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(54) **SYSTEMS AND METHODS FOR A COMMUNICATION PROTOCOL BETWEEN A LOCAL CONTROLLER AND A MASTER CONTROLLER**

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(58) **Field of Classification Search**

USPC **340/2.7, 3.1, 541; 714/4.2; 455/63.3; 700/286**

See application file for complete search history.

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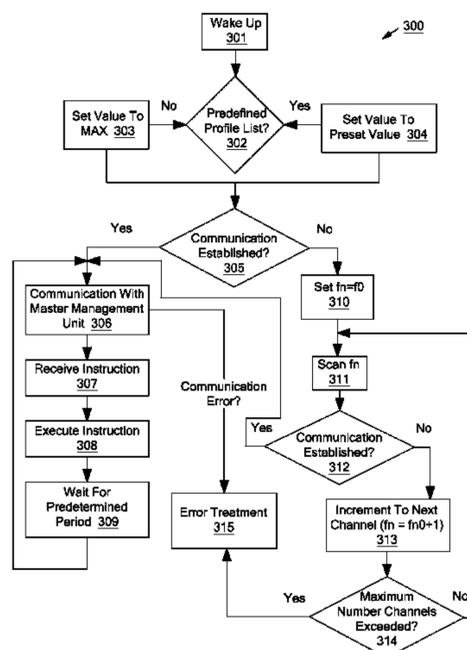
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(57) **ABSTRACT**

Systems and methods for local management units in a photovoltaic energy system. In one embodiment, a method implemented in a computer system includes: attempting to communicate on a first active channel with a master management unit from a local management unit that controls a solar module; if communication with the master management unit on the first active channel has not been established, attempting to communicate on a second active channel with the master management unit.

19 Claims, 6 Drawing Sheets



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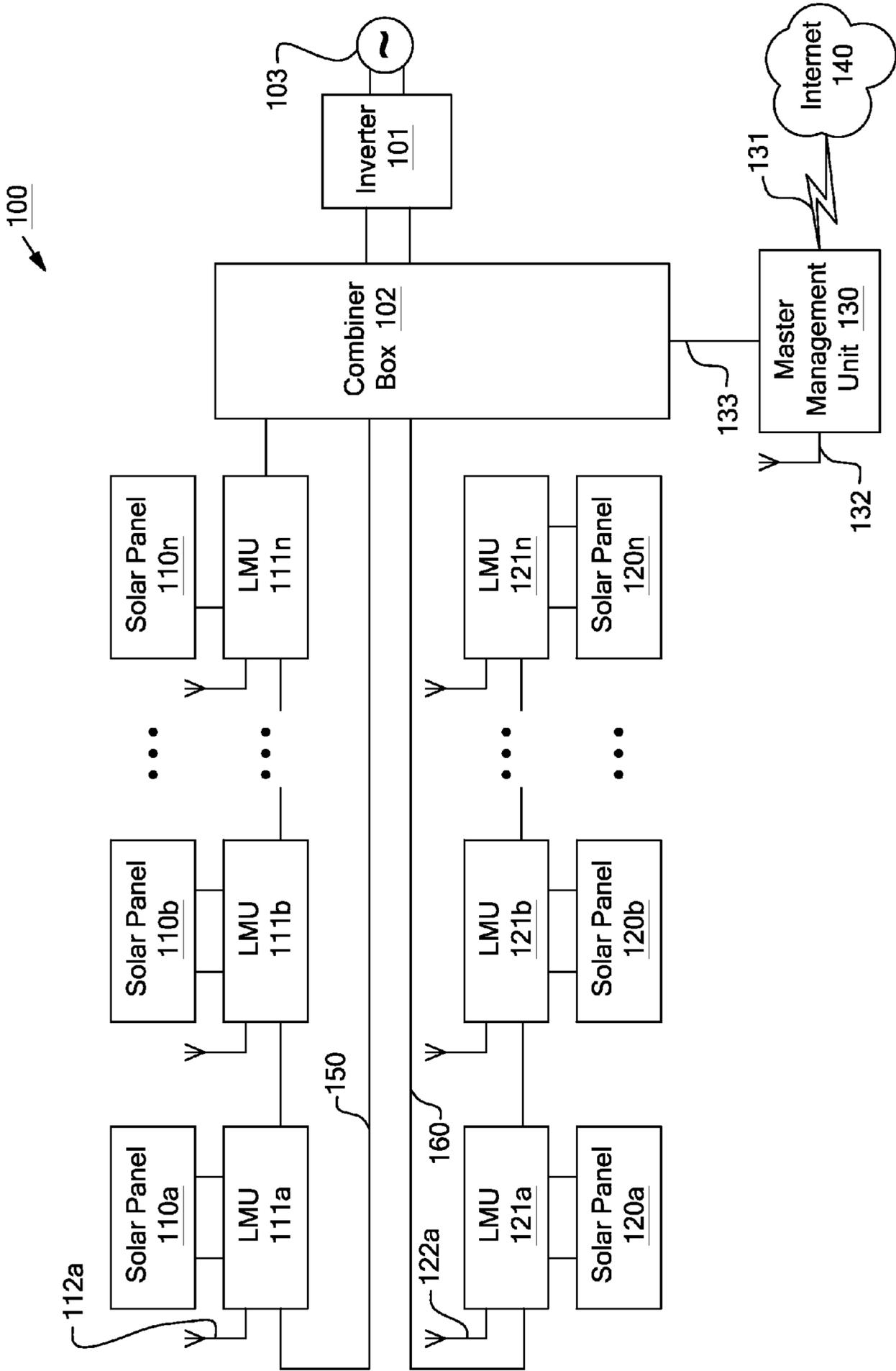


