



US00D833498S

(12) **United States Design Patent** (10) **Patent No.:** **US D833,498 S**
Amir et al. (45) **Date of Patent:** **** Nov. 13, 2018**

(54) **SOCIAL ROBOT**

(71) Applicant: **Intuition Robotics Ltd.**, Ramat Gan (IL)

(72) Inventors: **Roy Amir**, Ramat Gan (IL); **Itai Mendelsohn**, Ramat Gan (IL); **Dor Skuler**, Ramat Gan (IL); **Shlomi Azoulay**, Ramat Gan (IL)

(73) Assignee: **Intuition Robotics Ltd.**, Ramat Gan (IL)

(**) Term: **15 Years**

(21) Appl. No.: **29/590,441**

(22) Filed: **Jan. 10, 2017**

(51) **LOC (11) Cl.** **15-99**

(52) **U.S. Cl.**
USPC **D15/199**

(58) **Field of Classification Search**
USPC D15/199; D21/578-583, 621, 622
CPC B25J 5/007; B25J 11/001; B25J 11/0005;
B25J 13/003
See application file for complete search history.

(56) **References Cited**

U.S. PATENT DOCUMENTS

D510,066 S	9/2005	Hickey et al.	
D549,756 S	8/2007	Park et al.	
D579,035 S	10/2008	Kim et al.	
D663,333 S	7/2012	Kitano et al.	
D663,334 S	7/2012	Kitano et al.	
D685,438 S	7/2013	Fan et al.	
D695,345 S	12/2013	Park et al.	
D719,621 S	12/2014	Song	
D725,166 S	3/2015	Paik et al.	
D725,167 S	3/2015	Song et al.	
D799,575 S	* 10/2017	Tang	D15/199

9,776,327 B2 *	10/2017	Pinter	B25J 9/1676
D810,490 S *	2/2018	Cha	D7/306
2016/0107317 A1 *	4/2016	Hashimoto	B25J 9/042 414/744.2
2017/0165840 A1 *	6/2017	Lee	H04N 5/2257
2017/0206064 A1 *	7/2017	Breazeal	G06F 8/34
2017/0225336 A1 *	8/2017	Deyle	G08B 13/196

OTHER PUBLICATIONS

“Notice of Allowance dated Jul. 3, 2018; Japanese Patent Application No. 2017-14837”, Jul. 3, 2018.

“Notice of Allowance dated Nov. 2, 2017; Chinese Patent Application No. 201730300746.9”, Nov. 2, 2017.

“Office Action dated Mar. 23, 2018; Japanese Patent Application No. 2017-14837”, Mar. 23, 2018.

