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**Laidig**

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(54) **DATA TUNING FOR FAST COMPUTATION AND POLYGONAL MANIPULATION SIMPLIFICATION**

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*G06T 7/64* (2017.01)  
*G06T 9/20* (2006.01)  
*G03F 7/20* (2006.01)  
*G06T 17/20* (2006.01)

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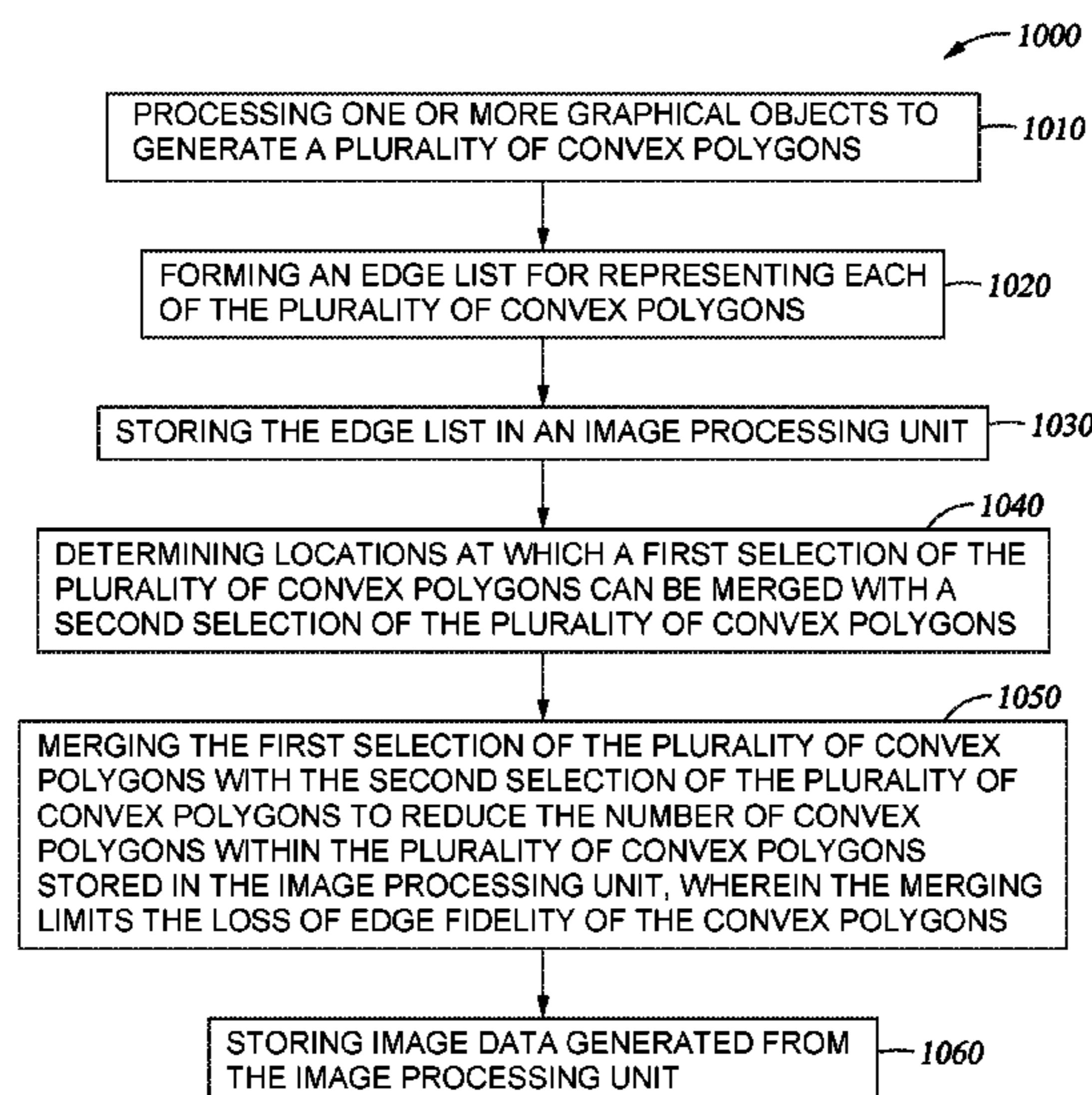
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CPC .... *G06T 1/20*; *G06T 7/64*; *G06T 7/70*; *G06T 11/40*; *G06T 11/203*; *G06T 17/20*; *G06T 9/20*; *G03F 7/70*; *G03F 7/70008*; *G03F 7/70058*; *G03F 7/70075*; *G03F 7/70091*; *G03F 7/70125*; *G03F 7/70216*; *G03F 7/70275*; *G03F 7/70283*; *G03F 7/70291*; *G03F 7/70508*  
See application file for complete search history.

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(57) **ABSTRACT**  
A data tuning software application platform relating to the ability to apply maskless lithography patterns to a substrate in a manufacturing process is disclosed in which the application processes graphical objects and configures the graphical objects for partition into a plurality of trapezoids. The trapezoids may be selectively merged in order to minimize the trapezoid count while limiting the loss of edge fidelity.

**21 Claims, 10 Drawing Sheets**



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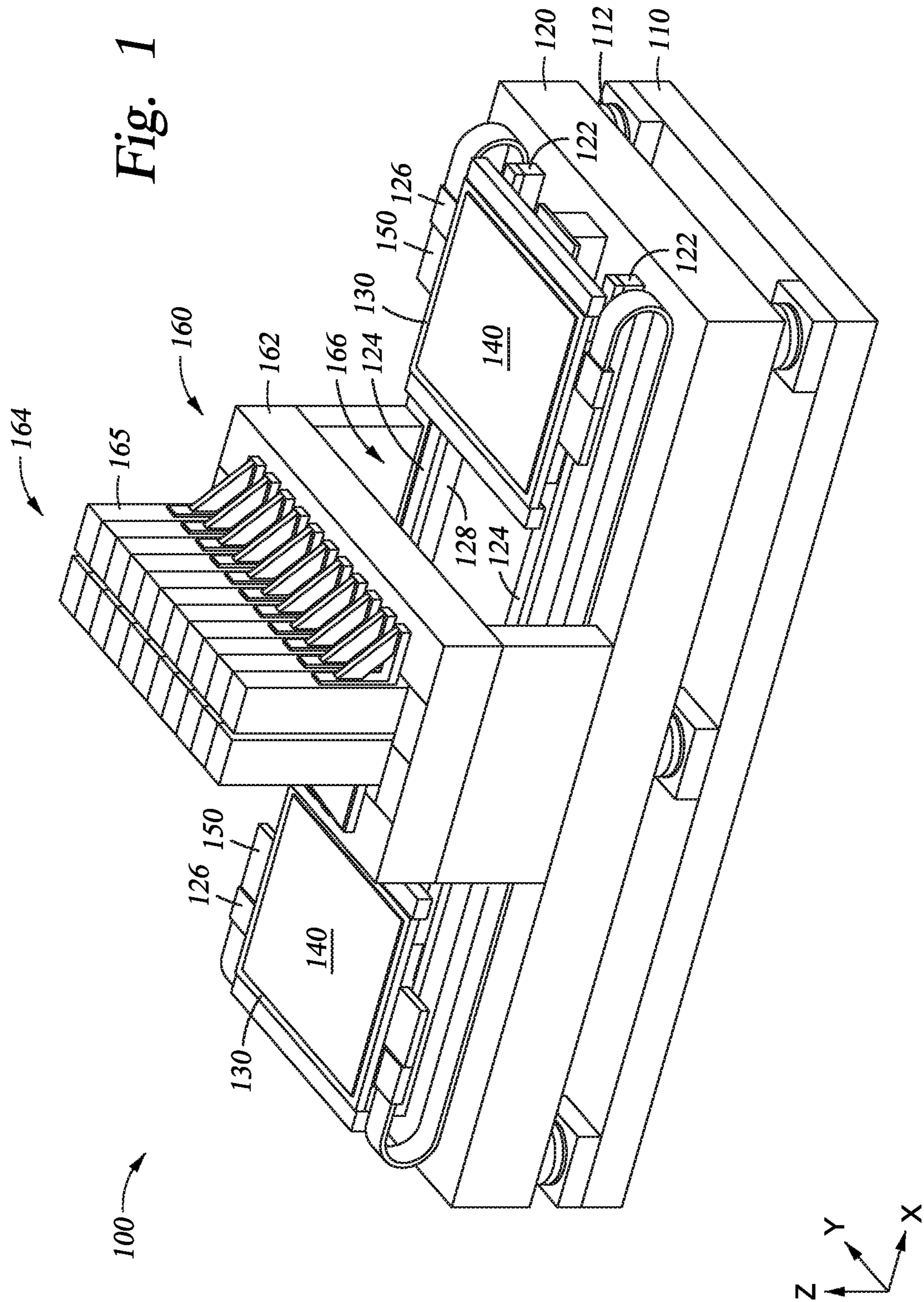
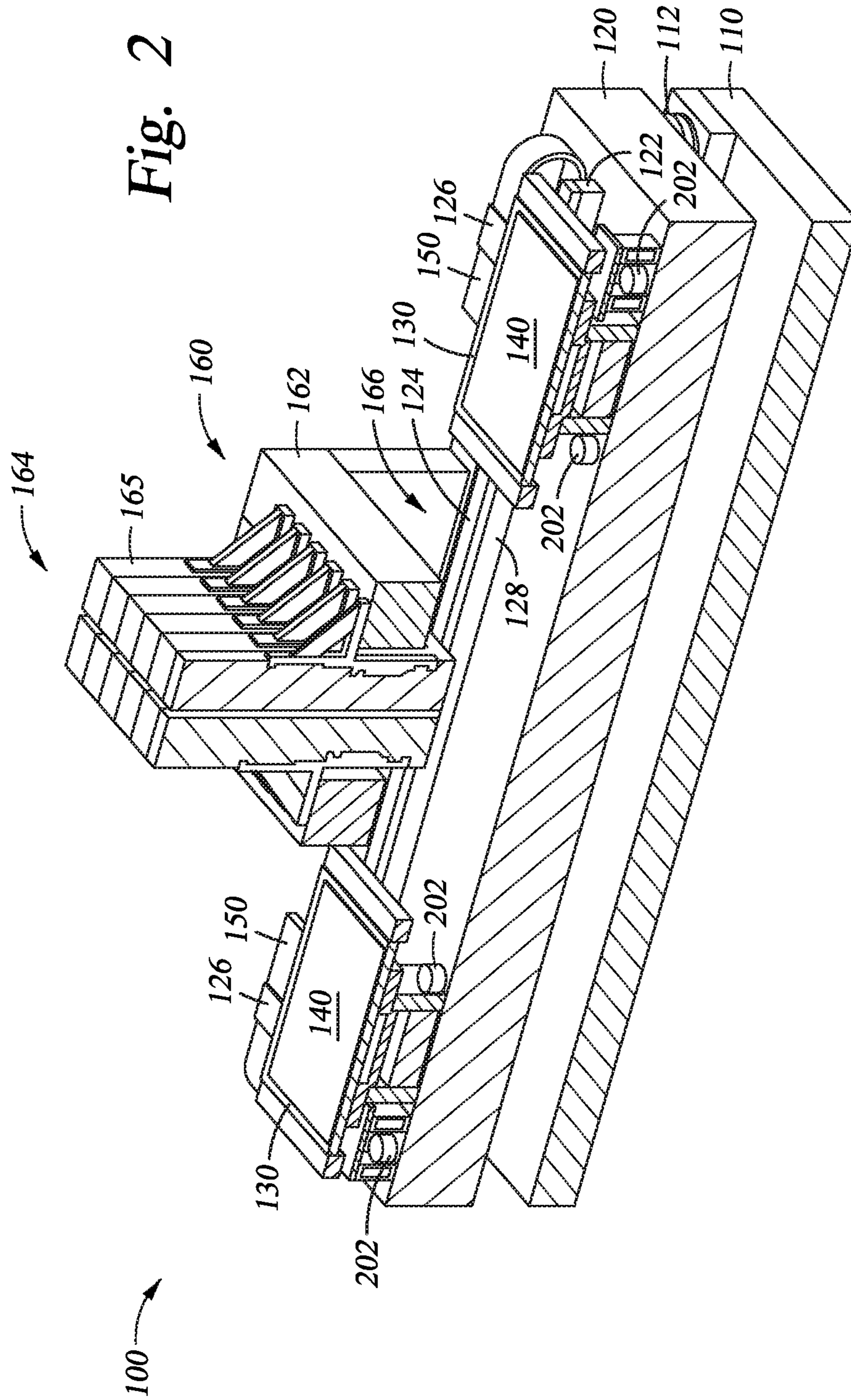




