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Sekine et al.

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(54) **MASK DEFECT INSPECTION APPARATUS**

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Mar. 18, 2005, now Pat. No. 7,379,176.

(30) **Foreign Application Priority Data**
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G01N 21/00 (2006.01)

(52) **U.S. Cl.** **356/237.5; 356/237.1; 356/237.2;**
356/237.4

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250/559.34, 559.36–559.39, 559.4, 559.45,
250/306; 382/149, 255, 141, 218, 144, 148,
382/199, 256–275, 293
See application file for complete search history.

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(57) **ABSTRACT**

The mask defect inspection apparatus including an illumination optical system for illuminating a mask on which a pattern is formed; an objective lens facing the mask; at least a pair of detection optical systems having a detection sensor for obtaining an image of the pattern, respectively, and which receive illumination light from illumination areas different from each other through the objective lens, respectively; and focusing changing means for changing a position of focusing between sites of the pattern in a film-thickness direction of the mask and the pattern images obtained by the detection sensors, such that the pattern images obtained by the detection sensors are changed corresponding to the film-thickness direction of the mask.

17 Claims, 11 Drawing Sheets

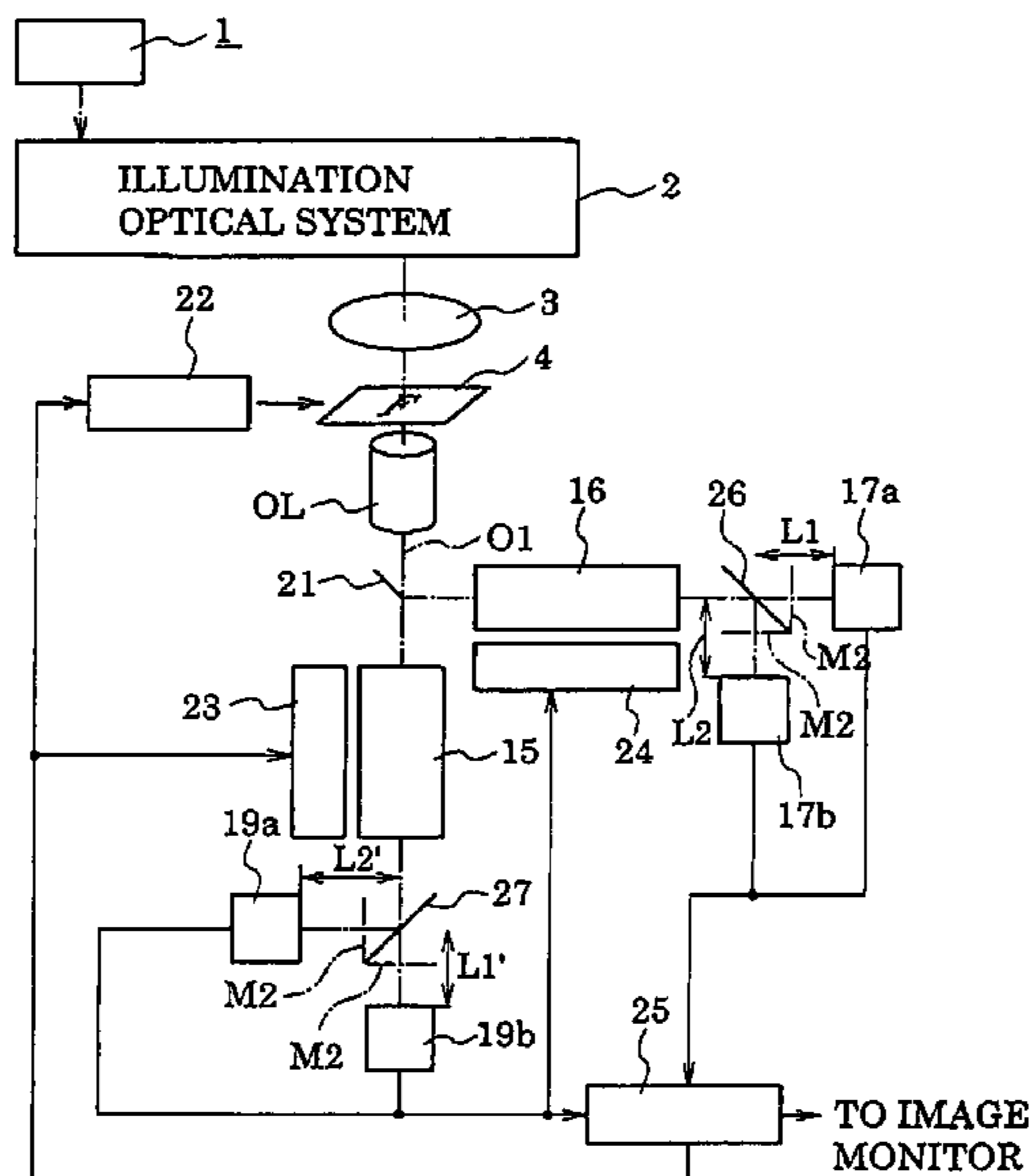


FIG. 1

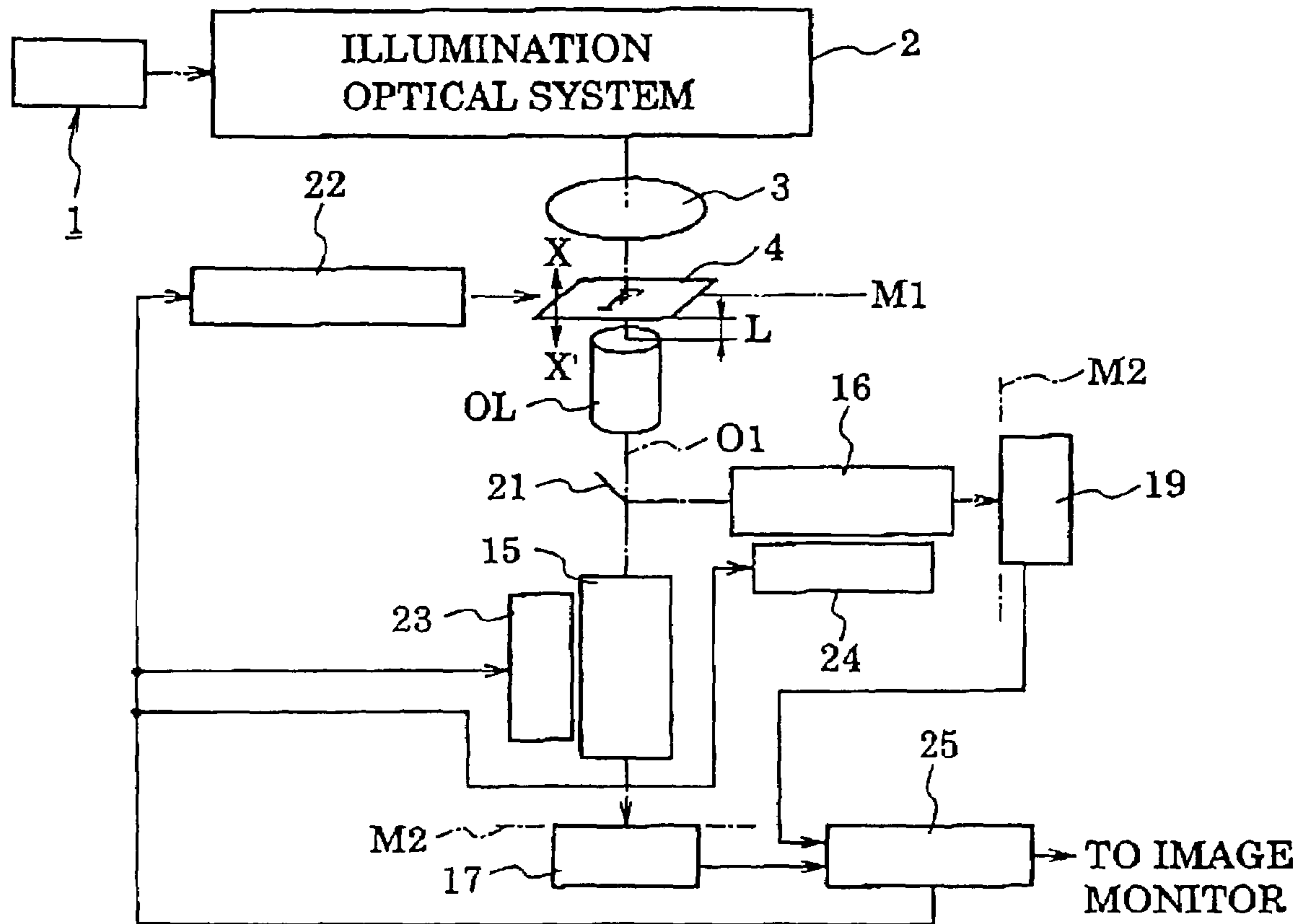


FIG. 2

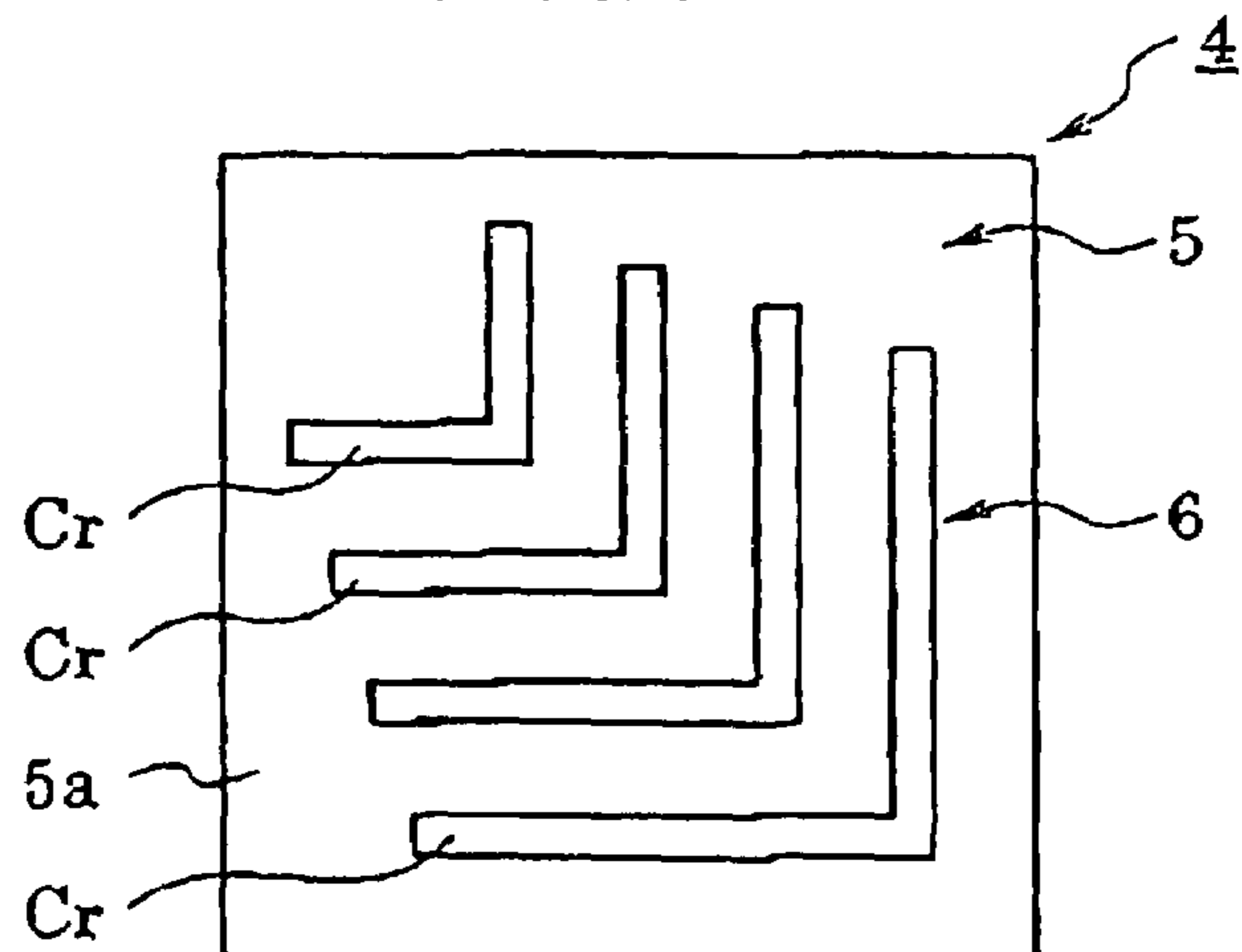


FIG.3A

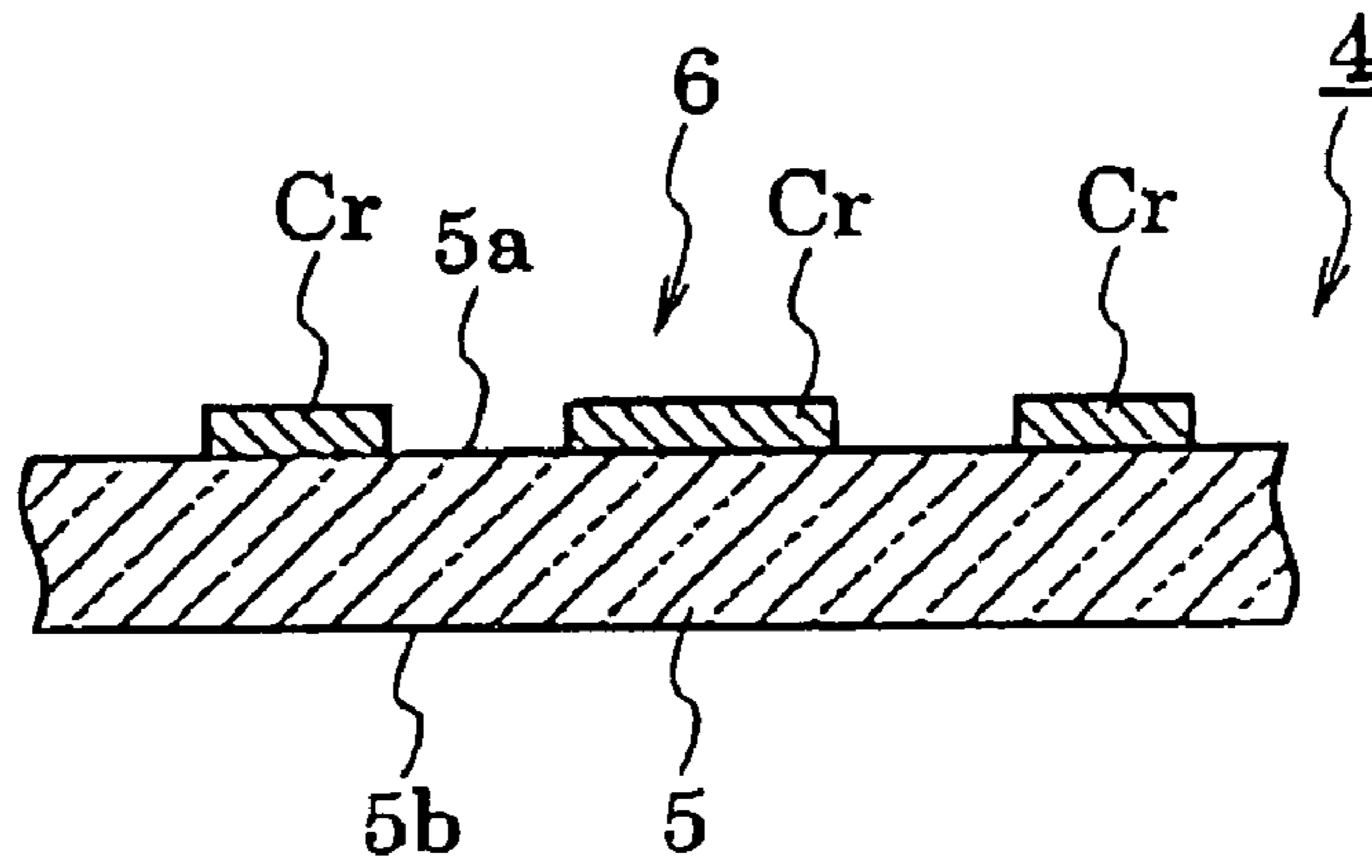


FIG.3B

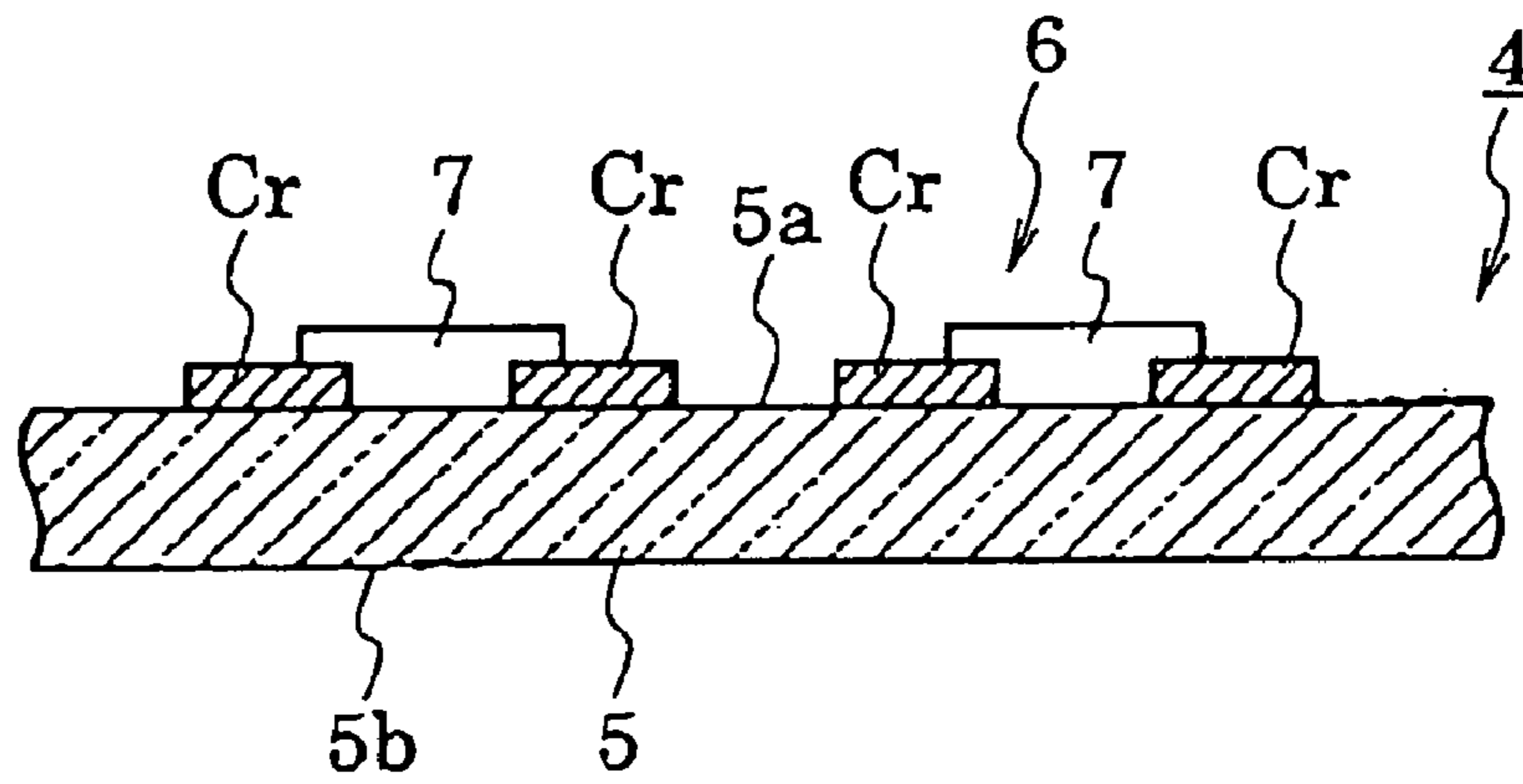


