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(12) **United States Design Patent** (10) **Patent No.:** **US D874,655 S**
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(54) **POSITIONING ARM FOR ARTICULATING ROBOTIC SURGICAL SYSTEM** 3,951,271 A * 4/1976 Mette B25J 9/041 414/591

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(**) Term: **15 Years**

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(51) **LOC (12) Cl.** **24-02**

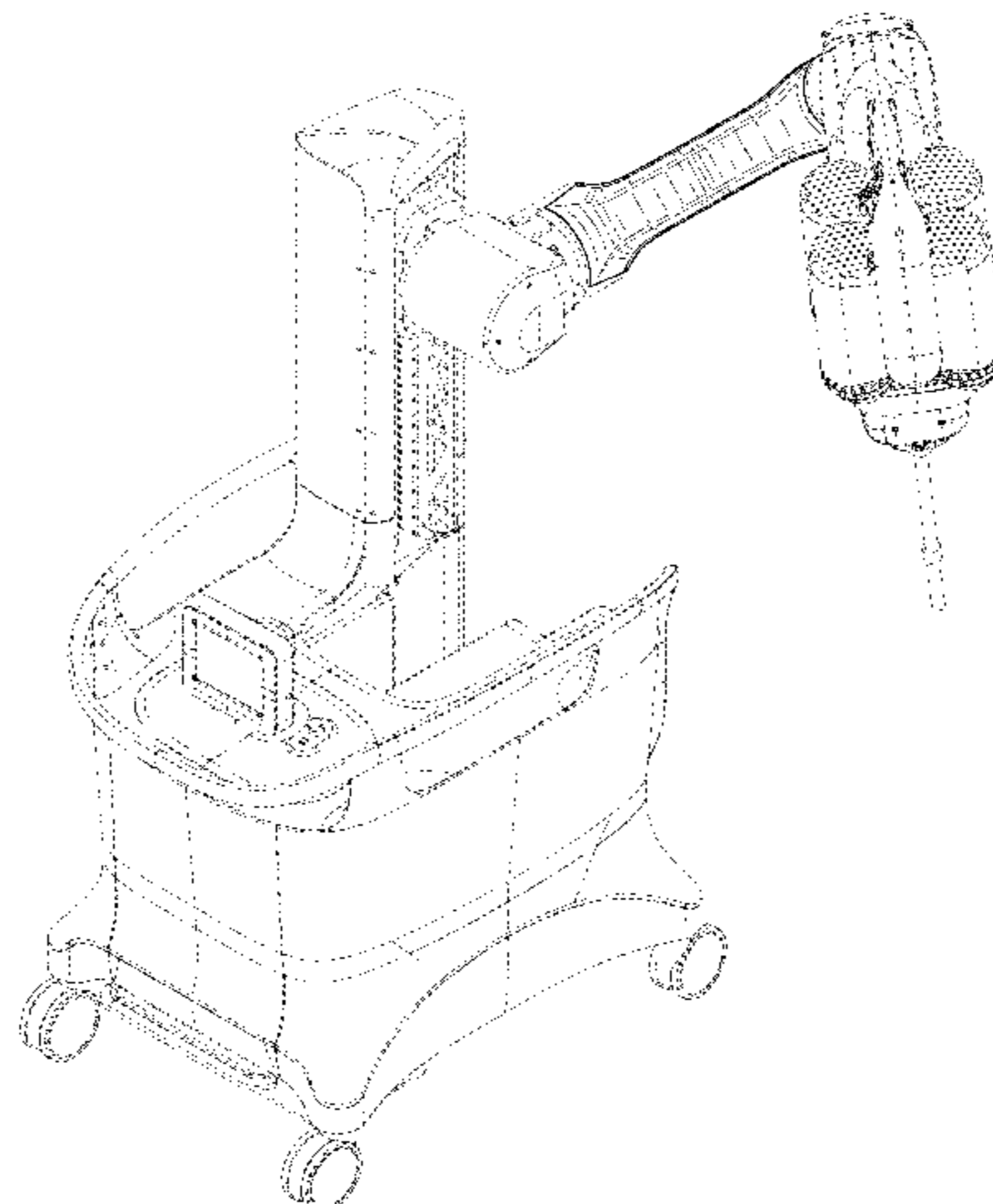
(52) **U.S. Cl.**
USPC **D24/185**

(58) **Field of Classification Search**
USPC D24/185, 199, 172, 232, 186, 170, 160, D24/158; D21/578; D15/199, 122; D13/168; D14/452
CPC .. A61B 34/71; A61B 18/22; B25J 9/08; B25J 9/041; B25J 9/1689; B25J 9/047; B25J 17/0283; B25J 18/06; A61H 1/0274; B05B 13/0431
See application file for complete search history.

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(74) Attorney, Agent, or Firm — Onello & Mello, LLP.

(57) CLAIM

The ornamental design for a positioning arm for articulating robotic surgical system, as shown and described.

DESCRIPTION

FIG. 1 is a front perspective view of a positioning arm for articulating robotic surgical system, illustrated in an extended position, in accordance with the present invention; FIG. 2 is a rear perspective view of a positioning arm for articulating robotic surgical system, illustrated in an extended position, in accordance with the present invention; FIG. 3 is a front view of a positioning arm for articulating robotic surgical system, illustrated in an extended position, in accordance with the present invention; FIG. 4 is a rear view of a positioning arm for articulating robotic surgical system, illustrated in an extended position, in accordance with the present invention; FIG. 5 is a top view of a positioning arm for articulating robotic surgical system, illustrated in an extended position, in accordance with the present invention; FIG. 6 is a bottom view of a positioning arm for articulating robotic surgical system, illustrated in an extended position, in accordance with the present invention; FIG. 7 is a left side view of a positioning arm for articulating robotic surgical system, illustrated in an extended position, in accordance with the present invention; FIG. 8 is a right side view of a positioning arm for articulating robotic surgical system, illustrated in an extended position, in accordance with the present invention; FIG. 9 is a front perspective view of a positioning arm for articulating robotic surgical system, illustrated in a retracted position, in accordance with the present invention; FIG. 10 is a rear perspective view of a positioning arm for articulating robotic surgical system, illustrated in a retracted position, in accordance with the present invention; FIG. 11 is a front view of a positioning arm for articulating robotic surgical system, illustrated in a retracted position, in accordance with the present invention; FIG. 12 is a rear view of a positioning arm for articulating robotic surgical system, illustrated in a retracted position, in accordance with the present invention; FIG. 13 is a top view of a positioning arm for articulating robotic surgical system, illustrated in a retracted position, in accordance with the present invention; FIG. 14 is a bottom view of a positioning arm for articulating robotic surgical system, illustrated in a retracted position, in accordance with the present invention; FIG. 15 is a left side view of a positioning arm for articulating robotic surgical system, illustrated in a retracted position, in accordance with the present invention; and, FIG. 16 is a right side view of a positioning arm for articulating robotic surgical system, illustrated in a retracted position, in accordance with the present invention.

In the drawings, the broken lines are for the purpose of illustrating environment only and form no part of the claimed design.

