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(54) **VALVE TRAIN DEVICE FOR ENGINE**

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(57) **ABSTRACT**

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74/559, 567, 569

See application file for complete search history.

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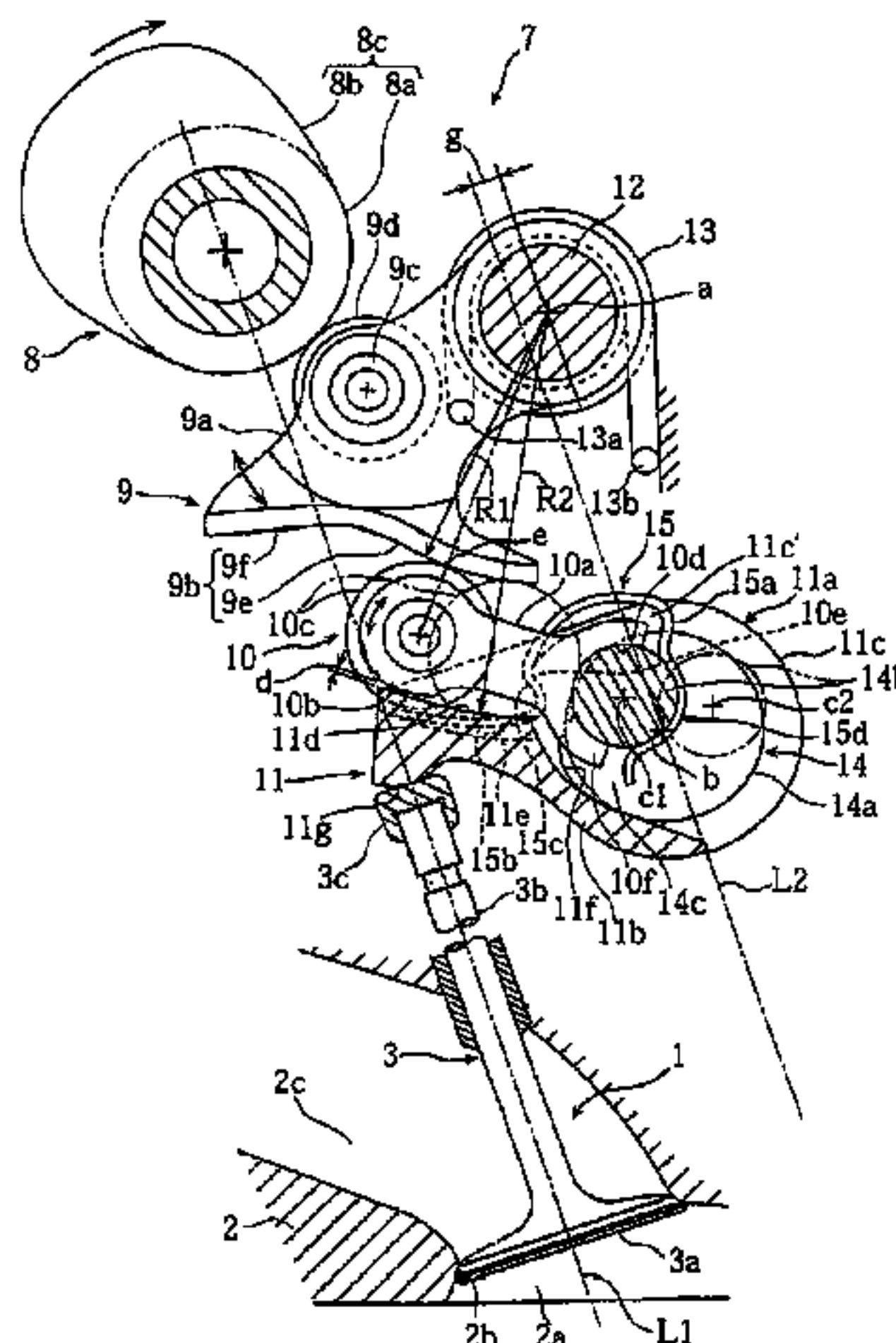
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A valve train device for an engine is configured to pivot a rocker arm supported on a rocker arm support shaft to drive a valve which opens and closes a valve opening formed in a combustion chamber. The device comprises a valve drive device and a swing member pivotally supported on a swing member support shaft and driven to pivot about the swing member support shaft by the valve drive device. A control arm is disposed between a swing cam surface formed on the swing member and a rocker-side surface formed on the rocker arm. The control arm is configured for transferring motion of the swing cam surface to the rocker-side surface. A displacement mechanism is provided for displacing a contact point between the control arm and the swing cam surface and a contact point between the control arm and the rocker-side surface. The rocker-side surface has an arcuate shape which arcs about a center of pivoting motion of the swing member and wherein the rocker-side surface or an extension of the rocker-side surface about said center of pivoting motion of the swing member passes in substantially near a center of swing of the rocker arm.

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22 Claims, 5 Drawing Sheets



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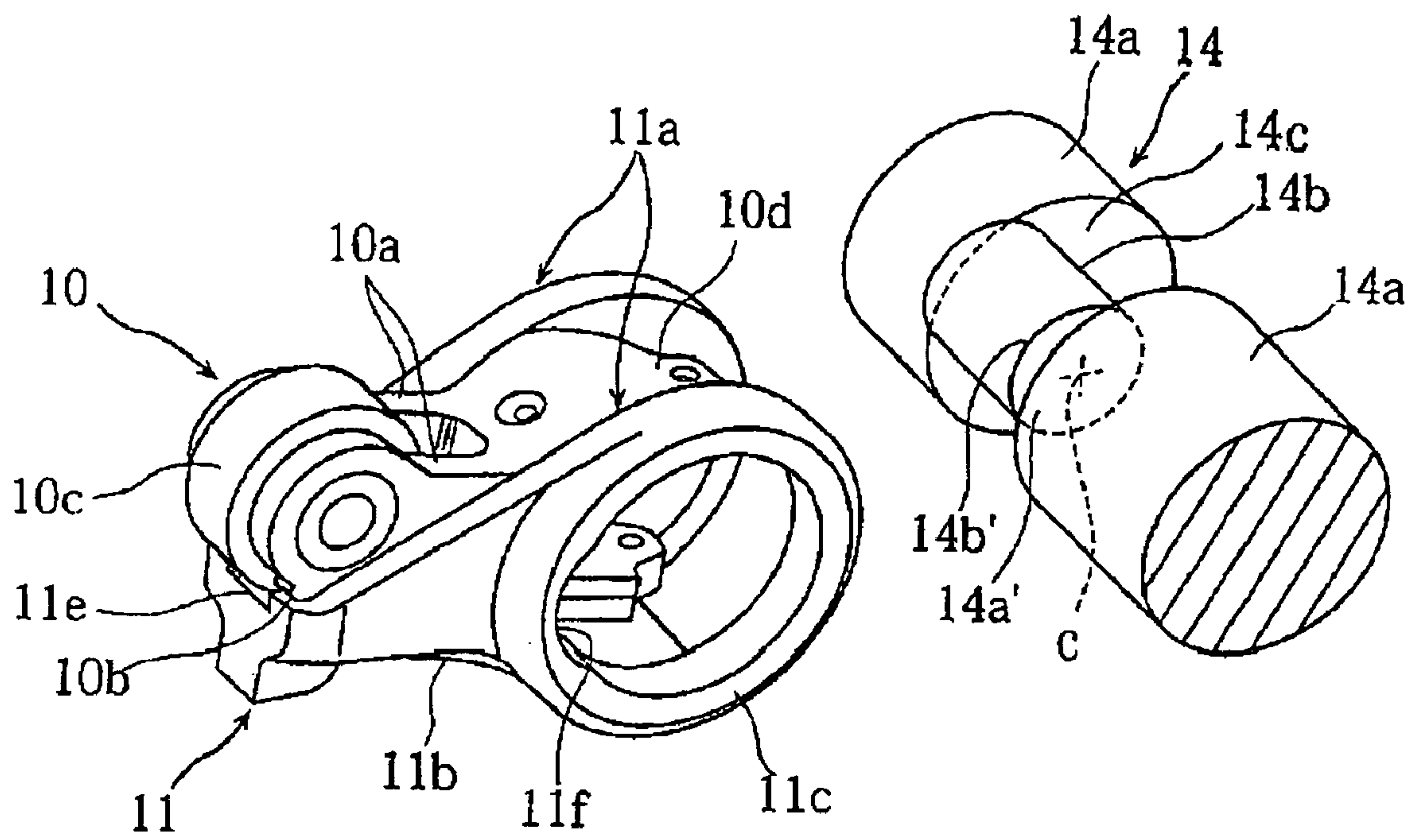


