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(12) **United States Design Patent**
Lundbäck et al.

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- (54) **ROBOT WITH FLEXIBLE ARMS**
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Jeroen Derkx, Vasteras (SE); **Johan Ernlund**, Västerås (SE); **Stefan Danielsson**, Vasteras (SE); **Mats Olov Olsson**, Vasteras (SE)
- (73) Assignee: **ABB Schweiz AG**, Baden (CH)
- (**) Term: **15 Years**
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(30) **Foreign Application Priority Data**

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(51) **LOC (12) Cl.** **15-99**

(52) **U.S. Cl.**
USPC **D15/199**

(58) **Field of Classification Search**
USPC D15/199; D21/578-583, 621, 622;
D32/21
CPC B25J 5/007; B60B 19/006; B62D 57/024;
H01F 7/0221; Y10S 901/01
See application file for complete search history.

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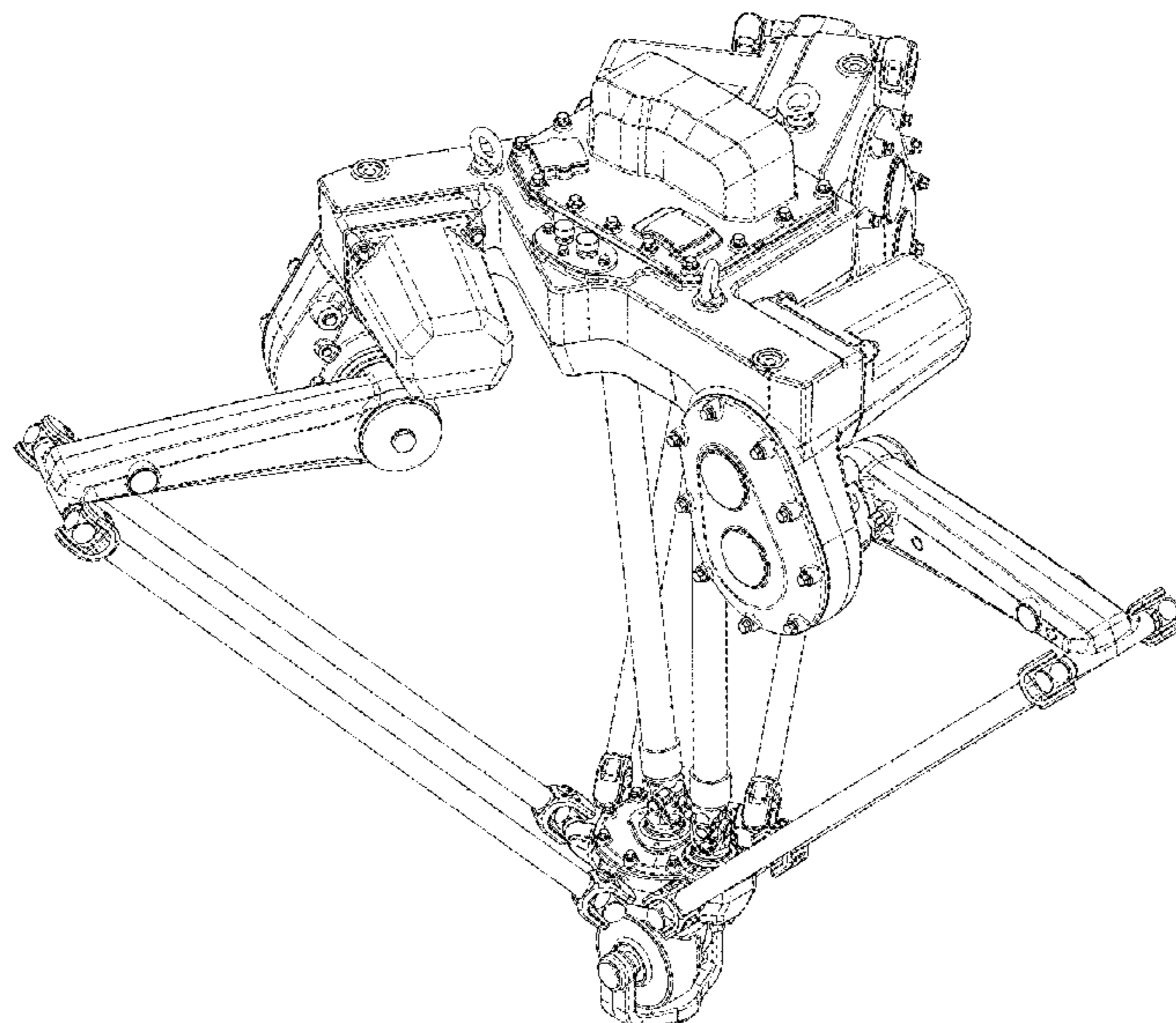
(57) **CLAIM**

The ornamental design for a robot with flexible arms, as shown and described.

