

## US00D367486S

# United States Patent

### Bunker et al.

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[54]	X-Y ROBOTIC MANIPULATOR			
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[73]	Assignee:	Dyne	ovation Inc., Canada	
[**]	Term:	14 Y	ears	
[21]	Appl. No.:	: 35,78	84	
[22]	Filed:	Mar	. 7, 1995	
[30] Foreign Application Priority Data				
Oct	12 1994 [6	CA1	Canada	1994-2021

Canada ...... 1994-2021 Oct. 12, 1994 [CA]

[52] U.S. Cl. D15/199 414/749; 901/1–10, 16, 21, 27

#### [56] **References Cited**

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Primary Examiner—Antoine Duval Davis Attorney, Agent, or Firm—Biebel & French

CLAIM [57]

The ornamental design for an X-Y robotic manipulator, as shown and described.

### DESCRIPTION

FIG. 1 is a perspective view looking toward the front of the X-Y robotic manipulator from above and to the left of a first embodiment of the design, the latter employing a single Y axis arm assembly;

FIG. 2 is a left side elevation view of the first embodiment;

FIG. 3 is a right side elevation view of the first embodiment;

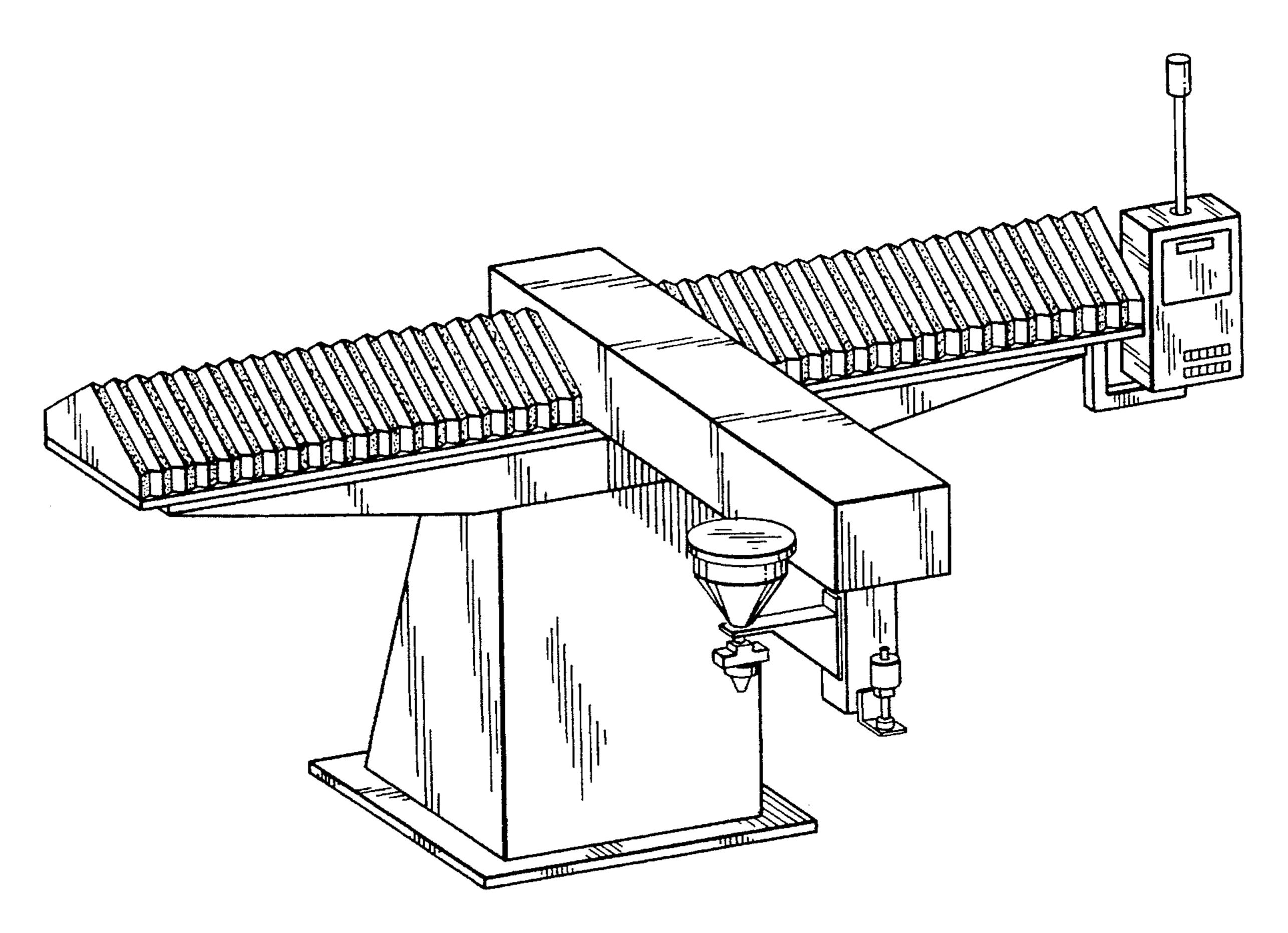
FIG. 4 is a rear elevation view of the first embodiment;

