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Grill**

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(54) **FOLDING DEVICE**

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CPC **B65H 45/20** (2013.01); **B65H 2701/1768** (2013.01); **B65H 45/30** (2013.01); **B65H 45/1015** (2013.01)
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USPC 493/359, 424, 356, 59, 68, 355, 463, 493/412, 357, 433
See application file for complete search history.

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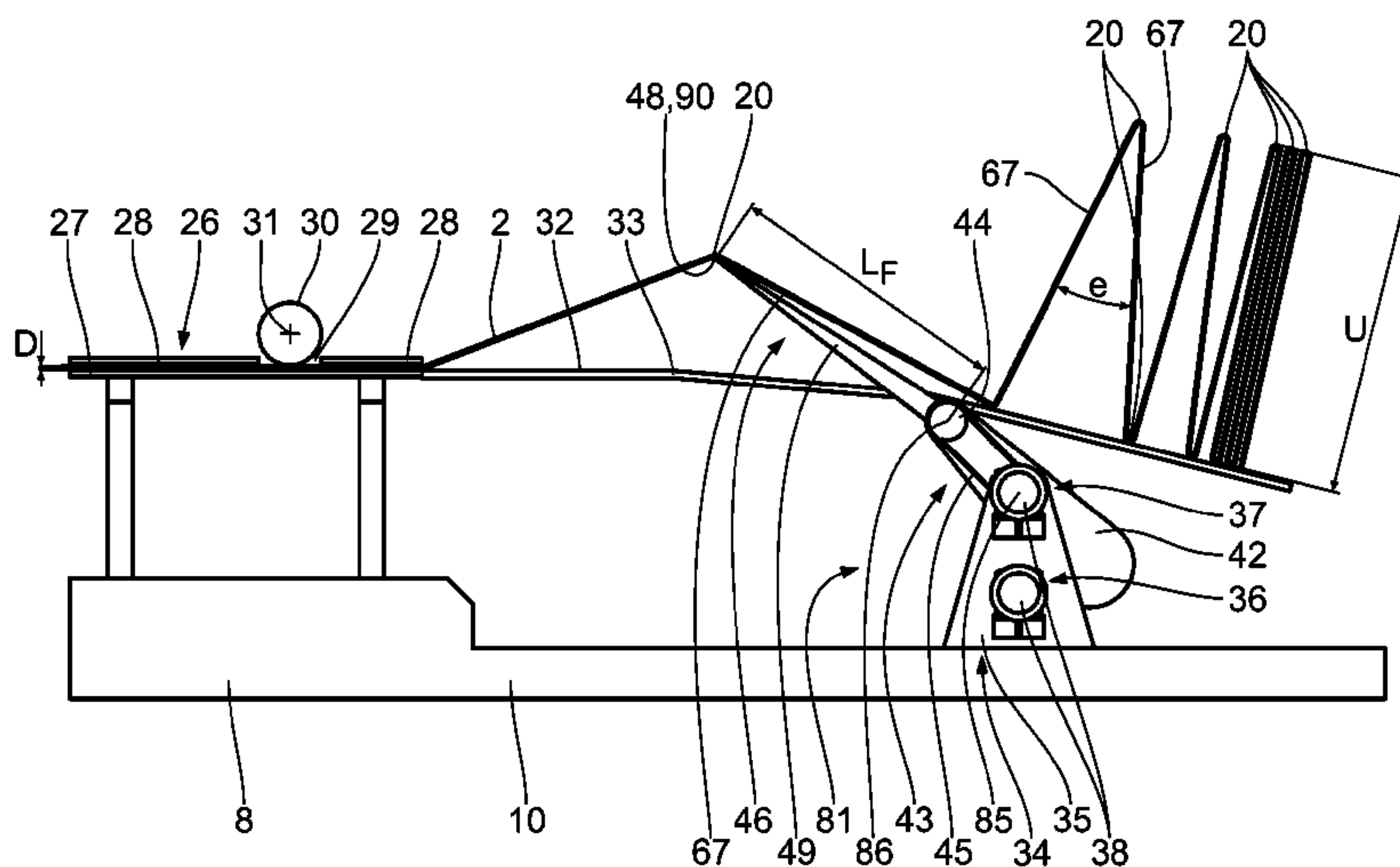
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(57) **ABSTRACT**

A device for folding an endlessly producible web of corrugated cardboard comprises a stand with two retaining members, at least one engagement member mounted in the stand, the engagement member comprising at least one projection which comprises at least one free end forming a contact edge, and at least one driving device for moving the at least one engagement member, with the at least one engagement member being movably mounted in the stand in such a way that the contact edge is movable at an angle relative to the contact surface along a predetermined trajectory so as to bring the contact edge into engagement with the web of corrugated cardboard sliding on the contact surface.

15 Claims, 11 Drawing Sheets



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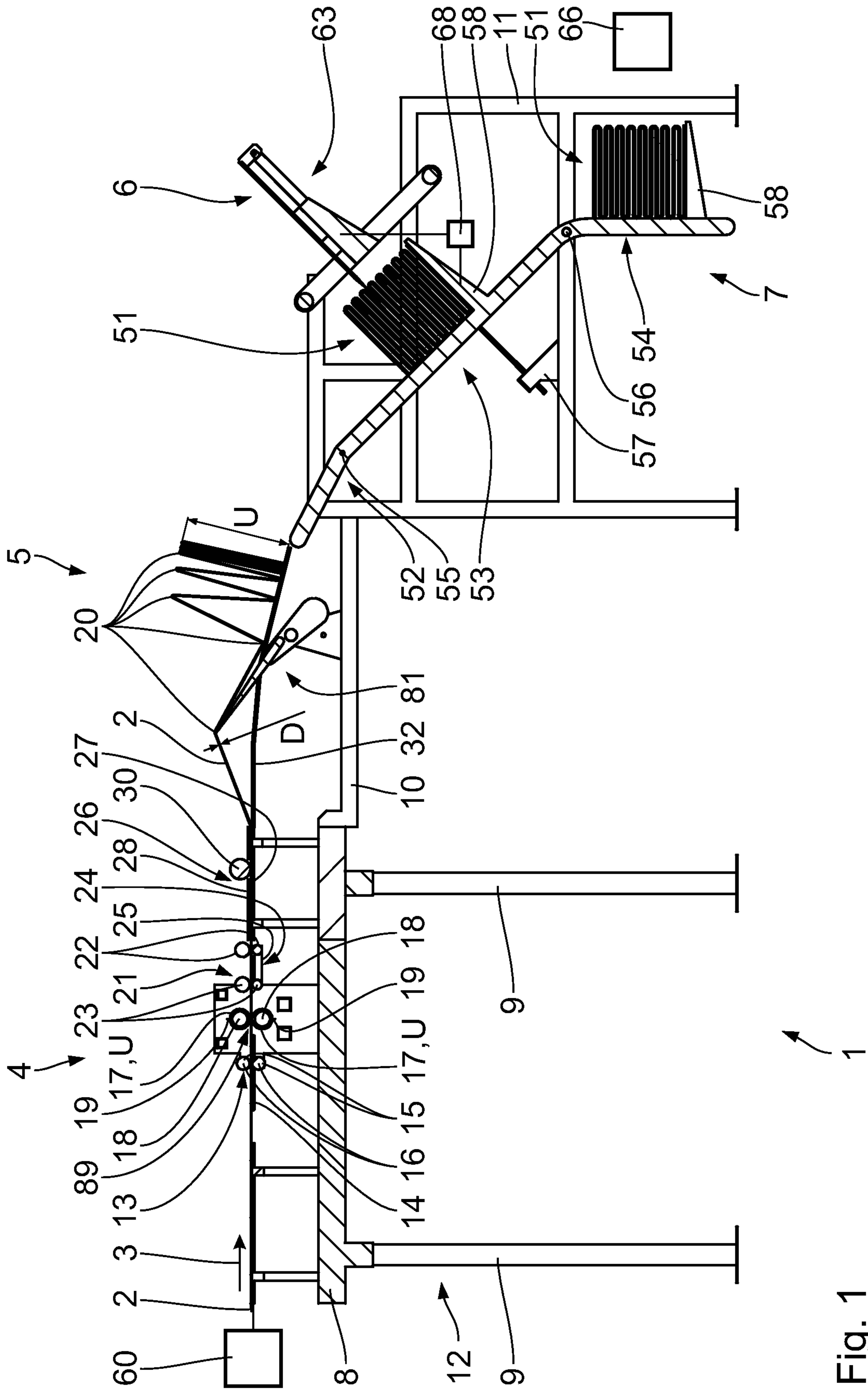


