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**Kawaguchi et al.**

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(54) **JOINT DRIVING MEMBER FOR ROBOT**

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(30) **Foreign Application Priority Data**

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(52) **U.S. Cl.**  
USPC ..... **D15/199**

(58) **Field of Classification Search**  
USPC ..... D15/199; D21/369, 578-583, 621, 622  
CPC ..... B25J 9/102; B25J 9/104; B25J 17/0241;  
Y10T 74/20317; Y10T 74/20323  
See application file for complete search history.

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PC

(57) **CLAIM**

The ornamental design for a joint driving member for robot, as shown and described.

**DESCRIPTION**

FIG. 1 is a front perspective view of the front, right, and top sides of a joint driving member for robot showing our new design;

FIG. 2 is a rear perspective view of the rear, left, and bottom sides thereof;

FIG. 3 is a front view thereof;

FIG. 4 is a rear view thereof;

FIG. 5 is a left side view thereof;

FIG. 6 is a right side view thereof;

FIG. 7 is a top plan view thereof;

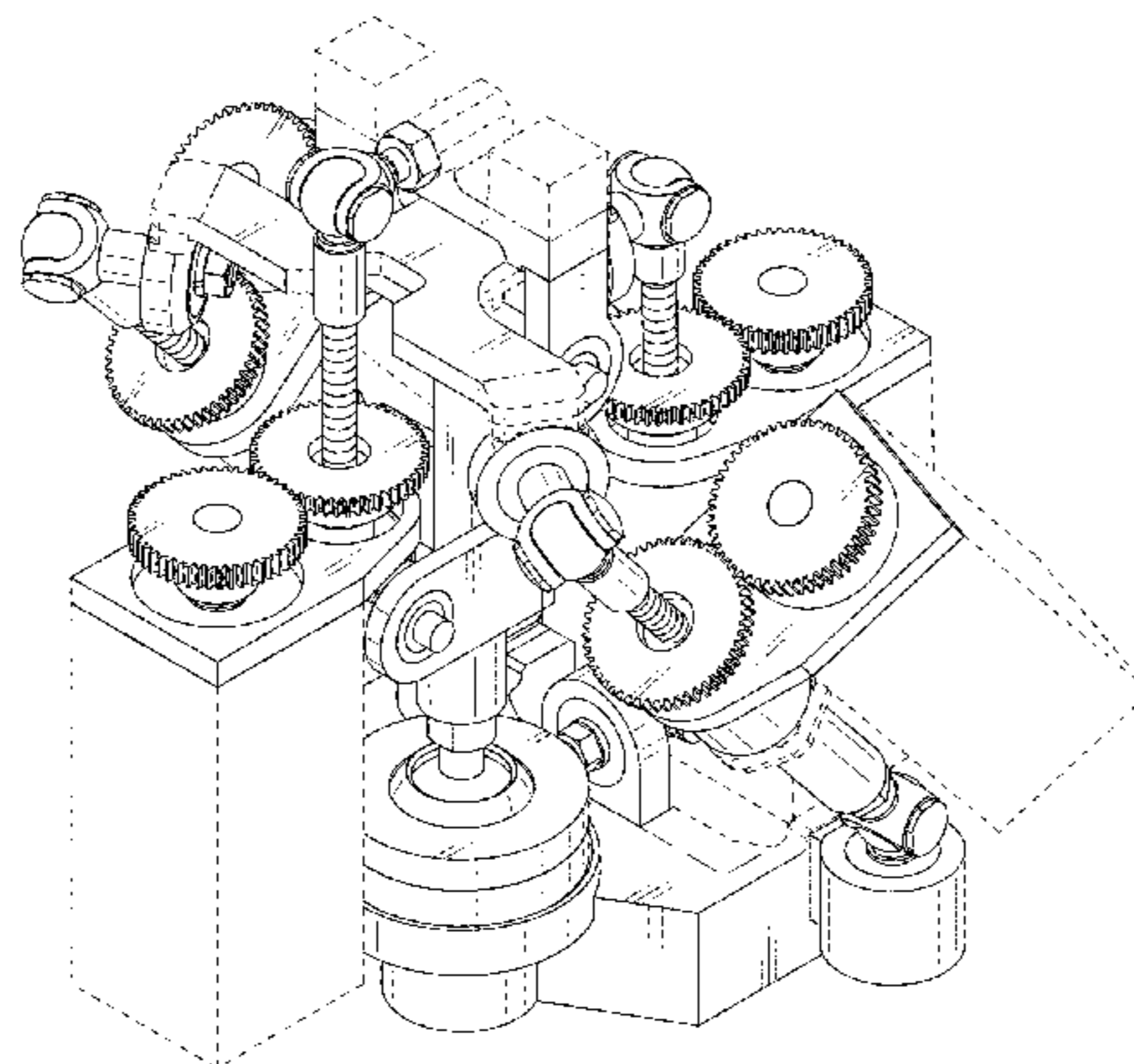
FIG. 8 is a bottom plan view thereof; and,

FIG. 9 is a right side view showing a state where a hinge angle is changed.