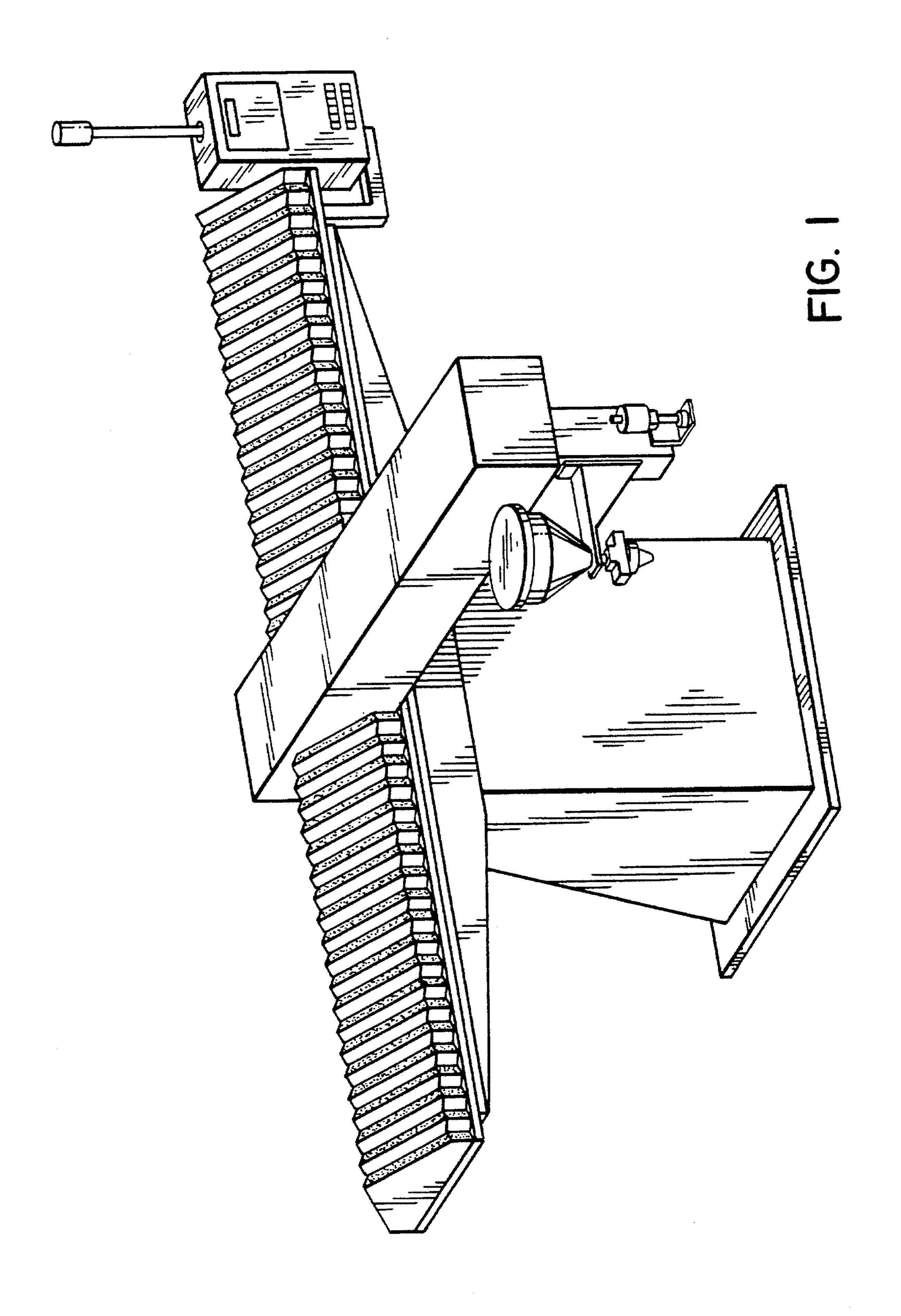
FIG. 5 is a side elevation view of a second embodiment of the design;

