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Fitzgerald

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(54) **METHOD AND SYSTEM FOR DETECTING AND ISOLATING STRAY VOLTAGE**

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G01R 31/04 (2006.01)

(52) **U.S. Cl.** **324/522; 324/511; 361/78; 361/79**

(58) **Field of Classification Search** 361/78, 361/79; 324/509-512, 522
See application file for complete search history.

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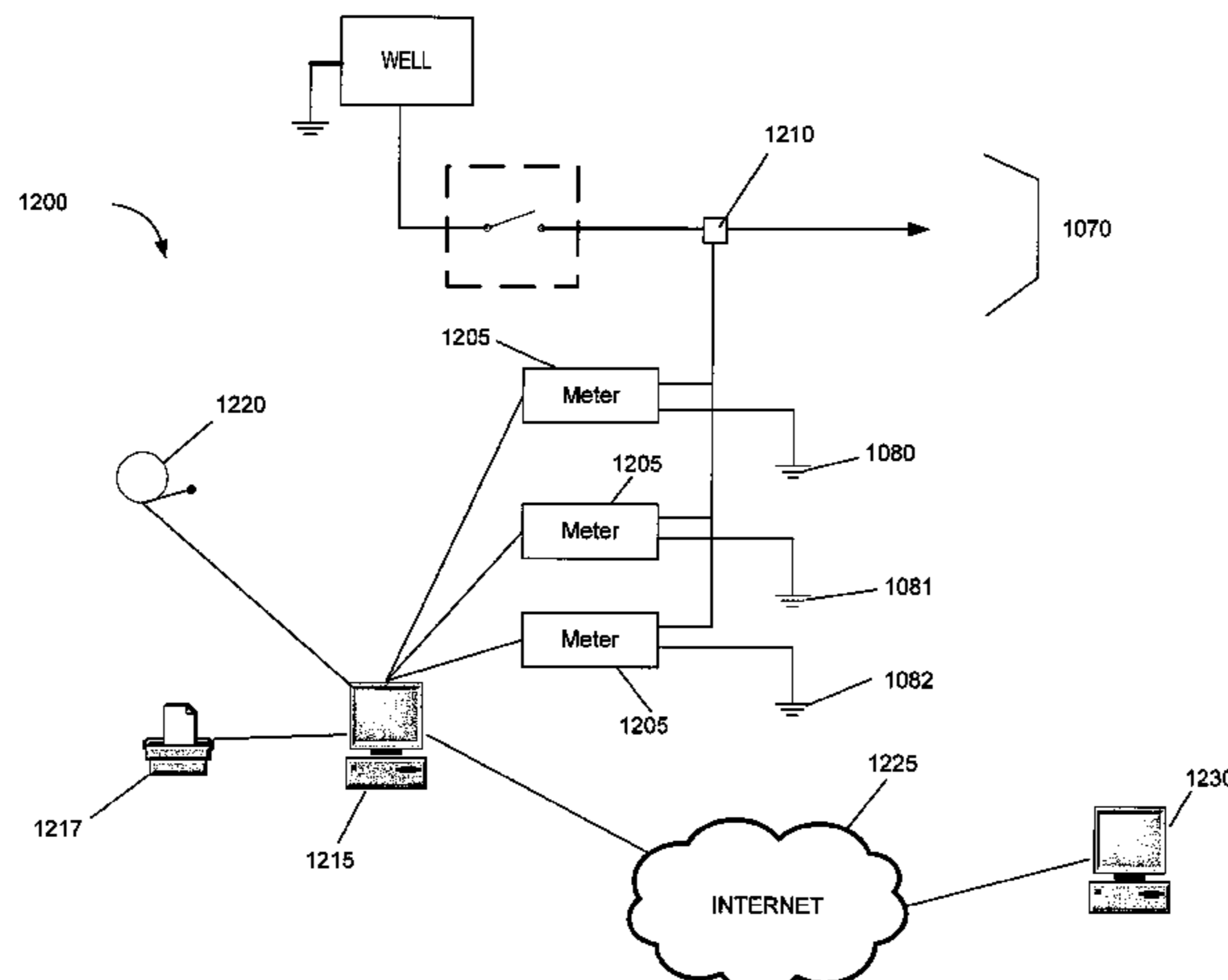
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(57) **ABSTRACT**

A stray voltage detection and isolation system. The stray voltage detection portion of the system includes a water delivery system electrically isolated from an electrical transmission system of an electric utility. Meters measure an electrical characteristic between a first test-point that is electrically connected to the water delivery system and a plurality of second test-points. The second test-points are at earth grounds at locations electrically connected to the first test-point. The location of a source of stray voltage can be determined by evaluating differences in the measured electrical characteristics. The stray voltage isolation portion of the system electrically isolates a water delivery system. A controller maintains an air gap between a water source and a first storage tank or between the first storage tank and a second storage tank. The second storage tank provides the electrically isolated water.

7 Claims, 21 Drawing Sheets



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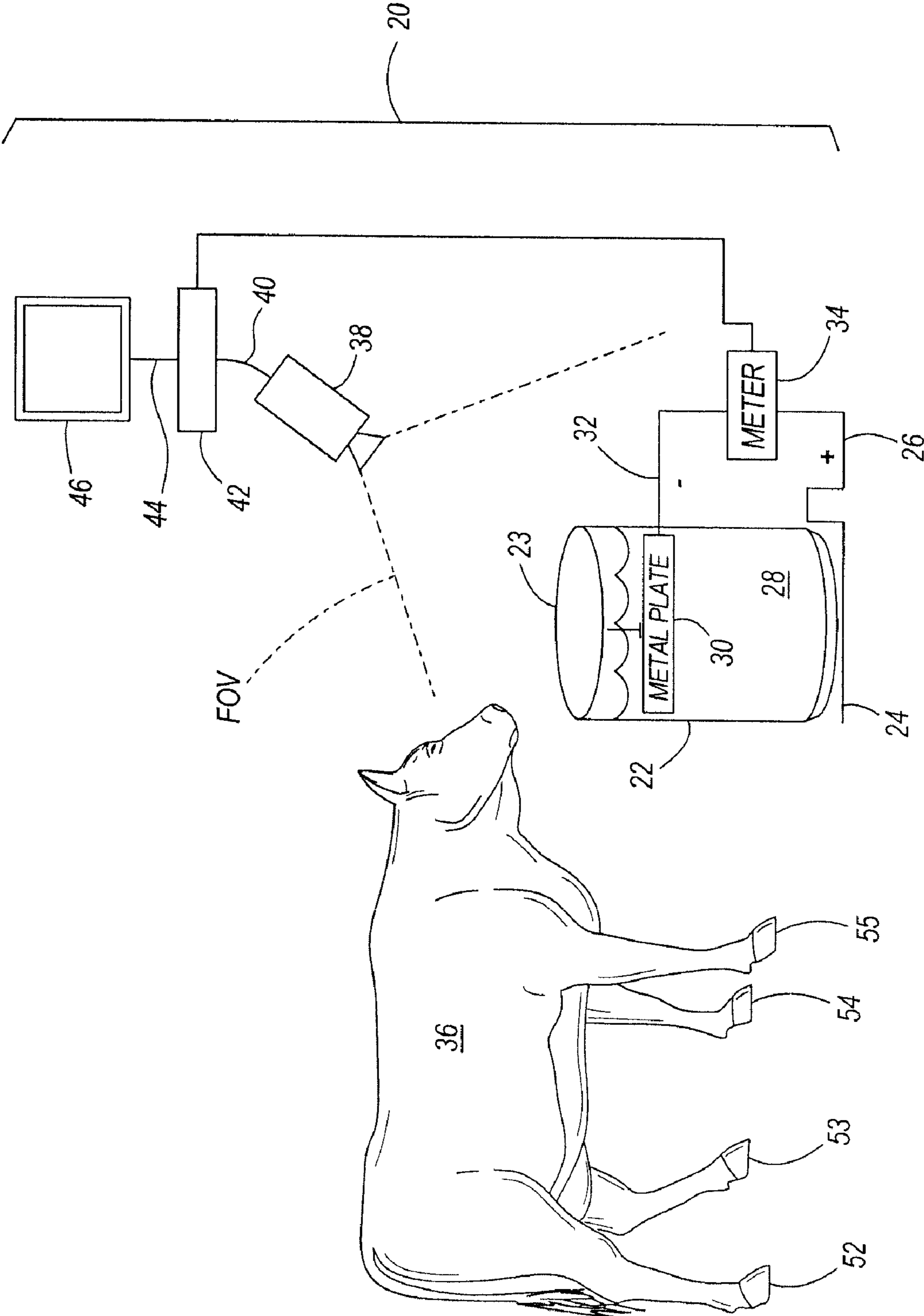


