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Xiong et al.

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(54) **ACOUSTIC REMOTE CONTROLLED INTELLIGENT UNDERWATER ROBOT**

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(**) Term: **15 Years**

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(30) **Foreign Application Priority Data**

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(51) **LOC (11) Cl.** **12-06**

(52) **U.S. Cl.**
USPC **D12/308**; D15/199

(58) **Field of Classification Search**
USPC D12/16.1, 308; D15/199; D21/578–583, D21/621, 622
CPC B25J 9/08; B63B 2201/02; B63B 2207/02; B63B 2755/00; B63G 8/04; B63G 8/08; B63G 8/22; B63G 8/001; B63G 8/005; G05D 1/0875
See application file for complete search history.

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(57) **CLAIM**

The ornamental design for an acoustic remote controlled intelligent underwater robot, as shown and described.

DESCRIPTION

FIG. **1** is a front upper perspective view of the acoustic remote controlled intelligent underwater robot showing my design and a controller as an accessory in broken lines and internal structures in broken lines.

FIG. **2** is a front elevation view thereof, showing internal structures in broken lines;

FIG. **3** is a back elevation view thereof;

FIG. **4** is a side elevation view thereof, showing internal structures in broken lines;

FIG. **5** is an opposite side elevation view thereof, showing internal structures in broken lines;

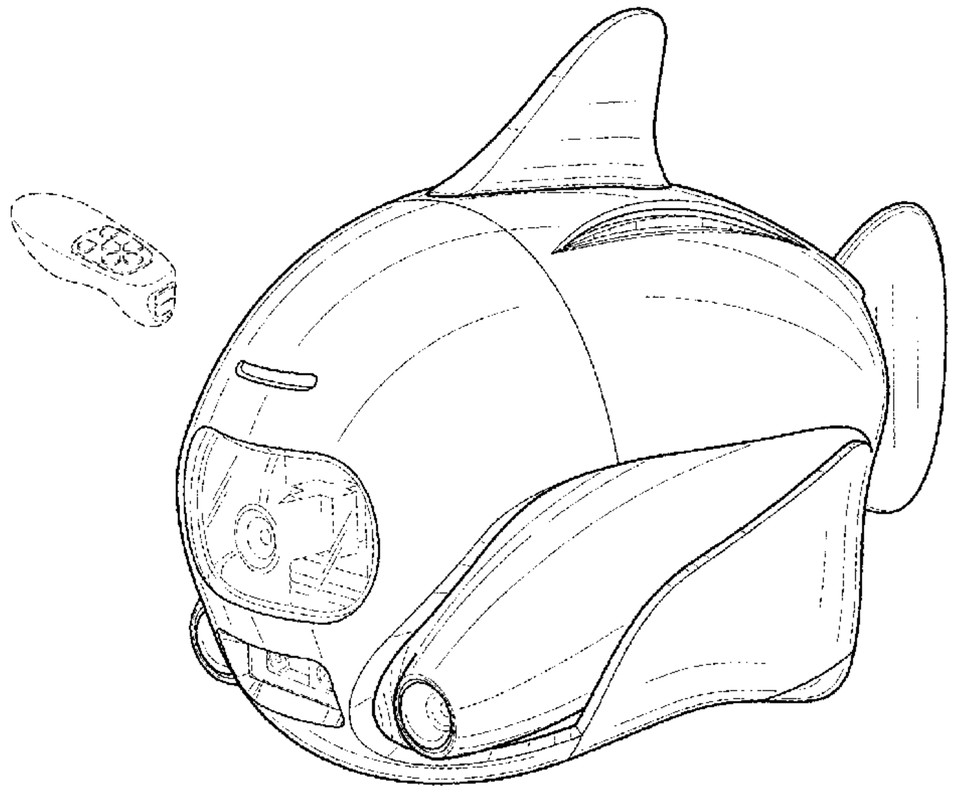
FIG. **6** is a top plan view thereof;

FIG. **7** is a bottom plan view thereof; and,

FIG. **8** is another perspective view thereof, showing a controller as an accessory in broken lines and internal structures in broken lines.

The accessory and internal structures in broken lines forms no part of the claimed design. The broken lines represent a remote controller as an accessory as environment for the context of the intelligent robot of the present application. The broken lines represent internal structures as environment for the context of the intelligent robot of the present application.

