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Hatano et al.

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(54) **GRIPPER FOR INDUSTRIAL ROBOT**

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(**) Term: **15 Years**

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(52) **U.S. Cl.**
USPC **D15/199**; D15/138

(58) **Field of Classification Search**
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CPC B25J 11/0045; B25J 15/08; B25J 15/024;
B25J 15/026; B25J 15/0475; B25J
15/0042; B65G 47/90; H05K 13/02;
Y10S 294/902; Y10S 294/907
See application file for complete search history.

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(57) **CLAIM**

The ornamental design for a gripper for industrial robot, as shown and described.

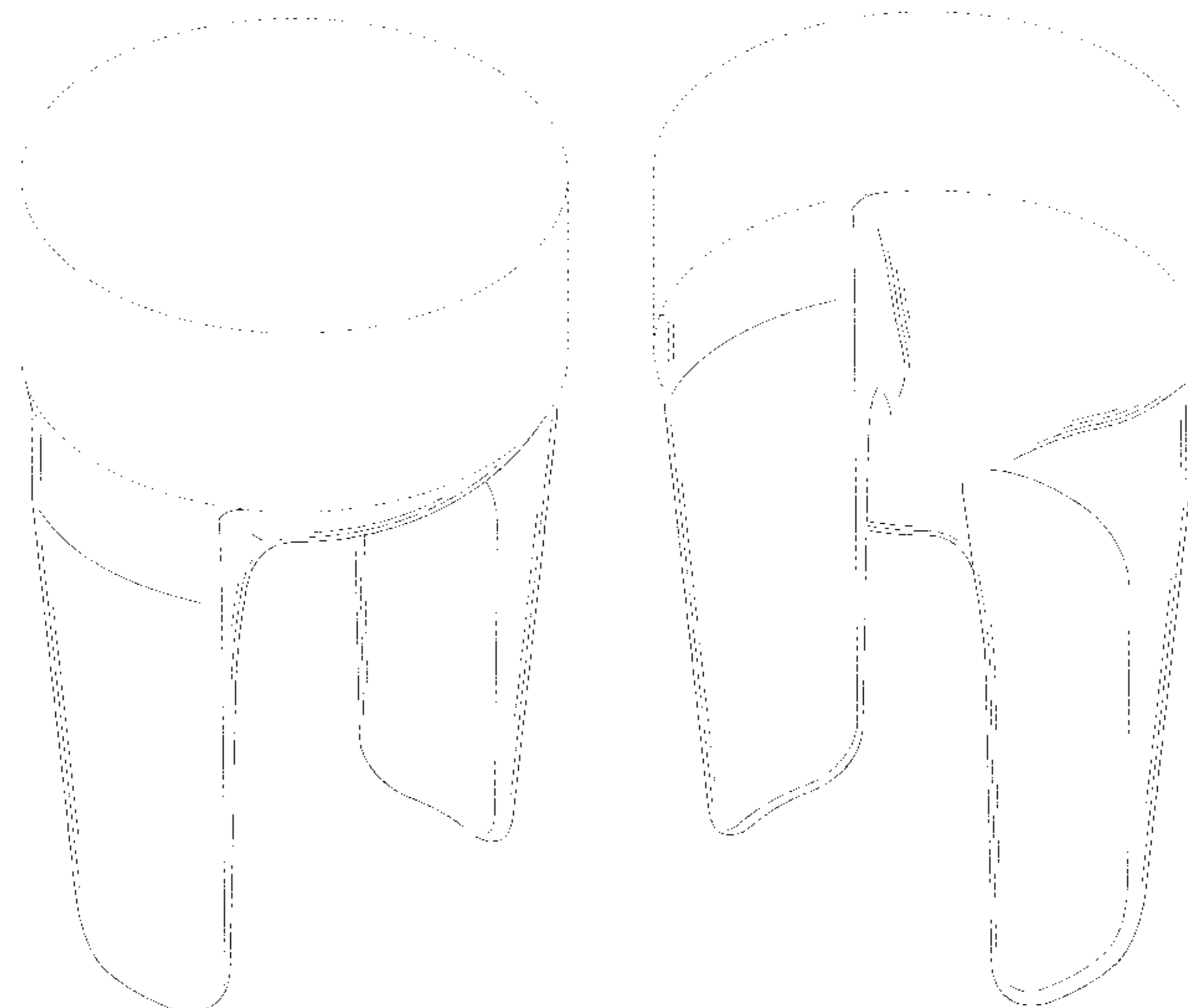
DESCRIPTION

FIG. 1 is a perspective view of a gripper for industrial robot illustrating our new design;
FIG. 2 is a bottom perspective view thereof;
FIG. 3 is a front view thereof;
FIG. 4 is a rear view thereof;
FIG. 5 is a right view thereof;
FIG. 6 is a left view thereof;
FIG. 7 is a top view thereof; and,
FIG. 8 is a bottom view thereof.

The gripper for industrial robot comprises a finger portion to grip an object.

The broken lines in the drawings depict portions of the gripper for industrial robot which form no part of the claimed design.

1 Claim, 8 Drawing Sheets



(56)