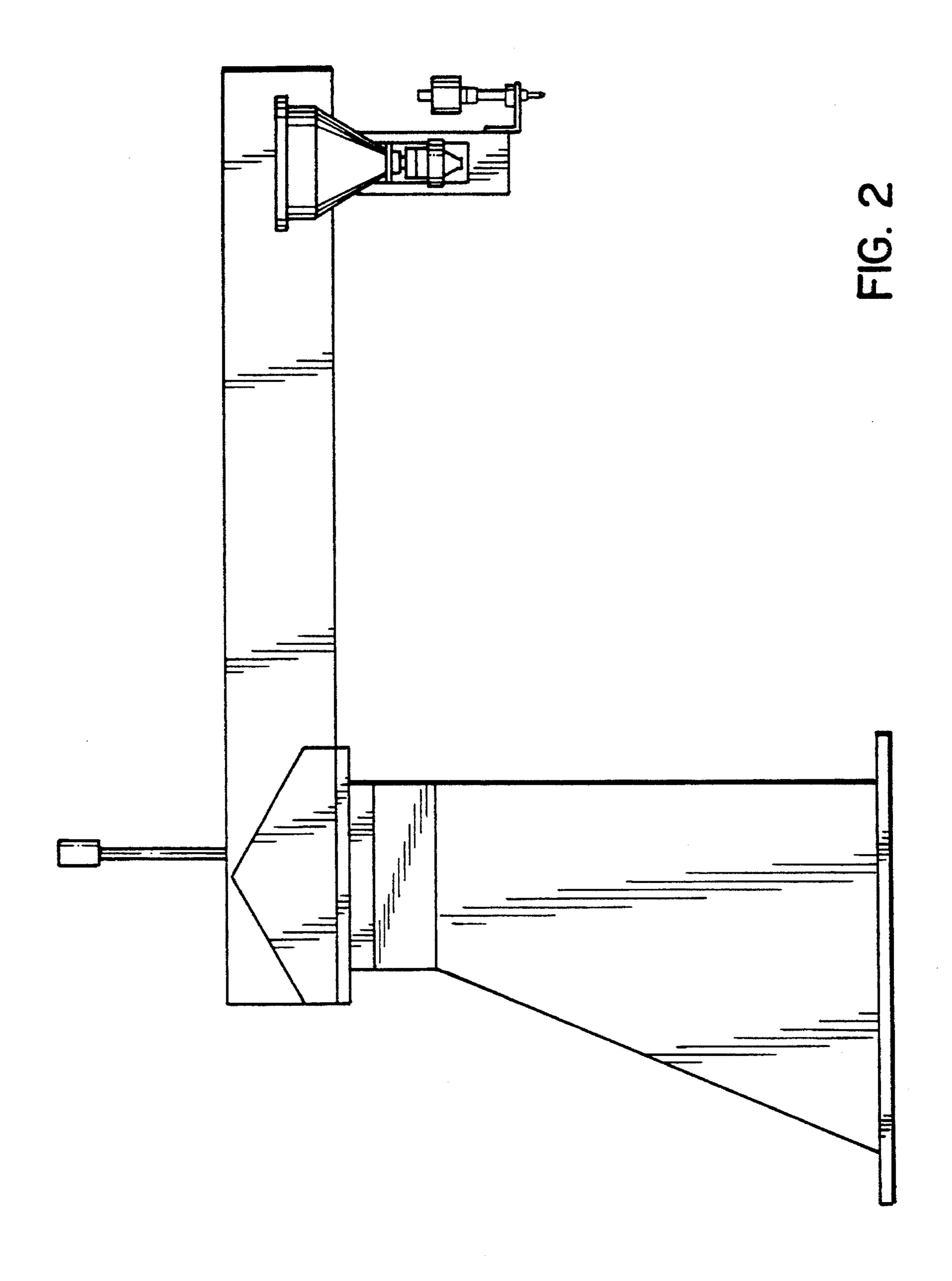
FIG. 6 is a front elevation view of the second embodiment; FIG. 7 is a perspective view as in FIG. 1 of the second embodiment wherein the X and Y arm assemblies have been rotated relative to the base about a vertical axis; and,

