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(12) **United States Patent**
Muramatsu

(10) **Patent No.:** **US 7,012,178 B2**
(45) **Date of Patent:** **Mar. 14, 2006**

(54) **COMPACT MUSICAL INSTRUMENT
EQUIPPED WITH AUTOMATIC PLAYER**

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(73) Assignee: **Yamaha Corporation, (JP)**

(*) Notice: Subject to any disclaimer, the term of this patent is extended or adjusted under 35 U.S.C. 154(b) by 248 days.

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(22) Filed: **Feb. 11, 2003**

(65) **Prior Publication Data**

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(30) **Foreign Application Priority Data**

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Mar. 20, 2002	(JP)	2002-079132
Mar. 20, 2002	(JP)	2002-079133
Mar. 20, 2002	(JP)	2002-079134
Mar. 20, 2002	(JP)	2002-079151

(51) **Int. Cl.**
G10F 1/06 (2006.01)

(52) **U.S. Cl.** **84/97; 84/100**

(58) **Field of Classification Search** 84/100,
84/94.2, 94.1, 95.1, 95.2, 96-99
See application file for complete search history.

(56) **References Cited**

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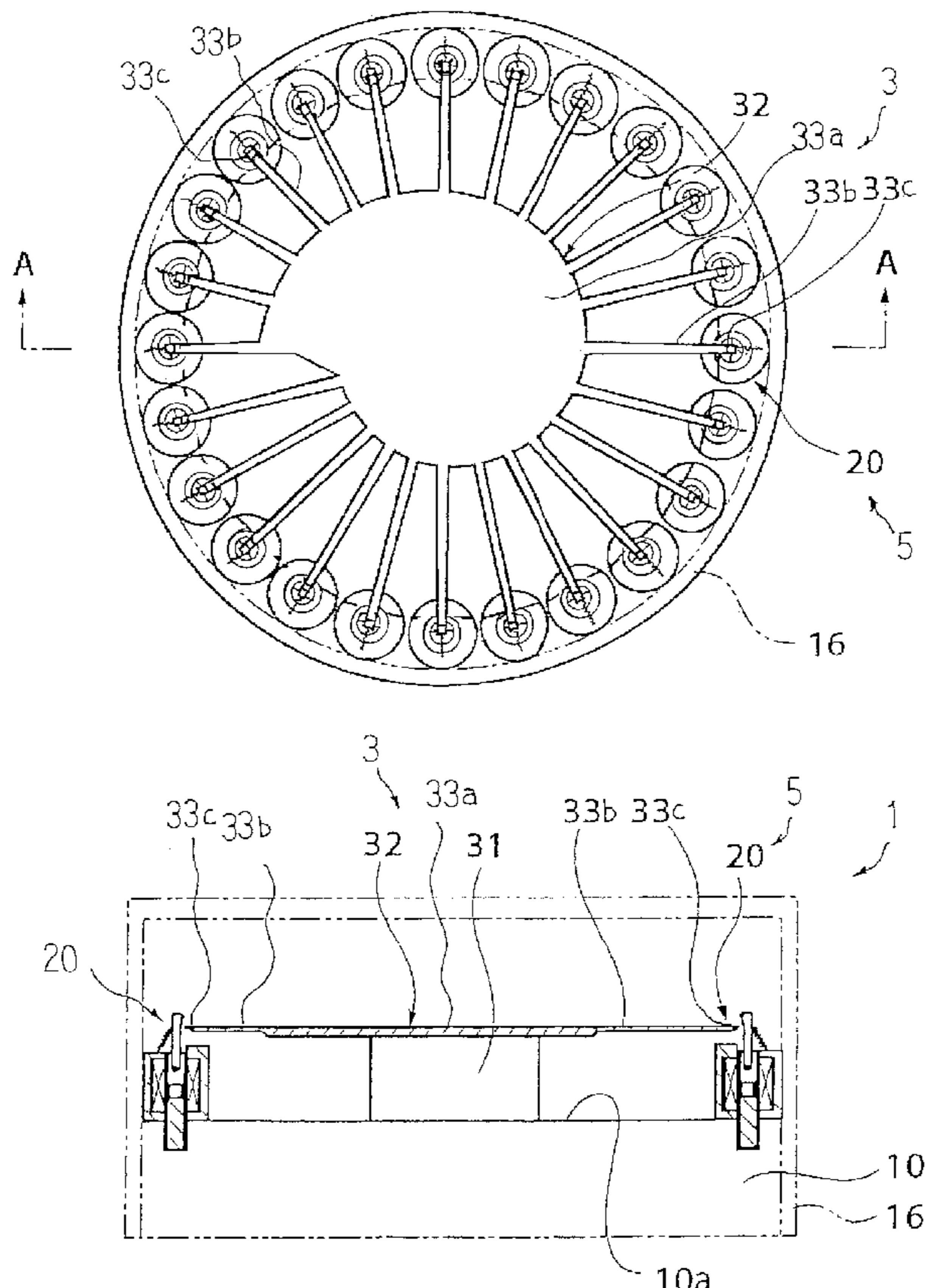
Primary Examiner—Kimberly Lockett

(74) *Attorney, Agent, or Firm*—Dickstein, Shapiro, Morin & Oshinsky, L.L.P.

(57) **ABSTRACT**

A music box includes a daisy reed wheel having reeds radially projecting from a hub for generating tones and solenoid-operated player's fingers arranged around the daisy reed wheel; the tips of the reeds are widely spaced from one another by virtue of the radial arrangement so that large-sized solenoid-operated actuators are used for the player's fingers; this results in the compact music box.

36 Claims, 57 Drawing Sheets



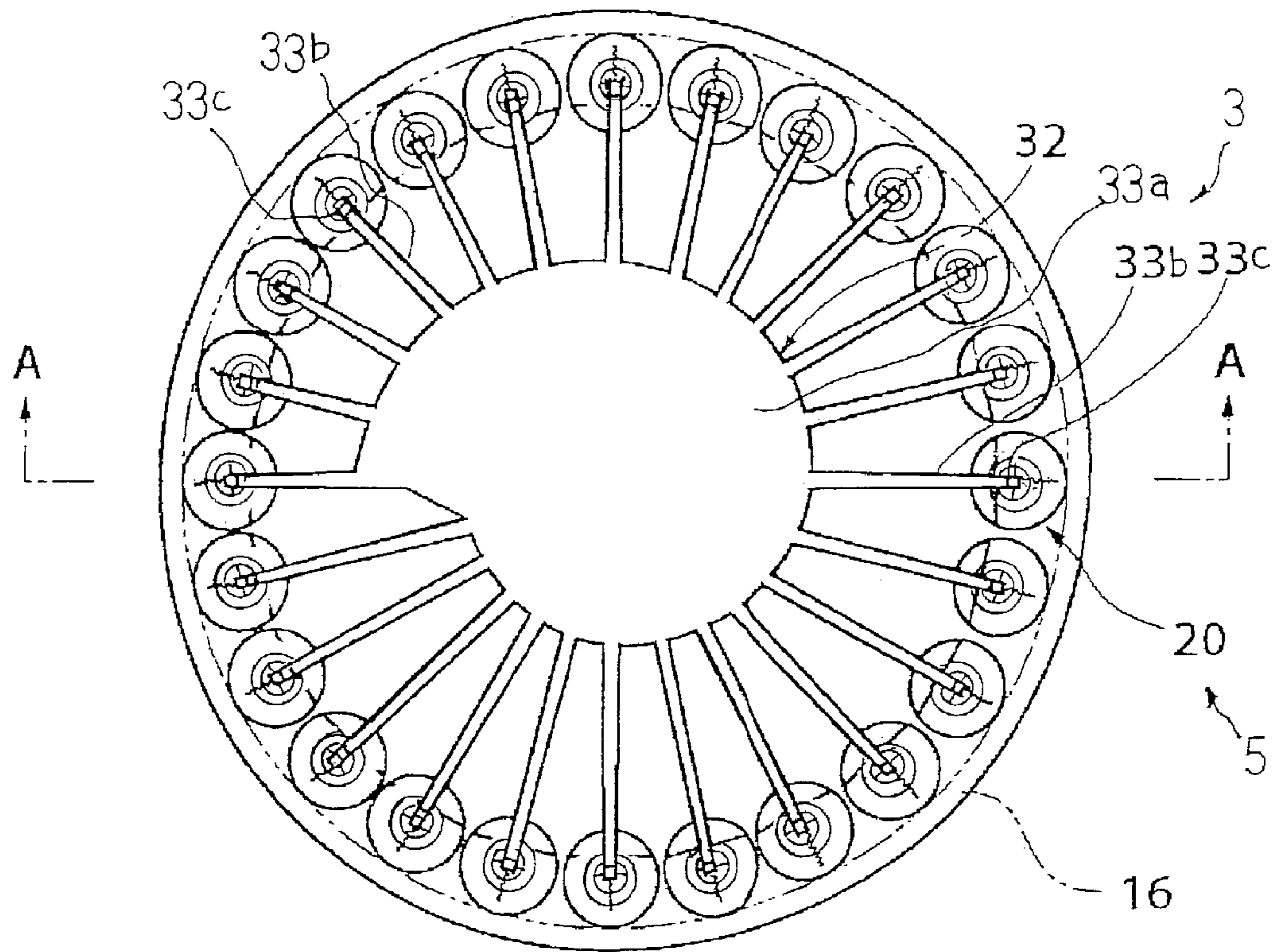


Fig. 1A

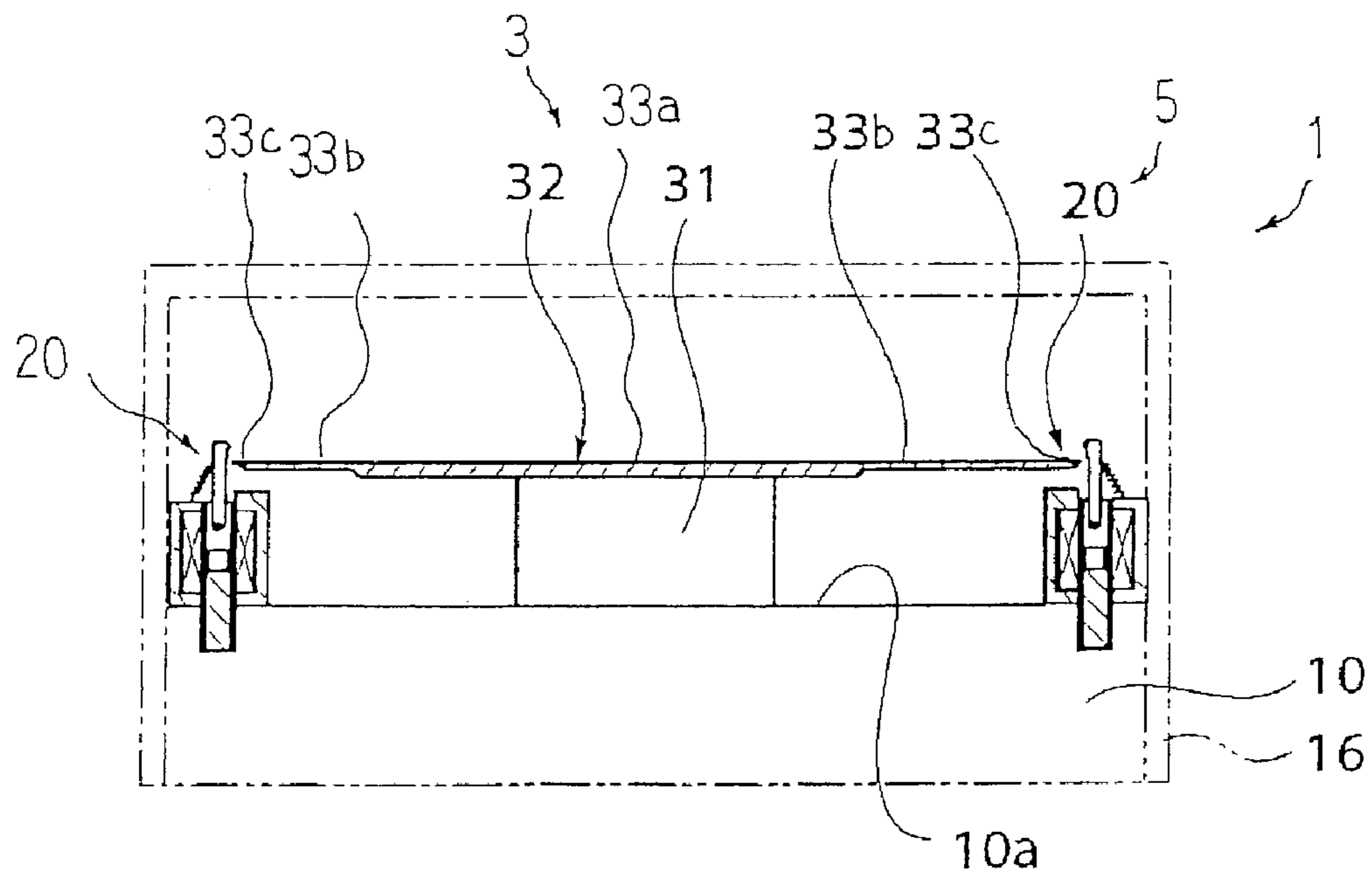
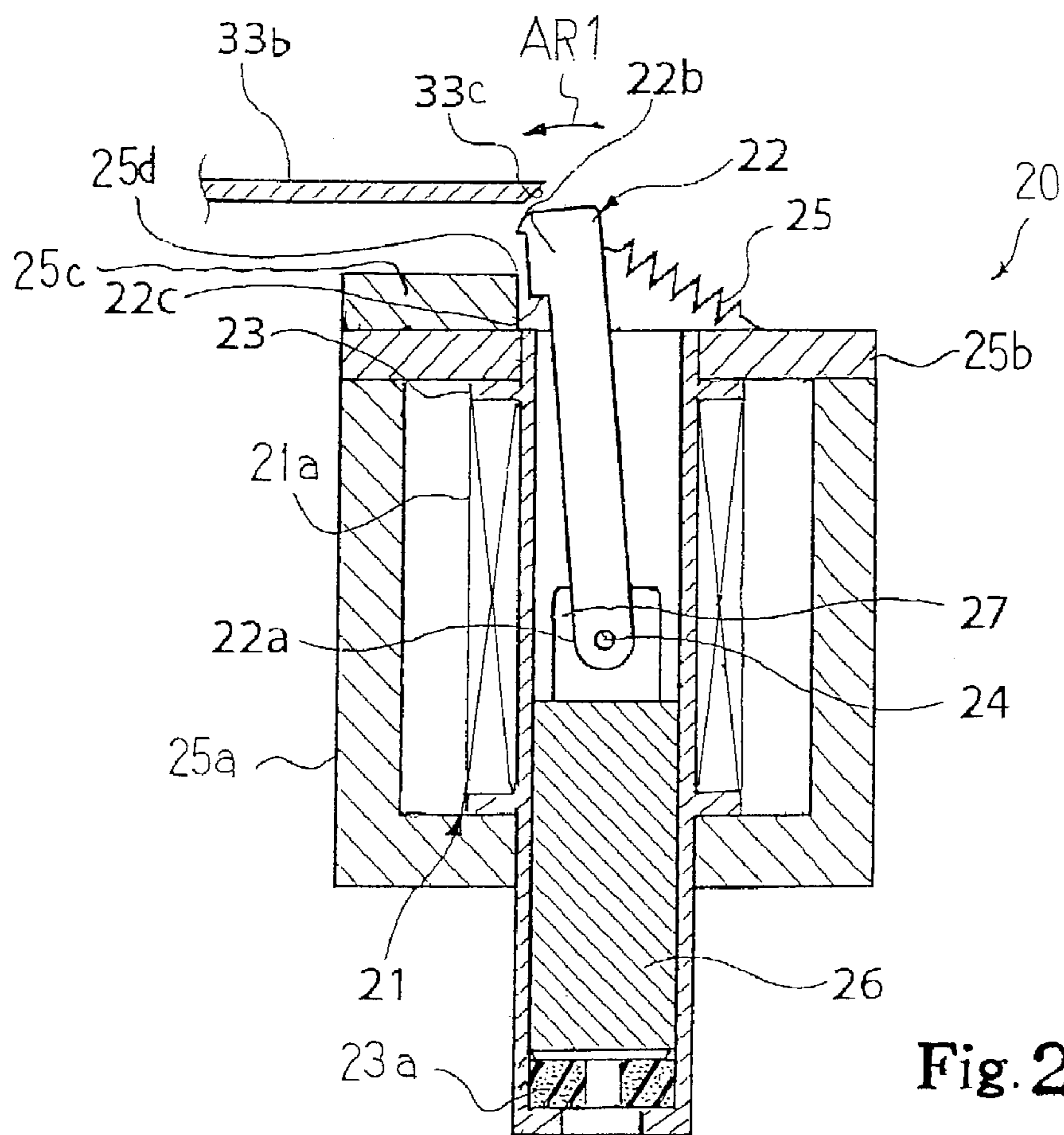
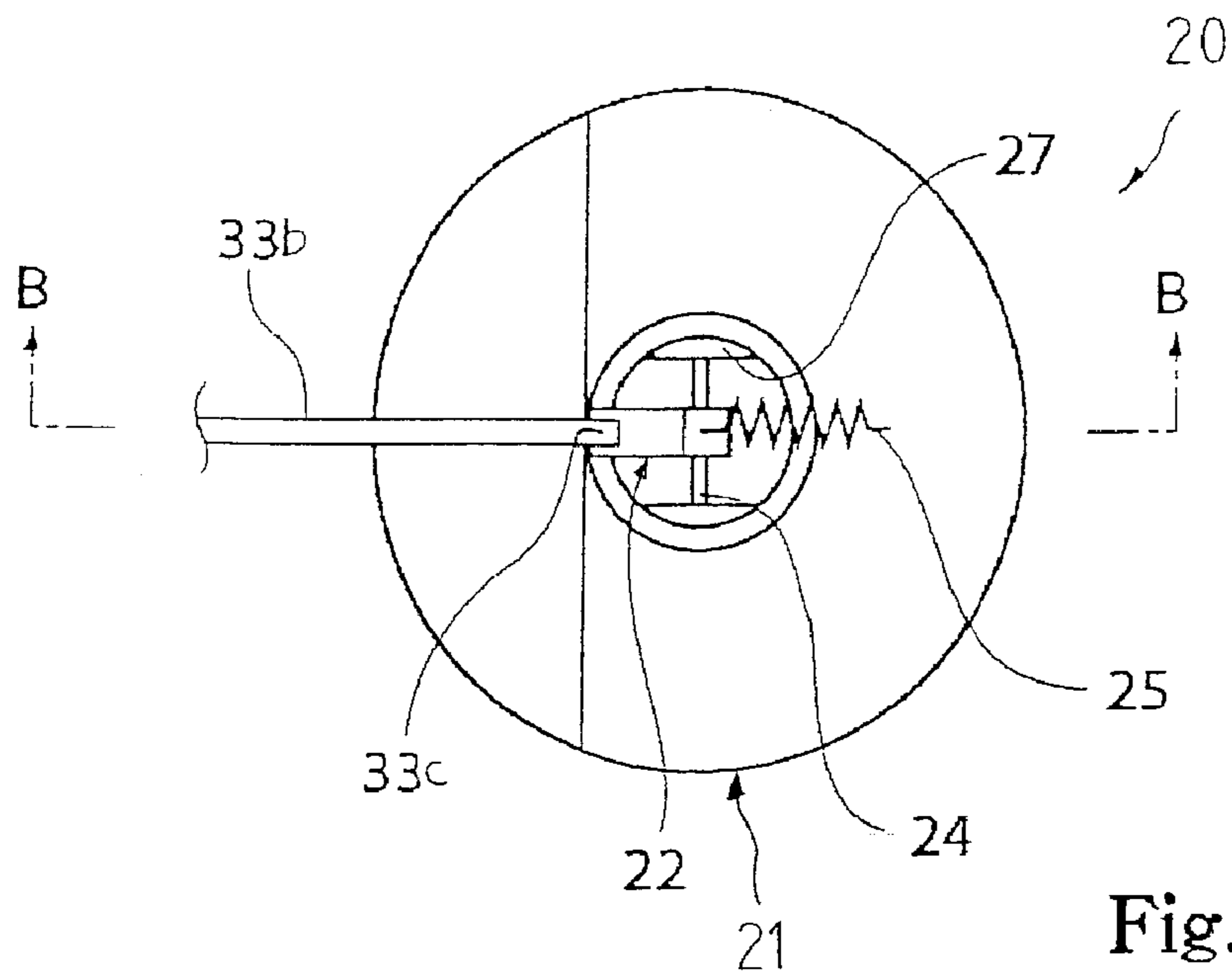


Fig. 1B



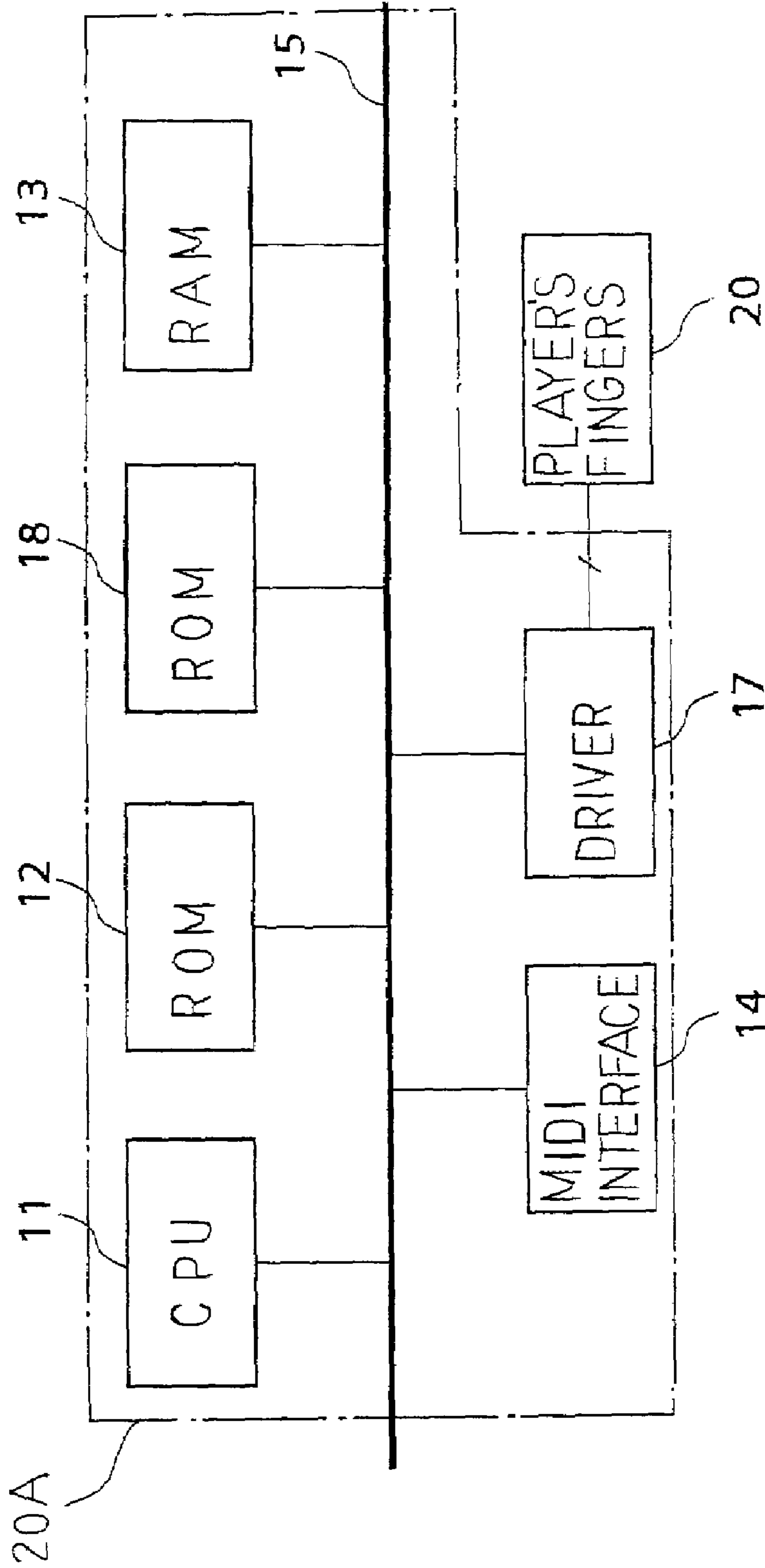


Fig. 3

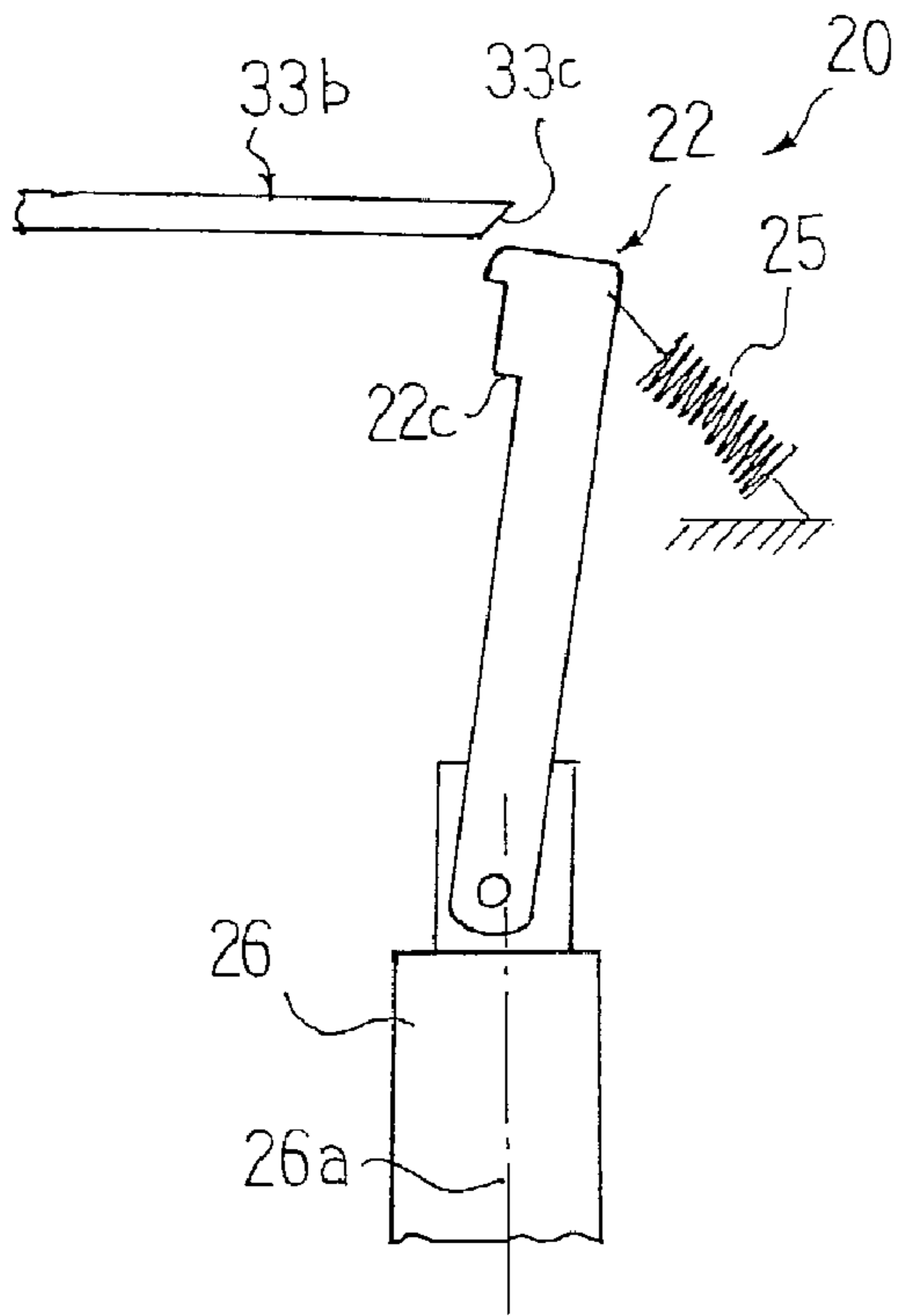


Fig. 4 A

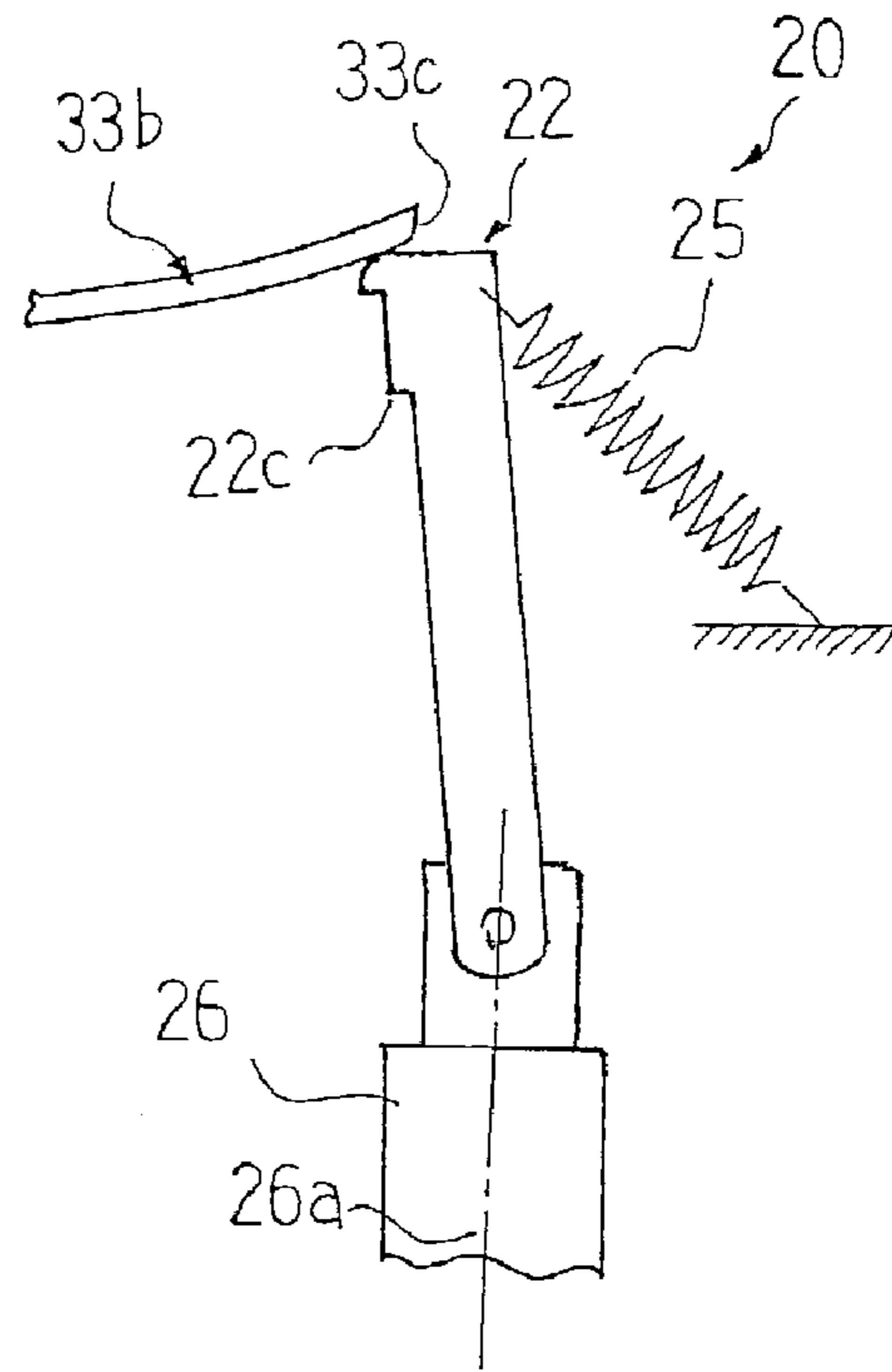


Fig. 4 B

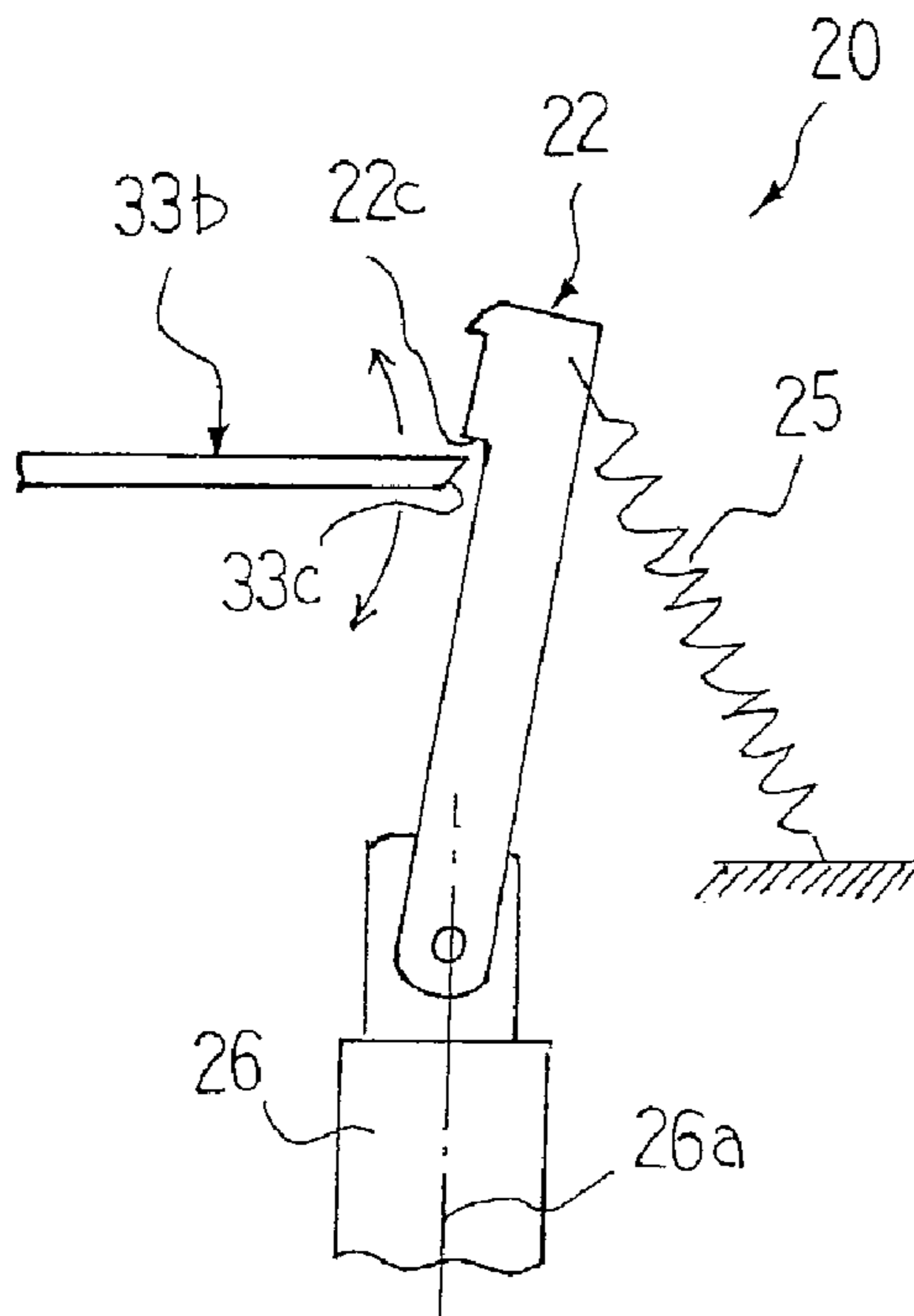


Fig. 4 C

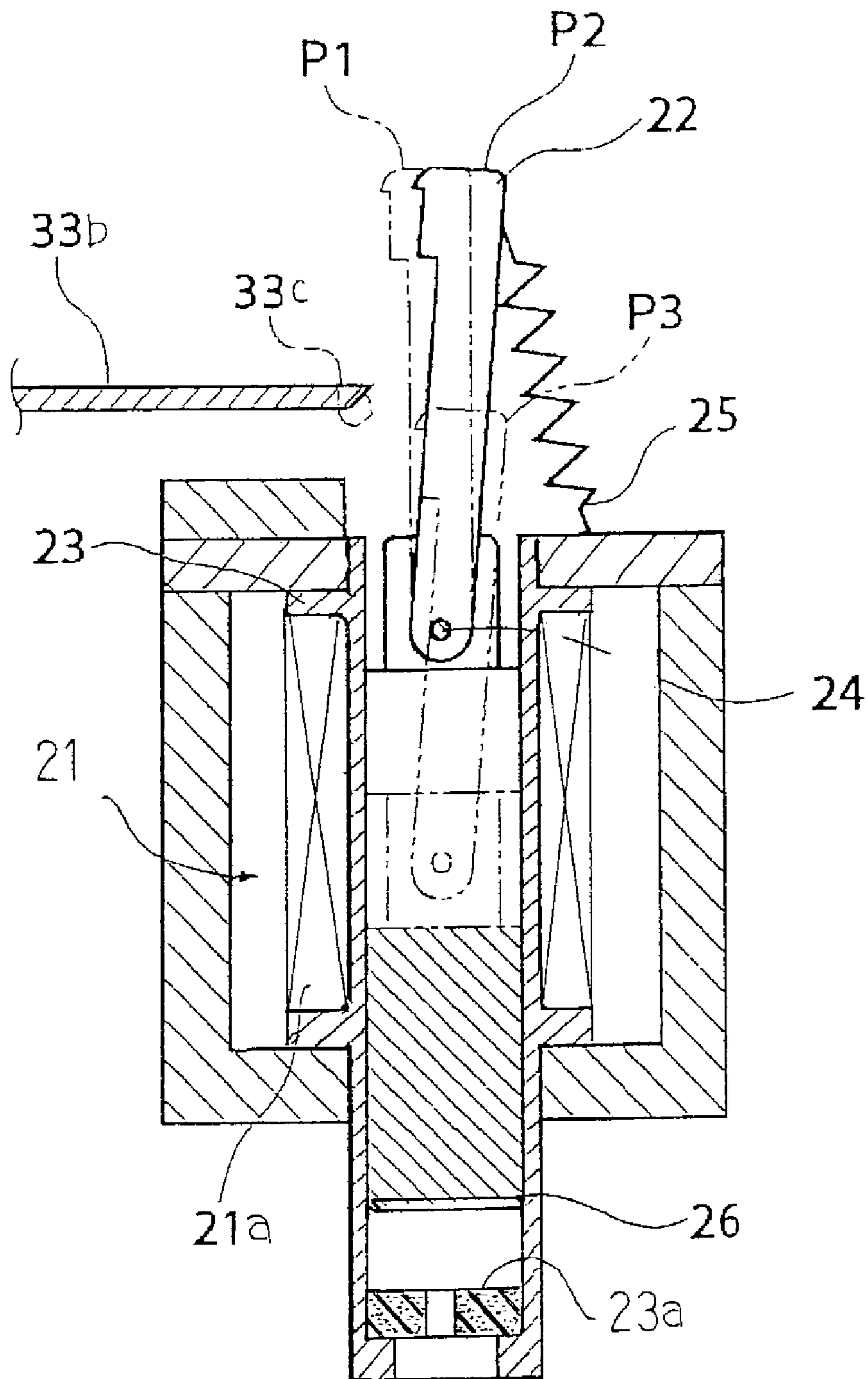


Fig. 5

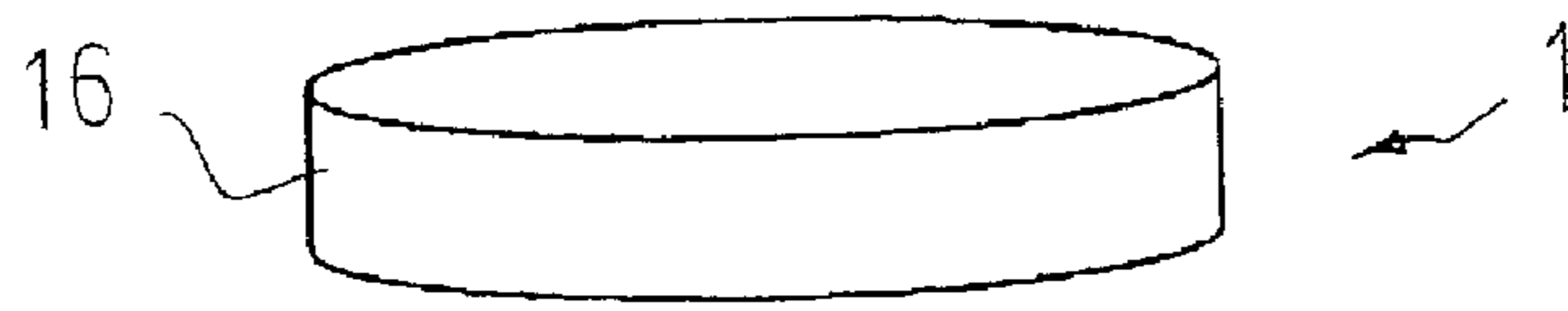


Fig. 6 A

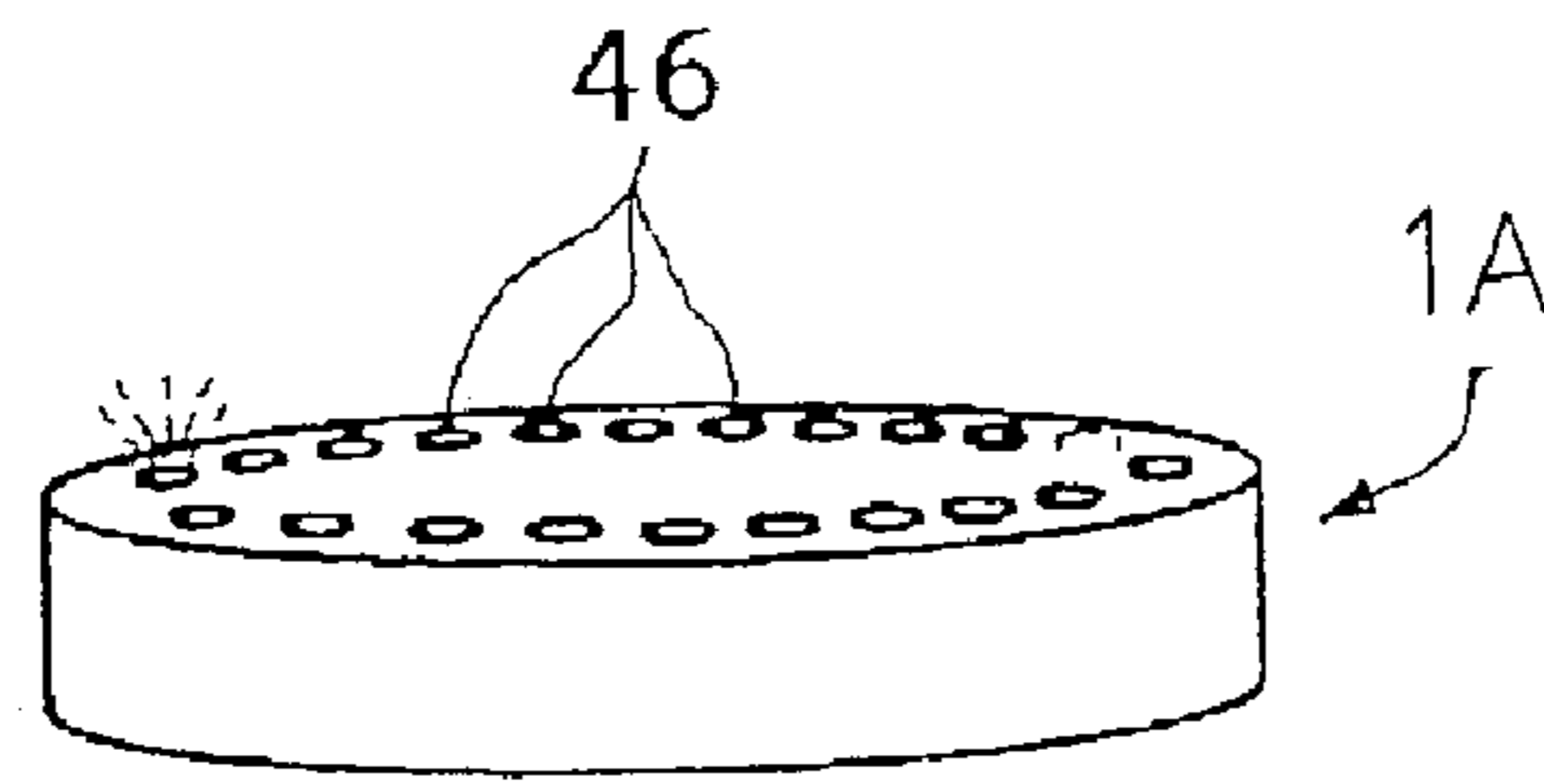


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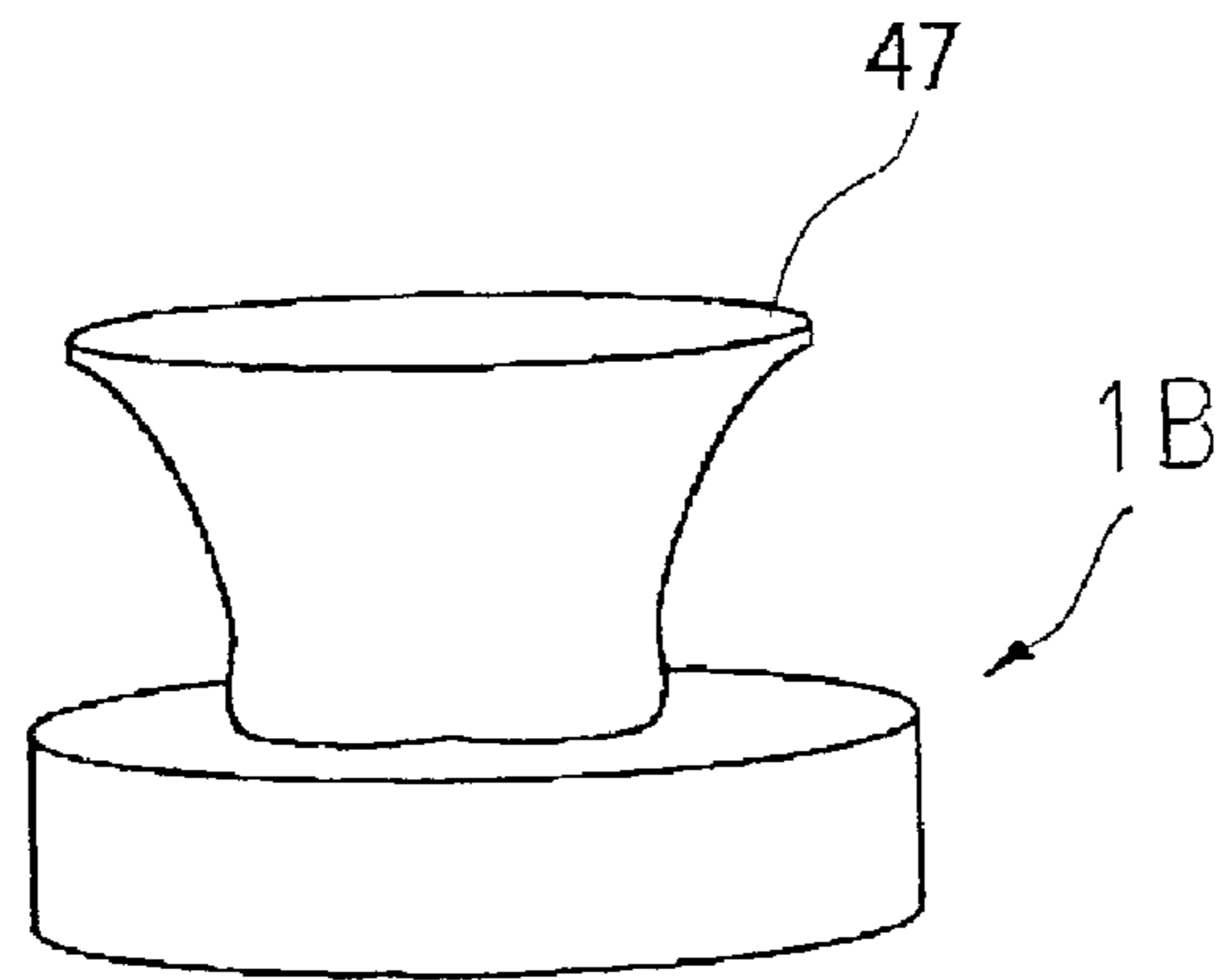


Fig. 6 C

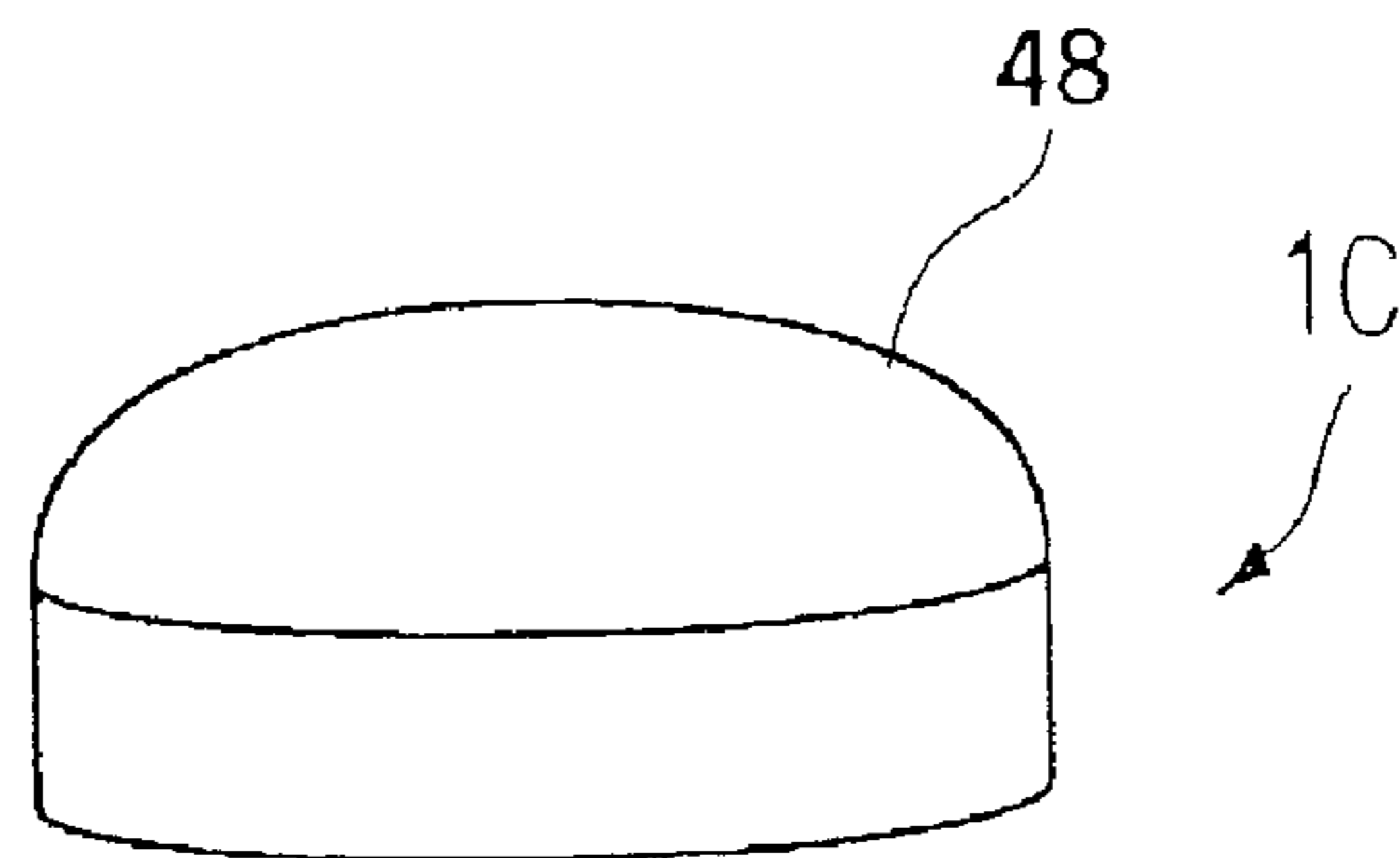


Fig. 6 D

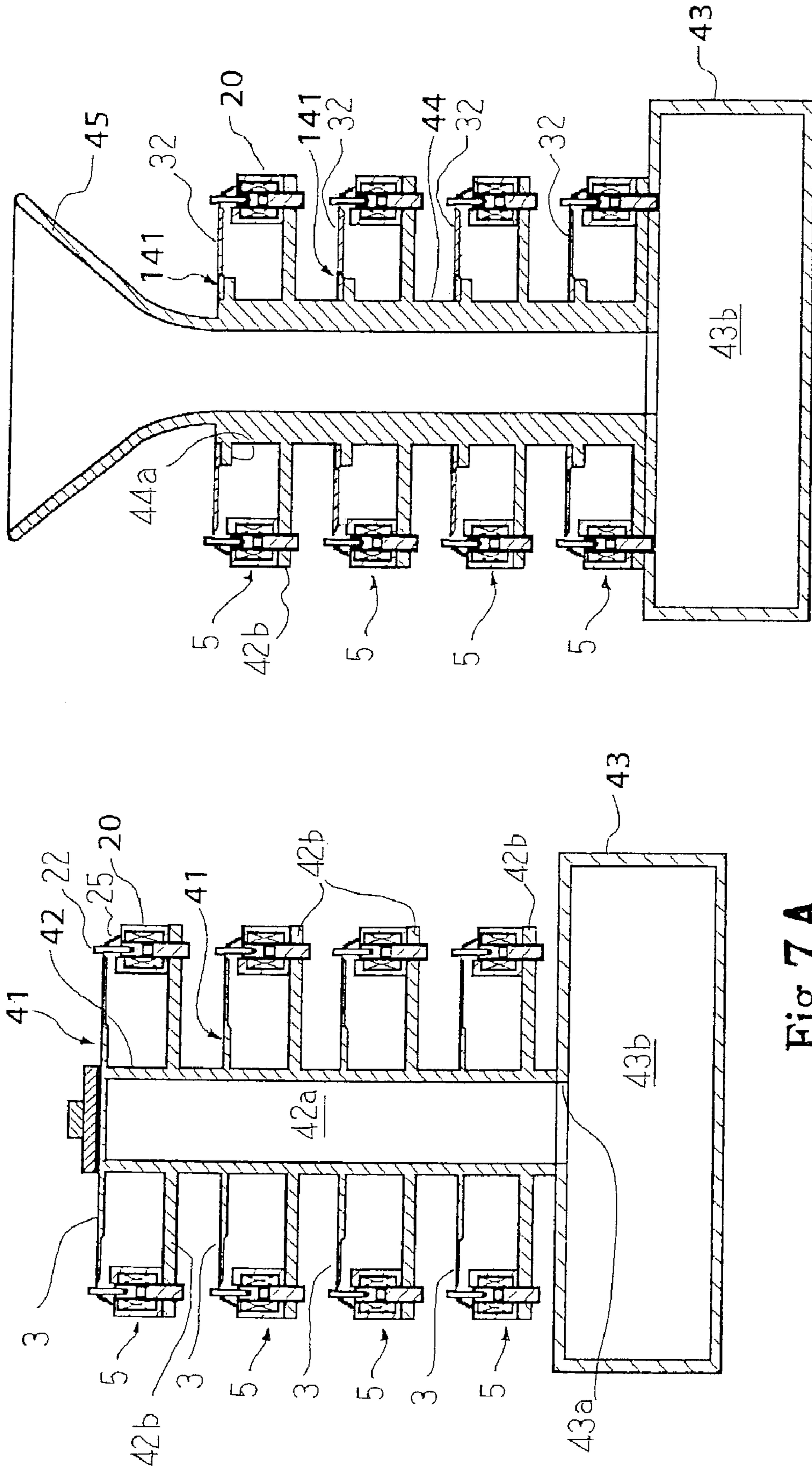


Fig. 7 A

Fig. 7 B

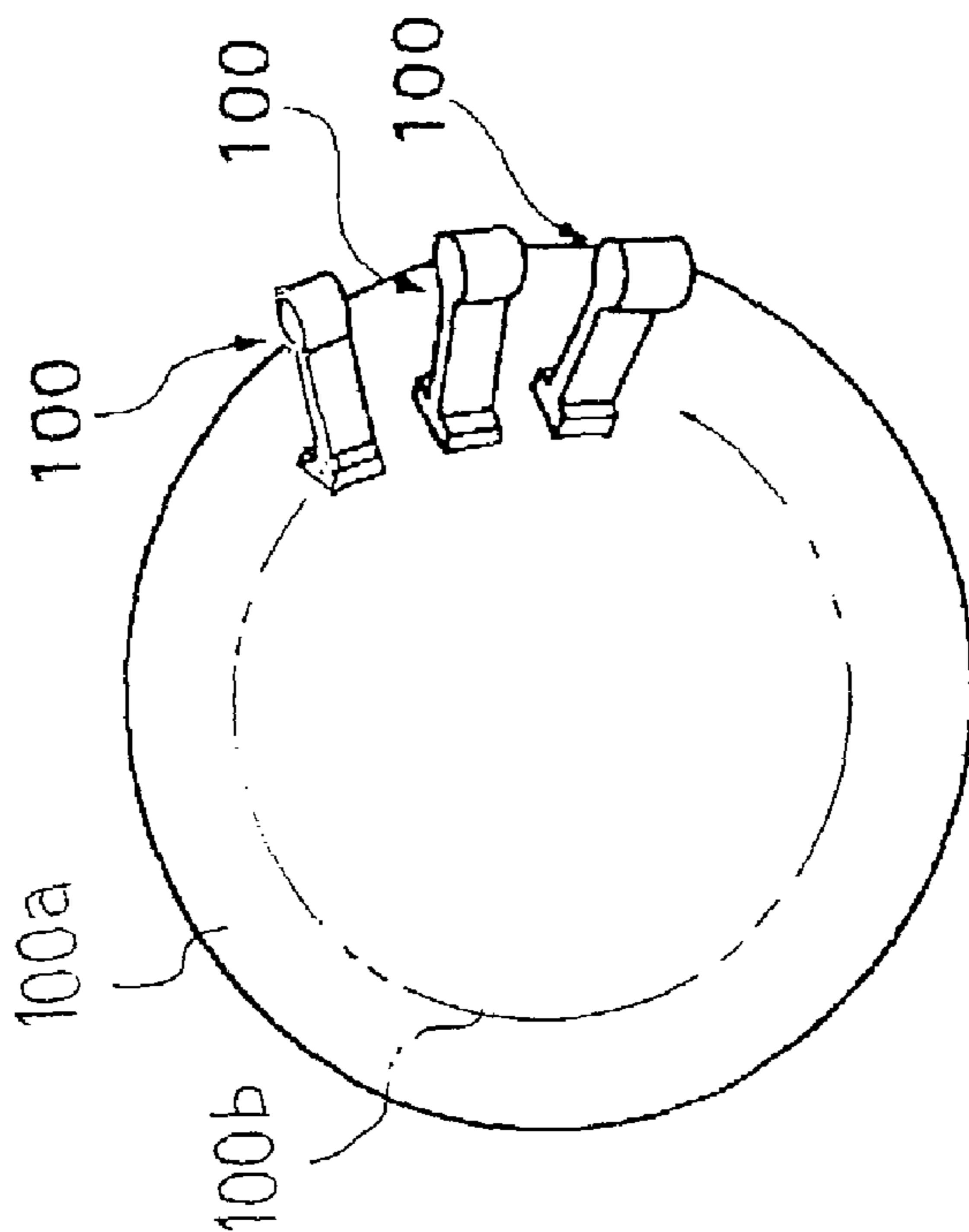


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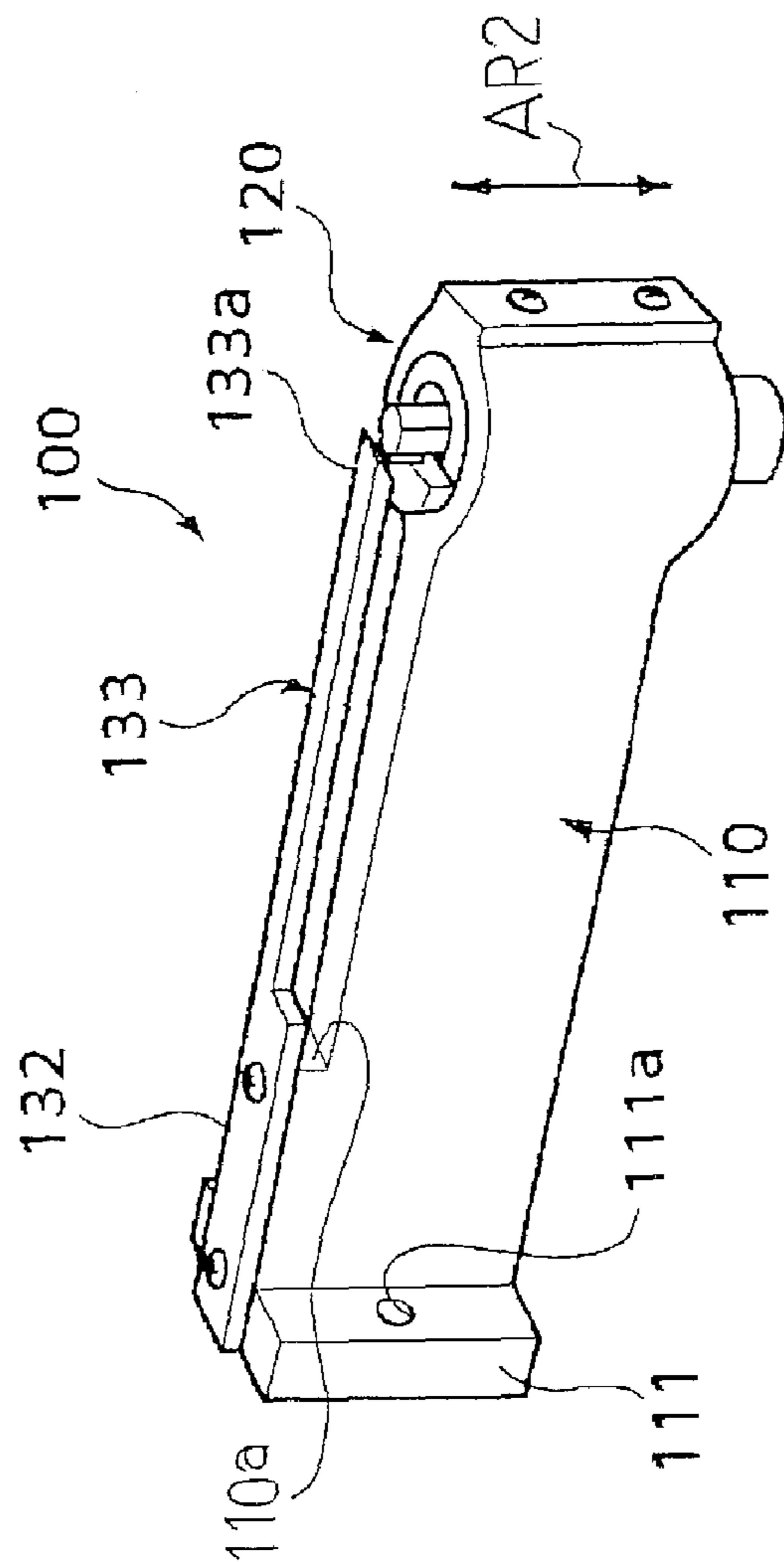