DESCRIPTION

FIG. 1 is a front isometric view of a robot with flexible arms in accordance with the new design;
 FIG. 2 is a front side elevational view thereof;
 FIG. 3 is a rear side elevational view thereof;
 FIG. 4 is a left side elevational view thereof;
 FIG. 5 is a right side elevational view thereof;
 FIG. 6 is a top plan view thereof;
 FIG. 7 is a bottom plan view thereof;
 FIG. 8 is a front side elevational view thereof; and,
 FIG. 9 is a rear side elevational view thereof.
 The broken lines in the drawings depict portions of the robot with flexible arms that form no part of the claimed design.

1 Claim, 9 Drawing Sheets



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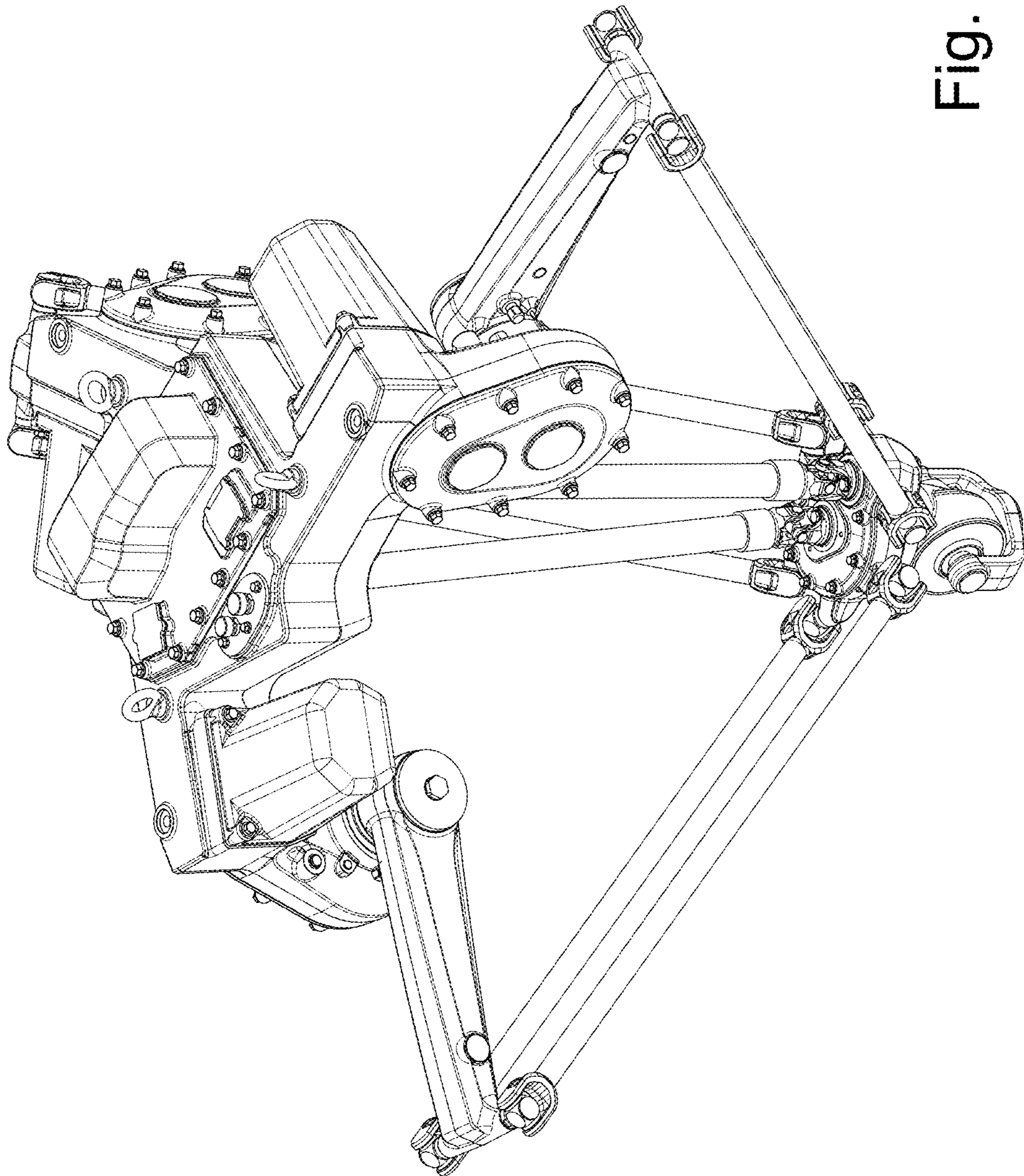


