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(54) **APPARATUS AND METHOD FOR
DETECTING ARTICLE MULTIFEED IN A
PREDEFINED REGION OF A FLAT ARTICLE**

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(52) **U.S. Cl.** **271/262; 271/265.04; 271/258.01**

(58) **Field of Classification Search** **271/258.01,**
271/262, 265.04, 265.01; 700/228

See application file for complete search history.

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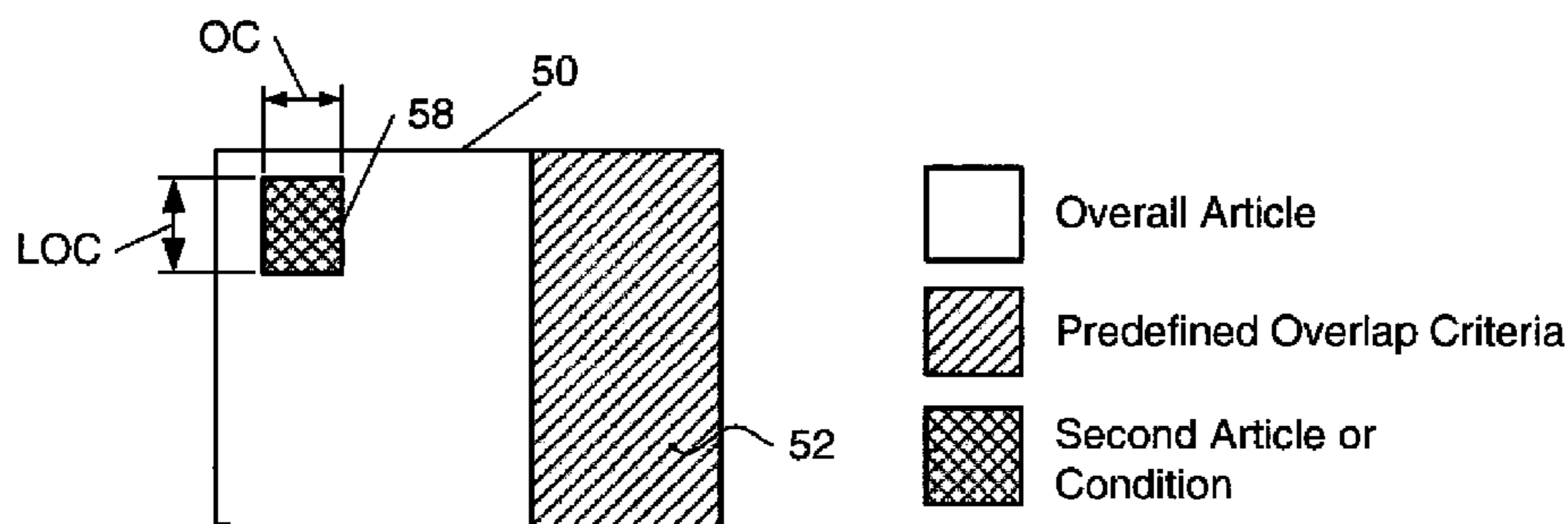
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(57) **ABSTRACT**

A document processing device capable of detecting a multi-
feed condition is configured to determine criteria of the mul-
tifeed or condition. If a detected multifeed meets the criteria,
a detection of the multifeed or condition may be ignored.

10 Claims, 11 Drawing Sheets



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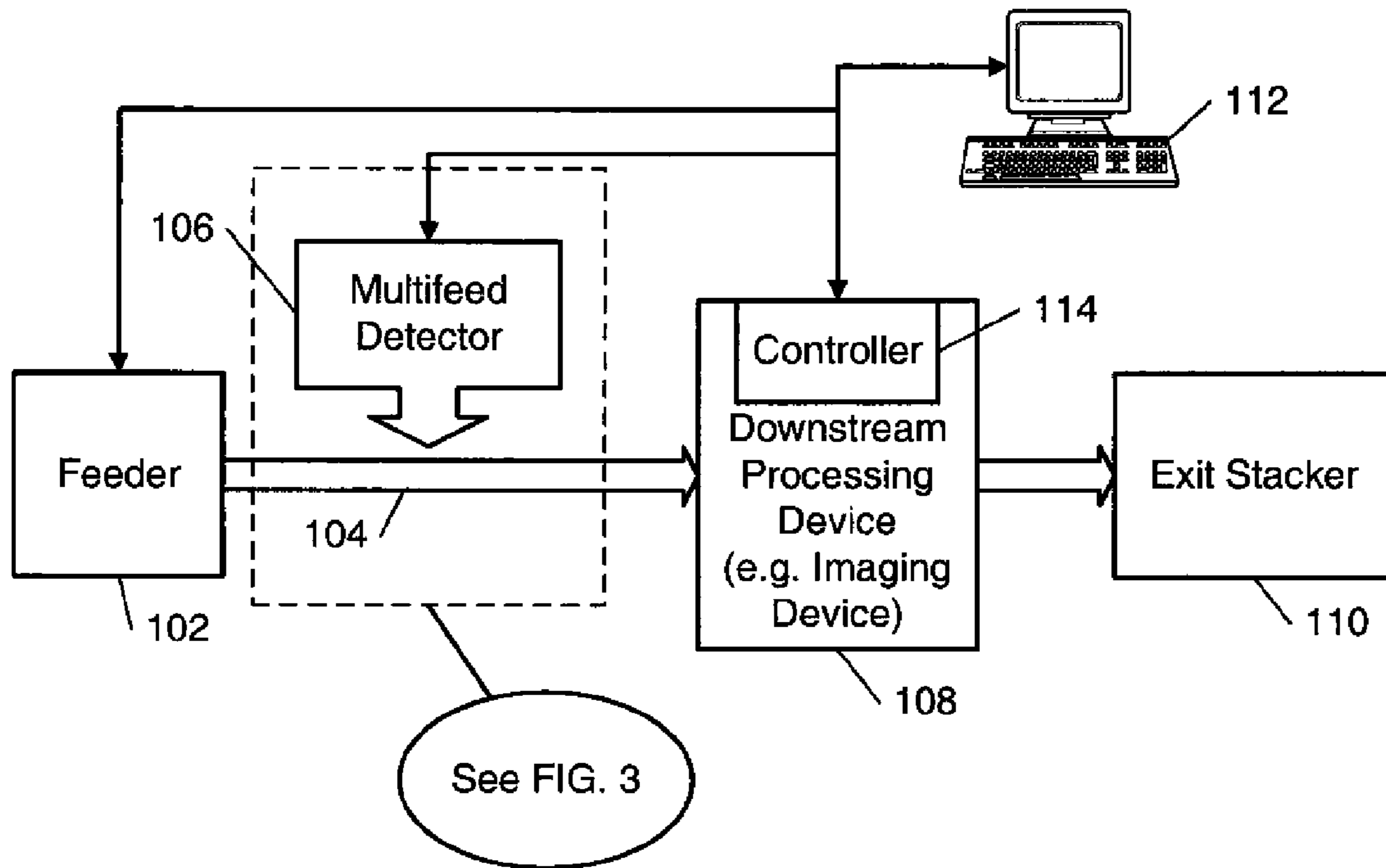


