



US009382739B1

(12) **United States Patent**
Johnson et al.

(10) **Patent No.:** **US 9,382,739 B1**
(45) **Date of Patent:** **Jul. 5, 2016**

(54) **DETERMINING RIGHT OR LEFT HAND SIDE DOOR INSTALLATION**

(56) **References Cited**

(71) Applicant: **August Home, Inc.**, San Francisco, CA (US)

(72) Inventors: **Jason Johnson**, San Francisco, CA (US); **Christopher Dow**, San Francisco, CA (US); **Shih Yu Thomas Cheng**, Union City, CA (US); **Thomas Peter Russo**, San Francisco, CA (US); **Siddharth Gidwani**, San Mateo, CA (US)

(73) Assignee: **AUGUST HOME, INC.**, San Francisco, CA (US)

(*) Notice: Subject to any disclaimer, the term of this patent is extended or adjusted under 35 U.S.C. 154(b) by 142 days.

(21) Appl. No.: **14/459,054**

(22) Filed: **Aug. 13, 2014**

(51) **Int. Cl.**
G08B 23/00 (2006.01)
E05D 15/50 (2006.01)
E05F 15/20 (2006.01)
E05B 49/00 (2006.01)

(52) **U.S. Cl.**
CPC **E05D 15/50** (2013.01); **E05B 49/00** (2013.01); **E05F 15/20** (2013.01)

(58) **Field of Classification Search**
CPC G08B 25/00; H04W 4/008; E05B 49/00
USPC 340/5.64, 5.72, 5.85, 540, 541, 542; 70/266, 275, 357

See application file for complete search history.

U.S. PATENT DOCUMENTS

2,680,177	A	6/1954	Rosenthal
5,306,407	A	4/1994	Hauzer et al.
5,407,035	A	4/1995	Cole et al.
5,594,430	A	1/1997	Swindler et al.
5,695,048	A	12/1997	Tseng
6,196,936	B1	3/2001	Meckel
6,323,846	B1	11/2001	Westerman et al.
6,570,557	B1	5/2003	Westerman et al.
6,612,415	B2	9/2003	Yamane
6,677,932	B1	1/2004	Westerman
6,967,562	B2	11/2005	Menard et al.
7,614,008	B2	11/2009	Ording
7,633,076	B2	12/2009	Huppi et al.
7,653,883	B2	1/2010	Hotelling et al.
7,657,849	B2	2/2010	Chaudhri et al.
7,663,607	B2	2/2010	Hotelling et al.
7,844,914	B2	11/2010	Andre et al.
8,006,002	B2	8/2011	Kalayjian et al.
8,239,784	B2	8/2012	Hotelling et al.
8,279,180	B2	10/2012	Hotelling et al.
8,347,720	B2	1/2013	De Los Santos et al.
8,351,789	B2	1/2013	Wagener et al.

(Continued)

FOREIGN PATENT DOCUMENTS

CA	2676196	A1	7/2008
CA	2834964		8/2012

(Continued)

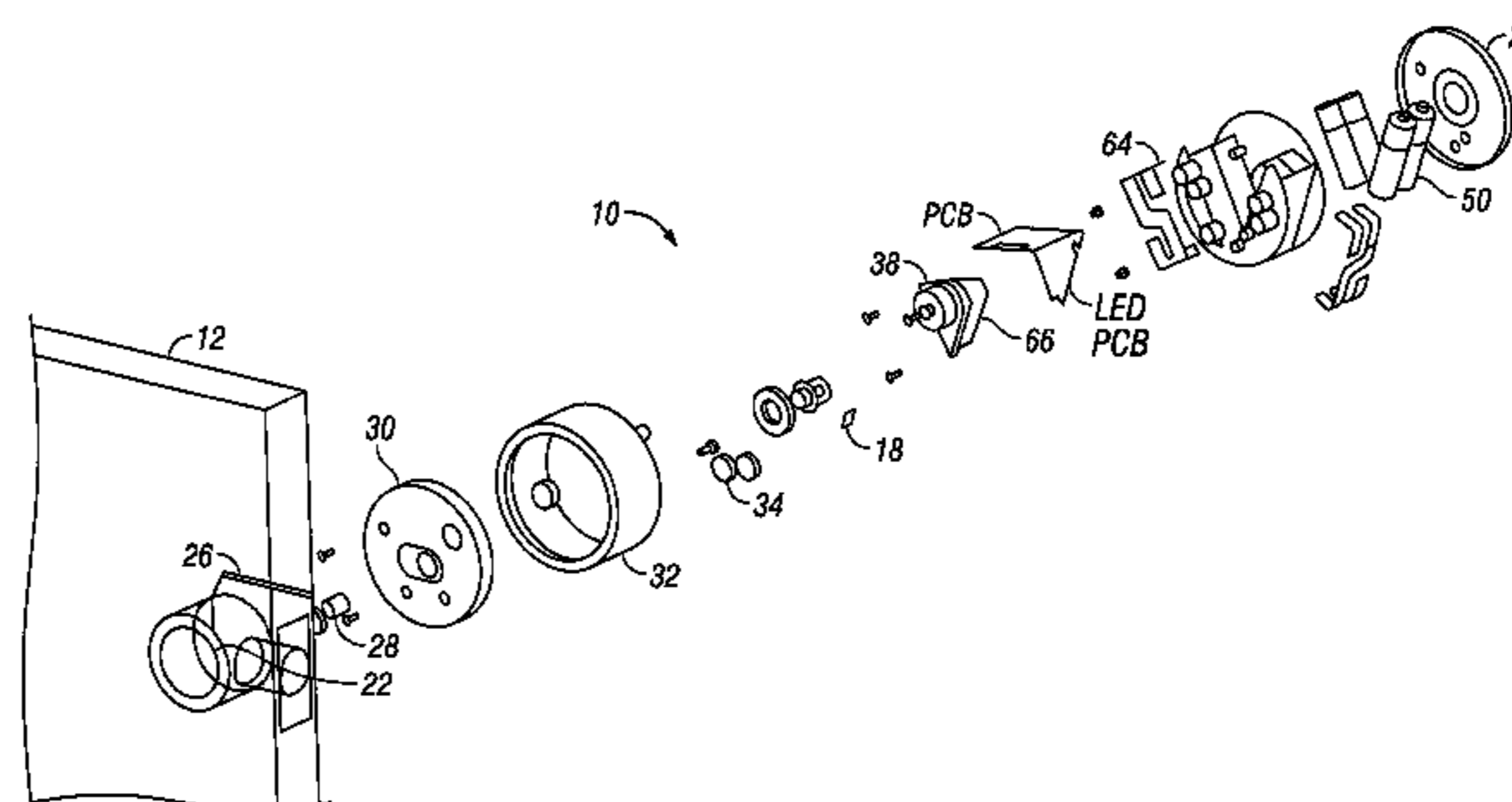
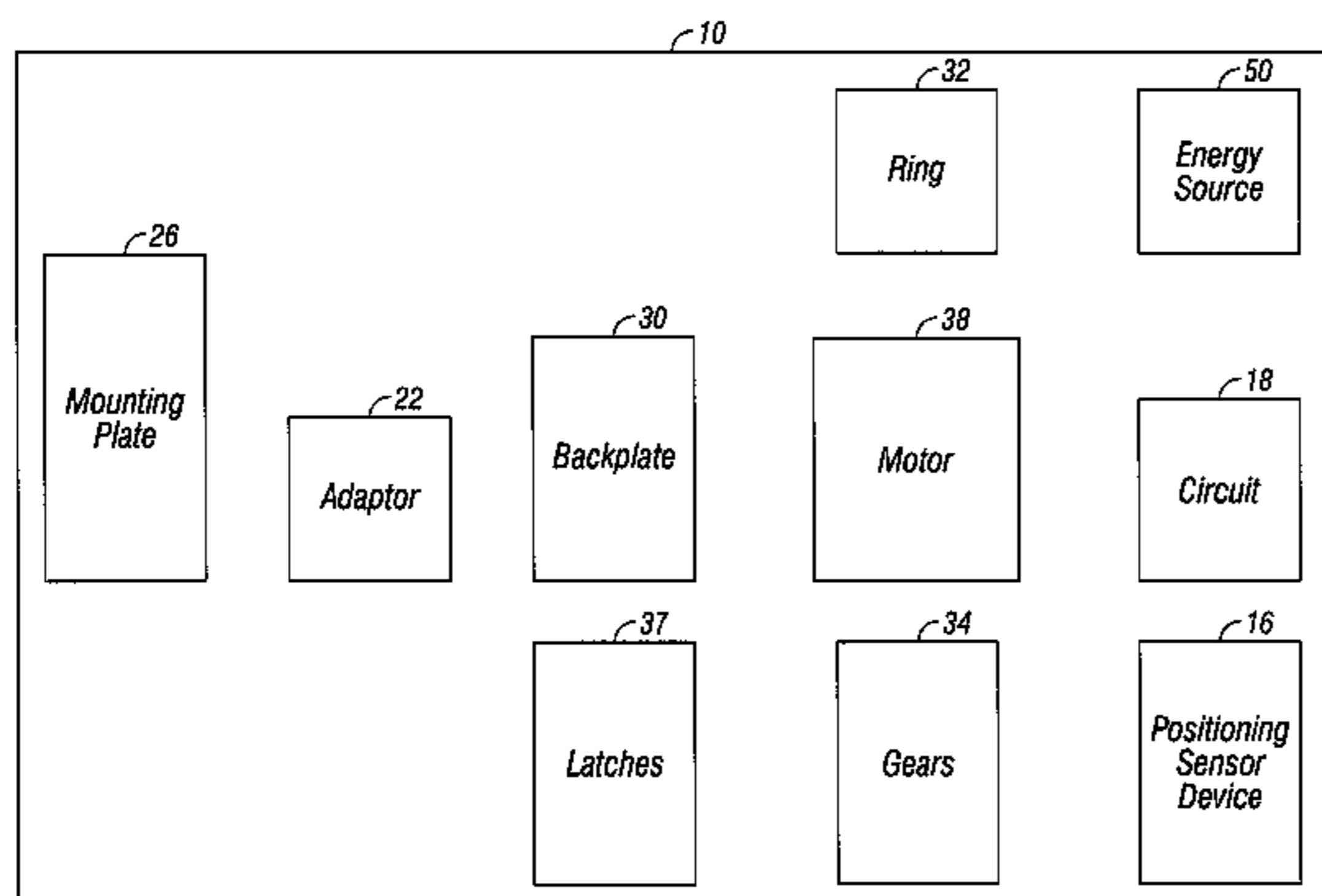
Primary Examiner — Tai T Nguyen

(74) Attorney, Agent, or Firm — Paul Davis; Beyer Law Group LLP

(57) **ABSTRACT**

A method is provided for determining right or hand side door installation. A drive shaft of the door lock mechanism is rotated with the bolt in a clock wise direction or a counter-clock wise direction. The rotation continues until there is sufficient extension of the bolt to provide for a lock position of an associated door.

19 Claims, 40 Drawing Sheets



(56)

References Cited

U.S. PATENT DOCUMENTS

8,405,387 B2 3/2013 Novak et al.
 8,476,577 B2 7/2013 Nagahama et al.
 8,479,122 B2 7/2013 Hotelling et al.
 8,522,596 B2 9/2013 Avery
 8,525,102 B2 9/2013 Augustyniak et al.
 8,542,189 B2 9/2013 Milne et al.
 8,544,326 B2 10/2013 Je
 8,600,430 B2 12/2013 Herz et al.
 8,826,708 B2 9/2014 Lopes
 9,057,210 B2 6/2015 Dumas
 2002/0015024 A1 2/2002 Westerman et al.
 2002/0196771 A1 12/2002 Vij et al.
 2003/0160681 A1* 8/2003 Menard E05B 45/06
 340/5.64
 2004/0075532 A1* 4/2004 Ueda E05B 77/48
 340/5.72
 2005/0252739 A1 11/2005 Callahan et al.
 2006/0026536 A1 2/2006 Hotelling et al.
 2006/0033724 A1 2/2006 Chaudhri et al.
 2006/0197753 A1 9/2006 Hotelling
 2007/0150842 A1 6/2007 Chaudhri et al.
 2012/0280789 A1 11/2012 Gerhardt et al.
 2012/0280790 A1 11/2012 Gerhardt et al.
 2012/0319827 A1 12/2012 Pance et al.
 2013/0063138 A1 3/2013 Takahashi et al.
 2013/0064378 A1 3/2013 Chuang
 2013/0138826 A1 5/2013 Ling et al.
 2013/0154823 A1 6/2013 Ostrer et al.

2013/0166202 A1 6/2013 Bandyopadhyay et al.
 2013/0237193 A1 9/2013 Dumas
 2014/0051355 A1 2/2014 Ahearn et al.
 2014/0239647 A1* 8/2014 Jadallah E05C 19/002
 292/140
 2014/0365773 A1 12/2014 Gerhardt et al.
 2015/0211259 A1 7/2015 Dumas
 2015/0213658 A1 7/2015 Dumas
 2015/0213663 A1 7/2015 Dumas

FOREIGN PATENT DOCUMENTS

EP 0486657 A1 5/1992
 EP 0907068 A1 4/1999
 EP 1404021 A2 3/2004
 EP 2428774 A1 3/2012
 EP 2454558 A1 5/2012
 EP 2564165 A2 3/2013
 EP 2579002 A1 4/2013
 EP 244750 8/2013
 EP 1529904 8/2013
 EP 2631400 8/2013
 EP 2642252 A1 9/2013
 WO WO2012151290 8/2012
 WO WO2014062321 4/2014
 WO WO2014107196 7/2014
 WO WO2015023737 2/2015
 WO PCT/US15/20180 5/2015
 WO PCT/US15/20226 5/2015
 WO PCT/US15/20206 6/2015

* cited by examiner

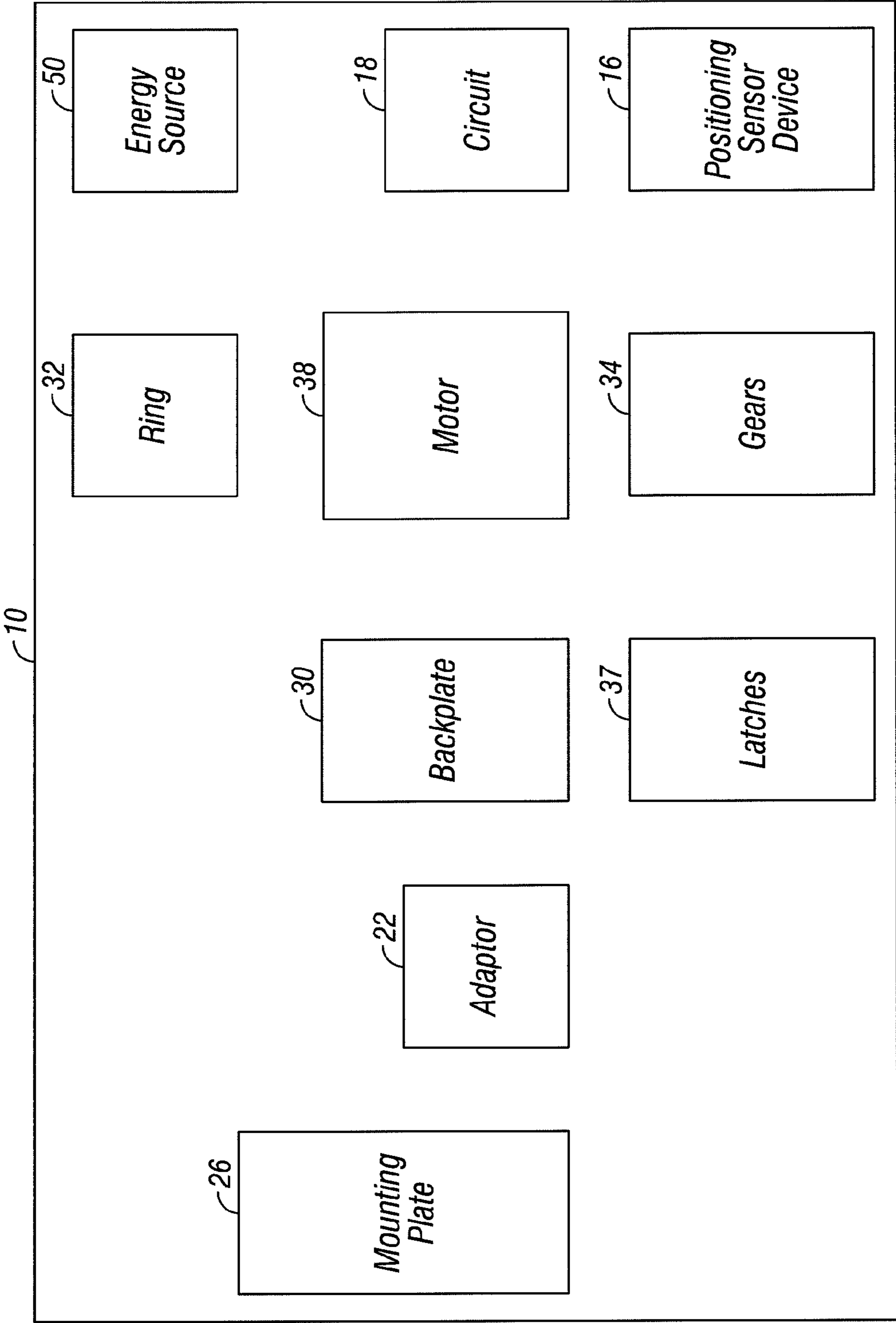


FIG. 1A

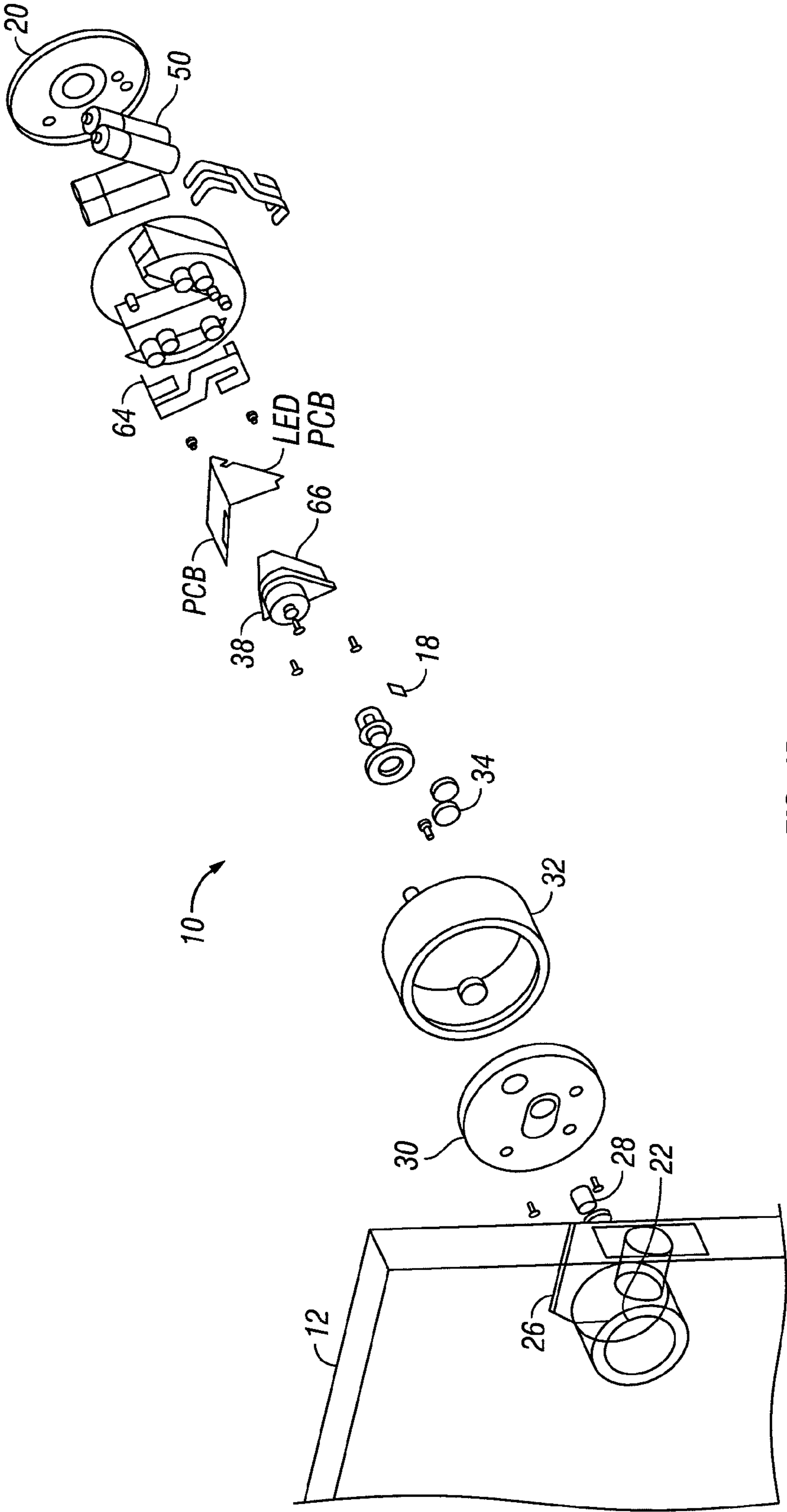


FIG. 1B

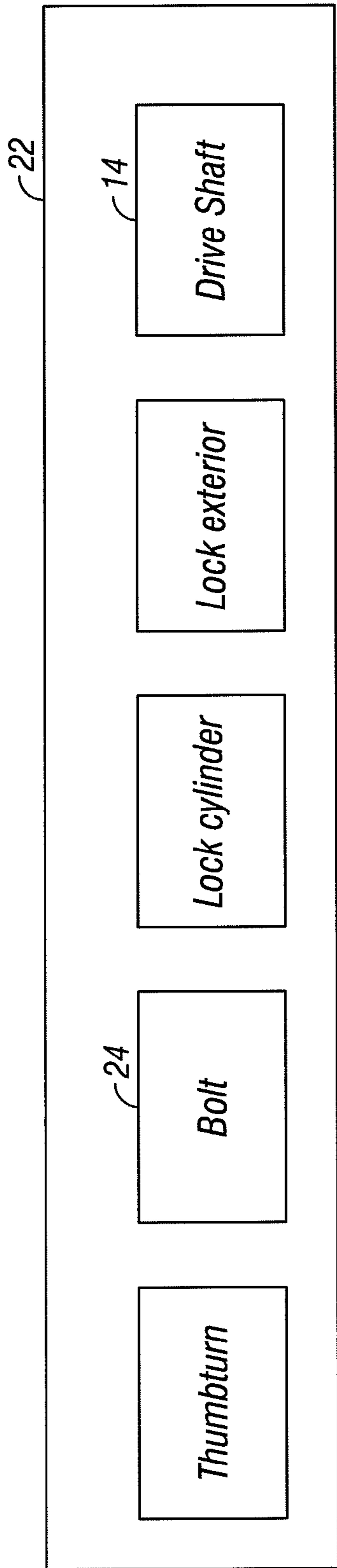


FIG. 1C

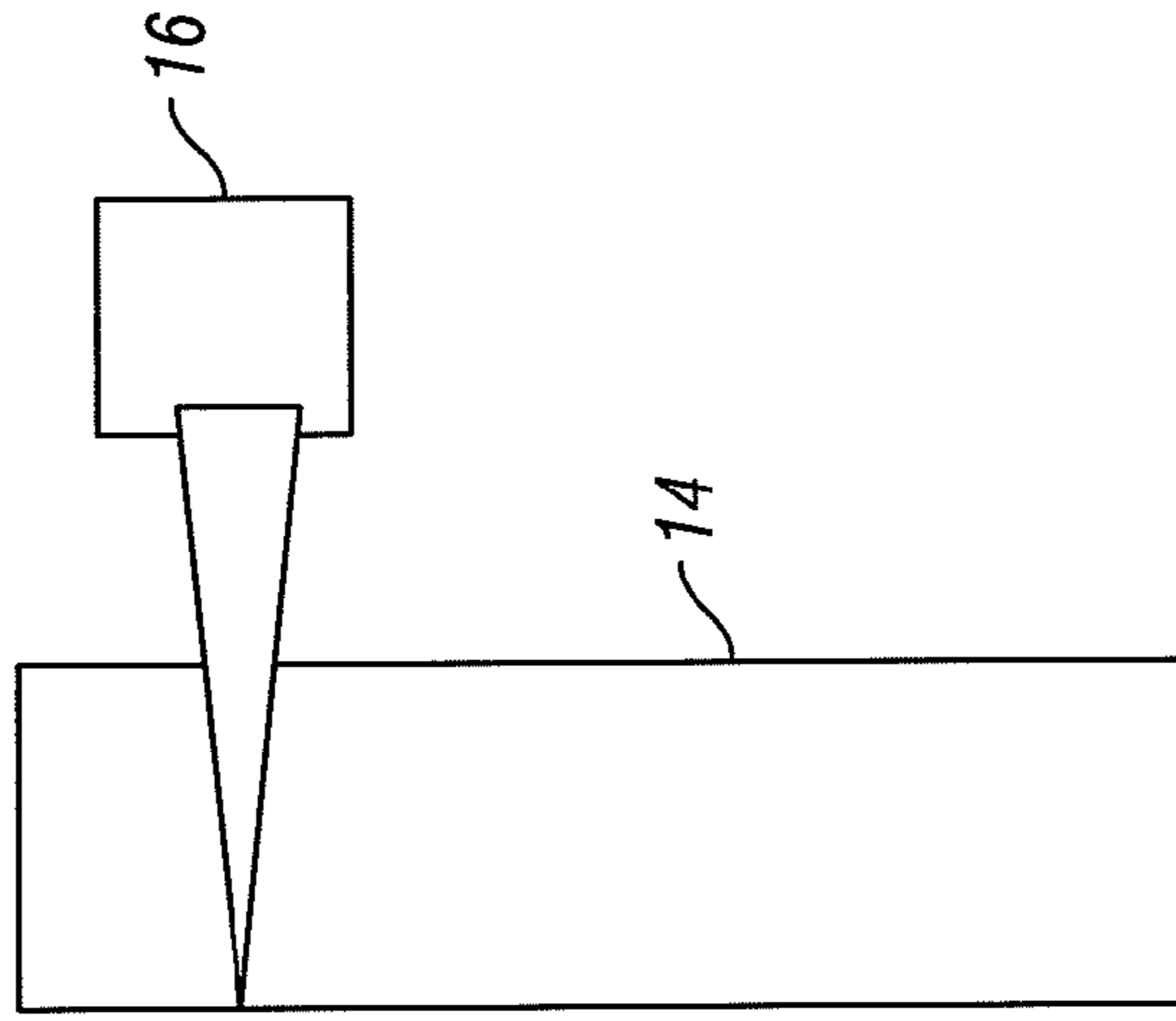
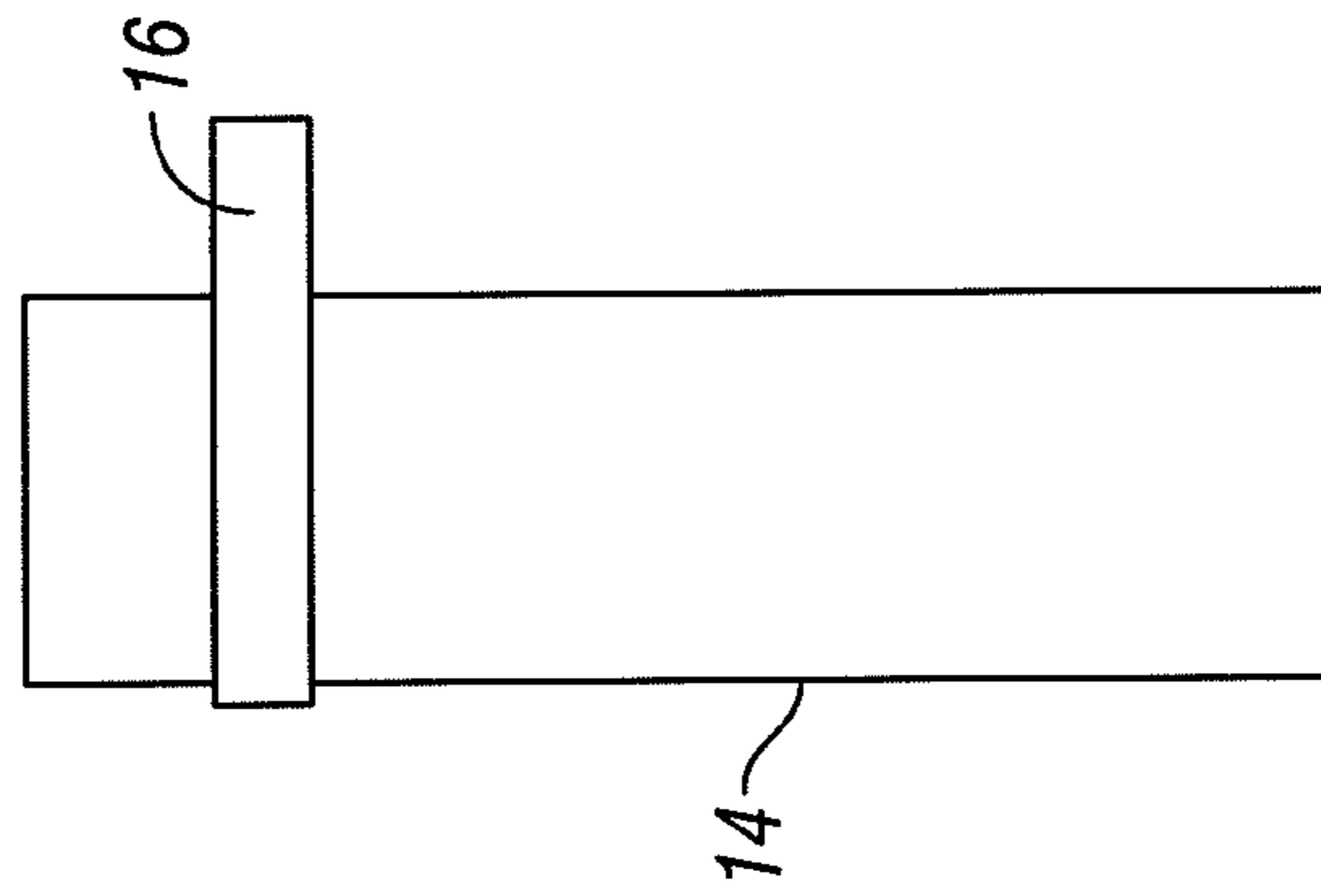
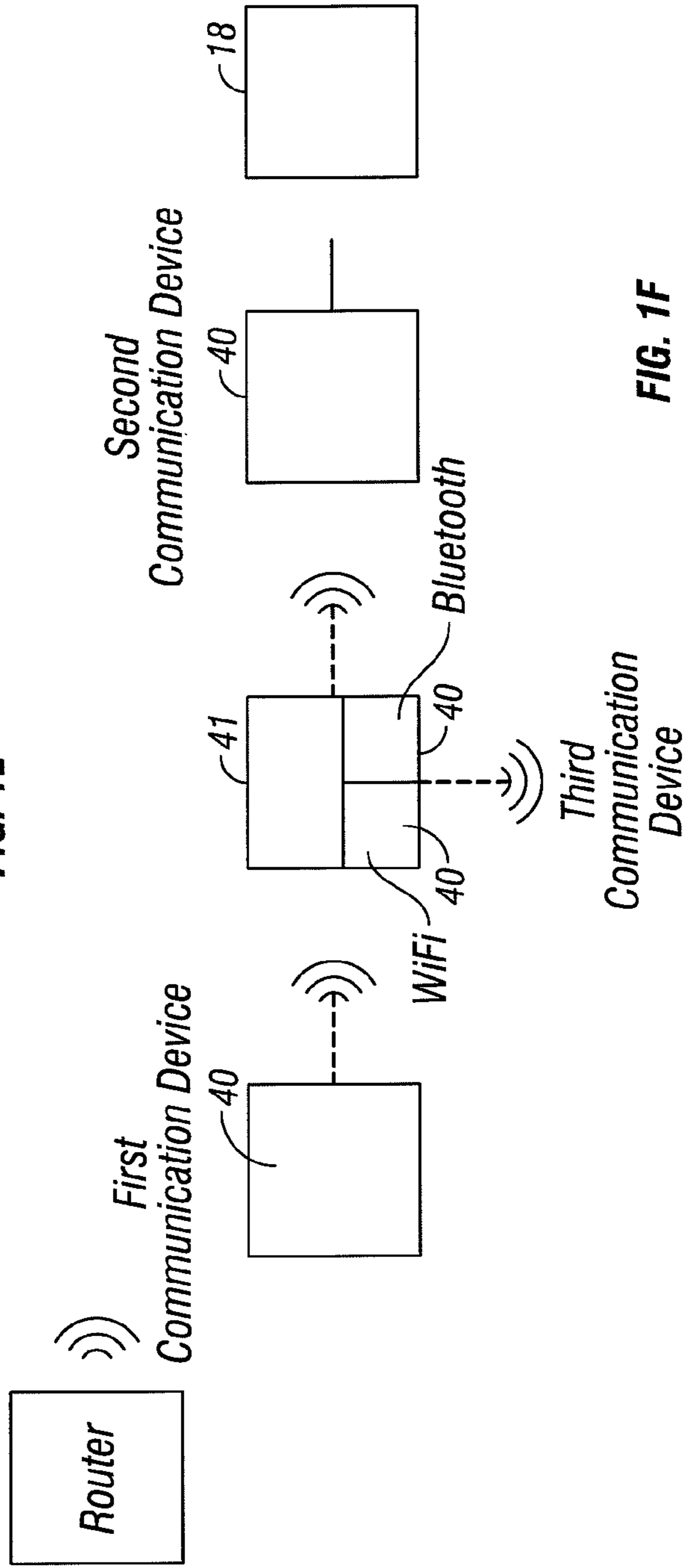
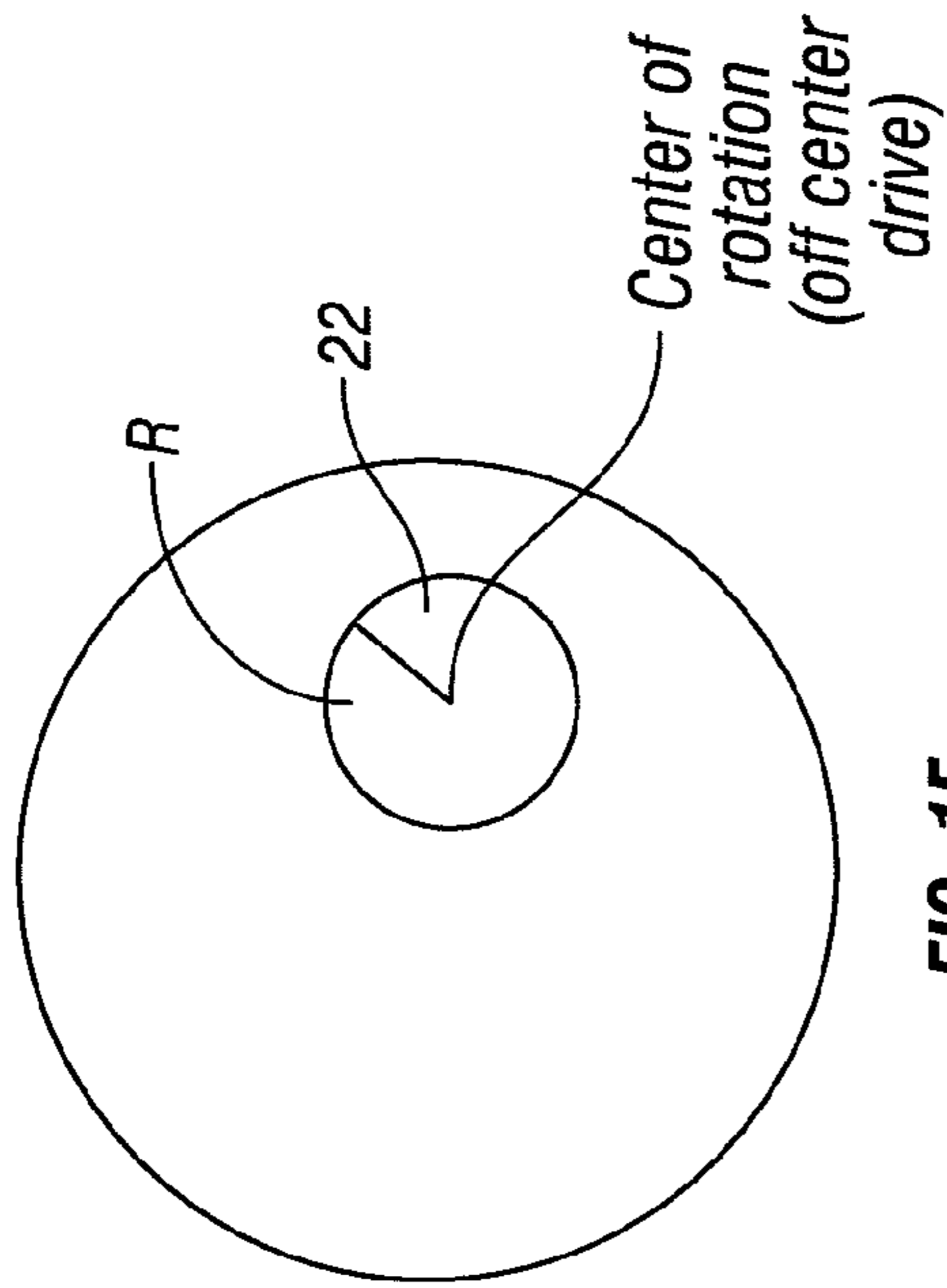


