



US00D529609S

(12) **United States Design Patent**  
**Ido et al.**

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(45) **Date of Patent:** **\*\* Oct. 3, 2006**

(54) **FORCEPS FOR MEDICAL ROBOT**

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(73) Assignee: **Kabushiki Kaisha Toshiba** (JP)

\* cited by examiner

(\*\*) Term: **14 Years**

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(21) Appl. No.: **29/210,706**

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(22) Filed: **Aug. 5, 2004**

(57) **CLAIM**

(30) **Foreign Application Priority Data**

The ornamental design for a forceps for medical robot, as shown and described.

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**DESCRIPTION**

(51) **LOC (8) Cl.** ..... **24-02**

(52) **U.S. Cl.** ..... **D24/143**

(58) **Field of Classification Search** ..... D24/143–146,  
D24/133, 108, 111; D14/218; 606/208, 170,  
606/48; 600/130, 564; 700/245; 604/34  
See application file for complete search history.

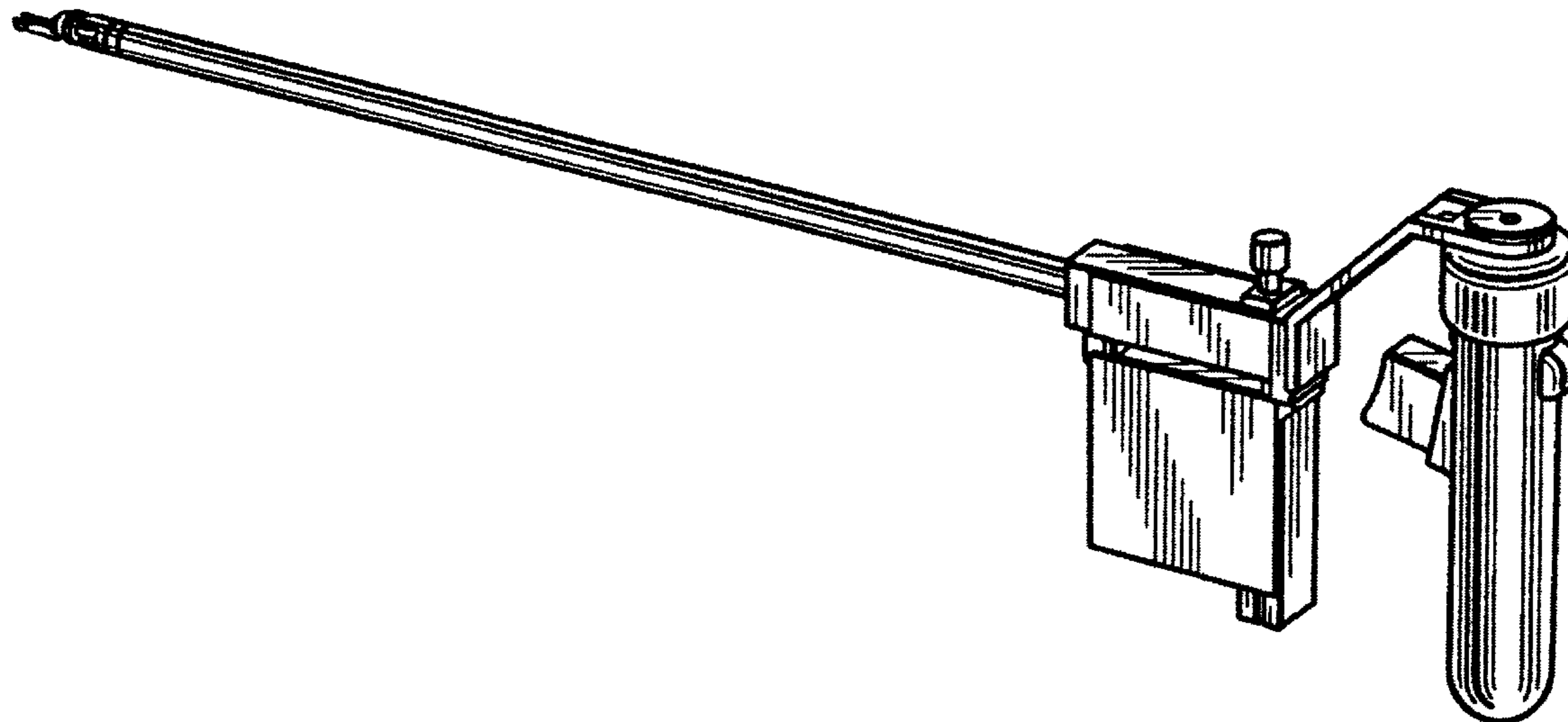
FIG. 1 is a front, top and right side perspective view of a forceps for medical robot, showing our new design; FIG. 2 is a front elevational view thereof; a rear elevational view being a mirror image thereof; FIG. 3 is a top plan view thereof; FIG. 4 is a bottom plan view thereof; FIG. 5 is a left side elevational view thereof; and, FIG. 6 is a right side elevational view thereof.