FIG. 1

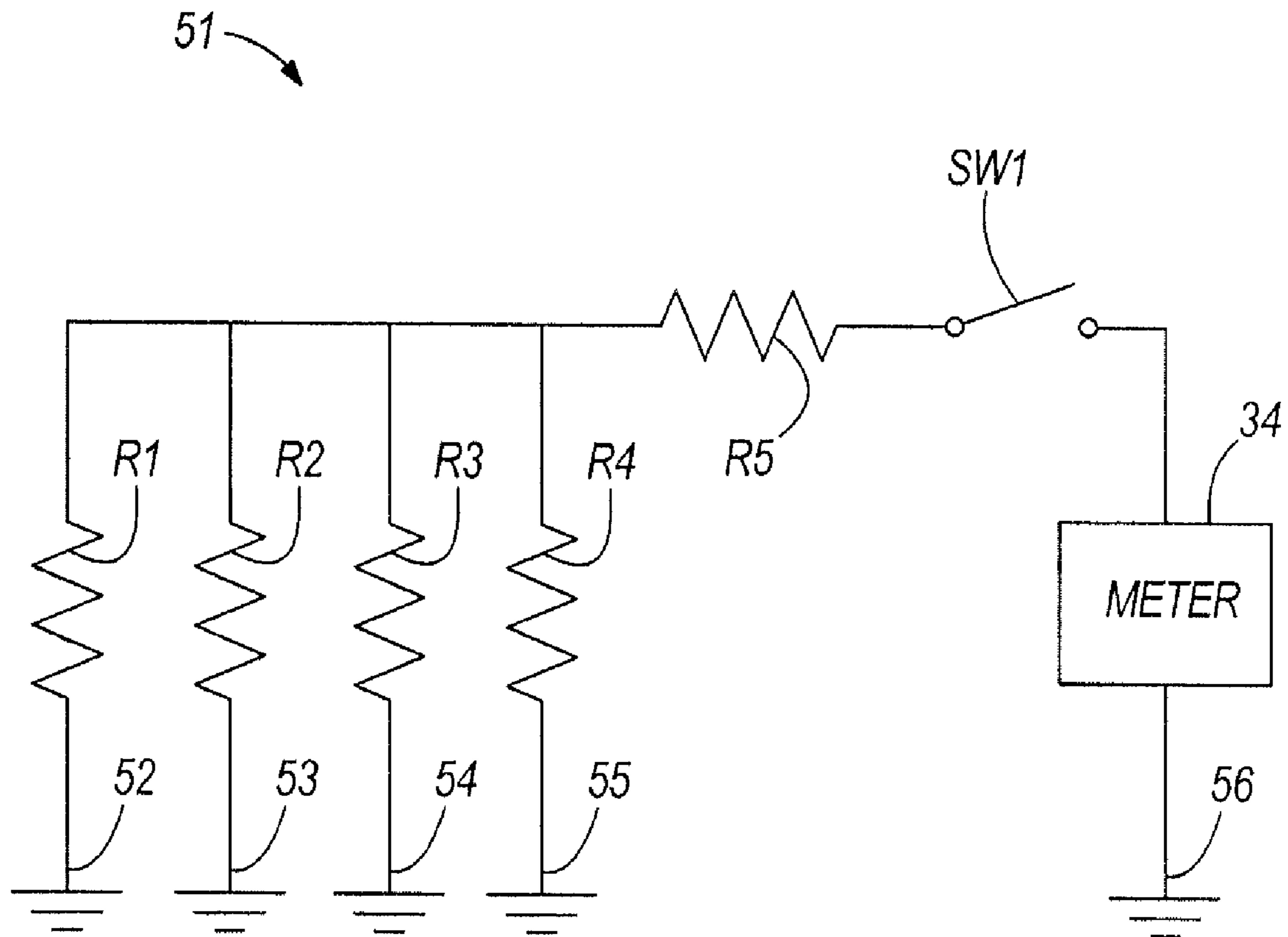


FIG. 2

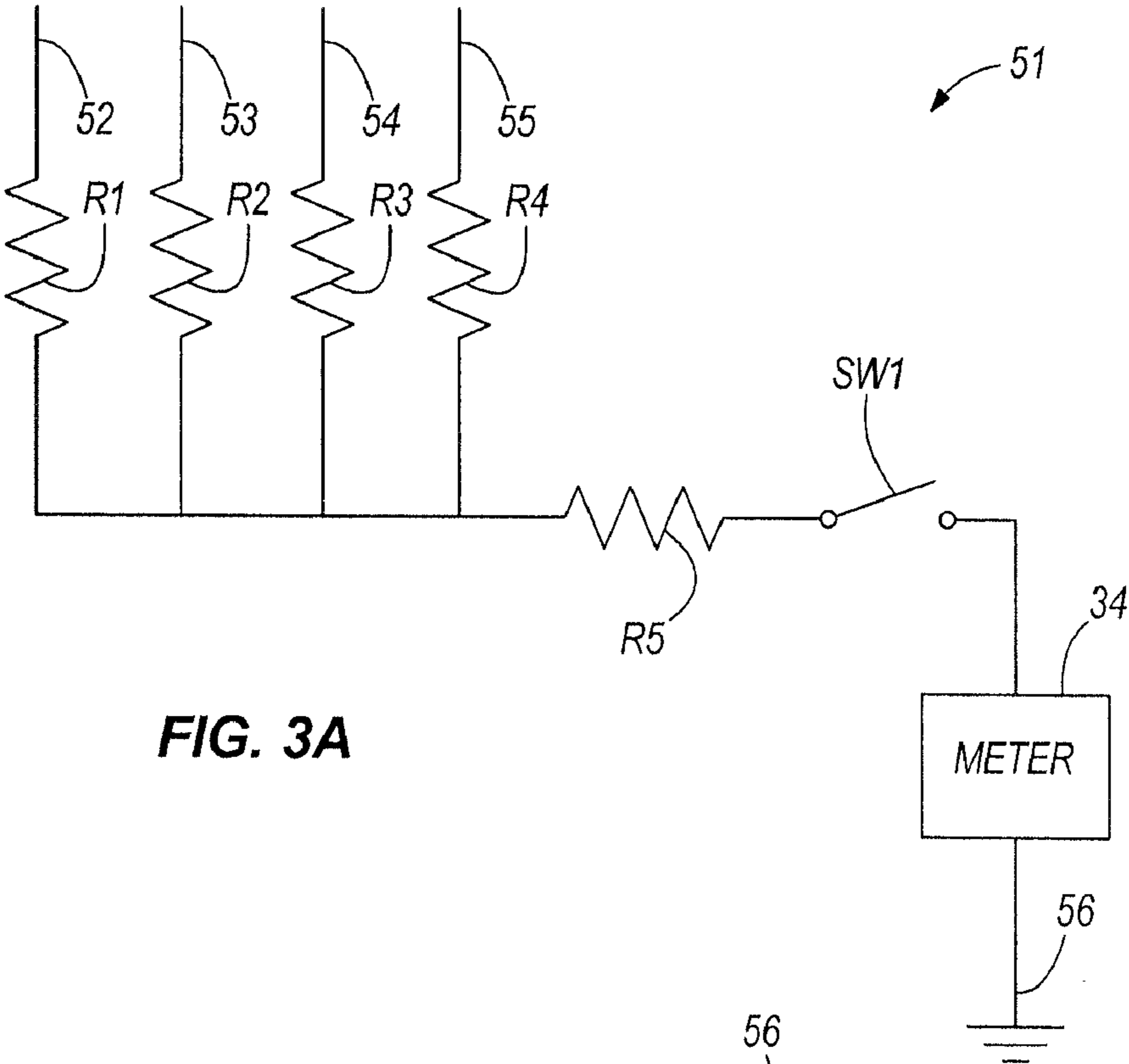


FIG. 3A

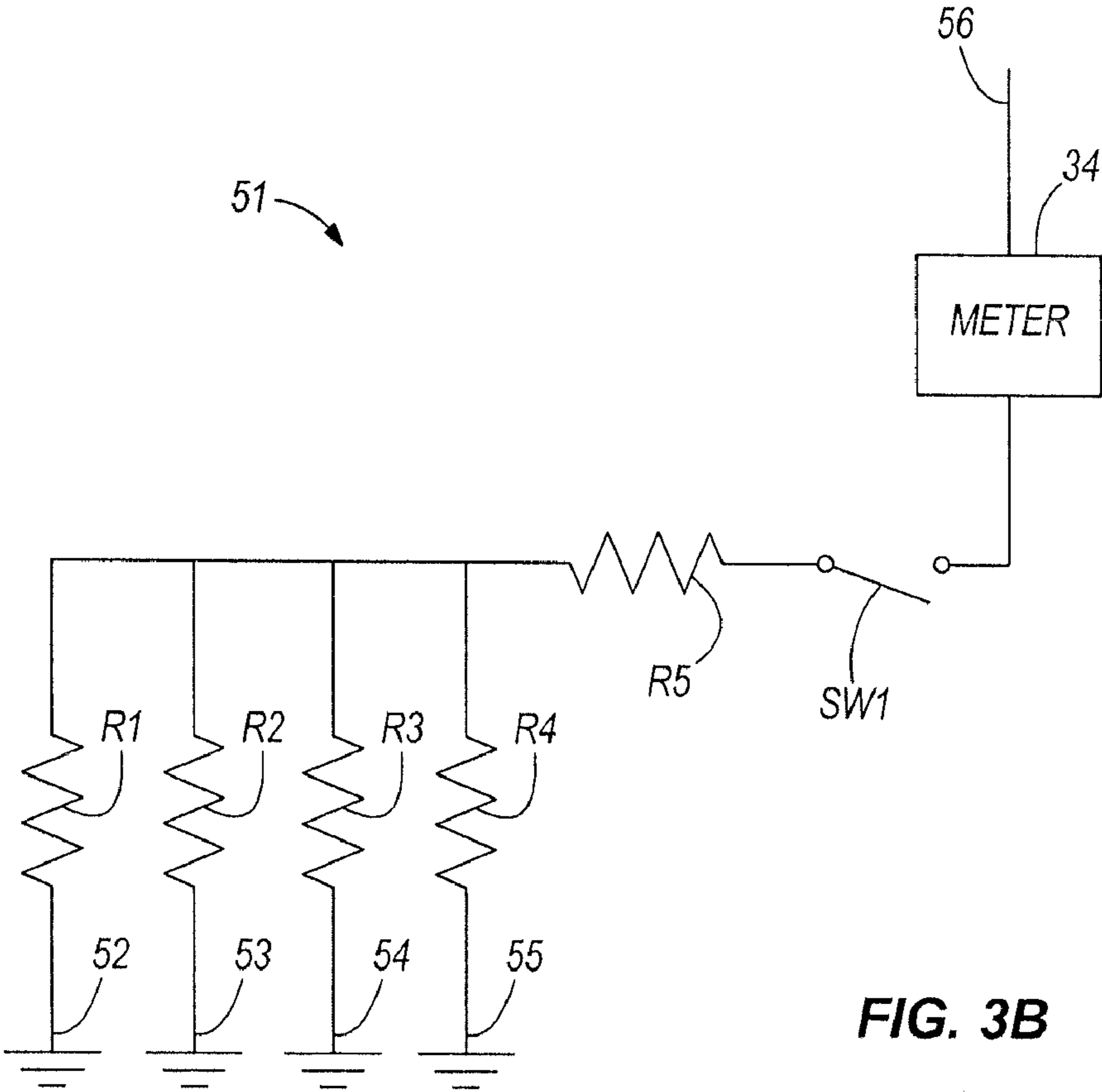


FIG. 3B

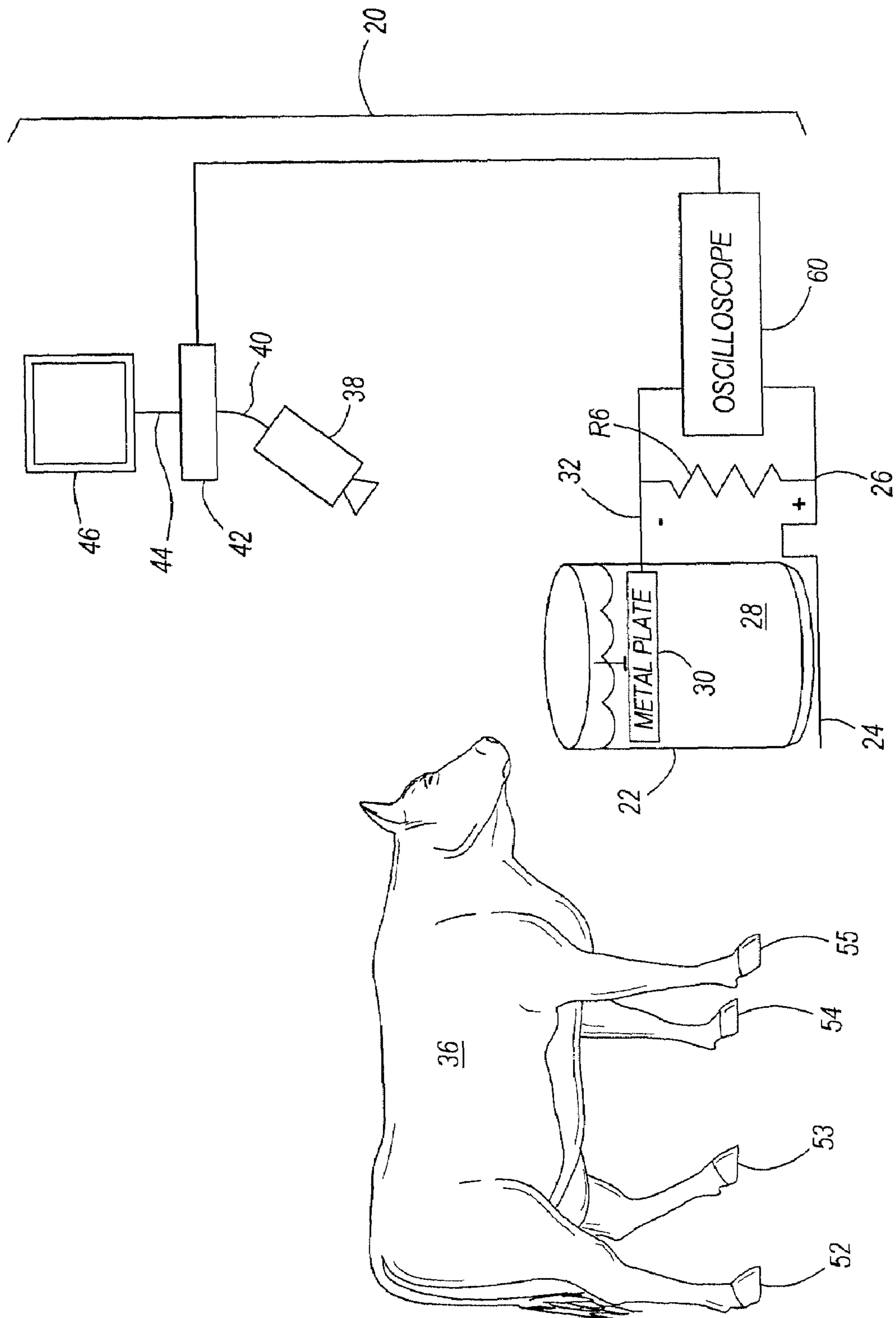


FIG. 4

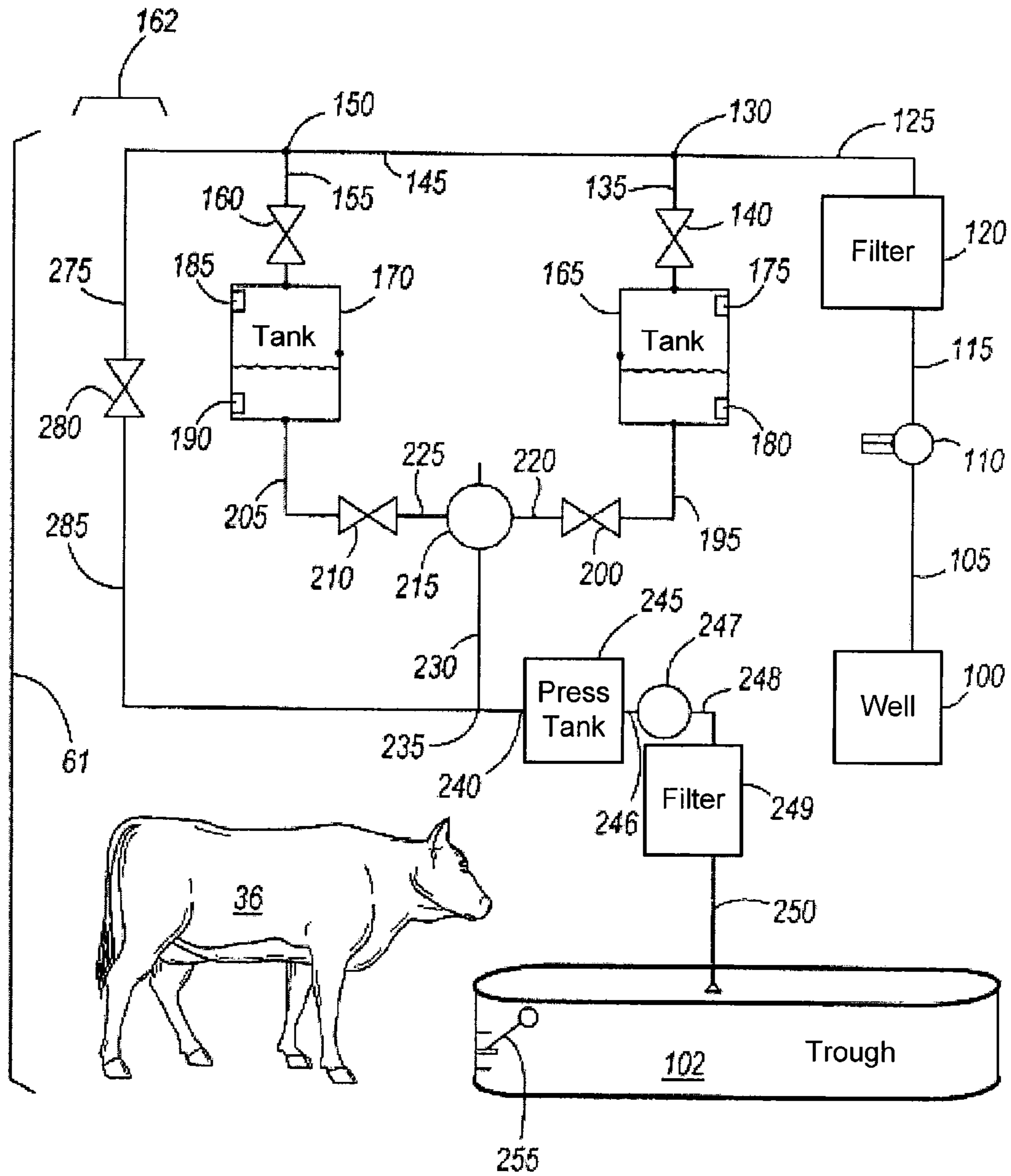


FIG. 5A

