



US00RE37975E

(19) **United States**
(12) **Reissued Patent**
Stephenson et al.

(10) **Patent Number:** **US RE37,975 E**
(45) **Date of Reissued Patent:** ***Feb. 4, 2003**

- (54) **DIRECTIONAL BORING HEAD WITH BLADE ASSEMBLY**
- (75) Inventors: **Brent G. Stephenson**, Stillwater, OK (US); **Arthur D. Deken**, Perry, OK (US); **Cody L. Sewell**, Perry, OK (US); **Richard P. Dunn**, Wichita Falls, TX (US)
- (73) Assignee: **The Charles Machine Works, Inc.**, Perry, OK (US)
- (*) Notice: This patent is subject to a terminal disclaimer.
- (21) Appl. No.: **09/671,806**
- (22) Filed: **Sep. 25, 2000**

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Primary Examiner—Frank S. Tsay

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(57) **ABSTRACT**

A directional boring machine equipped with a boring head comprising a blade assembly. The blade assembly may comprise a plurality of blades with deflecting surfaces. Alternately, the blade assembly has a single, stepped or serrated blade. The serrated blade assembly has a planar blade which is tapered in thickness and width from its base to its forward end. The forward end has teeth cut away on the backside to provide a recess or relief space for cuttings during the drilling process. A relief space or slot also is provided between the front two teeth for the same purpose. The blade is divided into two halves, and the halves are offset so that each of the teeth on each half provides a separate cutting point. The blade is angled in an upward direction relative to the base of the blade assembly to improve penetration and cutting actions. The blade assembly in combination with the boring head body provides exceptional cutting performance in a variety of soils and rock.

Related U.S. Patent Documents

Reissue of:

- (64) Patent No.: **5,799,740**
- Issued: **Sep. 1, 1998**
- Appl. No.: **08/398,311**
- Filed: **Feb. 27, 1995**

U.S. Applications:

- (63) Continuation-in-part of application No. 08/163,756, filed on Dec. 9, 1993, now Pat. No. 5,392,868, which is a continuation-in-part of application No. 08/067,298, filed on May 25, 1993, now Pat. No. 5,341,887, which is a continuation-in-part of application No. 07/857,167, filed on Mar. 25, 1992, now Pat. No. 5,242,026, which is a continuation-in-part of application No. 07/575,568, filed on Aug. 31, 1990, now Pat. No. 5,148,880, which is a continuation-in-part of application No. 07/211,889, filed on Jun. 27, 1988, now Pat. No. 4,953,638.

- (51) **Int. Cl.⁷** **E21B 10/00**
- (52) **U.S. Cl.** **175/62; 175/376**
- (58) **Field of Search** 175/61, 62, 67, 175/376, 161, 73, 397, 398, 400

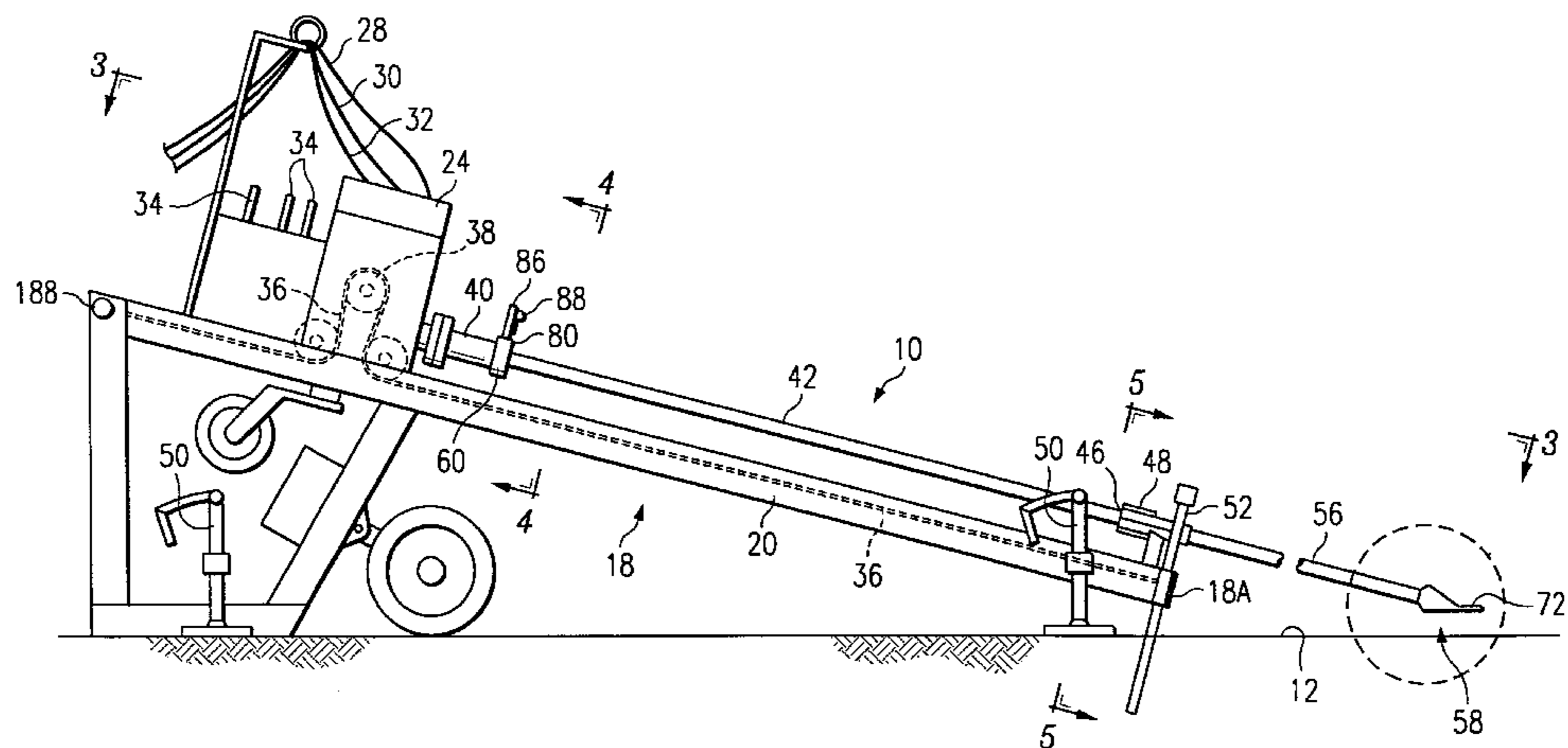
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112 Claims, 24 Drawing Sheets



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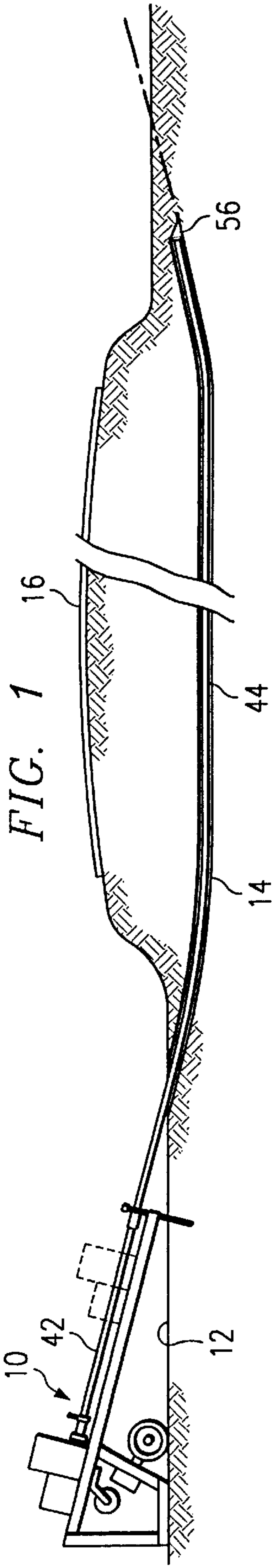


FIG. 1

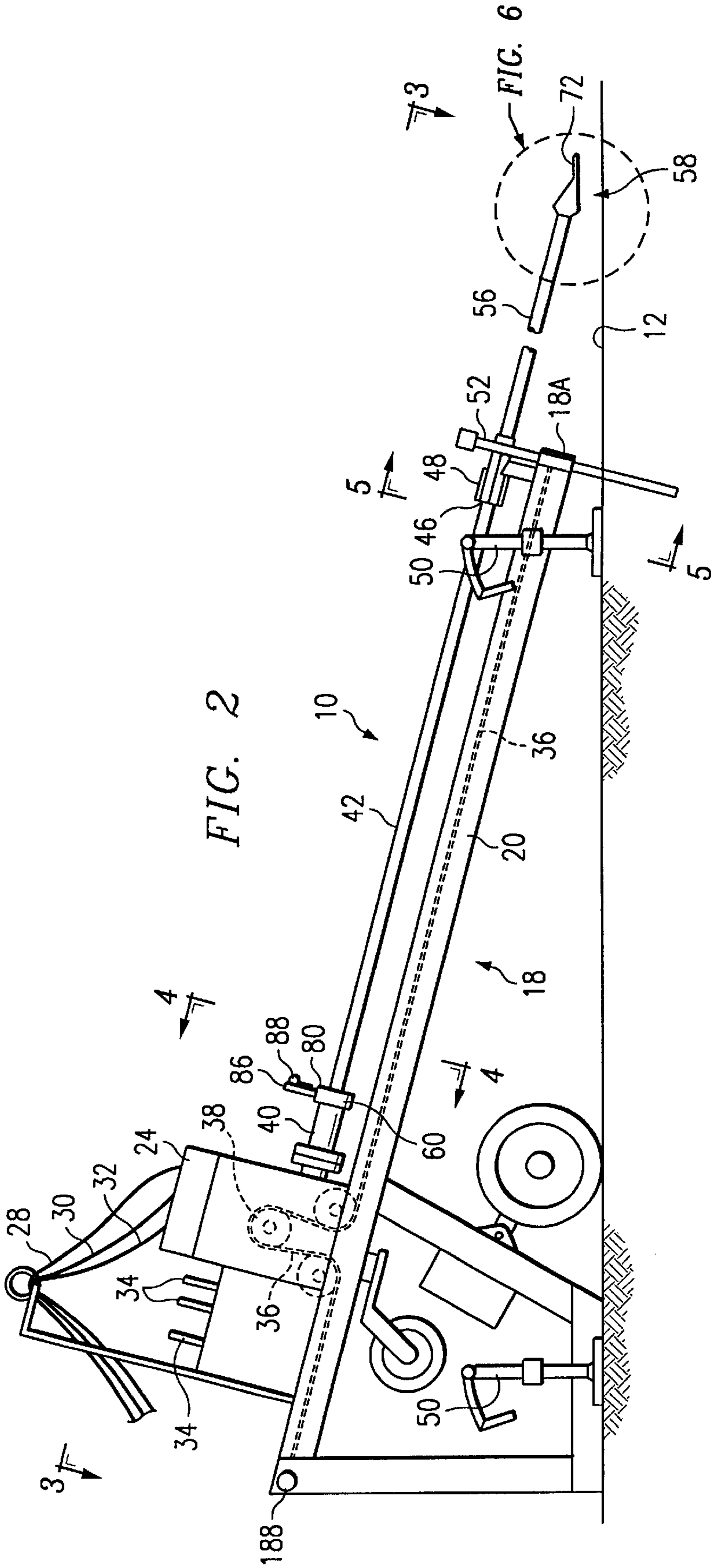
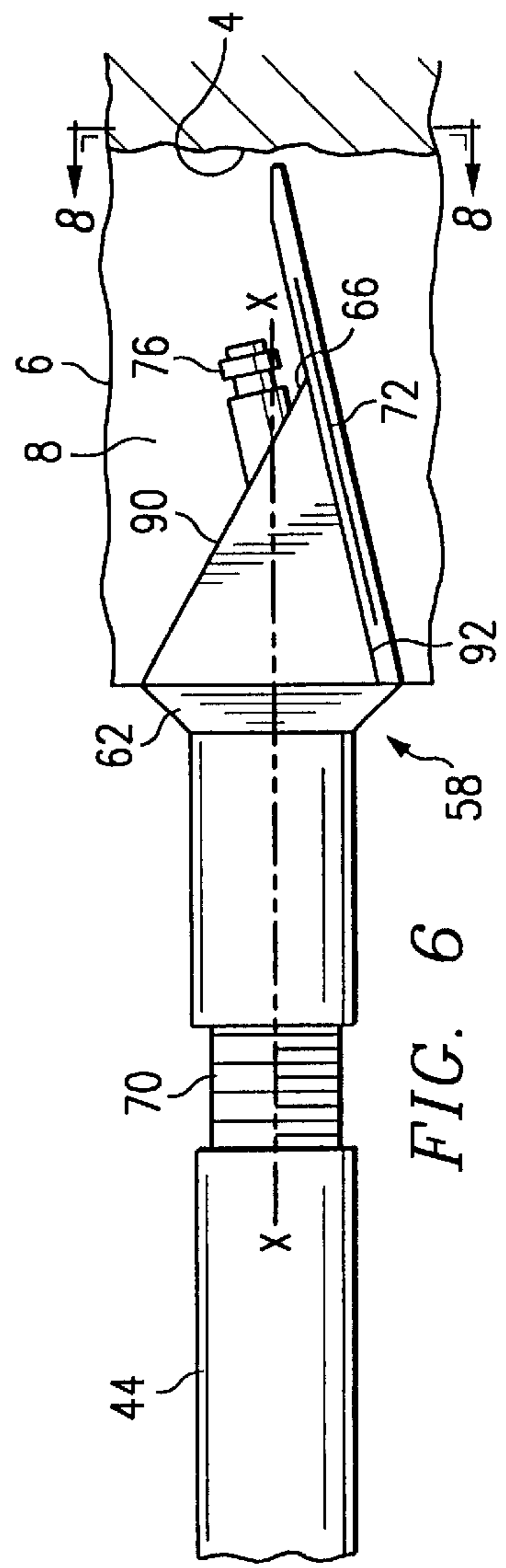
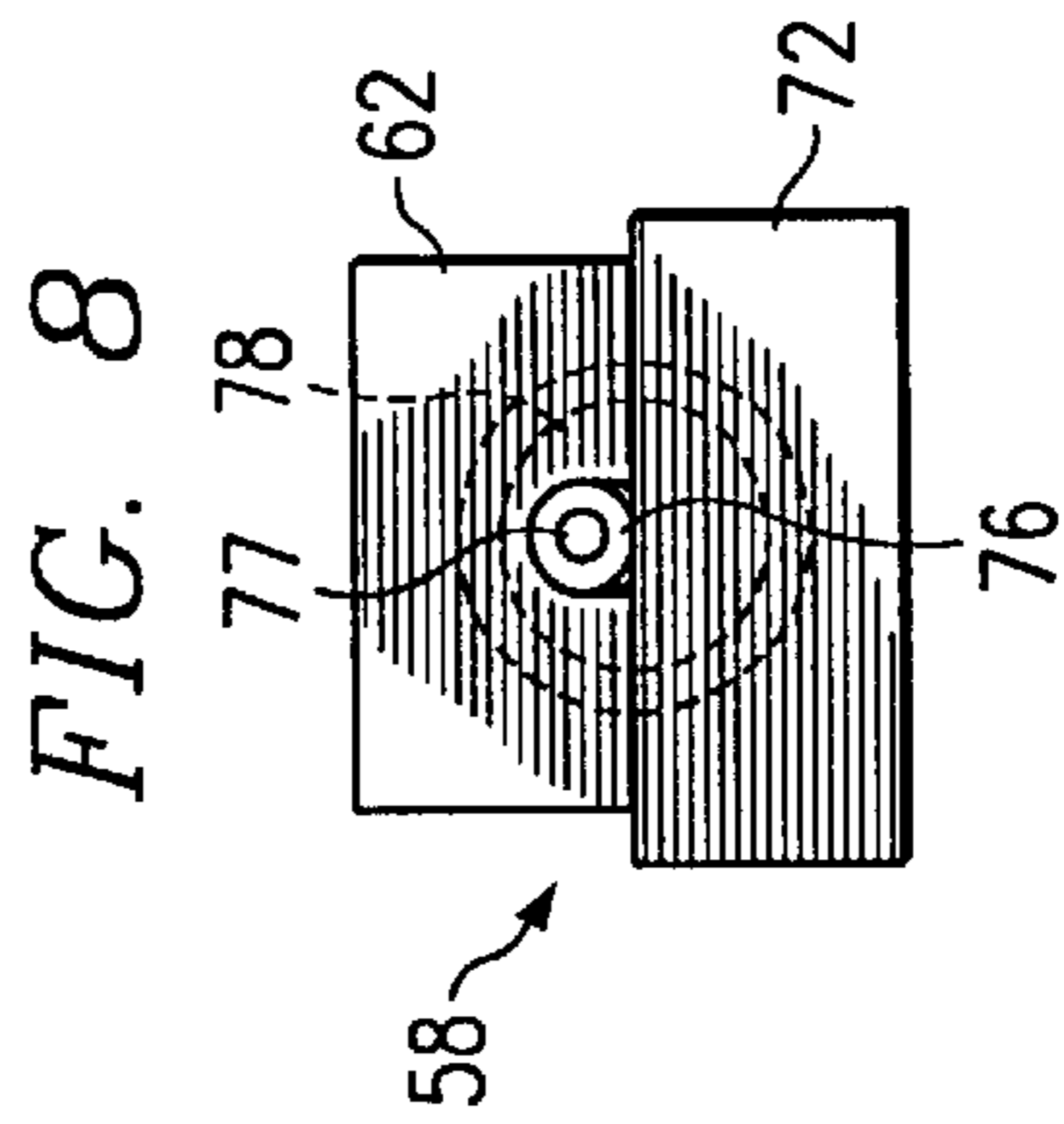
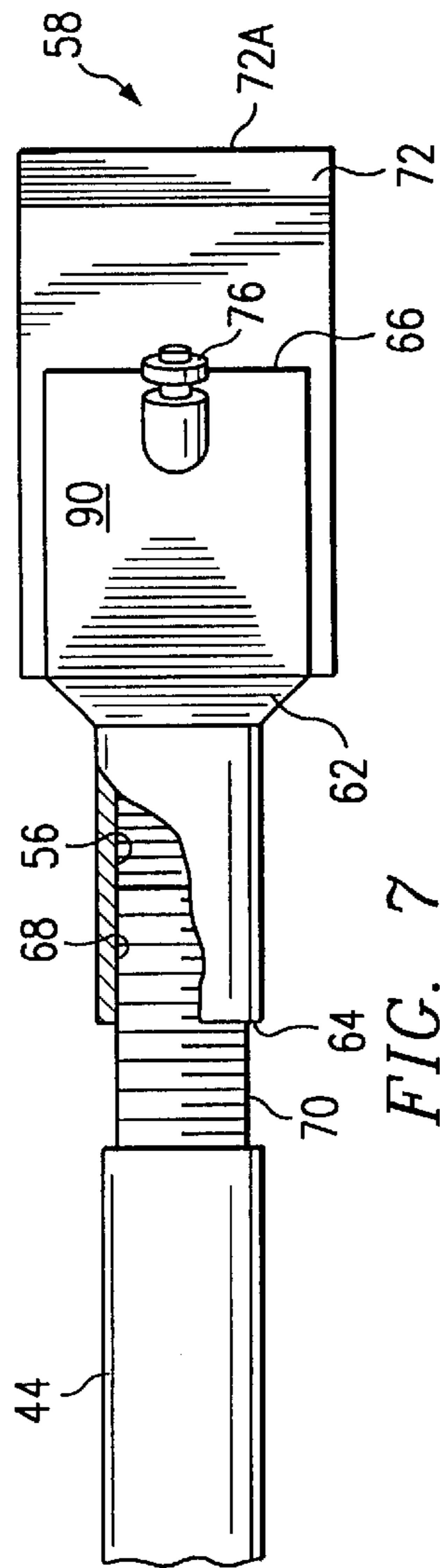
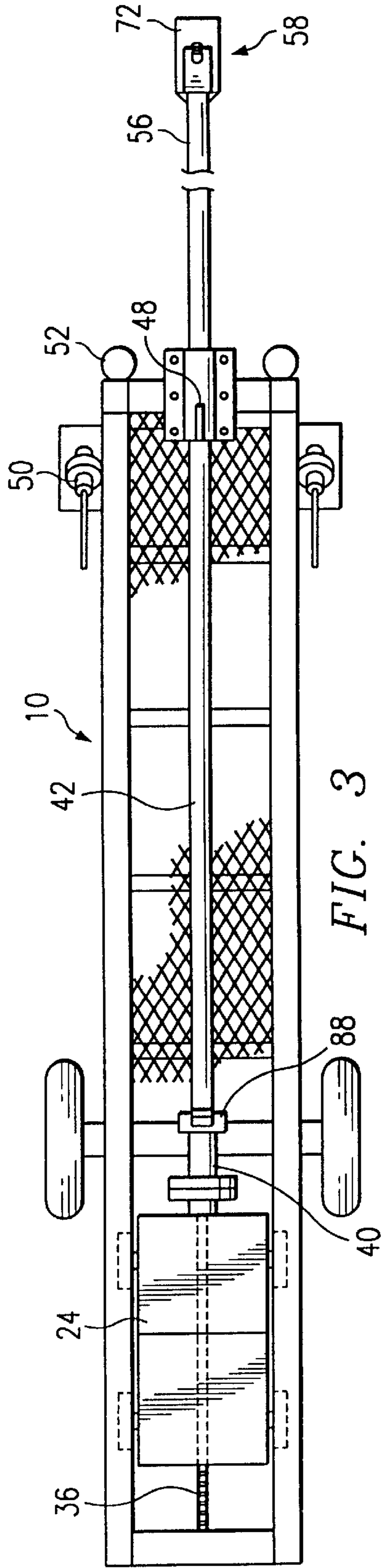
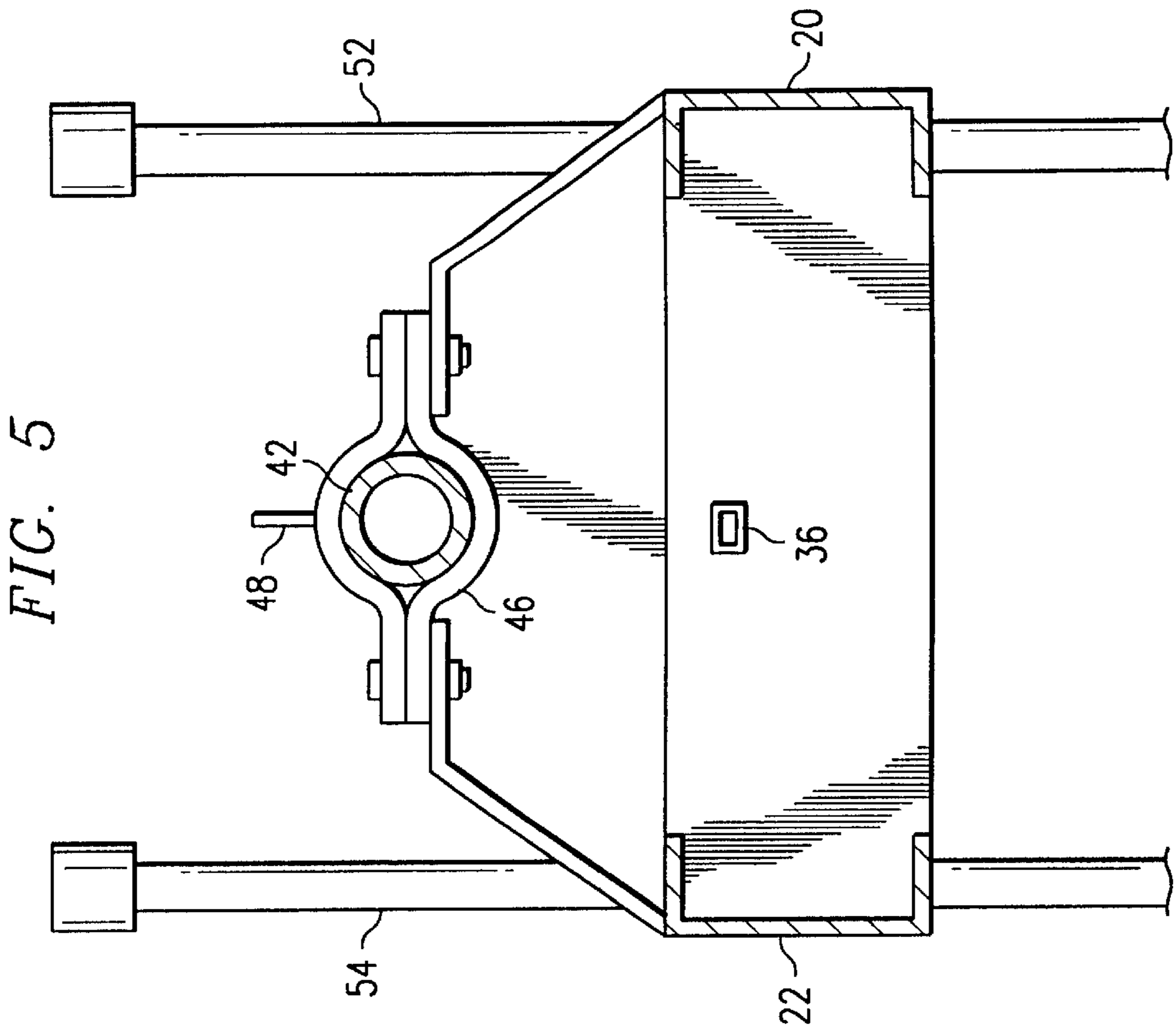
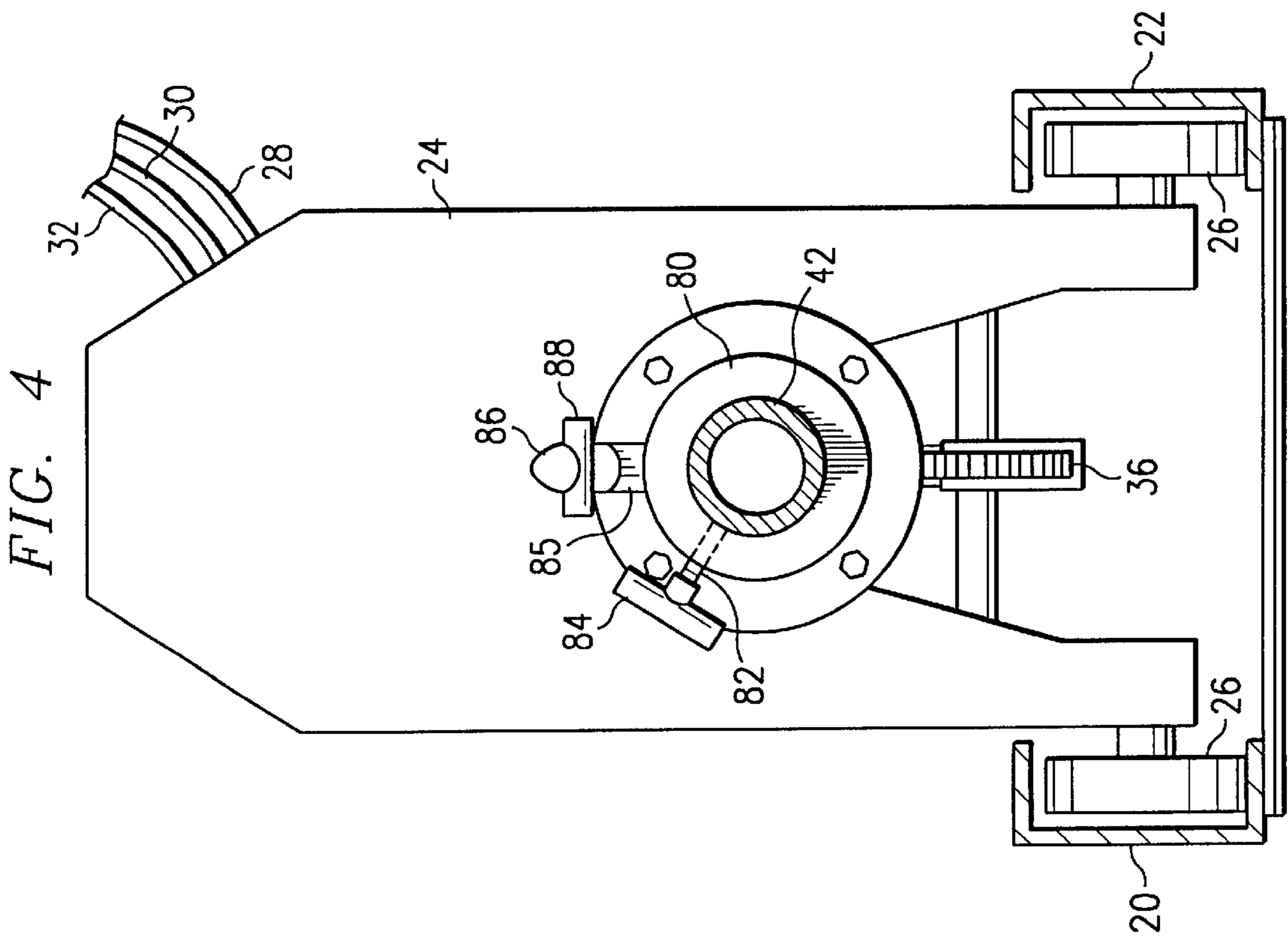
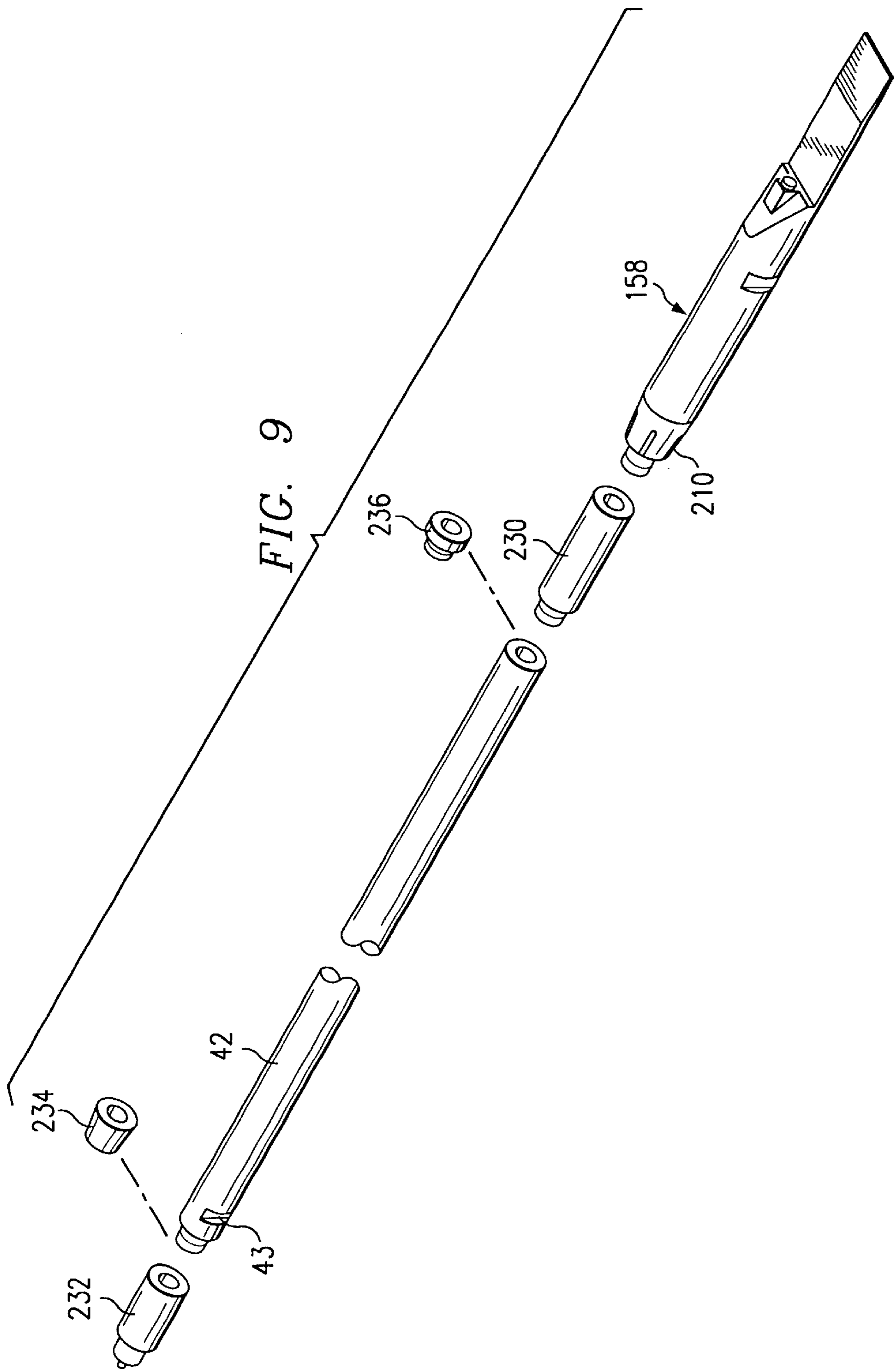