1 Claim, 3 Drawing Sheets



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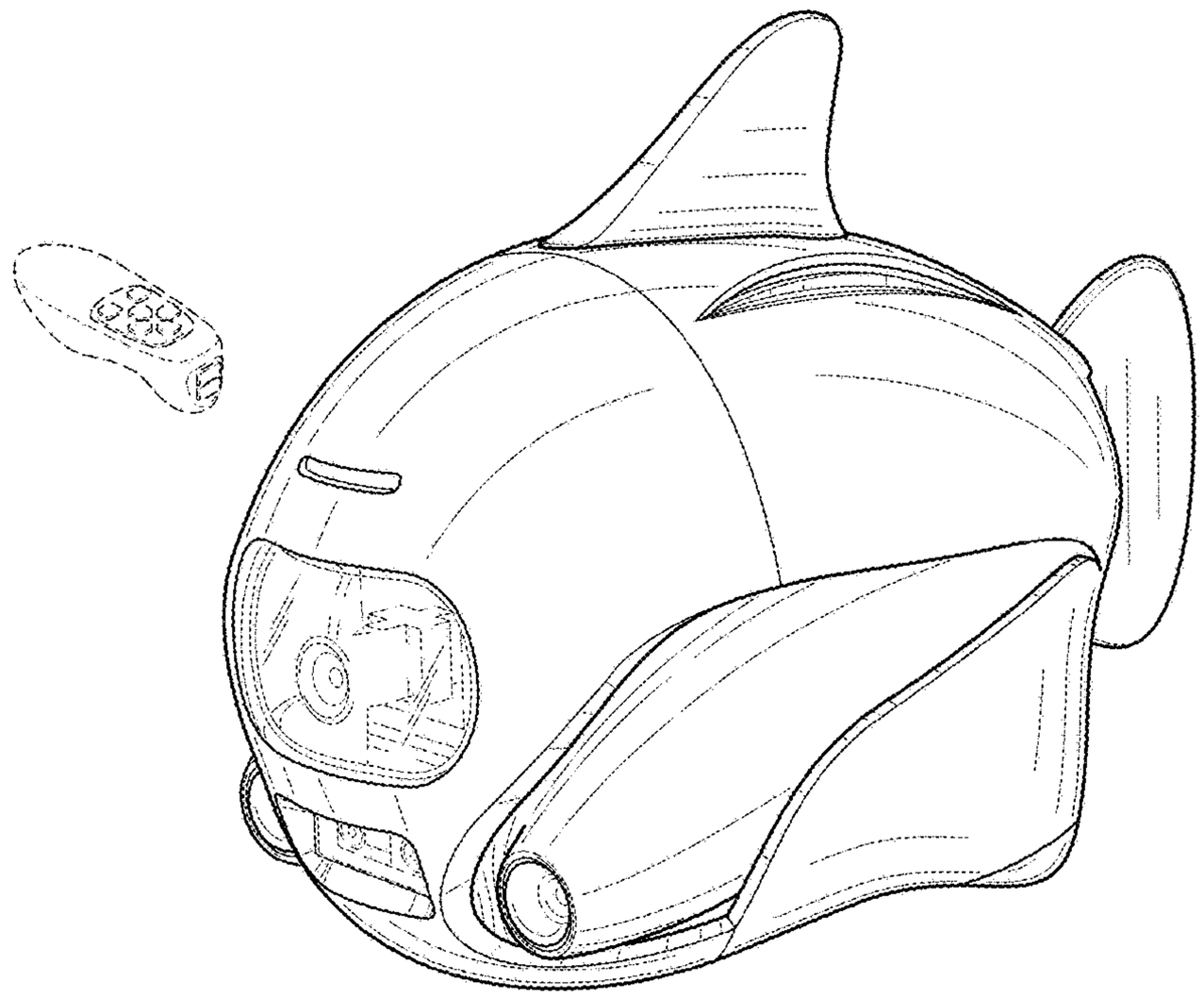