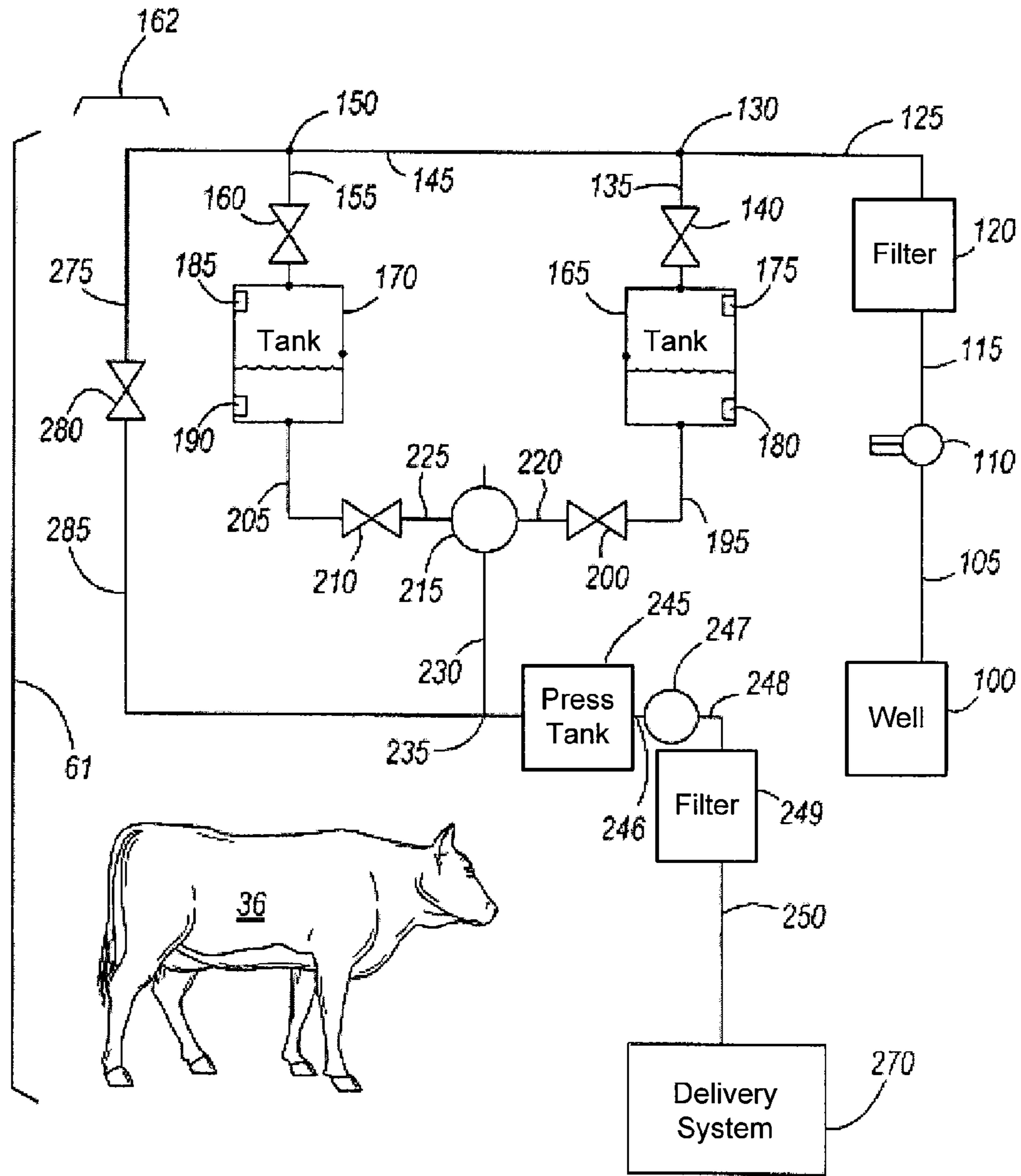


FIG. 5B

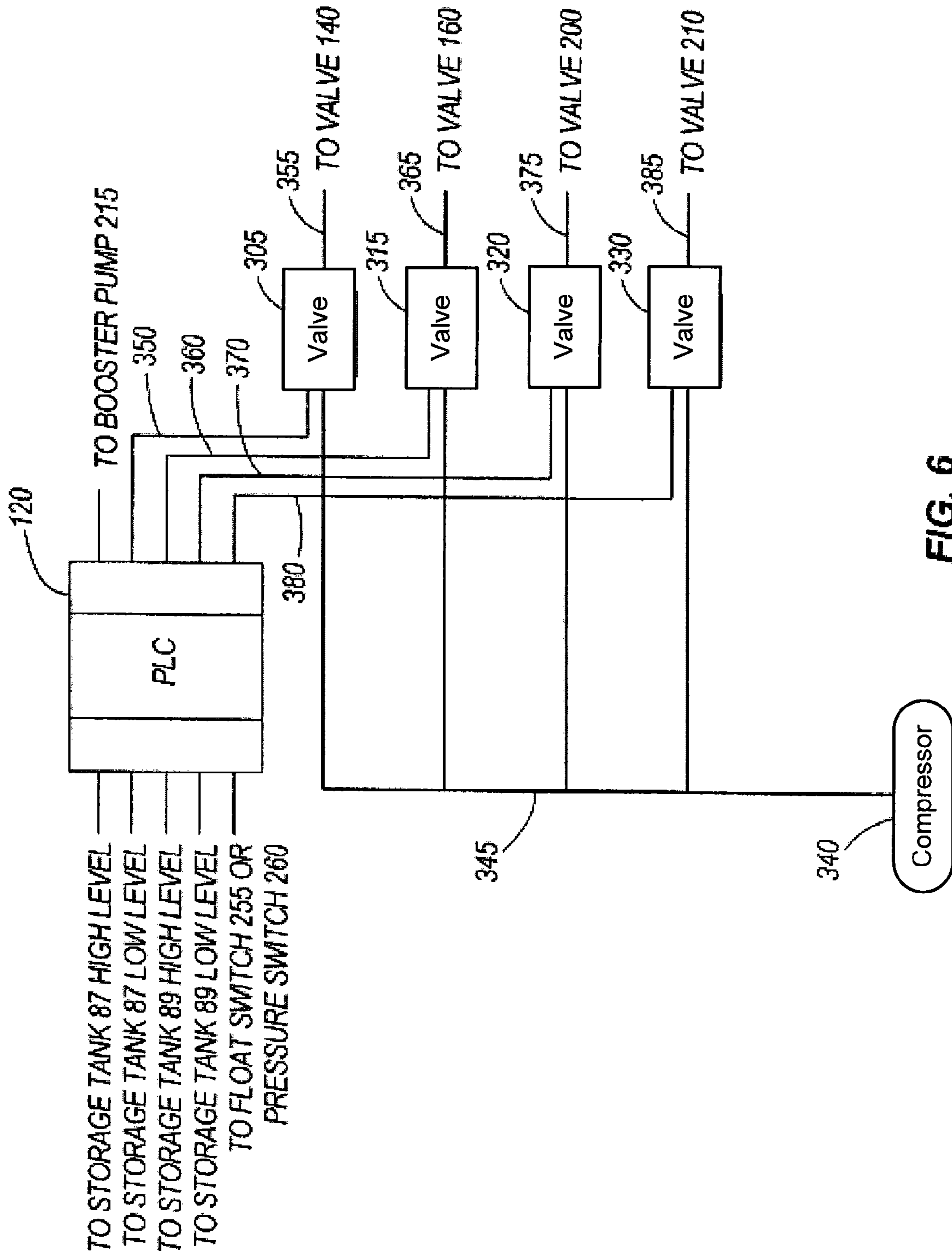


FIG. 6

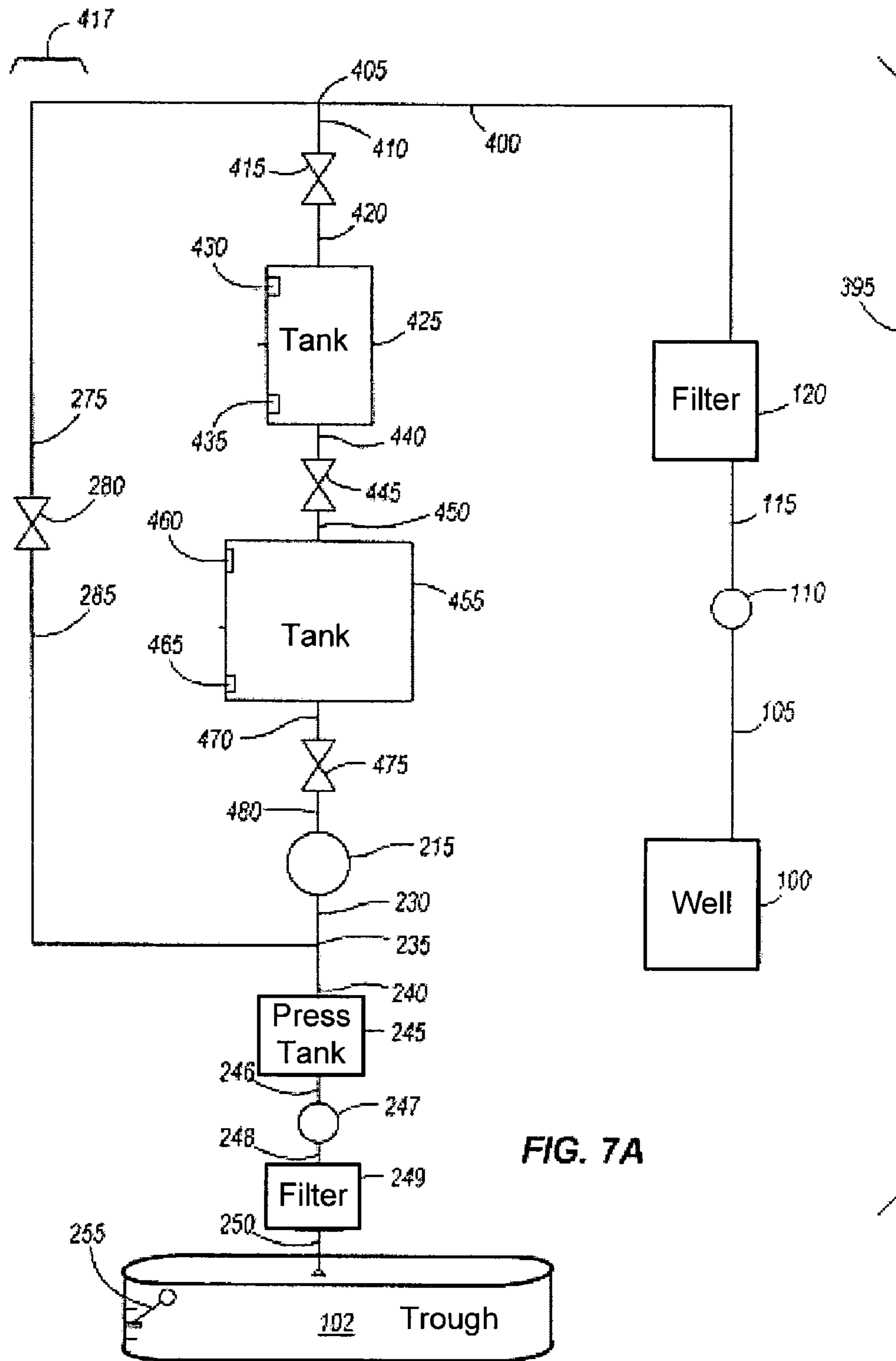


FIG. 7A

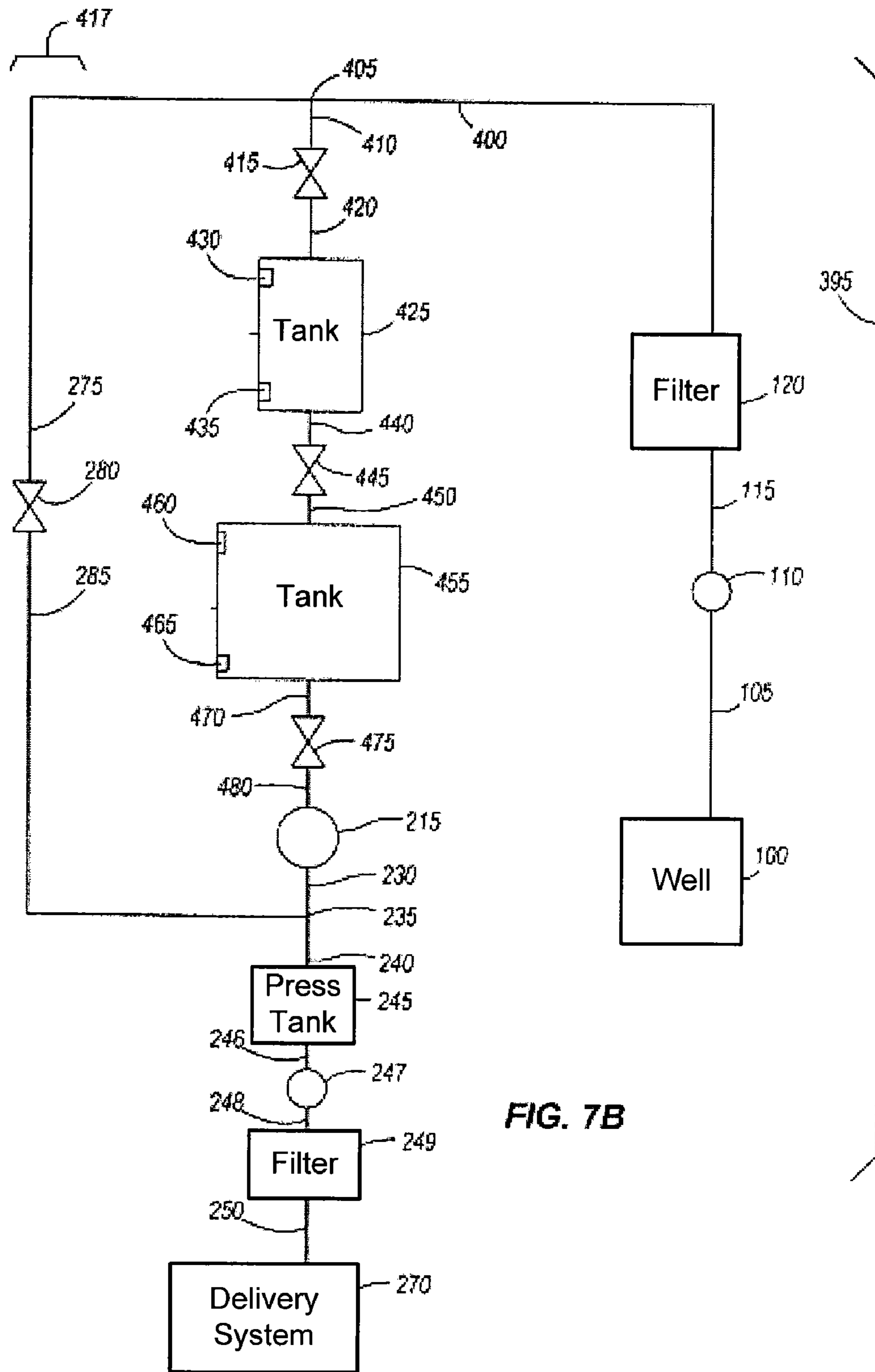


FIG. 7B

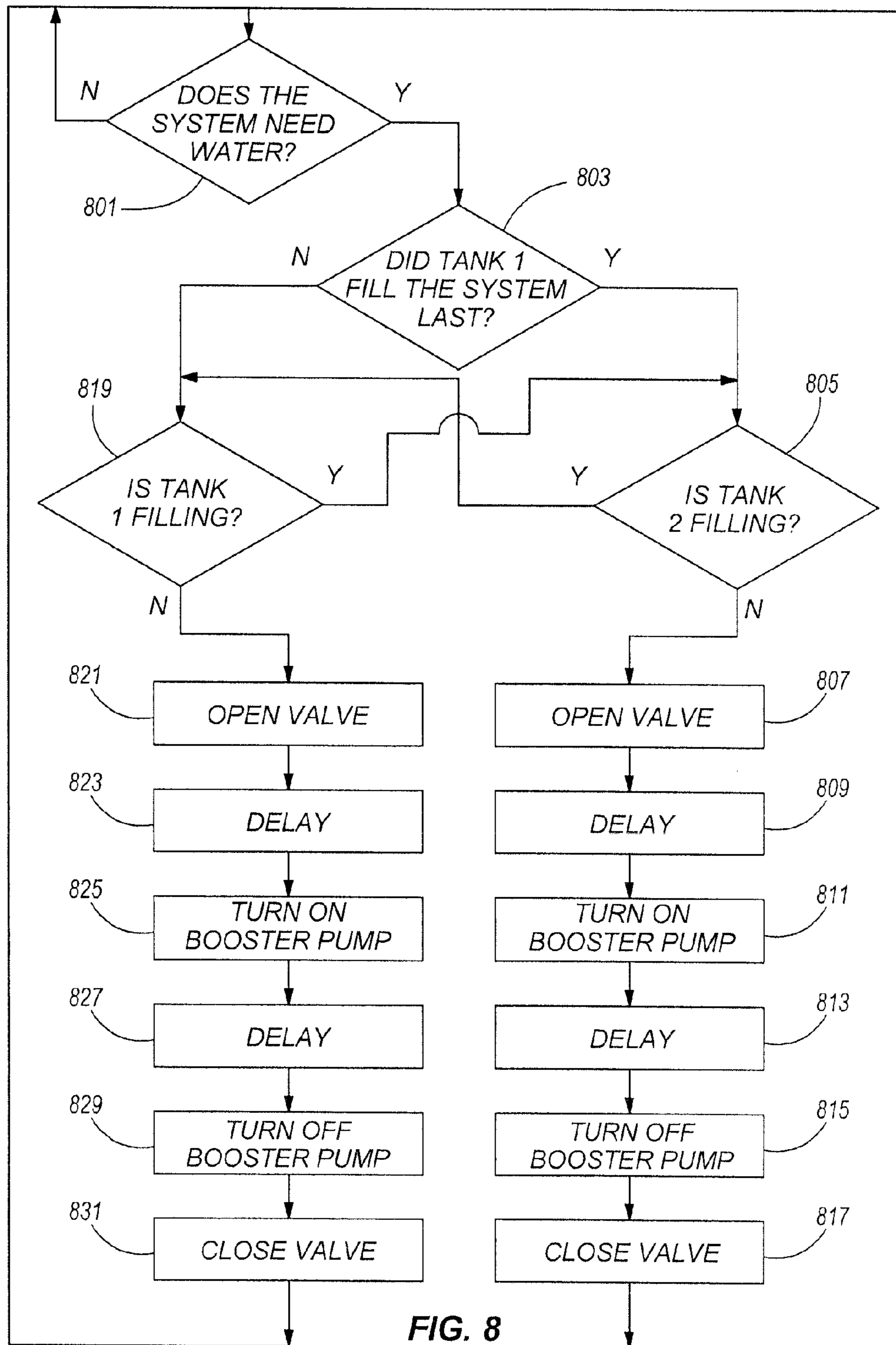


FIG. 8

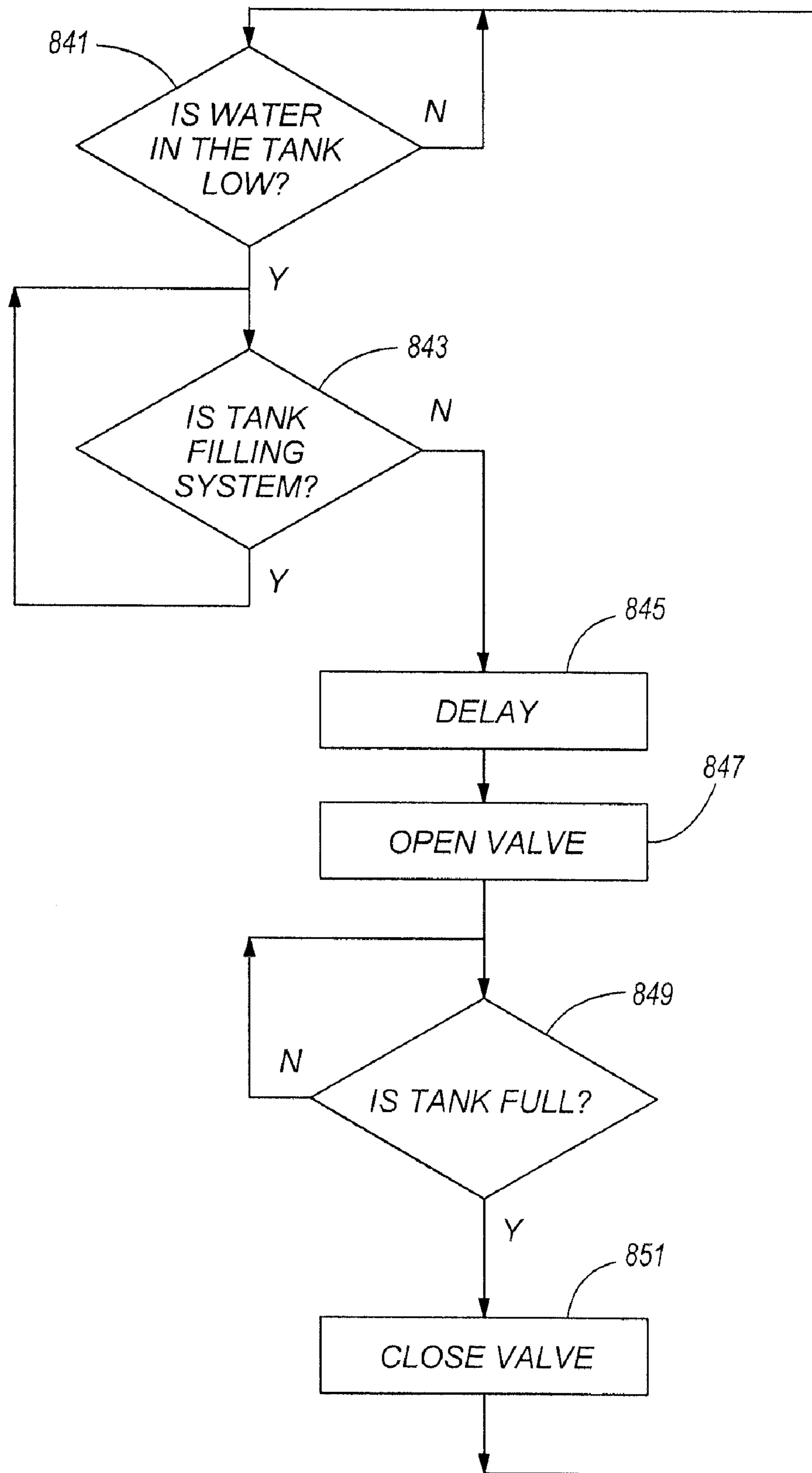


FIG. 9