FIG. 1D





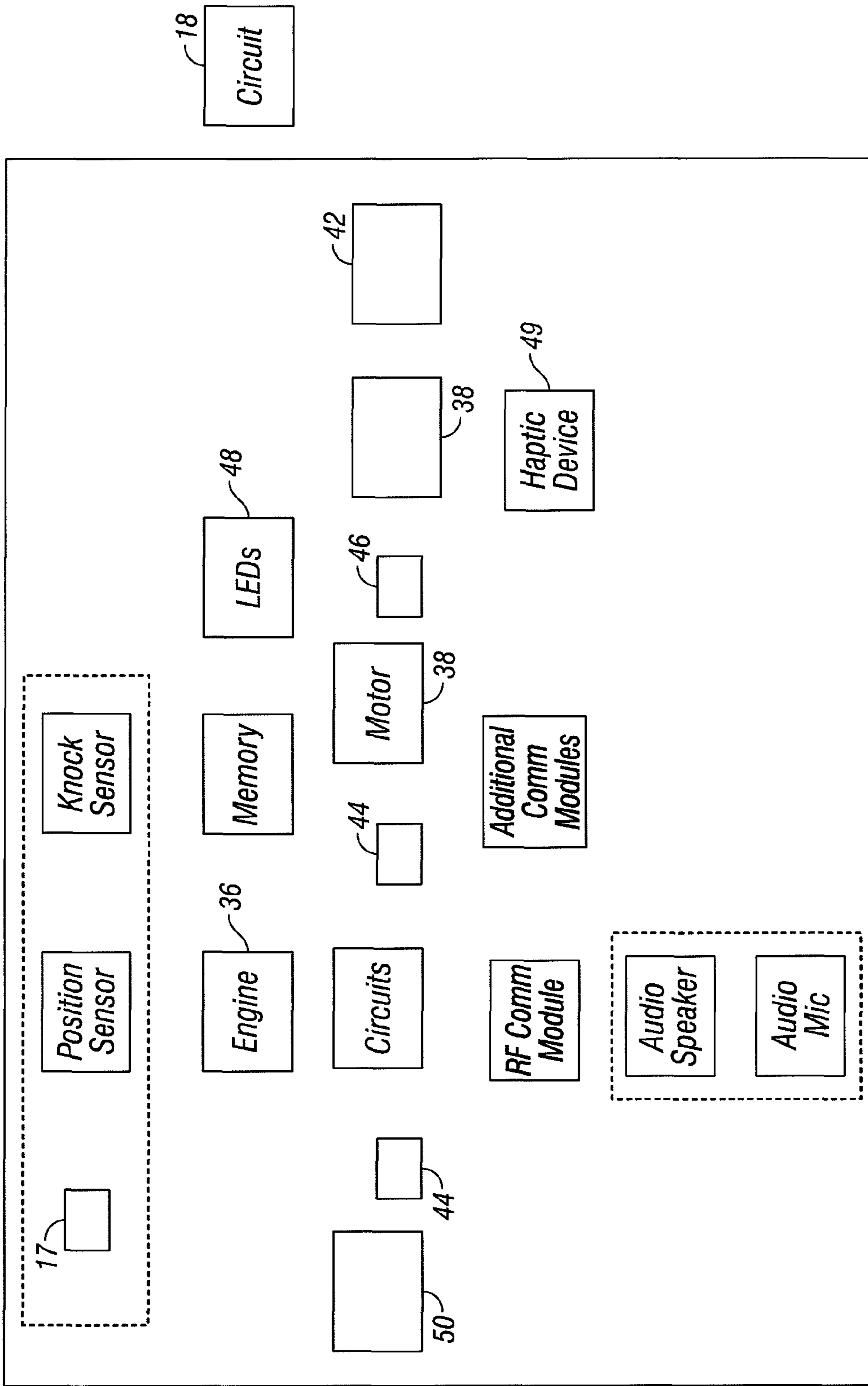


FIG. 1G

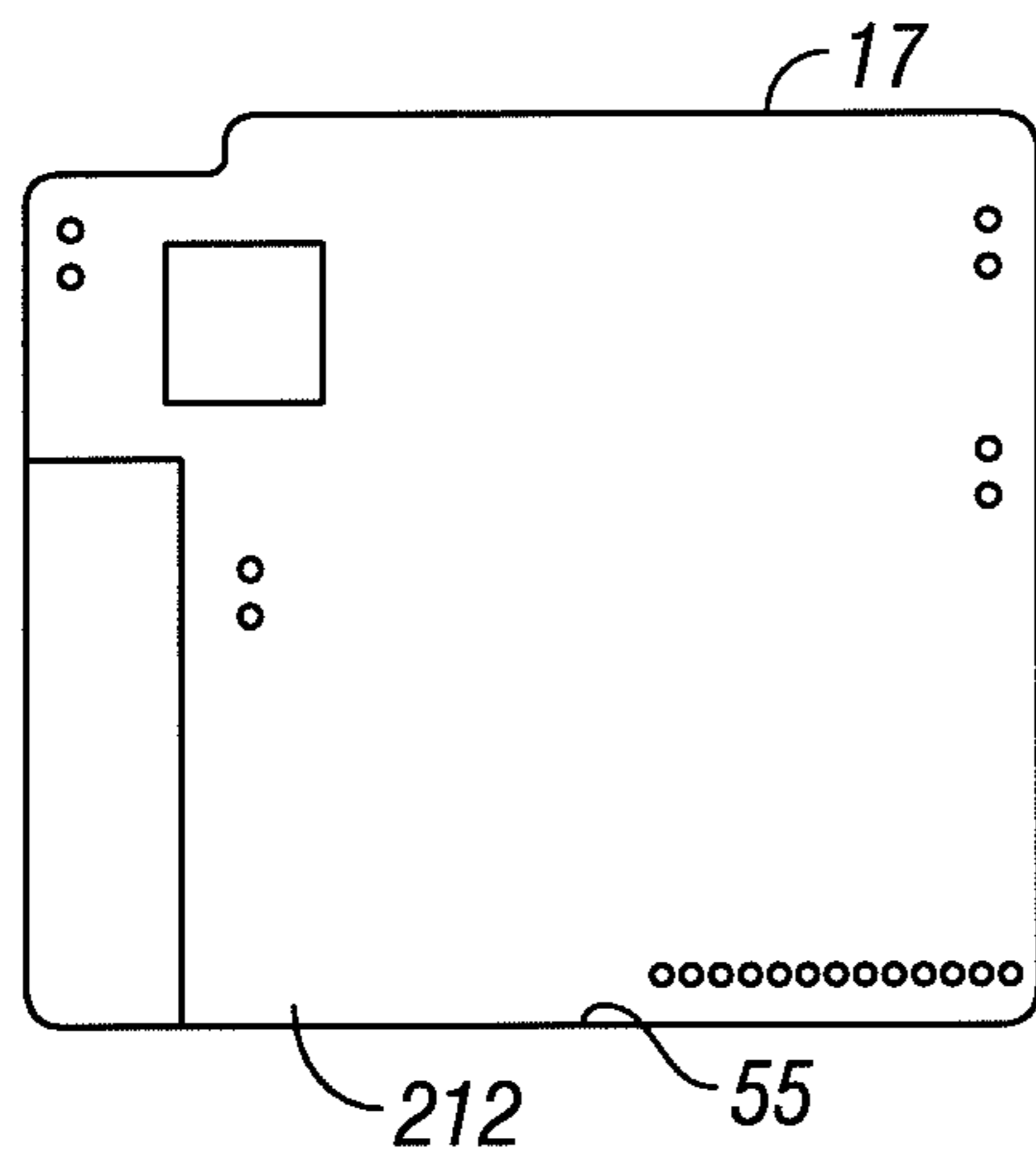


FIG. 2A

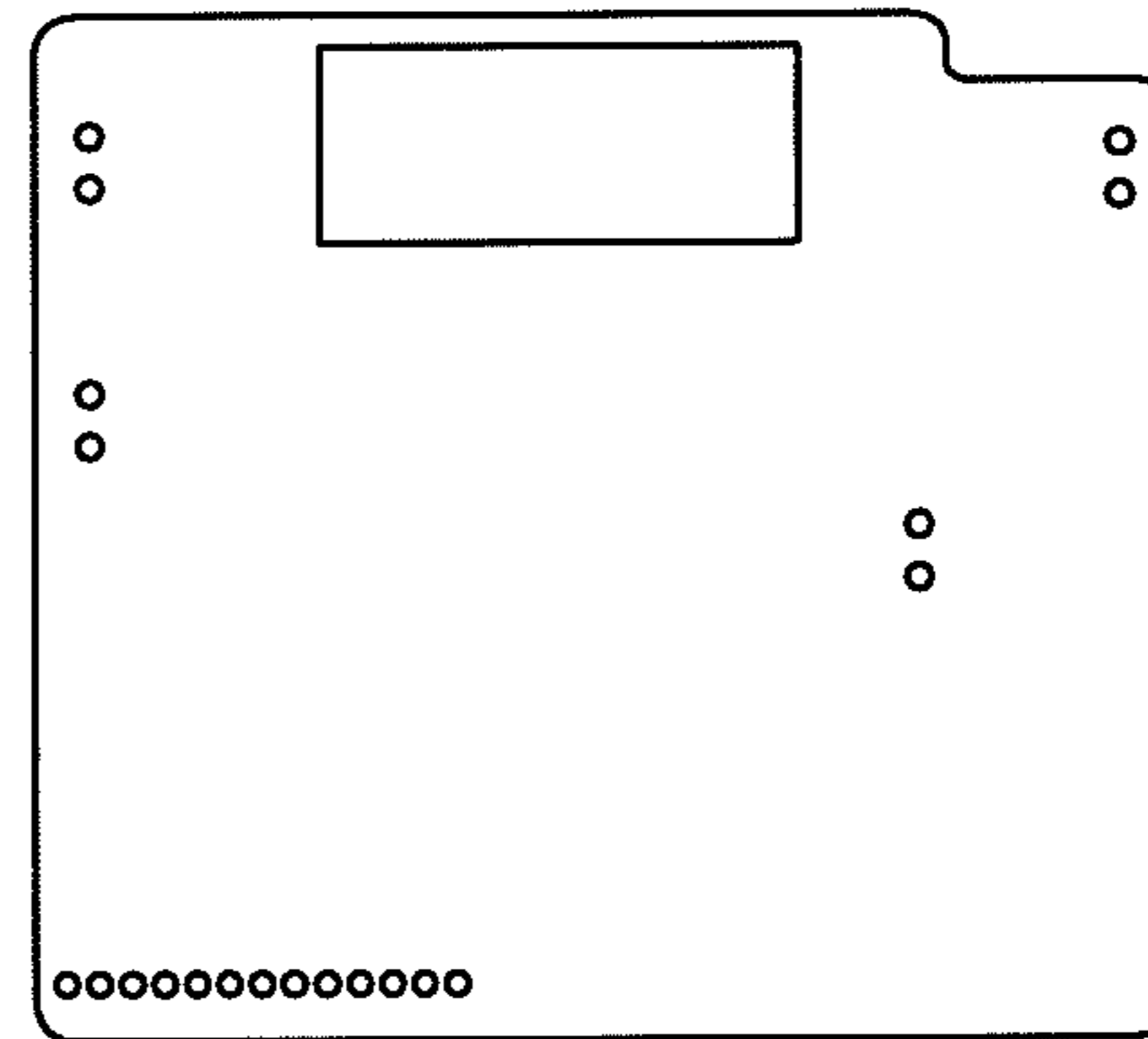


FIG. 2B

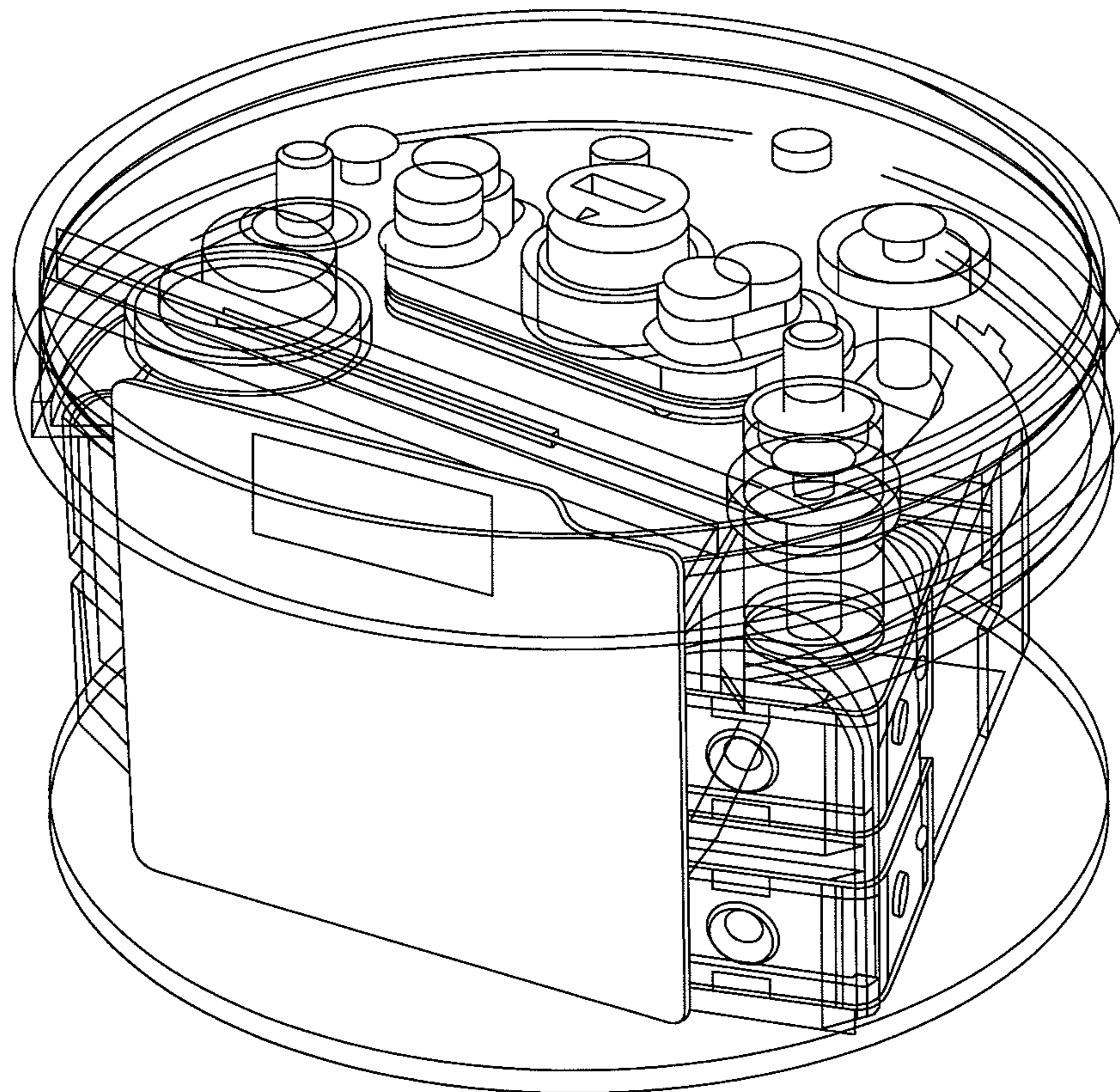


FIG. 2C

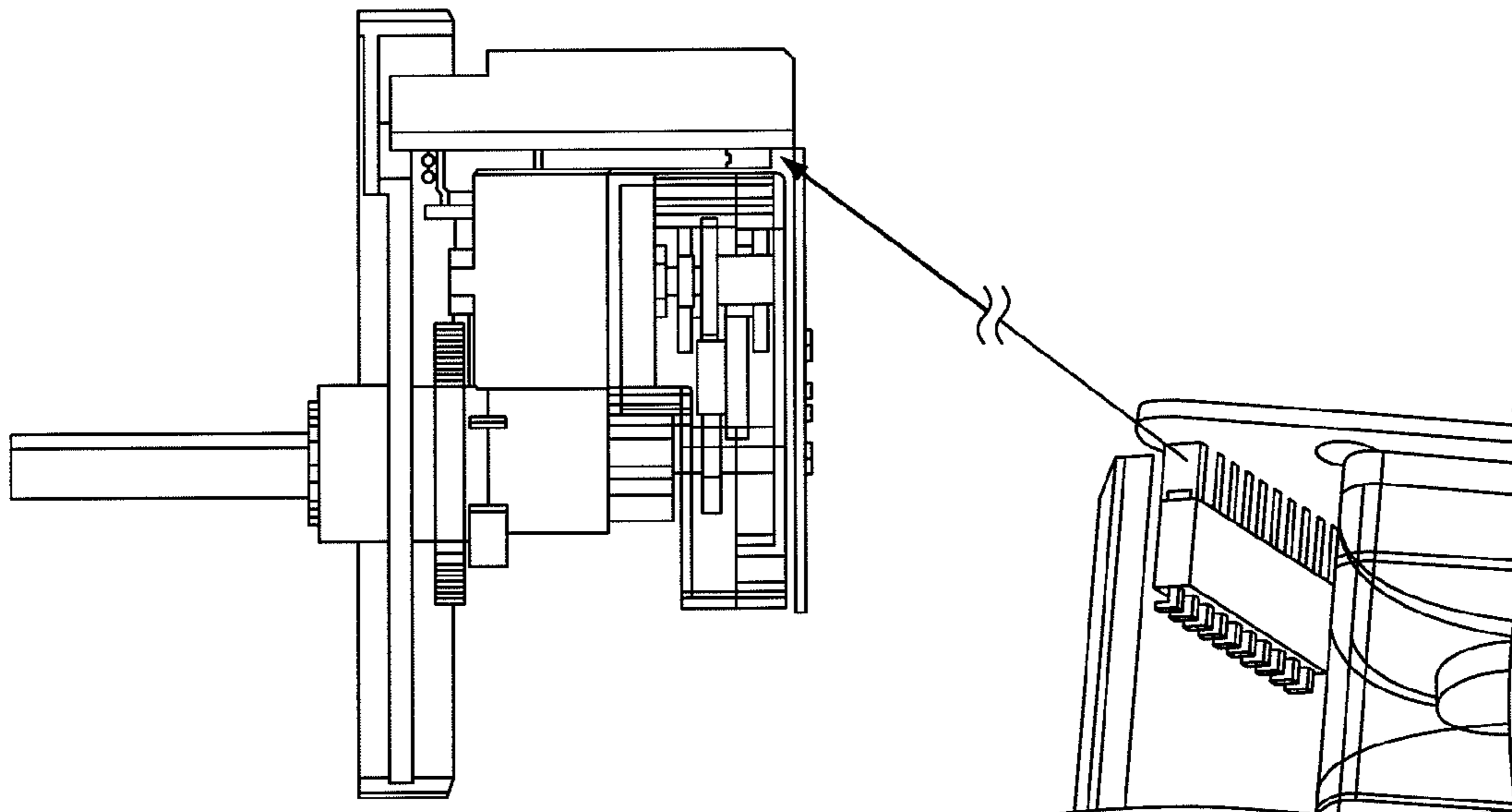


FIG. 2D

FIG. 2E

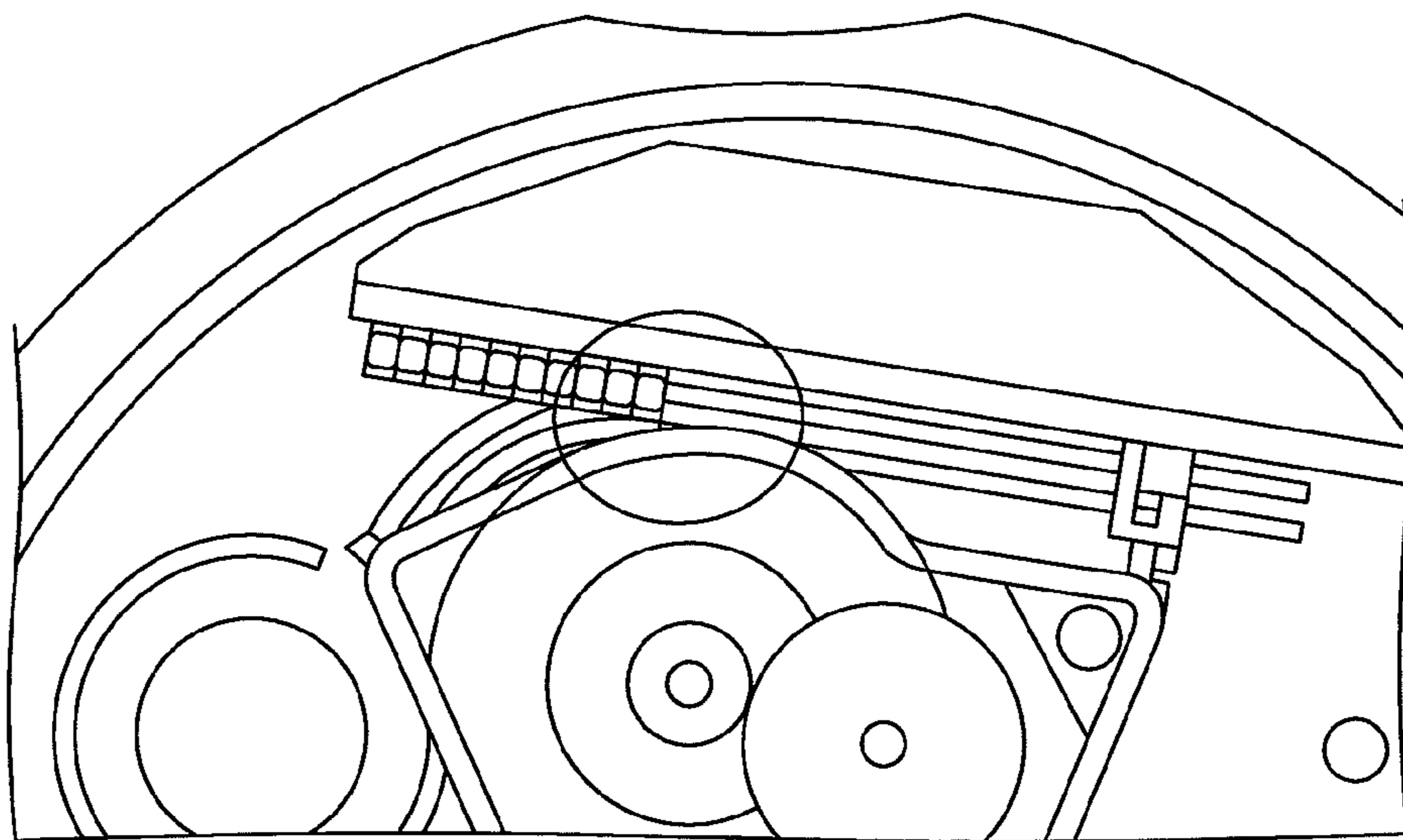


FIG. 2F

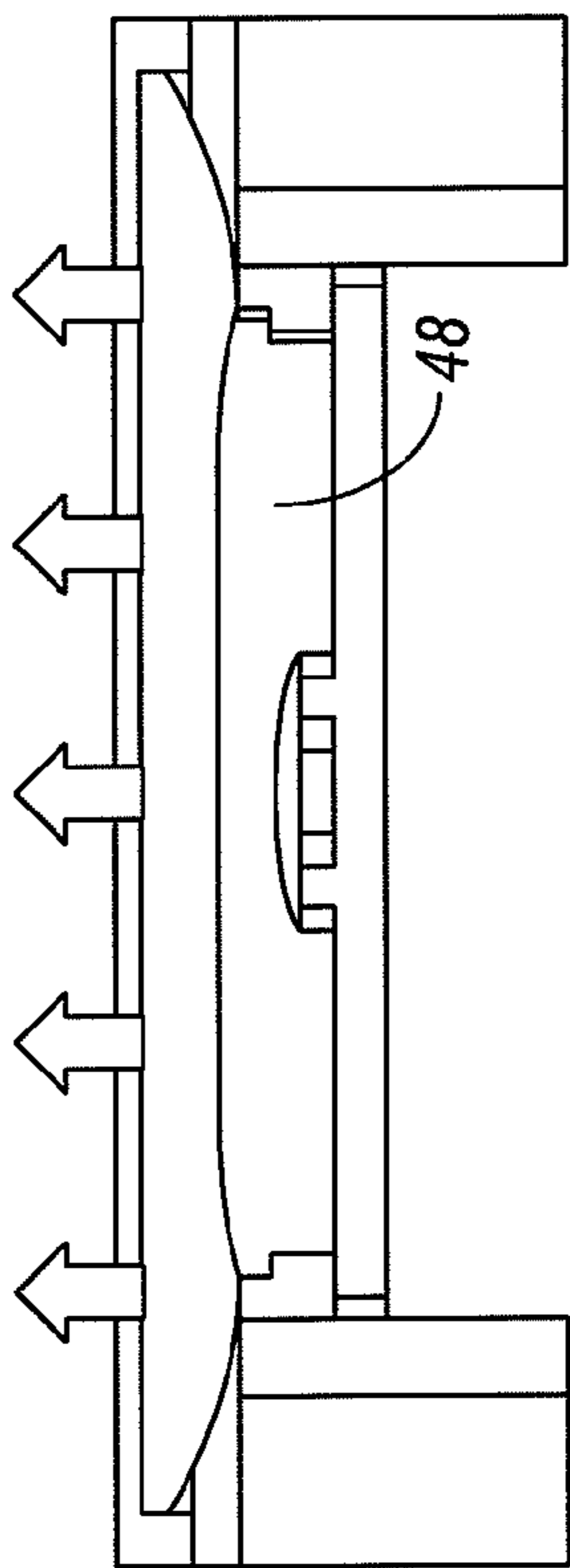


FIG. 3B

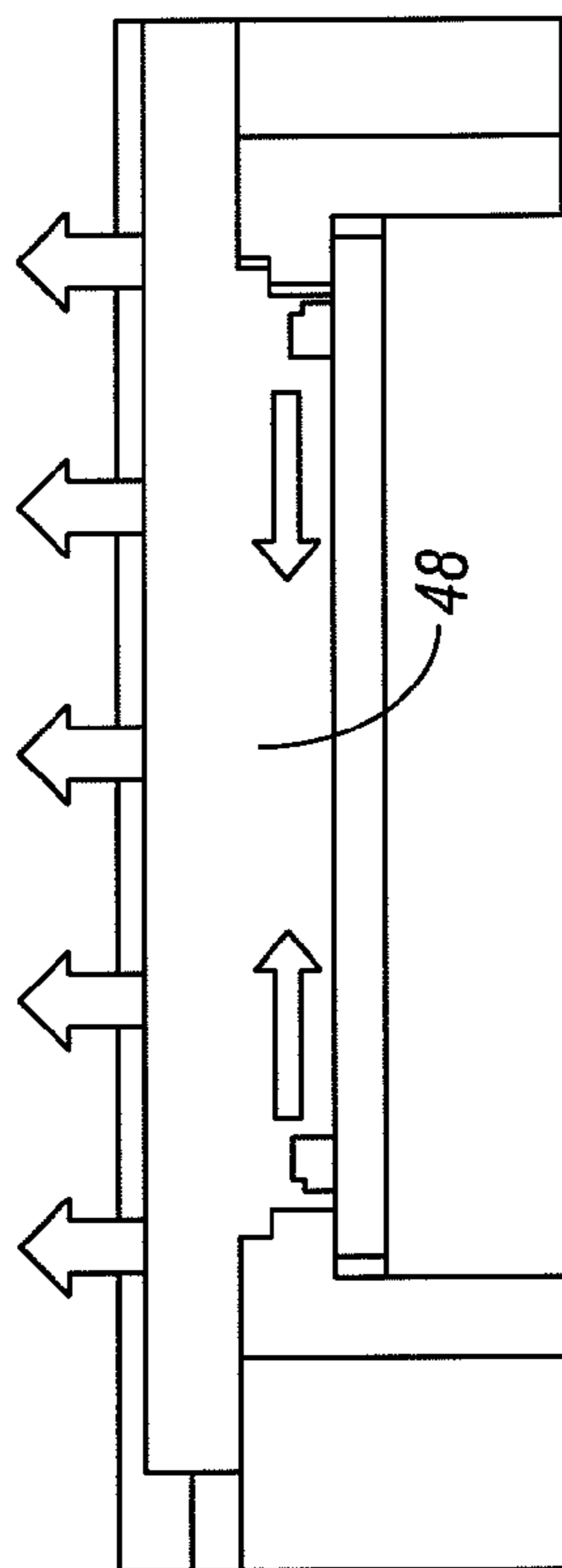


FIG. 3A

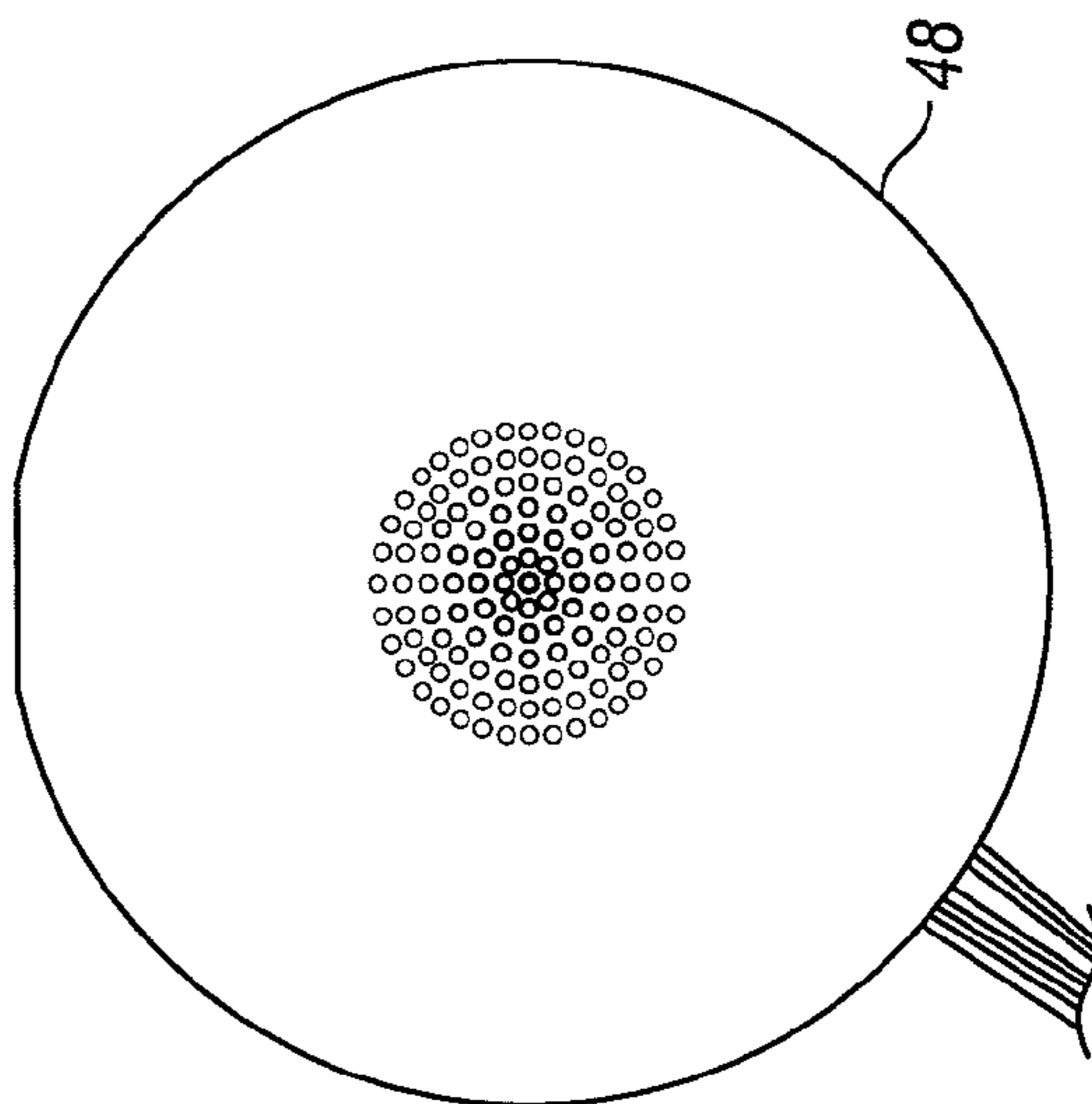


FIG. 3D

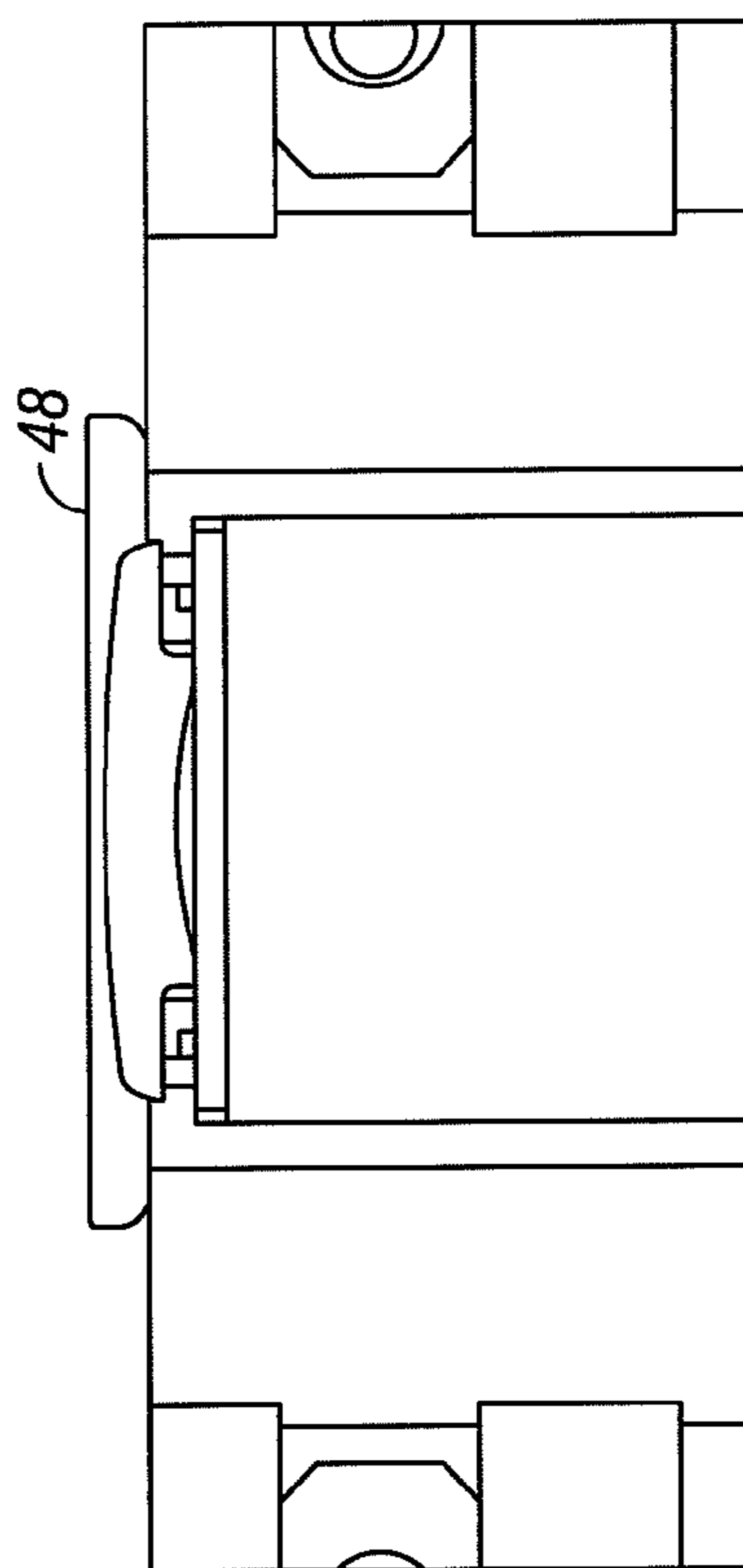


FIG. 3C

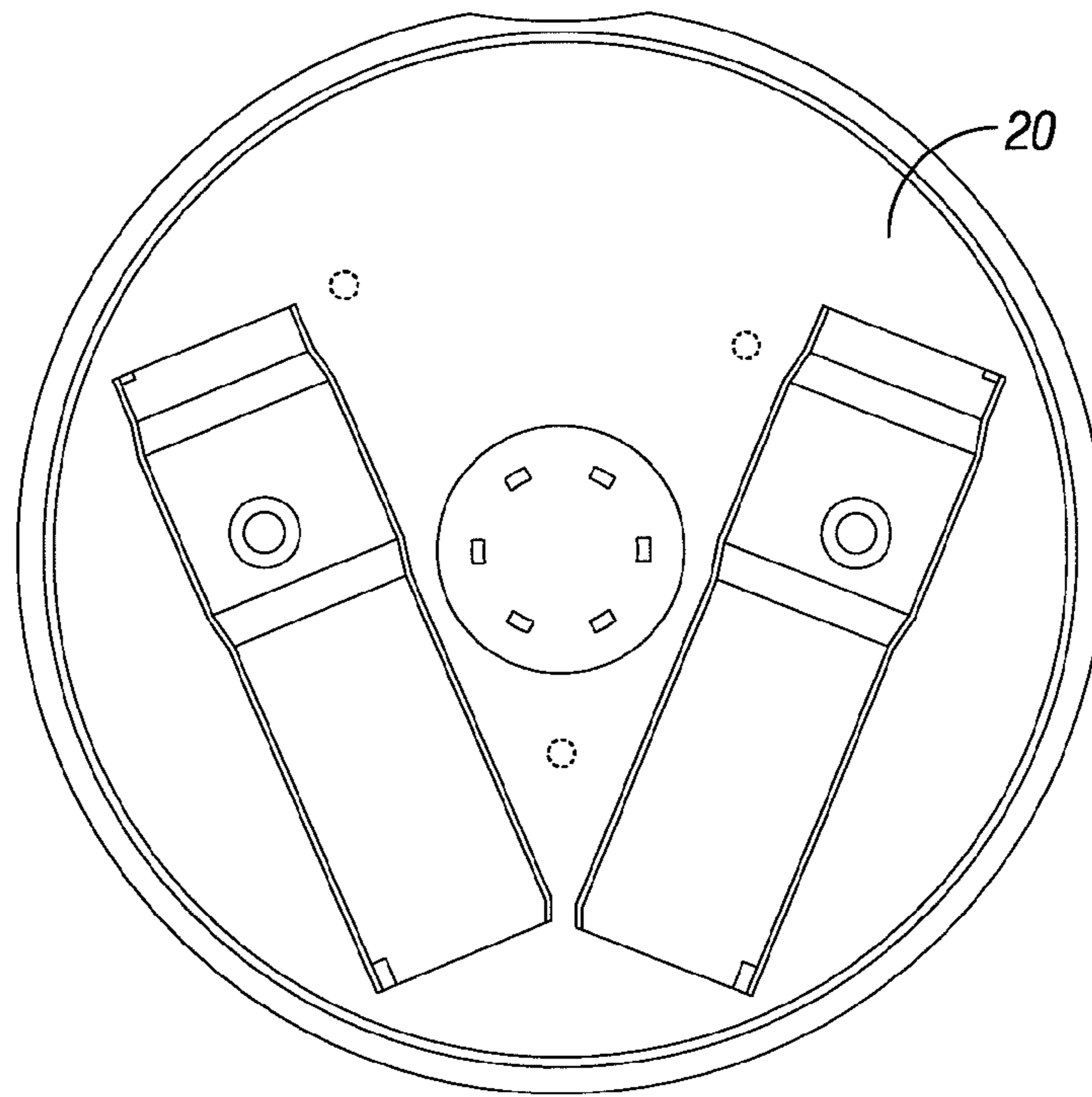


FIG. 4A

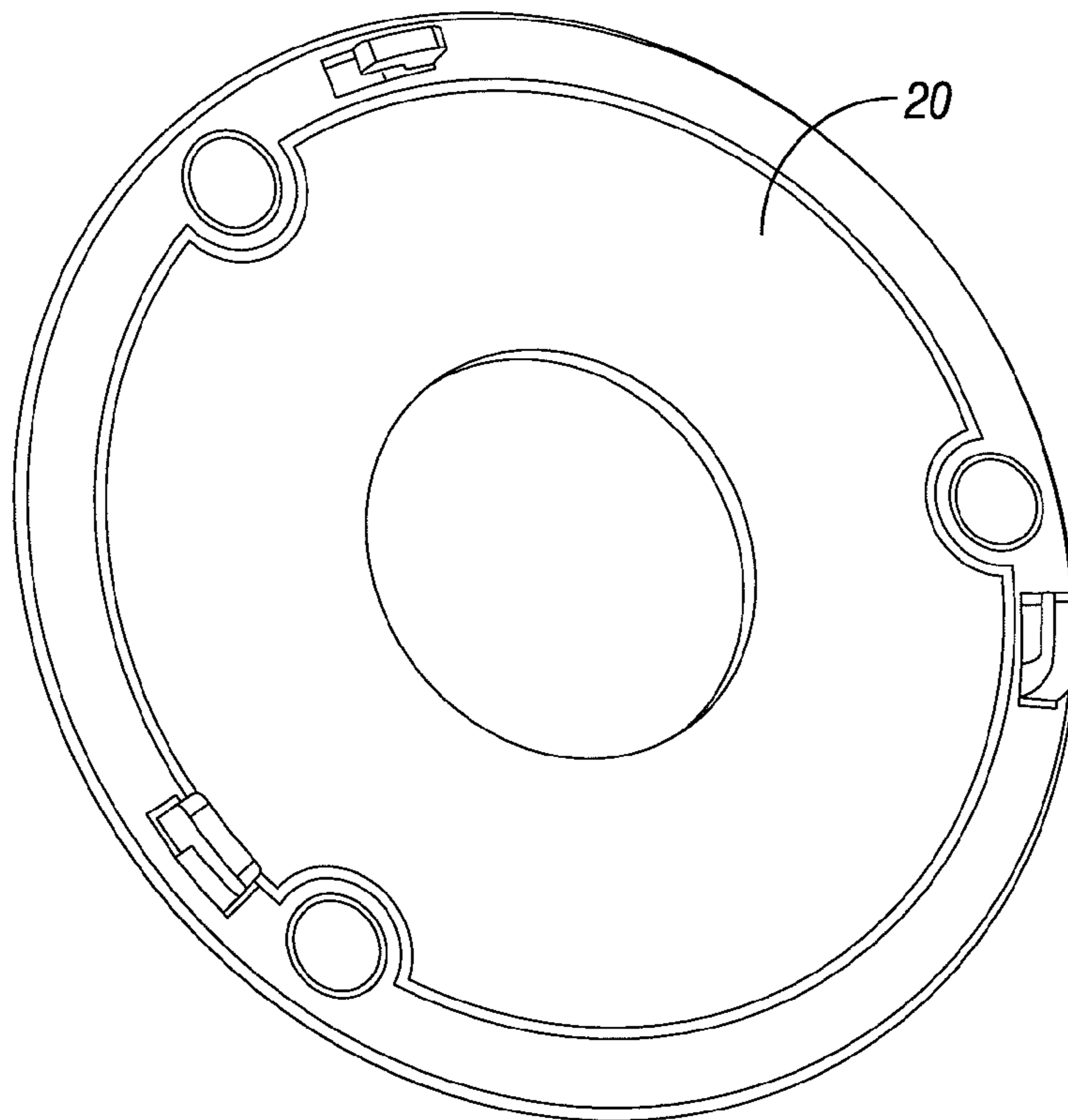


FIG. 4B

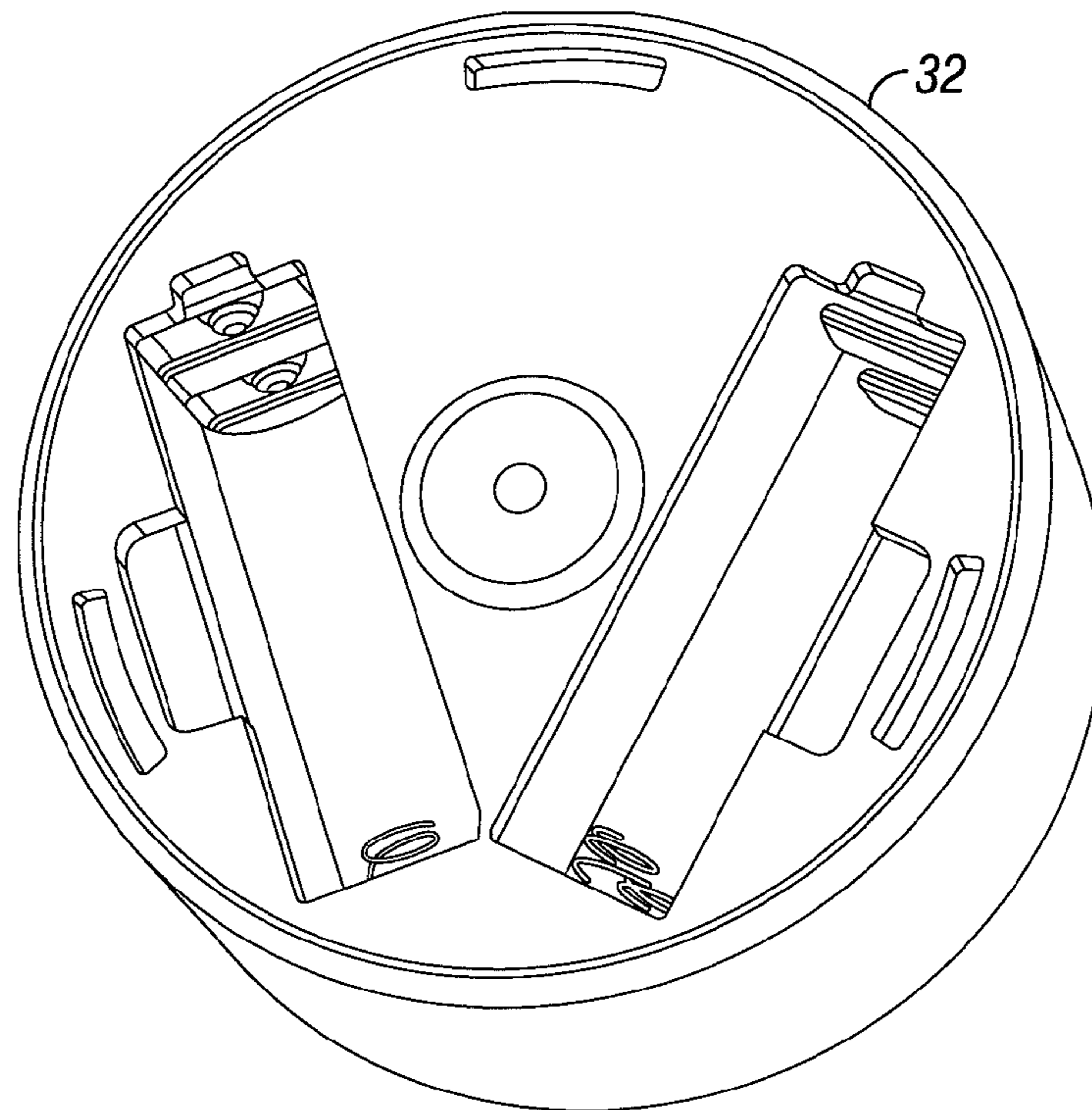


FIG. 4C