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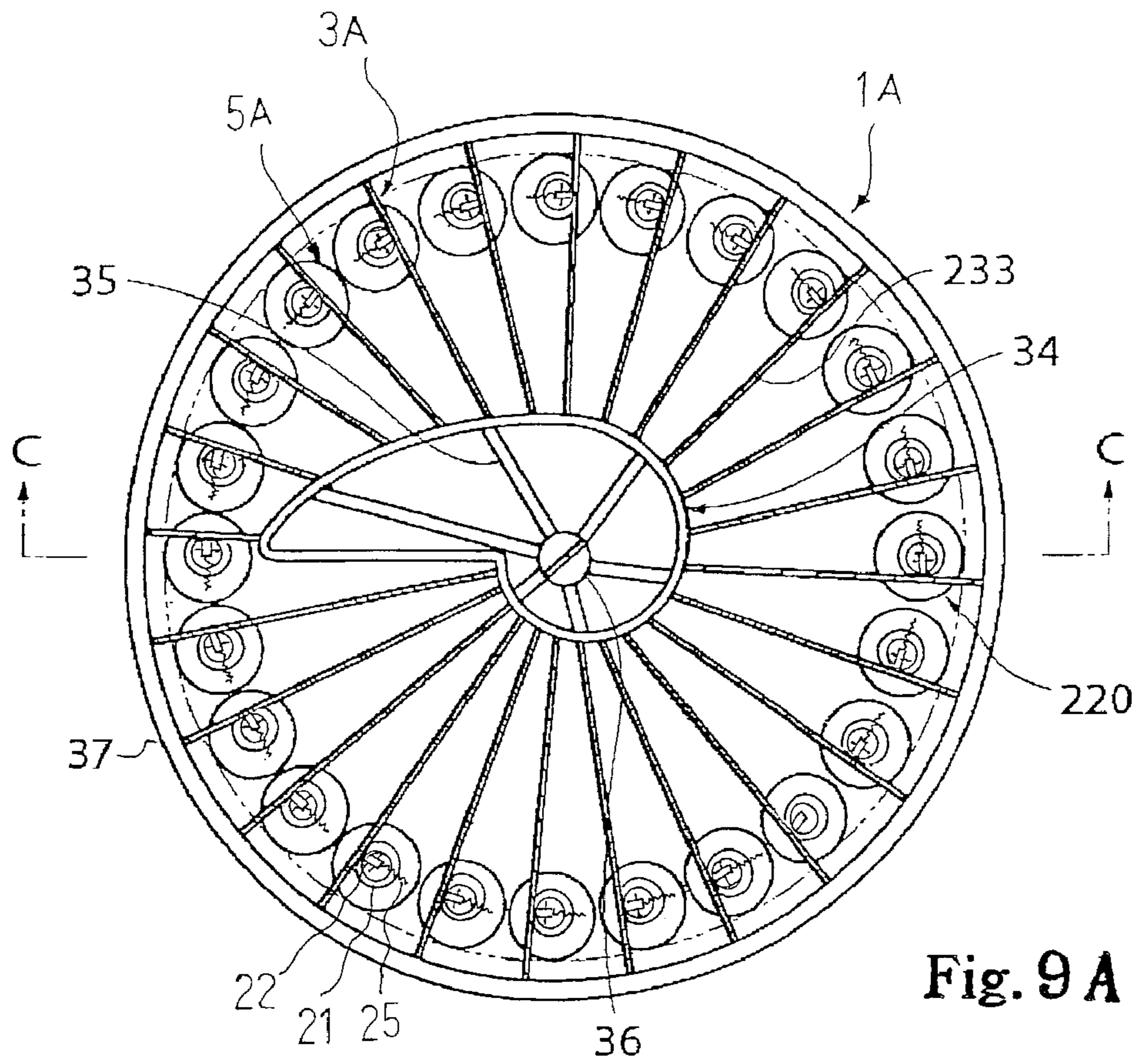


Fig. 9 A

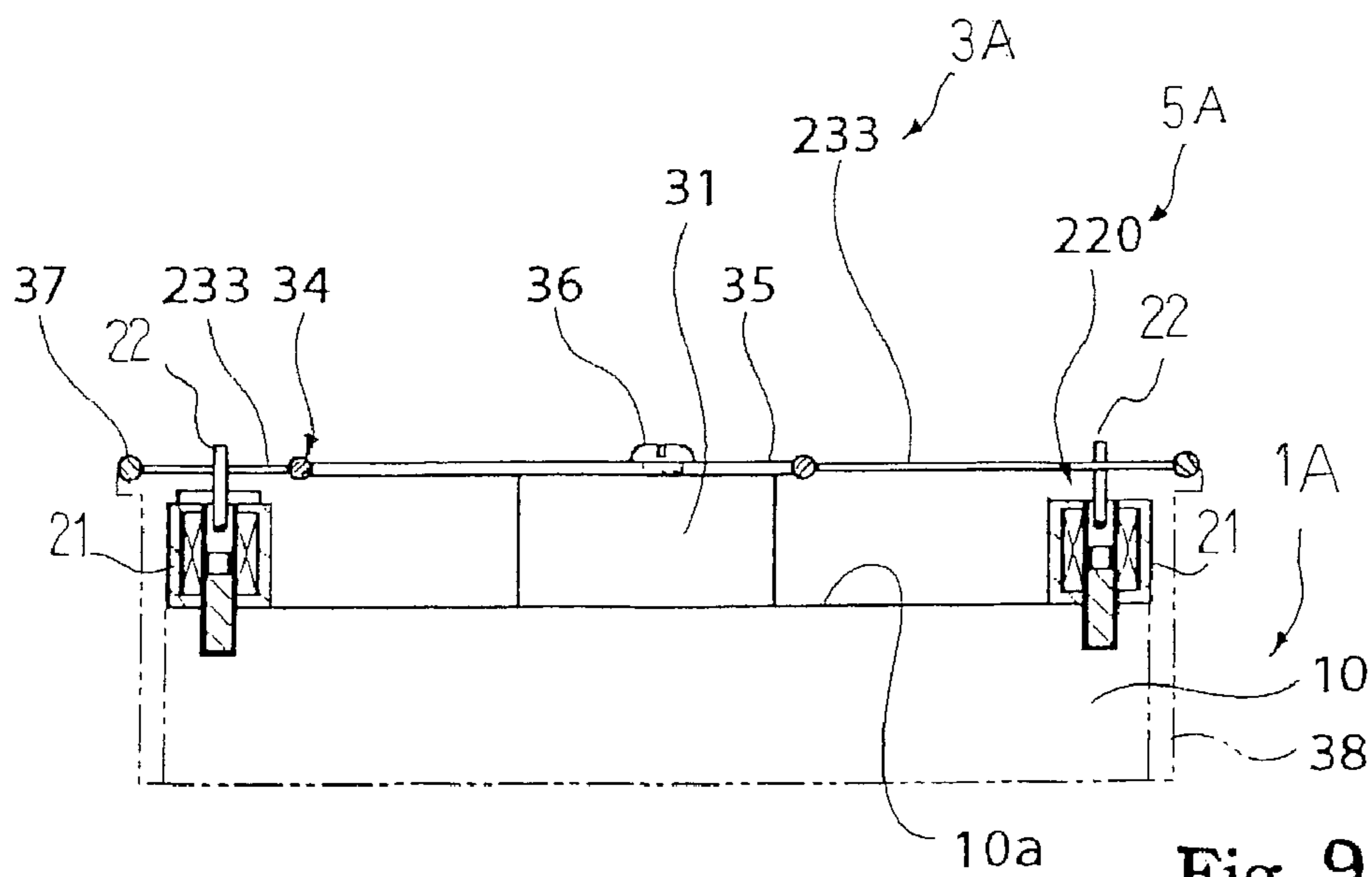


Fig. 9 B

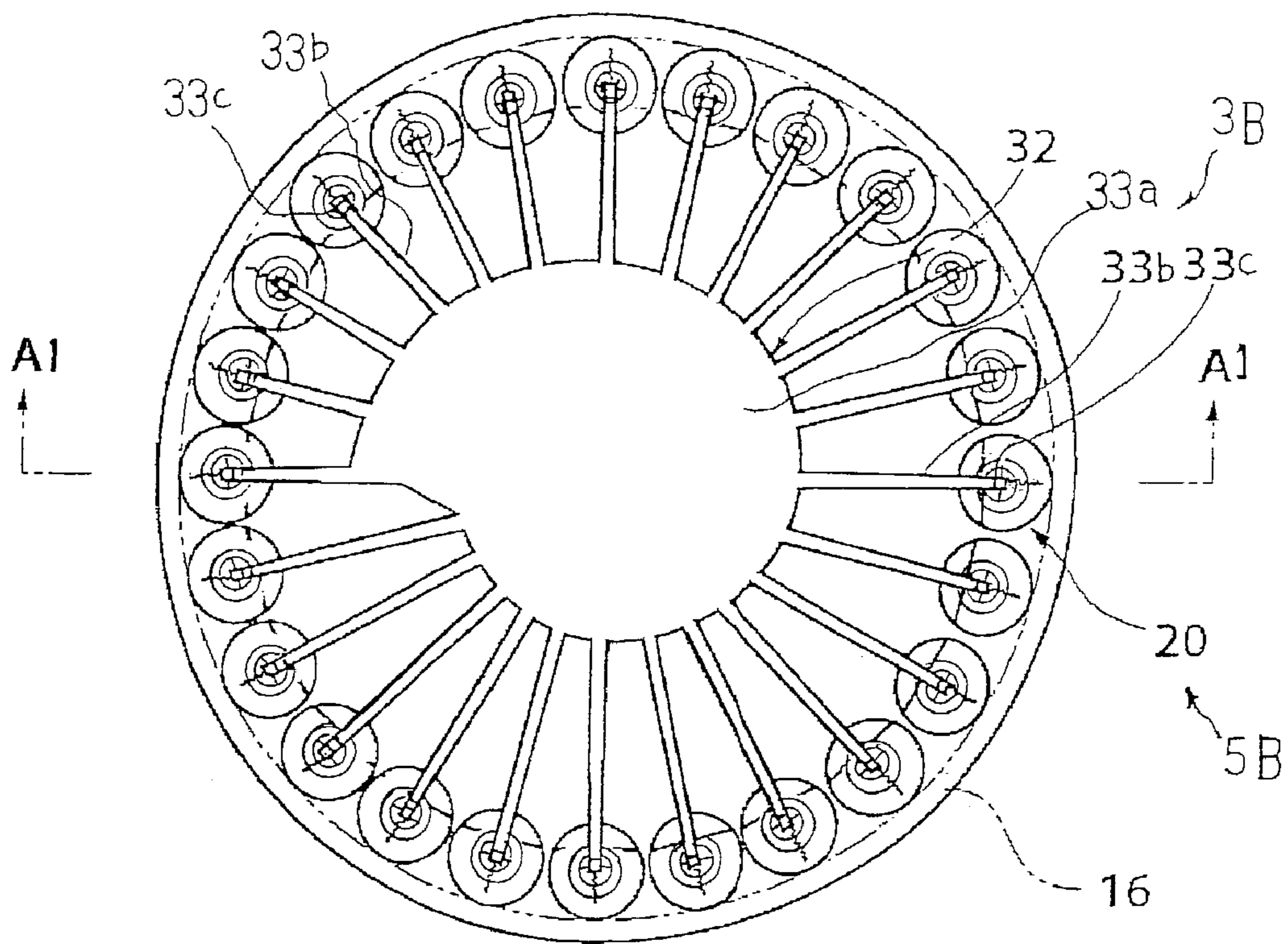


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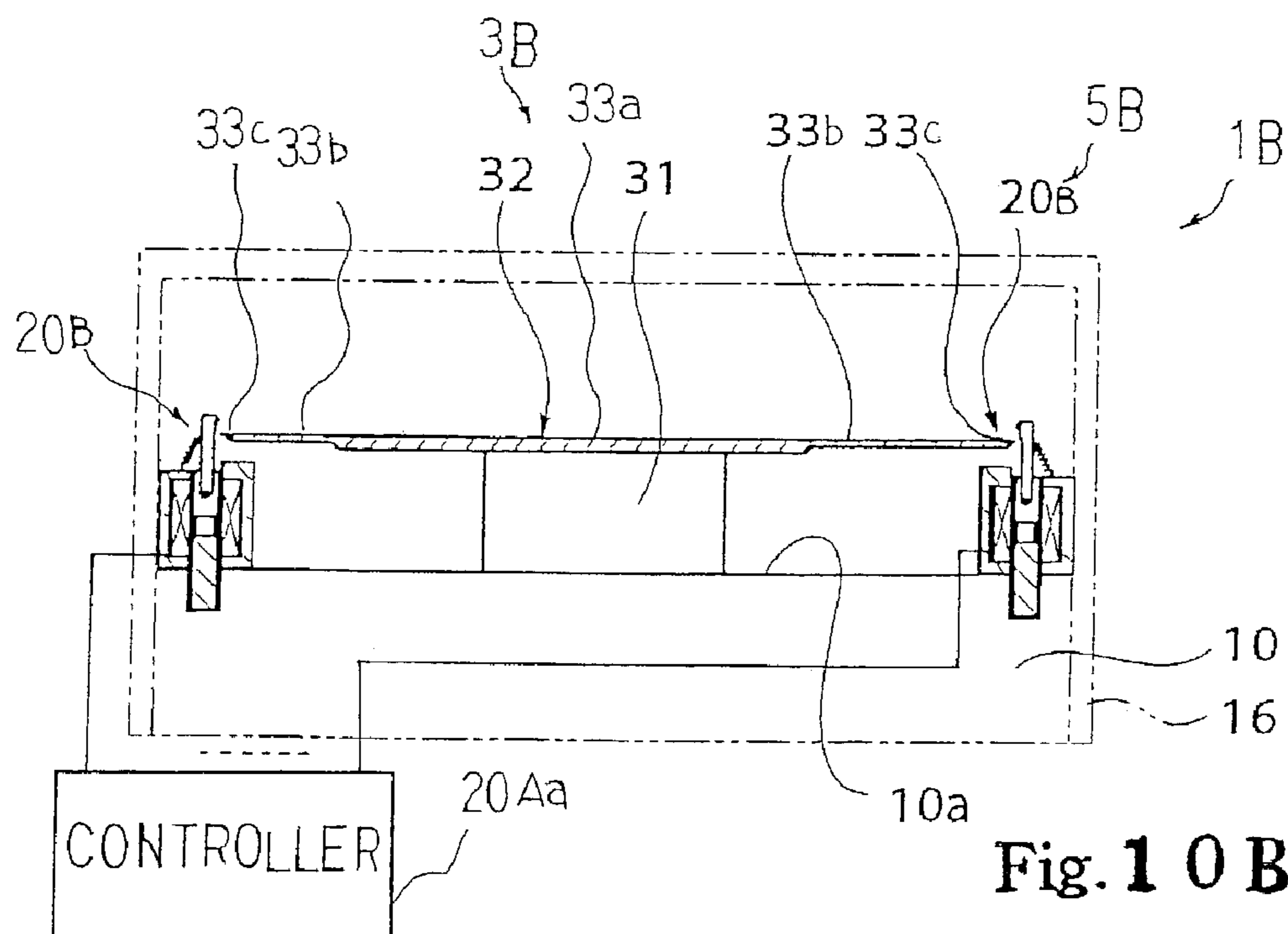


Fig. 10B

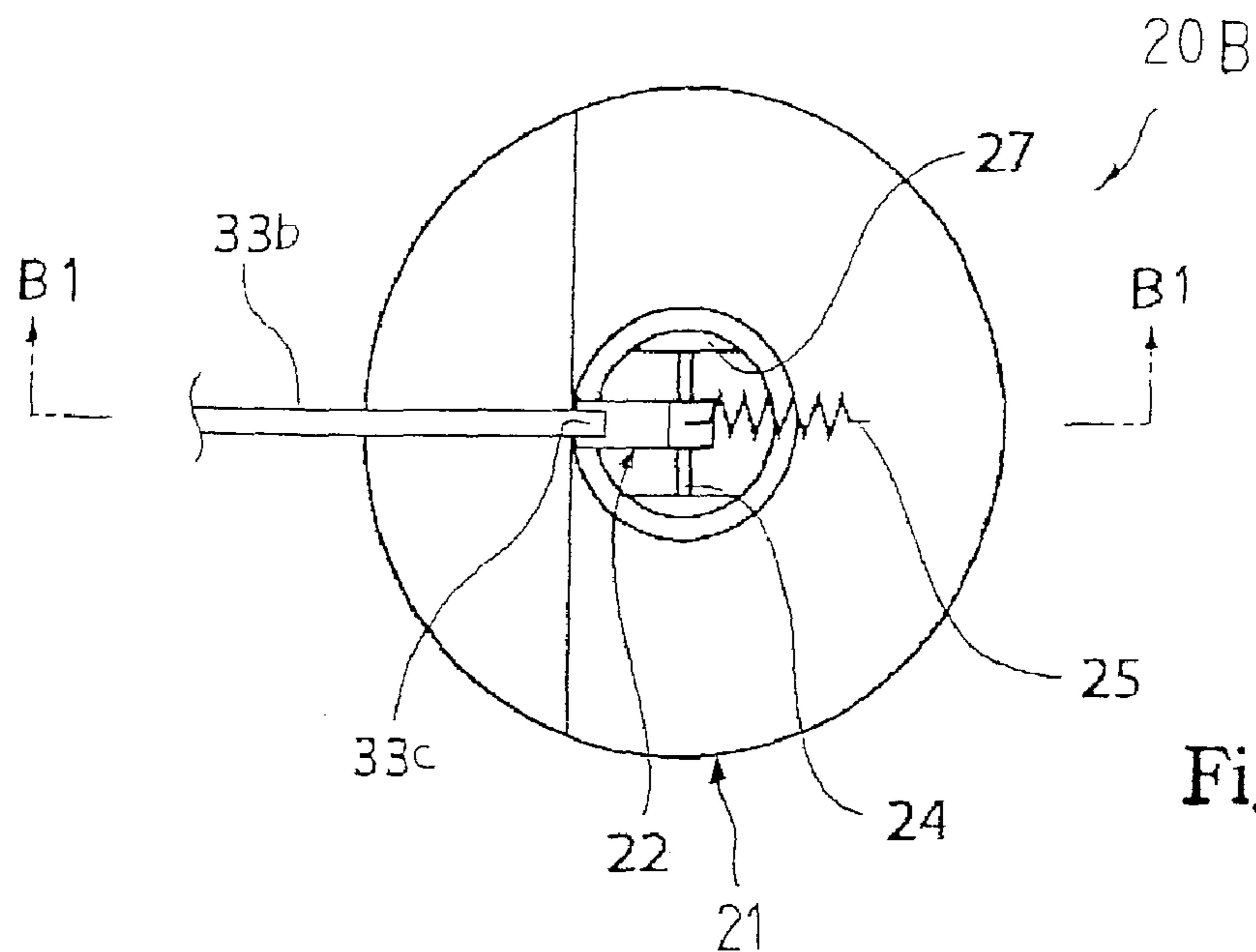


Fig. 11 A

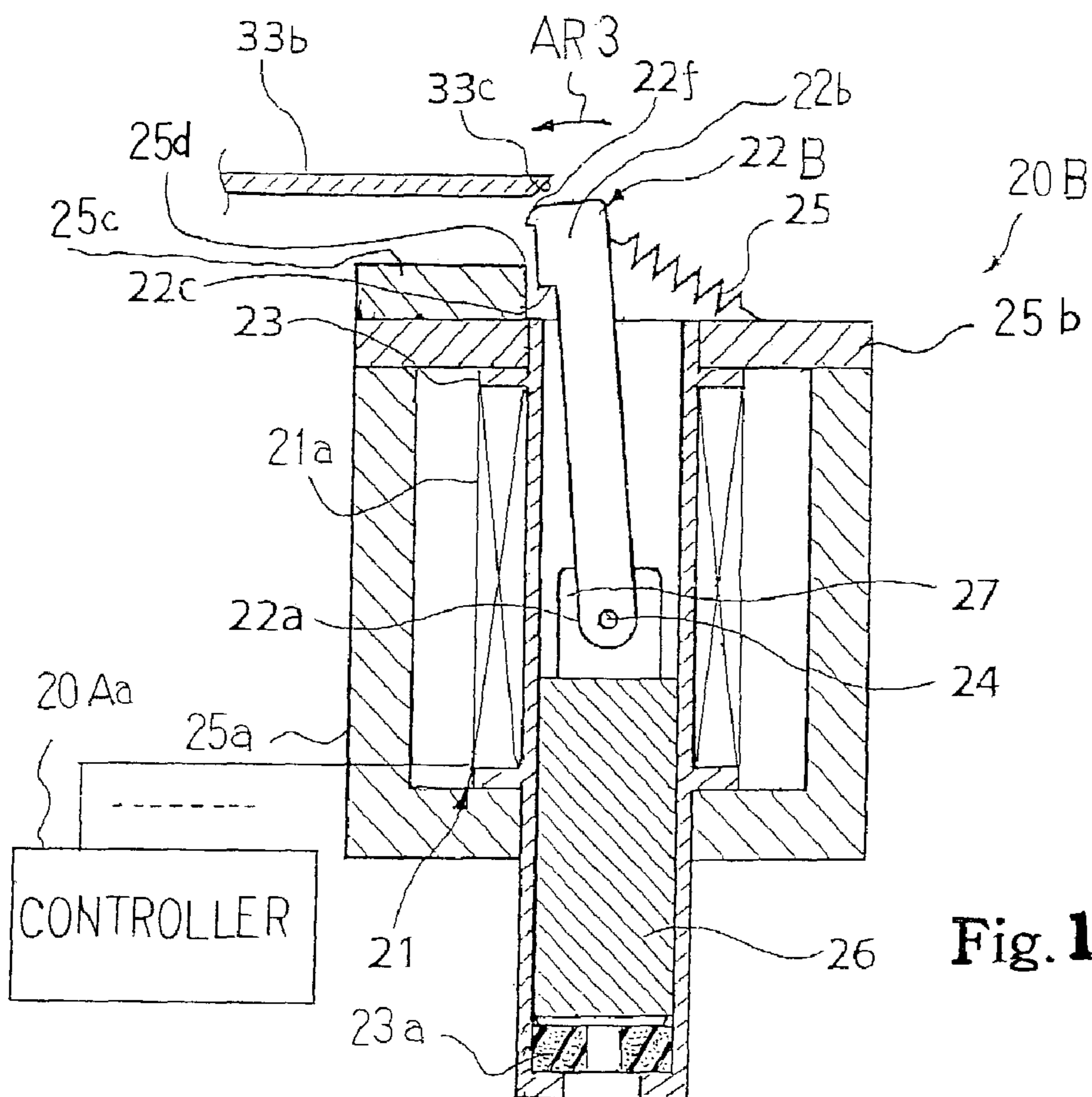


Fig. 11 B

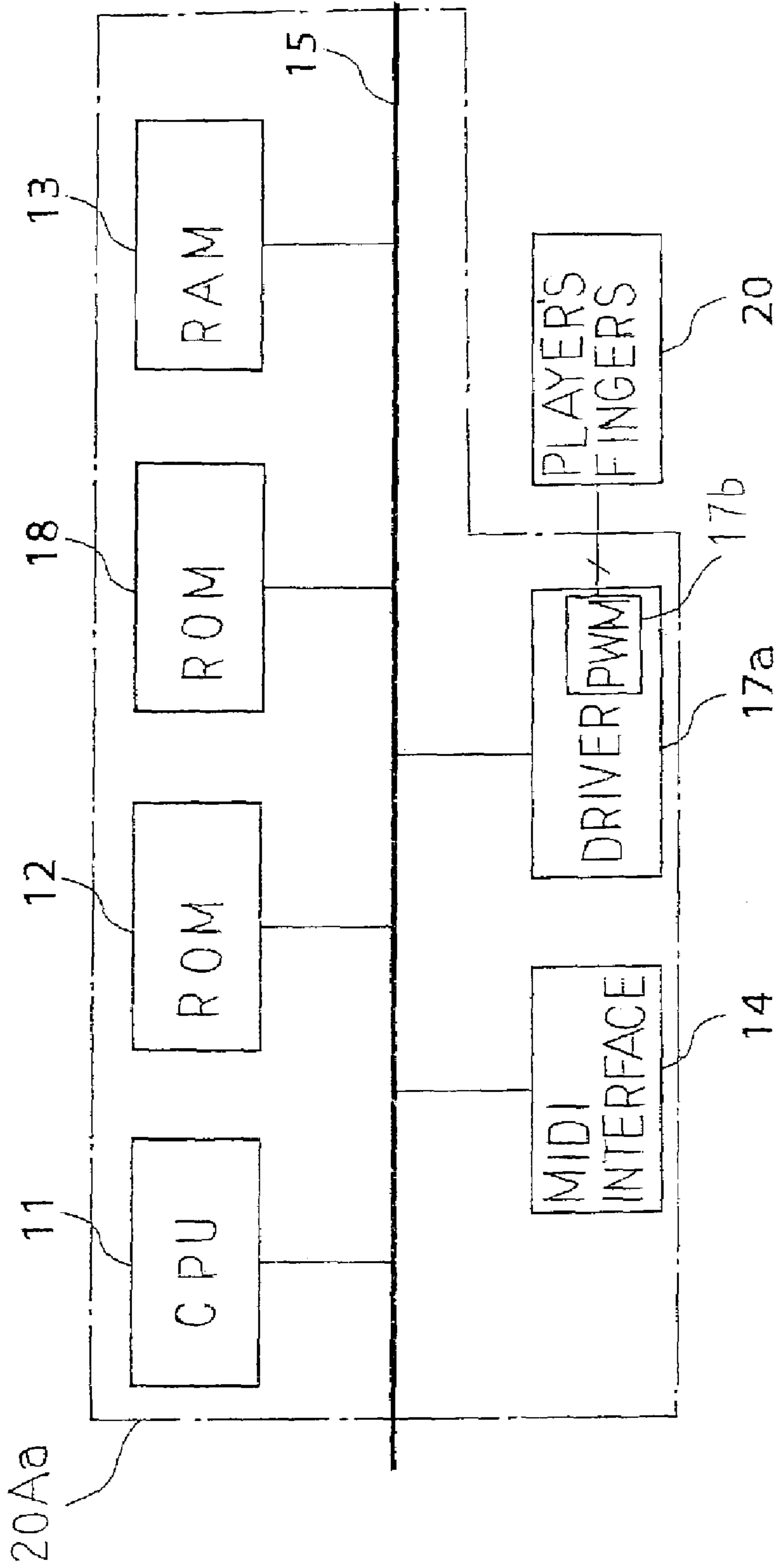


Fig. 12

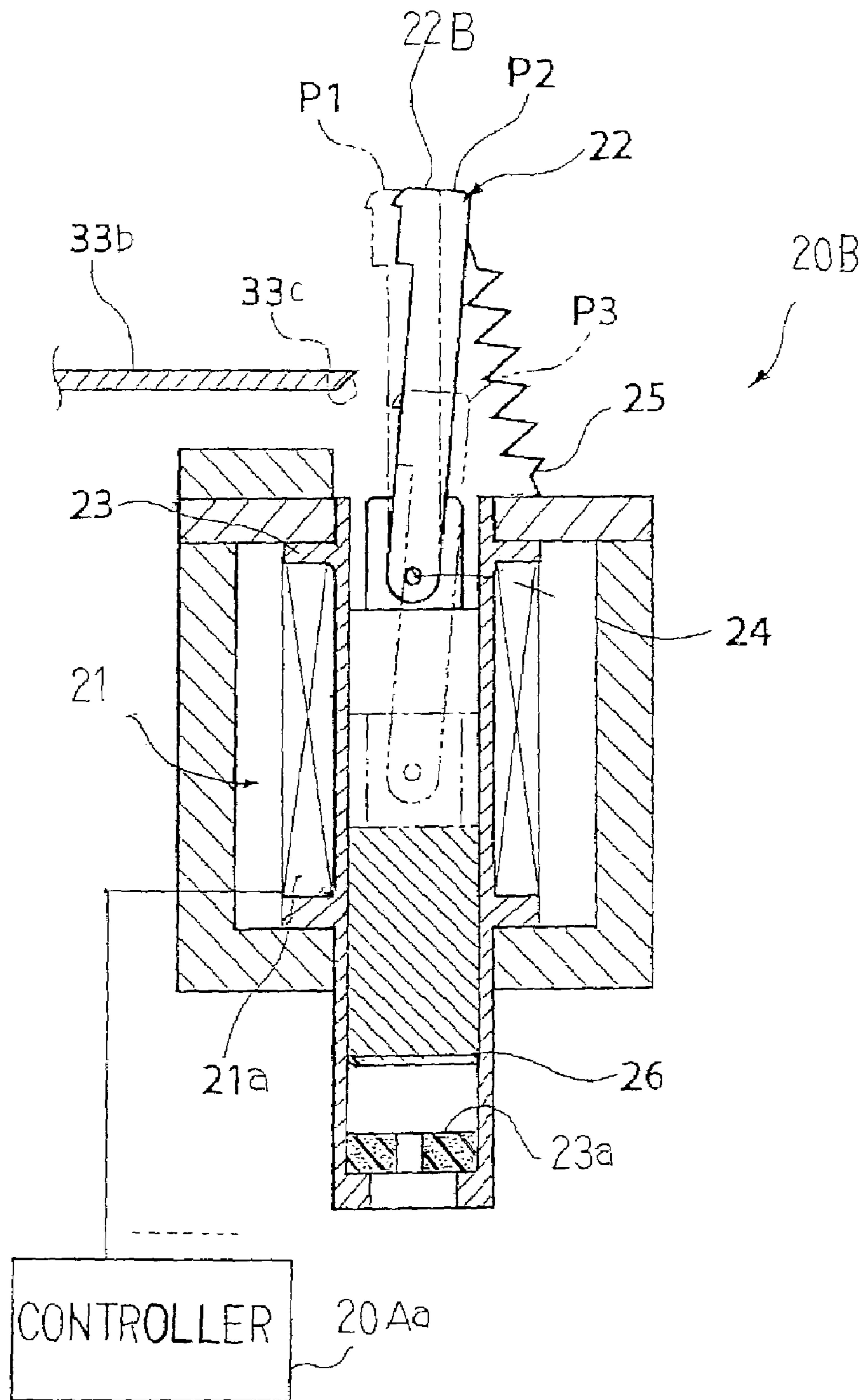


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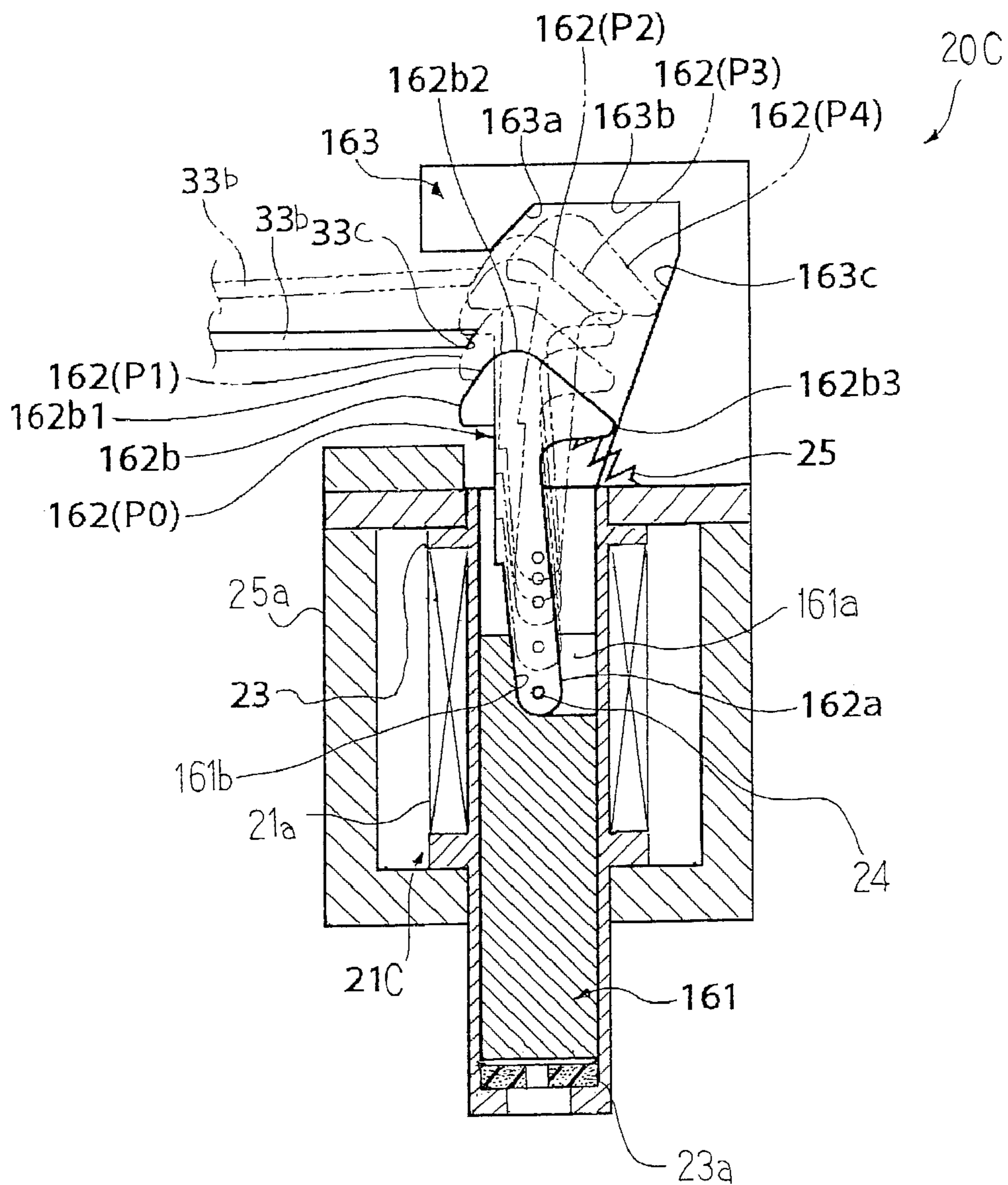


Fig. 14

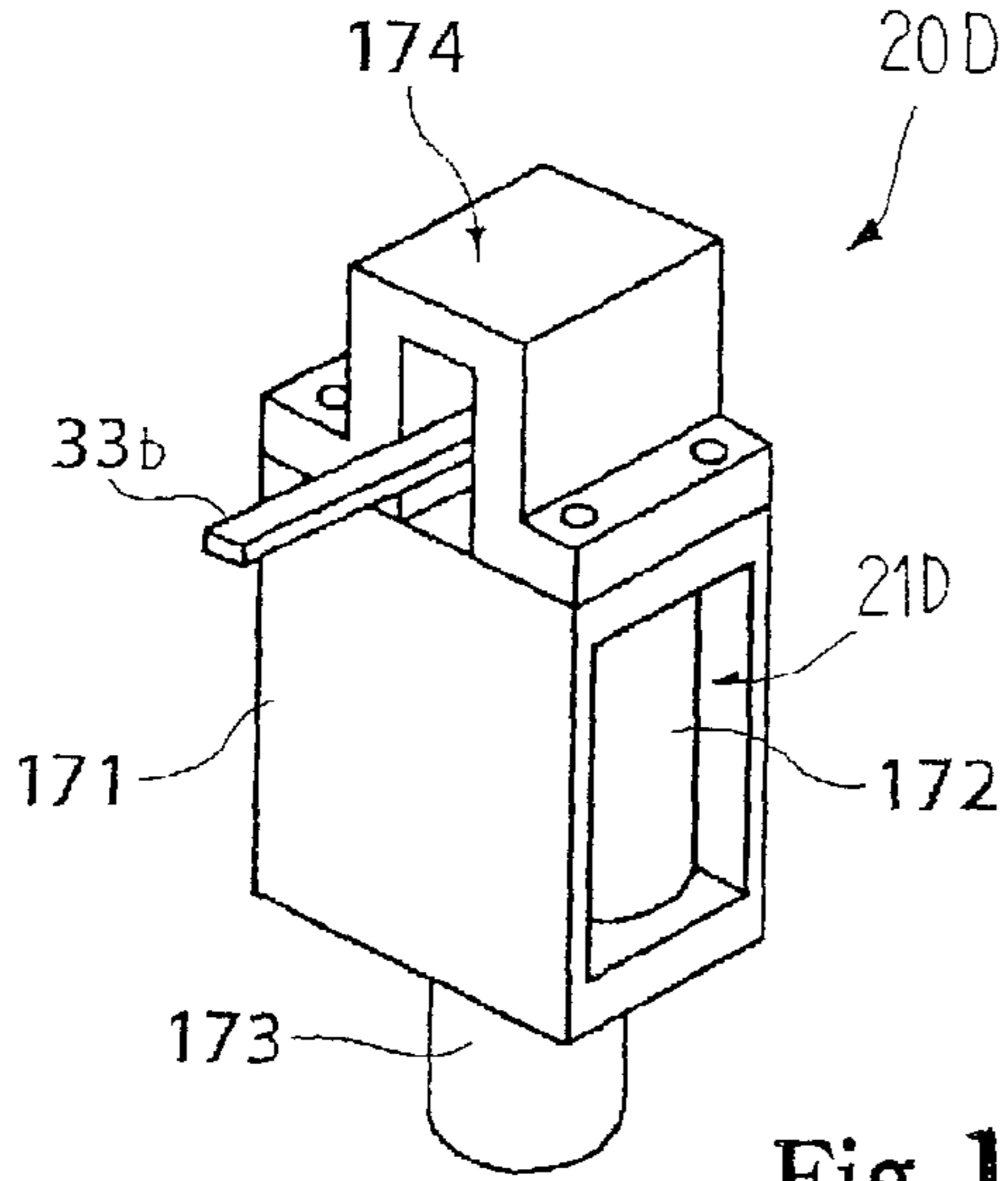


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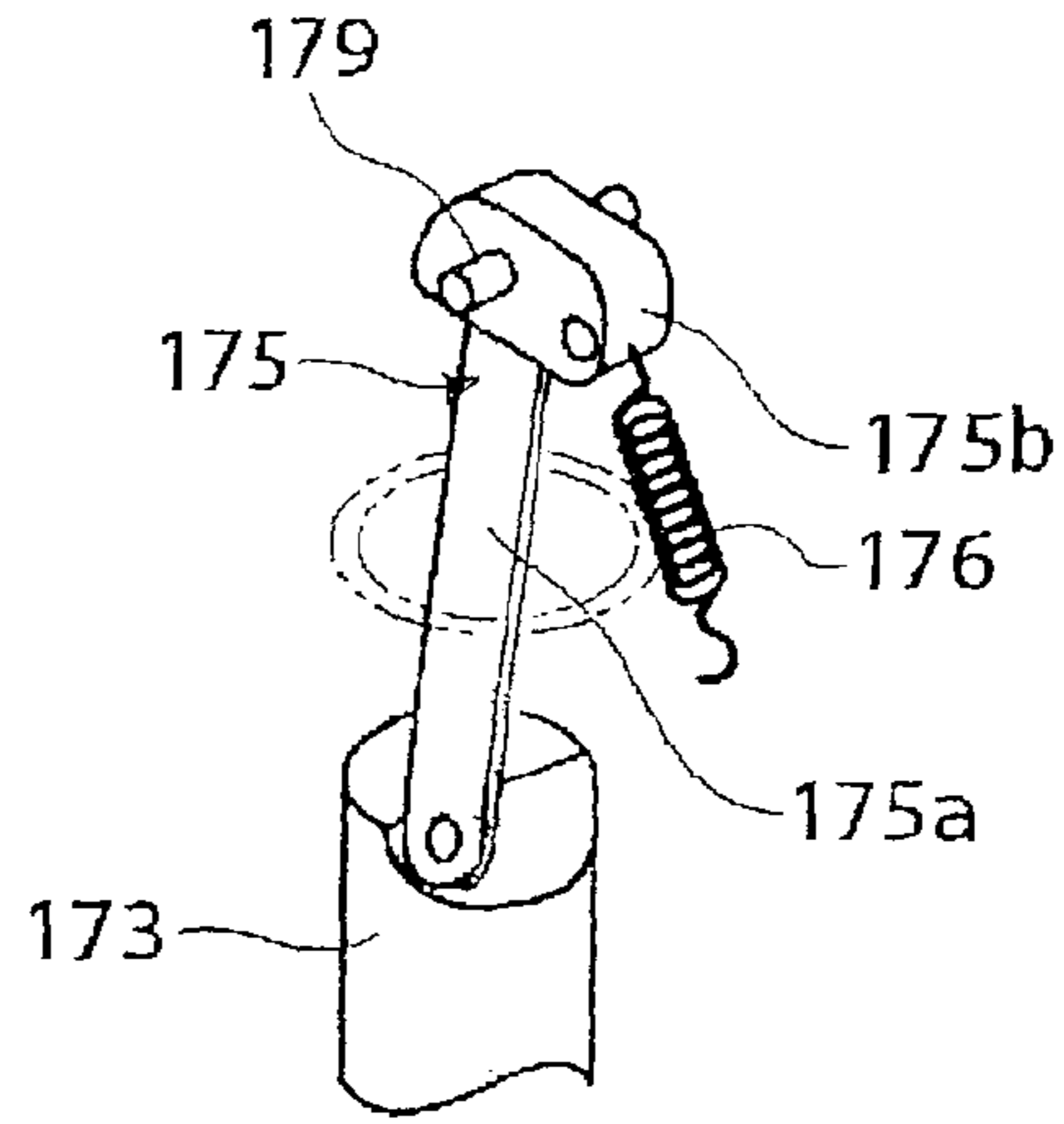


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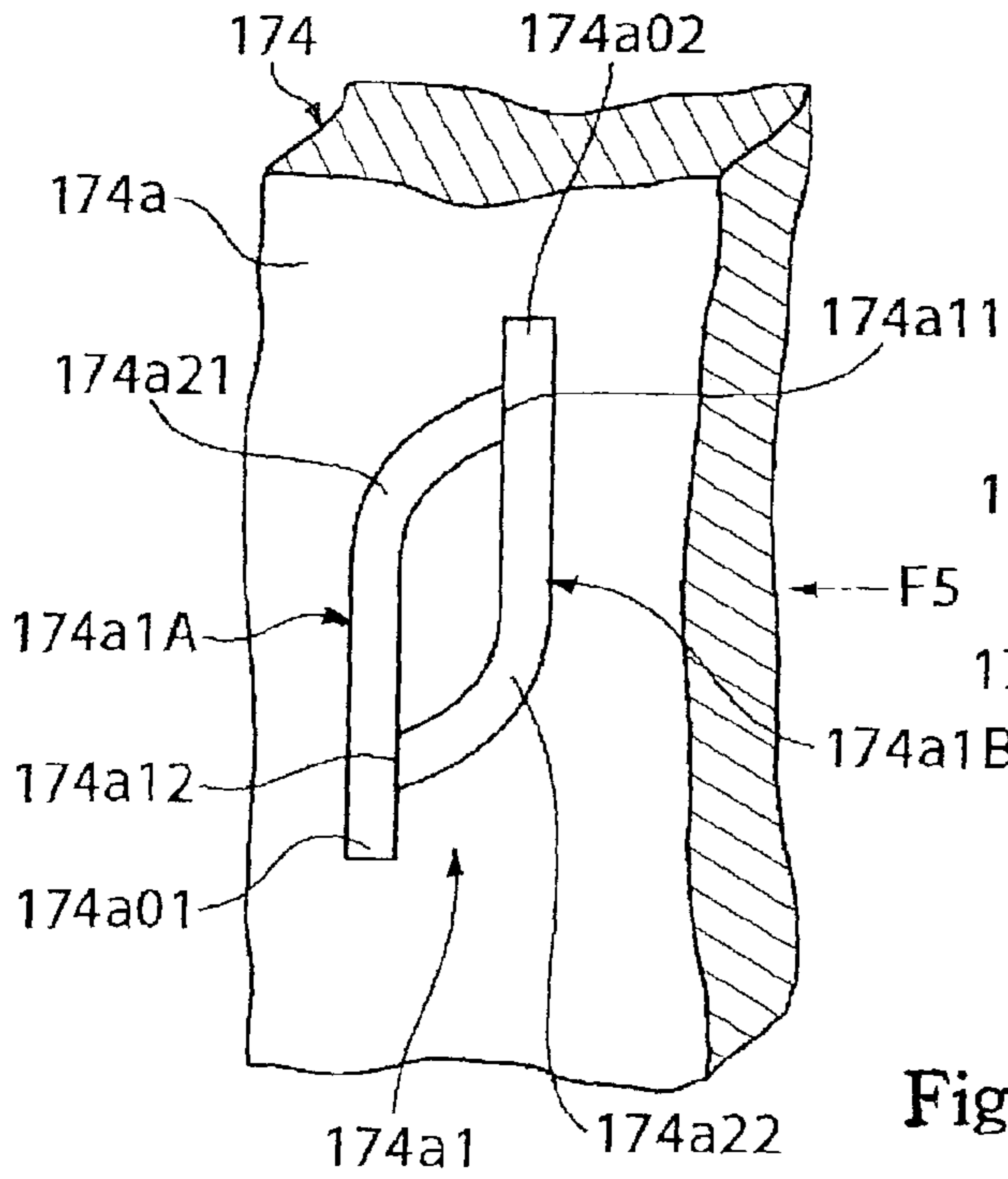


Fig. 15 C

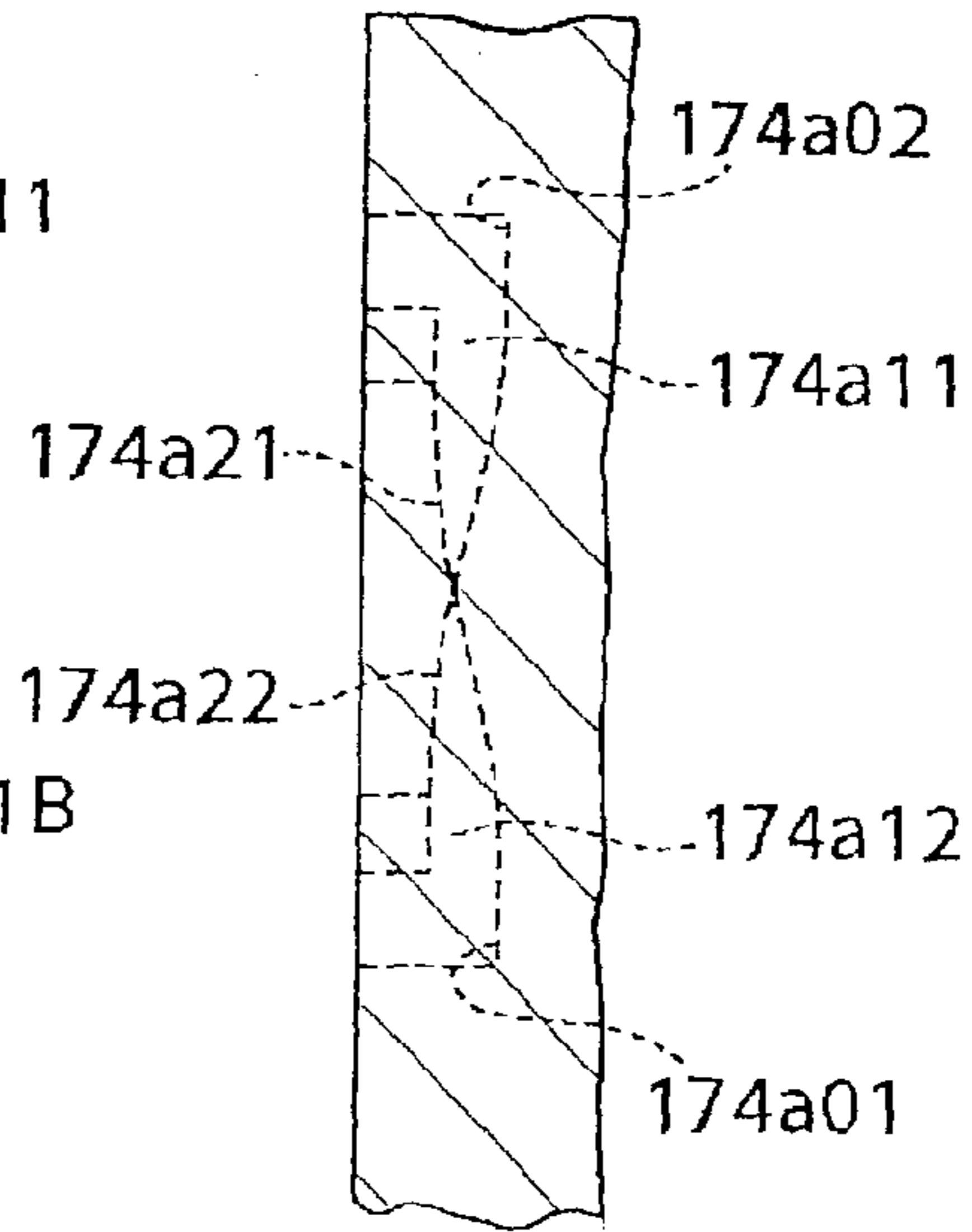


Fig. 15 D

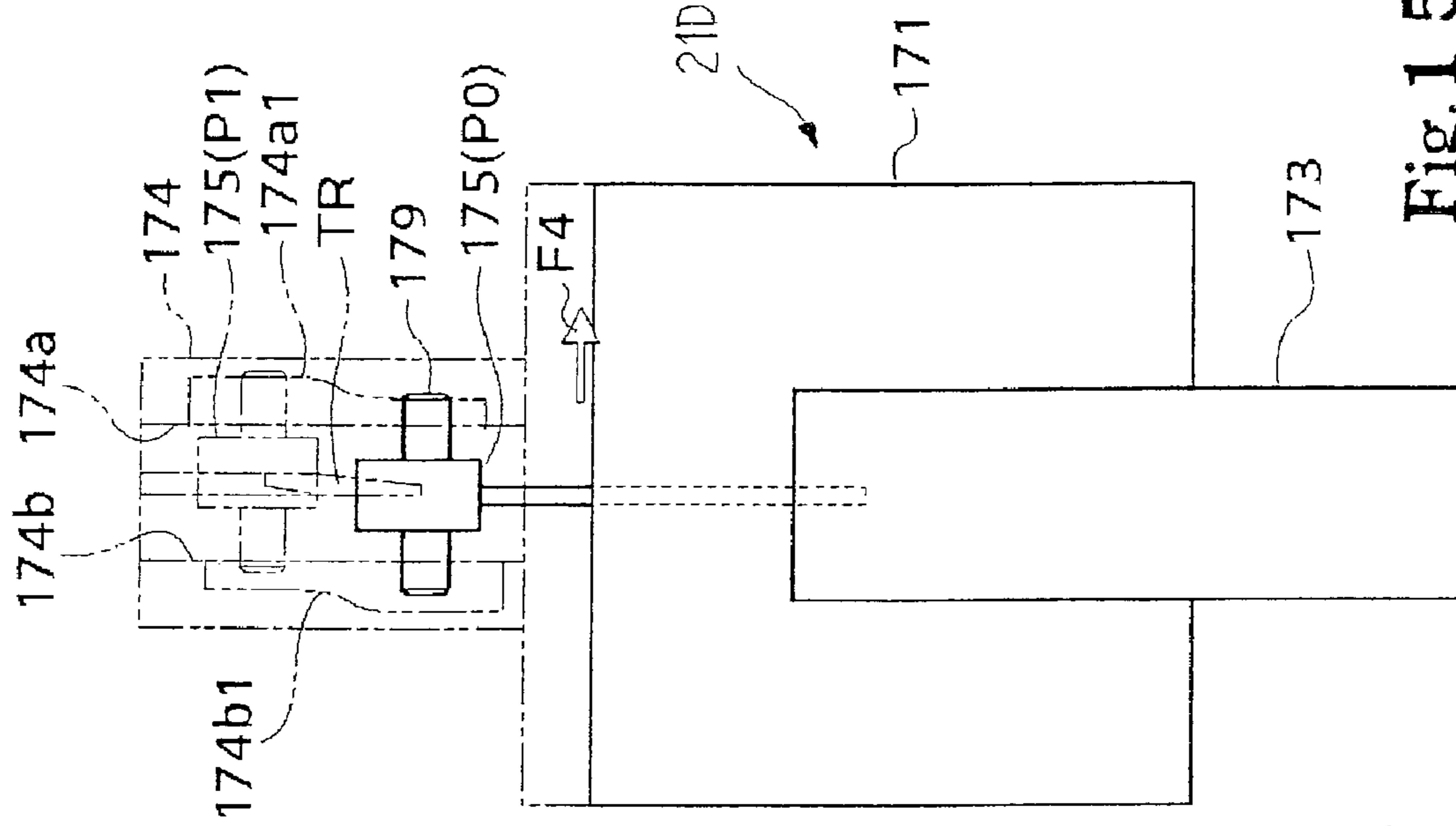


Fig. 15F

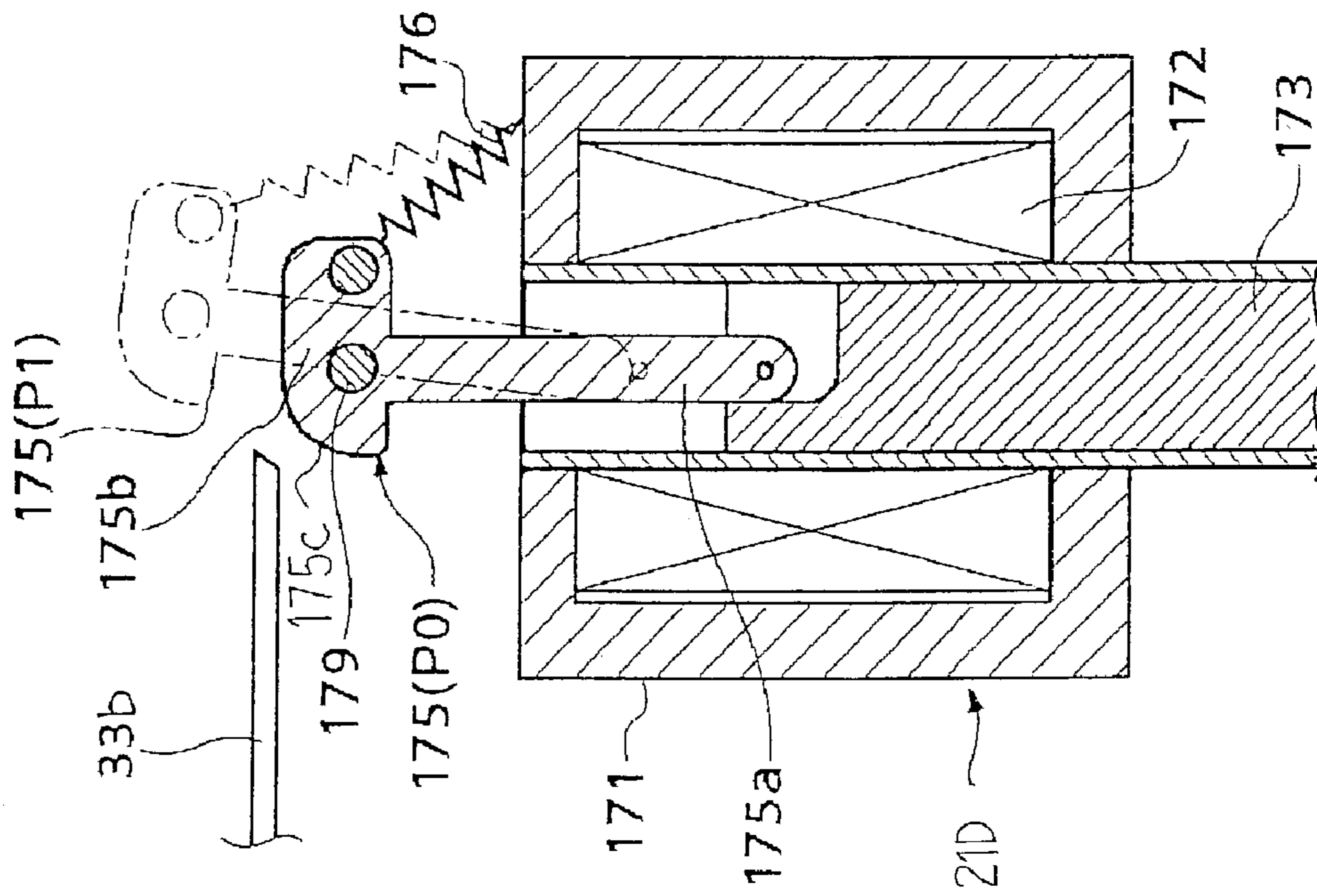


Fig. 15E

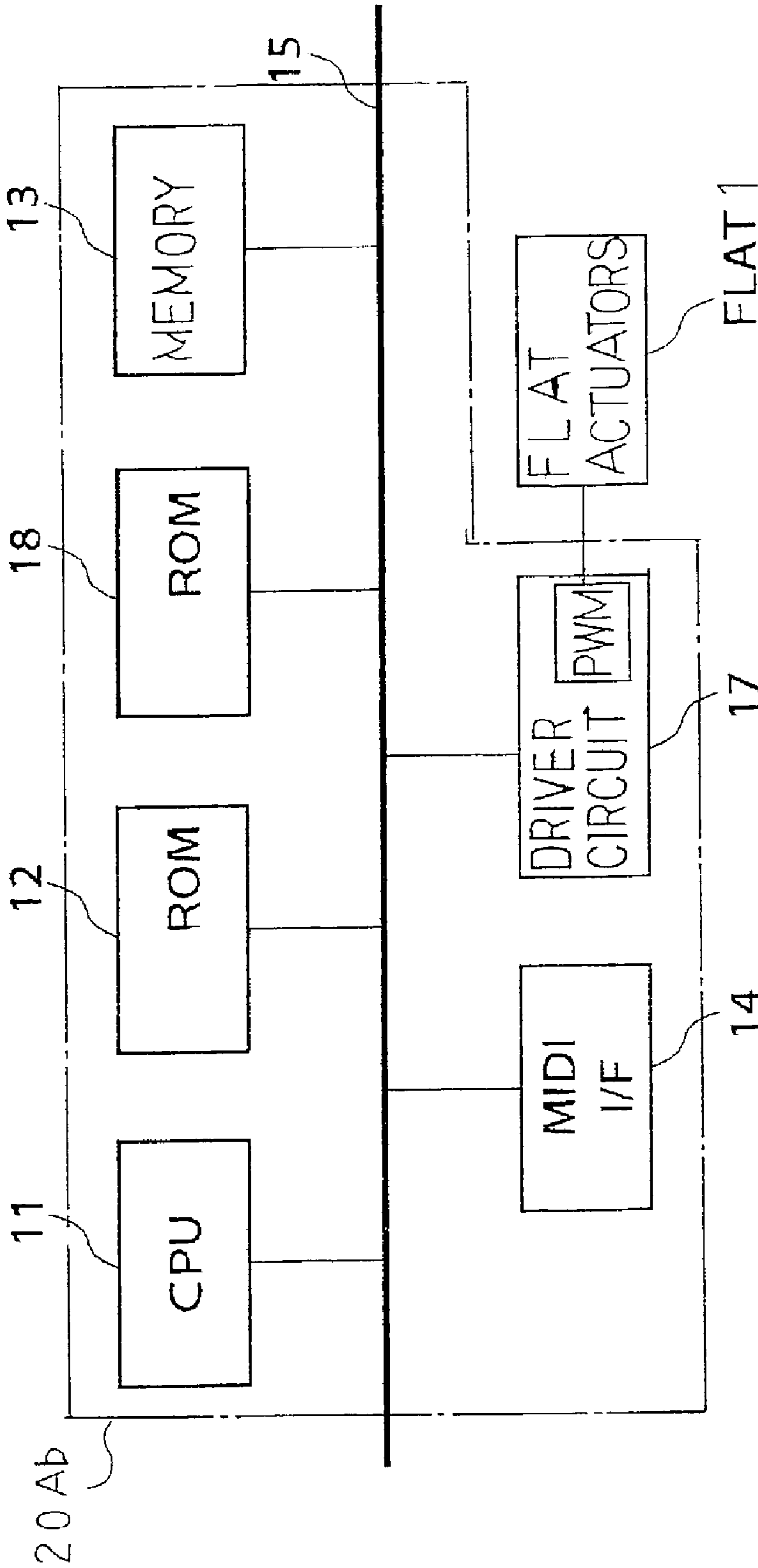


Fig. 16

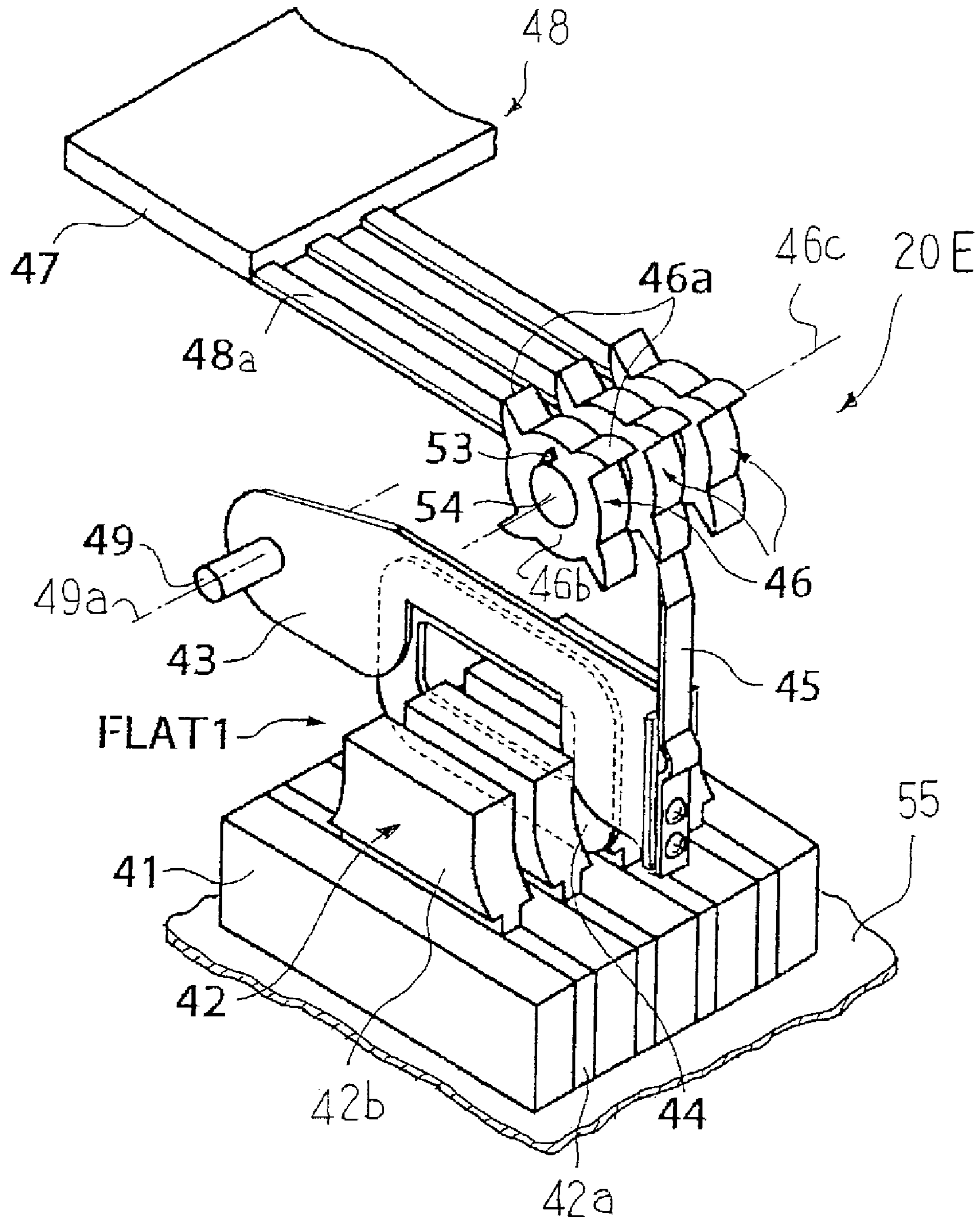


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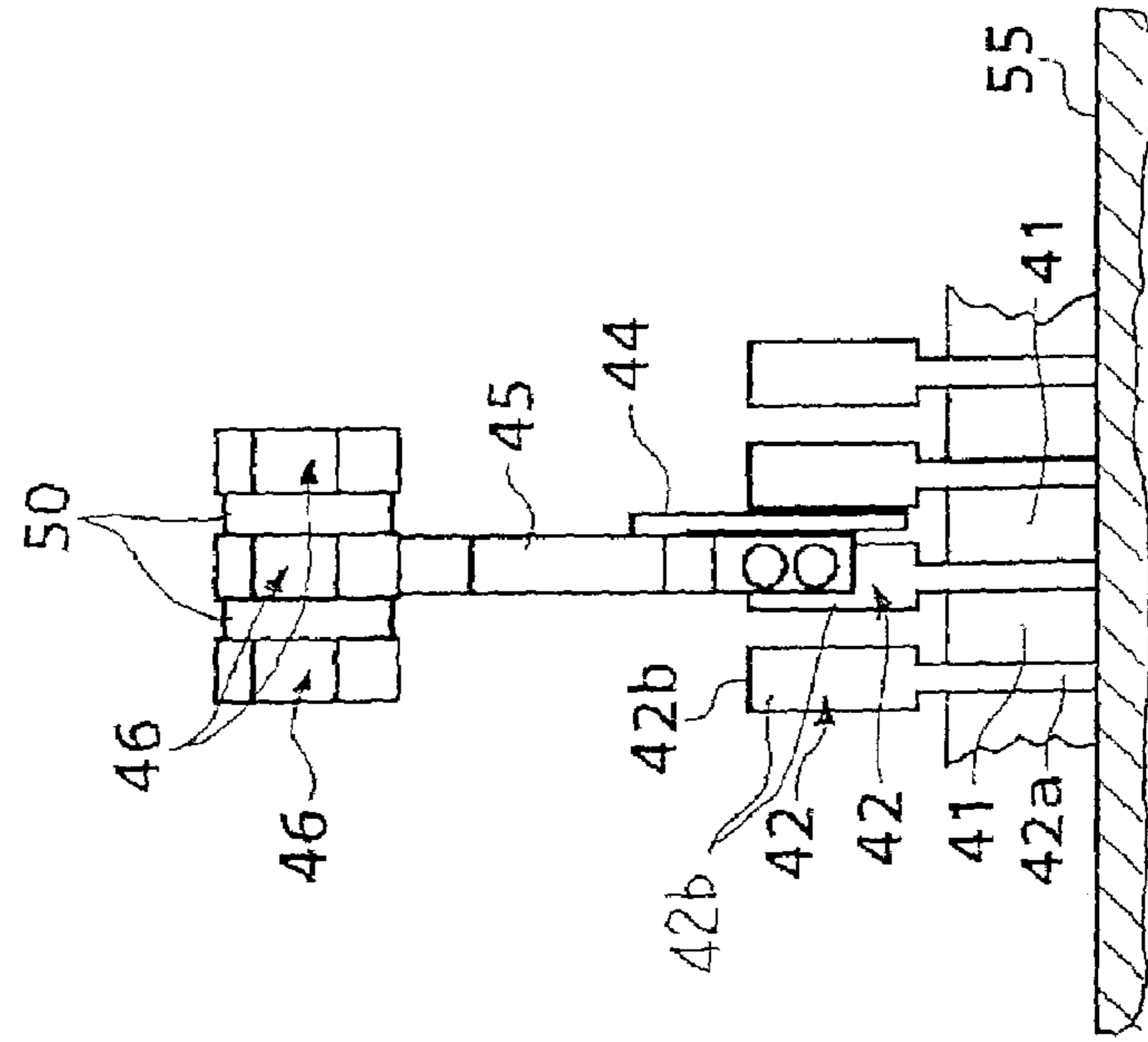