Fig. 1

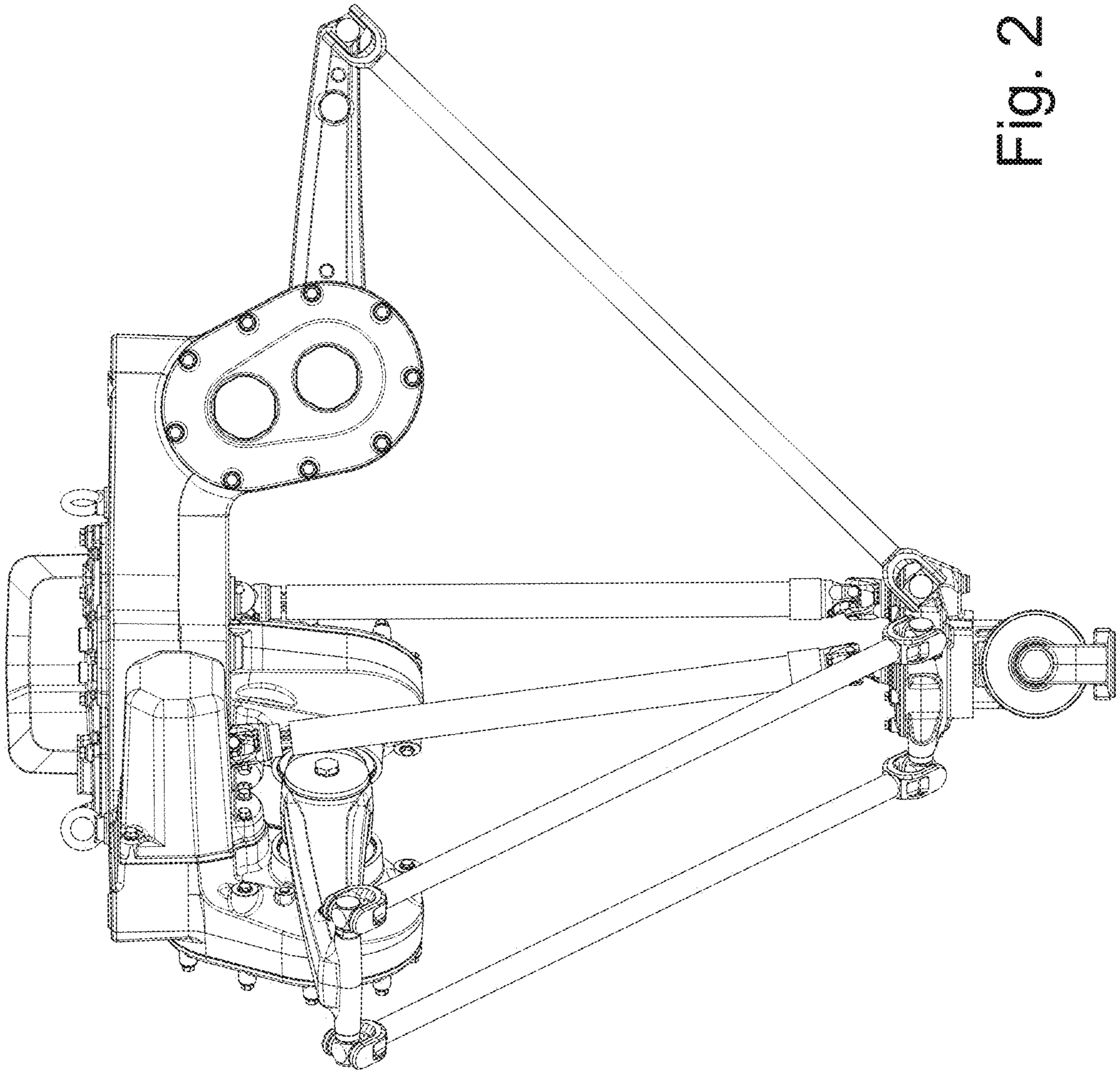


Fig. 2