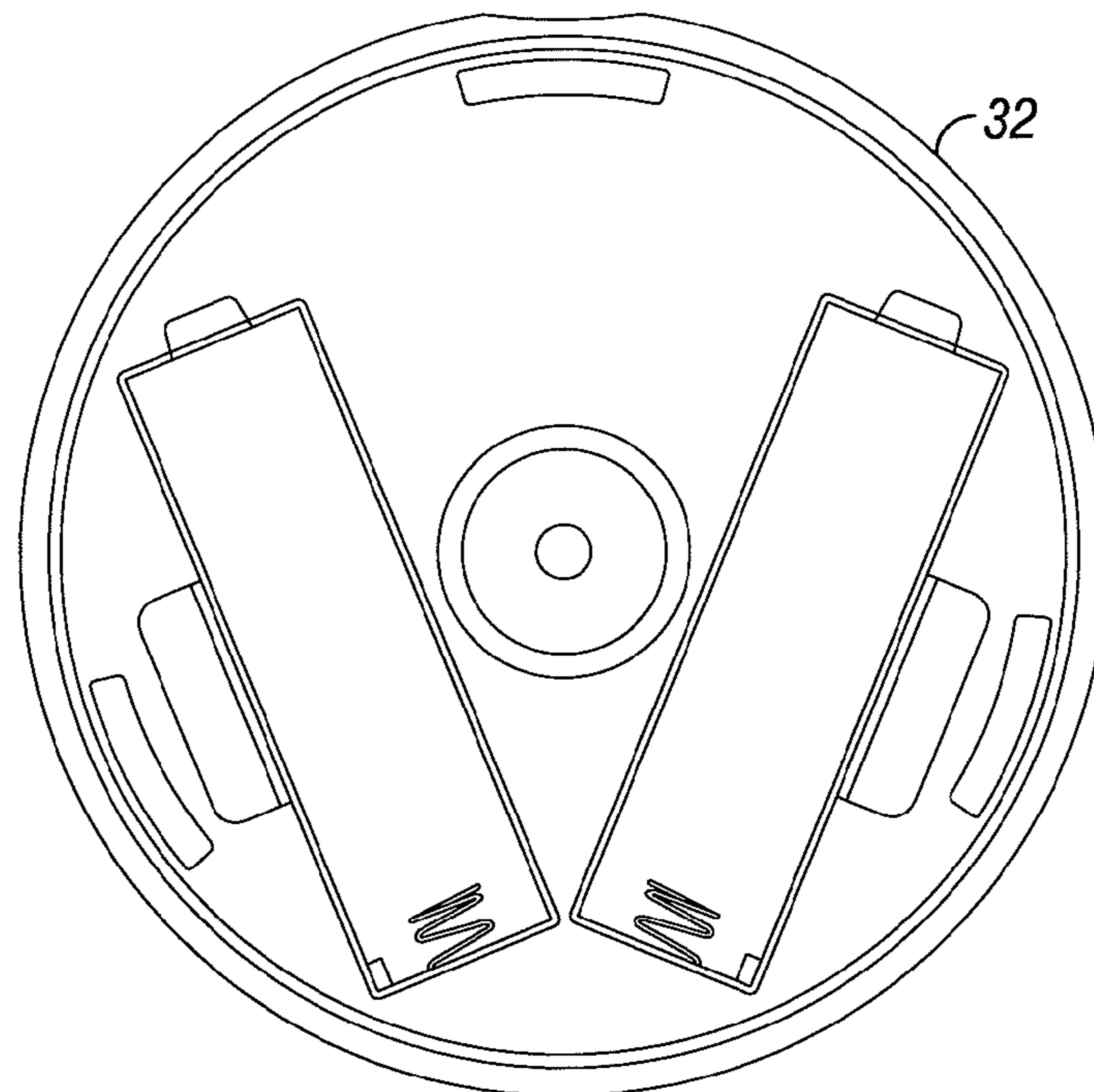


FIG. 4D

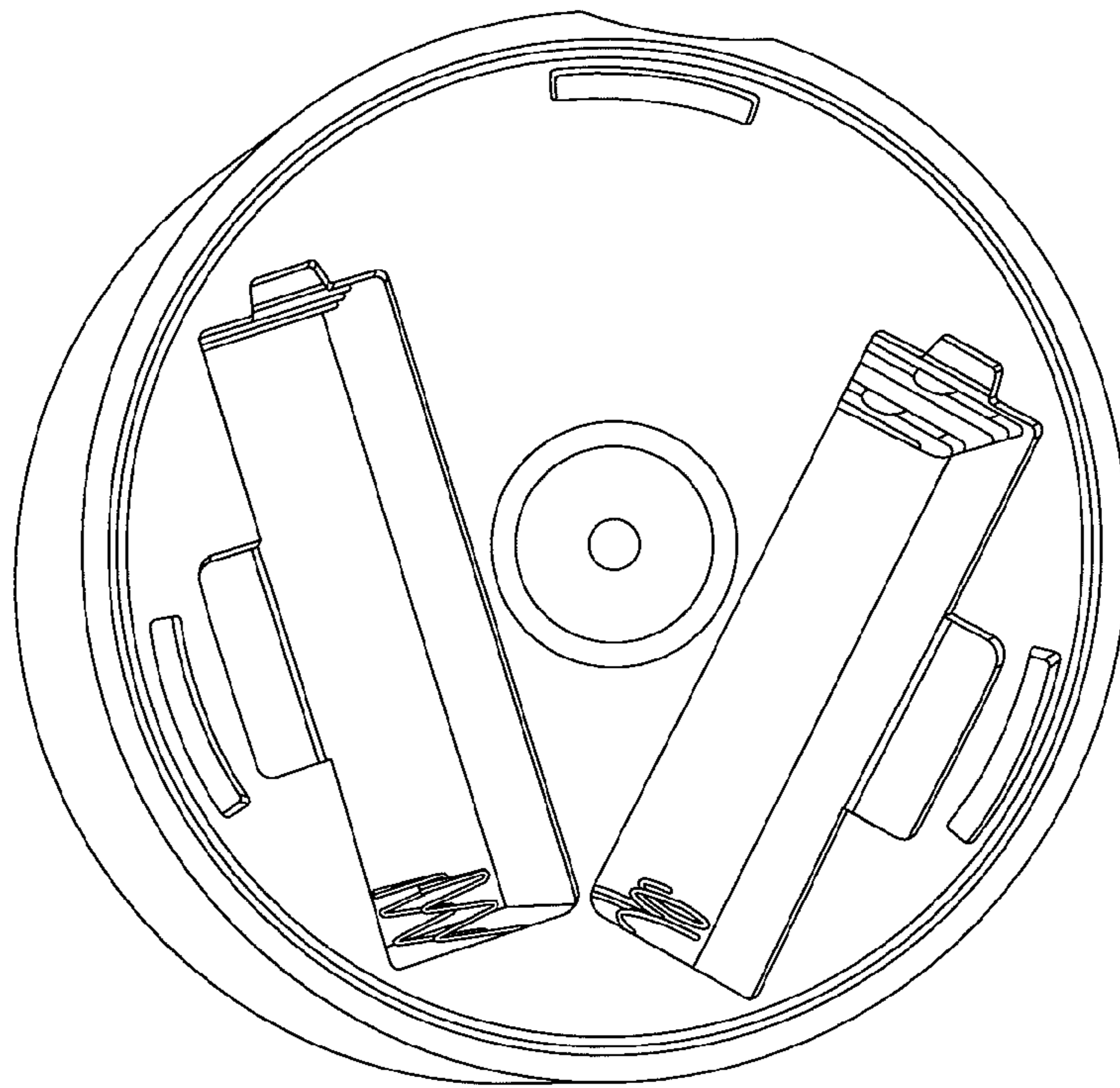


FIG. 5A

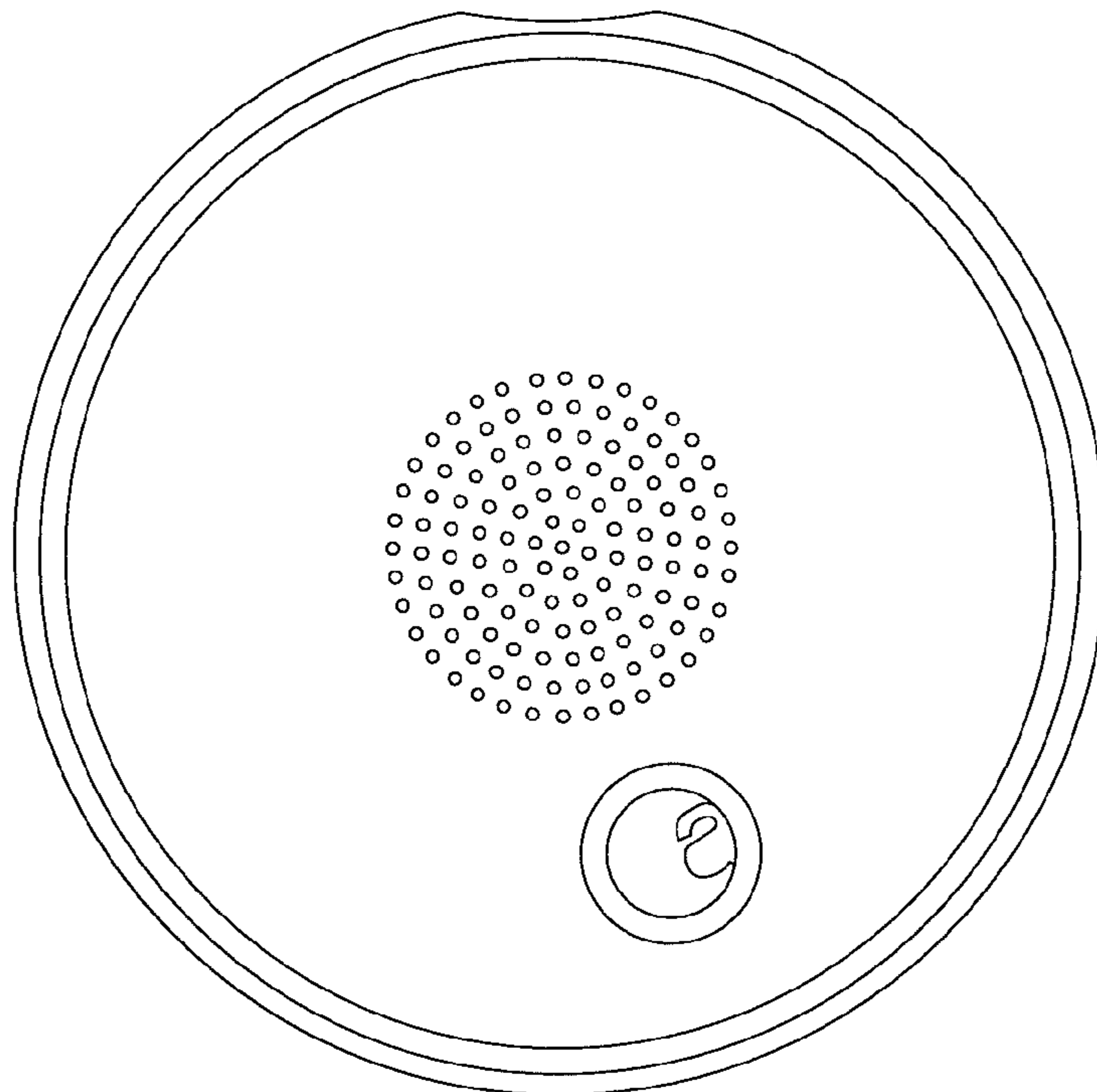


FIG. 5B

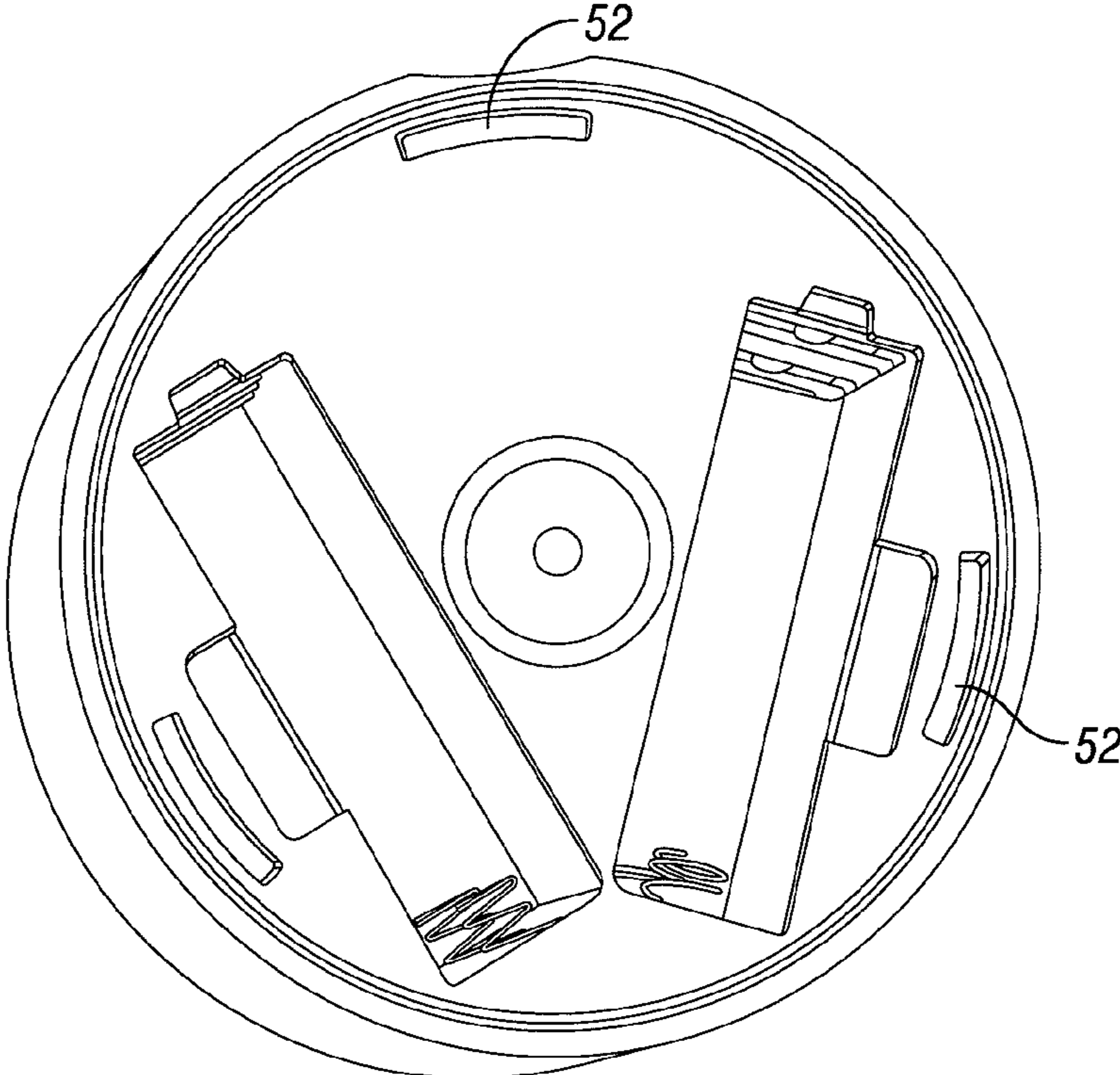


FIG. 6A

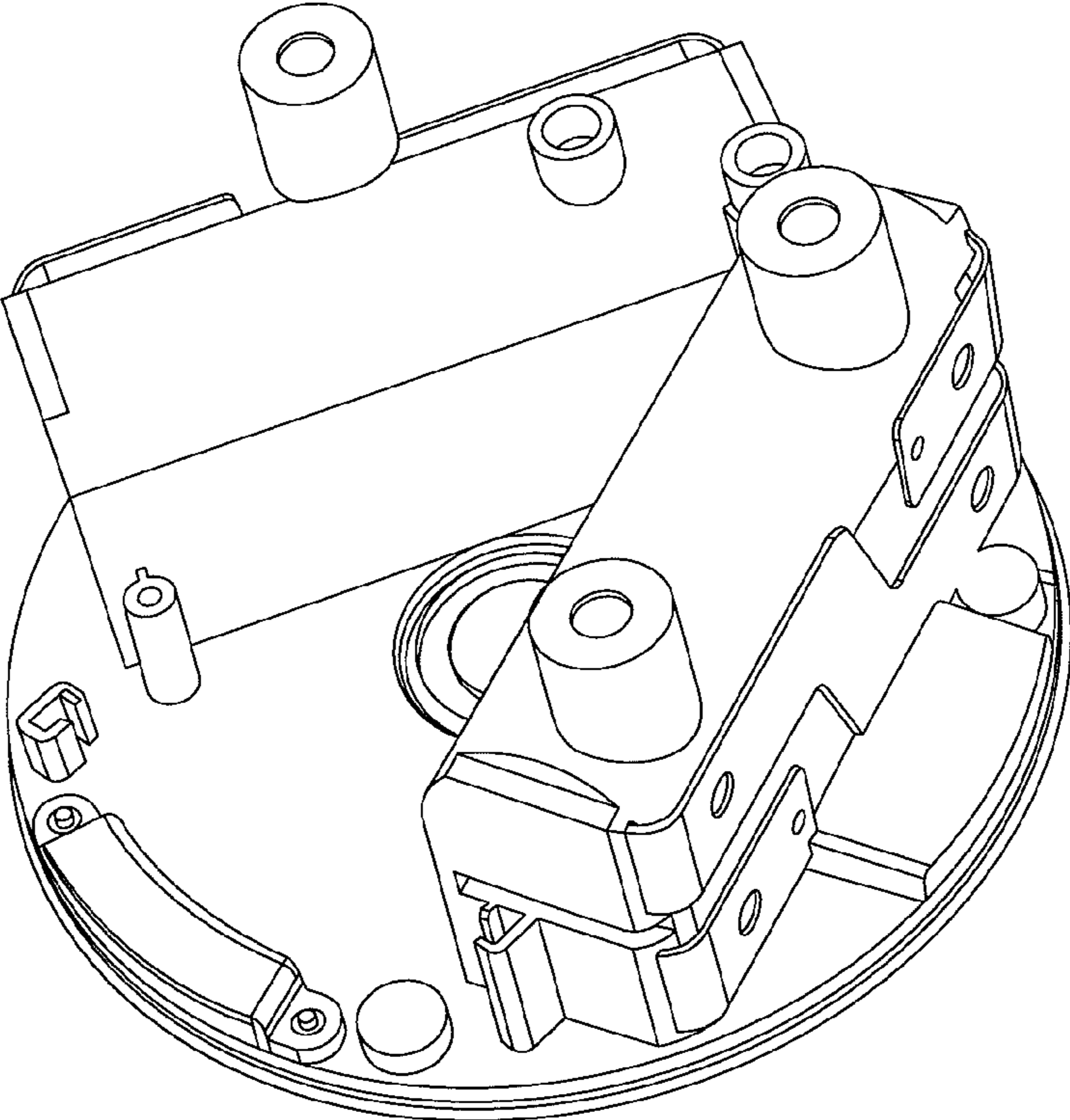


FIG. 6B

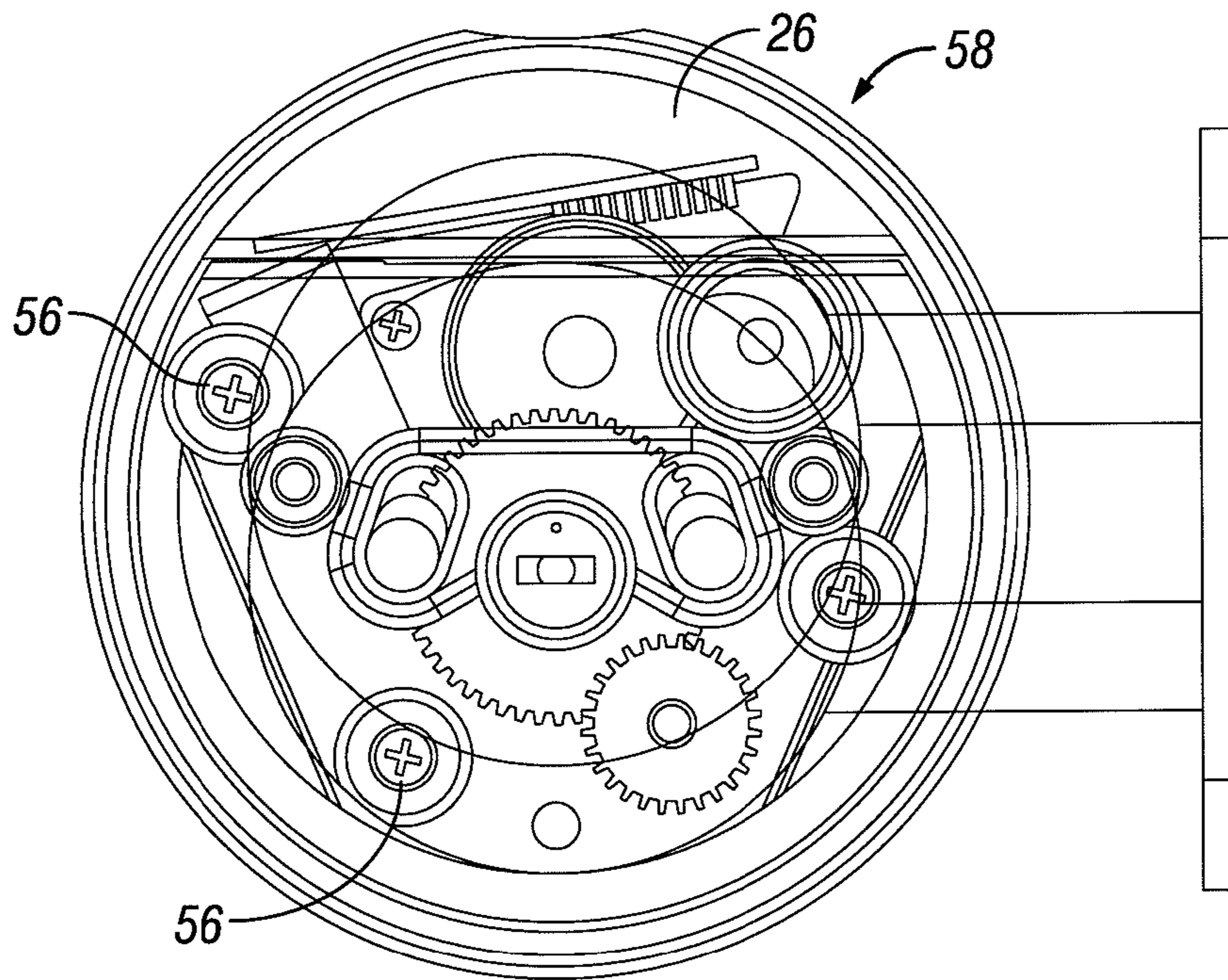


FIG. 7A

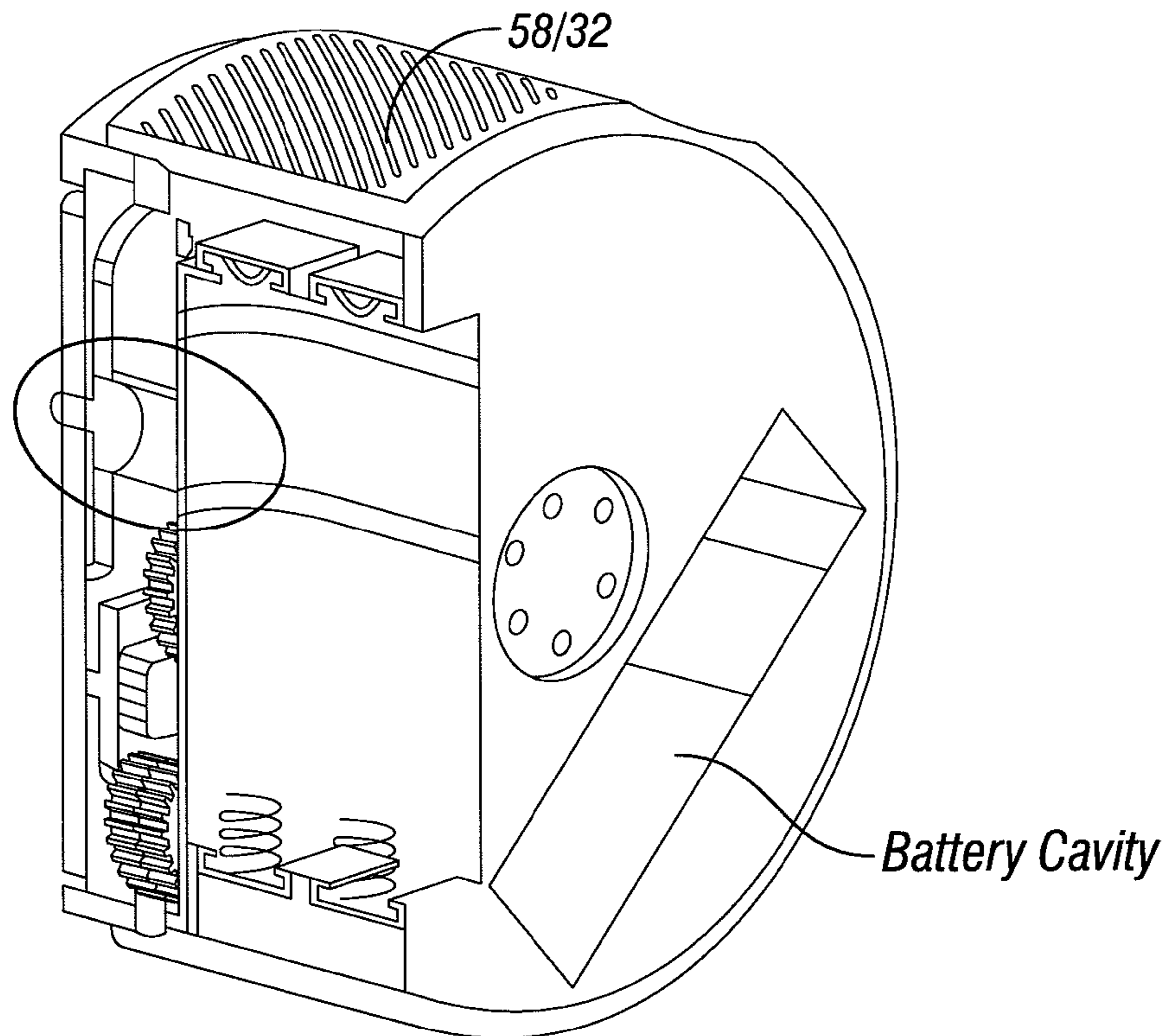


FIG. 7B

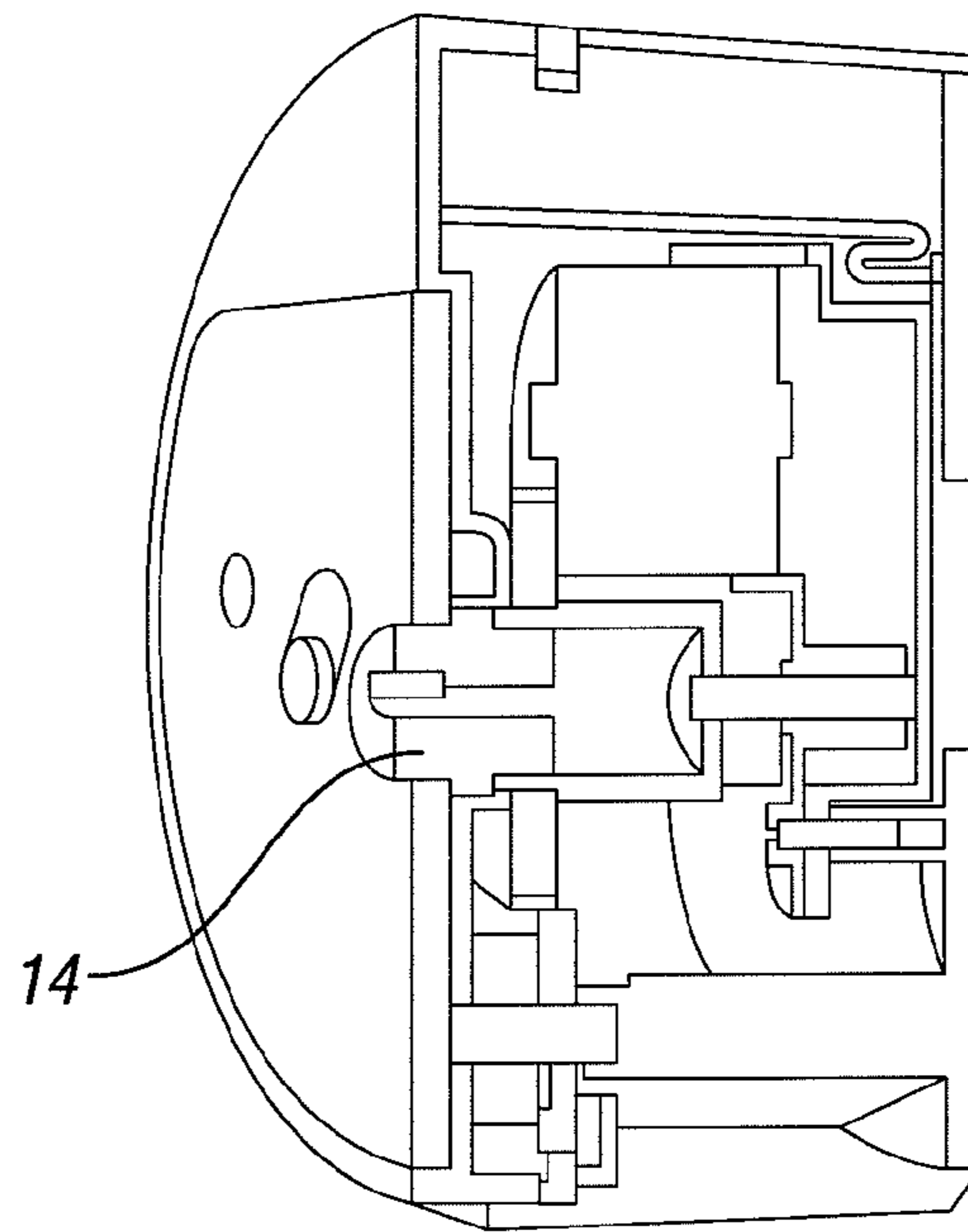


FIG. 7C

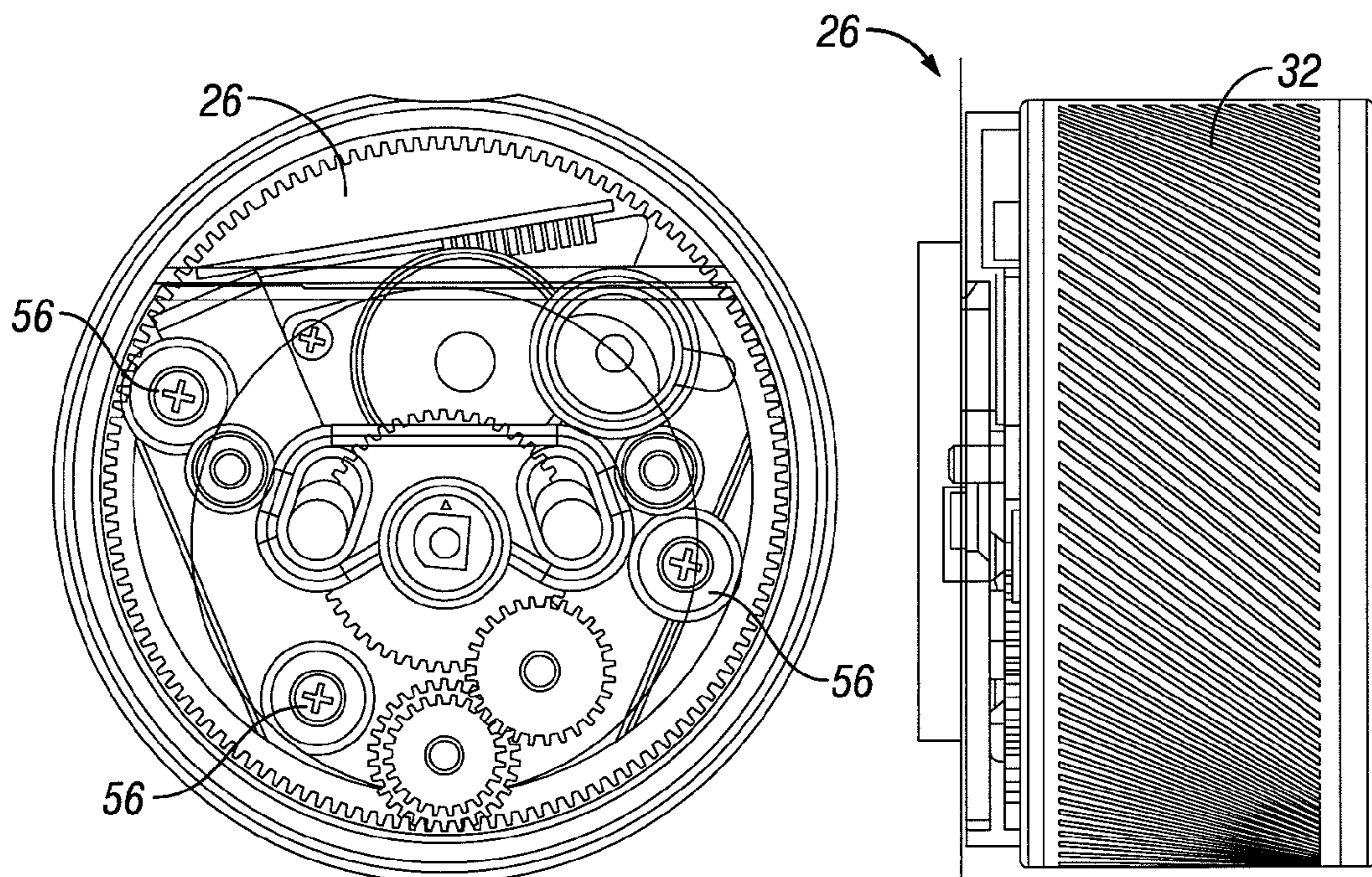


FIG. 7D

FIG. 7E

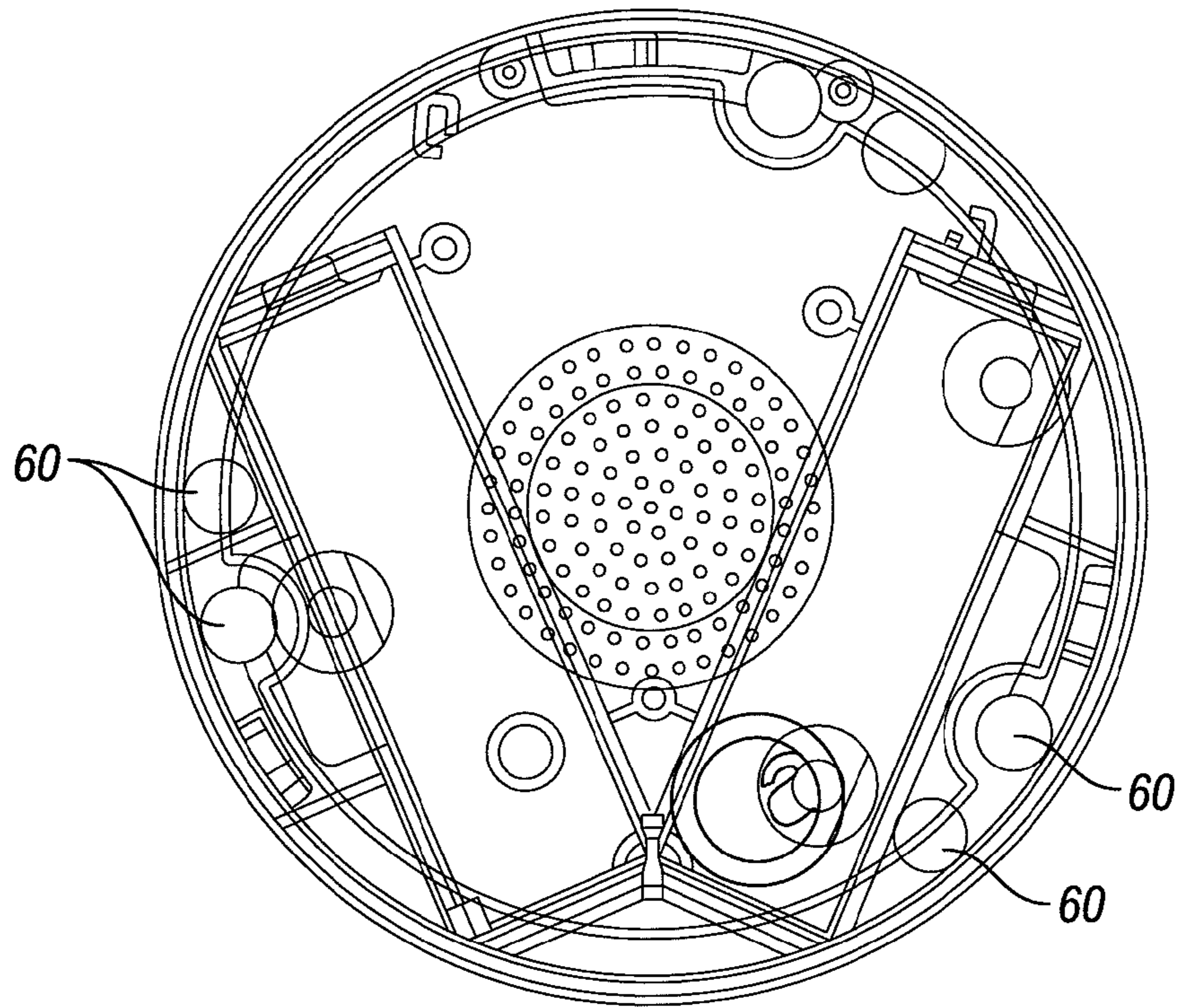


FIG. 8A

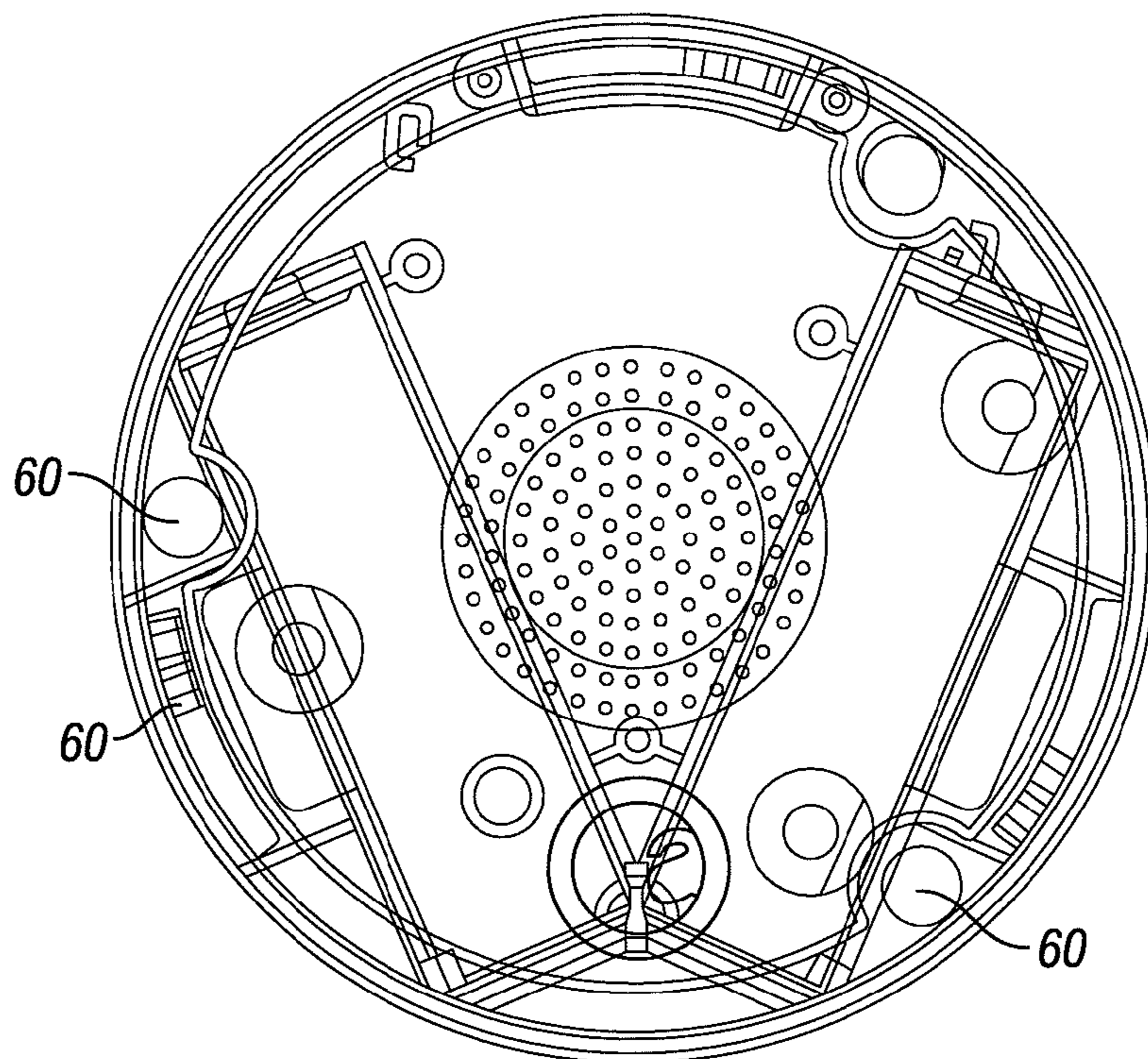


FIG. 8B

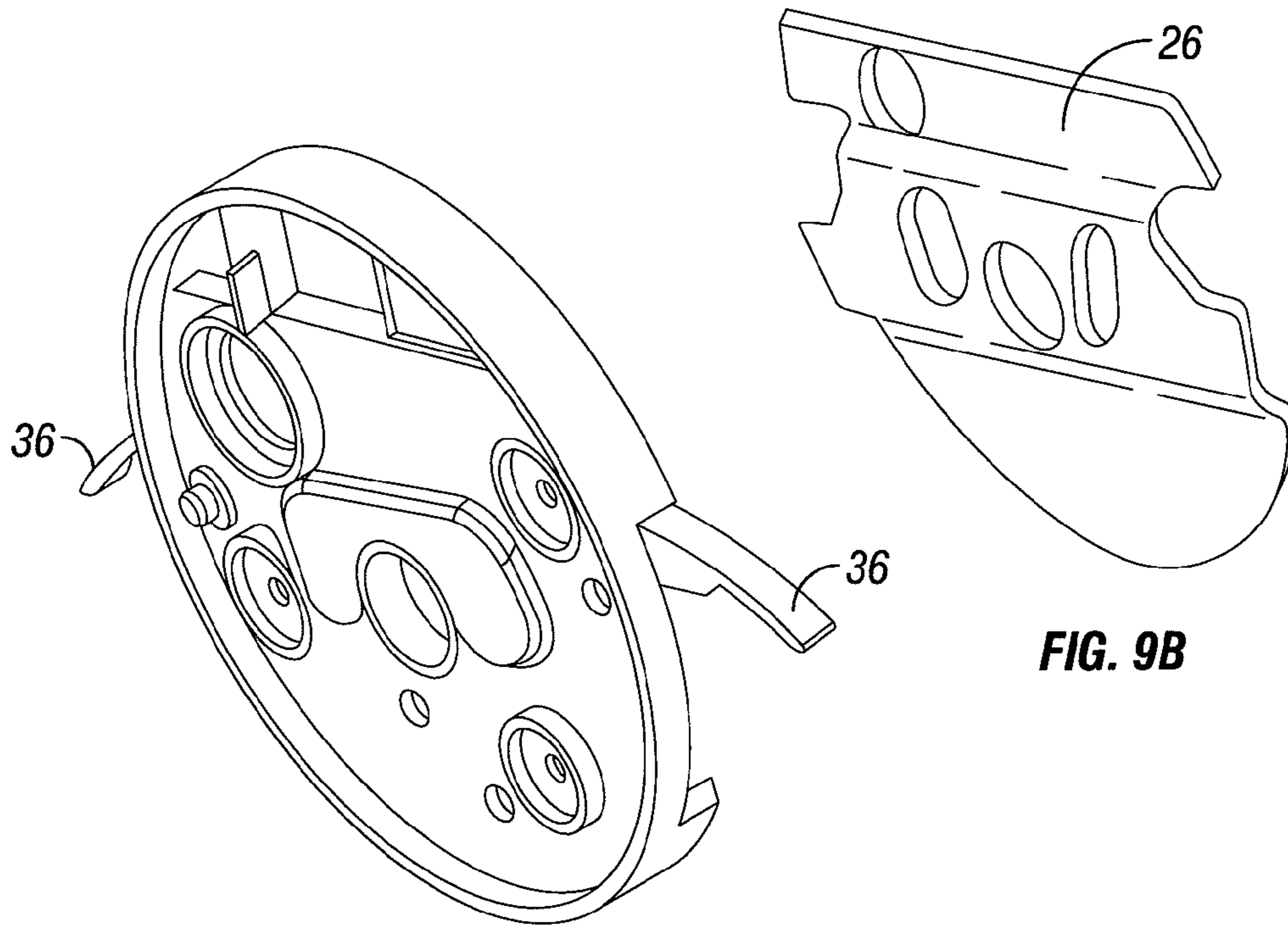


FIG. 9A

FIG. 9B

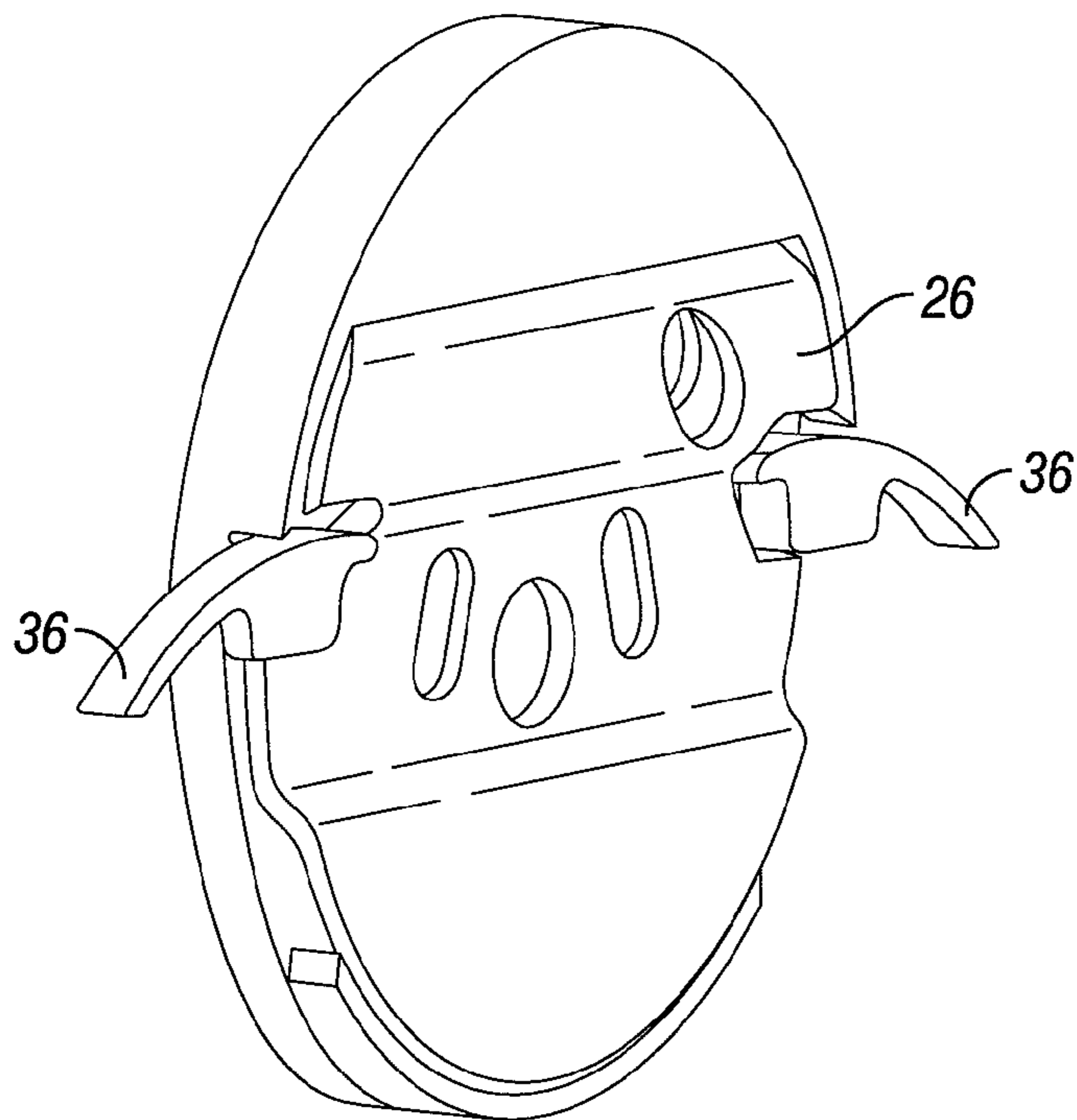


FIG. 9C

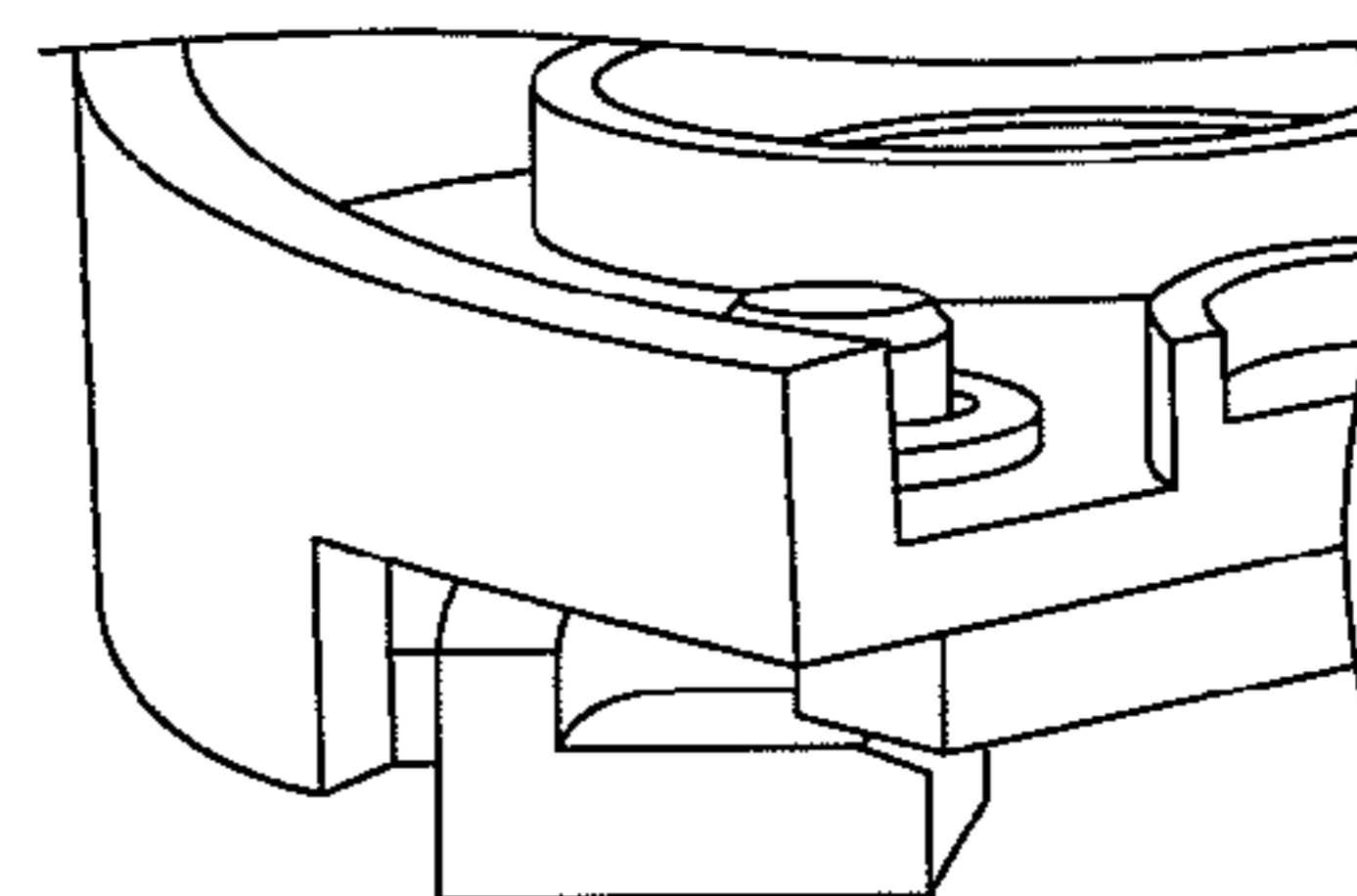