FIG. 1

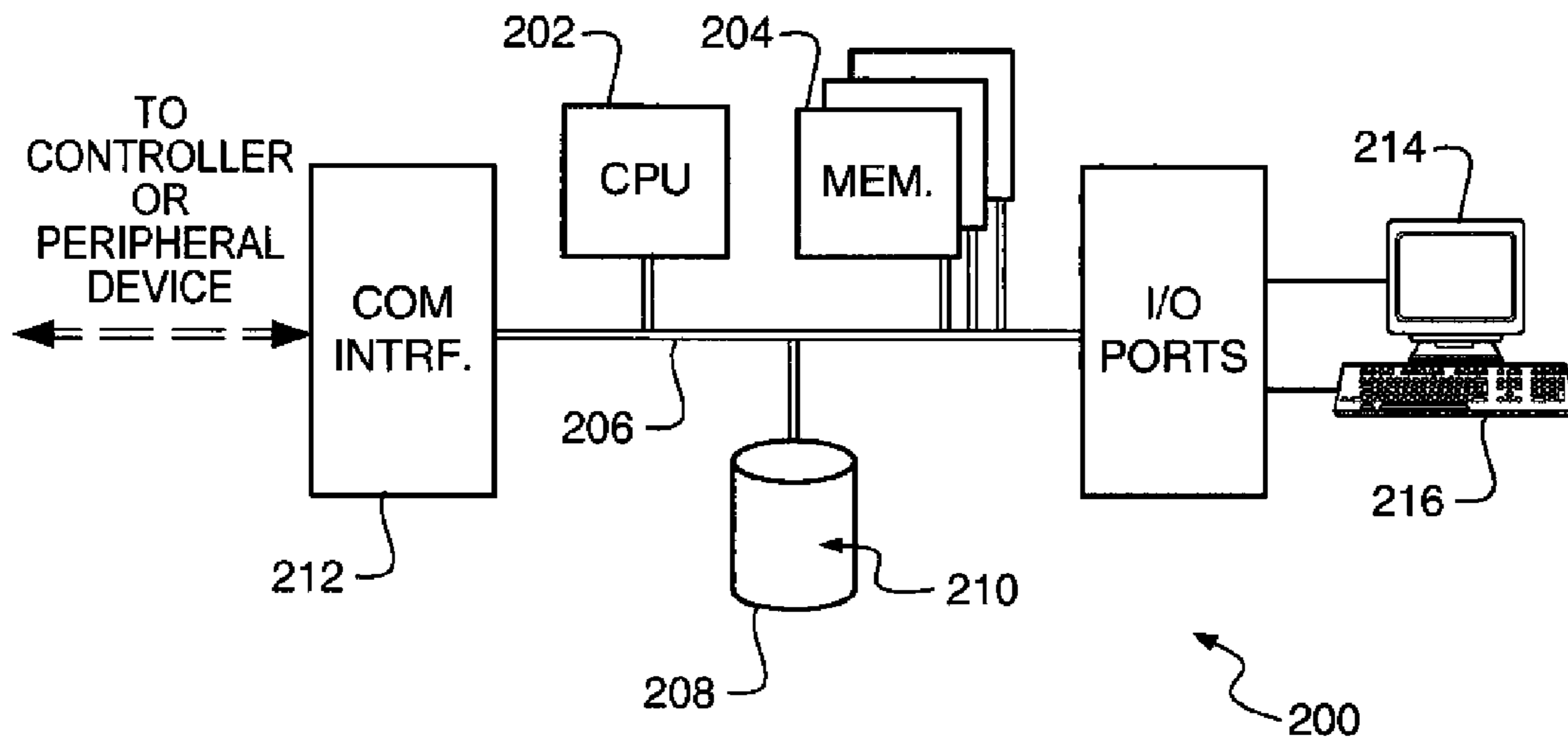


FIG. 2

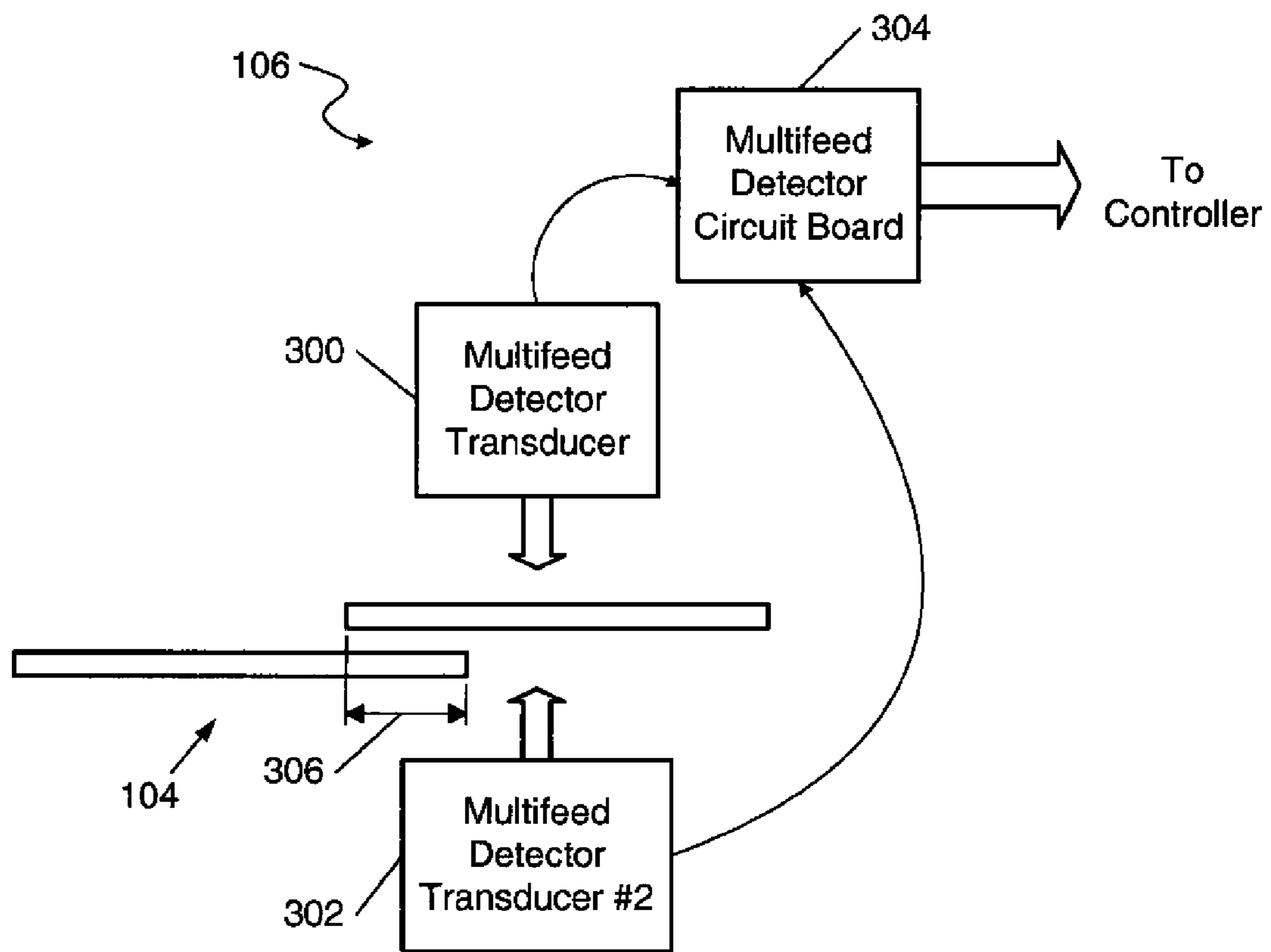


FIG. 3

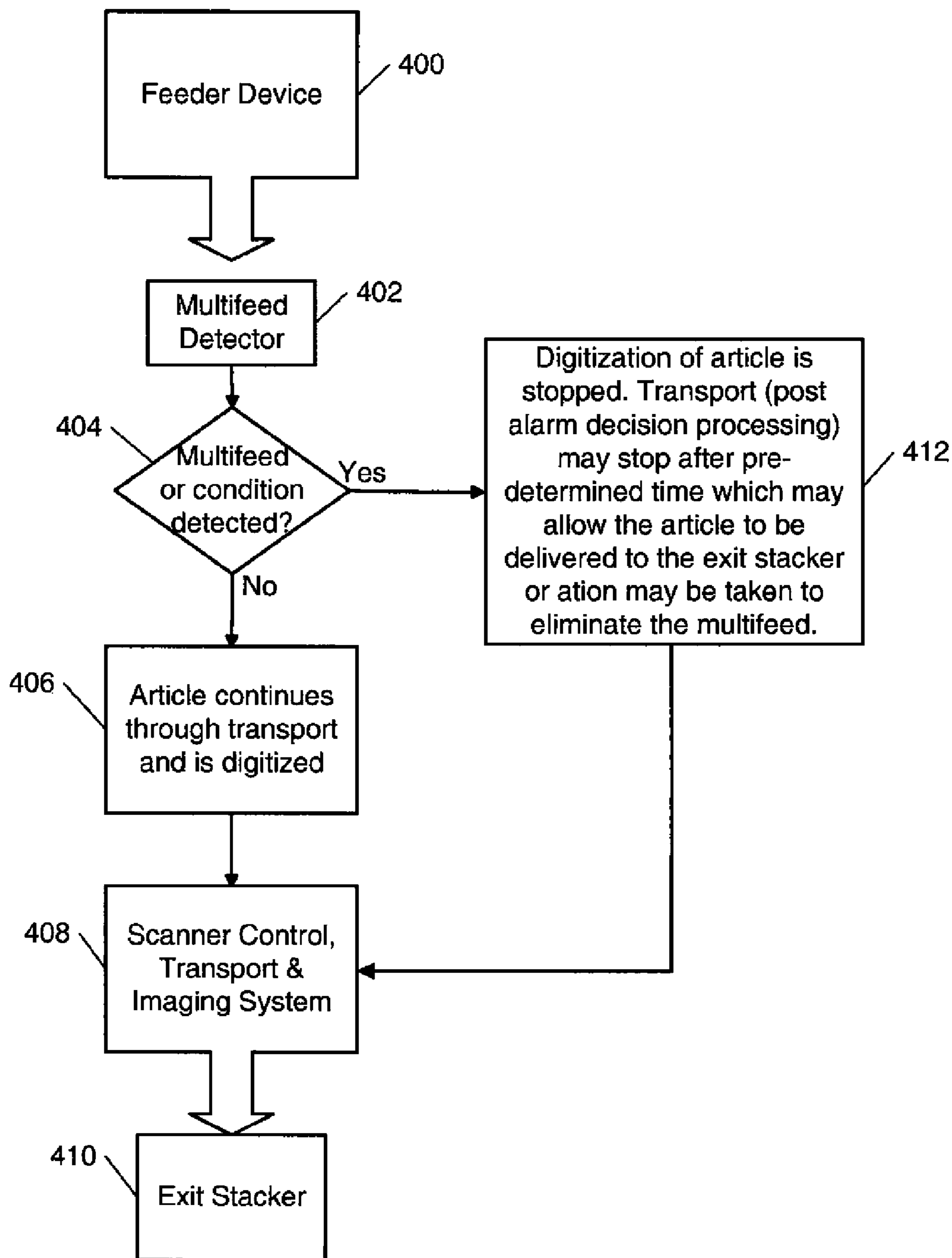


FIG. 4

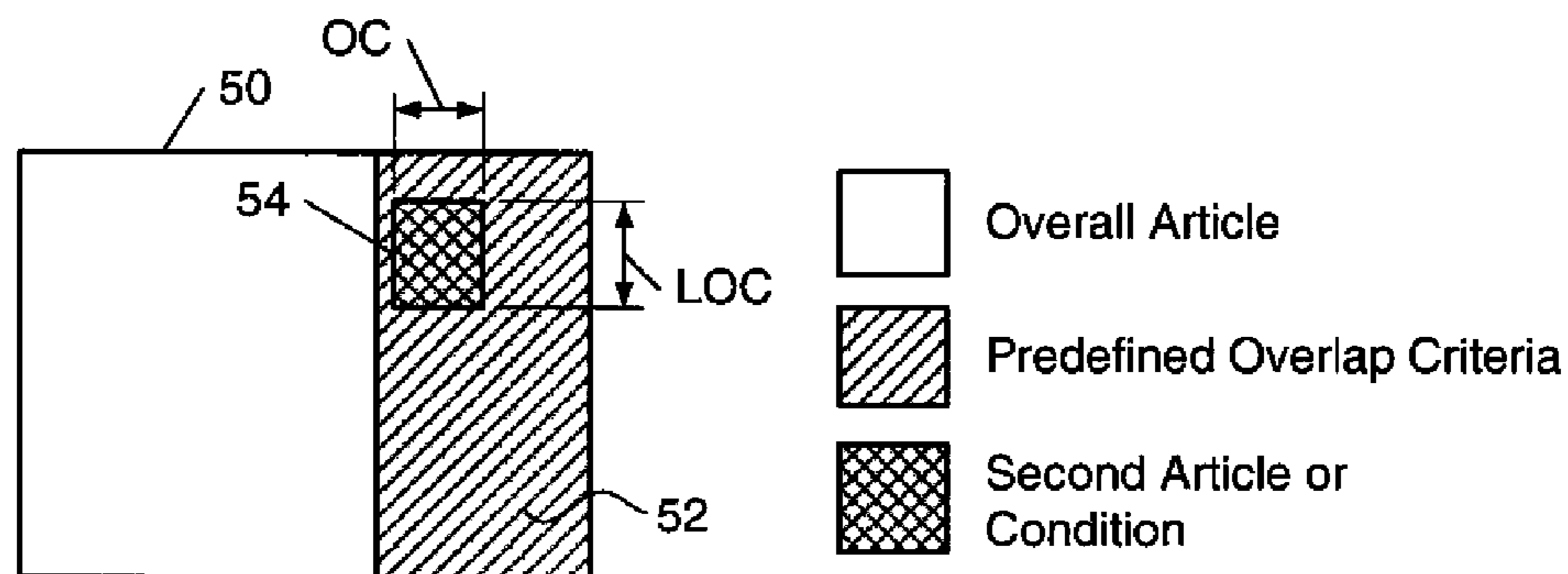


FIG. 5A

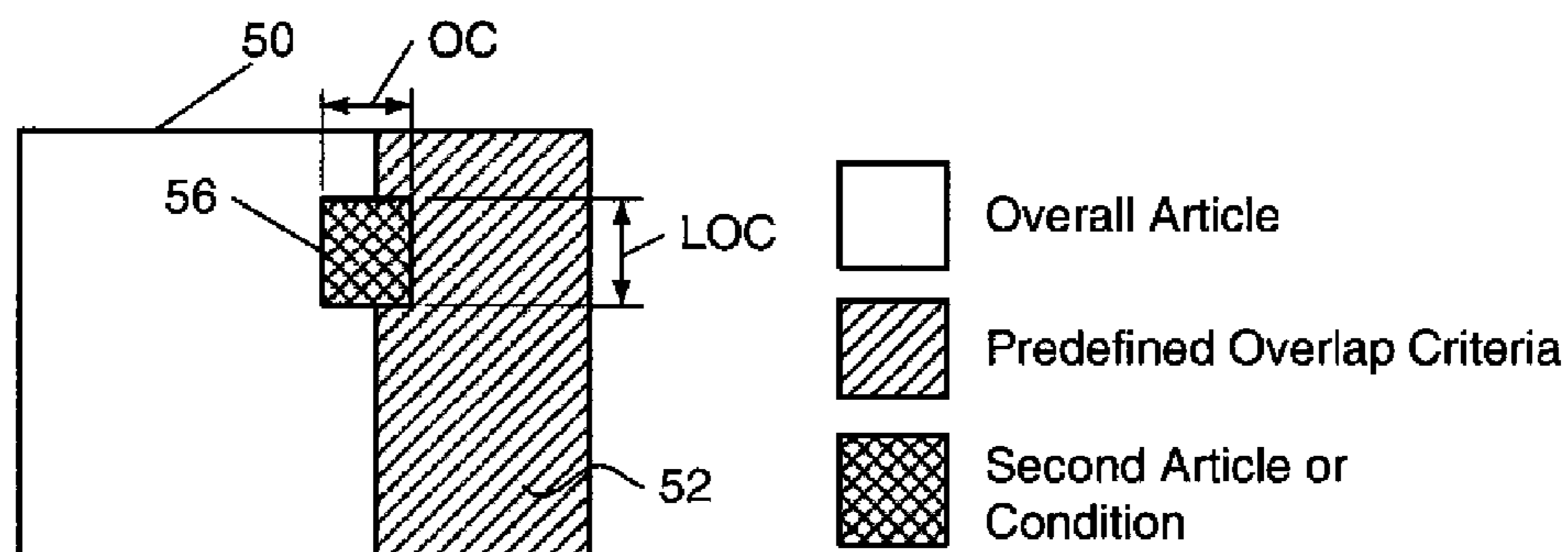


FIG. 5B

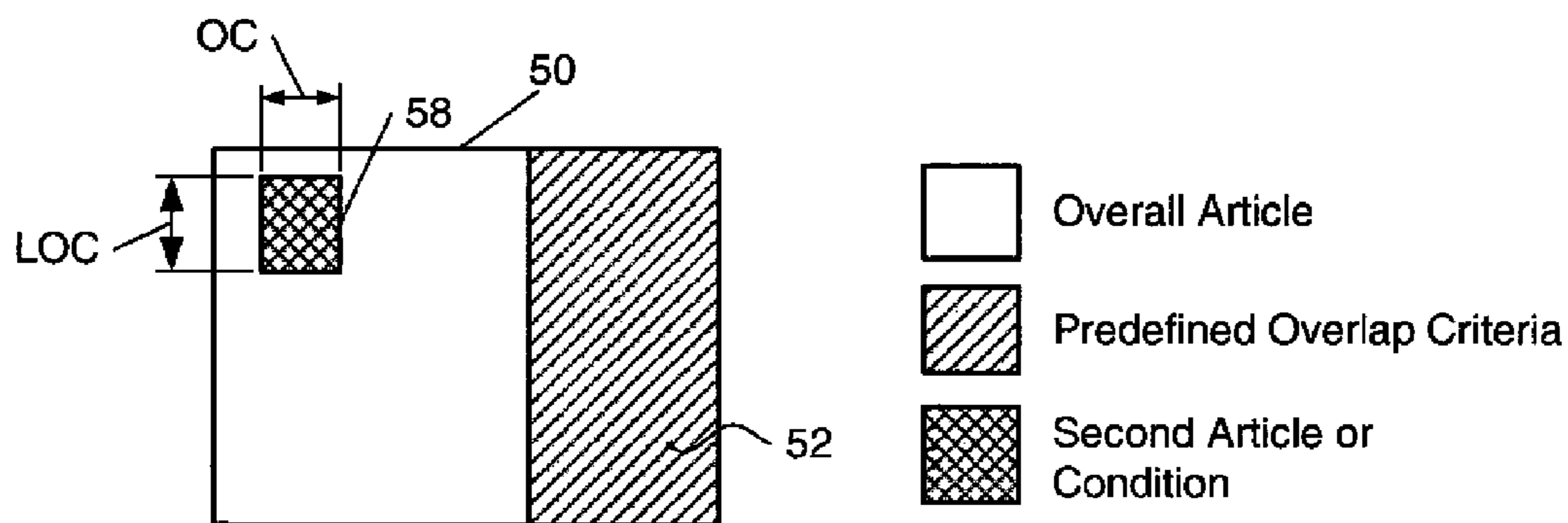


FIG. 5C