Fig. 1

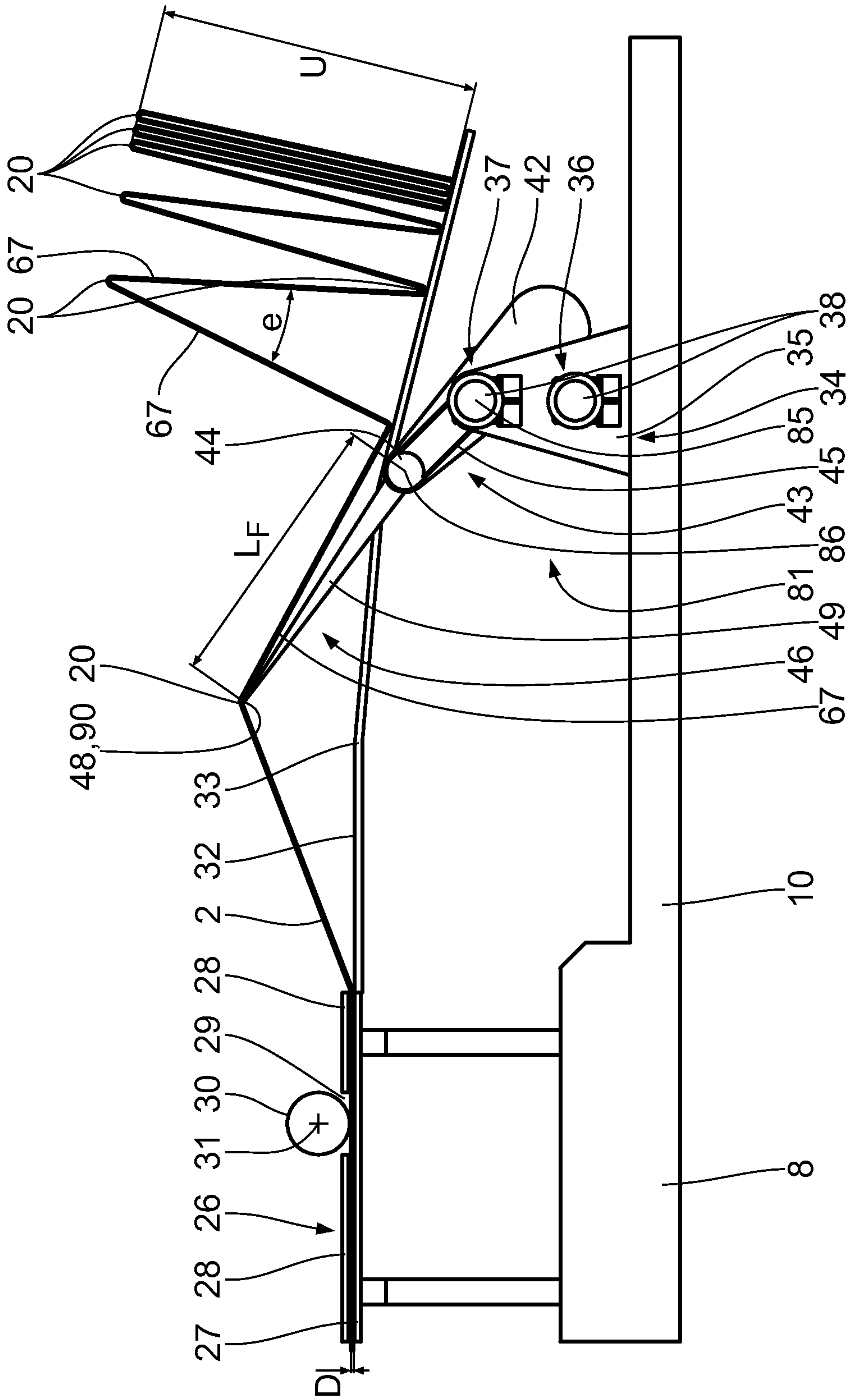


Fig. 2

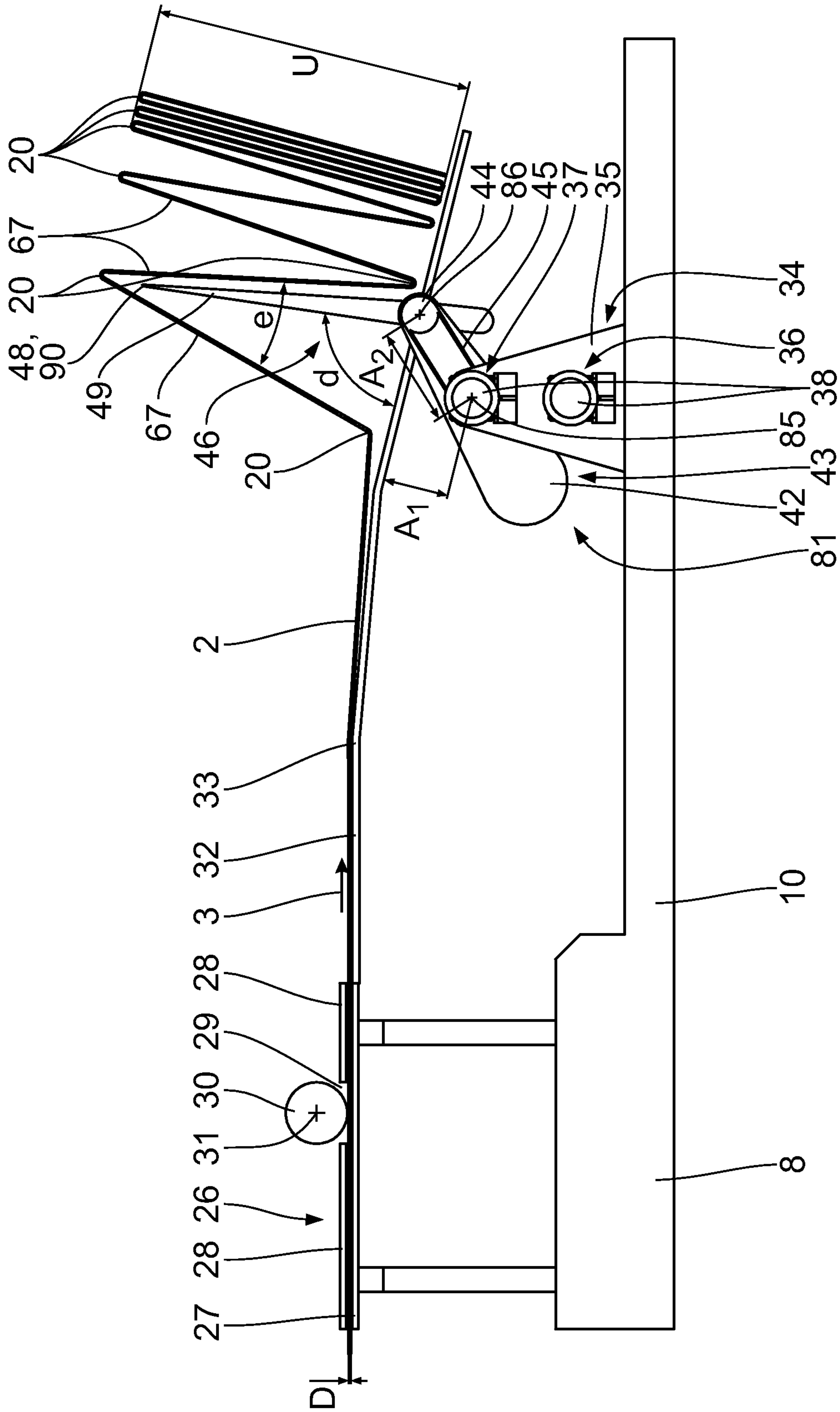


Fig. 3

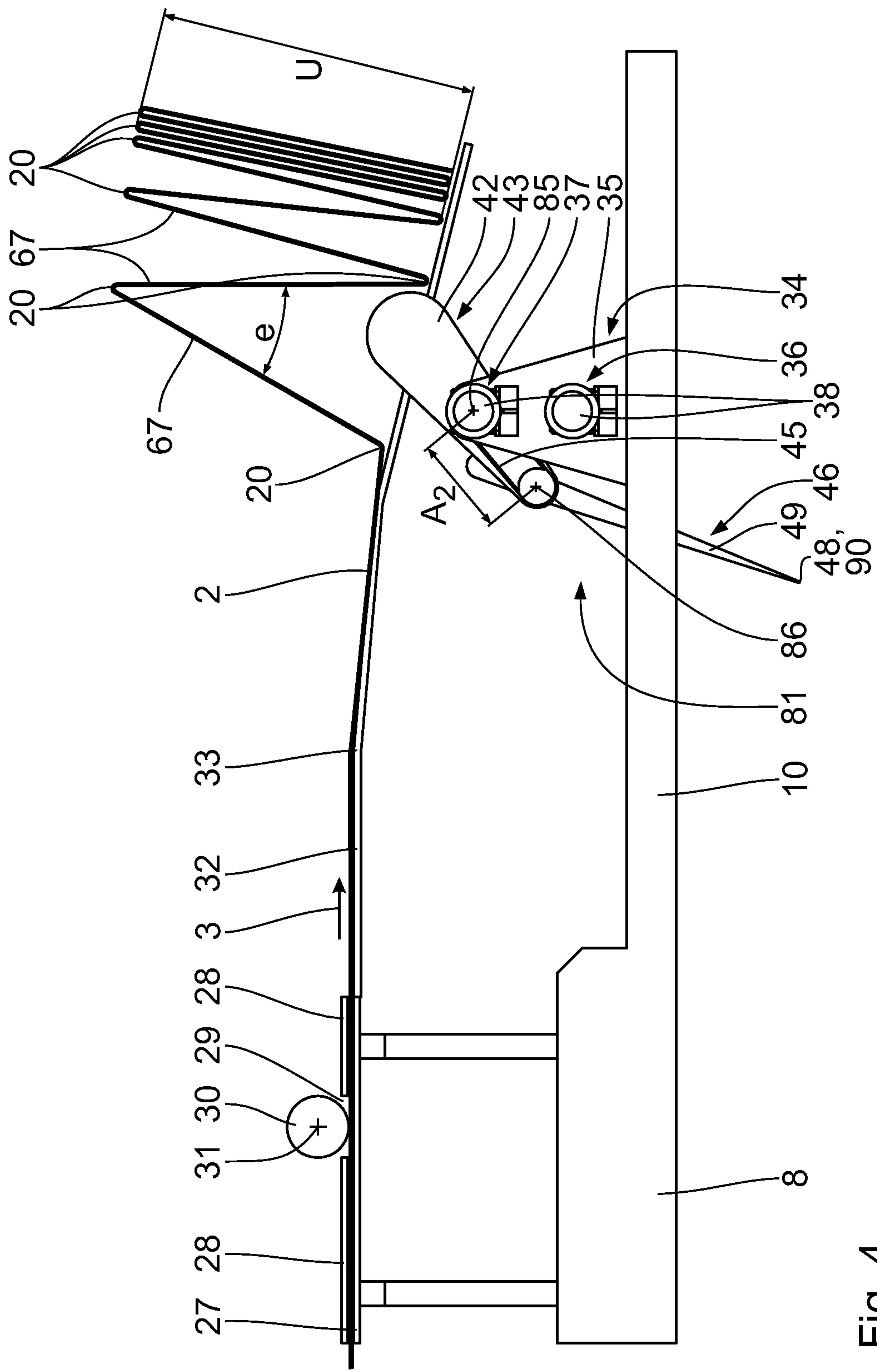


Fig. 4

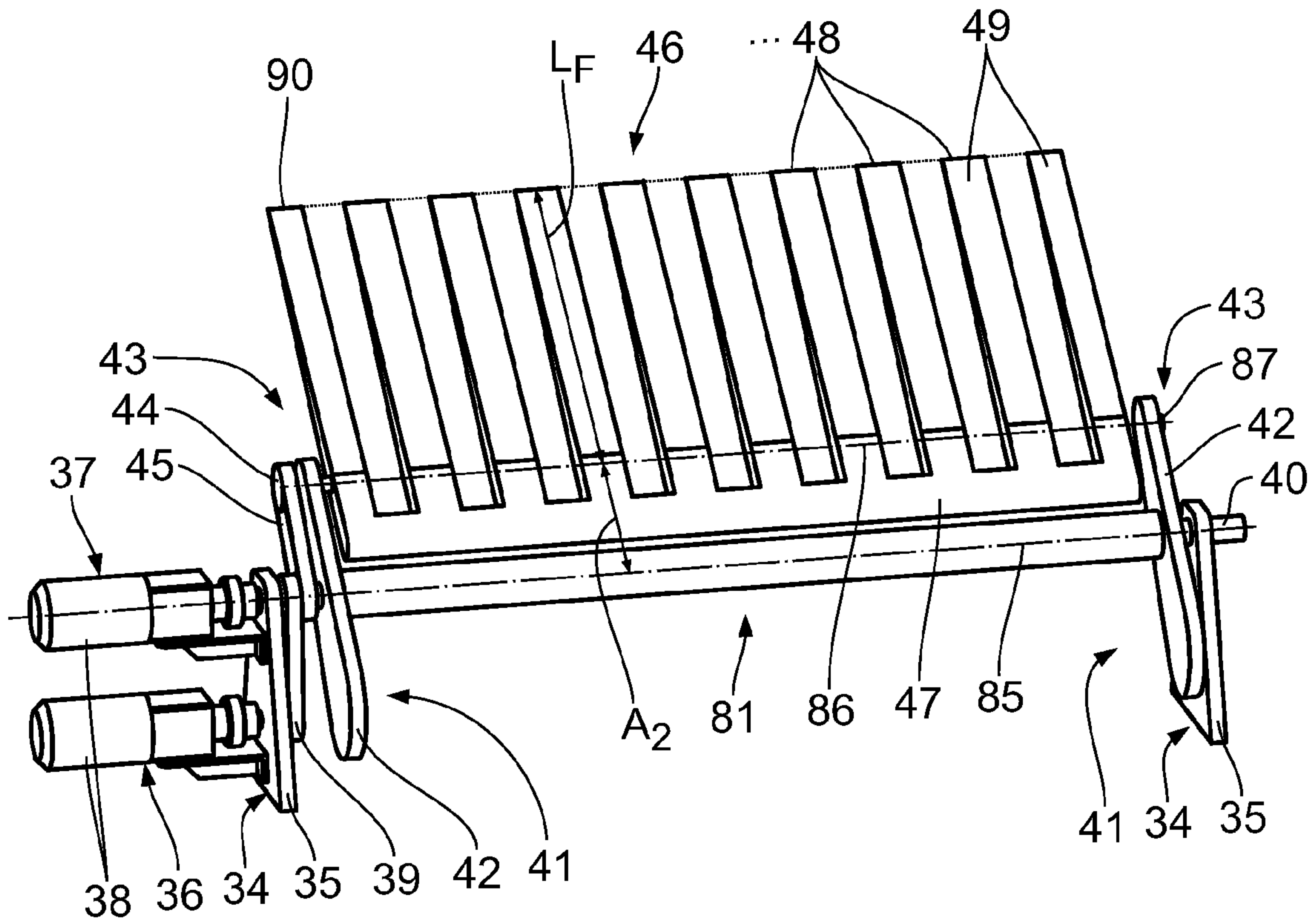


Fig. 5

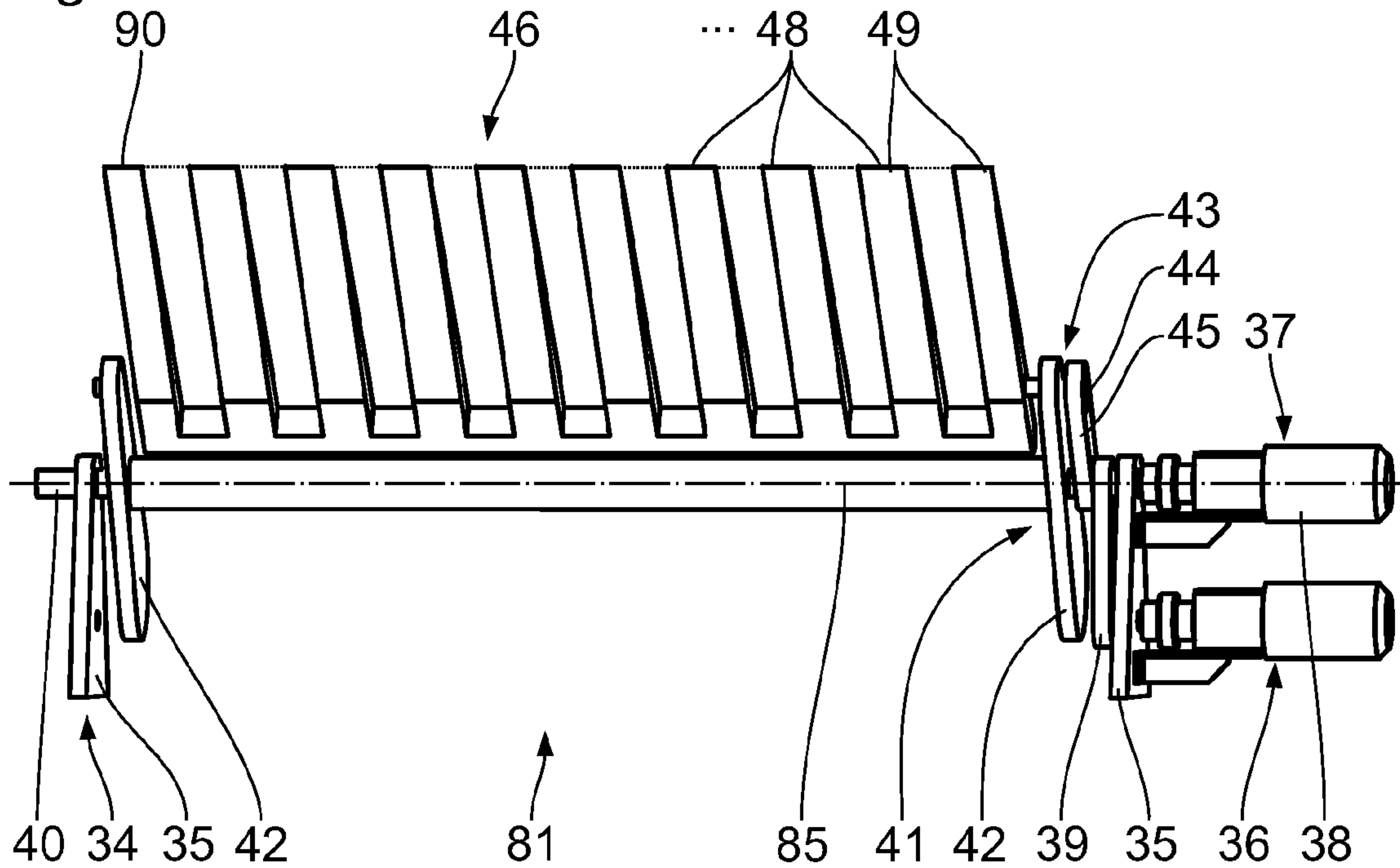


Fig. 6

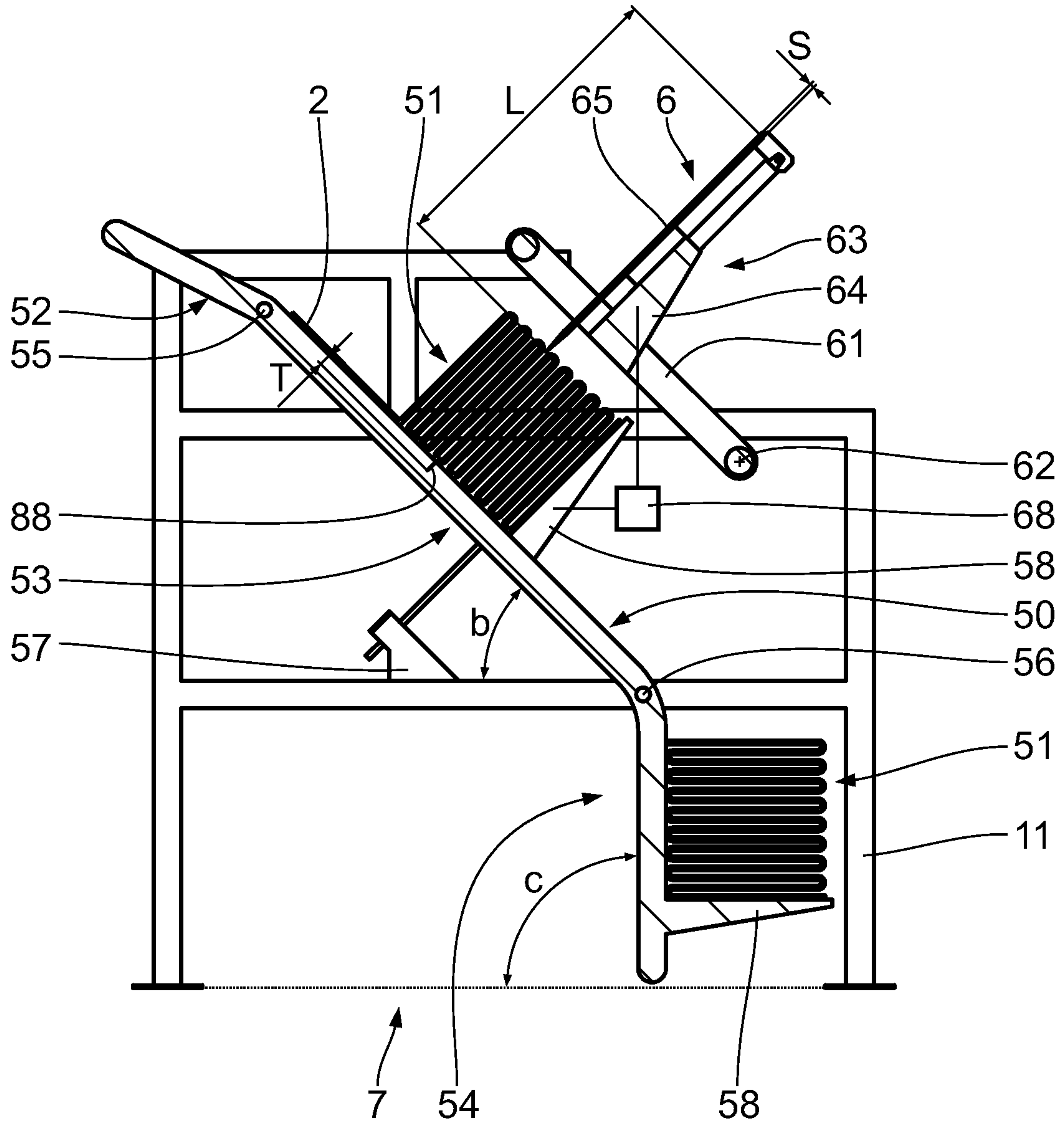


Fig. 7

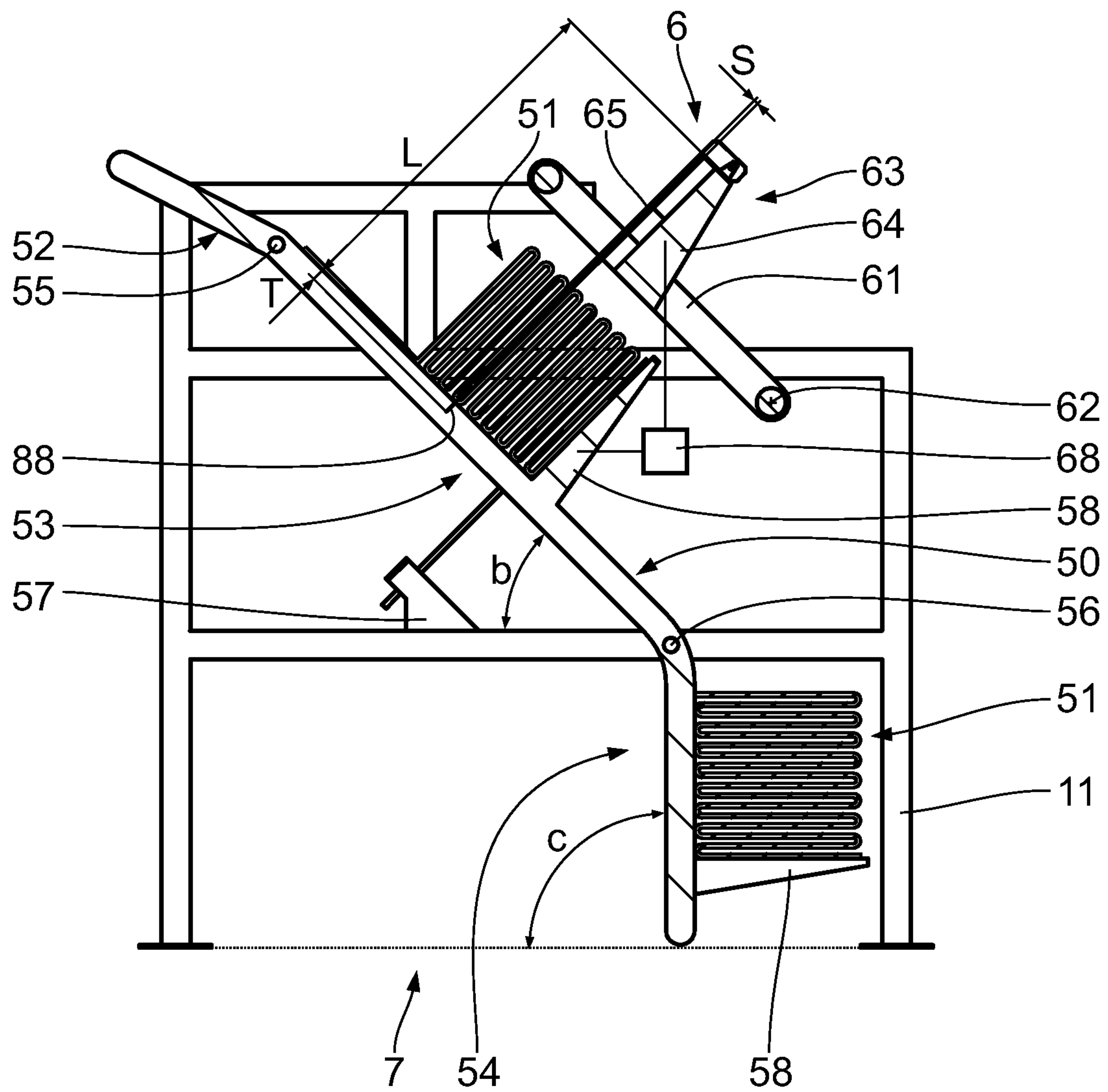


Fig. 8

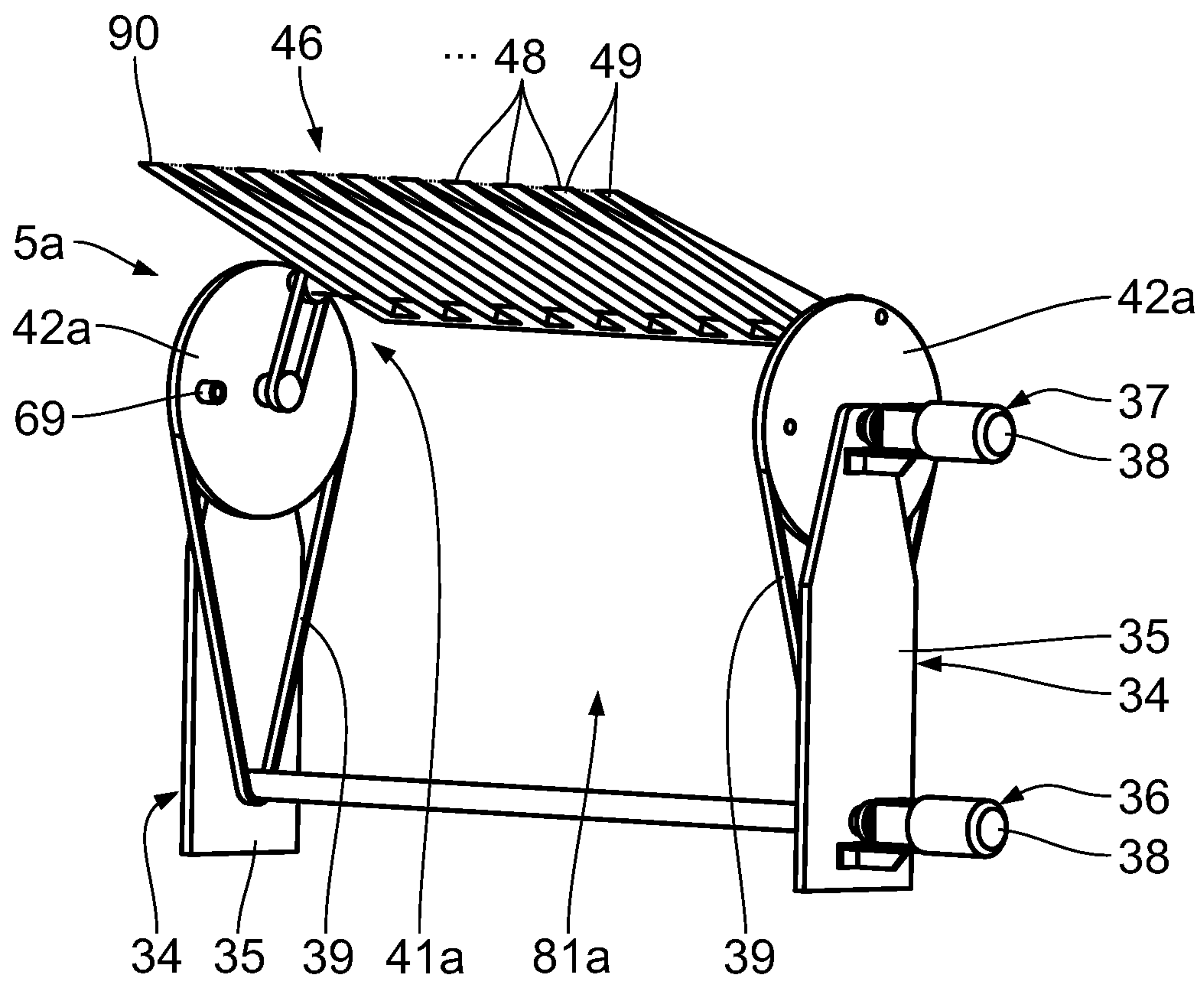


Fig. 9

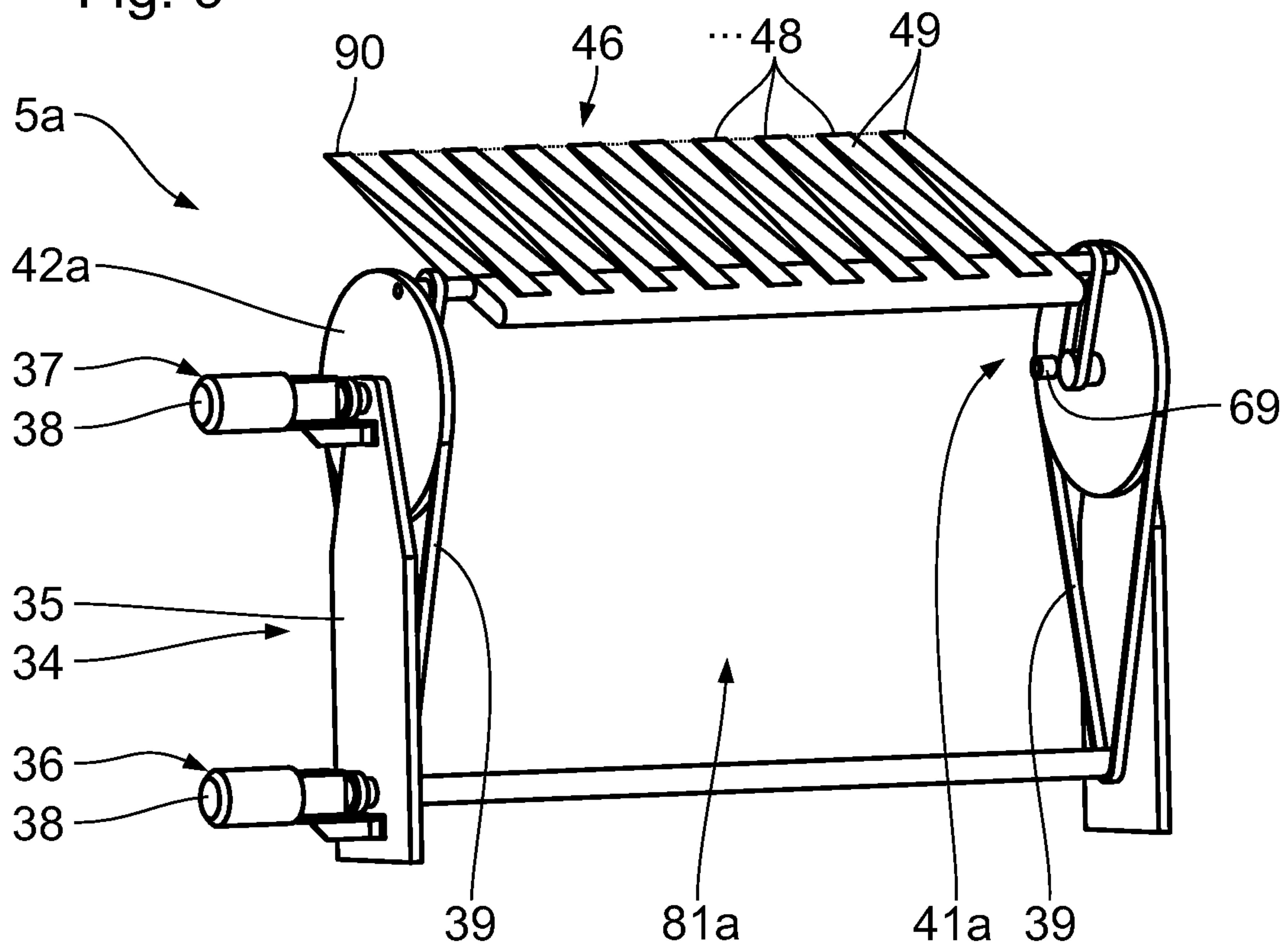


Fig. 10

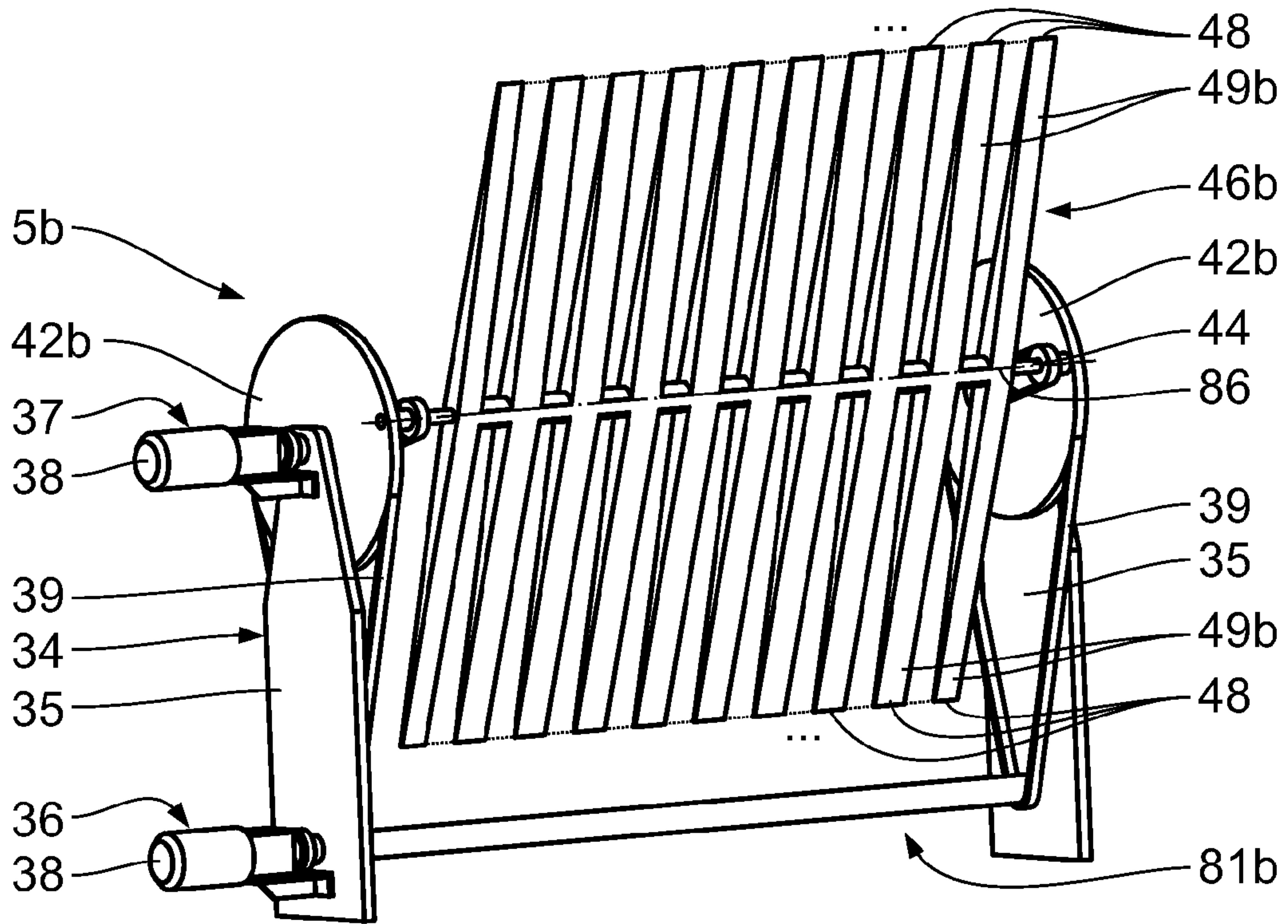


Fig. 11

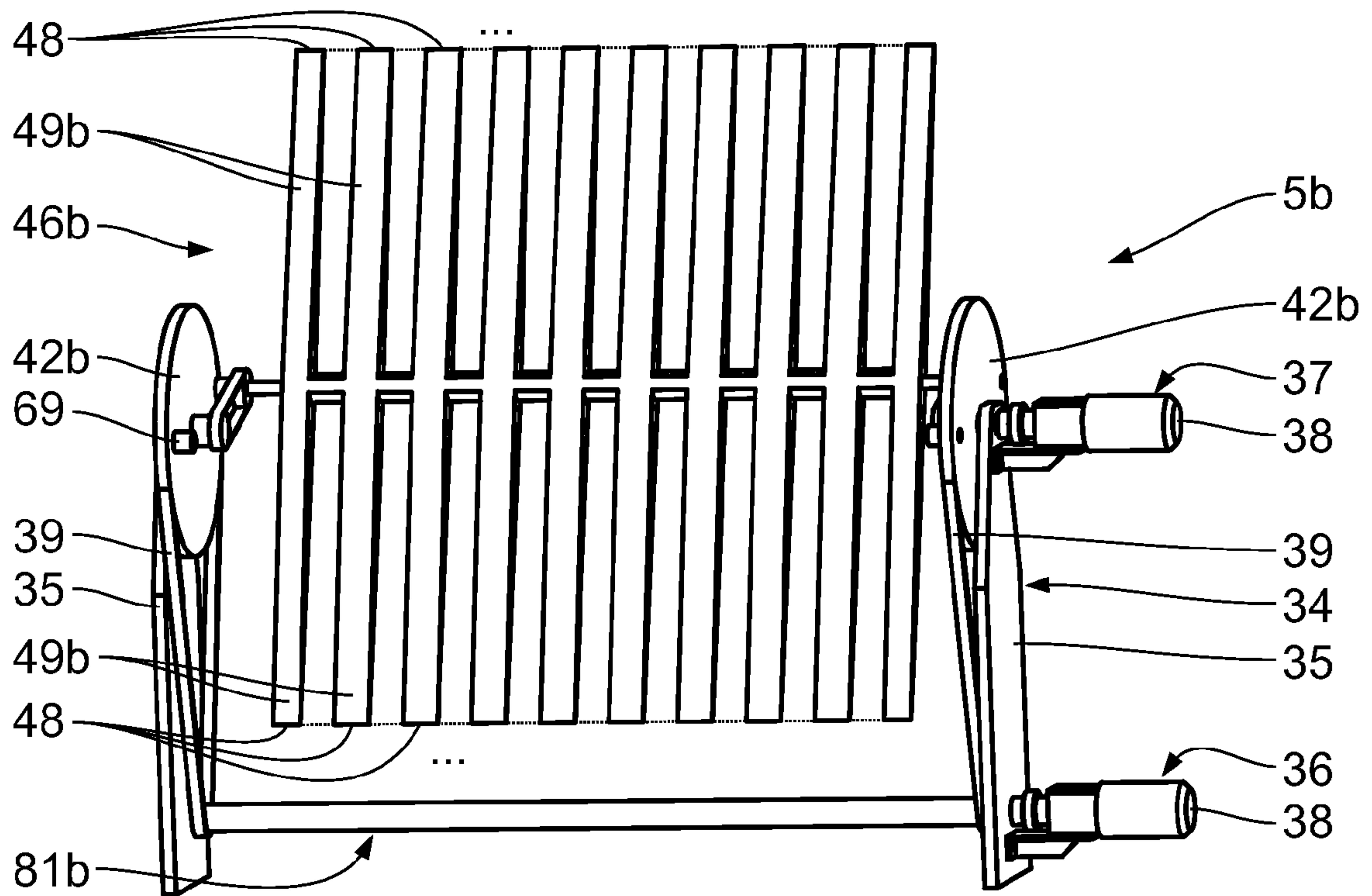


Fig. 12

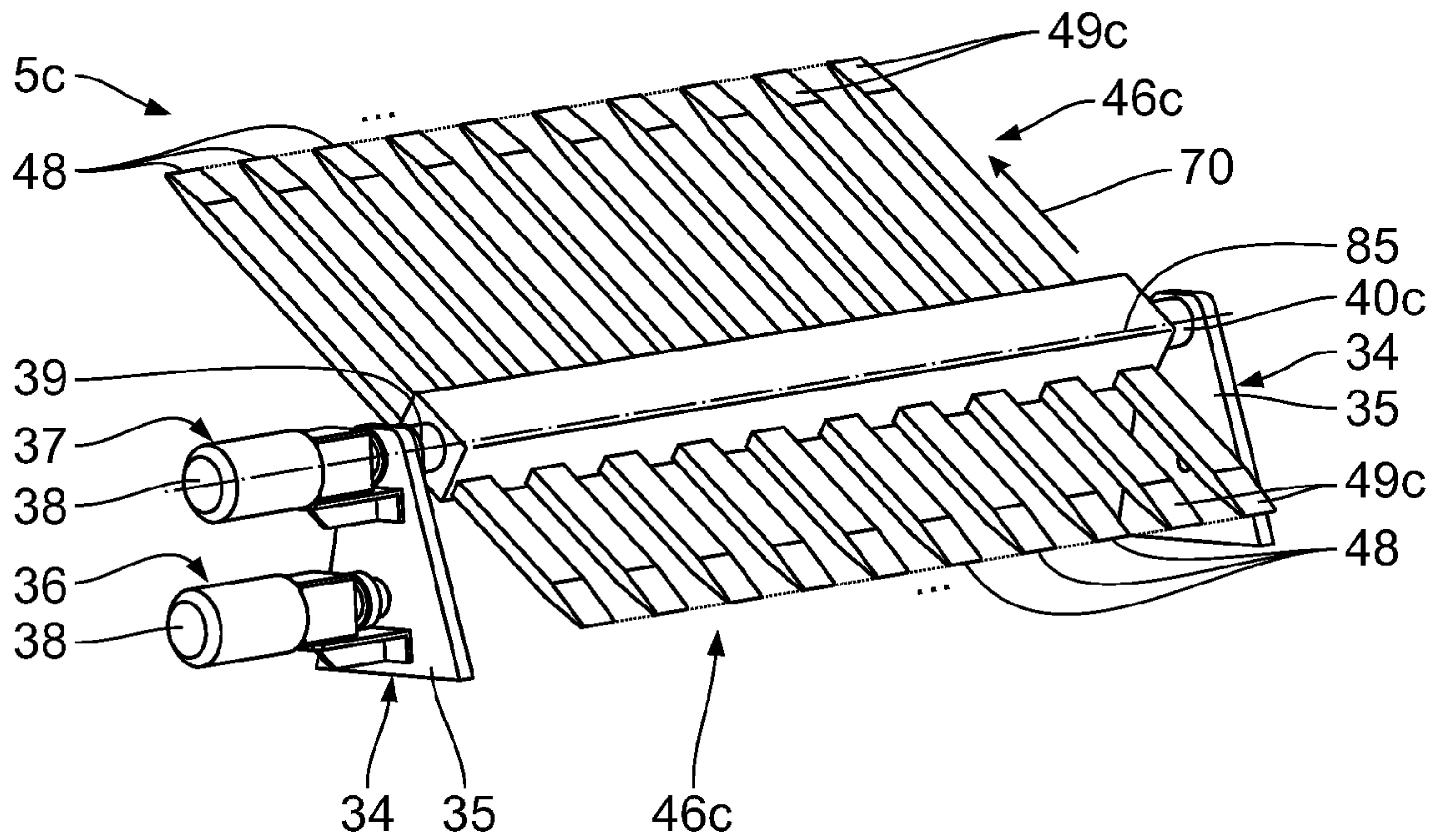


Fig. 13

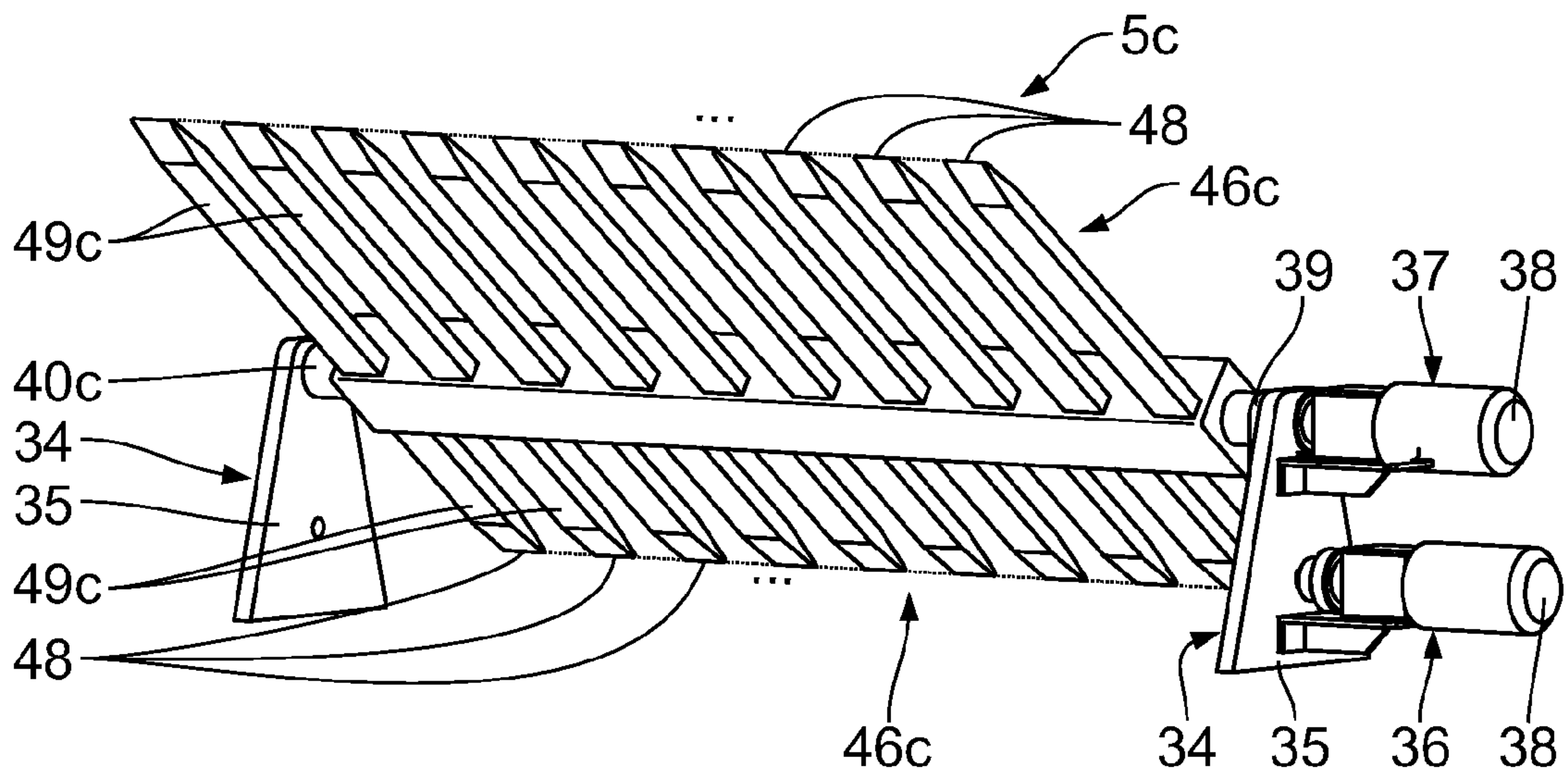


Fig. 14

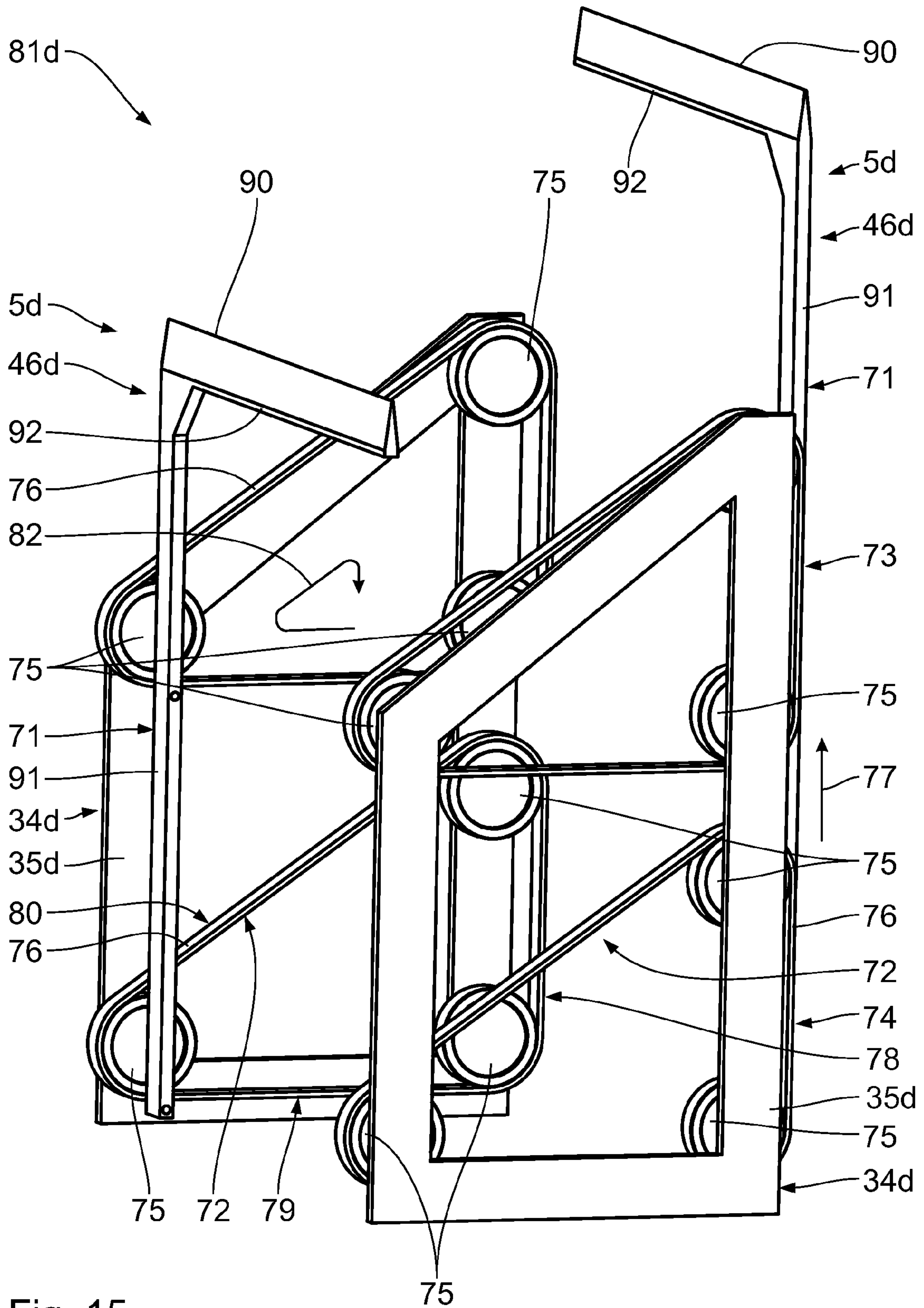


Fig. 15

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FOLDING DEVICE

BACKGROUND OF THE INVENTION

1. Field of the Invention

The invention relates to a device and a method for folding an endless web of corrugated cardboard.

2. Background Art

The production of corrugated cardboard usually takes place in a continuous process in which are generated endless webs. After production, these endless webs need to be stored in a suitable form. To this end, they are for instance folded. In particular when folding large-format webs of corrugated cardboard, this may lead to unwanted kinks in the webs.

SUMMARY OF THE INVENTION

It is therefore the object of the invention to provide a device and a method by means of which the folding of an endless web of corrugated cardboard is improved.