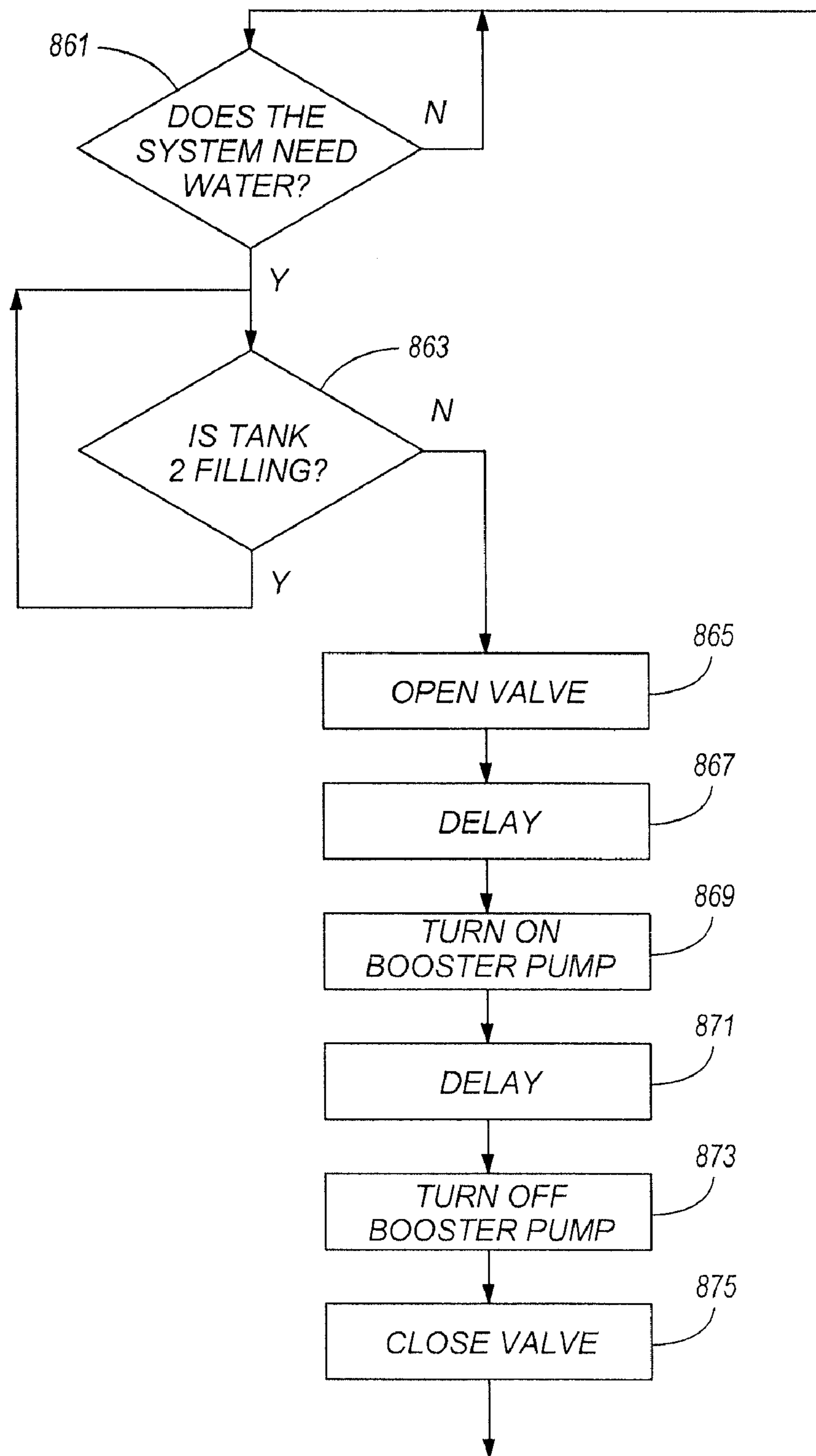


FIG. 10

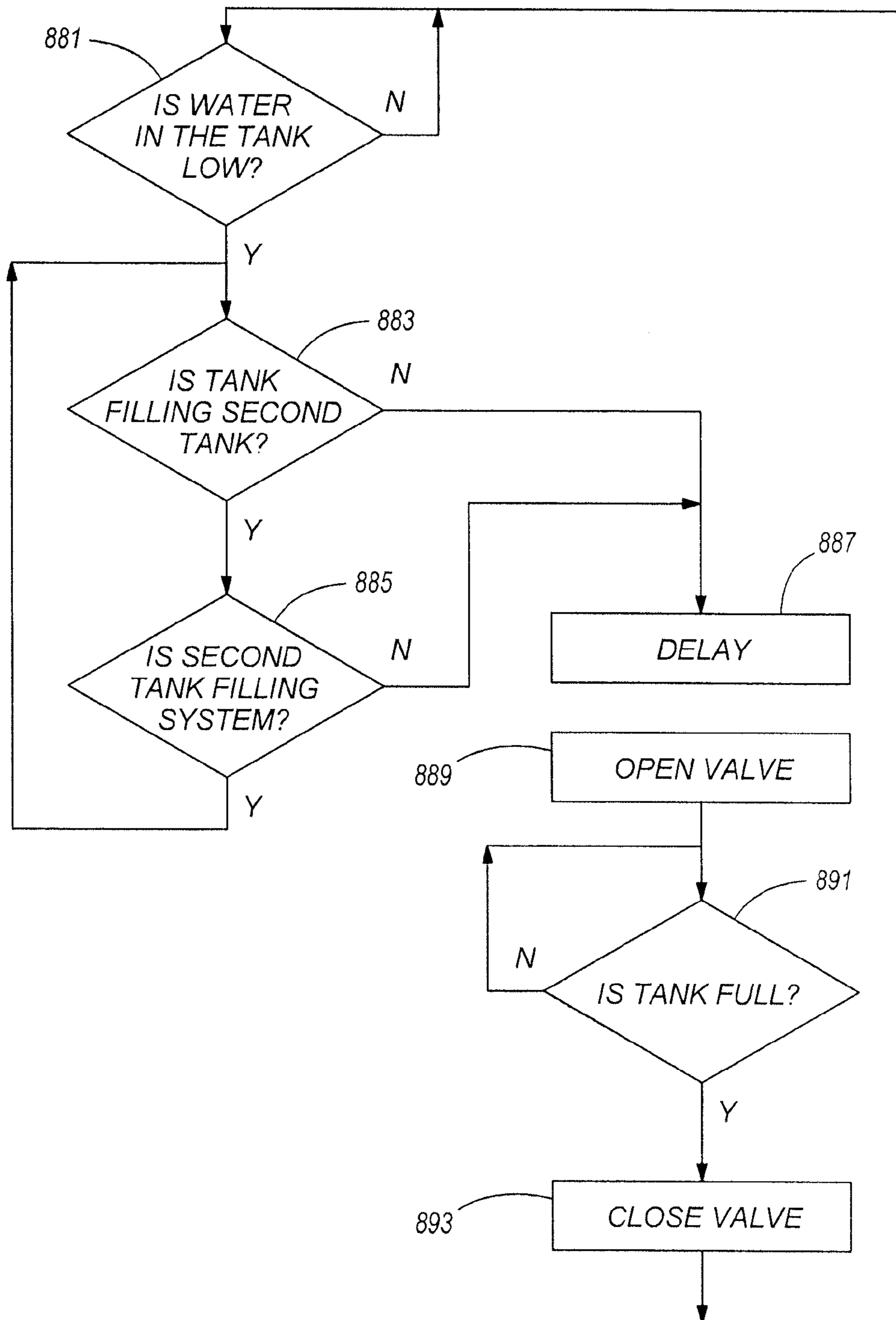
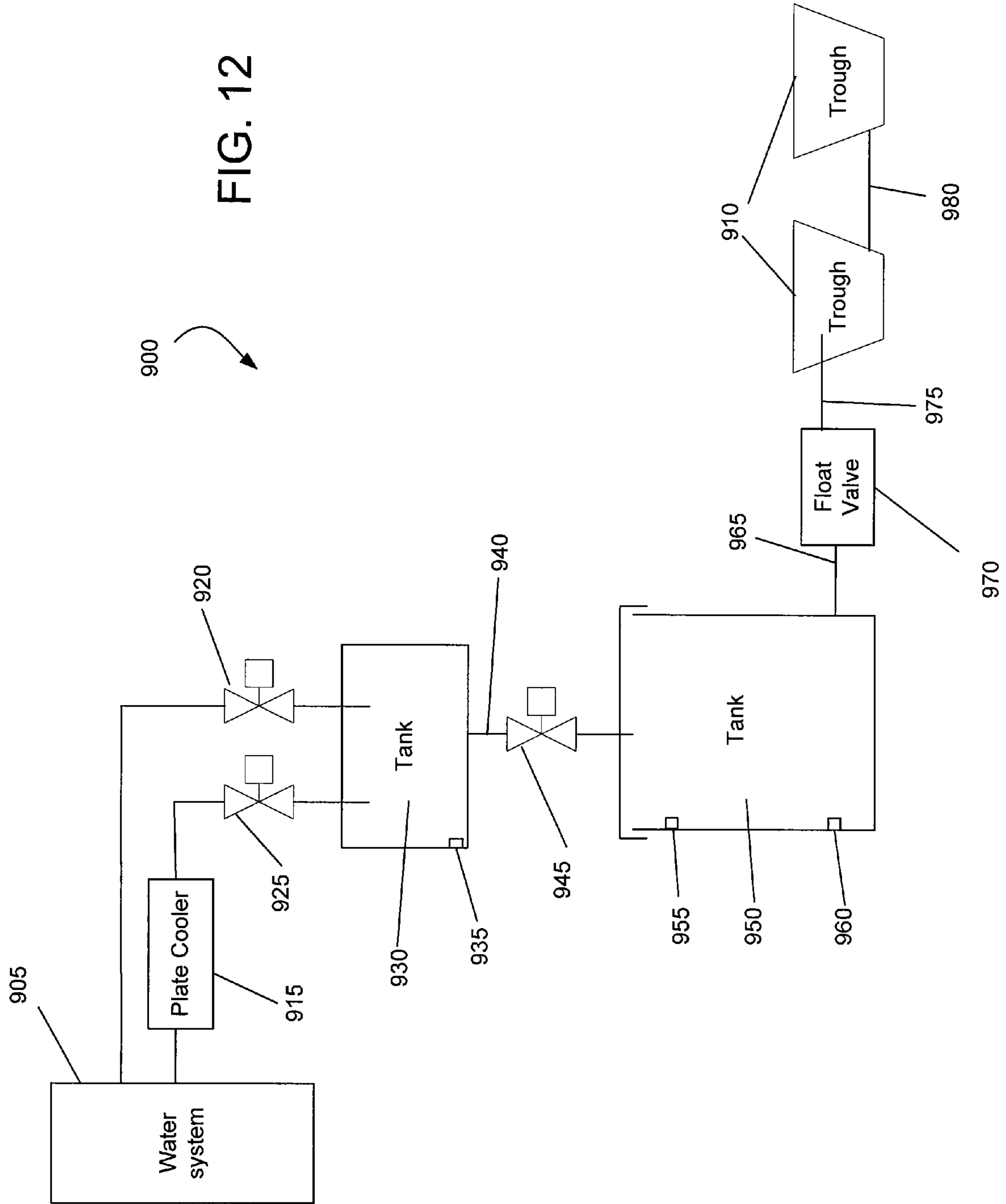


FIG. 11



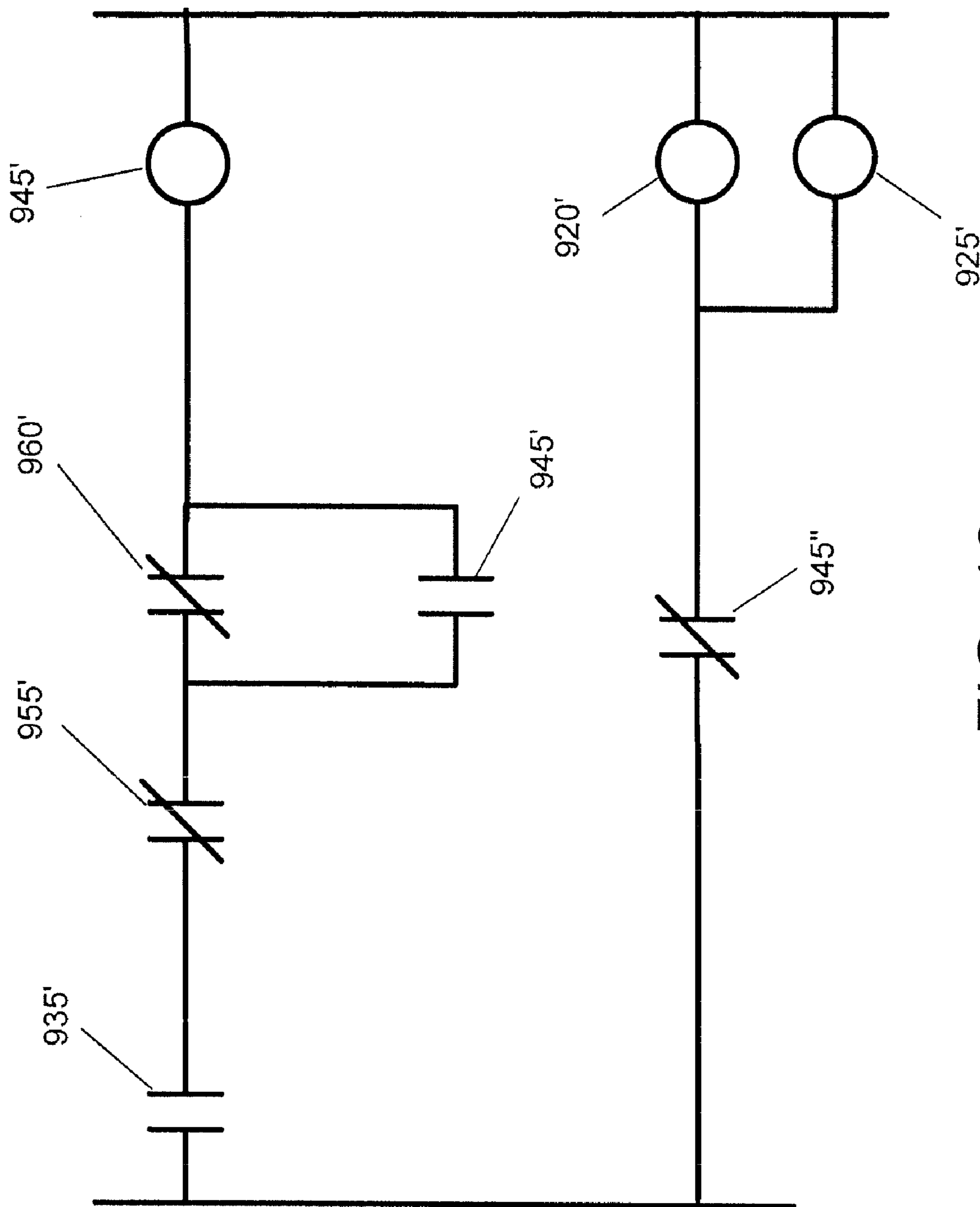


FIG. 13

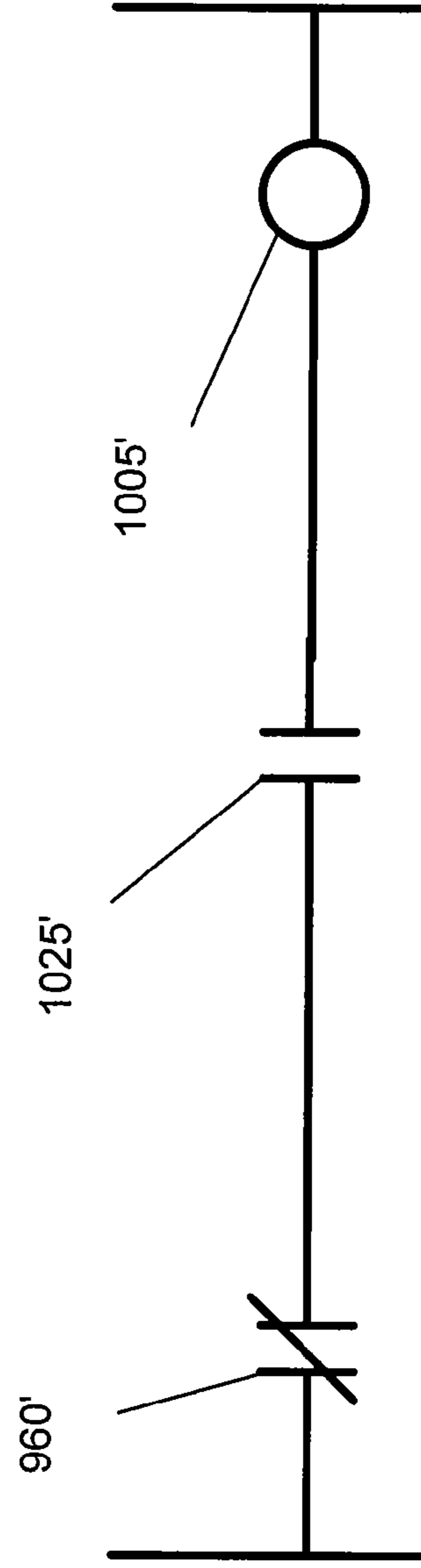
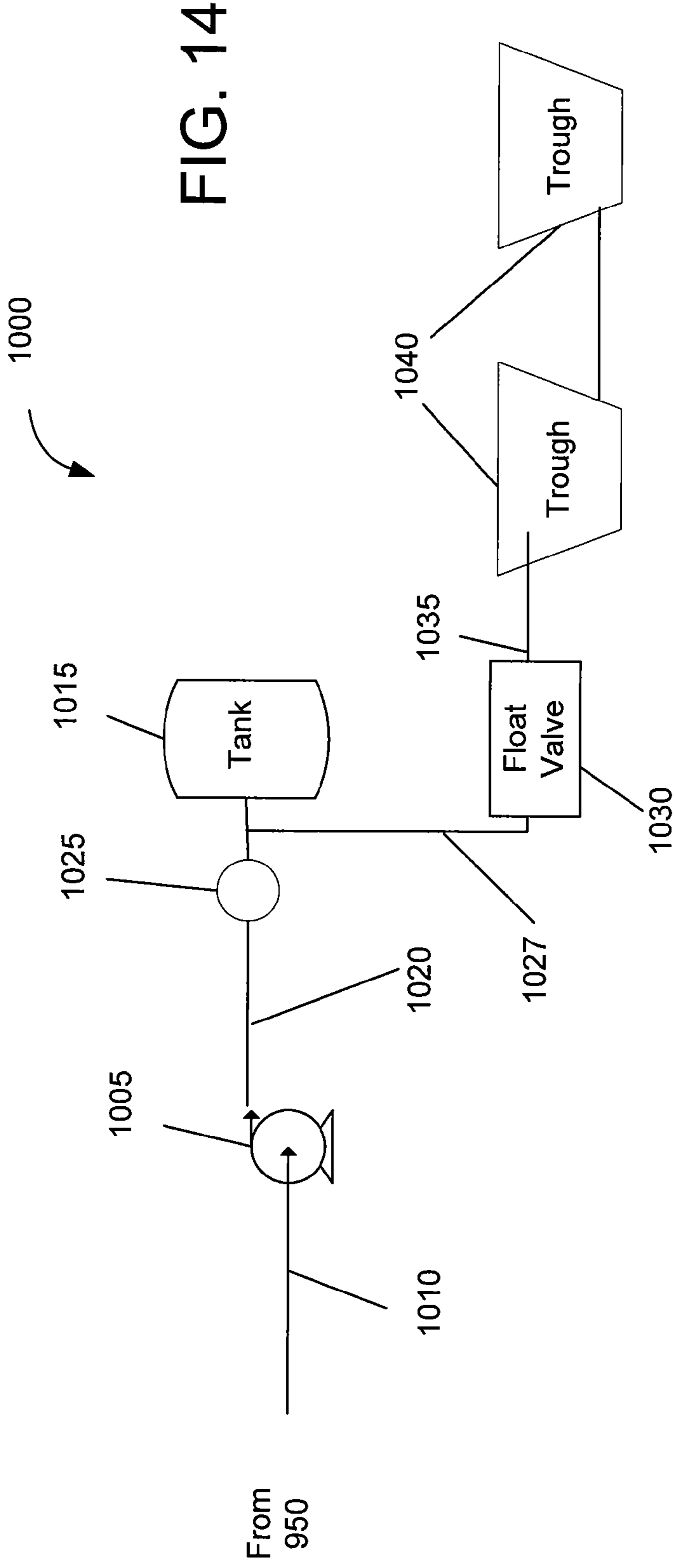