1 Claim, 16 Drawing Sheets

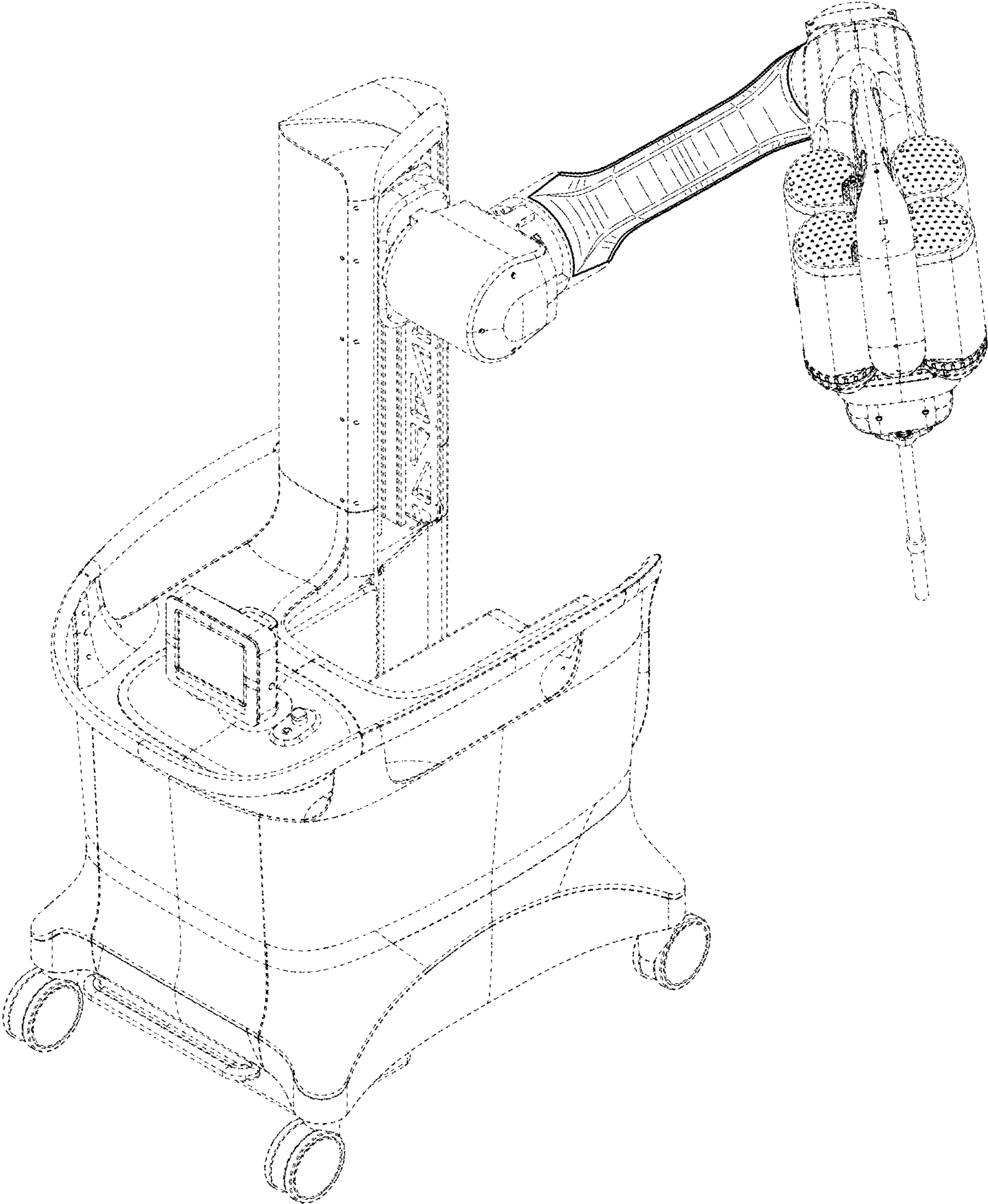


FIG. 1

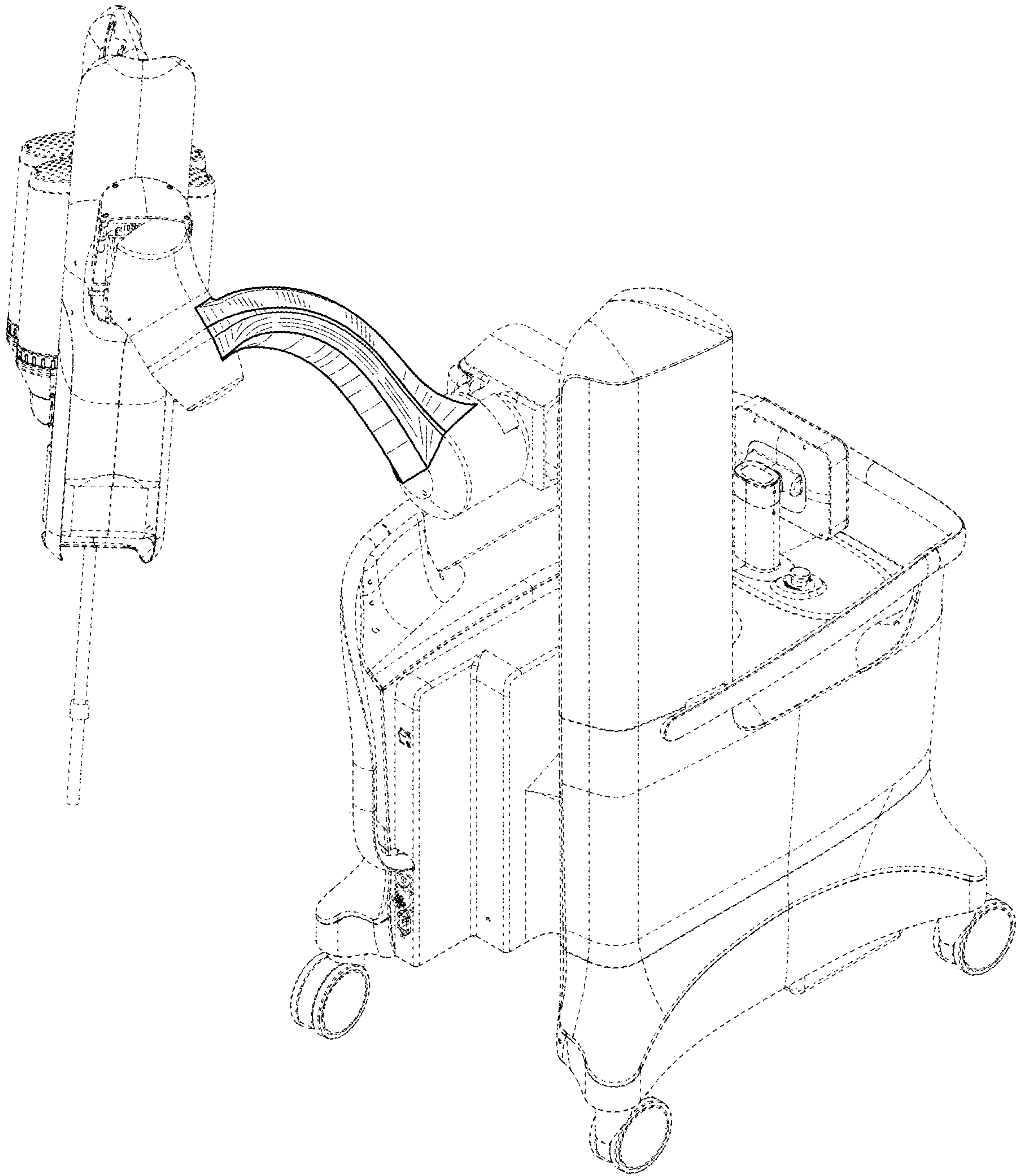


