

US006917198B2

(12) **United States Patent**
Johnson et al.

(10) **Patent No.:** **US 6,917,198 B2**
(45) **Date of Patent:** **Jul. 12, 2005**

(54) **HYBRID HALL VECTOR MAGNETOMETER**

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(*) Notice: Subject to any disclaimer, the term of this patent is extended or adjusted under 35 U.S.C. 154(b) by 0 days.

(21) Appl. No.: **10/857,368**

(22) Filed: **May 21, 2004**

(65) **Prior Publication Data**

US 2004/0217756 A1 Nov. 4, 2004

Related U.S. Application Data

(62) Division of application No. 10/287,876, filed on Nov. 4, 2002, now Pat. No. 6,800,913.

(51) **Int. Cl.**⁷ **G01R 33/07**

(52) **U.S. Cl.** **324/251**; 435/4; 324/243

(58) **Field of Search** 435/4; 324/244, 324/246, 249, 251, 260–261, 242, 243

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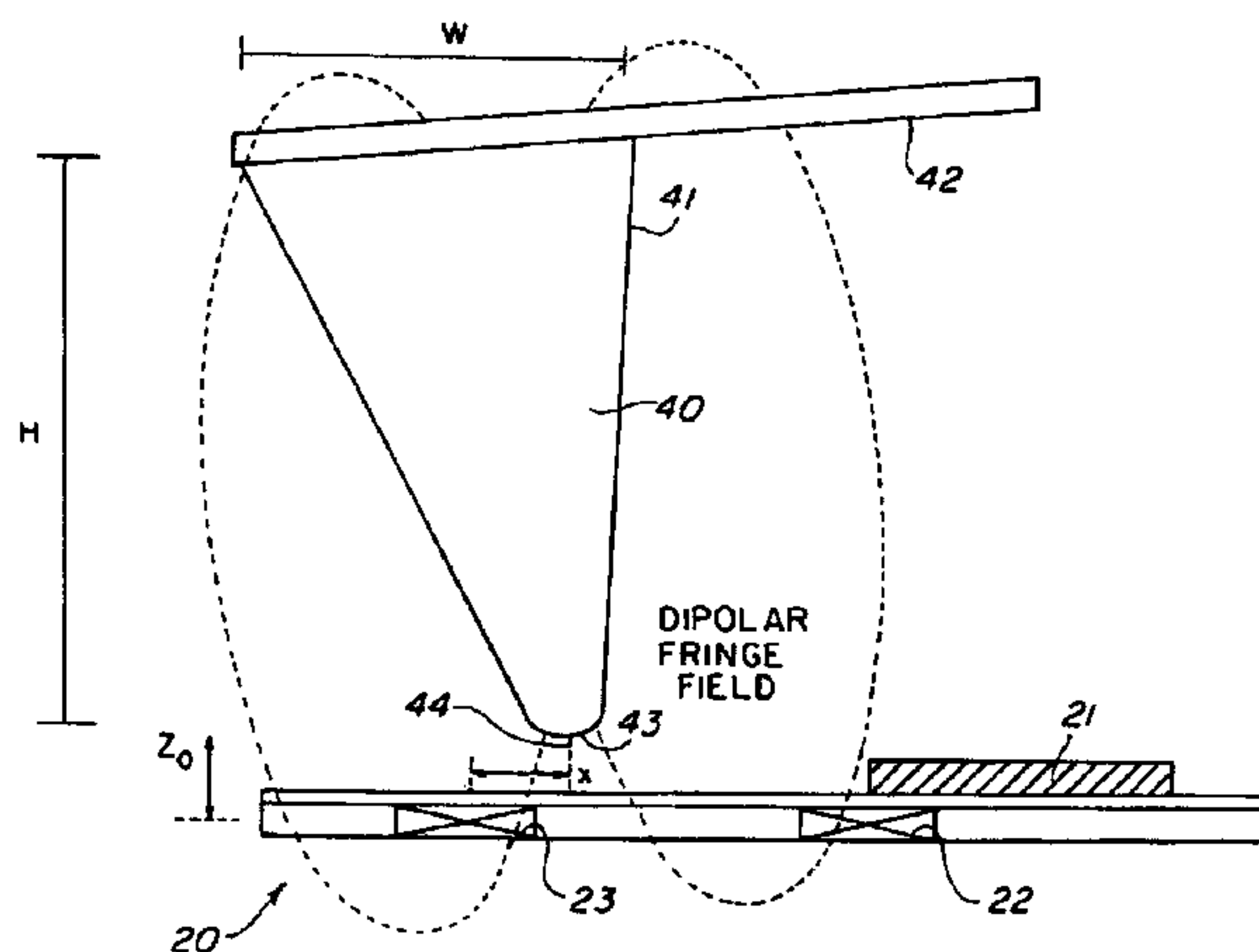
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(57) **ABSTRACT**

A modified hybrid Hall effect device is provided which is the combination of a conventional Hall effect device and a second Hall effect device having a Hall plate coupled to a ferromagnetic layer. The hybrid Hall effect device can be used to determine the independent magnetic field vector components comprising a vector magnetic field, such as for determining the \hat{x} and the \hat{z} components of a magnetic field, or for measuring the total magnitude of a vector magnetic field of any orientation. The modified Hall Effect device can be adapted for use as a magnetic field sensor for the detection of macroscopic objects that have associated magnetic fields, or for microscopic objects that have been tagged by microscopic magnetic particles. In one specific form, a plurality of hybrid Hall devices are electrically connected together to form an array in which a plurality of rows of hybrid Hall devices are electrically coupled to each other along a current axis, and the array is used for the detection of microscopic objects.

8 Claims, 14 Drawing Sheets



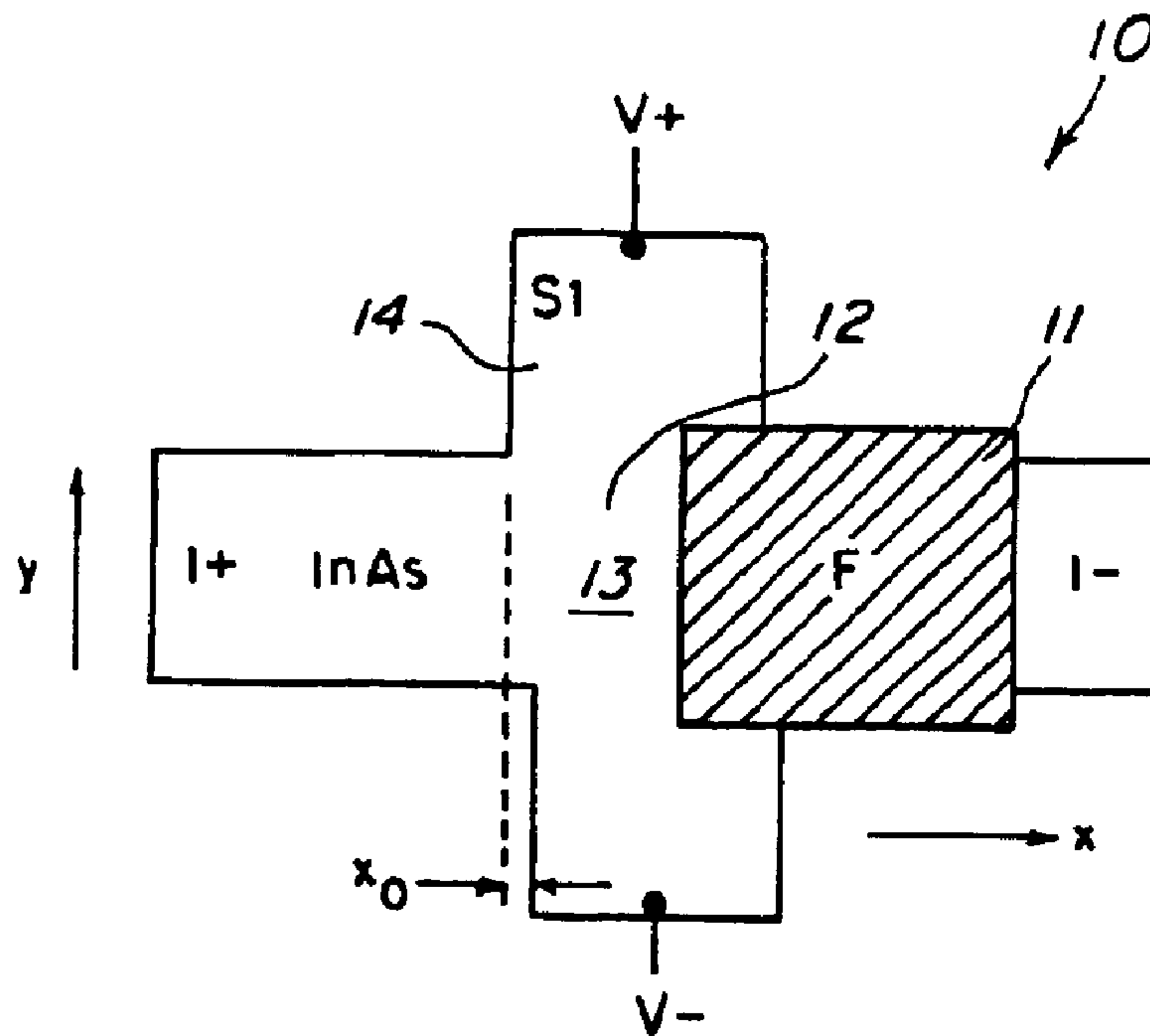


FIG. 1(a)
PRIOR ART

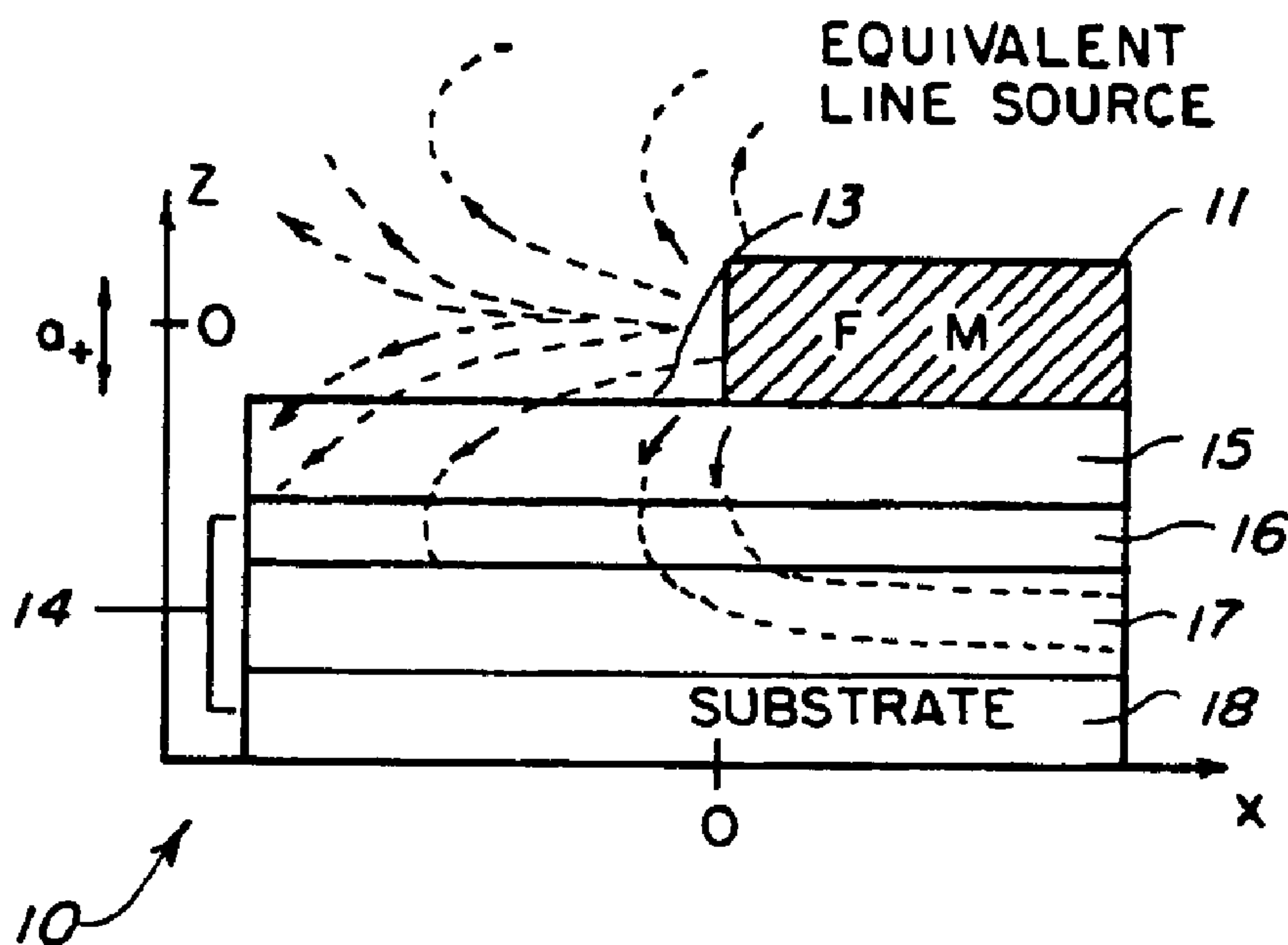


FIG. 1(b)

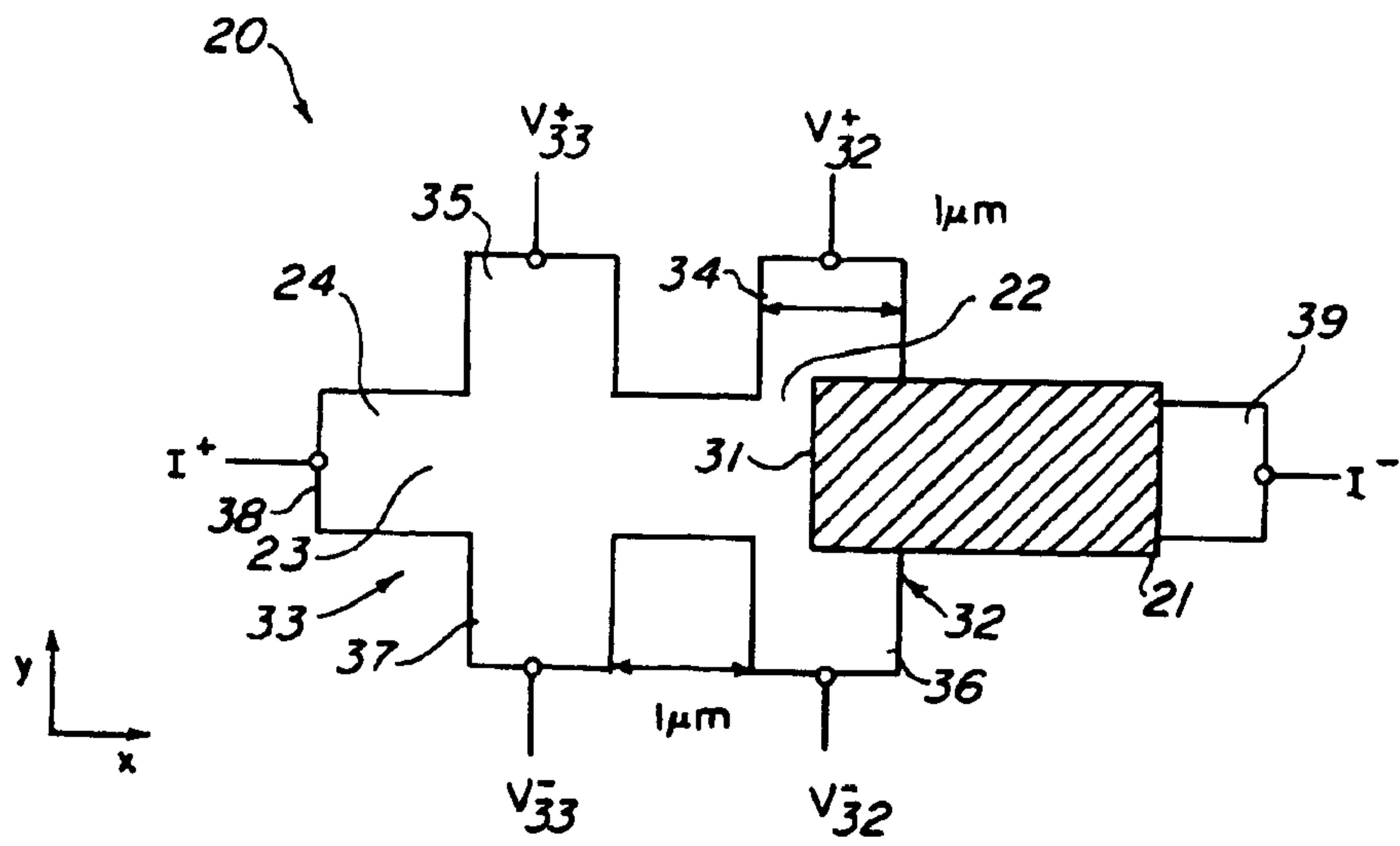


FIG. 2(a)