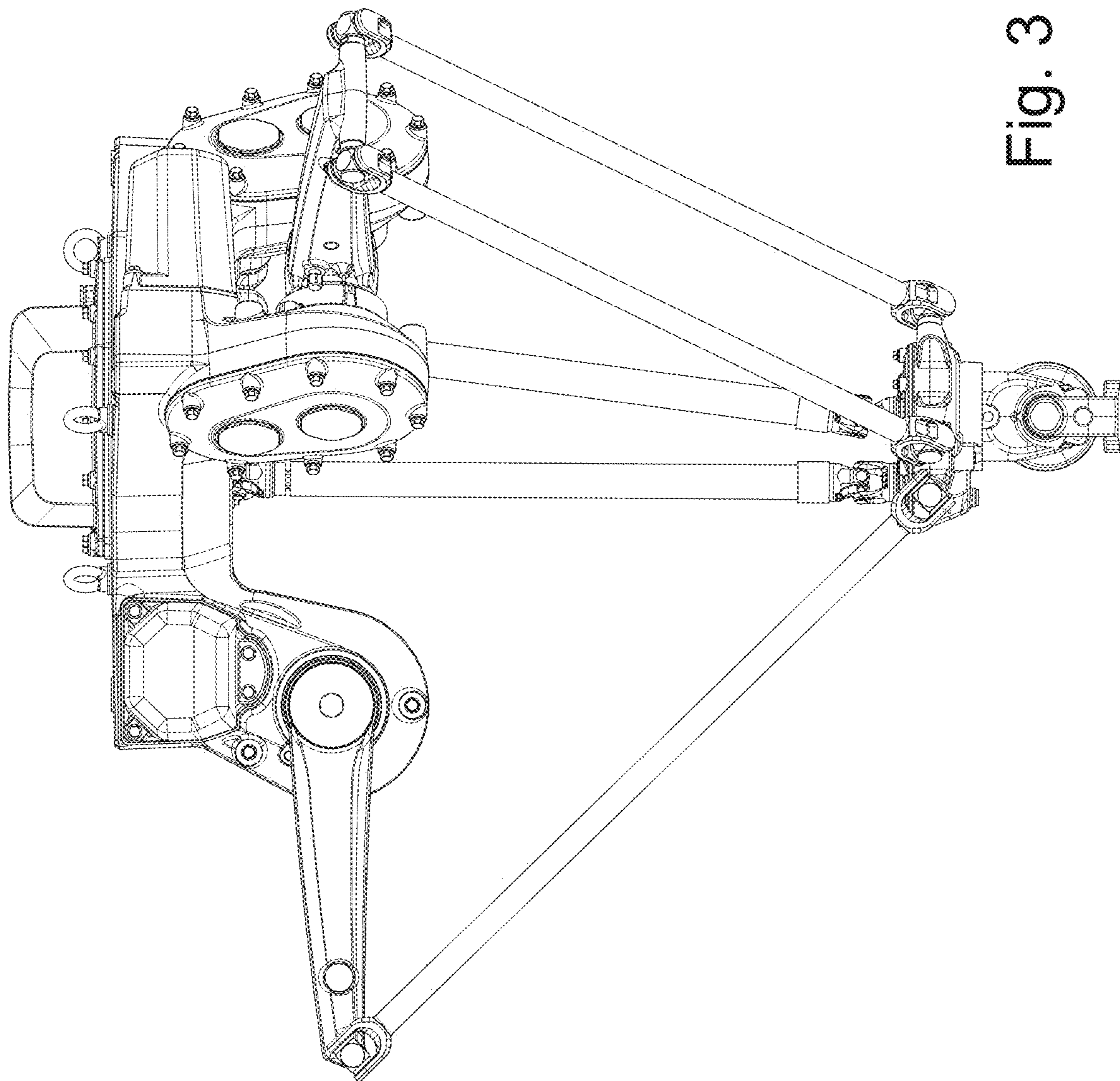


Fig. 3

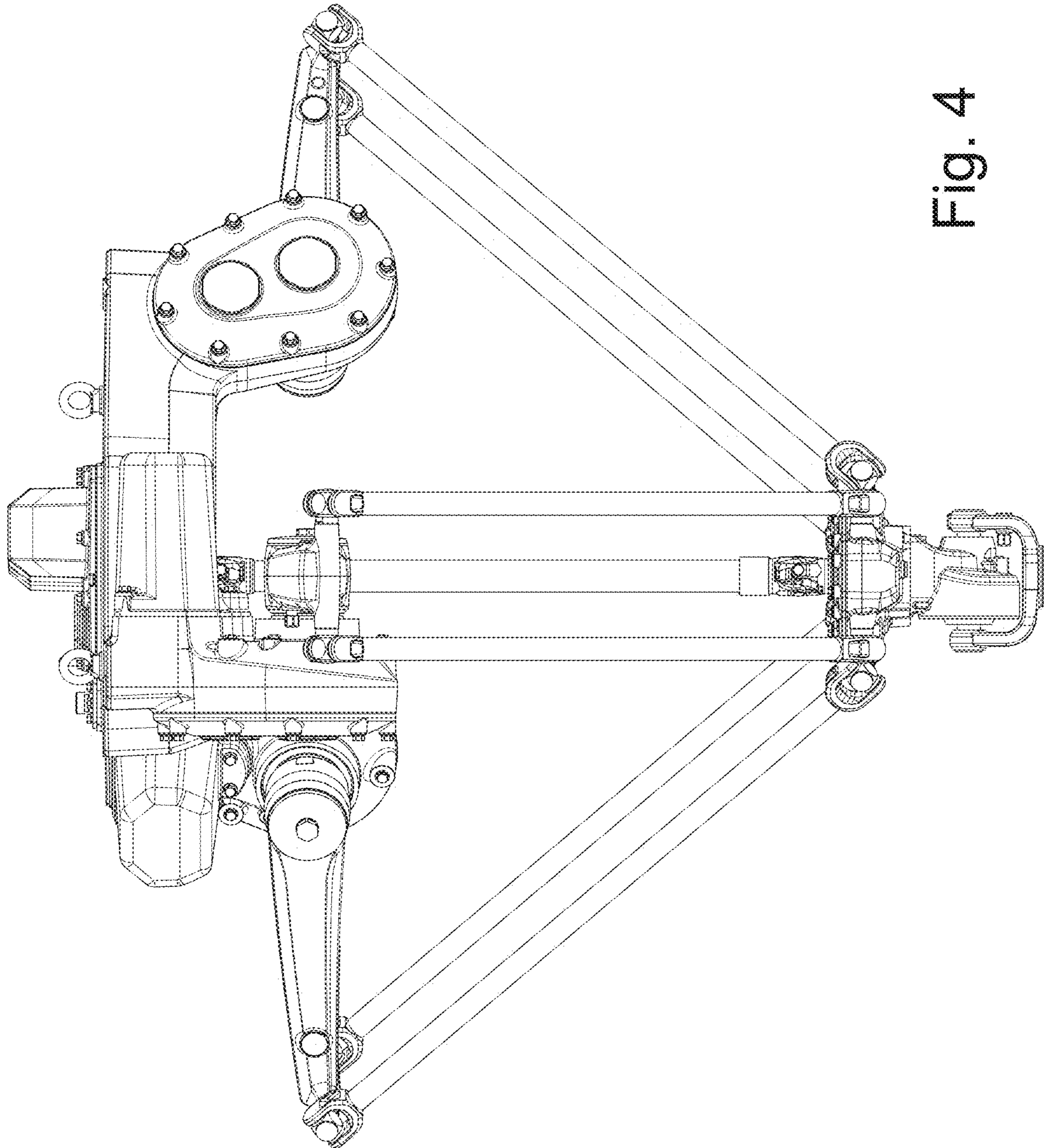