FIGURE 1

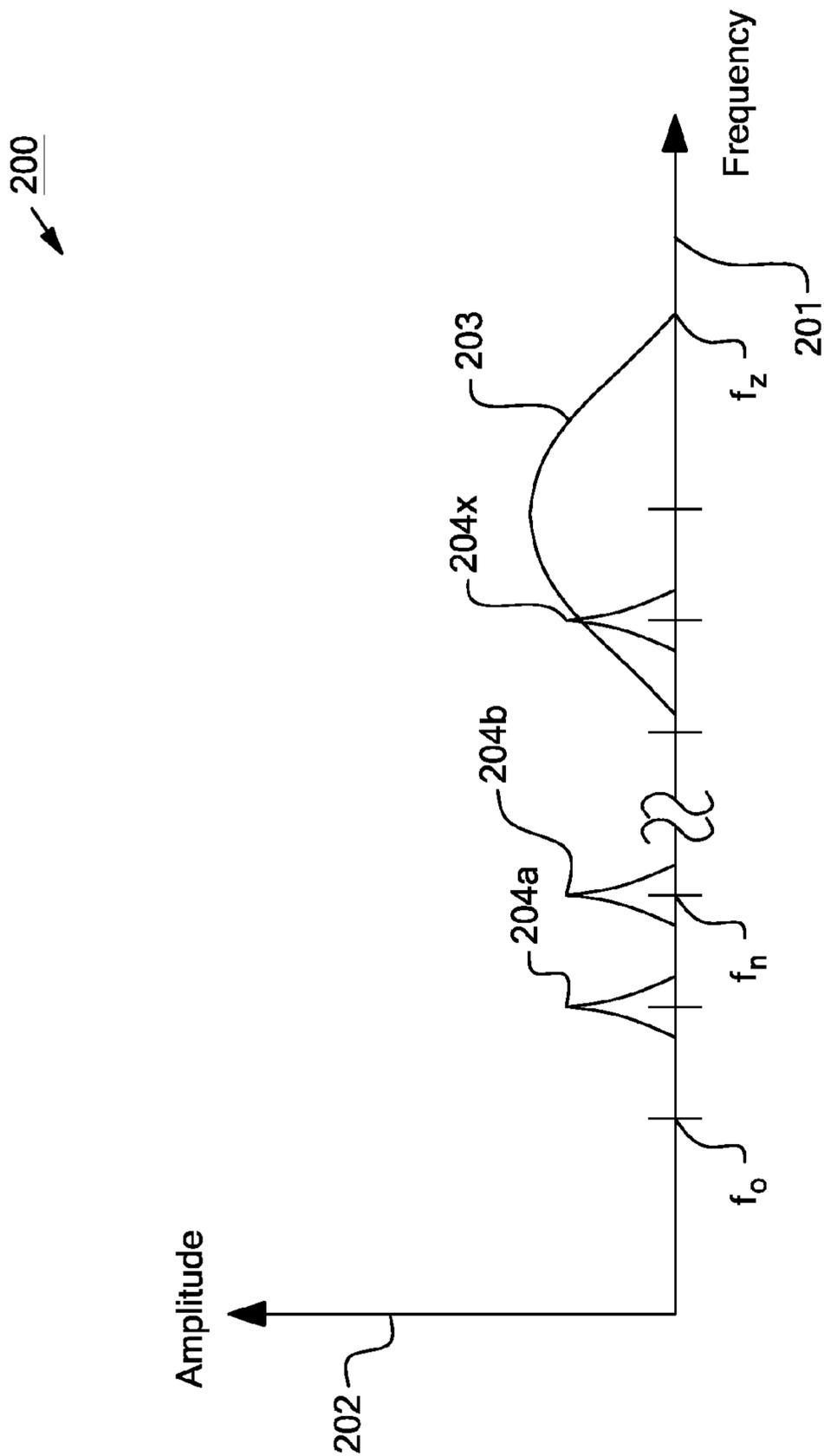


FIGURE 2

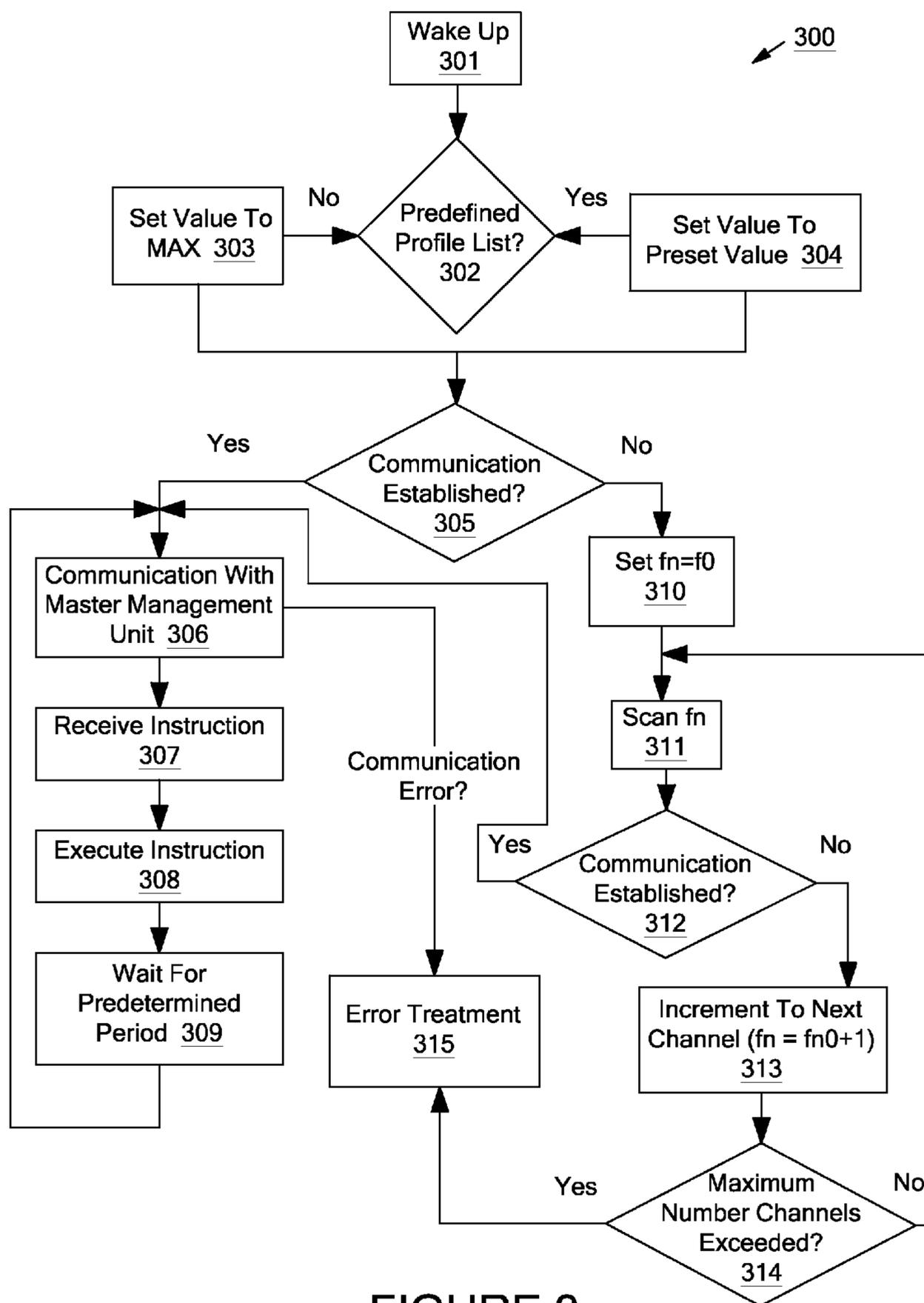


FIGURE 3

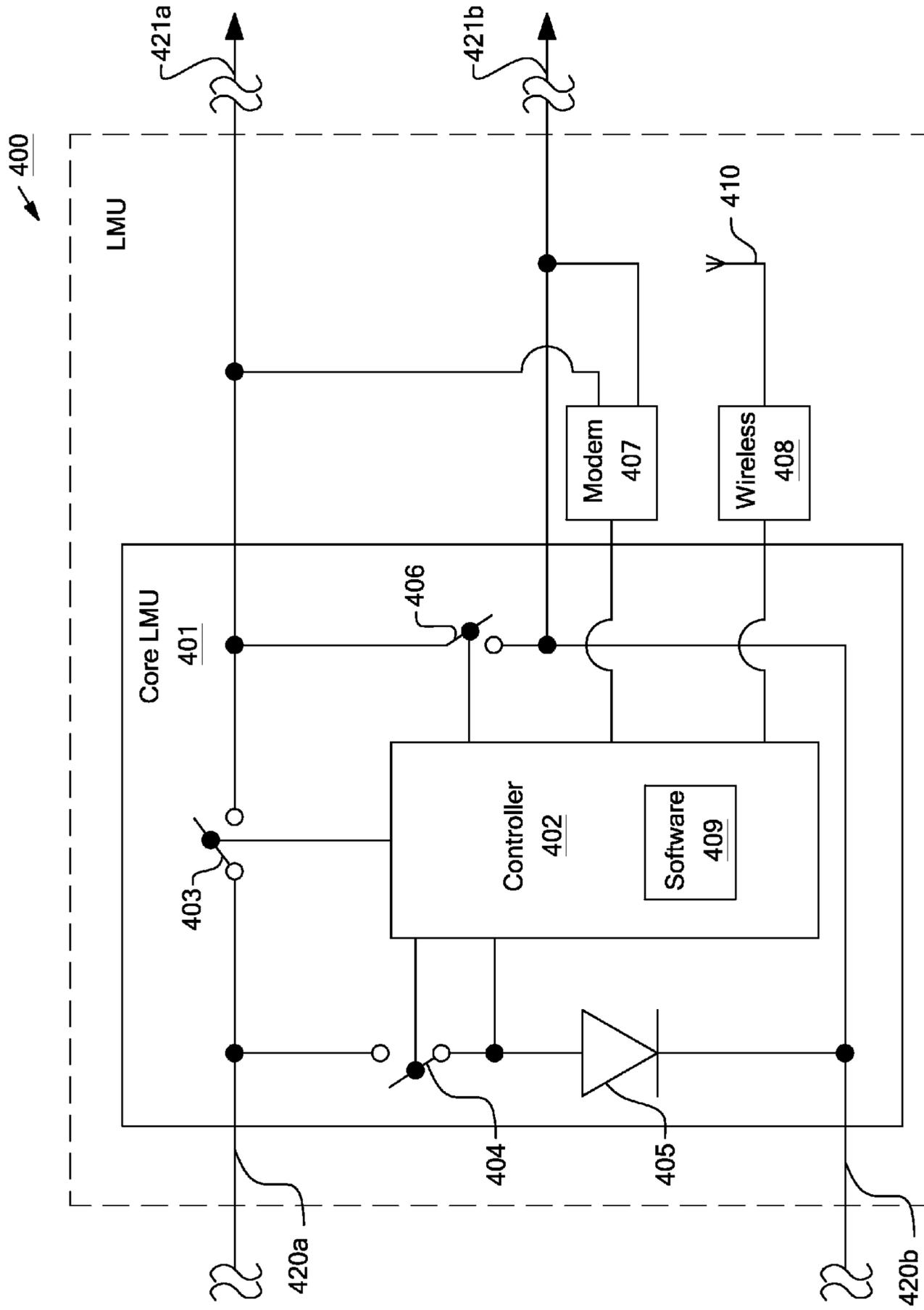


FIGURE 4

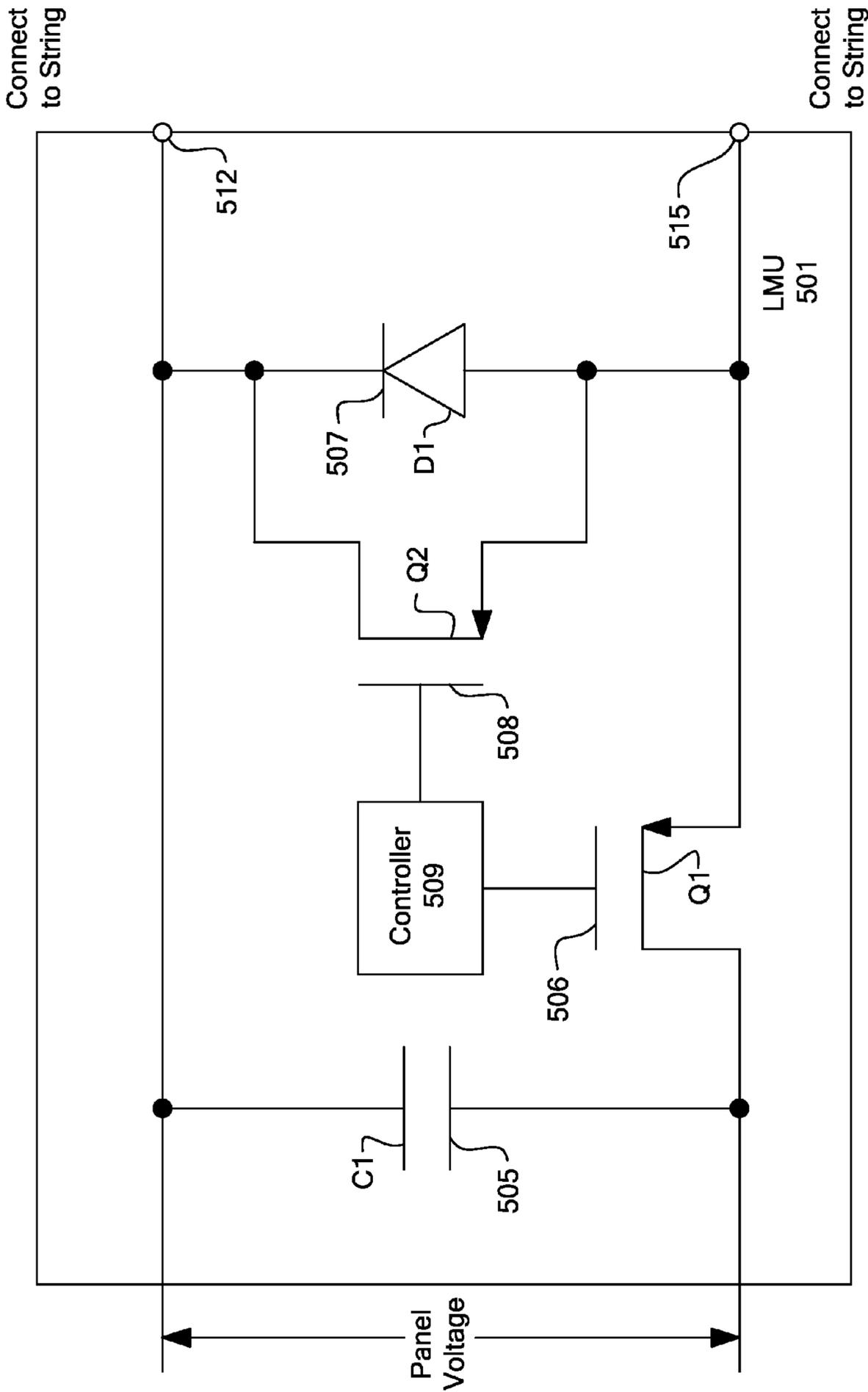


FIGURE 5

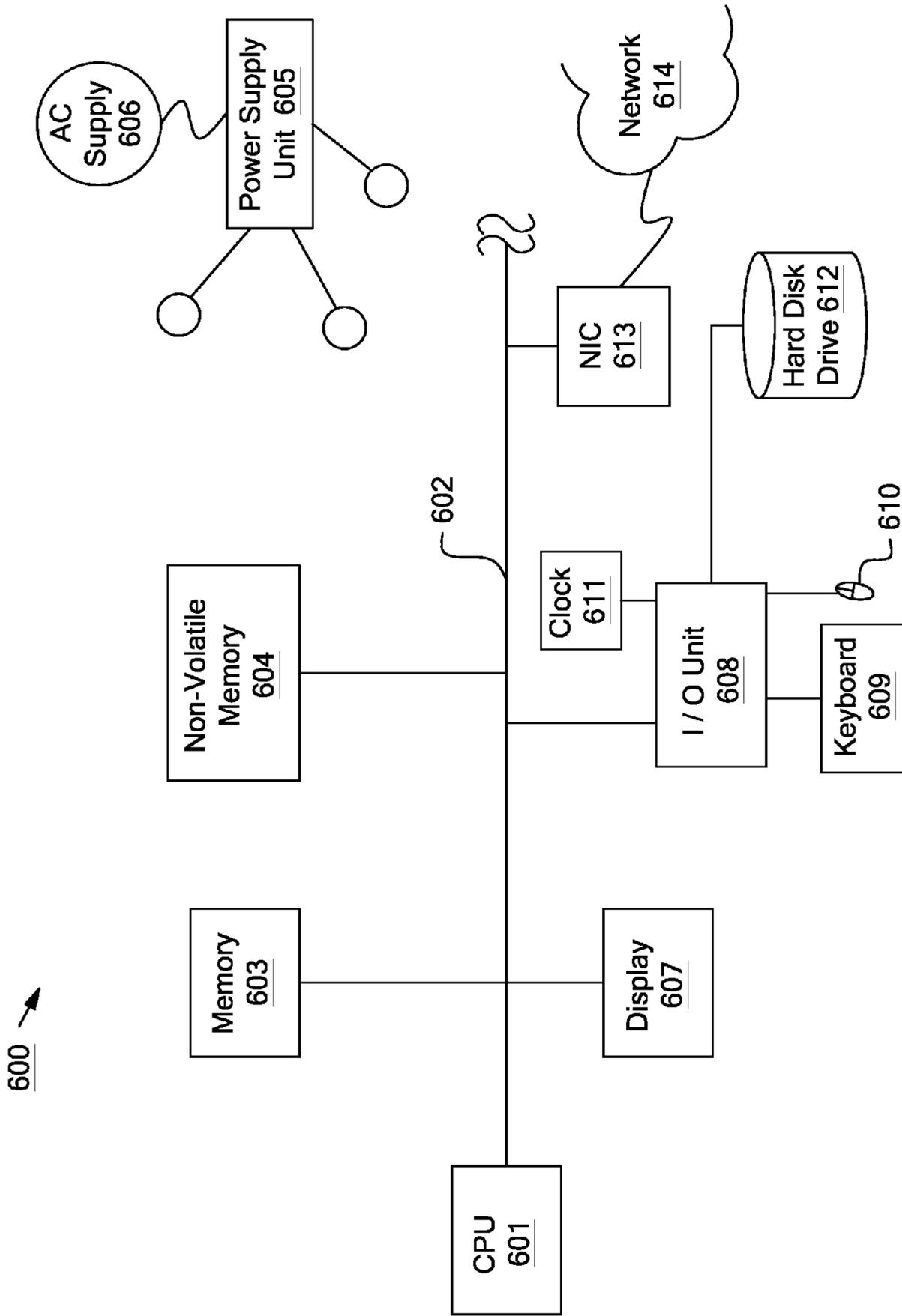


FIGURE 6

1

SYSTEMS AND METHODS FOR A COMMUNICATION PROTOCOL BETWEEN A LOCAL CONTROLLER AND A MASTER CONTROLLER

CROSS-REFERENCE TO RELATED APPLICATIONS

The present application claims priority to U.S. Provisional Application Ser. No. 61/335,004, filed Dec. 29, 2009, entitled "SYSTEM AND METHOD FOR AN ENHANCED PROTOCOL BETWEEN A LOCAL CONTROLLER AND A MASTER CONTROLLER," by Makhota et al., the entire contents of which application is incorporated by reference as if fully set forth herein.

FIELD OF THE TECHNOLOGY

At least some embodiments disclosed herein relate to photovoltaic systems in general, and more particularly, but not limited to, management units used in the configuration or operation of a photovoltaic system.

BACKGROUND

The operation of one or more local management units in a photovoltaic energy system may be defined by a protocol. In particular, the protocol is typically able to recover from various kinds of errors. For example, the protocol may be self-adjusting in the case of errors and other operational problems that may arise. Also, the protocol may maintain certain safety aspects associated with the operation of the photovoltaic energy system (e.g., a maximum operating voltage and other desired parameters).

SUMMARY OF THE DESCRIPTION

Systems and methods for management units for use in the configuration or operation of a photovoltaic system are described herein. Some embodiments are summarized in this section.