FIG. 2







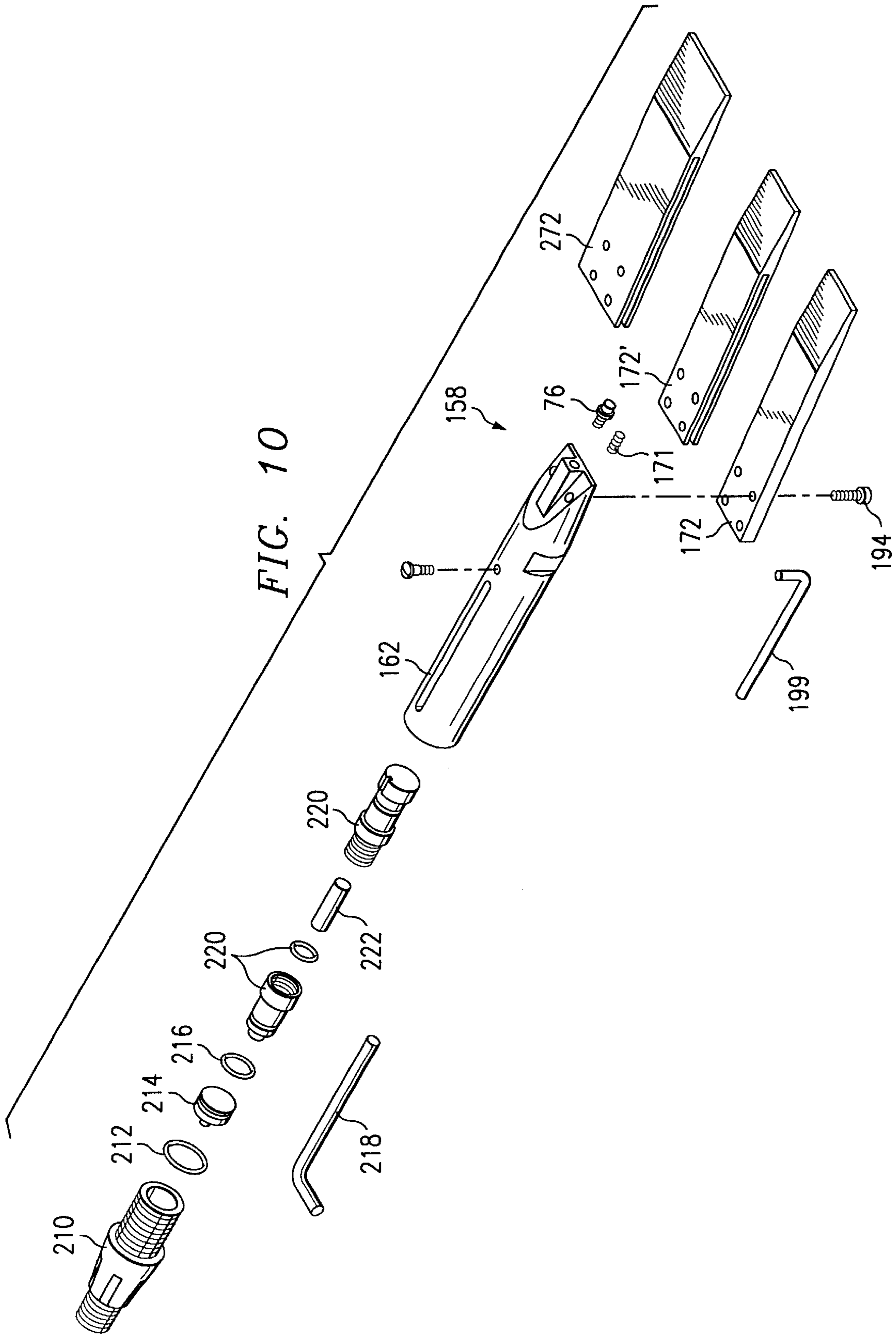


FIG. 10

FIG. 11

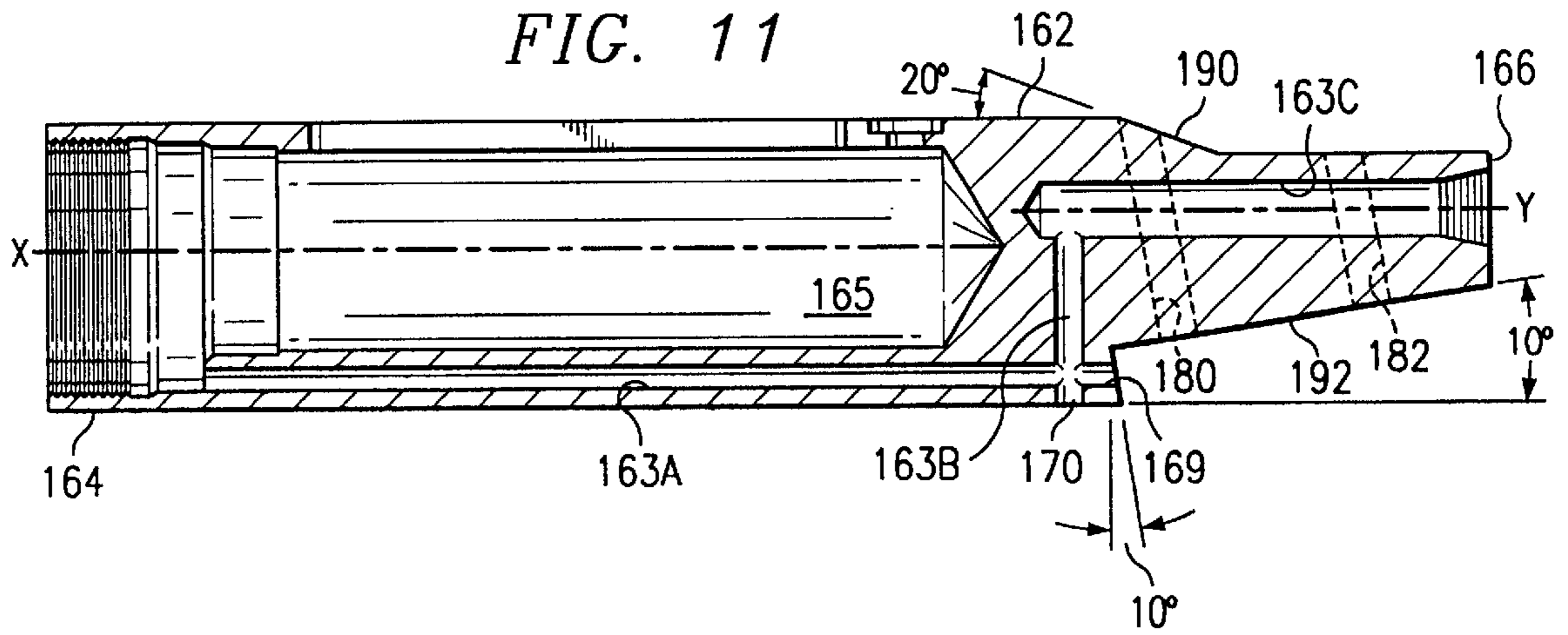


FIG. 12

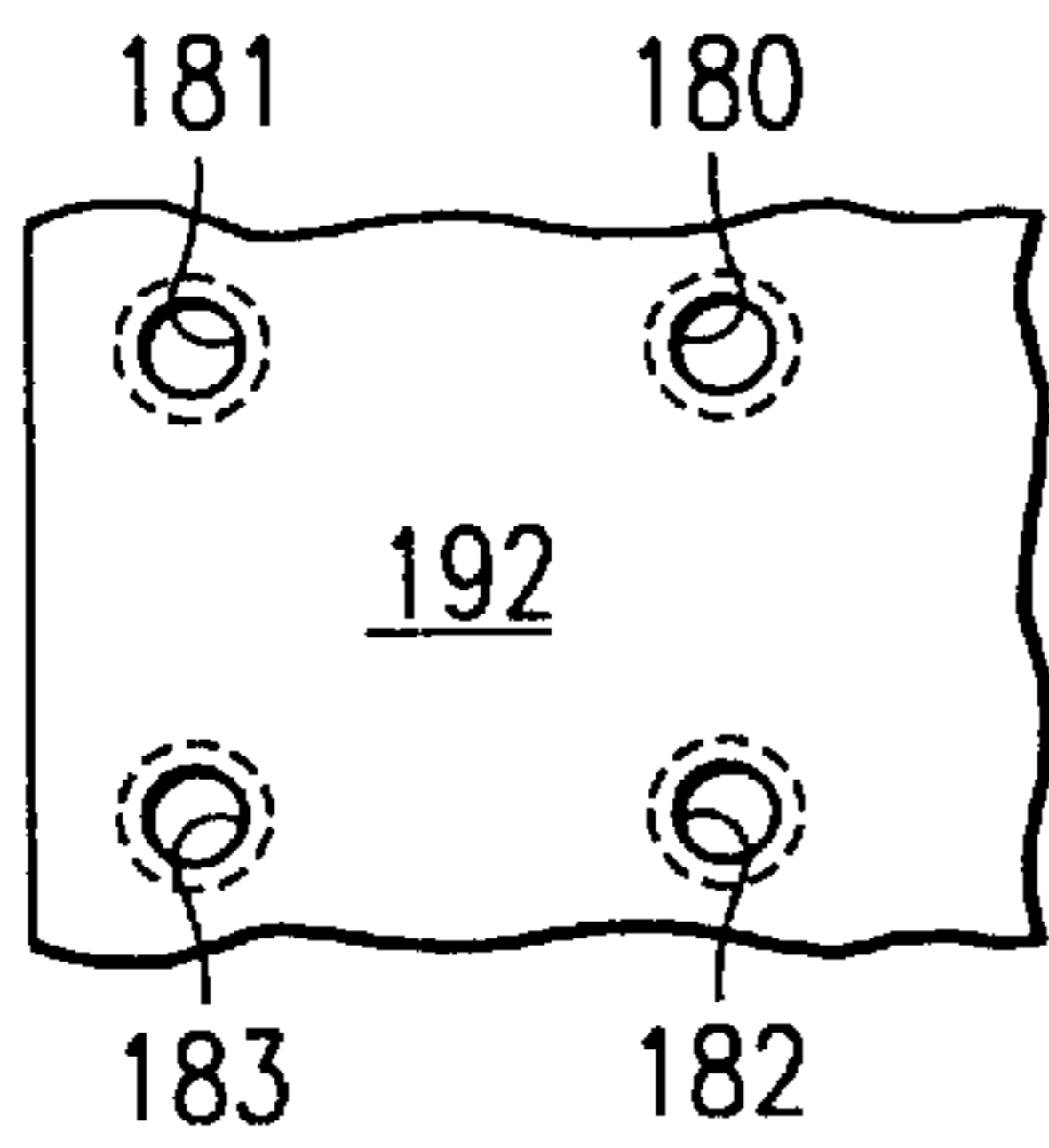


FIG. 13

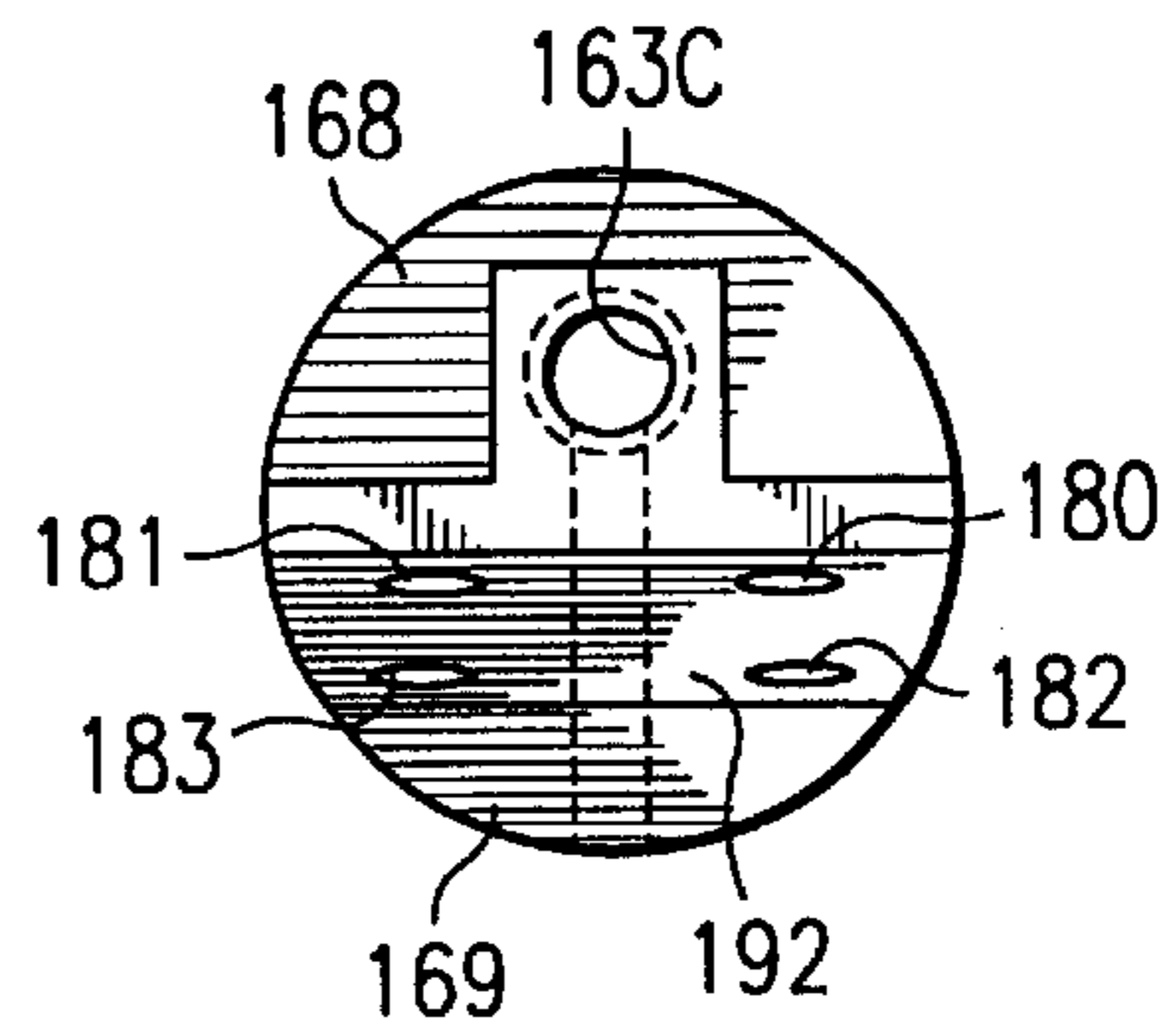
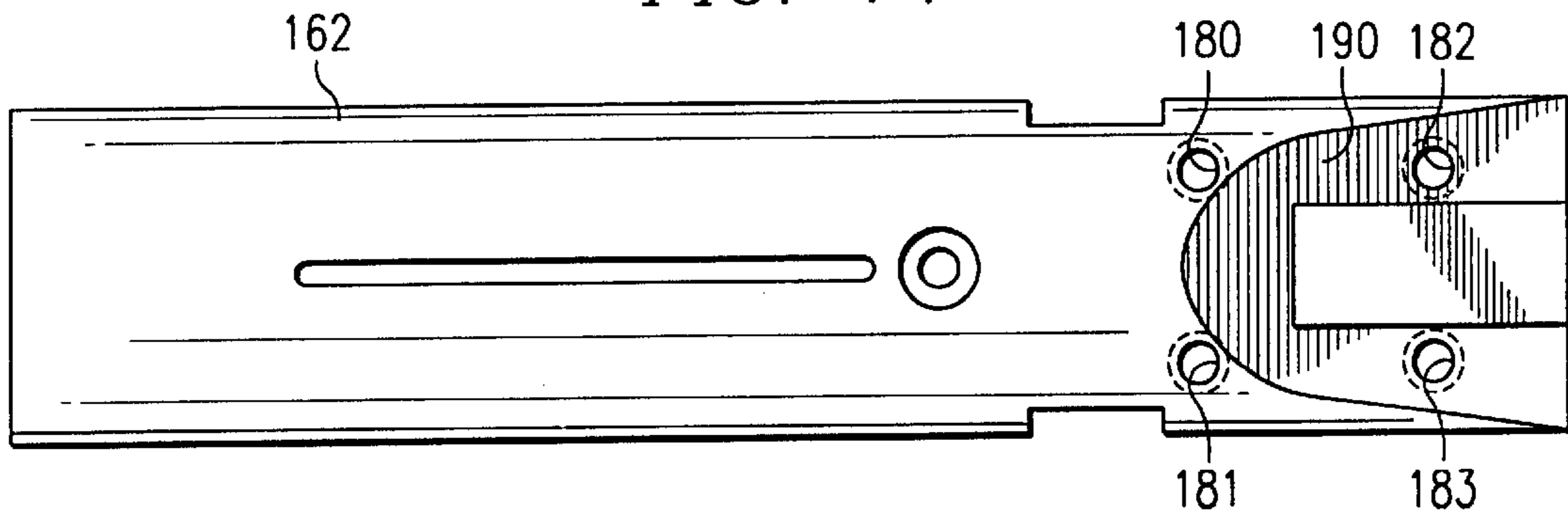
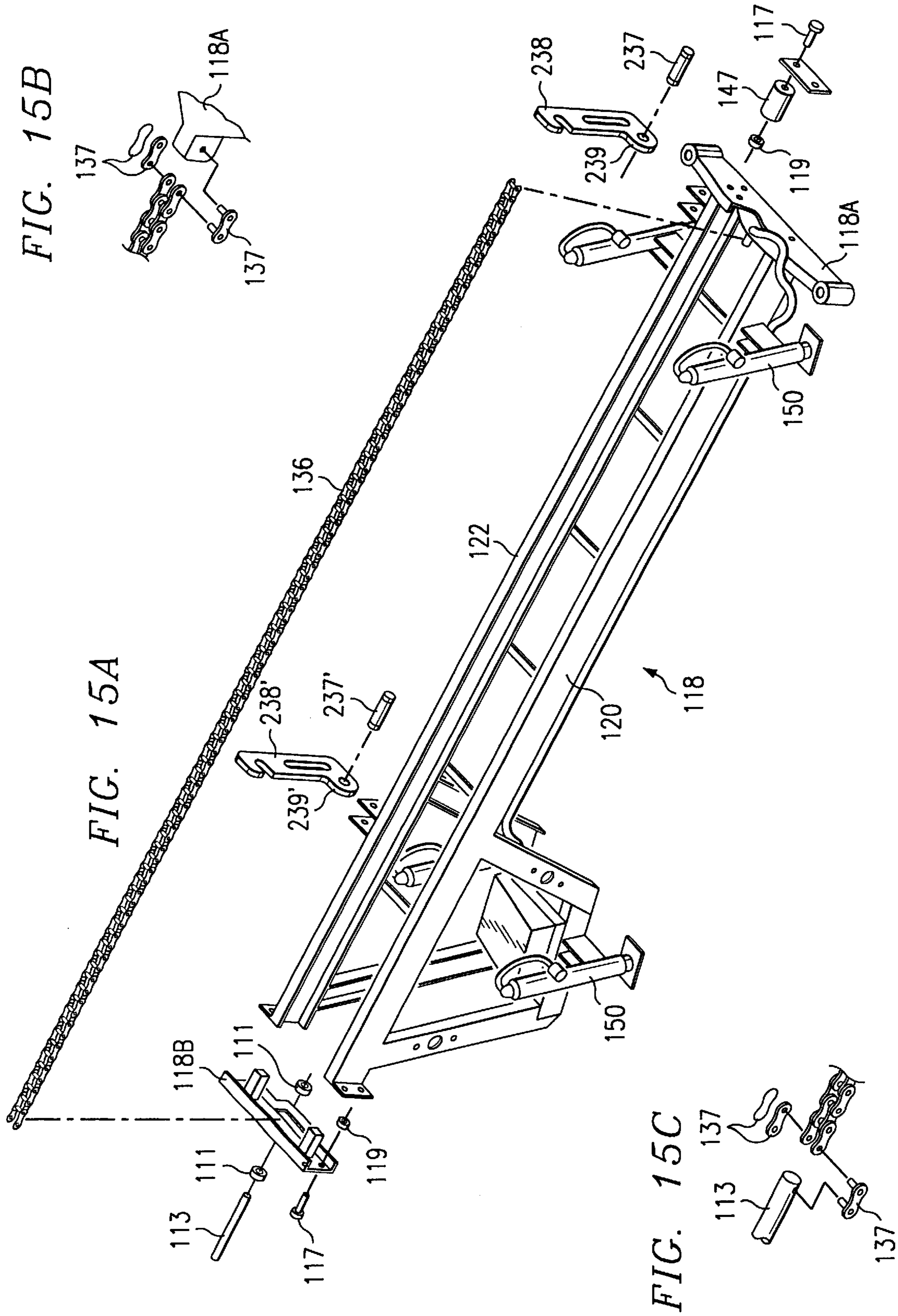


FIG. 14





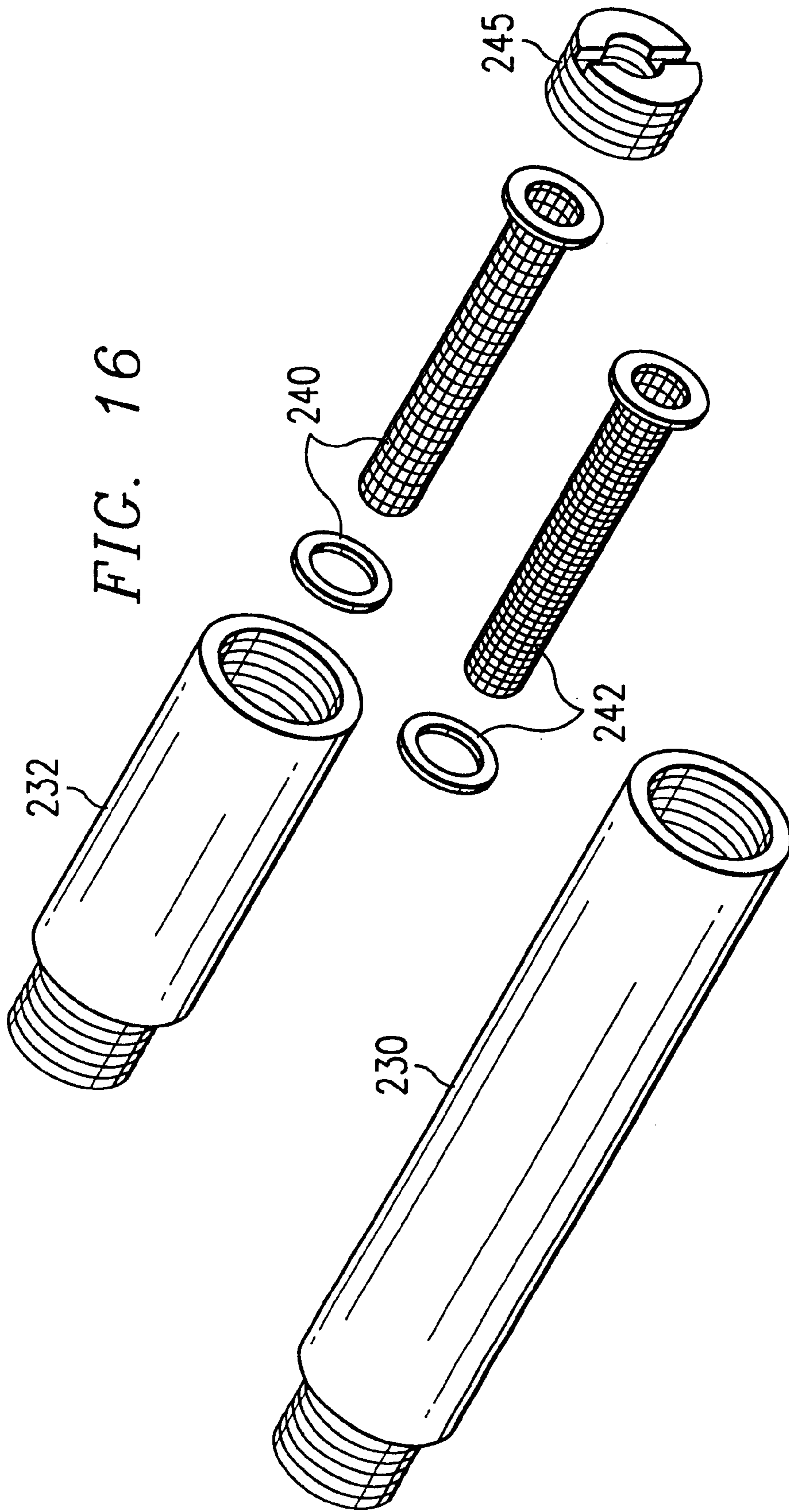


FIG. 17

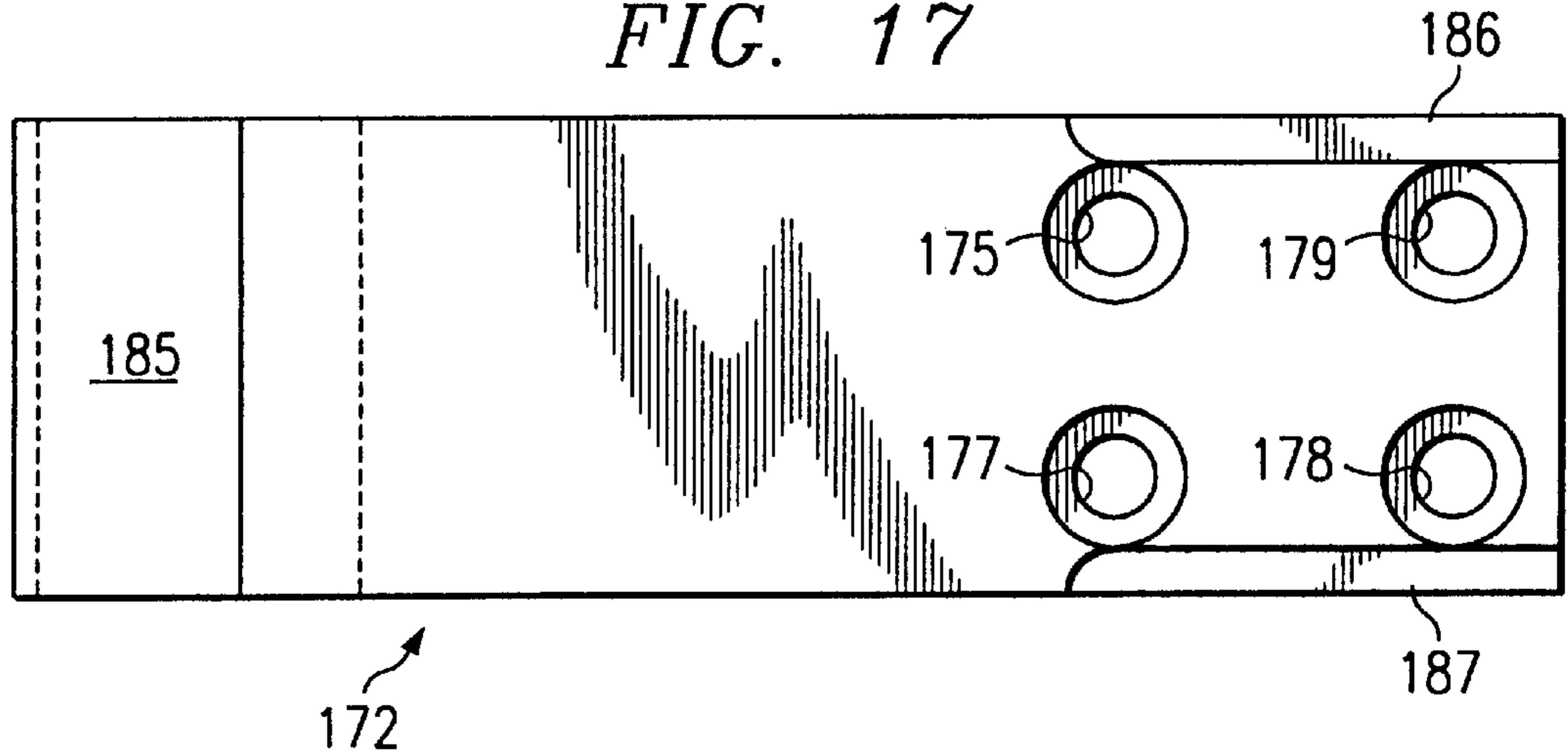


FIG. 18

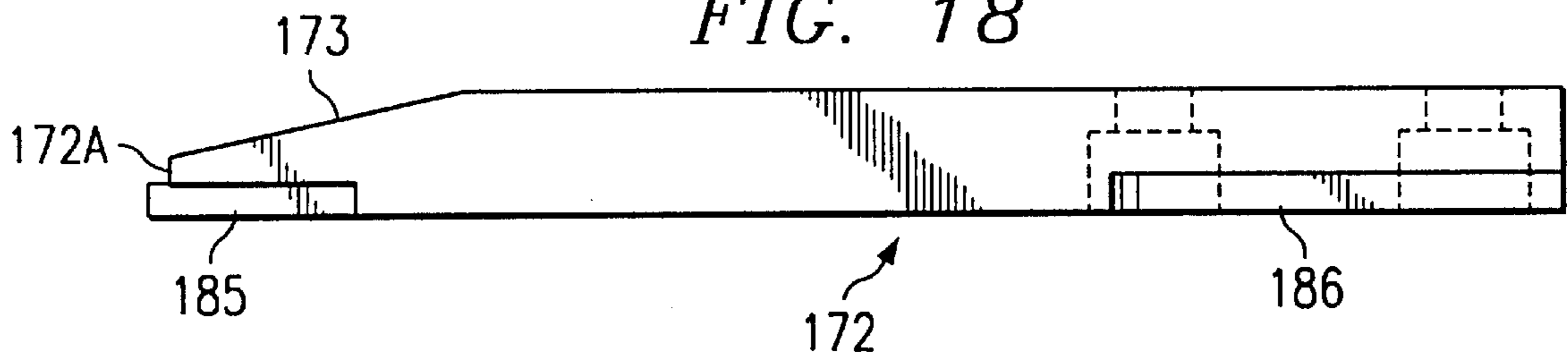


FIG. 19

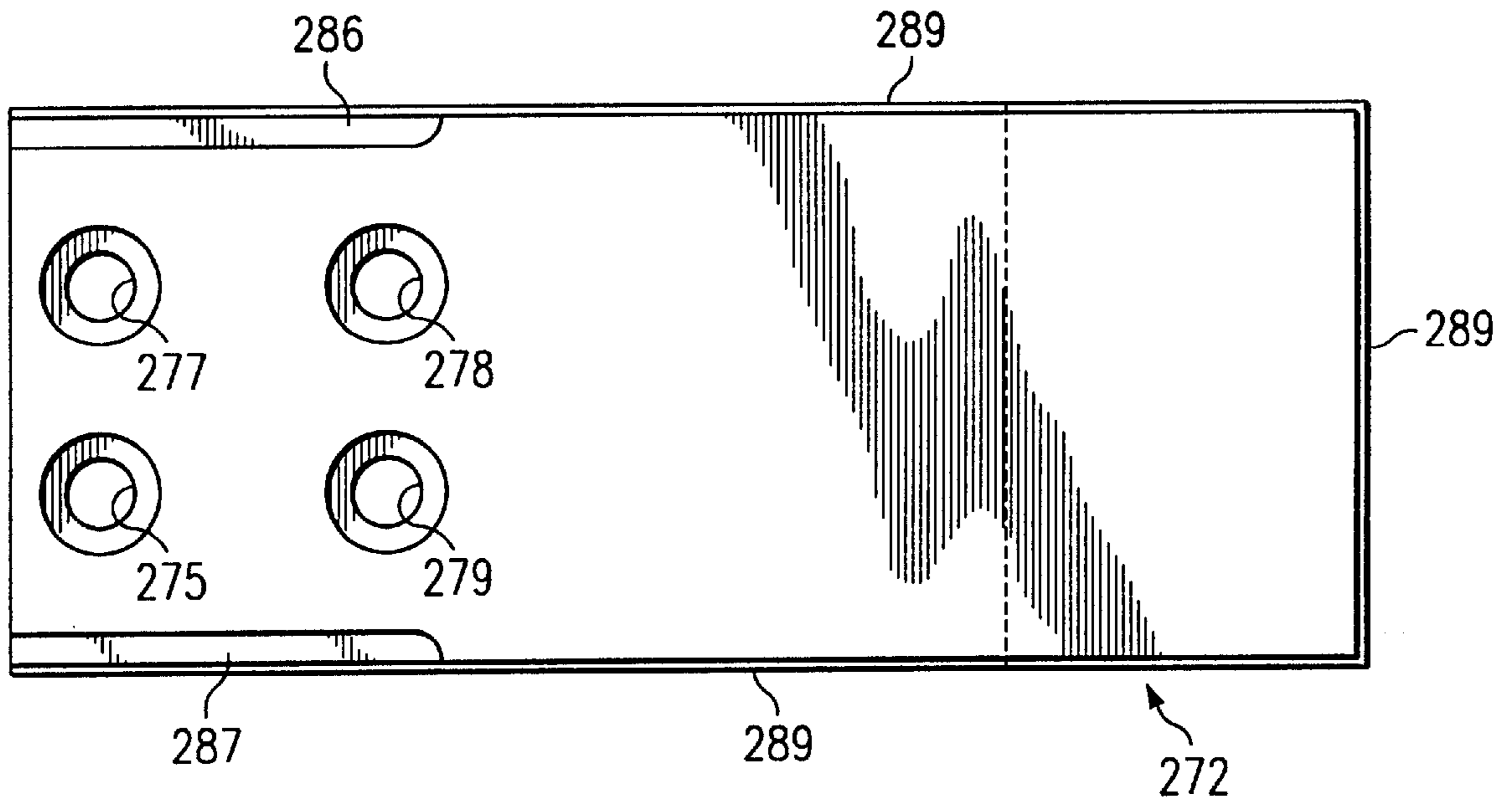


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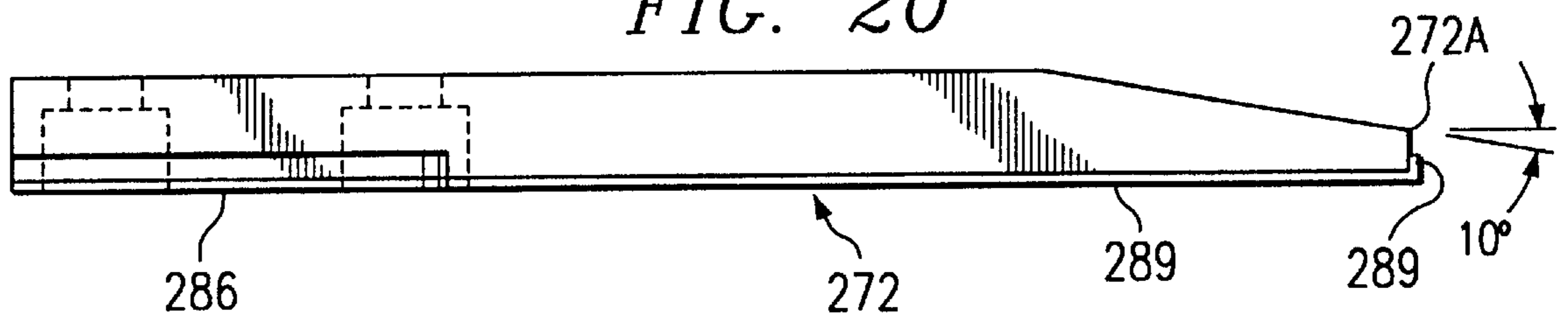


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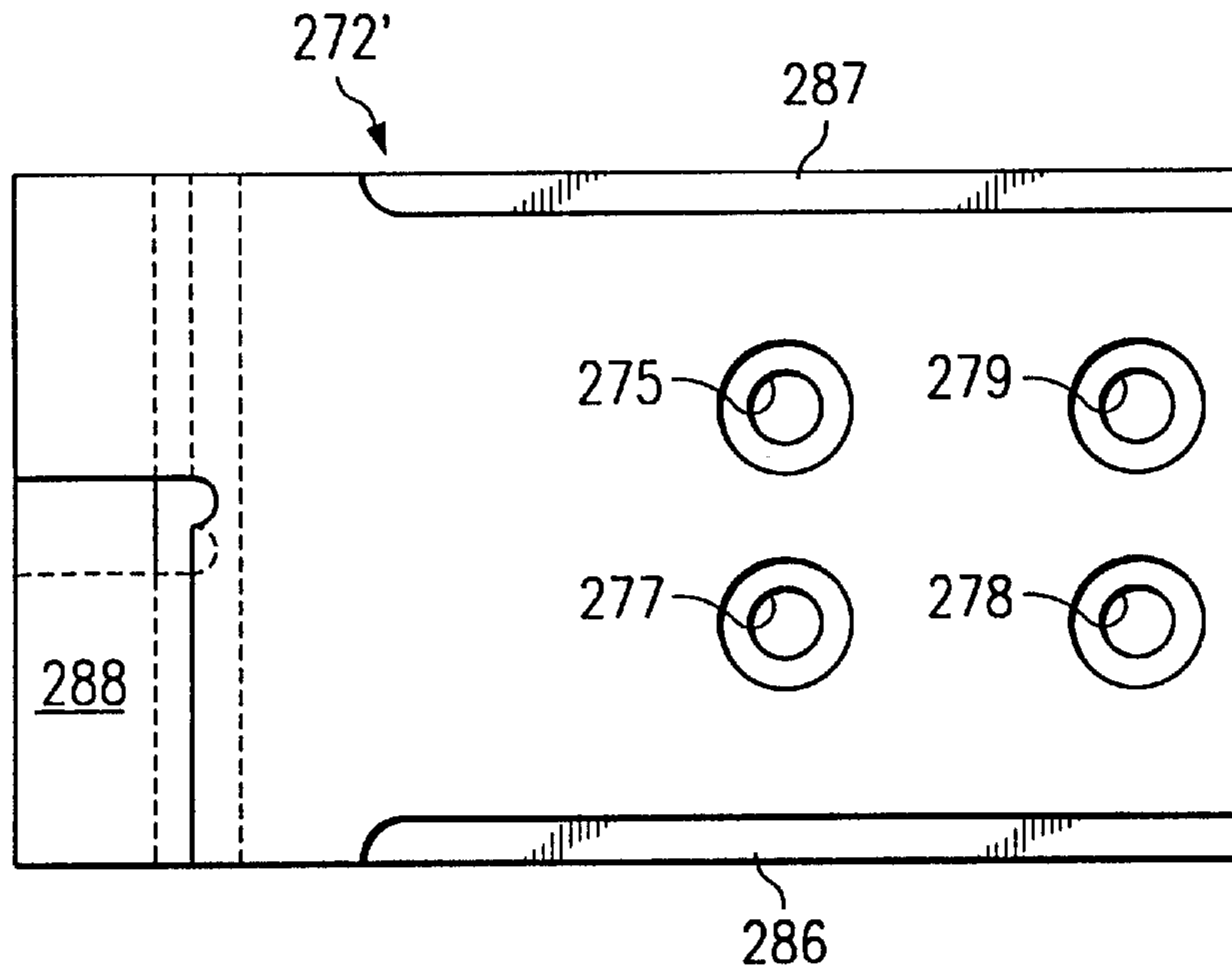


FIG. 22

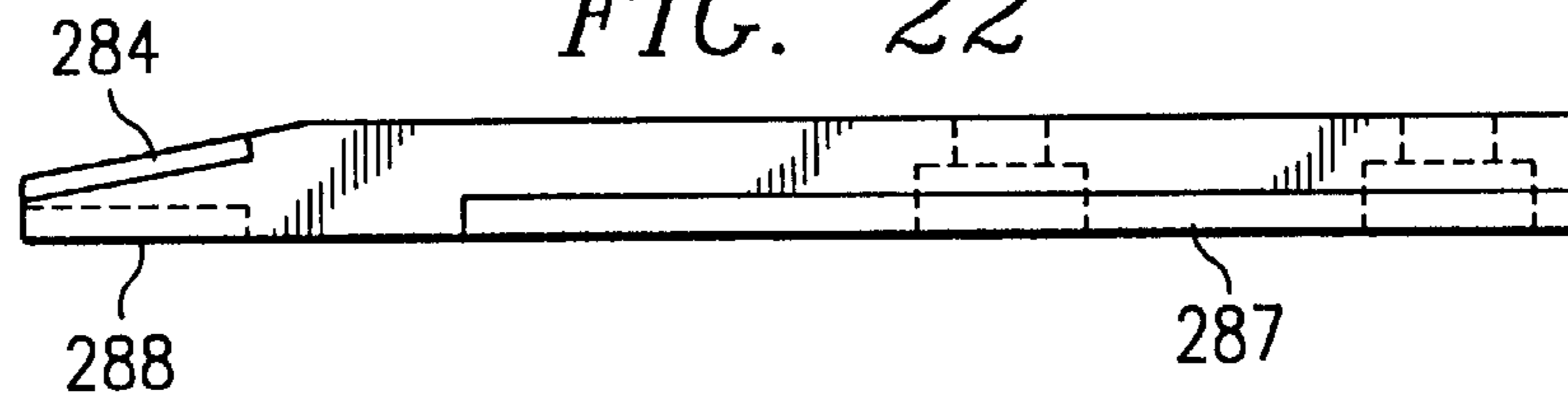


FIG. 27A

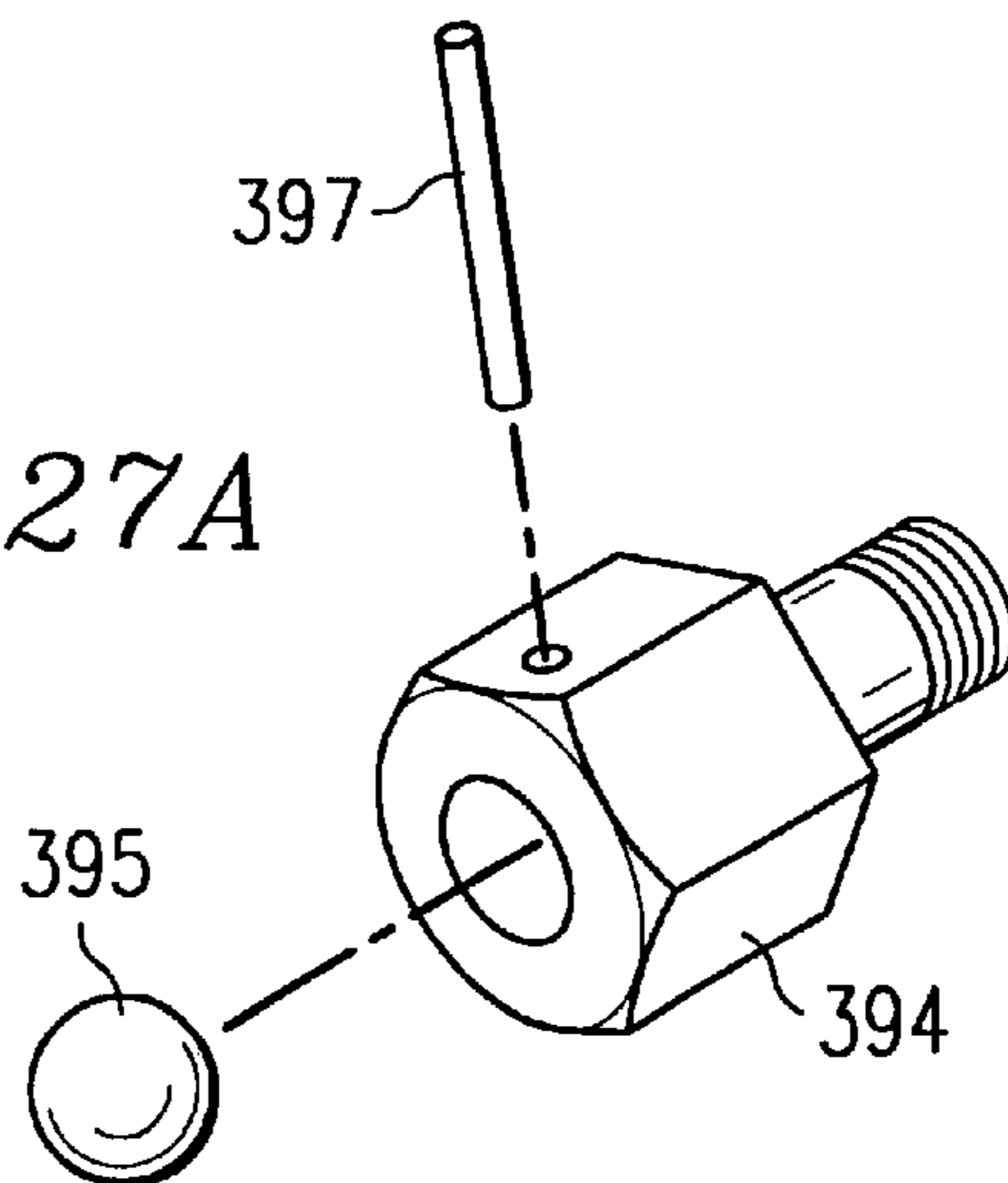


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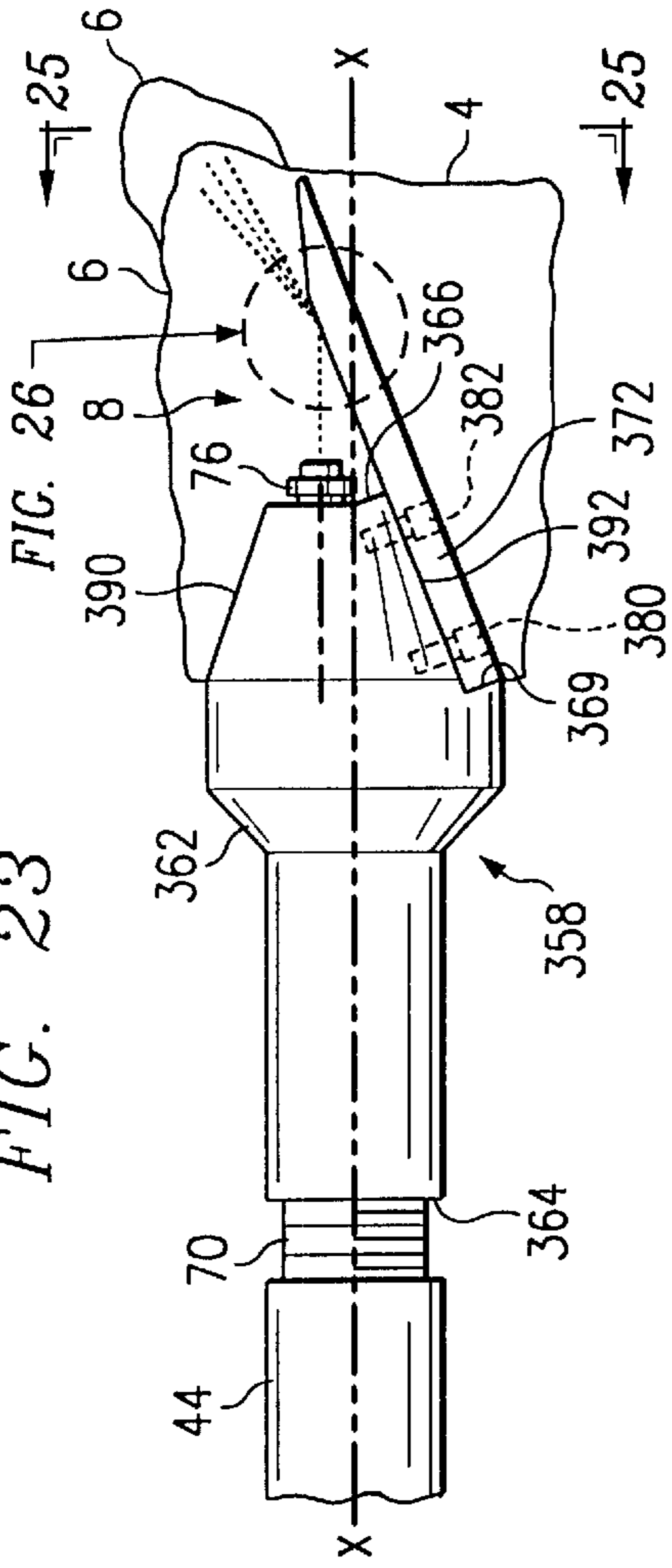


FIG. 28

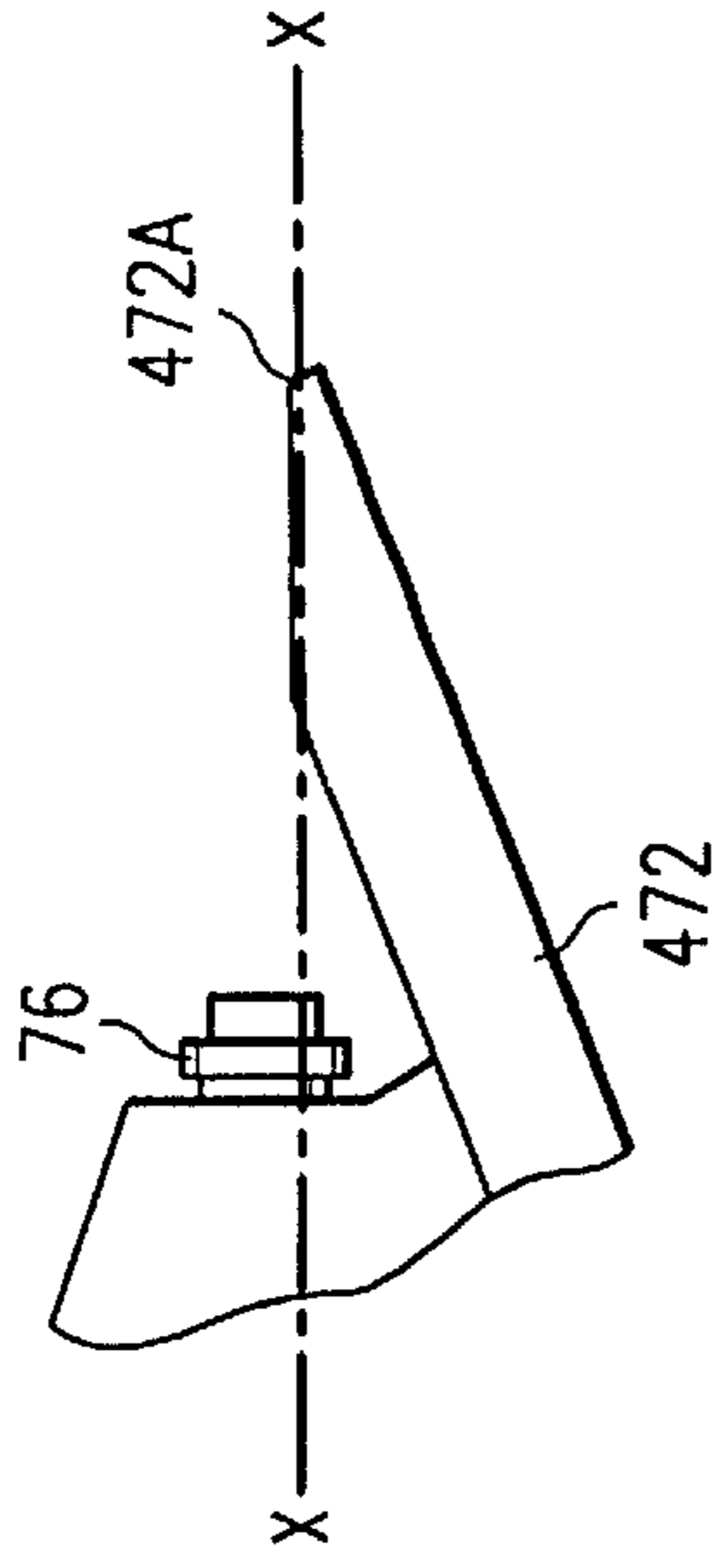


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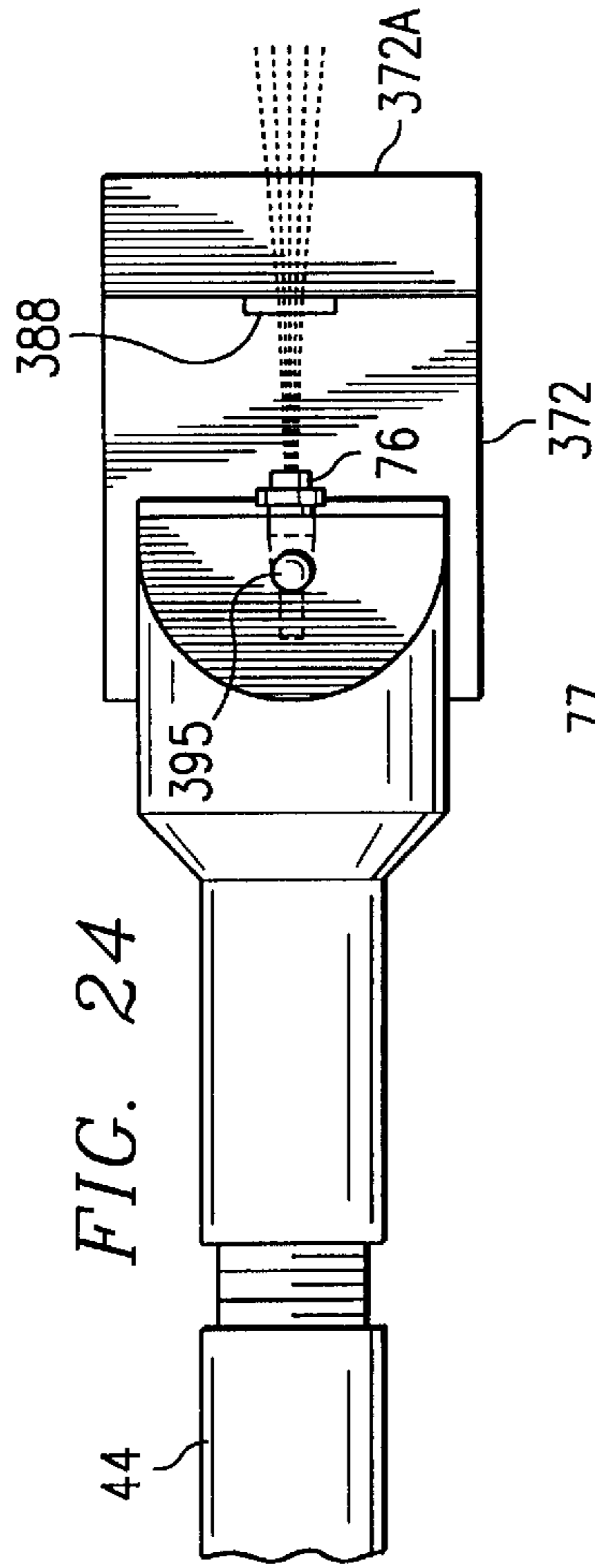