FIG.3C

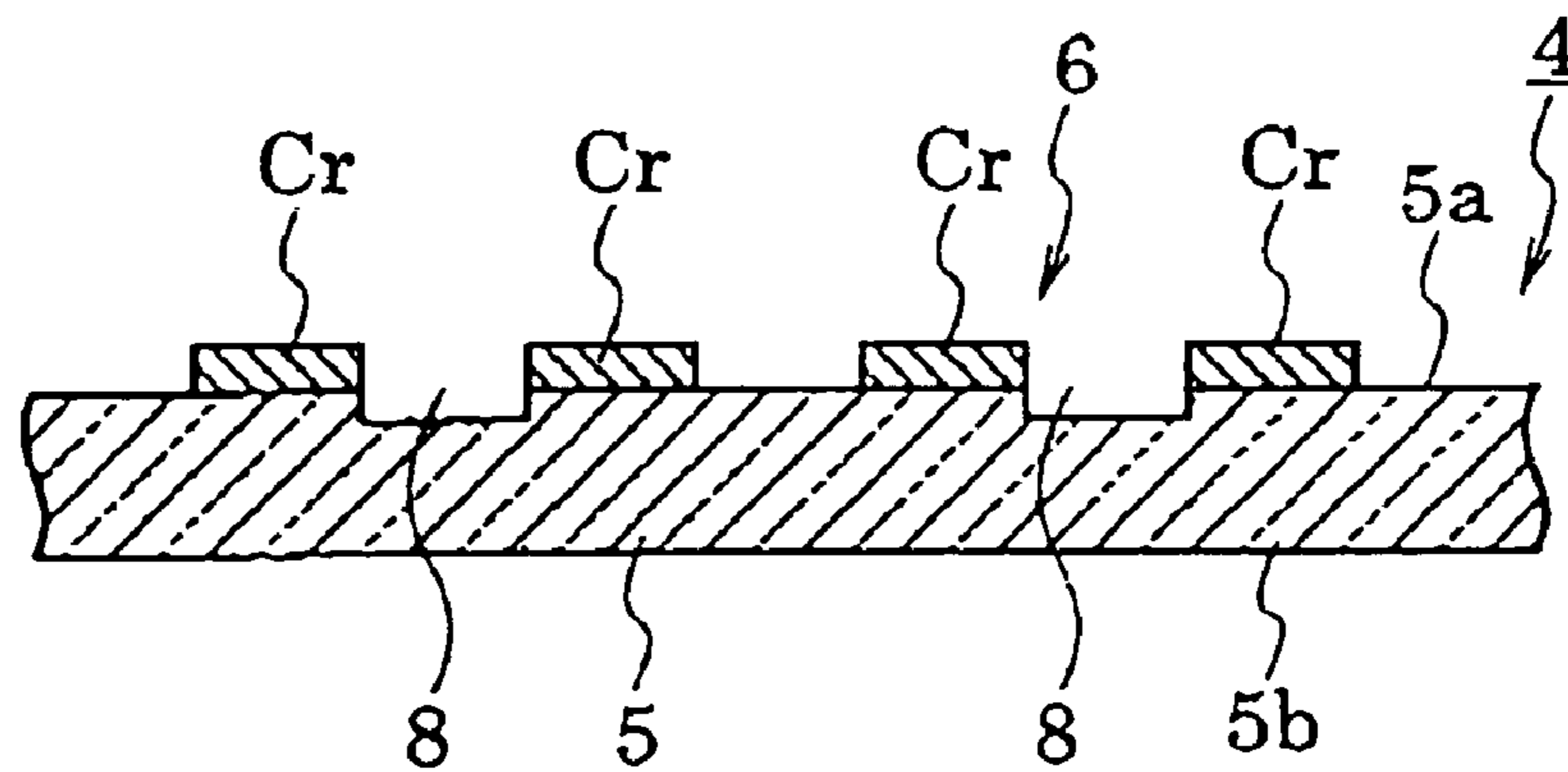


FIG. 4A

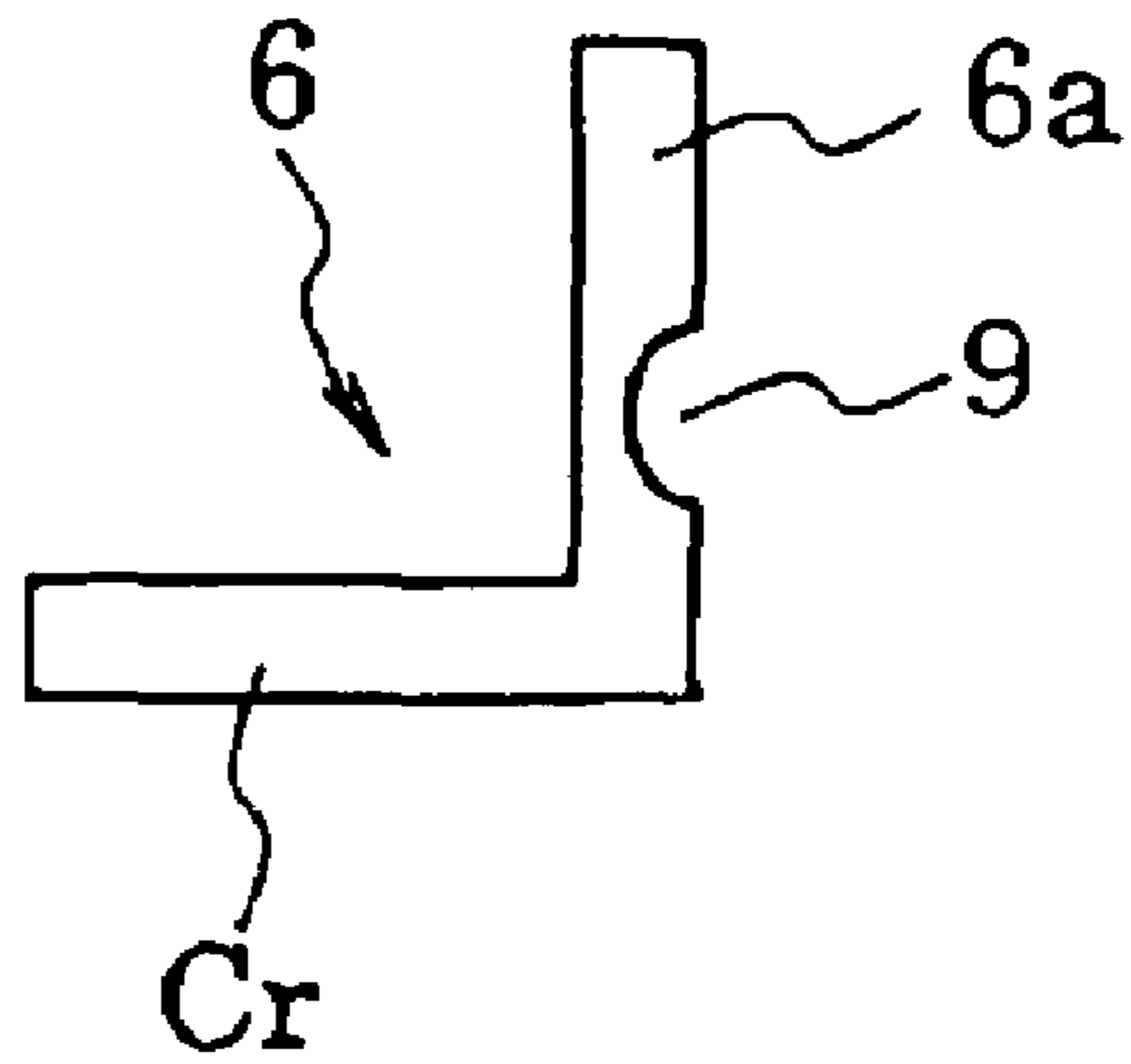


FIG. 4B

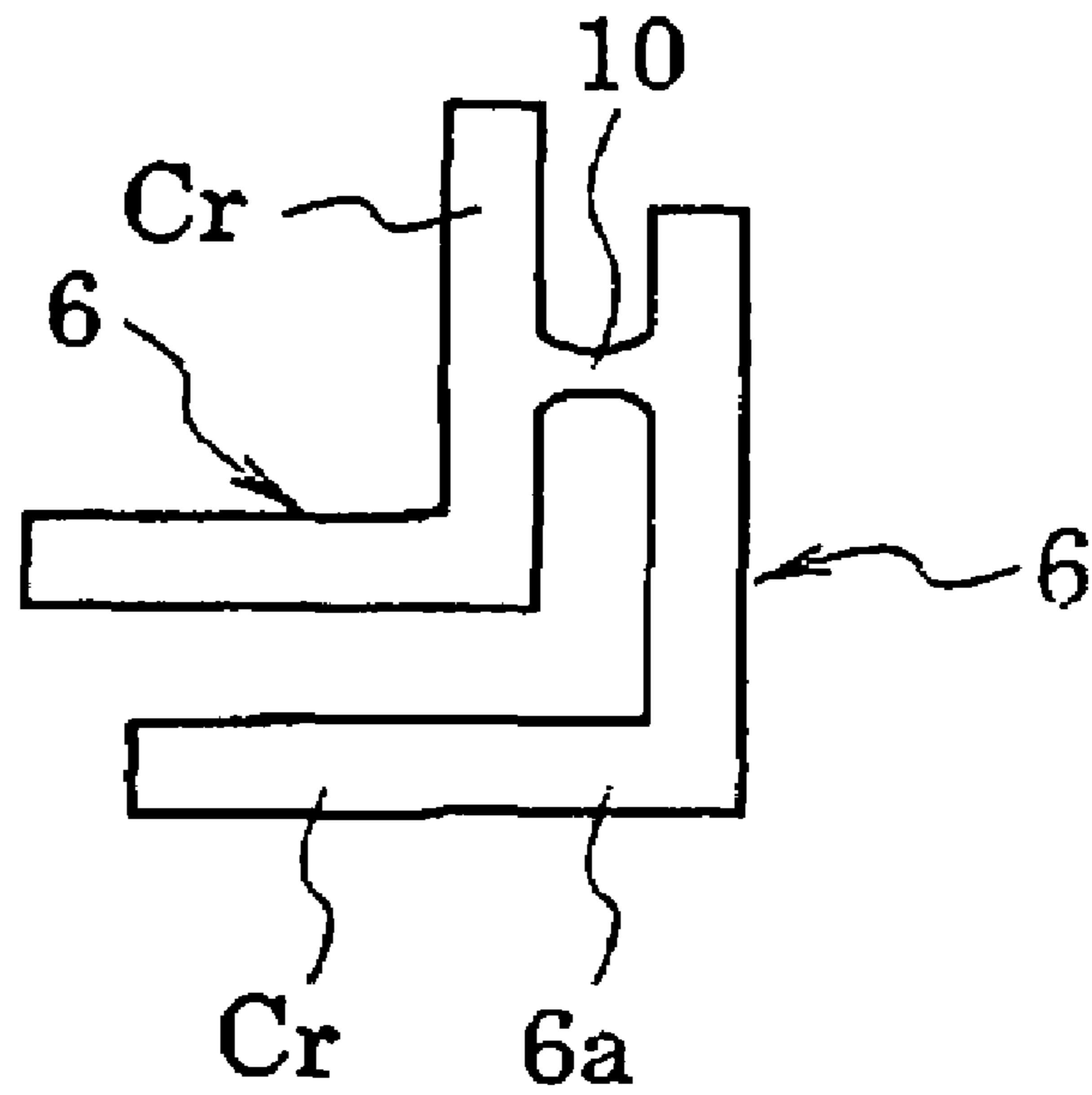


FIG. 4C

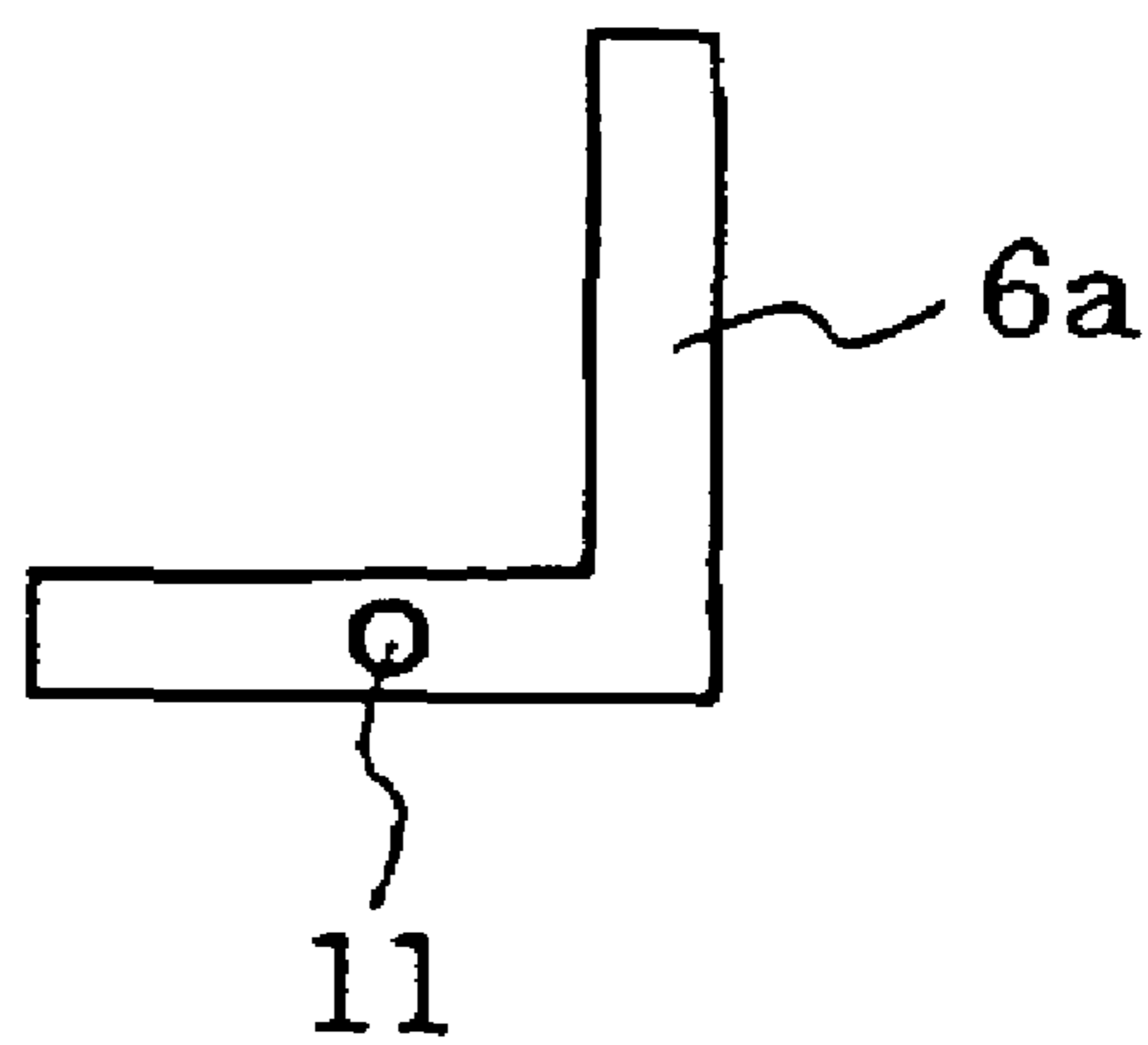


FIG.5A

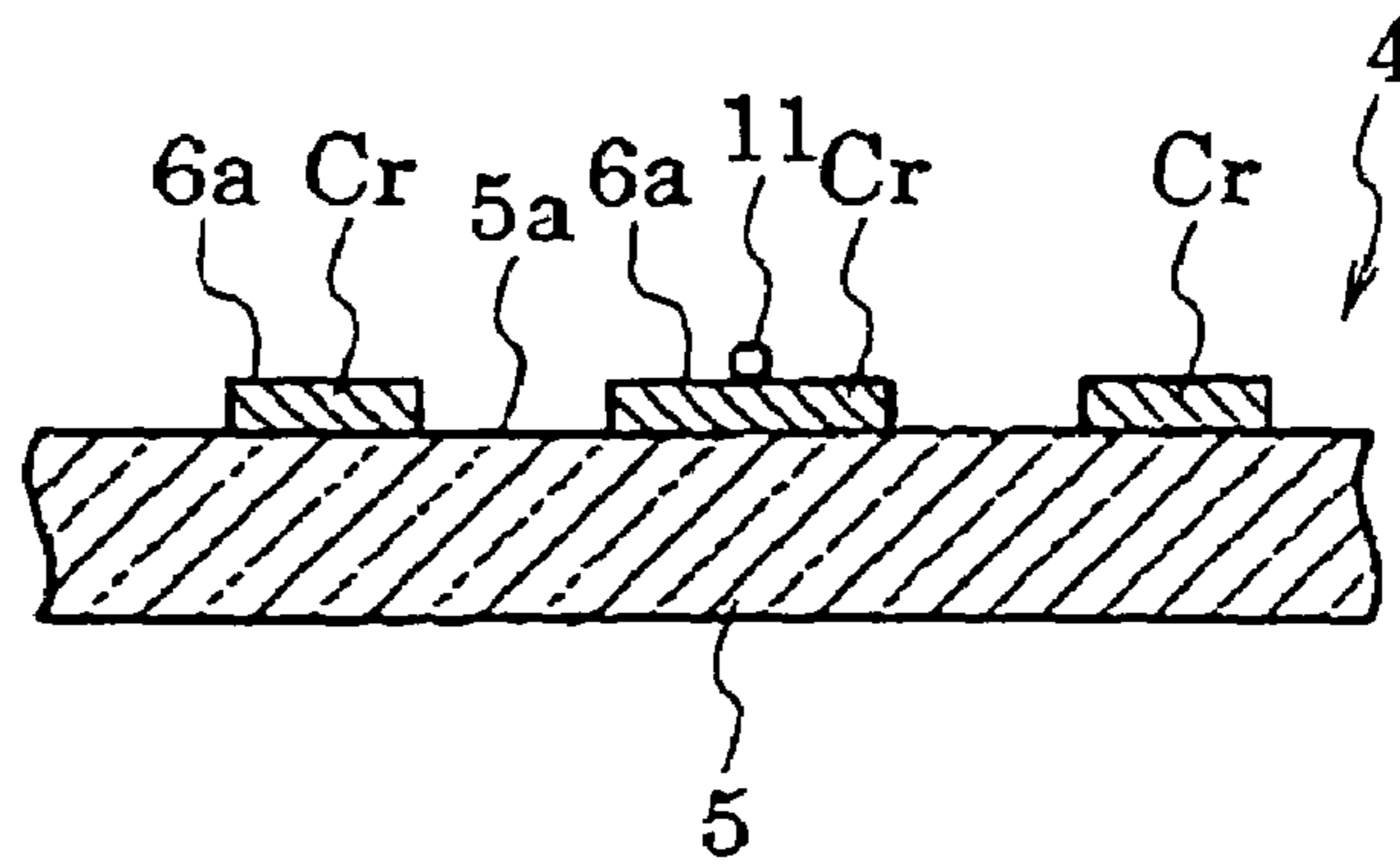


FIG.5B

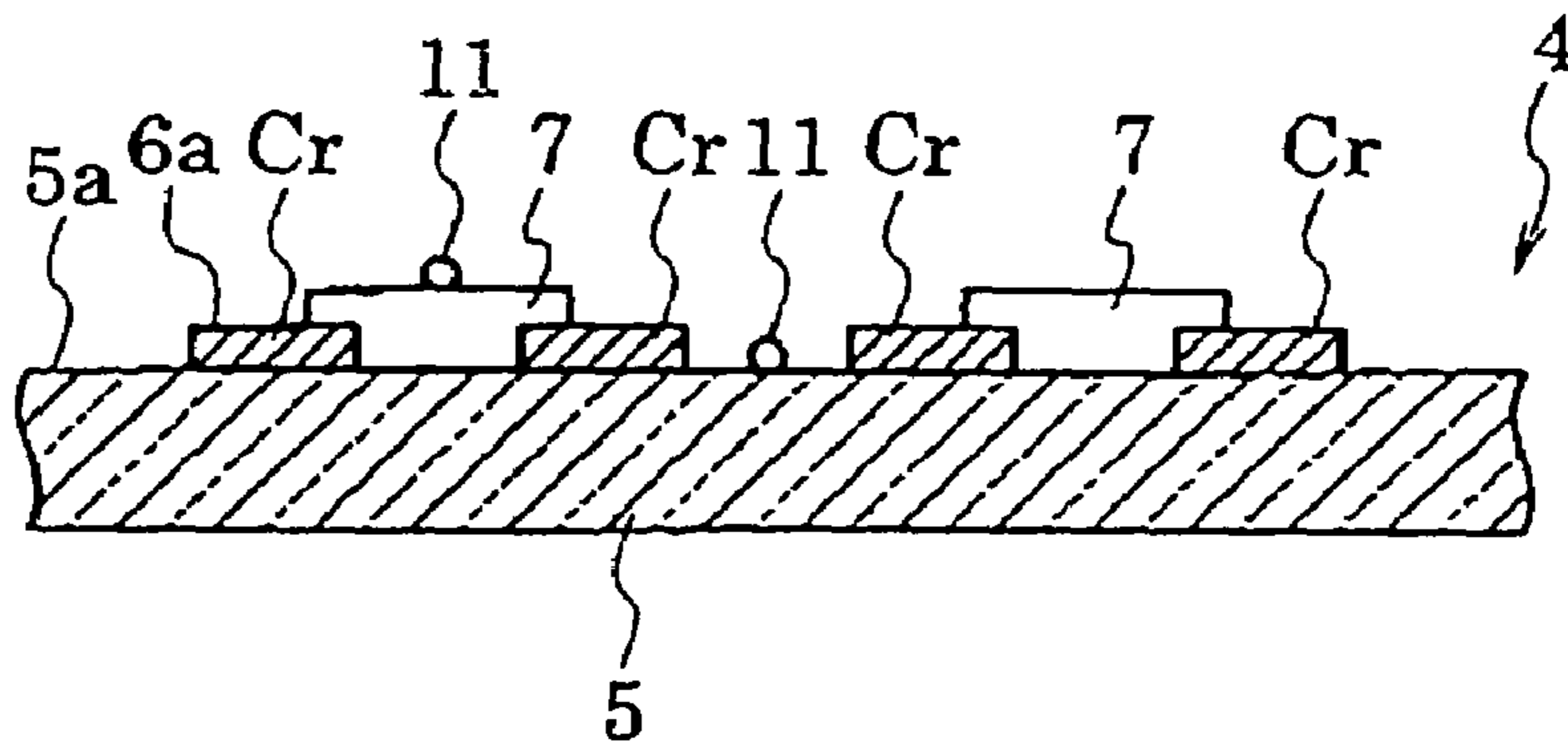


FIG.5C

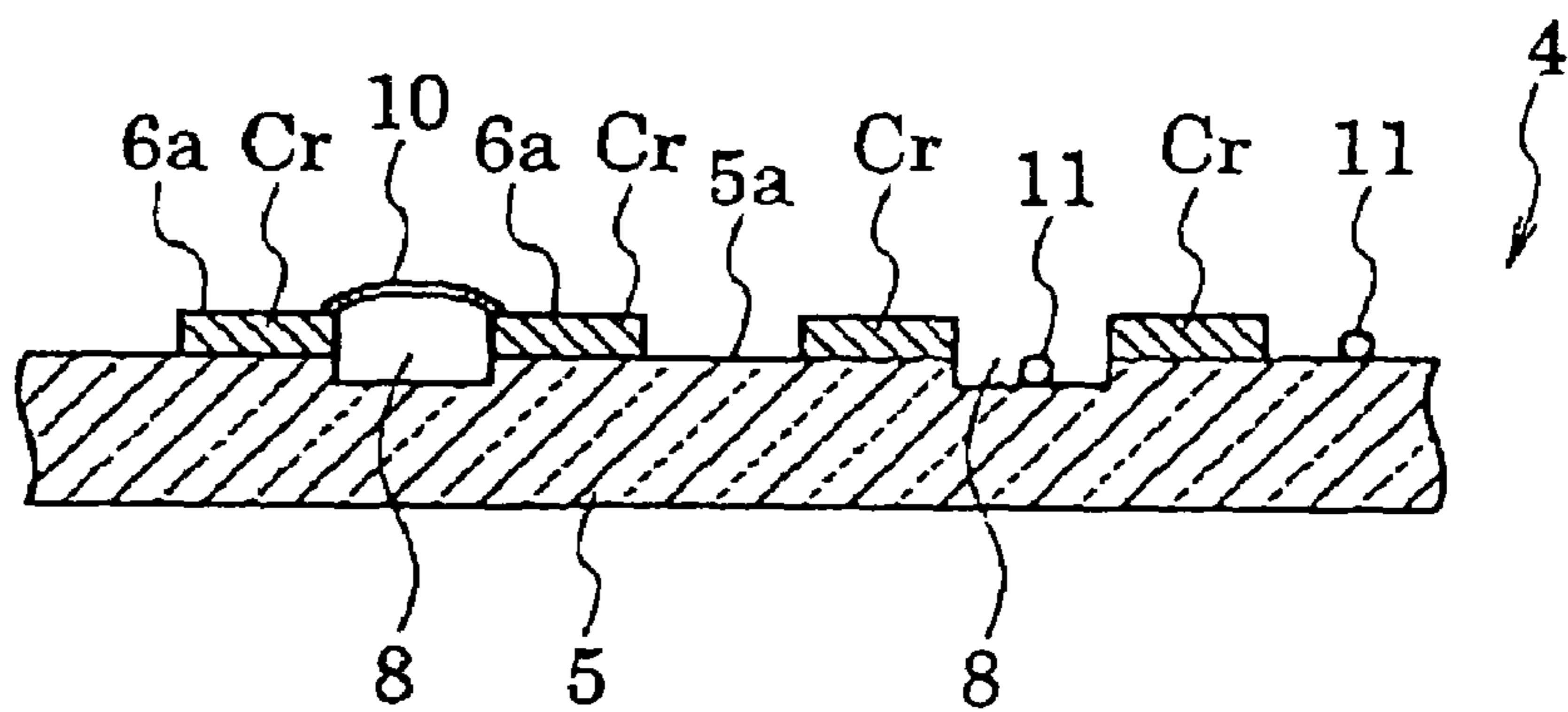


FIG. 6

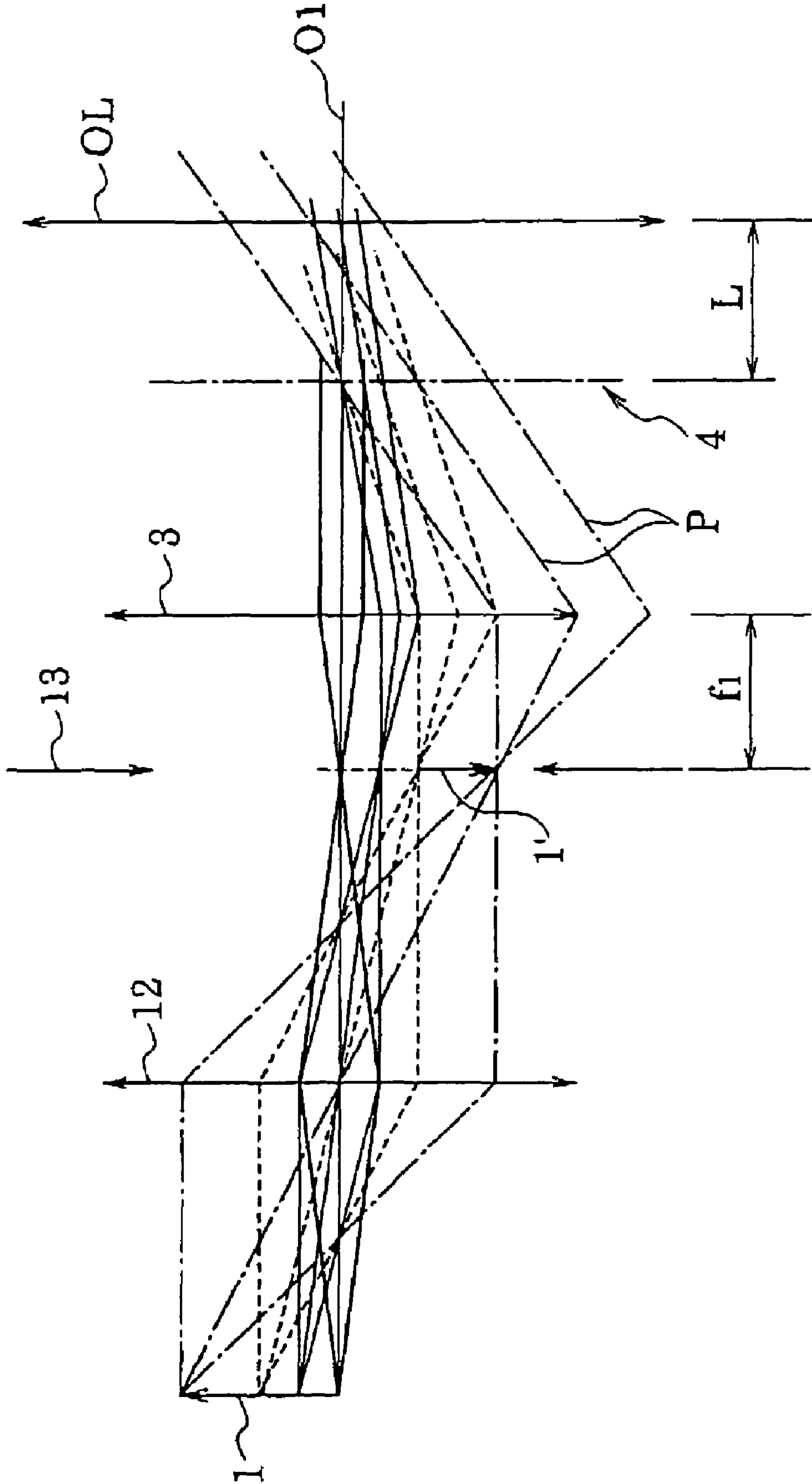


FIG. 7

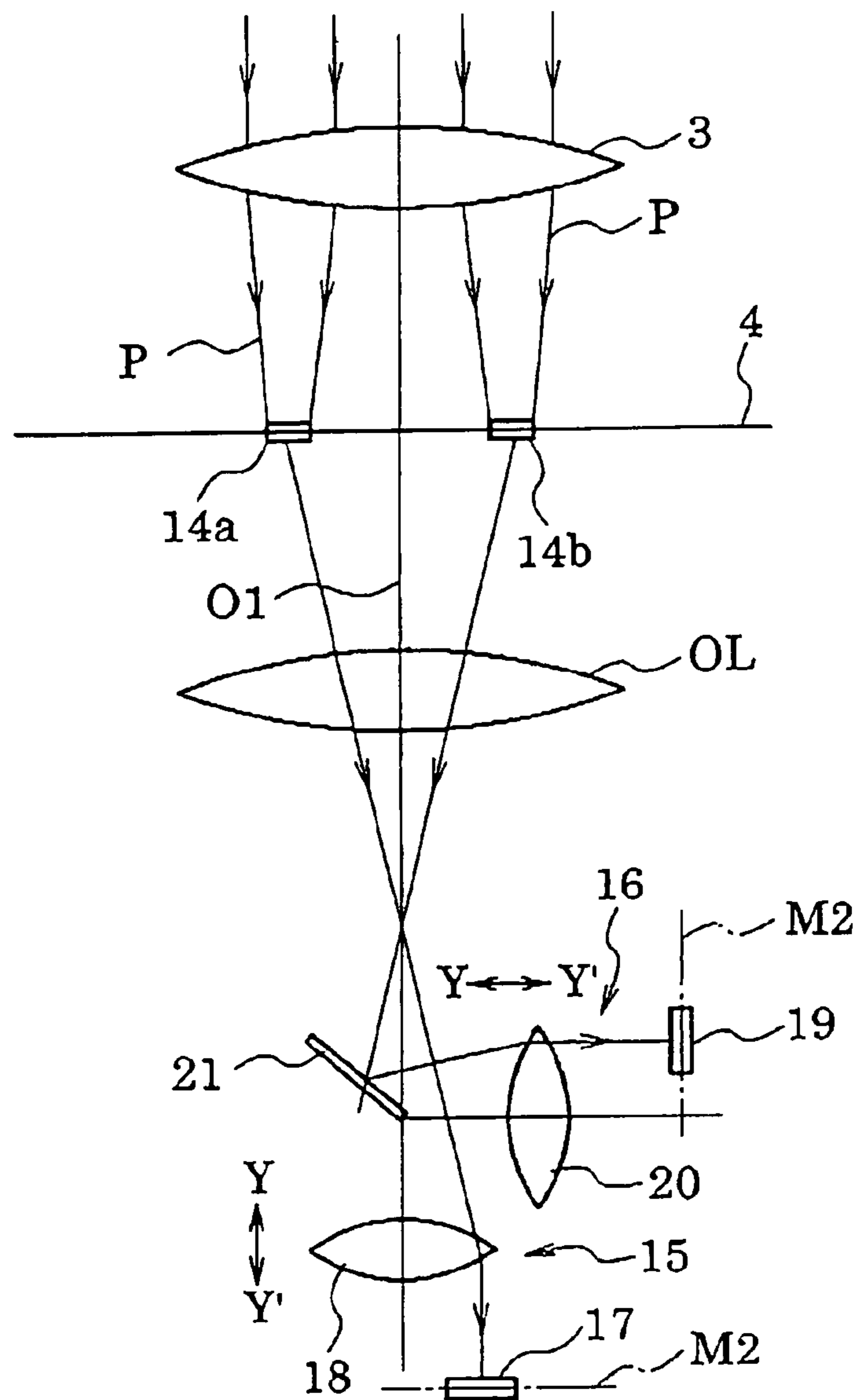


FIG. 8

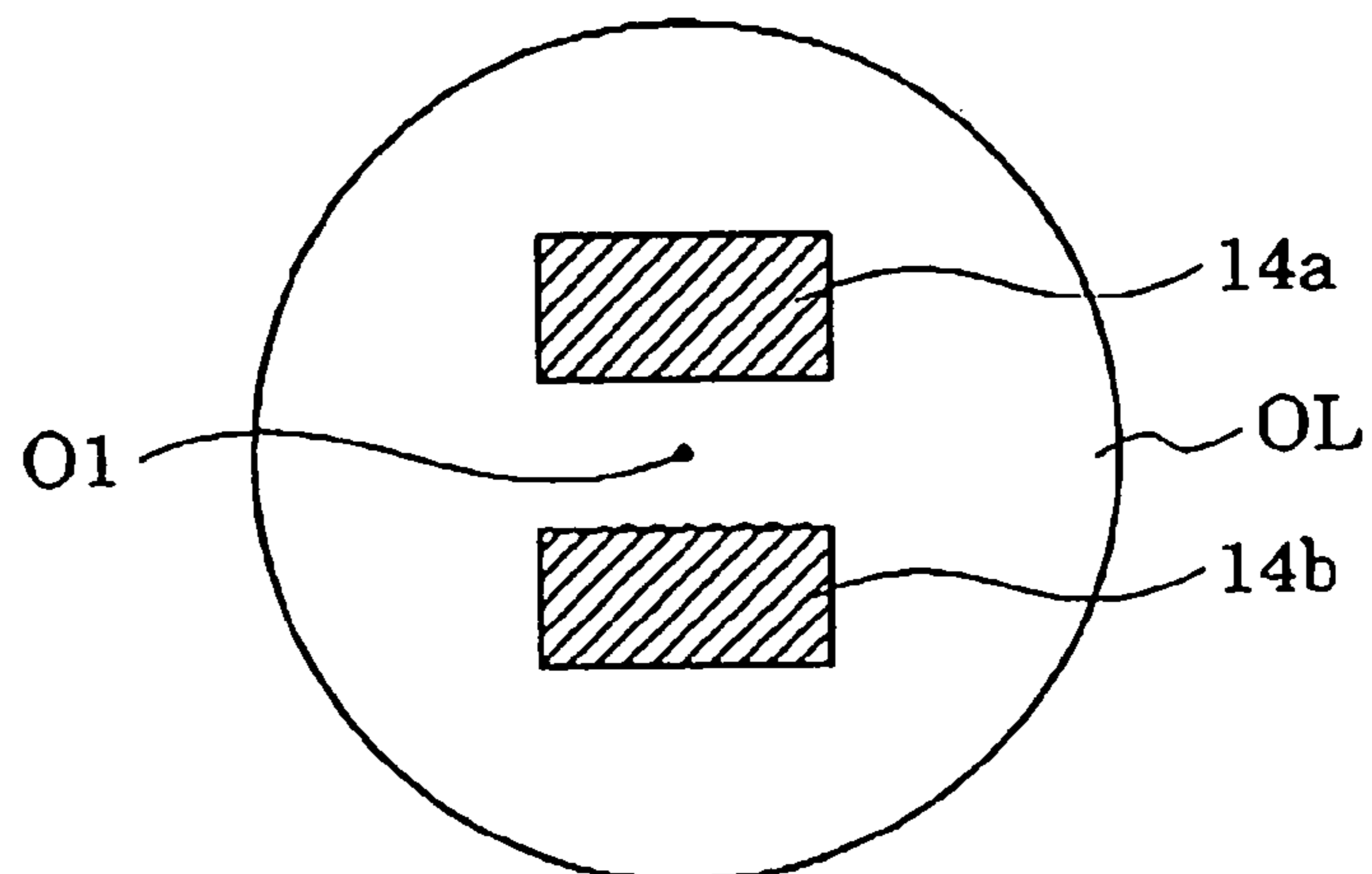


FIG. 9

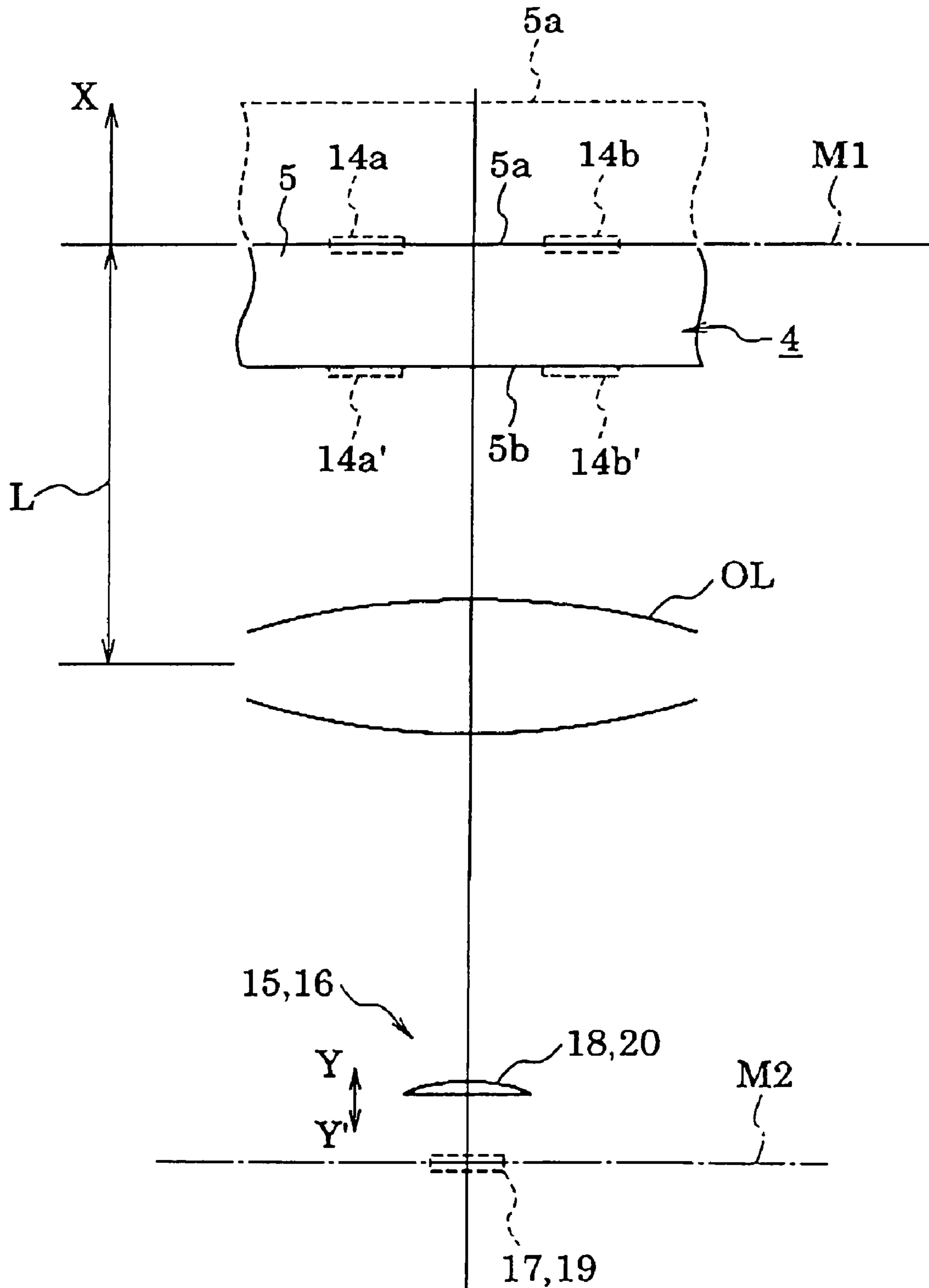


FIG.10

