



US006272768B1

(12) **United States Patent**
Danese

(10) **Patent No.:** **US 6,272,768 B1**
(45) **Date of Patent:** **Aug. 14, 2001**

(54) **APPARATUS FOR TREATING AN OBJECT USING ULTRA-VIOLET LIGHT**

(76) **Inventor:** **Michael J. Danese**, 22025 Creekside Ct., Cupertino, CA (US) 95014

(*) **Notice:** Subject to any disclaimer, the term of this patent is extended or adjusted under 35 U.S.C. 154(b) by 0 days.

(21) **Appl. No.:** **09/442,043**

(22) **Filed:** **Nov. 12, 1999**

(51) **Int. Cl.**⁷ **F26B 3/34**

(52) **U.S. Cl.** **34/275; 34/76; 34/202; 34/218**

(58) **Field of Search** 34/275, 276, 61, 34/73, 74, 75, 76, 77, 78, 79, 202, 218, 221, 222; 134/134, 137, 902; 414/313, 938; 427/96, 586, 126.3, 226, 229

(56) **References Cited**

U.S. PATENT DOCUMENTS

4,643,774	2/1987	Kisida et al.	134/1
4,714,086	12/1987	Kishida et al.	134/83
4,735,000	4/1988	Hayashi et al.	34/58
4,736,759	4/1988	Coberly et al.	134/134
4,738,759	4/1988	Bienvenu et al. .	
4,839,522	* 6/1989	Bourgeois et al.	34/275 X
4,882,853	* 11/1989	Schaft	34/275 X
4,984,597	1/1991	McConnell et al.	134/95
5,173,988	12/1992	Bhatia et al.	15/309.2
5,217,559	6/1993	Moslehi et al.	156/345
5,331,987	7/1994	Hayashi et al.	134/102.1
5,351,415	* 10/1994	Brooks et al.	34/389
5,443,540	8/1995	Kamikawa	34/471
5,505,785	4/1996	Ferrell	134/1
5,520,744	5/1996	Fujikawa et al.	134/11
5,542,441	8/1996	Mohindra et al.	134/95.2
5,571,337	11/1996	Mohindra et al.	134/25.4

5,634,978	6/1997	Mohindra et al.	134/2
5,651,379	7/1997	Mohindra et al.	134/95.2
5,653,045	8/1997	Ferrell	34/341
5,685,086	11/1997	Ferrell	34/61
5,685,327	11/1997	Mohindra et al.	134/95.2
5,772,784	6/1998	Mohindra et al.	134/21
5,783,790	* 7/1998	Mitsumori et al.	134/1.3 X
5,814,156	9/1998	Elliott et al.	134/1
5,849,104	12/1998	Mohindra et al.	134/25.4
5,868,150	2/1999	Mohindra et al.	134/135
5,873,947	2/1999	Mohindra et al.	134/18
5,878,760	3/1999	Mohindra et al.	134/95.2
5,884,640	3/1999	Fishkin et al.	134/95.2
5,891,256	4/1999	Mohindra et al.	134/2
5,897,844	4/1999	Amme et al.	422/186
5,909,741	6/1999	Ferrell	134/1
6,015,759	* 1/2000	Khan et al.	438/707
6,016,612	* 1/2000	Kruwinus	34/275 X
6,074,482	* 6/2000	Weber et al.	34/275 X

* cited by examiner

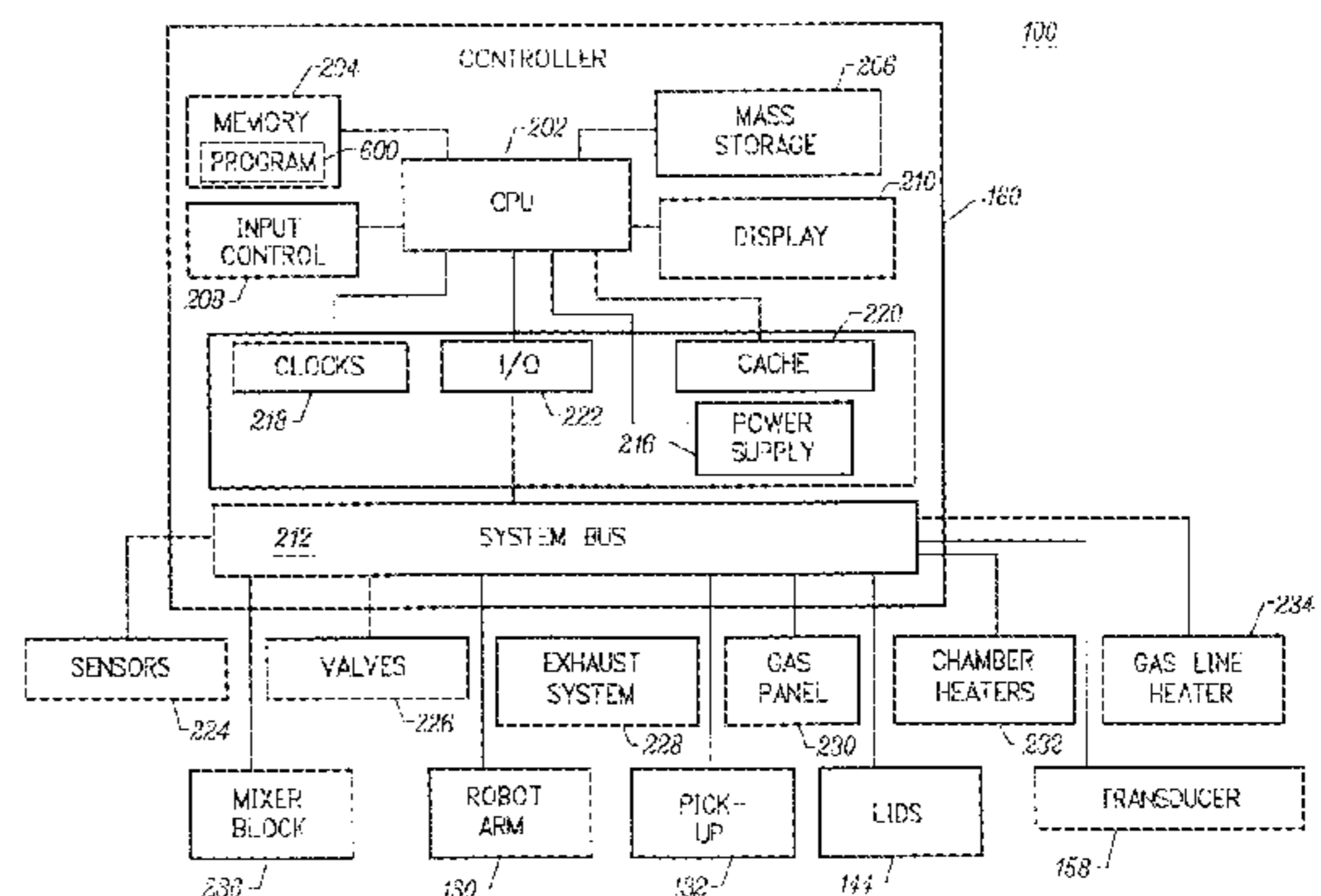
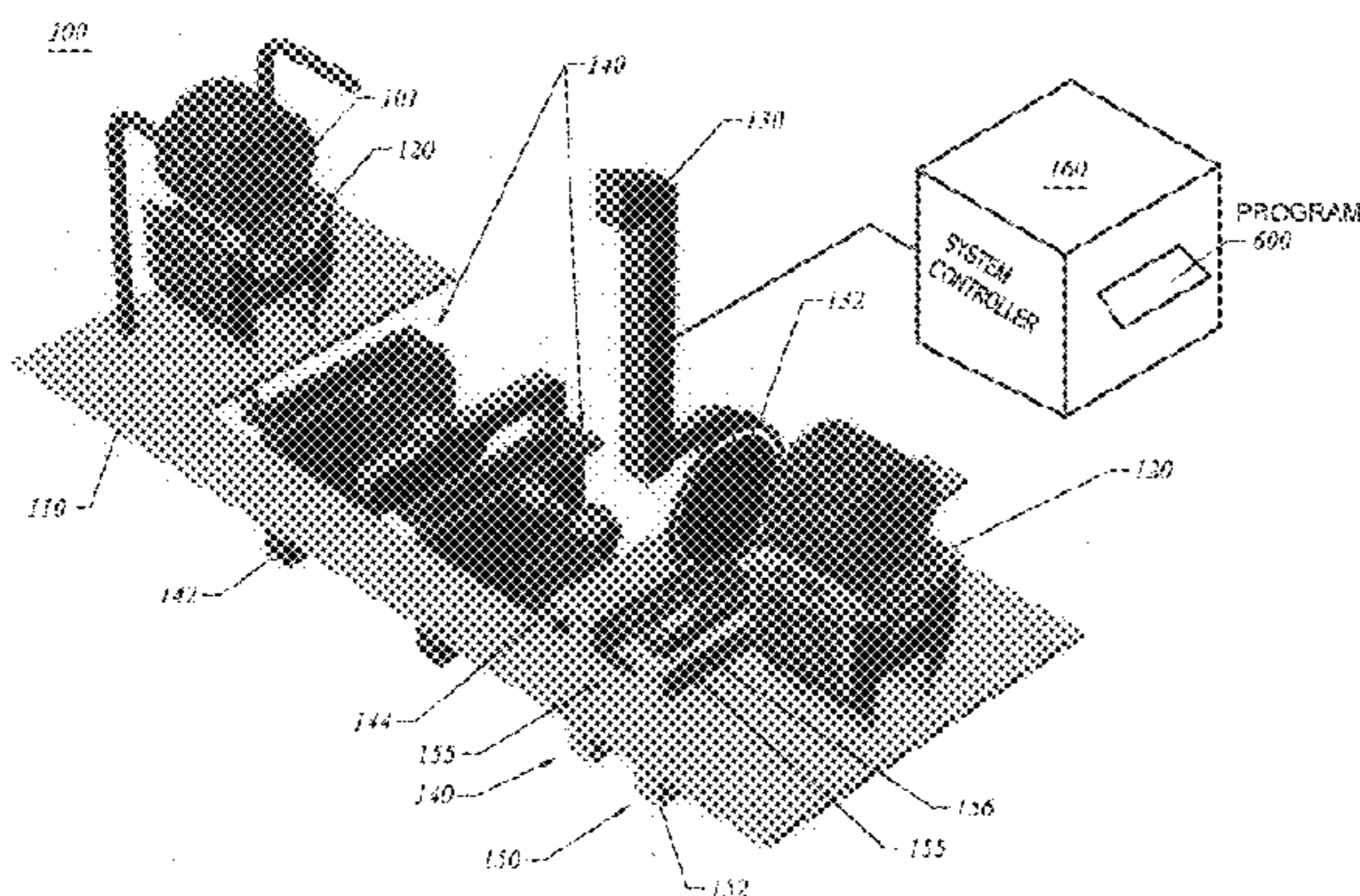
Primary Examiner—Stephen Gravini