FIG. 9E

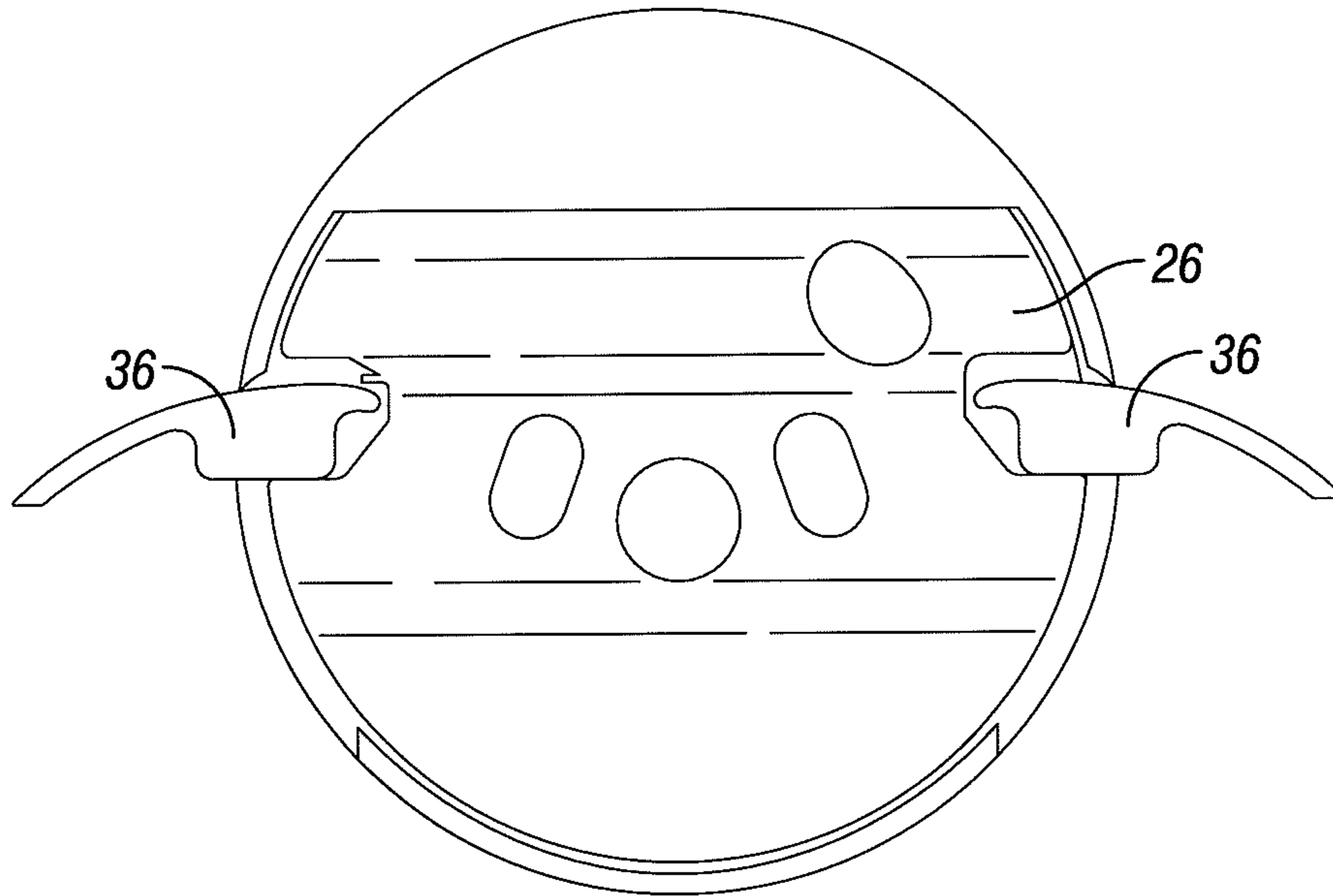


FIG. 9D

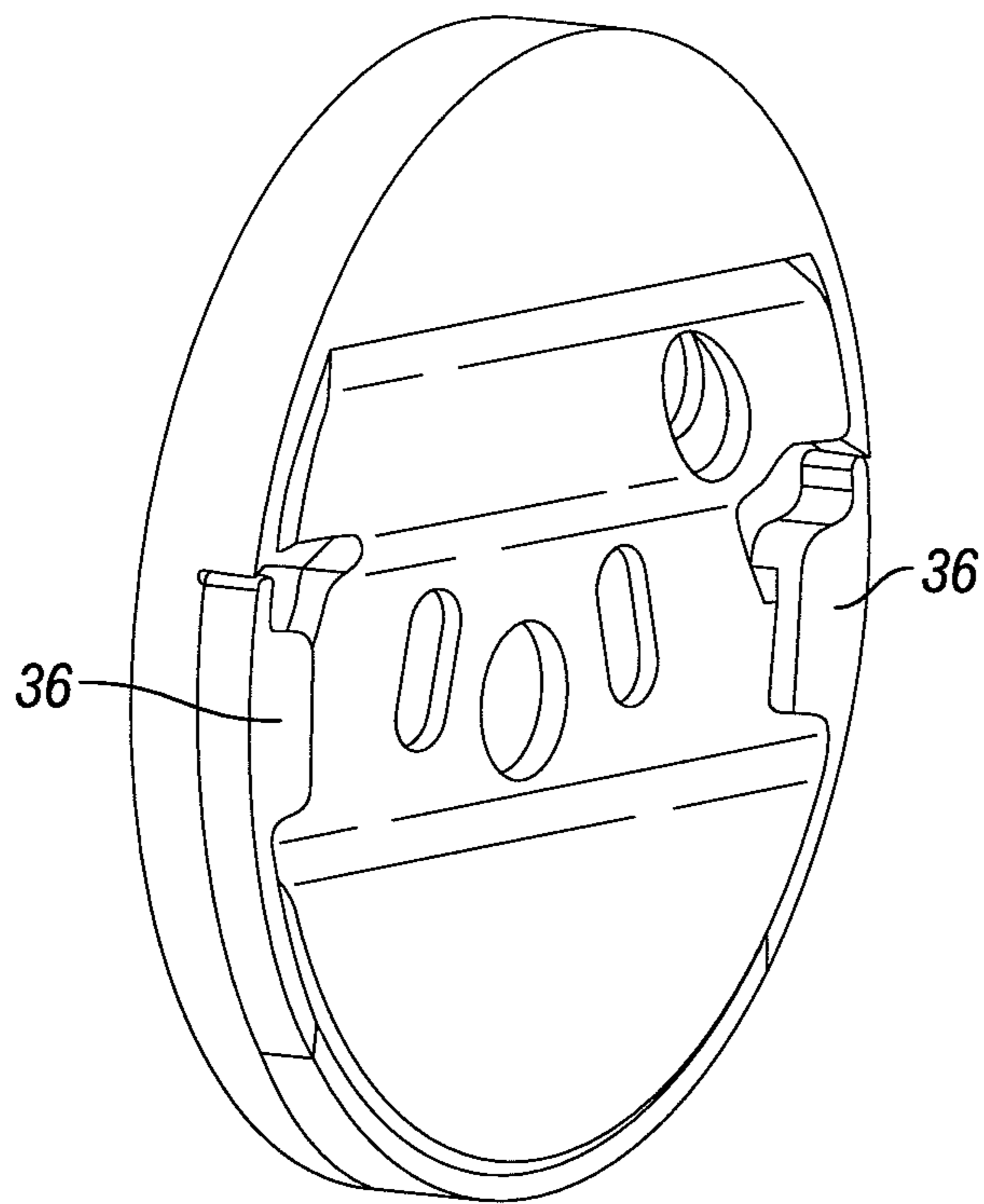


FIG. 10A

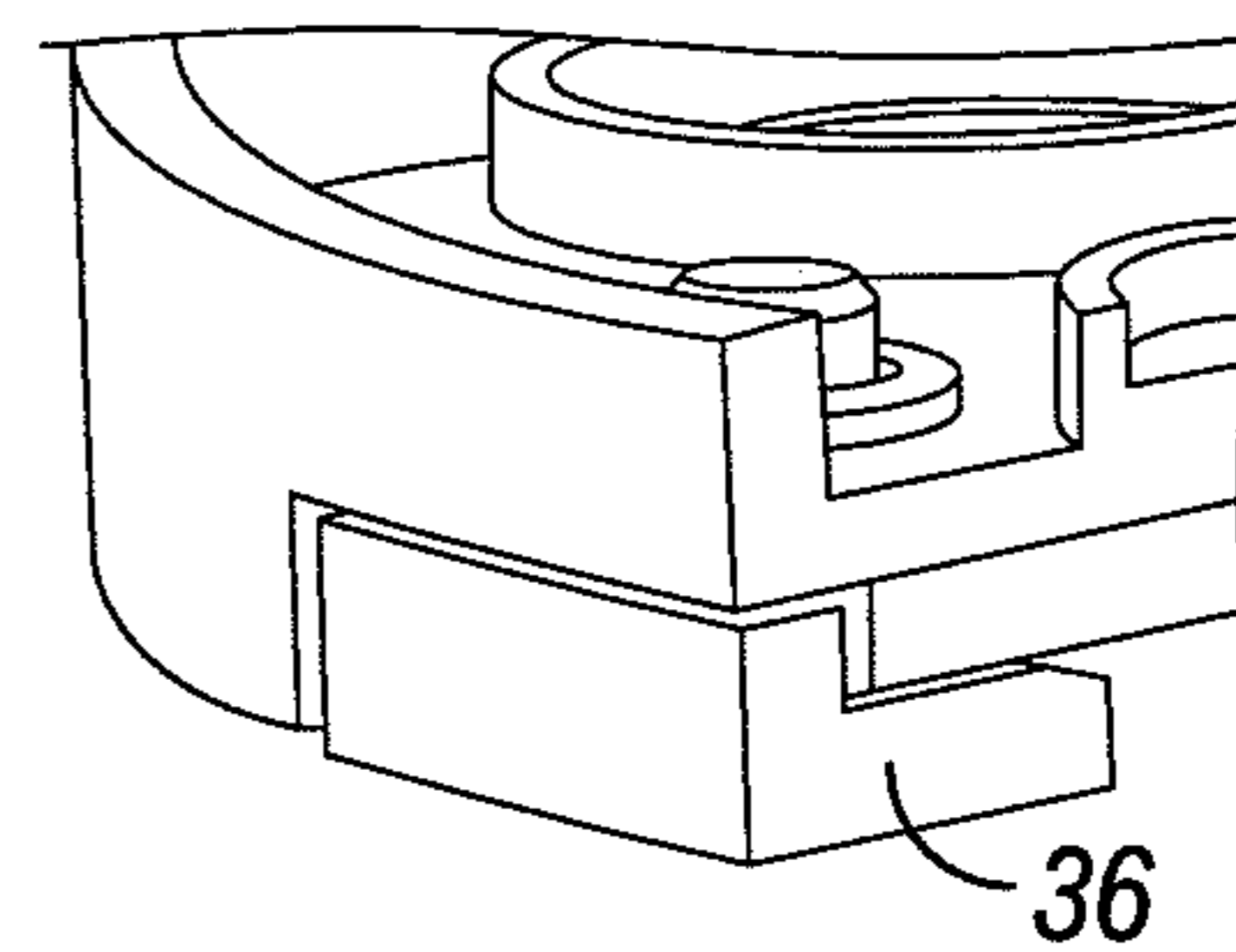


FIG. 10B

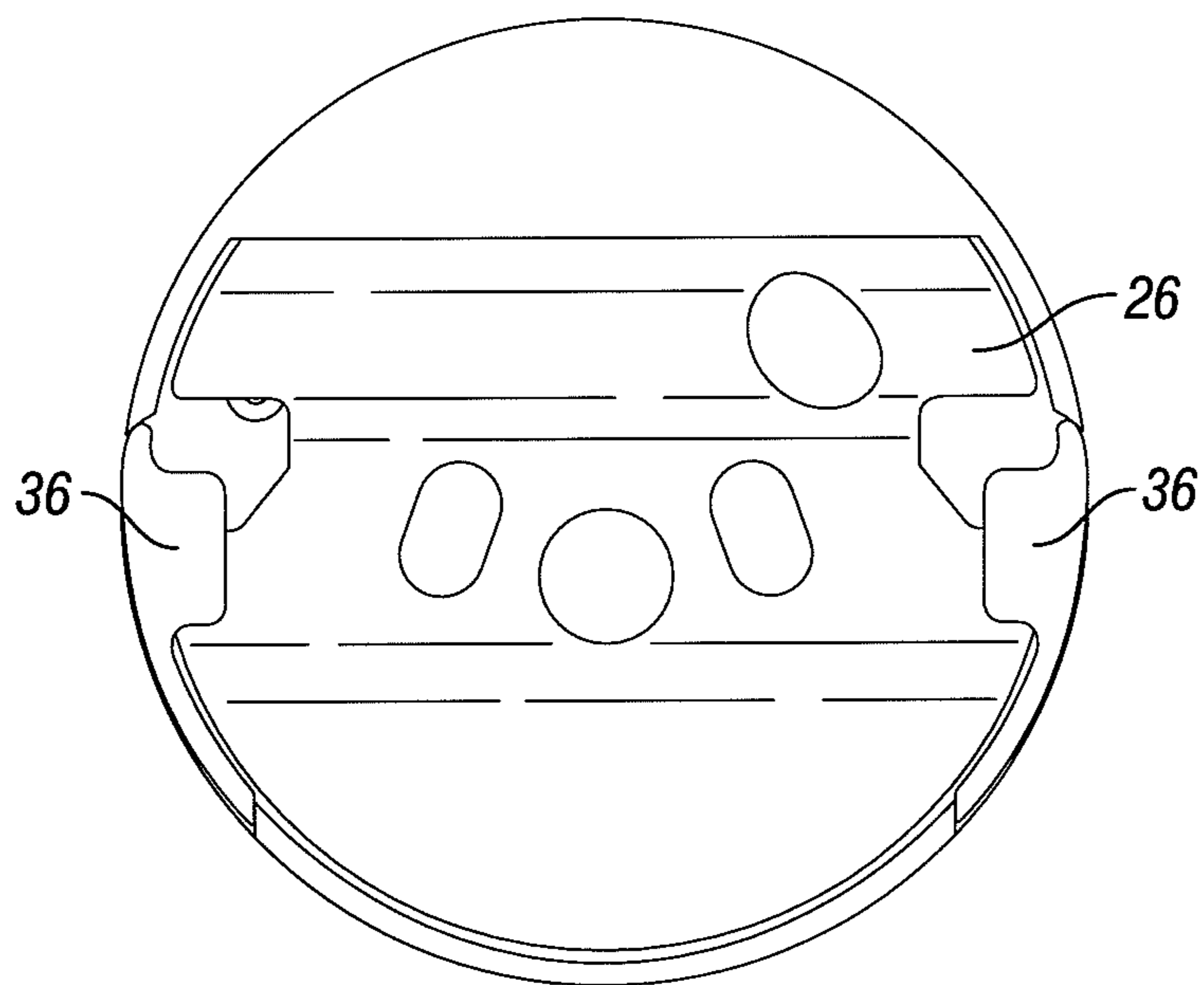


FIG. 10C

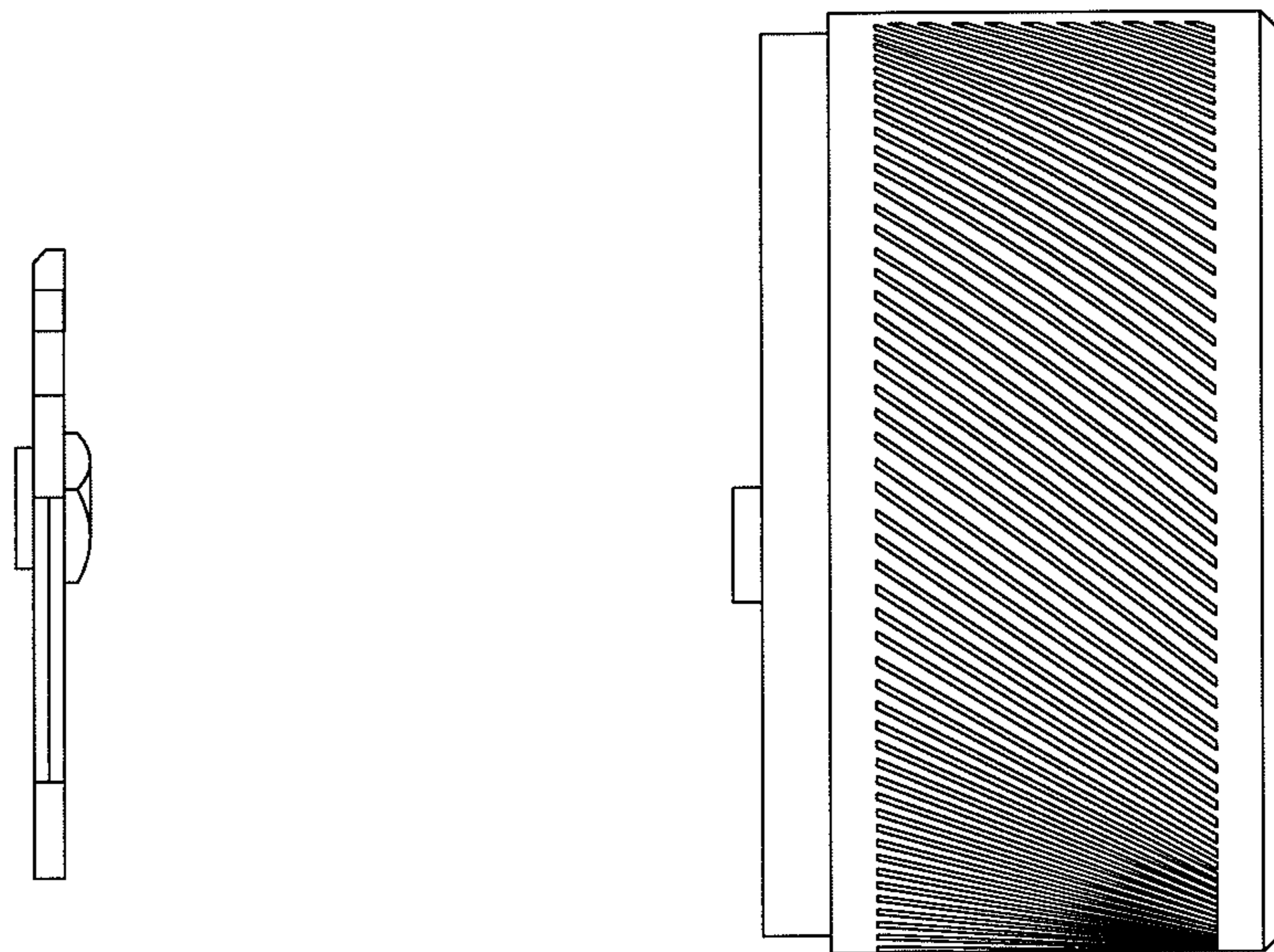


FIG. 11A

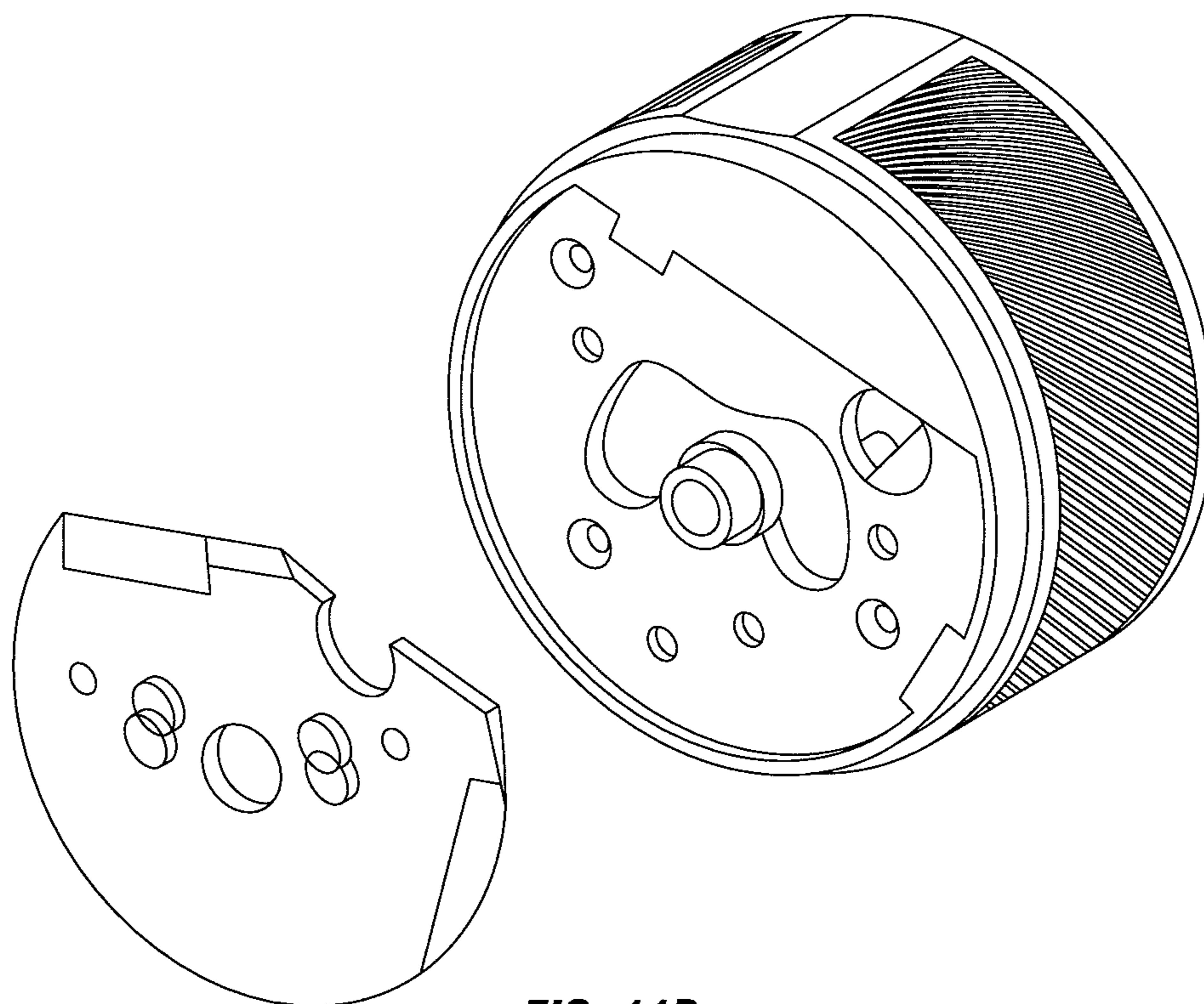


FIG. 11B

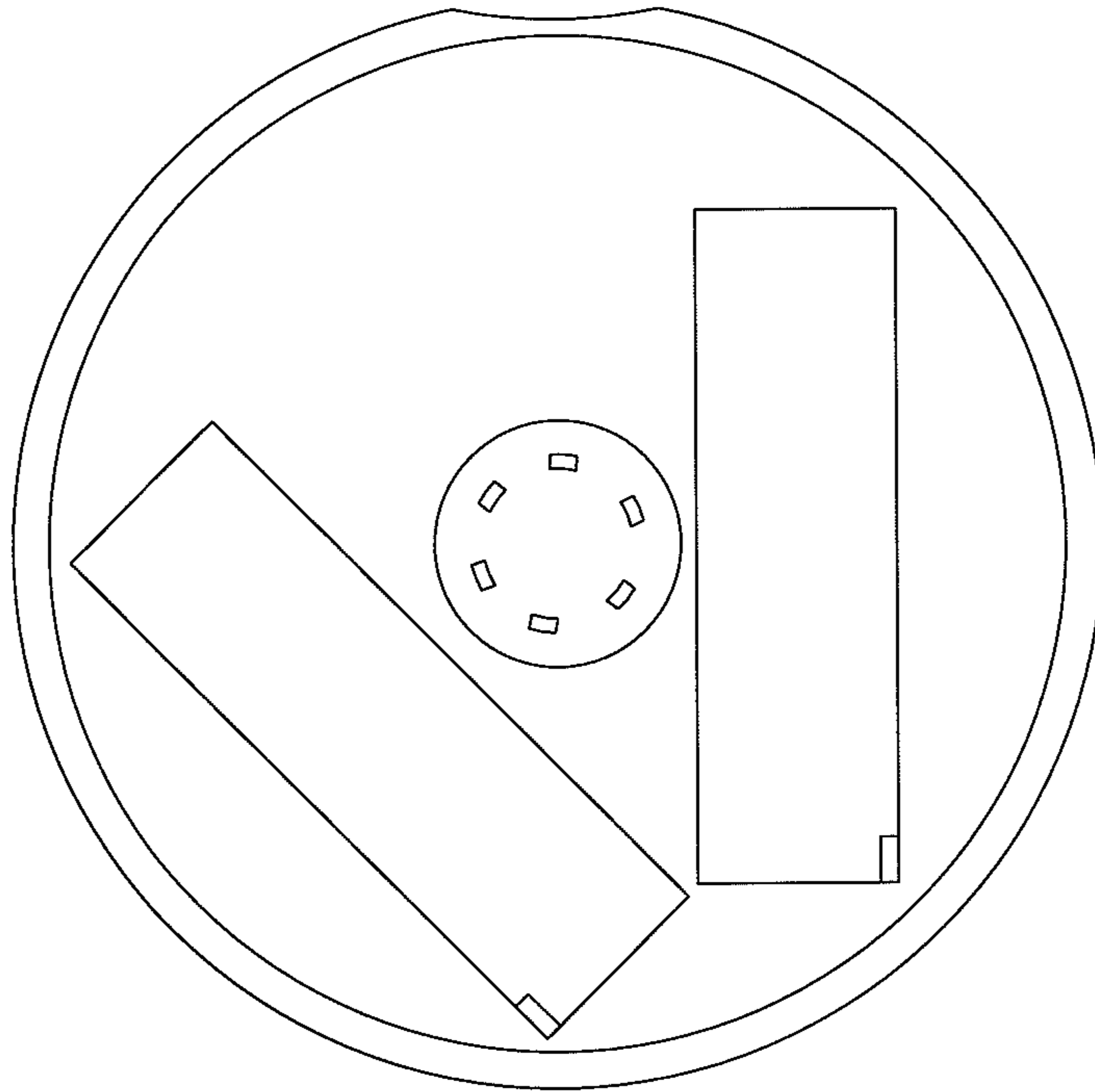


FIG. 11C

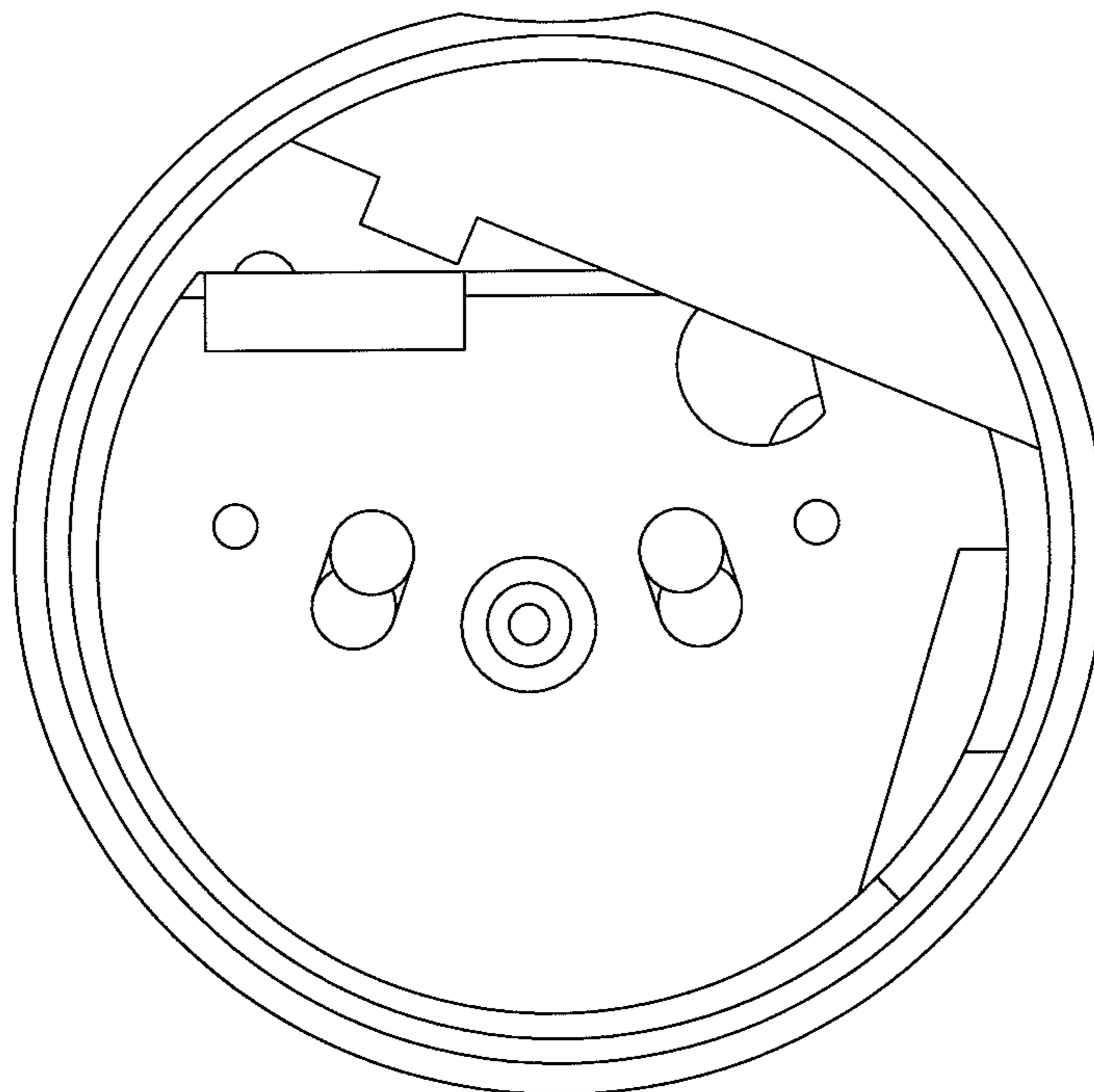


FIG. 11D

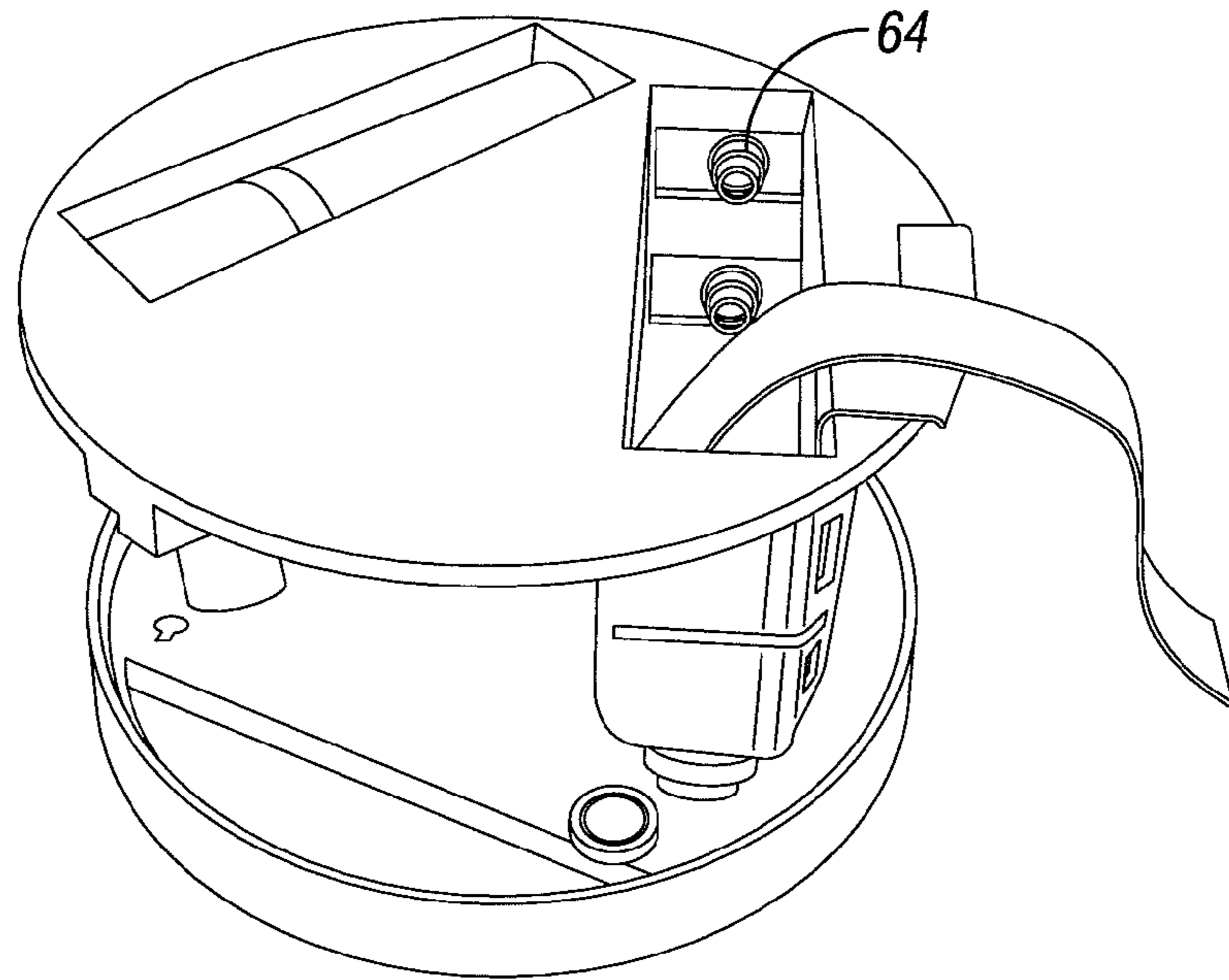


FIG. 12A

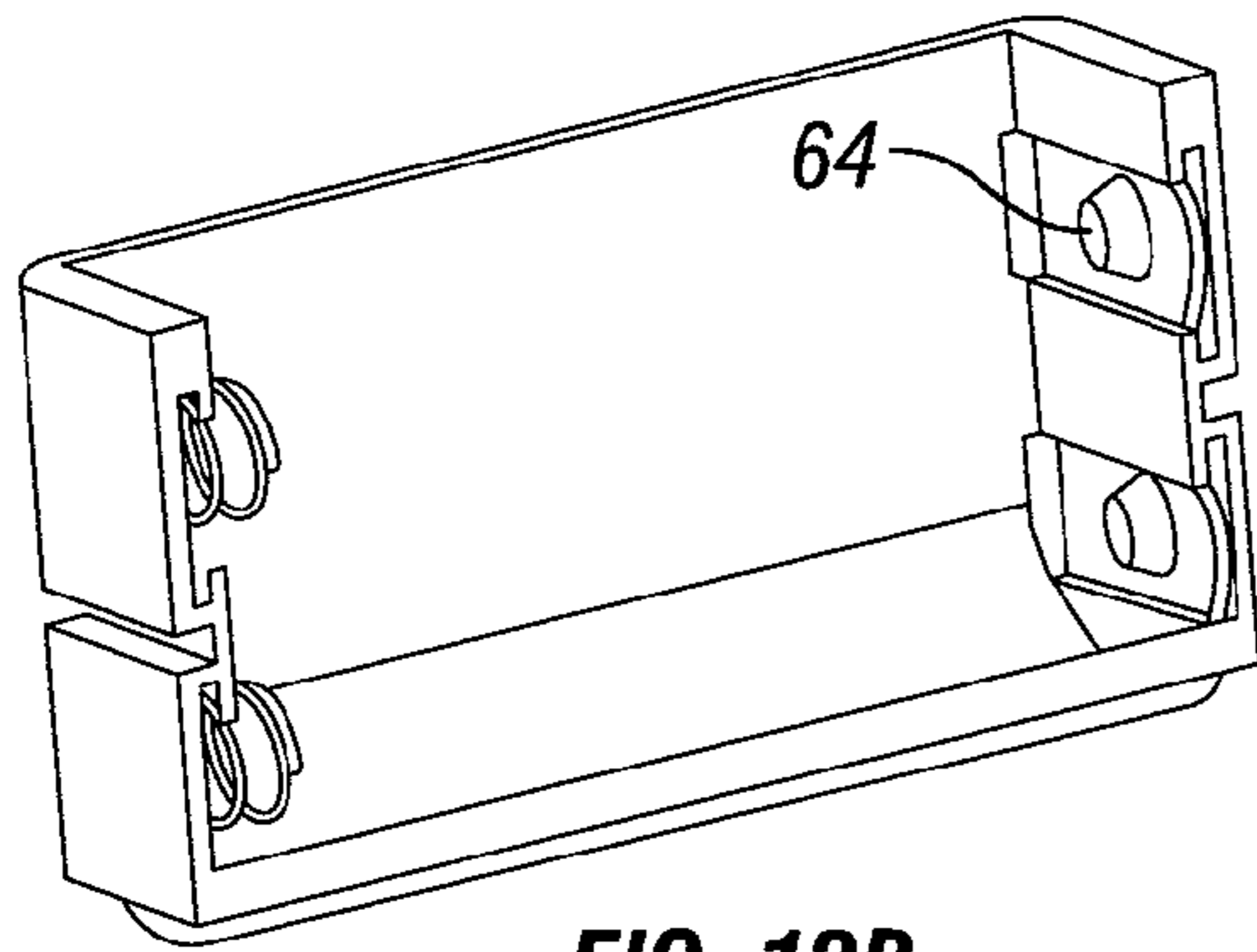


FIG. 12B

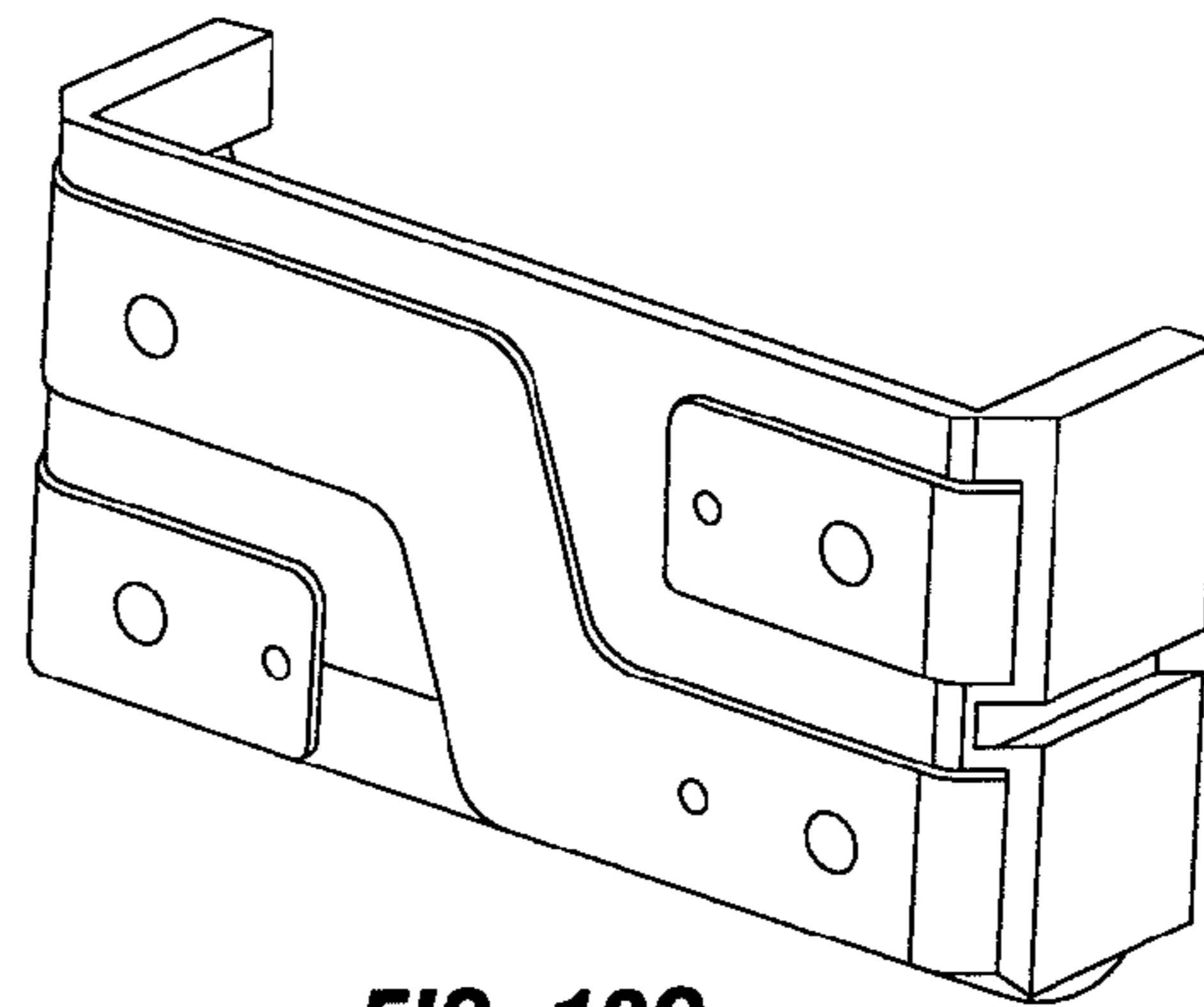


FIG. 12C

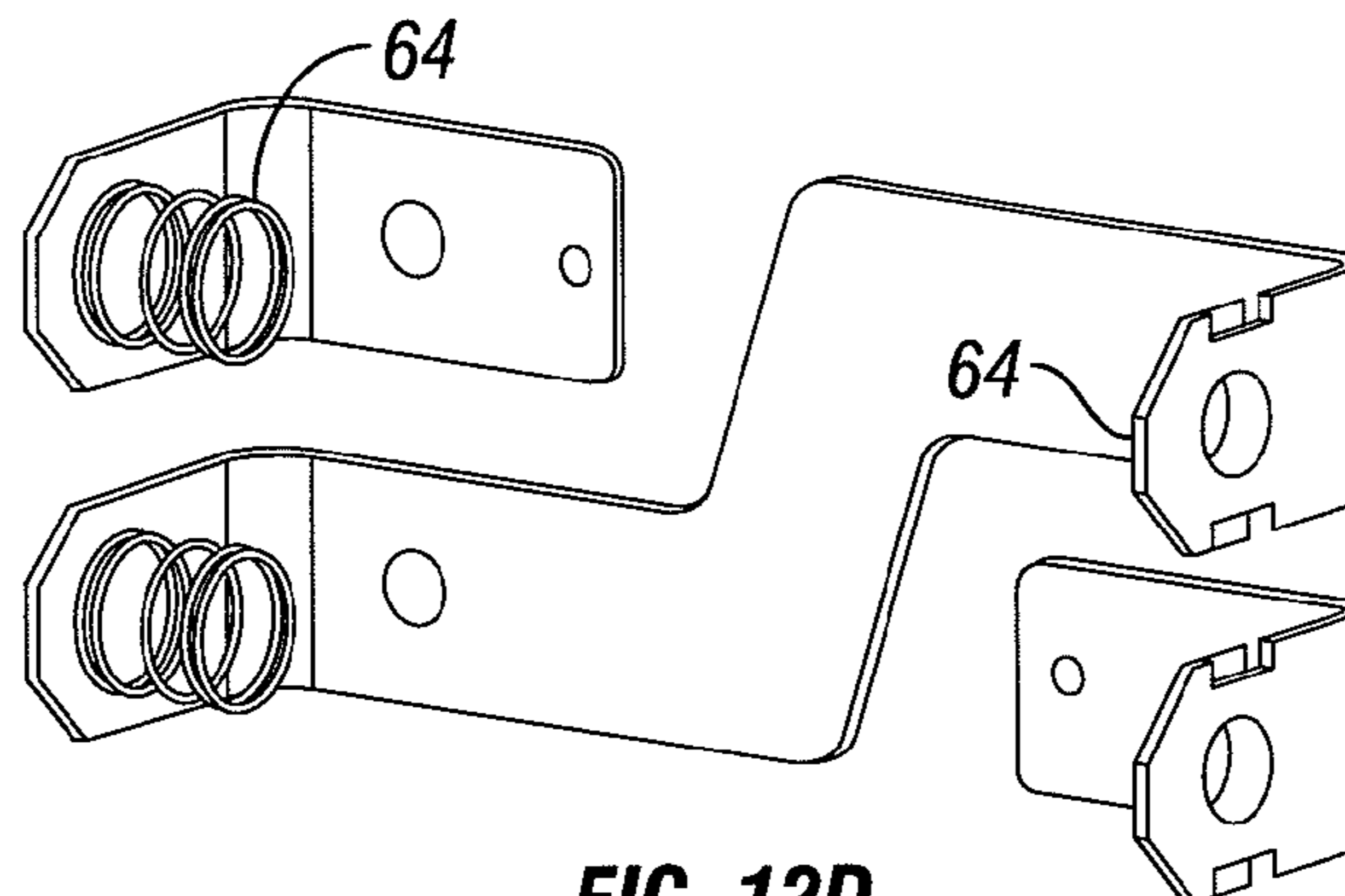


FIG. 12D

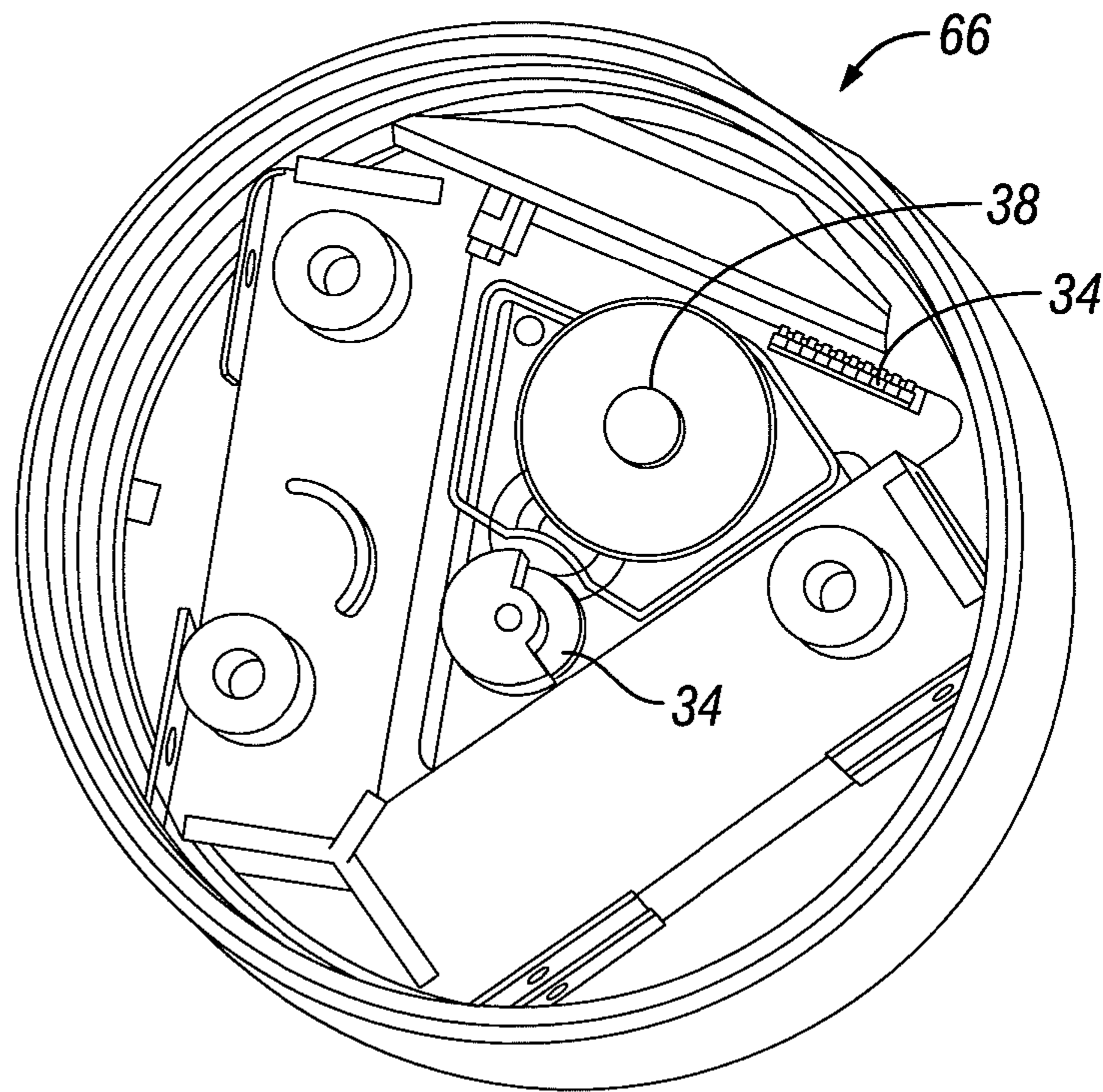


FIG. 13A