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Fig.1

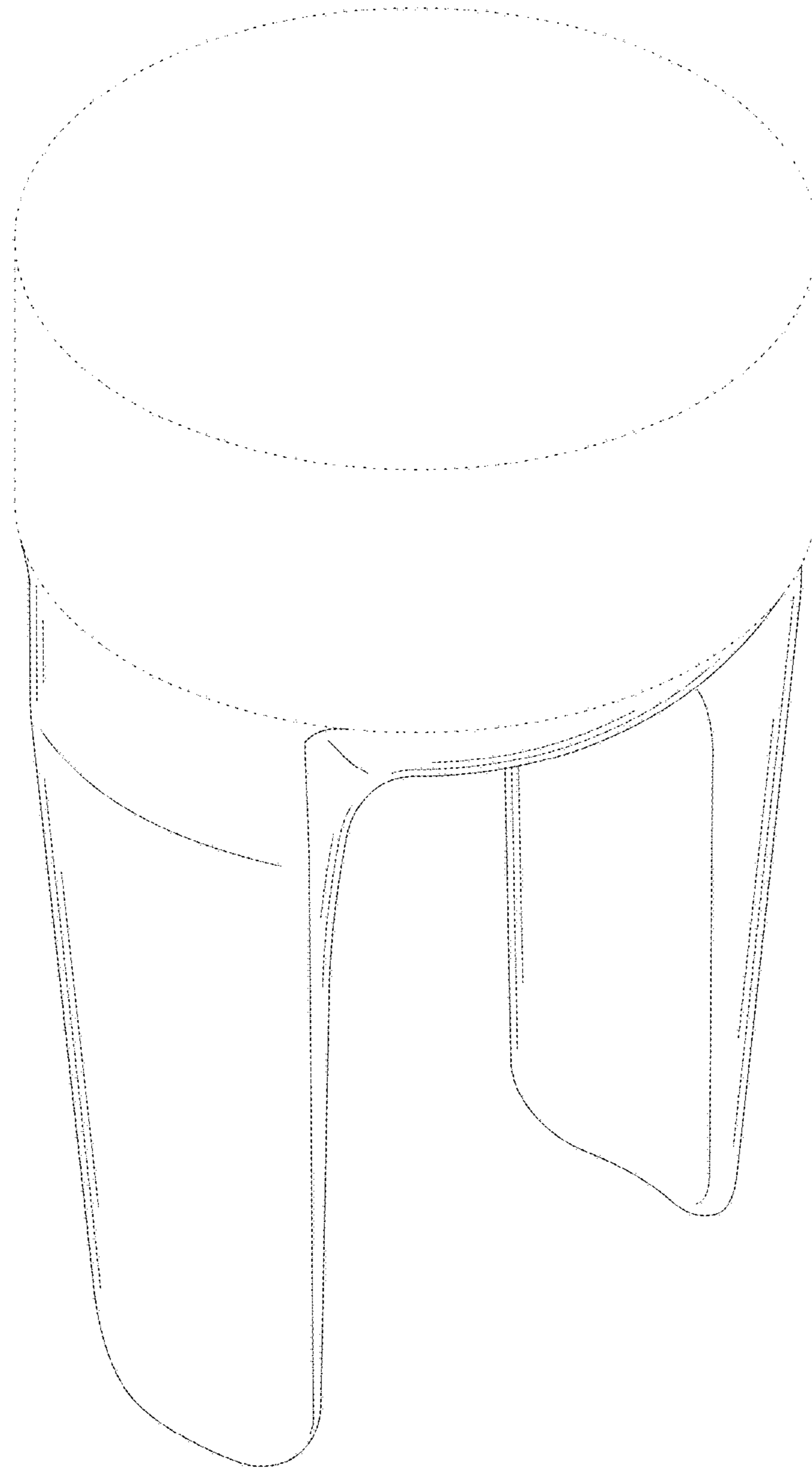


Fig. 2