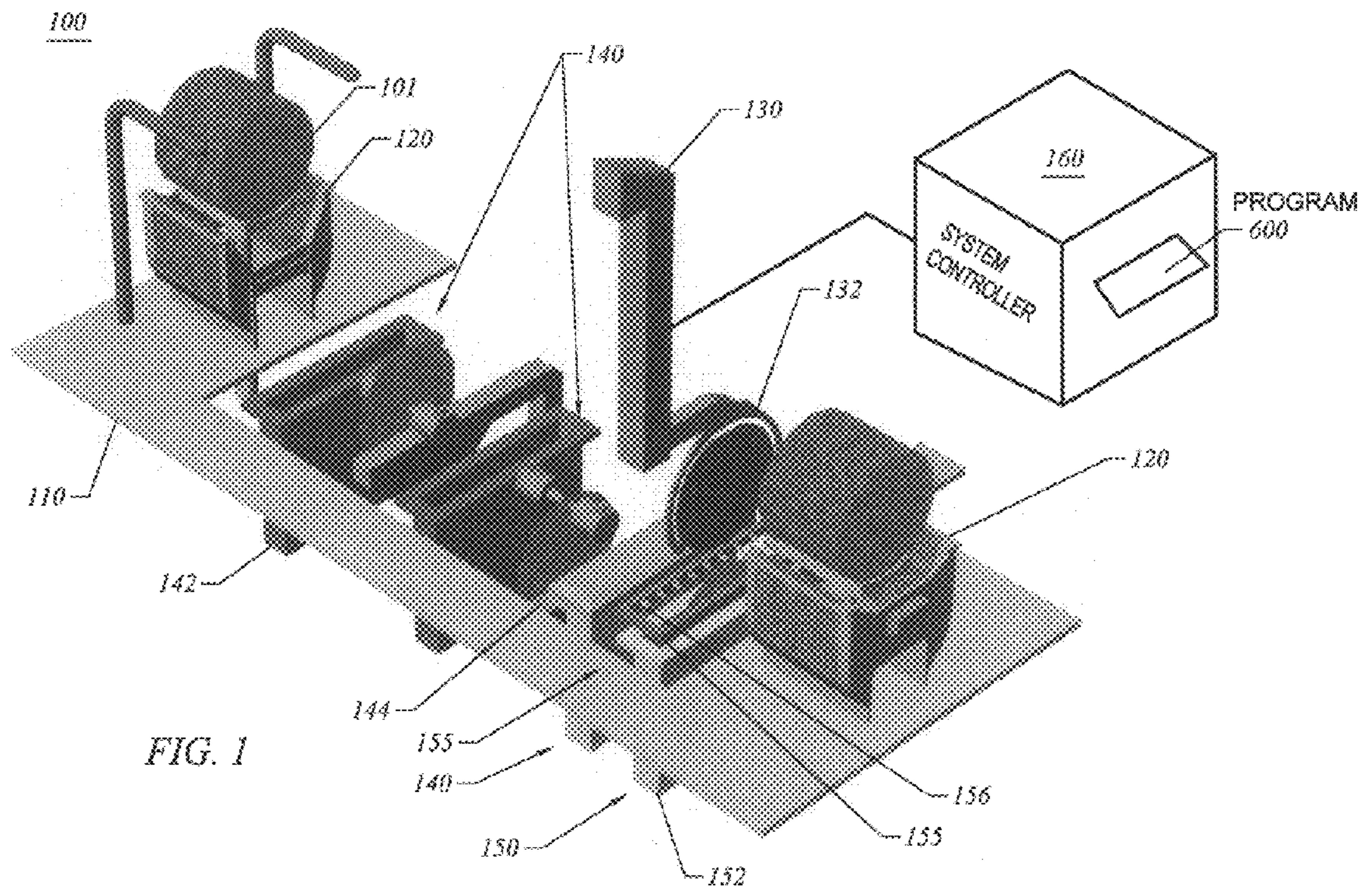
(74) *Attorney, Agent, or Firm*—Townsend and Townsend and Crew LLP

(57) **ABSTRACT**

An apparatus for processing an object with ultra-violet light is provided. The apparatus generally comprises a container, a transducer, coupled to the container; and a source of ultraviolet light configured to deliver ultraviolet light to an object disposed within said container. The UV source is configured to deliver the ultraviolet light through the vapor to process the object. The vapor and UV light react with a surface of the object to process the object. The apparatus is particularly suited to wet processing substrates in a single substrate processing system having multiple wet processing chambers configured within a process bench. The apparatus can include a robot arm having a pick-up, such as a vacuum wand, that adheres to a back side of the substrate.