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**1 Claim, 4 Drawing Sheets**



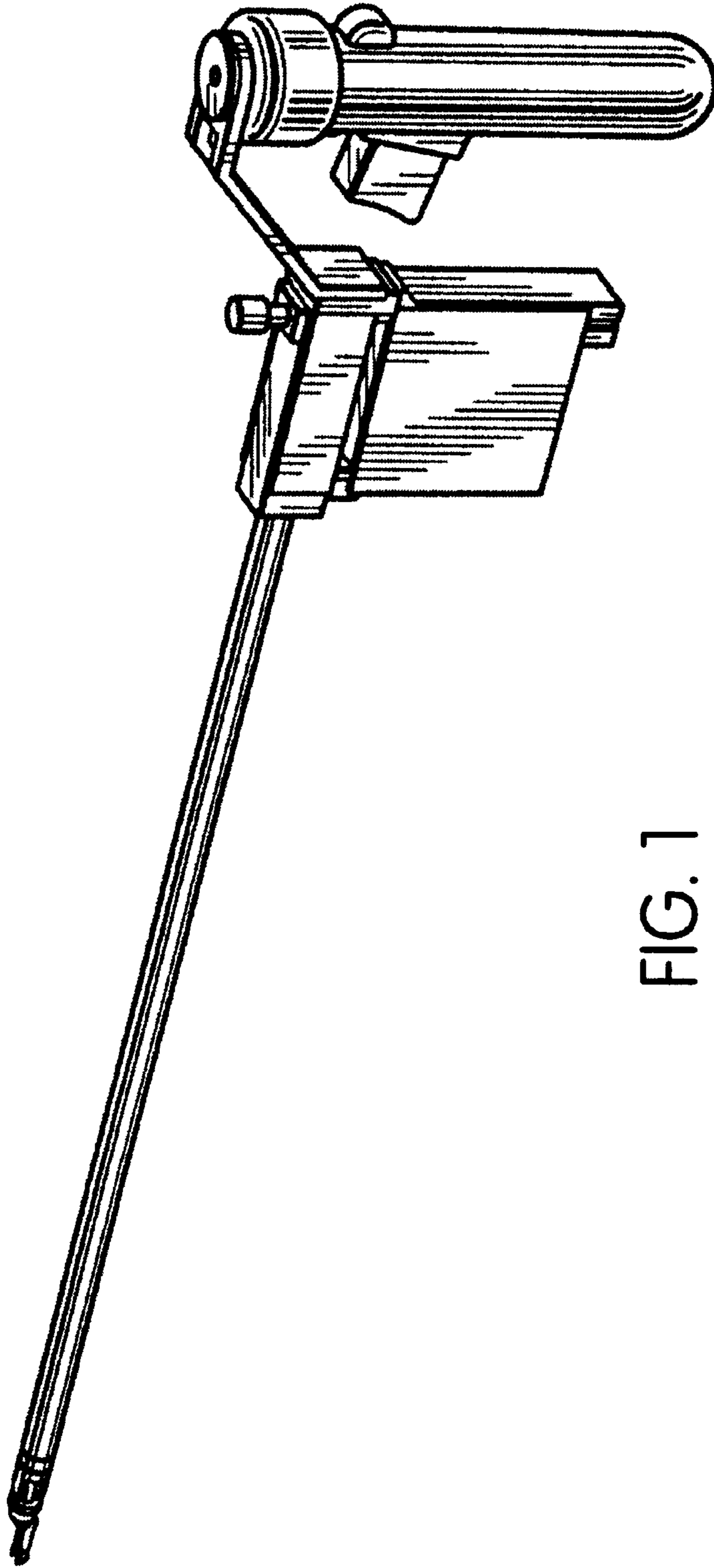


