

(10) **Patent No.:** **US 8,230,583 B2**
(45) **Date of Patent:** **Jul. 31, 2012**

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Related U.S. Application Data

Primary Examiner — Paul D Kim

(74) *Attorney, Agent, or Firm* — Zilka-Kotab, PC

(57) **ABSTRACT**

G11B 5/127 (2006.01)

H04R 31/00 (2006.01)

(52) **U.S. Cl.** **29/603.16**; 29/603.11; 29/603.13;
29/603.14; 29/603.15; 29/603.18; 216/22;
216/39; 216/41; 216/48; 216/65; 360/125.02;
360/125.03; 360/125.13; 360/125.3; 360/125.33;
451/5; 451/41

(58) **Field of Classification Search** 29/603.11,
29/603.13–603.16, 603.18; 216/22, 39, 41,
216/48, 65; 360/125.02, 125.03, 125.13,
360/125.3, 125.33, 121, 122, 317; 451/5,
451/41

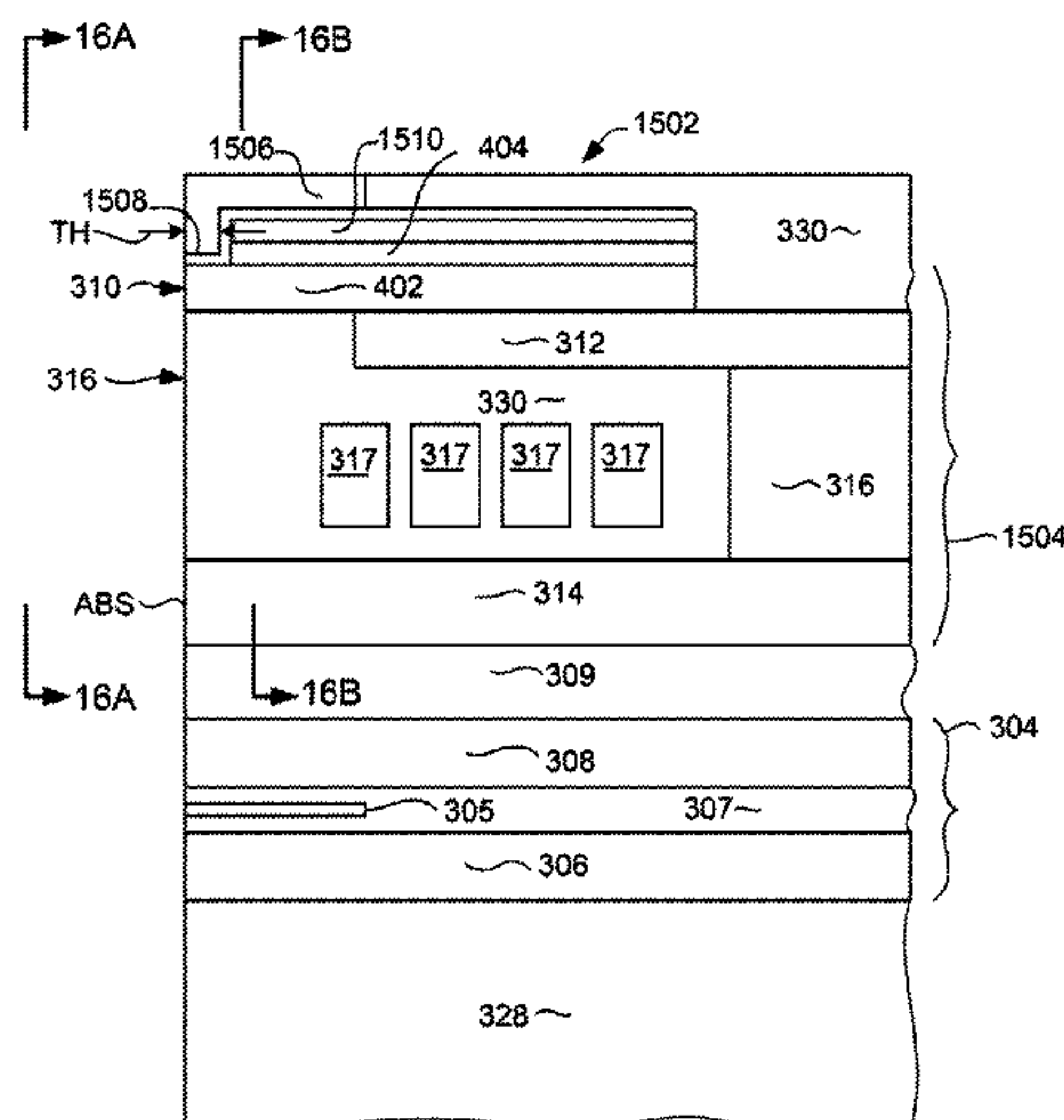
See application file for complete search history.

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10 Claims, 57 Drawing Sheets



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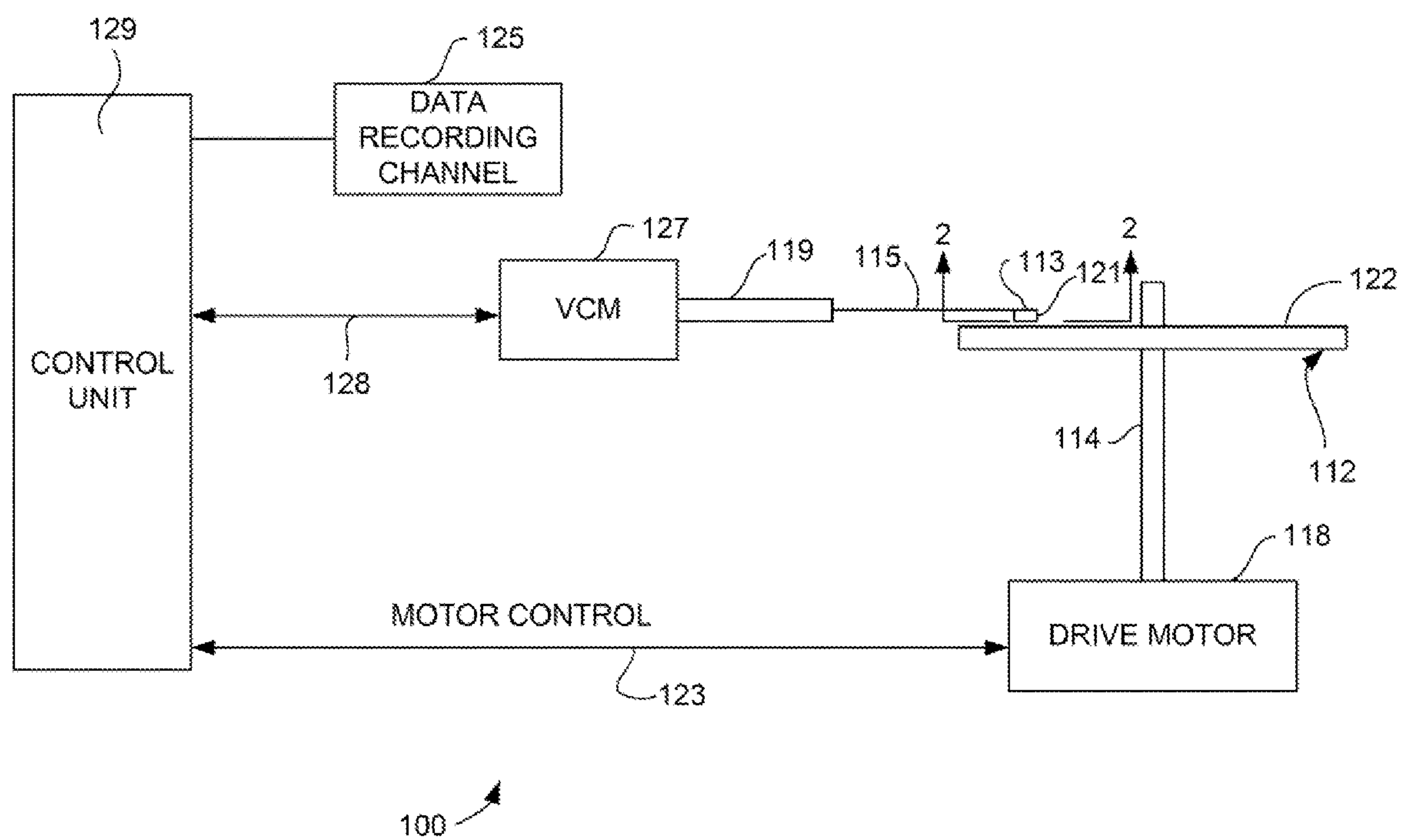


FIG. 1

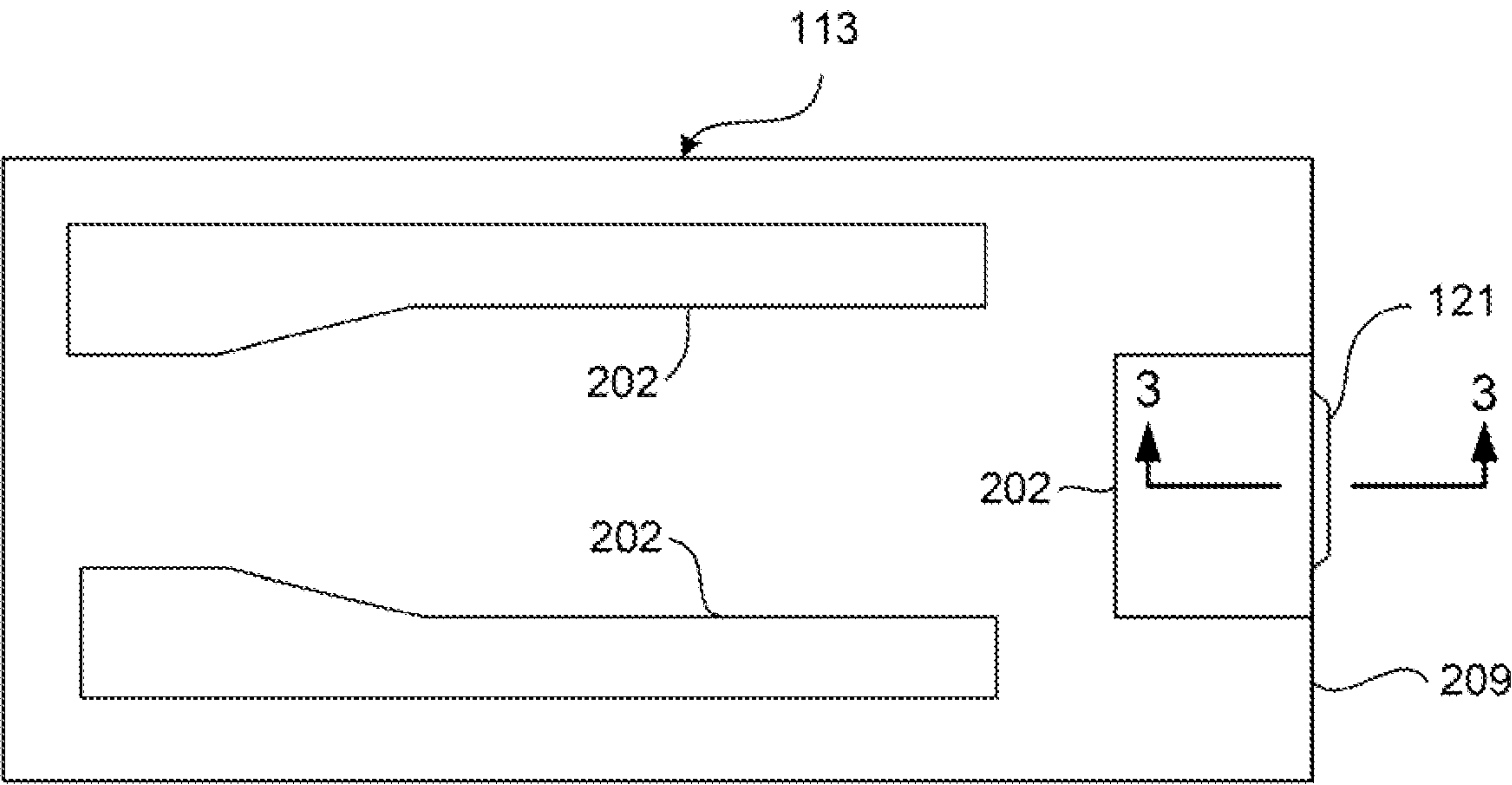
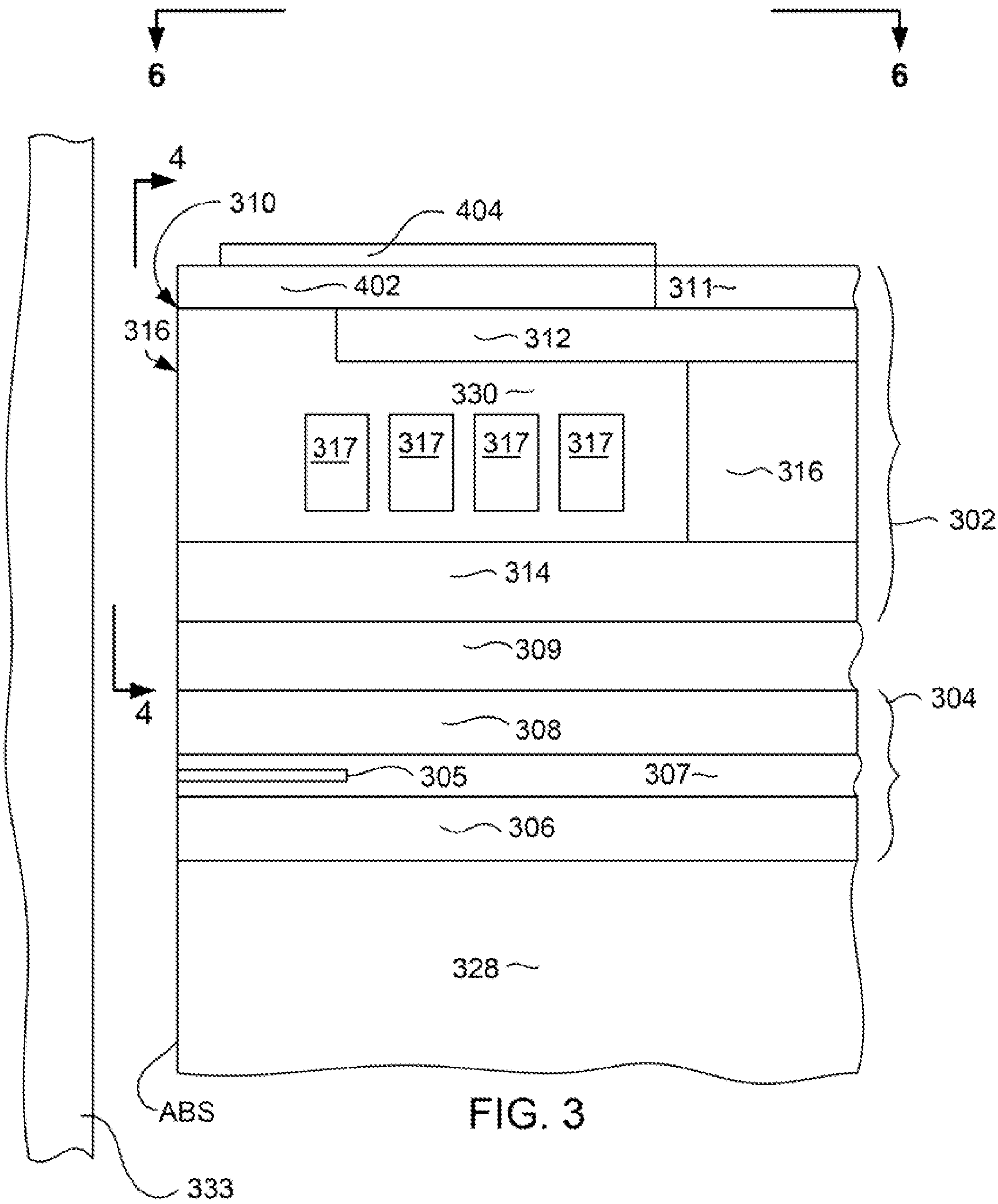


FIG. 2



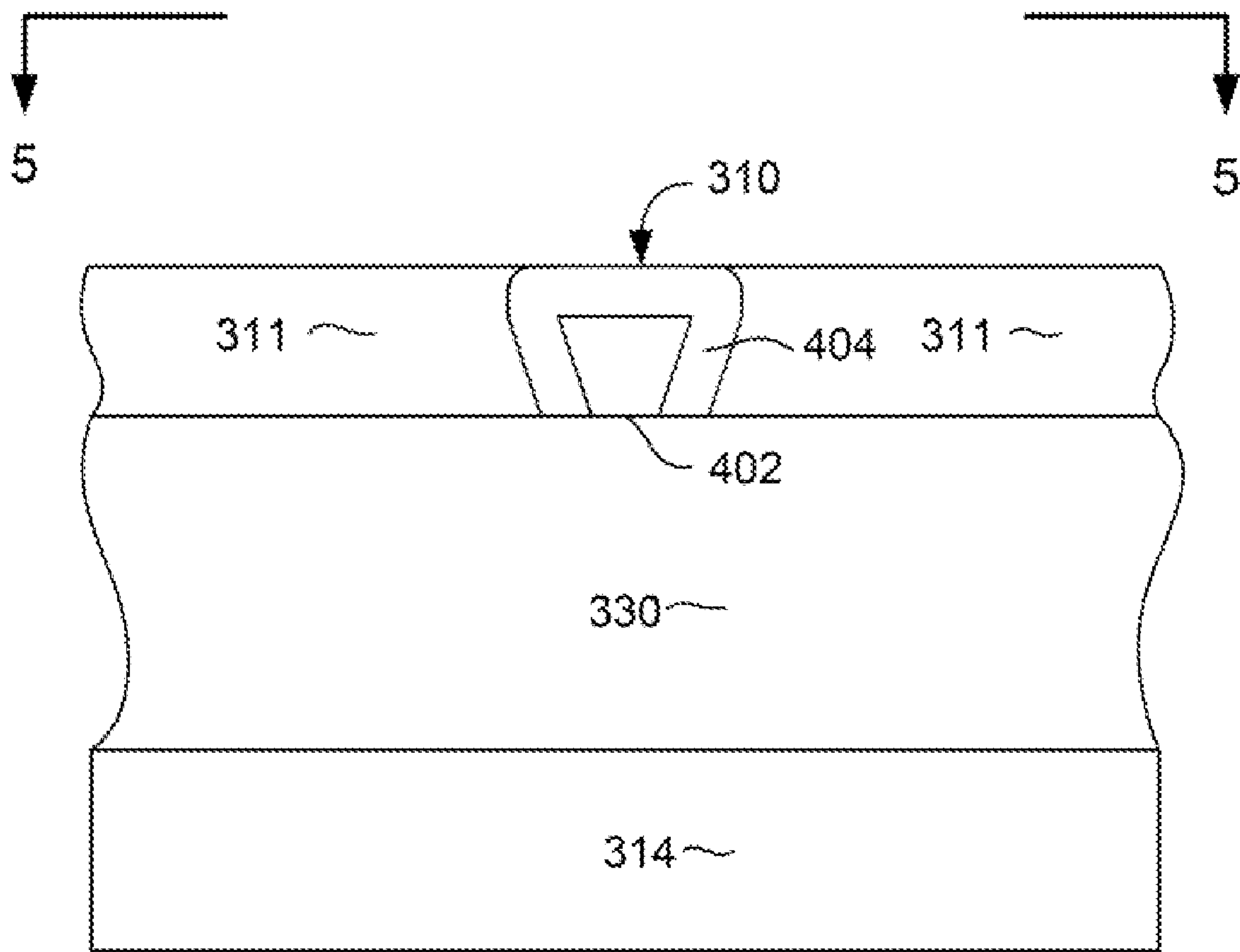


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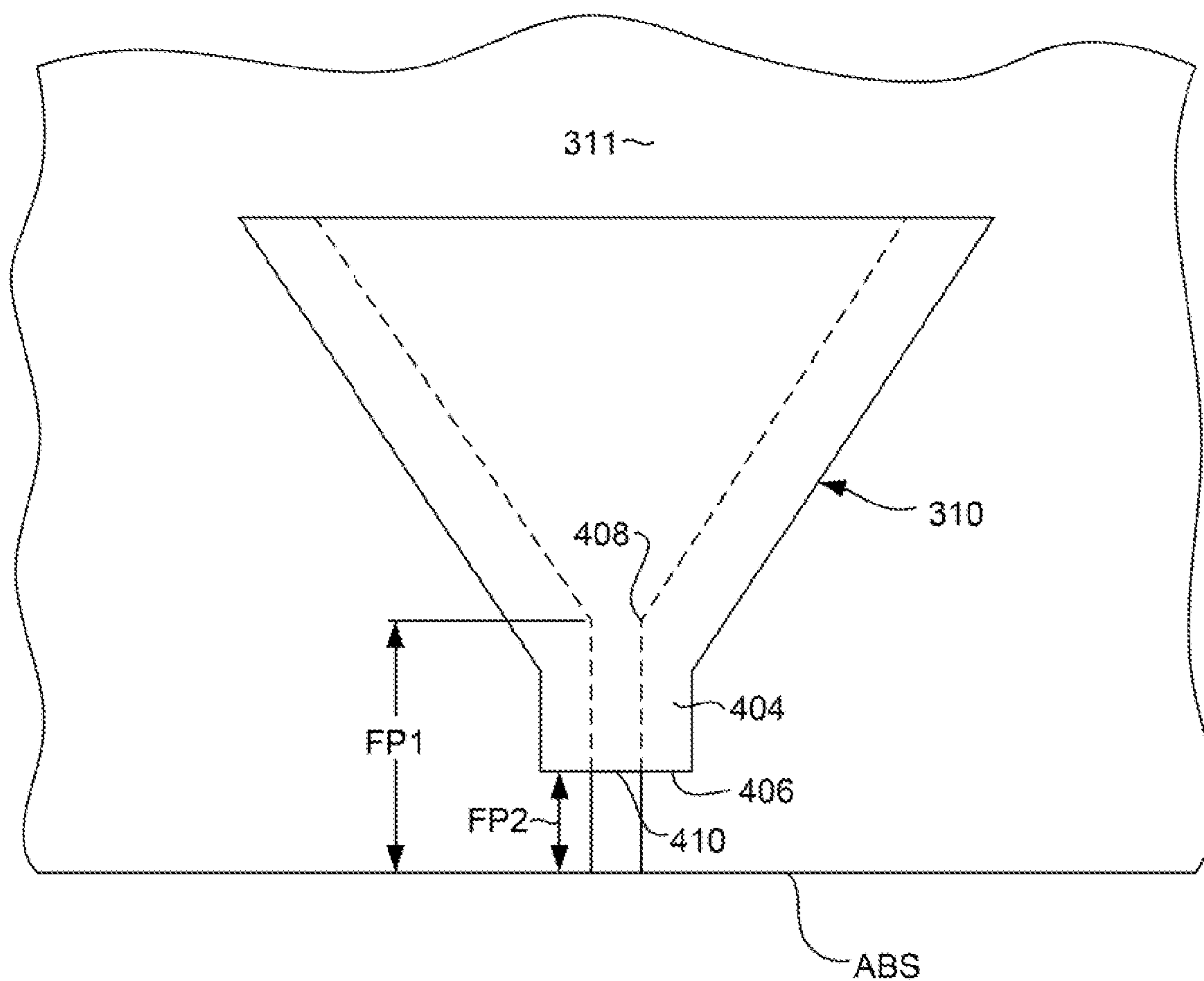


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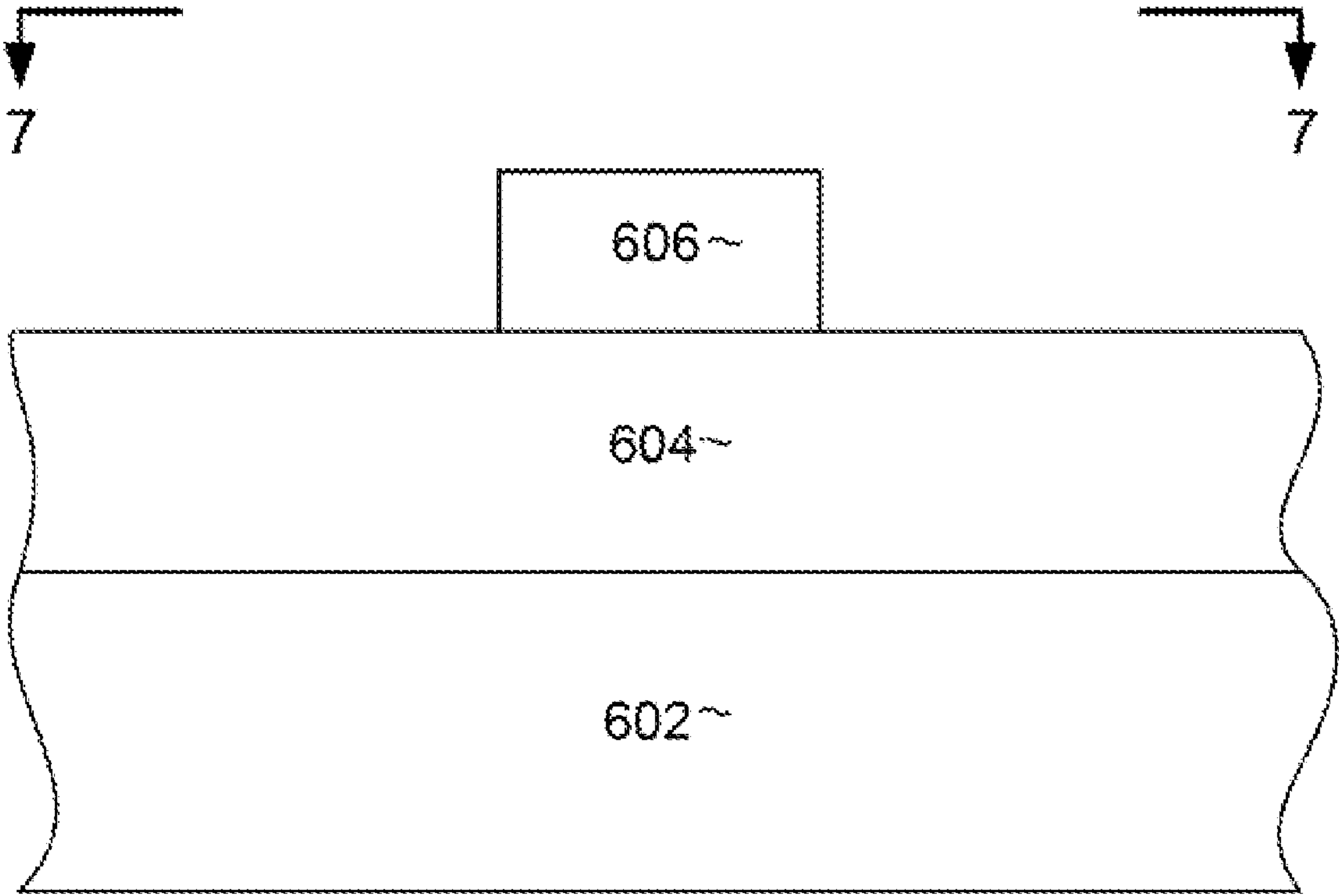