Figure 2

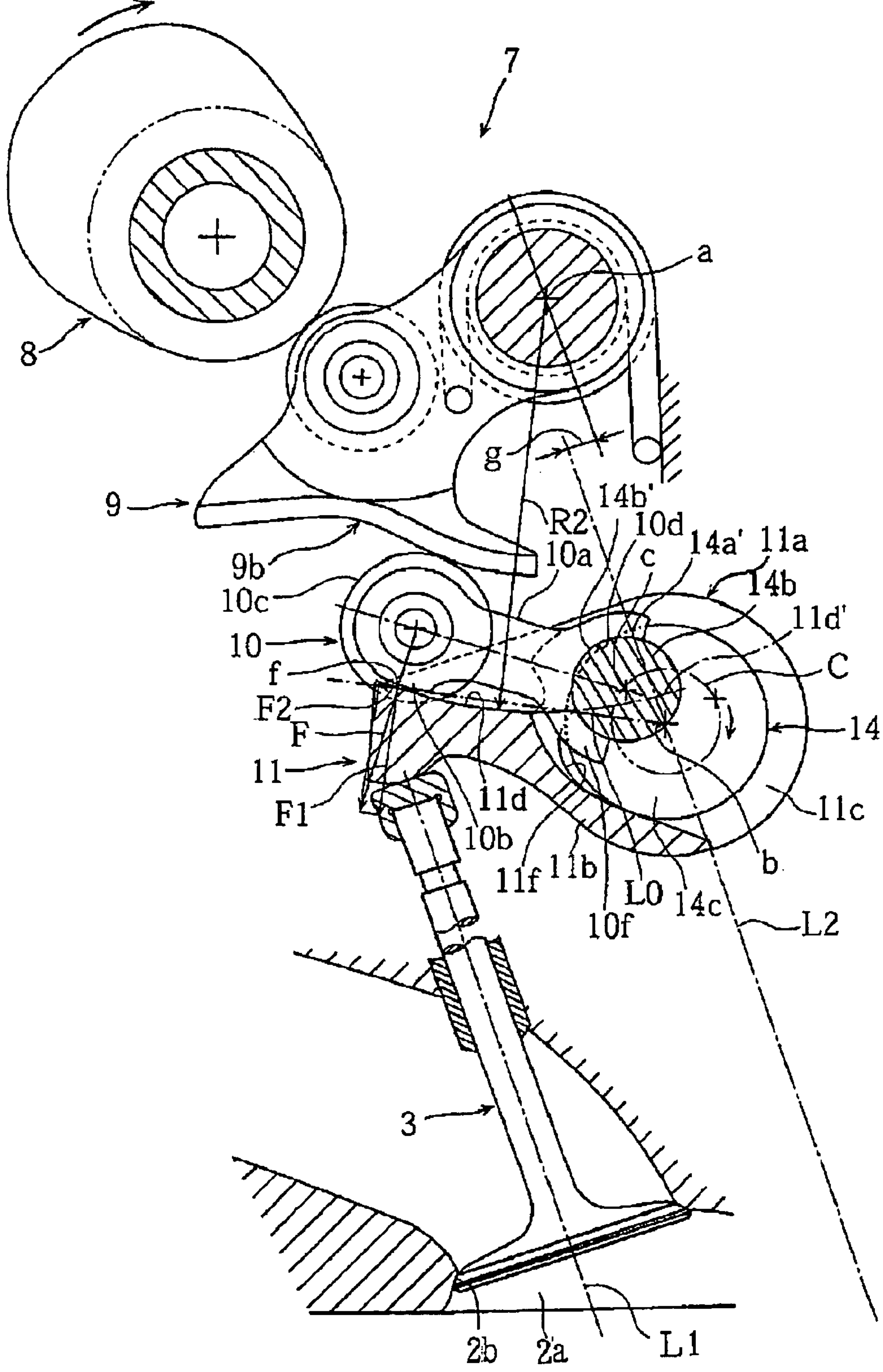


Figure 3

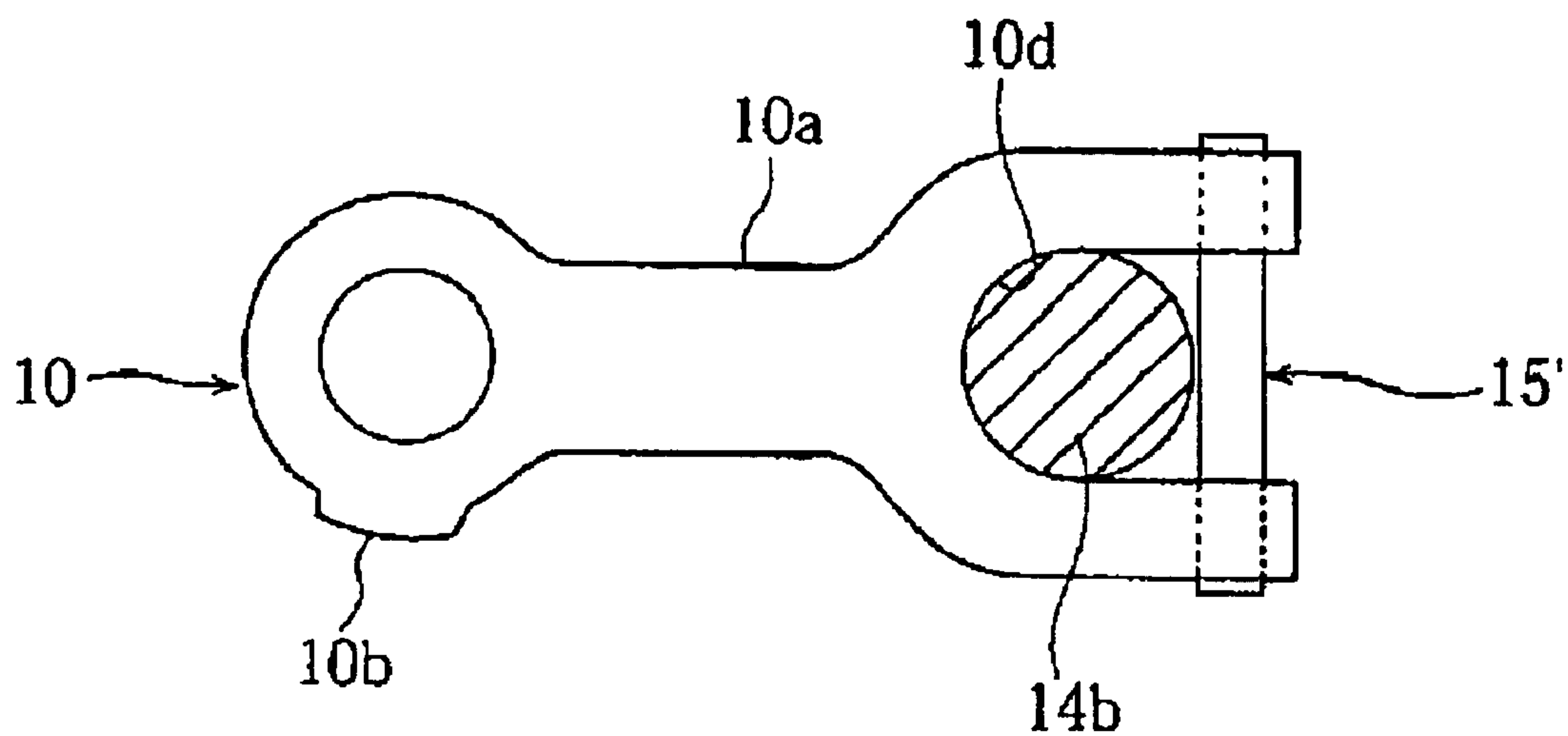


Figure 4

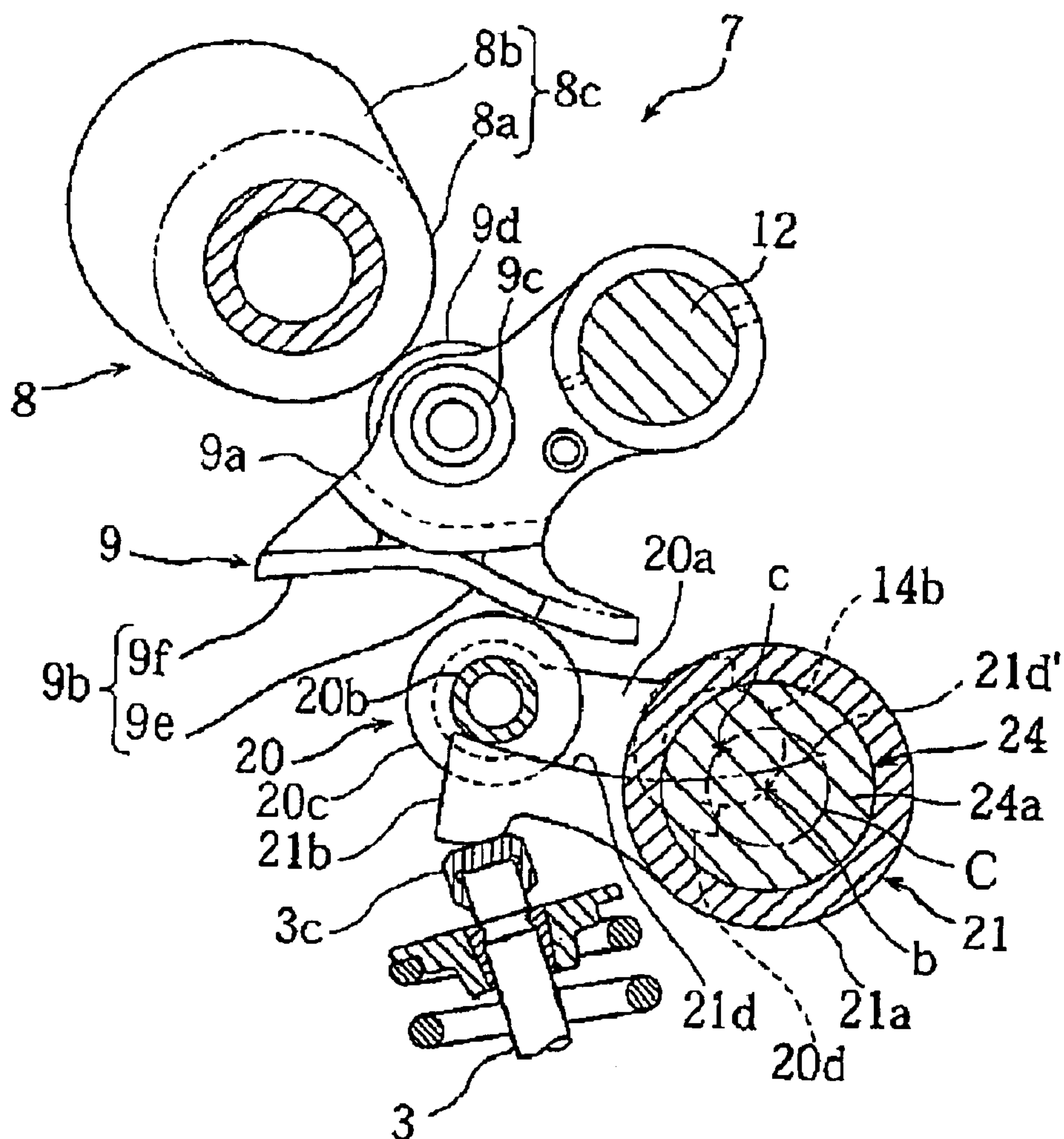


Figure 5

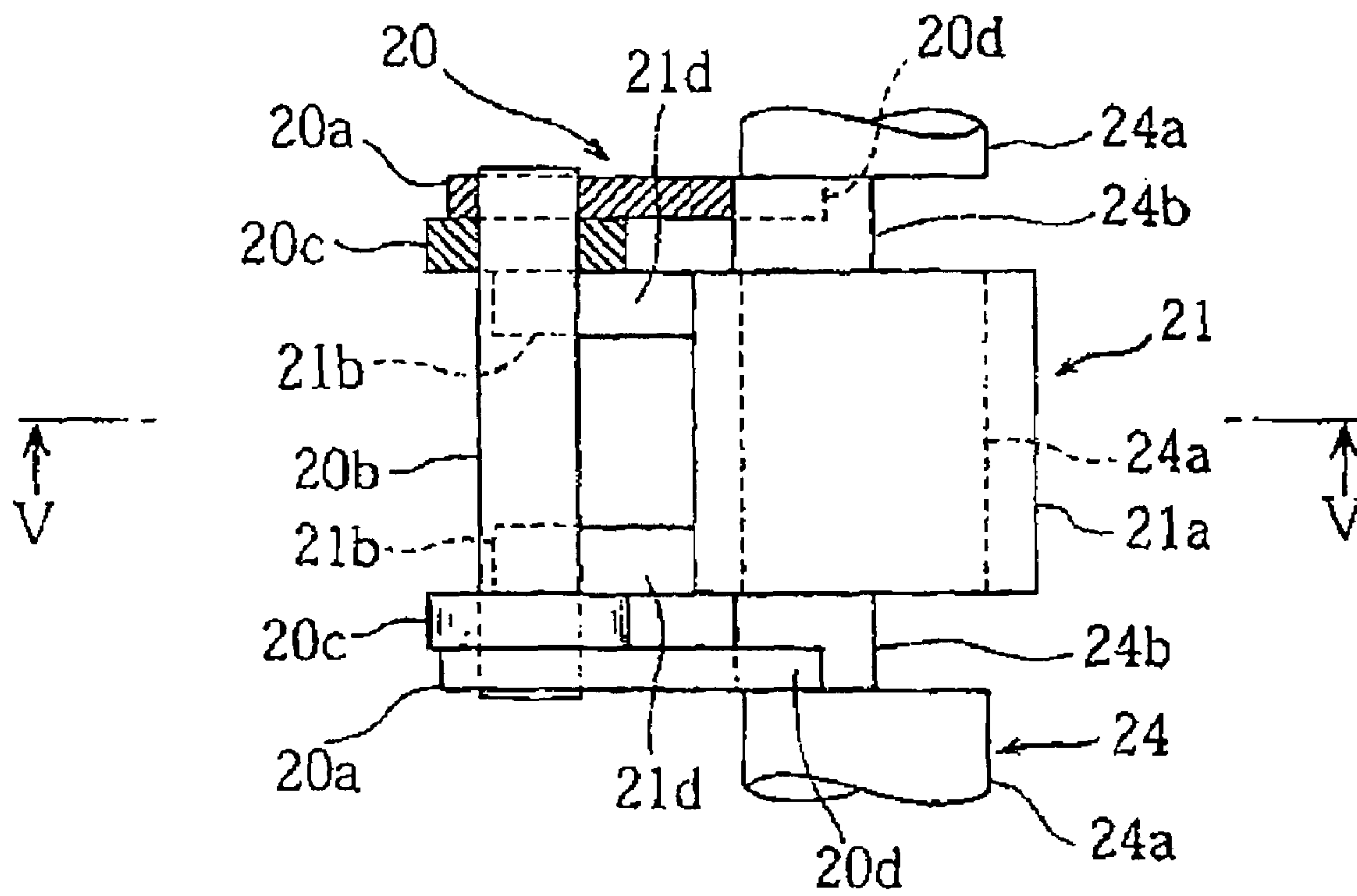


Figure 6

VALVE TRAIN DEVICE FOR ENGINE

PRIORITY INFORMATION

This application is continuation of PCT Application No. PCT/JP2004/006428, filed on May 6, 2004, which claims priority under 35 U.S.C. § 119 to Japanese Patent Application No. 2003-304931, filed on Aug. 28, 2003 and Japanese Patent Application No. 2003-126257, filed on May 1, 2003, the entire contents of these applications are expressly incorporated by reference herein.