The broken lines shown represent unclaimed subject matter of the joint driving member for robot or environments and form no part of the claimed design.

The dash-dot lines represent the boundary between the claimed design and unclaimed design and form no part of the claimed design.

**1 Claim, 9 Drawing Sheets**



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Fig. 1

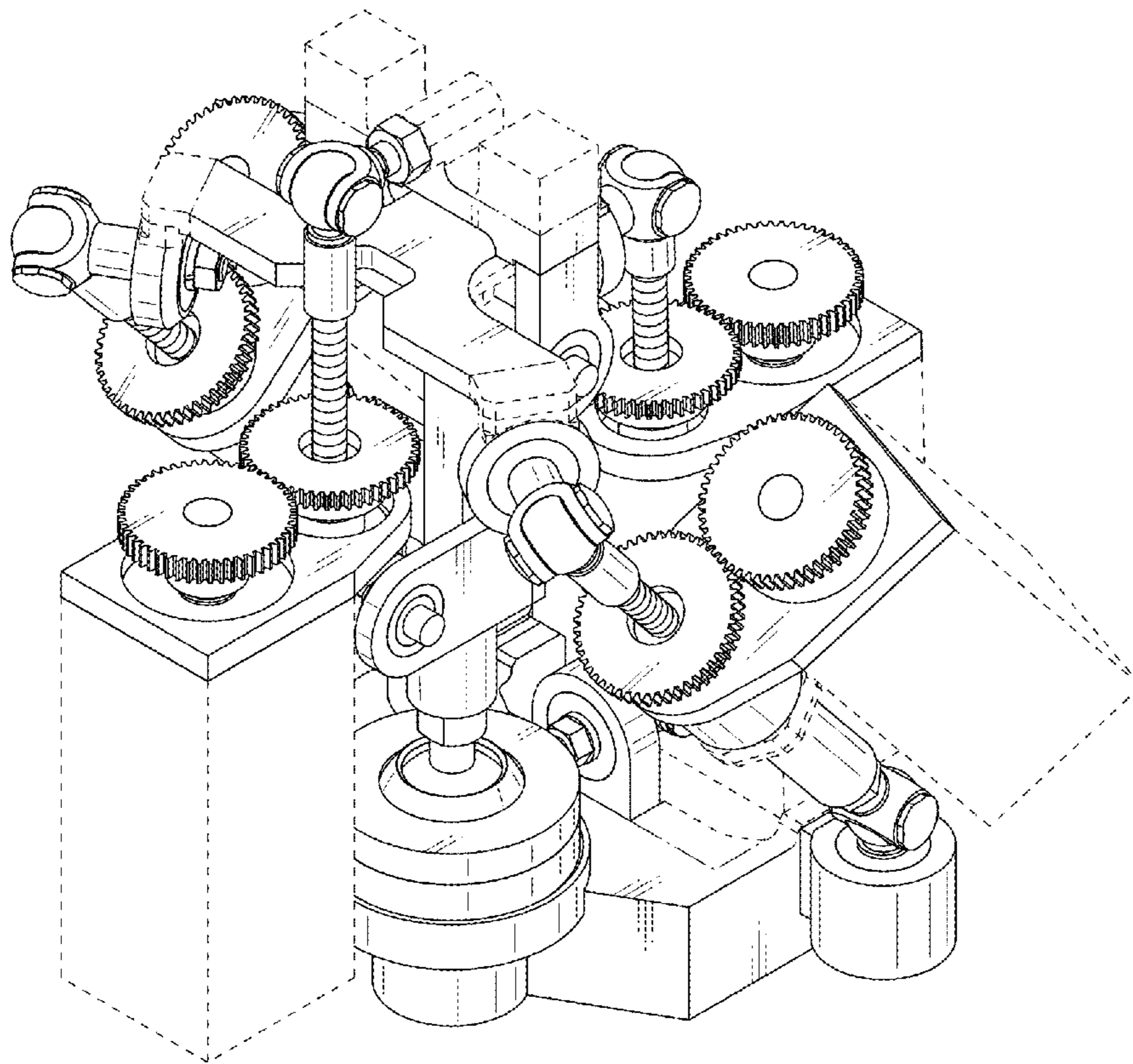




Fig. 2