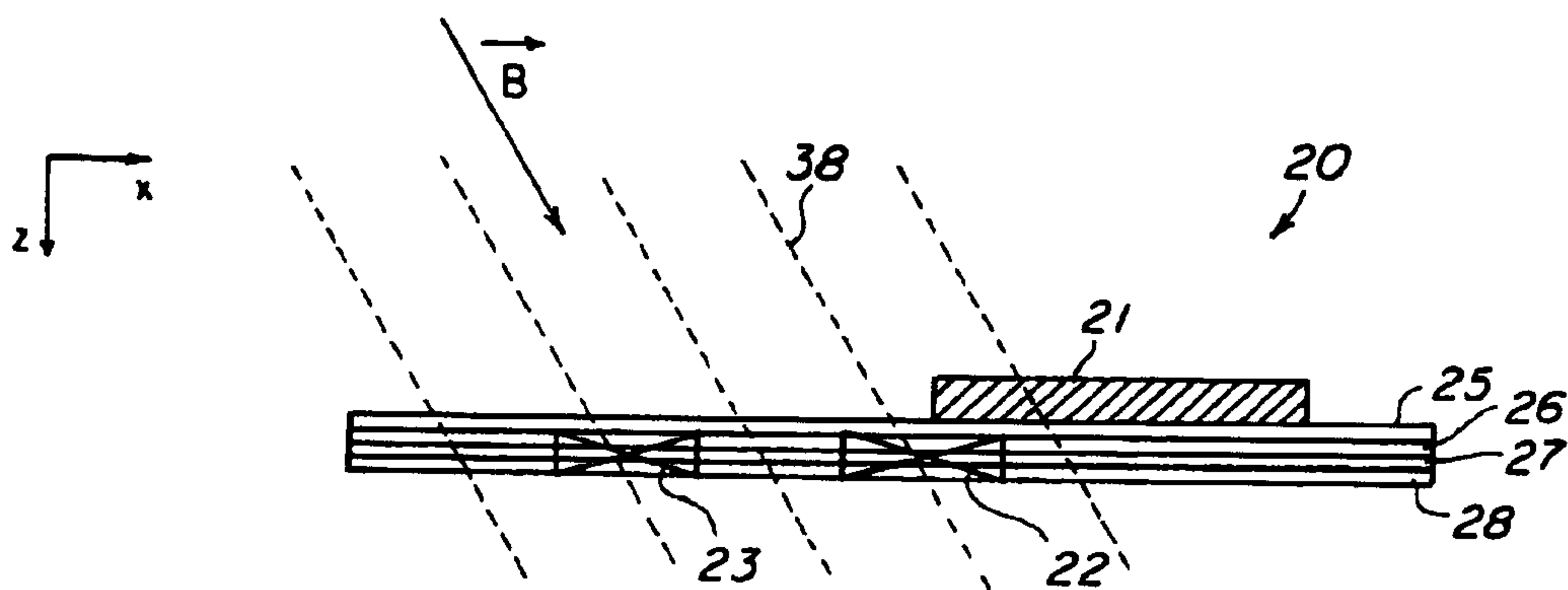


FIG. 2(b)

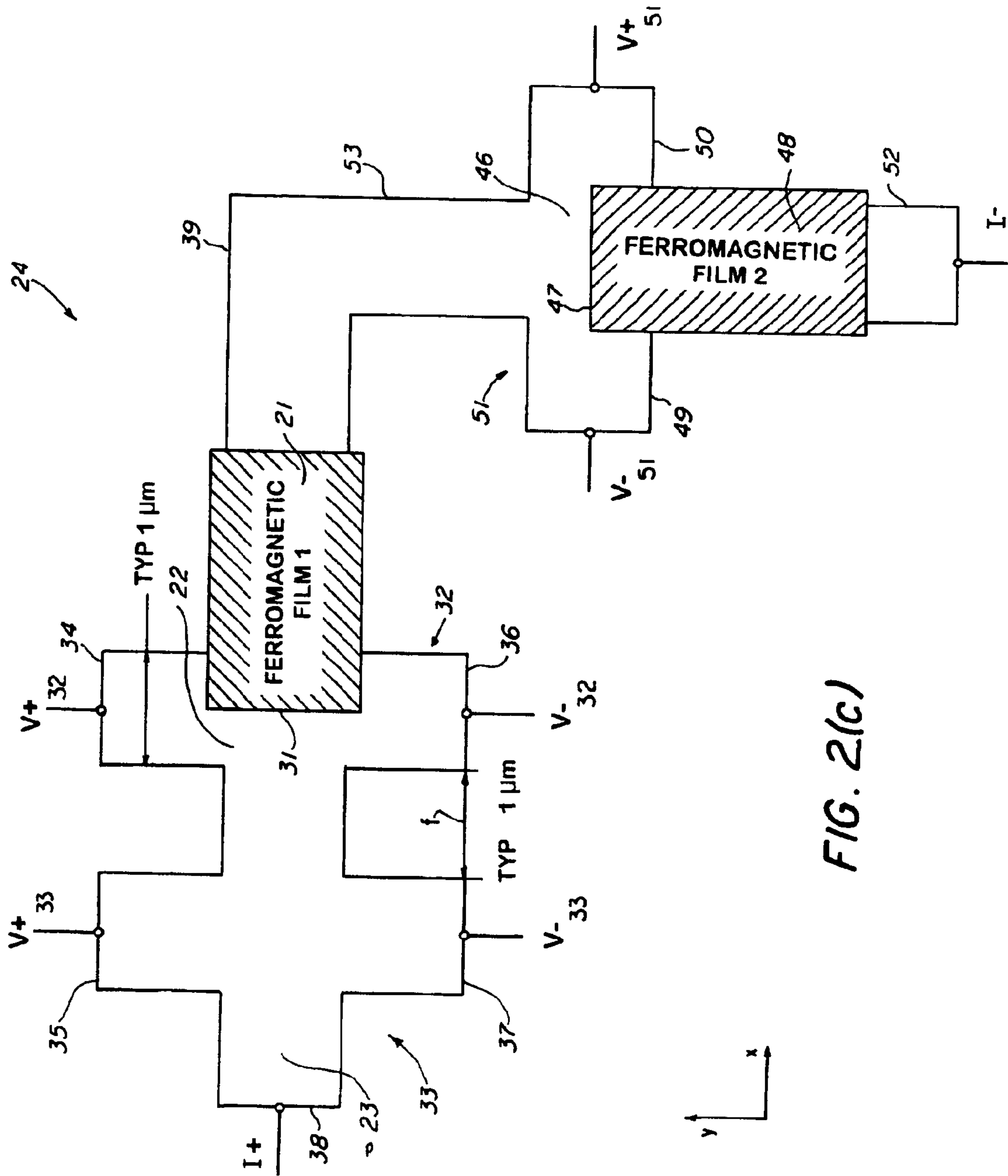


FIG. 2(c)

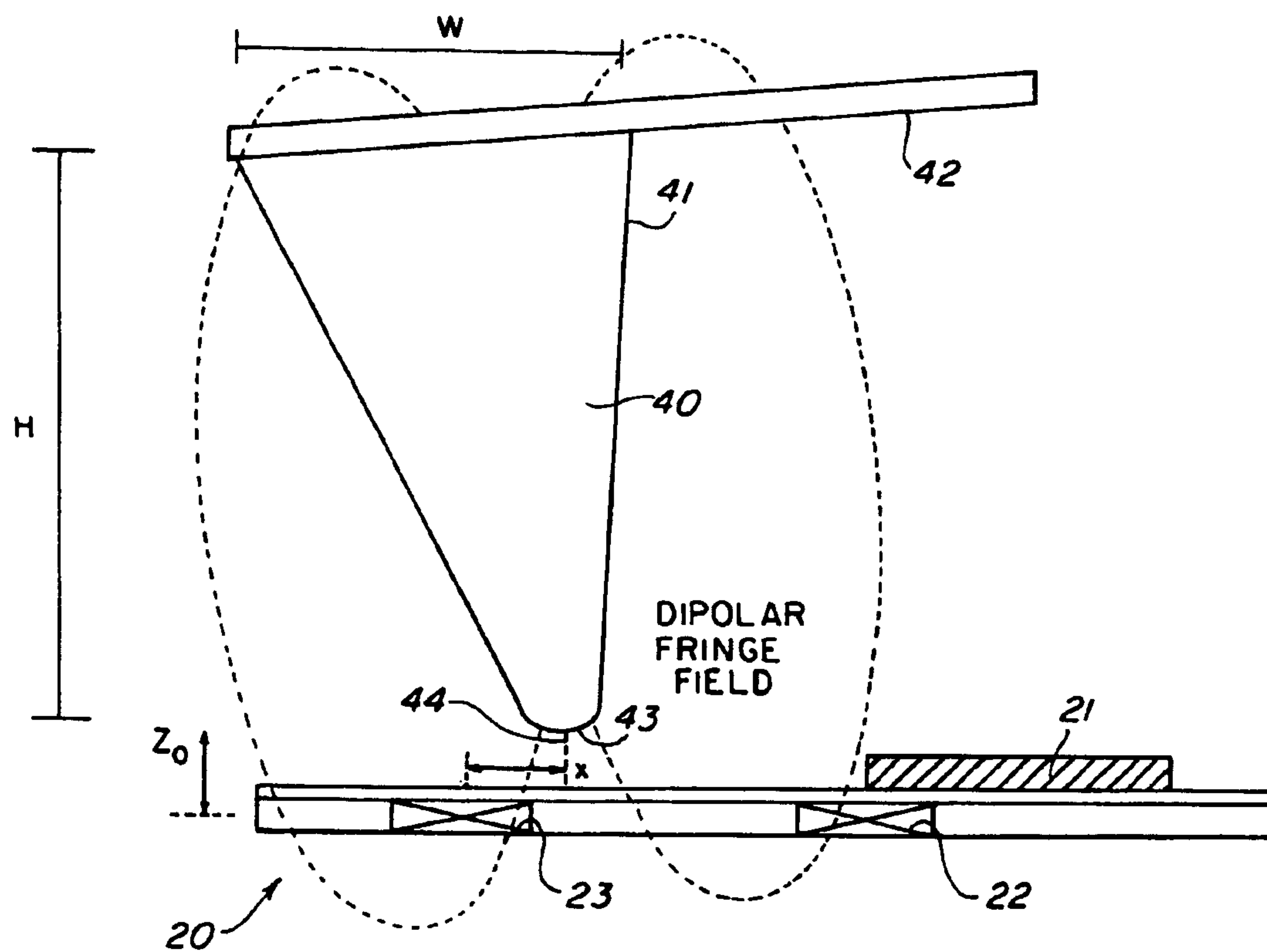


FIG. 3

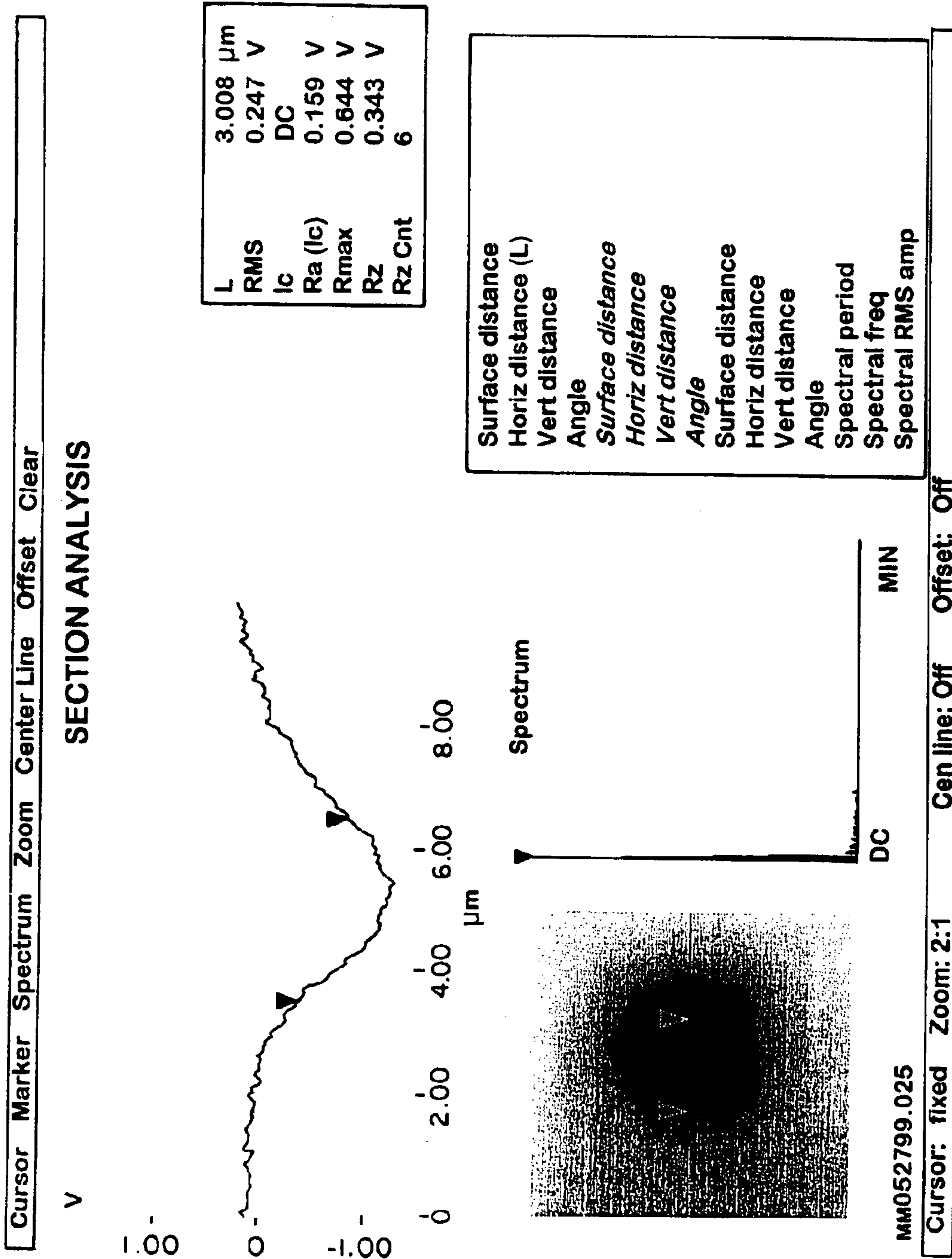


FIG. 4(a)

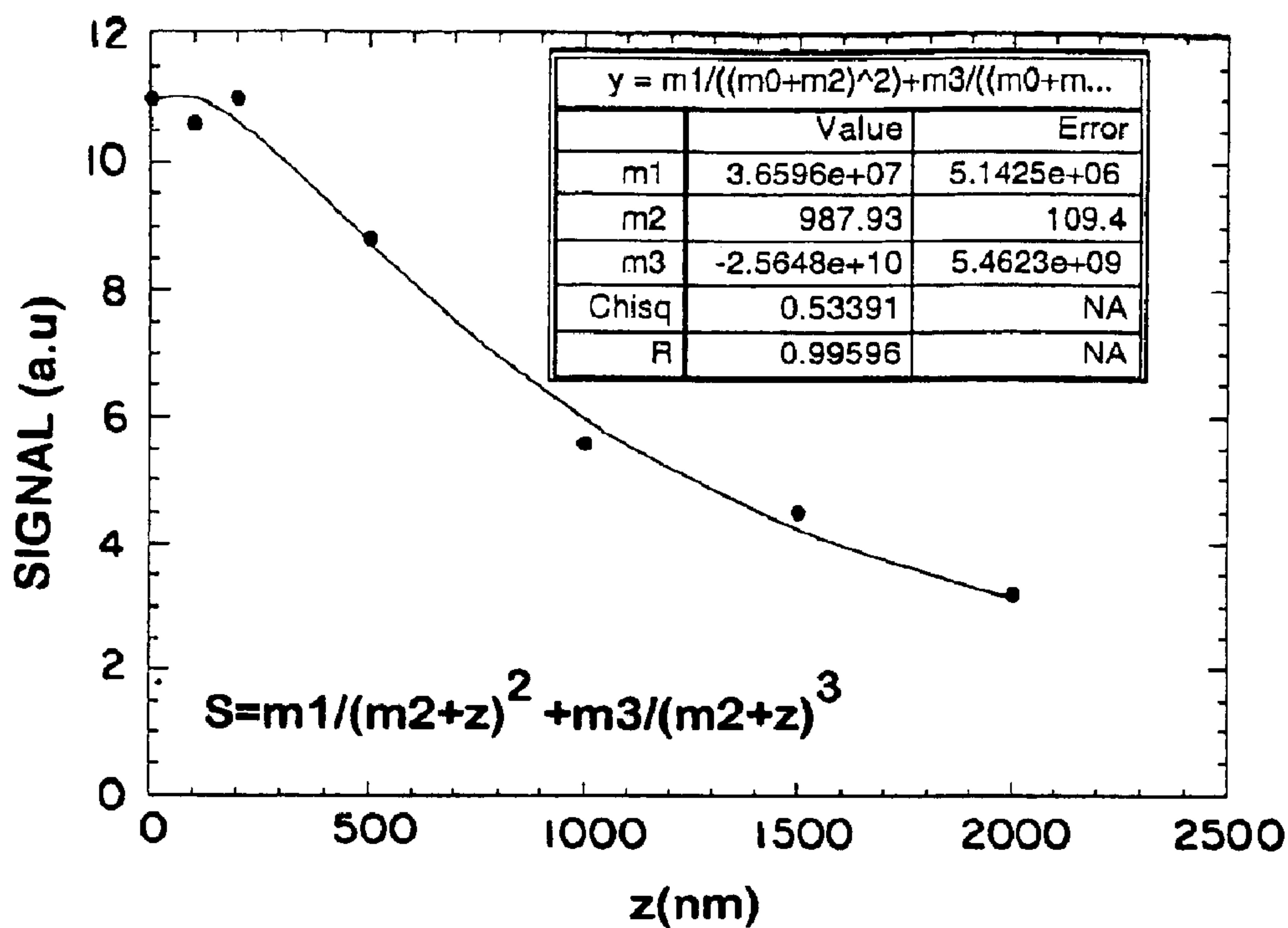


FIG. 4(b)