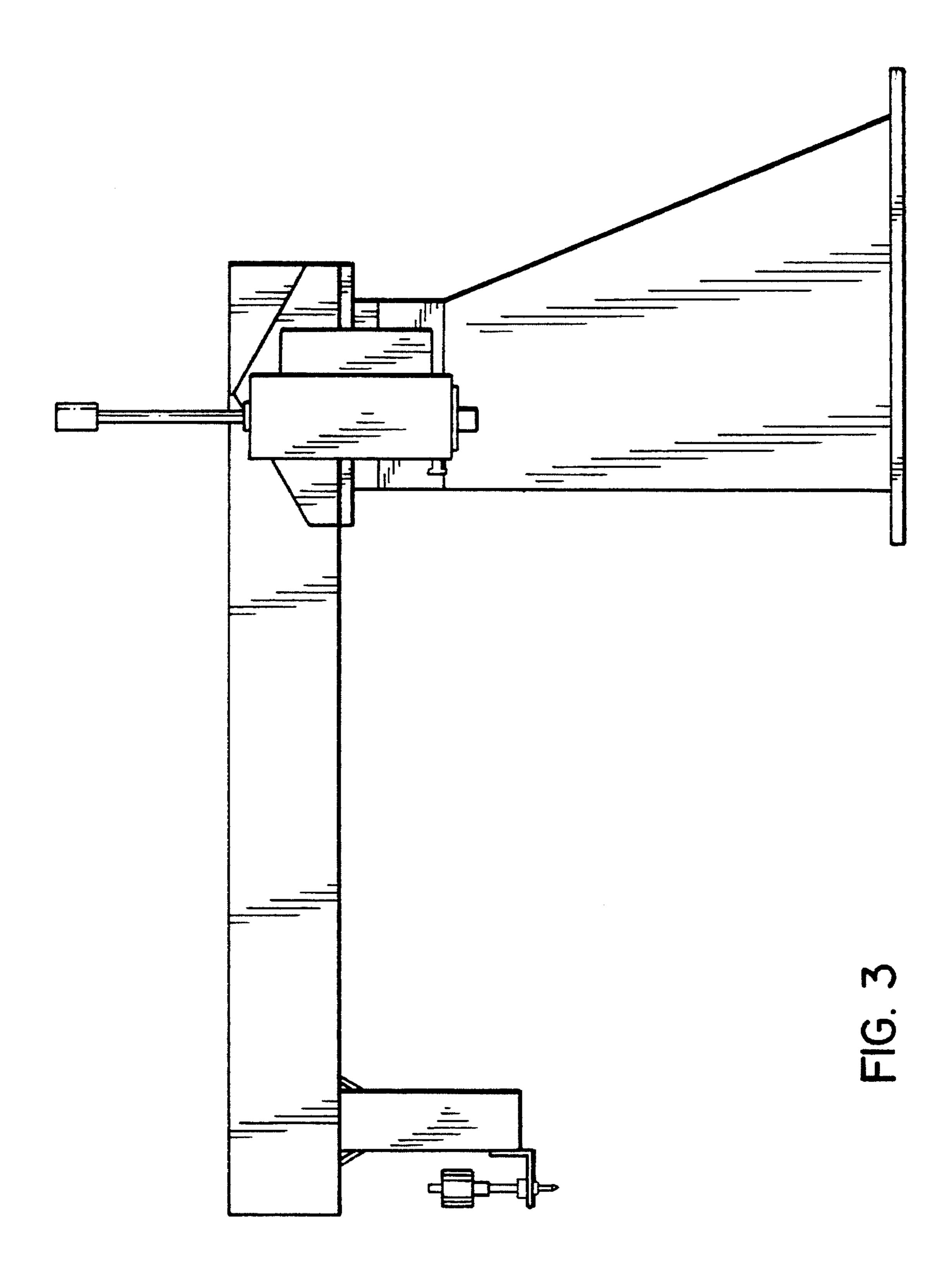
FIG. 8 is a perspective view as in FIG. 1 of a third embodiment of the design, the latter being essentially the same as the first embodiment except for the addition of a second Y axis arm assembly.