FIG. 15

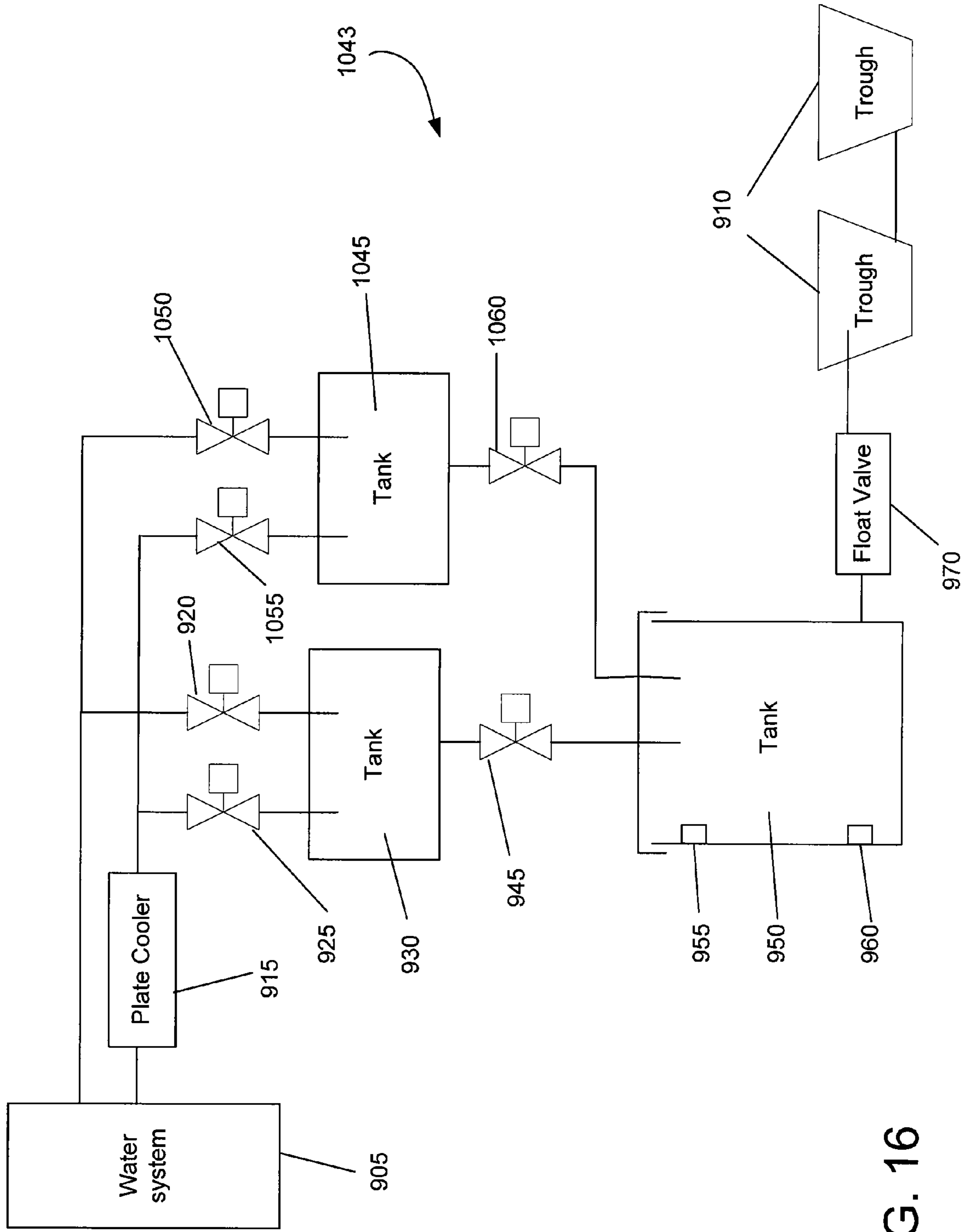


FIG. 16

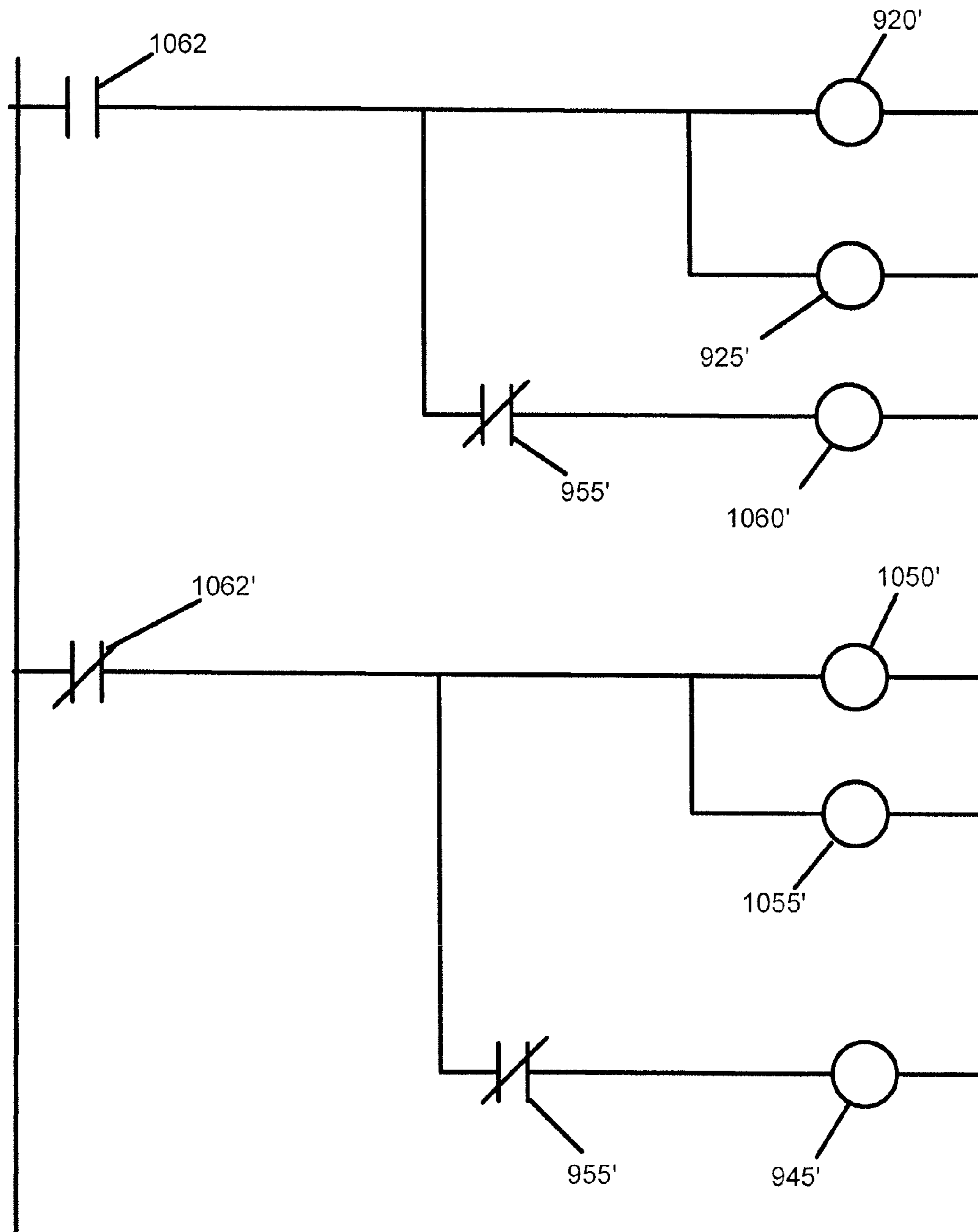


FIG. 17

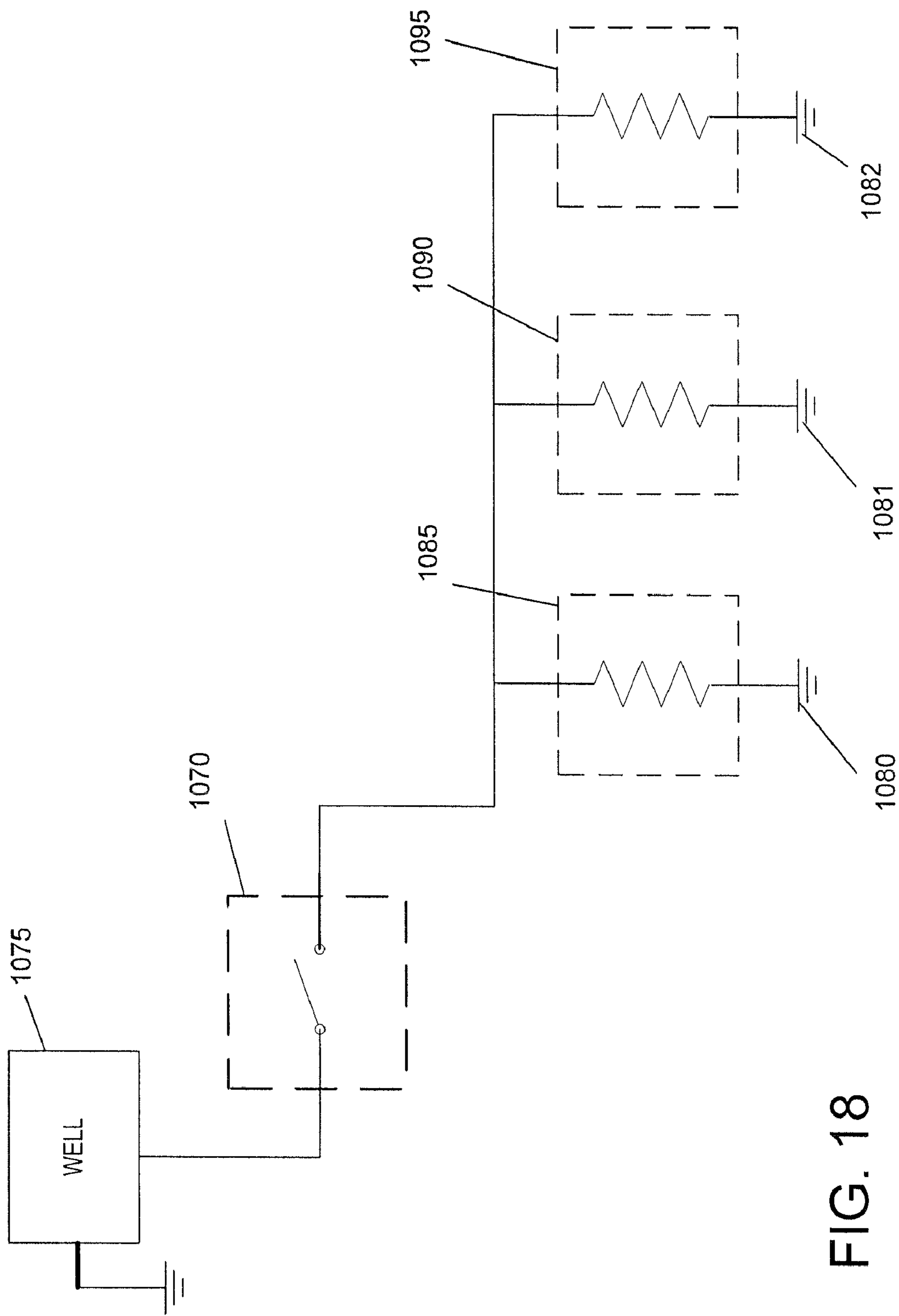


FIG. 18

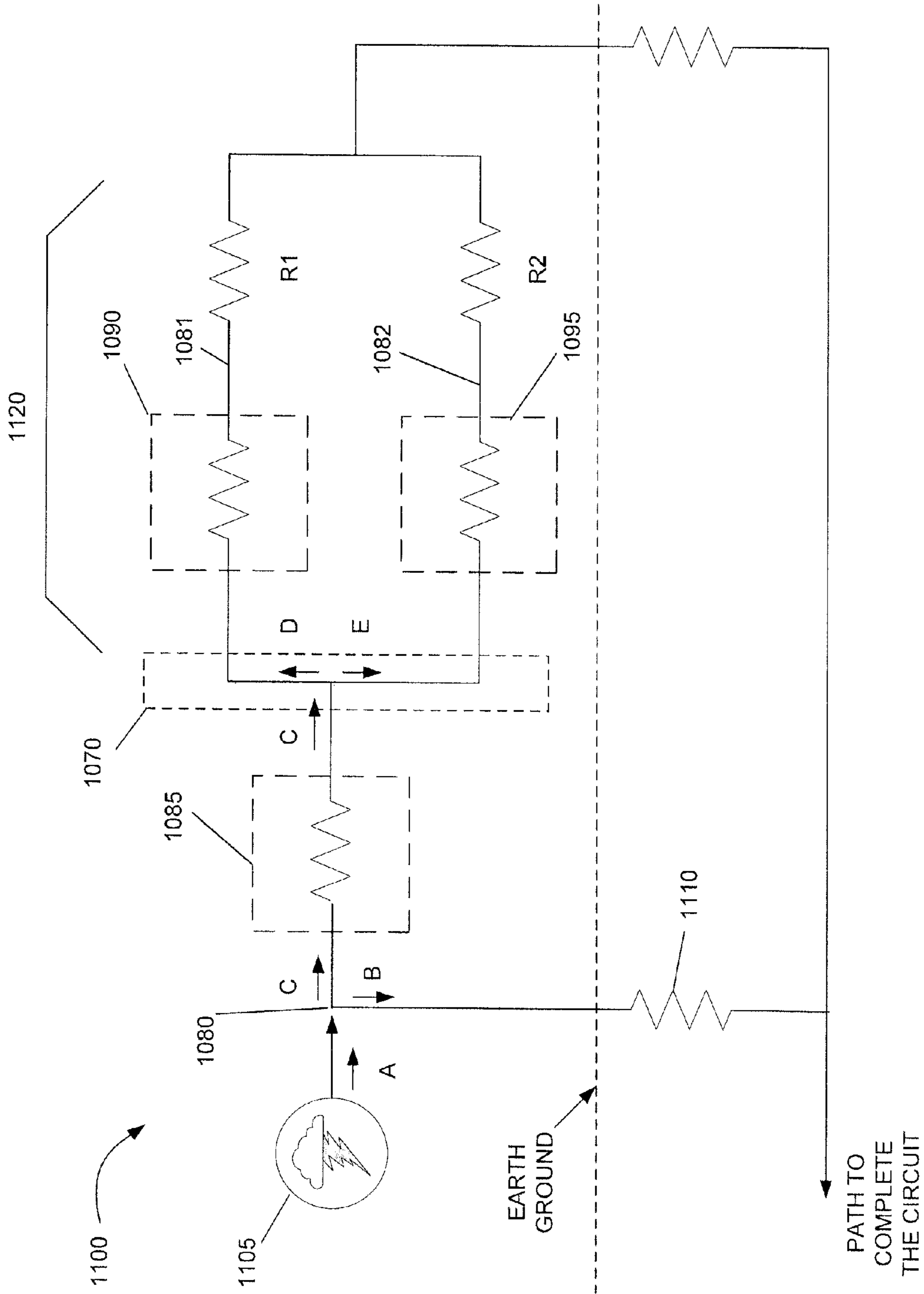
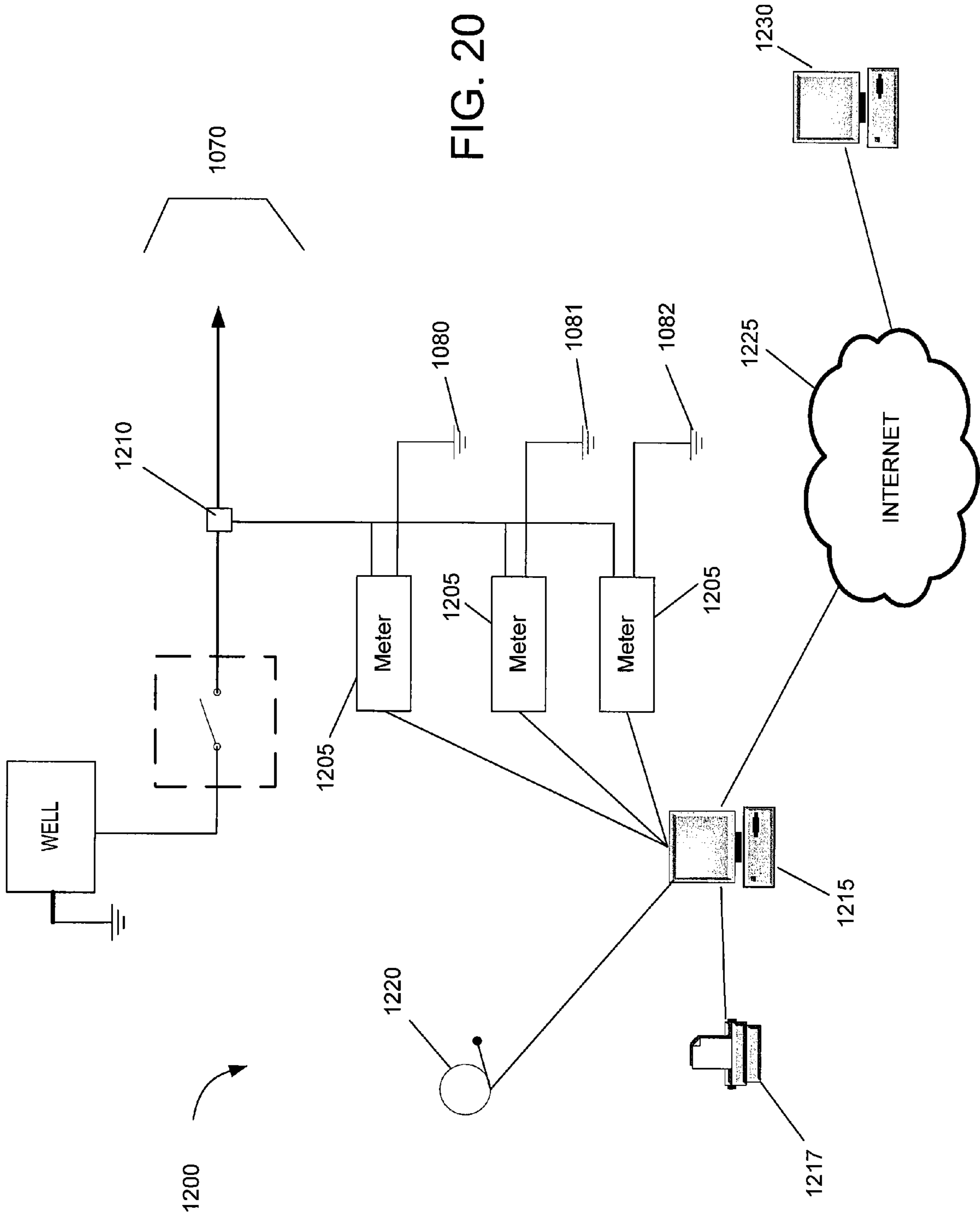


FIG. 19



METHOD AND SYSTEM FOR DETECTING AND ISOLATING STRAY VOLTAGE

RELATED APPLICATIONS

This application is a continuation-in-part of U.S. patent application Ser. No. 11/193,206 filed Jul. 29, 2005, the entire contents of which are incorporated herein by reference.

BACKGROUND

Stray voltage is a difference in electrical potential or a voltage that exists outside of an electrical delivery system. One form of stray voltage is neutral-to-earth (“NE”) voltage. NE voltage is an electrical potential or voltage between the neutral of an electrical delivery system and an earth ground. NE voltages may be created as a consequence of the architecture of an electric power distribution system. In general, electric power is distributed from a generation site to a number of substations. In one relatively common distribution path, high voltage electricity from a substation is delivered to a line transformer located at a facility that consumes electricity, such as a home, business, or farm. As the distance from the line transformer to the substation increases, an electrical potential between the primary neutral of the line transformer and earth ground increases. The National Electrical Safety Code (“NESC”) specifies that utilities connect the neutral on the primary side of a facility’s step down transformer to the neutral on the secondary side of the transformer. The purpose of this is to prevent excessively dangerous voltage levels in the event of an open circuit on the primary neutral. However, this recommended connection can cause a situation where the difference in potential of the primary neutral to earth ground is passed to the secondary neutral. The difference in potential can reach a relatively significant level, such as twenty volts.

Another form of stray voltage is an electrical potential that exists between two points susceptible to contact simultaneously by an animal. For example, some electrical distribution systems are designed to utilize the earth as a return path for current to the substation. More specifically, the earth is used as a current return in parallel to the primary neutral. Differences in the impedance of soils may result in differences in electrical potential between two points of earth ground or the earth ground and the electrical system neutral. Thus, it is possible that an animal may simultaneously contact points that have different potentials resulting in current traveling through the animal’s body.

The Public Service Commission of Wisconsin has developed a protocol for determining if stray voltage exists on a facility such as a dairy farm. The protocol includes four main tests:

- Primary neutral to a remote ground rod voltage
- Main service panel neutral to a remote ground rod voltage
- Voltage drop in the neutral wire between the primary transformer and the main service panel
- Cow contact voltage (obtained by measuring the voltage drop across a 500 ohm resistor shunted between two potential contact points, e.g., a drinking cup and a barn floor)

The tests are conducted for 24 to 48 hours and the results analyzed to determine if stray voltage, or the potential for stray voltage, exists at the facility.

SUMMARY

Stray voltages can have numerous effects including, as noted, causing current to travel through an animal. Although

relatively high voltages can cause shocks, stray voltages generally do not reach a level sufficient to cause an electrical shock. Nonetheless, such currents caused by stray voltage can cause discomfort. For example, it is possible for a stray current to travel through a floor of a livestock barn through the body of an animal to reach the metal structure of the barn, and its grounding connection network.

Although stray voltage is known to exist, and at least one protocol exists for detecting it, there are numerous problems surrounding stray voltage that have not been fully addressed. For example, the protocol noted above for detecting stray voltage cannot identify events that occur outside of the testing period nor can they identify all of the potential locations of “cow contact voltage.”