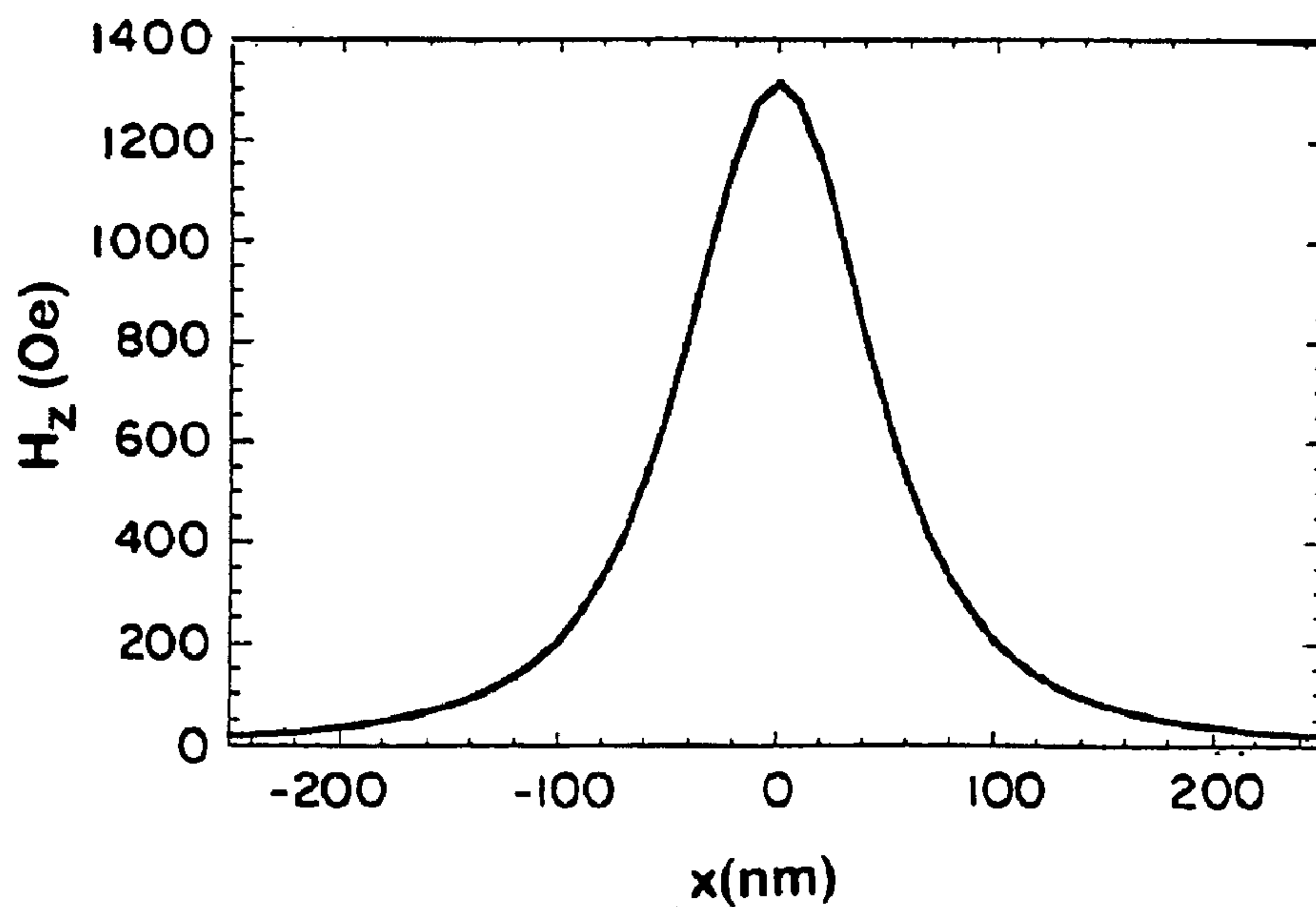


FIG. 4(c)

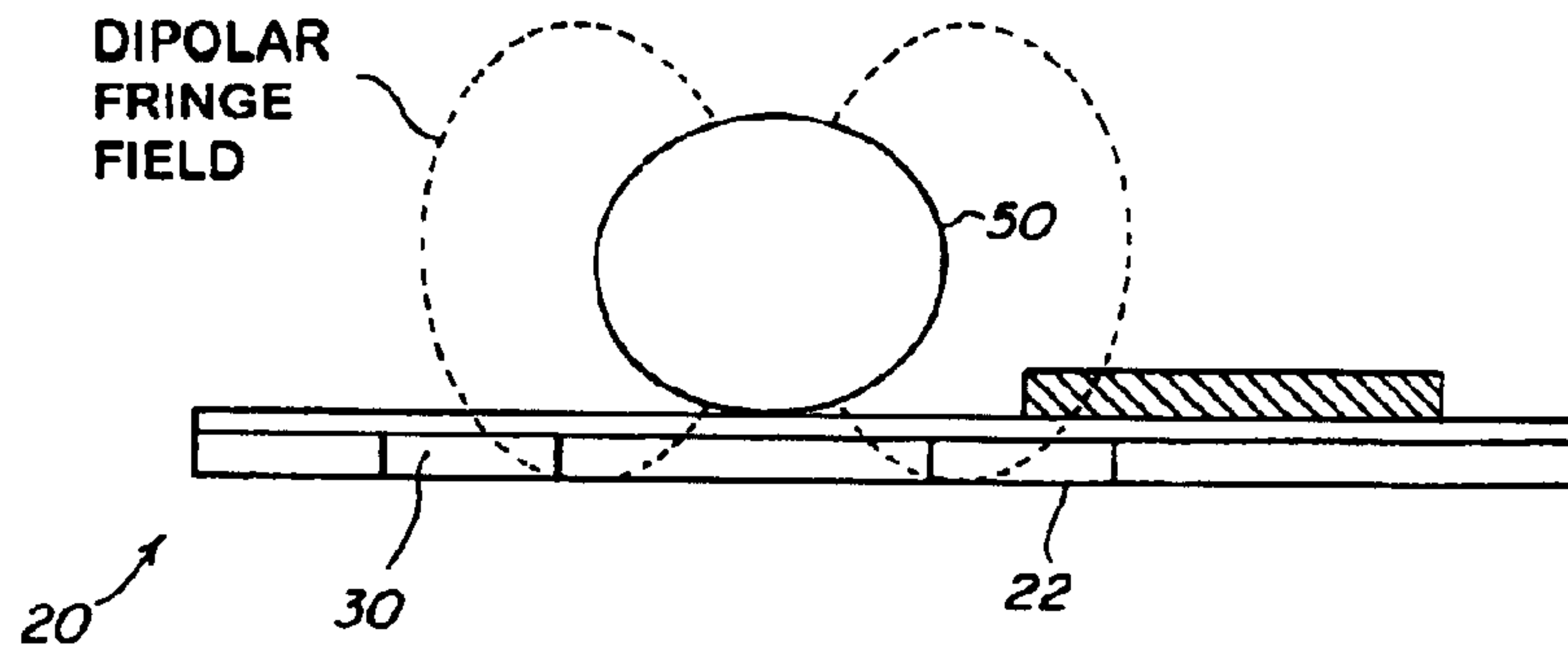


FIG. 5

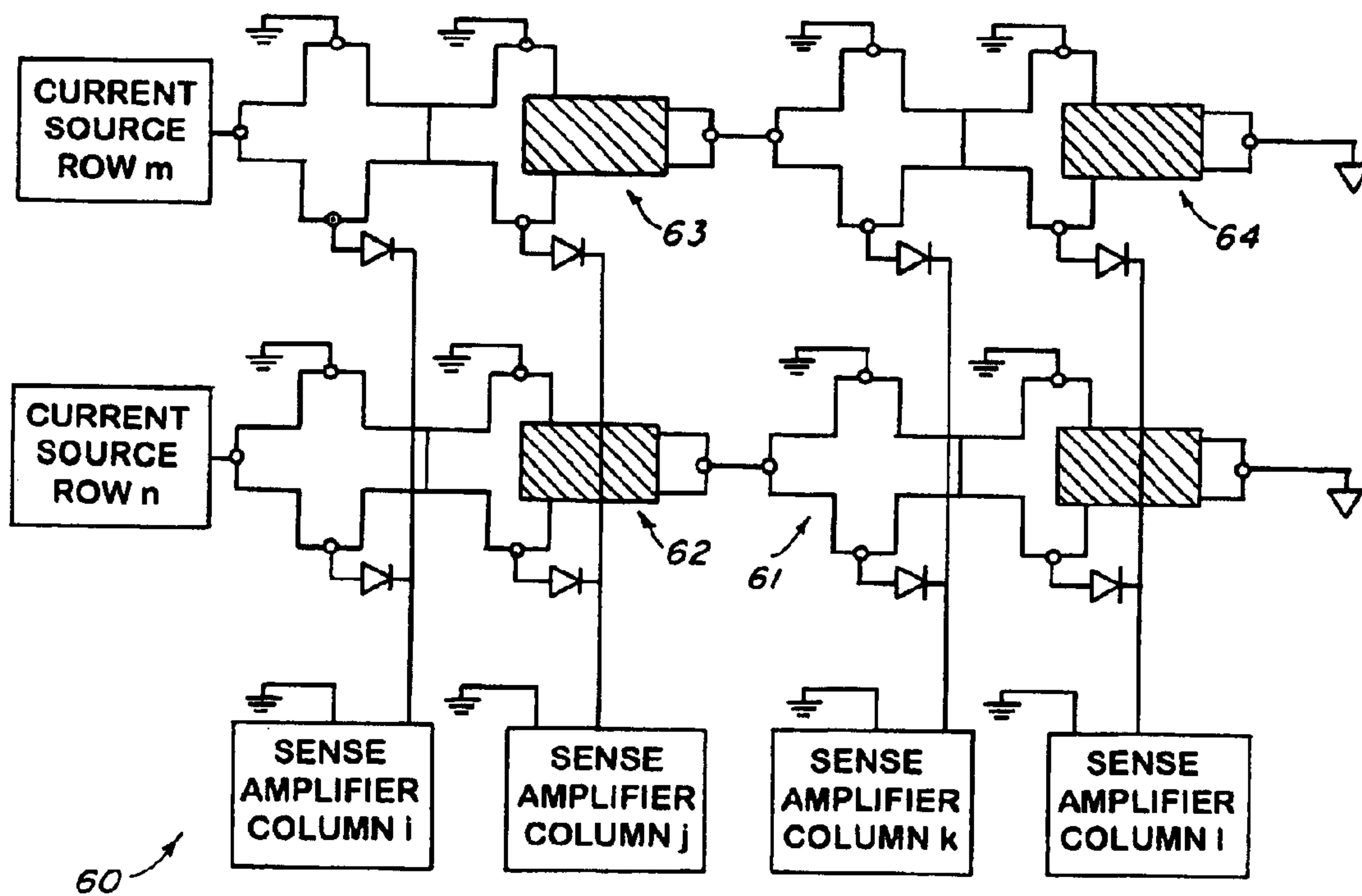


FIG. 6(a)

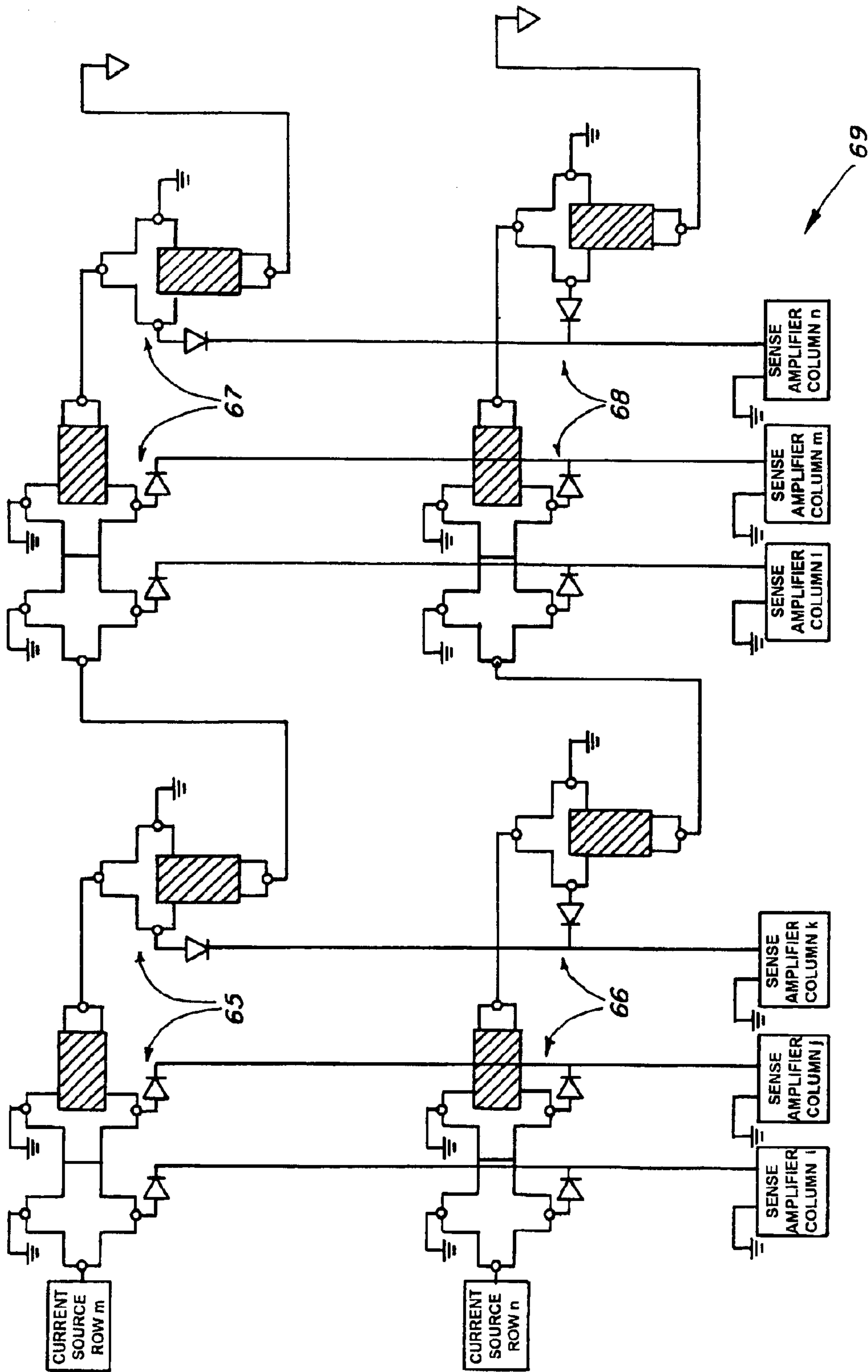


FIG. 6(b)

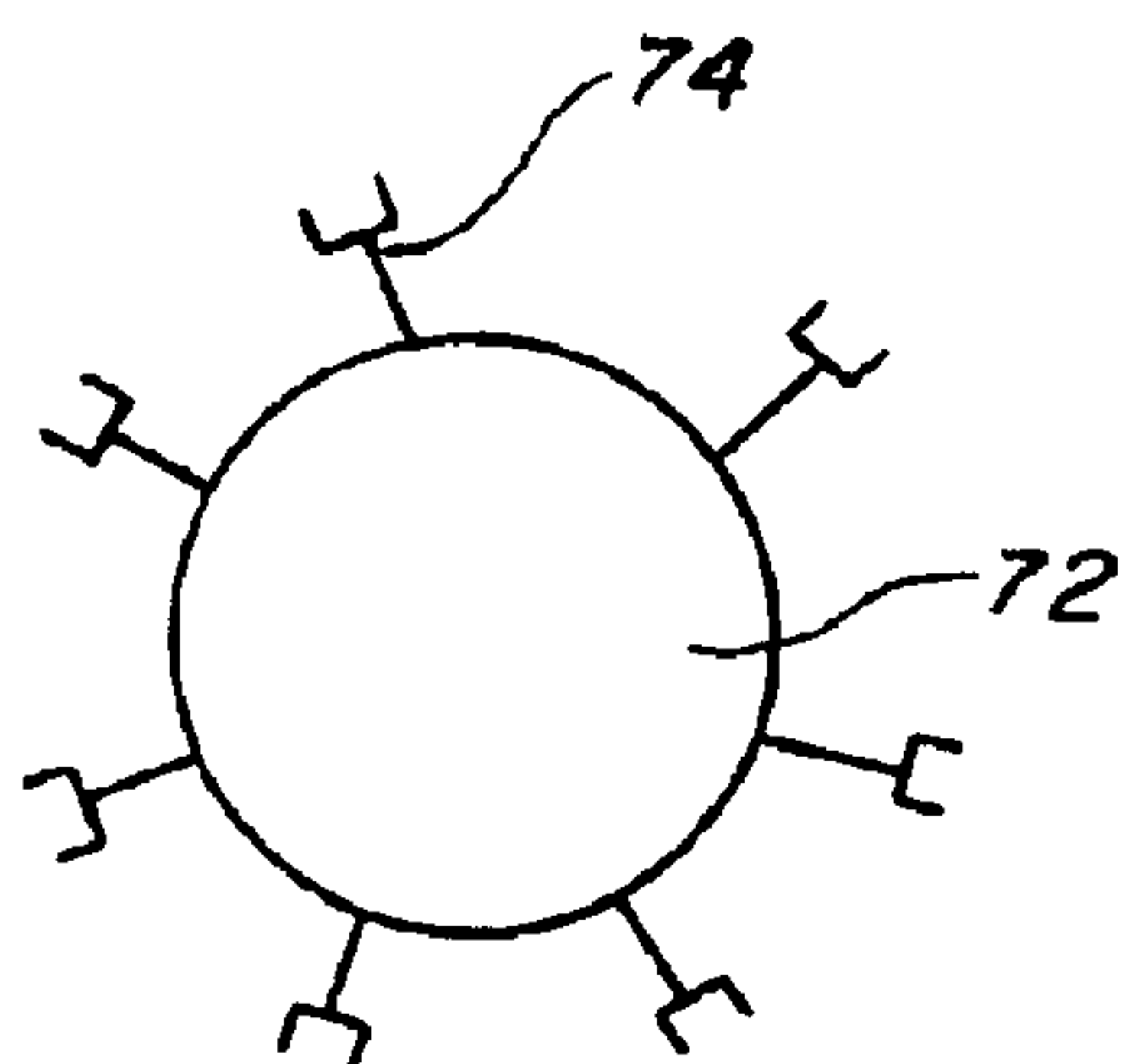


FIG. 7(a)

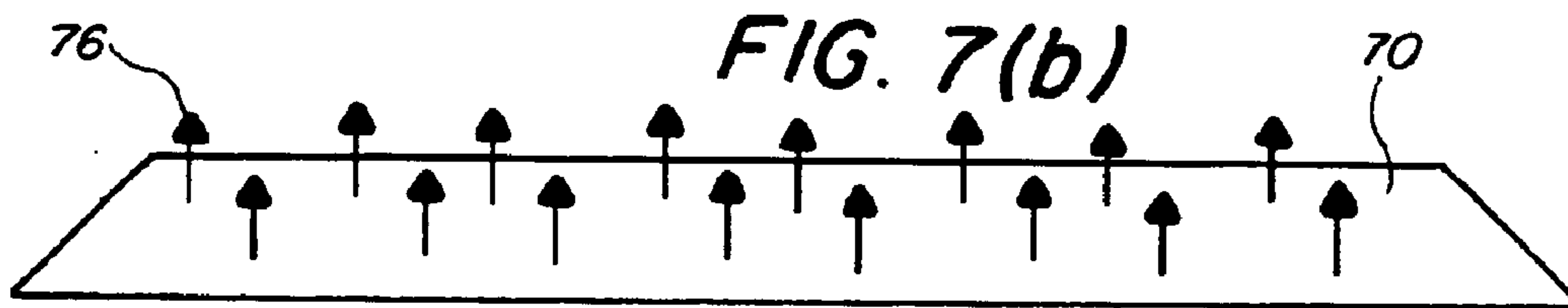


FIG. 7(b)

