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Kageyama

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(45) **Date of Patent:** **Sep. 24, 2013**

(54) **ELECTRO-MECHANICAL TRANSDUCER, AN ELECTRO-MECHANICAL CONVERTER, AND MANUFACTURING METHODS OF THE SAME**

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(*) Notice: Subject to any disclaimer, the term of this patent is extended or adjusted under 35 U.S.C. 154(b) by 380 days.

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§ 371 (c)(1),
(2), (4) Date: **Jan. 7, 2011**
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(30) **Foreign Application Priority Data**
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Oct. 21, 2008 (JP) 2008-271288

(57) **ABSTRACT**
An electro-mechanical transducer contains a vibrating electrode (15b), a vibrating-electrode-insulating film (15a) disposed at a bottom surface of the vibrating electrode (15b), an electret layer (13) facing to the vibrating electrode (15b), an electret-insulating layer (14e) joined to a top surface of the electret layer (13), and a back electrode 17 in contact with a bottom surface of the electret layer (13). A microgap between ten nanometers and 100 micrometers is established between the vibrating-electrode-insulating film (15a) and electret-insulating layer (14e). A central line average roughness Ra of the vibrating electrode (15b), including a bending, is 1/10 or less of a gap width measured between the bottom surface of the vibrating electrode (15b) and the top surface of the electret layer (13).

(51) **Int. Cl.**
H04R 25/00 (2006.01)
(52) **U.S. Cl.**
USPC **381/191; 381/173; 381/178; 381/355**
(58) **Field of Classification Search**
USPC 381/113, 122, 173, 178, 191, 355
See application file for complete search history.

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14 Claims, 45 Drawing Sheets

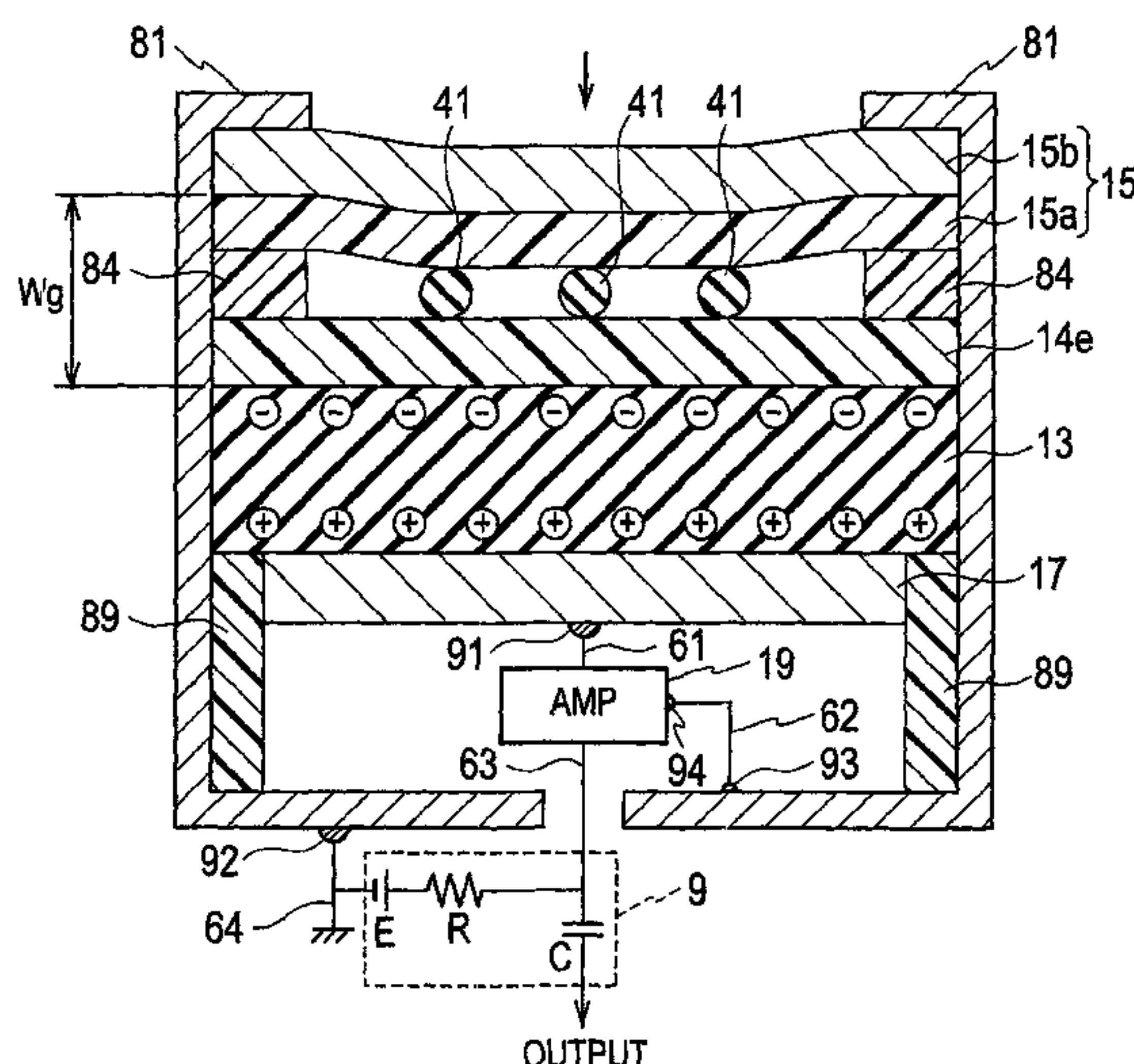


FIG. 1

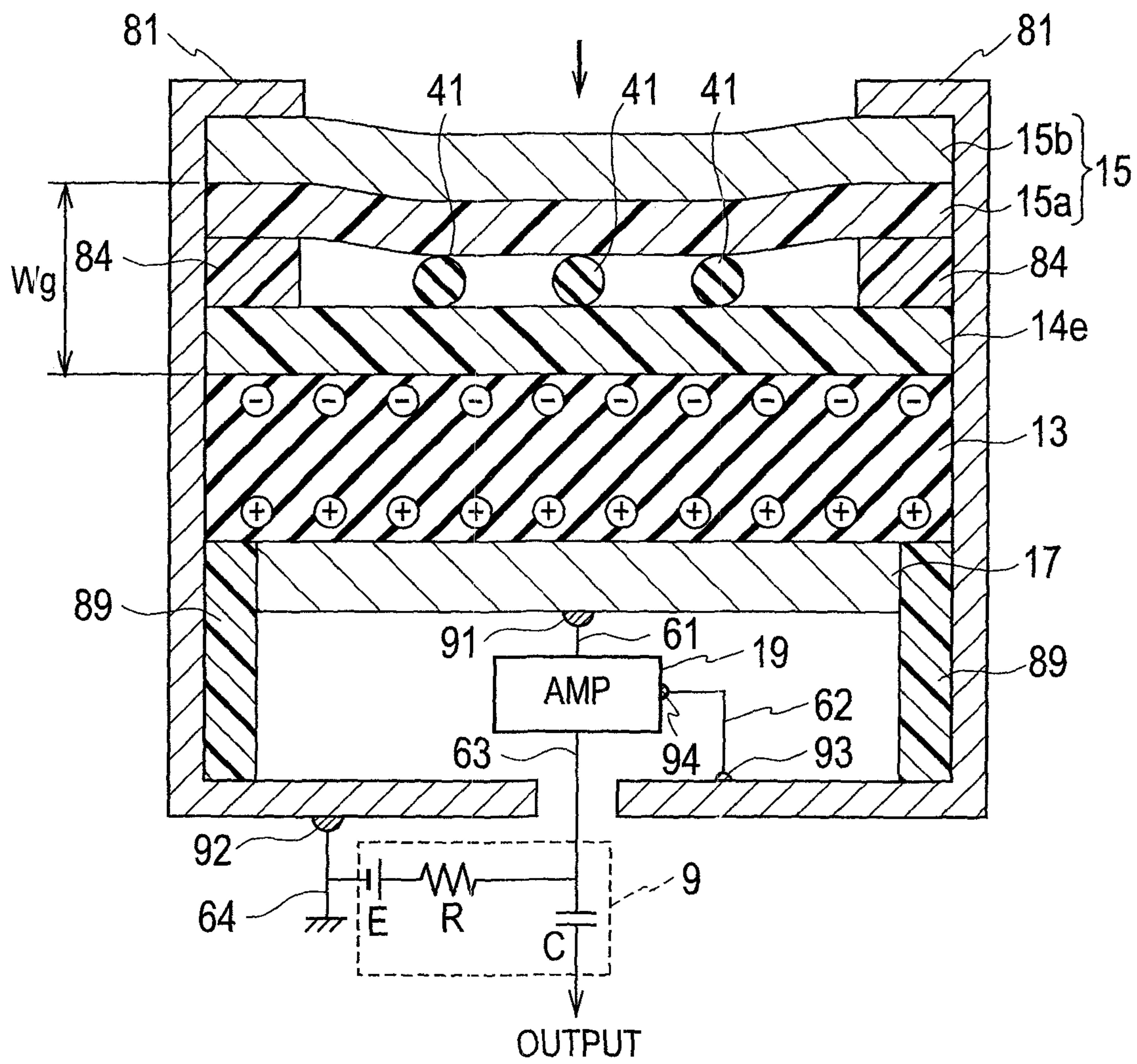


FIG. 2

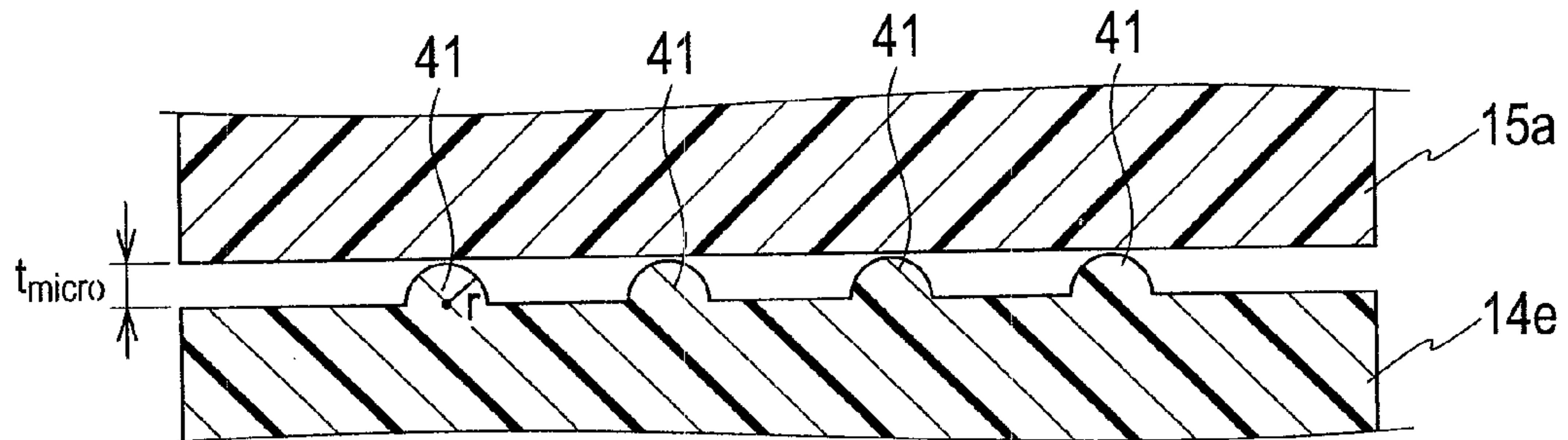


FIG. 3

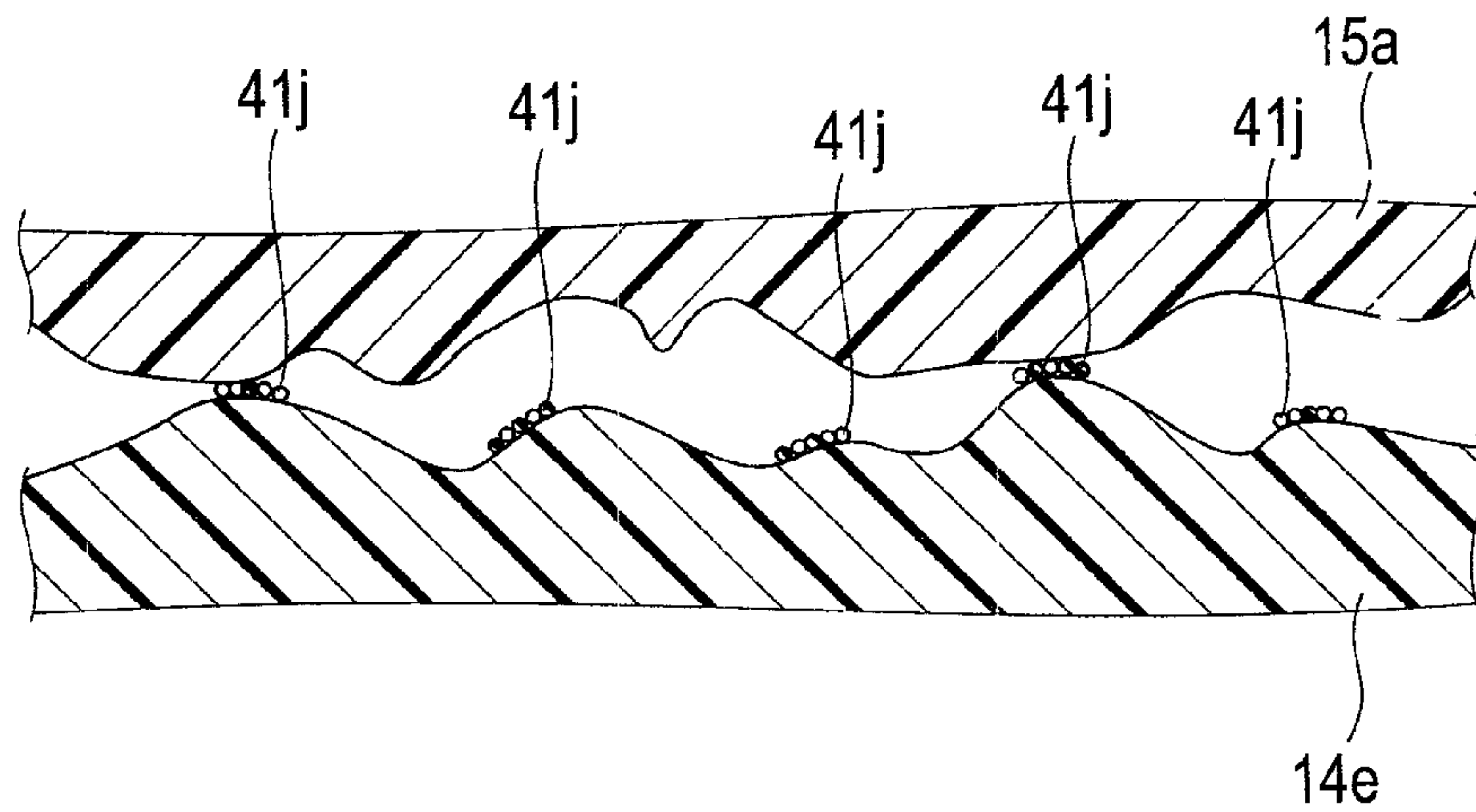


FIG. 4

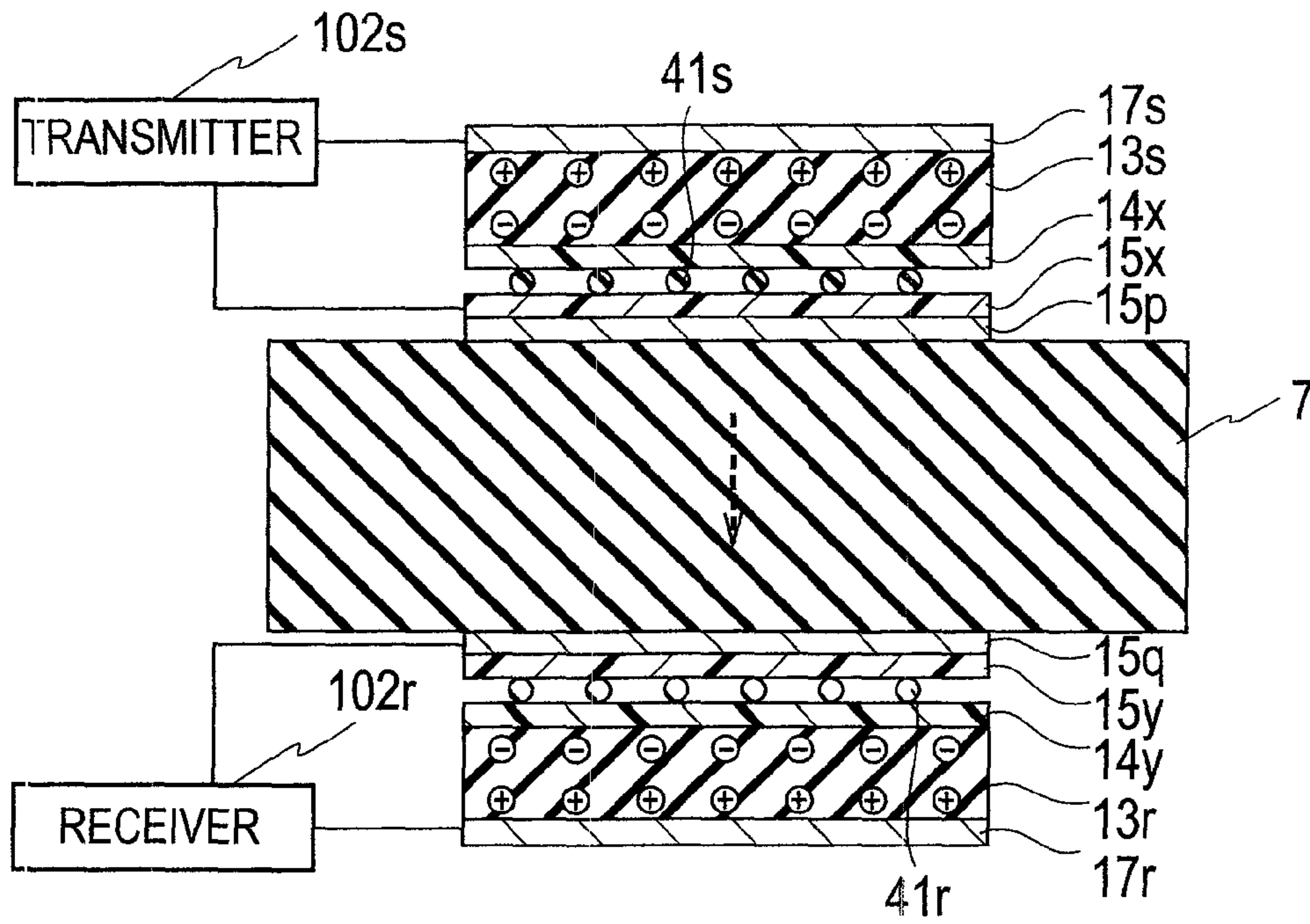


FIG. 5

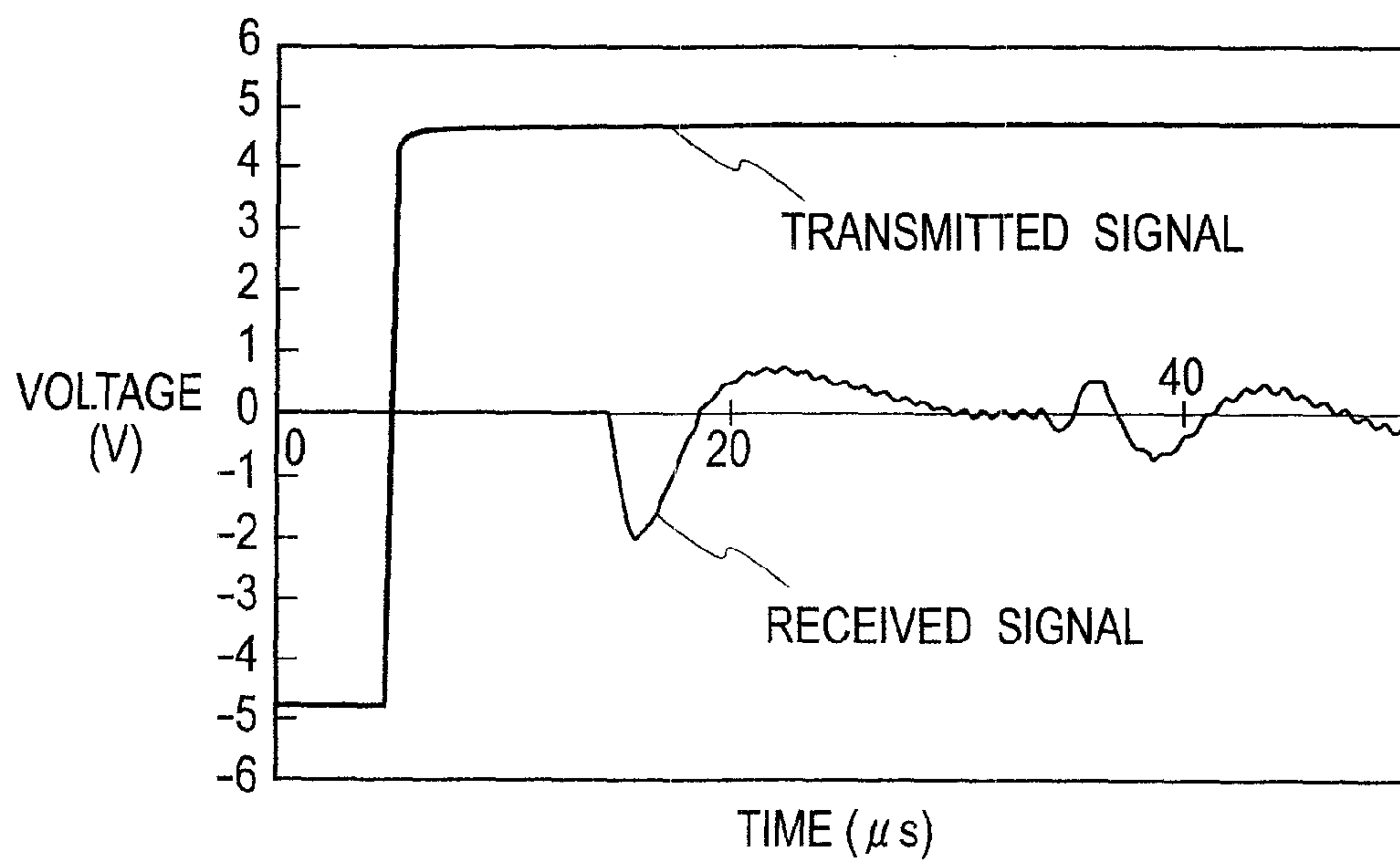


FIG. 6

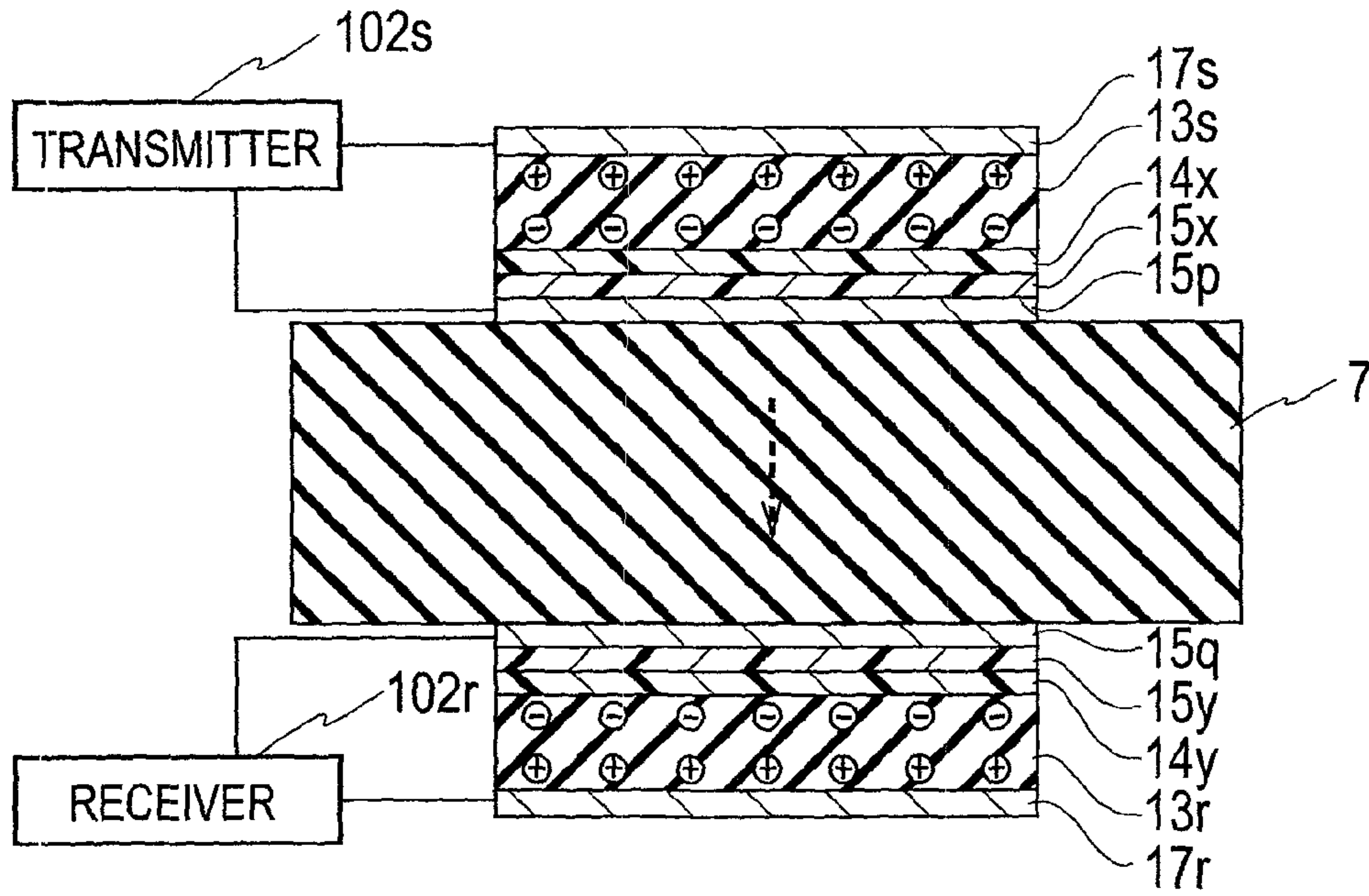


FIG. 7

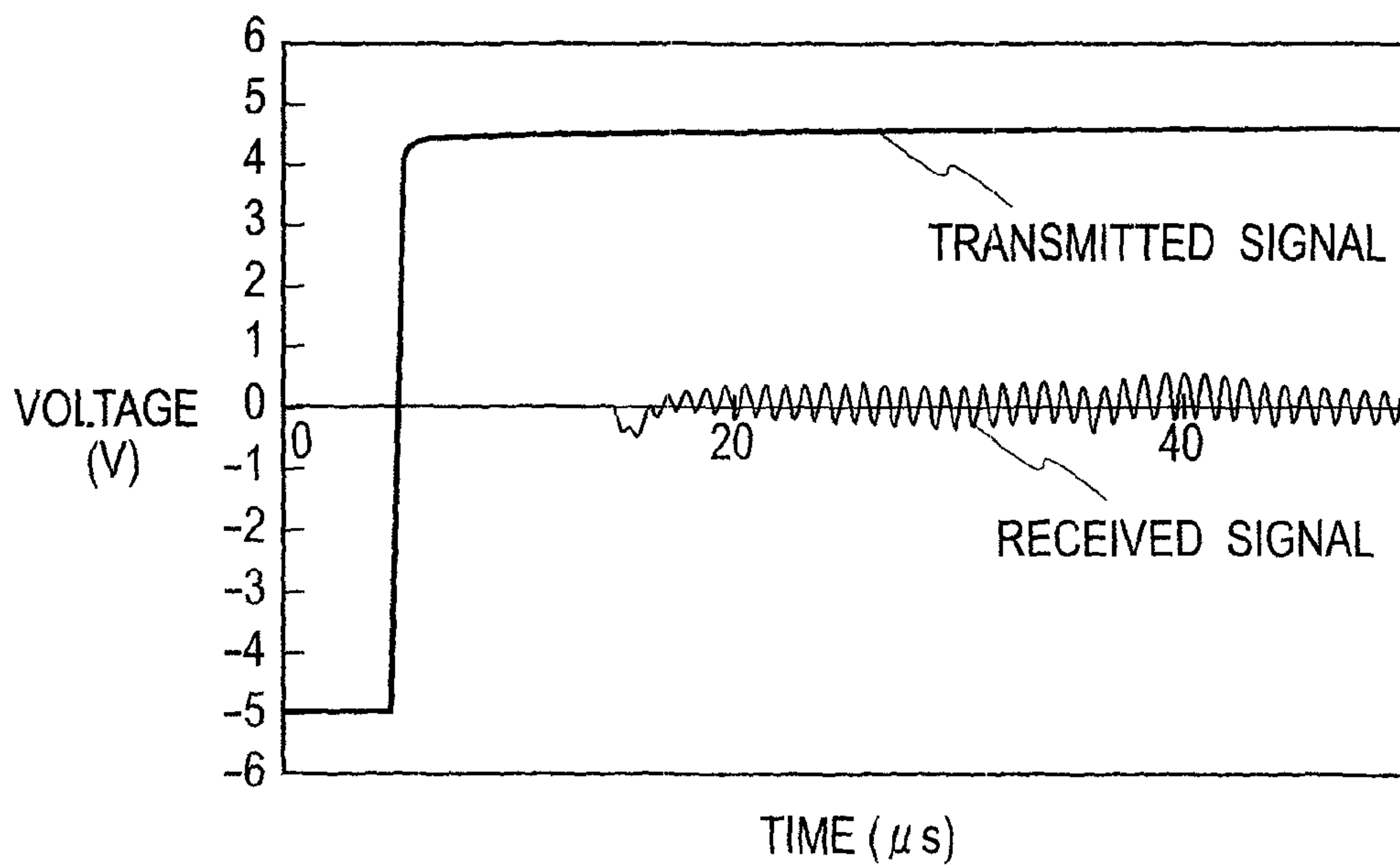


FIG. 8

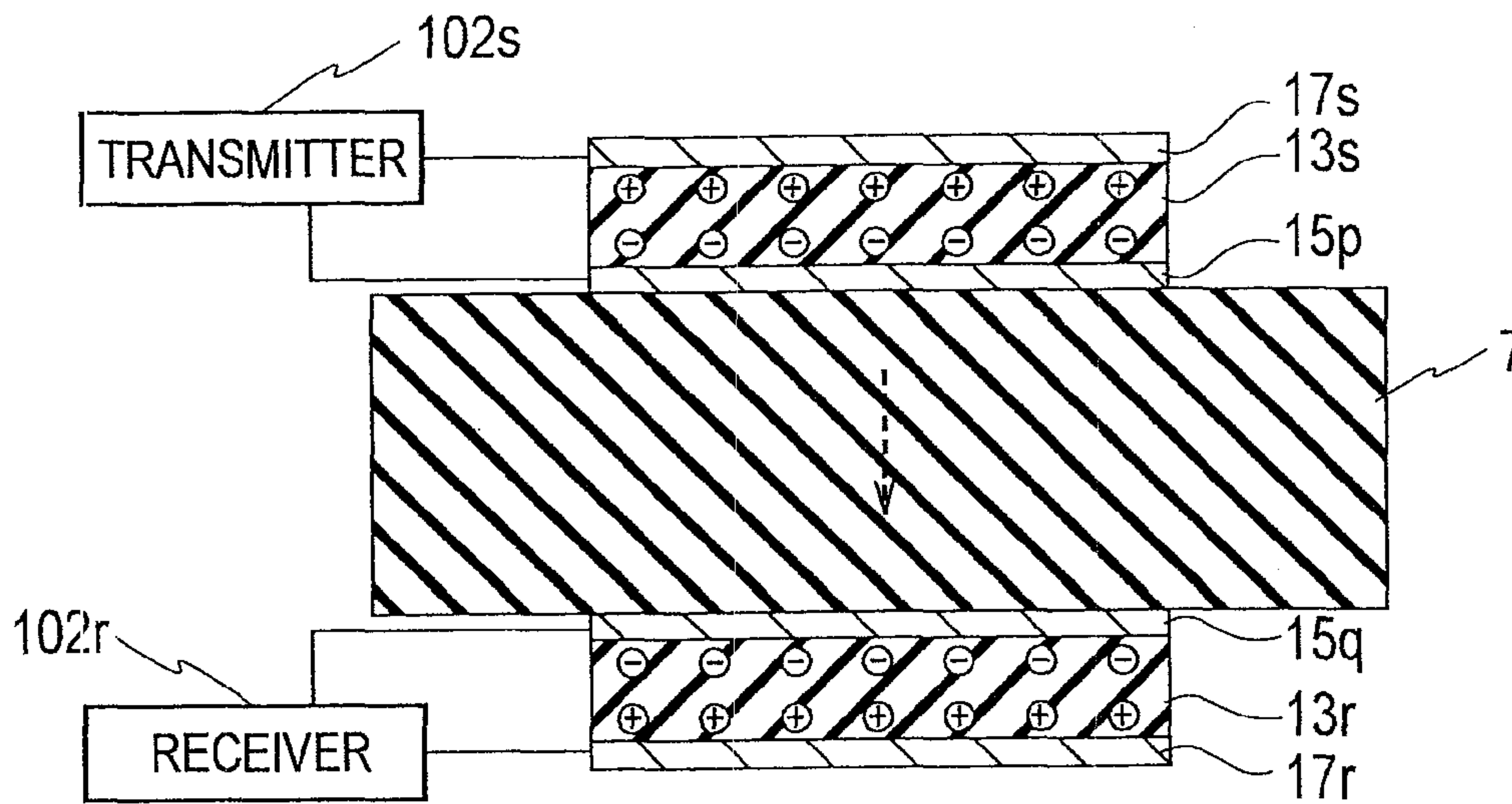


FIG. 9

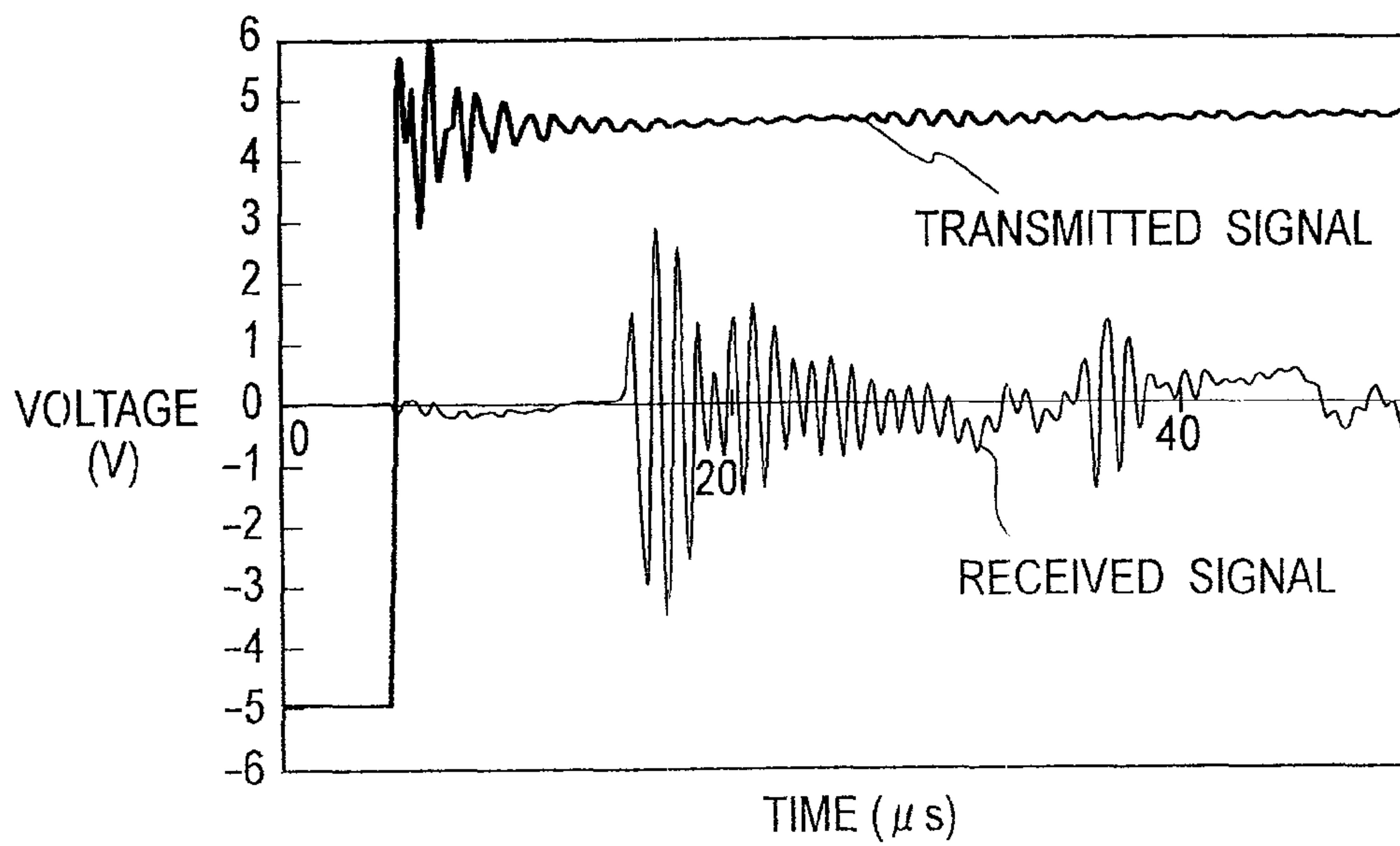


FIG. 10

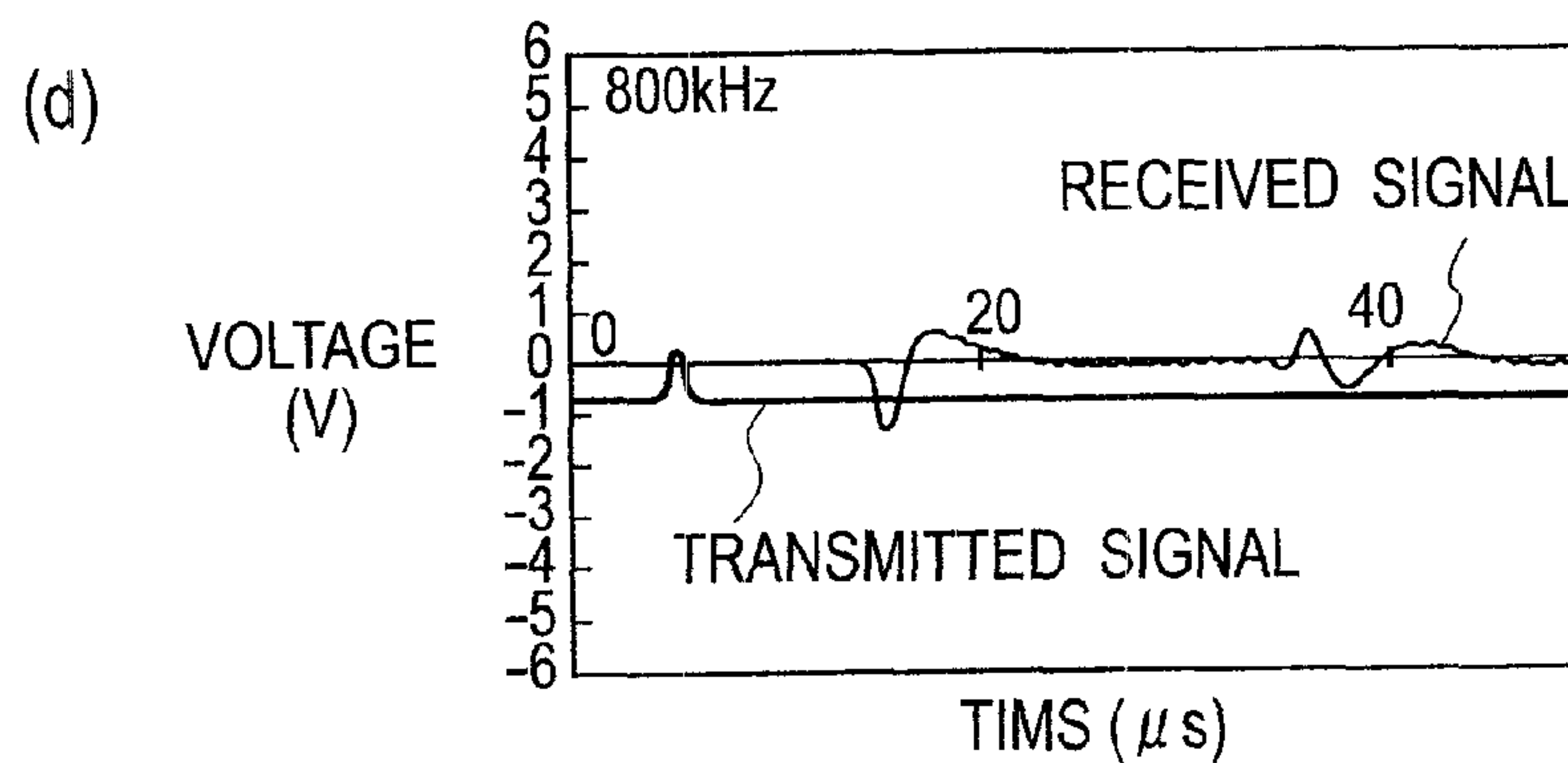
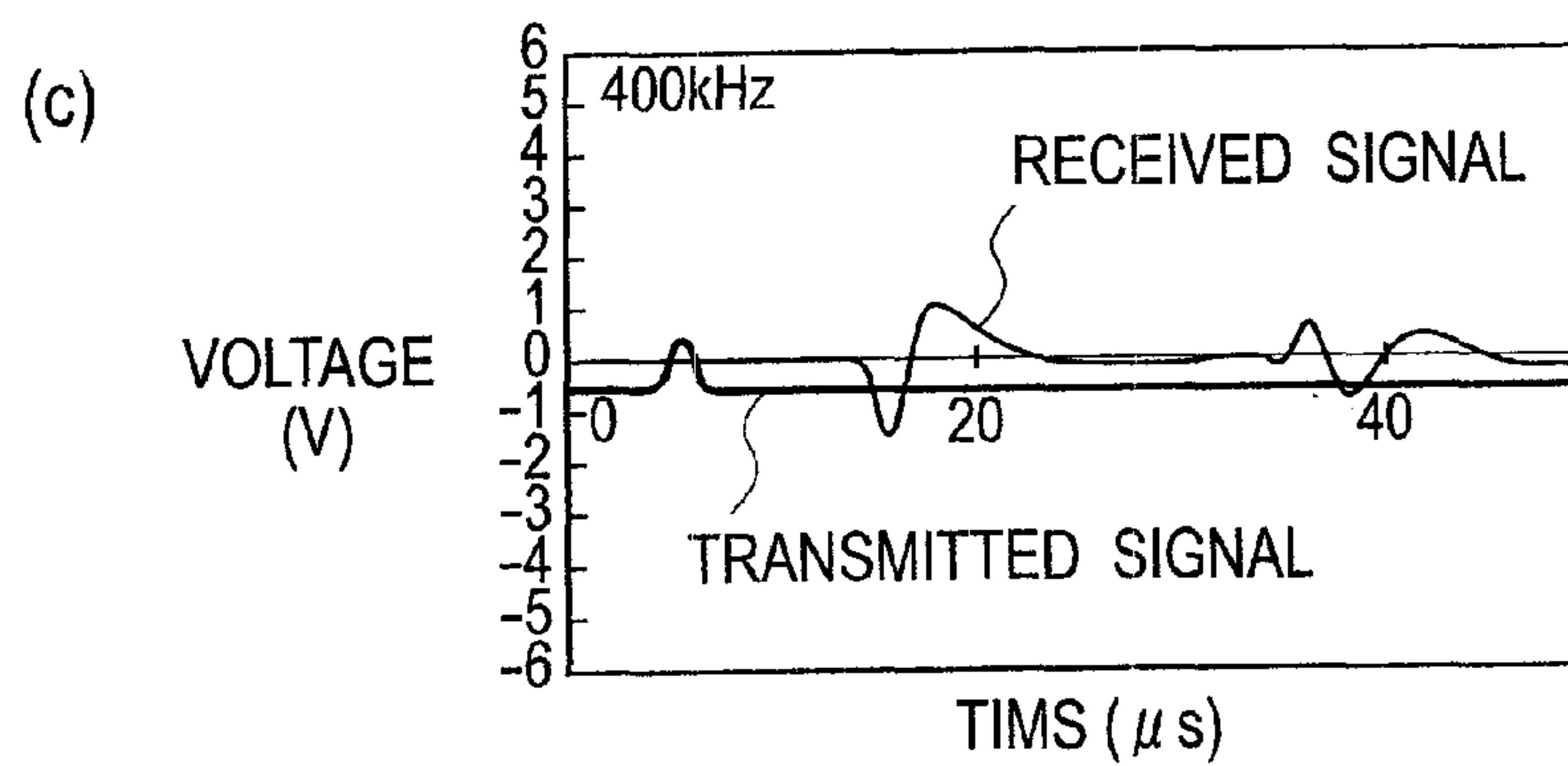
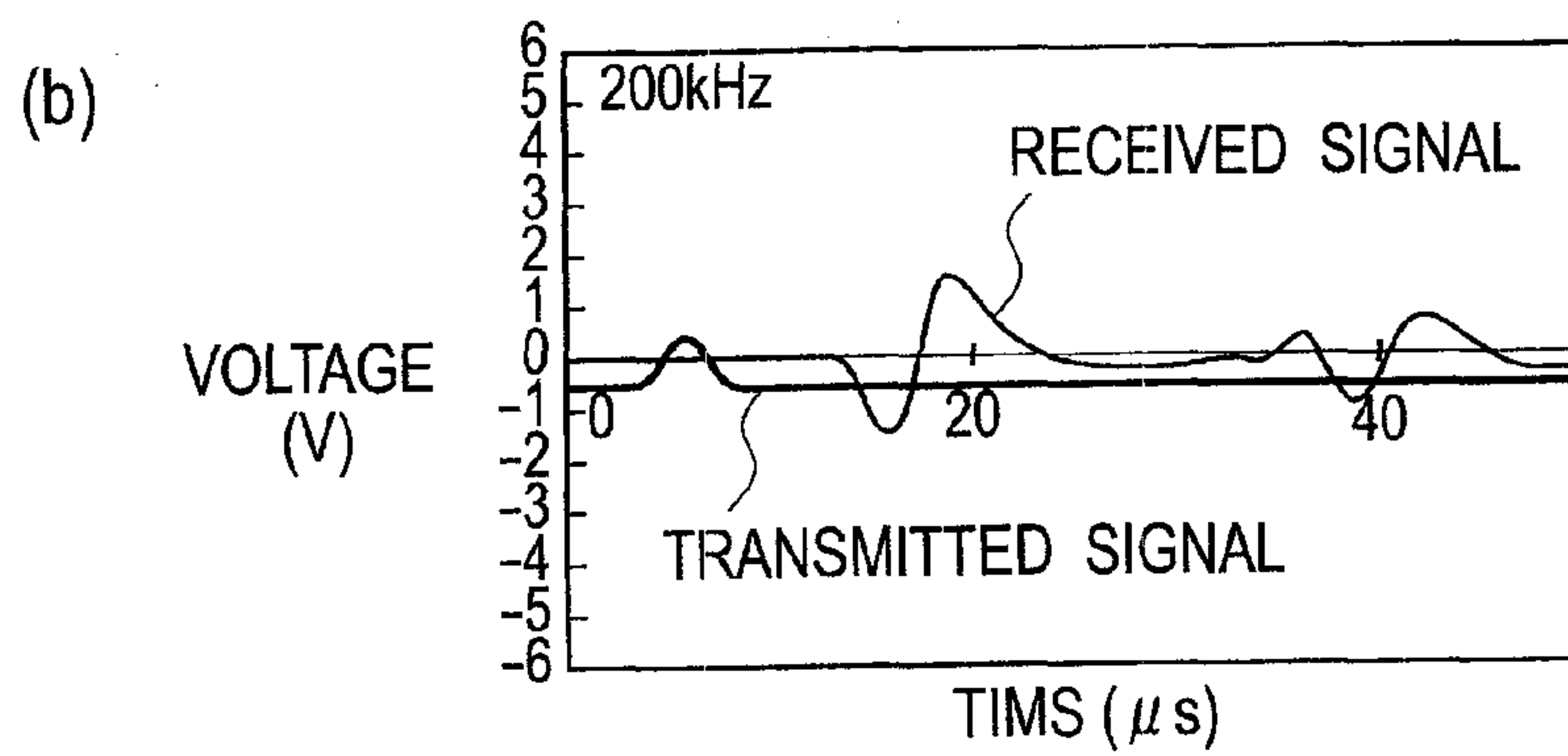
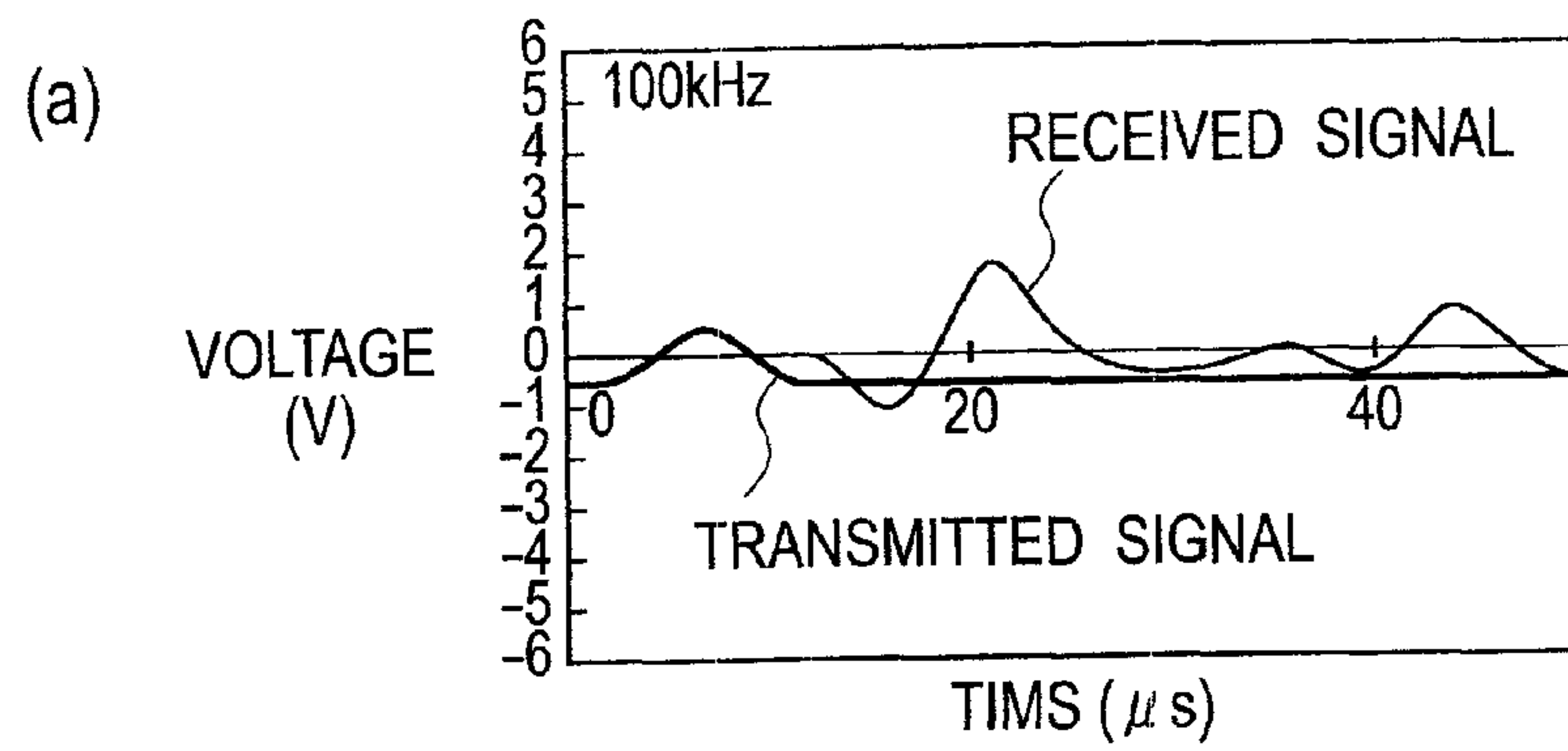
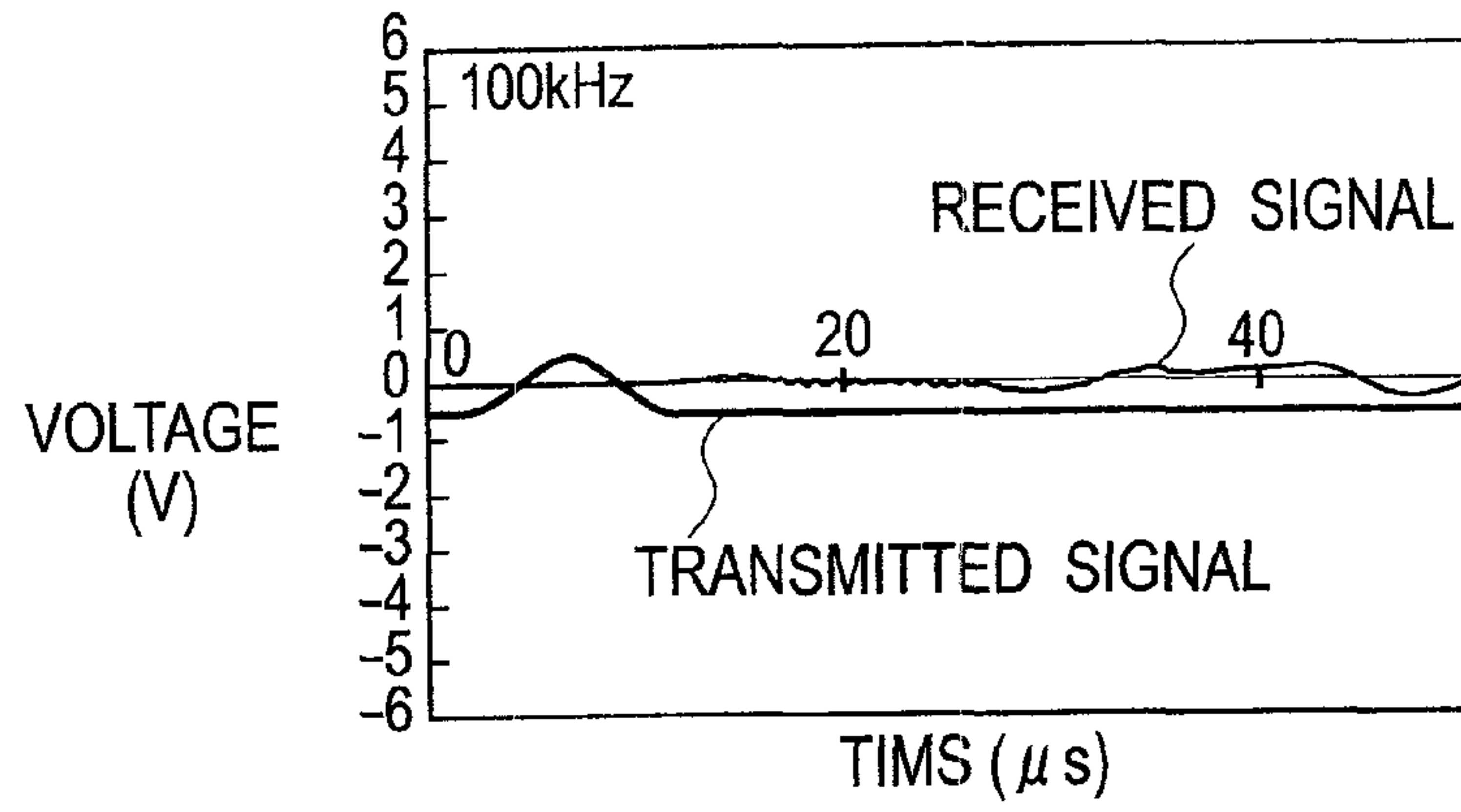
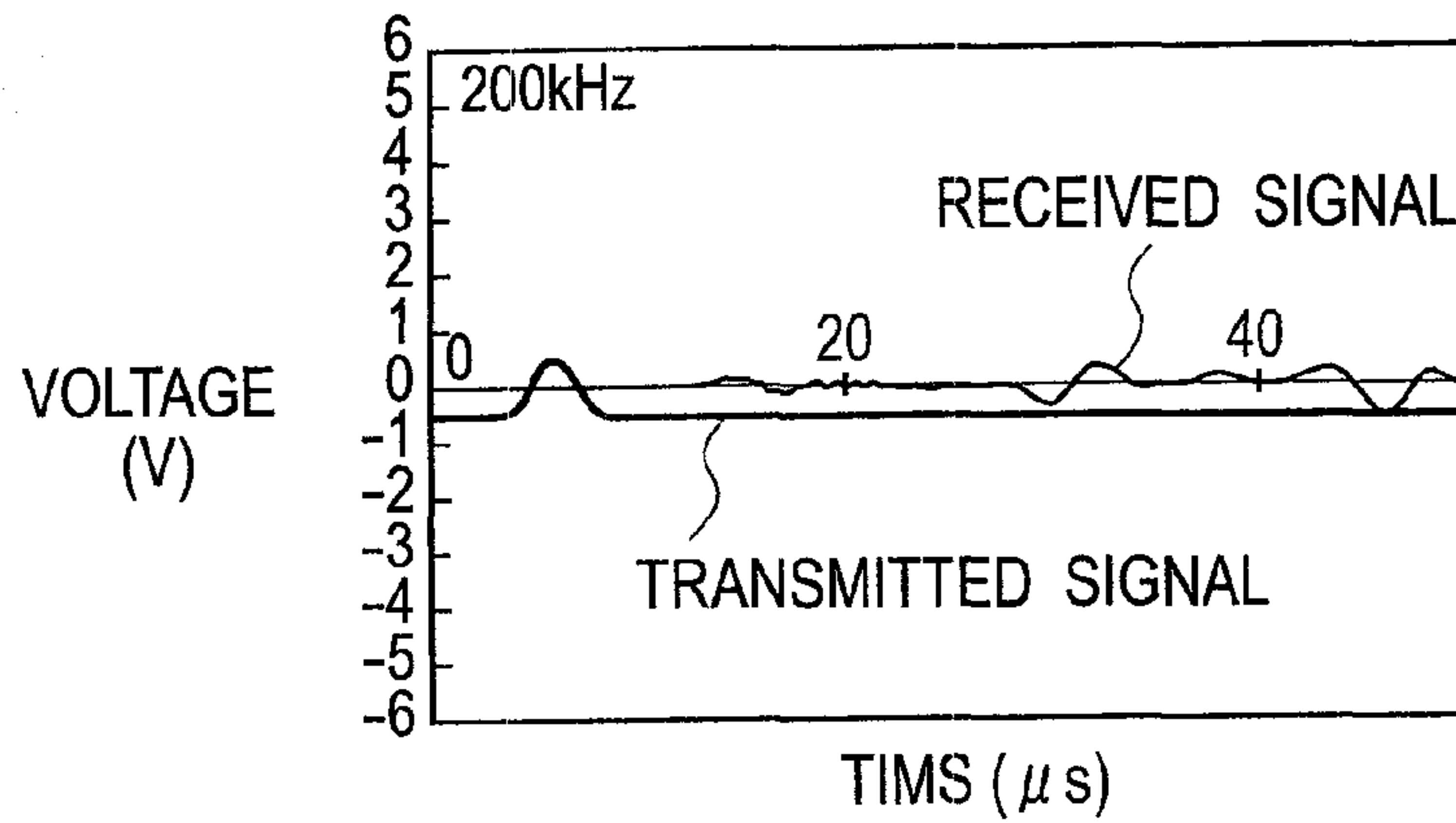


