United States Patent [19]

Stackhouse

[11] **Des. 268,033**

[45] ** **Feb. 22, 1983**

[54] **ROBOT ARM**

[75] Inventor: **Theodore H. Stackhouse,** Cincinnati, Ohio

[73] Assignee: **Cincinnati Milacron Inc.,** Cincinnati, Ohio

[**] Term: **14 Years**

[21] Appl. No.: **218,505**

[22] Filed: **Dec. 22, 1980**

[51] **Int. Cl.** ..... **D15—99**
[52] **U.S. Cl.** **D15/199;** D15/122
[58] **Field of Search** D15/122, 199; 414/735, 414/737, 732

[56] **References Cited**

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SME Technical Paper MR76-603, "Application Flexibility of a Computer-Controlled Industrial Robot" by R. E. Hohn, ©1976, p. 5, Hydraulic Rotary Actuator.

Primary Examiner—B. J. Bullock
Attorney, Agent, or Firm—Thomas M. Farrell

[57] **CLAIM**

The ornamental design for a robot arm, as shown and described.

DESCRIPTION

FIG. **1** is a left, front perspective view of a robot arm showing my new design;
FIG. **2** is a right, front perspective view thereof;
FIG. **3** is a rear perspective view of FIG. **2;**
FIG. **4** is a rear perspective view of FIG. **1;**
FIG. **5** is a side elevational view taken from the left of FIG. **1;**
FIG. **6** is a side elevational view taken from the right of FIG. **1;**
FIG. **7** is a front elevational view thereof;
FIG. **8** is a rear elevational view thereof;
FIG. **9** is a top plan view thereof, the bottom being unornamented.

