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**Twomey**

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(54) **LATCH MECHANISM FOR SURGICAL INSTRUMENTS**

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30/183-185; 87/407-412;  
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See application file for complete search history.

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(73) Assignee: **Covidien LP**, Mansfield, MA (US)

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(\* ) Notice: Subject to any disclaimer, the term of this patent is extended or adjusted under 35 U.S.C. 154(b) by 7 days.

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This patent is subject to a terminal disclaimer.

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(57) **ABSTRACT**

A latch mechanism for a surgical instrument includes a lever moveable from an initial position to an actuated position for moving an end effector assembly from a first to a second state. A pin extends from the lever. A cantilever spring is operably engaged to the housing of the instrument. A pin track member is operably engaged to the cantilever spring at a free end thereof. The pin track member is configured to permit translation of the pin therealong between a first position corresponding to the initial position of the lever and a second position corresponding to the actuated position of the lever. The pin is configured to translate from the first to the second position along a first path and from the second position back to the first position along a second path and is configured to be releasably retained in the second position.

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**2018/0091**; **A61B 2017/2946**; **A61B**

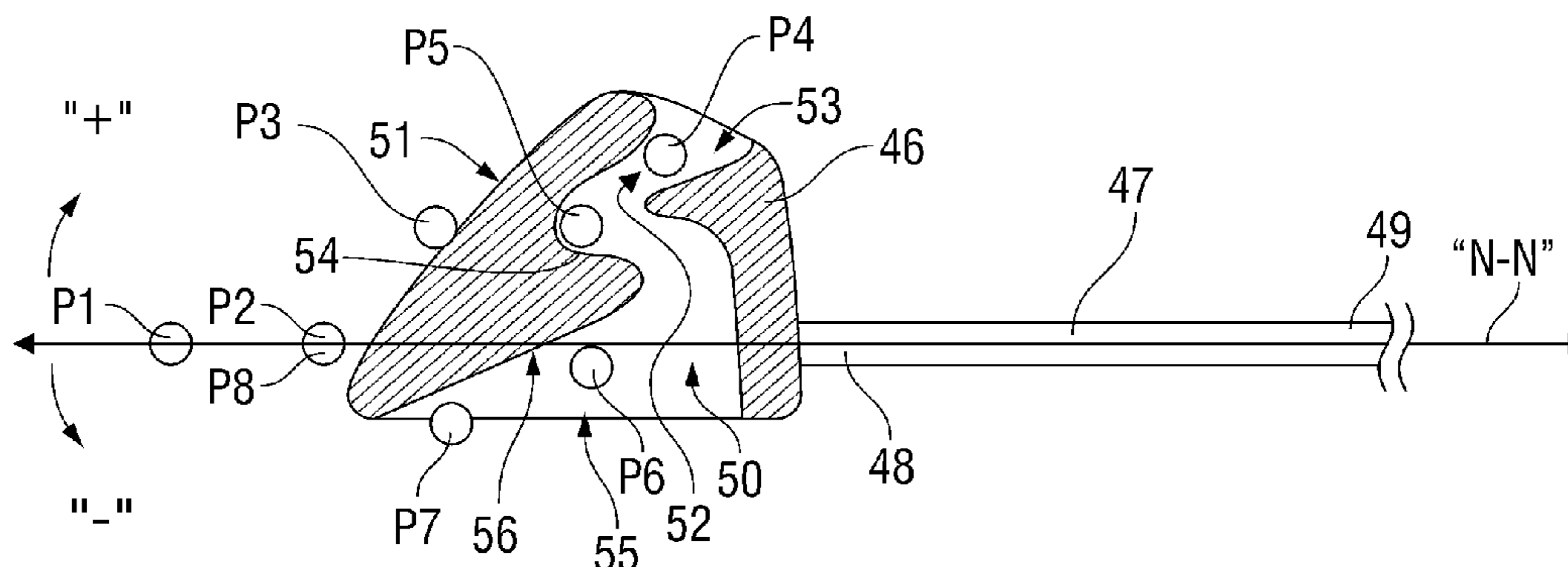
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**13 Claims, 6 Drawing Sheets**



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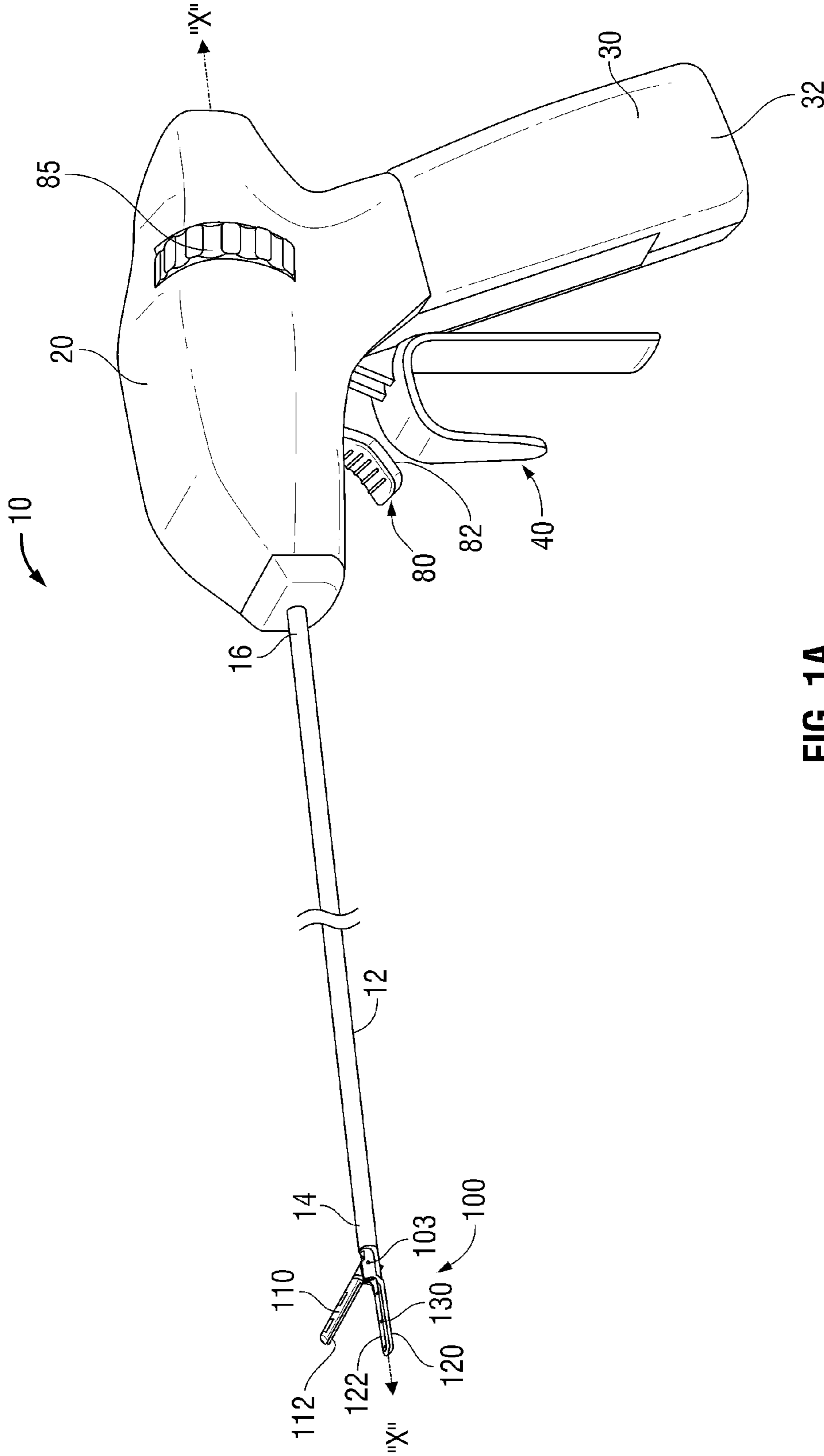