FIG. 6

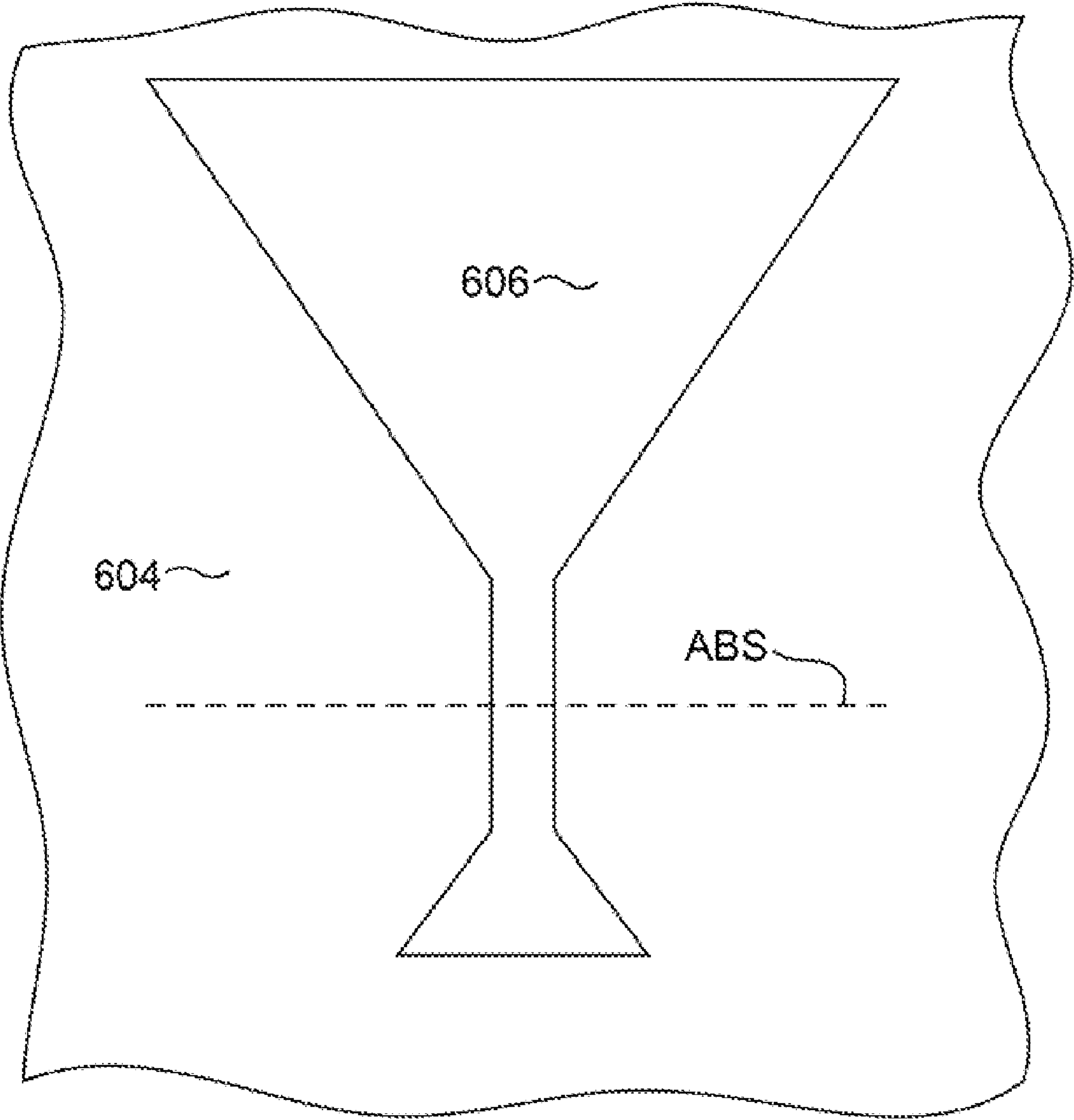


FIG. 7

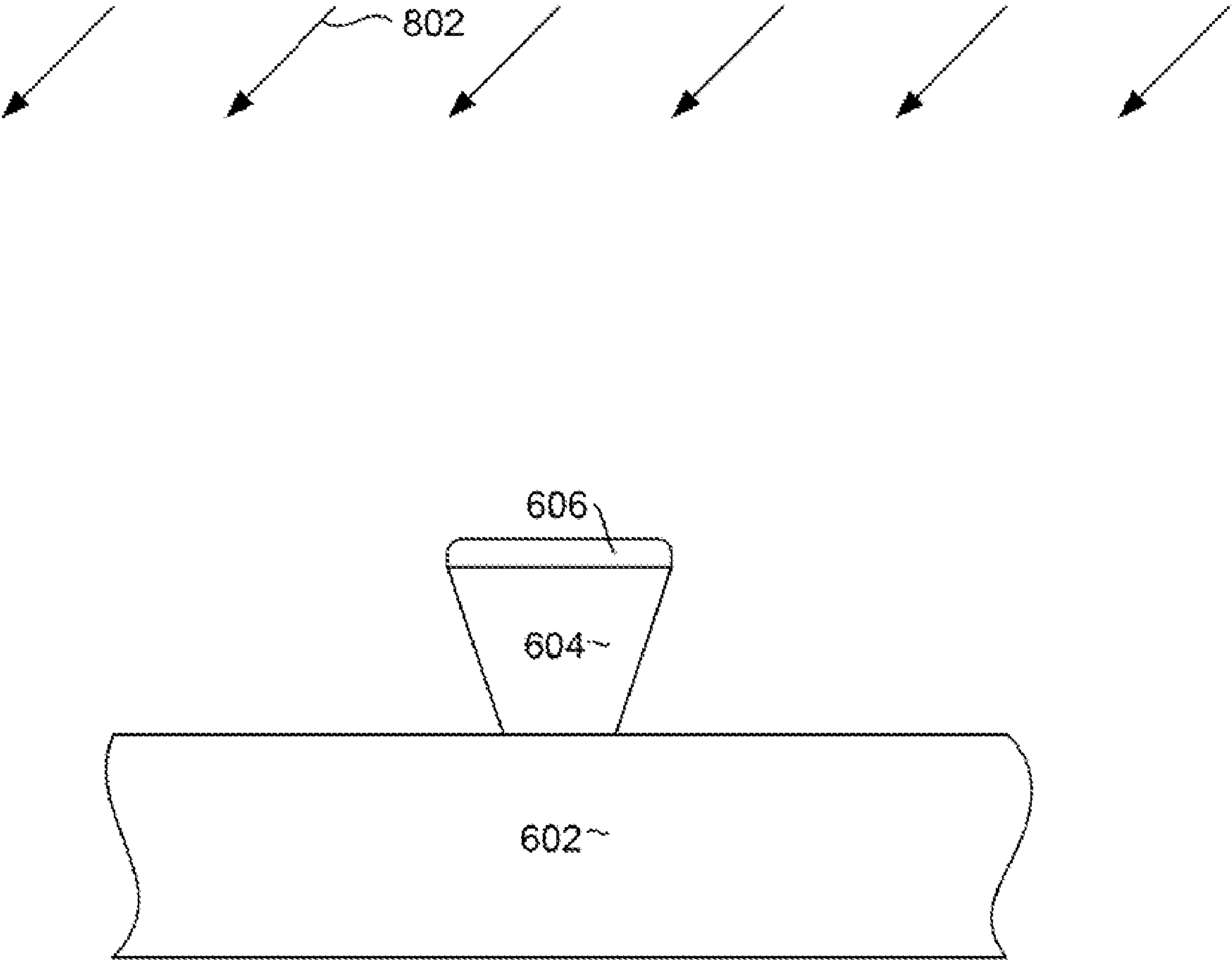


FIG. 8

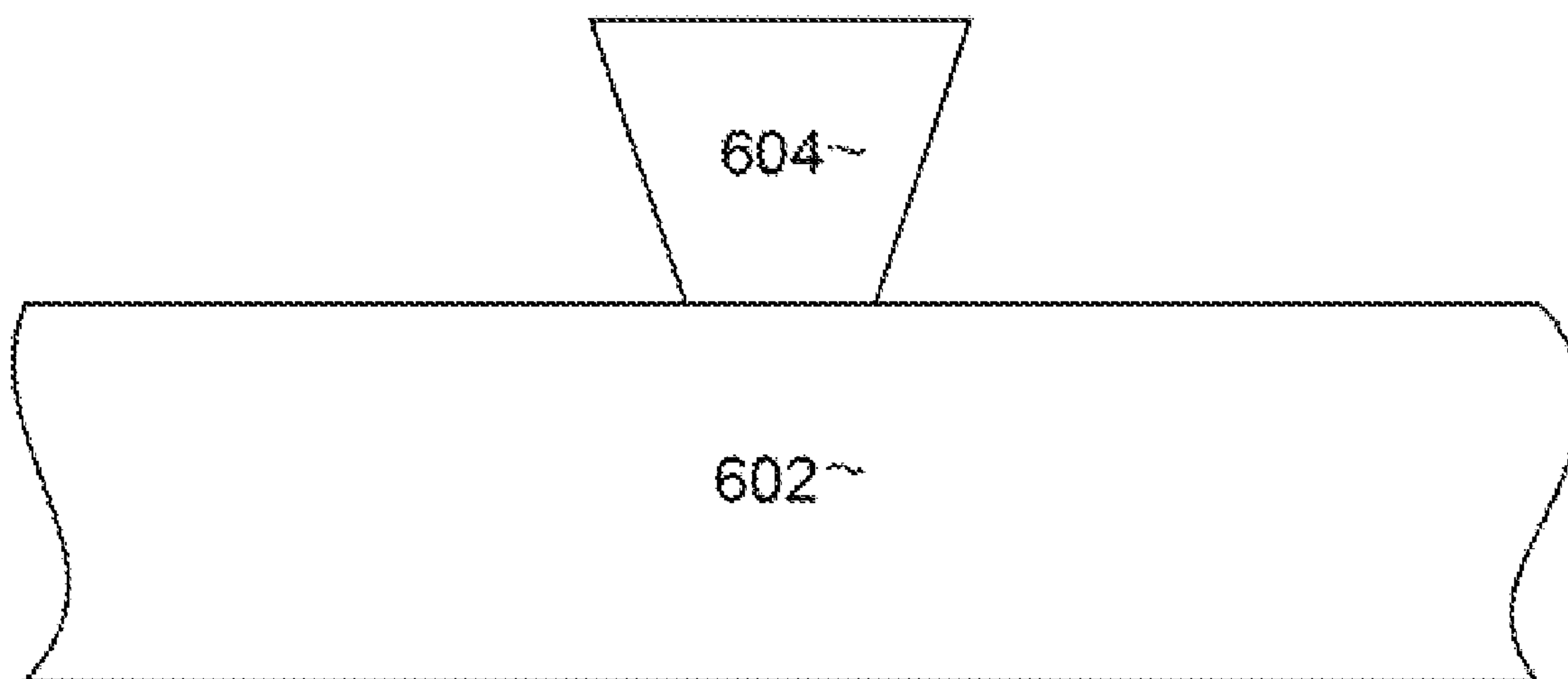


FIG. 9

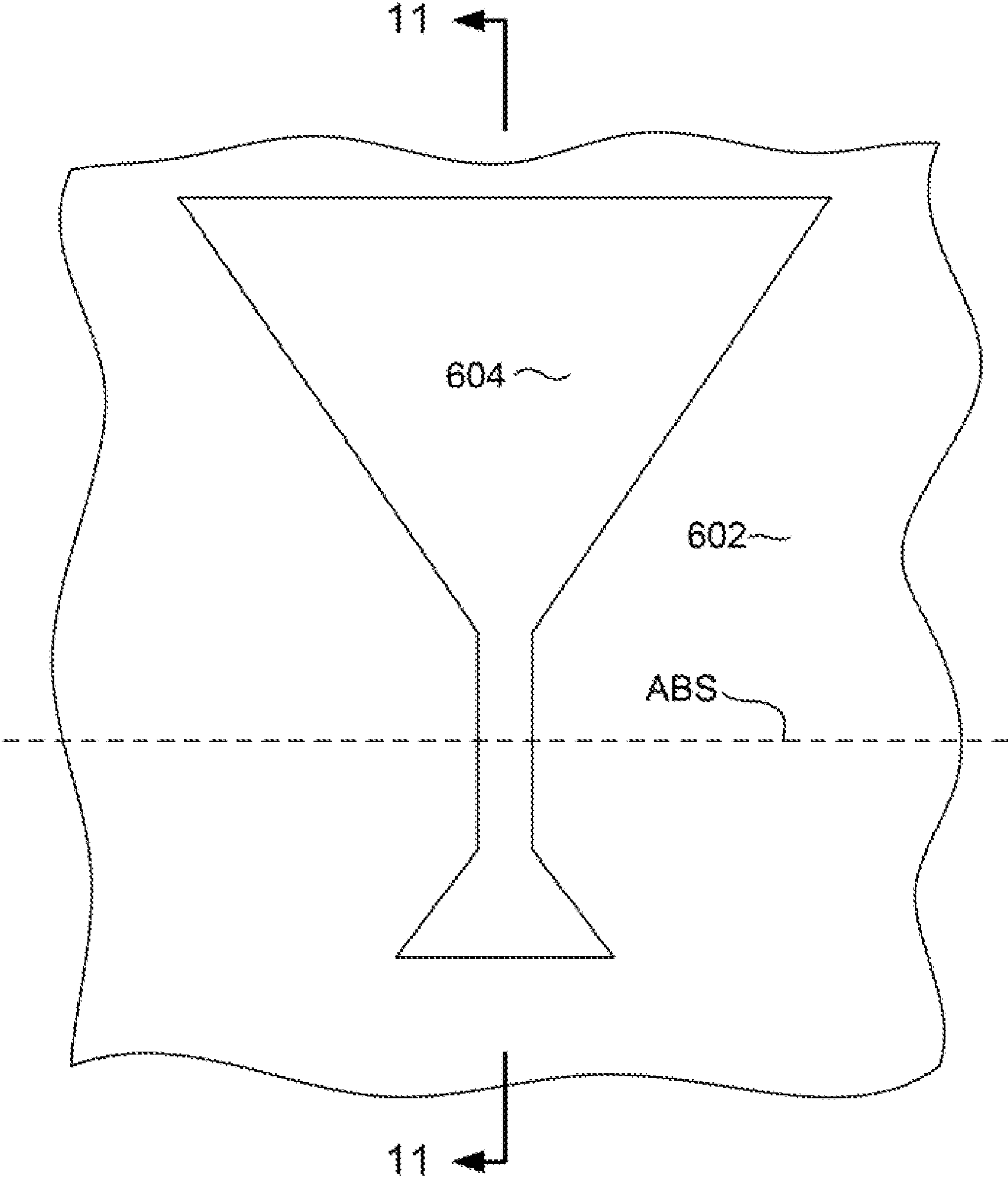


FIG. 10

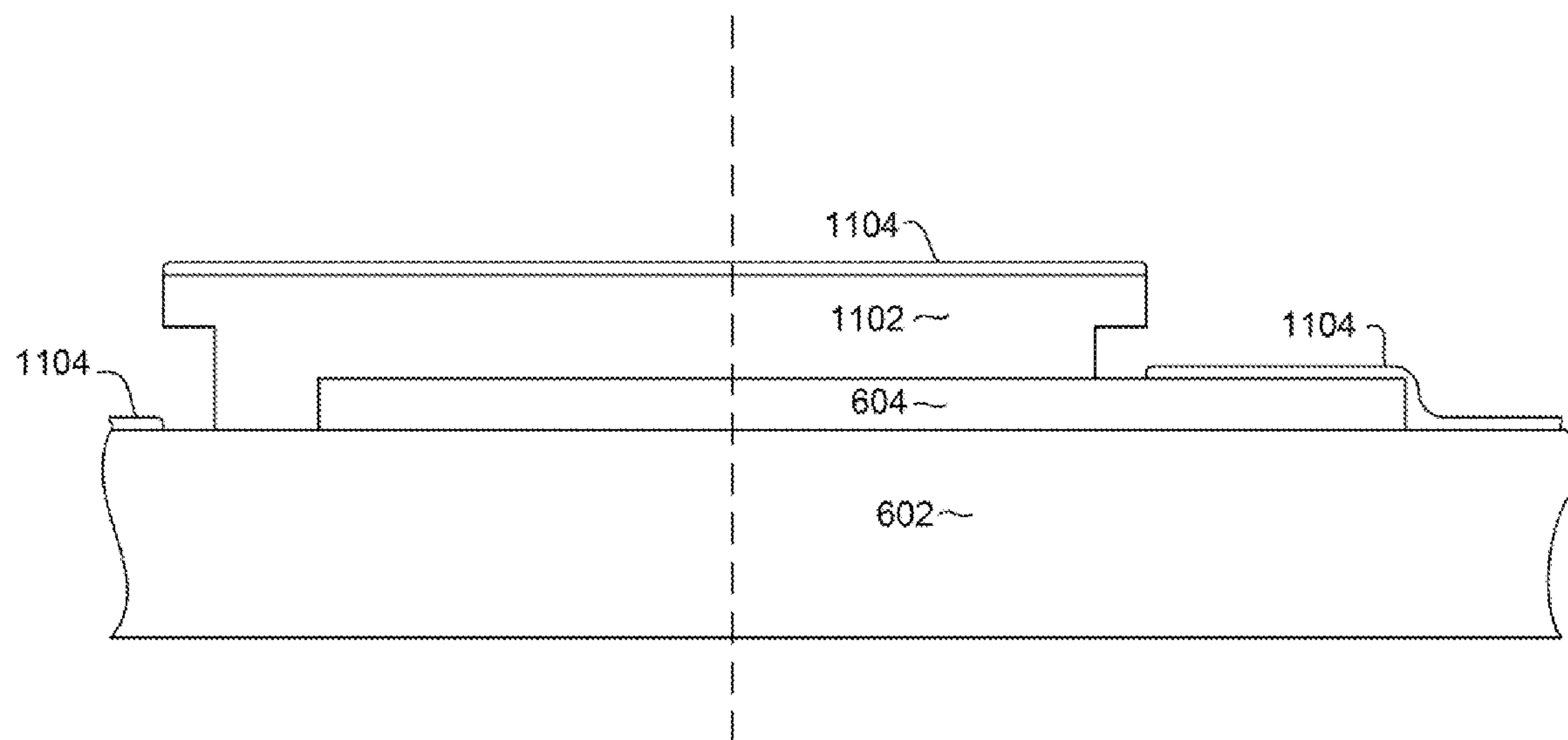


FIG. 11

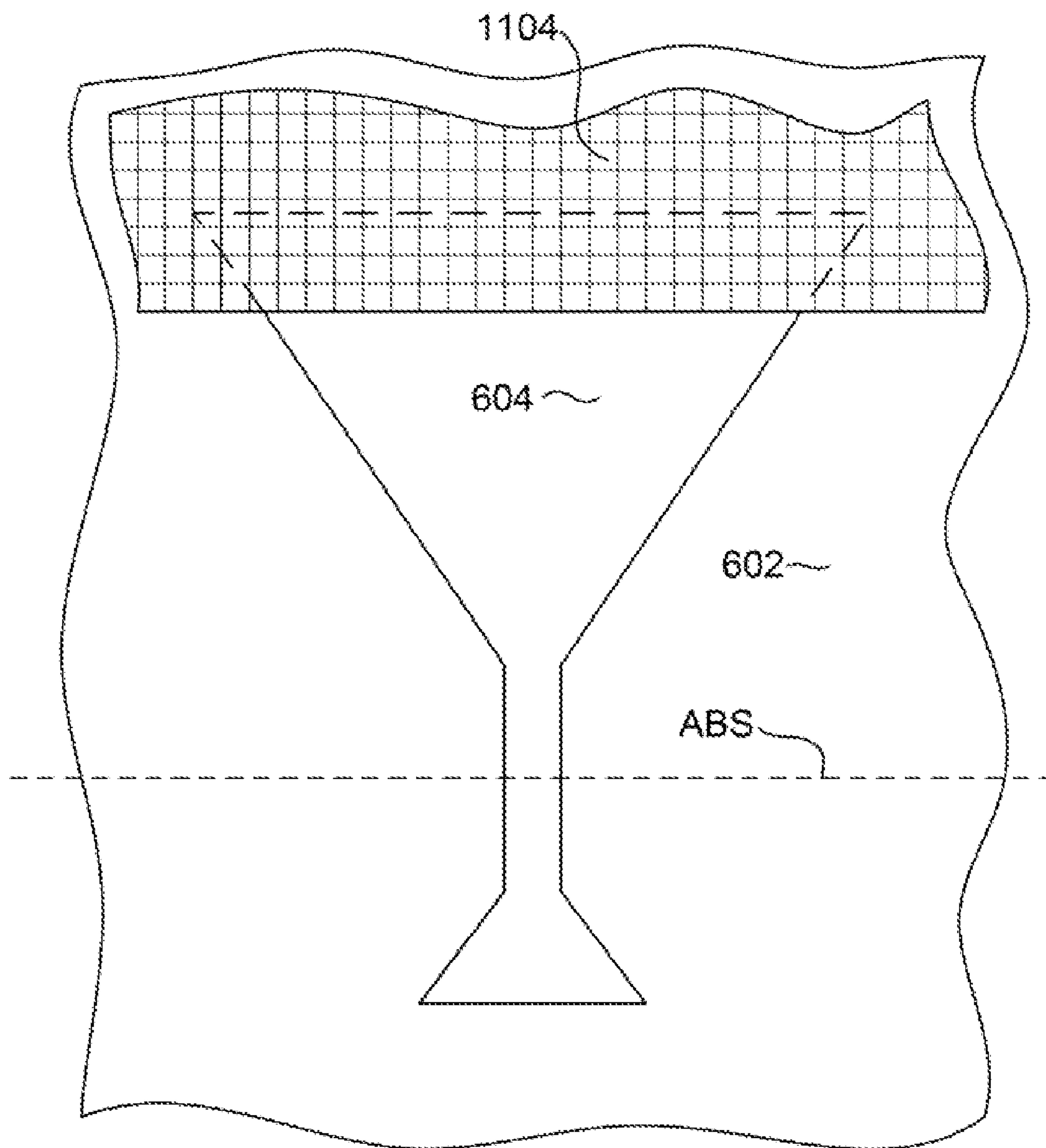


FIG. 12

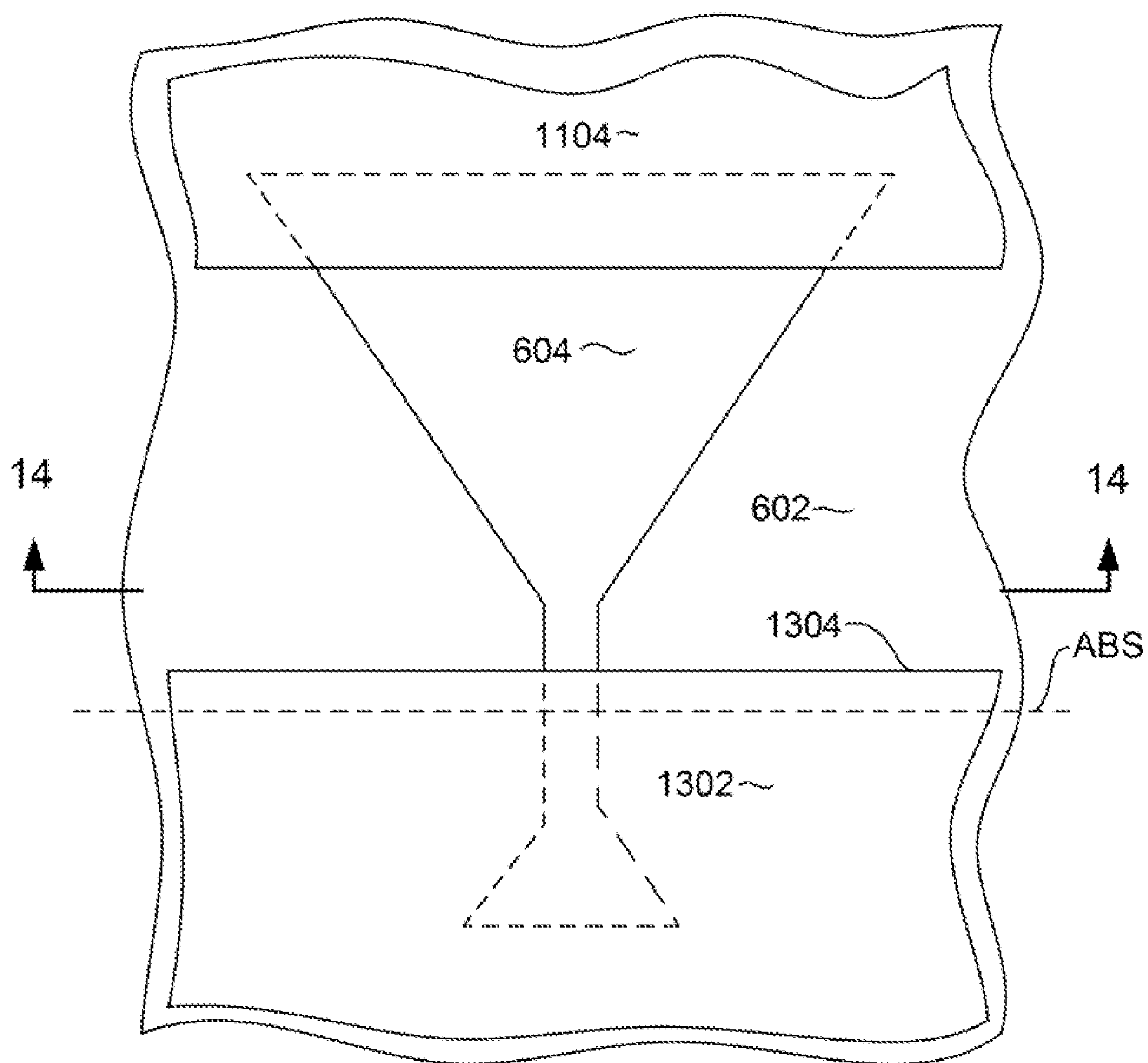


FIG. 13

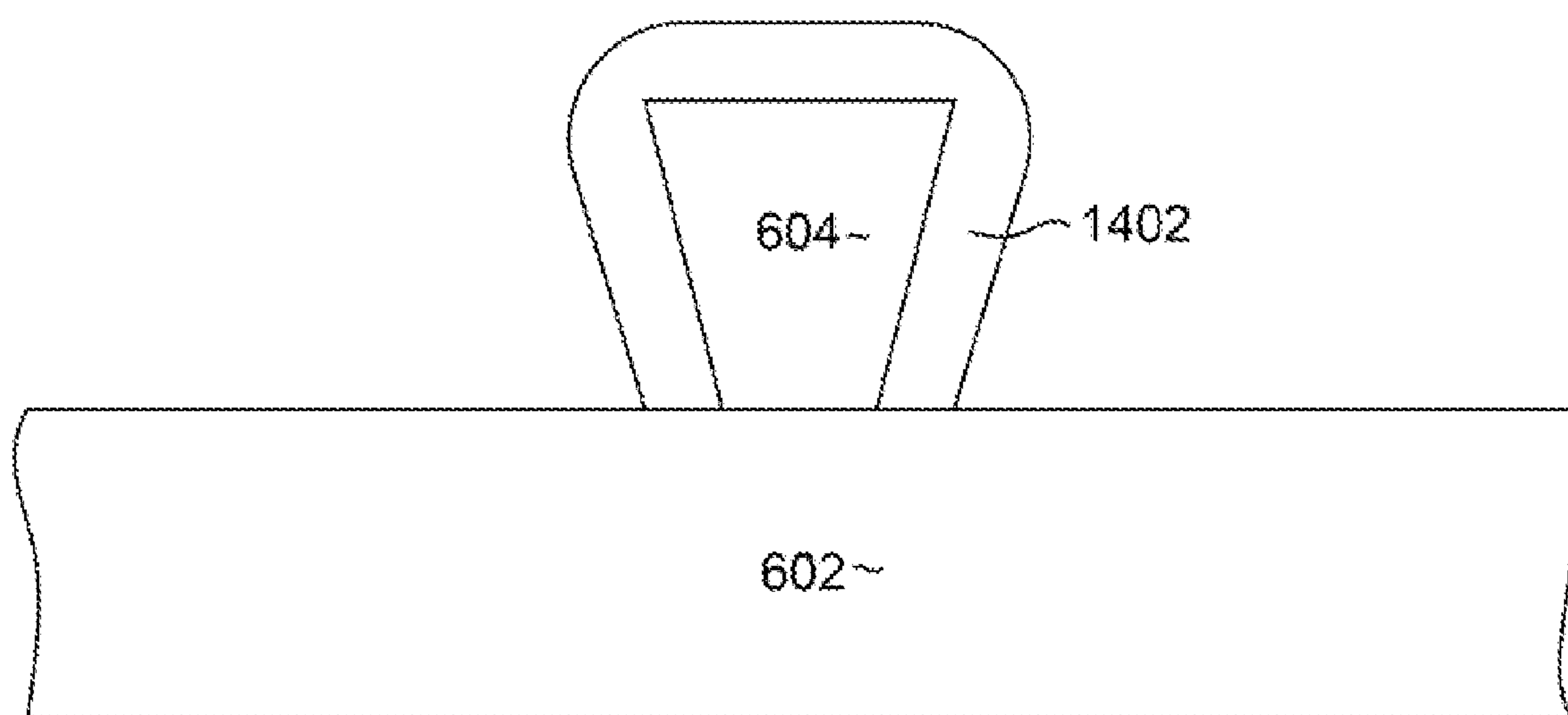


FIG. 14

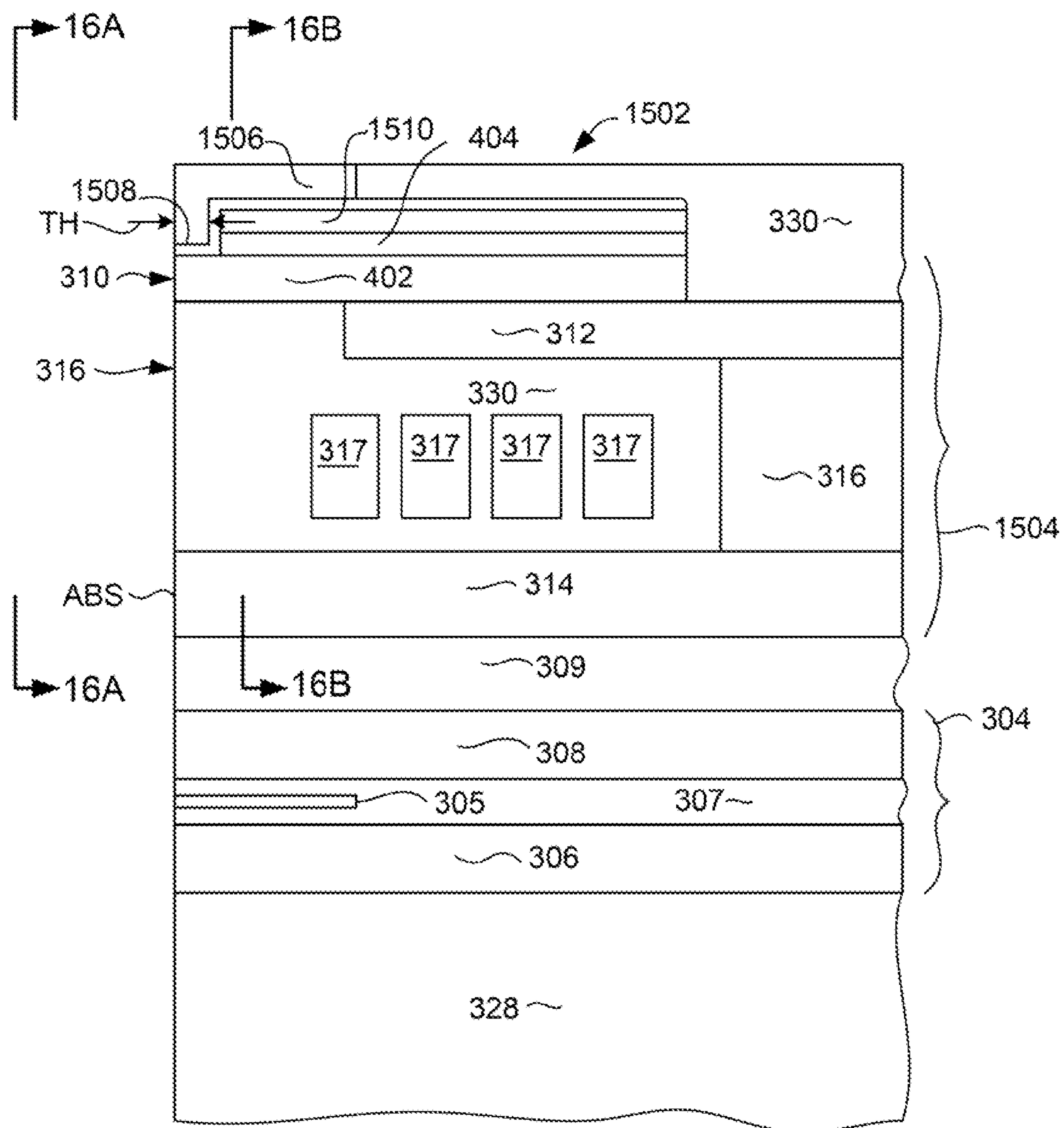


FIG. 15

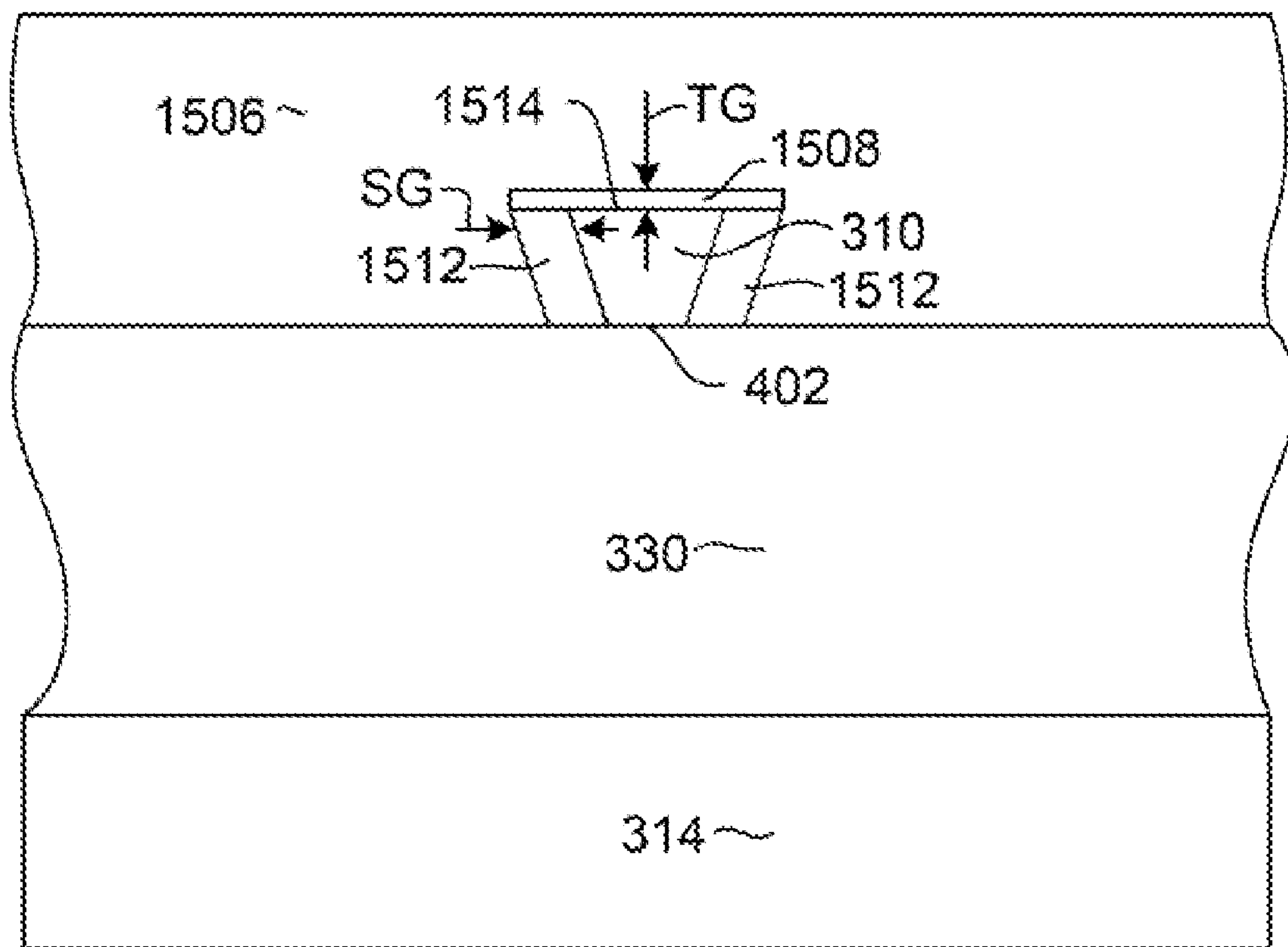


FIG. 16A

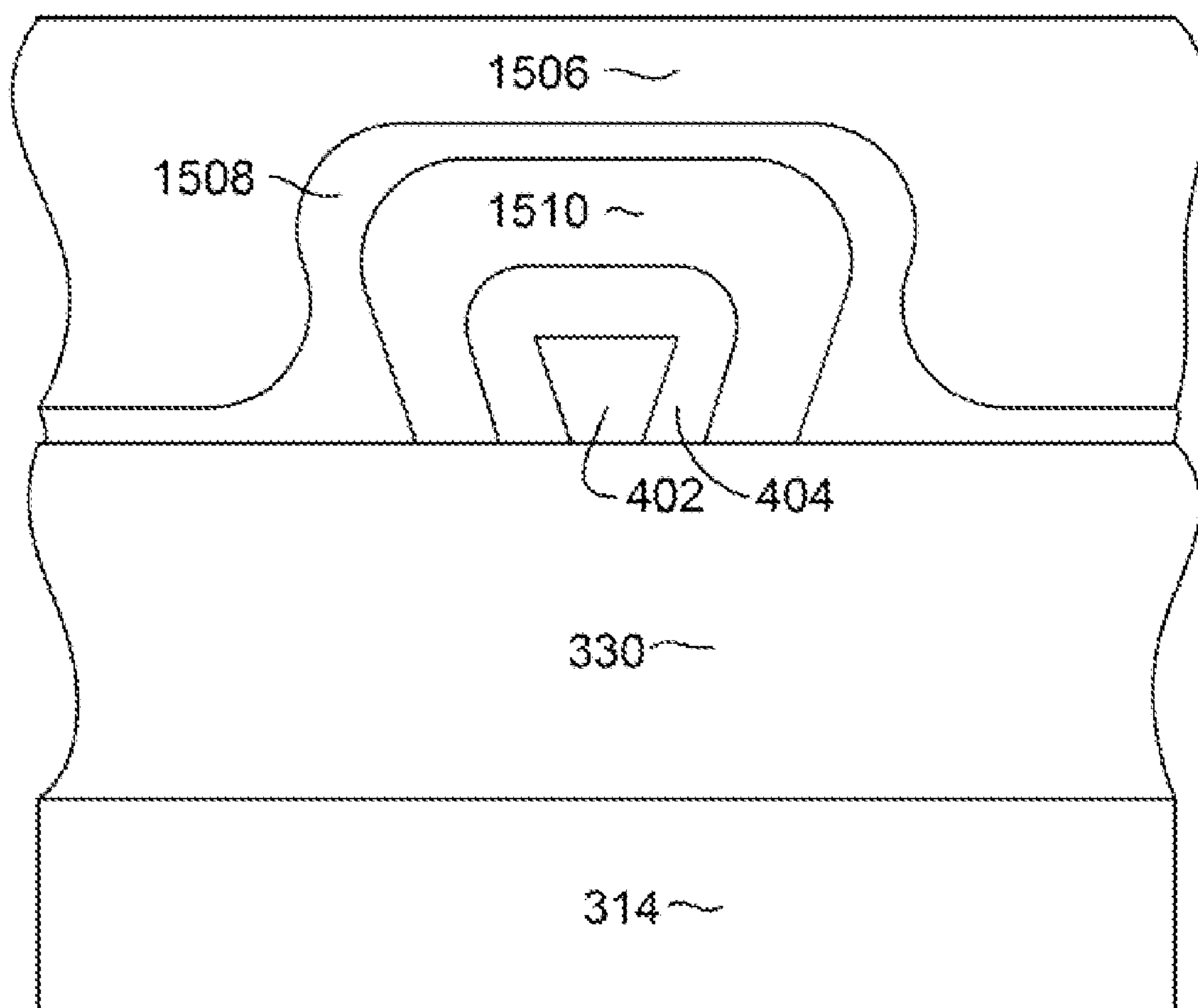


FIG. 16B

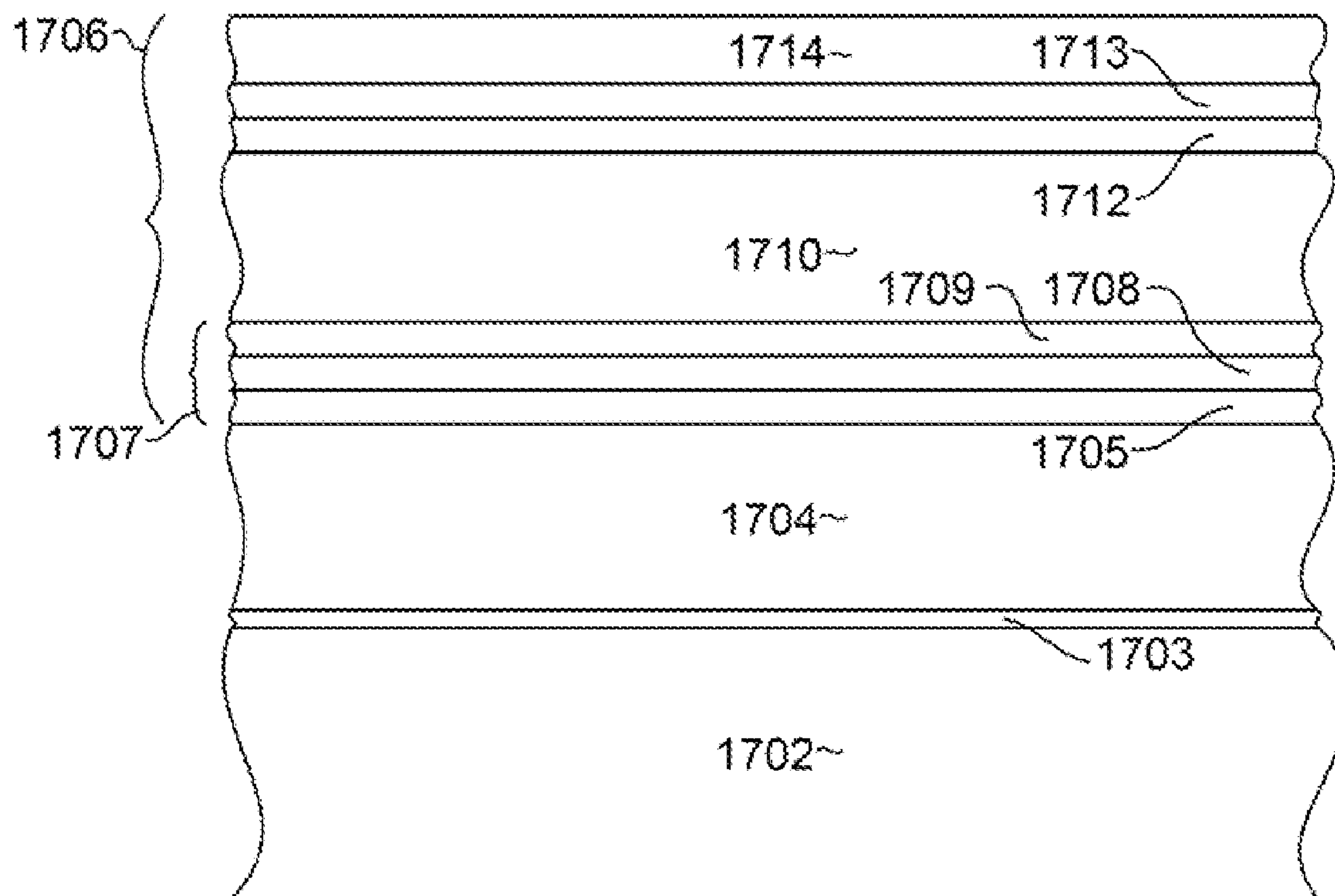


FIG. 17