FIG. 11

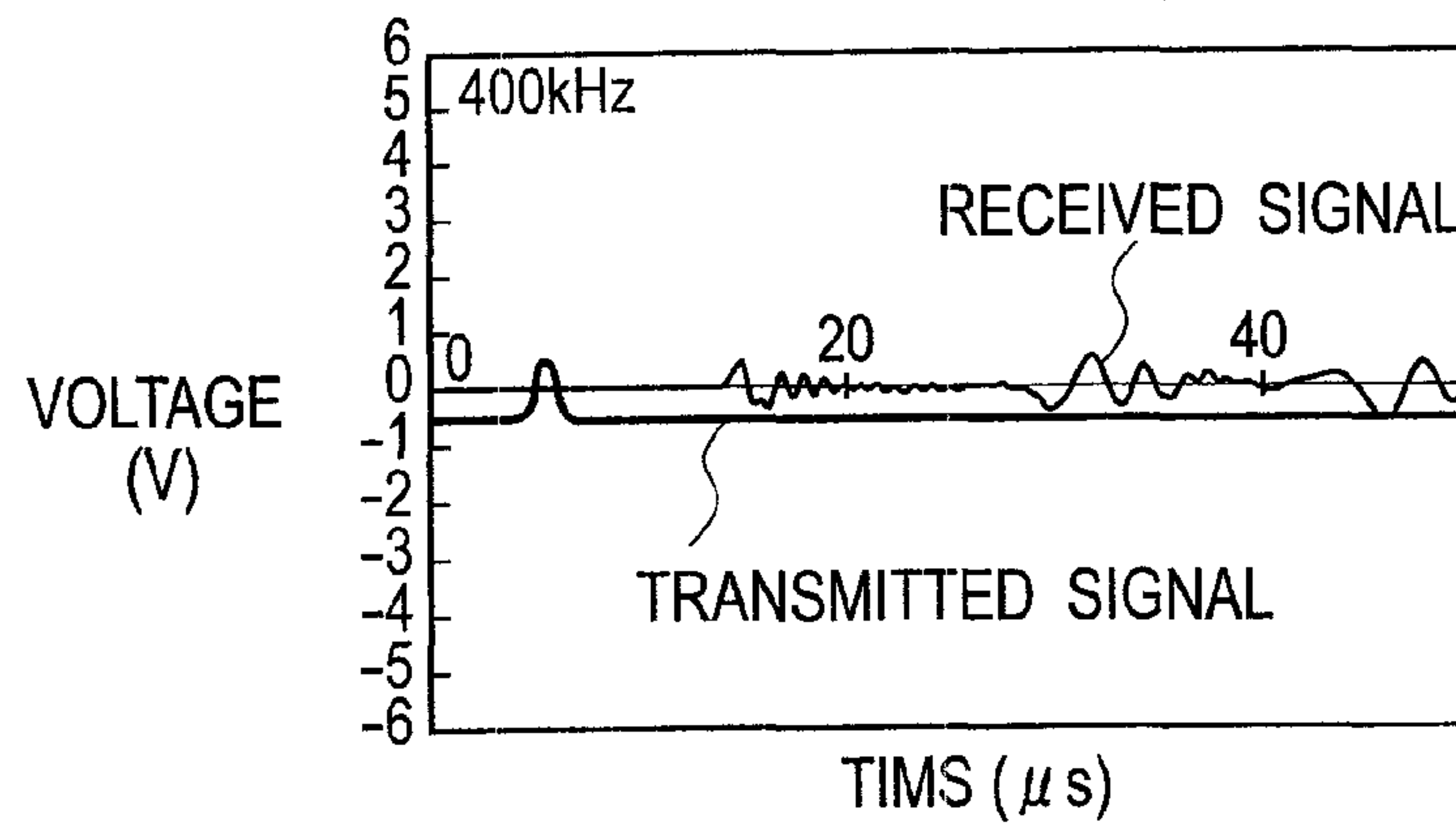
(a)



(b)



(c)



(d)

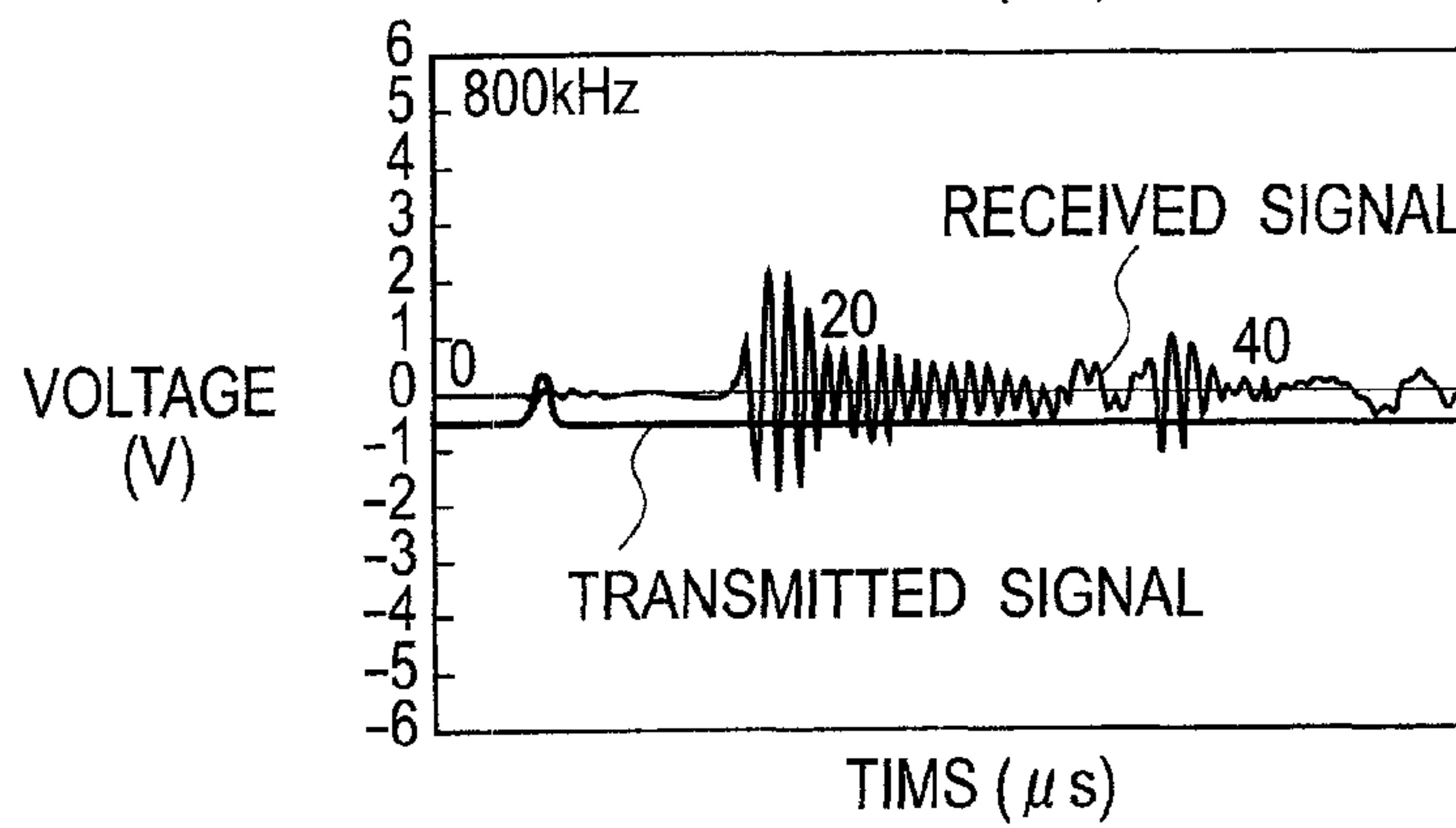


FIG. 12

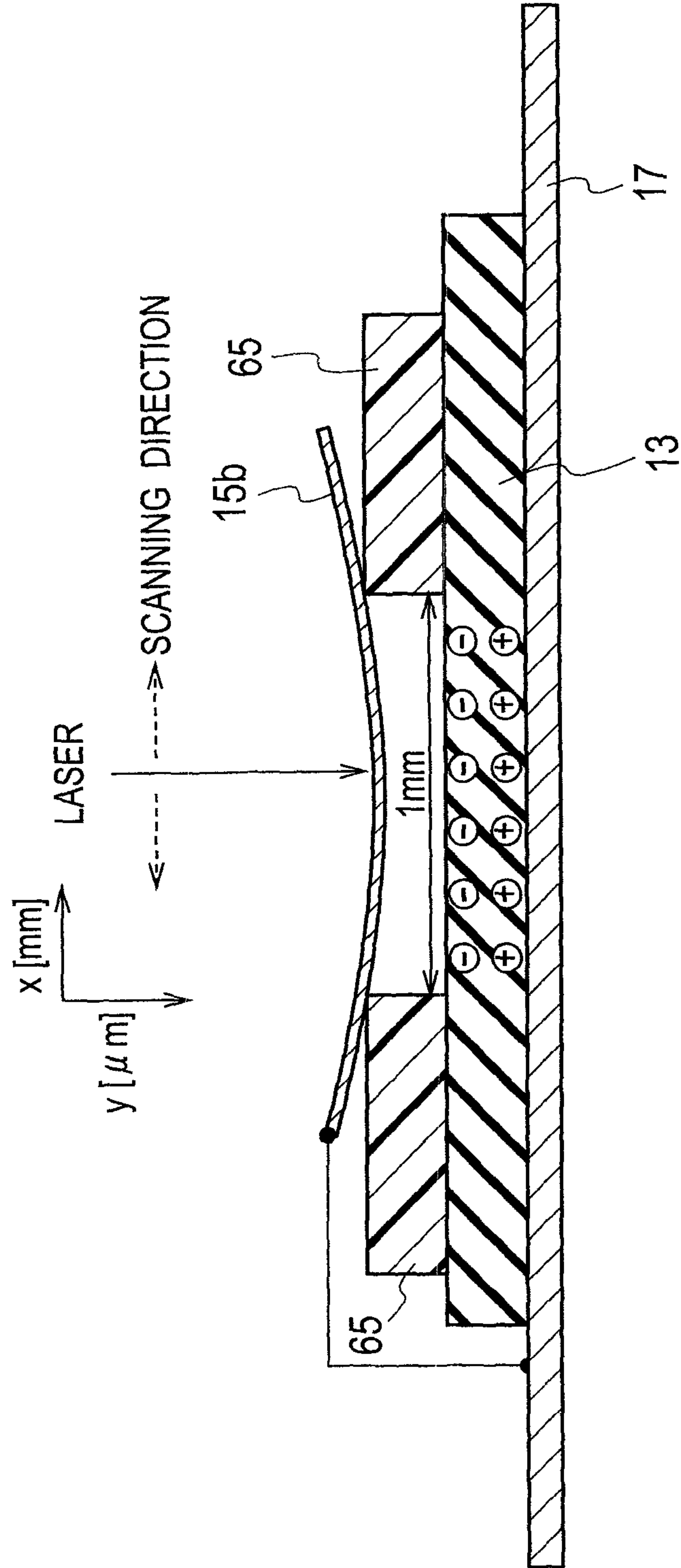
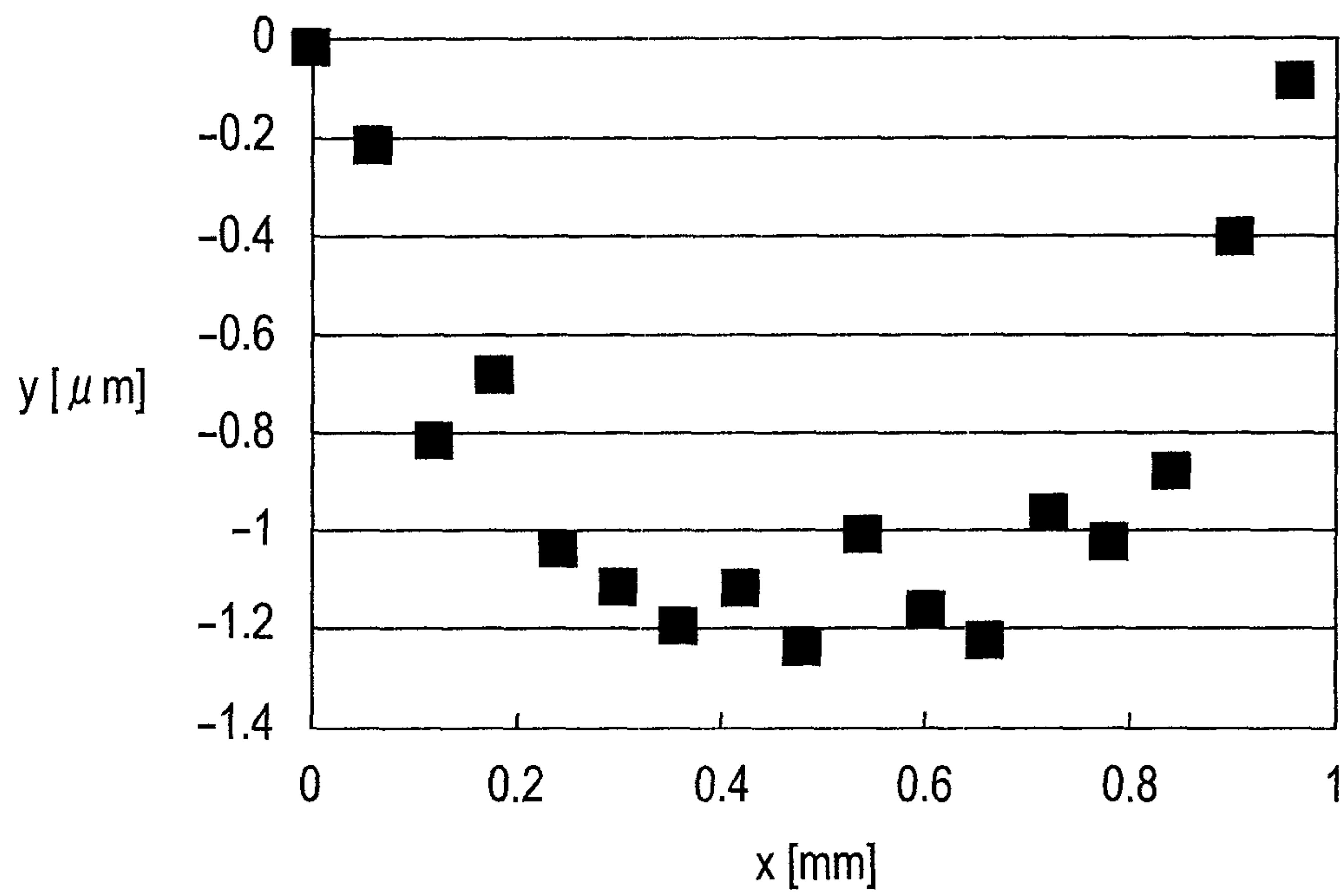