FIG. 26

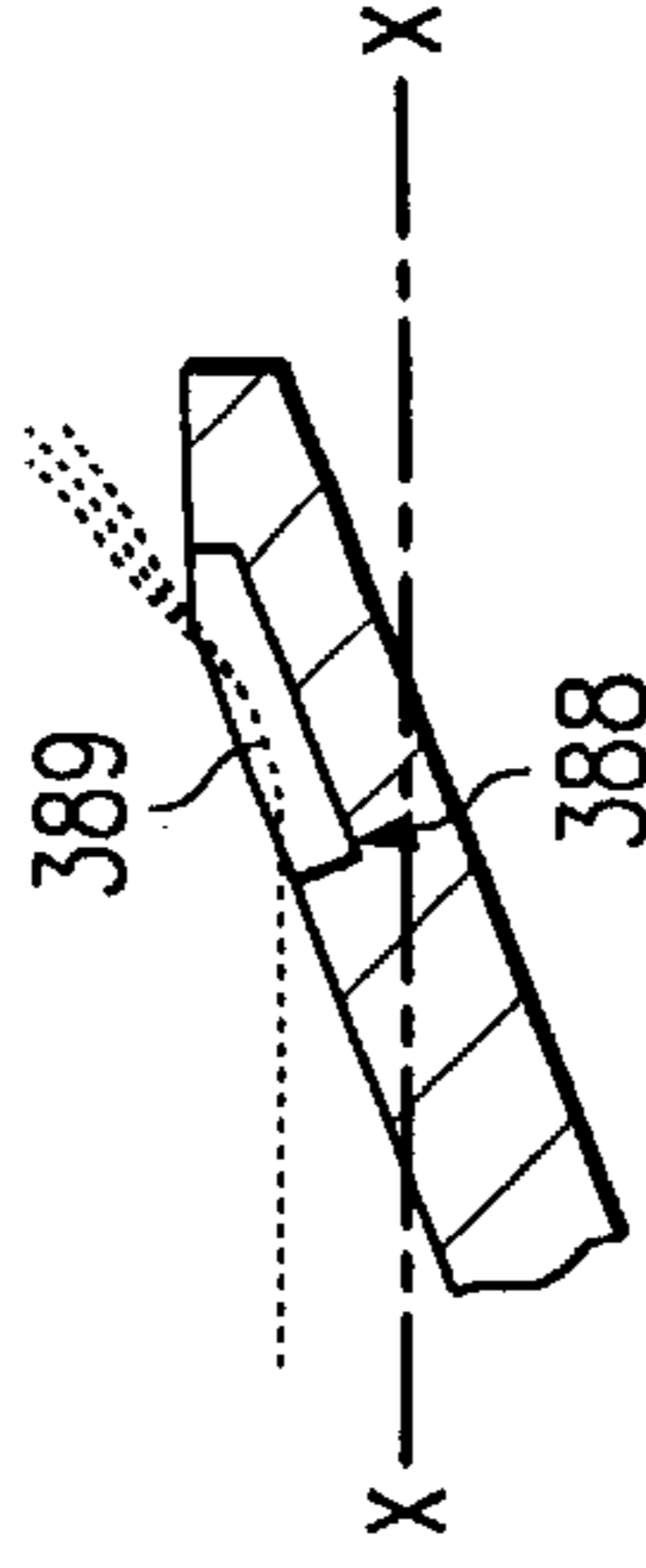


FIG. 27

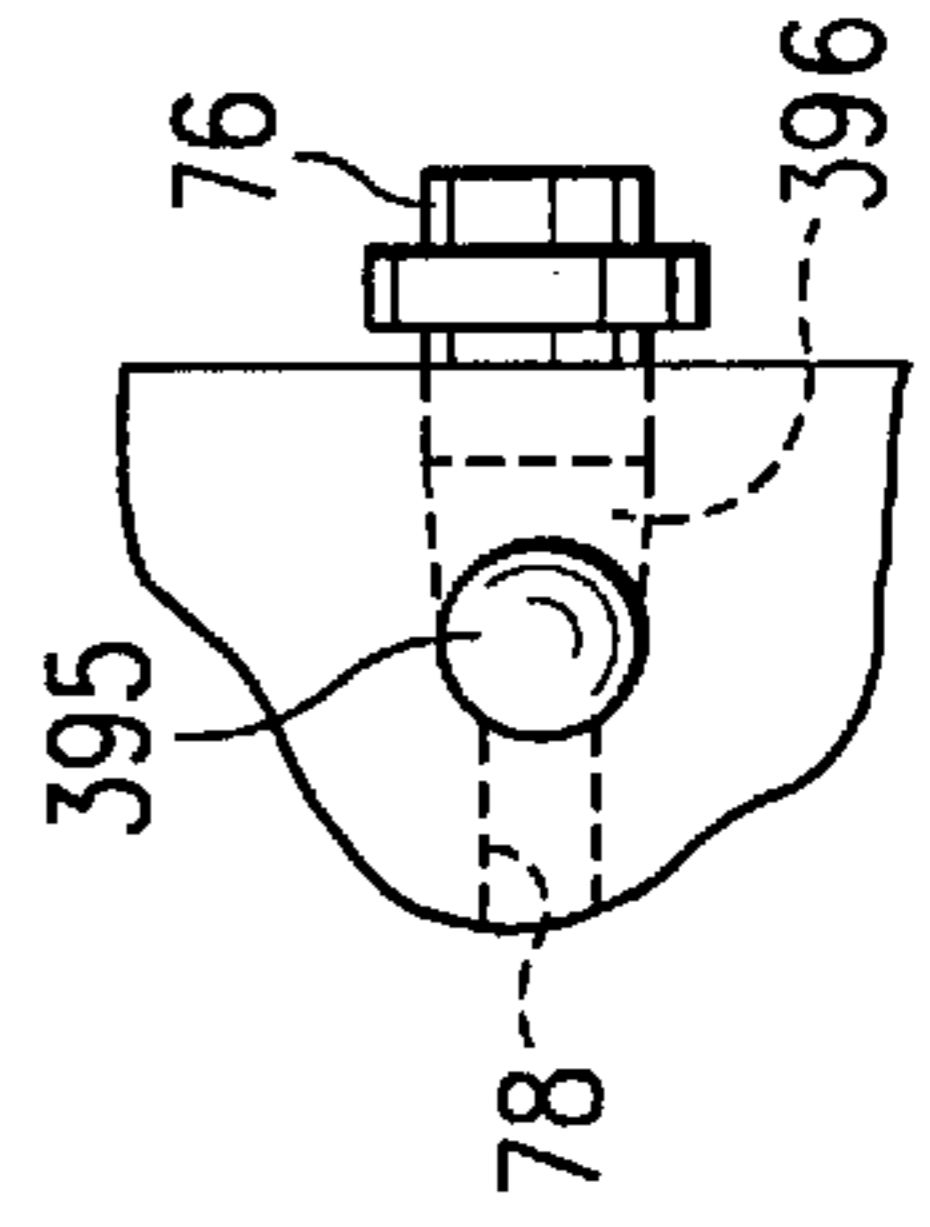


FIG. 25

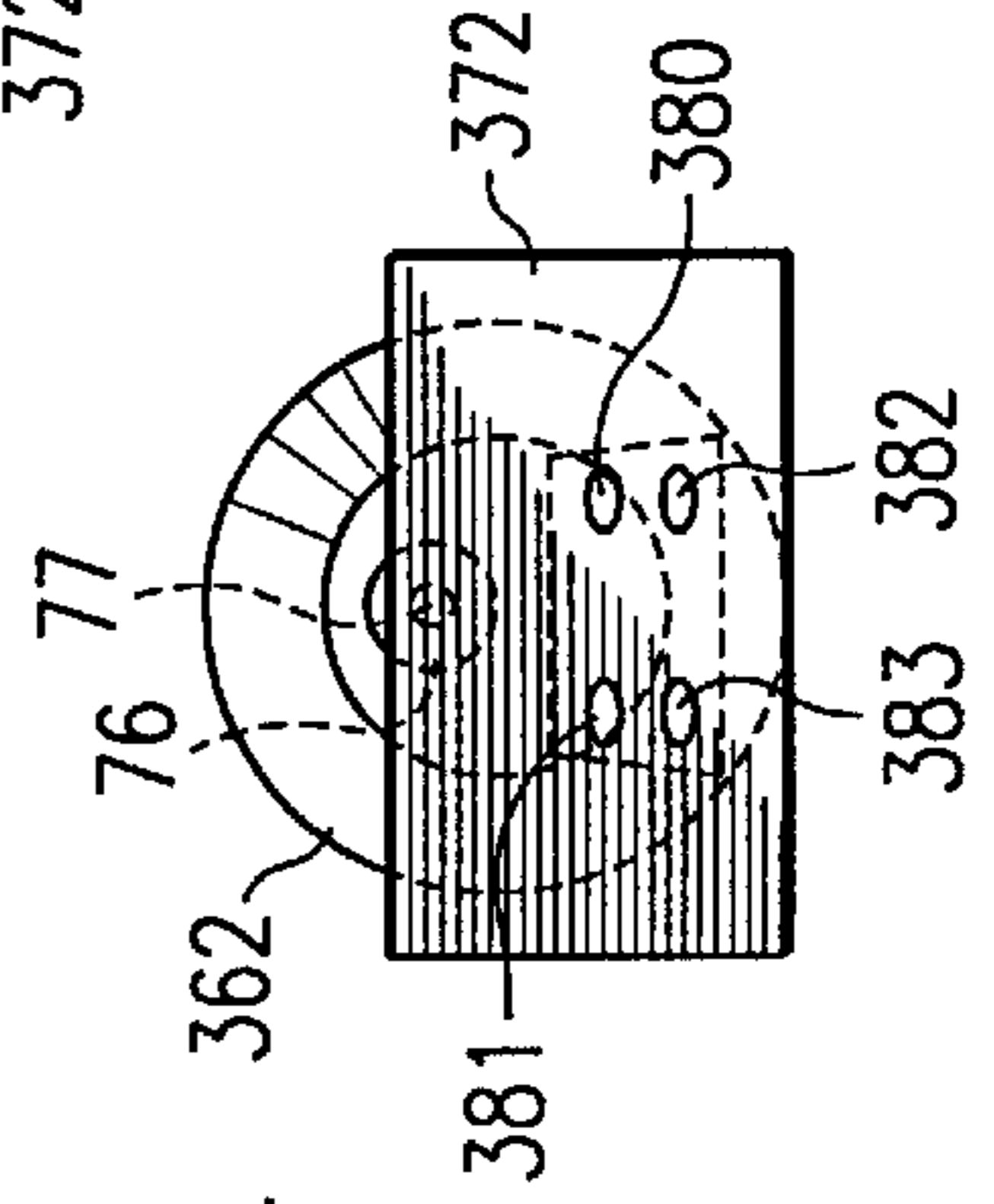


FIG. 29

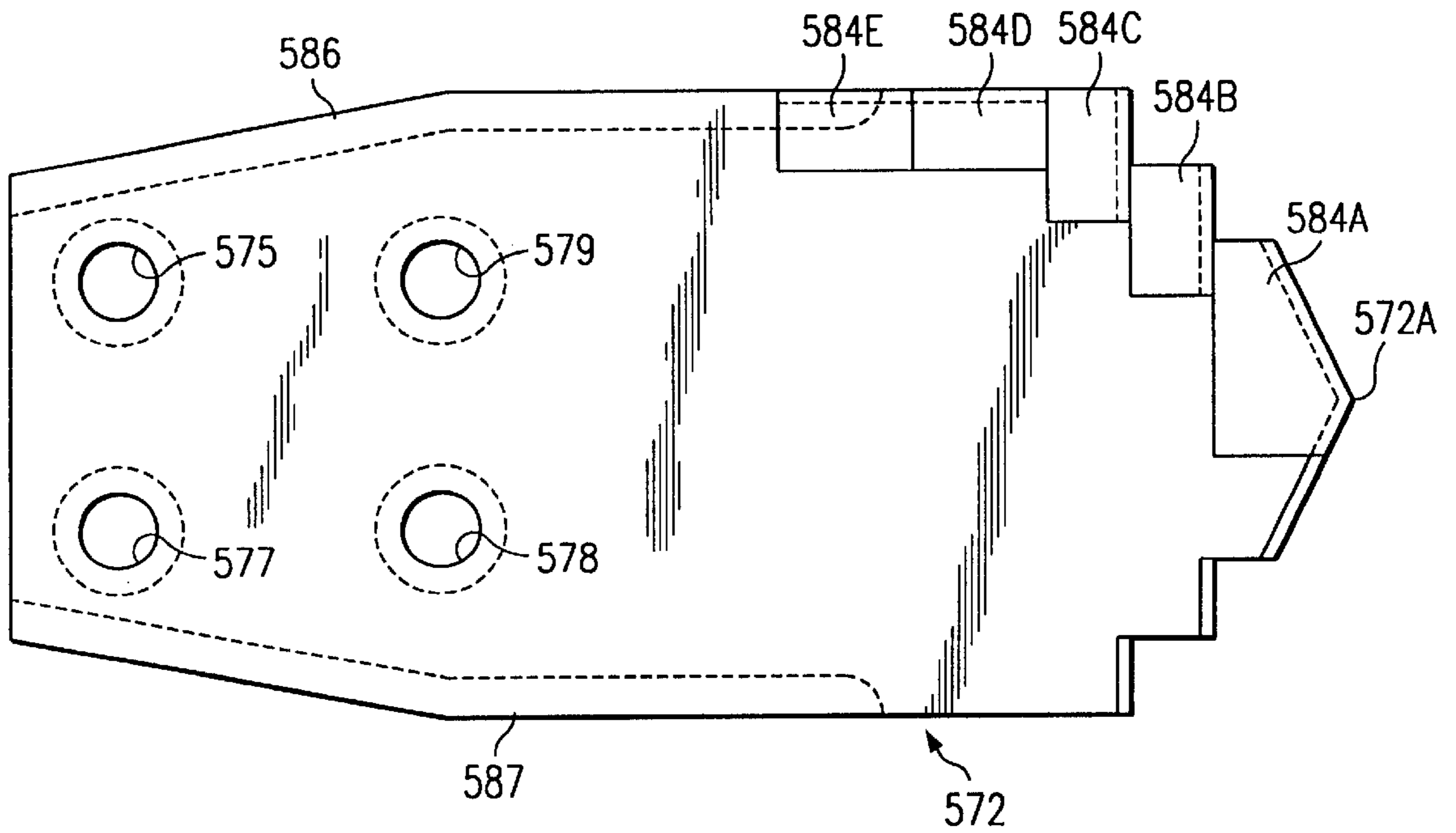


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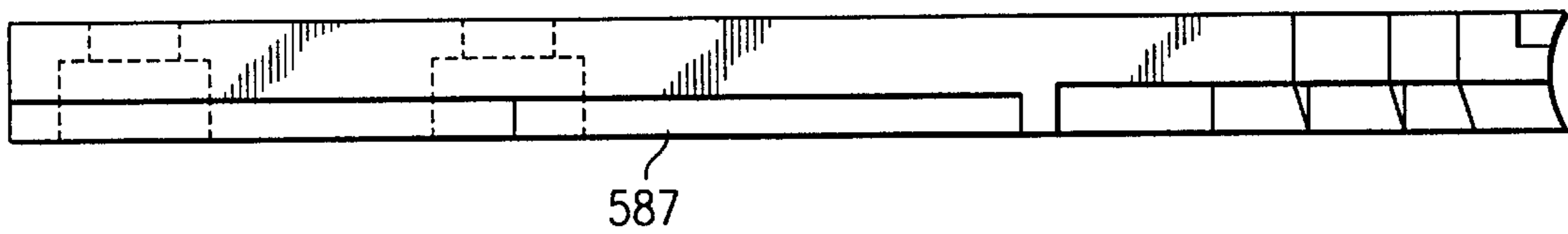


FIG. 31

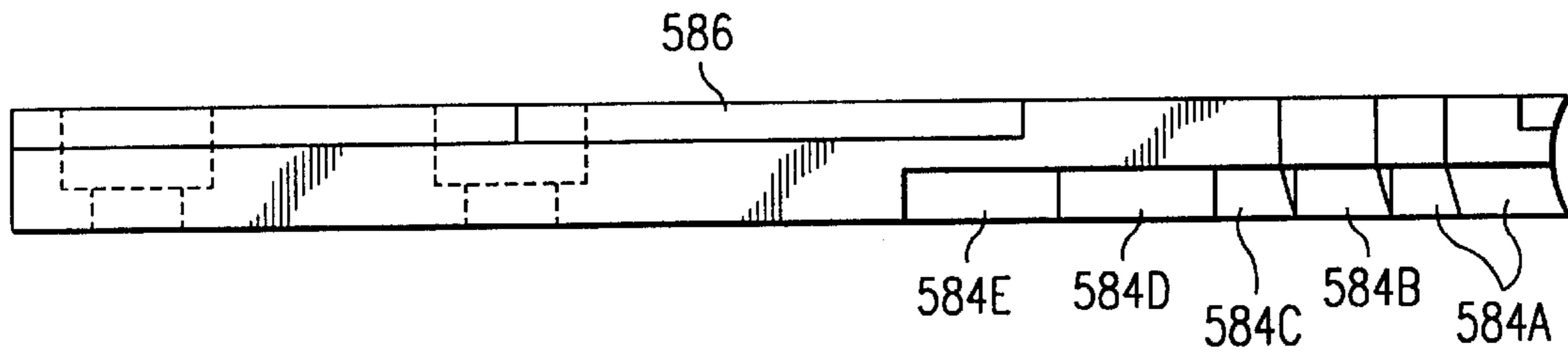


FIG. 32

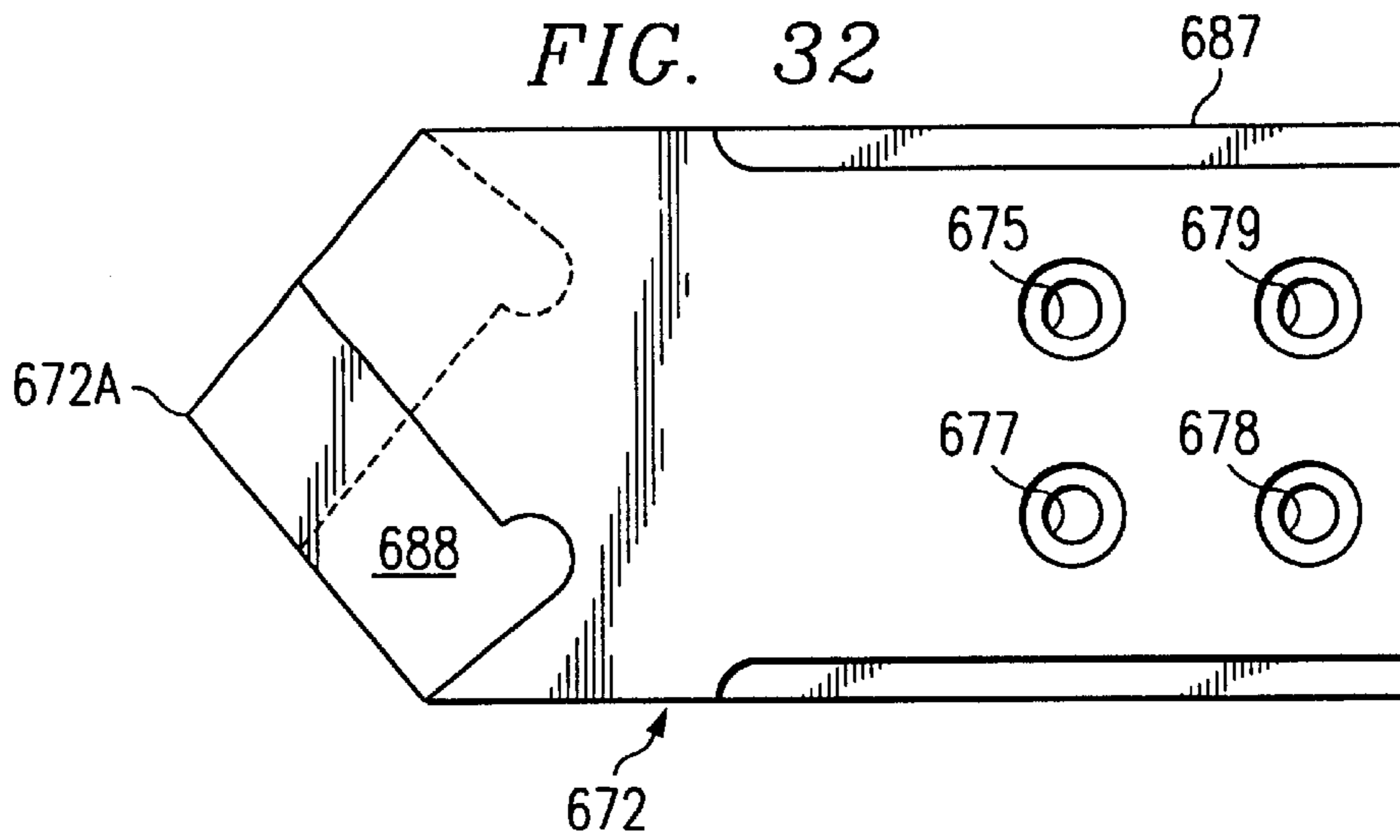


FIG. 33

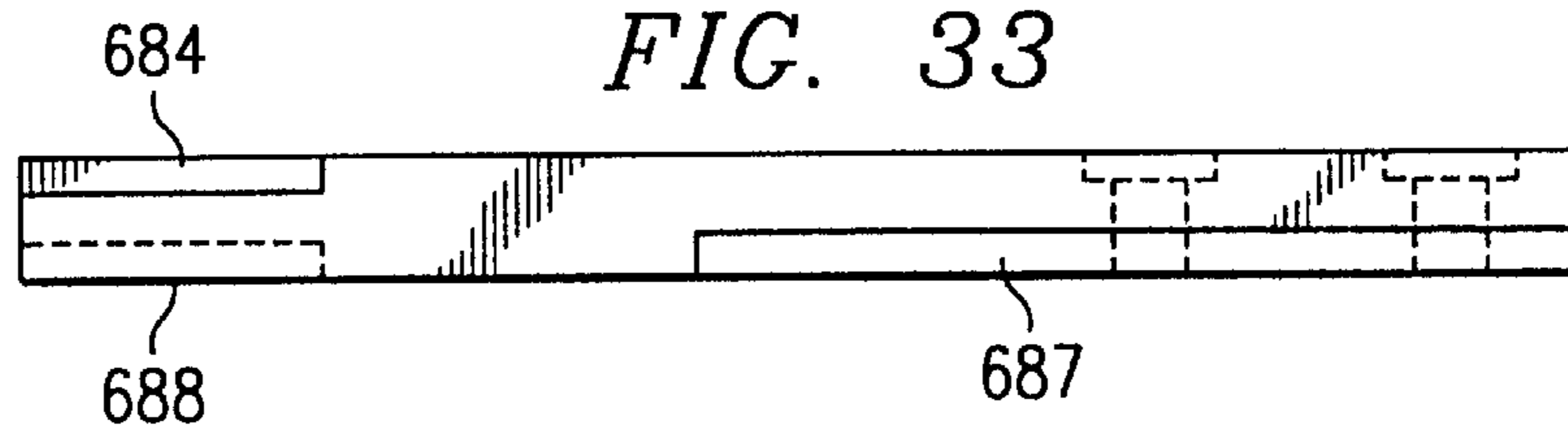


FIG. 34

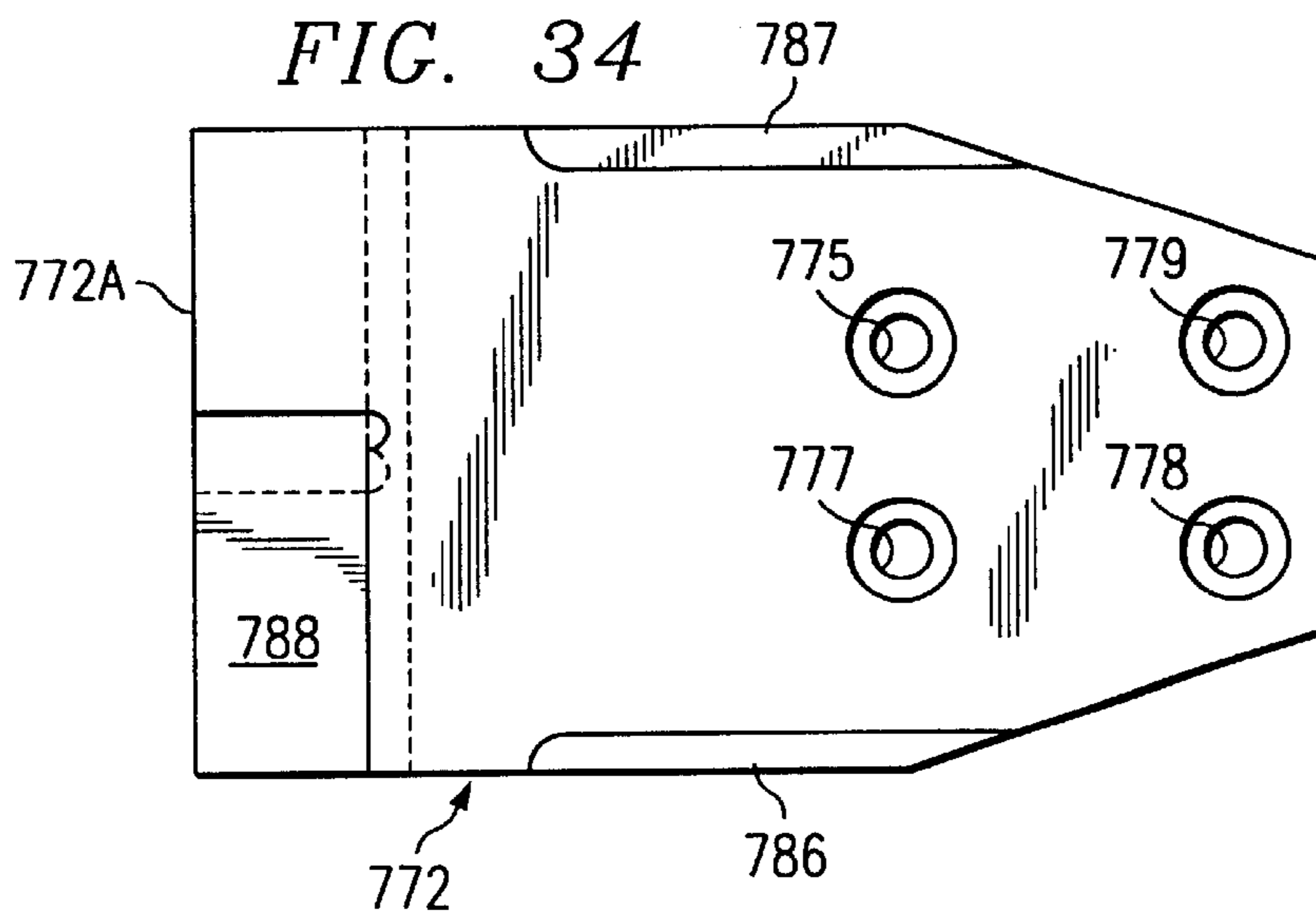
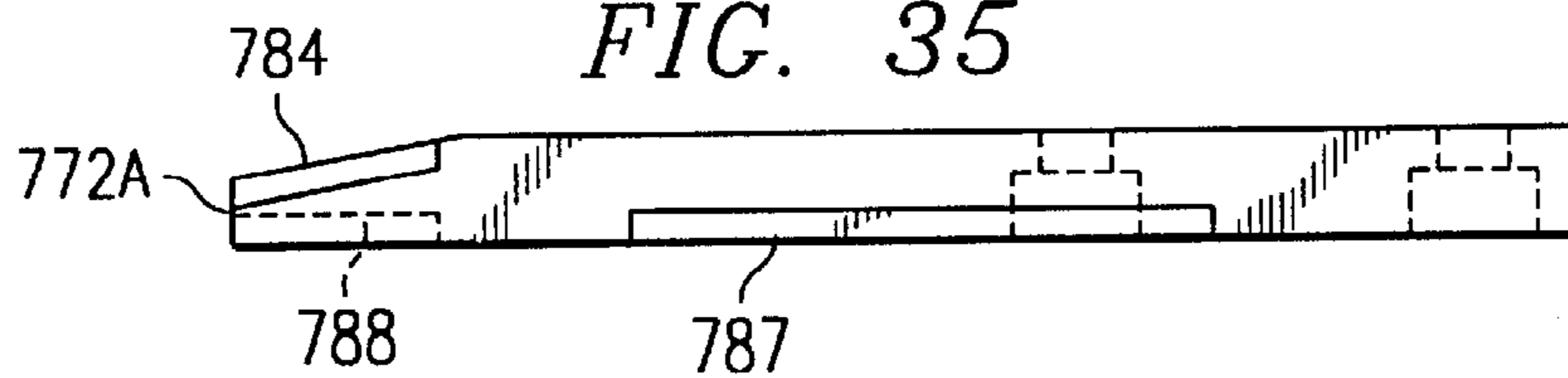
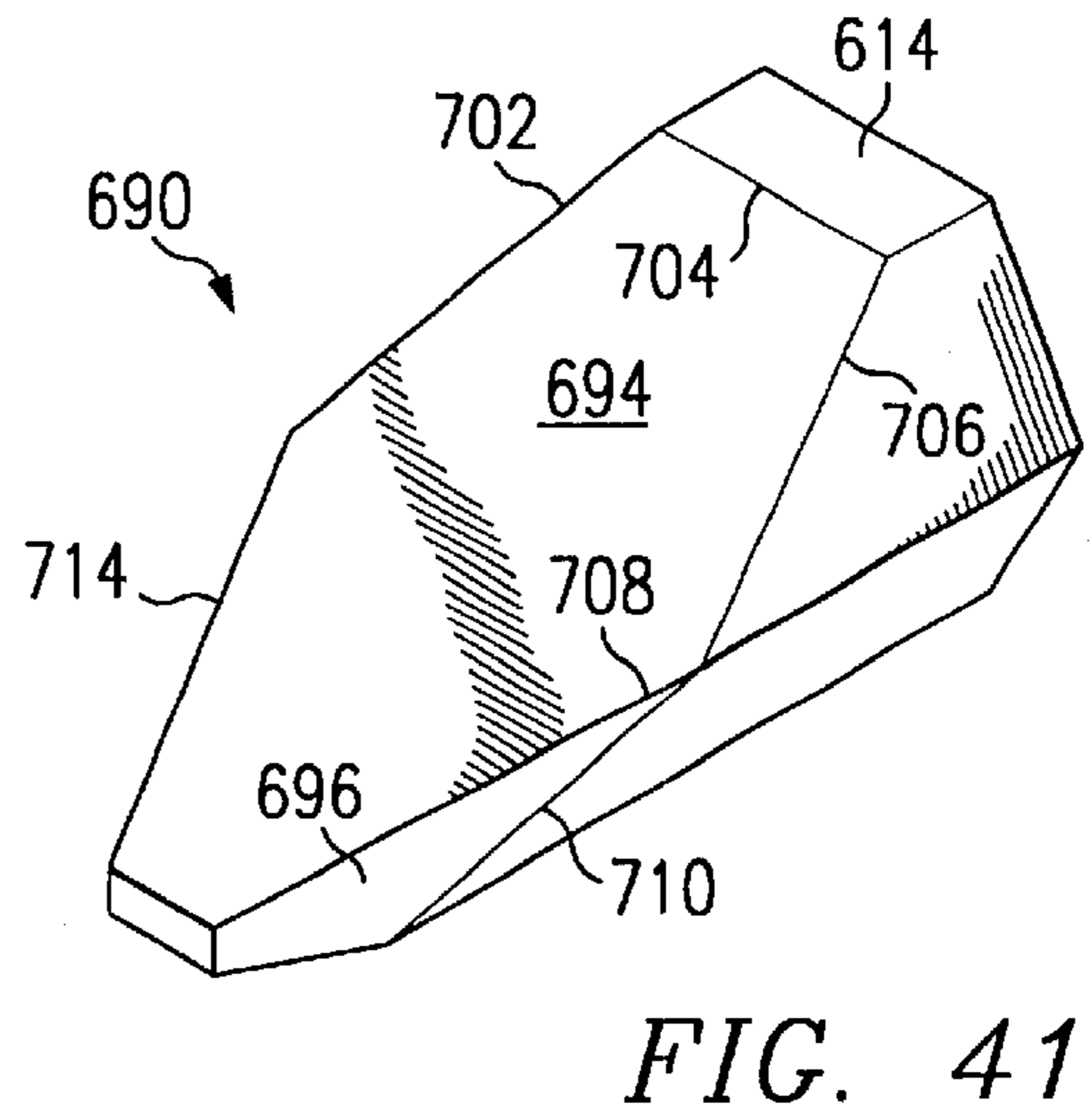
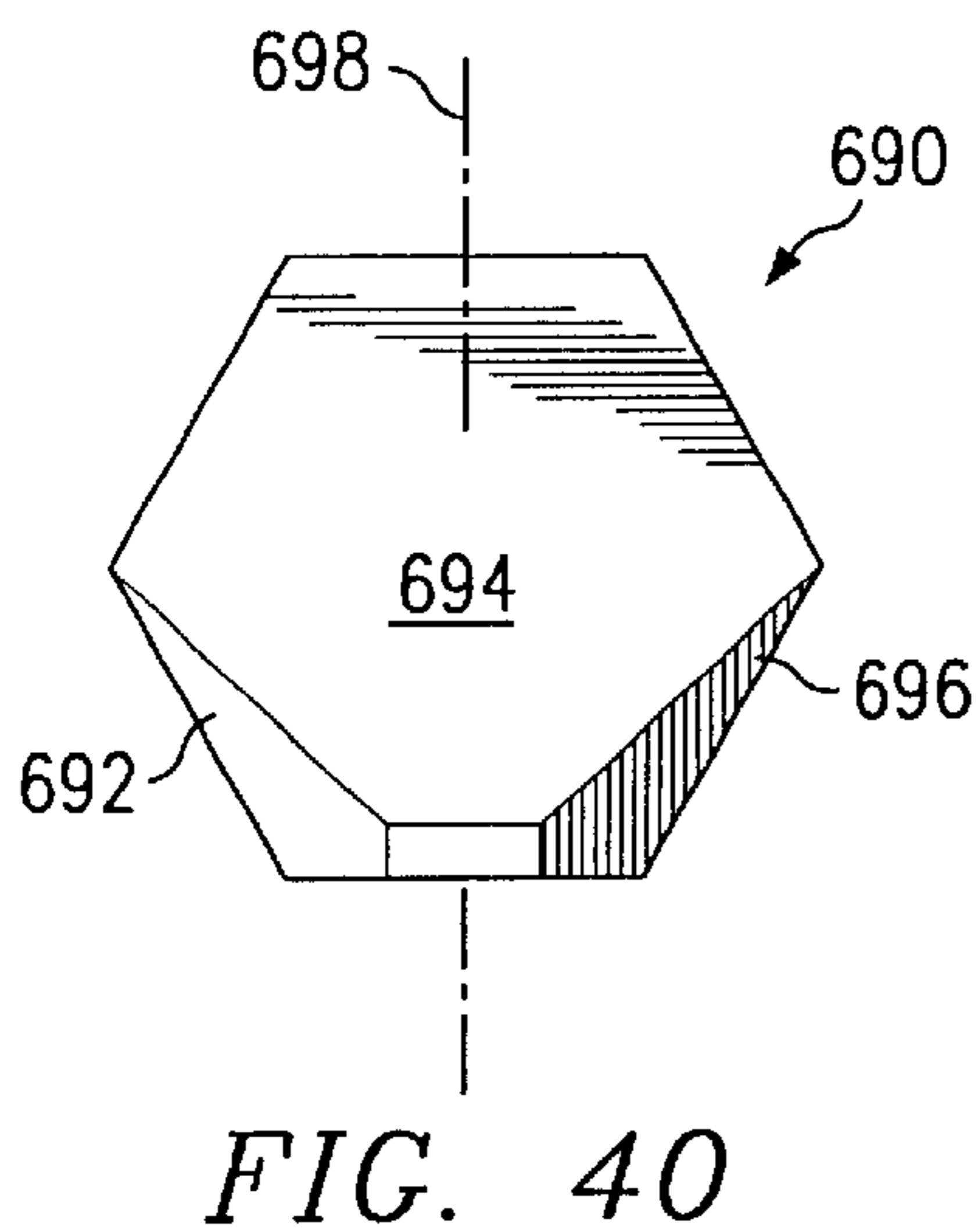
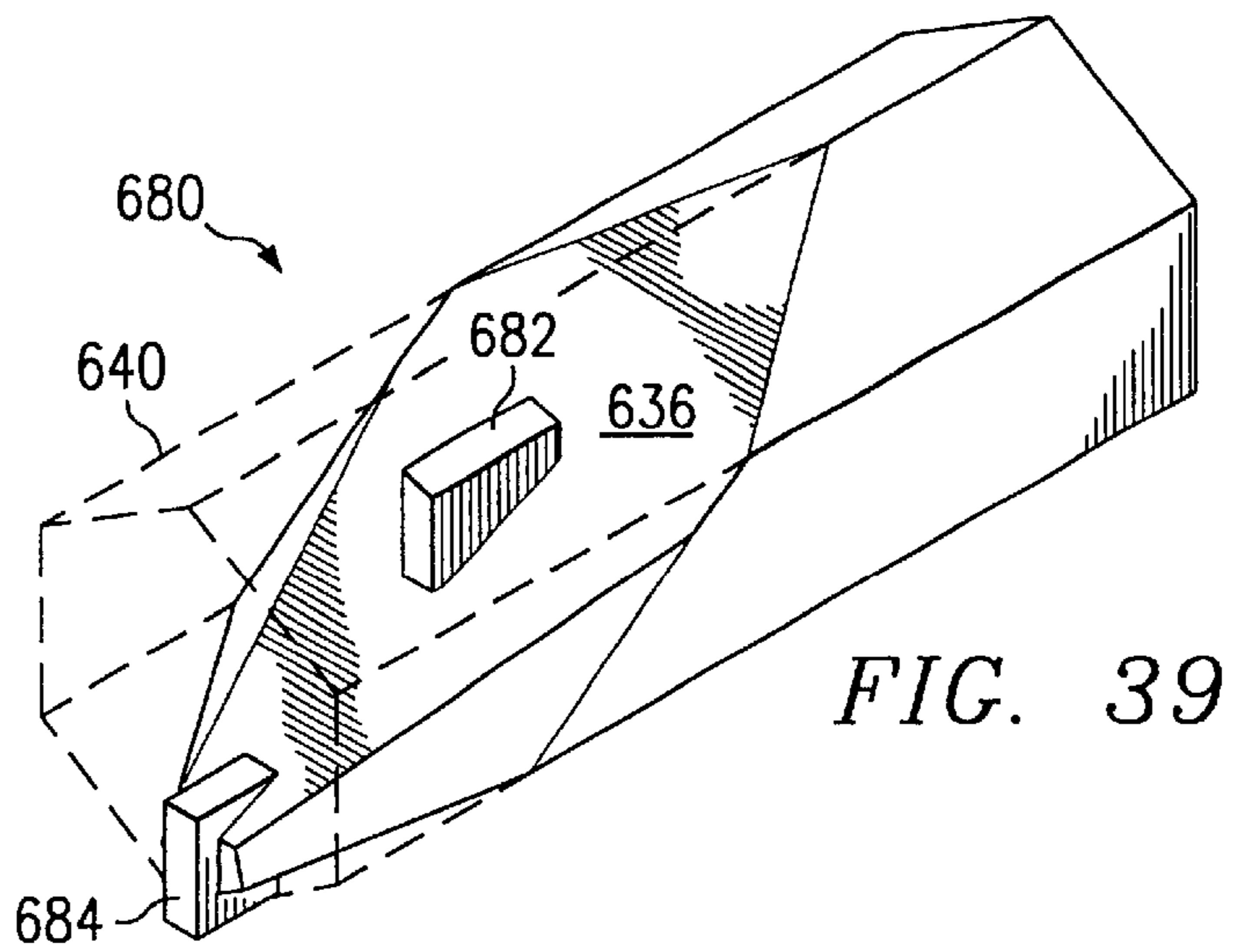
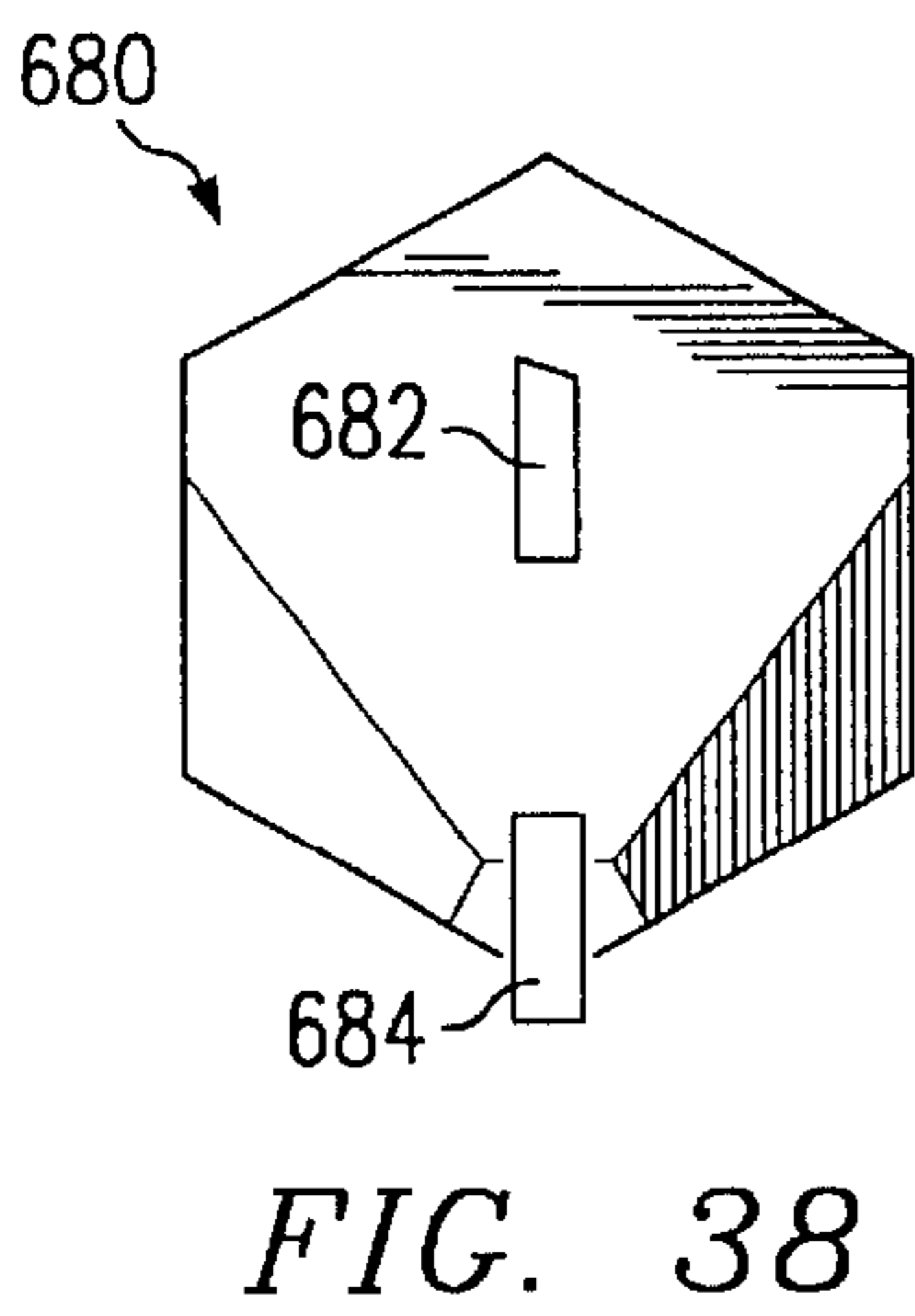
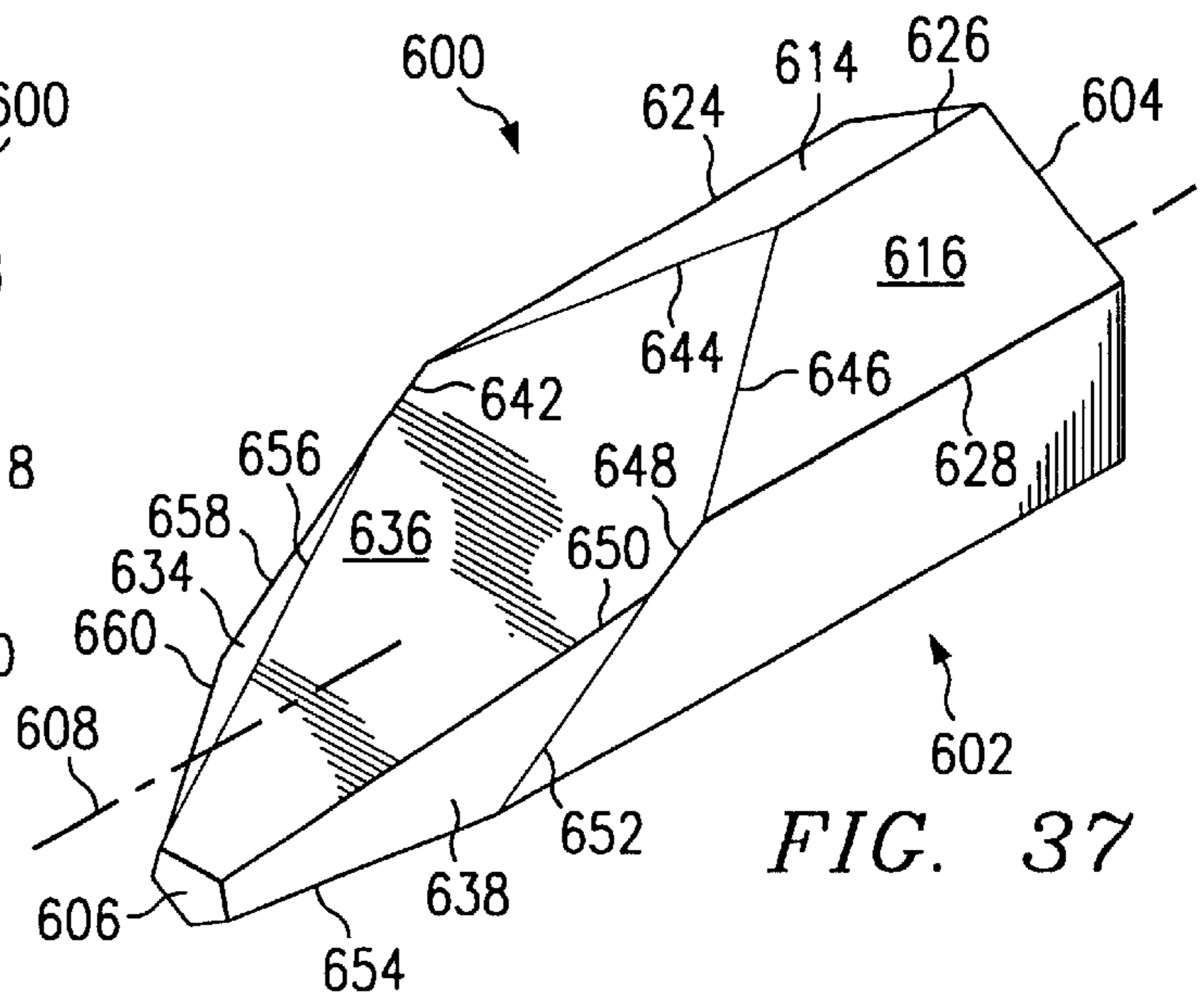
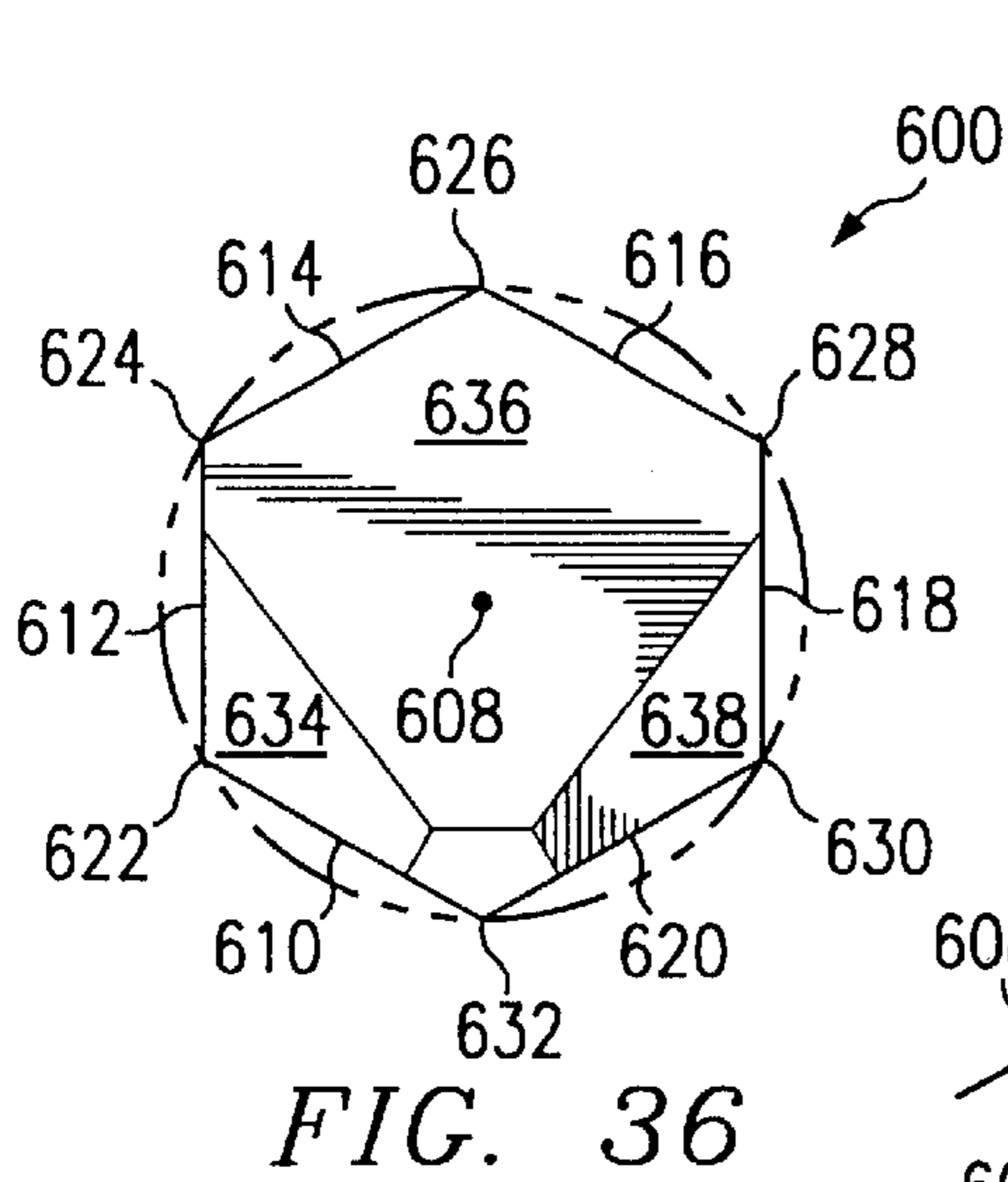