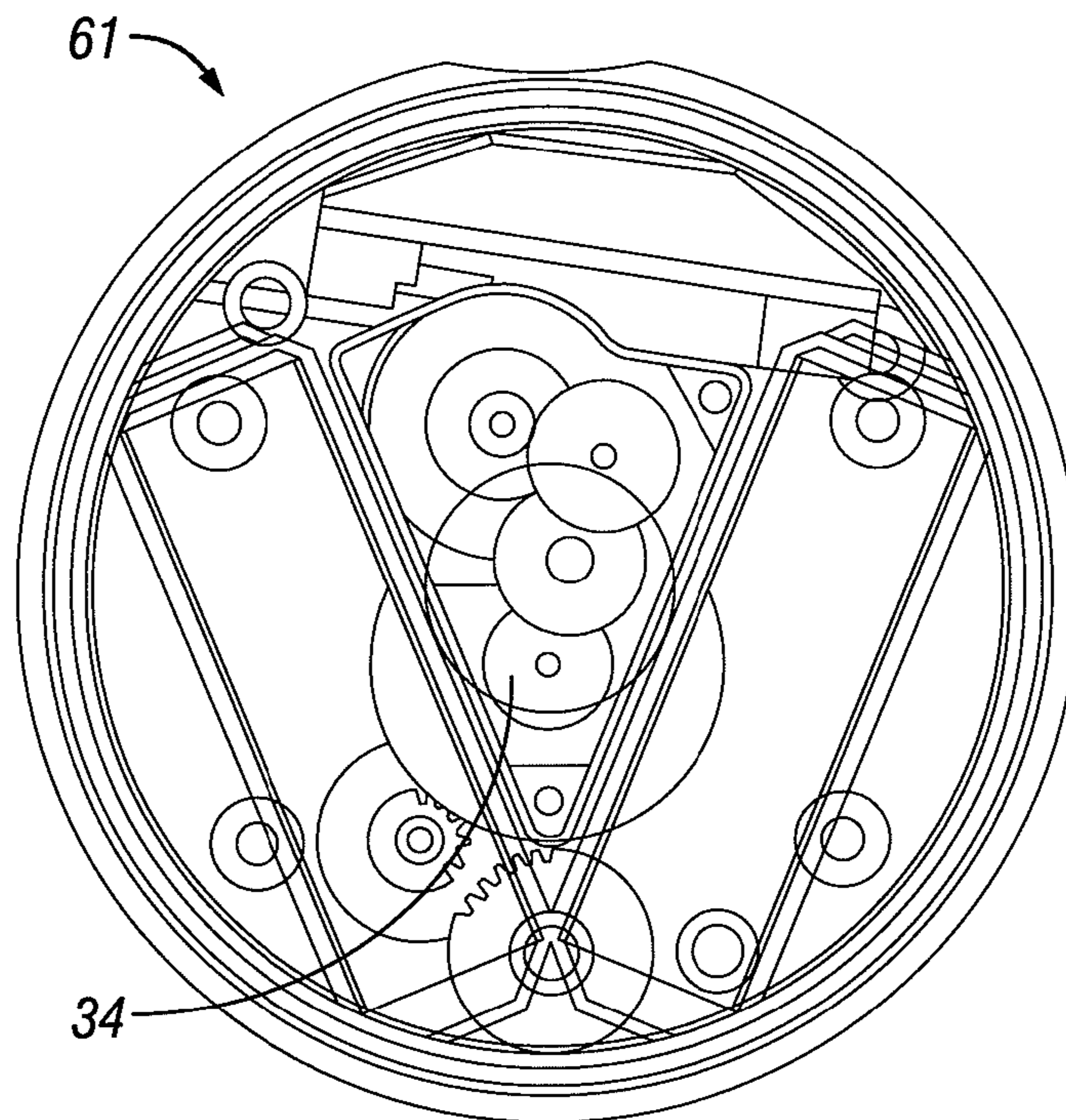


FIG. 13B

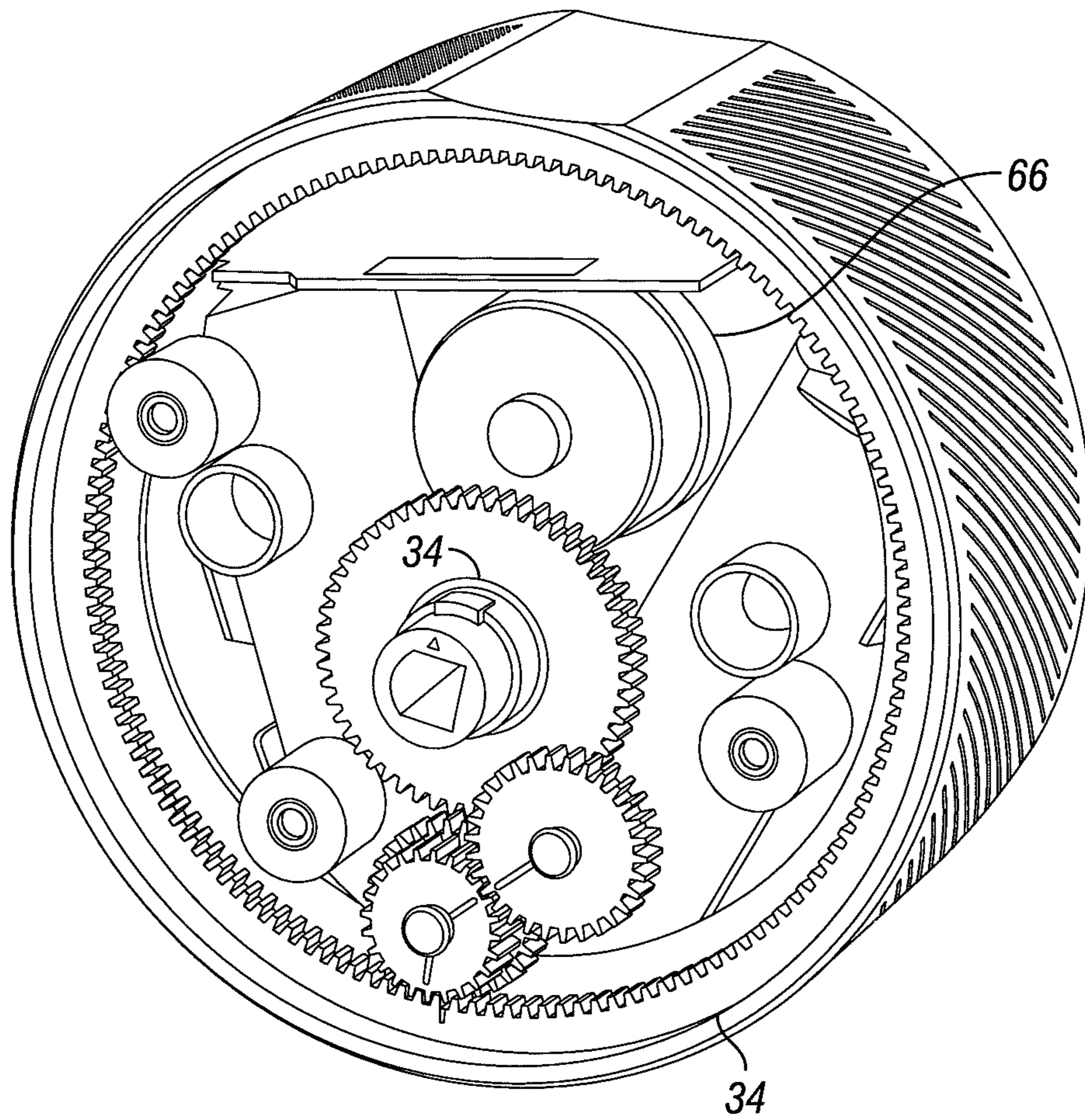


FIG. 14

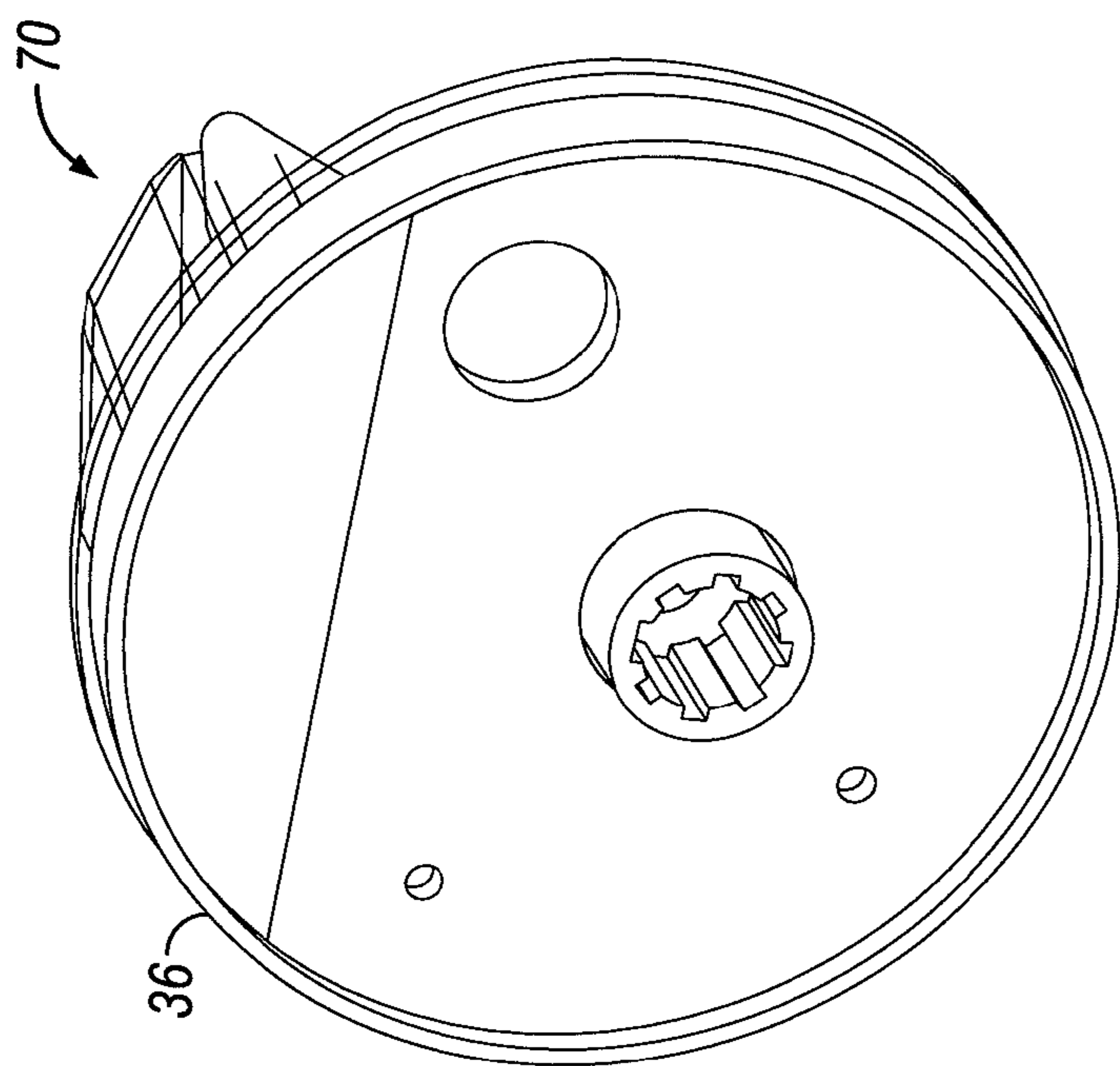


FIG. 15A

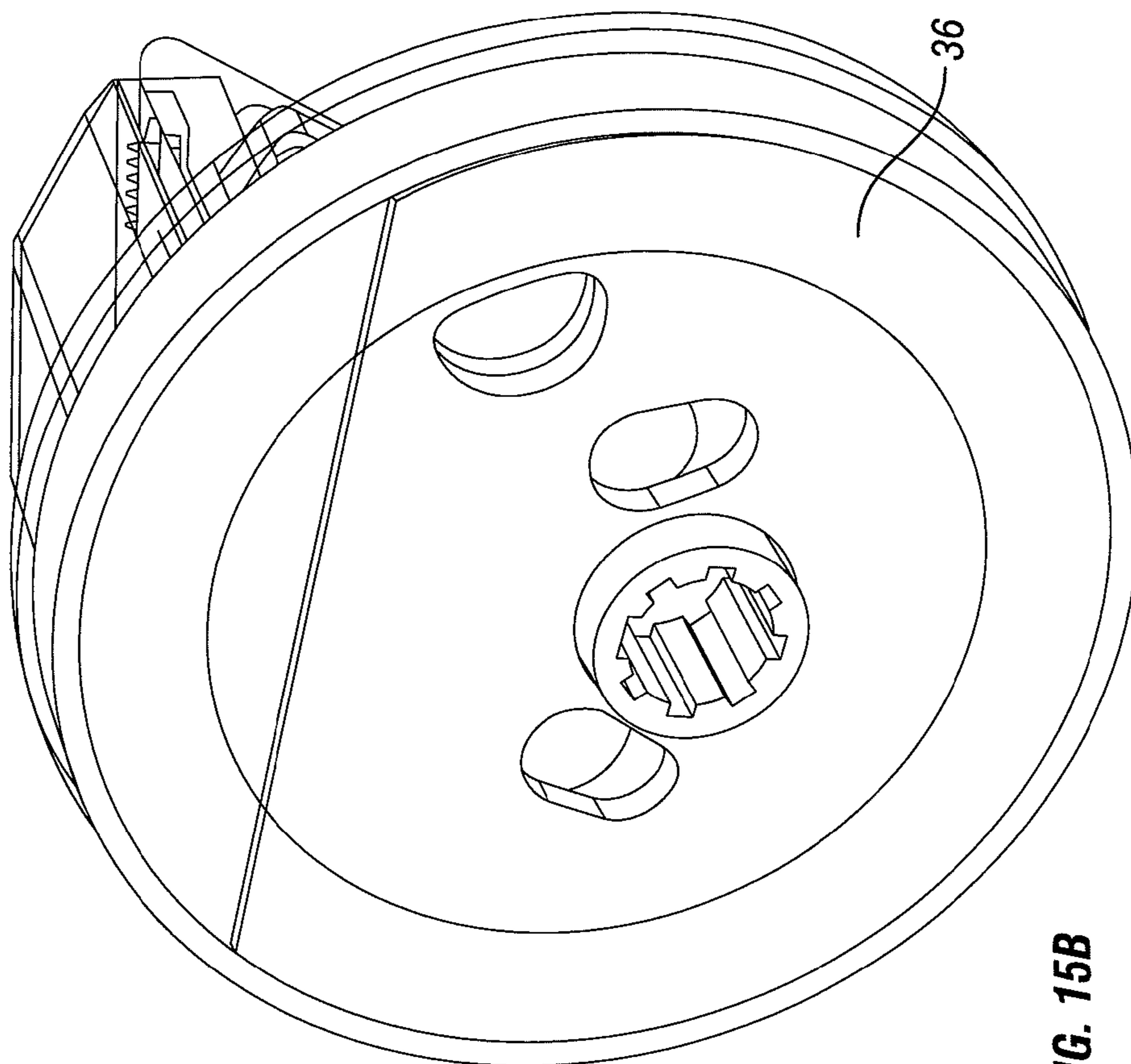


FIG. 15B

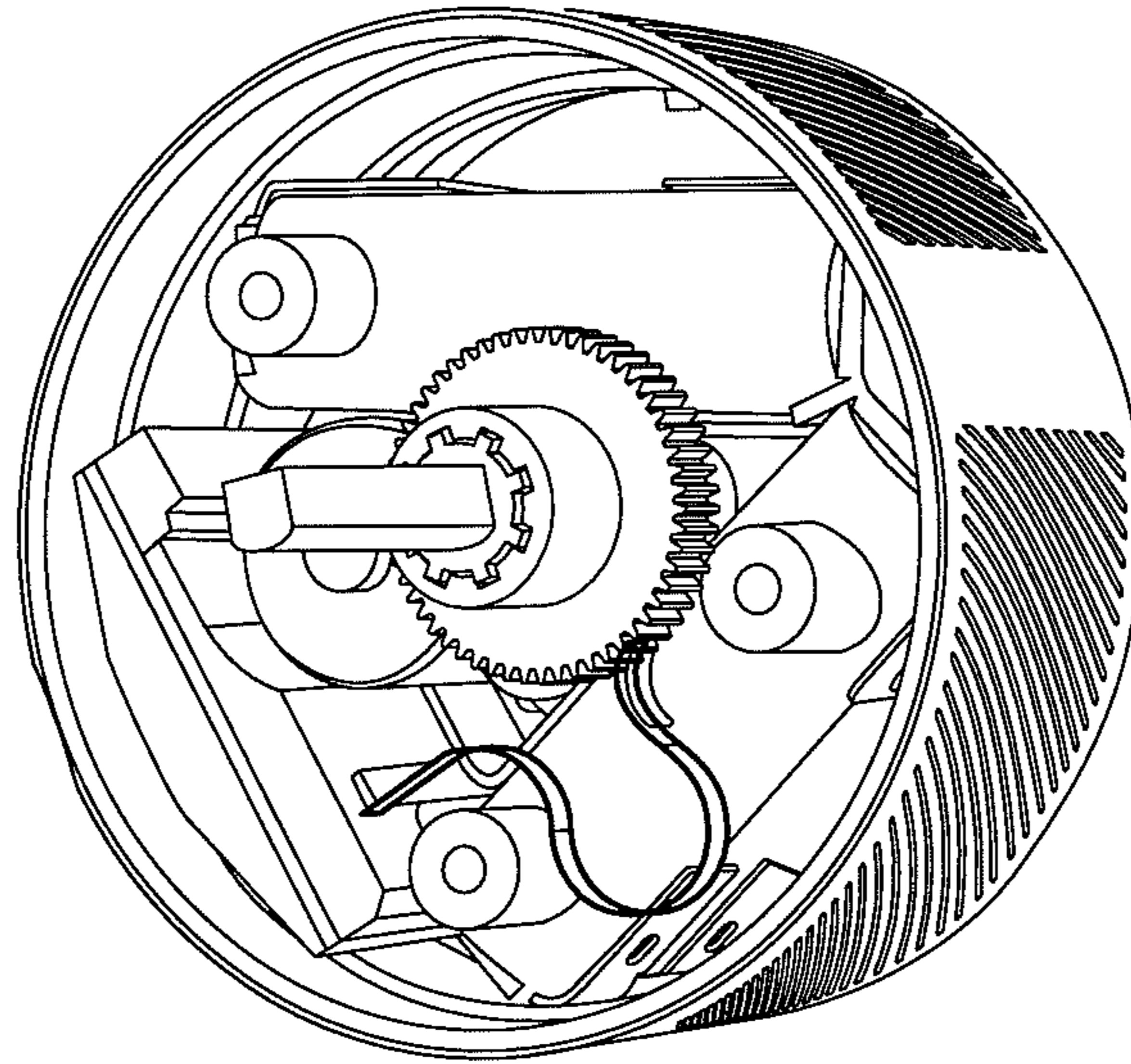


FIG. 15D

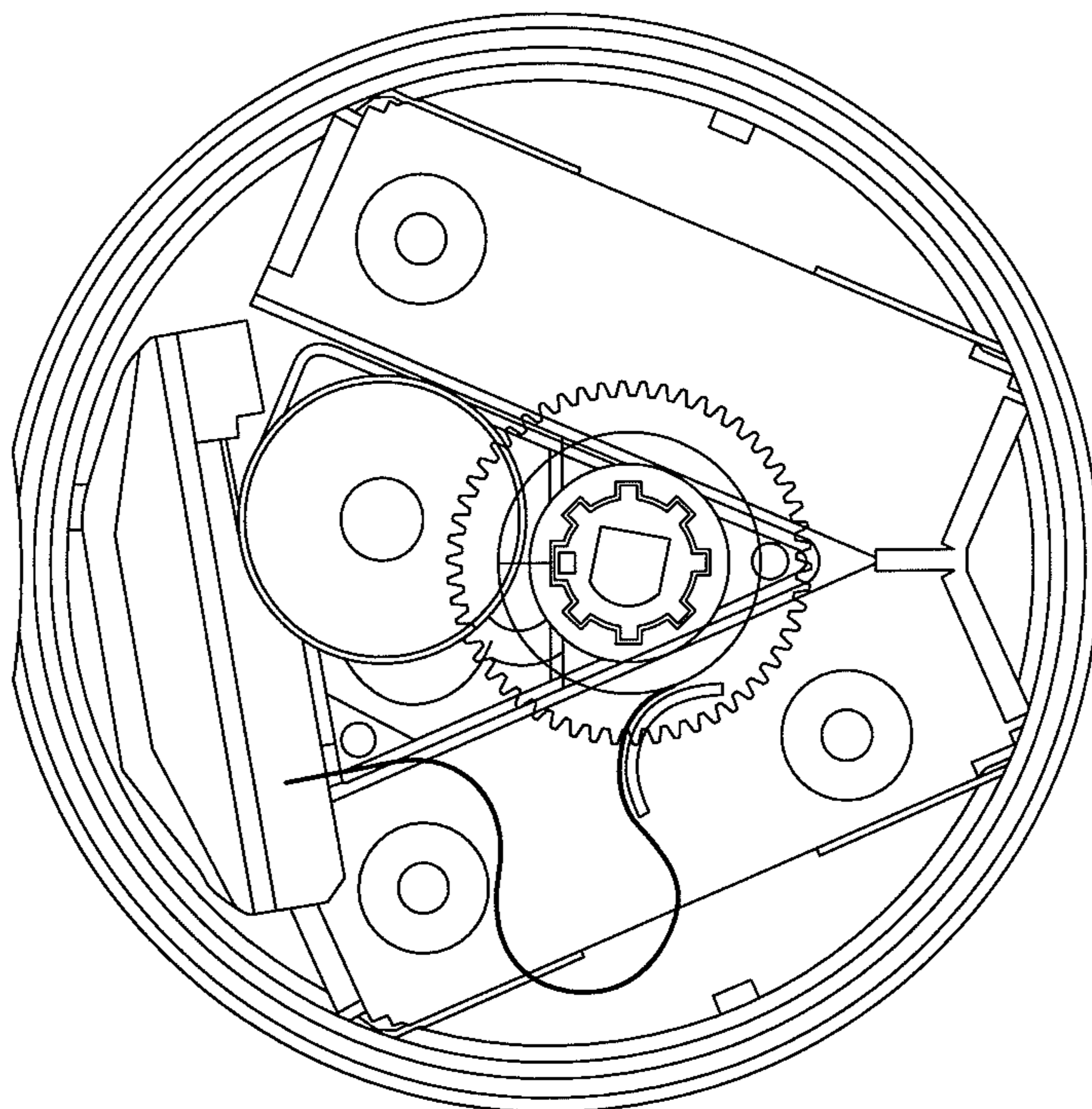


FIG. 15C

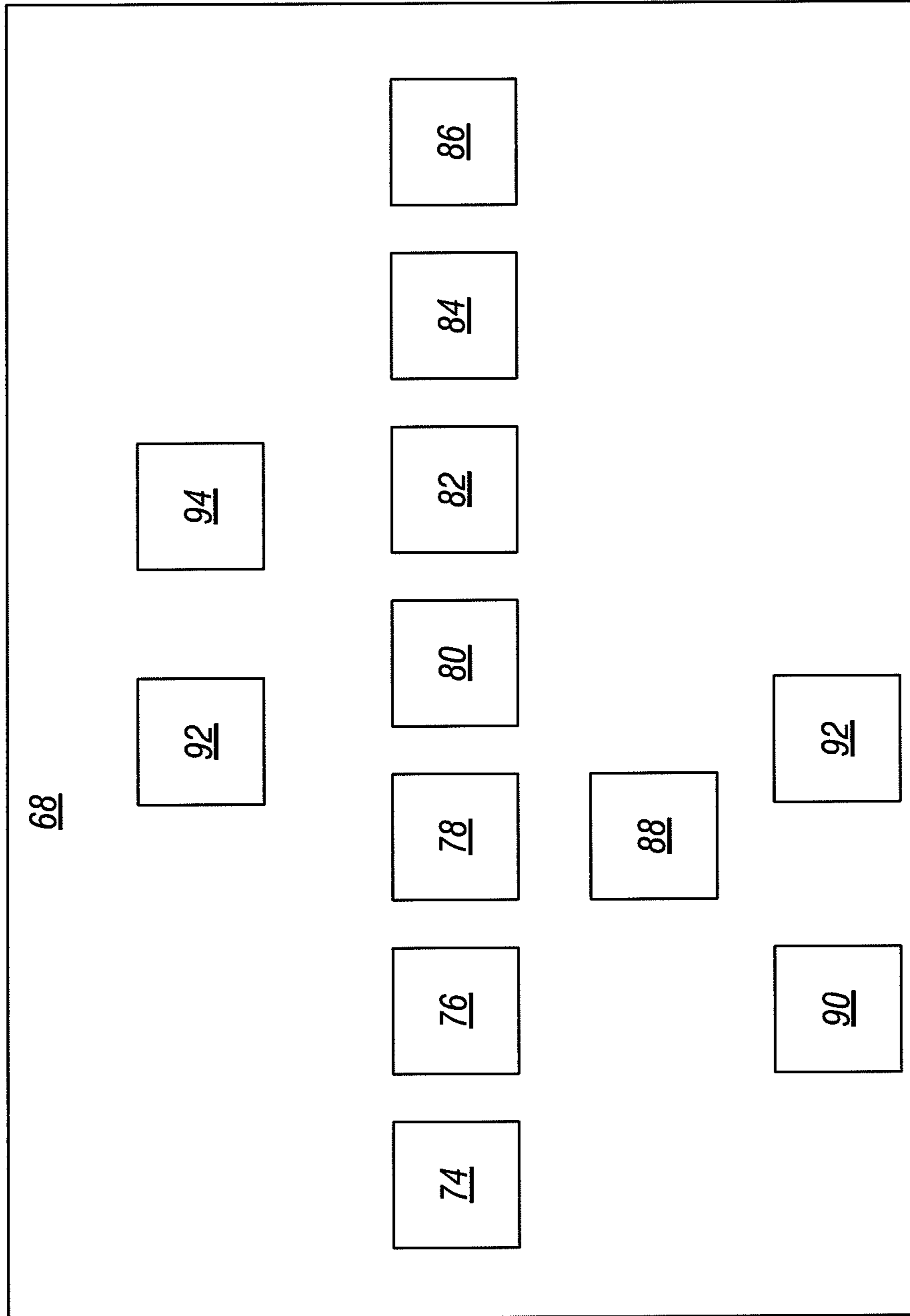


FIG. 16

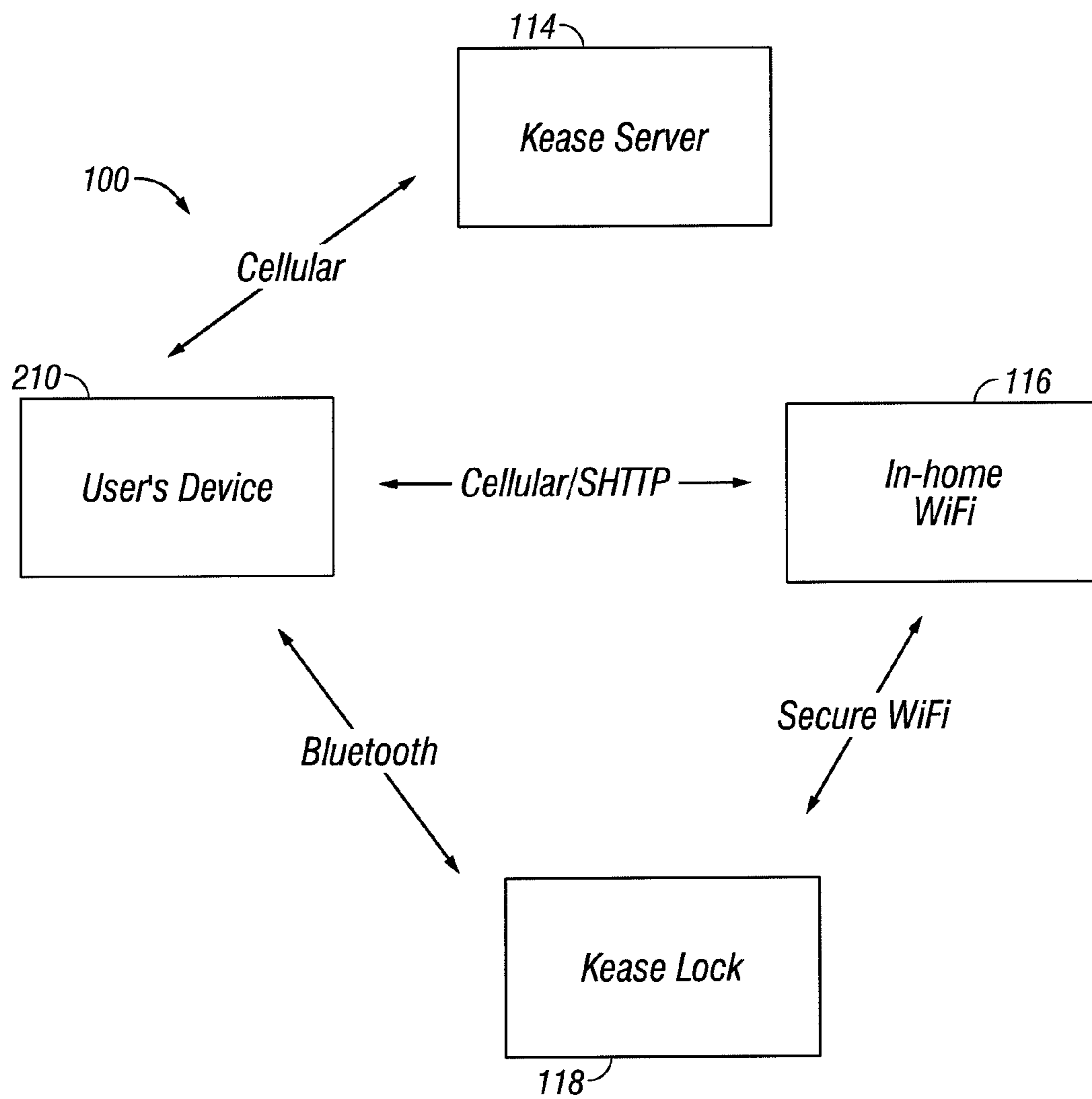


FIG. 17

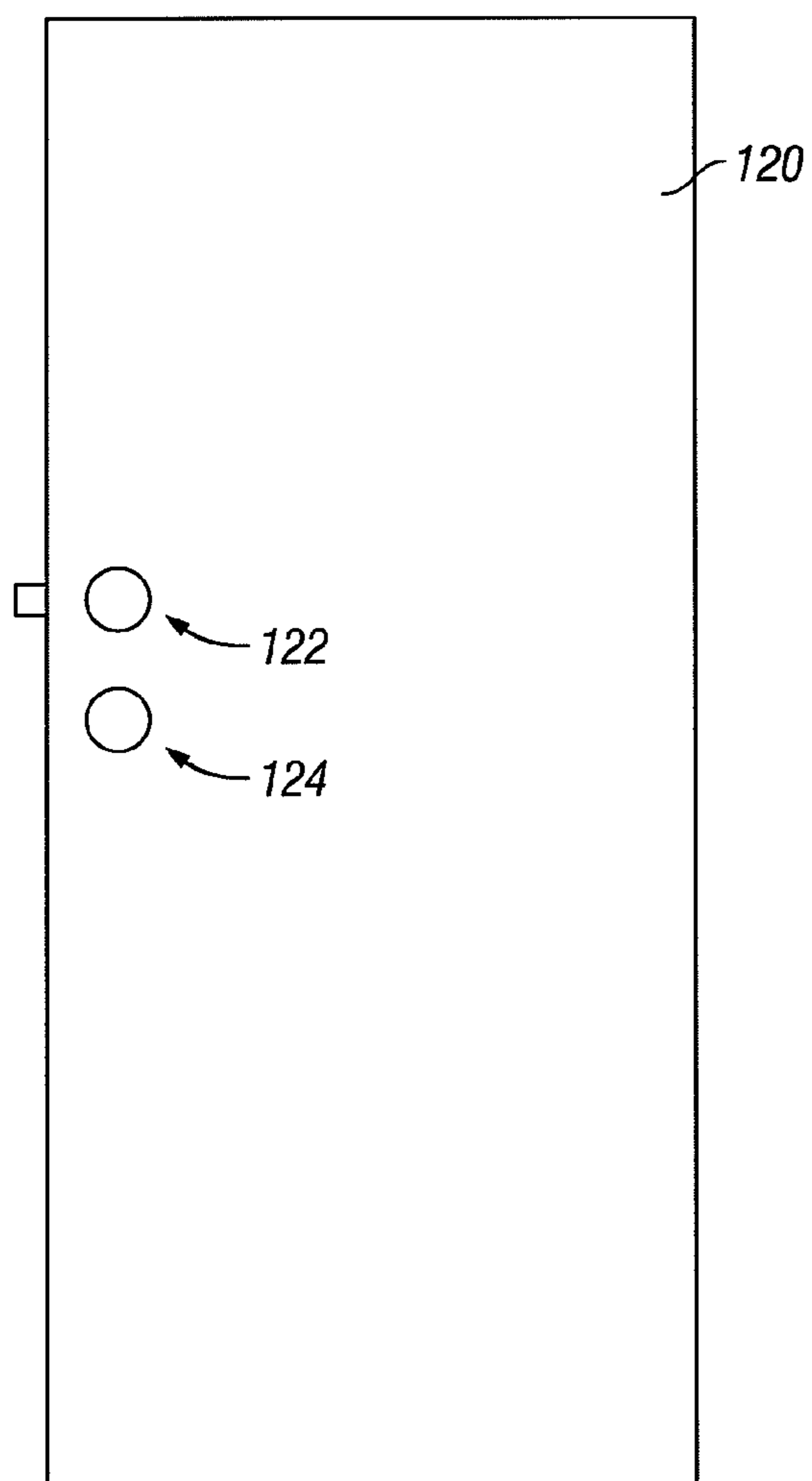


FIG. 18A

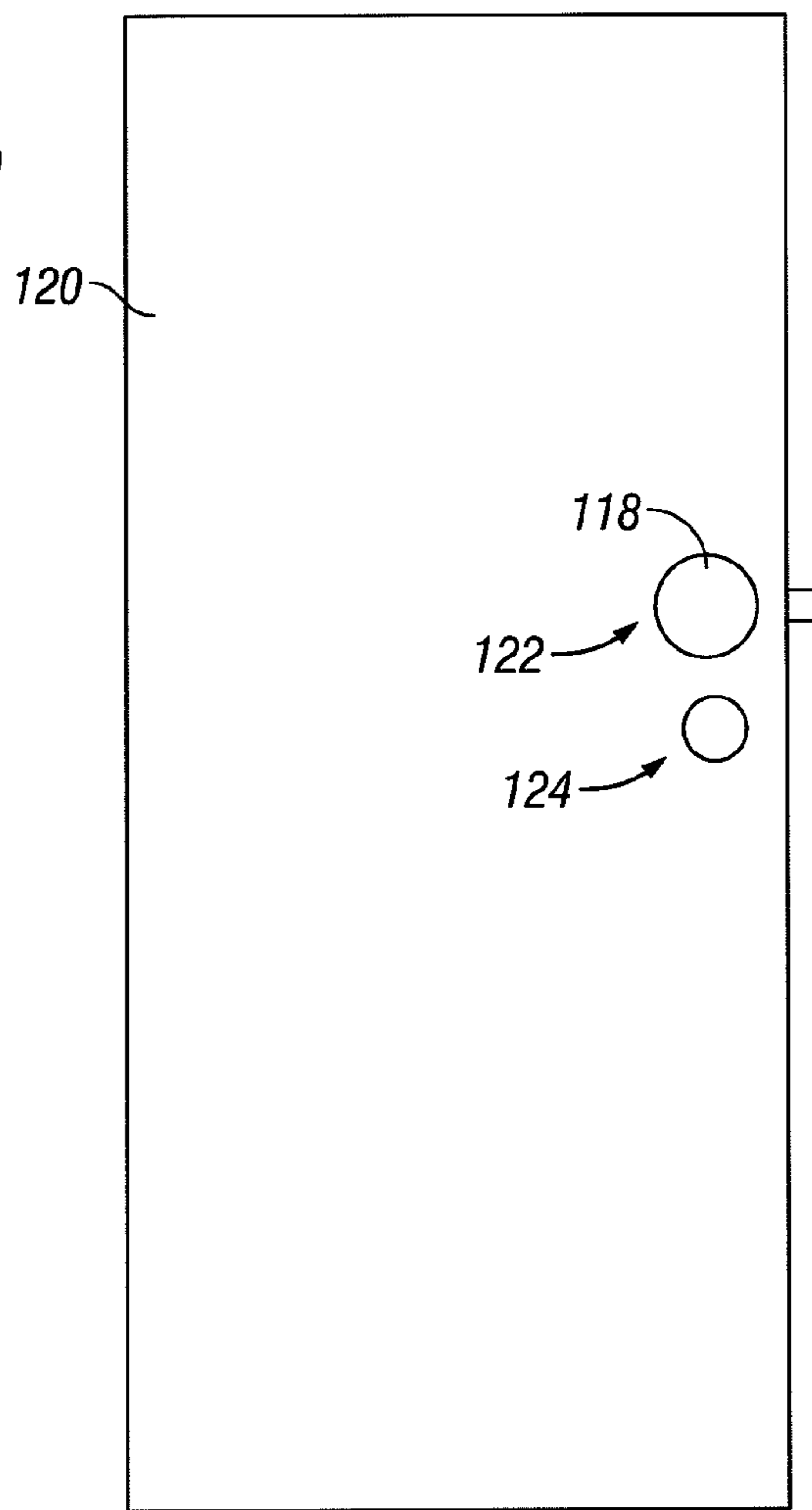


FIG. 18B

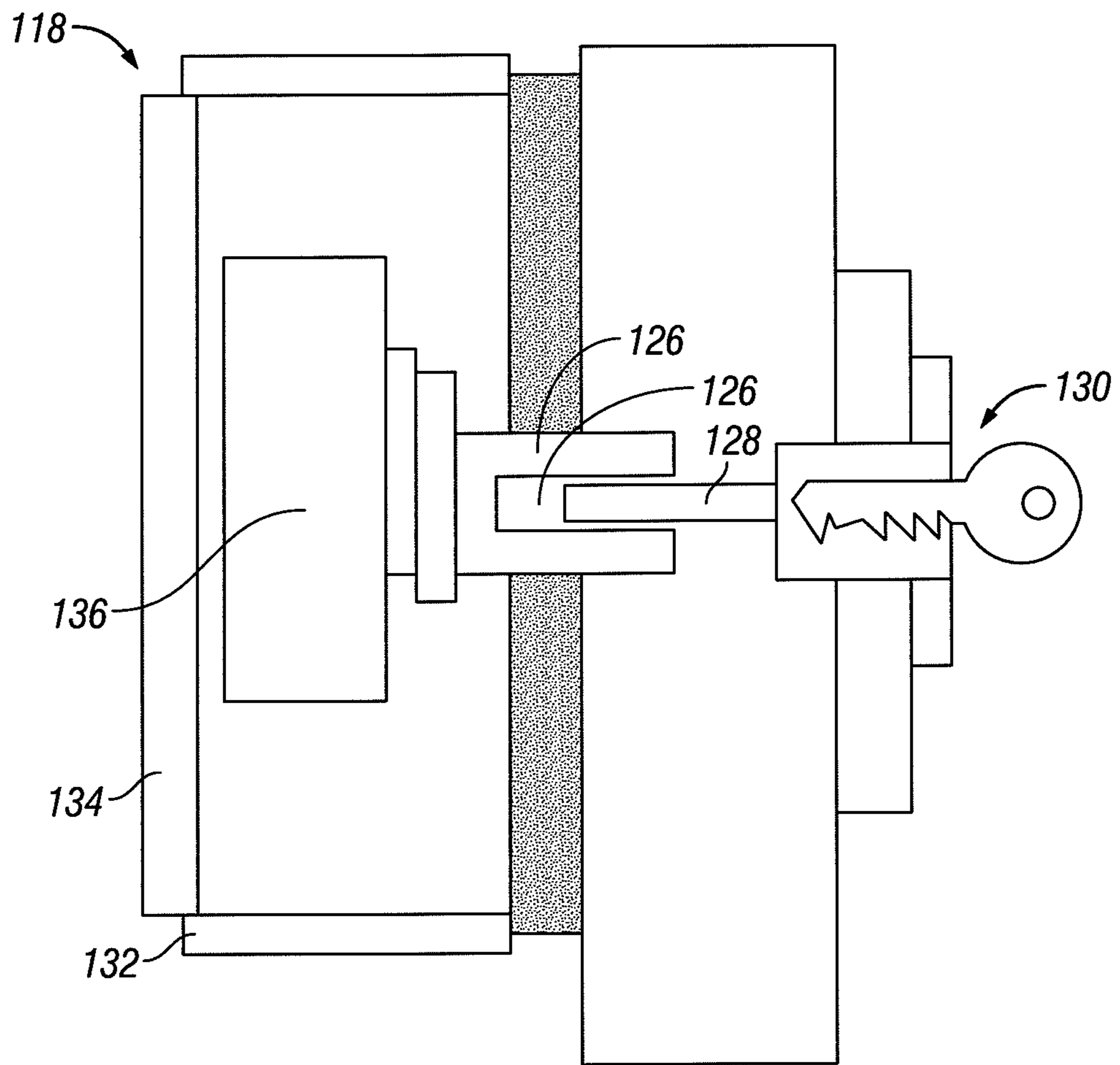


FIG. 19

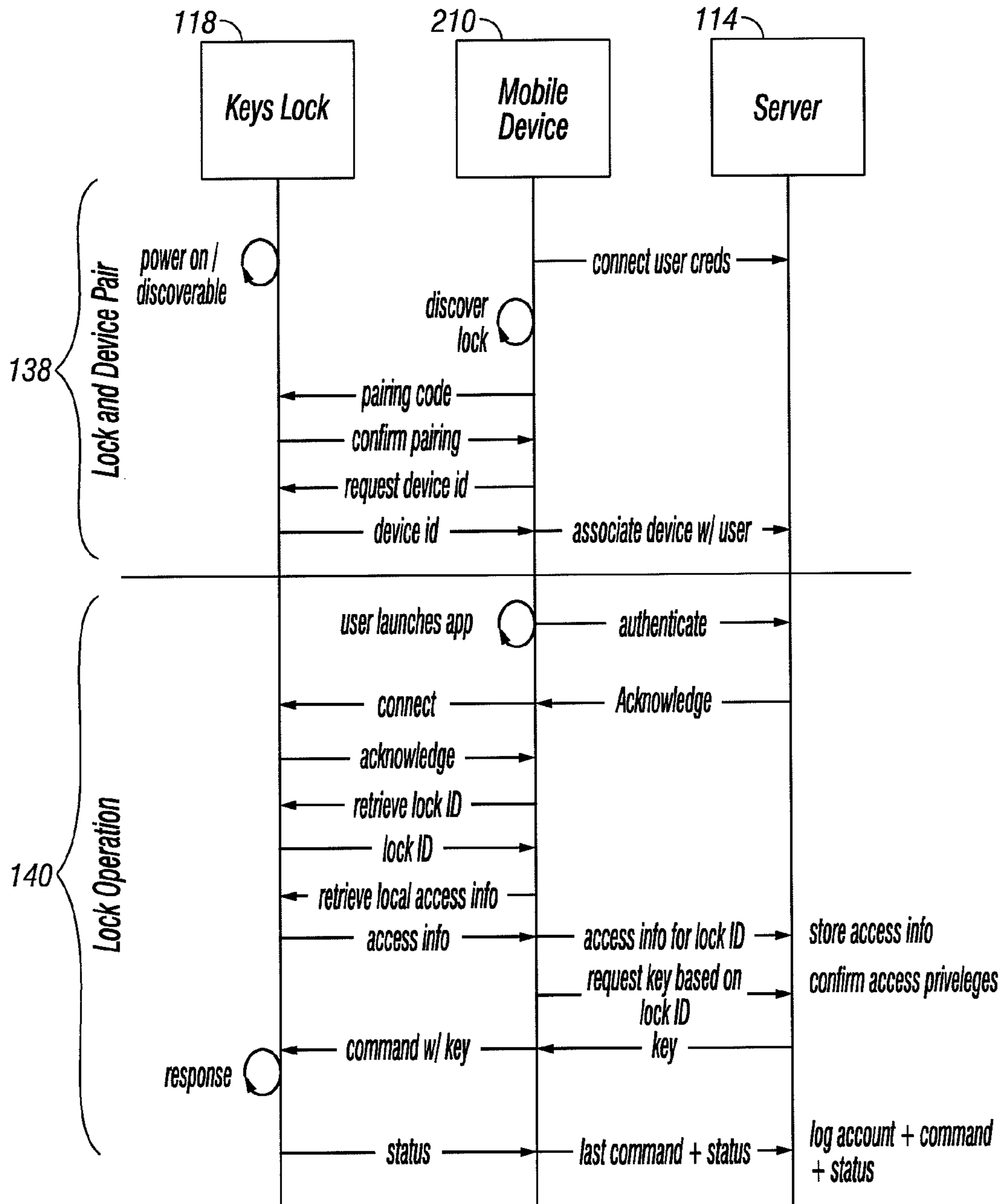


FIG. 20

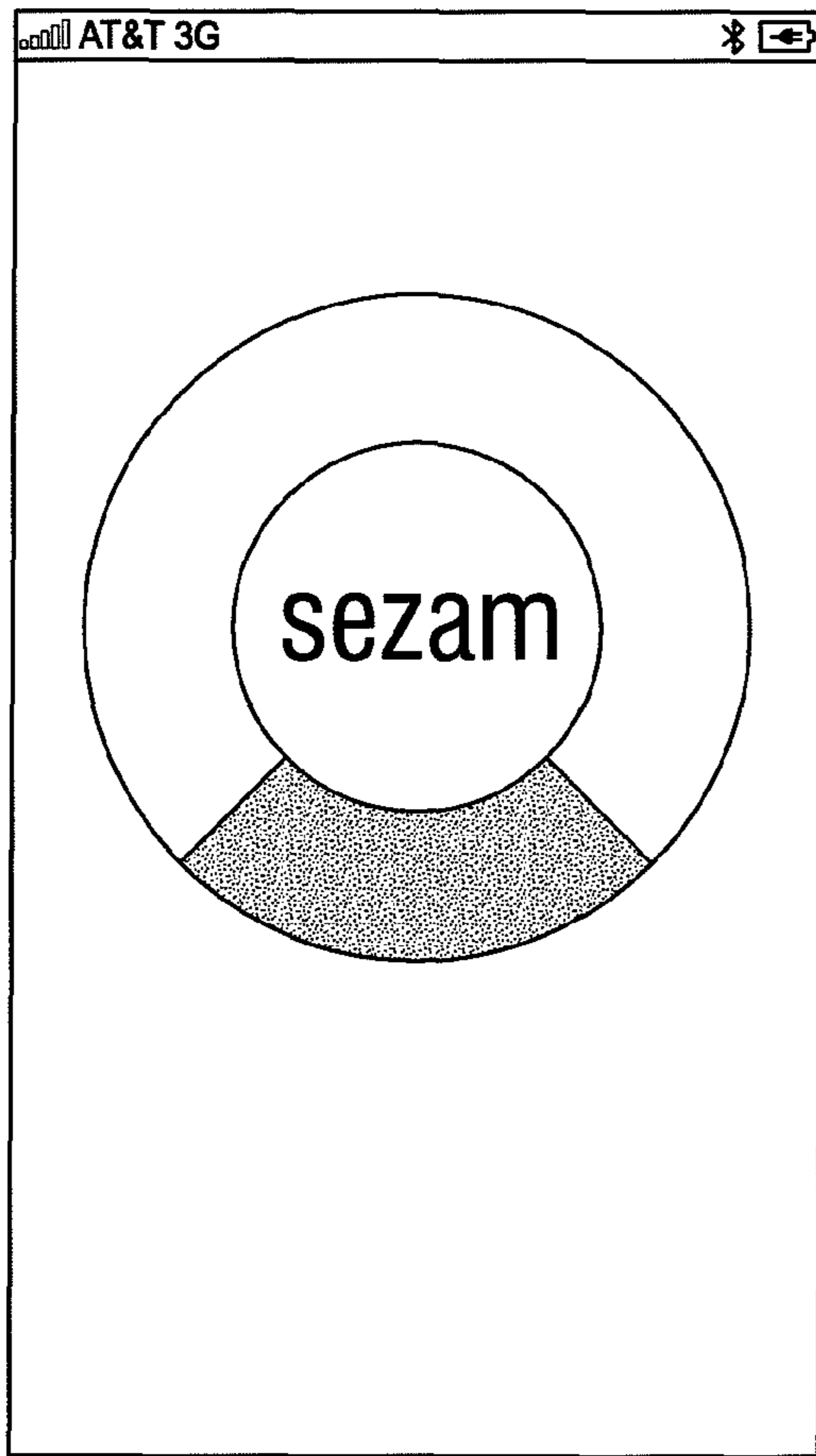


FIG. 21A