FIG. 1

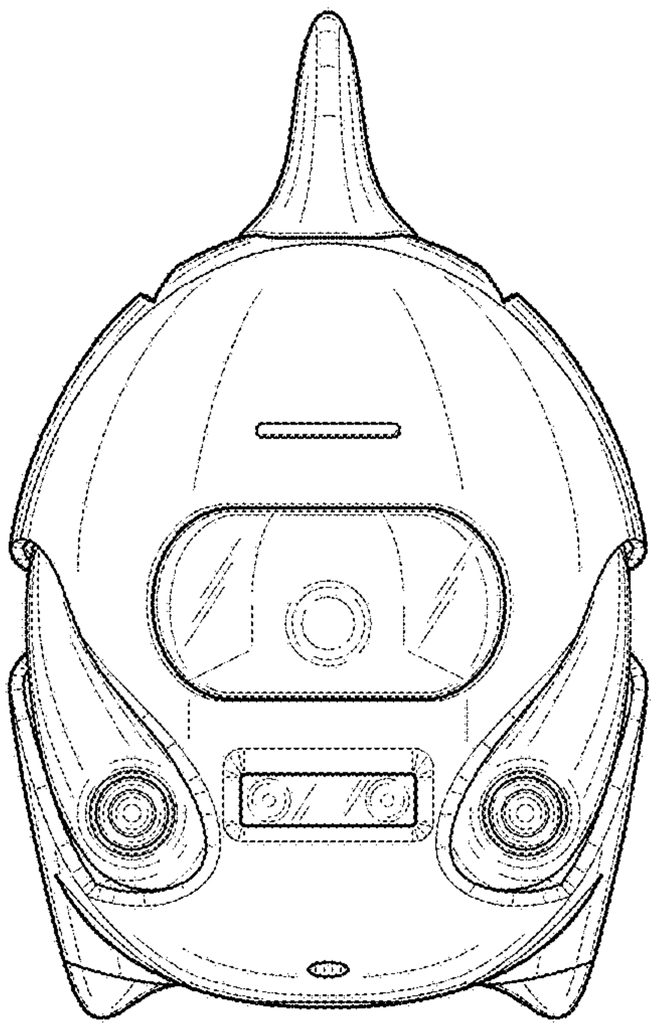

FIG. 2