### 1 Claim, 8 Drawing Sheets

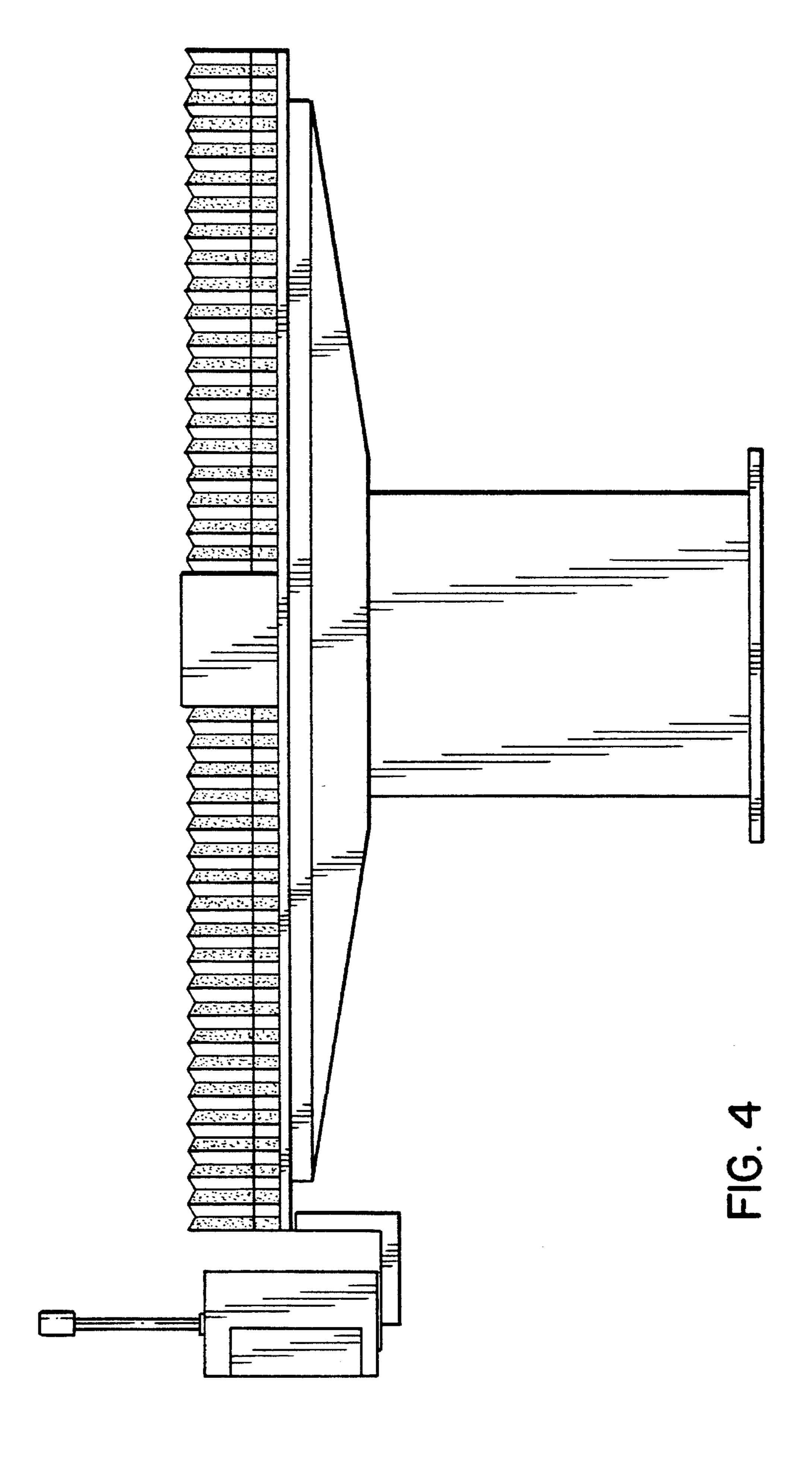