FIG. 35





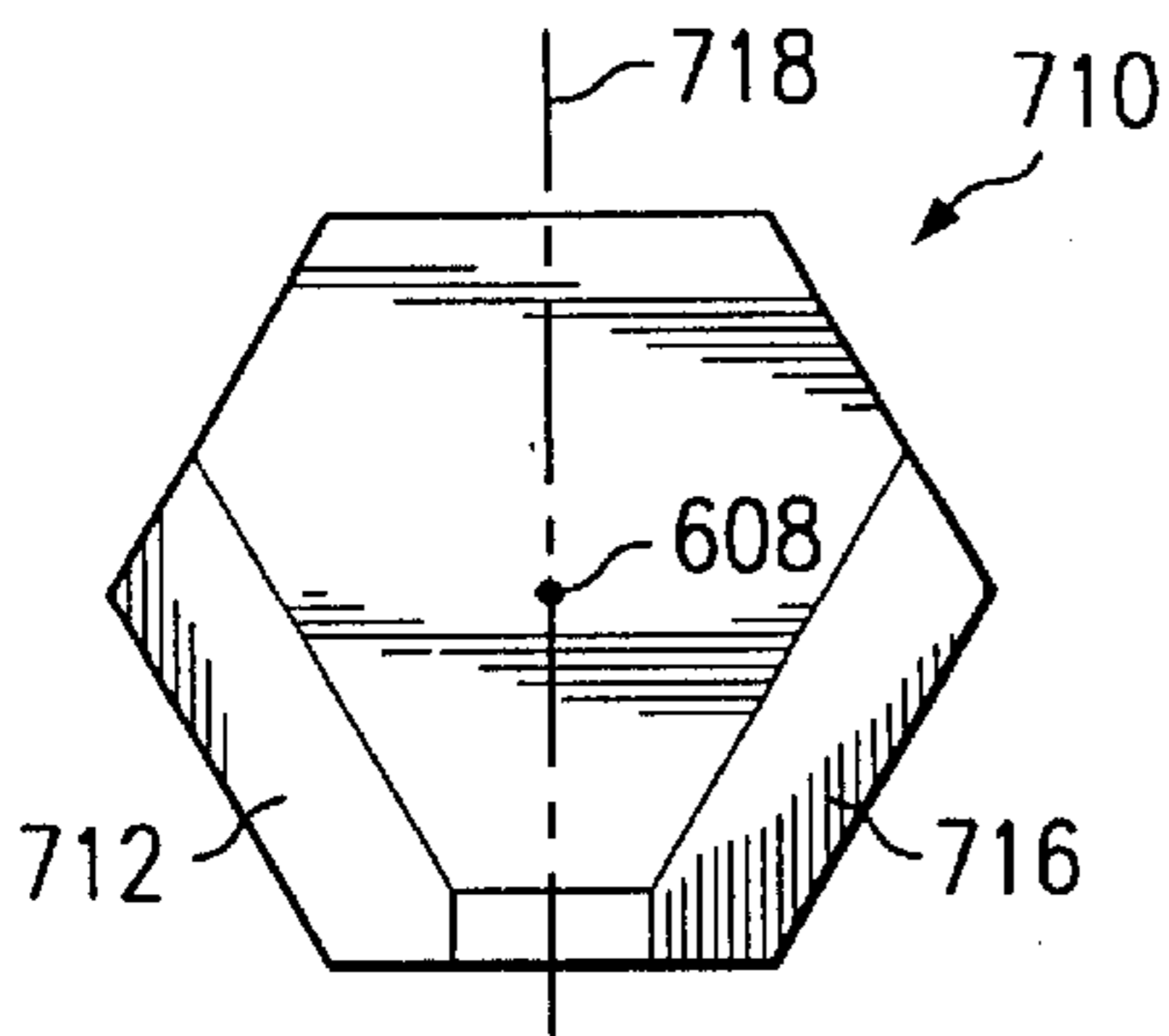


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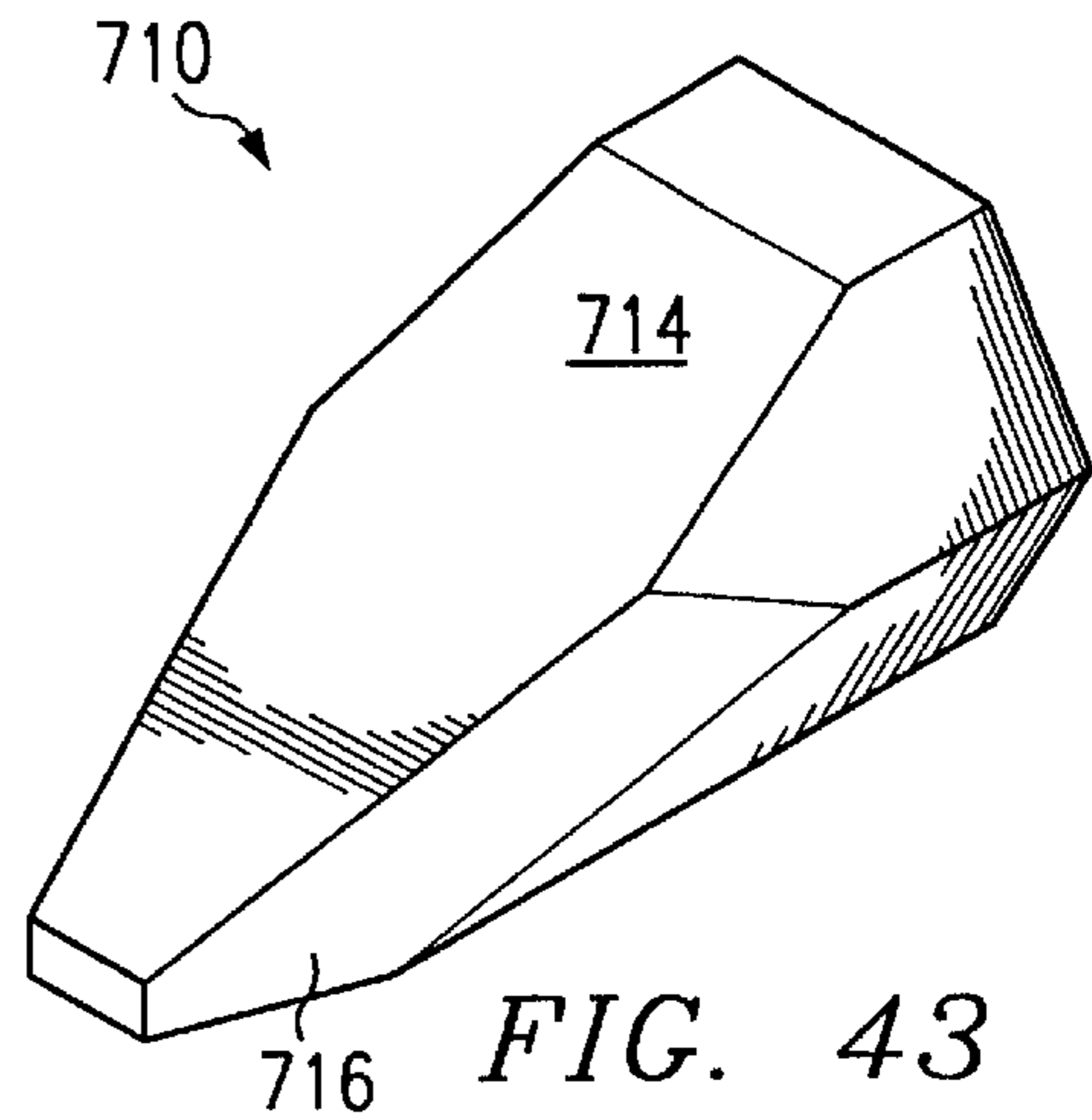