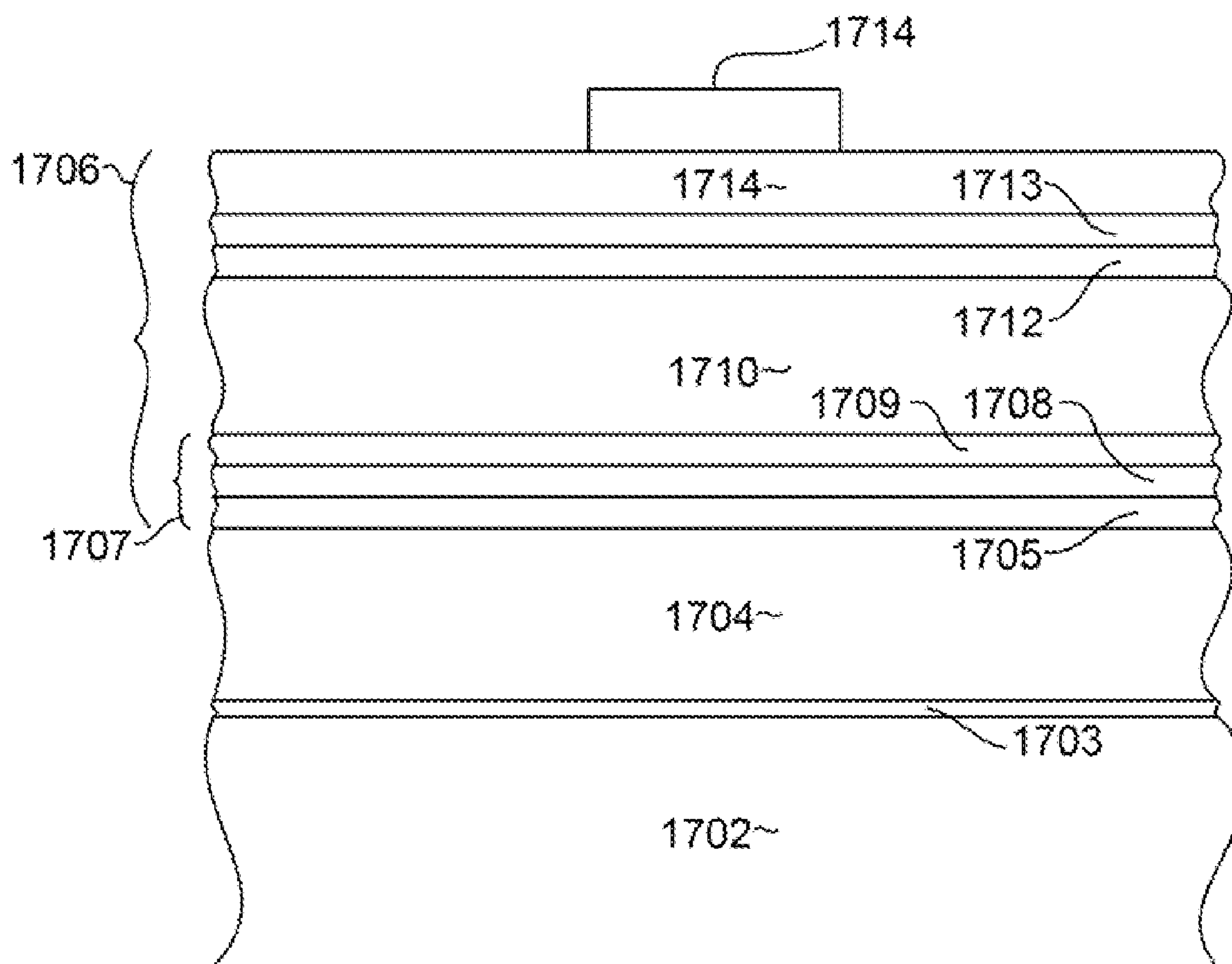


FIG. 18

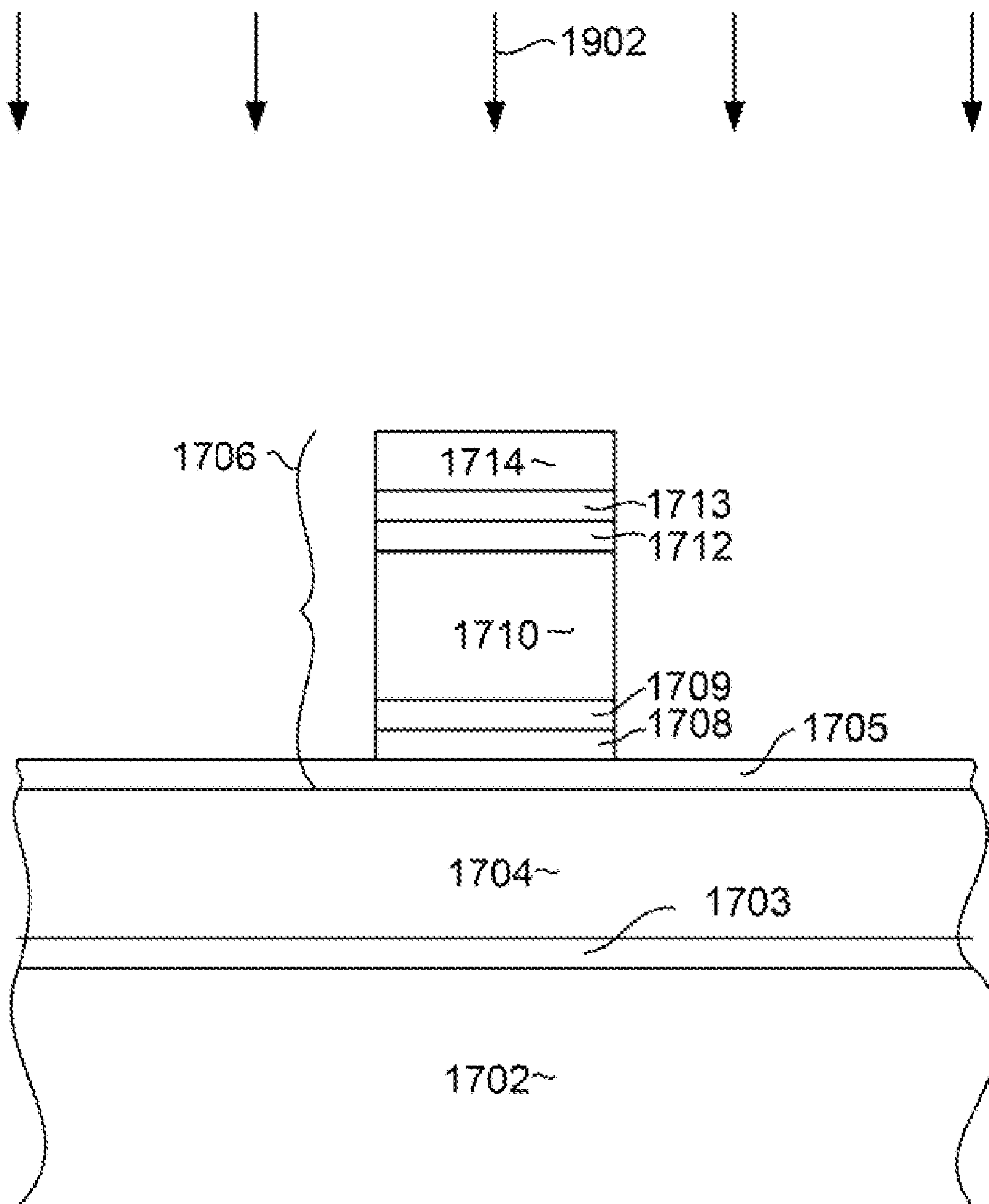


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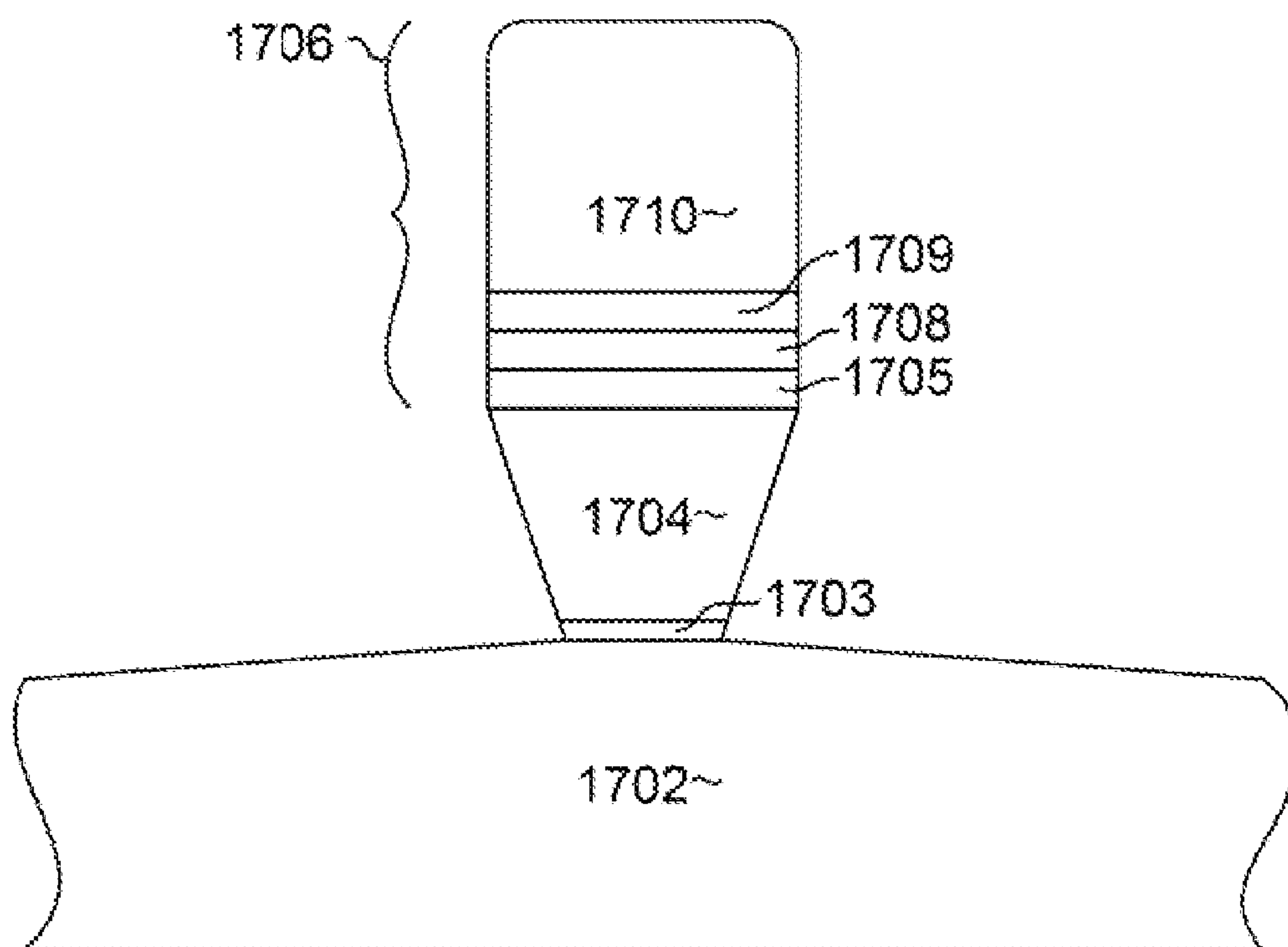
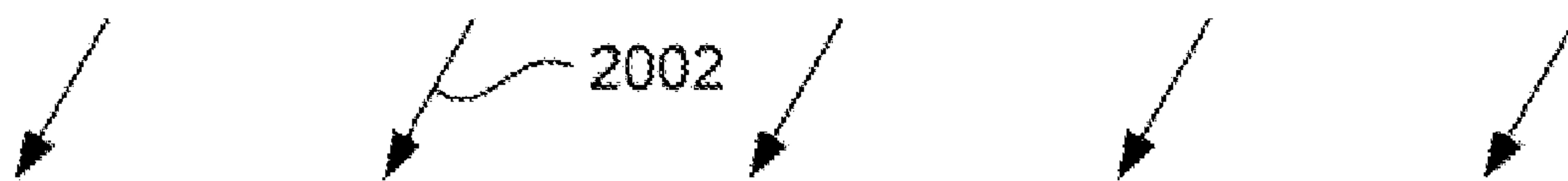


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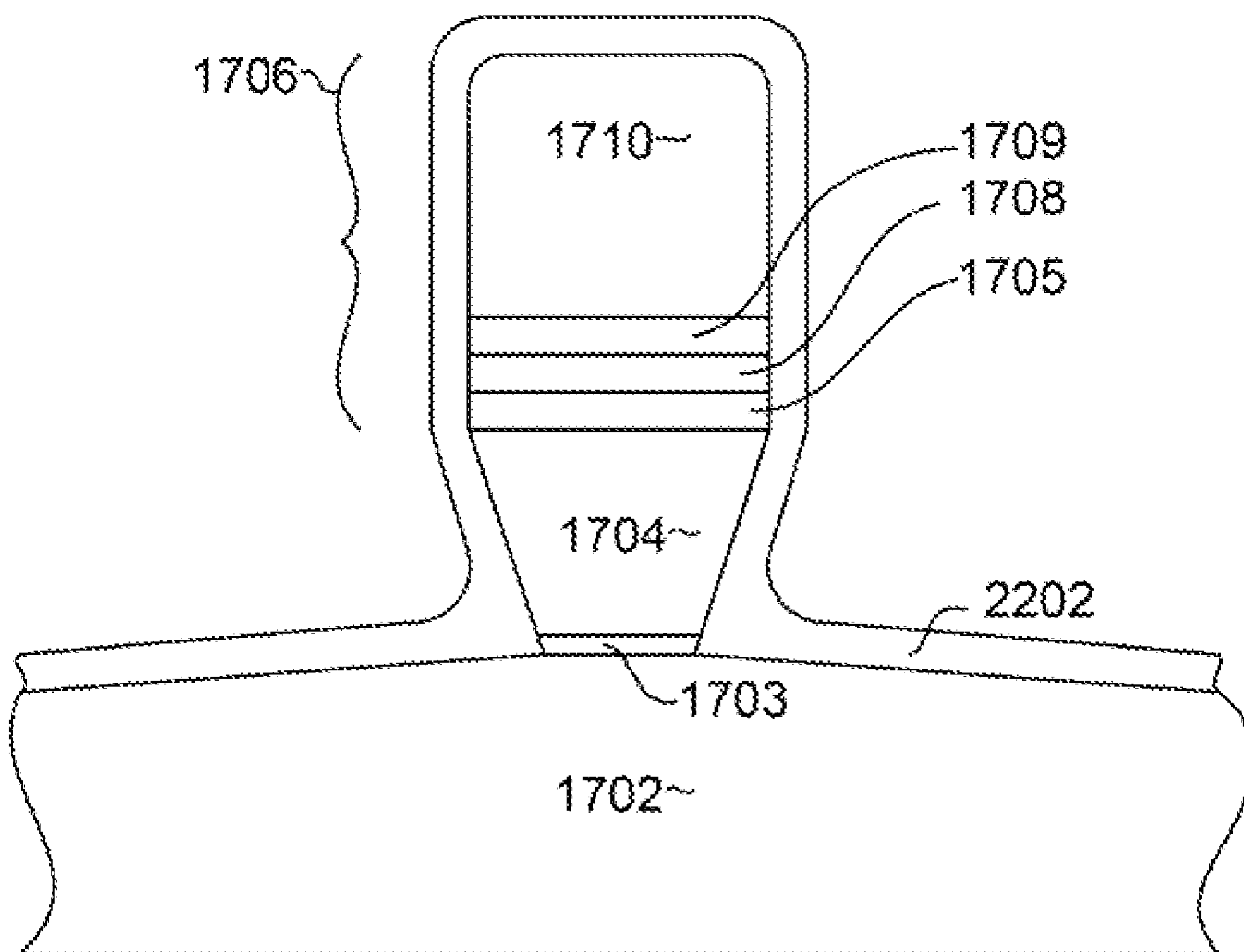


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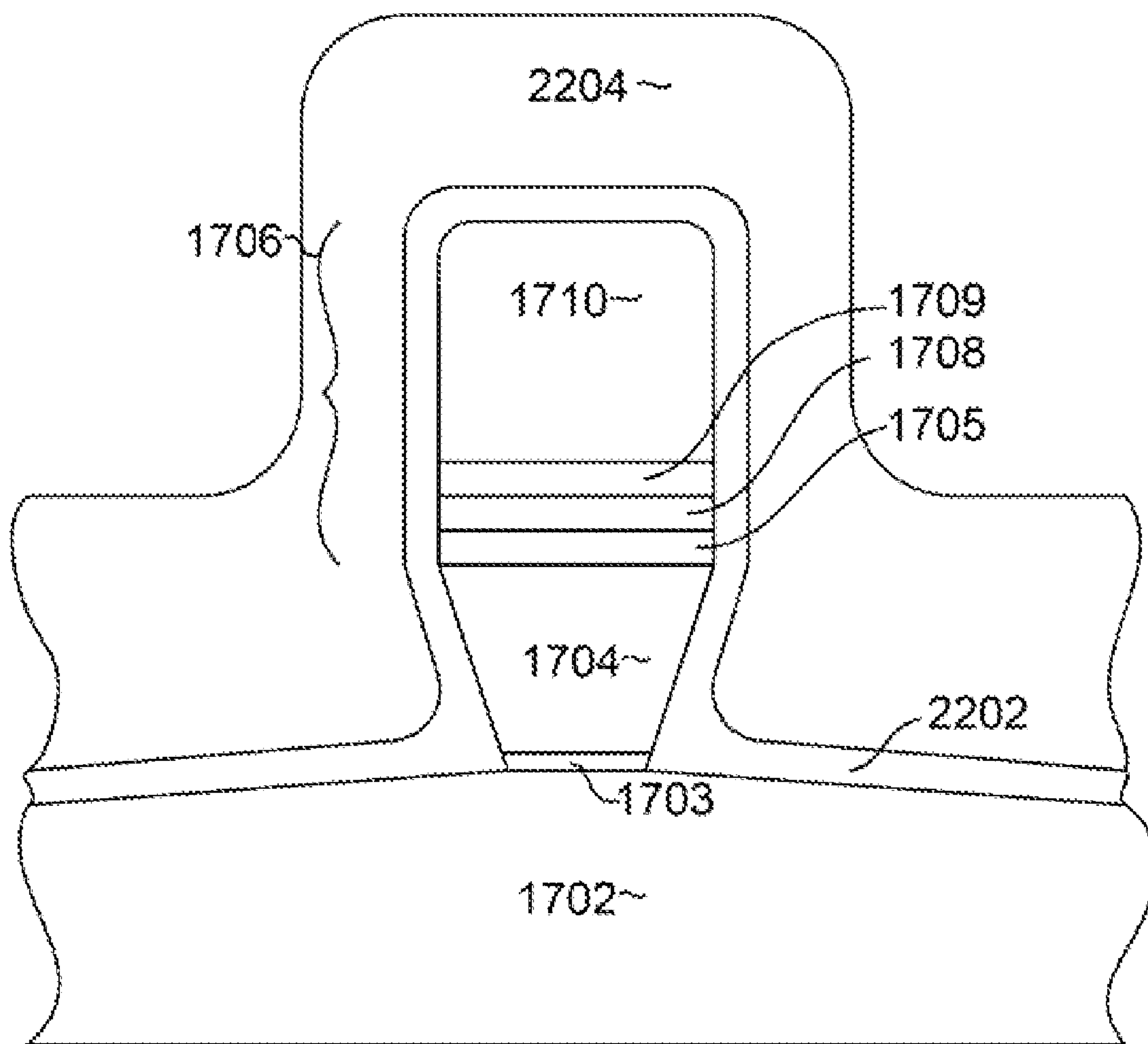


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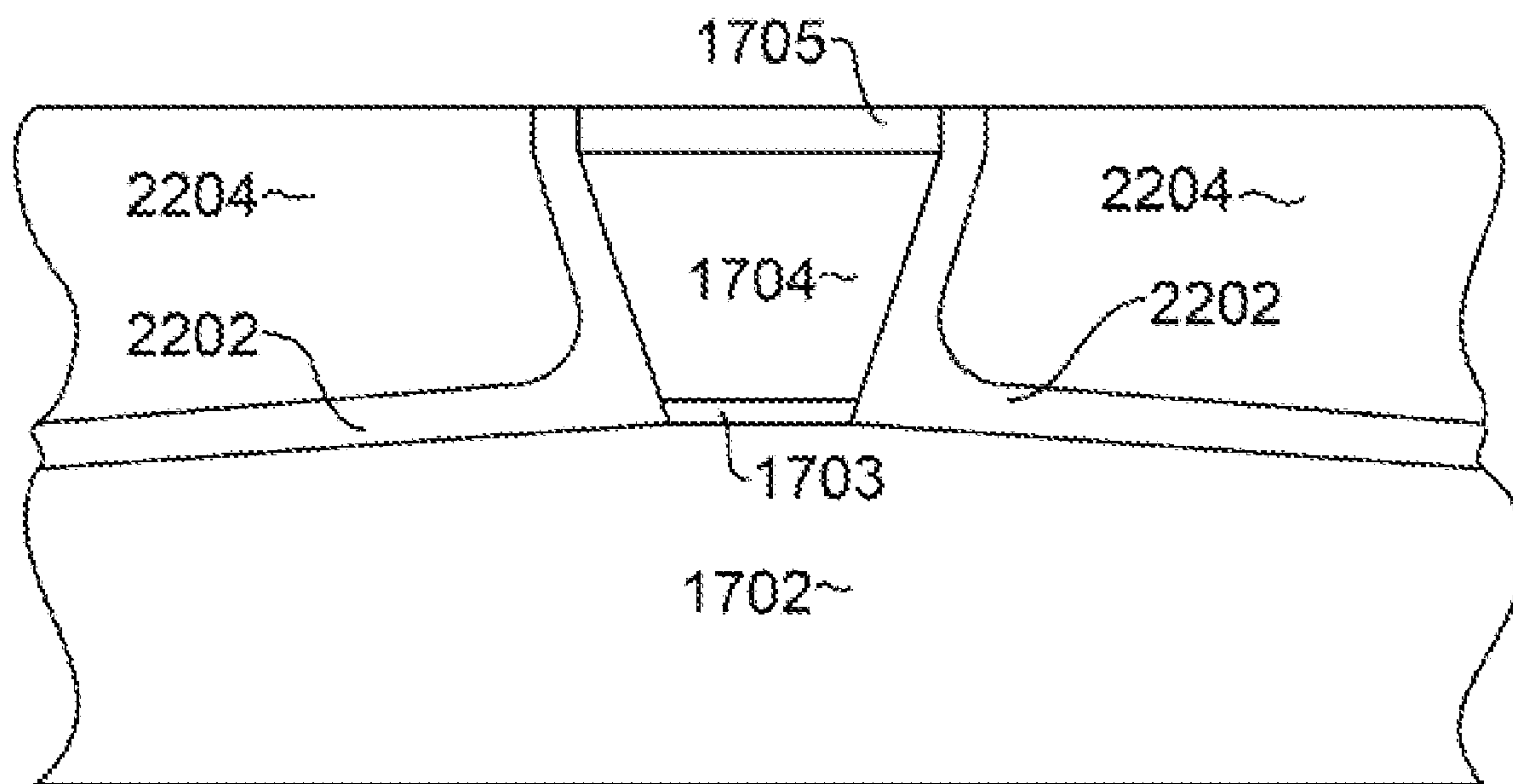


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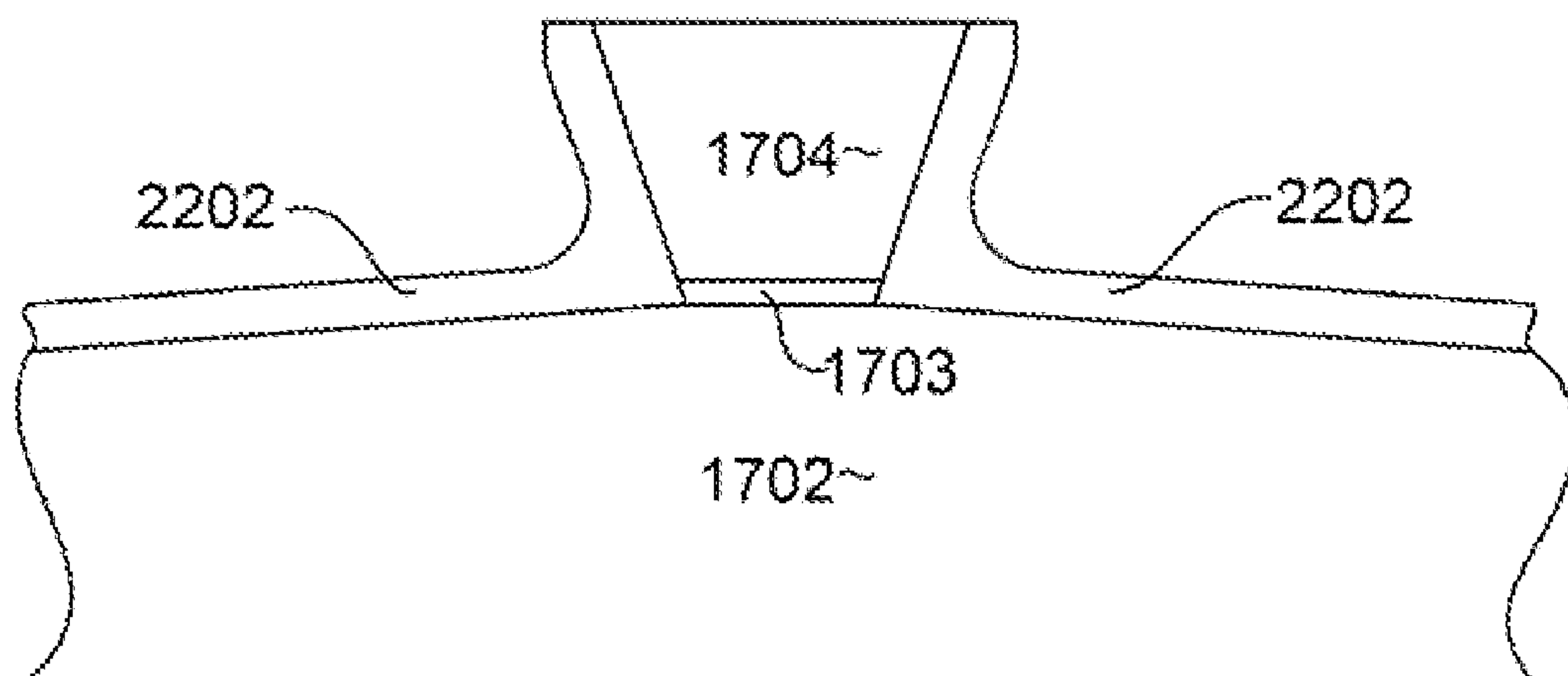
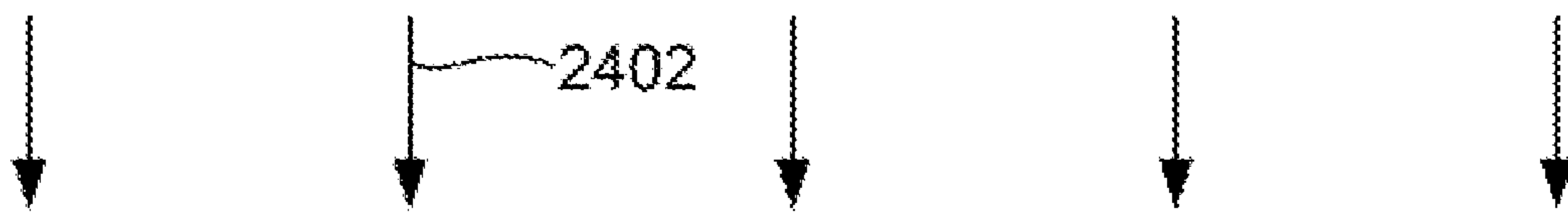