18 Claims, 6 Drawing Sheets





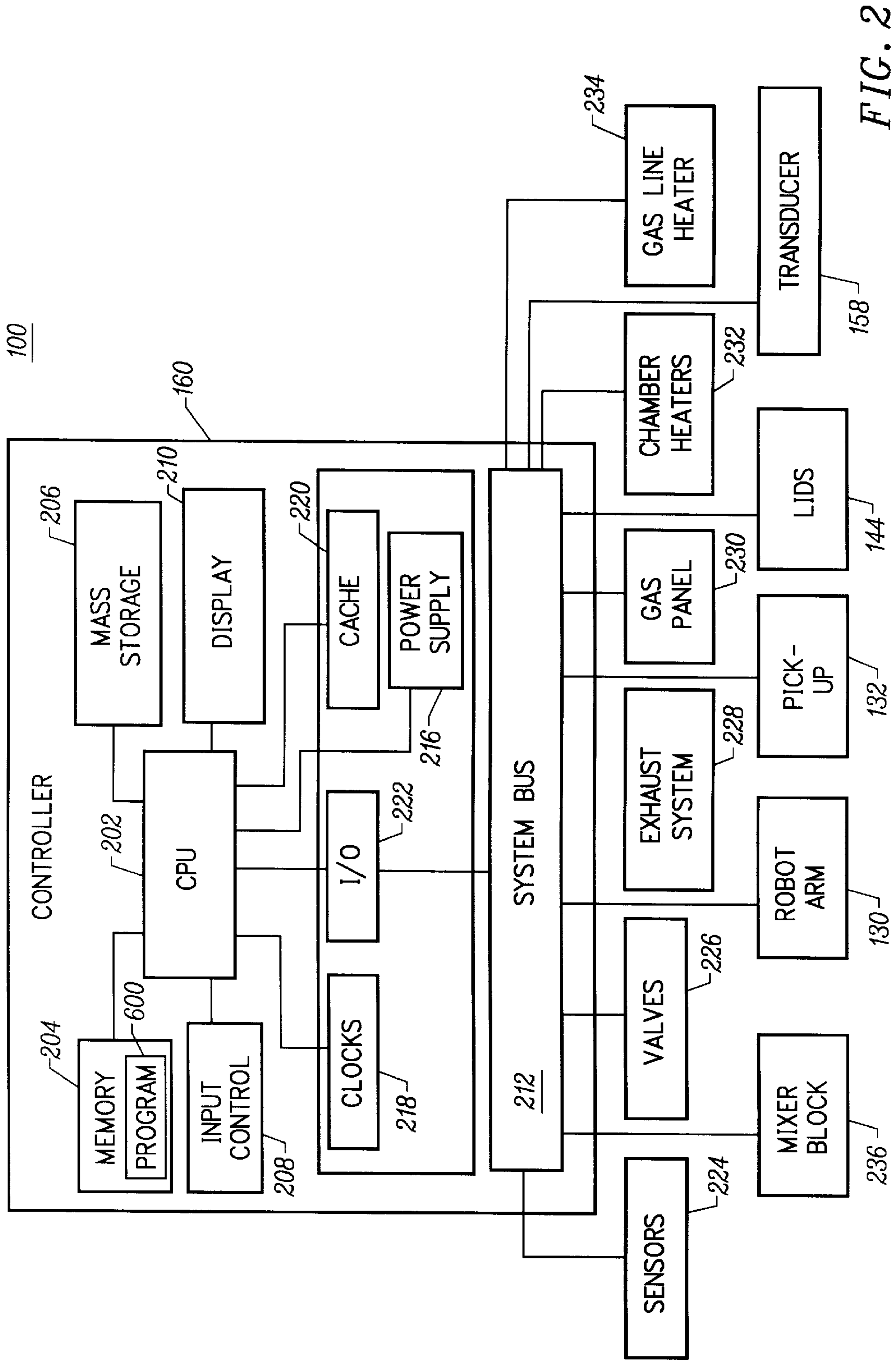


FIG. 2

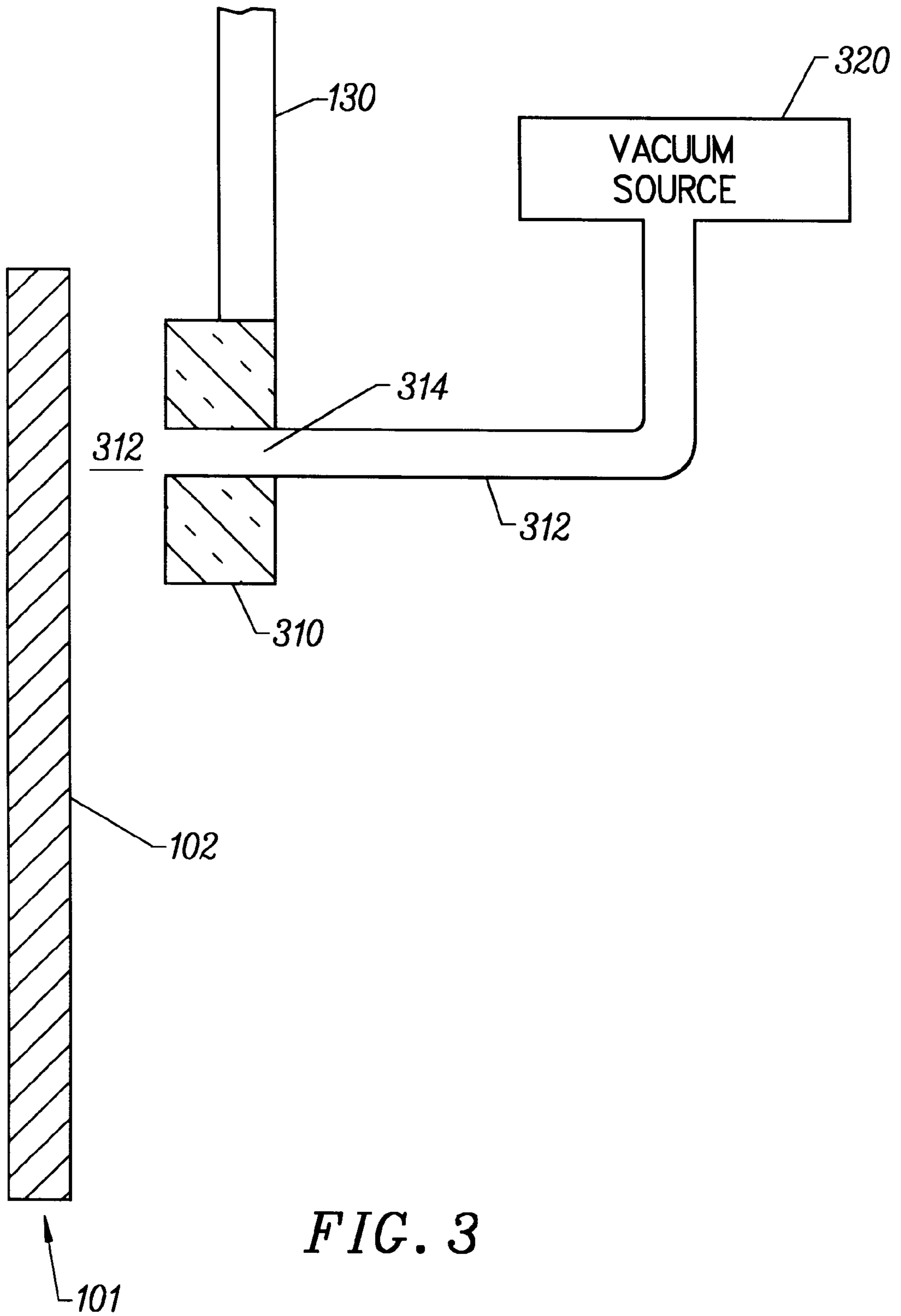


FIG. 3

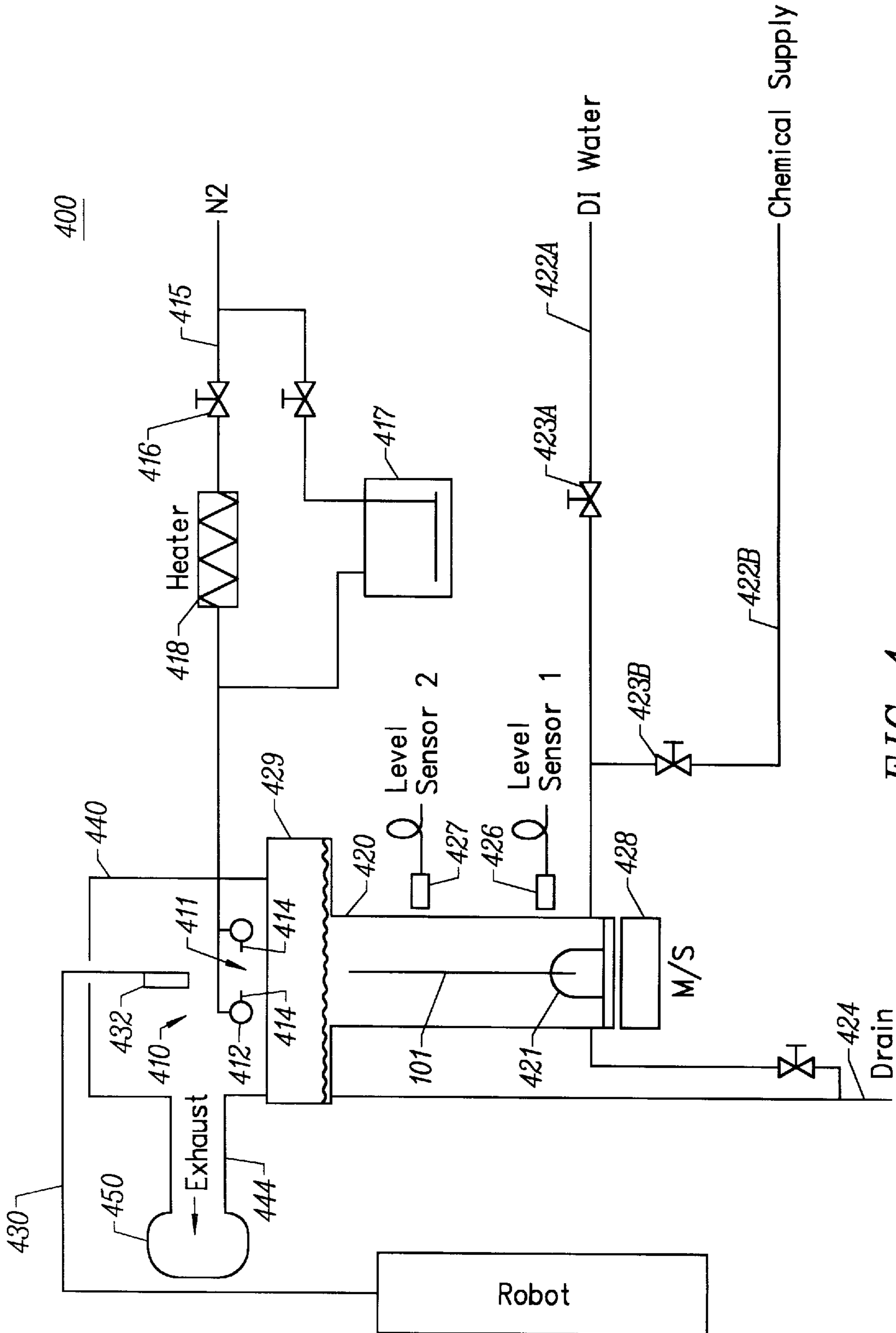


FIG. 4

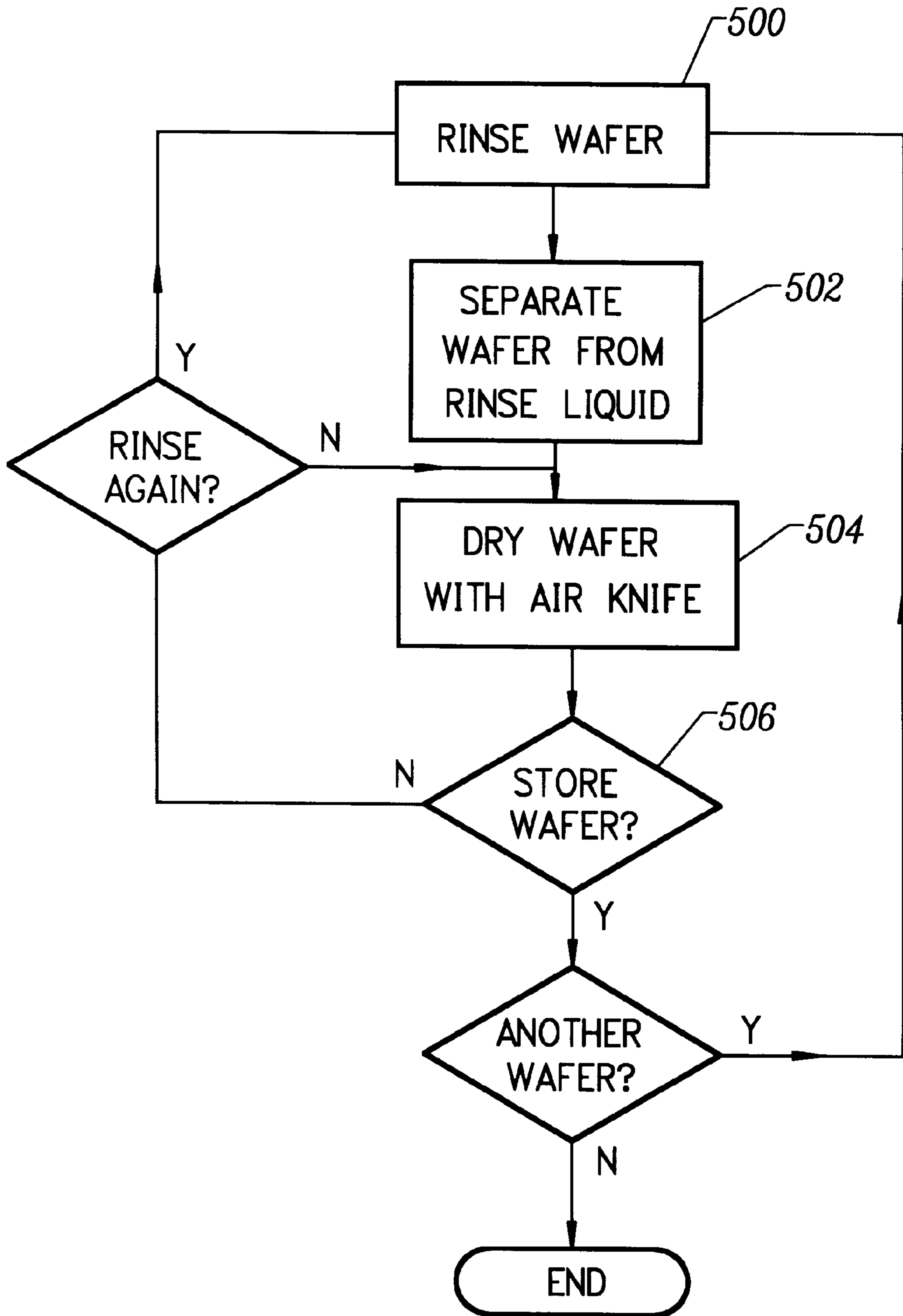


FIG. 5

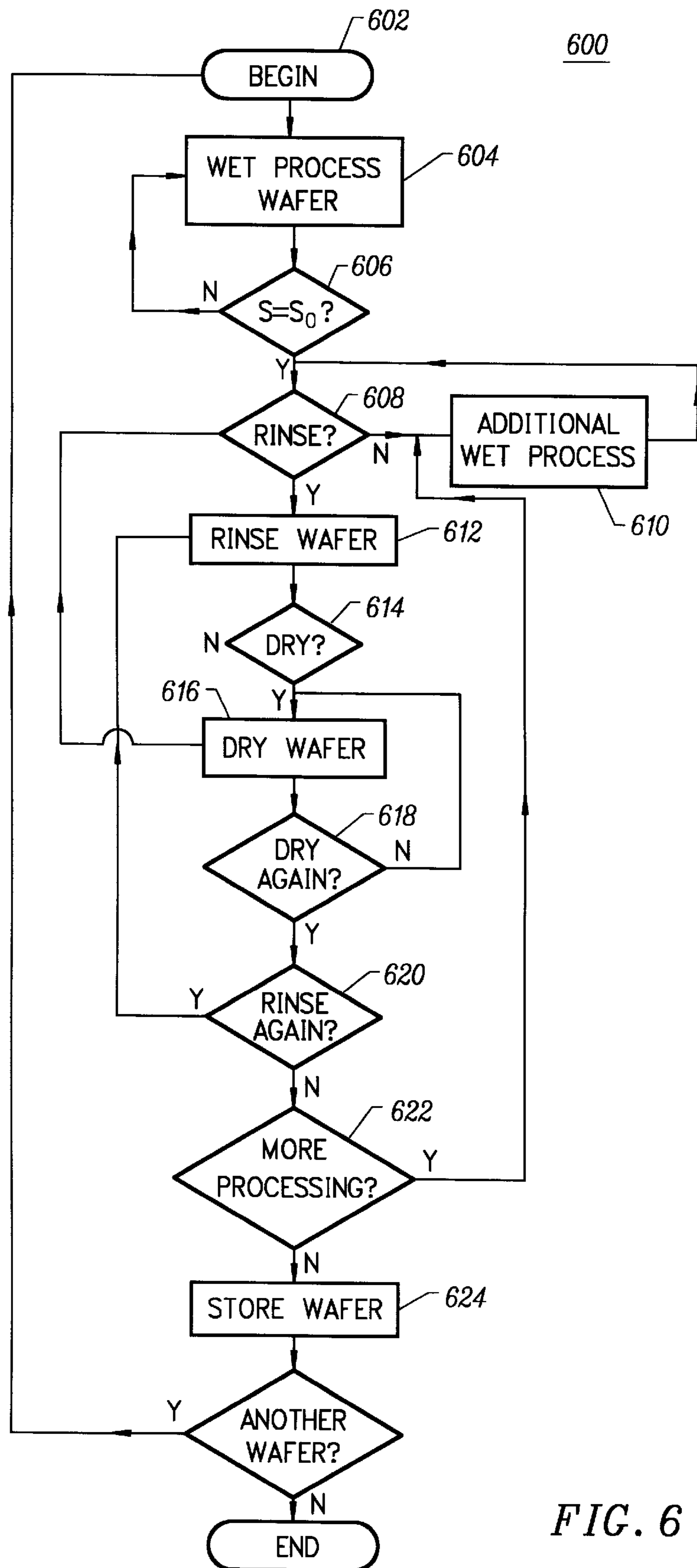


FIG. 6

APPARATUS FOR TREATING AN OBJECT USING ULTRA-VIOLET LIGHT

This application is related to U.S. patent application Ser. No. 09/439,474, entitled METHOD FOR TREATING AN OBJECT USING ULTRA-VIOLET LIGHT filed the same date as this application) in the name of Michael Danese, and to U.S. patent application Ser. No. 09/439,613, filed the same date as this application) entitled METHOD FOR DRYING AN OBJECT USING A SINGLE OBJECT TOOL in the name of Michael Danese, and to U.S. patent application Ser. No. 09/442,041, filed the same date as this application) entitled APPARATUS FOR DRYING AN OBJECT USING A SINGLE OBJECT TOOL in the name of Michael Danese, all of which are incorporated by reference herein.

BACKGROUND OF THE INVENTION

The present application generally relates to treatment of objects. More particularly, the present invention provides an improved method for processing substrates with ultraviolet light in a single substrate wet processing tool. The invention also provides for improved processing of substrates with a vapor.

In a wet chemistry process a substrate is immersed in or otherwise treated with a liquid chemical solution. Examples of wet process steps include etching, photoresist stripping, removal of oxides with acids such as hydrofluoric acid (HF) and cleaning. Substrates that are processed in this manner include semiconductor wafers, hard disk media, stepper masks, and flat panels. It is often important that cleaning and etching processes do not damage the substrate, the process apparatus, or features formed on the substrate. Also, the etching apparatus is desirably easily scaled to process many substrate sizes, including large area wafers that are 300 millimeters or more in diameter.

To process wafers efficiently, single substrate tools have been developed that allow simultaneous processing of single substrates in multiple chambers that implement different steps of the process. Such single substrate tools generally reduce the time that any given chamber remains idle. The equipment conventionally used for wet processing substrates generally includes a series of tanks or sinks containing the chemical solution into which racks of semiconductor wafers are dipped. Since the tanks are typically open to the atmosphere, airborne particulates can enter into the process solutions. Through surface tension these particles are easily transferred to the wafer surfaces as the wafers are dipped into and lifted out of the sinks. This particulate contamination is detrimental to the microscopic circuits that the wafer fabrication process creates.