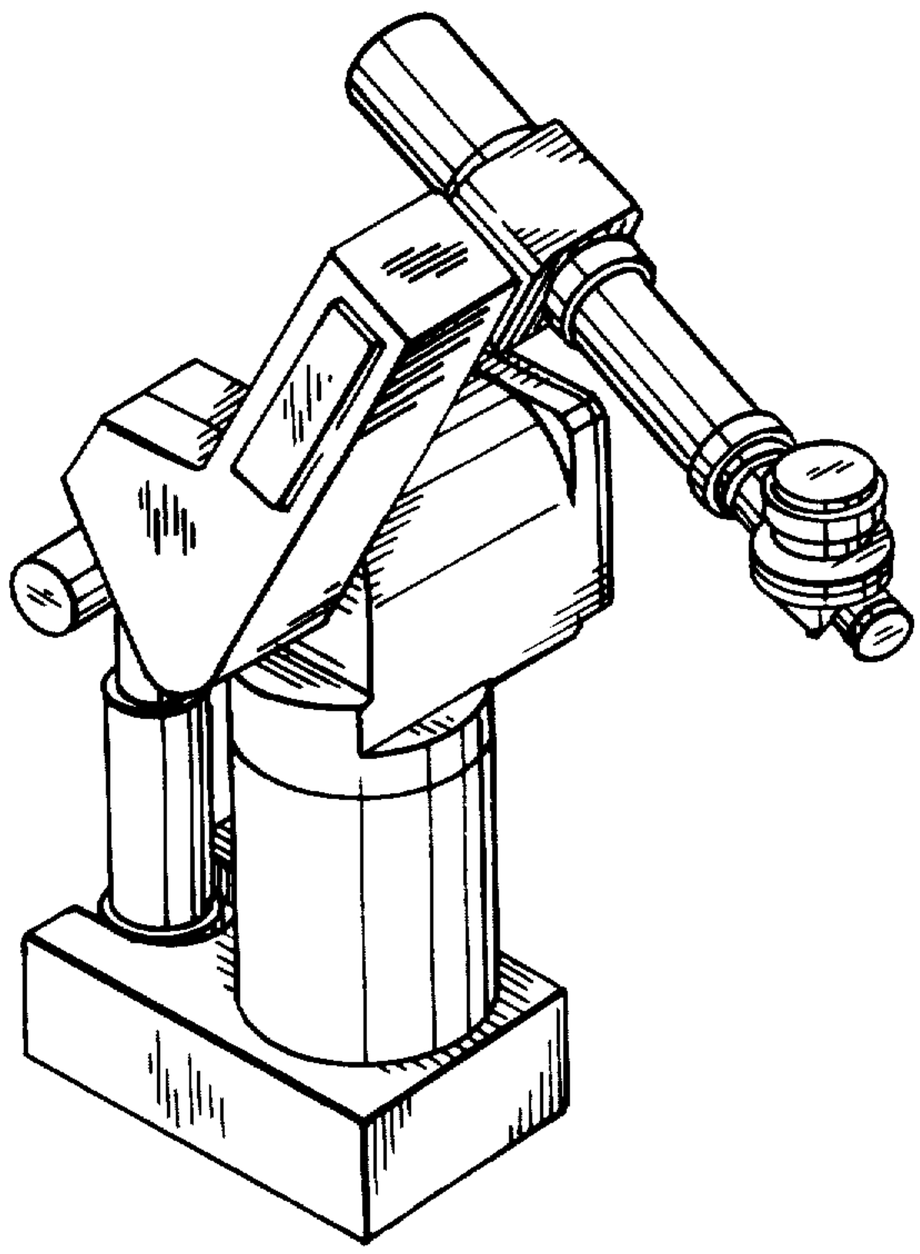

FIG-1

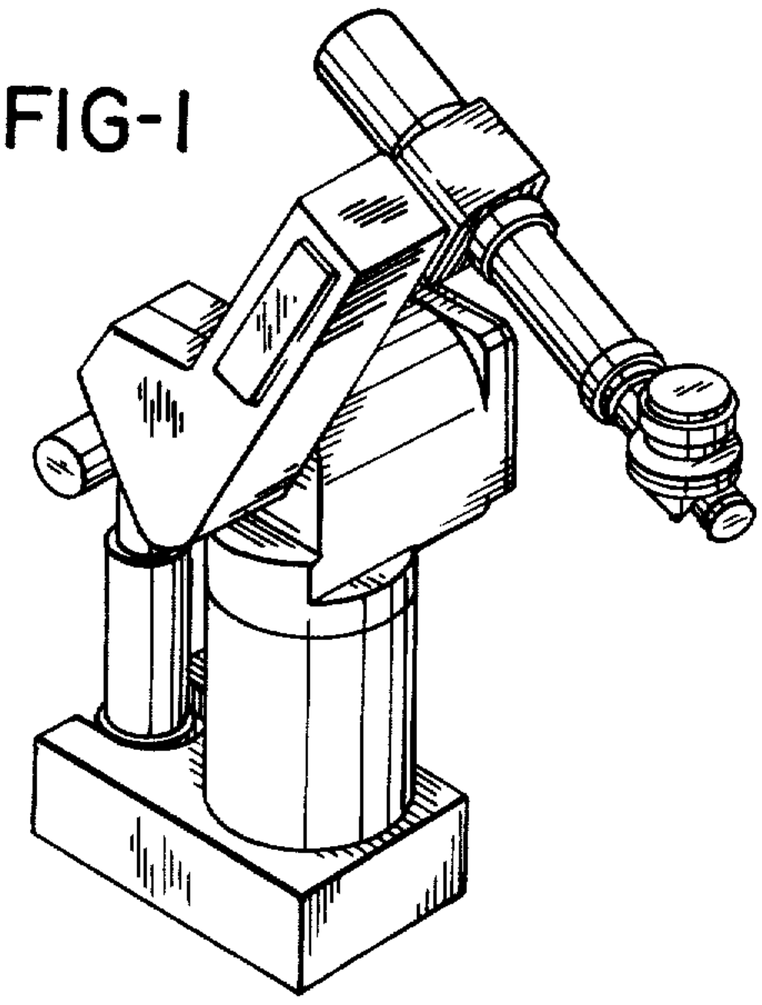