FIG. 24

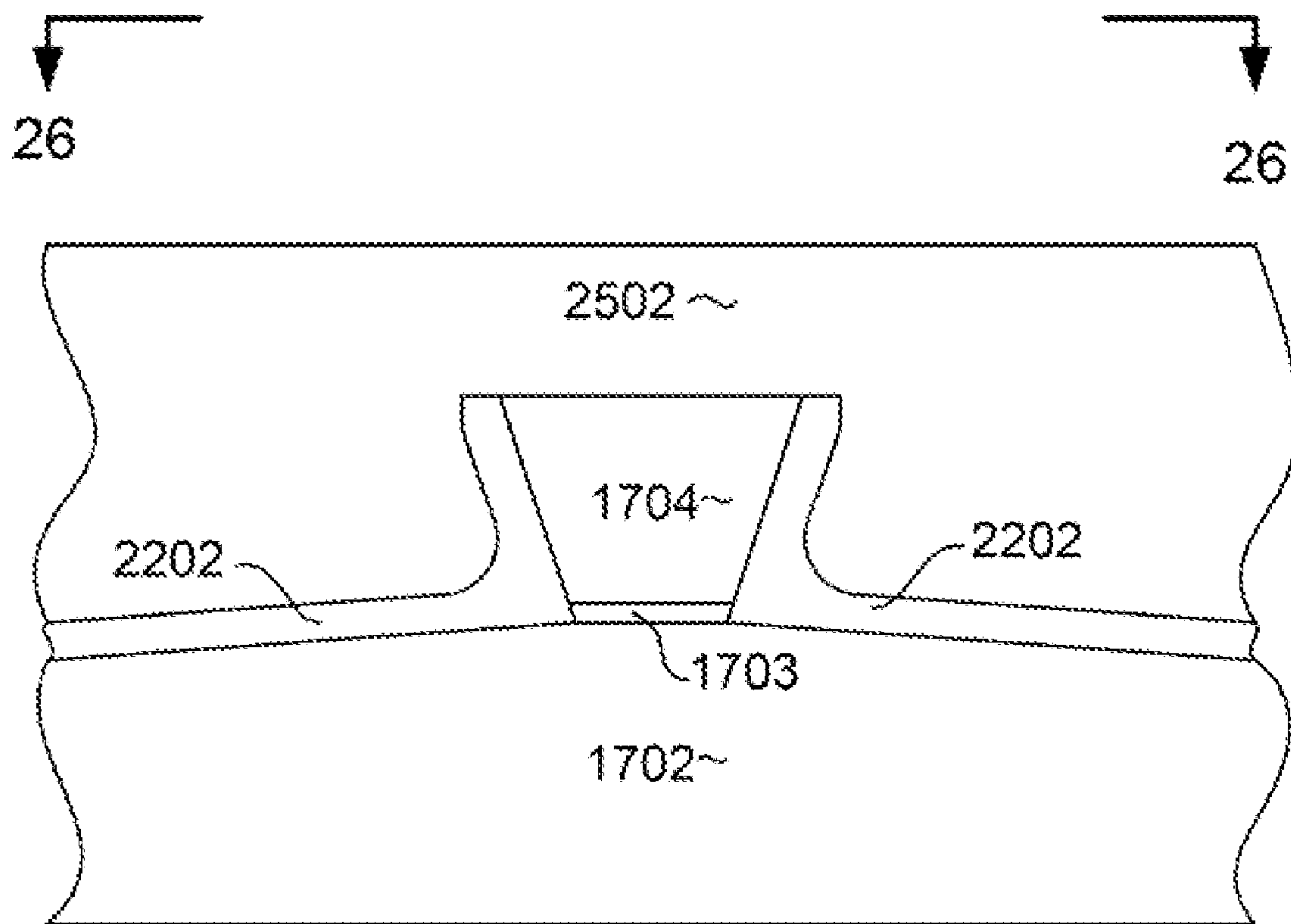


FIG. 25

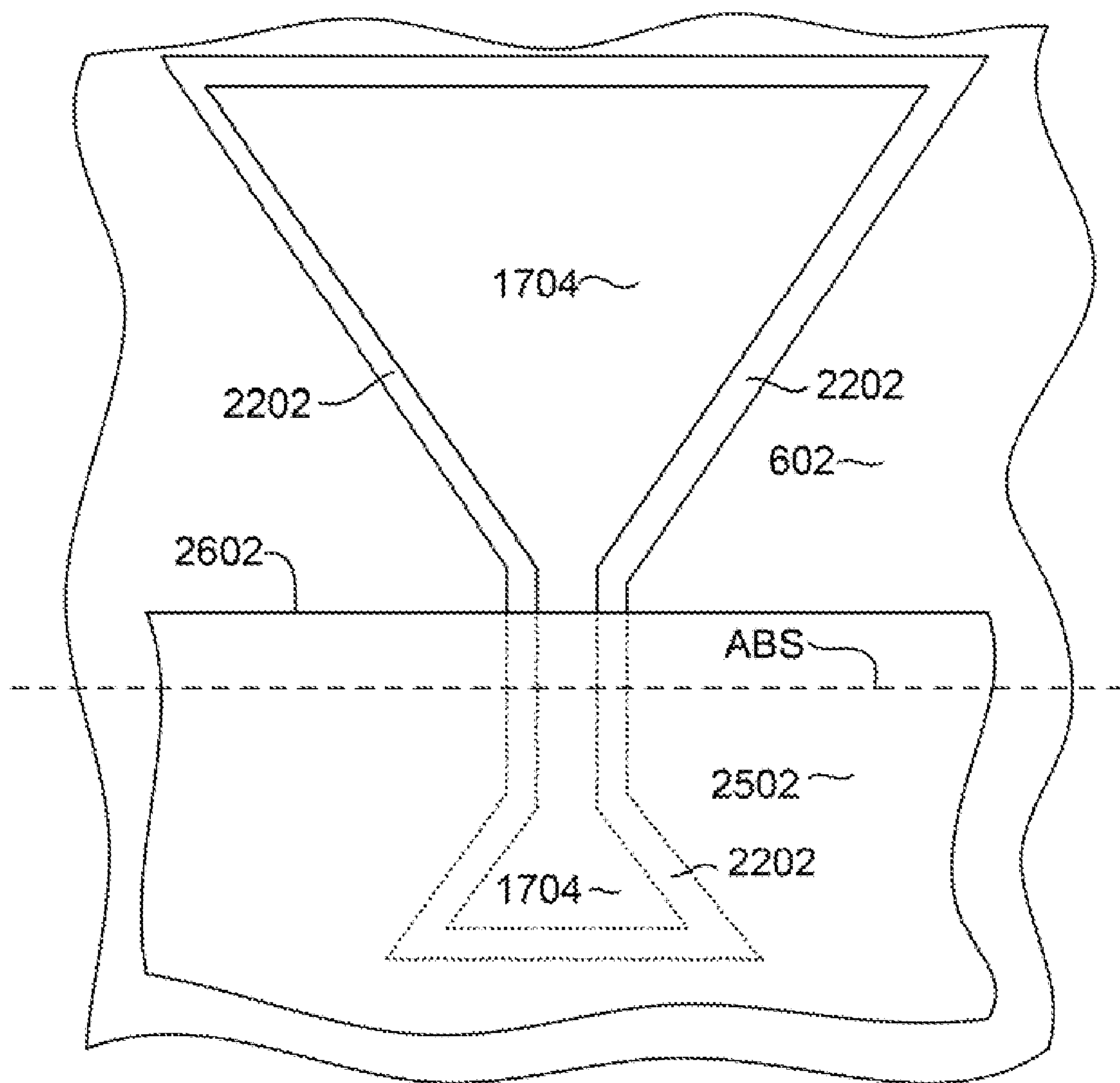


FIG. 26

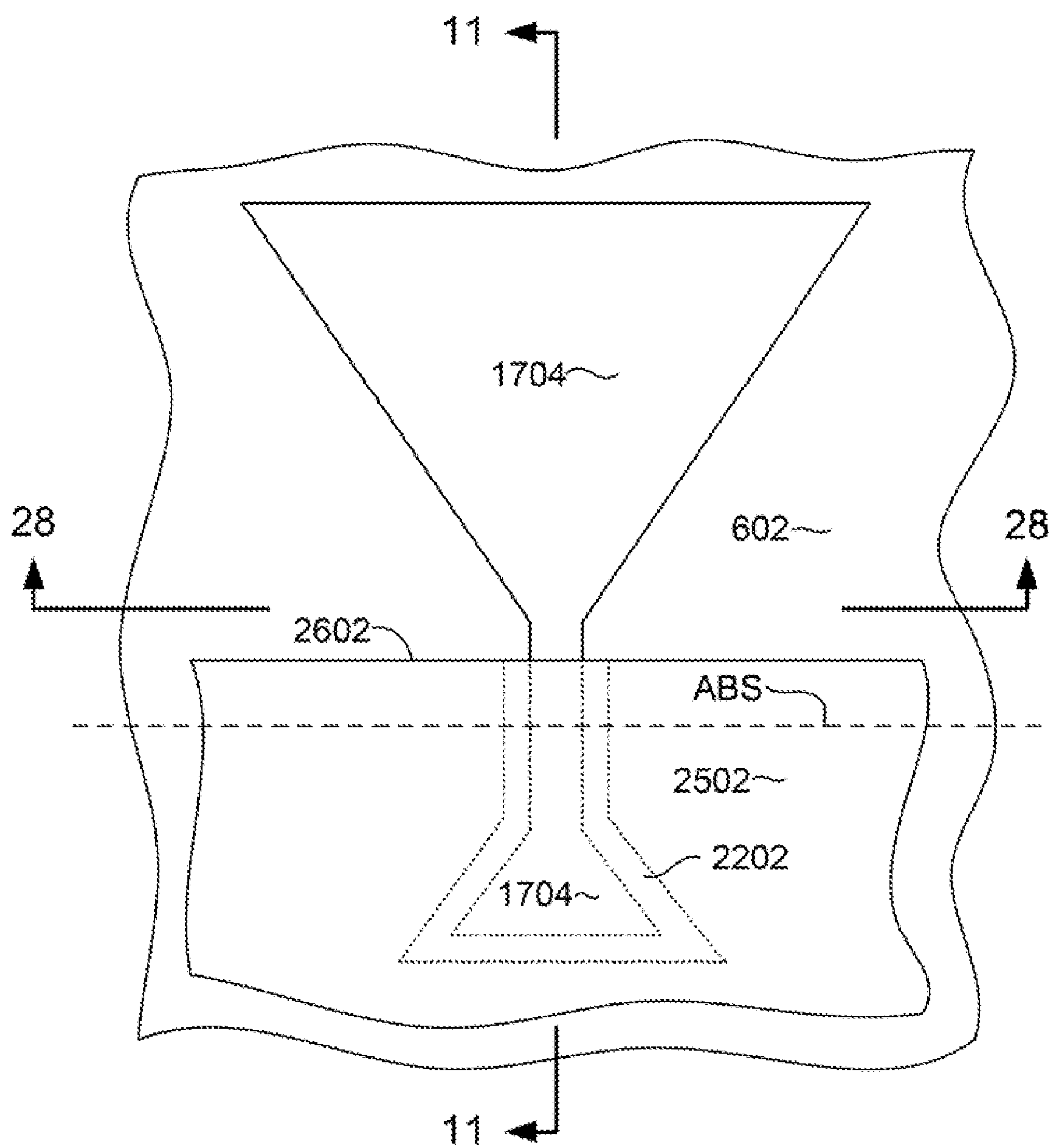


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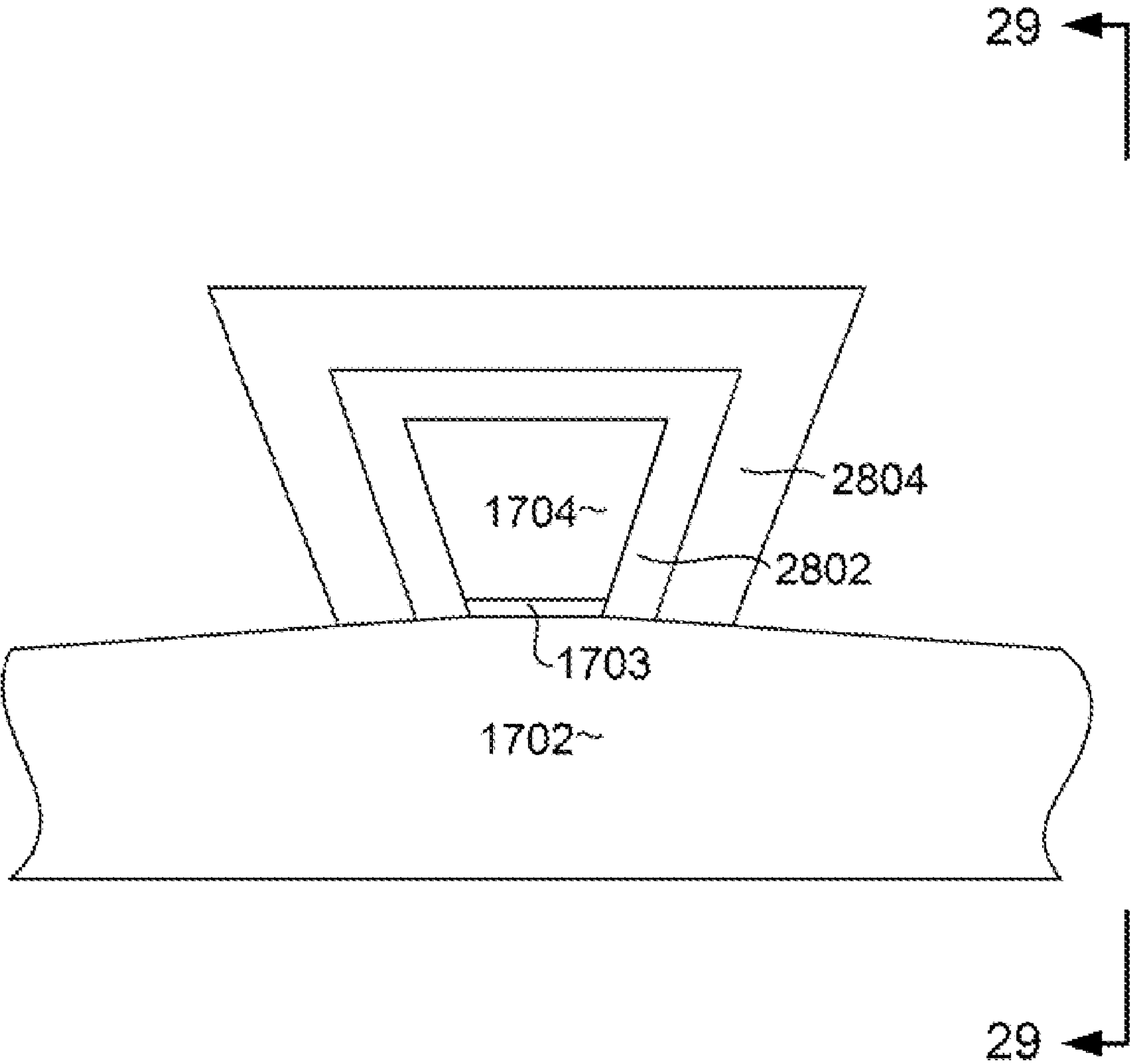


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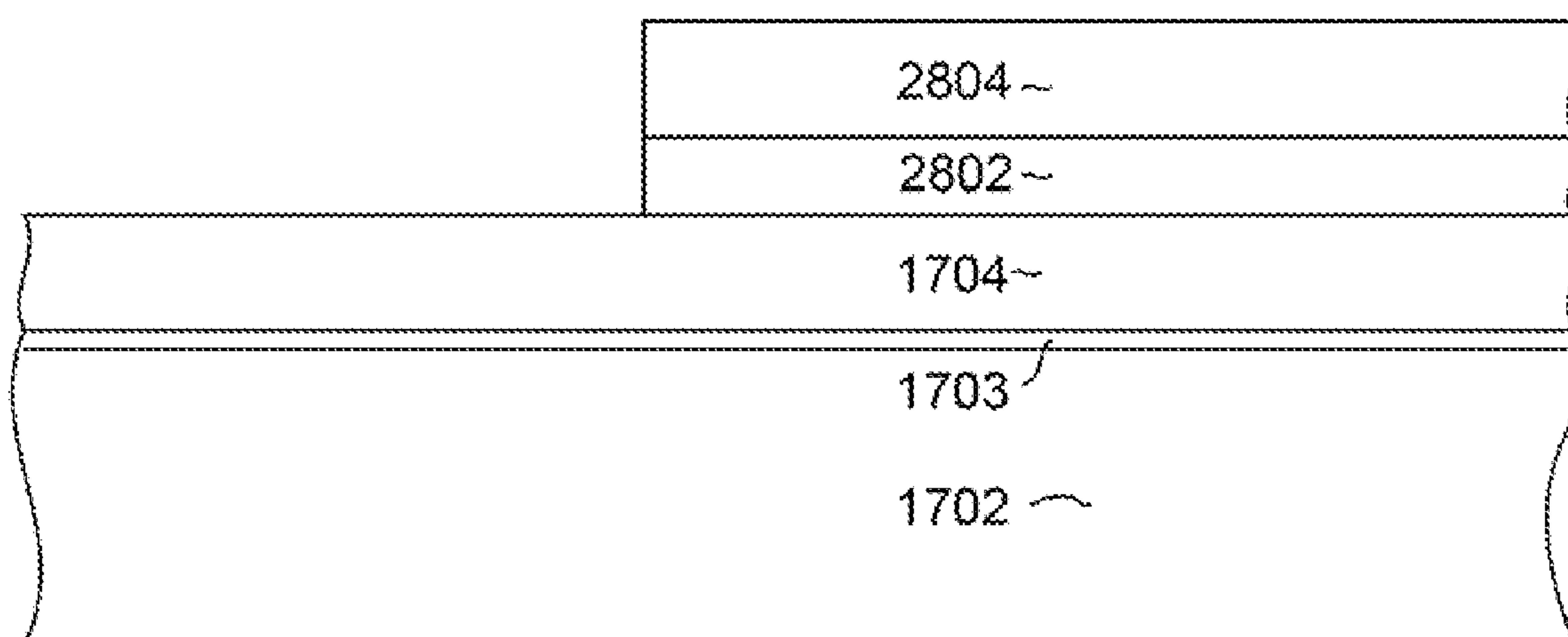


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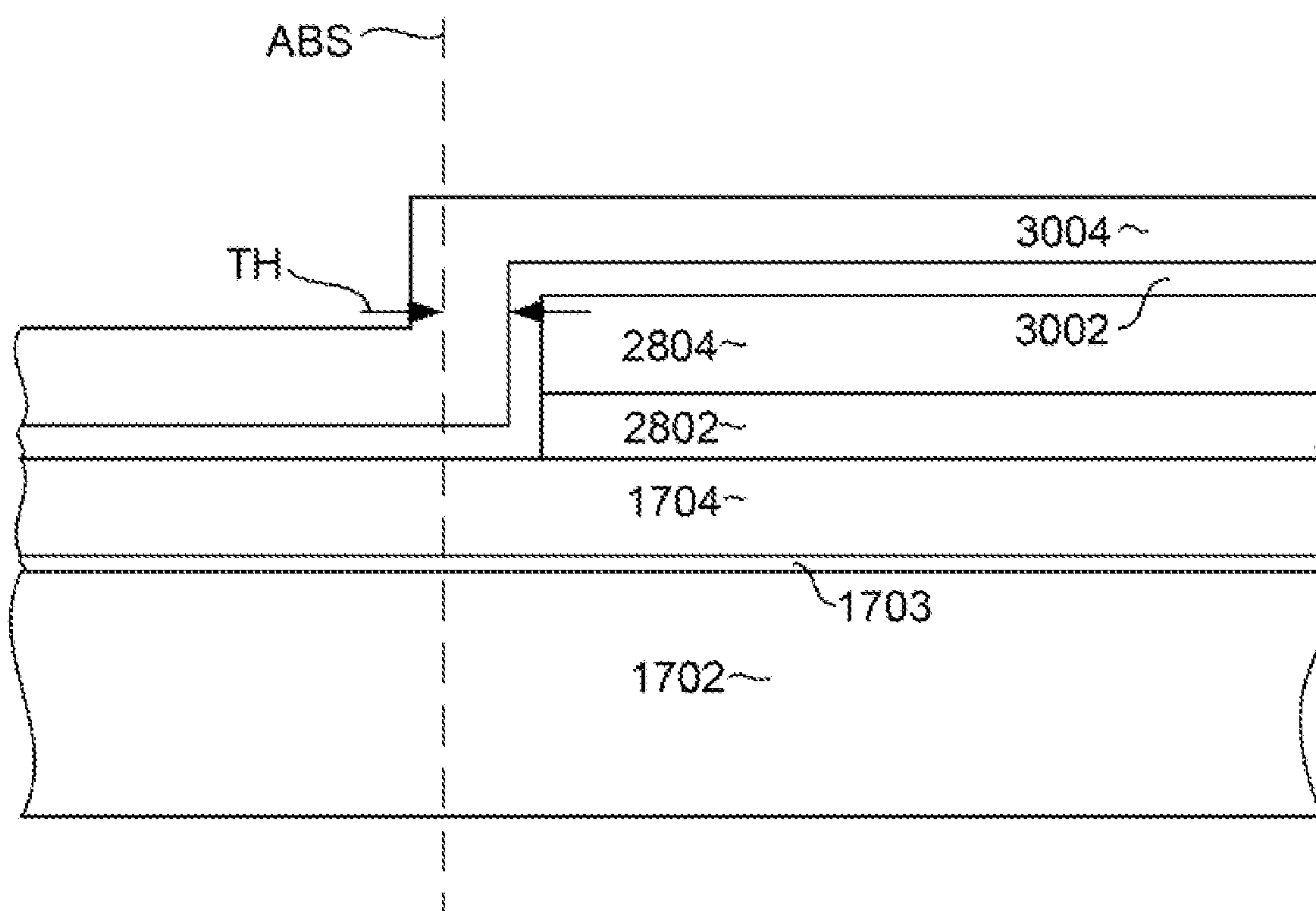


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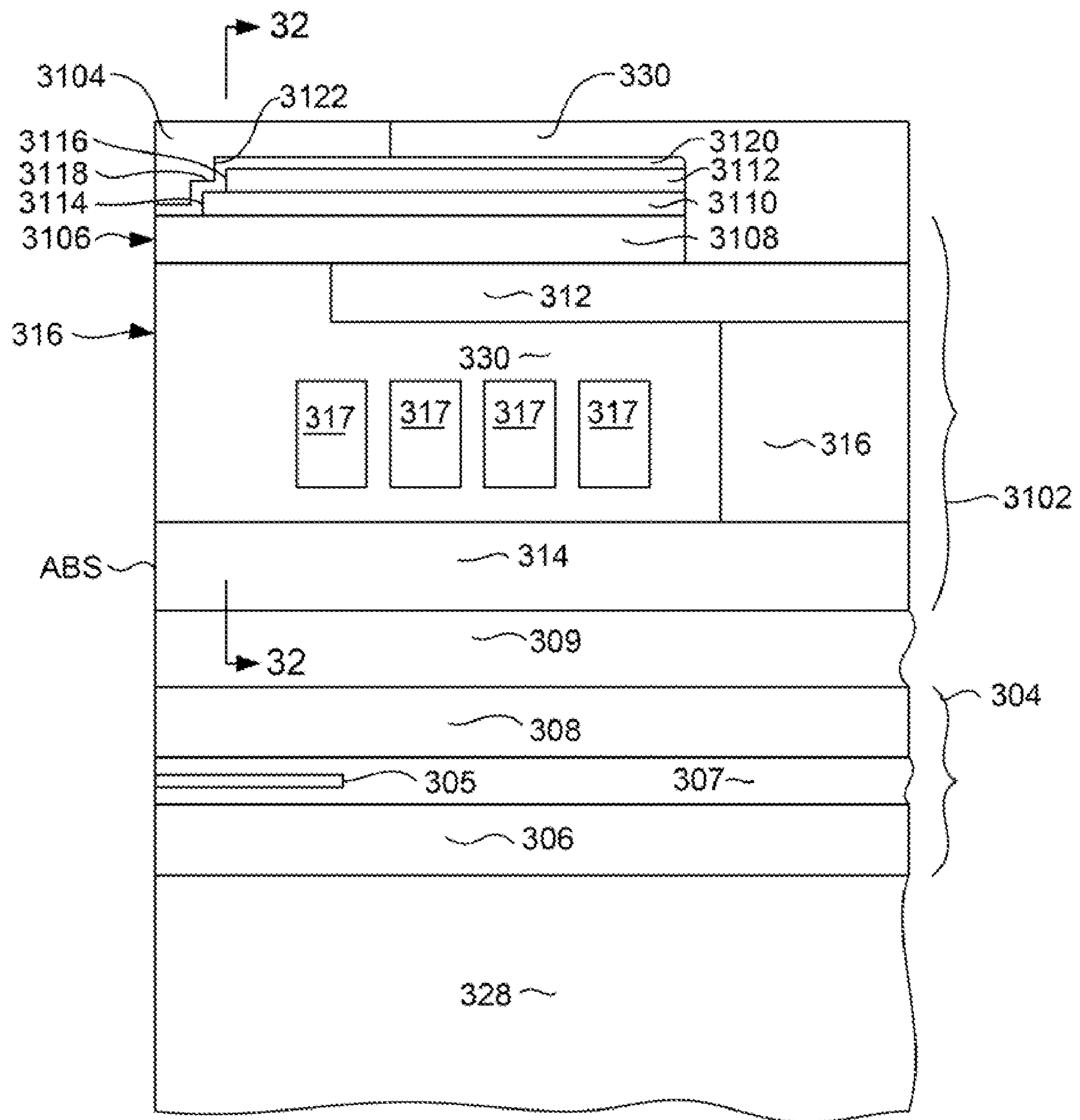


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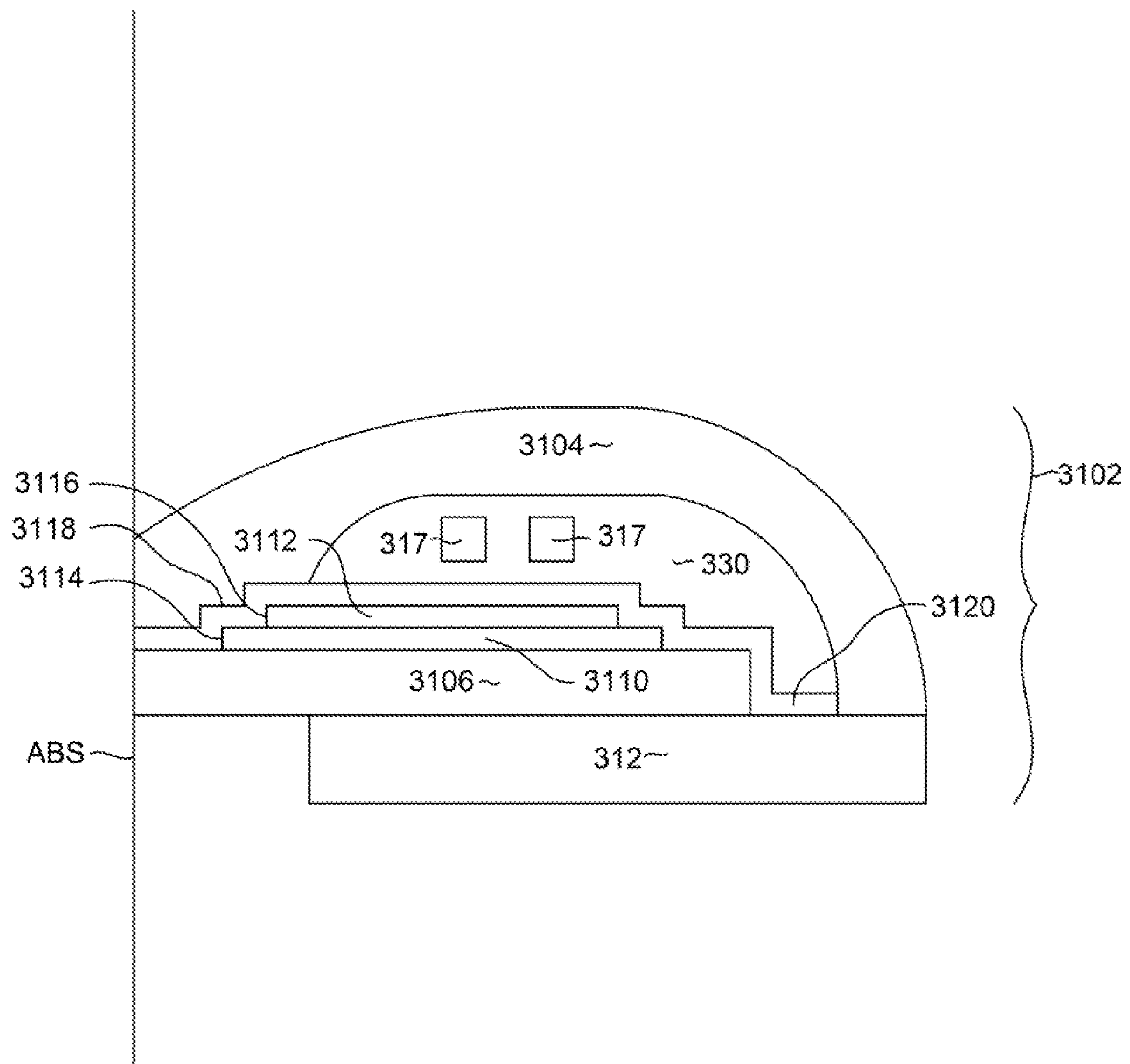


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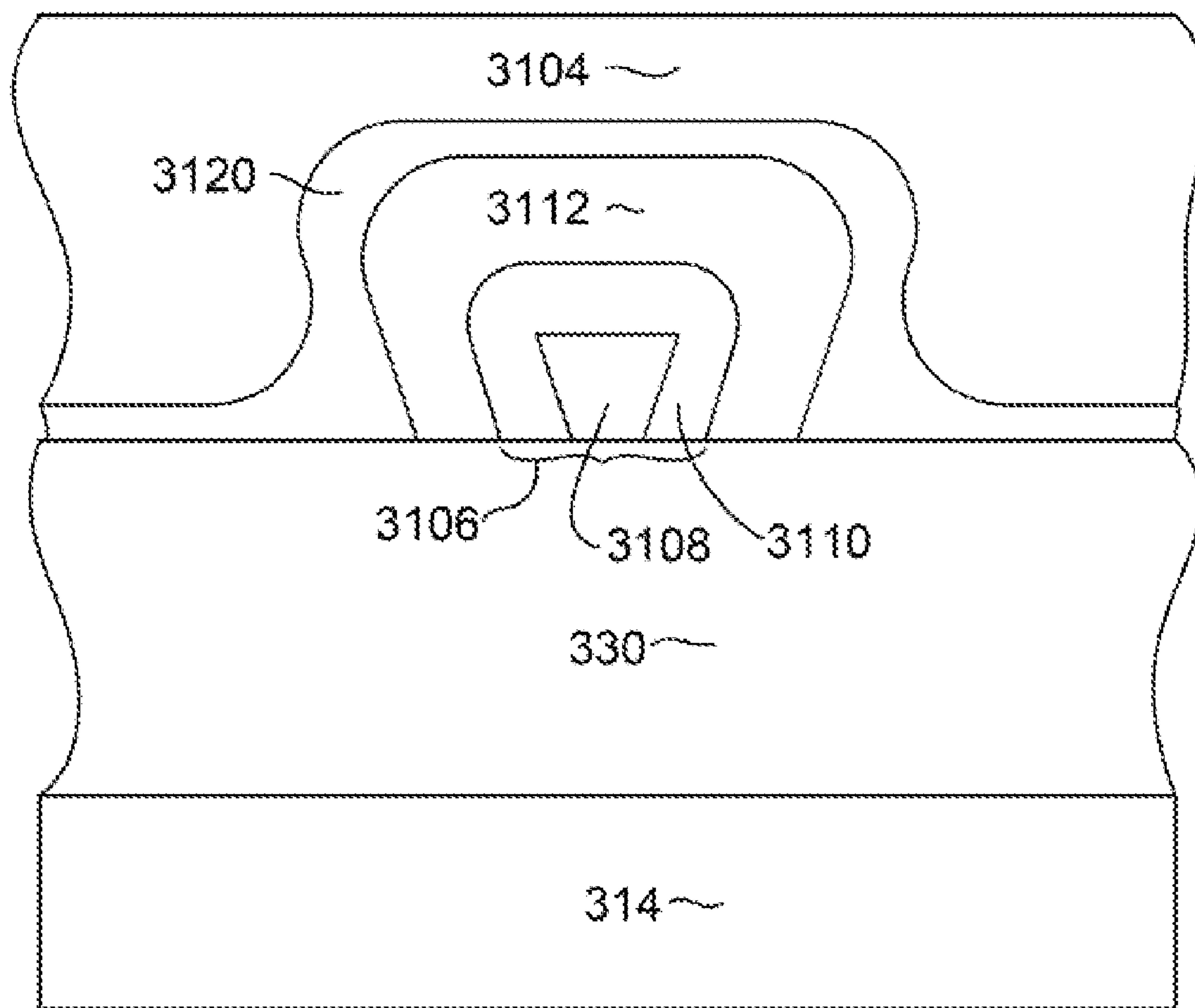