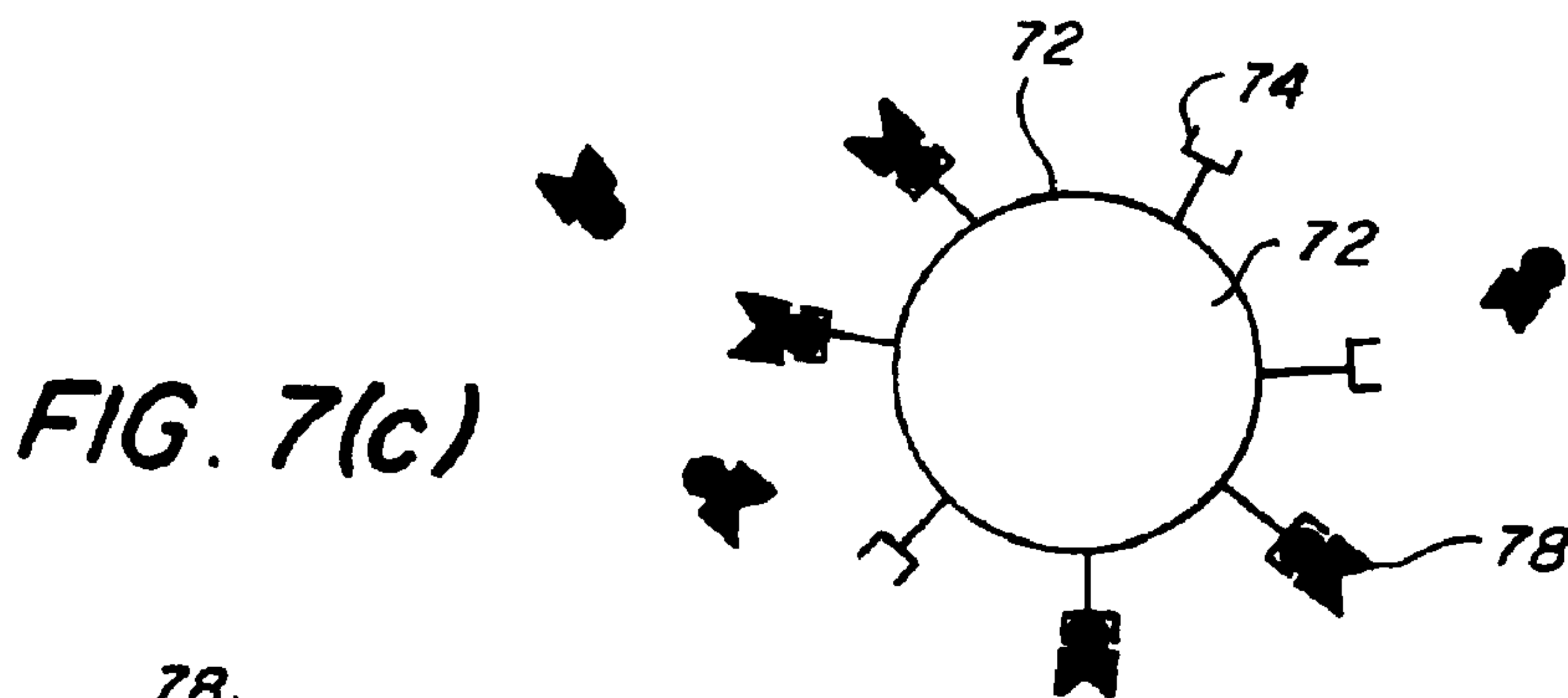


FIG. 7(c)

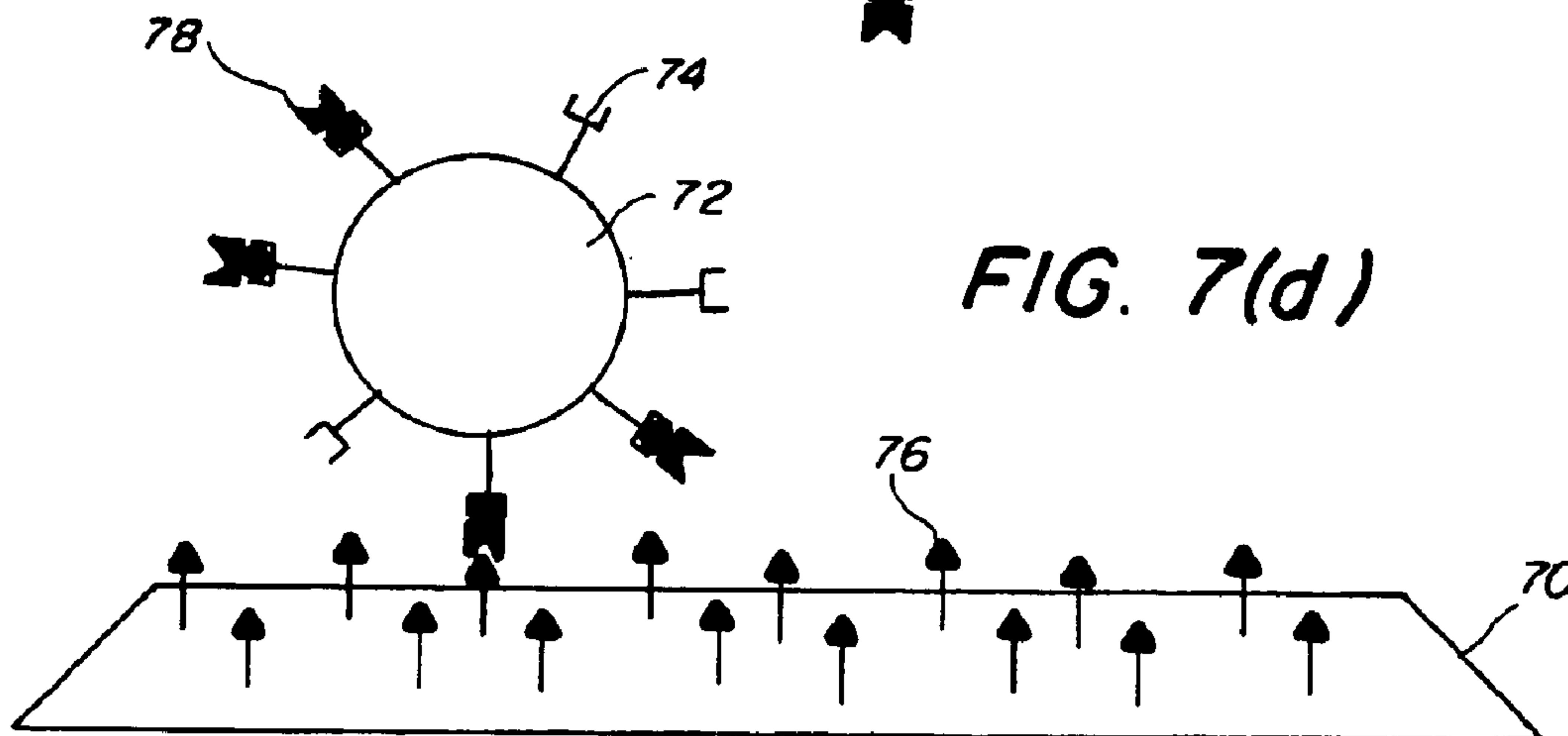


FIG. 7(d)

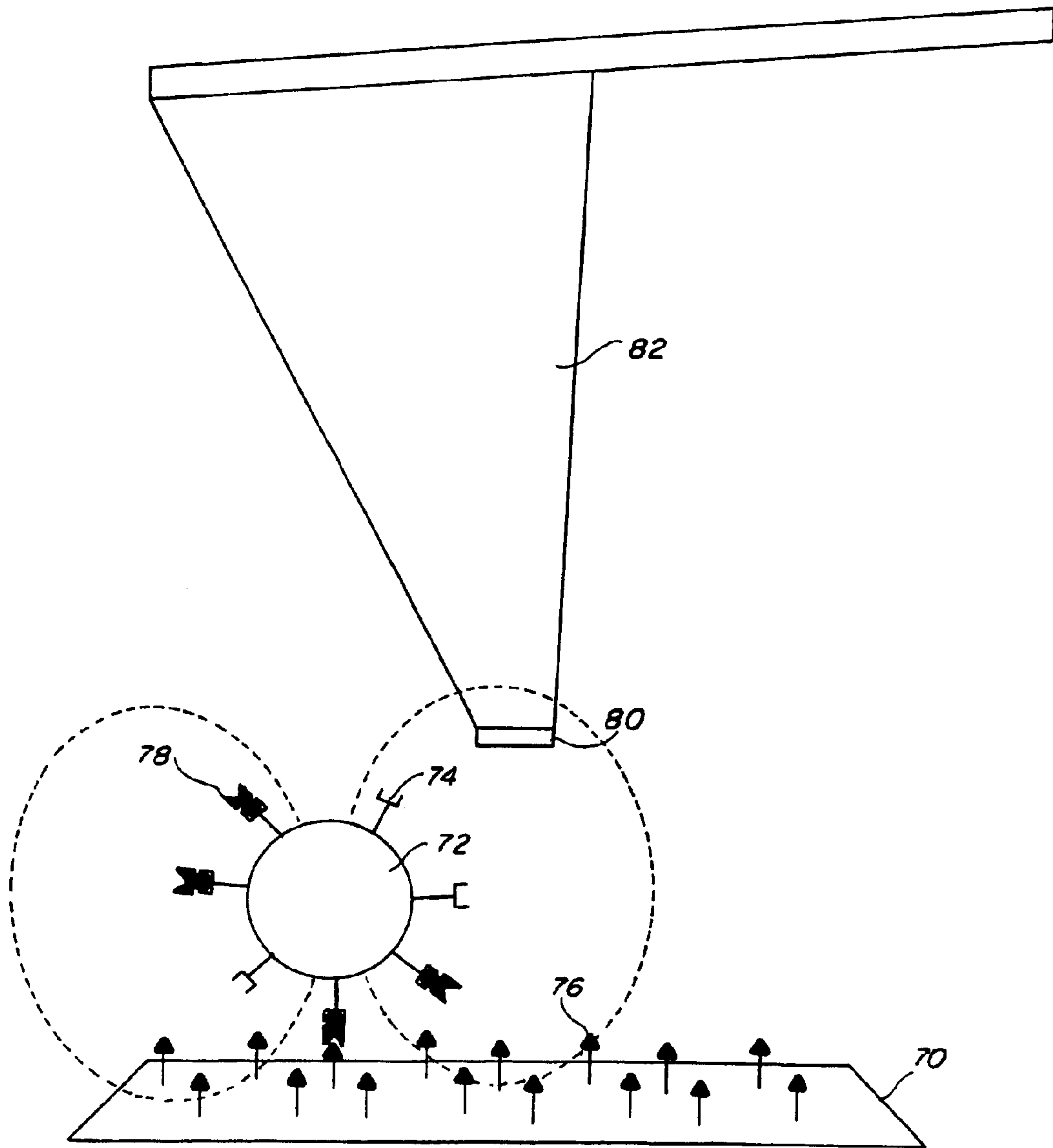


FIG. 7(e)

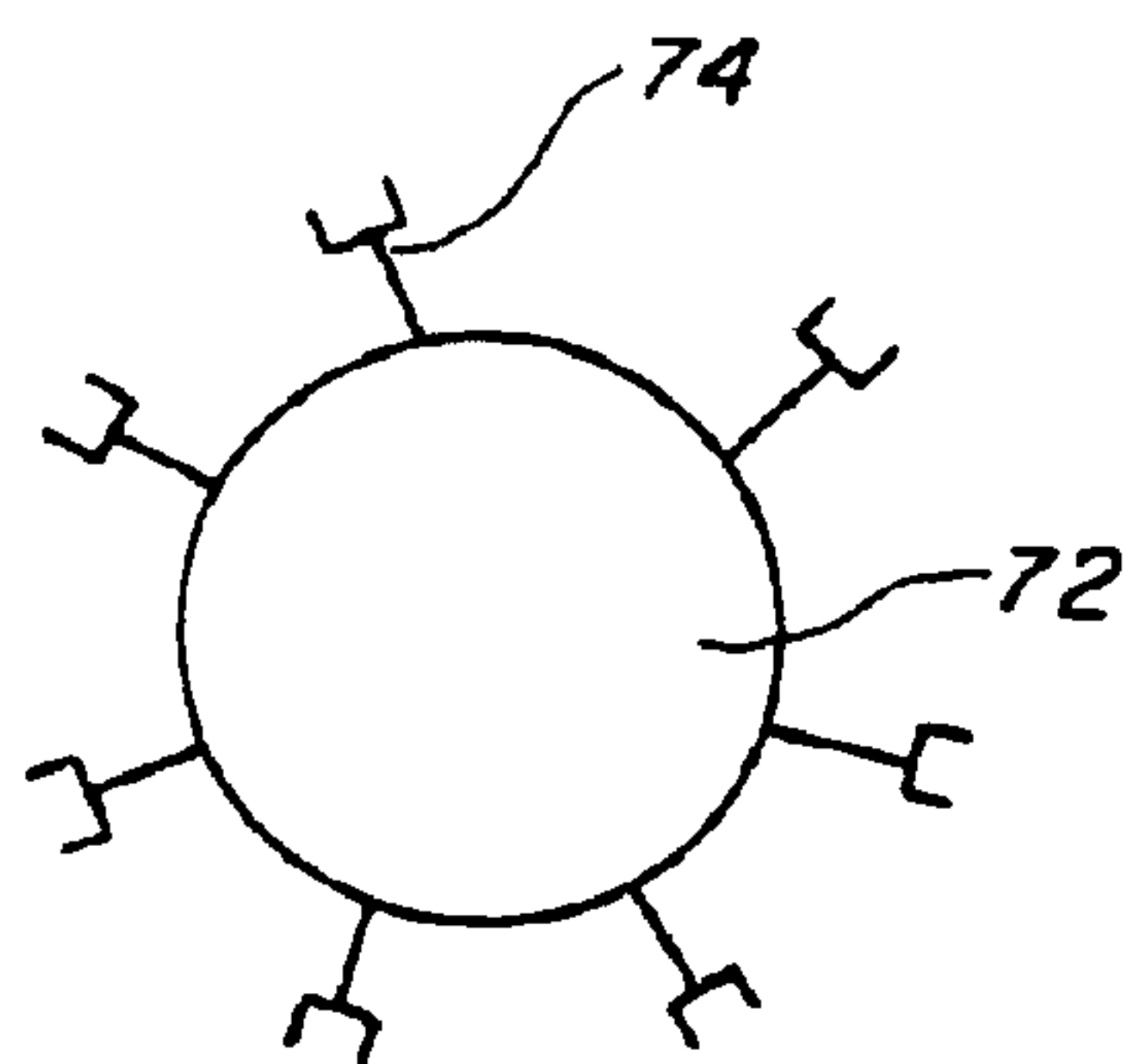


FIG. 8(a)

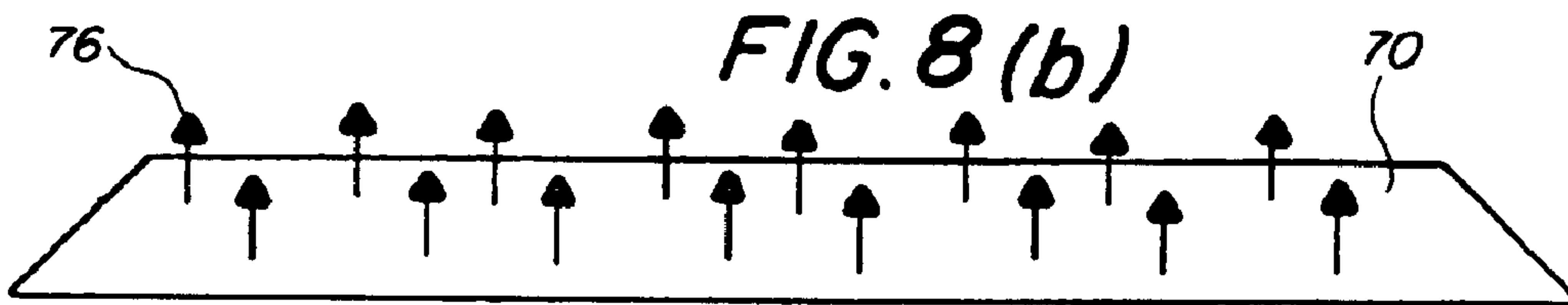


FIG. 8(b)

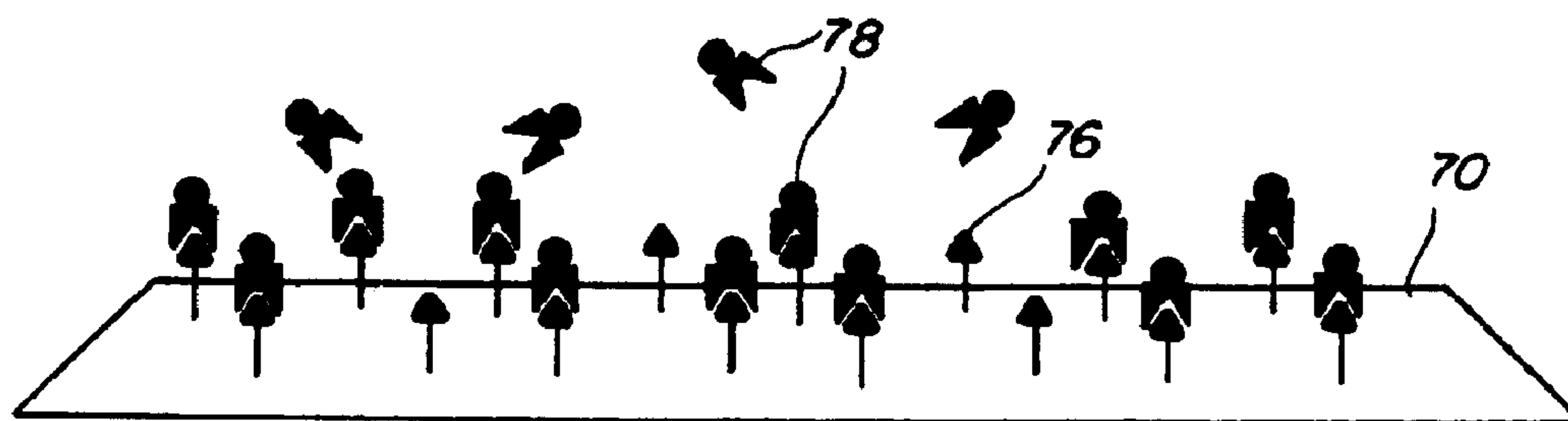


FIG. 8(c)