In one embodiment, a method implemented in a data processing system includes: attempting to communicate, from a first local management unit of a plurality of local management units, on a first active channel with a master management unit, each of the plurality of local management units coupled to control a respective solar module of a plurality of solar modules; determining if communication with the master management unit on the first active channel has been established; in response to a determination that the communication on the first active channel has not been established, attempting to communicate on a second active channel with the master management unit, the second active channel having a frequency different from the first active channel; and determining if communication with the master management unit on the second active channel has been established.

The disclosure includes methods and apparatuses which perform these methods, including data processing systems which perform these methods, and computer readable media containing instructions which when executed on data processing systems cause the systems to perform these methods.

Other features will be apparent from the accompanying drawings and from the detailed description which follows.

BRIEF DESCRIPTION OF THE DRAWINGS

The embodiments are illustrated by way of example and not limitation in the figures of the accompanying drawings in which like references indicate similar elements.

2

FIG. 1 shows an overview of a photovoltaic energy system including local management units (LMUs) according to one embodiment.

FIG. 2 shows a graph of the relationships of frequency vs. amplitude (with an amplitude axis and a frequency axis) for exemplary communication channels of a local management unit (LMU) according to one embodiment.

FIG. 3 is a flowchart illustrating a process for implementation of a communication protocol in an LMU according to one embodiment.

FIG. 4 is a circuit diagram illustrating a local controller or LMU according to one embodiment.

FIG. 5 is a circuit diagram illustrating an LMU providing two connectors for serial connections with other LMUs to form a serial power bus according to one embodiment.

FIG. 6 is a block diagram illustrating an overview of a computer system that may be used for one or more components of the system of FIG. 1 according to various embodiments.

DETAILED DESCRIPTION

The following description and drawings are illustrative and are not to be construed as limiting. Numerous specific details are described to provide a thorough understanding. However, in certain instances, well known or conventional details are not described in order to avoid obscuring the description. References to one or an embodiment in the present disclosure are not necessarily references to the same embodiment; and, such references mean at least one.

Reference in this specification to "one embodiment" or "an embodiment" means that a particular feature, structure, or characteristic described in connection with the embodiment is included in at least one embodiment of the disclosure. The appearances of the phrase "in one embodiment" in various places in the specification are not necessarily all referring to the same embodiment, nor are separate or alternative embodiments mutually exclusive of other embodiments. Moreover, various features are described which may be exhibited by some embodiments and not by others. Similarly, various requirements are described which may be requirements for some embodiments but not other embodiments.

As used herein, a "solar cell" is a photovoltaic device configured to absorb photons and convert them into electrical energy. A "solar module" is a device that includes at least one or more solar cells, wherein the solar cells are connected in series or in parallel. A solar panel is one example of a solar module. The solar cells absorb photons and convert the photons into electrical energy. A power bus may be a conductive path connecting one or more solar modules in series.

At least some embodiments of the disclosure provide a system and method for the operation of distributed local management units (LMUs) in a photovoltaic energy system.

In one embodiment, each LMU attempts to communicate on a first active channel with a master management unit. Each LMU is coupled to control one solar module of a plurality of solar modules in the system. If the communication with the master management unit on the first active channel has been established, then the LMU proceeds to a configuration process. If the communication on the first active channel is not established (i.e., fails for some reason), the LMU attempts to communicate on a second active channel.

In one embodiment, the second active channel has a frequency different from the first active channel. If communication with the master management unit on the second active channel is established, then the LMU proceeds to the configuration process. If communication is not established after a

predetermined total number of attempts or attempts on a predetermined number of channels, then the LMU proceeds to an error handling process.

FIG. 1 shows an overview of an exemplary system 100 according to one embodiment. System 100 contains two exemplary strings of solar panels, namely string 110a-n and string 120a-n. Each solar panel in each string has its own local management unit (e.g., a local controller or a data processing system), which, in this exemplary illustration, are units 111a-n and 121a-n, respective to the strings named above. The LMUs in FIG. 1 are connected in series (i.e., in a serial configuration) to power busses 150 and 160.

Each local management unit (LMU) has an antenna; in this exemplary illustration, only antennas 112a and 122a are numbered in FIG. 1, for simplicity and clarity of illustration. Combiner box 102 is typically used to combine the output of said multiple strings (i.e., 110a-n and 120a-n) of panels. Power busses 150 and 160 are connected to combiner box 102. For example, combiner box 102 may be used to house the wires, connections, etc., to combine the electricity generated from different solar panels, strings, subsystems, etc. Combiner box 102 is coupled to an inverter 101, for example, connected to power grid 103.

Master management unit (MMU) 130 (e.g., a master controller) is coupled to control each of the LMUs (e.g., by wireless communication via antennas 112a and 122a. MMU 130 acts as a gateway, connecting, for example, to the Internet 140, via connection 131, which may be wired, land line, Ethernet, wireless, or any other of various types of suitable connection. MMU 130 may store configuration profiles in a local database. MMU 130 may be updated or operated remotely from a remote server. For example, new profiles may be downloaded to MMU 130 using Internet 140.

In this example, MMU 130 has an antenna 132, which is used to communicate with the distributed LMUs. In some embodiments, one of the LMUs may act as the MMU for the system. The master management unit 130 is typically powered by the solar panels. However, it may be powered by alternative power sources, such as power grid 103.

Power line 133 may supply power to MMU 130, and in some cases, it could also transmit communications via power line communication between the MMU and LMUs, instead of using wireless communication. However, power line communication may exhibit problems similar to wireless communication, such as radio frequency (RF) interferences and other effects that may benefit from the use of active channel selection as described below. One example of power line communication is discussed in U.S. Non-Provisional Application Ser. No. 12/467,117, filed May 15, 2009, entitled "METHOD AND SYSTEM FOR CURRENT-MODE POWER LINE COMMUNICATIONS," by Leonid Rozenboim, the entire contents of which application is incorporated by reference as if fully set forth herein.

The structure as shown in FIG. 1 is one specific type of configuration, but other configurations may be used in other embodiments. For example, other system configurations may be as follows: 1) a set of solar panels, each connected to a parallel bus via a local management unit; 2) similarly as in FIG. 1, but with each string further connected to a parallel bus via a string management unit. In general, the operating protocol for the LMUs as described herein may be used with either a serial configuration (i.e., strings of local management units) or a parallel configuration (i.e., local management units on a parallel bus).

In one embodiment, an LMU may be provided for each solar panel, so that when the solar panels are connected into a system via the LMUs, the efficiency of the system as a whole

is increased. In this embodiment, the LMUs are designed to keep each solar panel working at, or close to, its respective maximum power point, substantially independently from each other, even through the panels are connected together to form a system.

In addition to the efficiency consideration, the LMUs may also be configured to provide various features, such as safety, panel protection, etc., in various implementations. There are two possible types of LMUs that may be adapted for different types of basic connection configurations for solar panels: parallel and series. In a combination, strings of LMUs connected in serial may be each connected to a string management unit for parallel combinations of strings at a combiner box.

At a given working condition (e.g., sunlight exposure, temperature, etc.), the power output level of a solar panel is based on the voltage or current consumed by its load. At the given working condition, there is a maximum power point at which the solar panel outputs maximum power W_{mp} , at current I_{mp} and voltage V_{mp} . If the working voltage deviates from V_{mp} (or the current from I_{mp}), the power from the solar panel will be reduced.

In this embodiment, the LMUs permit individual solar panels to work at their maximum power points, while adjusting LMU outputs for efficient operations in serial or parallel connections. The solar panel works at the maximum power point $W_{mp}=I_{mp}\times V_{mp}$; and the combination of the solar panel and the LMU outputs $W_{mp}=I_{out}\times V_{out}$ (since the LMU does not itself create power, and the power consumed by LMU is negligible).

In the parallel configuration, each of the solar panels is connected to an LMU to boost the voltage output V_{out} (while keeping the solar panel at its maximum power point $W_{mp}=I_{mp}\times V_{mp}=I_{out}\times V_{out}$, thus reducing I_{out}). The solar panels are connected in parallel to a high voltage DC bus via their LMUs; and the DC bus can be used to power an inverter, which is tied to a power grid, to supply the grid.

In the serial configuration, each of the solar panels is connected to an LMU to boost the current output (while keeping the solar panel at its maximum power point $W_{mp}=I_{mp}\times V_{mp}=I_{out}\times V_{out}$, thus reducing V_{out}). The solar panels are connected in series via their LMUs; and the string of the solar panels (a serial power bus) can be used to power an inverter, which is tied to a power grid, to supply the grid.