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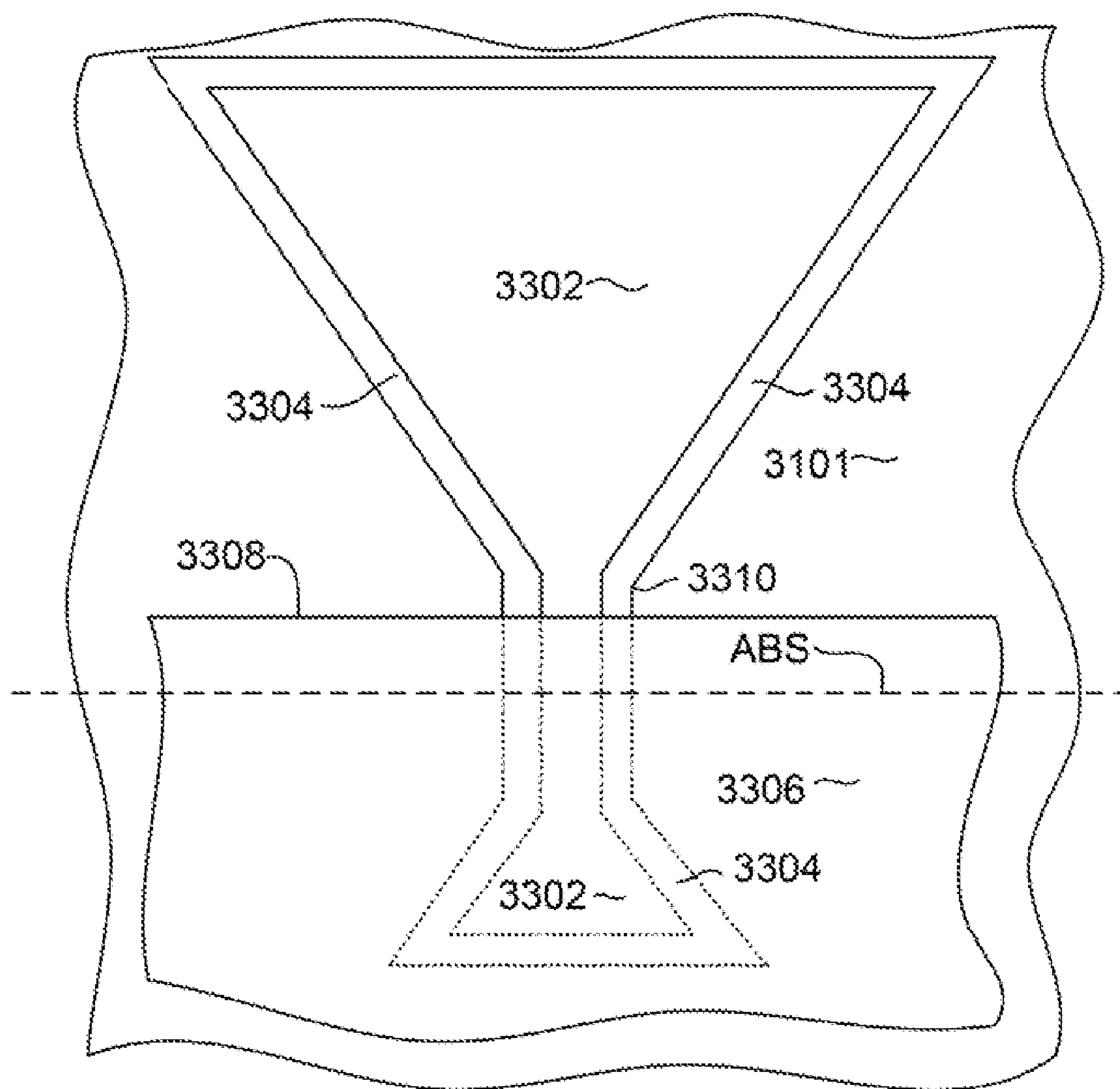


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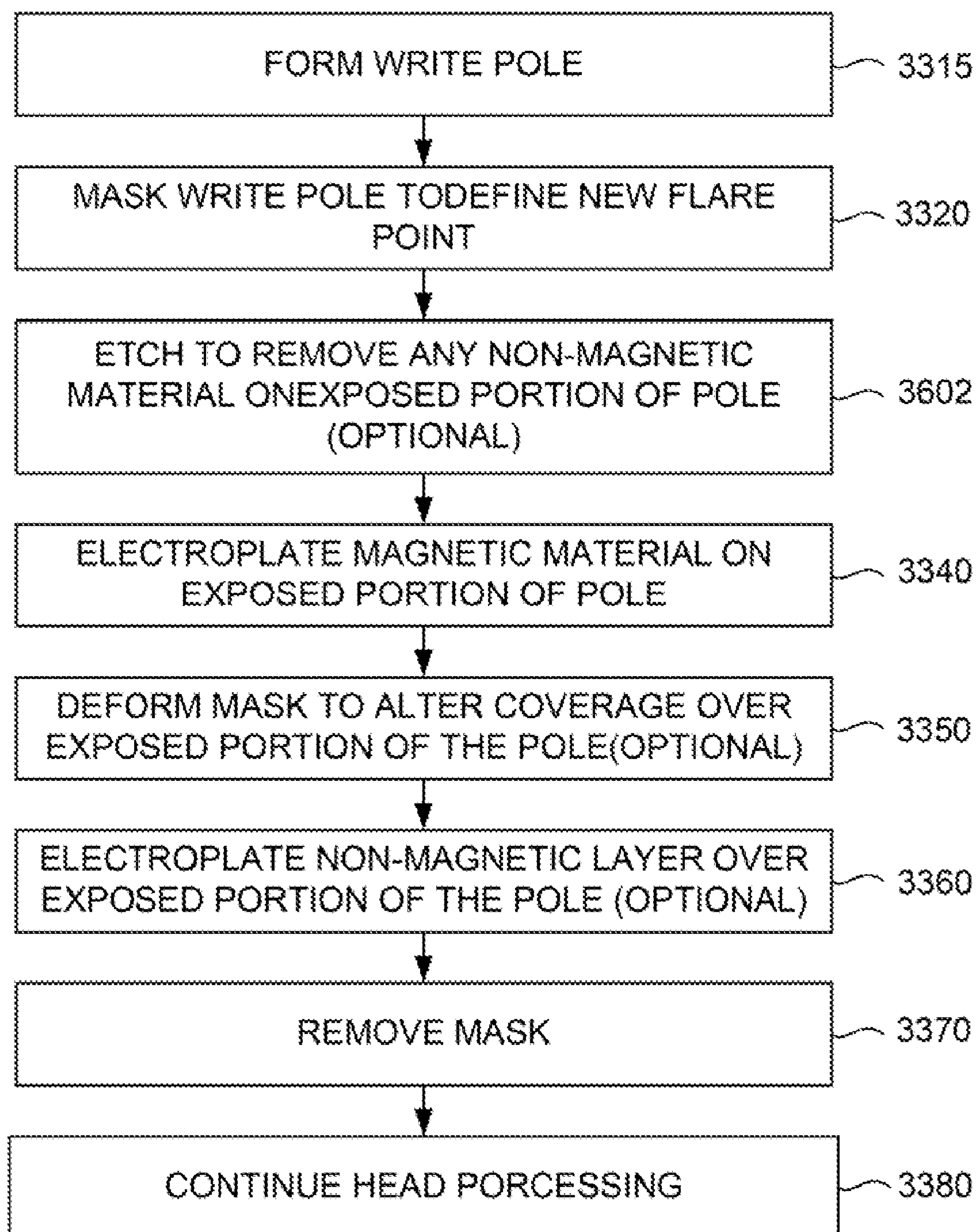


FIG. 33B

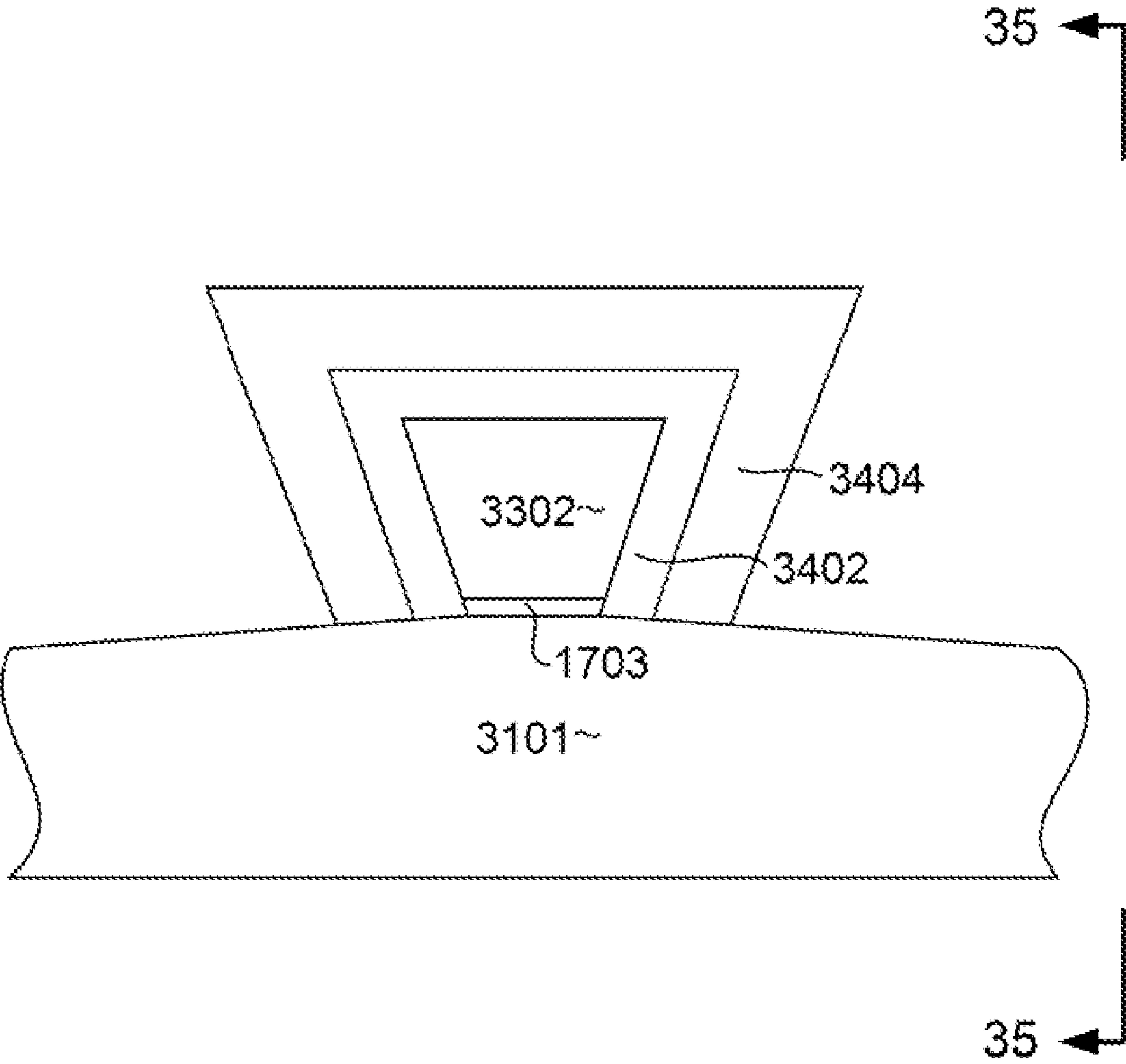


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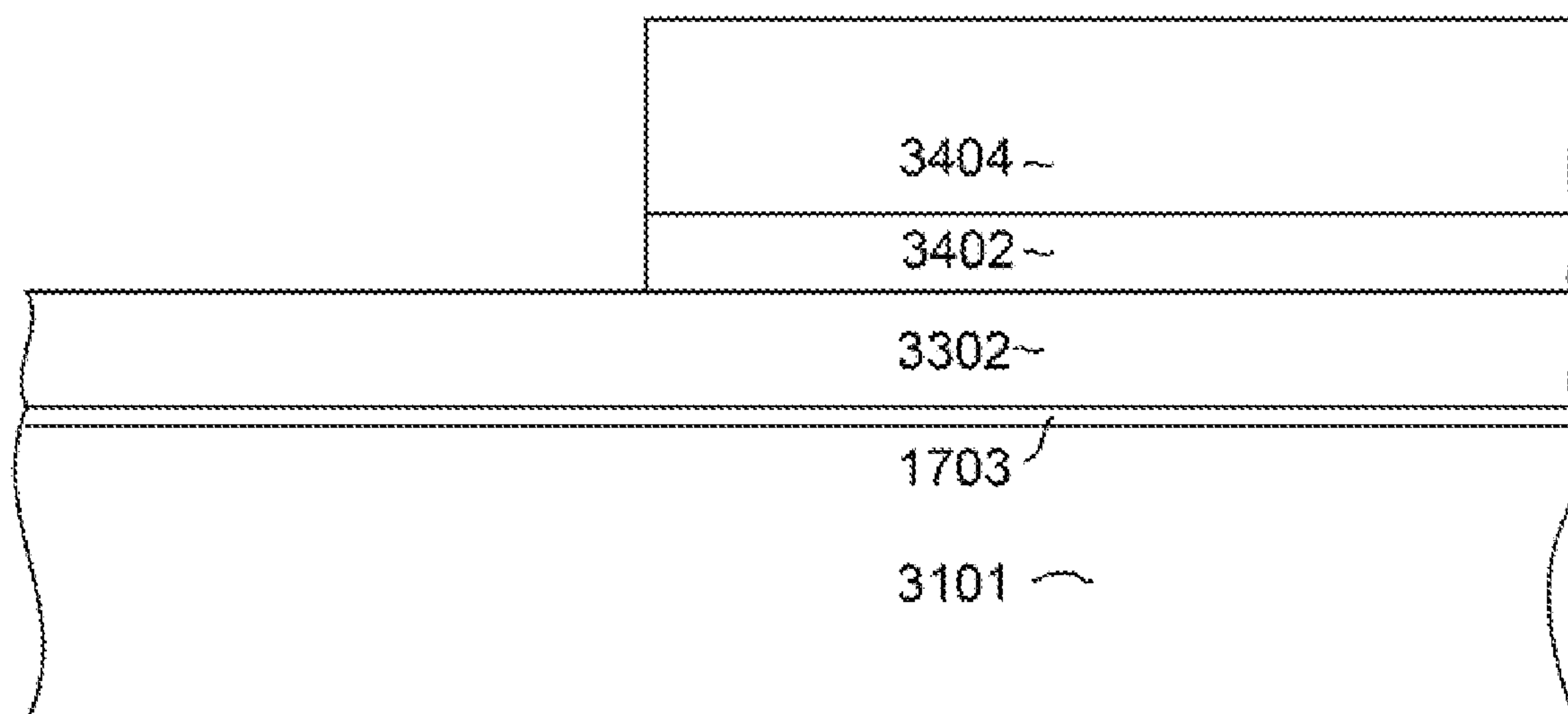


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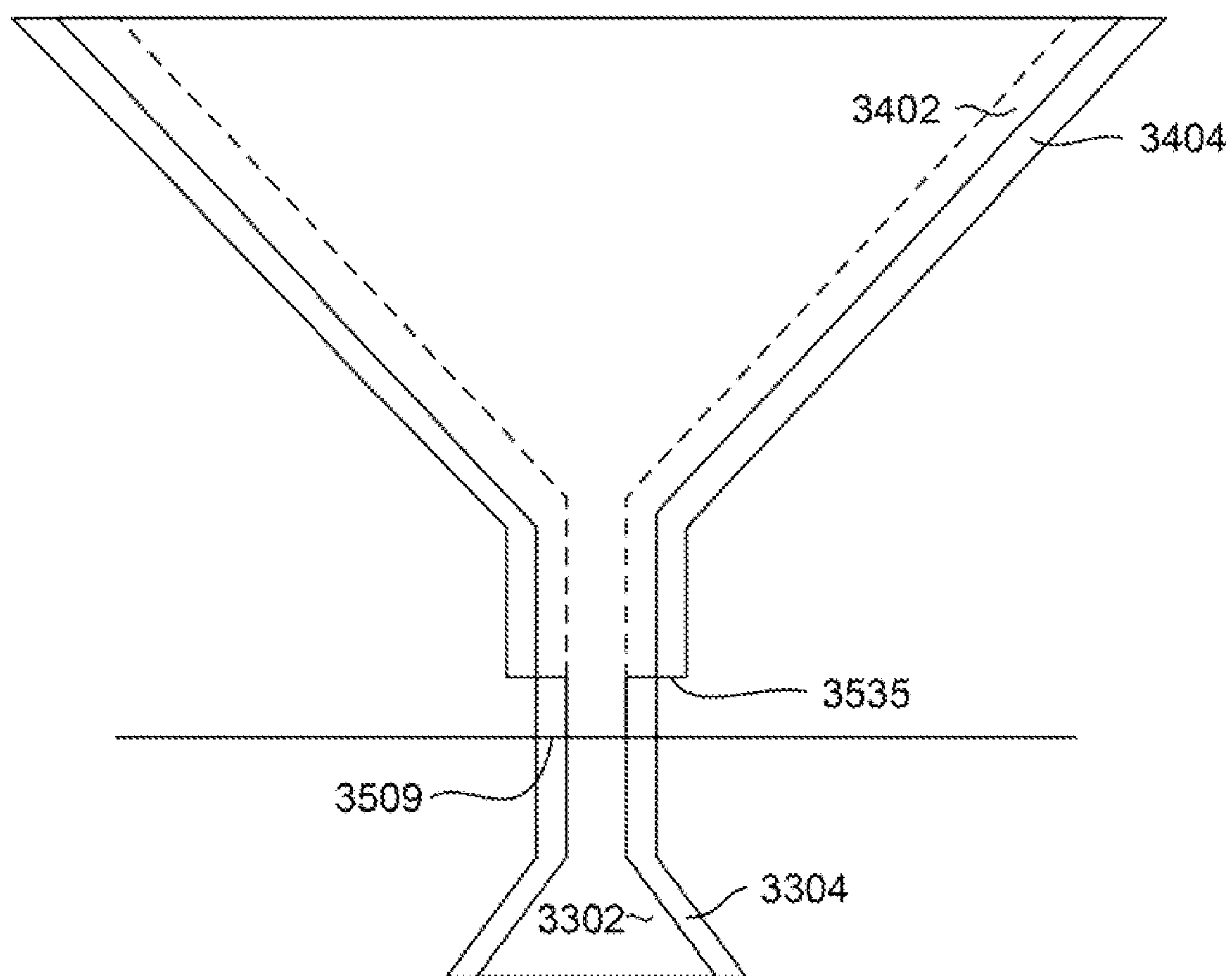


FIG. 35B

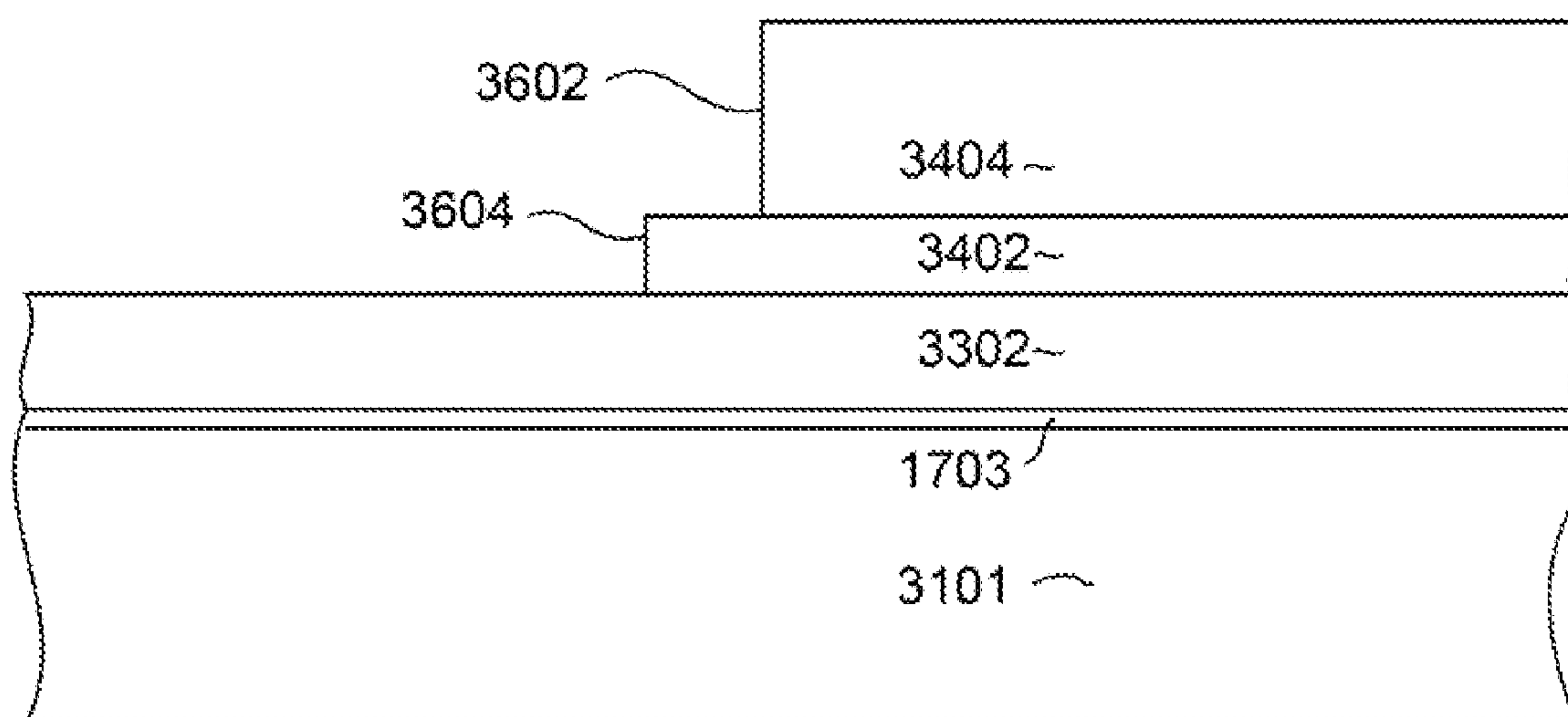


FIG. 36

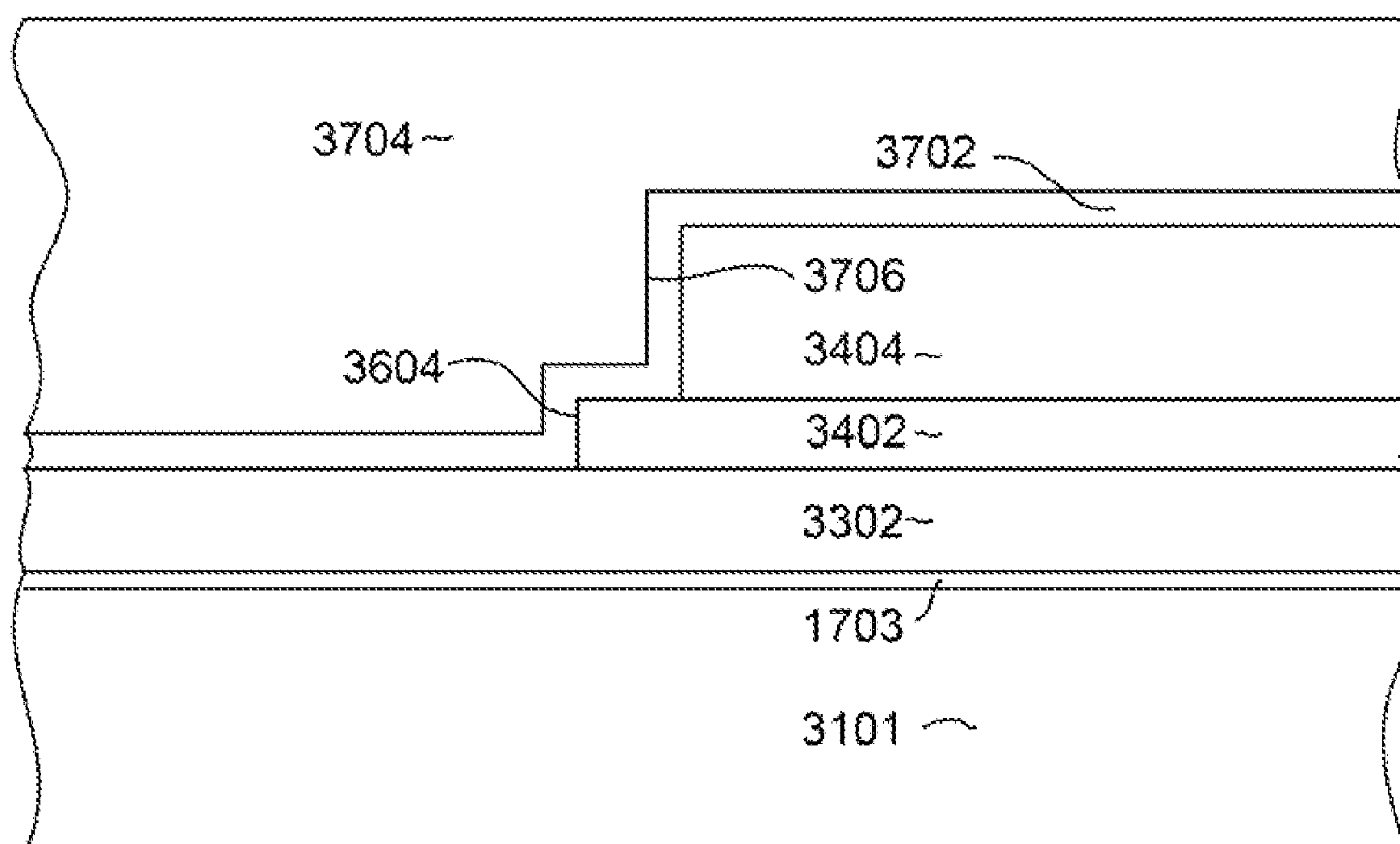


FIG. 37

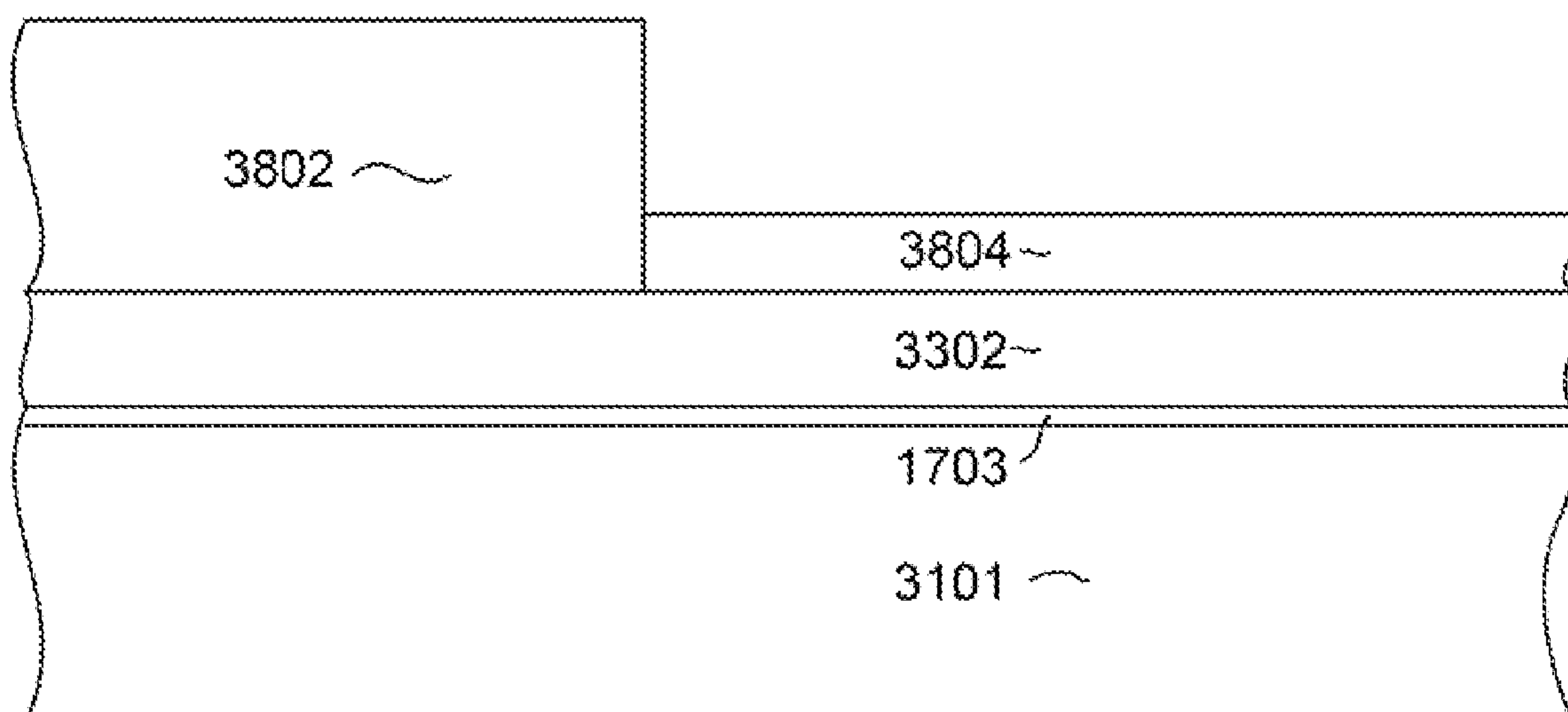


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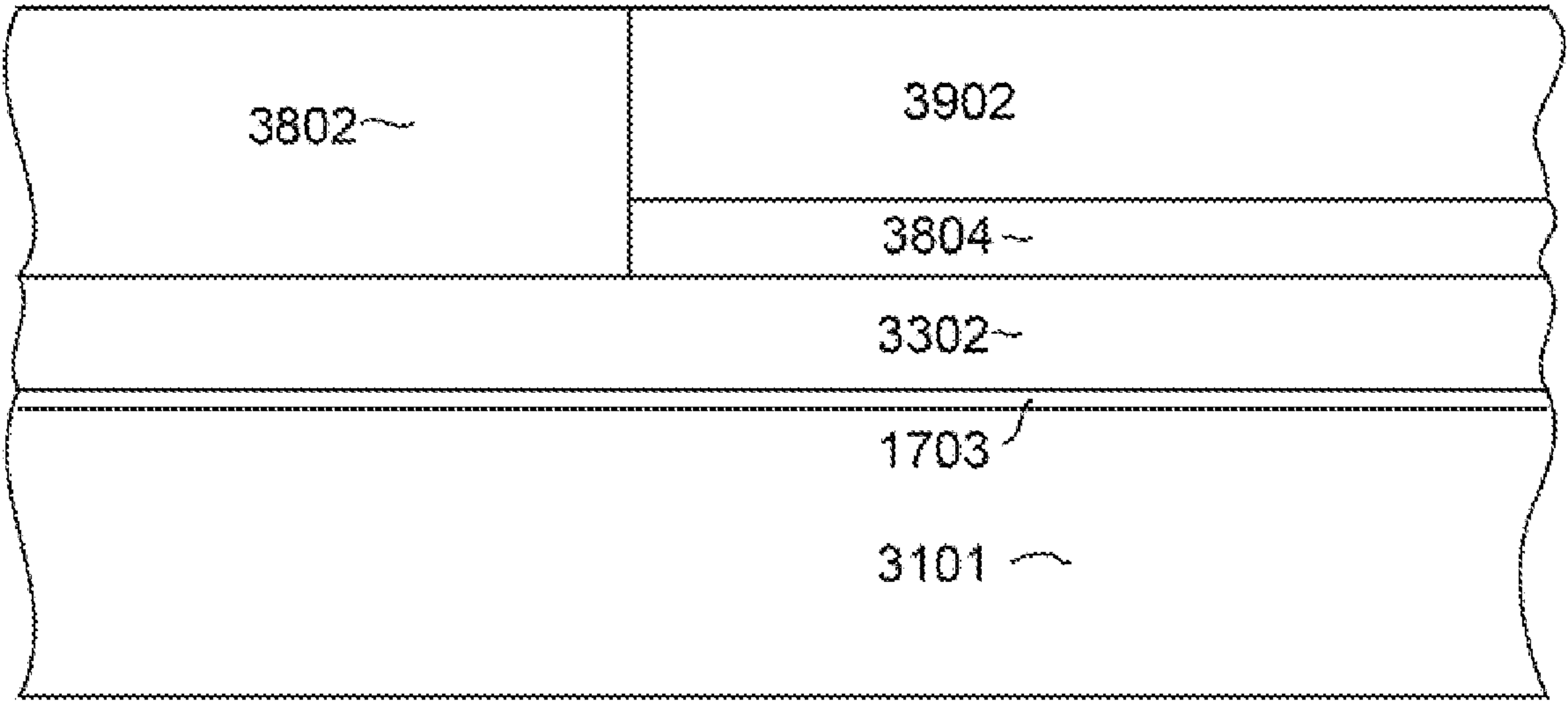