Fig. 2



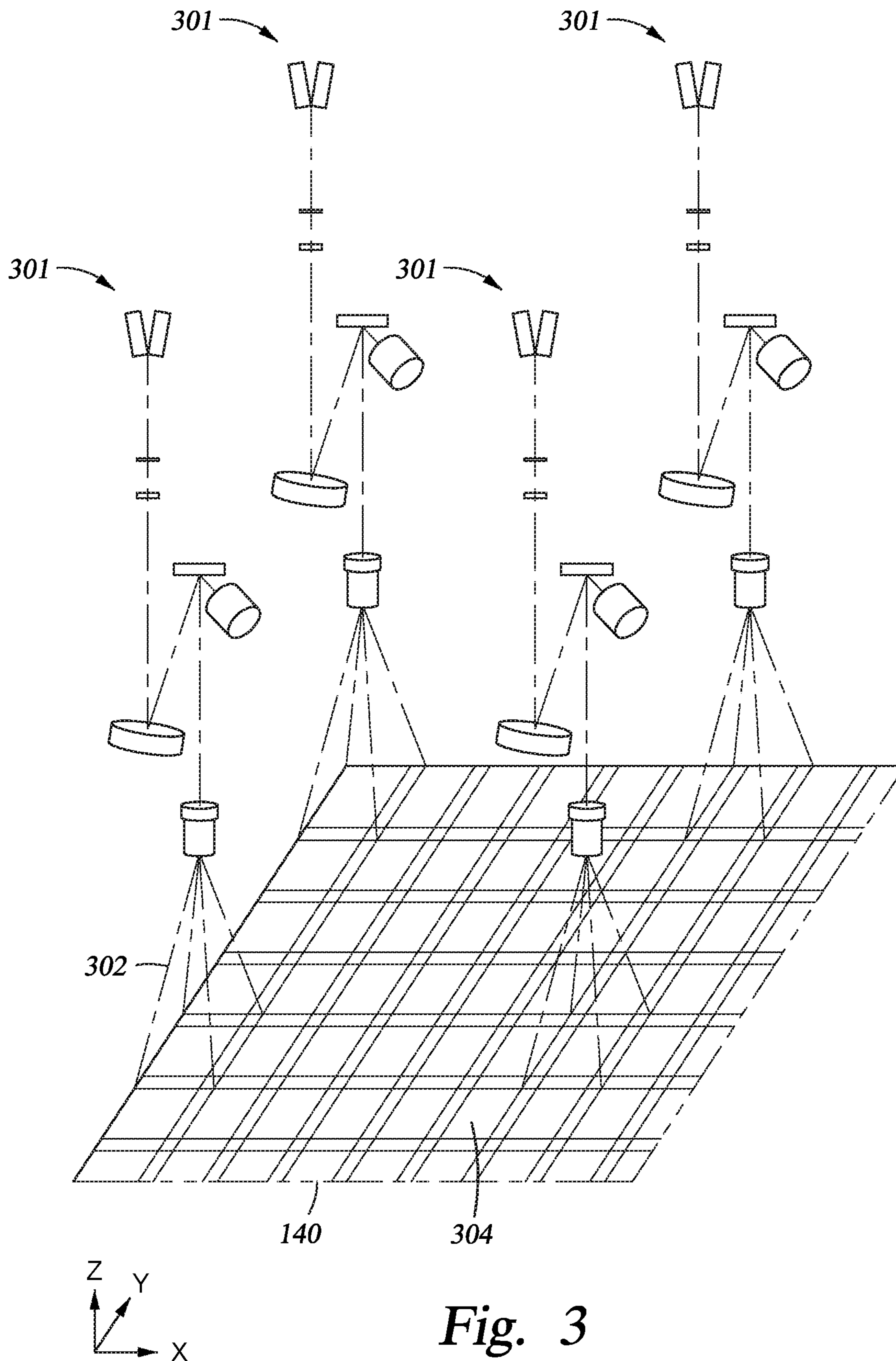


Fig. 3

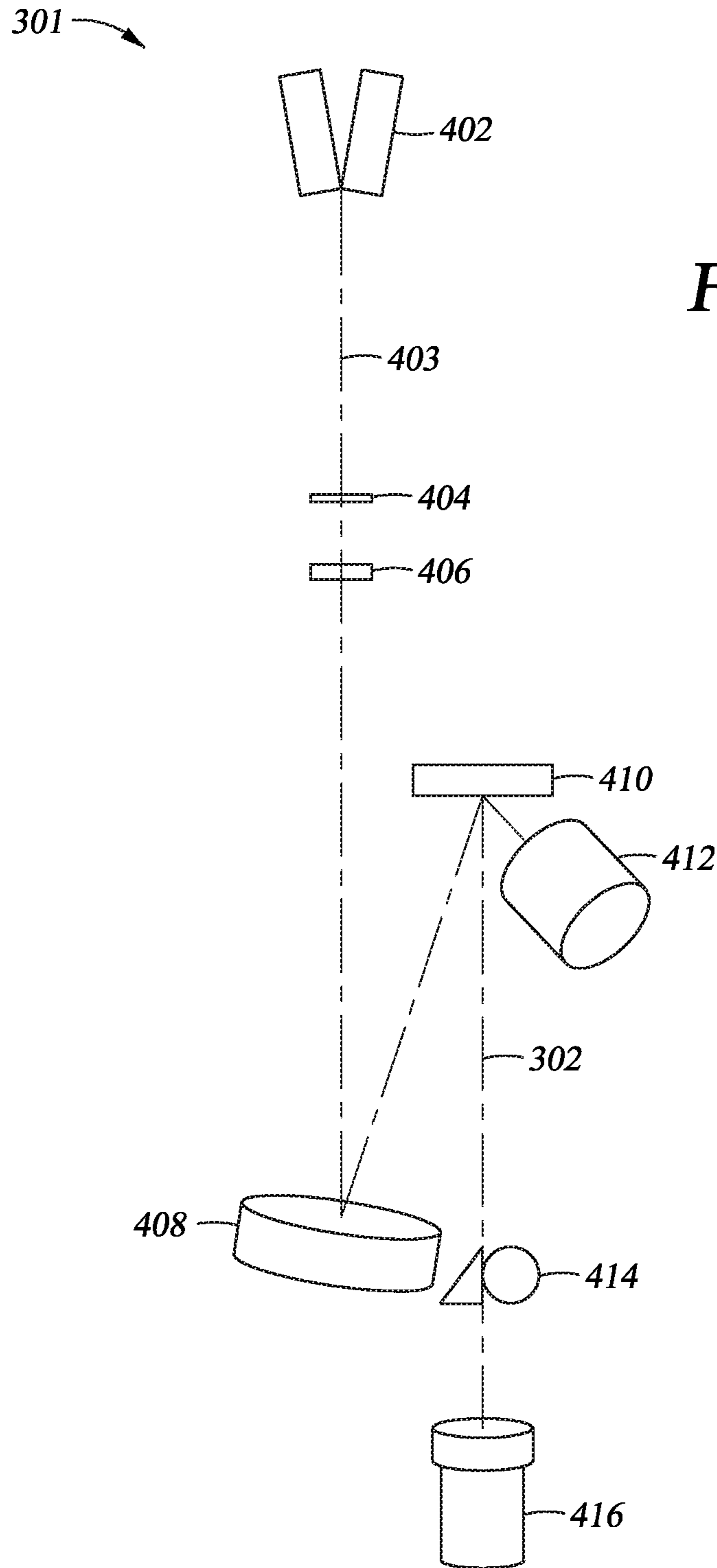


Fig. 4

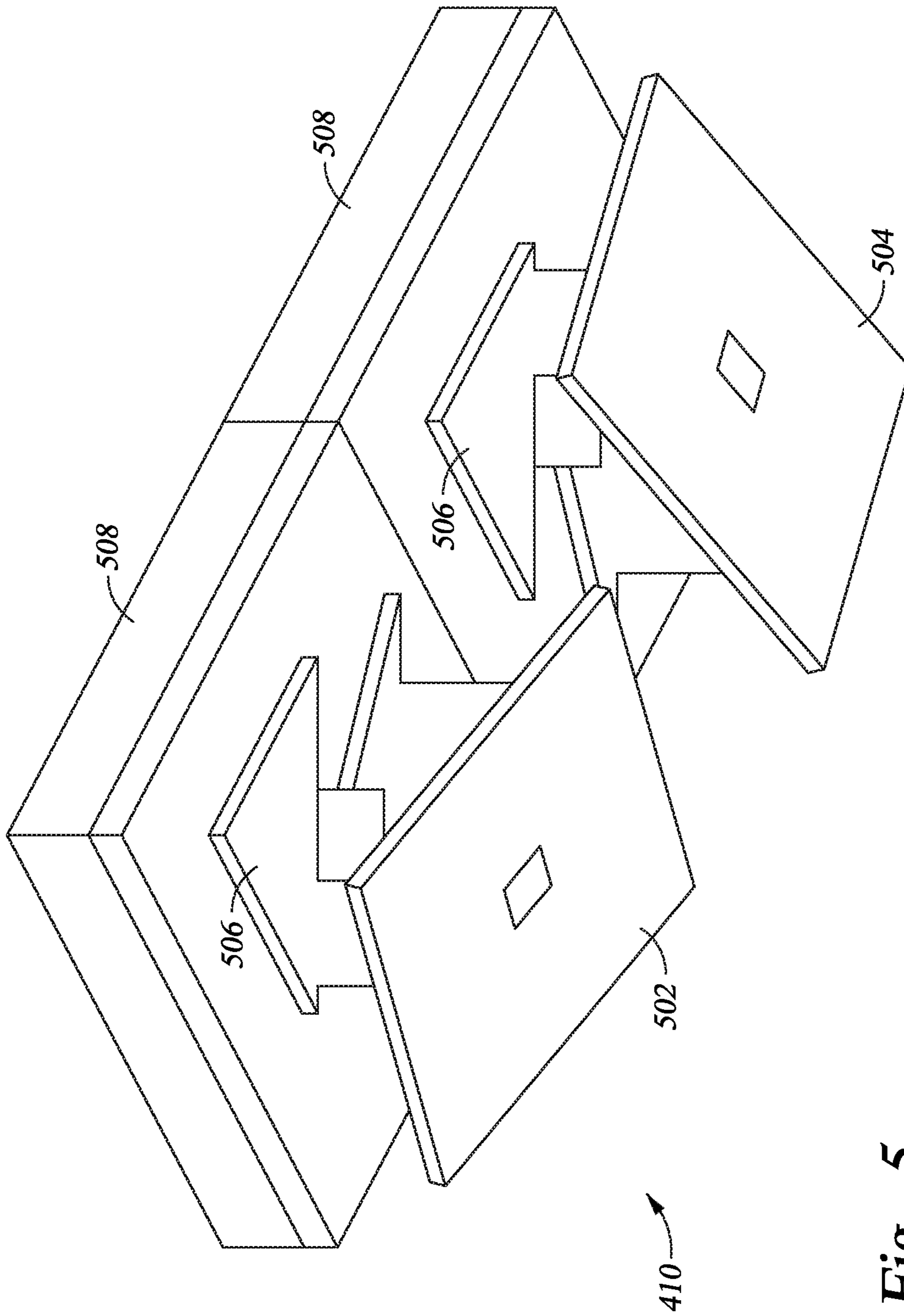
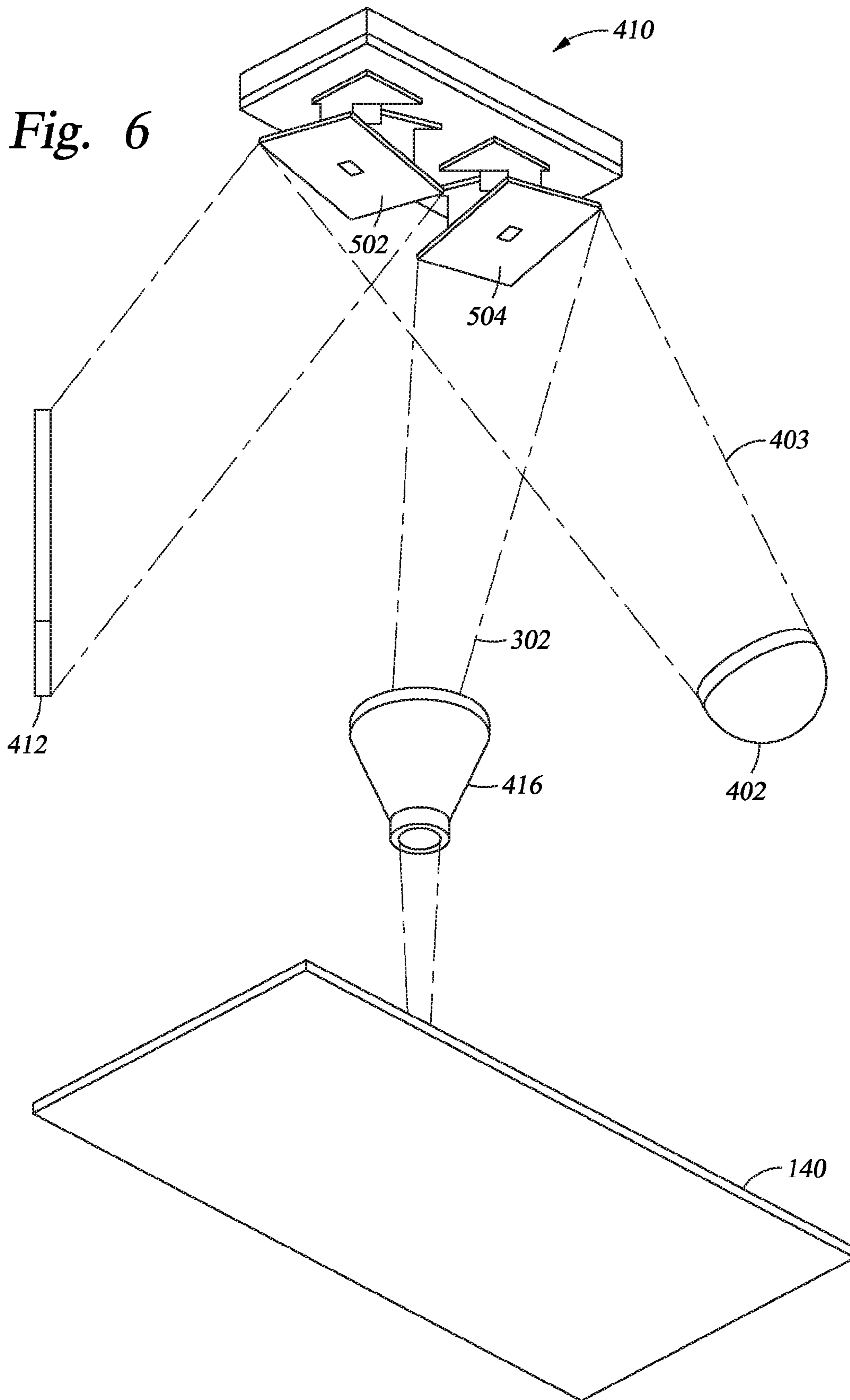