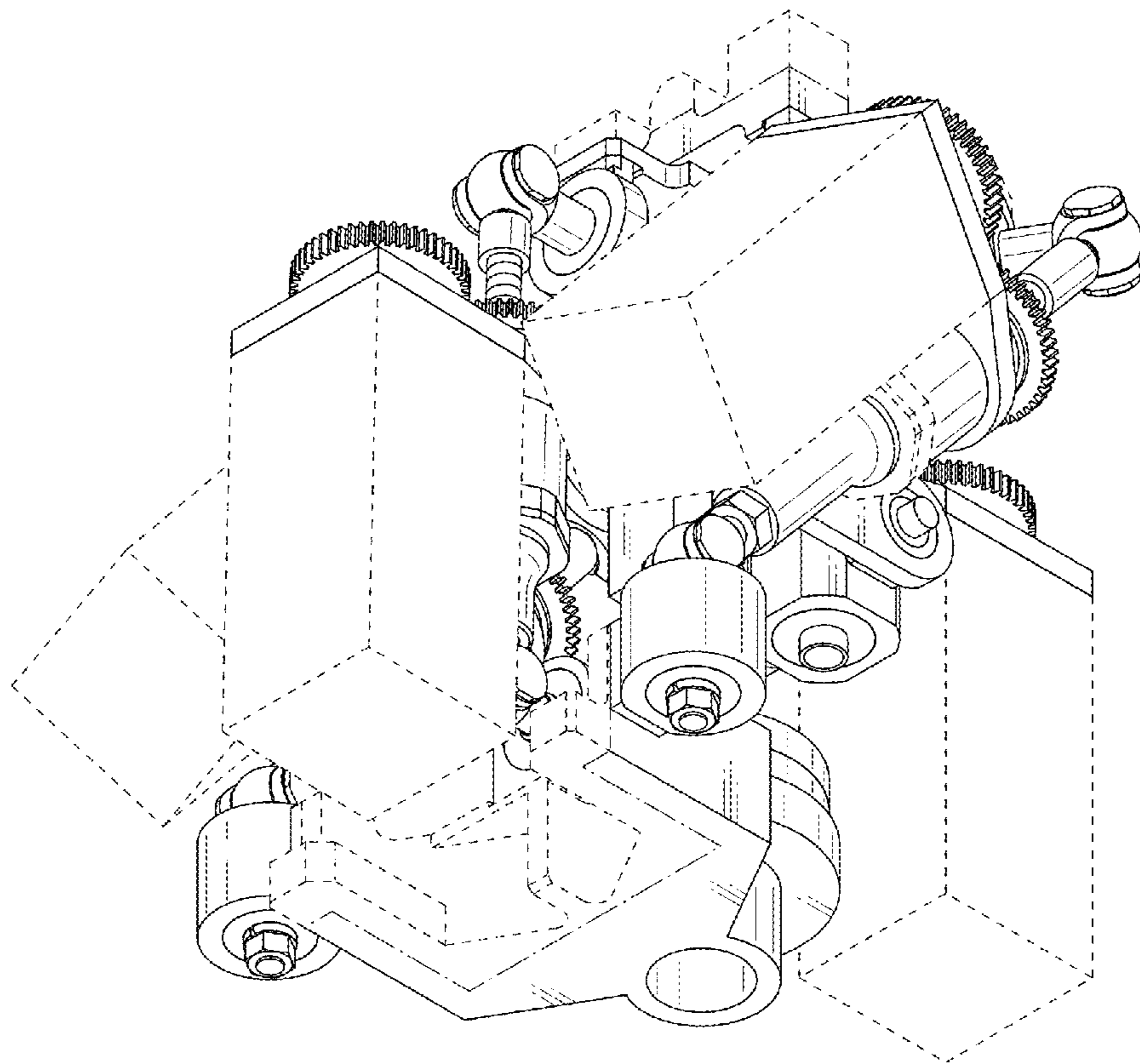


Fig. 3

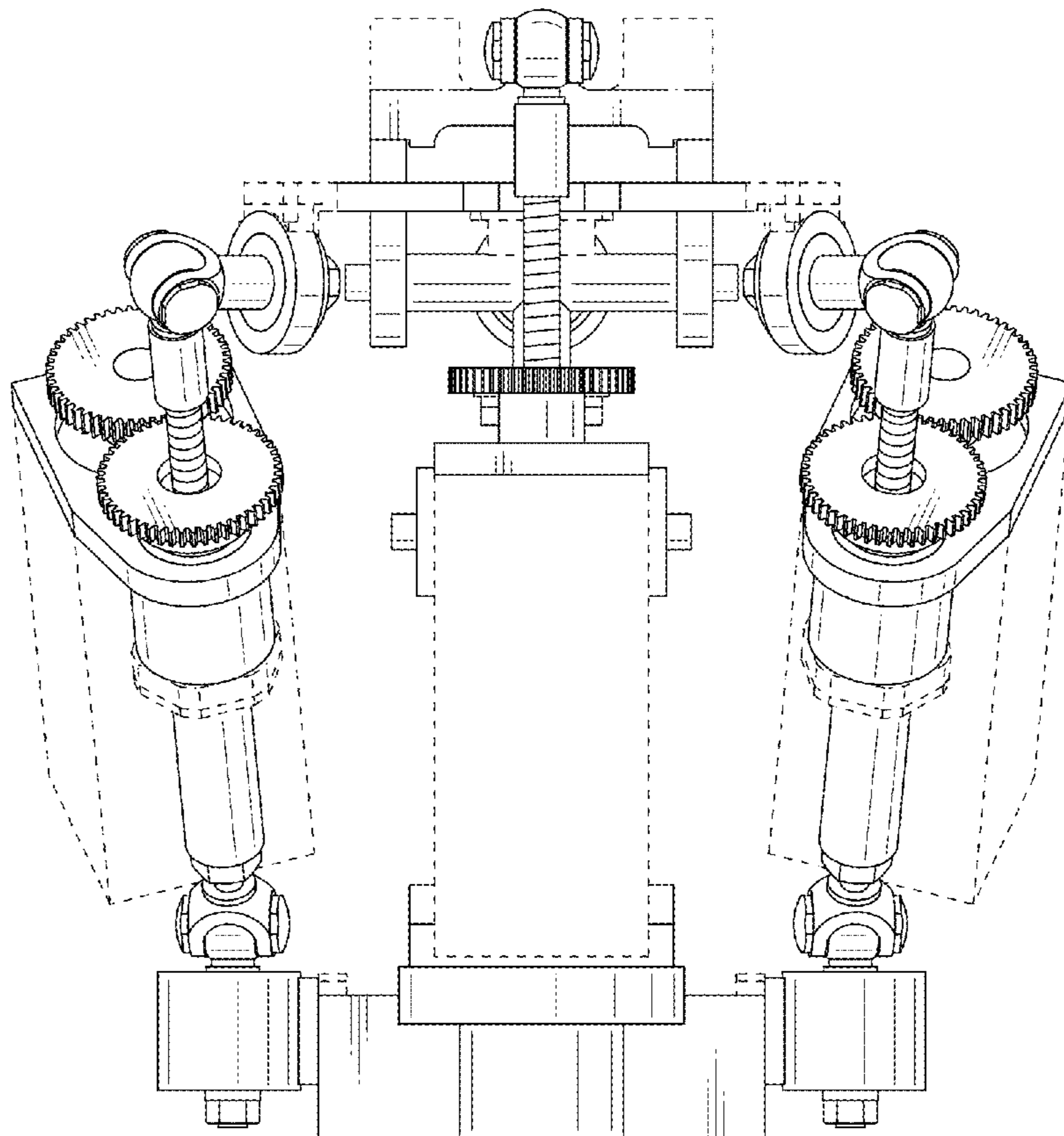


Fig. 4

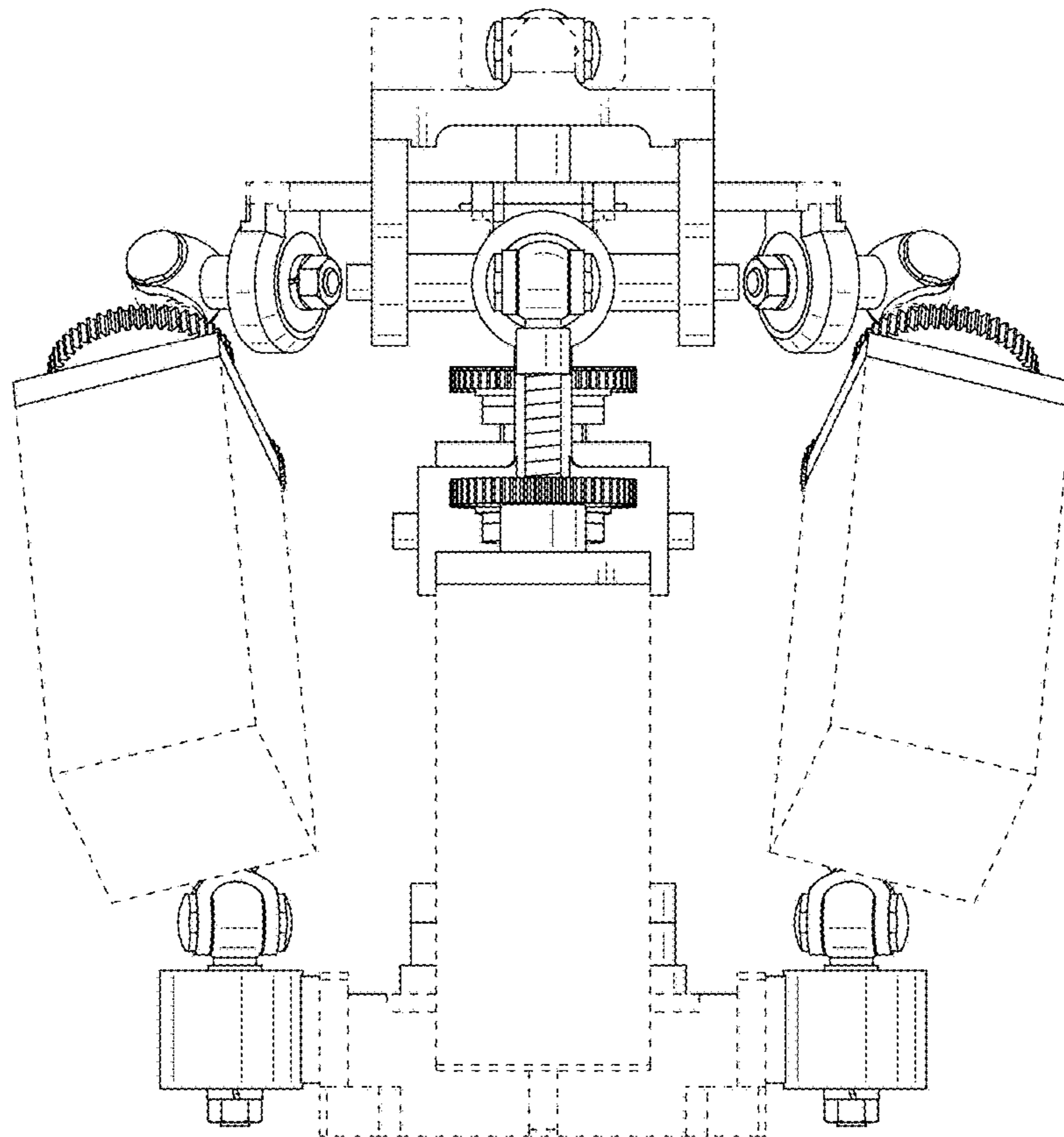