FIG. 1

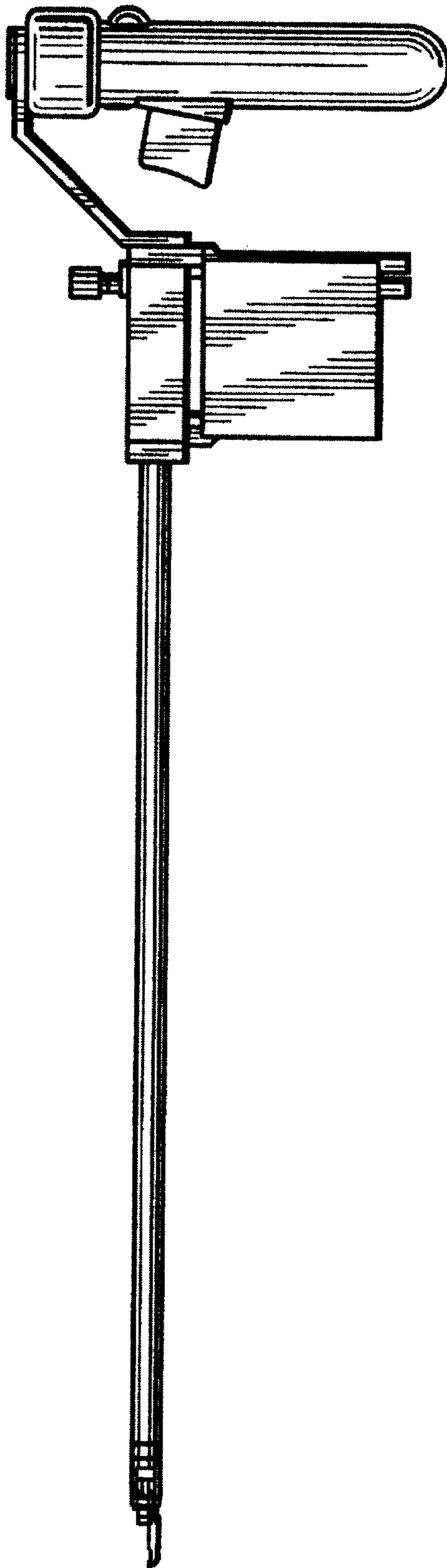


FIG. 2

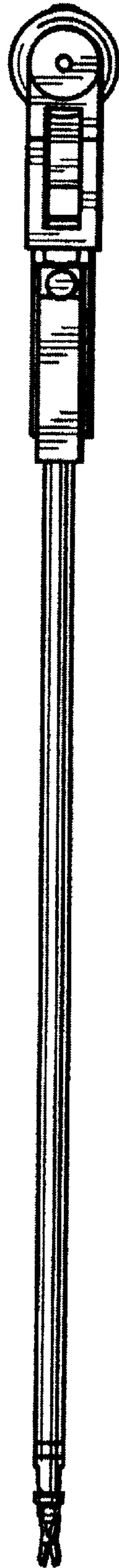


FIG. 3

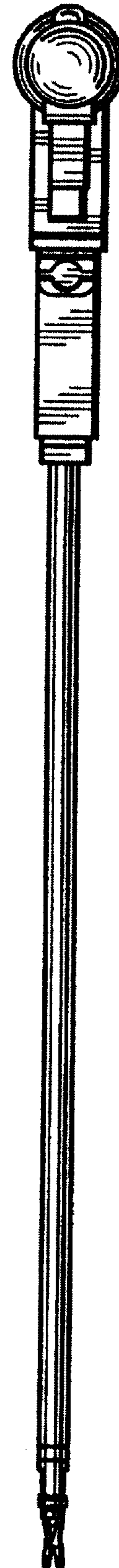