Fig. 5







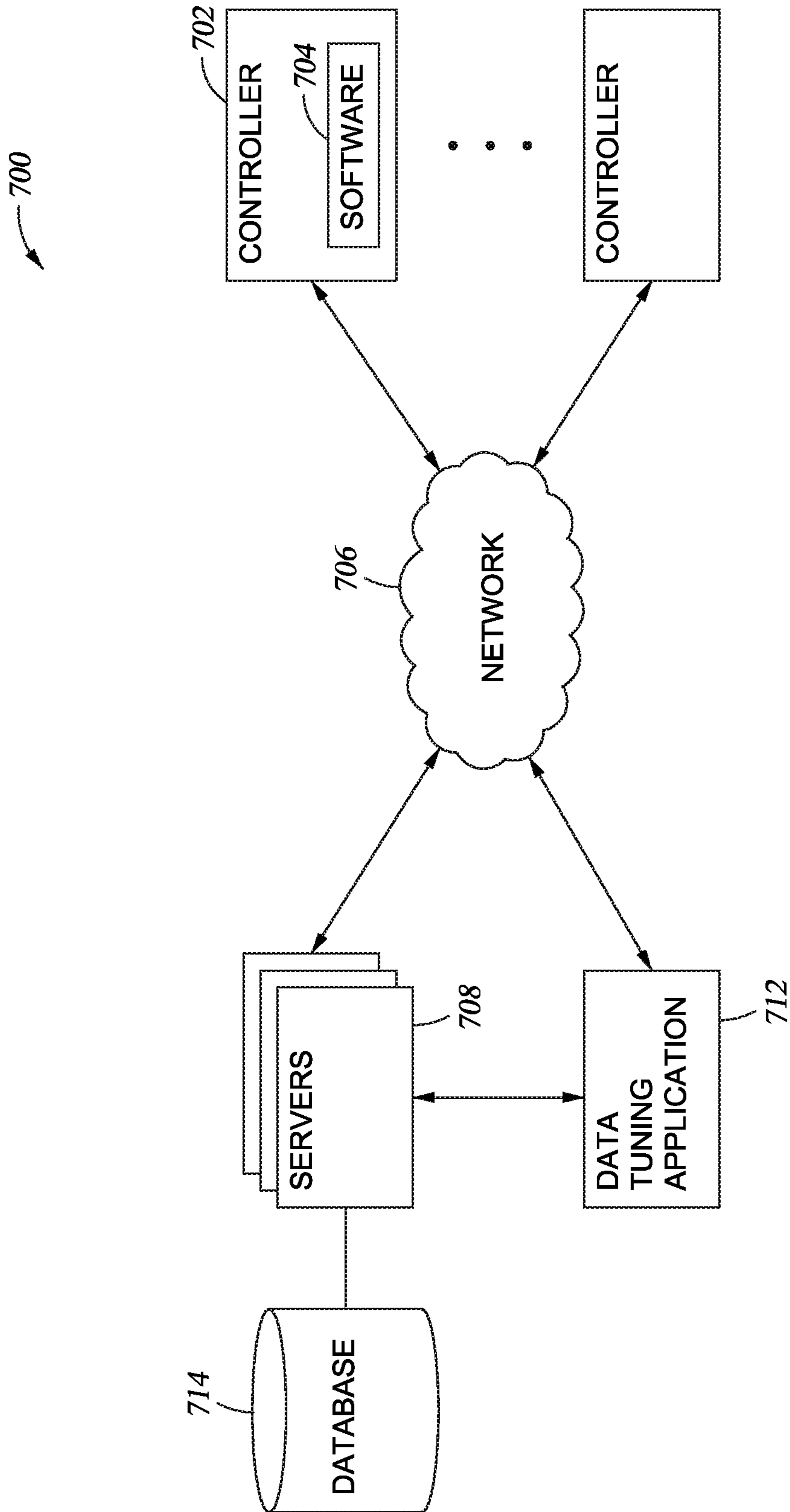


Fig. 7

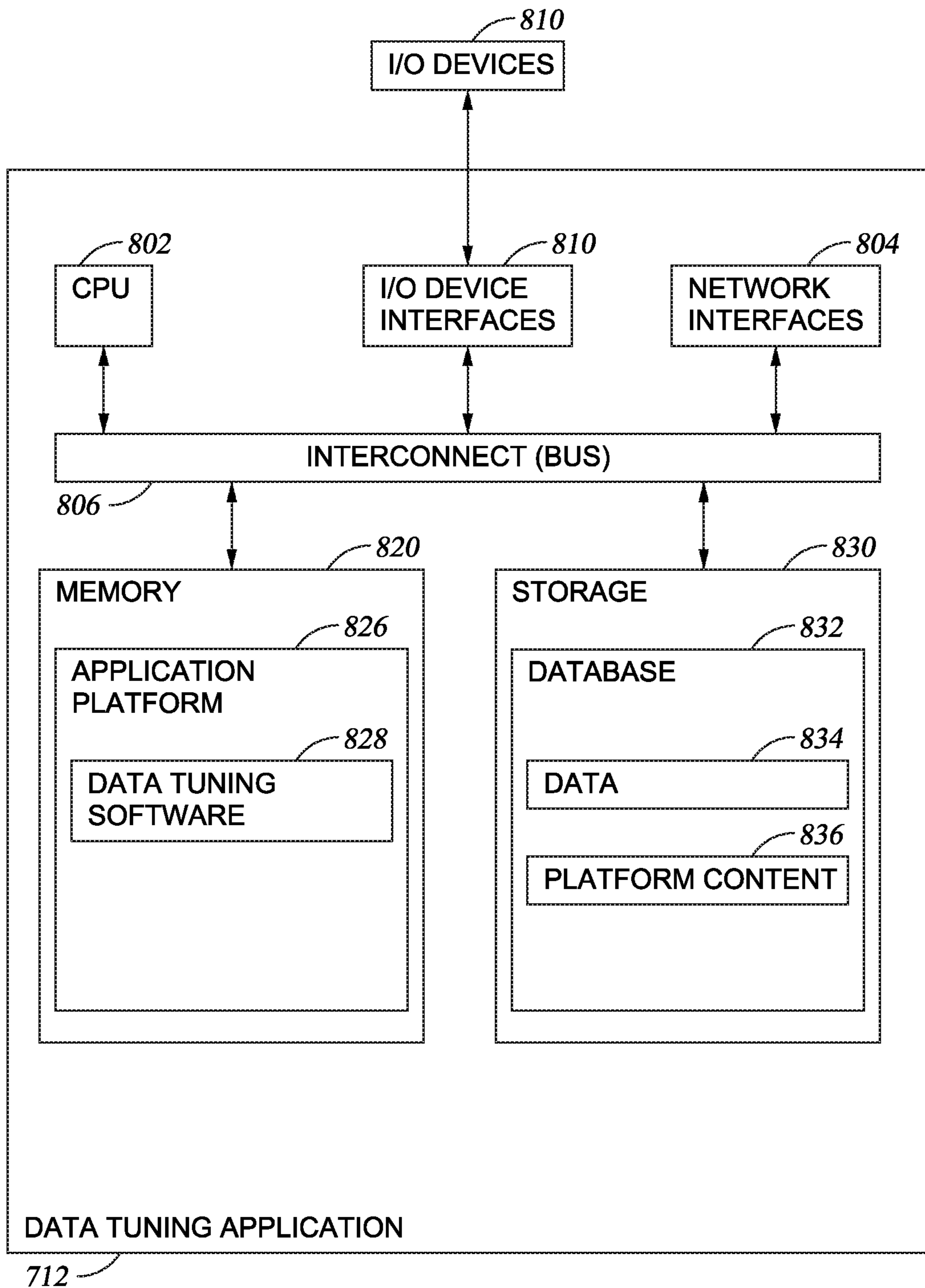