The gist of the invention is to arrange an engagement member comprising finger-shaped projections in a stand, the engagement member being movably mounted in such a way that the free ends of the finger-shaped projections are movable along a predetermined trajectory for folding the web of corrugated cardboard. In this process, the web of corrugated cardboard is lifted off a contact surface and thus folded along the finger-shaped projections.

Features and details of the invention will become apparent from the description of several embodiments by means of the drawings.

BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1 is a diagrammatic view of an installation for folding stacking and separating webs of corrugated cardboard according to a first embodiment;

FIG. 2 is a partial cross-section through the installation according to FIG. 1 in the region of the folding device, with the folding device being in a first position;

FIG. 3 is a view according to FIG. 2, with the folding device being in a second position;

FIG. 4 is a view according to FIG. 2, with the folding device being in a third position;

FIG. 5 is a detailed view of the folding device according to the first embodiment;

FIG. 6 is another view of the folding device according to FIG. 5;

FIG. 7 is a partial sectional view of the installation according to FIG. 1 in the region of the cutting and stacking device, with the cutting device being in a first position;

FIG. 8 is a view according to FIG. 7, with the cutting device being in a second position;

FIGS. 9 to 10 are views according to FIG. 5 and FIG. 6 of a second embodiment of a folding device;

FIGS. 11 to 12 are views according to FIG. 5 and FIG. 6 of a third embodiment of a folding device;

FIGS. 13 to 14 are views according to FIG. 5 and FIG. 6 of a fourth embodiment of a folding device; and