FIG. 39

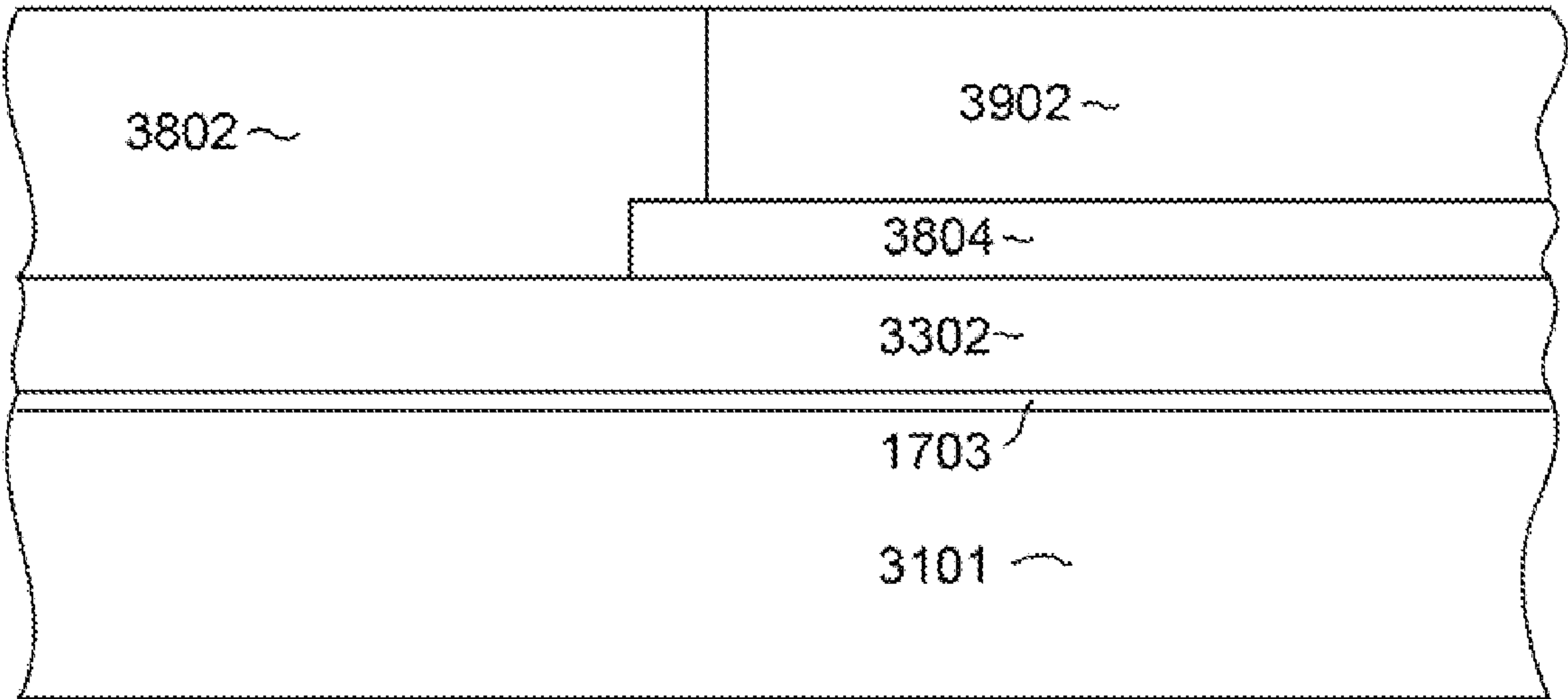


FIG. 40

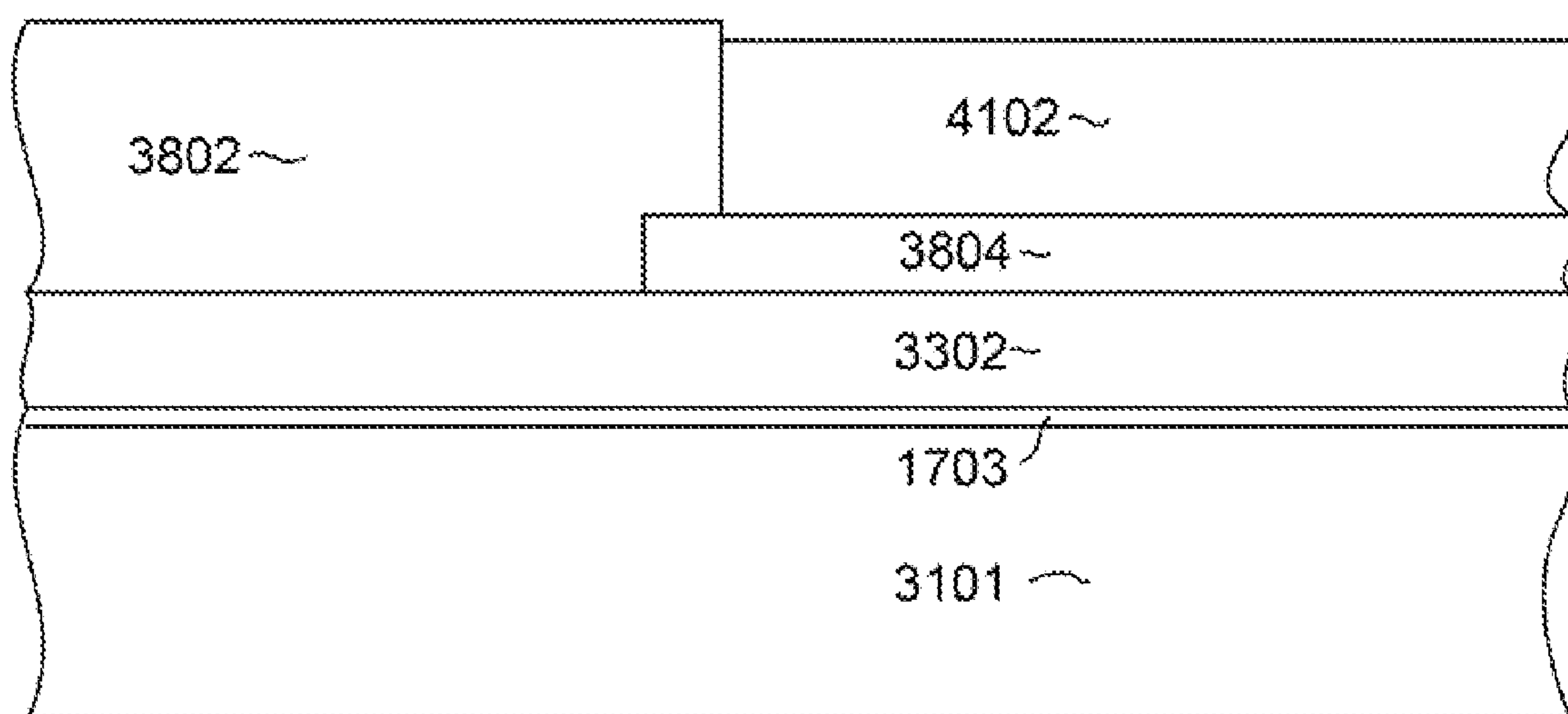


FIG. 41A

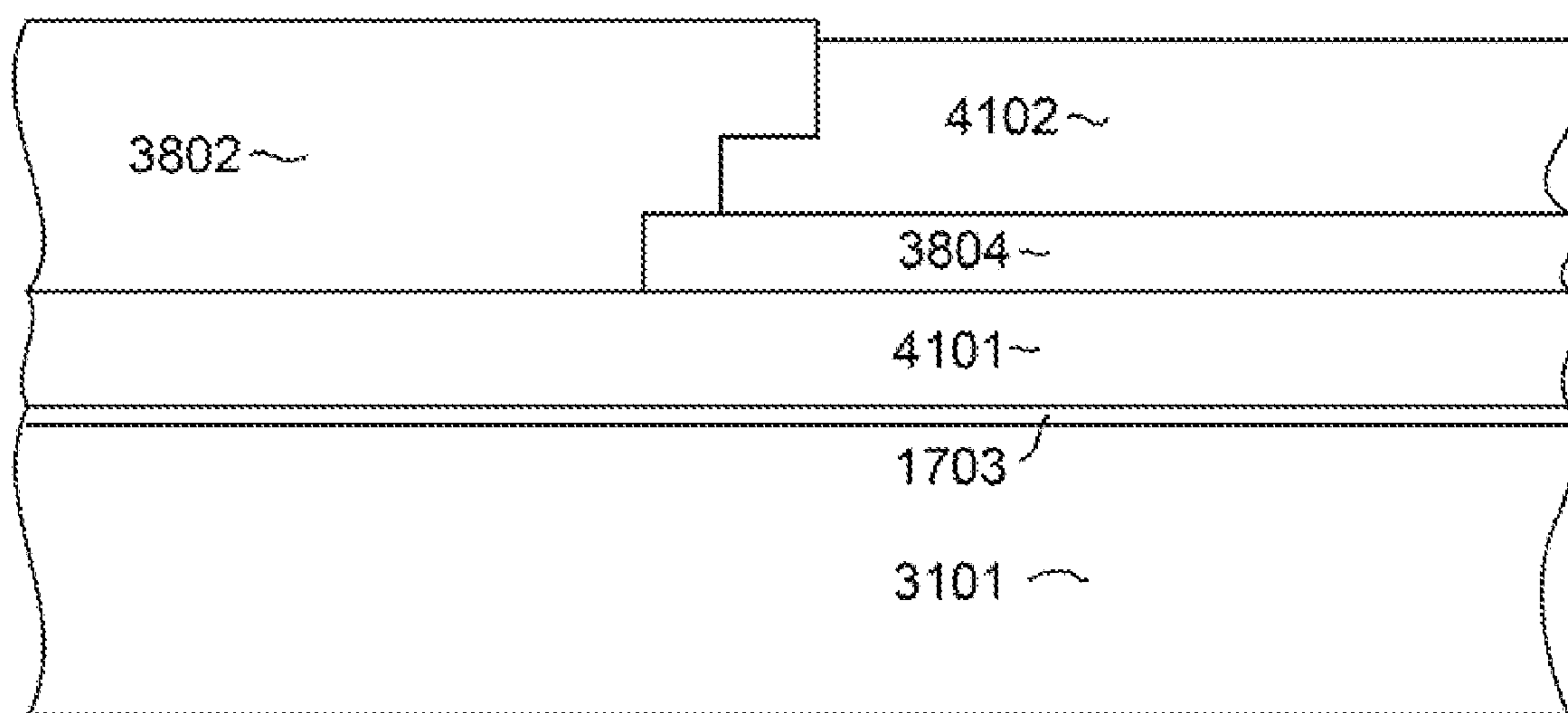


FIG. 41B

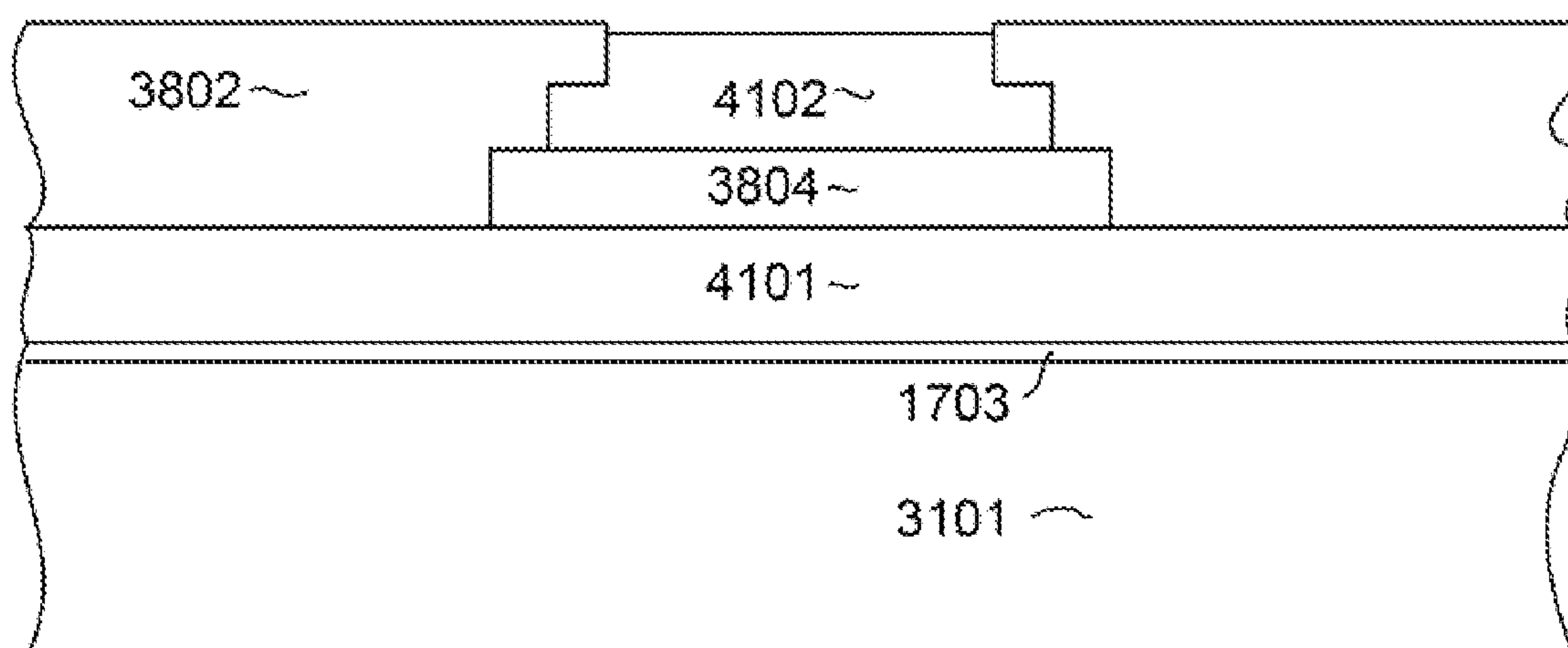


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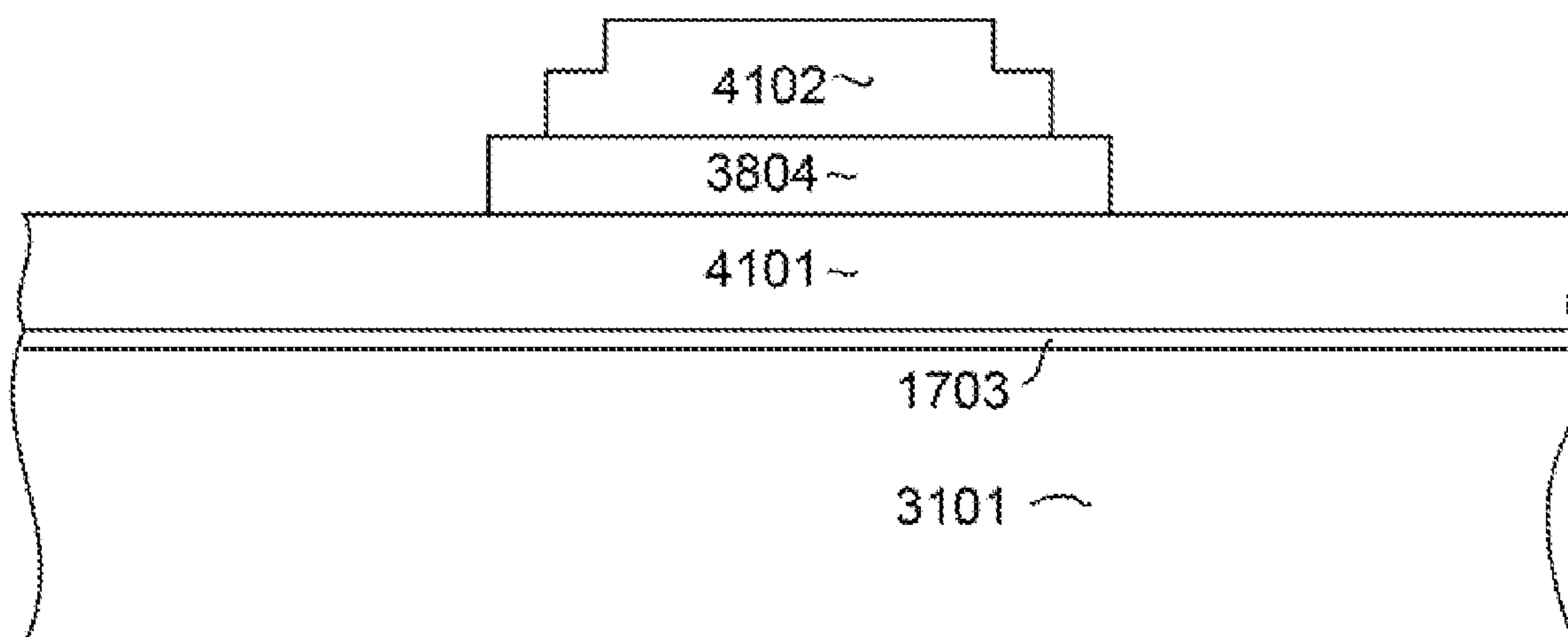


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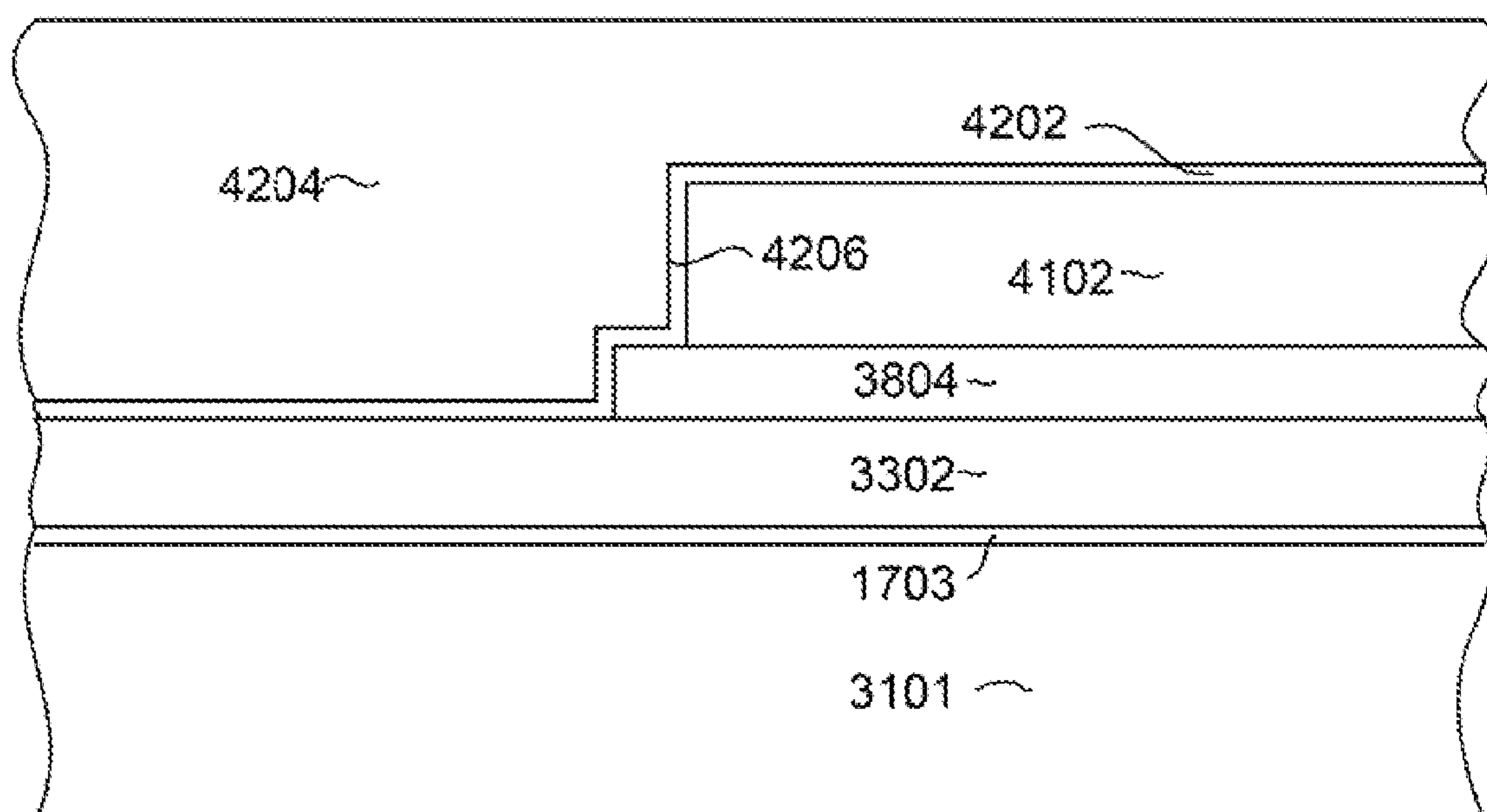


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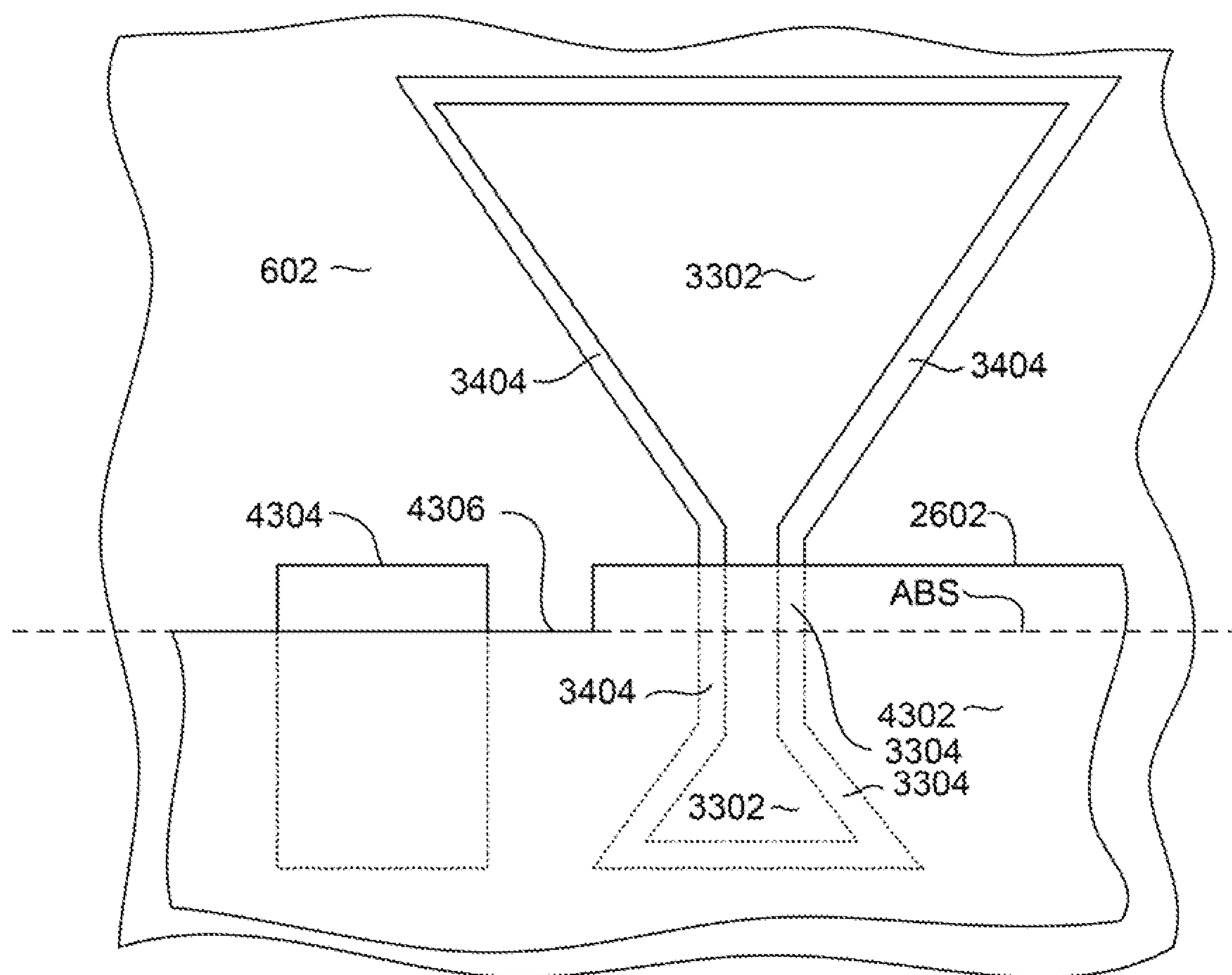


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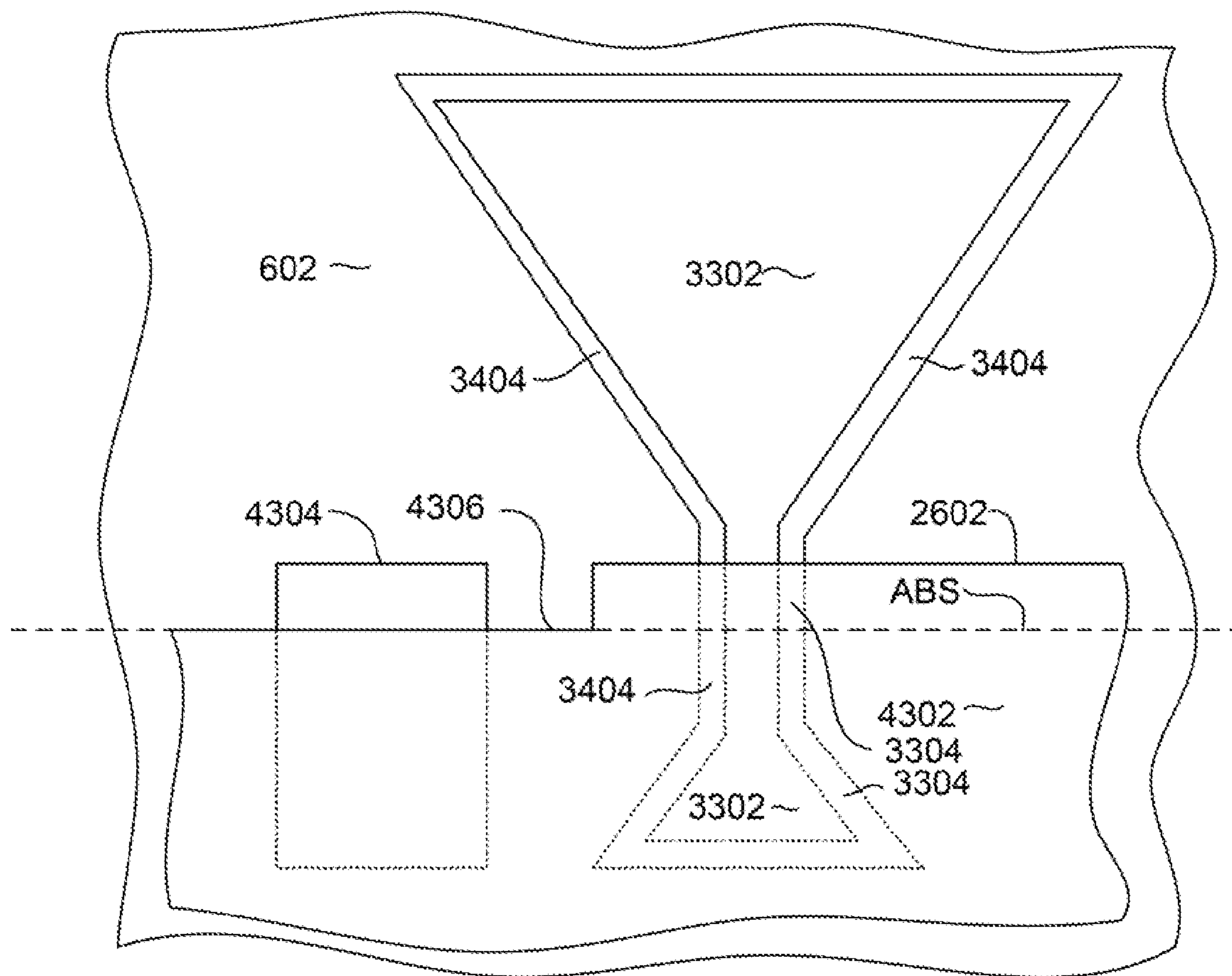