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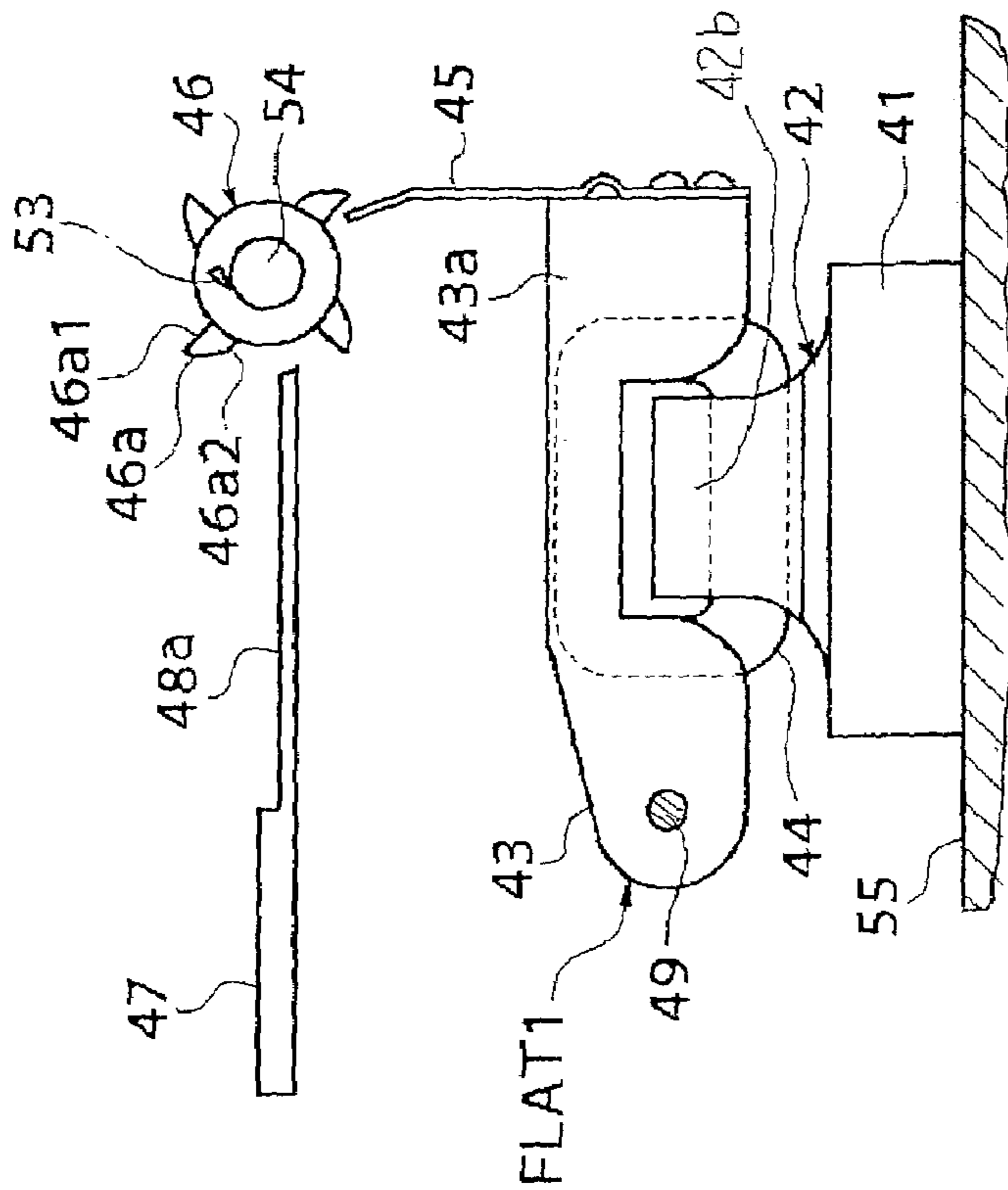


Fig. 18B

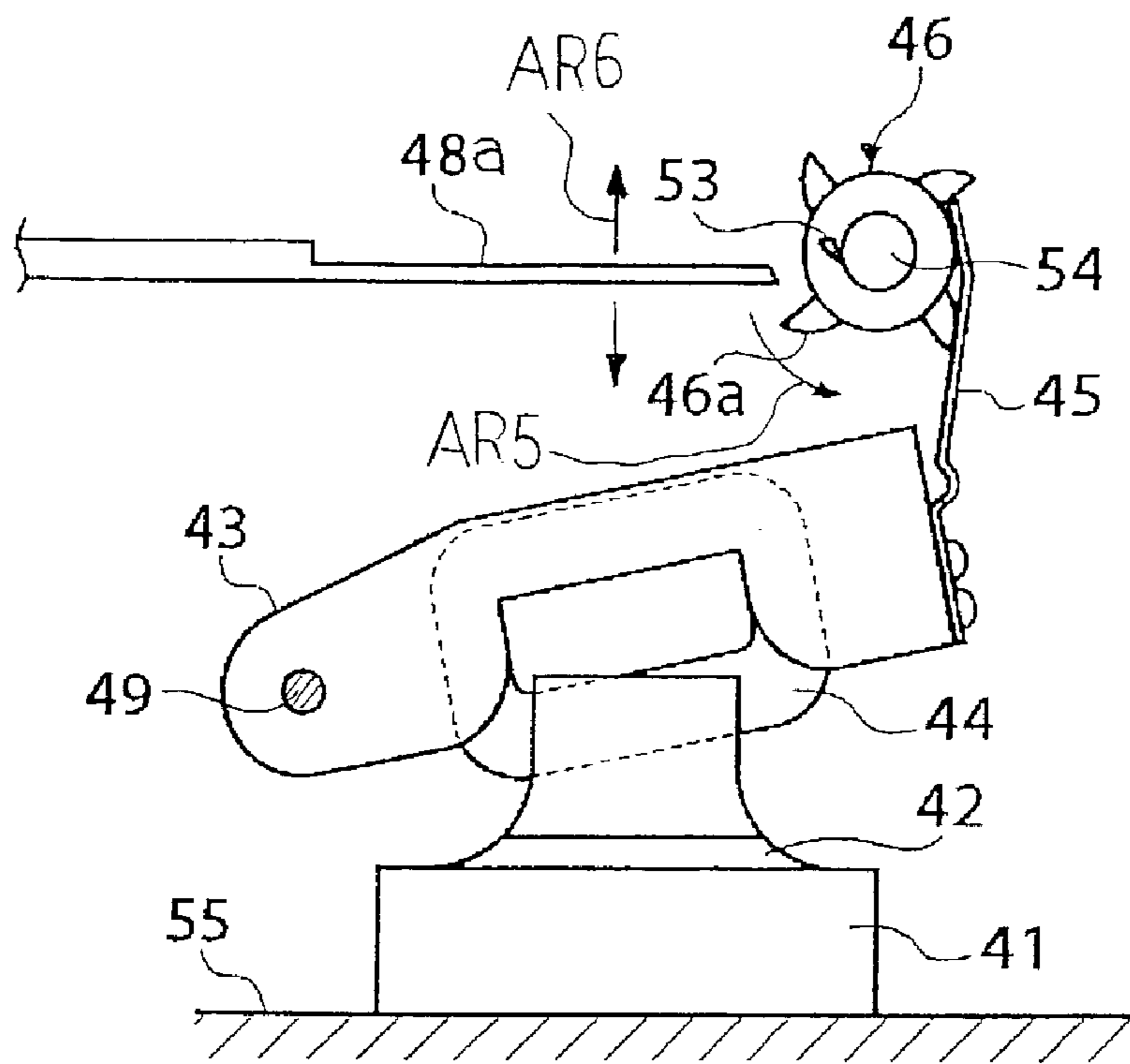


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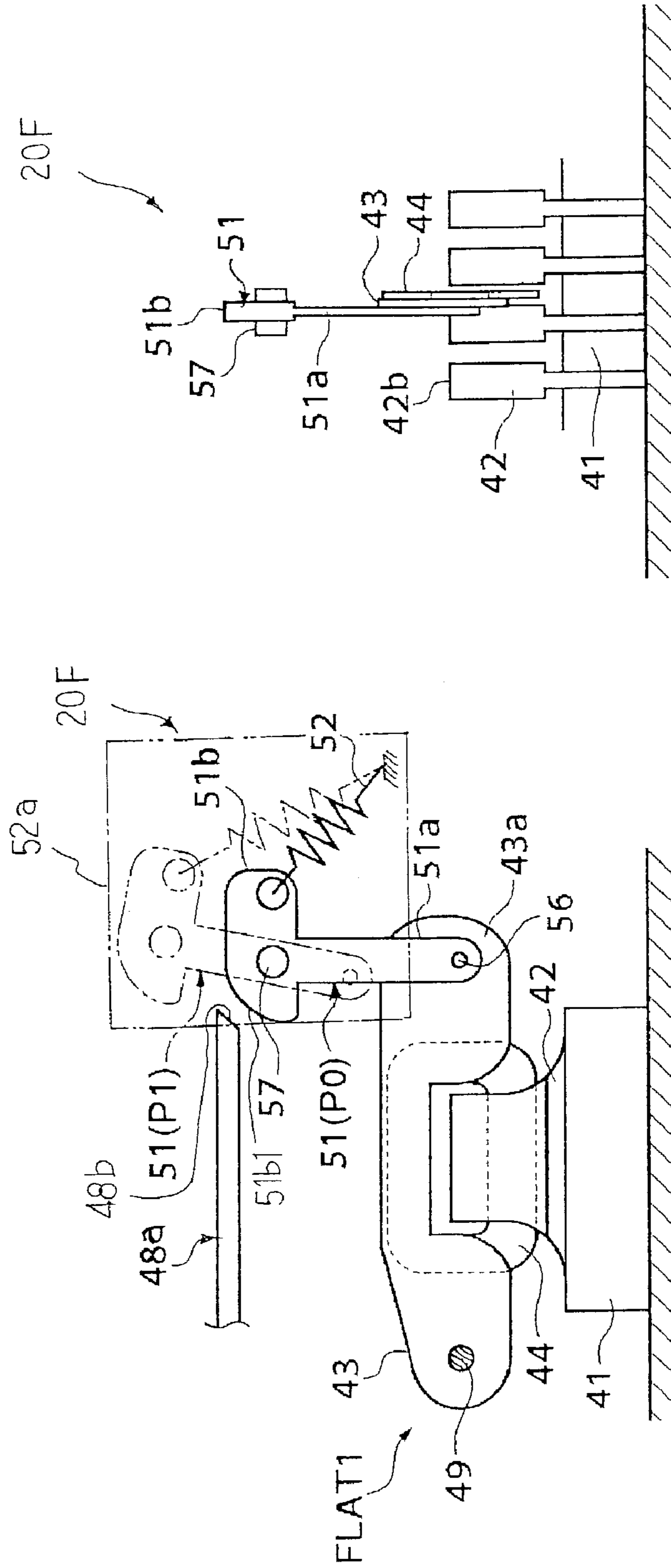


Fig. 20B

Fig. 20A

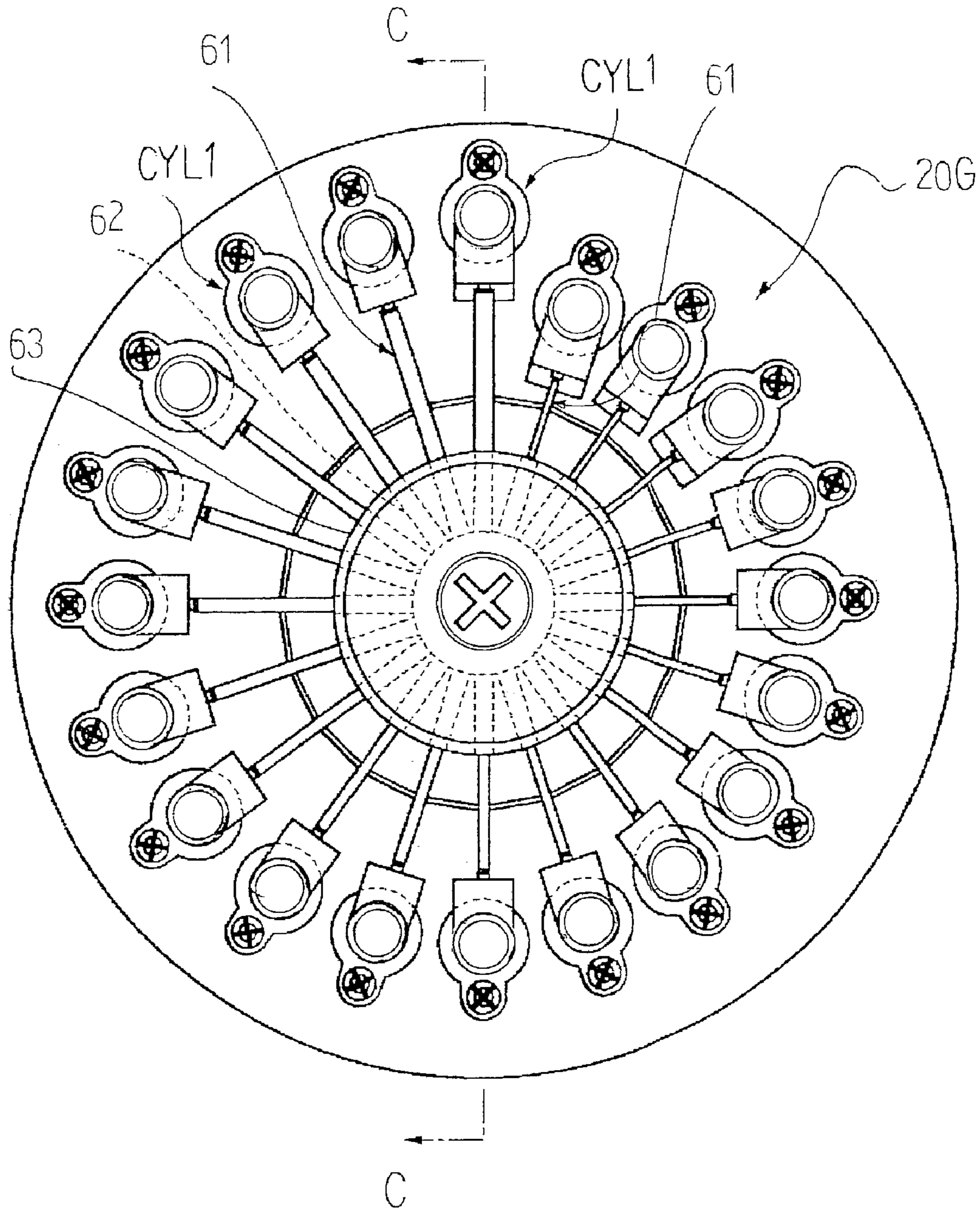


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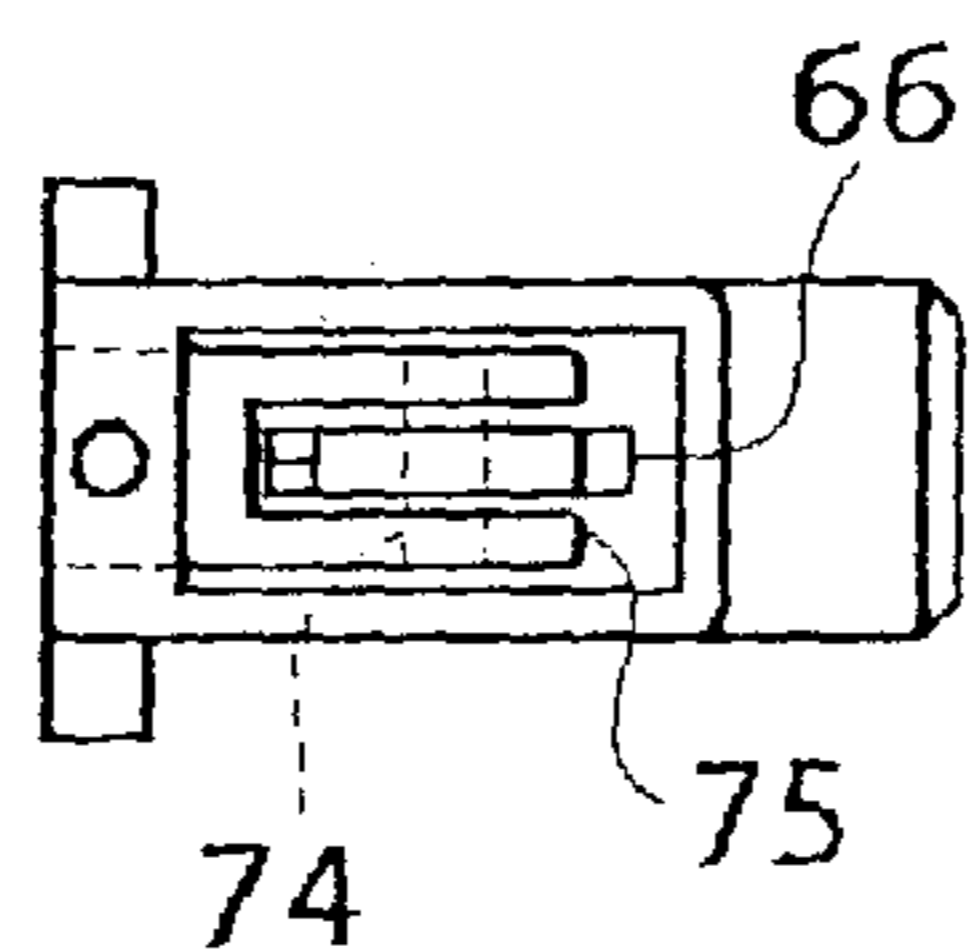


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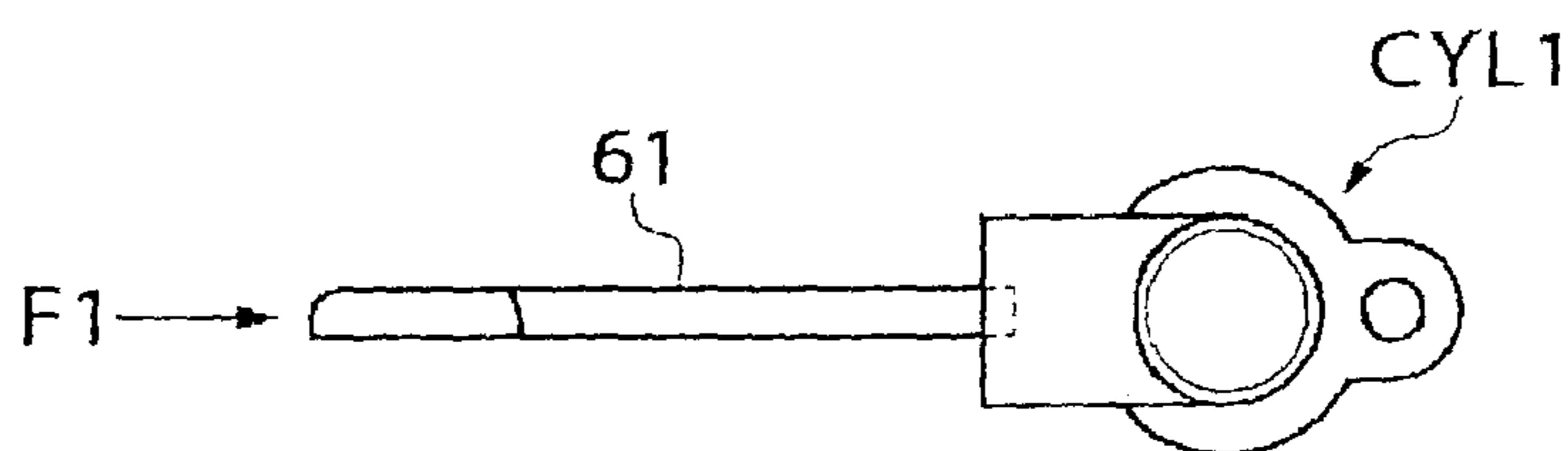


Fig. 22 B

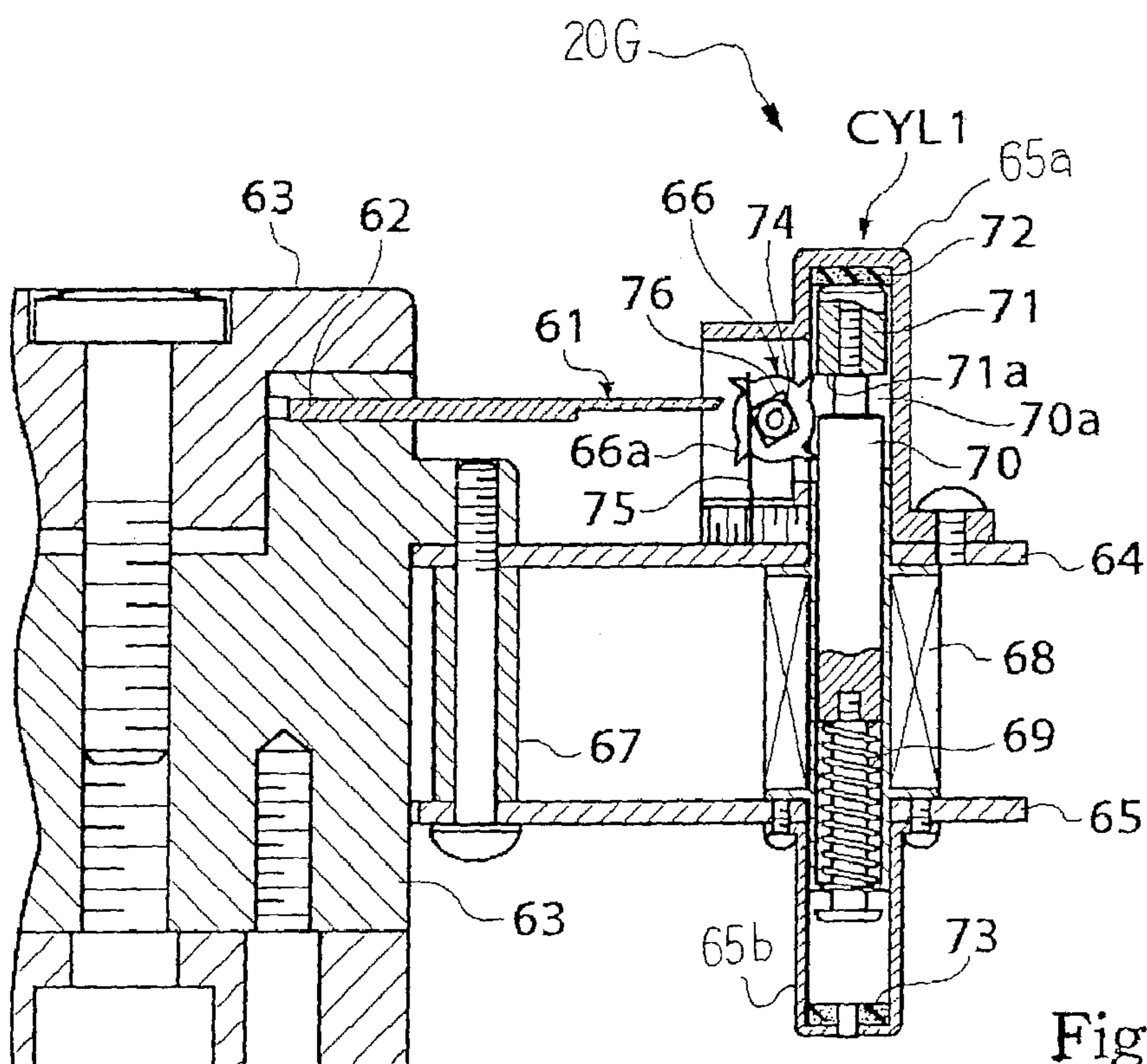


Fig. 22 A

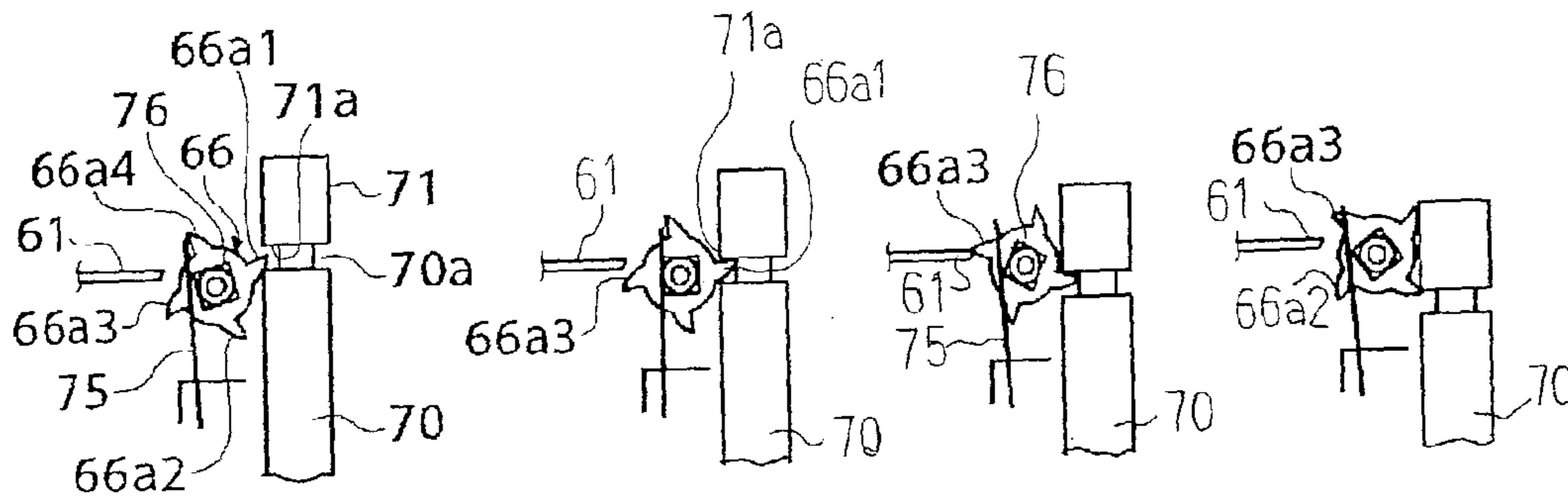


Fig. 23A Fig. 23B Fig. 23C Fig. 23D

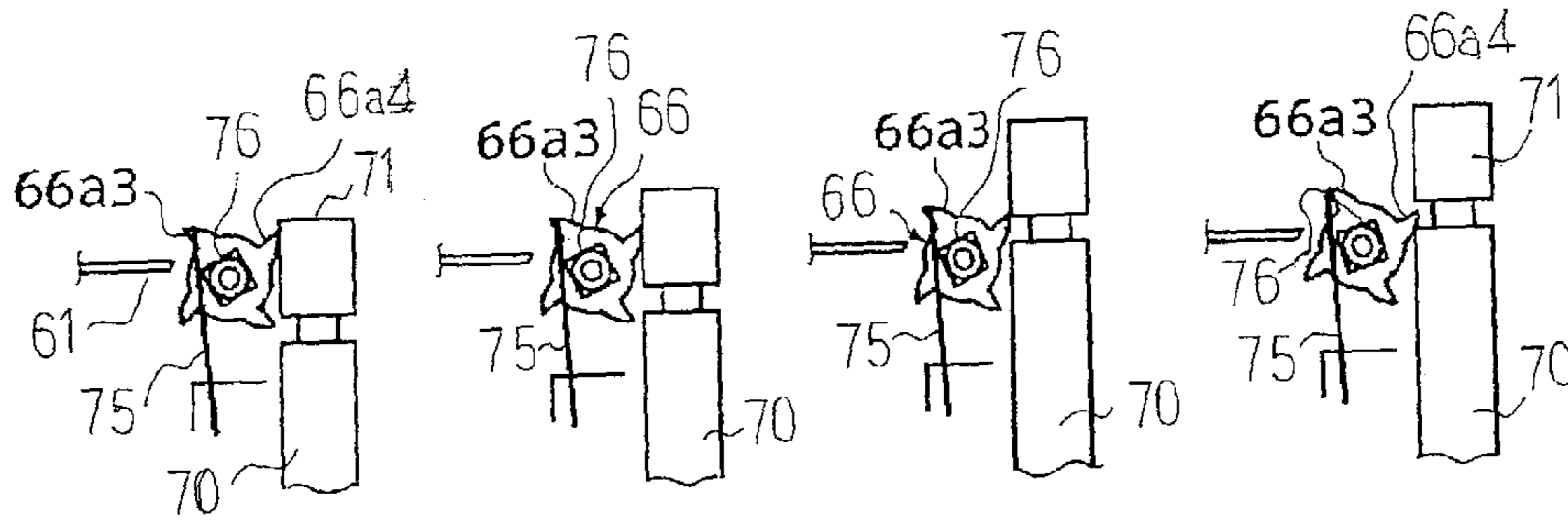


Fig. 23E Fig. 23F Fig. 23G Fig. 23H

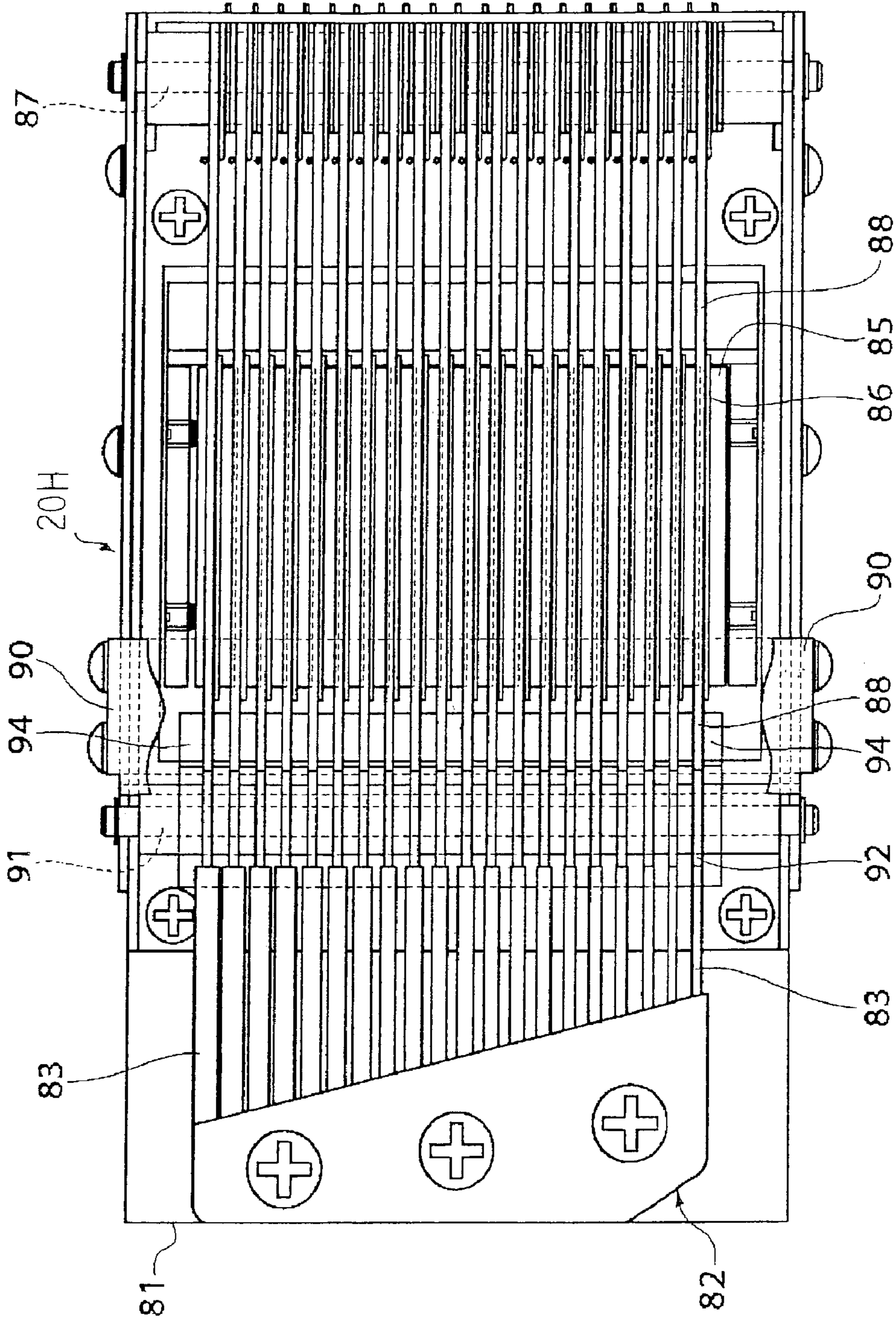


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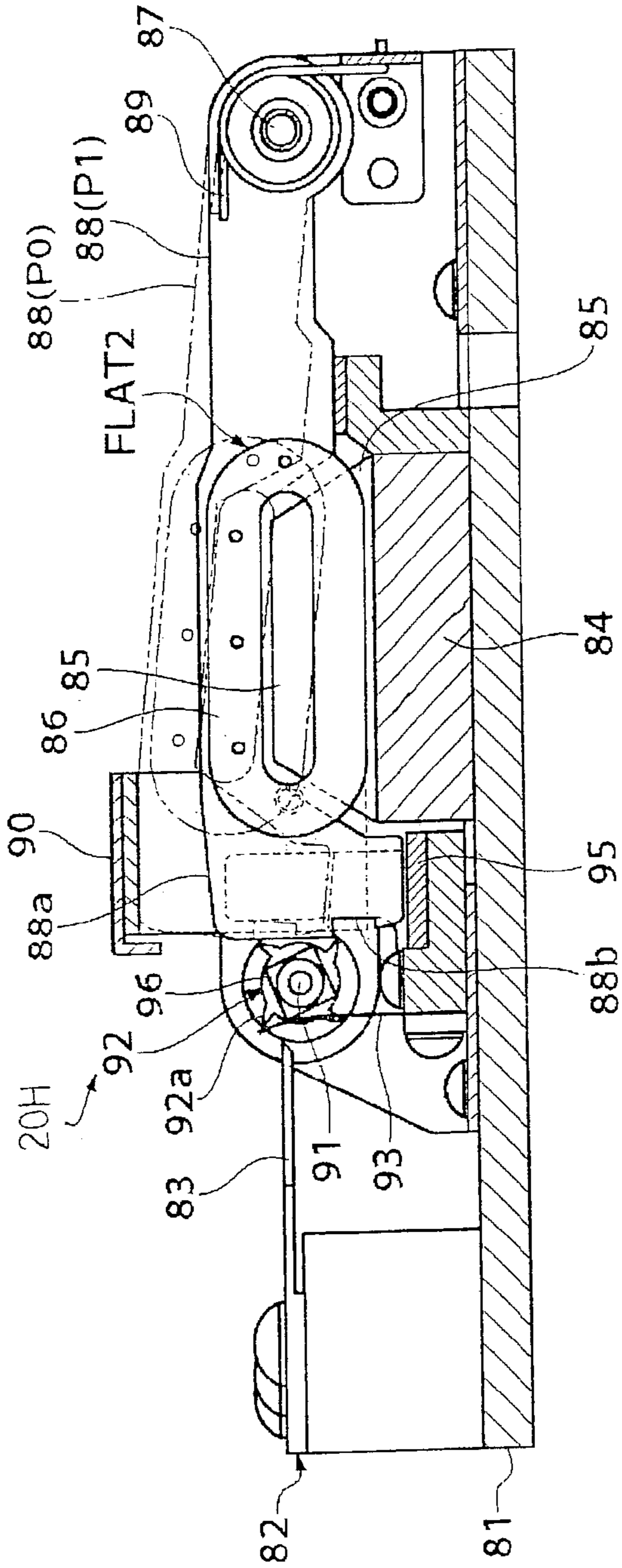


Fig. 25A

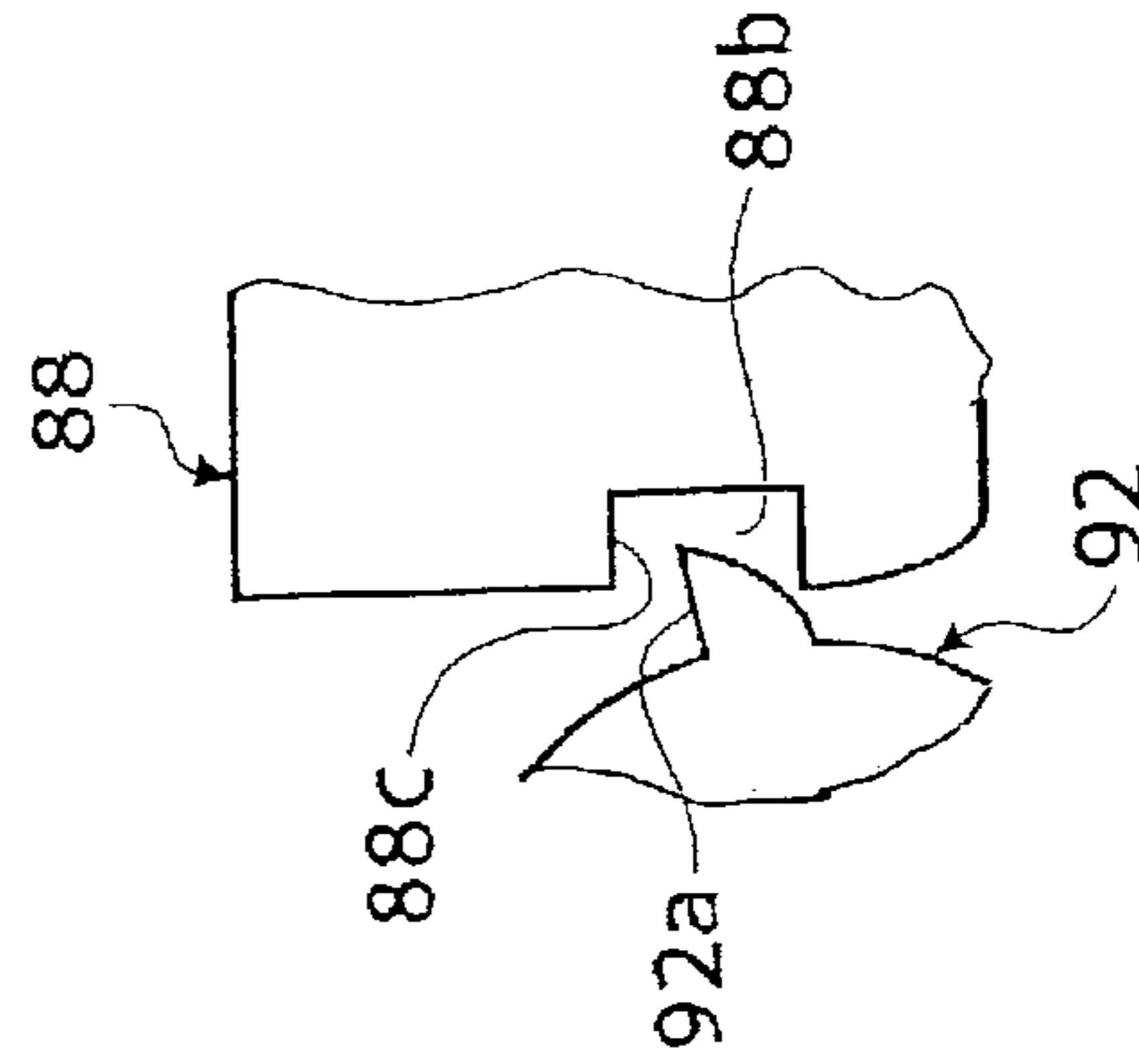


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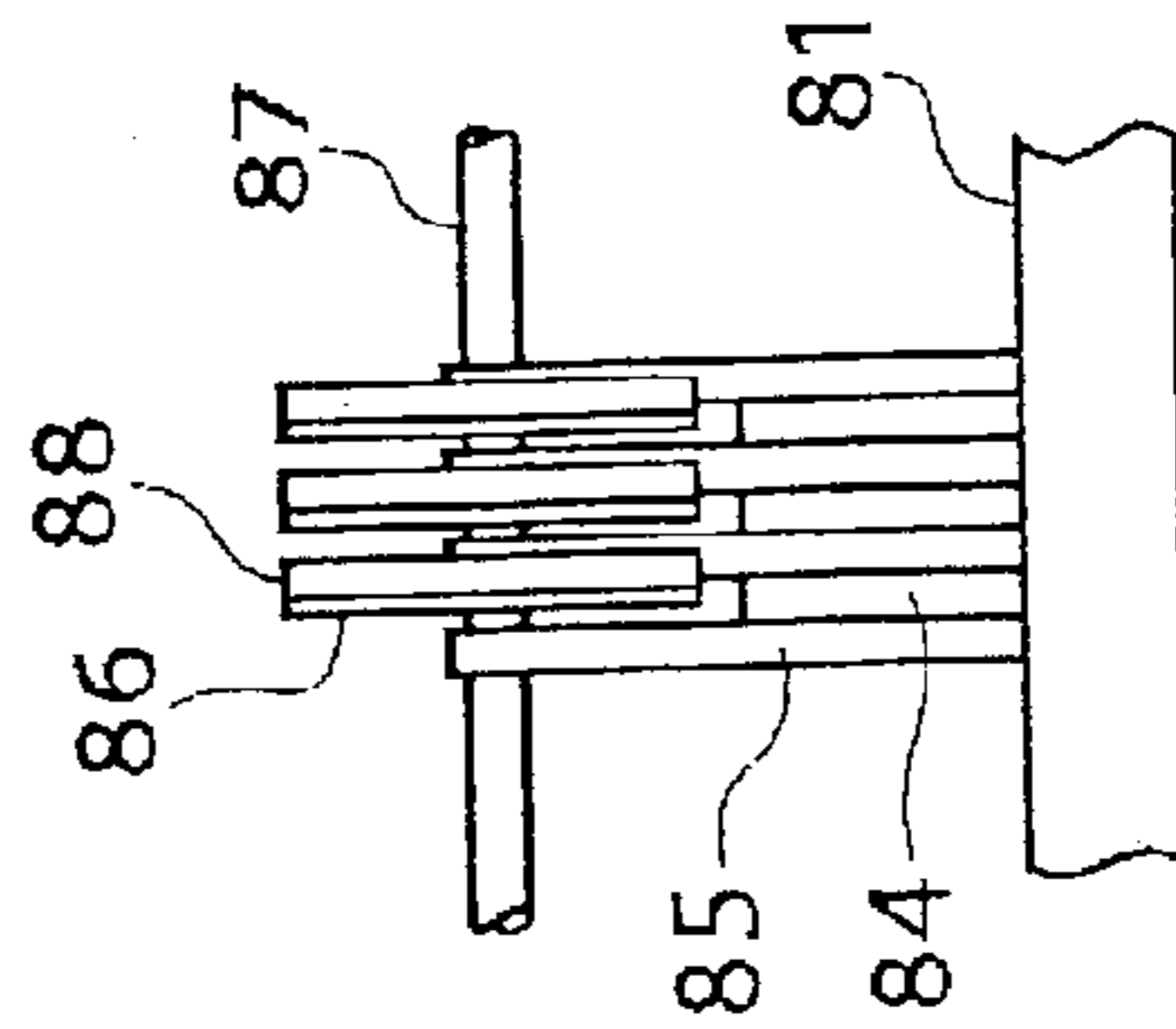


Fig. 25C

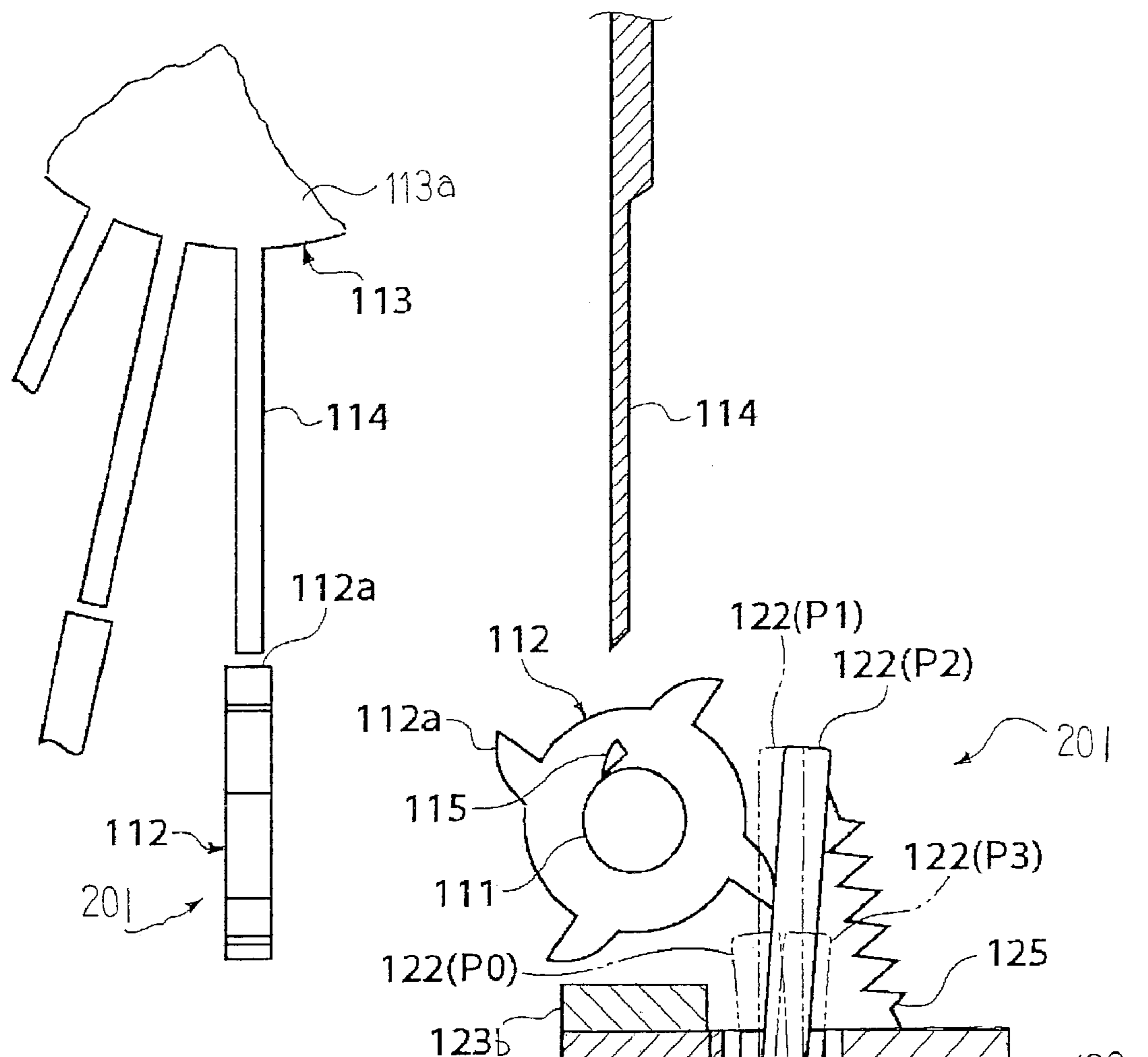


Fig. 26 A

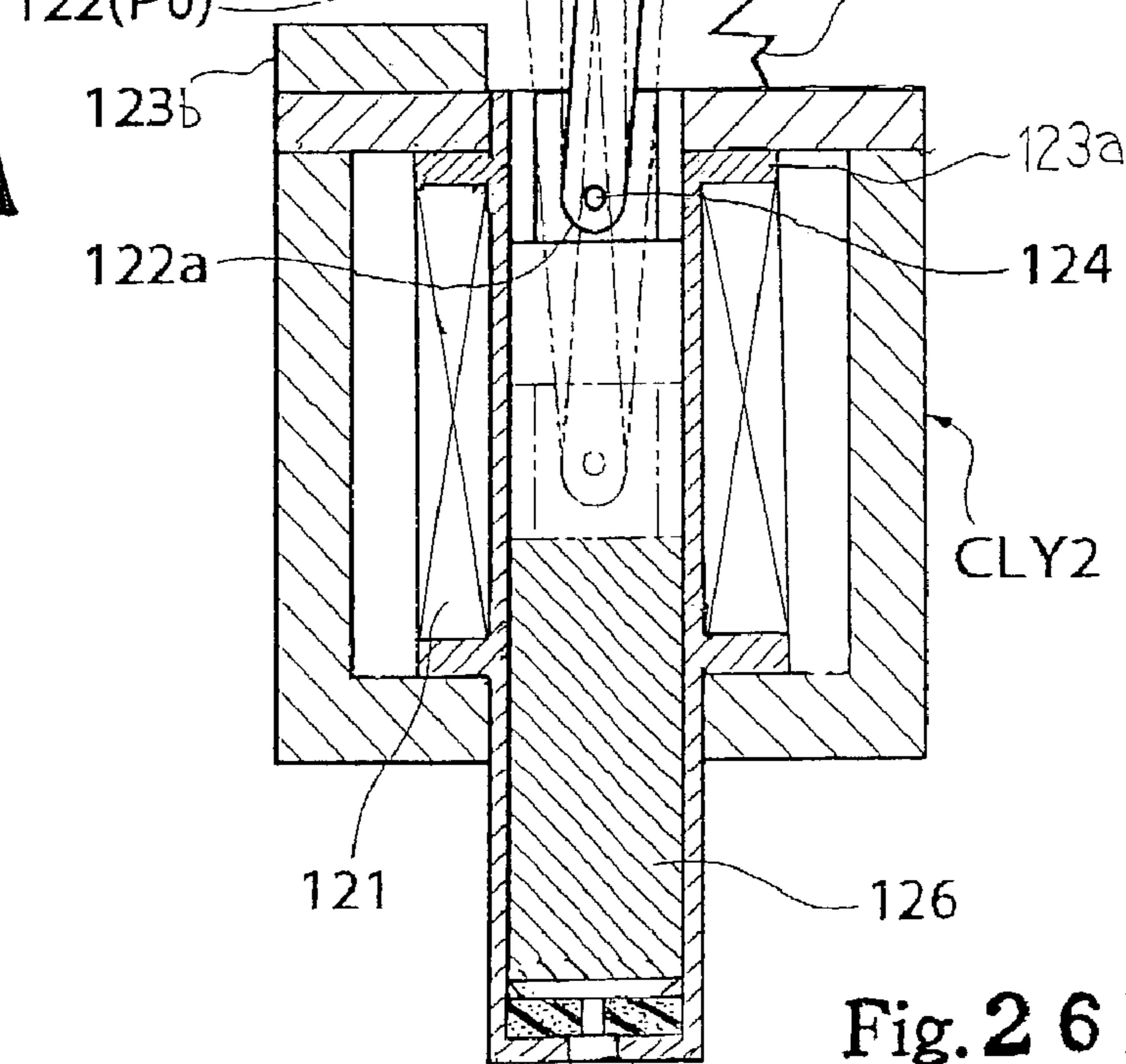


Fig. 26 B

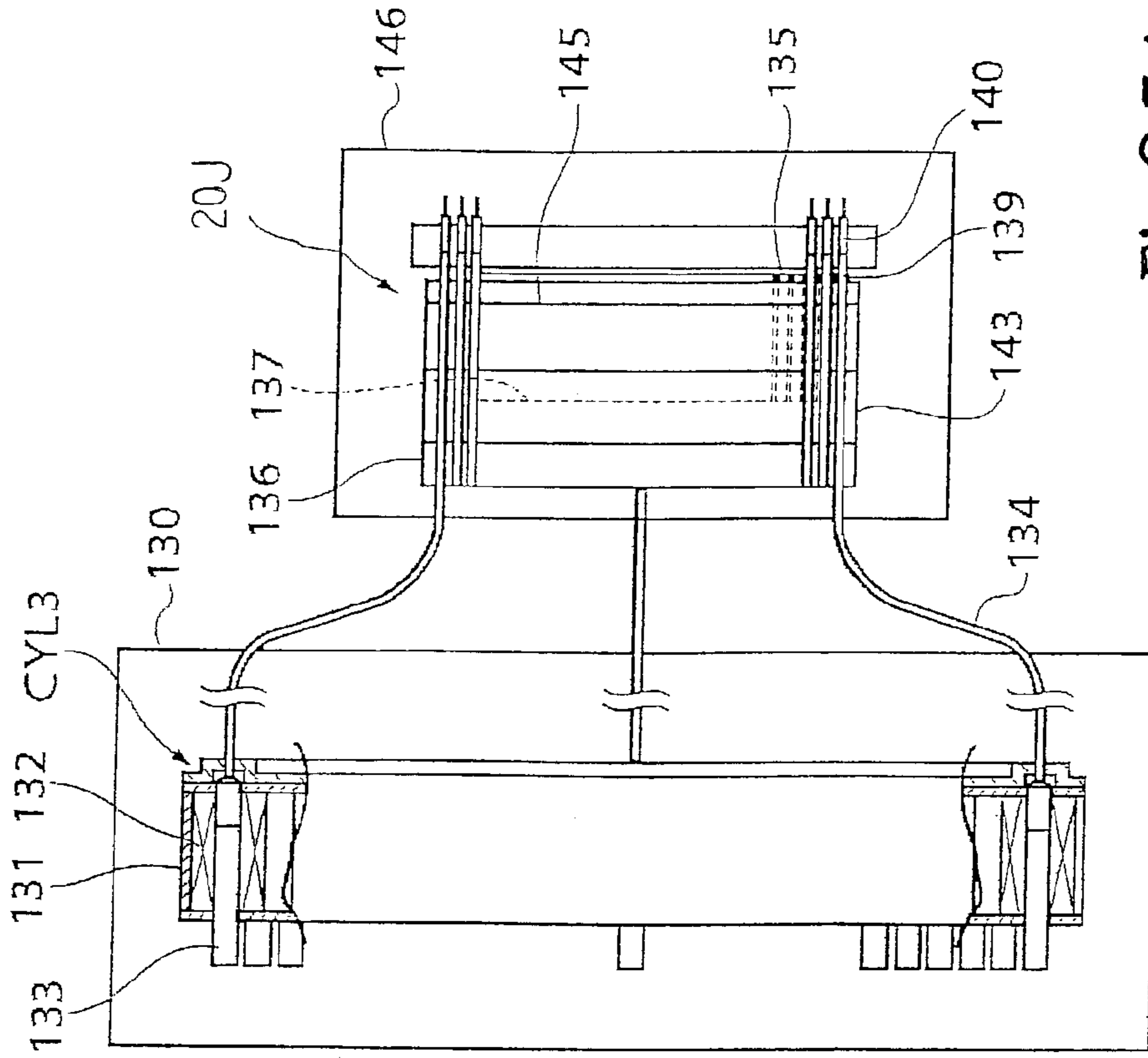


Fig. 27 A

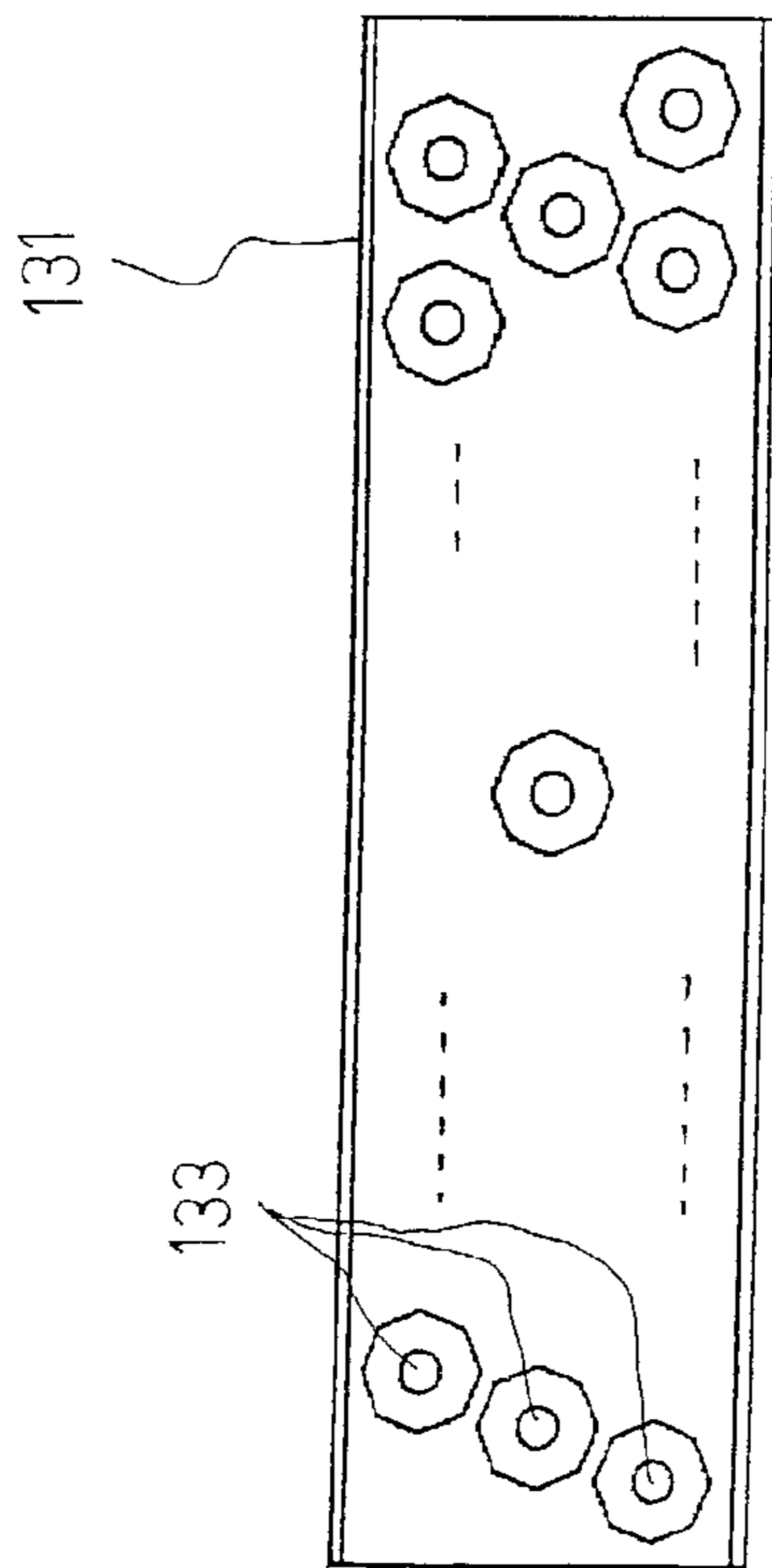


Fig. 27 B

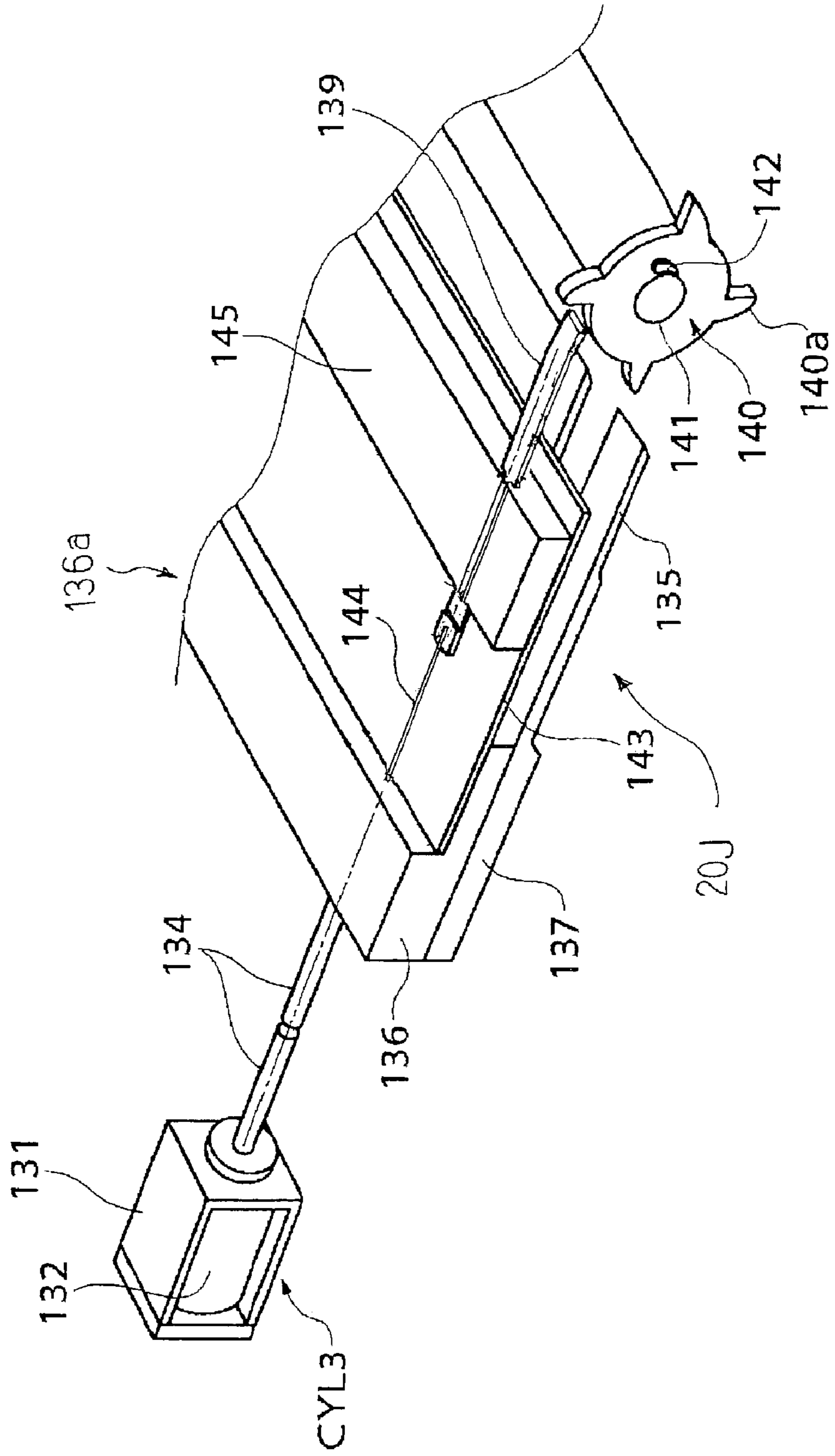


Fig. 28

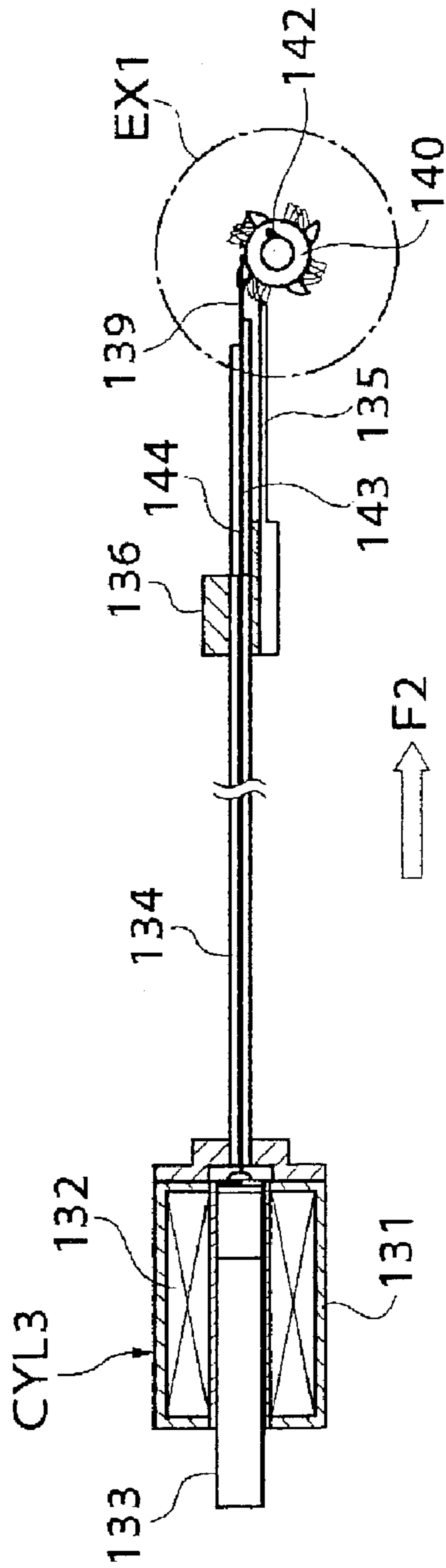


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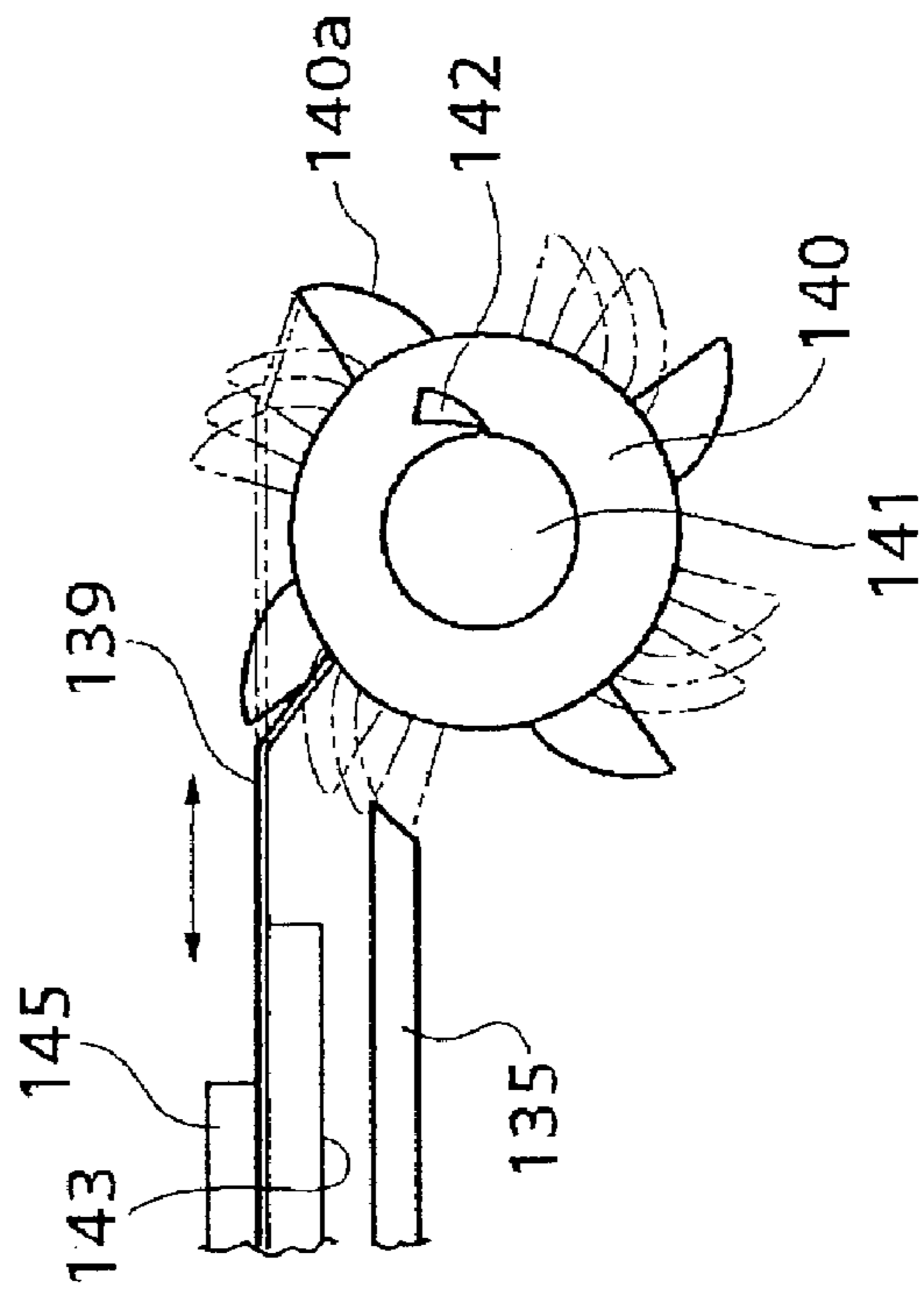