* cited by examiner

Primary Examiner — Patricia A Palasik

(74) *Attorney, Agent, or Firm* — Womble Bond Dickinson (US) LLP

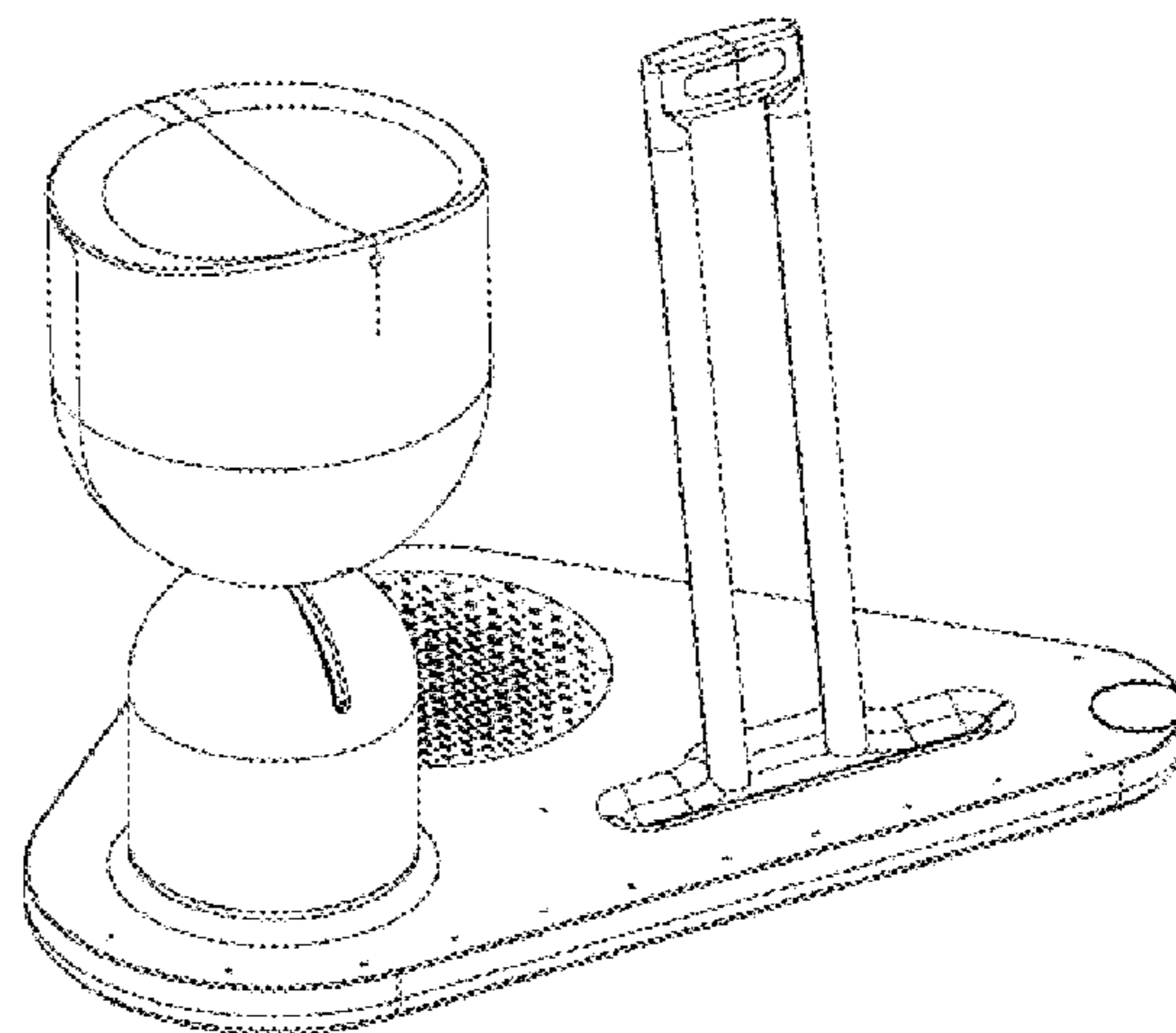
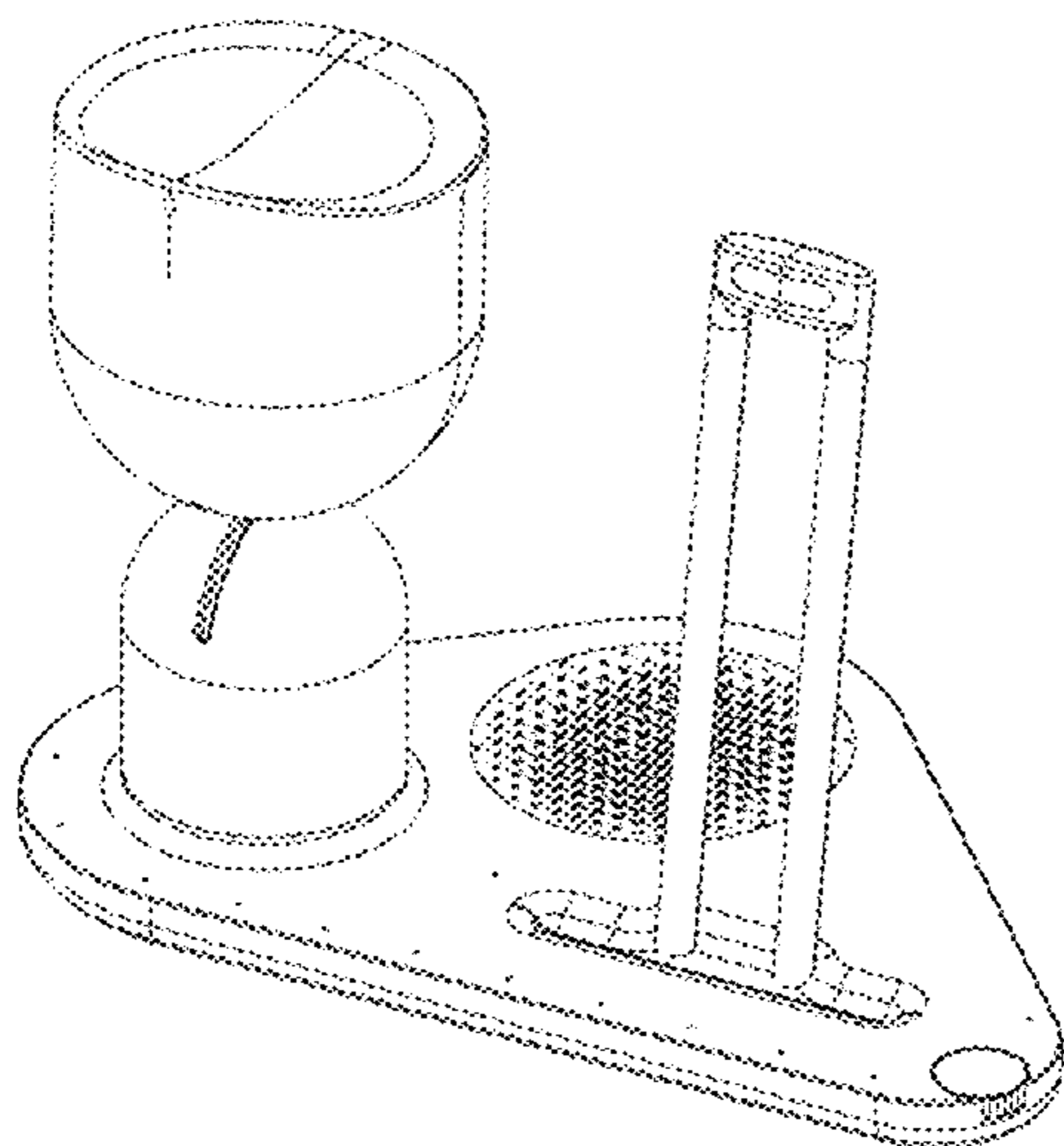
(57) **CLAIM**

We claim the ornamental design for a social robot, as shown and described.