FIG. 13



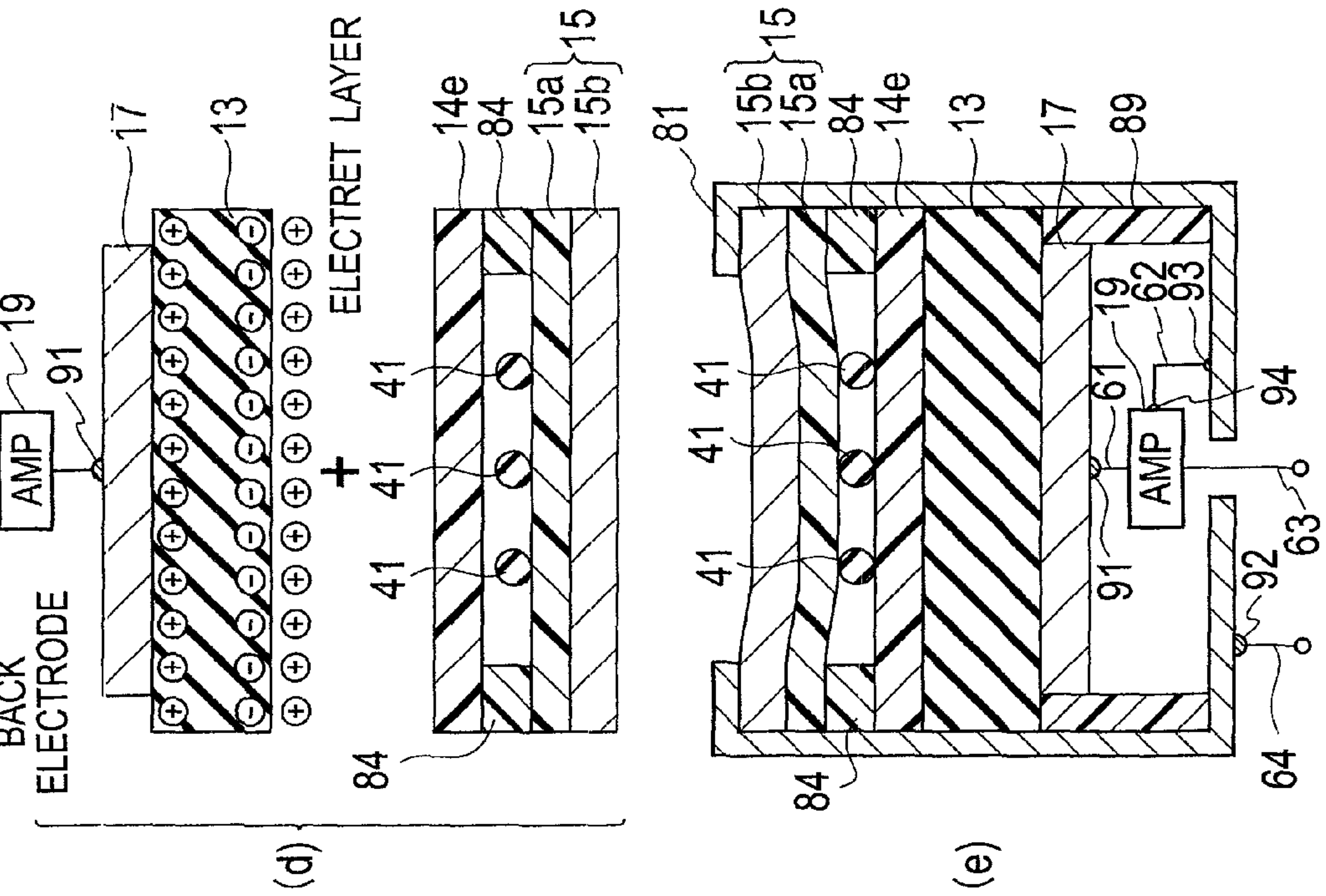


FIG. 14

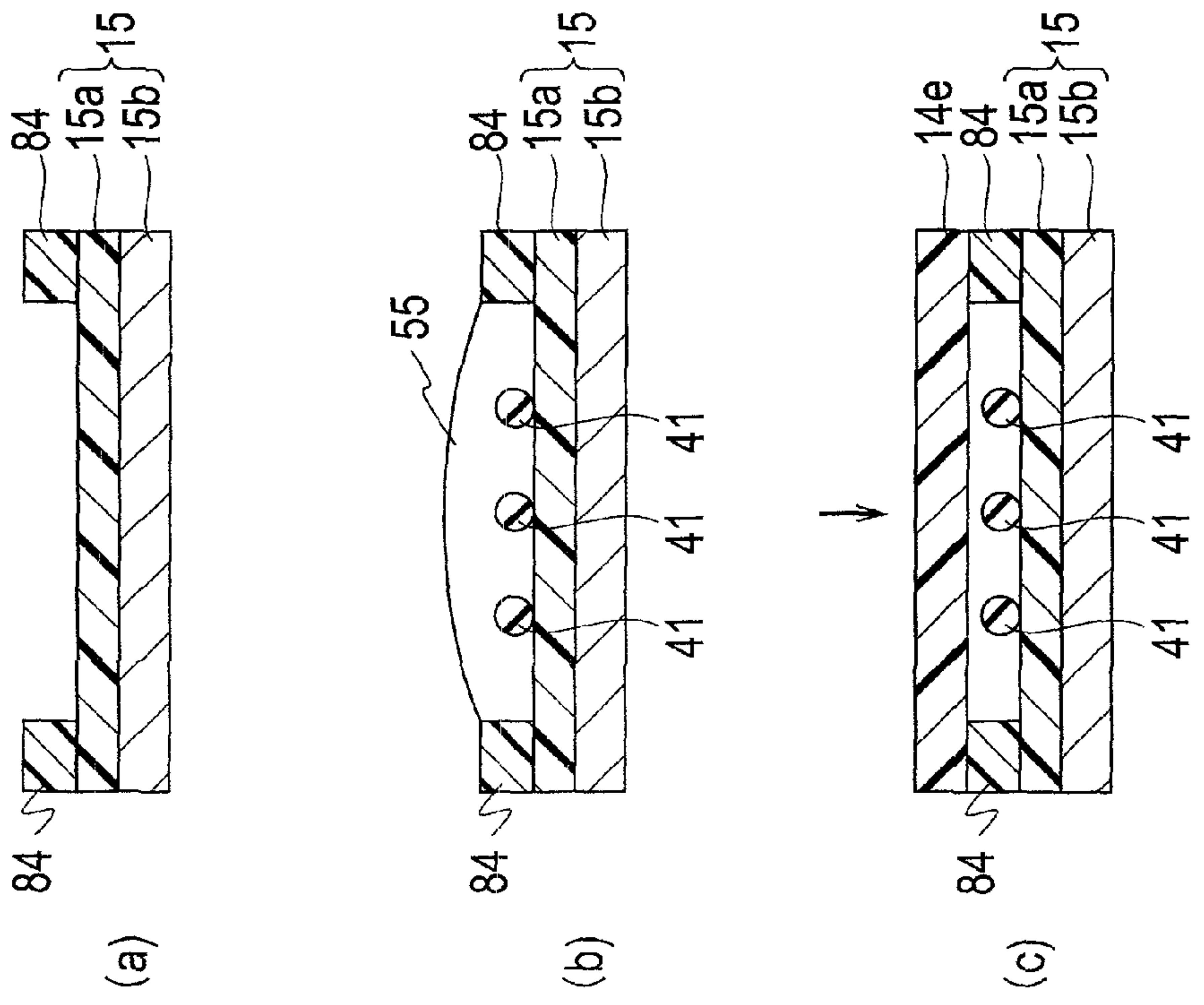


FIG. 15

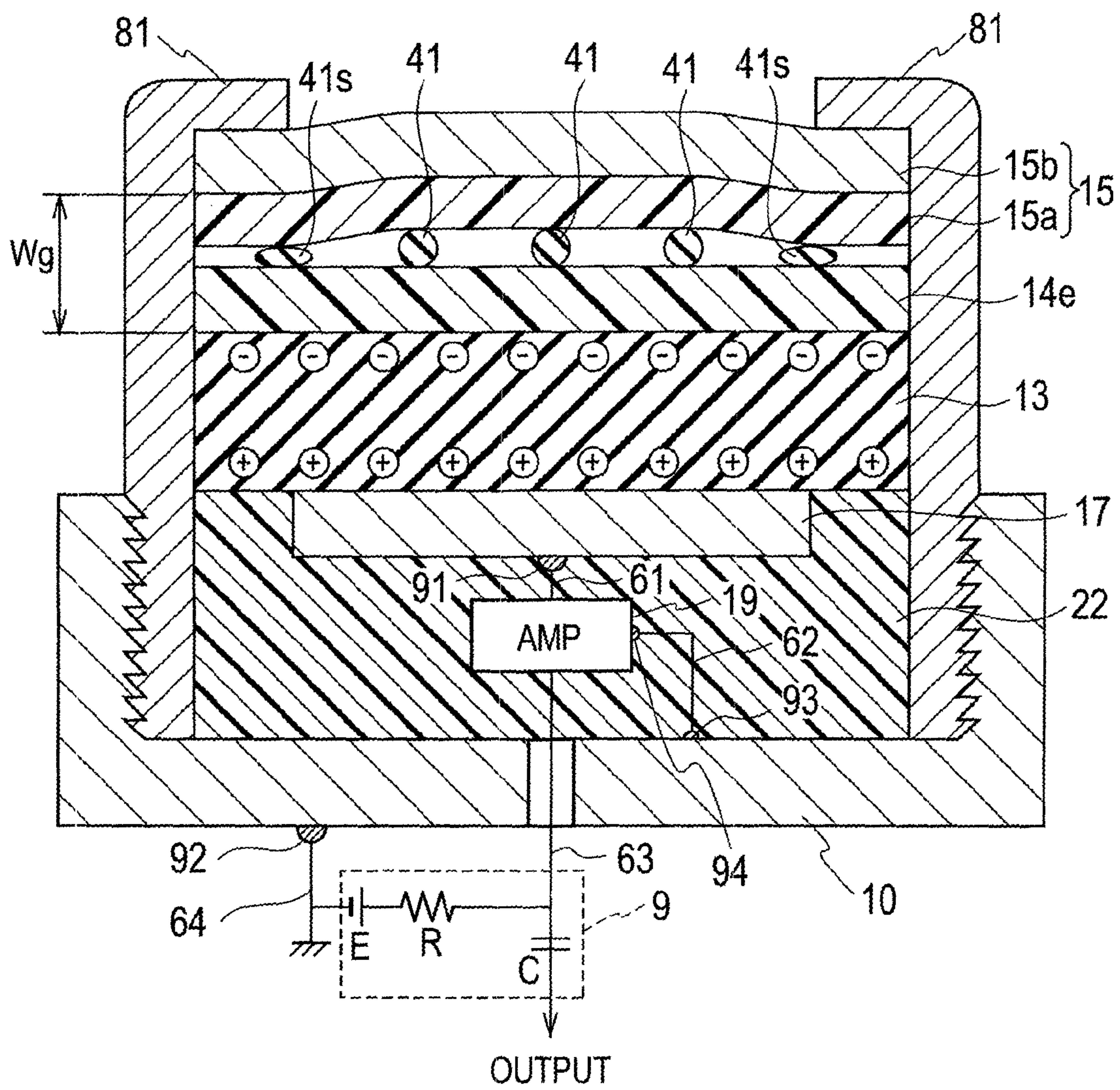


FIG.16

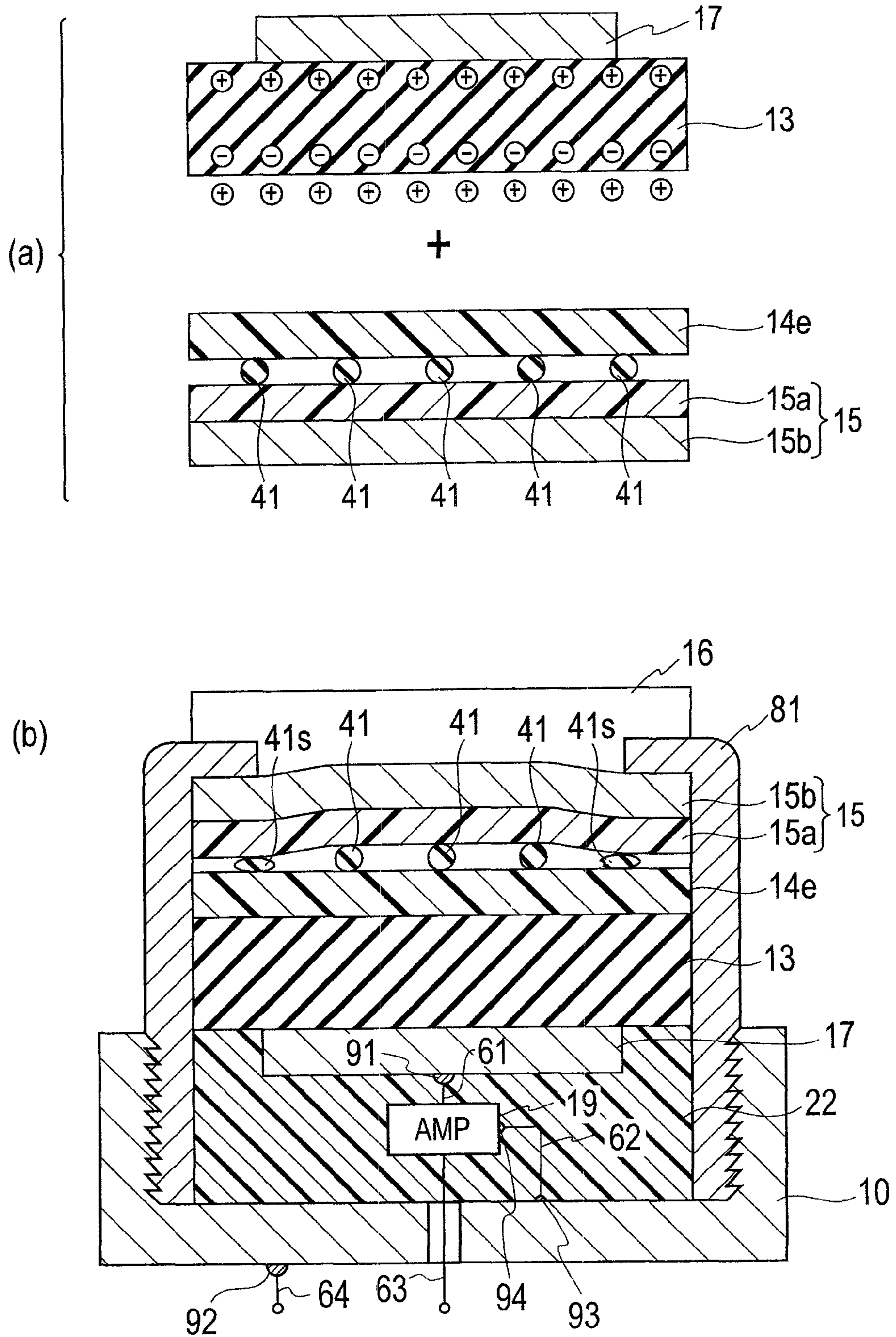


FIG. 17

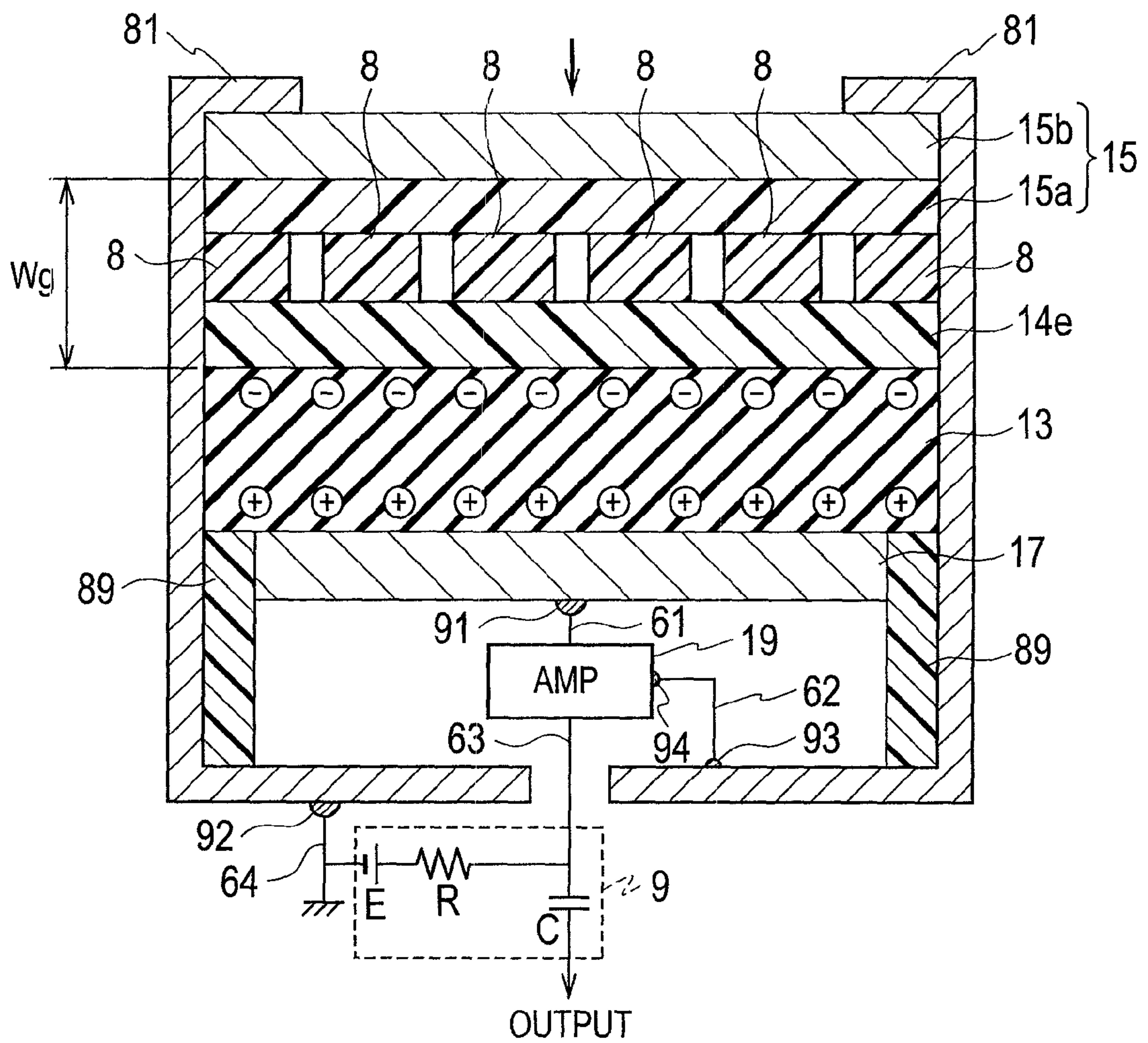


FIG. 18

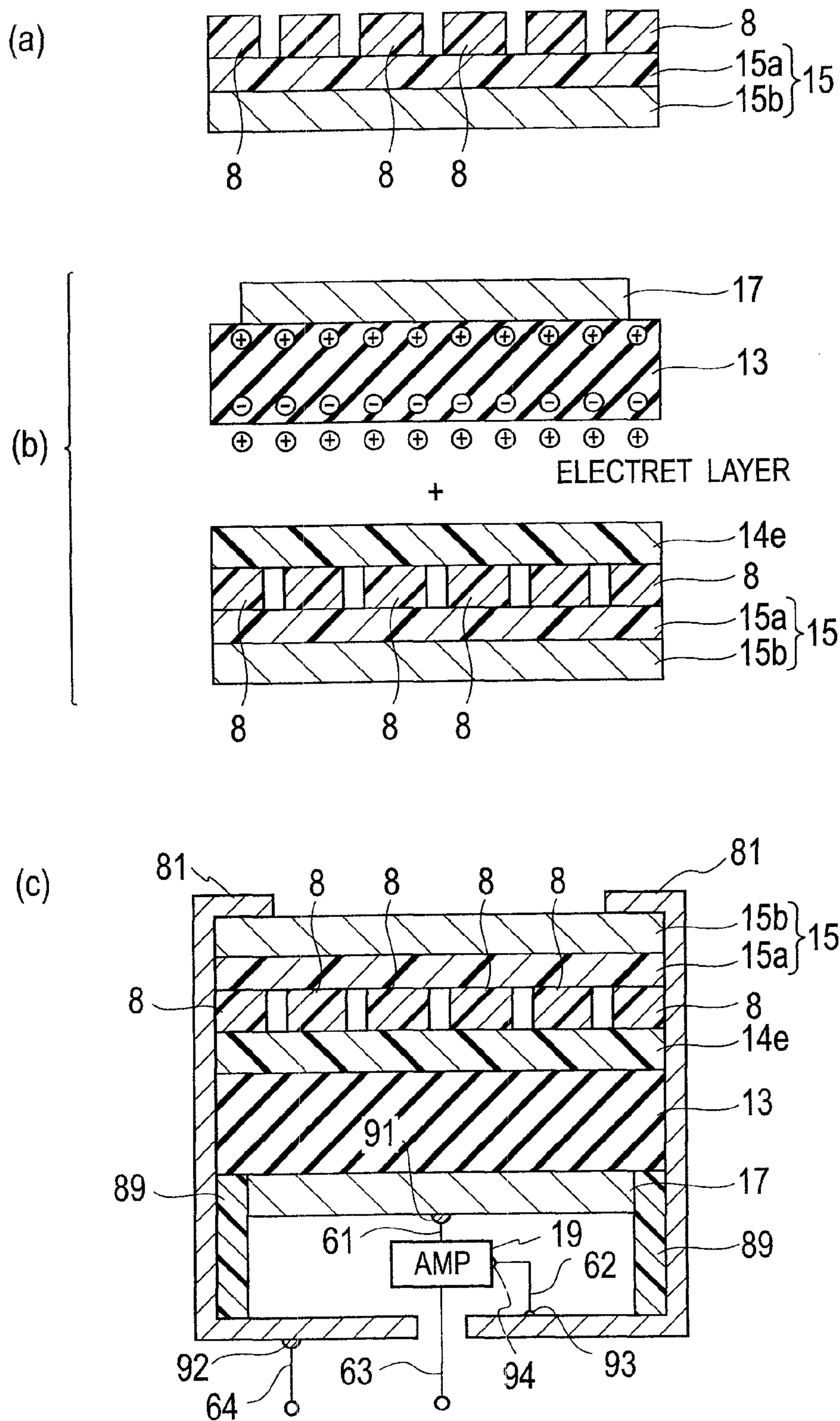


FIG. 19

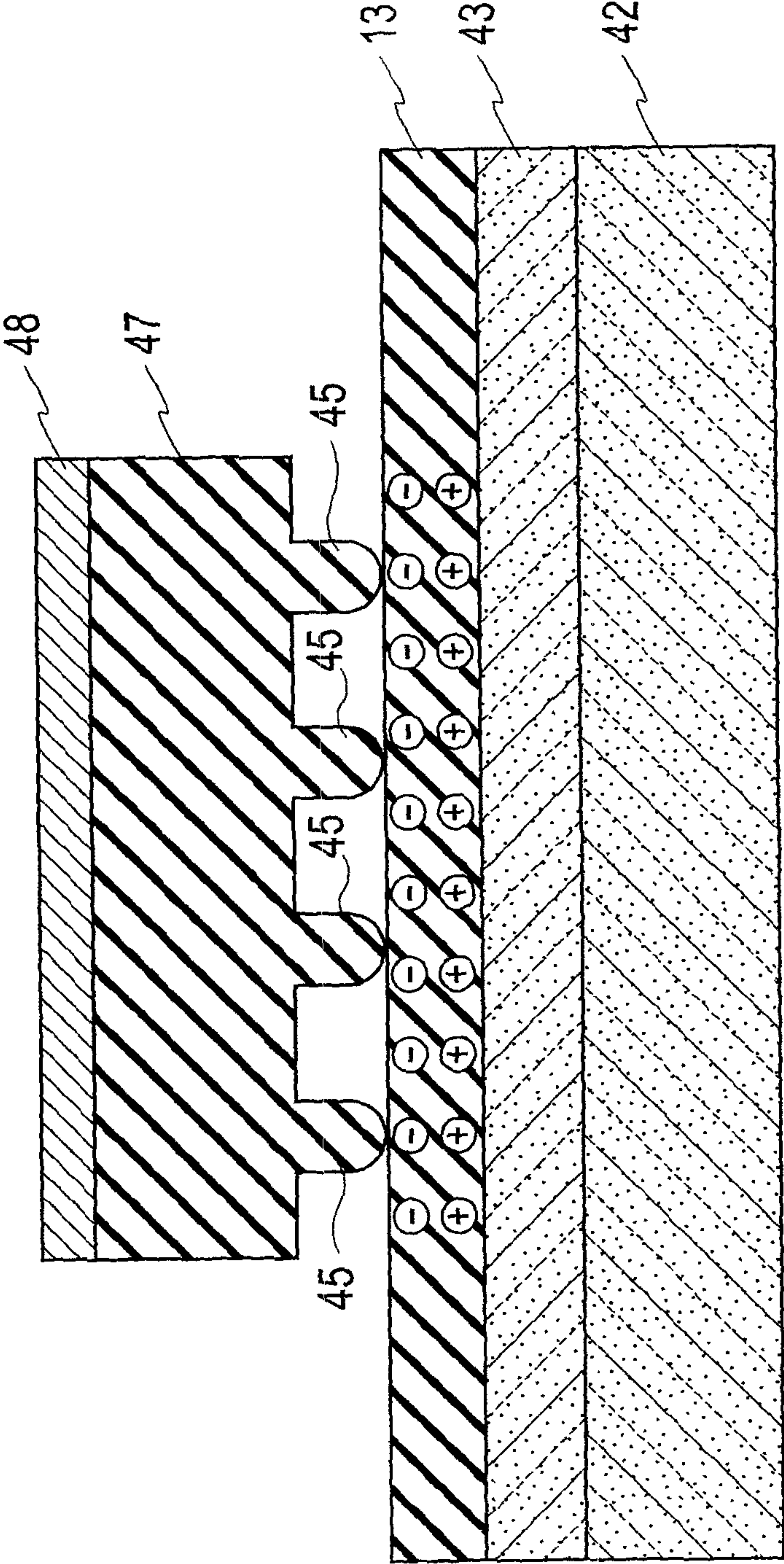


FIG. 20

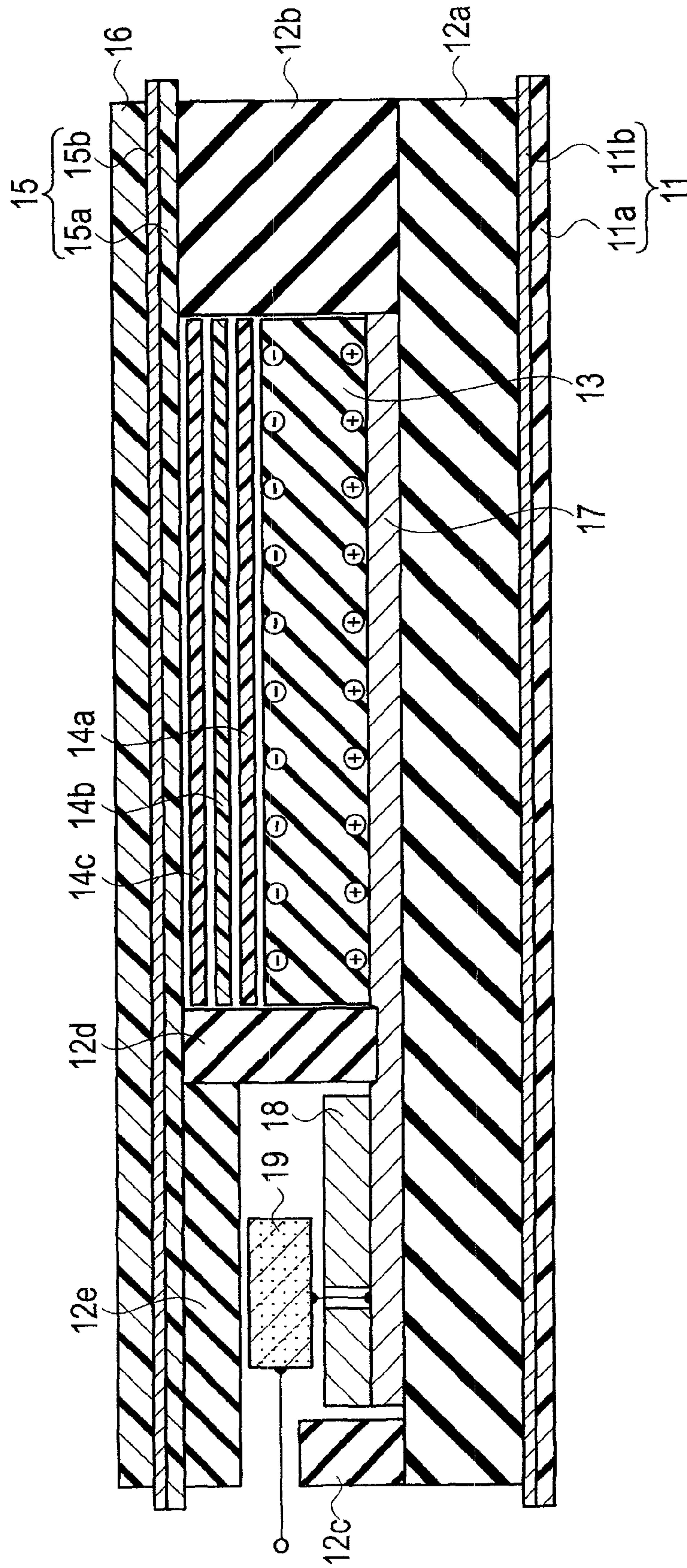


FIG. 21

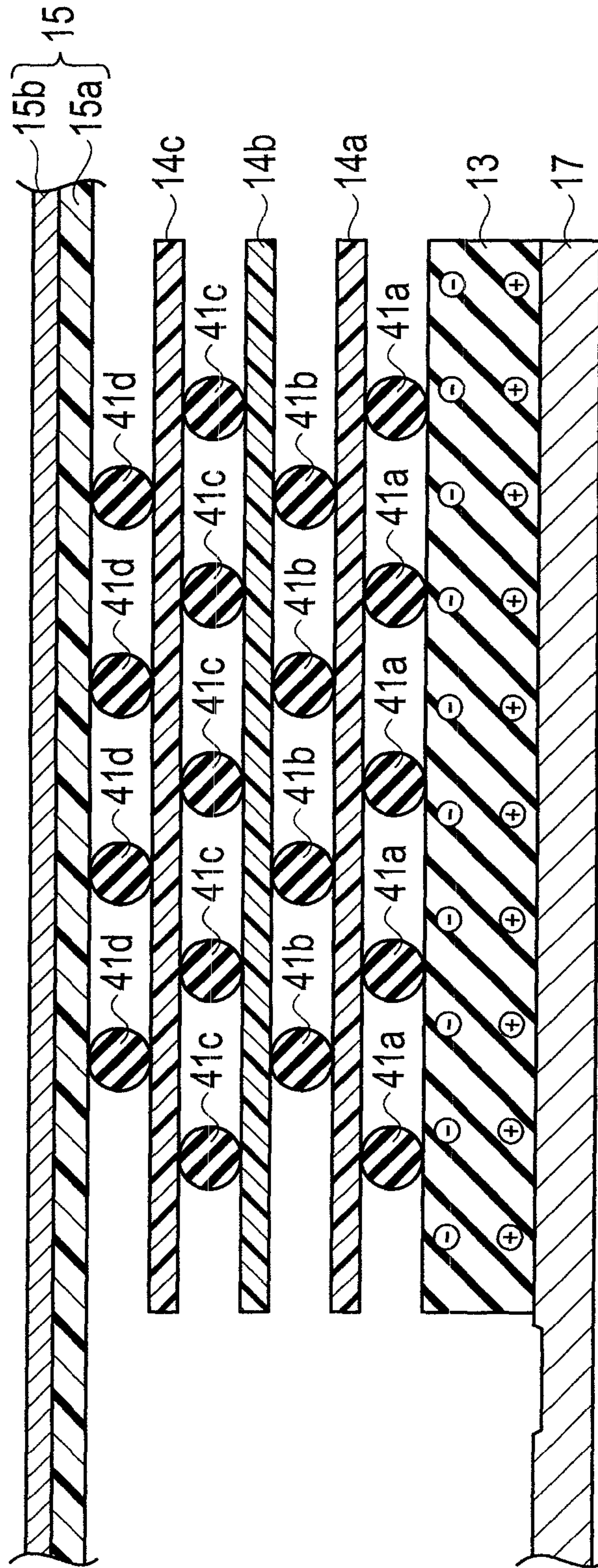


FIG. 22

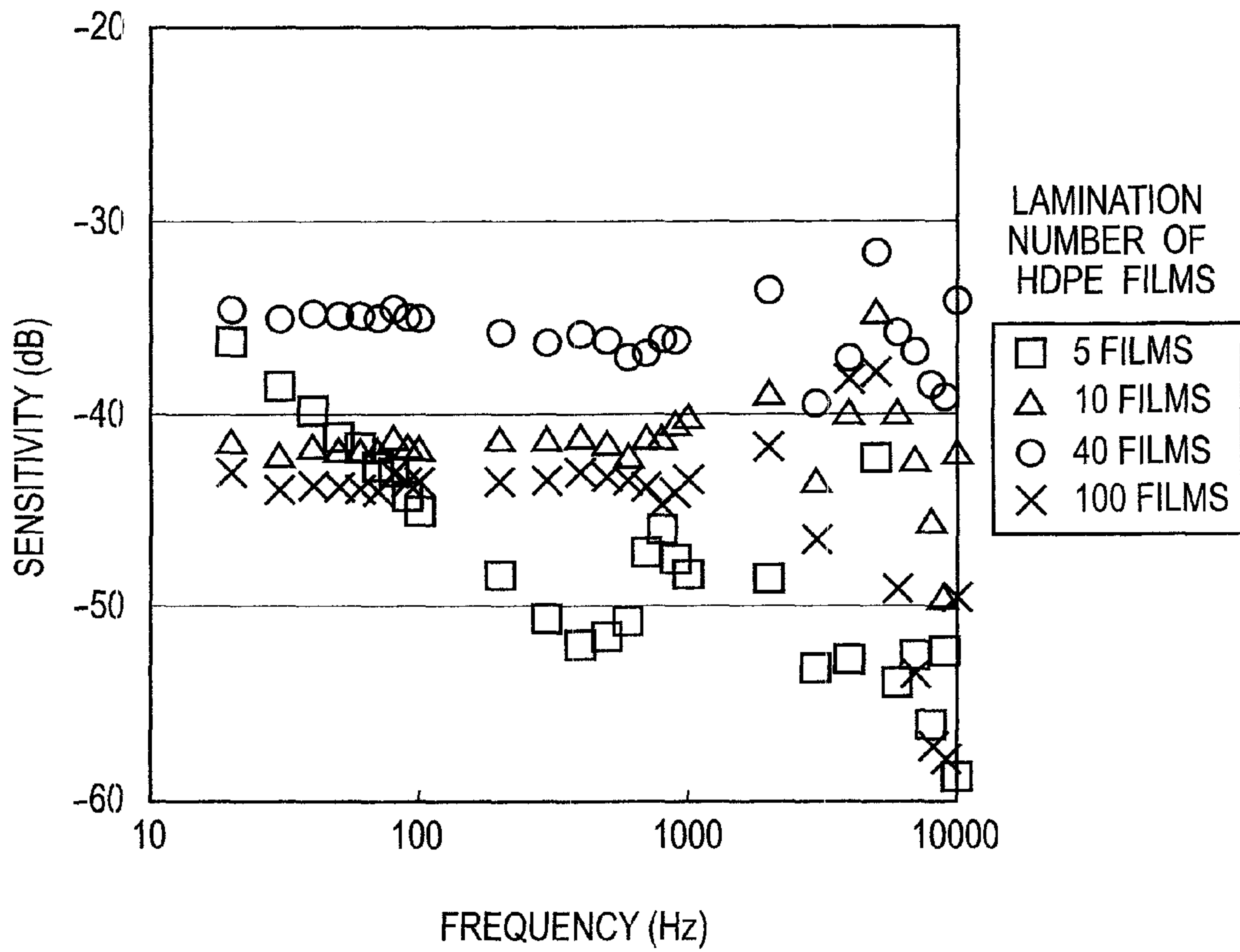


FIG. 23

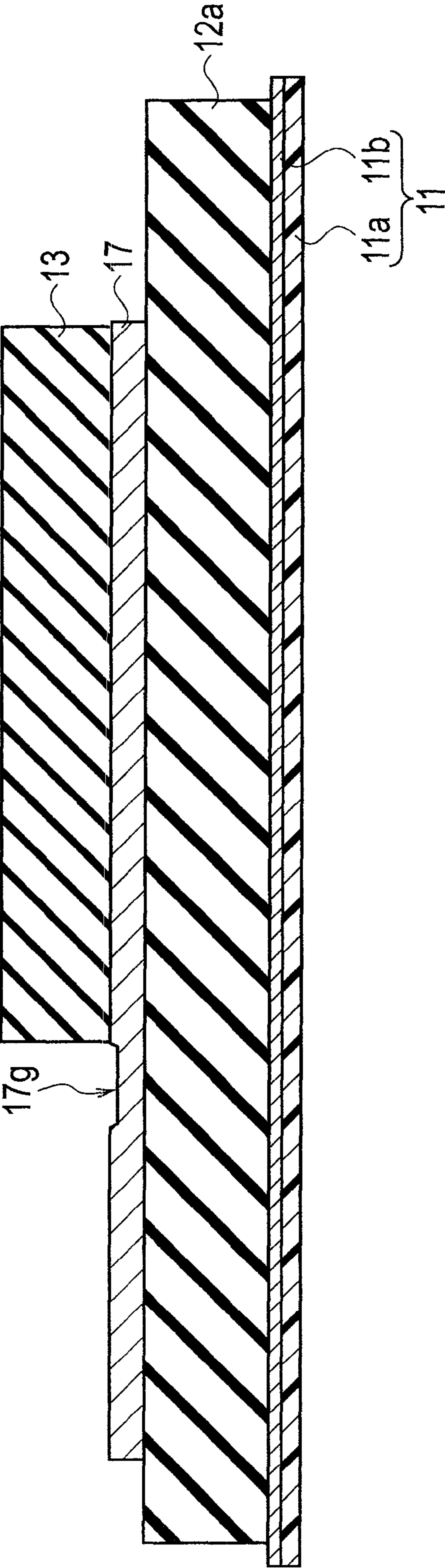


FIG. 24

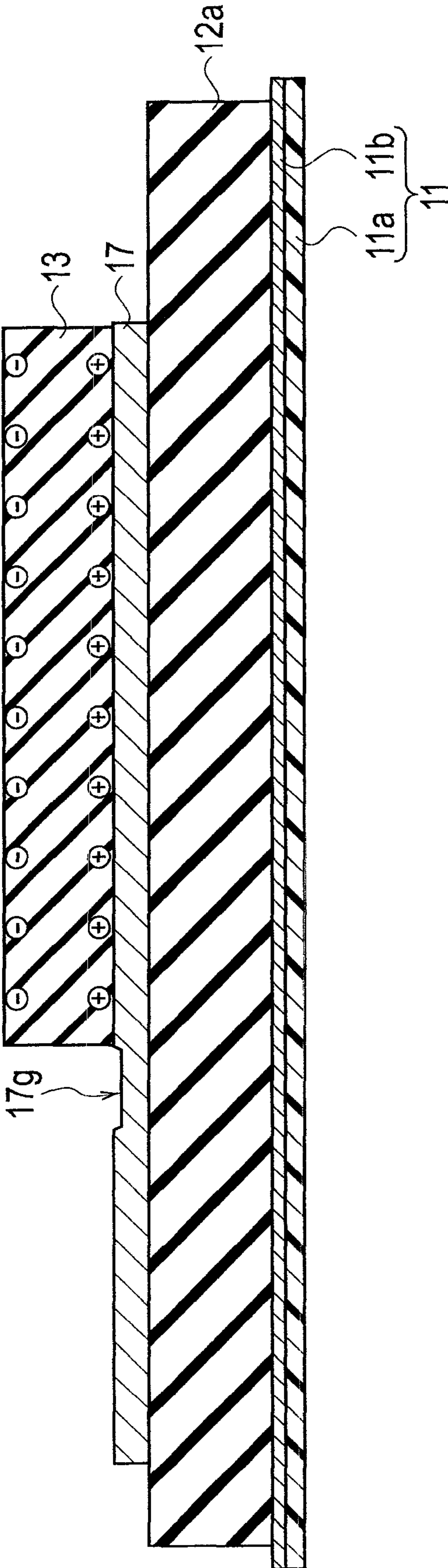


FIG. 25

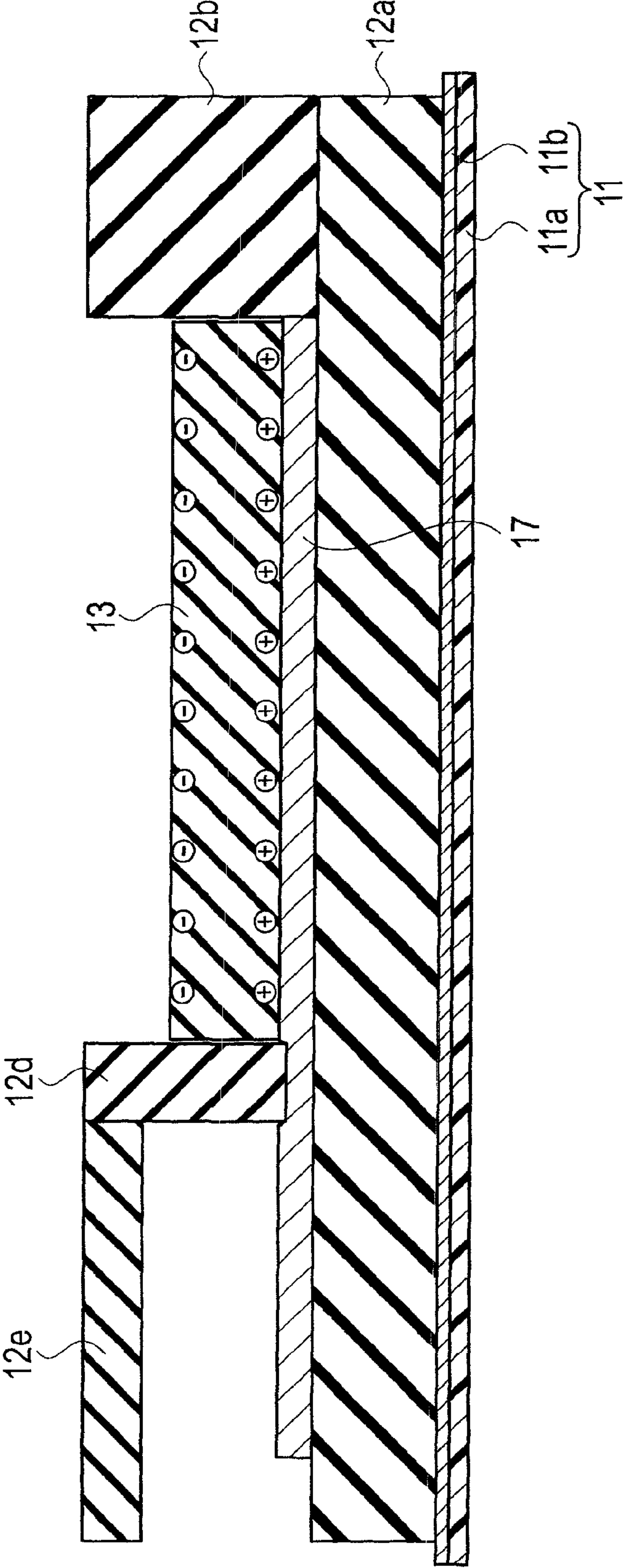


FIG. 26

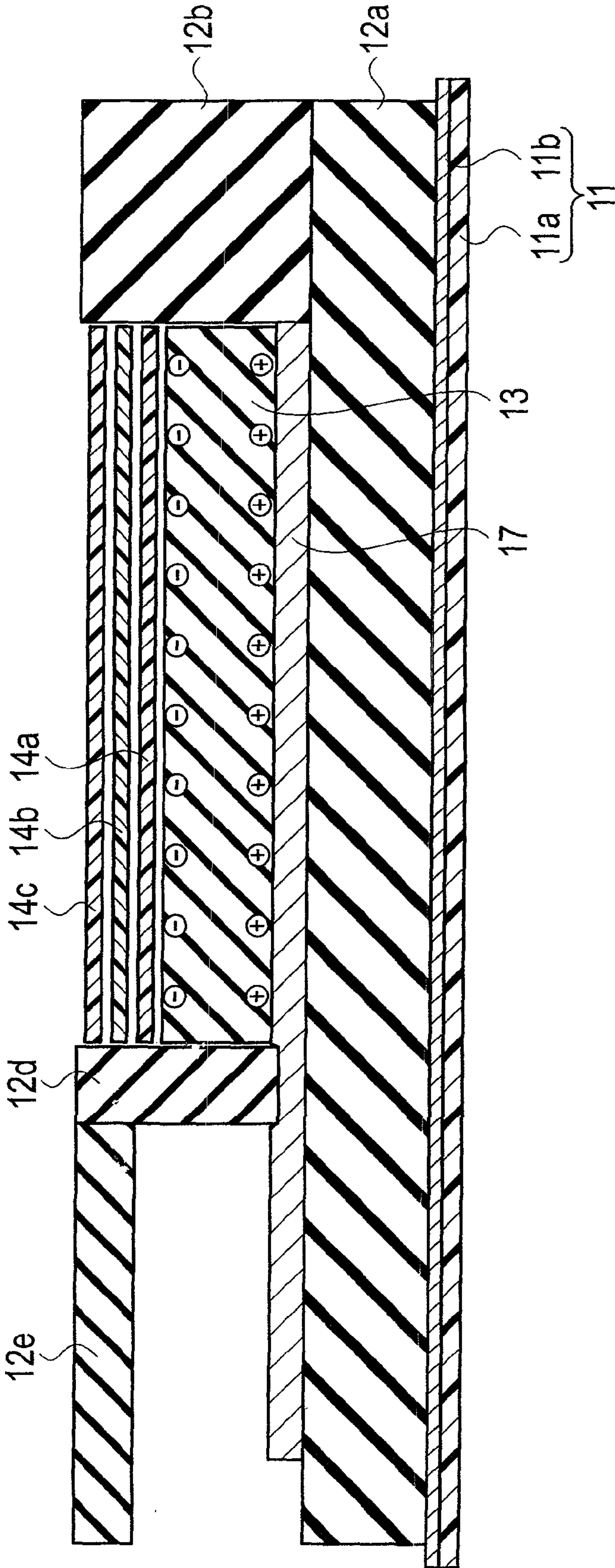


FIG. 27

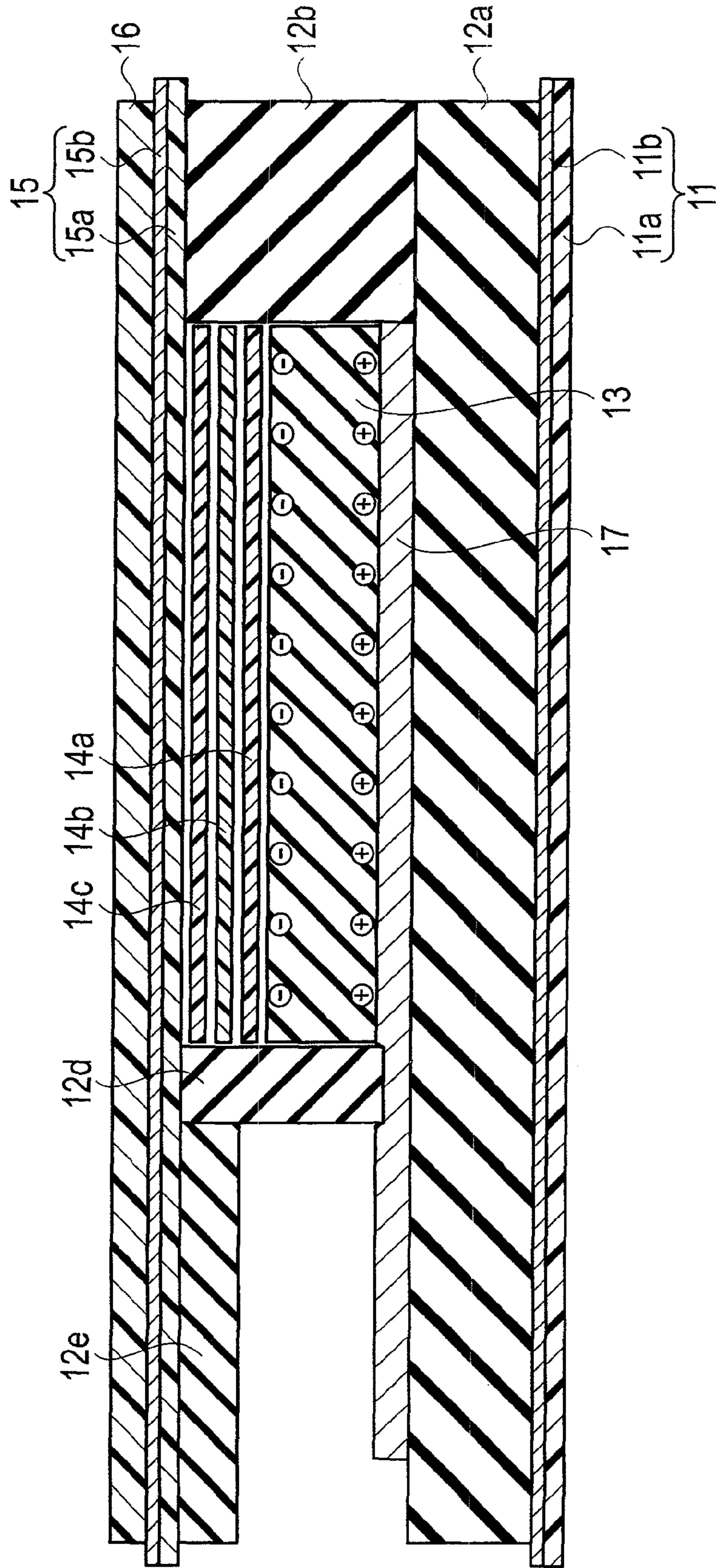


FIG. 28

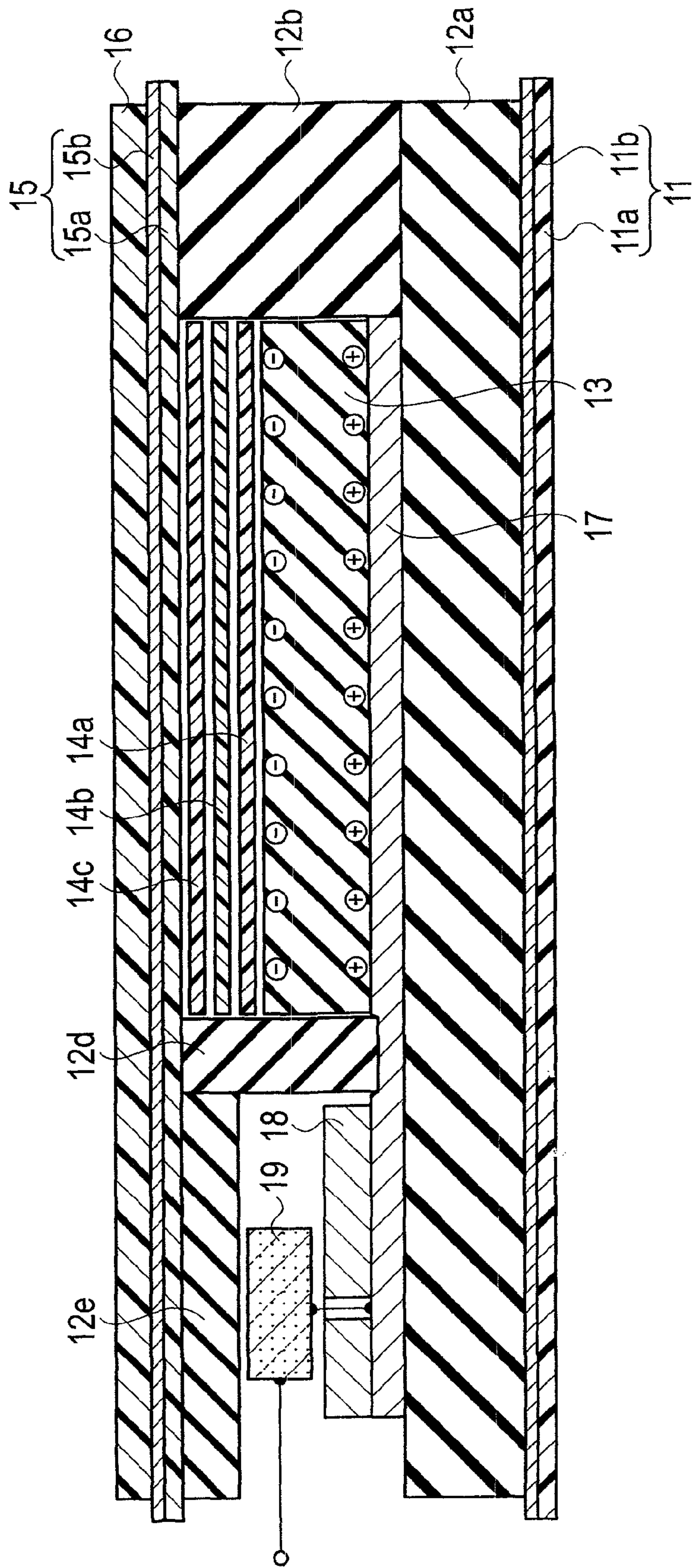


FIG. 29

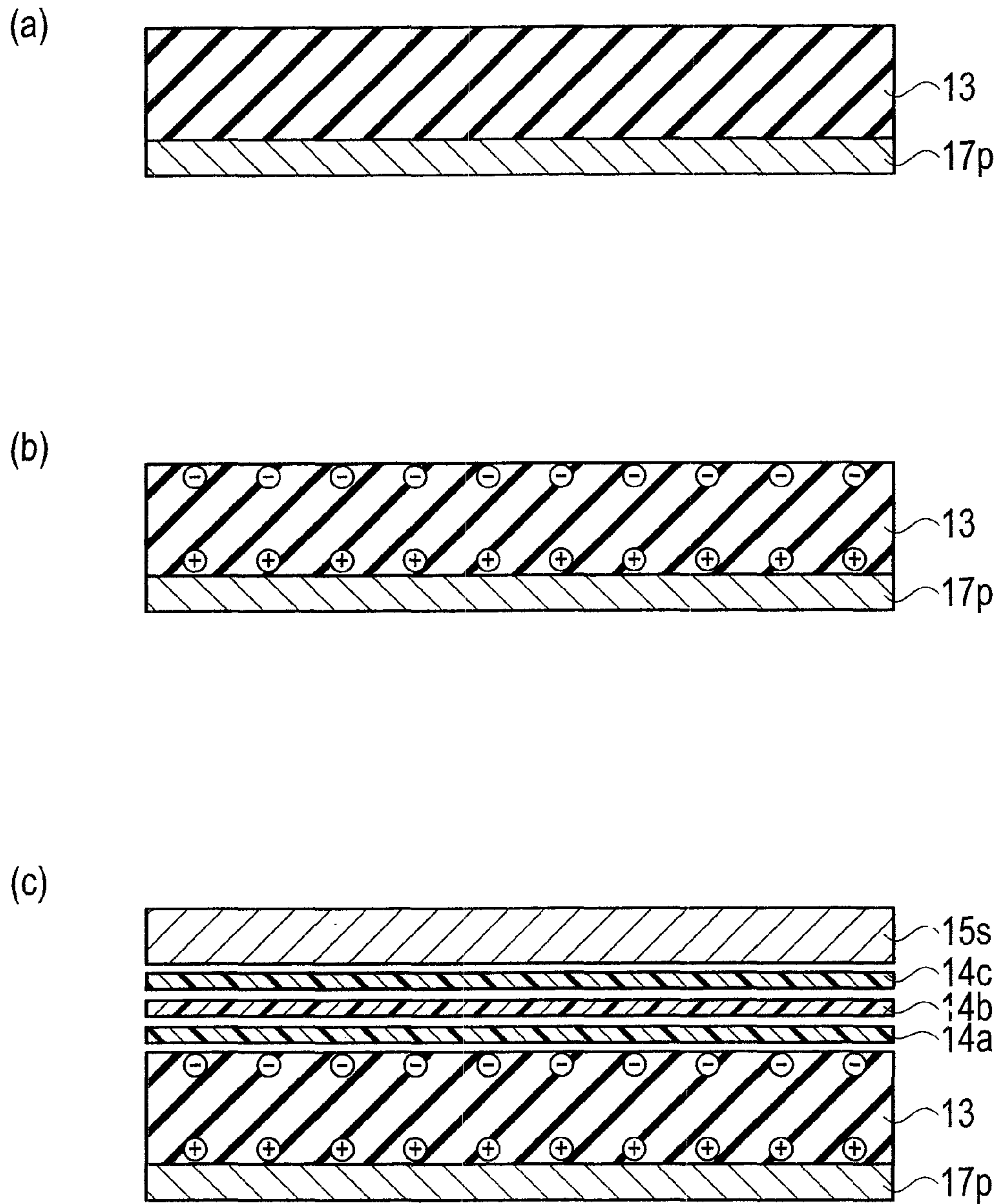


FIG. 30

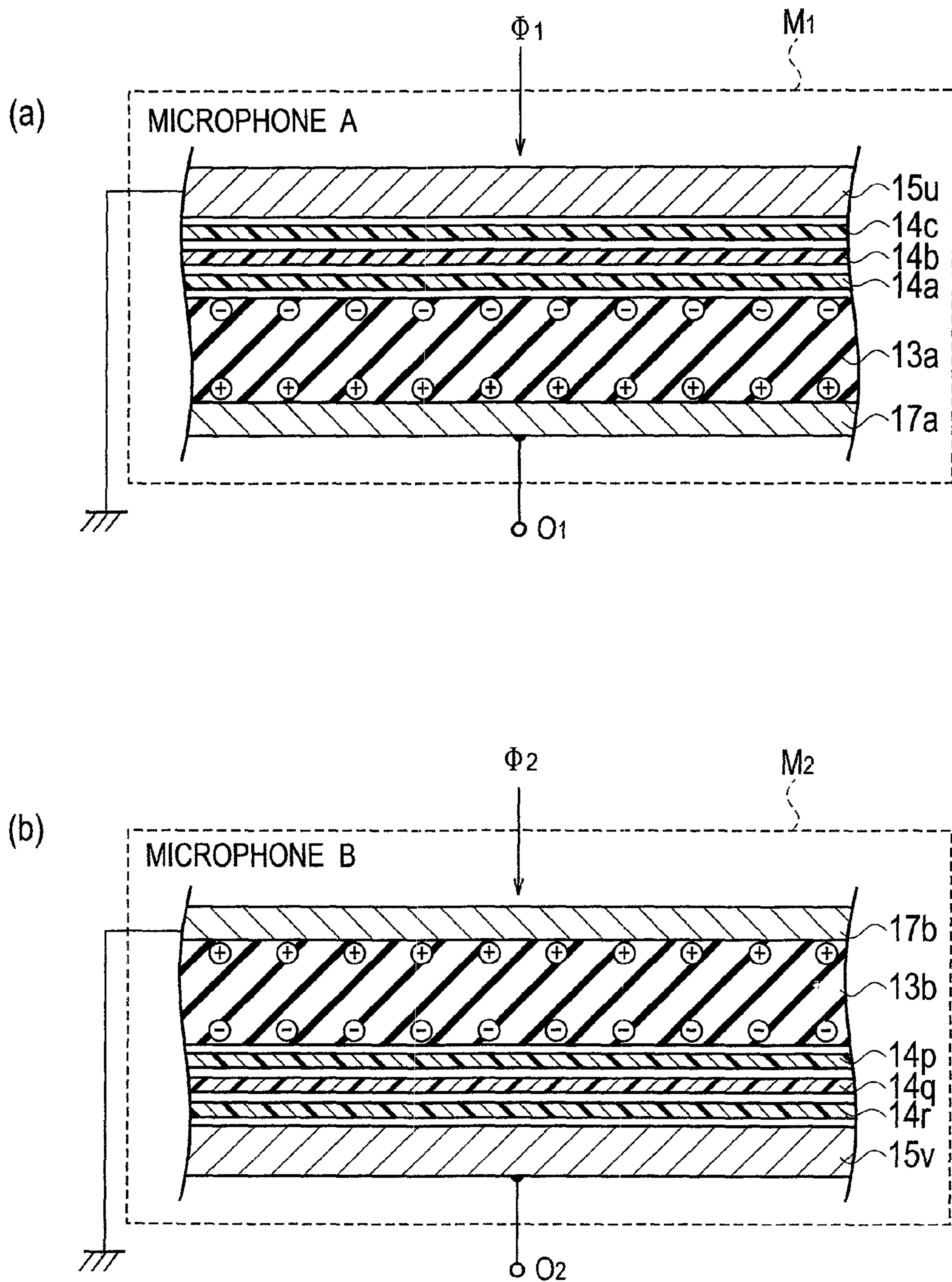


FIG. 31

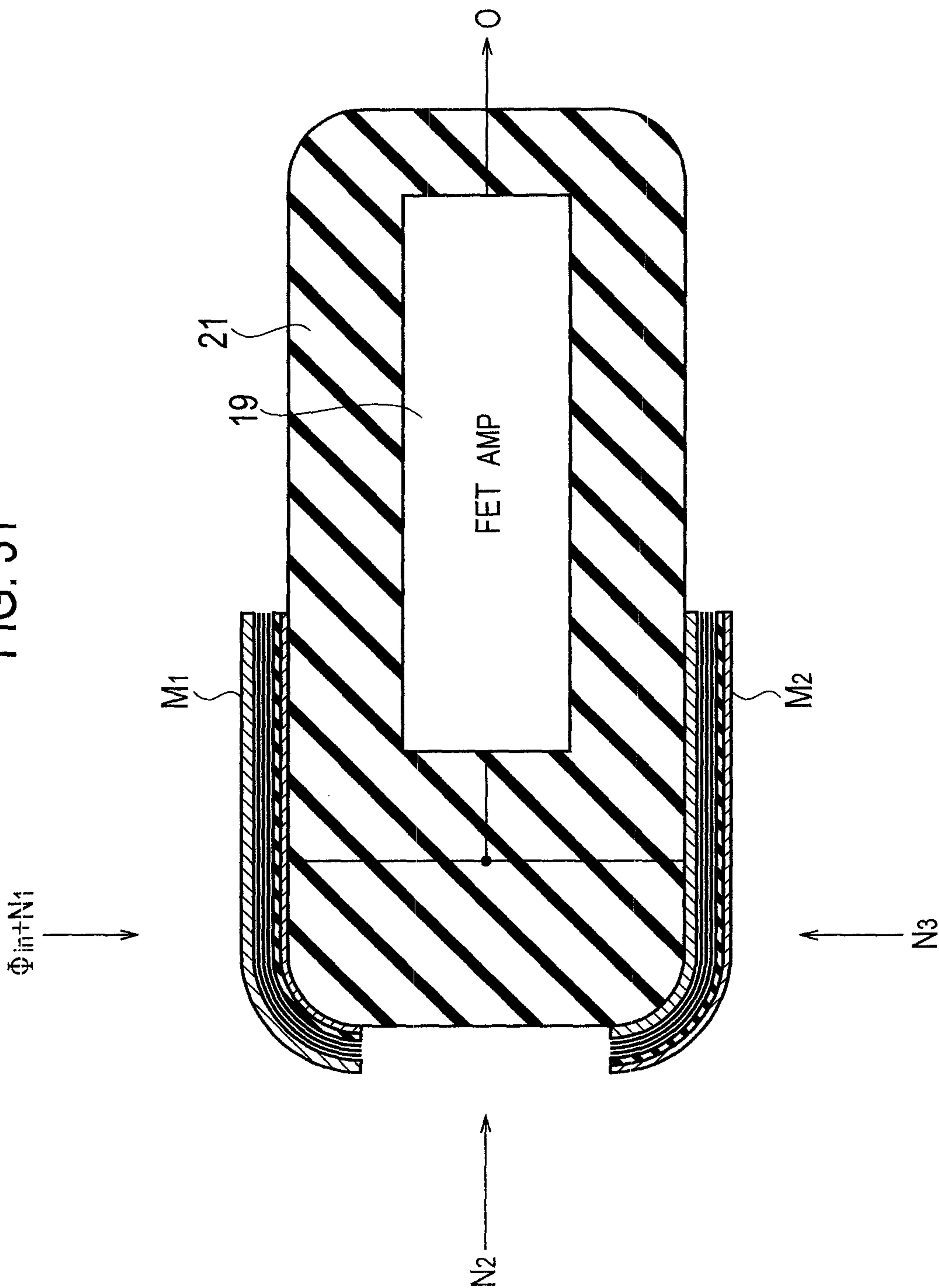


FIG. 33

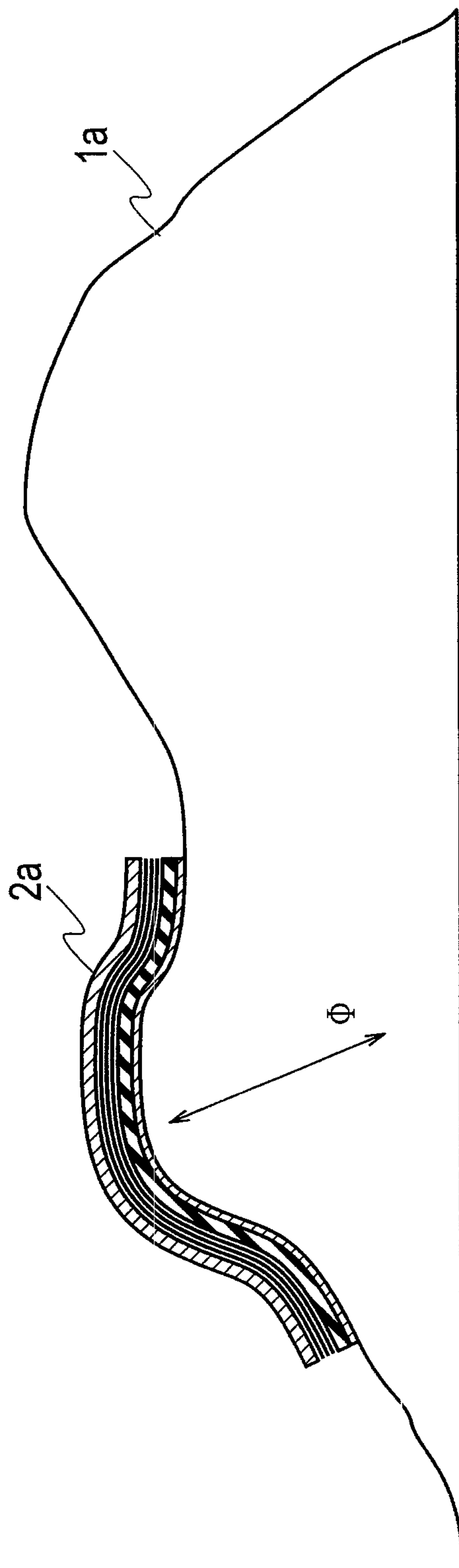


FIG. 34

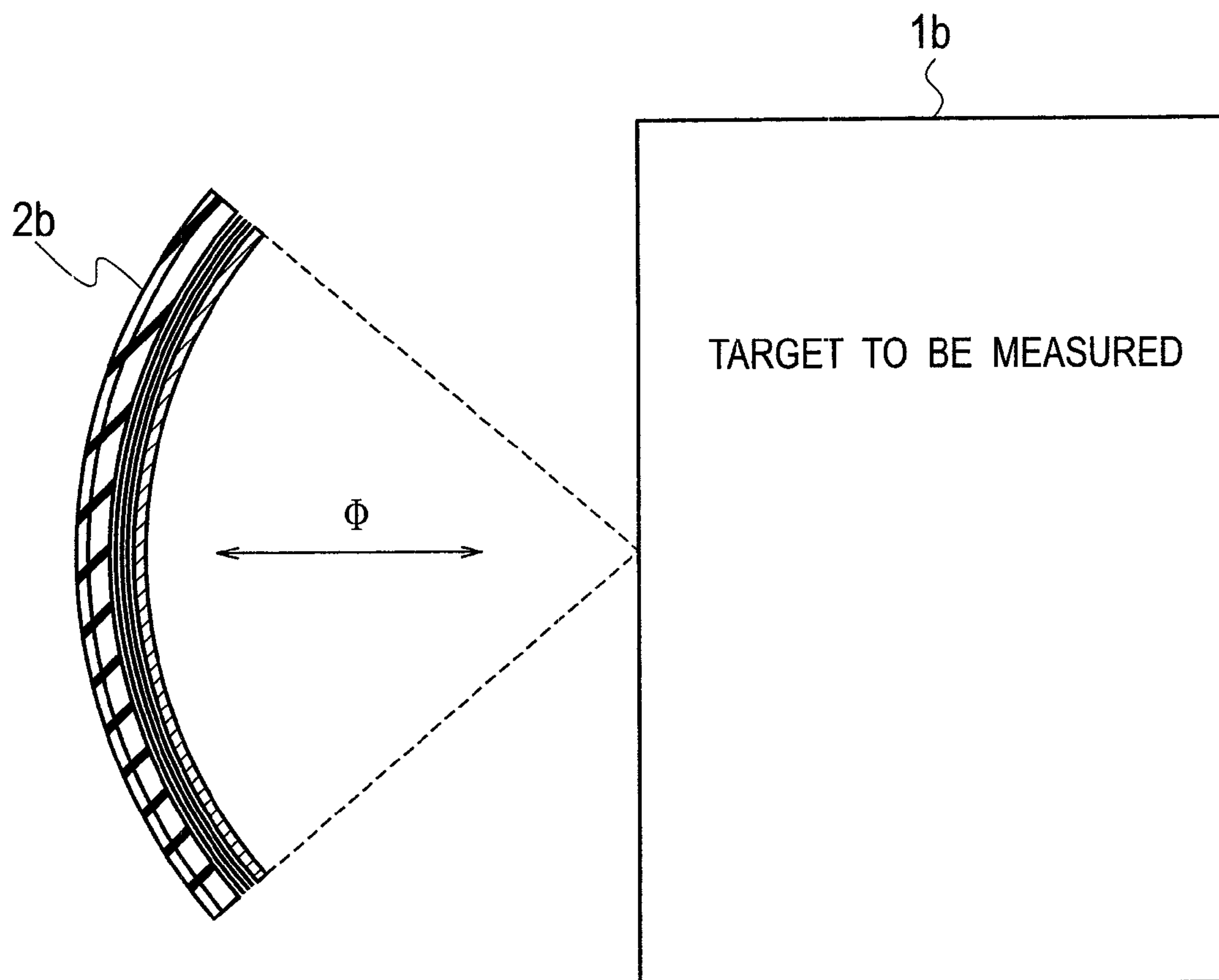


FIG. 35

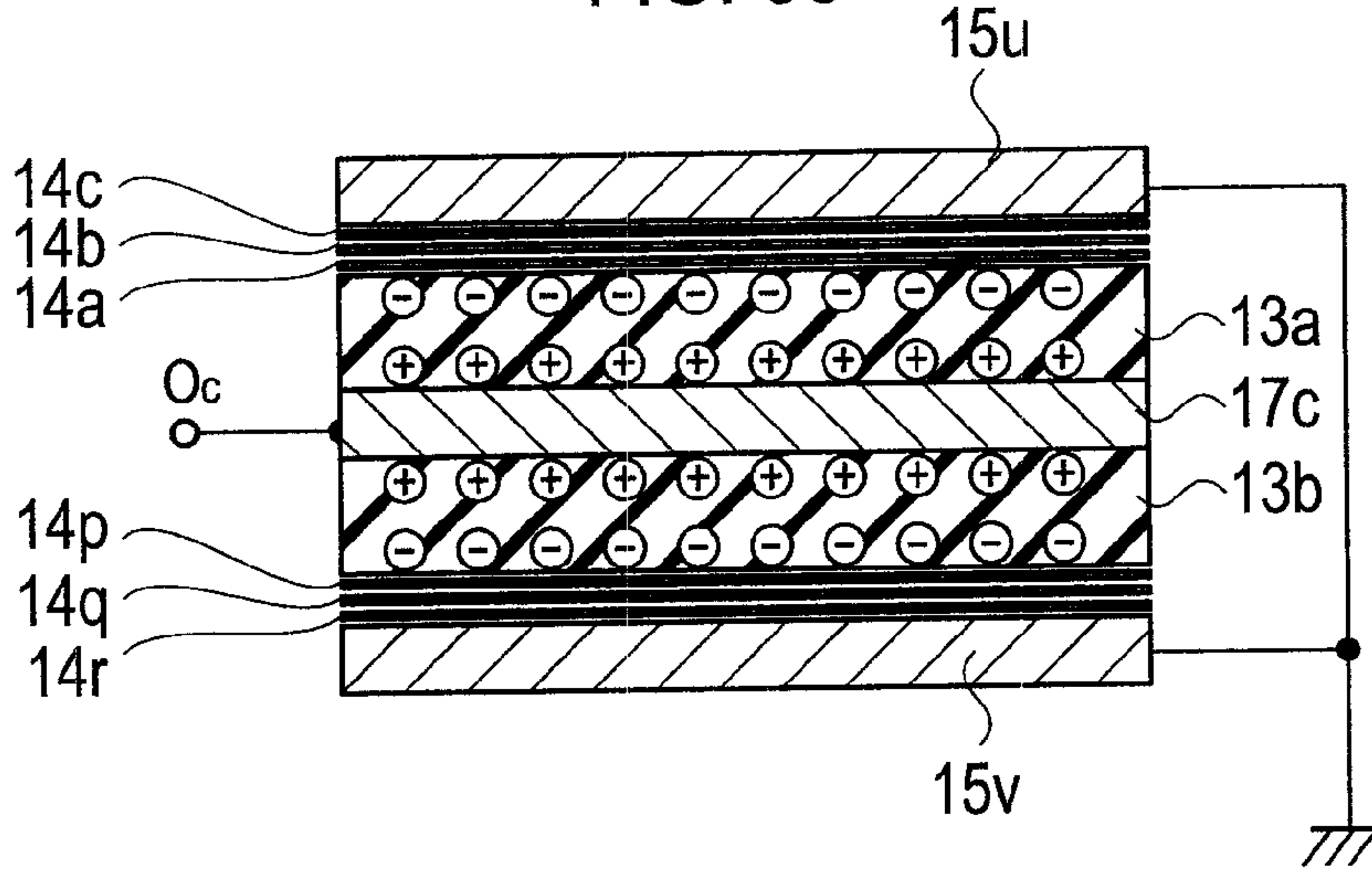


FIG. 36

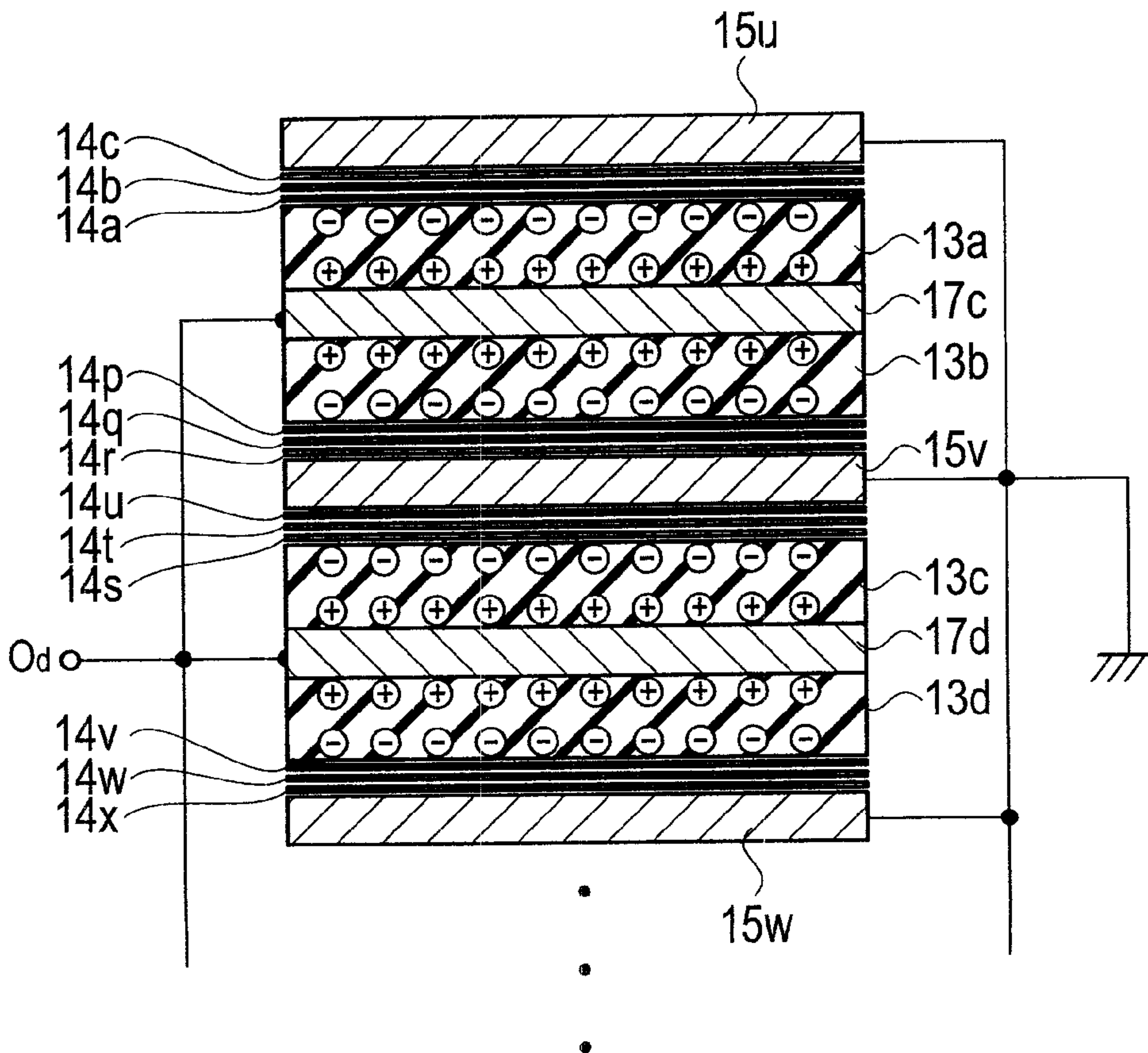


FIG. 38

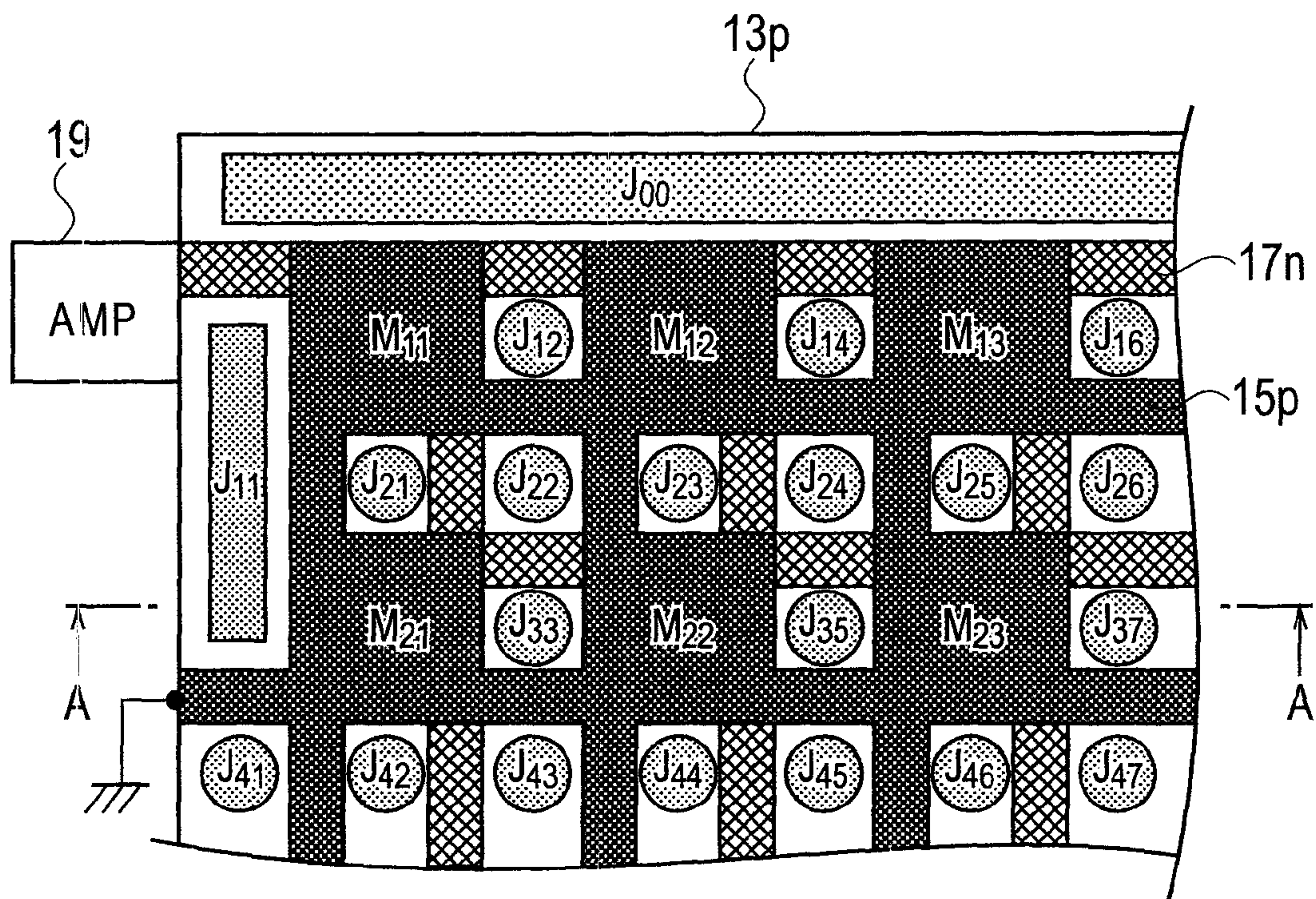


FIG. 39

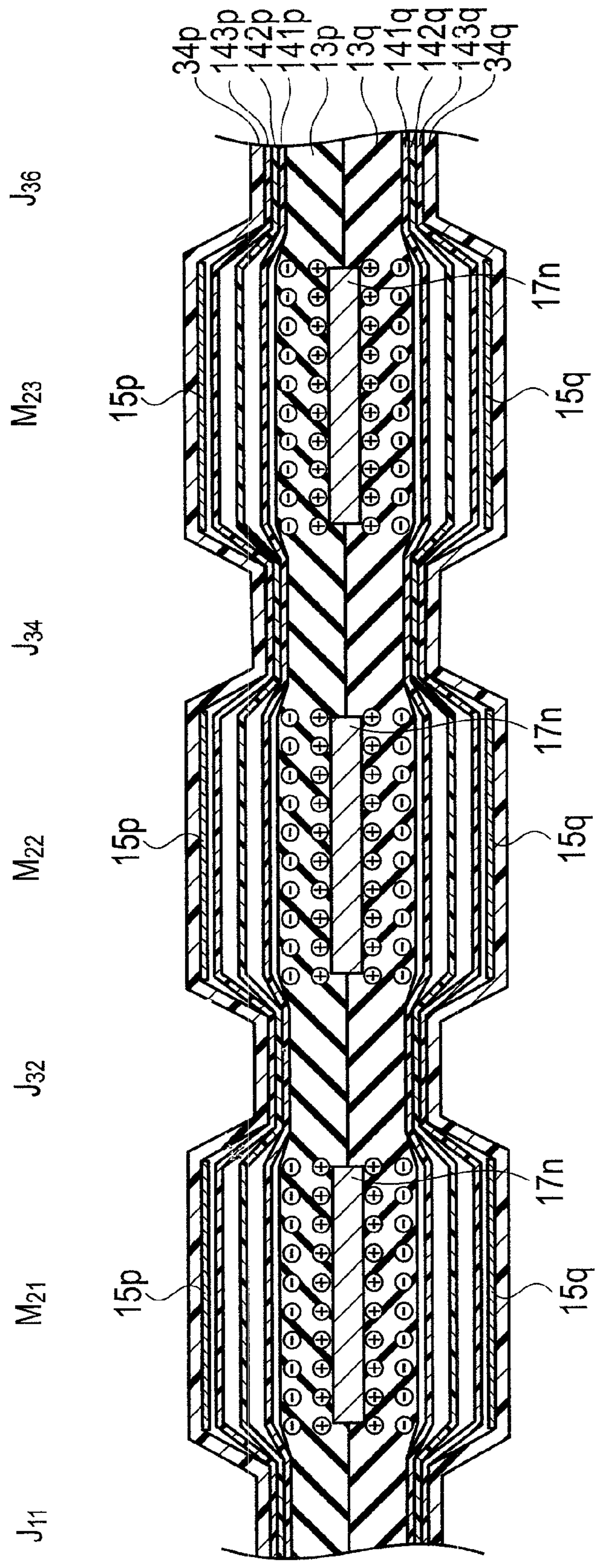


FIG. 40

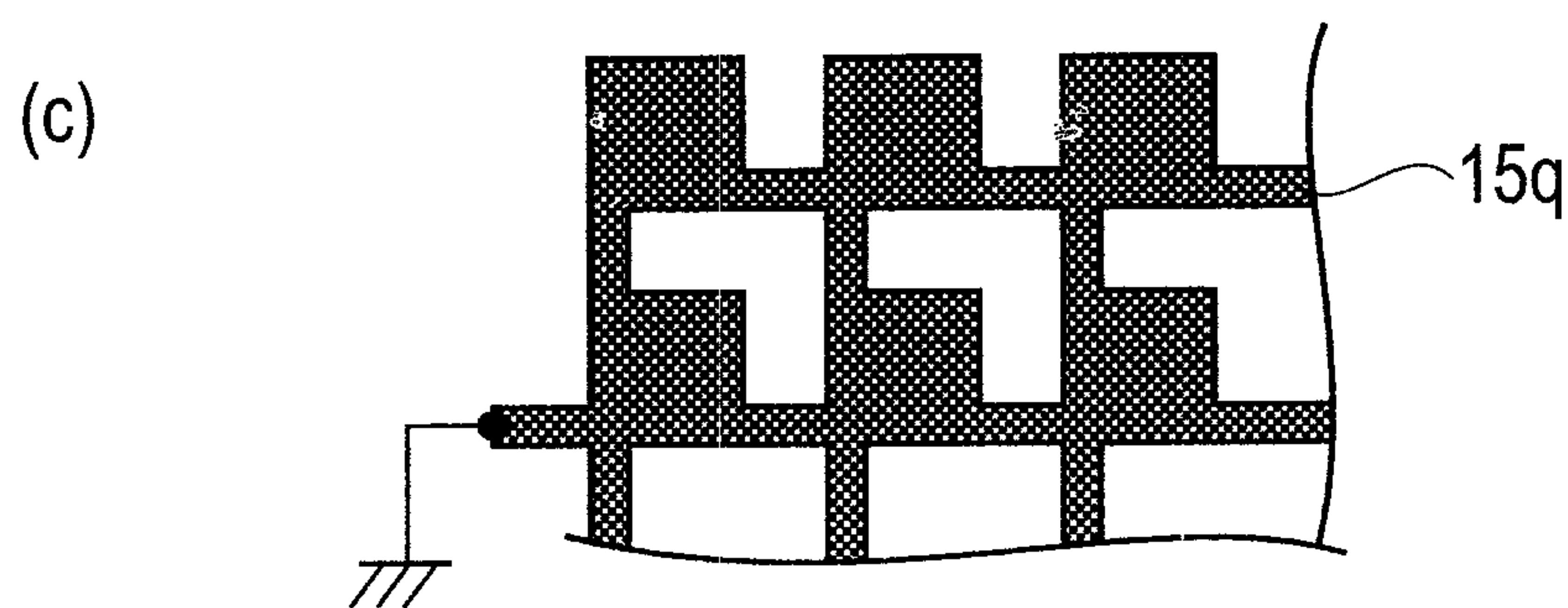
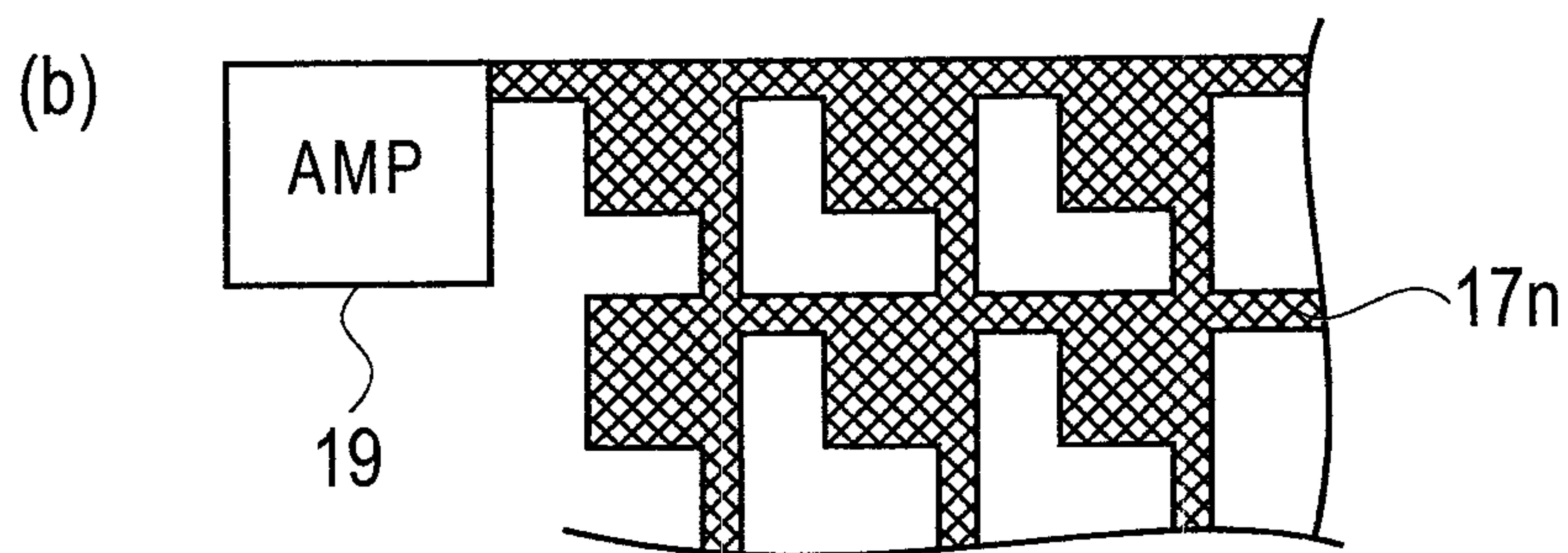
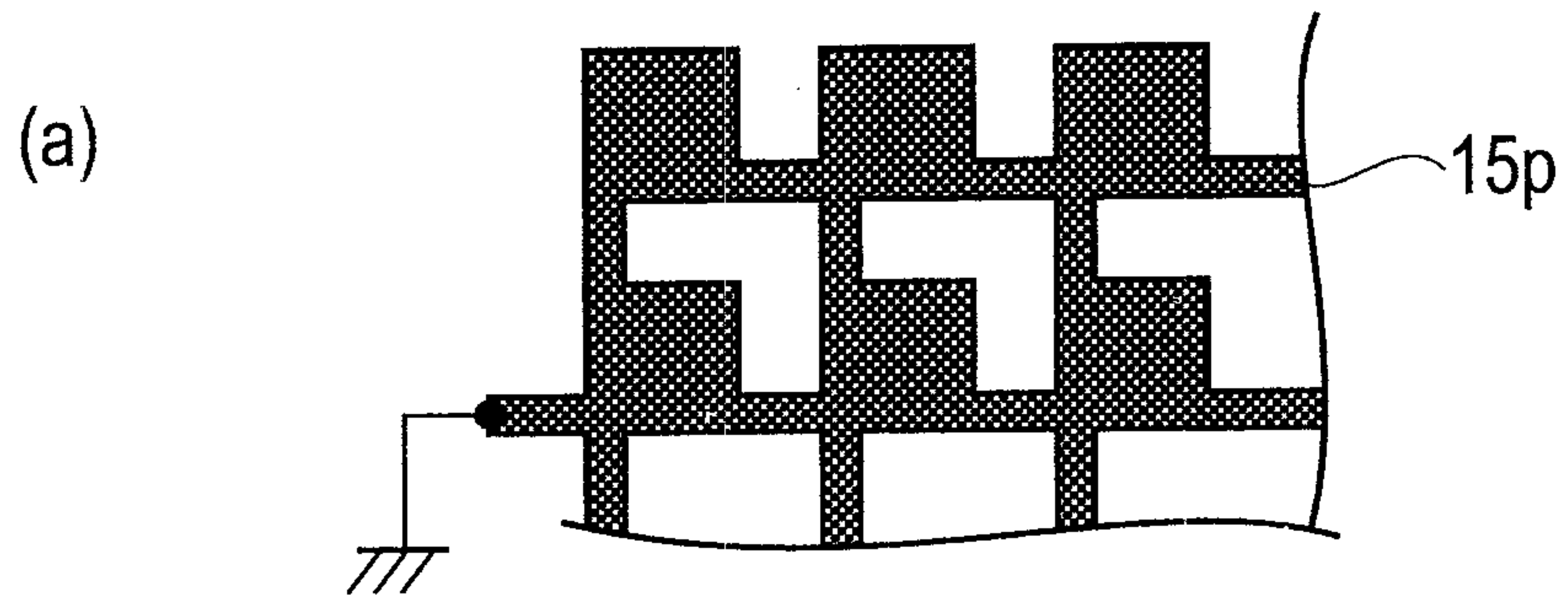