In various embodiments, LMUs may have the following features:

a. LMUs for parallel connections are used to boost voltage ($V_{out}>V_{mp}$). Each parallel LMU has a step up converter and has a maximum power point tracking circuit. Parallel LMUs are configured to output a substantially fixed voltage, allowing only very small variations from the nominal voltage of the high voltage DC bus.

b. LMUs for series connections typically boost current ($I_{out}>I_{mp}$). The serial LMUs do not use step up converters or maximum power point tracking circuits. Serial LMUs receive duty cycles from a system management unit (e.g., master management unit 130), which coordinates the output of the serial LMUs to improve the performance of the system. The system management unit adjusts the duty cycles of the serial LMUs to adjust the states of their respective solar panels.

In one embodiment, a solar panel has a few strings of solar cells (e.g., three solar cell strings per module). A local management unit can be applied to a group of cells within a string of an individual solar panel, or in some cases to each cell in a solar panel. A group of solar cells that are attached to a local management unit may be connected to each other in series, in parallel, or in a mesh configuration. A number of local man-

5

agement units connect the groups of the solar cells in a string to provide output for the solar panel. The foregoing is described further in U.S. Pat. No. 7,602,080, filed Oct. 13, 2009, entitled "SYSTEMS AND METHODS TO BALANCE SOLAR PANELS IN A MULTI-PANEL SYSTEM" by Hadar et al. (see, e.g., FIG. 5), the entire contents of which is incorporated by reference as if fully set forth herein. Some embodiments of the disclosure include methods to determine the duty cycles and/or phases for local management units connected to a string or mesh of solar modules.

In one embodiment, the system management unit controls the operations of the LMUs via a communication connection, which may be over the power line through which the solar panels deliver power, or over wireless connections, or via separate communication lines (e.g., as discussed above for FIG. 1). In one embodiment, as a safety feature, each LMU may have a watchdog circuit, which cuts off its output if the heartbeat signal from the system management unit is missing. This allows the solar system to be completely shut down remotely (e.g., for fire-fighting, or cleaning, etc.).

In one embodiment, the MMU listens for new LMUs that may be attempting to communicate with the MMU, for example during set up of a new system, or during replacement of an LMU. The MMU may listen on certain predefined channels (e.g., selected communication frequencies) known to the LMU. After the LMU establishes communication with the MMU, the LMU restarts and again establishes communication with the MMU, but does so on a different channel different from these predefined channels. A remote server or other computer system may be used to provide configuration profiles to the MMU (e.g., over the Internet). This permits a local photovoltaic system to be configured remotely by providing updated profiles to the MMU, then restarting one or more LMUs using the new profiles.

In one embodiment, a plurality of local management units are configured to, under supervision of a master management unit, balance currents between the plurality of solar modules in the power bus. In one embodiment, the LMUs may be configured to balance voltages and currents between solar modules and between power buses. The LMUs can be implemented serially or in parallel. The foregoing configurations are further described in U.S. Patent Application Publication No. 2010/0139734, published Jun. 10, 2010, entitled "SYSTEMS AND METHODS FOR AN ENHANCED WATCHDOG IN SOLAR MODULE INSTALLATIONS", by Hadar et al., the entire contents of which publication is incorporated by reference as if fully set forth herein.

FIG. 2 shows a graph 200 of the relationships of frequency vs. amplitude, with amplitude axis 202 and frequency axis 201 in one embodiment. FIG. 2 illustrates exemplary communication channels used by an LMU to communicate with the MMU. Shown on frequency axis 201 are a number of channels f_0 - f_z , with channel f_n , being the actual active channel in use. Also shown are exemplary signals 204a, 204b, and 204x corresponding to communication on these channels. In this example, a number of channels are covered by a disturbing interference 203 (e.g., interference from a microwave nearby). This interference may cause communications with the MMU to fail, and thus require the use of an alternate active channel.

FIG. 3 shows an exemplary process 300 in one embodiment for implementation of a communications protocol in an LMU. More specifically, FIG. 3 illustrates a protocol for an LMU to communicate with an MMU in one embodiment. In one embodiment, the protocol supports the automatic self-configuration of the LMU.

6

In step 301, the LMU unit wakes up. In step 302, the system checks to determine whether it has a predefined profile list of starting values (e.g., the output voltage for the solar panel controlled by the LMU; or power level and/or initial channel to use for communications). If not (No), in step 303, the system sets a maximum value (e.g., maximum communications power or a default active channel). The maximum value may typically be for the output voltage that particular LMU contributes to its string, except in cases where local regulations require that the value be set lower than the maximum.

If the system finds a preset value in a profile (Yes), in step 304 the system sets the LMU at the preset value(s). Once the value is set for LMU operation in either step 303 or step 304, communication is attempted with the MMU on a first active channel. In step 305, the system checks to determine whether communication with the MMU has been established.

If communication is established (Yes), in step 306 the system communicates with the MMU in step 306 and in step 307, it receives one or more instructions from the MMU. In step 308, the system executes the instruction(s) it has received. In step 309, the system waits for a period (e.g., 1-5 seconds) whose value is contained in its profile list, and then it repeats the communication loop beginning again at step 306.

In cases where a communication error occurs in step 306, the system moves to step 315 and commences an error treatment protocol, for example as described below or otherwise. Examples of errors may include detection of a non-existing command, a mismatch in the MMU identification number, etc.

If the system finds, in step 305, that communication is not established (No), in step 310 the system attempts to establish communication by setting the channel f_n to the frequency of initial active channel f_0 and, in step 311, scanning f_n . In step 312, the system checks to see if communication is then established on this new active channel. If it is (Yes), the system continues to the sequence of steps starting with step 306, as described above. If, in step 312, communication is not established (No), in step 313 the system increments the then-active channel f_n to the next available channel f_0+1 (i.e., channel f_1).

In step 314, the system checks to see if the next incremental channel exceeds the maximum number of available channels (e.g., a predetermined maximum number of channels stored in the LMU start-up profile). If the maximum is not exceeded (No), the system returns to step 311 and continues to scan succeeding active channels until either it establishes communication or it exceeds the maximum number of channels. In the case of exceeding the maximum number of available channels in step 314 (Yes), the system moves to step 315 and commences an error treatment protocol. An error treatment protocol may include one or more of various approaches. One typical approach would reset the LMU and start again at step 301. Another approach would shut down the LMU; while yet another would loop back to step 305 and try again.

The section below entitled "EXEMPLARY PROTOCOL COMMUNICATION INFORMATION" shows specific examples of the protocol of communications between an exemplary distributed LMU and an exemplary MMU. This protocol shows how a system can self-detect elements, available channels, etc., thus reducing setup efforts. This is advantageous with the use of wireless communications, as channels may be blocked by outside sources of interference (e.g., as discussed for FIG. 2 above), and the system desirably should be able to self-reconfigure in such situations.

FIG. 4 shows an exemplary local controller or LMU 400 according to one embodiment. Wires 420a,b are connected to a solar panel 110 or 120 (i.e., to provide incoming electricity).

Wires **421a,b** are used to chain the LMUs together to form a string, as in the serial configuration illustrated in FIG. 1. The hardware of LMU **400** is configured for use in such a serial connection.

Core LMU **401** has switches **403**, **404** and **406**, plus controller **402**. A diode **405** provides a voltage drop in the case of a short of switch **404**, to ensure enough voltage to operate controller **402**. Modem **407** and/or wireless network interface **408** are coupled to controller **402** to permit communications with the LMUs. In some cases, modem **407** connects to the string wiring **421a,b** (e.g., to modulate control signals onto the wiring **421a,b** at control frequencies higher than the normal operating frequencies used in power busses **150** and **160**).

In other cases, wireless network interface **408** has an antenna **410** to use for communications with the LMUs. The network communications type used may be one of many different types of conventional wireless networks. The use of wireless communication may be advantageous in some cases by reducing the number of hardware points of failure, and thus increasing the simplicity of system setup or the reliability of system operation.

In most cases, an LMU does not have both a modem **407** and a wireless network interface **408**. Typically, a system contains only one or the other, but in some cases, these may be, for example, plug-in modules. In other cases, both components may be present, but only one may be activated. Controller **402** may be configured for operation by additional software code **409** that may include, in addition to other previously discussed features for a communication protocol, code for implementing a shut-off system.

Examples of an LMU are described in U.S. Provisional Application Ser. No. 61/276,752, filed Sep. 16, 2009, entitled "SYSTEM AND METHOD FOR REMOTE OR LOCAL SHUT-OFF OF SOLAR PANEL SYSTEMS," by Makhota et al. (see, e.g., FIG. 6 and TGY010-3), and also in U.S. Provisional Application Ser. No. 61/277,867, filed Sep. 29, 2009, entitled "SYSTEM AND METHOD FOR REMOTE OR LOCAL SHUT-OFF OF SOLAR PANEL SYSTEMS," by Makhota et al. (see, e.g., FIG. 6 and TGY010-3), the entire contents of each of the foregoing applications being incorporated by reference as if fully set forth herein.