BACKGROUND OF THE INVENTION

1. Field of the Invention

This invention relates to a valve train device for an engine and, more particularly, to a valve train device which can continuously change valve opening duration and/or the amount of valve lift.

2. Description of the Related Art

It is known in the art how to provide engines with valve train devices that are capable of continuously changing intake valve opening duration and/or the amount of valve lift. An example of such a valve train device comprises a camshaft, which drives an intake valve to open and close through a rocker arm. This device is arranged in such a way that a swing member is pivoted by the camshaft. A control arm is interposed between a swing cam surface of the swing member and a rocker-side depressed surface of the rocker arm. The valve opening duration and the amount of valve lift is continuously varied by changing a position of the control arm that comes into contact with the swing cam surface and a position of the control arm that comes into contact with the rocker-side depressed surface (See e.g., JP-A-Sho 59-500002).

SUMMARY OF THE INVENTION

Using the aforementioned constitution, in which the position of the control arm to come into contact with the rocker-side depressed surface is changed, in the conventional type of valve train device may result in a problem depending on where the rocker-side depressed surface is disposed. For example, there may be a low transfer efficiency of force, applied from the swing cam surface to the control arm, and transferred to the rocker arm and therefore to the valve.

An object of an embodiment of the present invention is to address the situations with the prior art described above and provide a valve train device for an engine which can enhance transfer efficiency of the force, applied to the control arm, and transferred to the rocker arm and therefore to the valve.

Therefore, one embodiment of the present invention comprises a train device for an engine that is configured to pivot a rocker arm supported on a rocker arm support shaft to drive a valve which opens and closes a valve opening formed in a combustion chamber. The device comprises a valve drive device and a swing member pivotally supported on a swing member support shaft and driven to pivot about the swing member support shaft by the valve drive device. A control arm is disposed between a swing cam surface formed on the swing member and a rocker-side surface formed on the rocker arm. The control arm is configured for transferring motion of the swing cam surface to the rocker-side surface. A displacement mechanism is provided for displacing a contact point between the control arm and the swing cam surface and a contact point between the control

arm and the rocker-side surface. The rocker-side surface has an arcuate shape which arcs about a center of pivoting motion of the swing member and wherein the rocker-side surface or an extension of the rocker-side surface about said center of pivoting motion of the swing member passes in substantially near a center of swing of the rocker arm.

For purposes of summarizing the invention, certain aspects, advantages and novel features of the invention have been described herein. It is to be understood that not necessarily all such advantages may be achieved in accordance with any particular embodiment of the invention. Thus, the invention may be embodied or carried out in a manner that achieves or optimizes one advantage or group of advantages as taught herein without necessarily achieving other advantages as may be taught or suggested herein.

BRIEF DESCRIPTION OF THE DRAWINGS

A general architecture that implements various features of specific embodiments of the invention will now be described with reference to the drawings. The drawings and the associated descriptions are provided to illustrate embodiments of the invention and not to limit the scope of the invention.

FIG. 1 is a sectional side view of a valve train device for an engine according to a first embodiment of the present invention.

FIG. 2 is a perspective view of a control arm, rocker arm and rocker shaft of the first embodiment.

FIG. 3 is a sectional side view for describing the functions of an embodiment of the invention.

FIG. 4 is a schematic view showing an embodiment of a come-off prevention member of the first embodiment.

FIG. 5 is a sectional side view for describing a second embodiment of the invention.

FIG. 6 is a schematic top plan view of the second embodiment.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

An embodiment of the present invention will be described hereinafter with reference to the attached drawings.

FIGS. 1–3 describe a first embodiment of the invention. FIG. 1 is a sectional side view of a valve train device according to this embodiment of the invention. FIG. 2 is a perspective view of core parts of the valve train device. FIG. 3 is a view for describing transfer efficiency of a force F in this embodiment of the invention.

In FIG. 1, reference numeral 1 denotes an valve device for opening and closing an valve opening formed in a combustion chamber. An engine can be provided with two intake and exhaust valve devices. However, in FIG. 1, only a portion at an intake valve device is shown. A combustion recess 2a is provided on the mating face of a cylinder head 2 of the engine with the cylinder body. The combustion recess 2a forms a top ceiling of a combustion chamber. The combustion recess 2a includes left and right intake valve openings 2b. Each intake valve opening 2b is merged with an intake port 2c and led to an external connection opening of an engine wall. Each intake valve opening 2b is opened and closed through a valve head 3a of an intake valve 3. The intake valve 3 is constantly urged with a valve spring or biasing member (not shown) in closing direction.

In the embodiments described below, reference will be made to the intake valve 3 and intake valve device 1. However, it should be appreciated that certain features and

aspects of these embodiments may also be applied to an exhaust device and exhaust valve. It should also be appreciated that various features, aspects and advantages of the present invent may be used with engines having more than one intake valve and/or exhaust valve, and any of a variety of configurations including a variety of numbers of cylinders and cylinder arrangements (V, W, opposing, etc.).

A valve train device 7 is disposed above the intake valve 3. The valve train device 7 is configured such that: (i) an intake camshaft 8 which serves as swing member drive device causes a swing member 9 to swing or pivot, (ii) the swing member 9 causes a rocker arm 11 to swing or pivot through a control arm 10, and (iii) the swing of the rocker arm 11 causes the intake valve 3 to proceed and retract in the axial direction, and thus the intake valve opening 2b is opened and closed.

Causing the control arm 10 to proceed and retract can continuously change a contact point between the control arm 10 and the swing member 9 and a contact point between the control arm 10 and the rocker arm 11, thereby continuously changing the opening duration of the intake valve 3 and the amount of valve lift.

The intake camshaft 8 may be arranged in parallel with a crankshaft (not shown). The intake camshaft may be supported to be rotatable and immobile in a direction perpendicular to the crankshaft and in the axial direction through a cam journal portion formed on the cylinder head 2 and a cam cap provided on an upper mating face of the journal portion. In the illustrated embodiment, the intake camshaft 8 is formed with a single cam nose 8c common to the left and right intake valves, including a base circle portion 8a having a specified diameter, and a lift portion 8b having a specified cam profile. Each cylinder is provided with a single cam nose.

The swing member 9 has a pair of left and right swing arm portions 9a, 9a, a swing cam surface 9b, a roller shaft 9c, and a swing roller 9d. The pair of swing arm portions 9a, 9a is supported for free swinging movement by a swing shaft 12 arranged in parallel with the intake camshaft 8 so as to be immobilized in the direction perpendicular to the swing shaft and in the axial direction. The swing cam surface 9b is formed to connect the front (lower) ends of the swing arm portions 9a. The roller shaft 9c is arranged in parallel with the swing shaft 12 and in the midsection between the left and right swing arm portions 9a, 9a to pass therethrough. The swing roller 9d is rotatably supported on the roller shaft 9c. The swing roller 9d is constantly in rotational contact with the cam nose 8c.

Base (upper) portions of the swing arm portions 9a is fitted to and supported with the swing shaft 12 for free swinging movement. The swing shaft 12 is provided with a pair of left and right balance springs 13 (e.g., coil springs). Each balance spring 13 has a first end 13a retained between the swing shaft 12 of the swing arm portion 9a and the roller shaft 9c. A other end 13b of each balance spring is retained by the cylinder head 2. The balance spring 13 urges the swing member 9 such that the swing roller 9d of the swing member 9 comes into contact with the cam nose 8c of the intake camshaft 8, thereby preventing the swing roller 9d from moving away from the cam nose 8c at the high engine speed. This avoids or reduces abnormal behavior of the swing member 9.