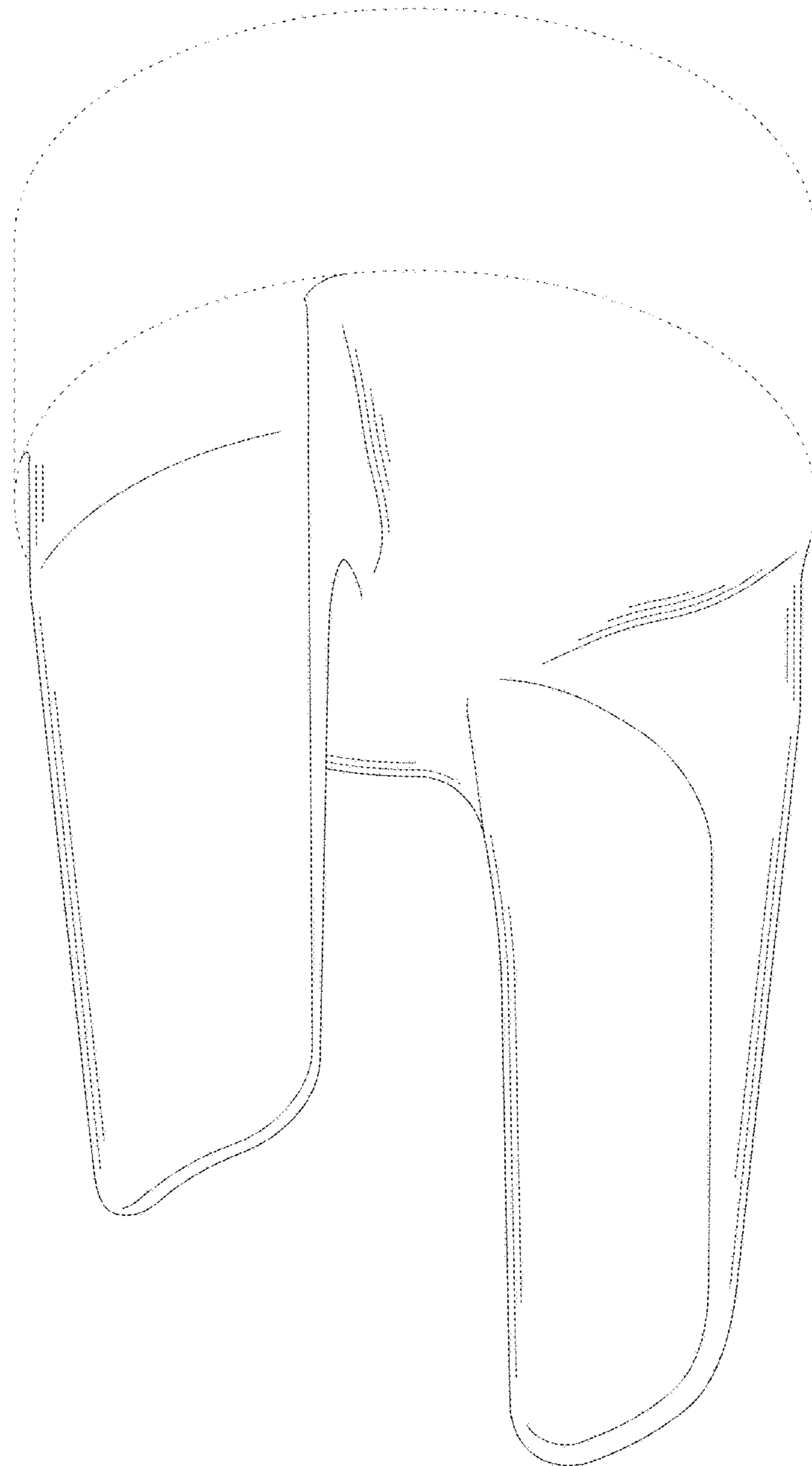


Fig. 3