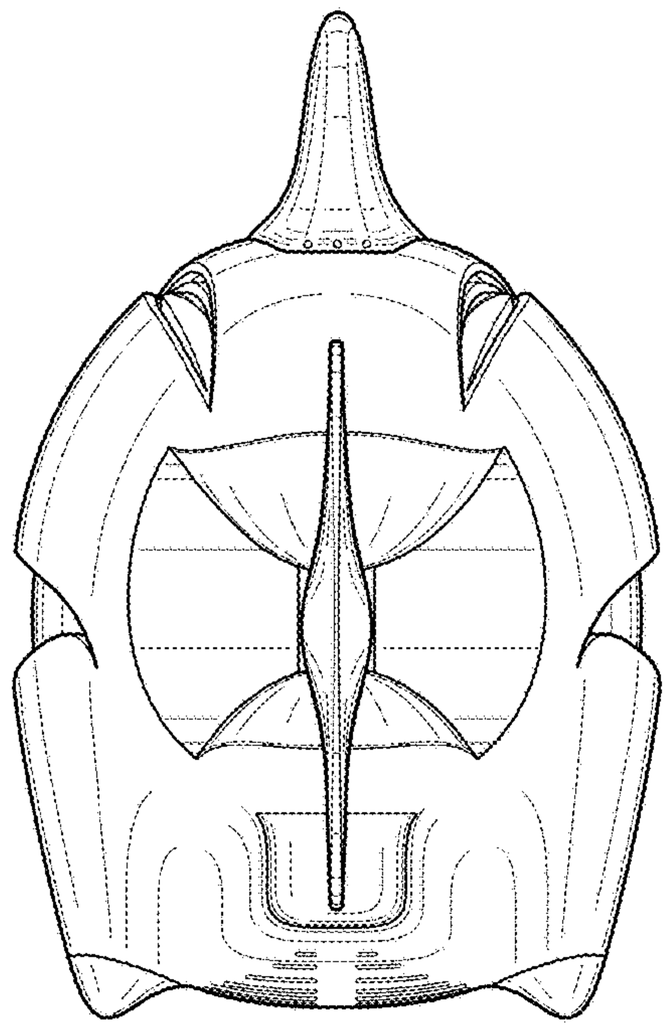

FIG. 3

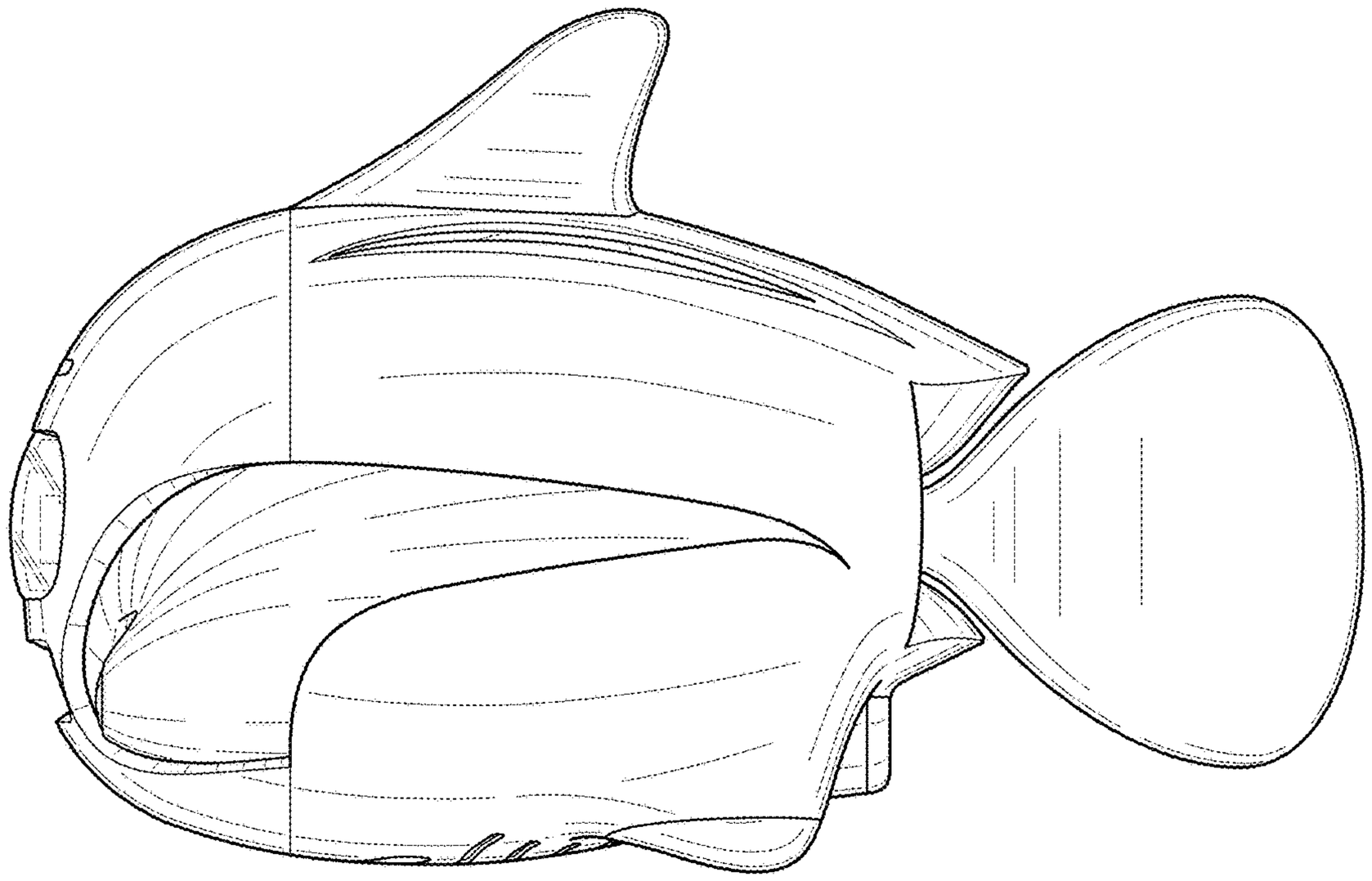