FIG. 15 is a view of a fifth embodiment of a folding device.

DESCRIPTION OF THE PREFERRED EMBODIMENTS

The following is a description of a first embodiment of the invention with reference to FIGS. 1 to 8. An installation 1 for the embossing, folding, stacking and cutting of endless webs

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2 of corrugated cardboard is arranged downstream, relative to a transport direction 3, of a device 60 for the production of corrugated cardboard, with the device 60 only being shown diagrammatically in the Figures. A device 60 of this type is for instance disclosed in DE 103 12 600 A1 to which reference is made. The web 2 of corrugated cardboard, which is produced by means of the device 60, may comprise substantially any desired number of layers. It has a thickness D.

The installation 1 comprises a squeezing device 4, a folding device 5, a cutting device 6 and a stacking device 7. The squeezing device 4 is arranged on a first platform 8 which is rigidly connected to the floor by means of a first frame 9.

Likewise, the folding device 5 is rigidly connected to the floor by means of a second frame 10. Finally, the stacking device 7 is rigidly connected to the floor by means of a third frame 11. Further attached to the third frame 11 is the cutting device 6. The second frame 10 may be connected to the first frame 9 and/or to the third frame 11. The frames 9, 10, 11 form a support framework 12 for the installation 1. The support framework 12 comprising the frames 9, 10, 11 permit a flexible modular layout of the installation 1.