To reduce particulate contamination, some wet processes use ultrasonic energy to assist wafer cleaning and drying. In an ultrasonic wafer cleaning process, for example, a non-reactive vessel or container is filled with an acidic cleaning solution such as sulfuric acid/hydrogen peroxide or hydrochloric acid/hydrogen peroxide, and the solution is ultrasonically vibrated to remove contamination from a wafer surface. Such an ultrasonic cleaning process is described in detail in U.S. Pat. No. 5,505,785 assigned to Gary W. Ferrell. The ultrasonic vibration is believed to cause an acoustic streaming of the cleaning solution, which induces a microflow of the solvent across the surface of the wafer. This induced microflow provides for quick and efficient cleaning of the wafer at reduced temperatures.

In an ultrasonic drying process wafers are dried by a mist of ultrafine droplets. Such an ultrasonic drying process is

described in detail in U.S. Pat. No. 5,653,045 assigned to Gary W. Ferrell. Typically, the wafers are immersed in de-ionized water as nitrogen-pressurized isopropyl alcohol (IPA) flows to a sonic head attached to the top of the drying chamber. The sonic head vibrates at about 100 kilohertz to produce a mist or fog of ultrafine IPA droplets having an average diameter of about 20 microns. A low-velocity gas nozzle coupled to the sonic head distributes the droplets into the drying chamber. The IPA mist settles on the surface of the de-ionized water and forms a film that partially diffuses into the water. The de-ionized water is then slowly drained from the drying chamber so that the low surface tension of the IPA film forces the de-ionized water from the surface of the wafers in a uniform sheet. After the de-ionized water has been completely drained from the drying chamber, hot nitrogen is introduced into the drying chamber to ensure drying of the wafers. Unfortunately, the slow rate at which the water is drained limits produces bottlenecks in single wafer processing tools.

Surface contaminants frequently comprise organic molecules. One technique for removing these contaminants from semiconductor wafers uses ultraviolet (UV) light to provide energy for chemical reactions such as wafer cleaning and oxide formation. Although it has long been known that ultraviolet (UV) light decomposes organic molecules, only in the last few years has UV cleaning of surfaces been explored. One such cleaning scheme is described in U.S. Pat. No. 5,814,156, assigned to UVTech Systems, Inc. In this scheme, a surface, contaminated by adsorbed hydrocarbons, is irradiated with UV light in an atmosphere of a reactive gas such as oxygen. The contaminants absorb the UV radiation and become excited. At low energy levels the bonds between the contaminant molecules and the surface tend to break and an inert gas can be used to carry away the debris. At higher energy levels some contaminant molecules tend to dissociate from the surface into free radicals that react with atomic oxygen, produced by the dissociation of ozone, to form carbon dioxide, water and nitrogen, while other contaminants tend to heat and expand quickly away from the surface.

If the UV light is produced outside the vacuum chamber, a window, typically made of quartz, couples the UV into the chamber. The window must be made thick since it must withstand a pressure difference on the order of 1 atmosphere (760 torr). Generally, the thicker the window the greater the attenuation of the UV.

In another cleaning scheme, a surface is irradiated in ambient air by laser pulses aimed normal to the surface to produce a spot size of several millimeters. Surface contaminants absorb the UV laser pulses, expand from highly localized heating, and accelerate away from the surface. The resulting particles are carried away with water or inert gas. Because this scheme takes place in ambient air, particulate contamination is a potential problem.

Dry processing in a plasma can generate a large amount of energetic UV photons via plasma afterglow emission. Such a plasma UV processing scheme is described in U.S. Pat. No. 5,217,559 assigned to Texas Instruments. These UV photons are produced in situ and can be used for photochemical processing with minimal attenuation. Unfortunately, plasma processing techniques require a large amount of process gases. Typically, only a small percentage of these process gases participate in useful chemical reactions. Hence, a large portion of the process gases is wasted. Even worse, the process gases can actually etch and damage the reaction chamber containing the plasma, necessitating frequent maintenance. Furthermore, the substrate that is

being processed is often exposed to the high temperature and energetic ions of the plasma. Semiconductor devices with fine geometry features can easily be damaged by the temperatures and ion bombardment associated with plasma processing. Further, high temperatures severely limit the kinds of processes that are available. Substrates having metal structures, polyamide structures, or soft glass structures cannot be exposed to high temperatures.

An additional drawback of known single substrate processing tools is the mechanical pick-up attached to the robot arm. Ideally, the pick-up should minimally contact the surface of the substrate. The pick-up generally has one or more "fingers" that grip the edge of the substrate. This does not present a problem for small diameter substrates such as six-inch semiconductor wafers. However, as the substrate diameter becomes larger it becomes more difficult for the pick-up to grip the wafer without bending or dropping them. Furthermore, stress applied at the edge of a substrate containing multiple thin films can cause delamination of the films. Liquid also tends to collect at edge contact points.

Furthermore, today's 300-mm wafers are very susceptible to contamination on both the front and back sides. Such wafers are generally polished on both the front and back sides. In most plasma processing techniques, however, the wafer typically rests on or adheres to a substrate support and only one side of the wafer is exposed. It would be desirable to use UV in a single wafer tool wet process since damage to the wafer can be minimized, both sides of the wafer can be exposed to UV and particulate contamination can be controlled. Unfortunately, UV light is strongly attenuated by most liquids. UV light generally penetrates only a few millimeters into water based liquid solutions. Therefore, although UV processing is now common in vacuum, plasma, or dry gas substrate processing, UV light is not normally used in wet processing.

Therefore, a need exists in the art for a fast clean and efficient method and apparatus for processing an object using with ultraviolet light a single object tool wet processing system.

SUMMARY OF THE INVENTION

According to the present invention, an apparatus for processing an object with ultra-violet light is provided. The apparatus generally comprises a container, a transducer, coupled to the container; and a source of ultraviolet light configured to deliver ultraviolet light to an object disposed within said container. A generator, coupled to the transducer, provides megasonic energy that forms a vapor from a process liquid in the container. The level of the process liquid is generally maintained below the bottom of the object while processing the object with the vapor. The UV source is configured to deliver the ultraviolet light through the vapor to process the object. The vapor and UV light react with a surface of the object to process the object.

The apparatus is particularly suited to wet processing substrates in a single substrate processing system having multiple wet processing chambers configured within a process bench. The apparatus can include a robot arm for manipulating substrates during processing. In one embodiment of the invention, the robot arm includes a pick-up, such as a vacuum wand, that adheres to a back side of the substrate. The system can also include a system controller to substantially automate the implementation of various substrate processes. The controller implements instructions in the form of a program code stored in a computer readable storage medium. The program code controls the operation of

the wet processing chamber, robot arm and other elements of the substrate wet processing system during object processing.

The present apparatus provides for fast clean and efficient processing of objects at low temperatures. These and other embodiments of the present invention, as well as its advantages and features are described in more detail in conjunction with the text below and attached figures.

BRIEF DESCRIPTION OF THE DRAWINGS

The teachings of the present invention can be readily understood by considering the following detailed description in conjunction with the accompanying drawings, in which:

FIG. 1 shows a perspective view of an exemplary wet processing system employing an aspect of the present invention;

FIG. 2 shows a block diagram of the wet processing system of FIG. 1;

FIG. 3 shows a close-up cross-section of a substrate pick-up according to an embodiment of the present invention.

FIG. 4 shows a partial cross-sectional schematic of a substrate processing apparatus of another embodiment of the present invention;

FIG. 5 shows a flow diagram of a preferred embodiment of the method of the present invention;

FIG. 6 shows a flow chart of a computer program that implements a method according to an embodiment of the present invention; and

To facilitate understanding, identical reference numerals have been used, where possible, to designate identical elements that are common to the figures.

DESCRIPTION OF THE SPECIFIC EMBODIMENTS

The present invention allows for efficient processing of objects with UV in a single object wet processing tool. A cloud or mist, formed from a process liquid, processes the object. UV light, transmitted through the cloud, further enhances processing of the object. A pick-up that manipulates the object minimizes bending stress on the object by adhering to a backside thereof.

FIG. 1 shows a schematic diagram of a wet processing system **100** in which the present invention can be practiced. This diagram is merely an illustration and should not limit the scope of the claims herein. The depicted system is illustratively a substrate cleaning system. The invention, however, is applicable to any wet processing system. The system generally comprises a bench **110**, substrate containers **120**, a robot arm **130**, a plurality of wet process chambers **140**, and a rinse/dry chamber **150**. The system **100** also includes a controller **160** for automated control of the robot arm **130**, the process chambers **140** and the rinse/dry chamber **150**.

The bench **110** is typically made of a durable chemical resistant material. This material should be relatively easy to work with and also provide suitable structural support. Only a portion of the bench **110** is shown for clarity. The bench is typically part of a larger housing that encloses the wet process chambers **140** and the rinse/dry chamber **150**.

Substrate containers **120** contain substrates **101** that are to be processed by the system **100**. In semiconductor wafer processing the wafer containers are often referred to as wafer

boats. Such wafer boats typically contain 20 or more semiconductor wafers. An exemplary wafer boat contains approximately twenty-five six-inch wafers, and has a width of about seven inches and a length of about five and one-half inches. Other than six-inch wafers, substrate containers **120** can hold smaller wafers such as five-inch, four-inch, three-inch, two-inch, and one-inch wafers. Alternatively, substrate container **120** can hold larger wafers such as eight-inch, ten-inch, twelve-inch, and greater, depending upon the application.