In FIG. 5, a local management unit **501** according to another embodiment is illustrated. Local management unit **501** provides two connectors **512** and **515** for serial connections with other local management units **501** to form a serial power bus (e.g., power bus **150** or **160** of FIG. 1). Note that in other embodiments, a parallel configuration of LMUs may be used.

A controller **509** controls the states of switches Q1 **506** and Q2 **508**. When the controller **509** turns on switch **506**, the panel voltage and the capacitor C1 **505** are connected in parallel to the connectors **512** and **515**. The output voltage between the connectors **512** and **515** is substantially the same as the output panel voltage. During the period the switch **506** is turned off (open), the controller **509** turns on (closes) the switch Q2 **508** to provide a path around the diode D1 **507** to improve efficiency.

When the switch **506** is turned off (open), the panel voltage charges the capacitor C1 **505**, such that when the switch **506** is turned on, both the solar panel and the capacitor **505** provides currents going through the connectors **512** and **515**, allowing a current larger than the current of the solar panel to flow in the string (e.g., the serial power bus **150** or **160** of FIG. 1). When the switch **506** is turned off (open), the diode D1 **507** also provides a path between the connectors **512** and **515** to sustain the current in the string, even if the switch **508** is off for some reason. In one embodiment, the controller **509** is

connected (not shown) to the panel voltage to obtain the power for controlling the switches Q1 **506** and Q2 **508**.

In one embodiment, the controller **509** is further connected (not shown) to at least one of the connectors **512** and **515** to transmit and/or receive information from the string. In one embodiment, the controller **509** includes sensors (not shown) to measure operating parameters of the solar panel, such as panel voltage, panel current, temperature, light intensity, etc.

Additional information regarding local management units, and the operation thereof, that may be used in some embodiments of the present disclosure is described in U.S. Pat. No. 7,602,080, filed Oct. 13, 2009, entitled "SYSTEMS AND METHODS TO BALANCE SOLAR PANELS IN A MULTI-PANEL SYSTEM" by Hadar et al., the entire contents of which is incorporated by reference as if fully set forth herein.

FIG. 6 shows an exemplary overview of a computer or data processing system **600** as may be used, in some embodiments, at various locations (e.g., for use as an MMU or an LMU) throughout system **100**. It is generally exemplary of any computer that may execute code to process data. Various modifications and changes may be made to computer system **600** without departing from the broader spirit and scope of the system and method disclosed herein. For example, in various embodiments, computer system **600** may be used to implement processes, protocols, or methods described herein. For example, an MMU may be implemented via computer system **600**. In other embodiments, LMUs are implemented via controllers, rather than use of a full computer system.

CPU **601** is connected to bus **602**, to which bus is also connected memory **603**, non-volatile memory **604**, display **607**, I/O unit **608**, and network interface card (NIC) **613**. I/O unit **608** may, typically, be connected to keyboard **609**, pointing device **610**, hard disk **612**, and real-time clock **611**. NIC **613** connects to network **614**, which may be the Internet or a local network, which local network may or may not have connections to the Internet. Also shown as part of system **600** is power supply unit **605** connected, in this example, to AC supply **606**. Not shown are batteries that may be present in some embodiments, and many other hardware devices and modifications thereof that are well known for use in such computer systems, but are not directly applicable to the specific novel functions of the system and method disclosed herein. Although FIG. 6 illustrates various components of a computer system, it is not intended to represent any particular architecture or manner of interconnecting the components. Other systems that have fewer or more components may also be used.

In other embodiments, typical I/O devices may include mice, modems, network interfaces, printers, scanners, video cameras and other devices which are well known in the art. The bus **602** may include one or more buses connected to one another through various bridges, controllers and/or adapters. In one embodiment, the I/O unit **608** includes a USB (Universal Serial Bus) adapter for controlling USB peripherals, and/or an IEEE-1394 bus adapter for controlling IEEE-1394 peripherals.

In other embodiments, memory may include ROM (Read Only Memory) and volatile RAM (Random Access Memory). Non-volatile memory may include, for example, a hard drive, flash memory, etc. Volatile RAM is typically implemented as dynamic RAM (DRAM) which requires power continually in order to refresh or maintain the data in the memory. Non-volatile memory is typically a magnetic hard drive, a magnetic optical drive, or an optical drive (e.g., a DVD RAM), or other type of memory system which maintains data even after power is removed from the system. The non-volatile memory may also be a random access memory.

The non-volatile memory can be a local device coupled directly to the rest of the components in the data processing system. A non-volatile memory that is remote from the system, such as a network storage device coupled to the data processing system through a network interface such as a modem or Ethernet interface, can also be used.

In some embodiments, one or more servers of the system can be replaced with the service of a peer to peer network of a plurality of data processing systems, or a network of distributed computing systems. The peer to peer network, or a distributed computing system, can be collectively viewed as a server data processing system.

Embodiments of the disclosure can be implemented via the processor(s) 601 and/or the memory 603/604. For example, the functionalities described can be partially implemented via hardware logic in the processor(s) 601 and partially using the instructions stored in the memory 603 and/or 604. Some embodiments are implemented using the processor(s) 601 without additional instructions stored in memory. Some embodiments are implemented using the instructions stored in the memory for execution by one or more general purpose microprocessor(s). Thus, the disclosure is not limited to a specific configuration of hardware and/or software.

As mentioned previously above, examples of additional communications protocol embodiments are described further in the section below entitled "EXEMPLARY PROTOCOL COMMUNICATION INFORMATION". Specific examples of communication packet data structures and communication commands that may be used in specific implementations of the various embodiments described above are included in this section.

In one embodiment, communications are attempted using this exemplary communication protocol, from a first local management, on a first active channel with the MMU. Next, it is determined if communication with the MMU has been established. In response to a determination that the communication on the first active channel has not been established, communication is attempted on a second active channel with the MMU, the second active channel having a frequency different from the first active channel. Then, it is determined if communication with the master management unit on the second active channel has been established. If so, then the LMU continues with a configuration or start-up process.

In one embodiment, the method further comprises after the communication on the second active channel has been established, receiving a first communication from the master management unit. In one embodiment, the first communication comprises an instruction (e.g., a command), and the method further comprises executing the instruction on the first local management unit. In one embodiment, the plurality of local management units are connected in series. In another embodiment, the plurality of local management units are connected in parallel.

In one embodiment, the communication on the first active channel is at a predetermined frequency used by the master management unit for establishing communication with new local management units being added to the system. In one embodiment, the method further comprises after communication with the master management unit has been established, restarting the first local management unit and subsequently communicating with the master management unit at a frequency other than the predetermined frequency.

In one embodiment, the method further comprises communicating from the first local management unit to the master management unit an identification code (e.g., Unit ID) associated with the first local management unit; and receiving a profile from the master management unit, the profile corre-

sponding to the identification code. In one embodiment, the method further comprises in response to receiving the identification code, retrieving, via the master management unit, the profile from a database that includes a plurality of different profiles suitable for configuration of local management units.

In one embodiment, the first local management unit comprises an antenna, and the attempting to communicate on the first active channel comprises sending a wireless signal via the antenna. In one embodiment, the method further comprises after the communication on the second active channel has been established, determining that an error has occurred in communication with the master management unit; and in response to the error, initiating an error treatment protocol for the first local management unit.

In one embodiment, the method further comprises: in response to a determination that the communication on the second active channel has not been established, attempting to communicate on a third active channel with the master management unit, the third active channel having a frequency different from the first and second active channels; determining if communication with the master management unit on the third active channel has been established; in response to a determination that the communication on the third active channel has not been established, determining whether a predetermined number of available channels for communication with the master management unit has been exceeded; and in response to a determination that the predetermined number has been exceeded, initiating an error treatment protocol for the first local management unit.

In one embodiment, the method further comprises: prior to the attempting to communicate on the first active channel, waking up the first local management unit; after the waking up, determining whether the first local management unit is storing a configuration profile; in response to a determination that the first local management unit is not storing the configuration profile, communicating to the master management unit a first identification code associated with the first local management unit; receiving a first profile from the master management unit, the first profile corresponding to the first identification code, and the first profile including a time period; and configuring the first local management unit using the first profile.

In one embodiment, the method further comprises: after the communication on the second active channel has been established, receiving a first instruction from the master management unit; executing the first instruction on the first local management unit; after the executing the first instruction, waiting for the time period; after the waiting, communicating with the master management unit to receive a second instruction; and executing the second instruction on the first local management unit.

In one embodiment, the method further comprises: establishing communication with the master management unit from a second local management unit of the plurality of local management units; and communicating to the master management unit a second identification code associated with the second local management unit; receiving a second profile from the master management unit, the second profile corresponding to the second identification code; and configuring the second local management unit using the second profile.