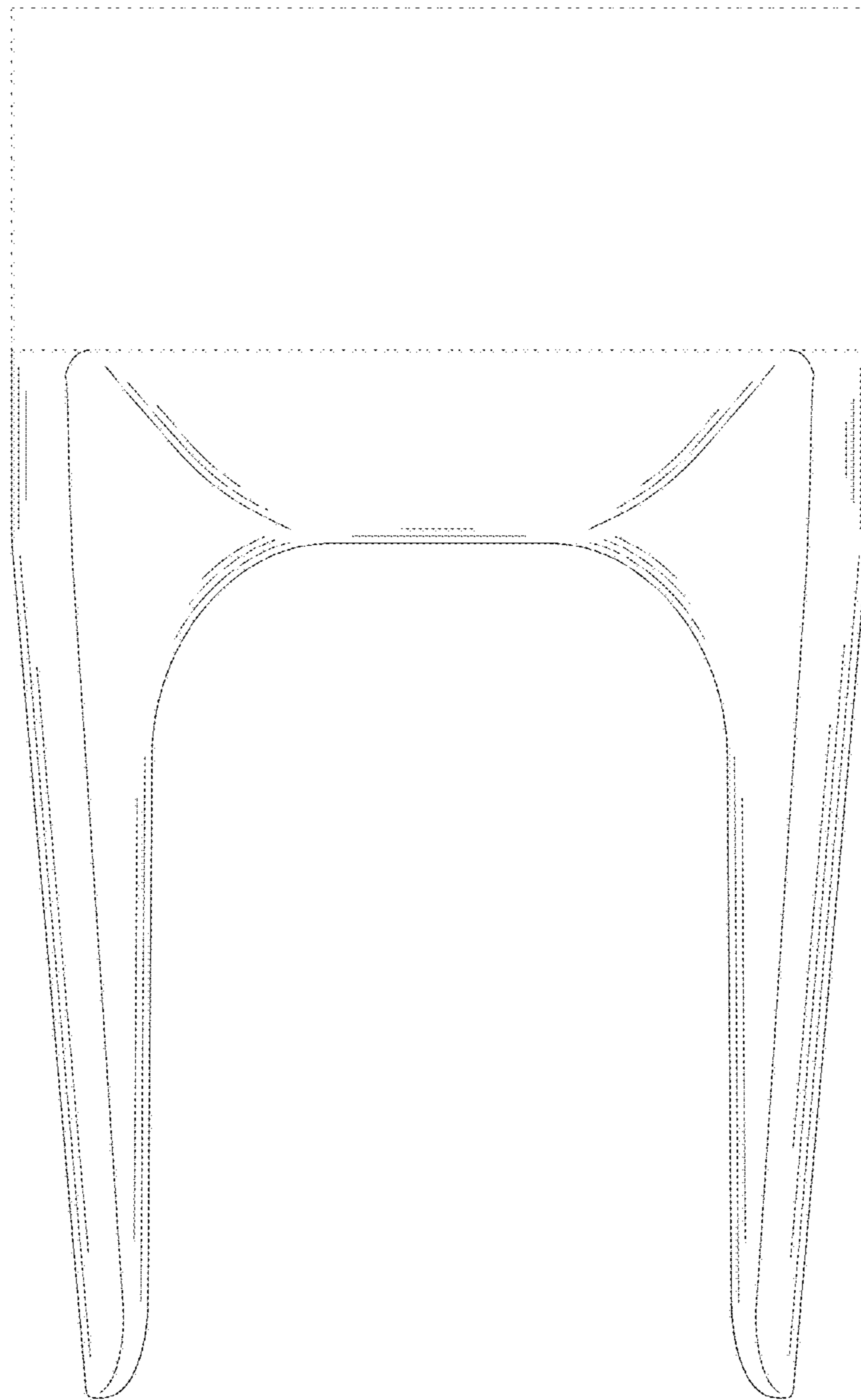


Fig. 4

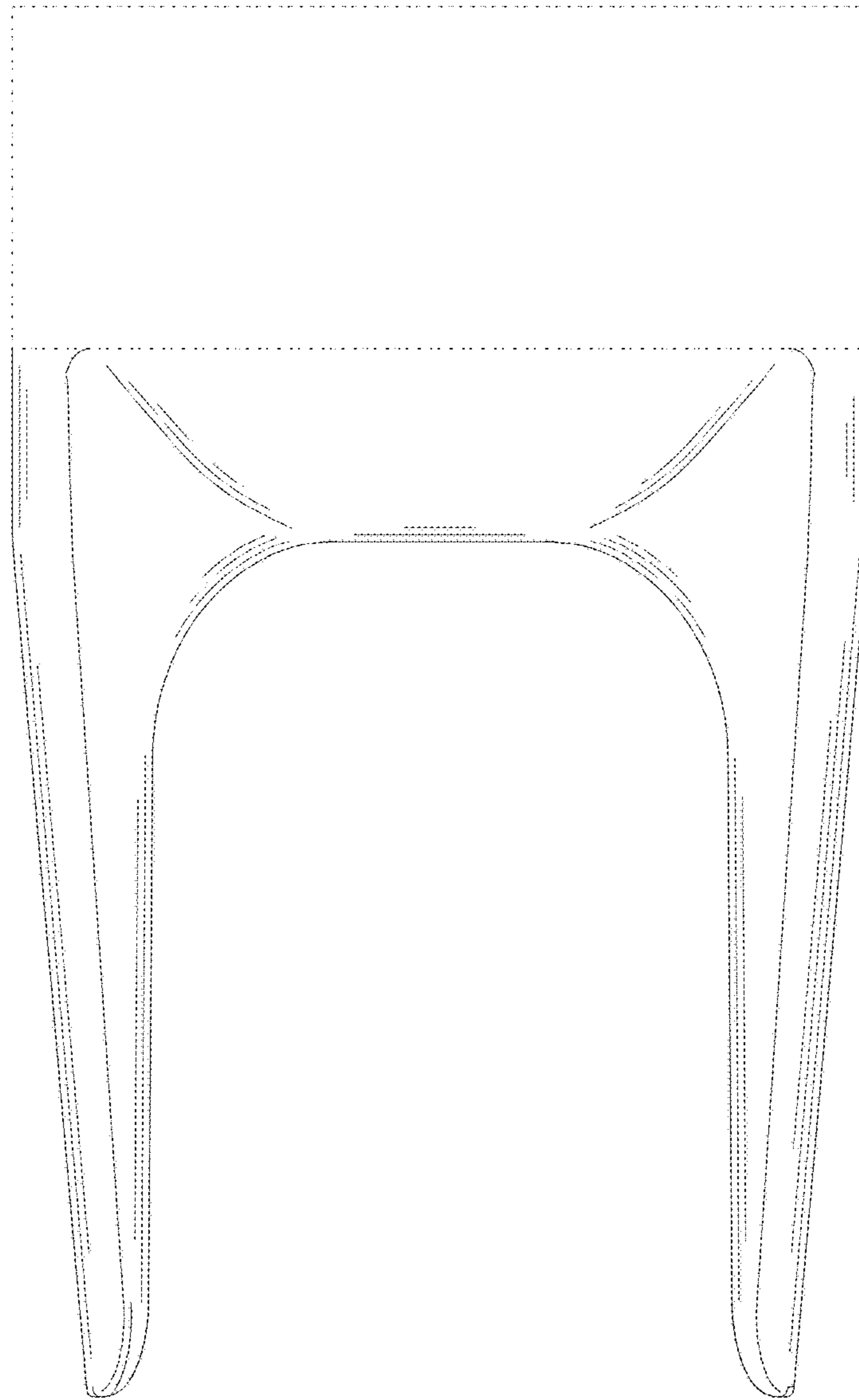