FIG. 1A

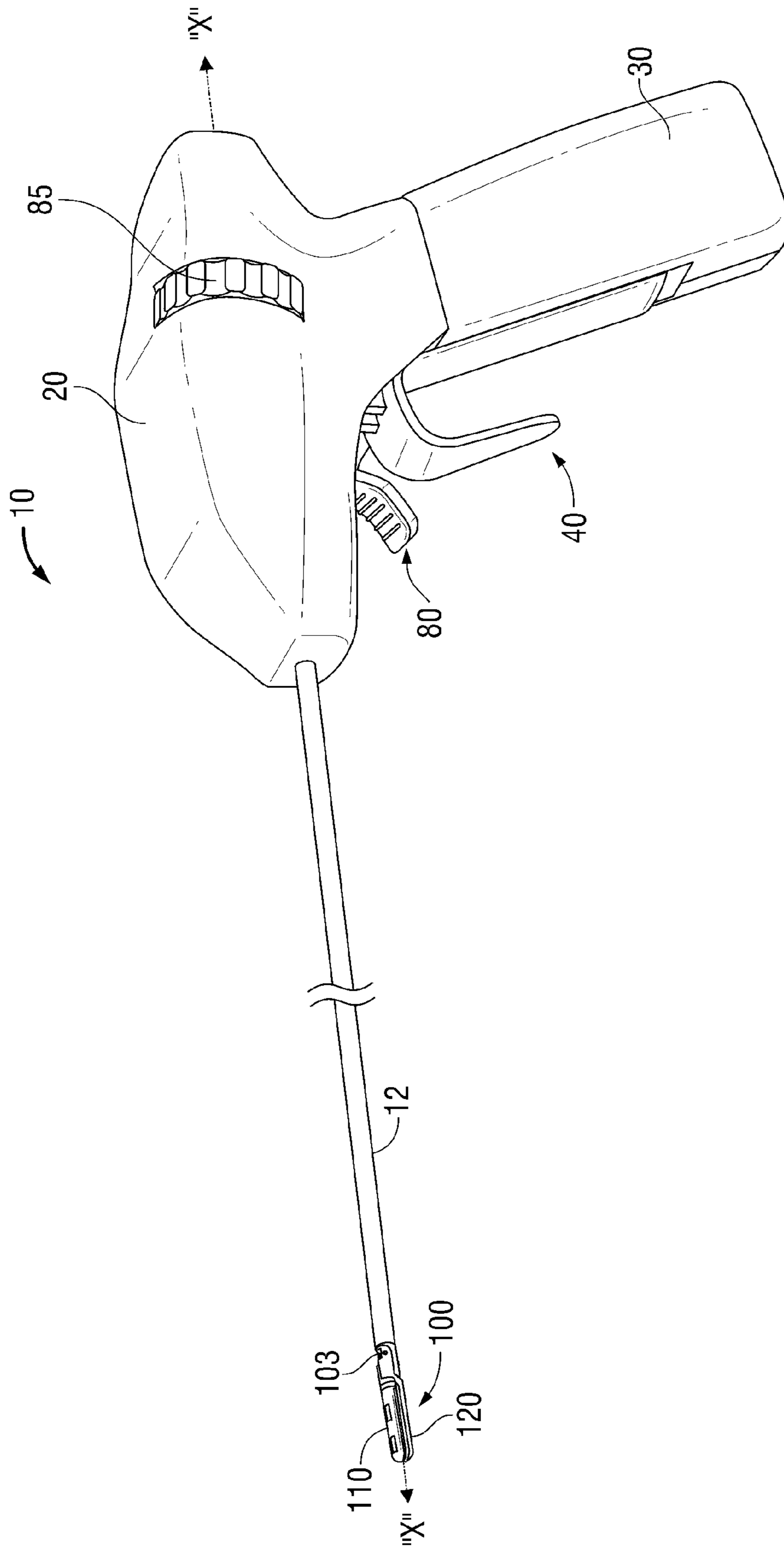


FIG. 1B

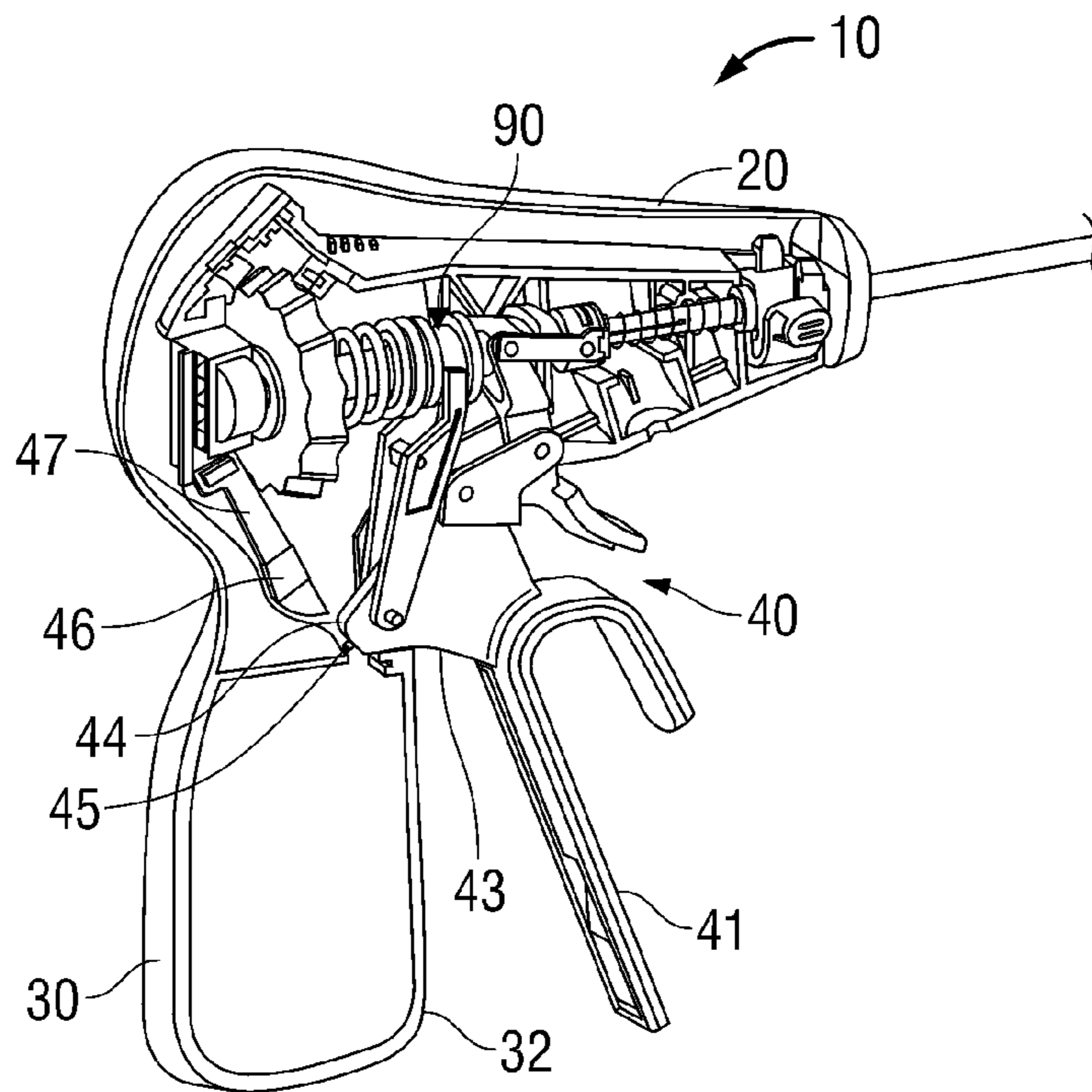


FIG. 2

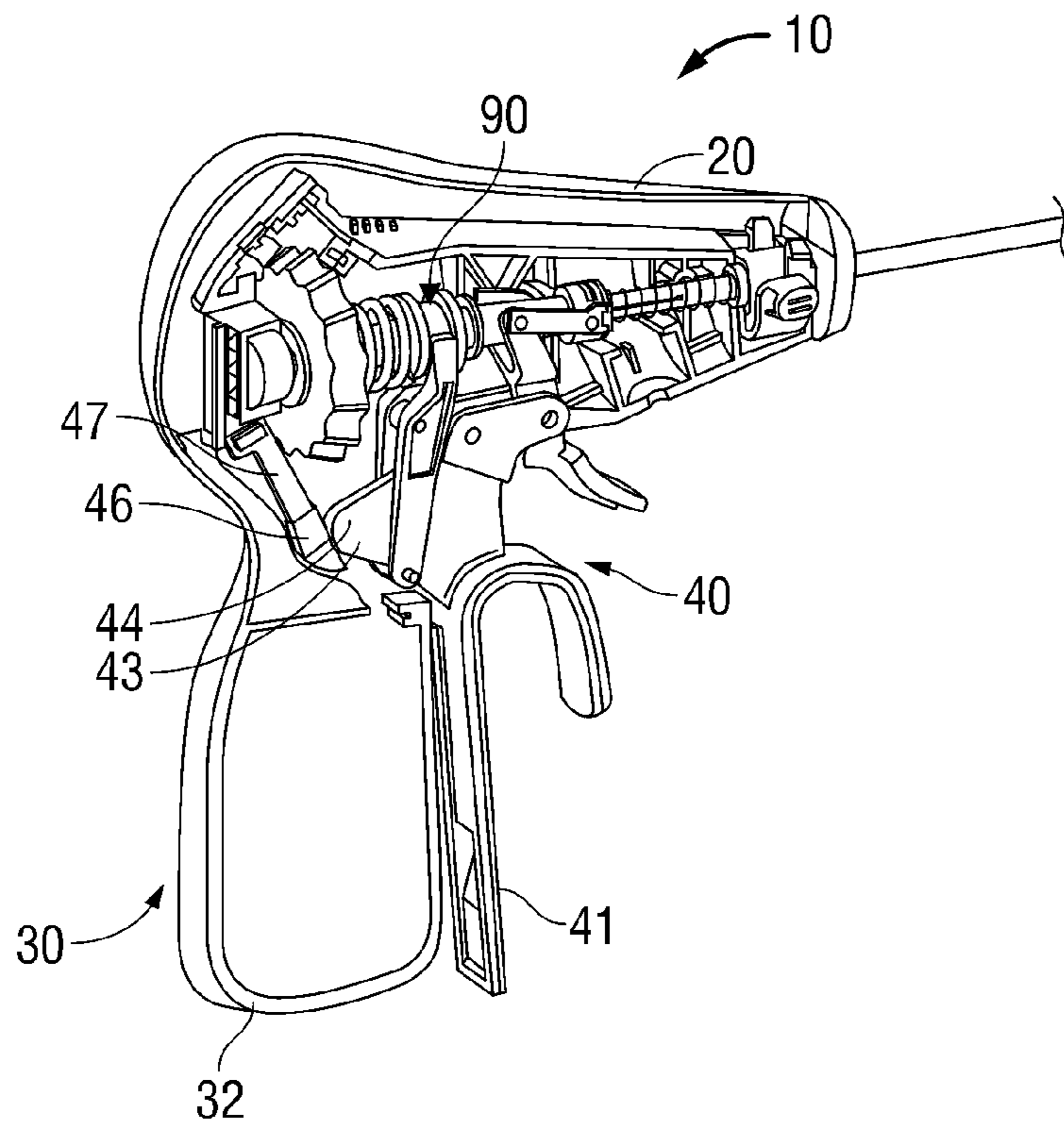


FIG. 3



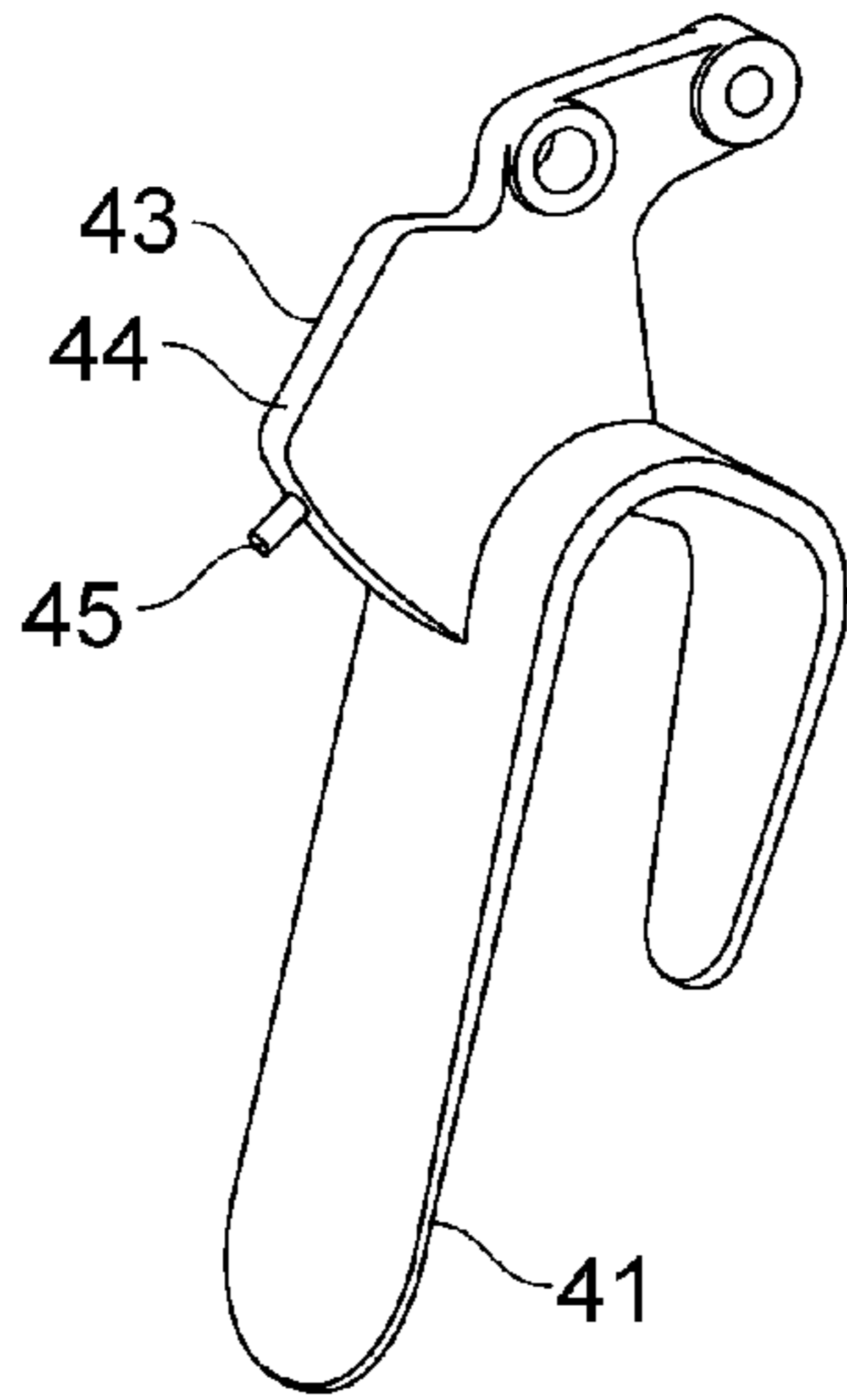


FIG. 4

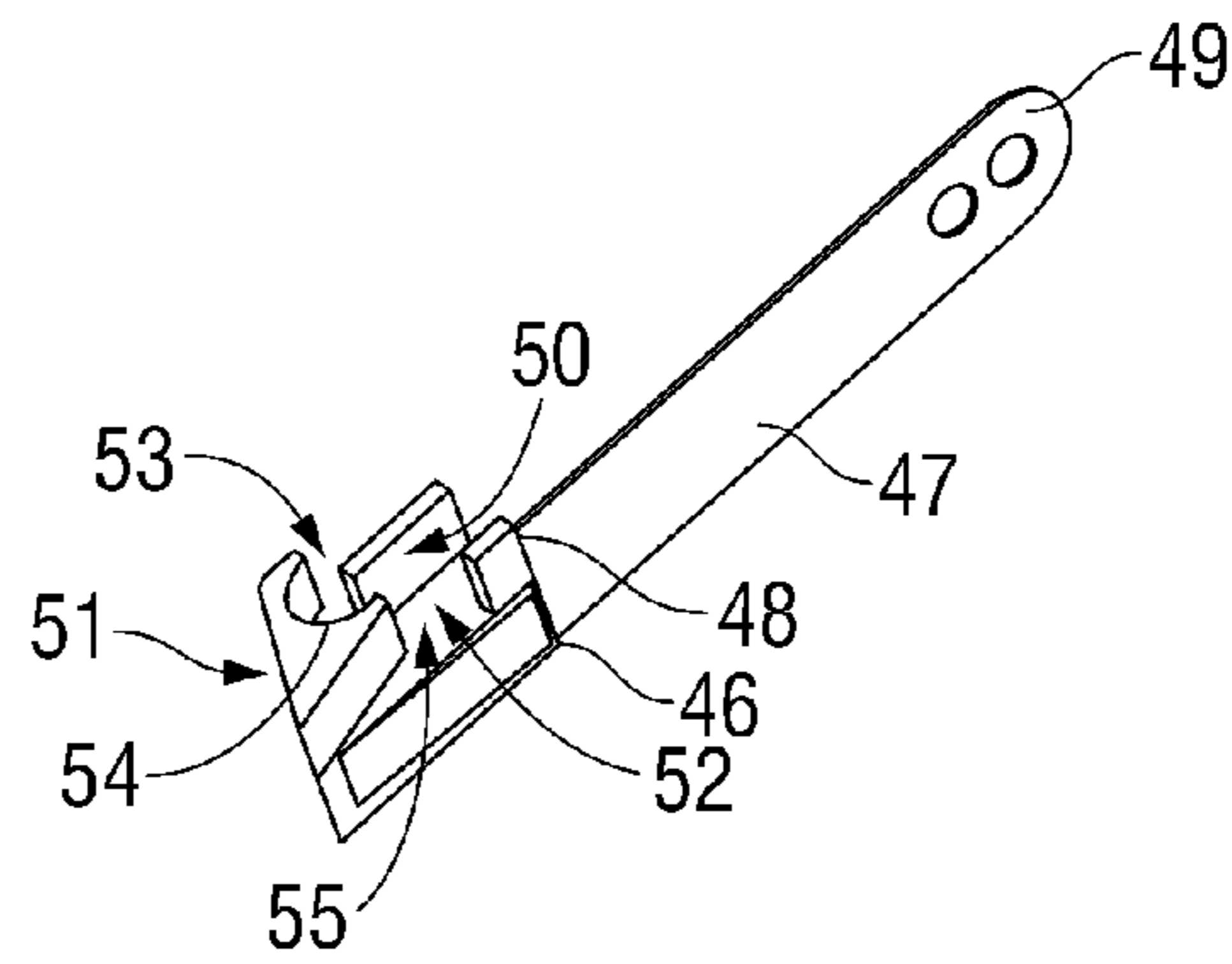


FIG. 5

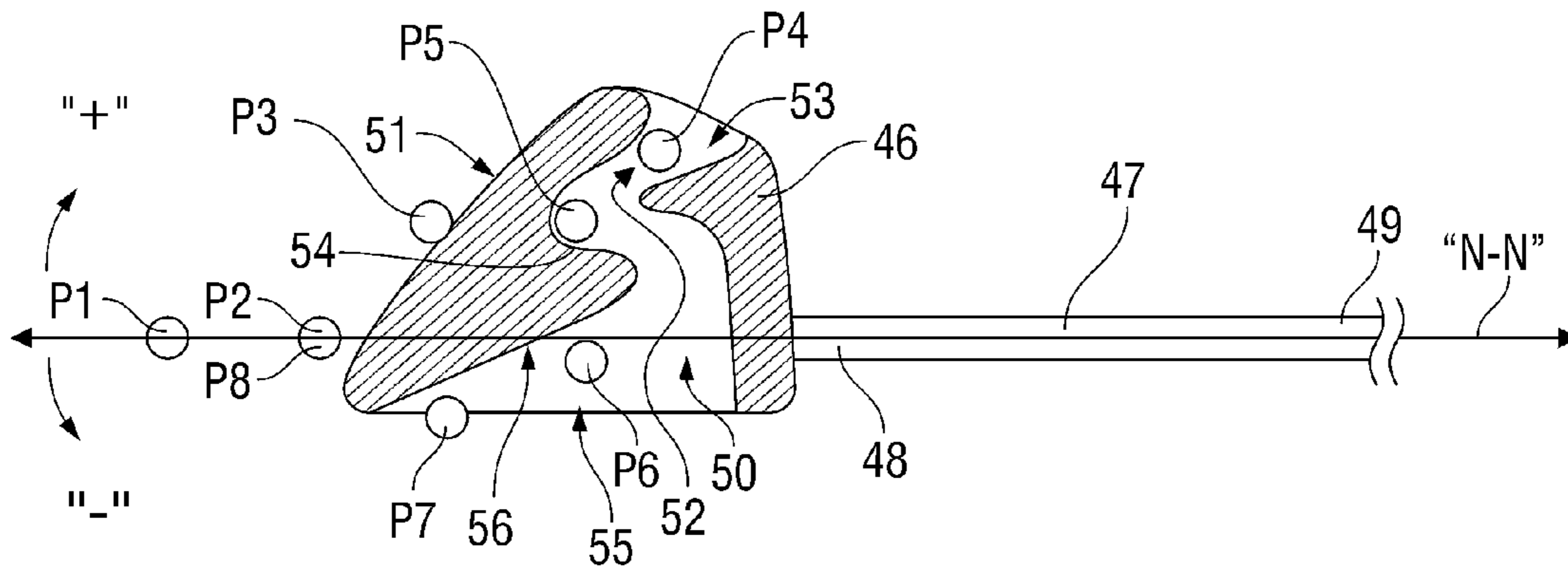


FIG. 6

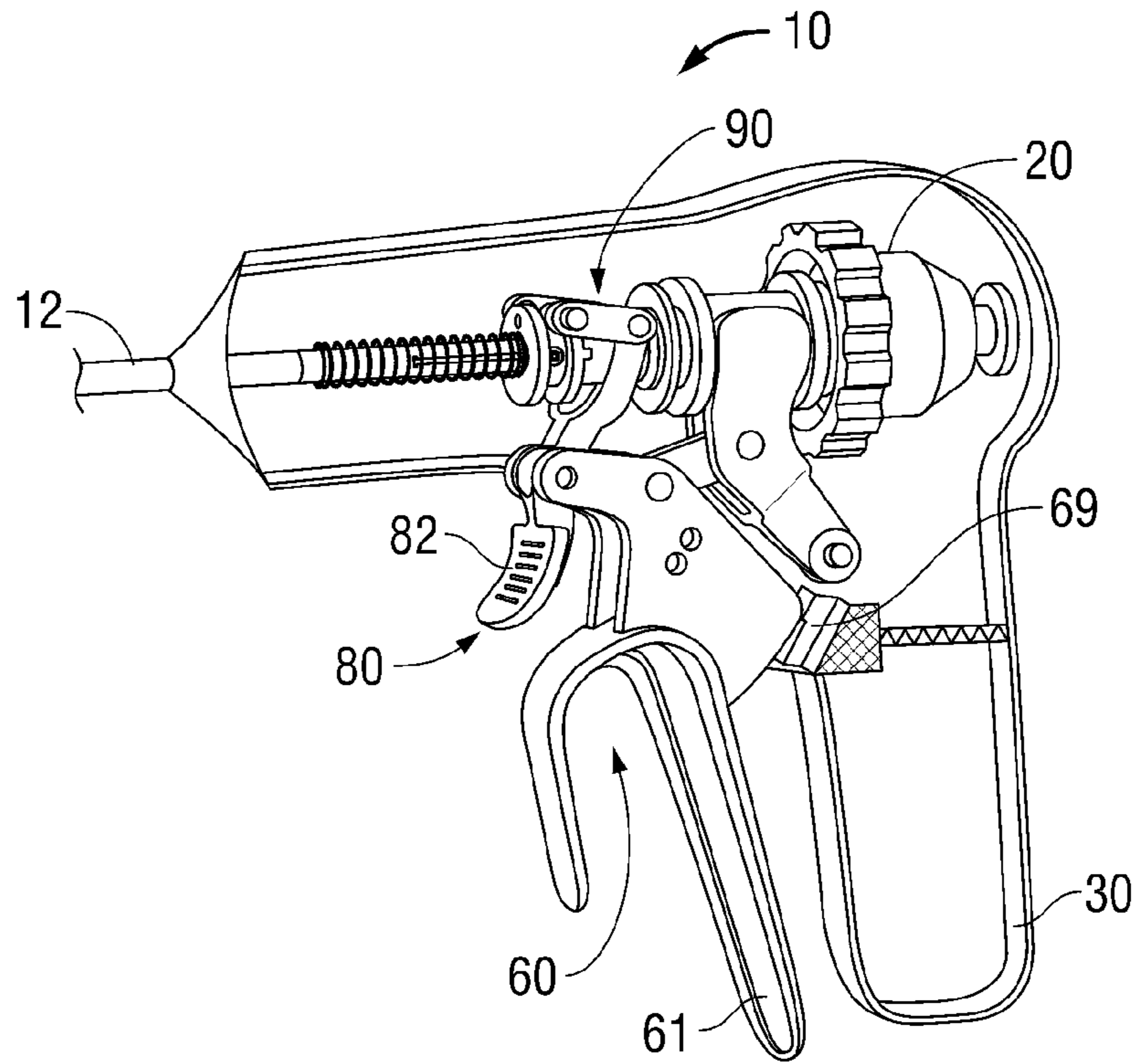


FIG. 7

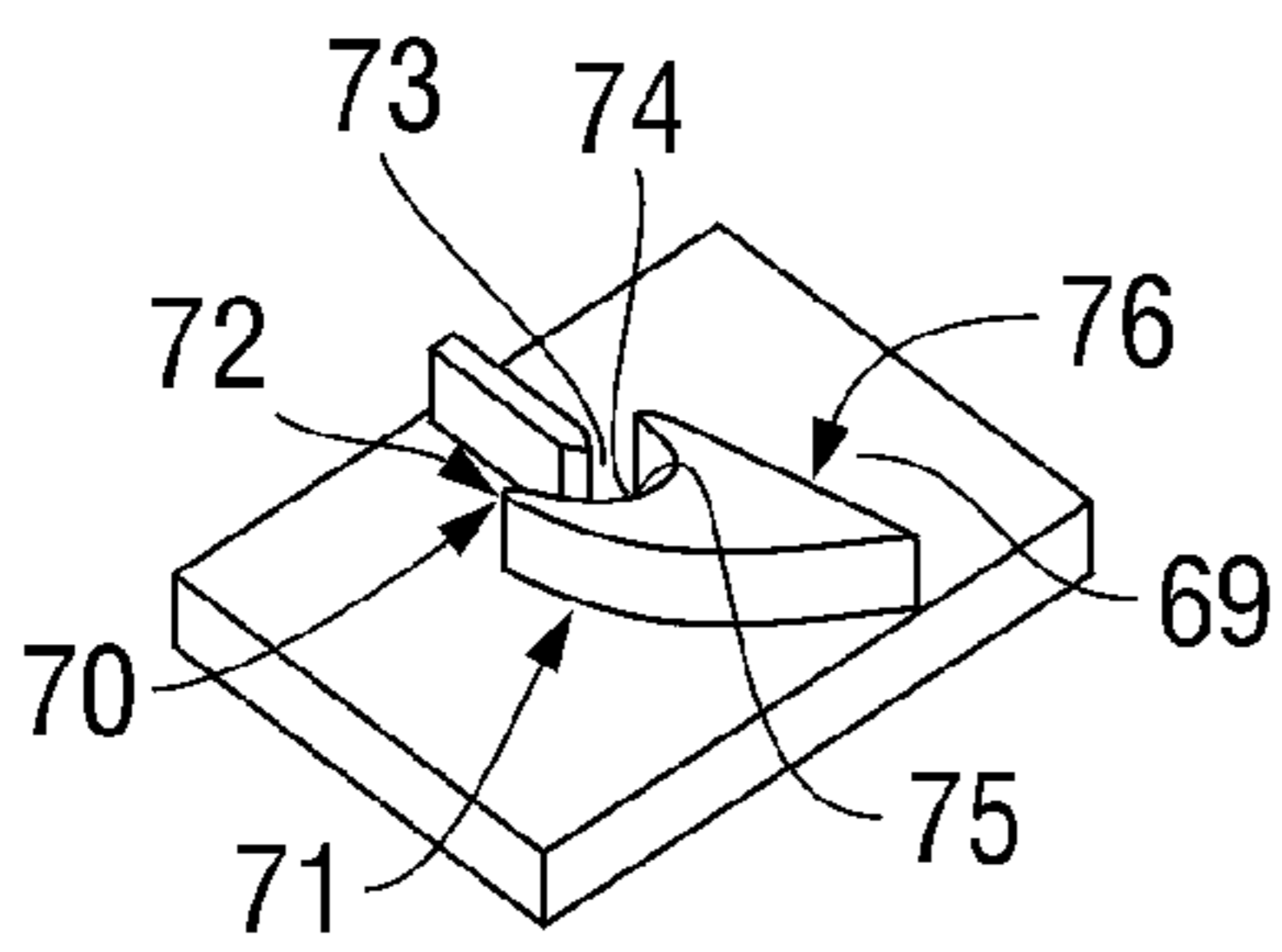


FIG. 8

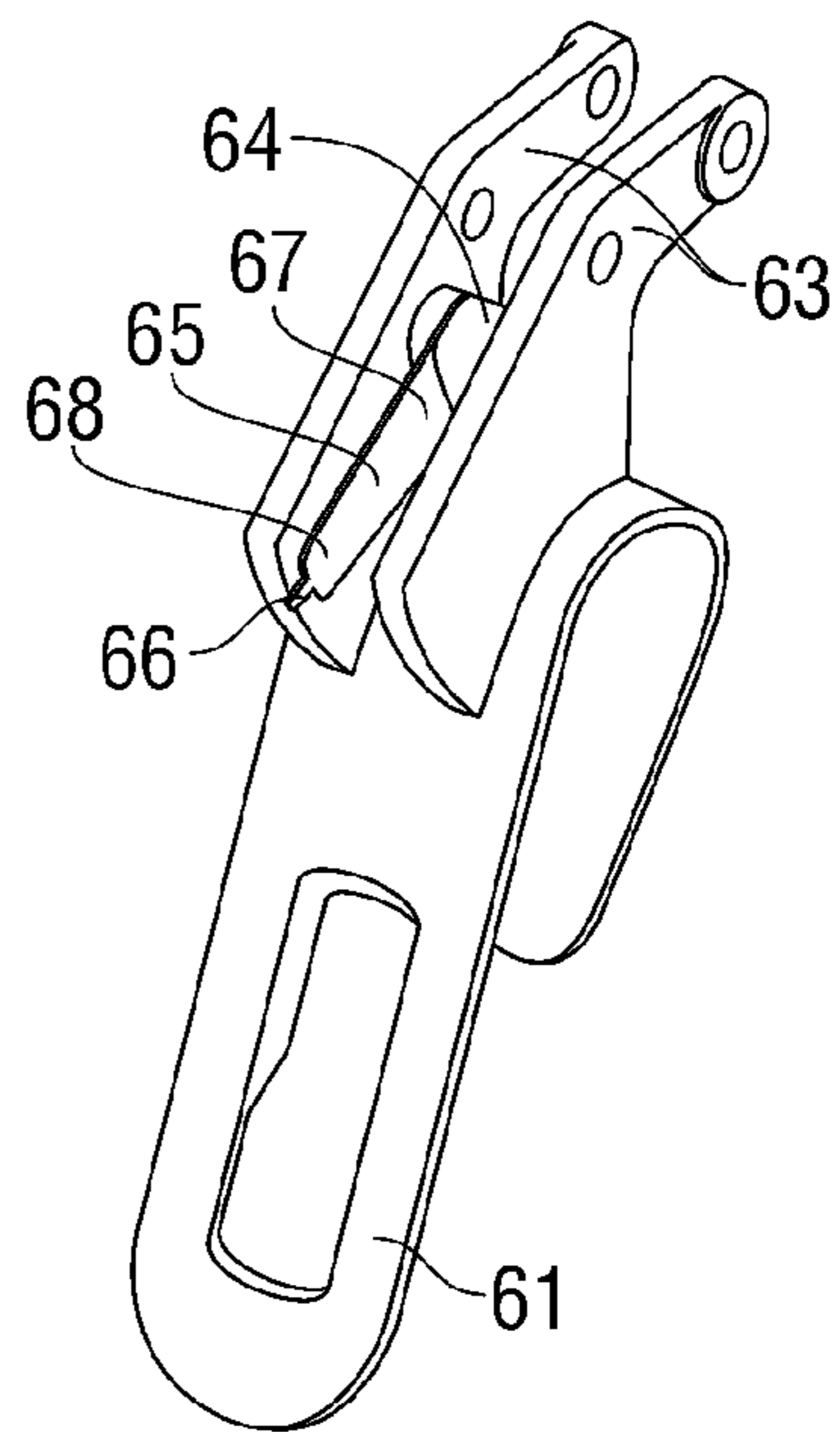


FIG. 9

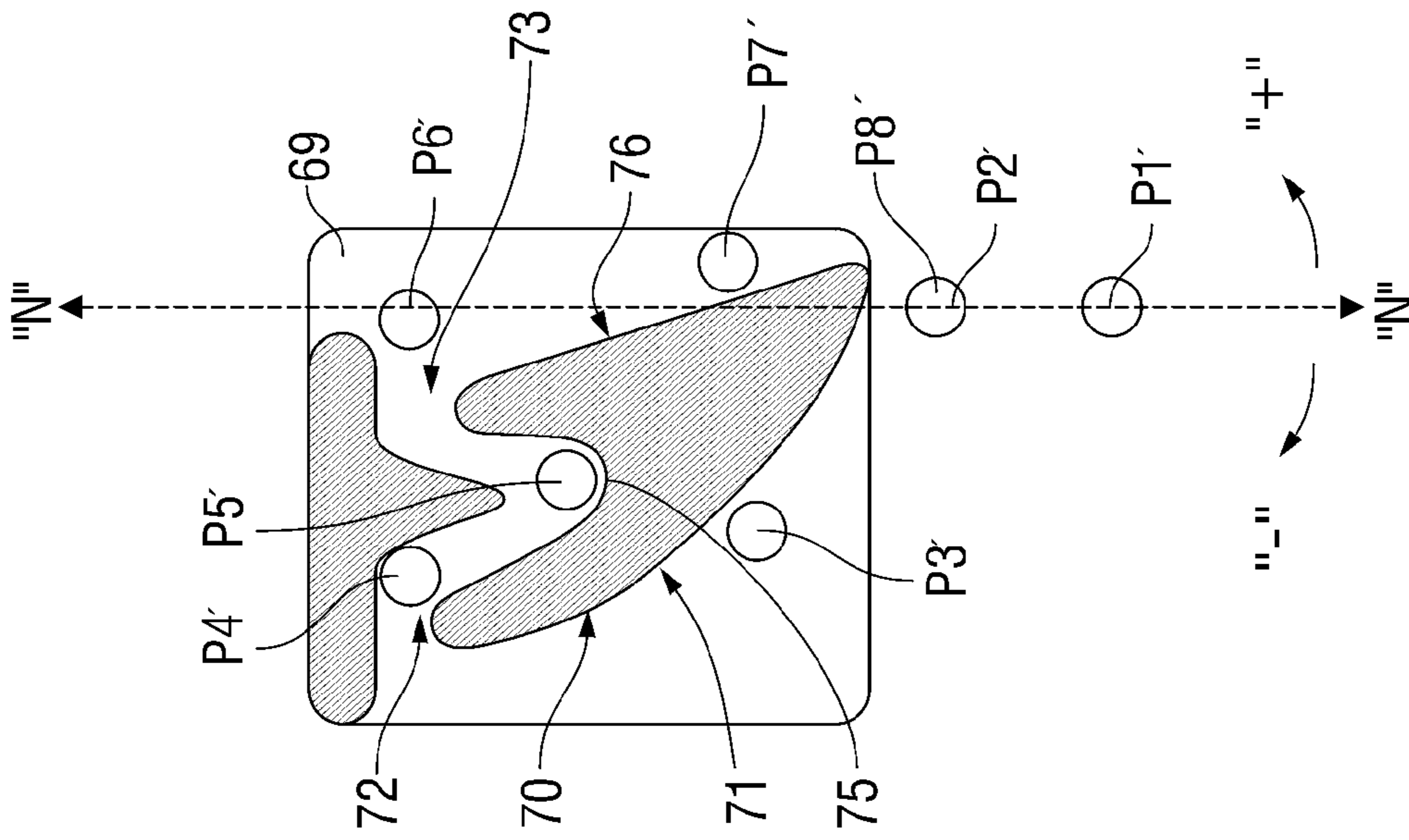


FIG. 10

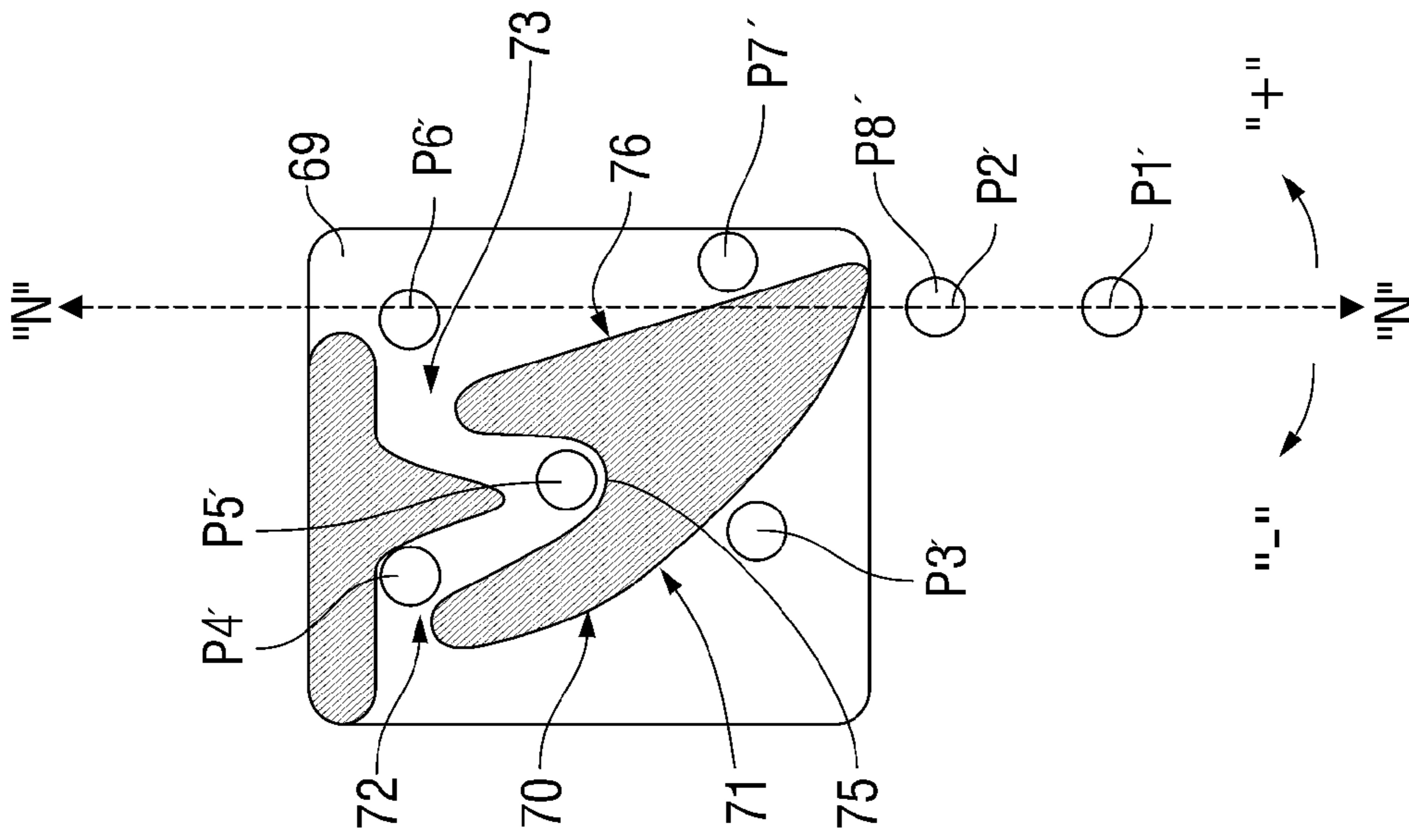


FIG. 11

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## LATCH MECHANISM FOR SURGICAL INSTRUMENTS

### CROSS-REFERENCE TO RELATED APPLICATIONS

This application is a continuation application of U.S. patent application Ser. No. 13/006,538 filed on Jan. 14, 2011, now U.S. Pat. No. 8,945,175, the entire contents of which are incorporated herein by reference.

### BACKGROUND

The present disclosure relates to surgical instruments. More particularly, the present disclosure relates to releasable latch mechanisms for use with surgical instruments.

### TECHNICAL FIELD

Electrosurgical instruments, e.g., forceps, utilize both mechanical clamping action and electrical energy to effect hemostasis by heating tissue and blood vessels to coagulate, cauterize and/or seal tissue. As an alternative to open forceps for use with open surgical procedures, many modern surgeons use endoscopic or laparoscopic instruments for remotely accessing organs through smaller, puncture-like incisions or natural orifices. As a direct result thereof, patients tend to benefit from less scarring and reduced healing time.