FIG. 43A

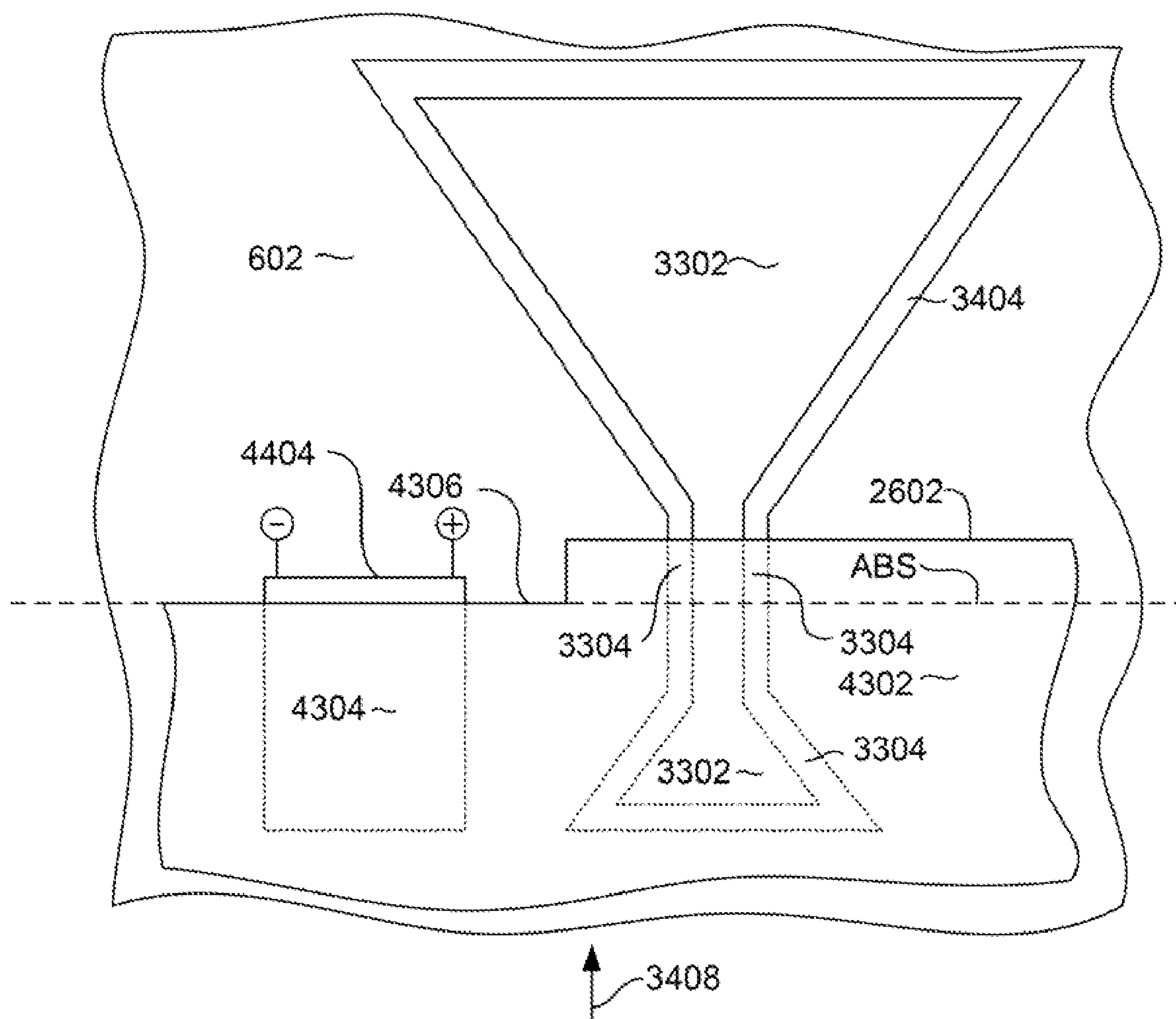


FIG. 44

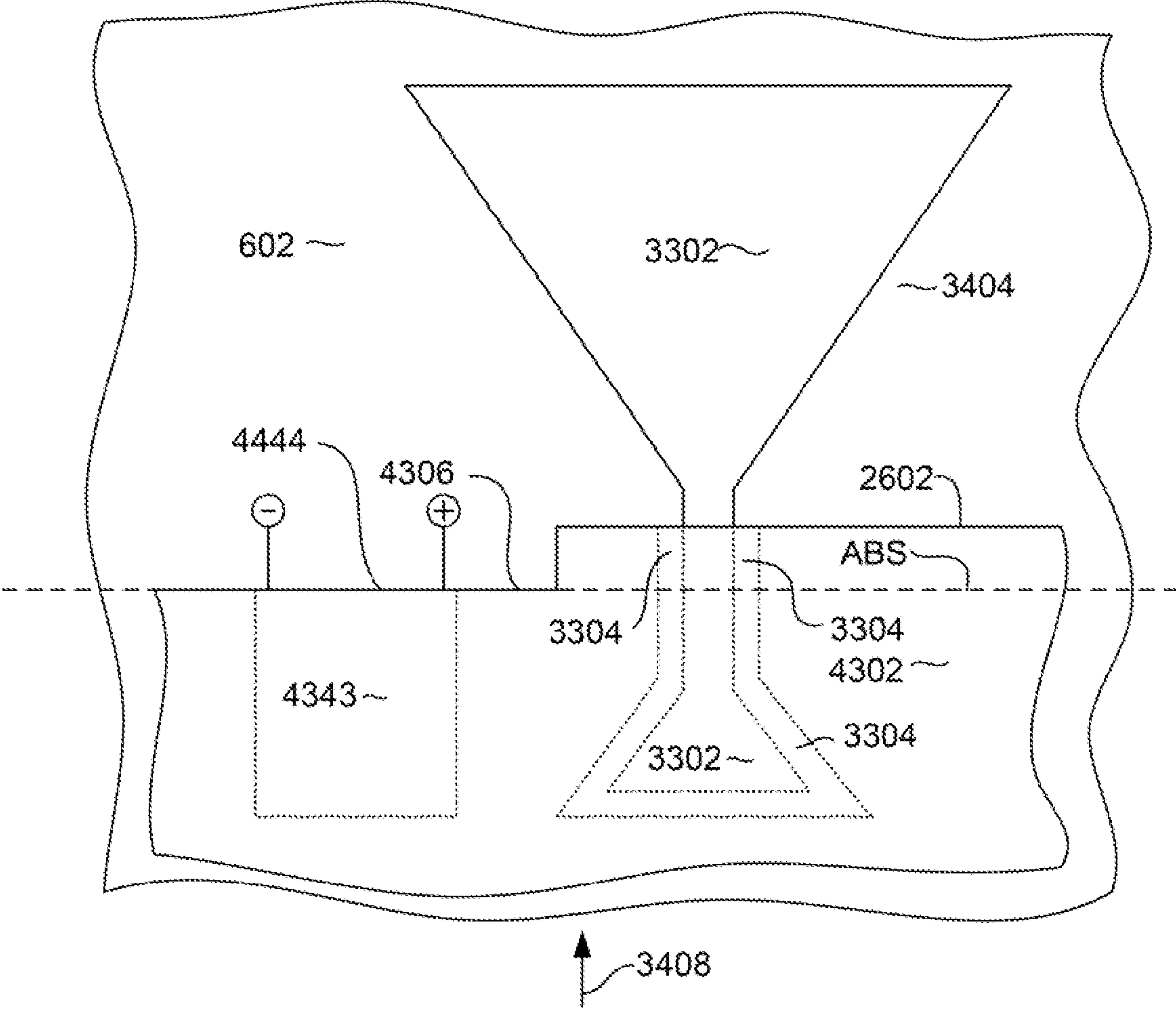


FIG. 44A

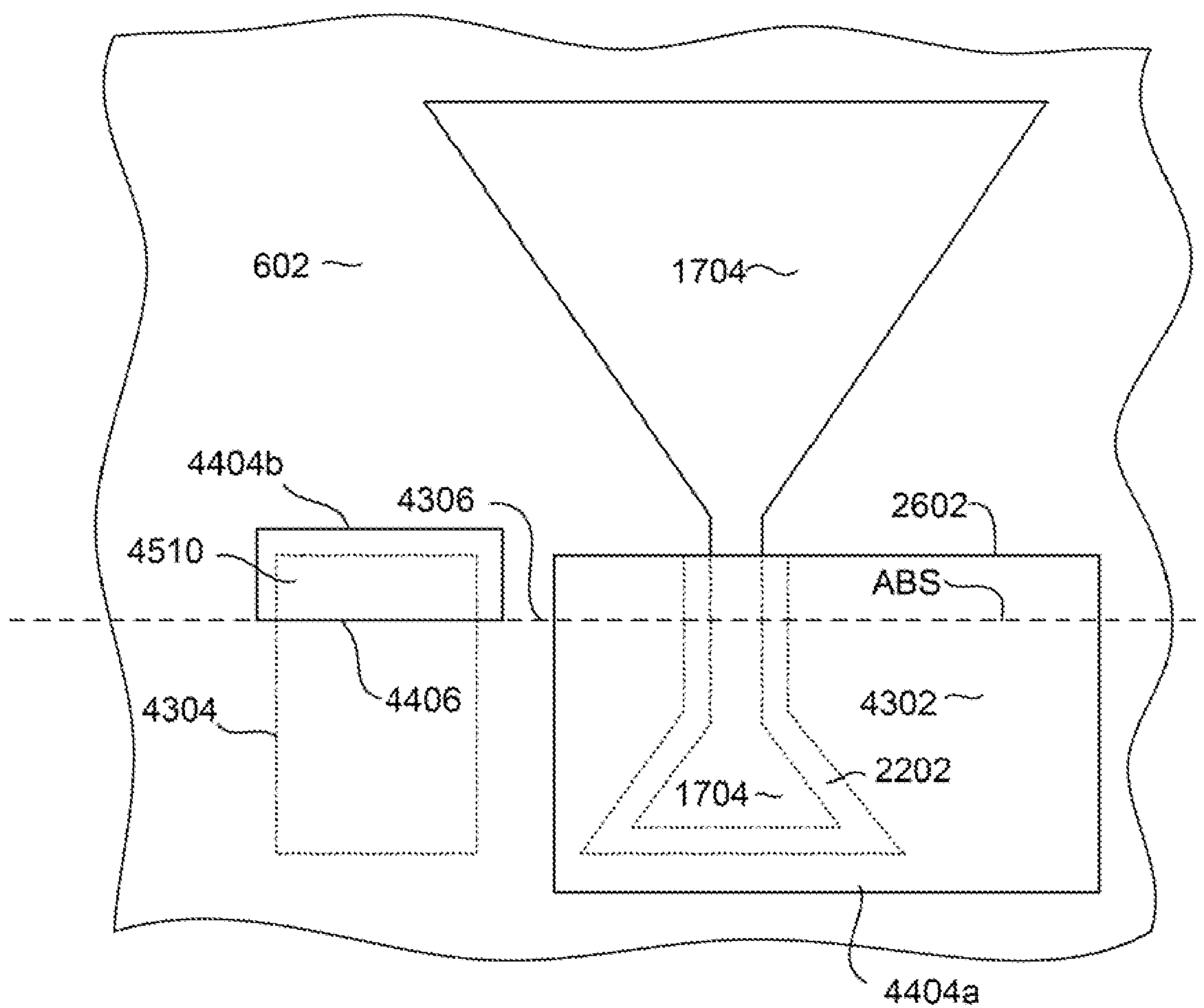


FIG. 45

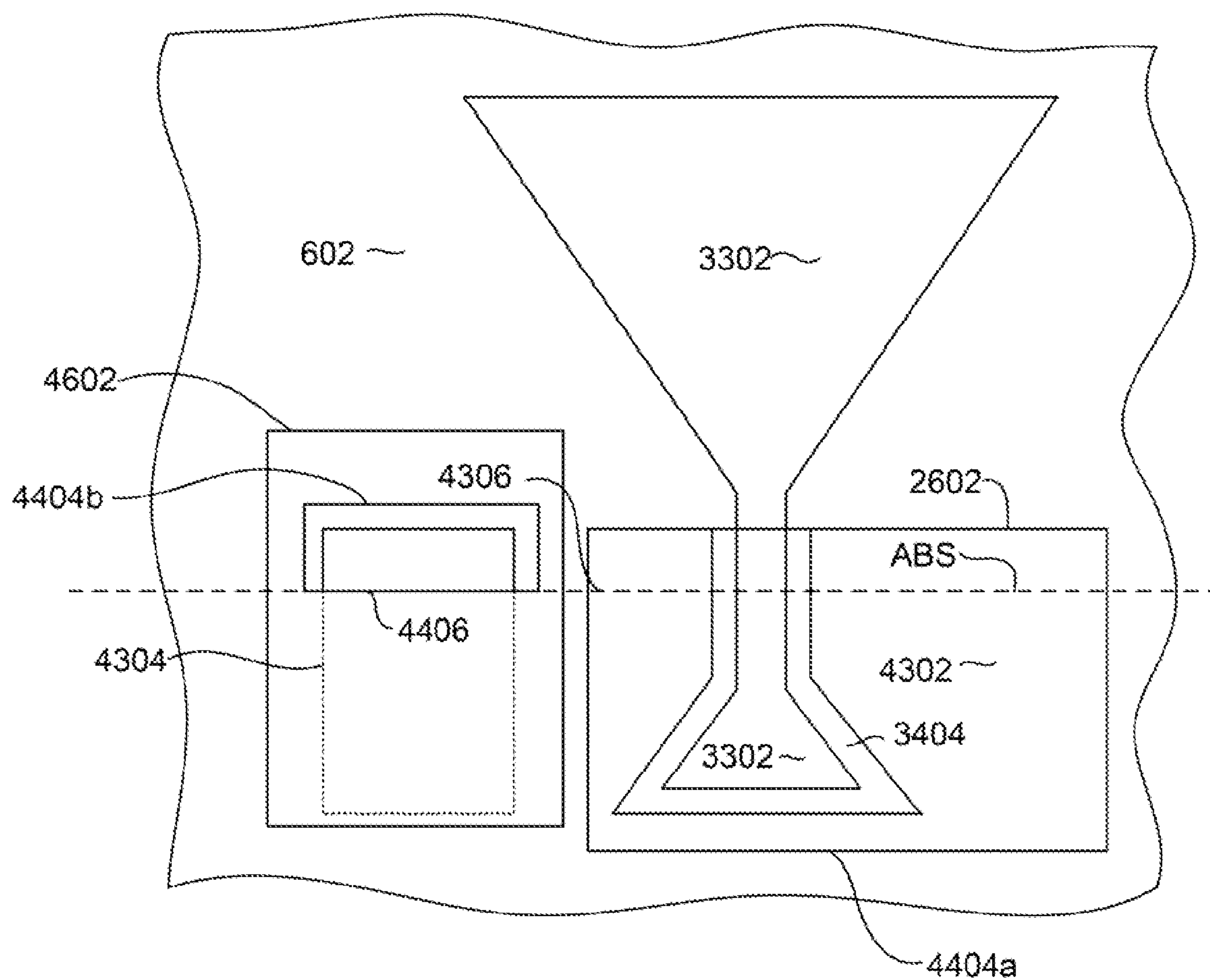


FIG. 46

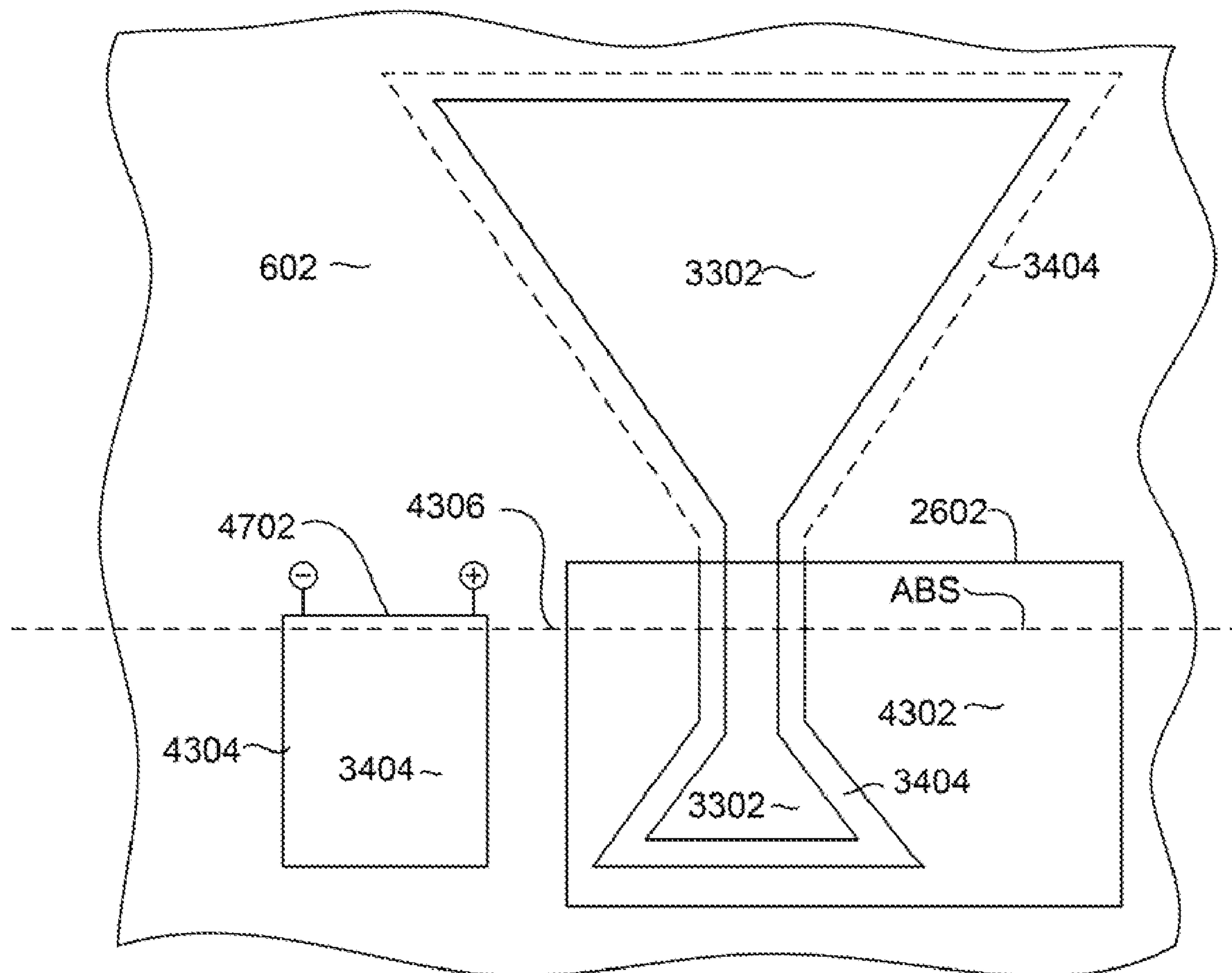


FIG. 47

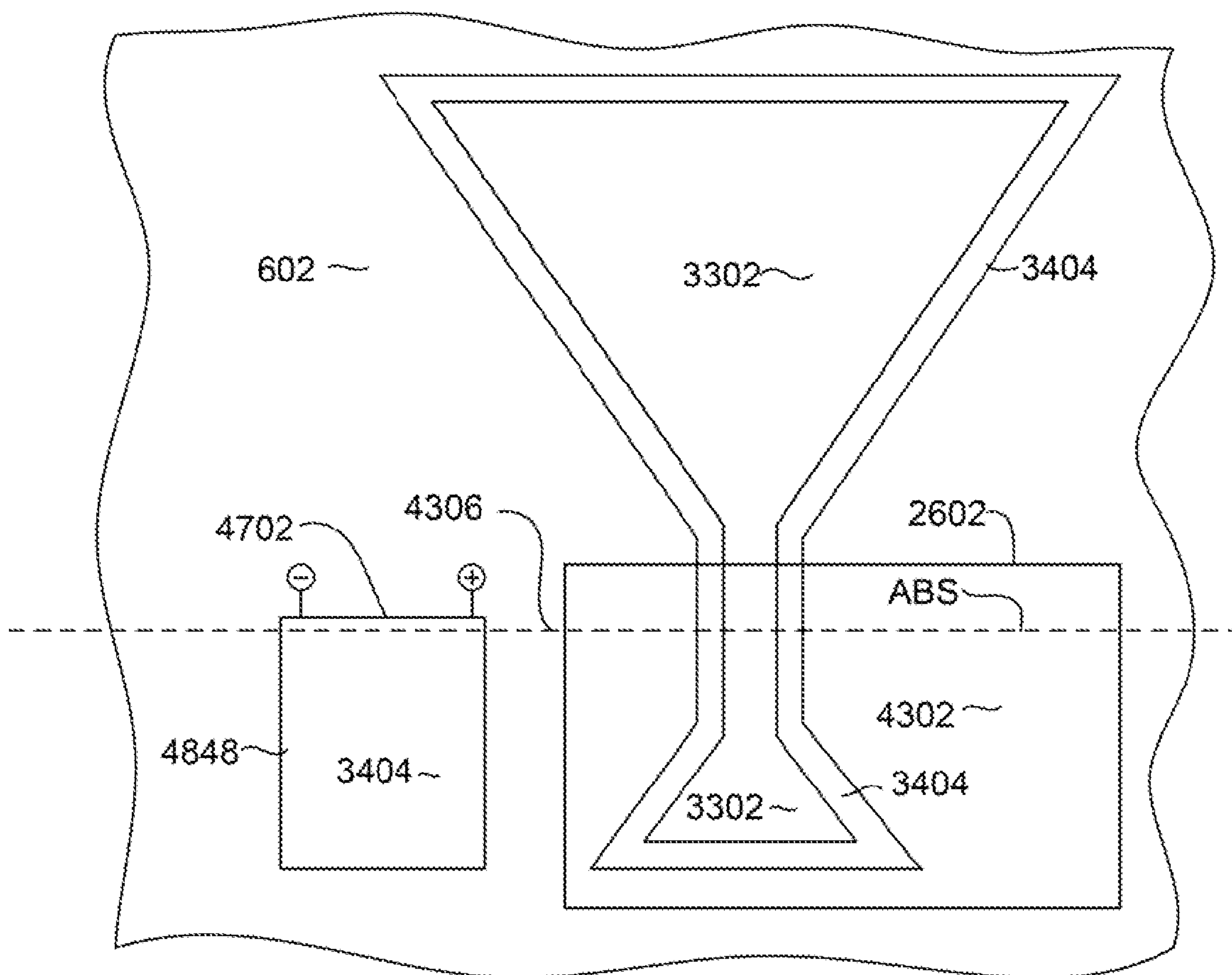


FIG. 48

1

**METHOD FOR MANUFACTURING A
MAGNETIC WRITE HEAD**

RELATED APPLICATIONS

The present invention is a divisional application of commonly assigned U.S. patent application Ser. No. 11/683,972, entitled PERPENDICULAR WRITE HEAD HAVING A STEPPED FLARE STRUCTURE AND NON-MAGNETIC SPACER LAYER AND METHOD OF MANUFACTURE THEREOF, which was filed on Mar. 8, 2007.

FIELD OF THE INVENTION

The present invention relates to the construction of perpendicular magnetic write heads and more particularly to the use of an optical lapping guide for accurately defining the write pole flare point of a perpendicular magnetic write head.

BACKGROUND OF THE INVENTION

The heart of a computer's long term memory is an assembly that is referred to as a magnetic disk drive. The magnetic disk drive includes a rotating magnetic disk, write and read heads that are suspended by a suspension arm adjacent to a surface of the rotating magnetic disk and an actuator that swings the suspension arm to place the read and write heads over selected circular tracks on the rotating disk. The read and write heads are directly located on a slider that has an air bearing surface (ABS). The suspension arm biases the slider toward the surface of the disk, and when the disk rotates, air adjacent to the disk moves along with the surface of the disk. The slider flies over the surface of the disk on a cushion of this moving air. When the slider rides on the air bearing, the write and read heads are employed for writing magnetic transitions to and reading magnetic transitions from the rotating disk. The read and write heads are connected to processing circuitry that operates according to a computer program to implement the writing and reading functions.

The write head traditionally has included a coil layer embedded in one or more insulation layers (insulation stack), the insulation stack being sandwiched between first and second pole piece layers. A gap is formed between the first and second pole piece layers by a gap layer at an air bearing surface (ABS) of the write head and the pole piece layers are connected at a back gap. Current conducted to the coil layer induces a magnetic flux in the pole pieces which causes a magnetic field to fringe out at a write gap at the ABS for the purpose of writing the aforementioned magnetic transitions in tracks on the moving media, such as in circular tracks on the aforementioned rotating disk.

In current read head designs a spin valve sensor, also referred to as a giant magnetoresistive (GMR) sensor, is employed for sensing magnetic fields from the rotating magnetic disk. The sensor includes a nonmagnetic conductive layer, hereinafter referred to as a spacer layer, sandwiched between first and second ferromagnetic layers, referred to as a pinned layer and a free layer. First and second leads are connected to the spin valve sensor for conducting a sense current therethrough. The magnetization of the pinned layer is pinned perpendicular to the air bearing surface (ABS) and the magnetic moment of the free layer is located parallel to the ABS, but free to rotate in response to external magnetic fields. The magnetization of the pinned layer is typically pinned by exchange coupling with an antiferromagnetic layer. The thickness of the spacer layer is chosen to be less than the mean free path of conduction electrons through the sensor. With this

2

arrangement, a portion of the conduction electrons is scattered by the interfaces of the spacer layer with each of the pinned and free layers.

When the magnetizations of the pinned and free layers are parallel with respect to one another, scattering is minimal and when the magnetizations of the pinned and free layer are antiparallel, scattering is maximized. Changes in scattering alter the resistance of the spin valve sensor in proportion to $\cos \theta$, where θ is the angle between the magnetizations of the pinned and free layers. In a read mode the resistance of the spin valve sensor changes proportionally to the magnitudes of the magnetic fields from the rotating disk. When a sense current is conducted through the spin valve sensor, resistance changes cause potential changes that are detected and processed as playback signals.

Recently, researchers have focused on the development of perpendicular magnetic recording systems in order to increase the data density of a recording system. Such perpendicular recording systems record magnetic bits of data in a direction that is generally perpendicular to the surface of the magnetic medium. A write head used in such a system generally includes a write pole having a relatively small cross section at the air bearing surface (ABS) and a return pole having a larger cross section at the ABS. A magnetic write coil induces a magnetic flux to be emitted from the write pole in a direction generally perpendicular to the plane of the magnetic medium. This flux returns to the write head at the return pole where it is sufficiently spread out and weak that it does not erase the signal written by the write pole.

The write pole typically has a flare point that is recessed a desired distance from the ABS. This flare point distance is a critical dimension that must be carefully controlled. The write head may also include a trailing magnetic shield that can be used to increase the field gradient and increase the write speed. The trailing shield has a thickness as measured from the ABS that defines a throat height of the trailing shield. The throat height of the trailing shield is another critical dimension that also must be carefully controlled.

However, as the size of magnetic heads decreases, variations in currently available tooling and photolithography processes make it impossible to control the flare point and trailing shield throat height with sufficient accuracy. Therefore, the inability to accurately control the flare point and trailing shield throat height is limiting the ability to further shrink write head sizes, and is therefore limiting any increase in data capacity.

Therefore, there is a strong felt need for a structure or process that can very accurately define and control the flare point of a write head and the throat height of a magnetic shield in a magnetic write head. Such a structure or process must also be manufacturable using currently available tooling and processes.

SUMMARY OF THE INVENTION

The present invention provides a method for aligning a structure with a lapping guide. The method includes first providing a substrate, and then depositing an electrically conductive material over a first portion of the substrate. A mask structure is formed, having an edge located in the first portion of the substrate and over the electrically conductive material and an edge located in a second portion of the substrate where a structure is to be formed. A material removal process is performed to remove portions of the electrically conductive material not covered by the mask, and electroplating a material over the second portion of the substrate.

3

This process allows an edge of the electrically conductive material (which can form the lapping guide) to be self aligned with the electroplated material, both the electrically conductive lapping guide material and the electroplated material having an edge that is defined by the same masking step. This, therefore, allows both of these features to be defined in a single photolithographic masking step, eliminating the need to align multiple masks.

These and other features and advantages of the invention will be apparent upon reading of the following detailed description of preferred embodiments taken in conjunction with the Figures in which like reference numerals indicate like elements throughout.

BRIEF DESCRIPTION OF THE DRAWINGS

For a fuller understanding of the nature and advantages of this invention, as well as the preferred mode of use, reference should be made to the following detailed description read in conjunction with the accompanying drawings which are not to scale.

FIG. 1 is a schematic illustration of a disk drive system in which the invention might be embodied;

FIG. 2; is an ABS view of a slider, taken from line 2-2 of FIG. 3, illustrating the location of a magnetic head thereon;

FIG. 3 is a cross sectional view of a magnetic head taken from line 3-3 of FIG. 2, enlarged, and rotated 90 degrees counterclockwise illustrating an embodiment of the invention incorporated into a perpendicular magnetic write head;

FIG. 4 is an ABS view taken from line 4-4 of FIG. 3 of a write head;

FIG. 5 is a top down view taken from line 5-5 of FIG. 4;

FIGS. 6-14 show a write head in various intermediate stages of manufacture illustrating a method of manufacturing a write head;

FIG. 15 is a side cross sectional view of a magnetic head according to an alternate embodiment of the invention;

FIG. 16A is an ABS view taken from line 16A-16A of FIG. 15;

FIG. 16B is a cross sectional view taken from line 16B-16B of FIG. 15;

FIGS. 17-30 are views of a write head in various intermediate stages of manufacture illustrating a method of manufacturing a magnetic write head according to an alternate embodiment of the invention;

FIG. 31 is a side, cross-sectional view of a magnetic head according to yet another embodiment of the invention;

FIG. 32 is a cross-sectional view taken from line 32-32 of FIG. 31;

FIGS. 33-37 are views of a magnetic head in various intermediate stages of manufacture illustrating a method of manufacturing a magnetic head;

FIG. 38-42 are views of a magnetic head in various intermediate stages of manufacture illustrating a method of manufacturing a magnetic head according to an alternate embodiment of the invention; and

FIGS. 43-48 are top down views illustrating a method of forming a self aligned electrical lapping guide for accurately defining an air bearing surface (ABS) of magnetic write head.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

The following description is of the best embodiments presently contemplated for carrying out this invention. This description is made for the purpose of illustrating the general

4

principles of this invention and is not meant to limit the inventive concepts claimed herein.

Referring now to FIG. 1, there is shown a disk drive 100 embodying this invention. As shown in FIG. 1, at least one rotatable magnetic disk 112 is supported on a spindle 114 and rotated by a disk drive motor 118. The magnetic recording on each disk is in the form of annular patterns of concentric data tracks (not shown) on the magnetic disk 112.

At least one slider 113 is positioned near the magnetic disk 112, each slider 113 supporting one or more magnetic head assemblies 121. As the magnetic disk rotates, slider 113 moves radially in and out over the disk surface 122 so that the magnetic head assembly 121 may access different tracks of the magnetic disk where desired data are written. Each slider 113 is attached to an actuator arm 119 by way of a suspension 115. The suspension 115 provides a slight spring force which biases slider 113 against the disk surface 122. Each actuator arm 119 is attached to an actuator means 127. The actuator means 127 as shown in FIG. 1 may be a voice coil motor (VCM). The VCM comprises a coil movable within a fixed magnetic field, the direction and speed of the coil movements being controlled by the motor current signals supplied by controller 129.

During operation of the disk storage system, the rotation of the magnetic disk 112 generates an air bearing between the slider 113 and the disk surface 122 which exerts an upward force or lift on the slider. The air bearing thus counter-balances the slight spring force of suspension 115 and supports the slider 113 off and slightly above the disk surface by a small, substantially constant spacing during normal operation.

The various components of the disk storage system are controlled in operation by control signals generated by control unit 129, such as access control signals and internal clock signals. Typically, the control unit 129 comprises logic control circuits, storage means and a microprocessor. The control unit 129 generates control signals to control various system operations such as drive motor control signals on line 123 and head position and seek control signals on line 128. The control signals on line 128 provide the desired current profiles to optimally move and position slider 113 to the desired data track on disk 112. Write and read signals are communicated to and from write and read heads 121 by way of recording channel 125.

With reference to FIG. 2, the orientation of the magnetic head 121 in a slider 113 can be seen in more detail. FIG. 2 is an ABS view of the slider 113, and as can be seen the magnetic head including an inductive write head and a read sensor, is located at a trailing edge of the slider 209. The ABS plane of the slider may include pads or recessions 202 relative to the ABS plane of the slider. The above description of a typical magnetic disk storage system, and the accompanying illustration of FIG. 1 are for representation purposes only. It should be apparent that disk storage systems may contain a large number of disks and actuators, and each actuator may support a number of sliders.

With reference now to FIG. 3, the magnetic head 121 for use in a perpendicular magnetic recording system is described. The head 121 includes a write element 302 and a read element 304. The read element 304 includes a magnetoresistive read sensor 305. The sensor 305, could be, for example, a current in plane giant magnetoresistive sensor (CIP GMR), a current perpendicular to plane giant magnetoresistive sensor (CPP GMR) or a tunnel junction sensor (TMR). The sensor 305 is located between first and second magnetic shields 306, 308 and embedded in a dielectric material 307. The magnetic shields 306, 308, which can be con-

5

structured of for example CoFe, NiFe or sendust, absorb magnetic fields, such as those from up-track or down-track data signals, ensuring that the read sensor **305** only detects the desired data track located between the shields **306**, **308**. A non-magnetic, gap layer **309** may be provided between the shield **308** and the write head **302**. If the sensor **305** is a CIP GMR sensor, then the sensor will be insulated from the shields **306**, **308** as shown in FIG. 3. However, if the sensor **305** is a CPP GMR sensor or TMR sensor, then, the top and bottom of the sensor **305** can contact the shields **306**, **308** so that the shields can act as electrically conductive leads for supplying a sense current to the sensor **305**.

With continued reference to FIG. 3, the write element **302** includes a write pole **310** that is magnetically connected with a magnetic shaping layer **312**, and is embedded within a non-magnetic material **311**. The write pole **310** has a small cross section at the air bearing surface and is constructed of a magnetic material. The write head **302** also includes a return pole **314** that is constructed of a magnetic material such as CoFe, NiFe, or their alloys and has a cross section parallel to the ABS surface that is significantly larger than that of write pole **310**. The return pole **314** can be magnetically connected with the shaping layer **312** and write pole **310** by a back gap portion **316** as shown in FIG. 3. The return pole **314** and back gap **316** can be constructed of, for example, NiFe, CoFe, or their alloys or some other magnetic material.

An electrically conductive write coil **317**, shown in cross section in FIG. 3, passes through the write element **302** between the pole layer **402**, and the return pole **314**. The coil **317** is embedded in an insulation layer **330** that can be, for example, alumina and can include one or more layers of one or more materials.

When a current passes through the coil **317**, the resulting magnetic field causes a magnetic flux to flow through the pole layer **402**, return pole **314**, back gap **316**, shaping layer **312** and write pole **310** and possibly some magnetic material in the adjacent media **333**. This magnetic flux causes a write field to be emitted toward an adjacent magnetic medium **333**. This magnetic field emitted from the write pole **310** magnetizes a relatively higher coercivity, thin top magnetic layer on the magnetic medium **333**. This magnetic field travels through a magnetically soft underlayer of the magnetic medium to the return pole **314**, where it is sufficiently spread out that it does not erase data elsewhere on the media **333** that is not located directly under the write pole **310**.

With reference to FIG. 4, which shows an ABS view of the write element **302**, it can be seen that the write pole **310** preferably has a trapezoidal shape. This shape helps to reduce skew related adjacent track interference. Although not shown, the trailing shield could be constructed to wrap around the sides of the write pole **310**, in which case the side portions of the trailing shield would be separated from the sides of the write pole **310** by a non-magnetic side gap material.

With reference to FIGS. 3, 4 and 5, it can be seen that the write pole **310** has a stepped flare structure. More particularly, the write pole **310** includes a magnetic core **402** that is preferably constructed of a lamination of magnetic layers such as NiFe or CoFe separated by thin non-magnetic layers such as alumina. Other materials that can be used in such a laminated write pole include silica, Ta, Ti, NiP, Pd, Si, Cr, Mo, Rh, Ru and Al. The write pole **310** also includes a magnetic shell portion **404**, constructed of an electroplated magnetic material such as NiFe, CoFe, or their alloys that wraps around the magnetic core **402**. With reference to FIG. 4, it can be seen that the magnetic shell **404** is laterally symmetrical about the

6

core **402**. By laterally symmetrical, it is meant that the shell **404** is symmetrical in the track width direction, to the left and right as shown in FIG. 4.

With reference to FIG. 5, which shows a view of the deposited end of the slider, it can be seen that the shell **404** forms a stepped structure **406** that is recessed from the ABS. In FIG. 5, the portions of the core **402** that are hidden within the shell **404** are shown in dashed line, and as can be seen, the core **402** has a flare point **408** that is recessed from the ABS by a first distance FP1. However, the stepped structure **406** formed by the front most edge (ABS facing edge **410**) of the shell, defines a secondary flare point that is recessed by a distance FP2 from the ABS, FP2 being smaller than FP1.

As write heads become ever smaller, the flare point distance from the ABS must become smaller as well. However, available manufacturing processes such as photolithography have resolution and variation limitations that limit the size and placement to which the flare point distance can be defined. For example, currently available photolithographic processes have variations that are sufficiently great that for very small write pole sizes, the location of the flare point in a standard write pole would vary between a write pole having a flare point that is too large to a write pole having no flare point at all. A flare point that is too large would choke off the flux, significantly reducing the write field. A flare point that is too small (or even non-existent) results in an extremely wide write signal that writes to several adjacent tracks. Both of these situations are of course unacceptable. The secondary flare point **406** provided by the magnetic shell **404** allows the location of the flare point FP2 to be carefully controlled using currently available photolithographic tools and techniques, as will be described below.