In one embodiment, a local management unit comprises memory storing software instructions, and a controller coupled to the memory. The controller is configured via the software instructions to execute a method comprising: controlling, under supervision by a master management unit, a first solar module of a plurality of solar modules, the master

management unit coupled to supervise a plurality of local management units, wherein the plurality of local management units are coupled by a power bus, and each one of the plurality of local management units controls a respective one of the plurality of solar modules, attempting to communicate on a first active channel with the master management unit, determining if communication with the master management unit on the first active channel has been established, in response to a determination that the communication on the first active channel has not been established, attempting to communicate on a second active channel with the master management unit, the second active channel having a frequency different from the first active channel, and determining if communication with the master management unit on the second active channel has been established.

In one embodiment, the system further comprises a modem or wireless network interface to attempt to communicate with the master management unit on the first active channel. In one embodiment, the plurality of local management units are configured to, under supervision of the master management unit, balance currents between the plurality of solar modules in the power bus.

In one embodiment, a non-transitory computer-readable storage medium tangibly stores computer readable instructions. The instructions cause a computer or data processing system to perform a method comprising: attempting to communicate, from a first local management unit of a plurality of local management units, on a first active channel with a master management unit, each of the plurality of local management units coupled to control a respective solar module of a plurality of solar modules; determining if communication with the master management unit on the first active channel has been established; in response to a determination that the communication on the first active channel has not been established, attempting to communicate on a second active channel with the master management unit, the second active channel having a frequency different from the first active channel; and determining if communication with the master management unit on the second active channel has been established.

In one embodiment, method further comprises: communicating from the first local management unit to the master management unit an identification code associated with the first local management unit; and receiving a profile from the master management unit, the profile corresponding to the identification code.

In this description, various functions and operations may be described as being performed by or caused by software code to simplify description. However, those skilled in the art will recognize what is meant by such expressions is that the functions result from execution of the code by a processor, such as a microprocessor. Alternatively, or in combination, the functions and operations can be implemented using special purpose circuitry, with or without software instructions, such as using an Application-Specific Integrated Circuit (ASIC) or a Field-Programmable Gate Array (FPGA). Embodiments can be implemented using hardwired circuitry without software instructions, or in combination with software instructions. Thus, the techniques are limited neither to any specific combination of hardware circuitry and software, nor to any particular source for the instructions executed by the data processing system.

While some embodiments can be implemented in fully functioning computers and computer systems, various embodiments are capable of being distributed as a computing product in a variety of forms and are capable of being applied regardless of the particular type of machine or computer-readable media used to actually effect the distribution.

At least some aspects disclosed can be embodied, at least in part, in software. That is, the techniques may be carried out in a computer system or other data processing system in response to its processor, such as a microprocessor, executing sequences of instructions contained in a memory, such as ROM, volatile RAM, non-volatile memory, cache or a remote storage device.

Routines executed to implement the embodiments may be implemented as part of an operating system, middleware, service delivery platform, SDK (Software Development Kit) component, web services, or other specific application, component, program, object, module or sequence of instructions referred to as "computer programs." Invocation interfaces to these routines can be exposed to a software development community as an API (Application Programming Interface). The computer programs typically comprise one or more instructions set at various times in various memory and storage devices in a computer, and that, when read and executed by one or more processors in a computer, cause the computer to perform operations necessary to execute elements involving the various aspects.

A machine readable medium can be used to store software and data which when executed by a data processing system causes the system to perform various methods. The executable software and data may be stored in various places including for example ROM, volatile RAM, non-volatile memory and/or cache. Portions of this software and/or data may be stored in any one of these storage devices. Further, the data and instructions can be obtained from centralized servers or peer to peer networks. Different portions of the data and instructions can be obtained from different centralized servers and/or peer to peer networks at different times and in different communication sessions or in a same communication session. The data and instructions can be obtained in entirety prior to the execution of the applications. Alternatively, portions of the data and instructions can be obtained dynamically, just in time, when needed for execution. Thus, it is not required that the data and instructions be on a machine readable medium in entirety at a particular instance of time.

Examples of computer-readable media include but are not limited to recordable and non-recordable type media such as volatile and non-volatile memory devices, read only memory (ROM), random access memory (RAM), flash memory devices, floppy and other removable disks, magnetic disk storage media, optical storage media (e.g., Compact Disk Read-Only Memory (CD ROMS), Digital Versatile Disks (DVDs), etc.), among others.

In general, a machine readable medium includes any mechanism that provides (e.g., stores) information in a form accessible by a machine (e.g., a computer, network device, personal digital assistant, manufacturing tool, any device with a set of one or more processors, etc.).

In various embodiments, hardwired circuitry may be used in combination with software instructions to implement the techniques. Thus, the techniques are neither limited to any specific combination of hardware circuitry and software nor to any particular source for the instructions executed by the data processing system.

Although some of the drawings illustrate a number of operations in a particular order, operations which are not order dependent may be reordered and other operations may be combined or broken out. While some reordering or other groupings are specifically mentioned, others will be apparent to those of ordinary skill in the art and so do not present an exhaustive list of alternatives. Moreover, it should be recognized that the stages could be implemented in hardware, firmware, software or any combination thereof.

13

Exemplary Protocol Communication Information

A. Message Level

Command Summary
 0x02—data request
 0x03—data response
 0x04—request NO DATA response
 0x05—no data response
 0x06—general parameter error response
 0x08—send broadcast request
 0x09—send broadcast response
 0x0a—send version request
 0x0b—send version response
 0x0c—set channel
 0x0d—set channel response
 0x0e—read channel
 0x0f—read channel response
 0x10—Hard reset of Gateway
 0x11—Response to hard reset
 0x12—STORE settings
 0x13—Response to STORE settings
 0x14—Set unit ID
 0x15—Set unit ID response
 0x16—Get unit ID
 0x17—Get unit ID response
 - - - diagnostic - - -
 0x100—Echo command
 0x101—Echo response

(0x02) Get data request
 Sent to request lines of LMU data from the Gateway
 <command>=0x02
 <body>=<line count> <seq ID>
 <line count>Number of lines desired
 16 bits, high byte first
 <seq ID>Starting sequence number desired
 <32 bits, high byte first
 Responses
 0x03—data response
 0x05—no data response

(0x03) Data Response
 Sent to supply LMU data to the MMU
 <response>=0x03
 <body>=<line count> <delimiter> <LMU line> . . .
 <line count>Count of available lines
 16 bits, high byte first
 <delimiter>0xDDDD
 16 bites, high byte first
 <LMU line>= . . .

(0x04) Get NO data request
 Sent to request sequence number limits
 <command>=0x04
 <body>=<empty>
 Responses
 0x05—no data response

(0x05) No Data Response
 Sent to indicate to the MMU that the requested sequence ID
 is not yet in the buffer
 <response>=0x05
 <body>=<Seq ID first> <Seq ID next>
 <Seq ID first> First available Seq ID
 32 bits, high byte first
 <Seq ID next>“Current” Seq ID (highest+1)
 32 bits, high byte first

(0x06) General parameter error response
 Sent to indicate a parameter error.
 <response>=0x06
 <body>=<empty>

14

(0x08) Send Broadcast Request
 Sent to load data to the beacon payload in the Gateway
 <command>=0x08
 <body>=<ascii bytes>
 5 <ascii bytes>Up to 40 ascii bytes . . .
 Responses
 0x09—send broadcast response

(0x09) Send Broadcast Response
 Sent in response to a broadcast command
 10 <command>=0x09
 <body>=<empty>

(0x0a) Send Version Request
 Request version and build strings
 15 <command>=0x0a
 <body>=<empty>
 Responses
 0x0b—Send Version Response

(0x0b) Send Version Response
 20 <response>=0x0b
 <body>=<version string><build date><build time>
 <version string>Delimited ascii string (CR delimiter)
 Typ: “Gateway Version 00.6a”
 <build date>Delimited ascii string (CR delimiter)
 25 Typ: “Build Aug 24 2009”
 <build time>Delimited ascii string (CR delimiter)
 Typ: “10:00:38”

(0x0c) Set Channel Request
 Sets new channel in gateway. Gateway is radio is then
 30 forcibly restarted with a hammer.
 <command>=0x0c
 <body>=<desired channel>
 <desired channel>Channel number between 11 and 26
 (dec)
 35 16 bit, high byte first
 Responses
 0x06—Bad parameter response
 0x0d—Set Channel Response

(0x0d) Set Channel Response
 40 <response>=0x0d
 <body>=<empty>

(0x0e) Get Channel Request
 <command>=0x0e
 <body>=<empty>
 45 <current channel>Channel number between 11 and 26
 (dec)
 16 bit, high byte first
 Responses
 0x0d—Get Channel Response

(0x0f) Set Channel Response
 50 <response>=0x0d
 <body>=<current channel>
 <current channel>Channel number between 11 and 26
 (dec)
 55 16 bit, high byte first

(0x10) Request Gateway Reset
 Gateway is put into hard reset
 <command>=0x10
 <body>=<magic string>
 60 <magic string>0x37249266L-arbitrary . . .
 32 bit, high byte first
 Responses
 0x06—General error response (bad magic number)
 0x11—Get reset request Response

(0x11) Request Gateway Reset Response
 65 <response>=0x11
 <body>=<empty>

15

In some embodiments, the gateway implementation does not finish the answer packet before resetting.