Many endoscopic surgical procedures require cutting or ligating blood vessels or vascular tissue. Due to the inherent spatial considerations of the surgical cavity, surgeons often have difficulty suturing vessels or performing other traditional methods of controlling bleeding, e.g., clamping and/or tying-off transected blood vessels. By utilizing an endoscopic electrosurgical forceps, a surgeon can either cauterize, coagulate/desiccate and/or simply reduce or slow bleeding simply by controlling the intensity, frequency and duration of the electrosurgical energy applied through the jaw members to the tissue. Most small blood vessels, i.e., in the range below two millimeters in diameter, can often be closed using standard electrosurgical instruments and techniques. However, if a larger vessel is ligated, it may be necessary for the surgeon to convert the endoscopic procedure into an open-surgical procedure and thereby abandon the benefits of endoscopic surgery. Alternatively, the surgeon can seal the larger vessel or tissue. Typically, after a vessel or tissue is sealed, the surgeon advances a knife to sever the sealed tissue disposed between the opposing jaw members.

### SUMMARY

The present disclosure relates to a latch mechanism for use with a surgical instrument. The latch mechanism includes a lever moveable relative to a housing of the surgical instrument from an initial position to an actuated position for moving an end effector assembly of the surgical instrument from a first state to a second state. A pin extends from the lever and a cantilever spring is operably engaged to the housing of the surgical instrument at a fixed end thereof. A pin track member is operably engaged to the cantilever spring at a free end of the cantilever spring. The pin track member is configured to permit translation of the pin therealong between a first position corresponding to the initial position