Fig. 8

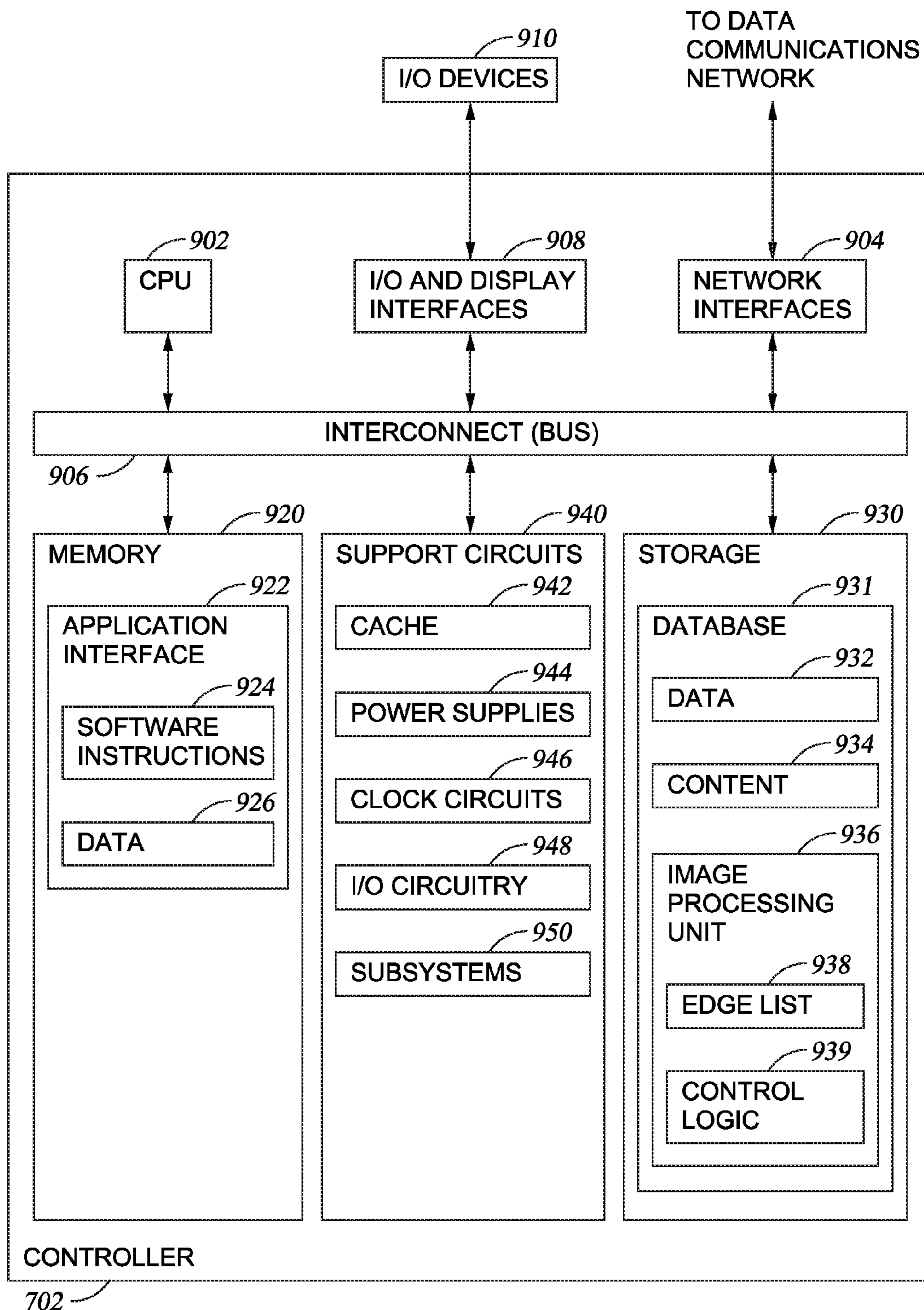
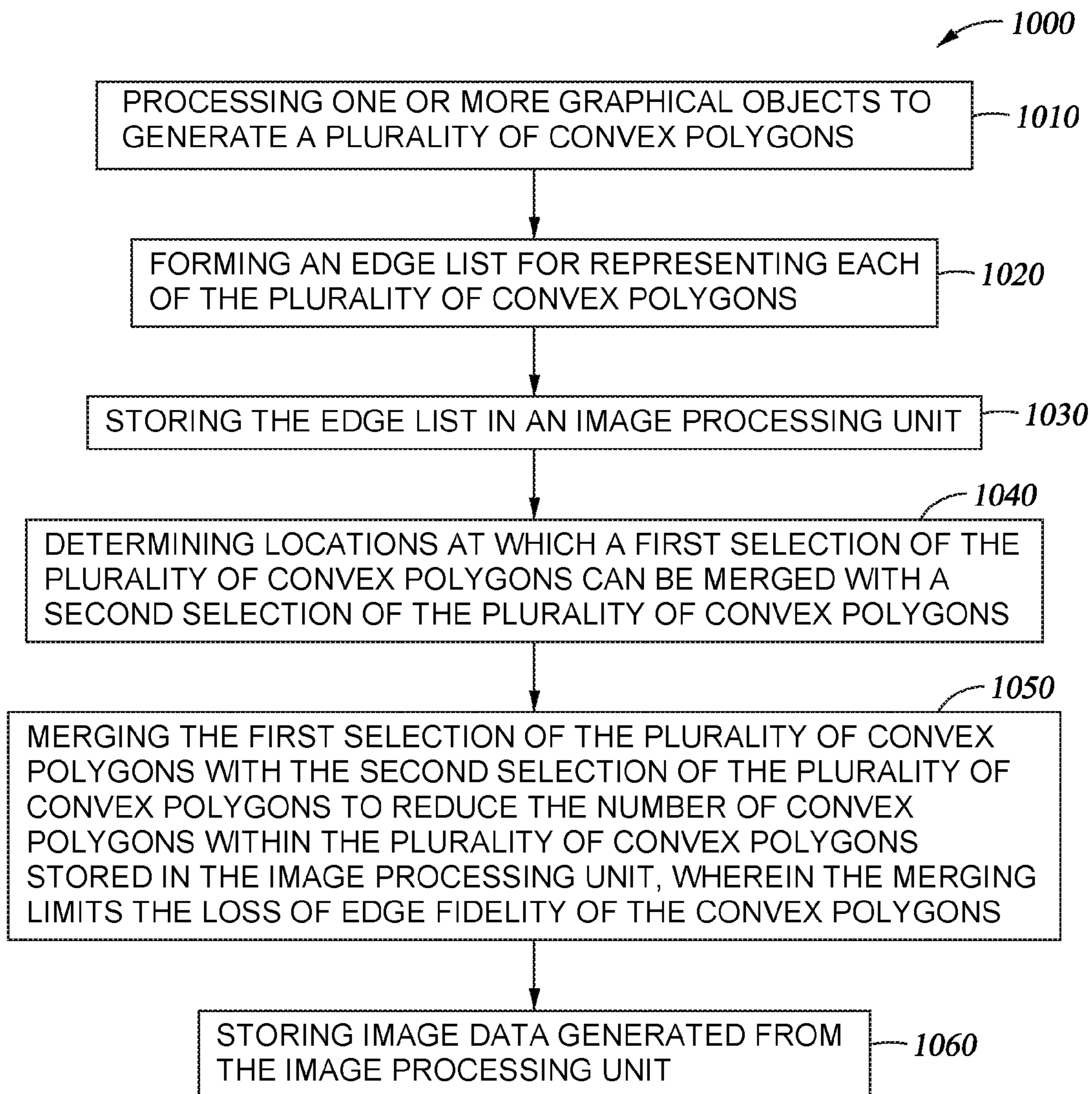