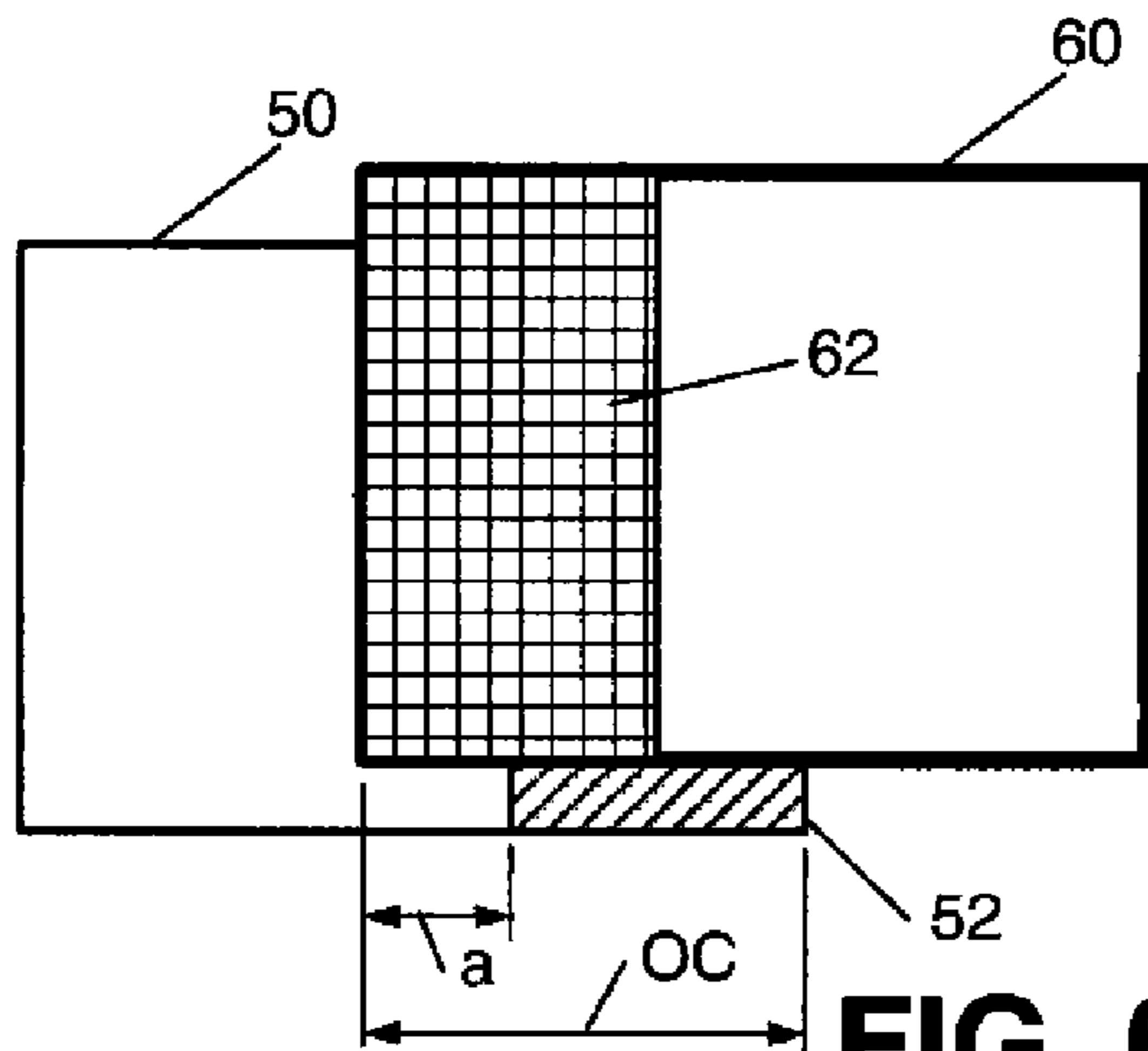


FIG. 6A

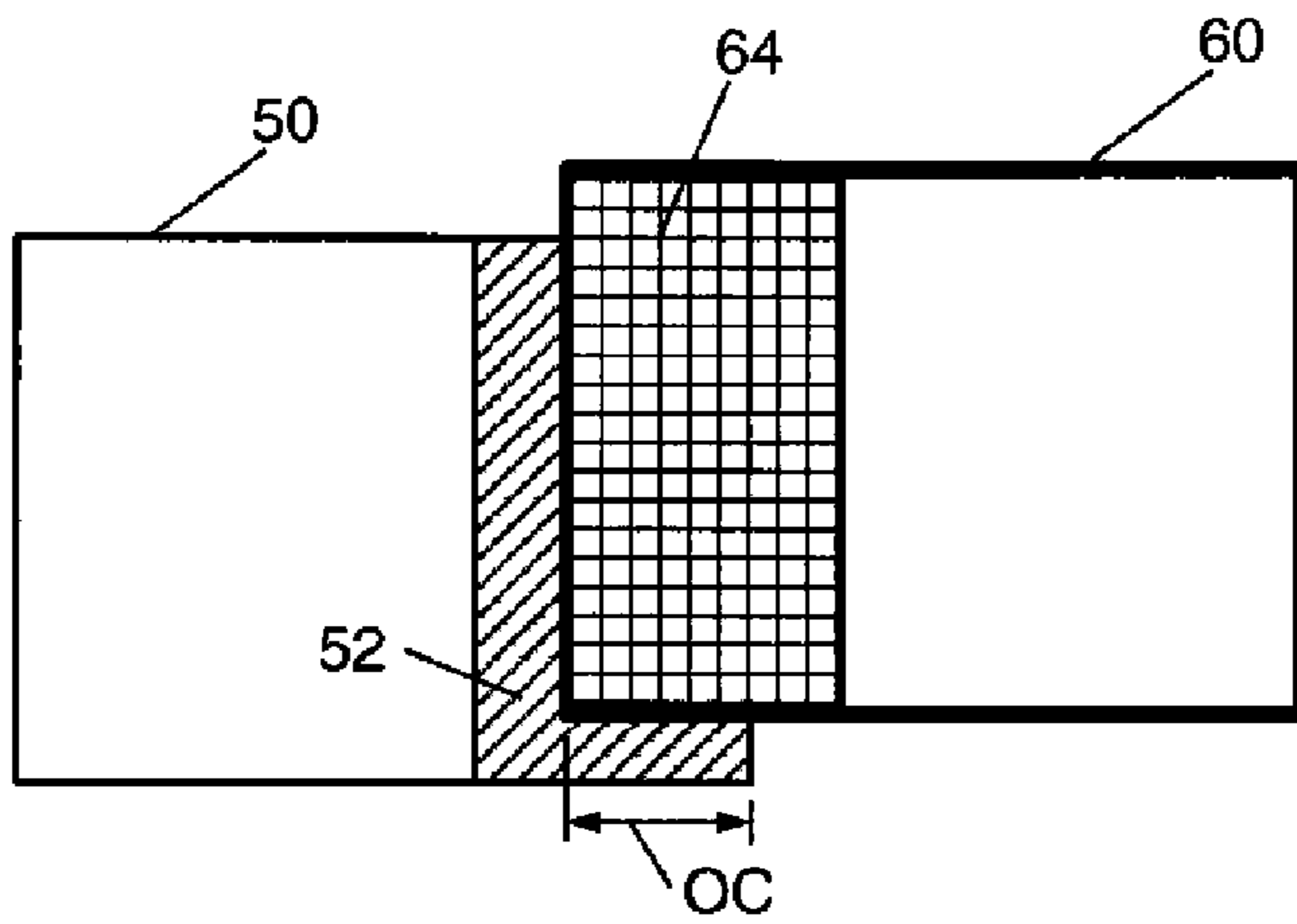


FIG. 6B

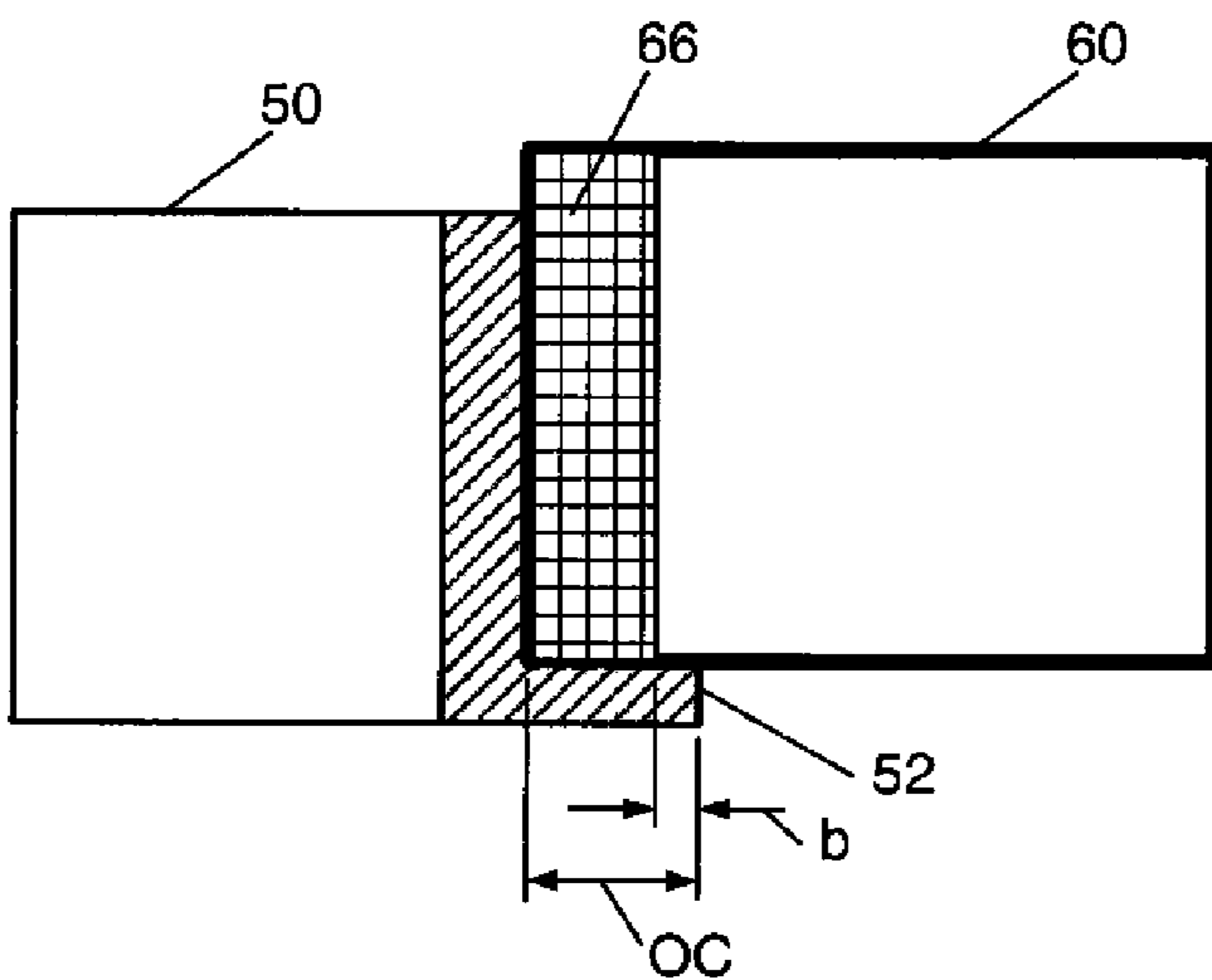


FIG. 6C

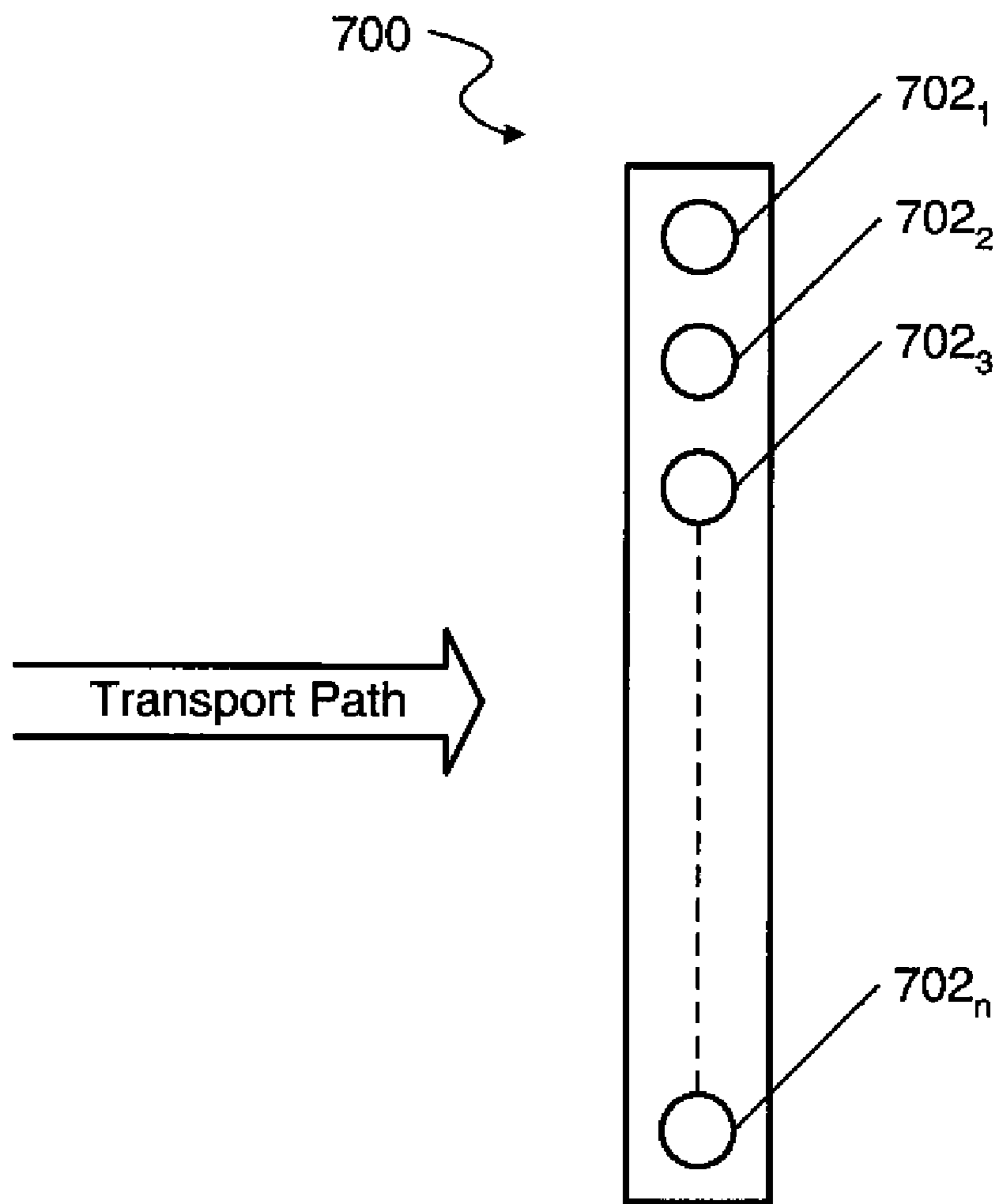


FIG. 7

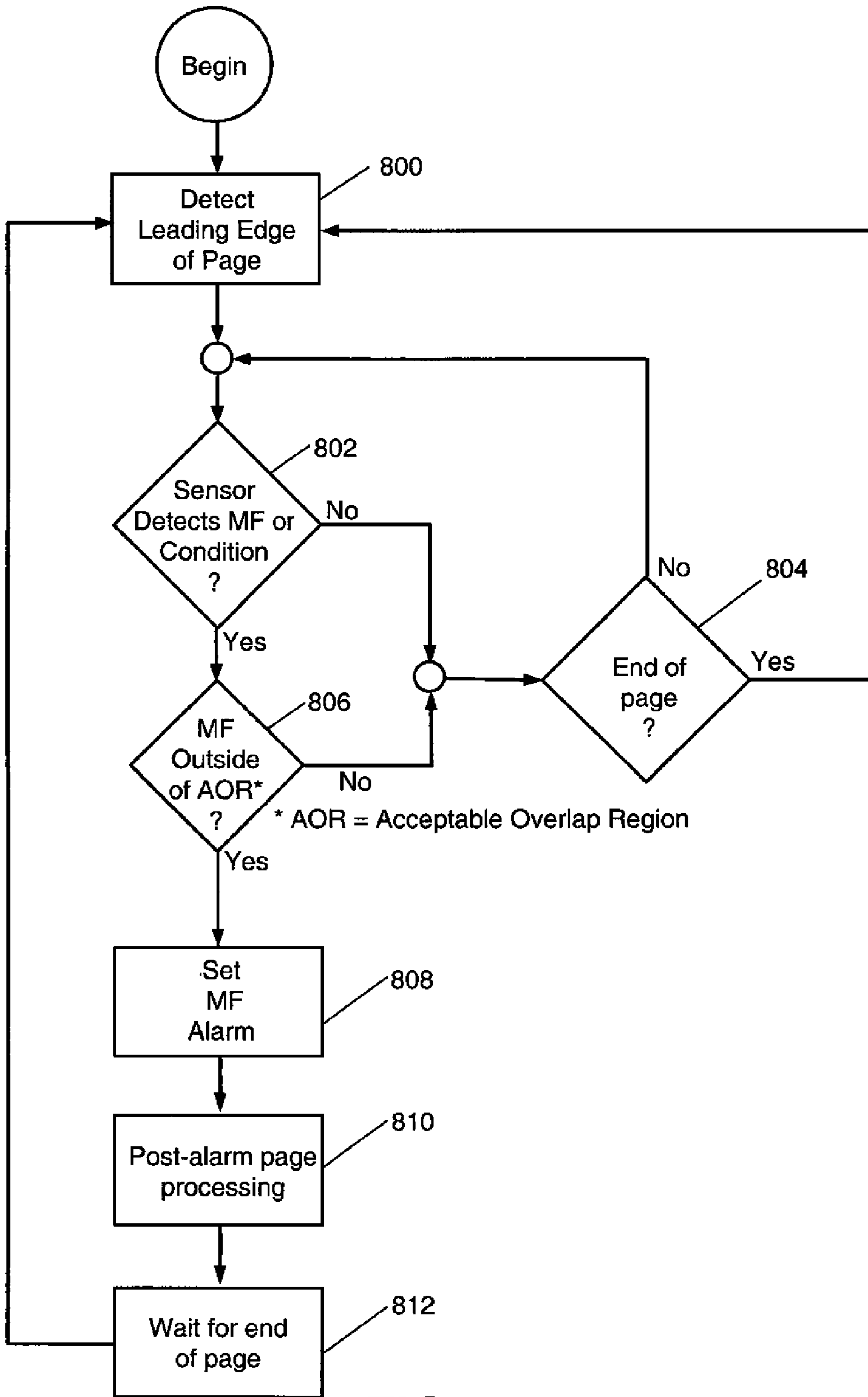


FIG. 8

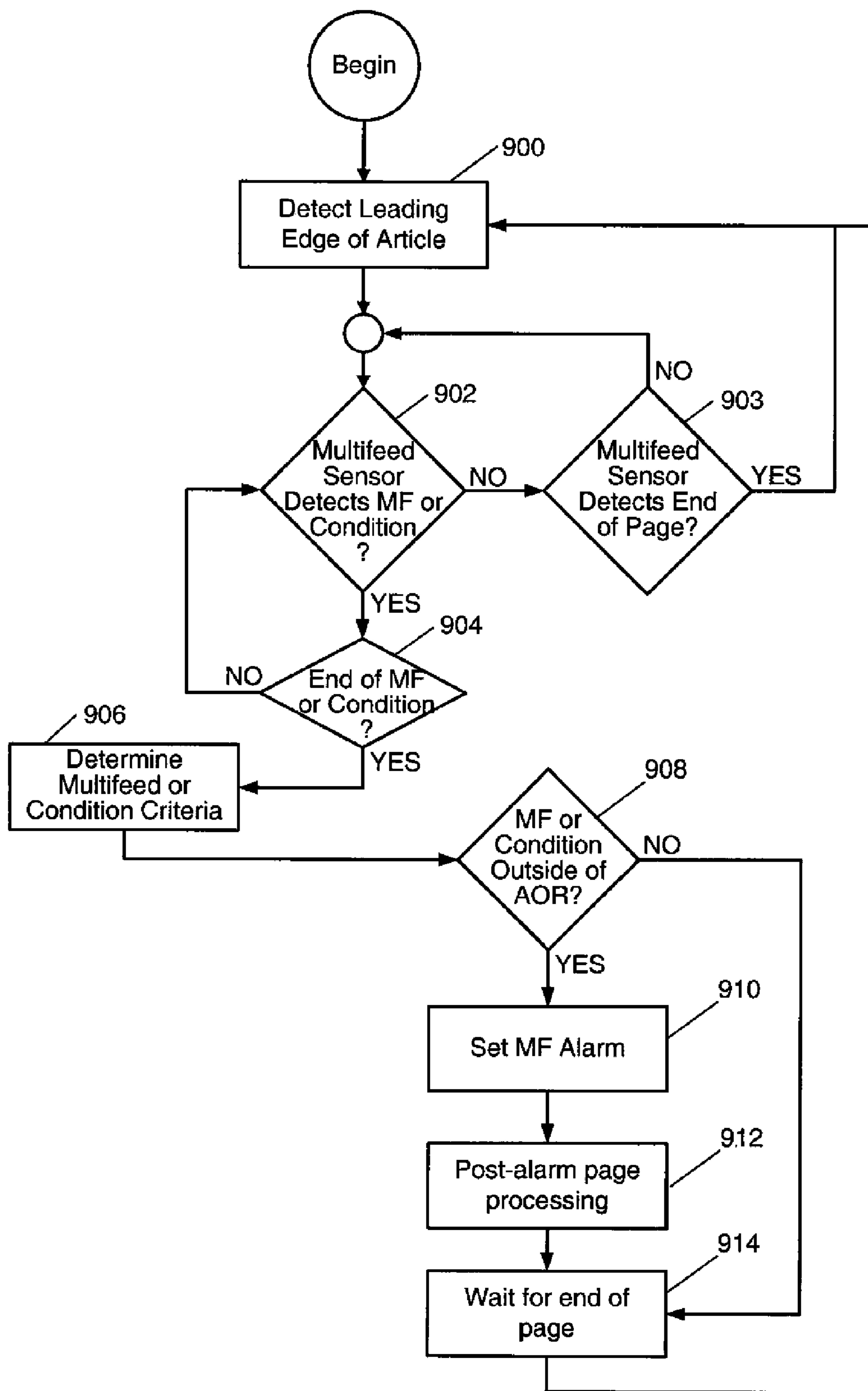


FIG. 9