of the lever and a second position corresponding to the actuated position of the lever. The pin is configured to translate from the first position to the second position along a first path and from the second position back to the first position along a second path different

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from the first path. The pin is further configured to be releasably retained in the second position upon translation of the pin from the first position to the second position along the first path.

5 In one embodiment, the cantilever spring is biased toward alignment with a neutral axis defined therein. The cantilever spring is capable of flexing in each of a positive direction and a negative direction relative to the neutral axis to permit translation of the pin along the first and second paths.

10 In another embodiment, the cantilever spring is configured to deflect in the negative direction relative to the neutral axis to permit translation of the pin from the first position to the second position along the first path. On the other hand, the cantilever spring may be configured to deflect in the positive direction relative to the neutral axis to permit translation of the pin from the second position back to the first position along the second path.

15 In yet another embodiment, the cantilever spring is substantially aligned with the neutral axis when the pin is disposed in the first position. When the pin is disposed in the second position, the cantilever spring may be biased in a negative direction relative to the neutral axis.

20 In still another embodiment, the pin track member includes a saddle portion defined therein and positioned relative to the neutral axis such that, in the second position, the pin is retained in the saddle portion of the pin track member under the bias of the cantilever spring back toward the neutral axis.

25 In still yet another embodiment, the pin is configured to translate from the first position to a third position corresponding to a position proximal of the actuated position of the lever and back to the second position along the first path to retain the lever in the actuated position.

30 In another embodiment, the pin is configured to translate from the second position to the third position and back to the first position along the second path to return the lever to the initial position.

35 Another embodiment of a latch mechanism configured for use with a surgical instrument is provided. The latch mechanism includes a lever moveable relative to a housing of the surgical instrument from an initial position to an actuated position for moving an end effector assembly of the surgical instrument from a first state to a second state. A cantilever spring is engaged to the lever at a fixed end thereof and a pin is engaged to the cantilever spring at a free end of the cantilever spring. A pin track member is operably engaged to the housing of the surgical instrument. The pin track member is configured to permit translation of the pin therealong between a first position corresponding to the initial position of the lever and a second position corresponding to the actuated position of the lever. The pin is configured to translate from the first position to the second position along a first path and from the second position back to the first position along a second path different from the first path. The pin is further configured to be releasably retained in the second position upon translation of the pin from the first position to the second position along the first path.