(0x12) STORE settings

Current parameters are formatted to a structure and written to Flash. A limited number of writes are allowed before the memory is filled up. Do NOT write to Flash unless the actions in NECESSARY

<command>=0x12

<body>=<magic string>

<magic string>0x37249266L-arbitrary . . .

32 bit, high byte first

Responses

0x06—General error response (bad magic number)

0x13—STORE settings response

(0x13) STORE settings response

<command>=0x13

<body>=<empty>

(0x14) Set Unit ID Request

Sets new Unit ID in gateway. Further transactions will use new ID.

<command>=0x14

<body>=<magic number> <desired ID>

<magic string>0x37249266L-arbitrary . . .

32 bit, high byte first

<desired id>Desired Unit ID

16 bit, high byte first

Responses

0x06—Bad parameter response

0x15—Set Unit ID Response

(0x15) Set Channel Response

<response>=0x15

<body>=<empty>

(0x16) Get Unit ID Request

<command>=0x16

<body>=<empty>

Responses

0x0d—Get Channel Response

(0x17) Get Unit ID Response

<response>=0x17

<body>=<current channel>

<current ID>Unit ID

16 bit, high byte first

B. Packet Level

(MMU to Gateway):

<0x55> <0x55> <length> <Gateway ID> <command>

<body> <checksum>

<0x55> literal header bytes

<length>length—count of bytes starting with gateway ID through checksum. Total length minus 4

16 bits, high byte first

<Gateway ID> Gateway address—test=0x1235

16 bits, high byte first

<command> Command to execute

16 bits, high byte first

(Gateway to MMU):

<0xAA> <0xAA> <length> <Gateway ID> <command>

<body> <checksum>

<0xAA> literal header bytes

<length> length—count of bytes starting with gateway ID through checksum. Total length minus 4

16 bits, high byte first

<Gateway ID> Gateway address—test=0x1235

16 bits, high byte first

<command> Command response

16 bits, high byte first

In the foregoing specification, the disclosure has been described with reference to specific exemplary embodiments

16

thereof. It will be evident that various modifications may be made thereto without departing from the broader spirit and scope as set forth in the following claims. The specification and drawings are, accordingly, to be regarded in an illustrative sense rather than a restrictive sense.

What is claimed is:

1. A method, comprising:

attempting to communicate, from a first local management unit of a plurality of local management units, on a first active channel at a predetermined frequency with a master management unit, each of the plurality of local management units coupled to control a respective solar module of a plurality of solar modules;

determining if communication with the master management unit on the first active channel has been established;

in response to a determination that the communication on the first active channel has not been established, attempting to communicate on a second active channel with the master management unit, the second active channel having a frequency different from the first active channel; determining if communication with the master management unit on the second active channel has been established; and

after communication with the master management unit has been established, restarting the first local management unit and subsequently communicating with the master management unit at a frequency other than the predetermined frequency.

2. The method of claim 1, further comprising after the communication on the second active channel has been established, receiving a first communication from the master management unit.

3. The method of claim 2, wherein the first communication comprises an instruction, the method further comprising executing the instruction on the first local management unit.

4. The method of claim 1, wherein the plurality of local management units are connected in series.

5. The method of claim 1, wherein the plurality of local management units are connected in parallel.

6. The method of claim 2, wherein the communication on the first active channel is at the predetermined frequency used by the master management unit for establishing communication with new local management units.

7. The method of claim 1, further comprising:

communicating from the first local management unit to the master management unit an identification code associated with the first local management unit; and

receiving a profile from the master management unit, the profile corresponding to the identification code.

8. The method of claim 7, further comprising in response to receiving the identification code, retrieving, via the master management unit, the profile from a database that includes a plurality of different profiles suitable for configuration of local management units.

9. The method of claim 1, wherein the first local management unit comprises an antenna, and the attempting to communicate on the first active channel comprises sending a wireless signal via the antenna.

10. The method of claim 2, further comprising:

after the communication on the second active channel has been established, determining that an error has occurred in communication with the master management unit; and

in response to the error, initiating an error treatment protocol for the first local management unit.

17

11. The method of claim 1, further comprising:
 in response to a determination that the communication on the second active channel has not been established, attempting to communicate on a third active channel with the master management unit, the third active channel having a frequency different from the first and second active channels;
 determining if communication with the master management unit on the third active channel has been established;
 in response to a determination that the communication on the third active channel has not been established, determining whether a predetermined number of available channels for communication with the master management unit has been exceeded; and
 in response to a determination that the predetermined number has been exceeded, initiating an error treatment protocol for the first local management unit.

12. A method, further comprising:
 waking up a first local management unit of a plurality of local management units, each of the plurality of local management units coupled to control a respective solar module of a plurality of solar modules;
 after the waking up, determining whether the first local management unit is storing a configuration profile;
 in response to a determination that the first local management unit is not storing the configuration profile, communicating to the master management unit a first identification code associated with the first local management unit, including:
 attempting to communicate, from the first local management unit, on a first active channel with a master management unit;
 determining if communication with the master management unit on the first active channel has been established;
 in response to a determination that the communication on the first active channel has not been established, attempting to communicate on a second active channel with the master management unit, the second active channel having a frequency different from the first active channel; and
 determining if communication with the master management unit on the second active channel has been established;
 receiving a first profile from the master management unit, the first profile corresponding to the first identification code, and the first profile including a time period; and
 configuring the first local management unit using the first profile.

13. The method of claim 12, further comprising:
 after the communication on the second active channel has been established, receiving a first instruction from the master management unit;
 executing the first instruction on the first local management unit;
 after the executing the first instruction, waiting for the time period;
 after the waiting, communicating with the master management unit to receive a second instruction; and
 executing the second instruction on the first local management unit.

14. The method of claim 12, further comprising:
 establishing communication with the master management unit from a second local management unit of the plurality of local management units; and

18

communicating to the master management unit a second identification code associated with the second local management unit;
 receiving a second profile from the master management unit, the second profile corresponding to the second identification code; and
 configuring the second local management unit using the second profile.

15. local management unit, comprising:
 memory storing software instructions; and
 a controller coupled to the memory, the controller configured via the software instructions to execute a method comprising:
 controlling, under supervision by a master management unit, a first solar module of a plurality of solar modules, the master management unit coupled to supervise a plurality of local management units, wherein the plurality of local management units are coupled by a power bus, and each one of the plurality of local management units controls a respective one of the plurality of solar modules,
 in response to a determination that the first local management unit is not storing a configuration profile, attempting to communicate with the master management unit, determining if communication with the master management unit on a first active channel has been established, in response to a determination that communication with the master management unit has not been established on the first active channel, attempting to communicate with the master management unit on a second active channel, the second active channel having a frequency different from the first active channel,
 determining if communication with the master management unit on the second active channel has been established,
 receiving, from the master management unit, a first configuration profile having a time period, and
 configuring the first local management unit using the first configuration profile.

16. The system of claim 15, further comprising a modem or wireless network interface to attempt to communicate with the master management unit on a first active channel.

17. The system of claim 15, wherein the plurality of local management units are configured to, under supervision of the master management unit, balance currents between the plurality of solar modules in the power bus.

18. A non-transitory computer-readable storage medium for tangibly storing thereon computer readable instructions, the instructions causing a data processing system to perform a method, the method comprising:
 attempting to communicate, from a first local management unit of a plurality of local management units, on a first active channel at a predetermined frequency with a master management unit, each of the plurality of local management units coupled to control a respective solar module of a plurality of solar modules;
 determining if communication with the master management unit on the first active channel has been established;
 in response to a determination that the communication on the first active channel has not been established, attempting to communicate on a second active channel with the master management unit, the second active channel having a frequency different from the first active channel; and

determining if communication with the master management unit on the second active channel has been established;

after communication with the master management unit has been established, restarting the first local management unit and subsequently communicating with the master management unit at a frequency other than the predetermined frequency. 5

19. The computer-readable storage medium of claim **18**, wherein the method further comprises: 10

communicating from the first local management unit to the master management unit an identification code associated with the first local management unit; and

receiving a profile from the master management unit, the profile corresponding to the identification code. 15

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