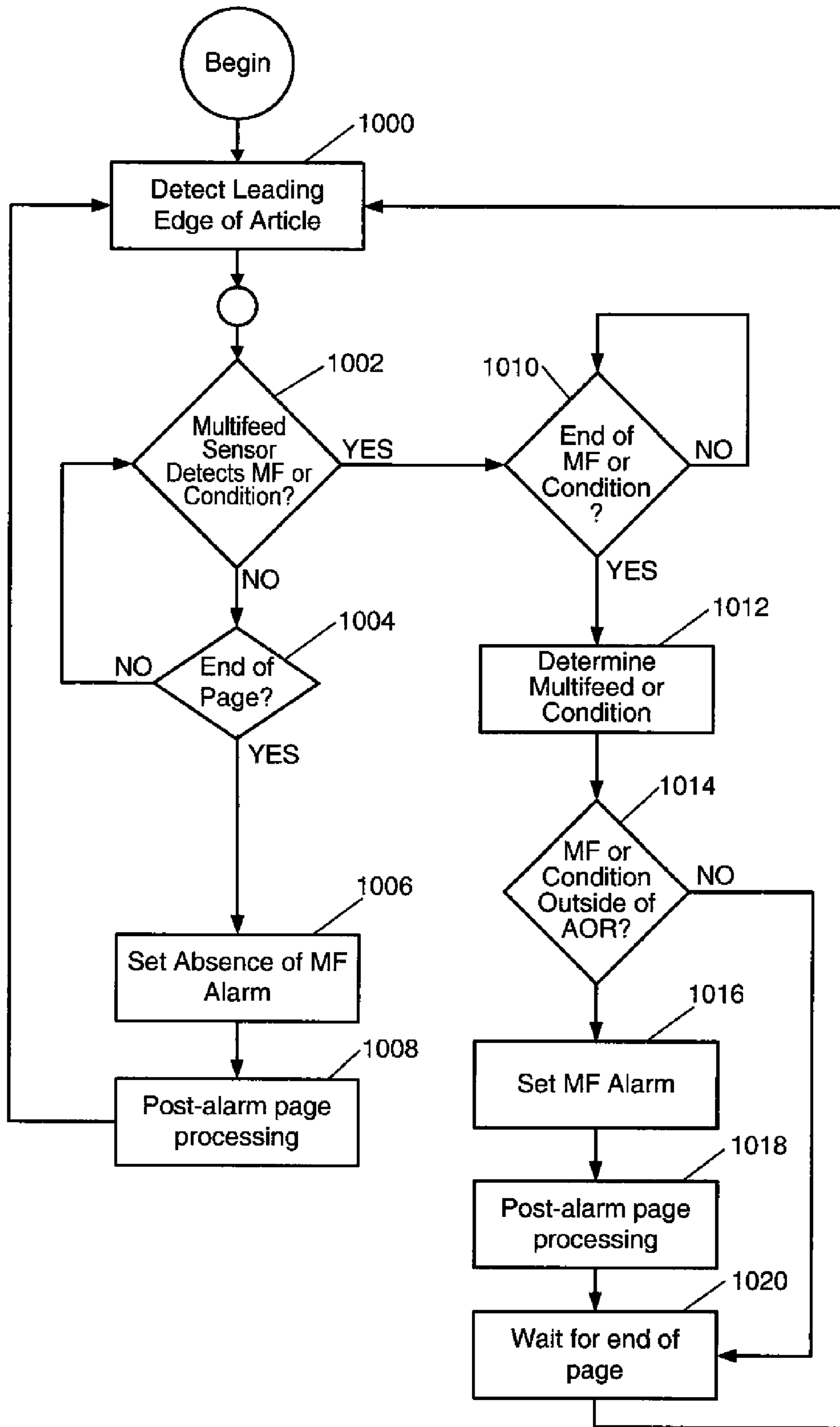


FIG. 10

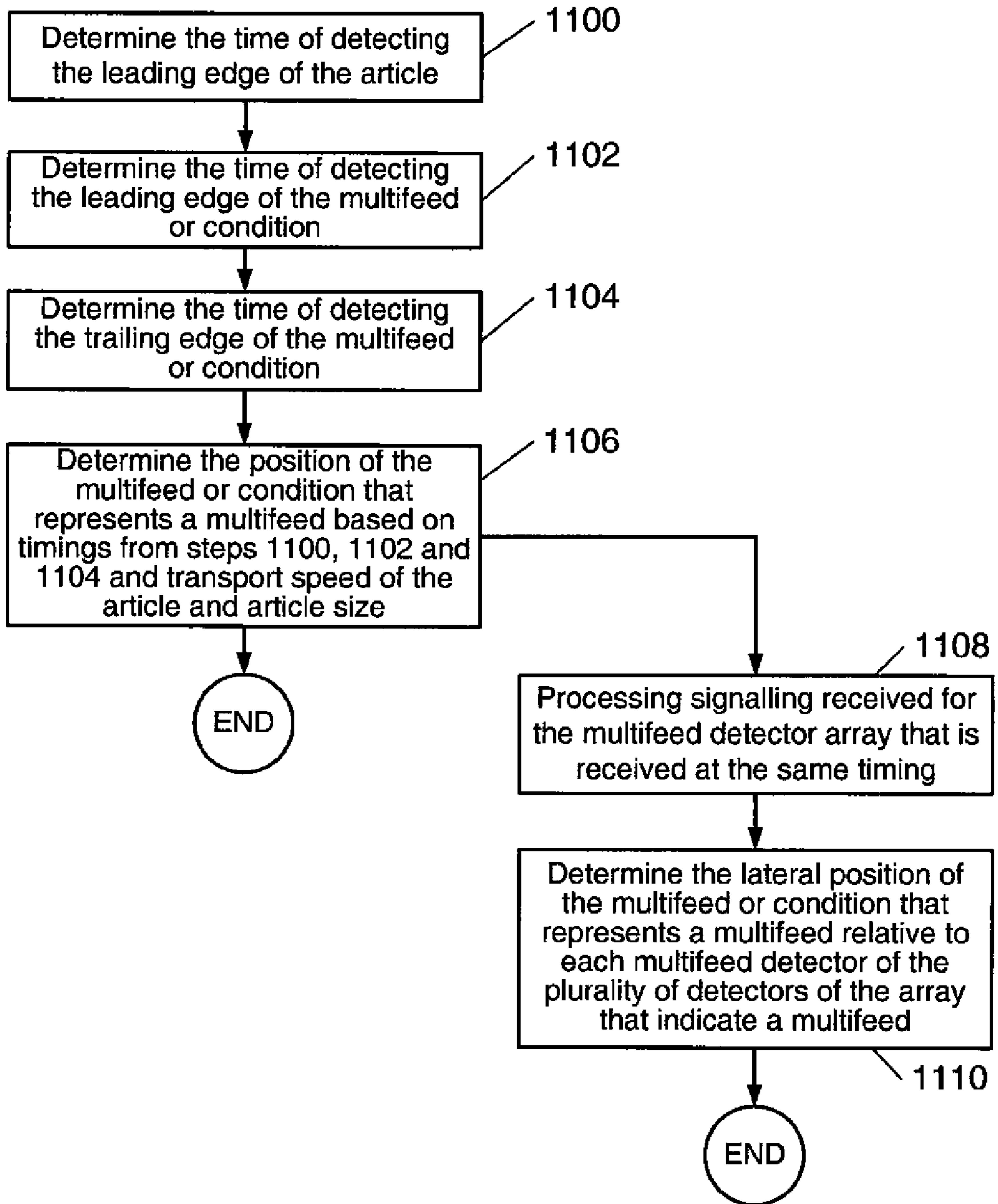


FIG. 11

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**APPARATUS AND METHOD FOR
DETECTING ARTICLE MULTIFEED IN A
PREDEFINED REGION OF A FLAT ARTICLE**

CROSS REFERENCE TO RELATED
APPLICATIONS

This application is a continuation of prior U.S. patent application Ser. No. 11/019,108, filed Dec. 22, 2004 now U.S. Pat. No. 7,654,521, now allowed as of Sep. 17, 2009 which claims the benefit of U.S. Provisional Patent Application No. 60/559,652, filed Apr. 6, 2004, each of which is incorporated herein by reference in its entirety.