Fig. 5

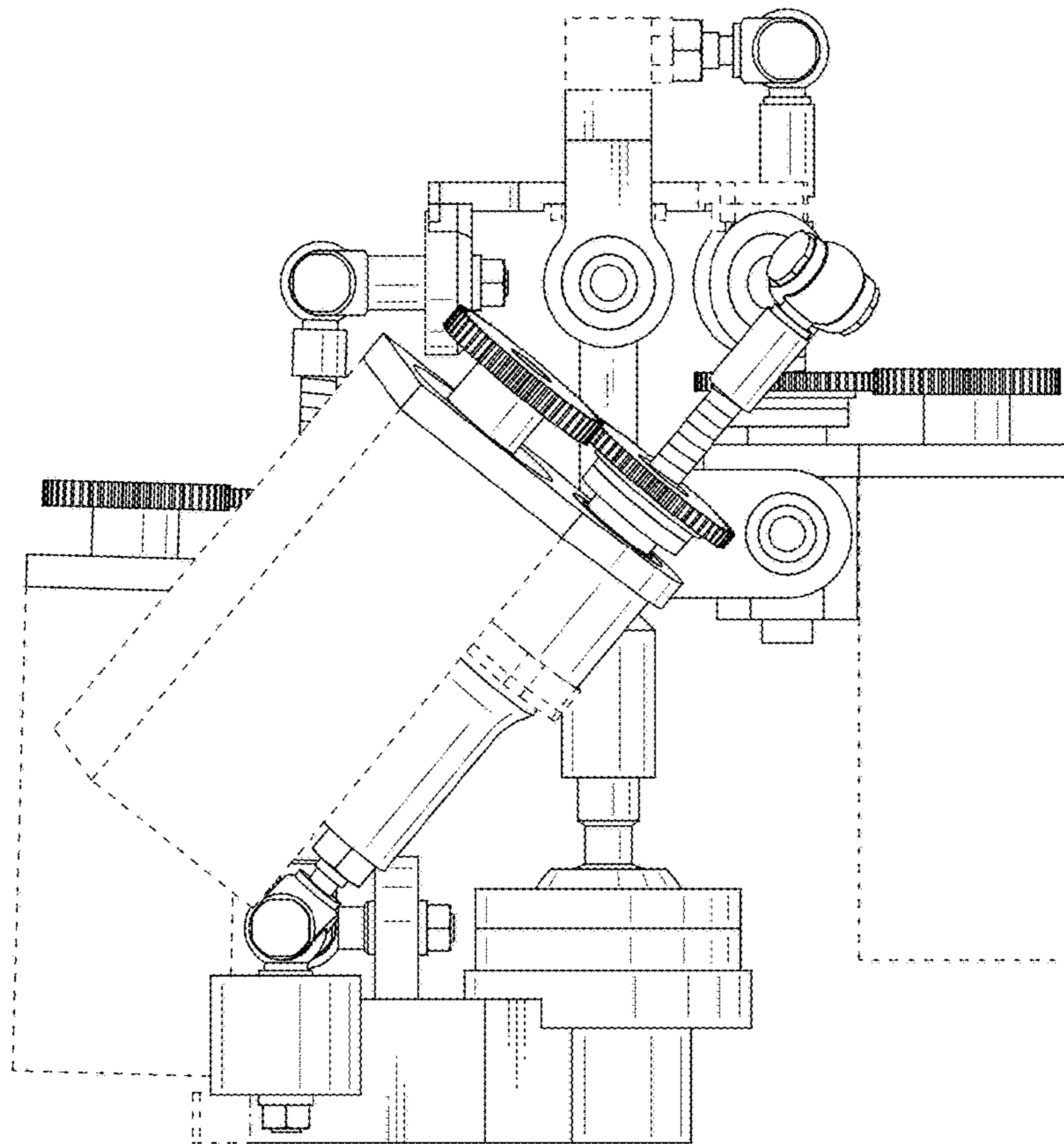


Fig. 6

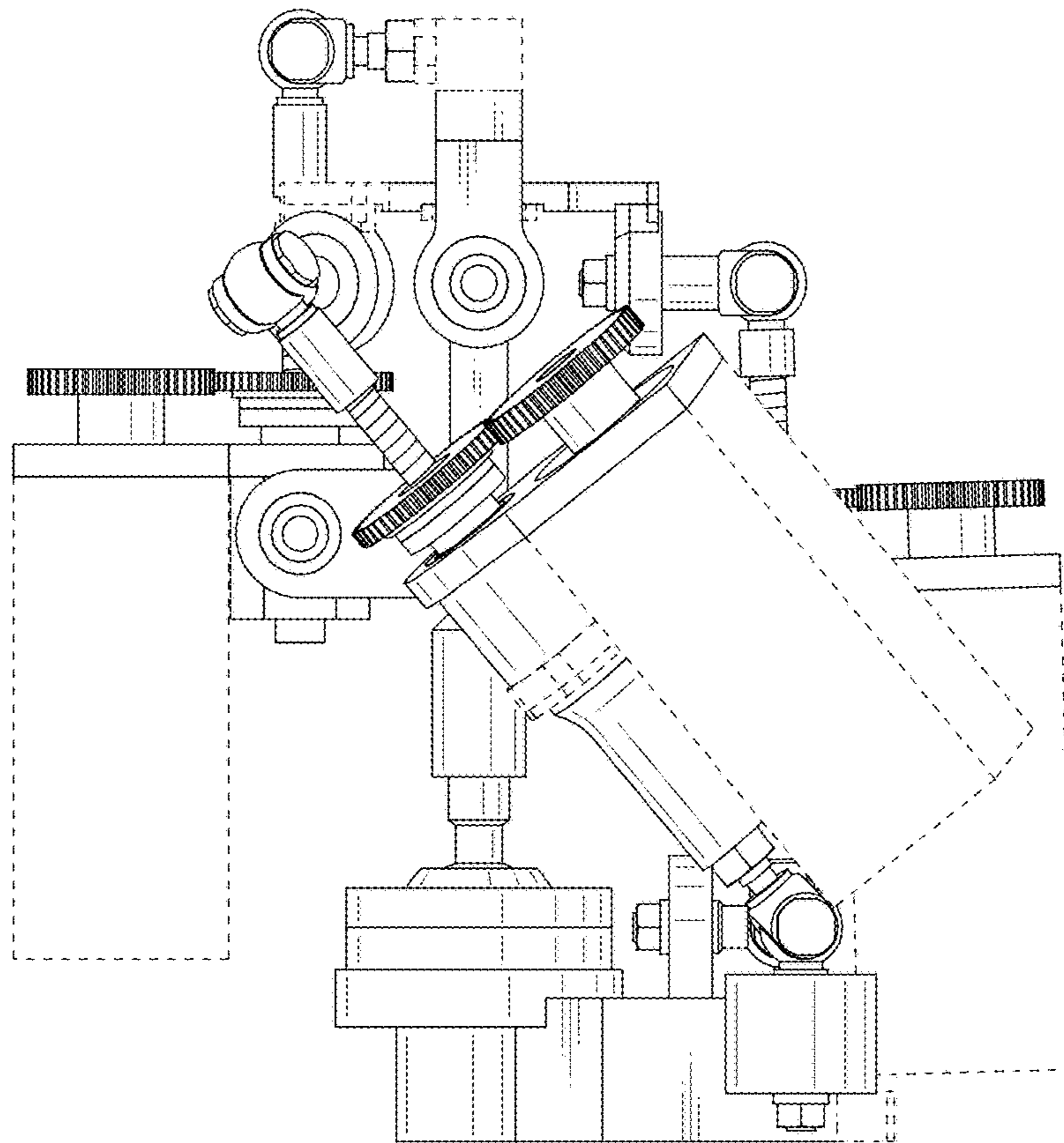