Fig. 5

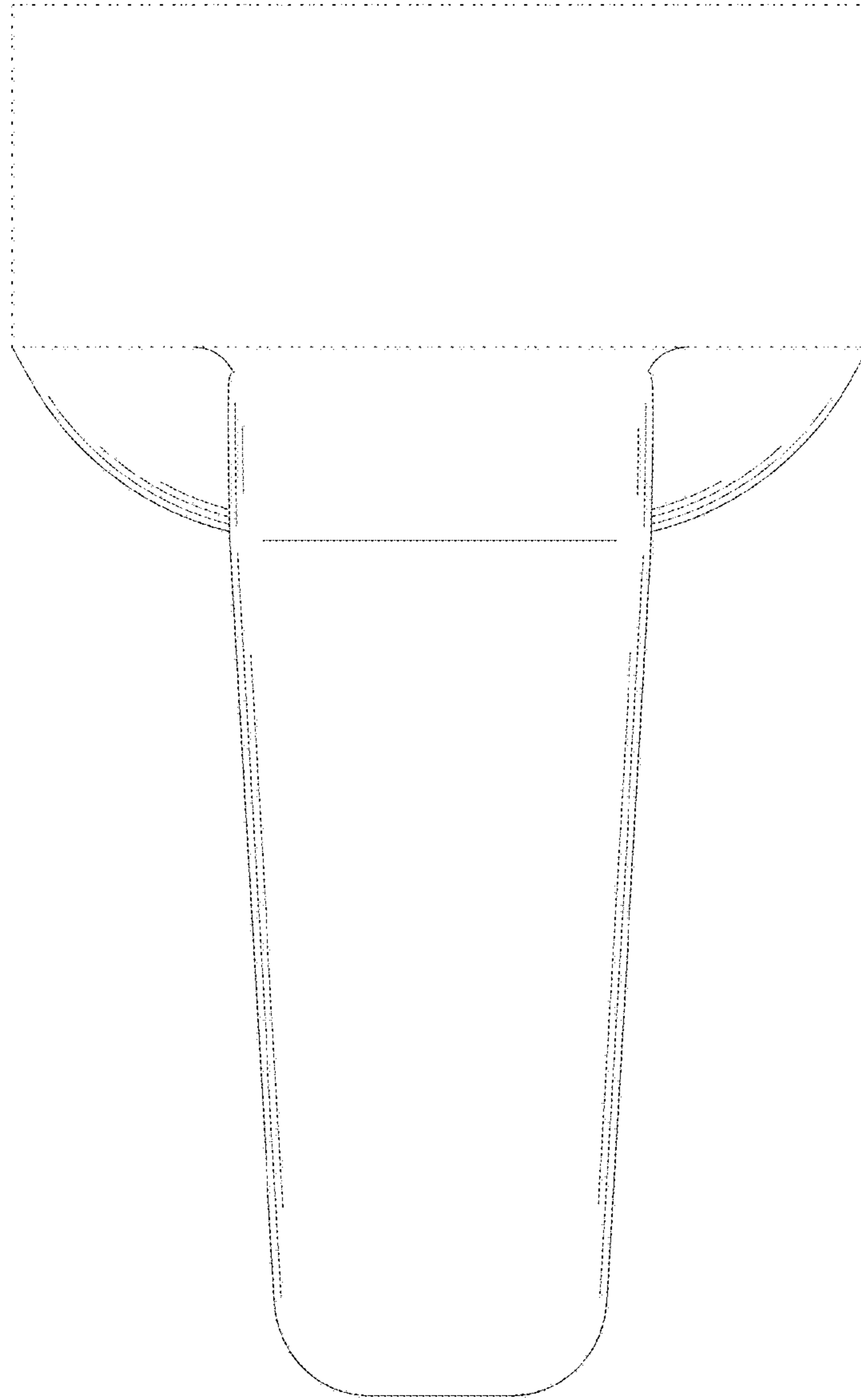