FIG. 2

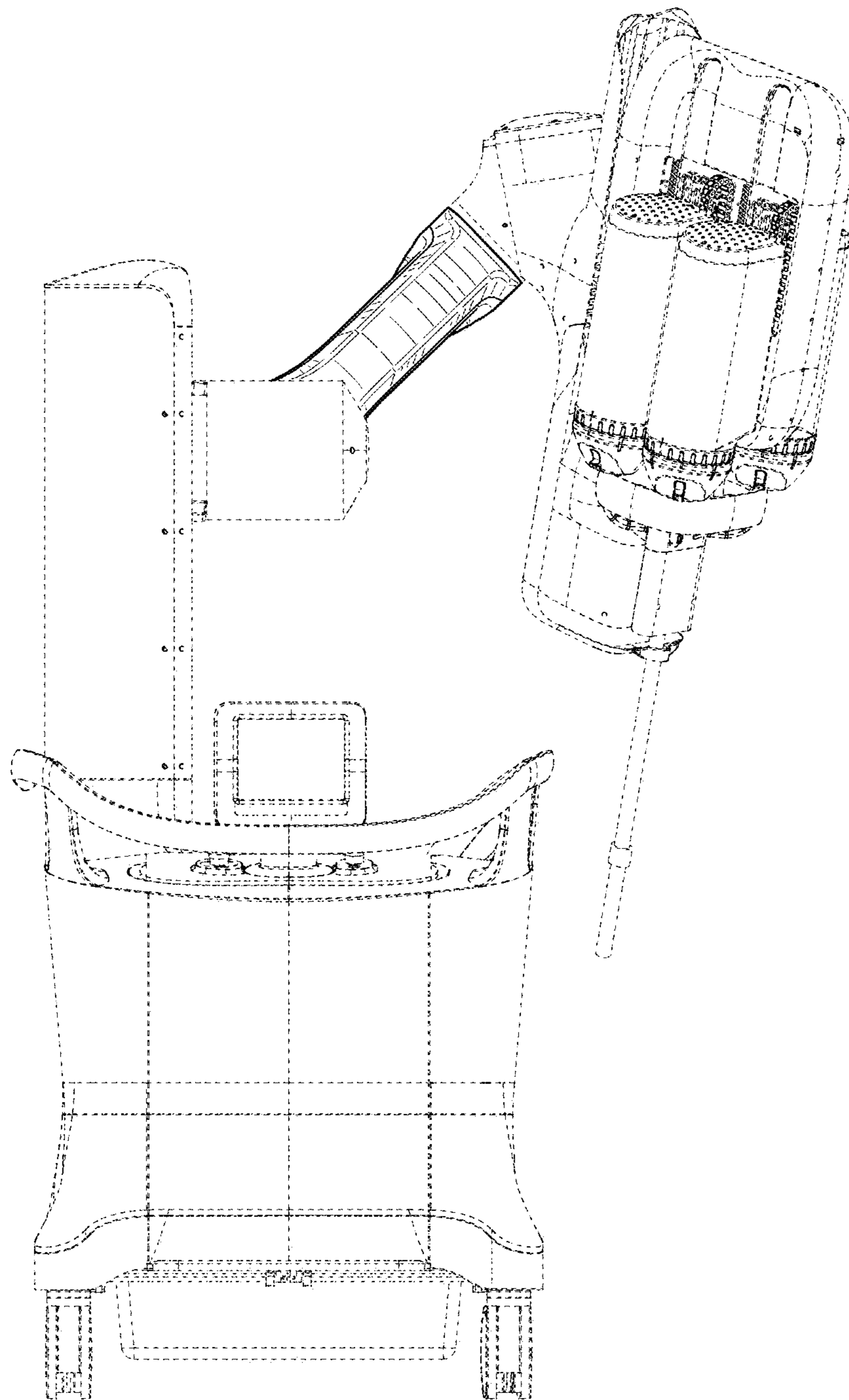


FIG. 3

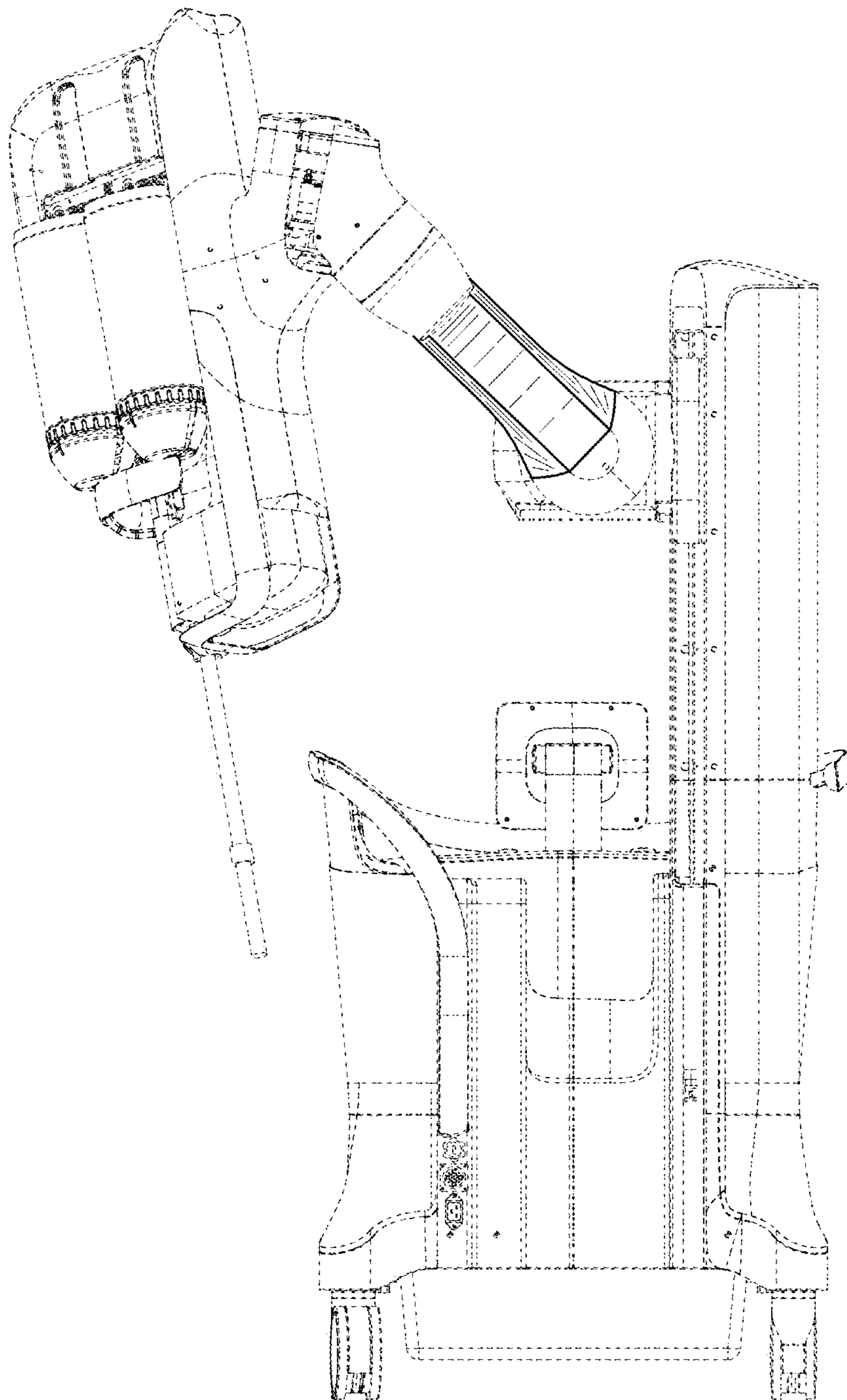


FIG. 4