Fig. 9

*Fig. 10*



1

**DATA TUNING FOR FAST COMPUTATION  
AND POLYGONAL MANIPULATION  
SIMPLIFICATION**

CROSS-REFERENCE TO RELATED  
APPLICATIONS

This application claims benefit of U.S. Provisional Patent Application Ser. No. 62/137,782 filed Mar. 24, 2015, which is incorporated by reference herein.

BACKGROUND

Field

Embodiments of the present disclosure generally relate to the field of maskless lithography. More specifically, embodiments provided herein relate to a system and method for performing maskless digital lithography manufacturing processes.

Description of the Related Art

Photolithography is widely used in the manufacturing of semiconductor devices and display devices, such as liquid crystal displays (LCDs). Large area substrates are often utilized in the manufacture of LCDs. LCDs, or flat panels, are commonly used for active matrix displays, such as computers, touch panel devices, personal digital assistants (PDAs), cell phones, television monitors, and the like. Generally, flat panels may include a layer of liquid crystal material forming pixels sandwiched between two plates. When power from the power supply is applied across the liquid crystal material, an amount of light passing through the liquid crystal material may be controlled at pixel locations enabling images to be generated.

Microolithography techniques are generally employed to create electrical features incorporated as part of the liquid crystal material layer forming the pixels. According to this technique, a light-sensitive photoresist is typically applied to at least one surface of the substrate. Then, a pattern generator exposes selected areas of the light-sensitive photoresist as part of a pattern with light to cause chemical changes to the photoresist in the selective areas to prepare these selective areas for subsequent material removal and/or material addition processes to create the electrical features.

In order to continue to provide display devices and other devices to consumers at the prices demanded by consumers, new apparatuses, approaches, and systems are needed to precisely and cost-effectively create patterns on substrates, such as large area substrates.

As the foregoing illustrates, there is a need for an improved technique for data tuning for fast computation and polygonal manipulation simplification within digital lithography. More specifically, what is needed in the art is a data tuning application which selectively merges convex polygons to minimize the polygon count while limiting the loss of edge fidelity.

SUMMARY

The present disclosure generally relates to a data tuning software application platform which maintains the ability to apply maskless lithography patterns to a substrate in a manufacturing process. The application processes graphical objects and configures the graphical objects for partition into a plurality of trapezoids. The trapezoids may be selectively merged in order to minimize the trapezoid count while limiting the loss of edge fidelity. In one embodiment, a method for tuning data for parallel image processing is

2

disclosed. The method includes processing one or more graphical objects to generate a plurality of convex polygons, forming an edge list for representing each of the plurality of convex polygons, and storing the edge list in an image processing unit. The method further includes determining locations at which a first selection of the plurality of convex polygons can be merged with a second selection of the plurality of convex polygons, merging a first selection of the plurality of convex polygons with a second selection of the plurality of convex polygons to reduce the number of convex polygons within the plurality of convex polygons stored in the image processing unit, wherein the merging limits the loss of edge fidelity of the convex polygons, and storing image data generated from the image processing unit.

In another embodiment, a computer system for performing data tuning for parallel image processing is disclosed. The computer system for performing parallel image processing may include a processor and a memory storing instructions that, when executed by the processor, cause the computer system to process one or more graphical objects to generate a plurality of convex polygons, form an edge list for representing each of the plurality of convex polygons, and store the edge list in an image processing unit. The memory may also store instructions that, when executed by the processor, cause the computer system to determine locations at which a first selection of the plurality of convex polygons can be merged with a second selection of the plurality of convex polygons, merge a first selection of the plurality of convex polygons with a second selection of the plurality of convex polygons to reduce the number of convex polygons within the plurality of convex polygons stored in the image processing unit, wherein the merging limits the loss of edge fidelity of the convex polygons, and store image data generated from the image processing unit.

In yet another embodiment, a non-transitory computer-readable medium, storing instructions that, when executed by a processor, cause a computer system to tune data for parallel image processing is disclosed. The processor may perform the steps of processing one or more graphical objects to generate a plurality of convex polygons, forming an edge list for representing each of the plurality of convex polygons, and storing the edge list in an image processing unit. The processor may also perform the steps of determining locations at which a first selection of the plurality of convex polygons can be merged with a second selection of the plurality of convex polygons, merging a first selection of the plurality of convex polygons with a second selection of the plurality of convex polygons to reduce the number of convex polygons within the plurality of convex polygons stored in the image processing unit, wherein the merging limits the loss of edge fidelity of the convex polygons, and storing image data generated from the image processing unit.

BRIEF DESCRIPTION OF THE DRAWINGS

So that the manner in which the above recited features of the present disclosure can be understood in detail, a more particular description of the disclosure, briefly summarized above, may be had by reference to embodiments, some of which are illustrated in the appended drawings. It is to be noted, however, that the appended drawings illustrate only exemplary embodiments of this disclosure and are therefore not to be considered limiting of its scope, for the disclosure may be applied to other equally effective embodiments.



FIG. 1 is a perspective view of a system that may benefit from embodiments disclosed herein.

FIG. 2 is a cross-sectional side view of the system of FIG. 1 according to one embodiment.

FIG. 3 is a perspective schematic view of a plurality of image projection systems according to one embodiment.

FIG. 4 is a perspective schematic view of an image projection system of the plurality of image projection devices of FIG. 3 according to one embodiment.

FIG. 5 is an enlarged perspective view of two mirrors of a DMD according to one embodiment.

FIG. 6 schematically illustrates a beam being reflected by the two mirrors of the DMD of FIG. 5 according to one embodiment.

FIG. 7 illustrates a computer system for providing a data tuning application for fast computation and polygonal manipulation simplification according to one embodiment described herein.

FIG. 8 illustrates a more detailed view of a server of FIG. 7 according to one embodiment described herein.

FIG. 9 illustrates a controller computing system used to access a data tuning application for fast computation and polygonal manipulation simplification according to one embodiment described herein.

FIG. 10 schematically illustrates operations of a method for tuning data for parallel image processing according to one embodiment described herein.

To facilitate understanding, identical reference numerals have been used, where possible, to designate identical elements that are common to the figures. It is contemplated that elements and features of one embodiment may be beneficially incorporated in other embodiments without further recitation.

#### DETAILED DESCRIPTION

Embodiments described herein generally relate to a data tuning software application platform which maintains the ability to apply maskless lithography patterns to a substrate in a manufacturing process. The application processes graphical objects and configures the graphical objects for partition into a plurality of trapezoids. Furthermore, the trapezoids may be selectively merged in order to minimize the trapezoid count while limiting the loss of edge fidelity.

The term “user” as used herein includes, for example, a person or entity that owns a computing device or wireless device; a person or entity that operates or utilizes a computing device or a wireless device; or a person or entity that is otherwise associated with a computing device or a wireless device. It is contemplated that the term “user” is not intended to be limiting and may include various examples beyond those described.

FIG. 1 is a perspective view of a system 100 that may benefit from embodiments disclosed herein. The system 100 includes a base frame 110, a slab 120, two or more stages 130, and a processing apparatus 160. The base frame 110 may rest on the floor of a fabrication facility and may support the slab 120. Passive air isolators 112 may be positioned between the base frame 110 and the slab 120. The slab 120 may be a monolithic piece of granite, and the two or more stages 130 may be disposed on the slab 120. A substrate 140 may be supported by each of the two or more stages 130. A plurality of holes (not shown) may be formed in the stage 130 for allowing a plurality of lift pins (not shown) to extend therethrough. The lift pins may rise to an extended position to receive the substrate 140, such as from a transfer robot (not shown). The transfer robot may position

the substrate 140 on the lift pins, and the lift pins may thereafter gently lower the substrate 140 onto the stage 130.

The substrate 140 may, for example, be made of quartz and be used as part of a flat panel display. In other embodiments, the substrate 140 may be made of other materials. In some embodiments, the substrate 140 may have a photoresist layer formed thereon. A photoresist is sensitive to radiation and may be a positive photoresist or a negative photoresist, meaning that portions of the photoresist exposed to radiation will be respectively soluble or insoluble to a photoresist developer applied to the photoresist after the pattern is written into the photoresist. The chemical composition of the photoresist determines whether the photoresist will be a positive photoresist or negative photoresist. For example, the photoresist may include at least one of diazonaphthoquinone, a phenol formaldehyde resin, poly(methyl methacrylate), poly(methyl glutarimide), and SU-8. In this manner, the pattern may be created on a surface of the substrate 140 to form the electronic circuitry.

The system 100 may further include a pair of supports 122 and a pair of tracks 124. The pair of supports 122 may be disposed on the slab 120, and the slab 120 and the pair of supports 122 may be a single piece of material. The pair of tracks 124 may be supported by the pair of the supports 122, and the two or more stages 130 may move along the tracks 124 in the X-direction. In one embodiment, the pair of tracks 124 is a pair of parallel magnetic channels. As shown, each track 124 of the pair of tracks 124 is linear. In other embodiments, the track 124 may have a non-linear shape. An encoder 126 may be coupled to each stage 130 in order to provide location information to a controller 702 (See FIG. 9).