FIG. 41

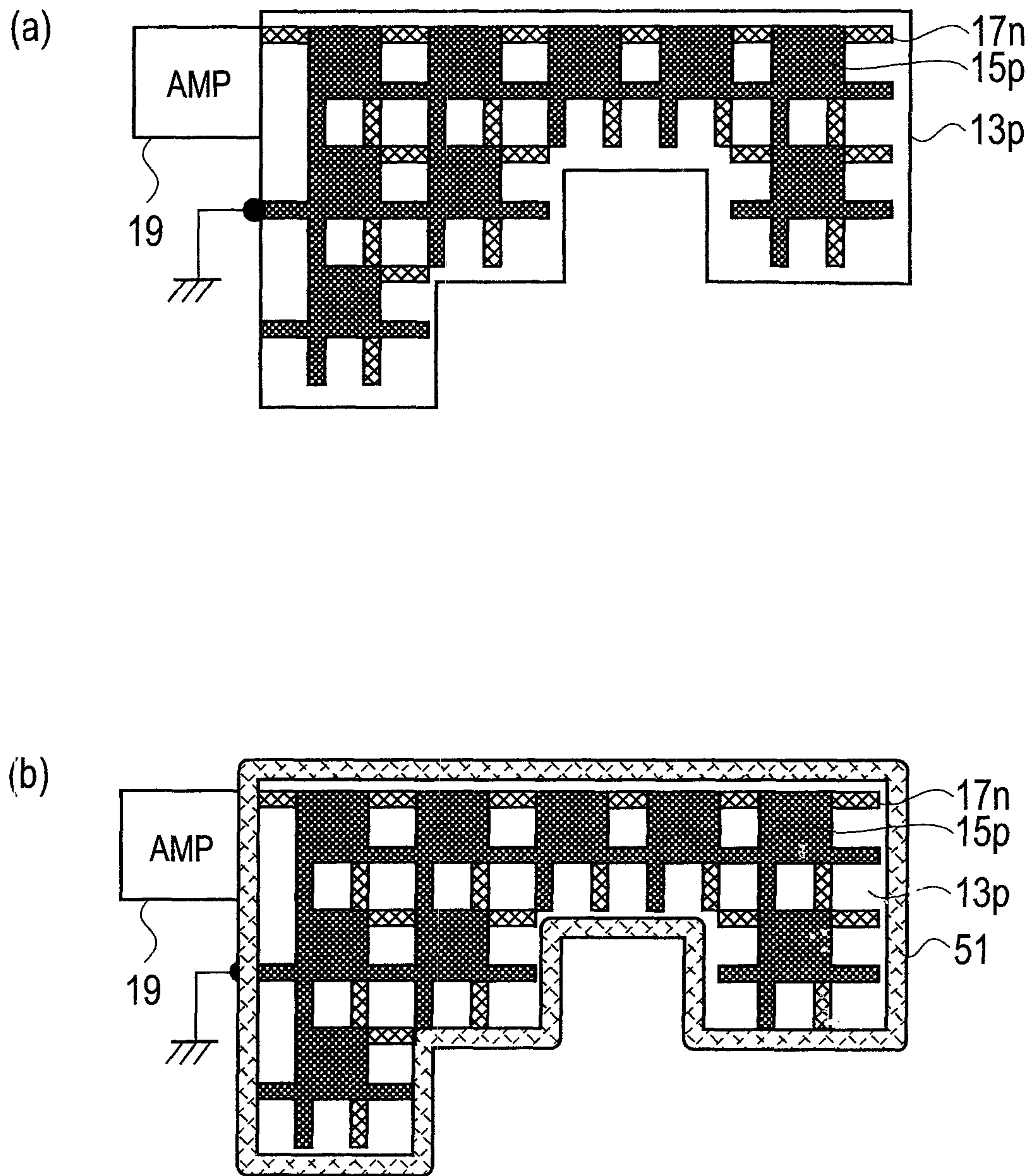


FIG. 42

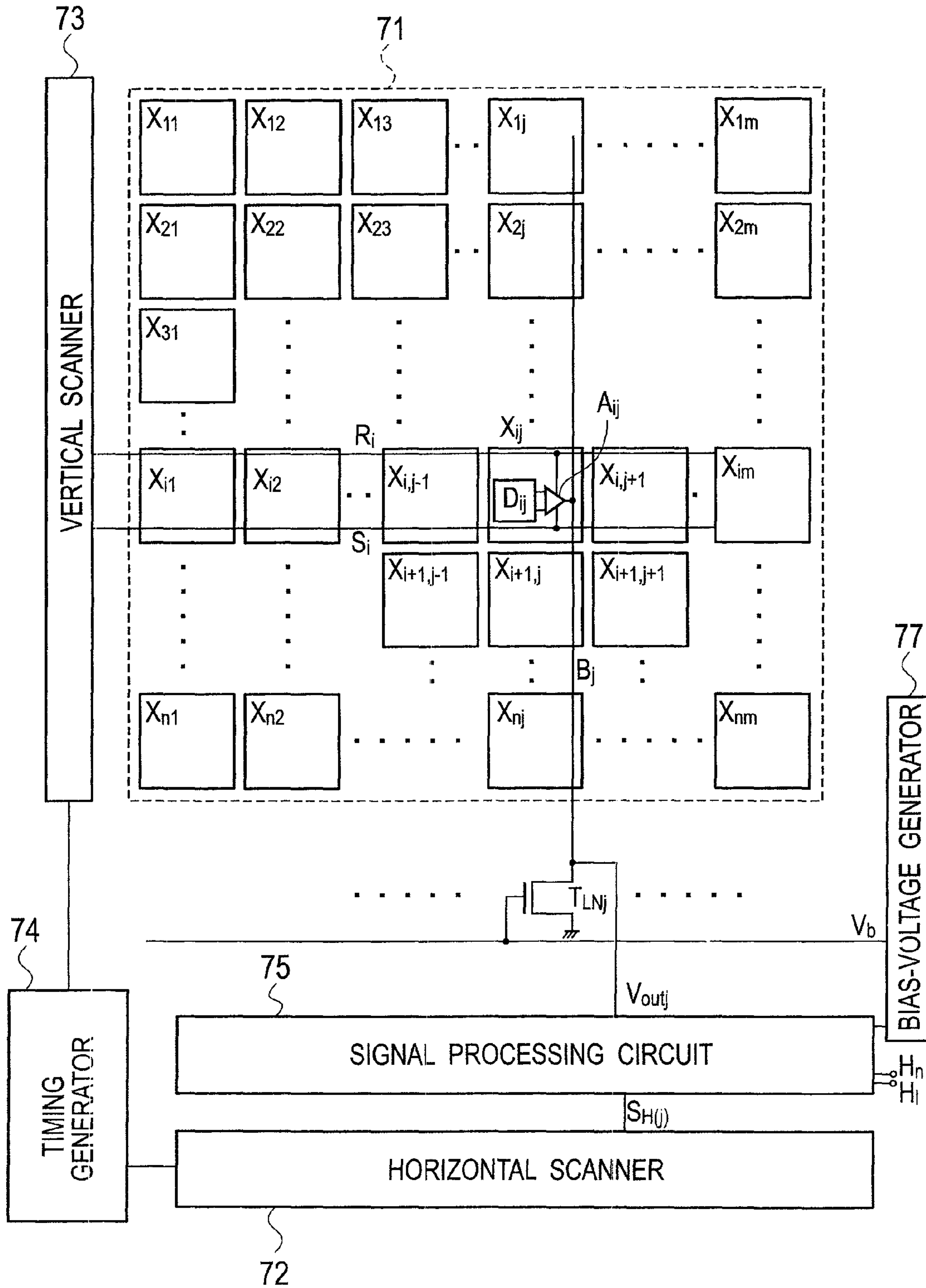


FIG. 43

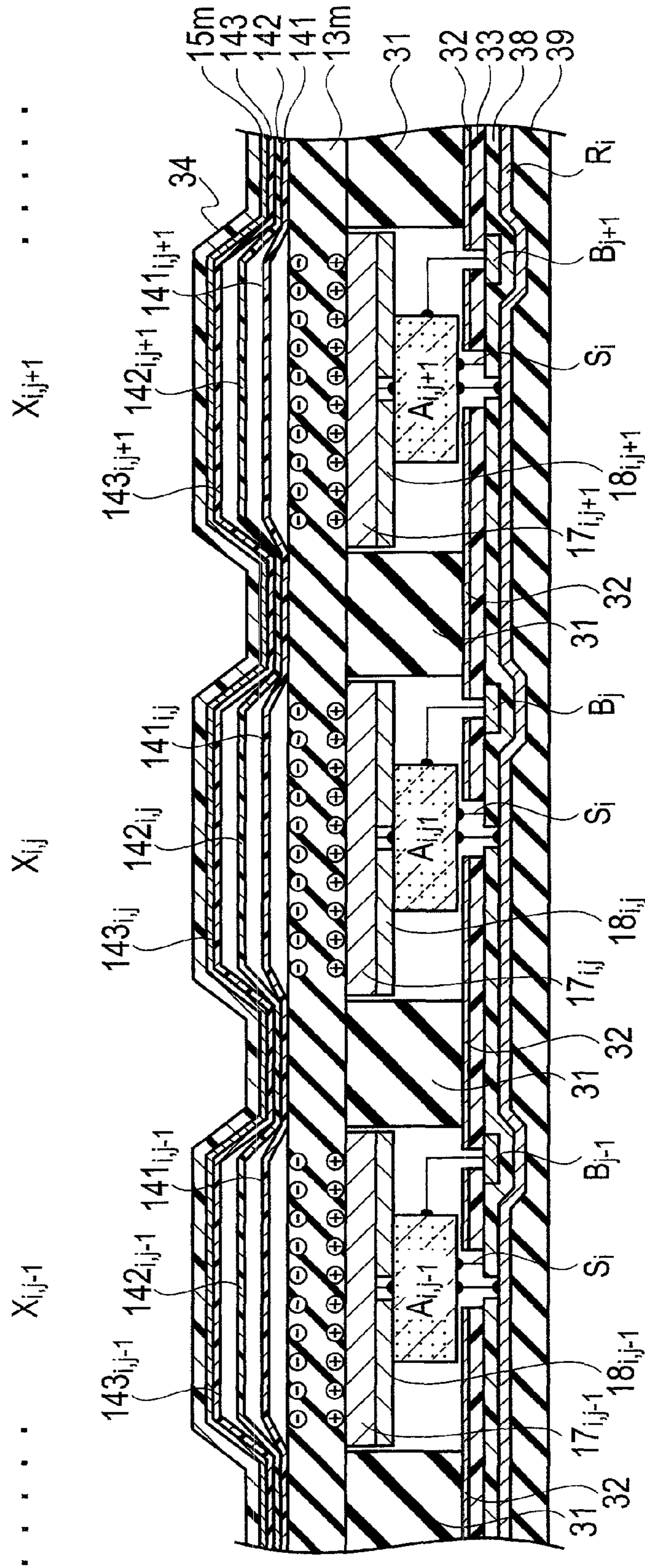


FIG. 44

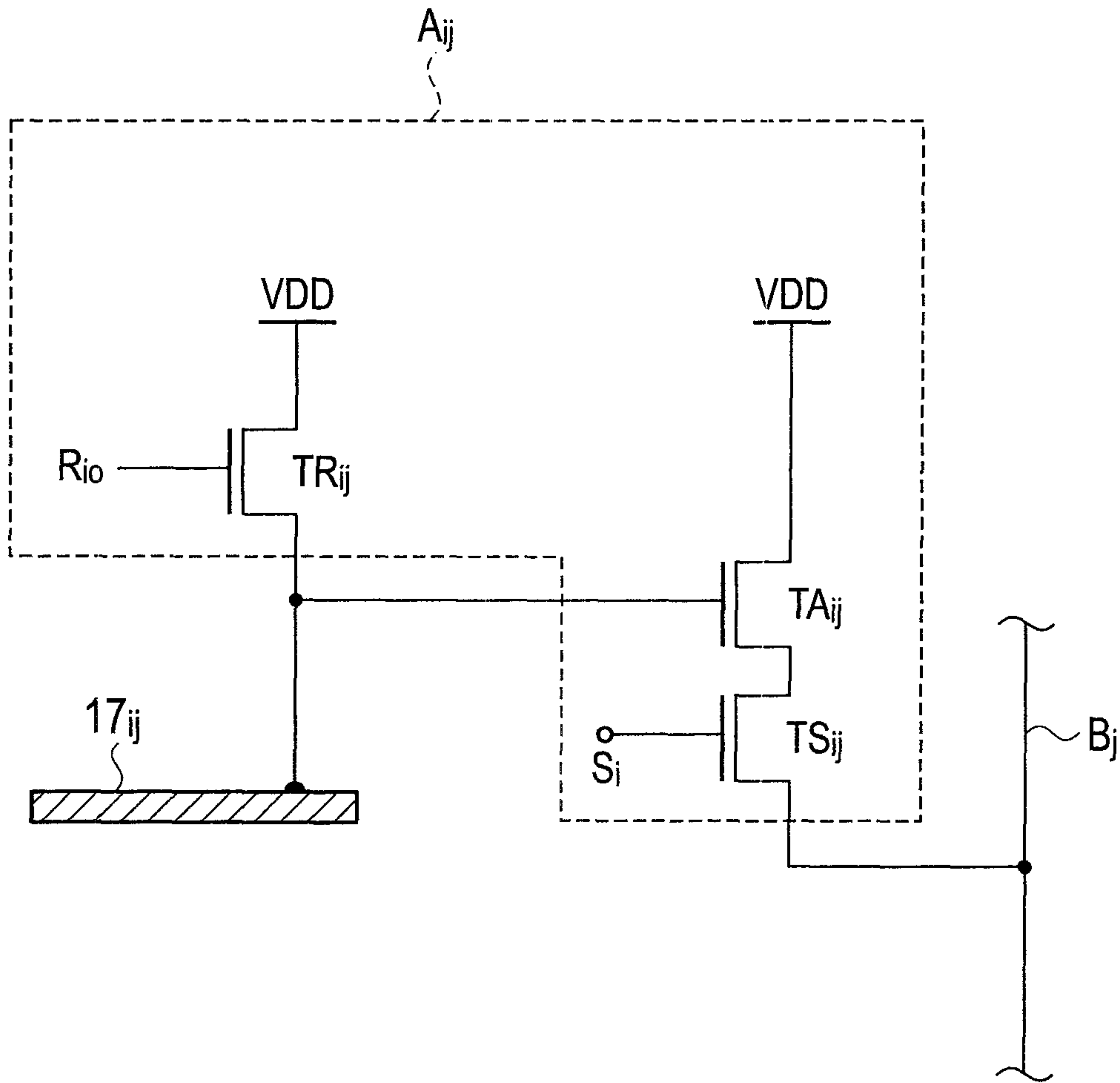


FIG. 46

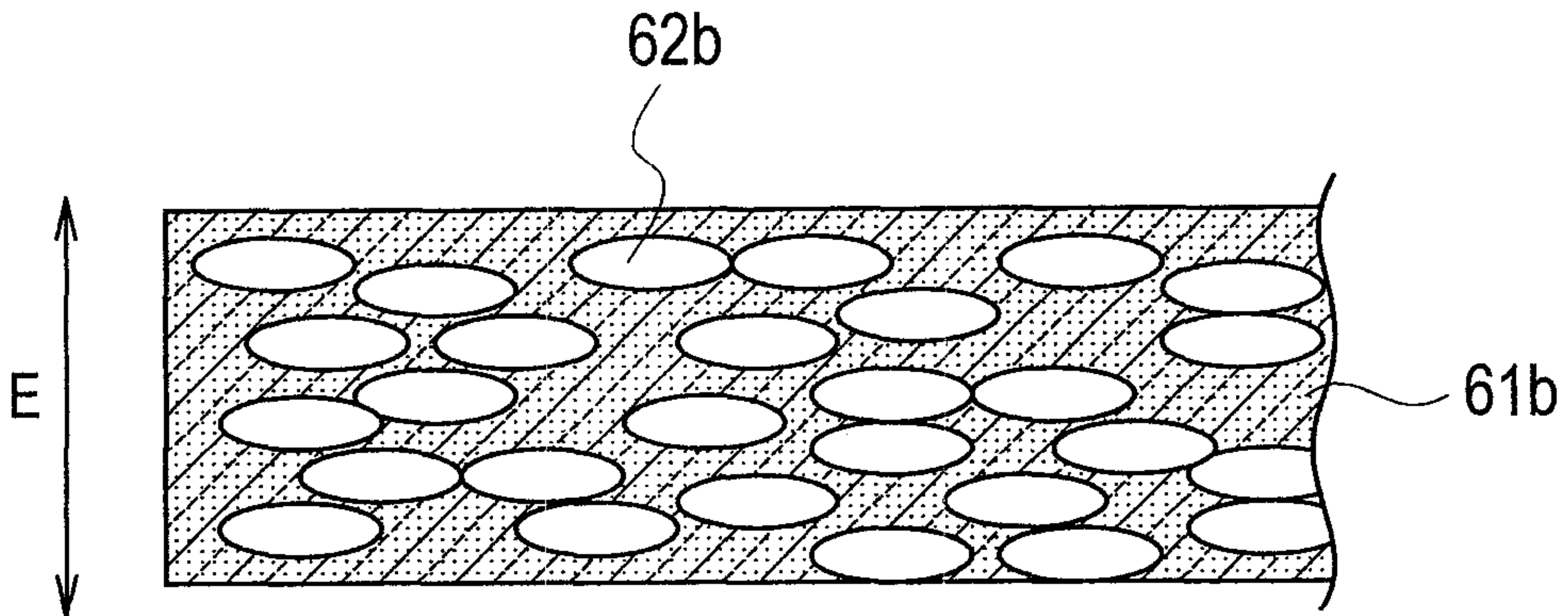
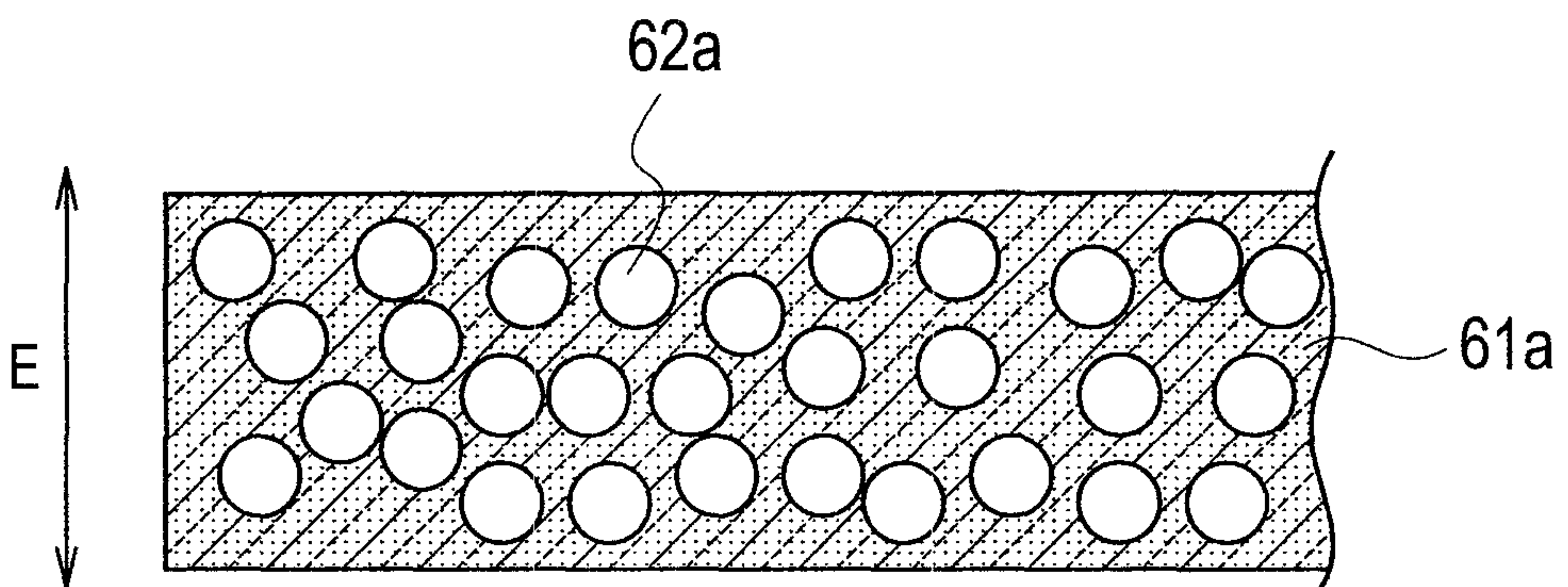


FIG. 47



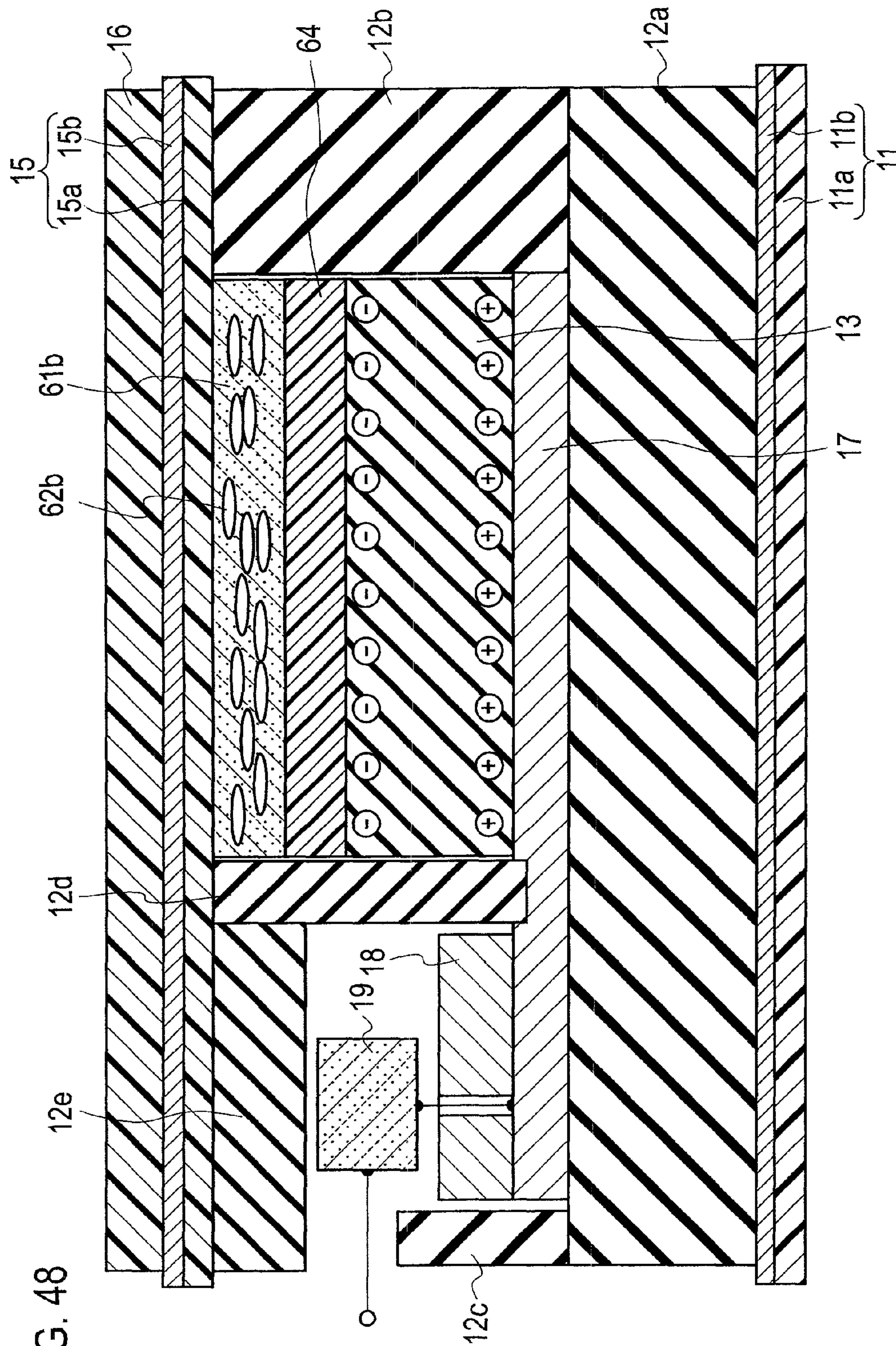


FIG. 48

FIG. 49

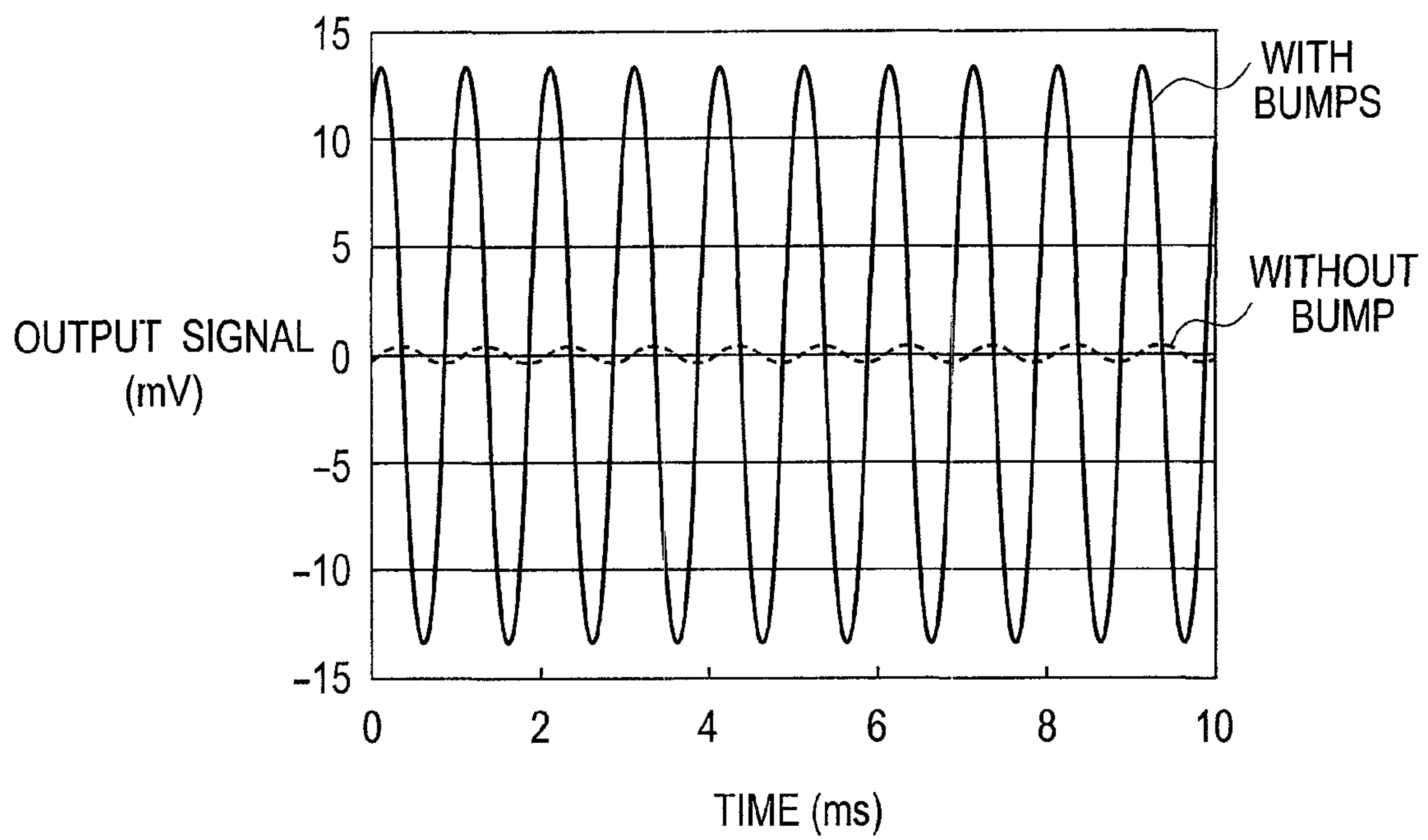


FIG. 50

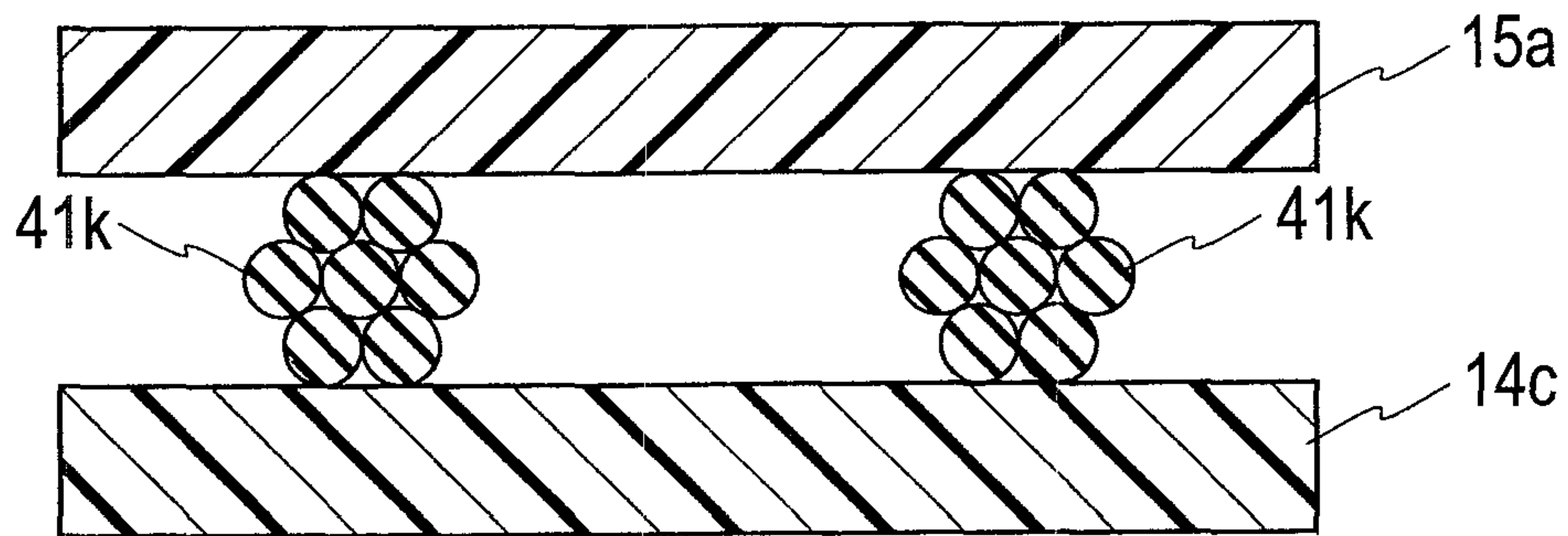


FIG. 51

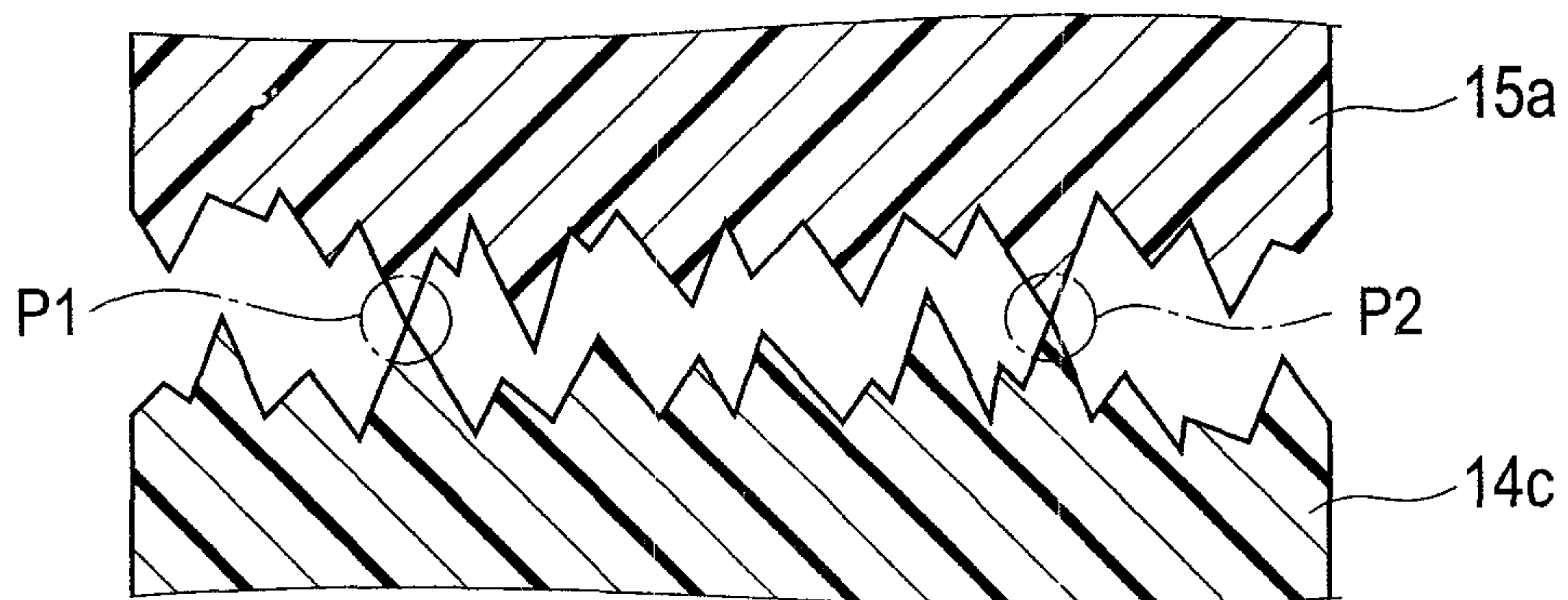


FIG. 52

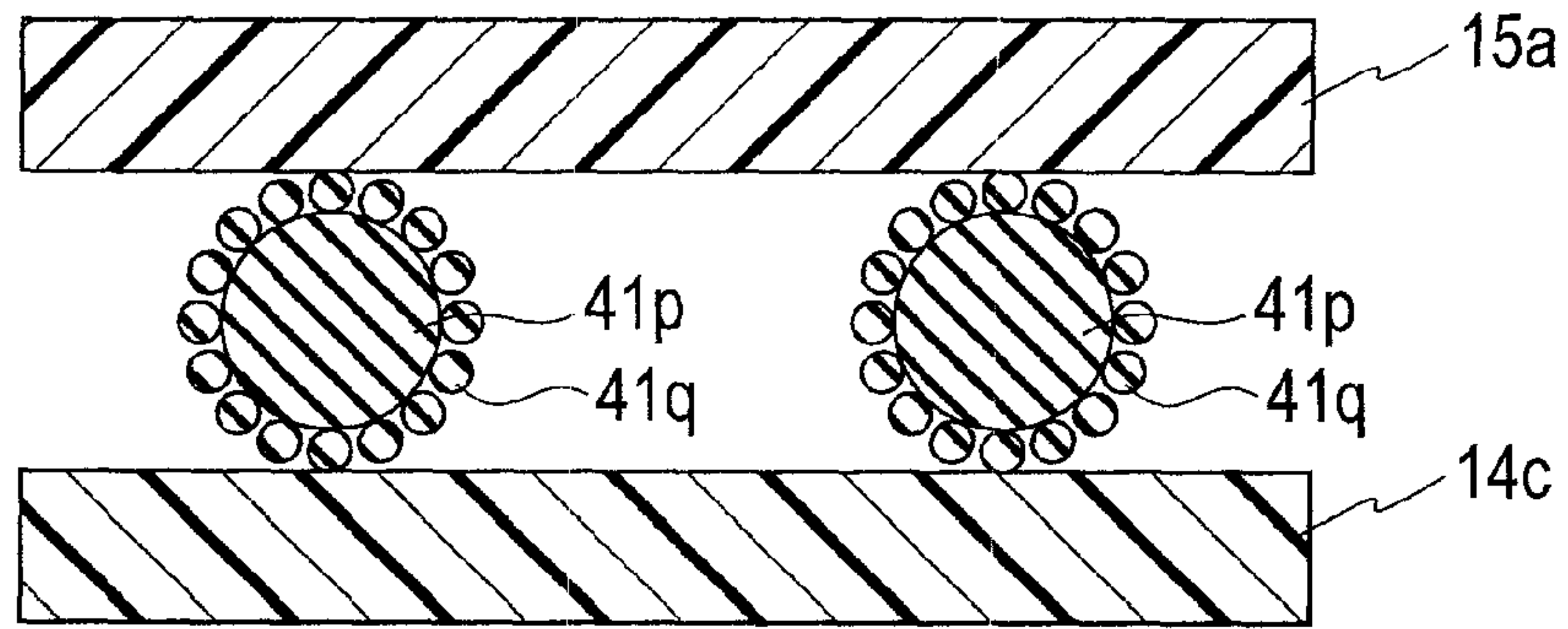


FIG. 53

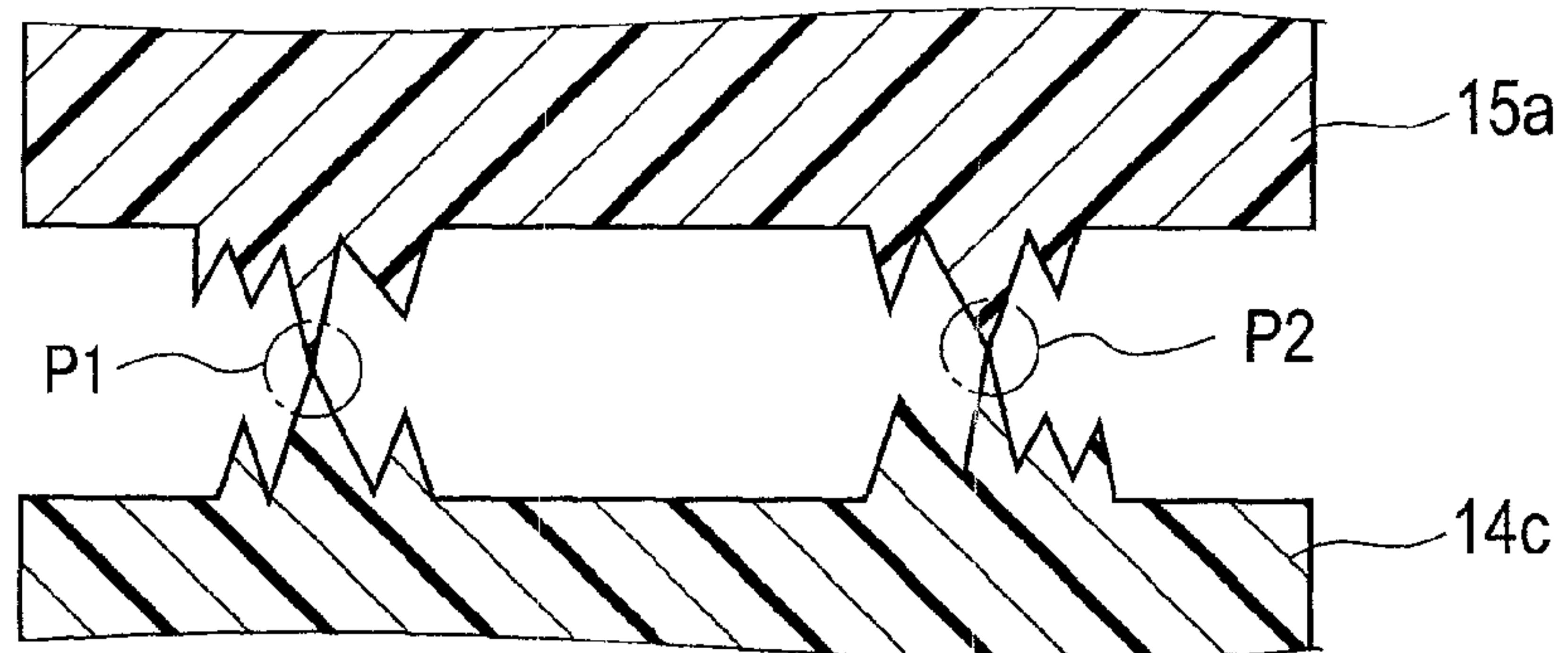
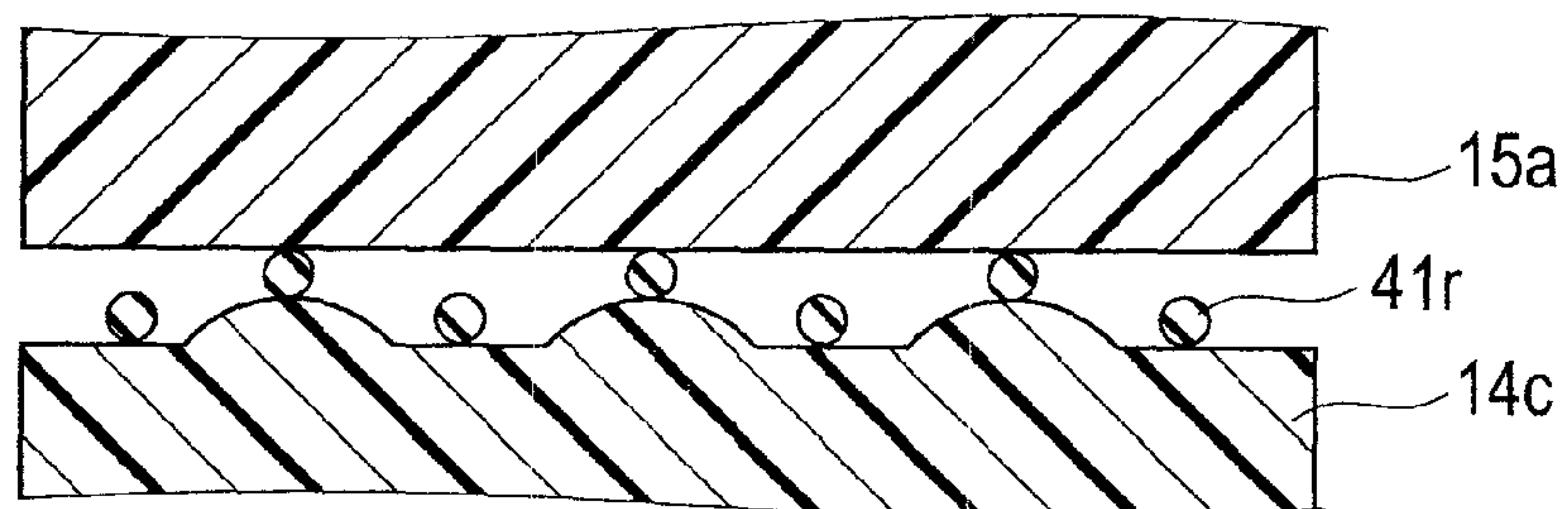


FIG. 54



**ELECTRO-MECHANICAL TRANSDUCER, AN
ELECTRO-MECHANICAL CONVERTER,
AND MANUFACTURING METHODS OF THE
SAME**

FIELD OF THE INVENTION

The present invention pertains to electro-mechanical transducers and electro-mechanical converters, which convert mechanical vibrations into electric signals, and manufacturing methods of the electro-mechanical transducers and the electro-mechanical converters.

DESCRIPTION OF THE RELATED ART

In a mobile telephone and the like, microphones are required to be miniaturized for the sake of space-saving design. Also, as a pickup microphone for acoustic equipment, a small microphone that can be easily incorporated into musical instrument, such as a guitar and the like, is required. In particular, in order to make the mobile telephone or the like waterproof, there is the demand for a miniaturized waterproof microphone.

A certain kind of polymers, such as polycarbonate and the like, has a property that, when a high electric field is applied from outside, charges induced on a surface are quasi-permanently held. O. Heaviside coined the term "electret" for material in a state in which the charges are quasi-permanently maintained. As compared with a dynamic microphone having a structure in which a coil (voice coil) merged with a vibrating plate is driven by a magnetic field, an electret condenser microphone (ECM) is designed such that the electret is arranged close to and in parallel with the vibrating plate. And, when the vibrating plate is driven by sound, because the distance from the electret is varied, the charged states of the electret are changed, and sound signals can be extracted as oscillating electric signals. However, since the oscillating electric signals are very small, the oscillating electric signals are amplified by a field effect transistor that is buried in a microphone unit.

In order to improve the performance of ECMs, the amount of electret charges (polarization) on the polymer film is required to be increased. However, in a method of using corona discharge and converting the polymer films into the electret films, the amount of remnant polarization has a limit of about $30 \mu\text{C}/\text{m}^2$. Also, the gap space between the electrodes of the ECM is required to be very clean. Thus, the manufacturing of the ECM is required to be carried out in clean environments such as a clean room.

On the other hand, as ferroelectric materials, there is material having the amount of remnant polarization, which is equal to or greater than 10,000 times of that of the electret film. However, in order to use as the electret film, there are a problem of a necessity of removing the influence of charged particles adsorbed on the surface of the electret film, and other problems.

In view of the miniaturization of microphones, a miniaturization architecture in which the microphone is directly mounted on a semiconductor substrate (silicon substrate) is tried. For example, an architecture that encompasses a lower electrode and an extraction wiring, which are made of conductive films, is proposed (see Patent Document 1). In the proposed architecture, a membrane area, from which a part of a semiconductor substrate is selectively removed, is defined in the center of the semiconductor substrate, and the lower electrode is allocated in the inside of the membrane area so that parasitic capacitances can be reduced, thereby achieving

a high performance ECM (see Patent Document 1). In the ECM proposed in Patent Document 1, the outer edges of a silicon nitride film, a silicon oxide film and a silicon nitride film are aligned respectively to overlap with the area of the semiconductor substrate so that the resonant frequency characteristics of the vibrating plate can be controlled.

On the other hand, an architecture, in which a PP film or a PTFE film is stretched and foamed so as to generate bubbles in the PP film or the PTFE film, is known. After bubbles are generated, discharge is excited in the insides of independent bubbles so as to implement an electret by the PP film or the PTFE film, and this electret is used for a flexible microphone in the pickup of the acoustic equipment. [Patent Document 1] JP-P 2006-074102A

SUMMARY OF THE INVENTION

The method recited in Patent Document 1, by which the ECM is directly fabricated on the semiconductor substrate, embraces the problems such that the span of the bending of the membrane area, which is allocated in the area where the semiconductor substrate is selectively removed, becomes $1/10$ or more of an air gap, and because the dielectric breakdown strength of air is low, the ECM cannot endure stronger sound pressures. In particular, since the silicon substrate is weak against impact pressures, a buffer layer is required even if the size of the silicon microphone itself is small.

Although the architecture using the porous film may improve the waterproof behavior, since the porous film attenuates the sound, the sensitivity of the ECM is decreased. Also, as for the architecture in which a film is changed into the electret, by using discharges in the insides of the bubbles in the porous PP film or PTFE film, when a temperature exceeds 100°C ., because the electret is deteriorated, the available temperature range is narrow.

On the other hand, although PZT is being tried to be incorporated in a piezoelectric probe, because PZT can be used only at the resonant frequency, the operation of PZT in a wide frequency band is difficult.

In view of the above-mentioned problems, an object of the present invention is to provide an electro-mechanical transducer and an electro-mechanical converter, both of which are flexible, having high degrees of freedom in geometrical deformations, a high sensitivity and can withstand stronger sound pressures, and further, can be used in wide frequency bands, and to provide manufacturing methods of the electro-mechanical transducer and the electro-mechanical converter.

In order to achieve the above object, a first aspect of the present invention inheres in an electro-mechanical transducer encompassing (a) a vibrating electrode having a flat vibration surface under no load condition, (b) a vibrating-plate-insulating layer disposed at a bottom surface of said vibrating electrode, (c) an electret layer facing to the vibrating electrode, and (d) a back electrode in contact with a bottom surface of the electret layer, (e) wherein a microgap between ten nanometers and 100 micrometers is established between the vibrating-plate-insulating layer and the electret layer, and a central line average roughness Ra of the vibrating electrode, including a bending under a loaded condition, is $1/10$ or less of a gap width measured between the bottom surface of the vibrating electrode and a top surface of the electret layer.

A second aspect of the present invention inheres in an electro-mechanical transducer encompassing (a) a vibrating electrode having a flat vibration surface under no load condition, (b) an electret layer facing to the vibrating electrode, (c) an electret-insulating layer joined to a top surface of the electret layer, and (d) a back electrode in contact with a

bottom surface of the electret layer, (e) wherein a microgap between ten nanometers and 100 micrometers is established between the vibrating electrode and the electret-insulating layer, and a central line average roughness Ra of the vibrating electrode, including a bending under a loaded condition, is $\frac{1}{10}$ or less of a gap width measured between a bottom surface of the vibrating electrode and the top surface of the electret layer.

A third aspect of the present invention inheres in an electro-mechanical transducer encompassing (a) a vibrating electrode having a flat vibration surface under no load condition, (b) a vibrating-plate-insulating layer disposed at a bottom surface of the vibrating electrode, (c) an electret layer facing to the vibrating electrode, (d) an electret-insulating layer joined to a top surface of the electret layer, (e) and a back electrode in contact with a bottom surface of the electret layer, (f) wherein a microgap between ten nanometers and 100 micrometers is tri established between the vibrating-plate-insulating layer and the electret-insulating layer, and a central line average roughness Ra of the vibrating electrode, including a bending under a loaded condition, is $\frac{1}{10}$ or less of a gap width measured between the bottom surface of the vibrating electrode and the top surface of the electret layer.

A fourth aspect of the present invention inheres in a manufacturing method of an electro-mechanical transducer, encompassing (a) laminating a vibrating electrode on a vibrating-plate-insulating layer and implementing a vibrating plate, (b) reversing the vibrating plate, and providing a spacer on the vibrating-plate-insulating layer, (c) stacking an electret-insulating layer on the vibrating-plate-insulating layer through the spacer, (d) preparing an electret layer provided with a back electrode, and (e) mating the electret-insulating layer with the electret layer, by installing the electret layer provided with the back electrode, and a structure in which an electret-insulating layer is stacked through the spacer on the vibrating plate, into a receptacle.

A fifth aspect of the present invention inheres in a film-shaped electro-mechanical converter, encompassing a vibrating electrode; an electret layer facing to the vibrating electrode, establishing an element-install cavity between the vibrating electrode and the electret layer; a back electrode in contact with a bottom surface of the electret layer; at least one gap-insulating layer dividing an inside of the element-install cavity into upper and the lower directions so as to establish a plurality of microgaps in the inside the element-install cavity, each of the microgaps having an interval between ten nanometers and 40 micrometers, and the microgaps are stacked in the inside of the element-install cavity; and an amplifier electrically connected between the vibrating electrode and the back electrode. In film-shaped electro-mechanical converter according to the fifth aspect of the present invention, effective surface roughness of each of surfaces defining the plurality of microgaps is $\frac{1}{10}$ or less of a gap width measured in the element-install cavity.

A sixth aspect of the present invention inheres in an electro-mechanical converter, encompassing (a) a board mounting an amplifying circuit, (b) a film-shaped lower element having: a lower vibrating electrode, at least a part of the lower vibrating electrode is in contact with a bottom surface of the board and the lower vibrating electrode is electrically connected to the amplifier; a lower electret layer facing to the lower vibrating electrode establishing a lower element-install cavity between the lower electret layer and the lower vibrating electrode; a lower back electrode in contact with a bottom surface of the lower electret layer, and at least one lower gap-insulating layer configured to divide an inside of the lower element-install cavity into upper and a lower directions so as to estab-

lish a plurality of lower microgaps in the inside of the lower element-install cavity, each of the lower microgaps having an interval between ten nanometers and 40 micrometers, and (c) a film-shaped upper element having: an upper back electrode, at least a part of the upper back electrode is in contact with a top surface of the board and the upper back electrode is electrically connected to the amplifying circuit; an upper electret layer in contact with a top surface of the upper back electrode; an upper vibrating electrode facing to the upper electret layer establishing an upper element-install cavity between the upper vibrating electrode and the upper electret layer; and at least one upper gap-insulating layer configured to divide an inside of the upper element-install cavity into upper and a lower directions so as to establish a plurality of upper microgaps in the inside of the upper element-install cavity, each of the upper microgaps having an interval between ten nanometers and 40 micrometers. In the electro-mechanical converter according to the sixth aspect of the present invention, effective surface roughness of each of surfaces defining the lower and upper microgaps is $\frac{1}{10}$ or less of a gap width measured in the corresponding lower and upper element-install cavities, respectively.

A seventh aspect of the present invention inheres in a film-shaped electro-mechanical converter, encompassing (a) a common back electrode connected to an amplifying circuit, (b) a lower element having; a lower electret layer in contact with a bottom surface of the common back electrode; a lower vibrating electrode facing to the lower electret layer establishing a lower element-install cavity between the lower vibrating electrode and the lower electret layer; and at least one lower gap-insulating layer configured to divide an inside of the lower element-install cavity into upper and a lower directions so as to establish a plurality of lower microgaps in the inside of the lower element-install cavity, each of the lower microgaps having an interval between ten nanometers and 40 micrometers, and (c) an upper element having: an upper electret layer in contact with a top surface of the common back electrode; an upper vibrating electrode facing to the upper electret layer establishing an upper element-install cavity between the upper vibrating electrode and the upper electret layer; and at least one upper gap-insulating layer configured to divide an inside of the upper element-install cavity into upper and a lower directions so as to establish a plurality of upper microgaps in the inside of the upper element-install cavity, each of the upper microgaps having an interval between ten nanometers and 40 micrometers. In the film-shaped electro-mechanical converter according to the seventh aspect of the present invention, effective surface roughness of each of surfaces defining the lower and upper microgaps is $\frac{1}{10}$ or less of a gap width measured in the corresponding lower and upper element-install cavities, respectively.

A eighth aspect of the present invention inheres in a film-shaped electro-mechanical converter having a plurality of elements being on a common spacer film, each of the elements encompassing a vibrating electrode; an electret layer facing to the vibrating electrode establishing an element-install cavity between the electret layer and the vibrating electrode; a back electrode in contact with a bottom surface of the electret layer; and at least one gap-insulating layer configured to divide an inside of the element-install cavity into upper and a lower directions so as to establish a plurality of microgaps in the inside of the element-install cavity, each of the microgaps having an interval between ten nanometers and 100 micrometers. In the film-shaped electro-mechanical converter according to the eighth aspect of the present invention, the plurality of elements are connected to each other so that the vibrating electrodes of the respective elements have a

common potential, and that the back electrodes of the respective elements have a common potential, and the back electrodes are connected to a common amplifying circuit. And further, in each of the elements of the film-shaped electro-mechanical converter according to the eighth aspect of the present invention, effective surface roughness of each of surfaces defining the plurality of microgaps is $\frac{1}{10}$ or less of a gap width measured in the element-install cavity.