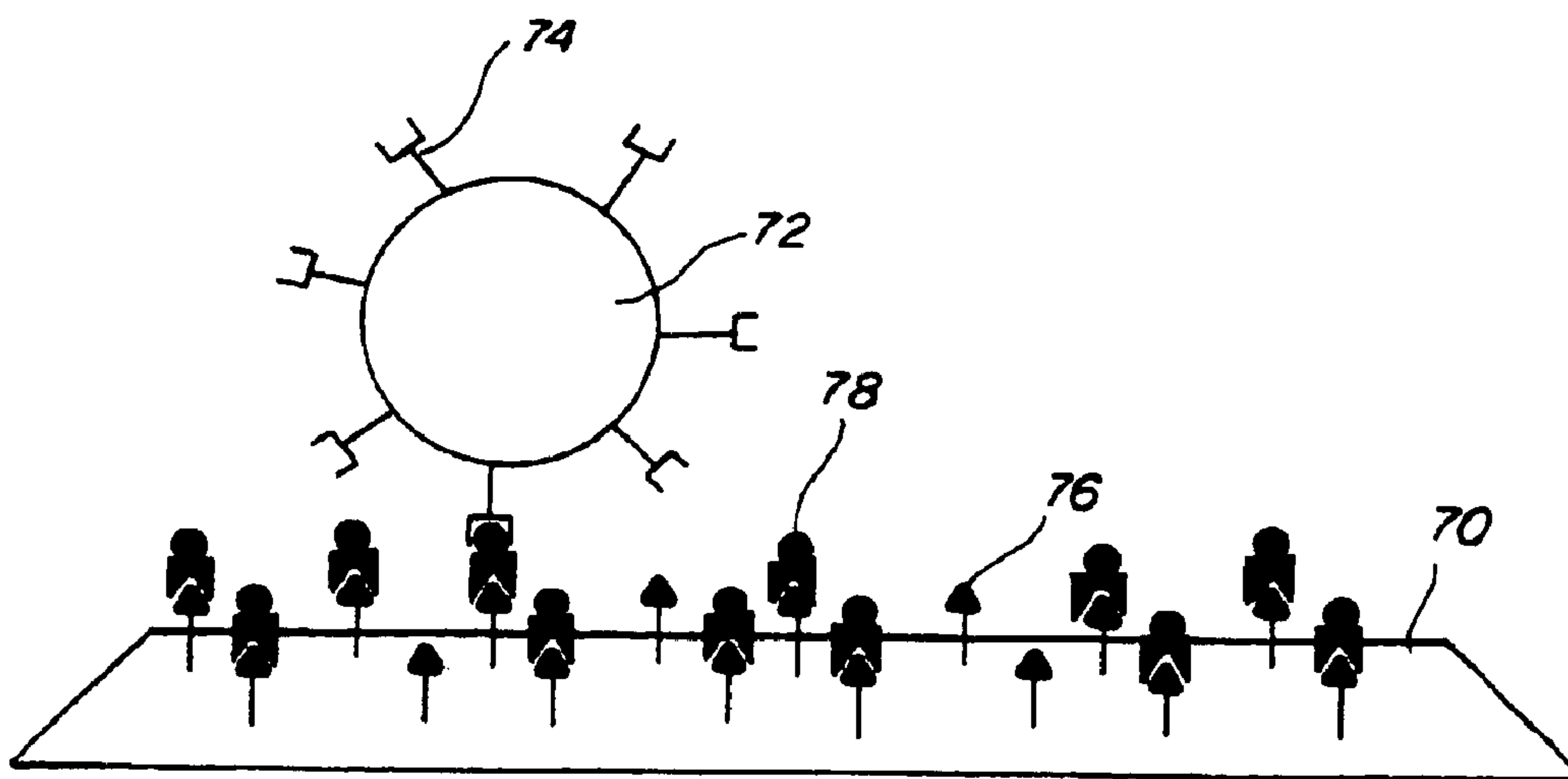


FIG. 8(d)

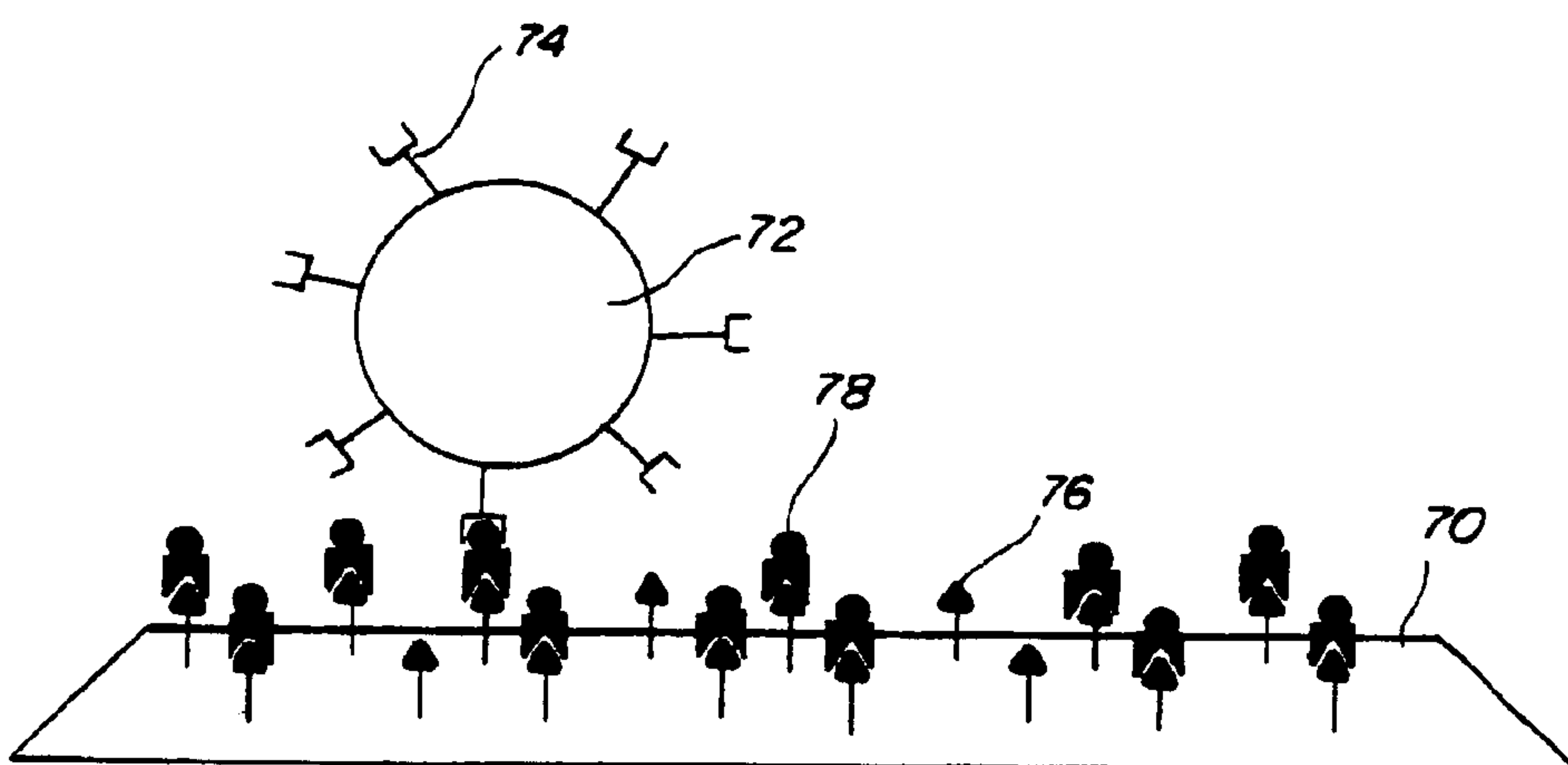
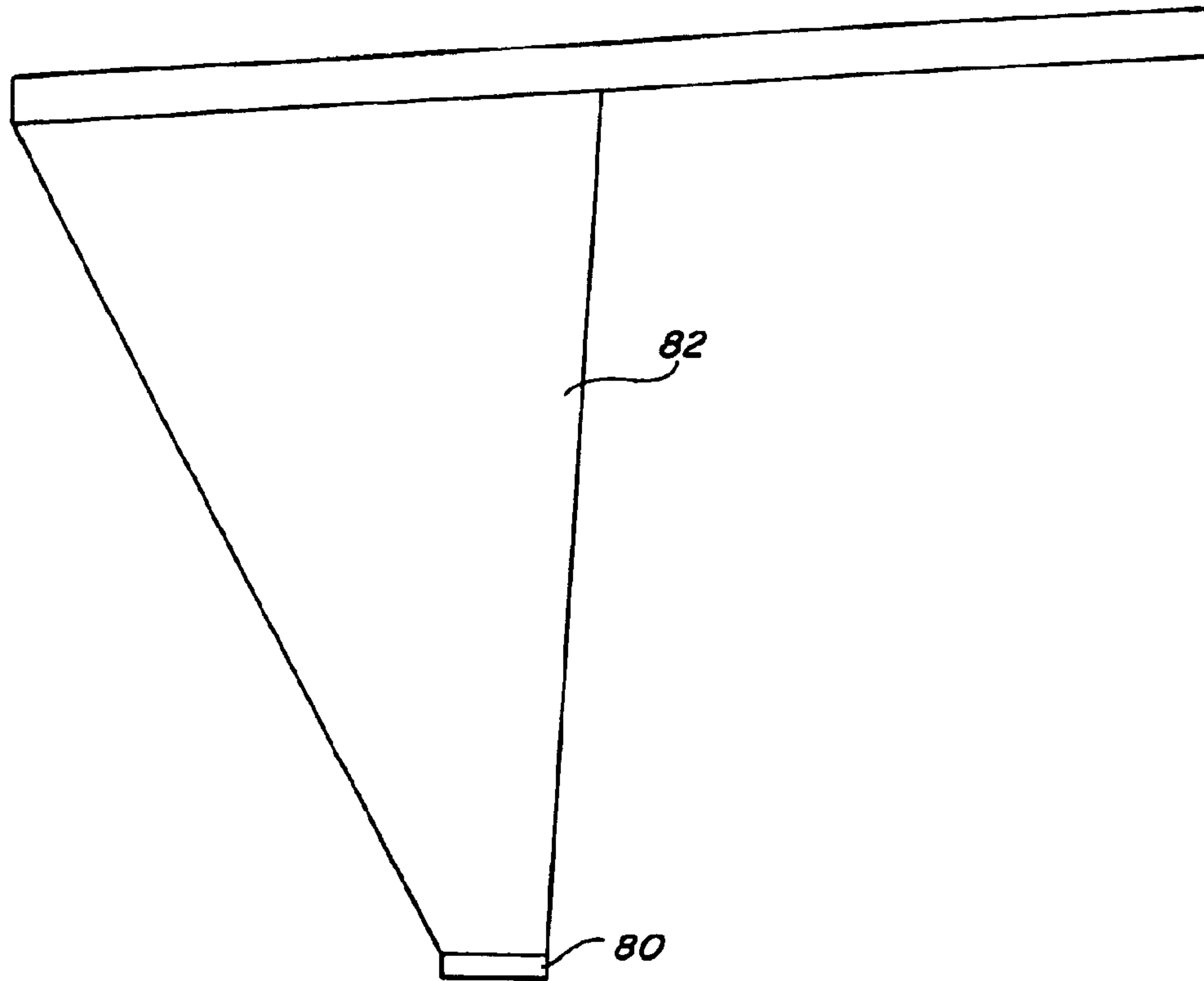


FIG. 8(e)

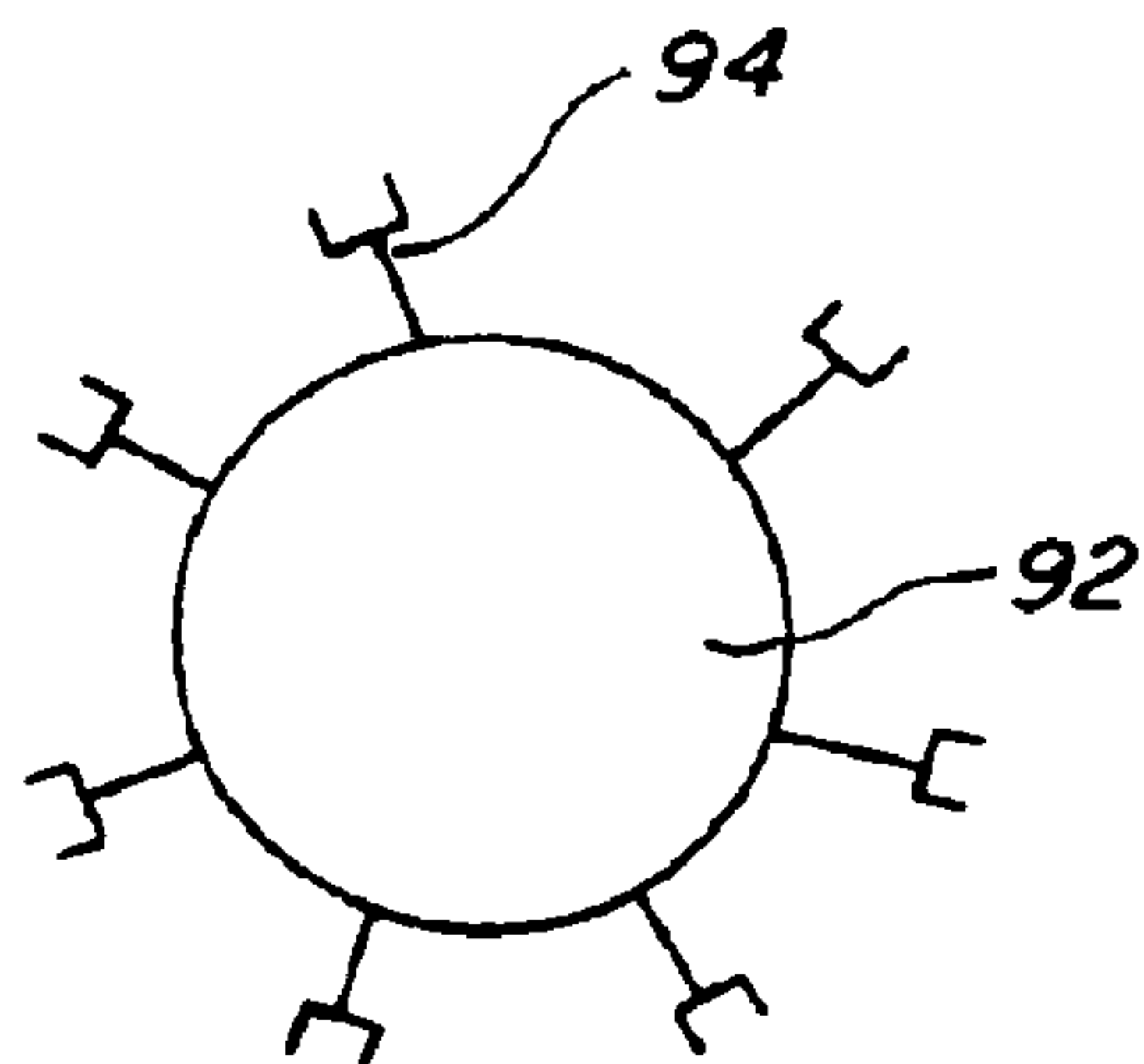


FIG. 9(a)

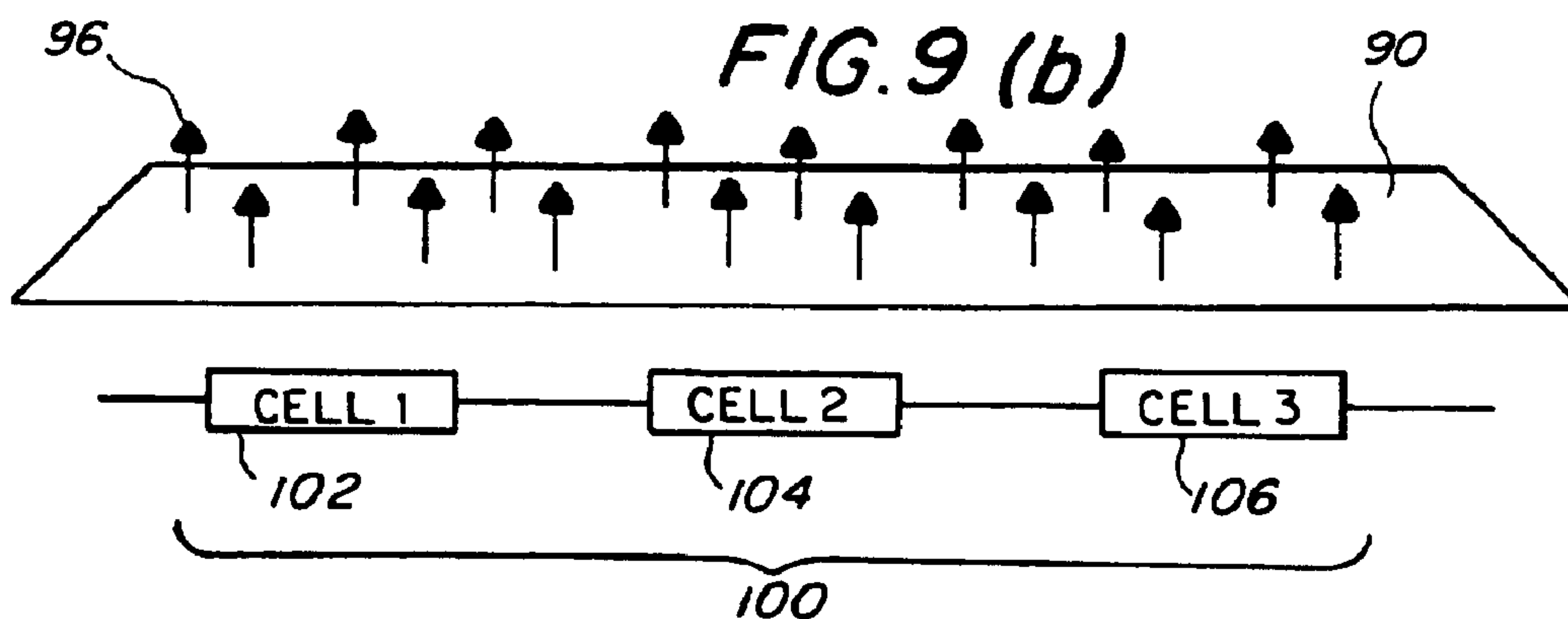


FIG. 9(b)