The following is a more detailed description of the squeezing device 4. The squeezing device 4 comprises an insertion portion 13 with a support surface 14. In the region of the feed portion 13 are arranged two feed rollers 15. The feed rollers 15 are cylindrical and in each case mounted for rotation about a feed roller axis 16 which is perpendicular to the transport direction 3. The feed rollers 15 may in particular be drivable for rotation. The squeezing device 4 further comprises at least one pair of embossing rollers 17 which are in each case mounted for rotation about an embossing roller axis 18. The embossing rollers 17 are in particular drivable for rotation by means of a driving device which is not shown in the Figures. The drive is therefore advantageously actuated in intermittent cycles. The embossing roller axes 18 are parallel to each other and perpendicular to the transport direction 3. The embossing roller axes 18 are arranged vertically above each other. The distance between the embossing roller axes 18 is adjustable. Between the surfaces of the embossing rollers 17 is formed a through gap 89 with a free opening. The free opening of the through gap 89 is at least equal to the thickness D of the web 2 of corrugated cardboard. The free opening might be adjusted to the thickness D of the web 2 of corrugated cardboard in such a way that it is just large enough for the embossing rollers to be in frictional contact with the web 2 of corrugated cardboard without however deforming the web 2 of corrugated cardboard when passed through between the embossing rollers 17. The two embossing rollers 17 are at least largely identical. They have a circumference U in the range of 80 cm to 140 cm.