A ninth aspect of the present invention inheres in a film-shaped electro-mechanical converter, encompassing an inner electrode films connected to an amplifying circuit, the inner electrode films having a plurality of empty areas being arrayed in a shape of a matrix; a lower electret layer in contact with a bottom surface of the inner electrode films; a lower outer electrode film facing to the lower electret layer establishing a lower element-install cavity between the lower outer electrode film and the lower electret layer, having a pattern of empty areas differing from a planer pattern of the inner electrode films; at least one lower gap-insulating layer configured to divide an inside of the lower element-install cavity into upper and a lower directions so as to establish a plurality of lower microgaps in the inside of the lower element-install cavity, each of lower microgaps having an interval between ten nanometers and 40 micrometers; an upper electret layer in contact with a top surface of the inner electrode films; an upper outer electrode film facing to the upper electret layer establishing an upper element-install cavity between the upper outer electrode film and the upper electret layer, having a pattern of empty areas differing from a planer pattern of the inner electrode films; and at least one upper gap-insulating layer configured to divide an inside of the upper element-install cavity into upper and a lower directions so as to establish a plurality of upper microgaps in the inside of the upper element-install cavity, each of the upper microgaps having an interval between ten nanometers and 40 micrometers. In the film-shaped electro-mechanical converter according to the ninth aspect of the present invention, wherein effective surface roughness of each of surfaces defining the lower and upper microgaps is $\frac{1}{10}$ or less of a gap width measured in the corresponding lower and upper element-install cavities, respectively.

A tenth aspect of the present invention inheres in a film-shaped electro-mechanical converter, encompassing a plurality of vertical signal lines running in a vertical direction; a plurality of vertical selection signal wirings which are insulated from the plurality of vertical signal lines and run in a direction orthogonal to the plurality of vertical signal lines; a spacer film provided above the plurality of vertical signal lines and the plurality of vertical selection signal wirings, a plurality of penetration holes are arrayed at positions inside a pattern of grids implemented by the plurality of vertical signal lines and the plurality of vertical selection signal wirings, respectively; a common electret layer disposed on an entire surface of a sensor array area, being contact with a top surface of the spacer film; a plurality of back electrodes arrayed independently of each other, being contact with a part of a bottom surface of the electret layer, in the inside of the penetration holes, respectively; a plurality of amplifying circuits arrayed in the inside of the penetration holes, independently from each other, being connected to one of the back electrodes, one of the plurality of vertical signal lines, and one of the plurality of vertical selection signal wirings, respectively; a vibrating electrode facing to the electret layer, in such a way that element-install cavity independent of each other are arrayed, above each of the penetration holes; and at least one gap-insulating layer configured to divide an inside of each of the element-install cavity into upper and a lower directions so

as to establish a plurality of microgaps in the inside of each of the element-install cavity, each of the microgaps having an interval between ten nanometers and 40 micrometers. In the film-shaped electro-mechanical converter according to the tenth aspect of the present invention, effective surface roughness of each of surfaces defining each of the plurality of microgaps is $\frac{1}{10}$ or less of a gap width measured in the element-install cavity.

BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1 is a schematic sectional view illustrating a rough configuration of an electro-mechanical transducer (ultrasonic probe) according to a first embodiment of the present invention;

FIG. 2 is a schematic sectional view explaining vibrations caused by a deformation of a microgap in the electro-mechanical transducer according to the first embodiment of the present invention;

FIG. 3 is a schematic sectional view illustrating a state of a microgap, in a situation that tolerance of each of thicknesses of a vibration-plate-insulating layer and an electret-insulating layer is $\pm 10\%$, in which the vibration-plate-insulating layer and the electret-insulating layer are brought into contact with each other through aggregated silicon particles;

FIG. 4 is a schematic sectional view illustrating a configuration of a system, in which an electro-mechanical transducer according to the first embodiment is used as a transmitter-side-ultrasonic probe so that ultrasonic wave can be generated, and the generated ultrasonic wave propagates through a silicon block, and then the ultrasonic wave propagated through the silicon block is received by another electro-mechanical transducer according to the first embodiment as a receiver-side-ultrasonic probe;

FIG. 5 is a view representing a transmission/reception property obtained by the transmitter-side-ultrasonic probe and the receiver-side-ultrasonic probe, which are illustrated in FIG. 4, between the transmitter-side-ultrasonic probe and the receiver-side-ultrasonic probe, the ultrasonic wave propagates in the silicon block;

FIG. 6 is a schematic sectional view illustrating a configuration in which an electro-mechanical transducer according to a first comparison-example is used as the transmitter-side-ultrasonic probe, and the ultrasonic wave is generated and propagated through the silicon block, and then the ultrasonic wave propagated through the silicon block is received by another electro-mechanical transducer according to the first comparison-example as the receiver-side-ultrasonic probe;

FIG. 7 is a view representing a transmission/reception property when the transmitter-side-ultrasonic probe according to the first comparison-example and the receiver-side-ultrasonic probe according to the first comparison-example illustrated in FIG. 5 are used to propagate the ultrasonic wave through the silicon block;

FIG. 8 is a schematic sectional view illustrating a configuration in which an electro-mechanical transducer according to a second comparison-example is used as the transmitter-side-ultrasonic probe, and the ultrasonic wave is generated and propagated through the silicon block, and then the ultrasonic wave propagated through the silicon block is received by using the electro-mechanical transducer according to the second comparison-example as the receiver-side-ultrasonic probe;

FIG. 9 is a view representing a transmission/reception property when the transmitter-side-ultrasonic probe according to the second comparison-example and the receiver-side-ultrasonic probe according to the second comparison-ex-

ample illustrated in FIG. 8 are used to propagate the ultrasonic wave through the silicon block;

FIG. 10 is a view representing a result when a sine wave signal (a single wave) is supplied to one of the electro-mechanical transducers according to the first embodiment in FIG. 4 and then the transmission/reception is carried out;

FIG. 11 is a view representing a result when the sine wave signal (a single wave) is supplied to one of the electro-mechanical transducers according to the second comparison-example in FIG. 8 and then the transmission/reception is carried out;

FIG. 12 is a sectional view of a measurement system for measuring a charge holding characteristics of an electret layer by the bending of a vibrating electrode;

FIG. 13 is an x-y correlation diagram that illustrates the charge holding characteristics of the electret layer illustrated in FIG. 12, by the bending of the vibrating electrode;

FIG. 14 is a schematic process-flow-sectional view illustrating a rough configuration of the electro-mechanical transducer (ultrasonic probe) according to the first embodiment of the present invention;

FIG. 15 is a schematic sectional view illustrating a rough configuration of an electro-mechanical transducer (hydrophone) according to a second embodiment of the present invention;

FIG. 16 is a schematic process-flow-sectional view illustrating a manufacturing method of the electro-mechanical transducer (hydrophone) according to the second embodiment of the present invention;

FIG. 17 is a schematic sectional view illustrating a rough configuration of an electro-mechanical transducer (ultrasonic sensor) according to a third embodiment of the present invention;

FIG. 18 is a schematic process-flow-sectional view illustrating a manufacturing method of the electro-mechanical transducer (ultrasonic sensor) according to the third embodiment of the present invention;

FIG. 19 is a schematic sectional view illustrating a rough configuration of an electro-mechanical transducer (MEMS microphone) according to a fourth embodiment of the present invention;

FIG. 20 is a schematic sectional view illustrating a rough configuration of a film-shaped electro-mechanical converter according to a fifth embodiment of the present invention;

FIG. 21 is a schematic sectional view illustrating a detailed structure of a microgap used in the film-shaped electro-mechanical converter according to the fifth embodiment;

FIG. 22 is a view that illustrates a relation between sensitivity and frequency in the film-shaped electro-mechanical converter according to the fifth embodiment, in which the lamination numbers n of high density polyethylene (HDPE) films ($n=5, 10, 40$ and 100) are used as parameters

FIG. 23 is a schematic process-flow-sectional view illustrating a manufacturing method of the film-shaped electro-mechanical converter according to the fifth embodiment (No. 1);

FIG. 24 is a schematic process-flow-sectional view illustrating the manufacturing method of the film-shaped electro-mechanical converter according to the fifth embodiment (No. 2);

FIG. 25 is a schematic process-flow-sectional view illustrating the manufacturing method of the film-shaped electro-mechanical converter according to the fifth embodiment (No. 3);

FIG. 26 is a schematic process-flow-sectional view illustrating a manufacturing method of the film-shaped electro-mechanical converter according to the fifth embodiment (No. 4);

FIG. 27 is a schematic process-flow-sectional view illustrating the manufacturing method of the film-shaped electro-mechanical converter according to the fifth embodiment (No. 5);

FIG. 28 is a schematic process-flow-sectional view illustrating the manufacturing method of the film-shaped electro-mechanical converter according to the fifth embodiment (No. 6);

FIG. 29 is a conceptual process-flow-sectional view, corresponding to an outline (main portion) of the manufacturing method of the film-shaped electro-mechanical converter, which has been illustrated in FIGS. 23 to 28;

FIG. 30(a) is a schematic sectional view illustrating a rough configuration of a film-shaped electro-mechanical converter (microphone A) when a sound pressure Φ_1 is received from the vibration plate side, and FIG. 30(b) is a schematic sectional view illustrating a rough configuration of a film-shaped electro-mechanical converter (microphone B) when a sound pressure Φ_2 is received from the electret layer side;

FIG. 31 is a schematic sectional view illustrating a rough configuration of the film-shaped electro-mechanical converters according to the second embodiment of the present invention, in which the microphone A illustrated in FIG. 30(a) and the microphone B illustrated in FIG. 30(b) are used;

FIG. 32 is a schematic sectional view illustrating a rough configuration of a film-shaped electro-mechanical converter according to a seventh embodiment of the present invention;

FIG. 33 is a schematic view illustrating a situation, in which a film-shaped electro-mechanical converter according to an eighth embodiment of the present invention is bonded on a measurement target, such that, when the surface of the measurement target is curved, the shape of the film-shaped electro-mechanical converter is fitted to the curved topology;

FIG. 34 is a schematic view illustrating a configuration, in which the film-shaped electro-mechanical converter according to the eighth embodiment that is deformed to a bowl-like shape, and the deformed film-shaped electro-mechanical converter converges the ultrasonic waves ϕ transmitted from the measurement target.

FIG. 35 is a schematic sectional view illustrating a rough configuration of a film-shaped electro-mechanical converter according to a ninth embodiment of the present invention, in which n units ($n=2$) are stacked and pasted to each other;

FIG. 36 is a schematic sectional view illustrating a rough configuration of another film-shaped electro-mechanical converter according to the ninth embodiment and illustrates a case in which n ($n \leq 3$) units are stacked and joined each other;

FIG. 37 is a schematic sectional view illustrating a rough configuration of a film-shaped electro-mechanical converter according to a tenth embodiment of the present invention, in which a sensing area is divided into many elements;

FIG. 38 is a plan view illustrating outline of an interconnection structure of a film-shaped electro-mechanical converter according to an eleventh embodiment of the present invention, in which the sensing area is divided into the many elements;

FIG. 39 is a sectional view taken from A-A direction in FIG. 38;

FIG. 40 is a schematic plan view illustrating patterns of an inner electrode film and outer electrode films in the film-shaped electro-mechanical converter according to the eleventh embodiment;

FIG. 41 is a schematic plan view illustrating a situation, in which a planer shape is changed, when a part of the film-shaped electro-mechanical converter according to the eleventh embodiment is cut away, in response to a status of use (shape of a target to be measured);

FIG. 42 is a schematic plan view illustrating the whole of a film-shaped electro-mechanical converter according to a twelfth embodiment of the present invention;

FIG. 43 is a schematic sectional view illustrating a structure of a part of elements of the film-shaped electro-mechanical converter according to the twelfth embodiment illustrated in FIG. 42;

FIG. 44 is a circuit diagram illustrating a rough configuration of an amplifying circuit, which is assigned in each of the elements in the film-shaped electro-mechanical converter according to the twelfth embodiment;

FIG. 45 is a schematic sectional view illustrating a rough configuration of a film-shaped electro-mechanical converter according to a thirteenth embodiment of the present invention;

FIG. 46 is a schematic sectional view illustrating a structure of a microgap used in the film-shaped electro-mechanical converter according to the thirteenth embodiment of the present invention;

FIG. 47 is a schematic sectional view illustrating another structure of the microgap used in the film-shaped electro-mechanical converter according to the thirteenth embodiment of the present invention;

FIG. 48 is a schematic sectional view illustrating a rough configuration of the film-shaped electro-mechanical converter according to the thirteenth embodiment of the present invention, in a scheme such that there is no protrusion;

FIG. 49 is a view illustrating output voltages when an acoustic wave of 1 kHz is irradiated to the film-shaped electro-mechanical converter according to the thirteenth embodiment of the present invention, in which protrusions are provided, comparing with a case, in which no protrusion is provided;

FIG. 50 is a schematic sectional view illustrating a structure of a microgap of a film-shaped electro-mechanical converter according to another embodiment of the present invention;

FIG. 51 is a schematic sectional view illustrating another structure of microgap of a film-shaped electro-mechanical converter according to still another embodiment of the present invention;

FIG. 52 is a schematic sectional view illustrating still another structure of microgap of a film-shaped electro-mechanical converter according to still another embodiment of the present invention;

FIG. 53 is a schematic sectional view illustrating yet still another structure of microgap of a film-shaped electro-mechanical converter according to yet still another embodiment of the present invention; and

FIG. 54 is a schematic sectional view illustrating further another structure of microgap of a film-shaped electro-mechanical converter according to further another embodiment of the present invention.

DETAILED DESCRIPTION OF THE EMBODIMENTS

The first to thirteenth embodiments of the present invention will be described below with reference to the drawings. In the following notifications on the drawings, the same or similar reference numerals are assigned to the same or similar parts and elements. However, the drawings are only diagrammatic.

Then, attention should be paid to the fact that the relations between thicknesses and planer dimensions, the ratios between thicknesses of respective layers, and the like differ from the actual values. Also, the thicknesses, dimensions and the like of the respective layers, which are exemplified and described in the first to thirteenth embodiments, should not be limitedly construed, and the specific thicknesses and dimensions should be judged by considering the following explanations. In particular, attention should be paid to the fact that the thicknesses, dimensions and the like can be determined to various values, on the basis of design schemes, requested properties and detailed requested particulars. Also, naturally, the portion in which the relations and ratios between the mutual dimensions are different is included even between the mutual drawings.

Also, the first to thirteenth embodiments, which will be described below, only exemplify the apparatuses and methods to specify the technical idea of the present invention. As for the technical idea of the present invention, the material qualities, shapes, structures, arrangements and the like of the configuration parts are not limited to the followings. Various changes can be added to the technical idea of the present invention, within the technical scopes prescribed by Claims.

First Embodiment

As illustrated in FIG. 1, an electro-mechanical transducer according to a first embodiment of the present invention is a ultrasonic probe encompassing a vibrating plate 15 that has a flat vibration surface under no load condition; an electret layer 13 in which polarization directions are aligned, defined by a flat first principal surface facing to the vibration surface of the vibrating plate 15 and a second principal surface facing in parallel to the first principal surface; a back electrode 17 in contact with the second principal surface of the electret layer 13; and amplifying means (19, 9) connected between the vibrating plate 15 and the back electrode 17. The back electrode 17 and the electret layer 13 may be metallurgically joined or may be adhered by an adhesive agent and the like, or may be merely brought into contact by a mechanical pressure. Although the illustrations on a plan view or a bird's eye view are omitted, each of the vibrating plate 15, the electret layer 13 and the back electrode 17 in the ultrasonic probe illustrated in FIG. 1 has a shape of a circular disk whose radius is between, for example, three millimeters and 40 millimeters. The vibrating plate 15 contains a vibrating electrode 15b made of conductor and a vibrating-electrode-insulating film 15a on the bottom surface of the vibrating electrode 15b, as illustrated in FIG. 1. Although the illustration is omitted, in the vibrating plate 15, as necessary, a matching layer made of insulating layer may be formed on the top surface of the vibrating electrode 15b so that the matching characteristics of the acoustic impedance with a medium can be improved.

Under no load condition, the first principal surface of the electret layer 13 faces in parallel to the vibration surface of the vibrating plate 15. Here, the amplifying means (19, 9) contains an amplifying circuit 19 connected to the back electrode 17 and an additional circuit 9 connected to the amplifier (FET) 19. FIG. 1 shows a receiver-side-ultrasonic probe, in which the additional circuit 9 encompasses a direct current power supply E whose one terminal is grounded; a buffer resistor R connected between the direct current power supply E and the amplifier (FET) 19; and a coupling capacitor C having one electrode connected to a connection node between the buffer resistor R and the amplifier (FET) 19 and the other electrode serving as an output terminal. External circuitry (illustration is omitted) is connected to the output terminal of

the coupling capacitor C serving as the output terminal of the amplifying means (19, 9). Then, the external circuitry carries out signal processes necessary for an external communication unit and an external recording/storage unit that are connected to the microphone. The amplifying means (19, 9) in the electro-mechanical transducer according to the first embodiment of the present invention measures the charges induced on the electret layer 13, in association with the displacement of the vibration surface of the vibrating plate 15, because the amplifier (FET) 19 amplifies the potential across the back electrode 17 and the vibrating plate 15. On the other hand, in a transmitter-side-ultrasonic probe, an additional circuit 9 encompasses a direct current power supply E whose one terminal is grounded; a buffer resistor R connected between the direct current power supply E and the amplifier (FET) 19; and a coupling capacitor C having one electrode connected to the connection node between the buffer resistor R and the amplifier (FET) 19 and the other electrode serving as the input terminal. An external circuitry (illustration is omitted) is connected to the input terminal of the coupling capacitor C serving as the input terminal of the amplifying means (19, 9), and an input signal is supplied from the external circuitry, and the input signal amplified by the amplifier (FET) 19 is applied across the back electrode 17 and the vibrating plate 15.

A macroscopic "gap width W_g " is defined between the vibrating electrode 15b and the electret layer 13. The W_g may be in a range between 0.1 micrometer and 100 micrometers. And a microgap that is defined as the microscopic air gap defined between the vibrating-electrode-insulating film 15a and an electret-insulating layer 14e, in which a gap width is between ten nanometers and 100 micrometers. In the microgap, because the dielectric breakdown strength of air in the gap is between five and 200 MV/m, the dielectric breakdown strength is improved as compared with the dielectric breakdown strength of the macroscopic gap. In the case of the macroscopic gap width W_g , the dielectric breakdown strength of air is about 3 MV/m. However, when insulating gas such as fluorine based gas and the like, other than air, is filled in the macroscopic gap width W_g , or alternatively, when the macroscopic gap width W_g is evacuated to vacuum, the dielectric breakdown strength of the macroscopic gap width W_g can be further improved. The vibrating electrode 15b is pulled and deformed by the electrostatic force between the electret layer 13 and the vibrating electrode 15b, and the deformation of the vibrating electrode 15b decreases the dielectric breakdown strength of the microgap. When the depth of concave and height of convex generated at the surface of the gap side of the vibrating electrode 15b in the deformed state is represented by a central line average roughness Ra, in order to obtain a high dielectric breakdown strength as mentioned above, the central line average roughness Ra must be $1/10$ or less of the gap width. The reason why Ra must be $1/10$ of the gap width will be described later by using FIGS. 12 and 13.

For the vibrating plate 15, any material may be used, in the condition that the bending is $1/10$ or less of the gap width W_g , as far as the vibrating electrode 15b is made to be superior in electrical conductivity and the vibrating-electrode-insulating film 15a is made to be superior in electrical insulation. The weight of the vibrating plate 15 is preferred to be light, in order to operate at higher frequencies, although the rigidity of the vibrating plate 15 is required to be high. Therefore, a material having a high value of specific rigidity ((elastic modulus)/density) is preferred to be used in one of the vibrating electrode 15b of the vibrating plate 15, the vibrating-electrode-insulating film 15a attached under the bottom surface of the vibrating electrode 15b, or the matching layer (whose illustration is omitted in FIG. 1) deposited on the top

surface of the vibrating electrode 15b. For this reason, as for the vibrating plate 15, a configuration such that an aluminum layer, an aluminum alloy layer, a magnesium layer or a magnesium alloy layer is used as the vibrating electrode 15b, and an ethylene tetrafluoride-propylene hexafluoride copolymer resin (FEP resin) layer may be laminated to the vibrating electrode 15b as the vibrating-electrode-insulating film 15a can be employed. Or, a polyethylene terephthalate (PET) layer, a polyethylene naphthalate (PEN), an epoxy resin layer, a phenol resin layer and the like can be used as the vibrating-electrode-insulating film 15a, and an aluminum layer is deposited on the vibrating-electrode-insulating film 15a so as to implement the vibrating electrode 15b. Or, an alumina layer, a silicon nitride layer, a silicon carbide ceramics layer and the like can be used as the vibrating-electrode-insulating film 15a, and on the vibrating-electrode-insulating film 15a, an aluminum layer is deposited or a silver layer is burned so as to implement the vibrating electrode 15b. In addition, a silicon substrate joined with a FEP resin layer or a silica layer, or the like, which is used in the insulating layer of earlier electret microphones, can be used for the vibrating-electrode-insulating film 15a. However, in this case, the increase of the thickness is limited such that the bending is $1/10$ or less of the gap width. Thus, the present architecture greatly differs from the designing scheme of the earlier electret microphone. Also, the other resins superior in insulation such as silicon based resin, fluorine based resin, polyethylene based resin, polyester, polypropylene, polycarbonate, polystyrene, urethane, ABS, flexible vinyl chloride and the like can be used as material for the vibrating-electrode-insulating film 15a, and the vibrating electrode 15b is attached on the vibrating-electrode-insulating film 15a by joining, depositing or burning so as to implement the vibrating plate 15. In this case, the thickness of the vibrating electrode 15b or vibrating-electrode-insulating film 15a shall be increased to ensure the rigidity necessary for the vibrating plate 15.

For both of spacers 41 and the electret-insulating layer 14e, the material superior in electric insulation characteristics shall be used. Specifically, ceramics such as silica, alumina, silicon nitride, silicon carbide and the like, or alternatively, resins such as silicon based resin, fluorine based resin, polyethylene resin (including PET and the like), polyester, polypropylene, polycarbonate, polystyrene, urethane, ABS, flexible vinyl chloride and the like can be used. Also, for one or both of the spacers 41 and the electret-insulating layer 14e, the material whose elastic modulus is 2 GPa or less is used. However, when the vibrating-electrode-insulating film 15a exists on the side of the vibrating plate 15 and also the elastic modulus of the vibrating-electrode-insulating film 15a is 2 GPa or less, there is no limit for the elastic modulus of the spacers 41 and the electret-insulating layer 14e. As the material having the superior electric insulation characteristics and the elastic modulus of 2 GPa or less, specifically, there are resins such as silicon based resin, fluorine based resin, polyethylene based resin, polyester resin, polypropylene resin, polycarbonate resin, polystyrene resin, urethane resin, acrylonitrile butadiene styrene resin (ABS resin), the flexible vinyl chloride resin and the like.

As the spacers 41, other than the particles whose particle diameters are between ten nanometers and 100 micrometers as illustrated in FIG. 1, at the bottom surface of the vibrating-electrode-insulating film 15a, at the top surface of the electret-insulating layer 14e, or alternatively, when the vibrating-electrode-insulating film 15a is omitted, at the bottom surface of the vibrating electrode 15b, or when the electret-insulating layer 14e is omitted, at the top surface of the electret layer 13, micro protrusions, or bumps, may be formed by pulse laser

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irradiation, lithography, etching, press and the like so that the height of micro protrusions lies between ten nanometers and 100 micrometers. The micro protrusions may be formed at any one of surfaces of the bottom surface of the vibrating-electrode-insulating film **15a**, the top surface of the electret-insulating layer **14e**, the bottom surface of the vibrating electrode **15b**, or the top surface of the electret layer **13**, or alternatively, at both surfaces of any of combinations of the bottom surface of the vibrating-electrode-insulating film **15a**, the top surface of the electret-insulating layer **14e**, the bottom surface of the vibrating electrode **15b**, or the top surface of the electret layer **13**, facing to each other. Each of the particles and the protrusions can serve as supporting members between the vibrating-electrode-insulating film **15a** and the electret-insulating layer **14e**, between the vibrating electrode **15b** and the electret-insulating layer **14e** when the vibrating-electrode-insulating film **15a** is omitted, between the vibrating-electrode-insulating film **15a** and the electret layer **13** when the electret-insulating layer **14e** is omitted, or between the vibrating electrode **15b** and the electret layer **13** when both of the vibrating-electrode-insulating film **15a** and the electret-insulating layer **14e** are omitted, and by these supporting members, the microgap is established. As far as the microgap can be formed, although the spacers **41** may be formed into any of arbitrary geometry, the curvatures of the contact points of the protrusions are desired to be great. Also, when a layer having an appropriate surface roughness, such that maximum height (R_{max}) lies between ten nanometers and 100 micrometers is stacked, the microgap can be established without using the spacers **41**.

The vibrating-electrode-insulating film **15a** and the electret-insulating layer **14e** are the layers of insulators as mentioned above, namely, the protrusions between ten nanometers and 100 micrometers are formed at the surface, or alternatively, the particles whose particle diameters are between ten nanometers and 100 micrometers are adhered on the surface. As necessary, a plurality of insulating layers can be laminated so as to increase the number of the microgap layers. Or, only at a limited area of the surface of the insulating layer, the protrusions are selectively formed or the particles are selectively adhered, and the remaining area is tightly adhered to, or dried and brought into contact with the facing insulating layer, where the microgap is established by the surface roughness. As far as the gap width is 100 micrometers or less, by increasing the lamination number of the insulating films, the acoustic damping characteristics can be improved. Also, as the insulating layer is made thicker, because the gap width becomes wider, the drop in the dielectric breakdown strength of the microgap, which is caused by the bending of the vibrating electrode **15b**, can be protected. However, the increase in the gap width leads to the drop in the electric field strength inside the gap. For this reason, the optimum number of the laminations shall be determined on the basis of the thickness of the insulating layer, the structure of the microgap and the like.

The electret layer **13** must have a surface potential that can establish electric fields between 5 and 200 MV/m across the gap. As the typical examples of the electret layer **13**, the following two schemes can be employed:

- (a) Insulating layer electrified by corona discharge, such as the electret layer **13**, in which the charges are generated on the fluorine based resin or silica surface by corona discharge.
- (b) Ferroelectric layer electrified by heating:
As the ferroelectric layer, it is possible to employ single-crystalline ferroelectric material, polycrystalline ferroelectric material, or a crystalline ferroelectric polymer.

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As the ferroelectric material, it is possible to use perovskite compound, tungsten bronze structure compound, bismuth based layered structure compound, wurtzite structure crystal, zinc oxide, quartz crystal, Rochelle salt and the like. For example, the ferroelectric material such as lead-zirconium-titanate (PZT), LiNbO_3 , polyvinylidene difluoride (PVDF) and the like, in which the polarization directions are oriented along one direction, is heated so that the polarization is temporally reduced by pyroelectric effect, and the surface charges are consequently removed, and the ferroelectric material is again cooled to room temperature, and the electret layer **13** is consequently implemented by the ferroelectric material.

The thickness of the electret layer **13** can be selected as, for example, about 20 to 400 micrometers, and the thickness of the back electrode **17** can be selected as, for example, about ten micrometers to 100 micrometers, and the thickness of the vibrating plate **15** can be selected as, for example, about ten micrometers to 100 micrometers. However, the specific thicknesses and radiuses of the vibrating plate **15**, the electret layer **13** and the back electrode **17** may be determined on the basis of design schemes, requested performances and detailed requested particulars.

A bottom plate of a receptacle **81** implemented by a metallic circular disk having an interconnect opening is connected to a bottom end surface of a holder **89**. The conductive (metallic) receptacle **81** may be implemented by a receptacle body and a bottom plate connected to the receptacle body through soldering and the like. The ground wiring from the amplifying circuit **19** is connected to the bottom plate of the receptacle **81** through soldering. The amplifying circuit **19** is electrically connected to the back electrode **17** through a solder **91** fused around the center of the back electrode **17**. Although a through hole (illustration is omitted) penetrating through the back electrode **17** and the electret layer **13** are formed in the back electrode **17** and the electret layer **13**, the through hole is sealed by using the soldering and the like so that (as necessary), gas (insulating gas) having a high insulating characteristics can be filled in the gap space between the electret layer **13** and the vibrating plate **15**. As the insulating gas, it is possible to employ nitrogen, sulfur hexafluoride and the like. In addition to the insulating gas, even if the insulating fluid such as silicon oil and the like can be filled in the gap space between the electret layer **13** and the vibrating plate **15**, so as to increase the dielectric breakdown strength, which makes the generation of the discharge difficult. As a result, amount of charges on the surface of the electret layer **13** that is induced by discharging can be decreased, thereby improving the sensitivity. Instead of filling the insulating gas or insulating fluid, even if the gap space between the electret layer **13** and the vibrating plate **15** is evacuated to establish vacuum, the sensitivity can be improved.

By the way, each of the vibrating plate **15**, the electret layer **13** and the back electrode **17** is not required to have the shape of the circular disk, and the vibrating plate **15**, the electret layer **13** and the back electrode **17** may have another geometrical shape, such as an ellipse, a rectangle or the like. In this case, naturally, the other members such as the conductive (metallic) receptacle **81** and the like shall be designed so as to agree with the geometrical shapes of the vibrating plate **15**, the electret layer **13** and the back electrode **17**.

—Dielectric Breakdown Strength of Air in Micro Gap—

When a potential difference is established across two electrodes sandwiching an air gap in between, under atmospheric pressure, it is known that the dielectric breakdown strength of air increases as the inter-electrode distance between two elec-

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trodes decreases, and the maximum value can be established at an inter-electrode distance between about one micrometer and two micrometers. However, as the curvature of the protrusion at the surface of the electrode becomes higher, the electric field is concentrated at the protruded portion, and the dielectric breakdown strength is decreased. Thus, when size of concave/convex structure at the electrode surface is represented by the central line average roughness Ra, Ra must be $1/10$ or less of the gap width, and it is desired to be $1/100$ or less, which will be described later by using FIGS. 12 and 13.

In any of the earlier electret microphones, the vibrating electrode 15b is greatly deformed by the electrostatic force between the electret layer 13 and the vibrating electrode 15b, where the central line average roughness Ra of the surface of the vibrating electrode 15b indicates the value that includes the deformation caused by the bending of the vibrating electrode 15b. Thus, the central line average roughness Ra of the vibrating electrode 15b of the earlier electret microphone exceeds $1/10$ of the gap width W_g (the topology of the earlier electret microphone corresponds to the configuration in which both of the vibrating-electrode-insulating film 15a and the electret-insulating layer 14e are omitted in FIG. 1, and the gap width W_g is defined as the distance between the electret layer 13 and the vibrating electrode 15b).

In the electro-mechanical transducer according to the first embodiment of the present invention, the width of the microgap between the vibrating-electrode-insulating film 15a and the electret-insulating layer 14e determines the dielectric breakdown strength of air. In the configuration of the electro-mechanical transducer according to the first embodiment, the insertion of the vibrating-electrode-insulating film 15a and the electret-insulating layer 14e enlarges the gap width W_g , and can decrease the central line average roughness Ra (that includes a deformation caused by the bending of the vibrating electrode 15b through the spacers 41) of the bottom surface of the vibrating-electrode-insulating film 15a (or, the bottom surface of the vibrating electrode 15b in a case when the vibrating-electrode-insulating film 15a is omitted) to be $1/10$ or less of the gap width W_g . Also, the surface roughness of the top surface of the electret-insulating layer 14e (or, the top surface of the electret layer 13, in a case when the electret-insulating layer 14e is omitted) similarly has influence on the dielectric breakdown strength of air in the gap. Also, Ra of the top surface of the electret-insulating layer 14e must be $1/10$ or less of the gap width, and it is desired to be $1/100$ or less.

—Reception Sensitivity—

When the electro-mechanical transducer according to the first embodiment of the present invention is used as an ultrasonic probe, the bending of the vibrating plate 15 and the deformation of the contact point in the microgap cause the vibrating plate 15 to be vibrated so that the acoustic wave (ultrasonic wave) can be transmitted or received. When the vibrating plate 15 of the ultrasonic probe is vibrated by the acoustic wave (ultrasonic wave), in accordance with the principle similar to an electret condenser microphone, the change in the capacitance of the gap results in the change in the potential difference across the electrodes, and an output ΔV_{out} is obtained as described by the following equation;

$$\Delta V_{out} = \Delta W_g E_g \quad (1)$$

$$E_g = V_e / W_g \quad (2)$$

E_g is the electric field strength in the gap, and ΔW_g is the amplitude of the vibrating plate 15, which is the summation of the amplitudes of the vibration caused by the bending and the vibration caused by the deformation of the contact point, W_g is the width of the entire gap, and V_e is the magnitude of the

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surface potential of the electret layer 13. At this time, the vibrating plate 15 is pulled from the electret layer 13 by the electrostatic force π_e , with q_d as unit charge:

$$\sigma_e = q_d E_g = \epsilon_g E_g^2 \quad (3)$$

Where, ϵ_g is the dielectric constant of the entire gap that includes the insulating layer. Attention should be paid to a fact that each of the protrusions (including the particles) in the microgap portion serves as a fulcrum, and therefore, with the electrostatic force σ_e , when the vibrating plate 15 is pulled to the gap side by the electrostatic force between the electret layer 13 and the vibrating plate 15, the vibrating plate 15 is statically bent, supported by the fulcrums. That is, the rigidity of the vibrating plate 15, the contact point density and the arrangement of the contact points in the microgap portion shall be designed in such a way that Ra of the surface at the gap side of the vibrating electrode 15b in the statically deformed state becomes $1/10$ or less of the gap width. Also, when the bending causes the two layers, implementing the microgap, mutually contact at a position different from the protrusions, the number of the contact points will increase, which severely reduces the contact rigidity. Thus, the contact of the two layers at the position different from the protrusions must be avoided, by increasing the rigidity of the vibrating plate 15, or alternatively, by increasing the height or density of the protrusion.

—Vibration Caused by Bending of Vibration Plate—

The vibration caused by the bending of the vibrating plate is similarly generated even in the earlier electret microphone. Also, even if an assumable maximum sound pressure causes the bending, the vibrating plate shall be designed such the two layers implementing the microgap will not be brought into contact with each other at the position except the protrusions.

Vibration Caused by Deformation of Micro Gap Portion—

The structure illustrated in FIG. 1 is illustrated as an example, and the microgap can be achieved without using the particles as the spacers 41. For example, as illustrated in FIG. 2, the microgap can be formed through a dry contact, in a condition that the bottom surface of the vibrating-electrode-insulating film 15a is very smooth, and that the top surface of the electret-insulating layer 14e has micro protrusions of a constant radius r, the micro protrusions are in dry contact with the bottom surface of the vibrating-electrode-insulating film 15a. For providing the micro protrusions of the constant radius r as illustrated in FIG. 2, a local thermal deformation may be generated when a pulse laser is irradiated to the bottom surface of the vibrating-electrode-insulating film 15a, or the precipitation of oligomers or the self-organization of polymers may be carried out by heating the entire film implementing the vibrating-electrode-insulating film 15a, or the micro protrusions may be formed by machining the vibrating-electrode-insulating film 15a such as a press working.

In a model in which the bottom surface of the vibrating-electrode-insulating film 15a has the micro protrusions of the constant radius r as illustrated in FIG. 2, a contact pressure σ is equal to σ_e and represented by the following equation:

$$\sigma = \sigma_e = (4/3) n S_d r^{1/2} W^{3/2} \quad (4)$$

$$1/S = ((1 - \nu_d^2)/S_d) + ((1 - \nu_g^2)/S_g) \quad (5)$$

Here, n represents the surface density of the protrusions, and w represents the displacement in the vibrating-electrode-insulating film 15a caused by the surface pressure, ν_d and the ν_g indicate Poisson ratios of the vibrating-electrode-insulating film 15a and the electret-insulating layer 14e, respectively, and S_d and S_g indicate the storage elastic moduli of the vibrating-electrode-insulating film 15a and the electret-insulating

layer **14e**, respectively. Here, the storage elastic modulus indicates the elastic modulus with respect to the elastic deformation in an acoustic frequency band (between 20 Hz and 10 GHz) received by the receiver-side-ultrasonic probe. Then, as the frequency becomes higher, both of S_d and S_g tend to be increased. Thus, S_d and S_g are assumed to be the values of the usable maximum frequency.

Then, a contact rigidity (boundary rigidity) K_g , which is a spring constant per unit area in the microgap between the vibrating-electrode-insulating film **15a** and the electret-insulating layer **14e**, is obtained by differentiating σ with respect to w :

$$K_g = 2nS'(rw)^{1/2} \quad (6)$$

If $K_g \ll S'$, the amplitude of the vibrating-electrode-insulating film **15a** agrees with the vibration of the microgap portion, and is inversely proportional to the K_g :

$$\Delta W_g = \Delta \sigma_d / K_g \quad (7)$$

From Eqs. (1), (3), (5), (6) and (7), the ΔV_{out} is represented as follows:

$$\Delta V_{out} = \Delta \sigma_d (E_g / (6\epsilon_g S^2 n^2 r))^{1/3} \quad (8)$$

From Eq. (8), in order to improve the reception sensitivity, it is understood that the electric field strength E_g in the gap shall be increased, the storage elastic moduli of one or both of the two layers with the microgap between shall be decreased, the radius r of the protrusion shall be made short, and the density n of the protrusions shall be decreased (the interval may be made wide). However, the drops in the radius r and the density n of the protrusion result in the increase in the bending of the vibrating-electrode-insulating film **15a**. Thus, as mentioned above, attention should be paid to the requirements that the central line average roughness R_a of the vibrating-electrode-insulating film **15a** shall be $1/10$ or less of the gap width, and that, also the contact density of the microgap portion shall not be increased by the bending.

—Influence on Transmission Output—

As for the transmission, when a voltage pulse of an amplitude ΔV_{in} is supplied to the transmitter-side-ultrasonic probe, a pressure $\Delta \sigma_{out}$ generated in the vibrating-electrode insulating film **15a** at the time of the transmission is represented as follows:

$$\begin{aligned} \Delta \sigma_{out} &= \epsilon_g ((V_e + \Delta V_{in}) / W_g)^2 - \epsilon_g (V_e / W_g)^2 \\ &\approx (2\epsilon_g E_g \Delta V_{in}) / W_g^2 \end{aligned} \quad (9)$$

Together with the bending of the vibrating-electrode-insulating film **15a** and the deformation of the contact point of the microgap portion, the vibrating-electrode-insulating film **15a** is changed on the basis of the $\Delta \sigma_{out}$, and the vibration of the vibrating-electrode-insulating film **15a** is generated, and the acoustic wave is transmitted. Thus, from Eq. (9), it is known that, when the gap width W_g is narrow and the electric field strength E_g of the gap is high, the transmission sound pressure becomes large and the transmission output is improved.

—Damping of Acoustic Wave—

As another merit of the microgap lies in the damping (attenuation) of the ultrasonic wave. At the boundary portion where the microgap does not contact owing to the existence of the spacers **41**, a reflection of the acoustic wave is generated. Thus, the acoustic wave that is propagated to the electret layer **13** is greatly attenuated in the microgap. When the acoustic wave is propagated to reach the electret layer **13**, the electret layer **13** is distorted to induce piezoelectric effect, and the

influence resulted from the piezoelectric effect may overlap with the reception output. Because the overlap of the piezoelectric effect will reduce the performance of the electret probe (ultrasonic probe), in the microgap portion, the acoustic wave is desired to be attenuated to the utmost extent. Providing with the microgap, the attenuation of the acoustic wave in the gap portion is dramatically increased.

Ultrasonic Transmission/Reception Property—

Let us consider an example in which the electro-mechanical transducer according to the first embodiment illustrated in FIG. 1 is applied to the ultrasonic probe (aerial ultrasonic probe) of aerial ultrasonic waves. In the example, the vibrating plate **15** encompasses a polyethylene terephthalate (PET) resin film having a thickness of 60 micrometers as the vibrating-electrode-insulating film **15a**, which is deposited on the bottom surface of an Al electrode plate having a thickness of one micrometer or less as the vibrating electrode **15b**, and the surface for the vibrating-electrode-insulating film **15a** of the Al electrode plate is finished to a mirror surface. Also, on the electret layer **13** whose surface potential is -2 kV, the PET resin layer having a thickness of ten micrometers is laminated as the electret-insulating layer **14e**, and on the electret-insulating layer **14e**, the silicon particles each having a diameter of five micrometers are adhered at an average interval of 500 micrometers as the spacers **41**. With the silicon particles, the microgap is formed between the PET resin layers, and the electric field of about 30 MV/m is applied from the electret layer **13**. At this time, the sum of the bending of the vibrating electrode **15b** and the deformation level of the silicon particle is 3.8 micrometers or less, and the vibrating-electrode-insulating film **15a** and the electret-insulating layer **14e** are never brought into contact with each other. Also, when the microgap is five micrometers or less, the dielectric breakdown strength of air is 60 MV/m or more. Thus, the dielectric breakdown of air in the microgap is not generated in the microgap. The reception sensitivity of this ultrasonic probe is -50 dB or more between 20 Hz and 1 MHz. Typically, the reception sensitivity of a piezoelectric aerial ultrasonic sensor in a narrow band in which the resonance is used is about -60 dB at -40 kHz, and it can be received at the sensitivity that is more higher than this and at a wider band.

Also, as for the transmission, the vibration amplitude of 3.4 nanometers is obtained for a voltage pulse input of 1 V. When lead-zirconium-titanate (PZT) is used as the material for the ultrasonic probe, the vibration amplitude greater than 3.4 nanometers can be obtained when the resonance is used. However, PZT can be used only at the resonant frequency. Under a non-resonant condition, only the vibration amplitude of about 0.3 nanometer is obtained in PZT. Thus, in the transmission in the wide frequency band, the ultrasonic probe of the present invention is very advantageous than the ultrasonic probe using PZT.

Let us consider another example, in which the electro-mechanical transducer according to the first embodiment is applied to the ultrasonic probe of the ultrasonic wave in which a low acoustic impedance material such as a water, a living body material and the like is used as a medium.

As illustrated in FIG. 4, the transmitter-side-ultrasonic probe according to the first embodiment encompasses vibrating plates (**15p**, **15x**); an electret layer **13s** having the first principal surface facing to the vibration surfaces of the vibrating plates (**15p**, **15x**); a back electrode **17s** in contact with the second principal surface of the electret layer **13s**; an electret-insulating layer **14x** joined to the first principal surface of the electret layer **13s**, and spacers **41s** inserted between the vibrating-plate-insulating layer **15x** and the electret-insulating layer **14x**, and the spacers **41s** control the interval of

“microgap” defined between the vibrating-plate-insulating layer 15x and the electret-insulating layer 14x. Similarly, the receiver-side-ultrasonic probe according to the first embodiment encompasses vibrating plates (15q, 15y), an electret layer 13r having the first principal surface facing to the vibration surfaces of the vibrating plates (15q, 15y), a back electrode 17r in contact with the second principal surface of the electret layer 13r, an electret-insulating layer 14y joined to the first principal surface of the electret layer 13r, and spacers 41r inserted between the vibrating-plate-insulating layer 15y and the electret-insulating layer 14y, and the spacers 41r control the interval of “microgap” defined between the vibrating-plate-insulating layer 15y and the electret-insulating layer 14y.

Each of the vibrating plates 15p, 15q are made of aluminum having a thickness of 12 micrometers, and the surfaces on the sides facing to the respective gaps of the vibrating plates 15p, 15q are finished to the mirror surfaces. Also, PZT is used as the electret layers 13s, 13r, and the surface potentials are set to -2 kV. On the electret layer 13s, the FEP resin layer having a thickness of 12 micrometers is laminated as each of the vibrating-plate-insulating layer 15x and the electret-insulating layer 14x, and on the electret layer 13r, the FEP resin layer having a thickness of 12 micrometers is laminated as the vibrating-plate-insulating layer 15y and the electret-insulating layer 14y, respectively. Between the vibrating-plate-insulating layer 15x and the electret-insulating layer 14x and between the vibrating-plate-insulating layer 15y and the electret-insulating layer 14y, the silicon particles each having a diameter of two micrometers are adhered at an average interval of ten micrometers as the spacers 41s, 41r. However, the silicon particles are aggregated in an in-plane direction, as illustrated in FIG. 3, and the average interval between the aggregated groups is 100 micrometers. Also, the tolerance of the thickness of each of the FEP resin layers as the vibrating-plate-insulating layers 15x, 15y and the electret-insulating layers 14x, 14y is $\pm 10\%$. For this reason, similar to the configuration illustrated in FIG. 3, the vibrating-plate-insulating layers 15x, 15y and the electret-insulating layers 14x, 14y contact locally through a part of the aggregated silicon particles, respectively, so as to form the corresponding microgaps between the vibrating-plate-insulating layers 15x, 15y and the electret-insulating layers 14x, 14y. At this time, in the inside of each of the microgaps, the electric field of about 70 MV/m is established from the electret layers 13s, 13r.

As illustrated in FIG. 4, a step voltage is supplied through a transmitting amplifier 102s to the transmitter-side-ultrasonic probe so as to generate an ultrasonic wave such that the generated ultrasonic wave can propagate a silicon block 7, and the ultrasonic wave propagated through a silicon block 7 is received by the receiver-side-ultrasonic probe, and then amplified and detected by a receiving amplifier 102r, and FIG. 5 represents a result, in which, as a transmitted signal, the step voltage is supplied to the transmitter-side-ultrasonic probe, and the ultrasonic wave propagated through the silicon block 7 is received by the receiver-side-ultrasonic probe, and then amplified and detected by the receiving amplifier 102r as a received signal.

On the contrary, FIG. 6 illustrates a structure of an ultrasonic probe according to a first comparison-example in which the silicon particle is not used as the spacer. As illustrated in FIG. 6, the transmitter-side-ultrasonic probe according to the first comparison-example encompasses a vibrating plates (15p, 15x); an electret layer 13s facing to the vibration surfaces of the vibrating plates (15p, 15x); a back electrode 17s in contact with the second principal surface of the electret layer 13s; and an electret-insulating layer 14x joined to the

first principal surface of the electret layer 13s. Then, the vibrating-plate-insulating layer 15x and the electret-insulating layer 14x are macroscopically in direct contact with each other. Similarly, in the receiver-side-ultrasonic probe according to the first comparison-example encompasses vibrating plates (15q, 15y); an electret layer 13r facing to the vibration surfaces of the vibrating plates (15q, 15y); an back electrode 17r in contact with the second principal surface of the electret layer 13r; and an electret-insulating layer 14y joined to the first principal surface of the electret layer 13r are contained. Then, the vibrating-plate-insulating layer 15y and the electret-insulating layer 14y are macroscopically in direct contact with each other. As the electret layers 13s, 13r, PZT of the same material and of the same shape as the electret layers 13s, 13r used in FIG. 4 is used.

FIG. 7 represents a result in which, as illustrated in FIG. 6, the step voltage is supplied through a transmitting amplifier 102s to a transmitter-side-ultrasonic probe, and the ultrasonic wave is generated, and the ultrasonic wave propagated through a silicon block 7 is received by the receiver-side-ultrasonic probe, and then amplified and detected by a receiving amplifier 102r. Even when the silicon particle is not used as the spacer, the tolerance of the thickness of each FEP resin layer as the vibrating-plate-insulating layers 15x, 15y and the electret-insulating layers 14x, 14y is $\pm 10\%$. Thus, as can be understood from FIG. 3, the microgap is microscopically established between the vibrating-plate-insulating layer 15x and the electret-insulating layer 14x and between the vibrating-plate-insulating layer 15y and the electret-insulating layer 14y.

FIG. 8 illustrates a structure of an ultrasonic probe (piezoelectric probe) according to a second comparison-example in which the vibrating-plate-insulating layer and the electret-insulating layer are not used, in addition to the fact that the silicon particle is not used as the spacer. As illustrated in FIG. 8, a transmitting piezoelectric probe (transmitter-side-ultrasonic probe) according to the second comparison-example encompasses a vibrating electrode 15p, an electret layer 13s facing to the vibration surface of the vibrating electrode 15p and a back electrode 17s in contact with the second principal surface of the electret layer 13s. Similarly, a receiving piezoelectric probe (receiver-side-ultrasonic probe) according to the second comparison-example encompasses a vibrating electrode 15q, an electret layer 13r facing to the vibration surface of the vibrating electrode 15q and a back electrode 17r in contact with the second principal surface of the electret layer 13r. As the electret layers 13s, 13r, PZT of the same material and of the same shape as the electret layers 13s, 13r used in FIG. 4 and FIG. 6 are used. FIG. 9 represents a result in which, as illustrated in FIG. 8, the step voltage is supplied through a transmitting amplifier 102s to the transmitter-side-ultrasonic probe (transmitter-side-ultrasonic probe), and the ultrasonic wave is generated, and the ultrasonic wave propagated through the silicon block 7 is received by the receiving piezoelectric probe (receiver-side-ultrasonic probe) and then amplified by a receiving amplifier 102r and detected.

In both of the results represented by FIGS. 5 and 7, the ultrasonic waves propagated through the silicon block 7 from the transmitter-side-ultrasonic probe and the ultrasonic wave after one round-trip through reflections in the silicon block 7 are received. Even when the silicon particle is not used, there is the tolerance of $\pm 10\%$ in each FEP resin layer as the vibrating-plate-insulating layer 15x and the electret-insulating layer 14x. Thus, the microgap ought to be formed between the respective layers of the vibrating electrode 15p, the vibrating-plate-insulating layer 15x, the electret-insulating layer 14x and the electret layer 13s. However, as can be understood

from the comparison between the results of FIGS. 5 and 7, since the silicon particles are used as the spacers 41s, 41r and then the microgaps are formed in the result represented by FIG. 5, the transmission/reception sensitivity of the ultrasonic wave is greatly increased in the result represented by FIG. 5. From the comparison between the results of FIGS. 5 and 7, the reduction in the number of the contact points of the microgaps and the reduction in the diameter of the contact portion can be understood to have great influence on the sensitivity.

Also, when the electret probe (ultrasonic probe) illustrated in FIG. 4 is compared with the piezoelectric probe in FIG. 8, it can be understood that, although there is not a great difference between their measured sensibilities, in the electret probe illustrated in FIG. 4, the received waveform has the waveform in which the leading edge is sharp such as the supplied step voltage waveform, and the resonance is rarely found.

Also, FIG. 10 represents results when sine wave signals (unit waves) are supplied respectively to the electret probe (ultrasonic probe) in FIG. 4 and the transmission/receptions are carried out respectively. FIG. 11 represents results when the piezoelectric probe in FIG. 8 is used and the transmission/receptions are similarly carried out respectively, by using the sine wave signals.

In the electret probe (ultrasonic probe) illustrated in FIG. 4, the waveforms close to the input signal are transmitted/received respectively in a wide frequency band, and their sensibilities are not greatly changed respectively. However, in the results of the piezoelectric probe illustrated in FIG. 8, only a signal waveform near the resonant frequency is transmitted/received, and as the frequencies of the input signals leave from the resonant frequency, the transmission/reception sensibilities are greatly decreased. In this way, by using the electret probe (ultrasonic probe) having the microgap, it is possible to obtain the ultrasonic probes having a high transmission/reception sensitivity in a wide band.

In the results represented by FIGS. 5 and 7 and FIGS. 9 to 11, the silicon block 7 is used as a propagation medium, because the acoustic impedance of the silicon block 7 is close to those of water and human body, even when water and human body are used as the propagation medium, the similar performance can be obtained. As one example of diagnostic approach using a medical ultrasonic probe, an approach of injecting a micro bubble into the living body and carrying out a contrast imaging of a blood flow is proposed. This approach is a method of receiving the ultrasonic wave that is generated by the resonance, breakdown or disappearance of the micro bubble when the ultrasonic wave is irradiated. However, since the sizes of the micro bubbles are not regular, there is dispersion in the frequencies of the ultrasonic waves generated by the micro bubbles. Since the piezoelectric probe of the resonance type can carry out the reception at only the particular frequency, the reception sensibilities of the ultrasonic waves generated by the micro bubbles are reduced. By the ultrasonic wave according to the first embodiment, because the ultrasonic waves of the various frequencies can be transmitted/received, and even if the sizes of the micro bubbles are irregular, the many ultrasonic waves can be received as compared with the piezoelectric probe, the contrast imaging effect becomes significant.

—Reason for $\frac{1}{10}$ of Gap Width—

Experimental results in which the influences of the ratios between the central line average roughness Ra of the vibrating electrodes 15b and the gap widths W_g on the charge holding characteristics of the electrets will be described here.

At first, as illustrated in FIG. 12, with corona discharge, negative charges were generated on a surface of a tetrafluoroethylene-perfluoroalkyl vinyl ether copolymer (PFA) film having a thickness of 12.5 micrometers, and the electret layer 13 was formed by the PFA film. At this time, the surface potential of the PFA film was -1 kV. Then, the electret layer 13 was placed on the back electrode 17 made of aluminum, and a PFA film 65 having a thickness of 12.5 micrometers, in which a slit having a width of one millimeter is cut, was laminated on the electret layer 13, and the vibrating electrode 15b made of aluminum having a thickness of 50 micrometers was further placed on the PFA film 65. At this time, the vibrating electrode 15b and the back electrode 17, which were arranged respectively on the top side and the bottom side, created a condenser, and inside the air gap formed by the slit having the width of one millimeter, the electric field was established by the electret layer 13, and the vibrating electrode 15b arranged on the top side was pulled and bent. After the vibrating electrode 15b was held in the pulled and bent state for 24 hours, the bending of the vibrating electrode 15b was measured by using a laser displacement meter.

FIG. 13 represents measured results. X-axis indicates a horizontal distance ($x=0$ at the left end of the slit), and a Y-axis indicates a vertical distance ($y=0$ at the left end of the slit). As illustrated in FIG. 13, the maximum bending of the vibrating electrode 15b was 1.23 micrometers. After that, when the vibrating electrode 15b was removed to measure the surface potential of the electret layer 13, the surface potential was increased to -750 V (the magnitude, or the absolute value of the surface potential was decreased). This was because, since the central line average roughness Ra of the vibrating electrode 15b (which corresponded to the maximum bending of the vibrating electrode 15b, in this experiment) was excessively large, which resulted in the electric field concentration, and consequently, the discharging caused the amount of polarization of the electret layer 13 to be decreased, thereby reducing the magnitude of the surface potential. Then, although the vibrating electrode 15b was again placed above the electret layer 13 and held for one week, the change in the surface potential that exceeded the above magnitude was not recognized. Thus, this indicated that the change in the surface potential caused by the electric field concentration was not generated under this condition. However, at this time, the central line average roughness Ra of the vibrating electrode 15b (which corresponded to the maximum bending of 1.23 micrometers of the vibrating electrode 15b in the experiment illustrated in FIG. 12) was determined to be about $\frac{1}{10}$ of the gap width (which is the height 12.5 micrometers of the slit) defined between the bottom surface of the vibrating electrode 15b and the top surface of the electret layer 13. From this experiment, it can be concluded that the central line average roughness Ra of the vibrating electrode 15b was required to be suppressed to be $\frac{1}{10}$ or less of the gap width defined between the bottom surface of the vibrating electrode 15b and the top surface of the electret layer 13.

Also, the experiment illustrated in FIG. 12 was carried out in the ambient of air gap. However, when the experiment is executed under the condition such that an insulating film and the like is laminated in the gap, attention should be paid to a possibility of the electric field concentration in the gap, when the dielectric constant of material laminated in the gap is high. In particular, the protrusions forming the microgap cause the dielectric constant to be changed in the surface direction (the vertical direction to the electric field) of the electret layer 13 and the vibrating electrode 15b. Thus, the electric field is likely to be concentrated at the protruded portion as compared with other portions in the microgap. In order to protect the

concentration of the electric field, the dielectric constant of the protrusion should be decreased. Specifically, the relative dielectric constant of the protrusion should be set to ten or less and desired to be set to three or less.