Robot arm **130** transfers substrates **101** between containers **120** wet process chambers **140**, and a rinse/dry chamber **150**. The robot arm **130** includes a pick-up **132** that retains a substrate **101** to facilitate transfer of a single substrate **101** at a time. Although a robot arm that transfers a single substrate is depicted and described herein, robot arms having multiple pick-ups or a single pick-up capable of handling multiple substrates at a time are considered to be within the scope of the present invention. The pick-up **132** typically grips a periphery of the substrate **101** and retains the substrate **101** by mechanical action. In a preferred embodiment of the present invention, the pick-up **132** is a vacuum wand that adheres to a backside of the substrate **101**. The term backside herein refers to the side of the substrate that does not normally require processing to form features. For example, if the substrate **101** is a semiconductor wafer, features, such as integrated circuit elements, are formed on only one side (the front side). Thus the side of the wafer on which circuit elements are not formed constitutes the backside.

Substrates **101** are processed in wet process chambers **140**. A typical process chamber includes a reservoir **142** that contains a process liquid solution and a lid **144**. Lids **144** can open and close in response to signals from controller **160**. Process chambers **140** implement such chemical processes as etching, photoresist stripping, removal of oxides, and substrate cleaning. By way of example, chambers **140** are substrate cleaning chambers. Other process chambers can also be coupled to the present cleaner such as scrubbers, chemical mechanical polish (CMP) chambers, and the like. One or more of wet process chambers **140** includes an megasonic transducer **146** and a UV source **148**. Transducer **146** is coupled to a bottom **143** of reservoir **142**. One or more UV sources **148** provide UV light through a window **149** in reservoir **142**.

After processing in wet process chambers **140**, the substrates **101** are typically rinsed and dried in rinse/dry chamber **150**. Rinse/dry chamber **150** typically includes a rinse tank **152** and a drying mechanism **154**. Rinse tank **152** contains a rinse liquid such as a solution containing deionized (DI) water. In one embodiment of the present invention, the rinse/dry chamber, the drying mechanism **154** is an air-knife. The air knife includes a manifold **155** having a plurality of nozzles **156** that direct a high velocity stream of air or other gas at the substrate **101**. The high velocity stream dries the substrate by stripping away excess liquid. Rinse chamber **150** may also include an megasonic transducer **158** and UV source (not shown).

Controller **160** produces the necessary signals to operate system **100** in accordance with the present invention. FIG. 2 shows a block diagram of processing system **100**. The system controller **160** includes a programmable central processing unit (CPU) **202** that is operable with a memory **204**, a mass storage device **206**, an input control unit **208**, and a display unit **210**. The system controller further includes well-known support circuits **214** such as power supplies **216**, clocks **218**, cache **220**, input/output (I/O)

circuits **222** and the like. The controller **160** also includes hardware for monitoring substrate processing through sensors **224** in the process chambers **140** and rinse/dry chamber **150**. Such sensors measure system parameters such as liquid temperature, pH liquid level, gas and liquid flow rates and the like. All of the above elements are coupled to a control system bus **212**.

The memory **204** contains instructions that the CPU **202** executes to facilitate the performance of the processing system **200**. The instructions in the memory **204** are in the form of program code such as a program **600** that implements the method of the present invention. The program code may conform to any one of a number of different programming languages. For example, the program code can be written in C, C++, BASIC, Pascal, or a number of other languages.

The mass storage device **206** stores data and instructions and retrieves data and program code instructions from a processor-readable storage medium, such as a magnetic disk or magnetic tape. For example, the mass storage device **206** can be a hard disk drive, floppy disk drive, tape drive, or optical disk drive. The mass storage device **206** stores and retrieves the instructions in response to directions that it receives from the CPU **202**. Data and program code instructions that are stored and retrieved by the mass storage device **206** are employed by the processor unit **202** for operating the processing system **200**. The data and program code instructions are first retrieved by the mass storage device **206** from a medium and then transferred to the memory **204** for use by the CPU **202**.

The input control unit **208** couples a data input device, such as a keyboard, mouse, or light pen, to the processor unit **202** to provide for the receipt of a chamber operator's inputs. The display unit **210** provides information to a chamber operator in the form of graphical displays and alphanumeric characters under control of the CPU **202**.

The control system bus **212** provides for the transfer of data and control signals between all of the devices that are coupled to the control system bus **212**. Although the control system bus is displayed as a single bus that directly connects the devices in the CPU **202**, the control system bus **212** can also be a collection of buses. For example, the display unit **210** input control unit **208** and mass storage device **206** can be coupled to an input-output peripheral bus, while the CPU **202** and memory **204** are coupled to a local processor bus. The local processor bus and input-output peripheral bus are coupled to form the control system bus **212**.

The system controller **160** is coupled to the elements of the processing system **200**, employed in etch processes in accordance with the present invention via the system bus **212** and the I/O circuits **222**. These elements include the following: sensors **224**, a plurality of valves **226** (for controlling gas and liquid flow), an exhaust system **228**, a gas panel **230**, robot arm **130**, pick-up **132**, process chamber lids **144**, megasonic transducers **146**, **158**, UV source **148**, one or more chamber heaters **232**, a gas line heater **234** and an optional mixer block **236** (for mixing different gases or mixing gases and liquids). The system controller **160** provides signals to the chamber elements that cause these elements to perform operations for forming a layer of copper in the subject apparatus.

Although the invention is described herein as being implemented in software and executed upon a general purpose computer, those skilled in the art will realize that it would be a matter of routine skill to select an appropriate computer system to control processing system **200**. Those of

skill in the art will also realize that the invention could be implemented using hardware such as an application specific integrated circuit (ASIC) or other hardware circuitry. As such, it should be understood that the invention could be implemented, in whole or in part, in software, hardware or both.

The present invention provides for a substrate pick-up to grip and retain a substrate **101** by a backside after wet processing. FIG. **3** depicts a close-up of such a substrate pick-up **300**. Substrate pick-up **300** is typically attached to robot arm **130** to facilitate substrate transfer. In a preferred embodiment, pick-up **300** is a vacuum wand. Pick-up **300** generally includes an adhesion pad **310** coupled to a vacuum source **320**. A vacuum line **312** typically connects vacuum source **320** to adhesion pad **310** via an orifice **314**. Vacuum source **320** is, for example, a vacuum pump of conventional type used for withdrawing fluid. Such pumps include rotary vane pumps, roots pumps, bellows type pumps, venturi effect pumps, etc. The term fluid herein is intended to mean both liquids and gases. As such, it should be understood that vacuum source **320** is not limited to pumps that withdraw gas but also includes devices such as aspirators that withdraw liquids.

Vacuum source **320** draws air or other gas from between adhesion pad **310** and a backside **102** of substrate **101**. Substrate **101** is oriented in a substantially vertical direction. As air or other fluid is drawn from a region **312** between adhesion pad **310** and a backside **102** of substrate **101** a partial vacuum is created in space **312**. Partial vacuum herein refers to a situation in which the fluid pressure in region **312** is lower than the fluid pressure in the surrounding region. As a result of the partial vacuum in region in **312**, the fluid in surrounding region forces adhesion pad **310** and substrate **101** together. Friction between adhesion pad **310** and substrate backside **102** supports substrate **101** against the force of gravity. The force of friction depends on the product of the adhering force pushing substrate **101** and adhesion pad **310** together and the coefficient of friction of the interface between substrate backside **101** and adhesion pad **310**. Although pick-up **300** is described herein as a vacuum wand, pick-up **300** is not limited herein to implementation as a vacuum wand. Alternatively, pick-up **300** can adhere to backside **102** of substrate **101** by an electrostatic or magnetic force of attraction.

Generally the greater the adhering force pushing substrate **101** and adhesion pad **310** together the greater the maximum force of friction and thus the greater weight of substrate pick-up **300** can support. Adhesion pad **310** is typically made of an elastomeric material such as Teflon. By adhering to and retaining substrate **101** in this fashion, the substrate pick-up **300** minimizes bending stress on the substrate **101**. As such, substrate **101** is less likely to break or deform as a result of handling. Furthermore, the substrate pick-up **300** of the present invention is simple in design and has no moving parts that can generate particles.

The present invention provides for apparatus for wet processing a substrate with a vapor and UV light. UV light, in this application is understood to mean electromagnetic radiation having a wavelength of between about 0.1 nanometers (nm) and about 400 nm. Although the invention is described in terms of UV light those skilled in the art will recognize that the method and apparatus of the present invention are readily adapted to substrate processing with any type of electromagnetic radiation. The method is particularly suited for radiation normally strongly attenuated by a given process chemical in the liquid state. For example, although liquid water is relatively transparent to visible

radiation having wavelengths between about 400 nm and 700 nm and radiofrequency (RF) radiation having wavelengths above about 30 cm. Nearly all other bands of the electromagnetic spectrum are strongly attenuated.

FIG. **4** depicts a substrate processing apparatus **400**. Apparatus **400** may be incorporated into processing system **100**, e.g., as part of processing chamber **140** or rinse/dry chamber **150** of FIG. **1**. Processing apparatus **400** generally includes a megasonic transducer **410** coupled to a container **420**, a robot arm **430** and one or more UV sources **440**. Substrate **101** is oriented in a substantially vertical direction while it is in container **420**. Robot arm **430** and pick-up **432** facilitate transfer substrate **101** to and from container **420**. In a preferred embodiment of the invention, pick-up **432** is a vacuum wand such as that depicted in FIG. **3**. Gases are supplied to a gas manifold **450** by gas lines **452** and valves **454**. In some applications, a vapor, such as IPA vapor, provided by a bubbler **456**, is supplied via gas lines **452**. A gas line heater **458** prevents the vapor from condensing in the gas lines. An exhaust system **460** removes gas and vapor from container **420** via an exhaust chamber **462** coupled to the container **400**.