Fig.6

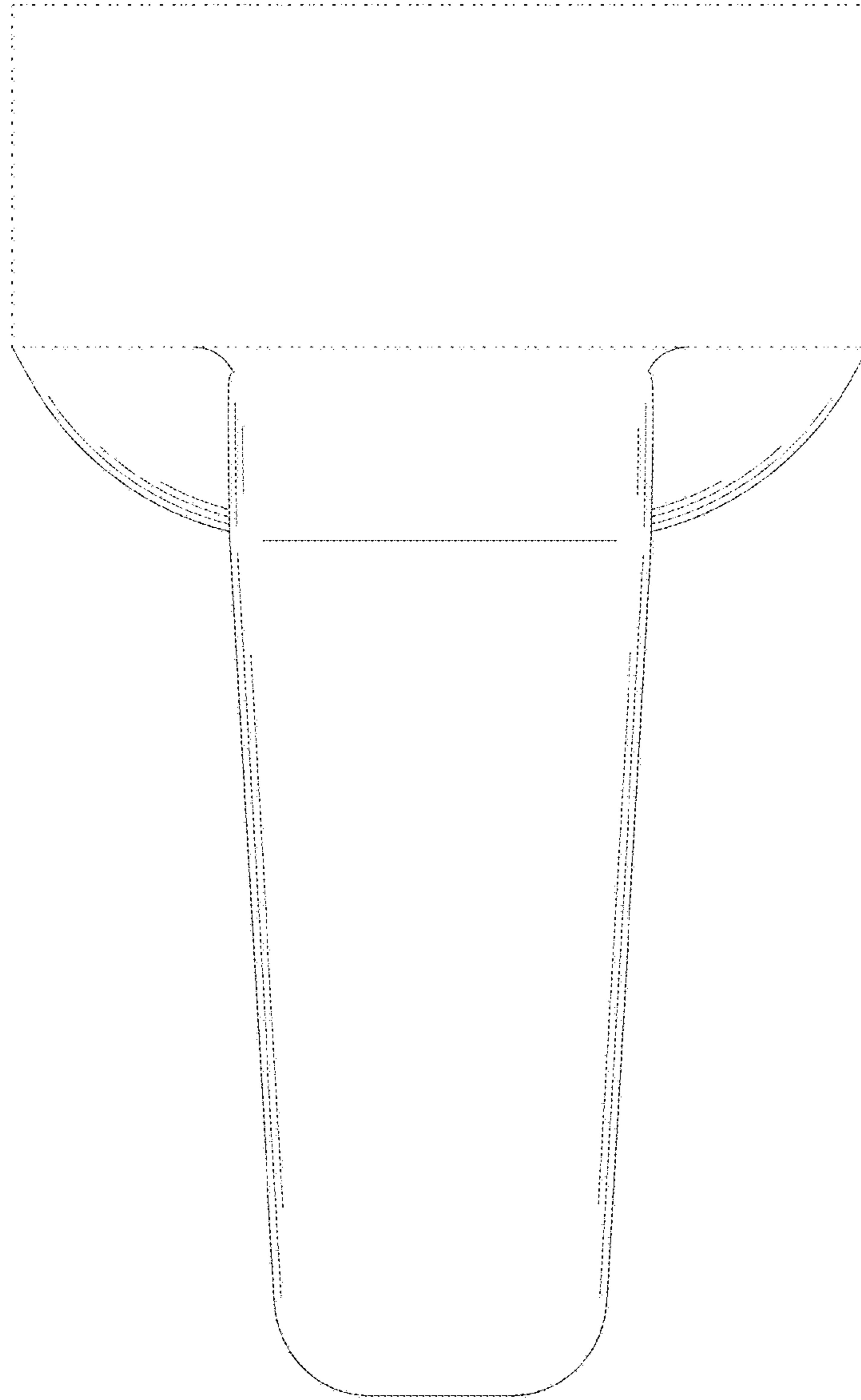