The swing cam surface 9b has a base circle portion 9e and a lift portion 9f formed together in a curved manner to have a connected surface and a generally plate-like shape. The swing member 9 is provided so that the base circle portion 9e is positioned nearer to a rocker shaft 14 and the lift

portion 9f is positioned opposite the rocker shaft 14. The base circle portion 9e has an arcuate shape of a radius R1 centered on the axis of the swing shaft 12 as the center of swing (a). Thus, while the base circle portion 9e depresses the roller 10c, the intake valve 3 is placed at a fully closed position and not lifted even if a swing angle of the swing member 9 increases.

Meanwhile, the lift portion 9f lifts the intake valve 3 greatly as the lift portion 8b of the intake camshaft 8 at the portion close to the top depresses the swing roller 9d, that is, as the swing angle of the swing member 9 increases. In this embodiment, the lift portion 9f includes a ramp zone which gives a constant speed, an acceleration zone which gives a varied speed, and a lift zone which gives generally a constant speed.

The rocker shaft 14 includes a large-diameter portion 14a and an eccentric pin 14b having a smaller diameter than the diameter for the large-diameter portion. In the illustrated embodiment, the eccentric pin 14b is provided on a mid-section of the large-diameter portion, while being offset from an axial center (b) of the rocker shaft 14 toward the outer side in the radial direction. The large-diameter portion 14a is rotatably supported with the cylinder head 2. The eccentric pin 14b has an axial center (c) positioned such that part of the outer surface 14b' protrudes outward in the radial direction from an outer surface 14a' of the larger-diameter portion 14a. To the rocker shaft 14 is connected a rocker shaft driving mechanism (not shown) for controlling an angular position of the rocker shaft 14 according to an engine load (throttle opening) and engine speed.

The rocker arm 11 is formed with left and right rocker arm portions 11a, 11a, a rocker coupling portion 11b, and ring-shaped bearing portions 11c, 11c. Lower-half portions on the distal end side of the left and right rocker arm portions 11a, 11a are coupled integrally with the rocker coupling portion 11b. The ring-shaped bearing portions 11c, 11c are formed integrally with the proximal ends of the left and right rocker arms 11a, 11a. The bearing portions 11c, 11c are supported with the large-diameter portions 14a, 14a of the rocker shaft 14. Part of the bearing portions 11c towards the rocker arm portions 11a is provided with a clearance recess 11f that conforms to the outwardly projecting shape of the eccentric pin 14b.

The control arm 10 has a schematic structure in which: a control-side depressing surface 10b is formed in an arcuate shape about the center of swing (a) on the lower face of the distal ends of the left and right bifurcated control arm portions 10a, a; the roller 10c in rotational contact with the swing cam surface 9b is pivoted between the distal ends of the control arm portions a, a; and the bifurcated, semi-circular bearing portion 10d is formed at the proximal ends of the control arm portions.

On the topside of the rocker coupling portion 11b of the rocker arm 11, left and right rocker-side depressed surfaces 11d, 11d are formed to come into sliding contact with the left and right control-side depressing surfaces 10b, 10b. The rocker-side depressed surfaces 11d, 11d are formed in an arcuate shape of a radius R2 about the center of swing (a) of the swing shaft 12. As shown in FIG. 4, An extension line 11d' of the rocker-side depressed surface 11d is so set as to pass in the vicinity of the center of sing (b) of the rocker arm 11, and more preferably, to pass inside a rotation locus C of the axial center (c) of the eccentric pin 14b.

With reference to FIG. 1, the control arm 10 is placed such that it is interposed between the left and right rocker arm portions 11a, 11a of the rocker arm 11. The semi-circular bearing portion 10d is rotatably supported with the eccentric

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pin **14b** of the rocker shaft **14**. The come-off prevention spring **15** prevents the bearing portion and the eccentric pin from coming off.

In one embodiment, the come-off prevention spring **15** is made of spring steel band member, and has a holding portion **15a** curved into approximately a C-shape and a depressing portion **15b** that extends from the front end of the holding portion **15a** toward the distal end of the rocker arm **11**. The come-off prevention spring **15** is designed to retain a curved retaining portion **15c**, which is formed adjacent to the boarder between the holding portion **15a** and the depressing portion **15b**, to a retained portion **10e** of the control arm **10**. The come-off prevention spring **15** is also designed to retain an accurate retaining portion **15d**, which is formed opposite to the pressing portion **15b**, to the eccentric pin **14b**. Thereby, the come-off prevention spring **15** holds the bearing portion **10d** and the eccentric pin **14b** together for relative rotation while preventing them from separating from each other.

The distal end of the depressing portion **15b** of the come-off prevention spring **15** comes into contact with a depressing groove **11e** with a predetermined amount of spring force, the depressing groove being provided on the topside of the rocker coupling portion **11b** of the rocker arm **11** and at the center in the axial direction. The depressing groove **11e** is formed in an arcuate shape about the center of rotation (a) of the swing member **9**. In the manner as described, the control arm **10** is urged clockwise as shown in the drawing. The roller **10c** comes into contact with the swing cam surface **9b**. A slight gap (d) is created between the rocker-side depressed surface **11d** and the control-side depressing surface **10b**.

In the manner as described, a displacement mechanism is constituted such that rotating the rocker shaft **14** allows a contact point (e) between the roller **10c** and the swing cam surface **9b** as well as a contact point (f) between the control-side depressing surface **10b** and the rocker-side depressed surface **11d** to be displaced.

In the displacement mechanism, displacement of the contact point relative to the rotation angle of the rocker shaft **14** in a high operation range in which the opening duration of the intake valve **3** is long and the amount of the valve lift is large (shown by solid lines in FIG. 1) and in a low operation range in which the opening duration of the intake valve **3** is short and the amount of the valve lift is small (shown by chain double-dashed lines in FIG. 1) is smaller than the displacement of the contact point in a medium operation range in which the opening duration of the intake valve **3** and the amount of the valve lift are medium. In other words, in the high operation range, the axial center of the eccentric pin **14b** is positioned near the point identified by the reference number **c1** in FIG. 1, while near the point identified by reference number **c2** in the low operation range. When the eccentric pin **14b** is adjacent to the points **c1** or **c2**, each displacement of the contact points e and f relative to the rotation angle of the rocker shaft **14** is smaller than that in another operation range. In contrast, in the medium operation range, the axial center of the eccentric pin **14b** is positioned approximately between **c1** and **c2**. When the eccentric pin **14b** is adjacent approximately between **c1** and **c2**, each displacement of the contact point e and f relative to the rotation angle of the rocker shaft **14** is larger than those in the other operation ranges.

An axial end surface **10f** of the bearing portion **10d** is in sliding contact with an end surface **14c** of the large-diameter portion **14a** of the rocker shaft **14**, the end surface forming a step from the eccentric pin **14b**, thereby positioning the

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control arm **10** in the axial direction. In turn, an inner end surface **11c'** of the bearing portion **11c** is in sliding contact with an opposite end surface to the end surface **10f** of the bearing portion **10d** of the control arm **10**, thereby positioning the rocker arm **11** in the axial direction.

Description will be next made of the operations and effects of this embodiment.

In the valve train device **7** of this embodiment, the rocker shaft driving mechanism controls a rotational angular position of the rocker shaft **14** in accordance with engine operation conditions determined based on the engine speed and load. For example, in a high-speed and high-load operation range, the angular position of the rocker shaft **14** is controlled to position the axial center of the eccentric pin **14** to point **c1** as shown by solid lines in FIG. 1. Thus, when the control arm **10** is positioned at the advanced end and the base circle portion **8a** of the camshaft **8** comes into contact with the roller **9d**, the contact point e between the roller **10c** of the control arm **10** and the swing cam surface **9b** of the swing member **9** is positioned closest to the lift portion **9f**. This results in maximizing both the opening duration of the intake valve **3** and the amount of valve lift.

