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### (12) United States Patent

Goto et al.

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(45) Date of Patent:

Apr. 24, 2001

# (54) MICROPROCESSOR WITH REDUCED INSTRUCTION SET LIMITING THE ADDRESS SPACE TO UPPER 2 MBYTES AND EXECUTING A LONG TYPE REGISTER BRANCH INSTRUCTION IN THREE INTERMEDIATE INSTRUCTIONS

(75) Inventors: Masaru Goto, Saitama; Hiroaki

Miyachi, Tokyo; Yukihiro Sakamoto,

Kanagawa, all of (JP)

(73) Assignee: Sony Corporation, Tokyo (JP)

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patent is extended or adjusted under 35

U.S.C. 154(b) by 0 days.

(21) Appl. No.: **09/096,584** 

(22) Filed: **Jun. 12, 1998** 

### (30) Foreign Application Priority Data

Jun.	20, 1997	(JP) 9-164358
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(52)		

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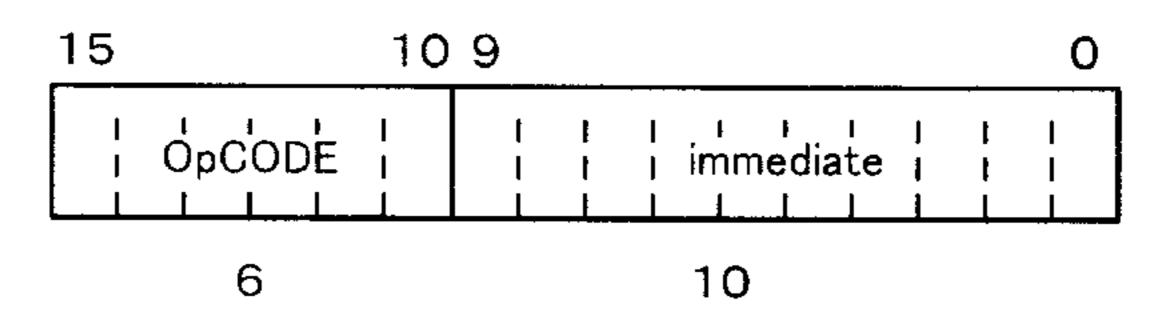
<sup>\*</sup> cited by examiner

Primary Examiner—Meng-Al T. An Assistant Examiner—Nabil El-Hady (74) Attorney, Agent, or Firm—Ronald P. Kananen; Rader, Fishman & Grauer

### (57) ABSTRACT

A 32-bit RISC processor is disclosed. The bit length of the instruction set is fixed to 16 bits. SLIL and SLIH instructions that cause the address space of 4 Gbytes to be limited to upper 2 Mbytes and that execute a long type register branch instruction are provided. Thus, a register branch instruction can be executed with three instructions rather than five instructions unlike with a related art reference.

### 12 Claims, 16 Drawing Sheets

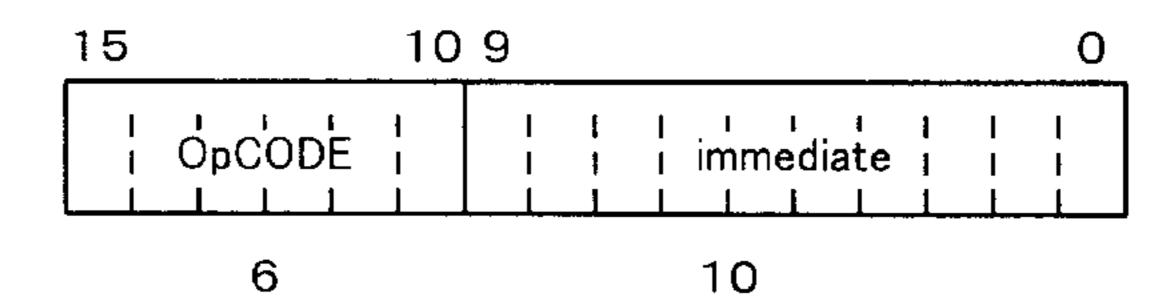


<FORMAT>

SLIL, #imm10

### <DESCRIPTION>

LOADS THE VALUE OF AN IMMEDIATE TO THE ACC CORRESPONDING THE BYTE POSITION BP. STORES THE CONTENT OF NON-DESIGNATED BYTE OF THE ACC.