FIG-2

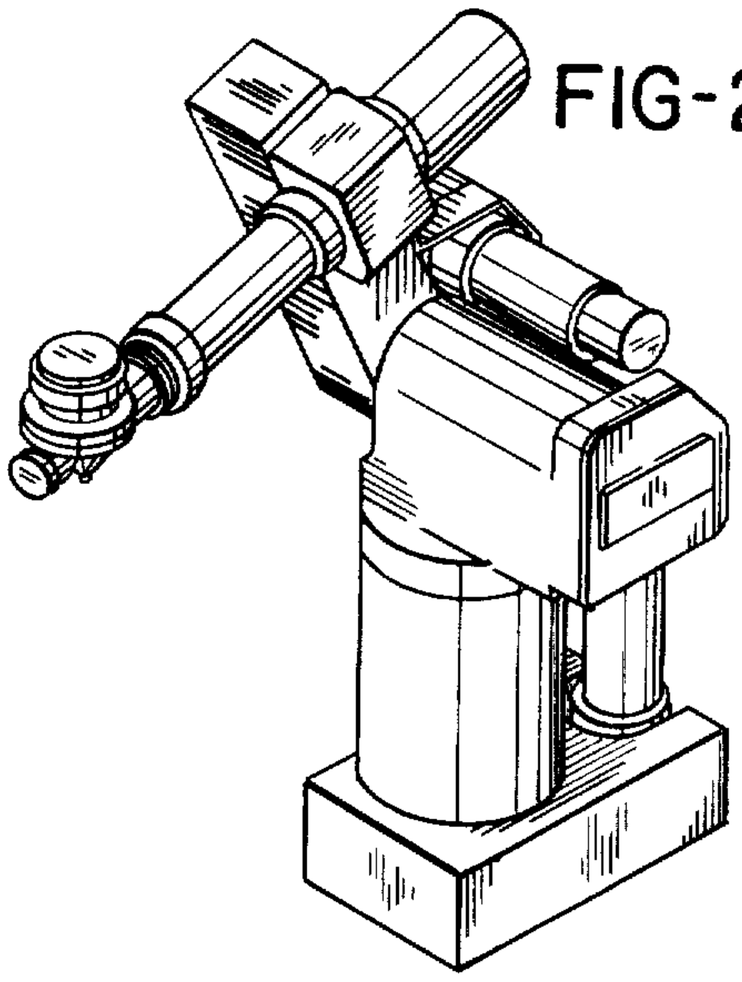

FIG-3

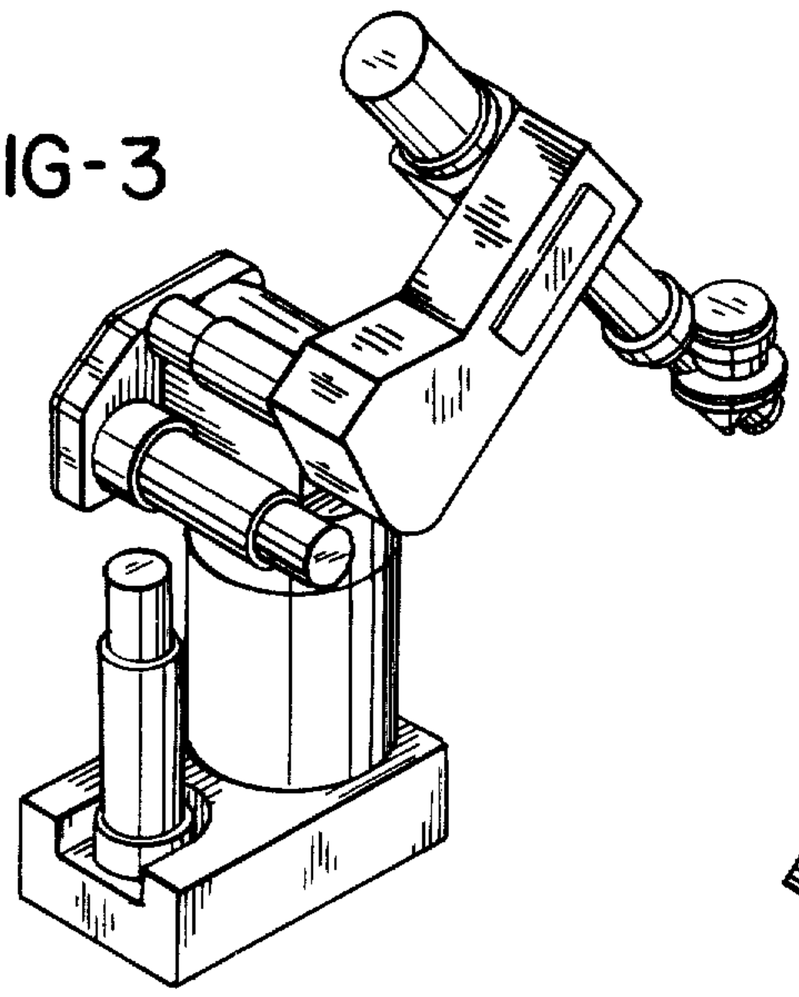