FIG. 4

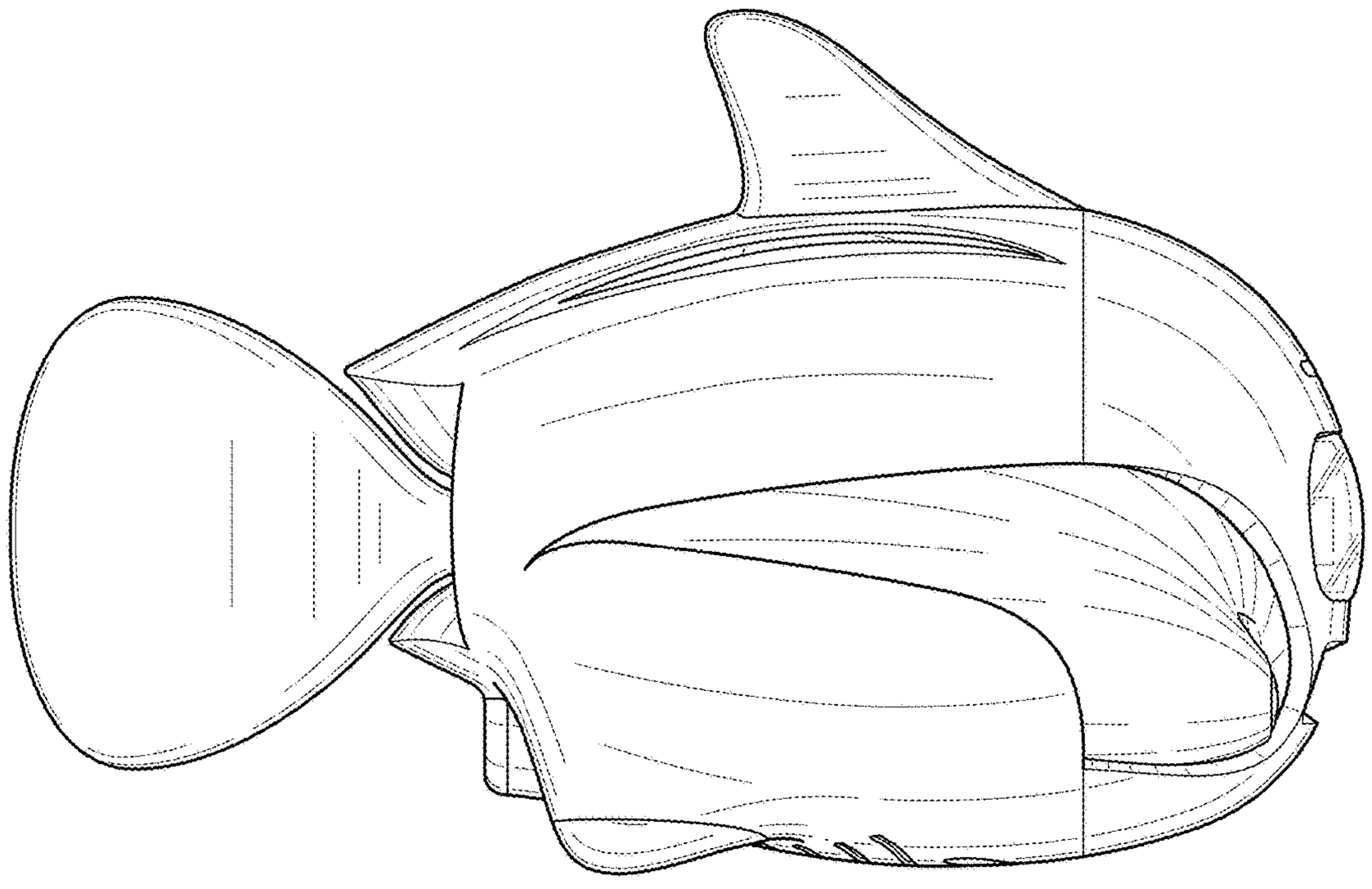

FIG. 5