<FORMAT>

SLIH, #imm10

### <DESCRIPTION>

LOADS THE VALUE OF AN IMMEDIATE TO THE ACC CORRESPONDING THE BYTE POSITION BP. STORES THE CONTENT OF NON-DESIGNATED BYTE OF THE ACC.

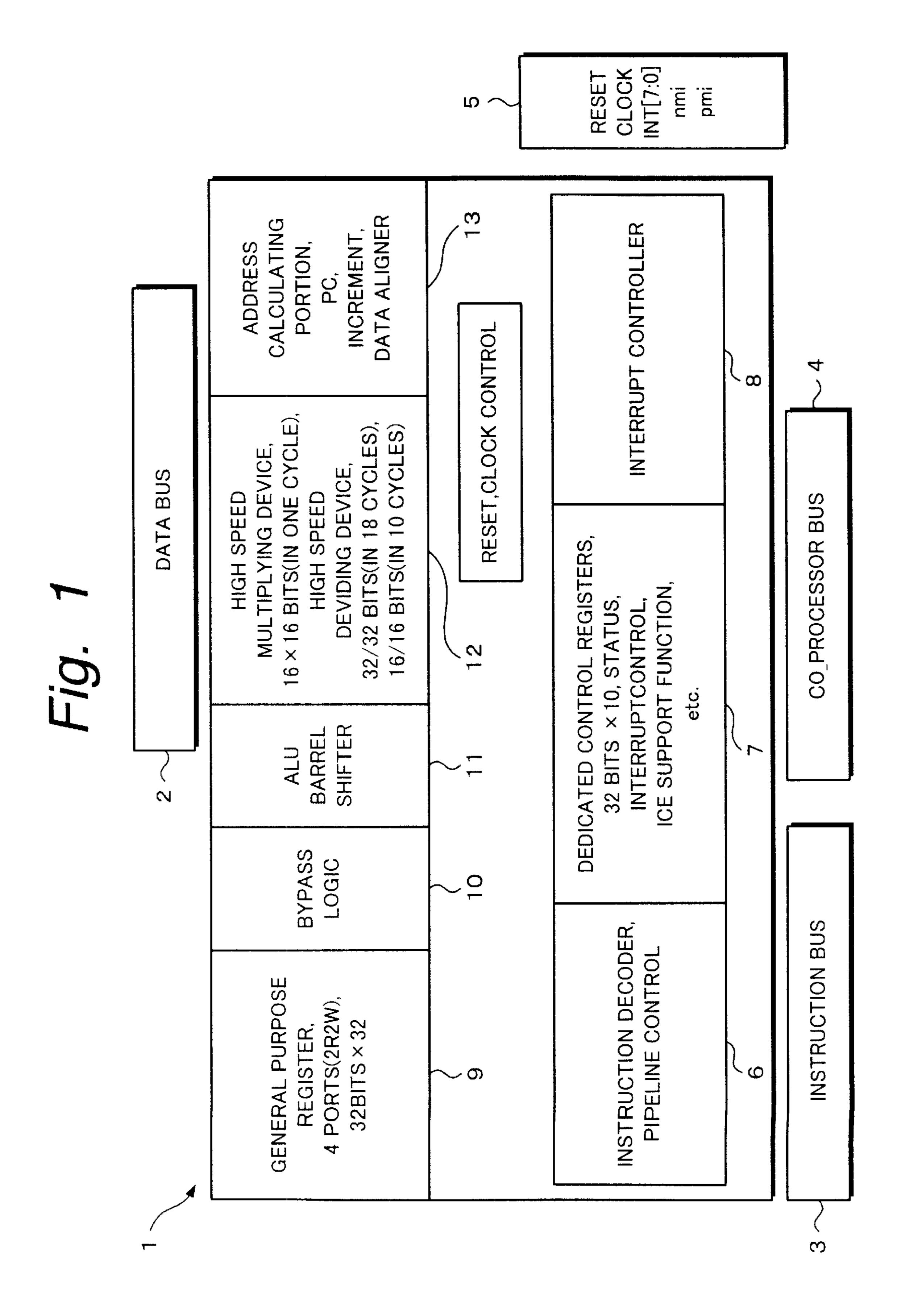


Fig. 2

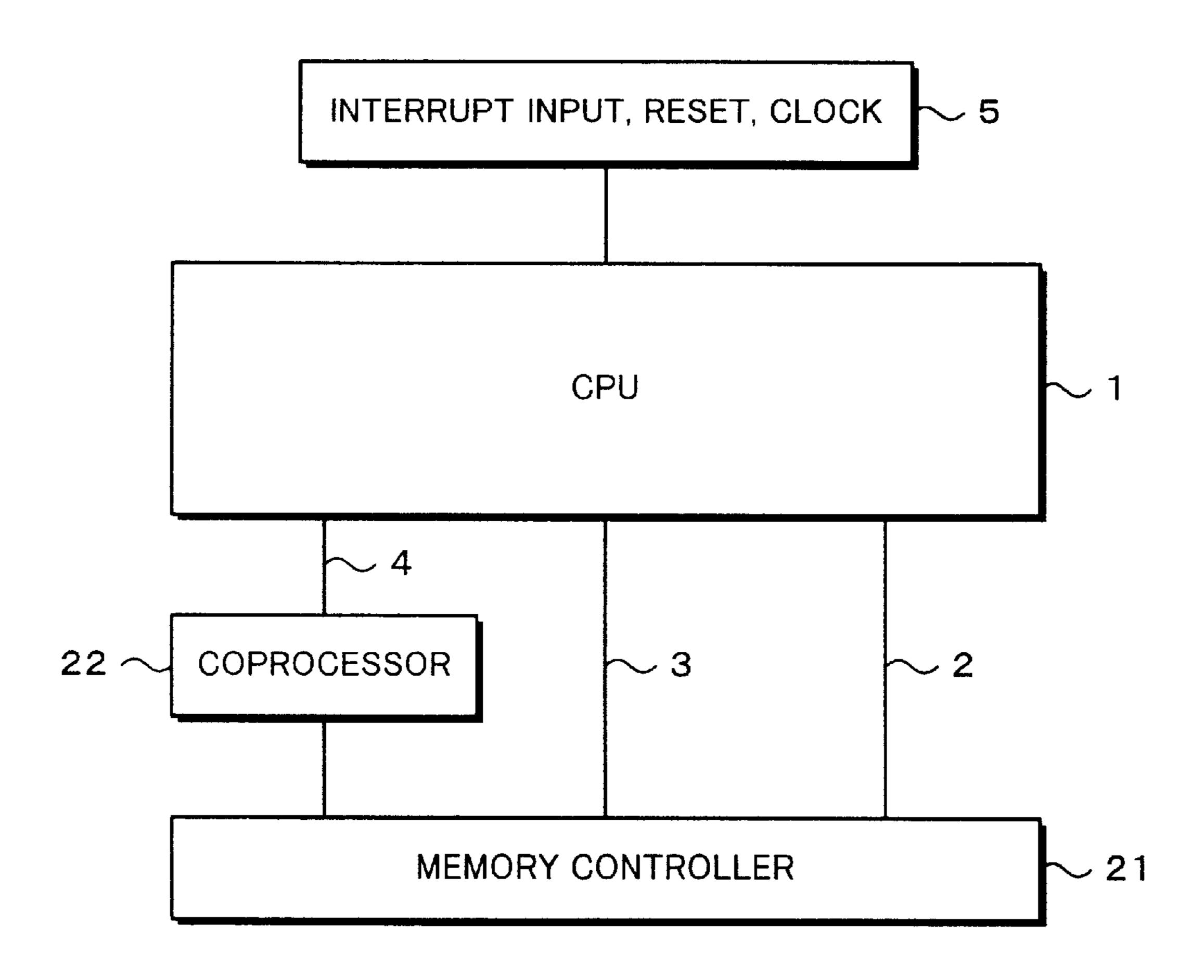


Fig. 3

Sheet 3 of 16

### CPU REGISTERS GENERAL PURPOSE REGISTERS

31	0
RO	
R1	ACC
R2	
R3	
R4	·
R5	
R6	
R7	
R8	
R9	
R10	
R11	
R12	
R13	_
R14	
R15	
R16	
R17	
R18	
R19	<del></del>
R20	
R21	
R22	
R23	
R24	
R25	··- ·· - · - · · · · · · · · · · · · ·
R26	·
R27	
R28	
R29	······································
R30	SP
R31	ISP