Fig. 4

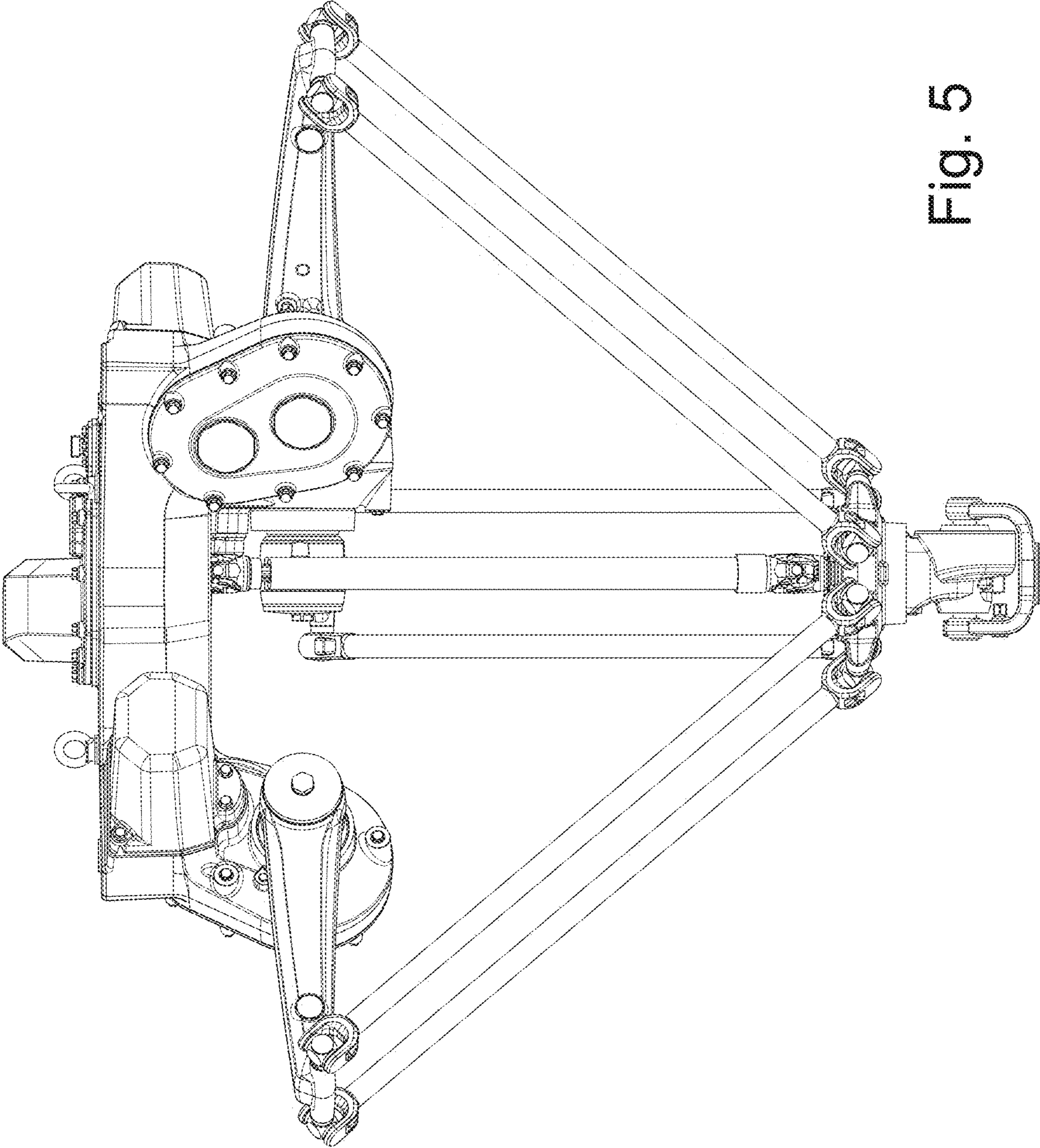