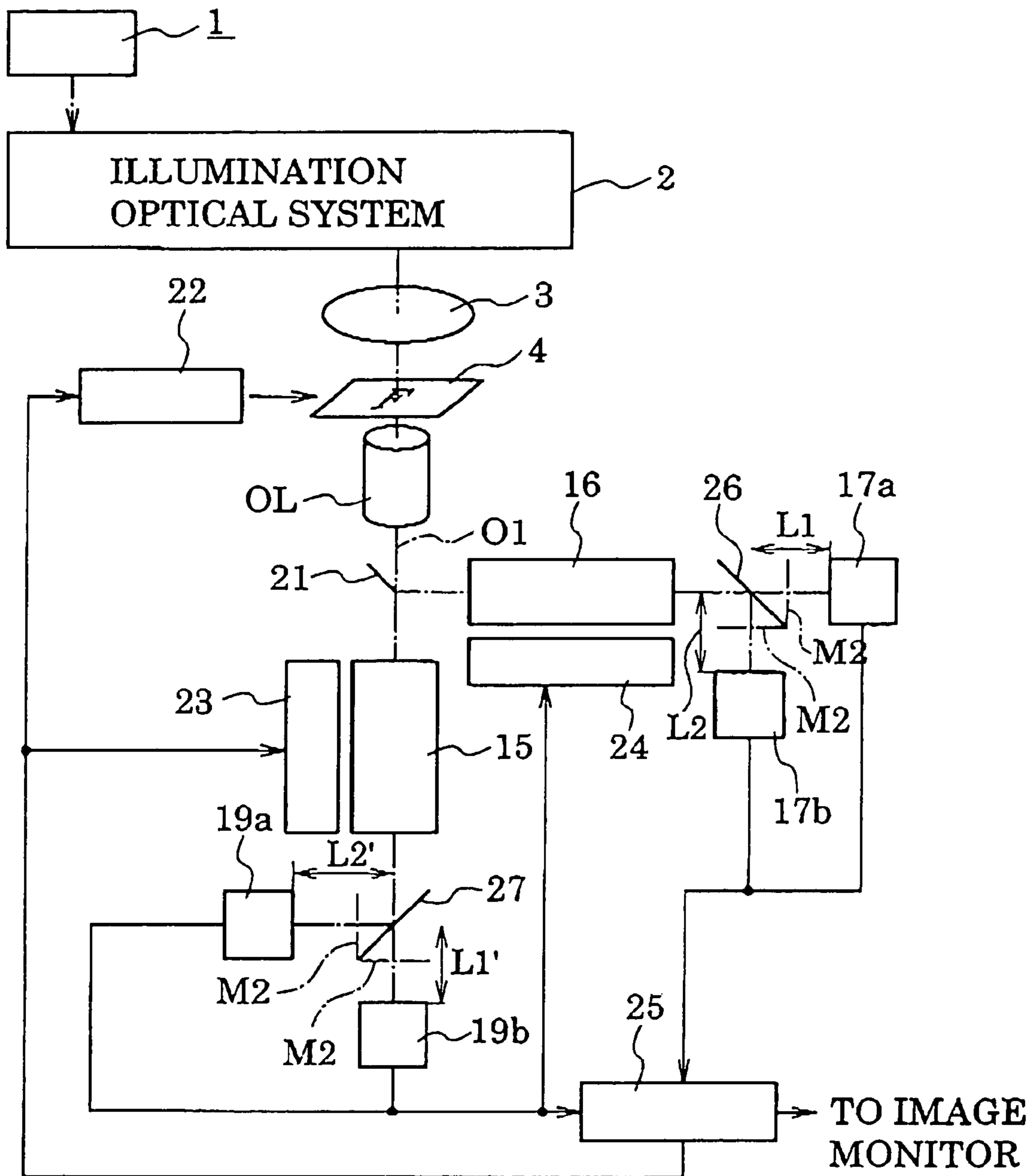


FIG. 11

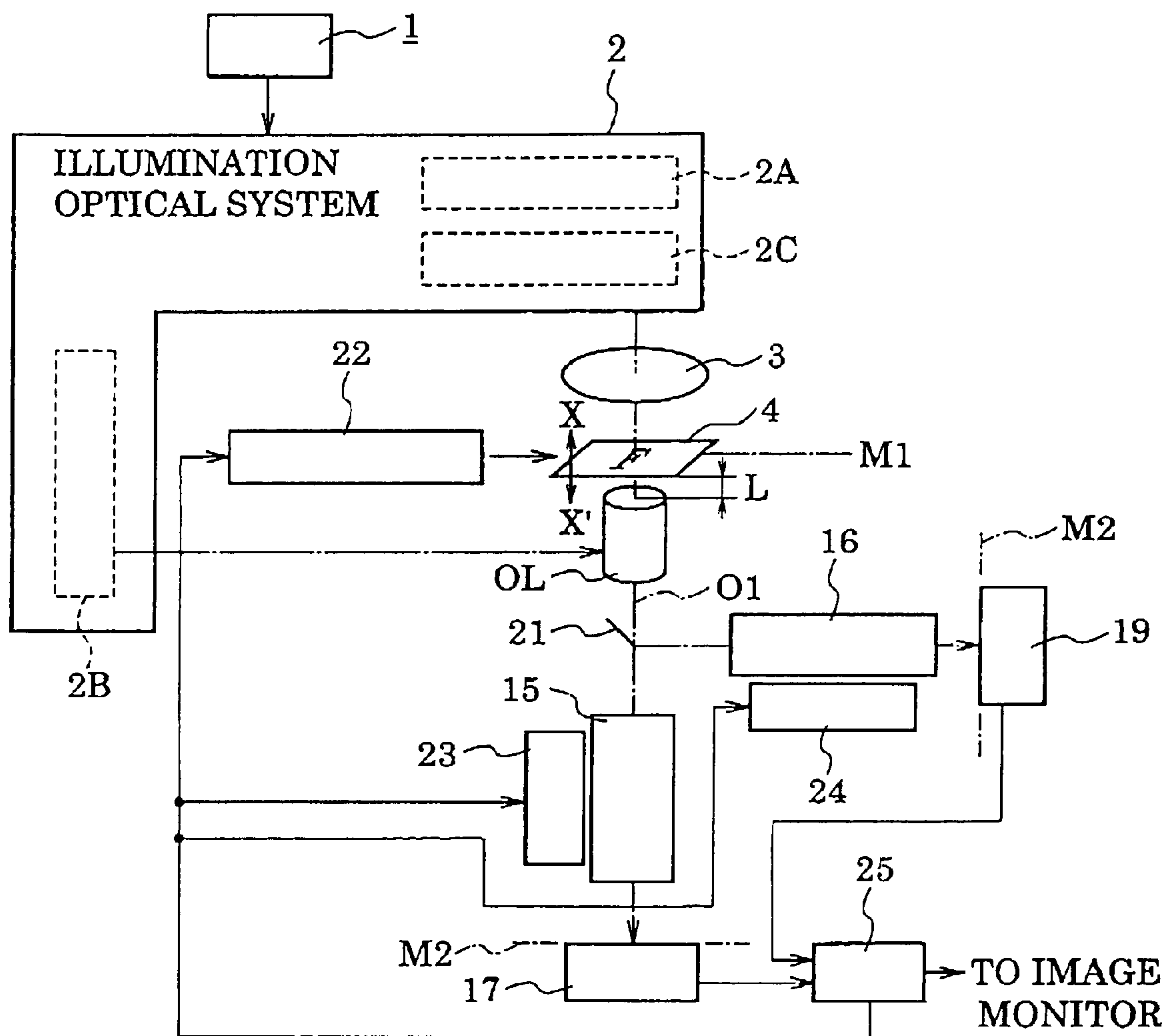


FIG. 12

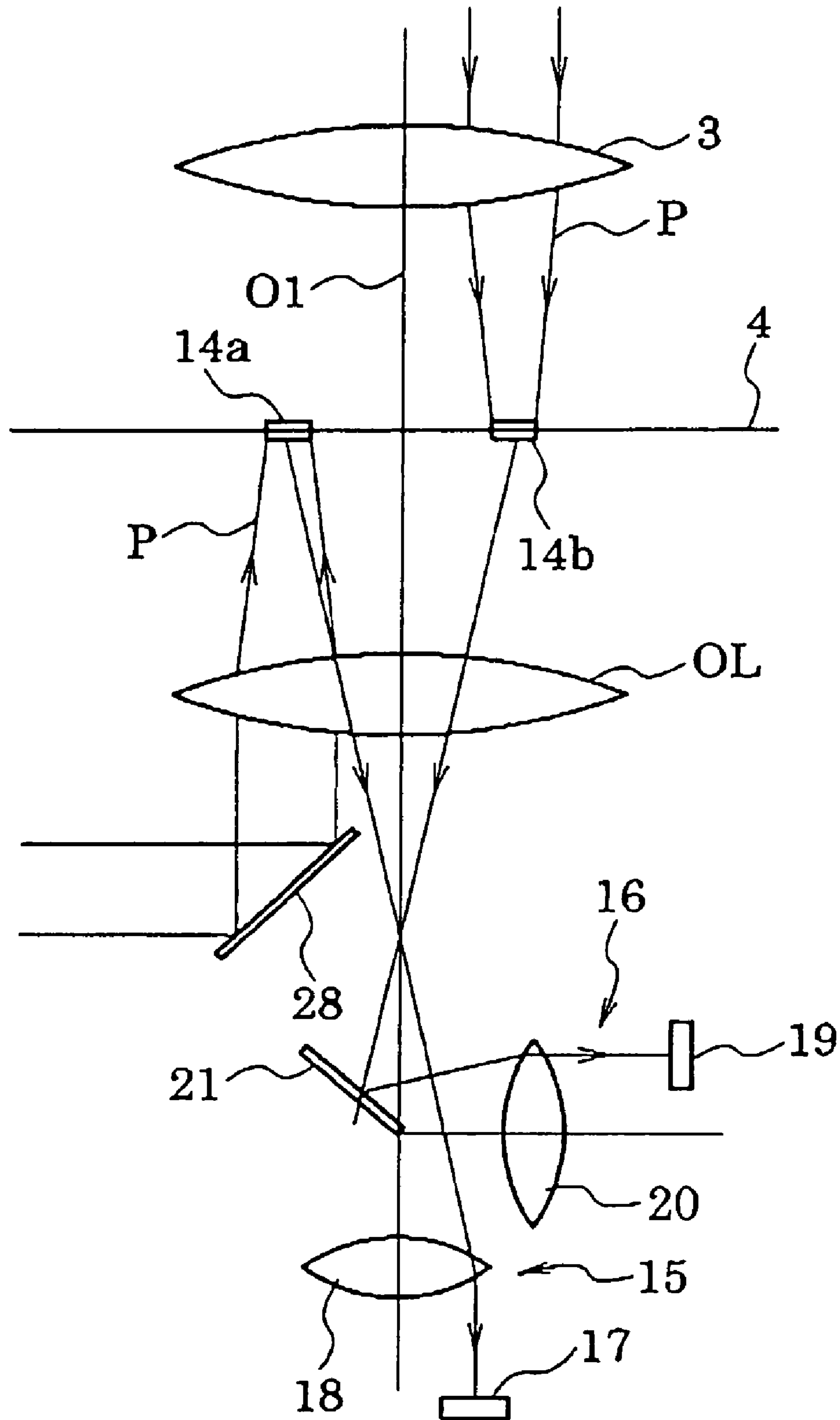
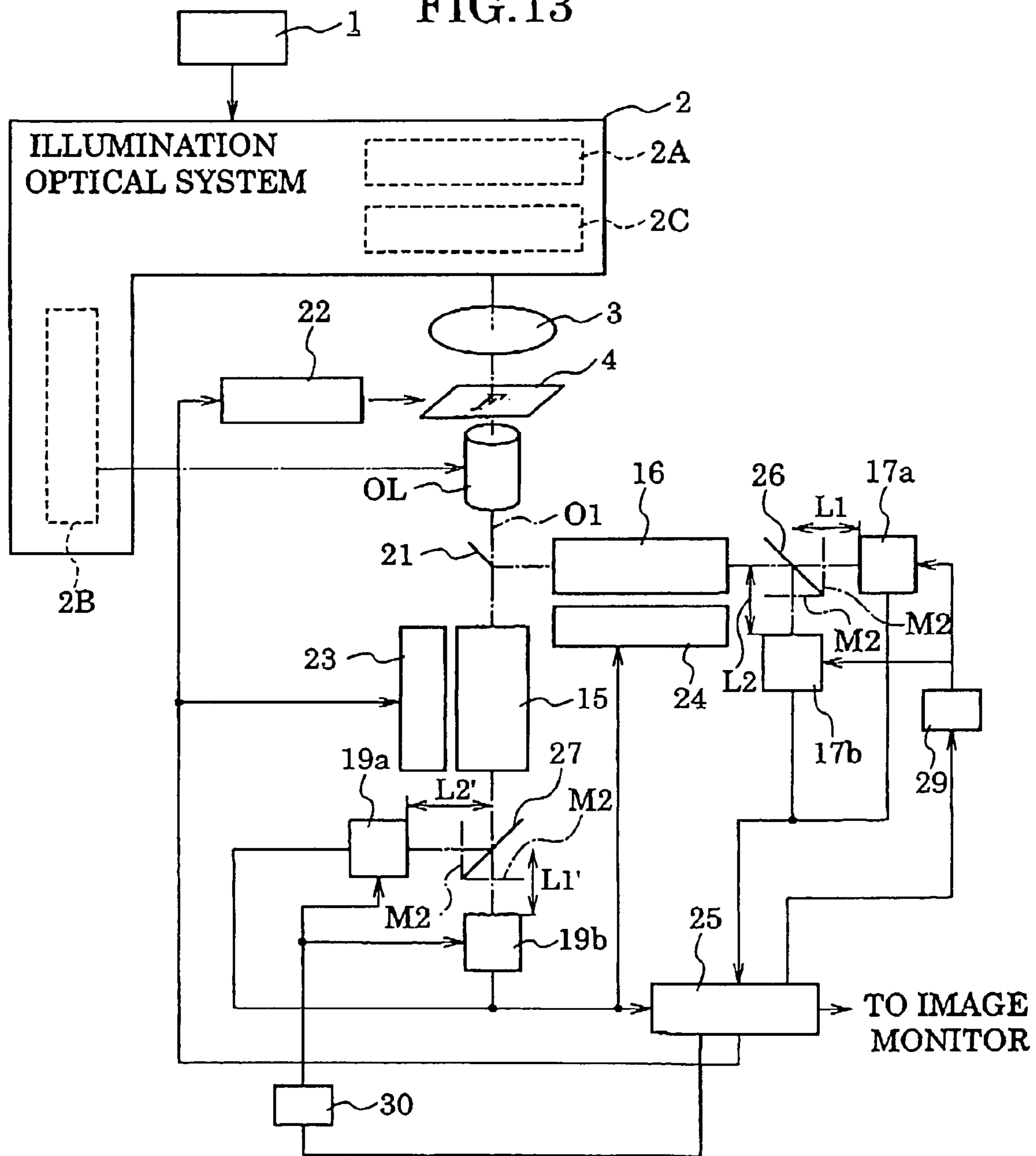


FIG. 13



MASK DEFECT INSPECTION APPARATUS**BACKGROUND OF THE INVENTION****1. Field of the Invention**

The present invention relates to an improvement in a mask defect inspection apparatus for inspecting a defect in a mask having a pattern (for example, break, thinning or attachment of foreign substance) formed on or in a sample of a photo-mask or a glass wafer used for fabrication of semiconductors.