In addition, although stray currents may travel through the structure of a building, the inventor has also learned that stray voltage may cause electricity to flow through the plumbing of a water delivery system. When wiring a farm, the National Electrical Code (“NEC”) requires that the secondary neutral of the line transformer mentioned above be hard wired to the buildings, the water system, and an electrical ground rod. In addition, NEC and NESC require that all wells be grounded and that secondary neutrals be connected to a building’s water system. However, in many areas a certain amount of current will flow to water wells from the primary neutral. Areas that are susceptible to this kind of current include areas where maintenance of power lines is poor, the distance from the utility substation is large, or the conductivity of the soil is poor. In addition, areas that have experienced growth in electrical load and development of wells are also susceptible. Therefore, a water delivery system, that is not electrically isolated from points in the system connected to the secondary neutral, has the ability to cause current to flow through animals that contact earth ground and the water system.

Stray current can cause a variety of affects in animals. For example, the discomfort experienced by an animal may cause it to avoid the area of a building where the current is experienced. If a stray current is caused when drinking from a water delivery system, an animal may avoid drinking or drink less. The affects can vary with the particular species of animal experiencing the stray current. For example, cows are sensitive to very low voltage levels, as low as 0.5 volt. In the presence of stray current, various observations have been made. Some cows refuse to be milked, refuse to enter a barn, or kick a milker. In some situations, it may be possible for a cow to experience mastitis, reproductive problems, and problems associated with somatic cell count.

Similar problems have also been encountered in pigs. In addition, it is believed that stray currents have caused diarrhea, constipation, and an increase in piglet mortality.

Therefore there exists a need to find and eliminate sources of stray currents and to protect animals from incidences of stray current that are not or cannot be eliminated.

One embodiment of the invention provides a liquid delivery system for providing a liquid that is electrically isolated from a liquid source. The liquid delivery system includes a first storage tank, a second storage tank constructed of one or more non-electrically conductive materials, a first inlet valve configured to control a flow of liquid from the liquid source into the first storage tank, a liquid delivery control device configured to control a flow of liquid from the first storage tank into the second storage tank and a control system configured to control the first inlet valve and the liquid delivery control device. The first inlet valve is further configured to create an electrical open between the liquid source and the first storage tank when the first inlet valve is closed. The liquid delivery control device is further configured to create an

electrical open between the first storage tank and the second storage tank when the liquid delivery control device is not providing the liquid to the second storage tank. The controller ensures that the first inlet valve is closed when the liquid delivery control device is providing liquid to the second storage tank.

Another embodiment provides a method of delivering a liquid that is electrically isolated from a liquid source to a delivery system. The system includes an inlet valve, a liquid delivery control device, a first storage tank, a second storage tank, and a controller. The method includes providing a liquid from the liquid source to the inlet valve, opening the inlet valve, providing the liquid from the inlet valve to the first storage tank, providing the liquid from a lower portion of the first storage tank to the outlet valve, determining that a level of liquid in the second storage tank is less than a first threshold, closing the inlet valve, maintaining an air gap between the inlet valve and the first storage tank when the inlet valve is closed, operating the liquid delivery control device, providing the liquid from the liquid delivery control device to the second storage tank, determining that the level of liquid in the second storage tank exceeds a second threshold, ceasing operation of the liquid delivery control device, and maintaining an air gap between the liquid delivery control device and the second storage tank when the liquid delivery control device is not operating.

Another embodiment provides a system for detecting and locating a source of unwanted electrical events including a water delivery system electrically isolated from an electrical transmission system of an electric utility, a first test-point electrically connected to the water delivery system and a plurality of locations, a plurality of second test-points, each of the second test points located at an earth ground at one of the plurality of locations, at least one meter, the at least one meter configured to measure an electrical characteristic between the first test-point and one of the second test-points, and a recording device configured to receive and record the measured electrical characteristic from the at least one meter.

Another embodiment provides a method of detecting stray current and determining the source of the stray current at a facility. The facility includes a water delivery system electrically isolated from an electrical transmission system of an electric utility, a first test-point electrically connected to the water delivery system and a plurality of locations, a plurality of second test-points, each of the second test points located at an earth ground at one of the plurality of locations, at least one meter, and a recording device. The method includes measuring an electrical characteristic with the at least one meter between the first test-point and the plurality of second test-points, recording the measured electrical characteristic, charting the electrical characteristic against time, determining an event has occurred, and determining a location where the event occurred.

While the embodiments of the invention described herein relate to animal containment facilities, embodiments could be used in other locations or facilities where there is a desire to electrically isolate a liquid delivery system from its source. Such applications may include hospital water delivery systems, spray painting systems, swimming pools, water parks, machining systems, semiconductor manufacturing, fiberglass manufacturing, and others.

Additional details and additional features and aspects of embodiments of the invention are described below.

BRIEF DESCRIPTION OF THE DRAWINGS

In the drawings:

FIG. 1 is an exemplary illustration of a detection device to determine if stray voltage is present in a facility.

FIG. 2 illustrates a circuit that may be formed by the detection device of FIG. 1.

FIG. 3A illustrates another circuit that may be formed by the detection device of FIG. 1.

FIG. 3B illustrates another circuit that may be formed by the detection device of FIG. 1.

FIG. 4 is an exemplary illustration of a detection device to determine if a time varying stray voltage is present in a facility.

FIG. 5A is an exemplary illustration of a first embodiment of a water delivery system to reduce stray voltage.

FIG. 5B is an exemplary illustration of a second embodiment of a water delivery system to reduce stray voltage.

FIG. 6 is an exemplary illustration of a control system for the water delivery system of FIG. 5.

FIG. 7A is an exemplary illustration of a third embodiment of a water delivery system to reduce stray voltage.

FIG. 7B is an exemplary illustration of a fourth embodiment of a water delivery system to reduce stray voltage.

FIG. 8 is an illustration of a process to supply water using the water delivery system of FIGS. 5A and 5B.

FIG. 9 is an illustration of a process for filling the storage tanks of FIGS. 5A and 5B.

FIG. 10 is an illustration of a process to supply water using the water delivery system of FIGS. 7A and 7B.

FIG. 11 is an illustration of a process for filling a storage tank of FIGS. 7A and 7B.

FIG. 12 is an exemplary illustration of an embodiment of a drinking water delivery system to isolate the drinking water from a water source.

FIG. 13 is a ladder diagram representation of an embodiment of the operation of the drinking water delivery system of FIG. 12.

FIG. 14 is an exemplary illustration of another embodiment of the delivery system for the drinking water delivery system of FIG. 12.

FIG. 15 is a ladder diagram representation of an embodiment of the operation of the delivery system of FIG. 14.

FIG. 16 is an exemplary illustration of another embodiment of a drinking water delivery system to isolate the drinking water from a water source.

FIG. 17 is a ladder diagram representation of an embodiment of the operation of the drinking water delivery system of FIG. 16.

FIG. 18 is a schematic illustration of a possible electrical relationship between a water delivery system and a plurality of earth grounds.

FIG. 19 is a schematic illustration of a possible stray current circuit.

FIG. 20 is an exemplary illustration of an embodiment of a stray current monitoring system.

DETAILED DESCRIPTION

Before embodiments of the invention are explained in detail, it is to be understood that the invention is not limited in its application to the details of the examples set forth in the following description or illustrated in the drawings. The invention is capable of other embodiments and of being practiced or carried out in a variety of applications and in various ways.

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FIG. 1 shows an embodiment of a detection device 20 to determine if stray voltage is present in a facility. In the embodiment shown, a 25 gallon non-conductive vessel or bucket 22, having a rim 23, sits on a non-galvanic conductive plate 24 (e.g., a one foot square copper plate). The conductive plate 24 has a 14 American wire gauge (“awg”) conductive lead 26 attached to it. The bucket is filled with water 28 and a second plate 30 (such as a copper plate or electrode) is suspended below the top surface of the water 28. The second plate 30 may be fixed to a float or other mechanism to maintain the plate 30 a predetermined distance below the surface of the water 28, such as 6". A 14 awg conductive lead 32 is attached to the plate 30. An electrical measuring device or meter 34, such as a direct current (“DC”) milliammeter, a voltmeter, or an alternating current (“AC”) meter, is attached between the two leads 26 and 32 to measure an electrical characteristic, such as current. When an animal 36 drinks from bucket 22, meter 34 measures a chosen electrical characteristic (e.g., current or voltage).

A camera 38 captures an image or images in a field of view (“FOV”) that may encompass the bucket 22 and animal 36 and transmits that image via cable 40 to a recording device 42 (e.g., a video cassette recorder). The recording device 42 records the images transmitted by the camera 38. The recording device 42 may deliver the images received from camera 38 via a cable 44 to a display device 46 (e.g., a television) or play back an image previously saved, transmitting a signal of the saved images to the display device 46.

Information from the meter 34 and the camera 38 can be used to determine the presence of stray voltage and the stray current or currents such voltage causes. For example, if a stray voltage is present, animals may avoid drinking from the bucket 22. In addition, the animals may exhibit other signs of discomfort, such as retracting their heads, when first contacting the water in bucket 22. This behavior is captured by the camera 38. Meter 34 may also be placed in the FOV and an image from the meter can be captured by the camera 38. When the meter indicates the presence of a stray voltage or current and discomfort or other behavior is observed in the images recorded by the camera and these phenomena happen at the same time, it can be assumed that an undesirable stray voltage situation exists. Of course, the presence of just one of these phenomena may be sufficient to determine that a stray voltage situation exists.

Other embodiments allow for meter 34 to be coupled directly to recording device 42. Readings from meter 34 could be indicated on, and correlated to, images of the animal’s reactions captured by the camera 38.

In still other embodiments, multiple cameras 38 can be configured such that the FOV of each camera 38 captures images of different components of the system (e.g., the meter 34 and the cow 36). The signals from the cameras 38 can then be multiplexed together and simultaneously recorded and/or viewed.

FIG. 2 illustrates a circuit 51 created by an animal 36 drinking from bucket 22. Resistors 1-4 represent legs of the animal 36. Each leg presents some impedance to electrical current and is represented as a resistor. The animal 36 stands on the ground with all four feet or hooves contacting the ground. Therefore, each resistor, R1-R4, is connected to earth ground. R5 represents the impedance to electrical current supplied by the body of the animal 36. R1-R4, R5, and meter 34 are part of a circuit 51. A switch (SW1) represents the break in the circuit 51 that exists when the animal 36 is not drinking from the bucket 22. When the animal 36 drinks from bucket 22, the circuit 51 is completed, which is represented by closure of the switch (SW1). In the absence of stray voltage,

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the electrical potential of grounds 52-56 are all the same and no electrical current flows through the circuit 51.

However, in the presence of stray voltage, an electrical potential between two or more of the earth grounds 52-56 may exist. FIGS. 3A and 3B represent two possible embodiments of stray voltage. In FIG. 3A, animal 36 is in contact with grounds 52-55 that are at a higher electrical potential than ground 56 under bucket 22. When the animal 36 drinks from bucket 22 (which in the model is represented as closing switch SW1), the electrical potential enables electrical current to flow from grounds 52-55 through the animal 36 to ground 55.

In FIG. 3B, animal 36 is in contact with grounds 52-55 that are at a lower electrical potential than ground 56 under bucket 22. When animal 36 drinks from bucket 22, the electrical potential enables electrical current to flow from ground 56 through the animal 36 to grounds 52-55.

In another embodiment, shown in FIG. 4, detection device 20 determines the presence of stray AC electricity. An optional resistor (R6) may be connected between lead 26 and lead 32. An oscilloscope 60 monitors the voltage across leads 26 and 32. When animal 36 is not drinking from the bucket, an open circuit condition exists. When animal 36 drinks from bucket 22, a closed circuit condition exists. If an electrical potential exists between earth ground 56 and one or more of the four grounds 52-55 under the hooves of animal 36, as illustrated in FIGS. 3A and 3B, the oscilloscope displays a waveform that represents a portion of the potential. If the electrical potential has an AC or time-varying component, the oscilloscope displays a sine wave or other time varying wave of a magnitude indicative of the magnitude of the AC component of the electrical potential. A cow is generally accepted to have a total impedance of approximately 200Ω. Therefore, if animal 36 is a cow, the magnitude of the signal displayed on the oscilloscope will be approximately 70% of the actual electrical potential.

FIG. 5A illustrates a water system 61 that is configured to reduce stray voltage affects on animals that drink from it. The system 61 could be implemented, for example, after testing a farm or other facility with the system 20 for the presence of stray voltage or current. The system 61 is configured such that a well 100 is electrically isolated from a portion of a water delivery system that animals can contact such as a water trough 102. Of course, the water could be delivered to a number of troughs or different delivery devices, such as sinks, tubs, and other plumbing fixtures. All electrical conductors (which include any conductive pipes, tanks, etc., that are included in the water delivery system 61) between the grounded well 100, and a secondary neutral of the electrical distribution system (not shown), are electrically isolated from the water trough 102.

The delivery containment devices and the water being supplied from a well 100 are electrically isolated in the system 61. The system 61 includes one or more wells (referred to as well 100) and its associated devices, such as a pump and power supply for the pump (not shown). Well 100 delivers water through pipe 105 which is connected to a pressure switch 110. When pressure above a predetermined threshold is detected by pressure switch 110, the pressure switch 110 opens an internal switch removing power to the pump of well 100.

Water exits the pressure switch 110 through pipe 115 and enters filter 120. The filter removes certain contaminants such as sediment contained in the water. Water then flows through pipe 125 into a Y-fitting or similar device 130 that divides the water into two paths. The first path flows through pipe 135 and into a first valve 140. The second path can flow through pipe

145. An optional Y-fitting or similar device 150 may be connected to the pipe 145 to again divide the water into two paths. The first path flows into a pipe 155 which feeds a second valve 160. The second path flows into an optional, manual bypass system 162. If desired, the bypass system 162 provides a mechanism to ensure the flow of water to the trough 102 in the event of a failure in other parts of the system 61.

When the first valve 140 is opened, water flows into a first storage tank 165. When the second valve 160 is opened, water flows into a second storage tank 170. When the first valve 140 is closed, an air gap exists between the water from the well 100 and water in the first storage tank 165. This air gap acts as an electrical isolator isolating the water in the first storage tank 165 from the well 100. When the second valve 160 is closed, an air gap exists between the water from the well 100 and water in the second storage tank 170. This air gap also acts as an electrical isolator isolating the water in the second storage tank 170 from the well 100.

A first sensor 175 detects when the water has reached a high level in the first storage tank 165. A second sensor 180 detects when the water has reached a low level in the first storage tank 165. A third sensor 185 detects when the water has reached a high level in the second storage tank 170. A fourth sensor 190 detects when the water has reached a low level in the second storage tank 170. Water flows out of the first storage tank 165 via pipe 195 and into a third valve 200. The third valve 200 is constructed from non-conductive materials and is actuated non-electrically (e.g., by air). Water flows out of the second storage tank 170 via pipe 205 and into a fourth valve 210. The valve 210 is constructed from non-conductive materials and is actuated non-electrically (e.g., by air). A booster pump 215 is fed from the third valve 200 via pipe 220 or from the fourth valve 210 via pipe 225.

Because of its construction, the third valve 200 provides an electrical open, when it is closed, that electrically isolates water in the booster pump 215 from water in the first storage tank 165. This provides electrical isolation between the booster pump 215 and the well 100 when the first storage tank 165 is filling and no air gap exists to isolate the first storage tank 165 from the well 100. Similarly, the fourth valve 210, because of its construction, provides an electrical open, when it is closed, that electrically isolates water in the booster pump 215 from water in the second storage tank 170. This provides electrical isolation between the booster pump 215 and the well 100 when the second storage tank 170 is filling and no air gap exists to isolate the second storage tank 170 from the well 100.

Water flows from the booster pump 215 through pipe 230. Pipe 230 is connected to a Y-fitting or similar device 235 which feeds pipe 240. Pipe 240 is connected to a pressure tank 245 which couples to a pipe 246. Pipe 246 feeds a low voltage pressure switch 247. When pressure above a predetermined threshold is detected by pressure switch 247, the pressure switch 247 opens an internal switch removing power to the booster pump 215. Water exits the pressure switch 247 through pipe 248 and enters filter 249 which filters the water and delivers it to pipe 250. Water flows through pipe 250 to trough 102. A float switch 255 resides in trough 102 to indicate when the water level in trough 102 exceeds a predetermined depth.

An alternative embodiment of the water delivery system 61 is illustrated in FIG. 5B. The system is the same as that shown in FIG. 5A, except water flows from pipe 250 into a pressurized delivery system 270. The low voltage pressure switch 247 detects when the water pressure in the pressurized delivery system 270 drops below a pre-determined threshold.

The manual bypass system 162 (FIGS. 5A and 5B) can be configured to supply water to the trough 102 or the pressurized delivery system 270 in the event the water system 61 is unable to do so. A pipe 275 receives water from Y-fitting 150 and is connected to a manually operated valve 280 which is constructed from non-conductive materials. Valve 280 is connected to pipe 285 which delivers water to Y-fitting 235 and the rest of the system. The use of non-conductive materials in valve 280 maintains the electrical isolation of the water system 61 when the valve 280 is closed.

A section of pipe 125 can be constructed of electrically conductive material (e.g., copper). In the presence of stray voltage on the well 100 system, measuring an electrical characteristic (e.g., voltage) between this conductive section of pipe 125 and ground reflects the level of stray voltage present. Additionally, a section of pipe 240 can be constructed of electrically conductive material (e.g., copper). If the system is operating correctly and electrical isolation between well 100 and the output of water system 61 is achieved, measuring an electrical characteristic (e.g., voltage) between this conductive section of pipe 240 and ground will indicate that stray voltage does not exist at this point in the water delivery system 61, even if such a characteristic exists between the conductive section of pipe 125 and ground.

Certain valves used throughout the water distribution system 61 may be non-electrically-actuated to further isolate the water delivery system 61 from the electrical distribution system. For example, pneumatic or air-actuated valves may be used.

In addition, pipes used throughout the water delivery system 61 may be made of non-conductive materials. Materials suitable for use in the pipes include plastics such as polyvinylchloride ("PVC"), ceramics, and other materials.

Operation of the water delivery system 61 can be controlled by a programmable logic controller ("PLC") 300 (FIG. 6) such as an Allen-Bradley Micrologix 1200. The PLC 300 receives input signals from the high level indicator 175 for the first storage tank 165. The PLC 300 also receives signals from the low level indicator 180 for first storage tank 165, the high level indicator 185 for second storage tank 170, the low level indicator 190 for second storage tank 170, and float switch 255 (or the low voltage pressure switch 247 in the alternative embodiment of FIG. 5B). Based on the states of the inputs it receives, the PLC 300 determines which devices in the water delivery system 61 to energize and which to de-energize.