The surface of the embossing rollers 17 is in each case provided with one embossing member 19. The embossing member 19 is blunt and formed in the shape of a bar. It has an extension in the radial direction, in other words perpendicular to the surface of the embossing rollers 17, which is smaller than half of the free opening. The embossing member 19 is continuous. It may however also be in the shape of a rake, in other words it may be provided with gaps in-between. The embossing members 19 of the two embossing rollers 17 are arranged along the circumference of the embossing rollers 17 in such a way that they meet during each revolution of the embossing rollers 17 about the embossing roller axes 18. When the embossing members 19 meet, the free opening of the through-gap 89 is reduced to a value which is smaller than the thickness D of the web 2 of corrugated cardboard. The web 2 of corrugated cardboard is thus squeezable by means of the embossing members 19.

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The embossing members 19 are advantageously oriented parallel to the embossing roller axes 18 so as to create folds 20 in the web 2 of corrugated cardboard which are perpendicular to the transport direction 3 and therefore to the longitudinal direction of the web 2 of corrugated cardboard. The distance between two succeeding folds 20 is just equal to the circumference U of the embossing rollers 17. The folds 20 form predetermined bending points in the web 2 of corrugated cardboard along which the web 2 of corrugated cardboard is foldable particularly easily as a bending elasticity thereof is lower in the region of the folds 20 than in the region beyond the folds 20 so that the web 2 of corrugated cardboard bends particularly easily in the region of the folds 20.

Alternatively, it is conceivable to provide only one of the embossing rollers 17 with an embossing member 19. In this case, the circumference U of the embossing roller 17 without embossing member 19 need not fulfill particular requirements. It is virtually freely selectable and may in particular be different from the circumference U of the embossing roller 17 comprising the embossing member 19.

In another embodiment are provided embossing rollers 17 whose circumference U is just equal to an integral multiple of the desired distance between two succeeding folds 20 in the web 2 of corrugated cardboard. The surface of the embossing rollers 17 of this type is provided with a corresponding number of embossing members 19. The embossing members 19 are equally distributed across the circumference U of the embossing rollers 17, in other words the angular distance between in each case two adjacent embossing members 19 is in each case identical. An embossing roller 17, whose circumference U is n-times the distance between two succeeding folds in the web 2 of corrugated cardboard, therefore comprises n embossing members 19 which are in each case arranged at an angular distance of $360^\circ/n$ on the surface of the embossing roller 17.

The embossing rollers 17 are exchangeable. This allows for easy adjustment of the distance between two succeeding folds 20 in the web 2 of corrugated cardboard, with the distance just being equal to the circumference U of the embossing rollers 17.

Finally, the squeezing device 4 comprises a discharge portion 21 where discharge rollers 22 with discharge roller axes 23 are arranged parallel to the feed roller axes 16. The discharge roller 22 arranged underneath the web 2 of corrugated cardboard is part of a transport unit 24 which further comprises an endless conveyor belt 25.

The folding device 5 is arranged downstream of the squeezing device 4, in other words behind the squeezing device 4 when seen in the transport direction 3. The folding device 5 comprises a double table 26. The double table 26 comprises a lower table top 27 and an upper table top 28. The table tops 27, 28 are parallel to each other. They are spaced from each other in such a way that the web 2 of corrugated cardboard can be passed through between them. To this end, their distance is adaptable to the thickness D of the web 2 of corrugated cardboard.

The upper table top 28 has an oblong opening 29 which is substantially perpendicular to the transport direction 3. In the region of the opening 29, a drive roller 30 is mounted for rotary drive about a drive roller axis 31 in such a way that the web 2 of corrugated cardboard sliding on the lower table top 27 is in tangential contact with the drive roller 30. The drive roller axis 31 is oriented perpendicular to the transport direction 3, parallel to the axes 16, 18, 23.

Seen in the transport direction 3, the double table 26 is adjoined by a contact surface 32 on which the web 2 of corrugated cardboard is slidably disposed in the initial state.

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The contact surface 32 adjoins the lower table top 27 of the double table 26 in a continuous, stepless manner. The contact surface 32 comprises a bending point 33 from which the contact surface 32 slopes slightly downwards when seen in the transport direction 3. The contact surface 32 may also be curved.

The folding device 5 further comprises a folding unit 81 which is arranged below the contact surface 32. The folding unit 81 comprises a stand 34 which is arranged downstream of the double table 26. Seen in the transport direction 3, the stand 34 is arranged at a distance from the downstream end of the double table 26 which is at least equal to, in particular at least one and a half times, in particular at least twice the distance between two adjacent folds 20 in the web 2 of corrugated cardboard. The stand 34 comprises two retaining members 35 which are arranged opposite to each other when seen perpendicular to the transport direction 3 of the web 2 of corrugated cardboard. On one of the retaining members 35 is disposed a first driving device 36 and a second driving device 37. The driving device 36, 37 comprises in each case one electric motor 38. Via a first belt 39, the electric motor 38 of the first driving device 36 is coupled to a torque transmission member which is configured as a first folding device shaft 40. The first folding device shaft 40 is mounted for rotation about a first axis 85 in the stand 34. The first axis 85 is oriented perpendicular to the transport direction 3, parallel to the axes 16, 18, 23 and 31. It is arranged at a distance A_1 from the contact surface 32.

The first folding device shaft 40 is part of a frame 41 which is pivotally mounted in the stand 34 by means of said first folding device shaft 40. The frame 41 further comprises two side parts 42 which are arranged in the end regions of the first folding device shaft 40 and are rigidly connected to the first folding device shaft 40. The side parts 42 are oriented parallel to the transport direction 3. The side parts 42 thus form arms which are perpendicular to the first folding device shaft 40.

In an end region 43 of the side parts 42, an engagement member 46 is mounted for rotation about a second axis 86. The second axis 86 is parallel to the first axis 85. It is arranged at a distance A_2 from said first axis 85. The engagement member 46 is coupled to the electric motor 38 of the second driving device 37 by means of a second belt 45 via a second torque transmission member 44. According to the embodiment shown in FIGS. 5 and 6, the second torque transmission member 44 is a stepped belt pulley which is mounted in the frame 41 on one side. On the side of the frame 41 opposite to the belt pulley, the engagement member 46 is mounted in the side part 42 by means of a pin 87. It is generally conceivable as well to provide a second folding device shaft instead of the belt pulley and the pin 87. The engagement member 46 is designed in the manner of a comb. It comprises a crossbar 47 which is oriented along the second axis 86, with a plurality of oblong, finger-shaped projections 49 being connected to said crossbar 47 which taper at their free ends 48 in the manner of the teeth of a comb. Measured from the second axis 86 to their free ends, the projections 49 have a length L_F . The length L_F is preferably no greater than the sum of the distance A_1 of the first axis 85 from the contact surface 32 and of the distance A_2 of the second axis 86 from the first axis 85:

$$L_F \leq A_1 + A_2.$$

By means of the frame 41, the engagement member 46 is pivotable about the first axis 85 in the stand 34 and about the second axis 86 in the frame 41. The engagement member 46 therefore has two degrees of freedom, in particular two degrees of rotational freedom. By varying and adapting the drive characteristics of the engagement member 46 about the

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two axes **85** and **86** in a suitable manner, a plurality of different web lengths can be folded without having to change the engagement member **46**. The engagement member **46** is at least virtually rigid. It is for instance at least partially, in particular fully of metal.

The stand **34** is adjustable in the vertical direction. The relative position of the stand **34** on which the engagement member **46** is held is therefore adjustable relative to the contact surface **32**.

The electric motors **38** are actuatable by a control unit which is not shown in the Figures. When the electric motors **38** are suitably actuated, the engagement member **46** is movable in such a way that the free ends **48** of the projections **49** may describe a randomly selected trajectory in a folding region about the stand **34**, the trajectory being parallel to the transport direction **3**. The free ends **48** of the projections **49** are in particular movable along a linear, in other words straight and/or curved path at an angle to the contact surface **32**. The web **2** of corrugated cardboard is thus liftable off the contact surface **32** by means of the engagement member **46** of the folding unit **81**, with the free ends **48** of the projections **49** forming an interrupted contact edge **90** on which the web **2** of corrugated cardboard is disposed, the contact edge **90** being engageable with the web **2** of corrugated cardboard.

In a region about the stand **34**, the contact surface **32** is provided with perforations in the manner of a grating, with the grating being oriented along the transport direction **3** to allow the engagement member **46** to reach through the contact surface **32**.

The stacking device **7** with the cutting device **6** is arranged downstream of the folding device **5**. The stacking device **7** comprises at least one guide member **50** configured as a slide surface on which stacks **51**, which have been folded by the folding device **5**, are transported along a predetermined path. The term transport also refers to the automatic sliding of the stacks **51** along the guide member **50** due to the gravitational force. The guide member **50** is arranged at an angle relative to the horizontal, thus forming an inclined plane on which the stack **51** slides. The guide member **50** comprises a first transition portion **52** facing the folding device **5**, a cutting portion **53** adjoining the transition portion **52** in the transport direction **3**, and a removal portion **54**. The abutting portions **52** and **53** as well as **53** and **54** are in each case pivotally interconnected by means of a first joint **55** or a second joint **56**, respectively. The portions **52**, **53** and **54** have a steepness which increases in the transport direction **3**. The guide member **50** therefore has a convex shape. The guide member **50** may in particular also be at least partially curved, in particular in the shape of a segment of a circular arc. This ensures that when depositing the stack **51**, the folds **20** abutting the guide member **50** are closer together than folds **20** located outside. This facilitates a damped and precise deposition of the folded stacks **51**. The guide member **50** may advantageously be a belt conveyor device comprising a conveyor belt extending across all of the three portions **52**, **53** and **54** as well as a drive unit.

The cutting portion **53** is arranged at an angle **b** relative to the horizontal. The inclination of the cutting portion **53** is adjustable by means of an adjustment member **57**. The adjustment member **57** is disposed on the third frame **11**. The adjustment member **57** is in particular hydraulically or electrically actuatable. In a simpler embodiment, the adjustment member **57** may also be manually operable. An adjustment of the inclination of the cutting portion **53** may be compensated for by pivoting the transition portion **52** relative to the cutting portion **53** by means of the first joint **55** in such a way that the guide member **50** forms a continuous, in other words a sub-

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stantially stepless transition to the contact surface **32** of the folding device **5**, regardless of the inclination of the cutting portion **53**. To this end, the transition portion **52** has an adjustable inclination as well.

The stacking device **7** further comprises several stop arms **58**. The stop arms **58** serve as end stop and stacking surface for the stacks **51** of corrugated cardboard. The stop arms **58** are displaceable along the guide member **50**. The stop arms **58** are oriented perpendicular to the surface of the guide member **50**. They are lowerable in a manner known to those skilled in the art, i.e. they are for instance foldable inwardly and outwardly or extendable and retractable.

The removal portion **54** is at least approximately vertical, in particular vertically oriented, in other words it forms an angle **c** with the horizontal which is in the range of 80° to 90° . A value of the angle **c** of less than 90° ensures that the stacks **51** of corrugated cardboard reliably abut the guide member **50** even in the region of the removal portion **54**, thus preventing the stacks **51** of corrugated cardboard from accidentally sliding off the stop arms **58**.

The cutting device **6** is arranged parallel to the cutting portion **53** of the guide member but offset thereto. The cutting device **6** comprises a support structure **61** which is connected to the third frame **11** in such a way as to be pivotable about a support structure axis **62** extending perpendicular to the transport direction **3**. Instead of pivotally mounting the support structure **61** to the frame **11**, the support structure **61** may alternatively also be connected directly to the stacking device **7**, in particular to the cutting portion **53** of the guide member **50** of the stacking device **7**. This ensures a particularly simple way of orienting the support structure **61** parallel to the cutting portion **53**. A hydraulically operable cutting unit **63** is arranged on the support structure **61**. The cutting unit **63** is displaceable on the support structure **61** parallel to the cutting portion **53** of the guide member **50** of the stacking device **7**. The cutting unit **63** is advantageously displaceable synchronously with the stop arms **58** which are displaceable along the guide member **50**.

The cutting unit **63** comprises a displacement mechanism **64** which is oriented perpendicular to the support structure **61**. The displacement mechanism **64** is advantageously a hydraulic cylinder, in particular a single-acting hydraulic cylinder with a spring return member. The hydraulic cylinder may alternatively also be a double-acting hydraulic cylinder. The hydraulic cylinder is advantageously a telescopic cylinder comprising at least 2, in particular at least 3 cylinders which are arranged inside one another. Alternative embodiments of the displacement mechanism **64** are conceivable as well.

On the displacement mechanism **64** is arranged a cutting member **65**. By means of the displacement mechanism **64**, the cutting member **65** is displaceable perpendicular to the support structure **61** and therefore perpendicular to the cutting portion **53** of the guide member **50**.