FIELD OF THE INVENTION

The present subject matter relates to multifeed detection, and more particularly, to detection of multifeed of sheets, pages, documents or like articles.

BACKGROUND OF THE INVENTION

In document processing devices that process a plurality of documents one at a time, on occasion multifeeds occur. Multifeeds are the overlapping of sheets, pages, documents, or like articles that are transported through a respective document processing device. Conventionally, when such a multifeed occurs and is detected, an alarm will sound and/or operation of the document processing device will be halted.

Most multifeeds are unacceptable, e.g., in a scanner which will miss scanning part or all of a page when at least two pages are simultaneously fed. The inventors, however, have found that some multifeeds are acceptable, examples of which include a document which is affixed to another document, or special media in which documents detachably overlap. Other acceptable multifeed types are possible and are discussed further herein. When some multifeeds are acceptable, document process devices that trigger an alarm or halt production when even a multifeed is detected degrade throughput because they require a user to check and confirm whether or not each and every multifeed is acceptable.

What is needed is a document processing device that allows for acceptable multifeeds to occur, to increase document processing throughput, but still trigger an alarm for unacceptable multifeeds.

SUMMARY OF THE INVENTION

The disclosed concepts include a method and program product for processing a plurality of articles. When an article is received for processing and a condition is detected that may represent a multifeed including the article, it is determined whether or not the condition represents an unacceptable multifeed based on criteria of the condition relative to the article. In the event that the overlap criteria is within the predefined overlap criteria, article processing continues. Alternatively, in the event that the overlap criteria is not within the predefined overlap criteria, article processing discontinues. Advantageously, each time a condition representing a multifeed is detected, it is determined whether or not the multifeed is unacceptable, thus increasing throughput and decreasing processing time.

Criteria of the condition is determined by detecting a leading edge of the condition that may represent the multifeed that traverses a direction of article transport, and detecting a trailing edge of the condition that may represent the multifeed that traverses the direction of article transport. Based on these

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detections, the criteria of the condition may be determined based at least on a preset size of the article, a transport speed of the article, and timing between the two detections.

In another unique aspect, the disclosed concepts include a method and program product of processing a plurality of articles by receiving an article for processing, detecting a multifeed including the article, and determining a position of an overlap of the multifeed relative to the article. It is determined whether the position of the overlap is within an acceptable range to continue processing the article. In the event that the position is within the predefined overlap criteria, article processing continues. In the event that the position is not within the predefined overlap criteria, article processing discontinues.

A position of the overlap is determined by detecting a leading edge of the overlap of the multifeed that traverses a direction of article transport, detecting a trailing edge of the overlap that traverses the direction of article transport, and determining the position of the multifeed relative to the article based at least on a preset size of the article, a transport speed of the article, and timing between each detection.

In even another unique aspect, the disclosed concepts include a method of processing a plurality of articles by receiving an article for processing, detecting a leading edge of the article relative to a direction of article transport, detecting a trailing edge of the article relative to the direction of article transport, and determining if a condition that may represent a multifeed including the article is present. In an event the condition is not present, article processing discontinues. In an event the condition is present, it is determining whether or not the condition represents an unacceptable multifeed based on criteria of the condition relative to the article.

Even yet another unique aspect of the disclosed concepts includes an article processing device including a transport path on which an article is conveyed, a detector positioned relative to the transport path for detecting a condition that may represent a multifeed including the article, and a controller configured to receive signaling from the detector and process the received signaling for determining criteria of the condition that may represent the multifeed relative to the article. The controller is further configured to determine whether the condition that may represent the multifeed is acceptable by comparing the criteria with a predefined overlap criteria. The controller is also configured to determine the criteria based on a first time of detecting a leading edge of an overlap that traverses a direction of article transport, a second time of detecting a trailing edge of the overlap that traverses the direction of article transport, a size of the article, and a transport speed of the article. The article processing device may further include a feeder configured to separate the article from a plurality of articles and feed the article to the transport path, and a downstream processing device positioned downstream of the transport path to receive the article.

Another unique aspect of the disclosed concepts includes a scanner for detecting a multifeed comprising at least two sheets. The scanner includes a feeder configured to separate a sheet from a plurality of sheets and feed the sheet to a transport path, a multifeed detector positioned relative to the transport path for detecting a multifeed including the sheet, an imaging device positioned downstream of the transport path to receive the sheet, and a controller configured to receive signaling from the multifeed detector and process the received signaling for determining an overlap criteria of the multifeed relative to the sheet. The controller is further configured to determine whether the multifeed is acceptable by comparing the overlap criteria with a predefined overlap criteria. Moreover, the controller is configured to determine the

overlap based on a first time of detecting a leading edge of an overlap of the multifeed that traverses a direction of article transport, a second time of detecting a trailing edge of the overlap, a size of the sheet, and a transport speed of the sheet.

The foregoing and other features, aspects, and advantages of the present subject matter will become more apparent from the following detailed description when taken in conjunction with the accompanying drawings.

BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1 is an exemplary block diagram of a document processing system.

FIG. 2 is an exemplary block diagram of a computer or computer system.

FIG. 3 is an exemplary block diagram of the multifeed sensor illustrated by FIG. 1.

FIG. 4 is an exemplary flow chart of the operation of the document processing system of FIG. 1.

FIG. 5A-C illustrate exemplary multifeed types in which a document is affixed to another document.

FIG. 6A-C illustrate exemplary multifeed types in which at least two documents overlap.

FIG. 7 illustrates an array of multifeed sensors.

FIG. 8 illustrates an exemplary flowchart of the operation of the document processing device for detecting multifeeds and determining whether or not they are within an acceptable range.

FIG. 9 illustrates a detailed exemplary flowchart corresponding to that of FIG. 8.

FIG. 10 illustrate an exemplary flowchart of the operation of the document processing device for detecting the absence multifeeds.

FIG. 11 illustrates an exemplary flowchart for determining overlap region and lateral overlap region.

DETAILED DESCRIPTION OF THE INVENTION

FIG. 1 illustrates a block diagram of a document processing device 100 for processing a plurality of single documents, sheets, pages, or like articles, that has the capability of detecting multifeed. The term "article" as used herein includes any type of single document, page, sheet, envelope, flat, mail-piece, etc., capable of being separated from a plurality of similar articles and separately transported through the document processing device or other article-handling equipment.

In FIG. 1, feeder device 102 is configured to separate an article from a plurality of articles, e.g., a stack, and feed the separated article to a transport path 104. Any type of feeder device 102 capable of separating an article from a plurality of articles may be used for this purpose. Various types of devices are known to one of ordinary skill in the art. On occasion, feeder device 102 does not completely separate an article from a plurality of articles, causing a multifeed. By positioning a multifeed detector 106 relative to the transport path 104, multifeeds may be detected and a feeder device and/or a downstream processing device 108 may be controlled accordingly. In a normal operation (without the occurrence of a multifeed), each article is conveyed along the transport path 104, applied to downstream processing device 108, and collected by exit stacker 110.

User interface 112 is in communication with controller 114, which is configured to control operation of the document processing device 100. A user may set parameters of operation of the document processing device 100 with user interface 112, for instance to cause controller 114 to disengage multifeed detection by deactivating multifeed detector 106.

Other operation parameters may be set, and are known to those of ordinary skill of the art. For example, after a predetermined number of multifeed detections, operation of the feeder device 102 may be halted for inspection and/or a message may be displayed recommending feeder device 102 inspection.

User interface 112, controller 114 or both may be a computer configured with a microprocessor and memory for setting user-defined parameters or controlling the processing of document processing device 100. FIG. 2 is a functional block diagram of such a computer.

The exemplary computer system 200 contains a central processing unit (CPU) 202, memories 204, and an interconnect bus 206. The CPU 202 may contain a single microprocessor, or may contain a plurality of microprocessors for configuring the computer system 200 as a multi-processor system. The memories 204 include a main memory, a read only memory, mass storage devices such as various disk drives, tape drives, etc., or any combination thereof. The main memory typically includes dynamic random access memory (DRAM) and high-speed cache memory. In operation, the main memory stores at least portions of instructions for executing data for processing by the CPU 202.

The mass storage 208 may include one or more magnetic disk or tape drives or optical disk drives, for storing data and instructions for use by CPU 202. For a workstation PC, for example, at least one mass storage system 208 in the form of a disk drive or tape drive, stores the operating system and application software as well as a data or operation file(s) 210. The mass storage 208 within the computer system 200 may also include one or more drives for various portable media, such as a floppy disk, a compact disc read only memory (CD-ROM or DVD-ROM), or an integrated circuit non-volatile memory adapter (i.e. PC-MCIA adapter) to input and output data and code to and from the computer system 200.

The system 200 also includes one or more input/output interfaces 212 for communications, shown by way of example as an interface for data communications to controller 114 or user interface 112 (depending on implementation) or another peripheral device. The interface may be a USB port (for connecting, e.g., a scanner), a modem, an Ethernet card or any other appropriate data communications device. The physical communication links may be optical, wired, or wireless. If used for scanning, the communications enable the computer system 200 to send scans and documentation thereof to a printer (not shown) or another appropriate output or storage device.

If the computer system 200 is used as controller 114, a discrete interface (not shown) also may connect to the multifeed detector 106 to receive data associated with detection, and connect to feeder device 102 for controlling the operation thereof. It is known to those of skill in the art that the computer system 200 need not have all of the components discussed above if used as controller 114. Rather, it may be formed on one or more circuit boards. Any type of communication implementation for receiving and transmitting information to and from components of the document processing device 100 and components external to the document processing device 100 may be utilized.