Fig. 5

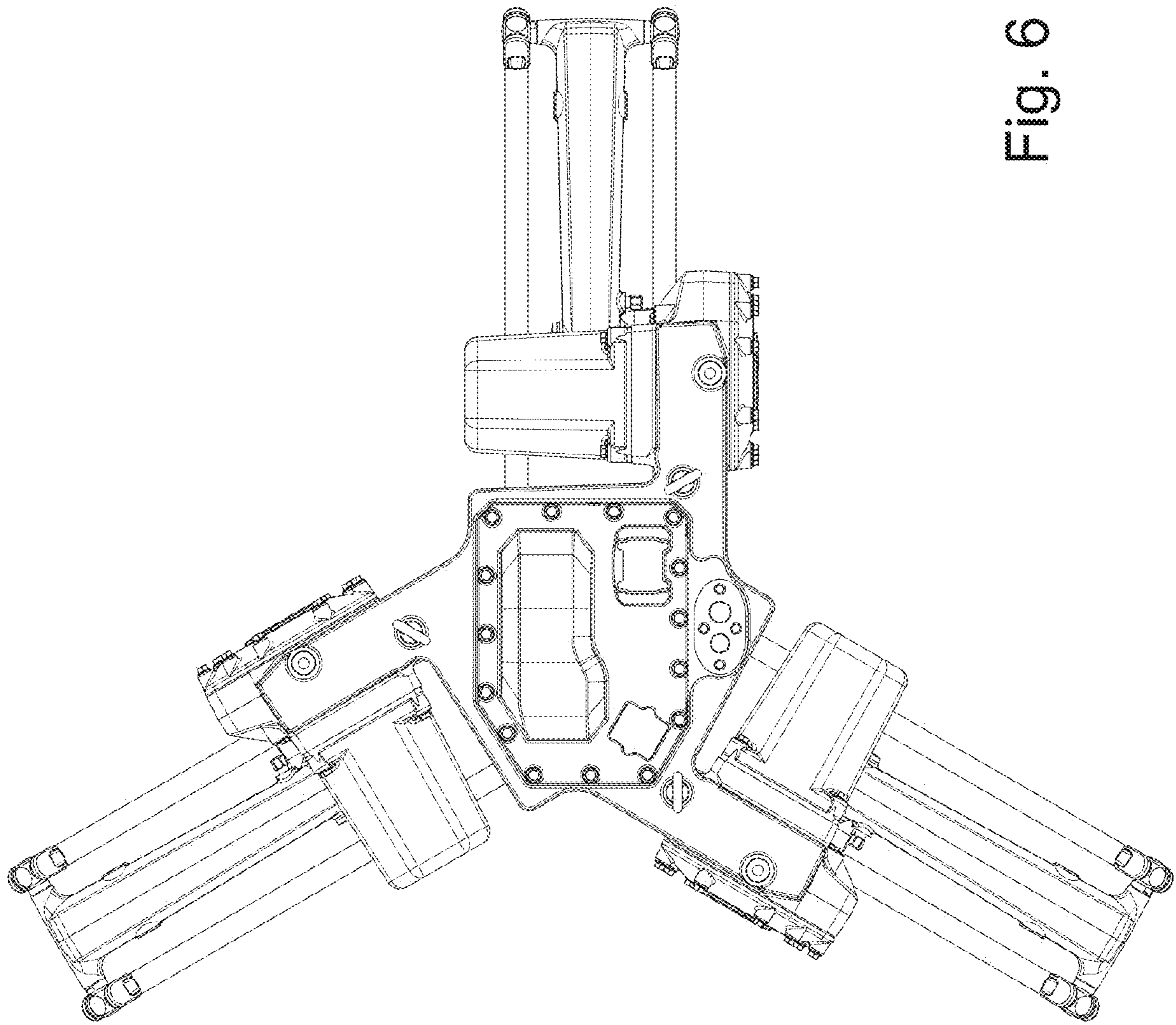


Fig. 6