FIG-4

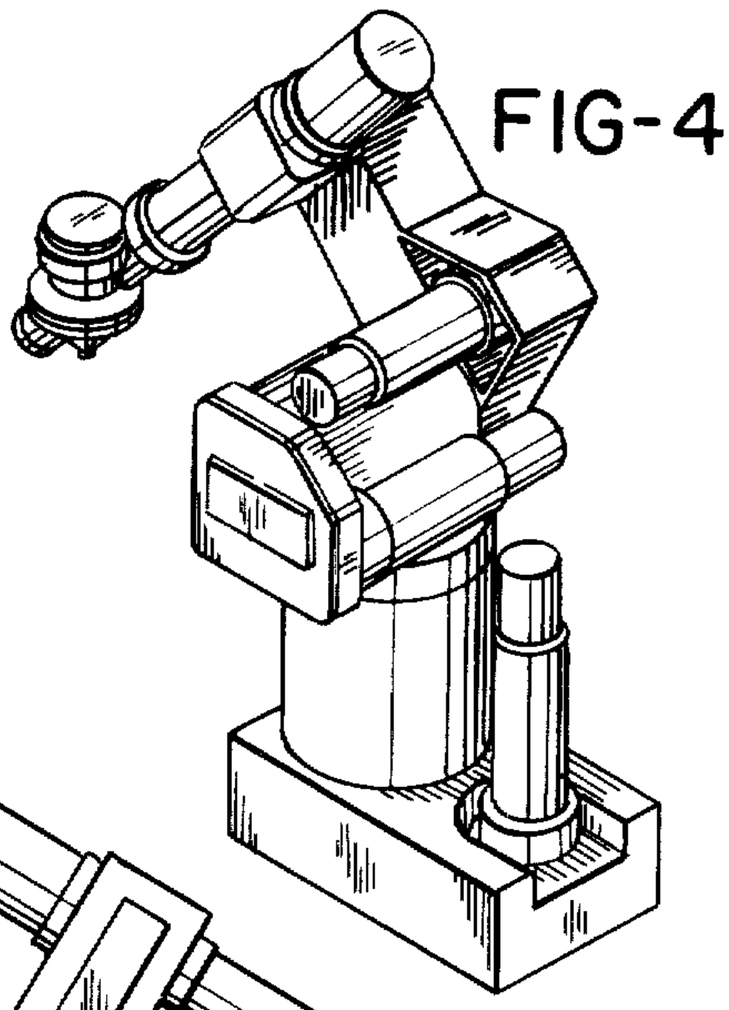

FIG-5