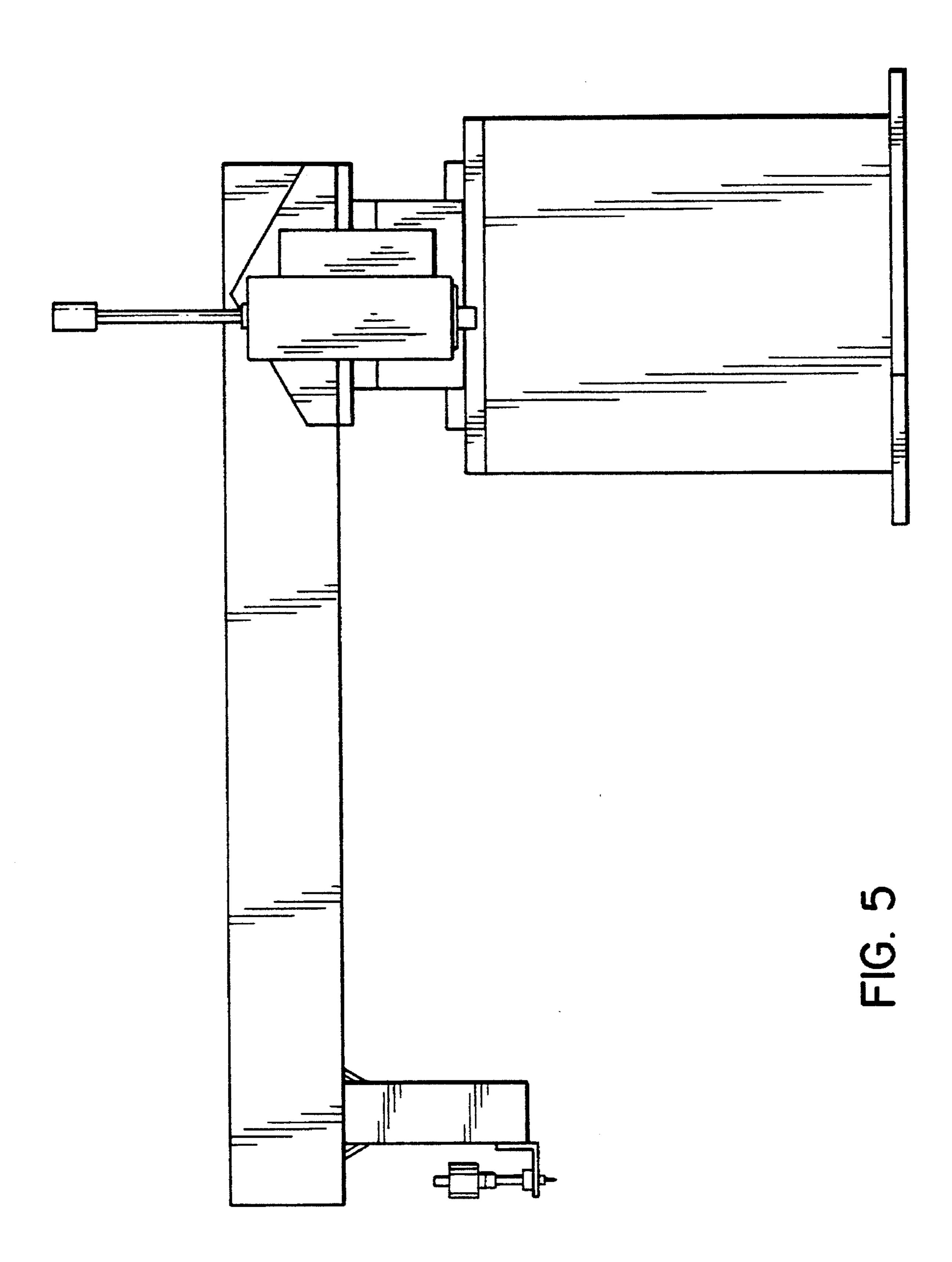




