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(12) United States Design Patent

Hatano et al.

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(54) **GRIPPER FOR INDUSTRIAL ROBOT**

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(73) Assignee: **Nitta Corporation**, Osaka-Shi (JP)

(**) Term: **15 Years**

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(52) **U.S. Cl.**
USPC **D15/199**

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CPC B25J 11/0045; B25J 15/08; B25J 15/024; B25J 15/026; B25J 15/0475; B25J 15/0042; B65G 47/90; H05K 13/02; Y10S 294/902; Y10S 294/907
See application file for complete search history.

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(57) **CLAIM**

The ornamental design for a gripper for industrial robot, as shown and described.

DESCRIPTION

FIG. **1** is a perspective view of a gripper for industrial robot illustrating our new design;
FIG. **2** is a bottom perspective view thereof;
FIG. **3** is a front view thereof;
FIG. **4** is a rear view thereof;
FIG. **5** is a right view thereof;
FIG. **6** is a left view thereof;
FIG. **7** is a top view thereof; and,
FIG. **8** is a bottom view thereof.
The gripper for industrial robot comprises a finger portion to grip an object.
The broken lines in the drawings depict portions of the gripper for industrial robot which form no part of the claimed design.

1 Claim, 8 Drawing Sheets

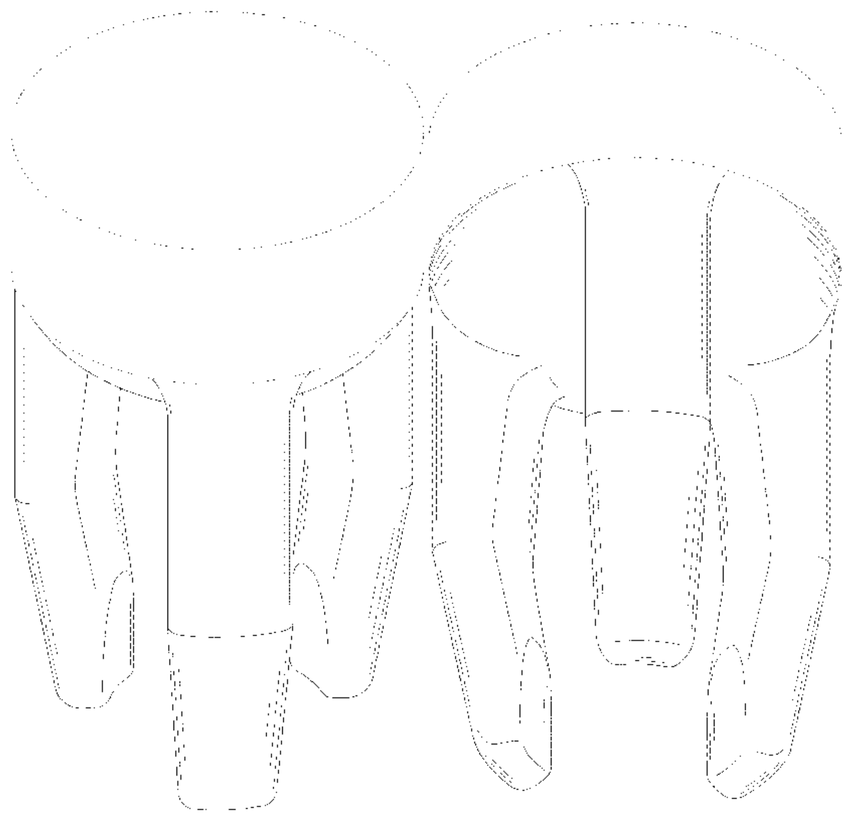

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Fig. 1

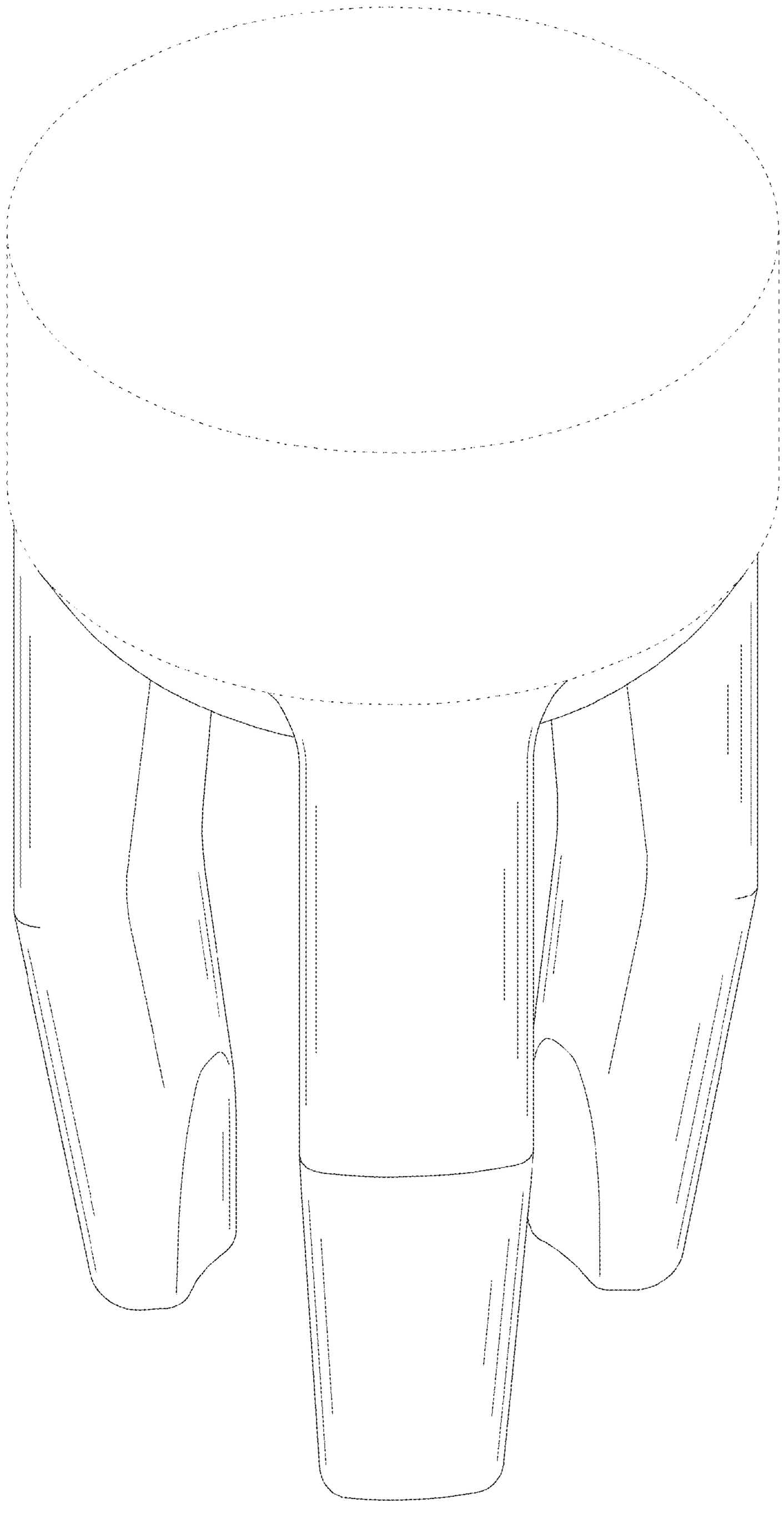

Fig. 2

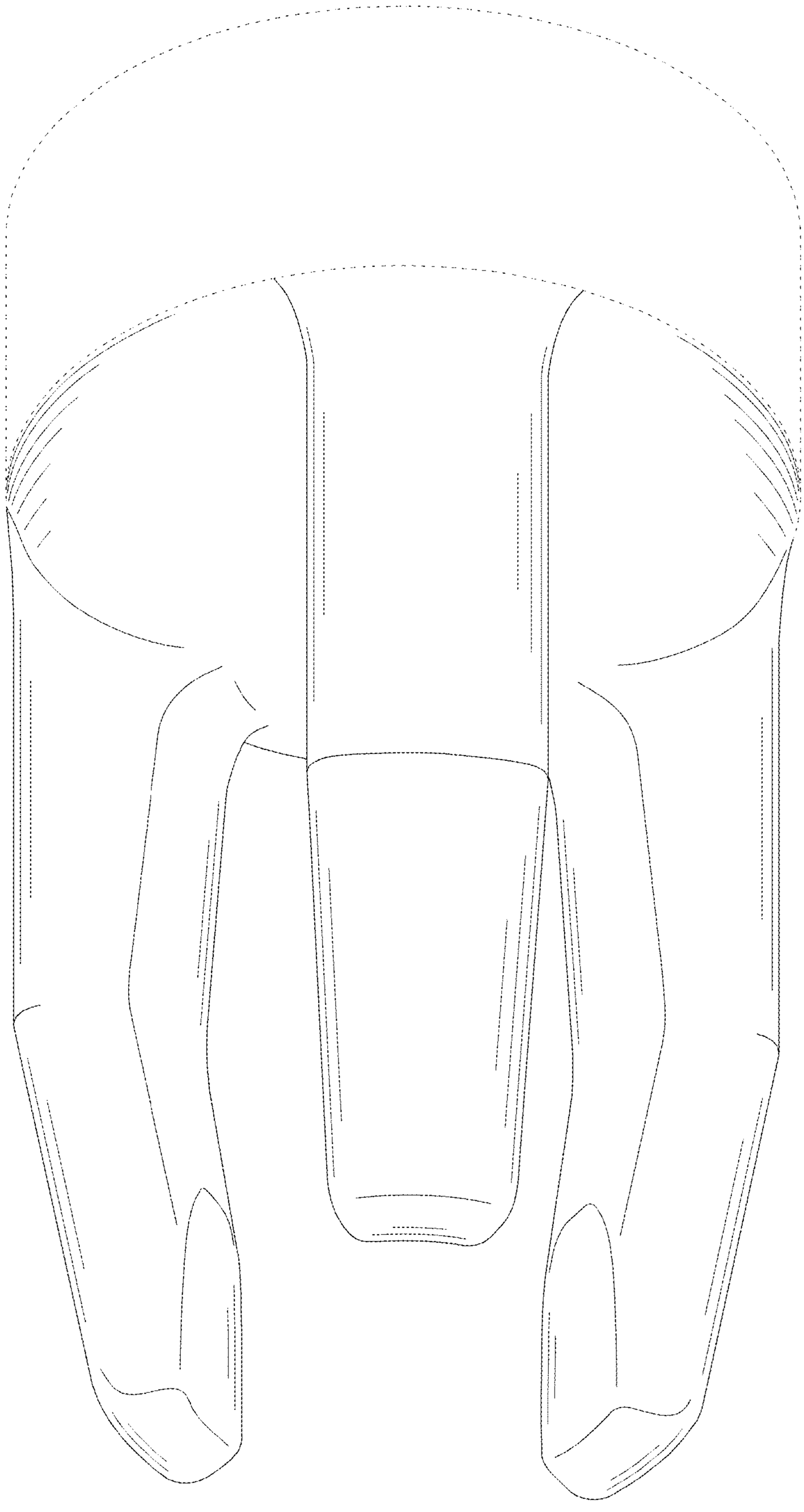

Fig. 3