The displacement mechanism **64** is dimensioned such that the cutting member **65** has a displaceability perpendicular to the support structure **61** which is greater than the maximum expected distance of two adjacent folds **20** in the web **2** of corrugated cardboard. The cutting member **65** has a total length **L** in the displacement direction perpendicular to the support structure **61**. For easy cutting of the web **2** of corrugated cardboard, the guide member **50** is provided with at least one reception groove **88** in a particular region of the cutting portion **53** for receiving the cutting member **65**. The reception groove **88** has a depth **T** which is smaller than the length **L** of the cutting member **65**. In a direction parallel to the surface of the guide member **50**, the reception groove **88**

has a free opening which is considerably smaller than the thickness of the web 2 of corrugated cardboard.

The cutting member 65 extends in the direction of the support structure axis 62 along the entire width of the web 2 of corrugated cardboard. Seen perpendicular thereto and perpendicular to its longitudinal direction, the cutting member 65 has a thickness S which amounts to no more than 5 cm, in particular less than 3 cm, in particular less than 1 cm. The cutting member 65 is in particular an aluminum cutting plate with a steel cutting blade. The cutting plate advantageously comprises longitudinal holes. The cutting member 65 has a sufficient transverse stiffness, allowing the cutting member 65 to at least temporarily take over the support function of the stop arms 58. The cutting member 65, in particular the blade thereof, is exchangeable. Consequently, the properties of the cutting member 65, in particular the thickness S thereof, are adaptable to the properties of the respectively produced web 2 of corrugated cardboard, for instance to the thickness D, the number of layers and the surface quality thereof. Due to its low thickness S, the cutting member 65 is particularly easily insertable into the stack 51 between two portions of the web 2 of corrugated cardboard which are disposed on top of each other in the stack 51. The support structure 61, which is pivotable about the support structure axis 62, may ensure that by means of the displacement mechanism 64, the cutting member 65 is displaceable parallel to the portions of the web 2 of corrugated cardboard which are disposed on top of each other in the stack 51.

In an alternative embodiment, a stop member is provided instead of the cutting member 65, the stop member being displaceable by means of the displacement mechanism 64. Instead of the cutting blade, the stop member advantageously comprises a groove. In this embodiment, a circular knife is provided for separating the stacks 51 from the upstream web 2 of corrugated cardboard. The circular knife is connected to the third frame 11 by means of a guide. The guide is advantageously a crossbar extending perpendicular to the transport direction 3. A detailed description thereof can be found in paragraph [0021] of DE 10 2007 049 422 A1. When separating the stacks 51 from the upstream web 2 of corrugated cardboard, the circular knife cooperates with the stop member. The circular knife advantageously engages into the groove of the stop member.

Once separated from the web 2 of corrugated cardboard by means of the cutting device 6, the stacks 51 are removable from the removal portion 54 by means of a removal device 66 for further transport and for storage, the removal device 66 only being shown diagrammatically in the Figures.

The following is a description of the function of the installation 1. In the device 60, the webs 2 of corrugated cardboard are produced according to a method which is for instance disclosed in DE 103 12 600 A1. To this end, one or several linerboards are connected to one or several corrugated boards by means of a method which is known to those skilled in the art. A detailed description of this method can for instance be found in DE 43 05 158 A1.

In a first step, the endless web 2 of corrugated cardboard exiting the device 60 is provided with embossings in the squeezing device 4. To this end, the web 2 of corrugated cardboard is passed through between the two embossing rollers 17. After in each case one full revolution of the embossing rollers 17, in other words when the circumference U thereof has rolled off on the web 2 of corrugated cardboard exactly once, the two embossing members 19 meet, thus causing the free opening of the through-gap 89 between the embossing rollers 17 to be reduced to a value A_{S2} which is smaller than the thickness D of the web 2 of corrugated cardboard so that

the fold 20 is embossed into the web 2 of corrugated cardboard which is just being passed through between the embossing members 19. To this end, the actuation of the embossing rollers 17 and/or the arrangement of the embossing members 19 on said embossing roller 17 are precisely matched to each other. This applies accordingly if the embossing rollers 17 comprise several embossing members 19. It is apparent that when each embossing roller 17 is provided with n embossing members 19, the web 2 of corrugated cardboard will be provided with n folds 20 per each revolution of the embossing rollers 17. It is generally conceivable as well to provide a sharp-pointed embossing member 19, causing the web 2 of corrugated cardboard passing through the squeezing device 4 to be perforated during each revolution of the embossing rollers 17. What is essential is that web 2 of corrugated cardboard is still in one piece even after passing through the squeezing device 4 in the transport direction 3.

In an alternative embodiment, the actuation of the embossing rollers 17 is independent from the feed speed of the web 2 of corrugated cardboard, and is in particular actuatable in intermittent cycles.

By means of the transport unit 24, the embossed web 2 of corrugated cardboard is transported on to the double table 26. In the double table 26, the web 2 of corrugated cardboard is transported on to the contact surface 32 of the folding device 5 by means of the driving roller 30 in such a way as to be protected against deflections perpendicular to the transport direction.

The following is a more detailed description of the folding process in the folding device 5. In the initial state, the web 2 of corrugated cardboard slides on the contact surface 32 in the folding device 5. When the web 2 of corrugated cardboard has been transported in the transport direction 3 at least until at least two folds 20 in the web 2 of corrugated cardboard are disposed in the region between the stand 34 and the discharge end of the double table 26, the engagement member 46 of the folding device 5 is pivoted in the stand 34 by means of the folding device shafts 40, 44 in such a way that the free ends 48 of the projections 49 engage with the web 2 of corrugated cardboard from below, namely exactly in the region of one of the folds 20. The free ends 48 hit the fold 20 with a tolerance of no more than 10 cm, in particular no more than 5 cm, in particular no more than 3 cm. When the free ends 48 hit the fold 20, said fold 20 has advantageously just reached the bending point 33 of the contact surface 32. This facilitates a folding of the web 2 of corrugated cardboard along the folds 20. Furthermore, when the free ends 48 hit the web 2 of corrugated cardboard, the fold 20 that is adjacent to the fold 20, which is in contact with the free ends 48, in the upstream direction is advantageously located at a few centimeters downstream of the downstream end of the double table 26.

When the engagement member 46 is pivoted even further, the web 2 of corrugated cardboard is lifted off the contact surface 32 in the region of the fold 20 by means of the engagement member 46. When this happens, the projections 49 of the engagement member 46 reach through the contact surface 32. During this pivoting movement, the portion of the web 2 of corrugated cardboard in the region of the fold 20 is in contact with the free ends 48 of the projections 49, the free ends 48 forming the contact edge, and is slightly extended in the region between this fold 20 and the downstream end of the double table. Due to the gravitational force, the web 2 of corrugated cardboard remains in contact with the contact surface 32 in the region of the downstream fold 20 that is adjacent to the fold 20 which is in contact with the contact edge. On the upstream side, the web 2 of corrugated card-

board is held on the contact surface 32 by the double table 26 which prevents a deflection of the web 2 of corrugated cardboard perpendicular to the transport direction 3. The web 2 of corrugated cardboard is thus folded along the fold 20 which is in contact with the contact edge.

The engagement member 46 is pivoted in the stand 34 by means of the driving devices 36 and 37 until the projections 49 form an angle d with the contact surface 32 which for instance amounts to at least 70° , in particular at least 80° . In a particular advantageous embodiment, the projections 49 are designed such that the portion of the web 2 of corrugated cardboard between the fold 20, which is in contact with the free ends 48 of the projections, and the adjacent downstream fold 20 at least largely abuts the projections 49. This prevents the web 2 of corrugated cardboard from sagging in the region between two folds 20.

In this stage of the folding process shown in FIG. 3, the engagement member 46 is located between two folded portions 67 of the web 2 of corrugated cardboard which are in each case bounded by folds 20 and form an acute angle e of no more than 40° , in particular no more than 20° , at the fold 20 connecting the folded portions 67.

The engagement member 46 is moved down and out of the gap between the folded portions 67 by pivoting the engagement member 46 about the two axes 85 and 86 in a suitable manner. The engagement member 46 is in particular pivoted about the second axis 86 in the frame 41 in a direction opposite to the pivoting direction of the frame 41 about the first axis 85 in the stand 34.

On the downstream end of the folding device 5, the folded web 2 of corrugated cardboard automatically reaches the transition portion 52 of the stacking device 7 due to the gravitational force on the contact surface 32. Due to the increasing inclination of the guide member 50 of the stacking device 7, the folded portions 67 of the folded web 2 of corrugated cardboard are increasingly pressed together when sliding down the guide member 50, causing them to be aligned parallel to each other. As in each case one of the folds 20 bounding the folded portions 67 is in contact with the guide member 50 of the stacking device 7 during the entire stacking process, the stacks 51 are aligned in a very precise, flush manner. A free falling of the folded web 2 of corrugated cardboard, which may result in a reduced precision and, in the worst case, in unwanted kinks, is avoided according to the invention. The in each case lowermost folded portion 67 of a stack 51 is disposed on the stop arms 58 projecting perpendicular to the guide member 50.

The stop arms 58 are displaced along the guide member 50 depending on the size of the stack 51. As soon as a desired number of folded portions 67 is obtained in the stack 51, which may easily be indicated on the guide member 50 by the position of the stop arms 58 on which the stack 51 is disposed, the cutting device 6 is actuated. When this happens, the cutting unit 63 on the support structure 61 is at first moved parallel to the cutting portion 53 of the guide member 50 to the desired position in order to adjust the stack height. The cutting device 6 is advantageously actuated automatically. It is for instance actuated by a control member 68 (only shown diagrammatically in the Figures) which is connected for signal transmission with at least one of the stop arms 58 and the cutting device 6. After triggering the displacement mechanism 64 which is at first in a position in which the cutting member 65 is out of engagement with the stack 51 on the cutting portion 53 of the guide member 50 of the stacking device 7, the cutting member 65 is inserted into the stack 51 between two adjacent folded portions 67 by means of the displacement mechanism 64. The cutting member 65 is dis-

placed parallel to the folded portions 67 by means of the displacement mechanism 64 until the stack 51 in the region of a fold 20 lying on the guide member 50 is separated from the upstream web 2 of corrugated cardboard. The convex shape of the guide member 50 facilitates an insertion of the cutting member 65 between two adjacent folded portions 67. This prevents damage to the web 2 of corrugated cardboard.

The cutting unit 63 is displaced synchronously with the stop arms 58 on which the stack 51 is disposed while the cutting member 65 is being inserted into the stack 51. This avoids unfavorable transverse loads of the cutting member 65.

As soon as the stack 51 is separated from the upstream web 2 of corrugated cardboard, the stack 51 lying on the stop arms 58 is moved at increased speed along the guide member 50 into the removal portion 54. The subsequent upstream stack 51 is temporarily in contact with the cutting member 65 which has separated the web 2 of corrugated cardboard. In other words, the cutting member 65 temporarily takes over the function of the stop arms 58. Meanwhile, further stop arms 58 are provided for placing the next stack 51 onto the guide member 50. In order to support the stack 51, these stop arms 58 are moved along the guide member 50 towards the cutting member 65 on the side thereof opposite to the stack lying on the cutting member 65. Afterwards, the cutting member 65 is retracted from the guide member 50 along the displacement direction by means of the displacement mechanism 64; when it is no longer in engagement with the stack 51, the cutting member 65 is moved back along the support structure 61 into its initial position. In this position, the cutting device 6 is ready for the next cutting process which advantageously takes place without interruption immediately after the preceding cutting process.

The cooperation of the stacking device 7 with the cutting device 6 thus ensures a continuous, interruption-free stacking and cutting of stacks 51 with folded portions 67 of a folded web 2 of corrugated cardboard. In an alternative embodiment, it is provided to displace the stop arms 58 along the guide member 50 in intermittent cycles. In this embodiment, the stop arms 58 stand still during the cutting process, in other words while the cutting member 65 is being inserted into the stack 51. A displaceability of the cutting unit 63 along the support structure 61 can therefore be dispensed with, which reduces the effort required for constructing the cutting device 6.

Once folded and separated from the web 2 of corrugated cardboard, the stacks 51 are removed from the removal portion 54 of the stacking device 7 by means of the removal device 66 for further storage and for transport.

The following is a description of another embodiment of the folding device 5a with reference to FIGS. 9 and 10. Identical parts have the same reference numerals as in the first embodiment to the description thereof reference is made. Differently constructed but functionally identical parts have the same reference numerals with a subsequent a. The main difference with respect to the first embodiment is that the side parts 42a of the frame 41a of the folding unit 81a are circular. The second torque transmission member 44 and the pin 87 are mounted at the circumference, in other words eccentrically, in these circular side parts 42a. The electric motor 38 of the second driving device 37 on the other hand is arranged in the region of the axis passing through the central points of the circular side parts 42a. Moreover, a pin-shaped stop member 69 is provided on the side parts 42a. In order to prevent torsional forces, it is advantageous to arrange electric motors 38 and torque transmission members 44 on both sides of the stand 34, in other words on both retaining members 35.