FIG. 43

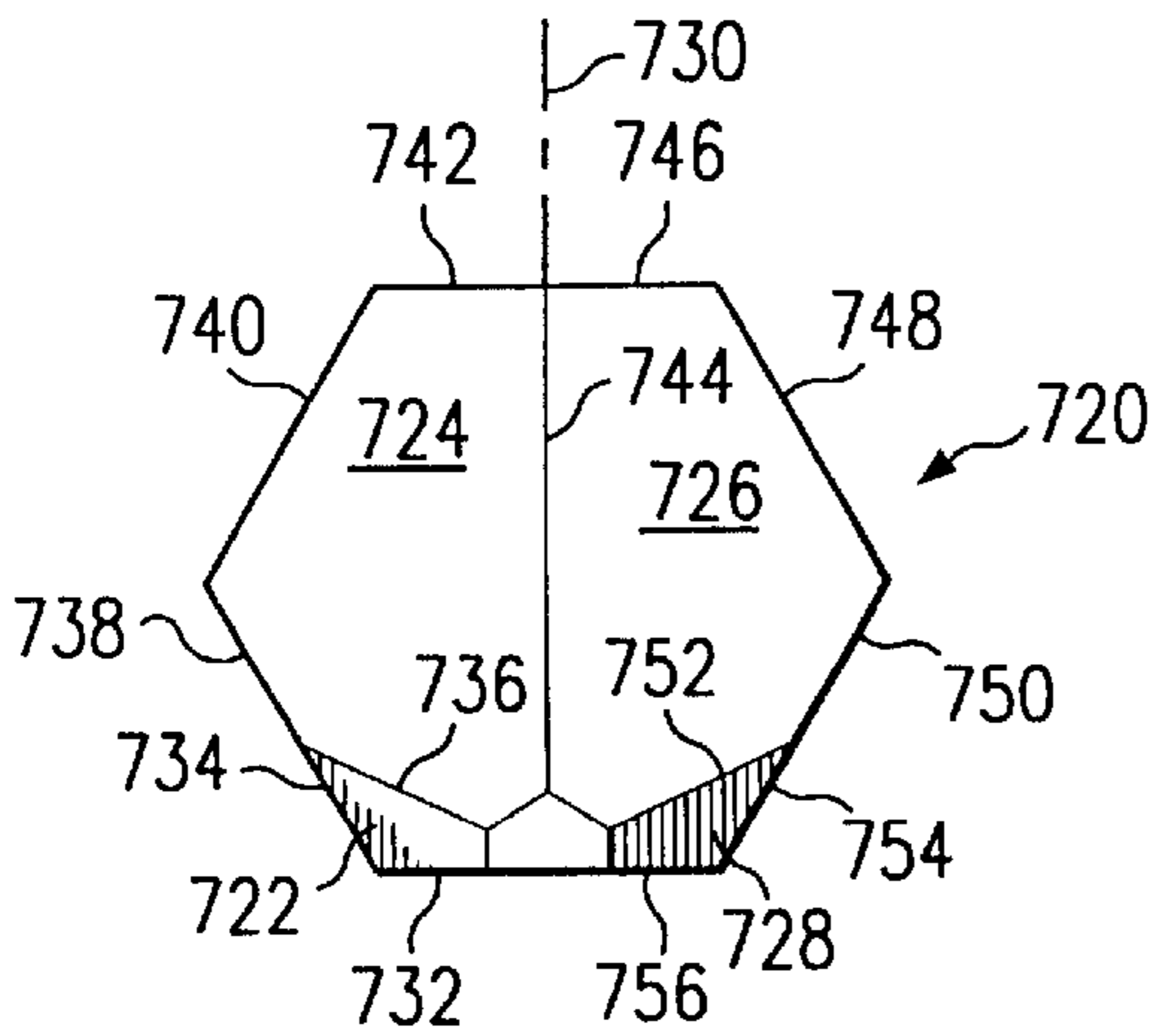


FIG. 44

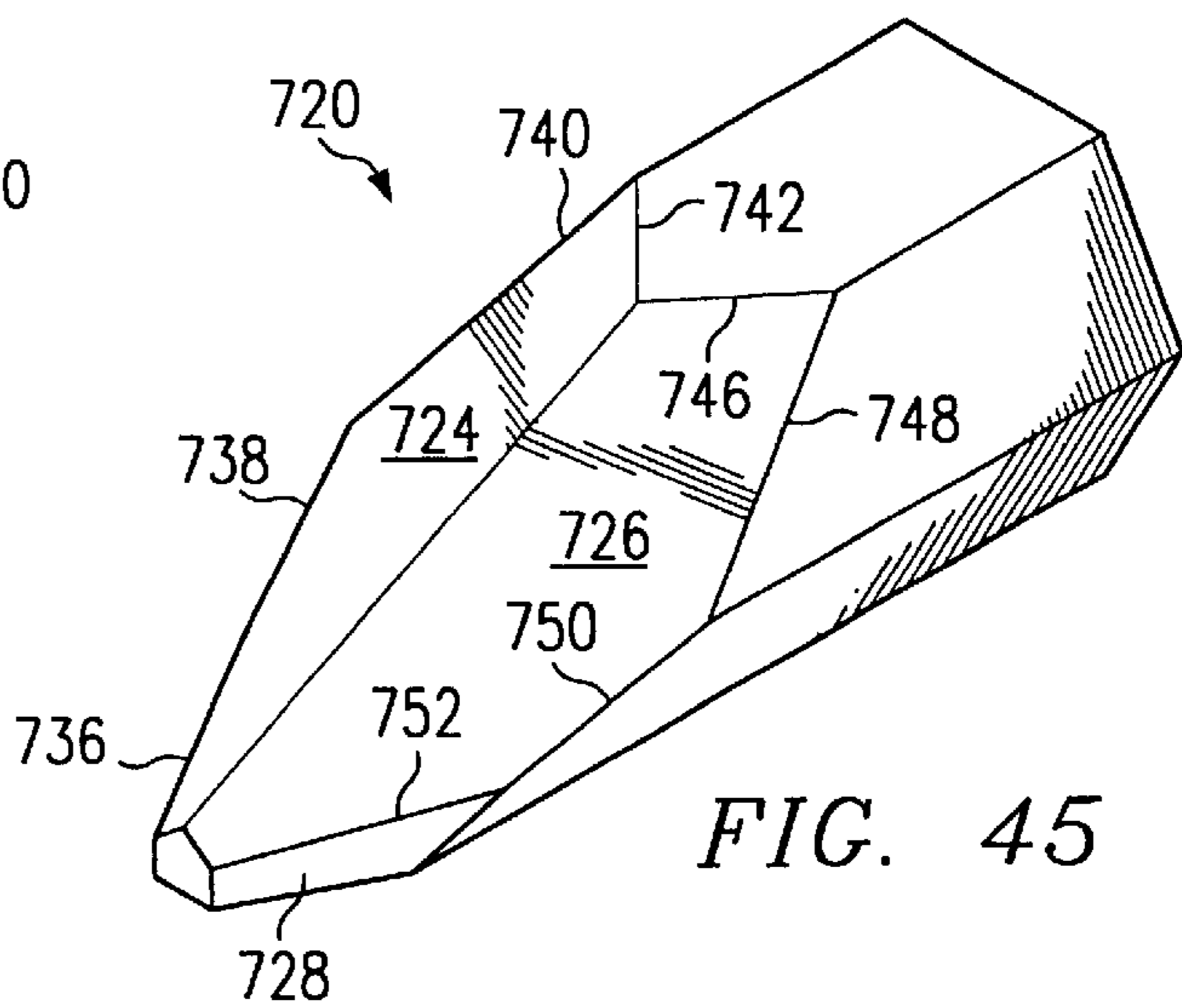


FIG. 45

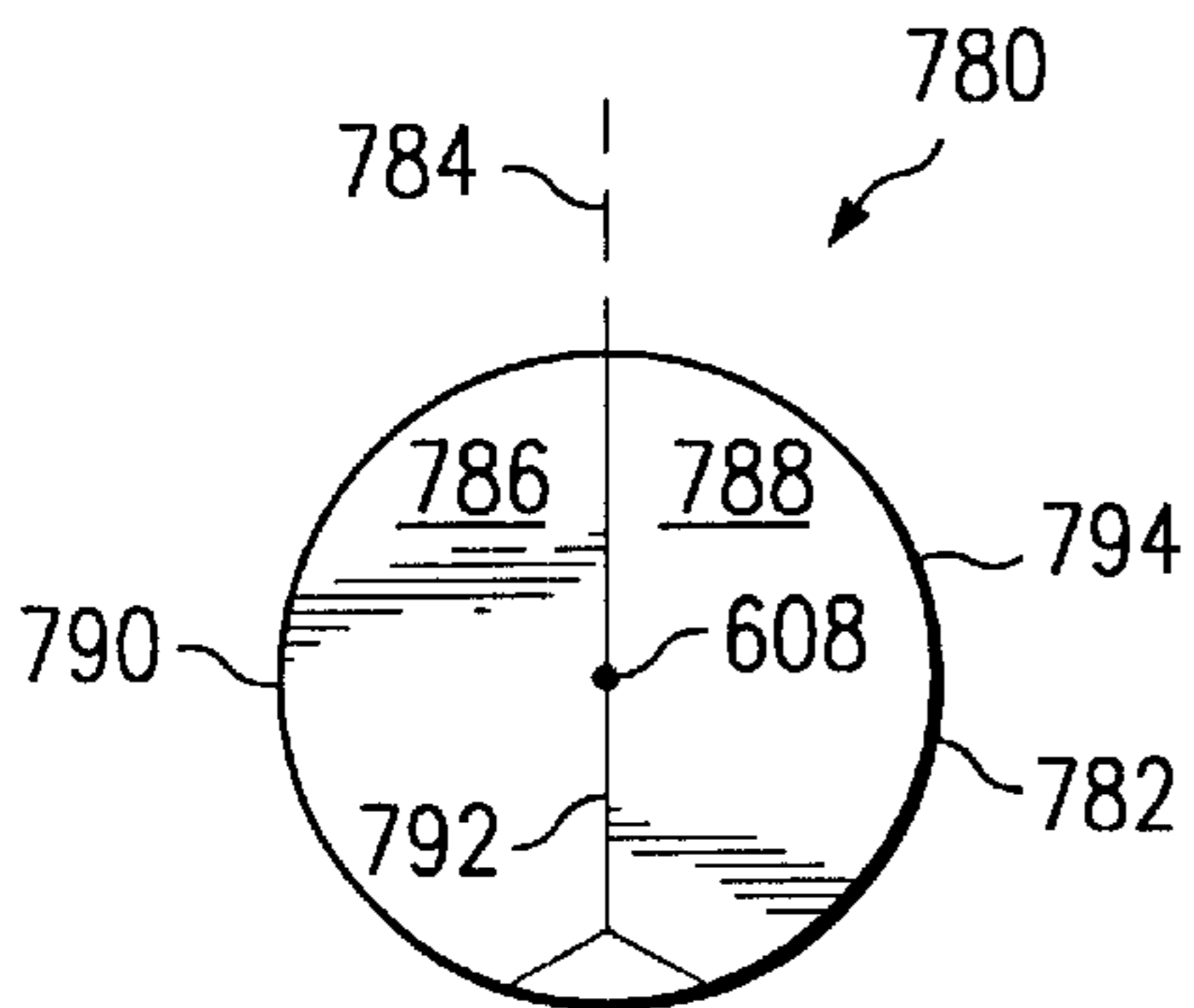


FIG. 46

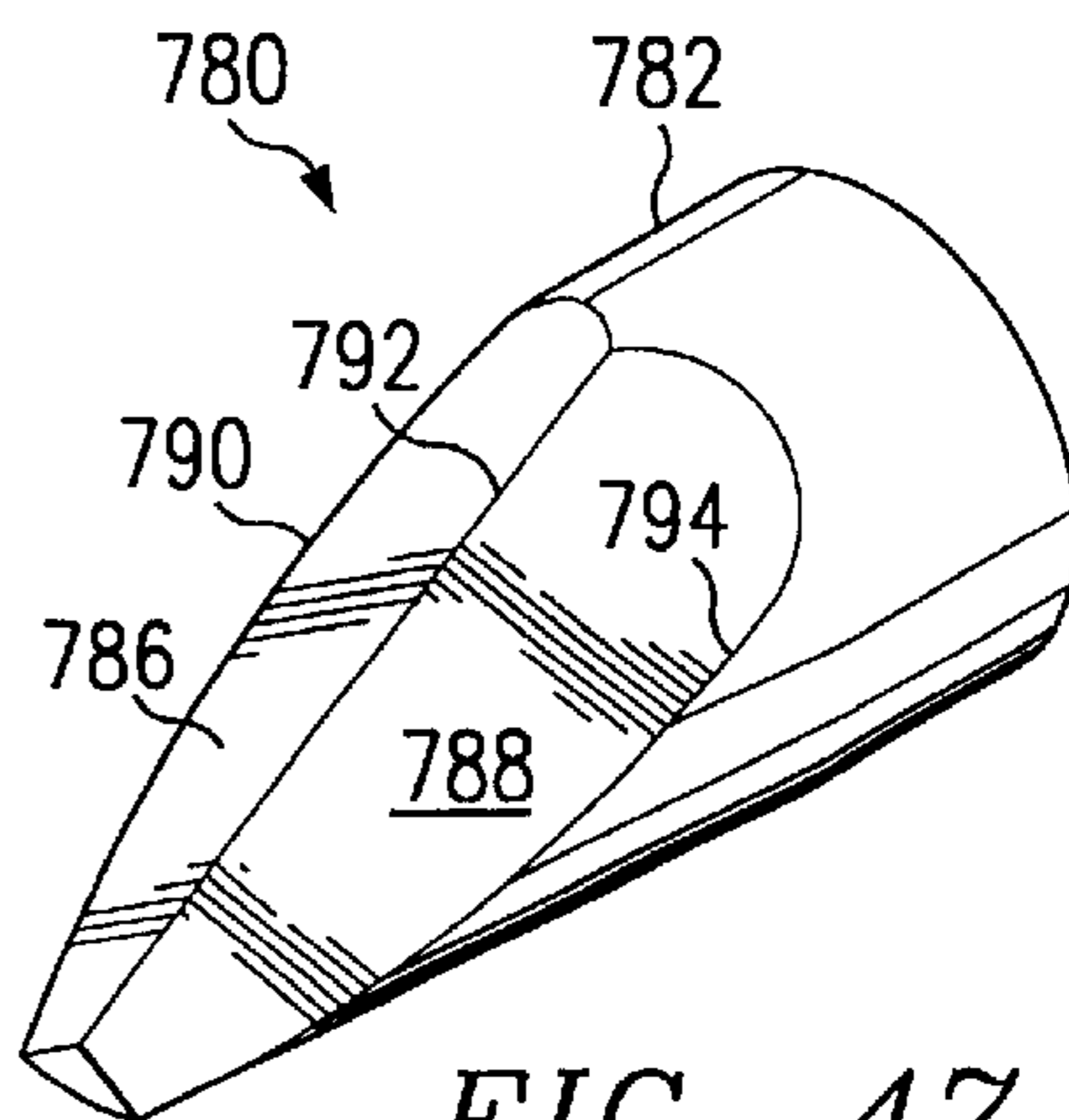


FIG. 47

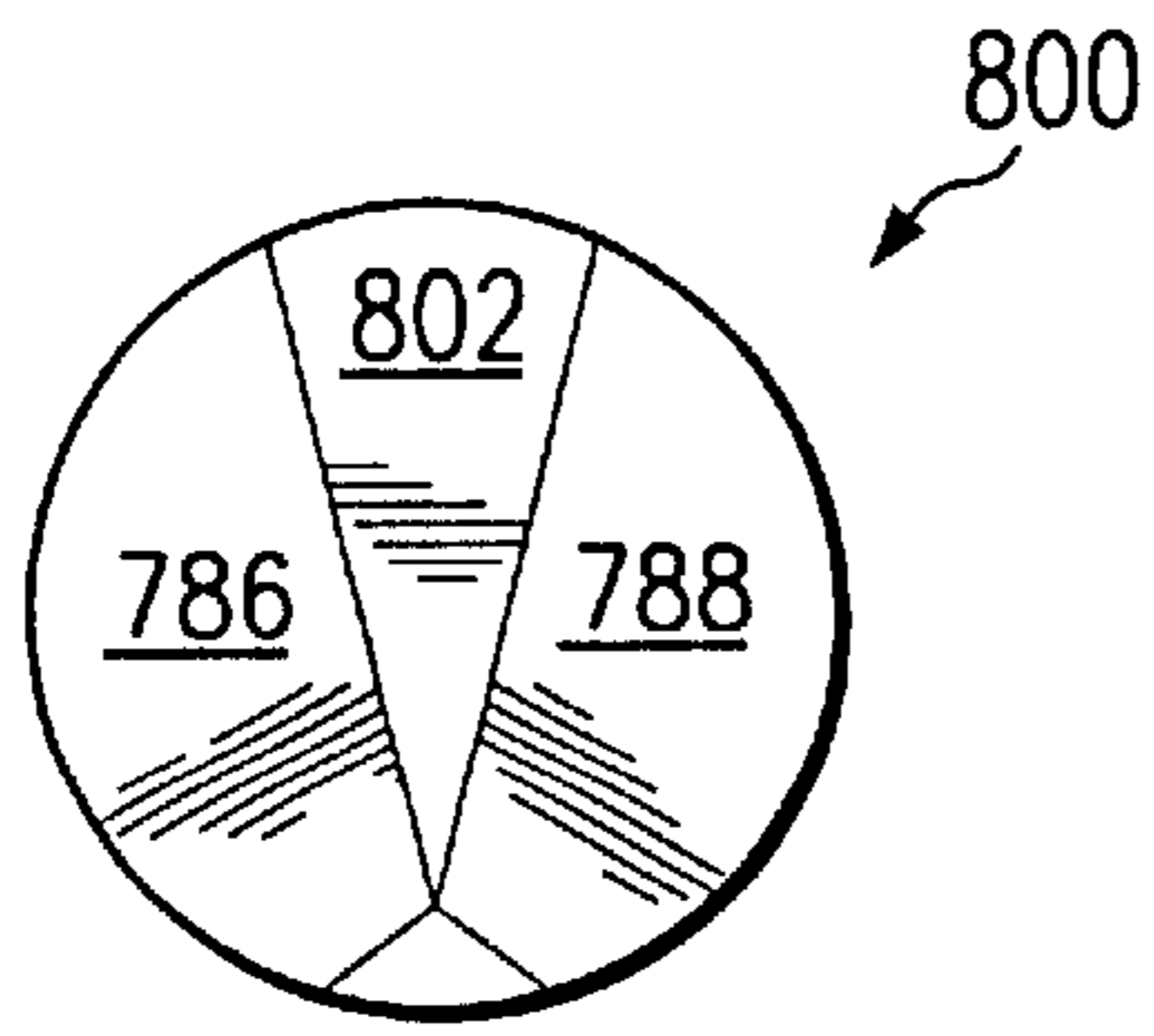


FIG. 48

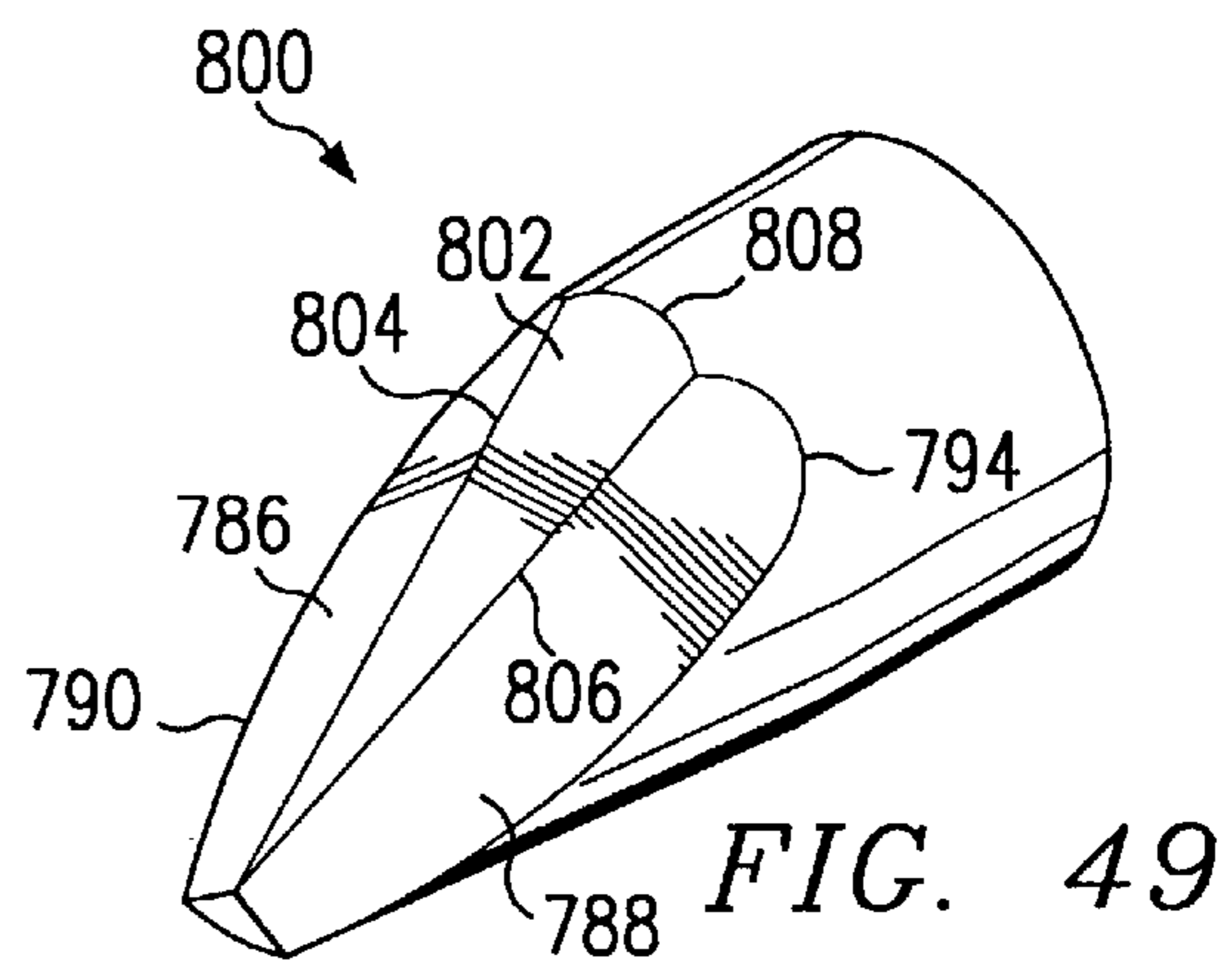


FIG. 49

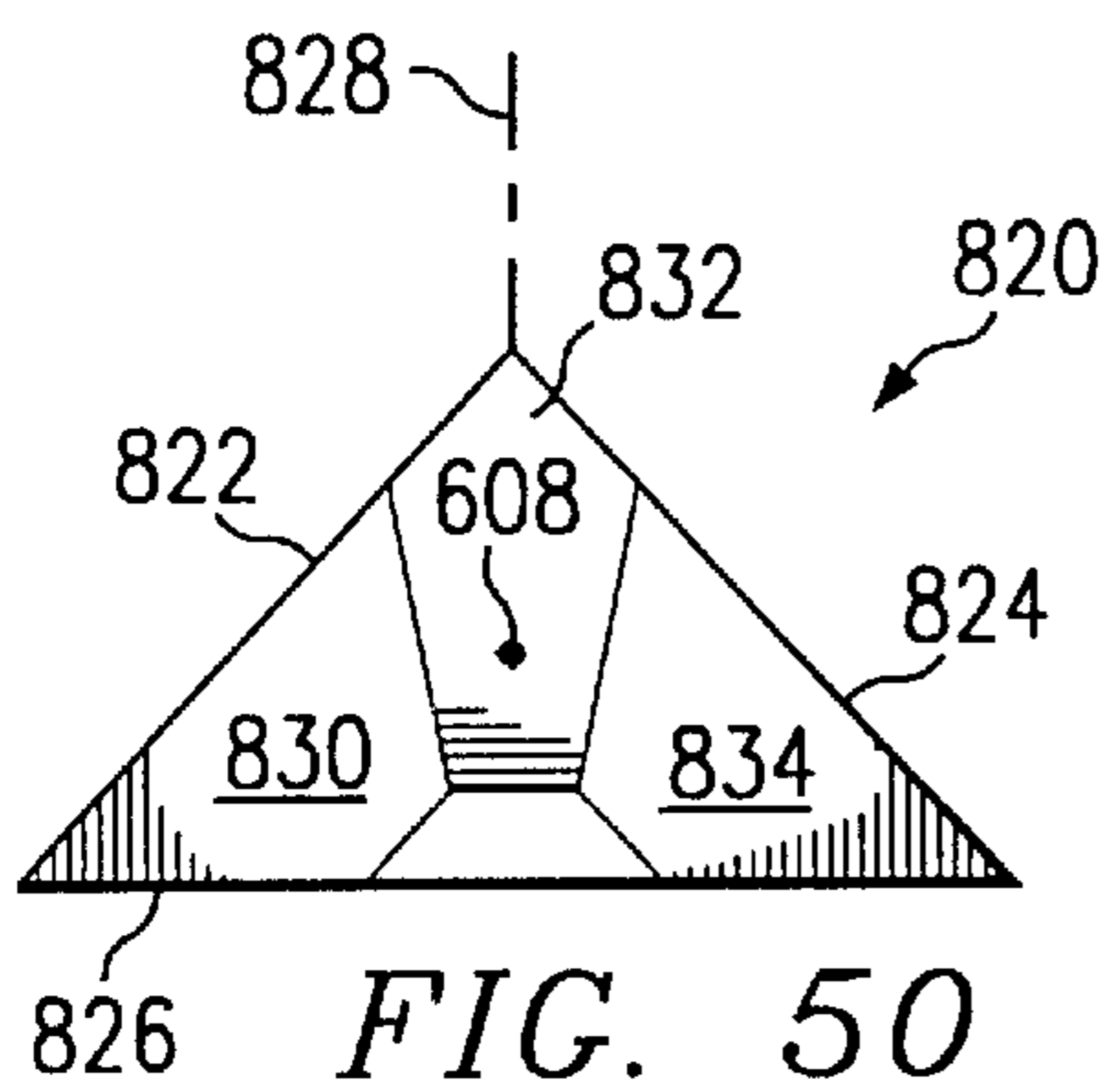


FIG. 50

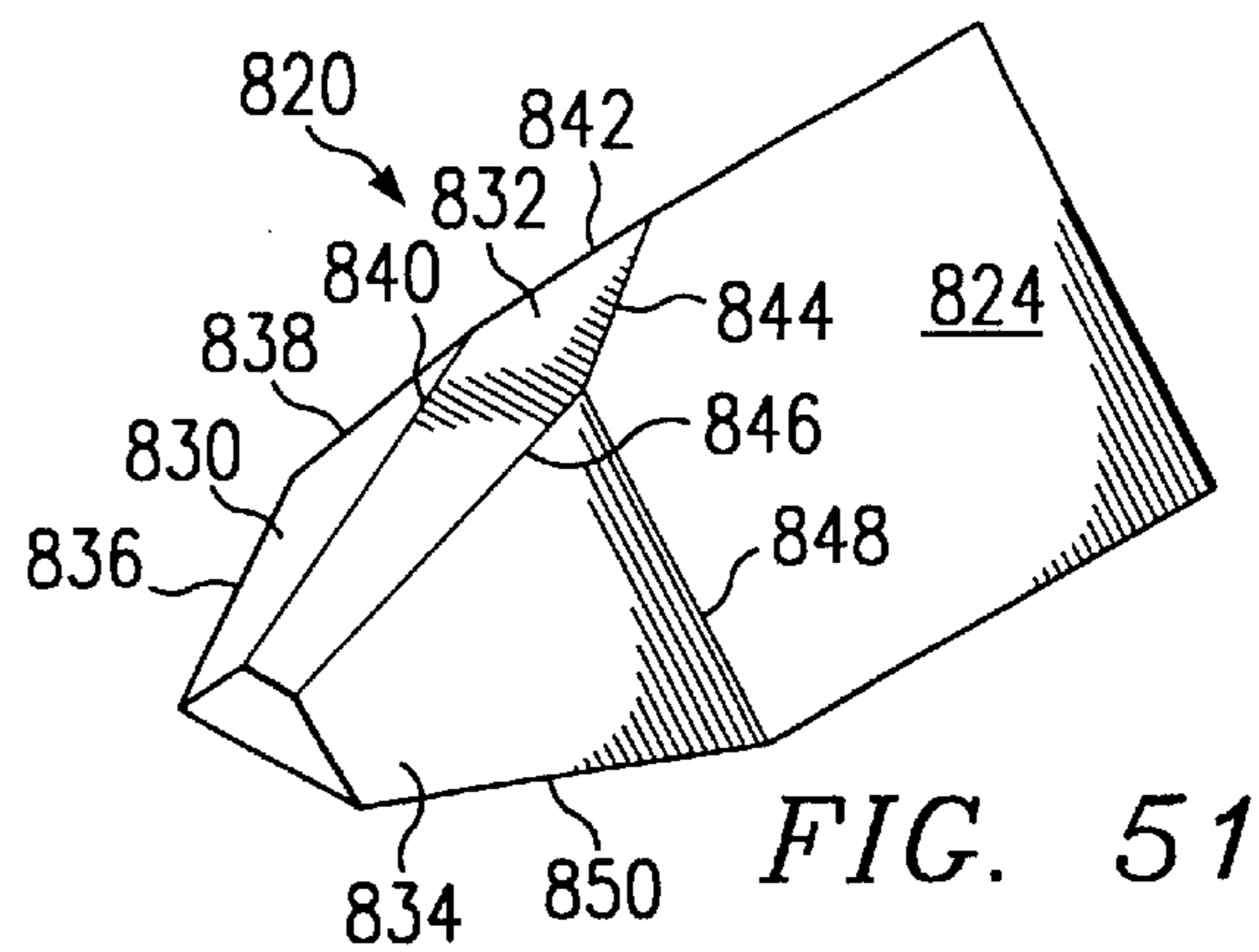


FIG. 51

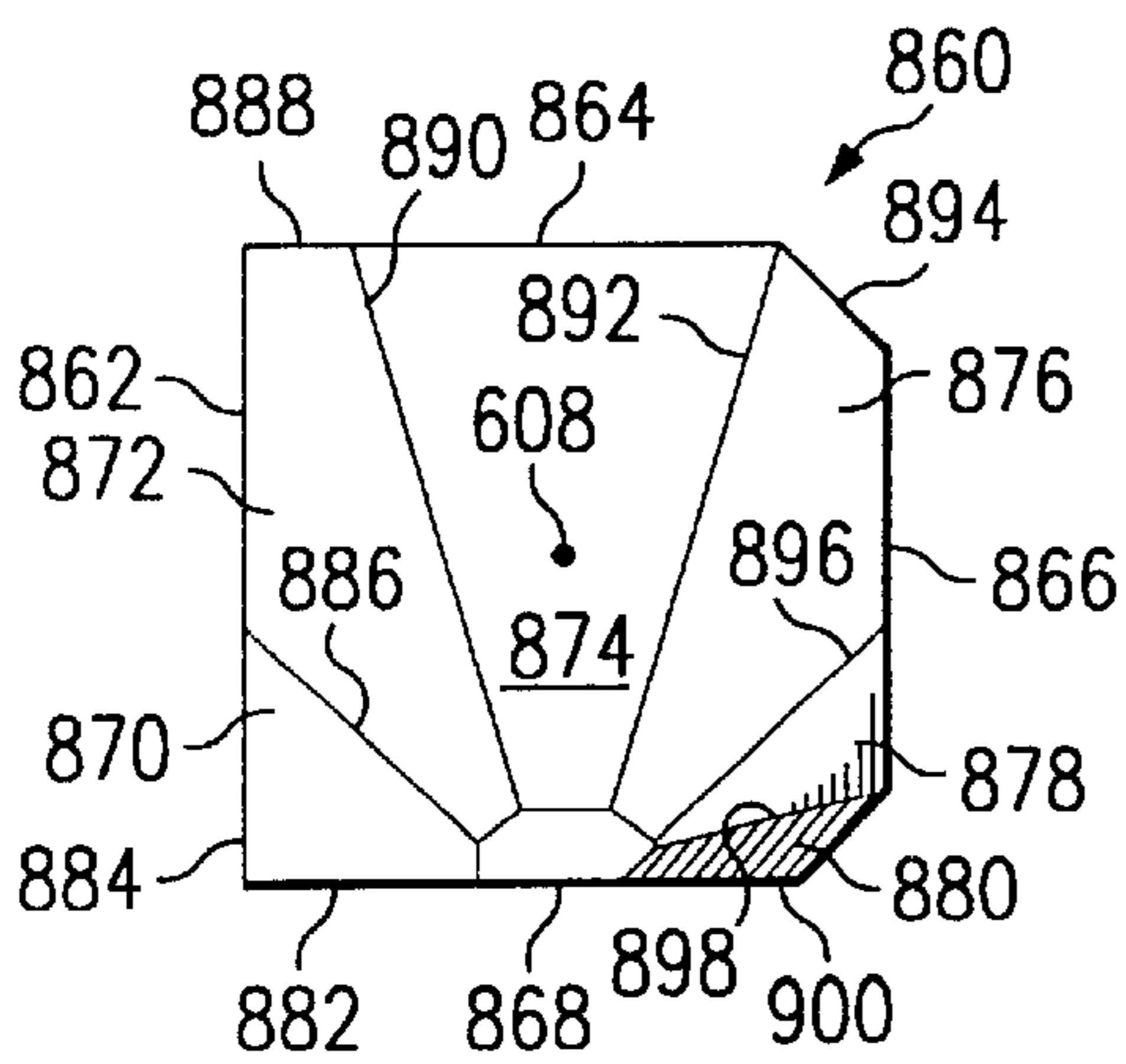


FIG. 52

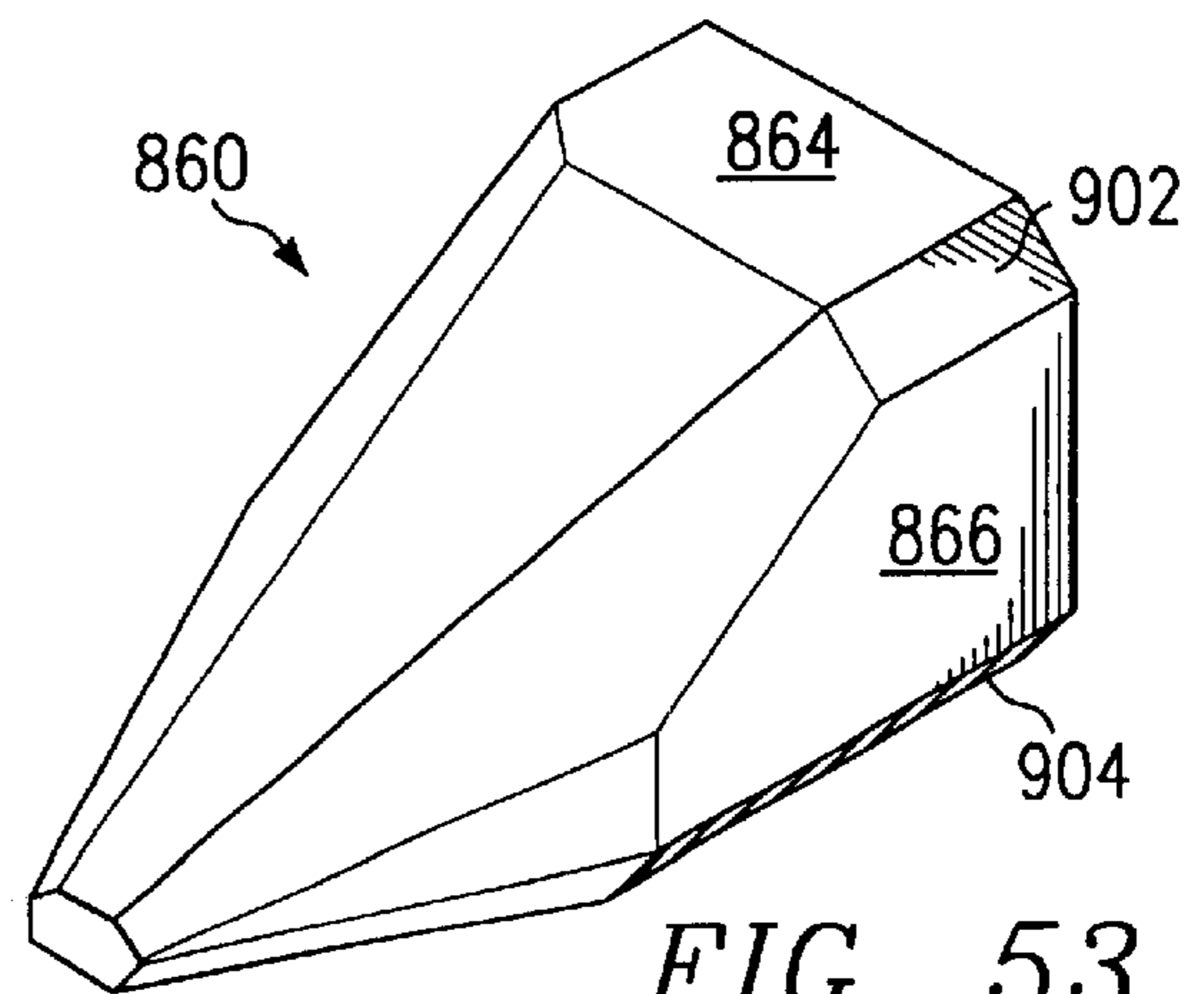


FIG. 53

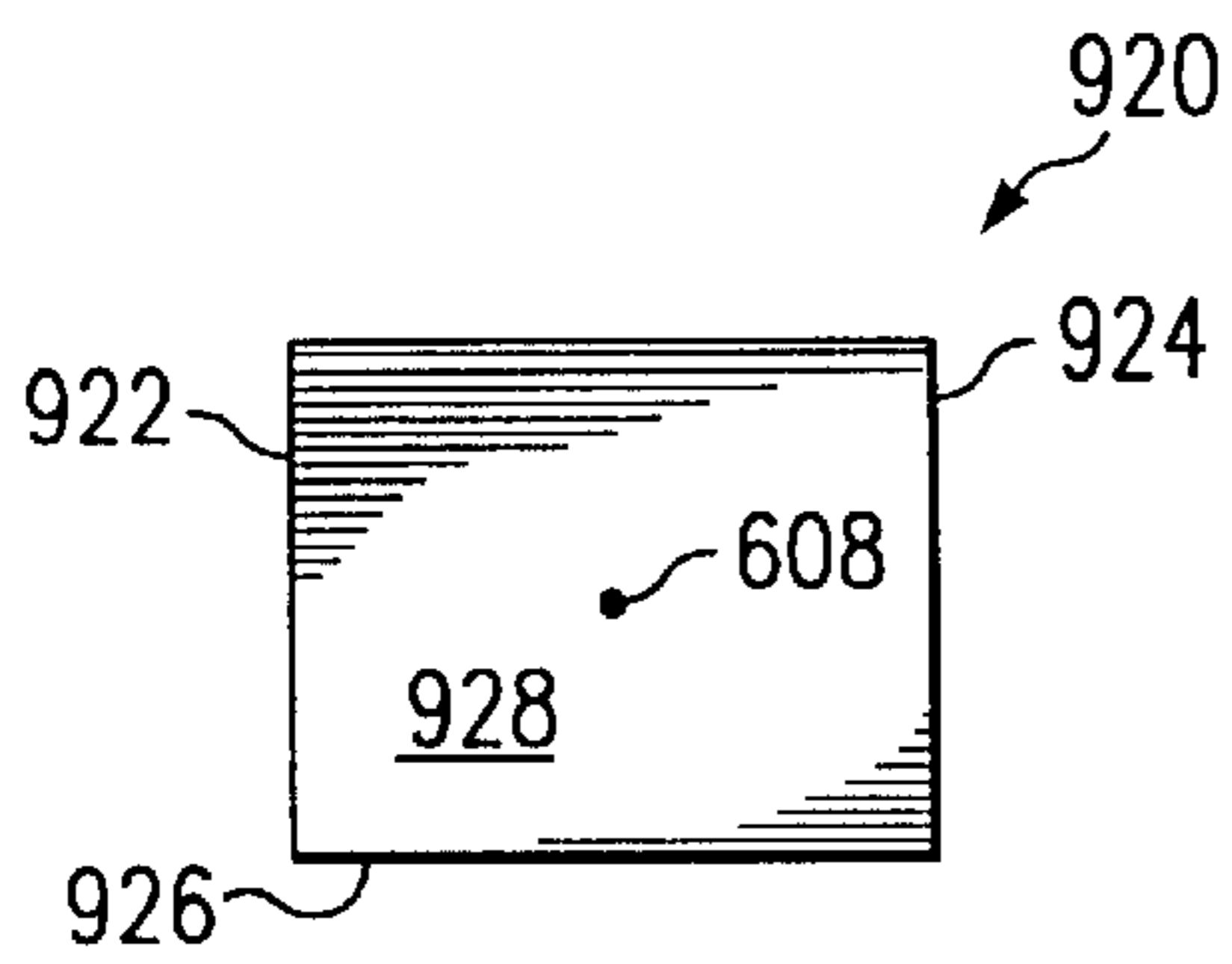


FIG. 54

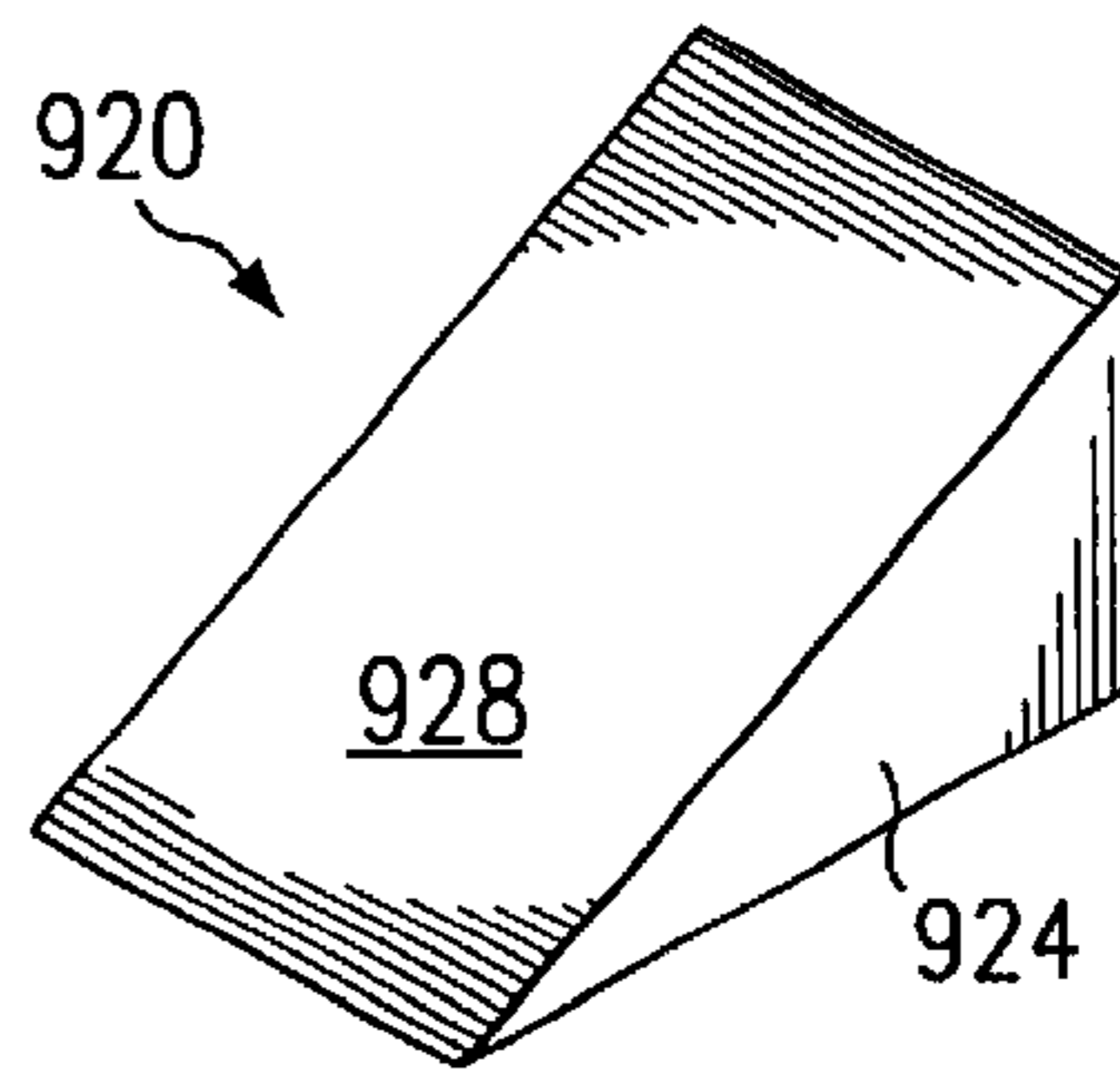


FIG. 55

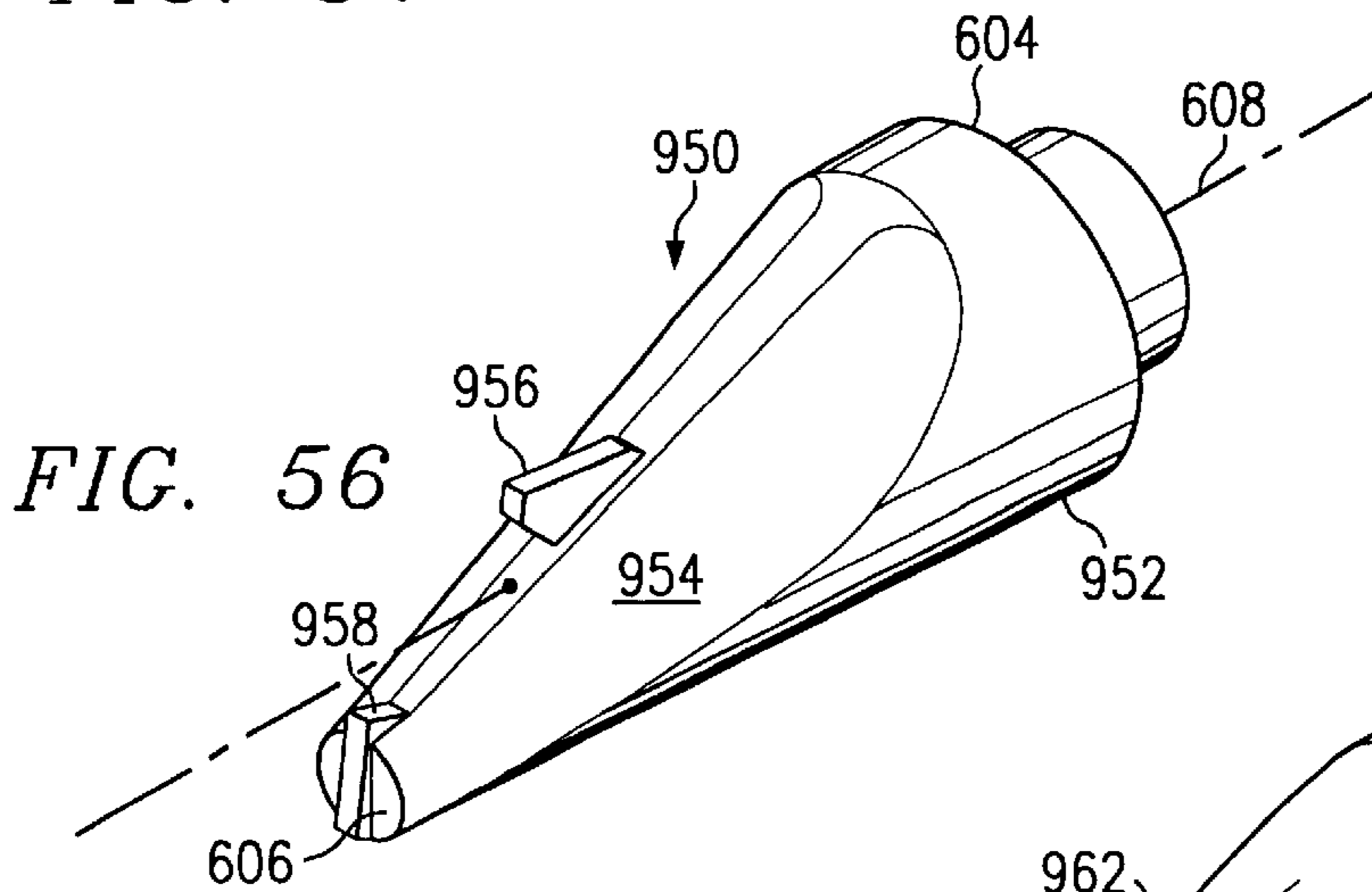


FIG. 56

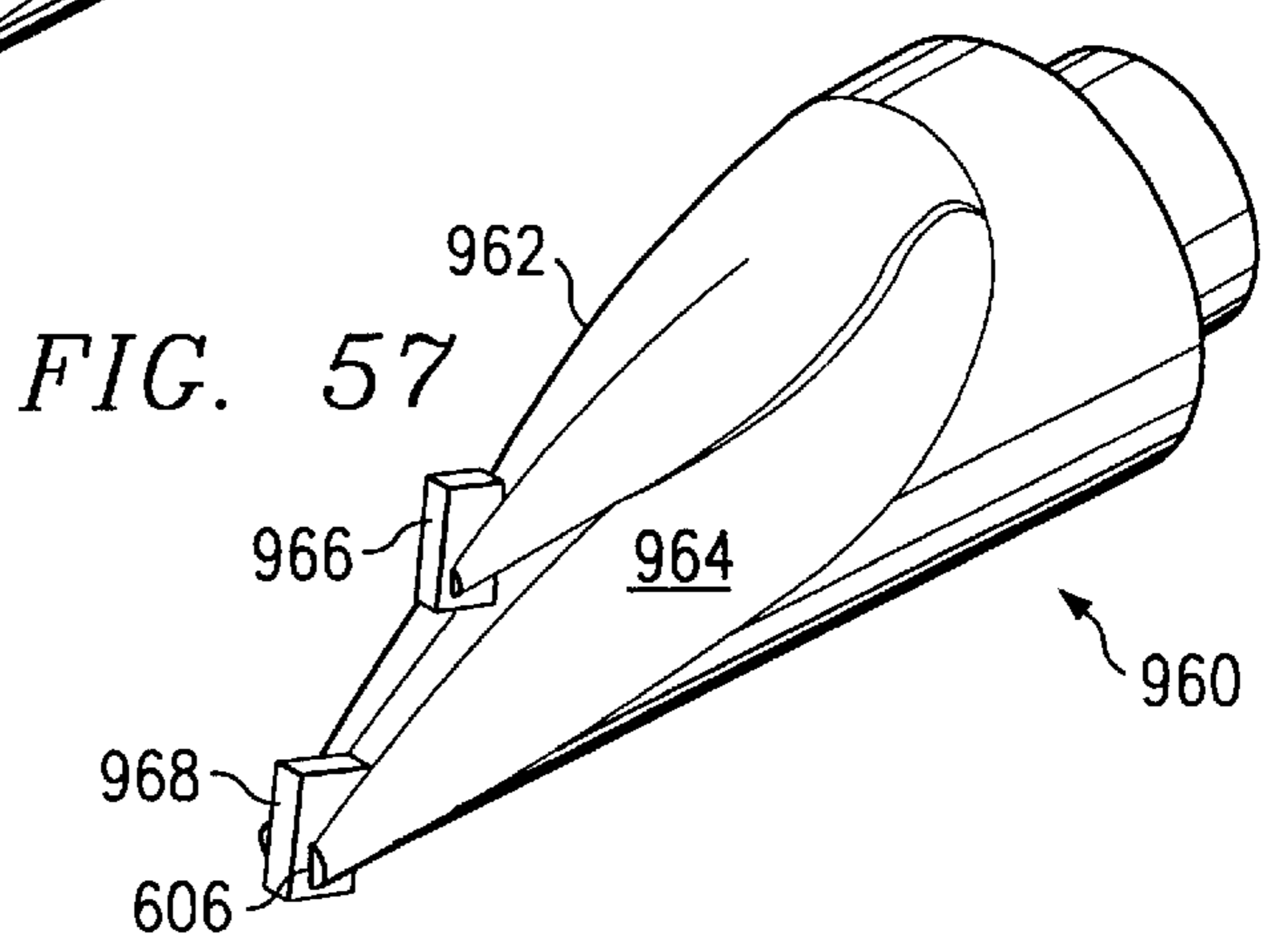


FIG. 57

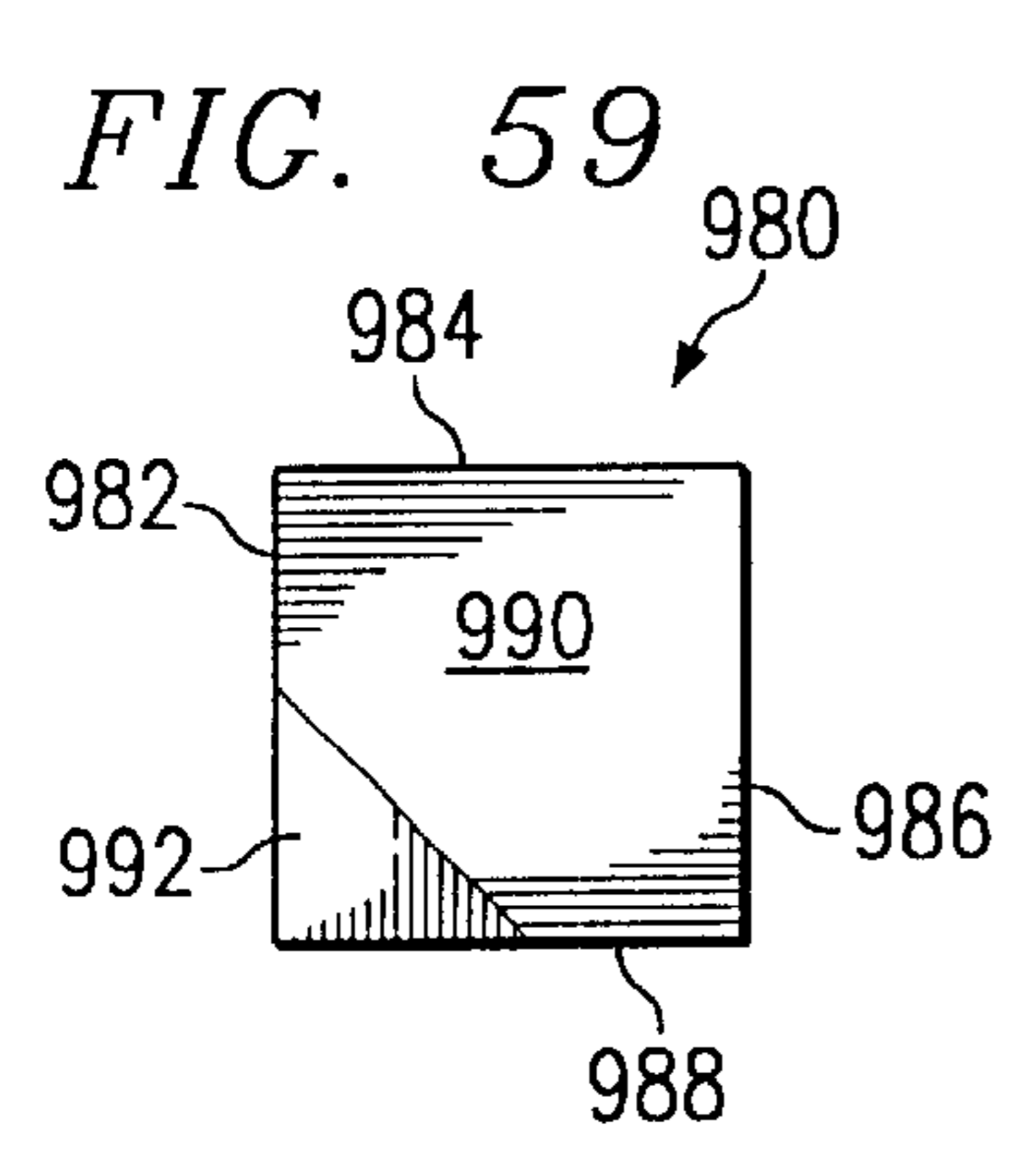


FIG. 59

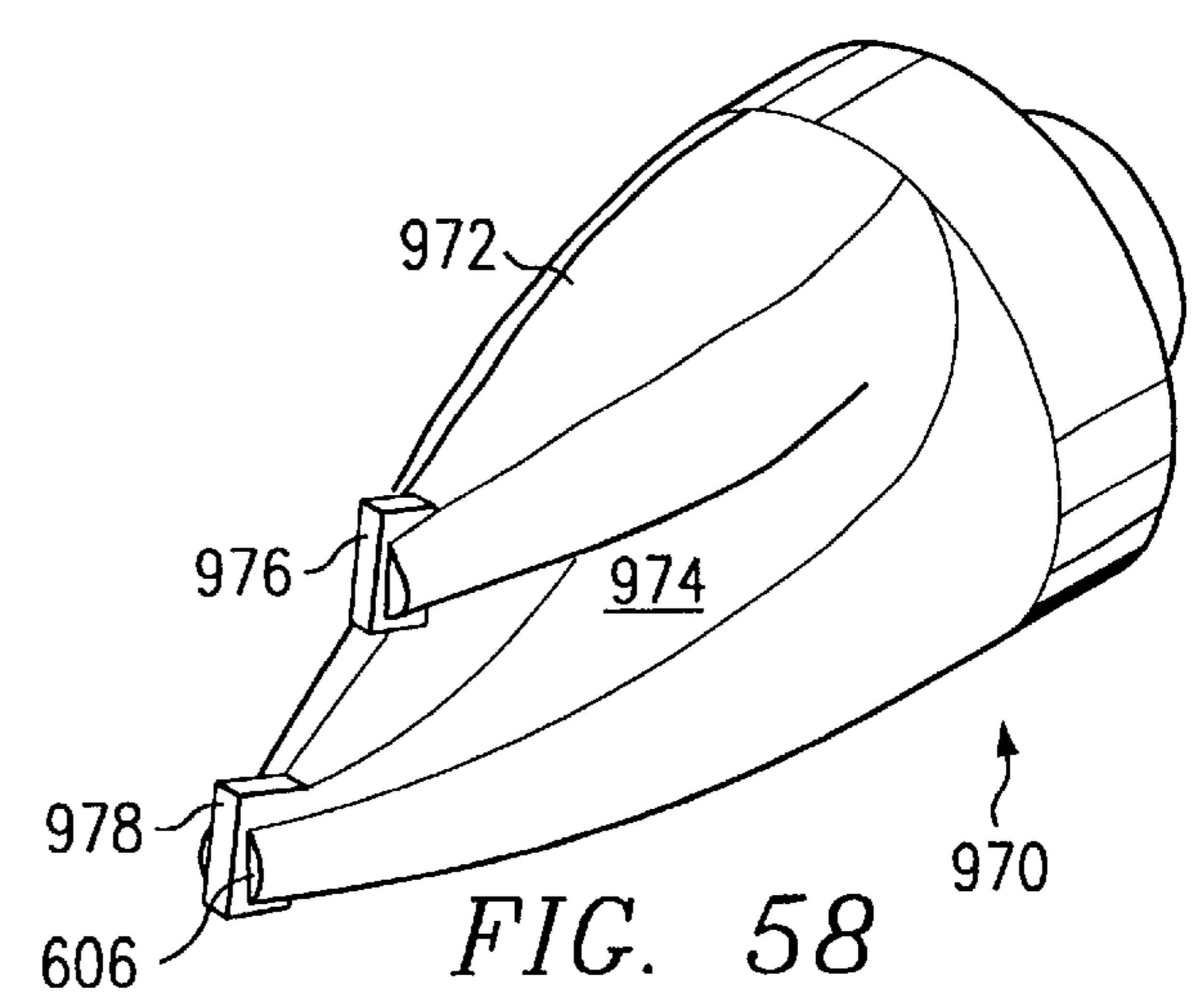


FIG. 58

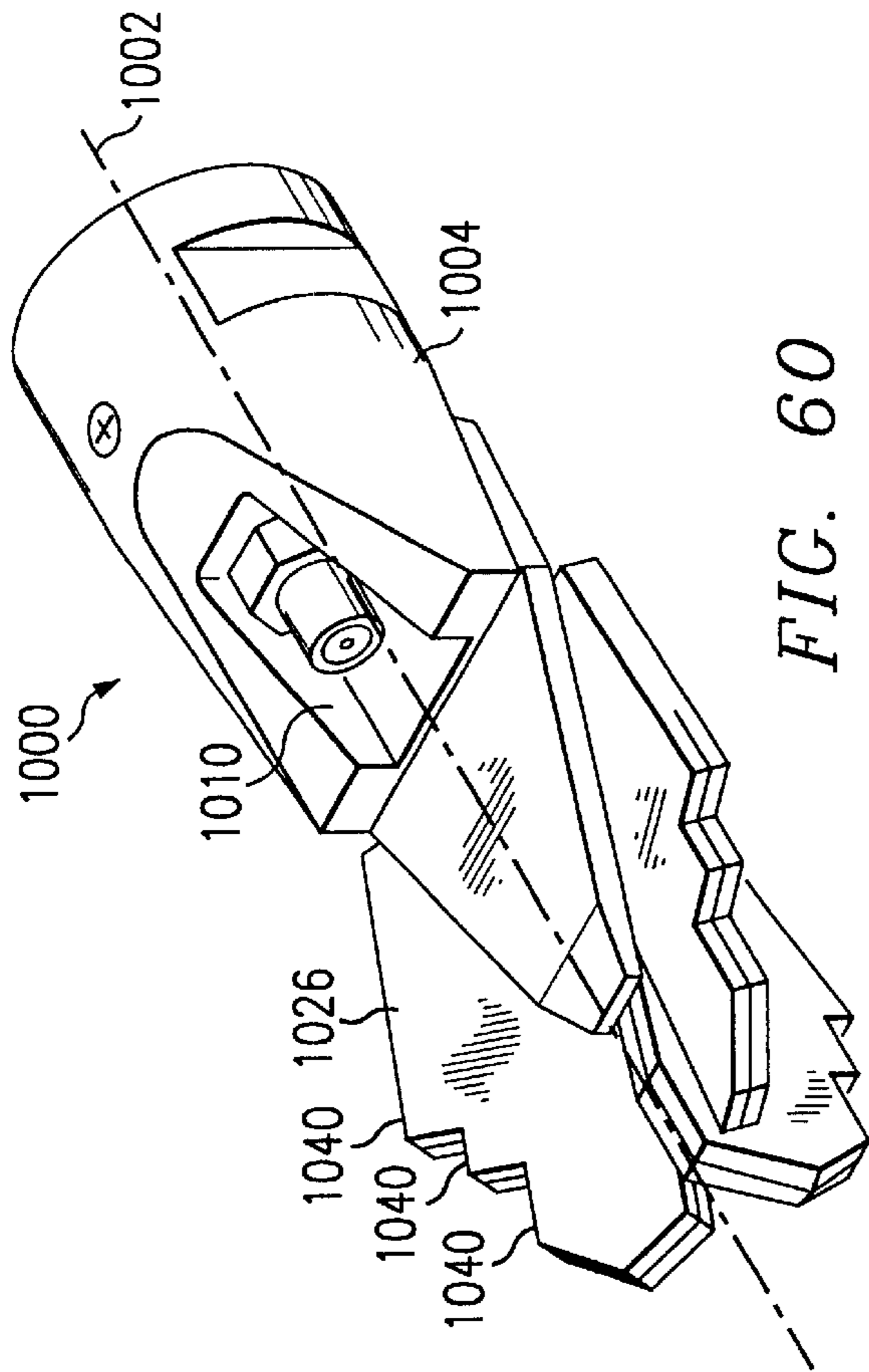


FIG. 60

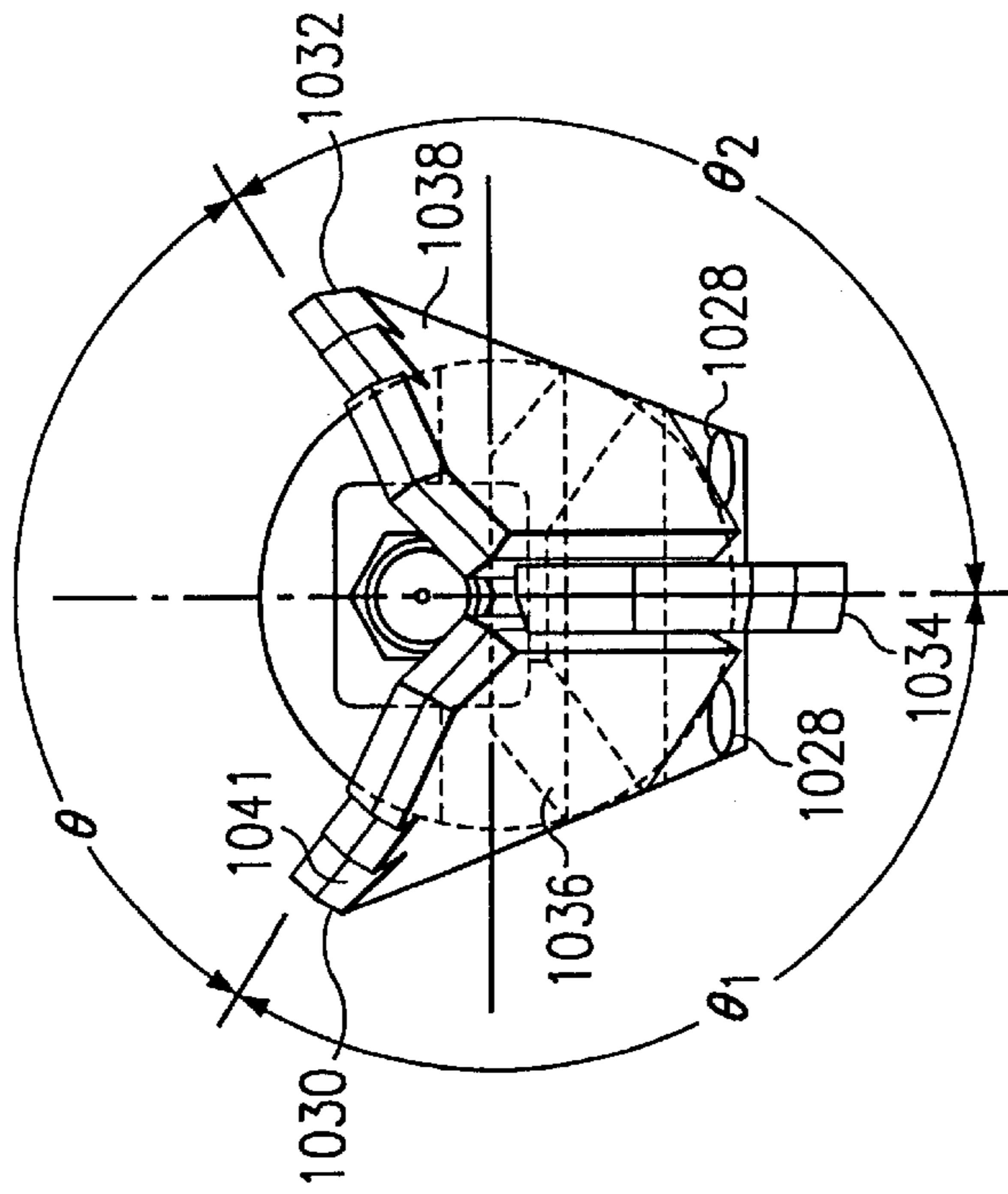


FIG. 61

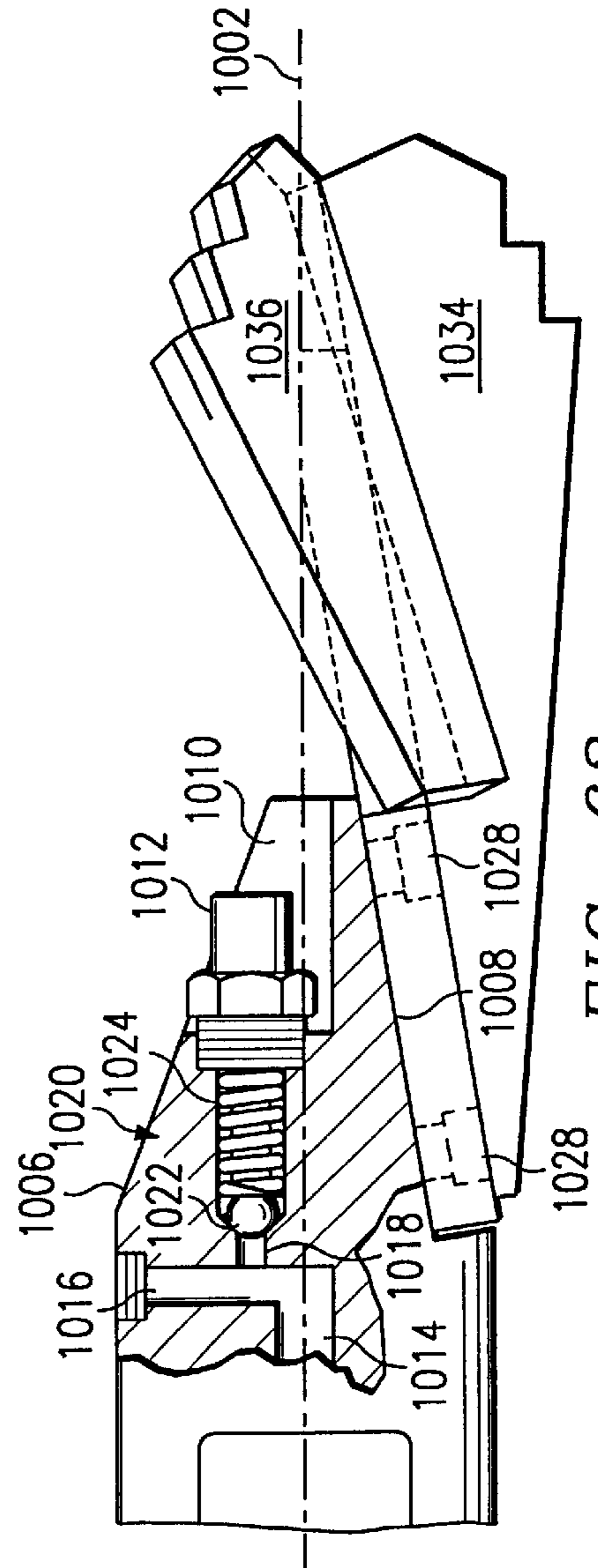
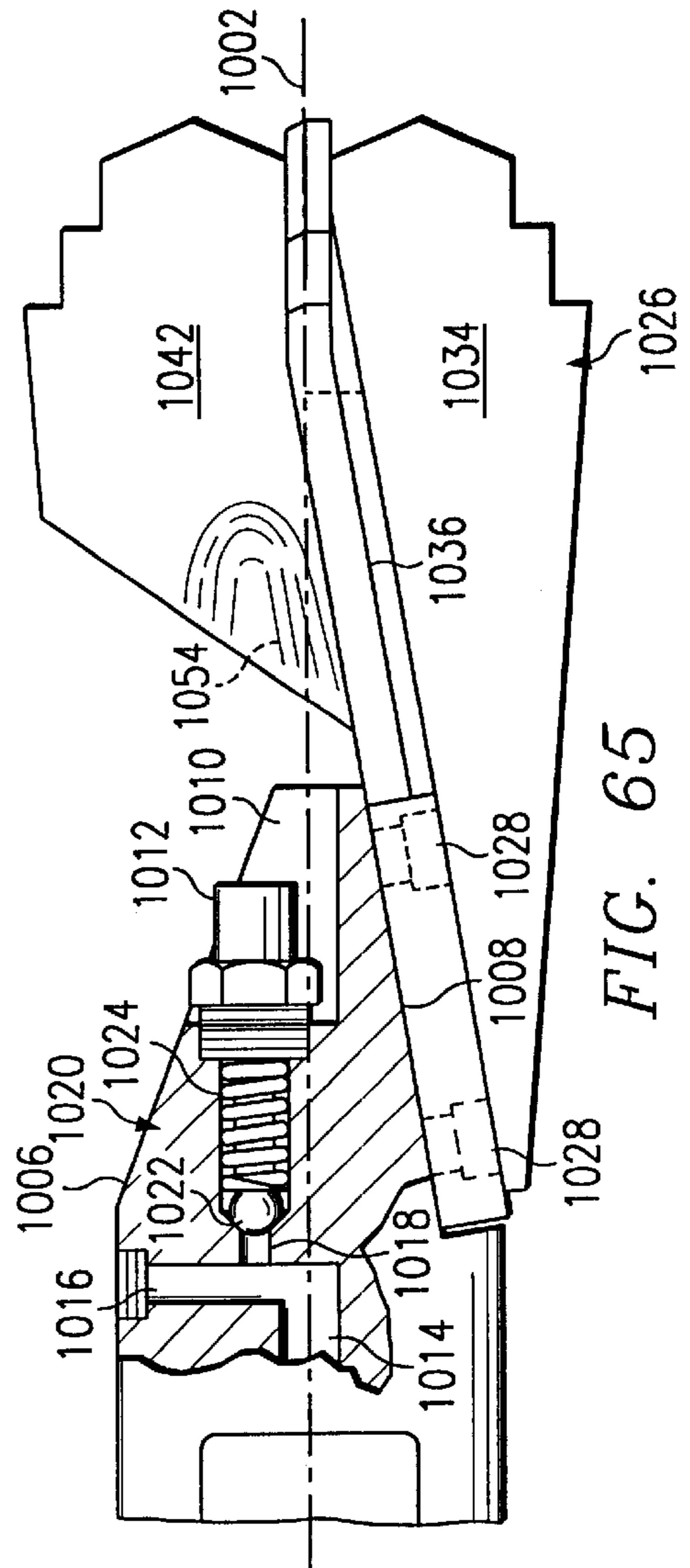
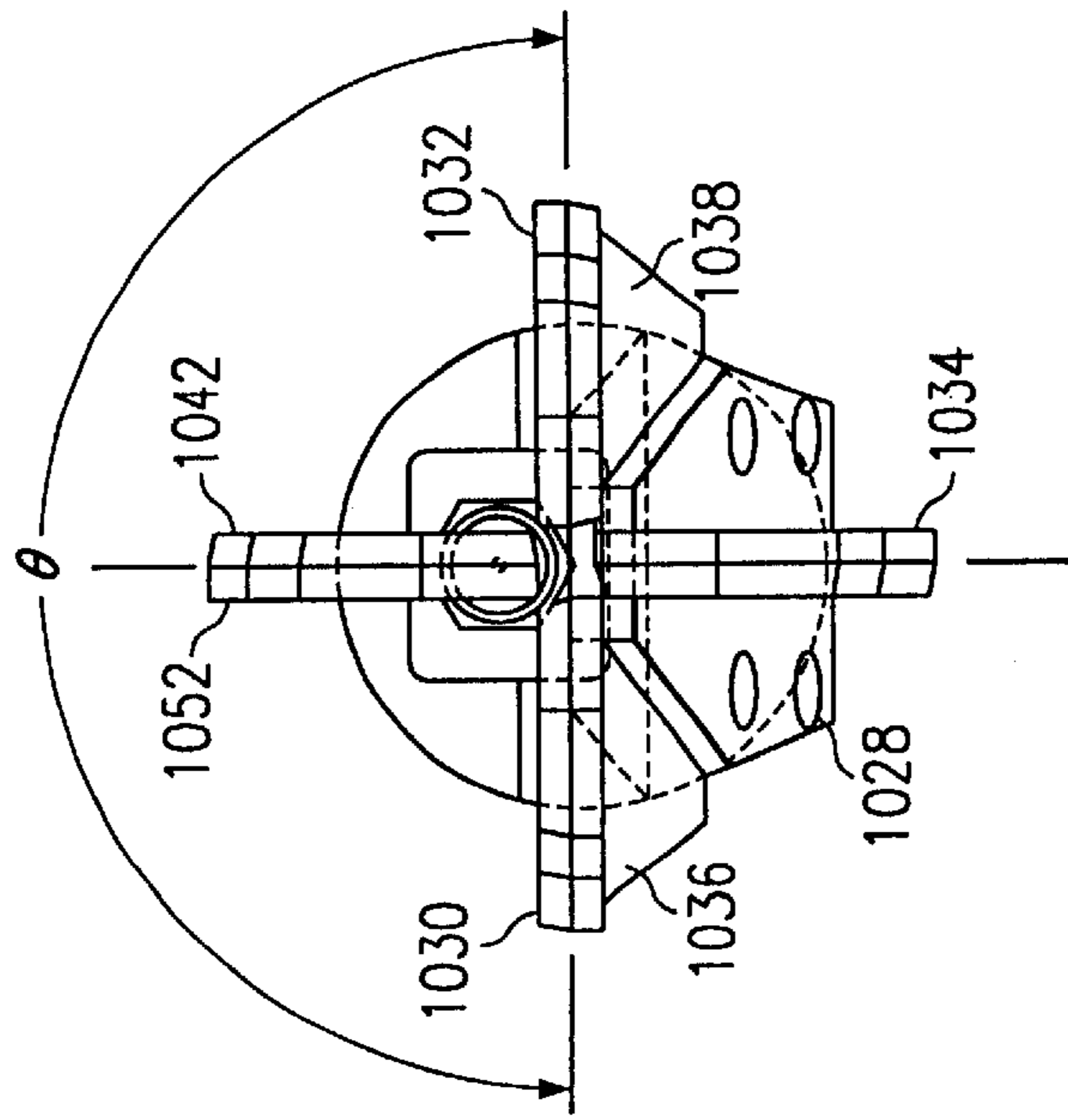
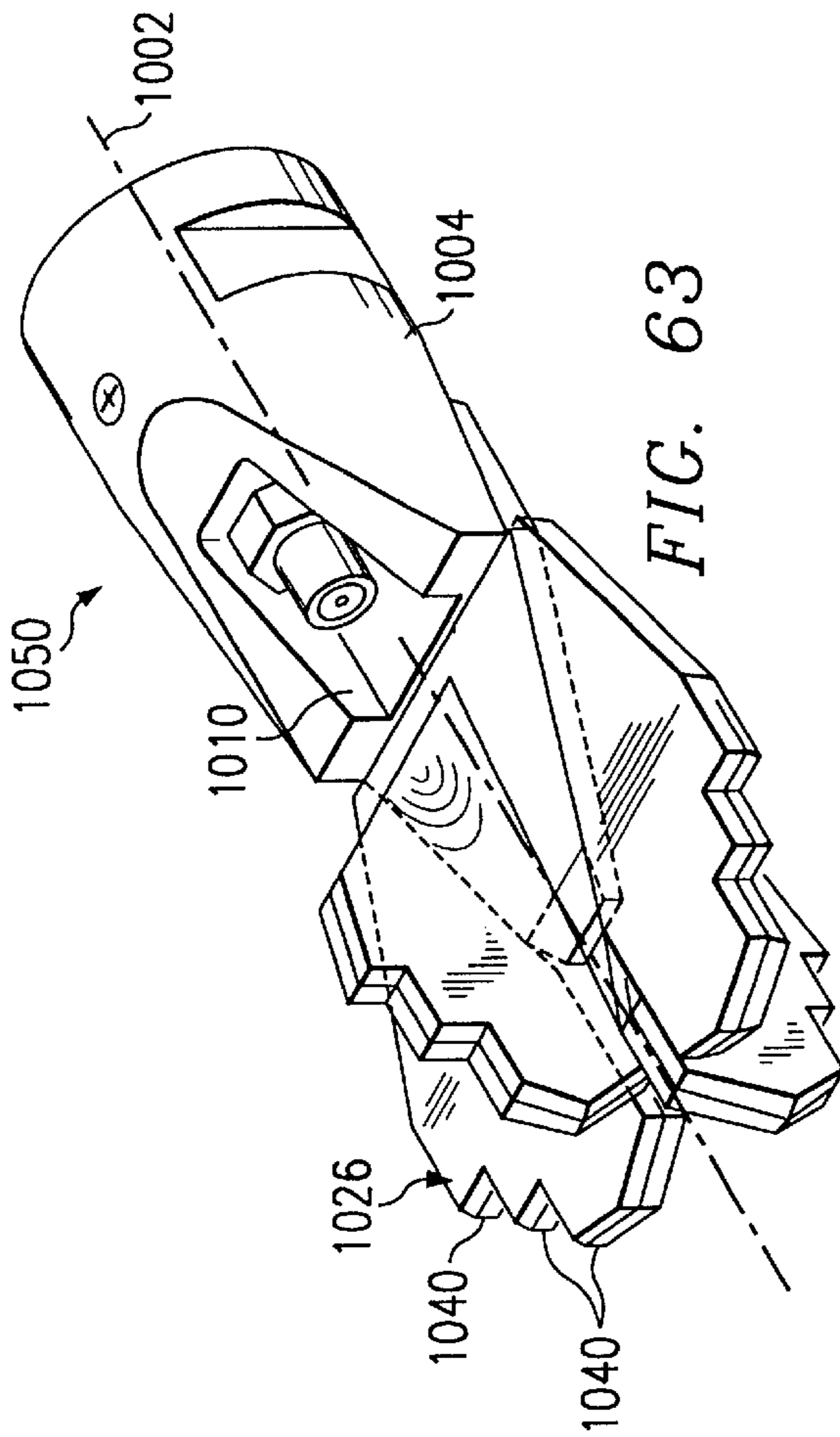
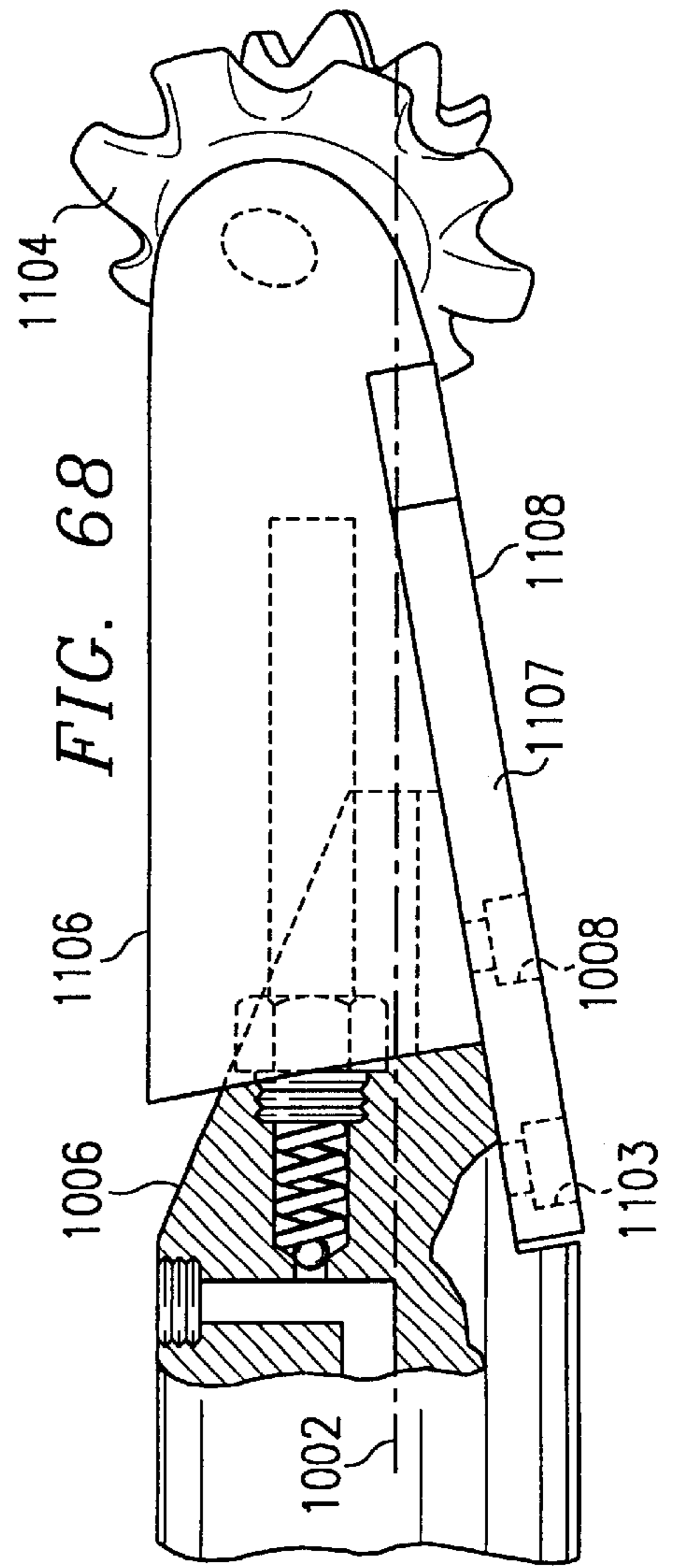
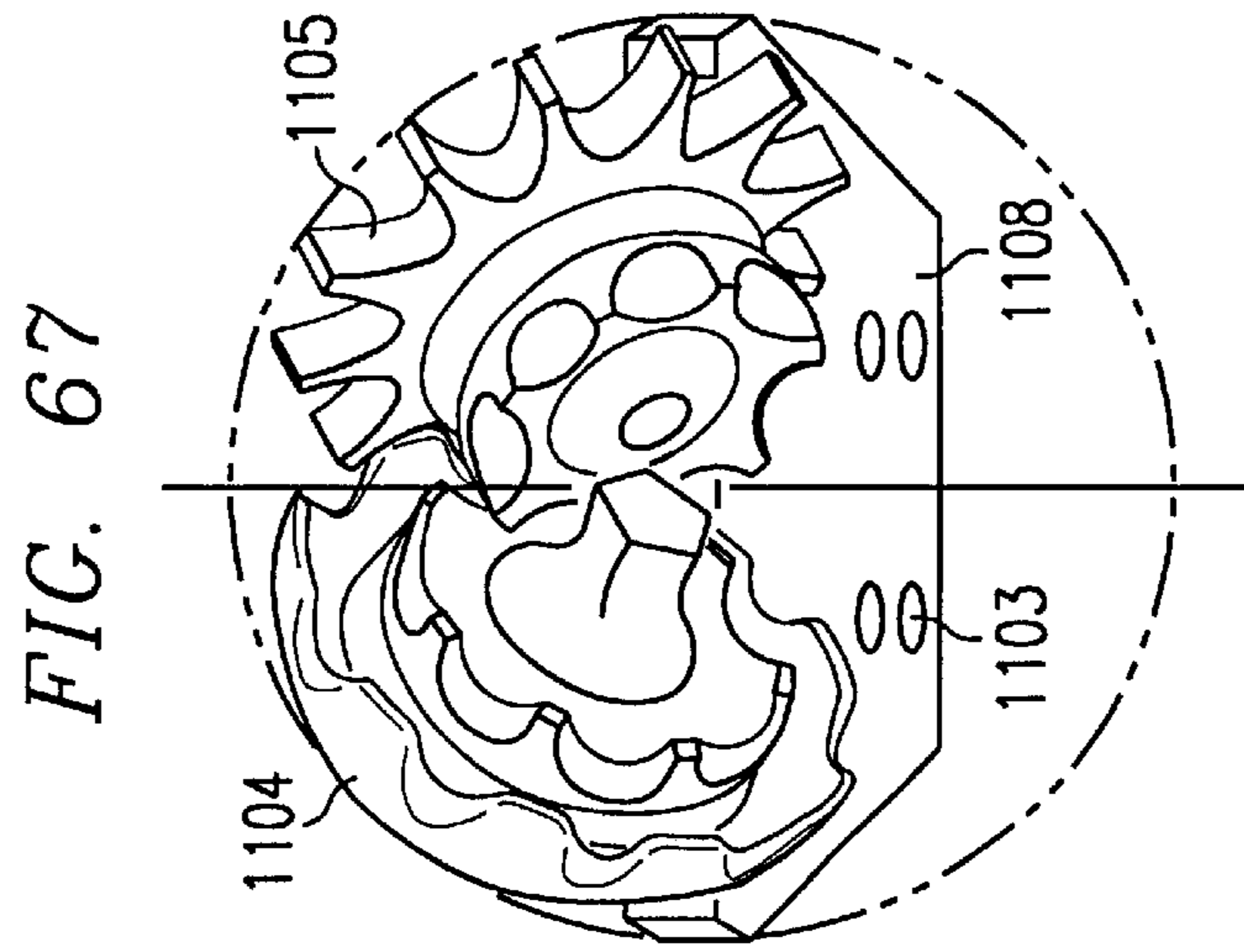
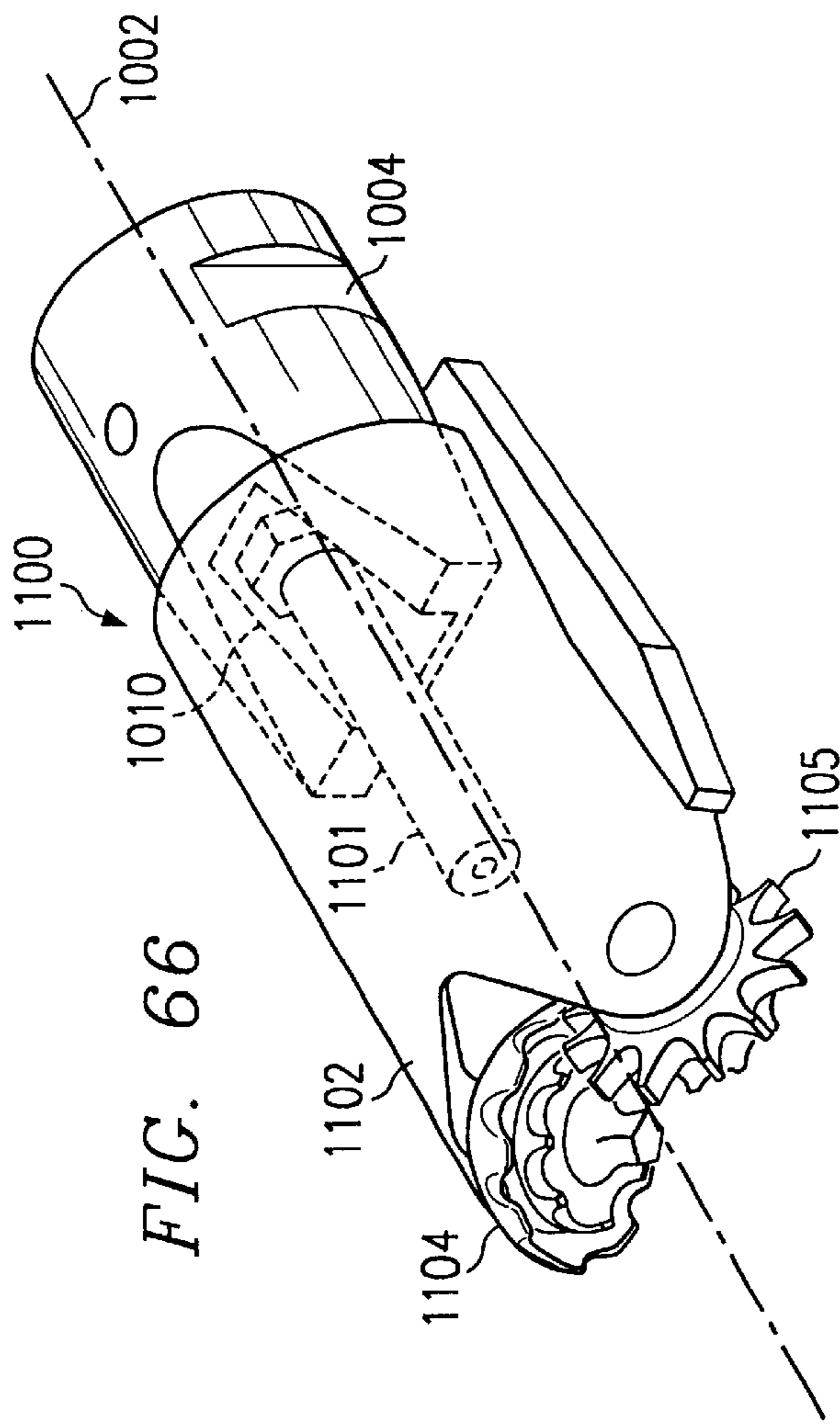
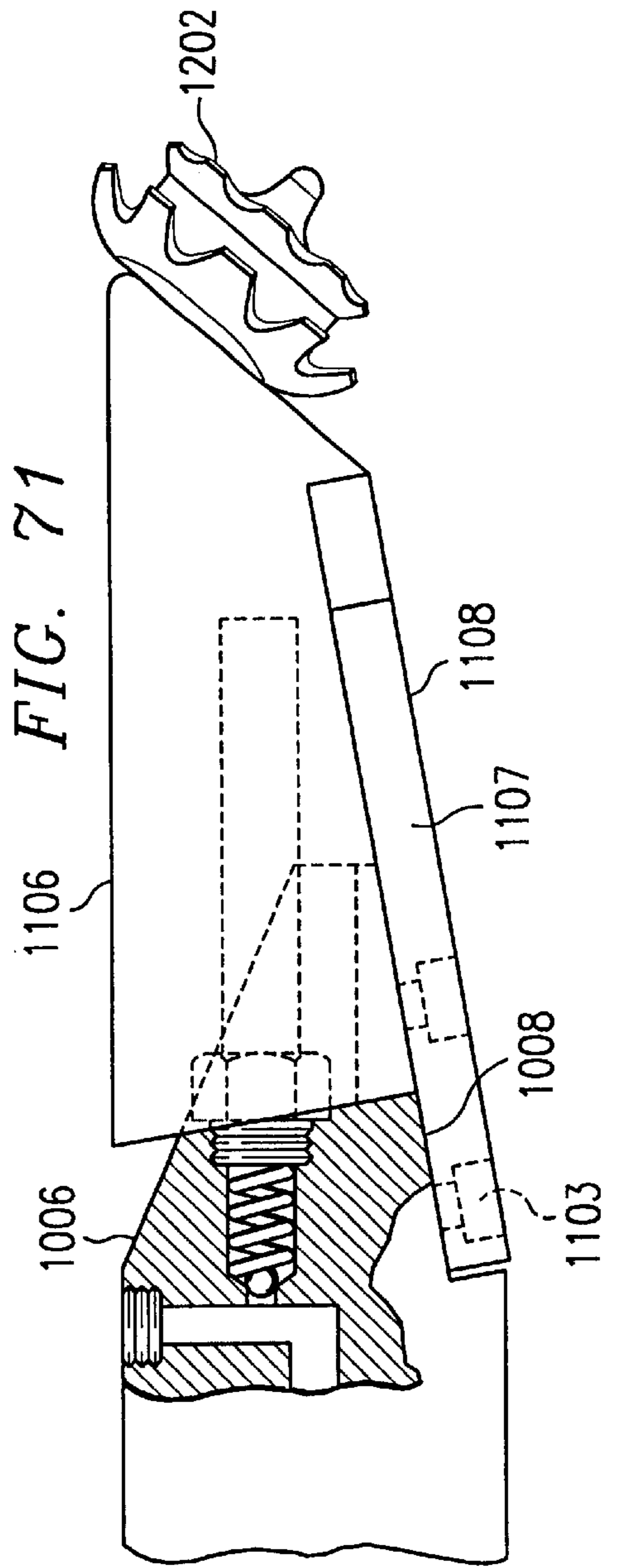
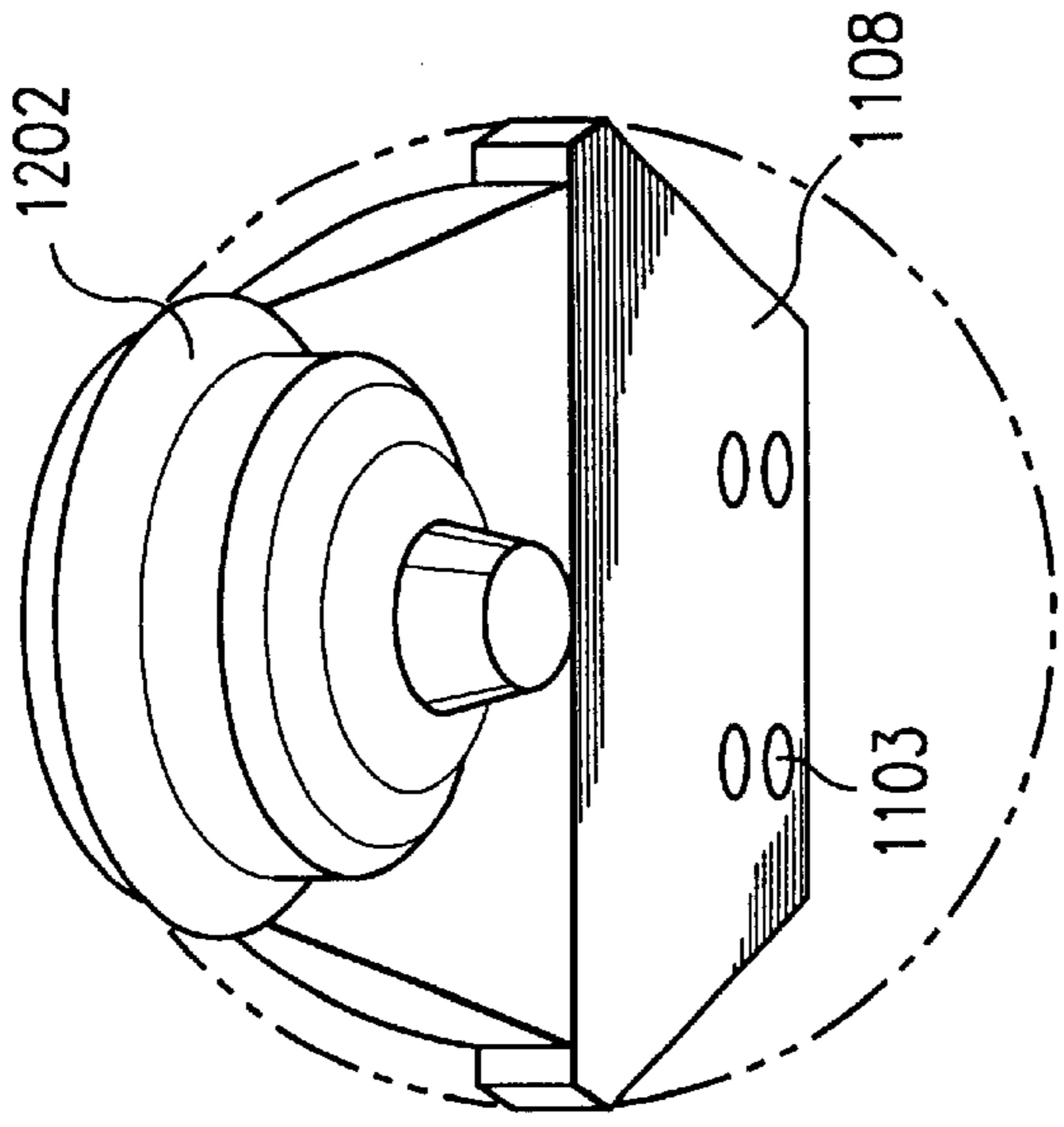
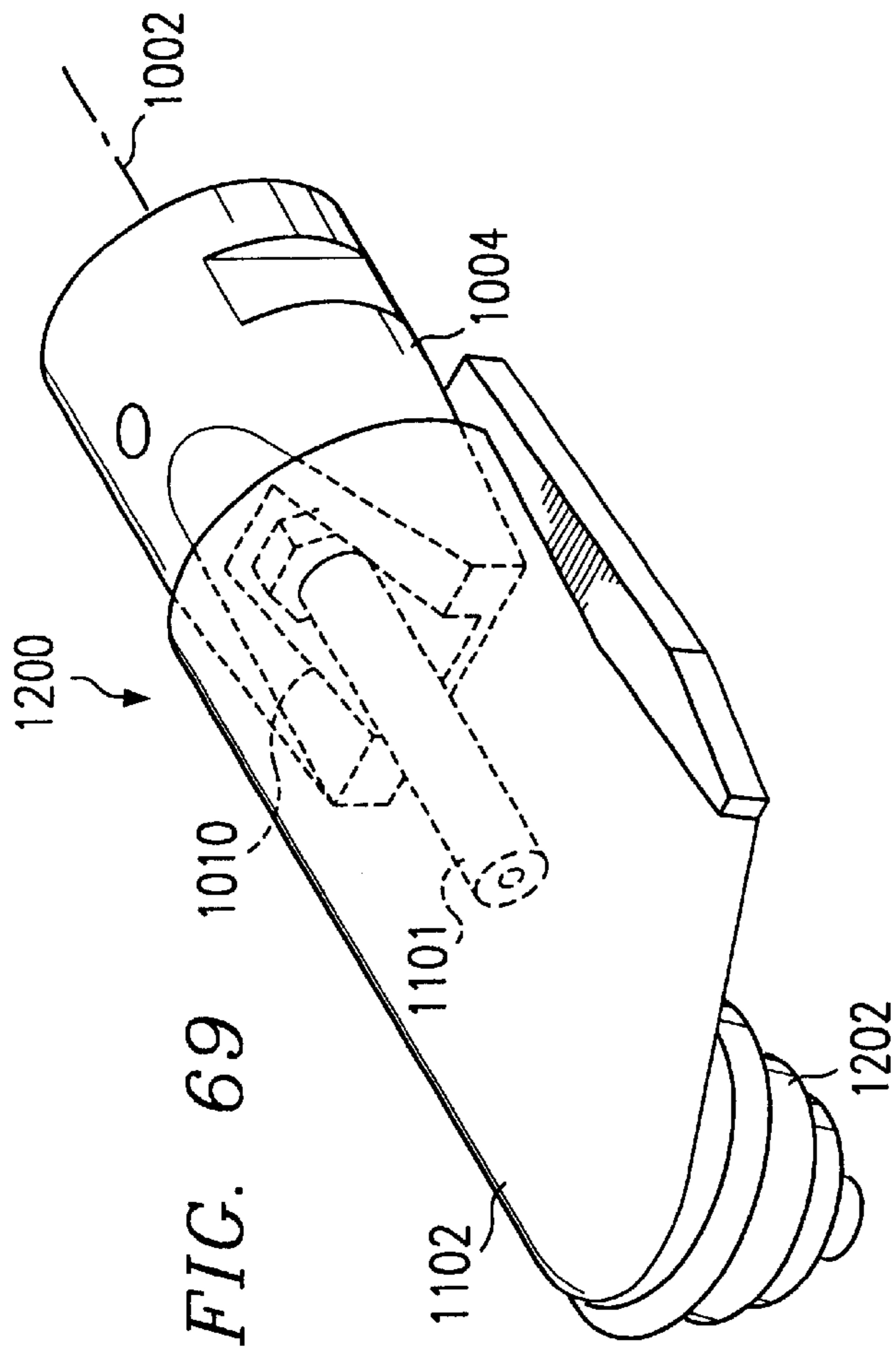
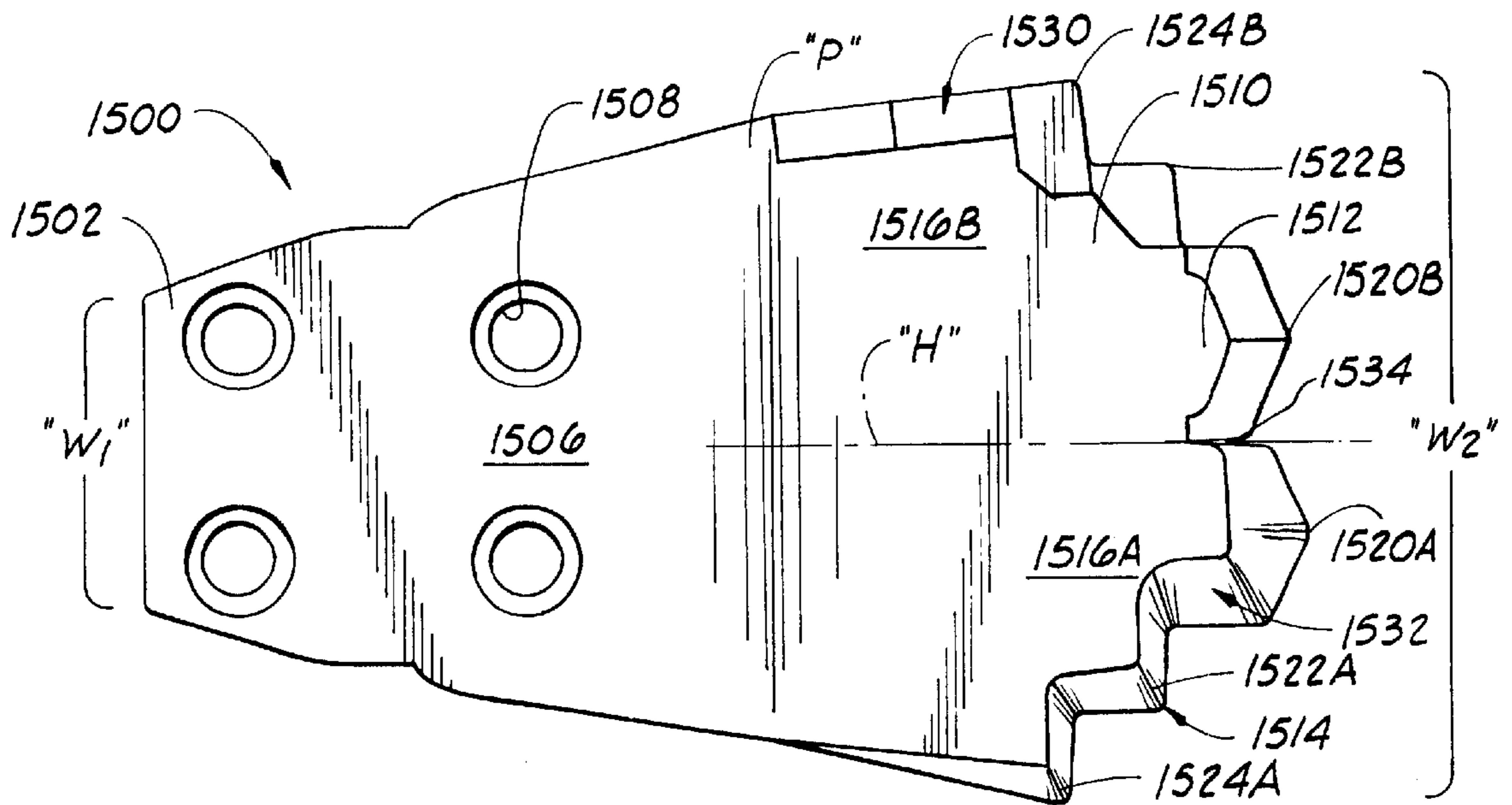
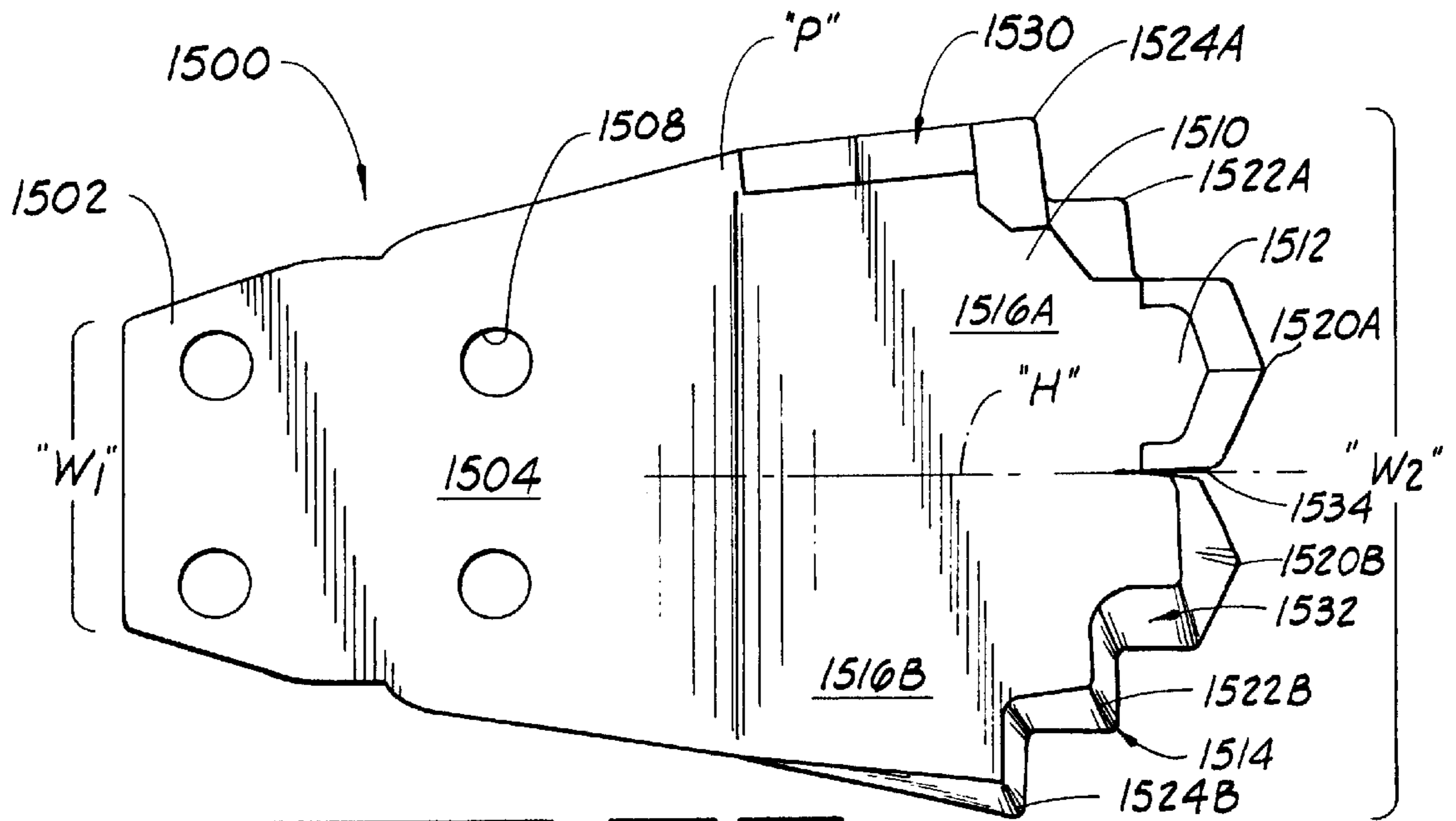


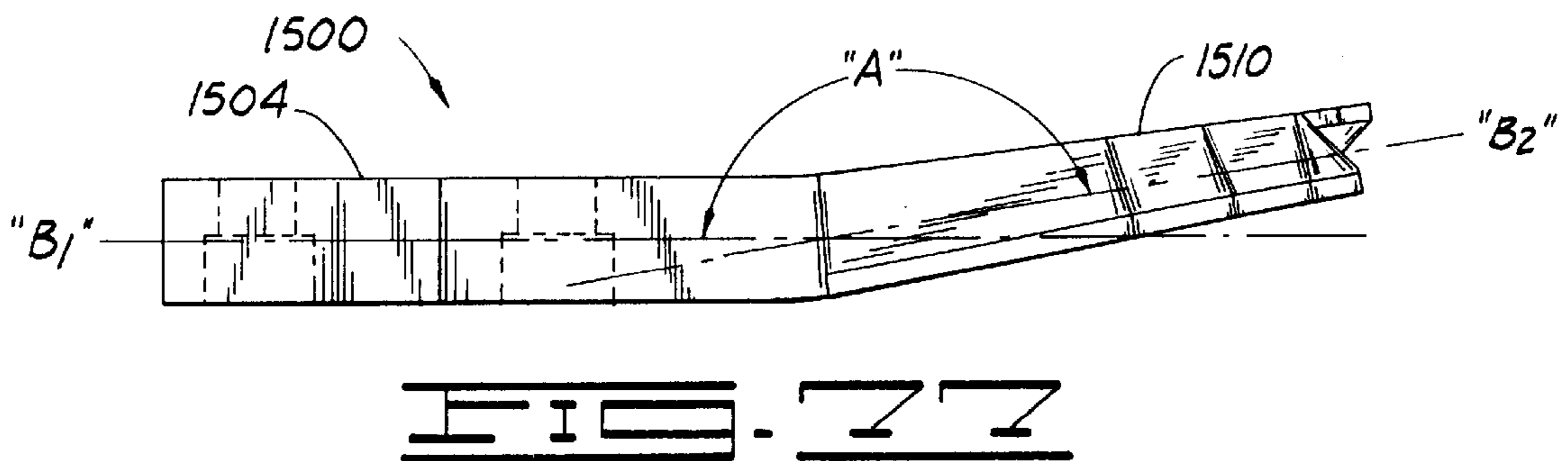
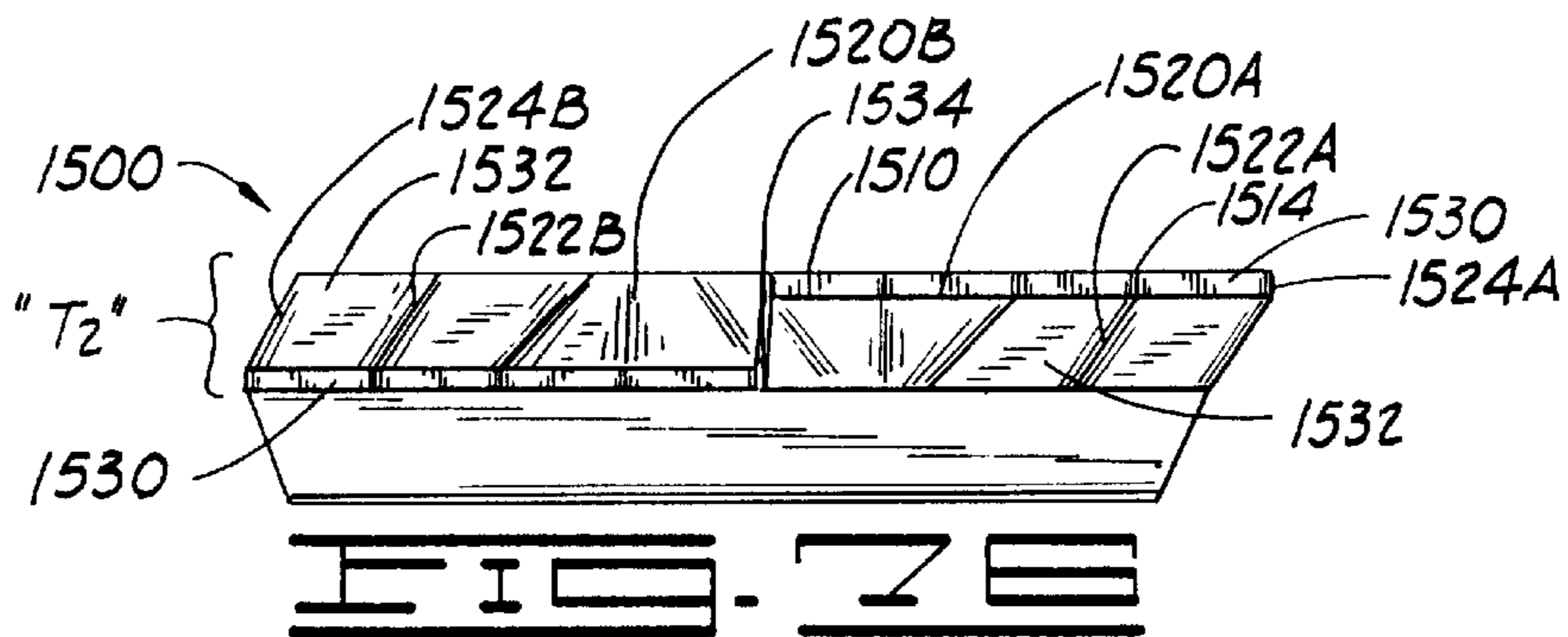
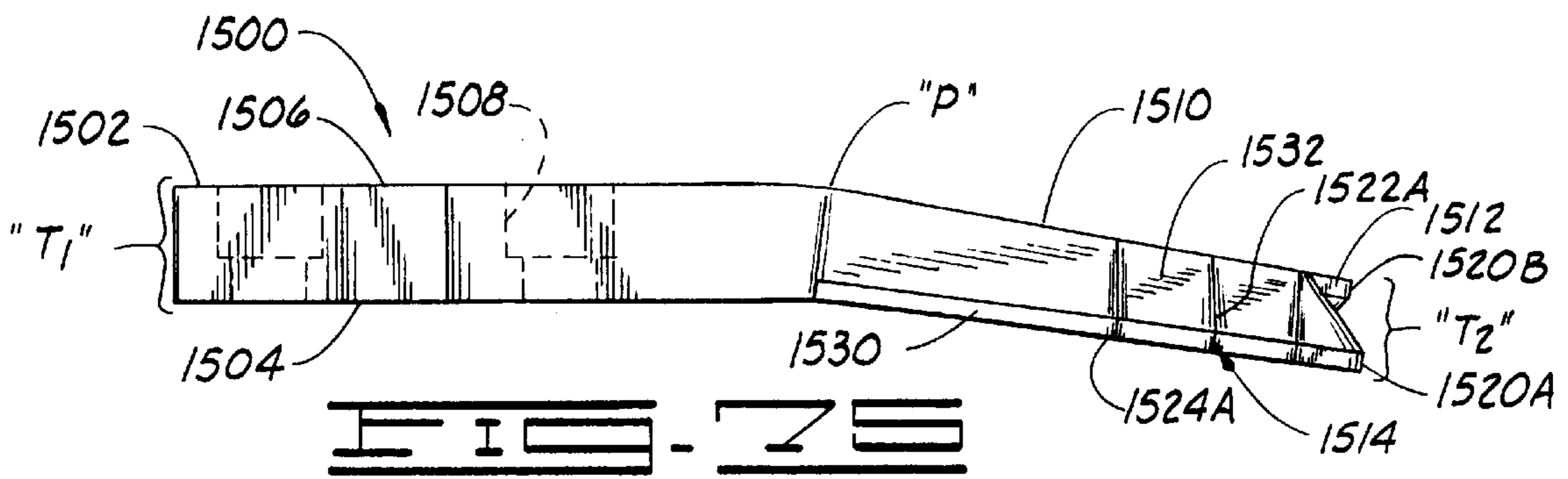
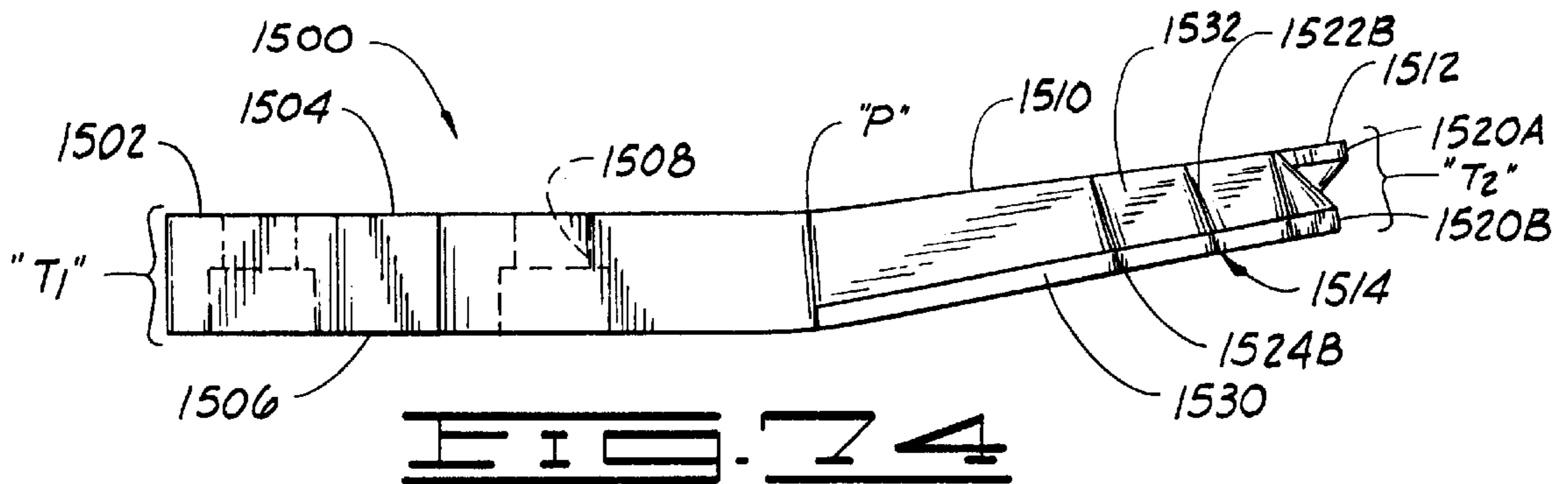
FIG. 62











DIRECTIONAL BORING HEAD WITH BLADE ASSEMBLY

Matter enclosed in heavy brackets [] appears in the original patent but forms no part of this reissue specification; matter printed in italics indicates the additions made by reissue.

CROSS-REFERENCE TO RELATED APPLICATIONS

This application is a continuation-in-part of application Ser. No. 163,756, entitled DIRECTIONAL MULTI-BLADE BORING HEAD, filed Dec. 9, 1993, now U.S. Pat. No. 5,392,868 which was a continuation-in-part of application Ser. No. 67,298, entitled DIRECTIONAL MULTI-BLADE BORING HEAD, filed on May 25, 1993, now U.S. Pat. No. 5,341,887, which was a continuation-in-part of application Ser. No. 857,167, entitled METHOD OF AND APPARATUS FOR DRILLING A HORIZONTAL CONTROLLED BOREHOLE IN THE EARTH, filed Mar. 25, 1992, now U.S. Pat. No. 5,242,026, which was a continuation-in-part of application Ser. No. [780,055, entitled METHOD OF AND APPARATUS FOR DRILLING A HORIZONTAL CONTROLLED BOREHOLE IN THE EARTH, filed Oct. 21, 1991, now abandoned,] 575,568, entitled APPARATUS FOR DRILLING A HORIZONTAL CONTROLLED BOREHOLE IN THE EARTH, filed Aug. 31, 1990, now U.S. Pat. No. 5,148,880, which was a continuation-in-part of application Ser. No. 211,889, entitled METHOD OF AND APPARATUS FOR DRILLING A HORIZONTAL CONTROLLED BOREHOLE IN THE EARTH, filed Jun. 27, 1988, now U.S. Pat. No. 4,953,638. The contents of each of these applications is incorporated herein by reference.

FIELD OF THE INVENTION

This invention relates to a directional boring machine with a steerable, fluid assisted mechanical boring head for drilling substantially horizontal boreholes under a roadway or other obstruction.

BACKGROUND OF THE INVENTION

Using boring machines with a steerable bit or head for drilling horizontal boreholes under a roadway or other obstruction is a well known practice. The process of providing such boreholes is generally referred to as "trenchless" digging, since an open trench is not required. A key to the operation of such a boring device is to have an effective steerable boring bit or head. If the bit is steerable, the operator can redirect the borehole along the proper path if it begins diverting from the desired path, and also allows the operator to steer around obstructions underground.

Many boring heads have been designed which have such a steering feature. However, there is a continuing need to develop boring heads which have better directional control, operate in a variety of soil conditions effectively and provide enhanced cutting action.

SUMMARY OF THE INVENTION

The present invention is directed to a directional boring machine comprising a frame, a rotary machine supported on the frame, a drill string operatively connected to the rotary machine to drive the rotation of the drill string; and a directional multi-blade boring head attached to the end of the drill string. The boring head comprises a body having a central axis of rotation and a blade assembly mounted on the body.

In one embodiment the blade assembly has a first blade defining a deflecting surface at an oblique angle to the central axis of rotation of the body and a second blade defining a deflecting surface at an oblique angle to the central axis of rotation of the body. The first and second blades extend at an angle relative to each other. At least one additional blade extends from the blade assembly between the deflecting surface. The deflecting surfaces of a first and second blade deflect the boring head as the boring machine advances the drill string without rotation, and the directional multi-blade boring head drills a relatively straight borehole as the boring machine advances the drill string with rotation.

In another embodiment, the blade assembly has a base and a blade extending from the base. The base is attached to the lower surface of the body of the boring head, and the base defines a first plane. The blade terminates in a forward end, and the blade defines a second plane intersecting the first plane of the base, so that the blade angles upward relative to the base. The blade has a thickness tapering gradually towards the forward end, and the forward end defines a plurality of teeth. Each tooth has a contact side and a back side, the contact side being the side that impacts the earth first as the boring head is rotated on the drill string, and the back side being the side opposite the contact side. The back side of each tooth is cut away forming a recess between the back side of the tooth and the surface being bored. Still further, the plurality of teeth includes a first set on a first side of the blade and a second set of teeth on the second side of the blade. The first set is substantially similar in size and configuration to the second set of teeth, but extends slightly forward of the second set of teeth.

BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1 is an elevational view of a boring machine as employed in practicing the method of the invention for drilling a borehole in the earth.

FIG. 2 is an elevational, enlarged scale view of the boring machine of FIG. 1.

FIG. 3 is a top plan view of the boring machine of FIGS. 1 and 2 taken along line 3—3 of FIG. 2.

FIG. 4 is an elevational, enlarged scale view of the boring machine of FIGS. 1 and 2 taken along line 4—4 of FIG. 2.

FIG. 5 is an elevational, cross-sectional, enlarged scale view taken along line 5—5 of FIG. 2 showing how the drill string is supported and rotationally oriented.

FIG. 6 is an enlarged, side elevational view of a boring head or downhole tool of FIG. 1 taken at (6) of FIG. 2.

FIG. 7 is top plan view of the boring head of FIG. 6.

FIG. 8 is an end view of the boring head of FIG. 6 taken along line 8—8 of FIG. 6.

FIG. 9 is a broken away perspective view of elements associated with a second alternative embodiment of a boring machine including a second alternative embodiment of a boring head.

FIG. 10 is a broken away perspective view of elements associated with the second alternative boring head of FIG. 9.

FIG. 11 is a side sectional view of the boring head of FIG. 10.

FIG. 12 is a cut-away view of the bottom flat surface of the boring head of FIGS. 10 and 11.

FIG. 13 is a front view of the boring head of FIGS. 10 and 11.

FIG. 14 is a top view of the boring head of FIGS. 10 and 11.

FIG. 15A is a broken away perspective view of elements associated with a frame of the second alternative embodiment of a boring machine.

FIG. 15B is a broken away partial perspective view of a connector link between a chain and a forward end of the frame of FIG. 15A.

FIG. 15C is a broken away partial perspective view of a connector link between a chain and a thread of the frame of FIG. 15A.

FIG. 16 is a broken away perspective view of a saver sub and an adapter assembly for a drill string.

FIG. 17 is a bottom view of a dirt blade assembly of FIG. 10.

FIG. 18 is a side view of the dirt blade assembly of FIG. 17.

FIG. 19 is a bottom view of a sand blade assembly of FIG. 10.

FIG. 20 is a side view of the sand blade assembly of FIG. 19.

FIG. 21 is a bottom view of an alternative sand blade assembly.

FIG. 22 is a side view of the sand blade assembly of FIG. 21.

FIG. 23 is an enlarged elevational view of a third alternative embodiment of a boring head and of a portion of a drill string.

FIG. 24 is a top view of the boring head of FIG. 23.

FIG. 25 is a front view of the boring head of FIG. 23 take along line 25—25 of FIG. 23.

FIG. 26 is a fragmented section view of the blade of the boring head of FIG. 23 illustrating the wear resistant material on the blade.

FIG. 27 is an enlarged partial view of FIG. 24 showing a ball in a check valve assembly which is disposed inside the fluid passageway and adjacent the nozzle.

FIGS. 27A is a perspective view of FIG. 24 showing a ball in a check valve assembly which is disposed inside the fluid passageway and adjacent the nozzle.

FIG. 28 is a partial view of the boring head of FIG. 23 including an alternative embodiment of a blade.

FIG. 29 is a top view of a hard soil/soft rock tapered blade assembly.

FIG. 30 is a side view of the hard soil/soft rock tapered blade assembly of FIG. 29.

FIG. 31 is an opposite side view of the hard soil/soft rock tapered blade assembly of FIG. 29.

FIG. 32 is a bottom view of a spade-like blade assembly.

FIG. 33 is a side view of the spade-like blade assembly of FIG. 32.

FIG. 34 is a bottom view of a relatively wide blade assembly.

FIG. 35 is a side view of the relatively wide blade assembly of FIG. 34;

FIGS. 36—59 illustrate various alternative boring heads that can be used;

FIG. 60 is a perspective view of another embodiment of the directional multiblade boring head;

FIG. 61 is a front view of the boring head of FIG. 60;

FIG. 62 is a side view of the boring head of FIG. 60;

FIG. 63 is a perspective view of another embodiment of the directional multiblade boring head;

FIG. 64 is a front view of the boring head of FIG. 63;

FIG. 65 is a side view of the boring head of FIG. 63;

FIG. 66 is a perspective view of another embodiment of the directional boring head;

FIG. 67 is an end view of the boring head of FIG. 66;

FIG. 68 is a side view of the boring head of FIG. 66;

FIG. 69 is a perspective view of a directional boring head forming a second embodiment of the present invention;

FIG. 70 is an end view of the boring head of FIG. 69;

FIG. 71 is a side view of the boring head of FIG. 69;

FIG. 72 is a plan view of an alternative blade assembly for the directional boring head;

FIG. 73 is a bottom view of the blade assembly shown in FIG. 72;

FIG. 74 is an elevational view of a first side of the blade assembly shown in FIG. 72;

FIG. 75 is an elevational view of the opposite side of the blade assembly shown in FIG. 72;

FIG. 76 is an elevational front end view of the blade assembly shown in FIG. 72; and

FIG. 77 is another side elevational view illustrating the angle of the blade portion of the assembly relative to the base portion.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENT

Referring to the drawings, and first to FIG. 1, the environment in which the apparatus of this invention is used is illustrated. The boring machine is generally indicated by the numeral 10. The machine 10 is shown resting on earth's surface 12 and in position for forming a borehole 14 underneath an obstruction on the earth such as a roadway 16. As shown in FIG. 1, by using the extended range boring machine 10, the direction of the borehole can be changed as the borehole passes under the roadway 16. This illustrates how the machine 10 can be utilized to form a borehole 14 under an obstruction without first digging a deep ditch in which to place a horizontal boring machine, and also without having to dig a deep ditch on the opposite side of the obstruction where the borehole is to be received. While the method of drilling a borehole and the machine used therewith will be described as showing the borehole being drilled from the earth's surface 12, it can be appreciated that the machine 10 can be used in a shallow ditch if desired. It should be kept in mind, however, that the main emphasis of the method and machine of this invention is that of drilling a borehole in which the direction of the borehole can be changed during the drilling process. These methods could be applied on other types of drilling machines as well.