2. Description of the Related Art

Heretofore, in a mask defect inspection apparatus for inspecting a defect in a pattern formed on a photomask used for fabrication of semiconductors, there has been known an apparatus in which a chip having a pattern drawn is observed using one detection optical system and an observed image is then compared with a standard image which corresponds to design data to inspect the defect in the mask.

In addition, as the conventional mask defect inspection apparatus of this kind, there has been also known an apparatus in which a reflection-illumination optical system and a transmission-illumination optical system are provided as a detection optical system so that an inspection of defect in the mask may be made with higher sensitivity (for reference, see JP-A 10-97053).

With a development in miniaturization of semiconductor devices, a wavelength of illumination light used for exposure and inspection is increasingly shortened, and deep-ultraviolet rays (DUV) are being used as the illumination light in the mask defect inspection apparatus in the recent years.

On the other hand, since the detection optical system used for the mask defect inspection apparatus has performance equivalent to that of a high-resolution microscope and uses an objective lens of high numerical aperture (high NA), such a detection optical system has high resolving power but shallow depth of focus. As a result, the detection optical system has properties that the depth of focus becomes shallower as the wavelength of illumination light becomes shorter.

Accordingly, the conventional apparatus of this type performs the inspection by finely tuning a focal plane of the detection optical system as well as by switching over an inspection carried out with transmission-illumination light and an inspection carried out with reflection-illumination light, so that it may be identified whether an detected defect is mainly due to the residue of the film-forming material or attachment of the foreign substance onto the mask.

However, while the conventional mask defect inspection apparatus of this type is on a trend that the shortening of wavelength is called for and the depth of focus becomes shallower, there is a tendency that a size in film thickness of the pattern of the mask as an object to be inspected is becoming thicker. Moreover, in addition to a demand for strict accuracy in finely tuning the focal plane for both the inspection using the transmission-illumination and the inspection using the reflection-illumination, there has also been a demand for enlarging a range of tuning of the focal plane. Therefore, the conventional mask inspection apparatus is posing troubles in terms of a prompt inspection and identification of the defect in the mask.

SUMMARY OF THE INVENTION

Therefore, the present invention has been made in view of the above circumstances, and at least one objective of the present invention is to provide a mask defect inspection apparatus capable of carrying out an inspection of defect in a mask simultaneously and easily identifying type of the defect

although the wavelength of illumination light becomes shorter and the film-thickness of a pattern of the mask becomes greater.

To achieve these and other advantages and in accordance with the purpose of the invention, as embodied and broadly described herein, the invention provides a mask defect inspection apparatus. The mask defect inspection apparatus comprises an illumination optical system for illuminating a mask on which a pattern is formed; an objective lens facing the mask; at least a pair of detection optical systems each having a detection sensor for obtaining an image of the pattern of the mask, and adapted to receive illumination lights from illumination areas different from each other through the objective lens, respectively; and a focusing changing device for changing a position of focusing between sites of the pattern in a film-thickness direction of the mask and the pattern images obtained by each of the detection sensors, such that pattern images obtained by each of the detection sensors are changed corresponding to the film-thickness direction of the mask.

According to the present invention, since the different areas of the mask formed with the pattern are illuminated and the illumination lights from the different areas are received by the respective detection optical systems so that the pattern images may be obtained simultaneously corresponding to the different areas illuminated, it is possible to simultaneously carry out the inspection of defect for the different areas. In addition, since the focusing position between the pattern sites in the film-thickness direction of the mask and the pattern images obtained by each of the detection sensors is changed such that the pattern images obtained by the detection sensors change corresponding to the film-thickness direction of the mask, it is possible to carry out the identification of the defect in the mask easily even when the mask is thick in the direction of film-thickness of the mask.

To achieve these and other advantages and in accordance with the purpose of the invention, as embodied and broadly described herein, the invention provides a mask defect inspection apparatus. The mask defect inspection apparatus comprises an illumination optical system configured to illuminate a plurality of illumination areas different from each other of a mask on which a pattern is formed; an objective lens facing the mask; at least two detection optical systems each configured to receive illumination light from a corresponding one of the illumination areas different from each other of the mask through the objective lens, and each having a detection sensor configured to obtain an image of the pattern in the corresponding one of the illumination areas of the mask based on the illumination light from the corresponding one of the illumination areas of the mask received by the corresponding one of the at least two detection optical systems; and a focusing changing device configured to change a position of focusing between sites of the pattern in a film-thickness direction of the mask and the pattern image obtained by each of the detection sensors, such that pattern obtained by each of the detection sensors are changed corresponding to the film-thickness direction of the mask.

(1) The focusing changing device decides the focusing position between the pattern sites in the film-thickness direction of the mask and the pattern images obtained by each of the detection sensors according to a cross-sectional structure of the pattern in the film-thickness direction.

According to the embodiment (1) of the present invention, since the focusing position between the pattern sites in the film-thickness direction of the mask and the pattern images obtained by the detection sensors is decided by the focusing changing device according to the cross-sectional structure of

the pattern in the film-thickness direction, it is possible to carry out the inspection of the defect promptly.

(2) One of the detection optical systems is a transmission-detection optical system for forming the pattern image of the illumination area illuminated by transmission-illumination light on the detection sensor, and the other of the detection optical systems is a reflection-detection optical system for forming the pattern image of the illumination area illuminated by reflection-illumination light on the detection sensor.

(3) The focusing changing device decides the focusing position between the pattern sites in the film-thickness direction of the mask and the pattern images obtained by each of the detection sensors based on inspection object information of whether to inspect a foreign substance attached on the mask or to inspect a residual substance of a film-forming material forming the pattern.

(4) The focusing changing device comprises a moving mechanism for moving either the mask or the objective lens in a direction of an optical axis of the objective lens.

(5) The focusing changing device comprises a moving mechanism for moving the detection sensor in a direction of an optical axis of the detection optical system while a distance between the mask and the objective lens is maintained constant.

(6) Each of the detection optical systems has a focusing lens, and the focusing changing device comprises a moving mechanism for moving the focusing lens in a direction of an optical axis of the focusing lens.

According to the embodiments (2) to (6) of the present invention, by using the transmission-detection optical system and the reflection-detection optical system appropriately, it is possible to carry out the easy and prompt identification of whether the foreign substance is attached on the mask or the film-forming material for forming the pattern remains on the mask.

(7) At least one of the detection optical systems is provided with a plurality of the detection sensors, and the plurality of detection sensors detect images of the pattern site which are different from each other in a direction of thickness of the mask.

According to the embodiment (7) of the present invention, it is possible to carry out the easy and prompt inspection of which pattern site in the thickness direction of the mask has the defect.

(8) The mask defect inspection apparatus further comprises a signal processor, wherein the signal processor controls the focusing changing device and compares the pattern images obtained by each of the detection sensors with standard images to inspect presence or absence of a defect in the mask.

(9) The mask defect inspection apparatus further comprises a monitor, wherein the signal processor outputs the pattern images obtained by each of the detection sensors to the monitor as image data so that the pattern images are observable on the monitor.

According to the embodiments (8) and (9) of the present invention, it is possible to carry out the inspection of the defect easily and promptly.

Another aspect of the present invention provides mask defect inspection apparatus. That is, this mask defect inspection apparatus comprises an illumination optical system for illuminating a mask on which a pattern is formed; an objective lens facing the mask, at least a pair of detection optical systems each having a detection sensor for obtaining an image of the pattern, and adapted to receive illumination lights from illumination areas different from each other through the objective lens, respectively; and a focus adjuster

for adjusting focusing between pattern sites of the mask in the film-thickness direction thereof and pattern images obtained by each of the detection sensors, the focus adjuster is adapted for enabling the detecting sensor to form the pattern images corresponding to the pattern sites of the mask in the film-thickness direction thereof, respectively, so that the obtained pattern images may change corresponding to changes in the pattern sites in the film-thickness direction.

Following are preferred embodiments (a) to (g) of the above mask defect inspection apparatus according to the present invention.

Any combinations thereof are considered to be preferred ones of the above mask defect inspection apparatus unless any contradictions occur.

Another aspect of the present invention provides mask defect inspection apparatus. That is, this mask defect inspection apparatus comprises an illumination optical system configured to illuminate a plurality of illumination areas different from each other of a mask on which a pattern is formed; an objective lens facing the mask; at least two detection optical systems each configured to receive illumination light from a corresponding one of the illumination areas different from each other of the mask through the objective lens, and each having a detection sensor configured to obtain an image of the pattern in the corresponding one of the illumination areas of the mask based on the illumination light from the corresponding one of the illumination areas of the mask received by the corresponding one of the at least two detection optical systems; and a focus adjuster configured to adjust focusing between pattern sites of the mask in the film-thickness direction thereof and the pattern image obtained by each of the detection sensors, the focus adjuster is adapted for enabling each of the detecting sensors to form the pattern image corresponding to the pattern site in the corresponding one of the illumination areas of the mask in the film-thickness direction thereof, so that the obtained pattern images are changed corresponding to changes in the pattern sites in the film-thickness direction.

(b) One of the detection optical systems is a transmission-detection optical system for forming the pattern image of the illumination area illuminated by transmission-illumination light on the detection sensor, and the other of the detection optical systems is a reflection-detection optical system for forming the pattern image of the illumination area illuminated by reflection-illumination light on the detection sensor.

(c) The focus adjuster adjusts the focusing between the pattern sites in the film-thickness direction of the mask and the pattern images obtained by each of the detection sensors based on inspection object information of whether to inspect a foreign substance attached on the mask or to inspect a residual substance of a film-forming material forming the pattern.

(d) The focus adjuster comprises a moving mechanism for moving either the mask or the objective lens in a direction of an optical axis of the objective lens.

(e) The focus adjuster comprises a moving mechanism for moving the detection sensor in a direction of an optical axis of the detection optical system while a distance between the mask and the objective lens is maintained constant.

(f) Each of the detection optical systems has a focusing lens, and the focus adjuster comprises a moving mechanism for moving the focusing lens in a direction of an optical axis of the focusing lens.

(g) At least one of the detection optical systems is provided with a plurality of the detection sensors, and the plurality of

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detection sensors detect images of the pattern site which are different from each other in a direction of thickness of the mask.

It is to be understood that both the foregoing general description and the following detailed description are exemplary, and are intended to provide further explanation of the invention as claimed.

This application claims priority of Japanese Patent Application No. 2004-81767, filed on Mar. 22, 2004, the entirety of which is incorporated by reference herein.

BRIEF DESCRIPTION OF THE DRAWINGS

The accompanying drawings are included to provide a further understanding of the invention, and are incorporated in and constitute a part of this specification. The drawings illustrate embodiments of the invention and, together with the description, serve to explain the principles of the invention.

FIG. 1 is a diagram schematically showing an optical system according to a first embodiment of a mask defect inspection apparatus of the present invention.

FIG. 2 is a diagram schematically showing one example of a pattern formed on a mask.

FIGS. 3A to 3C are diagrams to explain types of masks, wherein FIG. 3A shows a state that a predetermined pattern is formed on a surface of a quartz glass with a film-forming material, FIG. 3B shows a state that a pattern is formed on the surface of the quartz glass with the film-forming material and a phase shifter, and FIG. 3C shows a state that a pattern is formed by providing the film-forming material on the surface of the quartz glass and engraving grooves on the surface.

FIGS. 4A to 4C show examples of defects cause on the mask, wherein FIG. 4A shows thinning of the pattern, FIG. 4B shows that the film-forming material remains between the film-forming material and the film-forming material, and FIG. 4C shows a state that a foreign substance is attached on a surface of the film-forming material.

FIGS. 5A to 5C show examples of defects cause on the mask seen from a cross-sectional direction, wherein FIG. 5A shows the foreign substance attached on the surface of the film-forming material, FIG. 5B shows a state that foreign substances are attached on the surfaces of the quartz glass and the phase shifter, and FIG. 5C shows a state that the foreign substance is attached on the groove and a residual substance of the film-forming material exists on the surface of the film-forming material.

FIG. 6 is an optical diagram for explaining general conception of an illumination optical system according to a Kohler illumination method.

FIG. 7 is a diagram schematically showing different areas of the mask illuminated by the illumination optical system shown in FIG. 1 and a disposition relationship between detection optical systems and those areas.

FIG. 8 is a plan view showing a positional relationship of the areas and an objective lens shown in FIG. 7.

FIG. 9 is a diagram showing pattern sites in a direction of film-thickness of the mask and a relationship between an object surface and an image surface on a conceptual basis.

FIG. 10 is a diagram schematically showing an optical system according to a second embodiment of the mask defect inspection apparatus of the present invention.

FIG. 11 is a diagram schematically showing an optical system according to a third embodiment of the mask defect inspection apparatus of the present invention.

FIG. 12 is a diagram schematically showing a relationship between detection optical systems and illumination areas shown in FIG. 11.

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FIG. 13 is a diagram schematically showing an optical system according to a fourth embodiment of the mask defect inspection apparatus of the present invention.

DESCRIPTION OF THE PREFERRED EMBODIMENTS

Reference will now be made in detail to the present preferred embodiments of the invention, examples of which are illustrated in the accompanying drawings. Wherever possible, the same reference numbers are used in the drawings and the description to refer to the same or like parts.

