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(12) **United States Design Patent**  
**Kawaguchi et al.**

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- (54) **MANIPULATOR FOR ROBOT**
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- (52) **U.S. Cl.**  
USPC ..... **D15/199**
- (58) **Field of Classification Search**  
USPC ..... D15/199; D21/369, 578-583, 621, 622  
CPC ..... B25J 15/10; B25J 15/086; B25J 15/0009;  
Y10S 901/38; Y10S 901/39  
See application file for complete search history.

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(57) **CLAIM**

The ornamental design for a manipulator for robot, as shown and described.

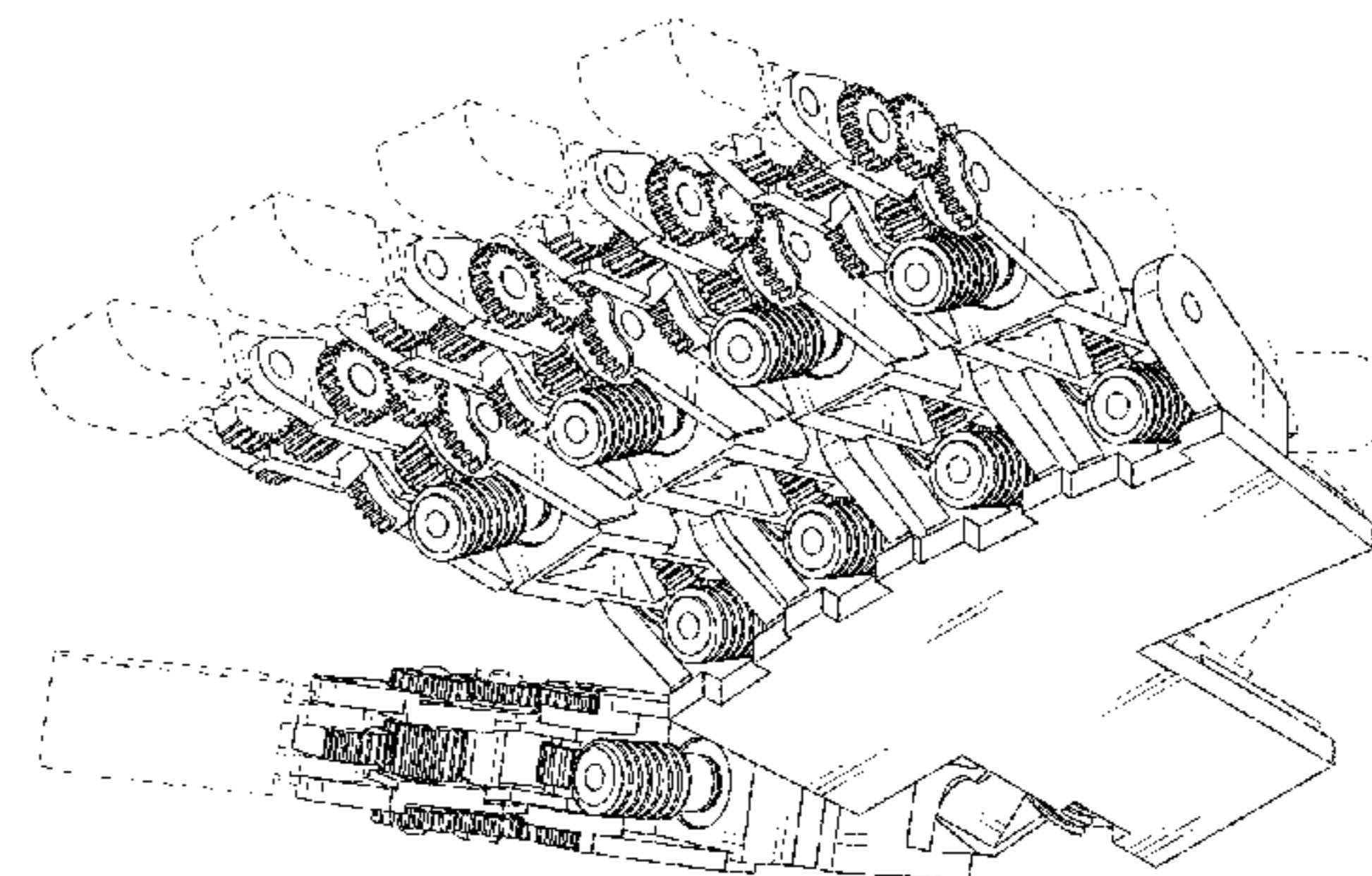
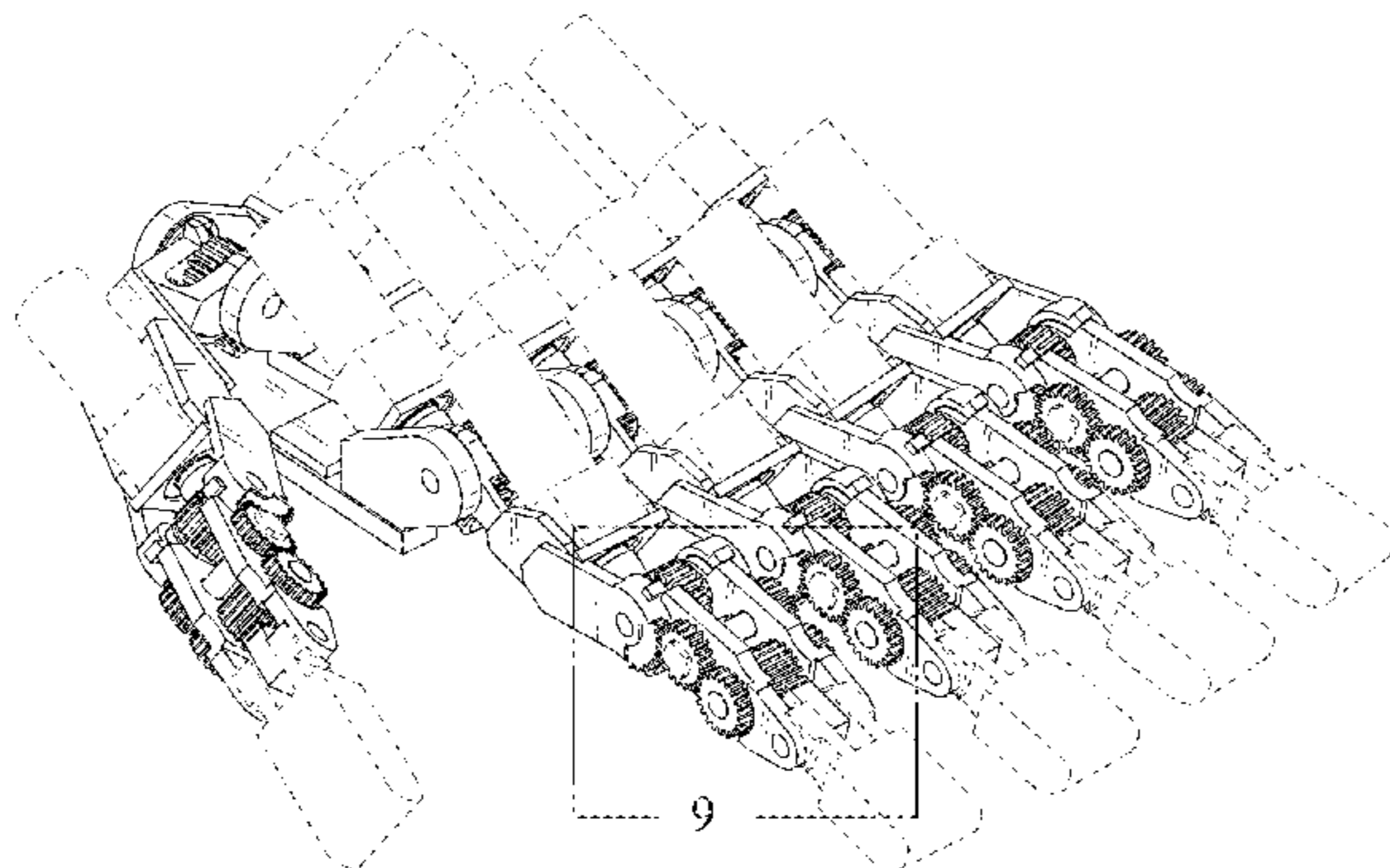
**DESCRIPTION**