Container **420** is, for example, reservoir **142** or, alternatively, rinse tank **152** of FIG. **1**. A substrate holder **421**, typically made of quartz, supports substrate **101** in a substantially vertical orientation in container **420** during processing. Container **420** receives process liquid **429** such as a diluent and/or process chemicals via liquid supply lines **422A**, **422B** and valves **423A**, **423B**. Process liquid **429** is removed from container **420** via drain **424**. Sensors **426** and **427** determine the level of liquid in container **420**. Other sensors (not shown, but generally indicated as **224** in FIG. **2**) monitor temperature, pH, chemical content, etc. of the liquid in container **420**. A lid **425** typically covers container **420** during processing. Lid **425** often includes a seal (not shown) so that container **420** can be sealed off from the ambient atmosphere during processing. The container **420** generally includes one or more cascade rinse weirs **429**. The lid **425** and cascade rinse weirs **429** capture liquid that would otherwise splash or overflow from container **420**. Cascade rinse weirs **429** communicate with container **420** and/or drain **424**. The liquid captured by cascade rinse weirs **429** is either returned to container **420** or drained away.

Megasonic transducer **410** includes, for example, one or more piezoelectric elements **412** that expand and contract in response to electric fields. One or more transducers **410**, typically between two and six, are arranged on the bottom of the container **420**. Transducers **410** are typically rectangular in shape having a width generally between 30 and 40 millimeters (mm) and a lengths of between 50 and 175 mm. Transducers **410** are coupled to a generator **414** via transmission line **416**. Signal generator can be a stand-alone unit coupled to a system controller or operated manually. Alternatively signal generator **414** can be part of a system controller such as controller **160** of FIG. **1**. Signal generator **414** provides electrical impulses that drive piezoelectric elements **412** at frequencies of between about 100 kHz and 1 MHz. Megasonic energy from transducer **410** is transmitted to the process liquid in the container **420**. The megasonic energy produces a dense cloud **418** from process liquid **429**. The dense cloud **418** processes the surface of substrate **101**. In a preferred embodiment, transducer **410** is coupled to a bottom of container **420** below substrate holder **421** and a level **L** of process liquid **429** is below that of a bottom **103** of substrate **101**. If the holder **421** is sufficiently thin, e.g., less than 3 mm for quartz, megasonic energy from transducer **410** passes right through holder **421** into substrate **101**.

Ultraviolet sources **440** are, for example, low-pressure mercury vapor lamps or excimer lasers. Preferably UV sources **440** provide UV light in the wavelength range between approximately 150 nm and 250 nm. UV radiation in this range is effective against organic contaminants and readily penetrates the vapor **418**. UV light shown by arrows **441** is transmitted from the sources to substrate **101** via one or more windows **442**. Window **442** is made of a material that is transparent to ultraviolet light and resistant to chemical attack. Suitable materials include, quartz, Pyrex, sapphire, and Teflon AF. Teflon AF is particularly suitable for applications that use hydrofluoric acid (HF). Although, for the sake of clarity, only a single window **442** is depicted in FIG. 4, container **420** can have two or more windows if it is desirable to illuminate the substrate **101** with UV radiation from more than one side simultaneously. For example two or more UV sources could be used, coupled to windows adjacent front and back sides of substrate **101**. Alternatively suitable optics containing beam splitters, mirrors and/or other suitable optics could be devised to direct radiation from UV source **440** to multiple sides of substrate **101**.

Since container **420** is typically at ambient atmospheric pressure (approximately 760 torr), the pressure difference between the two sides of window **442** is mostly due to process liquid **429** in container **420**. The pressure difference depends on the density and the depth of process liquid **429**. If the process liquid **429** is generally a water-based solution, the pressure difference can be much less than atmospheric pressure. For example, even if process liquid **429** in container **420** is water 100 centimeters deep, window **442** need only be able to withstand a pressure difference of about 74 torr. Consequently window **442** can be made relatively thin, and, therefore, less attenuating, compared to windows used in vacuum systems.

The method of the present invention will now be described in more detail with reference to the above described apparatus and the preferred substrate (a semiconductor wafer), diluent (water) and drying vapor (isopropanol), although it will be understood that the method can be carried out on other substrates with other suitable apparatus, and the method will be similar for other rinsing and drying fluids.

FIG. 5 illustrates a preferred embodiment of the method of the present invention. By this method, substrates such as semiconductor wafers can be processed using a single substrate tool incorporating conventional wet processing chambers. At **500** a substrate is introduced to container **420** for processing. Container **420** is filled with process liquid **429**. The process liquid can be introduced to container **420** before the substrate, after the substrate or simultaneously with the substrate. The substrate is generally oriented in a substantially vertical direction to facilitate drying and/or rinsing. Vertical orientation is implemented, for example, by robot arm **430**, pick-up **432** and/or substrate holder **421** in the container **420**. At step **510** level L of process liquid **429** is set. In the present invention, level L is generally maintained below that of the substrate during processing with ultrasound.

The process liquid used is typically dependent on the process. For an etching process, such as removal of native oxide, the liquid typically contains an acid such as HCl, HF, H₂SO₄ diluted in deionized water. In certain cleaning processes the process liquid contains an alkali such as NH₃ diluted in deionized water. In a rinse/dry process, the process liquid is generally deionized water with an alcohol vapor such as isopropyl alcohol (IPA) vapor. The concentration of

process liquid in the container **420** is controlled, for example, by valves **432A**, **423B** and drain **424**. By changing inlet flow rates for process liquid and deionized water the concentration of rinse liquid can be increased or decreased by dilution.

Once the liquid level is established relative to the substrate, processing with a vapor begins at step **520**. For example, signal generator **414** transmits a megasonic signal to the transducer **410**. Generally, megasonic refers to a frequency of 100 kHz or greater. In a preferred embodiment the signal has a frequency of about 950 kHz. The transducer **410** converts the electrical signal to megasonic energy that is coupled through container **420** to the process liquid. The megasonic energy forms vapor **418** from process liquid **429**. The vapor **418** cleans or otherwise processes the substrate **101**. Note that this type of vapor processing can be done in a sealed container with either a single substrate or multiple substrates in a batch process.

In addition to enabling the use of UV, processing the substrate with the vapor **418** reduces chemical usage. There is generally a higher chemical reactivity for a chemical vapor reacting on the surface of a substrate compared to the same chemical in the bulk liquid state. For example, an exemplary cleaning process uses a 2% HF solution as the process liquid to remove native oxide from a semiconductor substrate. Only a small amount of the HF solution, e.g., enough to fill the space below the bottom of substrate **101**, is used to process the substrate using vapor **418**. A bulk liquid process, using the same 2% HF solution, would almost fill container **420** to completely immerse the substrate.

Substrate **101** may be processed sequentially with megasonic vapor and conventional megasonic in the same chamber by simply changing liquid level L. For example, in some semiconductor wafer processes it may be desirable to perform a native oxide strip followed by rinsing and drying. Native oxide could be removed using a megasonic vapor formed from a 2% HF solution as described above. The HF solution could then be diluted with deionized water to stop the oxide strip process, e.g. by providing deionized water via valve **423A** and opening drain **424**. To rinse substrate **101**, liquid level L could then be raised by filling container **420** with deionized water while continuing to operate megasonic transducer **410**. Subsequently, IPA could be added to the solution in container **420** and liquid level L could be reduced so that substrate **101** is dried with a megasonic IPA vapor. Note that in this embodiment, the only interval between wet processing and vapor processing is the time necessary to raise or lower the liquid level.

The substrate is often processed with ultraviolet during vapor processing. If UV processing is desired UV source **440** is turned on at step **530** and processing with UV begins. The vapor **418** surrounding substrate **101** is generally less dense than process liquid **429**. Consequently, the vapor attenuates the UV less than the process liquid in the liquid state. UV processes include photoresist exposure, substrate cleaning, etching and deposition. UV processing can include an oxygen containing process gas, such as oxygen (O₂) or ozone (O₃), within the vapor. The oxygen containing process gas absorbs the UV radiation and dissociates forming atomic oxygen. The atomic oxygen reacts with the substrate to form an oxide. Alternatively, UV can be used in conjunction with NH₃ in a substrate cleaning process. Those skilled in the art will recognize that UV can be used to process a substrate through a vapor generated by means other than ultrasound. For example an atomizer, boiler, bubbler or the like could produce the vapor.

After UV processing is complete, the substrate is removed from container 420 at step 540 to another chamber, e.g., for rinsing or further processing.

Those skilled in the art would be readily able to devise a computer program to implement the present invention in a wet processing system such as that depicted in FIGS. 1 and 2. FIG. 6 is a flowchart showing the method of the invention implemented under the control of a computer program. The program 600 begins, at step 602, with the introduction of a substrate into one of the wet process chambers 140. For example the program 600 executes computer instructions that cause robot arm 130 to grab a substrate from the rack and move it to one of the wet process chambers 140. Other instructions cause the lid 144 to open and robot arm 130 to insert the substrate. A subsequently executed set of instructions retracts robot arm 130 and closes lid 144.