In turn, in a low-speed and low-load operation range, the angular position of the rocker shaft **14** is controlled to position the axial center of the eccentric pin **14** to point **c2** as shown by chain double-dashed lines in FIG. 1. Thus, the control arm **10** moves to the retracted end, and the contact point e between the roller **10c** of the control arm **10** and the swing cam surface **9b** of the swing member **9** is positioned farthest from the lift portion **9f**. This results in minimizing both the opening duration of the intake valve **3** and the amount of valve lift.

In one embodiment, the rocker-side depressed surface **11d** is formed such that the extension line **11d'** thereof passes in the vicinity of the center (b) of swing of the rocker arm **11**. In another embodiment, the structure describe herein allows the extension line **11d'** to pass inside the rotation locus C (see FIG. 3) of the center point (c) of the eccentric pin **14**. In the illustrate embodiment, the control arm **10** is also interposed between the left and right rocker arm portions **11a**, **11a** of the rocker arm **11**, and the rocker-side depressed surface **11d** is formed on the rocker coupling portion **11b** for coupling the left and right rocker arm portions **11a**, **11a**. This enhances positioning the extension line **11d'** of the rocker-side depressed surface **11d** such that it passes in the vicinity of the center (b) of swing of the rocker arm **11**.

In a preferred embodiment, "such that the rocker-side depressed surface **11d** or its extension line **11d'** passes in the vicinity of a center of swing (b) of the rocker arm **11**" means that the rocker-side depressed surface **11d** is approximated as close as possible to a straight line **Lo** that connects the center of swing (b) and a point (f) of application of force **F** transferred from the control arm **10** to the rocker arm **11**, thereby transferring the force **F** with high efficiency as the rotational force of the rocker arm **11**.

The rocker-side depressed surface **11d** is of the illustrated embodiment is therefore formed in such a manner that the extension line **11d'** thereof passes in the vicinity of the center (b) of swing of the rocker arm **11**. Thus, the force **F** transferred from the swing member **9** to the contact point (f) via the control arm **10** can be efficiently transferred to the rocker arm **11** and therefore to the valve **3**. In other words, in this embodiment, since the rocker-side depressed surface **11d** passes in the vicinity of the center (b) of swing of the rocker arm **11**, the rocker-side depressed surface **11d** generally agrees with the straight line **Lo**. This increases a first component force **F1** of the force **F**. The first component force

F1 being perpendicular to the straight line L_o as a rotational force of the rocker arm 11 and the force F being transferred from the control arm 10 to the rocker arm 11. Thus, the transfer efficiency of the force F from the control arm 10 to the rocker arm 11 enhances.

The center (a) of swing of the swing member 9 is located at a point opposite to a valve shaft line L₁ with respect to a straight line L₂ parallel to the valve shaft line L₁ and passing the axial center (b) of the rocker shaft 14, while being away from the straight line L₂ by a distance g. This provides an advantage to the extension line 11d' of the rocker-side depressed surface 11d to pass in the vicinity of the center (b) of rotation of the rocker arm 11. More specifically, as an angle formed between the direction of the force F applied to the rocker arm 11 and the straight line L_o that connects a point (f) of application of the force F and the center (b) of swing of the rocker arm 11 is closer to the right angle, the transfer efficiency of the force F increases. Since the center (a) of swing of the swing member 9 is located on the side opposite to the valve shaft line L₁, the direction of the force F can be easily changed to be close to the direction perpendicular to the straight line L_o.

The eccentric pin 14b provided on the midsection of the rocker shaft 14 is adapted to support the bearing portion 10d of the control arm portion a for free rotation, and the come-off prevention spring 15 holds the bearing portion 10d and the eccentric pin 14b. This allows the opening duration of the valve 3 and the amount of valve lift to continuously change by using a very simple structure or solely rotating the rocker shaft 14. This also facilitates work for coupling the control arm 10 and the eccentric pin 14b.

In the case of multi-cylinder engine, because uniform valve opening duration and amount of valve lift need be ensured for all cylinders, several control arms 10 within the dimensional tolerance range are prepared to be selected in combination with the rocker shaft 14 in order to uniform the valve opening duration and the amount of valve. Assemble and removal work when such a selective combination is required can be easily carried out.

The depressing portion 15b in the illustrated embodiment is integrally formed with the come-off prevention spring 15, the depressing portion 15b urging the control arm 10 by depressing the rocker arm 11, such that the roller 10c comes into contact with the swing cam surface 9b. Thus, the roller 10c of the control arm 10 can be constantly in contact with the swing cam surface 9b of the swing member 9 by a simple constitution. Also, a rolling contact of the roller 10c with respect to the motion of the swing cam surface 9b can be kept normal, thereby preventing the wearing of the swing cam surface 9b and the roller 10c.

Offset displacement of the eccentric pin 14b is preset so that the outer surface 14b' of the eccentric pin 14b protrudes outward from the outer surface 14a' of the rocker shaft 14 in the radial direction. This can increase the displacement of the control arm 11 without increasing the diameter of the rocker shaft 14, thereby increasing the adjustment range for the valve opening duration and amount of valve lift.

When the eccentric pin 14b protrudes outward, an inner peripheral surface of the bearing portion 11c supported with the rocker shaft 14 of the rocker arm 11 is formed with the clearance recess 11f which conforms with the amount of protrusion of the eccentric pin 14b. Thus, while the clearance recess 11f of the rocker arm 11 fits the protrusion of the eccentric pin 14b, the rocker arm 11 is displaced in the axial direction of the rocker shaft 14, so that the rocker arm 11 can be assembled with the rocker shaft 14 without any problem.

In the low operation range in which the opening duration of the valve 3 is short and the amount of valve lift is small, the eccentric pin 14b is positioned at point c₂ so that the displacement of the contact point (e) relative to the rotation angle of the rocker shaft 14 is smaller than the displacement in the medium operation range in which the opening duration of the valve 3 and the amount of valve lift are medium. This, in the low engine speed range, can avoid abrupt variations in engine output due to slight variations in rotation angle of the rocker shaft 14, and can provide smooth operations, thereby avoiding jerky feeling.

In the high operation range in which the opening duration of the valve 3 is long and so forth, the eccentric pin 14b is positioned at (c₁), so that the displacement of the contact point (e) relative to the opening angle of the rocker shaft 14 is preset smaller than the displacement in the medium operation range in which the opening duration of the valve is medium and so forth. This, in the high engine speed range, can reduce a torque required for rotating rocker shaft 14, and can provide smooth driving operations.

The control arm 10 is brought into sliding contact with the step 14c from the eccentric pin 14b of the rocker shaft 14, thereby positioning the control arm in the axial direction. The rocker arm 11 is brought into sliding contact with the axial end surface 10f of the control arm 10, thereby positioning the rocker arm in the axial direction. Therefore, positioning of the control arm 10 and the rocker arm 11 in the axial direction can be achieved without any dedicate parts.

In the description of the first embodiment, the come-off prevention member is a leaf spring. However, as shown in FIG. 4, the come-off prevention member of the invention may be a rod-shaped come-off prevention pin whose both ends are press-fitted through the outer ends of the bearing portion 10d.

In the description of the first embodiment, the control arm is included in the rocker arm. However, the control arm may be disposed externally to the rocker arm in the invention.

For example, FIGS. 5 and 6 are for describing a second embodiment in which a control arm is disposed externally to a rocker arm. In these figures, the same reference numerals as in FIGS. 1 to 4 designate the same or corresponding parts.

A rocker arm 21 includes: a cylindrical bearing portion 21a supported with a large-diameter portion 24a of a rocker shaft 24; and left and right rocker arm portions 21b, 21b integrally extending forward from axially opposite ends of the bearing portion 21a. Bottom surfaces of the distal ends of the rocker arm portions 21b come into contact with the top ends of left and right intake valves 3, 3, respectively.

Rocker-side depressed surfaces 21d are formed on the top side of the left and right rocker arm portions 21b. The rocker-side depressed surfaces 21d are formed in an arcuate shape of a predetermined radius about an axial center of a swing shaft 12. An extension line 21d' of the rocker-side depressed surface 21d is so set as to pass in the vicinity of a center of swing (b) of the rocker arm 21, and more preferably, to pass inside a rotation locus C of an axial center (c) of an eccentric pin 24b.