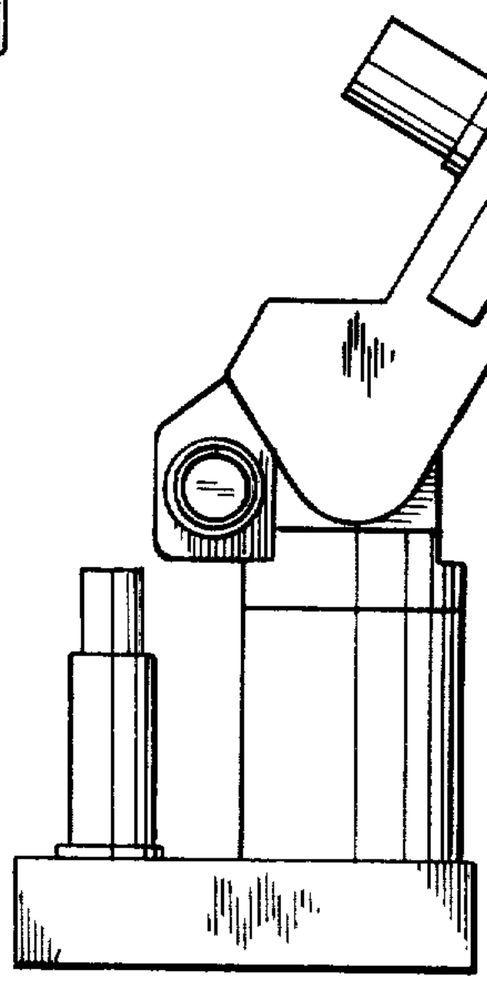

FIG-6

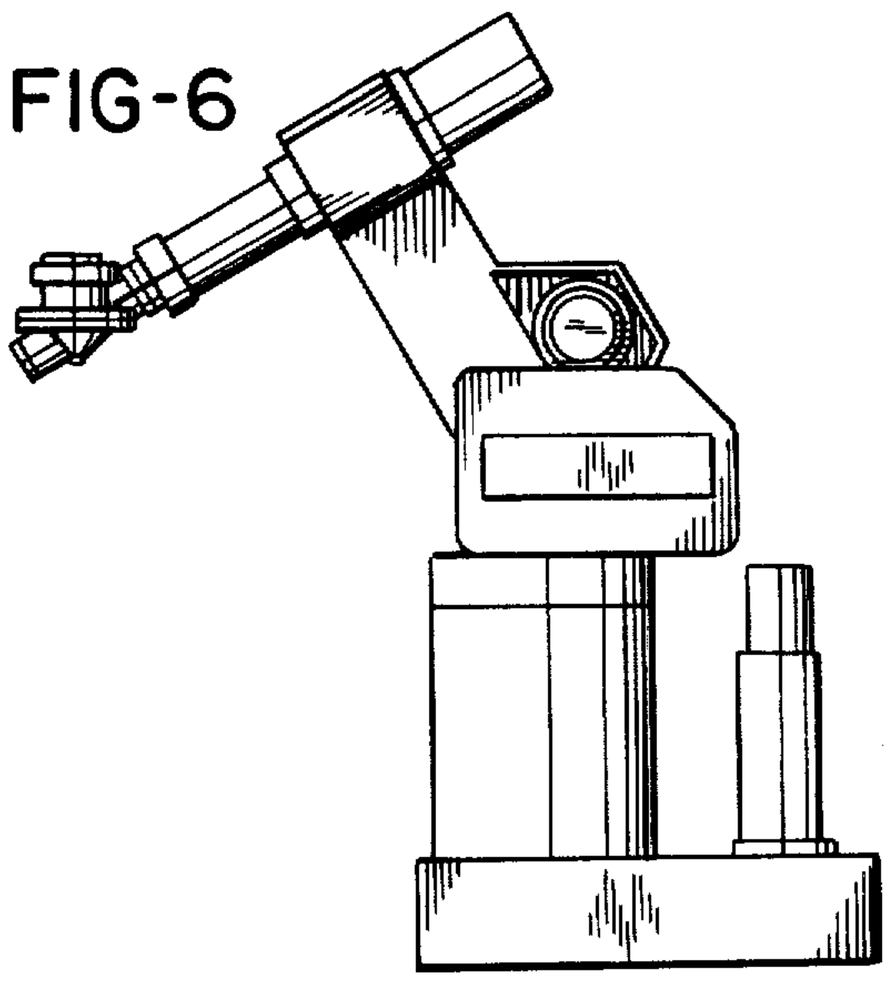

FIG-7