Fig. 29B

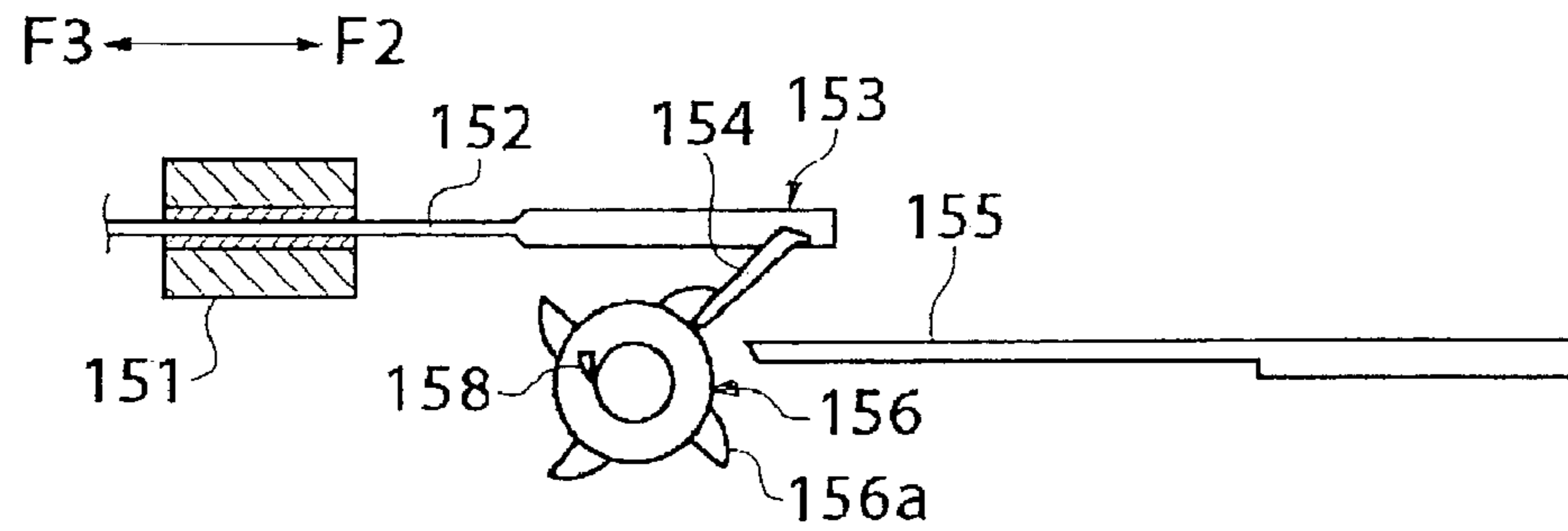


Fig. 30 A

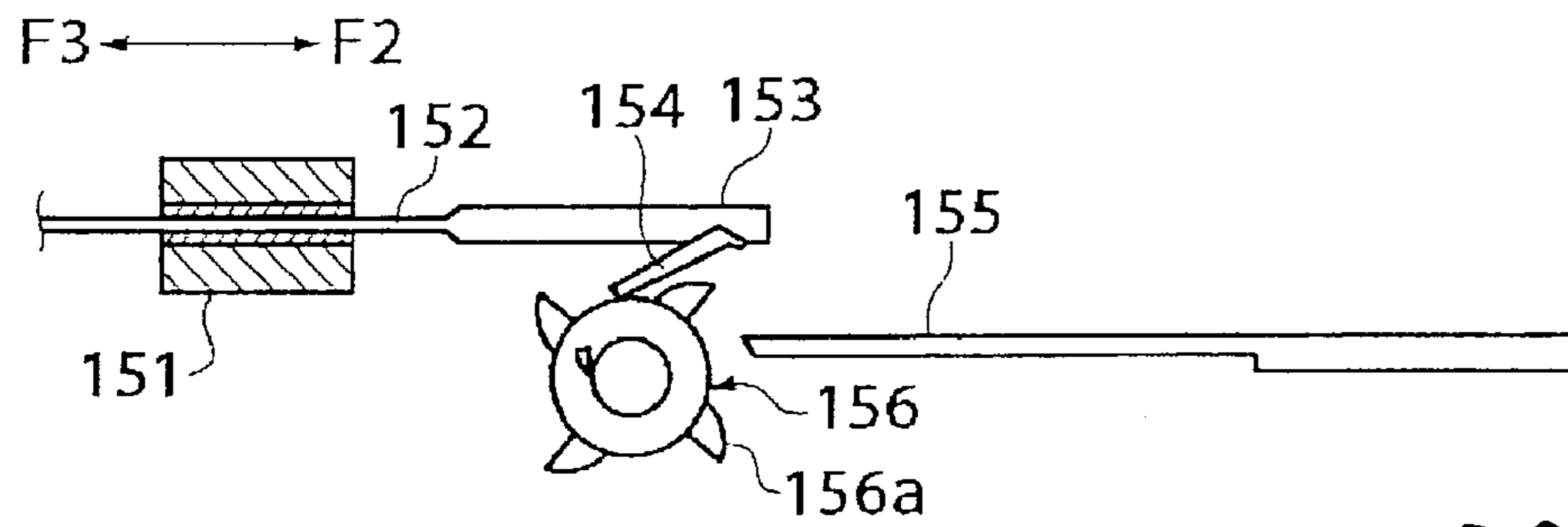


Fig. 30 B

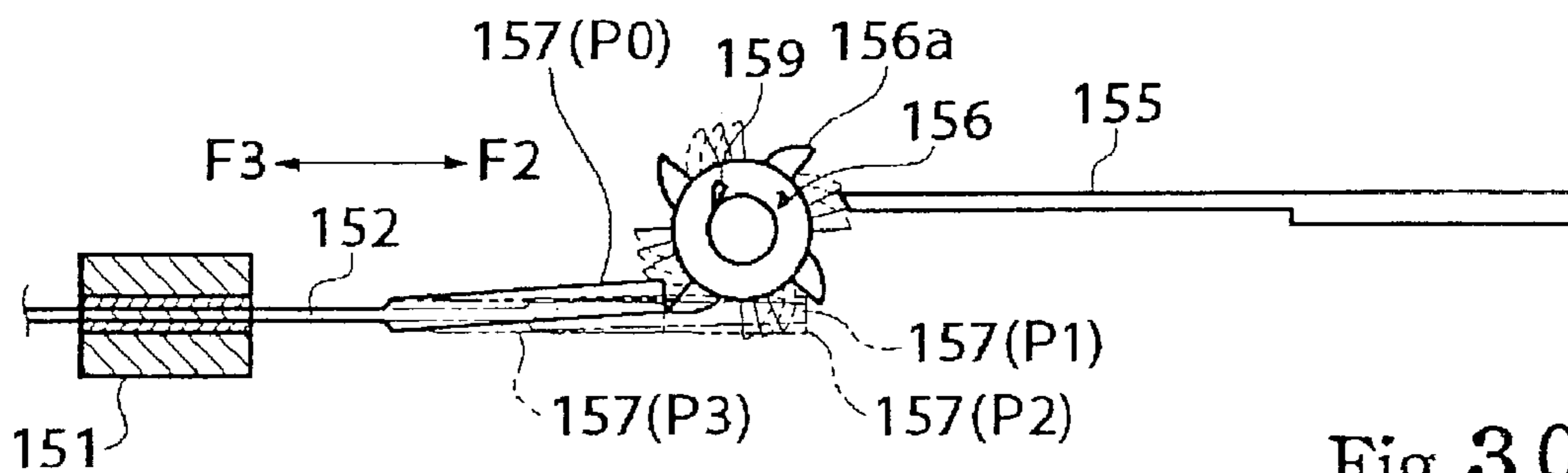


Fig. 30 C

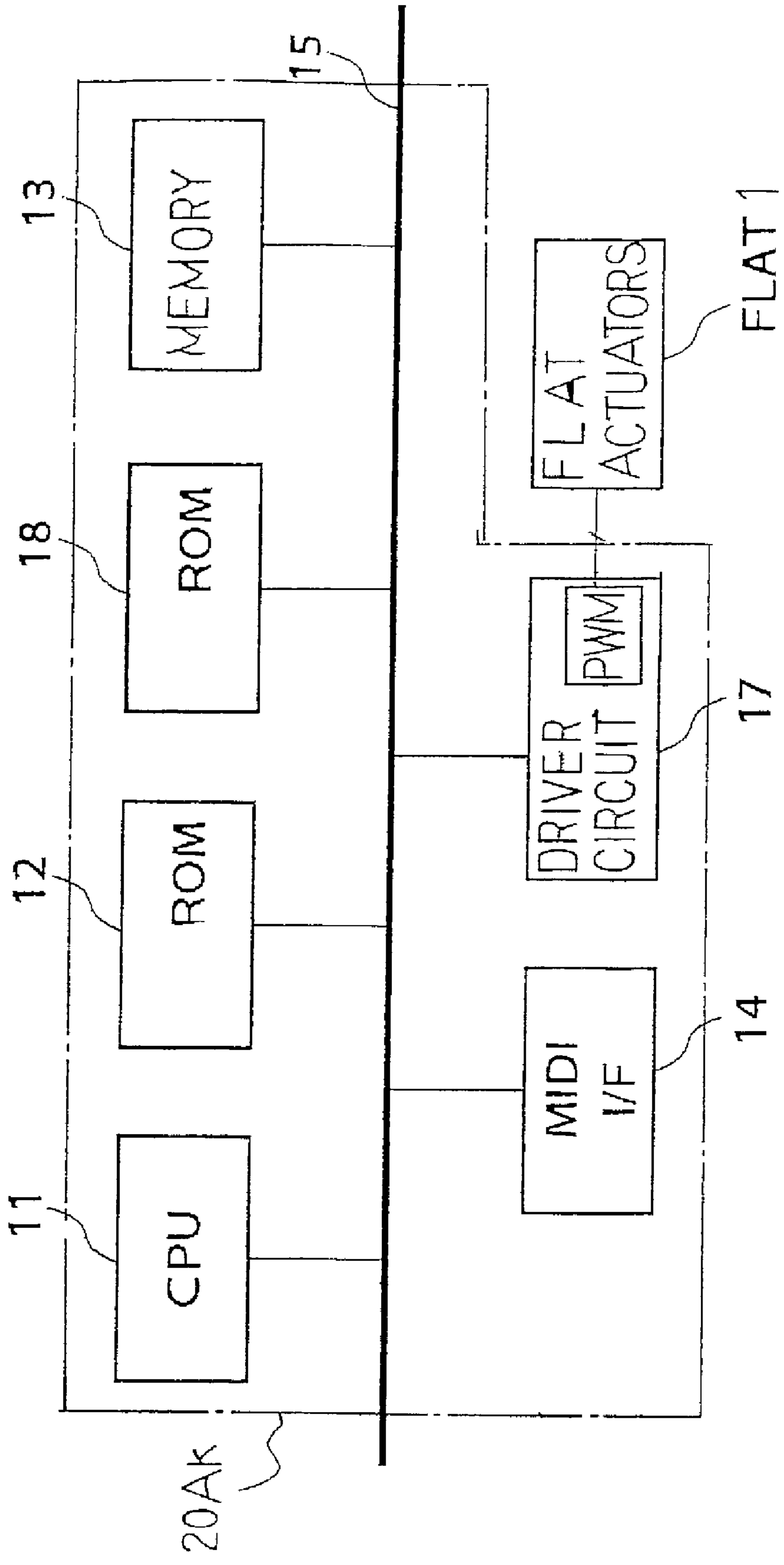


Fig. 31

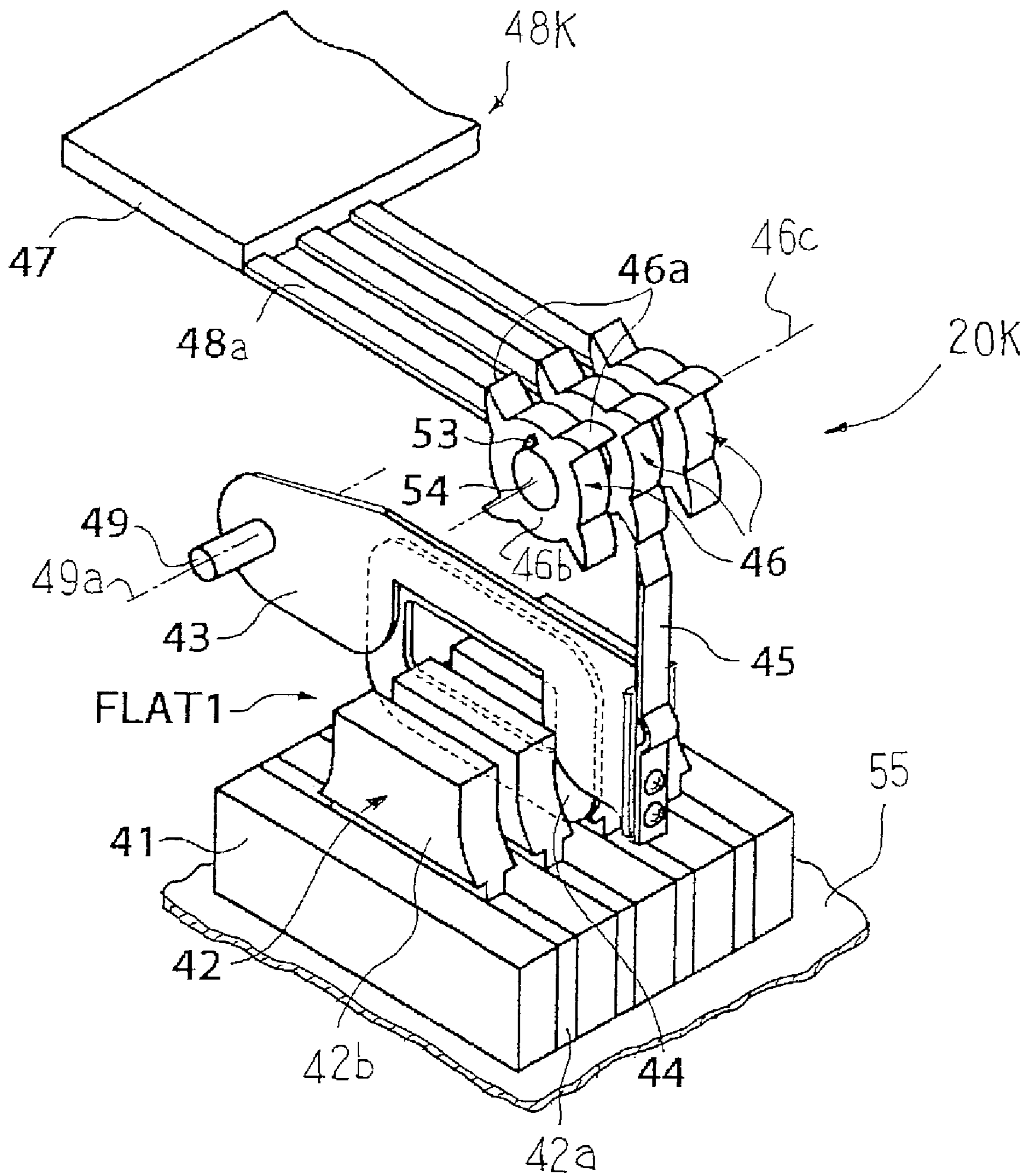


Fig. 32

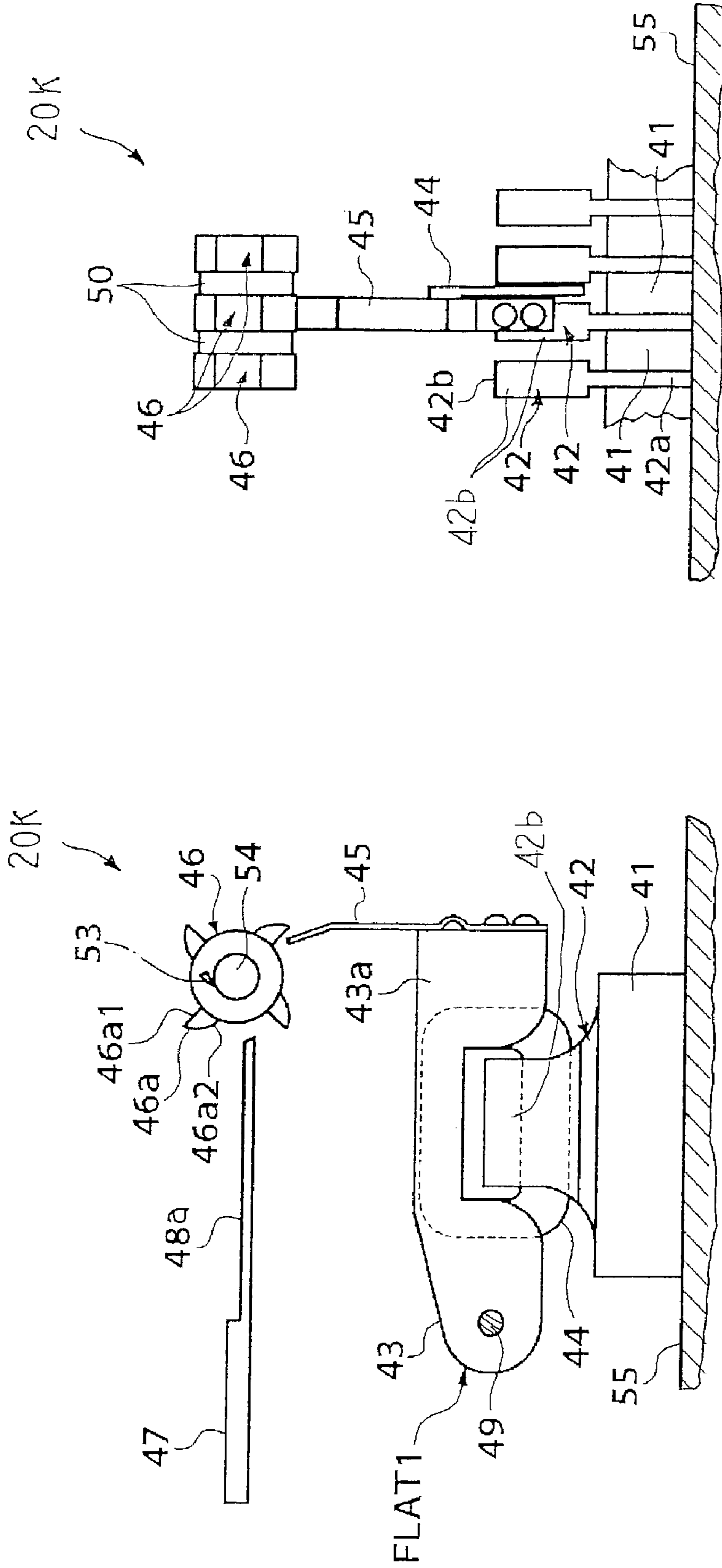


Fig. 33A

Fig. 33B

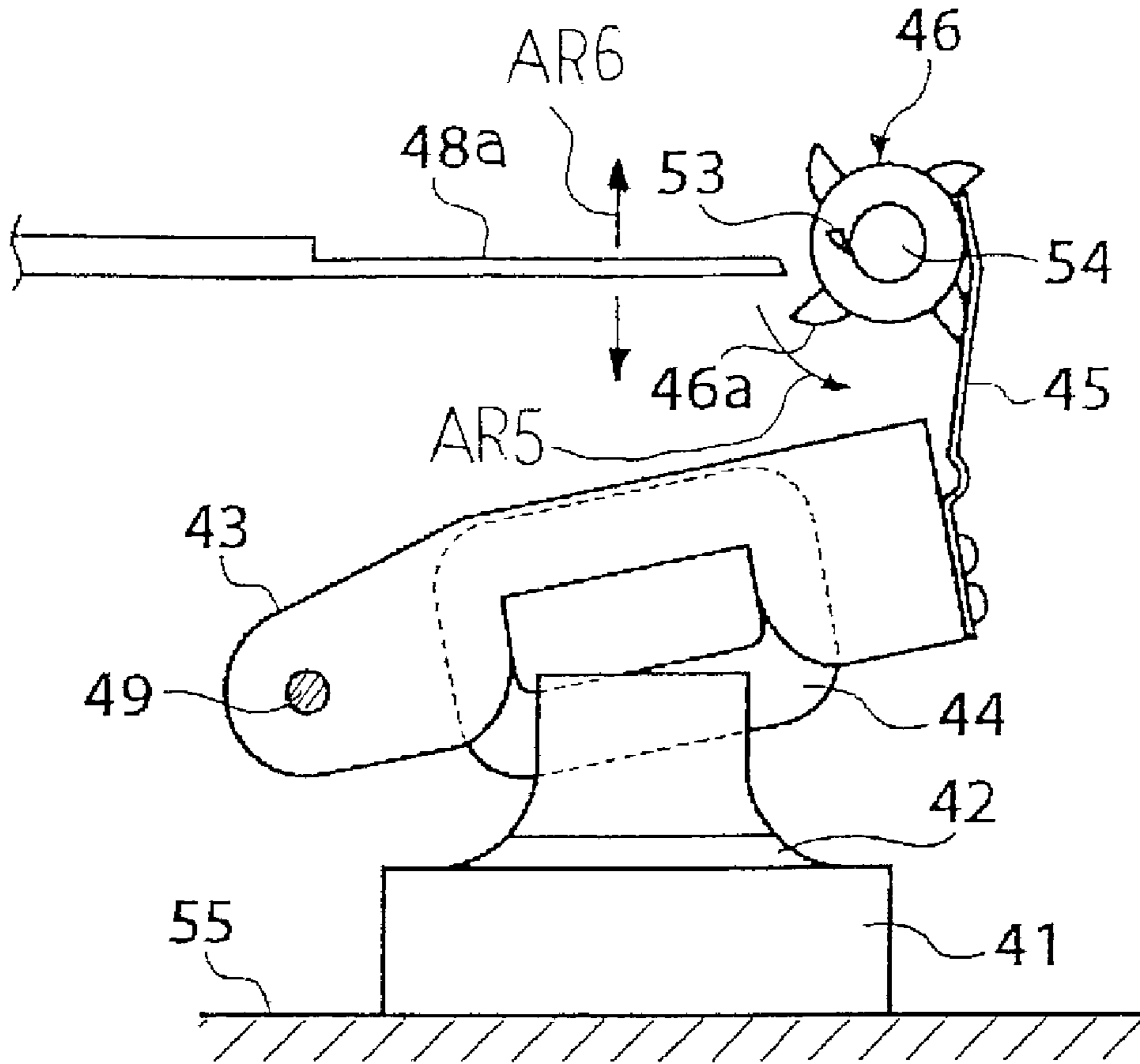


Fig. 34

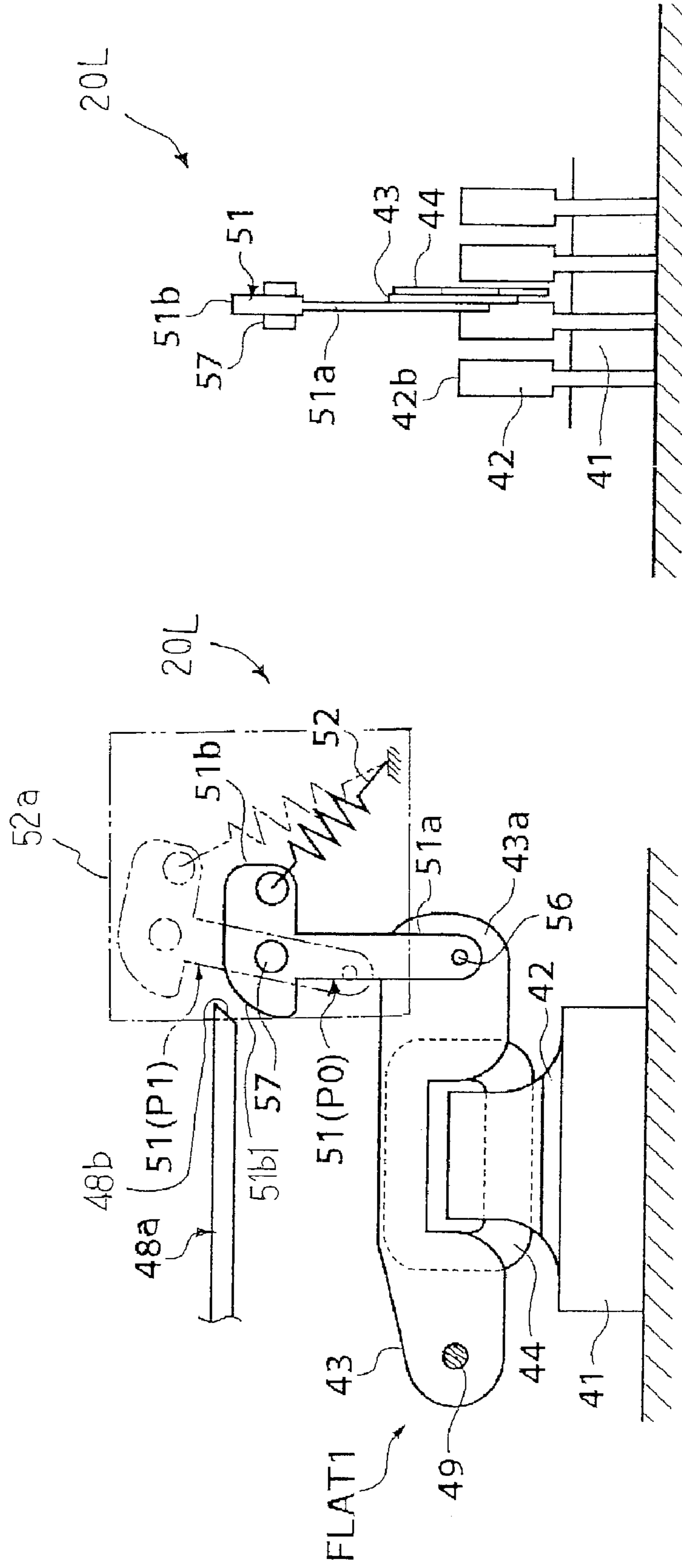


Fig. 35B

Fig. 35A

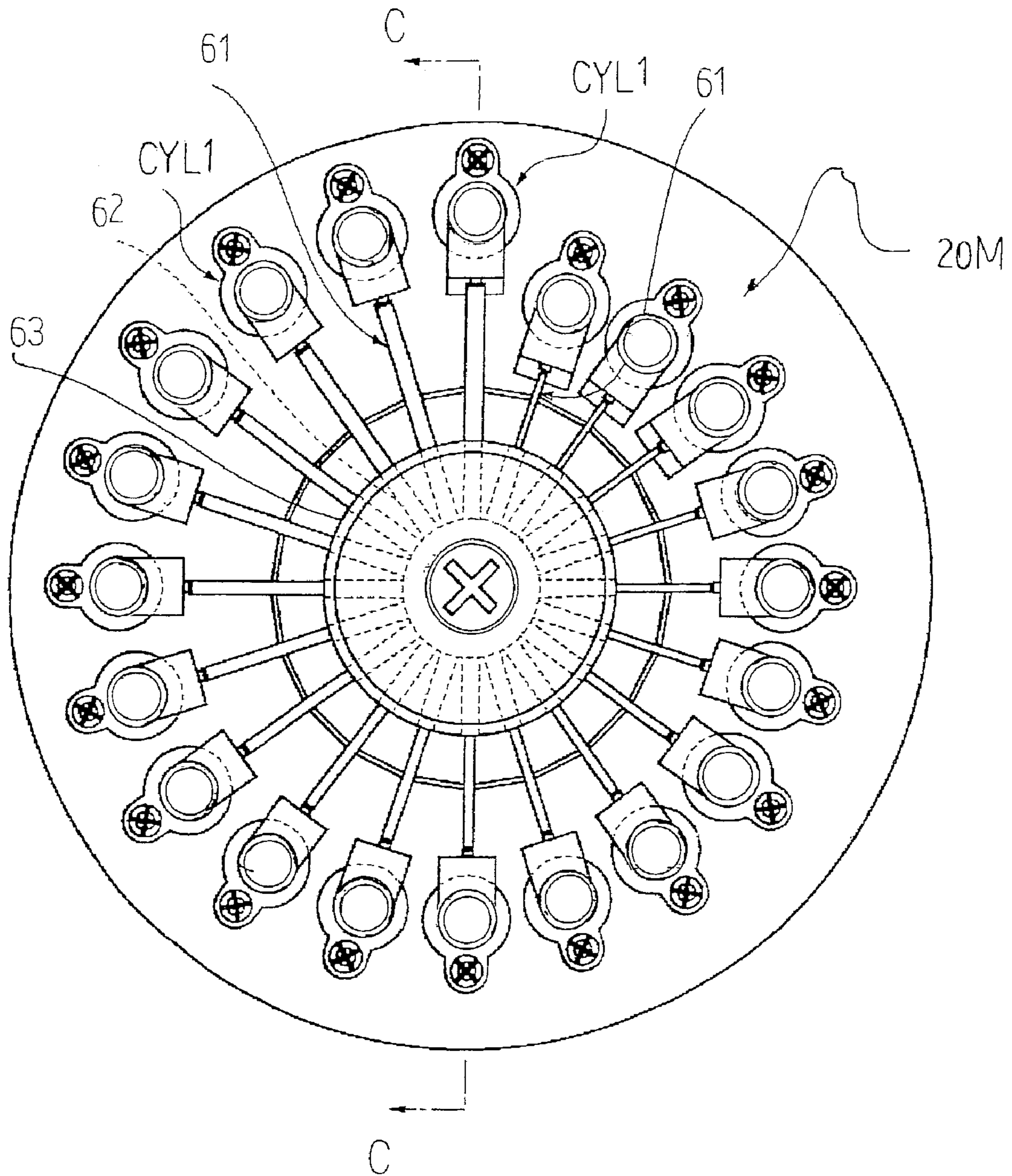


Fig. 36

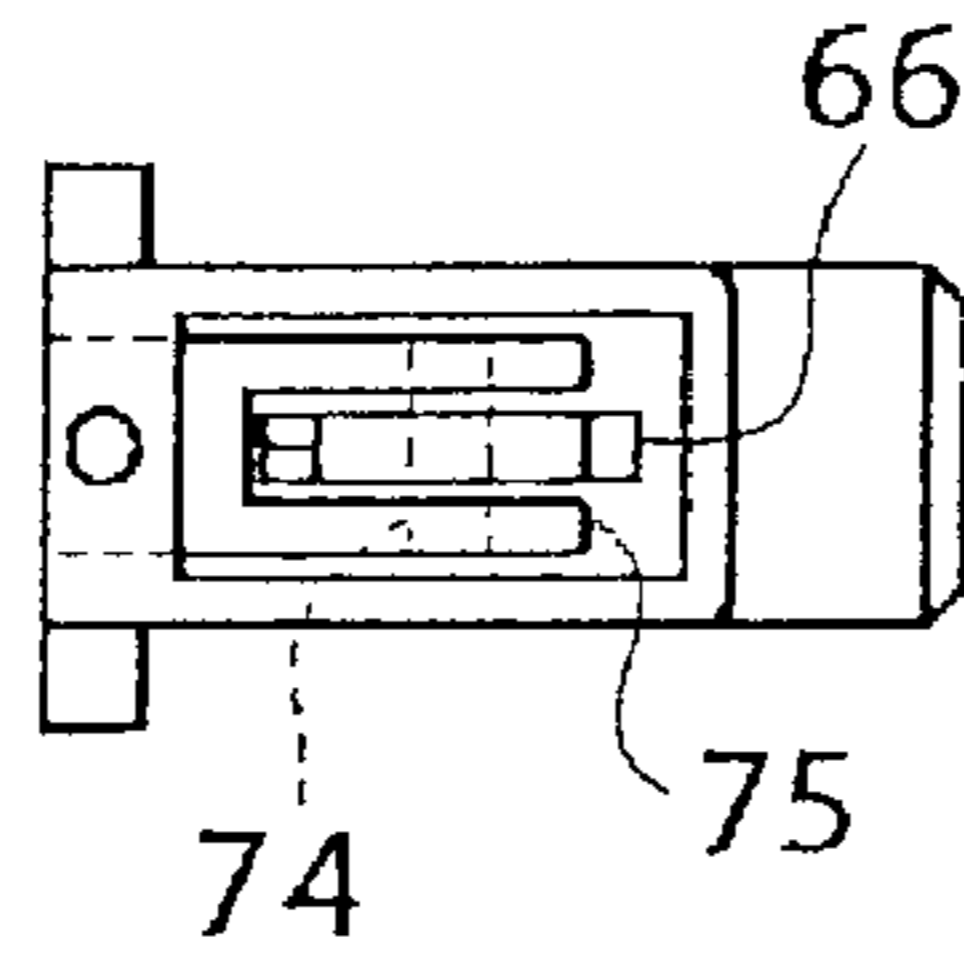


Fig. 37 C

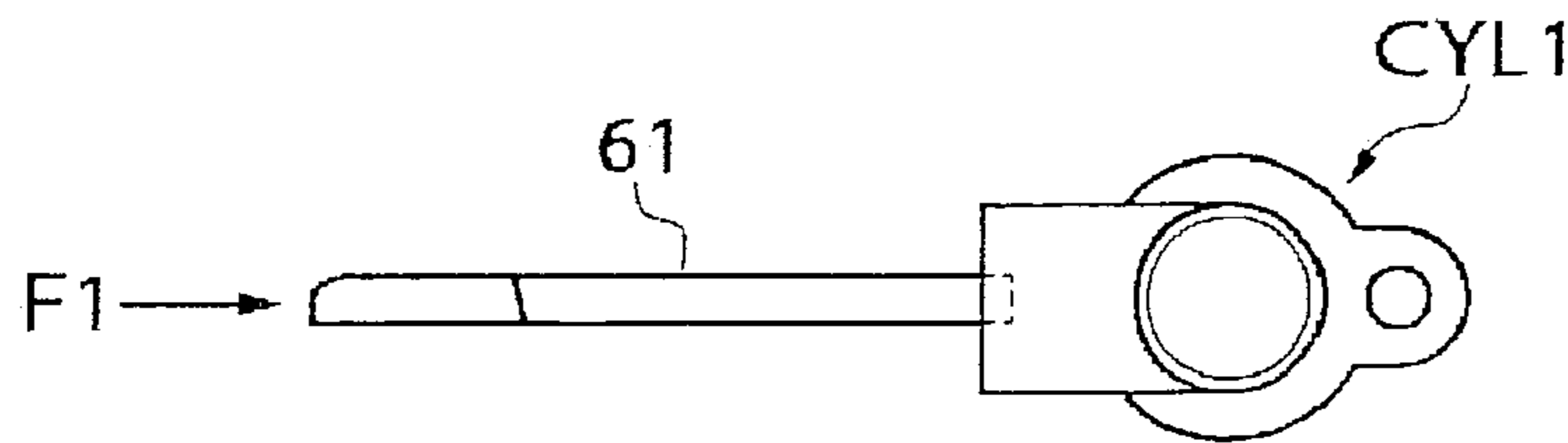


Fig. 37 B

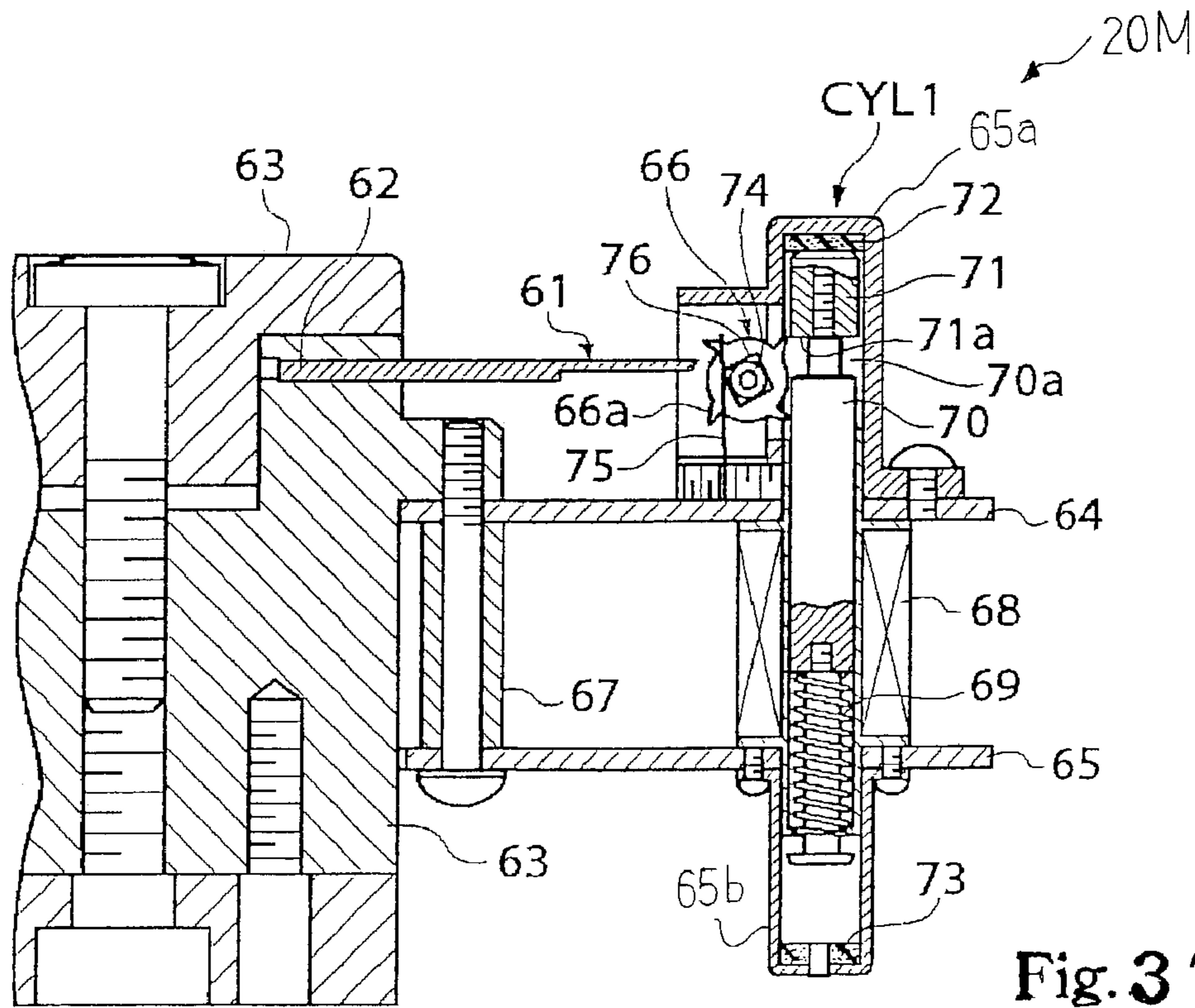


Fig. 37 A

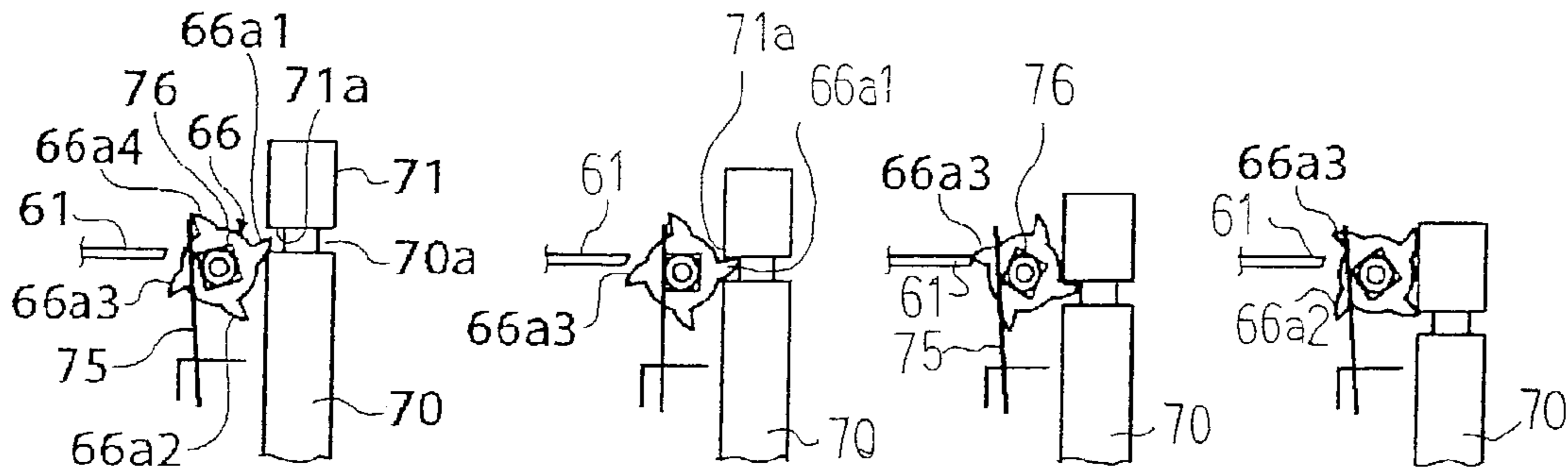


Fig. 38 A

Fig. 38 B

Fig. 38 C

Fig. 38 D

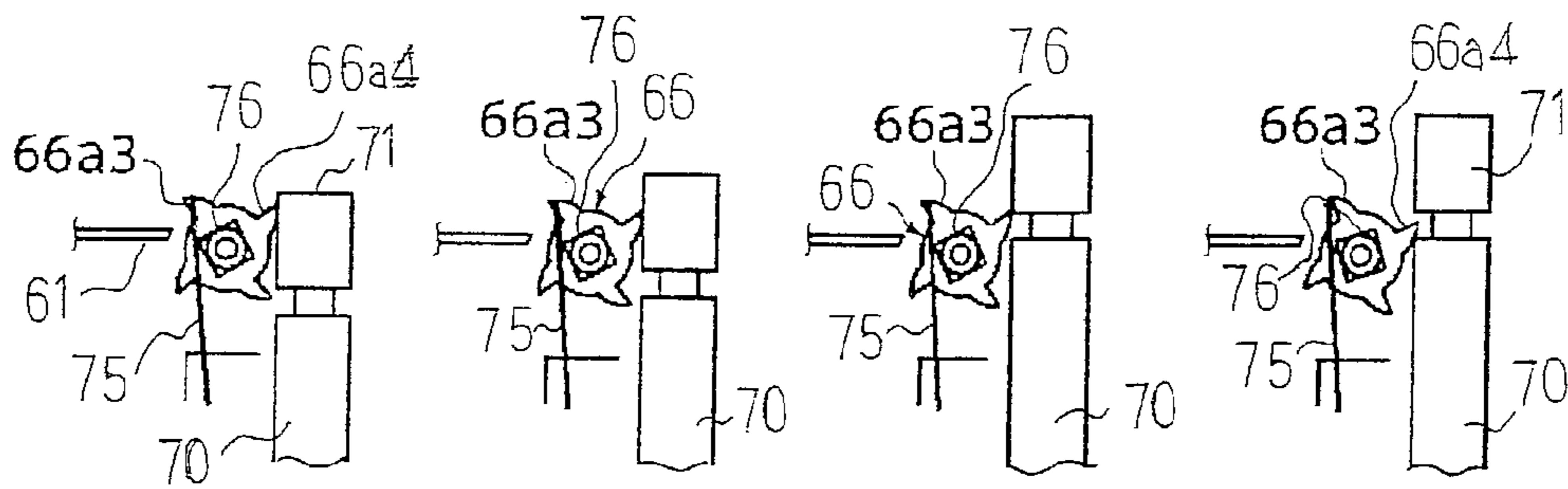


Fig. 38 E

Fig. 38 F

Fig. 38 G

Fig. 38 H

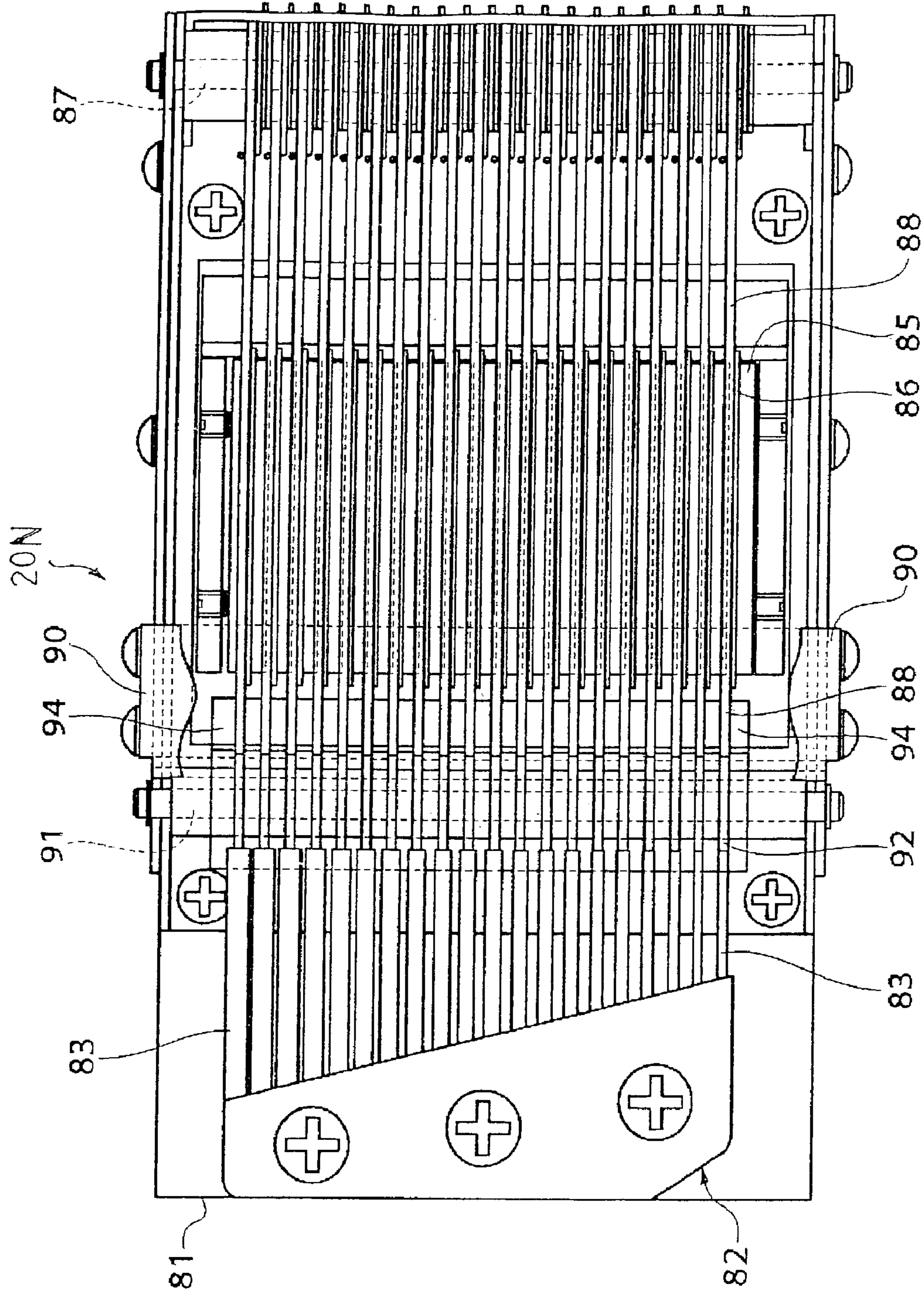


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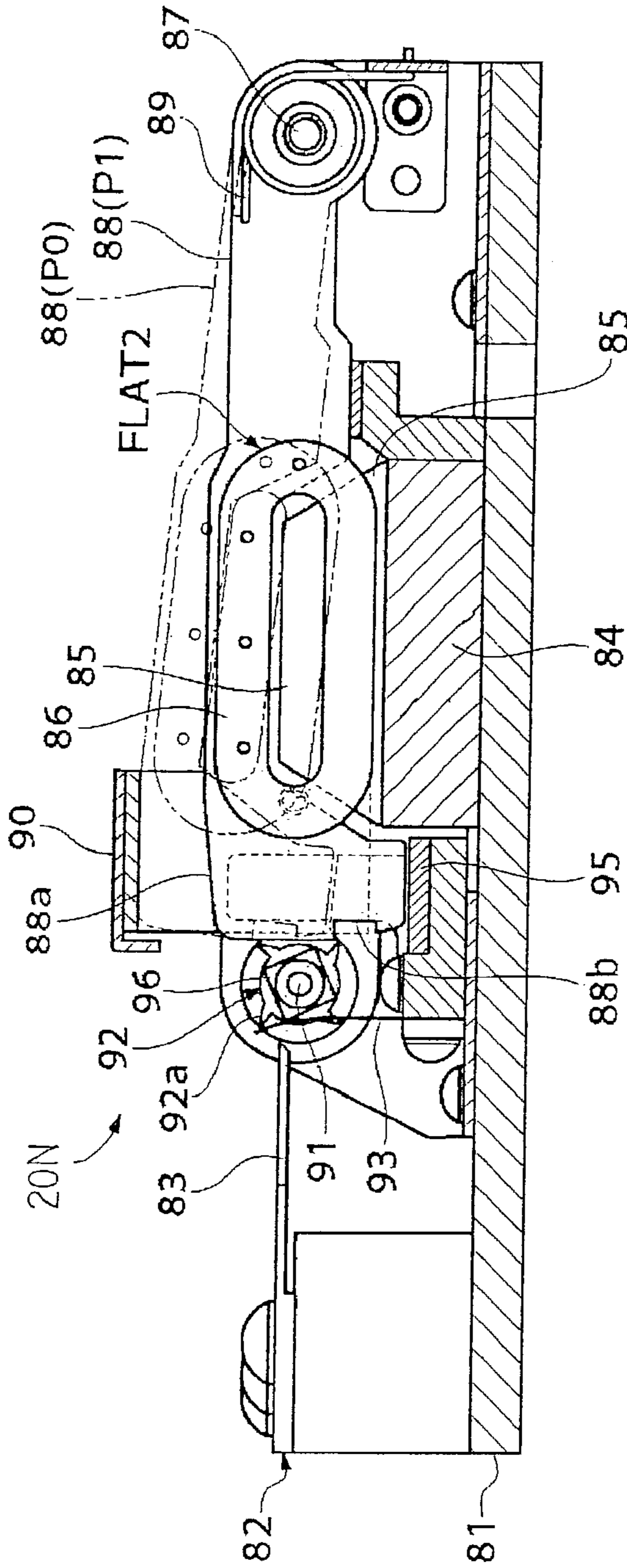


Fig. 40A

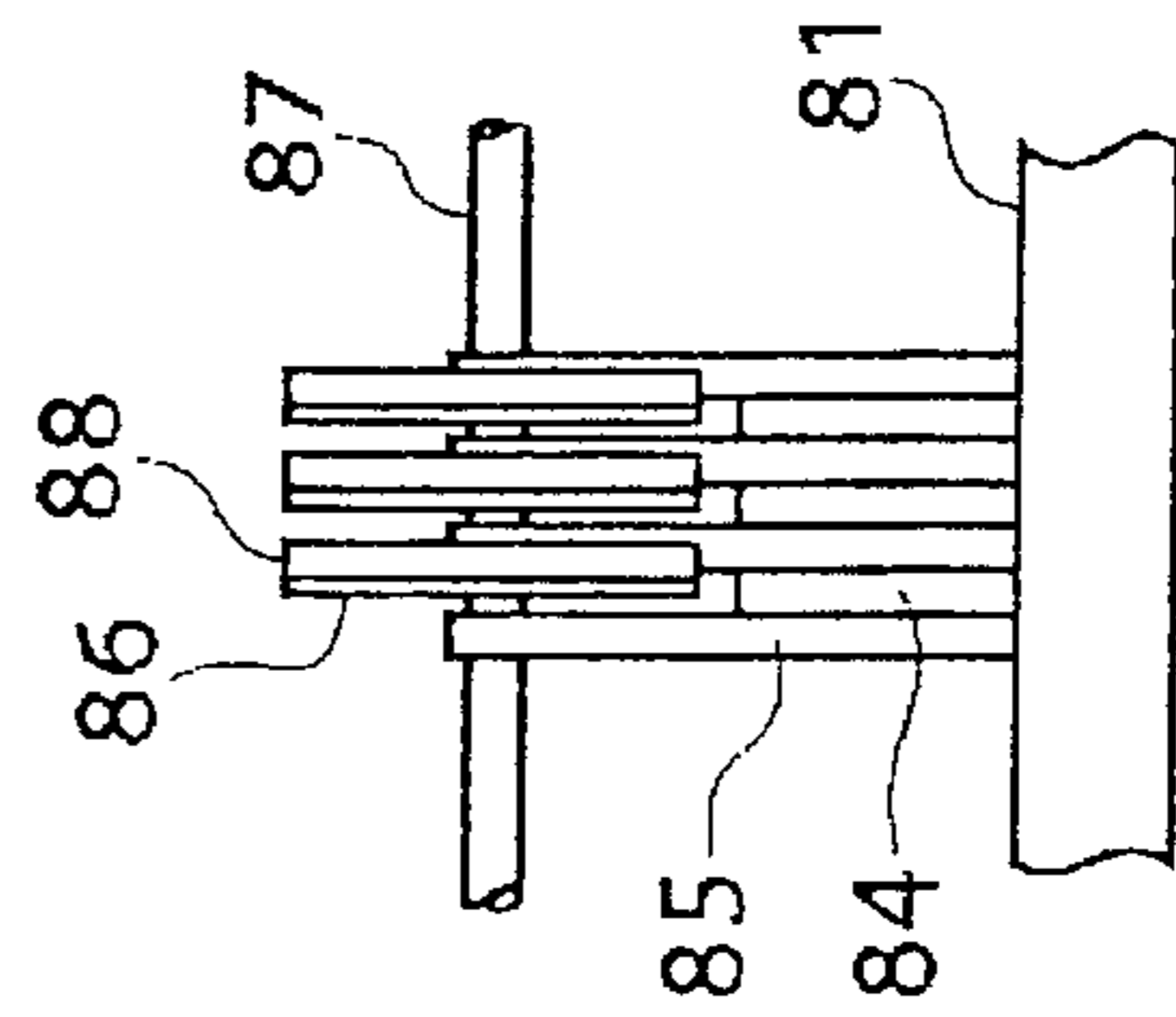


Fig. 40B

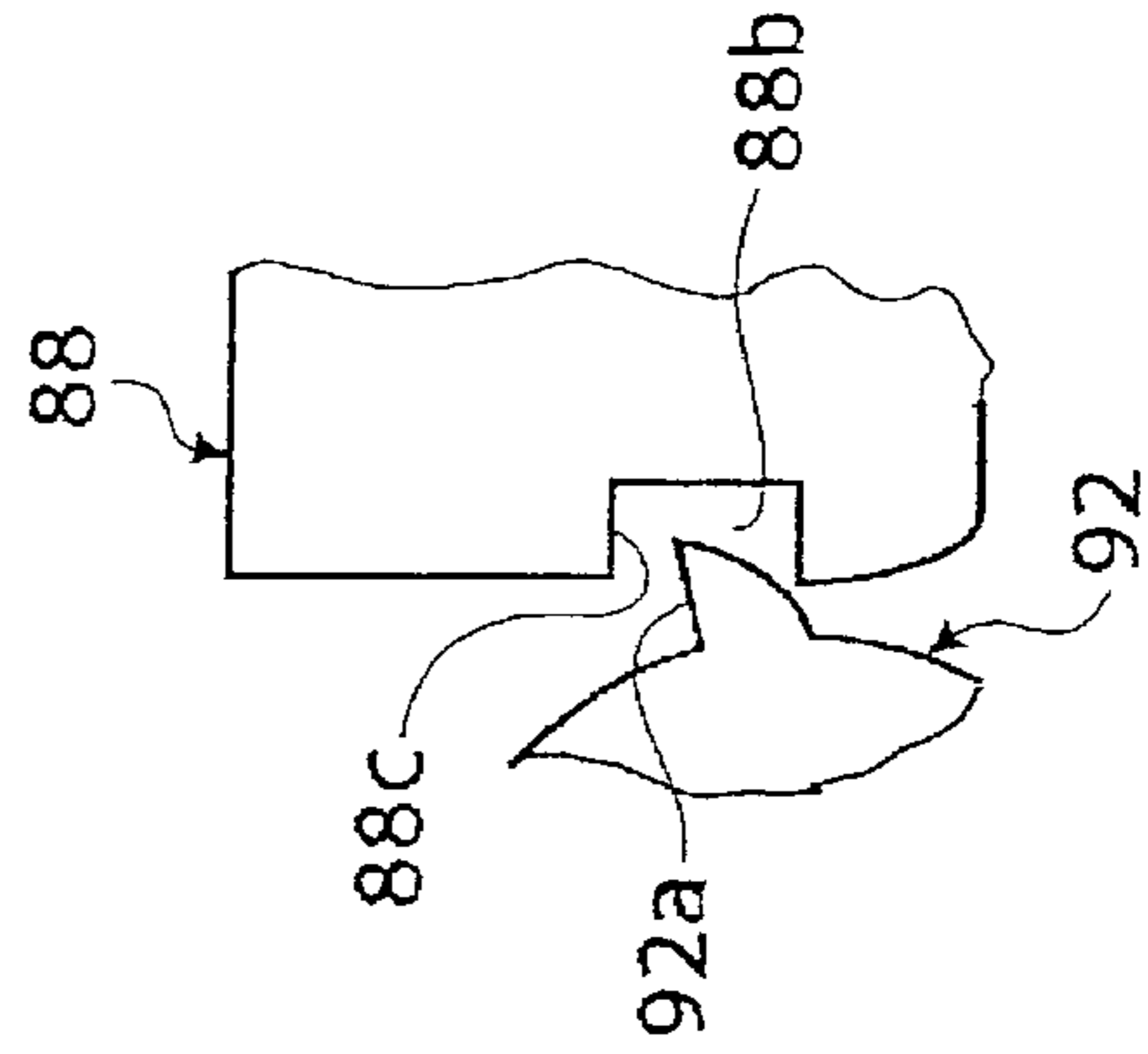


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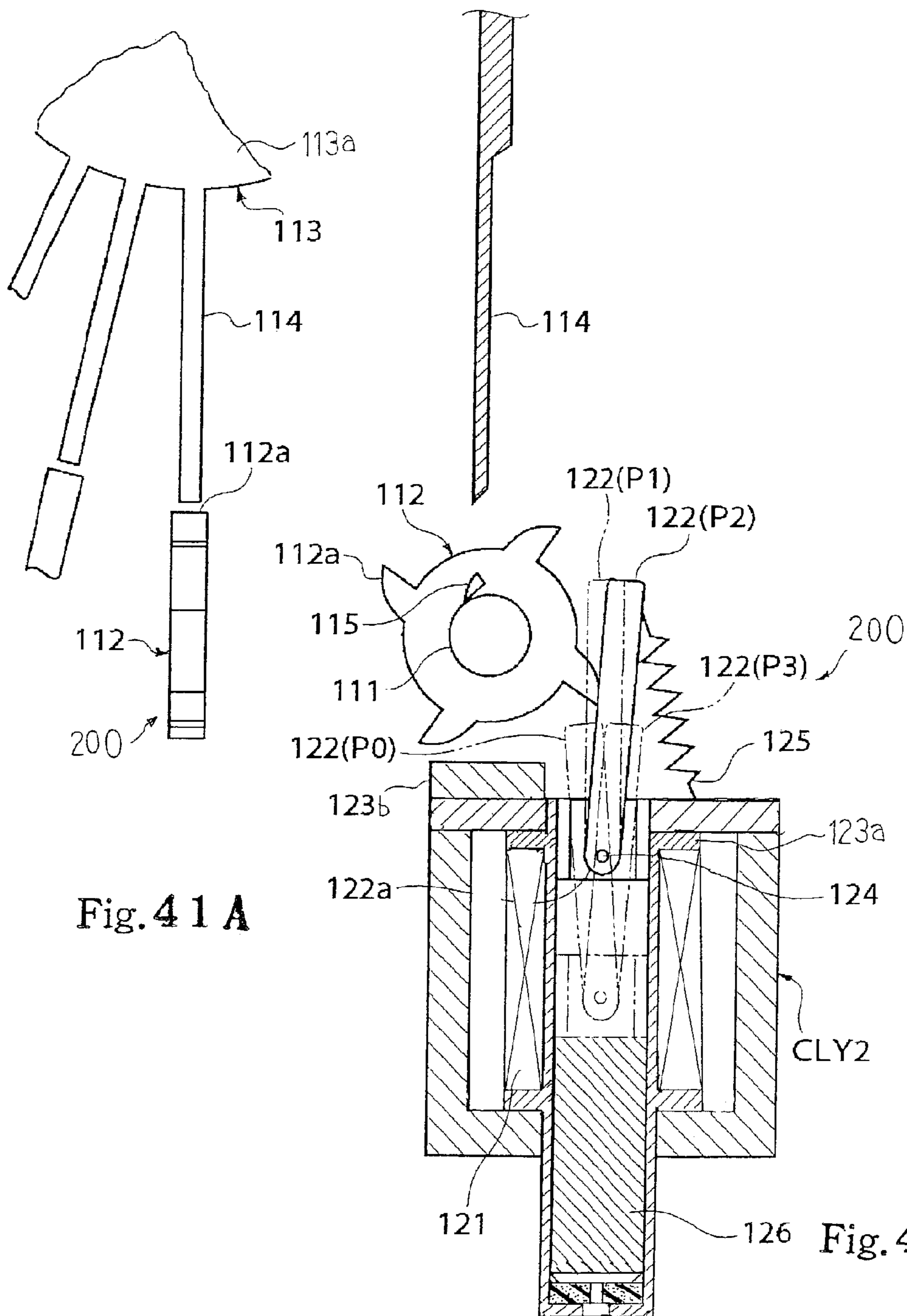