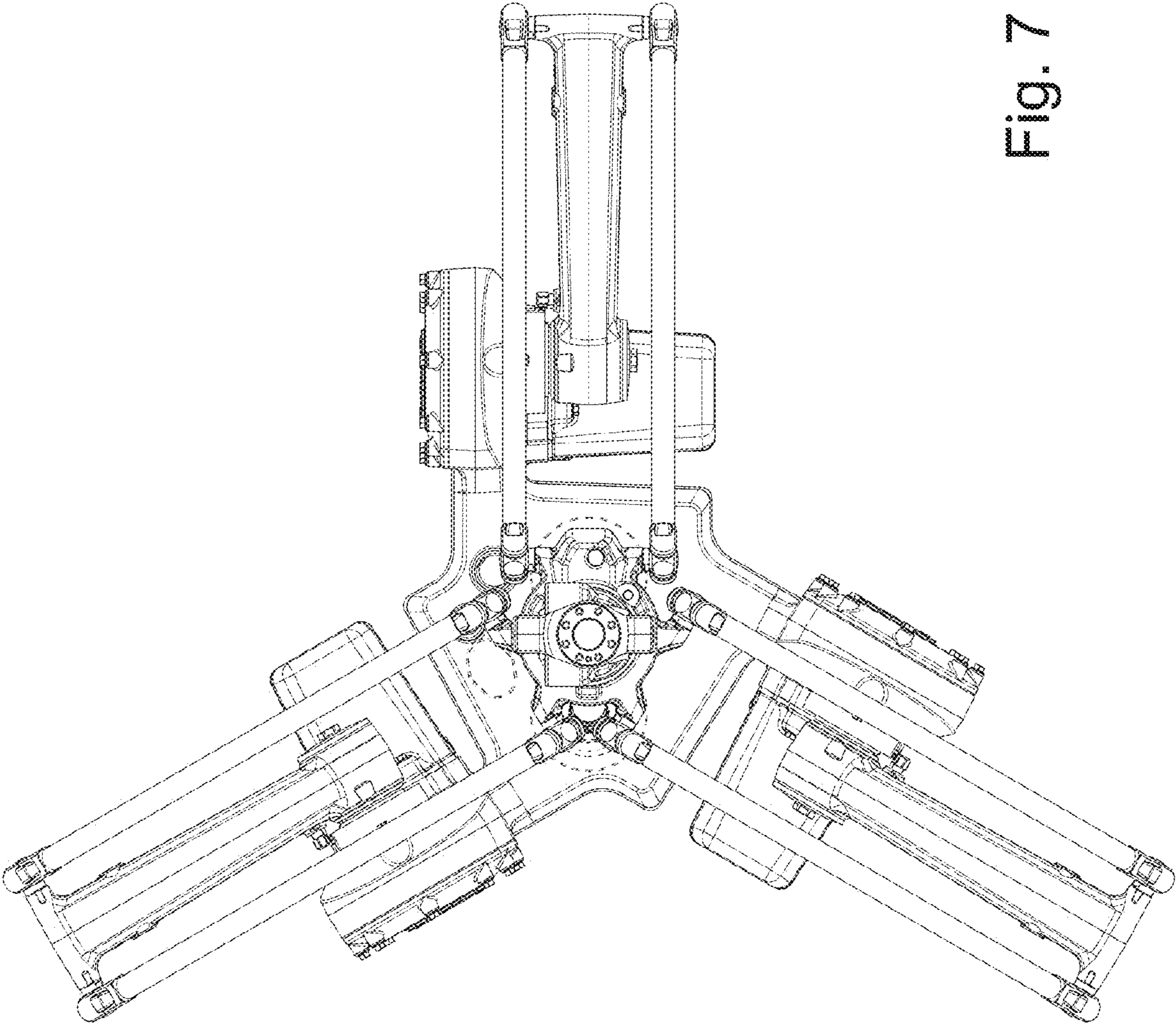


Fig. 7

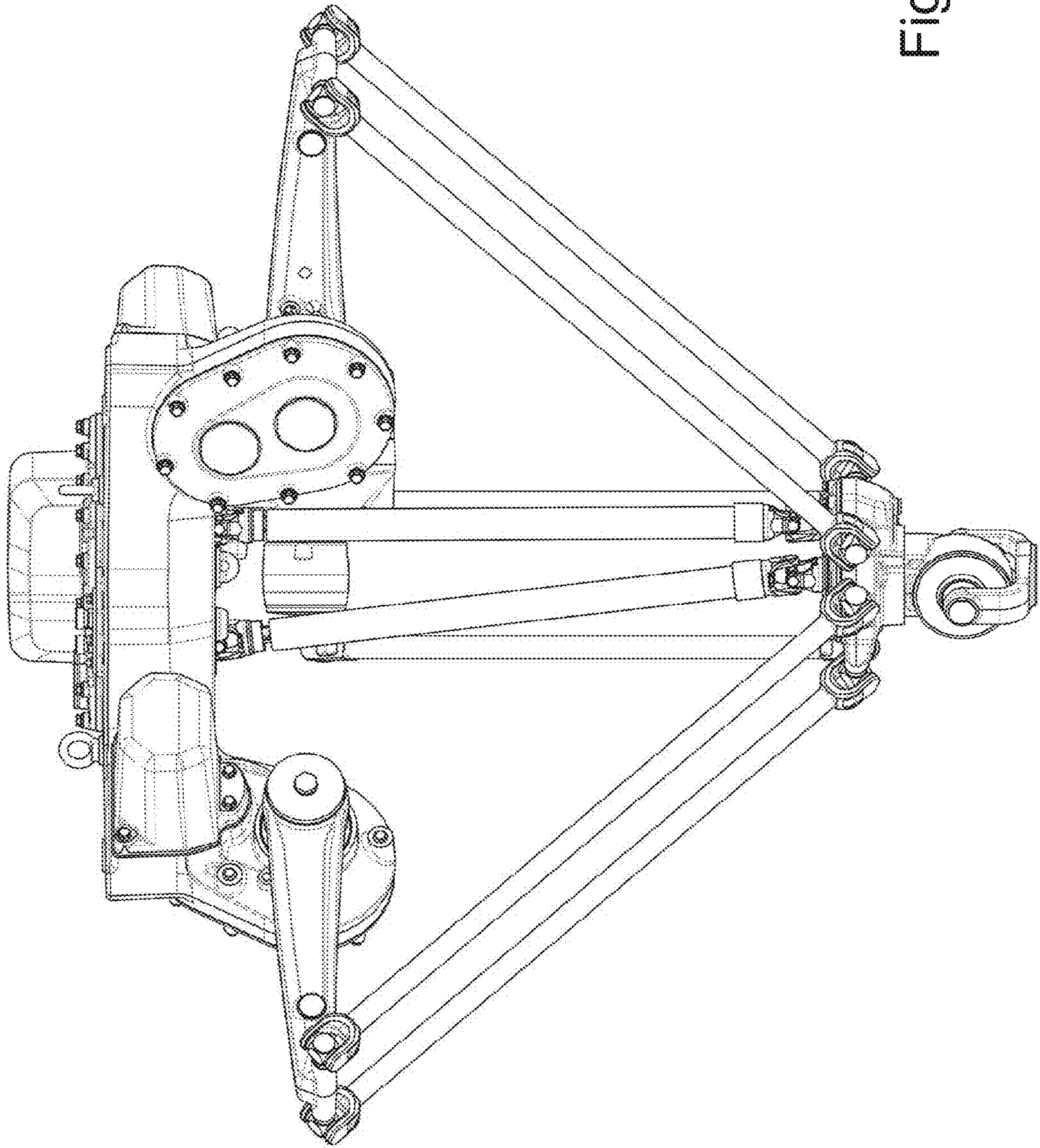