When the ferroelectric ceramic whose polarization is very large (0.1 C/m^2 or more) is used as the electret layer **13**, a rate at which the amount of polarization decreases is small, even if the discharging caused by the electric field concentration is similarly generated, as compared with the electret layer **13** implemented by polymers. Thus, when the ferroelectric ceramic of the single-crystal such as a lithium niobate single-crystal is used in the electret layer **13**, the central line average roughness R_a of the vibrating electrode **15b** can be set to $1/10$ or more of the gap width that is defined between the bottom surface of the vibrating electrode **15b** and the top surface of the electret layer **13**. However, on the other hand, when the poly-crystalline ceramic as the ferroelectric material is used in the electret layer **13**, because the insulating characteristics (volume resistance) of the ferroelectric material itself is inferior, a leakage current flowing inside the ferroelectric material causes the drop in the amount of polarization. For this reason, when the ferroelectric ceramic of the poly-crystal is used as the electret layer **13**, the central line average roughness R_a of the vibrating electrode **15b** is required to be suppressed to be $1/10$ or less of the gap width that is defined between the bottom surface of the vibrating electrode **15b** and the top surface of the electret layer **13**, similarly to the polymer electret layer **13**.

Also, in the experiment illustrated in FIG. **12**, although the average magnitude of the electric field of the air gap is known to be about 60 MV/m , if the electric field magnitude can be reduced, the discharging caused by the electric field concentration can be protected. However, on the other hand, when the electric field magnitude is reduced, the amplitude of the vibrating electrode **15b** is required to be made high, in order to keep the sensitivity as the microphone, and therefore, the bands of the frequency and the sound pressure will become narrow. Also, the reduction in the electric field magnitude leads to the drop in the transmission output. Because the feature of the electro-mechanical transducer according to the first embodiment of the present invention inheres in the achieved high electric field across the gap, ascribable to the employment of the microgap, the approach for reducing the electric field magnitude so as to protect discharge caused by the electric field concentration should be avoided. Hence, it is necessary to protect discharge caused by the electric field concentration by suppressing the central line average roughness R_a of the vibrating electrode **15b** to be $1/10$ or less of the gap width defined by the bottom surface of the vibrating electrode **15b** and the top surface of the electret layer **13**.

<Manufacturing Method of Ultrasonic Probe>

The manufacturing method of the electro-mechanical transducer (ultrasonic probe) according to the first embodiment of the present invention will be described below with reference to FIG. **14**. By the way, the manufacturing method of the electro-mechanical transducer (ultrasonic probe) described below is recited as one of the examples. Within the scope prescribed by Claims, including the modified examples, the electro-mechanical transducer can be naturally manufactured by using various manufacturing methods other than the example described here.

(a) At first, an Al film as the vibrating plate **15** is deposited on the PET film as the vibrating-electrode-insulating film **15a**, and the vibrating plate **15** is formed. A washer of the PET film is placed as a spacer ring **84** on the PET film on which the Al film as the vibrating plate **15** is deposited, as illustrated in FIG. **14(a)**. The thickness of the spacer ring **84** is set to be slightly thicker than that of the silicon particle serving as the

spacers **41**. The PET washer as the spacer ring **84** is provided such that at a state illustrated in FIG. **14(e)**, which will be described later, when the PET washer is assembled into the receptacle **81**, the electrostatic stress except the electrostatic force of the electret layer **13** is not applied to the microgap portion. However, when the thickness of the PET washer is set to be thicker than that of the silicon particles as the spacers **41** so as to support the vibrating-electrode-insulating film **15a**, because the pressure applied to the silicon particle by the electrostatic force of the electret layer **13** can be decreased, the contact rigidity of the microgap portion can be reduced. In this configuration, although the entire bending of the vibrating-electrode-insulating film **15a** supported by the PET washer is made large, as far as the vibrating-electrode-insulating film **15a** is in contact with the silicon particles as the spacers **41**, R_a determined by the silicon particles can be set to be $1/10$ or less of the gap width.

(b) Next, the silicon particles as the spacers **41** are colloidal diffused into a solvent **55** by a dispersant. Then, as illustrated in FIG. **14(b)**, the solvent **55** is dropped onto the PET film implementing the vibrating plate **15** and dried. Then, the silicon particles as the spacers **41** are coated on the PET film. By the way, differently from the method illustrated in FIG. **14(b)**, it is allowable to use a method such that preliminarily performing a surface processing on the PET film implementing the vibrating plate **15** so as to form the micro protrusions (spacers **41**) at the surface of the vibrating plate **15**, beforehand.

(c) Then, as illustrated in FIG. **14(c)**, the PET film as the electret-insulating layer **14e** is placed on the spacer ring **84** and the spacers **41**. The microgap is established between the vibrating-electrode-insulating film **15a** and the electret-insulating layer **14e**, and the entire thickness of the vibrating-electrode-insulating film **15a**, the spacers **41** and the electret-insulating layer **14e** becomes the macroscopic gap width W_g .

(d) Apart from the above flow of procedures (a) to (c), as illustrated in FIG. **14(d)**, the electret layer **13** having the back electrode **17** is prepared. The back electrode **17** and the electret layer **13** may be metallurgically joined or may be adhered by an adhesive agent and the like, or may be merely brought into contact by a mechanical pressure. For example, a copper electrode as the back electrode **17** is provided on a substrate, under which the amplifying circuit **19** is mounted, and the PET film as the electret layer **13** is placed on the back electrode **17**. Then, the PET film is electrified by corona discharge.

(e) Then, the electret layer **13** having the back electrode **17** is stacked on a structure encompassing the electret-insulating layer **14e**, which is arranged through the spacer ring **84** and the spacers **41** on the vibrating plate **15**, and then, the structure, on which the electret layer **13** is stacked, is assembled into a receptacle **81**, as illustrated in FIG. **14(e)**. By the way, the ferroelectric material can be used as the electret layer **13**, such that, for example, PZT in which the polarization directions are aligned, but is not electrified, may be assembled as the electret layer **13** into the receptacle **81**, in accordance with the above procedure, and after the assembling of the PZT is finished, and that the PZT is heated to the temperature close to Curie point and held for several seconds to several minutes, and then, when the PZT is cooled to a room temperature so that surface charges of the PZT can be removed so as to form the electret layer **13** by the PZT. When Curie point temperature of PZT is higher than a soldering reflow temperature, as the reflow process of the packaged structure (product) including the ultrasonic probe is carried out, the PZT is changed into the electret layer **13** by the reflow process.

According to the ultrasonic probe pertaining to the first embodiment of the present invention, since the aerial transmission/reception sensitivity is higher than that of the earlier ultrasonic probe, the precisions of the distance measurement and the like can be expected to be improved. Moreover, if a frequency modulation is used, the transmission/reception with higher precision can be further achieved. Specifically, a particular signal pattern is selected to be transmitted by changing the frequency at the time of the transmission. Then, when the transmitted signal pattern is extracted at receiving site, if the particular signal pattern is so selected that the pattern is not generated under noise environment, the received waveform buried in the noise can be identified even in the higher noise environment. This noise protection scheme is an approach peculiar to the ultrasonic probe of the present invention in which the transmission/reception is possible in the wide frequency band. If ultrasonic waves can be transmitted/received in the wider frequency band, because a signal waveform in which only the leading edge is sharp as illustrated in FIG. 5 can be transmitted/received, duplicated reflected waves can be easily discriminated even when a plurality of reflected waves are simultaneously received.

Second Embodiment

As illustrated in FIG. 15, an electro-mechanical transducer according to a second embodiment of the present invention is a hydrophone which encompasses a vibrating plate 15 that contains a vibrating electrode 15b made of conductor having a flat vibration surface; an electret layer 13 which is defined by the flat first principal surface facing to the vibration surface of the vibrating plate 15 and the second principal surface facing in parallel to the first principal surface and in which the polarization directions are aligned; a back electrode 17 in contact with the second principal surface of the electret layer 13; and amplifying means (19, 9) connected between the vibrating plate 15 and the back electrode 17. As described in the first embodiment, the back electrode 17 and the electret layer 13 may be metallurgically joined or may be adhered by adhesive agent and the like or may be merely brought into contact by the mechanical pressure. The vibrating plate 15 contains a vibrating electrode 15b and a vibrating-electrode-insulating film 15a on the bottom surface of the vibrating electrode 15b, as illustrated in FIG. 13. An electret-insulating layer 14e is arranged on the top surface of the electret layer 13. A plurality of spacers 41 implemented by particles of insulators, each having the particle diameter between ten nanometers and 100 micrometers are inserted between the vibrating-electrode-insulating film 15a and the electret-insulating layer 14e, and the spacers 41 control the interval of "microgap" defined between the vibrating-electrode-insulating film 15a and the electret-insulating layer 14e. As illustrated in FIG. 15, a holder 89 made of a cylindrical insulator is arranged under the circular electret layer 13 and supports the periphery of the electret layer 13. The vibrating plate 15, the electret layer 13, the back electrode 17, a part of the amplifying means (19, 9) and the holder 89 are accommodated in a conductive (metallic) receptacle 81 and implement the hydrophone.

Differently from the ultrasonic probe pertaining to the first embodiment, in the hydrophone according to the second embodiment, only the spacers 41 are arranged between the vibrating-electrode-insulating film 15a and the electret-insulating layer 14e, and the spacer ring 84 illustrated in FIG. 1 is not inserted. On the other hand, in the hydrophone according to the second embodiment, a silicon layer as a matching layer 16 is coated on the vibrating electrode 15b, as illustrated in

FIG. 16(b). The matching layer 16 has a role as a protecting layer of the vibrating electrode 15b, in addition to the function for increasing the matching characteristics of the acoustic impedance with the medium.

The amplifying means (19, 9) contains an amplifier (FET) 19 connected to the back electrode 17 and an additional circuit (illustration is omitted) connected to the amplifying circuit 19. However, the amplifying circuit 19 and the additional circuit are buried in a resin layer 22 at the bottom surface side of the back electrode 17. Moreover, a lower portion of the receptacle 81 is screwed into a screw cap 10. The vibrating electrode 15b, the vibrating-electrode-insulating film 15a, the spacers 41, the electret-insulating layer 14e and the electret layer 13 are pushed upward of the receptacle 81 by the screw cap 10, and with this pushing force, the hydrophone can endure the high water pressure. Because the other configurations are substantially similar to those of the ultrasonic probe pertaining to the first embodiment, duplicative explanations are omitted.

For example, in the structure illustrated in FIG. 15, when the surface potential of the electret layer 13 is assumed to be as -4.5 kV, the thickness of the Al film layer as the vibrating electrode 15b is assumed to be as 20 micrometers, each of the thicknesses of the vibrating-electrode-insulating film 15a and the PET layer as the electret-insulating layer 14e is assumed to be as ten micrometers, the silicon particles as the spacers 41 are assumed to be PTFE particles, each having a diameter of two micrometers, and the average interval between the particles is assumed to be as 60 micrometers, the electric field of the microgap becomes about 150 MV/m (the dielectric breakdown strength is 180 MV/m or more). The reception sensitivity of the hydrophone according to the second embodiment becomes -80 dB or more between 20 Hz and 1 MHz. Also, when the vibrating-electrode-insulating film 15a implemented by the PET layer and the electret-insulating layer 14e will be brought into contact with each other, because a hydrostatic pressure of 2.5 MPa or more (which corresponds to a water depth of 2500 meters) is required, and the hydrophone according to the second embodiment can be used until the water depth of 1000 meters, with a drop in the sensitivity of 6 dB or less.

Because the earlier piezoelectric probe hydrophone that can be used up to the water depth of 1000 meters, the maximum sensitivity of -174 dB, in accordance with the hydrophone pertaining to the second embodiment, it is possible to obtain a high sensitivity, which largely exceeds that of the earlier piezoelectric type hydrophone.

<Manufacturing Method of Hydrophone>

The manufacturing method of the electro-mechanical transducer (hydrophone) pertaining to the second embodiment of the present invention will be described below with reference to FIG. 16. By the way, the manufacturing method of the electro-mechanical transducer (hydrophone) which will be described below is recited as one of examples. Within the scope prescribed by Claims, including various modified examples, the electro-mechanical transducer can be naturally fabricated by using various manufacturing methods other than the method described below.

(a) At first, similarly to the manufacturing method of the ultrasonic probe pertaining to the first embodiment, an Al film as the vibrating plate 15 is deposited on a PET film as the vibrating-electrode-insulating film 15a so as to form a vibrating plate 15. On the PET film on which the Al film as the vibrating plate 15 is deposited, the solvent 55 in which silicon particles are colloiddally diffused is dropped, and dried so as to provide the silicon particles on the vibrating-electrode-insulating film 15a as the spacers 41. By the way, it is allowable to

use a method that preliminarily performs the surface process on the PET film as the vibrating-electrode-insulating film **15a** and then forms the micro protrusions (spacers **41**). Differently from the manufacturing method of the ultrasonic probe pertaining to the first embodiment illustrated in FIG. **14(a)**, the washer of the PET film as the spacer ring **84** is not used. Then, as illustrated in FIG. **16(a)**, the PET film as the electret-insulating layer **14e** is placed on the spacers **41**. The microgap is established between the vibrating-electrode-insulating film **15a** and the electret-insulating layer **14e**, and the entire thickness of the vibrating-electrode-insulating film **15a**, the spacers **41** and the electret-insulating layer **14e** becomes the macroscopic gap width W_g .

(b) On the other hand, as illustrated in FIG. **16(a)**, an electret layer **13** having a back electrode **17** is prepared. Similarly to the manufacturing method of the ultrasonic probe pertaining to the first embodiment, the back electrode **17** and the electret layer **13** may be metallurgically joined or may be adhered by adhesive agent and the like, or may be merely brought into contact by the mechanical pressure. For example, a copper electrode as the back electrode **17** is arranged in the substrate under which an amplifying circuit **19** is mounted, and the PET film as the electret layer **13** is placed on the back electrode **17**. Then, the PET film is electrified by corona discharge.

(c) Then, the electret layer **13** having the back electrode **17** is stacked on a structural-body unit encompassing the electret-insulating layer **14e**, which is arranged through the spacers **41** on the vibrating plate **15**, and then, the structural-body unit, on which the electret layer **13** is stacked, is assembled into a receptacle **81**, as illustrated in FIG. **16(b)**. When the structural-body unit and the electret layer **13** are assembled into the receptacle **81**, the bottom surfaces of the back electrode **17** and the electret layer **13** are buried in a resin layer **22**. Moreover, the vibrating electrode **15b**, the vibrating-electrode-insulating film **15a**, the spacers **41**, the electret-insulating layer **14e** and the electret layer **13** are pushed upward of the receptacle **81** by the screw cap **10**. Moreover, a silicon layer as the matching layer **16** is coated on the vibrating electrode **15b**. By the way, ferroelectric material can be used as the electret layer **13**, for example, PZT, in which the polarization directions are aligned, but the surface of which is not electrified, might be assembled as the electret layer **13** into the receptacle **81**, in accordance with the above procedure. After the assembling of the PZT is finished, the PZT is heated to the temperature close to Curie point and held for several seconds to several minutes. Then, when the PZT is cooled to the room temperature, the surface charges of the PZT are removed so as to form the electret layer **13**.

Third Embodiment

As illustrated in FIG. **17**, an electro-mechanical transducer according to a third embodiment of the present invention is an ultrasonic sensor which encompasses a vibrating plate **15** that contains a vibrating electrode **15b** made of conductor having a flat vibration surface; an electret layer **13** which is defined by the flat first principal surface facing to the vibration surface of the vibrating plate **15** and the second principal surface facing in parallel to the first principal surface and in which the polarization directions are aligned; a back electrode **17** in contact with the second principal surface of the electret layer **13**; and amplifying means (**19, 9**) connected between the vibrating plate **15** and the back electrode **17**. Similarly to the first and second embodiments, the back electrode **17** and the electret layer **13** may be metallurgically joined or may be adhered by adhesive agent and the like or may be merely

brought into contact by the mechanical pressure. Although the illustrations on a plan view and a bird's eye view are omitted, each of the vibrating plate **15**, the electret layer **13** and the back electrode **17** in the ultrasonic sensor illustrated in FIG. **17** can employ the shape of the circular disk having the radius, for example, between three nanometers and 40 nanometers. The vibrating plate **15** contains a vibrating electrode **15b** and a vibrating-electrode-insulating film **15a** at the bottom surface of the vibrating electrode **15b**, as illustrated in FIG. **17**. Similarly to the first and second embodiments, as necessary, a matching layer may be arranged on the top surface of the vibrating electrode **15b** so that the matching characteristics of the acoustic impedance with the medium can be increased. The vibrating plate **15** is vibrated by receiving the acoustic wave. The electret layer **13** is a charged layer from which electric fields diverge to the outside. For example, electrifying the polymer film through corona discharge or by heating the ferroelectric material and removing the surface charges can implement the electret layer **13**. The structural-body unit in which the electret-insulating layer **14e** is arranged on the top surface of the electret layer **13** is similar to the electro-mechanical transducer according to the first embodiment. However, a spacer layer **8** in which many holes each having a diameter of 0.05 to one millimeter are opened is inserted between the vibrating-electrode-insulating film **15a** and the electret-insulating layer **14e**, and the interval of "microgap" defined between the vibrating-electrode-insulating film **15a** and the electret-insulating layer **14e** is controlled. The holder **89** made of the cylindrical insulator is arranged under the circular electret layer **13** and supports the periphery of the electret layer **13**. The vibrating plate **15**, the electret layer **13**, the back electrode **17**, the part of the amplifying means (**19, 9**) and the holder **89** are accommodated in the conductive (metallic) receptacle **81** and implement the ultrasonic sensor. The amplifying means (**19, 9**) contains the amplifier (FET) **19** connected to the back electrode **17** and the additional circuit **9** connected to the amplifier (FET) **19**. The potential across the back electrode **17** and the vibrating plate **15** is amplified by the amplifier (FET) **19**. Consequently, the charges that are induced on the electret layer **13** in association with the displacement of the vibration surface of the vibrating plate **15** are measured. The other configurations are substantially similar to those of the electro-mechanical transducer according to the first and second embodiments. Thus, the duplicative explanations are omitted.

Because the electro-mechanical transducer (ultrasonic sensor) according to the third embodiment of the present invention has a configuration such that the spacer layer **8**, in which the many holes each having the diameter of 0.05 to one millimeter are opened, is inserted between the vibrating-electrode-insulating film **15a** and the electret-insulating layer **14e**, vibrations caused by the deformation of portions at the contact points in the microgap portion cannot be barely expected, and only the vibrations caused by the bending of the localized portions above the holes, which are opened by a punching work. Thus, the electric field magnitude cannot be made large, which is not suitable for the transmission. However, the sufficient sensitivity is obtained for only the reception. For example, under the above condition, when the surface potential of the electret layer **13** is 1 kV, the sensitivity becomes -45 dB.

<Manufacturing Method of Ultrasonic Sensor>

The manufacturing method of the electro-mechanical transducer (ultrasonic sensor) according to the third embodiment of the present invention will be described below with reference to FIG. **18**. By the way, the manufacturing method of the electro-mechanical transducer (ultrasonic sensor),

which will be described below, is recited as one of examples. Within the scope prescribed by Claims, including various modified examples, the electro-mechanical transducer (ultrasonic sensor) can be naturally fabricated by using various manufacturing methods other than the following description.

(a) At first, an Al film as the vibrating electrode **15b** is deposited on a PET film having a thickness of 40 micrometers, as the vibrating-electrode-insulating film **15a** so as to form a vibrating plate **15**. On the other hand, in another PET film with a thickness of ten micrometers, many holes, each having a diameter of 50 to 700 micrometers, are opened by punching process such as etching, pressing or laser process so as to form a spacer layer **8**. As illustrated in FIG. **18(b)**, the spacer layer **8** is stacked on the vibrating plate **15**, which encompasses the PET film and the Al film deposited on the PET film.

(b) On the other hand, as illustrated in FIG. **18(b)**, an electret layer **13** having a back electrode **17** is prepared. Similarly to the first and second embodiments, the back electrode **17** and the electret layer **13** may be metallurgically joined or may be adhered by adhesive agent and the like, or alternatively, may be merely brought into contact by the mechanical pressure. For example, a copper electrode as the back electrode **17** is arranged on a substrate under which the amplifying circuit **19** is mounted, and a PET film may be placed on the back electrode **17** as the electret layer **13**. Then, the PET film is electrified by corona discharge.

(c) Then, the electret layer **13** having the back electrode **17** is stacked on a structural-body unit encompassing the electret-insulating layer **14e**, which is arranged through the spacers layer **8** on the vibrating plate **15**, and then, the structural-body unit, on which the electret layer **13** is stacked, is assembled into a receptacle **81**, as illustrated in FIG. **18(c)**. By the way, ferroelectric material can be used as the electret layer **13**, for example, PZT, in which the polarization directions are aligned, but the surface of which is not electrified, might be assembled as the electret layer **13** into the receptacle **81**, in accordance with the above procedure. After the assembling of the PZT is finished, the PZT is heated to the temperature close to Curie point and held for several seconds to several minutes. Then, when the PZT is cooled to the room temperature, the surface charges of the PZT are removed so as to form the electret layer **13**. When Curie point temperature is higher than the soldering reflow temperature and then the reflow process of the packaged structure (product) including the ultrasonic sensor is carried out, PZT is changed into the electret layer **13** by the reflow process.

As mentioned above, because the manufacturing method of the electro-mechanical transducer (ultrasonic sensor) according to the third embodiment of the present invention is simple and easy, the manufacturing cost can be reduced.

Fourth Embodiment

As illustrated in FIG. **19**, an electro-mechanical transducer according to the fourth embodiment of the present invention is a MEMS microphone encompassing vibrating plate (**48, 47**) implemented by conductor having a flat vibration surface; an electret layer **13** which is defined by a flat first principal surface facing to the vibration surfaces of the vibrating plate (**48, 47**) and a second principal surface facing in parallel to the first principal surface and in which the polarization directions are aligned; a semiconductor integrated circuit **43** that contains a metal thin film layer serving as a back electrode in contact with the second principal surface of the electret layer **13** and an integrated electronic-circuit serving as an amplifying means connected to this metal thin film layer; and a

semiconductor substrate **42** in which the semiconductor integrated circuit **43** is merged at a surface.

The vibrating plate (**48, 47**) contain a vibrating electrode **48** and a vibrating-electrode-insulating film **47** at the bottom surface of the vibrating electrode **48**, as illustrated in FIG. **19**. The electret layer **13** is implemented by a silicon oxide film serving as an inter-layer insulating film and a passivation film that are disposed on the semiconductor integrated circuit **43**. With corona discharge, the silicon oxide film is electrified and changed into the electret layer **13**. Similarly to the first to third embodiments, the metal thin film layer serving as the back electrode that is provided inside the semiconductor integrated circuit **43** and the electret layer **13** may be metallurgically joined or may be adhered by adhesive agent and the like, or alternatively, may be merely brought into contact by the mechanical pressure. However, in view of the multilevel interconnect technique of the semiconductor integrated circuit, as for the metal thin film layer serving as the back electrode formed inside the semiconductor integrated circuit **43** and the electret layer **13**, the metallurgical-structure can be easily achieved. The PET film is used as the vibrating-electrode-insulating film **47**. On the surface of the vibrating-electrode-insulating film **47**, a polymer film that is superior in insulation characteristics such as a polyimide film and the like can be printed by ink jet. Consequently, protrusions **45** are formed. The protrusions **45** disposed on the surface of the vibrating-electrode-insulating film **47** control the interval of "microgap" defined between the vibrating-electrode-insulating film **47** and the electret layer **13**.

The macroscopic "gap width W_g " is defined between the vibrating electrode **48** and the electret layer **13**. The vibrating electrode **48** is pulled and bent by the electro-statistic force of the electret layer **13**. However, size of concave/convex structure on the surface of the gap side of the vibrating electrode **48** in the deformed state is designed such that the central line average roughness R_a is $1/10$ or less of the gap width.

For this reason, although the MEMS microphone according to the fourth embodiment can achieve a high sensitivity equal to that of the microphone described in the Patent Document 1, the manufacturing method of the MEMS microphone according to the fourth embodiment is simpler and more easy, and the MEMS microphone according to the fourth embodiment can endure the stronger sound pressure.

Fifth Embodiment

As illustrated in FIG. **20**, a film-shaped electro-mechanical converter according to a fifth embodiment of the present invention encompasses a vibrating electrode **15b**; an electret layer **13** which faces the vibrating electrode **15b** so as to provide an element-install cavity in between the vibrating electrode **15b** and the electret layer **13**; a back electrode **17** in contact with the bottom surface of the electret layer **13**; a plurality of gap-insulating layers **14a, 14b** and **14c**, which are inserted in the element-install cavity, dividing the inside of the element-install cavity in upper and lower directions, so that a plurality of microgaps each having an interval between ten nanometers and 40 micrometers can be laminated in the inside of the element-install cavity; and an amplifying circuit (semiconductor chip) **19** electrically connected between the vibrating electrode **15b** and the back electrode **17**. The vibrating plate **15** has the flat vibration surface under no load condition.

In the film-shaped electro-mechanical converter according to the fifth embodiment, the effective surface roughness of the respective surface, defining each of the plurality of microgaps, is $1/10$ or less of the gap width W_g of the element-install

cavity. In FIG. 20, the gap width W_g of the element-install cavity is defined in a configuration, which corresponds to a state in which the vibrating-electrode-insulating film **15a** and all of the plurality of gap-insulating layers **14a**, **14b**, **14c**, . . . are omitted like as the earlier electret microphone, and also the gap width W_g corresponds to a distance between the electret layer **13** and the vibrating electrode **15b**. Thus, in the film-shaped electro-mechanical converter according to the fifth embodiment, the gap width W_g of the element-install cavity is defined in the stacked structure implemented by the gap-insulating layer **14a** of the first level layer, the gap-insulating layer **14b** of the second level layer and the gap-insulating layer **14c** of the third level layer, which are disposed beneath the vibration surface of the vibrating plate **15**. The polymer film is a film defined by a flat first principal surface facing to the vibrating electrode **15b** through the element-install cavity and a second principal surface facing in parallel to the first principal surface, and the polarization directions are aligned in the polymer film.

Although the definition that will be recited below are similarly applied to even in the sixth to thirteenth embodiments of the present invention, “effective surface roughness Ra_{eff} of the surface establishing microgap” in the film-shaped electro-mechanical converter according to the fifth embodiment mean as follows:

(a) the central line average roughness Ra of the convex portions provided at either one of the films between the vibrating-electrode-insulating film **15a** and the gap-insulating layer **14c** of the third level layer, or alternatively, the central line average roughness Ra when the particles inserted between the vibrating-electrode-insulating film **15a** and the gap-insulating layer **14c** of the third level layer are considered to implement the convex portions (see FIG. 2) (the central line average roughness Ra of the convex portions provided at either one of the films between the vibrating electrode **15b** and the gap-insulating layer **14c** of the third level layer when the vibrating-electrode-insulating film **15a** is omitted, or alternatively, the central line average roughness Ra when the particles inserted between the vibrating electrode **15b** and the gap-insulating layer **14c** of the third level layer are considered to implement the convex portions);

(b) the central line average roughness Ra of the convex portions provided at either one of the films between the gap-insulating layer **14c** of the third level layer and the gap-insulating layer **14b** of the second level layer, or alternatively, the central line average roughness Ra when the particles inserted between the gap-insulating layer **14c** of the third level layer and the gap-insulating layer **14b** of the second level layer are considered to implement the convex portions;

(c) the central line average roughness Ra of the convex portions provided at either one of the films between the gap-insulating layer **14b** of the second level layer and the gap-insulating layer **14a** of the first level layer, or alternatively, the central line average roughness Ra when the particles inserted between the gap-insulating layer **14b** of the second level layer and the gap-insulating layer **14a** of the first level layer are considered to implement the convex portions; and

(d) the central line average roughness Ra of the convex portions provided at either one of the films between the gap-insulating layer **14a** of the first level layer and the electret-insulating film, or alternatively, the central line average roughness Ra when the particles inserted between the gap-insulating layer **14a** of the first level layer and the electret-insulating film are considered to implement the convex portions (the central line average roughness Ra of the convex portions provided at either one of the films between the gap-insulating layer **14a** of the first level layer and the polymer

film when the electret-insulating film is omitted, or alternatively, the central line average roughness Ra when the particles inserted between the gap-insulating layer **14a** of the first level layer and the polymer film are considered to implement the convex portions).

Each thickness of the vibrating plate **15**, the gap-insulating layer **14a** of the first level layer, the gap-insulating layer **14b** of the second level layer and the gap-insulating layer **14c** of the third level layer is elected to be about 0.1 micrometer to 100 micrometers, preferably about one micrometer to 40 micrometers, more preferably about one micrometer to 12 micrometers.

The thickness of the polymer film is elected to be about one micrometer to 50 micrometers, in the case of the electret manufactured by corona discharge, preferably one micrometer to 25 micrometers, or more preferably about five micrometers to 25 micrometers. Also, in the case of the electret of the ferroelectric material, its thickness is set to one micrometer to 10 millimeters, preferably five micrometers to two millimeters, or more preferably about 50 to 500 micrometers. However, when the flexibility is expected, the thickness is preferred to be 60 micrometers or less.

As illustrated in FIG. 21, first spacers **41a** implemented by the particles of insulators each having a diameter between ten nanometers and 40 micrometers are inserted between the gap-insulating layer **14a** of the first level layer and the polymer film, and second spacers **41b** implemented by the particles of insulators each having a diameter between ten nanometers and 40 micrometers are inserted between the gap-insulating layer **14a** of the first level layer and the gap-insulating layer **14b** of the second level layer, and third spacers **41c** implemented by the particles of insulators each having a diameter between ten nanometers and 40 micrometers are inserted between the gap-insulating layer **14b** of the second level layer and the gap-insulating layer **14c** of the third level layer, and fourth spacers **41d** implemented by the particles of insulators each having a diameter between ten nanometers and 40 micrometers are inserted between the vibrating electrode **15b** and the gap-insulating layer **14c** of the third level layer, and the interval of the gap defined between the vibrating electrode **15b** and the polymer film is controlled. In this way, the plurality of gap-insulating layers **14a**, **14b**, **14c**, . . . are laminated and inserted, through the spacers **41a**, **41b**, **41c**, **41d**, . . . implemented by the particles of insulators each having the diameter between ten nanometers and 40 micrometers, between the vibrating-electrode-insulating film **15a** and the polymer film. Consequently, between the vibrating-electrode-insulating film **15a** and the gap-insulating layer **14c** of the third level layer, between the gap-insulating layer **14c** of the third level layer and the gap-insulating layer **14b** of the second level layer, between the gap-insulating layer **14b** of the second level layer and the gap-insulating layer **14a** of the first level layer and between the gap-insulating layer **14a** of the first level layer and the polymer film, “microgaps” that are the respective microscopic air gaps are defined, thereby controlling the respective intervals. The back electrode **17** and the polymer film may be metallurgically joined or may be adhered by adhesive agent and the like, or alternatively, may be merely brought into contact by the mechanical pressure. When the particle diameter of the particle serving as each of the spacers **41a**, **41b**, **41c**, **41d**, . . . is set to 100 micrometers or less, the effective surface roughness Ra_{eff} of the surfaces establishing each of the microgaps can be set to $1/10$ or less of the gap width of the element-install cavity that is provided so as to accommodate the microgaps between the bottom surface of the vibrating electrode **15b** and the top surface of the polymer film (the effective surface roughness Ra_{eff} includes

the bending under a loaded condition). However, in order to achieve the film-shaped electro-mechanical converter that is flexible and has a high degree of freedom in geometrical deformations, the particle diameter of the particle of each of the spacers **41a**, **41b**, **41c**, **41d**, . . . is set to ten nanometers to ten micrometers, which is preferable because the entire thickness becomes further thin. Moreover, in a range between ten nanometers and five micrometers, naturally, the particle diameter is desirable to be more and more close to ten nanometers. Although the representations on a plan view and a bird's eye view are omitted, the planer geometries of the vibrating plate **15**, the plurality of gap-insulating layers **14a**, **14b**, **14c**, . . . , the polymer film and the back electrode **17** in the film-shaped electro-mechanical converter illustrated in FIG. **20** can employ any shapes. For example, each of the plurality of gap-insulating layers **14a**, **14b**, **14c**, . . . and the polymer film can have a shape of a circular disk having a radius between three millimeters and 40 millimeters. When each of the plurality of gap-insulating layers **14a**, **14b**, **14c**, . . . and the polymer film is assumed to have a shape of a circular disk, each of the vibrating plate **15** and the back electrode **17** may have any planer geometry, such as an ellipse, barrel vault-shape or the like, in which an extension tongue is attached to the semi-circular portion with a radius between three millimeters and 40 millimeters, or alternatively, may have a circular shape that has a diameter larger than the diameters of each of the plurality of gap-insulating layers **14a**, **14b**, **14c**, . . . and the polymer film. On the other hand, when the plurality of gap-insulating layers **14a**, **14b**, **14c**, . . . and the polymer film are made into a rectangular shape, each of the vibrating plate **15** and the back electrode **17** can employ the various planer shapes such as a rectangular planer shape in which extension wings are joined to enlarge the area of the rectangular shape of the dimensions between three millimeters and 40 millimeters and the like. The vibrating plate **15** contains the vibrating electrode **15b** made of conductor and the vibrating-electrode-insulating film **15a** disposed at the bottom surface of the vibrating electrode **15b**, as illustrated in FIG. **20**. The thickness of each of the vibrating electrode **15b** and the back electrode **17** may be set to ten nanometers to 100 micrometers, preferably ten nanometers to 20 micrometers, or more preferably about 0.1 micrometer to one micrometer.

Furthermore, a vibrating-plate-protection film **16** implemented by an insulating film such as polyvinyl chloride (PVC) film and the like is formed on the top surface of the vibrating plate **15**, and the vibrating-plate-protection film **16** serves as the matching layer for increasing the matching characteristics of the acoustic impedance with the medium. Thus, the thickness of the vibrating-plate-protection film **16** may be changed in accordance with the requirement of the matching characteristics, within a range between about 10 and 100 micrometers.

As illustrated in FIG. **21**, in a configuration such that the plurality of gap-insulating layers **14a**, **14b**, **14c**, . . . are laminated, if the number of the microgap layers is increased, not only the damping characteristics but also the transmission/reception sensitivity will be improved. The improvement is ascribable to the fact that the amplitude of the vibrating electrode **15b** is the summation of the deformations in all of the microgap layers. Thus, unless the acoustic wave (ultrasonic wave) propagated through the gap portion is perfectly attenuated, as the number of the microgap layers increases more, the transmission/reception sensitivity will improve more. In a structure such that the plurality of gap-insulating layers **14a**, **14b**, **14c**, . . . are laminated, because the plurality of gap-insulating layers **14a**, **14b**, **14c**, . . . can cover the increase of the deformation level, a film of a high elastic modulus such as

fluorine resin film and the like can be used in each of the plurality of gap-insulating layers **14a**, **14b**, **14c**, As the fluorine resin, the tetrafluoroethylene-perfluoroalkyl vinyl ether copolymer (PFA) is typical. In addition to the fluorine resin, it is possible to use PET resin (3 GPa), polyphenylene-sulfide (PPS) resin (4 GPa), polyimide resin (3 to 7 GPa) and the like. However, attention should be paid to a fact that in order to increase the lamination number of the plurality of gap-insulating layers **14a**, **14b**, **14c**, . . . , the increase of the width of the entire gap will lead to the drop in the electric field strength in the gap.

If the film-shaped electro-mechanical converter is applied to a transmitter, the amplifying circuit **19** amplifies an input electric signal and the amplified electric signal is provided between the vibrating electrode **15b** and the back electrode **17**. On the other hand, if the film-shaped electro-mechanical converter is applied to a receiver, the amplifying circuit **19** amplifies the signal between the vibrating electrode **15b** and the back electrode **17** so as to measure the charges induced in association with the displacement of the vibrating electrode **15b**. In the film-shaped electro-mechanical converter for the transmitter, the vibrating plate **15** is vibrated by supplying the electric signal between the vibrating electrode **15b** and the back electrode **17** through the amplifying circuit **19**. On the other hand, in the film-shaped electro-mechanical converter for receiver, the vibrating plate **15** is vibrated by the reception of the acoustic wave from the outside.

The polymer film is the charged layer from which electric fields diverge to the outside. For example, the polymer film is electrified by corona discharge, and the ferroelectric material is heated to remove the surface charges so as to implement the polymer film. Although the illustration is omitted, the electret-insulating film may be laminated on the top surface of the polymer film, and the first spacers **41a** may be provided on the electret-insulating film. As illustrated in FIG. **20**, the plurality of gap-insulating layers **14a**, **14b**, **14c**, . . . and the polymer film are accommodated in the inside of a box-shaped inner insulation container (**12b**, **12d**), and the vibrating plate **15** serves as a cover of the inner insulation container (**12b**, **12d**), and the back electrode **17** serves as the bottom plate of the inner insulation container (**12b**, **12d**). Moreover, the structure in which the plurality of gap-insulating layers **14a**, **14b**, **14c**, . . . and the polymer film are accommodated in the inside of the inner insulation container (**12b**, **12d**) is further accommodated into an outer insulation container (**12a**, **12b** and **12c**) in which the spacer film **12a** made of an insulation material serves as the bottom plate, together with the amplifying circuit **19**. The vibrating plate serves as the cover of the outer insulation container (**12a**, **12b** and **12c**). A conductive (metallic) shielding-conductor film **11b** is provided at the bottom of the outer insulation container (**12a**, **12b** and **12c**), and a shielding-conductor-protection film **11a** is provided under the bottom of the shielding-conductor film **11b**. The shielding-conductor-protection film **11a** and the shielding-conductor film **11b** implement a shield plate **11**. Each of the spacer film **12a** and the shielding-conductor-protection film **11a** can be elected to be a value between about five micrometers and 150 micrometers, or preferably a value between about 50 and 100 micrometers.

For example, when the polymer film, the gap-insulating layers **14a**, **14b**, **14c**, . . . and the vibrating-electrode-insulating film **15a** are made of the PFA films, each of their thicknesses can be set to about ten micrometers. When the vibrating electrode **15b** and the back electrode **17** are made of the Al films, each of their thicknesses can be set to about ten micrometers. Also, when the vibrating-plate-protection film **16** is made of the PVC film, its thickness can be about 50

micrometers, and when the spacer film **12a** and the shielding-conductor-protection film **11a** are made of the PVC films, the thickness of each of the spacer film **12a** and the shielding-conductor-protection film **11a** can be set to about 100 micrometers. In FIG. **20**, the thicknesses of side-wall films **12b**, **12d** that serve as the side-plate blocks of the box-shaped insulation container (**12a**, **12b**, **12d** and **12e**) may be designed by considering the thicknesses of the polymer films, the number of the gap-insulating layers **14a**, **14b**, **14c**, . . . and the respective thicknesses of the gap-insulating layers **14a**, **14b**, **14c**, However, in order to make the insulation container (**12a**, **12b**, **12d** and **12e**) flexible, the thickness of about 100 micrometers is preferable.

Under no load condition, the first principal surface of the polymer film faces in parallel to the vibration surface of the vibrating plate **15**. Here, the amplifying means encompasses an amplifying circuit **19** in which the amplifier (FET) connected to the back electrode **17** is integrated, and an additional circuit (illustration is omitted) connected to the amplifying circuit **19**. FIG. **20** shows the film-shaped electro-mechanical converter for receiver. However, in the film-shaped electro-mechanical converter for receiver, the additional circuit encompasses a direct current power supply E whose one terminal, is grounded; a buffer resistor R connected between the direct current power supply E and the amplifying circuit **19**; and a coupling capacitor C in which one electrode is connected to a connection node between the buffer resistor R and the amplifying circuit **19**, and the other electrode serves as an output terminal. External circuitry (illustration is omitted) is connected to the output terminal of the coupling capacitor C serving as the output terminal of the amplifying circuit **19**, and the external circuitry carries out a signal process necessary for a communication unit and a recording/storage unit that are connected to a microphone. In the amplifying circuit **19** in the film-shaped electro-mechanical converter according to the fifth embodiment, the potential across the back electrode **17** and the vibrating plate **15** is amplified by the amplifying circuit **19**, and the charges induced onto the polymer film in association with the displacement of the vibration surface of the vibrating plate **15** is measured. On the other hand, in the film-shaped electromechanical converter for transmitter, the additional circuit encompasses a direct current power supply E whose one terminal is grounded; a buffer resistor R connected between the direct current power supply E and the amplifying circuit **19**; and a coupling capacitor C in which one electrode is connected to the connection node between the buffer resistor R and the amplifying circuit **19**, and the other electrode serves as an input terminal. External circuitry (illustration is omitted) is connected to the input terminal of the coupling capacitor C serving as the input terminal of the amplifying circuit **19**, and an input signal is supplied from the external circuitry, and the input signal amplified by the amplifying circuit **19** is applied across the back electrode **17** and the vibrating plate **15**.

The macroscopic "gap width W_g of element-install cavity" is defined between the vibrating electrode **15b** and the polymer film. The W_g lies in a range between 0.1 micrometer and 1000 micrometers. The microgap is defined for each of the microscopic air gaps established between the vibrating-electrode-insulating film **15a** and the gap-insulating layer **14c** of the third level layer (between the vibrating electrode **15b** and the gap-insulating layer **14c** of the third level layer when the vibrating-electrode-insulating film **15a** is omitted), between the gap-insulating layer **14c** of the third level layer and the gap-insulating layer **14b** of the second level layer, between the gap-insulating layer **14b** of the second level layer and the

gap-insulating layer **14a** of the first level layer, and between the gap-insulating layer **14a** of the first level layer and the electret-insulating film (the gap-insulating layer **14a** of the first level layer and the polymer film when the electret-insulating film is omitted) is the gap, in each of which the gap width is set to be between ten nanometers and 40 micrometers and the dielectric breakdown strength of air in each of the gaps is achieved to be between 5 and 200 MV/m, the value of which is improved as compared with the macroscopic gap. For the gap width W_g of the macroscopic element-install cavity, the dielectric breakdown strength of air is about 3 MV/m. However, when the insulating gas such as the fluorine based gas and the like other than air is filled in the gap width W_g of the macroscopic element-install cavity, or when the macroscopic element-install cavity is evacuated to establish vacuum, the dielectric breakdown strength in the macroscopic element-install cavity can be further improved.

Because the vibrating electrode **15b** is pulled and deformed by the electrostatic force between the polymer film and the vibrating electrode **15b**, the dielectric breakdown strength of the microgap decreases. In order to obtain a high dielectric breakdown strength as mentioned above, the effective surface roughness Ra_{eff} of a plane defining the microgap must be $1/10$ or less of the gap width of the element-install cavity, as described by using FIG. **12** and FIG. **13**.

Any material may be used for the vibrating plate **15**, as far as the bending of the vibrating-electrode-insulating film **15a** or vibrating electrode **15b** can be made to be $1/10$ or less of the gap width W_g of the element-install cavity, the vibrating electrode **15b** can be made to be superior in electrical conductivity, and the vibrating-electrode-insulating film **15a** can be made to be superior in electrical insulation. Although the vibrating plate **15** is required to be high in rigidity, the light weight is preferable in order to be able to follow the high frequency. For this reason, the material having the high value of the specific rigidity ((elastic modulus)/density) is preferred to be used for one of the vibrating electrode **15b** of the vibrating plate **15**, the vibrating-electrode-insulating film **15a** at the bottom surface of the vibrating electrode **15b**, and the matching layer (whose illustration is omitted in FIG. **20**) on the top surface of the vibrating electrode **15b**. For this reason, as for the vibrating plate **15**, aluminum (Al) and its alloy, or magnesium (Mg) and its alloy can be used as the vibrating electrode **15b**, and a structure in which the FEP layer is laminated as the vibrating-electrode-insulating film **15a** can be employed. Or, PET resin, polyethylene naphthalate (PEN) resin, epoxy resin, phenol resin and the like can be used as the vibrating-electrode-insulating film **15a**, and aluminum may be deposited on the vibrating-electrode-insulating film **15a** so as to implement the vibrating electrode **15b**. Or, alumina, silicon nitride, silicon carbide ceramics and the like can be used as the vibrating-electrode-insulating film **15a**, and on the vibrating-electrode-insulating film **15a**, aluminum may be deposited or silver may be burned so as to implement the vibrating electrode **15b**. In addition, a silicon substrate provided with a FEP resin layer or a silica layer, and the like, which is known to be used in the insulating layer of the earlier electret microphone, can be used for the vibrating-electrode-insulating film **15a**. However, in this case, the thickness is required to be increased such that the bending is $1/10$ or less of the gap width of the element-install cavity. Thus, the present scheme largely differs from the designing scheme of the earlier electret microphone. Also, the other resins that are superior in insulation (silicon based resin, fluorine based resin, polyethylene based resin, polyester, polypropylene, polycarbonate, polystyrene, urethane, ABS, flexible vinyl chloride and the like) may be used as the vibrating-electrode-

insulating film **15a**, and the vibrating electrode **15b** may be attached on the vibrating-electrode-insulating film **15a**, by adhesion, deposition or burning, so as to implement the vibrating plate **15**. In this scheme, the thickness of the vibrating electrode **15b** or vibrating-electrode-insulating film **15a** shall be increased to ensure the rigidity necessary for the vibrating plate **15**.

The material superior in electric insulation characteristics shall be used for the spacers **41a**, **41b**, **41c**, **41d**, Specifically, the ceramics such as silica, alumina, silicon nitride, silicon carbide and the like, the resin such as silicon based resin, fluorine based resin, polyethylene resin (including PET and the like), polyester, polypropylene, polycarbonate, polystyrene, urethane, ABS, flexible vinyl chloride and the like can be used. Also, the material whose elastic modulus is 2 GPa or less can be used for the spacers **41a**, **41b**, **41c**, **41d**, However, when there is the vibrating-electrode-insulating film **15a** on the side of the vibrating plate **15** and also the elastic modulus of the vibrating-electrode-insulating film **15a** is 2 GPa or less, there is no limit on each of elastic modulus of the spacers **41a**, **41b**, **41c**, **41d**, As the material having the superior electric insulation characteristics and the elastic modulus of 2 GPa or less, specifically, there are silicon based resin, the fluorine based resin, the polyethylene based resin, and the resins such as polyester, polypropylene, polycarbonate, polystyrene, urethane, ABS, flexible vinyl chloride and the like.

As for the spacers **41a**, **41b**, **41c**, **41d**, . . . , in addition to the particles whose particle diameter is between ten nanometers and 100 micrometers as illustrated in FIG. **21**, the spacers **41** as the micro protrusions having a height between ten nanometers and 40 micrometers may be provided on the top surface of the gap-insulating layer **14c** of the third level layer, as illustrated in FIG. **2**. The spacers **41** can be provided at the top surface of the gap-insulating layer **14c** of the third level layer, by means of tri pulse laser irradiation, lithography, etching, press and the like. Or, when the bottom surface of the vibrating-electrode-insulating film **15a** or the vibrating-electrode-insulating film **15a** is omitted, the micro protrusions having a height between ten nanometers and 40 micrometers may be formed at the bottom surface of the vibrating electrode **15b**. Similarly, instead of the spacers **41d** implemented by the particles of the insulator having a particle diameter between ten nanometers and 40 micrometers, the micro protrusions having a height between ten nanometers and 40 micrometers may be arranged at the bottom surface of the gap-insulating layer **14c** of the third level layer. Moreover, instead of the spacers **41b**, **41c**, each of which are implemented by the particles of the insulator having a particle diameter between ten nanometers and 40 micrometers, the micro protrusions having a height between ten nanometers and 40 micrometers may be provided to at least one of the bottom surface and the top surface of the gap-insulating layer **14b** of the second level layer, and instead of the spacers **41a**, **41b**, each of which are implemented by the particles of the insulator having a particle diameter between ten nanometers and 40 micrometers, the micro protrusions having a height between ten nanometers and 40 micrometers may be provided to at least one of the bottom surface and the top surface of the gap-insulating layer **14a** of the first level layer. Moreover, when the electret-insulating film is laminated on the polymer film and when the top surface of the electret-insulating film and the electret-insulating film are omitted, the micro protrusions having a height between ten nanometers and 40 micrometers may be provided at the top surface of the polymer film. In order to achieve the film-shaped electro-mechanical converter that is flexible and has a high degree of freedom in geometrical

deformations, the micro protrusions shall be set to a height between ten nanometers and ten micrometers so that the entire thickness can be made thinner. More preferably, the height, which is closer and closed to ten nanometers, in the range between ten nanometers and five micrometers, is preferable.

Each of the particle and the protrusion serves as the supporting member between the vibrating-electrode-insulating film **15a** and the gap-insulating layer **14c** of the third level layer (between the vibrating electrode **15b** and the gap-insulating layer **14c** of the third level layer when the vibrating-electrode-insulating film **15a** is omitted), between the gap-insulating layer **14c** of the third level layer and the gap-insulating layer **14b** of the second level layer, between the gap-insulating layer **14b** of the second level layer and gap-insulating layer **14a** of the first level layer, and between the gap-insulating layer **14a** of the first level layer and the electret-insulating film (the gap-insulating layer **14a** of the first level layer and the polymer film when the electret-insulating film is omitted). Consequently, the microgaps are formed. As far as the microgaps can be formed, the shapes of the spacers **41a**, **41b**, **41c**, **41d**, . . . may be arbitrary. However, the curvature of the contact points of the protrusions is desired to be large. Also, when the layer having a surface roughness whose maximum height (R_{max}) is between ten nanometers and 100 micrometers is stacked as illustrated in FIG. **3**, the microgap can be formed without the spacers **41a**, **41b**, **41c**, **41d**,

As mentioned above, the vibrating-electrode-insulating film **15a**, the gap-insulating layer **14a** of the first level layer, the gap-insulating layer **14b** of the second level layer, the gap-insulating layer **14c** of the third level layer and the electret-insulating film, the illustration of the electret-insulating film is omitted, are the layers of insulators, at the surface of which protrusions between ten nanometers and 100 micrometers are formed, or alternatively, on the surface of which particles whose particle diameters are between ten nanometers and 100 micrometers are adhered. Although FIGS. **20** and **21** exemplify the case in which the three insulating films of the gap-insulating layer **14a** of the first level layer, the gap-insulating layer **14b** of the second level layer and the gap-insulating layer **14c** of the third level layer are laminated, as necessary, the insulating layers can be further laminated, so as to increase the number of the microgap layers. Or, only on the surface of a part of the insulating layers, the protrusions may be formed or the particles may be adhered, and the remainders may be tightly adhered or dried and brought into contact, thereby enabling the microgap to be formed through the surface roughness. As far as the gap width is limited to be 100 micrometers or less, as the lamination number of the insulating films increases, the acoustic damping characteristics improves. Also, as the insulating layer becomes thicker, the gap width becomes larger, and the large gap width can protect the drop in the dielectric breakdown strength of the microgap, which is caused by the bending of the vibrating electrode **15b**. However, because the increase in the gap width leads to the drop in the electric field strength in the gap, the optimal number of the laminations is determined on the basis of the thickness of the insulating layer, the structure of the microgap and the like.

The polymer film must have the surface potential that enables the electric field between 5 and 200 MV/m to be generated in the gap. As the typical example of the polymer film, it is possible to use an insulating layer electrified by corona discharge, or a ferroelectric layer electrified by heating, and the like, which is described in the electro-mechanical transducer according to the first embodiment of the present invention. The thickness of the polymer film can be selected

to be, for example, about 10 and 50 micrometers in the case of the poly-tetrafluoroethylene (PTFE) film electrified by corona discharge, and about 0.5 millimeter to two millimeters in the case of using PZT as ferroelectric material. Then, the thicknesses of the back electrode **17** and the vibrating plate **15** can be selected to, for example, about one micrometer to 100 micrometers in the case of an Al deposited PET film. However, the specific thicknesses and radiuses of the vibrating plate **15**, the polymer film and the back electrode **17** may be determined on the basis of design schemes, requested performances and detailed requested particulars.

The amplifying circuit **19** is installed (mounted) on a circuit board **18**, in the vicinity of the left end of the back electrode **17**. A through hole (via) is made in the circuit board **18**, and through the through hole (via), the amplifying circuit **19** is electrically connected to the back electrode **17**, through a solder that is fused and connected to the vicinity of the left end of the back electrode **17**. Although the illustration is omitted, the ground wiring from the amplifying circuit **19** is connected to the shielding-conductor film **11b** of the shield plate **11** through solder.

Penetration holes (illustration is omitted) that penetrate through the back electrode **17**, the plurality of gap-insulating layers **14a**, **14b**, **14c**, . . . and the polymer film are made in the back electrode **17**, the plurality of gap-insulating layers **14a**, **14b**, **14c**, . . . and the polymer film. However, the penetration holes are sealed by using the solders so that (as necessary) the gas having high insulation characteristics (the insulating gas) can be sealed in the gap space between the polymer film and the vibrating plate **15**. As the insulating gas, it is possible to employ nitrogen, sulfur hexafluoride and the like. In addition to the insulating gas, even if the insulating fluid such as silicon oil and the like can be filled in the gap space implemented by the plurality of gap-insulating layers **14a**, **14b**, **14c**, . . . between the polymer film and the vibrating plate **15** so that the dielectric breakdown strength can be increased, which makes the generation of the discharge difficult. As a result, the amount of charges generated on the surface of the polymer film by discharge, can be reduced, thereby improving the sensitivity. Instead of the method of filling the insulating gas or insulating fluid, the gap space between the polymer film and the vibrating plate **15** is evacuated to establish vacuum, which can improve the sensitivity.

By the way, each of the vibrating plate **15**, the polymer film and the back electrode **17** is not required to have a shape of the circular disk, and various geometrical shapes such as an ellipse, a rectangle or the like are allowable, but naturally, the other constituent members such as the shield plate **11** and the like shall be designed to be fitted to the geometric shapes of the vibrating plate **15**, the polymer film and the back electrode **17**.

—Dielectric Breakdown Strength of Air in Micro Gap—

When a potential difference is applied across two electrodes having air gap, it is known that the dielectric breakdown strength of air is increased under atmospheric pressure, as the inter-electrode distance is decreased and the maximum value is established when the inter-electrode distance lies between about one micrometer and two micrometers. However, as the curvature of the protrusion at the surface of the electrode becomes higher, the electric field is more concentrated at the protruded portion, and the dielectric breakdown strength decreases further. Thus, when size of concave/convex structure at the electrode surface is represented by the central line average roughness Ra, Ra must be $\frac{1}{10}$ or less of the gap width, and Ra is desired to be $\frac{1}{100}$ or less.

In any of the earlier electret microphones, the vibrating electrode is largely deformed by the electrostatic force

between the electret layer, and the central line average roughness Ra of the surface of the vibrating electrode indicates the value that includes the deformation caused by the bending of the vibrating electrode. Thus, the central line average roughness Ra of the vibrating electrode of the earlier electret microphone exceeds $\frac{1}{10}$ of the gap width W_g of the element-install cavity (in FIG. 20, as mentioned above, the earlier electret microphone corresponds to a case in which all of the vibrating-electrode-insulating film **15a** and the plurality of gap-insulating layers **14a**, **14b**, **14c**, . . . are omitted, and the gap width W_g is the distance between the polymer film and the vibrating electrode **15b**).

In the film-shaped electro-mechanical converter according to the fifth embodiment, the width of each of the microgaps between the vibrating-electrode-insulating film **15a** and the gap-insulating layer **14c** of the third level layer (between the vibrating electrode **15b** and the gap-insulating layer **14c** of the third level layer when the vibrating-electrode-insulating film **15a** is omitted), between the gap-insulating layer **14c** of the third level layer and the gap-insulating layer **14b** of the second level layer, between the gap-insulating layer **14b** of the second level layer and the gap-insulating layer **14a** of the first level layer, and between the gap-insulating layer **14a** of the first level layer and the electret-insulating film (between the gap-insulating layer **14a** of the first level layer and the polymer film when the electret-insulating film is omitted) determines the dielectric breakdown strength of air.