Fig. 41 A

Fig. 41 B

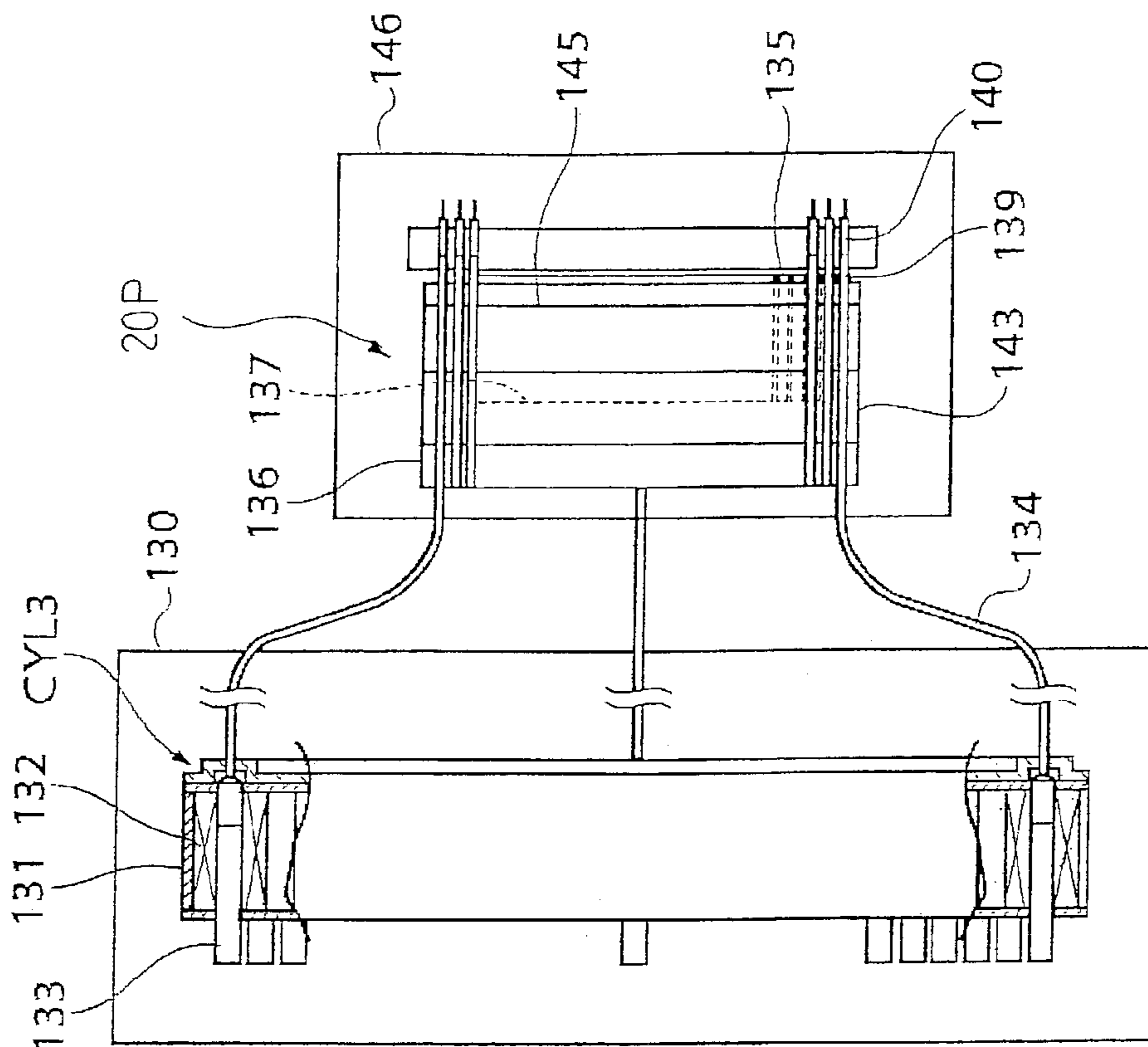


Fig. 42B

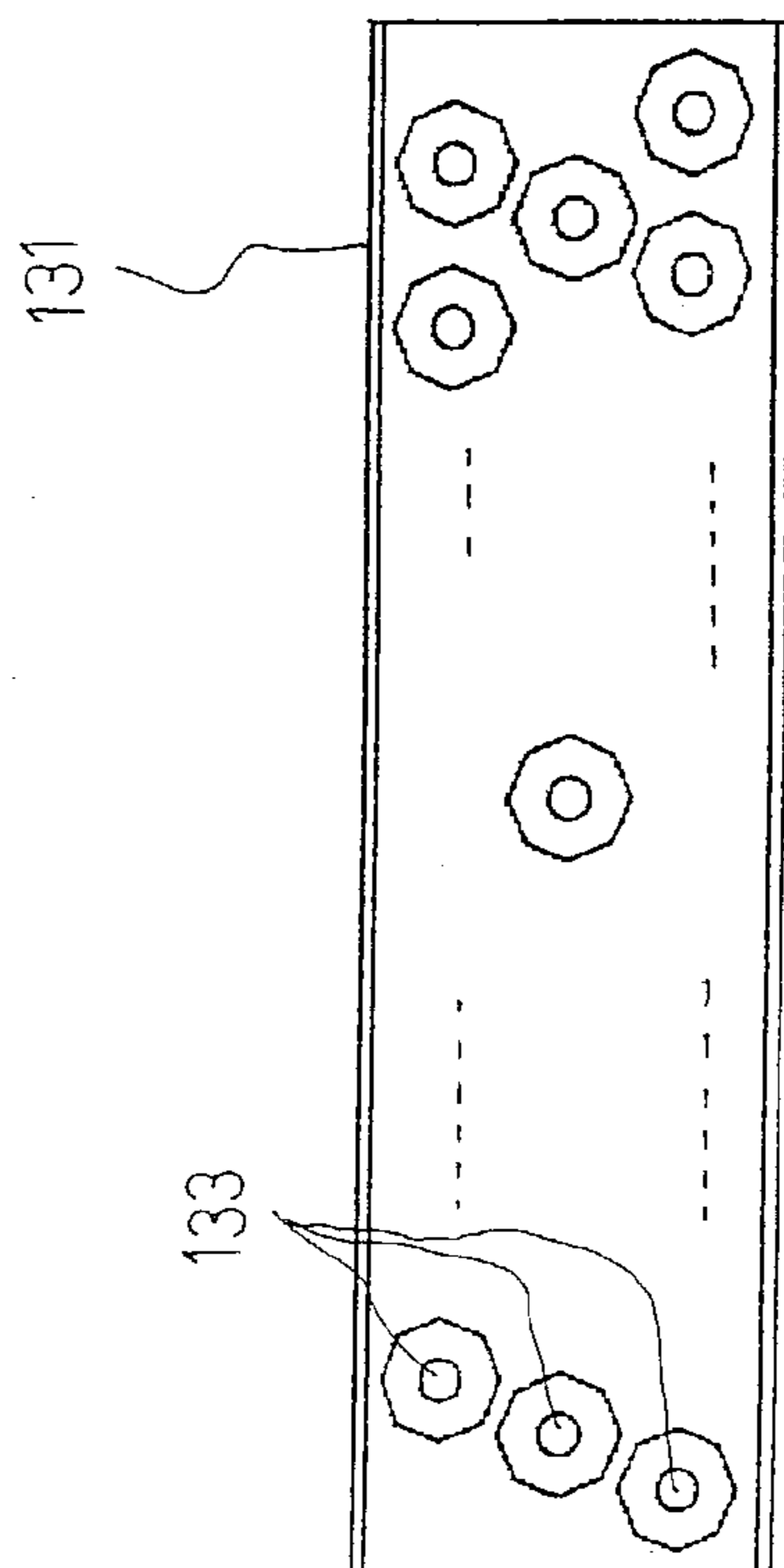


Fig. 42A

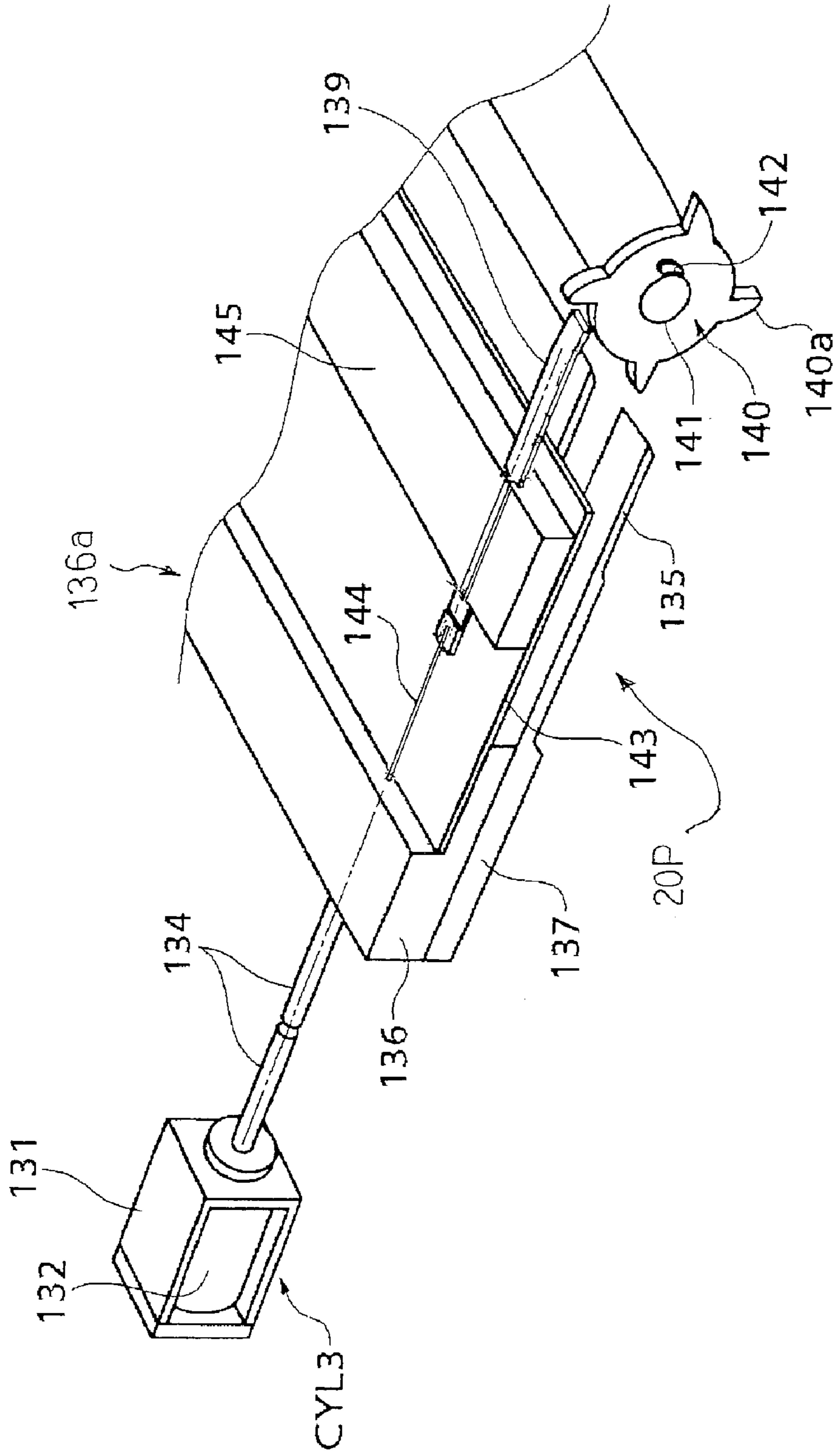


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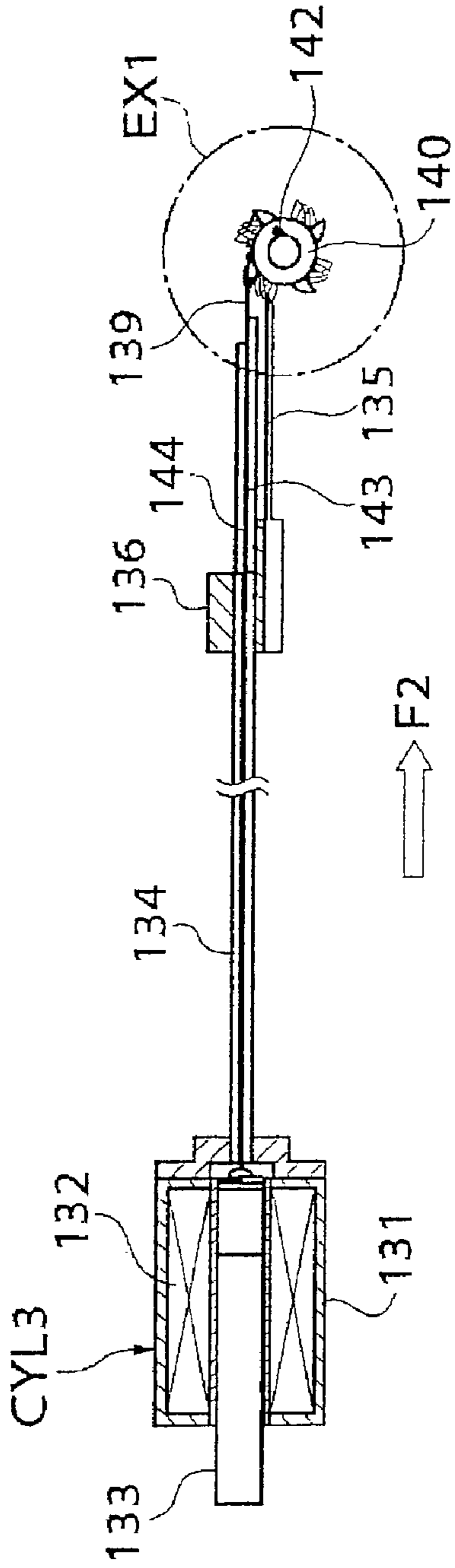