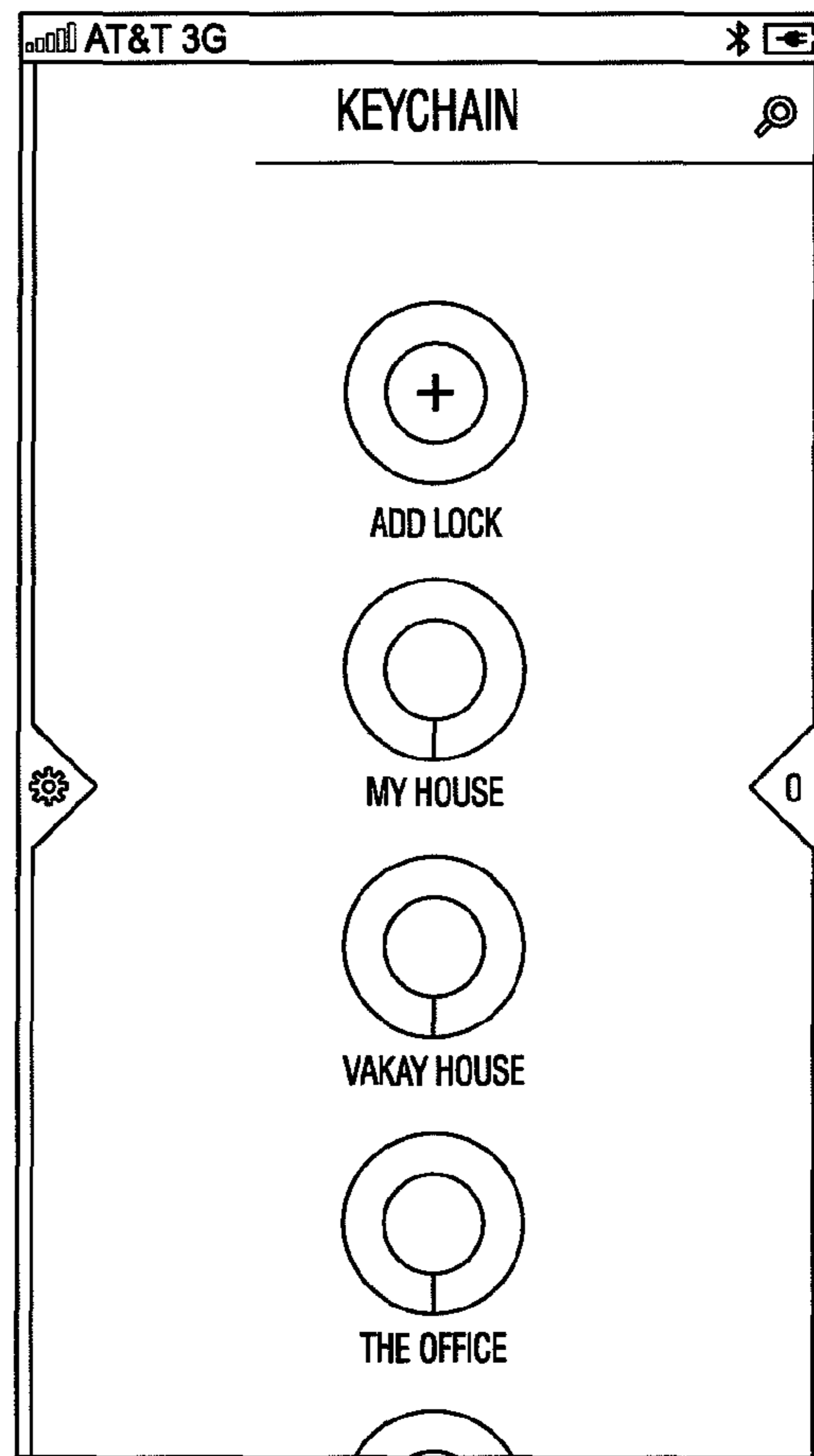


FIG. 21B

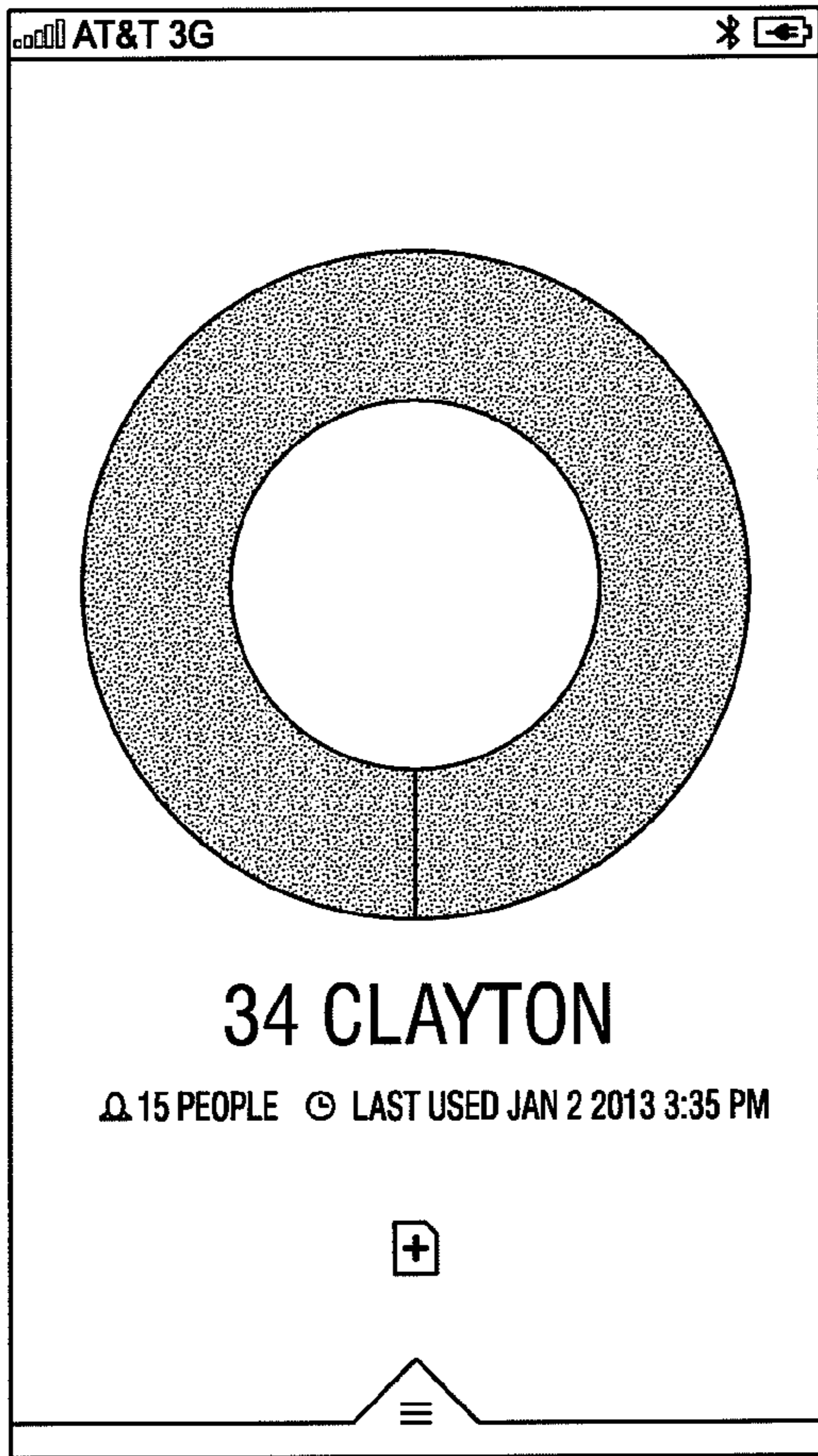


FIG. 21C

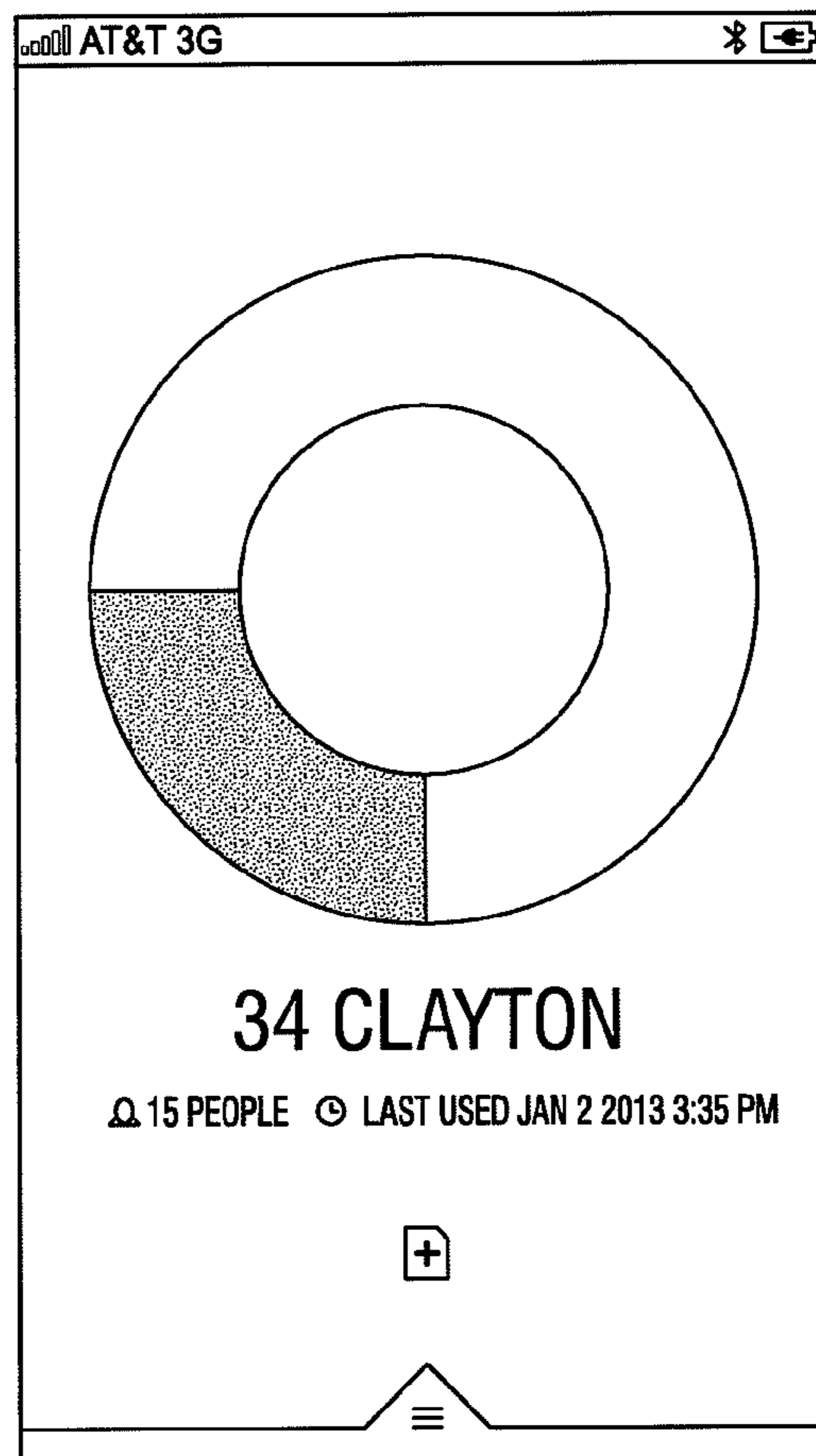


FIG. 21D

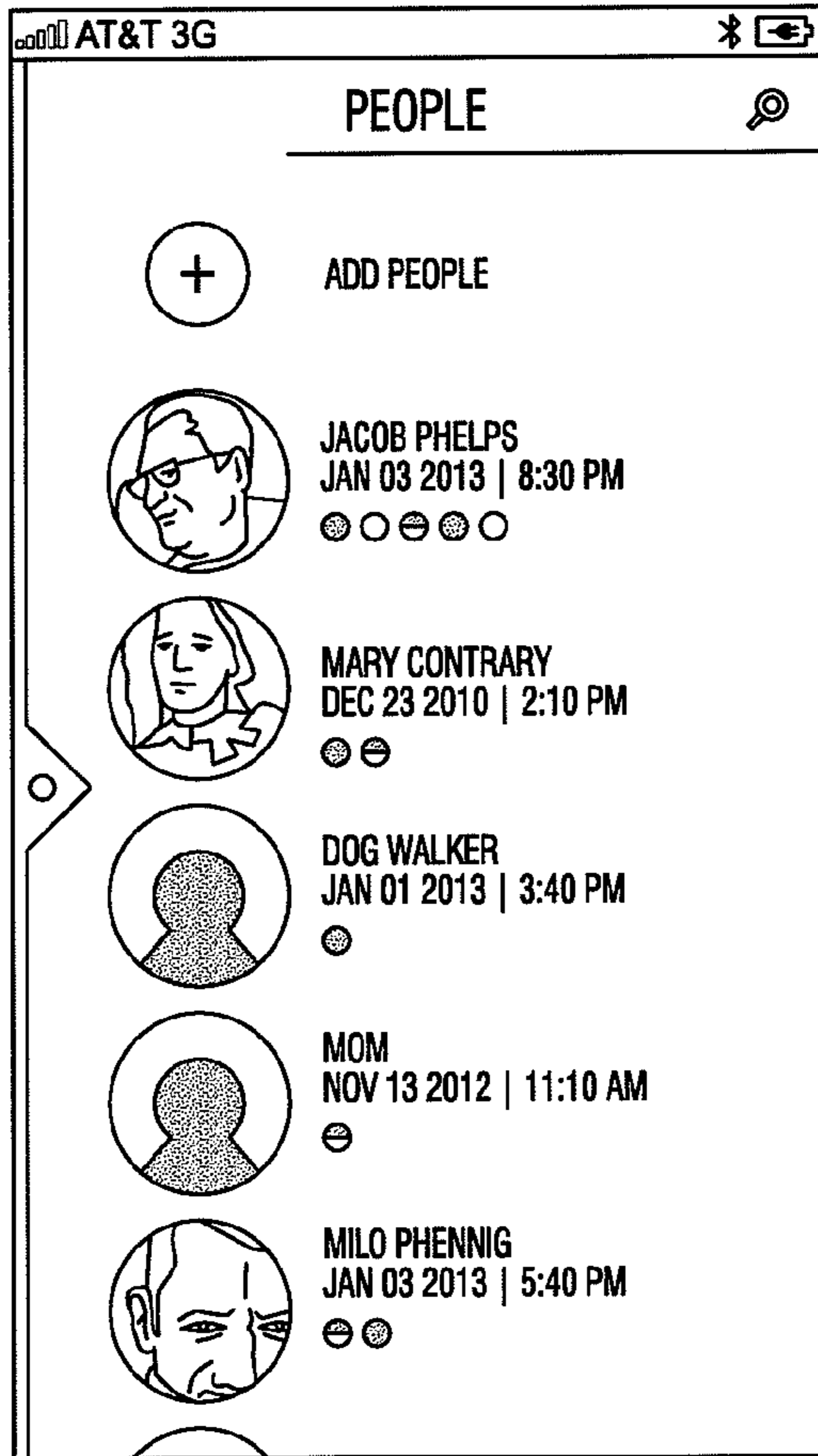


FIG. 21E

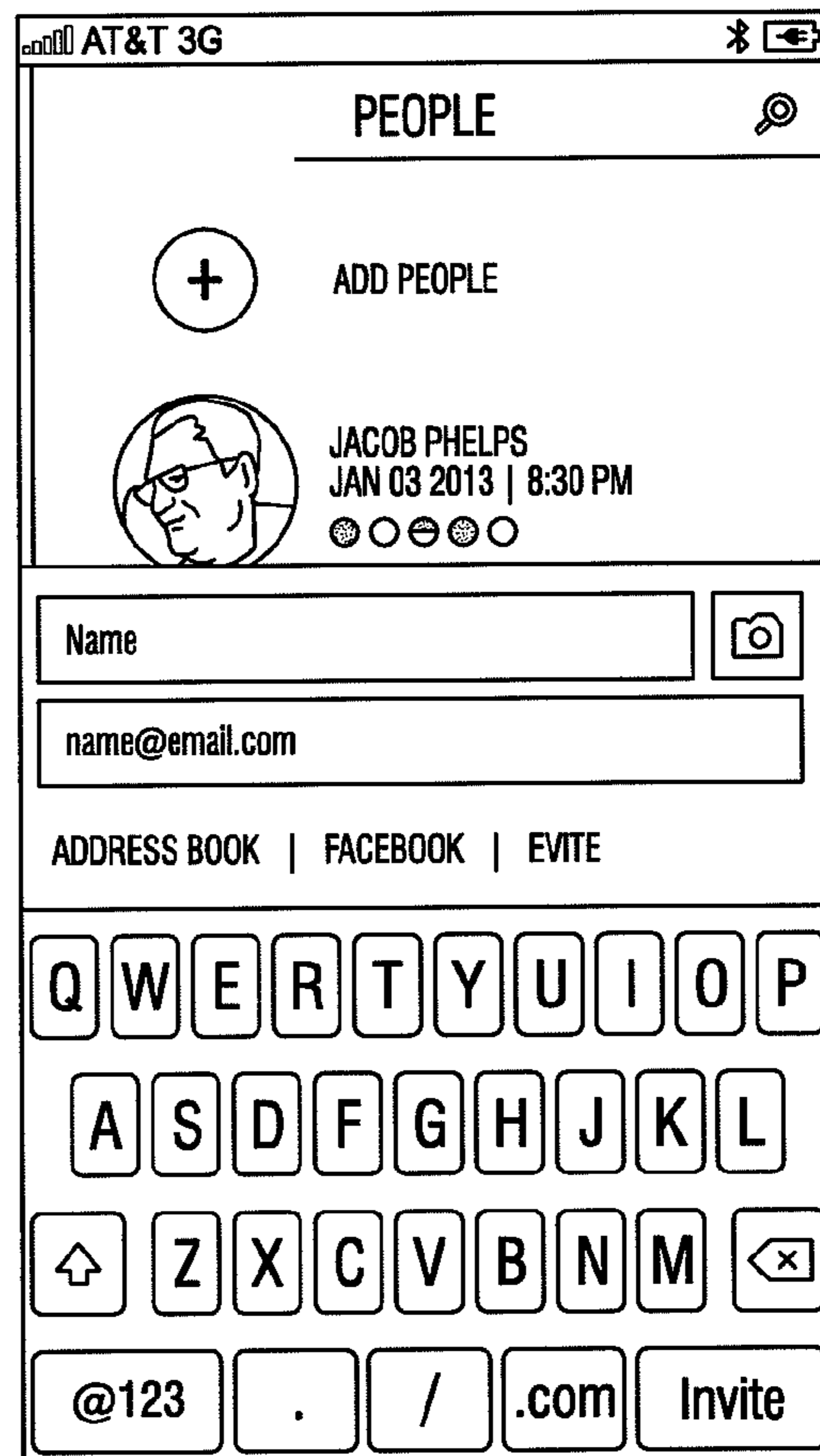


FIG. 21F

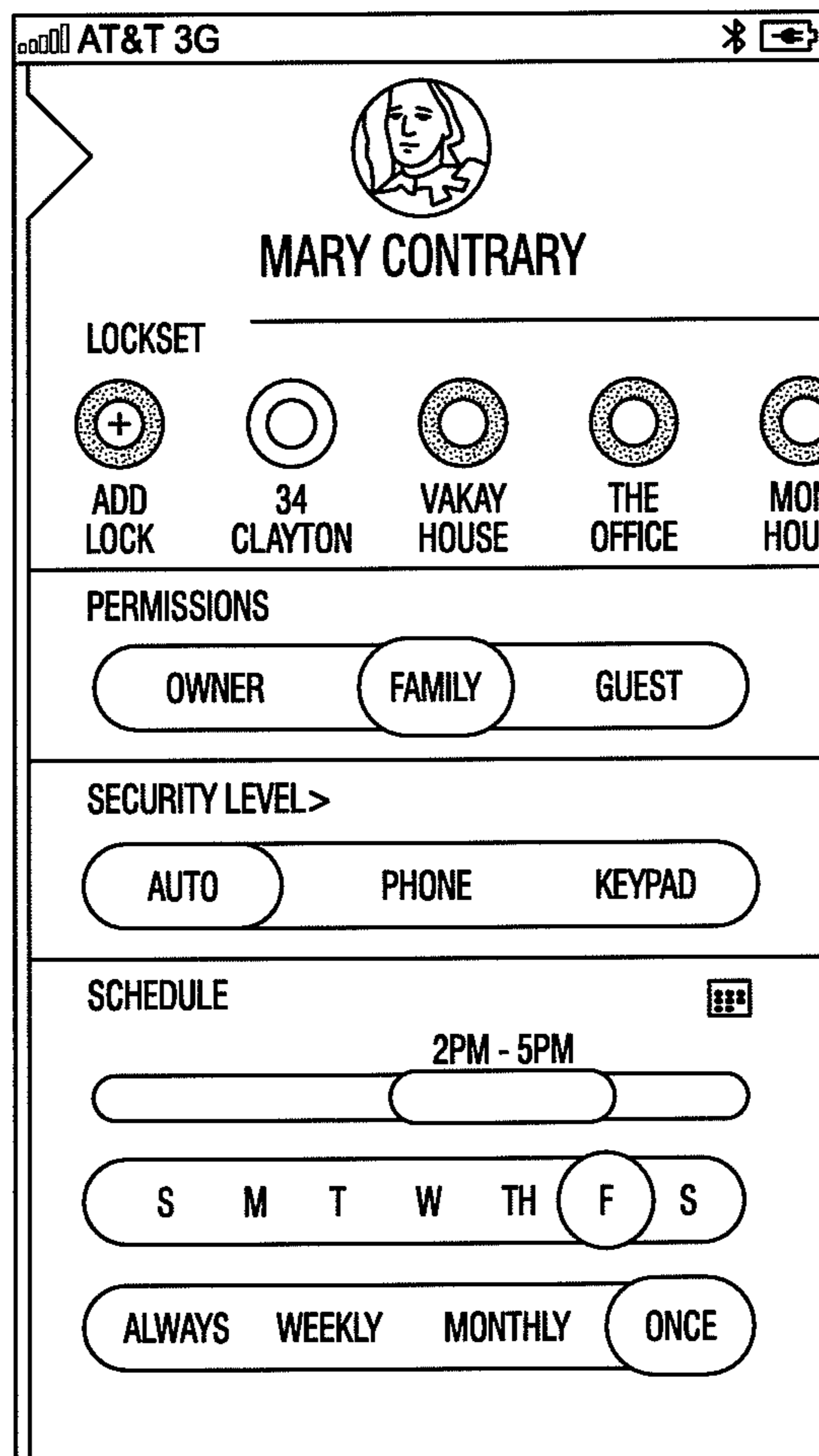


FIG. 21G

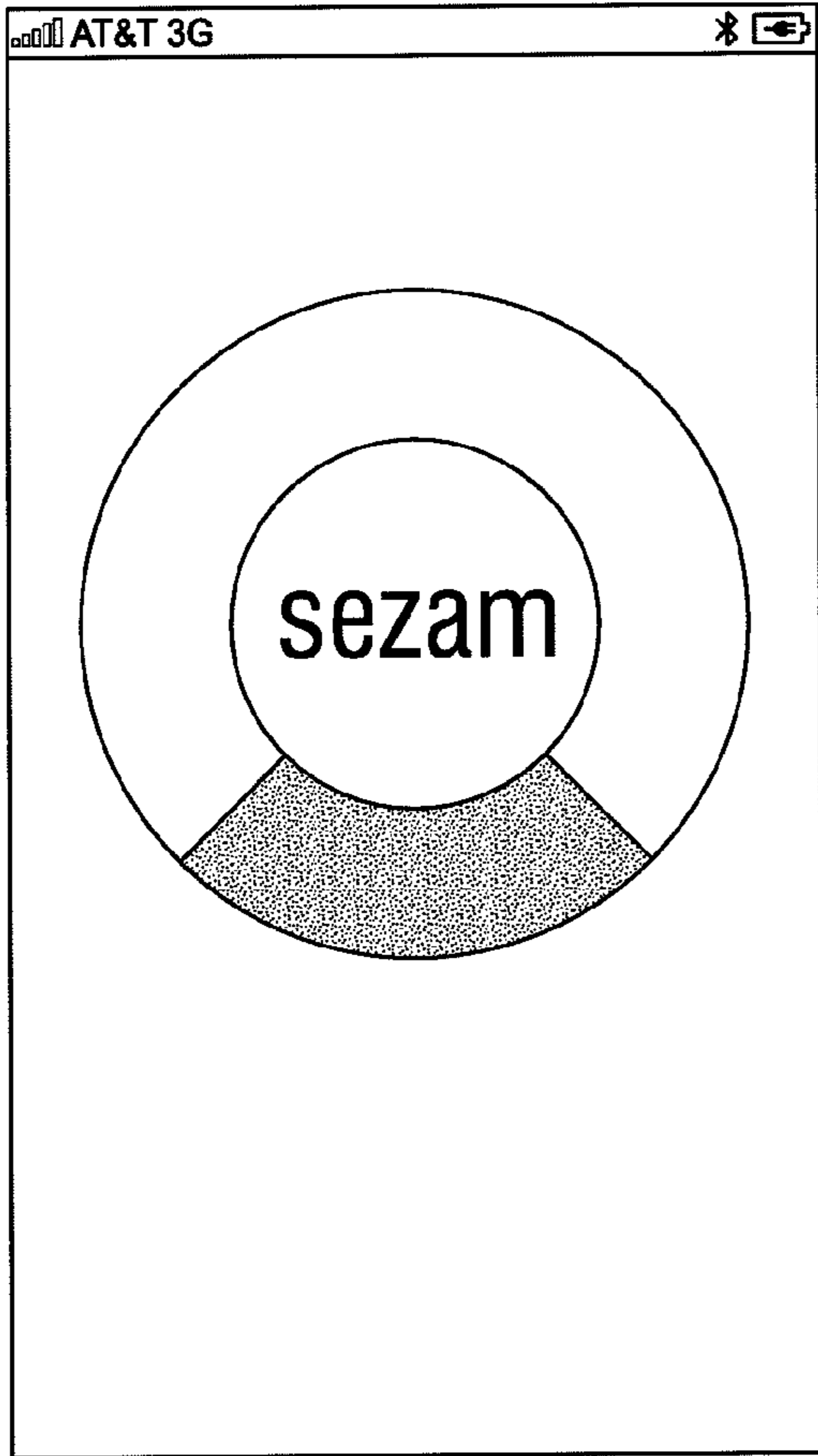


FIG. 22A

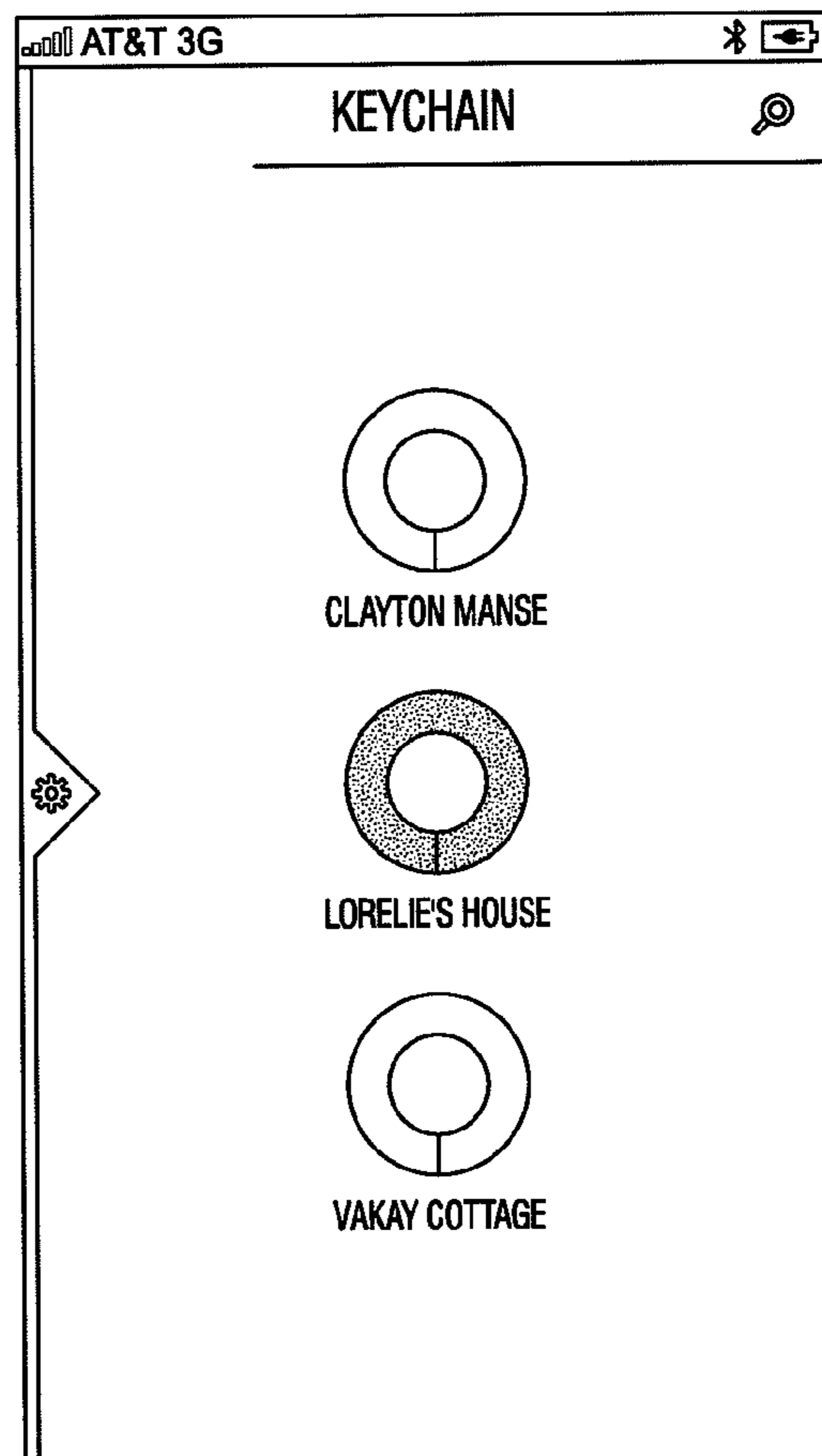


FIG. 22B

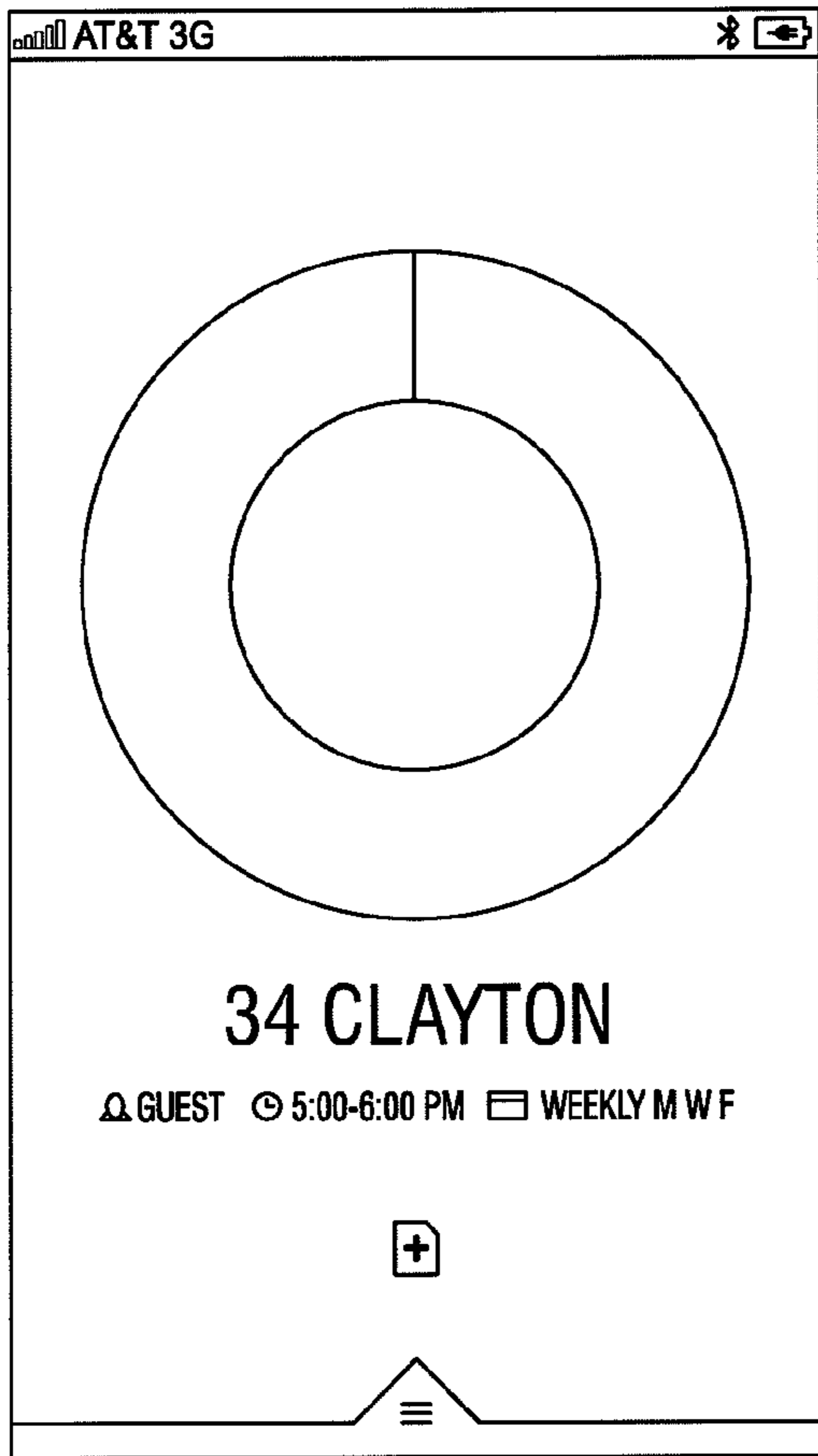


FIG. 22C

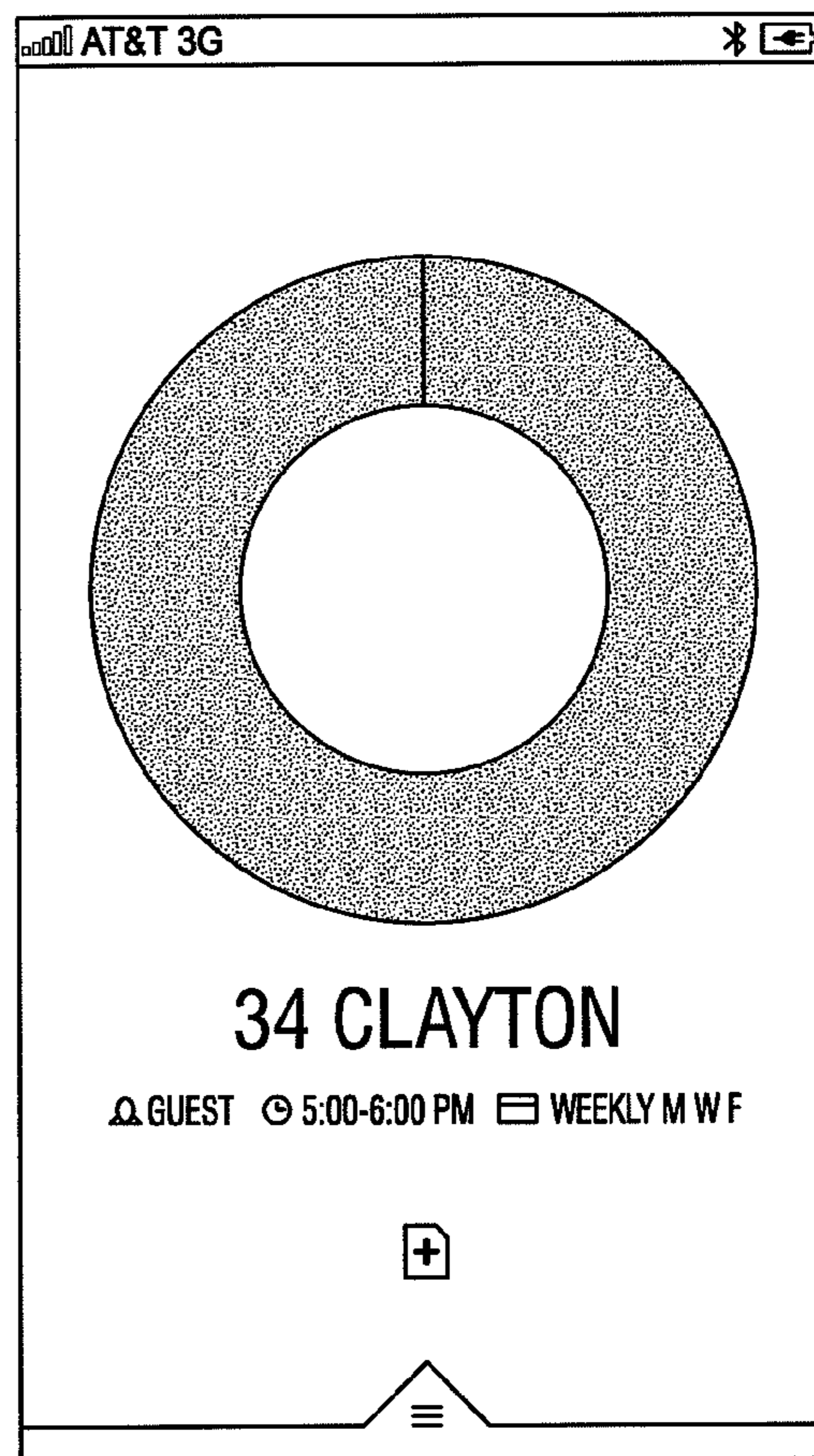


FIG. 22D

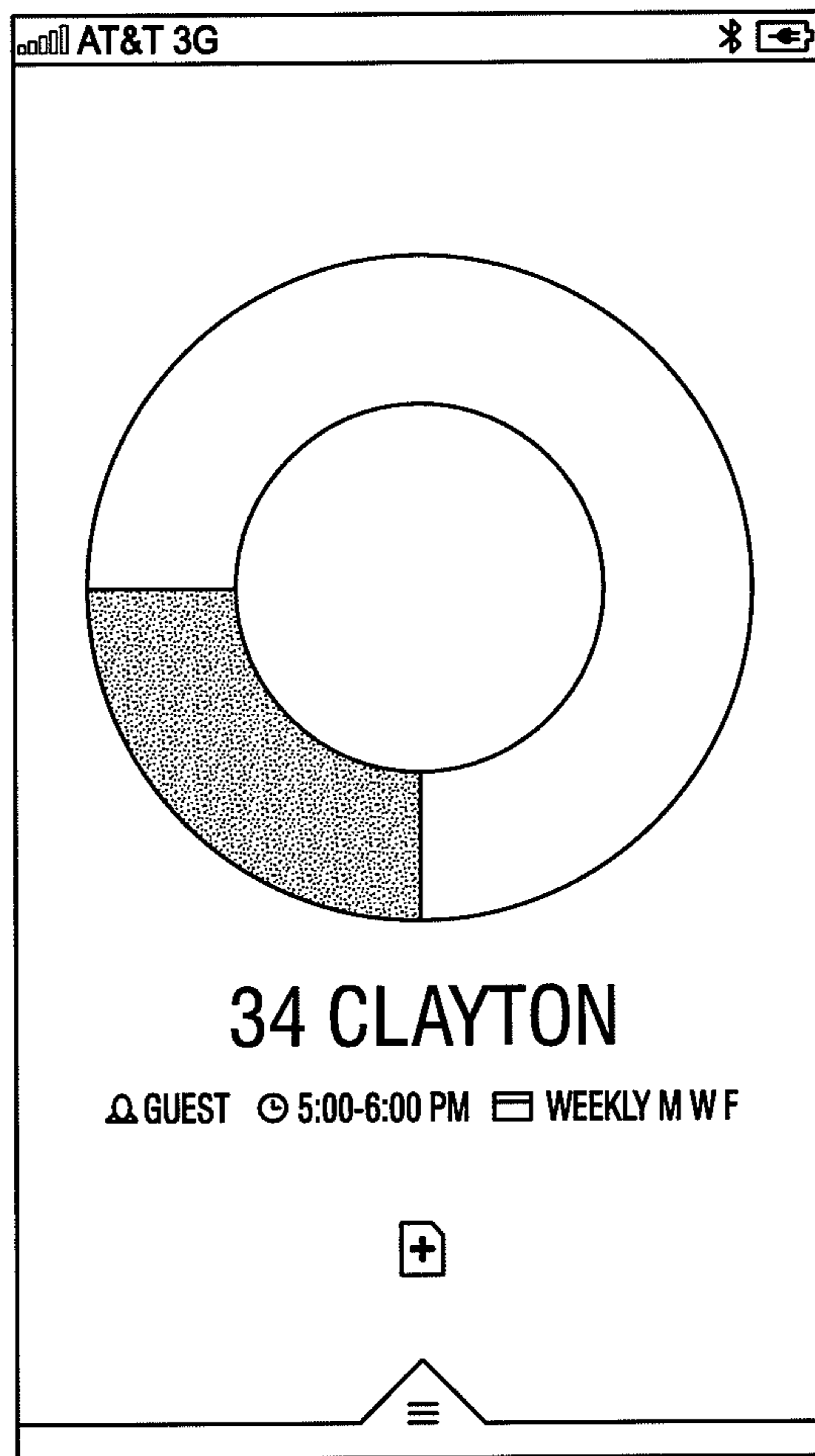


FIG. 22E

Empty Extension Gear

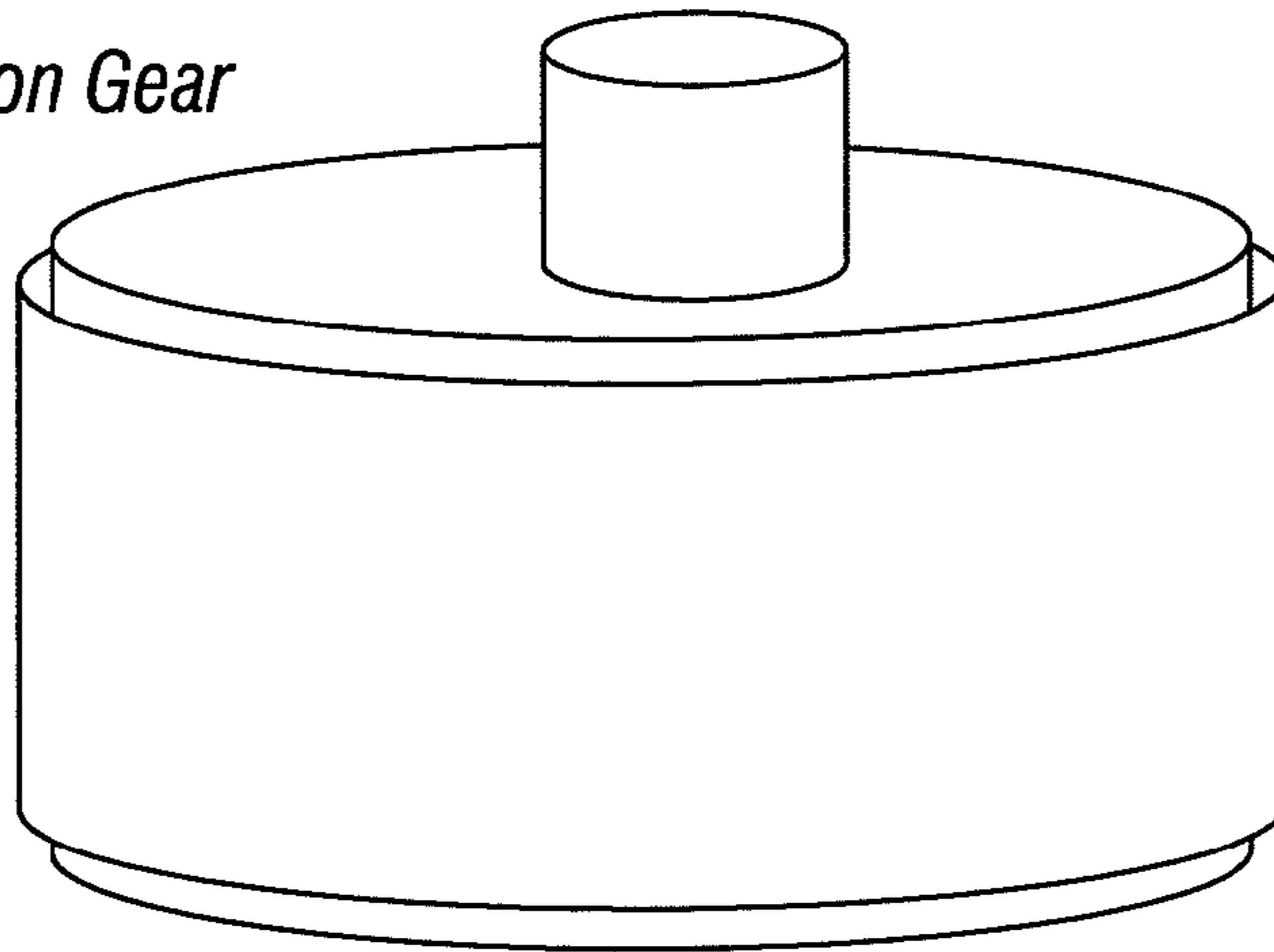
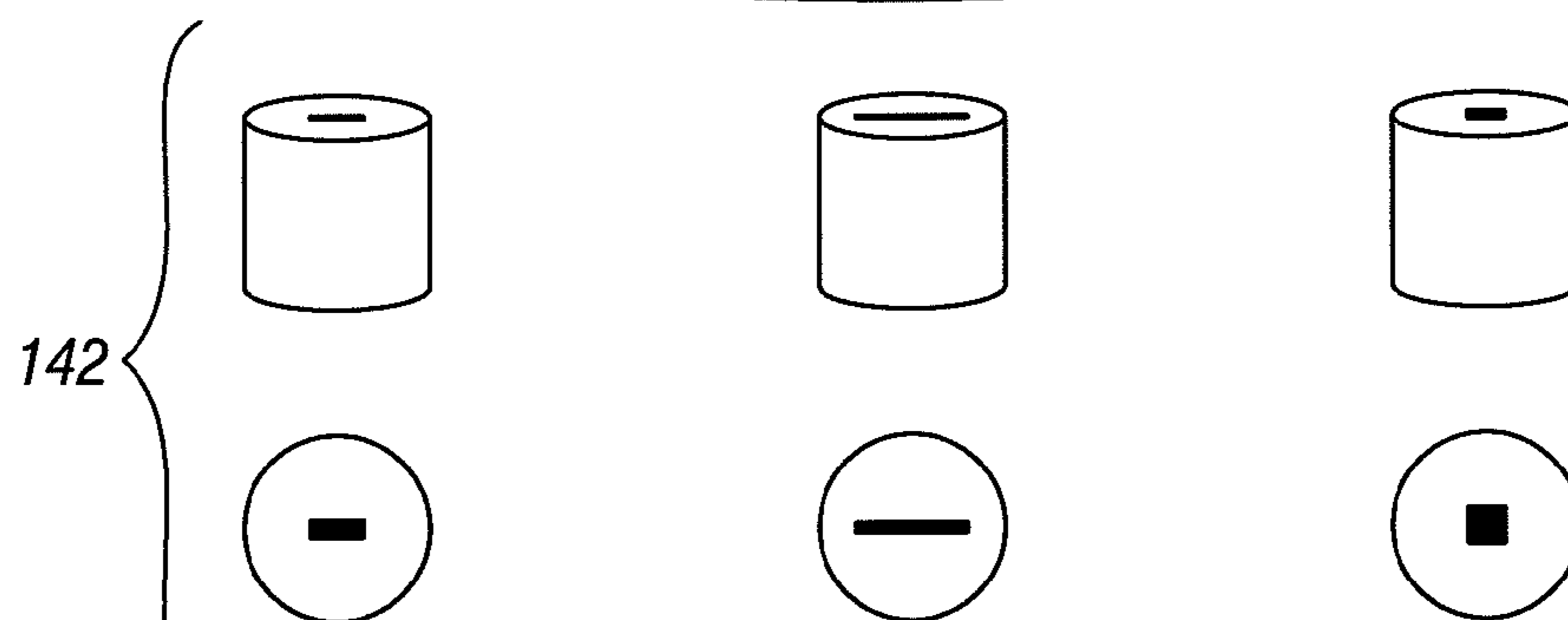
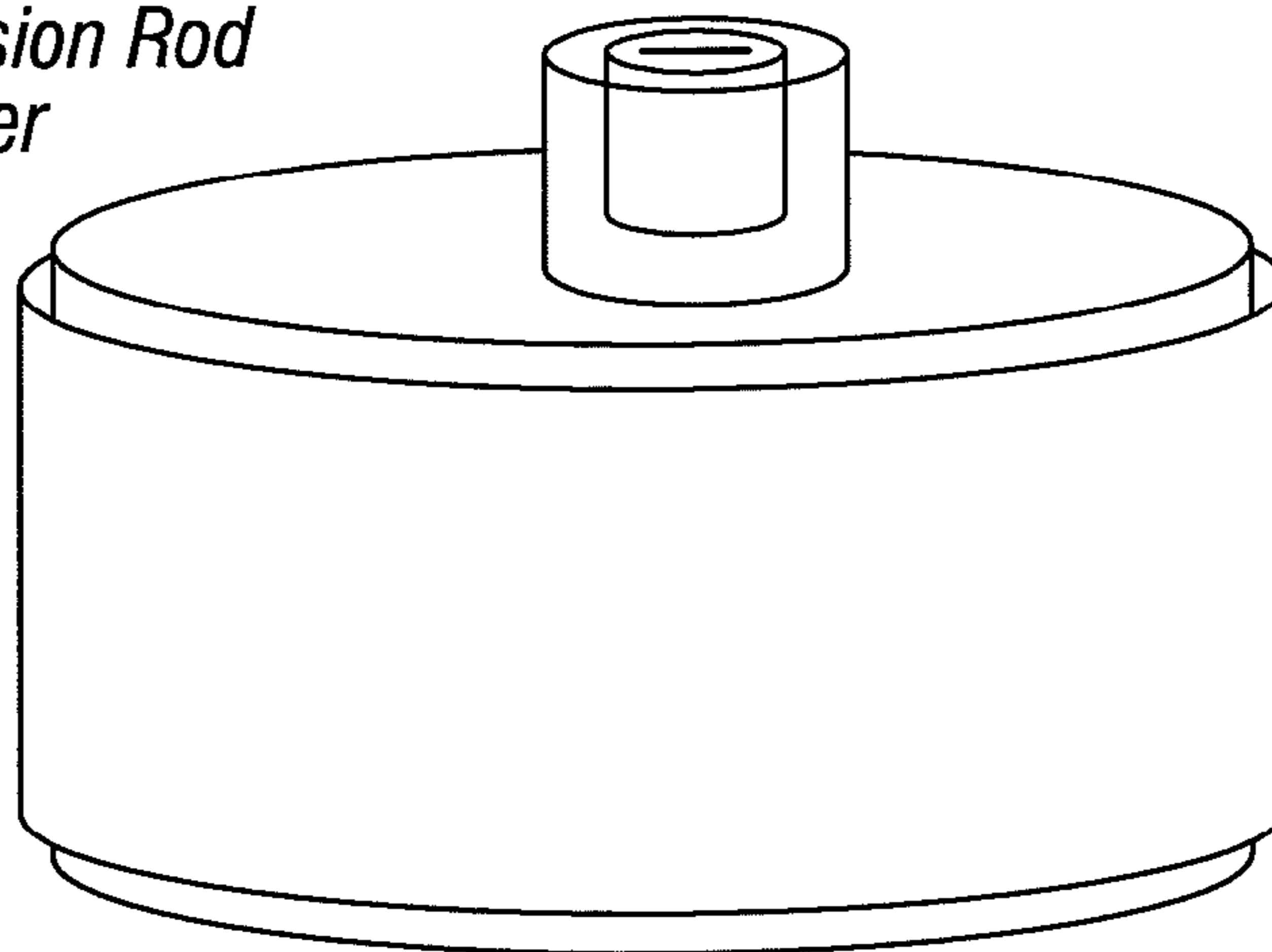