40 In one embodiment, the cantilever spring is biased toward alignment with a neutral axis defined therein. In such an embodiment, the cantilever spring is capable of flexing in each of a positive direction and a negative direction relative to the neutral axis to permit translation of the pin along the first and second paths.

45 In another embodiment, the cantilever spring is configured to deflect in the negative direction relative to the neutral axis to permit translation of the pin from the first position to the second position along the first path. On the other hand, the cantilever spring may be configured to deflect in the positive

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direction relative to the neutral axis to permit translation of the pin from the second position back to the first position along the second path.

In yet another embodiment, the cantilever spring is configured to be substantially aligned with the neutral axis when the pin is disposed in the first position. When in the second position, the cantilever spring may be configured to be biased in a negative direction relative to the neutral axis.

In still another embodiment, the pin track member includes a saddle portion defined therein and positioned relative to the neutral axis such that, in the second position, the pin is retained in the saddle portion of the pin track member under the bias of the cantilever spring back toward the neutral axis.

In still yet another embodiment, the pin is configured to translate from the first position to a third position corresponding to a position proximal of the actuated position of the lever and back to the second position along the first path to retain the lever in the actuated position.

In another embodiment, the pin is configured to translate from the second position to the third position and back to the first position along the second path to return the lever to the initial position.

#### BRIEF DESCRIPTION OF THE DRAWINGS

Various embodiments of the presently disclosed latch mechanisms are described herein with reference to the drawings, wherein:

FIG. 1A is a perspective view of a forceps including an end effector assembly in accordance with an embodiment of the present disclosure wherein jaw members of the end effector assembly are disposed in a spaced-apart position;

FIG. 1B is a perspective view of the forceps of FIG. 1A wherein the jaw members of the end effector assembly are disposed in an approximated position;

FIG. 2 is a perspective view of a handle assembly of the forceps of FIG. 1A wherein a portion of the housing has been removed to show the internal components therein, the handle assembly including a latch mechanism disposed in an initial position;

FIG. 3 is a perspective view of the handle assembly of the forceps of FIG. 1A wherein a portion of the housing has been removed to show the internal components therein and wherein the latch mechanism is disposed in an actuated position;

FIG. 4 is an isolated, perspective view of a lever of the latch mechanism of FIGS. 2 and 3;

FIG. 5 is an isolated, perspective view of a pin track member and cantilever spring of the latch mechanism of FIGS. 2 and 3;

FIG. 6 is a schematic illustration of the use of the latch mechanism of FIGS. 2 and 3;

FIG. 7 is a perspective view of the handle assembly of the forceps of FIG. 1A wherein a portion of the housing has been removed to show the internal components therein, the handle assembly including another embodiment of a latch mechanism disposed in an actuated position;

FIG. 8 is an isolated, perspective view of a pin track member and cantilever spring of the latch mechanism of FIG. 7;

FIG. 9 is an isolated, perspective view of a lever of the latch mechanism of FIG. 7;

FIG. 10 is a transverse, cross-sectional view of the lever of FIG. 9; and

FIG. 11 is a schematic illustration of the use of the latch mechanism of FIG. 7.

#### DETAILED DESCRIPTION

Embodiments of the present disclosure are described in detail with reference to the drawing figures wherein like

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reference numerals identify similar or identical elements. As used herein, the term “distal” refers to the portion that is being described which is further from a user, while the term “proximal” refers to the portion that is being described which is closer to a user.

Turning now to FIGS. 1A and 1B, forceps 10 is one example of an instrument for use in accordance with the present disclosure. Forceps 10 including a housing 20, a handle assembly 30, a lever latch assembly 40, a trigger assembly 80, a rotating assembly 85, and an end effector assembly 100. Forceps 10 further includes a shaft 12 having a distal end 14 configured to mechanically engage end effector assembly 100 and a proximal end 16 that mechanically engages housing 20. Alternatively, any surgical instrument having a lever latch assembly operable to control one or more functions of the end effector assembly may be provided.

With continued reference to FIGS. 1A and 1B, end effector assembly 100 includes a pair of opposing jaw members 110 and 120. End effector assembly 100 is designed as a unilateral assembly, i.e., jaw member 120 is fixed relative to the shaft 12 and jaw member 110 is moveable about a pivot 103 relative to jaw member 120. However, either, or both jaw members 110, 120 may be moveable with respect to the other. In either embodiment, jaw members 110, 120 are moveable from a spaced-apart position, as shown in FIG. 1A, to an approximated position, as shown in FIG. 1B, to grasp tissue therebetween. Further, one or both of jaw members 110, 120 may include an electrically conductive tissue sealing surface 112, 122, respectively. Sealing surfaces 112, 122 are disposed in opposed relation relative to one another such that, with jaw members 110, 120 in the approximated position grasping tissue therebetween, electrosurgical energy may be supplied to one or both of sealing surfaces 112, 122 of jaw members 110, 120, respectively, to seal tissue grasped therebetween.

One or both of jaw members 110, 120 may also include a longitudinally extending blade channel 130 to permit reciprocation of a blade (not shown) therethrough for dividing tissue grasped therebetween. Trigger assembly 80 is operably coupled to the blade (not shown) such that, upon actuation of trigger 82, the blade (not shown) is translated from a retracted position to an extended position wherein the blade (not shown) is advanced between jaw members 110, 120 to cut tissue grasped therebetween. Further, trigger 82 may be biased toward an un-actuated position such that, upon release of trigger 82, the blade (not shown) is returned to the retracted position.

Rotating assembly 85 is integrally associated with housing 20 and is rotatable in either direction about a longitudinal axis “X-X” to rotate jaw members 110, 120 with respect to housing 20 about longitudinal axis “X-X.”

Handle assembly 30 extends downwardly from housing 20 and is releasably engageable with housing 20. Handle assembly 30 is ergonomically configured such that, when engaged with housing 20, a surgeon may grasp handle assembly 30 and operate lever latch assembly 40, trigger assembly 80 and/or rotating assembly 85 with a single hand. Handle assembly 30 further includes a battery pack (not shown) disposed within a battery housing 32. The battery pack (not shown) of handle assembly 30 provides power to forceps 10, e.g., for energizing sealing surfaces 112, 122 of jaw members 110, 120, respectively. More particularly, the battery pack (not shown) is configured to electrically couple to a generator (not shown) disposed within housing 20 for powering the generator (not shown). The generator (not shown), in turn, supplies the desired energy to sealing surfaces 112, 122 of jaw members 110, 120, respectively, of end effector assembly 100. Alternatively, forceps 10 may be configured to be

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coupled to an external power source (not shown) and/or generator (not shown), e.g., via an electrosurgical cable (not shown).

With reference to FIGS. 2 and 3, in conjunction with FIGS. 1A and 1B, battery housing 32 of handle assembly 30 includes mechanical keying features (not shown) configured complementarily to the mechanical keying features associated with housing 20 such that handle assembly 30 may be securely locked in mechanical engagement with housing 20. The battery pack (not shown) is electrically coupled to the generator (not shown), and may also be released from housing 20, e.g., to replace or recharge the battery pack (not shown).

Continuing with reference to FIGS. 2 and 3, one embodiment of a lever latch assembly 40 is shown including a lever 41 pivotably coupled to housing 20 and extending downwardly therefrom. Lever 41 is ultimately connected to drive assembly 90 that, together, mechanically cooperate to impart movement of jaw members 110 and 120 between the spaced-apart position (FIG. 1A) and the approximated position (FIG. 1B). As mentioned above, spatial constraints within housing 20 limit the positioning of lever 41, e.g., such that the generator (not explicitly shown) and other control circuitry (not explicitly shown) may be disposed above drive assembly 90 within housing 20. Further, as will become apparent below, the working components of lever latch assembly 40 are all relatively closely-spaced with respect to one another, thereby providing more area within housing 20 for the generator (not shown) and for engagement of the battery pack (not shown).

Continuing with reference to FIGS. 2 and 3, lever 41 is selectively moveable from an initial position (FIG. 2), wherein lever 41 is spaced-apart from handle assembly 30, to an actuated position (FIG. 3), wherein lever 41 is positioned adjacent to handle assembly 30, to move jaw members 110, 120 from the spaced-apart position (see FIG. 1A) to the approximated position (see FIG. 1B). As will be described below, lever latch assembly 40 is configured to permit movement of lever 41 between the initial position (FIG. 2) and the actuated position (FIG. 3) and for releasably locking lever 41 in the actuated position. Accordingly, lever latch assembly 40 is configured to selectively move jaw members 110, 120 (FIGS. 1A and 1B) between the spaced-apart position and the approximated position and to releasably lock jaw members 110, 120 (FIGS. 1A and 1B) in the approximated position. Further, lever 41 may be biased toward the initial position (FIG. 2), such that jaw members 110, 120 are biased toward the spaced-apart position (FIG. 1A).

Turning now to FIG. 4, in conjunction with FIGS. 2-3, lever 41 of lever latch assembly 40 includes a proximally-extending tab 43. Tab 43 extends at least partially into housing 20, e.g., through a slot (not shown) defined therein. More particularly, a proximal tip 44 of tab 43 extends into housing 20 when lever 41 is disposed in the initial position (FIG. 2), while the entire tab 43 (or a substantial portion thereof) extends into housing 20 when lever 41 is moved to the actuated position (FIG. 3). Tab 43 extends into housing 20 above handle assembly 30, as best shown in FIGS. 2 and 3, such that, when the battery pack (not shown) is engaged to housing 20, tab 43 may still be advanced into housing 20 upon movement of lever 41 from the initial position (FIG. 2) to the actuated position (FIG. 3).

A pin 45 is integrally formed with, or fixedly engaged to tab 43 of lever 41 and extends proximally therefrom. Pin 45 may be formed from a metal or other rigid material. As tab 43 is advanced into housing 20 upon movement of lever 41 from the initial position to the actuated position, pin 45 is similarly advanced into housing 20 toward pin track member 46 (FIG.

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5). In other words pin 45 is translated along an arc upon movement of lever 41 between the initial position and the actuated position. However, since pin 45 is fixedly engaged within lever 41 and since lever 41 is pivotably engaged to housing 20, the transverse position of pin 45 relative to housing 20 is fixed. More specifically, pin 45 is transversely aligned with a neutral axis "N-N" (FIG. 6) defined by cantilever spring 47 throughout movement of lever 41 between the initial position and the actuated position.