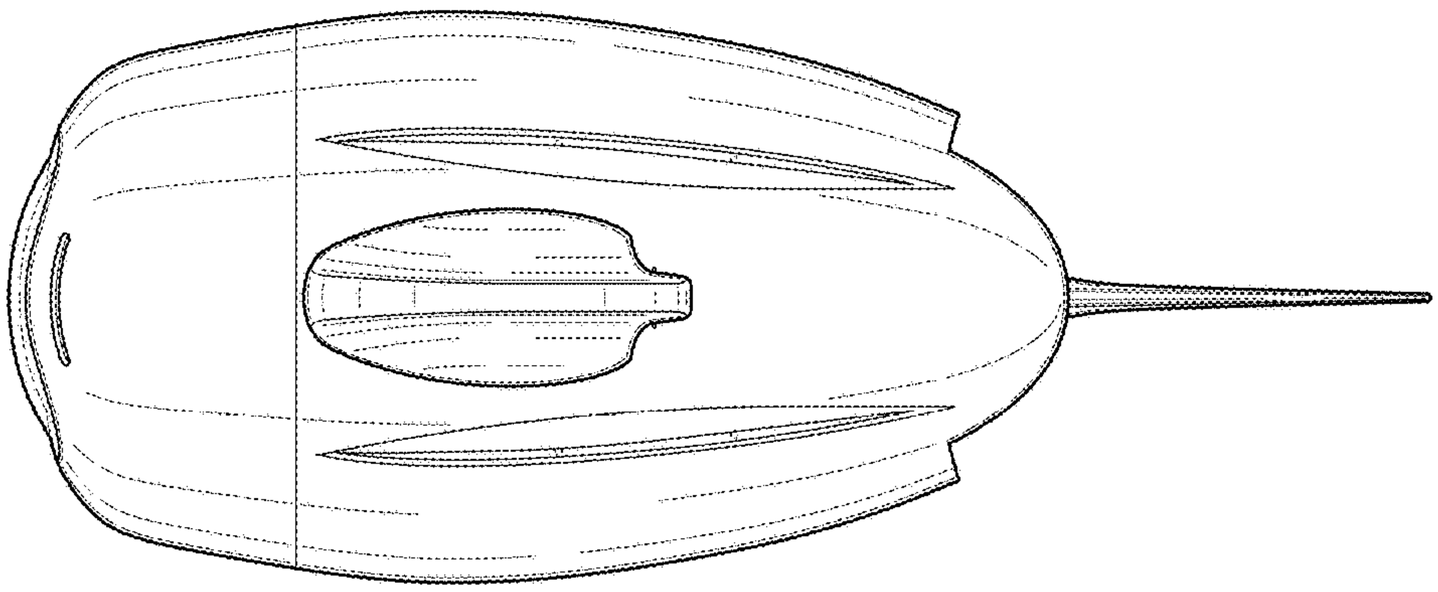

FIG. 6

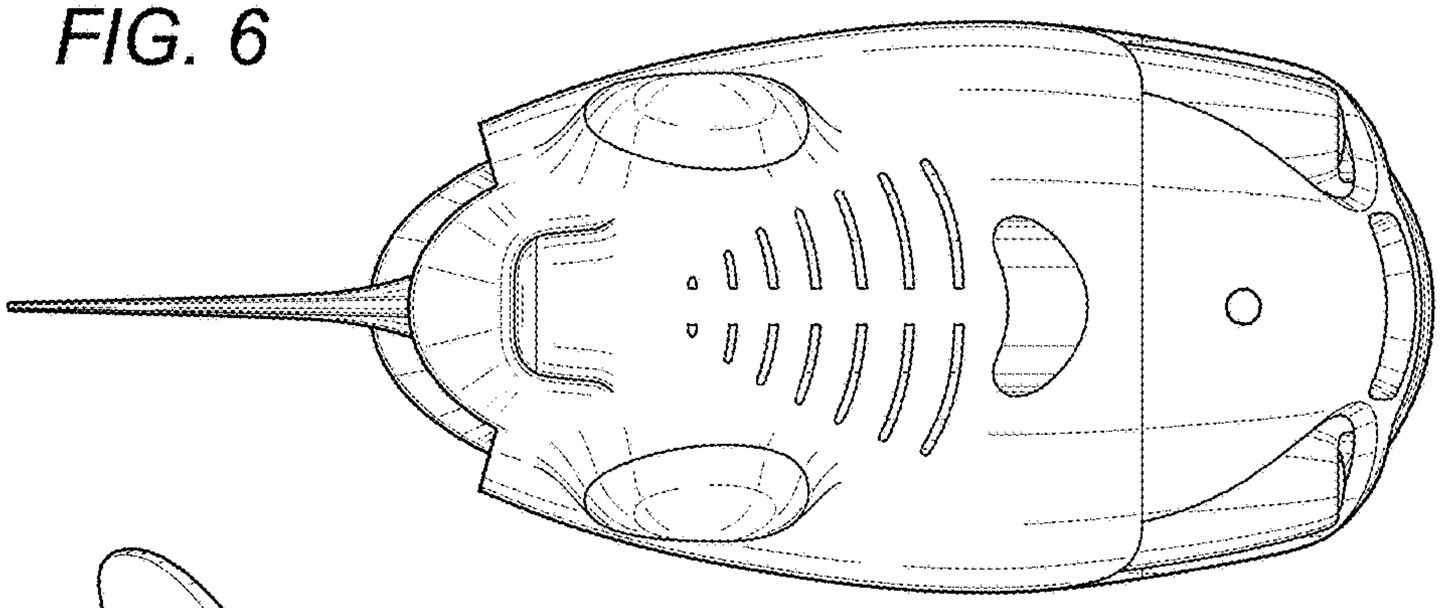