FIG. 23A

Modular Extension Rod Controller



Extension Gear Adapters

FIG. 23B

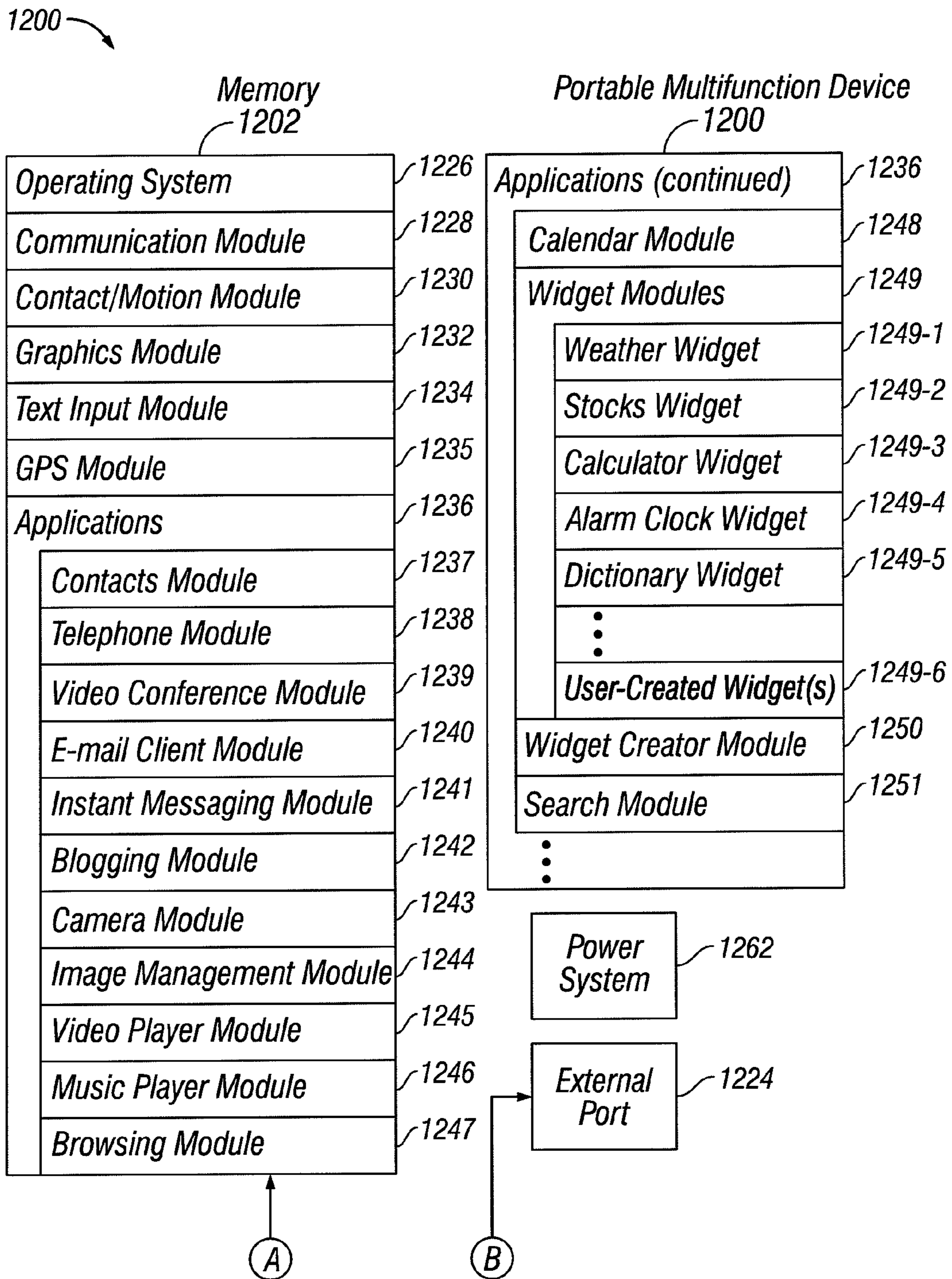


FIG. 24

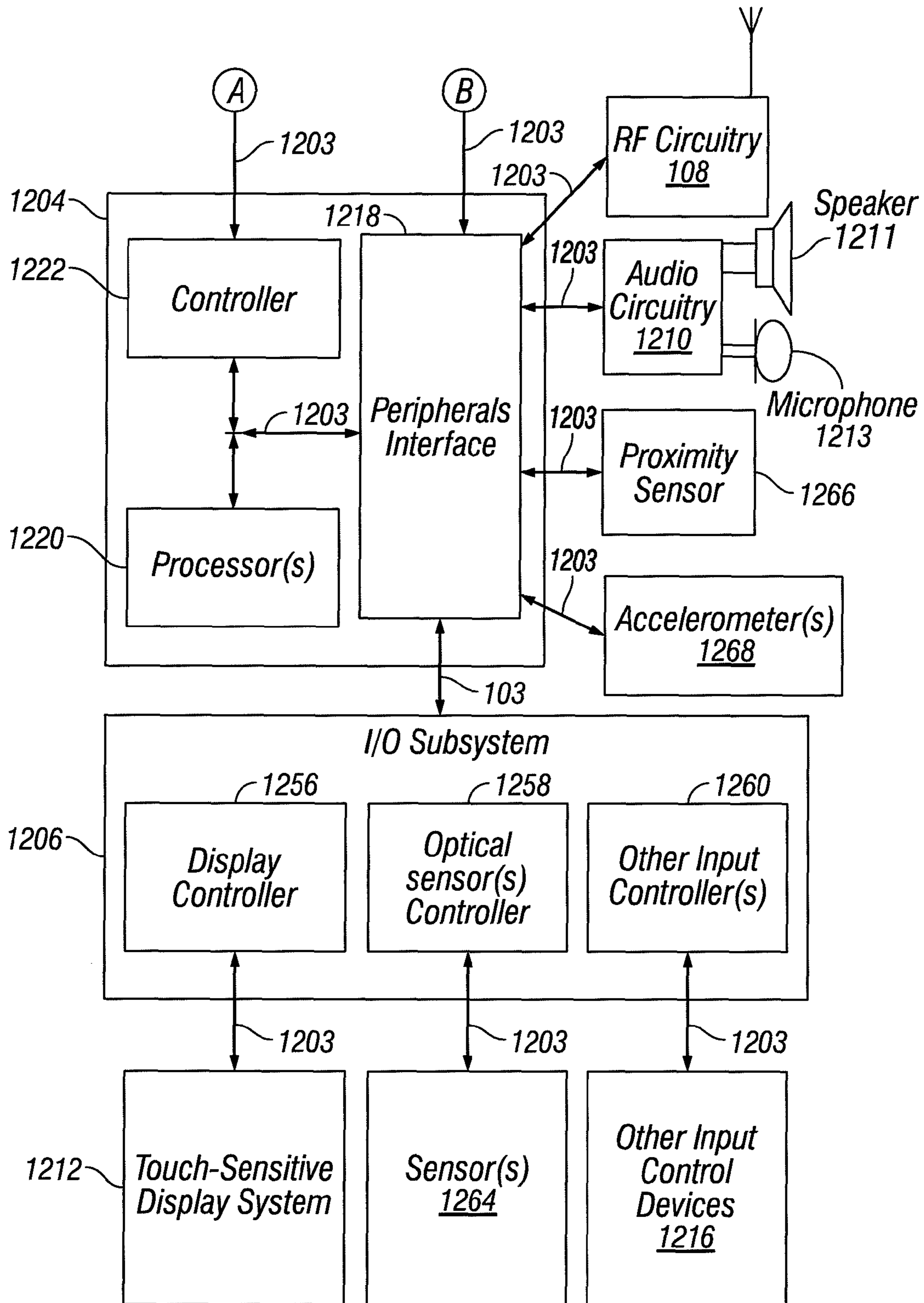


FIG. 24
(Cont'd)

DETERMINING RIGHT OR LEFT HAND SIDE DOOR INSTALLATION

CROSS-REFERENCE TO RELATED APPLICATION

The present application is a Continuation-in-Part of U.S. patent application Ser. No. 14/205,608, filed Mar. 12, 2014, which application claims priority to U.S. Provisional Patent Application Nos. 61/800,937, filed Mar. 15, 2013, 61/801,236, filed Mar. 15, 2013, 61/801,294, filed Mar. 15, 2013 and 61/801,335, filed Mar. 15, 2013; the present application also claims priority to U.S. Provisional Patent Application No. 62/036,979, filed Aug. 13, 2014; U.S. Provisional Patent Application No. 62/036,971, filed Aug. 13, 2014; U.S. Provisional Patent Application No. 62/036,991, filed Aug. 13, 2014; U.S. Provisional Patent Application No. 62/036,989, filed Aug. 13, 2014 and U.S. Provisional Patent Application No. 62/036,993, filed Aug. 13, 2014, the entire contents of which applications are incorporated by reference as set forth herein.

BACKGROUND

1. Field of the Invention

This invention relates generally to door lock devices, and more particularly to determining right or left hand side door installation.

2. Brief Description of the Related Art

Among the more successful assemblies offered for building construction is the pre-hung door assembly in which a door is fully prepared for the reception of latching hardware and is hinged in a door frame so that all the installer need do is mount the door frame within a prepared building wall in order to achieve a properly hung door. The precision with which the door is located and hung within the frame and the accuracy with which the door is prepared for the reception of latching hardware is maintained at a high level by virtue of accomplishing those operations in the factory, with specialized manufacturing tooling, leaving little to chance and to the less sophisticated tools and procedures available to installers in the field.

In order to accommodate the requirement for both right-hand and left-hand openings, it has been necessary to supply pre-hung door assemblies in both configurations, enabling an installer to select the appropriate assembly for a particular installation. The necessity to make available pre-hung door assemblies in both hands essentially doubles the number of assemblies which must be made available by the manufacturer and by the distributor and retailer, requiring larger inventories and the concomitant dedication of greater amounts of space, both for storage and on the selling floor.

However, modular door assemblies present particular difficulties of their own. Specifically, there is scope for confusion as to the handedness of the door. Door sets are not symmetrical, as a door can open on the left-hand side or the right-hand side. In addition, the door can open inwardly or outwardly. It would be apparent that an inward opening door hinged on the left is physically identical to an outward opening door hinged on the right. The same applies to inward opening doors hinged on the right and outward opening doors hinged on the left. However, this presents difficulty in definition, since designers will normally specify, for example a "left-hinged door" which can be of either configuration. It is not unknown for door sets to be supplied to site only to find that the orders have been reversed and further supplies are needed. Examples of complex door assemblies are disclosed

in patent literature, for example FR 2268970, US2004/0016182, U.S. Pat. No. 5,832,670 and WO2005/033458. None of these door assemblies offer an effective simple solution for reversing a door in a door frame.

In addition, problems in the installation and design of doors often only become apparent when they are fitted on site. Clashes between nearby doors or between doors and other fittings may not have been noticed at the design stage. If this happens, the door set must often be scrapped and replaced with an opposite door set.

SUMMARY

An object of the present invention is to provide a method for determining if a door is hung on the right or left side.

Another object of the present invention is to provide a method for determining if a door is hung on the right or left side, with a drive shaft of a door lock mechanism being until there is sufficient extension of the bolt to provide for a lock position of an associated door.

Yet another object of the present invention is to provide a method for determining if a door is hung on the right or left side, with a drive shaft rotation continuing to an end point where there is no further rotational movement of the drive shaft to determine an operating rotational range of the drive shaft.

A further object of the present invention is to provide a method for determining if a door is hung on the right or left side, with a user of the door lock when a drive shaft is at an end point.

Another object of the present invention is to provide a method for determining if a door is hung on the right or left side, with the door lock mechanism being in communication with a user's mobile device.

These and other objects of the present invention are achieved in a method for determining right or hand side door installation. A drive shaft of the door lock mechanism is rotated with the bolt in a clock wise direction or a counter-clock wise direction. The rotation continues until there is sufficient extension of the bolt to provide for a lock position of an associated door.

BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1(a) is an exploded view of a mounting assembly of an intelligent door lock device that can be used with the present invention.

FIG. 1(b) illustrates various embodiments of a positioning sensing device coupled to a drive shaft.

FIG. 1(c) illustrates one embodiment of a door lock device that can be used for retrofitting with an embodiment of an intelligent door lock device of the present invention.

FIG. 1(d) illustrates coupling of a positioning sensing device with a drive shaft of a door lock device.

FIG. 1(e) illustrates one embodiment of an intelligent door lock system of the present invention with an off-center drive.

FIG. 1(f) illustrates a wireless bridge that can be used in one embodiment of the present invention.

FIG. 1(g) illustrates one embodiment of elements coupled to a circuit in one embodiment of the present invention, including a haptic device.

FIGS. 2(a)-(c) illustrate embodiments of front and back surfaces of a main circuit that can be used and included in the intelligent door lock device of the present invention.

FIGS. 2(d)-(f) illustrate an embodiment of non-wire, direct connection between PCBAs in one embodiment of the present invention, with position of a PCBA in intelligent door lock device.

FIGS. 3(a)-(d) illustrate embodiments of LED lighting that can be used with the present invention.

FIGS. 4(a)-(d) illustrate one embodiment of a faceplate and views of a housing that can be used with the present invention.

FIGS. 5(a) and (b) illustrate the rotation range, with a minimized slot length of a faceplate lock that can be used in one embodiment of the present invention.

FIGS. 6(a) and (b) illustrate hook slots that can be used with the present invention.

FIGS. 7(a) through (e) illustrate one embodiment of a mount, with attachment to the mounting plate that can be used with the present invention.

FIGS. 8(a)-(b) illustrate embodiments of the present invention where magnets are utilized.

FIGS. 9(a)-(e) illustrate embodiments of the present invention with wing latches.

FIGS. 10(a)-(c) and FIGS. 11(a)-(d) illustrate further details of wing latching that is used in certain embodiments of the present invention.

FIGS. 12(a)-(d) illustrate embodiments of battery contacts that can be used with the present invention.

FIGS. 13(a) and (b) illustrate embodiments of a motor and gears in one embodiment of the present invention.

FIG. 14 illustrates an embodiment of the plurality of motion transfer device, including but not limited to gears, used in one embodiment of the present invention.

FIGS. 15(a)-(b) illustrate an embodiment of a speaker mounting.

FIGS. 15(c)-(d) illustrate an embodiment of an accelerometer FPC service loop.

FIG. 16 illustrates one embodiment of a back-end associated with the intelligent door lock system.

FIG. 17 is a diagram illustrating an implementation of an intelligent door lock system.

FIGS. 18(a) and (b) illustrate one embodiment of the present invention with a front view and a back view of a door with a bolt and an intelligent door lock system.

FIG. 19 illustrates more details of an embodiment of an intelligent door lock system of the present invention.

FIG. 20 illustrates one embodiment of the present invention showing a set of interactions between an intelligent door lock system, a mobile or computer and an intelligent door lock system back-end.

FIG. 21(a)-21(g) are examples of a user interface for an owner of a building that has an intelligent door lock system in one embodiment of the present invention.

FIGS. 22(a)-22(e) are examples of a user interface for a guest of an owner of a building that has an intelligent door lock system in one embodiment of the present invention.

FIGS. 23(a) and (b) illustrate one embodiment of an intelligent door lock system with an empty extension and extension gear adapters.

FIG. 24 illustrates one embodiment of a mobile device that is used with the intelligent door lock system.

DETAILED DESCRIPTION

As used herein, the term engine refers to software, firmware, hardware, or other component that can be used to effectuate a purpose. The engine will typically include software instructions that are stored in non-volatile memory (also referred to as secondary memory). When the software instructions are executed, at least a subset of the software instructions can be loaded into memory (also referred to as primary memory) by a processor. The processor then executes the software instructions in memory. The processor may be a

shared processor, a dedicated processor, or a combination of shared or dedicated processors. A typical program will include calls to hardware components (such as I/O devices), which typically requires the execution of drivers. The drivers may or may not be considered part of the engine, but the distinction is not critical.

As used herein, the term database is used broadly to include any known or convenient means for storing data, whether centralized or distributed, relational or otherwise.

As used herein a mobile device includes, but is not limited to, a cell phone, such as Apple's iPhone®, other portable electronic devices, such as Apple's iPod Touches®, Apple's iPads®, and mobile devices based on Google's Android® operating system, and any other portable electronic device that includes software, firmware, hardware, or a combination thereof that is capable of at least receiving the signal, decoding if needed, exchanging information with a server to verify information. Typical components of mobile device may include but are not limited to persistent memories like flash ROM, random access memory like SRAM, a camera, a battery, LCD driver, a display, a cellular antenna, a speaker, a Bluetooth® circuit, and WIFI circuitry, where the persistent memory may contain programs, applications, and/or an operating system for the mobile device. A mobile device can be a key fob A key fob which can be a type of security token which is a small hardware device with built in authentication mechanisms. It is used to manage and secure access to network services, data, provides access, communicates with door systems to open and close doors and the like.

As used herein, the term "computer" or "mobile device or computing device" is a general purpose device that can be programmed to carry out a finite set of arithmetic or logical operations. Since a sequence of operations can be readily changed, the computer can solve more than one kind of problem. A computer can include of at least one processing element, typically a central processing unit (CPU) and some form of memory. The processing element carries out arithmetic and logic operations, and a sequencing and control unit that can change the order of operations based on stored information. Peripheral devices allow information to be retrieved from an external source, and the result of operations saved and retrieved.

As used herein, the term "Internet" is a global system of interconnected computer networks that use the standard Internet protocol suite (TCP/IP) to serve billions of users worldwide. It is a network of networks that consists of millions of private, public, academic, business, and government networks, of local to global scope, that are linked by a broad array of electronic, wireless and optical networking technologies. The Internet carries an extensive range of information resources and services, such as the inter-linked hypertext documents of the World Wide Web (WWW) and the infrastructure to support email. The communications infrastructure of the Internet consists of its hardware components and a system of software layers that control various aspects of the architecture, and can also include a mobile device network, e.g., a cellular network.

As used herein, the term "extranet" is a computer network that allows controlled access from the outside. An extranet can be an extension of an organization's intranet that is extended to users outside the organization that can be partners, vendors, and suppliers, in isolation from all other Internet users. An extranet can be an intranet mapped onto the public Internet or some other transmission system not accessible to the general public, but managed by more than one company's administrator(s). Examples of extranet-style networks include but are not limited to:

5

LANs or WANs belonging to multiple organizations and interconnected and accessed using remote dial-up

LANs or WANs belonging to multiple organizations and interconnected and accessed using dedicated lines

Virtual private network (VPN) that is comprised of LANs or WANs belonging to multiple organizations, and that extends usage to remote users using special “tunneling” software that creates a secure, usually encrypted network connection over public LINES, SOMETIMES VIA AN ISP.

As used herein, the term “Intranet” is a network that is owned by a single organization that controls its security policies and network management. Examples of intranets include but are not limited to:

A LAN

A Wide-area network (WAN) that is comprised of a LAN that extends usage to remote employees with dial-up access

A WAN that is comprised of interconnected LANs using dedicated communication lines

A Virtual private network (VPN) that is comprised of a LAN or WAN that extends usage to remote employees or networks using special “tunneling” software that creates a secure, usually encrypted connection over public lines, sometimes via an Internet Service Provider (ISP)

For purposes of the present invention, the Internet, extranets and intranets collectively are referred to as (“Network Systems”).

As used herein, “Haptic Feedback”, “Haptic technology”, or “Haptics”, is a visual, audio or tactile feedback and visual technology, which takes advantage of the sense of an event, by touch, visual or audio. Haptic feedback can be by applying forces, vibrations, visual and audio feedback or motions to the user. This mechanical stimulation can be used to assist in the creation of virtual objects in a computer simulation, to control such virtual objects, and to enhance the remote control of machines and devices (telerobotics). It has been described as doing for the sense of touch what computer graphics does for vision. Haptic devices can incorporate tactile sensors that measure forces exerted by the user on the interface. When referring to mobile phones and similar devices, this generally means the use of vibrations from the device’s vibration alarm to denote that a touchscreen button has been pressed. In this particular example, the phone would vibrate slightly in response to the user’s activation of an on-screen control, making up for the lack of a normal tactile response that the user would experience when pressing a physical button. Haptic feedback can provide a visual indication of an event.

In one embodiment a method is provided of determining right or hand side door installation. The drive shaft of the door lock mechanism is rotated with the bolt in a clock wise direction or a counter-clock wise direction. In one embodiment the rotation continues until there is sufficient extension of the bolt to provide for a lock position of an associated door. In another embodiment the rotation continues to an end point where there is no further rotational movement of the drive shaft to determine an operating rotational range of the drive shaft. In another embodiment is anywhere from a minimum extension of the bolt to provide for the bolt to provide a minimum locking to a full end point. A user of the door lock is then queried when the drive shaft is at the end point to. The door is right hand in-swing (or left hand outswing) installed when the door locks with clock wise rotation and is left hand in-swing (or right hand outswing) installed when the door lock with counter clock wise rotation.

6

In one embodiment the door lock mechanism is in communication with a user’s mobile device. In one embodiment the user’s mobile device communicates a status of bolt extension.

In one embodiment a position sensing device is coupled to the drive shaft to determine the sufficient extension and the end point.

In one embodiment the door lock mechanism includes: an engine with a memory, the engine being coupled to the positioning sensing device; a circuit coupled to the engine;

In one embodiment an energy source is coupled to the circuit; and a device that converts energy into mechanical energy coupled to the circuit, positioning sensing device and the drive shaft, the device that converts energy being coupled to the energy source to receive energy from the energy source.

In one embodiment the device that converts energy is used to rotate the drive shaft to the end point.

In one embodiment the drive shaft is manually until there is sufficient extension of the bolt to provide for a lock position of an associated door.

In one embodiment a recordation is made at the back end of the sufficient extension of the bolt to provide for a lock position of an associated door, the end point and the like.

In one embodiment the user is queried if the bolt is extended. The query can come from the back-end.

In one embodiment the sufficient extension of the bolt is determined when the user sets up the lock system.

In one embodiment the sufficient extension of the bolt to provide for a lock position of the associated door by the drive shaft calibrates its range of motion.

In one embodiment the position sensor determines position and not just relative movement.

In one embodiment a guess is made if the door is right or left side hung and the user is queried if the guess is wrong. This can be done by the back-end.

In one embodiment a door user confirms which side the door is hung. This confirmation can be made using the user’s mobile device and communicated to the back-end.

Referring now to FIG. 1(a), one embodiment of an intelligent door lock system **10** is illustrated, as more fully described hereafter.

In one embodiment, the intelligent door lock system **10** is configured to be coupled to a structure door **12**, including but not limited to a house, building and the like, window, locked cabinet, storage box, bike, automobile door or window, computer locks, vehicle doors or windows, vehicle storage compartments, and the like. In one embodiment, the intelligent door lock system **10** is coupled to an existing drive shaft **14** of a lock device **22** already installed and is retrofitted to all or a portion of the lock device **22**, which includes a bolt/lock **24**.

In another embodiment, the intelligent door lock system **10** is attached to a door **12**, and the like, that does not have a pre-existing lock device. FIG. 1(b) illustrates door lock elements that can be at an existing door, to provide for the mounting of the intelligent door lock system **10** with an existing lock device **22**.

FIG. 1(b) illustrates one embodiment of a lock device **22** that can be pre-existing at a door **10** with the intelligent door lock system **10** retrofitted to it. Components of the lock device **22** may be included with the intelligent door lock device **10**, as more fully discussed hereafter.

In one embodiment, the intelligent door lock system **10** includes a positioning sensing device **16**, a motor **38**, an engine/processor **36** with a memory and one or more wireless communication devices **40** coupled to a circuit **18**. The motor **38** converts any form of energy into mechanical energy. As a non-limiting example, three more four wireless communications devices **40** are in communication with circuit **18**.

In one embodiment, the intelligent door lock system **10** is provided with the position sensing device **16** configured to be coupled to the drive shaft **14** of the lock device **22**. The position sensing device **16** senses position of the drive shaft **14** and assists in locking and unlocking the bolt/lock **24** of the lock device **22**. The engine **36** is provided with a memory. The engine **36** is coupled to the positioning sensing device **16**. A circuit **18** is coupled to the engine **36** and an energy source **50** is coupled to the circuit. A device **38** converts energy into mechanical energy and is coupled to the circuit **18**, positioning sensing device **16** and the drive shaft **14**. Device **38** is coupled to the energy source **50** to receive energy from the energy source **50**, which can be via the circuit **18**.

In one embodiment, the intelligent door lock system **10** includes any or all of the following, a face plate **20**, ring **32**, latches such as wing latches **37**, adapters **28** coupled to a drive shaft **14**, one or more mounting plates **26**, a back plate **30**, a power sensing device **46**, energy sources, including but not limited to batteries **50**, and the like.

In one embodiment (see FIG. 1(c)), the intelligent door lock system **10** retrofits to an existing lock device **22** already installed and in place at a door **12**, and the like. The existing lock device **12** can include one or more of the following elements, drive shaft **14**, a lock device **22** with the bolt/lock **24**, a mounting plate **26**, one or more adapters **28** for different lock devices **22**, a back plate **30**, a plurality of motion transfer devices **34**, including but not limited to, gears **34**, and the like.

In one embodiment, the memory of engine/processor **36** includes states of the door **12**. The states are whether the door **12** is a left handed mounted door, or a right handed mounted door, e.g., opens from a left side or a right side relative to a door frame. The states are used with the position sensing device **16** to determine via the engine/processor **36** if the lock device **22** is locked or unlocked.

In one embodiment, the engine/processor **36** with the circuit **18** regulates the amount of energy that is provided from energy source **50** to the motor **38**. This thermally protects the motor **38** from receiving too much energy and ensures that the motor **38** does not overheat or become taxed.

FIG. 1(d) illustrates various embodiments of the positioning sensing device **16** coupled to the drive shaft **14**.

A variety of position sensing devices **16** can be used, including but not limited to, accelerometers, optical encoders, magnetic encoders, mechanical encoders, Hall Effect sensors, potentiometers, contacts with ticks, optical camera encoders, and the like.

As a non-limiting example, an accelerometer **16**, well known to those skilled in the art, detects acceleration. The accelerometer **16** provides a voltage output that is proportional to a detected acceleration. Suitable accelerometers **16** are disclosed in, U.S. Pat. No. 8,347,720, U.S. Pat. No. 8,544,326, U.S. Pat. No. 8,542,189, U.S. Pat. No. 8,522,596, EP0486657B1, EP 2428774 A1, incorporated herein by reference.

In one embodiment, the position sensing device **16** is an accelerometer **16**. Accelerometer **16** includes a flex circuit coupled to the accelerometer **16**. The accelerometer reports X, Y, and X axis information to the engine/processor **36** of the drive shaft **14**. The engine/processor **36** determines the orientation of the drive shaft **14**, as well as door knocking, bolt/lock **24** position, door **12** close/open (action) sensing, manual key sensing, and the like, as more fully explained hereafter.

Suitable optical encoders are disclosed in U.S. Pat. No. 8,525,102, U.S. Pat. No. 8,351,789, and U.S. Pat. No. 8,476,577, incorporated herein by reference.

Suitable magnetic encoders are disclosed in U.S. Publication 20130063138, U.S. Pat. No. 8,405,387, EP2579002A1, EP2642252 A1, incorporated herein by reference.

Suitable mechanical encoders are disclosed in, U.S. Pat. No. 5,695,048, and EP2564165A2, incorporated herein by reference.

Suitable Hall Effect sensors are disclosed in, EP2454558B1 and EP0907068A1, incorporated herein by reference.

Suitable potentiometers are disclosed in, U.S. Pat. No. 2,680,177, EP1404021A3, CA2676196A1, incorporated herein by reference.

In various embodiments, the positioning sensing device **16** is coupled to the drive shaft **14** by a variety of means, including but not limited to the adapters **28**. In one embodiment, the position sensing device **16** uses a single measurement, as defined herein, of drive shaft **14** position sensing which is used to determine movement in order to determine the location of the drive shaft **14** and the positioning sensing device **16**. The exact position of the drive shaft **14** can be measured with another measurement without knowledge of any previous state. Single movement, which is one determination of position sensing, is the knowledge of whether the door **12** is locked, unlocked or in between. One advantage of the accelerometer is that one can determine position, leave if off, come back at a later time, and the accelerometer **16** will know its current position even if it has been moved since it has been turned off. It will always know its current position.

In one embodiment, the positioning sensing device **16** is directly coupled to the drive shaft **14**, as illustrated in FIG. 1(d). Sensing position of the positioning sensing device **16** is tied to the movement of the drive shaft **14**. In one embodiment with an accelerometer **16**, the accelerometer **16** can detect X, Y and Z movements. Additional information is then obtained from the X, Y, and Z movements. In the X and Y axis, the position of the drive shaft **14** is determined; this is true even if the drive shaft **14** is in motion. The Z axis is used to detect a variety of things, including but not limited to, door **12** knocking, picking of the lock, break-in and unauthorized entry, door **12** open and closing motion. If a mobile device **201** is used to open or close, the processor **36** determines the lock state.

In one embodiment, the same positioning sensing device **16** is able to detect knocks by detecting motion of the door **12** in the Z axis. As a non-limiting example, position sensing is in the range of counter and clock wise rotation of up to 180 degrees for readings. The maximum rotation limit is limited by the position sensing device **16**, and more particularly to the accelerometer cable. In one embodiment, the result is sub 1° resolution in position sensing. This provides a higher lifetime because sampling can be done at a slower rate, due to knowing the position after the position sensing device **16** has been turned off for a time period of no great 100 milli seconds. With the present invention, accuracy can be enhanced taking repeated measurements. With the present invention, the positioning sensing device **16**, such as the accelerometer, does not need to consume additional power beyond what the knock sensing application already uses.

In one embodiment, the position sensing device **16** is positioned on the drive shaft **14**, or on an element coupled to the drive shaft **14**. In one embodiment, a position of the drive shaft **14** and power sensing device and/or a torque limited link **38** are known. When the position of the drive shaft **14** is known, it is used to detect if the bolt/lock **24** of a door lock device **22** is in a locked or unlocked position, as well as a depth of bolt/lock **24** travel of lock device **22**, and the like. This includes but is not limited to if someone, who turned the bolt/lock **24** of lock device **22** from the inside using the ring

32, used the key to open the door 12, if the door 12 has been kicked down, attempts to pick the bolt/lock 24, bangs on the door 12, knocks on the door 12, opening and closing motions of the door 12 and the like. In various embodiments, the intelligent door lock system 10 can be interrogated via hardware, including but not limited to a key, a mobile device, a computer, key fob, key cards, personal fitness devices, such as Fitbit®, nike fuel, jawbone up, pedometers, smart watches, smart jewelry, car keys, smart glasses, including but not limited to Google Glass, and the like.

During a power up mode, the current position of the drive shaft 14 is known.

Real time position information of the drive shaft 14 is determined and the bolt/lock 24 of lock device 22 travels can be inferred from the position information of the drive shaft 14. The X axis is a direction along a width of the door 12, the Y axis is in a direction along a length of a door 12, and the Z axis is in a direction extending from a surface of the door 12.

In one embodiment, the accelerometer 16 is the knock sensor. Knocking can be sensed, as well as the number of times a door 12 is closed or opened, the physical swing of the door 12, and the motion the door 12 opening and closing. With the present invention, a determination is made as to whether or not someone successfully swung the door 12, if the door 12 was slammed, and the like. Additionally, by coupling the position sensing device 16 on the moveable drive shaft 14, or coupled to it, a variety of information is provided, including but not limited to, if the bolt/lock 24 is stored in the correct orientation, is the door 12 properly mounted and the like.

In one embodiment, a calibration step is performed to determine the amount of drive shaft 14 rotations to fully lock and unlock the bolt/lock 24 of lock device 22. The drive shaft 14 is rotated in a counter-counter direction until it can no longer rotate, and the same is then done in the clock-wise direction. These positions are then stored in the engine memory. Optionally, the force is also stored. A command is then received to rotate the drive shaft 14 to record the amount of rotation. This determines the correct amount of drive shaft 14 rotations to properly lock and unlock the lock device 22.

In another embodiment, the drive shaft 14 is rotated until it does not move anymore. This amount of rotation is then stored in the memory and used for locking and unlocking the lock device 22.

In another embodiment, the drive shaft 14 is rotated until it does not move anymore. However, this may not provide the answer as to full lock and unlock. It can provide information as to partial lock and unlock. Records from the memory are then consulted to see how the drive shaft 14 behaved in the past. At different intervals, the drive shaft 14 is rotated until it does not move anymore. This is then statistically analyzed to determine the amount of drive shaft 14 rotation for full locking and unlocking. This is then stored in the memory.

In one embodiment, the engine/processor 36 is coupled to at least one wireless communication device 40 that utilizes audio and RF communication to communicate with a wireless device, including but not limited to a mobile device/key fob 210, with the audio used to communicate a security key to the intelligent door lock system 10 from the wireless device 210 and the RF increases a wireless communication range to and from the at least one wireless communication device 40. In one embodiment, only one wireless communication device 40 is used for both audio and RF. In another embodiment, one wireless communication device 40 is used for audio, and a second wireless communication device 40 is used for RF. In one embodiment, the bolt/lock 22 is included in the intelligent door lock system 10. In one embodiment, the audio commu-

nications initial set up information is from a mobile device/key fob 210 to the intelligent door lock system 10, and includes at least one of, SSID WiFi, password WiFi, a Bluetooth key, a security key and door configurations.

In one embodiment, an audio signal processor unit includes an audio receiver, a primary amplifier circuit, a secondary amplifier circuit, a current amplifier circuit, a wave detection circuit, a switch circuit and a regulator circuit. In one embodiment, the audio receiver of each said audio signal processor unit is a capacitive microphone. In one embodiment, the switch circuit of each audio signal processor unit is selected from one of a transistor and a diode. In one embodiment, the regulator circuit of each audio signal processor unit is a variable resistor. In one embodiment, the audio mixer unit includes a left channel mixer and a right channel mixer. In one embodiment, the amplifier unit includes a left audio amplifier and a right audio amplifier. In one embodiment, the Bluetooth device includes a sound volume control circuit with an antenna, a Bluetooth microphone and a variable resistor, and is electrically coupled with the left channel mixer and right channel mixer of said audio mixer unit. Additional details are in U.S. Publication US20130064378 A1, incorporated fully herein by reference.

In one embodiment, the faceplate 20 and/or ring 32 is electrically isolated from the circuit 18 and does not become part of circuit 18. This allows transmission of RF energy through the faceplate 20. In various embodiments, the faceplate and/or ring are made of materials that provide for electrical isolation. In various embodiments, the faceplate 20, and/or the ring 32 are at ground. As non-limiting examples, (i) the faceplate 20 can be grounded and in non-contact with the ring 32, (ii) the faceplate 20 and the ring 32 are in non-contact with the ring 32 grounded, (iii) the faceplate 20 and the ring can be coupled, and the ring 32 and the faceplate 20 are all electrically isolated from the circuit 18. In one embodiment, the ring 32 is the outer enclosure to the faceplate 20, and the bolt/lock 24 and lock device 22 is at least partially positioned in an interior defined by the ring 32 and the faceplate 20.

In one embodiment, the lock device 22 has an off center drive mechanism relative to the outer periphery that allows up to R displacements from a center of rotation of the bolt/lock 24 of lock device 22, where R is a radius of the bolt/lock 24, 0.75 R displacements, 0.5 R displacements, and the like, as illustrated in FIG. 1(e). The off center drive mechanism provides for application of mechanical energy to the lock device 22 and bolt/lock 22 off center relative to the outer periphery.

As illustrated in FIG. 1(f) in one embodiment, a wireless communication bridge 41 is coupled to a first wireless communication device 40 that communicates with Network Systems via a device, including but not limited to a router, a 3G device, a 4G device, and the like, as well as mobile device 210. The wireless communication bridge 41 is also coupled to a second wireless communication device 40 that is coupled to the processor 38, circuit 18, positioning sensing device 16, motor 38 and the lock device 22 with bolt/lock 24, and provides for more local communication. The first wireless communication device 40 is in communication with the second wireless communication device 40 via bridge 41. The second wireless communication device 40 provides local communication with the elements of the intelligent door lock system 10. In one embodiment, the second communication device 45 is a Bluetooth device. In one embodiment, the wireless communication bridge 41 includes a third wireless communication device 40. In one embodiment, the wireless communication bridge 41 includes two wireless communication devices 40, e.g. third and fourth wireless communication devices 40. In one embodiment, the wireless communication bridge 41

11

includes a WiFi wireless communication device 40 and a Bluetooth wireless communication device 40.

FIG. 1(g) illustrates various elements that are coupled to the circuit 18 in one embodiment of the present invention.

In one embodiment of the present invention, a haptic device 49 is included to provide the user with haptic feedback for the intelligent door lock system 10, see FIG. 1(g). The haptic device is coupled to the circuit 18, the processor 38, and the like. In one embodiment, the haptic device provides a visual indication that the bolt/lock 24 of lock device 22 has reached a final position. In another embodiment, the haptic device 49 provides feedback to the user that the bolt/lock 24 of lock device 22 has reached a home open position versus a final position so the user does not over-torque. A suitable haptic device 49 is disclosed in U.S. Publication No. 20120319827 A1, incorporated herein by reference.

In one embodiment, the wing latches 37 are used to secure the intelligent door lock system 10 to a mounting plate 26 coupled to the door 12. In one embodiment, the wing latches 37 secure the intelligent door lock system 10 to a mounting plate 26 coupled to a door 12 without additional tools other than the wing latches 37.

FIG. 1(g) illustrates one embodiment of circuit 18, as well as elements that includes as part of circuit 18, or coupled to circuit 18, as discussed above.

FIGS. 2(a)-(c) illustrate front and back views of one embodiment of circuit 18, and the positioning of circuit 18 in the intelligent door lock system 10. FIGS. 2(d)-(e) illustrate an embodiment of non-wire, direct connection between PCBAs. FIG. 2(e) shows the relative positioning of a PCBA in the intelligent door lock device 10.

In one embodiment, the main circuit 18 is coupled to, the engine 36 with a processor and memory, the motor 38, wireless communication device 40 such as a WiFi device including but not limited to a Bluetooth device with an antenna, position sensing device 16, speaker (microphone) 17, temperature sensor 42, battery voltage sensor 44, current sensor or power sensor 46 that determines how hard the motor 38 is working, a protection circuit to protect the motor from overheating, an LED array 48 that reports status and one or more batteries 50 that power circuit 18, see FIG. 1(g).

The current sensor 46 monitors the amount of current that goes to the motor 38 and this information is received and processed by the engine/processor 36 with memory and is coupled to the circuit 18. The amount of current going to the motor 38 is used to determine the amount of friction experienced by door 12 and/or lock device 22 with lock/bolt 24 in opening and/or closing, as applied by the intelligent door lock system 10 and the positioning sensing device 16 to the drive shaft 14. The circuit 18 and engine/processor 36 can provide for an adjustment of current. The engine/processor 36 can provide information regarding the door and friction to the user of the door 12.

FIGS. 3(a)-(b) illustrate embodiments of LED 48 lighting that can include diffusers, a plurality of LED patterns point upward, inward, and outward and a combination of all three. In one embodiment two control PCDs are provide to compare side by side. Each LED 48 can be independently addressable to provide for maximization of light with the fewest LEDs 48. In one embodiment, an air gap is provided.

FIGS. 4(a)-(d), illustrate one embodiment of a faceplate 20 and views of the housing 32 and faceplate 20.

FIGS. 5(a) and (b) illustrate the rotation range of the ring 32, with a minimized slot length of a bolt/lock 24 of lock device 22 in one embodiment of the present invention. In one embodiment, there is a 1:1 relationship of ring 32 and shaft rotation. In other embodiments, the ratio can change. This can

12

be achieved with gearing. In various embodiments, the bolt/lock 24 and/or lock device 22 can have a rotation of 20-5 and less turns clockwise or counter-clockwise in order to open the door 12. Some lock devices 22 require multiple turns.

FIGS. 6(a) and (b), with front and back views, illustrate hook slots 52 that can be used with the present invention.

FIGS. 7(a) through (f) illustrate an embodiment of a mount 54, with attachment to the mounting plate 26. Screws 56 are captured in the housing 58, and/or ring 32 and accessed through a battery cavity. A user can open holes for access and replace the screws 56. In one embodiment, the screws extend through the mounting plate 26 into a door hole. In one embodiment, a height of the mounting plate 26 is minimized. During assembly, the lock device 22 is held in place, FIG. 7(c), temporarily by a top lip, FIG. 7(d) and the lock drive shaft 14.