The processing apparatus 160 may include a support 162 and a processing unit 164. The support 162 may be disposed on the slab 120 and may include an opening 166 for the two or more stages 130 to pass under the processing unit 164. The processing unit 164 may be supported by the support 162. In one embodiment, the processing unit 164 is a pattern generator configured to expose a photoresist in a photolithography process. In some embodiments, the pattern generator may be configured to perform a maskless lithography process. The processing unit 164 may include a plurality of image projection systems (shown in FIG. 3) disposed in a case 165. The processing apparatus 160 may be utilized to perform maskless direct patterning. During operation, one of the two or more stages 130 moves in the X-direction from a loading position, as shown in FIG. 1, to a processing position. The processing position may refer to one or more positions of the stage 130 as the stage 130 passes under the processing unit 164. During operation, the two or more stages 130 may be lifted by a plurality of air bearings 202 (shown in FIG. 2) and may move along the pair of tracks 124 from the loading position to the processing position. A plurality of vertical guide air bearings (not shown) may be coupled to each stage 130 and positioned adjacent an inner wall 128 of each support 122 in order to stabilize the movement of the stage 130. Each of the two or more stages 130 may also move in the Y-direction by moving along a track 150 for processing and/or indexing the substrate 140.

FIG. 2 is a cross-sectional side view of the system 100 of FIG. 1 according to one embodiment. As shown, each stage 130 includes a plurality of air bearings 202 for lifting the stage 130. Each stage 130 may also include a motor coil (not shown) for moving the stage 130 along the tracks 124. The two or more stages 130 and the processing apparatus 160 may be enclosed by an enclosure (not shown) in order to provide temperature and pressure control.



FIG. 3 is a perspective schematic view of a plurality of image projection systems 301 according to one embodiment. As shown in FIG. 3, each image projection system 301 produces a plurality of write beams 302 onto a surface 304 of the substrate 140. As the substrate 140 moves in the X-direction and Y-direction, the entire surface 304 may be patterned by the write beams 302. The number of the image projection systems 301 may vary based on the size of the substrate 140 and/or the speed of stage 130. In one embodiment, there are 22 image projection systems 164 in the processing apparatus 160.

FIG. 4 is a perspective schematic view of one image projection system 301 of the plurality of image projection systems 301 of FIG. 3 according to one embodiment. The image projection system 301 may include a light source 402, an aperture 404, a lens 406, a mirror 408, a DMD 410, a light dump 412, a camera 414, and a projection lens 416. The light source 402 may be a light emitting diode (LED) or a laser, and the light source 402 may be capable of producing a light having predetermined wavelength. In one embodiment, the predetermined wavelength is in the blue or near ultraviolet (UV) range, such as less than about 450 nm. The mirror 408 may be a spherical mirror. The projection lens 416 may be a 10× objective lens. The DMD 410 may include a plurality of mirrors, and the number of mirrors may correspond to the resolution of the projected image. In one embodiment, the DMD 410 includes 1920×1080 mirrors, which represent the number of pixels of a high definition television or other flat panel displays.

During operation, a beam 403 having a predetermined wavelength, such as a wavelength in the blue range, is produced by the light source 402. The beam 403 is reflected to the DMD 410 by the mirror 408. The DMD 410 includes a plurality of mirrors that may be controlled individually, and each mirror of the plurality of mirrors of the DMD 410 may be at “on” position or “off” position, based on the mask data provided to the DMD 410 by the controller (not shown). When the beam 403 reaches the mirrors of the DMD 410, the mirrors that are at “on” position reflect the beam 403, i.e., forming the plurality of write beams 302, to the projection lens 416. The projection lens 416 then projects the write beams 302 to the surface 304 of the substrate 140. The mirrors that are at “off” position reflect the beam 403 to the light dump 412 instead of the surface 304 of the substrate 140.

FIG. 5 is an enlarged perspective view of two mirrors 502, 504 of the DMD 410 according to one embodiment. As shown, each mirror 502, 504 is disposed on a tilting mechanism 506, which is disposed on a memory cell 508. The memory cell 508 may be a CMOS SRAM. During operation, each mirror 502, 504 is controlled by loading the mask data into the memory cell. The mask data electrostatically controls the tilting of the mirror 502, 504 in a binary fashion. When the mirror 502, 504 is in a reset mode or without power applied, it may be set to a flat position, not corresponding to any binary number. Zero in binary may correspond to an “off” position, which means the mirror is tilted at -10 degrees, -12 degrees, or any other feasibly negative tilting degree. One in binary may correspond to an “on” position, which means the mirror is tilted at +10 degrees, +12 degrees, or any other feasibly positive tilting degree. As shown in FIG. 5, the mirror 502 is at “off” position and the mirror 504 is at “on” position.

FIG. 6 schematically illustrates the beam 403 being reflected by the two mirrors 502, 504 of the DMD 410 of FIG. 5 according to one embodiment. As shown, the mirror 502, which is at “off” position, reflects the beam 403

generated from the light source 402 to the light dump 412. The mirror 504, which is at “on” position, forms the write beam 302 by reflecting the beam 403 to the projection lens 416.

FIG. 7 illustrates a computing system 700 configured for providing a data tuning application for fast computation and polygonal manipulation simplification in which embodiments of the disclosure may be practiced. As shown, the computing system 700 may include a plurality of servers 708, a data tuning application server 712, and a plurality of controllers (i.e., computers, personal computers, mobile/wireless devices) 702 (only two of which are shown for clarity), each connected to a communications network 706 (for example, the Internet). The servers 708 may communicate with the database 714 via a local connection (for example, a Storage Area Network (SAN) or Network Attached Storage (NAS)) or over the Internet. The servers 708 are configured to either directly access data included in the database 714 or to interface with a database manager that is configured to manage data included within the database 714.

Each controller 702 may include conventional components of a computing device, for example, a processor, system memory, a hard disk drive, a battery, input devices such as a mouse and a keyboard, and/or output devices such as a monitor or graphical user interface, and/or a combination input/output device such as a touchscreen which not only receives input but also displays output. Each server 708 and the data tuning application server 712 may include a processor and a system memory (not shown), and may be configured to manage content stored in database 714 using, for example, relational database software and/or a file system. The servers 708 may be programmed to communicate with one another, the controllers 702, and the data tuning application server 712 using a network protocol such as, for example, the TCP/IP protocol. The data tuning application server 712 may communicate directly with the controllers 702 through the communications network 706. The controllers 702 are programmed to execute software 704, such as programs and/or other software applications, and access applications managed by servers 708.

In the embodiments described below, users may respectively operate the controllers 702 that may be connected to the servers 708 over the communications network 706. Pages, images, data, documents, and the like may be displayed to a user via the controllers 702. Information and images may be displayed through a display device and/or a graphical user interface in communication with the controller 702.

It is noted that the controller 702 may be a personal computer, laptop mobile computing device, smart phone, video game console, home digital media player, network-connected television, set top box, and/or other computing devices having components suitable for communicating with the communications network 706 and/or the applications or software. The controller 702 may also execute other software applications configured to receive content and information from the data tuning application 712.

FIG. 8 illustrates a more detailed view of the data tuning application server 712 of FIG. 7. The data tuning application server 712 includes, without limitation, a central processing unit (CPU) 802, a network interface 804, memory 820, and storage 830 communicating via an interconnect 806. The data tuning application server 712 may also include I/O device interfaces 808 connecting I/O devices 810 (for example, keyboard, video, mouse, audio, touchscreen, etc.). The data tuning application 712 may further include the



network interface **804** configured to transmit data via the communications network **706**.

The CPU **802** retrieves and executes programming instructions stored in the memory **820** and generally controls and coordinates operations of other system components. Similarly, the CPU **802** stores and retrieves application data residing in the memory **820**. The CPU **802** is included to be representative of a single CPU, multiple CPU's, a single CPU having multiple processing cores, and the like. The interconnect **806** is used to transmit programming instructions and application data between the CPU **802**, I/O device interfaces **808**, storage **830**, network interfaces **804**, and memory **820**.

The memory **820** is generally included to be representative of a random access memory and, in operation, stores software applications and data for use by the CPU **802**. Although shown as a single unit, the storage **830** may be a combination of fixed and/or removable storage devices, such as fixed disk drives, floppy disk drives, hard disk drives, flash memory storage drives, tape drives, removable memory cards, CD-ROM, DVD-ROM, Blu-Ray, HD-DVD, optical storage, network attached storage (NAS), cloud storage, or a storage area-network (SAN) configured to store non-volatile data.

The memory **820** may store instructions and logic for executing an application platform **826** which may include data tuning software **828**. The storage **830** may include a database **832** configured to store data **834** and associated application platform content **836**. The database **832** may be any type of storage device.

Network computers are another type of computer system that can be used in conjunction with the disclosures provided herein. Network computers do not usually include a hard disk or other mass storage, and the executable programs are loaded from a network connection into the memory **820** for execution by the CPU **802**. A typical computer system will usually include at least a processor, memory, and an interconnect coupling the memory to the processor.

FIG. **9** illustrates a controller **702** used to access the data tuning application **712** and retrieve or display data associated with the application platform **826**. The controller **702** may include, without limitation, a central processing unit (CPU) **902**, a network interface **904**, an interconnect **906**, a memory **920**, storage **930**, and support circuits **940**. The controller **702** may also include an I/O device interface **908** connecting I/O devices **910** (for example, keyboard, display, touchscreen, and mouse devices) to the controller **702**.

Like CPU **802**, CPU **902** is included to be representative of a single CPU, multiple CPU's, a single CPU having multiple processing cores, etc., and the memory **920** is generally included to be representative of a random access memory. The interconnect **906** may be used to transmit programming instructions and application data between the CPU **902**, I/O device interfaces **908**, storage **930**, network interface **904**, and memory **920**. The network interface **904** may be configured to transmit data via the communications network **706**, for example, to transfer content from the data tuning application server **712**. Storage **930**, such as a hard disk drive or solid-state storage drive (SSD), may store non-volatile data. The storage **930** may contain a database **931**. The database **931** may contain data **932** and other content **934**. Illustratively, the memory **920** may include an application interface **922**, which itself may display software instructions **924**, and/or store or display data **926**. The application interface **922** may provide one or more software

applications which allow the controller to access data and other content hosted by the data tuning application server **712**.