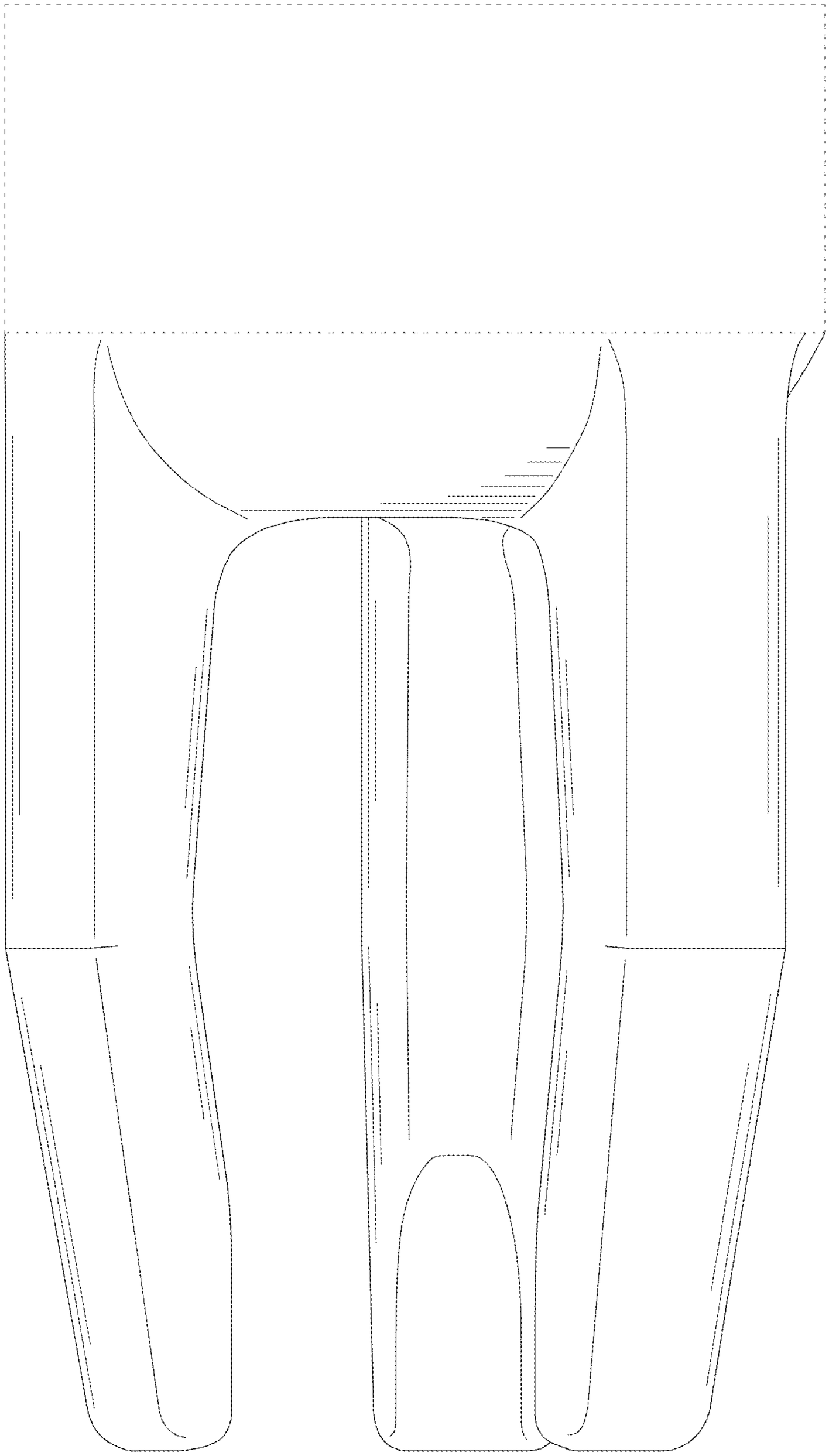

Fig. 4

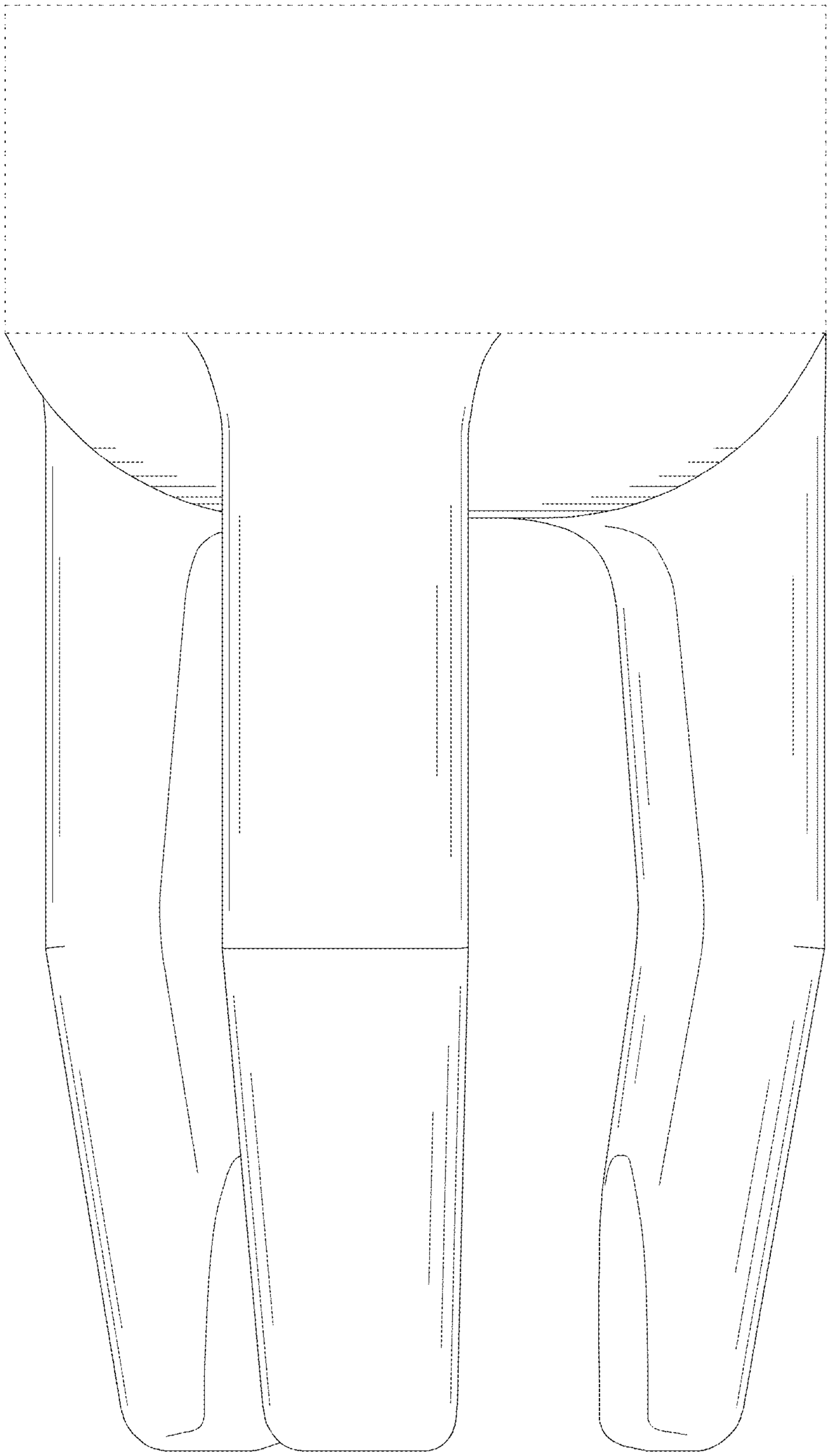

Fig. 5

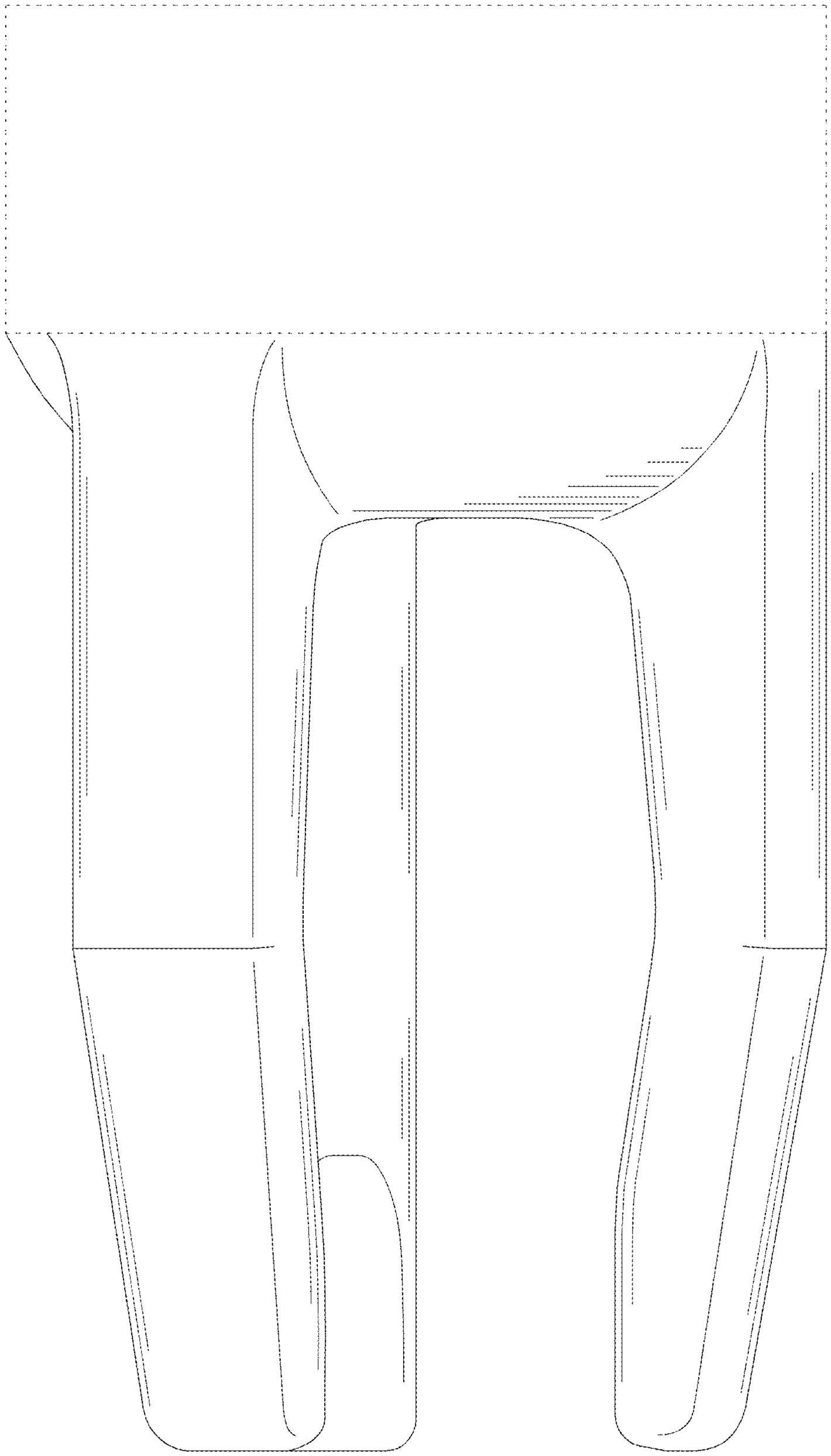

Fig. 6

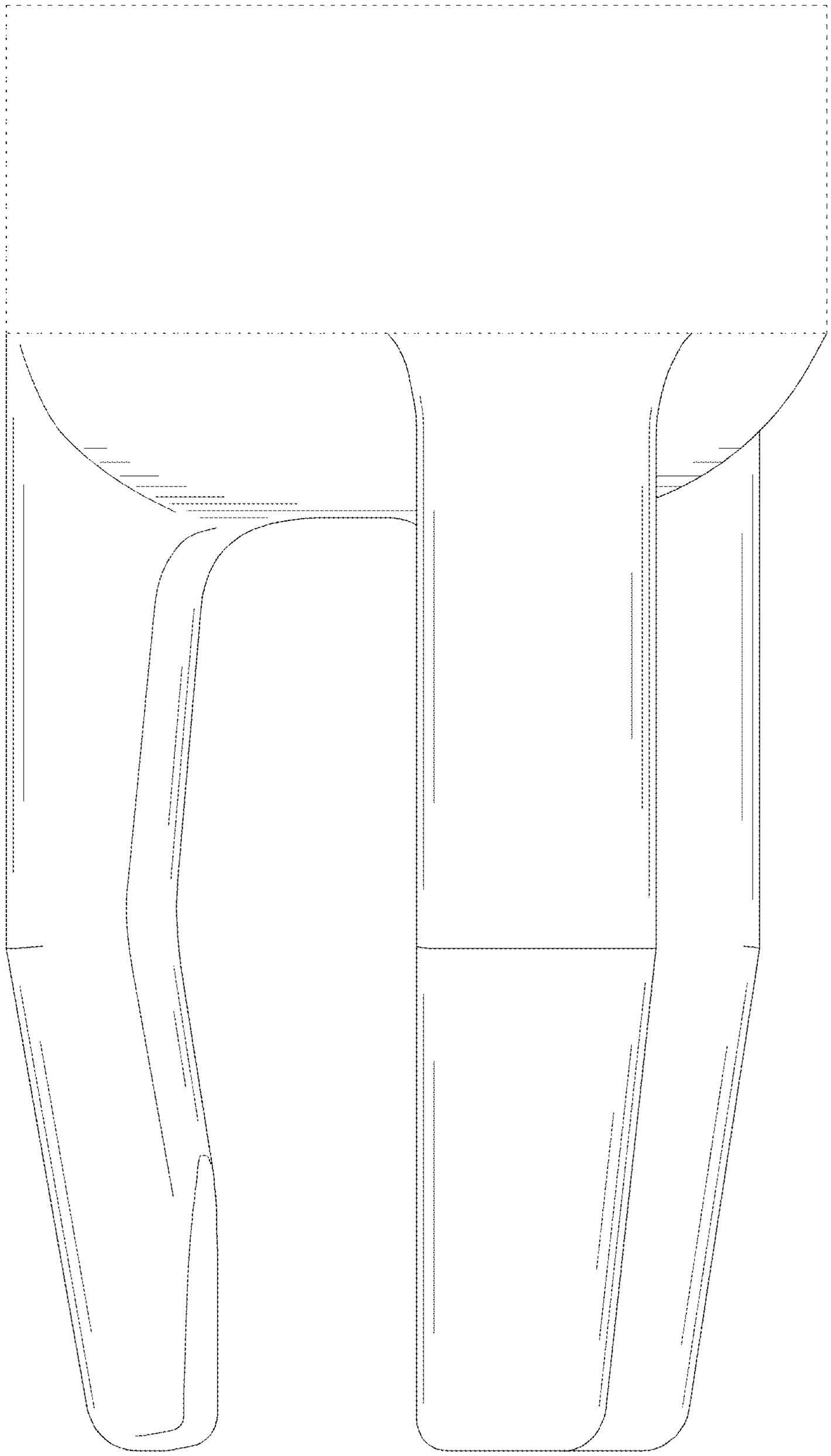

Fig. 7

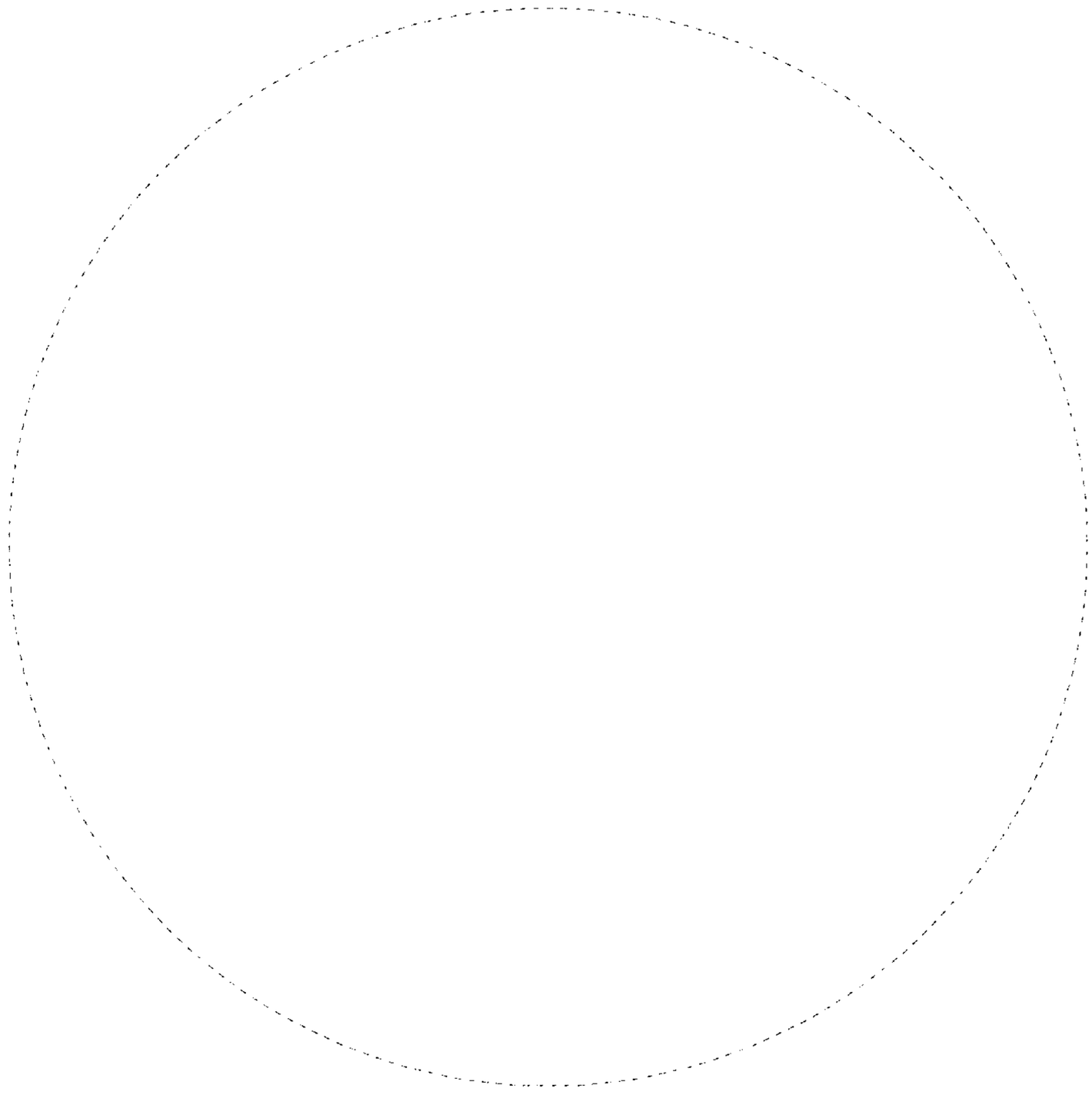

Fig. 8