Fig. 44A

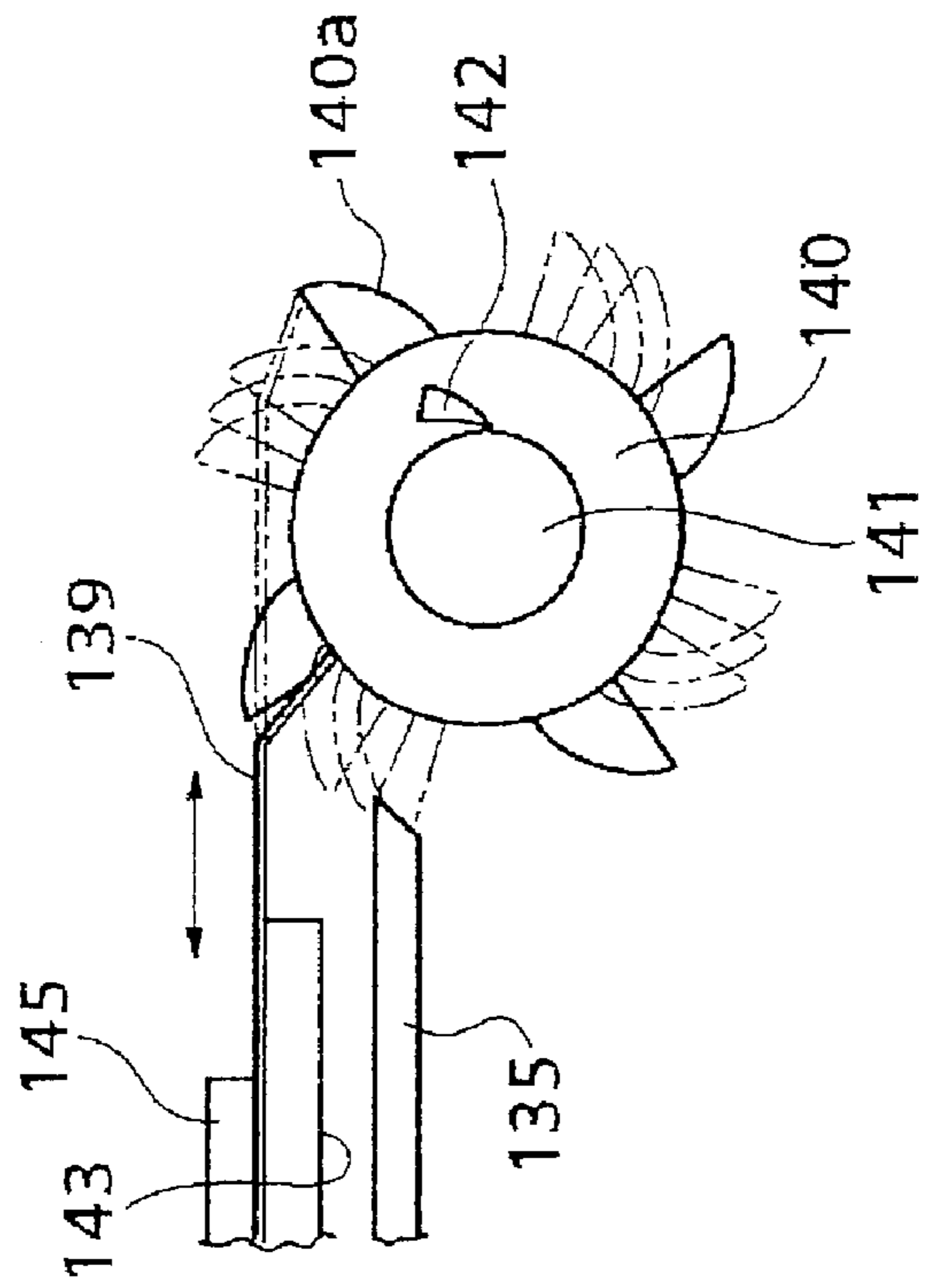


Fig. 44B

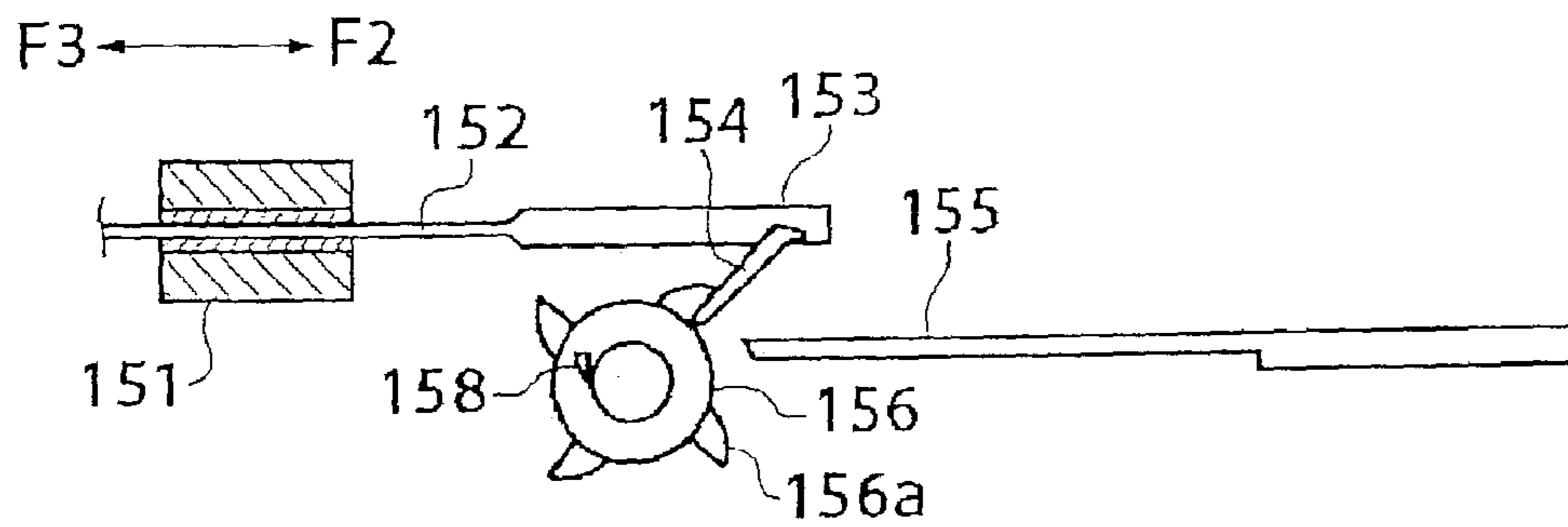


Fig. 45 A

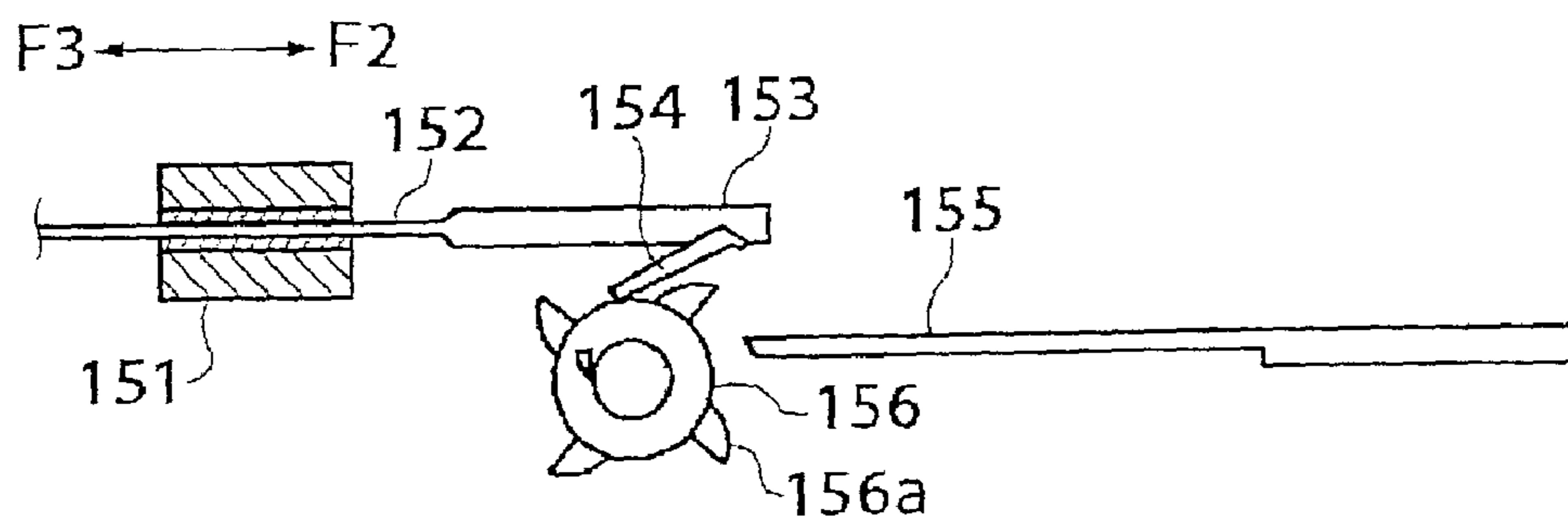


Fig. 45 B

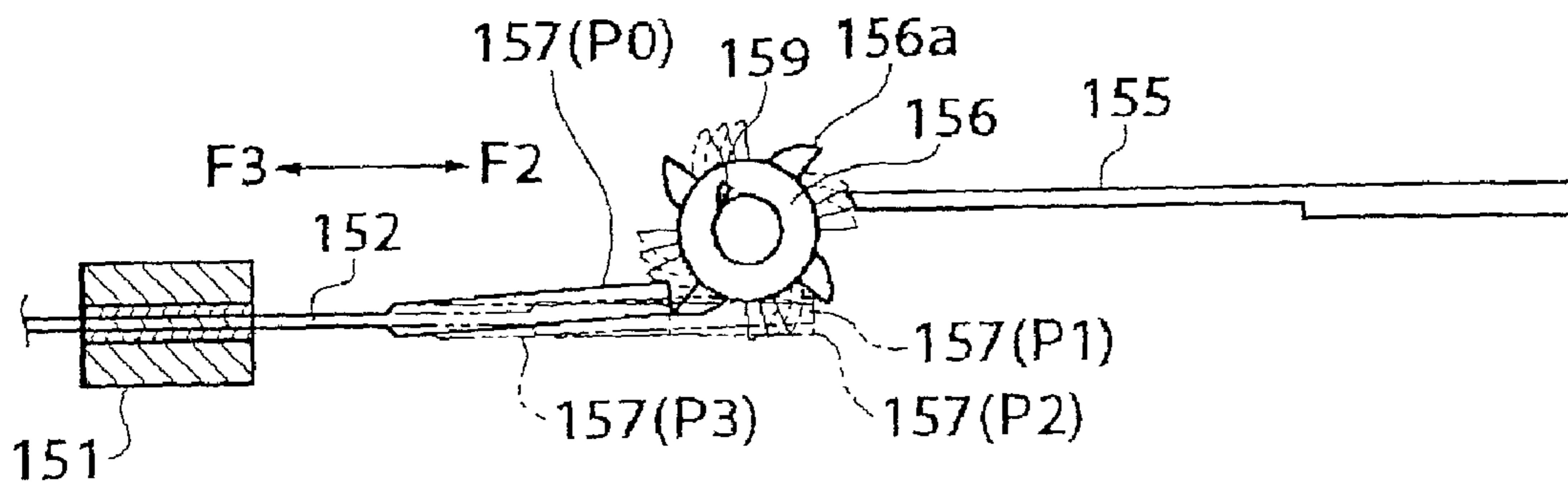


Fig. 45 C

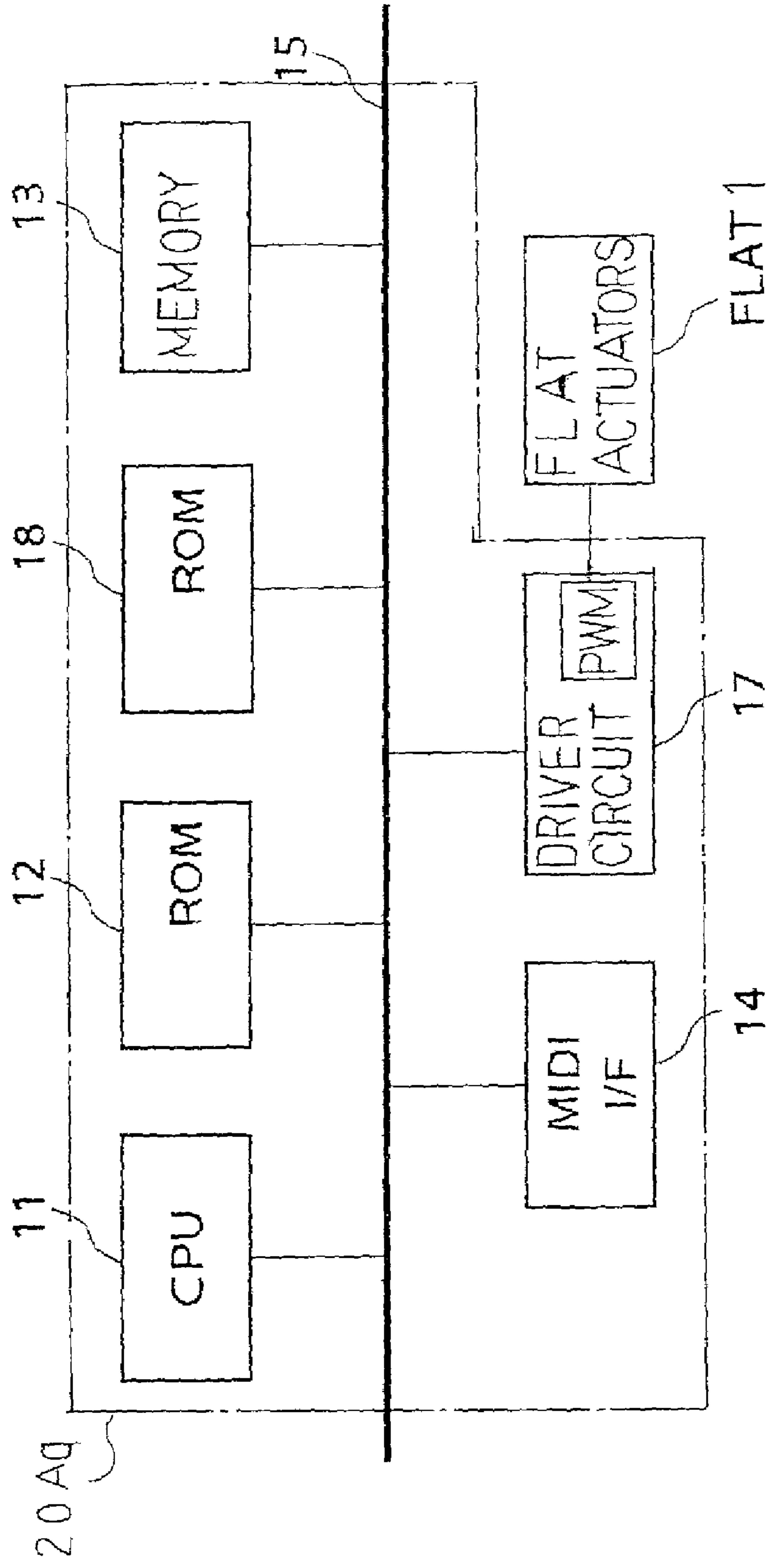


Fig. 46

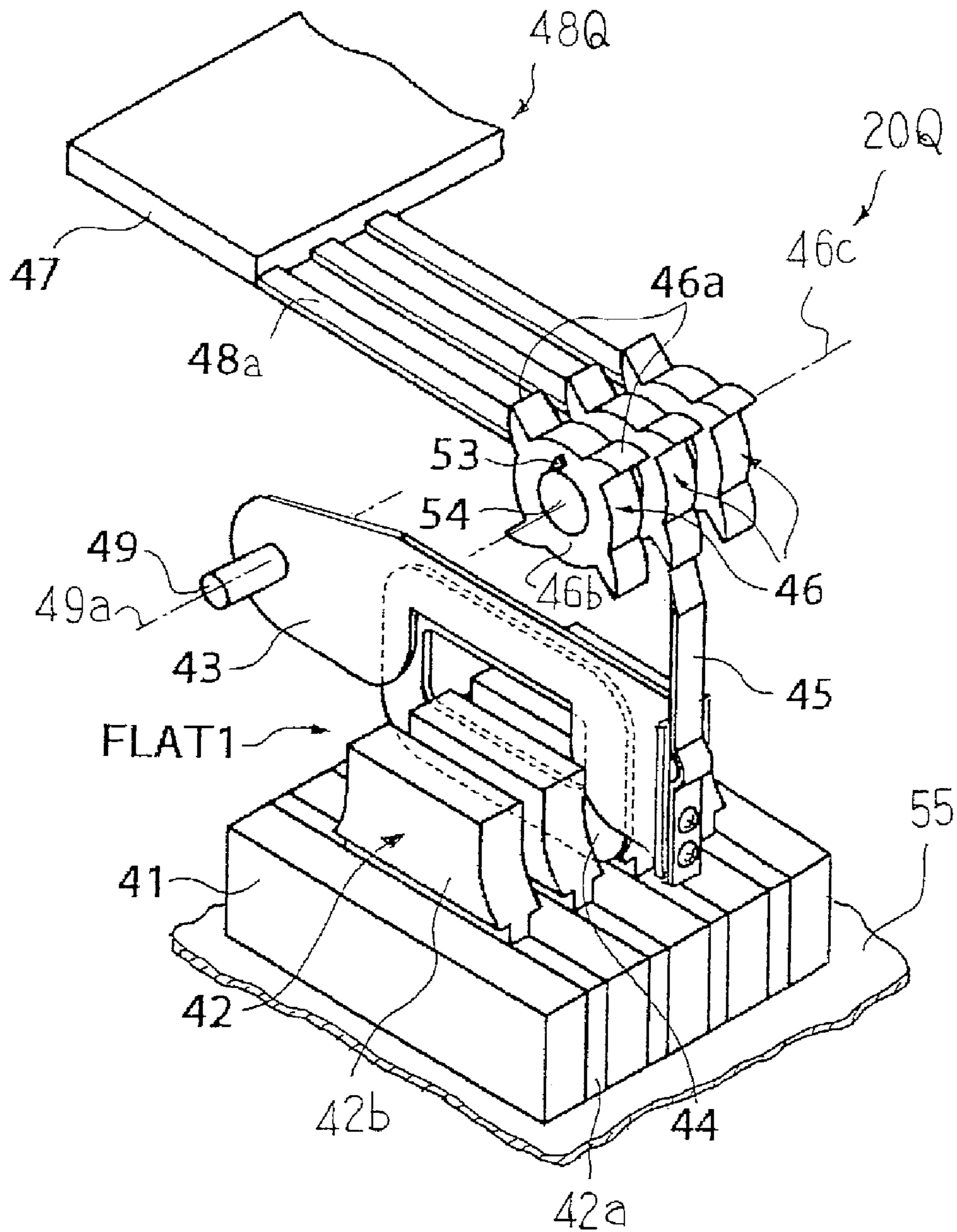


Fig. 47

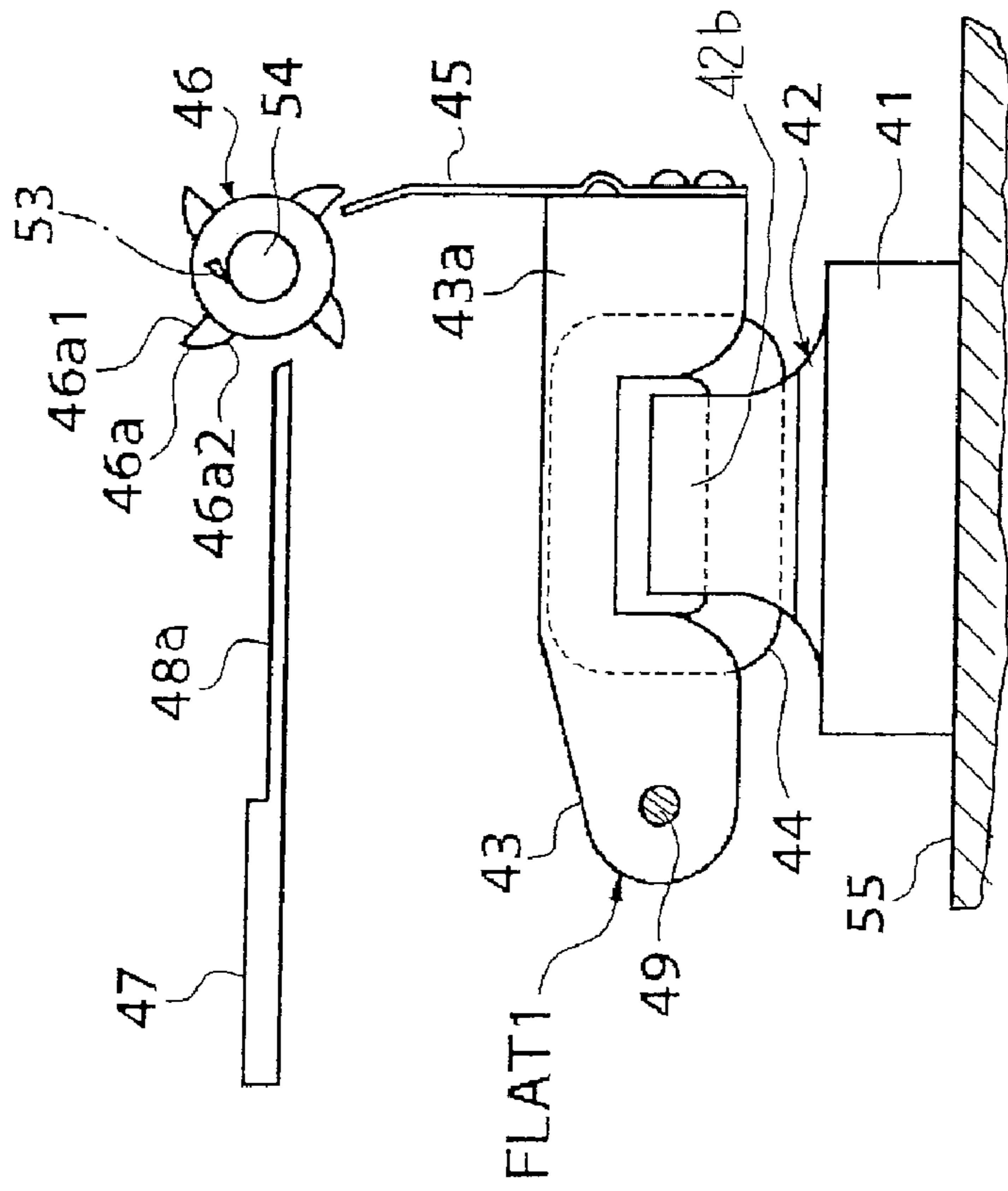


Fig. 48A

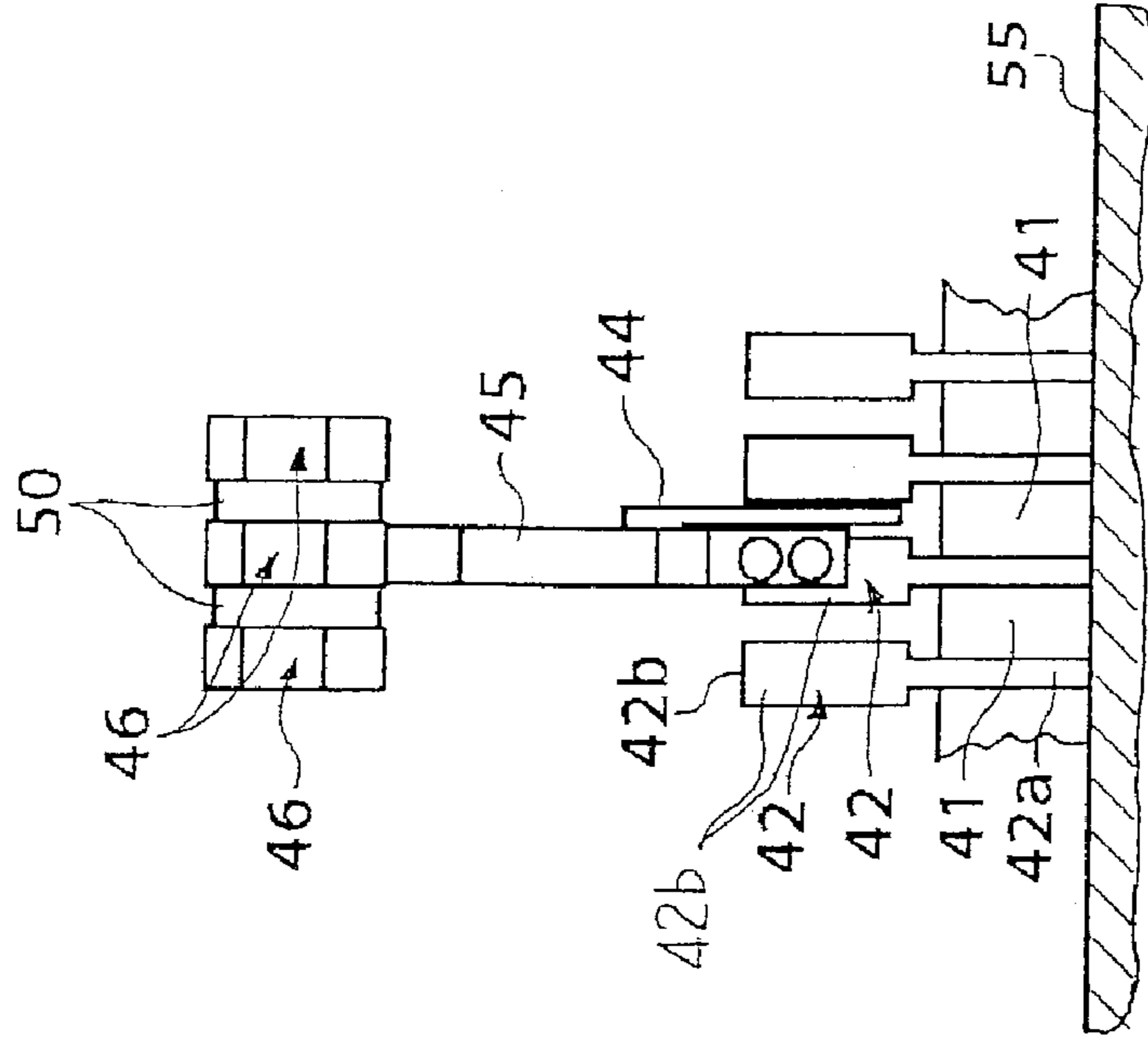


Fig. 48B

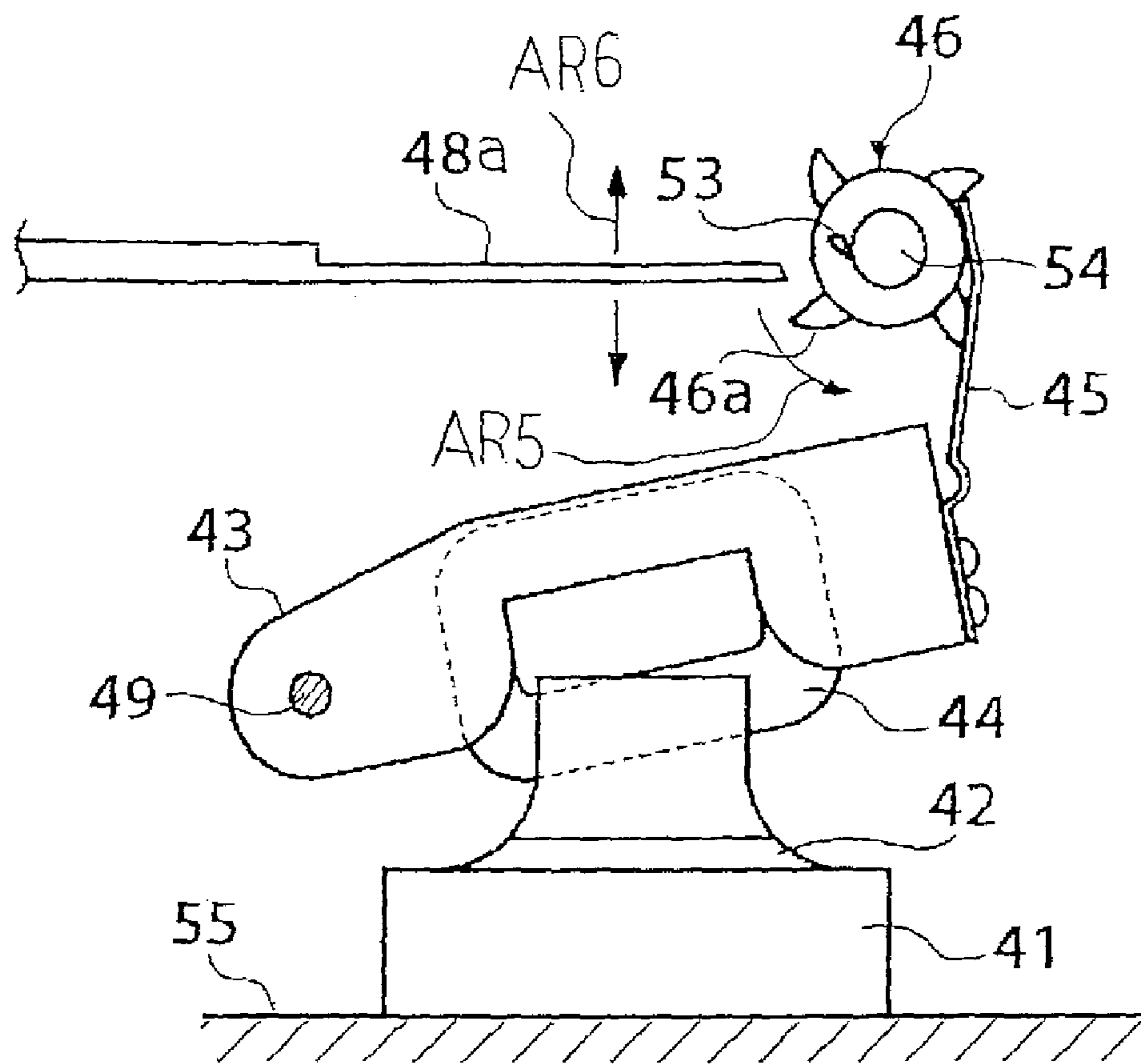


Fig. 49

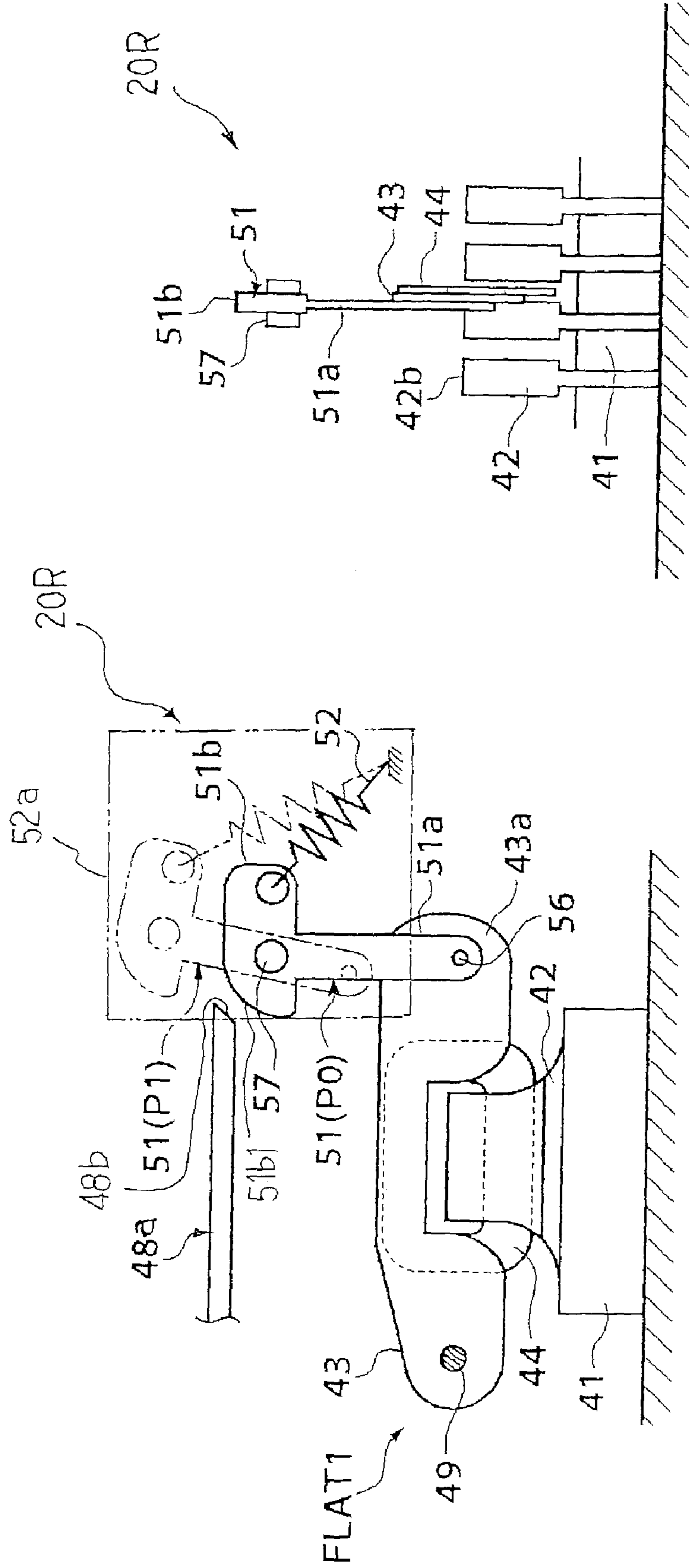


Fig. 50A

Fig. 50B

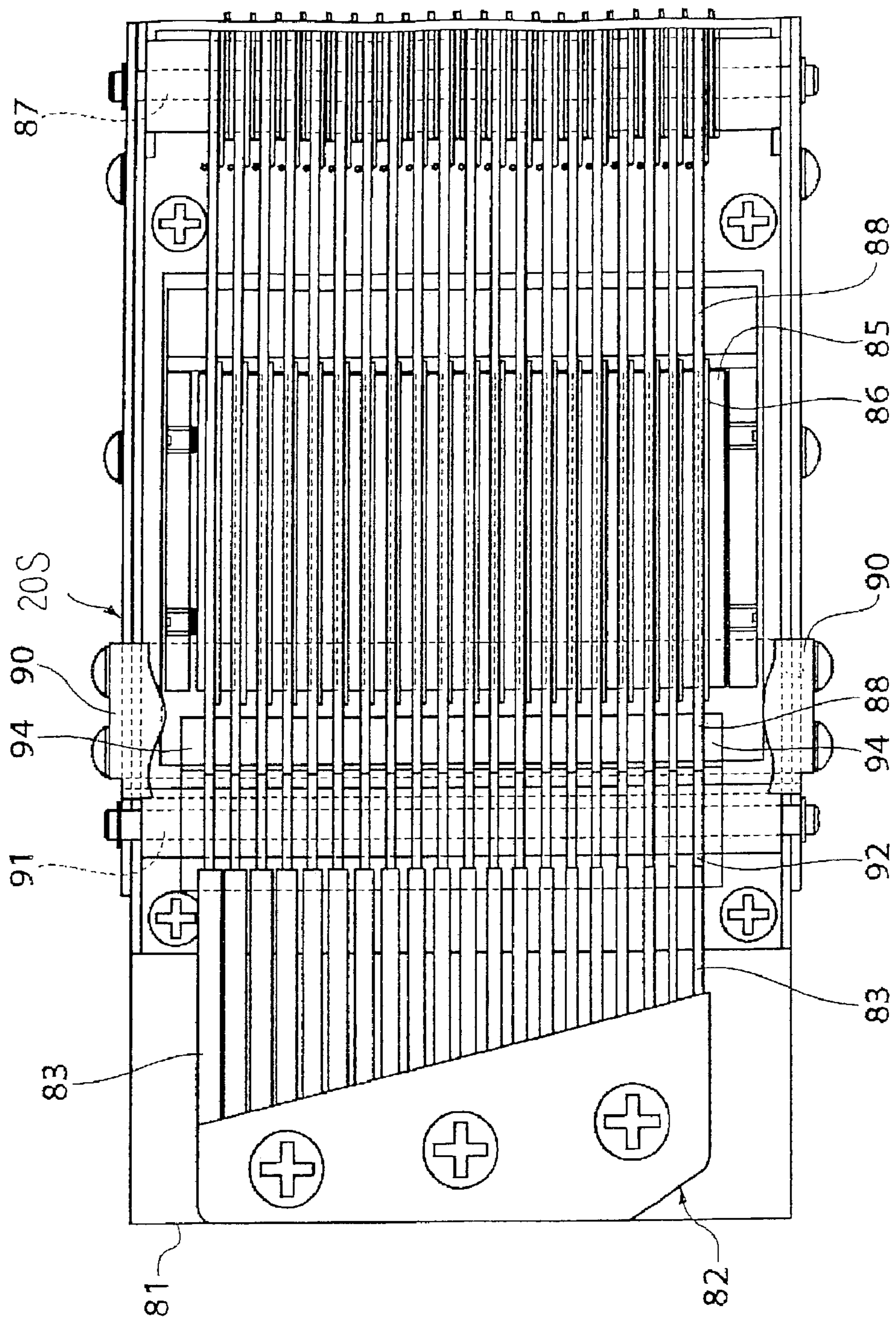


Fig. 51

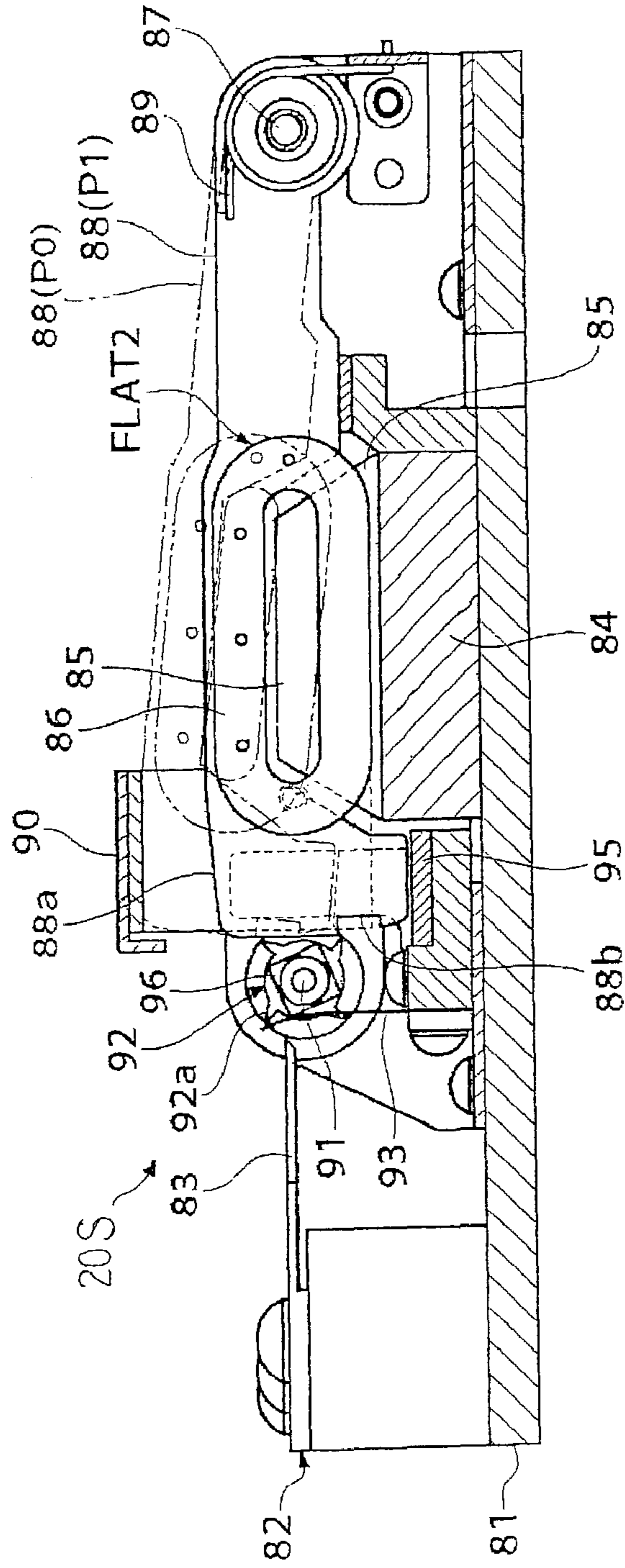


Fig. 52 A

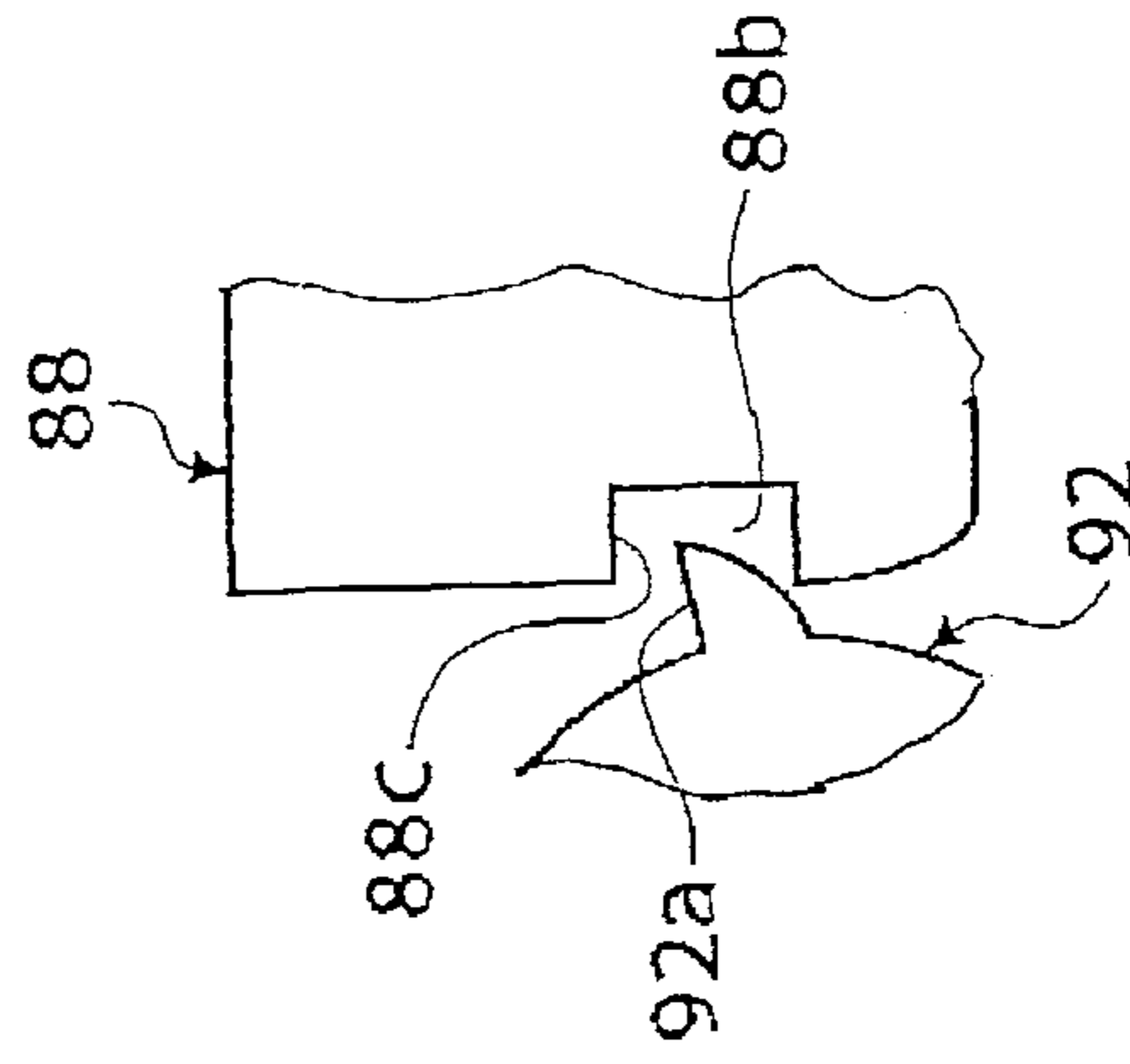


Fig. 52 C

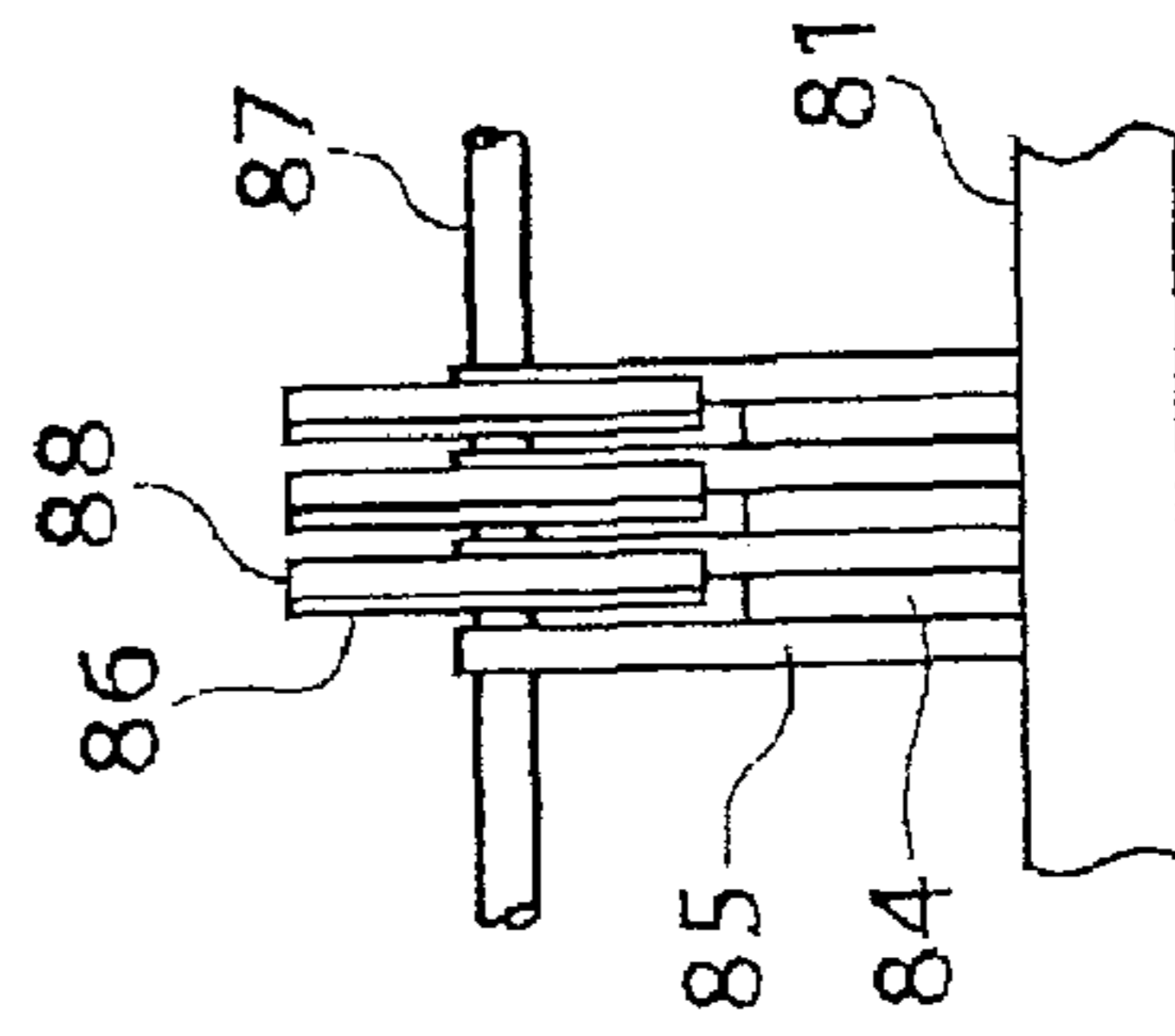


Fig. 52 B

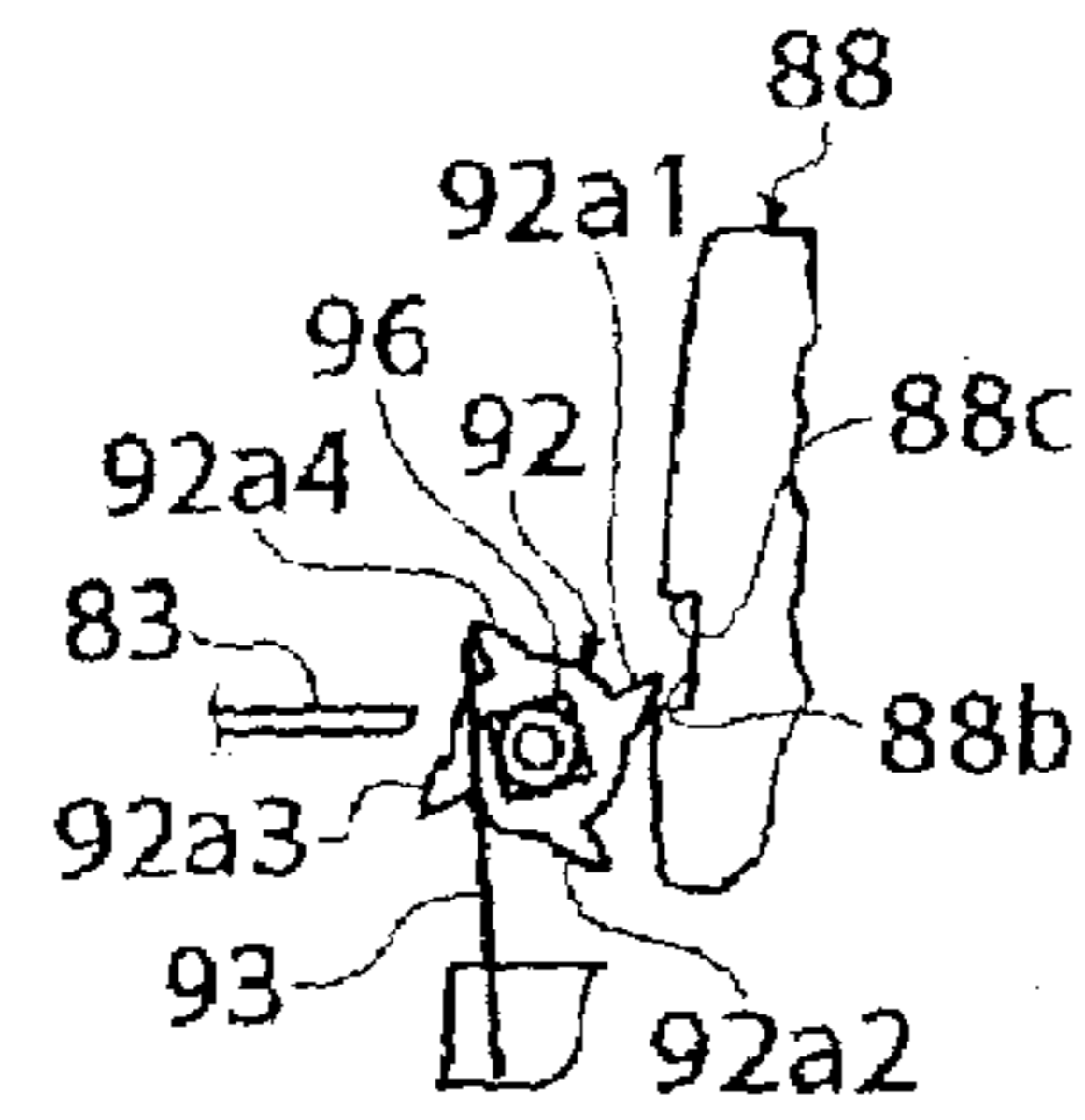


Fig. 53A

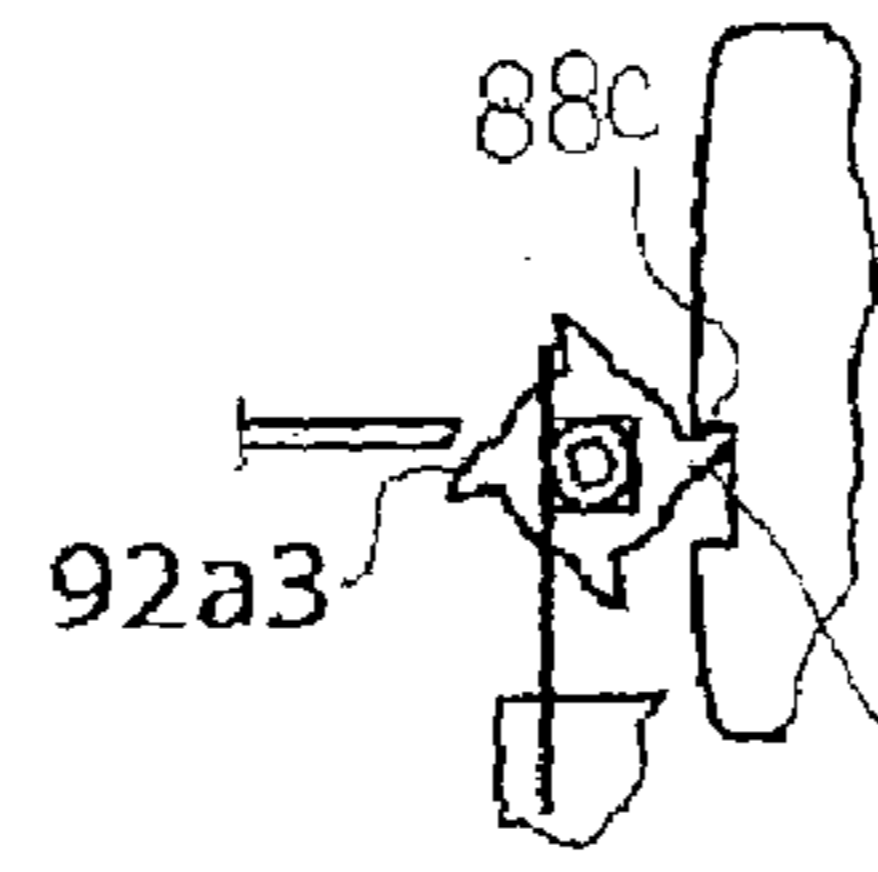


Fig. 53B

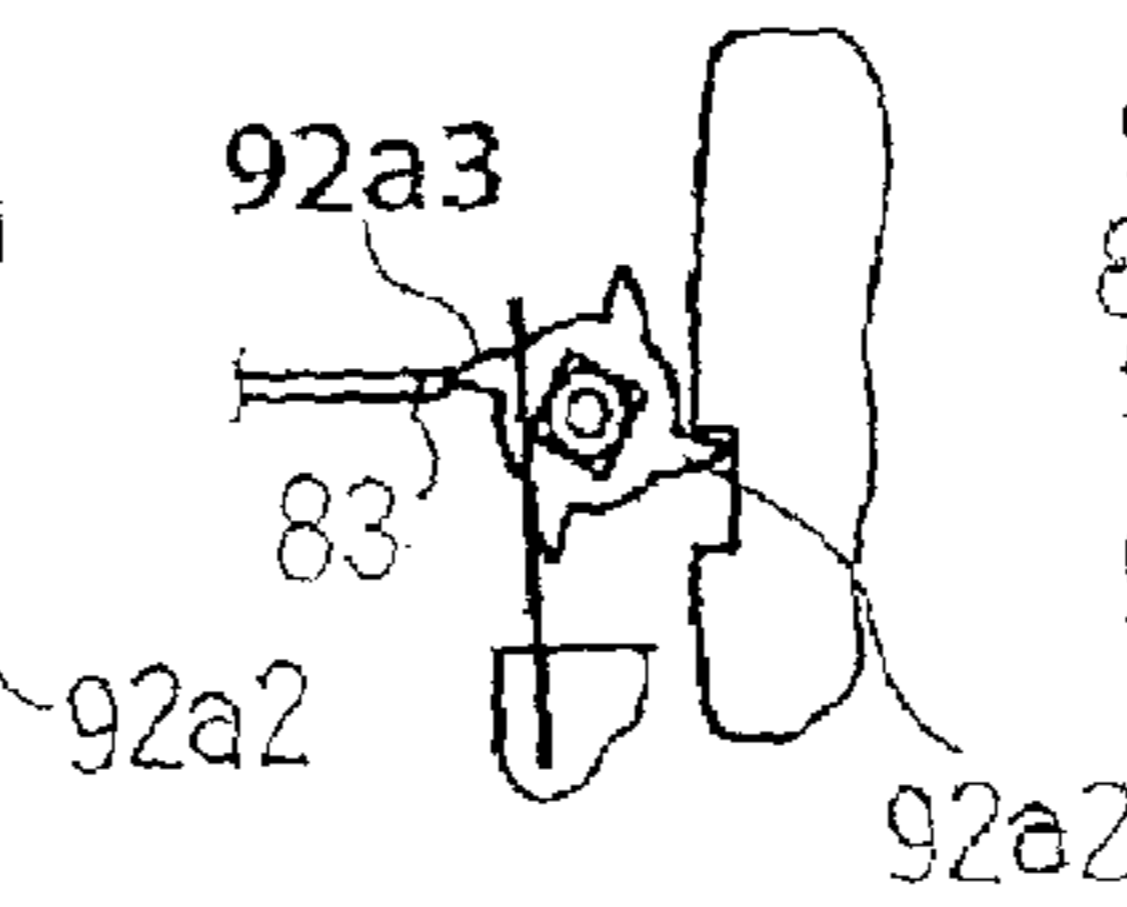


Fig. 53C

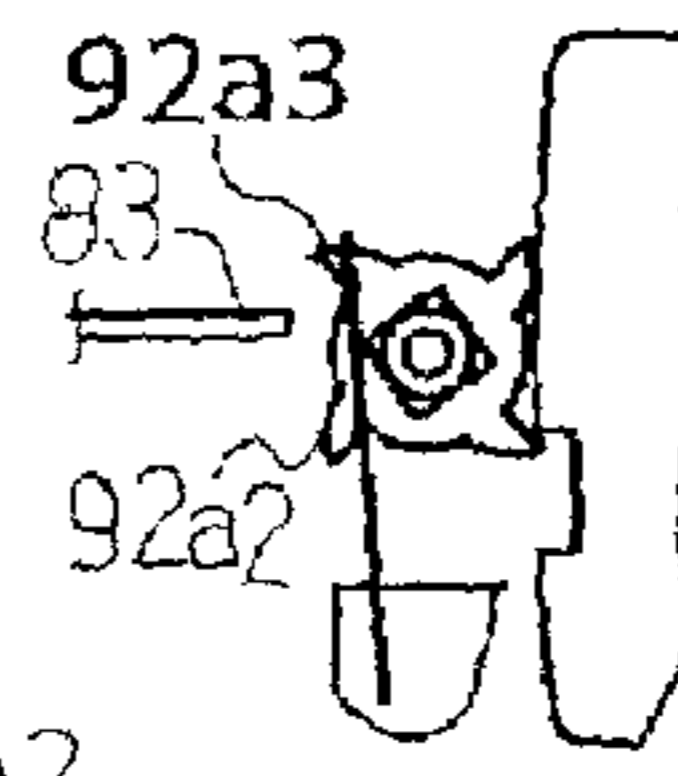


Fig. 53D

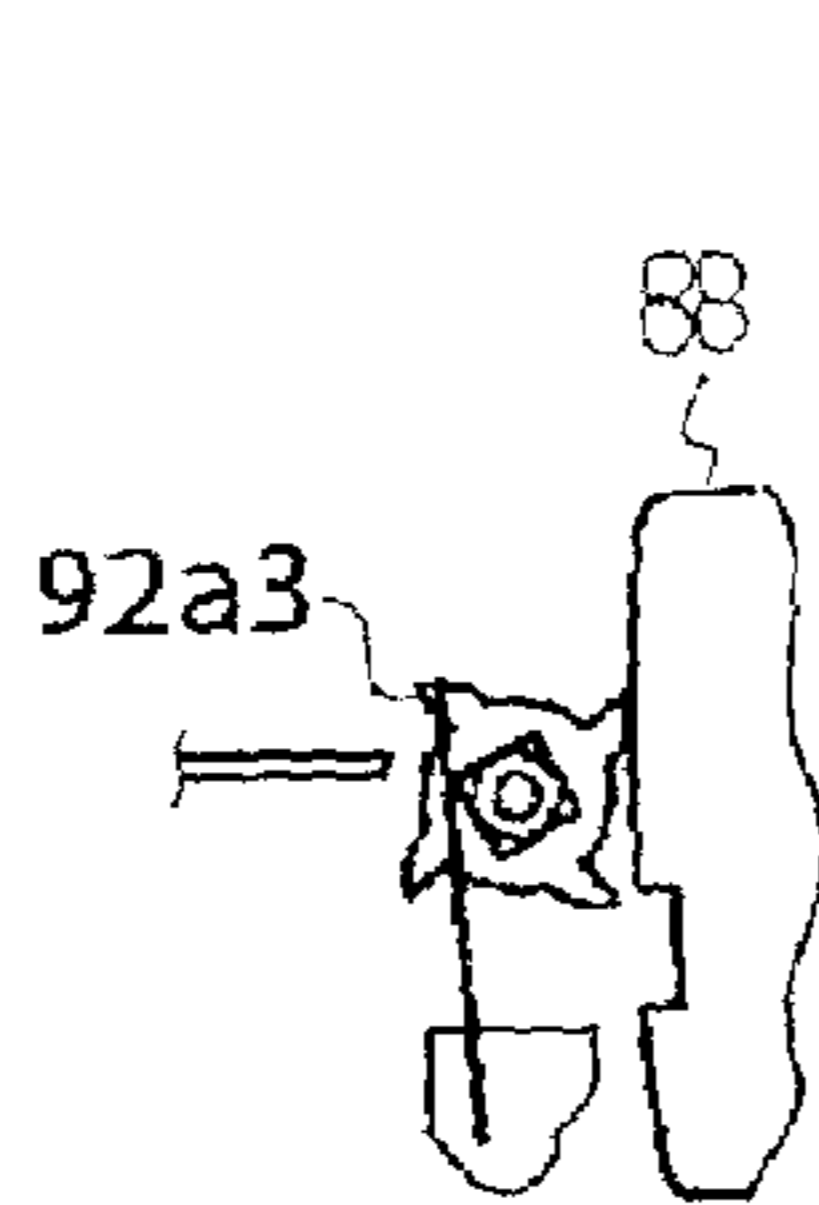


Fig. 53E

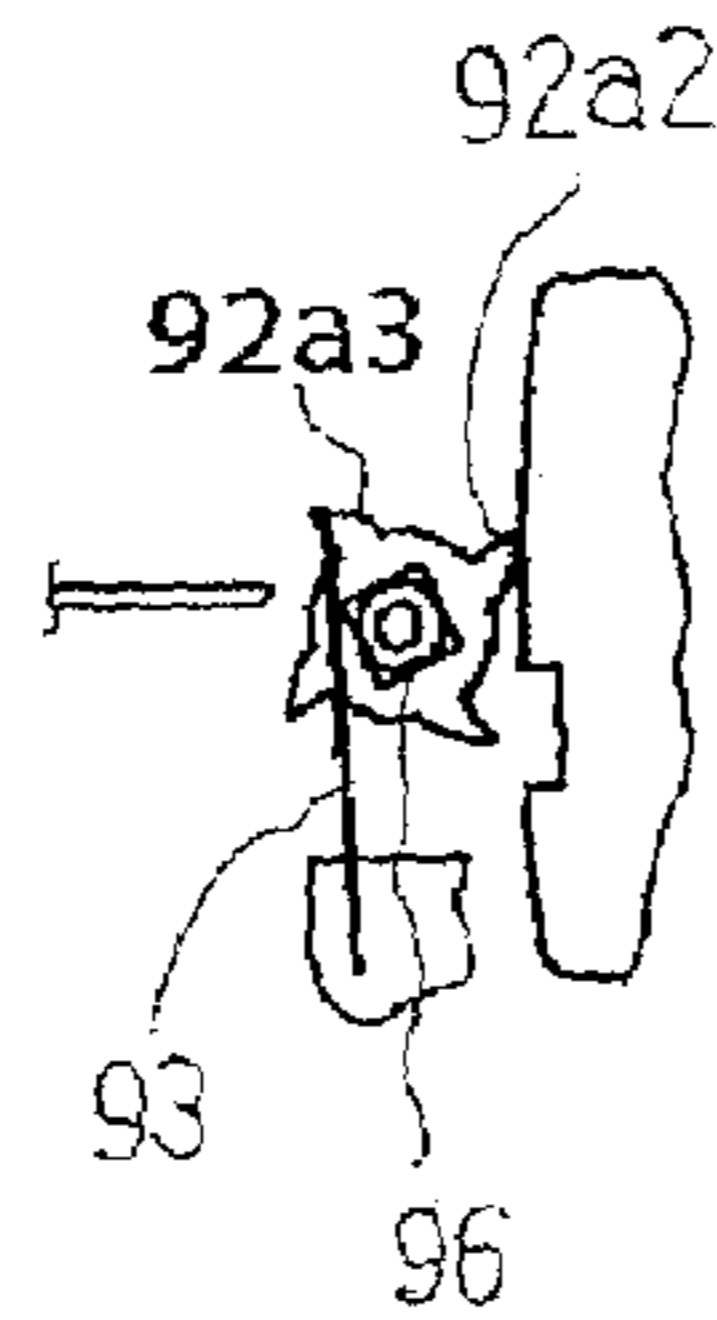


Fig. 53F

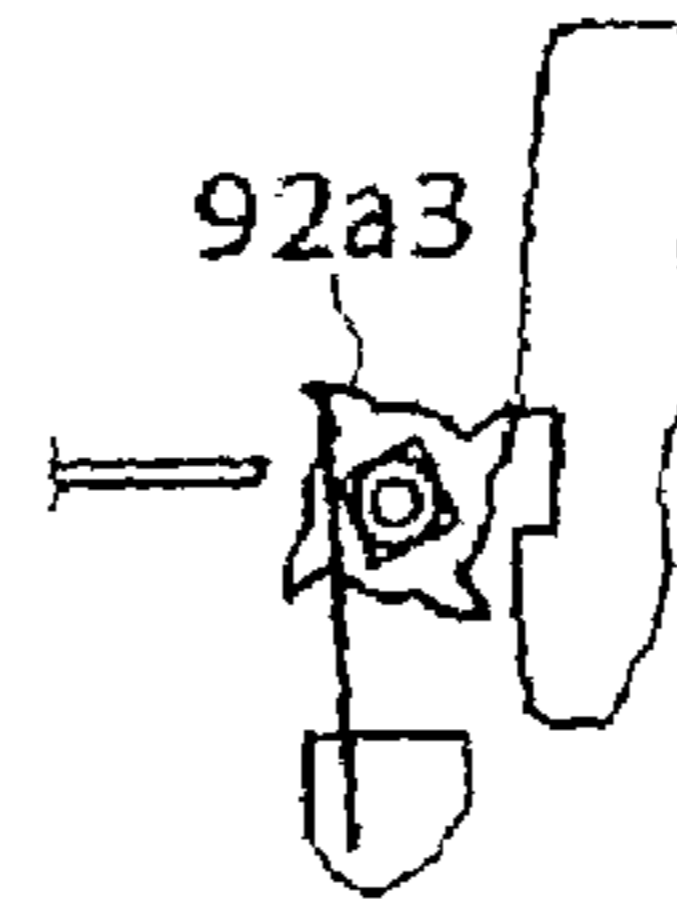


Fig. 53G

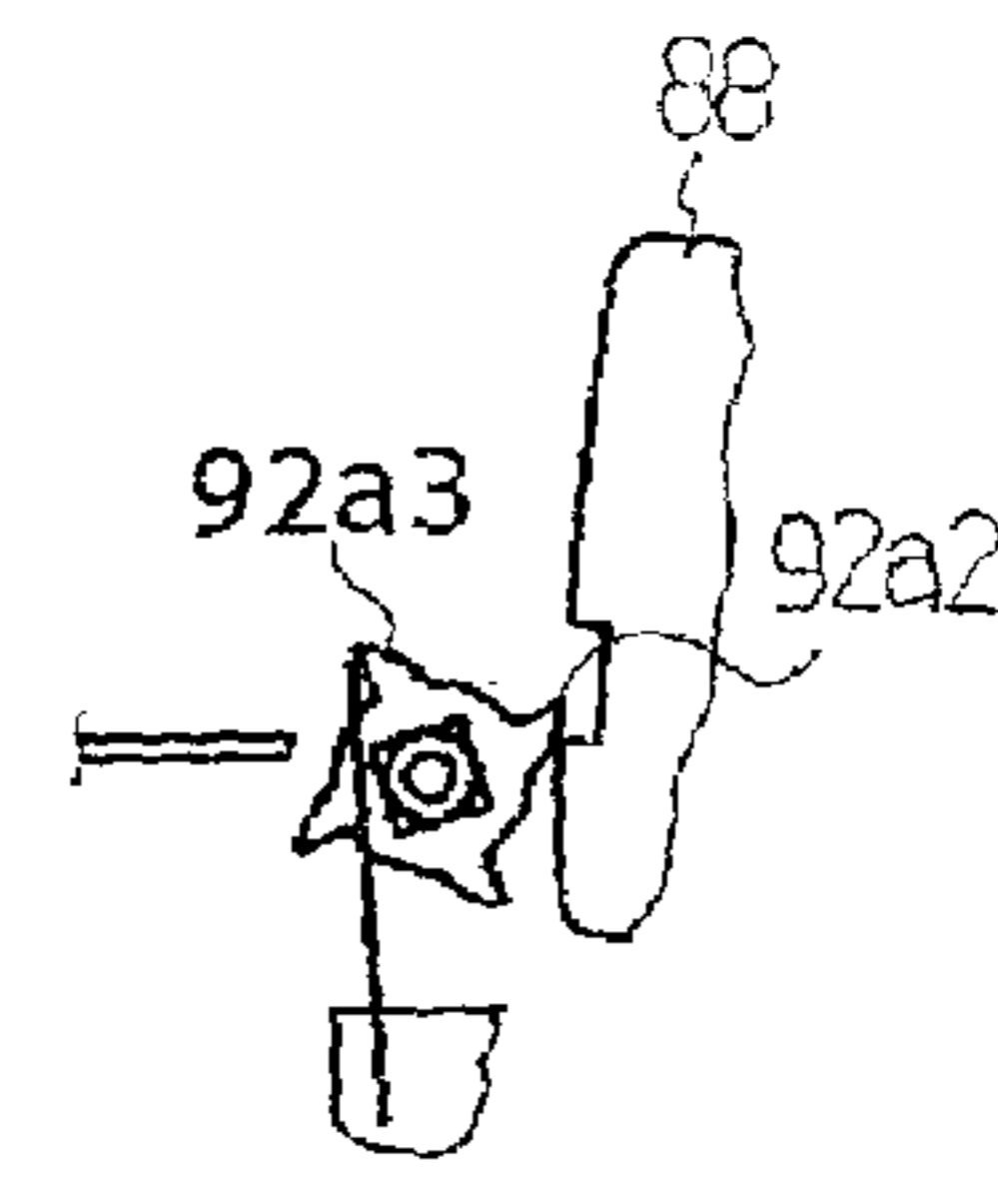


Fig. 53H

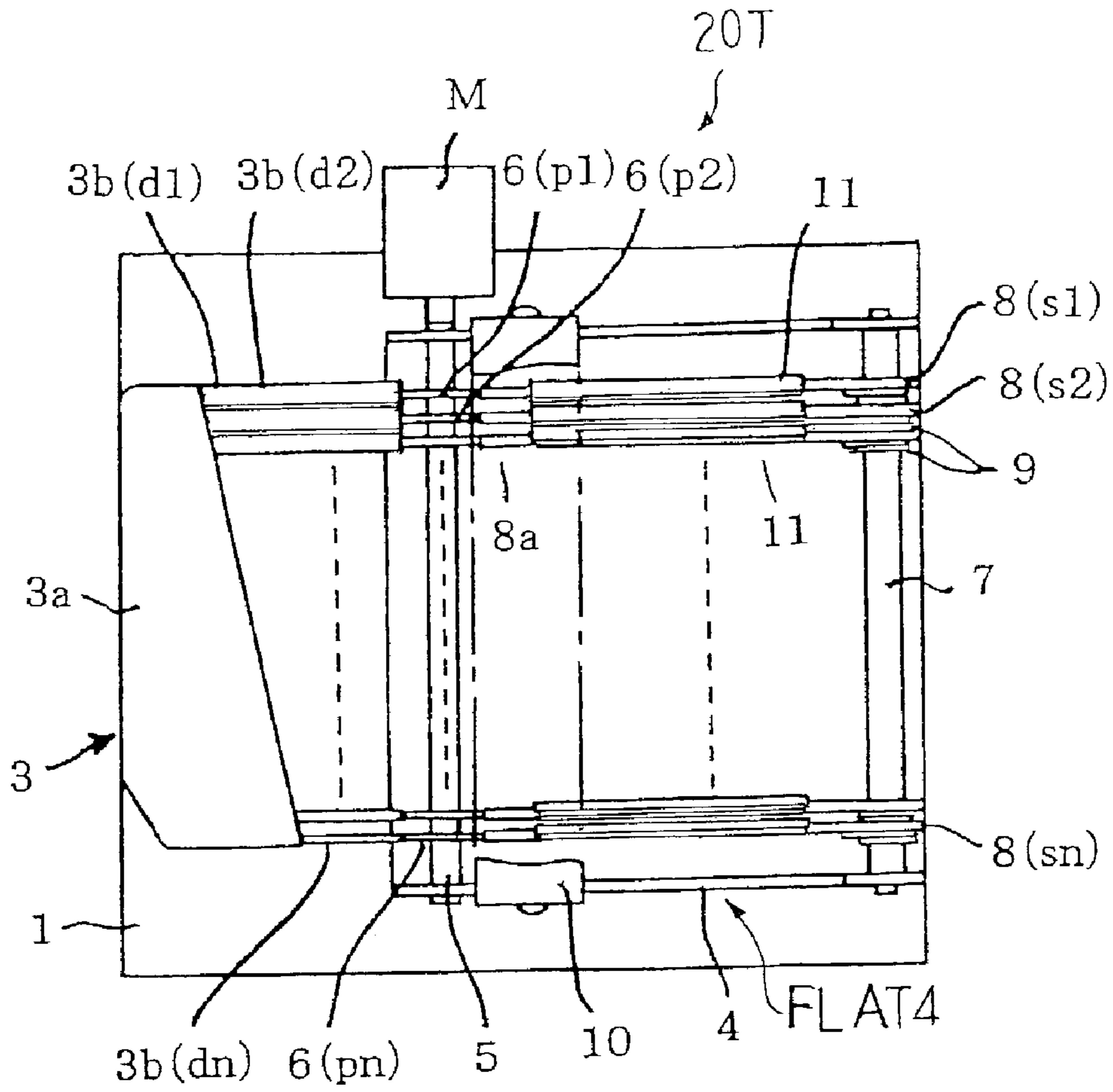


Fig. 54

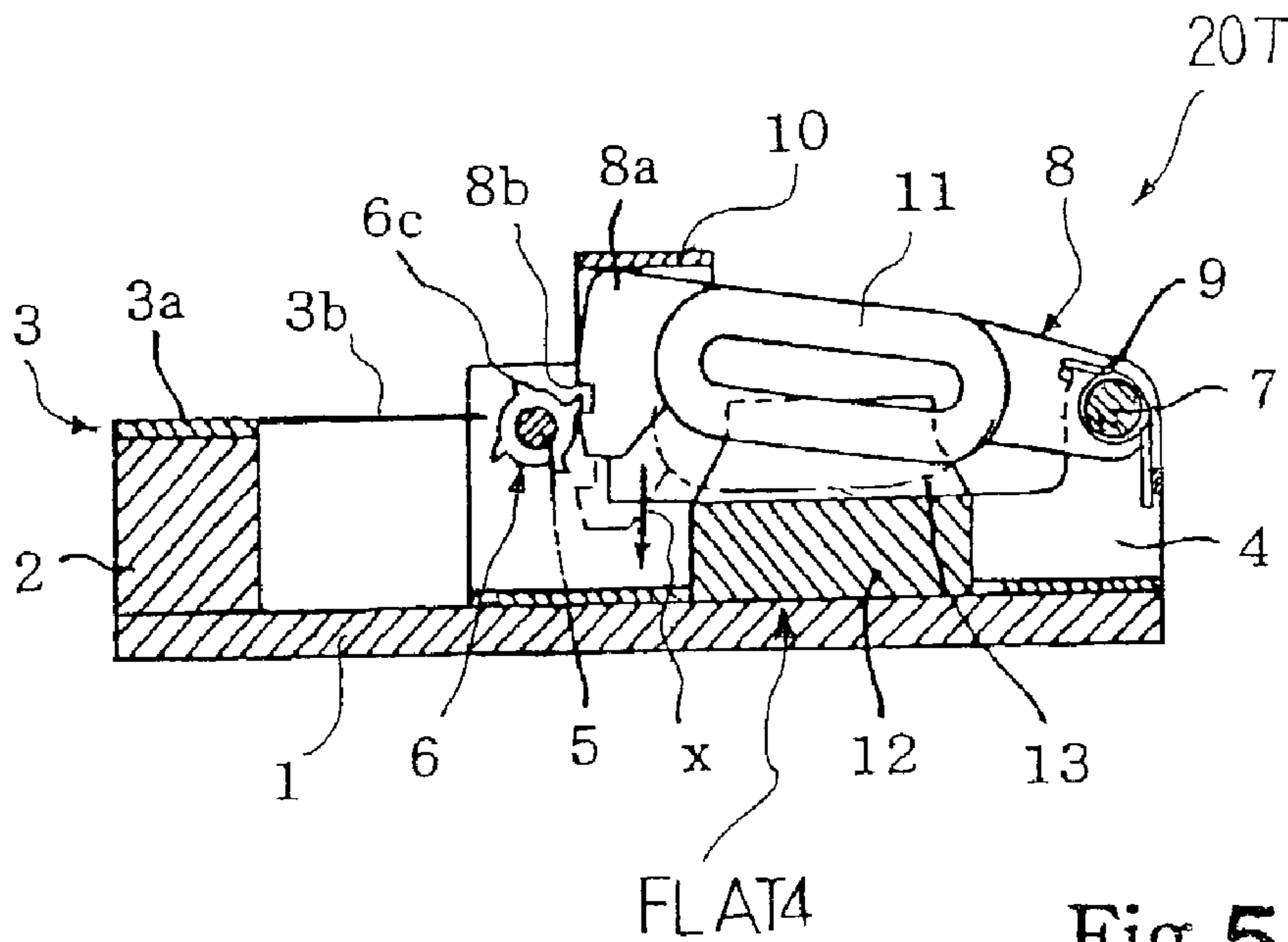
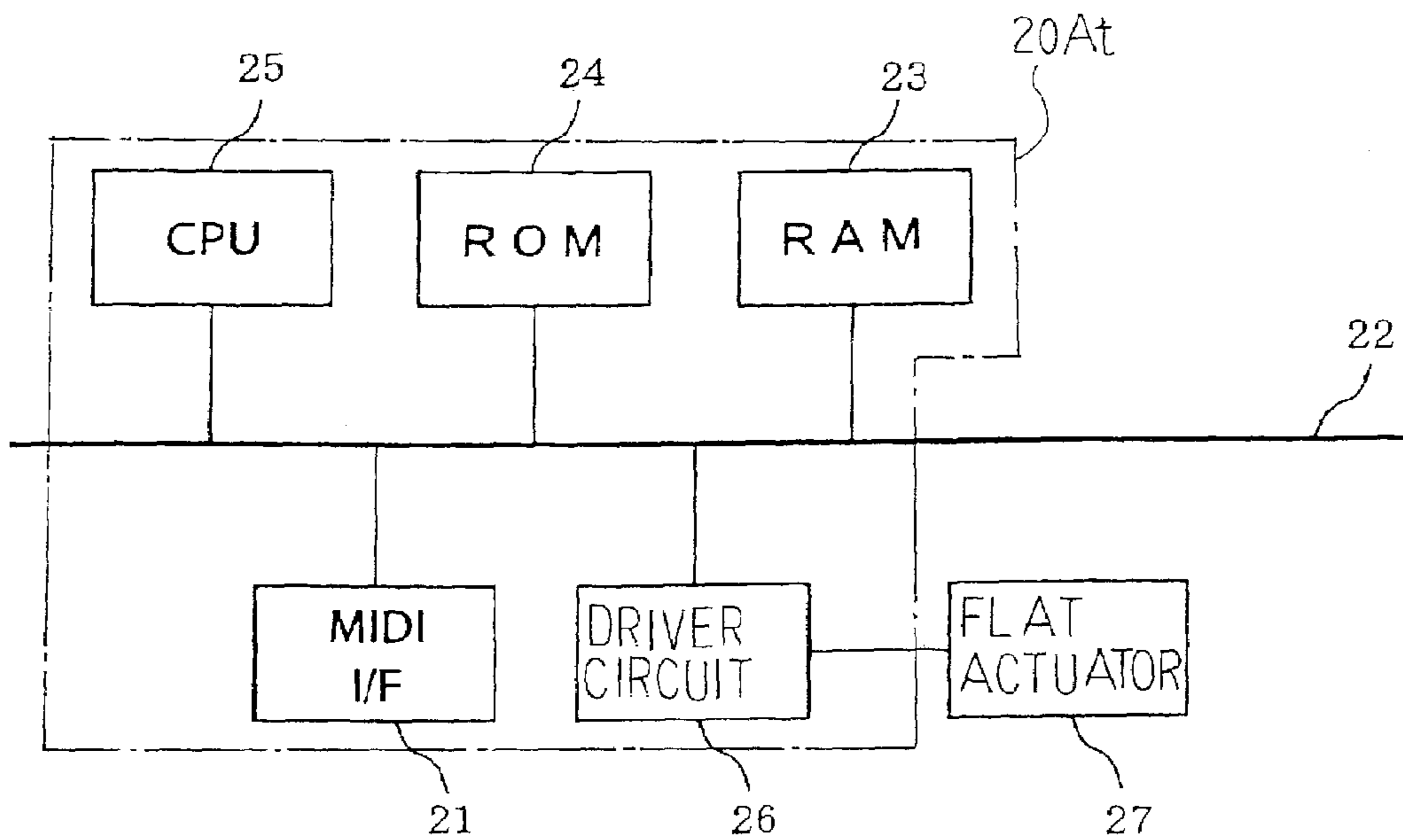
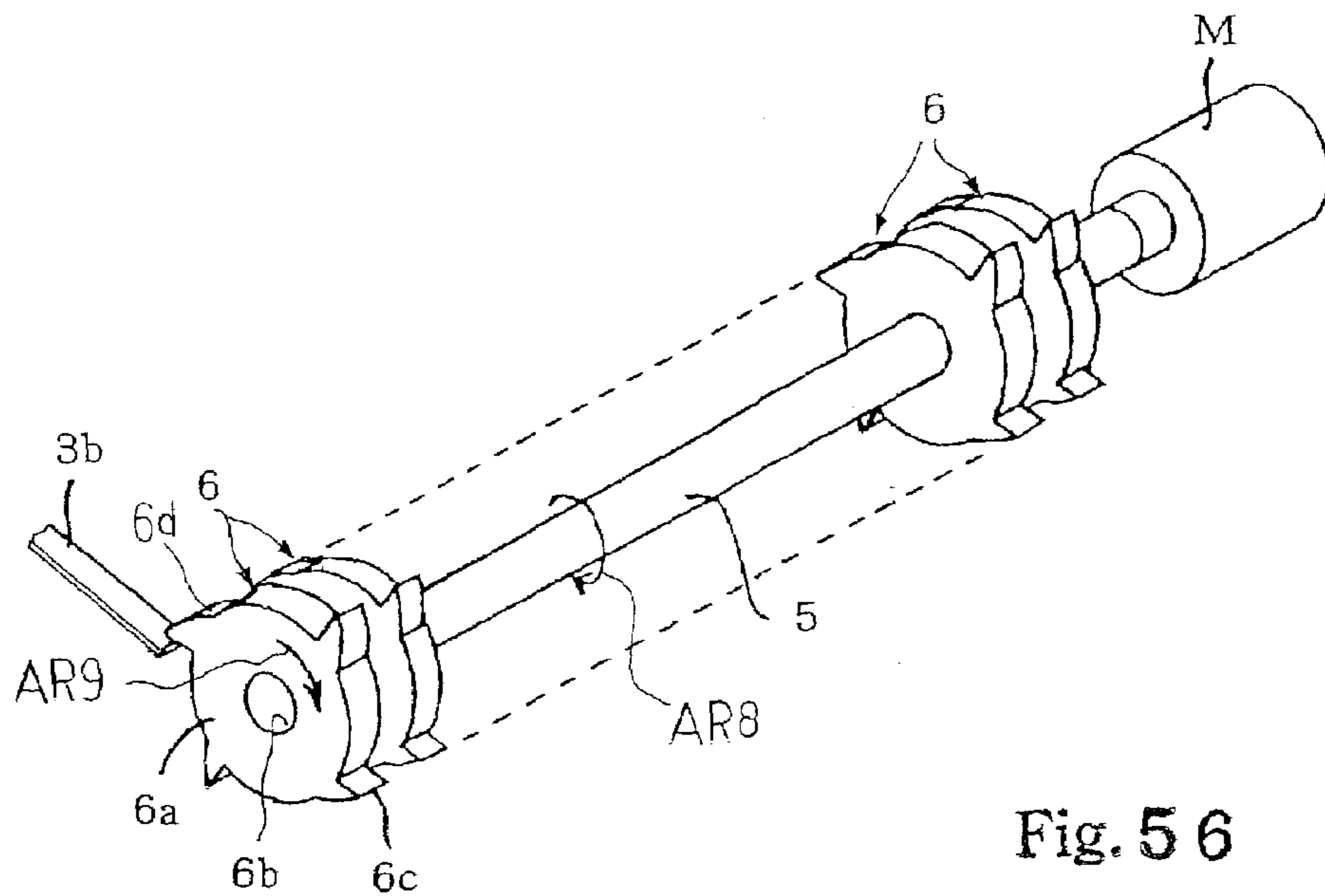


Fig. 55



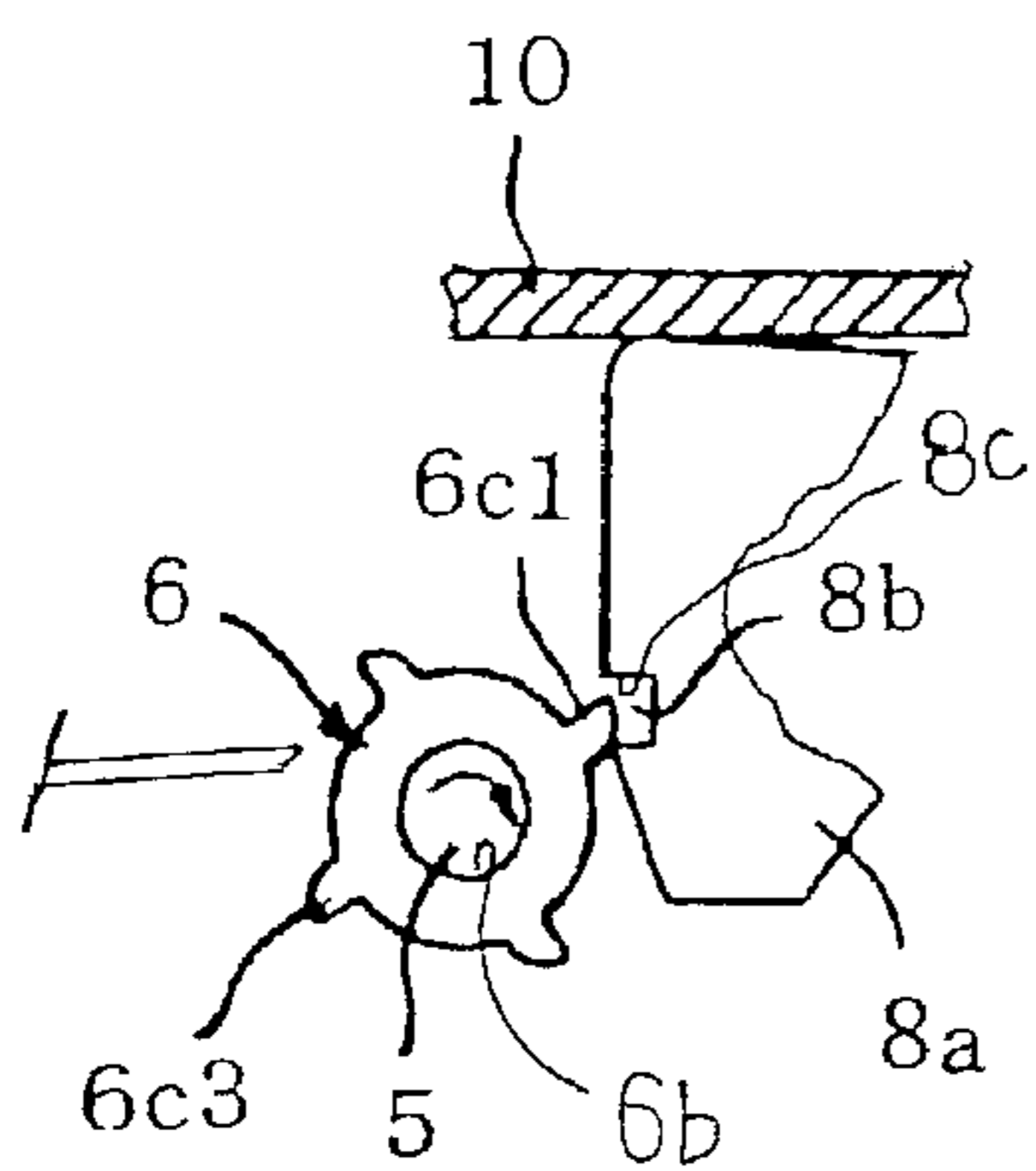


Fig. 58A

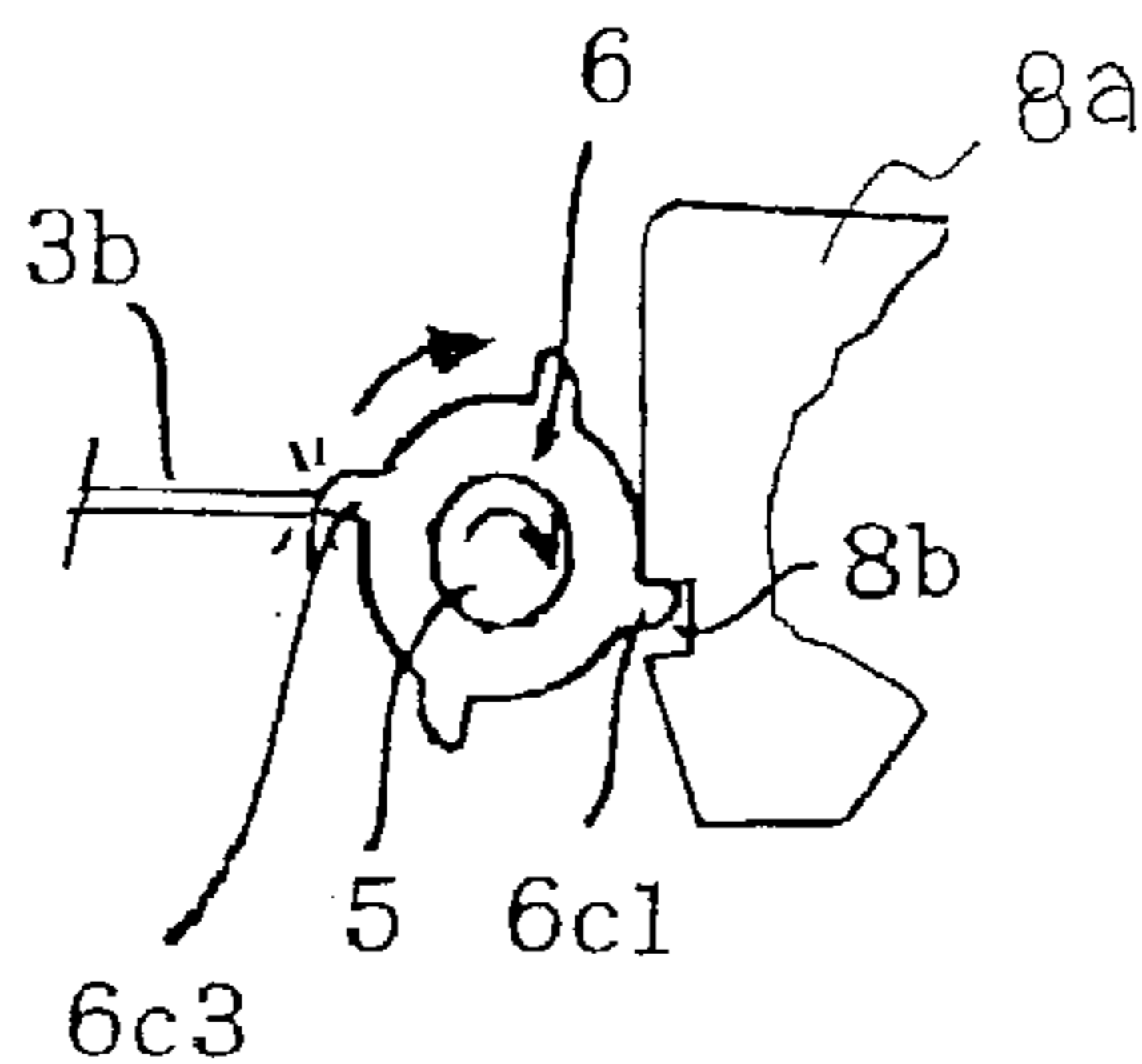


Fig. 58B

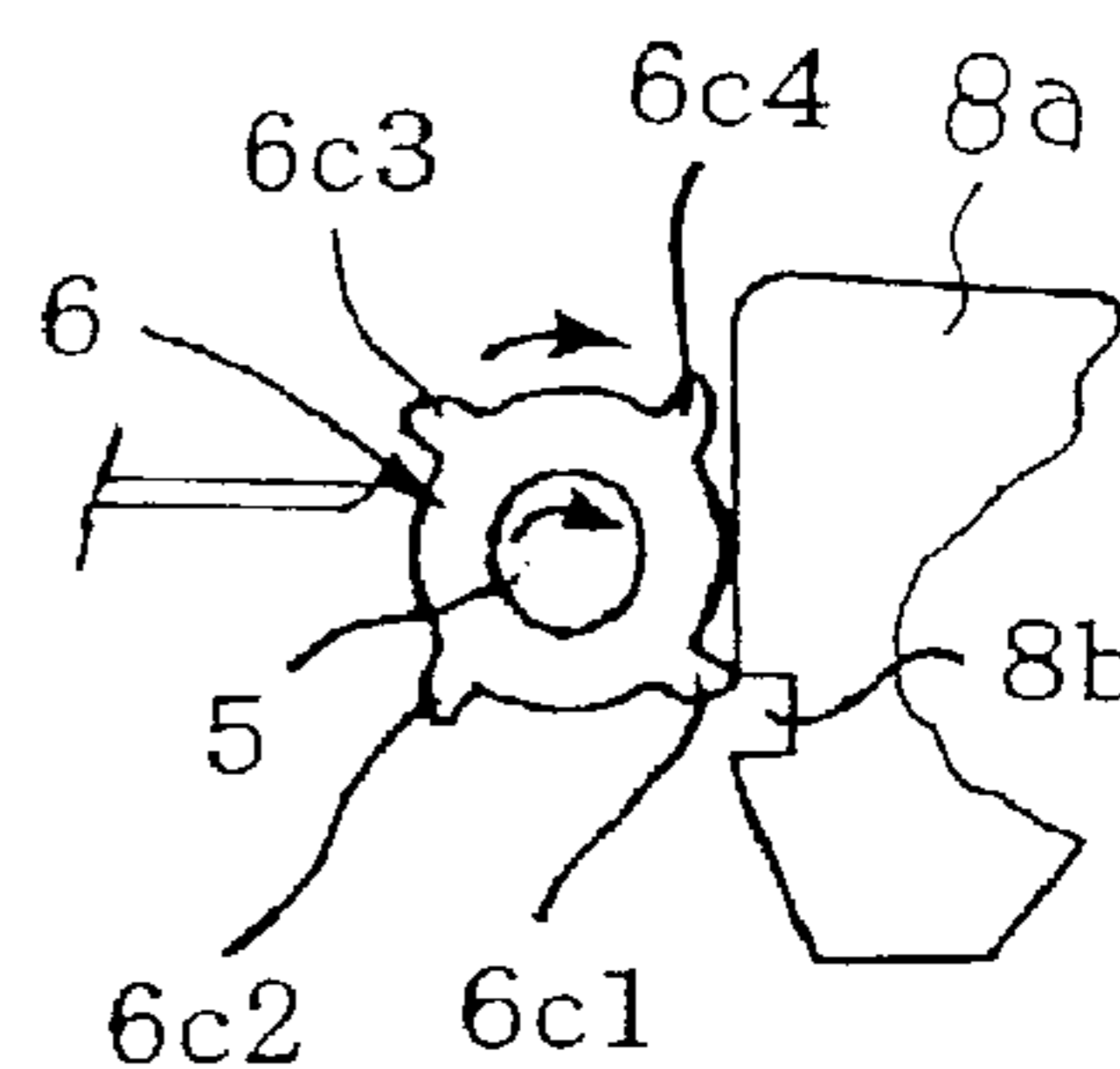


Fig. 58C

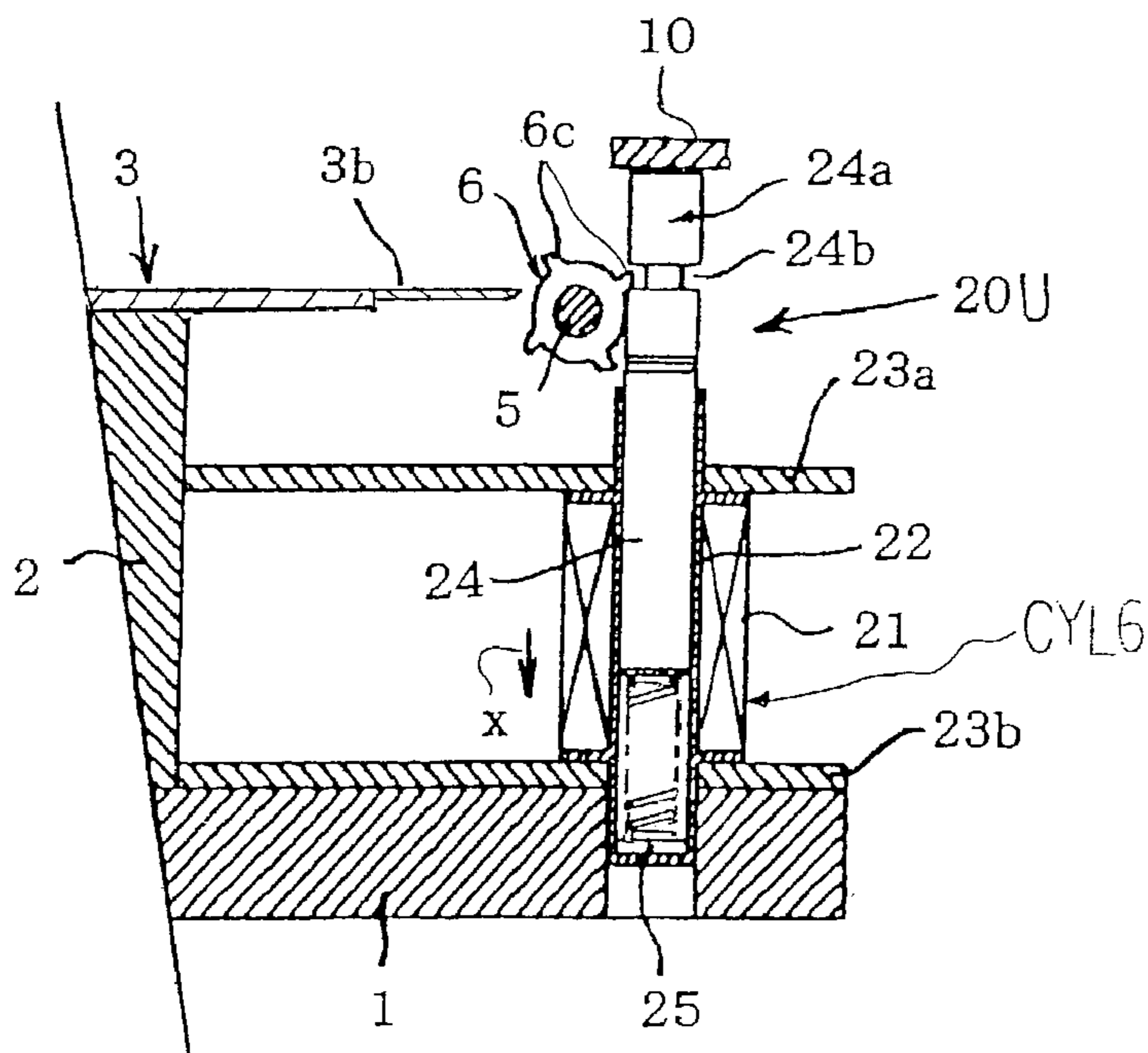


Fig. 59

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COMPACT MUSICAL INSTRUMENT EQUIPPED WITH AUTOMATIC PLAYER

FIELD OF THE INVENTION

This invention relates to a musical instrument and, more particularly, to a musical instrument equipped with an automatic player such as, for example, a music box.

DESCRIPTION OF THE RELATED ART

A music box is a typical example of the musical instrument with a built-in automatic player. A standard music box is broken down into a tone generator and an automatic player. The tone generator is implemented by an array of plural reeds, and the reeds vibrate for generating tones when the automatic player selectively plucks them. The tones are different in pitches from one another. The plural reeds may be formed into a comb-like reed unit. On the other hand, the automatic player is implemented by a rotational barrel drum. The rotational barrel drum is formed with small projections over the outer surface thereof, and the small projections are fixed to the outer surface. In other words, users can not relocate the small projections. The rotational barrel drum is provided in the close proximity of the array of reeds, and the barrel drum is driven for rotation over a certain angle equal to or less than 360 degrees. While the barrel drum is rotating, the small projections are selectively brought into contact with the reeds, and pluck the reeds. The reeds vibrate for generating the tones. Thus, the automatic player performs a piece of music through the vibrations of the reeds.

Each reed is doubled in another sort of tone generator, and the small projection concurrently plucks the double reed for generating a tone. The vibrating double reed makes the tone richer the tone generated from the single reed. The other features are similar to those of the standard music box. A barrel drum is formed with small projections, and is provided in the close proximity of the set of double reeds. While the barrel drum is rotating, the small projections selectively pluck the double reeds for performing a piece of music. However, the projections are fixed to the outer surface of the barrel drum. This means that the user can not relocate the small projections.

A problem inherent in the prior art standard music boxes is poor flexibility. The barrel drums are designed for particular pieces of music. Even if the user wishes to make the prior art standard music box perform another piece of music, the prior art standard music box can not respond to the user's request. Only one way to respond the user's request is to suggest the user to replace the barrel drum with a new barrel drum designed for the other piece of music.

The poor flexibility is because of the small projections fixed to the outer surface of the barrel drum. If the small projections are easily relocated, the standard music box can selectively play pieces of music without any replacement of the barrel drum. From this viewpoint, several music boxes have been proposed.

One of the music boxes selectively performing pieces of music on demand includes the tone generator, which is also implemented by an array of reeds, and an automatic player with a complex mechanism. The reeds are arranged in a row on a virtual straight line. The automatic player includes a turn-table, plural solenoid-operated actuators, hammers and a controlling circuit. The hammers are provided in association with the reeds for striking the associated reeds, and are rotatably supported by a frame like levers. Although the reeds are quite thin, the hammers are arranged along an arc,

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and the hammers strike the reeds at the inner ends thereof. This feature is desirable, because the large-sized hammers are arrayed. The large-sized hammers are durable.

The turn-table has an axis of rotation vertical to the array of reeds so that the rotating surface of the turn-table is maintained in parallel to the array of reeds. The solenoid-operated actuators are fixed to the turn-table, and the controlling circuit selectively supplies driving current to the solenoid-operated actuators. The solenoid-operated actuators retract the plungers into the associated solenoids in the absence of the driving current. Even though the turn table is rotated, the plungers do not kick the hammers, and, accordingly, the hammers never strike the reeds.

When the user requests the automatic player to perform a piece of music, the turn-table is driven for rotation, and the controlling circuit starts to selectively supply the driving current to the solenoid-operated actuators. The solenoid-operated actuators sequentially project the plungers in the presence of the driving current, and the plungers kick the associated hammers. Then, the hammers strike the associated reeds, and give rise to vibrations of the reeds. The reeds generate the tones for performing the piece of music.

The user is assumed to request the automatic player to perform another piece of music. The controlling circuit changes the sequence of the solenoid-operated actuators to be energized with the driving current. The controlling circuit starts to supply the driving current to the solenoid-operated actuators, and the hammers strike the reeds in the different order. This results in the other piece of music. This music box is hereinafter referred to as "first prior art music box".

Another music box selectively performing pieces of music on demand is also broken down into the tone generator, which is implemented by an array of reeds, and an automatic player. The reeds are arranged in a single row on a virtual straight line. The automatic player includes a rotational cylinder, pins, solenoid-operated actuators and a controlling circuit. The rotational cylinder has an axis of rotation, which is in parallel to the array of reeds. Through-holes are formed in the cylinder, and the pins are received in the through-holes. The pins are projectable from and retractable into the through-holes. The solenoid-operated actuators are accommodated in the cylinder, and push and pull the associated pins. The controlling circuit is electrically connected to the solenoid-operated actuators, and selectively supplies driving current to the solenoid-operated actuators. The reeds are respectively aligned with the orbits of the pins. While the solenoid-operated actuators are keeping the pins retracted into the through-holes, the reeds are spaced from the outer surface of the cylinder, and any reed is not plucked. When the controlling circuit energizes a solenoid-operated actuator, the solenoid-operated actuator makes the associated pin project from the through-hole, and the pin plucks the associated reed.

A user is assumed to request the automatic player to perform a piece of music, the controlling circuit searches the data storage for a set of pieces of music data, and sequentially supplies the driving current to the solenoid-operated actuators in accordance with the pieces of music data. The solenoid-operated actuators project pins and retract the pins so that the reeds are selectively plucked for generating the tones along the piece of music. If the user requests the automatic player to perform another piece of music, the controlling circuit changes the sequence of the solenoid-operated actuators to be energized, and the pins plucks the reeds in the different order. This music box is hereinafter referred to as "second prior art music box".

Yet another music box selectively performing pieces of music on demand is also broken down into a tone generator and an automatic player. The tone generator is also implemented by an array of reeds. The reeds are arranged in a single row on a virtual straight line. A plurality of driving units form in combination the automatic player together with a controller, and give rise to vibrations in the associated reeds, respectively. Each of the driving unit includes a solenoid-operated actuator, an arm and a variable rod. The arm is rotatably supported by a frame, and is engaged with the solenoid-operated actuator and variable rod at different portions. When the solenoid-operated actuator is energized, the arm is driven for rotation, and pushes down the variable rod. Then, the reed is warped. The variable rod laterally escapes from the reed, and the reed starts to vibrate for generating the tone. The variable rod returns to the initial position, and gets ready to push the reed, again. Thus, the variable rod does not interfere with the vibrations in the associated reed. The sequence of the solenoid-operated actuators to be energized is changeable so that the automatic player selectively performs pieces of music without change of the component parts. This music box is hereinafter referred to as "third prior art music box".

Still another music box selectively performing pieces of music on demand comprises a comb and an automatic player. The teeth of the comb are arranged in a single row on a virtual straight line, and are vibratory at different pitches. The automatic player includes star wheels respectively associated with the teeth, a solenoid-operated actuator, a conveyer and a controlling circuit. The solenoid-operated actuator is attached to the conveyer, and the conveyer moves the solenoid-operated actuator in a direction parallel to the row of the teeth. The star wheels are selectively driven for rotation by the solenoid-operated actuator, and pluck the associated teeth for generating the tones. When the user requests the automatic player to perform a piece of music, controlling circuit starts the conveyer quickly to move the solenoid-operated actuator. The controlling circuit sequentially stops the solenoid-operated actuator at the star wheels associated with the teeth to be plucked, and energizes the solenoid-operated actuator. The solenoid-operated actuator gives rise to the rotation of the selected star wheels so that the star wheels pluck the associated teeth for generating the tones. This music box is hereinafter referred to as "fourth prior art music box".

However, the flowing problems are encountered in those prior art music boxes. The first prior art music box is bulky. This is because of the fact that the automatic player requires a lot of rotatably supported hammers equal in number to the reeds for generating the tones. Moreover, it is difficult to concurrently drive more than one hammer for a chord.

The second prior art music box can merely perform several pieces of music. The through-holes formed in the cylinder and the rotating speed set the limit on the pieces of music to be performed. The controller can change the sequence of the pins to be driven from a combination of the through-holes to another combination of the through-hole. Another problem inherent in the second prior art music box is poor design flexibility. The relative position between the array of reeds and the rotational cylinder is hardly changed so that the designer merely modifies the other parts. Yet another problem inherent in the second prior art music box is poor durability. The solenoid-operated actuators and pins are complicatedly accommodated in the narrow inner space defined in the rotational cylinder. The complicated mechanism is liable to have troubles. The users can not cope with the mechanical troubles, and are discarded without repair.

The third prior art music box is also bulky, and the tones are not clear. These problems are derived from the action of the variable rods. When the automatic player generates a tone, the variable rod is pushed downwardly so as to warp the reed. When the variable rod escapes from the warped reed, the reed vibrates. In order to permit the variable rods, which are equal in number to the reeds, to escape from the reeds and return to the initial positions, hollow space is required in the vicinity of the reeds. The hollow space makes the third prior art music box bulky. The vibrations take place at the escape of the variable rod. In other words, the reeds start the vibrations from the warped state. This is unnatural, and the tones are less clear.

The fourth prior art music box is also bulky. The conveyer is required for moving the solenoid-operated actuator along the array of teeth, and a suitable mechanism is further required for making the star wheels to the initial positions. These components occupy wide space, and makes the fourth prior art music box bulky.

SUMMARY OF THE INVENTION

It is therefore an important object of the present invention to provide a compact musical instrument, which is equipped with an automatic player for selectively performing pieces of music.

It is also an important object of the present invention to provide a musical instrument, which is equipped with an automatic player with a simple structure for performing a piece of music.

It is another important object of the present invention to provide a musical instrument, which is equipped with an automatic player for generating clear tones.

In accordance with one aspect of the present invention, there is provided a musical instrument comprising a tone generator having vibratory members radially arranged with respect to a center of the tone generator, and an automatic player selectively generating vibrations of said vibratory members for producing tones different in pitch from one another through the vibrations and including player's fingers arranged in the proximity of outer ends of the vibratory members and a controller connected to the player's fingers for selectively actuating the player's fingers on the basis of pieces of music data variable without changing a physical structure of the controller.

In accordance with another aspect of the present invention, there is provided a musical instrument comprising a tone generator having an array of vibratory members for generating tones different in pitch from one another through vibrations and an automatic player including player's fingers for selectively generating the vibrations in the vibratory members and a controller connected to the player's fingers for selectively actuating the player's fingers on the basis of pieces of music data variable without changing a physical structure of the controller, and each of the player's fingers has a rotary vibration generator rotatably supported by a stationary member in the proximity of associated one of the vibratory members for generating the vibrations through rotation thereof and an actuator connected to the controller and selectively energized by the controller for rotating the rotary vibration generator.

In accordance with yet another aspect of the present invention, there is provided a musical instrument comprising a tone generator having an array of vibratory members for generating tones different in pitch from one another through vibrations and an automatic player including player's fingers for selectively generating the vibrations in the vibratory

members and a controller connected to the player's fingers for selectively actuating the player's fingers on the basis of pieces of music data variable without changing a physical structure of the controller, and each of the player's fingers includes a vibration generator moved from a rest position along a first path for generating the vibrations in associated one of the vibratory members and a second path for returning to the rest position, an actuator connected to the controller and moving the vibration generator along the first path and the second path and a route changer connected to the vibration generator for guiding the vibration generator to the second path after generating the vibrations so as to permit the associated vibratory member to freely vibrate without any interference due to the vibration generator passing beside the associated vibratory member along the second path.

BRIEF DESCRIPTION OF THE DRAWINGS

The features and advantages of the musical instrument with the automatic player will be more clearly understood from the following description taken in conjunction with the accompanying drawings, in which

FIG. 1A is a schematic plane view showing the layout of a tone generator and an automatic player incorporated in a music box according to the present invention,

FIG. 1B is a cross sectional view taken along line A—A of FIG. 1A and showing the structure of the music box,

FIG. 2A is a plane view showing a reed and a player's finger of an automatic player incorporated in the music box,

FIG. 2B is a cross sectional view taken along line B—B and showing the structure of the player's finger,

FIG. 3 is a block diagram showing the system configuration of a controller,

FIGS. 4A to 4C are schematic views showing the player's finger plucking the associated reed,

FIG. 5 is a cross sectional view showing the player's finger after the plucking,

FIGS. 6A to 6D are perspective views showing the external appearance of the music box and modifications thereof,

FIGS. 7A and 7B are cross sectional views showing other modifications of the music box implementing the first embodiment,

FIG. 8A is a perspective view showing the structure of a tone generating unit incorporated in another modification of the music box,

FIG. 8B is a schematic view showing the arrangement of the tone generating units,

FIG. 9A is a plane view showing strings and automatic player incorporated in another modification of the music box,

FIG. 9B is a cross sectional view taken along line C—C of FIG. 9A and showing the structure of the modification,

FIG. 10A is a schematic plane view showing the layout of a tone generator and an automatic player incorporated in a musical instrument according to the present invention,

FIG. 10B is a cross sectional view taken along line A1—A1 of FIG. 10A and showing the structure of the music box,

FIG. 11A is a plane view showing a reed and a player's finger of an automatic player incorporated in the music box,

FIG. 11B is a cross sectional view taken along line B1—B1 of FIG. 11A and showing the structure of the player's finger,

FIG. 12 is a block diagram showing the system configuration of a controller incorporated in the automatic player,

FIG. 13 is a cross sectional view showing the player's finger after the plucking,

FIG. 14 is a cross sectional view showing a player's finger incorporated in a modification of the musical instrument,

FIG. 15A is a perspective view showing a player's finger incorporated in another modification of the musical instrument,

FIG. 15B is a perspective view showing a pick incorporated in the player's finger,

FIG. 15C is a perspective view showing paths formed in a guide block also incorporated in the player's finger,

FIG. 15D is a cross sectional view in a direction of F5 of FIG. 15C and showing the paths.