FIG. 7

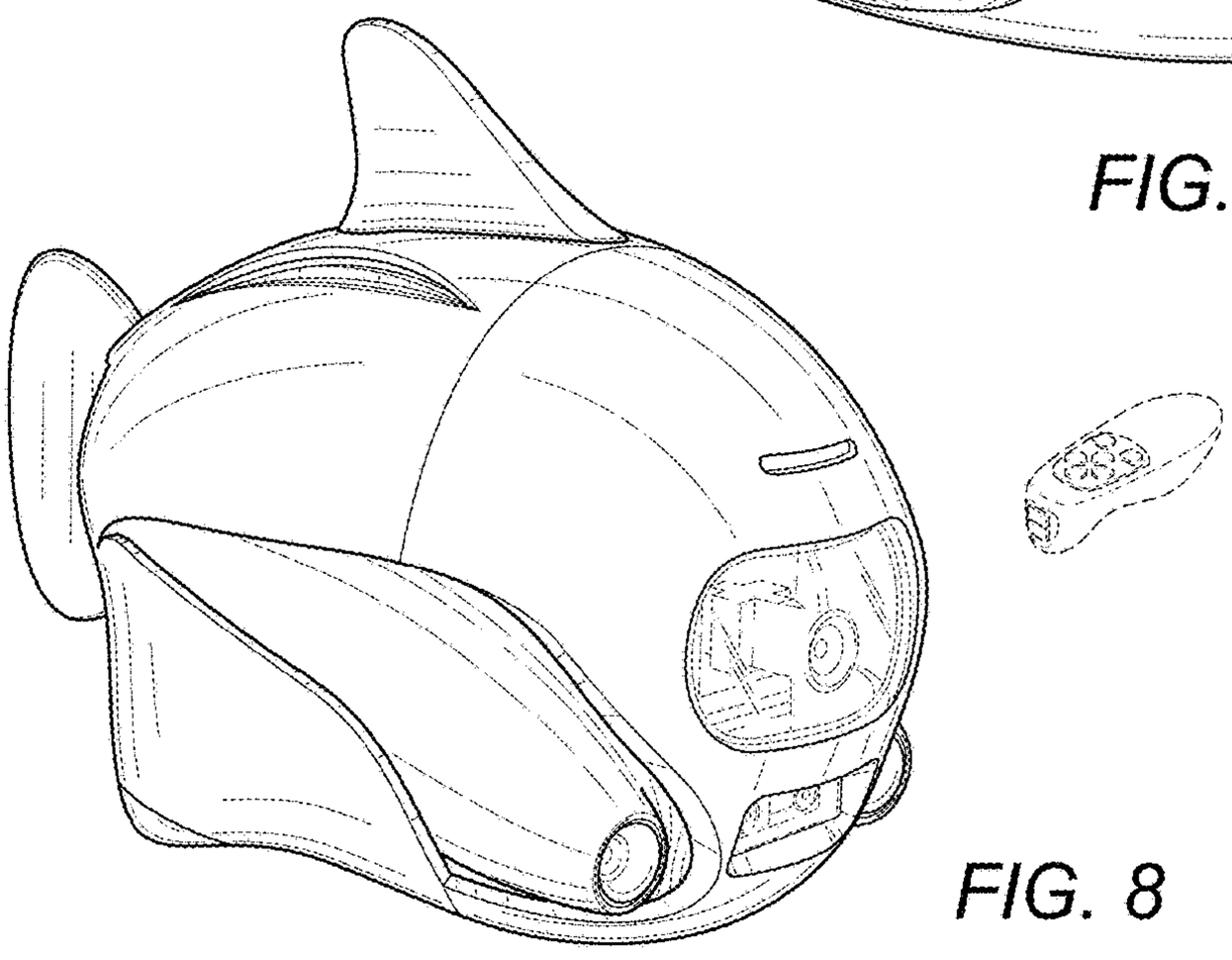

FIG. 8