FIGS. 8(a)-(b) illustrate embodiments where magnets 60 are utilized. The magnet 60 locations are illustrated as are the tooled recesses from the top and side. In one embodiment, the magnets 60 are distanced by ranges of 1-100 mm, 3-90, 5-80 mm apart and the like.

FIGS. 9(a)-(e) illustrate embodiments of the present invention with wing latches 36. The wing latches 36 allow for movement of the lock device 22 with bolt/lock 24 towards its final position, in a Z-axis direction towards the door 12. Once the lock device 22 with bolt/lock 24 is in a final position, the wing latches 36 allows for the secure mounting without external tools. The wing latches 36 do the mounting. Wing latches 36 enable mounting of the lock device 22 and bolt/lock 24 with use of only the Z axis direction only, and X and Y directionality are not needed for the mounting.

In one embodiment, a lead in ramp, FIG. 9(e) is used to pull the elements together.

FIGS. 10(a)-(c) and FIGS. 11(a)-(d) illustrate further details of wing latching.

FIGS. 12(a)-(d) illustrate embodiments of battery contacts 64.

FIGS. 13(a) and (b) illustrate embodiments of motor 38 and one or more gears 34, with a gearbox 66. In one embodiment, a first gear 34 in sequence takes a large load if suddenly stopped while running.

FIG. 14 illustrates an embodiment of a plurality of motion transfer devices such as gears 34. There can be come backlash in a gear train as a result of fits and tolerances. There can also be play between adapters 28 and lock drive shafts 14. This can produce play in an out gearbox 66 ring. This can be mitigated with a detent that located the outer ring.

The intelligent door lock system 10 can be in communication with an intelligent door lock system back-end 68, via Network Systems, as more fully described hereafter.

In one embodiment, the flex circuit 18, which has an out-of-plane deflection of at least 1 degree, includes a position detector connector 46, Bluetooth circuit, and associated power points, as well as other elements.

In one embodiment, the intelligent door lock system 10 can use incremental data transfer via Network Systems, including but not limited to BLUETOOTH® and the like. The intelligent door lock system 10 can transmit data through the inductive coupling for wireless charging. The user is also able to change the frequency of data transmission.

In one embodiment, the intelligent door lock system 10 can engage in intelligent switching between incremental and full syncing of data based on available communication routes. As a non-limiting example, this can be via cellular networks, WiFi, BLUETOOTH® and the like.

In one embodiment, the intelligent door lock system **10** can receive firmware and software updates from the intelligent lock system back-end **68**.

In one embodiment, the intelligent door lock system **10** produces an output that can be received by an amplifier, and decoded by an I/O decoder to determine I/O logic levels, as well as, both clock and data information. Many such methods are available including ratio encoding, Manchester encoding, Non-Return to Zero (NRZ) encoding, or the like; alternatively, a UART type approach can be used. Once so converted, clock and data signals containing the information bits are passed to a memory at the intelligent door lock system **10** or intelligent door lock system back-end **68**.

In one embodiment, the intelligent door lock system **10**, or associated back-end **68**, can include a repeatable pseudo randomization algorithm in ROM or in ASIC logic.

FIGS. **15(a)-(b)** illustrate an embodiment of a speaker **17** and speaker mounting **70**.

FIGS. **15(c)-(d)** illustrate one embodiment of an accelerometer FPC service loop.

As illustrated in FIG. **16**, the intelligent door lock system back-end **68** can include one or more receivers **74**, one or more engines **76**, with one or more processors **78**, coupled to conditioning electronics **80**, one or more filters **82**, one or more communication interfaces **84**, one or more amplifiers **86**, one or more databases **88**, logic resources **90** and the like.

The back-end **68** knows that an intelligent door lock system **10** is with a user, and includes a database with the user's account information. The back-end **68** knows if the user is registered or not. When the intelligent door lock system **10** is powered up, the back-end **68** associated that intelligent door lock system **10** with the user.

The conditioning electronics **80** can provide signal conditioning, including but not limited to amplification, filtering, converting, range matching, isolation and any other processes required to make sensor output suitable for processing after conditioning. The conditioning electronics can provide for, DC voltage and current, AC voltage and current, frequency and electric charge. Signal inputs accepted by signal conditioners include DC voltage and current, AC voltage and current, frequency and electric charge. Outputs for signal conditioning electronics can be voltage, current, frequency, timer or counter, relay, resistance or potentiometer, and other specialized output.

In one embodiment, the one or more processors **78**, can include a memory, such as a read only memory, used to store instructions that the processor may fetch in executing its program, a random access memory (RAM) used by the processor **78** to store information and a master dock. The one or more processors **78** can be controlled by a master clock that provides a master timing signal used to sequence the one or more processors **78** through internal states in their execution of each processed instruction. In one embodiment, the one or more processors **78** can be low power devices, such as CMOS, as is the necessary logic used to implement the processor design. Information received from the signals can be stored in memory.

In one embodiment, electronics **92** are provided for use in intelligent door system **10** analysis of data transmitted via System Networks. The electronics **92** can include an evaluation device **94** that provides for comparisons with previously stored intelligent door system **10** information.

Signal filtering is used when the entire signal frequency spectrum contains valid data. Filtering is the most common signal conditioning function, as usually not all the signal frequency spectrum contains valid data.

Signal amplification performs two important functions: increases the resolution of the inputted signal, and increases its signal-to-noise ratio.

Suitable amplifiers **86** include but are not limited to sample and hold amplifiers, peak detectors, log amplifiers, antilog amplifiers, instrumentation amplifiers, programmable gain amplifiers and the like.

Signal isolation can be used in order to pass the signal from to a measurement device without a physical connection. It can be used to isolate possible sources of signal perturbations.

In one embodiment, the intelligent door lock system back-end **68** can provide magnetic or optic isolation. Magnetic isolation transforms the signal from voltage to a magnetic field, allowing the signal to be transmitted without a physical connection (for example, using a transformer). Optic isolation takes an electronic signal and modulates it to a signal coded by light transmission (optical encoding), which is then used for input for the next stage of processing.

In one embodiment, the intelligent door lock system **10** and/or the intelligent door lock system back-end **68** can include Artificial Intelligence (AI) or Machine Learning-grade algorithms for analysis. Examples of AI algorithms include Classifiers, Expert systems, case based reasoning, Bayesian networks, and Behavior based AI, Neural networks, Fuzzy systems, Evolutionary computation, and hybrid intelligent systems.

Information received or transmitted from the back-end **68** to the intelligent door system **10** and mobile device **210** can use logic resources, such as AI and machine learning grade algorithms to provide reasoning, knowledge, planning, learning communication, and create actions.

In one embodiment, AI is used to process information from the intelligent door lock system **10**, from mobile device **210**, and the like. The back-end **68** can compute scores associated with various risk variables involving the intelligent door lock system **10**. These score can be compared to a minimum threshold from a database and an output created. Alerts can be provided to the intelligent door lock system **10**, mobile device **210** and the like. The alert can provide a variety of options for the intelligent door lock system **10** to take, categorizations of the received data from the mobile device **210**, the intelligent door lock system **10**, and the like, can be created. A primary option can be created as well as secondary options.

In one embodiment, data associated with the intelligent door lock system **10** is received. The data can then be pre-processed and an array of action options can be identified. Scores can be computed for the options. The scores can then be compared to a minimum threshold and to each other. A sorted list of the action options based on the comparison can be outputted to the intelligent door lock system **10**, the mobile device **210** and the like. Selections can then be received indicating which options to pursue. Action can then be taken. If an update to the initial data is received, the back-end **68** can then return to the step of receiving data.

Urgent indicators can be determined and directed to the intelligent door lock system **10**, including unlocking, locking and the like.

Data received by the intelligent door lock system **10** and mobile device **210** can also be compared to third party data sources.

In data evaluation and decision making, algorithm files from a memory can be accessed specific to data and parameters received from the intelligent door lock system **10** and mobile device **210**.

Scoring algorithms, protocols and routines can be run for the various received data and options. Resultant scores can then be normalized and weights assigned with likely outcomes.

The intelligent door lock system **10** can be a new lock system mounted to a door **12**, with all or most of the elements listed above, or it can be retrofitted over an existing lock device **22**.

To retrofit the intelligent door lock system **10** with an existing lock system, the user makes sure that the existing lock device **22** and bolt/lock **24** is installed right-side up. The existing thumb-turn is then removed. With some lock devices **22**, additional mounting plates **26** need to be removed and the intelligent door lock system **10** can include replacement screws **56** that are used. The correct mounting plate **26** is then selected. With the existing screws **56** in the thumb-turn, the user sequentially aligns with 1 of 4 mounting plates **26** that are supplied or exist. This assists in determining the correct diameter and replace of the screws **56** required by the bolt/lock **24**. The mounting plate **26** is then positioned. The correct adapter **28** is positioned in a center of the mounting plate **26** to assist in proper positioning. Caution is made to ensure that the adapter **28** does not rub the sides of the mounting plate **26** and the screws **56** are then tightened on the mounting plate **26**. The intelligent door lock system bolt/lock **24** of lock device **22** is then attached. In one embodiment, this is achieved by pulling out side wing latches **36**, sliding the lock device **22** and/or bolt/lock **24** over the adapter **28** and pin and then clamping down the wings **36** to the mounting plate **26**. The faceplate is rotated to open the battery compartment and the battery tabs are then removed to allow use of the battery contacts **64**. An outer metal ring **32** to lock and unlock the door **12** is then rotated. An app from mobile device **210** and/or key then brings the user through a pairing process.

A door **12** can be deformed, warped, and the like. It is desirable to provide a customer or user, information about the door, e.g., if it is deformed, out of alignment, if too much friction is applied when opening and closing, and the like.

As recited above, the current sensor **46** monitors the amount of current that goes to the motor **38** and this information is received and processed by the engine/processor **36** with memory and is coupled to the circuit **18**. The amount of current going to the motor **38** is used to determine the amount of friction experienced by door **12** and/or lock device **22** in opening and/or closing, as applied by the intelligent door lock system **10** and the positioning sensing device **16** to the drive shaft **14**. The circuit **18** and engine/processor **36** can provide for an adjustment of current. The engine/processor **36** can provide information regarding the door and friction to the user of the door **12**.

In one embodiment of the present invention, the intelligent door lock system **10** provides an ability to sense friction on the lock device **22** and/or door **12** by measuring the torque required to move the bolt/lock **24**. The intelligent door lock system **10** increases the applied torque gradually until the bolt/lock **24** moves into its desired position, and the applied torque is the minimum amount of torque required to move the bolt/lock **24**, which is directly related to how deformed the door is.

In one embodiment, when a bad door is detected, a customer can be notified that their door may require some servicing. In one embodiment, door deformation can be detected with a torque device is used to determine if the torque applied when the door is rotated is too high. As a non-limiting example, this can be 2-15 in lbs of torque The intelligent door lock system back end **68** can then perform a comparison

between the measured torque with a standard, or a norm that is included in the one or more databases **88**.

In one embodiment of the present invention, before the door is serviced, the intelligent door lock system **10** allows operation by offering a high-friction mode. As a non-limiting example, the high friction mode is when, as non-limiting examples, 2 inch lbs, 3 inch lbs., 3.5 inch pounds, and the like are required to open the door. In the high friction mode, the bolt/lock **24** is driven while the user is pushing, lifting, torquing the door, pulling, performing visual inspections of rust, blockage, other conditions that can compromise a door and the like, that is applied to the doorknob. The position sensing device **16** is used to determine if the bolt/lock **24** was moved to a final position. In the high friction mode, motion of the door closing is confirmed. Upon detecting the closing of the door, the bolt/lock **24** is then driven. When the user receives an auditory, visual, or any other type of perceptible confirmation, the user then knows that the door has been locked. In one embodiment, the firmware elements, of the intelligent door lock system **10**, as well as other door lock device **22** elements, can also attempt to drive the bolt/lock **24** for a second time when the first time fails. However, this can result in more power consumption, reducing lifetime of the power source, particularly when it is battery **50** based.

In one embodiment of the present invention, the intelligent door lock system **10** seeks to have the motor **38** operate with reduced energy consumption for energy source lifetime purposes, as well as eliminate or reduce undesirable noises, operations, and user experiences that occur when this is a failure in door locking and unlocking, particularly due to door deformation, door non-alignment, as well as other problems with the door that can be irritating to the person locking or unlocking the door.

In one embodiment of the present invention, the intelligent door lock system back-end **68** can track performance of doors and friction levels across time and build a service to encourage users to better maintain their doors. Such service can be a comparison of a door's friction level to other users that are similar geographic locations, at similar weather pattern, such that the user is encouraged to maintain their doors at a competent level. There can be a comparison to standards that at a certain level the door becomes unsafe. Guidelines are provided as to how to maintain their doors. This can be achieved by asking a door user what improves their door, including but not limited to, pushing, lifting, torquing the door, pulling, visual inspections of rust, blockage, other conditions that can compromise a door, and the like. The analysis and comparison can be conducted at the back-end **68** and the results computed to door lock operator as well as others.

In one embodiment of the present invention, the intelligent door lock system **10** has a deformed operation mode that can be activated after a selected amount of time. As a non-limiting example, this can immediately after the user has been notified, more than 1 pico second, 1 second, 5 seconds, and greater periods of time. The deformed operation mode can be activated by the intelligent door lock system **10** itself, or by the intelligent door lock system back-end **68**. It can be activated on the door operator's request. In one embodiment, the back-end **68** can anticipate these problems. As non-limiting examples, these can include but are not limited to, due to analysis of doors **12** in similar geographic areas, doors under similar conditions, doors with similar histories, similar environmental conditions, as well as the history of a particular door, and the like.

The deformed mode provides cooperation with the door user to more readily open the door. In one embodiment, this is a mechanism for the door to communicate back to the door

lock operator. As a non-limiting example, feedback can be provided to the door operator. Such feedback can include, but is not limited to, communication via, tactile, audio, visual, temperature, electronic, wirelessly, through a computer, mobile device and the like. In another embodiment, the operator can signify to the door the operator's desire to leave by unlocking and opening the door **12**. This is a door operator and lock communication. The door operator can close the door, which is sensed by the intelligent door lock system **10**, a timer can then be initiated to provide with door operator with a selected time period in which the door operator can manually alleviate the friction problem. When the time has expired, the intelligent door system **10** can then lock the door **12**. Upon detecting a successful door locking event, the intelligent door lock system **10** can advise the door operator that there is a successful door locking. If the door locking is not successful, the intelligent door lock system **10** can provide a message to the door operator via a variety of means, including but not limited to a message or alert to the door lock operator's mobile device. Such a mobile device message provides the door operator with notification that door locking was not successful or achieved, and the door lock operator can then take action to lock the door **12** either in person, wirelessly, and the like.

For entry, communication with the lock device **22** may be different. In one embodiment, it can be locking coupled with close proximity to a mobile device that is exterior to the door.

In another embodiment of the present invention, the intelligent door lock system back-end **68** can track performance of doors and friction levels across time and build a simple service to encourage users to maintain their doors better, as discussed above.

This information can be stored in the one or more databases **64**.

In one embodiment of the present invention, the intelligent door lock system **10** unlocks when a selected temperature is reached, when smoke is detected, when a fire is detected by processor **38** and the like. As non-limiting examples, the intelligent door lock system **10** unlocks the bolt/lock **24** when a temperature is sensed by the temperature sensor **46** that, as non-limiting examples, is greater than 40 degrees C., any temperature over 45 degrees C. and the like. The temperature sensor **46** **212** sends a signal to the processor **36** which communicates with the motor **38** that will then cause the drive shaft **14** to rotate sufficiently and unlock the bolt/lock **24**. An arm can also be activated. It will be appreciated that the processor **36** can be anywhere as long as it is in communication with the temperature sensor **46**, and the motor **38**, which can be at the intelligent door lock system **10**, at the back-end **68**, anywhere in the building, and at any remote location. The processor **36** determines if there is an unsafe condition, e.g., based on a rise in temperature and this then results in an unlocking of the bolt/lock **24**.

In one embodiment, the intelligent door lock system back-end **68** can track performance of doors and friction levels across time and build a service to encourage users to better maintain their doors, as discussed above.

FIG. **17** is a diagram illustrating an implementation of an intelligent door lock system **100** that allows an intelligent lock on one or more buildings to be controlled, as described above, and also controlled remotely by a mobile device or computer, as well as remotely by an intelligent lock system back-end component **114**, a mobile device or a computing device **210** of a user who is a member of the intelligent door lock system **100**, as disclosed above. The intelligent door lock system back-end component **114** may be any of those listed above included in the intelligent lock system back-end **68**,

one or more computing resources, such as cloud computing resources or server computers with the typical components, that execute a plurality of lines of computer code to implement the intelligent door lock system **100** functions described above and below. Each computing device **210** of a user may be a processing unit based device with sufficient processing power, memory and connectivity to interact with the intelligent door lock system back-end component **114**. As a non-limiting example, the mobile device or computing device **210** may be as defined above, and include those disclosed below, that is capable of interacting with the intelligent door lock back-end component **114**. In one implementation, the mobile device or computing device **210** may execute an application stored in the memory of the mobile device computing device **210** using a processor from the mobile device or computing device **210** to interact with the intelligent door lock back-end component **114**. Examples of a user interface for that application is shown in FIGS. **21(a)**-**22(e)** discussed below in more detail.

In another embodiment, the mobile device or computing device **210** may execute a browser stored in the memory of the mobile or computing device **210** using a processor from the mobile device or computing device **210** to interact with the intelligent door lock system back-end component **114**. Each of the elements shown in FIG. **17** may be linked by System Networks, including but not limited to a cellular network, a Bluetooth system, the Internet (HTTPS), a WiFi network and the like.

As shown in FIG. **17**, each user's mobile device or computer **210** may interact with the intelligent door lock system back-end **68** over System Networks, including but not limited to a wired or wireless network, such as a cellular network, digital data network, computer network and may also interact with the intelligent door lock system **10** using System Networks. Each mobile device or computing device **210** may also communicate with a WiFi network **115** or Network Systems over, as a non-limiting example, a network and the WiFi network **115** may then communicate with the intelligent door lock system **10**.

FIGS. **18(a)** and **(b)** illustrate a front view and a back view, respectively, of a door **120** with intelligent door lock system **10**. The front portion of the door **120** (that is outside relative to a building or dwelling) shown in FIG. **17** looks like a typical door **120** with a bolt assembly **122** and a doorknob and lock assembly **124**. The back portion of the door **120**, that is inside of the dwelling when the door **120** is closed, illustrated in FIG. **18(b)** has the same doorknob and lock assembly **124**, but then has an intelligent door lock system **100** that is retrofitted onto the bolt assembly **124** as described below in more detail.

The intelligent door lock assembly **100** may have an extension gear which extends through the baseplate of the smart door lock. The baseplate may have one or more oval mounting holes to accommodate various rose screw distances from 18 mm to 32 mm to accommodate various different doors. In one implementation, the intelligent door lock system **100** may have a circular shape and also a rotating bezel. The rotating bezel allows a user to rotate the smart door lock and thus manually lock or unlock the bolt as before. The extension gear extends through the baseplate and then interacts with the existing bolt elements and allows the smart door lock to lock/unlocks the bolt. The extension gear may have a modular adapter slot at its end which interfaces with an extension rod of the bolt assembly **124**. These modular adapters, as shown in FIG. **23(b)**, may be used to match the existing extension rod of the bolt assembly **124**. The smart door lock housing may further include an energy source, such as a battery, a motor

assembly, such as a compact, high-torque, high-accuracy stepper motor, and a circuit board that has at least a processor, a first wireless connectivity circuit and a second wireless connectivity circuit, as described above. In one embodiment, the first wireless connectivity circuit may be a Bluetooth chip that allows the smart door lock to communicate using a Bluetooth protocol with a computing device of a user, such as a smartphone, tablet computer and the like. The second wireless connectivity circuit may be a WiFi chip that allows the smart door lock to communicate using a WiFi protocol with a back-end server system. The circuit board components may be intercoupled to each other and also coupled to the energy source and the motor for power and to control the motor, respectively. Each of the components described here may be coupled to the energy source and powered by the energy source.

FIG. 19 illustrates the smart door lock system 100 being retrofitted onto a bolt in a door 10. As shown in FIG. 19, when the intelligent door lock system 100 is installed on the door 120, the thumb turn 124 is removed (replaced by the bezel that allows the user to manually unlock or lock the bolt.) In addition, the extension gear 126 of the intelligent door lock system 100, and more specifically the slotted portion 126(a) at the end of the extension gear, is mechanically coupled to the extension rod 128 of the bolt assembly as shown in FIG. 19. When the intelligent door lock system 100 is installed, as shown in FIG. 19, the user can rotate the bezel 132 to manually lock or unlock the bolt assembly. In addition, when commanded to do so, the motor assembly in the intelligent door lock system 100 can also turn the extension gear 126 that in turn turns the extension rod and lock or unlock the bolt assembly. Thus, the extension gear 126 allows the smart door lock to act as a manual thumb turn (using the bezel) and rotate either clockwise or counterclockwise to engage or disengage the bolt of a bolt. The extension gear 126 is designed in a manner to control the physical rotation of extension rods/axial actuators/tail pieces/tongues 128 which are traditionally rotated by means of a thumb turn. This is achieved by designing the extension gear 126 with modular gear adapters as shown in FIG. 23(b) to fit over the extension rod 22 as shown. This allows the extension gear 126 to fit with a variety of existing extension rods.

FIG. 20 illustrates a set of interactions between the intelligent door lock system 100, mobile or computing device 210 and intelligent door lock system back-end 68, that may include a pairing process 138 and a lock operation process 140. During the pairing process 138, the intelligent door lock system 100 and mobile or computing device 210 can be paired to each other and also authenticated by the intelligent door lock system back-end 68. Thus, as shown in FIG. 20, during the pairing process, the intelligent door lock system 100 is powered on and becomes discoverable, while the mobile or computing device 210 communicates with the intelligent door lock system back-end 68, and has its credentials validated and authenticated. Once the mobile or computing device 210, and the app on the mobile or computing device 210, is authenticated, the mobile or computing device 210 discovers the lock, such as through a Bluetooth discovery process, since the intelligent door lock system 100 and the mobile or computing device 210 are within a predetermined proximity to each other. The mobile or computing device 210 may then send a pairing code to the intelligent door lock system 100, and in turn receive a pairing confirmation from the intelligent door lock system 100. The pairing process is then completed with the processes illustrated in FIG. 20. The lock operation may include the steps listed in FIG. 20 to

operate the intelligent door lock system 100 wirelessly using the mobile or computing device 210.

The intelligent door lock system 100 may be used for various functions. As a non-limiting example, the intelligent door lock system 100 may enable a method to exchange a security token between mobile or computing device 210 and the intelligent door lock system 100. All or all of the intelligent door lock systems 100 may be registered with the intelligent door lock back-end 68 with a unique registration ID. The unique ID of the an intelligent door lock system 100 may be associated with a unique security token that can only be used to command a specific intelligent door lock system 100 to lock or unlock. Through a virtual key provisioning interface of the intelligent door lock system back-end 68, a master user, who may be an administrator, can issue a new security token to a particular mobile or computing device 210. The intelligent door lock system 100 can periodically broadcast an advertisement of its available services over System Networks. When the mobile or computing device 210 is within a predetermined proximity of the intelligent door lock system 100, which varies depending on the protocol being used, the mobile or computing device 210 can detect the advertisement from the intelligent door lock assembly 100.

The application on the mobile or computing device 210 detects the intelligent door lock system 100 and a communications session can be initiated. The token, illustrated as a key 118 in FIG. 20, is exchanged and the lock is triggered to unlock automatically. Alternatively, if the intelligent door lock system 100 is equipped with a second wireless communications circuit, then the intelligent door lock system 100 can periodically query the intelligent door lock system back-end 68 for commands. A user can issue commands via a web interface to the intelligent door lock system back-end 68, and the intelligent door lock system 100 can lock or unlock the door 120. The intelligent door lock system 100 may also allow the user to disable auto-unlock, at which time the application on the user's mobile or computing device 210 can provide a notification which then allows the user to press a button on the mobile or computing device 210 to lock or unlock the lock.

The intelligent door lock system 100 may also allow for the triggering of multiple events upon connection to an intelligent door lock system 100 by a mobile or computing device 210. As a non-limiting example, the intelligent door lock system 100 can detect and authenticate the mobile or computing device 210, as described herein, and initiate a series of actions, including but not limiting to, unlocking doors 100, turning on lights, adjusting temperature, turning on stereo etc. The commands for these actions may be carried out by the mobile or computing device 210 or the intelligent door lock system back-end 68. In addition, through a web interface of the intelligent door lock system back-end 68, the user may define one or more events to be triggered upon proximity detection and authentication of the user's mobile or computing device 210 to the intelligent door lock system 100.

The intelligent door lock system 100 may also allow for the intelligent triggering of events associated with an individual. In particular, environmental settings may be defined per individual in the intelligent door lock system back-end 68 and then applied intelligently by successive ingress by that person into a building that has an intelligent door lock system 100. For example: person A arrives home and its mobile or computing device 210 is authenticated by the intelligent door lock system 100. His identity is shared with the intelligent door lock system back-end 68. The intelligent door lock system back-end 68 may send environmental changes to other home controllers, such as "adjust heat to 68 degrees". Person B

21

arrives at the same building an hour later and her mobile or computing device **210** is also authenticated and shared with the intelligent door lock system back-end **68**. The intelligent door lock system back-end **68** accesses her preferred environmental variables such as “adjust heat to 71 degrees”. The intelligent door lock system back-end understands that person B has asked for a temperature increase and issues the respective command to the dwelling thermostat. In one example, the intelligent door lock back-end system **68** has logic that defers to the higher temperature request or can deny it. Therefore if person A entered the home after person B, the temperature would not be decreased.

FIGS. **21(a)-(g)** are examples of a user interface for an owner of a building that has an intelligent door lock system **100**. These user interfaces may be seen by a user who is the owner of a building that has an intelligent door lock system **100** with the unique ID. FIG. **21(a)** is a basic home screen while FIG. **22(b)** shows the smart door locks (in a keychain) which the user of the mobile or computing device **210** has access rights to in intelligent door lock system **100**. FIG. **21(c)** illustrates an example of a user interface when a particular intelligent door lock system **100** is locked. FIG. **22(d)** illustrates an example of a user interface when a particular intelligent door lock system **100** is unlocked. FIGS. **21(e)** and **(f)** are user interface examples that allow the owner to add other users/people to be able to control the intelligent door lock system **100** of the building. FIG. **21(g)** is an example of a configuration interface that allows the owner of the building to customize a set of permissions assigned for each intelligent door lock system **100**.

FIGS. **22(a)-(e)** are examples of a user interface for a guest of an owner of a building that has an intelligent door lock system **100**.

FIGS. **23(a)** and **(b)** illustrate an intelligent door lock system **100** and extension gear adapters **142**. In particular, FIG. **23(a)** shows the bolt of a lock device with an empty extension gear receptacle that allows different extension gear adapters **150** (shown in FIG. **7B**) to be inserted into the receptacle so that the an intelligent door lock system **100** may be used with a number of different bolts of lock devices that each have a different shaped extension rod and/or extension rods that have different cross-sections.

Referring now to FIG. **24**, **1212** is a block diagram illustrating embodiments of a mobile or computing device **210** that can be used with intelligent door lock system **10**.

The mobile or computing device **210** can include a display **1214** that can be a touch sensitive display. The touch-sensitive display **1214** is sometimes called a “touch screen” for convenience, and may also be known as or called a touch-sensitive display system. The mobile or computing device **210** may include a memory **1216** (which may include one or more computer readable storage mediums), a memory controller **1218**, one or more processing units (CPU’s) **1220**, a peripherals interface **1222**, Network Systems circuitry **1224**, including but not limited to RF circuitry, audio circuitry **1226**, a speaker **1228**, a microphone **1230**, an input/output (I/O) subsystem **1232**, other input or control devices **1234**, and an external port **1236**. The mobile or computing device **210** may include one or more optical sensors **1238**. These components may communicate over one or more communication buses or signal lines **1240**.

It should be appreciated that the mobile or computing device **210** is only one example of a portable multifunction mobile or computing device **210**, and that the mobile or computing device **210** may have more or fewer components than shown, may combine two or more components, or a may have a different configuration or arrangement of the compo-

22

nents. The various components shown in FIG. **24** may be implemented in hardware, software or a combination of hardware and software, including one or more signal processing and/or application specific integrated circuits.

Memory **1216** may include high-speed random access memory and may also include non-volatile memory, such as one or more magnetic disk storage devices, flash memory devices, or other non-volatile solid-state memory devices. Access to memory **1216** by other components of the mobile or computing device **210**, such as the CPU **1220** and the peripherals interface **1222**, may be controlled by the memory controller **1218**.

The peripherals interface **1222** couples the input and output peripherals of the device to the CPU **1220** and memory **1216**. The one or more processors **1220** run or execute various software programs and/or sets of instructions stored in memory **1216** to perform various functions for the mobile or computing device **210** and to process data.

In some embodiments, the peripherals interface **1222**, the CPU **1220**, and the memory controller **1218** may be implemented on a single chip, such as a chip **1242**. In some other embodiments, they may be implemented on separate chips.

The Network System circuitry **1244** receives and sends signals, including but not limited to RF, also called electromagnetic signals. The Network System circuitry **1244** converts electrical signals to/from electromagnetic signals and communicates with communications networks and other communications devices via the electromagnetic signals. The Network Systems circuitry **1244** may include well-known circuitry for performing these functions, including but not limited to an antenna system, an RF transceiver, one or more amplifiers, a tuner, one or more oscillators, a digital signal processor, a CODEC chipset, a subscriber identity module (SIM) card, memory, and so forth. The Network Systems circuitry **1244** may communicate with networks, such as the Internet, also referred to as the World Wide Web (WWW), an intranet and/or a wireless network, such as a cellular telephone network, a wireless local area network (LAN) and/or a metropolitan area network (MAN), and other devices by wireless communication.

The wireless communication may use any of a plurality of communications standards, protocols and technologies, including but not limited to Global System for Mobile Communications (GSM), Enhanced Data GSM Environment (EDGE), high-speed downlink packet access (HSDPA), wideband code division multiple access (W-CDMA), code division multiple access (CDMA), time division multiple access (TDMA), BLUETOOTH®, Wireless Fidelity (Wi-Fi) (e.g., IEEE 802.11a, IEEE 802.11b, IEEE 802.11g and/or IEEE 802.11n), voice over Internet Protocol (VoIP), Wi-MAX, a protocol for email (e.g., Internet message access protocol (IMAP) and/or post office protocol (POP)), instant messaging (e.g., extensible messaging and presence protocol (XMPP), Session Initiation Protocol for Instant Messaging and Presence Leveraging Extensions (SIMPLE), and/or Instant Messaging and Presence Service (IMPS)), and/or Short Message Service (SMS)), or any other suitable communication protocol, including communication protocols not yet developed as of the filing date of this document.

The audio circuitry **1226**, the speaker **1228**, and the microphone **1230** provide an audio interface between a user and the mobile or computing device **210**. The audio circuitry **1226** receives audio data from the peripherals interface **1222**, converts the audio data to an electrical signal, and transmits the electrical signal to the speaker **1228**. The speaker **1228** converts the electrical signal to human-audible sound waves. The audio circuitry **1226** also receives electrical signals converted

by the microphone **1230** from sound waves. The audio circuitry **1226** converts the electrical signal to audio data and transmits the audio data to the peripherals interface **1222** for processing. Audio data may be retrieved from and/or transmitted to memory **1216** and/or the Network Systems circuitry **1244** by the peripherals interface **1222**. In some embodiments, the audio circuitry **1226** also includes a headset jack. The headset jack provides an interface between the audio circuitry **1226** and removable audio input/output peripherals, such as output-only headphones or a headset with both output (e.g., a headphone for one or both ears) and input (e.g., a microphone).

The I/O subsystem **1232** couples input/output peripherals on the mobile or computing device **210**, such as the touch screen **1214** and other input/control devices **1234**, to the peripherals interface **1222**. The I/O subsystem **1232** may include a display controller **1246** and one or more input controllers **210** for other input or control devices. The one or more input controllers **1** receive/send electrical signals from/to other input or control devices **1234**. The other input/control devices **1234** may include physical buttons (e.g., push buttons, rocker buttons, etc.), dials, slider switches, and joysticks, click wheels, and so forth. In some alternate embodiments, input controller(s) **1252** may be coupled to any (or none) of the following: a keyboard, infrared port, USB port, and a pointer device such as a mouse. The one or more buttons may include an up/down button for volume control of the speaker **1228** and/or the microphone **1230**. The one or more buttons may include a push button. A quick press of the push button may disengage a lock of the touch screen **1214** or begin a process that uses gestures on the touch screen to unlock the device, as described in U.S. patent application Ser. No. 11/322,549, "Unlocking a Device by Performing Gestures on an Unlock Image," filed Dec. 23, 2005, which is hereby incorporated by reference in its entirety. A longer press of the push button may turn power to the mobile or computing device **210** on or off. The user may be able to customize a functionality of one or more of the buttons. The touch screen **1214** is used to implement virtual or soft buttons and one or more soft keyboards.

The touch-sensitive touch screen **1214** provides an input interface and an output interface between the device and a user. The display controller **1246** receives and/or sends electrical signals from/to the touch screen **1214**. The touch screen **1214** displays visual output to the user. The visual output may include graphics, text, icons, video, and any combination thereof (collectively termed "graphics"). In some embodiments, some or all of the visual output may correspond to user-interface objects, further details of which are described below.

A touch screen **1214** has a touch-sensitive surface, sensor or set of sensors that accepts input from the user based on haptic and/or tactile contact. The touch screen **1214** and the display controller **1246** (along with any associated modules and/or sets of instructions in memory **1216**) detect contact (and any movement or breaking of the contact) on the touch screen **1214** and converts the detected contact into interaction with user-interface objects (e.g., one or more soft keys, icons, web pages or images) that are displayed on the touch screen. In an exemplary embodiment, a point of contact between a touch screen **1214** and the user corresponds to a finger of the user.

The touch screen **1214** may use LCD (liquid crystal display) technology, or LPD (light emitting polymer display) technology, although other display technologies may be used in other embodiments. The touch screen **1214** and the display controller **1246** may detect contact and any movement or

breaking thereof using any of a plurality of touch sensing technologies now known or later developed, including but not limited to capacitive, resistive, infrared, and surface acoustic wave technologies, as well as other proximity sensor arrays or other elements for determining one or more points of contact with a touch screen **1214**.

A touch-sensitive display in some embodiments of the touch screen **1214** may be analogous to the multi-touch sensitive tablets described in the following U.S. Pat. No. 6,323,846 (Westerman et al.), U.S. Pat. No. 6,570,557 (Westerman et al.), and/or U.S. Pat. No. 6,677,932 (Westerman), and/or U.S. Patent Publication 2002/0015024A1, each of which is hereby incorporated by reference in their entirety. However, a touch screen **1214** displays visual output from the portable mobile or computing device **210**, whereas touch sensitive tablets do not provide visual output.

A touch-sensitive display in some embodiments of the touch screen **1214** may be as described in the following applications: (1) U.S. patent application Ser. No. 11/381,313, "Multipoint Touch Surface Controller," filed May 12, 2006; (2) U.S. patent application Ser. No. 10/840,862, "Multipoint Touchscreen," filed May 6, 2004; (3) U.S. patent application Ser. No. 10/903,964, "Gestures For Touch Sensitive Input Devices," filed Jul. 30, 2004; (4) U.S. patent application Ser. No. 11/048,264, "Gestures For Touch Sensitive Input Devices," filed Jan. 31, 2005; (5) U.S. patent application Ser. No. 11/038,590, "Mode-Based Graphical User Interfaces For Touch Sensitive Input Devices," filed Jan. 18, 2005; (6) U.S. patent application Ser. No. 11/228,758, "Virtual Input Device Placement On A Touch Screen User Interface," filed Sep. 16, 2005; (7) U.S. patent application Ser. No. 11/228,700, "Operation Of A Computer With A Touch Screen Interface," filed Sep. 16, 2005; (8) U.S. patent application Ser. No. 11/228,737, "Activating Virtual Keys Of A Touch-Screen Virtual Keyboard," filed Sep. 16, 2005; and (9) U.S. patent application Ser. No. 11/367,749, "Multi-Functional Hand-Held Device," filed Mar. 3, 2006. All of these applications are incorporated by reference herein in their entirety.

The touch screen **1214** may have a resolution in excess of 1000 dpi. In an exemplary embodiment, the touch screen has a resolution of approximately 1060 dpi. The user may make contact with the touch screen **1214** using any suitable object or appendage, such as a stylus, a finger, and so forth. In some embodiments, the user interface is designed to work primarily with finger-based contacts and gestures, which are much less precise than stylus-based input due to the larger area of contact of a finger on the touch screen. In some embodiments, the device translates the rough finger-based input into a precise pointer/cursor position or command for performing the actions desired by the user.

In some embodiments, in addition to the touch screen, the mobile or computing device **210** may include a touchpad (not shown) for activating or deactivating particular functions. In some embodiments, the touchpad is a touch-sensitive area of the device that, unlike the touch screen, does not display visual output. The touchpad may be a touch-sensitive surface that is separate from the touch screen **1214** or an extension of the touch-sensitive surface formed by the touch screen.

In some embodiments, the mobile or computing device **210** may include a physical or virtual click wheel as an input control device **1234**. A user may navigate among and interact with one or more graphical objects (henceforth referred to as icons) displayed in the touch screen **1214** by rotating the click wheel or by moving a point of contact with the click wheel (e.g., where the amount of movement of the point of contact is measured by its angular displacement with respect to a center point of the click wheel). The click wheel may also be

used to select one or more of the displayed icons. For example, the user may press down on at least a portion of the click wheel or an associated button. User commands and navigation commands provided by the user via the click wheel may be processed by an input controller **1252** as well as one or more of the modules and/or sets of instructions in memory **1216**. For a virtual click wheel, the click wheel and click wheel controller may be part of the touch screen **1214** and the display controller **1246**, respectively. For a virtual click wheel, the click wheel may be either an opaque or semitransparent object that appears and disappears on the touch screen display in response to user interaction with the device. In some embodiments, a virtual click wheel is displayed on the touch screen of a portable multifunction device and operated by user contact with the touch screen.

The mobile or computing device **210** also includes a power system **1214** for powering the various components. The power system **1214** may include a power management system, one or more power sources (e.g., battery **1254**, alternating current (AC)), a recharging system, a power failure detection circuit, a power converter or inverter, a power status indicator (e.g., a light-emitting diode (LED)) and any other components associated with the generation, management and distribution of power in portable devices.

The mobile or computing device **210** may also include one or more sensors **1238**, including not limited to optical sensors **1238**. An optical sensor can be coupled to an optical sensor controller **1248** in I/O subsystem **1232**. The optical sensor **1238** may include charge-coupled device (CCD) or complementary metal-oxide semiconductor (CMOS) phototransistors. The optical sensor **1238** receives light from the environment, projected through one or more lens, and converts the light to data representing an image. In conjunction with an imaging module **1258** (also called a camera module); the optical sensor **1238** may capture still images or video. In some embodiments, an optical sensor is located on the back of the mobile or computing device **210**, opposite the touch screen display **1214** on the front of the device, so that the touch screen display may be used as a viewfinder for either still and/or video image acquisition. In some embodiments, an optical sensor is located on the front of the device so that the user's image may be obtained for videoconferencing while the user views the other video conference participants on the touch screen display. In some embodiments, the position of the optical sensor **1238** can be changed by the user (e.g., by rotating the lens and the sensor in the device housing) so that a single optical sensor **1238** may be used along with the touch screen display for both video conferencing and still and/or video image acquisition.

The mobile or computing device **210** may also include one or more proximity sensors **1250**. In one embodiment, the proximity sensor **1250** is coupled to the peripherals interface **1222**. Alternately, the proximity sensor **1250** may be coupled to an input controller in the I/O subsystem **1232**. The proximity sensor **1250** may perform as described in U.S. patent application Ser. No. 11/241,839, "Proximity Detector In Handheld Device," filed Sep. 30, 2005; Ser. No. 11/240,788, "Proximity Detector In Handheld Device," filed Sep. 30, 2005; Ser. No. 13/096,386, "Using Ambient Light Sensor To Augment Proximity Sensor Output"; Ser. No. 11/586,862, "Automated Response To And Sensing Of User Activity In Portable Devices," filed Oct. 24, 2006; and Ser. No. 11/638,251, "Methods And Systems For Automatic Configuration Of Peripherals," which are hereby incorporated by reference in their entirety. In some embodiments, the proximity sensor turns off and disables the touch screen **1214** when the multifunction device is placed near the user's ear (e.g., when the

user is making a phone call). In some embodiments, the proximity sensor keeps the screen off when the device is in the user's pocket, purse, or other dark area to prevent unnecessary battery drainage when the device is a locked state.

In some embodiments, the software components stored in memory **1216** may include an operating system **1260**, a communication module (or set of instructions) **1262**, a contact/motion module (or set of instructions) **1264**, a graphics module (or set of instructions) **1268**, a text input module (or set of instructions) **1270**, a Global Positioning System (GPS) module (or set of instructions) **1272**, and applications (or set of instructions) **1272**.

The operating system **1260** (e.g., Darwin, RTXC, LINUX, UNIX, OS X, WINDOWS, or an embedded operating system such as VxWorks) includes various software components and/or drivers for controlling and managing general system tasks (e.g., memory management, storage device control, power management, etc.) and facilitates communication between various hardware and software components.

The communication module **1262** facilitates communication with other devices over one or more external ports **1274** and also includes various software components for handling data received by the Network Systems circuitry **1244** and/or the external port **1274**. The external port **1274** (e.g., Universal Serial Bus (USB), FIREWIRE, etc.) is adapted for coupling directly to other devices or indirectly over a network (e.g., the Internet, wireless LAN, etc.). In some embodiments, the external port is a multi-pin (e.g., 30-pin) connector that is the same as, or similar to and/or compatible with the 30-pin connector used on iPod (trademark of Apple Computer, Inc.) devices.

The contact/motion module **106** may detect contact with the touch screen **1214** (in conjunction with the display controller **1246**) and other touch sensitive devices (e.g., a touchpad or physical click wheel). The contact/motion module **106** includes various software components for performing various operations related to detection of contact, such as determining if contact has occurred, determining if there is movement of the contact and tracking the movement across the touch screen **1214**, and determining if the contact has been broken (i.e., if the contact has ceased). Determining movement of the point of contact may include determining speed (magnitude), velocity (magnitude and direction), and/or an acceleration (a change in magnitude and/or direction) of the point of contact. These operations may be applied to single contacts (e.g., one finger contacts) or to multiple simultaneous contacts (e.g., "multitouch"/multiple finger contacts). In some embodiments, the contact/motion module **106** and the display controller **1246** also detects contact on a touchpad. In some embodiments, the contact/motion module **1284** and the controller **1286** detects contact on a click wheel.

Examples of other applications that may be stored in memory **1216** include other word processing applications, JAVA-enabled applications, encryption, digital rights management, voice recognition, and voice replication.

In conjunction with touch screen **1214**, display controller **1246**, contact module **1276**, graphics module **1278**, and text input module **1280**, a contacts module **1282** may be used to manage an address book or contact list, including: adding name(s) to the address book; deleting name(s) from the address book; associating telephone number(s), e-mail address(es), physical address(es) or other information with a name; associating an image with a name; categorizing and sorting names; providing telephone numbers or e-mail addresses to initiate and/or facilitate communications by telephone, video conference, e-mail, or IM; and so forth.

The foregoing description of various embodiments of the claimed subject matter has been provided for the purposes of illustration and description. It is not intended to be exhaustive or to limit the claimed subject matter to the precise forms disclosed. Many modifications and variations will be apparent to the practitioner skilled in the art. Particularly, while the concept "component" is used in the embodiments of the systems and methods described above, it will be evident that such concept can be interchangeably used with equivalent concepts such as, class, method, type, interface, module, object model, and other suitable concepts. Embodiments were chosen and described in order to best describe the principles of the invention and its practical application, thereby enabling others skilled in the relevant art to understand the claimed subject matter, the various embodiments and with various modifications that are suited to the particular use contemplated.

What is claimed is:

1. A method of determining right or hand side door installation, comprising:

rotating a drive shaft of a door lock mechanism with a bolt in a clock wise direction or a counter-clock wise direction until there is sufficient extension of the bolt to determine a status of a lock position of an associated door at a dwelling, the door lock mechanism including a position sensing device, the position sensing device sensing a position of the drive shaft and assists in locking and unlocking the bolt;

querying a user of the door lock when the drive shaft is at an end point, wherein the associated door is right hand in-swing, or left hand outswing, installed when the door locks with clock wise rotation and is left hand in-swing, or right hand outswing installed when the door locks with counter clock wise rotation; and

wherein a mobile device of a user occupant of the dwelling is in communication with the door lock mechanism to provide locking or unlocking of the door, and a non-user occupant third party is allowed controlled access to the dwelling with the non-user occupant third party mobile device when the user occupant grants access rights to the non-user occupant third party, the user being the user occupant of the dwelling or the non-user occupant third party.

2. The method of claim 1, wherein the sufficient extension is not a full extension of the bolt.

3. The method of claim 1, wherein the drive shaft is rotated to the end point where there is no further rotational movement of the drive shaft to determine an operating rotational range of the drive shaft.

4. The method of claim 3, further comprising: recording the end point.

5. The method of claim 1, wherein the door locks mechanism is battery powered.

6. The method of claim 1, wherein a rotation of the door lock mechanism is directly coupled to dead bolt extension.

7. The method of claim 1, wherein a maximum rotation limit is limited by the position sensing device.

8. The method of claim 7, wherein the position sensing device is selected from at least one of, an accelerometer, optical encoders, magnetic encoders, mechanical encoders, Hall Effect sensors, potentiometers, contacts with ticks and optical camera encoders.

9. The method of claim 1, wherein the user occupant's mobile device communicates a status of bolt extension.

10. The method of claim 1, wherein the door lock mechanism includes:

an engine with a memory, the engine being coupled to the positioning sensing device;

a circuit coupled to the engine;

an energy source coupled to the circuit; and

a device that converts energy into mechanical energy coupled to the circuit, positioning sensing device and the drive shaft, the device that converts energy being coupled to the energy source to receive energy from the energy source.

11. The method of claim 10, wherein the device that converts energy into mechanical energy is used to rotate the drive shaft.

12. The method of claim 1, wherein the drive shaft is manually rotated.

13. The method of claim 1, further comprising: recording the sufficient extension of the bolt to provide for a lock position of the associated door.

14. The method of claim 1, further comprising:

asking the user if the bolt is extended.

15. The method of claim 1, wherein the sufficient extension of the bolt to provide for a lock position of the associated door is determined when the user sets up the lock system.

16. The method of claim 1, wherein the sufficient extension of the bolt to provide for a lock position of the associated door by the drive shaft calibrates a door's range of motion.

17. The method of claim 1, wherein the position sensor determines position and not just relative movement.

18. The method of claim 1, further comprising:

guessing if the door is right or left side hung and asking the user if the guess is wrong.

19. The method of claim 1, further comprising: having a door user confirm which side the door is hung.

* * * * *