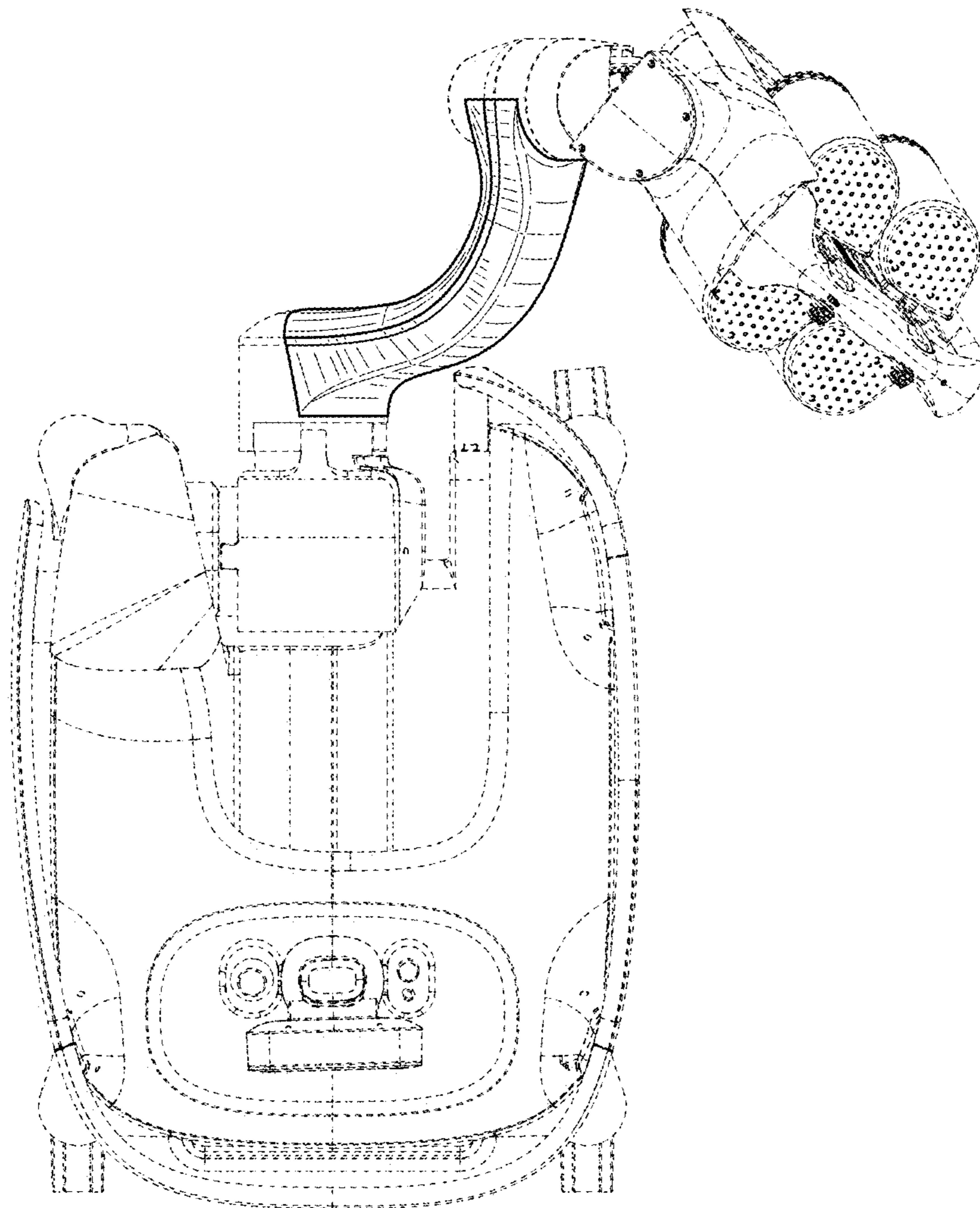


FIG. 5

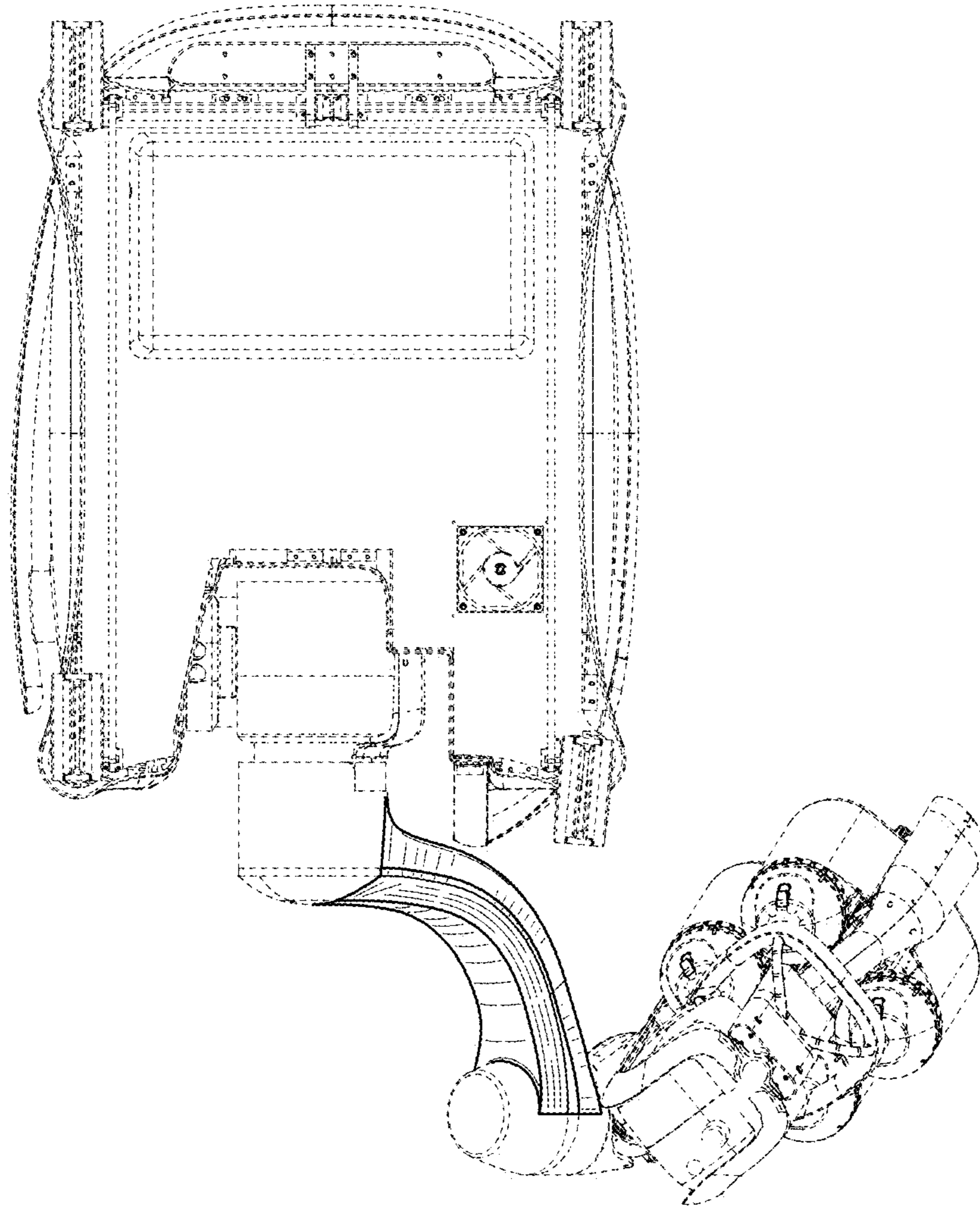


FIG. 6

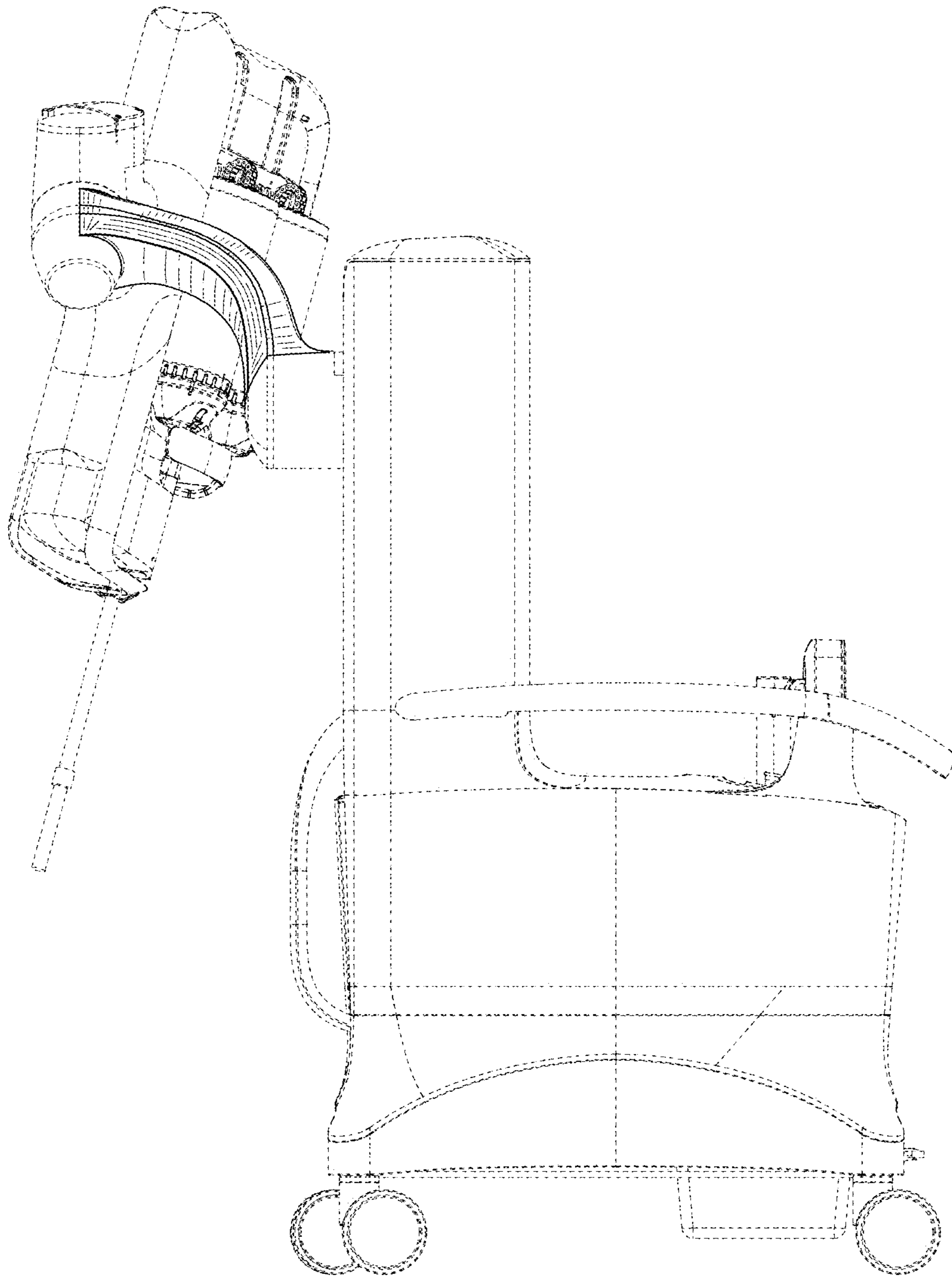