FIG. 15E is a schematic cross sectional view showing a pick attached to a solenoid-operated actuator incorporated in the player's finger,

FIG. 15F is a front view showing the pick attached to the solenoid-operated actuator,

FIG. 16 shows a block diagram showing the system configuration of a controller incorporated in another musical instrument according to the present invention,

FIG. 17 is a perspective view showing player's fingers incorporated in the musical instrument,

FIG. 18A is a side view showing the player's finger before plucking the associated reed,

FIG. 18B is a rear view showing the player's finger,

FIG. 19 is a side view showing the player's finger after the plucking,

FIG. 20A is a side view showing another player's finger incorporated in a musical instrument according to the present invention,

FIG. 20B is a rear view showing the player's finger,

FIG. 21 is a plane view showing the layout of reeds and player's fingers incorporated in a musical instrument according to the present invention,

FIG. 22A is a cross sectional view taken along line C—C of FIG. 21 and showing the structure of the musical instrument,

FIG. 22B is a plane view showing a standard solenoid-operated actuator,

FIG. 22C is a view a rotary pick and a brake unit viewed in a direction indicated by F1,

FIGS. 23A to 23H are schematic views illustrating a plucking motion of the rotary pick,

FIG. 24 is a plane view showing the layout of a musical instrument according to the present invention,

FIG. 25A is a cross sectional view showing the structure of the musical instrument,

FIG. 25B is a front view showing swingable arms and solenoid-operated flat actuators,

FIG. 25C is a schematic side view showing the swingable arm and an associated rotary pick,

FIG. 26A is a plane view showing another musical instrument according to the present invention,

FIG. 26B is a cross sectional view showing the structure of a player's finger incorporated in the musical instrument,

FIG. 27A is a plane view showing the layout of another musical instrument according to the present invention,

FIG. 27B is a rear view showing the structure of the musical instrument on the left side,

FIG. 28 is a perspective view showing a player's finger incorporated in the musical instrument,

FIG. 29A is a side view showing the player's finger,

FIG. 29B is a side view showing the parts encircled in EX1 of FIG. 29A,

FIGS. 30A and 30B are side views showing a modification of the player's finger shown in FIG. 28,

FIG. 30C is a side view showing another modification of the player's finger,

FIG. 31 is a block diagram showing the system configuration of a controller incorporated in another musical instrument according to the present invention,

FIG. 32 is a perspective view showing the structure of a player's finger incorporated in the musical instrument,

FIG. 33A is a side view showing the player's finger before plucking,

FIG. 33B is a rear view showing the player's finger,

FIG. 34 is a side view showing the player's finger after the plucking,

FIG. 35A is a side view showing another player's finger incorporated in a musical instrument according to the present invention,

FIG. 35B is a rear view showing the player's finger,

FIG. 36 is a plane view showing the layout of reeds and player's fingers incorporated in another musical instrument according to the present invention,

FIG. 37A is a cross sectional view taken along line C—C of FIG. 36 and showing the structure of the musical instrument,

FIG. 37B is a plane view showing a standard solenoid-operated actuator,

FIG. 37C is a view a rotary pick and a brake unit viewed in a direction indicated by F1 in FIG. 37B,

FIGS. 38A to 38H are schematic views illustrating a plucking motion of the rotary pick,

FIG. 39 is a plane view showing the layout of another musical instrument according to the present invention,

FIG. 40A is a cross sectional view showing the structure of the musical instrument,

FIG. 40B is a front view showing swingable arms and solenoid-operated flat actuators,

FIG. 40C is a schematic side view showing the swingable arm and an associated rotary pick,

FIG. 41A is a plane view showing a musical instrument according to the present invention,

FIG. 41B is a cross sectional view showing the structure of player's fingers incorporated in the musical instrument according to the present invention,

FIG. 42A is a rear view showing the structure of another musical instrument on the left side,

FIG. 42B is a plane view showing the layout of the musical instrument according to the present invention,

FIG. 43 is a perspective view showing a player's finger incorporated in the musical instrument,

FIG. 44A is a side view showing the player's finger,

FIG. 44B is a side view showing the parts encircled in EX1 of FIG. 44A,

FIGS. 45A and 45B are side views showing a modification of the player's finger shown in FIG. 43,

FIG. 45C is a side view showing another modification of the player's finger,

FIG. 46 is a block diagram showing the system configuration of a controller incorporated in another musical instrument according to the present invention,

FIG. 47 is a perspective view showing the structure of a player's finger incorporated in the musical instrument,

FIG. 48A is a side view showing the player's finger before plucking,

FIG. 48B is a rear view showing the player's finger,

FIG. 49 is a side view showing the player's finger after the plucking,

FIG. 50A is a side view showing another player's finger incorporated in a musical instrument according to the present invention,

FIG. 50B is a rear view showing the player's finger,

FIG. 51 is a plane view showing the layout of another musical instrument according to the present invention,

FIG. 52A is a cross sectional view showing the structure of the musical instrument,

FIG. 52B is a front view showing swingable arms and solenoid-operated flat actuators,

FIG. 52C is a view a rotary pick and a brake unit viewed in a direction indicated by F1 in FIG. 52B,

FIGS. 53A to 53H are schematic views illustrating a plucking motion of the rotary pick,

FIG. 54 is a plane view showing the layout of another musical instrument according to the present invention,

FIG. 55 is a cross sectional view showing the structure of the musical instrument,

FIG. 56 is a perspective view showing an array of rotary picks,

FIG. 57 is a block diagram showing the system configuration of a controller,

FIGS. 58A to 58C are schematic views showing the rotary pick plucking an associated reed, and

FIG. 59 is a cross sectional view showing a modification of the musical instrument.

DESCRIPTION OF THE PREFERRED EMBODIMENTS

First Embodiment

Prototype

Referring to FIGS. 1A and 1B of the drawings, a music box embodying the present invention largely comprises a housing 1, a tone generator 3 and an automatic player 5. A hollow space is defined in the housing 1, and the tone generator 3 and automatic player 5 are placed inside the housing 1. The tone generator 3 occupies a central zone of the hollow space, and the automatic player 5 is disposed in the peripheral zone of the hollow space, i.e., around the tone generator 3. The automatic player 5 drives the tone generator without changing its position so that any additional space is not required for the automatic player. This results in the compact music box.

In the following description, a direction from the central zone toward the peripheral zone is "outward direction", and a direction from the peripheral zone to the central zone is "inward direction".

A bottom disk 10 and a cap 16 form in combination the housing 1. The cap 16 defines a recess, and the depth of the recess is greater than the thickness of the bottom disk 10. For this reason, when the cap 16 and bottom disk 10 are assembled into the housing 1, the inner space takes place in the housing 1, and the tone generator 3 and the automatic player 5 are accommodated therein.

The tone generator 3 includes a pedestal 31 and a daisy reed wheel 32. The pedestal 31 has a column shape, and is upright on the central area of the upper surface of the bottom disk 10. The daisy reed wheel 32 has a boss portion 33a and reeds 33b. The boss portion 33a is fixed to the upper surface of the pedestal 31, and is horizontally maintained. The reeds 33b radially project from the periphery of the boss portion 33a, and reach the boundary between the central zone and the peripheral zone. In this instance, twenty-four reeds 33b project from the boss portion 33a at regular intervals. Although the reeds 33b are different in length and width from one another, the tips 33c of the reeds 33b reaches a virtual circle concentric with the boss portion 33a. This

means that the boss portion **33a** has the radius increased together with the angle. For this reason, the periphery of the boss portion **33a** is like an involute line. The reeds **33b** are vibratory at predetermined values of the frequency so that the vibrating reeds **33b** generate the tones of a scale, respectively.

The daisy reed wheel **32** is desirably for the automatic player **5**, because the tips **33c** are widely spaced from one another along the boundary between the central zone and the peripheral zone. The automatic player **5** includes player's fingers **20**, which are provided around the daisy reed wheel **32** at regular intervals. The player's fingers **20** are respectively associated with the reeds **33b**, and are selectively energized for plucking the reeds **33b**. In this instance, twenty-four player's fingers **20** are disposed on the bottom disk **10**. Since the tips **33c** are widely spaced, a wide local space is assigned to each of the player's fingers **20**. When the player's fingers **20** pluck the associated reeds **33b**, the reeds **33b** vibrate for generating the tones. Thus, the automatic player **5** performs a piece of music or a passage of the piece of music.

Turning to FIGS. 2A, 2B and 3, the automatic player **5** includes the player's fingers **20** and a controller **20A**. The player's fingers **20** are similar in structure to one another, and one of the player's fingers **20** is hereinafter described in detail with reference to FIGS. 2A and 2B. The controller **20A** is connected to the player's fingers **20** in parallel, and selectively supplies driving current to the player's fingers **20**.

The player's finger **20** is broken down into a solenoid-operated actuator **21**, a pick **22** and a spring **25**. The solenoid-operated actuator **21** is supported by a bottom yoke **25a**, which in turn is supported by the bottom disk **10**, and the pick **22** is mounted on the solenoid-operated actuator **21**. The spring **25** is connected between the pick **22** and the bottom yoke **25a**, and urges the pick **22** outwardly.

A coil **21a**, a bobbin **23**, a cushion sheet **23**, a top yoke **25b**, an additional yoke **25c** and a plunger **26** form in combination the solenoid-operated actuator **21**. The bobbin **23** has a cylindrical configuration, and the cushion sheet **23a** is provided at the bottom of the inner space of the bobbin **23**. The coil **21** is wound on the outer surface of the bobbin **23**, and the plunger **26** is slidably received in the inner space of the bobbin **23**. The bottom yoke **25** has an inner portion slightly projecting, and forms an offset yoke structure. When current flows through the coil **21a**, the current creates a magnetic field across the bobbin **23**. The bobbin **23** and bottom yoke **25a** offer a magnetic path to the electric field. The bottom yoke **25a** has the inner portion projecting from the outer portion so that the magnetic field is asymmetrically developed. For this reason, the picks **22** are urged inwardly as indicated by arrow AR1, and the plunger **26** upwardly projects from the bobbin **23**. The inwardly inclined pick **22** is brought into contact with the tip **33c** of the associated reed **33b**. If the magnetic field is removed, then the plunger **26** is retracted into the bobbin **23**, and is landed on the cushion sheet **23a**. The cushion sheet **23a** prevents the plunger **26** from dropping out.

The plunger **26** is formed with a pair of wall portions **27**. The wall portions **27** are upright on the upper surface of the plunger **26**, and are spaced from each other in parallel to the associated reed **33b**. A pin **24** is fixed at both ends thereof to the wall portions **27** in such a manner as to be perpendicular to the longitudinal direction of the associated reed **33b**, and the pick **22** is rotatably connected at the lower portion **22a** thereof to the pin **24**. The pick **22** is a thin narrow plate of soft magnetic material, and is rotatable about the pin **24**. The

extension line of the centerline of the associated reed **33b** is on the trajectory of the pick **22**. The pick **22** has an upper end portion **22b**, which is wider than the lower end portion **22a** so that a step **22c** is formed at the boundary between the upper end portion **22b** and the lower end portion **22a**. The upper end portion **22b** has a rounded end surface. On the other hand, the tip **33c** of the reed **33b** is tapered. While the plunger **26** is projecting from the bobbin **23**, the rounded end surface is brought into contact with the tapered tip **33c**, and makes the reed **33b** warped.

The spring **25** is connected at one end thereof to the upper portion of the pick **22** and at the other end thereof to the upper surface of the bottom yoke **25a**. While the plunger **26** is resting in the bobbin **23**, the spring **25** is almost in its free length, and a negligible amount of elastic force is exerted on the pick **22**. The spring **25** increases the elastic force together with the distance between the pick **22** and the bottom yoke **25a**, and urges the pick **22** outwardly. As described hereinbefore, when the current starts to flow through the coil **21a**, the magnetic force makes the pick **22** inwardly inclined. The magnetic force is larger than the elastic force of the spring **25** in the initial stage where the pick **22** warps the reed **33b**. When the step **22c** exceeds the upper end of the bottom yoke **25a**, the space between the pick **22** and the coil **21a** is so wide that the magnetic force is equalized to the elastic force. The plunger **26** further projects upwardly, and the step **22c** is spaced from the upper end **25d**. Then, the elastic force becomes larger than the magnetic force, and the pick **22** escapes from the reed **33b**. Then, the reed **33b** vibrates for generating the tone. While the plunger **26** is being retracted into the bobbin **23**, the spring **25** keeps the pick **22** inclined outwardly. Thus, the spring **25** prevents the pick **22** from chattering.

The player's finger **20** behaves for plucking the associated reed **33b** as follows. The controller **20A** is assumed to have already removed the magnetic field from the player's finger **20**. The pick **22** is outwardly inclined with respect to the centerline **26a** of the plunger **26**, and the rounded upper end portion **22b** is spaced from the tapered tip **33c** as shown in FIG. 4A.

When the current flows through the coil **21a**, the pick **22** is inwardly inclined, and the plunger **26** starts to upwardly project against the elastic force of the string **25**. The plunger **26** is brought into contact with the tapered tip **33c**, and pushes the reed **33b** upwardly. Although the expanded spring **25** increases the elastic force exerted on the pick **22**, the magnetic force is still larger than the elastic force so that the pick **22** makes the reed **33b** warped as shown in FIG. 4B.

The plunger **26** further projects from the bobbin **23**, and the pick **22** becomes far from the coil **21a**. When the magnetic force becomes smaller than the elastic force, the spring **25** pulls the pick **22** outwardly, and the pick **22** escapes from the reed **33b**. Then, the reed **33b** starts the vibrations, and generates the tone. The other player's fingers **20** behave along the above-described sequence so as to pluck the associated reeds **33b**.

Turning to FIG. 3 of the drawings, the controller **20A** includes a central processing unit **11**, which is abbreviated as "CPU", read only memories **12/18**, which are abbreviated as "ROM"s, a random access memory **12**, which is abbreviated as "RAM", an MIDI (Musical Instrument Digital Interface) interface **14** and a driver circuit **17**. These system components **11, 12, 13, 14, 17** and **18** are connected to a bus system **15** so that the central processing unit **11** is communicable with the other system components through the bus system **15**. The driver circuit **17** is connected to the player's fingers

20 through a suitable cable, and selectively supplies the driving current to the player's fingers **20**.

Computer programs and data codes to be required for the execution of the computer programs are stored in the read only memory **12**, and the central processing system sequentially executes the instruction codes for achieving given tasks. The random access memory **13** serves as a working memory and a data storage for music data codes representative of pieces of music. The central processing unit **11** is further communicable with external musical instruments and a computer system through the MIDI interface **14**. A set of MIDI music data code representative of a piece of music may be supplied from an external data source to the MIDI interface **14**, and the central processing unit **11** stores the set of MIDI music data codes into the random access memory **13** for a performance on the daisy reed wheel **32**.

The read only memory **18** offers a data storage facility for parameters, and the central processing unit **11** accesses the parameters during the execution of the given computer program.

Assuming now that a user instructs the automatic player **5** to perform a piece of music represented by a set of MIDI music data codes on the daisy reed wheel **32**. The set of MIDI music data codes has been already stored in the random access memory **13**. As well known to skilled person, event codes and duration codes form essential parts of the set of MIDI music data codes. The tones to be generated and the loudness of the tones are represented by the event codes, and each duration data code is indicative of a time interval between the event or events, i.e., note-on event/note-off event and the next event.

The central processing unit **11** executes a computer program so as to determine the reeds **33b** to be driven for vibrations, the timing to supply a driving signal to the associated player's fingers **20** and the magnitude of the driving signal as follows. While the central processing unit **11** sequentially fetches the MIDI music data codes from the random access memory **13**, an event code just fetched by the central processing unit **11** is assumed to represent the note-on event for generating a tone. The central processing unit **11** specifies one of the reeds **33b**. The central processing unit **11** accesses the parameters and data codes stored in the read only memories **12/18**, and determines the magnitude of the driving signal for generating the tone at the given loudness.

When the time at which the tone is to be generated comes, the central processing unit **11** supplies data codes representative of the position assigned to the player's finger to be energized and the magnitude of the driving signal to be supplied to the driver circuit **17**. Then, the driver circuit **17** sets the driving signal to the magnitude, and supplies the driving signal to the solenoid-operated actuator **21** incorporated in the player's finger **20**. The solenoid-operated actuator **21** maintains the pick **22** at the rest position **P3**. When the driving signal reaches the coil **21a**, the current creates the magnetic field across the bobbin **23**. The magnetic force is exerted on the pick **22** as well as the plunger **26**. The pick **22** is inclined toward the tip **33c** of the associated reed **33b** against the elastic force of the spring **25**, and the plunger **26** upwardly projects. The pick **22** upwardly pushes the tip **33c** of the reed **33b** so that the reed **33b** is warped.

Though not shown in FIG. 3, the driver circuit **17** includes a pulse width modulator. The pulse width modulator incorporated in the driver circuit **17** controls the loudness of the tones to be produced through the vibrations of the reeds **33b**. The central processing unit **11** is assumed to instruct the driver circuit **17** to supply the driving signal for generating

a loud tone. The pulse width modulator increases the pulse width of the driving signal, and supplies it to the solenoid-operated actuator associated with the reed **33b** to be plucked. When the driving signal reaches the coil **21a**, a large amount of current flows, and creates a strong magnetic field. The pick **22** is strongly attracted to the inner portion of the additional yoke **25d**, and the plunger upwardly projects from the bobbin **23** powerfully. The magnetic force is so large that the spring can not outwardly incline the pick **22** as usual. Thus, the driving signal with the wide pulse width results in the strong attractive force exerted on the pick **22** as well as the speed-up of the plunger **26**. For this reason, the pick **22** makes the reed **33b** widely warped. However, the elastic force exceeds the magnetic force later than usual. Then, the pick **22** escapes from the tapered tip **33c**, and permits the reed **33b** to vibrate. The escape is later than the usual escape is. This means that the reed **33b** is widely warped, and the amplitude of the vibrations is wider than the amplitude of the usual vibrations. This results in the loud tone.

When the elastic force exceeds the magnetic force, the spring **25** pulls the pick **22** outwardly, and the pick **22** escapes from the reed **33b**. The pick **22** plucks the reed **33b** so that the reed **33b** naturally vibrates. The clear tone is generated through the naturally vibrating reed **33b**. Upon escape, the pick **22** is changed to position **P1**.

The driving circuit **17** removes the driving signal from the solenoid-operated actuator **21**. Then, the plunger **26** is retracted due to the self-weight and the elastic force of the spring **25**, and the spring **25** outwardly inclines the pick **22** as indicated by **P2**. The cushion sheet **23a** receives the plunger **26**. While the plunger **26** is sinking together with the pick **22**, the pick **22** never interferes with the vibrating reed **33b**, because the spring **25** keeps the pick **22** outwardly inclined. In order to prevent the vibrating reed **33b** from interference, the spring **25** slightly inclines the pick **22** so that the additional space to be required is negligible. Thus, the music box implementing the first embodiment is made compact by virtue of the radial arrangement of the reeds **33b** and the picks **22** outwardly inclined.

As will be understood from the foregoing description, the daisy reed wheel **32** occupies the central zone of the inner space defined in the housing **1**, and the reeds **33b** radially extend from the boss portion **33a**. This feature is desirable, because the automatic player **5** occupies the wide peripheral zone around the tips **33c** of the reeds **33b**. Thus, the tone generator **3** and automatic player **5** do not waste the inner space. This results in the compact music box.

Moreover, the tips **33c** are widely spaced so that the wide local spaces are assigned to the player's fingers **20**. The player's fingers **20** require the actuators **21** for plucking the reeds **33b**. The designer can install large-sized actuators in the wide local spaces so that the player's fingers **20** perform a piece of music at a high tempo. The designer can further install the strong picks **22** on the large-sized plungers **26**. Thus, the music box is durable.

Yet another advantage is resulted from the pick's action. The picks **22** upwardly push the tips **33c** of the associated reeds **33b**, and, thereafter, escape from the tips **33c** outwardly. The picks **22** pluck the associated reeds **33b** as if a human player plucks strings or reeds with his or her fingers. Thus, the picks **20** naturally give rise to vibrations of the reeds **33b**. This results in clear tones.

Still another advantage is also resulted from the pick's action after the plucking. The springs **25** elastically pull the picks **22**, and the picks **22** are outwardly inclined. The outwardly inclined picks **22** return to the initial positions without interference with the vibrating reeds **33b**. Only a

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small amount of space is required for the outwardly inclined picks 22. Thus, the pick's action is conducive to the compactness of the music box.

The solenoid-operated actuators 21 are independently controlled by the controller 20A. This means that the controller 20A can concurrently energize more than one solenoid-operated actuator 21. Thus, the automatic player 5 can play a piece of music along the melody accompanied with chords.

The controller 20A sequentially energizes the solenoid-operated actuators 21 on the basis of the music data, and the user arbitrarily changes the music data. Thus, the music box is responsive to any user's request for performing tunes.

Several Models of Music Box

Various modifications of the music box implementing the first embodiment are hereinafter described in detail. FIG. 6A shows the external appearance of the music box described hereinbefore. The first modification has a casing 1A, and light-emitting diodes 46 are provided along the periphery of the upper surface of the casing as shown in FIG. 6B. The light-emitting diodes 46 are respectively associated with the reeds 33b, and are connected in parallel to the controller 20A. The controller 20A energizes the light-emitting diodes 46 concurrently with the solenoid-operated actuators 21 for the reeds 33b to be plucked. Thus, the tones are harmonized with the light.

The second modification has a casing 1B, on which a megaphone 47 is provided as shown in FIG. 6C. The megaphone 47 makes the tones loud. The third modification has a casing 1C provided with the light-emitting diodes like the casing 1A of the first modification. A semi-transparent cupola 48 is attached to the casing 1C as shown in FIG. 6D. The semi-transparent cupola 48 disperses the light, and gives fantastic impression. An illumination system may be provided inside of the semi-transparent cupola 48 independently of the solenoid-operated actuators 21.

Multiple Music Box

The tone generator and automatic player may be multiplexed. FIG. 7A shows an example of the multiple music box according to the present invention. The multiple music box comprises plural performing units 41, a cylindrical post 42 and a resonator box 43. Each of the performing units 41 includes the daisy reed wheel 3 and the automatic player 5, which are similar to those of the music box described hereinbefore. A tone hole 43a is formed in the upper plate of the resonator box 43, and the resonator 43b is connected through the tone hole 43a to the column-shaped space 42a defined in the cylindrical post 42. Plural trays 42b project from the outer surface of the cylindrical post 42, and the performing units 41 are respectively mounted on the trays 42b.

Different registers are respectively assigned to the performing units 41 so that the multiple music box produces a piece of music in plural parts. The automatic players 5 of the plural performing units 41 are connected to the controller 20A, and the driver circuit 17 selectively supplies the driving signal to the solenoid-operated actuators 21. When the solenoid-operated actuators 21 are energized, the player's fingers 20 pluck the associated reeds with the picks 22. The tones and vibrations are propagated through the cylindrical post 42 to the resonator 43b so that the loud tones are radiated from the resonator box 43.

FIG. 7B shows another example of the multiple music box. The multiple music box comprises plural performing units 141, the resonator box 43 and a combined structure of cylindrical post and bell 44/45. The combined structure of

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cylindrical post and bell 44/45 is upright on the resonator box 43, and brims 44a are formed together with the trays 42b. Each of the performing units 141 has the daisy reed wheel 32 and the automatic player 5. The daisy reed wheels 32 are detachably connected to the brims 44a, and the resonator 43b is connected through the bell 45 to the air. The multiple music box produces loud tones, and the daisy reed wheels 32 are easily replaced with another daisy reed wheels.

Unitized Structure

A reed and a player's finger may form a tone generating unit. In this instance, plural tone generating units may be arranged on a virtual circle. FIG. 8A shows an example of the tone generating unit 100. The tone generating unit 100 largely comprises a holder 110, a player's finger 120 and a reed 133. The player's finger 120 is similar in structure to the player's finger 20 so that no further description is hereinafter incorporated for the sake of simplicity.

The holder 110 is a generally rectangular parallelepiped configuration. A pair of flanges 111 is formed in one end portion, and a through-hole is formed in the other end portion. Bolt holes 11a are formed in the pair of flanges 111, and the player's finger 120 is received in the through-hole. The plunger is projectable and retractable in a direction indicated by arrow AR2. The one end portion is thicker than the other end portion so that a step 110a takes place at the boundary therebetween. The reed 133 is fixed to the one end portion by means of bolts. The boss portion 132 of the reed 133 is held in contact with the one end portion. However, the remaining portion of the reed is overhung like a cantilever. The tip 133a of the reed 133 is over the pick without physical contact as shown. When the solenoid-operated actuator is energized with the driving signal, the pick is inclined toward the tip 133a, and the plunger upwardly projects from the bobbin. The pick upwardly pushes the reed 133, and warps it. The pick escapes from the tip 133a, and permits the reed 133 to vibrate. The magnetic field is removed from the solenoid-operated actuator, and the plunger is retracted into the bobbin together with the pick. Thus, the player's finger behaves as similar to the player's finger 20.

The tone generating unit or units 100 are attached to any sort of frame. FIG. 8B shows the tone generating units 100 fixed to a disk 100a. The tone generating units 100 are arranged on a virtual circle 100b, and are fixed to the disk 100a by means of the screws. In this instance, the tone generating units 100 occupy an inner space between the disk 100a and an outer space assigned to the automatic player. Although the through-holes of the holders 110 are directed in the tangential directions of the virtual circle 100b on the disk 100a, the through-holes may be arbitrarily directed on another disk 100a.

The tone generating units 100 occupy a relatively narrow space, and a compact music box or musical instrument is realized with an array of tone generating units 100.

Stringed Instrument

The reeds do not set any limit on the musical instrument according to the present invention. Any sort of vibratory member is available for the musical instrument. Strings are one of the sorts of vibratory members.

FIGS. 9A and 9B shows an example of the stringed instrument. The stringed instrument may serve as a part of a music box. The stringed instrument largely comprises a housing 1A, a tone generator 3A implemented by strings 233 and an automatic player 5A.

The housing 1A includes the bottom disk 10 and a cylindrical wall 38. The cylindrical wall 38 and bottom disk 10 are assembled into the housing, and define a space over the upper surface of the bottom disk 10. The tone generator 3A and automatic player 5A are accommodated in the space.

The tone generator 3A includes the pedestal 31, an inner frame 34, an outer frame 37 and strings 34 stretched between the inner frame 34 and the outer frame 37. The pedestal 31 is upright on the upper surface 10a of the bottom disk 10, and is fixed to the bottom disk 10. The inner frame 34 is made of metal or alloy. The inner frame 34 is reinforced with beams 35, and the distance between the center of the pedestal 31 and the periphery of the inner frame 34 is varied together with the angle. The frame 34 is horizontally disposed on the upper surface of the pedestal 31, and is fixed thereto by means of a bolt 36. The outer frame 37 is circular, and is fixed to the cylindrical wall 38. The distance between the inner frame 34 and the outer frame 37 is varied together with the angle. The strings 233 are stretched between the inner frame 34 and the outer frame 37, and are different in thickness and length for generating tones different in pitch from one another. In this instance, twenty-four strings 233 are incorporated in the tone generator 3A.

Since the strings 233 radially extend between the inner frame 34 and the outer frame 37 so that the strings 233 are spaced from the adjacent strings 233 at the outer ends wider than at the inner ends. Thus, the radial arrangement of the strings 233 offers wide local spaces to the automatic player 5A along the outer frame 37.

The automatic player 5A includes player's fingers 220 and a controller (not shown). The player's finger 220 is similar in structure to the player's finger 20, and a solenoid-operated actuator 21, a pick 22 and a spring 25 form parts of each player's finger 220. The player's fingers 220 are respectively associated with the strings 233, and each player's finger 220 is disposed on one side of the associated string 233.

When a user requests the automatic player 5A to perform a piece of music, the controller (not shown) selectively supplies the driving signal to the solenoid-operated actuators 21 associated with the strings 233 to be plucked. The picks 22 are inclined toward the associated strings 233, and the plungers upwardly project from the bobbins. The picks 22 push the strings 233 upwardly. Then, the picks 22 escape from the associated strings 233, and permit the strings 233 to vibrate. The picks 22 are inclined toward the opposite sides of the associated strings 233. The controller removes the magnetic field from the solenoid-operated actuators 220. Then, the plungers are retracted into the bobbins, and the inclined picks 22 return to the rest positions without any interference with the vibrating reeds 33b.

It is preferable to pluck the strings 233 at which each string 233 is divided at 1:7. In this instance, the player's fingers 220 are located around the optimum positions. However, the player's fingers are just located at the respective optimum positions.

Second Embodiment

Prototype

FIGS. 10A and 10B show another musical instrument embodying the present invention. The musical instrument shown in FIGS. 10A and 10B is categorized in a music box. The musical instrument largely comprises a housing 1B, a tone generator 3B and an automatic player 5B. The housing 1B and tone generator 3B are similar in structure to the housing 1 and tone generator 3. For this reason, the com-

ponent parts of the housing/tone generator 1/3 are labeled with the references designating the corresponding component parts of the housing/tone generator 1/3 without detailed description.

The automatic player 5B also comprises player's fingers 20B and a controller 20Aa. The system components of the controller 20Aa are similar to those of the controller 20A (see FIG. 12). In the controller 20Aa, the driver circuit 17a includes a pulse width modulator 17b. The pulse width modulator 17b varies the pulse width of the driving signal depending upon the loudness of a tone to be generated as will be described hereinafter.

The player's fingers 20B are arranged in the peripheral zone of the inner space defined in the housing 1B, and are in the close proximity of the tips 33c of the reeds 33b. The player's fingers 20B are similar in structure to one another. As will be better seen in FIGS. 11A and 11B, the player's finger 20B includes the solenoid-operated actuator 21, a pick 22B and the spring 25.

The pick 22B is rotatably connected to the pin 24, which in turn is supported by the plunger 26. The pick 22B has a relatively narrow lower portion 22a and a relatively wide upper portion 22b so that the step 22c takes place at the boundary between the upper end portion 22b and the lower end portion 22a. The pick 22B has an end surface 22f partially flat and partially rounded. The flat area is brought into contact with the tapered tip 33c during the upward motion of the plunger 26, and pushes the tapered tip 33c so as to warp the reed 33b. When the elastic force exceeds the magnetic force, the spring 25 inclines the pick 22B outwardly. Then, the rounded area slides on the tapered tip 33c, and the pick 22B escapes from the tapered tip 33c. Thus, the rounded area makes the escape smooth, and the pick 22B is never caught on the tapered tip 33c.

The pulse width modulator 17b incorporated in the driver circuit 17a controls the loudness of the tones to be produced through the vibrations of the reeds 33b. The central processing unit 11 is assumed to instruct the driver circuit 17a to supply the driving signal for generating a loud tone. The pulse width modulator 17b increases the pulse width of the driving signal, and supplies it to the solenoid-operated actuator associated with the reed 33b to be plucked. When the driving signal reaches the coil 21a, a large amount of current flows, and creates a strong magnetic field. The pick 22B is strongly attracted to the inner portion of the bottom yoke 25a, and the plunger upwardly projects from the bobbin 23 powerfully. The magnetic force is so large that the spring can not outwardly incline the pick 22 as usual. Thus, the driving signal with the wide pulse width results in the strong attractive force exerted on the pick 22 as well as the speed-up of the plunger 26. For this reason, the pick 22B makes the reed 33b widely warped. However, the elastic force exceeds the magnetic force later than usual. Then, the pick 22 escapes from the tapered tip 33c, and permits the reed 33b to vibrate. The escape is later than the usual escape is. This means that the reed 33b is widely warped, and the amplitude of the vibrations is wider than the amplitude of the usual vibrations. This results in the loud tone.

Assuming now that a user requests the automatic player 5B to perform a piece of music, the central processing unit 11 sequentially fetches the music data codes from the random access memory 13. One of the music data codes is assumed to represent the note-on event for generating a tone. When the time at which the tone is to be generated comes, the central processing unit 11 instructs the driving circuit 17a to supply the driving signal to the associated solenoid-operated actuator 21. The driving circuit 17a determines the

optimum pulse width, and the pulse width modulator **17b** adjusts the driving signal to the optimum pulse width. The driving signal is supplied to the coil **21a**, and creates the magnetic field. The pick **22B** was resting at position **P3** before reaching the driving current. When the magnetic field is created, the pick **22B** is inwardly inclined, and the plunger **26** starts to lift the pick **22B**.

The pick **22B** is brought into face-to-face contact with the tapered tip **33c** at the flat area of the upper surface **22f**. The upper surface **22f** pushes the tapered tip **33c**, and warps the reed **33b**. While the plunger **26** is upwardly projecting, the magnetic force is weakened, and the elastic force of the spring **25** is increased. When the elastic force exceeds the magnetic force, the spring **25** pulls the pick **22B**, and outwardly inclines the pick **22B** as indicated by **P1**. While the spring **25** is inclining the pick **22B**, the rounded area of the upper surface **22f** smoothly slides on the tapered tip **33c** until the escape from the tapered tip **33c**.

The driver circuit **17a** recovers the driving signal to the inactive level. The magnetic field is removed from the solenoid-operated actuator **21**, and the magnetic force is exerted on the pick **22B**. For this reason, the spring **25** further inclines the pick **22B** outwardly as indicated by **P2**. The plunger **26** is retracted into the bobbin **23**, and the pick **22B** returns to the rest position as indicated by **P3**.

As will be appreciated from the foregoing description, the musical instrument implementing the second embodiment achieves all the advantages of the first embodiment. Moreover, the spring **25** inclines the pick **22B** outwardly so that the pick **22B** returns to the rest position without interference with the vibrating reed **33b**. The automatic player **5B** merely requires an additional space, which permits the outwardly inclined picks **22B** to return to the rest positions thereof. Any other space is not required for the player's fingers **20B**. The additional space is negligible in the inner space of the housing **1B** so that the musical instrument is compact.

Another attractive point of the musical instrument according to the present invention is forcibly to incline the pick **22B** after the plucking. The outwardly inclined pick **22B** never interferes with the vibrating reeds **33b**. This results in clear tones. Moreover, the springs **25** continuously exert the elastic force on the pick **22B** until returning to the rest position. Thus, the springs **25** prevent the picks **22B** from chattering.

Yet another attractive point of the music instrument according to the present invention is the upper surfaces **22f** of the picks **22B** which have the respective flat areas and respective rounded areas. While the picks **22B** is warping the tips **33c** of the associated reeds **33b**, the flat areas are held in contact with the flat surfaces of the associated tapered tips **33c** so that the force is effectively transferred from the picks **22B** to the reeds **33b** without slippage. When the springs **25** pull the picks **22B** outwardly, the rounded area slide on the flat surfaces of the tapered tips **33c** so that the picks **22B** smoothly escape from the reeds **33b**.

Other Player's Fingers

The musical instrument implementing the second embodiment are modified as follows. First, the player's fingers **20B** are replaced with player's fingers **20C** shown in FIG. 14. The player's finger **20C** includes a solenoid-operated actuator **21C**, the spring **25**, a pick **162** and a guide block **163**. The solenoid-operated actuator **21C** is similar to the solenoid-operated actuator **21** except a plunger **161**. For this reason, the other component parts are labeled with the

references designating the corresponding component parts of the solenoid-operated actuator **21** without detailed description.

The plunger **161** is slidably received in the bobbin **23**, and a slit **161a** is formed in the upper end portion of the plunger **161**. The slit **161a** is opened at the outer end, and is closed at the inner end. In other words, a pair of side surfaces and an inner end surface **161b** define the slit **161a**. The pin **24** is provided in the upper portion of the plunger **162** across the slit **161a**, and the pick **162** is rotatably supported at the lower end of the stem portion **162a** thereof by the pin **24**. The pick **162** is rotatable on a trajectory, which is aligned with the centerline of the associated reed **33b**. However, the inner end surface **161b** sets a limit to the rotation of the pick **162**, and the inner end surface **161b** causes the pick **162** to be brought into contact with the tapered tip **33c** of the associated reed **33b**. The pick **162** is made of soft magnetic material.

The pick **162** is like a plate, and has a head portion **162b** at the upper end of the stem portion **162a**. The head portion **162b** projects inwardly and outwardly from the stem portion **162a**, and the spring **25** is connected between the head portion **162b** and the upper surface of the bottom yoke **25a**. The head portion **162b** has a rounded upper surface. The rounded upper surface is steep in the inward direction, and is gentle in the outward direction. The part of the head portion **162b** inwardly projecting from the stem portion **162a** is hereinafter referred to as "inner sub-portion **162b1**", the top of the head portion is labeled with **162b2**, and the part of the head portion **162b** outwardly projecting from the stem portion **162a** is referred to as "outer sub-portion **162b3**". The tip of the inner sub-portion **162b1** is rounded.

The guide block **163** is fixed to the bottom yoke **25a**. The guide block **163** rises from the upper surface of the bottom yoke **25a**, and inwardly projects. The inner end portion of the guide block **163** is spaced from the associated reed **33b** so that the vibrating reed **33b** does not beat the inner end portion. The guide block **163** has three guide surfaces **163a**, **163b** and **163c** over the pick **162**. As will be described hereinafter in detail, the head portion **162b** is firstly brought into contact with the guide surface **163a**, thereafter, slides on the guide surfaces **163a**, **163b** during the escape, and the guide surface **163c** leads the head portion **162b** to the rest position. Thus, the guide block **163** defines the behavior of the pick **162** in the reciprocal motion.

The reference **162(P0)** is indicative of the pick at the rest position. Assuming now that the controller energizes the solenoid-operated actuator **21C**, the magnetic field is created, and the plunger **161** starts to project from the bobbin **23**. The pick **162** is inwardly attracted in the magnetic field. For this reason, although the elastic force of the spring **25** is increased together with the upward motion of the plunger **161**, the stem portion **162a** is pressed to the inner end surface **161b**.

The inner sub-portion **162b1** is brought into contact with the tapered tip **33c** as indicated by **162(P1)**. The plunger **161** further projects upwardly, and the head portion **162b** warps the reed **33b**. The inner sub-portion **162b1** keeps the face-to-face contact with the tapered tip **33c** so that the force is effectively exerted on the reed **33b**. When the pick **162** reaches the position indicated by **162(P2)**, the elastic force of the spring **25** becomes larger than the magnetic force, and the pick **162** outwardly inclined. The inner sub-portion **162b1** slides on the tapered tip **33c**, and the pick **162** escapes from the reed **33b**. Since the tip of the inner sub-portion **162b1** is rounded, the pick **162** smoothly escapes from the reed **33b**.

The plunger 161 further projects, and the inner sub-portion 162b1 is brought into contact with the guide surface 163a as indicated by 162(P3). The guide surface 163a makes the head portion 162b further spaced from the reed 33b, and the pick 162 is further inclined outwardly. The elastic force of the spring 25 is increased together with the stroke of the plunger 161, and the magnetic force is weakened. The head portion 162b slides on the guide surface 163b, and reaches the guide surface 163c as indicated by 162(P4).

The magnetic field is removed from the solenoid-operated actuator 21C, and the plunger 161 is retracted into the bobbin 23. The elastic force is still exerted on the pick 162, and the outer sub-portion 162b3 downwardly slides on the guide surface 163c. The plunger 161 is softly received on the cushion sheet 23a, and the pick 162 reaches the rest position 162(P1).

As will be understood, the guide block 163 defines the trajectory of the pick 162, and prevents the pick 162 from damage due to excess force. This results in that the pick 162 is durable.

FIGS. 15A to 15F shows another modification 20D of the player's finger. The player's finger 20D includes a solenoid-operated actuator 21D, a spring 176 and a guide block 174 and a pick 175. The solenoid-operated actuator 21D includes a yoke 171, a coil 172 and a plunger 173. The yoke 171 has a cylindrical space, and the plunger 173 is slidably received in the cylindrical space. The coil 172 is wound around the plunger 173. The upper portion of the plunger 173 is partially cut off (see FIG. 15B), and the pick 175 is rotatably connected to the plunger 171 by means of a pin.

The yoke 171 has a flat upper surface, and any projection is not formed in the inner portion thereof. For this reason, the magnetic force is not exerted on the pick 175 so as to make the pick 175 inclined inwardly.

The pick 175 has a plate portion 175a and a head portion 175b. The plate portion 175a is rotatably connected to the pin. The head portion 175b has an inner rounded end surface 175c. The spring 176 is connected at one end thereof to the head portion 175b, and is anchored to the upper surface of the yoke 171. The anchored portion is sidewardly offset from the trajectory of the pick 175 so that the pick 175 is sidewardly outwardly urged. In other words, the pick 175 is urged outwardly as similar to the pick 162, and is further urged in the direction indicated by F4 (see FIG. 15F). A guide pin 179 passes through the head portion 175b, and sideward projects from both side surfaces of the head portion 175b.

The guide block 174 is fixed to the yoke 171, and is shaped like a channel. When the guide block 174 is fixed to the yoke 171, a hollow space is defined. The reed 33b projects into the hollow space as shown in FIG. 15A. The guide block 174 has a pair of side walls 174a/174b, and the side wall 174a is in parallel to the other side wall 174b. Guide grooves 174a1 and 174b1 are respectively formed in the side walls 174a/174b, and the pin 179 is loosely received at both end portions thereof to the guide grooves 174a1/174b1. The guide groove 174a1 has an upward path 174a1A and a downward path 174a1B. The lowermost end of the upward path 174a1A is the lower dead point 174a01 of the guide groove 174a1, and the uppermost end of the downward path 174a1B is the upper dead point 174a02 of the guide groove 174a1. The guide groove 174a1 is deepest at the lower dead point 174a01 and upper dead point 174a02 (see FIG. 15D). The upward path 174a1A becomes shallower along the curved portion 174a21, and the curved portion 174a21 is connected to the downward path 174a1B. However, the curved portion 174a21 is shallower than the downward path 174a1B at the boundary therebetween so

that a step 174a11 takes place. Similarly, the downward path 174a1B becomes shallower along the curved portion 174a22, and is connected to the upward path 174a1A. The curved portion 174a22 is also shallower than the upward path 174a1A so that a step 174a12 takes place at the boundary therebetween. The other guide groove 174b1 also has an upward path and a downward path, and the upward path and downward path are arranged in parallel to the upward path 174a1A and downward path 174a1B, respectively. However, any step is not formed between the upward path and the downward path. The spring 176 always urges the pick 175 toward the side wall 174a so that the pin 179 slides on the bottom surfaces of the upward/downward paths 174a1A/174a1B.

The pin 179 is moved along the guide grooves 174a/174b. While the plunger 173 is projecting from the yoke 171, the pick 175 is moved upwardly together with the plunger 173, and the upward paths 174a1A guide the pin 179. The pin 179 passes through the curved portion 174a21, and enters the downward path 174a1B. Although the pin 179 passes through the boundary between the downward path 174a1B and the curved portion 174a21 in the downward motion, the pin 179 does not enter the curved portion 174a21, because the step 174a11 does not permit the pin 179 to enter the curved portion 174a21. Similarly, the step 174a12 does not permit the pin 179 to enter the curved portion 174a22 in the upward motion. Thus, the head 175a is traced along a trajectory TR (see FIG. 15F), and plucks the reed 33b as will be described hereinafter in detail.

While any current does not flow through the coil 172, the pick 175 is staying at the rest position 175(P0). Assuming now that the controller (not shown) energizes the solenoid-operated actuator 21D, the magnetic field is created, and gives rise to the upward motion of the plunger 173. The plunger 173 upwardly lifts the pick 175, and the pin 179 slides on the bottom surface from the lower dead point 174a01 to the boundary between the straight portion and the curved portion 174a21. Since the depth is constant, the head 175b is straightly moved toward the tip of the associated reed 33b. When the head 175b is brought into contact with the tip of the reed 33b, the pin 179 is still on the way to the boundary between the straight portion and the curved portion 174a21. The head 175b is further moved upwardly, and warps the reed 33b.

The pin 179 enters the curved portion 174a21. Then, the head 175b starts to laterally slide on the tapered tip of the reed 33b. The elastic force of the spring 176 is increased together with the plunger stroke, and makes the pick 175 outwardly inclined. The elastic force becomes large so that the pick 175 escapes from the reed 33b. The reed 33b freely vibrates for generating the tone. The plunger 173 further projects, and the pin 179 enters the downward path 174a1B over the step 174a11. The head 175b becomes offset from the vibrating reed 33b.

The controller (not shown) removes the magnetic field from the solenoid-operated actuator 21D so that the plunger 173 and, accordingly, pick 175 start to sink downwardly. The pin 179 slides on the bottom surface of the downward path 174a1B toward the boundary between the straight portion and the curved portion 174a22. Since the depth is constant, the pick 175 passes beside the vibrating reed 33b, and does not interfere with the vibrating reed 33b. When the pin 179 reaches the boundary, the head 175b is below the vibrating reed 33b. Then, the pin 179 enters the upward path over the step 174a12. Although the head 175b returns to the space beneath the reed 33b, the head 175b does not interfere with the vibrating reed 33b. Finally, the pin 179 slides on the

bottom surface of the straight portion to the lower dead point **174a01**, and reaches the rest position.

Thus, the pin **179** and guide block **174** shunt the head portion **175b** from the upward pass to the downward path after the plucking, and make the head portion **175b** pass beside the vibrating reed **33b**. The pick **175** never interfere with the vibrating reed **33b** so that the musical instrument generates clear tones.

FIGS. **16** and **17** show an automatic player, in which another modification of the player's fingers. The player's fingers **20E** form parts of the automatic player together with a controller **20Ab**, and the automatic player in turn forms a musical instrument together with an array **48** of reeds. The musical instrument is categorized in the music box. The array **48** includes a base plate **47** and reeds **48a**, and the reeds **48a** project from the base plate **47** in parallel to one another. Thus, the comb-like reed array is used in the musical instrument. The player's fingers **20E** are associated with the reeds **48a**, respectively, and are disposed in the proximity of the tips of the associated reeds **48a**.

The controller **20Ab** causes the player's fingers **20E** to selectively pluck reeds **48**. The system configuration of the controller **20Ab** is similar to that of the controller **20Aa**, and the system components are labeled with references designating corresponding system components of the controller **20Aa** without detailed description.

The player's fingers **20E** include respective solenoid-operated flat actuators **FLAT1**, respective blades **45** and respective rotary picks **46**. Plural permanent magnet plates **41** are alternated with yokes **42** so as to form a magnetic block, which is shared among the solenoid-operated flat actuators **FLAT1**. The magnetic block is fixed to a base **55** in such a manner that the permanent magnet plates **41** are elongated in directions in parallel to the centerlines of the associated reeds **48a**. The permanent magnet plates **41** are made of magnetic material containing a rare earth element such as, for example the magnetic material in neodymium series.

The yokes **42** have a same shape. Each yoke **42** has a thin portion **42a** and a thick portion **42b**. The thin portion **42a** is sandwiched between two permanent magnetic plates **41**, and the thick portion **42b** projects over the permanent magnetic plates **41**. Since the thick portion **42b** is thinner than the permanent magnetic plate **41**, the adjacent thick portion **42b** is spaced from the adjacent thick portions **42b**, and gaps take place between the thick portions **42b**. The yokes **42** offer magnetic paths to the magnetic field created by the permanent magnet plates **41**, and the magnetic field are created across the gaps.

Each of the solenoid-operated flat actuators **FLAT1** further includes a swingable arm **43** and a flat coil **44**. The swingable arm **43** has both side surfaces substantially in parallel to a virtual plane on which the centerline of the associated reed **48a** extends. The flat coil **44** is fixed to one of the side surfaces of the swingable arm **43**, and a pin **49** is fixed to the swingable arm **43**. The pin **49** sidewardly projects from the side surfaces of the swingable arm **43**, and is rotatably supported by a frame (not shown). Thus, the swingable arm **43** and, accordingly, the flat coil **44** are rotatably supported by the frame. Although the gaps are respectively assigned to the swingable arms **43**, only one swingable arm **43** is illustrated in FIG. **17**. While any current does not flow through the flat coil **44**, the flat coil **44** is resting in the magnetic field created in the gap. When the current flows through the flat coil **44**, the magnetic force is exerted on the flat coil **44**, and causes the flat coil **44** and, accordingly, the arm **43** to move in the direction determined

on the basis of the Fleming's left-hand rule. Thus, the current flowing through the flat coil **44** gives rise to the rotation of the swingable arm **43** about the centerline **49a** of the pin **49** in the counter clockwise direction in FIG. **17**. When the controller **20Ab** stops the current, the self-weight of the swingable arm/flat coil **43/44** return to the rest position in the gap. The trajectory of the swingable arm **43** is substantially coplanar with the vibrating reed **48a**.

The blade **45** is made of metal or alloy, and is fixed to the leading end of the swingable arm **43**. The blade **45** has a leading end portion slightly inclined to the associated rotary pick **46**. For this reason, the blade **45** gives rise to rotation of the rotary pick **46** without slippage. Thus, the force is surely transferred from the blade **45** to the rotary pick **46**. While the swingable arm **43** is resting in the gap, the blade **45** upwardly projects from the swingable arm **43** (see FIG. **18A**). The blade **45** is rotated together with the swingable arm **43** when the current flows through the flat coil **44**.

The rotary picks **46** are made of metal or alloy, and are respectively associated with the reeds **48a**. Spacers **50** are alternated with the rotary picks **46** so as to make the rotary picks **46** confronted to the associated reeds **48a** (see FIG. **18B**). The rotary picks **46** are arrayed as similar to the reeds **48a**. Each of the rotary picks **46** has plural claws **46a** and a disk **46b**. In this instance, claws **46a** radially project from the disk **46b** at regular intervals. In other words, each claw **46a** is spaced from the adjacent claws **46a** at 90 degrees. The disk **46b** is rotatably supported by the frame. Although the disk **46b** is spaced from the tip of the associated reed **48a**, the claws **46a** reach the reed **48a**, and pluck the reed **48a** for vibrations. A ratchet **53** is provided for each of the rotary pick **46** so that the rotary pick **46** is rotatable about a centerline **46c** only in the counter clockwise direction in FIG. **17**.

While the swingable arm **43** is resting in the gap, the tip of the blade **45** is located in the close proximity of one of the claws **46a**. When the swingable arm **43** is rotated, the tip of the blade **45** pushes the claw **46b** so that the rotary pick **46** is driven for rotation, and another claw **46b** pushes the tip of the reed **48a** downwardly. The claw **46b** is further rotated, and is spaced from the tip of the reed **48a**. Thus, the rotary pick **46** plucks the reed **48a** for vibrations.

The claw **46a** has a rounded front surface **46a2** and a flat back surface **46a1** (see FIG. **18A**). The blade **45** pushes the flat back surface **46a1** so that the force is certainly exerted on the claw **46a**. On the other hand, the rounded front surface **46a2** is brought into contact with the tip of the reed **48a**, and makes the reed **48a** warped. The tip of the reed **48a** smoothly slides on the rounded front surface **46a2** so that the claw **46a** is never caught on the reed **48a**.

Assuming now that a user requests the automatic player to perform a piece of music, the central processing unit **11** sequentially accesses music data codes stored in the memory **13**, and instructs the driver circuit **17** to selectively energize the solenoid-operated flat actuators **FLAT1**. While the central processing unit **11** is sequentially processing the music data, the central processing unit **11** is assumed to instruct the driver circuit **17** to pluck the reed **48a** shown in FIG. **18A**. The flat coil **44** has not been energized so as to keep the swingable arm **43** horizontal. The tip of the blade **45** stands upright, and is spaced from the rotary pick **46**.

The driver circuit **17** determines the pulse width to be required for the target loudness, and the pulse width modulator PWM supplies the driving signal with the pulse width to be required for the target loudness to the flat coil **44**. When the current flows through the flat coil **44**, the magnetic force is exerted on the flat coil **44**, and gives rise to rotation of the

swingable arm **43** in the counter clockwise direction. The blade **45** is brought into contact with the flat back surface **46a1** of the rotary pick **46**, and pushes it. The rotary pick **46** is driven for rotation over 90 degrees as indicated by arrow **AR5** (see FIG. 19), and plucks the reed **48a** with the claw **46** spaced 180 degrees from the claw **46** pushed by the blade **45**. The reed **48a** vibrates as indicated by arrow **AR6**, and generates the tone. The disk **46b** is spaced from the vibrating reed **48a**, and the claws **46a** are out of the trajectory of the vibrating reed **48a**. Thus, the rotary pick **46** does not interfere with the vibrating reed **48a**.

The driver circuit **20Ab** removes the driving signal from the flat coil **44**. Then, the self weight causes the swingable arm **43**, flat coil **44** and blade **45** to return to the rest position shown in FIG. 18A. The ratchet **53** prevents the rotary pick **46** from the reverse rotation.

In this instance, the swingable arms **43** and flat coils **44** occupy the space under the array of reeds **48**, and the blades **45** and the rotary picks **46** are provided in the proximity of the tips of the reeds **48a**. The space to be additionally required for the vibrating reeds **48a** is the gap between the claws **46a**. Thus, the array of reeds **48** and player's fingers **20E** are compactly packed in a housing of the musical instrument without interference with the vibrating reeds **48**. This results in the compact musical instrument.

Moreover, the controller **20Ab** independently energizes the solenoid-operated flat actuators **FLAT1** on the basis of the music data codes so that the automatic player performs any piece of music. If plural tones are to be concurrently produced for a chord, the controller **20Ab** concurrently energizes the associated solenoid-operated flat actuators **FLAT1**.

The flat coils **44** are used in the player's fingers **20E**. The flat coils **44** are so thin that the manufacturer can arrange the player's fingers **20E** at small pitches. Thus, the player's fingers **20E** plucks the reeds **48a** of the comb-like array **48**.

The claws **46a** are arranged on the disk **46b** at intervals, and the intervals are wide enough to permit the associated reed **48a** to vibrate without interference. The vibrations are stable, and, accordingly, the tones are clear.

The rotary pick **46** includes more than one claws **46a**. One of the claws **46a** is pushed with the blade **45**, and another claw **46a** plucks the reed **48a**. The roles are sequentially changed among the plural claws **48a**. This results in the simple structure of the player's fingers.

FIGS. 20A and 20B show another player's finger **20F** incorporated in an automatic player, which in turn forms a part of a musical instrument. The player's fingers **20F** are respectively associated with the reeds **48a**, and, are selectively energized by the controller **20Ab** (see FIG. 16). Each of the player's fingers **20F** includes the solenoid-operated flat actuator **FLAT1**, a pick **51**, a string **52** and a guide block **52a**. The solenoid-operated flat actuator **FLAT1** is similar to that of the player's finger **20E**, and the component parts are labeled with same references designating corresponding component parts in the player's finger **20E** without detailed description.

The blade **45** and rotary pick **46** are replaced with the pick **51**. The pick **51** has a stem portion **51a** and a head portion **51b**, and the stem portion **51a** is rotatably connected at the lower end thereof to the free end portion **43a** of the swingable arm **43** by means of a pin **56**. For this reason, the pick **51** is rotatable in the clockwise direction and counter clockwise direction. The head portion **51b** has a rounded front surface **51b1**, and the rounded front surface **51b1** smoothly slides on the tapered tip **48b** of the associated reed **48a**. The spring **52** is connected at one end thereof to the

head portion **51b** and at the other end thereof to a stationary member of the musical instrument such as an inner surface of the guide block **52a**. While the swingable arm **43** is staying in the gap between the yokes **42**, the spring exerts a negligible amount of elastic force on the pick **51** so that the pick **51** keeps its attitude upright. The spring **52** increases the elastic force together with the rotation of the swingable arm **43** in the counter clockwise direction.

Guide pins **57** sidewardly project from the side surfaces of the head portion **51b**. Though not shown in the figures, guide grooves are formed in the side walls of the guide block **52a**, and the pins **57** are moved along the guide grooves. The guide grooves for the upward motion are routed differently from the guide grooves for the downward motion. While the pins **57** are moved along the guide grooves for the upward motion, the rounded front surface **51b1** is brought into contact with the tapered tip **48b**, makes the rounded front surface **51b1** slide on the tapered tip **48b**, and escapes from the tapered tip **48b**. Then, the reed **48a** vibrates for generating a tone. After the escape, the pins **57** enter the guide grooves for the downward motion. While the pins **57** are moving along the guide grooves for the downward motion, the pick **51** is inclined as indicated by **51(P1)**, and passes in front of the vibrating reed **48a** without any interference. Thus, the trajectory of the head portion **51b** is defined by the guide grooves.

The pick **51** is staying at the rest position **P0**. The driver circuit **17** is assumed to energize the solenoid-operated flat actuator **FLAT1** during performance of the automatic player.

The swingable arm **43** is driven for rotation in the counter clockwise direction, and the pins **57** keep the pick **51** tangential with the longitudinal direction of the swingable arm **43** against the elastic force of the spring **52**. The rounded front surface **51b1** is brought into contact with the tapered tip **48b**, and warps the reed **48a**. The guide grooves and pins **57** make the pick **51** inclined as indicated by **51(P1)**, and the pick **51** escapes from the tapered tip **48b** of the reed **48a**. The rounded front surface **51b1** smoothly slides on the tapered tip **48b** so that the head portion **51b** is never caught on the tapered tip **48b**.

The driving circuit **17** removes the driving signal from the flat solenoid **44**, and the self-weight and elastic force cause the swingable arm **43**, flat solenoid **44** and pick **51** to pull down. Since the pins **57** are moved along the guide grooves for the downward motion, the head portion **51b** passes the space in front of the vibrating reed **48a**. Thus, the pick **51** does not interfere with the vibrating reed **48a**.

As will be understood, the player's fingers **20F** achieve all the advantages of the player's fingers **20E**. Moreover, the picks **51** are simpler than the rotary picks **46** so that the production cost is reduced. The guide block **52a**, pins **57** and springs **52** surely shunt the picks **51** to the downward trajectory, and prevent the vibrating reeds **48a** from the interference. This results in the clear tones.

FIG. 21 shows another modification of the musical instrument. The musical instrument shown in FIG. 21 is similar to the musical instrument shown in FIG. 17 except that rotary picks **66** are driven for rotation by solenoid-operated cylindrical actuators **CYL1**. The musical instrument comprises plural reeds **61**, a hub **63**, a controller (not shown) and player's fingers **20G**. The reeds **61** have respective boss portions **62** fixed to the hub **63**, and radially project from the hub **63**. In this instance, twenty reeds **61** are arranged around the hub **63**, and the hub **63** has a disk shape. In other words, the distance from the center of the hub **63** to the periphery thereof is constant. The reeds **61** are different in length and width from one another depending upon pitches of tones to

be generated. The distance between the center of the hub **62** and the player's fingers **20G** is varied depending upon the length of the reeds **61**. However, the distance between the center of the hub **63** and the periphery may be varied together with the angle so that the player's fingers **20G** are disposed on a virtual circle.

The player's fingers **20G** are fixed to brackets **64/65**, and are respectively associated with the reeds **61** for plucking. The player's finger **20G** includes the solenoid-operated cylindrical actuator **CYL1**, a rotary pick **66**, a head block **71** and a combination of cam plates and cam springs **76/75** serving as a brake unit. A solenoid coil **68**, a plunger **70**, a plunger spring **69** and yoke **64/65** form in combination the solenoid-operated cylindrical actuator **CYL1**. The yoke **64/65** has a pair of ring plates **64/65**, and yoke spacers **67** are provided between the ring plates **64** and **65**. The yoke **64/65** is bolted to the hub **63**, and is shared among all the solenoid-operated cylindrical actuators **CYL1**. The solenoid coils **68** are inserted into the space between the ring plates **64** and **65**, and the plungers **70** are slidably received in the cylindrical spaces defined in the associated solenoid coils **68**. Caps **65a/65b** are bolted to the ring plate **64** and **65** at intervals, and the caps **65a** offer extension spaces to the associated plungers **70**, respectively. Cushion sheets **72** and **73** are disposed at the bottoms of the caps **65a/65b**, and define the upper dead points and the lower dead points for the associated plungers **70**. The cushion sheets **72** and **73** absorb the impact of the plunger **70**, and prevent the solenoid-operated actuator **CYL1** from noise.

The plunger springs **69** are attached to the ring plate **65**, and always urge the associated plungers **70** upwardly. When current flows through the coil **68**, magnetic field is created, and the plunger **70** is downwardly pulled. On the other hand, the magnetic field is removed, the plunger spring **69** pushes the plunger **70** upwardly.

The head block **71** is fixed to an upper thin portion of the plunger **70**, and a ring space **70a** takes place between the head block **71** and the remaining thick portion of the plunger **70**. The claws **66a** of the associated rotary pick **66** selectively slide into the ring space **70a**, and are brought into contact with a part **71a** of the head block **71** when the plunger returns to the upper dead point. Thus, the head block **71** serves as a pusher.

The rotary pick is rotatably supported between the tip of the reed **61** and the solenoid-operated cylindrical actuator **CYL1**. The rotary pick **66** is similar to the rotary pick **46**, and has plural claws **66a**, which radially project at regular intervals. The brake units are respectively associated with the rotary picks **66**. The cam plates **76** are fixed to the sides surface of the rotary pick **66**, and the cam springs **75** are fixed to the cap **65a** on both sides of the rotary pick **66**. Each cam plate **76** has four corners, and the cam springs, which are leaf springs made of metal, are urged to be always held in contact with the cam plates **76**. The brake unit **76/75** permits the associated rotary pick **66** to be rotated in the clockwise direction. However, the brake unit **76/75** prohibits the rotary pick **66** from the rotation in the counter clockwise direction.

The player's finger **20G** plucks the associated reed **61** as shown in FIGS. **23A** to **23H**. FIG. **23A** shows the plunger **71** at the upper dead point, and the claw **66a1** is resting in the ring space **70a**. The controller is assumed to energize the coil **68**. The plunger **70** starts the downward motion against the elastic force of the spring **69**. The inner portion **71a** is brought into contact with the claw **66a1** as shown in FIG. **23B**. However, the claw **66a3** is still spaced from the tip of the reed **61**.

The plunger **70** is further moved downwardly, and gives rise to the rotation of the rotary pick **66** in the clockwise direction. The cam plates **76** are rotated against the elastic force of the cam springs **75** exerted on the corners, and the claw **66a3** plucks the reed **61** as shown in FIG. **23C**. The reed **61** vibrates, and generates a tone. The plunger **70** is further moved downwardly, and the rotary pick **66** is rotated in the clockwise direction. However, the next claw **66a2** has not reached the vibrating reed **61**, and the rotary pick **66** does not interfere with the vibrating reed **61** as shown in FIG. **23D**. When the plunger **70** reaches the lower dead point, the next claw **66a2** is still spaced from the vibrating reed **61**.

The magnetic field is removed from the solenoid-operated cylindrical actuator **CYL1**, and the plunger spring **69** urges the plunger **70** in the upward direction. Although the head block **71** pushes the claw **66a4**, the cam springs **75** and cam plates **76** do not permit the rotary pick **76** to be rotated in the counter clockwise direction, because the braking force is larger than the friction between the head block **71** and the claw **66a4** (see FIG. **23E**).

FIGS. **23F** and **23G** illustrate the plunger **70** on way to the upper dead point. However, the cam plates **76** and cam springs **75** prevent the rotary pick **66** from the rotation in the counter clockwise direction. When the plunger **70** reaches the upper dead point, the head block **71** is spaced from the claw **66a4**, which is to be pushed during the next downward motion of the plunger **70**, and the cam springs **75** slightly rotate the rotary pick **66** in the clockwise direction. As a result, the next claw **66a4** slides into the ring space as shown in FIG. **23H**.

The musical instrument achieves all the advantages of the above-described musical instrument according to the present invention. Moreover, the player's fingers **20G** pluck the associated reeds **61** surer than the player's fingers **20E**, because the head blocks **71** faithfully reciprocate the given trajectories. The brake unit **75/76** not only prevents the rotary pick **66** from the reverse rotation but also keep the claws **66a** at the same position in the ring space **70a** after the spring **69** spaces the head block **71** from the claws **66a**. The magnetic force exerted on the plunger **70** is constant, and the head block **71** exerts the constant force on the claw **66a**. This results in the clear tones at constant loudness.

FIGS. **24** and **25A** show another musical instrument according to the present invention. The musical instrument comprises an array **82** of reeds **83** and an automatic player. The automatic player includes plural player's fingers **20H** and a controller, which is same as the controller **20Ab** shown in FIG. **16**.

The array **82** is like a comb, and the reeds **83** project in parallel like the teeth of the comb. The reeds **83** are different in length and width so that tones different in pitch are generated by the reeds **83**. The array **82** is mounted on a block, and is fixed to the base plate **81** by means of bolts.

Solenoid-operated flat actuators **FLAT2** are employed in the player's fingers **20H**, and include permanent magnet plates **84**, yokes **85**, flat coils **86** and swingable arms **88**. The flat coils **86** are respectively attached to the side surfaces of the swingable arms **88**. The yokes **85** are taller than the permanent magnet plates **84**, and the yokes **85** and permanent magnet plates **84** are alternated with one another. For this reason, gaps take place between the yokes **85**, and the swingable arms **88** are resting in the gaps together with the flat coils **86** as shown in FIG. **25B**.

The arms **88** are swingably connected at the rear ends thereof to a shaft **87**, which in turn is supported by the base plate **81**. Arm springs **89** are provided for the swingable arms **88**, respectively, and always urge the swingable arms

88 in the clockwise direction in FIG. 25A so that free end portions of the arms **88** are rested on the lower surface of the upper stopper **90**, which is fixed to the base plate **81**, without any magnetic field. The rest positions of the swingable arms **88** are indicated by **88(P0)**, and the upper surfaces of the swingable arms **88** are held in contact with the lower surface of the upper stopper **90** at the rest positions. A lower stopper **95** is further fixed to the base plate **81**, and receives the free end portions of the arms **88** at the end of the rotation in the counter clockwise direction. **88(P1)** is indicative of the swingable arm **88** on the way to the lower stopper **95**. Guide plates **94** (see FIG. 24) are provided on both sides of each swingable arm **88**, and define the trajectory of the associated swingable arm **88**. For this reason, the trajectory of the swingable arm **88** is perpendicular to the upper surface of the base plate **81**.

The swingable arms **88** are respectively formed with notches **88b** in the free end portions as shown in FIG. 25C. Rotary picks **92** are rotatably connected to a shaft **91**, which is supported at both end portions thereof by the base plate **81**. A brake unit **93/96** is associated with each of the rotary pick **92**. The rotary pick **92** and brake unit **93/96** are same as those of the music player shown in FIGS. 21 to 23H. For this reason, detailed description is omitted for the sake of simplicity.