First Embodiment

FIG. 1 shows a first embodiment of a mask defect inspection apparatus according to the present invention, in which reference number 1 denotes an illumination light source, 2 is an illumination optical system, 3 is a condenser lens, 4 is a mask as a sample, and OL represents an objective lens.

As schematically shown in FIG. 2, for example, a pattern 6 is formed on a surface 5a of a quartz glass 5 as a transparent substrate of the mask 4 with Cr (chromium) as a film-forming material. There are various types of cross-sectional structures in a direction of film-thickness of the pattern 6 formed on the mask 4. For example, FIG. 3A shows that the pattern 6 is formed by providing a Cr film as the film-forming material on the surface 5a of the quartz glass 5, FIG. 3B shows that the pattern 6 is formed by providing the Cr film on the surface 5a of the quartz glass 5 at an equal interval and providing a phase shifter material 7 between the Cr film and the Cr film, and FIG. 3C shows that the pattern 6 is formed by providing the Cr film on the surface 5a of the quartz glass 5 at an equal interval and engraving a groove 8 on the surface 5a of the quartz glass 5.

The mask 4 of this kind is formed by vapor depositing the Cr on the surface 5a of the quartz glass 5 and coating a photoresist thereon, exposing a part of the photoresist thereafter and removing the Cr by etching, and so on. However, various defects may exist on the mask 4 if it is seen from the top, such as a pattern-thinning defect 9 as schematically shown in FIG. 4A in which a part of the Cr film forming the pattern 6 is removed and hence the pattern 6 is slenderized, a film-forming material residual defect 10 as shown in FIG. 4B in which the Cr as the film-forming material remains in such a manner as to bridge between the Cr film forming the pattern 6 and another Cr film, and a foreign substance attachment defect 11 as shown in FIG. 4C in which the foreign substance is attached to a surface 6a of the Cr film forming the pattern 6.

When such defects are seen in a cross-sectional view taken in the film-thickness direction of the pattern 6, for example, the foreign substance attachment defect 11 may exist on the surface 6a of the Cr film as shown in FIG. 5A or exist on a surface of the phase shifter material 7 or on the surface 5a of the quartz glass 5 as shown in FIG. 5B. As shown in FIG. 5C, the film-forming material residual defect 10 may exist in such a manner as to bridge between the surface 6a of one Cr film and the surface 6a of another Cr film instead of existing on the surface 5a of the quartz glass 5.

For example, a laser is used for the illumination light source 1. The illumination optical system 2 is provided with a laser coherence reduction mechanism and an integrator. Since a structure of the illumination optical system 2 is disclosed in JP-A 2002-39960 and in Japanese patent application No. 2003-209043 for example, its explanation will not be given in detail.

The mask **4** is illuminated for example by a well-known Kohler illumination method using the condenser lens **3**. As schematically shown in FIG. **6**, the illumination light source **1** is once imaged on a front focal plane **f1** of the condenser lens **3** as a light source image **1'** by a light-focusing lens **12**, and illumination light which exits from the front focal plane **f1** illuminates the mask **4** as a parallel light flux **P**. Reference number **13** in FIG. **6** denotes an aperture stop.

As schematically shown in FIG. **7**, the illumination optical system **2** illuminates different areas **14a** and **14b** of the mask **4**. The objective lens **OL** faces the mask **4**. Detection optical systems **15** and **16** also face the mask **4** through the objective lens **OL**. As schematically shown in FIG. **7**, the detection optical system **15** has a focusing lens **18** which receives transmission-illumination light from the area **14a** obtained through the objective lens **OL** and forms a pattern image based on the area **14a** on a detection sensor **17**. The detection optical system **16** has a focusing lens **20** which receives transmission-illumination light from the area **14b** obtained through the objective lens **OL** and forms a pattern image of the area **14b** on a detection sensor **19**. As schematically shown in FIG. **8**, when a positional relationship of the areas **14a** and **14b** is seen from the top in perpendicular to an optical axis **O1** of the objective lens **OL**, the area **14a** and the area **14b** are provided at positions symmetrical in such a manner that the optical axis **O1** is interposed between the areas **14a** and **14b**. Reference numeral **21** denoted in FIG. **7** is a total reflection mirror for reflecting the illumination light from the area **14b** toward the focusing lens **20**.

The mask **4** is configured to be movable in a direction of optical axis (in a direction of arrows **X-X'**) of the objective lens **OL** by a mask position control mechanism (moving mechanism) **22** shown in FIG. **1**, thereby a distance **L** from the surface **5a** of the quartz glass **5** of the mask **4** to the center of the objective lens **OL** can be adjustable.

A conjugate relationship between an object surface **M1** and an image surface **M2** relative to the objective lens **OL** is defined by optical performance of the objective lens **OL**. As schematically shown in FIG. **9**, given that the areas **14a** and **14b** of the surface **5a** of the quartz glass **5** are on the object surface **M1** and the detection sensors **17** and **19** are on the image surface **M2**, pattern images corresponding to pattern sites existing at the areas **14a** and **14b** of the surface **5a** of the quartz glass **5** are formed on the detection sensors **17** and **19**.

At this point, when the mask **4** is moved in the direction **X** along the optical axis **O1** to locate a back surface **5b** of the quartz glass **5** at the object surface **M1**, pattern images corresponding to pattern sites existing at areas **14a'** and **14b'** of the back surface **5b** of the quartz glass **6** are formed on the detection sensors **17** and **19**.

More specifically, when the distance **L** between the mask **4** and the objective lens **OL** is changed by the mask position control mechanism **22**, a position of the object surface **M1** in the film-thickness direction with respect to the mask **4** is changed relatively. As a result, the pattern images of the pattern sites obtained by the detection sensors **17** and **19** are changed in the film-thickness direction. Therefore, the mask position control mechanism **22** functions as focusing changing means (focusing changing device, focus adjuster) for changing a position (relation) of focusing between the pattern sites in the film-thickness direction of the mask **4** and the pattern images obtained by the detection sensors **17** and **19**, such that the pattern images obtained by the detection sensors **17** and **19** may change corresponding to the film-thickness direction of the mask **4**.

The detection optical system **15** is provided with a focusing control mechanism (moving mechanism) **23**, and the detec-

tion optical system **16** is provided with a focusing control mechanism (moving mechanism) **24**. The focusing control mechanism **23** has a function to control the focusing lens **18** in the direction of an optical axis of the focusing lens **18** (in the direction of **Y-Y'**), and the focusing control mechanism **24** similarly has a function to control the focusing lens **20** in the direction of an optical axis of the focusing lens **20** (in the direction of **Y-Y'**). When the distance **L** between the mask **4** and the objective lens **OL** is maintained constant and the focusing lenses **18** and **20** are adjusted in the optical axis directions, focusing positions of the pattern images relative to image surfaces **M2** and **M2** are changed by the focusing lenses **18** and **20**, and thereby, fine-tuning of focuses of the pattern images formed on the detection sensors **17** and **19** are carried out. Therefore, the focusing control mechanism **23** and **24** also function as focusing changing means (focusing changing device, focus adjuster) for changing the focusing position between the pattern sites in the film-thickness direction of the mask **4** and the pattern images obtained by the detection sensors **17** and **19** so that the pattern images obtained by the detection sensors **17** and **19** may change corresponding to the film-thickness direction of the mask **4**.

The mask position control mechanism **22**, and focusing control mechanisms **23** and **24** are controlled by a signal processing system (signal processor) **26**. The signal processing system **25** compares the pattern images obtained by the detection sensors **17** and **19** with a standard image which is planed in terms of design, to inspect the presence or absence of defect in the mask **4**.

In addition, the signal processing system **25** outputs the pattern images obtained by the detection sensors **17** and **19** to an image monitor (not illustrated) as image data. Accordingly, in the mask defect inspection apparatus, it is possible to observe the pattern images on a screen of the image monitor.

Identification of type of defect is for example, carried out by comparing and considering a defect according to a pattern image obtained at the time when the surface **5a** of the quartz glass **5** is in focus and a defect according to a pattern image obtained at the time when the surface of the film-forming material is in focus.

There are various types of cross-sectional structures of the pattern **6** in the direction of film-thickness as shown in FIGS. **3A** to **3C** for example. Therefore, if data corresponding to the cross-sectional structures are previously stored in the signal processing system **25** and a distance of the mask **4** relative to the objective lens **OL** is decided on the basis of a cross-sectional structure of the mask **4** to be inspected, it is possible to carry out the inspection of defect promptly.

Also, the focusing position between the pattern sites in the film-thickness direction of the mask **4** and the pattern images obtained by the detection sensors **17** and **19** may be decided by the distance of the mask **4** relative to the objective lens **OL**, based on inspection object information of whether to inspect the foreign substance attached on the mask **4** or to inspect a residual substance of the film-forming material forming the pattern.

Although the illumination optical system **2** is configured to illuminate the different areas **14a** and **14b** of the mask **4** separately in the first embodiment, it is to be noted that this configuration is for convenience of explanation. As a matter of course, the illumination optical system may be configured to illuminate a wide area including the areas **14a** and **14b**.

Second Embodiment

FIG. **10** is a diagram schematically showing a second embodiment of the mask defect inspection apparatus accord-

ing to the present invention. In the mask defect inspection apparatus of the second embodiment, the detection optical systems **15** and **16** are provided with half mirrors **26** and **27**, respectively, for dividing the illumination light obtained through the focusing lenses **18** and **20** into two. Toward the directions reflected by the half mirrors **26** and **27**, there are provided detection sensors **17a**, **17b**, **19a** and **19b**, respectively.

It is to be noted that a distance **L1** from the detection sensor **17a** to the half mirror **26** and a distance **L2** from the detection sensor **17b** to the half mirror **26** are different from each other. Likewise, a distance **L1'** from the detection sensor **19a** to the half mirror **27** and a distance **L2'** from the detection sensor **19b** to the half mirror **27** are different from each other as well. In other words, the distances of the detection sensor **17a** (**19a**) and the detection sensor **17b** (**19b**) relative to the image surfaces **M2** are different. Accordingly, when such a structure is employed in which at least one of the detection optical systems is provided with a plurality of detection sensors and the distances of the detection sensors relative to the image surfaces **M2** are differentiated from each other, each focal plane becomes different with regard to each of the detection sensors **17a** (**19a**) and **17b** (**19b**). As a result, a pattern image obtained by the detection sensor **17a** (**19a**) and a pattern image obtained by the detection sensor **17b** (**19b**) become images of a pattern site which are different from each other in a direction of thickness of the mask **4**. Hence, it is possible to identify promptly which of positions of the pattern site in the thickness direction of the mask **4** has the defect.

For example, as shown in FIG. **5C**, it is possible to inspect whether the foreign substance attachment defect **11** exists on the surface **5a** or on the groove **8** of the quartz glass **5**, promptly, according to the second embodiment of the present invention.

Third Embodiment

FIG. **11** is a diagram schematically showing a third embodiment of the mask defect inspection apparatus according to the present invention. In the mask defect inspection apparatus of the third embodiment, the illumination optical system **2** is provided with a transmission-type illumination optical system **2A** for illuminating the mask **4** from the surface **5a** of the quartz glass **5** of the mask **4** and a reflection-type illumination optical system **2B** for illuminating the mask **4** from the back surface **5b** of the quartz glass **5** of the mask **4**. In this embodiment, the transmission-type illumination optical system **2A** is provided with an illumination light switch-over mechanism **2C** for carrying out switching over of the illumination light between the transmission-illumination light and the reflection-illumination light. However, the skilled artisan will readily recognize that the reflection-type illumination optical system **2B** may be provided with such an illumination light switch-over mechanism **2C** instead of providing the optical system **2A** with the mechanism **2C**.

As shown in FIG. **12**, the reflection-type illumination optical system **2B** is provided with a light-focusing lens which is not illustrated and a reflection mirror **28** for reflecting the illumination light toward the objective lens **OL**. The reflection-type illumination optical system **2B** illuminates the mask **4** for example by the Kohler illumination method. The light focusing lens forms a light source image of the light source **1** on a focal plane of the objective lens **OL**. The objective lens **OL** converts its illumination light into a parallel light flux to illuminate the area **14a** as the reflection-illumination light.

The detection optical system **15** is disposed to face the area **14a** through the objective lens **OL**, and the detection optical

system **16** is disposed to face the area **14b** through the objective lens **OL**. The detection optical system **15** functions as a reflection-detection optical system for forming a pattern image of the area **14a** illuminated by the reflection-illumination light on the detection sensor **17**, and the detection optical system **16** functions as a transmission-detection optical system for forming a pattern image of the area **14b** illuminated by the transmission-illumination light on the detection sensor **19**.

It is not easy to differentiate images when a same area is illuminated simultaneously by the transmission-type illumination and the reflection-type illumination and the pattern images are retrieved by same detection optical system, since the pattern images overlap with each other. However, when the detection optical systems **15** and **16** are differentiated into and used as the transmission-detection optical system and the reflection-detection optical system, and at the same time, when the different areas **14a** and **14b** are illuminated simultaneously as in the present embodiment, it is possible to retrieve the pattern images simultaneously without causing the pattern images to be overlapped. Therefore, it is possible to promptly carry out the identification of whether the foreign substance is attached on the mask **4** or the film-forming material for forming the pattern remains on the mask **4**.

As well as in this embodiment, the focusing position between the pattern sites in the film-thickness direction of the mask **4** and the pattern images obtained by the detection sensors **17** and **19** may be decided by the distance **L** of the mask **4** relative to the objective lens **OL**, based on the inspection object information of whether to inspect the foreign substance attached on the mask **4** or to inspect the residual substance of the film-forming material forming the pattern.

More specifically, if a position of the surface **5a** of the quartz glass **6** and a position of the surface **6a** of the film-forming material are calculated by calibration carried out before the inspection and positions in focus of the detection sensors **17** and **19** are previously set on the basis of whether the object to be inspected is the residual substance of the film-forming material attached on the mask **4** or the foreign substance attached on the mask **4**, it is possible to ensure the prompt inspection of the defect.

In addition, if the illumination optical system **2A** is switched-over from the illumination type of transmission-illumination to the illumination type of reflection-illumination by using the illumination light switch-over mechanism **2C**, it is possible to retrieve the pattern image according to the transmission-illumination and the pattern image according to the reflection-illumination with the same detection optical system **16** with regard to the same area **14b**. Hence, by comparing those pattern images, it is possible to carry out the identification of the defect more easily.

Because a well-known structure can be utilized to the illumination light switch-over mechanism **2C**, explanation for its structure will not be given in detail.

Fourth Embodiment

FIG. **13** is a diagram schematically showing a fourth embodiment of the mask defect inspection apparatus according to the present invention. As similar to the second embodiment, in the mask defect inspection apparatus of the fourth embodiment, the detection optical systems **15** and **16** are provided with the half mirrors **26** and **27**, respectively, for dividing the illumination light obtained through the focusing lenses **18** and **20** into two. Toward the directions reflected by the half mirrors **26** and **27**, there are provided the detection sensors **17a**, **17b**, **19a** and **19b**, respectively. The distance **L1**

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from the detection sensor **17a** to the half mirror **26** and the distance **L2** from the detection sensor **17b** to the half mirror **26** are different from each other. Likewise, the distance **L1'** from the detection sensor **19a** to the half mirror **27** and the distance **L2'** from the detection sensor **19b** to the half mirror **27** are also different from each other.