DESCRIPTION

FIG. 1 is a first front isometric view of one embodiment of a social robot showing our new design in closed position. FIG. 2 is a second front isometric view thereof. FIG. 3 is a front view thereof. FIG. 4 is a rear view thereof. FIG. 5 is a top view thereof. FIG. 6 is a left side view thereof. FIG. 7 is a right side view thereof; and, FIG. 8 is a front isometric view thereof that demonstrates one movement capability. The broken lines in the drawing depict unclaimed environment subject matter.

1 Claim, 8 Drawing Sheets



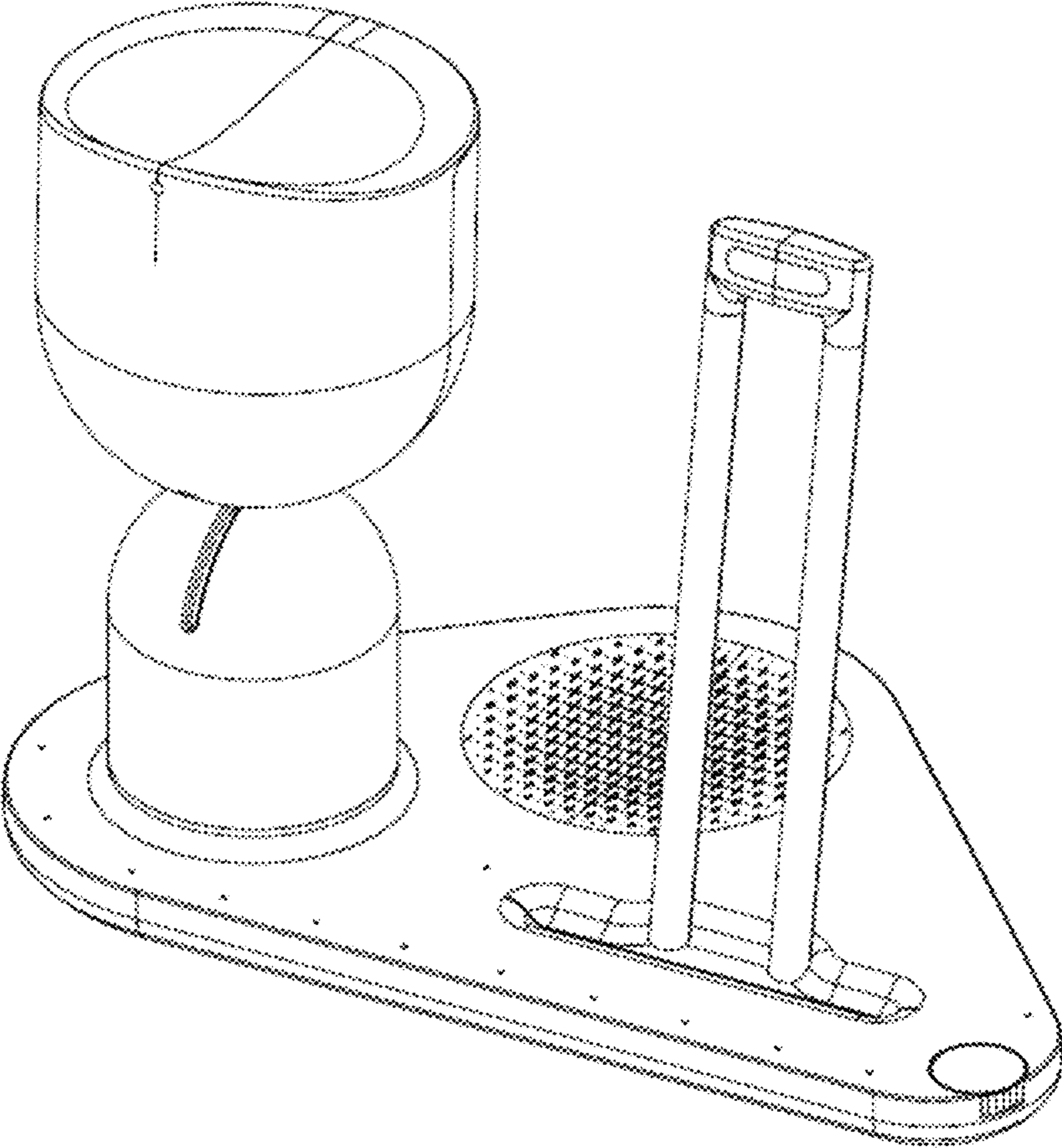


FIG. 1

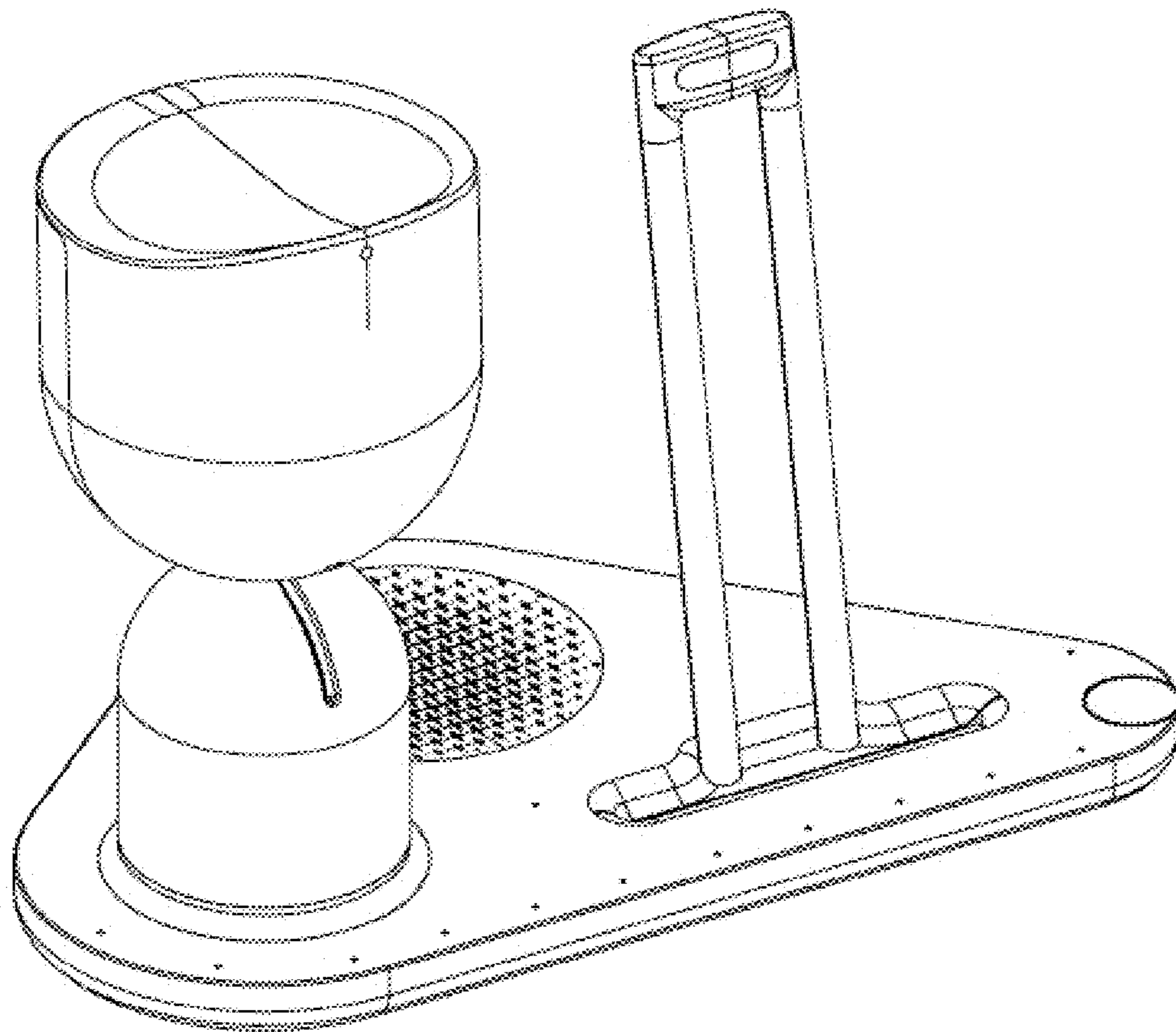