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The following is a description of a third embodiment of the folding device **5b** with reference to FIGS. **11** and **12**. Identical parts have the same reference numerals as in the preceding embodiments to the description thereof reference is made. Differently constructed but functionally identical parts have the same reference numerals with a subsequent b. The main difference with respect to the second embodiment is that the engagement member **46b** of the folding unit **81b** is symmetric to the second axis **86**. The second torque transmission member **44** is advantageously a second folding device shaft in this embodiment. The finger-shaped projections **49b** extend in each case from the second folding device shaft **44** in opposite directions. The engagement member **46b** is thus symmetric to the second axis **86**. A rotation of the engagement member **46b** through 180° about the second axis **86** converts the engagement member **46b** into itself. In other words, the engagement member **46b** has a plurality of free ends **48** on both sides of the second axis **86** which can be used for folding the web **2** of corrugated cardboard. This reduces the pivoting radius of the engagement member **46b** required for folding the web **2** of corrugated cardboard, thus reducing in particular the time required for returning the engagement member **46b** into the initial position, and therefore the time between two folding processes.

The following is a description of a fourth embodiment of the folding device **5c** with reference to FIGS. **13** and **14**. Identical parts have the same reference numerals as in the first embodiment to the description thereof reference is made. Differently constructed but functionally identical parts have the same reference numerals with a subsequent c. The main difference with respect to the first embodiment is that the folding unit **81c** comprises only one folding device shaft **40c** for pivoting the engagement member **46c** in the stand **34**. The engagement member **46c** has therefore only one degree of rotational freedom. The finger-shaped projections **49c** are however mounted in the stand **34** for displacement along the folding device shaft **40c** in and opposite to their longitudinal direction **70**. The engagement member **46c** therefore has an additional degree of translational freedom. A gear mechanism (not shown in the Figures), which is drivable by means of the second electric motor **38**, is provided for displacing the projections **49c** perpendicular to the folding device shaft **40c**. The finger-shaped projections **49c** comprise in each case two free ends **48**. The free ends **48** have in each case a flat shape. The use of both sides is therefore advantageous. In this embodiment, the length L_F of the finger-shaped projections **49c** is freely selectable.

The following is a description of a fifth embodiment of the folding device **5d** with reference to FIG. **15**. Identical parts have the same reference numerals as in the first embodiment to the description thereof reference is made. Differently constructed but functionally identical parts have the same reference numerals with a subsequent d. In this embodiment, two engagement members **46d** are mounted for parallel displacement in the stand **34d** of the folding unit **81d**.

The engagement member **46d** comprises in each case one L-shaped guide arm **71**. The L-shaped guide arm **71** comprises two limbs **91**, **92** which are perpendicular to each other. The first limb **91** serves for mounting the L-shaped arm **71** to the stand **34d** while the second limb **92** forms the contact edge **90**. The guide arm **71** is in each case connected for displacement with one of the retaining members **35d** of the stand **34d** by means of a belt system **72**. The retaining members **35d** of the stand **34d** are trapezoidal. They are advantageously provided with cut-outs and therefore form only a rigid retaining frame. A solid and/or rectangular design of the retaining members **35d** is of course conceivable as well.

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The belt system **72** comprises an upper partial belt system **73** and a lower partial belt system **74**. The lower partial belt system **74** comprises three rolls **75** on each of the two retaining members **35d**. A belt **76** is in each case passed over the rolls **75**. The rolls **75** are mounted for rotation on the stand **34d**.

At least one of the rolls **75** on each of the retaining members **35d** is drivable for rotation. The rolls **75** on the two retaining members **35d** of the lower partial belt system **74** are in particular synchronized with each other. The driving device **36**, which is not shown in FIG. **15**, is provided for driving the rolls **75**. The driving speed of the lower partial belt system **74** is equal to that of the upper partial belt system **73**. The partial belt systems **73**, **74** are advantageously driven synchronously. Their driving speed is adaptable to the feed speed of the web **2** of corrugated cardboard. The lower partial belt system **74** comprises a vertical portion **78**, a horizontal portion **79** and a diagonal portion **80**.

The upper partial belt system **73** is parallel to the lower partial belt system **74** but offset relative thereto in an offset direction **77**, in particular in the vertical direction. It is at least largely identical to the lower partial belt system **74** to the description thereof reference is made.

Two points of the guide arm **71** are connected to in each case one of the belts **76** of the upper partial belt system **73** and to one of the belts **76** of the lower partial belt system **74**. As a result, each guide arm **71** is in each case connected to one of the retaining members **35d** by means of the upper and lower partial belt system **73**, **74** via points disposed vertically above one another, thus ensuring that the guide arm **71** is mounted in the stand **34d** in a tilt-free, parallelly displaceable manner. The engagement members **46d** are movable past each other when displaced in the stand **34d** by means of the belt system **72**.

The connection points between the guide arm **71** and the belt system **72** are oriented such that the engagement member **46d** is oriented parallel to the offset direction **77**. By means of the belt system **72**, the engagement member **46d** is cyclically displaceable along the vertical portion **78**, the horizontal portion **79** and the diagonal portion **80** in a first direction of rotation **82**.

The folding unit **81d** is advantageously arranged such that the contact edge **90** is disposed slightly below the web **2** of corrugated cardboard, in particular slightly below the contact surface **32** when the engagement member **46d** is displaced along the horizontal portion **79**.

In this embodiment, the folding device **5d** may comprise a second folding device **81d** which is arranged above the web **2** of corrugated cardboard. The second folding unit **81d** is mirror-symmetric to the folding unit **81d** which will hereinafter be referred to as first folding unit **81d**. The symmetry plane is horizontal. The second folding unit **81d** is arranged above the web **2** of corrugated cardboard in such a way that the lowest point of the contact edge **90** is disposed just above the contact surface **32** and presses the web **2** of corrugated cardboard against the contact surface **32**. The second folding unit **81d** is height-adjustable in the vertical direction as well. The second folding unit **81d** is at least slightly arranged offset relative to the first folding unit **81d** when seen in the transport direction **3** of the web **2** of corrugated cardboard. It is in particular arranged downstream of and adjacent to the first folding unit **81d**. Alternatively, an overlapping arrangement of the folding units **81d** may be advantageous as it results in an improved folding of the web **2** of corrugated cardboard.

The belt systems **72** of the folding units **81d** are synchronized with each other.

For folding the web **2** of corrugated cardboard, the contact edge **90** of the engagement member **46d** of the first folding unit **81** is brought into engagement with one of the folds **20** in the web **2** of corrugated cardboard from below. A suitable control device ensures that the contact edge **90** comes into engagement with in each case one of the folds **20**.

Afterwards, the engagement member **46d** is displaced obliquely parallel to the contact surface **32** along the diagonal portion **80** by means of the belt system **72**. This causes the web **2** of corrugated cardboard to be lifted and folded down in the region of the fold **20** lying on the contact edge **90**. At the same time, the engagement member **46d** of the second folding unit **81d** is displaced obliquely downwards along the diagonal portion **80**. When this happens, the contact edge **90** comes into engagement with the fold **20** in the web **2** of corrugated cardboard which is adjacent to the fold **20** in the downstream direction and lies on the contact edge **90** of the first folding unit **81d**, thus ensuring that this fold **20** is in contact with the contact surface **32**. As a result, the web **2** of corrugated cardboard is precisely folded along the folds **20**, namely alternately up and down.

When the engagement members **46d** are displaced along the vertical portions **78**, the limbs **92** of the folding units **81d** are in each case removed from the region between two folded portions **67**.

Finally, the engagement members **46d** of the folding units **81d** are returned to their initial positions along the horizontal portions **79**.

What is claimed is:

1. A device for folding an endless web (**2**) of corrugated cardboard, the device comprising:
 - a. a contact surface (**32**) for supporting the web (**2**) of corrugated cardboard in a sliding manner, wherein the contact surface (**32**) comprises a bending point (**33**), from which the contact surface (**32**) slopes slightly downwards, when seen in a transport direction (**3**) of the web (**2**) of corrugated cardboard;
 - b. a stand (**34; 34d**) located below the contact surface (**32**) comprising two retaining members (**35; 35d**);
 - c. at least one engagement member (**46; 46b; 46c; 46d**) which is mounted in the stand (**34; 34d**) and comprises at least one projection (**49; 49b; 49c**) which comprises at least one free end (**48**) forming a contact edge; and
 - d. at least one driving device (**36, 37**) located below the contact surface (**32**) for moving the at least one engagement member (**46; 46b; 46c; 46d**);
 - e. with the at least one engagement member (**46; 46b; 46c; 46d**) being movably mounted in the stand (**34; 34d**) in such a way that the contact edge is movable at an angle relative to the contact surface (**32**) along a predetermined trajectory so as to bring the contact edge into engagement with the web (**2**) of corrugated cardboard sliding on the contact surface (**32**),
 - f. wherein the device is configured such that the web (**2**) of corrugated cardboard is lifted off the contact surface (**32**) by the at least one projection (**49, 49b, 49c**) and is folded along the at least one projection (**49, 49b, 49c**), and wherein, when the at least one free end (**48**) hits a fold (**20**) created in the web (**2**) of corrugated cardboard, said fold (**20**) has just reached the bending point (**33**) of the contact surface (**32**);
 - g. wherein in a region about the stand (**34**) the contact surface (**32**) is provided with perforations in a manner of a grating;
 - h. wherein the grating is oriented along a transport direction (**3**) to allow the engagement member (**46**) to reach through the contact surface (**32**).

2. A device according to claim **1**, wherein the engagement member (**46; 46b; 46c; 46d**) has two degrees of freedom.

3. A device according to claim **2**, wherein the engagement member (**46; 46b; 46c; 46d**) has two degrees of rotational freedom

4. A device according to claim **1**, wherein the engagement member (**46; 46b; 46c; 46d**) comprises a plurality of finger-shaped projections (**49; 49b; 49c**).

5. A device according to claim **1**, wherein the engagement member (**46; 46b; 46c**) is pivotable about at least one axis (**85; 86**) in order to bring the engagement member (**46; 46b; 46c**) into engagement with the web (**2**) of corrugated cardboard, with the axis (**85; 86**) being arranged at a distance **A1** from the contact surface (**32**).

6. A device according to claim **5**, wherein the engagement member (**46b; 46c**) comprises at least one projection (**49b; 49c**) on both sides of at least one of the axes (**85; 86**).

7. A device according to claim **6**, wherein the engagement member (**46b**) is symmetric to the axis (**86**).

8. A device according to claim **5**, wherein the at least one projection (**49c**) is mounted in the stand (**34**) for displacement perpendicular to the axis (**85**).

9. A device according to claim **1**, wherein the free end (**48**) of the at least one finger-shaped projection (**49; 49b; 49c**) has a flattened shape.

10. A device according to claim **1**, wherein the at least one driving device (**36, 37**) comprises an electric motor (**38**).

11. A device according to claim **10**, further comprising a control unit for actuating the electric motor (**38**).

12. A device according to claim **11**, wherein the electric motor (**38**) is actuated such that the at least one engagement member (**46; 46b; 46c; 46d**) is movable in such a way that the at least one free end (**48**) describes a randomly selected trajectory in a folding region about the stand (**34**), where in the trajectory is parallel to a transport direction (**3**).

13. A device according to claim **1**, wherein the stand is adjustable in vertical direction.

14. A device for folding an endless web (**2**) of corrugated cardboard, the device comprising:

- a. a contact surface (**32**) for supporting the web (**2**) of corrugated cardboard in a sliding manner, wherein the contact surface (**32**) comprises a bending point (**33**), from which the contact surface (**32**) slopes slightly downwards, when seen in a transport direction (**3**) of the web (**2**) of corrugated cardboard;
- b. a stand (**34; 34d**) located below the contact surface comprising two retaining members (**35; 35d**);
- c. at least one engagement member (**46; 46b; 46c; 46d**) which is mounted in the stand (**34; 34d**) and comprises at least one projection (**49; 49b; 49c**) which comprises at least one free end (**48**) forming a contact edge; and
- d. at least one driving device (**36, 37**) located below the contact surface for moving the at least one engagement member (**46; 46b; 46c; 46d**);
- e. with the at least one engagement member (**46; 46b; 46c; 46d**) being movably mounted in the stand (**34; 34d**) in such a way that the contact edge is movable at an angle relative to the contact surface (**32**) along a predetermined trajectory so as to bring the contact edge into engagement with the web (**2**) of corrugated cardboard sliding on the contact surface (**32**);
- f. where in the web (**2**) of corrugated cardboard is lifted off the contact surface (**32**) and is folded along the at least one projection (**49; 49b; 49c**), and wherein, when the at least one free end (**48**) hits a fold (**20**) created in the web

(2) of corrugated cardboard, said fold (20) has just reached the bending point (33) of the contact surface (32);

- g. wherein the engagement member (46; 46b; 46c) is pivotable about at least two axes (85; 86) which are oriented parallel to each other, with the axes (85; 86) being arranged at a distance A2 from one another;
- h. wherein in a region about the stand (34) the contact surface (32) is provided with perforations in a manner of a grating;
- i. wherein the grating is oriented along a transport direction (3) to allow the engagement member (46) to reach through the contact surface (32).

15. A device according to claim 14, wherein the at least one projection (49; 49b) has a length LF which, when measured from the second axis (86) to the contact edge, is no larger than the sum of the distance A1 of the first axis (85) from the contact surface (32) and the distance A2 of the second axis (86) from the first axis (85):

$$LF \leq A1 + A2.$$

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