FIG. 7

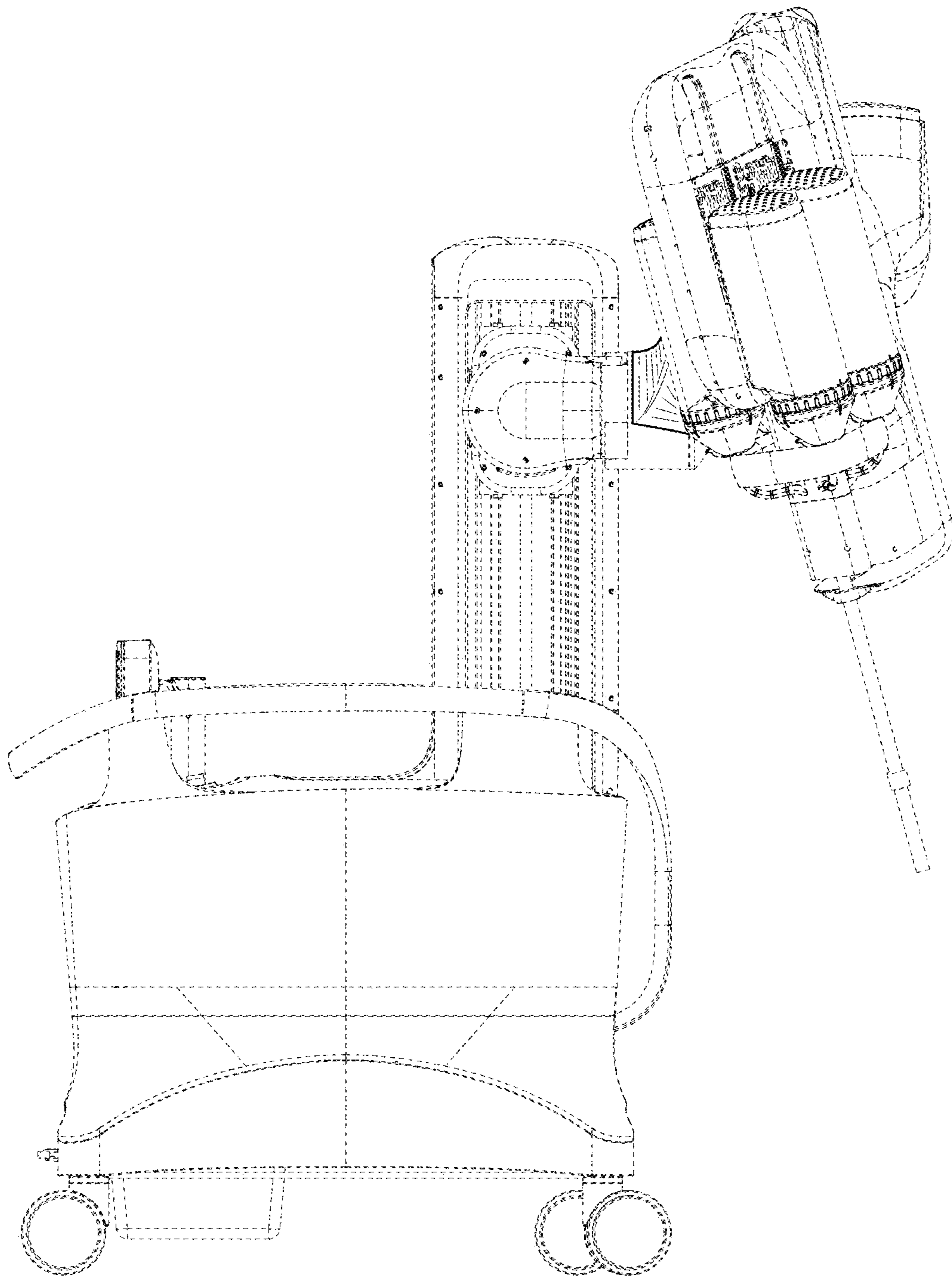


FIG. 8

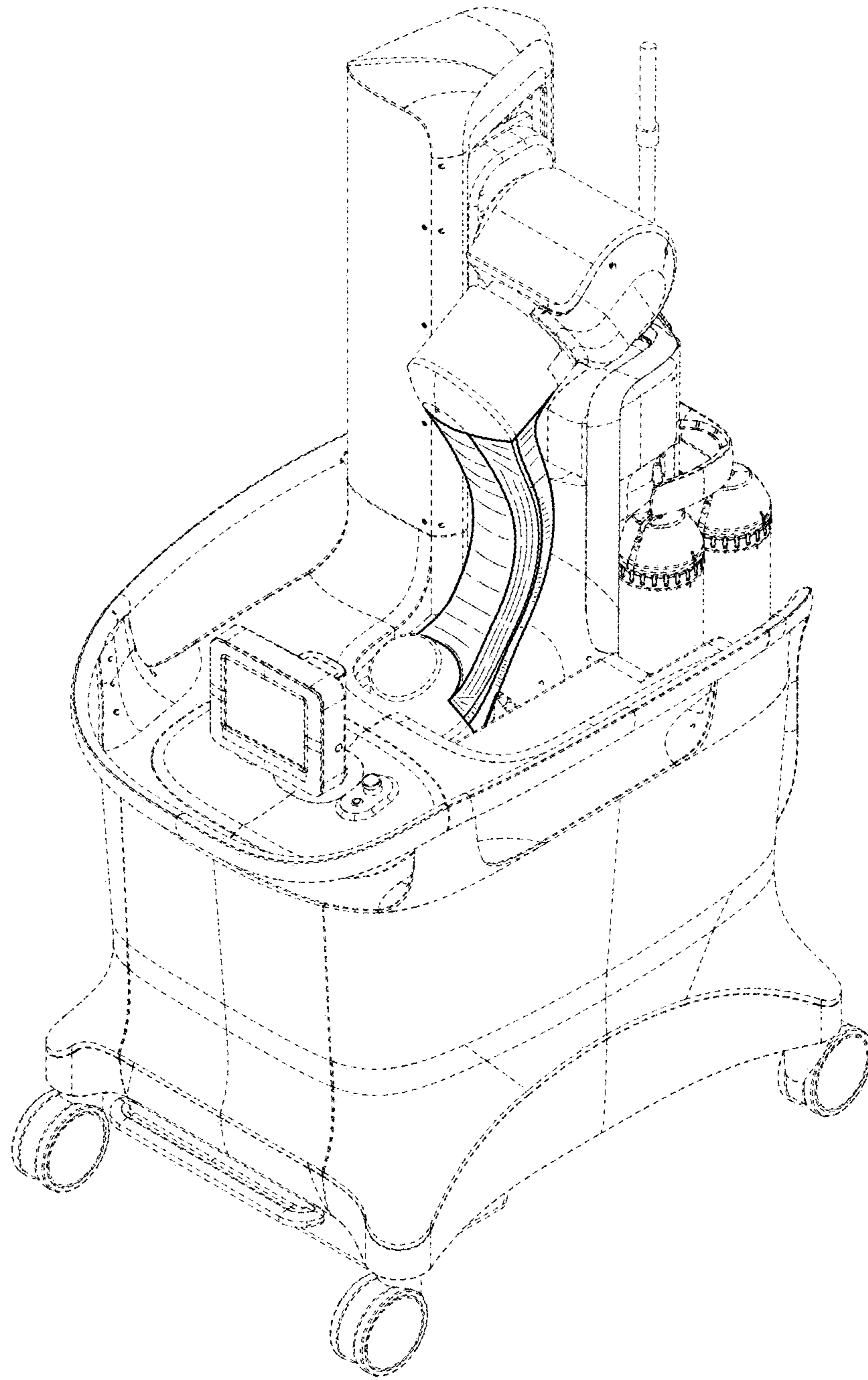


FIG. 9