FIG. 2

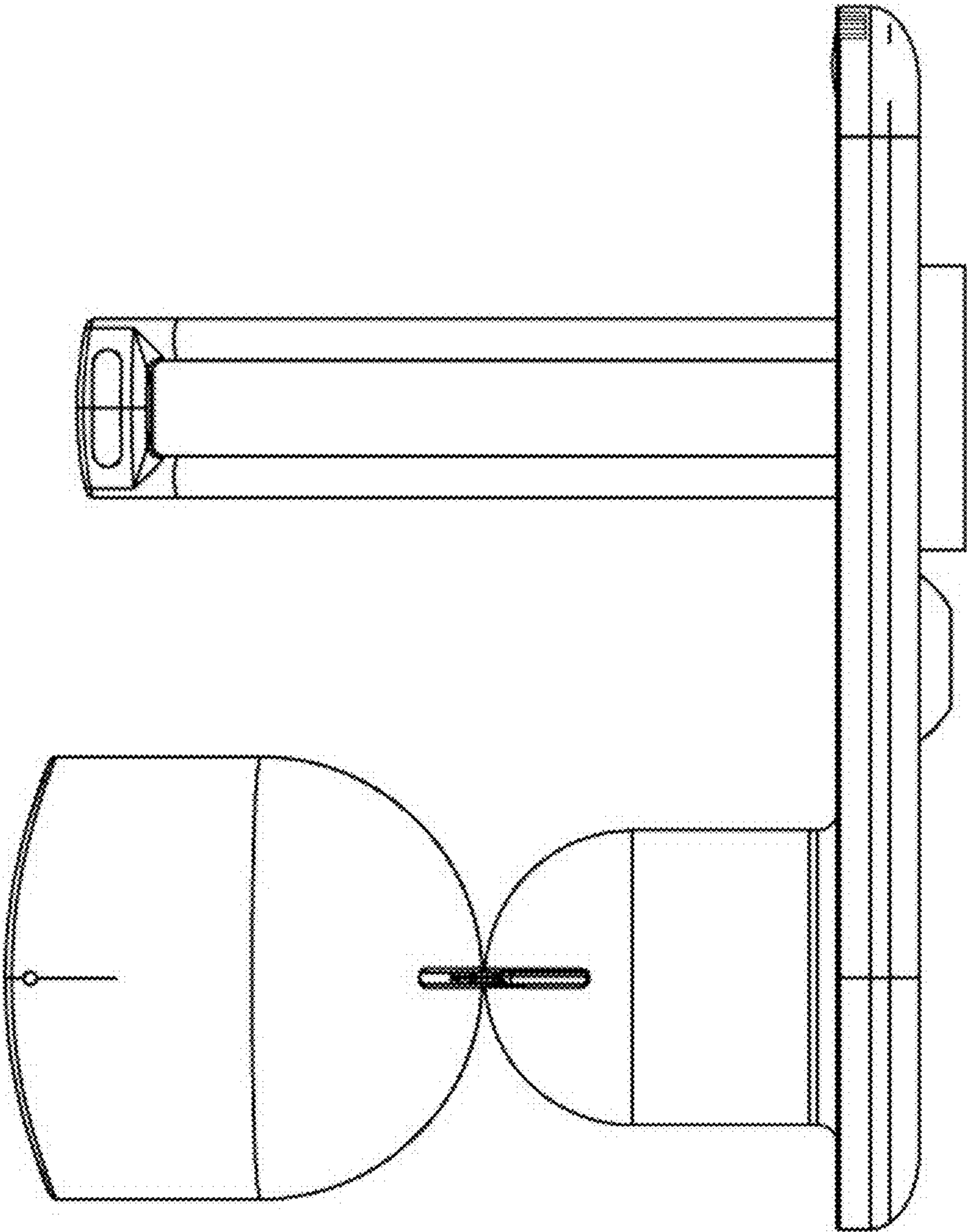


FIG. 3

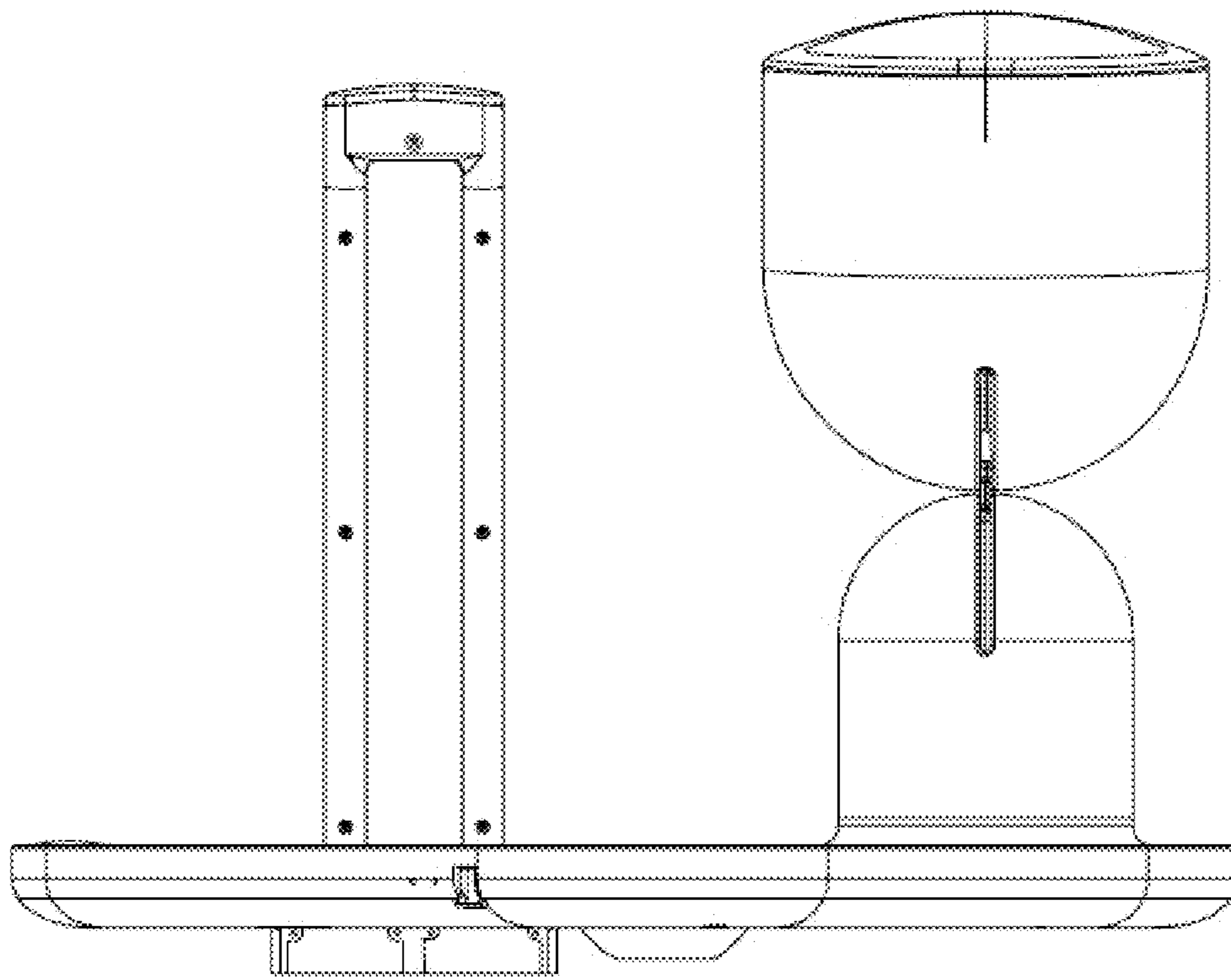


FIG. 4

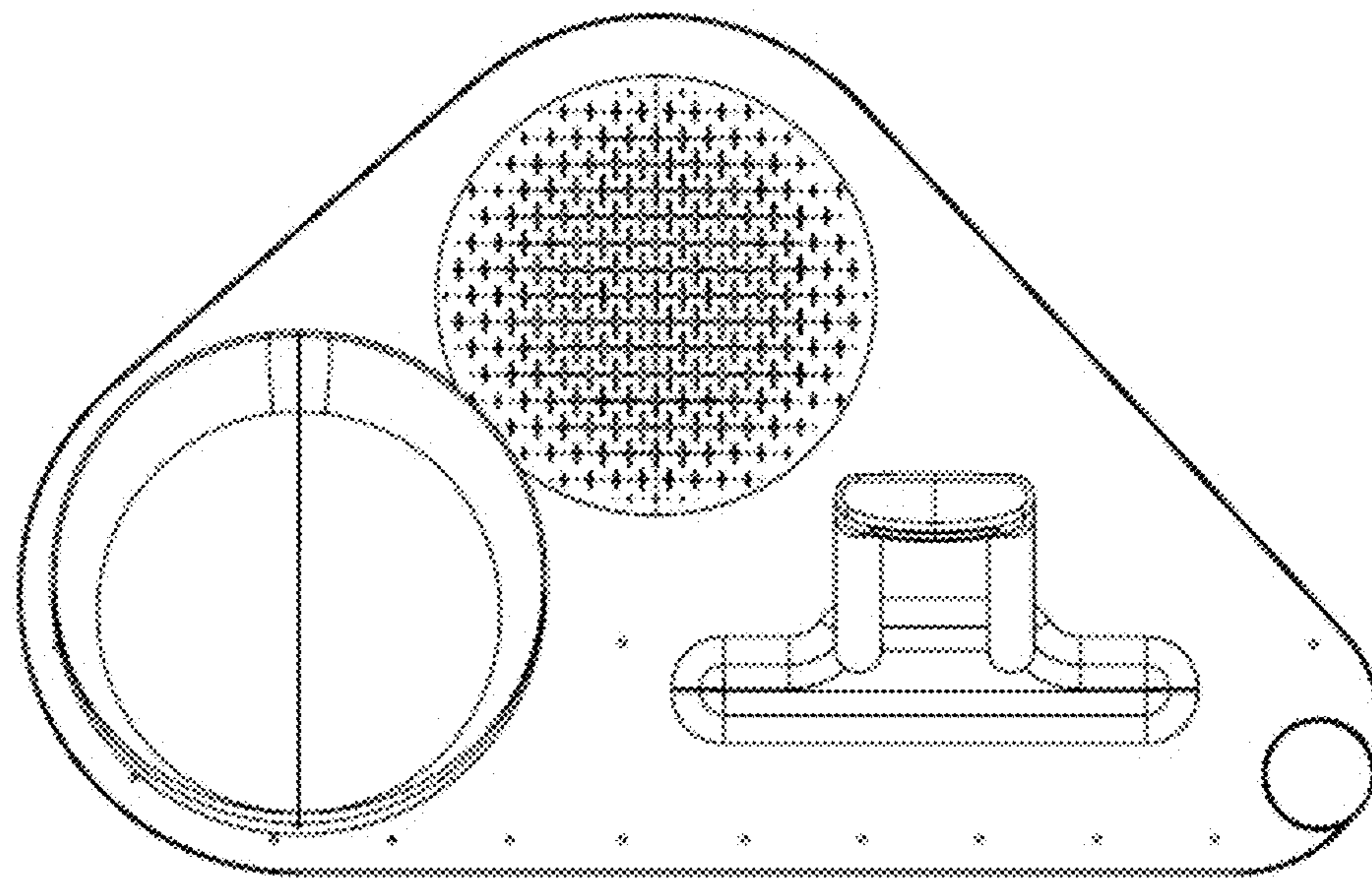