In conventional fashion, the drill string 44 is simultaneously rotated and advanced by means of the boring machine 10 to establish a borehole in the earth. The drilling operation, wherein the pipe 42 of FIG. 2 is simultaneously rotated and axially advanced, is continued until a change in direction of the borehole is desired. This typically occurs when the borehole is near a desired depth and when the borehole is to be moved substantially horizontal for a distance. In order to change the direction of the borehole, the following sequence is employed:

1. The rotation of the drill string 44 is stopped.
2. The rotational position of the drill string 44 is oriented so that the blade assembly 72, 172, 172', 272, 372, 472, 572, 672 or 772 of the boring head 58, 158 or 358 is inclined at an acute angle relative to the longitudinal axis of the drill string and towards the new direction of the borehole desired.

3. The drill string is axially advanced without rotation to axially advance the boring head **58**, **158** or **358** a short distance such that the blade assembly moves the boring head in the earth towards the new desired direction.
4. Simultaneous rotation and axial advancement of the drill string is resumed for a short distance.
5. Sequentially repeating steps 1, 2, 3 and 4, until the direction of the borehole is in the new direction desired.

Thereafter, the boring head **58**, **158** or **358** is axially advanced and simultaneously rotated until it is again desirable to change directions. This typically can occur when a borehole has reached a point adjacent the opposite side of the obstruction under which the borehole is being drilled. At this stage in the drilling of the borehole, it is desirable to have the direction of the borehole inclined upwardly so that the borehole will emerge at the surface of the earth on the opposite side of the obstruction.

To again change the direction of the borehole, the same sequence is repeated. That is, the rotation of drill string **44** is stopped, the orientation of the drill string is corrected so that the blade assembly of the boring head is inclined in the newly desired direction (that is, in this example, upwardly), the drill string is axially advanced without rotation a short distance, the drill string is then rotated and axially advanced a short distance, and the sequence is repeated until the new direction of drilling the borehole is attained. After the new direction is attained, the borehole is drilled by simultaneously rotating and advancing the drill string until the borehole is completed. Referring to FIGS. **2** and **3**, more details of the boring machine are illustrated. In particular, the machine **10**, which is utilized for practicing a method of this invention, includes a frame **18** having a forward end **18A** and a rearward end **18B** and supportable on the earth's surface. The frame **18** of FIGS. **2** and **3** and the frame **118** of FIGS. **15A-15C** are preferably operated from a surface launch position which eliminates the need to dig a pit. Also, the frames **18** and **118** provide an elongated linear travel pathway. As best seen in FIGS. **4**, **5** and **15A** the linear pathway is preferably provided by spaced apart parallel channels **20** and **22** or **120** and **122**.

Rotary machine **24** of FIGS. **2**, **3** and **4** is supported on the frame and in the travel path. More specifically, rotary machine **24** is supported on wheels **26** of FIG. **4** which are received within channels **20** and **22**.

The drill string **44** includes a plurality of drill pipes **42** each having a male thread at one end and a female threaded opening at the other end. Each pipe is attachable at one end to rotary machine **24** and to each other in series to form drill string **44**. As seen in FIGS. **2** and **3**, the rearward end of drill string **44** can be attached to the rotary machine **24**. The drill string **44** can also include an adapter **230** and saver subs **232**, as in FIGS. **9** and **16**. Thread caps **234** and **236** are used to protect the drill pipe and are removed prior to insertion into the drill string.

The rotary machine **24** is supplied by energy such as by hydraulic pressure through hoses **28** and **30** of FIGS. **2** and **4**. This hydraulic energy can be supplied by an engine driven trailer mounted hydraulic pump (not shown) which preferably is positioned on the earth's surface adjacent the drilling machine. The use of hydraulic energy is by example only. Alternatively, the rotary machine or drive **24** could be operated by electrical energy, an engine or the like. The use of hydraulic energy supplied by a trailer mounted engine driven pump is preferred, however, because of the durability and dependability of hydraulically operated systems. Third hose **32** of FIGS. **2** and **4** is used for supplying fluid for a purpose to be described subsequently.

By means of control levers **34** of FIG. **2**, hydraulic energy can be controlled to cause rotary machine **24** to be linearly moved in the pathway provided by channels **20** and **22** of FIGS. **4** and **5** or **120** and **122** of FIG. **15A**, and at the same time to cause a drill pipe to be axially rotated. The linear advancement or withdrawal of the rotary machine **24** is accomplished by means of the chain **36** of FIG. **2** or the chain **136** of FIG. **15A** which is attached at one end to the frame front end **18A** or **118A** and at the other end to the frame rearward end **18B** or **118B**. The chain **36** passes over the cog wheel **38**, the rotation of which is controlled by one of the levers **34** to connect hydraulic power to a hydraulic motor (not shown) which rotates the cog wheel **38** in the forward or in the rearward direction or which maintains it in a stationary position.

As seen in FIGS. **2** and **3**, extending from the forward end of the rotary machine **24** is a drive spindle or shaft **40** which has means to receive the male or female threaded end of the drill pipe **42**. Upper or uphole end **60** of the drill string is attached to shaft **40** (FIG. **2**), that is, to the rotary machine **24**. The saver sub **232**, attached to the shaft **40** with a thread retaining compound such as Loctite® RC/680 is a replaceable protector ("saver") of the threads on the shaft **40**.

A plurality of drill pipes **42** are employed and, when the drill pipes are assembled together, they form the drill string **44** as seen in FIG. **1**. The drill pipes **42** are of lengths to fit a particular size drill frame **18** or **118**, such as 5 feet, 10 feet, 12 feet and/or 20 feet. When sequentially joined the drill pipes **42** can form a drill string of a length determined by the length of the hole to be bored. The preferred embodiments generally have a distance capability of over 400 feet in many soil conditions.

As seen in FIGS. **2** and **5**, adjacent the forward end **18A** of the frame is a drill pipe support **46**. The drill pipe support **46** maintains the drill pipe **42** in a straight line parallel to the guide path formed by the channels **20** and **22**. The drill pipe support can include a sight **48**, the purpose of which will be described subsequently.

Positioned adjacent the forward and rearward ends of the frames **18** or **118** are jacks **50** or **150** by which the elevation of the frame relative to the earth's surface **12** may be adjusted. In addition, at front end **18A** of the frame are opposed stakes **52** and **54** which are slidably received by the frame front end. The stakes **52** and **54** may be driven in the earth's surface so as to anchor the machine during the drilling operation.

Also illustrated in FIG. **15A** are a flange lock bolt **117** and a flange lock nut **119** for attaching the rearward end of the rear cross-member **118B** of the frame **118** to the channels **120** and **122**. Also, as seen in FIG. **15C**, the thread **113** (attached to the rearward end **118B** by nuts **111**) adjustably engages the chain **136** via the connector link **137**. In addition, as seen in FIG. **15B**, the opposite end of the chain **136** also engages the forward end **118A** of the frame **118** via the second connector link **137**.

Affixed to the downhole end **56** of the drill string **44** is a bit or downhole tool generally indicated by the numeral **58** and referred to hereinafter as a boring head. The boring head is best seen in FIGS. **6**, **7** and **8**.

The boring head **58** includes body portion **62** which has rearward end portion **64** and a forward end portion **66**. The rearward end portion **64** of the body **62** includes an internally threaded recess **68** which receives the external threads **70** of the drill string forward end **56**.

The blades or blade assemblies **72**, **172**, **172'**, **272**, **272'**, **372**, **472**, **572**, **672** and **772** can be affixed to the bodies **62**, **162** or **362** of the boring head **58**. The plane of the blade

assemblies **72**, **172**, **172'**, **272**, **272'**, **372**, **472**, **572**, **672** and **772** is inclined at an acute angle to the axis X—X of the boring head's internally threaded recess **68**. Axis X—X is also the longitudinal axis of the drill string **44** or the forward most drill pipe **42**. That is, the axis X—X is the axis of the portion of the drill string immediately adjacent and rearward of the boring head.

The blade assemblies are preferably sharpened at their outer forward ends **72A**, **172A**, **272A**, **372A**, **472A**, **572A**, **672A** and **772A**. When rotated, the blade assemblies cut a circular pattern to form walls **6** or **6'** at end **4** of borehole **14** as illustrated in FIG. **6**.

The boring head bodies **62**, **162** and **362** have fluid passageway **78** therethrough connecting to jet or nozzle **76**. The fluid passageway **78** is in turn connected to the interior of the tubular drill string **44**. As previously stated with reference to FIG. **2**, the hose **32** provides means for conveying fluid under pressure to the boring machine **24**. This fluid is connected to the interior of the drill pipe **42** and thereby to the entire drill string **44**, and, thus, to the interior of the bodies **62**, **162** and **362**. The fluid is ejected from the boring head bodies **62**, **162** and **362** through the nozzle **76** to aid in the drilling action. That is, fluid is ejected from the nozzle **76** to cool and lubricate the blade assemblies **72**, **172**, **172'**, **272**, **272'**, **372**, **472**, **572**, **672** or **772** and flush away cuttings formed by the blade as it bores through the earth by forming a slurry of cuttings.

The nozzle **76** in this case refers to any of a plurality of fluid nozzles designed for different soil conditions. For example, one can use one nozzle for soft dirt or hard dirt and then interchange that with another nozzle for sand. Also, one can interchange nozzles to vary the flow rate.

As best seen in FIGS. **6** and **7**, the blade assembly **72** includes an outer surface which is substantially flat. Also, the blade assembly **72** is rectangular as illustrated.

The preferred boring head improves the ability to make rapid steering corrections. The boring head bodies **62**, **162** and **362** include a tapered portion, between the rearward end **64**, **164** and **364**, and the forward ends **66**, **166** and **366**, which tapers toward the forward end of the body. Also, this surface of the body defines an outer surface which is free of cutters, except for the blade.

Although not necessary, the body **62** has a substantially triangular cross-section defined by a converging flat top surface **90** and flat bottom surface **92**. Also, the blade assembly **72** is fixed to the bottom flat surface of the boring head body and extends axially beyond forward end **66** of the body **62** at an acute angle. This angled extension, in conjunction with the converging top surface **90** of the boring head body, defines a relief space **8** in which a fluid nozzle **76** is positioned. In use, the relief space **8** will form a cavity in the borehole which will facilitate rapid steering corrections. Thus, the structure in FIG. **6** illustrates this acute angle of the blade assembly and the tapered portion of the body having the uniquely advantageous function of defining a relief area or space **8** of reduced axial resistance near the forward end **4** of borehole **14** to thereby allow for rapid deviation of the borehole from a straight line when the boring head **58** is thrust forward without rotation.

Although the invention provides an improved rapid steering correction function in a boring operation with both a blade assembly and a fluid jet or nozzle, it is not necessary in certain circumstances to have a fluid jet to achieve the desired advantageous functions. A preferred structure, however, is the blade assembly **72** having an outer surface which is substantially flat and a tapered portion which defines an outer surface of the body from which only the blade assembly **72** and nozzle **76** project.

When a change of direction of the drill pipe is desired, rotation is stopped and the drill pipe is advanced axially without rotation. However, in certain soils or ground conditions, it is very difficult to move the drill pipe forward without rotation. The relief area **8** shown in FIGS. **6** and **23**, which is created by the structure of the boring head, allows for reduced axial resistance at least over the relief area when the drill string **44** is advanced without rotation. This relief area **8** of reduced axial resistance may be all that is needed to provide for rapid or sudden steering corrections. In some soil or boring situations, however, it may be necessary to incrementally repeat the rotation and push cycle to get the proper steering correction to form the walls **6** of the borehole **14** a along a curved path as in FIG. **1** or some other desired path. The present invention, thus, provides for improved rapid steering correction which is not available with known prior art devices.

An orientation directional indicator may be secured to the drill string adjacent the drill machine so that the angle of the plane of the boring head body can at all times be known. Referring back to FIGS. **2** and **4**, a device which is utilized to indicate the rotational orientation of drill string **44**, and thereby the rotational orientation of boring head **58**, is shown. The ring member **80** is slidably and rotatably received on the drill pipe **42**. The ring has a threaded opening therein receiving a set screw **82** having a handle **84**. When the set screw **82** is loosened, the ring **80** can be slid on the drill pipe **42** and rotated relative to it.

Affixed to the ring **80** is a bracket **85** having a pointer **86**. In addition to the pointer **86**, the bracket **85** carries a liquid bubble level **88**.

The function of the ring **80** with its pointer and bubble level is to provide means of maintaining the known orientation of the drill string **44**. When a drilling operation is to start, the first length of the drill pipe **42** is placed in the machine and the boring head **58** is secured tightly to it. At this juncture, the boring head is above ground and the operator can easily observe the orientation of blade assemblies **72**, **172**, **172'**, **272**, **272'**, **372**, **472**, **572**, **672** or **772**. The operator can then affix the ring **80** so that it is in accurate orientation with the blade, that is, as an example, the ring **80** is affixed so that pointer **86** points straight up with the blade aligned so that a plane drawn perpendicular to the plane of the blade would be vertical. With the ring **80** so aligned, the set screw **82** is tightened by the handle **84**. Thereafter, as the drill pipe **42** is rotated and advanced into the earth, the ring **80** remains in the same axial rotation orientation, rotating with the drill string. As the drill string is advanced by the advancement of the machine **24** towards the forward end **18A** of the boring machine frame, the ring **80** moves with it. It can be seen that when the boring machine has been advanced so that the shaft **40** is adjacent the frame forward end, drilling must be stopped and a new length of pipe **42** inserted. With drilling stopped, the drill string **44** can be aligned with the pointer **86** in alignment with sight **48** affixed to drill pipe support **46**. The ring **80** may then be removed and inserted on a new length of drill pipe **42** threadably secured to the drill string and the procedure continually repeated, each time tightening the set screw **88** so that the alignment of the blade is always known to the operator.

To form a borehole **44** in the earth, the operator attaches the drill pipe and boring head as shown in FIG. **2**, begins rotation of the drill pipe and at the same time, by means of control levers **34**, causes rotary machine **24** to linearly advance in the travel path of the frame towards the forward end **18A** or **118A** of frame **18** or **118**. The boring head **58**, rotating and advancing, enters the earth and forms a bore-

hole therein. As long as the boring head **58** is rotated as it is advanced, the borehole follows generally the axis of the drill pipe. That is, the borehole continues to go straight in the direction in which it is started.

In the most common application of the invention wherein the borehole is started at the earth's surface to go under an obstruction such as a highway, the borehole must first extend downwardly beneath the roadway. When the borehole has reached the necessary depth, the operator can then change the direction of drilling so as to drill horizontally. This can be accomplished in the following way: When it is time to change direction, the operator stops drilling and orients the drill string so that boring head blade assembly **72**, **172**, **172'**, **272**, **272'**, **372**, **472**, **572**, **672** or **772** is oriented in the direction desired. In the illustrated case of FIG. **1**, the borehole is first changed in the direction so that instead of being inclined downwardly, it is horizontal. For this purpose the operator will stop drilling with drill string **44** having pointer **86** pointing straight up, that is, with bracket **85** in the vertical position. With rotation stopped and the drill string properly oriented, the operator causes rotary machine **24** to move forwardly without rotating the drill pipe. After forcing the boring head a foot or two (or as far as possible, if less), the operator begins rotation of the boring head and continues to advance the drill string for a short distance. After a short distance of rotary boring, the procedure is repeated. That is, the drill string is reoriented so that the operator knows the inclination of blade assembly **72**, **172**, **172'**, **272**, **272'**, **372**, **472**, **572**, **672** or **772** and then the tool is advanced a short distance as above described without rotation and the procedure is repeated. The procedure may be repeated sequentially for a number of times until the direction of drilling has changed to that which is desired. The opposite steering correction will have to be applied just prior to the bit reaching the desired path in order to prevent or minimize any overshooting of that path. After the borehole has been oriented in the desired direction, such as horizontal, the drilling can continue by simultaneous rotation and advancement of drill string **44**, adding new links of drill pipe **42** as necessary until it is again time to change the direction of drilling, such as to cause the borehole to be inclined upwardly towards the earth's surface after the borehole has reached the opposite of the extremity of the obstruction under which the borehole is being placed. This is achieved as previously indicated; that is, by orienting the drill string **44** to thereby orient the blade assembly, advancing the boring head without rotation of drill string **44**, rotating and advancing the drill string for a short distance, reorienting the boring head or tool and advancing without rotation and sequentially repeating the steps until the new direction of drilling is achieved. The experienced operator soon learns the number of sequences which are normally required in order to achieve a desired direction of drilling.

Thus, it can be seen that a method of drilling provided by the present disclosure is completely different than that of the typical horizontal boring machine. The necessity of digging ditches to the opposite sides of an obstruction in which to place a horizontal boring machine is avoided.

The structure of FIGS. **9-35**, which disclose alternative embodiments for a boring system, will now be described in greater detail. Shown in FIGS. **9-22** is a second embodiment of a drill string assembly and a second embodiment of a boring head body. The boring head body **162** of FIGS. **10-14** at least differs from the body **62** of the embodiment of FIGS. **1-8** in that the jet is no longer at an acute angle to the centerline of the longitudinal axis of the drill string **548** and the blade assembly is now removable. If a difference is not

identified between embodiments, the elements described herein to operate the boring machine **10** can be used in the latter discussed embodiments.

As seen from the combination of FIGS. **9-14** and **23-28**, the boring head bodies **162** and **362** have fluid nozzle **76** fixed to the fluid passageway and positioned behind a forward end **72A**, **172A**, **272A**, **372A**, **472A**, **572A**, **672A** and **772A** of the blade assembly. The nozzle **76** can project from a nozzle receiving portion either on or adjacent top **190** and **390** of the outer surface of the bodies **162** and **362**. The nozzle **76** can also be recessed into the nozzle receiving portion of the body.

The top surface **190** of the body **162** is preferably 20° to the longitudinal axis X—X of the drill pipe. It can be appreciated that other types of nozzles or jet orifices could be employed.

The nozzle **76** on bodies **162** and **362** has a centerline Y—Y substantially parallel to the longitudinal axis X—X of the drill pipe **42**. Preferably, as most clearly seen in FIG. **28**, the nozzle **76** is displaced laterally from the longitudinal axis X—X of drill pipe **42** so that a fluid stream is emitted above the blade. Also, the nozzle opening or orifice **77** size is governed by factors such as pump capacity, fluid viscosity and flow rate desired downhole. Blade assemblies **72**, **172**, **172'**, **272**, **272'**, **372**, **472**, **572**, **672** and **772** include an outer surface which is substantially flat. Blade assemblies **172**, **172'**, **272**, **272'**, **372**, **472**, **572**, **672** and **772** are removably mounted on the tapered portion of the boring head body so that the blade assembly is at an acute angle to the longitudinal axis X—X of the drill pipe and the blade assembly is extending beyond the forward end **166** and **366** of the boring head bodies **162** and **362**. Having removable blade assemblies means that the blades can be replaceable without having to replace the body. This results in substantially lower operating cost. Also, one obtains versatility, because one can use a variety of cutter blade assemblies for trenchless installations in various soil types without having to invest in a plurality of boring heads.

The means for mounting removable blade assemblies is especially important, because of the high stress which these blades undergo. A preferred mode for mounting a removable blade assembly includes having apertures on the blade assembly receiving surfaces **192** and **392** of the outer surface of the boring head body and having corresponding apertures on the blade assemblies. Also, the blade assemblies are preferably disposed directly adjacent and flush mounted with the shouldered sections **169** and **369** of the bodies **162** and **362**. Furthermore, shouldered sections **169** and **369** are preferably at an angle 10° to a line perpendicular to the axis X—X.

Apertures on the body **162** are identified as elements **180-183** in FIGS. **11-14**, and apertures on body **362** are identified as elements **380-383** in FIGS. **23** and **25**. Apertures on the blade assembly **172** are identified as elements **175** and **177-79** in FIG. **17**. Apertures on the blade assembly **272** are identified as elements **275** and **277-279** in FIG. **19**. Also, apertures on the blade assembly **572** are identified as elements **575** and **577-9** in FIG. **29**, apertures on the blade assembly **672** are identified as elements **675** and **677-79** in FIG. **32**, and apertures on the blade assembly **772** are identified as elements **775**, and **777-79** in FIG. **34**. As seen in FIG. **10**, each blade assembly is removably mounted on the boring head body by means of a plurality of bolts **194** mounted through the corresponding apertures and substantially flush with an outer surface of the blade. Preferably the bolts **194** are coated with a thread retaining compound, such as Loctite® **242**, and torqued to 40 ft.-lbs. by wrench **199**.

Different types of removable blade assemblies are preferred. One blade type, represented by preferred blade assemblies **172** and **172'** in FIGS. **10**, **17** and **18**, is for cohesive soils and soils that offer a reasonable amount of steering resistance. Thus, blade assemblies **172** and **172'** are primarily for dirt/clay conditions. The blade assembly **172** is preferably $2\frac{1}{4}$ inches wide, 7 inches long and $\frac{1}{2}$ inch thick and preferred for dry/hard clay. Alternative blade assembly **172'**, is slightly wider at $2\frac{1}{2}$ inches. The wider blade assembly **172'** would be preferable for less resistant applications such as moist or soft dirt/clay conditions. The wider blade assembly is more advantageous in these softer dirt applications, because the wider the blade assembly the more steering force one obtains.

Even wider 3" blade assemblies **272** or **272'** of FIGS. **19–22** are preferred for sandy soils and other loose soils of little resistance. In these sandy soils, a big surface area blade assembly is desired. The additional width provides improved steering response.

Wear resistant material is added in selective areas of the blade assemblies for additional durability. As seen in FIGS. **17** and **18**, the blade assembly **172** includes wear resistant material **185** such as a carbide strip on the underside of forward portion **173** of the blade. The blade assembly **172** also includes wear resistant material **186** and **187** adjacent the underside rear portion of the blade as seen in FIGS. **17** and **18**.

Alternatively, one can place a weld bead **289** (of harder surface material than the blade) on the forwardmost portion of the blade and down the edges of the blade as seen in FIGS. **19** and **20**. Basically, it is preferred that all blade assemblies have either the weld bead or hard facing strips such as carbide on three edges as shown. It is not desired, though, that the carbide strips and weld beads be mixed on a blade assembly. Note, however, if the soil has any rock content, use of carbide strips on the blades is preferred.

Seen in the alternative 3" blade assembly **272'** of FIGS. **21** and **22** is a more preferred location for hard surfacing on a forward portion of the blade. As seen in FIGS. **21** and **22**, the forward portion of the blade includes strips **284** and **288** of harder surface material (i.e., carbide) than the blade which are disposed in recesses on portions of the surfaces of the blade. In particular, strip **288** is disposed on a right-hand side portion of the bottom or outer side of the blade when facing endwall **4** of borehole **14** and strip **284** is on a left-hand side portion of the top or inner side of the blade when facing endwall **4** of borehole **14**. With clockwise rotating (when looking in the direction of boring) of the blade assembly, the preferred location of hard surfacing in FIGS. **21** and **22** is more effective in protecting both front corners of the blade assembly. Consequently, the strips are provided on the portions of the surfaces of the blade assembly which have the primary contact with the earth when the tool body is simultaneously rotated and axially advanced.

It is also preferred that the recesses and the strips of harder surface material in the recesses cross a centerline of the blade assembly as seen in FIG. **21**. This double reinforcement at the centerline of the blade assembly is particularly advantageous where the blade and carbide strips **684** and **688** define a spade-like profile in the forward portion of the blade assembly **672** as seen in the blade of FIGS. **32** and **33**.

In addition, as seen in FIGS. **21** and **22**, the blade assembly **272'** includes hard surface material **286** and **287** in the rear portion of the blade assembly, and FIGS. **32** and **33** show hard surface material **687** in the rear portion of blade assembly **672**. This wear resistant material is preferably either brazed or welded onto the blade.

The boring head body **162** includes a forward end **166** and rearward end **164** having an aperture including threads for engaging a drill pipe. As seen in FIG. **11**, an intermediate portion of boring head body **162** has cavity **165** for receiving a transmitter and first fluid passageway **163A**.

As can be appreciated from FIGS. **10** and **11**, transmitter **220** is disposed in cavity **165** of the intermediate portion of the body. Pulling tool or wrench **218** is preferably used to install transmitter **220** in cavity **165**. Transmitter **220** produces an electromagnetic signal which allows the position and depth of boring head body **162** to be determined by use of an above ground receiver.

The rotational orientation of blade assembly **172** et al., must also be known when advancing without rotation to make course direction changes. An angle or roll sensor, such as those known in the art, can be used in conjunction with the above transmitter/receiver system to determine blade rotational orientation or aid in positioning the blade assembly at a particular desired orientation. Although downhole roll sensing is preferred, tophole drill string indicating means, such as described in the parent U.S. application Ser. No. 07/211,889, may be employed to determine blade orientation.

The removable plug **214** of FIG. **10** is disposed on a rearward portion of cavity **165** of the intermediate portion of the body. Plug **214** is also installed with pulling tool or wrench **218**. The plug is waterproof and it is positioned in the body for diverting pressurized fluid from drill string **44** the first passageway **163A** of the intermediate portion of the tool body. In other words, as the fluid comes down the center of fluid pipe (i.e., drilling cap) **210** in FIGS. **9** and **10**, the fluid path is deviated as it hits plug **214**. The fluid path is diverted downward through first passageway **163A** of boring head body **162** of FIG. **11**. An advantage of this arrangement is that plug **214** is removable. Thus, one can get into body **162** or **362** to replace battery **222** of transmitter **220**. Also, while performing a fluid deviating function, the plug protects the transmitter from fluid. Consequently, an additional advantage of this structure is that it allows the on-board transmitter to be disposed very close to the boring head.

The boring head further comprises O-rings **212** and **216** adjacent each end of plug **214**. Also, adjacent the forward end of the tool body is second fluid passageway **163B** and third fluid passageway **163C**. Second passageway **163B** is in fluid communication with and substantially perpendicular to first passageway **163A**. Third passageway **163C** is in fluid communication with and substantially perpendicular to second passageway **163B**. It would be understood by one of ordinary skill in the art that the passageway adjacent the connection of first passageway **163A** with second passageway **163B** would be tightly sealed at shouldered section **169** and at outer end **170**. Also, as can be appreciated from FIGS. **9–11**, fluid nozzle **76** is fixed to the fluid end **166** of body **162**.

FIGS. **9**, **10** and **16** illustrate elements for an arrangement wherein the nozzle **76** or the like is actually moved up the drill string and inside saver sub **232** or inside the adapter **230**. In particular, the drill string **44** includes a channel for transferring fluid from the exterior of the borehole to the front of the drill string. In FIG. **10**, fluid outlet **171** is fixed to the fluid passageway and associated with boring head body **162**.

When boring in sandy situations, it is preferred to place the nozzle rearward of the boring head body and install it in saver sub **232** or adapter **230**. As can be appreciated from FIG. **9**, disposed adjacent drive spindle **40** and the back end of the drill string **44** is saver sub assembly **232**. As shown in

FIG. 16, within saver sub assembly 232 is filter seating plug 245 which is internally threaded to hold nozzle 76. If inserted in saver sub 232, inner nozzle 76 meters the amount of and controls the rate of fluid that the surface fluid pump discharges into borehole 16. Once ejected from that inner nozzle 76, the fluid fills drill string 44 and exits out through outlet or bushing 171 in boring head body 62, 162 or 362. The hole in outlet or bushing 171 is large enough so that the downhole debris entering drill string 44 when the flow stops will likely be flushed back out when the flow resumes. In the preferred embodiments, outlet 171 has a diameter approximately the same as the diameter of the fluid passageway. This arrangement is particularly beneficial when drilling in sand or sandy soils where sand particles flowing back into a small orifice nozzle located at end 166 of body 162, could at least partially plug the opening when pressurized flow is resumed.

When installing the nozzle in saver sub 232, the operator must be careful. When the fluid pump is turned on, the pressure gauge will begin to show pressure before fluid ever reaches the boring head body. Even though the gauge shows pressure, the operator must wait until the fluid has reached the boring head body. This waiting time varies depending upon whether there are just a few feet or a few hundred feet of drill pipe in the ground. If the operator happens to thrust the boring head body forward before fluid reaches it, there is the possibility of plugging the boring head body. If drilling is continued while the boring head body is plugged, damage to the transmitter can occur.

To reduce the operator involvement in this process, one can alternatively install nozzle 76 in adapter 230. By installing nozzle 76 in adapter 230, the operator knows that when the gauge pressures up, the fluid is at the boring head body. This is true whether there are thirty feet or three hundred feet of pipe in the ground.

The saver sub 232 and adapter 230 both include filter and gasket combinations 240 and 242 as seen in FIG. 16. The filter and gasket combination 240 includes 30 mesh coarse screen filter for use with drilling fluids (bentonite, polymers, etc.). The fluid filter and gasket combination 242 includes 100 mesh fine screen for use with water or a water and antifreeze combination. If one uses 100 mesh filter with drilling fluid, the filter may collapse and stop the flow of fluid. The purpose of the filters is to remove any particles from the fluid flow which could obstruct nozzle 76.

FIGS. 23–27A illustrate an alternative boring head embodiment 362. As shown in FIGS. 23–26, some embodiments function to deflect fluid from nozzle 76 to an acute angle relative to the longitudinal axis X—X of the drill pipe. In particular, by having spray from nozzle 76 impinge upon removable cutting blade 372, the deflected jet stream should more easily allow redirecting of the body out of an existing borehole. This becomes important if an obstruction is encountered.

The deflecting portion of the blade assembly 372 comprises wear-resistant material 388 disposed in the blade as seen in FIGS. 24 and 26. Furthermore, the deflecting material 388 includes concave portion 389 for controlling the fluid spray pattern.

As soils become more difficult to drill, it is preferred to have the forward end of the blade assembly adjacent the longitudinal axis X—X of the drill pipe as in FIG. 28. This relationship of the blade assembly forward end to axis X—X is preferred, because if one happens to drill into a hard soil or soft rock, the boring head and its drill string will start rotating around the tip of the tool. If the blade assembly tip is not on or adjacent the centerline of the bore, this may

cause the rear portion to wobble and rub against walls of the diameter of borehole 14 which are behind the bit. Thus, in these situations blade assembly 472 of FIG. 28 may be more advantageous. Therefore, in the embodiment of FIG. 28, a forward end 472A of blade assembly 472 is adjacent and in fact on the longitudinal axis X—X of the drill pipe. For example, when harder soils or soft rock formations are anticipated, a tapered (pointed) rather than straight leading edge on the blade assembly (as in the spade-like blade assembly of FIGS. 32 and 33 or the stepped-taper blade assembly of FIGS. 29–31) can further aid in causing the blade assembly to “pilot” into the end of the borehole and will also rotate more smoothly than a straight-edged bit in such hard conditions.

In soft soils, however, it is preferred to have the forward end of the blade assembly extend beyond the longitudinal axis X—X of the drill pipe as in FIGS. 23–26. In soft soils, the tool will not tend to pilot on the face of the bore but instead will slip across it. In fact, for such soils it is advantageous for the blade assembly to be above (i.e., beyond) the centerline of the borehole in order to provide more steering force. It should be recognized that the above principle would apply whether or not deflecting of the spray is employed. By varying the lateral displacement of the jet relative to the X—X axis, a deflecting of the spray can be accomplished for the various types of blades discussed herein.

Shown in FIGS. 24, 27 and 27A is ball check valve 394 to prevent sand or the like from plugging the nozzle opening. When boring a hole in a tight formation, there tends to be a head pressure in borehole 16 at front portion 166 or 366 of boring head 162 or 362. Therefore, when one shuts off fluid flow to drill string 44 in order to, for example, add another piece of drill pipe, external debris-laden fluid in the borehole can actually flow upstream and into the drill pipe. Cuttings such as grains of sand and the like which enter nozzle 76 may plug the relatively small nozzle orifice 77 and, after adding a new piece of drill pipe and beginning fluid pressure through the fluid passageway, restrict or prevent the start of flow again.

It is preferred, therefore, to have check valve 394, disposed in the passageway, for opening the passageway when fluid pressure in the passageway towards nozzle 76 and on valve 394 is greater than pressure from borehole 16 on valve 394, and for closing the passageway when pressure from borehole 16 on valve 394 is greater than fluid pressure in the passageway towards nozzle 76 and on valve 394. The preferred valve includes ball 395 for preventing external downhole particles from entering a portion of the fluid passageway which is upstream of the ball. Also, included in valve 394 is roll pin 397.

Even with an essentially horizontal drill string, there is a tendency for fluid to flow out of nozzle 76 during the addition to the drill string or other work stoppages. This tends to be wasteful of drilling fluid and also causes delays in re-initiating the drilling operation, because of the time required to refill the drill string and reach operating pressure. This factor can become significant when drilling longer boreholes. Thus, the check valve means also preferably includes spring 396 disposed in the passageway and on a front side of the ball. The spring provides little pressure. In fact, the spring only biases the check valve closed with sufficient force to hold fluid in the drill string when pump flow is stopped and another joint of pipe is added to the drill string. In particular, the light spring force only causes the ball to close the passageway when the pressure of fluid in the passageway towards nozzle 76 and on ball 395 is less than 10–20 PSI.

As discussed herein, as an alternative to using ball check valve 394 one can use nozzle 76 in saver sub assembly 232 in combination with outlet 171. If the nozzle 76 is moved to adapter 230 instead of saver sub 232 for operation in sand, however, the ball check valve may preferably be used in combination with the nozzle to prevent plugging since nozzle 76 is only about a foot behind forward portion 166 (containing bushing/outlet 171) of body 162. In fact, a further reason for having the nozzle in adapter 230 at the downhole end of the drill string is to make use of the spring-biased check valve method of keeping the drill string full.

When drilling with nozzle 76 in saver sub 232 or adapter 230 and with check valve 394 installed in place of the nozzle on the boring head body, one will reduce the chance of mud and fluid being sucked back into the housing while breaking loose drill pipe to add another joint. This should also reduce the chance of plugging the [tool] boring head body. In addition, it should reduce the possibilities of damaging the transmitter 220. Note, however, it is strongly suggested that one should not run nozzles in both the boring head body and adapter 230 at the same time.

Also, one can also utilize two or more jets instead of one. It is preferred that these jets also be displaced vertically from the centerline of the housing as in FIGS. 13 and 23 and side by side. In other words, the front of body 362 of FIG. 25 can be modified to include one or more nozzles 76 laterally displaced from longitudinal axis X—X of drill pipe 42.

Shown in FIGS. 29–31 is a removable blade assembly 572 for hard soil or soft rock cutting. In particular, the blade assembly 572 is for drilling harder formations such as soft sedimentary rocks (i.e., sandstone or even soft limestone). This stepped-taper blade assembly 572 is advantageous because it has improved steering control. The blade assembly 572 includes a forward portion including end 572A, which when mounted on the boring head body, projects beyond a forward end of the body. The forward portion of the blade assembly 572 preferably, when viewed from its top as in FIG. 29, has a staggered profile which steps rearwardly from a forwardmost point 572A at a center of the blade to an outside of the forward portion of the blade.

As discussed with respect to the blade assembly 272' of FIGS. 21 and 22 and blade assembly 672 of FIGS. 32 and 33, the blade 572 also preferably includes a plurality of strips 584A–E which are disposed on recessed portions of the top and bottom surfaces of the substantially flat blade assembly. These strips have the primary contact with the earth when the blade assembly is simultaneously rotated and axially advanced.

The forward portion of the top of blade assembly 572 is a mirror image of a forward position of a bottom of the blade assembly 572. Furthermore, as discussed, it is preferred to have strips 584A on the top and bottom surfaces extend across the centerline of blade assembly 572 and to have these same strips extend forward of the forwardmost point of the blade as illustrated in FIGS. 30 and 31.

Forward portion of blade assembly 572 is wider than rear portions of the blade for smoother operation when rotated in hard soil or soft rock formations. Also, bottom edges 586 and 587 include wear resistant material such as carbide. Also, apertures 575 and 577–79 are for mounting the blade assembly on a tool body 162 or 362.

The blade assembly 572 has been shown to penetrate hard formations at a fast drilling rate, as well as enabling some corrective steering action in those formations. In this hard formation application, as was mentioned herein, it is desirable to have the forwardmost point on strip 584A on the

longitudinal axis X—X of drill pipe 42 in order to prevent the tool body from being rotated eccentrically around the center of bit rotation. In order to steer in soft rock, it takes an operating technique of intermittent rotating and thrusting. With this technique, directional blade assembly 572 allows a selective chipping away of the face of the borehole in order to begin deviating in the desired direction.

The blade assembly 772 of FIGS. 34 and 35 is a 4" wide bit having hard facing carbide strips 784 and 788 at forward point or tip 772A and carbide strips 786 and 787 all functioning and having advantages as discussed herein. The 4" wide blade assembly is preferred for making a larger pilot hole so that backreaming is not necessary for a 3" to 4" conduit installation.

There can also be an assembly associated with the drill frame 18 or 118 of a boring machine for preventing rotation of a drill pipe 42 having wrench receiving slots 43 as shown in FIG. 9. The assembly includes wrench 238 of FIG. 15A having an open end for removably engaging wrench receiving slots 43 of a rearward portion of a lower or first drill pipe. Also, included is pin 237 received in apertures of both the wrench and the frame and disposed adjacent forward end 118A of the frame for attaching wrench 238 to the frame. When the wrench engages the drill pipe, the lower or first drill pipe is substantially prevented from rotation.

With this preferred structure, a method of breaking a joint between drill pipe 42 and rotary machine 24 with saver sub 232 can include the steps of moving saver sub 232, which is joined to drill pipe 42, to a forward portion in drill frame 18 or 118. This joint breaking method then includes placing lower joint wrench 238, which is attached to the frame and adjacent a forward end 118A of the frame, in wrench receiving slots 43 on drill pipe 42 to substantially prevent rotation of the drill pipe, and using rotary drive 24 to rotate saver sub 232 in a reverse direction to unscrew saver sub 232 from drill pipe 42.

The method of adding a second drill pipe between saver sub 232 and a first drill pipe 42 includes breaking a joint between first drill pipe 42 and saver sub 232 as discussed in the prior paragraph. The method further includes the steps of moving saver sub 232 to a rearward portion in drill frame 18 or 118, placing a second or intermediate drill pipe in the frame between saver sub 232 and the lower or first drill pipe, threading a male end of the second or intermediate drill pipe into the saver sub, aligning a female end of the second drill pipe with a male end of the first drill pipe, moving the second drill pipe forward until a female end of the second drill pipe fits around a male end of the first drill pipe and applying rotational torque to tighten the rotating second drill pipe, with the stationary first drill pipe. This method can further include the steps of a slight reversing rotation to relieve pressure on joint wrench 238 and removing the joint wrench from wrench receiving slots 43 of the first drill pipe 42.

Preferably an open end of wrench 238 is at a first end of the wrench and a pin receiving aperture 239 of the wrench is at an opposite second end of the wrench so that the wrench can be rotated into engagement with the wrench receiving slots of the drill pipe. In addition, it is preferable that the wrench can be slid on pin 237 in a direction parallel to a centerline of drill pipe 42 for easy alignment with drill pipe receiving slots 43.

A second wrench 238' is also preferred for removing a second drill pipe from between a first drill pipe and saver sub 232 as would be required when withdrawing the drill string from the borehole. The second wrench 238' also has aperture 239' for receiving pin 237' which attaches the second wrench

to frame **18** or **118**. The second wrench is closer to rearward end **18B** or **118B** of the frame than to forward end **18A** or **118A** of the frame. A preferred method for removing a second drill pipe from between a first drill pipe and saver sub **232** includes the steps of moving rotary drive **24** to a substantially rearward position in drill frame **18** or **118** so that wrench receiving slots on a rearward portion of the first drill pipe are adjacent a forward end of the frame and the second or intermediate drill pipe is disposed on the frame between the saver sub and the first or lower drill pipe. This method then includes placing a first joint wrench **238**, which is attached to the frame and adjacent forward end **18A** or **118A** of the frame, in wrench receiving slots **43** of the first drill pipe to substantially prevent rotation of the first drill pipe. The next preferred step includes securing the second drill pipe to saver sub **232** to ensure that the joint of the second drill pipe to the first drill pipe will loosen before the joint of the second drill pipe to the saver sub when rotational torque is applied to the second drill pipe. It is preferred that a lock be applied between the saver sub and the second drill pipe so that this joint does not break before the joint between the second drill pipe and the lower first drill pipe is broken. One can, however, use additional torque applied by a hand held pipe wrench on the second drill pipe to accomplish this same function, i.e., to insure that the lower joint is broken first.

The method then includes applying a rotational torque to the second drill pipe which is sufficient to loosen the second drill pipe from the first drill pipe. After applying this rotational torque, one can then unsecure the second drill pipe from the saver sub. The method then includes rotating the saver sub and the second drill pipe in a reverse direction to unscrew the second or intermediate drill pipe from the first or lower drill pipe. Further steps include placing second joint wrench **238'**, which is attached to the frame, in wrench receiving slots on a rearward portion of the second drill pipe to substantially prevent rotation of the second uppermost drill pipe, and rotating the saver sub in a reverse direction to unscrew the saver sub from the second drill pipe.

Additional steps in removing a second drill pipe can include removing second joint wrench **238'** from the wrench receiving slots of the second drill pipe and removing the second drill pipe from the frame. Further steps can include moving rotary drive **24** forward in the frame, rotating the saver sub to join it with the first drill pipe and, removing the first joint wrench from the wrench receiving slots of the first drill pipe. To remove additional drill pipes, these above recited steps can be repeated.

Having a joint wrench attached to the frame provides advantages in safety, simplicity and economy. Safety is attained because attaching the wrench to the frame alleviates the prior worry about the wrench being accidentally loosened if, for example, the drill pipe accidentally rotates in an opposite direction than desired. Also, by using this fixed wrench assembly, one eliminates the complex hydraulic systems and the need for another valve section as would be required for a powered breakout wrench.

All patents and applications mentioned in this specification are hereby incorporated by reference in their entireties. In addition, the structures described in this specification and claimed are preferably used with structures disclosed in U.S. patent application Ser. Nos. 07/539,851; 07/539,699; 07/539,551; 07/539,847; 07/539,616; 07/513,186; and 07/513,588, which are also hereby incorporated by reference in their entireties.

With reference now to FIGS. **36–55**, a number of bits suitable for use with the boring machine will be described.

These bits will be used for horizontal and near horizontal drilling as well as vertical drilling. FIGS. **36** and **37** illustrate a bit **600**. The bit has a body **602** which defines a rearward end **604** for attachment to the drill string and a forward end **606** facing the ground to be bored.

The portion of the body adjacent the rearward end **604** can be seen to have a hexagonal cross-section perpendicular to the axis of rotation **608** of the bit. The body defines six parallel surfaces **610–620** which each extend parallel the axis **608**. Outer edges **622–632** are defined at the intersection of the parallel surfaces as illustrated.

Three angled surfaces **634**, **636** and **638** are defined on the body and extend from intermediate the rearward and forward ends to the forward end **606**. Each of the surfaces **634**, **636** and **638** are at an angle relative to the axis **608**. The orientation of the angled surfaces can be defined relative to a hypothetical framework **640** (illustrated in FIG. **39**) which is defined as if the parallel surfaces **610–620** of the body extended all the way to the forward end **606**. The angled surfaces **634** and **638** can be seen each to intersect two of the hypothetical parallel surfaces, specifically parallel surfaces **610** and **612** in the case of angled surface **634** and parallel surfaces **618** and **620** in the case of angled surface **638**. It is also helpful to define a plane of symmetry **601** (not shown) which contains axis **608** and divides the bit **600** into two mirror image halves. Each angled surface **634** and **638** is a mirror image of the other relative the plane of symmetry **601**. Angled surface **636**, in turn, will intersect a total of four parallel surfaces, specifically surfaces **612–618**. Angled surface **636** also is bisected by the plane of symmetry **601**. The intersection of the angled surfaces and the actual parallel surfaces will define a series of edges **642–660** between the various intersecting surfaces, each one of those edges being at an angle relative to the axis **608**.

The bit **600** has numerous advantages in the drilling operation. Each of the edges **622–632** and **642–660** are potential cutting surfaces to cut the ground. The angled surfaces **634**, **636** and **638** define an area as the drill bit is thrust forward which causes the bit to be deflected in a new direction. The area is a compaction area during thrust and simultaneous rotation. Further, the inclined surfaces **634–638** define incline planes that, as the bit is rotated and thrust forward simultaneously, permit the surfaces **634–638** to work in conjunction with cutting edges **642–660** to cut the periphery of the borehole and simultaneously compact the material into the bore wall or pass the cuttings through the relief areas defined by the borehole and surfaces **610–620**. Further, the use of a hexagonal cross-section defined by the surfaces **610** through **620** will further define an additional relief area as the drill bit is rotated bounded by the surfaces and the cylindrical bore cut through the ground. This additional relief area will also assist steering of the bit. As the drill bit is rotated to form a borehole, the bit will define a cylindrical borehole of diameter determined by the radial dimension between the axis of rotation **608** and the edges **622–632**. When the bit rotation is halted to steer the bit into a new direction, voids exist between the inner surface of the borehole and the surface **610–620**, providing this additional area to more easily deflect the bit into the new direction of drilling. It also has a stabilizing effect to maintain a truer line (course) while making corrections to a new base path.

With reference now to FIGS. **38** and **39**, a bit **680** is illustrated which is in all respects identical to bit **600** with the exception of the addition of two carbide cutting tips **682** and **684**. The carbide tip **682** is positioned to extend outwardly from about the center of surface **636** and near axis **608**. The carbide tip **684** is at the forward end **606**. As the

bit **680** rotates, the carbide tips will define cutting circles established by the radial distance between the rotational axis **608** and the individual tip. Tip **682**, being closer to axis **608**, defines the inner cutting circle. Tip **684**, at the outer portion of the bit, defines the outer cutting circle. The tips **682** and **684** assist in boring, particularly in cutting through hard soil conditions.

FIGS. **40** and **41** illustrate a bit **690** which is a modification of bit **600**. In bit **690**, angled surfaces **692**, **694** and **696** are positioned on the bit with the surface **694** intersecting five of the six parallel surfaces. The plane of symmetry **698** bisects parallel surface **614** and the angled surface **694**. The surfaces define angled outer edges **702–714**. The distance between edges **702** and **714** and the edges **706** and **708** are greater in bit **690** than the corresponding distance in bit **600**, which makes the surface **694** wider and the bit more appropriate for boring in softer soils. It is expected that bit **690** will be easier to direct in soft soils because of the width of the surface **694** and the greater surface area of the angled surface **694**.