As shown in FIG. **9**, the system **100** includes a controller **702**. The controller **702** is generally designed to facilitate the control and automation of the processing techniques described herein. The controller **702** may be coupled to or in communication with one or more of the processing apparatus **160**, the stages **130**, and the encoder **126**. The processing apparatus **160** and the stages **130** may provide information to the controller **702** regarding the substrate processing and the substrate aligning. For example, the processing apparatus **160** may provide information to the controller **702** to alert the controller that substrate processing has been completed. The encoder **126** may provide location information to the controller **702**, and the location information is then used to control the stages **130** and the processing apparatus **160**.

The controller **702** may include a central processing unit (CPU) **902**, memory **920**, and support circuits **940** (or I/O **908**). The CPU **902** may be one of any form of computer processors that are used in industrial settings for controlling various processes and hardware (e.g., pattern generators, motors, and other hardware) and monitor the processes (e.g., processing time and substrate position). The memory **920**, as shown in FIG. **9**, is connected to the CPU **902**, and may be one or more of a readily available memory, such as random access memory (RAM), read only memory (ROM), floppy disk, hard disk, or any other form of digital storage, local or remote. Software instructions and data can be coded and stored within the memory for instructing the CPU **902**. The support circuits **940** are also connected to the CPU **902** for supporting the processor in a conventional manner. The support circuits **940** may include conventional cache **942**, power supplies **944**, clock circuits **946**, input/output circuitry **948**, subsystems **950**, and the like. A program (or computer instructions) readable by the controller **702** determines which tasks are performable on a substrate. The program may be software readable by the controller **702** and may include code to monitor and control, for example, the processing time and substrate position.

It should be borne in mind, however, that all of these and similar terms are to be associated with the appropriate physical quantities and are merely convenient labels applied to these quantities. Unless specifically stated otherwise as apparent from the following discussion, it is appreciated that throughout the description, discussions utilizing terms such as "processing" or "computing" or "calculating" or "determining" or "displaying" or the like, refer to the action and processes of a computer system, or similar electronic computing device, that manipulates and transforms data represented as physical (electronic) quantities within the computer system's registers and memories into other data similarly represented as physical quantities within the computer system memories or registers or other such information storage, transmission, or display devices.

The present example also relates to an apparatus for performing the operations herein. This apparatus may be specially constructed for the required purposes, or it may comprise a general purpose computer selectively activated or reconfigured by a computer program stored in the computer. Such a computer program may be stored in a computer readable storage medium, such as, but is not limited to, read-only memories (ROMs), random access memories (RAMs), EPROMs, EEPROMs, flash memory, magnetic or optical cards, any type of disk including floppy disks, optical disks, CD-ROMs, and magnetic-optical disks, or any type of



media suitable for storing electronic instructions, and each coupled to a computer system interconnect.

The algorithms and displays presented herein are not inherently related to any particular computer or other apparatus. Various general purpose systems may be used with programs in accordance with the teachings herein, or it may prove convenient to construct a more specialized apparatus to perform the method operations. The structure for a variety of these systems will appear from the description above. In addition, the present examples are not described with reference to any particular programming language, and various examples may thus be implemented using a variety of programming languages.

As described in greater detail within, embodiments of the disclosure provide a software application through which graphical objects, such as convex polygons, such as trapezoids, may be selectively merged in order to minimize the graphical object count. Despite minimizing trapezoid count, the loss of edge fidelity is also limited.

In one embodiment, a method for tuning data for parallel image processing is disclosed. The method may be performed by a controller 702, as shown in FIG. 9. As discussed with reference to FIG. 3, supra, each image projection system 301 produces a plurality of write beams 302 onto a surface 304 of the substrate 140, and, as the substrate 140 moves in the X-direction and Y-direction, the entire surface 304 may be patterned by the write beams 302. During patterning the controller may process one or more graphical objects of the surface 304 of the substrate 140. The processing of the graphical objects may generate and/or partition the one or more graphical objects into a plurality of convex polygons. To facilitate parallel image processing acceleration, the polygons may be tessellated into convex polygons, such as trapezoids and/or triangles. The tessellation may occur along the scan direction. The trapezoids may be sorted by scan line, however, the order of the trapezoids may be arbitrary. A tessellation of the polygons to trapezoids, a lower level primitive, may simplify a second stage of the patterning process, rasterization.

The coordinates of the convex polygons may be used to form an edge list 938 for representing each of the plurality of convex polygons. The processing of the one or more graphical objects may also include the identification of transitions at the boundaries of the one or more graphical objects or convex polygons according to a scan direction of the DMD 410.

The edge list 938 may be stored in an image processing unit 936 of the storage 930 of the controller 702. The edge list 938 may be updated as further scans of the substrate 140 are completed. Scans may be completed by an optical unit or image projection system 301. After storing the edge list 938, the plurality of convex polygons, or a portion thereof, may be scanned according to a predetermined scan direction. The scanning may include scanning a portion of a convex polygon along a column. The scanning may further include scanning a portion of a convex polygon along a row. A first portion of the each of the plurality of convex polygons may be processed and analyzed. The analyzing may allow for the identification of merge locations with respect to the first portion of each of the plurality of convex polygons before merging occurs.

Locations at which the first selection of the plurality of convex polygons can be merged with a second selection of the plurality of convex polygons may further be determined. The image processing unit 936 may contain control logic 939 configured to selectively merge individual convex polygons. The control logic 939 of the image processing unit 936

may be configured to synchronize operations of the plurality of convex polygons. Merging the first selection of the plurality of convex polygons with the second selection of the plurality of convex polygons may occur to reduce the number of convex polygons within the plurality of convex polygons, as well as the number of convex polygons stored within the image processing unit 936. Merging to reduce the number of convex polygons may ease the burden and/or balance the load with respect to the storage capabilities of the image processing unit 936. Furthermore, the merging of the convex polygons may act to limit the loss of edge fidelity of the convex polygons. Limiting the loss of edge fidelity may preserve with a degree of exactness the edges and overall shape of edge lines as copied or reproduced with respect to the substrate 140. The image projection system 301, supra, may expose a substrate and deliver light to the surface of the substrate 140. Each exposure may last approximately about 65 microseconds. During each exposure approximately 350,000 trapezoids may be generated and, therefore, processed. In order to limit the loss of edge fidelity, smaller trapezoids may be merged with larger or immediately connected trapezoids, thus easing the storage requirements of the controller 702. The merging of trapezoids may create an error amount which may be compared against an acceptable error amount. The image data generated from the image processing unit 936 may further be stored in the image processing unit 936 or in another suitable storage facility.

In another embodiment, a computer system for performing data tuning for parallel image processing is disclosed. The computer system may comprise a processor and a memory. The memory may store instructions that, when executed by the processor, cause the computer system to process one or more graphical objects to generate a plurality of convex polygons. The processing of the graphical objects may generate and/or partition the one or more graphical objects into a plurality of convex polygons. To facilitate parallel image processing acceleration, the polygons may be tessellated into convex polygons, such as trapezoids and/or triangles. The tessellation may occur along the scan direction. The trapezoids may be sorted by scan line, however, the order of the trapezoids may be arbitrary. A tessellation of the polygons to trapezoids, a lower level primitive, may simplify a second stage of the patterning process, rasterization.

The coordinates of the convex polygons may be used to form an edge list 938 for representing each of the plurality of convex polygons. The processing of the one or more graphical objects may also include the identification of transitions at the boundaries of the one or more graphical objects or convex polygons according to a scan direction of the DMD 410.

The memory may further store instructions that, when executed by the processor, cause the computer system to store the edge list 938 in an image processing unit 936. The edge list 938 may be updated as further scans of the substrate 140 are completed. Scans may be completed by an optical unit or image projection system 301. After storing the edge list 938, the instructions may cause the computer system to scan, according to a predetermined scan direction, the plurality of convex polygons, or a portion thereof. The scanning may include scanning a portion of a convex polygon along a column. The scanning may further include scanning a portion of a convex polygon along a row. A first portion of the each of the plurality of convex polygons may be processed and analyzed. The analyzing may allow for the



identification of merge locations with respect to the first portion of each of the plurality of convex polygons before merging occurs.

The instructions may further cause the computer system to determine locations at which the first selection of the plurality of convex polygons can be merged with a second selection of the plurality of convex polygons. The stored instructions may contain control logic **939** for the image processing unit **936** configured to selectively merge individual convex polygons. The control logic **939** of the image processing unit **936** may be configured to synchronize operations of the plurality of convex polygons. Merging the first selection of the plurality of convex polygons with the second selection of the plurality of convex polygons may occur to reduce the number of convex polygons within the plurality of convex polygons, as well as the number of convex polygons stored within the image processing unit **936**. Merging to reduce the number of convex polygons may ease the burden and/or balance the load with respect to the storage capabilities of the image processing unit **936** or other storage device. Furthermore, the merging of the convex polygons may act to limit the loss of edge fidelity of the convex polygons. Limiting the loss of edge fidelity may preserve with a degree of exactness the edges and overall shape of edge lines as copied or reproduced with respect to the substrate **140**. The image projection system **301**, supra, may expose a substrate and deliver light to the surface of the substrate **140**. Each exposure may last approximately about 65 microseconds. During each exposure approximately 350,000 trapezoids may be generated and, therefore, processed. In order to limit the loss of edge fidelity, smaller trapezoids may be merged with larger or immediately connected trapezoids, thus easing the storage requirements of the controller **702**. The merging of trapezoids may create an error amount which may be compared against an acceptable error amount. The image data generated from the image processing unit **936** may further be stored in the image processing unit **936** or in another suitable storage facility.

In yet another embodiment, a non-transitory computer-readable medium storing instructions that, when executed by a processor, cause a computer system to tune data for parallel image processing is disclosed. The non-transitory computer-readable medium may perform the steps of processing one or more graphical objects to generate a plurality of convex polygons. The processing of the graphical objects may generate and/or partition the one or more graphical objects into a plurality of convex polygons. To facilitate parallel image processing acceleration, the polygons may be tessellated into convex polygons, such as trapezoids and/or triangles. The tessellation may occur along the scan direction. The trapezoids may be sorted by scan line, however, the order of the trapezoids may be arbitrary. A tessellation of the polygons to trapezoids, a lower level primitive, may simplify a second stage of the patterning process, rasterization.

The coordinates of the convex polygons may be used to form an edge list **938** for representing each of the plurality of convex polygons. The processing of the one or more graphical objects may also include the identification of transitions at the boundaries of the one or more graphical objects or convex polygons according to a scan direction of the DMD **410**.