FIG. 1 is a front perspective view of the front, right, and top sides of a manipulator for robot showing our new design; FIG. 2 is a rear perspective view of the rear, right, and bottom sides thereof; FIG. 3 is a front view thereof; FIG. 4 is a rear view thereof; FIG. 5 is a left side view thereof; FIG. 6 is a right side view thereof; FIG. 7 is a top plan view thereof; FIG. 8 is a bottom plan view thereof; FIG. 9 is an enlarged view of FIG. 1; and, FIG. 10 is a perspective view showing a state where a hinge angle is changed.

The broken lines shown represent unclaimed subject matter of the manipulator for robot or environments and form no part of the claimed design.

The dash-dot-dot lines represent the locations and borders of an enlarged view showing details and form no part of the claimed design.

**1 Claim, 8 Drawing Sheets**



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Fig. 1

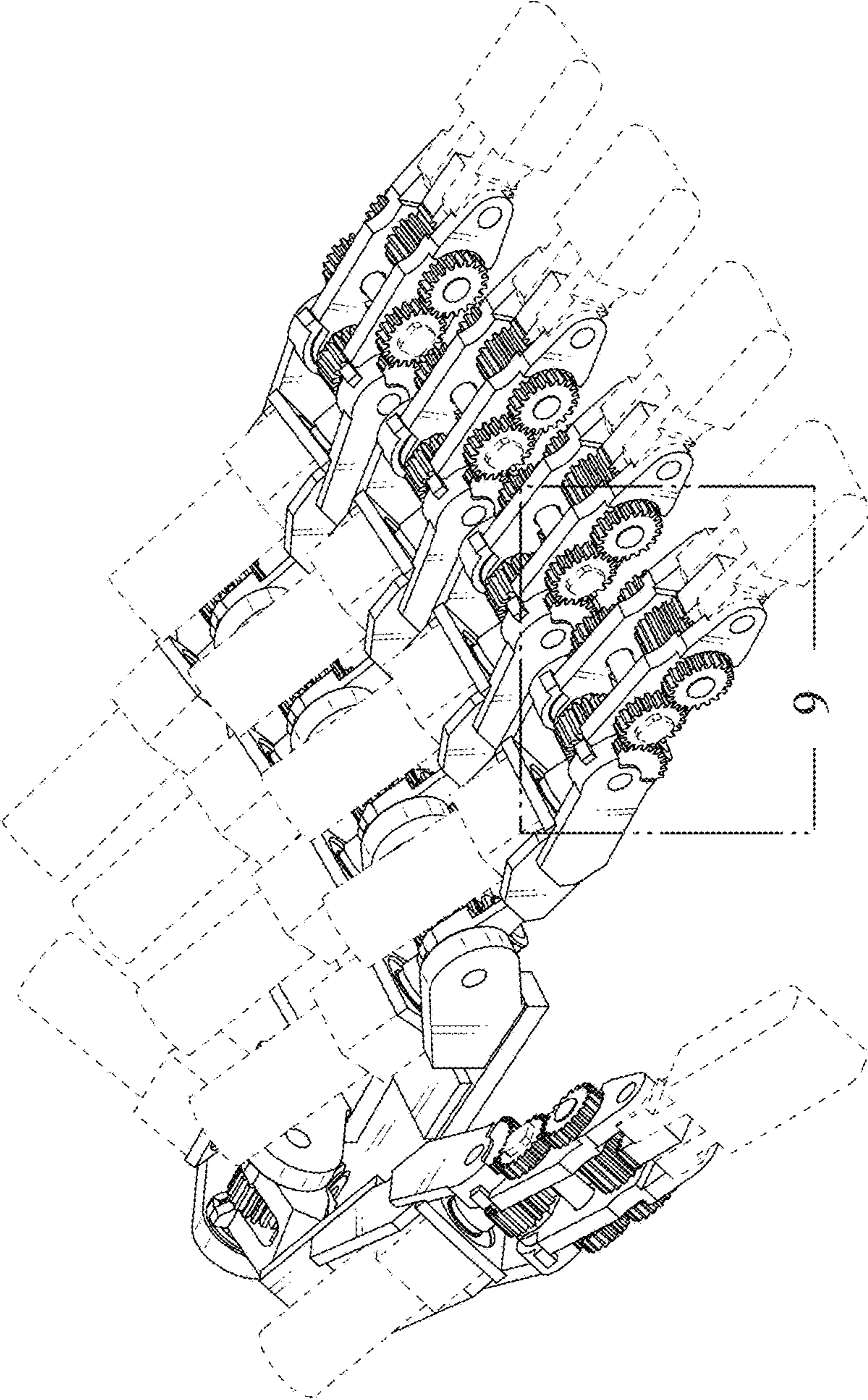


Fig. 2

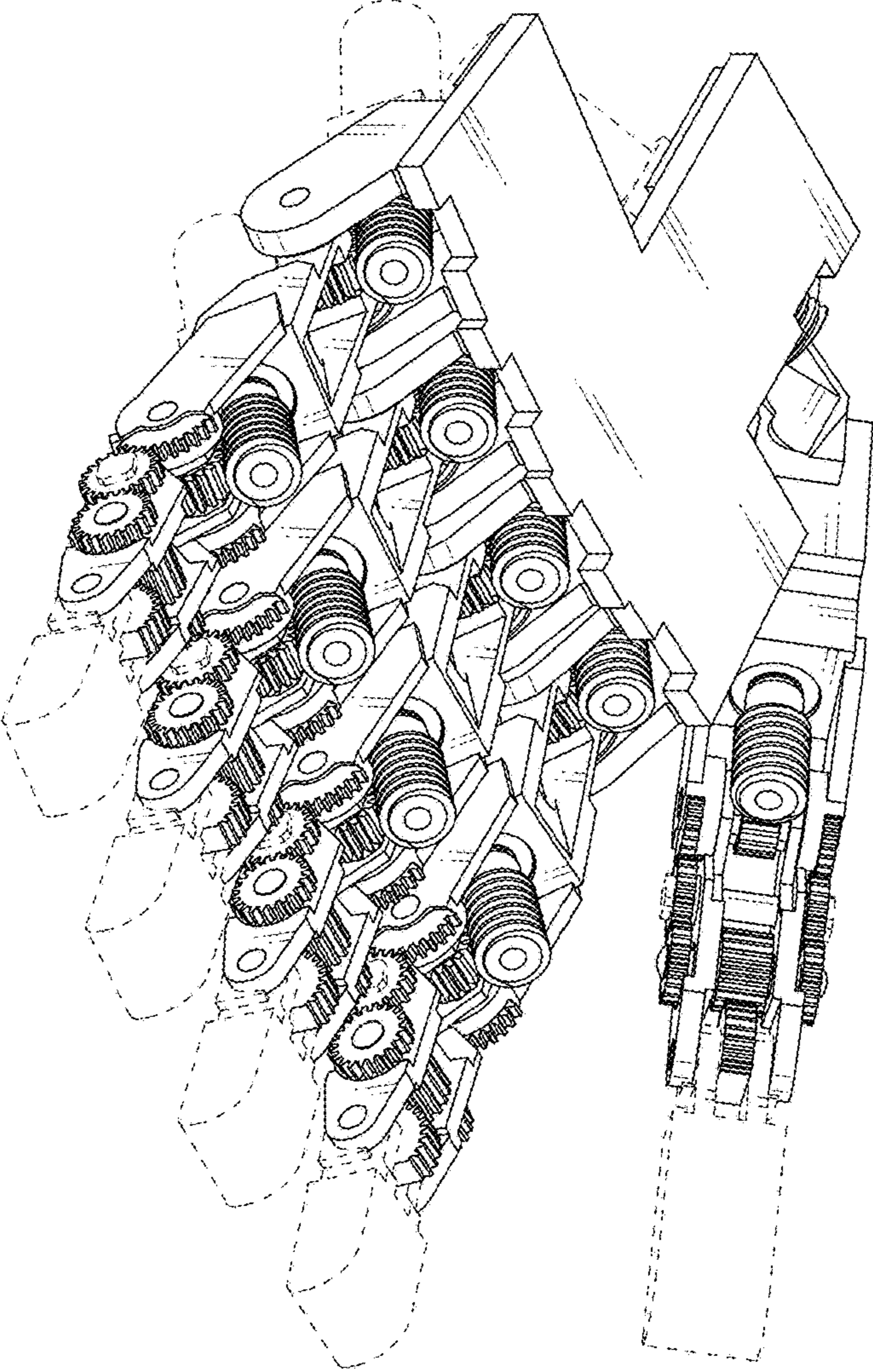


Fig. 3

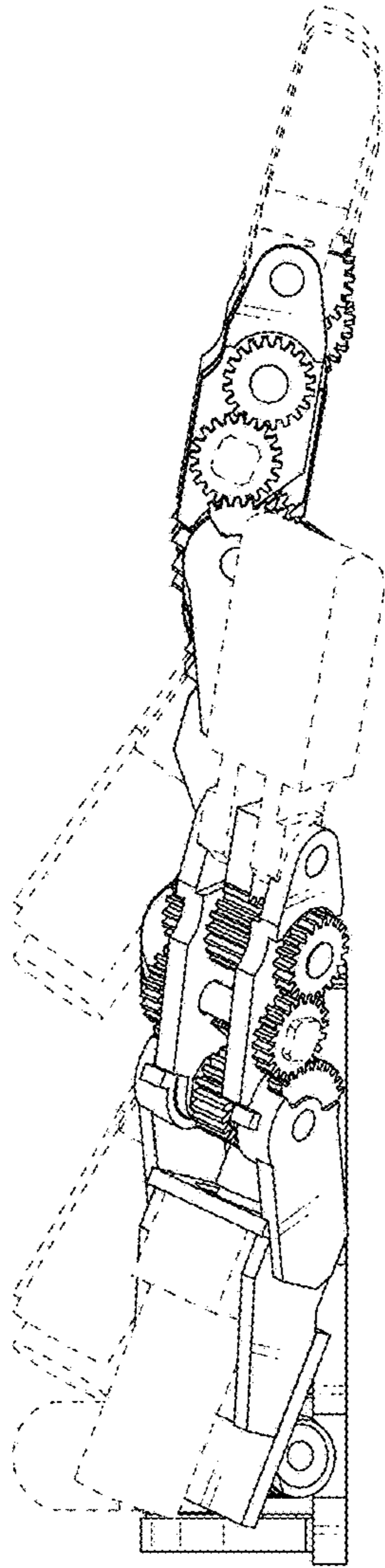


Fig. 4

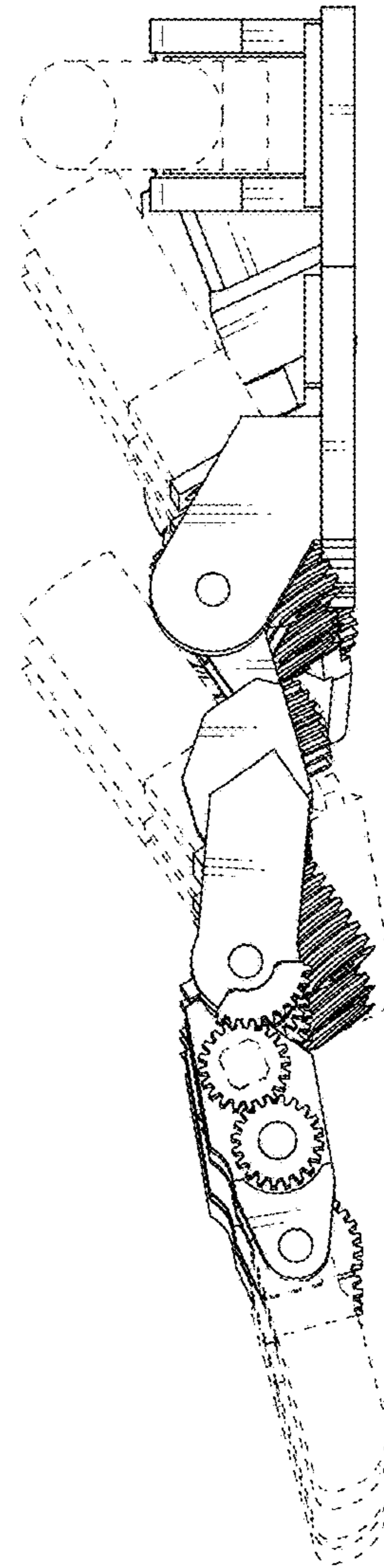


Fig. 5

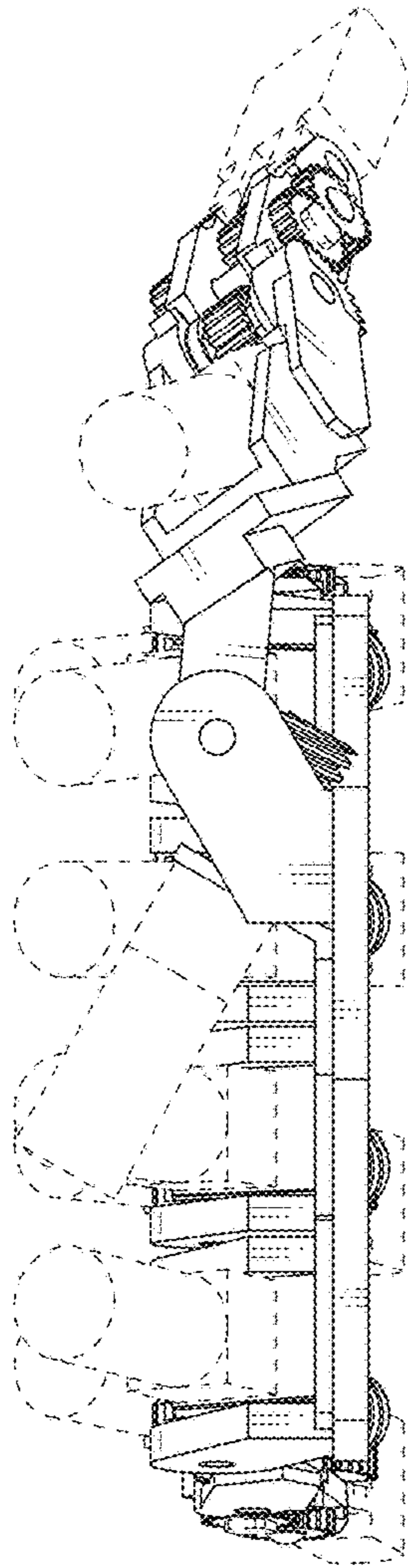