Devices controlled by the PLC 300 include the booster pump 215, and a set of valves 305-330 (which in one embodiment are pneumatic valves). The valves 305-330 open and close the valves 140, 160, 200, and 210 (which in one embodiment are also pneumatic valves) of the water delivery system 61. Valves 305-330 are connected to compressor 340 which maintains pressure, such as 40 pounds per square inch ("psi"), in air line 345. The valve 305 is energized by a signal from the PLC 300 delivered from an output 350. When the PLC 300 generates an appropriate signal, the valve 305 opens. This causes air pressure in air line 355 to rise to 40 psi or some other pressure sufficient to activate the valves. The rise in pressure causes valve 140 to open. When valve 305 is de-energized, it closes. When the valve 305 closes, air pressure in air line 355 returns to zero, causing valve 140 to close. When valve 315 is energized, it opens. This causes air pressure in air line 365 to rise (e.g., to 40 psi). The rise in pressure causes valve 160 to open. When pneumatic valve 320 is de-energized it closes, and air pressure in air line 365 returns to zero. Valve 160 then closes. Valve 320 operates in a similar manner.

When valve **320** is energized by the PLC **300**, air pressure in air line **375** rises (e.g., to 40 psi). This causes valve **200** to open. When the valve **320** is de-energized, it closes. This causes air pressure in air line **375** to return to zero, causing air-actuated valve **200** to close. Valve **210** operates in a similar manner, opening and closing in accordance with commands received from the PLC and causing changes in air pressure that affect valve **210**. Since operation of valves **200** and **210** are similar to the other valves discussed above, additional details are not provided.

The PLC **300** controls various components to create electrical isolation between water being delivered from the booster pump **215** and the well **100**. The PLC **300** ensures that an electrical open exists in the water path through the first storage tank **165** by ensuring that valve **140** is closed (creating an air gap) or that valve **200** is closed (isolation created by non-conductive materials). The PLC **300** also ensures that an electrical open exists in the water path through the second storage tank **170** by ensuring that valve **160** is closed (creating an air gap) or that valve **210** is closed (isolation created by non-conductive materials).

FIG. 7A shows another embodiment of a water delivery system **395** that electrically isolates both the delivery containment devices and the water being supplied from one or more wells (referred to as well **100**). The system includes well **100** and its associated devices, such as a pump and power supply for the pump (not shown). Well **100** delivers water through pipe **105** which is connected to a pressure switch **110**. When pressure above a predetermined threshold is detected by pressure switch **110**, the switch **110** opens an internal switch removing power to the pump of well **100**.

Water exits pressure switch **110** through pipe **115** and enters filter **120**. The filter removes certain contaminants such as sediment contained in the water. Water then flows through pipe **400** and into a Y-fitting or similar device **405** that divides the water into two paths. The first path flows into a pipe **410** which feeds a first valve **415**. The second path flows into a manual bypass system **417**.

When the first valve **415** is opened, water flows through pipe **420** into a first storage tank **425**. A first sensor **430** detects when the water has reached a high level in the first storage tank **425**. A second sensor **435** detects when water has reached a low level in the first storage tank **425**. Water flows out of the first storage tank **425** via gravity through pipe **440** and into a second valve **445**. When the second valve **445** is opened, water flows through pipe **450** into a second storage tank **455**. A third sensor **460** detects when the water has reached a high level in the second storage tank **455**. A fourth sensor **465** detects when water has reached a low level in the second storage tank **455**. Water flows out of the second storage tank **455** via gravity through pipe **470** and into a third valve **475**. In certain embodiments, the third valve **475** is air-actuated and constructed from non-conductive materials.

The booster pump **215** is fed from the third valve **475** via pipe **480**. Water flows from the booster pump **215** through pipe **230**. Pipe **230** connects to a Y-fitting or similar device **235** which feeds pipe **240**. Pipe **240** is connected to pressure tank **245** which couples to a pipe **246**. Pipe **246** feeds a low voltage pressure switch **247**. When pressure above a predetermined threshold is detected by pressure switch **247**, the pressure switch **247** opens an internal switch removing power to the booster pump **215**. Water exits the pressure switch **247** through pipe **248** and enters filter **249**. Filtered water leaves filter **249** via pipe **250** and flows into trough **102**. As noted, the float switch **255** resides in trough **102** to indicate when the water level in trough **102** exceeds a predetermined depth.

Like the system **61**, pipes in the water delivery system **395** are made of non-conductive materials and certain valves are non-electrically-actuated (e.g., air-actuated).

An alternative embodiment of the water delivery system **395** is illustrated in FIG. 7B. The system is the same as that shown in FIG. 7A except that water flows from pipe **250** into a pressurized delivery system **270**. The low-voltage pressure switch **247** detects when the water pressure in the pressurized delivery system **270** drops below a pre-determined threshold.

The manual bypass system **417** (FIGS. 7A and 7B) can be configured to supply water to the trough **102** or the pressurized delivery system **270** in the event the water system **395** is unable to do so. A pipe **275** receives water from Y-fitting **405** and is connected to a manually operated valve **280** which is constructed from non-conductive materials. Valve **280** is connected to pipe **285** which delivers water to Y-fitting **235** and the rest of the system. The use of non-conductive materials in valve **280** maintains the electrical isolation of the water system **61** when the valve **280** is closed.

A section of pipe **400** can be constructed of electrically conductive material (e.g., copper). In the presence of stray voltage on the well **100** system, measuring an electrical characteristic (e.g., voltage) between this conductive section of pipe **400** and ground reflects the level of stray voltage present. Additionally, a section of pipe **240** can be constructed of electrically conductive material (e.g., copper). If the system is operating correctly and electrical isolation between well **100** and the output of water system **395** is achieved, measuring an electrical characteristic (e.g., voltage) between this conductive section of pipe **240** and ground will indicate that stray voltage does not exist at this point in the water delivery system **395**, even if such a characteristic exists between the conductive section of pipe **400** and ground.

Like certain other embodiments, certain valves used in the water distribution system **395** are non-electrically-actuated to further isolate the water delivery system **395** from the electrical distribution system. In addition, pipes used throughout the water delivery system **395** are made of non-conductive materials, such as plastics, ceramics, or other materials.

Operation of the System

In the embodiment shown in FIGS. 5A and 5B, electrical isolation of delivery system **61** is achieved, in part, by the use of non-conductive pipes. This creates an open circuit condition between well **100** and water trough **102** (or pressurized delivery system **270**). In addition, utilization of air-actuated, relay-driven, low-voltage devices within the system reduces the possibility of introducing stray voltage from other sources. Electrical isolation of the water is achieved by preventing completion of an electrical circuit in water traveling from well **100** to water trough **102** (or pressurized delivery system **270**). This is accomplished by ensuring that an open circuit condition (e.g., an air gap) exists in the water path between well **100** and the storage tank **165** or **170** that is supplying the water trough **102** (or pressurized delivery system **270**). In addition, non-conductive air-actuated valves **200** and **210** act as electrical opens in the water circuit when they are closed, ensuring an electrical open exists in the circuit when the storage tanks are filling and an air gap does not otherwise exist in the water flowing through the system.

FIG. 8 illustrates the process of sourcing water to trough **102** (or pressurized delivery system **270**) in the water delivery system **61** shown in FIGS. 5A and 5B. The water level in trough **102** (or pressure in pressure delivery system **270**) is checked at step **801** by PLC **300** by determining if float switch **255** (or pressure switch **247**) is engaged. If float switch **255** (or pressure switch **247**) is not engaged, the trough **102** (or

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pressurized delivery system 270) has sufficient water and the process loops back to step 801 to continue checking if the trough 102 (or pressurized delivery system 270) requires additional water. If, at step 801, float switch 255 (or pressure switch 247) is engaged, which indicates that the water level in trough 102 (or pressure in the pressurized delivery system 270) is low, the process of providing water to trough 102 (or pressurized delivery system 270) continues.

At step 803 a determination is made if the first storage tank 165 filled trough 102 (or pressurized delivery system 270) the previous time water was required. If the first storage tank 165 was used to fill trough 102 (or pressurized delivery system 270) the previous time water was required, an attempt to utilize the second storage tank 170 is made. At step 805 second storage tank 170 is checked to determine if it is being filled from well 100. If the second storage tank 170 is not being filled by well 100, the second storage tank 170 is chosen to fill trough 102 (or pressurized delivery system 270). Non-conductive air-actuated valve 210 is opened at step 807. To ensure that an open exists in the water path from well 100 through second storage tank 170, it is necessary to ensure that valve 160 is not open and residual water flow has ceased. A delay, at step 809, accomplishes this. Following the delay at step 809, booster pump 215 is energized at step 811. A predetermined delay to fill trough 102 (or pressurized delivery system 270) is executed at step 813. Once trough 102 (or pressurized delivery system 270) has been filled, booster pump 215 is de-energized at step 815 and valve 210 is closed. Processing continues at step 801 to wait for water in trough 102 (or pressure in pressurized delivery system 270) to reach a low level.

If it is determined that the second storage tank 170 was used to fill trough 102 (or pressurized delivery system 270) the previous time water was required or if the second storage tank 170 is being filled from well 100, it is determined whether the first storage tank 165 is being filled from well 100 at step 819. If the first storage tank 165 is being filled from well 100, processing continues at step 805. If both the first storage tank 165 and the second storage tank 170 are filling from well 100, the first one to finish filling is utilized to fill trough 102 (or pressurized delivery system 270).

If it is determined that the first storage tank 165 is not filling (step 819), the first storage tank 165 is used to fill trough 102 (or pressurized delivery system 270). Valve 200 is opened at step 821. To ensure that an open circuit condition exists in the water path from well 100 through the first storage tank 165, air-actuated valve 140 should be closed and any residual water flow should end. A delay (step 823) is used to ensure that sufficient time has passed to allow valve 140 to close and water flow to stop. Following the delay, booster pump 215 is energized at step 825. A predetermined delay to fill trough 102 (or pressurized delivery system 270) is executed at step 827. Once trough 102 (or pressurized delivery system 270) has been filled, booster pump 215 is de-energized at step 829 and valve 200 is closed. Processing continues at step 801 waiting for water in trough 102 (or pressurized delivery system 270) to reach a low level.

FIG. 9 illustrates the process for filling storage tanks 165 and 170 when their water level reaches a low point. Sensor 180 is checked at step 841 to determine if the water level in the first storage tank 165 has reached a low level. If the water level in the first storage tank 165 is not low, the process loops back to step 841 to continue monitoring the water level.

If the sensor 180 indicates that the water level has reached a low level (step 841), it is determined at step 843 whether first storage tank 165 is filling trough 102 (or pressurized delivery system 270). If first storage tank 165 is filling trough 102 (or

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pressurized delivery system 270), it cannot be filled from well 100 without closing the electrical open in the water loop. Therefore, the process loops at step 843 until trough 102 (or pressurized delivery system 270) has finished filling.

Once the first storage tank 165 is finished filling trough 102 (or pressurized delivery system 270), processing continues at step 845 with a delay. This delay ensures an open circuit condition exists in the water loop by providing sufficient time for residual water flow to end. Once the delay is complete, air-actuated valve 140 is opened at step 847. Water flows into first storage tank 165 from well 100. Sensor 175 is monitored at step 849. Once water reaches a level sufficient for the sensor 175 to detect (step 849), valve 140 is closed (step 851). Processing continues at step 841 by monitoring sensor 180.

For the second storage tank 170, sensor 190 is checked at step 841 to determine if the water level in the second storage tank 170 has reached a low level. If the water level in the second storage tank 170 is not low, the process loops back to step 841 to continue monitoring the water level.

If the sensor 190 indicates that the water level has reached a low level (step 841), it is determined at step 843 whether second storage tank 170 is filling trough 102 (or pressurized delivery system 270). To maintain electrical isolation, storage tank 170 is not filled from the well 100 while the tank 170 is filling through 102 (or pressurized delivery system 270). Therefore, the process loops at step 843 until the trough 102 (or pressurized delivery system 270) has finished filling.

Once the second storage tank 170 is finished filling trough 102 (or pressurized delivery system 270), processing continues at step 845 with a delay. This delay ensures an electrical open exists in the water loop by allowing any residual water flow to end. Once the delay is complete, air-actuated valve 160 is opened at step 847. Water flows into second storage tank 170 from well 100. Sensor 185 is monitored at step 849. Once water reaches a level sufficient for the sensor 185 to detect (step 849), valve 160 is closed (step 851). Processing continues at step 841 by monitoring the sensor 190.

FIG. 10 illustrates an embodiment of a process of sourcing water to trough 102 (or pressurized delivery system 270) in the water delivery system 395 shown in FIGS. 7A and 7B. The water level in trough 102 (or pressure in pressurized delivery system 270) is checked at step 861 by PLC 300 determining if float switch 255 (or pressure switch 247) is engaged. In alternative embodiments, the float switch 255 may be non-electrical. If float switch 255 (or pressure switch 247) is not engaged, trough 102 (or pressurized delivery system 270) has sufficient water and the process loops back to step 861 to continue checking if trough 102 (or pressurized delivery system 270) requires additional water. If, at step 861, the float switch 255 (or pressure switch 247) is engaged, which indicates that the water level in trough 102 (or pressure in pressurized delivery system 270) is low, the process of providing water to trough 102 (or pressurized delivery system 270) continues at step 863.

Second storage tank 455 is checked to determine if it is being filled from the first storage tank 425. If the first storage tank 425 is not filling second storage tank 455, the second storage tank 455 fills trough 102 (or pressurized delivery system 270). Valve 475 is opened at step 865. To ensure that an open circuit condition exists in the water path from well 100 through second storage tank 455, it is necessary to ensure that valve 445 is not open and residual water flow has ceased. A delay, at step 867, accomplishes this. Following the delay at step 867, booster pump 215 is energized at step 869. A predetermined delay to fill trough 102 (or pressurized delivery system 270) is executed at step 871. Once the trough 102 (or pressurized delivery system 270) has been filled, booster pump 215 is de-energized at step 873 and valve 475 is closed.

Processing continues at step **861** to wait for water in trough **102** (or pressure in pressurized delivery system **270**) to reach a low level.

FIG. **11** illustrates the process for filling first storage tank **425** in the water delivery system **395** shown in FIGS. **7A** and **7B**. Sensor **435** is checked at step **881** to determine if the water level in first storage tank **425** has reached a low level. If the water level in first storage tank **425** is not low, the process loops back to step **881** to continue monitoring the water level.

If the sensor **435** indicates that the water level has reached a low level, it is determined at step **883** whether first storage tank **425** is filling the second storage tank **455**. If first storage tank **425** is filling the second storage tank **455**, it is determined at step **885** whether second storage tank **455** is filling trough **102** (or pressurized delivery system **270**). If the first storage tank **425** is filling the second storage tank **455** and the second storage tank **455** is filling trough **102** (or pressurized delivery system **270**), the first storage tank **425** cannot be filled from well **100** without closing the electrical open in the water loop. Therefore, the process loops back to step **883** until either the second storage tank **455** or the trough **102** (or pressurized delivery system **270**) has finished filling.

Once the second storage tank **455** is not filling or trough **102** (or pressurized delivery system **270**) is filled, processing continues at step **887** with a delay. This delay ensures an electrical open exists in the water loop by allowing any residual water flow to end. Once the delay is complete, air-actuated valve **415** is opened at step **889**. Water then flows into first storage tank **425** from well **100**. Sensor **430** is monitored at step **891**. Once water reaches the high level, sensor **430** detects the water at step **891** and valve **415** is closed at step **893**. Processing continues at step **881** by monitoring the sensor **435**.

FIG. **9** illustrates the process for filling second storage tank **455** in the water delivery system **395** shown in FIGS. **7A** and **7B**. Sensor **465** is checked at step **841** to determine if the water level in second storage tank **455** has reached a low level. If the water level in second storage tank **455** is not low, the process loops back to step **841** to continue monitoring the water level.

If the sensor **465** indicates that the water level has reached a low level (step **841**), it is determined at step **843** whether the second storage tank **455** is filling trough **102** (or pressurized delivery system **270**). If the second storage tank **455** is filling trough **102** (or pressurized delivery system **270**) it cannot be filled from well **100** without the possibility of closing the electrical open in the water loop. Therefore, the process loops at step **843** until the trough **102** (or pressurized delivery system **270**) has finished filling.

Once trough **102** (or pressurized delivery system **270**) is filled from the second storage tank **455**, processing continues at step **845** with a delay. This delay ensures an electrical open exists in the water loop by allowing any residual water flow to end. Once the delay is complete, valve **445** is opened at step **847**. Water then flows into second storage tank **455** from the first storage tank **425** via gravity. Sensor **460** is monitored at step **849**. Once water reaches a high level, sensor **460** detects the water at step **849** and valve **445** is closed at step **851**. Processing continues at step **841**, monitoring the sensor **465**.

Because of the way a well must be grounded to meet NEC regulations, wells and associated water delivery systems can be a major transmission mechanism of stray current on a farm or other facility, especially stray current generated by a utility. The embodiments of the water delivery system previously discussed electrically isolate the water delivery system from the well. In addition to stray current transmitted through

grounds, water delivery systems are vulnerable to the introduction of stray current from on-site electrical systems such as electric motors. The links between the water delivery system and various locations at a facility make every location vulnerable to stray current introduced at another location. This stray current can impact animals drinking from the water delivery system in the same way stray current introduced at the well can. Therefore, there exists a need to isolate the animal drinking water from the rest of the water delivery system.

FIG. **12** illustrates an embodiment of a drinking water delivery system **900** that electrically isolates drinking water from a water source **905**, preventing stray current in the water source **905** from reaching the drinking water in one or more drinking tanks or troughs **910**.

The water source **905** can be a pressurized delivery system, or a pump-driven system. In some embodiments, the water source **905** is linked directly to a well. In other embodiments, the water source **905** is an isolated water delivery system such as discussed previously. In the embodiment shown, the water source **905** provides water to a plate cooler **915** and to a first inlet valve **920** (in addition to other locations on the facility). Water flows through the plate cooler **915** and into a second inlet valve **925**. The first and second inlet valves **920** and **925** supply the water to a top portion of a first non-conductive storage tank **930**. In some embodiments, the first tank **930** includes a low-level sensor **935**. An outlet pipe **940** in a lower portion of the first tank **930** allows water to flow out of the first tank **930** and into a liquid delivery control device such as a first outlet valve **945**. The first outlet valve **945** supplies water, via gravity, to a top portion of a second non-conductive storage tank **950**. In some embodiments, a pump can be used in place of the first outlet valve **945** as the liquid delivery control device. The pump can supply water to the second tank **950** when the second tank **950** is located at an elevation higher than an elevation of the first tank **930**.