As best shown in FIG. 5, pin track member 46 defines a track 50 configured to permit translation of pin 45 therealong. Pin track member 46 is engaged, or integrally formed, e.g., insert molded, with a cantilever spring 47 at a first end 48 of cantilever spring 47. Cantilever spring 47 is coupled at a second end 49 thereof to housing 20, e.g., via protrusion-aperture friction fitting, or other suitable engagement. In other words, cantilever spring 47 is fixedly coupled to housing 20 at second end 49 thereof, while first end 48 of cantilever spring 47, having pin track member 46 disposed thereon, is free. At-rest, cantilever spring 47 is biased toward an aligned position defining the neutral axis "N-N" (FIG. 6). However, cantilever spring 47 is capable of being flexed off of the neutral axis "N-N" (FIG. 6) in both a positive direction "+" (FIG. 6) and a negative direction "-" (FIG. 6). As such, upon urging of pin track member 46 and, thus, the free first end 48 of cantilever spring 47 in either direction relative to the fixed second end 49 of cantilever spring 47, cantilever spring 47 is flexed off of the neutral axis "N-N" (FIG. 6) such that pin track member 46 is repositioned relative to the neutral axis "N-N" (FIG. 6). Under the bias of cantilever spring 47 toward an aligned position with respect to the neutral axis "N-N" (FIG. 6), pin track member 46 is likewise biased toward an aligned position with respect to the neutral axis "N-N" (FIG. 6).

Turning now to FIG. 6, in conjunction with FIGS. 2-3, the operation of lever latch assembly 40 will be described. Initially, with lever 41 disposed in the initial position (and, thus, with jaw members 110, 120 disposed in the spaced-apart position (FIG. 1A)), pin 45 extends minimally into housing 20, spaced-apart from pin track member 46. As shown in FIG. 6, this position corresponds to position P<sub>1</sub>. When it is desired to close jaw members 110, 120 (FIG. 1A), e.g., for grasping tissue therebetween, the surgeon grasps handle assembly 30 and lever 41 and pulls lever 41 proximally toward handle assembly 30, i.e., toward the actuated position. As lever 41 is moved from the initial position toward the actuated position, drive assembly 90 imparts movement of jaw members 110, 120 from the spaced-apart position to the approximated position. At the same time, as lever 41 is pulled proximally, tab 43 is advanced proximally into housing 20 such that pin 45 is translated, in transverse alignment with neutral axis "N-N," toward pin track member 46 to position P<sub>2</sub>. However, at this point, pin track member 46 remains aligned on the neutral axis "N-N" under the bias of cantilever spring 47.

Upon further movement of lever 41 toward the actuated position, pin 45 is advanced further proximally into housing 20, eventually contacting an outer surface 51 of pin track member 46. With pin 45 transversely fixed with respect to the neutral axis "N-N," pin 45 causes cantilever spring 47 to be flexed and urges pin track member 46 off of the neutral axis "N-N" in a negative direction "-" as pin 45 is translated through position P<sub>3</sub>. More specifically, the outer surface 51 of pin track member 46 is angled relative to neutral axis "N-N" such that, as lever 41 is pulled further toward the actuated position, pin 45 is slid proximally along outer surface 51 of pin track member 46, urging pin track member 46 off of the neutral axis "N-N."

Once lever **41** has been moved to the actuated position, corresponding to the approximated position of jaw members **110**, **120** (FIG. 1B), respectively, of end effector assembly **100**, pin **45** has been slid proximally past angled outer surface **51** of pin track member **46** to a position  $P_4$  adjacent first end **53** of track channel **52** of pin track member **46**. In this position  $P_4$ , with pin **45** no longer contacting outer surface **51** of pin track member **46**, pin **45** no longer urges pin track member **46** off of the neutral axis "N-N." As such, cantilever spring **47** is flexed back toward the aligned position, thereby moving pin track member **46** back toward alignment with the neutral axis "N-N."

When the actuated position of lever **41** has been achieved, such that jaw members **110**, **120** (FIG. 1B) are disposed in the approximated position to grasp tissue therebetween, lever **41** is automatically locked in the actuated position to fix jaw members **110**, **120** (FIG. 1B) in the approximated position. More particularly, once pin **45** is positioned adjacent first end **53** of track channel **52**, cantilever spring **47** biases pin track member **46** back toward the neutral axis "N-N" such that pin **45** is translated along track channel **52** from position  $P_4$  at the first end **53** of track channel **52** to position  $P_5$  at the saddle portion **54** of track channel **52**. Even if lever **41** is released at this point, pin **45** is retained in position within saddle portion **54** of track channel **52** of pin track member **46**. Specifically, pin track member **46** inhibits distal translation of pin **45** and, thus lever **41**, thereby maintaining jaw members **110**, **120** (FIG. 1B) in the approximated position. Further, with pin **45** disposed in position  $P_5$ , i.e., with pin **45** disposed within saddle portion **54** of track channel **52** of pin track member **46**, pin track member **46** is inhibited from returned into alignment with neutral axis "N-N."

Pin track member **46** may include one or more feedback features (not shown) for providing tactile and/or audible feedback notifying the surgeon that lever **41** has been translated to the actuated position. For example, saddle portion **54** may be configured to provide an audible or tactile response when pin **45** is translated into saddle portion **54**, e.g., when pin **45** is moved to position  $P_5$ . Such a feature indicates to the surgeon that lever latch assembly **40** is in the locked position and that lever **41** may be released to lock jaw members **110**, **120** in the approximated position.

With lever latch assembly **40** maintaining lever **41** in the actuated position and, thus, maintaining jaw members **110**, **120** (FIG. 1B) in the approximated position with tissue grasped therebetween, electrosurgical energy may be supplied to sealing surfaces **112**, **122** of jaw members **110**, **120**, respectively, to effect a tissue seal (see FIG. 1B). Thereafter, trigger **82** may be actuated to advance the blade (not shown) between jaw members **110**, **120** to cut tissue along the previously formed tissue seal. Finally, lever latch assembly **40** may be unlatched, as described in further detail below, allowing lever **41** to return to the initial position and allowing jaw members **110**, **120** (FIGS. 1A and 1B) to return to the spaced-apart position to release tissue such that forceps **10** may be removed from the surgical site.

In order to unlock lever latch assembly **40**, lever **41** is moved further proximally from the actuated position a sufficient distance to dislodge pin **45** from saddle portion **54** of track channel **52** of pin track member **46**. In other words, lever **41** is moved proximally such that pin **45** is no longer retained within saddle portion **54**. Track channel **52** is configured such that, once pin **45** is removed from saddle portion **54**, pin **45** enters open second end **55** of track channel **52**. Once pin **45** is moved into the open second end **55** of track channel **52**, e.g., once pin **45** is moved to position  $P_6$ , pin **45** no longer inhibits pin track member **46** from returning under the bias of canti-

lever spring **47** to the aligned position with respect to neutral axis "N-N." As such, cantilever spring **47** is returned to the at-rest position, thereby returning pin track member **46** into alignment with neutral axis "N-N."

At this point, with pin **45** in position  $P_6$ , the surgeon may release lever **41**. Similarly as discussed above, pin track member **46** may include feedback features (not shown) for providing a tactile or audible indication to the surgeon that pin **45** has been removed from saddle portion **54** of track channel **52** and, thus, that lever **41** may be released allowing jaw members **110**, **120** (FIGS. 1A and 1B) to return to the spaced-apart position.

Upon release of lever **41** by the surgeon, lever **41** is returned back to the initial position. As such, pin **45** is translated distally relative to pin track member **46** and housing **20**. More particularly, pin **45** is translated distally from position  $P_6$  along inner surface **56** of pin track member **46**. Inner surface **56** of pin track member **46** is angled such that, as pin **45** is translated therealong to position  $P_7$ , cantilever spring **47** is flexed to permit pin track member **46** to be repositioned off of the neutral axis "N-N" in a positive direction "+." Upon further distal translation of pin **45** to position  $P_8$ , pin **45** exits second end **55** of track channel **52** of pin track member **46**, allowing pin track member **46** to return under the bias of cantilever spring **47** back into alignment with the neutral axis "N-N." Thereafter, lever is further returned, e.g., under the bias, back to the initial position corresponding to position  $P_1$  of pin **45** and corresponding to the spaced-apart position of jaw members **110**, **120** of end effector assembly **100** (FIGS. 1A and 1B).

Turning now to FIGS. 7-9, another embodiment of a lever latch assembly **60** is shown configured for use with a surgical instrument, e.g., forceps **10**. Similar to lever latch assembly **40** discussed above (see FIGS. 2-6), lever latch assembly **60** includes a lever **61** pivotably coupled to housing **20** and extending downwardly therefrom. Lever **61** is ultimately connected to drive assembly **90** that, together, mechanically cooperate to impart movement of jaw members **110** and **120** between the spaced-apart position (FIG. 1A) and the approximated position (FIG. 1B). More particularly, lever **61** is selectively moveable from an initial position, wherein lever **61** is spaced-apart from handle assembly **30**, to an actuated position, wherein lever **61** is positioned adjacent to handle assembly **30**, to move jaw members **110**, **120** from the spaced-apart position (see FIG. 1A) to the approximated position (see FIG. 1B).

With continued reference to FIGS. 7-9, lever latch assembly **60** is similar to lever latch assembly **40** in that lever latch assembly **60** is configured to permit movement of lever **61** between the initial position and the actuated position and for releasably locking lever **61** in the actuated position. Accordingly, lever latch assembly **60** is configured to selectively move jaw members **110**, **120** between the spaced-apart position (FIG. 1A) and the approximated position (FIG. 1B) and to releasably lock jaw members **110**, **120** in the approximated position (FIG. 1B). Further, lever **61** may be biased toward the initial position, such that jaw members **110**, **120** are biased toward the spaced-apart position (FIG. 1A).

As best shown in FIG. 9, lever **61** of lever latch assembly **60** includes a pair of flanges **63** extending upwardly therefrom. Flanges **63** extend into housing **20** to couple lever **61** to housing **20**. A crossbar **64** extends between flanges **63** in a generally perpendicular orientation with respect to flanges **63**. A cantilever spring **65** is fixedly engaged at a first end **67** thereof to crossbar **64** and includes a pin **66** integrally formed with, or otherwise engaged to free second end **68** of cantilever spring **65**. Cantilever spring **65** extends downwardly and

proximally from crossbar 64 of flanges 63 of lever 61 such that pin 66 extends generally toward housing 20. More specifically, when lever 61 is disposed in the initial position, pin 66 is spaced-apart from housing 20. On the other hand, when lever 61 is moved to the actuated position, pin 66 is positioned adjacent housing 20. Further, cantilever spring 65 is positioned off-center on crossbar 64, i.e., cantilever spring 65 is positioned asymmetrically between flanges 63 of lever 61. At-rest, cantilever spring 65 is biased toward an aligned position defining the neutral axis "N-N" (FIGS. 10 and 11). However, cantilever spring 65, similar to cantilever spring 65, is capable of being flexed off of the neutral axis "N-N" (FIGS. 10 and 11) in both a position direction "+" and a negative direction "-" to thereby reposition pin 66 off of the neutral axis "N-N" (FIGS. 10 and 11).