The computer system 200 may further include appropriate input/output ports for interconnection with a display 214 and a keyboard or keypad 216 serving as the respective user interface. For example, the computer system 200 may include a graphics subsystem to drive the output display. The output display may include a cathode ray tube (CRT) display or liquid crystal display (LCD). These may be integrated with document processing device or separate. Although not

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shown, computer system **200** may include a port for connection to a printer. The input control devices for such an implementation of the system would include the keyboard for inputting alphanumeric and other key information. The input control devices for the system may further include a cursor control device (not shown), such as a mouse, a trackball, stylus, or cursor direction keys. The links of the peripherals to the system may be wired connections or use wireless communications.

The computer system **200** shown and discussed is an example of a platform supporting processing and control functions of the document processing device **100** described herein. Functions of the document processing device **100** and computer processing operations discussed herein may be controlled by a single computer system, or two separate systems; or one or both of these functions may be distributed across a number of computers.

The software functionalities of the computer system **200** involve programming, including executable code as well as associated stored data. Software code is executable by the general-purpose computer **200** that functions as a device controller. In operation, the code and possibly the associated data records are stored within the general-purpose computer platform **200**. At other times, however, the software may be stored at other locations and/or transported for loading into the appropriate general-purpose computer system. Hence, the embodiments involve one or more software products in the form of one or more modules of code carried by at least one machine-readable. Execution of such code by a processor of the computer platform enables the platform to implement the catalog and/or software downloading functions, in essentially the manner performed in the embodiments discussed and illustrated herein.

As used herein, terms such as computer or machine “readable medium” refer to any medium that participates in providing instructions to a processor for execution. Such a medium may take many forms, including but not limited to, non-volatile media, volatile media, and transmission media. Non-volatile media include, for example, optical or magnetic disks, such as any of the storage devices in any computer(s) operating as one of the server platform, discussed above. Volatile media include dynamic memory, such as main memory of such a computer platform. Physical transmission media include coaxial cables; copper wire and fiber optics, including the wires that comprise a bus within a computer system. Carrier-wave transmission media can take the form of electric or electromagnetic signals, or acoustic or light waves such as those generated during radio frequency (RF) and infrared (IR) data communications. Common forms of computer-readable media therefore include, for example: a floppy disk, a flexible disk, hard disk, magnetic tape, any other magnetic medium, a CD-ROM, DVD, any other optical medium, punch cards, paper tape, any other physical medium with patterns of holes, a RAM, a PROM, and EPROM, a FLASH-EPROM, any other memory chip or cartridge, a carrier wave transporting data or instructions, cables or links transporting such a carrier wave, or any other medium from which a computer can read programming code and/or data. Many of these forms of computer readable media may be involved in carrying one or more sequences of one or more instructions to a processor for execution.

Referring back to FIG. 1, at times, the feeder device **102** may not completely separate at least two articles, causing a multifeed to be applied to the transport path **104**. In this instance, multifeed detector **106** detects a multifeed, and may halt operation of the feeder and/or the document processing device **100** and/or set a multifeed alarm for prompting user

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intervention. Alternatively, characteristics of a separated article may be interpreted as a multifeed.

Although the present principles are applicable to processing other types of articles that may be subject to multifeeds, many common examples relate to processing of individual pages or sheets. FIG. 3 illustrates a detailed block diagram of multifeed detector **106** of FIG. 1 for detecting multifeed of individual sheets or pages, etc. at the input of a scanner or the like. The detector **106** includes multifeed transducers **300**, **302** opposing one another that are positioned relative to a top and bottom of transport path **104**. Multifeed sensor circuit board **304** is in communication with transducers **300**, **302**, and processes signals received therefrom. Transducers **300**, **302** may use ultrasonic waves to detect an airgap between two sheets of paper, and more generally between two articles as in a multifeed. Also, these transducers are configured to detect a single sheet or no sheets. Transducers **300**, **302** are particularly useful for detecting an airgap between overlapping sheets or pages. However, other types of multifeed detectors **106** may be used that do not rely on detecting an airgap, and are known to those of skill in the art.

A high-frequency burst waveform is sent through one transducer **300** and received by the other transducer **302**. When no article is present, the signal received by the other transducer and processed by multifeed sensor circuit board **304** is at a first level. When one article is present, the signal received by the other transducer **302** and processed by multifeed sensor circuit board **304** is at a second level different from the first level. When an airgap is detected, as would be detected for a multifeed (overlap region **306** shown), the signal received by the other transducer **302** and processed by multifeed sensor circuit board **304** is at a third level different from the first and second level. In this instance, a multifeed is detected. However, a multifeed may be detected under special circumstances, which are discussed further starting with FIG. 5.

Document processing device **100** may embody any type of device which employs a feeder **102** for separating an article from a plurality of articles and a downstream processing device **108** for processing articles separated by feeder **102**. Types of devices could include a scanner, printer, fax machine, copy machine, bulk collator, etc. For discussion purposes, explanation will focus on operation of a scanner configured for multifeed detection. For ease of discussion, reference numbers will be used interchangeably. Overall document processing device **100** may be referred to as scanner **100**, and then the downstream processing device **108** may be referred to as the actual imaging device **108** within the scanner **100**. FIG. 1 even denotes that an imaging device **108** is an exemplar of a document processing device **108**. Reference to other components of the document processing device **100** will remain the same.

FIG. 4 illustrates a flow diagram of the operation of scanner **100**. In this discussion, reference will be made to components illustrated by FIGS. 1 and 3. In step **400**, feeder device **102** (FIG. 1) separates an article from a plurality of articles and applies the presumed separated article to transport path **104** (FIG. 1). In step **402**, multifeed detector circuit board **304** (FIG. 3) receives a signal from multifeed sensor transducer **302** (FIG. 3), and outputs a signal to the controller **114** (FIG. 1) at either the first, second or third signal level, as is described above. In step **404**, controller **114** (FIG. 1) processes the signal(s) received from multifeed detector **106**.

When the signal level is at the first or second level, no multifeed is detected. As described above, these signal levels would represent detection of a single article or no article. In step **406**, the article continues through the transport path **104**,

is received by imaging device **108**, and is scanned, imaged and digitized. In step **410**, the article is collected by the exit stacker **110**.

If a multifeed is detected, in step **412**, controller **114** (FIG. **1**) follows post alarm processing. For example, if document processing device **100** is a printer or copier, upon a multifeed detection, operation may be halted or other post alarm processing logic followed. Then, the multifeed may be conveyed to the exit stacker **110**, and/or user intervention may be required or other post alarm processing followed. Other types of post-alarm processing are well within the knowledge of one of ordinary skill in the art. Often, multifeed processing will depend on the device or equipment utilized.

Problems arise when articles applied to scanner **100** include a sheet with a self stick removable note affixed, photographs affixed to a larger sheet, a document having a sticker or other document affixed, articles with an adhesive such as an envelope, and even articles with special print. In these instances, multifeed detector **106** may detect an air gap, i.e., detect a condition that may represent a multifeed, and cause scanner **100** to halt operation. Also, multifeed detector **106** may be spoofed in detecting an airgap as in the case of special print. Notwithstanding, a condition that may represent a multifeed as used herein includes these instances and actual multifeeds. Further novel concepts discussed herein overcome these problems and further optimize scanner **100**.

FIGS. **5A**, **5B** and **5C** and **6A**, **6B** and **6C**, respectively illustrate various multifeed types. Other multifeed types are possible, but are not explicitly described herein. Predefined overlap criteria **52**, **62**, **64**, **66** shown in these figures represent parameters set by a user for a particular job or operation of scanner **100**. Predefined overlap criteria **52**, **62**, **64**, **66** may correspond to any portion of the overall article **50**, **60**. However, commonly illustrated is predefined overlap criteria **52** set corresponding to an end portion of a respective overall article **50**, **60**. Also shown is an overlap criteria (“OC”) and a lateral overlap criteria (“LOC”), which is discussed further in connection with FIG. **11**. Overlap criteria may also represent criteria of a condition that may represent a multifeed, e.g., as in the case of a photograph affixed to a piece of paper. However, to be consistent, these criterion are simply referred to as overlap criteria.

FIGS. **5A** to **5C** illustrate a second article **54**, **56**, **58**, respectively, affixed to the overall article, respectively, which constitutes the multifeed. Also, the second article **54**, **56**, **58** may represent a characteristic of the overall article **50** that could be interpreted as a multifeed. For example, the second article **54**, **56**, **58** may represent an adhesive, special print or ink applied to the overall article **50**, which produces an increased thickness that the detector senses and might otherwise interpret as multifeed.

FIGS. **6A** to **6C** illustrate multifeeds first and second overall articles **50**, **60**. Each of the first and second overall articles **50**, **60** has predefined overlap criteria **52** and **62**, **64**, **68**, respectively. The dimensions of the predefined overlap criteria **52**, **62**, **64**, **66** may be the same, as in FIGS. **6A** and **B**, or may be different, as shown in FIG. **6C**. For illustrative purposes, the first and second overall articles **50**, **60** are offset to show the actual overlap. In FIG. **6A**, the second overall article **60** overlaps with the first overall article **50** and extends beyond the predefined overlap criteria **52** specified for the first overall article **50** by a distance “a.” FIG. **6B** illustrates a multifeed in which the second overall article **60** overlaps with the first overall article **50**, and the overlap is within the predefined overlap criteria **52** defined for the first article **50** and predefined overlap criteria **64** for the second overall article **60**. FIG. **6C** illustrates a multifeed in which the second overall

article overlaps the first overall article **50**. As in FIG. **6B**, the overlap is within the predefined overlap criteria **52** for the first article **50**. However, the overlap is outside the predefined overlap criteria **66** defined for the second article **60** by a distance “b.”

In order to detect these various multifeed or condition types described above, multifeed detector **106** (FIG. **1**) may include an array **700** of transducers **7021**, **7022**, **7023** . . . **702n**, as shown by FIG. **7**. Only one array **700** is illustrated. However, typically two arrays **700** would oppose one another, as is described in connection with the transducers **300** and **302** in FIG. **3**. In this manner, the multifeed detector **106** may be configured to detect a multifeed or condition types of various types illustrated by FIGS. **5A** to **5C** and FIGS. **6A** to **6C**. In other words, the multifeed detector **106** would be capable of detecting a multifeed or condition along the entire width of the overall article, i.e., traverse the transport path **104**. As well, this array approach may be used to detect a multifeed comprising an overlap of articles, as shown in FIG. **6**. In this instance, a single set of opposed transducers **302**, **304** may be used, as described above in connection with FIG. **3**.

For determining whether a multifeed is within an acceptable range, two parameters may be compared. They include the predefined overlap criteria and the overlap criteria (or criteria of the condition that may represent the multifeed).

As is described in connection with FIGS. **5A** to **5C** and **6A** to **6C**, predefined overlap criteria **52** and **62**, **64** and **66** may be set by a user by specifying the area corresponding to the input media, (i.e., article type). Also, the user may set the type of article applied to the document processing device **100** (e.g., scanner **100**), such as letter-size paper. For example, a user may define the predefined overlap criteria **52**, **62**, **64**, **66** to extend a predetermined distance from the leading edge, as is illustrated by FIGS. **5A** to **5C** or extend a certain distance from the trailing edge, as is illustrated by FIGS. **6A** to **6C**. Moreover, predefined overlap criteria **52**, **62**, **64**, **66** does not need to be limited to an edge of an article. Rather, predefined overlap criteria **52**, **62**, **64**, **66** may be set to predetermined distances from each edge of an article. In other words, predetermined overlap criteria **52**, **62**, **64**, **66** may be set to any area of the article.