Fig. 7

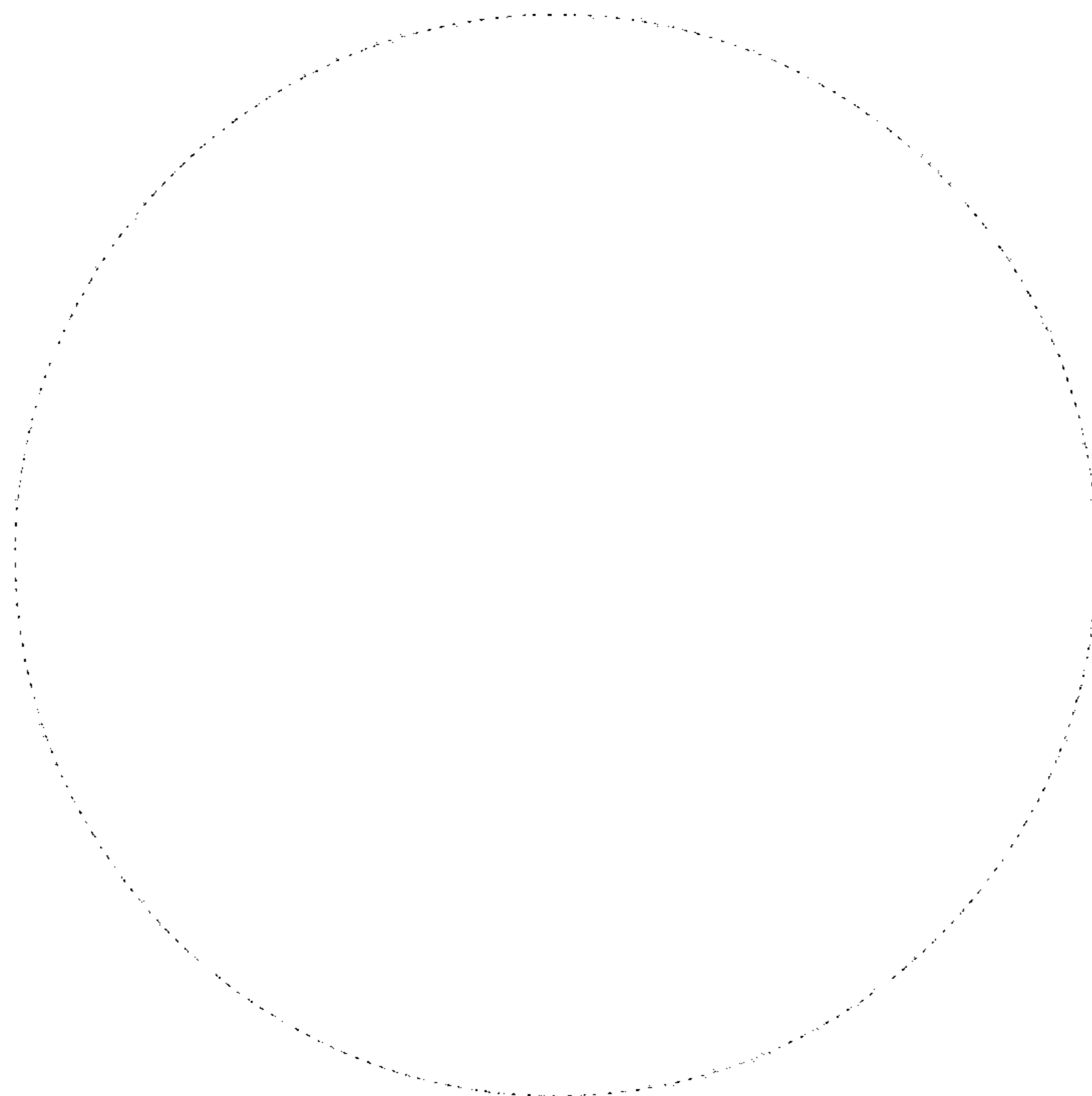


Fig. 8