In the fourth embodiment, the detection sensors **17a** and **17b** are configured to be movable in the optical axis direction of the detection optical system **16** by a sensor moving mechanism (moving mechanism) **29**, and the detection sensors **19a** and **19b** are configured to be movable in the optical axis direction of the detection optical system **15** by a sensor moving mechanism (moving mechanism) **30**.

According to this embodiment, when the detection sensors **17a**, **17b**, **19a** and **19b** are moved in the optical axis directions in a state that the distance **L** between the mask **4** and the objective lens **OL** is held constant and positional relationships of the focusing lenses **18** and **20** relative to the objective lens **OL** are held constant, focusing positions of pattern images relative to the image surfaces **M2** are changed by the detection sensors **17a**, **17b**, **19a** and **19b**, thereby fine-tuning for focuses of the pattern images formed on the detection sensors **17a**, **17b**, **19a** and **19b** is carried out.

Therefore, in the fourth embodiment, the sensor moving mechanisms **29** and **30** function as focusing changing means (focusing changing device, focus adjuster) for changing the position of focusing between the pattern sites in the film-thickness direction of the mask **4** and the pattern images obtained by the detection sensors **17a**, **17b**, **19a** and **19b** so that the pattern images obtained by the detection sensors **17a**, **17b**, **19a** and **19b** may change corresponding to the film-thickness direction of the mask **4**.

As described in the foregoing, in some of the embodiments of the present invention, the focusing changing means (focusing changing device, focus adjuster) is structured by the mask position control mechanism (mask moving mechanism) **22** which changes the distance **L** between the objective lens **OL** and the mask **4** by moving the mask **4** relative to the objective lens **OL** in the direction of optical axis of the objective lens **OL**. However, in one embodiment, the focusing changing means (focusing changing device focus adjuster) may be structured by an objective lens moving mechanism (moving mechanism) for moving the objective lens **OL** in the optical axis direction.

It will be apparent to those skilled in the art that various modifications and variations can be made to the structure of the present invention without departing from the scope or spirit of the invention. In view of the foregoing, it is intended that the present invention covers modifications and variations of this invention provided they fall within the scope of the following claims and their equivalents.

What is claimed is:

1. A mask defect inspection apparatus, comprising:

an illumination optical system which illuminates a plurality of illumination areas including at least a first illumination area and a second illumination area different from each other of a mask on which a pattern is formed;

an objective lens facing the mask;

a first focusing lens which receives first illumination light from the first illumination area of the mask obtained through the objective lens;

a second focusing lens which receives second illumination light from the second illumination area of the mask obtained through the objective lens;

a first detection sensor which obtains an image of the pattern in the first illumination area of the mask based on the first illumination light received by the first focusing lens;

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a second detection sensor which obtains an image of the pattern in the second illumination area of the mask based on the second illumination light received by the second focusing lens;

a first moving mechanism which moves the first detection sensor in a direction of an optical axis of the first detection sensor to change a position of focusing between sites of the pattern in the first illumination area in a film-thickness direction of the mask and the image of the pattern obtained by the first detection sensor, such that the image of the pattern obtained by the first detection sensor is changed corresponding to the film-thickness direction of the mask; and

a second moving mechanism which moves the second detection sensor in a direction of an optical axis of the second detection sensor to change a position of focusing between sites of the pattern in the second illumination area in the film-thickness direction of the mask and the image of the pattern obtained by the second detection sensor, such that the image of the pattern obtained by the second detection sensor is changed corresponding to the film-thickness direction of the mask.

2. A mask defect inspection apparatus according to claim **1**, further comprising a signal processor connected with the first moving mechanism and the second moving mechanism and which controls the first moving mechanism and the second moving mechanism to move the first detection sensor and the second detection sensor.

3. A mask defect inspection apparatus according to claim **2**, wherein the signal processor compares the image of the pattern obtained by the first detection sensor and the image of the pattern obtained by the second detection sensor with preset standard images to inspect presence of a defect of the mask.

4. A mask defect inspection apparatus according to claim **3**, further comprising a display, wherein the signal processor displays the image of the pattern obtained by the first detection sensor and the image of the pattern obtained by the second detection sensor on the display.

5. A mask defect inspection apparatus according to claim **1**, further comprising a third moving mechanism which moves the mask in a direction of an optical axis of the objective lens to change the position of focusing between the sites of the pattern in the first illumination area and the second illumination area in the film-thickness direction of the mask and the images of the pattern obtained by the first detection sensor and the second detection sensor, such that the images of the pattern obtained by the first detection sensor and the second detection sensor are changed corresponding to the film-thickness direction of the mask.

6. A mask defect inspection apparatus according to claim **1**, further comprising a fourth moving mechanism which moves the objective lens in a direction of an optical axis of the objective lens to change the position of focusing between the sites of the pattern in the first illumination area and the second illumination area in the film-thickness direction of the mask and the images of the pattern obtained by the first detection sensor and the second detection sensor, such that the images of the pattern obtained by the first detection sensor and the second detection sensor are changed corresponding to the film-thickness direction of the mask.

7. A mask defect inspection apparatus according to claim **1**, further comprising:

a condenser lens provided between the illumination optical system and the mask; and

a total reflection mirror provided between the objective lens and the first and the second focusing lenses, and which reflects one of the first illumination light from the first illumination area and the second illumination light from the second illumination area of the mask through

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the objective lens toward one of the first focusing lens and the second focusing lens.

8. A mask defect inspection apparatus, comprising:

an illumination optical system which illuminates a plurality of illumination areas including at least a first illumination area and a second illumination area different from each other of a mask on which a pattern is formed;

an objective lens facing the mask;

a first focusing lens which receives first illumination light from the first illumination area of the mask obtained through the objective lens;

a second focusing lens which receives second illumination light from the second illumination area of the mask obtained through the objective lens;

a first detection sensor which obtains an image of the pattern in the first illumination area of the mask based on the first illumination light received by the first focusing lens;

a second detection sensor which obtains an image of the pattern in the second illumination area of the mask based on the second illumination light received by the second focusing lens;

a first moving mechanism which moves the first focusing lens in a direction of an optical axis of the first focusing lens to change a position of focusing between sites of the pattern in the first illumination area in a film-thickness direction of the mask and the image of the pattern obtained by the first detection sensor, such that the image of the pattern obtained by the first detection sensor is changed corresponding to the film-thickness direction of the mask; and

a second moving mechanism which moves the second focusing lens in a direction of an optical axis of the second focusing lens to change a position of focusing between sites of the pattern in the second illumination area in the film-thickness direction of the mask and the image of the pattern obtained by the second detection sensor, such that the image of the pattern obtained by the second detection sensor is changed corresponding to the film-thickness direction of the mask.

9. A mask defect inspection apparatus according to claim **8**, further comprising a signal processor connected with the first moving mechanism and the second moving mechanism and which controls the first moving mechanism and the second moving mechanism to move the first focusing lens and the second focusing lens.

10. A mask defect inspection apparatus according to claim **9**, wherein the signal processor compares the image of the pattern obtained by the first detection sensor and the image of the pattern obtained by the second detection sensor with preset standard images to inspect presence of a defect of the mask.

11. A mask defect inspection apparatus according to claim **10**, further comprising a display, wherein the signal processor displays the image of the pattern obtained by the first detection sensor and the image of the pattern obtained by the second detection sensor on the display.

12. A mask defect inspection apparatus according to claim **8**, further comprising a third moving mechanism which moves the mask in a direction of an optical axis of the objective lens to change the position of focusing between the sites of the pattern in the first illumination area and the second illumination area in the film-thickness direction of the mask and the images of the pattern obtained by the first detection sensor and the second detection sensor, such that the images of the pattern obtained by the first detection sensor and the second detection sensor are changed corresponding to the film-thickness direction of the mask.

13. A mask defect inspection apparatus according to claim **8**, further comprising a fourth moving mechanism which

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moves the objective lens in a direction of an optical axis of the objective lens to change the position of focusing between the sites of the pattern in the first illumination area and the second illumination area in the film-thickness direction of the mask and the images of the pattern obtained by the first detection sensor and the second detection sensor, such that the images of the pattern obtained by the first detection sensor and the second detection sensor are changed corresponding to the film-thickness direction of the mask.

14. A mask defect inspection apparatus according to claim **8**, further comprising:

a condenser lens provided between the illumination optical system and the mask; and

a total reflection mirror provided between the objective lens and the first and the second focusing lenses, and which reflects one of the first illumination light from the first illumination area and the second illumination light from the second illumination area of the mask through the objective lens toward one of the first focusing lens and the second focusing lens.

15. A mask defect inspection apparatus comprising:

an illumination optical system which illuminates a plurality of illumination areas including at least a first illumination area and a second illumination area different from each other of a mask on which a pattern is formed;

an objective lens facing the mask;

a first focusing lens which receives first illumination light from the first illumination area of the mask obtained through the objective lens;

a second focusing lens which receives second illumination light from the second illumination area of the mask obtained through the objective lens;

a first detection sensor which obtains an image of the pattern in the first illumination area of the mask based on the first illumination light received by the first focusing lens;

a second detection sensor which obtains an image of the pattern in the second illumination area of the mask based on the second illumination light received by the second focusing lens;

a third detection sensor which obtains the image of the pattern in the first illumination area of the mask based on the first illumination light received by the first focusing lens;

a fourth detection sensor which obtains the image of the pattern in the second illumination area of the mask based on the second illumination light received by the second focusing lens;

a first half-mirror which divides the first illumination light obtained through the first focusing lens into the first illumination light that travels toward the first detection sensor and the first illumination light that travels toward the third detection sensor;

a second half-mirror which divides the second illumination light obtained through the second focusing lens into the second illumination light that travels toward the second detection sensor and the second illumination light that travels toward the fourth detection sensor;

a first moving mechanism which moves the first focusing lens in a direction of an optical axis of the first focusing lens to change a position of focusing between sites of the pattern in the first illumination area in a film-thickness direction of the mask and the images of the pattern obtained by the first detection sensor and the third detection sensor, such that the images of the pattern obtained by the first detection sensor and the third detection sensors are changed corresponding to the film-thickness direction of the mask; and

a second moving mechanism which moves the second focusing lens in a direction of an optical axis of the

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second focusing lens to change a position of focusing between sites of the pattern in the second illumination area in the film-thickness direction of the mask and the images of the pattern obtained by the second detection sensor and the fourth detection sensor, such that the images of the pattern obtained by the second detection sensor and the fourth detection sensors are changed corresponding to the film-thickness direction of the mask.

16. A mask defect inspection apparatus, comprising:
- an illumination optical system which illuminates a plurality of illumination areas including at least a first illumination area and a second illumination area different from each other of a mask on which a pattern is formed;
 - an objective lens facing the mask;
 - a first focusing lens which receives first illumination light from the first illumination area of the mask obtained through the objective lens;
 - a second focusing lens which receives second illumination light from the second illumination area of the mask obtained through the objective lens;
 - a first detection sensor which obtains an image of the pattern in the first illumination area of the mask based on the first illumination light received by the first focusing lens;
 - a second detection sensor which obtains an image of the pattern in the second illumination area of the mask based on the second illumination light received by the second focusing lens;
 - a third detection sensor which obtains the image of the pattern in the first illumination area of the mask based on the first illumination light received by the first focusing lens;
 - a fourth detection sensor which obtains the image of the pattern in the second illumination area of the mask based on the second illumination light received by the second focusing lens;
 - a first half-mirror which divides the first illumination light obtained through the first focusing lens into the first illumination light that travels toward the first detection sensor and the first illumination light that travels toward the third detection sensor;
 - a second half-mirror which divides the second illumination light obtained through the second focusing lens into the second illumination light that travels toward the second detection sensor and the second illumination light that travels toward the fourth detection sensor;
 - a first moving mechanism which moves the first focusing lens in a direction of an optical axis of the first focusing lens to change a position of focusing between sites of the pattern in the first illumination area in a film-thickness direction of the mask and the image of the pattern obtained by the first detection sensor, such that the image of the pattern obtained by the first detection sensor is changed corresponding to the film-thickness direction of the mask; and
 - a second moving mechanism which moves the second focusing lens in a direction of an optical axis of the second focusing lens to change a position of focusing between sites of the pattern in the second illumination area in the film-thickness direction of the mask and the image of the pattern obtained by the second detection sensor, such that the image of the pattern obtained by the second detection sensor is changed corresponding to the film-thickness direction of the mask,
- wherein a distance between the first detection sensor to the first half-mirror and a distance between the third detection sensor to the first half-mirror are different from each other, and a distance between the second detection sen-

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sor to the second half-mirror and a distance between the fourth detection sensor to the second half-mirror are different from each other.

17. A mask defect inspection apparatus, comprising:
- an illumination optical system which illuminates a plurality of illumination areas including at least a first illumination area and a second illumination area different from each other of a mask on which a pattern is formed;
 - an objective lens facing the mask;
 - a first focusing lens which receives first illumination light from the first illumination area of the mask obtained through the objective lens;
 - a second focusing lens which receives second illumination light from the second illumination area of the mask obtained through the objective lens;
 - a first detection sensor which obtains an image of the pattern in the first illumination area of the mask based on the first illumination light received by the first focusing lens;
 - a second detection sensor which obtains an image of the pattern in the second illumination area of the mask based on the second illumination light received by the second focusing lens;
 - a third detection sensor which obtains the image of the pattern in the first illumination area of the mask based on the first illumination light received by the first focusing lens;
 - a fourth detection sensor which obtains the image of the pattern in the second illumination area of the mask based on the second illumination light received by the second focusing lens;
 - a first half-mirror which divides the first illumination light obtained through the first focusing lens into the first illumination light that travels toward the first detection sensor and the first illumination light that travels toward the third detection sensor;
 - a second half-mirror which divides the second illumination light obtained through the second focusing lens into the second illumination light that travels toward the second detection sensor and the second illumination light that travels toward the fourth detection sensor;
 - a first sensor moving mechanism which moves the first detection sensor and the third detection sensor in a direction of an optical axis of the first detection sensor and in a direction of an optical axis of the third detection sensor to change a position of focusing between sites of the pattern in the first illumination area in a film-thickness direction of the mask and the images of the pattern obtained by the first detection sensor and the third detection sensor, such that the images of the pattern obtained by the first detection sensor and the third detection sensor are changed corresponding to the film-thickness direction of the mask; and
 - a second sensor moving mechanism which moves the second detection sensor in a direction of an optical axis of the second detection sensor and the fourth detection sensor in a direction of an optical axis of the fourth detection sensor to change a position of focusing between sites of the pattern in the second illumination area in the film-thickness direction of the mask and the images of the pattern obtained by the second detection sensor and the fourth detection sensor, such that the images of the pattern obtained by the second detection sensor and the fourth detection sensor are changed corresponding to the film-thickness direction of the mask.