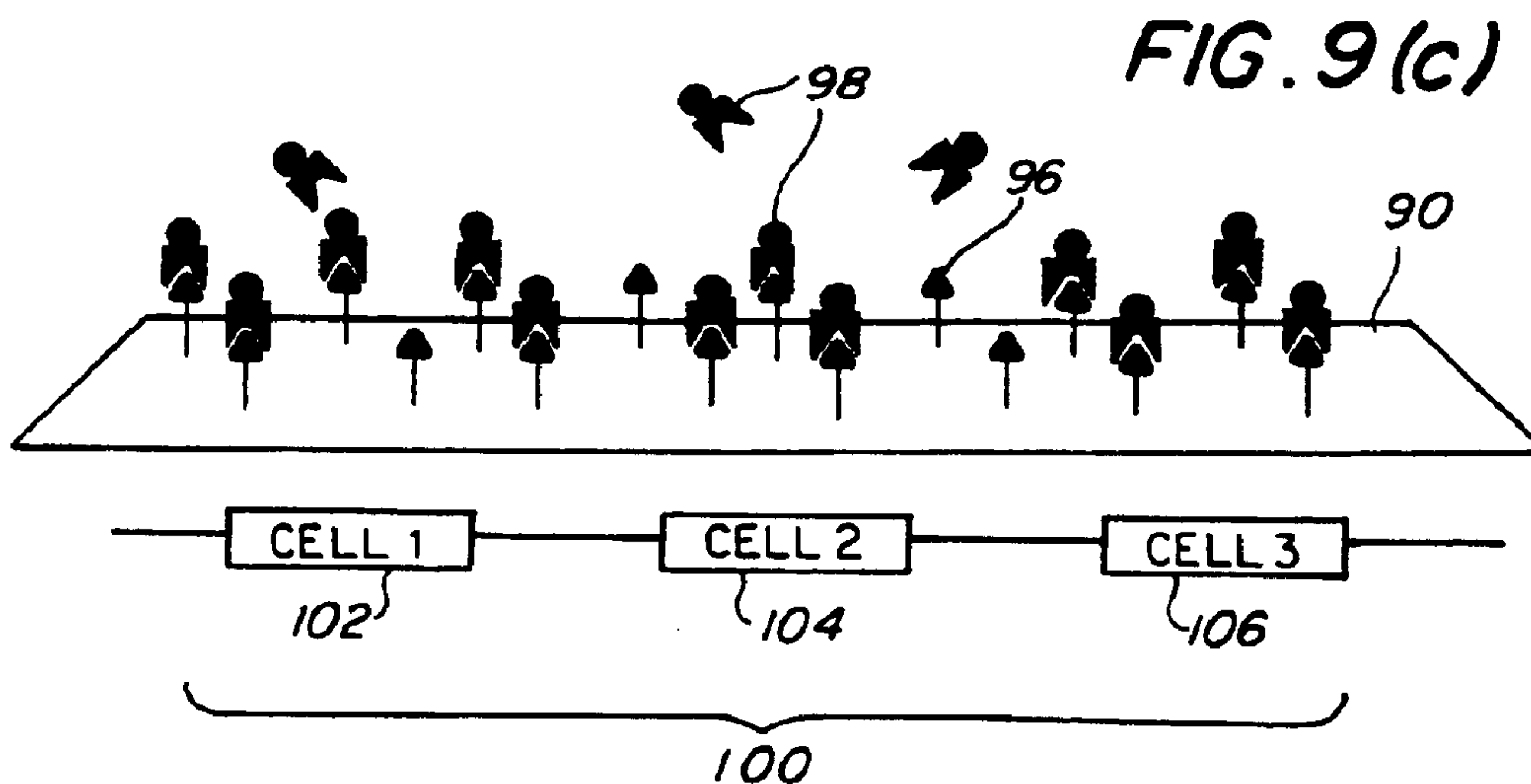


FIG. 9(c)

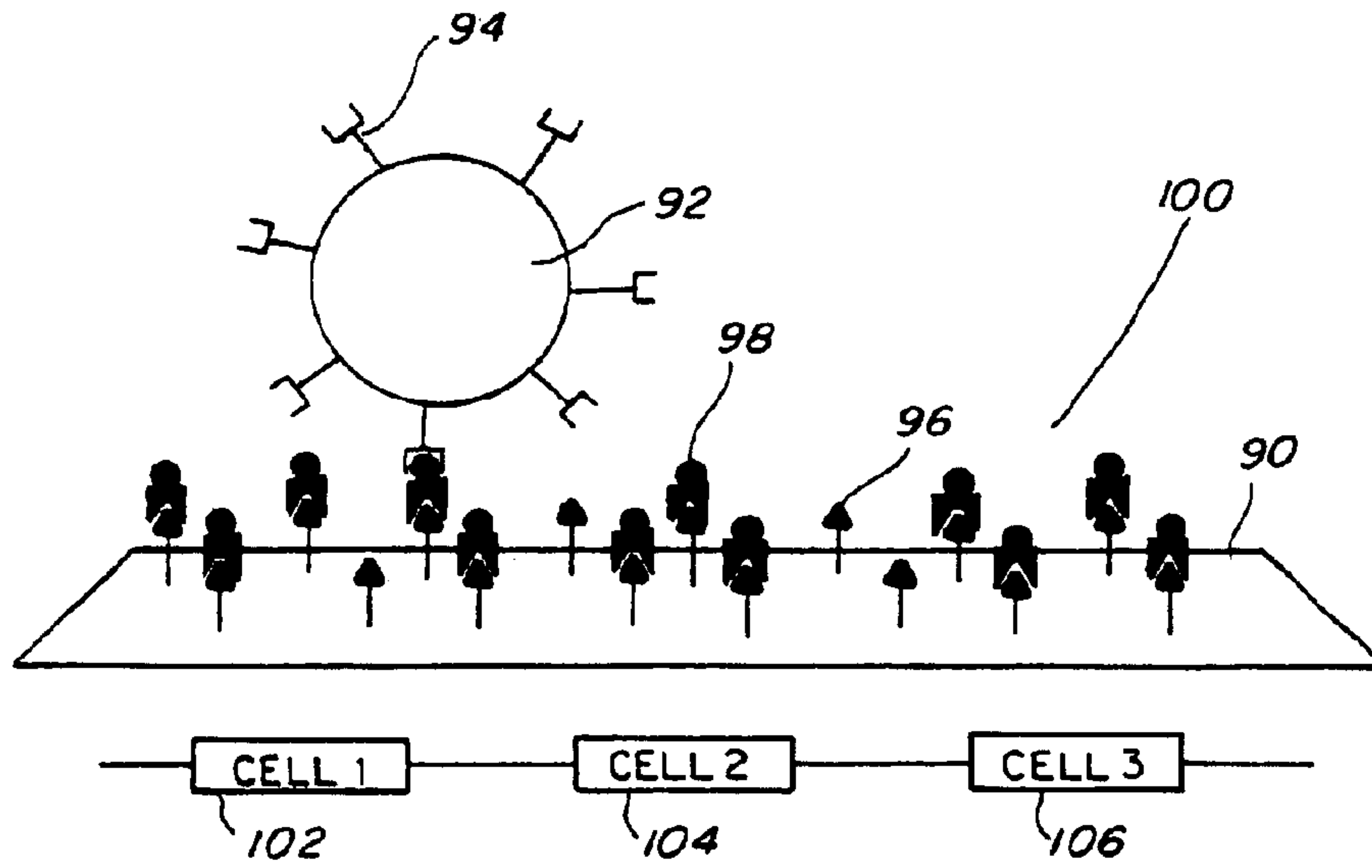


FIG. 9(d)

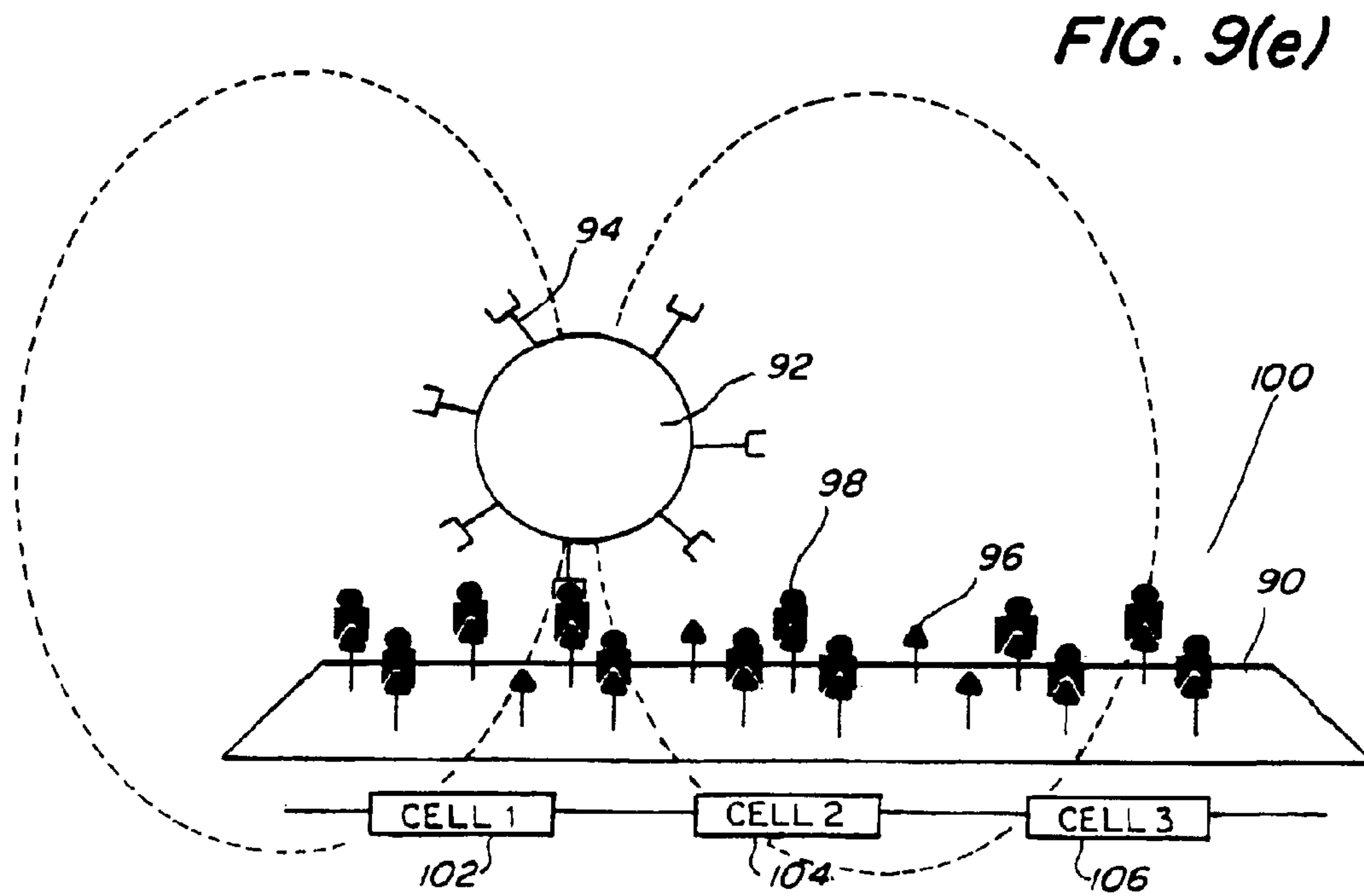


FIG. 9(e)

HYBRID HALL VECTOR MAGNETOMETER

CROSS REFERENCE TO RELATED APPLICATIONS

This application is a divisional of application Ser. No. 10/287,876, filed Nov. 4, 2002, now issued as U.S. Pat. No. 6,800,913.

FIELD OF THE INVENTION

The present invention relates generally to a Hall Effect device, and, in particular, to a modified Hall effect device which is a hybrid combination of a first conventional Hall plate and a second conventional Hall plate coupled to a ferromagnetic layer.

BACKGROUND OF THE INVENTION

Several different types of devices are available for the measurement of magnetic fields. Examples that operate at room temperature include flux gate magnetometers and magnetoresistors. A third family of devices is one of the oldest commercial field sensors, the Hall plate. All of these devices share a common trait; they measure a scalar value of magnetic field that represents a single component of the vector field to be measured. The family of Hall devices includes dozens, if not hundreds, of variations, for example, R. S. Popovic, "Hall-effect Devices," *Sens. Actuators* 17, 39 (1989); and R. S. Popovic, "Hall Effect Devices", (Adam Hilger, Bristol, 1991), both herein incorporated by reference. One limitation of all of these Hall devices is that these devices only can measure a scalar field value proportional to the component of vector field that is perpendicular to the plane of the Hall plate.

In the art, one-dimensional arrays of Hall devices have been used to achieve a moderate magnetic field spatial resolution. A one-dimensional array of Hall crosses has been described by E. Zeldov et al., "Thermodynamic observation of first-order vortex-lattice melting transition in BiSrCaCuO," *Nature* 375, 373 (1995), herein incorporated by reference. In this study, an array of ten Hall crosses, with dimensions of 3 μm by 3 μm for each sensor, was used to detect the motion of fluxons in a small sample of single crystal superconducting BiSrCaCuO. The sensors were fabricated on a GaAs/AlGaAs chip and a macroscopic (0.7 mm by 0.3 mm by 0.1 mm) sample was placed on top. Each Hall sensor had a DC sensitivity of order 0.1 Oe and each was able to sense the presence of a single fluxon when in proximity to the sensor. The spatial resolution of the measurement was therefore of the order of magnitude of the Hall sensor dimensions, a few microns.

One recent advancement in the art of measuring magnetic fields is provided by a hybrid Hall effect device. A hybrid Hall device is a simple bilayer magnetoelectronic device. The physical principles of operation are described in the publication "Hybrid Hall Effect Device," by Mark Johnson, B. Bennett, M. J. Yang, M. M. Miller and B. V. Shanabrook, *Appl. Phys. Lett.* 71, (1997) and in U.S. Pat. No. 5,652,445 entitled "Hybrid Hall Effect Device and Method of Operating," both herein incorporated by reference, and are briefly described below with reference to FIGS. 1(a) and (b).

An example of one prior art hybrid Hall effect device is generally denoted **10** in FIGS. 1(a) and 1(b). A thin, microstructured ferromagnetic film F, denoted **11**, is fabricated over a standard Hall cross **12** formed from a Hall plate **14**, and positioned such that edge **13** of film **11** is disposed over the central region of the Hall cross **12**. The film **11** is

electrically isolated from the Hall cross **12**, typically by a thin insulating layer **15**.

The film **11** has a magnetization anisotropy in the film plane and acts as a local source of magnetic field. When an external magnetic field $H_x \hat{x}$ causes the magnetization M of F to be along $-\hat{x}$, there is a positive magnetic pole density on the edge over the Hall cross **12**, and a local negative field $-|B_z|$ is generated in the vicinity of the carriers in the Hall plate **14** which comprises an InAs layer **16**, a second insulating layer **17** and a substrate **18** (see FIG. 1(b)). The result is a positive sense voltage $V_s = V_+ - V_-$. If the magnetization orientation is reversed, the sign of the pole density, the local field $|B_z|$, and the sense voltage V_s is reversed. Thus, device **10** translates a horizontal magnetic field into a vertical magnetic field, thereby providing for the detection and measurement of the convolution of the \hat{x} and \hat{z} field components comprising the magnetic field.

When fabricated with appropriate magnetic properties, the film **11** has bistable magnetization and the resulting hybrid Hall effect device **10** has digital applications, such as nonvolatile storage. When fabricated with other magnetic properties, the magnetization of film **11** responds linearly with an external field. A hybrid Hall effect device engineered in this way can act as a sensor of in-plane magnetic fields.

One limitation with prior art hybrid Hall effect devices, such as device **10**, is that these prior art devices cannot be used to determine the independent magnetic field vector components comprising a vector magnetic field, such as for determining the \hat{x} and the \hat{z} components of a magnetic field; device **10** merely measures the convolution of the \hat{x} and \hat{z} field components.

BRIEF SUMMARY OF THE INVENTION

The present invention concerns a modified hybrid Hall effect device, which is a hybrid combination of a first conventional Hall plate and a second conventional Hall plate coupled to a ferromagnetic layer, corresponding to film F. The modified Hall Effect device can be adapted for use as a magnetic field sensor capable of measuring the individual components of a vector magnetic field. Equivalently, the device is capable of measuring the magnitude of a vector magnetic field of any orientation.

In the present modified hybrid Hall effect device, the ferromagnetic film acts as a field transducer that translates a horizontal field into a vertical field. This is a function that can be combined with the sensitivity of Hall devices for use in applications where perpendicular and horizontal magnetic field components are present, to make a magnetometer that is sensitive to more than a single component of the field.

An object of the present invention is to provide an inexpensive, integrated combination of a Hall device that is adaptable for measuring two or three components of a vector magnetic field, \vec{B} . A magnetometer, incorporating the present invention, which is capable of measuring two or more vector components of a magnetic field, has several advantages over magnetometers which are capable only of scalar measurements. The single component to which a scalar magnetometer is sensitive may be the smallest component of the vector field to be measured. Therefore, measuring all three vector components, the vector magnetometer always measures the total field magnitude, and is therefore intrinsically more sensitive in any application.

An additional object of the present invention is to provide a microfabricated magnetometer cell with two or three components for measuring a vector field with high spatial resolution. A specific application is the calibration and

characterization of magnetic force microscope (MFM) tips. A cell that measures a single component of field can also be used for this application, with diminished field sensitivity by comparison with the two or three component cells.

A further object of the present invention is to provide a device, which is adaptable to use any source of magnetic field and which generates a three-dimensional magnetic field that is dipolar but has properties unique to that source. The source may be either a macroscopic source, such as a vehicle, or a microscopic source such as a magnetic particle used to tag a molecule or bundle of molecules. While measuring a scalar field might permit the detection of a source of the field, measuring a vector field permits the detection of a source and, with a suitable model, also permits the identification of the object that is the source. Following this functionality, measurement of a vector field as a function of time and/or position permits an analysis of position and motion of the object, which is the field source.

An additional object of the present invention is to provide an inexpensive vector magnetometer adaptable for use in remotely sensing large objects that have intrinsic magnetic moments.

Yet another object of the present invention is to provide a microfabricated vector magnetometer with high spatial resolution that can be adapted to scan across a magnetic field that includes an object of interest.

A further object of the present invention is to provide novel techniques for forming two-dimensional arrays of Hall cells, and new applications employing arrays of Hall devices for sensing magnetic fields with high spatial resolution.

Another object of the present invention is to provide a two-dimensional array of sensor cells for high spatial resolution of objects that have local magnetic fields that vary on a small spatial scale.

Yet a further object of the present invention is to provide a sensor cell that can be adapted for use as a susceptometer, to detect one, two or three components of magnetic field when a perturbing magnetic field is applied to an object.