The details of the electroplating bath and process are also relevant. The material that is electroplated should preferably be ferromagnetic, but could consist of more than one layer where one layer is ferromagnetic and another is non-ferromagnetic. An example of a non-magnetic layer could be NiP alloy or Pd alloy. Plating such an alloy is a balance between bath composition, plating area, current density and other factors. Other factors include anode and cathode material, voltage or current variations, bath composition including additives, surfactants, buffering, and complexing agents, plating cell design, bath temperature, plating flow rate, wafer mask design, and magnetic field.

In order to electroplate a thin magnetic layer, it is important to control the plating process. Therefore, the plating rate should preferably be less than 100 nm/min. The thin plated layer should be conformal and not introduce increased roughness or morphology to the surface. Preparation of the surface to plate a thin layer could include pre-wetting the surface or using surfactants in the bath. Additives can also be added that will slow the plating process in order to achieve improved thickness control. Another important factor in thin plating is the dwell time which is the amount of time that the wafer sits in the bath prior to applying a potential to the wafer. This dwell time should be minimized because the bath can actually etch or corrode the very material one would want to plate upon (ie. the anode).

A method for minimizing the dwell time in the plating bath is to have a voltage applied to the cathode or anode prior to placement in the plating bath. Therefore, once a wafer enters the plating bath, the circuit is complete and electroplating begins instantaneously. This is referred to hereinafter as a "hot start" process because the wafer can be "hot" by having a voltage on it outside the plating bath which is similar to a live, ungrounded wire.

Plating methods can also affect the material properties and its final thickness. One pulse plating method includes applying a series of voltage or current pulses that plate material in a non-continuous method. This will have the end result of having a slower average overall plating rate compared to the plating rate during a pulse. Reducing the pulse frequency or voltage can slow the plating process. One can even briefly reverse the potential on the wafer and etch (or de-plate) briefly to slow or alter the final plated film.

With reference now to FIGS. 6-14, a method for manufacturing a magnetic write head 302 such as that described above will be described. With particular reference to FIG. 6, a substrate or under-layer 602 is provided. The substrate 602 can be, for example, the fill layer 330 and shaping layer 312 described with reference to FIG. 3. Other structures or devices in a head may also be in or below the under-layer 602. The fill layer 330 can be constructed of alumina. A layer of magnetic pole material 604 is deposited over the substrate 602. The magnetic pole material 604 can be constructed of several materials, and is preferably a lamination of magnetic layers such as CoFe, NiFe, or their alloys separated by thin non-magnetic layers such as alumina, silicon dioxide or some other material. A mask structure 606 is formed over the magnetic layer 604. The mask structure can include various layers such as one or more hard mask layers, one or more image transfer layer, and a mask material such as photoresist or thermal image resist. With reference to FIG. 7 it can be seen that the mask structure 606 is configured to define a write pole structure that extends beyond the plane of the Air Bearing Surface (ABS).

With reference now to FIG. 8, a material removal process such as ion milling, or some other process is performed to remove portions of the magnetic material 604 that are not protected by the mask structure 606 to form a write pole structure 604. The material removal process, represented by slanted arrows 802 can be performed, for example, by directing an ion beam at an angle or combination of angles relative to normal to form the write pole with a trapezoidal shape as shown in FIG. 8. With reference to FIG. 9, the remaining mask material 606 can be removed by one or more of various material removal processes, which may include reactive ion milling, reactive ion etching, etc. This results in a structure as shown in FIGS. 9 and 10 with a write pole structure 604 formed over the substrate 602. One should also note that the particular method of making the initial pole is not central to the structure or methods described herein. Alternatively, the pole 604 could be formed by electroplating and may be formed without non-magnetic lamination layers.

With reference now to FIG. 11, a liftoff process can be used to create a plating seed on a portion of the write pole. For example, a bi-layer photoresist mask 1102 can be formed to cover a majority of the write pole structure 604, leaving a portion of the write pole uncovered. Then, an electrically conductive, magnetic seed layer 1104 such as NiFe or Ta and/or Ir, Rh, etc. can be deposited such as by sputter deposition. The mask 604, can then be lifted off by a chemical liftoff process. The overhanging structure of the bi-layer mask facilitates the mask liftoff by allowing a liftoff chemical solution to reach under the edges of the mask 1102. The resulting seed layer 1104 covering a portion of the write pole 604 (preferably near the back edge of the write pole 604) can be seen with reference to FIG. 12. The portions of the write pole 604 that are hidden under the seed layer 1104 are shown in dashed line in the cross-hatched portion of FIG. 12. There would also, preferably, be seed 1104 deposited between devices as well.

With reference now to FIG. 13, a mask structure, such as a photoresist mask 1302 is formed over a front portion of the write pole 604. As can be seen, the mask 1302 has a back edge 1304 that is located a desired distance behind the ABS plane designated (ABS). As will be seen, the location of this back edge 1304 determines the amount by which the secondary flare structure 406 (described with reference to FIG. 5) is recessed from the ABS. In other words, the location of the back edge 1304 determines the flare point (FP2) of the finished write head.

After, the mask 1302 has been formed, an electroplating process can be used to deposit an electrically conductive magnetic material such as NiFe, CoFe, or their alloys. This results in magnetic material being plated onto portions of the pole that are not covered by the mask 1302. With reference to FIG. 14, a cross section of a portion of the write pole 604 shows that the magnetic material 1402 is plated evenly over the write pole 604. Therefore, the electroplating results in a laterally symmetrical deposition of magnetic material 1402 onto the portions of the write pole 604 that are not covered by the mask 1302 (FIG. 13). By laterally symmetrical, it is meant that the deposition of magnetic material 1402 is symmetrical in a track width direction (ie. to the right and left and above as shown in FIG. 14).

The above described process results in a write pole structure such as the write pole 310 described with reference to FIGS. 3-5 above. As will be appreciated by those skilled in the art, inherent process limitations such as photolithographic variation, limit the amount by which the flare point distance can be reduced in a very small write head using a standard write pole structure and standard processes. The above described process makes it possible to construct a write pole having very reduced effective flare point (ie. flare point 406 in FIG. 5) using currently available manufacturing processes, and currently available photolithographic tools. The present invention, therefore, allows the reduction of write head sizes for current and future write head fabrication.

Sacrificial Fill Layer:

The above described method for manufacturing a write head included a method of forming a write pole having a secondary flare point (FP2) formed by electroplating a stepped structure over a write pole. With reference now to FIGS. 15 and 16 a write head is described that has a stepped secondary notch structure similar to that described above, but which also has a wrap around trailing shield. With particular reference to FIG. 15 a magnetic read/write head 1502 according to an embodiment of the invention has a write head 1504 that has a trailing shield 1506 constructed to wrap around the sides of the write pole 310 and constructed of a magnetic material such as CoFe, NiFe, or their alloys. The trailing shield 1506 is separated from the write pole 310 by a non-magnetic gap material 1508 such as alumina (Al_2O_3) and/or Ta/Rh, Ta/Ir, or Au. The trailing shield has a throat height (TH) that is measured from the ABS to its back edge adjacent to the end of the magnetic shell portion 1510.

The write head 1504 includes a write pole 310 similar to that described above, which includes a magnetic shell stepped structure 404 that wraps around the top and sides of the main pole portion 402 as seen in FIG. 6B at a location recessed from the ABS. A non-magnetic spacer layer 1510 wraps around the top and sides of the stepped magnetic structure 404 as can also be seen in FIG. 16B. The non-magnetic spacer can be constructed of an electroplatable, non-magnetic material, such as NiP, and as can be seen in FIG. 16B, both the magnetic step structure 404 and the non-magnetic spacer 1510 are laterally symmetrical at either side of the main write pole portion 402.

With reference now to FIG. 16A, it can be seen that the trailing shield wraps around the sides of the write pole 310, the sides of the write pole 310 being separated from the trailing shield 1506 by non-magnetic side gap layers 1512, which may be the same material as the trailing gap 1508 (such as alumina and/or Ta/Rh, Ta/Ir, or Au.) or could be some other material. The trailing edge 1514 of the write pole 310 is separated from the trailing shield 1506 by a trailing gap distance (TG), and the sides of the write pole 310 are separated from the wrap around portions of the trailing shield by a side gap (SG). SG and TG can be different from one another, with the side gap SG being preferably (but not necessarily) larger than the trailing gap TG.

With reference again to FIG. 15, it can be seen, that the trailing shield 1506 can be magnetically connected to the return pole 314 or an additional pole that has the same magnetic state as the return pole 314. Alternatively, the trailing shield 1506 can be a floating shield that is not magnetically connected to the other magnetic structures of the write head 1504.

With reference now to FIGS. 17-30 a possible method is described for constructing a write head such as the write head 1504 described above. With particular reference to FIG. 17, a substrate 1702 is provided. The substrate 1702 can include an underlying non-magnetic, electrically insulating material such as 330 such as alumina and may include all or a portion of the shaping layer 312, both of which are described above with reference to FIG. 15. Optionally a non-magnetic under-layer material 1703 such as TaOx can be deposited over the substrate 1702. The under-layer 1703 can be helpful in reducing undercut of the write pole during fabrication as will be described in greater detail herein below. A magnetic write pole material 1704 is deposited over the substrate 1702, and over the under-layer 1703 if present. The write pole layer 1704 can be constructed of several magnetic materials, such as NiFe, CoFe, or their alloys but is preferably a laminated structure that includes layers of a magnetic material such as CoFe separated by thin non-magnetic layers such as alumina.

One or more masking layers 1706 are deposited over the write pole material layer 1704. Although the mask 1706 can include various configurations and material combinations, the mask 1706 preferably includes a hard mask structure 1707 formed over the write pole material 1704 and resist such as photoresist or thermal image resist 1714. The hard mask structure 1707 can be a tri-layer first hard mask structure, having a first layer 1705 a second layer 1708 and a third layer 1709. The first layer is preferably a material that is resistant to removal by chemical mechanical polishing (CMP) such as DLC (diamond-like carbon), Ta Rh, Ir, Ru, Cr or their combination. The second layer 1708 is preferably a material that is resistant to ion milling, such as alumina (Al_2O_3) and can have a thickness of about 20 nm. The third layer 1709 of the first hard mask structure 1707 is also preferably resistant to ion milling and is preferably constructed of AlTiO or Al containing alloy, and can have a thickness of about 50 nm.

A method used to create the pole can be one in which the mask 1707 becomes part of the non-magnetic trailing gap (TG) 1709 and is used as an endpoint detection layer during ion milling to define, in part, the non-magnetic side gap (SG) and removes the transfer mask 1710. In this case, the mill resistant material chosen for 1708 should have a bulk material of 1709 with a small percentage of doped material for endpoint detection. For example, a layer 1708 would be comprised of Al_2O_3 and the gap 1709 preferably has Al_2O_3 doped with Ti where the material to detect for end point would be Ti.

However, the layer 1709 could be doped (less than 10% by weight) with another material that can be clearly detected using an end point detection signal.

The mask structure 1709 can also include an image transfer layer 1710 formed over the first hard mask structure 1707. The image transfer layer can be a soluble polyimide material such as DURAMIDE®. A second hard mask 1712 can be provided over the image transfer layer 1710 and can be constructed of SiO_2 having a thickness of about 125 nm. An antireflective coating layer 1713 can be provided over the second hard mask 1712. The antireflective coating layer 1713 can be constructed of the same material as the image transfer layer 1710 (eg. a soluble polyimide solution such as DURAMIDE®), and can have a thickness about 120 nm. The resist mask layer 1714 can have a thickness of about 250 nm and can be deposited over the antireflective coating layer 1713.

With reference now to FIG. 18, the resist layer 1714 is photolithographically patterned and developed to have a shape that is configured to define a write pole. Then, with reference to FIG. 19, one or more material removal processes 1902 are performed to transfer the image of the photoresist layer onto the underlying mask layers. The material removal processes preferably include a combination of reactive ion etching (RIE) and reactive ion milling (RIM), which remove the remove portions of the mask layers 1708, 1709, 1710, 1712 and 1713, while leaving the first sub-layer 1705 of the first hard mask 1707 substantially intact to protect the magnetic write pole layer 1704 from being damaged by the material removal processes 1902.

Then, with reference to FIG. 20, an ion milling process 2002 is performed by directing an ion beam at an angle relative to normal to remove portions of the magnetic write pole material 1704 that are not protected by the mask structure 1706. It can be seen that while some of the mask structure 1706 is consumed by the ion milling 1706, a considerable portion remains. The angled ion milling 2002 results in the write pole 1704 having a desired trapezoidal shape, such as is shown in FIG. 20 and which has been previously discussed above.

With reference now to FIG. 21, a non-magnetic side gap material 2202 is deposited. The side gap material can be alumina (Al_2O_3) and is preferably deposited by a conformal process such as atomic layer deposition (ALD) or some other conformal process.

The side gap material 2202 could also be a non-magnetic metal. If a metal is used as the side gap material 2202, then it must be a material that can remain in the ABS without presenting corrosion problems. Then, with reference to FIG. 22, a fill material 2204 is deposited. This fill material 2204 is preferably a material that can be readily removed without damaging the write pole material. For example, in one preferred embodiment, the fill material 2204 can be a material such as SiO_2 , which can later be removed by a process that will be described below. In another preferred embodiment, the fill material 2204 can be a material such as Cu or some other non-magnetic material.

With reference now to FIG. 23 a chemical mechanical polishing process (CMP) is performed to planarize the structure and remove most of mask layer 1706 from over the pole 1704. The bottom layer 1705 can be used as a CMP stop layer so that CMP can be stopped when the layer 1705 is reached. The remaining mask material (CMP stop layer) 1705 (FIG. 22) can be left intact and becomes part of TG or can be removed by a material removal process suited to the material making up the layer 1705. For example, if the layer 1705 is diamond like carbon (DLC) it can be removed by using an oxygen containing reactive ion etch (RIE) plasma. Then, with

11

reference to FIG. 24, the fill material **2204** can be removed. If the fill layer **2204** is a material such as silicon dioxide (SiO_2), then the fill layer **2204** can be removed by a fluorine containing reactive ion etching (RIE) plasma or reactive ion milling (RIM) beam. Alternatively, the fill and CMP process can be omitted and a reactive ion milling process (RIM) can be used to remove the mask structure **1710**. In that case, the bottom mask layer **1705** (such as Ti or Rh) or **1709** can be used as an etch stop indicator using secondary ion mass spectroscopy (SIMS) to detect when the layer **1705** has been reached. The selection of a layer **1705** or layer **1709** which comprises an end point material enables the ability to control TG thickness. One can also insert more than one end point layer, such as one in layer **1705** and layer **1709**. This gives the manufacturing of heads the flexibility of altering the trailing gap (TG) for different products having different gap targets. This can also affect the associated side gap (SG). Furthermore, the end point materials in the two layers could be comprised of different materials (eg. Ti for one layer and Ta for another end point layer).

The above described processes result in a write pole having non-magnetic side walls **2204** and a non-magnetic trailing gap layer **1705** formed over the write pole **1704**.

If the fill material **2204** is Cu, then a different process can be performed to remove it after the CMP. One method that can be employed to remove the Cu fill layer **2204** is emersion in a basic complexing etch bath that will not readily etch the CoFe pole material **1704**. The Cu fill layer **2204** could also be removed by electroetching.

With reference now to FIGS. 5, 25 and 26, a photoresist mask **2502** is formed. As can be seen in FIG. 26, the mask **2502** has a back edge **2602** that is located behind the ABS plane between the ABS plane and the flare point **408** of the write head **1704**. As shown in FIG. 26, the portions of the pole **1704** and side walls **2202** that are hidden beneath the photoresist mask **2602** are shown in dotted line.

Then, with reference to FIG. 27, a material removal process is performed to remove portions of the sidewall material **2202**. If the side wall material **2202** is alumina, it can be removed by an etching process that is designed to remove the alumina side wall material **2202** without damaging or removing the pole material (eg. CoFe). Possible etching solutions include a metal ion free developer solution such as tetramethylammonium hydroxide (TMAH), KOH, or a chrome etch such as CR-7® produced by Cyantek® of Fremont, Calif. The choice of what etchant to use will depend upon the side-gap material **2202**. Whatever method of etching is used, it must cleanly remove all of the side wall material, to insure effective plating of a magnetic material onto the pole **1704** as will be described in greater detail herein below. If the side gap **2202** material is a Zn alloy, it can be removed from the area behind the mask **2502** by electroetching. If the side gap **2202** is constructed of silicon oxide (SiOx) it can be removed etching with an HF acid that is buffered (BOE). This results in a structure as shown in FIG. 27.

With reference now to FIG. 28, which shows a cross section of the write pole in a region beyond the back edge **2602** of the mask **2502** (shown in FIG. 27), a magnetic material **2802** can be electroplated onto the portion of the pole **1704**. This magnetic material **2802** can be, for example CoFe, NiFe, or their alloys and is preferably CoFe. This magnetic material forms a stepped structure on the write pole similar to the step **406** described in FIG. 4, and is similar to FIG. 16B where the plated materials **2802** and **2804** may be the same as **404** and **1510** as seen in FIG. 16B. In order for this stepped pole structure to function optimally, there must be no non-magnetic remnant material left between the pole **1704** and the

12

magnetic material **2802**. This is one reason that the above described process used to remove the side wall material **2202** must very effectively remove all of this material. optionally, a non-magnetic gap layer **2804** can then be deposited over the plated magnetic layer **2802**. This non-magnetic layer can be a non-magnetic metal, such as Cu or NiP and can be electroplated directly onto the magnetic layer **2804**.

The resist mask **2502** can then be lifted off, leaving the structure as shown in a side cross sectional view in FIG. 29. Then, with reference to FIG. 30, a non-magnetic trailing gap layer **3002** can be deposited. This layer **3002** can be a non-magnetic material such as Ta and/or Rh, Au, and Ir, which can be deposited by a conformal deposition method such as ion beam deposition (IBD). The non-magnetic trailing gap layer **3002** is deposited to such a thickness to provide a desired trailing gap thickness TG and side gap **15**, thickness SG as described in FIG. 16A. Then a magnetic material **3004** can be deposited by electroplating to provide a magnetic trailing shield, such as the trailing shield **1506** described above with reference to FIG. 15. A lapping process (not shown) can be used to remove material (from the left side as shown in FIG. 30) until the ABS plane has been reached, thereby forming a write head with an air bearing surface (ABS) and having a trailing shield **1506** with a desired throat height as measured as measured from the ABS. The above described processes can produce a magnetic write head **1504** such as that described with reference to FIGS. 15, 16A and 16B, having a desired stepped pole structure **310** with a trailing shield **1506**.

Write Head with Stair Stepped Trailing Shield:

With reference now to FIG. 31 a magnetic write head **3102** having a stair stepped trailing shield **3104** is described. The write head includes a magnetic write pole **3106**, that has a core portion **3108** similar to the core **402** described above with reference to FIGS. 15, 16A and 16B. The pole **3106** also has a magnetic shell portion **3110** that is similar to the magnetic shell **404** described with reference to FIGS. 15 and 16B. The trailing shield **3104** can also act as a return pole **314** as seen in FIG. 31A.

In addition, the write head **3102** includes a non-magnetic spacer layer **3112**. The non-magnetic spacer layer **3112** is similar to the spacer **1510** described with reference to FIGS. 15 and 16B in that it wraps around the top and sides of the stepped magnetic shell structure **3110** as shown in FIG. 32. However, as can be seen in FIG. 31, the non-magnetic spacer structure is stepped back from the ABS. In other words the magnetic shell has a front edge **3114** that is recessed from the ABS by a first distance, and the non-magnetic spacer **3112** has a front edge that is spaced from the ABS by a second distance that is greater than the first distance. The trailing shield **3104** is separated from the pole **3106** by a spacer **3112** comprising, for example, NiP and a non-magnetic trailing gap material **3120** that could be constructed of, for example, alumina and Ta and/or Rh, Au, and Ir,

This extra recession of the non-magnetic spacer **3112** allows the magnetic shield **3104** to form a stair stepped back edge **3118** that tapers away from the ABS. This results in a magnetic shield **3104** that has a back edge **3122** that is coincident with or recessed beyond the secondary flare point defined by front edge **3114** of the magnetic shell structure **3110**. Although shown as a single stair stepped notch, the number of stair steps could be increased to more closely resemble a smooth taper, if desired.

With reference now to FIGS. 33-42 a method is described for constructing a magnetic write head such as the write head **3102** discussed above. With particular reference to FIG. 33A a magnetic write pole core portion **3302** is formed on a substrate **3101**, with non-magnetic side walls **3304** (preferably

alumina) surrounding the magnetic core **3302**. A photoresist mask **3306** is formed over a front portion of the write pole core **3302**, the mask having a back edge **3308** that is between the ABS and the flare point **3310** of the core portion. A material removal process can then be performed to remove the portions of the side wall material **3304** that are not covered by the mask **3306** (ie. beyond the back edge **3308** of the mask **3306**). This can be performed by methods such as those discussed above with reference to FIGS. **17-24**.

Then, with reference to FIG. **34** a magnetic material **3402** such as CoFe is deposited onto the magnetic write pole core **3302**, preferably by electroplating. A non-magnetic metal **3304** such as NiP, ZnNi, Cu, Cr or Au is then deposited onto the magnetic layer **3302**, preferably by electroplating. Then, the resist mask is lifted off, leaving a structure as shown in a side cross sectional view in FIG. **35A**. Similarly, in FIG. **36**, a magnetic and non-magnetic layer containing a stack which is electroplated may have a step between one layer and another where the first edge of one plated layer **3604** is protruding relative to the edge of a second plated layer **3602**.

An example of the process flow is shown in FIG. **33B**, where an existing pole **3315** will have a flare point defined by a masking step **3320**. This is followed an etch of material on the pole **3302** in a step **3602**. However, this is only needed if there is non-magnetic material covering the pole. Then, a magnetic layer is electroplated directly off of the pole **3302** in a step **3340**. Optionally, in a step **3350** one may deform the mask layer after the magnetic layer is plated. In addition step **3360**, an optional non-magnetic portion may be plated on the magnetic plated pole portion. The mask would be removed in a step **3370** and processing would continue **3380**.

Referring to FIGS. **33A**, **33B**, **35A** and **36**, the material removal process **3602** is performed, prior to plating, to remove a portion of the non-magnetic layer **3304**. The material removal process **3602** is a process that is carefully chosen to remove the non-magnetic metal **3304**, without affecting the magnetic layers **3404** or **3302**. This process **3602** can be a wet etch. For example, if the non-magnetic layer **3404** is constructed of ZnNi, it can be removed by electroetching. If the non-magnetic layer **3404** comprises Cu, it can be removed by etching with a basic solution containing ammonium persulfate and ammonium hydroxide. If the non-magnetic layer **3404** is Cr it can be etched with a Cr etchant such as CR-7® produced by Cyantek Corp.®. If the non-magnetic layer **3404** is Au, it can be etched with potassium iodine. As can be seen in FIG. **35B**, the removal of a portion of the non-magnetic layer **3304**, allows for the plating of magnetic layer **3402** and non-magnetic layer **3404**, defining a front edge **3509**. This front edge of **3509** of, at least, the first electroplated layer will define the new flare point **3535**.

Then, with reference to FIG. **37**, a non-magnetic trailing gap layer **3702** such as Ta and/or Rh, Au, and Ir, can be deposited, and a magnetic material **3704** such as NiFe, CoFe, or their alloys can be deposited by electroplating to form a trailing shield having a stair stepped back edge. In this manner, a trailing shield can be constructed that has a back edge **3706** that is either coincident with or behind the flare point defined by the front edge **3604** of the magnetic shell layer **3402**.

With reference now to FIG. **38** a possible method is described for constructing a stair stepped shield structure. After constructing a write pole core portion **3302** over an under-layer **1703** and substrate **3101**, a photoresist mask **3802** is formed. Then, a layer of magnetic material **3804** is deposited to form the magnetic shell over the magnetic core **3302**. Then, with reference to FIG. **39**, a soluble material **3902** such as a SAFIER® coating is deposited (ie. spun on) to the struc-

ture. The structure thus far formed can then be heated. This heating causes the soluble coating **3902** to contract, pulling the photoresist mask **3802** with it, resulting in a structure as shown in FIG. **40**, with the mask **3802** overlapping the magnetic shell **3804**. Then, with reference to **41A**, the shrinkable coating **3902** can be removed and a non-magnetic metal **4102** can be plated onto the magnetic shell **3804**. Then, with reference to FIG. **42**, a non magnetic gap layer **4202** such as Ta and/or Rh, Au, and Ir, which can be deposited and a magnetic material such as NiFe, CoFe, or their alloys can be deposited by electroplating over the gap layer **4202**. As can be seen, this results in a magnetic shield **4204** having a stair stepped back edge **4206**. Alternatively, a multi-stair structure can be created as shown in FIG. **41B**, where upon some substrate with seed **4101** a multi-step structure is electroplated that comprises more than one material. Similarly, an electroplated feature can be formed as shown in FIG. **41C**. This may comprise one or more materials with one or more steps where each step recession of less than 50 nm makes the structure progressively narrower, as seen in FIG. **41D**. Depending on the head design, the distance from the flare point to the ABS **3737** may be less than, equal to, or greater than the distance from the back edge of the trailing shield and the ABS **3747**.

Self Aligned Electrical Lapping Guide (ELG):

As seen in FIG. **37**, the formation of a magnetic write head, such as the embodiments disclosed above require careful control of flare point (distance between flare point and ABS **3737**) and trailing shield throat height (thickness of the trailing shield as measured from the ABS **3747**). Both the write pole flare point and the trailing shield throat height are measured from the location of the ABS, which in turn is defined by a lapping operation. This lapping operation occurs after the wafer has been cut into rows of sliders. A side of the row of sliders, or an individual slider, is lapped to remove material until a desired ABS plane location has been reached. At this point the row of sliders can be cut into individual sliders. This lapping operation is, however, difficult to control.

An electrical lapping guide (ELG) can be used to determine at what point lapping should be terminated. A lapping guide is an electrically conductive material, with an edge that is at a predefined from, or exactly at, the intended ABS plane. As lapping progresses, the electrical resistance of the lapping guide is measured by applying a voltage across the lapping guide. When this resistance reaches a predetermined level, the operator can determine that the ABS plane has been reached and lapping should terminate.

As can be appreciated, then, defining the location of the edge of the lapping guide must be carefully controlled relative to the intended ABS and relative to the flare point and shield throat height. However, manufacturing tolerances, such as aligning multiple mask photolithographic steps make this edge location control very difficult. The method described herein below provides an accurate self alignment process for accurately and reliably locating the critical edge of the lapping guide, relative to the ABS, flare point and shield throat height.

With reference now to FIGS. **43** and **35B**, a write pole structure **3302** is shown at a manufacturing stage similar to that described with reference to FIG. **26**. This structure includes a write pole core portion **3302** and a non-magnetic side wall **3404** surrounding the write pole core **3302**. An electrically conductive ELG **4304** is formed in a kerf area beside the write pole **3302**. The ELG material can be formed by a liftoff process such as by forming a bi-layer photoresist mask (not shown), depositing an electrically conductive material, and then lifting off the mask. A subtractive method could also be used. A mask structure **4302** is formed similar to

15

the mask **2502** described in FIG. **26**, except that this mask structure **4302** has a back edge **4302** that is aligned relative to the intended ABS plane. In fact, the edge **4306** could be located at the ABS plane as shown, or could be at some other predetermined location relative to the ABS plane. The mask **4302** and edge **4306** extend over, at least a part of, the ELG material **4304** as shown in FIG. **43**

With reference now to FIG. **44**, a material removal process such as that described above with reference to FIG. **27** can be performed to remove portions of the non-magnetic side wall **3404** that are not covered by the mask **4302**. This removes the portions of the side wall **3304** that extend beyond the back edge **2602** of the mask **4302**. The same or a different material removal process (such as reactive ion etch) can be used to remove the portion of the ELG **4304** that extends beyond the back edge **4306** of the mask **4302**. As will be recalled from the discussions above, the location of the edge **2602** of the mask **4302** defines the location of the secondary flare point (for example **FP2** in FIG. **5**) as well as the trailing shield throat height (for example **TH** in FIGS. **15** and **30**). Therefore, by continuing processing as described above with regard to the previously described methods and embodiments, the back edge **4404** of the ELG lapping guide is self aligned with the write head flare point and shield throat height and ABS. One can also say that the edge **4404** is self aligned so that the photo edge **2602** of the mask layer **4302** is used to define the ELG as well as the flare point (**FP2**) and its associated shield throat height **TH**, there is no need to align multiple masks in multiple photolithographic steps. During lapping, a voltage can be applied across the ELG **4304** to measure the resistance across the ELG. As lapping progresses in a direction as indicated by arrow **3408**, the ELG will be consumed. As a greater and greater portion of the ELG is consumed, the resistance across the ELG will increase, and when a predetermined resistance is reached, lapping can stop. With the back edge located directly at the ABS as shown in FIG. **44**, the lapping can the resistance across the lapping guide **4304** increases to infinity (ie. when the lapping guide **4304** is completely removed) by lapping material away.

With reference to FIG. **43A**, an alternate device that can be patterned is a sensor **4304**. This may exist in a side-by-side head where a write head is co-planar with a sensor structure. Similar to the patterning of the write head ELG material **4304**, the back edge of a sensor **4343** can be defined with the edge **4306** of the mask **4302**. The sensor **4343** would be deposited and possibly partially patterned prior to deposition of the defining mask **4302**. As symbolized in FIG. **44A**, the sensor **4343** would be electrically connected to outside the device. This would result in a head that has the back edge **4444** of the sensor self-aligned to the flare point **FP** and its associated throat height (**TH**).

Collectively, one could also define the flare point **FP** and its associated throat height **TH** with the back edge **2602** of the mask **4302** along with a coplanar sensor **4343** and a write head ELG material **4304** using variations in the shape of mask **4302**.

With reference now to FIG. **45**, another method for constructing a lapping includes depositing an electrically conductive lapping guide material **4304** such as Au. Then, a mask structure can be formed that includes a first portion **4404a** having a back edge **2602** located to define a flare point **FP2** and its associated shield throat height **TH** as described above. The mask also includes a portion **4404b** that has a front edge **4406** located to define a back edge of a lapping guide, which may or may not be co-linear with the ABS plane. Then, with reference to FIG. **46**, an etchable material **4602** such as CoFe can be plated onto the lapping guide material **4304** adjacent to

16

the mask **4404b**. Although the etchable material **4602** is shown only over the lapping guide region in FIG. **46**, this is for purposes of illustration only. The etchable material **4602** could actually be deposited full film, as it will be later removed by etching. Then, the mask portion **4404b** can be removed leaving a non-plated portion **4510** on the lapping material **4304**. Then, etching the non-plated portion **4510** creates the back edge of the write head ELG. The plated material **3404** that was electroplated on the ELG material **4304**, as well as the ELG material **3404** itself, collectively form an ELG that has a back edge **4702**, as seen in FIG. **47**. Since the mask structures **4404a** and **4404b** are defined in the same photolithographic step, the edge **4702** can be accurately aligned with the ABS plane, flare point **FP2** and shield throat height **TH**, which is defined by the placement of the edge **2602**. Similarly, the ELG **4304** would be electrically connected to enable monitoring the ABS plane by inferring resistance changes in the ELG **4304**. This would create a resistance measurement that would relate the ABS plane to the back edge **4702** of the ELG **4304**.

Furthermore, as seen in FIG. **48**, a similar additive process could have a plated material **3404** on a sensor **4848** where the back edge **4802** of the sensor was created with part of the same mask **4302** that defined the flare point **FP** and its associated throat height **TH**.

While various embodiments have been described above, it should be understood that they have been presented by way of example only, and not limitation. Other embodiments falling within the scope of the invention may also become apparent to those skilled in the art. Thus, the breadth and scope of the invention should not be limited by any of the above-described exemplary embodiments, but should be defined only in accordance with the following claims and their equivalents.

What is claimed is:

1. A method for manufacturing a magnetic write head, comprising:

- providing a substrate;
- forming a magnetic write pole over the substrate;
- depositing an electrically conductive material;
- forming a mask structure having an edge located over the electrically conductive material and also having an edge located over the write pole;
- performing a material removal process to remove a portion of the electrically conductive material that is not protected by the mask structure; and
- electroplating a magnetic material over a portion of the write pole that is not covered by the mask structure.

2. The method as in claim 1 wherein the mask structure leaves a portion of the electrically conductive material and a portion of the write pole exposed.

3. The method as in claim 1 further comprising, after electroplating the magnetic material, electroplating a non-magnetic material.

4. The method as in claim 3 wherein the electroplated magnetic material and the electroplated non-magnetic material each have an edge that is aligned with the edge of the mask structure.

5. The magnetic method as in claim 3 wherein the electroplated non-magnetic material comprises NiP.

6. The method as in claim 3, further comprising, before forming the mask structure, forming non-magnetic sidewalls at first and second sides of the write pole, wherein the material removal process removes portions of the non-magnetic side wall that are not protected by the mask structure.

17

7. The method as in claim 3 wherein the material removal process is a first material removal process, the method further comprising, after forming the mask structure and before electroplating the magnetic material, performing a second material removal process to remove portions of the side walls that are not protected by the mask structure.

8. The method as in claim 1 wherein the material removal process comprises reactive ion etching.

18

9. The method as in claim 1 wherein the electroplated magnetic material has an edge that is aligned with the edge of the mask structure.

10. The method as in claim 1 wherein the magnetic material comprises NiFe or Co—Fe.

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