Fig. 6

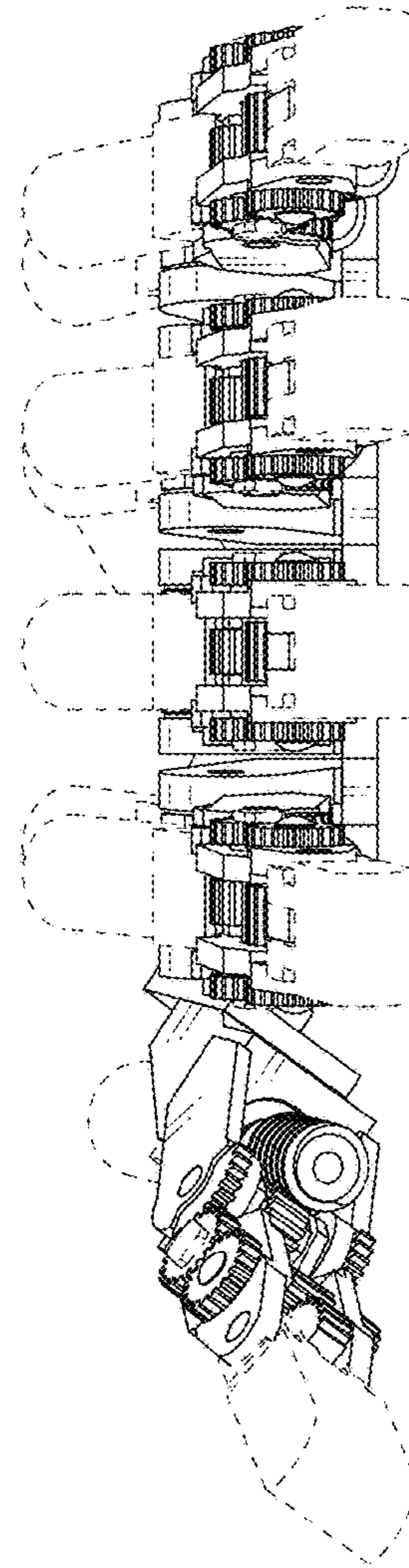


Fig. 7

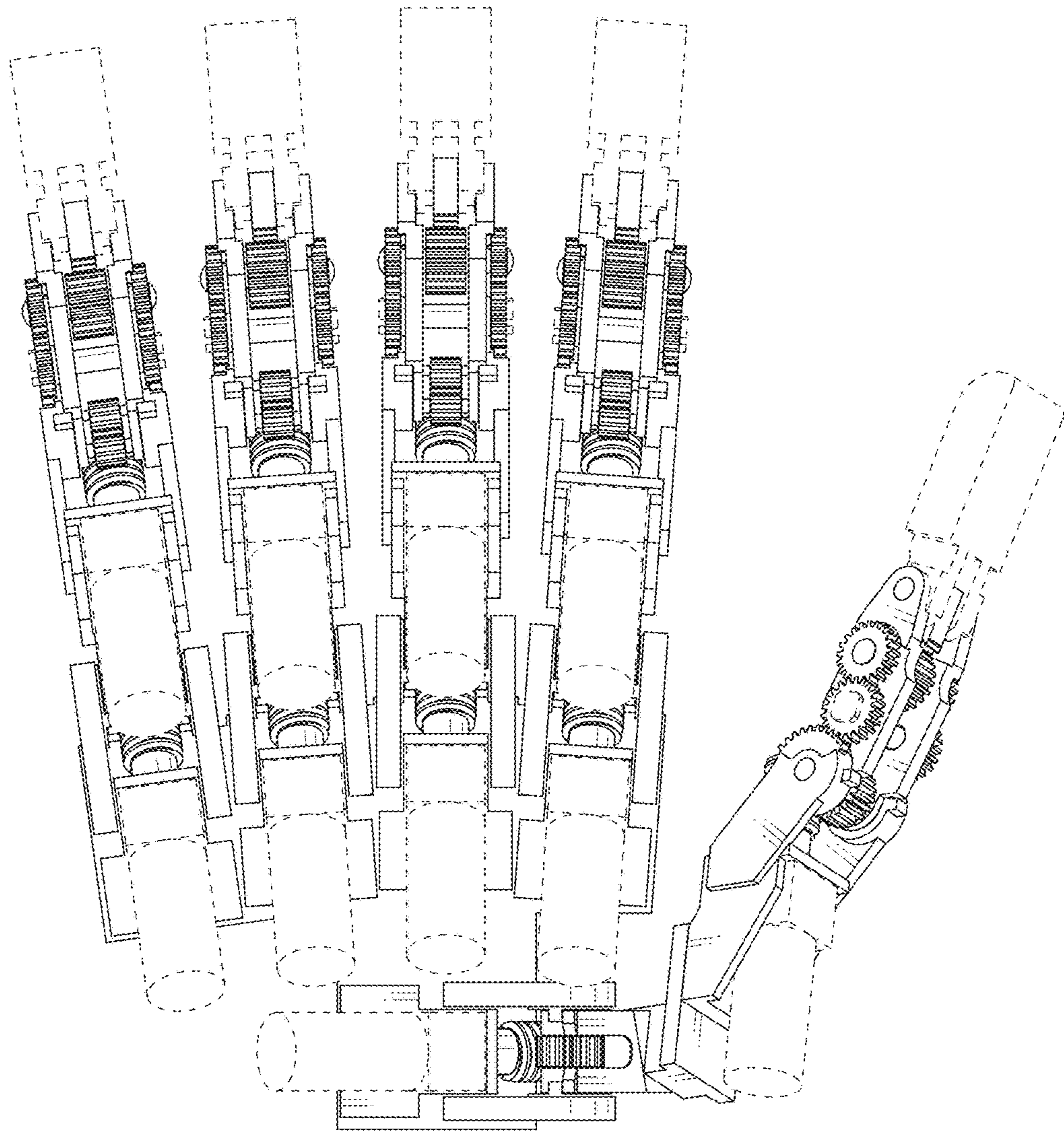


Fig. 8

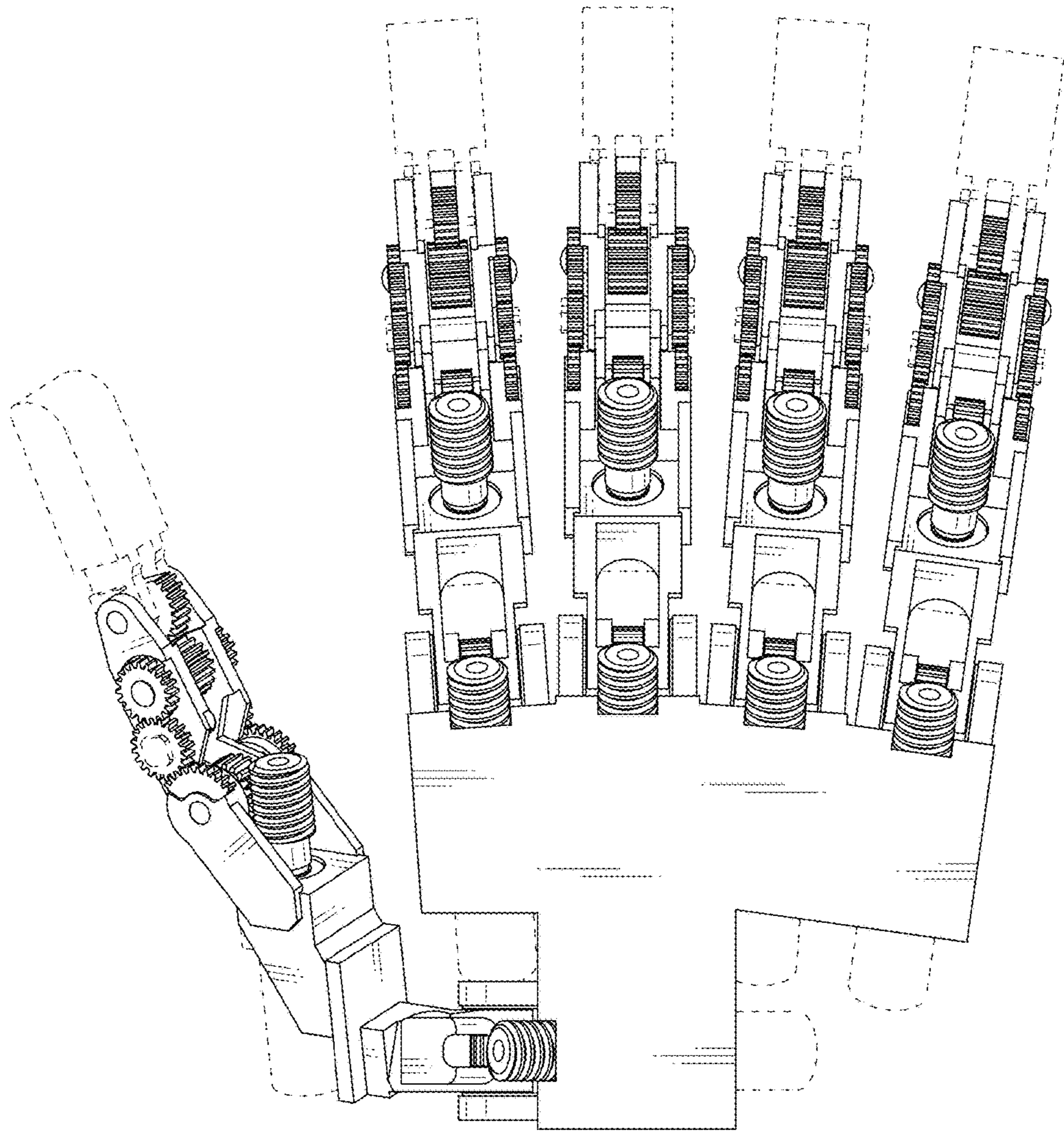




Fig. 9

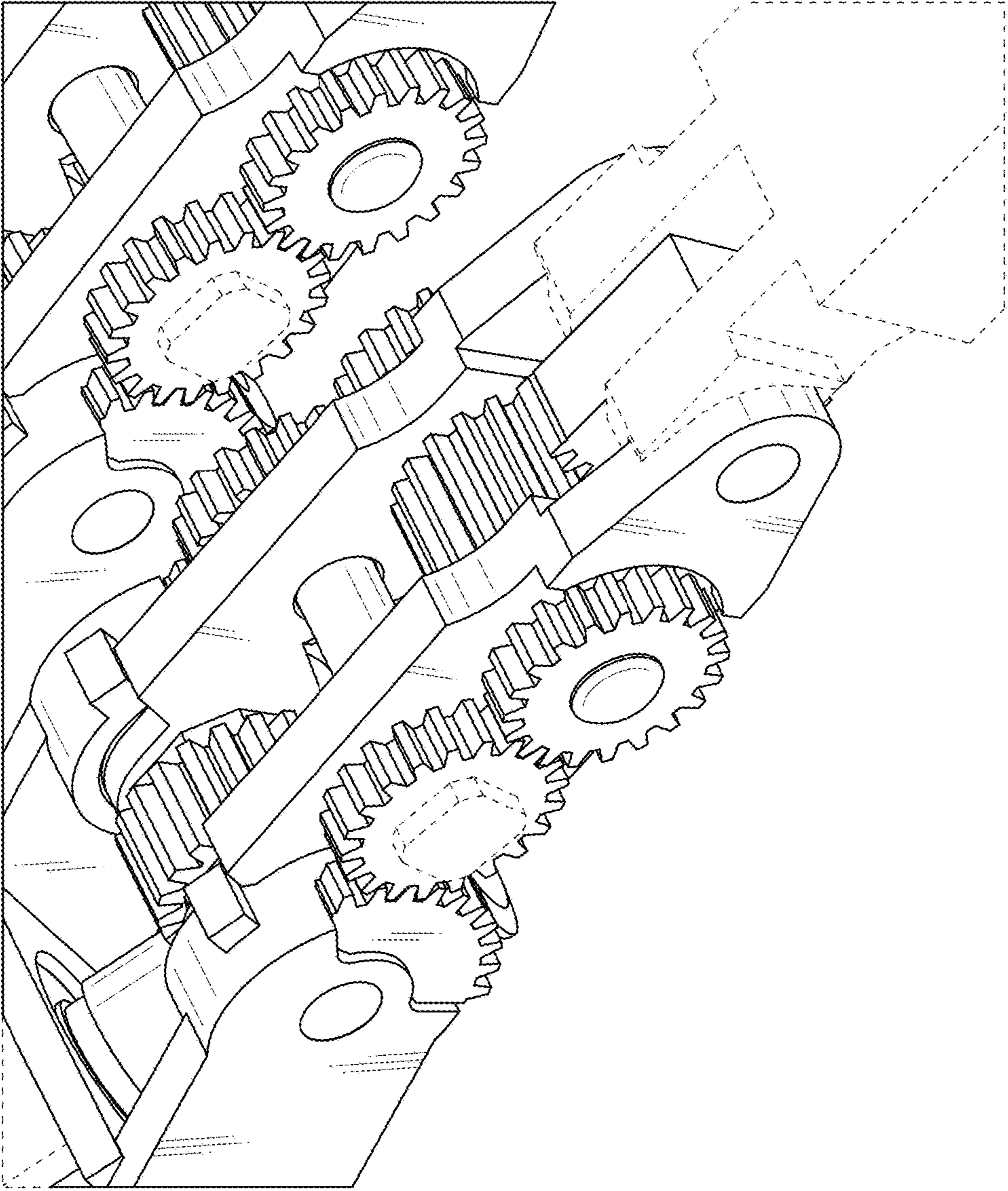


Fig. 10