Referring to FIGS. 7-11, lever latch assembly 60 also includes a pin track member 69 defining a track 70 configured to permit translation of pin 66 therealong. Pin track member 69 is engaged to, or integrally formed with housing 20 in a generally distal-facing orientation and is positioned to at least partially intersect the neutral axis "N-N." As such, upon movement of lever 61 from the initial position to the actuated position, pin 66 is translated along an arc toward housing 20 and, thus, toward pin track member 69, eventually engaging pin track member 69. As will be described in greater detail below, with pin track member 69 fixedly engaged to housing 20, and with pin 66 engaged to lever 61 via cantilever spring 65, movement of lever 61 between the initial position and the actuated position causes pin track member 69 to urge the free second end 68 of cantilever spring 65 off of the neutral axis "N-N" such that pin 66 is repositioned relative to the neutral axis "N-N" to releasably lock lever 61 in the actuated position.

The operation of lever latch assembly 60 will now be described. Initially, with lever 61 disposed in the initial position (and, thus, with jaw members 110, 120 disposed in the spaced-apart position (FIG. 1A)), pin 66 is spaced-apart from pin track member 69 and, thus, cantilever spring 65 is aligned on neutral axis "N-N." As shown in FIG. 6, this position corresponds to position P<sub>1</sub>'. When it is desired to close jaw members 110, 120 (FIGS. 1A-1B), e.g., for grasping tissue therebetween, the surgeon grasps handle assembly 30 and lever 61 and pulls lever 61 proximally toward handle assembly 30, i.e., toward the actuated position. As lever 61 is moved from the initial position toward the actuated position, drive assembly 90 imparts movement of jaw members 110, 120 from the spaced-apart position to the approximated position (FIG. 1B). At the same time, as lever 61 is pulled proximally, pin 66 is advanced proximally toward housing 20 such that pin 66 is translated toward pin track member 69, represented by position P<sub>2</sub>'. However, at this point, pin 66 is still spaced from pin track member 69 and, thus, remains aligned on the neutral axis "N-N" under the bias of cantilever spring 65.

Upon further movement of lever 61 toward the actuated position, pin 66 is advanced further proximally toward housing 20, eventually contacting an outer surface 71 of pin track member 69. Due to the angled configuration of outer surface 71 of pin track member 69 relative to the neutral axis "N-N," and with pin track member 69 transversely fixed with respect to the neutral axis "N-N," cantilever spring 65 is flexed and pin 66 is urged off of the neutral axis "N-N" in a negative direction "-" as pin 66 is translated through position P<sub>3</sub>' and along outer surface 71.

Once lever 61 has been moved to the actuated position, corresponding to the approximated position of jaw members 110, 120, respectively, of end effector assembly 100 (FIGS. 1A and 1B), pin 66 has been slid proximally past angled outer

surface 71 of pin track member 69 to a position P<sub>4</sub>' adjacent first end 72 of track channel 74 of pin track member 69. In this position P<sub>4</sub>', with pin 66 no longer contacting outer surface 71 of pin track member 69, pin track member 69 no longer urges pin 66 off of the neutral axis "N-N." As such, cantilever spring 65 is flexed back toward the aligned position, thereby moving pin 66 back toward alignment with the neutral axis "N-N."

When lever is moved to the actuated position and is subsequently released, lever latch assembly 60 releasably locks lever 61 in the actuated position to fix jaw members 110, 120 in the approximated position (see FIG. 1B). More particularly, once pin 66 is positioned adjacent first end 72 of track channel 74, cantilever spring 65 biases pin 66 back toward the neutral axis "N-N" such that pin 66 is translated along track channel 74 from position P<sub>4</sub>' at the first end 72 of track channel 74 to position P<sub>5</sub>' at the saddle portion 75 of track channel 74. In this position, pin track member 69 inhibits distal translation of pin 66 and, thus lever 61, thereby maintaining jaw members 110, 120 in the approximated position. As in the previous embodiment, pin 66 and/or pin track member 69 may include one or more feedback features (not shown) for providing tactile and/or audible feedback notifying the surgeon that lever 61 has been translated to the actuated position.

With lever latch assembly 60 maintaining lever 61 in the actuated position and, thus, maintaining jaw members 110, 120 (FIG. 1B) in the approximated position with tissue grasped therebetween, electrosurgical energy may be supplied to sealing surfaces 112, 122 of jaw members 110, 120, respectively, to effect a tissue seal (see FIG. 1B). Thereafter, trigger 82 may be actuated to advance the blade (not shown) between jaw members 110, 120 (FIG. 1B) to cut tissue along the previously formed tissue seal. Finally, lever latch assembly 60 may be unlatched, as will be described in greater detail below, allowing lever 61 to return to the initial position and allowing jaw members 110, 120 (FIGS. 1A and 1B) to return to the spaced-apart position to release tissue such that forceps 10 may be removed from the surgical site.

In order to unlock lever latch assembly 60, lever 61 is moved further proximally from the actuated position a sufficient distance to dislodge pin 66 from saddle portion 75 of track channel 74 of pin track member 69. In other words, lever 61 is moved proximally such that pin 66 is no longer retained within saddle portion 75. Track channel 74 is configured such that, once pin 66 is removed from saddle portion 75, pin 66 enters open second end 73 of track channel 74. Once pin 66 is moved into the open second end 73 of track channel 74, e.g., once pin 66 is moved to position P<sub>6</sub>', pin track member 69 no longer inhibits pin 66 from returning under the bias of cantilever spring 65 to the aligned position with respect to neutral axis "N-N." As such, cantilever spring 65 is returned to the at-rest position, thereby returning pin 66 into alignment with neutral axis "N-N." At this point, with pin 66 in position P<sub>6</sub>', the surgeon may release lever 61, allowing jaw members 110, 120 to return to the spaced-apart position (see FIG. 1A). Upon release of lever 61 by the surgeon, lever 61 is returned back to the initial position. As such, pin 66 is translated distally relative to pin track member 69 and housing 20. More particularly, pin 66 is translated distally from position P<sub>6</sub>' along inner surface 76 of pin track member 69. Inner surface 76 of pin track member 69 is angled such that, as pin 66 is translated therealong to position P<sub>7</sub>', cantilever spring 65 is flexed to permit pin 66 to be repositioned off of the neutral axis "N-N" in a positive direction "+." Upon further distal translation of pin 66 to position P<sub>8</sub>', pin 66 exits second end 73 of track channel 74 of pin track member 69, allowing pin 66 to return under the bias of cantilever spring 65 back into alignment



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with the neutral axis "N-N." Thereafter, lever 61 is further returned, e.g., under the bias, back to the initial position corresponding to position P<sub>1</sub>' of pin 66 and corresponding to the spaced-apart position of jaw members 110, 120 of end effector assembly 100 (FIG. 1A).

From the foregoing and with reference to the various figure drawings, those skilled in the art will appreciate that certain modifications can also be made to the present disclosure without departing from the scope of the same. While several embodiments of the disclosure have been shown in the drawings, it is not intended that the disclosure be limited thereto, as it is intended that the disclosure be as broad in scope as the art will allow and that the specification be read likewise. Therefore, the above description should not be construed as limiting, but merely as exemplifications of particular embodiments. Those skilled in the art will envision other modifications within the scope and spirit of the claims appended hereto.

What is claimed:

1. A surgical instrument, comprising:
  - a housing;
  - an end effector assembly;
  - a lever operably coupled to the end effector assembly and movable relative to the housing between an initial position and an actuated position for moving the end effector assembly between a first state and a second state; and
  - a latch mechanism, including:
    - a pin associated with the lever;
    - a pin track member associated with the housing;
    - a cantilever spring coupling the pin with the lever or coupling the pin track member with the housing, wherein, where the cantilever spring couples the pin with the lever, the pin track member is fixed relative to the housing, and wherein, where the cantilever spring couples the pin track member with the housing, the pin is fixed relative to the handle, the cantilever spring configured to flex transversely relative to a direction of movement of the lever to permit movement of the pin relative to the pin track member between a first position corresponding to the initial position of the lever and a second position corresponding to the actuated position of the lever, the pin configured to be releasably retained in the second position upon movement of the pin from the first position to the second position, wherein, in the first position, the pin is disposed outside the pin track member, and, wherein, in the second position, the pin is disposed within the pin track member.
2. The surgical instrument according to claim 1, wherein the pin is configured to move from the first position to the second position along a first path and from the second position back to the first position along a second path different from the first path.

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3. The surgical instrument according to claim 2, wherein the cantilever spring is biased toward alignment with a neutral axis, the cantilever spring capable of flexing in each of a positive transverse direction and a negative transverse direction relative to the neutral axis to permit movement of the pin along the first and second paths.

4. The surgical instrument according to claim 3, wherein the cantilever spring is configured to deflect in the negative transverse direction relative to the neutral axis to permit movement of the pin from the first position to the second position along the first path.

5. The surgical instrument according to claim 3, wherein the cantilever spring is configured to deflect in the positive transverse direction relative to the neutral axis to permit movement of the pin from the second position back to the first position along the second path.

6. The surgical instrument according to claim 3, wherein the cantilever spring is substantially aligned with the neutral axis when the pin is disposed in the first position.

7. The surgical instrument according to claim 3, wherein the cantilever spring is biased in the negative transverse direction relative to the neutral axis when the pin is disposed in the second position.

8. The surgical instrument according to claim 7, wherein the pin track member includes a saddle portion defined therein and positioned relative to the neutral axis such that, in the second position, the pin is retained in the saddle portion of the pin track member under the bias of the cantilever spring.

9. The surgical instrument according to claim 1, wherein the pin is configured to move from the first position to a third position corresponding to a position proximal of the actuated position of the lever and back to the second position along the first path to retain the lever in the actuated position.

10. The surgical instrument according to claim 9, wherein the pin is configured to translate from the second position to the third position and back to the first position along the second path to return the lever to the initial position.

11. The surgical instrument according to claim 1, further including a shaft extending distally from the housing and interconnecting the housing with the end effector assembly.

12. The surgical instrument according to claim 1, further including a drive assembly coupled between the lever and the end effector assembly.

13. The surgical instrument according to claim 1, wherein the end effector assembly includes first and second jaw members, wherein, in the first state, the first and second jaw members are disposed in a spaced-apart position relative to each other and, wherein, in the second state, the first and second jaw members are disposed in an approximated position relative to one another.

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