FIG. 5

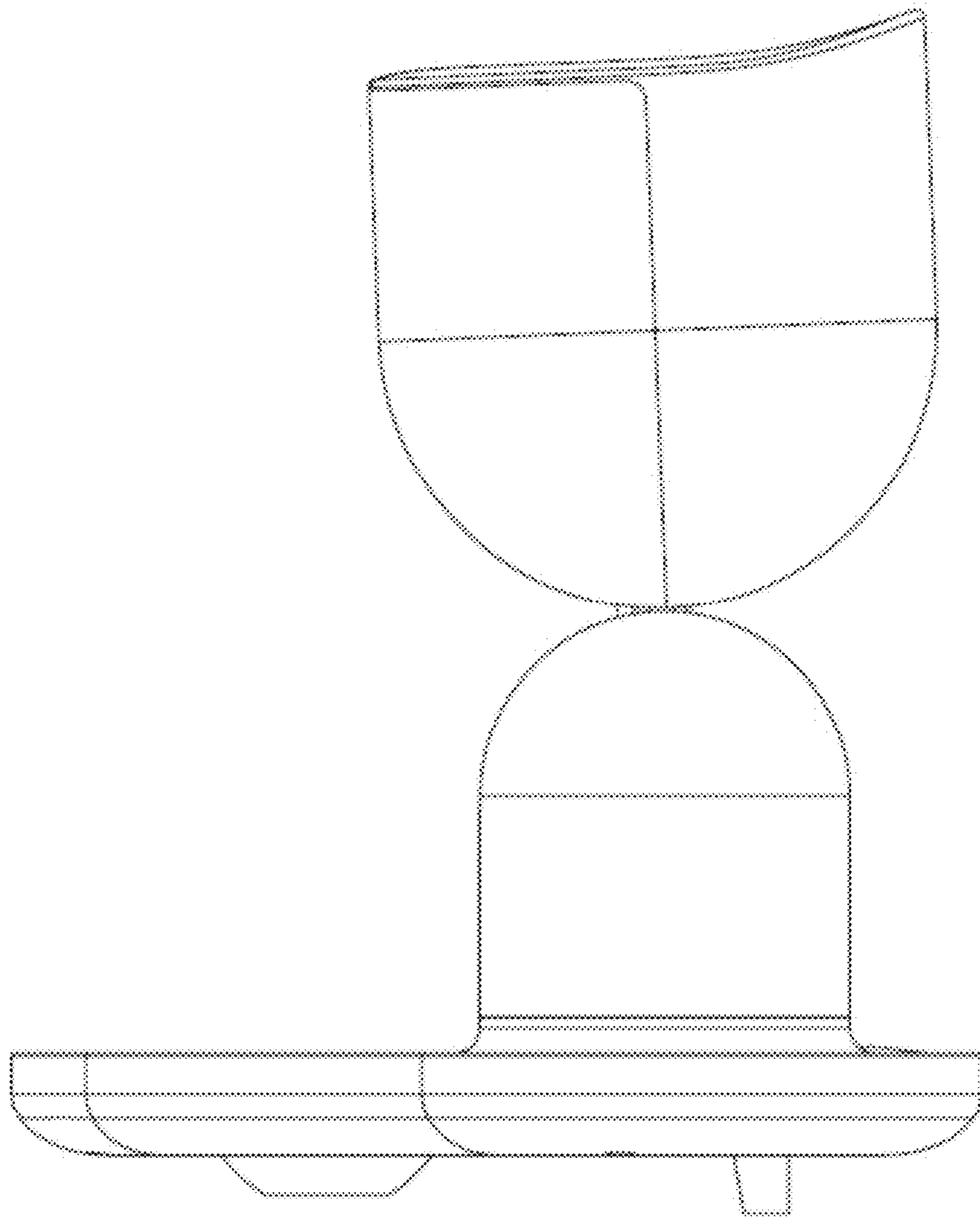


FIG. 6

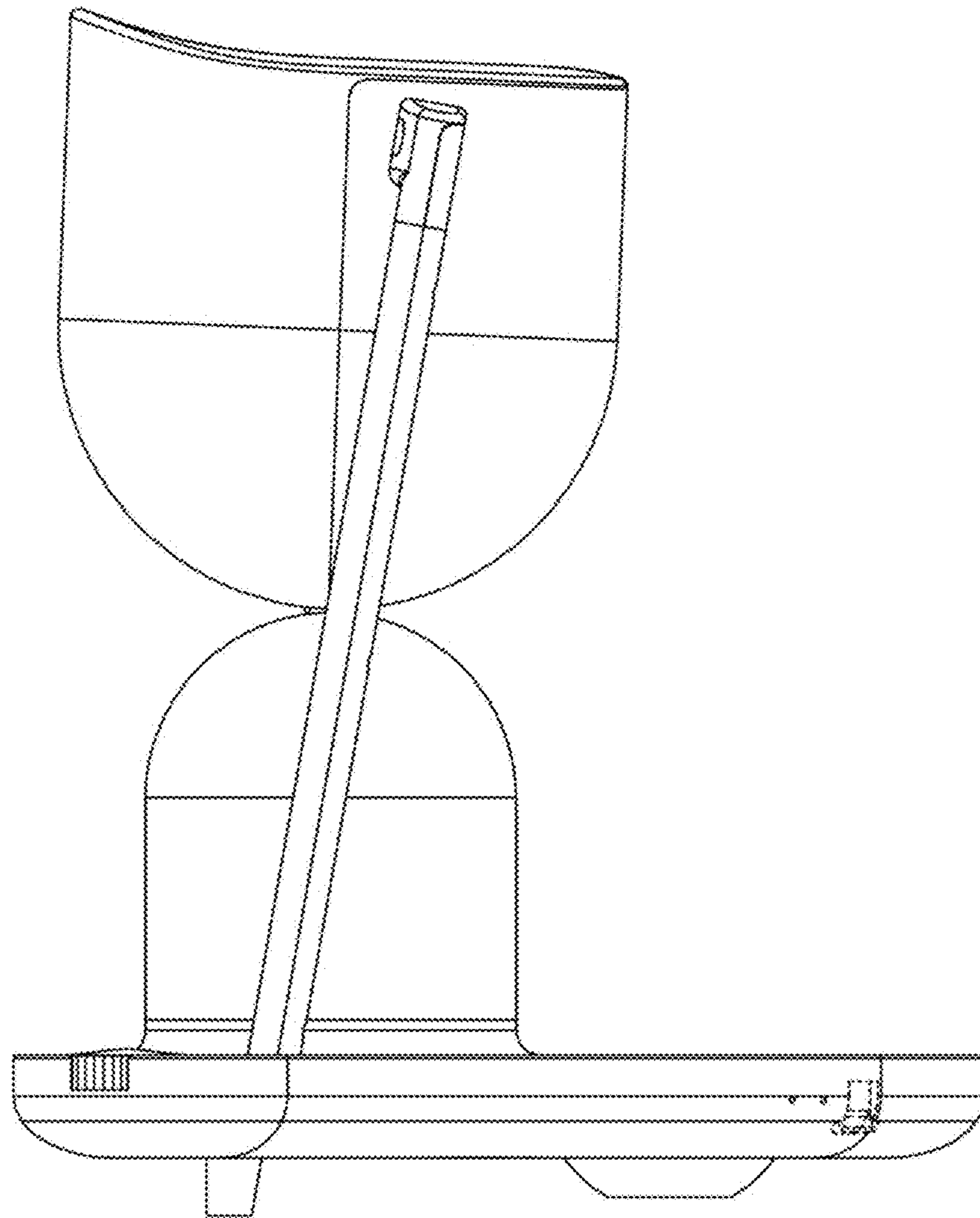


FIG. 7

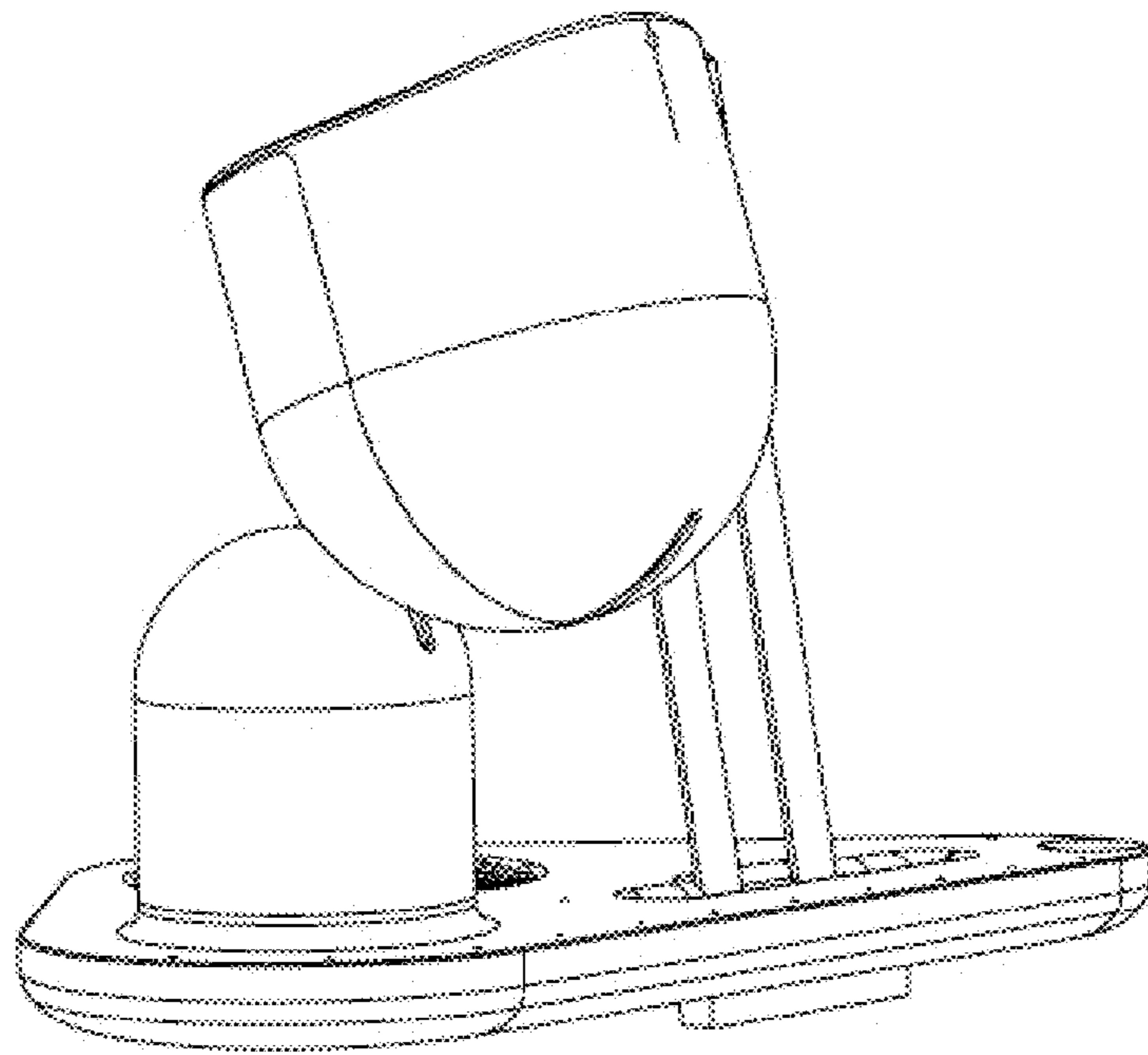


FIG. 8