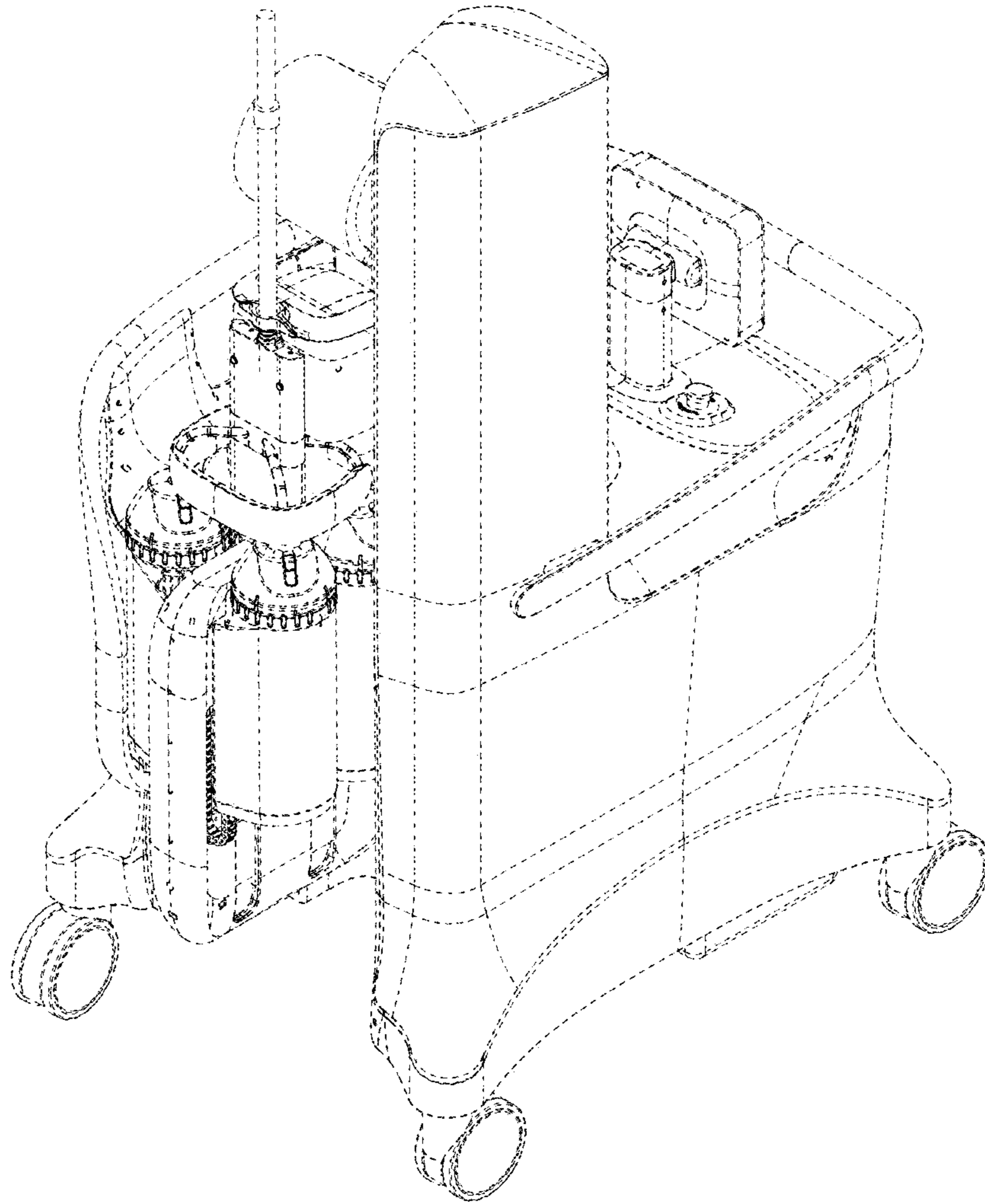


FIG. 10

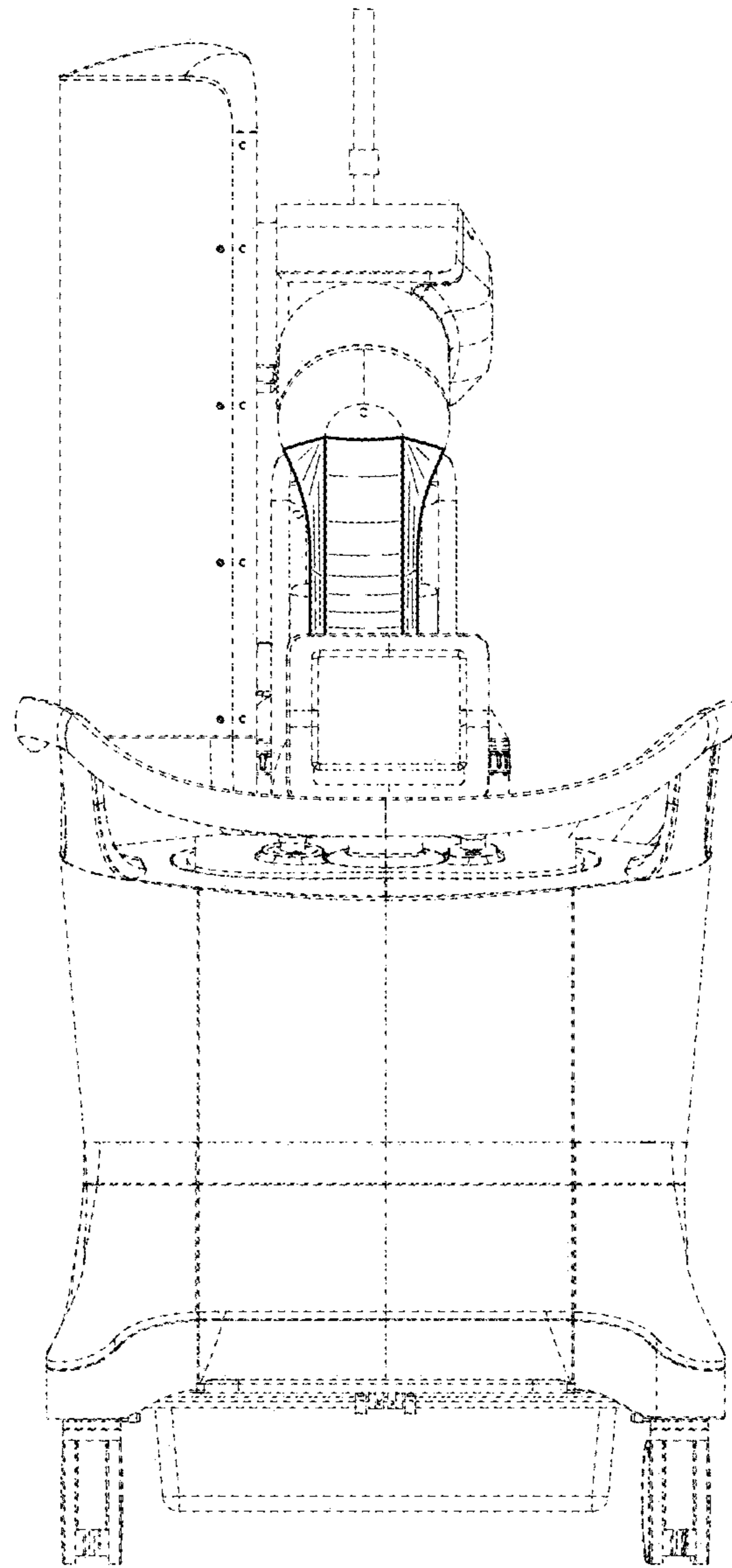


FIG. 11