In the embodiment shown, the second tank **950** includes a high-level sensor **955** and a low-level sensor **960**. A second outlet pipe **965**, manufactured of non-conductive materials, is positioned in a lower portion of the second tank **950** and supplies water from the second tank **950** to a float valve **970**. The float valve **970** is coupled, via a non-conductive pipe **975** to one or more drinking tanks or troughs **910**. The float valve **970** opens when a level of the water in the troughs **910** drops below a predetermined level allowing water to flow into the troughs **910**. In embodiments employing more than one trough **910**, a non-conductive pipe **980** can couple the troughs **910** together and maintain a substantially equal level of water in each trough **910**.

FIG. **13** illustrates a ladder diagram of an embodiment of the operation of the drinking water delivery system **900**. Elements are numbered in the ladder diagram to correspond to their equivalents in FIG. **12**. A normally open contact **935'** is closed when the low-level sensor **935** detects a water level in the first tank **930** above a first predetermined level and is open when the low-level sensor **935** detects the water level in the first tank **930** below the first predetermined level. A normally closed contact **955'** is closed when the high-level sensor **955** detects a water level in the second tank **950** below a second predetermined level and is open when the high-level sensor **955** detects a water level in the second tank **950** above the second predetermined level. A normally closed contact **960'** is closed when the low-level sensor **960** detects a water level in the second tank **950** below a third predetermined level and is open when the low-level sensor **960** detects the water

level in the second tank **950** above the third predetermined level. The third predetermined level is less than the second predetermined level.

A normally closed contact **960'** is closed when the water level in the second tank **950** is below the third predetermined level. Normally closed contact **955'** is also closed when the water level in the second tank **950** is below the third predetermined level indicating that the water level in the second tank **950** is below the second predetermined level. If the water level in the first tank **930** is above the first predetermined level, all three contacts **935'**, **955'**, and **960'** are closed and power is provided to a coil **945'** which opens the first outlet valve **945**. Water flows from the first tank **930** into the second tank **950** when the first outlet valve **945** is open.

Normally closed contact **960'** opens once the water level in the second tank **950** rises above the third predetermined level. A normally open contact **945''** closes and a normally closed contact **945''** opens when power is provided to coil **945'**. Normally open contact **945''** is wired in parallel around normally open contact **960'** and provides a path for power to continue to be provided to coil **945'** after normally closed contact **960'** opens. Water continues to flow from the first tank **930** to the second tank **950** until either the water level in the first tank **930** drops below the first predetermined level or the water level in the second tank **950** rises above the second predetermined level. Normally open contact **935'** opens when the water in the first tank **930** rises above the first predetermined level. Normally closed contact **955'** opens when the water in the second tank **950** rises above the second predetermined level. Either one of these contacts opening removes power from coil **945'** causing the first outlet valve **945** to close (stopping the flow of water from the first tank **930** to the second tank **950**) and normally open contact **945''** to open.

Power is removed from coils **920'** and **925'**, closing the first inlet valve **920** and the second inlet valve **925**, when normally closed contact **945''** opens (i.e., power is provided to coil **945'**). The flow of water from the water source **905** and the plate cooler **915** into the first tank **930** stops when the inlet valves **920** and **925** are closed.

In the embodiment shown, the low-level sensor **935** prevents a situation where the first outlet valve **945** is open and the first tank **930** runs out of water. Without the low-level sensor **935**, the system **900** would remain in this state indefinitely. Other embodiments can prevent the system **900** from remaining in this state indefinitely including using a timer in place of the low-level sensor **935**. The timer can remove power to the coil **945'** following a period of time sufficient to fill the second tank **950** with water from the first tank **930**.

The operation of the embodiment shown ensures that both the first and second inlet valves **920** and **925** are closed when the first outlet valve **945** is open. The first outlet valve **945** is closed when the first and second inlet valves **920** and **925** are open. Therefore, an air gap exists either between the first outlet valve **945** and the water in the second tank **950** or between the first and second inlet valves **920** and **925** and the water in the first tank **930**. The existence of an air gap ensures that an electrical open exists between the water source **905** and the water in the second tank **950**, and between the plate cooler **915** and the water in the second tank **950**. Therefore, the water in the troughs **910** is isolated from the water source **905** and the plate cooler **915**.

FIG. **14** illustrates a delivery system **1000**, which is an alternative to the drinking water delivery system **900**. A pump driven, pressurized delivery system can be used in circumstances where a gravity fed delivery system, as shown in FIG. **12**, is impractical (e.g., due to the elevation of the troughs).

A pump **1005** receives the water from the second tank **950** via a non-conductive pipe **1010**. To prevent the pump **1005** from inducing stray current into the drinking water delivery system **900**, the pump **1005** is electrically isolated from earth ground by mounting the pump **1005** on an insulated surface (e.g., wood) and not grounding the pump **1005**.

The pump **1005** supplies water to a pressure tank **1015**. A low-voltage electro-mechanical pressure switch **1025** monitors the pressure of the water in the pressure tank **1015** and a pipe **1020**. The non-conductive pipe **1020** couples the pressure tank **1015** to a float valve **1030**. The float valve **1030** is coupled, via a non-conductive pipe **1035** to one or more drinking tanks or troughs **1040**. The float valve **1030** opens when a level of the water in the troughs **1040** drops below a predetermined level, allowing water to flow into the troughs **1040**.

FIG. **15** illustrates an exemplary ladder diagram for controlling the pump driven pressurized delivery system **1000**. A normally open contact **1025'** closes when the pressure switch **1025** detects that a pressure in the pressure tank **1015** has dropped below a first threshold, supplying power to a coil **1005'**. The pump **1005** is energized when coil **1005'** receives power and supplies water to the pressure tank **1015**. The pump **1005** continues to run until the pressure switch **1025** detects a pressure in the pressure tank **1015** above a second threshold, the second threshold greater than the first threshold. Since the water in the second tank **950** is electrically isolated from the water source **905** at all times by the air gaps previously discussed, the pump can run independent of the rest of the drinking water delivery system **900**. The low-level sensor **960** detects if the water in the second tank **950** is below a predetermined level. A normally closed contact **960'** opens when the low-level sensor **960** detects that the water level in the second tank **950** is below the third predetermined level removing power from the coil **1005'** which deenergizes the pump **1005**. This prevents the pump **1005** from being destroyed by running when there is no water in the second tank **950**.

In some high volume environments, the first tank **930** may be unable to fill the second tank **950** quickly enough to meet the drinking water needs of the facility or a flow of water from the plate cooler **915** cannot be stopped for a time period sufficient to allow filling of the second tank **950**. FIG. **16** illustrates an embodiment of a drinking water delivery system **1043** designed to operate in such a high volume environment. In the embodiment shown, the drinking water delivery system **900** shown in FIG. **12** is modified by adding a third storage tank **1045**, a third inlet valve **1050**, a fourth inlet valve **1055**, and a second outlet valve **1060**.

The third non-conductive storage tank **1045** is supplied by the water source **905** and/or the plate cooler **915**. The third inlet valve **1050** supplies water from the water source **905** and the fourth inlet valve **1055** supplies water from the plate cooler **915** to a top portion of the third tank **1045**. The second outlet valve **1060** receives water from a bottom portion of the third tank **1045** and supplies the water to the top portion of the second tank **950**.

FIG. **17** illustrates a ladder diagram of an embodiment for operating the drinking water delivery system **1043** shown in FIG. **16**. A timer **1062** having a 50% duty cycle (i.e., on 50% of the time and off 50% of the time) runs at a rate (e.g., one minute) that is less than the time it takes to fill the first tank **930** or the third tank **1045**. The timer **1062** alternates the filling of the first tank **930** and the third tank **1045**.

During a first half of the timer's duty cycle, a normally open contact **1062'** is closed and a normally closed contact **1062''** is open. When normally open contact **1062'** is closed

power is provided to coils **920'** and **925'** opening the first and second inlet valves **920** and **925**. In addition, a normally closed contact **955'** is in series with normally open contact **1062'**. Normally closed contact **955'** is closed when the water level in the second tank **950** is below a second predetermined level. If the normally closed contact **955'** is closed, power is provided to coil **1060'** which opens the second outlet valve **1060** allowing water to flow from the third tank **1045** into the second tank **950**. If the water level in the second tank **950** rises above the second predetermined level, normally closed contact **955'** opens and power is removed from the coil **1060'** which closes the second outlet valve **1060**.

Since normally closed contact **1062'** is open, power is removed from coils **1050'**, **1055'**, and **945'** closing the third and fourth inlet valves **1050** and **1055** and the first outlet valve **945**.

During a second half of the timer's duty cycle, the normally open contact **1062'** is open and the normally closed contact **1062'** is closed. When normally open contact **1062'** is open, power is removed from coils **920'** and **925'** and the first and second inlet valves **920** and **925** are closed. In addition, a normally closed contact **955'** is in series with normally closed contact **1062'**. Normally closed contact **955'** is closed when the water level in the second tank **950** is below a second predetermined level. If the normally closed contact **955'** is closed, power is provided to coil **945'** which opens the first outlet valve **945** allowing water to flow from the first tank **930** into the second tank **950**. If the water level in the second tank **950** rises above the second predetermined level, normally closed contact **955'** opens and power is removed from the coil **945'** which closes the first outlet valve **945**.

Since normally open contact **1062'** is open, power is removed from coils **920'**, **925'**, and **1060'** closing the first and second inlet valves **920** and **925** and the second outlet valve **1060**.

When the first tank **930** is filling, the first outlet valve **945** is closed creating an air gap at the top of the second tank **950** and the second outlet valve **1060** is open filling the second tank **950**. The third and fourth inlet valves **1050** and **1055** are closed creating an air gap at the top of the third tank **1045**. Therefore, the combination of the air gap between the first tank **930** and the second tank **950** and between the water source **905** and the plate cooler **915** and the third tank **1045** electrically isolates the water in the second tank **950** from the water source **905** and the plate cooler **915**. If the high-level sensor **955** in the second tank **950** opens, indicating that the water level in the second tank **950** has reached the high level, the first outlet valve **945** closes and no water is provided to the second tank **950**.

When the third tank **1045** is filling, the second outlet valve **1060** is closed creating an air gap at the top of the second tank **950** and the first outlet valve **945** may be open and filling the second tank **950**. The first and second inlet valves **920** and **925** are closed creating an air gap at the top of the first tank **930**. If the high-level sensor **955** opens, indicating that the water level in the second tank **950** has reached the high level, the second outlet valve **1060** is closed and no water is provided to the second tank **950**.

Alternative embodiments can rely on other methods of controlling the delivery of water to the second tank **950** and the creation of air gaps to provide electrical isolation. Some of these embodiments include, but are not limited to, level sensors in the first and third tanks **930** and **1045**, providing only water from the plate cooler **915** to the third tank **1045**, filling and emptying the first and third tanks **930** and **1045** simultaneously, using diverters (instead of inlet valves) to divert water into either the first tank **930** or the third tank **1045**. It is critical that an air gap be maintained along each path of water from the water source **905** to the troughs **1040**.

As discussed above, embodiments of the water delivery system can isolate the water delivery system from the well and, thus, the grounded secondary neutral, and the primary neutral, if it is jumpered. The water delivery system is, therefore, no longer a path for stray current from the neutrals of the electrical distribution system and is thus isolated from stray current caused by the utility.

Implementing the drinking water delivery systems **900** and **1043** helps isolate drinking water from the rest of the water system and prevent stray current in the water system from affecting animals when they drink. However, these systems add expense and do not prevent stray current on the farm from affecting the animals through other means such as milking equipment. Therefore, it is desirable to identify the sources of stray current at a facility and eliminate them.

FIG. **18** is a schematic illustration of a water system **1070** fed by a well **1075** and having a plurality of earth grounds **1080**, **1081**, and **1082**. The water delivery system **1070** acts like a switch, opening the electrical connection between the water delivery system **1070** and the well **1075**. The water system **1070** is electrically connected to each location of the facility or farm (e.g., milk house **1085**, watering facility **1090**, office **1095**, etc.). Within each location, the water system **1070** may also be electrically connected to an earth ground. Depending on how the connection to earth ground is made, the impedance between the water system **1070** and the earth ground can vary from zero ohms to infinite ohms (an open connection). For example, in the case of the animal watering area, each time an animal drinks, the animal can provide a connection between the water system and an earth ground.

When a stray current is introduced to an earth ground, it divides along all the available paths to complete its circuit. Based on impedance levels, different levels of current will be present on the different paths to the circuit completion. According to Kirchoff's second law, the currents on all these different paths will all add up to the original stray current.

FIG. **19** illustrates a simplified schematic diagram of an example of a possible stray current circuit **1100**. For example, if a faulty pump in the milk house **1085** generates a stray current **1105** and introduces it to the earth ground **1080** at the milk house **1085**, the stray current can take a number of paths back to complete its circuit. If there is a path to complete the circuit through the water system **1070**, some of the stray current will pass through the water system **1070**. The amount of stray current that passes through the water system **1070** depends on an impedance **1110** of the local earth ground to complete the circuit versus the impedance through the water system **1070** to complete the circuit. Based on Kirchoff's second law, the amount of current entering a node equals the amount of current leaving the node. Referring to FIG. **19**, the stray current entering node **1080**, represented by arrow A, is equal to the sum of the currents leaving the node **1080**, represented by the arrow B entering earth ground and arrow C entering the water system **1070**.

Current on path C passes through the impedance at the milk house **1085** and enters the water system **1070**. A voltage between the water system **1070** and earth ground **1080** can be measured to detect the presence of stray current. The voltage level measured will be indicative of the amount of stray current in path C and the impedance at the milk house **1085**.

The current in path C will again divide in the water system **1070** and enter parallel circuit **1120**. The currents on paths D and E will add up to the current on path C. Because the voltage across a parallel circuit is the same for each path of the parallel circuit, the voltages measured between the water system **1070** and earth grounds **1081** and **1082** may be similar, depending on the impedance between the earth grounds **1081** and **1082** (represented by R1 and R2) and a point where they meet.

The impedance of the entire parallel circuit **1120** is less than the impedance of the lowest impedance path, D or E. Therefore, the voltage measured between the water system **1070** and the earth ground **1080** is greater than the voltage measured between the water system **1070** and any other earth ground as long as one path in the parallel circuit **1120** has an impedance less than the impedance of the milk house **1085**.

FIG. **20** shows an embodiment of a monitoring system **1200** for monitoring a facility to identify a source of stray current. The monitoring system **1200** includes a plurality of meters **1205** monitoring an electrical characteristic between a test-point **1210** on an isolated water system **1070** (e.g., the electrically conductive section of pipe **240** in FIG. **5A**) and a plurality of earth grounds **1080**, **1081**, and **1082** at different locations on the farm. Using the isolated water system **1070** as one of the test points helps provide cleaner signals that are segregated from the stray current caused by the utility and helps ease detecting and locating sources of stray current other than the utility.

In some embodiments, the system includes a computer **1215** linked to the plurality of meters **1205** for logging and processing the readings from the meters **1205**. The computer **1215** can link to the plurality of meters **1205** in any suitable means available for communicating the measurements taken by the meters **1205** including a direct connection (e.g., serial communications and universal serial bus) and a networked connection. The computer **1215** can communicate with a printer **1217** to print reports and logs.

The plurality of meters **1205** can monitor a variety of electrical characteristics including alternating current volts (“ V_{AC} ”), direct current volts (“ V_{DC} ”), root mean square volts (“ V_{RMS} ”), peak-to-peak volts (“ V_{P-P} ”), and V_{AC} plus V_{DC} . In some embodiments V_{P-P} is monitored since V_{P-P} can include all of the voltage components of the stray current including harmonics.

In some embodiments, the monitoring system **1200** logs the voltages detected at each location and displays a chart showing the voltage levels over a period of time. An operator can view the charts. A rise in voltage level is indicative of the presence of a stray current. The operator can then compare the voltages detected at each location at the time the event occurred, with the location displaying the largest voltage being the most likely point where the stray current was introduced. Next, the operator can determine if similar events have occurred and can analyze, based on the times and durations of the events, what on-site operations coincide with the events. This analysis can help to isolate the possible sources of the stray current. For example, if a set of events appear to originate in a milk house and they coincide with the filling of a dairy truck, the equipment involved with filling the dairy truck is a likely source of the stray current.

In some embodiments, the monitoring system **1200** includes software that monitors the detected voltages and provides an indication that an event has occurred. Indications the monitoring system **1200** provides include an alarm **1220**, automatically sending an email describing the event, and printing an event log. The monitoring system **1200** also performs analysis on the logged data. The analysis provides a report of events that have similar characteristics (e.g., the timing, the wave form of the event, etc.) along with one or more probable locations of the introduction of the stray current and possible causes (e.g., equipment known to exist at the locations) of the stray current event.

In some embodiments, the monitoring system **1200** is linked to a wide area network **1225** such as the Internet. When the monitoring system **1200** network is enabled, a remote operator **1230** can monitor activity and view logs and reports.

In addition, the monitoring system **1200** can automatically provide alarms and reports to remote locations via the network.

In some embodiments, the meters **1205** are coupled to a plotter for recording the measurements taken by the meters **1205**.

The embodiments described above and illustrated in the figures are presented by way of example only and are not intended as a limitation upon the concepts and principles of the present invention. As such, it will be appreciated by one having ordinary skill in the art that various changes in the elements and their configuration and arrangement are possible. As should also be apparent to one of ordinary skill in the art, some systems and components shown in the figures are models of actual systems and components. Some control components described are capable of being implemented in software executed by a microprocessor or a similar device or of being implemented in hardware using a variety of components including, for example, timers and relays. In addition, terms like “processor” or “controller” may include or refer to both hardware and/or software.

Various features and advantages of the invention are set forth in the following claims.

What is claimed is:

1. A system for detecting and locating a source of unwanted electrical events, the system comprising:

a water delivery system electrically isolated from an electrical transmission system of an electric utility and earth ground;

a first test-point electrically connected to the water delivery system and electrically connected to a plurality of locations, the plurality of locations electrically isolated from the electrical transmission system and earth ground;

a plurality of second test-points, each of the second test points located at earth grounds and proximate to one of the plurality of locations;

at least one meter, the at least one meter configured to measure an electrical characteristic between the first test-point and one of the second test-points; and

a recording device configured to receive and record the measured electrical characteristic from the at least one meter.

2. The system of claim 1 wherein the recording device includes a computer.

3. The system of claim 2 wherein the computer is configured to display the measured electrical characteristic graphically.

4. The system of claim 2 wherein the computer monitors the measured electrical characteristic and determines an event has occurred when the electrical characteristic exceeds a threshold.

5. The system of claim 4 wherein the computer provides an indication that an event has occurred, the indication being at least one of printing a report, sounding an alarm, and sending an email.

6. The system of claim 2 wherein the computer analyzes the measured electrical characteristic and identifies commonality between events.

7. The system of claim 2 wherein the electrical characteristic is at least one of alternating current volts, direct current volts, root mean square volts, peak-to-peak volts, and alternating current volts plus direct current volts.