With reference to FIGS. **42** and **43**, a bit **710** is illustrated which is a slight modification of bit **690**. In bit **710**, the angled surfaces **712** and **716** are at a slighter greater angle relative to the plane of symmetry **718** than those of bit **690**. It would be expected that bit **710** would be more effective in medium soils than bit **690**.

With reference now to FIGS. **44** and **45**, a bit **720** is illustrated which is formed with angled surfaces **722–728**. Angled surfaces **722** and **724** are on a first side of the plane of symmetry **730**. Each of the surfaces **724** and **726** intersect three of the parallel surfaces, while angled surfaces **722** and **728** each intersect two of the parallel surfaces. The surfaces define angled outer edges **732–756**. Bit **720** would be intended primarily for clay and harder soils.

FIGS. **46** and **47** illustrate a bit **780**. Bit **780** has a body **782** with a circular cross-section perpendicular the axis **608**. A plane of symmetry **784** passes through the bit, intersecting axis **608**, to divide the bit into two equal mirror halves. Angled surfaces **786** and **788** are formed on the bit **780** on either side of the plane of symmetry. Because of the circular cross-section of the bit, the surfaces **786** and **788** will define curved edges **790** and **794**, and linear edge **792**. Bit **780** would also be intended primarily for clay and harder soils.

FIGS. **48** and **49** illustrate a bit **800** which is a modification of bit **780**. Bit **800** includes a third angled surface **802** which bisects the plane of symmetry to form linear edges **804** and **806** and a curved edge **808**.

FIGS. **50** and **51** illustrate a bit **820** which has a triangular cross-section perpendicular the axis of rotation **608**. The bit defines parallel surfaces **822**, **824** and **826**. A plane of symmetry **828** is defined through the bit **820** which divides the bit into mirror image halves. Angled surface **830** is formed on one side of the plane while an angled surface **834** is formed on the other side the plane. An angled surface **832** bisects the plane of symmetry between the surfaces **830** and **834**. The surfaces define slanted outer edges **836–850**.

FIGS. **52** and **53** illustrate a bit **860** which has a generally square cross-section perpendicular the axis **608** defining parallel surfaces **862–868**. Angled surfaces **870–880** are formed to define angled edges **882–900**. It should be noted that bit **860** does not have a plane of symmetry, defining two parallel surfaces **902** and **904** on one side of the bit.

With reference to FIGS. **54** and **55**, a bit **920** is illustrated which has a tapered wedged shape. The bit includes parallel surfaces **922**, **924** and **926** and angled surface **928**.

With reference to FIG. **59**, a bit **980** is illustrated which has parallel surfaces **982**, **984**, **986** and **988** and an angled

surface **990**. The front end of the bit **992** is perpendicular to parallel surfaces **982–988** and is formed at the intersection of parallel surfaces **982** and **988** and angled surface **990**. The angled surface **990** preferably extends at an angle of about 20° from the rotational axis of the bit.

With reference now to FIG. **56**, a drill bit **950** is illustrated which has a body **952** with a circular cross-section perpendicular the axis **608**. A curved surface **954** is formed on the drill bit which extends from near the rear end **604** to the forward end **606**. Carbide cutting tips **956** and **958** are mounted along the drill bit to aid in cutting with the same cutting action as described in bit **680**.

With reference to FIG. **57**, a drill bit **960** is illustrated which has a prong **962** which extends outward from the curved surface **964**. A carbide cutting tip **966** is mounted at the end of the prong **962** and a carbide cutting tip **968** is mounted at the end **606** of the drill bit to provide the same cutting action as described in bit **680**.

With reference to FIG. **58**, a drill bit **970** is disclosed which has a prong **972** extending from surface **974**. A carbide cutting tip **976** is mounted at the end of prong **972**, a carbide cutting tip **978** is mounted at the end **606** of the drill bit to provide the same cutting action as described in bit **680**.

With reference now to FIGS. **60–62**, a directional multi-blade boring head **1000** will be described. The head **1000** is mounted at the end of a drill string which is capable of selectively rotating the head about its central axis of rotation **1002** and advancing the head along the axis **1002**. The head includes a body **1004** which is attached to the end of the drill string in a conventional manner. The body defines a first planar surface **1006** on a first side of the body and a second planar surface **1008** on the other side of the body. The planar surfaces are both angled in an oblique angle, preferably 13° , relative to the axis **1002**. A jet recess **1010** is cut from the first planar surface **1006** and mounts a jet **1012** to discharge a fluid to assist in the boring action.

As can best be seen in FIG. **62**, the body has internal passages **1014**, **1016** and **1018** which direct the fluid from the drill string to the jet **1012**. The fluid can be air, water, gas or any suitable drilling fluid. As can be seen, a check valve **1020** is provided within the passages which includes a check ball **1022** and a spring **1024** to urge the check ball into a closed position unless the fluid pressure in passage **1018** acting on the ball is sufficient to overcome the force of the spring **1024**.

A blade assembly **1026** is mounted to the body at the second planar surface **1008**. Preferably, the blade assembly **1026** is bolted to the body by bolts **1028** to permit the body assembly to be removed for repair or replaced by a new blade assembly when necessary.

The blade assembly **1026** is formed of at least three blades, including a first blade **1030**, a second blade **1032** and at least one intermediate blade **1034**.

The first blade **1030** defines a deflecting surface **1036** and the second blade defines a similar deflecting surface **1038**. The deflecting surfaces extend at an oblique angle relative to the axis **1002**, preferably 13° . These deflecting surfaces act to deflect the head when the drill string to which the head is attached is thrust forward without rotation. Thus, the head **1000** acts as a directional boring head in the manner of the bits and heads described previously.

The first and second blades **1030** and **1032** also define staggered cutting teeth **1040** to assist the boring action. The included angle θ between the first and second blades is preferably about 120° . The intermediate blade **1034** extends between the deflecting surfaces **1036** and **1038** at an angle

θ_1 from the first blade and at an angle θ_2 from the second blade. With the single intermediate blade **1034**, the angles θ_1 and θ_2 are preferable each 120° .

Each of the teeth **1040** are staggered in the direction of rotation of the head for more effective cutting. Also, carbide cutting elements **1041** form the part of the teeth exposed to the greatest wear to lengthen the service life of the blade assembly **1026**.

With reference now to FIGS. **63–65**, a directional multi-blade boring head **1050**, forming a modification of the invention, is illustrated. A number of the elements of boring head **1050** are identical to those of multi-blade boring head **1000**. These elements have been identified by the same reference numerals and have similar functions to those described with reference to head **1000**.

However, the included angle θ between the blades **1030** and **1032** is 180° . A second intermediate blade **1042** extends between the blades **1030** and **1032** on the sides of the blades opposite the deflecting surfaces **1036** and **1038**. The second intermediate blade **1042** in effect forms a continuation of the intermediate blade **1034** and is also provided with serrated teeth **1040** and carbide cutting elements **1041**. It will be noted that the discharge of nozzle **1012** will strike a portion of the second intermediate blade **1042** and a recess **1054** has been formed in the blade **1042** to redirect the stream to assist in the cutting action. The four bladed bit **1050** will permit smoother, straighter bores in harder soil conditions while the inclined planes **1036** and **1038** provide the bit with directional capabilities.

Now with reference to FIGS. **66–68**, a directional dual-cone boring head **1100** is illustrated. The dual cone boring head has rotary cutters or cones **1104** and **1105** similar to those used on prior art tri-cone drilling bits used in the oil field. The boring head **1100** is used to directionally drill in hard or semi-hard materials. The head **1100** is mounted at the end of a drill string which is capable of selectively rotating the head about its central axis of rotation **1002** and advancing the head along the axis **1002**. The head includes a body **1004** which is attached to the end of the drill string in a conventional manner. The body defines a first planar surface **1006** on the first side of the body and a second planar surface **1008** on the other side of the body. The planar surfaces are both angled in an oblique angle, preferably 13 degrees, relative to the axis **1002**. A jet recess **1010** is cut from the first planar surface **1006** and mounts a jet **1101** to discharge a fluid such as a liquid or a gas to assist in the boring. The jet **1101** is extended in length as compared to jet **1012** of the previous multi-blade bits to ensure fluid is directed at the dual cones to provide lubrication, cooling and assist in boring. All other aspects of the fluid delivery system are the same as boring heads **1000** and **1050**.

The bit assembly **1102** is mounted to the body at the second planar surface **1008**. Preferably, the bit assembly **1102** is bolted to the body by bolts **1103** to permit the body assembly to be removed for repair or install a new bit assembly when necessary.

The bit is formed of two roller cones and attachment body consisting of the center cut cone **1104** and adjacent cone **1105** from a standard tri-cone oil field bit. The rotational axis of each of the cones preferably intersects the axis **1002**. The cones and bodies are welded to components **1106** and **1107** to form bit assembly **1102**. A part of the bit assembly defines a deflecting surface **1108** extending at an oblique angle similar to and causing the bit to act as a directional boring head in the manner of the bits and heads described previously.

With reference now to FIGS. **69–71**, a directional single cone boring head **1200** is illustrated. The single cone head

has a single rotary cutter or cone **1202** similar to those used on prior art tri-cone drilling bits used in the oil field. The jet **1101** discharges against the side of the cutter **1202** to clean debris therefrom. In other aspects, the boring head **1200** is identical to boring head **1100** discussed previously, and identical elements on the figures are identified by the same reference numerals.

The roller cones described in this invention provide the same cutting action as in the oil field application of the tri-cone bits previously described. These tri-cone bits have one center cut cone and two adjacent cones. However, the addition of the deflecting surface and the removal of one of the adjacent roller cones permits the boring head **1100**, when thrust forward without rotation, to be deflected from the axis of the bore thus permitting the direction of the bore to be altered. The addition of the deflecting surface and the removal of two of the adjacent roller cones permits the head **1200**, when thrust forward without rotation, to be deflected from the axis of the bore thus permitting the direction of the bore to be altered. The continuous rotation of the boring head and application of thrust permits the borehole to be in a straight line relative to the drill string axis **1002**. The hardness of the material being cut will dictate the amount of steering capable of being accomplished. Some semi-hard materials will permit the oscillating of the boring head and the drill string about the central axis of rotation **1002** while applying thrust to change the direction of the bore axis.

The boring heads **1000**, **1050**, **1100** and **1200** described have a number of significant advantages over previous known boring heads. The heads **1000**, **1050**, **1100** and **1200** bore a rounder, straighter hole than a one-sided slanted head which tends to drill more of a helical borehole. The heads **1000**, **1050**, **1100** and **1200** have proven particularly effective in boring productivity and direction accuracy through sand and rock. With previous one-sided slanted heads, the head could impact and catch on a hard object, causing the boring rods in the drill string to wind up in torsion until the head breaks free of the object with a sudden release. The heads **1000**, **1050**, **1100** and **1200** appear to alleviate this problem.

The additional advantages of the heads **1000**, **1050**, **1100**, and **1200** include an improvement in the directional accuracy of the head through rock and other hard boring conditions. The boring head also uses less water to cool the bit which has significant advantages, as EPA regulations for disposal of drilling fluids are becoming more difficult to comply with. The presence of the blades also reduces a tendency for the head to roll when pushed forward without rotation to make a directional change. Finally, the head provides an improved ease of surface launch.

Turning now to FIGS. **72–77**, another preferred blade assembly will be described. The blade assembly, designated generally by the reference numeral **1500**, can be attached to and used with any of the boring head bodies **62** (FIGS. **6–8**), **162** (FIG. **10**), **362** (FIGS. **23–24**) and **1004** (FIGS. **60–71**), to form a boring head in accordance with the present invention.

The blade assembly **1500** comprises a flat base portion **1502** with a top surface **1504** and a bottom surface **1506**. The base portion is adapted to removably attach the blade assembly **1500** to the bottom surface **92**, **192**, **392**, **1008**, of the boring head body **62**, **162** and **362** (FIGS. **6**, **11** and **23**, **62**, **65**, **68** and **71**), in the manner previously described. To this end, the top surface **1504** of the blade assembly **1500** is sized and shaped to conform closely to the bottom surface of the boring head body, and is provided with bolt holes only one of which is designated in the drawings as reference

numeral **1508**. The base has a thickness " T_1 " (FIGS. **74-75**) and width " W_1 " (FIGS. **72-73**). The width W_1 is selected to be about the width of the boring head body. The thickness may vary but should provide sufficient rigidity and strength.

Extending from the base **1502** is a blade portion **1510** 5 which preferably is flat and broader than the base **1502**. More preferably, the blade **1510** has a width " W_2 " which increases gradually from the point " P " where the blade joins the base **1502** to the forward end **1512**. This provide a larger cutting surface on the blade and therefore a borehole slightly 10 larger than the boring head body.

The blade **1510** is serrated, that is, the forward end **1512** of the blade terminates in a plurality of points or teeth, designated generally in the drawings by the numeral **1514**. As best seen in FIGS. **72** and **73**, in the preferred embodiment of the blade assembly **1500** the blade may be considered as having two halves **1516A** and **1516B**, joining at about the line " H ." These halves are similarly formed, each having three teeth including a forward tooth **1520A** and **1520B**, a middle tooth **1522A** and **1522B**, and a rearward tooth **1524A** and **1524B**. The half **1516A** extends slightly beyond the half **1516B**. This provides good cutting action by allowing each of the teeth on each half to contact a different point (for a total of six points in this particular embodiment) on the surface through which the borehole is being made. 15 Were the two halves **1516A** and **1516 B** perfectly symmetrical, rather than offset as taught herein, the tooth **1522B**, for example, would follow in the cutting path of the tooth **1522A**. This would be duplicative, providing in effect only three true cutting points on the end of borehole and 20 being less efficient than the design herein with the offset halves.

With continuing reference to FIGS. **72** and **73**, the front or primary contact surfaces of the teeth **1514** are provided with hardened strips, designated generally by the numeral 25 **1530** of carbide or some other suitable material, as previously described herein.

With reference now to FIGS. **74-76**, it will be seen that the teeth **1514** do not have a flat frontal surface parallel to the blade **1510**. Rather, the back sides of the teeth **1514** are cut away at **1532**. As used herein, the "back" of a tooth refers to the side of the tooth opposite the primary contact surfaces, such as those shown in the drawings covered with the hardened strips **1530**, that is, behind or following the sharp edge that first contacts the surface to be cut. This cut away 30 portion of the teeth **1514**, when the boring head is penetrating the earth or rock through which the borehole is being drilled, forms a recess or cavity for the cuttings formed by the drilling action of the blade. This also provides a thinner frontal edge, which impacts the earth or rock, and improves 35 the stabbing or penetration ability of the boring head when the head is not being rotated.

Still further, and now referring also to FIG. **76**, there is slot or space **1534** between the two frontal teeth **1520A** and **1520B**. (See also FIGS. **72** and **73**.) This serves as additional 40 relief space for the cuttings as the blade pushes and rotates through the earth.

Referring still to FIGS. **74** and **75**, it will be seen that the thickness " T_2 " of the blade **1510** tapers slightly from the point " P " where it joins the base **1502** to the forward end 45 **1512**. This provides a thinner profile to the blade and aids in piercing the earth when the blade is being axially, but not rotationally, advanced.

Referring now to FIG. **77**, both the base **1502** and blade **1510** are substantially planar. Thus, the plane of the base 50 may be identified as B_1 and plane of the blade may be identified as B_2 . It will be seen that the plane B_1 is the center

of the converging upper and lower planes of the tapered blade. The plane B_1 forms an angle " A " of about 170 degrees with the plane B_2 so that the blade **1510** is angled upwardly relative to the base when the base **1502** is attached to the boring head body. This angled configuration provides the boring head with better penetration and better steering capabilities.

Now it will be appreciated that the serrated or stepped, tapered blade **1500** provides many advantages. The relief areas provide space for cuttings being thrown back from the cutting surface. The angle and tapered configuration of the blade improves its ability to penetrate the earth and to steer the boring head, when the rotation is stopped but axial advancement continues.

While the invention has been described with a certain degree of particularity, it is manifest that many changes may be made in the details of construction and arrangement of components without departing from the spirit and scope of this disclosure. It is understood that the invention is not limited to the embodiments set forth herein for purposes of exemplification, but is to be limited only by the scope of the attached claims, including the full range of equivalency to which each element thereof is entitled.

What is claimed is:

1. A directional boring machine comprising a drill string operatively connected to a rotary machine for rotating the drill string and including an assembly for axially advancing the drill string and wherein the free end of the drill string is adapted to support a bit for forming the borehole, the machine comprising:

a bit attached to the free end of the drill string, the bit comprising:

a body portion defining parallel surfaces extending parallel the axis of rotation of the bit, the body portion defining a rear end for attachment to the drill string and a front end facing the earth being bored; and

at least one angled surface formed on the body portion lying in a plane at an angle relative the axis of rotation of the bit defining a plurality of edges at the intersection of the angled and parallel surfaces to assist cutting, the angled surface extending on the body from intermediate the rear and front ends to proximate the front end.

2. A directional boring machine comprising a drill string operatively connected to a rotary machine for rotating the drill string and including an assembly for axially advancing the drill string and wherein the drill string has a free end adapted to support a bit for forming the borehole, the machine comprising:

a bit attached to the free end of the drill string, the bit comprising:

a body portion defining parallel surfaces extending parallel the axis of rotation of the bit, the body portion defining a rear end for attachment to the drill string and a front end facing the earth being bored;

at least one angled surface formed on the body portion lying in a plane at an angle relative the axis of the rotation of the bit defining a plurality of edges at the intersection of the angled and parallel surfaces to assist cutting, the angled surface extending on the body from intermediate the rear and front ends to proximate the front end; and

a carbide tip mounted at the front end of the body portion.

3. A directional boring machine comprising a drill string operatively connected to a rotary machine for rotating the

drill string and including an assembly for axially advancing the drill string and wherein the free end of the drill string is adapted to support a bit for forming the borehole, the machine comprising:

a bit attached to the free end of the drill string, the bit comprising:

a body portion defining parallel surfaces extending parallel the axis of rotation of the bit, the body portion defining a rear end for attachment to the drill string and a front end facing the earth being bored; at least one angled surface formed on the body portion lying in a plane at an angle relative the axis of rotation of the bit defining a plurality of edges at the intersection of the angled and parallel surfaces to assist cutting, the angled surface extending on the body from intermediate the rear and front ends to proximate the front end; and

a carbide tip mounted on the body portion through said angled surface.

4. A directional boring machine comprising a drill string operatively connected to a rotary machine for rotating the drill string and including an assembly for axially advancing the drill string and wherein the free end of the drill string is adapted to support a bit for forming the borehole, the machine comprising:

a bit attached to the free end of the drill string, the bit comprising:

a body portion defining a plurality of surfaces parallel the axis of rotation, the body portion defining a rear end for attachment to the drill string and a front end facing the earth to be bored;

at least one angled surface formed on the body portion lying along a direction at an angle to the axis of rotation; and

the parallel surfaces defining parallel edges at their intersection which extend parallel the rotational axis of the drill bit and defining angled surfaces along the parallel surfaces between the parallel edges, the bit drilling a cylindrical borehole at the parallel edges, the angled surfaces being bounded by the parallel surfaces and the wall of the borehole.

5. A directional boring machine comprising a drill string operatively connected to a rotary machine for rotating the drill string and including an assembly for axially advancing the drill string and wherein the free end of the drill string is adapted to support a boring head for forming the borehole, the machine comprising:

a directional multi-blade boring head attached to the free end of the drill string, the boring head comprising:

a body having a central axis of rotation;

a blade assembly mounted on the body having a first blade defining a deflecting surface at an oblique angle to the central axis of rotation of the body and a second blade defining a deflecting surface at an oblique angle to the central axis of rotation of the body, the first and second blades extending at an angle relative to each other;

at least one additional blade extending from the blade assembly between the deflecting surface; and

the deflecting surfaces of the first and second blades deflecting the boring head as the boring machine advances the drill string without rotation and the directional multi-blade boring head drilling a relatively straight borehole as the boring machine advances the drill string with rotation.

6. A directional boring machine comprising a drill string operatively connected to a rotary machine for rotating the

drill string and including an assembly for axially advancing the drill string and wherein the free end of the drill string is adapted to support a boring head for forming the borehole, the machine comprising:

a multi-blade boring head attached to the free end of the drill string, the boring head comprising:

a body having a central axis of rotation and a planar surface at an oblique angle to the central axis, a plane of symmetry passing through the central axis of rotation and perpendicular to the planar surface;

a blade assembly mounted to the body at the planar surface and defining a first blade extending at an angle of about 60 degrees from the plane of symmetry on a first side of the plane of symmetry and a second blade extending at an angle of about 60 degrees from the opposite side of the plane of symmetry, said first and second blades each defining deflecting surfaces thereon;

at least one intermediate blade extending from the blade assembly between the deflecting surfaces; and the deflecting surfaces of the first and second blades deflecting the boring head as the boring machine advances the drill string without rotation and the directional multi-blade boring head drilling a relative straight borehole as the boring machine advances the drill string with rotation.

7. A directional boring machine comprising a drill string operatively connected to a rotary machine for rotating the drill string and including an assembly for axially advancing the drill string and wherein the free end of the drill string is adapted to support a boring head for forming the borehole, the machine comprising:

a directional multi-blade boring head attached to the free end of the drill string, the boring head comprising:

a body having a central axis of rotation and a planar surface at an oblique angle to the central axis, a plane of symmetry passing through the central axis of rotation and perpendicular to the planar surface;

a blade assembly mounted to the body at the planar surface and defining a first blade extending perpendicular to the plane of symmetry on a first side of the plane of symmetry and a second blade extending perpendicular to the plane of symmetry from the opposite side of the plane of symmetry, said first and second blades each defining deflecting surfaces thereon;

at least one intermediate blade extending from the blade assembly between the deflecting surfaces and lying parallel to the planar surface; and

the deflecting surfaces of the first and second blades deflecting the boring head as the boring machine advances the drill string without rotation and the directional multi-blade boring head drilling a relatively straight borehole as the boring machine advances the drill string with rotation.

8. A directional boring machine comprising a drill string operatively connected to a rotary machine for rotating the drill string and including an assembly for axially advancing the drill string and wherein the free end of the drill string is adapted to support a boring head for forming the borehole, the machine comprising:

a directional boring head attached to the free end of the drill string, the boring head comprising:

a body having a central axis of rotation;

a deflection structure mounted on the body defining a deflection surface at an oblique angle to the central axis of rotation of the body;

at least one roller cone mounted to said body; and the deflecting surface deflecting the boring head as the boring machine advances the drill string without rotation and the directional boring head drilling a relatively straight borehole as the boring machine advances the drill string with rotation.

9. A directional boring machine comprising a drill string operatively connected to a rotary machine for rotating the drill string and including an assembly for axially advancing the drill string and wherein the free end of the drill string is adapted to support a boring head for forming the borehole, the machine comprising:

a directional boring head attached to the free end of the drill string, the boring head comprising:

a body having a central axis of rotation;

a deflection structure mounted on the body defining a deflecting surface at an oblique angle to the central axis of rotation of the body;

only one roller cone mounted to said body; and

the deflecting surface deflecting the boring head as the boring machine advances the drill string without rotation and the directional boring head drilling a relatively straight borehole as the boring machine advances the drill string with rotation.

10. A blade assembly for cutting a borehole underground, the blade assembly adapted for use with a directional boring machine capable of axially advancing and rotating a drill string about an axis of rotation underground, wherein the drill string has a first end operatively connected to the directional boring machine and a second end terminating in the boring head body having a central axis of rotation and a blade attachment surface, the blade assembly comprising:

a base adapted to be attached to the blade attachment surface on the boring head body, the base being flat defining a first plane;

a blade extending from the base, the blade having a rearward end and a forward end, the rearward end attached to the base and the forward end having a cutting surface, the blade being flat and defining a second plane; and

wherein the second plane of the blade intersects the first plane of the base to form an angle so that the blade is angled upwardly relative to the base.

11. The blade assembly of claim 10 wherein the angle formed by the intersection of the first plane of the base and the second plane of the blade is about 170 degrees.

12. The blade assembly of claim 11 wherein the base is about the same width as the boring head body, wherein the width of the blade gradually increases from the rearward end to the forward end, and wherein the thickness of the blade gradually decreases from the rearward end to the forward end.

13. The blade assembly of claim 10 wherein the cutting surface defines a plurality of teeth.

14. The blade assembly of claim 13 wherein each one of the plurality of teeth terminates in a point which is positioned to contact a different point on the underground surface through which the borehole is being made.

15. The blade assembly of claim 14 wherein each one of the plurality of teeth is tapered defining a sharp frontal edge slanting rearwardly to form a recess for receiving cuttings formed by the blade as the borehole is being made.

16. The blade assembly of claim 13 wherein each one of the plurality of teeth is tapered defining a sharp frontal edge slanting rearwardly to form a recess for receiving cuttings formed by the blade as the borehole is being made.

17. The blade assembly of claim 10 wherein the width of the blade gradually increases from the rearward end to the forward end.

18. The blade assembly of claim 10 wherein the thickness of the blade gradually decreases from the rearward end to the forward end.

19. The blade assembly of claim 10 wherein the blade is characterized by a first half and a second half, each half having a forward end, the cutting surface on the forward end of the first half is formed by a first set of cutting teeth, wherein the cutting surface on the forward end of the second half is formed by a second set of cutting teeth, wherein each of the first set and second set of teeth comprises a plurality of teeth forming a staggered profile which steps rearwardly from a forward most tooth near the center of the forward end of the blade to a rearward most tooth, wherein the first set of teeth on the first half of the blade is offset relative to the second set of teeth on the second half of the blade so that the first set of teeth will contact the surface of the borehole at different points during the boring process than the second set of teeth.

20. The blade assembly of claim 19 wherein a recess for receiving cuttings during the boring process is formed between the forward end of the first half and the forward end of the second half.

21. The blade assembly of claim 20 wherein the angle formed by the intersection of the first plane of the base and the second plane of the blade is about 170 degrees.

22. A blade assembly for cutting a borehole underground, the blade assembly adapted for use with a directional boring machine capable of axially advancing and rotating a drill string about an axis of rotation underground, wherein the drill string has a first end operatively connected to the directional boring machine and a second end terminating in the boring head body having a central axis of rotation and a blade attachment surface, the blade assembly comprising:

a flat base adapted to be attached to the blade attachment surface on the boring head body; and

a flat blade extending from the base, the blade having a rearward end and a forward end, the rearward end attached to the base and the forward end having a cutting surface characterized by a first half and a second half, the first half having a first set of cutting teeth, the second half having a second set of cutting teeth, wherein each of the first set and second set of teeth comprises a plurality of teeth forming a staggered profile which steps rearwardly from a forward most tooth near the center of the forward end of the blade to a rearward most tooth, wherein the first set of teeth on the first half of the blade is offset relative to the second set of teeth on the second half of the blade so that the first set of teeth will contact the surface of the borehole at different points during the boring process than the second set of teeth.

23. The blade assembly of claim 22 wherein base is about the same width as the boring head body, wherein the width of the blade gradually increases from the rearward end to the forward end, and wherein the thickness of the blade gradually decreases from the rearward end to the forward end.

24. The blade assembly of claim 22 wherein each one of the plurality of teeth is tapered defining a sharp frontal edge slanting rearwardly to form a recess for receiving cuttings formed by the blade as the borehole is being made.

25. The blade assembly of claim 22 wherein the width of the blade gradually increases from the rearward end to the forward end.

26. The blade assembly of claim 22 wherein the thickness of the blade gradually decreases from the rearward end to the forward end.

27. The blade assembly of claim 22 wherein a recess for receiving cuttings during the boring process is formed

between the forward end of the first half and the forward end of the second half.

28. A blade assembly for cutting a borehole underground, the blade assembly adapted for use with a directional boring machine capable of axially advancing and rotating a drill string about an axis of rotation underground, wherein the drill string has a first end operatively connected to the directional boring machine and a second end terminating in the boring [headbody] *head body* having a central axis of rotation and a blade attachment surface, the blade assembly comprising:

a base adapted to be attached to the blade attachment surface on the boring head body; and

a blade extending from the base, the blade having a rearward end and a forward end, the rearward end attached to the base and the forward end having a cutting surface characterized by a plurality of cutting teeth, the plurality of cutting teeth forming a staggered profile which steps rearwardly from at least one forward most tooth near the center of the forward end of the blade to a rearward most tooth on either side of the forward end, wherein each one of the plurality of teeth is tapered defining a sharp frontal edge slanting rearwardly to form a recess for receiving cuttings formed by the blade as the borehole is being made.

29. The blade assembly of claim **28** wherein the blade attachment surface of the boring head defines a plane which intersects the central axis of rotation of the boring head.

30. The blade assembly of claim **28** wherein the width of the blade gradually increases from the rearward end to the forward end.

31. The blade assembly of claim **28** wherein the thickness of the blade gradually decreases from the rearward end to the forward end.

32. The blade assembly of claim **28** wherein the base is flat defining a first plane and the blade is flat defining a second plane which intersects the first plane at an angle so that the blade is angled upwardly relative to the base.

33. A directional boring machine comprising a drill string operatively connected to a rotary machine for rotating the drill string and including an assembly for axially advancing the drill string and wherein the free end of the drill string is adapted to support a boring head with a body having a central axis of rotation and a blade attachment surface for attaching a blade assembly for forming the borehole, the machine comprising:

a blade assembly comprising:

a base adapted to be attached to the blade attachment surface on the boring head body, the base being flat defining a first plane;

a blade extending from the base, the blade having a rearward end and a forward end, the rearward end attached to the base and the forward end having a cutting surface, the blade being flat and defining a second plane; and

wherein the second plane of the blade intersects the first plane of the base to form an angle so that the blade is angled upwardly relative to the base.

34. The directional boring machine of claim **33** wherein the angle formed by the intersection of the first plane of the base of the blade assembly and the second plane of the blade is about 170 degrees.

35. The directional boring machine of claim **34** wherein the base of the blade assembly is about the same width as the boring head body, wherein the width of the blade gradually increases from the rearward end to the forward end, and wherein the thickness of the blade gradually decreases from the rearward end to the forward end.

36. The directional boring machine of claim **33** wherein the cutting surface on the blade defines a plurality of teeth.

37. The directional boring machine of claim **36** wherein each one of the plurality of teeth on the blade terminates in a point which is positioned to contact a different point on the underground surface through which the borehole is being made.

38. The directional boring machine of claim **37** wherein each one of the plurality of teeth on the blade is tapered defining a sharp front edge slanting rearwardly to form a recess for receiving cuttings formed by the blade as the borehole is being made.

39. The directional boring machine of claim **36** wherein each one of the plurality of teeth on the blade is tapered defining a sharp frontal edge slanting rearwardly to form a recess for receiving cuttings formed by the blade as the borehole is being made.

40. The directional boring machine of claim **33** wherein the width of the blade gradually increases from the rearward end to the forward end.

41. The directional boring machine of claim **33** wherein the thickness of the blade gradually decreases from the rearward end to the forward end.

42. The directional boring machine of claim **33** wherein the blade is characterized by a first half and a second half, each half having a forward end, the cutting surface on the forward end of the first half is formed by a first set of cutting teeth, wherein the cutting surface on the forward end of the second half is formed by a second set of cutting teeth, wherein each of the first set and second set of teeth comprises a plurality of teeth forming a staggered profile which steps rearwardly from a forward most tooth near the center of the forward end of the blade to a rearward most tooth, wherein the first set of teeth on the first half of the blade is offset relative to the second set of teeth on the second half of the blade so that the first set of teeth will contact the surface of the borehole at different points during the boring process than the second set of teeth.

43. The directional boring machine of claim **42** wherein a recess for receiving cuttings during the boring process is formed between the forward end of the first half and the forward end of the second half.

44. The directional boring machine of claim **43** wherein the angle formed by the intersection of the first plane of the base and the second plane of the blade is about 170 degrees.

45. A directional boring machine comprising a drill string operatively connected to a rotary machine for rotating the drill string and including an assembly for axially advancing the drill string and wherein the free end of the drill string is adapted to support a boring head with a body having a central axis of rotation and a blade attachment surface for attaching a blade assembly for forming the borehole, the machine comprising:

a blade assembly comprising:

a flat base adapted to be attached to the blade attachment surface on the boring head body; and

a flat blade extending from the base, the blade having a rearward end and a forward end, the rearward end attached to the base and the forward end having a cutting surface characterized by a first half and a second half, the first half having a first set of cutting teeth, the second half having a second set of cutting teeth, wherein each of the first set and second set of teeth comprises a plurality of teeth forming a staggered profile which steps rearwardly from a forward most tooth near the center of the forward end of the blade to a rearward most tooth, wherein the first set

of teeth on the first half of the blade is offset relative to the second set of teeth on the second half of the blade so that the first set of teeth will contact the surface of the borehole at different points during the boring process than the second set of teeth.

46. The directional boring machine of claim 45 wherein the base of the blade assembly is about the same width as the boring head body, wherein the width of the blade gradually increases from the rearward end to the forward end, and wherein the thickness of the blade gradually decreases from the rearward end to the forward end.

47. The directional boring machine of claim 45 wherein each one of the plurality of teeth on the blade is tapered defining a sharp frontal edge slanting rearwardly to form a recess for receiving cuttings formed by the blade as the borehole is being made.

48. The directional boring machine of claim 45 wherein the width of the blade gradually increases from the rearward end to the forward end.

49. The directional boring machine of claim 45 wherein the thickness of the blade gradually decreases from the rearward end to the forward end.

50. The directional boring machine of claim 45 wherein a recess for receiving cuttings during the boring process is formed between the forward end of the first half of the blade and the forward end of the second half.

51. A directional boring machine comprising a drill string operatively connected to a rotary machine for rotating the drill string and including an assembly for axially advancing the drill string and wherein the free end of the drill string is adapted to support a boring head with a body having a central axis of rotation and a blade attachment surface for attaching a blade assembly for forming the borehole, the machine comprising:

a blade assembly comprising:

a base adapted to be attached to the blade attachment surface on the boring head body; and

a blade extending from the base, the blade having a rearward end and a forward end, the rearward end attached to the base and the forward end having a cutting surface characterized by a plurality of cutting teeth, the plurality of cutting teeth forming a staggered profile which steps rearwardly from at least one forward most tooth near the center of the forward end of the blade to a rearward most tooth on either side of the forward end, wherein each one of the plurality of teeth is tapered defining a sharp frontal edge slanting rearwardly to form a recess for receiving cuttings formed by the blade as the borehole is being made.

52. The directional boring machine of claim 51 wherein the blade attachment surface of the boring head defines a plane which intersects the central axis of rotation of the boring head.

53. The directional boring machine of claim 51 wherein the width of the blade gradually increases from the rearward end to the forward end.

54. The directional boring machine of claim 51 wherein the thickness of the blade gradually decreases from the rearward end to the forward end.

55. A directional boring machine comprising a drill string operatively connected to a rotary machine for rotating the drill string and including an assembly for axially advancing the drill string and wherein the free end of the drill string is adapted to support a boring head for forming the borehole, the machine comprising:

a directional multi-blade boring head attached to the free end of the drill string, the boring head comprising:

a body having a central axis of rotation;

a blade assembly mounted on the body, the blade assembly comprising:

a base attached to the lower surface of the body, the base defining a first plane;

a blade extending from the base and terminating in a forward end, the blade defining a second plane intersecting the first plane of the base, so that the blade angles upward relative to the base;

wherein the blade has a first side and a second side thickness tapering gradually towards the forward end, wherein the forward end defines a plurality of teeth, each tooth having a contact side and a back side, the contact side being the side that impacts the earth first as the boring head is rotated on the drill string, and the back side being the side opposite the contact side, and wherein the back side of each tooth is cut away forming a recess between the back side of the tooth and the surface being bored; and

wherein the plurality of teeth includes a first set of teeth on a first side of the blade and a second set of teeth on the second side of the blade, the first set being substantially similar in size and configuration as the second set of teeth, but extending slightly forward of the second set of teeth.

56. A blade assembly for cutting a borehole underground, the blade assembly adapted for use with a directional boring machine capable of axially advancing and rotating a drill string about an axis of rotation underground, wherein the drill string has a first end operatively connected to the directional boring machine and a second end terminating in the boring head body having a central axis of rotation and a blade attachment surface, the blade assembly comprising:

a blade assembly mounted on the body, the blade assembly comprising:

a base attached to the lower surface of the body, the base defining a first plane;

a blade extending from the base and terminating in a forward end, the blade defining a second plane intersecting the first plane of the base, so that the blade angles upward relative to the base;

wherein the blade has a first side and a second side thickness tapering gradually towards the forward end, wherein the forward end defines a plurality of teeth, each tooth having a contact side and a back side, the contact side being the side that impacts the earth first as the boring head is rotated on the drill string, and the back side being the side opposite the contact side, and wherein the back side of each tooth is cut away forming a recess between the back side of the tooth and the surface being bored; and

wherein the plurality of teeth includes a first set of teeth on the first side of the blade and a second set of teeth on the second side of the blade, the first set being substantially similar in size and configuration as the second set of teeth, but extending slightly forward of the second set of teeth.

57. A directional boring head for a boring machine, the boring machine capable of axially advancing and rotating a drill string about an axis of rotation underground, the drill string ending in the directional boring head, the directional boring head comprising:

a body having a central axis of rotation;

a deflection structure mountable on the body and adapted to deflect the boring head from the axis of rotation of the drill string as the boring machine advances the drill

string without rotation, thus permitting alteration in the direction of the boring head; and

at least one roller cone mountable on the body.

58. The directional boring head of claim 57 wherein a fluid jet is mounted on the body, the body having a passage for flow of fluid for discharge from the jet to assist in drilling.

59. The directional boring head of claim 57 wherein the jet is oriented to discharge a fluid at the roller cone.

60. The directional boring head of claim 57 wherein the deflection structure and roller cone are mounted on a bit assembly removably attached to the body.

61. The directional boring head of claim 57 wherein the roller cone is offset with respect to the central axis of rotation of the body.

62. The directional boring head of claim 57 having two roller cones mounted on the body.

63. The directional boring head of claim 57 wherein the deflection surface deflects the boring head from the axis of rotation underground when the boring head is thrust forward without rotation.

64. The directional boring head of claim 57 having only one roller cone mounted on the body.

65. The directional boring head of claim 64 wherein a fluid jet is mounted on the body, the body having a passage for flow of fluid for discharge from the jet to assist in drilling.

66. The directional boring head of claim 64 wherein the jet is oriented to discharge a fluid at the roller cone.

67. The directional boring head of claim 64 wherein the deflection structure and roller cone are mounted on a bit assembly removably attached to the body.

68. The directional boring head of claim 64 wherein the rotational axis of the roller cone intersects the central axis of rotation of the body.

69. The directional boring head of claim 64 wherein the deflection surface deflects the boring head from the axis of rotation underground when the boring head is thrust forward without rotation.

70. The directional boring head of claim 57 wherein the body and the deflection structure are integrally formed.

71. A directional boring machine comprising a drill string operatively connected to a rotary machine for rotating the drill string and including an assembly for axially advancing the drill string and wherein the free end of the drill string is adapted to support a boring head for forming the borehole, the machine comprising:

a directional boring head attached to the free end of the drill string, the boring head comprising:

a body having a central axis of rotation;

a deflection structure mountable on the body and adapted to deflect the boring head from the axis of rotation of the drill string as the drill string is advanced without rotation, thus permitting alteration in the direction of the boring head; and

at least one roller cone mountable on the body.

72. The directional boring machine of claim 71 wherein a fluid jet is mounted on the body, the body having a passage for flow of fluid for discharge from the jet to assist in drilling.

73. The directional boring machine of claim 71 wherein the jet is oriented to discharge a fluid at the roller cone.

74. The directional boring machine of claim 71 wherein the deflection structure and roller cone are mounted on a bit assembly removably attached to the body.

75. The directional boring machine of claim 71 wherein the roller cone is offset with respect to the central axis of rotation of the body.

76. The directional boring machine of claim 71 having two roller cones mounted on the body.

77. The directional boring machine of claim 71 wherein the deflection surface deflects the boring head from the axis of rotation underground when the boring head is thrust forward without rotation.

78. The directional boring machine of claim 71 having only one roller cone mounted on the body.

79. The directional boring machine of claim 78 wherein a fluid jet is mounted on the body, the body having a passage for flow of fluid for discharge from the jet to assist in drilling.

80. The directional boring machine of claim 78 wherein the jet is oriented to discharge a fluid at the roller cone.

81. The directional boring machine of claim 78 wherein the deflection structure and roller cone are mounted on a bit assembly removably attached to the body.

82. The directional boring machine of claim 78 wherein the rotational axis of the roller cone intersects the central axis of rotation of the body.

83. The directional boring machine of claim 78 wherein the deflection surface deflects the boring head from the axis of rotation underground when the boring head is thrust forward without rotation.

84. The directional boring machine of claim 71 wherein the body and the deflection structure are integrally formed.

85. A drill bit for use at the end of a drill pipe having a means of drilling a borehole in the earth in the axial direction of the drill pipe when the drill pipe is simultaneously rotated and axially advanced and for changing the direction of the borehole when the drill bit is advanced without rotation, the drill bit comprising:

a body attachable to the drill pipe, wherein the body defines a rearward end and a forward end;

a blade defining a rearward end and a forward end, wherein the blade is attachable to the body so that the forward end of the blade extends beyond the forward end of the body and defines a relief area with the body to enable deviation in the direction of the borehole upon axially advancing the drill pipe without rotation.

86. The drill bit of claim 85 wherein the blade and body are integrally formed.

87. The drill bit of claim 85 wherein the body tapers toward the forward end of the body and further defines a longitudinal axis and wherein the blade, when assembled with the body, is inclined at an acute angle with respect to the longitudinal axis of the body.

88. The drill bit of claim 87 wherein the body comprises a top surface which tapers toward the forward end of the body, wherein the blade comprises a top surface and wherein the top surface of the body and the top surface of the blade, when in assembled operation, define the relief area.

89. The drill bit of claim 85 wherein the body defines a longitudinal axis and comprises a top surface generally parallel with the longitudinal axis of the body.

90. The drill bit of claim 85 wherein the body further defines a fluid passageway adapted to transmit fluid and a fluid nozzle associated with the body and positioned behind the forward end of the blade so that fluid from the fluid passageway is deflected off of the blade.

91. A boring head body for a boring head for cutting a borehole underground, wherein the body is attachable to a cutting blade having a rearward end and a forward end and is adapted for use with a boring machine capable of axially advancing and rotating a drill string underground, wherein the drill string has a first end operatively connected to the boring machine and a second end terminating in the boring

head body to which a blade is attachable, the boring head body comprising:

a body attachable to the drill string, wherein the body defines a rearward end and a forward end;

wherein the body, when assembled with the blade so that the blade extends beyond the forward end of the body defines a relief area with the body to enable deviation in the direction of the borehole upon axially advancing the drill pipe without rotation.

92. The boring head body of claim 91 wherein the blade and body are integrally formed.

93. The boring head body of claim 91 wherein the body further defines a longitudinal axis and wherein the blade, when assembled with the body, is inclined at an acute angle with respect to the longitudinal axis of the body.

94. The boring head body of claim 91 wherein the body further defines a fluid passageway adapted to transmit fluid and a fluid nozzle associated with the body and positioned behind the forward end of the blade so that fluid from the fluid passageway is deflected off of the blade.

95. A boring head body for a boring head for cutting a borehole underground, the body adapted for use with a boring machine capable of axially advancing and rotating a drill string underground, wherein the drill string has a first end operatively connected to the boring machine and a second end terminating in the boring head body to which a blade is attachable, the boring head body comprising:

a body adapted to support a blade for boring the underground surface through which the bore is to be made; wherein the body and the blade when in assembled relation define a relief area to enable deviation in the direction of the borehole upon axially advancing the drill pipe without rotation.

96. The drill bit of claim 95 wherein the blade and body are integrally formed.

97. The drill bit of claim 95 wherein the body further defines a longitudinal axis and wherein the blade, when assembled with the body, is inclined at an acute angle with respect to the longitudinal axis of the body.

98. The drill bit of claim 95 wherein the body further defines a fluid passageway adapted to transmit fluid and a fluid nozzle associated with the body and positioned behind the forward end of the blade so that fluid from the fluid passageway is deflected off of the blade.

99. A blade assembly for a boring head for cutting a borehole underground, the blade assembly adapted for use with a boring machine capable of axially advancing and rotating a drill string underground, wherein the drill string has a first end operatively connected to the boring machine and a second end terminating in a boring head body to which the blade assembly is attachable, the blade assembly comprising:

a base adapted to be attached to the boring head;

a blade extending from the base, the blade having a rearward end and a forward end, wherein the rearward end is attachable to the base; and

a cutting element attachable to the forward end of the blade, the cutting element adapted to bore a hole when the boring head body is rotated.

100. The blade assembly of claim 99 wherein the cutting element comprises a cutting edge.

101. The blade assembly of claim 99 wherein the cutting edge comprises a straight edge.

102. The blade assembly of claim 100 wherein the cutting edge further comprises a forward most point adapted to make first contact with the underground surface through which the borehole is to be made.

103. The blade assembly of claim 100 wherein the cutting edge tapers toward the forward end of the blade.

104. The blade assembly of claim 99 wherein the boring head body and the blade are integrally formed.

105. The blade assembly of claim 99 wherein the cutting element comprises a plurality of cutting teeth.

106. The blade assembly of claim 105 wherein each one of the plurality of cutting teeth terminates in a point which is positioned to contact a different point on the underground surface through which the borehole is to be made.

107. The blade assembly of claim 99 wherein the blade is generally rectangular.

108. The blade assembly of claim 99 wherein the base is about the same width as the boring head body, wherein the width of the blade gradually increases from the rearward end to the forward end.

109. The blade assembly of claim 99 wherein the blade further comprises wear-resistant material positioned on the blade at the points of primary contact with underground surface to be bored.

110. A directional boring head for a boring machine, the boring machine capable of axially advancing and rotating a drill string about an axis of rotation underground, the drill string ending in a directional boring head, the directional boring head comprising:

a body having a longitudinal axis;

a roller cone mountable on the body;

wherein the position of the roller cone is offset with respect to the axis of the body, so that when the roller cone is simultaneously advanced and rotated, the boring head bores a generally straight borehole, and when the roller cone is advanced without rotation, the boring head deviates the direction of the bore.

111. The directional boring head of claim 110 further comprising a deflection structure mountable on the body and adapted to deflect the boring head from the axis of rotation of the drill string as the boring machine advances the drill string without rotation, thus permitting alteration in the direction of the boring head.

112. The directional boring head of claim 111 wherein the deflection structure and the body are integrally formed.

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