Referring to FIGS. **6A** and **6B**, predefined overlap criteria **52**, **62**, **64**, may be set to different areas depending on whether an article is leading or trailing another article. For example, in FIG. **6C**, a first predefined overlap criteria **66** may be set for an article that leads another article, and a second predefined overlap criteria **52** may be set for an article that trails another article. Setting predefined overlap criteria in this manner may be useful when scanning or copying is only needed for areas outside of the first and second predefined overlap criteria **66**, **52**.

FIG. **8** illustrates a general flow for processing multifeeds. In step **800**, the leading edge of an article is detected by the multifeed sensors described herein. In step **802**, it is determined whether the sensor detected a multifeed (“MF”) or a condition that may represent the multifeed (“condition”). If not, in step **804**, it is determined whether the end of the page has been detected. If not detected, the signals from the multifeed detector **106** (FIG. **1**) are continually monitored until the end of the article is detected, at which time the detector **106** detects the next leading edge, returning to step **800**.

If a multifeed is detected, in step **806**, it is determined whether the multifeed or condition is outside of predefined overlap criteria. Controller **114** may factor known dimensions of articles applied, transport speed of the article, detection of the multifeed or condition, etc., for determining the criteria of the multifeed or condition. By comparing these

characteristics with predefined overlap criteria **52, 62, 64, 66**, it may be determined whether the multifeed or condition is within the acceptable range in accordance with predefined overlap criteria.

As in the case of FIGS. **5B** and **5C** and FIGS. **6A** and **6C**, the multifeed or condition would be outside of acceptable range. As a result, in step **808**, the multifeed alarm may be set. In step **810**, there may be post-alarm page processing, such as halting the scanning operation, tagging a scan of the multifeed including the article for manual review, etc. When in step **812**, the end of the multifeed including the article is detected, the process returns to detecting the leading edge of the next article (step **800**).

If in step **804**, it is determined that the multifeed or condition is within acceptable range, as in the case of FIGS. **5A** and **6B**, the end of the article is detected in step **804**, and the scanner **100** is returned to detecting the next leading edge (step **800**). This avoids problems of the prior art.

FIG. **9** illustrates a flow chart of the operation of the scanner **100** in greater detail.

In step **900**, the leading edge of an article is detected by the multifeed detector **106** described herein. In step **902**, it is determined whether the multifeed detector **106** detected a multifeed (“MF”) or a condition that may represent the multifeed (“condition”). If not, in step **903**, it is determined whether the end of the article has been detected. If not detected, the signals from the multifeed detector **106** are continually monitored (returning to step **902**) until the end of the article is detected, at which time the multifeed detector **106** detects the next leading edge, returning to step **900**.

If a multifeed or condition is detected, in step **904**, the multifeed detector **106** is continually monitored (returning to step **902**) until the end of the multifeed or condition is detected. In step **906**, controller **114** may factor known dimensions of articles applied, transport speed of the article, detection of the multifeed or condition, etc., for determining multifeed overlap or condition criteria. By comparing this criteria with predefined overlap criteria **52, 62, 64, 66**, it may be determined whether the multifeed is within the acceptable range in accordance with predefined overlap criteria.

In step **908**, it is determined whether the overlap or condition criteria is within an acceptable overlap range, by comparing the overlap or condition criteria with the predefined overlap criteria of the first article, second article or both. If outside of the acceptable range, in step **910**, a multifeed alarm is set. In step **912**, there may be post-alarm page processing, such as halting the scanning operation, tagging a scan of the multifeed including the article for manual review, etc. When in step **912**, the end of the multifeed including the article is detected, the process returns to detecting the leading edge of the next article (step **900**).

If in step **908** the multifeed or condition is within the acceptable range, the end of article is detected, and no multifeed alarms is triggered. This overcomes the problems of the prior art.

Described in connection with FIG. **10**, scanner **100** may be configured to detect the absence of a multifeed or a condition that may represent the multifeed (“condition”) and trigger a different alarm. This may be applicable for detecting the absence of a label on an envelope. If a multifeed is detected, as described above, it may be determined whether positioning of the overlap or condition criteria is acceptable.

In step **1000**, the leading edge of an article is detected. If in step **1002**, a multifeed or condition is not detected, and in step **1004**, the end of the article is detected, the absence of a multifeed alarm is set, as in step **1006**. In step **1008**, post-

alarm processing may be performed, which may include halting operation or tagging the scan of the article.

If in step **1002**, the multifeed detector **106** detects a multifeed or condition, the process continues for determining whether the multifeed or condition is acceptable, as described above. For determining the multifeed or condition criteria, as in step **1012**, both the beginning of the multifeed or condition (step **1002**) and end of the multifeed or condition (step **1010**) may be considered. Controller **114** may factor known dimensions of articles applied, transport speed of the article, detection of the multifeed or condition, etc., for determining characteristics of the criteria of the multifeed or condition.

In step **1016**, it is determined whether the overlap or condition criteria is within an acceptable overlap range, by comparing the criteria with the predefined overlap criteria. If outside of the acceptable range, in step **1016**, a multifeed alarm is set. In step **1018**, there may be post-alarm page processing, such as halting the scanning operation, tagging a scan of the multifeed including the article for manual review, etc. When in step **1020**, the end of the multifeed including the article is detected, the process returns to detecting the leading edge of the next article (step **1000**). If in within the acceptable range (step **1014**), the end of the multifeed is detected, the process returns to detecting the leading edge of the next article.

In step **906** (FIG. **9**) and step **1012** (FIG. **10**), the position of the multifeed overlap or condition (i.e., criteria) is determined. The overlap or condition criteria may be determined by factoring various parameters including, but not limited to, detection of a leading edge of an article, detection of a trailing edge of an article, detection of a leading edge of the overlap or condition, detection of a trailing edge of the overlap or condition, article size, and article transport speed.

FIG. **11** illustrates an exemplary flow chart for detecting the position of the overlap criteria or criteria of a condition that may represent a multifeed based on at least these factors. Recall that in step **900** of FIG. **9** and in step **1000** of FIG. **10**, the leading edge of the article is detected. Adverting to FIG. **11**, in step **1100**, the time of this detection (e.g., 0 sec) is determined. When a multifeed detector **106** (FIG. **1**) detects a leading edge of an overlap or condition, as in step **1102**, the time of the detection (e.g., 1 sec) is determined. Similarly, in step **1104**, the time of the detection (e.g., 3 sec) of the trailing edge of the overlap or condition is determined. Because the article size and article transport speed is known, based on the times determined in steps **1100, 1102, and 1104**, a length and position of the overlap or condition region relative to the article may be determined. Adverting to FIGS. **5A-C** and **6A-C**, the length and position of the overlap region (“OC”) relative to the respective article is shown.

In FIGS. **5A** to **5C**, the lateral overlap criteria (“LOC”) is shown. Although it is not notated in FIGS. **6A-6C**, the LOC would correspond the width of each article. For determining the LOC, the multifeed sensor **700** including an array of transducers **7021, 7022, 7023 . . . 702n**, shown by FIG. **7** may be used. Because each transducer **702n** has a fixed position relative to the transport path **104** and article transported on this transport path **104**, the LOC size and position may be determined.

For instance, the array of transducers **700** may generate signaling at the same timing for detecting a multifeed or condition. In the event of the multifeed type shown in FIGS. **5A** to **5C**, a portion of transducers **702n** which is positioned relative to the lateral overlap (LOC) will generate signaling indicating detection of a multifeed or condition. The other portion of the transducers **702n** positioned outside of the LOC will generate signaling that indicates an absence of a multi-

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feed or condition. Therefore, in step 1108, signals received at the same timing (i.e., from each transducer 702_n of the array 700) indicates a position of the LOC. In step 1110, by associating the position of the transducers 702_n that indicate a detection of a multifeed to the article, the LOC may be determined. Additionally, the array of transducers 700 may generate signaling at different timing for detecting a multifeed or condition. In the event of a multifeed in which the overlapped regions are not parallel and perpendicular to each other (a condition known as skew), each transducer in the area of the overlap condition will generate signaling indicating detection of a multifeed or condition at a different time. This represents an angle aspect of the multifeed. Knowing the speed of the paper, the position of the transducer and the timing of the signal allows for determining the skew angle of the overlap which allows for an accurate calculation of the overlap condition.

For example, referring to FIG. 7, consider transducers 7022 and 7023 generate signaling indicating detection of a multifeed or condition. Conversely, transducers 7021 and 7024-702_n generate signaling that indicates absence of a multifeed or condition. Now adverting to FIGS. 5A to 5C, consider transducers 7022 and 7023 positioned relative to the lateral overlap LOC illustrated. By processing only the signaling received to indicate detection of a multifeed or condition, and associating the position transducers 7022 and 7023 relative to the overall article 50, LOC can be determined.

Although the subject matter has been described and illustrated in detail, it is to be clearly understood that the same is by way of illustration and example only and is not to be taken by way of limitation, the scope of the present invention being limited only by the terms of the appended claims.

The invention has been described in detail with particular reference to certain preferred embodiments thereof, but it will be understood that variations and modifications can be effected within the spirit and scope of the invention.

The invention claimed is:

1. A document handling apparatus comprising:

a transport path;

a feeder device adapted to separate a first flat article from a plurality of stacked flat articles;

a user interface for predefining a region of the first flat article before the feeder device feeds the first flat article;

one or more ultrasonic devices positioned in the transport path to determine that a multifeed condition exists indicating that a second flat article is overlapping the first flat article in the predefined region of the first flat article; and

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a controller adapted to receive and process signaling from the one or more ultrasonic devices, the controller configured to determine whether or not the second flat article is contained within the predefined region of the first flat article.

2. The apparatus according to claim 1, wherein the one or more ultrasonic devices determines an existence of an air gap between the first flat article and the second flat article.

3. The apparatus according to claim 1 further comprising a scanner for scanning the first flat article and the second flat article.

4. The apparatus according to claim 3 further comprising a printer for printing an image obtained from scanning the first flat article and the second flat article.

5. The apparatus according to claim 1 wherein the predefined region of the first flat article comprises a portion of the first flat article.

6. A method comprising the steps of:

receiving a first flat article from a feeder device adapted to separate the first flat article from a plurality of stacked flat articles, the first flat article including at least four side edges defining boundaries of the first flat article; predefining at least one region within the boundaries of the first flat article;

determining that a second flat article is present within the boundaries of the first flat article and outside the predefined region using one or more ultrasonic devices, wherein the second flat article is smaller in size than the first flat article; and

responsive to the presence of the second flat article, disallowing further processing of the first and second flat articles based upon the step of determining.

7. The method of claim 6, further comprising the steps of: detecting a leading side edge of the second flat article that traverses a direction of first flat article transport; and detecting a trailing side edge of the second flat article that traverses the direction of first flat article transport

8. The method according to claim 6, wherein the second flat article is attached or detachably removable from a surface of the first flat article.

9. The method according to claim 6, wherein the second flat article is selected from the group consisting of a self stick removable note, a photograph, or a sticker.

10. The method according to claim 6, wherein the one or more ultrasonic devices detects an air gap between the first flat article and the second flat article.

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