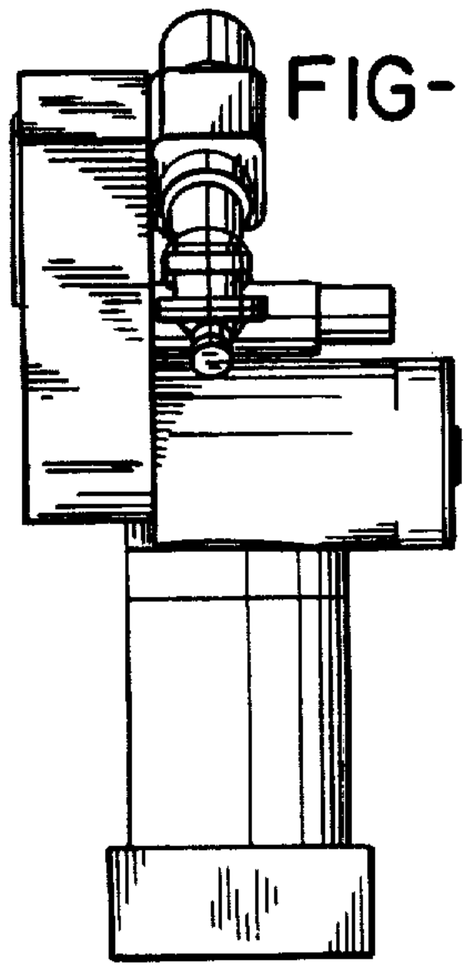

FIG-8

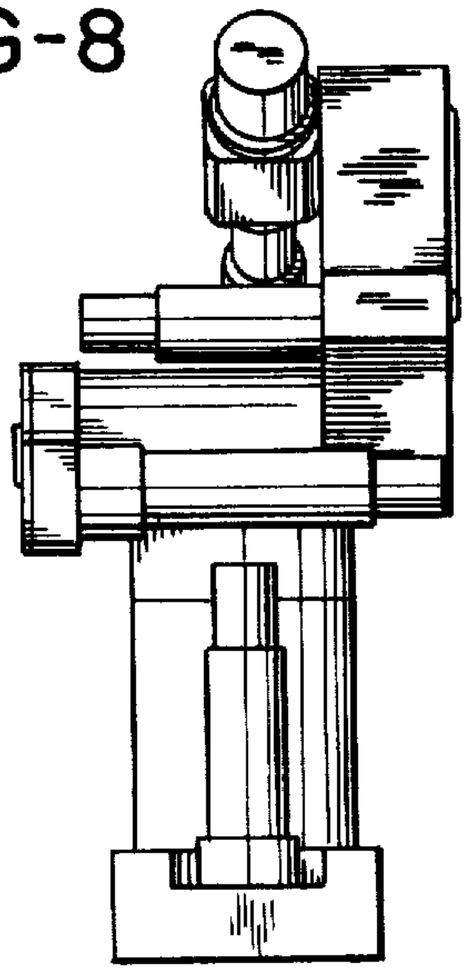

FIG-9