The claws **92a** selectively enter the notch formed in the associated swingable arm **88**. While the swingable arm **88** is rotating in the counter clockwise direction, the edge **88c**, which partially defines the notch **88b**, presses the claw **92a**, and gives rise to rotation of the rotary pick **92**. When the rotary pick **92** is rotated over a predetermined angle, the brake unit **93/96** stops the rotary pick **92**, and does not permit the rotary pick **92** from the reverse rotation.

Assuming now that the controller **20Ab** energizes the flat coil **86** shown in FIG. 25A, the magnetic force is exerted on the flat coil **86** and, accordingly, the swingable arm **88** so as to give rise to the rotation of the swingable arm **88** about the shaft **87** in the counter clockwise direction against the elastic force of the arm spring **89**. The swingable arm **88** starts the rotation at the rest position **88(P0)**, and is moved on the trajectory toward the lower stopper **95**.

The edge **88c** is brought into contact with the claw **92a**, and gives rise to the rotation of the rotary pick **92** in the clockwise direction against the elastic force of the cam springs **93**. Subsequently, the claw **92a**, which is at the opposite position 180 degrees spaced from the claw **92a** pressed by the edge **88c**, is brought into contact with the associated reed **83**, and plucks it. The reed **83** vibrates, and generates the tone. When the swingable arm **88** reaches the lower stopper **95**, the reed **83** is vibrating in the space between the claw **92a** and the next claw **92a** so that the rotary pick **92** does not interfere with the vibrating reed **83**.

When the magnetic force is removed from the flat coil **86**, the arm spring **89** rotates the swingable arm **88** in the clockwise direction. Although the friction between the claw **92a** and the swingable arm **88** urges the rotary pick **92** in the counter clockwise direction, the brake unit **93/96** does not permit the rotary pick **92** from the reverse rotation. The swingable arm **88** reaches the upper stopper **90**, and the cam springs **93** urge the rotary pick **92** in the clockwise direction so that the next claw **92a** enters the notch **88b**.

The musical instrument achieves the advantages by virtue of the solenoid-operated flat actuators **FLAT2**, rotary picks **92** and brake units **93/96**. Moreover, the swingable arms **88** are stable and large in mechanical strength so that the musical instrument is durable.

FIGS. 26A and 26B show another musical instrument according to the present invention. The musical instrument comprises an automatic player and a daisy reed wheel **113**, which forms a part of a tone generator. The automatic player includes plural player's fingers **20I** and the controller **20Aa** (see FIG. 12). The daisy reed wheel **113** has reeds **114** radially outwardly projecting from the circular periphery of a disk **113a**, and the player's fingers **20I** are disposed in the proximity of the tips of the reeds **114**. In this instance, twenty-four reeds project from the disk **113a**, and are different in length and width from one another for generating tones different in pitch.

The player's finger **20I** includes a solenoid-operated actuator **CLY2**, a rotary pick **112**, a pusher **122** and a spring **125**. The solenoid-operated actuator **CLY2** is similar to the solenoid-operated **21C** (see FIG. 14), and includes a coil **121**, a bobbin **123a**, a bottom yoke **123b** and a plunger **126**. The pusher **122** has a lower end portion **122a**, which is rotatably connected to a pin **124**, and the string **125** is connected at one end thereof to the upper end portion of the pusher **122** and at the other end thereof to the bottom yoke **123b**. While the plunger **126** is staying at the rest position, the spring **125** exerts a negligible amount of elastic force on the pusher **122**. However, the elastic force is increased together with the stroke of the plunger **126** from the rest position. Since the bottom yoke **123b** has the inward portion upwardly project from the remaining portion, pusher **122** is inwardly inclined in the magnetic field. While the plunger **126** is projecting upwardly, the pusher **122** is spaced from the bottom yoke **123b**, and the magnetic force exerted on the pusher **122** is decreased. When the elastic force exceeds the magnetic force, the pusher **122** is outwardly inclined.

The rotary pick **112** is rotatably supported by the shaft **111** between the tip of the associated reed **114** and the solenoid-operated actuator **CLY2**. The rotary pick **112** has plural claws **112a** spaced at regular intervals, and a ratchet **115** is provided for the rotary pick **112**. The ratchet **115** permits the rotary pick **112** in the counter clockwise direction in FIG. 26B.

The controller **20Aa** is assumed to energize the solenoid-operated actuator **CLY2**, current flows through the coil **121**, and magnetic field is created. The pusher **122** is inwardly inclined as indicated by **122(P0)**, and the plunger **126** starts to project upwardly. The pusher **122** is brought into contact with the claw **112a**, and gives rise to rotation of the rotary pick **112** in the counter clockwise direction. Another claw **112a** warps the reed **114**, and escape from the reed **144**. Then, the reed **114** vibrates, and generates the tone. The ratchet **115** stops the rotary pick **112**. When the elastic force exceeds the magnetic force, the pusher **122** escapes from the claw **112a**.

When the pusher **122** reaches the upper dead point **122(P1)**, the controller **20Aa** removes the magnetic field from the solenoid-operated actuator **CLY2** so that any magnetic force is not exerted on the pusher **122**. The spring **125** outwardly inclines the pusher **122** as indicated by **122(P2)**, and the plunger **126** is retracted into the bobbin **123a**. When the plunger **126** reaches the lower dead point, the pusher **122** returns to the rest position **122(P3)**. Thus, the pusher **122** returns to the rest position without any interference with the claw **112a**.

The musical instrument achieves the advantages by virtue of the rotary pick **112** and solenoid-operated actuator **CLY2**. The player's fingers **20I** shown in FIG. 26B do not set any limit to the positions to be occupied. Other player's fingers may be provided over the rotary picks **112**.

FIGS. 27A, 27B and 28 show another musical instrument according to the present invention. The musical instrument is also broken down into a tone generator and an automatic player. The tone generator includes plural reeds 135 arranged like a comb on a base plate 146. The reeds 135 project from a boss portion 137 in parallel to one another. In the following description, term "front" is indicative of a relative position close to the right side of the paper where FIGS. 27A and 27B are drawn. For this reason, the reeds 135 project frontward.

On the other hand, the automatic player includes the controller 20Aa and plural player's fingers 20J, which share a guide frame 136a on the base plate 146 and a yoke 131 on a base plate 130 spaced from the base plate 146. The guide frame 136a is fixed to the base plate 146, and is provided over the reeds 135. The player's fingers 20J are respectively associated with the reeds 135.

Each of the player's fingers 20J includes a solenoid-operated actuator CYL3, a flexible tube 134, a wire 144, a pusher 139, a rotary pick 140 and a ratchet 142. The yoke 131 is fixed to the base plate 130, and is shared among the solenoid-operated actuators CYL3. Coils 132 are retained by the yoke 131, and are partially overlapped with one another. For this reason, plungers 133, which are respectively inserted into the coils 132, are exposed to the rear surface of the yoke 131 as shown in FIG. 27B.

The wire 144 is inserted into the flexible tube 134, and is connected at one end thereof to the associated plunger 133 and at the other end to the pusher 139. The wire 144 is flexible, and is strong enough to transmit the force to the pusher 139. A piano wire may be used as the wire 144. Even if the flexible tube 134 is winded, the wire 144 can slide inside the winded tube 134.

The guide frame 136a has two guide blocks 136 and 146 and a base plate 143. The guide blocks 136/145 are as wide as the array of reeds 135. The guide block 145 is frontward spaced from the other guide block 136, and are fixed to the base plate 143. Through-hole are formed in the guide block 136 for the flexible wires 144, and grooves are formed in the other guide block 145 for the pushers 139. The flexible wires 144 pass through the through-holes, and the pushers 139 are slidably received in the groove. The pushers 139 frontward project from the front end surfaces of the guide block 145. When the plungers 133 project from the yoke 131, the plungers 133 push the flexible wires 144, and the flexible wires 144 transfer the force to the associated pushers 139. As a result, the pushers 139 frontward project from the guide block 145. The pushers 139 are made from a relatively thin metal plate, and are elastically deformable.

The shaft 141 is arranged in parallel to the guide block 145, and the rotary picks 140 are rotatably supported by the shaft 141 at intervals. The rotary picks 140 are close to the associated pushers 139 and associated reeds 135. The ratchets 142 permit the associated rotary picks 140 in the clockwise direction in FIGS. 29A and 29B. Each of the rotary picks 140 has plural claws 140a spaced at regular intervals. In this instance, four claws 140a radially project at intervals of 90 degrees.

Assuming now that the controller 20Aa energizes the solenoid-operated actuator shown in FIG. 29A, the current flows through the coil 132, and creates magnetic field. Then, the plunger 133 frontward projects from the yoke 131, and the force F2 is transmitted from the plunger 133 through the flexible wire 144 to the pusher 139. The pusher 139 frontward projects from the guide block 145, and is brought into contact with one of the claws 140a. Although the tip of the pusher 139 is deformed (see FIG. 29B), the force F2 gives

rise to the rotation of the rotary pick 140 over 90 degrees. While the rotary pick 140 is rotating, another claw 140a plucks the reed 135 so that the reed 135 vibrates for generating a tone. The claw 140a, which has plucked the reed 135, reaches the position occupied by the claw 140a previously pushed by the pusher 139.

When the controller 20Aa removes the magnetic field, a return spring (not shown) moves the plunger 133 backwardly, and the plunger 133 is retracted into the yoke 131. The plunger 133 pulls the flexible wire 144 and the pusher 139. The pusher 139 slides on the claw 140a backwardly. However, the ratchet 142 does not permit the rotary pick 140 to rotate in the counter clockwise direction. The tip of the pusher 139 is warped, and returns to the rest position.

The musical instrument achieves the advantages by virtue of the rotary wheel 140. Moreover, the solenoid-operated actuators CYL3 are connected to the pushers 139 by means of the flexible wires 144 so that the manufacturer can locate the base plates 130 and 146 at the optimum positions. Thus, the flexible wires 144 enhance the design flexibility.

The yoke 131 may be separated into yokes, which are incorporated in the solenoid-operated actuators CYL3, respectively. The yoke may be replaced with a pair of plates. In this instance, each of the coils 132 is sandwiched between the plates.

In the musical instrument described hereinbefore, the pusher 139 projects from the guide block 145 for exerting the force on the claw 140a of the rotary pick 140. Another musical instrument may have a reciprocal rod 153 instead of the pusher 139 as shown in FIGS. 30A and 30B. In these figures, reference numeral 155 designates one of the reeds of a comb-like array, and rotary picks 156 are rotatably supported in the proximity of the associated reeds 155. The ratchets 158 are provided on the rotary picks 156, and permit the associated rotary picks 156 in the counter clockwise direction over the predetermined angle. Though not shown in the figures, the solenoid-operated actuators CYL3 are connected through flexible wires 151 to the reciprocal rods 153, and a guide block 151 slidably supports the flexible wires 152. Arms 154 are swingably connected to the tips of the reciprocal rods 153, and springs (not shown) always urge the swingable arms 154 in the counter clockwise direction. However, stoppers (not shown) do not allow the arms 154 to rotate beyond the positions shown in FIG. 30A. While the controller 30Aa is keeping the solenoid-operated actuators CYL3 non-magnetized, the reciprocal rods are staying at the rest positions spaced from the guide block 151, and the tip of the reed 155 is in the gap between the claws 156a as shown in FIG. 30A.

The solenoid-operated actuator CYL3 is assumed to pull the flexible wire 152. The reciprocal rod 153 is moved in the direction indicated by F3, and the arm 154 gives rise to the rotation of the rotary pick 156 in the counter clockwise direction. The ratchet 158 permits the rotary pick 156 to rotate over the predetermined angle, and another claw 156a plucks the reed 155 as shown in FIG. 30B. The reed 155 vibrates, and generates a tone.

The controller 20Aa removes the magnetic field from the solenoid-operated actuator CYL3. Then, the spring (not shown) moves the flexible wire 152 and the reciprocal rod 153 in the direction F2. Although the claw 156a is the obstacle against the arm 154 moved in the direction F2, the arm 154 is folded against the elastic force of the spring, and returns to the rest position. Even though the arm 154 slides on the claw 156a, the ratchet 158 keeps the rotary pick 156 stable. Thus, the player's finger achieves all the advantages of the player's finger 20J.

The pusher **139** may be replaced with a foldable pusher **157** shown in FIG. **30C**. The ratchet **159** permits the rotary pick **156** to rotate in the counter clockwise direction, and the foldable pusher **157** is connected through the flexible wire **152** to the plunger of the solenoid-operated actuator **CYL3**. A spring urges the foldable pusher **157** at a slightly raised attitude at the rest position **157(P0)**.

The plunger **133** is assumed to project from the yoke **131**. The flexible wire **152** and the foldable pusher **157** project from the rest position **157(P0)** to the position **157(P1)**, and gives rise to the rotation of the rotary pick **156** in the counter clockwise direction. The claw **156a** plucks the reed **155** for vibrations.

When the controller **20Aa** removes the magnetic field from the solenoid-operated actuator **CYL3**, the flexible wire **152** and foldable pusher **157** are moved in the direction **F3**. The foldable pusher **157** is stretched against the elastic force of the spring as indicated by **157(P2)**, and passes under the claw **156a** as indicated by **157(P3)**.

As will be understood from the foregoing description, the musical instruments implementing the second embodiment have the following advantages. The musical instruments equipped with the rotary picks make the reeds vibrate with the claws, and the reeds vibrate in the gap between the claws. This results in the natural vibrations without interference. In other words, clear tones are generated from the vibrating reeds.

The rotary picks change themselves between the plucking positions and the shunt positions through the rotation thereof. Any additional space is not required for leaving the reeds vibrating. Moreover, the rotary picks per se require narrow space. Thus, the rotary picks are conducive to the compactness of the musical instruments.

Another advantage by virtue of the rotary picks is promptness. The rotary picks require the rotation over the predetermined angle for changing their positions. Even if the controller quickly changes the plunger of the solenoid-operated actuator between the projecting position and the retracted position, the rotary pick can respond to the quick motion so that the musical instrument reproduces the repetition on the certain reed.

The reeds are replaceable with another sort of vibrating members such as, for example, strings or tone bars. Although the strings are plucked, the tone bars are beaten with mallets. In this instance, the player's fingers selective beat the tone bars.

Third Embodiment

Prototype

FIGS. **31**, **32**, **33A** and **33B** show a musical instrument embodying the present invention. The musical instrument is categorized in the music box. The musical instrument largely comprises a tone generator and an automatic player as similar to the first and second embodiments. The tone generator is implemented by a comb-like array **48K** of reeds **48a**, and the automatic player comprises a controller **20Ak** and player's fingers **20K**. The comb-like array **48K** of reeds **48a**, controller **20Ak** and player's fingers **20K** are similar in structure to the array **48** of reeds **48**, controller **20Ab** and player's fingers **20E** shown in FIGS. **16** and **17**. For this reason, component circuits of the controller **20Ak** and component parts of the comb-like array **48K** and player's fingers **20K** are labeled with references designating corresponding circuits of the controller **20Ab** and corresponding parts of the array **48** and player's finger **20E** without detailed description.

Assuming now that a user requests the automatic player to perform a piece of music, the central processing unit **11** sequentially accesses music data codes stored in the memory **13**, and instructs the driver circuit **17** to selectively energize the solenoid-operated flat actuators **FLAT1**. While the central processing unit **11** is sequentially processing the music data, the central processing unit **11** is assumed to instruct the driver circuit **17** to pluck the reed **48a** shown in FIG. **33A**. The flat coil **44** has not been energized so as to keep the swingable arm **43** horizontal. The tip of the blade **45** stands upright, and is spaced from the rotary pick **46**.

The driver circuit **17** determines the pulse width to be required for the target loudness, and the pulse width modulator **PWM** supplies the driving signal with the pulse width to be required for the target loudness to the flat coil **44**. When the current flows through the flat coil **44**, the magnetic force is exerted on the flat coil **44**, and gives rise to rotation of the swingable arm **43** in the counter clockwise direction. The blade **45** is brought into contact with the flat back surface **46a1** of the rotary pick **46**, and pushes it. The rotary pick **46** is driven for rotation over 90 degrees as indicated by arrow **AR5** (see FIG. **34**), and plucks the reed **48a** with the claw **46** spaced 180 degrees from the claw **46** pushed by the blade **45**. The reed **48a** vibrates as indicated by arrow **AR6**, and generates the tone. The disk **46b** is spaced from the vibrating reed **48a**, and the claws **46a** are out of the trajectory of the vibrating reed **48a**. Thus, the rotary pick **46** does not interfere with the vibrating reed **48a**.

The driver circuit **20Ab** removes the driving signal from the flat coil **44**. Then, the self weight causes the swingable arm **43**, flat coil **44** and blade **45** to return to the rest position shown in FIG. **33A**. The ratchet **53** prevents the rotary pick **46** from the reverse rotation.

In this instance, the controller **20Ak** selectively energizes the flat coils **FLAT1** for plucking the reeds **48a** with the claws **46a**. This means that the plural rotary picks **46** can concurrently pluck the reeds **48a** for producing a chord. The rotary pick **46** is rotated over only the predetermined angle for plucking the reed **48a**. The rotary pick **46** is responsive to quick repetition so that the automatic player can perform any complicated passage.

The solenoid-operated flat actuators **FLAT1** give rise to the rotation of the associated swingable arms **43** without any physical contact between the flat coils **44** and the yokes **42** and between the arms **43** and the yokes **42**. The arms **42** and flat coils **44** are less worn out. Thus, the player's fingers **20K** are durable.

The solenoid-operated flat actuators **FLAT1** occupy the space under the reeds **48a**. In other words, the solenoid-operated flat actuators **FLAT1** are overlapped with the comb-like reed array **48K**. This results in the compact musical instrument.

The automatic player can perform various passages without changing the hardware. The user needs to load a piece of music data into the memory **13**. Thus, the automatic player can answer all the user's requests in so far as the user prepares the pieces of music data.

The solenoid-operated flat actuators **FLAT1** are desirable for the comb-like reed array **48K**, because the manufacturer can arrange them at small pitches. Even though the reeds **48a** are extremely narrow, the solenoid-operated flat actuators **FLAT1** are provided in the proximity of the tips of the reeds **48a**.

The rotary picks **46** are desirable for the simple structure of the automatic player, because the claws **46a** not only receive the force from the blades **45** but also pluck the reeds **48a**.

Another attractive point of the rotary picks **46** is smoothly to change itself between the plucking position and the shunt position. This results in that the reeds **48a** generate clear tones. When the rotary pick **46** is rotated over the predetermined angle, the rotary pick **46** plucks the reed **48a** with one of the claws **48a**, and stops at the angular position in which the reed **48a** freely vibrates between the claws **46a**. The rotary pick **46** is required for the rotation over the predetermined angle. The claws **46a** do not interfere with the vibrating reed **48a**, because the claws **46a** are spaced wide enough to permit the reed **48a** to vibrate in the gap therebetween.

The solenoid-operated flat actuators **FLAT1** are disposed at any space, because the rotary picks **46** pluck the associated reeds **48a**. The combination between the rotary picks **46** and the solenoid-operated flat actuators **FLAT1** enhances the design flexibility.

The flat coils **44** may be alternated with the yokes **42**. In this instance, the permanent magnet plates **41** are attached to the swingable arms **43**. A large magnet may create a strong magnetic field for all the flat coils **44**.

Modifications

FIGS. **35A** and **35B** show a modification of the player's finger. The player's finger **20L**. The player's fingers **20L** are similar to the player's fingers **20F** so that the component parts of the player's finger **20L** are labeled with the component parts of the player's finger **20F** without detailed description.

The guide block **52a** and pin **57** keep the trajectory of the pusher **51** stable so that the pusher **51** does not interfere with the vibrating reed **48a**. The player's finger **20F** has the advantages by virtue of the solenoid-operated flat actuators **FLAT1**.

FIGS. **36**, **37A** and **37B** show a modification of the musical instrument. The musical instrument is broken down into a tone generator and an automatic player. The tone generator is implemented by a daisy reed wheel, and automatic player includes a controller and player's fingers **20M**. The daisy reed wheel, controller and player's fingers **20M** are similar to those of the musical instrument shown in FIGS. **21**, **22A** and **22B**. For this reason, the component parts are labeled with references designating corresponding parts of the musical instrument shown in those figures.

The player's finger **20M** plucks the associated reed **61** as shown in FIGS. **38A** to **38H**. FIG. **38A** shows the plunger **71** at the upper dead point, and the claw **66a1** is resting in the ring space **70a**. The controller is assumed to energize the coil **68**. The plunger **70** starts the downward motion against the elastic force of the spring **69**. The inner portion **71a** is brought into contact with the claw **66a1** as shown in FIG. **38B**. However, the claw **66a3** is still spaced from the tip of the reed **61**.

The plunger **70** is further moved downwardly, and gives rise to the rotation of the rotary pick **66** in the clockwise direction. The cam plates **76** are rotated against the elastic force of cam springs **75** exerted on the corners, and the claw **66a3** plucks the reed **61** as shown in FIG. **38C**. The reed **61** vibrates, and generates a tone. The plunger **70** is further moved downwardly, and the rotary pick **66** is rotated in the clockwise direction. However, the next claw **66a2** has not reached the vibrating reed **61**, and the rotary pick **66** does not interfere with the vibrating reed **61** as shown in FIG. **38D**. When the plunger **70** reaches the lower dead point, the next claw **66a2** is still spaced from the vibrating reed **61**.

The magnetic field is removed from the solenoid-operated cylindrical actuator **CYL1**, and the plunger spring **69** urges

the plunger **70** in the upward direction. Although the head block **71** pushes the claw **66a4**, the cam springs **75** and cam plates **76** do not permit the rotary pick **76** to be rotated in the counter clockwise direction, because the braking force is larger than the friction between the head block **71** and the claw **66a4** (see FIG. **38E**).

FIGS. **38F** and **38G** illustrate the plunger **70** on way to the upper dead point. However, the cam plates **76** and cam springs **75** prevent the rotary pick **66** from the rotation in the counter clockwise direction. When the plunger **70** reaches the upper dead point, the head block **71** is spaced from the claw **66a4**, which is to be pushed during the next downward motion of the plunger **70**, and the cam springs **75** slightly rotate the rotary pick **66** in the clockwise direction. As a result, the next claw **66a4** slides into the ring space as shown in FIG. **38H**.

The automatic players **20M** have the advantages by virtue of the rotary picks **66**. Moreover, the player's fingers **20M** pluck the associated reeds **61** surer than the player's fingers **20K**, because the head blocks **71** faithfully reciprocate the given trajectories. The brake unit **75/76** not only prevents the rotary pick **66** from the reverse rotation but also keep the claws **66a** at the same position in the ring space **70a** after the spring **69** spaces the head block **71** from the claws **66a**. The magnetic force exerted on the plunger **70** is constant, and the head block **71** exerts the constant force on the claw **66a**. This results in the clear tones at constant loudness.

FIGS. **39**, **40A**, **40B** and **40C** show another musical instrument according to the present invention. The musical instrument largely comprises a tone generator and an automatic player. The tone generator is implemented by a comb-like reed array, and the automatic player includes a controller and player's fingers **20N**. The comb-like reed array, controller and player's fingers are similar to those of the musical instrument shown in FIGS. **24**, **25A**, **25B** and **25C**. For this reason, the component parts are labeled with same references designating corresponding parts shown in those figures without detailed description.

Assuming now that the controller energizes the flat coil **86** shown in FIG. **40A**, the magnetic force is exerted on the flat coil **86** and, accordingly, the swingable arm **88** so as to give rise to the rotation of the swingable arm **88** about the shaft **87** in the counter clockwise direction against the elastic force of the arm spring **89**. The swingable arm **88** starts the rotation at the rest position **88(P0)**, and is moved on the trajectory toward the lower stopper **95**.

The edge **88c** is brought into contact with the claw **92a**, and gives rise to the rotation of the rotary pick **92** in the clockwise direction against the elastic force of the cam springs **93**. Subsequently, the claw **92a**, which is at the opposite position 180 degrees spaced from the claw **92a** pressed by the edge **88c**, is brought into contact with the associated reed **83**, and plucks it. The reed **83** vibrates, and generates the tone. When the swingable arm **88** reaches the lower stopper **95**, the reed **83** is vibrating in the space between the claw **92a** and the next claw **92a** so that the rotary pick **92** does not interfere with the vibrating reed **83**.

When the magnetic force is removed from the flat coil **86**, the arm spring **89** rotates the swingable arm **88** in the clockwise direction. Although the friction between the claw **92a** and the swingable arm **88** urges the rotary pick **92** in the counter clockwise direction, the brake unit **93/96** does not permit the rotary pick **92** from the reverse rotation. The swingable arm **88** reaches the upper stopper **90**, and the cam springs **93** urge the rotary pick **92** in the clockwise direction so that the next claw **92a** enters the notch **88b**.

The musical instrument achieves the advantages by virtue of the solenoid-operated flat actuators FLAT2, rotary picks 92 and brake units 93/96. Moreover, the upper stopper 90 and lower stopper 95 exactly define the upper dead point and lower dead point for the swingable arms 88. The motion of the swingable arms 88 is constant so that a constant force is exerted on the reeds 83.

FIGS. 41A and 41B show another player's finger 200 incorporated in a musical instrument according to the present invention. The player's finger 200 is similar in structure to the player's finger 20I so that the component parts are labeled with same references designating corresponding parts of the player's finger 20I without detailed description.

In the musical instrument, plural player's fingers 200 are disposed in the proximity of the tips of reeds 114, which radially project from a hub 113a. The reeds 114 and hub 113a form in combination a daisy reed wheel 113.

The controller is assumed to energize the solenoid-operated actuator CLY2, current flows through the coil 121, and magnetic field is created. The pusher 122 is inwardly inclined as indicated by 122(P0), and the plunger 126 starts to project upwardly. The pusher 122 is brought into contact with the claw 112a, and gives rise to rotation of the rotary pick 112 in the counter clockwise direction. Another claw 112a warps the reed 114, and escape from the reed 144. Then, the reed 114 vibrates, and generates the tone. The ratchet 115 stops the rotary pick 112. When the elastic force exceeds the magnetic force, the pusher 122 escapes from the claw 112a.

When the pusher 122 reaches the upper dead point 122(P1), the controller removes the magnetic field from the solenoid-operated actuator CLY2 so that any magnetic force is not exerted on the pusher 122. The spring 125 outwardly inclines the pusher 122 as indicated by 122(P2), and the plunger 126 is retracted into the bobbin 123a. When the plunger 126 reaches the lower dead point, the pusher 122 returns to the rest position 122(P3). Thus, the pusher 122 returns to the rest position without any interference with the claw 112a.

The player's fingers 200 achieve all the advantages by virtue of the rotary pick 112, solenoid-operated actuator CLY2 and the daisy reed wheel 113. The player's fingers 20I shown in FIG. 41B do not set any limit to the positions to be occupied. Other player's fingers may be provided over the rotary picks 112.

FIGS. 42A, 42B and 43 show another musical instrument according to the present invention. The musical instrument largely comprises a tone generator and an automatic player. The tone generator is implemented by a comb-like array of reeds 137, and the automatic player includes a controller and player's fingers 20P. The comb-like array 137, controller and player's fingers 20P are similar to the comb-like array 137, controller and player's fingers 20J shown in FIGS. 27A, 27B and 28 so that component parts are labeled with same references designating corresponding parts shown in those figures without detailed description.

Assuming now that the controller energizes the solenoid-operated actuator shown in FIG. 43A, the current flows through the coil 132, and creates magnetic field. Then, the plunger 133 frontward projects from the yoke 131, and the force F2 is transmitted from the plunger 133 through the flexible wire 144 to the pusher 139. The pusher 139 frontward projects from the guide block 145, and is brought into contact with one of the claws 140a. Although the tip of the pusher 139 is deformed (see FIG. 44B), the force F2 gives rise to the rotation of the rotary pick 140 over 90 degrees.

While the rotary pick 140 is rotating, another claw 140a plucks the reed 135 so that the reed 135 vibrates for generating a tone. The claw 140a, which has plucked the reed 135, reaches the position occupied by the claw 140a previously pushed by the pusher 139.

When the controller removes the magnetic field, a return spring (not shown) moves the plunger 133 backwardly, and the plunger 133 is retracted into the yoke 131. The plunger 133 pulls the flexible wire 144 and the pusher 139. The pusher 139 slides on the claw 140a backwardly. However, the ratchet 142 does not permit the rotary pick 140 to rotate in the counter clockwise direction. The tip of the pusher 139 is warped, and returns to the rest position.

The musical instrument achieves the advantages by virtue of the rotary wheel 140 and rotary pick 140. Moreover, the solenoid-operated actuators CYL3 are connected to the pushers 139 by means of the flexible wires 144 so that the manufacturer can locate the base plates 130 and 146 at the optimum positions. Thus, the flexible wires 144 enhance the design flexibility.

The yoke 131 may be separated into yokes, which are incorporated in the solenoid-operated actuators CYL3, respectively. The yoke may be replaced with a pair of plates. In this instance, each of the coils 132 is sandwiched between the plates.

The pusher 139 may be replaced with a reciprocating rod 153 and a foldable arm 154 as shown in FIGS. 45A and 45B. The reciprocating rod 153 and foldable arm 154 are similar to those shown in FIGS. 30A and 30B. Otherwise, a foldable rod 157 may be employed in the player's finger 20P. The foldable rod 157 is similar to that shown in FIG. 30C.

As will be understood from the foregoing description, the musical instruments implementing the third embodiment generate the clear tones through the natural vibrations of the reeds. The controllers make the player's fingers pluck the reeds on the basis of the music data so that the automatic players can answer any user's requests. The structures of the musical instruments enhance the design flexibility.

The reeds are replaceable with another sort of vibrating members such as, for example, strings or tone bars. Although the strings are plucked, the tone bars are beaten with mallets. In this instance, the player's fingers selective beat the tone bars.

Fourth Embodiment

Prototype

FIGS. 46, 47, 48A and 48B show another musical instrument embodying the present invention. The musical instrument is categorized in the music box. The musical instrument largely comprises a tone generator and an automatic player as similar to the first, second and third embodiments. The tone generator is implemented by a comb-like array of reeds 48a, and the automatic player comprises a controller 20Aq and player's fingers 20Q. The comb-like array 48Q of reeds 48a, controller 20Aq and player's fingers 20Q are similar in structure to the array 48 of reeds 48a, controller 20Ab and player's fingers 20E shown in FIGS. 16 and 17. For this reason, component circuits of the controller 20Aq and component parts of the comb-like array 48Q and player's fingers 20Q are labeled with references designating corresponding circuits of the controller 20Ab and corresponding parts of the array 48 and player's finger 20E without detailed description.

Assuming now that a user requests the automatic player to perform a piece of music, the central processing unit 11

sequentially accesses music data codes stored in the memory **13**, and instructs the driver circuit **17** to selectively energize the solenoid-operated flat actuators FLAT1. While the central processing unit **11** is sequentially processing the music data, the central processing unit **11** is assumed to instruct the driver circuit **17** to pluck the reed **48a** shown in FIG. **48A**. The flat coil **44** has not been energized so as to keep the swingable arm **43** horizontal. The tip of the blade **45** stands upright, and is spaced from the rotary pick **46**.

The driver circuit **17** determines the pulse width to be required for the target loudness, and the pulse width modulator PWM supplies the driving signal with the pulse width to be required for the target loudness to the flat coil **44**. When the current flows through the flat coil **44**, the magnetic force is exerted on the flat coil **44**, and gives rise to rotation of the swingable arm **43** in the counter clockwise direction. The blade **45** is brought into contact with the flat back surface **46a1** of the rotary pick **46**, and pushes it. The rotary pick **46** is driven for rotation over 90 degrees as indicated by arrow AR5 (see FIG. **49**), and plucks the reed **48a** with the claw **46** spaced 180 degrees from the claw **46** pushed by the blade **45**. The reed **48a** vibrates as indicated by arrow AR6, and generates the tone. The disk **46b** is spaced from the vibrating reed **48a**, and the claws **46a** are out of the trajectory of the vibrating reed **48a**. Thus, the rotary pick **46** does not interfere with the vibrating reed **48a**.

The driver circuit **20Aq** removes the driving signal from the flat coil **44**. Then, the self weight causes the swingable arm **43**, flat coil **44** and blade **45** to return to the rest position shown in FIG. **33A**. The ratchet **53** prevents the rotary pick **46** from the reverse rotation.

In this instance, the controller **20Aq** selectively energizes the flat coils FLAT1 for plucking the reeds **48a** with the claws **46a**. This means that the plural rotary picks **46** can concurrently pluck the reeds **48a** for producing a chord. The rotary pick **46** is rotated over only the predetermined angle for plucking the reed **48a**. The rotary pick **46** is responsive to quick repetition so that the automatic player can perform any complicated passage.

The solenoid-operated flat actuators FLAT1 give rise to the rotation of the associated swingable arms **43** without any physical contact between the flat coils **44** and the yokes **42** and between the arms **43** and the yokes **42**. The arms **43** and flat coils **44** are less worn out. Thus, the player's fingers **20Q** are durable.

The solenoid-operated flat actuators FLAT1 occupy the space under the reeds **48a**. In other words, the solenoid-operated flat actuators FLAT1 are overlapped with the comb-like reed array **48K**. This results in the compact musical instrument.

The automatic player can perform various passages without changing the hardware. The user needs to load a piece of music data into the memory **13**. Thus, the automatic player can answer all the user's requests in so far as the user prepares the pieces of music data.

The solenoid-operated flat actuators FLAT1 are desirable for the comb-like reed array **48Q**, because the manufacturer can arrange them at small pitches. Even though the reeds **48a** are extremely narrow, the solenoid-operated flat actuators FLAT1 are provided in the proximity of the tips of the reeds **48a**.

The flat coils **44** may be alternated with the yokes **42**. In this instance, the permanent magnet plates **41** are attached to the swingable arms **43**. A large magnet may create a strong magnetic field for all the flat coils **44**.

Modifications

FIGS. **50A** and **50B** show a modification of the player's finger. The player's fingers **20R** are similar to the player's fingers **20F** so that the component parts of the player's finger **20R** are labeled with the component parts of the player's finger **20F** without detailed description.

The guide block **52a** is formed with a pair of guide grooves for upward motion and another pair of guide grooves for downward motion. While the solenoid-operated flat actuator FLAT1 gives rise to the rotation of the arm **43**, the pin **57** is moved along the pair of guide grooves for the upward motion, and the head portion **51b** plucks the reed **48a** for vibrations.

When the pick **51** reaches the upper dead point, the driving signal is removed from the flat coil **44**, and the arm **42** returns to the rest position. The spring **52** makes the pick **51** inclined as indicated by **51(P1)**. The pin **57** enters the pair of guide grooves for the downward motion, and the pin **57** and pair of guide grooves keep the pick **51** inclined. For this reason, the head **51b** does not interfere with the vibrating reed **48a**.

The guide block **52a** and pin **57** keep the trajectory of the pusher **51** stable so that the pusher **51** does not interfere with the vibrating reed **48a**. The player's finger **20F** has the advantages by virtue of the solenoid-operated flat actuators FLAT1.

FIGS. **51**, **52A**, **52B** and **52C** show another musical instrument according to the present invention. The musical instrument largely comprises a tone generator and an automatic player. The tone generator is implemented by a comb-like reed array, and the automatic player includes a controller and player's fingers **20S**. The comb-like reed array, controller and player's fingers **20S** are similar to those of the musical instrument shown in FIGS. **24**, **25A**, **25B** and **25C**. For this reason, the component parts are labeled with same references designating corresponding parts shown in those figures without detailed description.

A pair of cams **96** are fixed to the side surfaces of each rotary pick **92**, and the cam spring **93** is bifurcated so that two spring leaves are pressed to the cams **96**, respectively.

Assuming now that the controller energizes the flat coil **86** shown in FIG. **52A**, the magnetic force is exerted on the flat coil **86** and, accordingly, the swingable arm **88** so as to give rise to the rotation of the swingable arm **88** about the shaft **87** in the counter clockwise direction against the elastic force of the arm spring **89**. The swingable arm **88** starts the rotation at the rest position **88(P0)**, and is moved on the trajectory toward the lower stopper **95**.

The edge **88c** is brought into contact with the claw **92a**, and gives rise to the rotation of the rotary pick **92** in the clockwise direction against the elastic force of the cam springs **93**. Subsequently, the claw **92a**, which is at the opposite position 180 degrees spaced from the claw **92a** pressed by the edge **88c**, is brought into contact with the associated reed **83**, and plucks it. The reed **83** vibrates, and generates the tone. When the swingable arm **88** reaches the lower stopper **95**, the reed **83** is vibrating in the space between the claw **92a** and the next claw **92a** so that the rotary pick **92** does not interfere with the vibrating reed **83**.

When the magnetic force is removed from the flat coil **86**, the arm spring **89** rotates the swingable arm **88** in the clockwise direction. Although the friction between the claw **92a** and the swingable arm **88** urges the rotary pick **92** in the counter clockwise direction, the brake unit **93/96** does not permit the rotary pick **92** from the reverse rotation. The swingable arm **88** reaches the upper stopper **90**, and the cam

springs **93** urge the rotary pick **92** in the clockwise direction so that the next claw **92a** enters the notch **88b**.

The player's finger **20M** plucks the associated reed **61** as shown in FIGS. **38A** to **38H**. FIG. **38A** shows the plunger **71** at the upper dead point, and the claw **66a1** is resting in the ring space **70a**. The controller is assumed to energize the coil **68**. The plunger **70** starts the downward motion against the elastic force of the spring **69**. The inner portion **71a** is brought into contact with the claw **66a1** as shown in FIG. **38B**. However, the claw **66a3** is still spaced from the tip of the reed **61**.

The plunger **70** is further moved downwardly, and gives rise to the rotation of the rotary pick **66** in the clockwise direction. The cam plates **76** are rotated against the elastic force of cum springs **75** exerted on the corners, and the claw **66a3** plucks the reed **61** as shown in FIG. **38C**. The reed **61** vibrates, and generates a tone. The plunger **70** is further moved downwardly, and the rotary pick **66** is rotated in the clockwise direction. However, the next claw **66a2** has not reached the vibrating reed **61**, and the rotary pick **66** does not interfere with the vibrating reed **61** as shown in FIG. **38D**. When the plunger **70** reaches the lower dead point, the next claw **66a2** is still spaced from the vibrating reed **61**.

The magnetic field is removed from the solenoid-operated cylindrical actuator **CYL1**, and the plunger spring **69** urges the plunger **70** in the upward direction. Although the head block **71** pushes the claw **66a4**, the cam springs **75** and cam plates **76** do not permit the rotary pick **76** to be rotated in the counter clockwise direction, because the braking force is larger than the friction between the head block **71** and the claw **66a4** (see FIG. **38E**).

FIGS. **53F** and **53G** illustrate the motion of the rotary pick **92** in detail. FIG. **53A** shows the arm at the rest position. The arm **88** starts to rotate in the counter clockwise direction. The edge **88c** is brought into contact with the claw **92a2** as shown in FIG. **53B**, and pushes the claw **92a2** of the rotary pick **92** as shown in FIG. **53C**. The rotary pick **92** is drive for rotation over the predetermined angle against the elastic force of the cam spring **93**, and plucks the reed **83** with the claw **92a3**. The reed **83** vibrates for generating the tone. The rotary pick **92** stops the rotation, and the reed **83** freely vibrates the gap between the claws **92a3** and **92a2** as shown in FIG. **53D**.

The arm **88** starts to return to the upper dead point as indicated by FIG. **53E**. Although the arm **88** slides on the claw **92a2**, the cam plates **96** and cam spring **93** do not permit the rotary pick **92** to rotate in the counter clockwise direction, and the rotary pick **92** keeps the attitude unchanged as shown in FIGS. **53F** and **53G**. When the arm **88** reaches the upper stopper **90**, the next claw **92a2** is in the space as shown in FIG. **53H**.

As will be understood, the musical instrument has the advantages by virtue of the solenoid-operated flat actuators **FLAT2**. The manufacturer can arrange the reeds at short intervals so that the musical instrument is compact. The arm **88** per se pushes the claws **92a**, and the cam plates/cam spring **93/95** prevent the rotary pick **92** from the reverse rotation. This results in that the reeds **83** are constantly plucked with the claws **92a**. This means that the loudness is exactly controlled.

The solenoid-operated flat actuators **FLAT2** may linearly move plates in the up-and-down direction. The reeds **83** may be replaced with strings or tone bars. In case where the tone bars are employed in a musical instrument, the player's fingers strike the tone bars with mallets or sticks.

FIGS. **54** and **55** show another musical instrument embodying the present invention. The musical instrument is categorized in the music box. The musical instrument also largely comprises a tone generator and an automatic player. The tone generator is implemented by a comb-like reed array **3**. The comb-like reed array **3** has a boss portion **3a** fixed to a block **2**, which in turn is fixed to a base plate **1**. Plural reeds **3b** project from the boss portion **3a** in parallel to one another. The reeds **3b** are designed such that they generate the tones at intervals of semitone. References **3b(d1)**, **3b(d2)**, . . . and **3b(dn)** are individually assigned to the reeds **3b**. The reed **3b(d1)** generates the tone with the pitch name C, and the reed **3b(d2)** generates the tone with the pitch name C#. Thus, the tones of the scale are respectively assigned to the reeds **3b(d1)** to **3b(dn)**.

The automatic player includes a controller **20At** and plural player's fingers **20T**. An electric motor M is shared among the player's fingers **20T** (see FIG. **56**), and one of the particular features of the musical instrument is directed to the electric motor M, with which the cams and cam springs are replaced. The particular feature will be described in detail in conjunction with the structure of the player's fingers **20T**.

The controller **20At** includes a MIDI interface **21**, a bus system **22**, a random access memory **23**, a read only memory **24**, a central processing unit **25** and a driver circuit **26** as shown in FIG. **57**. The MIDI interface **21**, random access memory **23**, read only memory **24**, central processing unit **25** and driver circuit **26** are connected to the bus system **22** so that digital codes are transferred through the bus system **22** between those system components **21/23/24/25/26**.

The random access memory **23** has a capacity large enough to store plural sets of music data codes representative of several pieces of music. Computer programs are stored in the read only memory **24** together with data codes representative of data required for plucking the reeds **3b**. Other sets of music data codes, with which the automatic player performs pieces of music, may be stored in the read only memory **24**. The automatic player may require several minutes for performing a piece of music represented by a set of music data codes. The music data codes specify the pitch of a tone to be generated, touch and timing at which the tone is to be generated, and are called as "note event data".

The central processing unit **25** is responsive to user's instructions given through a manipulating panel (not shown). When a user specifies a piece of music through the manipulating panel, the central processing unit **25** starts to sequentially execute instruction codes of the computer program, and successively fetches the music data codes stored in the random access memory **23** or read only memory **24** in order to the timing. The central processing unit **25** specifies the player's finger **20T** to be actuated on the basis of the piece of music data representative of the pitch and note-on event. The central processing unit **25** informs the driver circuit **26** of the player's finger **20T** to be actuated at the timing at which the tone is to be generated. Another task to be achieved through the sequential execution of the computer program relates to the MIDI interface **21**, and will be hereinafter described.

The MIDI interface **21** is connected to an external MIDI data source (not shown), and receives data codes of a standard MIDI file, by way of example. A detachable memory device such as, for example, a memory card is also connectable to the MIDI interface **21**, and the data codes are supplied from the detachable memory to the MIDI interface

21. The data codes are transferred through the bus system 22 to the random access memory 23, and are stored therein. The central processing unit 25 converts the data codes in the standard MIDI file to other data codes in another format for the musical instrument according to the present invention. The central processing unit 25 stores the data codes in the other format in the random access memory 23, again.

Turning back to FIGS. 54 and 55, each of the player's fingers 20T includes a solenoid-operated flat actuator FLAT4, a swingable arm 8, a spring 9 and a rotary pick 6. Shafts 5/7, a stopper 10 and a base chassis 4 are shared among the player's fingers 20T. The base chassis 4 is spaced from the block 2, and is fixed to the base plate 1. The shaft 5 is rotatably supported by the base chassis 4, and the other shaft 7 is fixedly supported by the base chassis 4. The shafts 5 and 7 extend in parallel to one another in a direction parallel to the virtual line on which the tips of the reeds 3b are rowed up, and the shaft 5 is closer to the tips of the reeds 3b than the other shaft 7. The solenoid-operated flat actuators FLAT4 are disposed between the shafts 5 and 7. The stopper 10 is spaced from the base plate 1 in a direction normal to the upper surface of the base plate 1, and extends in parallel to the shafts 5 and 7 and over the player's fingers 20T.

The rotary picks 6 are arranged on the shaft 5 at short intervals, and the electric motor M has an output shaft coupled to one end of the shaft 5 as will be better seen in FIG. 56. The rotary picks have respective boss portions 6a, which are formed with center holes 6b, respectively, and claws 6c. In this instance, four claws 6c project from each boss portion 6a, and are 90 degrees spaced from one another. The shaft 5 passes through the center holes 6b, and the rotary picks 6 keep themselves spaced from the adjacent rotary picks 6 at the short intervals. However, the rotary picks 6 are never fixed to the shaft 5. While the electric motor M drives the output shaft for rotation, the shaft 5 is rotated together with the output shaft in a direction indicated by arrow AR8 (see FIG. 56), which is corresponding to the clockwise direction in FIG. 55, and urges the rotary picks 6 to rotate together due to the friction between the output surface of the shaft 5 and the inner surfaces of the boss portions 6a. In this instance, the rotary picks 6 and the shaft 5 are made of synthetic resin. However, the rotary picks 6 and shaft 5 may be made of metal or alloy in another musical instrument.

Although the base portion 6a is spaced from the tip of the associated reed 3b, the claws 6c reach the tip of the associated reed 3b so that the rotary pick 3 plucks the reed 3b with the claws 6c. As described hereinafter in detail, the swingable arms 8 give rise to rotation of the associated rotary picks 6 in a direction indicated by arrow AR9, and the rotary picks 6 make the tips of the associated reeds 3b on the rounded surfaces 6d of the claws 6c. The individual rotary picks 6 are labeled with 6(p1), 6(p2), . . . and 6(pn), and the rotary picks 6(p1), 6(p2), . . . and 6(pn) are respectively associated with the reeds 3b(d1), 3b(d2), . . . and 3b(dn).

The swingable arms 8 are rotatably supported by the shaft 7 at the short intervals, and the springs 9 always urge the associated swingable arms 8 in the clockwise direction in FIG. 55. The stopper 10 receives the swingable arms 8, and defines the upper dead points for the swingable arms 8. The elastic force exerted on each swingable arm 8 is larger than the force exerted on the swingable arm 8 due to the friction between the outer surface of the shaft 5 and the inner surface of the associated rotary pick 6. For this reason, even though the shaft 5 is driven for rotation, the springs 9 keep the associated swingable arms 8 at the rest position beneath the stopper 10.

Each of the swingable arm 8 has a head portion 8a, and a notch 8b is formed in the head portion 8a. The notch 8b is so wide that one of the claws 6c of the associated rotary pick 6 can enter the notch 8b. The individual swingable arms 8 are labeled with 8(s1), 8(s2), . . . and 8(sn). The swingable arms 8(s1), 8(s2), . . . and 8(sn) are respectively associated with the rotary picks 6(p1), 6(p2), . . . and 6(pn) and, accordingly, with the reeds 3b(d1), 3b(d2), . . . and 3b(dn).

The solenoid-operated flat actuators FLAT4 include permanent magnet plates 12, yokes 13 and respective flat coils 11. The yokes 13 are taller than the permanent magnet plates 12, and the yokes 13 and permanent magnet plates 12 are alternated with one another. For this reason, a gap takes place between the adjacent two yokes 13, and the swingable arms 8 are respectively assigned to the gaps. The flat coils 11 are fixed to the side surfaces of the associated swingable arms 8, and are moved together with the associated swingable arms 8. The coil 11 is so short that the flat coil 11 is thin enough to be resting in the gap together with the swingable arm without any physical contact with the yokes 13.

Assuming now that the user requests the automatic player to perform a piece of music, the central processing unit 25 accesses the random access memory 23 or read only memory 24, and sequentially fetches the music data codes representative of the tones to be generated. The central processing unit 25 specifies the player's fingers 20T to be actuated, and instructs the driver circuit 26 to energizes the solenoid-operated flat actuators FLAT4 at the appropriate times. The note-on events are defined on the lapse of time from the initiation of the performance, and the controller 20At increments the tempo clocks. When the lapse of time reaches the time at which the note-on event is to occur, the central processing unit 25 instructs the driver circuit 26 to supply the driving signal to the player's finger.

While the automatic player is performing the piece of music, the controller 20At is assumed to energize the solenoid-operated flat actuator FLAT4 shown in FIG. 55. Before the controller 20At energizes the solenoid-operated flat actuator FLAT4, the head portion 8a was in contact with the stopper 10, and the claw 6c1 was rest in the notch 8b as shown in FIG. 58A. The claw 6c1 was held in contact with the lower edge of the head portion 8a. Although the shaft 5 was rotating in the center hole 6b in the rotary pick 6, the moment exerted on the head portion 8a due to the friction was smaller than the moment due to the elastic force of the string, and the shaft 5 was rotating in the center hole 6b of the rotary pick 6.

When the current flows through the flat coil 11, the magnetic force is exerted on the flat coil 11, and the associated swingable arm 8 starts the rotation as indicated by arrow x against the elastic force of the spring 9. The head portion 8a is spaced from the stopper 10, and the edge 8c is brought into contact with the claw 6c1. The head portion 8a pushes the claw 6c1 downwardly, and gives rise to the rotation of the rotary pick 6 in the clockwise direction against the friction between the outer surface of the shaft 5 and the inner surface of the boss portion 6a. The claw 6c3 is brought into contact with the tip of the associated reed 3b, and makes the tip slide on the rounded surface 6d. When the claw 6c3 escapes from the tip of the reed 3b, the reed 3b vibrates for generating the tone as shown in FIG. 58B. The reed 3b is vibrating in the gap between the claw 6c3 and the next claw 6c2 so that the rotary pick 6 does not interfere with the vibrating reed 3b.

When the head portion 8a reaches the lower dead point, the controller 20At removes the magnetic force from the flat coil 11, and the head portion 8a starts to return toward the

rest position. Although the front end surface of the head portion **8a** slides on the rotary pick **6**, the rotating shaft **5** urges the rotary pick **6** in the clockwise direction so that the rotary pick **6** keeps the attitude thereof unchanged as shown in FIG. **58C**.

When the head portion **8a** reaches the rest position, the shaft **5** slightly rotates the rotary pick **6**, and the next claw **6c** enters the notch **8b**.

As will be understood from the foregoing description, the musical instrument has the advantages by virtue of the solenoid-operated flat coils **FLAT4**. The rotary picks **6** are urged by the rotating shaft **5**, and neither ratchet nor combination of cams and cam springs are required for the rotary picks **6**. This results in the simple structure of the player's fingers **20T**.

The player's fingers **20T** may be replaced with player's fingers **20U**. In the player's finger **20U**, the solenoid-operated flat actuator **FLAT** and swingable arm **8** are replaced with a solenoid-operated cylindrical actuator **CYL6** and a plunger head **24a** as shown in FIG. **59**. The solenoid-operated cylindrical actuator **CYL6** includes yoke plates **23a** spaced from each other in an up-and-down direction, a cylindrical coil **22** sandwiched between the yoke plates **23a** and **23b**, a plunger **24** projectable from and retractable into the space defined by the cylindrical coil **22** and a spring **25** urging the plunger **24** upwardly. The plunger head **24a** is connected to the upper end of the plunger **24**, and a ring space **24b** takes place between the plunger **24** and the plunger head **24a**. The spring **26** urges the plunger upwardly so that the plunger head **24a** is held in contact with the stopper **10** in the absence of the magnetic field, and the friction between the outer surface of the shaft **5** and the inner surface of the rotary pick **6** causes the claw **6c** to be in contact with the upper edge of the plunger **24**.

Assuming now that the controller energizes the solenoid operated cylindrical actuator **CYL6**, the plunger **24** is moved downwardly as indicated by **x**, and the plunger head **24a** is brought into contact with the claw **6c**. The plunger head **24a** pushes down the claw **6c**, and gives rise to rotation of the rotary pick **6** in the clockwise direction. Another claw **6c** plucks the reed **3b** so that the reed **3b** vibrates for generating the tone.

When the plunger **24** reaches the lower dead point, the controller removes the magnetic field from the solenoid-operated cylindrical actuator **CYL6**, and the spring **25** makes the plunger **24** project upwardly. Since the rotating shaft **5** exerts the moment on the rotary pick **6**, the rotary pick **6** is never rotated in the counter clockwise direction. Thus, the rotary pick **6** permits the reed **3b** to freely vibrate in the gap between the claws **6c**. When the plunger head **24a** is brought into contact with the stopper **10**, the next claw **6c** enters the ring space for the next plucking.

The solenoid-operated cylindrical actuators **CYL6** may be arranged in two or three stages stacked with one another for preventing the coils **21** from interference. In this instance, the plunger heads **24a** are thinned so that the player's fingers are arranged like the player's fingers **20T**.

The solenoid-operated cylindrical actuators **CYL6** may be arranged in parallel to the base plate **1**. In this instance, the plungers **24** and plunger heads **24a** horizontally project from and are retracted into the yokes for driving the rotary picks **6** for rotation.

The electric motor **M** may intermittently rotate the shaft **5** for keeping the rotary picks **6** stable during the plunger's motion from the lower dead points to the upper dead points.

The solenoid-operated cylindrical actuators **CYL6** may rotate the associated rotary picks **6** during the straight

motion from the lower dead points to the upper dead points. The shaft **5** prevents the rotary picks **6** from the reverse rotation in the straight motion from the upper head points to the lower head points. The plucking with the swingable arms **8** are similarly changed from the counter clockwise direction to the clockwise direction.

The rotary picks **6** may be driven for rotation by the shaft **5** so as to pluck the reeds **3b**. In this instance, the swingable arms **8** stop the rotation of the rotary picks **6** while the reeds **3b** are to be silent.

Although particular embodiments of the present invention have been shown and described, it will be apparent to those skilled in the art that various changes and modifications may be made without departing from the spirit and scope of the present invention.

For example, the boss portion **33a** may have a circular periphery. In this instance, the tips **33c** are arranged on a certain curved line such as an involute line.

The resonator box **43** or both of the resonator box **43** and bell **45** may be attached to one of the music boxes shown in FIGS. **1** to **6D**.

In a multiple music box according to the present invention, all the daisy reed wheels **32** may be assigned a register. The performing boxes **41/141** may play only one part of a piece of music. In this instance, the tones are richer than those of the other music boxes.

The tone generator and automatic player may form parts of a toy, electrical goods or a new sort of musical instrument. The automatic players described hereinbefore may be provided for a harp or another plucking instrument. Tone bars may be used for a musical instrument according to the present invention. In this instance, the automatic player does not pluck the tone bars, but strikes the tone bars.

The music data codes may be supplied from a musical instrument, on which a human player plays a piece of music, to the controller in real time fashion. In this instance, the musical instrument according to the present invention performs a part of the piece of music in ensemble with the other musical instrument.

In the modification shown in FIGS. **17** to **19**, the solenoid-operated flat actuators **FLAT1** may occupy the space over the array **48** of reeds or space in front of the array **48** of reeds. Thus, the manufacturer freely designs the musical instrument. The permanent magnet plates **41** may be fixed to the swingable arms **43**. In this instance, the flat coils **44** are placed between the yokes **42**. Namely, the permanent magnet plates **41** and flat coils **44** are exchangeable. Moreover, plural swingable arms **43** may be assigned to one of the gap between the yokes **43**. In this instance, the permanent magnet plates **41** or flat coils **44** are expected to create strong magnetic field in the gap.

Although the solenoid-operated flat actuators **FLAT1/FLAT2** give rise to rotations of the swingable arms **43/88** in the musical instruments, other solenoid-operated flat actuators may move plates linearly.

What is claimed is:

1. A musical instrument comprising:

a tone generator having vibratory members radially arranged with respect to a center of said tone generator; and

an automatic player selectively generating vibrations of said vibratory members for producing tones different in pitch from one another through said vibrations, and including:

player's fingers arranged in the proximity of outer ends of said vibratory members and responsive to an

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instruction so as to convert energy to said vibrations of said vibratory members, and
 a controller giving said instruction selectively to said player's fingers so as to make the player's fingers start to convert said energy to said vibrations of the associated vibratory members on the basis of pieces of music data that are changeable without changing a physical structure of said controller.

2. The musical instrument as set forth in claim 1, in which said controller concurrently activates more than one player's finger for generating the tones.

3. The musical instrument as set forth in claim 1, in which each of said player's fingers includes

a pick for plucking associated one of said vibratory members,

an actuator connected to said controller so as to be energized by said controller for plucking said associated one of said vibratory members with said pick and an attitude controller connected to said pick and changing said pick between a plucking attitude for plucking said associated one of said vibratory members and a shunt position for passing beside said associated one of said vibratory members without any interference with said vibrations.

4. The musical instrument as set forth in claim 3, in which said attitude controller includes an offset yoke of a solenoid-operated actuator serving as said actuator so that said pick is inclined toward said associated one of said vibratory members while a plunger of said solenoid-operated actuator is moving said pick to said associated one of said vibratory members for plucking, said attitude controller further includes an elastic member connected to said pick so that said pick is oppositely inclined while said plunger is making said pick spaced from the vibrating vibratory member.

5. The musical instrument as set forth in claim 1, in which said vibratory members are reeds.

6. The musical instrument as set forth in claim 1, in which said vibratory members are strings.

7. The musical instrument as set forth in claim 1, in which said tone generator and said player's fingers form a playing unit, and more than one playing unit is combined together for producing the tones under the control of said controller.

8. The musical instrument as set forth in claim 7, further comprising a resonator connected to said more than one playing unit for enlarging the loudness of said tones.

9. The musical instrument as set forth in claim 1, further comprising holders each having a portion at which one of said vibratory members is fixed and a space where one of said player's fingers is accommodated for generating said one of said vibratory members.

10. The musical instrument as set forth in claim 3, each of said player's fingers further includes a guide for spacing said pick from associated one of said vibratory members after generating said vibrations therein.

11. The musical instrument as set forth in claim 10, in which said guide has a pin fixed to said pick and a guide block formed with a first passage for guiding said pin during a first motion of said pick for generating said vibrations and a second passage for guiding said pin during a second motion of said pick for returning to a rest position.

12. The musical instrument as set forth in claim 3, in which said pick has a boss rotatably supported by a member stationary with respect to said actuator and claws radially projecting from said boss at intervals, and in which said actuator gives rise to rotation over a predetermined angle for plucking said associated one of said vibratory members with one of said claws.

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13. The musical instrument as set forth in claim 1, further comprising a housing accommodating said tone generator and said automatic player so that said tone generator, said automatic player and said housing form in combination a music box.

14. A musical instrument comprising:

a tone generator having an array of vibratory members for generating tones different in pitch from one another through vibrations; and

an automatic player including:

player's fingers responsive to an instruction so as to convert energy to said vibrations of said vibratory members, and

a controller giving said instruction selectively to said player's fingers so as to make the player's fingers start to convert said energy to said vibrations of the associated vibratory members on the basis of pieces of music data that are changeable without changing a physical structure of said controller,

each of said player's fingers having a rotary vibration generator rotatably supported by a stationary member in the proximity of associated one of said vibratory members for generating said vibrations through rotation thereof and an actuator connected to said controller and selectively energized by said controller for rotating said rotary vibration generator.

15. The musical instrument as set forth in claim 14, in which said controller concurrently activates more than one player's finger for generating the tones.

16. The musical instrument as set forth in claim 14, in which said rotary vibration generator has a boss portion rotatably supported by said stationary member and plural claws radially projecting from said boss at intervals.

17. The musical instrument as set forth in claim 16, in which said vibratory members project from a boss portion of said array in parallel to one another, and said rotary vibration generators are respectively provided in the proximity of tips of said vibratory members.

18. The musical instrument as set forth in claim 17, in which the actuators and said array of vibratory members are overlapped with one another, and said actuators selectively rotate the associated rotary vibration generators over a predetermined angle for plucking said tips of said vibratory members under the control of said controller.

19. The musical instrument as set forth in claim 16, in which said actuators have array of magnetic plates and yokes alternated with one another for forming gaps between said yokes, respective arms having first end portions rotatably connected to a stationary member, respective flat coils respectively attached to said arms and connected in parallel to said controller, and respective blades connected at second ends of said arm opposite to said first ends and projecting toward said rotary vibration generators for selectively pushing said claws while said arms are rotating about said stationary member.

20. The musical instrument as set forth in claim 15, in which said actuator includes a movable member for rotating said rotary vibration generator, a flexible wire connected at one end thereof to said movable member and a power generating unit connected to the other end of said flexible wire for exerting a force on said movable member through said flexible wire.

21. The musical instrument as set forth in claim 14, in which said array of vibratory members is formed in a daisy reed wheel having vibratory reeds radially projecting from a boss portion, and said player's fingers are arranged outside of said daisy reed wheel.

22. The musical instrument as set forth in claim 21, in which said rotary vibration generator has a boss portion and plural claws radially projecting from said boss portion at intervals, and the rotary vibration generators are provided around said daisy reed wheel for plucking said reeds with the claws.

23. The musical instrument as set forth in claim 14, further comprising a housing accommodating said tone generator and said automatic player so that said tone generator, said automatic player and said housing form in combination a music box.

24. The musical instrument as set forth in claim 14, in which said each of said player's fingers further has a back stop so as to permit said rotary vibration generator to unidirectionally rotate.

25. The musical instrument as set forth in claim 24, in which said back stop is formed by a ratchet.

26. The musical instrument as set forth in claim 24, in which said back stop is formed by a cam plate fixed to said rotary vibration generator and a cam spring pressed to said cam.

27. The musical instrument as set forth in claim 24, in which said back stop includes a shaft loosely passing through the rotary vibration generators and a motor connected to said shaft and unidirectionally rotating for urging said vibration generators.

28. A musical instrument comprising:

a tone generator having an array of vibratory members for generating tones different in pitch from one another through vibrations; and

an automatic player including player's fingers for selectively generating said vibrations in said vibratory members and a controller connected to said player's fingers for selectively actuating said player's fingers on the basis of pieces of music data variable without changing a physical structure of said controller,

each of said player's fingers including

a vibration generator moved from a rest position along a first path for generating said vibrations in associated one of said vibratory members and a second path for returning to said rest position,

an actuator connected to said controller and moving said vibration generator along said first path and said second path, and

a route changer connected to said vibration generator for guiding said vibration generator to said second path after generating said vibrations so as to permit the associated vibratory member to freely vibrate without any interference due to said vibration generator passing beside said associated vibratory member along said second path.

29. The musical instrument as set forth in claim 28, in which said route changer includes a magnetic field generator for forcing said vibration generator to said first path and an elastic member for forcing said vibration generator to said second path.

30. The musical instrument as set forth in claim 29, in which said magnetic field generator exerts a magnetic force larger than an elastic force of said elastic member on said vibration generator from a rest position to a certain position in said first path, and makes said magnetic force smaller than said elastic force after the generation of said vibration in said first path.

31. The musical instrument as set forth in claim 28, in which said route changer further includes a guide block

having a hollow space partially serving as said first path and partially serving as said second path.

32. The musical instrument as set forth in claim 31, in which said route changer further includes a guide pin fixed to said vibration generator, and said guide block is formed with a first groove slidably receiving said guide pin for guiding said vibration generator along said first path and a second groove slidably receiving said guide pin for guiding said vibration generator along said second path.

33. The musical instrument as set forth in claim 32, in which said first groove is connected to a certain portion of said second groove, and said second groove is connected to another certain portion of said first groove, said certain portion and said another certain portion respectively preventing said vibration generator from entering into said first path and said second path so that said vibration generator is moved along said first path, enters said second path over said certain portion, moved along said second path and enters said first path over said another certain portion.

34. The musical instrument as set forth in claim 28, in which said route changer includes a rotatable disc, and said vibration generator includes claws radially projecting from said rotatable disc at intervals, said rotatable disc causes one of said claws to enter said first path through a rotation over a certain angle and said second path through a further rotation over another certain angle.

35. A musical instrument comprising:

a tone generator having vibratory members radially arranged with respect to a center of said tone generator; and

an automatic player selectively generating vibrations of said vibratory members for producing tones different in pitch from one another through said vibrations, said automatic player comprising:

player's fingers arranged in the proximity of outer ends of said vibratory members and respectively associated with said vibratory members, and

a controller connected to said player's fingers for selectively and electrically actuating said player's fingers on the basis of pieces of music data that are changeable without changing a physical structure of said controller.

36. A musical instrument comprising:

a tone generator having an array of vibratory members for generating tones different in pitch from one another through vibrations; and

an automatic player comprising:

player's fingers respectively associated with said vibratory members for selectively generating said vibrations in said vibratory members, and

a controller connected to said player's fingers for selectively and electrically actuating said player's fingers on the basis of pieces of music data that are changeable without changing a physical structure of said controller,

each of said player's fingers having a rotary vibration generator rotatably supported by a stationary member in the proximity of associated one of said vibratory members for generating said vibrations through rotation thereof and an actuator connected to said controller and selectively and electrically energized by said controller for rotating said rotary vibration generator.