FIG. 4

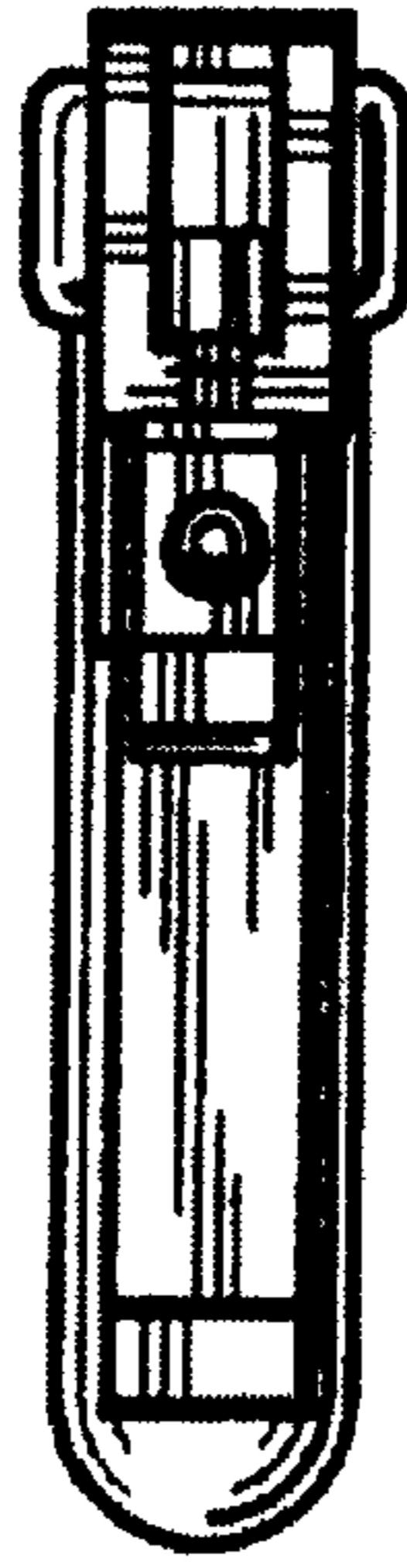


FIG. 5

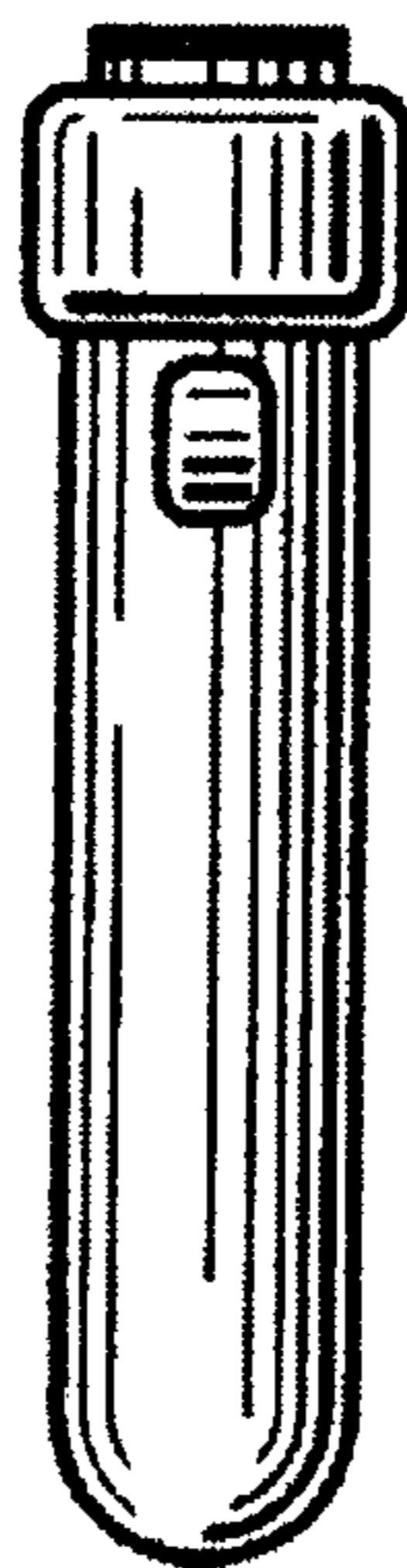


FIG. 6