A further object of the present invention is to provide susceptometers for use in applications where an external perturbing magnetic field is applied to the object that is the source of magnetic field to be measured, even if the perturbing field is also applied to the sensor.

In accordance with the aforementioned objects, the present invention concerns an integrated Hall effect device for measuring the vector components of an external magnetic field. The device includes a conductive substrate having a top surface with a first section and a second section and is capable of carrying an electrical current. The first section is positioned in close proximity to the second section such that a first electrical signal can be generated in response to one of the vector components of the external magnetic field acting perpendicularly on the electrical current in the conductive substrate. A ferromagnetic film is provided having at least one configurable magnetization orientation state and the ferromagnetic film is disposed over a portion of the second section such that a fringe magnetic field can be generated from an edge of the ferromagnetic film by vector components of the external magnetic field acting on the magnetic film wherein a second electrical signal can be generated in response to the fringe magnetic field acting on an external current in the conductor substrate. In one further specific form, the conductive substrate and the ferromagnetic film are separated by an insulating layer.

According to another aspect of the present invention, a method is provided for calibrating a magnetic force micro-

scope (MFM) tip by measuring vector components of a magnetic field generated by the microscope tip. The method includes the steps of generating an electrical current that flows along a current axis of a conductor substrate, scanning the microscope tip across the conductor substrate at a variable height, and generating a first electrical signal along a first voltage axis in response to a vector component of a magnetic field from the microscope tip acting on the electrical current in the conductor substrate. The values of the first electrical signal are mapped as a function of the variable height.

In one specific further embodiment, the microscope tip is scanned across a ferromagnetic film disposed over a portion of the second section at a variable height and a corresponding fringe field is generated at an edge of the ferromagnetic film in response to vector components of a magnetic field from the microscope tip acting on the ferromagnetic film. The edge of the ferromagnetic film is located adjacent to a second voltage axis such that the corresponding fringe field is perpendicular to the current axis. A second electrical field is generated along the second voltage axis in response to the fringe field acting on the electrical current in the connected substrate. The values of the first electrical signal and the second electrical signal are mapped as a function of the variable height.

In accordance with another aspect of the present invention, a method is provided for identifying chemical or biological agents that have been tagged with microscopic magnetic particles by measuring vector components of a magnetic field generated by the magnetic particles. The method includes generating an electrical current that flows along a current axis of a conducting substrate mounted on a proximal probe tip. The substrate is scanned for chemical or biological agents and a first electrical signal along a first voltage axis is generated in response to vector components of a particle's magnetic field acting on the electrical current in the conductive substrate. The first electrical signal is recorded and values of the first electrical signal are mapped with respect to magnetic fields associated with the magnetic particles.

In one further specific embodiment, the chemical or biological agents are scanned by a vector magnetometer mounted on a proximal probe tip and a fringe field is generated at an edge of a ferromagnetic film in response to a vector component of a particle's magnetic field acting on the ferromagnetic film where the edge of the ferromagnetic film is located adjacent to a second voltage axis such that the fringe field is perpendicular to the current axis. A second electrical signal is generated along the second voltage axis in response to the fringe field acting on the electrical current in the second section of the conducting substrate. The second electrical signal is recorded and values of the second electrical signal, along with the values of the first electrical signal, are mapped with respect to magnetic fields associated with the magnetic particles.

In accordance with yet another aspect of the present invention, a cell array is provided which includes integrated Hall effect devices for measuring the vector components of an external magnetic field of an object. The cell array includes a plurality of rows comprising a plurality of integrated Hall effect devices. Each Hall effect device is electrically connected to each other along a current axis. Each of the plurality of integrated Hall effect devices includes a conductor substrate having a top surface with a first section and second section, which are capable of carrying an electrical current. The first section is positioned in close proximity to the second section such that a first electrical signal

can be generated in response to one of the vector components of the external magnetic field acting perpendicularly on the electrical current in the conducting substrate. A ferromagnetic film is provided having at least two configurable magnetization orientation states and is positioned disposed over a portion of the second section such that a fringe magnetic field can be generated from an edge of the ferromagnetic film by vector components of the external magnetic field acting on the magnetic film wherein a second electrical current can be generated in response to the fringe magnetic field acting on an electrical current in the conductor substrate.

The present invention offers numerous advantages over prior devices. For example, sensors based on Hall devices according to the present invention offer numerous advantages and are superior in many ways to MR sensors known in the art. The present sensors have linear response over a large field range, and they can be fabricated on a small size scale with highly reproducible characteristics.

In addition, the present invention provides for a superior magnetometer that is sensitive to single components of field. In addition, a vector magnetometer, in accordance with the present invention, can be adapted to sense a magnetic field and, using knowledge and properties of the vector components, can also be used to detect and identify an object that is the source of field. Further, the present vector magnetometer may also be used to analyze the position and motion of such an object.

A further advantage of the present invention is that the present device is readily integrated and can be manufactured and packaged using inexpensive techniques. It is therefore inexpensive, and is much less expensive than scalar magnetometers such as flux gates and SQUIDs.

Further features and advantages of the present invention will be set forth in, or apparent from, the detailed description of preferred embodiments thereof which follows.

BRIEF DESCRIPTION OF THE DRAWING

The invention will now be described in detail with respect to preferred embodiments with reference to the accompanying drawings, wherein:

FIG. 1(a), which was described above, is a plan view of a prior art hybrid Hall effect device and FIG. 1(b), which was also described above, is a cross sectional view of the hybrid Hall device of FIG. 1(a);

FIG. 2(a) is a plan view of a hybrid Hall device in accordance with the present invention and FIG. 2(b) is a cross sectional view of the hybrid Hall device of FIG. 2(a);

FIG. 2(c) is a plan view of a hybrid Hall device including three Hall crosses in accordance with the present invention;

FIG. 3 is a cross sectional view of a magnetic force microscope (MFM) tip and the hybrid Hall device of FIG. 2(b);

FIG. 4(a) depicts a sample trace using the hybrid Hall device and MFM tip configuration of FIG. 3, FIG. 4(b) is a plot of the peak Hall voltage as a function of lift height and fitting to a monopole and dipole term for the configuration of FIG. 3, and FIG. 4(c) is a plot of the field profile for the MFM tip of FIG. 3;

FIG. 5 is a cross sectional view of the hybrid Hall device of FIG. 2 adapted to measure the magnetic field associated with a chemical or molecular molecule in accordance with the present invention;

FIG. 6(a) is a plan view of an array of hybrid Hall devices in accordance with the present invention;

FIG. 6(b) is a plan view of an array of hybrid Hall devices in accordance with the present invention;

FIGS. 7(a) through 7(e) are schematic views of a hybrid Hall device in the various stages of a first type of sandwich assay in accordance with the present invention;

FIGS. 8(a) through 8(e) are schematic views of a hybrid Hall device in the various stages of a second type of sandwich assay in accordance with the present invention; and

FIGS. 9(a) through 9(e) are schematic views of a hybrid Hall device in the various stages of a third type of sandwich assay in accordance with the present invention.

DETAILED DESCRIPTION OF THE INVENTION

The basic device structure for a modified hybrid Hall device 20 that measures two vector field components is depicted in FIGS. 2(a) and 2(b). A standard Hall plate 24 is fabricated using conventional techniques known in the art to form two Hall crosses 22, 23, which are adapted to function as two Hall sensors generally denoted as 32, 33. The Hall crosses 22, 23, each have a first arm 34, 35 and a second arm 36, 37, respectively.

The Hall cross 22 is located in close proximity to Hall cross 23 and is formed in a manner consistent with that in the prior art Hall sensor 10 of FIG. 1. A thin, microstructured ferromagnetic film 21 is fabricated over the Hall cross 22 and positioned such that edge 31 of the ferromagnetic film 21 is over the central region of the Hall cross 22 and a fringe magnetic field emanates or projects from the edge 31 of the ferromagnetic film 21. The ferromagnetic film 21 is electrically isolated from the surface of Hall plate 24 by a thin insulating layer 25, which has a magnetization anisotropy in the plane of film 21, and acts as a source of magnetic field.

For the purposes of this invention, "proximity" is defined relative to the spatial scale of the homogeneity of the vector magnetic field to be measured. Each of the sections of the vector magnetometer should be fabricated in proximity with each other, where the proximal spacing d varies according to the application. For remote sensing of fields that have small variation on a length scale of meters, spacing d can be 10 mm or larger. In practice, procedures of integrated fabrication will likely dictate a spacing no larger than 10 mm. An example of this kind is the remote sensing of a magnetic field associated with a large vehicle, such as an armored tank. At distances of the order of a kilometer, the magnetic field from the tank will have a small variation on the length scale on the order of 1 meter. On the other hand, magnetic fields associated with small magnetic particles may vary on a length scale of tens of nm. In this case, spacing d may be the smallest feature size available with the fabrication process. Indeed, it may be preferred to fabricate the device with sections adjacent to each other, wherein the spacing is zero.

In one exemplary form, a semi-insulating buffer layer 27 is formed over substrate 28 (See FIG. 2(b)). The buffer layer 27 is composed of 200 nm $\text{Al}_{0.6}\text{Ga}_{0.4}\text{Sb}$ /3 μm AlSb . An InAs layer 26 is grown on the buffer layer 27 by molecular beam epitaxy (MBE) to form a high mobility heterostructure.

The InAs layer 26 consists of 3 nm InAs/25 nm $\text{Al}_{0.6}\text{Ga}_{0.4}\text{Sb}$ and a 15 nm InAs layer which is doped by an arsenic soak in the middle of the 25 nm $\text{Al}_{0.6}\text{Ga}_{0.4}\text{Sb}$ barrier to form a conductive substrate. The Hall crosses 22, 23 are fabricated on a micron or submicron scale by conventional photolithography or electron beam lithography and standard mesa etch techniques known in the art.

In a typical mode of operation, a bias current, I^+ , is applied to a first bias arm 38 and a second bias arm 39 and

is removed at ground (denoted by Γ^-), flowing along \hat{x} . A Hall voltage V is measured in each sensor as $V_{H,33}=V_{33,+}-V_{33,-}$ and $V_{H,32}=V_{32,+}-V_{32,-}$. In the cross-sectional view of FIG. 2(b), a homogeneous external field \vec{B} (depicted with dotted field lines 38) is to be measured. Hall sensor 33 measures the \hat{z} field component, and Hall sensor 32 measures the convolution of the \hat{x} and \hat{z} field components. The \hat{x} component is derived by subtracting the voltage $V_{H,33}$ from $V_{H,32}$, with the resulting voltage directly proportional to B_x .

One of ordinary skill in the art will readily appreciate that it is straightforward to add a third device as a third Hall sensor as shown in FIG. 2(c) with a bias current arm oriented along \hat{y} and a ferromagnetic element that spans the current bias arm. The standard Hall plate 24 is fabricated to form three Hall crosses 23, 22 and 46 that are adapted to function as a first Hall sensor 33, a second Hall sensor 32, and a third Hall sensor 51. A second ferromagnetic film 48 is fabricated over the Hall cross 46 and is positioned such that edge 47 of the ferromagnetic film 48 is over the central region of the Hall cross 46. The ferromagnetic film 48 can be isolated from the surface of the Hall plate 24 by a thin insulating layer or film as previously described. The Hall cross 46 has a first arm 50 and a second arm 49 defining a third voltage axis. Hall cross 46 has a third bias arm 52 and a fourth bias arm 53 defining a second bias current axis oriented along \hat{y} . The second bias current axis is connected electrically in series with the first bias current axis so that current I^+ applied to arm 38 flows down the first bias axis, along \hat{x} , and proceeds down the second axis, along \hat{y} , to ground Γ^- at arm 52. The second bias current, applied to bias arms 52 and 53, respectively, produce a voltage V_{51} measured in Hall sensor 53 as $V_{H,51}=V_{51,+}-V_{51,-}$ across the third voltage axis 40 and 50. Such a third Hall sensor would measure the convolution of the \hat{y} and \hat{z} field components, and the \hat{y} component can be readily derived by subtracting the \hat{z} component measured by Hall sensor 33

For simplicity of discussion and clarity of the drawings, the following discussion is limited to a two-component device. However, one skilled in the art will be able to apply the principles provided herein to that of a three-component device.

A vector magnetometer incorporating sensor 20 can be fabricated on a small size scale for applications where spatial resolution is important. Each Hall sensor 32, 33 can be lithographically formed with a feature size of $1\ \mu\text{m}$ being readily attained and a minimum feature size f of $0.1\ \mu\text{m}$ being possible. Similarly, the two Hall sensors 32, 33 can be placed in close proximity, typically separated by f .

Sensor 20 can be employed for use in numerous applications including the following, non-limiting example depicted in FIG. 3. In this example, sensor 20 is employed in an application for which spatial resolution is important in the calibration of a magnetic force microscope (MFM) tip 40. The tip 40 has a height H and base 41 with a width W of about $10\ \mu\text{m}$. The base 41 attached to a scanning cantilever 42. The radius of curvature of the end 43 of the tip 40 is typically about $50\ \text{nm}$. Tip 43 is coated with a ferromagnetic thin film of about $10\ \text{nm}$ thick. Dipolar magnetic fields, with steep field gradients, emanate from the end 43.

During MFM operation, the tip 40 is scanned across a surface of sensor 20 at a variable height z_0 on the order of 0 to $100\ \text{nm}$. Magnetic tip 40 may have a unique domain structure and field pattern whereby the sensor 20 can be advantageously used to calibrate magnetic tip 40 by measuring a profile of the dipolar magnetic field from the tip 40.

The magnetic field profile is readily achieved by scanning the tip 40 across a Hall vector magnetometer incorporating sensor 20, at a variety of scan heights, z_0 , on the order of about 0 to $2000\ \text{nm}$. Although an adequate profile can be achieved by scanning MFM tip 40 across the simple hybrid Hall device such as sensor 33 of FIG. 2, a superior magnetic profile is achievable by scanning across a Hall vector magnetometer which also employs both a conventional Hall sensor, i.e. Hall sensor 33, in conjunction with a hybrid Hall sensor, i.e. Hall sensor 32. In the former case, a novel method is provided for by using the prior Hall device 10 to map the spatial magnitude of magnetic fields by scanning a magnetic source, and calibrating MFM tips by using such a procedure.

Data to calibrate the MFM tip 40 is acquired by scanning the tip 40 across Hall sensor 32 while recording an AFM image in order to locate the center of the Hall cross 22. The Hall sensor 32 is then biased with an AC current of $10\ \mu\text{A}$ at $10\ \text{KHz}$, and the Hall voltage V_H was recorded as the tip 40 is raised and lowered through different heights z_0 as shown in FIG. 3. A detailed discussion of these experiments is presented as the following non-limiting experiments.

MFM Calibration Experiments

The photolithographically defined Hall sensor 32 was scanned in a Tapping Mode using a high moment MFM tip (HM-MESP from Digital Instruments, hereinafter "DI"). This tip has a nominal moment of $3 \times 10^{-13}\ \text{emu}$ and the nominal radius of curvature at the end of the tip is $50\ \text{nm}$, as provided by DI. The Hall sensor 32 was driven by a $10\ \text{KHz}$, $5\ \text{V}$ p-p signal from a lockin amplifier in series with a $0.51\ \text{M}\Omega$ resistor to ensure a constant current source of about $10\ \mu\text{A}$. The Hall voltage V_H was then detected with a full scale sensitivity of $100\ \mu\text{V}$ and the $\pm 10\ \text{V}$ signal monitor output of the lockin amplifier was applied to the auxD channel of a DI Signal Access Module and recorded as channel 2 deflection voltage. This means that the input voltage range was preserved when recorded by AFM software, e.g. $1\ \text{V}$ input, was $1\ \text{V}$ recorded.

A series of measurements was then made by scanning a line through the center of the Hall cross 22 for varying lift heights ($0\ \text{nm}$ to $2000\ \text{nm}$) and the corresponding Hall voltages recorded. FIG. 4(a) shows a sample trace for $z_0=0$. The peak Hall voltage was then plotted as a function of z_0 and fitted to a monopole and dipole term, as shown in FIG. 4(b).

The results can be modeled in the following way. The Hall cross 22 is coated with a $27\ \text{nm}$ thick insulating layer of SiO_2 . If one assumes that the tip can be represented by a magnetic sphere $50\ \text{nm}$ in radius, then the z -component of the magnetic field at the Hall cross with the tip in contact with the SiO_2 layer will be about $1300\ \text{Oe}$. This is simply calculated from the dipole field which has the form

$$H_z = \frac{2m}{z^3},$$

where z is the sum of the SiO_2 layer thickness, the tip radius and the tip-sample separation distance (i.e. the distance between the center of the dipole and the Hall cross). The magnetic dipole moment is taken from the vendor (Digital Instruments) to be about $3 \times 10^{-13}\ \text{emu}$. For a spherical tip in contact with the sample, the lateral dependence of the field is given by

$$H_z(x) = \frac{m(2z^2 - x^2)}{(x^2 + z^2)^{5/2}}.$$

This field profile is shown in FIG. 4(c). The profile is sharply peaked with a FWHM of about 100 nm. If this field profile is centered on the Hall cross 22 and integrated over the expected 5 μm extent of the cross sensing area, the average value of the magnetic field becomes about 20 Oe. The sensitivity of the Hall cross 22 was measured using a uniform, externally applied field to be 3.5×10^{-7} V/Oe. For zero lift height, the expected signal for the peak field of 1300 Oe should be about 450 μV . However, using the average value of field, the expected signal would be about 7 μV . The actual value is about 11 μV , which is in very good agreement especially since the true sensing area is unknown and the tip is not a pure dipole and the value of the dipole moment is only approximately known. It should be noted that uncertainties in this model become relatively smaller as the dimensions of the Hall cross shrink, and highly accurate measurements are expected for sub-micron Hall crosses.

In a conceptually similar operational mode, a vector magnetometer, incorporating sensor 20, can be fabricated on a chip and attached to a scanning apparatus. The sensor 20 can then be adapted to be scanned across samples of interest. While a simple scalar scanning Hall magnetometer is sensitive to the scalar value of the magnetic field component perpendicular to the device plane, the present vector magnetometer is sensitive to two or three field components and therefore sensor 20 provides enhanced, i.e. greater, sensitivity. Moreover, sensor 20 affords greater utility because the detection of vector magnetic fields enables more reliable identification of the field source.