Next, in step 604, substrate processing begins. For example, the program 600 executes a set of computer instructions that cause certain valves 226 to open and allow process liquid to enter process chamber 140 to a desired level below the substrate 101. For a native oxide etch, a solution containing an acid such as hydrofluoric acid (HF), is typically provided to wet process chamber 140. Process gases can also be introduced to the chamber at this time.

For example, if it desired to completely immerse the substrate in container 420, level sensor 427 could be set just above the top of substrate 101. A signal from level sensor 427 would signal program 600 when the liquid level reached above the top of substrate 101. If it is desired to not immerse substrate 101 level sensor 426 could be set below the bottom of substrate 101. A signal from sensor 426 would cause program 600 to stop filling chamber 420 before the liquid level reaches the bottom of substrate 101. For vapor processing it is generally desirable to set the level of the liquid below the bottom of substrate 101.

The desired level could be a predetermined level based on the geometry of substrate 101 and chamber 140. Alternatively, level sensors 426, 427 could monitor the level. Once desired level is set, ultrasound processing commences at step 606. The program 600 signals the ultrasound generator to provide a signal having a frequency of approximately 950 kHz to the transducer. Megasonic energy from the transducer produces a vapor as described above. The program 600 monitors conditions within chamber 140 by referring, for example, to signals from one or more sensors 224. For example, at step 608, the program 600 executes computer instructions that compare the a sensor signal S indicating etch progress, such as the pH of the process liquid and/or vapor, to a predetermined signal S_0 indicating desired rate of etch. The program 600 continues processing until the sensor signal S equals the predetermined signal S_0 . Alternatively, the program 600 can continue processing for a predetermined period of time T_0 . Such timing can be accomplished by comparing T_0 to a time T measured by the clock 218.

The signal from the sensors 224 can provide feedback to adjust the rate of processing by changing one or more process parameters in such a way as to null the difference between sensor signal S and desired signal S_0 . For example, the pH of the process liquid and the vapor depend on the concentration of acid in the process liquid. The concentration of acid in the process liquid can be controlled by controlling the flow of acid and deionized water to the chamber with valves 226. If the actual pH of the process liquid is too low, program 600 can direct valves 226 to increase the flow of acid or decrease the flow of deionized water to process chamber 140.

Once the desired process conditions are established, UV vapor processing commences at step 610. The program 600 signals the UV source to turn on. In addition, the program 600 may set the desired UV intensity and, in the case of tunable UV source, the desired wavelength or range of wavelengths. UV processing continues until a desired processing condition has been reached or a predetermined amount of time has elapsed.

Once processing is complete, substrate is removed for subsequent processing at step 612. Subsequent substrate processing can proceed directly to a rinse step 614 or another wet process. Step 612 can include any type of wet process including a UV wet process in the same chamber as steps 603–610. For example, after processing the front side of substrate 101 the robot arm 130 and pick-up 132 can turn substrate around and replace it in process chamber 140 so that UV source 148 can process the back side. Alternatively, the process of step 612 can occur in a different chamber than the process of steps 603–610. After the desired sequence of wet process steps has been executed, the program 600 executes, at step 612, computer instructions that signal the robot arm 130 to remove the substrate from the process chamber 140 and transfer the substrate to the dry/rinse chamber 150 for rinsing and drying.

Rinse step 614 includes, for example, a set of instructions that cause rinse tank 152 to fill with rinse liquid. For example, the program 600 executes a sequence of instructions that open one or more valves 226 that cause deionized water and/or other liquids to enter rinse tank 152. Note that rinse tank 152 can be filled before the substrate is placed into rinse tank 152 or afterwards. Signals from the program 600 start and stop the flow of rinse liquid into the rinse tank 152. Additional instructions may optionally cause transducer 158 to couple sonic energy to the rinse liquid and/or substrate. Rinse can proceed for a predetermined period of time as measured by signals from clock 218.

Once the rinse step 614 is completed, the program 600 decides at step 616 whether to initiate a drying step 618 or repeat rinse step 614. Drying step 618 includes instructions that cause the substrate to be separated from the rinse liquid. Such instructions, for example, cause the robot arm to grip and lift the substrate out of the rinse tank 152. Alternatively program 600 could issue instructions that cause a drain to open and allow rinse liquid to drain away from the substrate. In a preferred embodiment of the invention, program 600 issues instructions to open drain for a short period of time to lower the liquid level in the rinse tank 152. The robot arm 130 then moves pick-up 300 into proximity to an exposed portion of the substrate backside. Substrate pick-up 300 then adheres to the substrate backside by vacuum action as described with respect to FIG. 3 above. The robot arm then lifts the substrate out of the rinse tank 152. Once the substrate is separated from the rinse liquid, program 600 dries the substrate by moving the substrate past a gas stream issuing from the nozzles 156 of the air knife 154. For example, program 600 issues a set of instructions that cause the robot arm to lift the substrate through the manifold 155 while streams of gas are directed against both the front and back sides of the substrate.

After drying, the program 600 decides, at step 620, whether or not to repeat the dry step 618. If drying is not to be repeated, program 600 decides at step 624 whether to repeat rinse step 614 or proceed with processing. If, at step 622, the program decides that additional wet processing is to proceed on the same substrate, program 600 issues instructions to return the substrate to one of the wet processing chambers 140 at step 612. If wet processing is complete,

program **600** issues instructions to place the processed substrate in a storage rack at step **626**. At step **628** program **600** decides whether to begin the process over with a new substrate at step **602** or end at step **630**.

Although program **600** has been described herein in terms of wet process steps alone, those skilled in the art will recognize that dry process steps such as chemical vapor deposition (CVD), physical vapor deposition (PVD) dry etch, etc. can be included within the present invention. Furthermore, the invention is not limited to practice by a single wet process system or cluster tool. Substrates can be transferred, for example, from one wet process system, such as an etch system, to a dry process system, such as a deposition system, and then to another wet process system such as chemical mechanical polishing (CMP). Furthermore the various embodiments of the present invention can be used in processing substrates such as flat panel displays, stepper masks and hard disk media.

Although various embodiments, which incorporate the teachings of the present invention, have been shown and described in detail herein, those skilled in the art can readily devise many other varied embodiments that still incorporate these teachings.

What is claimed is:

1. A apparatus for processing an object, comprising:
 - a container including a vapor chamber;
 - a transducer, coupled to said container; and
 - a source of ultraviolet light configured to deliver ultraviolet light to an object disposed within said container vapor chamber.
2. The apparatus of claim 1, further comprising a megasonic generator coupled to said transducer.
3. The apparatus of claim 1, wherein said transducer is coupled to a bottom of said container.
4. The apparatus of claim 1 wherein said source of ultraviolet light is configured to deliver said ultraviolet light through said vapor.
5. The apparatus of claim 1 wherein said container includes a window disposed between said source of ultraviolet light and the object.
6. The apparatus of claim 1 further comprising a source of ozone coupled to said container.
7. The apparatus of claim 1, wherein said container is part of a wet process chamber.
8. The apparatus of claim 7, wherein said wet process chamber is configured to process a single substrate.
9. The apparatus of claim 7, wherein said wet process chamber is configured to process multiple substrates simultaneously.
10. The apparatus of claim 7, wherein said wet process chamber further comprises a lid sealably connected to said container.
11. The apparatus of claim 7, wherein said wet process chamber is an etch chamber, a photoresist stripping chamber, an oxide removal chamber, or a substrate cleaning chamber.
12. A substrate processing system for processing a substrate comprising:

a bench
one or more wet process chambers disposed within said bench, wherein at least one of said one or more process chambers includes:

- a container
- a transducer, coupled to said container, said transducer being configured to form a vapor from a liquid in said container; and
- a source of ultraviolet light configured to deliver ultraviolet light to a substrate disposed within said container.

13. The substrate processing system of claim **12**, wherein said container is configured to process a single substrate.

14. The substrate processing system of claim **12** further comprising a robot arm having a pick-up that adheres to a back side of a substrate.

15. The substrate processing system of claim **14**, wherein said pick-up is a vacuum wand.

16. The substrate processing system of claim **14** further comprising a system controller coupled to said transducer, said source of ultraviolet light said robot arm and said pick-up.

17. The substrate processing system of claim **16** wherein said system controller contains a computer readable storage medium having program code embodied therein for controlling the substrate processing system in accordance with the following:

- introducing said substrate to said container;
- introducing a process liquid to said container to a level below that of said substrate;
- applying megasonic energy to said transducer to form a vapor from said process liquid;
- processing the substrate with said vapor; and
- exposing the substrate to ultraviolet light through said vapor.

18. A substrate processing system, comprising:

- a bench
- one or more wet process chambers disposed within said bench, at least one of said one or more process chambers includes a container and a transducer coupled to said container;
- a robot arm having a pick-up; and
- a system controller, coupled to said transducer, said chamber and said robot arm, wherein said system controller contains a computer readable storage medium having program code embodied therein for controlling the substrate processing system in accordance with the following:
 - supporting the object above a level of a process liquid in said container; and
 - applying megasonic energy to said process liquid with said transducer to form a vapor that processes the object.