Fig. 8

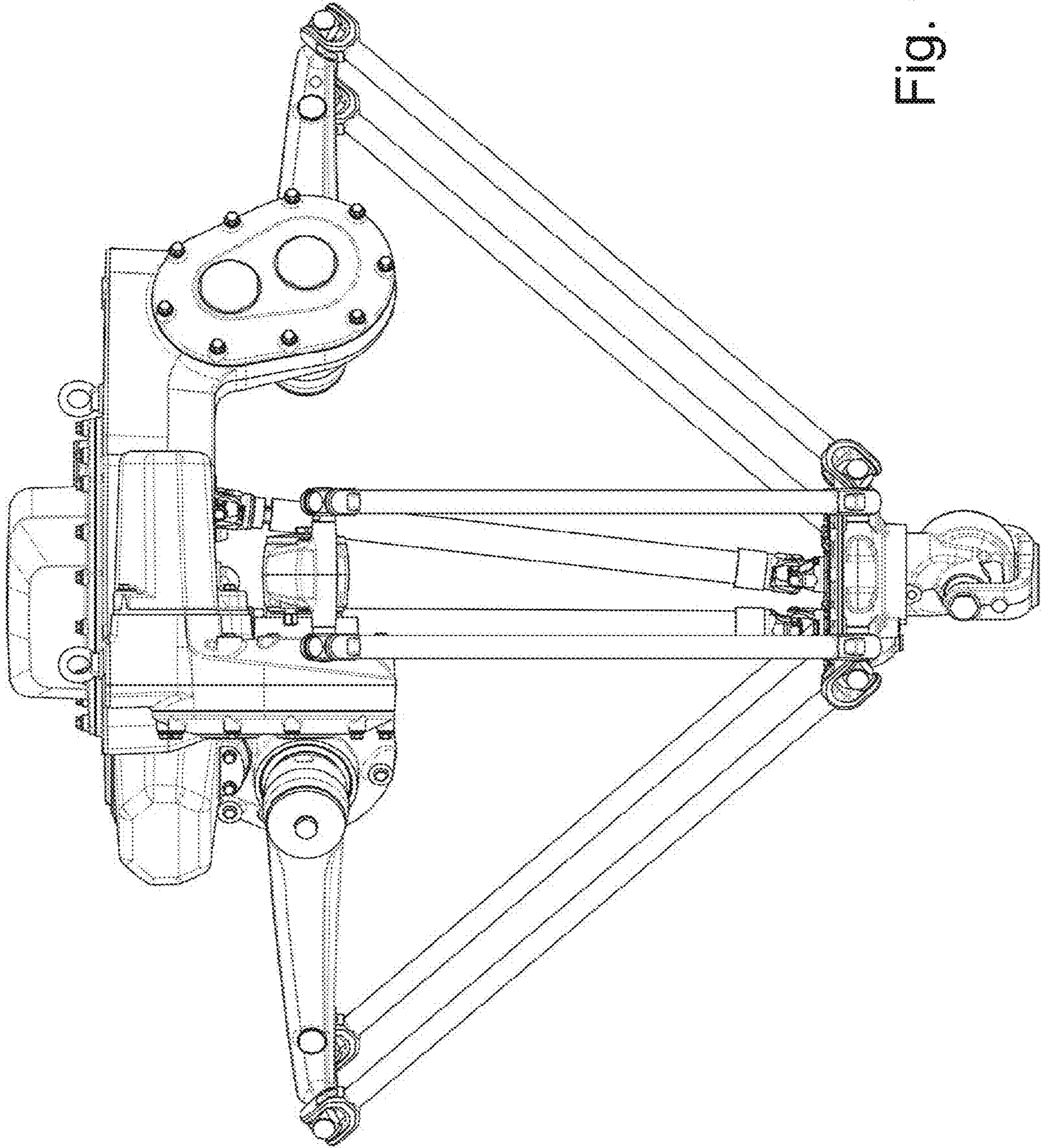


Fig. 9