Fig. 7

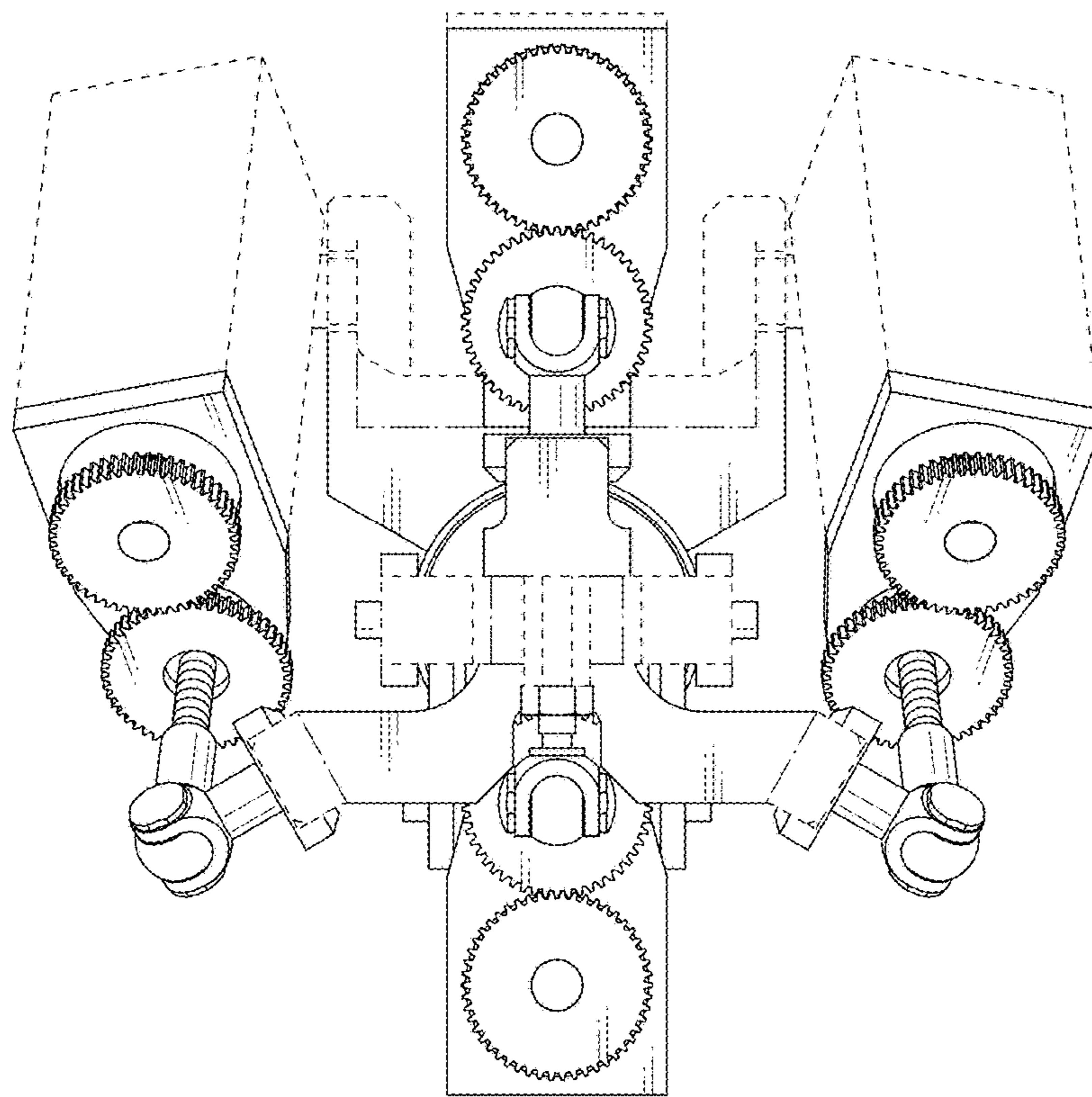


Fig. 8

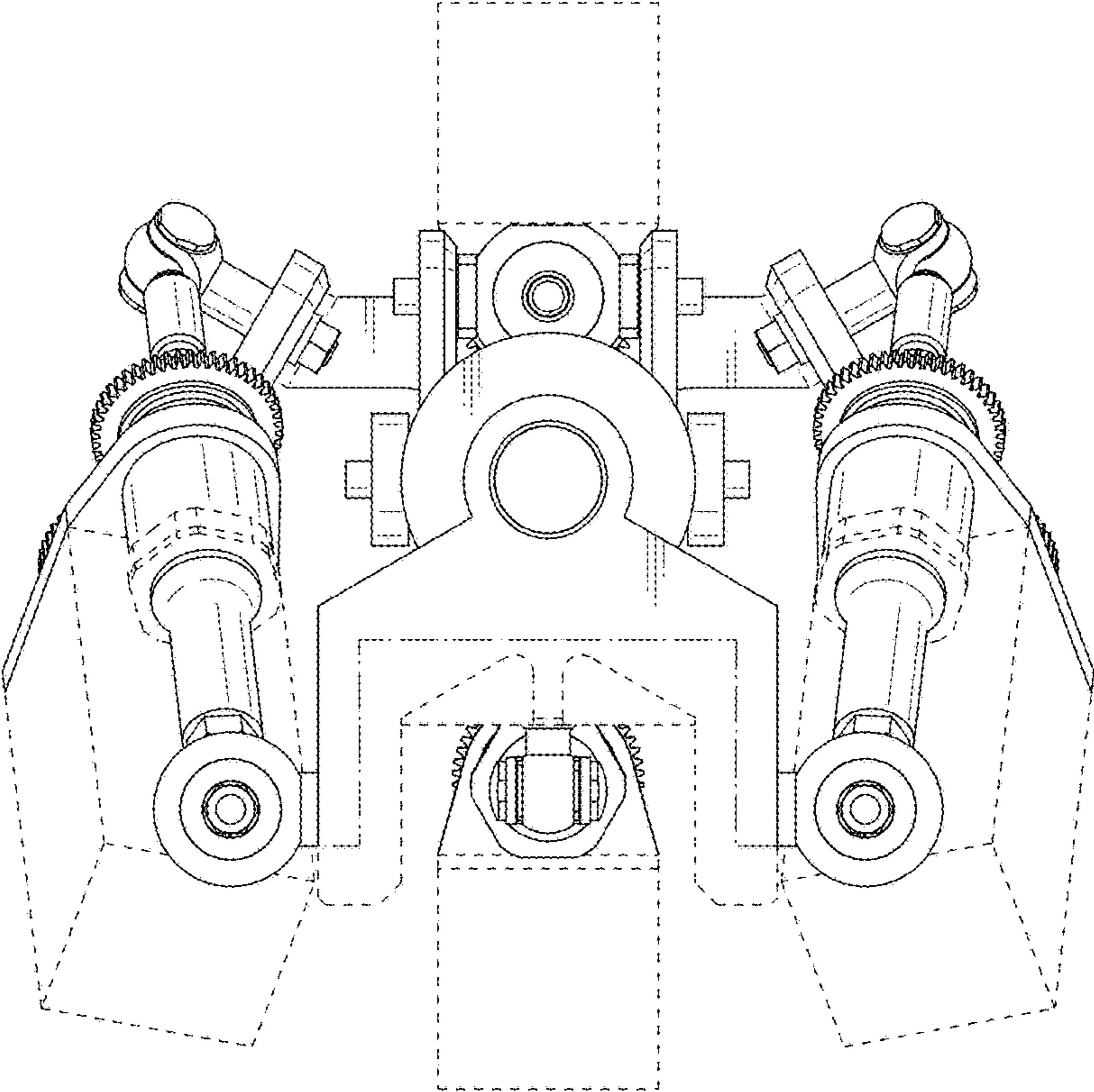


Fig. 9