An additional specific application of a scanning vector magnetometer, incorporating the present hybrid Hall sensor, is for the identification of chemical or biological agents that have been tagged with microscopic magnetic particles. The identification proceeds by, first, partially coating a sample molecule or system of molecules, such as a biological organism or agent, with magnetic particles having a diameter d_p , where $0.5 \mu\text{m} < d_p < 5 \mu\text{m}$. The magnetic particles stick to the molecule at particular sites. Subsequently, the sample is scanned and identified via a unique detection pattern corresponding to the sample.

The magnetic particles may have an intrinsic magnetic moment and generate magnetic fringe fields in a zero applied field, or they may develop an appropriate moment in the presence of a small-applied field. A scanning vector magnetometer-incorporating sensor 20 can detect magnetic particle 50 as shown in FIG. 5. As will now be readily apparent to one skilled in the art, the use of the sensor 20 provides detection of two or more components of the field the detection process, which is more sensitive and reliable than is possible by simple scalar magnetometers. By scanning across a grid that includes a sample such as the magnetic particle 50, a vector magnetometer-incorporating sensor 20 can plot a map of the locally strong magnetic fields associated with the particles, and with such a map the sample molecule can be identified.

In the above example, sensor devices fabricated with small dimensions are required for the spatial resolution necessary to detect fringe magnetic fields from microscopic sources. There are many applications, however, where spatial resolution is not important. In these cases, device dimensions may be of the order of 1 to 10 μm .

One skilled in the art will appreciate that the field sensitivity of a Hall sensor is a function of the intrinsic sensitivity

of the device and the sensing circuit. The intrinsic sensitivity is proportional to the Hall coefficient R_H , and is usually given in units of Ω/Tesla . For example, prototypes of sensor 20 have shown an intrinsic sensitivity of 350 Ω/Tesla for both B_z and B_x measurements, and higher sensitivities are feasible.

Sensor 20 may also be employed for DC measurements of steady state fields as part of a circuit, for example, using a simple sense circuit having a 0.1 mA DC current source, a digital voltmeter, and a resulting sensitivity of about 5 m Ω . The corresponding field sensitivity, for static or slowly varying fields, is on the order of 0.1 Oe. A simple linear feedback circuit can be integrated with a Hall sensor 20 and packaged inexpensively by using the method provided in Horowitz and Hill, *The Art of Electronics* (1989). The resulting sensitivity of $1 \times 10^{-4} \Omega$ corresponds to an absolute field sensitivity of order 10^{-3} Oe.

In some applications of magnetometry, the absolute value of magnetic field is needed. Since conventional Hall sensors tend to suffer from a small but random output offset, a variety of techniques previously have been used to compensate for this offset. In applications requiring an absolute value of magnetic field, magnetometry is used to sense the field associated with an object. However, using the present Hall sensor such as sensor 20, the baseline value of field, or any offset inherent in the device, is not important because the sense circuit can be built to detect a change in output value that is to be associated with the presence of the field from the object to be detected. Equivalently stated, any initial offset can be subtracted.

There are numerous examples of applications where spatial resolution is not required, such as remote sensing. Objects of interest, such as vehicles, tanks, or submarines, have sufficient iron content that they have a small magnetic moment. The moment generates stray fields, which can be detected at distances of the order of 100 to 1000 meters.

A vector magnetometer incorporating sensor 20 offers enhanced sensitivity and further offers the ability to first detect a small field, but also to identify the object that is the source of the field by comparing details of the measured vector field with simple models that can be stored in memory. Because the present vector magnetometer can be packaged as an inexpensive system with no maintenance and low power requirements, it can be deployed in remote applications.

The foregoing discussion has described the application of a pair or a trio of Hall devices for the measurement of two or three vector components of magnetic field. In addition, the present hybrid device can be employed as hybrid Hall device field sensing cells using the techniques of forming two-dimensional arrays of Hall cells using the array method disclosed in U.S. Pat. No. 5,652,445. By considering each pair (FIG. 6(a)) or trio (FIG. 6(b)) of devices as a single vector magnetometer cell, one can employ these array techniques to address novel applications of vector magnetometry. In particular, these novel applications require high spatial resolution of magnetic fields. Rather than scanning a vector magnetometer across a field that includes an object of interest, an integrated array of devices fills the field, an object is introduced onto the array, and the output values of the cells are read out in rapid succession.

An example of such an array is array 60, depicted schematically in FIG. 6(a), for the simple case of two columns and two rows (although any desired number of rows and columns can be used) of 2-component vector magnetometer cells, 61, 62, 63, and 64. Each vector magnetometer cell 61, 62, 63, 64 is formed from an individual

sensor **20** (FIG. 2(a)) and is fabricated with a small asymmetry as disclosed in "Hybrid Hall Effect Device," by Mark Johnson et al., so that the voltage output is always positive. FIG. 6(b) depicts schematically an array **69** of two columns and two rows of 3-component vector magnetometer cells **65**, **66**, **67**, and **68**.

To read the output voltage of any component of a device employing array **60**, a small bias current or voltage is applied to row *m* and a voltage is recorded at the sense amplifier for column *i*. If there is sufficiently high impedance between voltage ground and current ground, the bias current will flow down the row. Thus, a simple diode, such as a Schottky diode, can be used for isolating each device from the sense amplifier line that is common to the column.

While array **60** represents a particularly simple means for cell isolation, it will be clear to those skilled in the art that a variety of devices could be used to achieve this function. One typical example would be a field effect transistor (FET). With appropriate isolation, the sense voltage from the device (*i*, *m*) is transmitted to the sense amplifier and is not diminished by dissipation through the cell (*i*, *n*).

The vector magnetometer array **60** has a spatial resolution, which is a convolution of the device dimension and the pitch between cells. In practice, this can be the order of a few microns, and can be made as small as the order of 0.1 micron. The array **60** can be adapted for sensing magnetic fields that are spatially varying on this scale.

An example of one application, which employs the array **60**, is the detection of microscopic magnetic particles used to tag chemical or biological agents, as described above. Each Hall device, i.e. cells **61**–**64**, in the array **60** may have a unique offset value, so the initial value of the array **60** is first measured and stored in memory. Next, a target molecule or system of molecules, such as a biological agent or organism is tagged with biofunctionalized microscopic magnetic particles and is placed on the array **60**. The target may be fixed to the surface of array **60** by selective chemical bonding to biochemical agents that have functionalized the surface of the array. The local magnetic fields associated with individual particles cause a voltage response in different cells in the array **60**. The value of the array is then measured, and the subsequent data processing is simple. The initial value of the array **60** is subtracted, values of the B_z sensor are subtracted from those of the B_x sensor for each cell, and the remaining array of values is a map of the *z* and *x* components of field associated with magnetic particles. From the map, the location of particles can be identified and the molecule or system of molecules can be identified.

FIGS. 7(a)–(e), 8(a)–(e) and 9(a)–(e) depict three ways of doing a sandwich assay. In FIG. 7(a), a magnetic particle **72** is functionalized with a first agent **74** (e.g. an enzyme, antigen or segment of DNA). In FIG. 7(b), a flat, level surface **70** is functionalized with a second agent **76**. In FIG. 7(c), the functionalized magnetic particles are admitted to the solution that contains the sample. If the target species **78** (biological or chemical) is present in the sample then it will bind to the first functionalizing agent **74** that is on the surface of the particle **72**. This process is called tagging. One can state that one or more of the target species **78** is tagged with the magnetic particle **72**, or equivalently that the magnetic particle **72** is tagged with the target **78**. In FIG. 7(d), the sample solution is admitted to the flat surface **70**. Target species **78** bind to the second functionalizing agent **76** on the flat surface **70**, thereby binding the magnetic particle **72** in close proximity to the flat surface **70**. This step is often followed by a rinse, such that magnetic particles **72** which are not bound to target species **78** will be removed from the

surface. In FIG. 7(e), a Hall detector **80** (which may have 1, 2 or 3 sections) is fixed to a proximal probe tip **82**, and the tip assembly is scanned over the flat surface **70**. The magnetic particle **72** is identified by detecting (and/or measuring) the fringe magnetic field from the magnetic particle **72**, and the presence of the target species **78** is thereby inferred. The number of targets **78** can be calculated from the number of magnetic particles **72** detected in a mapping of the surface **70**. This assay technique may be called "tagged particle" because the target species **78** binds to the magnetic particles **72** before binding to the surface **70**.

FIGS. 8(a)–(e) represent a variation of the process depicted with FIGS. 7(a)–(e). As before, the magnetic particle **72** is functionalized with a first agent **74**, and the surface is functionalized with a second agent **76**. Here, the sample solution containing the target species **78** is applied to the flat surface **70** [as shown in FIG. 8(c)], and target species **78** will bind to the functionalizing agent **76**. This step is often followed by a rinse. Now the separate solution with the functionalized magnetic particles **72** is applied to the flat surface **70** [as shown in FIG. 8(d)]. If target species **78** have bonded to the surface **70**, the magnetic particle **72** will bind to the target species **78**. This step is often followed by a rinse to remove unbound magnetic particles **78**. FIG. 8(e) depicts the same scanning procedure discussed in FIG. 7(e), and the presence of the target species **78** is again inferred from the detection of magnetic particles **72**. This assay technique may be called "tagged surface" because the target species **78** binds to surface **70** before binding to the magnetic particles **72**. The methods shown in FIGS. 7(a)–(e) and 8(a)–(e) can both be used, but the former is probably more popular. In the methods of FIGS. 7(a)–(e) and 8(a)–(e), a single sensor **80** (with 1, 2 or 3 sections) is used to make multiple readings, each reading producing 1, 2 or 3 electrical signals in proportion to the local magnetic field when a sensor **80** with only one section is used. A simple scalar mapping of the field is possible. Better mapping becomes available with the addition of the second and/or third section to sensor **80**.

FIGS. 9(a)–(e) depict a different measuring technique that can be used with either of the sandwich assay methods, i.e. either the "tagged particle" or "tagged surface" method. FIGS. 9(a)–(e) depict the latter assay method, but the former assay method is equally valid. In FIG. 9(a) the magnetic particles **92** are functionalized with a first agent **94**. In FIG. 9(b), a chip **100** is fabricated with an integrated array (one row or many rows) of Hall effect devices or cells. Each cell **102**, **104** and **106** has 1, 2 or 3 sections. The array may be a single row or a plurality of rows. The surface of the chip **100** is functionalized with a second agent **96**. In FIG. 9(c), the sample solution is admitted to the surface **90** of the chip **100**. If target species **98** are present, they bind to the second functionalizing agent **96**. This step is often followed by a rinse. In FIG. 9(d), the solution of magnetic particles is applied to the surface **90**. If target species **98** are bound to the surface **90** of the chip **100**, the magnetic particles **92** can bind to the targets **98**. This step is often followed by a rinse. When magnetic particles **92** bind to a target **98** as shown in FIG. 9(e), an electrical signal (1, 2 or 3 signals for 1, 2 or 3 sections) is recorded (detected and/or measured) for each cell. The presence of a magnetic particle **92** in the vicinity of a given cell **102**, **104** or **106** is determined or detected from the readings of the electrical signals. A map of electrical signals of all cells near the chip surface can be made, and the number and location of magnetic particles **92** (and therefore of targets **98**) can be inferred, thereby allowing identification of the target chemical or biological material. By contrast with the technique of FIGS. 7(a)–(e) and 8(a)

–(e), this technique involves a single measurement from multiple, integrated sensors. In practice, this technique has several benefits. It is less expensive and portable.

Arrays, such as array **60**, can be fabricated with many elements, on the order of 1000^2 to $10,000^2$, with a rapid integrated readout. Thus, the present array of vector magnetometers affords a utilitarian means for mapping tagged molecules. The array **60** can be passivated with a thin protective coating so that the object to be identified can be applied and removed, and the chip can be reused. Alternatively, even if the chip cannot be reused the cost of highly integrated arrays is relatively low. Since the time required for readout is short, e.g., on the order of 10 nanoseconds per cell, the contents of the array **60** can be read and recorded periodically, and the array **60** can be used for studies of motion for appropriate samples.

While the foregoing discussion of arrays has been made with reference to an example of a cell that measures two vector components, generalization to three vector components (as shown in FIG. **6(b)**) is straightforward and will now be apparent to one skilled in the art. Further, there are many examples where measurement of a single component of magnetic field with high spatial resolution is adequate for a given application. In that case, the present invention represents a novel application of a traditional Hall device: the use of a two-dimensional array of Hall sensors, with integrated readout, for scalar field measurements with high spatial resolution.

There are applications where an external perturbing magnetic field can be applied to the object that is the source of magnetic field to be measured. The present vector magnetometer, in any of the embodiments described above, can be used in these applications as a susceptometer, even if the perturbing field is also applied to the sensor.

An example of a susceptometer, which incorporates the present invention, is provided by the use of a vector magnetometer to sense the local field of a microscopic magnetic particle, where the vector magnetometer can be for either a single scanning magnetometer employing a single sensor **20** or an array of devices such as array **60**. For some classes of magnetic particles, a small external field develops a magnetic moment in the particle, and the axis of the magnetic dipole may be determined by intrinsic magnetic anisotropies and need not be aligned with the field.

For example, application of a field $H_x \hat{x}$ may result in a dipolar moment with field components along \hat{z} and these components would be detected by Hall sensor **33** of FIGS. **2(a)** and **2(b)**. If the resulting dipole creates fields with components along \hat{x} , the response of Hall sensor **32** could be tested for deviations from the linear response to applied field, with such a deviation indicating the presence of a local field.

The present vector magnetometer-incorporating sensor **20** has advantages over previous devices, such as a magnetoresistive (MR) sensor. As previously noted, a magnetoresistive element has sufficient field sensitivity but only over a limited range of field, and it is sensitive to inplane fields. Further, as previously described, a magnetoresistive sensor is insensitive to a \hat{z} component. Thus, a single Hall sensor, such as Hall sensor **33** of device **20**, can be adapted for use in measuring components of a magnetic field where MR sensors have no sensitivity, such as the application of in-plane fields that result in dipolar moments with substantial field components along the \hat{z} axis.

Furthermore, the present vector magnetometer can be employed to measure components where conventional MR sensors are ineffective since MR sensors have linear

response only over a narrow field range, and MR sensors cannot be used to sense local dipolar field components along the \hat{x} axis for external fields along \hat{x} that exceed a small value. Thus, MR sensors have limited use for susceptometry applied to microscopic magnetic particles. The present hybrid Hall effect vector magnetometer, although it has less field sensitivity than MR sensors, has a much larger dynamic range and has sensitivity to all field components, and is therefore a superior device for this application.

In addition, the present Hall effective devices, when adapted for use as magnetometers, have advantages of scaling as compared with MR sensors. Although both devices can be microfabricated on a small scale, the margins of reproducibility are higher for the present Hall sensors. For example, the present device can be manufactured with dimensions of 300 nm by 300 nm, with highly reproducible characteristics from device to device. Margins and yields are of particular importance in array applications, where thousands or millions of Hall devices may be used.

The present Hall devices may also be integrated with conventional MR sensors to thereby provide additional functionality. As discussed previously, magnetoresistive sensors have higher field sensitivity over a small range of field. There may be environments where higher field sensitivity over a narrow field range is required. Therefore, it may be advantageous to integrate one or more MR sensors with one or more of the present Hall devices to form a hybrid cell.

Although the invention has been described above in relation to preferred embodiments thereof, it will be understood by those skilled in the art that variations and modifications can be effected in these preferred embodiments without departing from the scope and spirit of the invention.

What is claimed is:

1. A method of identifying chemical or biological agents that have been tagged with microscopic magnetic particles and introduced onto a substantially flat surface, by measuring vector components of a magnetic field generated by the magnetic particles, said method comprising:

- mounting a Hall device on a scanning probe tip;
- generating an electrical current that flows along a first current axis of a conductive substrate of the Hall device;
- scanning the chemical or biological agents introduced onto said surface and generating a first electrical signal along a first voltage axis in response to vector components of a magnetic particle's magnetic field acting on the electrical current in said conductive substrate based on the Hall effect;
- detecting said first electrical signal;
- recording said first electrical signal; and
- mapping values of said first electrical signal with respect to magnetic fields associated with the magnetic particles.

2. The method of claim **1**, further comprising measuring said first electrical signal after detecting said first electrical signal.

- 3.** The method claim **1**, further comprising:
 - generating a second electrical signal along said second voltage axis in response to a fringe field acting on the electrical current in said conductive substrate;
 - detecting said second electrical signal;
 - recording said second electrical signal; and
 - mapping values of said second electrical signal with respect to magnetic fields associated with the magnetic particles.

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4. The method of claim 3, further comprising measuring said second electrical signal after detecting said second electrical signal.

5. The method of claim 3, further comprising;

generating an electrical current that flows along a second current axis of a third section of said conductive substrate;

scanning the chemical or biological agents and generating a fringe field at an edge of a second ferromagnetic film in response to vector components of a magnetic particle's magnetic field acting on said second ferromagnetic film, said edge of said second ferromagnetic film located on a third section of said conductive substrate adjacent to a third voltage axis of said conductive substrate, such that said fringe field is perpendicular to a second current axis;

generating a third electrical signal along said third voltage axis in response to said fringe field acting on the electrical current in said conductive substrate;

detecting said third electrical signal;

recording said third electrical signal; and

mapping values of said each electrical signal with respect to magnetic fields associated with the magnetic particles.

6. The method of claim 5, further comprising measuring said third electrical signal after detecting said third electrical signal.

7. A method of identifying chemical or biological agents that have been tagged with microscopic magnetic particles by measuring vector components of a magnetic field generated by the magnetic particles, said method comprising:

generating an electrical current that flows along a current axis of a conductive substrate forming a plurality of integrated Hall effect devices, each Hall effect device being electrically connected to each other along said current axis;

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introducing the chemical or biological agents onto said substrate;

generating a first electrical signal along a first voltage axis in response to vector components of a particle's magnetic field acting on said electrical current in said conductive substrate based on the Hall effect;

detecting each electrical signal;

measuring each electrical signal;

recording each electrical signal; and

mapping values of each electrical signal with respect to magnetic fields associated with the magnetic particles.

8. The method of claim 7, further comprising:

generating an electrical current that flows along a plurality of current axes of a conductive substrate, the conductive substrate comprising a plurality of rows of a plurality of integrated Hall effect devices, each Hall effect device of a respective current axis being electrically connected to one another along the respective current axis;

introducing the chemical or biological agent onto said plurality of rows;

generating a plurality of electrical signals along a plurality of voltage axes, respectively, in response to vector components of a particle's magnetic field acting on said electrical current in said conductive substrate;

detecting said plurality of electrical signals;

measuring said plurality of electrical signals;

recording said plurality of electrical signals; and

mapping values of said plurality of electrical signals with respect to magnetic fields associated with the magnetic particles.

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