The non-transitory computer-readable medium may also perform the steps of storing the edge list **938** in an image processing unit **936**. The edge list **938** may be updated as further scans of the substrate **140** are completed. Scans may be completed by an optical unit or image projection system **301**. After storing the edge list **938**, the non-transitory

computer-readable medium may perform the step of scanning, according to a predetermined scan direction, the plurality of convex polygons, or a portion thereof. The scanning may include scanning a portion of a convex polygon along a column. The scanning may further include scanning a portion of a convex polygon along a row. A first portion of the each of the plurality of convex polygons may be processed and analyzed. The analyzing may allow for the identification of merge locations with respect to the first portion of each of the plurality of convex polygons before merging occurs.

The non-transitory computer-readable medium may further perform the steps of determining locations at which the first selection of the plurality of convex polygons can be merged with a second selection of the plurality of convex polygons. The non-transitory computer-readable medium may contain control logic **939** for the image processing unit **936** configured to selectively merge individual convex polygons. The control logic **939** of the image processing unit **936** may be configured to synchronize operations of the plurality of convex polygons. Merging the first selection of the plurality of convex polygons with the second selection of the plurality of convex polygons may occur to reduce the number of convex polygons within the plurality of convex polygons, as well as the number of convex polygons stored within the image processing unit **936**. Merging to reduce the number of convex polygons may ease the burden and/or balance the load with respect to the storage capabilities of the image processing unit **936** or other storage device. Furthermore, the merging of the convex polygons may act to limit the loss of edge fidelity of the convex polygons. Limiting the loss of edge fidelity may preserve with a degree of exactness the edges and overall shape of edge lines as copied or reproduced with respect to the substrate **140**. The image projection system **301**, supra, may expose a substrate and deliver light to the surface of the substrate **140**. Each exposure may last approximately about 65 microseconds. During each exposure approximately 350,000 trapezoids may be generated and, therefore, processed. In order to limit the loss of edge fidelity, smaller trapezoids may be merged with larger or immediately connected trapezoids, thus easing the storage requirements of the controller **702**. The merging of trapezoids may create an error amount which may be compared against an acceptable error amount. The image data generated from the image processing unit **936** may further be stored in the image processing unit **936** or in another suitable storage facility.

FIG. **10** schematically illustrates operations of a method **1000** for tuning data for parallel image processing according to one embodiment described herein. The method **1000** generally relates to the selective merging of graphical objects, such as convex polygons, to minimize the graphical object count. Furthermore, the method **1000** generally relates to the limiting of the loss of edge fidelity of the selectively merged graphical objects. At operation **1010**, one or more graphical objects are processed to generate a plurality of convex polygons. At operation **1020**, an edge list is formed for representing each of the plurality of convex polygons. At operation **1030**, the edge list is stored in an image processing unit. At operation **1040**, a location at which a first selection of this plurality of convex polygons can be merged with a second selection of the plurality of convex polygon is determined. At operation **1050**, the first selection of the plurality of convex polygons is merged with the second selection of the plurality of convex polygons to reduce the number of convex polygon within the plurality of convex polygons stored in the image processing unit. The



## 13

merging limits the loss of edge fidelity of the convex polygons. At operation 1060, image data generated from the image processing unit is stored.

The data tuning application quickly computes and simplifies polygonal manipulations such that trapezoids and/or other convex polygons may be selectively merged. The selective merging of trapezoids may reduce the overall amount of data to be stored in the image processing unit. Further benefits may include a reduction in trapezoid count, a reduction in the amount of data to be processed, as well as a limiting of the loss of edge fidelity of the trapezoids and/or other convex polygons.

While the foregoing is directed to embodiments described herein, other and further embodiments may be devised without departing from the basic scope thereof. For example, aspects of the present disclosure may be implemented in hardware or software or in a combination of hardware and software. One embodiment described herein may be implemented as a program product for use with a computer system. The program(s) of the program product define functions of the embodiments (including the methods described herein) and can be contained on a variety of computer-readable storage media. Illustrative computer-readable storage media include, but are not limited to: (i) non-writable storage media (for example, read-only memory devices within a computer such as CD-ROM disks readable by a CD-ROM drive, flash memory, ROM chips or any type of solid-state non-volatile semiconductor memory) on which information is permanently stored; and (ii) writable storage media (for example, floppy disks within a diskette drive or hard-disk drive or any type of solid-state random-access semiconductor memory) on which alterable information is stored. Such computer-readable storage media, when carrying computer-readable instructions that direct the functions of the disclosed embodiments, are embodiments of the present disclosure.

It will be appreciated to those skilled in the art that the preceding examples are exemplary and not limiting. It is intended that all permutations, enhancements, equivalents, and improvements thereto that are apparent to those skilled in the art upon a reading of the specification and a study of the drawings are included within the true spirit and scope of the present disclosure. It is therefore intended that the following appended claims include all such modifications, permutations, and equivalents as fall within the true spirit and scope of these teachings.

What is claimed is:

1. A method for patterning a substrate using write beams and tuning data for parallel image processing, comprising: loading mask data into a memory cell and controlling tilting of a plurality of mirrors using the mask data; delivering light to a surface of the substrate; processing one or more graphical objects to generate a plurality of convex polygons; forming an edge list for representing each of the plurality of convex polygons; storing the edge list in an image processing unit; determining locations at which a first selection of the plurality of convex polygons can be merged with a second selection of the plurality of convex polygons; merging the first selection of the plurality of convex polygons with the second selection of the plurality of convex polygons to reduce the number of convex polygons within the plurality of convex polygons stored in the image processing unit, wherein the merging limits the loss of edge fidelity of the convex polygons;

## 14

creating an error amount based on the merging of convex polygons and comparing the error amount against an acceptable error amount; and storing image data generated from the image processing unit.

2. The method of claim 1, wherein processing one or more graphical objects comprises:

identifying transitions at the boundaries of the one or more graphical objects according to a scan direction; and partitioning the one or more graphical objects into the plurality of convex polygons.

3. The method of claim 1, further comprising: scanning the plurality of convex polygons according to a predetermined scan direction after storing the edge list; processing at least a first portion of each of the plurality of convex polygons after scanning the plurality of convex polygons; and analyzing merge locations before merging.

4. The method of claim 1, further comprising scanning the portion of the convex polygons, wherein the scanning comprises at least one of scanning the portion of the convex polygon along a column and scanning the portion of the convex polygon along a row.

5. The method of claim 1, wherein the merging reduces the number of convex polygons within the plurality of convex polygons.

6. The method of claim 1, wherein the image processing unit comprises control logic configured to selectively merge individual convex polygons.

7. The method of claim 6, wherein the control logic is configured to synchronize operations of the plurality of convex polygons.

8. A computer system for patterning a substrate using write beams and performing data tuning for parallel image processing, comprising:

a processor; and a memory storing instructions that, when executed by the processor, cause the computer system to:

load mask data into a memory cell and control tilting of a plurality of mirrors using the mask data; deliver light to a surface of the substrate; process one or more graphical objects to generate a plurality of convex polygons;

form an edge list for representing each of the plurality of convex polygons; store the edge list in an image processing unit;

determine locations at which a first selection of the plurality of convex polygons can be merged with a second selection of the plurality of convex polygons; merge the first selection of the plurality of convex polygons with the second selection of the plurality of convex polygons to reduce the number of convex polygons within the plurality of convex polygons stored in the image processing unit, wherein the merging limits the loss of edge fidelity of the convex polygons;

create an error amount based on the merging of convex polygons and comparing the error amount against an acceptable error amount; and store image data generated from the image processing unit.

9. The computer system of claim 8, wherein processing one or more graphical objects comprises:

identifying transitions at the boundaries of the one or more graphical objects according to a scan direction; and



## 15

partitioning the one or more graphical objects into the plurality of convex polygons.

10. The computer system of claim 8, further comprising: scanning the plurality of convex polygons according to a predetermined scan direction after storing the edge list; processing at least a first portion of each of the plurality of convex polygons after scanning the plurality of convex polygons; and analyzing merge locations before merging.

11. The computer system of claim 8, further comprising scanning the portion of the convex polygons, wherein the scanning comprises at least one of scanning the portion of the convex polygon along a column and scanning the portion of the convex polygon along a row.

12. The computer system of claim 8, wherein the merging reduces the number of convex polygons within the plurality of convex polygons.

13. The computer system of claim 8, wherein the image processing unit comprises control logic configured to selectively merge individual convex polygons.

14. The computer system of claim 13, wherein the control logic is configured to synchronize operations of the plurality of convex polygons.

15. A non-transitory computer-readable medium storing instructions that, when executed by a processor, cause a computer system to control the patterning of a substrate using write beams and to tune data for parallel image processing, by performing the steps of:

loading mask data into a memory cell and control tilting of a plurality of mirrors using the mask data;

delivering light to a surface of the substrate; processing one or more graphical objects to generate a plurality of convex polygons;

forming an edge list for representing each of the plurality of convex polygons;

storing the edge list in an image processing unit;

determining locations at which a first selection of the plurality of convex polygons can be merged with a second selection of the plurality of convex polygons;

merging the first selection of the plurality of convex polygons with the second selection of the plurality of convex polygons to reduce the number of convex

## 16

polygons within the plurality of convex polygons stored in the image processing unit, wherein the merging limits the loss of edge fidelity of the convex polygons;

creating an error amount based on the merging of convex polygons and comparing the error amount against an acceptable error amount; and storing image data generated from the image processing unit.

16. The non-transitory computer-readable medium of claim 15, wherein processing one or more graphical objects comprises:

identifying transitions at the boundaries of the one or more graphical objects according to a scan direction; and

partitioning the one or more graphical objects into the plurality of convex polygons.

17. The non-transitory computer-readable medium of claim 15, further comprising:

scanning the plurality of convex polygons according to a predetermined scan direction after storing the edge list; processing at least a first portion of each of the plurality of convex polygons after scanning the plurality of convex polygons; and

analyzing merge locations before merging.

18. The non-transitory computer-readable medium of claim 15, further comprising scanning the portion of the convex polygons, wherein the scanning comprises at least one of scanning the portion of the convex polygon along a column and scanning the portion of the convex polygon along a row.

19. The non-transitory computer-readable medium of claim 15, wherein the merging reduces the number of convex polygons within the plurality of convex polygons.

20. The non-transitory computer-readable medium of claim 15, wherein the image processing unit comprises control logic configured to selectively merge individual convex polygons.

21. The non-transitory computer-readable medium of claim 20, wherein the control logic is configured to synchronize operations of the plurality of convex polygons.

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