In the film-shaped electro-mechanical converter according to the fifth embodiment, the insertions of the vibrating-electrode-insulating film **15a** and the plurality of gap-insulating layers **14a**, **14b**, **14c**, . . . enable the gap width W_g of the element-install cavity to be enlarged, and consequently the film-shaped electro-mechanical converter according to the fifth embodiment enables the central line average roughness Ra (that includes the displacement caused by the bending of the vibrating electrode **15b** through the spacers **41a**, **41b**, **41c**, **41d**, . . .) of the bottom surface of the vibrating-electrode-insulating film **15a** (the bottom surface of the vibrating electrode **15b**, when the vibrating-electrode-insulating film **15a** is omitted) to be $\frac{1}{10}$ or less of the gap width W_g . Also, the surface roughnesses of the top surfaces and the bottom surfaces of the gap-insulating layers **14a**, **14b**, **14c**, . . . and the top surface of the electret-insulating film (the top surface of the polymer film when the electret-insulating film is omitted) similarly have influence on the dielectric breakdown strength of air in the gap. Also, Ra of the top surface of the electret-insulating film must be $\frac{1}{10}$ or less of the gap width, and Ra is desired to be $\frac{1}{100}$ or less.

In this way, in the film-shaped electro-mechanical converter according to the fifth embodiment, because the dielectric breakdown strength of air is set to be high, the pressure resistance is very high. Thus, as illustrated in FIG. 20, when the pressure receiving plane contains the vibrating-plate-protection film **16**, differently from the earlier film-shaped electro-mechanical converter, the film-shaped electro-mechanical converter is not required to be stored in a receptacle, and the film-shaped electro-mechanical converter can be used, by pasting the film-shaped electro-mechanical converter onto a necessary portion. Also, the film-shaped electro-mechanical converter according to the fifth embodiment can be used as a waterproof microphone, because the structure having the high waterproof characteristics can be easily achieved. Moreover, the film-shaped electro-mechanical converter can be used as a pressure sensor for detecting a pressure fluctuation of 10 Hz or more in the fluid and the living body. Because the earlier film-shaped electro-mechanical converter is low in pressure resistance, the microphone device is accommodated

in a receptacle so that the pressure receiving plane can be protected. However, in the film-shaped electro-mechanical converter according to the fifth embodiment, because the vibrating-plate-protection film **16** and the like are used to protect the surface of the vibrating electrode **15b** from being damaged, even if the pressure receiving plane is directly thumped with a finger and the like, the sensitivity is never deteriorated.

—Reception Sensibility—

When the film-shaped electro-mechanical converter according to the fifth embodiment is used as the ultrasonic probe, the bending of the vibrating plate **15** and the deformation of the contact point in the microgap cause the vibrating plate **15** to be vibrated and the acoustic wave (ultrasonic wave) to be transmitted/received. When the vibrating plate **15** of the film-shaped electro-mechanical converter is vibrated by the acoustic wave (ultrasonic wave), with the principle similar to the electret condenser microphone, the change in the capacitance of the gap results in the change in the potential difference across the electrodes, and the output ΔV_{out} is given by Eqs. (1), (2) described in the first embodiment. At this time, with q_d as the unit charge, the vibrating plate **15** is pulled by the electro-statistic force σ_e given by Eq. (3) described in the first embodiment, from the polymer film. Attention should be paid to the fact that, via the protrusions (including the particles) in the microgap, which serve as the fulcrums, the vibrating plate **15** is pulled to the gap side, by the electrostatic force σ_e of the polymer film, and statically bent. That is, the rigidity of the vibrating plate **15**, the contact point density and the arrangement in the microgap shall be designed in such a way that Ra of the surface at the gap side of the vibrating electrode **15b** is $1/10$ or less of the gap width in the element-install cavity at statically deformed state. Also, when the bending causes the plurality of gap-insulating layers **14a**, **14b**, **14c**, . . . implementing the microgaps to be brought into contact at a position different from the protrusions, the number of the contact points will increase, which severely reduces the contact rigidity. Thus, the contact at the position different from the protrusions must be avoided by increasing the rigidity of the vibrating plate **15**, by increasing the height of the protrusions, or by increasing density of the protrusions.

—Vibration Caused by Bending of Vibration Plate—

The vibration caused by the bending of the vibrating plate is similarly generated even in the earlier electret microphone. Also, even if the bending is caused by the assumable maximum sound pressure, the two layers implementing the microgap must not be brought into contact at the position except the protrusions.

Vibration Caused by Deformation of Micro Gap—

The structure illustrated in FIG. 20 is illustrated as an example, and the microgap can be achieved without using the particles as the spacers **41a**, **41b**, **41c**, **41d**, By replacing the electret-insulating layer **14e** in the explanation of the first embodiment with the gap-insulating layer **14c** of the third level layer in the fifth embodiment, in a model that the microgap is formed through the dry contact, the micro protrusions of the constant radius r illustrated in FIG. 2 can be considered as the central line average roughness Ra of the convex portion formed at the surface of any films between the vibrating-electrode-insulating film **15a** and the gap-insulating layer **14c** of the third level layer (the electret-insulating layer **14e** in the explanation in the first embodiment). Or alternatively, it can be considered that the particles, which are inserted between the vibrating-electrode-insulating film **15a** and the gap-insulating layer **14c** of the third level layer, implement the convex portions. Thus, the configuration illustrated in FIG. 2 is a schematic view serving as the base of the definition of “effec-

tive surface roughness Ra_{eff} of the surface establishing microgap”, which is formed between the vibrating-electrode-insulating film **15a** and the gap-insulating layer **14c** of the third level layer. The micro protrusions of the constant radius r as illustrated in FIG. 2, may be formed by generating local thermal deformations when the pulse laser is irradiated to the top surface of the gap-insulating layer **14c** of the third level layer, by heating the entire film implementing the gap-insulating layer **14c** of the third level layer so as to carry out the precipitation of oligomers or the self-organization of polymers, or alternatively, by processing the gap-insulating layer **14c** of the third level layer through the press working.

As described in the first embodiment, silicon particles may be aggregated in the in-plane direction, as illustrated in FIG. 3, and the average interval between the aggregated groups is 100 micrometers. Also, the tolerance of the thickness of each resin layer as the vibrating-electrode-insulating film **15a** and the gap-insulating layer **14c** of the third level layer (the electret-insulating layer **14e** in the explanation of the first embodiment) is $\pm 10\%$, in many cases. For this reason, similar to the configuration illustrated in FIG. 3, between the vibrating-electrode-insulating film **15a** and the gap-insulating layer **14c** of the third level layer, microgaps can be formed by contacts at localized portions in the distribution of the aggregations of silicon particles. Via contacts through the aggregations of silicon particles, an electric field of about 70 MV/m can be applied from the polymer film in the inside of the microgap.

As described in the first embodiment, in the model in which the top surface of the gap-insulating layer **14c** of the third level layer has the micro protrusions of the constant radius r as illustrated in FIG. 2, the contact pressure σ is represented by Eqs. (4), (5). Then, the contact rigidity (boundary rigidity) K_g that is the spring constant per unit area in the microgap between the vibrating-electrode-insulating film **15a** and the gap-insulating layer **14c** of the third level layer is given by Eq. (6) described in the first embodiment. Thus, if $K_g \ll S'$, the amplitude ΔW_g of the vibrating-electrode-insulating film **15a** is given by Eq. (7). Thus, similarly to the first embodiment, from Eqs. (1), (3), (5), (6) and (7), the output ΔV_{out} is represented by Eq. (8). From Eq. (8), in order to improve the reception sensitivity, the electric field strength E_g in the gap shall be increased, and the storage elastic moduli of one or both of the two layers with the microgap between shall be made low, and the radius r of the protrusion shall be made small, and the density n of the protrusions shall be made low (the interval may be made wide). However, the decrease in the radius r and the density n of the protrusions results in the increase of the bending of the vibrating-electrode-insulating film **15a**. Thus, as mentioned above, attention should be paid to the requirements that the effective surface roughness Ra_{eff} of a plane defining the microgap is limited to be $1/10$ or less of the gap width of the element-install cavity and also that the contact density of the microgap portion shall not be increased by the bending.

—Influence on Output of Film-Shaped Electro-Mechanical Converter—

As for the film-shaped electro-mechanical converter, when a voltage pulse of the amplitude ΔV_{in} is supplied to an input of the film-shaped electro-mechanical converter for transmitter, the pressure $\Delta \sigma_{out}$ generated at the vibrating-electrode-insulating film **15a** in the film-shaped electro-mechanical converter is given by Eq. (9) described in the first embodiment. Together with the bending of the vibrating-electrode-insulating film **15a** and the deformations at the contact points in the microgap, the vibrating-electrode-insulating film **15a** is driven on the basis of the $\Delta \sigma_{out}$ of Eq. (9), and the vibration of the vibrating-electrode-insulating film **15a** is generated, and

the acoustic wave is transmitted from the film-shaped electro-mechanical converter. Thus, from Eq. (9), it can be understood that, when the gap width W_g of the element-install cavity becomes narrower and the electric field strength E_g of the gap becomes higher, the sound pressure of the film-shaped electro-mechanical converter becomes large, and the output of the film-shaped electro-mechanical converter improves.

—Damping of Acoustic Wave—

As another merit of the microgap lies in the damping (attenuation) of the ultrasonic wave. At boundary portions that do not contact because of the spacers **41a**, **41b**, **41c**, **41d**, . . . in the microgap portions, reflections of the acoustic wave are generated. Thus, the acoustic wave that is propagated to the polymer film is largely attenuated. When the acoustic wave is propagated to reach the polymer film, the polymer film is distorted to generate piezoelectric effect, and the output resulting from the piezoelectric effect overlaps with the subject reception output. Because the overlap of the piezoelectric effect deteriorates the performance of the electret probe (film-shaped electro-mechanical converter), in the gap portion, the acoustic wave is desired to be attenuated to the utmost extent. Providing with a plurality of microgaps, the attenuation of the acoustic wave in the gap portion is dramatically increased.

FIG. 22 is a view representing a relation between the sensitivity (dB) and the frequency (Hz) of the film-shaped electro-mechanical converter according to the fifth embodiment, while the lamination number n ($n=5, 10, 40$ and 100) of high density polyethylene (HDPE) films is recited as a parameter. In the targeted film-shaped electro-mechanical converter for the measurement in FIG. 22, the tetra-fluoride ethylene-hexafluoride propylene copolymerization (FEP) film with a thickness of 12 micrometers is changed into an electret by corona discharge so as to implement the polymer film serving as the electret, and on the polymer film, the n HDPE films each having a thickness of ten micrometers are laminated as the gap-insulating layers **14a**, **14b**, **14c**, . . . , and the gap is formed, and then, Al foils are used as the vibrating electrode **15b** and the back electrode **17**, and the pressure receiving plane is formed as a circular shape having a diameter of 30 millimeters.

As can be understood from FIG. 22, when the n ($n=40$) HDPE films are laminated as the gap-insulating layers **14a**, **14b**, **14c**, . . . , the sensitivity is about -32 dB. Because the sensitivity of general electret condenser microphones is between -60 and -45 dB, the film-shaped electro-mechanical converter according to the fifth embodiment has shown a very high sensitivity compared with the general electret condenser microphones.

<Manufacturing Method of Film-Shaped Electro-Mechanical Converter According to Fifth Embodiment>

The manufacturing method of the film-shaped electro-mechanical converter according to the fifth embodiment will be described below by using FIG. 23 to FIG. 28. By the way, the manufacturing method of the film-shaped electro-mechanical transducer which will be described below is recited as one of examples. Within the scope prescribed by Claims, including various modified examples, the film-shaped electro-mechanical converter can be naturally fabricated by using various manufacturing methods other than the following description.

(a) At first, an aluminum (Al) film serving as a shielding-conductor film **11b** is deposited on a shielding-conductor-protection film **11a** such as PVC film and the like, so as to implement a shield plate **11**. The shield plate **11** is pasted on the rear surface of a spacer film **12a** made of insulating material. Moreover, after second Al film is pasted on the top surface of the spacer film **12a**, the second Al film is delineated to implement a back electrode **17**. On a part of the back

electrode **17**, a shallow groove **17g** is cut as illustrated in FIG. 23. Then, as illustrated in FIG. 23, a tetrafluoroethylene-perfluoroalkyl vinyl ether copolymer (PFA) film as a polymer film is pasted on a part of the top surface of the back electrode **17**. The back electrode **17** and the polymer film may be metallurgically joined or may be adhered by adhesive agent and the like, or alternatively, may be merely brought into contact by the mechanical pressure. After the polymer film is formed on the back electrode **17**, as illustrated in FIG. 24, the polymer film is electrified by corona discharge.

(b) Then, as illustrated in FIG. 25, while the spacer film **12a** made of insulating material can be used as a bottom plate, side-wall films **12b**, **12d** servicing as side-plate blocks of a box are arranged around the polymer film, and a box-shaped insulation container (**12a**, **12b**, **12d** and **12e**) is assembled. At this time, the insulating layer **12d** attached with a canopy top **12e** is fitted into the shallow groove **17g** formed in a part of the back electrode **17**.

(c) In the inside of the box-shaped insulation container (**12a**, **12b**, **12d** and **12e**), a stacked structure in which the plurality of gap-insulating layers **14a**, **14b**, **14c**, . . . are laminated through the spacers **41a**, **41b**, **41c**, **41d**, . . . implemented by the particles of insulators each having a particle diameter between ten nanometers and 40 micrometers are accommodated as illustrated in FIG. 26. When the diameter of the particles of insulators serving as each of the spacers **41a**, **41b**, **41c**, **41d**, . . . is elected to be between ten nanometers and ten micrometers, the entire thickness is made thinner, which is preferable. Moreover, in a range between ten nanometers and five micrometers, the particle diameter closer to ten nanometers is naturally desirable. The stacked structure implemented by the plurality of gap-insulating layers **14a**, **14b**, **14c**, . . . can be manufactured by, for example, the repetition of the following procedures. That is, inside a separately-prepared lamination-process container, the silicon particles, which are scheduled to become spacers **41a**, **41b**, **41c**, **41d**, . . . , are colloiddally diffused into solvent **55** by dispersant. Then, after a gap-insulating layer **14a** of the first level layer is accommodated into the lamination-process container, the solvent **55** is dropped on the gap-insulating layer **14a** of the first level layer, and dried so as to coat silicon particles serving as the spacers **41a**, **41b** on the gap-insulating layer **14a**. Next, after a gap-insulating layer **14b** of the second level layer is accommodated in the lamination-process container, the solvent **55** is dropped on the gap-insulating layer **14b** of the second level layer, and dried so as to coat the silicon particles serving as the spacers **41c** on the gap-insulating layer **14b**. Moreover, after a gap-insulating layer **14c** of the third level layer is accommodated in the lamination-process container, the solvent **55** is dropped on the gap-insulating layer **14c** of the third level layer, and dried so as to coat the silicon particles as the spacers **41d** on the gap-insulating layer **14c**. By the way, another methods such that preliminarily performing surface processes on each of the plurality of gap-insulating layers **14a**, **14b**, **14c**, . . . so as to implement micro protrusions (spacers **41a**, **41b**, **41c**, **41d**, . . .) can be available.

Moreover, when the surface of the gap-insulating layer **14a** facing to the electret is electrified by corona discharge (the polarity of the charges generated on the surface of the gap-insulating layer **14a** is set to the same polarity as the electret), it is possible to protect discharge after when the electret is stacked, and also to reduce the attenuation of the charges on the electret.

(d) On the other hand, on a PFA film as the vibrating-electrode-insulating film **15a**, an Al film as a vibrating electrode **15b** is deposited so as to form a vibrating plate **15**. Moreover, on the vibrating electrode **15b**, a vibrating-plate-

protection film **16** made of PVC film is pasted so as implement a stacked structure with the vibrating plate **15**, and the stacked structure is provided on the insulation container (**12a**, **12b**, **12d** and **12e**) as a top cover, as shown FIG. **27**. By the way, the solvent in which the silicon particles are colloiddally diffused may be dropped on the PFA film on which the Al film is deposited as the vibrating plate **15**, and dried so that the silicon particles as the spacers **41d** are coated on the vibrating-electrode-insulating film **15a**, and after that, as illustrated in FIG. **27**, the stacked structure may be put as the top cover of the insulation container (**12a**, **12b**, **12d** and **12e**). Moreover, it is allowable to use a method that preliminarily performs surface process on the PFA film as the vibrating-electrode-insulating film **15a** so as to form the micro protrusions.

(e) Moreover, separately, such as a ball grid array and the like, on a circuit board **18** that has a connector at the bottom of the board, an amplifying circuit **19** in which an amplifier (FET) is integrated is installed (mounted), thereby preparing a mounted structure (package) of the amplifier. Each of the electrodes of the amplifier integrated in the amplifying circuit **19** are electrically connected to connection electrodes, such as solder balls and the like, which are provided on the rear surface of the circuit board **18**, through inner wirings and through holes (vias) provided in the circuit board **18** and surface wirings disposed on the surface of the circuit board **18**. The mounted structure (package) of the amplifier is accommodated under the canopy top **12e** of the box-shaped insulation container (**12a**, **12b**, **12d** and **12e**), as illustrated in FIG. **28**. After when the mounted structure (package) is accommodated under the canopy top **12e** of the box-shaped insulation container (**12a**, **12b**, **12d** and **12e**), a sealing insulating block **12c** is inserted under the canopy top **12e** as illustrated in FIG. **20** so that the sealing cover is plugged into the portion of the box-shaped insulation container (**12a**, **12b**, **12d** and **12e**) for storing the mounted structure (package), the film-shaped electro-mechanical converter according to the fifth embodiment is completed.

FIG. **29** illustrates roughly an outline of the main processes of the manufacturing method of the film-shaped electro-mechanical converter according to the fifth embodiment, which are explained with referring to FIG. **23** to FIG. **28**. That is, (a) at first, as illustrated in FIG. **29(a)**, on the top surface of a back electrode **17p**, a PFA film is pasted as the polymer film. (b) Then, after the polymer film is pasted on the back electrode **17p**, as illustrated in FIG. **29(b)**, the polymer film is electrified by corona discharge and the like. (c) Meanwhile, a vibrating plate **15s** is prepared, by depositing an Al film as the vibrating electrode on the rear surface of a PFA film as the vibrating-electrode-insulating film. And on the PFA film, a plurality of gap-insulating layers **14a**, **14b**, **14c**, . . . are laminated through spacers (illustration is omitted) on the vibrating plate **15s**. (d) Then, the polymer film having the back electrode **17p**, and a structure in which the plurality of gap-insulating layers **14a**, **14b**, **14c**, . . . are laminated through the spacers (illustration is omitted) on the vibrating plate **15s** are assembled into a predetermined box, such as the insulation container (**12a**, **12b**, **12d** and **12e**) illustrated in FIG. **20**, so as to implement the lamination relationship as illustrated in FIG. **29(c)**. Through the above simple steps, the film-shaped electro-mechanical converter according to the fifth embodiment is completed.

By the way, ferroelectric material can be used as the polymer film, for example, when PZT, in which the polarization directions are aligned although the ferroelectric material is not electrified is assembled as the polymer film into the box-shaped insulation container (**12a**, **12b**, **12d** and **12e**), in accordance with the above procedure. After the assembling is finished, the ferroelectric material is heated to the temperature

close to Curie point and held for several seconds to several minutes. Then, when the ferroelectric material is cooled to the room temperature, the surface charges of the ferroelectric material are removed so as to form the polymer film. When Curie point temperature is higher than the soldering reflow temperature and then the reflow process of the packaged structure (product) including the film-shaped electro-mechanical converter is carried out, the ferroelectric material is changed into the polymer film by the reflow process.

According to the film-shaped electro-mechanical converter pertaining to the fifth embodiment, since its aerial transmission/reception sensitivity is higher than that of the earlier film-shaped electro-mechanical converter, the precisions of the distance measurement and the like can be expected to be improved. Moreover, if a frequency modulation is used, the transmission/reception with higher precision can be further achieved. Specifically, by changing the frequency of the film-shaped electro-mechanical converter, a particular signal pattern is generated in the film-shaped electro-mechanical converter. Then, the electro-mechanically converted signal pattern may be selectively extracted at receiver site, and if the signal pattern is predetermined to be the pattern that is not generated under the noise, the received waveform buried in the noise can be identified even in the environment in which the noise is high. The above scheme which employs such particular signal pattern can be estimated as an approach peculiar to the film-shaped electro-mechanical converter of the present invention, in which the transmission/reception is possible in the wide frequency band.

As mentioned above, in the film-shaped electro-mechanical converter pertaining to the fifth embodiment, when the polymer film is used as the electret layer **13**, the film-shaped electro-mechanical converter is flexible and has no constraint on the shape of the pressure receiving plane. Thus, it is possible to deform the shape of the pressure receiving plane corresponding to the shape of an object allocated at any desired measurement location. Also, except the amplifying circuit **19** (if the thickness of the amplifying circuit **19** is set to 60 micrometers or less, the amplifying circuit **19** can be deformed although its deformation level is small), because all of the constituent members are made of thin films, the film-shaped electro-mechanical converter can be flexibly deformed. Ferroelectric material can be used as the electret layer **13** and when the ferroelectric material is processed to a film having the thickness of 60 micrometers or less, the flexibility is obtained. However, as compared with the polymer film, the deformation level of the ferroelectric material is small, and the flexibility cannot be expected at a thickness of 60 micrometers or more. Moreover, the microgaps are supported by the spacers **41a**, **41b**, **41c**, **41d**, . . . implemented by the many particles (or micro protrusions) made of insulators each having the particle diameter between ten nanometers and 40 micrometers, as illustrated in FIG. **21**. Thus, the shape of the pressure receiving plane can be arbitrarily designed. For example, when the film-shaped electro-mechanical converter is used in a mobile telephone, the film-shaped electro-mechanical converter pertaining to the fifth embodiment can be attached between buttons and the like. However, when the film-shaped electro-mechanical converter pertaining to the fifth embodiment is deformed, there is a fear that the respective layers of the polymer film, the gaps and the vibrating electrode **15b** are slightly displaced. The entire amount of displacement depends on the deformation level, the thickness and area of the film-shaped electro-mechanical converter, and the amount of displacement for each of the gap-insulating layers **14a**, **14b**, **14c**, . . . implementing the respective layers

depends on even the film thickness. Then, when each thickness of the gap-insulating layers **14a**, **14b**, **14c**, . . . is assumed to be t , because the maximum amount of displacement for each of the gap-insulating layers **14a**, **14b**, **14c**, . . . caused by the deformation is $2\pi t$, the maximum amount of displacement must be smaller than the interval between the micro protrusions implementing the microgap. The interval between the micro protrusions is determined on the basis of the maximum allowable sound pressure (pressure resistance) of the film-shaped electro-mechanical converter, and a pressure resistance of at least one atmospheric pressure or more is required, because the external force is directly applied to the pressure receiving plane, as illustrated in FIG. 20. By considering the above situations, the interval between the micro protrusions shall be 500 micrometers or less, and each thickness of the gap-insulating layers **14a**, **14b**, **14c**, . . . implementing the film-shaped electro-mechanical converter shall be 80 micrometers or less.

Also, when the area of the pressure receiving plane of the film-shaped electro-mechanical converter pertaining to the fifth embodiment is excessively small, the capacitance is insufficient, which results in the reduction in sensitivity. The necessary area depends on the gap thickness, the thickness of the polymer film and the dielectric constant. However, at least 1 mm^2 or more is required and 10 mm^2 or more is desirable. Also, when the area of the pressure receiving plane is excessively large, the gap-insulating layers **14a**, **14b**, **14c**, . . . may be fluctuated by sound, and the variation in the output is consequently increased. Moreover, as the displacements of the laminated gap-insulating layers **14a**, **14b**, **14c**, . . . increase, air gap width between the gap-insulating layers **14a**, **14b**, **14c**, . . . increases, which brings about the generation of the discharge, and the sensitivity is deteriorated. The upper limit of the area of the pressure receiving plane depends on the thicknesses of the gap-insulating layers **14a**, **14b**, **14c**, . . . implementing the film-shaped electro-mechanical converter and the frequency band of the sound to be measured. So, at least 100 cm^2 or less is required and 10 cm^2 or less is desirable.

Sixth Embodiment

In the film-shaped electro-mechanical converter pertaining to the fifth embodiment of the present invention illustrated in FIG. 20, when a polymer film is used as the polymer film **13b**, as shown as a microphone B in FIG. 30(b), even if a sound pressure Φ_2 is received from the side of the polymer film **13b**, the vibration is transmitted to gap-insulating layers **14p**, **14q**, **14r**, . . . without any substantial attenuation through the polymer film **13b**. Thus, when the side of the back electrode **17b** is used as the pressure receiving plane, the sensitivity is little different from a situation in which a sound pressure Φ_1 is received from the side of the vibrating plate **15u**, such as a microphone A illustrated in FIG. 30(a).

A film-shaped electro-mechanical converter according to a sixth embodiment of the present invention is a double-sided film-shaped electro-mechanical converter that can carry out receptions on both faces of the electro-mechanical converter, in which the microphone A illustrated in FIG. 30(a) and the microphone B illustrated in FIG. 30(b) are compatible. As illustrated in FIG. 30(a), the microphone A as a first pressure receiving device M_1 encompasses a vibrating plate **15u** having a flat vibration surface under no load condition; a polymer film **13a**, which is defined by a flat first principal surface facing to the vibration surface of the vibrating plate **15u** through a gap space, the thickness of the gap space is measured in a stacked structure implemented by a gap-insulating

layer **14a** of the first level layer, a gap-insulating layer **14b** of the second level layer and a gap-insulating layer **14c** of the third level layer, and a second principal surface facing in parallel to the first principal surface, the polarization directions are aligned in the polymer film **13a**; a back electrode **17a** in contact with the second principal surface of the polymer film **13a**; and an amplifying means (illustration is omitted) connected between the vibrating plate **15u** and the back electrode **17a**. Similarly to the configuration illustrated in FIG. 21 in the explanation of the film-shaped electro-mechanical converter pertaining to the fifth embodiment, first spacers implemented by particles of insulator having a particle diameter between ten nanometers and 40 micrometers are inserted between the gap-insulating layer **14a** of the first level layer and the polymer film **13a**, and second spacers implemented by particles of insulators having a particle diameter between ten nanometers and 40 micrometers are inserted between the gap-insulating layer **14a** of the first level layer and the ID gap-insulating layer **14b** of the second level layer, and third spacers implemented by particles of insulators having a particle diameter between ten nanometers and 40 micrometers are inserted between the gap-insulating layer **14b** of the second level layer and the gap-insulating layer **14c** of the third level layer, and fourth spacers implemented by particles of insulators having a particle diameter between ten nanometers and 40 micrometers are inserted between the vibrating electrode **15b** and the gap-insulating layer **14c** of the third level layer so as to control the interval of the gap defined between the vibrating electrode **15b** and the polymer film **13a**. In this way, between the vibrating plate **15u** and the polymer film **13a**, the plurality of gap-insulating layers **14a**, **14b**, **14c**, . . . are laminated and inserted through the spacers implemented by particles of insulators each having the particle diameter between ten nanometers and 40 micrometers. Consequently, microgaps are defined between the vibrating plate **15u** and the gap-insulating layer **14c** of the third level layer, between the gap-insulating layer **14c** of the third level layer and the gap-insulating layer **14b** of the second level layer, between the gap-insulating layer **14b** of the second level layer and the gap-insulating layer **14a** of the first level layer, and between the gap-insulating layer **14a** of the first level layer and the polymer film **13a**, respectively. Consequently, the gap width W_g of the macroscopic element-install cavity between the vibrating plate **15u** and the polymer film **13a** is controlled. When each diameter of the particles serving as the first to fourth spacers are assumed to be 100 micrometers or less, the effective surface roughness Ra_{eff} of the surfaces establishing each of the microgaps can be set to $1/10$ or less of each gap width of the element-install cavity which is defined to accommodate the microgaps between the bottom surfaces of the vibrating plates **15u**, **15v** and the top surfaces of the polymer films **13a**, **13b** (the effective surface roughness Ra_{eff} includes the bending under no load condition). However, in order to achieve the film-shaped electro-mechanical converter that is flexible and has a high degree of freedom in geometrical deformations, the particle diameter of the particle of each of the first to fourth spacers is elected to be ten nanometers to ten micrometers, which is preferable because the entire thickness becomes further thin. Moreover, in a range between ten nanometers and five micrometers, the particle diameter closer to ten nanometers is naturally desirable. In the first pressure receiving device M_1 (microphone A), the side of the back electrode **17a** is used as the output terminal.

Meanwhile, as illustrated in FIG. 30(b), the microphone B as a second pressure receiving device M_2 encompasses a vibrating electrode **15v** having a flat vibration surface under no load condition; a polymer film **13b** which is defined by a

flat first principal surface facing to the vibration surface of the vibrating plate **15v** through a gap space, the thickness of the gap space is measured in a stacked structure implemented by a gap-insulating layer **14p** of the first level layer, a gap-insulating layer **14q** of the second level layer and a gap-insulating layer **14r** of the third level layer, and a second principal surface facing in parallel to the first principal surface, the polarization directions are aligned in the polymer film **13b**; a back electrode **17b** in contact with the second principal surface of the polymer film **13b**; and amplifying means (illustration is omitted) connected between the vibrating plate **15v** and the back electrode **17b**. Similarly to the microphone A, between the vibrating plate **15v** and the polymer film **13b**, the plurality of gap-insulating layers **14p**, **14q**, **14r**, . . . are laminated and inserted through the spacers implemented by particles of insulators each having a particle diameter between ten nanometers and 40 micrometers. Consequently, the microgaps are defined between the vibrating plate **15v** and the gap-insulating layer **14r** of the third level layer, between the gap-insulating layer **14r** of the third level layer and the gap-insulating layer **14q** of the second level layer, between the gap-insulating layer **14q** of the second level layer and the gap-insulating layer **14p** of the first level layer, and between the gap-insulating layer **14p** of the first level layer and the polymer film **13b**, respectively. Consequently, the gap width W_g of the macroscopic element-install cavity between the vibrating plate **15v** and the polymer film **13b** is controlled. In the second pressure receiving device M_2 (microphone B), the side for receiving a voice is located facing to the first pressure receiving device M_1 (microphone A). Thus, the side of the vibrating plate **15v** serves as the output terminal.

The microphone A (the first pressure receiving device M_1) illustrated in FIG. **30(a)** and the microphone B (the second pressure receiving device M_2) illustrated in FIG. **30(b)** are both made of thin film. Thus, the deformation is flexibly possible.

FIG. **31** shows a noise-cancelling phone as a specific example of the film-shaped electro-mechanical converter according to the six embodiment. As illustrated in FIG. **31**, the film-shaped electro-mechanical converter according to the sixth embodiment encompasses a board (microphone substrate) **21** in which a semiconductor chip (FET amplifier) **19** is built; a first pressure receiving device M_1 (microphone A) that is bent correspondingly to a curvature of a corner and bonded to an the upper left corner of the board (microphone substrate) **21**; and a second pressure receiving device M_2 (microphone B) that is bent correspondingly to a curvature of a corner and bonded to the lower left corner of the board (microphone substrate) **21**. Both of the first pressure receiving device M_1 and the second pressure receiving device M_2 are flexible and have no constraint on the shape of the pressure receiving plane. Thus, the first pressure receiving device M_1 and the second pressure receiving device M_2 can have any shape corresponding to a target allocated at the arrangement place and can be deformed. Thus, as illustrated in FIG. **31**, the first pressure receiving device M_1 (microphone A) can be curved and bonded to the upper left corner of the board (microphone substrate) **21** so that the back electrode **17a** is brought into contact with the board (microphone substrate) **21**, and the second pressure receiving device M_2 (microphone B) can be curved and bonded to the bottom left corner of the board (microphone substrate) **21** so that the vibrating plate **15v** is brought into contact with the board (microphone substrate) **21**.

In this way, in the film-shaped electro-mechanical converter (noise-cancelling phone) according to the sixth

embodiment, the first pressure receiving device M_1 and the second pressure receiving device M_2 , in which the sides for receiving the voice are located opposite to each other with regard to the front/rear relation, are bonded to the surface of the board (microphone substrate) **21**, and the outputs from the first pressure receiving device M_1 and the second pressure receiving device M_2 can be received by the same semiconductor chip (FET amplifier) **19**.

As illustrated in FIG. **31**, the first pressure receiving device M_1 is bonded to the board (microphone substrate) **21** in such a way that the back electrode **17a** is brought into contact with the board (microphone substrate) **21**, and the second pressure receiving device M_2 is bonded to the board (microphone substrate) **21** in such a way that the vibrating plate **15v** is brought into contact with the board (microphone substrate) **21**. Thus, the polarities of the signals of the first pressure receiving device M_1 and the second pressure receiving device M_2 are inverted, thereby removing noises N_1 , N_2 and N_3 . Consequently, it is possible to simplify the circuit of the film-shaped electro-mechanical converter (noise-cancelling phone) according to the sixth embodiment.

In the film-shaped electro-mechanical converter according to the sixth embodiment, there is a fear that stray capacitances will increase on the transmission route from the first pressure receiving device M_1 and the second pressure receiving device M_2 to the semiconductor chip (FET amplifier) **19**. However, as mentioned above, as for the first pressure receiving device M_1 and the second pressure receiving device M_2 , because the respective shapes are free, the freedom in shape can be used to enlarge the areas of the pressure receiving planes, and, it is adequate to make the active capacitances of the first pressure receiving device M_1 and the second pressure receiving device M_2 sufficiently large.

Seventh Embodiment

In the film-shaped electro-mechanical converter according to the sixth embodiment, there is the fear that the stray capacitance will increase on the transmission route from the first pressure receiving device M_1 and the second pressure receiving device M_2 to the semiconductor chip (FET amplifier) **19**. For this reason, the film-shaped electro-mechanical converter according to the sixth embodiment employs the method which uses the fact that the shapes of the first pressure receiving device M_1 and the second pressure receiving device M_2 are free, and enlarges the area of the pressure receiving plane and sufficiently increases the active capacitances of the first pressure receiving device M_1 and the second pressure receiving device M_2 . In a film-shaped electro-mechanical converter according to a seventh embodiment of the present invention, another method is described which can increase the active capacitance, facilitating the compensation of the stray capacitance, in the double-sided film-shaped electro-mechanical converter that can carry out the reception on both sides of the film-shaped electro-mechanical converter.

That is, in the film-shaped electro-mechanical converter according to the seventh embodiment of the present invention, as illustrated in FIG. **32**, an upper polymer film **13a** and a lower polymer film **13b** are bonded on and under a common electrode **17c** for inputting/delivering signals, respectively, so that their respective polarities are opposite to each other.

The first pressure receiving device M_1 formed on the common electrode **17c** encompasses an upper vibrating plate **15** having a flat vibration surface under no load condition; an electret-insulating layer **14e** that faces the vibration surface of the upper vibrating plate **15** through a gap space, the thickness of the gap space is measured in a stacked structure imple-

mented by an upper gap-insulating layer **14a** of the first level layer, an upper gap-insulating layer **14b** of the second level layer and an upper gap-insulating layer **14c** of the third level layer; an upper polymer film **13a** which is defined by a flat first principal surface facing to the electret-insulating layer **14e** and a second principal surface facing in parallel to the first principal surface, the polarization directions are aligned in the electret-insulating layer **14e**; and a common electrode **17c** in contact with the second principal surface of the upper polymer film **13a**. The upper vibrating plate **15** contains an upper vibrating electrode **15b** made of conductor and a vibrating-electrode-insulating film **15a** at the bottom surface of the upper vibrating electrode **15b**, as illustrated in FIG. **32**. Similarly to that illustrated in FIG. **21** in the explanation of the film-shaped electro-mechanical converter pertaining to the fifth embodiment, the first spacers implemented by particles of insulators having a particle diameter between ten nanometers and 40 micrometers are inserted between the upper gap-insulating layer **14a** of the first level layer and the electret-insulating layer **14e**, the second spacers implemented by particles of insulators having a particle diameter between ten nanometers and 40 micrometers are inserted between the upper gap-insulating layer **14a** of the first level layer and the upper gap-insulating layer **14b** of the second level layer, and the third spacers implemented by particles of insulators having a particle diameter between ten nanometers and 40 micrometers are inserted between the upper gap-insulating layer **14b** of the second level layer and the upper gap-insulating layer **14c** of the third level layer, and the fourth spacers implemented by particles of insulators having a particle diameter between ten nanometers and 40 micrometers are inserted between the vibrating plate **15b** and the upper gap-insulating layer **14c** of the third level layer, and the interval of the gap defined between the vibrating electrode **15b** and the upper polymer film **13a** is controlled. In this way, between the upper vibrating plate **15** and the upper polymer film **13a**, the plurality of upper gap-insulating layers **14a**, **14b**, **14c**, . . . are laminated and inserted through the spacers implemented by particles of insulators each having the particle diameter between ten nanometers and 40 micrometers. Consequently, the microgaps are defined between the upper vibrating plate **15** and the upper gap-insulating layer **14c** of the third level layer, between the upper gap-insulating layer **14c** of the third level layer and the upper gap-insulating layer **14b** of the second level layer, between the upper gap-insulating layer **14b** of the second level layer and the upper gap-insulating layer **14a** of the first level layer, and between the upper gap-insulating layer **14a** of the first level layer and the upper polymer film **13a**, respectively. Consequently, the gap width W_g of the macroscopic element-install cavity between the upper vibrating plate **15** and the upper polymer film **13a** is controlled. When the particle diameter of the particle serving as each of the first to fourth spacers is elected to be 100 micrometers or less, the effective surface roughness Ra_{eff} of the surfaces establishing each of the microgaps can be $1/10$ or less of the gap width of the element-install cavity that is defined to accommodate the microgaps between the bottom surface of the upper vibrating plate **15** and the top surface of the upper polymer film **13a** (the effective surface roughness Ra_{eff} includes the bending under a loaded condition). However, in order to achieve the film-shaped electro-mechanical converter that is flexible and has a high degree of freedom in geometrical deformations, the particle diameter of the particle serving as each of the first to fourth spacers is elected to be ten nanometers to ten micrometers, which is preferable because the entire thickness becomes further thin. Moreover,

in a range between ten nanometers and five micrometers, the particle diameter closer to ten nanometers is naturally desirable.

The second pressure receiving device M_2 formed under the common electrode **17c** encompasses a shielding-conductor film **11b**; a lower polymer film **13b** which is defined by a flat first principal surface facing to the vibration surface of the shielding-conductor film **11b**, through a gap space, the thickness of the gap space is measured in a stacked structure implemented by a lower gap-insulating layer **14p** of the first level layer, a lower gap-insulating layer **14q** of the second level layer and a lower gap-insulating layer **14r** of the third level layer, and a second principal surface facing in parallel to the first principal surface; and a common electrode **17c** in contact with the second principal surface of the lower polymer film **13b**. The shielding-conductor film **11b** serves as the vibrating plate having the flat vibration surface under no load condition of the second pressure receiving device M_2 . Similarly to the first pressure receiving device M_1 , between the shielding-conductor film **11b** and the lower polymer film **13b**, a plurality of lower gap-insulating layers **14p**, **14q**, **14r**, . . . are laminated and inserted through the spacers implemented by particles of insulators each having the particle diameter between ten nanometers and 40 micrometers. Consequently, the microgaps are defined between the shielding-conductor film **11b** and the lower gap-insulating layer **14r** of the third level layer, between the lower gap-insulating layer **14r** of the third level layer and the lower gap-insulating layer **14q** of the second level layer, between the lower gap-insulating layer **14q** of the second level layer and the lower gap-insulating layer **14p** of the first level layer, and between the lower gap-insulating layer **14p** of the first level layer and the lower polymer film **13b**, respectively. Consequently, the gap width W_g of the macroscopic element-install cavity between the shielding-conductor film **11b** and the lower polymer film **13b** is controlled. In the first pressure receiving device M_1 and the second pressure receiving device M_2 , the common electrode **17c** is used as the common output terminal.

When the particle diameter of the particle serving as each of the first to fourth spacers is elected to be 100 micrometers or less, the effective surface roughness Ra_{eff} of the surfaces establishing each of the microgaps can be $1/10$ or less of the gap width of the element-install cavity that is defined to accommodate the microgaps between the bottom surface of the lower polymer film **13b** and the top surface of the shielding-conductor film **11b** (the effective surface roughness Ra_{eff} includes the bending under a loaded condition). However, in order to achieve the film-shaped electro-mechanical converter that is flexible and has a high degree of freedom in geometrical deformations, the particle diameter of the particle serving as spacer shall be elected to be ten nanometers to ten micrometers, which is preferable because the entire thickness becomes further thin. Moreover, in a range between ten nanometers and five micrometers, the particle diameter closer to ten nanometers is naturally desirable.

As illustrated in FIG. **32**, the plurality of upper gap-insulating layers **14a**, **14b**, **14c**, . . . , the electret-insulating layer **14e** and the upper polymer film **13a** are accommodated in the inside of the box-shaped insulation containers (**12k**, **12l**) in which the common electrode **17c** is used as the bottom plate, and the upper vibrating plate **15** serves as the cover of the insulation containers (**12k**, **12l**). Meanwhile, the lower polymer film **13b** and the plurality of lower gap-insulating layers **14p**, **14q**, **14r**, . . . are accommodated in the inside of the box-shaped insulation containers (**12k**, **12m** and **12o**) in which the common electrode **17c** serves as the ceiling plate,

and the shielding-conductor film **11b** serves as the bottom plate of the insulation containers (**12k**, **12m** and **12o**).

The semiconductor chip (FET amplifier) **19** is installed (mounted) through a circuit board **18**, in the vicinity of the left end of the bottom surface of the common electrode **17c**, in FIG. **32**. On the circuit board **18**, a through hole (via) is made, and through the through hole (via), an amplifying circuit **19** is electrically connected to the common electrode **17c**, through a solder that is fused and connected to the vicinity of the left end of the common electrode **17c**. Although the illustration is omitted, the ground wiring from the amplifying circuit **19** is connected to the shielding-conductor film **11b** through solder. The electrodes of the amplifier integrated in the amplifying circuit **19** are electrically connected to the connection electrodes, such as the solder ball and the like, on the rear surface of the circuit board **18**, through the inner wirings and the through holes (vias) provided in the circuit board **18** and surface wiring delineated on the surface of the circuit board **18**. The mounted structure (package) of the amplifying circuit **19** is accommodated in an installing cavity provided under the box-shaped insulation containers (**12k**, **12m** and **12o**), as illustrated in FIG. **32**. When the mounted structure (package) is accommodated, as illustrated in FIG. **32**, an insulating layer **12n** is used to put the cover at the bottom surface of the installing cavity. Then, the film-shaped electro-mechanical converter according to the seventh embodiment is completed.

As illustrated in FIG. **32**, in the film-shaped electro-mechanical converter according to the seventh embodiment, the upper polymer film **13a** and the lower polymer film **13b** are bonded on and under the common electrode **17c** for inputting/outputting; the signal, while their polarities are opposite to each other. Moreover, the plurality of upper gap-insulating layers **19a**, **14b**, **14c**, . . . , the plurality of lower gap-insulating layers **14p**, **14q**, **14r**, . . . , the upper vibrating electrode **15b** and the shielding-conductor film **11b** are laminated. The capacitance is two times that of the film-shaped electro-mechanical converter pertaining to the fifth embodiment illustrated in FIG. **20**.

In the film-shaped electro-mechanical converter (noise-cancelling phone) according to the seventh embodiment, in such a way that the sides for receiving the voice are opposite to each other, the first pressure receiving device M_1 and the second pressure receiving device M_2 are bonded to both sides of the common electrode **17c**, and the outputs from the first pressure receiving device M_1 and the second pressure receiving device M_2 can be received by the same amplifying circuit **19**. Thus, the polarities of the signals of the first pressure receiving device M_1 and the second pressure receiving device M_2 are inverted, thereby enabling the removal of the noise. Consequently, it is possible to simplify the circuit of the film-shaped electro-mechanical converter (noise-cancelling phone) according to the seventh embodiment.

By the way, in the second pressure receiving device M_2 in the film-shaped electro-mechanical converter according to the seventh embodiment, the electret-insulating film and the vibrating-electrode-insulating film are omitted. However, similarly to the first pressure receiving device M_1 , the electret-insulating film and the vibrating-electrode-insulating film may be contained. Also, the common electrode **17c** and the upper polymer film **13a**, or the common electrode **17c** and the lower polymer film **13b** may be metallurgically joined or may be adhered by an adhesive agent and the like, or alternatively, may be merely brought, into contact by a mechanical pressure.

Eighth Embodiment

The film-shaped electro-mechanical converters according to the fifth to seventh embodiments can be used not only as

microphones but also as acoustic probes (ultrasonic probes) even with the structures recited in FIGS. **20** and **32**, as they are, because these film-shaped electro-mechanical converters can transmit acoustic waves. Also, the film-shaped electro-mechanical converters according to the fifth to seventh embodiments can be flexibly deformed, because all of them can be made of thin films.

For this reason, for example, even if the surface of a measurement target **1a** is curved as illustrated in FIG. **33**, so as to be fitted to the shape of the target **1a**, a film-shaped electro-mechanical converter **2a** according to a eighth embodiment can be bonded to the target **1a**, thereby enabling the transmission/reception of an acoustic wave (ultrasonic wave) ϕ . For example, when the film-shaped electro-mechanical converter **2a** according to IJ the eighth embodiment is used as an electronic stethoscope, the human body as the measurement target **1a** and the electronic stethoscope (film-shaped electro-mechanical converter) **2a** can be tightly pressed, thereby reducing variation in the reception sensitivity caused by various contact states of the electronic stethoscope **2a**. Also, because the electronic stethoscope **2a** can transmit and receive the ultrasonic wave Φ , by measuring a sound speed and an attenuation rate of body tissues with the electronic stethoscope **2a**, the electronic stethoscope **2a** can doubly conduct percussion and palpation.

Also, as illustrated in FIG. **34**, when a film-shaped electro-mechanical converter **2b** according to the eighth embodiment is deformed into bowl-shape, it is possible to converge ultrasonic waves Φ transmitted from a measurement target **1b**. The scheme illustrated in FIG. **34** is a method referred as an immersion testing, which uses water as a contact medium and carries out an ultrasonic wave measurement, and the piezoelectric device is used to carry out the immersion testing. However, in the transmission/reception of aerial ultrasonic waves, because the reception sensitivity is low, the generation of strong ultrasonic waves is required, and the piezoelectric device is strongly resonated to generate the strong ultrasonic wave. However, with the piezoelectric device, the structure illustrated in FIG. **31** cannot be manufactured.

On the contrary, the film-shaped electro-mechanical converter **2b** according to the eighth embodiment can carry out the transmission/reception of aerial ultrasonic waves without using the resonance, because a high sensitivity is kept up to about 100 kHz.

Ninth Embodiment

As described in the explanation of the eighth embodiment, the film-shaped electro-mechanical converters according to the fifth to seventh embodiments can be used not only as microphones but also as acoustic probes (ultrasonic probes) even with the structures illustrated in FIGS. **20** and **32**, because the acoustic waves can be transmitted. However, because dielectric constant of the film-shaped electro-mechanical converters is lower than that of the piezoelectric device, as compared with the piezoelectric ultrasonic probe having the same area of the pressure receiving plane, the low capacitance of the film-shaped electro-mechanical converters becomes problematic.

In a film-shaped electro-mechanical converter according to a ninth embodiment of the present invention, in order to solve the problem associated with the low capacitance, as illustrated in FIG. **35**, a plurality of polymer films **13a**, **13b** are stacked to achieve a condenser microphone or an ultrasonic probe.

FIG. **35** illustrates a structure in which the main portion is substantially equal to the film-shaped electro-mechanical

converter according to the seventh embodiment, which has already been illustrated in FIG. 32. However, the first pressure receiving device M_1 formed on the common electrode $17c$ encompasses an upper vibrating plate (first vibrating plate) $15u$; an upper electret layer (first electret layer) $13a$ that faces the vibration surface of the upper vibrating plate (first vibrating plate) $15u$ through a gap space, the thickness of the gap space is measured in a stacked structure of a plurality of upper gap-insulating layers (first gap-insulating layers) $14a, 14b, 14c, \dots$; and a common electrode $17c$ in contact with the upper electret layer (first electret layer) $13a$ (the upper vibrating plate $15u$ contains an upper vibrating electrode $15b$ made of conductor and a vibrating-electrode-insulating film $15a$ at the bottom surface of the upper vibrating electrode $15b$, as illustrated in FIG. 32). The second pressure receiving device M_2 arranged under the common electrode $17c$ encompasses a lower vibrating plate (second vibrating plate) $15v$; a lower electret layer (second electret layer) $13b$ that faces the vibration surface of the lower vibrating plate (second vibrating plate) $15v$, through a gap space, the thickness of the gap space is measured in a stacked structure of a plurality of lower gap-insulating layers (second gap-insulating layers) $14p, 14q, 14r, \dots$; and the common electrode $17c$ in contact with the lower electret layer $13b$. In the first pressure receiving device M_1 and the second pressure receiving device M_2 , the common electrode $17c$ is used as the output terminal.

As illustrated in FIG. 35, the first polymer film $13a$ and the second polymer film $13b$ are bonded on and under the common electrode $17c$ for inputting/outputting the signal, while their polarities are opposite to each other. Moreover, the plurality of first gap-insulating layers $14a, 14b, 14c, \dots$, the plurality of second gap-insulating layers $14p, 14q, 14r, \dots$, the first vibrating plate $15u$ and the second vibrating plate $15v$ are stacked. Thus, as compared with the structure of the film-shaped electro-mechanical converter pertaining to the fifth embodiment illustrated in FIG. 20, it is possible to obtain a two-fold capacitance by the same pressure receiving plane.

When the piezoelectric ultrasonic probe for the aerial ultrasonic wave transmission/reception has a diameter of ten nanometers, the piezoelectric ultrasonic probe has a capacitance of about 2000 pF. On the contrary, in the structure illustrated in FIG. 35, when each thickness of the electrode layer and the films that implement the gap layer is assumed to be five micrometers and the thickness of the polymer film is assumed to be ten micrometers and the specific dielectric constant between the polymer film layer and the gap layer is three, the thickness of the film-shaped electro-mechanical converter according to the ninth embodiment illustrated in FIG. 35 is 70 micrometers and the capacitance is 200 pF.

Moreover, as illustrated in FIG. 36, when a plurality of polymer films $13a, 13b, 13c, 13d, \dots$ are stacked and joined corresponding to the number of the necessary units ($=n$: n is integer of two or more), the capacitance can be largely increased. In FIG. 36, a third pressure receiving device M_3 and a fourth pressure receiving device M_4 , are stacked under the stacked structure of the first pressure receiving device M_1 and the second pressure receiving device M_2 illustrated in FIG. 36.

That is, in FIG. 36, the first pressure receiving device M_1 disposed on a first common electrode $17c$ encompasses a first vibrating plate $15u$; a first polymer film $13a$ that faces the vibration surface of the first vibrating plate $15u$, through a gap space, the thickness of the gap space is measured in a stacked structure of a plurality of first gap-insulating layers $14a, 14b, 14c, \dots$; and the first common electrode $17c$ serves as the back electrode in contact with the first polymer film $13a$. The second pressure receiving device M_2 arranged under the first

common electrode $17c$ encompasses a vibrating plate (second common electrode) $15v$; a second polymer film $13b$ that faces the vibration surface of the vibrating plate (second common electrode) $15v$, through a gap space, the thickness of the gap space is measured in a stacked structure of a plurality of second gap-insulating layers $14p, 14q, 14r, \dots$; and the first common electrode $17c$ serves as the back electrode in contact with the second polymer film $13b$. In the first pressure receiving device M_1 and the second pressure receiving device M_2 , the first common electrode $17c$ is used as the output terminal.

Under the second pressure receiving device M_2 , the third pressure receiving device M_3 is arranged, the third pressure receiving device M_3 encompasses a second common electrode film $15v$ serving as the vibrating electrode; a third polymer film $13c$ that faces the vibration surface of the second common electrode film $15v$, through a gap space, the thickness of the gap space is measured in a stacked structure of a plurality of third gap-insulating layers $14s, 14t, 14u, \dots$; and a third common electrode film $17d$ serving as the back electrode in contact with the third polymer film $13c$. The fourth pressure receiving device M_4 , arranged under the third common electrode film $17d$, encompasses a vibrating plate (fourth common electrode) $15w$; a fourth polymer film $13d$ that faces the vibration surface of the vibrating plate (fourth common electrode) $15w$, through a gap space, the thickness of the gap space is measured in a stacked structure of a plurality of fourth gap-insulating layers $14v, 14w, 14x, \dots$; and the third common electrode film $17d$ serves as the back electrode in contact with the fourth polymer film $13d$. In the third pressure receiving device M_3 and the fourth pressure receiving device M_4 , the third common electrode film $17d$ is used as the common output terminal.

In this way, in FIG. 36, the plurality of polymer films $13a, 13b, 13c, 13d, \dots$ are stacked, with the unit number $n=10$, so that the same capacitance as the piezoelectric ultrasonic probe can be achieved. While, the piezoelectric ultrasonic probe for the aerial ultrasonic wave reception is accommodated in a protecting receptacle, and generally, the thickness of the piezoelectric ultrasonic probe is about 10 millimeters. Meanwhile, in the film-shaped electro-mechanical converter according to the ninth embodiment, even if the plurality of polymer films $13a, 13b, 13c, 13d, \dots$ are stacked with the unit number $n=10$, the entire thickness is about 700 micrometers. Thus, it is possible to obtain the film-shaped electro-mechanical converter that is extremely thin. Also, as described in the fifth embodiment by using Eq. (8) and the like, the film-shaped electro-mechanical converter according to the ninth embodiment has the high reception sensitivity and the wide band.

Tenth Embodiment

As described in the fifth embodiment, when the area of the pressure receiving plane of the film-shaped electro-mechanical converter pertaining to the fifth embodiment is excessively small, the capacitance is insufficient, which results in the reduction in sensitivity. Although the area of the pressure receiving plane depends on the gap thickness, the thickness of the polymer film and the dielectric constant, at least 1 mm^2 or more is required for the area of the pressure receiving plane. Meanwhile, when the area of the pressure receiving plane is excessively large, the gap-insulating layers $14a, 14b, 14c, \dots$ are fluctuated by the sound, and the variation in the output is consequently increased. Moreover, since the displacements of the laminated gap-insulating layers $14a, 14b, 14c, \dots$ are increased, air gap widths between the gap-insulating layers $14a, 14b, 14c, \dots$ increases, which brings

about the generation of the discharge, and the sensitivity is deteriorated. Although the area of the pressure receiving plane depends on the thicknesses of the gap-insulating layers **14a**, **14b**, **14c**, . . . and the frequency band of the sound to be measured, the area of the pressure receiving plane is preferred to be at least 100 cm² or less. However, as indicated in a film-shaped electro-mechanical converter according to a tenth embodiment illustrated in FIG. 37, when a sensing area in the film-shaped electro-mechanical converter is divided into many elements M_{ij-1} , M_{ij} , M_{ij+1} , . . . ($i=1$ to m ; $j=1$ to n : each of the m and the n is positive integer of two or more) and the portions between the elements M_{ij-1} , M_{ij} , M_{ij+1} , . . . are joined so that the films are not displaced, as far as the area of each one of pressure receiving planes of the respective elements M_{ij-1} , M_{ij} , M_{ij+1} , . . . is limited to be within the above range, an upper limit of the entire area of the film-shaped electro-mechanical converter is not limited to the foregoing values.

As indicated in FIG. 37, the film-shaped electro-mechanical converter according to the tenth embodiment of the present invention encompasses a vibrating plate **15m** having a flat vibration surface under no load condition; a polymer film **13m** which is defined by a flat first principal surface facing to the vibration surface of the vibrating plate **15m**, through a gap space, the thickness of the gap space is measured in a stacked structure implemented by a gap-insulating layer **141** of the first level layer, a gap-insulating layer **142** of the second level layer and a gap-insulating layer **143** of the third level layer, and a second principal surface facing in parallel to the first principal surface, the polarization directions are aligned in the polymer film **13m**; and a back electrode **17m** in contact with the second principal surface of the polymer film **13m**. On the vibrating plate **15m**, a vibrating-plate-protection film **34** is laminated for protecting the vibrating plate **15m**. Each thickness of the gap-insulating layer **141** of the first level layer, the gap-insulating layer **142** of the second level layer, the gap-insulating layer **143** of the third level layer and the polymer film **13m** is elected to be about one micrometer to 50 micrometers, preferably about one micrometer to 25 micrometers, more preferably about five micrometers to 25 micrometers.