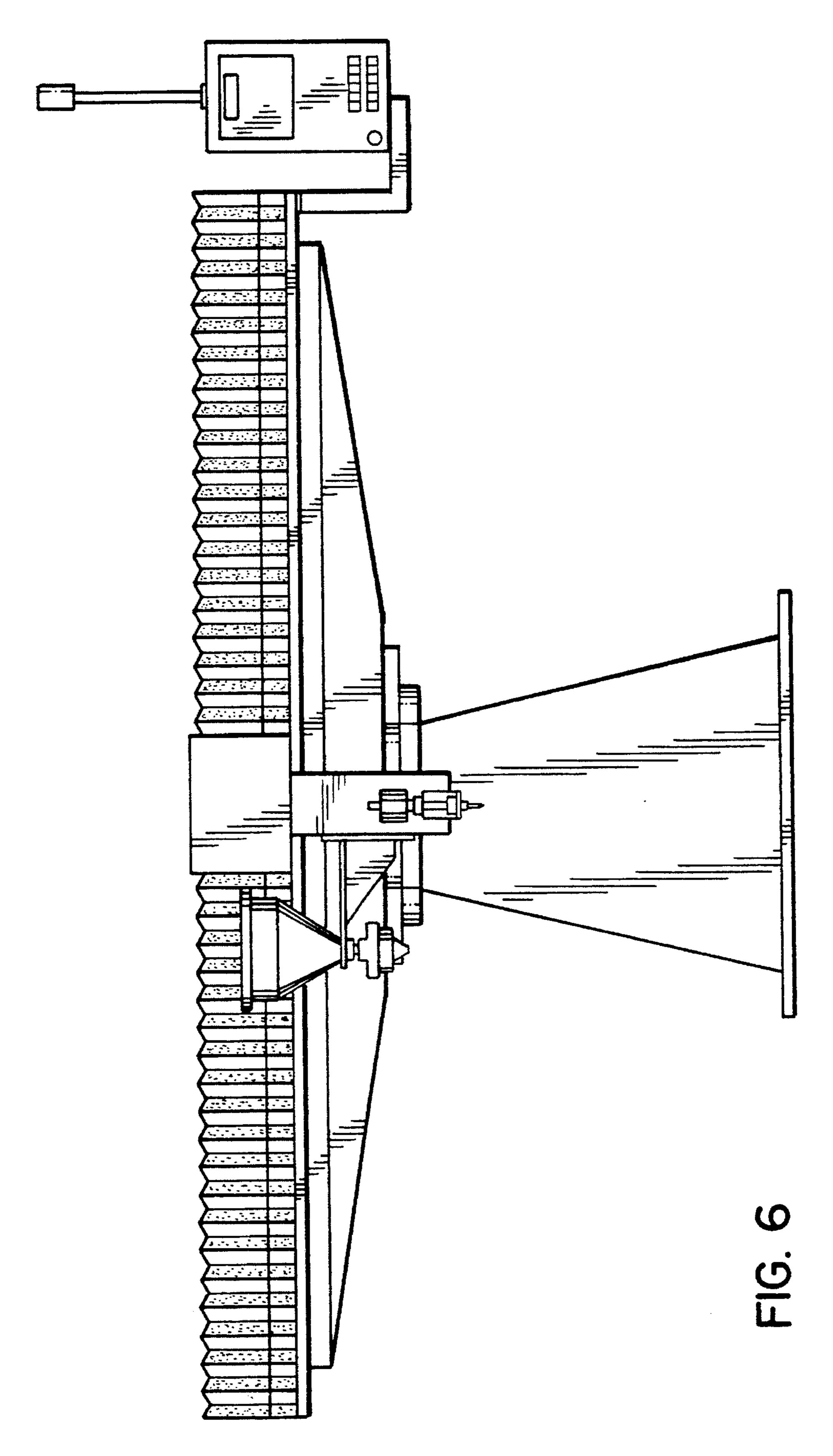


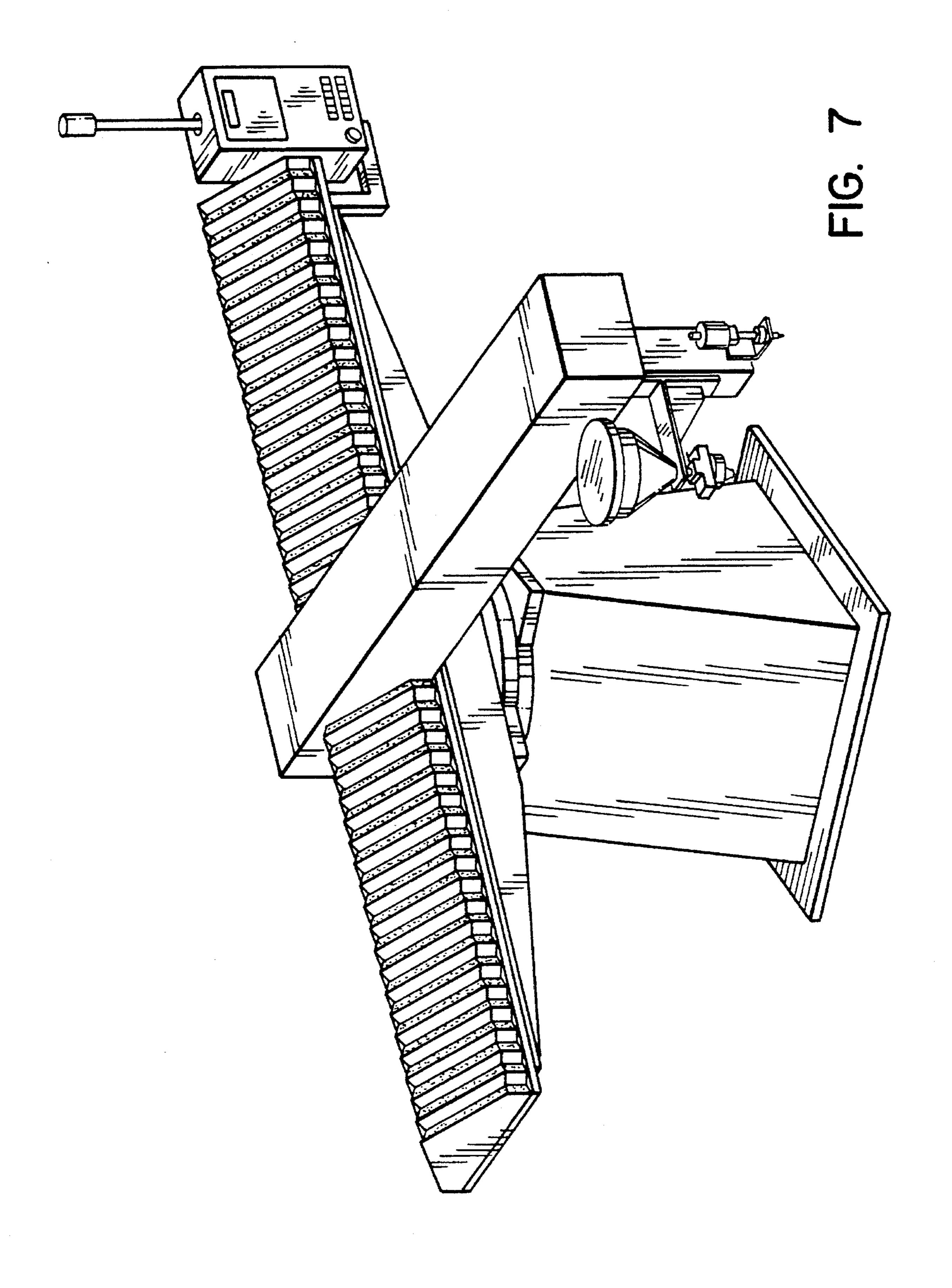
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