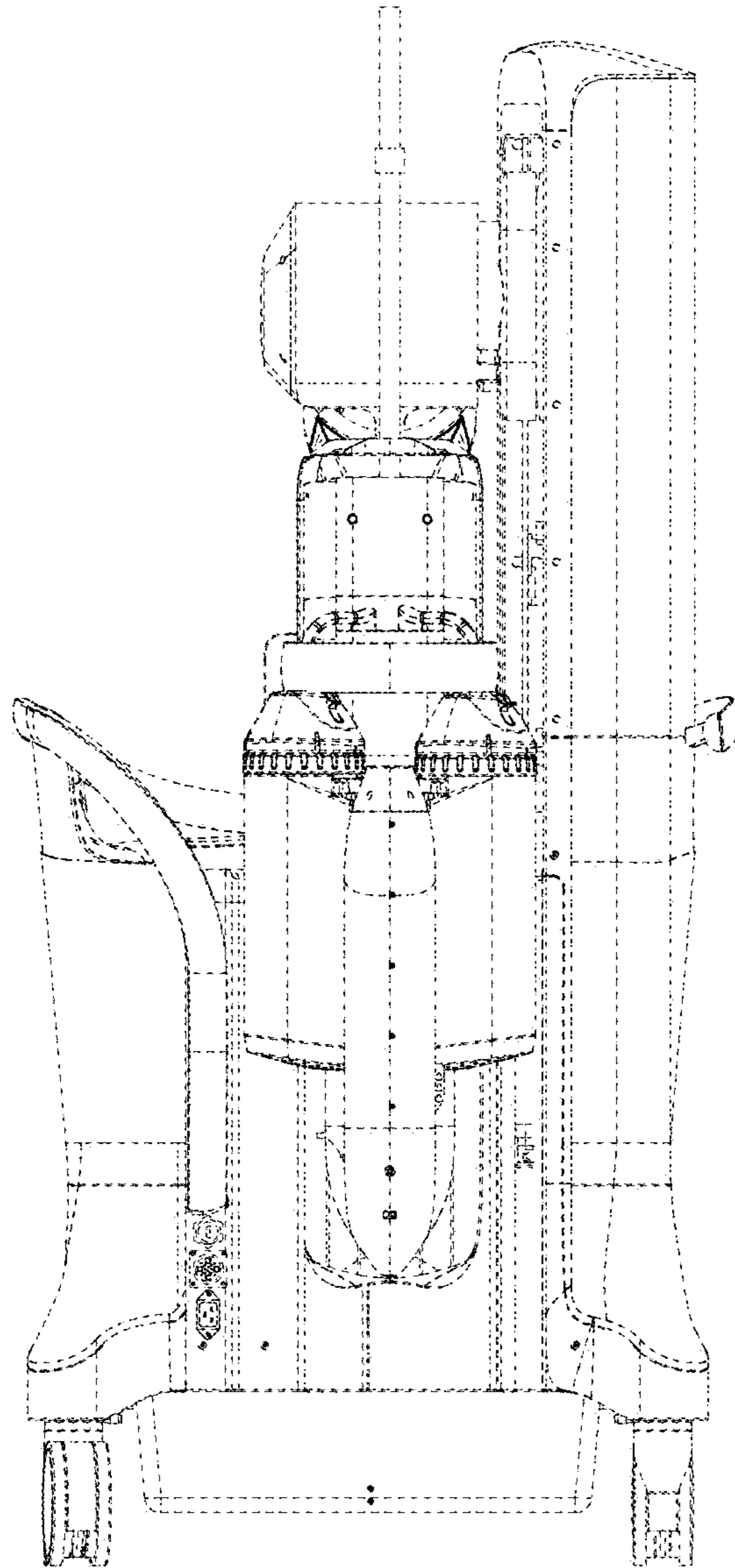


FIG. 12

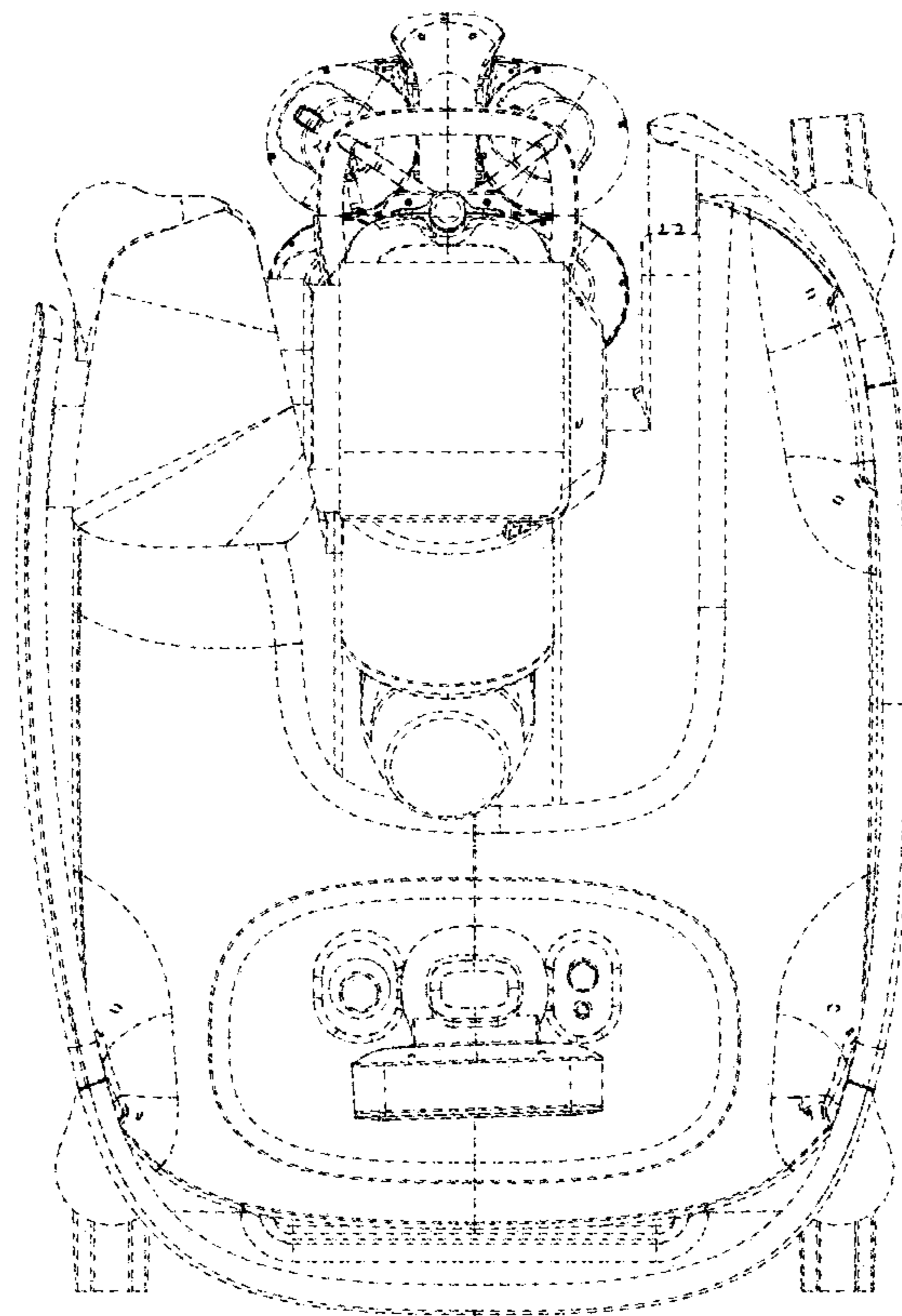


FIG. 13

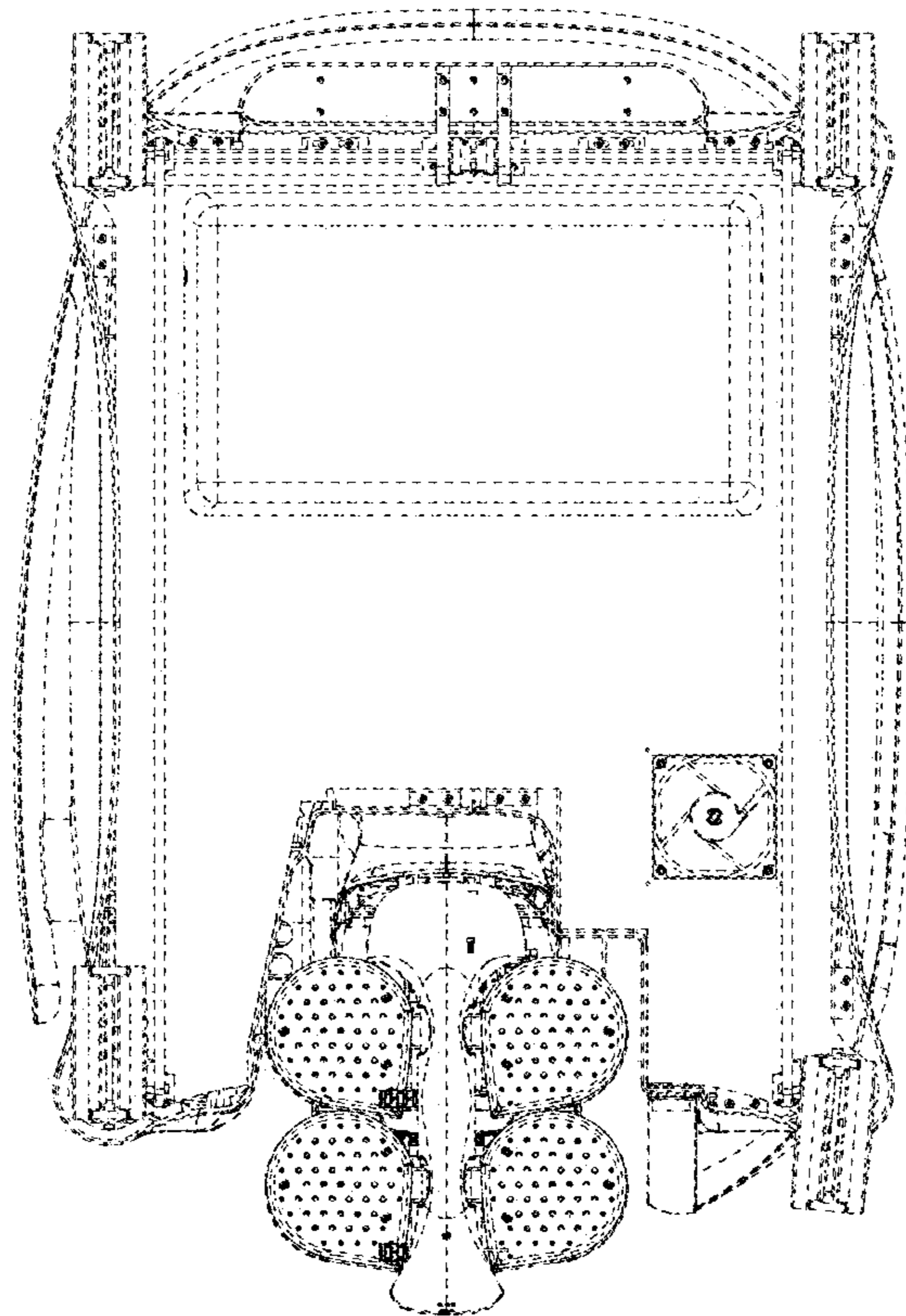