The control arm 20 includes a pair of left and right arm portions 20a, 20a, a roller shaft 20b and proximal end portions 20d of the left and right arm portions 20a, 20a. The roller shaft 20b rigidly connects the distal ends of the left and right arm portions 20a, 20a together. The proximal end portions 20d, which are formed in a semi-circular, are coupled and supported with the eccentric pin 24b of the

rocker shaft **24**, and retained together with the eccentric pin by the leaf spring, using the same constitution as in the first embodiment.

The left and right arm portions **20a**, **20a** are positioned externally to their associated rocker arm portions **21b**, **21b** 5 in the axial direction. Each arm portion and the associated rocker arm portion form a clearance between them to accommodate a roller **20c**. The rollers **20c**, **20c** are supported with the roller shaft **20b** for free rotation. The rollers **20c** are in rotational contact with a swing cam surface **9b** of 10 the swing arm **9**.

The roller shaft **20b** is in sliding contact with the left and right rocker-side depressed surfaces **21d**, **21d** of the rocker arm **21**. In other words, in this embodiment, the roller shaft **20b** has a control-side depressing surface for depressing the 15 rocker-side depressed surface **21d**.

The second embodiment of the invention is constituted in a way such that: the arm portions **20a** of the control arm **20** are placed externally to the rocker arm portions **21b** of the rocker arm **21**, the roller **20c** is placed between the arm 20 portion and the rocker arm portion, and the roller shaft **20b** depresses the rocker-side depressed surface **21d**. This enables the rocker-side depressed surface **21d** to be formed 20 such that an extension line **21d'** thereof passes in the vicinity of the center of swing (b) of the rocker arm **21**. This can enhance transfer efficiency of force from the control arm **20** to the rocker arm **21** as with the case in the first embodiment.

According to the embodiments described herein, as shown in FIG. 3, the control arm **10** is designed to transfer the motion of the swing cam surface **9b** of the swing member **9** to the rocker-side depressed surface lid of the rocker arm **11**. In this case, the rocker-side depressed surface **11d** is formed in an arcuate shape about the center of swing (a) of the swing member **9**, such that the rocker-side depressed surface **11d** or its extension line **11d'** passes in the vicinity 25 of the center of swing (b) of the rocker arm **11**. Thus, the force *F* applied from the swing member **9** to the control arm **10** can be efficiently transferred to the rocker arm **11** and therefore to the valve **3**.

To be more specific, the force *F* transmitted from the control arm **10** to the rocker arm **11** is divided into a first component force (rotational force of the rocker arm) **F1** perpendicular to the direction of a straight line *L_o* that connects a point (f) of application of the force *F* and the center of swing (b) of the rocker arm, and into a second 35 component force **F2** in the direction of the straight line *L_o*. In the embodiments described herein, since the rocker-side depressed surface **11d** or its extension line *lid'* passes in the vicinity of the center of swing (b) of the rocker arm **11**, the rocker-side depressed surface **11d** generally agrees with the straight line *L_o*. This decreases the second component force **F2** while increasing the first component force **F1**, which results in enhanced transfer efficiency of the force *F* from the control arm **10** to the rocker arm **11**.

According to the illustrated embodiment of FIGS. 1-3, 45 the control arm **10** is interposed between the left and right rocker arm portions **11a**, **11a** of the rocker arm **11**, and the rocker-side depressed surface **11d** is formed on the rocker coupling portion **11b** for coupling the left and right rocker arm portions **11a**, **11a**. This facilitates placing the rocker-side depressed surface **11d** or its extension line **11d'** such that it passes in the vicinity of the center of swing (b) of the rocker arm **11**, thereby achieving enhanced transmission efficiency of the force from the control arm **10** to the rocker arm **11**.

According to the embodiments of FIGS. 5-6, the control arm **20** is provided with the roller **20c** which comes into

contact with the swing cam surface **9b** such that the roller is located externally to the rocker arm portion **21b** of the rocker arm **21**, and the roller shaft **20b** for supporting the roller **20c** is designed to depress the rocker-side depressed surface **21d** 5 of the rocker arm portion **21b**. This facilitates the rocker-side depressed surface **21d** or its extension line **21d'** being formed to pass in the vicinity of the center of swing (b) of the rocker arm **21**, thereby achieving enhanced transfer efficiency of the force from the control arm **20** to the rocker arm **21**.

According to the embodiment of FIGS. 1-3, the proximal end of the control arm portion **10a** is rotatably coupled with the eccentric pin **14b** provided on the midsection of the rocker shaft **14**, and rotating the rocker shaft **14** allows 10 displacing the contact point between the roller **10c** and the swing cam surface **9b** and the contact point between the control-side depressing surface **10b** and the rocker-side depressed surface **11d**. This allows the opening duration of the valve **3** and the amount of the valve lift to continuously change by using a very simple structure that can be actuated 15 by solely rotating the rocker shaft **14**.

To the illustrated embodiments, the rocker-side depressed surface **11d** or its extension line **11d'** passes inside the rotation locus C of the axial center (c) of the eccentric pin **14b**, which is generated by rotating the rocker shaft **14**. Thus, enhanced transmission efficiency of the force from the control arm **10** to the rocker arm **11** can be more certainly 20 achieved.

According to the embodiment of FIGS. 1-3, offset displacement of the eccentric pin **14b** is preset so that the outer surface **14b'** of the eccentric pin **14b** protrudes outward from the outer surface **14a'** of the rocker shaft **14** in the radial direction. This can increase the displacement of the control arm **11** without increasing the diameter of the rocker shaft **14**, thereby increasing the adjustment range for the valve opening duration and amount of the valve lift. 25

For the eccentric pin **14b** protruding outward, an inner peripheral surface of the bearing portion **11c** of the rocker arm **11**, which is supported on the rocker shaft **14**, is formed with the clearance recess **11f** which conforms with the amount of protrusion of the eccentric pin **14b**. Thus, while the clearance recess **11f** fits the protrusion of the eccentric pin **14b**, the rocker arm **11** is displaced in the axial direction 30 of the rocker shaft **14**, so that the rocker arm **11** can be assembled to the rocker shaft **14** without any problem.

According to the embodiments described above, the displacement of the contact point relative to the rotation angle of the rocker shaft **14** in a low operation range, in which the opening duration of the valve **3** is short and the amount of the valve lift is small, is preset smaller than the displacement 35 of the contact point in a medium operation range in which the opening duration of the valve **3** and the amount of the valve lift are medium. This, in the low engine speed range, can avoid abrupt variations in engine output due to slight variations in rotation angle of the rocker shaft **14**, and can provide smooth operations, thereby avoiding jerky feeling.

The displacement of the contact point in a high operation range, in which the opening duration of the valve **3** is long and so forth, is preset smaller than the displacement of the contact point in a medium operation range. This, in the high engine speed range, can reduce a torque required for rotating rocker shaft **14**, and can provide smooth driving operations.

According to embodiment shown in FIG. 4, the semi-circular-shaped bearing portion **10d** is formed at and integrally with the proximal end of the control arm portion a, and rotatably supported with the eccentric pin **14b**, and the come-off prevention member is provided for preventing the 40

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bearing portion **10d** and the eccentric pin **14b** from separating from each other. This facilitates work for coupling the control arm **10** and the eccentric pin **14b**.

To be more specific, in the case of multi-cylinder engine, adjustments for uniform valve opening duration and amount of the valve lift are needed for all cylinders. Therefore, several control arms **10** within the dimensional tolerance range are prepared for selecting a combination to uniform the valve opening duration and the amount of the valve lift. Assembly and removal of the control arm to be carried out for selecting the combination are required to be easy. The illustrated embodiments can meet such a requirement.

According to the embodiment of FIGS. 1-3, the come-off prevention member is a leaf spring **15** for holding the bearing portion **10d** of the control arm portion **10a** and the eccentric pin **14b**. This further facilitates the assembly/removal of the control arm **10** to/from the rocker shaft **14**.

