program code for performing the step of selectively transferring comprises program code for:

initializing a row variable to a first row of pixel colors required by the image processing unit;

initializing a column variable to a column containing a first pixel color required by the image processing unit;

transferring pixel color at an array location, defined by the row variable and the column variable, to the image processing unit;

incrementing the column variable to a column containing a next pixel color required by the image processing unit;

returning to the transferring step, if a column containing a last color pixel has not been transferred;

incrementing the row variable to a next row of pixel colors required by the image processing unit; and

returning to the initializing a column variable step, if a last row of pixel colors has not been transferred.]

[35. An apparatus for rotating a display orientation of multicolor captured image data having an i -by- j pixel matrix with a pattern representative of an object, comprising:

an image sensor, for generating said multicolor captured image data;

an orientation sensor coupled to said image sensor, for generating a signal corresponding to the position of said image sensor relative to said object; and

a hardware device, having an auto-rotate unit comprising circuits for selectively transforming said multicolor captured image data into rotated multicolor image data in response to said position signal, said hardware device coupled to said image sensor and to said orientation sensor;

wherein, from a defined referenced viewpoint, said rotated multicolor image data includes an $(i-1)$ -by- $(j-1)$ pixel matrix having said pattern.]

36. A method for rotating image data in a digital image capture device, comprising:

capturing image data with an image capture device;

detecting one or more orientations of the image capture device by a plurality of orientation sensors, wherein a first orientation by a first orientation sensor of the plu-

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rality of the orientation sensors indicates whether the
 image capture device is in a landscape or a portrait
 orientation, and a second orientation by a second ori-
 entation sensor of the plurality of the orientation sensors
 indicates whether the image capture device is in a level 5
 or an off-level orientation;
 selecting an orientation from the plurality of orientations
 of the image capture device;
 rotating the captured image data according to the selected 10
 orientation of the image capture device; and
 outputting the rotated image data to a display device in
 accordance with the selected orientation.
 37. A digital camera, comprising:
 an image sensor for capturing an image;
 a plurality of orientation sensors, coupled to the image 15
 sensor, adapted to detect one or more orientations of the
 captured image, wherein a first orientation by a first

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orientation sensor of the plurality of the orientation
 sensors indicates whether the digital camera is in a
 landscape or a portrait orientation, and a second orien-
 tation by a second orientation sensor of the plurality of
 the orientation sensors indicates whether the digital
 camera is in a level or an off-level orientation;
 an auto-rotate unit, coupled to the plurality of orientation
 sensors, for selecting an orientation from the plurality of
 the orientations, and rotating the captured image
 according to the selected orientation;
 a memory, coupled to the auto-rotate unit and the plurality
 of orientation sensors, for storing the rotated image and
 the selected orientation; and
 an image processing unit, coupled to the memory, for out-
 putting the stored rotated image in accordance with the
 selected orientation.

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