FIG. 14

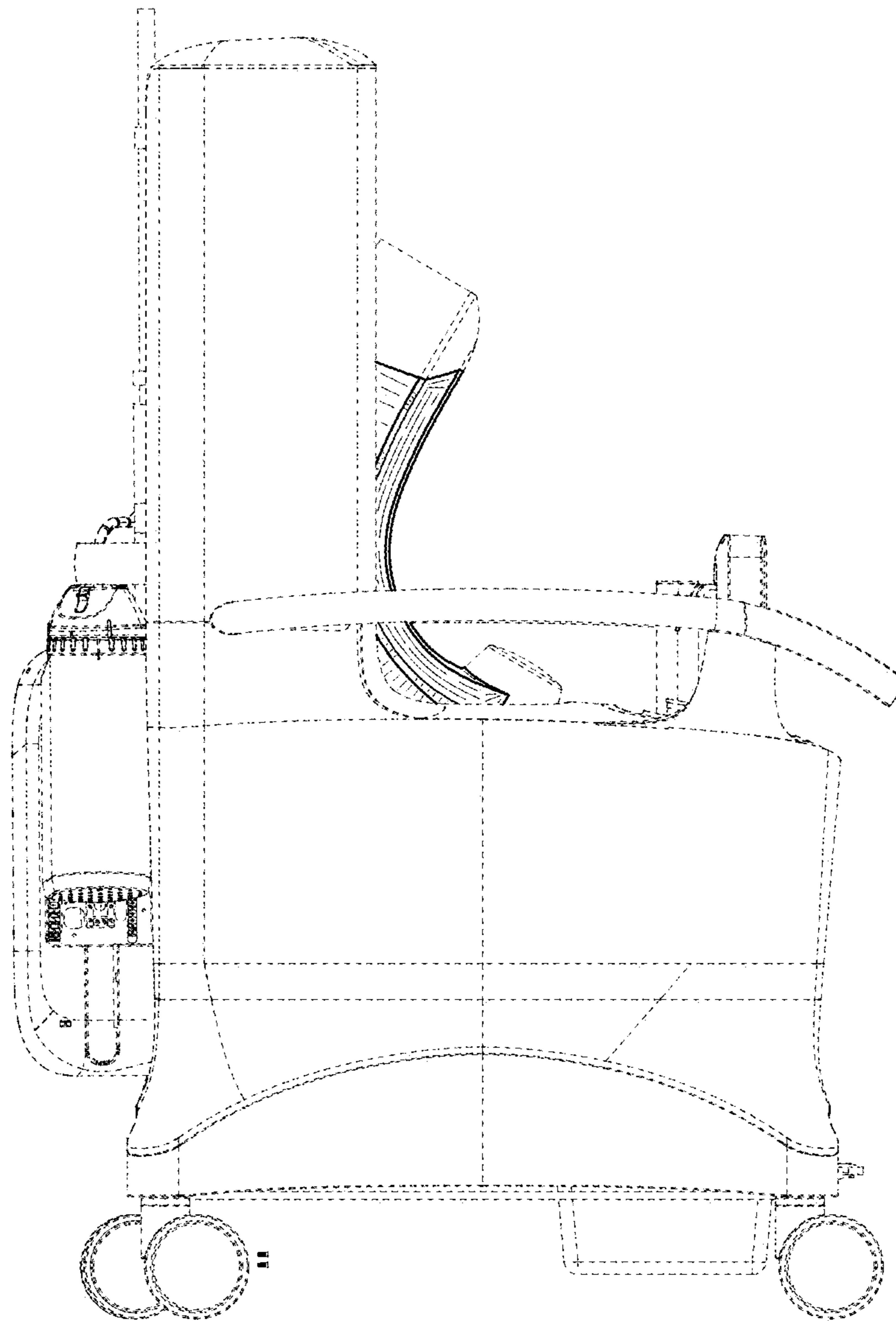


FIG. 15

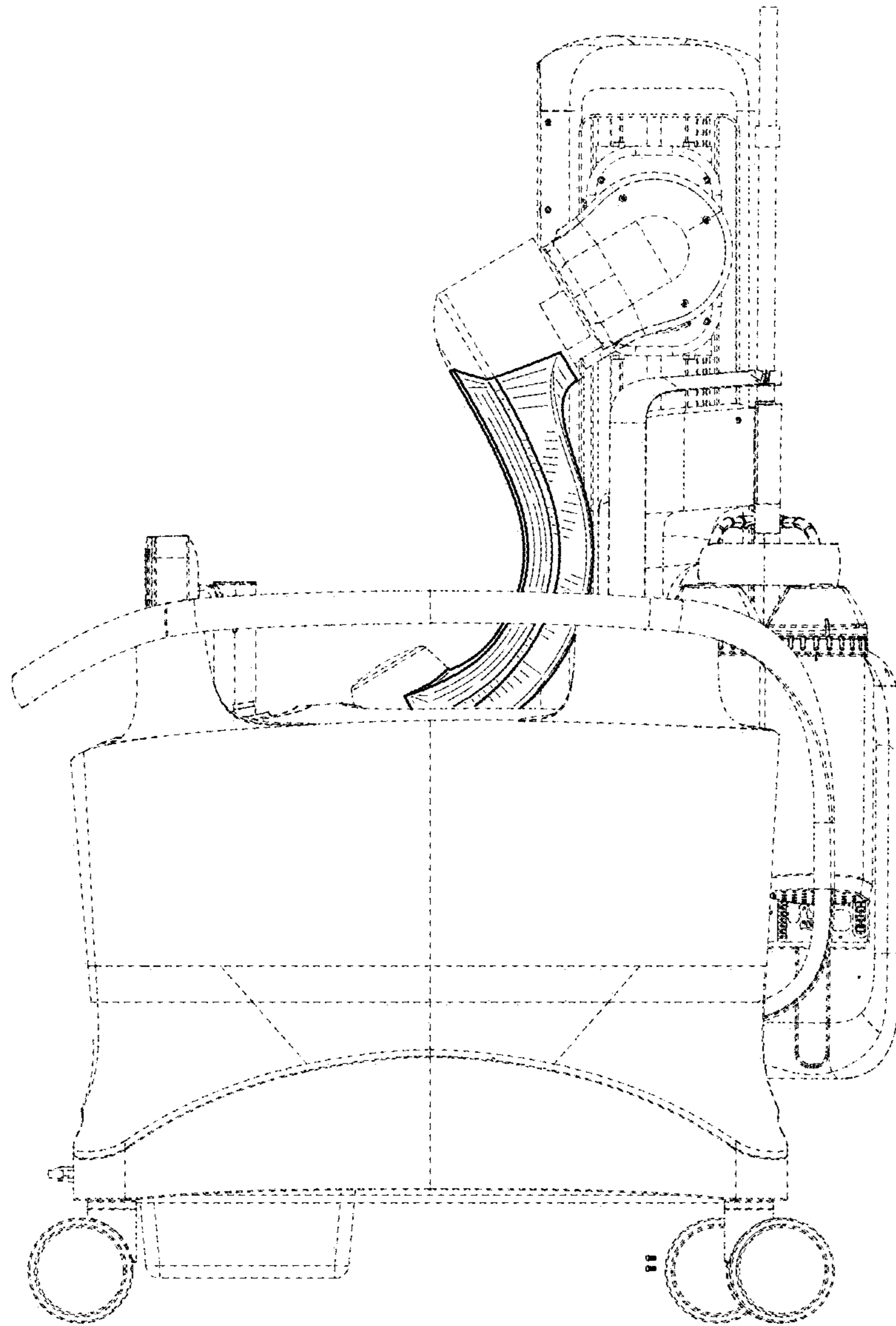


FIG. 16