Also, the leaf spring **15** has the depressing portion **15b** integrally formed therewith and urging the control arm **10** by depressing the rocker arm **11** such that the roller **10c** comes into contact with the swing cam surface **9b**. Thus, the roller **10c** of the control arm **10** can be constantly in contact with the swing cam surface **9b** of the swing member **9** with a simple constitution. Therefore, a rolling contact of the roller **10c** with respect to the motion of the swing cam surface **9b** can be kept normal, thereby preventing the wearing of the swing cam surface **9b** and the roller **10c**.

According to the embodiments described above, the control arm **10** is brought into sliding contact with the step **14c** from the eccentric pin **14b** of the rocker shaft **14**, thereby being positioned in the axial direction. Also, the rocker arm **11** is brought into sliding contact with the axial end surface **10f** of the control arm **10**, thereby being positioned in the axial direction. Therefore, positioning of the control arm **10** and the rocker arm **11** in the axial direction can be achieved without any dedicate parts.

According to the embodiments described above, the center of swing (a) of the swing member **9** is located at a point opposite to the valve shaft line **L1** with respect to the straight line **L2** parallel to the valve shaft line **L1** and passing the axial center (b) of the rocker shaft **14**. This gives advantage to the rocker-side depressed surface **11d** or its extension line **11d'** to pass in the vicinity of the center of rotation (b) of the rocker arm **11**. More specifically, as an angle formed between the direction of the force **F** applied to the rocker arm **11** and the straight line **Lo** that connects the point (f) of application of the force **F** and the center of swing (b) of the rocker arm **11** is closer to the right angle, the transfer efficiency of the force increases. Since the center of swing (a) of the swing member **9** is located on the side opposite to the valve shaft line **L1**, the direction of the force **F** can be easily set perpendicular to the direction of the straight line **Lo**.

Although this invention has been disclosed in the context of certain preferred embodiments and examples, it will be understood by those skilled in the art that the present invention extends beyond the specifically disclosed embodiments to other alternative embodiments and/or uses of the invention and obvious modifications and equivalents thereof. In addition, while a number of variations of the invention have been shown and described in detail, other modifications, which are within the scope of this invention, will be readily apparent to those of skill in the art based upon this disclosure. It is also contemplated that various combinations or subcombinations of the specific features and aspects of the embodiments may be made and still fall within the scope of the invention. Accordingly, it should be under-

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stood that various features and aspects of the disclosed embodiments can be combine with or substituted for one another in order to form varying modes of the disclosed invention. Thus, it is intended that the scope of the present invention herein disclosed should not be limited by the particular disclosed embodiments described above, but should be determined only by a fair reading of the claims that follow.

What is claimed is:

1. A valve train device for an engine is configured to pivot a rocker arm supported on a rocker arm support shaft to drive a valve which opens and closes a valve opening formed in a combustion chamber, the device comprising:

a valve drive device;

a swing member pivotally supported on a swing member support shaft and driven to pivot about the swing member support shaft by the valve drive device;

a control arm, which is disposed between a swing cam surface formed on the swing member and a rocker-side surface formed on the rocker arm, for transferring motion of the swing cam surface to the rocker-side surface; and

a displacement mechanism for displacing a contact point between the control arm and the swing cam surface and a contact point between the control arm and the rocker-side surface;

wherein the rocker-side surface has an arcuate shape which arcs about a center of pivoting motion of the swing member and wherein the rocker-side surface or line extending from the rocker-side surface about said center of pivoting motion of the swing member passes substantially near a center of swing of the rocker arm.

2. The valve train device for an engine according to claim 1, wherein the rocker-side surface or the extension of the rocker-side surface lies substantially near a straight line that connects the center of pivoting motion of the rocker arm to the contact point between the control arm and the rocker side surface.

3. The valve train device for an engine according to claim 1, wherein the rocker-side surface at least partially forms a recess in the rocker arm.

4. The valve train device for an engine according to claim 1, wherein the extension of the rocker-side surface extends through the rocker arm support shaft.

5. The valve train device for an engine according to claim 1, wherein the rocker arm comprises left and right rocker arm portions that are supported by the rocker arm support shaft and are coupled together by a rocker coupling portion.

6. The valve train device for an engine according to claim 5, wherein the control arm comprises a control arm portion with a distal end that forms a control-side surface that contacts the rocker arm; and a contact portion provided at the distal end of the control arm portion that contacts the swing cam surface, the control arm being interposed between the left and right rocker arm portions, and the rocker-side surface being formed on the rocker coupling portion.

7. The valve train device for an engine according to claim 6, wherein the contact portion of the control arm, is a roller supported at the distal end of the control arm portion.

8. The valve train device for an engine according to claim 1, wherein the rocker arm has a rocker arm portion pivotally supported on the rocker arm support shaft and the control arm includes a roller that comes into contact with the swing cam surface, the roller being positioned externally, with respect to the longitudinal axis of the rocker arm support shaft, to the rocker arm.

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9. The valve train device for an engine according to claim 8, comprising a roller shaft that supports the roller of the control arm, the roller shaft forming a control-side surface which comes into contact with the rocker-side surface formed on the rocker arm.

10. The valve train device for an engine according to claim 1, wherein the displacement mechanism comprises an eccentric pin that is positioned on the rocker support shaft.

11. The valve train device for an engine according to claim 10, wherein the eccentric pin is positioned on a midsection of the rocker support shaft, and a proximal end of the control arm is rotatably coupled to the eccentric pin, and rotating the rocker shaft allows displacing the contact point between the control arm and the swing cam surface and the contact point between the control arm and the rocker-side surface.

12. The valve train device for an engine according to claim 10, wherein the rocker-side surface or the extension of the rocker-side surface passes inside a circle defined by a rotation locus of an axial center of the eccentric pin, which is generated by rotating the rocker support shaft.

13. The valve train device for an engine according to claim 10, wherein the eccentric pin has a surface that protrudes outward from an outer surface of the rocker arm support shaft in a radial direction.

14. The valve train device for an engine according to claim 13, wherein an inner peripheral surface of a bearing portion of the rocker arm supported on the rocker arm support shaft includes a clearance recess that conforms to the protrusion of the eccentric pin.

15. The valve train device for an engine according to claim 10, wherein the displacement mechanism is configured such that displacement of the contact point between the control arm and the swing cam surface relative to the rotation angle of the rocker arm support shaft in a low or high operation range, in which the opening duration of the valve is short or long and the amount of the valve lift is small or large, is smaller than the displacement of the contact point between the control arm and the swing cam surface in a medium operation range in which the opening duration of

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the valve and the amount of the valve lift are between the low and high operation range.

16. The valve train device for an engine according to claim 10, wherein a coupling portion of the control arm portion with the eccentric pin includes a semi-circular-shaped bearing portion formed integrally with a proximal end of the control arm portion, and is rotatably supported with the eccentric pin.

17. The valve train device according to claim 16, further comprising a come-off prevention member that is configured to prevent the bearing portion and the eccentric pin from separating from each other.

18. The valve train device for an engine according to claim 17, wherein the come-off prevention member is a leaf spring configured to hold the bearing portion of the control arm portion and the eccentric pin, and the leaf spring has a depressing portion integrally formed therewith and urging the control arm by depressing the rocker arm such that the roller comes into contact with the swing cam surface.

19. The valve train device for an engine according to claim 10, wherein the valve train device is configured such that the control arm is brought into sliding contact with an axially facing step from the eccentric pin of the rocker arm support shaft and the rocker arm is brought into sliding contact with an axially facing end surface of the control arm.

20. The valve train device for an engine according to claim 1, wherein a valve shaft line extends through a longitudinal axis of the valve, a second line lies parallel to the valve shaft line and passes through an axial axis of the rocker arm support shaft and between a center of pivoting motion of the swing member and the valve shaft line.

21. The valve train device for an engine according to claim 1, wherein the valve drive device comprise a camshaft.

22. The valve train device for an engine according to claim 21, wherein the valve drive device comprise a camshaft for an intake valve.

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