When focusing to a central element M_{ij} in FIG. 37 and describing only the central element M_{ij} , in the element M_{ij} implementing the film-shaped electro-mechanical converter according to the tenth embodiment of the present invention, first spacers (illustration is omitted) implemented by particles of insulators having a particle diameter between ten nanometers and 40 micrometers are inserted between a gap-insulating layer **141_{ij}** of the first level layer and the polymer film **13m**, and the second spacers (illustration is omitted) implemented by particles of insulators having a particle diameter between ten nanometers and 40 micrometers are inserted between the gap-insulating layer **141_{ij}** of the first level layer and a gap-insulating layer **142_{ij}** of the second level layer, and the third spacers (illustration is omitted) implemented by particles of insulators having a particle diameter between ten nanometers and 40 micrometers are inserted between the gap-insulating layer **142_{ij}** of the second level layer and a gap-insulating layer **143_{ij}** of the third level layer, and the interval of the gap defined between the vibrating plate **15m** and the polymer film **13m** is controlled. The gap-insulating layer **143_{ij}** of the third level layer and the vibrating plate **15m** are tightly joined, and the gap-insulating layer **143_{ij}** of the third level layer carries out the function equivalent to that of the vibrating-electrode-insulating film of the film-shaped electro-mechanical converter pertaining to the fifth embodiment. In this way, between the vibrating plate **15m** and the

polymer film **13m**, the plurality of gap-insulating layers **141_{ij}**, **142_{ij}**, **143_{ij}**, . . . are laminated and inserted through the spacers (illustration is omitted) implemented by particles of insulators, each having the particle diameter between ten nanometers and 40 micrometers. Consequently, the microgaps are defined between the gap-insulating layer **143_{ij}** of the third level layer and the gap-insulating layer **142_{ij}** of the second level layer, between the gap-insulating layer **142_{ij}** of the second level layer and the gap-insulating layer **141_{ij}** of the first level layer, and between the gap-insulating layer **141_{ij}** of the first level layer and the polymer film **13m**, respectively, and the respective intervals in the elements M_{ij} are controlled.

When each diameter of the particles serving as the first to third spacers is elected to be 100 micrometers or less, the effective surface roughness Ra_{eff} of the surfaces establishing each of the microgaps can be $1/10$ or less of the gap width of the element-install cavity, which is defined for each of elements, between the bottom surface of the gap-insulating layer **143_{ij}** of the third level layer and the top surface of the polymer film **13m** (the effective surface roughness Ra_{eff} includes the bending under a loaded condition). However, in order to achieve the film-shaped electro-mechanical converter that is flexible and has a high degree of freedom in geometrical deformations, the diameter of the particles serving as each of the first to third spacers is elected to be ten nanometers to ten micrometers, which is preferable because the entire thickness becomes further thin. Moreover, in the range between ten nanometers and five micrometers, the particle diameter closer to ten nanometers is naturally desirable. The back electrode **17m** and the polymer film **13m** may be metallurgically joined or may be adhered by adhesive agent and the like, or alternatively, may be merely brought into contact by the mechanical pressure.

A spacer film **31** made of insulating material is bonded to at the bottom surface of the polymer film **13m**, a conductive (metallic) shielding-conductor film **32** is laminated at the bottom surface of the spacer film **31**, and a shielding-conductor-protection film **33** is laminated at the bottom surface of the shielding-conductor film **32**. The shielding-conductor-protection film **33** and the shielding-conductor film **32** implement a shield plate. Each thickness of the spacer film **31** and the shielding-conductor-protection film **33** can be elected to be a value of about five to 150 micrometers, preferably about 50 to 100 micrometers. As indicated in the vicinity of the left end, below the back electrode **17m** in FIG. 37, an amplifying circuit **19** is accommodated in a hollow cavity formed in a part of the spacer film **31**. The amplifying circuit **19** is installed (mounted) on the circuit board **18**, in the vicinity of the left end of the back electrode **17m**. On the circuit board **18**, a through hole (via) is made, and through the through hole (via), the amplifying circuit **19** is electrically connected to the back electrode **17m**, through a solder that is fused and connected to the vicinity of the left end of the back electrode **17m**. Although the illustration is omitted, a ground wiring from the amplifying circuit **19** is connected to the shielding-conductor film **32** through solder. In the film-shaped electro-mechanical converter for transmitter, the amplifying circuit **19** amplifies the input electric signal and applies across the vibrating plate **15m** and the back electrode **17m**. Meanwhile, in the film-shaped electro-mechanical converter for receiver, the amplifying circuit **19** amplifies and measures the charges induced in association with the displacement of the vibrating plate **15m**, between the vibrating plate **15m** and the back electrode **17m**. In the film-shaped electro-mechanical converter for transmitter, the vibrating plate **15m** is vibrated by supplying the electric signal, through the amplifying circuit **19**, across the vibrating plate **15m** and the back electrode **17m**. Mean-

while, in the film-shaped electro-mechanical converter for receiver, the vibrating plate **15m** is vibrated by the reception of the acoustic wave from the outside.

For example, in FIG. **37**, a PVC film with a thickness of 100 micrometers can be used as the vibrating-plate-protection film **34**, and an Al film with a thickness of ten micrometers can be used as each of the vibrating plate **15m**, the back electrode **17m** and the shielding-conductor film **32**, and a PTFE film with a thickness of 50 micrometers can be used as the spacer film **31**, and a PFA film with a thickness of ten micrometers can be used as the polymer film **13m**, and three PFA films each having a thickness of five micrometers can be used as the gap-insulating layer **141** of the first level layer, the gap-insulating layer **142** of the second level layer, and the gap-insulating layer **143** of the third level layer, respectively. When the vibrating plate **15m** is an Al film, which is deposited on the gap-insulating layer **143** of the third level layer, the vibrating plate **15m** and the gap-insulating layer **143** of the third level layer are tightly joined. Similarly, when the back electrode **17m** is an Al film, which is deposited on the polymer film **13m**, the polymer film **13m** and the back electrode **17m** are tightly joined. When the shielding-conductor film **32** is an Al film, which is deposited on the spacer film **31**, the spacer film **31** and the shielding-conductor film **32** are tightly joined.

In the film-shaped electro-mechanical converter according to the tenth embodiment illustrated in FIG. **37**, a portion between the element M_{ij-1} and the element M_b and a portion between the element M_b and the element M_{ij+1} are tightly joined by a thermal compression bonding and the like. Thus, they are thinner in thickness than the portions of the elements M_{ij-1} , M_{ij} and M_{ij+1} In the polymer film **13m**, above the regions corresponding to the elements M_{ij-1} , M_{ij} and M_{ij+1} , . . . , corona discharges resulting from needle electrodes are generated respectively, thereby electrifying the polymer film **13m**, and electret regions are formed in the elements M_{ij-1} , M_{ij} and M_{ij+1} respectively.

Also, in the configuration of the film-shaped electro-mechanical converter according to the tenth embodiment, it is possible to use ferroelectric material such as PZT, LiNbO_3 as the polymer film **13m** of the elements M_{ij-1} , M_{ij} and M_{ij+1} , However, in using the ferroelectric material, since the flexibility is decreased, the deformation is possible only between the elements, such as between the element M_{ij-1} and the element M_{ij} , between the element M_{ij} and the element M_{ij+1} , and the like.

Eleventh Embodiment

As illustrated in FIGS. **38** to **40**, when a pattern in which L-shaped empty areas are arrayed in a shape of a matrix is delineated on each of inner electrode films **17n** for delivering signals and outer electrode films **15p**, **15q** serving as shields, element isolation regions J_{rs-1} , J_{rs} , J_{rs+1} , . . . (each of the r and the s is integer determined by a wiring topology) are formed between the two-dimensionally arranged elements M_{ij-1} , M_{ij} , M_{ij+1} As illustrated in FIG. **40**, between the pattern of the inner electrode films **17n** and the patterns of the outer electrode films **15p**, **15q**, the directions and positions of the L-shaped empty areas differ from each other. However, the amplifying circuit **19** is connected to the inner electrode films **17n** for delivering the signal, and the outer electrode films **15p**, **15q** serving as the shields are grounded.

With the arrangement of the element isolation regions J_{rs-1} , J_{rs} , J_{rs+1} , . . . , the stray capacitance between the metallic wirings arrayed in a vertical direction can be decreased in each of the elements M_{ij-1} , M_{ij} , M_{ij+1} . . . , when the thin films are laminated. Also, at the locations of the element isolation

regions J_{rs-1} , J_{rs} , J_{rs+1} , . . . , where each of the element isolation regions J_{rs-1} , J_{rs} , J_{rs+1} , . . . is only implemented by the plurality of polymer films, it becomes easy to join the plurality of thin films which implement each of the elements M_{ij-1} , M_{ij} , M_{ij+1} . . . into the stacked structures, respectively.

FIG. **39** is a sectional view taken from A-A direction and illustrates the elements M_{21} , M_{22} , M_{23} , as an example, and the element isolation region J_{11} implemented only by polymer films on the left side of the element M_{21} , the element isolation region J_{32} implemented only by polymer films between the element M_{21} and the element M_{22} , the element isolation region J_{34} implemented only by polymer films between the element M_{22} and the element M_{23} , and the element isolation region J_{36} implemented only by polymer films on the right side of the element M_{23} can be tightly joined by the thermal press bonding and the like. Thus, the element isolation regions J_{rs-1} , J_{rs} , J_{rs+1} , . . . are thinner in thickness than the portions of the elements M_{21} , M_{22} , M_{23} ,

As shown in the sectional view in FIG. **39**, in the film-shaped electro-mechanical converter according to the eleventh embodiment of the present invention, the structure of each of the elements M_{21} , M_{22} , M_{23} , is similar to that of the film-shaped electro-mechanical converter according to the seventh embodiment illustrated in FIG. **32** or the film-shaped electro-mechanical converter according to the ninth embodiment illustrated in FIG. **35**. Then, an upper element of each of the elements M_{ij-1} , M_{ij} , M_{ij+1} , . . . disposed on inner electrode films **17n** serving as a common back electrode encompasses an upper vibrating plate **15p** having a flat vibration surface under no load condition; an upper polymer film **13p** which is defined by a flat first principal surface facing to the vibration surface of the upper vibrating plate **15p**, through a gap space, the thickness of the gap space is measured in a stacked structure implemented by an upper insulating layer **141p** of the first level layer, an upper gap-insulating layer **142p** of the second level layer and an upper gap-insulating layer **143p** of the third level layer, and the second principal surface facing in parallel to the first principal surface, the polarization directions are aligned in the upper polymer film **13p**; and the inner electrode films **17n** serves as the back electrode in contact with the second principal surface of the upper polymer film **13p**. An upper vibrating-plate-protection film **34p** for protecting the upper vibrating plate **15p** is laminated on the upper vibrating plate **15p**.

Meanwhile, a lower element of each of the elements M_{21} , M_{22} , M_{23} , . . . arranged under the inner electrode films **17n** encompasses a lower vibrating plate **15q** having a flat vibration surface under no load condition; a lower polymer film **13q** which is defined by a flat first principal surface facing to the vibration surface of the lower vibrating plate **15q**, through a gap space, the thickness of the gap space is measured in a stacked structure implemented by a lower insulating layer **141q** of the first level layer, a lower gap-insulating layer **142q** of the second level layer and a lower gap-insulating layer **143q** of the third level layer, and the second principal surface facing in parallel to the first principal surface, the polarization directions are aligned in the lower polymer film **13q**, and the inner electrode films **17n** serves as the back electrode in contact with the second principal surface of the lower polymer film **13q**. A lower vibrating-plate-protection film **34q** for protecting a lower vibrating plate **15q** is laminated under the lower vibrating plate **15q**. Each thickness of the upper gap-insulating layer **141p** of the first level layer, the upper gap-insulating layer **142p** of the second level layer, the upper gap-insulating layer **143p** of the third level layer and the upper polymer film **13p** may be set to about one micrometer to 50 micrometers, preferably about one micrometer to 25

micrometers, more preferably five micrometers to 25 micrometers. Each thickness of the lower gap-insulating layer **141q** of the first level layer, the lower gap-insulating layer **142q** of the second level layer, the lower gap-insulating layer **143q** of the third level layer and the lower polymer film **13q** may be set to about one micrometer to 50 micrometers, preferably about one micrometer to 25 micrometers, more preferably five micrometers to 25 micrometers.

Focusing to the central element M_{22} in FIG. 37 and describing the element M_{22} , in the element M_{22} implementing the film-shaped electro-mechanical converter according to the eleventh embodiment of the present invention, first spacers (illustration is omitted) implemented by particles of insulators having a particle diameter between ten nanometers and 40 micrometers are inserted between an upper gap-insulating layer **141p₂₂** of the first level layer and the upper polymer film **13p**, and second spacers (illustration is omitted) implemented by particles of insulators having a particle diameter between ten nanometers and 40 micrometers are inserted between an upper gap-insulating layer **141p₂₂** (having the relation similar to FIG. 37, although the suffix **22** indicating the inner structure of the element M_{22} , in FIG. 39) of the first level layer and an upper gap-insulating layer **142p₂₂** of the second level layer, and third spacers (illustration is omitted) implemented by particles of insulators having a particle diameter between ten nanometers and 40 micrometers are inserted between an upper gap-insulating layer **142p₂₂** of the second level layer and an upper gap-insulating layer **143p₂₂** of the third level layer, and interval of the gap defined between the upper vibrating plate **15p** and the upper polymer film **13m** is controlled. The upper gap-insulating layer **143p₂₂** of the third level layer and the upper vibrating plate **15p** are tightly joined, and the upper gap-insulating layer **143p₂₂** of the third level layer carries out the function equivalent to that of the vibrating-electrode-insulating film of the film-shaped electro-mechanical converter pertaining to the fifth embodiment. In this way, between the upper vibrating plate **15p** and the upper polymer film **13p**, the plurality of upper gap-insulating layers **141p₂₂**, **144p₂₂**, **143p₂₂**, are laminated and inserted through the spacers (illustration is omitted) implemented by particles of insulators each having the particle diameter between ten nanometers and 40 micrometers. Consequently, the microgaps are defined between the upper gap-insulating layer **143p₂₂** of the third level layer and the upper gap-insulating layer **142p₂₂** of the second level layer, between the upper gap-insulating layer **142p₂₂** of the second level layer and the upper gap-insulating layer **141p₂₂** of the first level layer, and between the upper gap-insulating layer **141p₂₂** of the first level layer and the upper polymer film **13p**, respectively, and respective intervals in the elements M_{22} are controlled.

When each diameter of the particles serving as the first to third spacers is elected to be 100 micrometers or less, the effective surface roughness Ra_{eff} of the surfaces establishing each of the microgaps can be $1/10$ or less of the gap width of the element-install cavity, which is defined for each element, between the bottom surface of the upper gap-insulating layer **143p₂₂** of the third level layer and top surface of the upper polymer film **13p** (the effective surface roughness Ra_{eff} includes the bending under a loaded condition). However, in order to achieve the film-shaped electro-mechanical converter that is flexible and has a high degree of freedom in geometrical deformations, the diameter of the particles serving as each of the first to third spacers is elected to be ten nanometers to ten micrometers, which is preferable because the entire thickness becomes further thin. Moreover, in the range between ten nanometers and five micrometers, the particle diameter closer to ten nanometers is naturally desirable.

Similarly, first spacers (illustration is omitted) implemented by particles of insulators having a particle diameter between ten nanometers and 40 micrometers are inserted between the lower gap-insulating layer **141q₂₂** of the first level layer and the lower polymer film **13q**, second spacers (illustration is omitted) implemented by particles of insulators having a particle diameter between ten nanometers and 40 micrometers are inserted between the lower gap-insulating layer **141q₂₂** of the first level layer and the lower gap-insulating layer **142q₂₂** of the second level layer, and third spacers (illustration is omitted) implemented by particles of insulators having a particle diameter between ten nanometers and 40 micrometers are inserted between the lower gap-insulating layer **142q₂₂** of the second level layer and the lower gap-insulating layer **143q₂₂** of the third level layer, and the interval of the gap defined between the lower vibrating plate **15q** and the lower polymer film **13q** is controlled. The lower gap-insulating layer **143q₂₂** of the third level layer and the lower vibrating plate **15q** are tightly joined, and the lower gap-insulating layer **143q₂₂** of the third level layer carries out the function equivalent to that of the vibrating-electrode-insulating film of the film-shaped electro-mechanical converter pertaining to the fifth embodiment. In this way, between the lower vibrating plate **15q** and the lower polymer film **13q**, the plurality of lower gap-insulating layers **141q₂₂**, **142q₂₂**, **143q₂₂**, . . . are laminated and inserted through the spacers (illustration is omitted) implemented by particles of insulators each having the particle diameter between ten nanometers and 40 micrometers. Consequently, the microgaps are defined between the lower gap-insulating layer **143q₂₂** of the third level layer and the lower gap-insulating layer **142q₂₂** of the second level layer, between the lower gap-insulating layer **142q₂₂** of the second level layer and the lower gap-insulating layer **141q₂₂** of the first level layer, and between the lower gap-insulating layer **141q₂₂** of the first level layer and the upper polymer film **13q**, respectively, and respective intervals in the element M_{22} are controlled.

When each diameter of the particles serving as the first to third spacers is elected to be 100 micrometers or less, the effective surface roughness Ra_{eff} of the surfaces establishing each of the microgaps can be $1/10$ or less of the gap width of the element-install cavity, which is defined for each element, between the bottom surface of the lower polymer film **13q** and top surface of the lower gap-insulating layer **143q₂₂** of the third level layer (the effective surface roughness Ra_{eff} includes the bending under a loaded condition). However, in order to achieve the film-shaped electro-mechanical converter that is flexible and has a high degree of freedom in geometrical deformations, the diameter of the particles serving as each of the first to third spacers is elected to be ten nanometers to ten micrometers, which is preferable because the entire thickness becomes further thin. Moreover, in the range between ten nanometers and five micrometers, the particle diameter closer to ten nanometers is naturally desirable. The inner electrode films **17n** and the upper polymer film **13p**, or the inner electrode films **17n** and the lower polymer film **13q** may be metallurgically joined or may be adhered by adhesive agent and the like, or alternatively, may be merely brought into contact by the mechanical pressure.

In the film-shaped electro-mechanical converter according to the eleventh embodiment, when the film-shaped electro-mechanical converter is used in a flat surface state without any deformation, there is no fear that the film implementing the film-shaped electro-mechanical converter is displaced. For this reason, the joining of the elements M_{22-1} , M_{22} , M_{22+1} , . . . can be omitted, and in the element isolation regions J_{rs-1} , J_{rs} , J_{rs+1} , . . . implemented by only the polymer films, the

films can be adsorbed only by the electrostatic force between the polymer films **13p**, **13q**, and can be used.

The film-shaped electro-mechanical converter according to the eleventh embodiment illustrated in FIGS. **38** to **40** can be operated as a single film-shaped electro-mechanical converter, even if a part of the film-shaped electro-mechanical converter is cut, when the respective electrode layers **15p**, **15q** and **17n** of the elements M_{22-1} , M_{22} , M_{22+1} are electrically connected in any topology in a two-dimensional direction, respectively. Thus, after the film-shaped electro-mechanical converter film that has the structure illustrated in FIGS. **38** to **40** and has a large area is manufactured, it is possible to change the planer shape by cutting a selected portion between the elements, as illustrated in FIG. **41(a)**, in view of the status of use (the shape of target to be measured). Then, when the film-shaped electro-mechanical converter film is attached to a service allocation (target to be measured), by sealing the cutting edge with an insulating adhesive agent **51** as illustrated in FIG. **41(b)**, the film-shaped electro-mechanical converter film can be delineated to any planer shape corresponding to the shape of the target to be measured, and can be used as the film-shaped electro-mechanical converter.

Twelfth Embodiment

When the inner electrode films **17n** of the elements M_{ij-1} , M_{ij} , M_{ij+1} , that are two-dimensionally arrayed as illustrated in FIG. **38** to FIG. **40** are divided for facilitating random access, and a large number of separated film-shaped electro-mechanical converters are integrated, it is possible to produce the film-shaped electro-mechanical converter as a two-dimensional sensor (acoustic image sensor) that can measure a sound-pressure distribution.

In a film-shaped electro-mechanical converter (acoustic image sensor) according to a twelfth embodiment of the present invention, as illustrated in FIG. **42**, a sensor array area **71** and peripheral circuit portions (**72**, **73**, **74**, **75** and **77**) are integrated on the same polymer film. In the sensor array area **71**, many elements X_{ij} ($i=1$ to m ; $j=1$ to n : each of the m and n is integer) are arrayed in a shape of a two-dimensional matrix and implement a rectangular sound-pressure distribution measurement area. Then, the vertical shift register (vertical scanner) **73** is merged through the timing generator **74** on the left side of the sensor array area **71**, and horizontal shift register (horizontal scanner) **72** is merged on the lower side, and a bias-voltage generator **77** is merged on the lower right side of the sensor array area **71**. In FIG. **42**, its inner structure is exemplified only in the elements X_{ij} on an i -th row and j -th column. However, the elements X_{11} to X_{1m} ; X_{21} to X_{2m} ; \dots ; X_{i1} to X_{im} ; \dots ; X_{n1} to X_{nm} contain sound pressure detecting devices D_{11} to D_{1m} ; D_{21} to D_{2m} ; \dots ; D_{i1} to D_{im} ; \dots ; D_{n1} to D_{nm} and amplifiers (charge reading buffer amplifiers) A_{11} to A_{1m} ; A_{21} to A_{2m} ; \dots ; A_{i1} to A_{im} ; \dots ; A_{n1} to A_{nm} , respectively, similarly to the elements X_{ij} on the i -th row and j -th column. As illustrated in FIG. **43**, the sound pressure detecting device D_{ij} ($i=1$ to m ; $j=1$ to n : each of the m and n is integer) encompasses a vibrating plate **15m**; a polymer film **13m** which is defined by a flat first principal surface facing to the vibration surface of the vibrating plate **15m**, through a gap space, the thickness of the gap space is measured in a stacked structure implemented by a gap-insulating layer **141** of the first level layer, a gap-insulating layer **142** of the second level layer and a gap-insulating layer **143** of the third level layer, and a second principal surface facing in parallel to the first principal surface, the polarization directions are aligned in the polymer film **13m**; and back electrodes 17_{ij-1} , 17_{ij} , 17_{ij+1} , which are individually arranged correspondingly to the array

of the X_{ij-1} , X_{ij} , X_{ij+1} , on the second principal surface of the polymer film **13m**. A vibrating-plate-protection film **34** for protecting the vibrating plate **15m** is laminated on the vibrating plate **15m**.

As illustrated in FIG. **42**, the elements X_{ij} in the inside of the sensor array area **71** are sequentially scanned by the vertical shift register (vertical scanner) **73** driven by the timing generator **74**, and horizontal shift register (horizontal scanner) **72** driven by the timing generator **74**, and reading out operation of element signals is executed. That is, the film-shaped electro-mechanical converter according to the twelfth embodiment of the present invention is designed such that the sensor array area **71** is vertically scanned at the units of the respective element rows X_{11} to X_{1m} ; X_{21} to X_{2m} ; \dots ; X_{i1} to X_{im} ; \dots ; X_{n1} to X_{nm} , and element signals of the respective element rows X_{11} to X_{1m} ; X_{21} to X_{2m} ; \dots ; X_{i1} to X_{im} ; \dots ; X_{n1} to X_{nm} are consequently read out by vertical signal lines B_{j-1} , B_j , B_{j+1} , \dots , which are provided on each of the element columns X_{11} to X_{n1} ; X_{12} to X_{n2} ; \dots ; X_{1j} to X_{nj} ; \dots ; X_{1m} to X_{nm} , respectively (for simplicity, FIG. **42** illustrates only a vertical signal line **A** on the j -th column of the sensor array area **71** and the others are omitted).

As illustrated in FIG. **42**, a constant current transistor T_{LNj} serving as a common load is connected to the vertical signal line B_j on the j -th column of the sensor array area **71**. For example, a source follower circuit is implemented by an amplifier A_{ij} on the i th row j -th column and the constant current transistor T_{LNj} , and an output V_{outj} of the source follower circuit is read out to a column processing circuit on the j -th column. Although the illustration is omitted, other constant current transistors T_{LN1} , T_{LN2} , \dots , T_{LNj-1} , T_{LNj+1} , \dots , T_{LNm} serving as the common loads are similarly connected to the vertical signal lines B_1 , B_2 , \dots , B_{j-1} , B_{j+1} , \dots , B_m on the other columns, respectively, and the source follower circuits are constituted. Then, the outputs V_{out1} , V_{out2} , \dots , V_{outj-1} , V_{outj+1} , \dots , V_{outm} of the source follower circuits are read out to the column processing circuits on the respective columns.

So as to read out the signals from the respective elements X_{11} to X_{1m} ; X_{21} to X_{2m} ; \dots ; X_{i1} to X_{im} ; \dots ; X_{n1} to X_{nm} , a signal processing circuit **75** is merged on the lower stage (output side) of the sensor array area **71**. The element signals of the element column X_{11} to X_{n1} , which are read out through the vertical signal lines B_1 from the sensor array area **71**, are sequentially supplied to the column processing circuit on the first column in the signal processing circuit **75**, and a signal process is performed by the column processing circuit. Similarly, the element signals of the element column X_{12} to X_{n2} are sequentially supplied to the column processing circuit on the second ID column in the signal processing circuit **75**, and a process for removing noises unique to the element is performed by the column processing circuit. The element signals of the element column X_{1m} to X_{nm} are sequentially supplied to the column processing circuit on the j -th column in the signal processing circuit **75**, and signal process is performed by the column processing circuit. Also, the element signals of the element column X_{1m} to X_{nm} are sequentially supplied to the column processing circuit on the m -th column in the signal processing circuit **75**, and signal process is performed by the column processing circuit.

In FIG. **43**, focusing to the central element X_{ij} (sound pressure detecting device D_{ij}), and explaining a cross section structure, in the sound pressure detecting device D_{ij} implementing the film-shaped electro-mechanical converter (acoustic image sensor) according to the twelfth embodiment of the present invention, first spacers (illustration is omitted) implemented by particles of insulators having a particle diameter between ten nanometers and 40 micrometers are

inserted between a gap-insulating layer 141_{ij} of the first level layer and a polymer film $13m$, and second spacers (illustration is omitted) implemented by particles of insulators having a particle diameter between ten nanometers and 40 micrometers are inserted between the gap-insulating layer 141_{ij} of the first level layer and a gap-insulating layer 142_{ij} of the second level layer, and third spacers (illustration is omitted) implemented by particles of insulators having a particle diameter between ten nanometers and 40 micrometers are inserted between the gap-insulating layer 142_{ij} of the second level layer and a gap-insulating layer 143_{ij} of the third level layer, and the interval of a gap defined between the vibrating electrode $15m$ and polymer film $13m$ is controlled. The gap-insulating layer 143_{ij} of the third level layer and vibrating electrode $15m$ are tightly joined, and the gap-insulating layer 143_{ij} of the third level layer carries out the function equivalent to that of the vibrating-electrode-insulating film of the film-shaped electro-mechanical converter (acoustic image sensor) according to the fifth embodiment. In this way, between the vibrating electrode $15m$ and the polymer film $13m$, the plurality of gap-insulating layers 141_{ij} , 142_{ij} , 143_{ij} , . . . are laminated and inserted through the spacers (illustration is omitted) implemented by particles of insulators each having the particle diameter between ten nanometers and 40 micrometers. Consequently, microgaps are defined between the gap-insulating layer 143_{ij} of the third level layer and the gap-insulating layer 142_{ij} of the second level layer, between the gap-insulating layer 142_{ij} of the second level layer and the gap-insulating layer 141_{ij} of the first level layer, and between the gap-insulating layer 141_{ij} of the first level layer and the polymer film $13m$, respectively, and respective intervals between the sound pressure detecting devices D_{ij} are controlled.

When each diameter of the particles serving as the first to third spacers is elected to be 100 micrometers or less, the effective surface roughness Ra_{eff} of the surfaces establishing each of the microgaps can be $1/10$ or less of a gap width of the element-install cavity, which is defined for each element, between the bottom surface of the gap-insulating layer 143_{ij} of the third level layer and top surface of the polymer film $13m$ (the effective surface roughness Ra_{eff} includes the bending under a loaded condition). However, in order to achieve the film-shaped electro-mechanical converter that is flexible and has a high degree of freedom in geometrical deformations, the diameter of the particles serving as each of the first to third spacers is elected to be ten nanometers to ten micrometers, which is preferable because the entire thickness becomes further thin. Moreover, in the range between ten nanometers and five micrometers, the particle diameter closer to ten nanometers is naturally desirable. Each of the back electrodes 17_{ij-1} , 17_{ij} , 17_{ij+1} , . . . arranged separately from each other and the polymer film $13m$ may be metallurgically joined or may be adhered by adhesive agent and the like, or alternatively, may be merely brought into contact by the mechanical pressure.

The spacer film 31 made of insulating material is bonded to at the bottom surface of the polymer film $13m$. Correspondingly to the array of the elements X_{ij-1} , X_{ij} , X_{ij+1} , . . . , hollow cavities are sequentially arranged in the spacer film 31 . Amplifiers (charge reading buffer amplifiers) A_{ij-1} , A_{ij} , A_{ij+1} , . . . are accommodated in the hollow cavities, respectively. The amplifiers A_{ij-1} , A_{ij} , A_{ij+1} , . . . are merged (mounted) on the circuit boards 18_{ij-1} , 18_{ij} , 18_{ij+1} , . . . joined (merged) at the bottom surfaces of the back electrodes 17_{ij-1} , 17_{ij} , 17_{ij+1} , . . . of the elements X_{ij-1} , X_{ij} , X_{ij+1} , . . . , respectively. The through holes (vias) are made in the circuit boards 18_{ij-1} , 18_{ij} , 18_{ij+1} , . . . , respectively. Through the respective

through holes (vias), the amplifiers A_{ij-1} , A_{ij} , A_{ij+1} , . . . are electrically connected to the back electrodes 17_{ij-1} , 17_{ij} , 17_{ij+1} , . . . through the connecting means such as solder balls that are fused ID and connected to the back electrodes 17_{ij-1} , 17_{ij} , 17_{ij+1} , . . . , independently of each other.

A conductive (metallic) shielding-conductor film 32 is laminated at the bottom surface of the spacer film 31 , and a shielding-conductor-protection film 33 is laminated at the bottom surface of the shielding-conductor film 32 . Through the shielding-conductor-protection film 33 , the vertical signal lines B_{j-1} , B_j , B_{j+1} , . . . run in a direction vertical to a plane of paper. The vertical signal lines B_{j-1} , B_j , B_{j+1} , are connected to the amplifiers 41 , A_{ij-1} , A_{ij} , A_{ij+1} , . . . , of the corresponding columns, respectively. So as to cover the vertical signal lines B_{j-1} , B_j , B_{j+1} , . . . an inter-layer insulation film 38 is laminated at the bottom surface of the shielding-conductor-protection film 33 . Through the inter-layer insulation film 38 , a reset signal wiring R_i is arranged orthogonally to the amplifiers A_{ij-1} , A_{ij} , A_{ij+1} , Although the illustration is omitted on the sectional view, a vertical selection signal wiring S_i runs orthogonally to the amplifiers A_{ij-1} , A_{ij} , A_{ij+1} , . . . at the deep rearward portion of the plane of paper (see FIG. 42). So as to cover the reset signal wiring R_i and a vertical selection signal lines S_i whose illustration is omitted, a passivation film 39 is laminated on the inter-layer insulation film 38 .

FIG. 44 illustrates an example of the amplifier A_{ij} arranged in the hollow cavity of the spacer film 31 , correspondingly to the array of the elements X_{ij-1} , X_{ij} , X_{ij+1} , As illustrated in FIG. 44, a gate electrode of a signal reading transistor (amplifying transistor) TA_{ij} and a source electrode of a reset transistor TR_{ij} are connected through the metallic wiring, which is fused with solder ball and the like, to the back electrode 17_{ij} . Each of a drain electrode of the reset transistor TR_{ij} and a drain electrode of the signal reading transistor (amplifying transistor) TA_{ij} is connected to a power supply V_{DD} . A source electrode of the signal reading transistor (amplifying transistor) TA_{ij} is connected to a drain electrode of a switching transistor TS_{ij} for an element selection. With respect to a reset gate electrode of the reset transistor TR_{ij} , a potential of the reset signal wiring R_i is set to a high (H) level ($R_i=“1”$), and charges accumulated in the back electrode 17_{ij} are discharged respectively, and charges accumulated in the back electrode 17_{ij} are reset. A source electrode of the switching transistor TS_{ij} for the element selection is connected to the vertical signal line B_j on j -th column. Selection signal is given to a gate electrode of the switching transistor TS_{ij} from the vertical shift register (vertical scanner) 73 , when driven by the signal timing generator 74 , through the vertical selection signal wiring S_i on the horizontal line of i -th row.

In the topology of the vertical signal line B_j illustrated in FIG. 44, a signal for setting the vertical selection signal wiring S_i on i -th row to the high level ($S_i=“1”$) is applied to the gate electrode of the switching transistor TS_{ij} for the element selection in the amplifier A_{ij} , and switching transistor TS_{ij} is turned on. Also, a constant voltage V_b is applied from the bias-voltage generator 77 to the gate electrode of the constant current transistor T_{LNj} . Consequently, the charges that are amplified by the signal reading transistor (amplifying transistor) TA_{ij} and accumulated in the back electrode 17_{ij} are read out as the output V_{outj} of the source follower circuit to outside the sensor array area 71 .

As illustrated in FIG. 43, when the amplifiers A_{ij-1} , A_{ij} , A_{ij+1} , . . . , are arranged under the independent elements X_{ij-1} , X_{ij} , X_{ij+1} , . . . and outputs are extracted, separate outputs from the sound pressure detecting devices D_{ij-1} , D_{ij} , D_{ij+1} , . . . in the respective elements X_{ij-1} , X_{ij} , X_{ij+1} , . . . can be obtained, thereby knowing the sound-pressure distribution.

Also, when the film-shaped electro-mechanical converter according to the twelfth embodiment is used as a pressure sensor, it is possible to measure a pressure fluctuation distribution of 10 Hz or more. The film-shaped electro-mechanical converter according to the twelfth embodiment becomes a helpful inspection tool, because the reflection and propagation of the vibrations can be made into a visible image, when the vibration characteristics of the target material having a material-quality distribution, for example, such as wood, are measured.

By the way, although the explanation of the twelfth embodiment exemplified the two-dimensional array (area sensor), in the two-dimensional matrix illustrated in FIG. 42, with $j=m=1$, a plurality of elements may be one-dimensionally arrayed, as easily understood from the content of the above disclosure.

Thirteenth Embodiment

As illustrated in FIG. 45(b), a microgap of a film-shaped electro-mechanical converter according to a thirteenth embodiment of the present invention is so established that a polymer film 61b (see FIG. 46) including a plurality of independent bubbles 62 is inserted into an element-install cavity defined between a vibrating electrode 15b and an electret layer 13.

Namely, as illustrated in FIG. 45, the film-shaped electro-mechanical converter according to the thirteenth embodiment of the present invention encompasses the vibrating electrode 15b; the electret layer 13 facing to the vibrating electrode 15b with an element-install cavity provided in between the vibrating electrode 15b and the electret layer 13; a back electrode 17 in contact with the bottom surface of the electret layer 13; an electret-insulating layer 64 laminated on the top surface of the electret layer 13; the polymer film 61b provided with the plurality of independent bubbles 62b that is provided between the vibrating-electrode-insulating film 15a and electret-insulating layer 64; and an amplifying circuit (semiconductor chip) 19 electrically connected between the vibrating electrode 15b and back electrode 17. The vibrating plate 15 has the flat vibration surface under no load condition. A plurality of protrusions 63 are provided at the top surface of the electret-insulating film 64. The polymer film 61b is laminated on the top surface of electret-insulating layer 64 through the plurality of protrusions 63. The interval between the plurality of protrusions 63 may be, for example, about one to three millimeters. Each height of the plurality of protrusions 63 may be, for example, five to 20 micrometers. Each curvature of the plurality of protrusions 63 may be, for example, about 15 to 35 millimeters. Alternatively, another polymer film 61a including independent bubbles 62a as illustrated in FIG. 47 may be inserted between the vibrating-electrode-insulating film 15a and electret-insulating layer 64.

As illustrated in FIG. 45, the polymer film 61b provided with the plurality of independent bubbles 62b is accommodated in the inside of a box-shaped inner insulation container (12b, 12d), and the vibrating plate 15 serves as the cover of the inner insulation container (12b, 12d), and the back electrode 17 serves as the bottom plate of the inner insulation container (12b, 12d). Moreover, the structure in which the polymer film 61b provided with the plurality of independent bubbles 62b, which is accommodated in the inside of the inner insulation container (12b, 12d), is further accommodated in the inside of an outer insulation container (12a, 12b, and 12c) together with the amplifying circuit 19, and the spacer film 12a made of insulating material can be used as a bottom plate of the outer insulation container (12a, 12b, and 12c). The vibrating

plate 15 serves as the cover of the outer insulation container (12a, 12b and 12c). A conductive (metallic) shielding-conductor film 11b is laminated on the bottom of the outer insulation container (12a, 12b and 12c), and a shielding-conductor-protection film 11a is laminated on the bottom of the shielding-conductor film 11b. The shielding-conductor-protection film 11a and the shielding-conductor film 11b implement a shield plate 11. Each thickness of the spacer film 12a and the shielding-conductor-protection film 11a can be set to the value of about five to 150 micrometers, preferably about 50 to 100 micrometers. The amplifying circuit 19 is merged (mounted) on a circuit board 18, in the vicinity of the left end of the back electrode 17. A through hole (via) is provided in the circuit board 18, and through the through hole (via), the amplifying circuit 19 is electrically connected to the back electrode 17 through a solder that is fused and connected to the vicinity of the left end of the back electrode 17. Although the illustration is omitted, a ground wiring being extended from the amplifying circuit 19 is connected to the shielding-conductor film 11b of the shield plate 11 through solder.

As for the sizes of the polymer films 61b, 61a, which are respectively provided with the plurality of independent bubbles 62b, 62a as illustrated in FIGS. 46 and 47, it is preferable to employ the dimension and topology that can establish air gaps separated at the length between ten nanometers and 40 micrometers in the direction of electric field E, similarly to the particle diameter of the particles and height of the protrusions. In particular, as for the configuration illustrated in FIG. 46, a PP film as the polymer film 61b is stretched so that independent bubbles 62b, having sizes in which the vertical direction as the direction of the electric field E is about one micrometer and horizontal direction is between about ten nanometers and 40 micrometers, are foamed, thereby producing a porous film. As far as air gaps that are separated at the length between ten nanometers and 40 micrometers in the direction of the electric field E can be established, it is allowable to use a topology such that the plurality of independent bubbles are mated together along the horizontal direction (the direction vertical to the electric field E from the electret) so as to establish a continuous space.

Usually, when a film is stacked on the protrusions 63 and the electrostatic force is applied to the film surface, the film will bent. However, as illustrated in FIGS. 46 and 47, in the porous substance such as the polymer films 61b, 61a provided with the many independent bubbles 62b, 62a, although planes in contact with the protrusions 63 is largely bent, the bending is absorbed in the inside of the polymer films 61b, 61a, and the other planes that are not in contact with the protrusions 63 are little bent. Using this phenomenon, the deformation of the microphone resulting from the protrusions 63 can be enlarged, while the central line average roughness Ra of the vibrating electrode 15b is being suppressed to be $1/10$ or less of the gap width defined between the bottom surface of the vibrating electrode 15b and top surface of the electret layer 13. The above porous substance provided with the plurality of independent bubbles 62b, 62a can be fabricated by adding a foaming agent to a thermo plastic such as polypropylene (PP) and the like, and thereafter, melting, foaming, and stretching the thermo plastic.

The manufacturing method of the film-shaped electro-mechanical converter according to the thirteenth embodiment is basically similar to the manufacturing method of the film-shaped electro-mechanical converter pertaining to the fifth embodiment illustrated in FIG. 23 to FIG. 28.

(a) At first, on a shielding-conductor-protection film 11a such as PVC film and the like, an aluminum (Al) film serving as a shielding-conductor film 11b is deposited so as to imple-

ment a shield plate **11**. The shield plate **11** is bonded to the rear surface of a spacer film **12a** made of insulating material. Moreover, after the Al film is bonded to the top surface of the spacer film **12a**, the Al film is delineated so as to form a back electrode **17**. On a part of the back electrode **17**, a shallow groove **17g** is cut as illustrated in FIG. **23**. Then, as illustrated in FIG. **23**, a PTFE film with a thickness of 25 micrometers is bonded to a part of the back electrode **17**. After the PTFE film is bonded to the back electrode **17**, as illustrated in FIG. **24**, the PTFE film is electrified by corona discharge.

(b) Then, as illustrated in FIG. **25**, while the spacer film **12a** made of insulating material can be used as the bottom plate, the side-wall films **12b**, **12d** serving as the side-plate blocks of a box are arranged around the PTFE film, and a box-shaped insulation container (**12a**, **12b**, **12d** and **12e**) is assembled. At this time, the insulating layer **12d** attached with a canopy top **12e** is fitted into the shallow groove **17g** formed in a part of the back electrode **17**.

(c) In the inside of the box-shaped insulation container (**12a**, **12b**, **12d** and **12e**), another PTFE film with a thickness of 25 micrometers is laminated as the electret-insulating layer **64** on the electret layer **13**. Then, the plurality of protrusions **63** implemented by particles made of boron nitride are formed on the top surface of the electret-insulating layer **64** by spray coating. The interval between the plurality of protrusions **63** may be set to, for example, about two millimeters, each height of the plurality of protrusions **63** may be set to, for example, about ten micrometers, and each curvature of the plurality of protrusions **63** may be set to, for example, about 25 millimeters. Then, similarly to the configuration illustrated in FIG. **26**, a stacked structure in which a PTFE film **61b** having a thickness of about 50 micrometers is stacked is accommodated via the plurality of protrusions **63** on the electret-insulating layer **64**.

(d) Meanwhile, on the PFA film as the vibrating-electrode-insulating film **15a**, an Al film as a vibrating electrode **15b** is deposited so as to form a vibrating plate **15**. Moreover, on the vibrating electrode **15b**, a vibrating-plate-protection film **16** made of a PVC film is bonded as the top cover of the Insulation container (**12a**, **12b**, **12d** and **12e**), similarly to the configuration illustrated in FIG. **27**.

(e) Separately, such as ball grid array and the like, on a circuit board **18** that has connectors at the bottom of the board, an amplifying circuit **19** in which an amplifier (FET) is integrated is merged (mounted), thereby preparing a mounted structure (package) of the amplifier. The electrodes of the amplifier integrated in the amplifying circuit **19** are electrically connected to the connection electrodes, such as the solder ball and the like, on the rear surface of the circuit board **18**, through the inner wirings and through holes (vias) provided in the circuit board **18** and surface wiring delineated on the surface of the circuit board **18**. The mounted structure (package) of the amplifier is accommodated under the canopy top **12e** of the box-shaped insulation container (**12a**, **12b**, **12d** and **12e**), similarly to the configuration illustrated in FIG. **20**, the insulating block **12c** is inserted under the canopy top **12e**. Then, when the cover is put on the portion for storing the mounted structure (package), the film-shaped electro-mechanical converter according to the thirteenth embodiment is completed.

Alternatively, a foamed PP film can be used, substantially similar to the above (a) to (c), as the polymer film **61b** provided with the plurality of independent bubbles **62b**. That is, with biaxially-stretching work, the foamed PP film (having a

thickness of 50 micrometers) may be prepared, and an Al film is deposited on the foamed PP film as a vibrating electrode **15b**. Meanwhile, negative charges are generated on a PTFE film (having a thickness of 25 micrometers) by corona discharge so as to implement an electret layer **13**, and a different PTFE film (having a thickness of 25 micrometers) may be laminated as an electret-insulating layer **64** on the electret layer **13**. Thereafter, when the separately prepared polymer film **61b** is laminated on the electret-insulating layer **64**, the film-shaped electro-mechanical converter having no protrusion can be manufactured as illustrated in FIG. **48**.

The dashed line in FIG. **49** illustrates an output voltage from the configuration of the film-shaped electro-mechanical converter having no protrusion as illustrated in FIG. **48**, and solid line in FIG. **49** illustrates an output voltage from the configuration of the film-shaped electro-mechanical converter having the plurality of protrusions **63** as illustrated in FIG. **45** (protrusion interval is two millimeters, protrusion height is ten micrometers, and protrusion curvature is 25 millimeters), when an acoustic wave of 1 kHz is irradiated to each of the above film-shaped electro-mechanical converters. In the film-shaped electro-mechanical converter having the plurality of protrusions **63** as illustrated in FIG. **45**, it can be understood that the output voltage is largely improved and deformation caused by the plurality of protrusions **63** contributes to a large improvement of the output voltage.

In the film-shaped electro-mechanical converter according to the thirteenth embodiment, the gap width is 75 micrometers, and when each height of the plurality of protrusions **63** is assumed to be ten micrometers, the height exceeds $\frac{1}{10}$ of the gap width. However, since the bending caused by the protrusions **63** is absorbed in the inside of the polymer film **61b**, the central line average roughness Ra of the vibrating electrode **15b** is suppressed to be $\frac{1}{10}$ or less of the gap width.

Other Embodiments

As mentioned above, the present invention has been described by using the first to thirteenth embodiments. However, the discussions and drawings that constitute a part of this disclosure should not be understood to limit the present invention. From this disclosure, the various implementations, variations, embodiments and operational techniques may be evident for one skilled in the art.

For example, as configurations of the microgaps, in addition to those described in the first to thirteenth embodiments, it is possible to employ those configurations illustrated in FIGS. **50** to **54**. That is, as illustrated in FIG. **50**, it is possible to employ a structure in which minute nano-particles are aggregated. When the structure illustrated in FIG. **50** is used, the diameter of the contact point can be reduced to a very small value. Also, as illustrated in FIG. **51**, it is possible to employ a structure in which the surface roughness of the film is used to form the microgap. When the structure illustrated in FIG. **51** is used, the microgap can be formed easier than other methodologies. However, in the case of the structure illustrated in FIG. **51**, it is difficult to control the average interval between the contact points.

Moreover, as illustrated in FIG. **52**, it is possible to employ a structure in which nano-particles are aggregated on the surface of the particle of a micron size. When the structure illustrated in FIG. **52** is used, it is possible to expect the same effect as the effect of FIG. **50** while the gap width is enlarged to the micron size. Moreover, as illustrated in FIG. **53**, it is possible to employ a structure in which the surface roughness is periodically changed by polishing, etching and the like.

When the structure illustrated in FIG. 53 is used, the control of the average interval between the contact points becomes easier than that of FIG. 51.

Moreover, as illustrated in FIG. 54, it is possible to employ a structure in which by pressing work, a plurality of protrusions are formed at a surface of a film at an interval between ten micrometers and one millimeter, and thereafter, particles are coated the surface of the film. According to the structure illustrated in FIG. 54, it is possible to enlarge the interval between the contact points easily.

In the film-shaped electro-mechanical converters, which are illustrated in FIG. 20 in the fifth embodiment or in FIG. 32 in the seventh embodiment, a transparent electrode and a transparent polymer film can be used to manufacture a transparent film-shaped electro-mechanical converter. For example, as the vibrating-plate-protection film 16, the vibrating-electrode-insulating film 15a and the spacer film 12a, widely used transparent resin such as polyethylene resin and the like can be used. As the polymer film and the gap-insulating layers 14a, 14b and 14c, the fluorine transparent resin such as PFA and the like can be used. And as the vibrating electrode 15b and the back electrode 17, transparent electrode material, such as tin doped indium oxide (In_2O_3) film (ITO), indium (In) doped zinc oxide (ZnO) film (IZO), gallium (Ga) doped zinc oxide film (GZO), tin oxide film (SnO_2), conductive polymer films and the like can be used. Consequently, the transparent film-shaped electro-mechanical converter can be provided. Also, although the flexibility is poor, as the polymer film, it is possible to use the transparent ferroelectric material such as LiNbO_3 , LiTaO_3 , PLZT and the like.

Similarly, when the transparent electrode and the transparent polymer film are applied to the film-shaped electro-mechanical converter (acoustic image sensor) according to the twelfth embodiment, whose sectional structure is illustrated in FIG. 43, a transparent film-shaped electro-mechanical converter (acoustic image sensor) can be provided. In order to achieve the transparent film-shaped electro-mechanical converter (acoustic image sensor), it is required that the amplifiers A_{ij-1} , A_{ij} , A_{ij+1} , . . . shall be located in the outer edge of the film-shaped electro-mechanical converter (acoustic image sensor), and a wiring pattern shall be formed so as to electrically conduct with the inner electrode films (back electrodes) 17_{ij-1}, 17_{ij}, 17_{ij+1}, and with the corresponding amplifiers A_{ij-1} , A_{ij} , A_{ij+1} ,

In addition, as described already, because the film-shaped electro-mechanical converter according to the twelfth embodiment can transmit and receive the acoustic wave, the film-shaped electro-mechanical converter according to the twelfth embodiment can be applied to a touch panel for example. As to the touch panels, although there are various configurations, in a next generation touch panel, such operations that, when a finger is brought into contact with the panel, not only its position is detected, but also the contact of the finger can be transmitted to human by using the vibration and the like are required. When the film-shaped electro-mechanical converter according to the twelfth embodiment illustrated in FIG. 43 is used as the touch panel, electric pulse signals are sent to the respective elements X_{ij-1} , X_{ij} , X_{ij+1} , . . . , and minute vibrations are generated in the respective elements X_{ij-1} , X_{ij} , X_{ij+1} , . . . , and the vibration of the panel caused thereby is again measured by the film-shaped electro-mechanical converter (acoustic image sensor). Consequently, when the finger is brought into contact, the change in the local vibration distribution of the panel can be detected, thereby detecting the contact. Moreover, at that time, when different electric pulse signals are sent to the respective elements X_{ij-1} , X_{ij} , X_{ij+1} , . . . so that vibration having a magnitude that can be

sensed by the finger can be excited, the contact of the finger can be transmitted to human. As a method of transmitting the contact of the finger, there is a method of using a piezoelectric device and generating a surface acoustic wave on the panel. However, when a droplet and a dust and the like are adhered on the touch panel, the propagation state is changed, which disables the vibration to be accurately transmitted. Also, even depending on the assembled condition of the panel, because the propagation state of the surface acoustic wave will change, careful attention shall be paid when the panel is assembled into a product, at the time of manufacturing. By contrast, the film-shaped electro-mechanical converter according to the twelfth embodiment illustrated in FIG. 43 will not suffer from the influences of the droplet, the dust and the assembled condition, because only the place at which the finger is brought into contact can be selectively vibrated.

By the way, in the first to thirteenth embodiments, the diameter of the particles of insulators and the height of the protrusions, the particles and serving the protrusions serve as the spacers, are preferred to be ten nanometers and 40 micrometers. However, for an object in which the flexibility and degrees of freedom in geometrical deformations are not required, such as a situation when the electro-mechanical converter is bonded to a window glass, the diameter of the particles of insulators or the height of the protrusions may be about ten nanometers to 100 micrometers.

In this way, the present invention may naturally include the various implementations and embodiments that are not described herein. Therefore, the technical scope of the present invention should be defined only by subject matters for specifying the invention prescribed by appended Claims, which can be construed appropriate according to the above description.

INDUSTRIAL APPLICABILITY

Because the electro-mechanical transducers of the present invention and the electro-mechanical converters using the electro-mechanical transducers are flexible, have a high degree of freedom in geometrical deformations, have a high sensitivity, can endure a strong sound pressure and can convert mechanical vibrations into electric signals in a wide frequency band, they can be applied in various technical fields of mobile telephones, acoustic equipments, hydrophones, electric power generation devices and the like.

The invention claimed is:

1. An electro-mechanical transducer comprising:
 - a vibrating electrode having a flat vibration surface under no load condition;
 - a vibrating-plate-insulating layer disposed at a bottom surface of said vibrating electrode;
 - an electret layer facing to the vibrating electrode; and
 - a back electrode in contact with a bottom surface of the electret layer,
- wherein a microgap between ten nanometers and 100 micrometers is established between the vibrating-plate-insulating layer and the electret layer, and a central line average roughness Ra of the vibrating electrode, including a bending under a loaded condition, is $1/10$ or less of a gap width measured between the bottom surface of the vibrating electrode and a top surface of the electret layer.
2. An electro-mechanical transducer comprising:
 - a vibrating electrode having a flat vibration surface under no load condition;
 - an electret layer facing to the vibrating electrode;
 - an electret-insulating layer joined to a top surface of the electret layer; and

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a back electrode in contact with a bottom surface of the electret layer,

wherein a microgap between ten nanometers and 100 micrometers is established between the vibrating electrode and the electret-insulating layer, and a central line average roughness Ra of the vibrating electrode, including a bending under a loaded condition, is $\frac{1}{10}$ or less of a gap width measured between a bottom surface of the vibrating electrode and the top surface of the electret layer.

3. An electro-mechanical transducer comprising:
a vibrating electrode having a flat vibration surface under no load condition;

a vibrating-plate-insulating layer disposed at a bottom surface of the vibrating electrode;

an electret layer facing to the vibrating electrode;

an electret-insulating layer joined to a top surface of the electret layer; and

a back electrode in contact with a bottom surface of the electret layer,

wherein a microgap between ten nanometers and 100 micrometers is established between the vibrating-plate-insulating layer and the electret-insulating layer, and a central line average roughness Ra of the vibrating electrode, including a bending under a loaded condition, is $\frac{1}{10}$ or less of a gap width measured between the bottom surface of the vibrating electrode and the top surface of the electret layer.

4. The electro-mechanical transducer according to claim **1**, wherein the microgap is controlled by a height of a protrusion, which is provided as a spacer at a bottom surface of the vibrating-plate-insulating layer.

5. The electro-mechanical transducer according to claim **2**, wherein the microgap is controlled by a height of a protrusion, which is provided as a spacer at a top surface of the electret-insulating layer.

6. The electro-mechanical transducer according to claim **1**, wherein the microgap is controlled by a diameter of a particle,

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which is provided as a spacer between the vibrating-plate-insulating layer and the electret layer.

7. The electro-mechanical transducer according to claim **2**, wherein the microgap is controlled by a diameter of a particle, which is provided as a spacer between the vibrating electrode and the electret-insulating layer.

8. The electro-mechanical transducer according to claim **3**, wherein the microgap is controlled by a diameter of a particle, which is provided as a spacer between the vibrating-plate-insulating layer and the electret-insulating layer.

9. The electro-mechanical transducer according to claim **3**, wherein the microgap is controlled by a thickness of a spacer layer that has a plurality of penetration holes, the spacer layer is inserted between the vibrating-plate-insulating layer and the electret-insulating layer.

10. The electro-mechanical transducer according to claim **1**, further comprising a spacer ring that surrounds the microgap, the spacer ring is inserted between the vibrating-plate-insulating layer and the electret layer in a periphery of the microgap.

11. The electro-mechanical transducer according to claim **2**, further comprising a spacer ring that surrounds the microgap, the spacer ring is inserted between the vibrating electrode and the electret-insulating layer in a periphery of the microgap.

12. The electro-mechanical transducer according to claim **3**, further comprising a spacer ring that surrounds the microgap, the spacer ring is inserted between the vibrating-plate-insulating layer and the electret-insulating layer in a periphery of the microgap.

13. The electro-mechanical transducer according to claim **1**, further comprising a matching layer configured to increase matching characteristics of acoustic impedance, the matching layer is provided on a top surface of the vibrating electrode.

14. The electro-mechanical transducer according to claim **1**, wherein the electret layer is a single crystalline ferroelectric material, a polycrystalline ferroelectric material or a crystalline polymer film.

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