### MULTIPLY/DIVIDING REGISTERS

31		0
	HI	- "·
	LO	

### Fig. 4

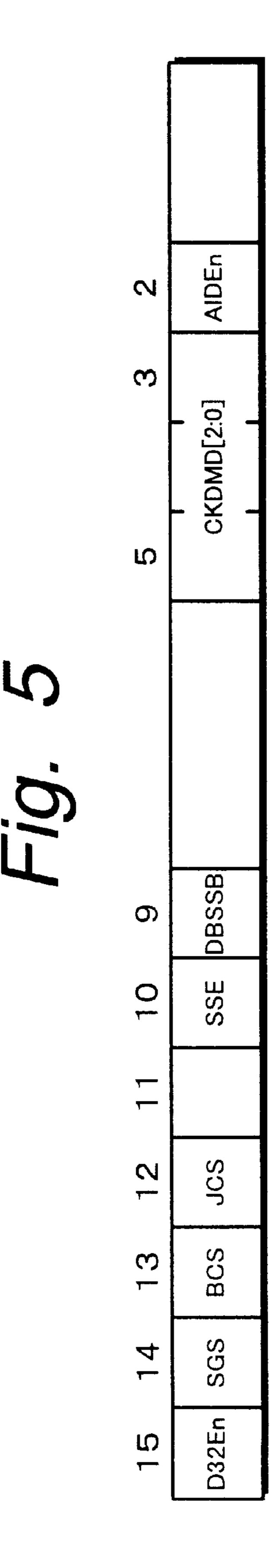
### COPROCESSOR REGISTERS

Cop0 REGISTERS
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Apr. 24, 2001

### Cop1 REGISTERS

31	0	31	0	31	0	31	0
G0	SR	C0		GO		CO	
G1	MCR	C1		G1		C1	
G2	IBR	C2		G2		C2	
G3	ICR	C3		G3		С3	
G4	IMR0	C4		G4	DABR0	C4	
G5	IMR1	C5		G5	WDBR0	C5	
G6	JBR	C6		G6	WDMR0	C6	
G7		C7		G7	DBCR0	C7	
G8		C8		G8	DBRR0	C8	
G9		C9	· · · · · · · · · · · · · · · · · · ·	G9	FMWR	C9	
G10	IBP0	C10		G10	DABR1	C10	
G11	IBP1	C11		G11	DAMR1	C11	
G12	IBP2	C12		G12	WDBR1	C12	
G13		C13		G13	WDMR1	C13	
G14		C14		G14	DBCR1	C14	• 10
G15		C15		G15	DBRR1	C15	· · · · · · · · · · · · · · · · · · ·
G16		C16		G16		C16	
G17		C17		G17		C17	
G18		C18		G18		C18	
G19	-	C19		G19		C19	
G20		C20		G20		C20	
G21		C21		G21		C21	
G22		C22		G22		C22	
G23		C23		G23		C23	
G24		C24		G24		C24	<u> </u>
G25		C25		G25		C25	
G26		C26		G26		C26	
G27		C27		G27		C27	
G28		C28		G28		C28	
G29	•	C29		G29		C29	
G30		C30		G30		C30	<u> </u>
G31		C31		G31		C31	



Apr. 24, 2001

US 6,223,275 B1

SPECIAL	JABPO	*	JAL*	RR	F.	COMPU	SLIH
H0000	0400H	H0080	H0000	1000H	1400H	1800H	1C00H
ADD	ADDU	SUB	SUBU	AND	OR	XOR	NOR
200H	2400H	2800H	2C00H	3000H	3400H	3800H	3C00H
SLIL	COPI	LSI	LSIU	ADDSI	ADDSIU	ADDC	SBB
4000H	4400H	4800H	4C00H	5000H	5400H	5800H	5C00H
SLL	SRL	SRA	SLLV	SRLV	SRAV		Id7
H0009	6400H	H0089	H0029	H000L	7400H	7800H	7C00H
LB	MHJ	ΓM	LBU	COMPI	COMPIU	COMP	MOV
H0008	8400H	H0088	8C00H	900H	9400H	9800H	9C00H
SB	SHW	SW	LHWU	MULT	MULTU	) I	DIVU
A000H	A400H	A800H	AC00H	B000H	B400H	B800H	ВСООН
LWC0	LWC1	MFC0	MTC0	BEQ/BZ*	BNE/BNZ*	BLT*	BGE*
C000H	C400H	C800H	CC00H	D000H	D400H	D800H	DC00H
SWC0	SWC1	MFC1	MTC1	BLE* BBE*	BGT* BAB*	BLTAL* BBLAL*	BGEAL* BAEAL*
E000H	E400H	E800H	EC00H	F000H	F400H	F800H	FC00H
					PC relative is	is Rxx, xx is sa	same nimonic.

Apr. 24, 2001

= 6b000000

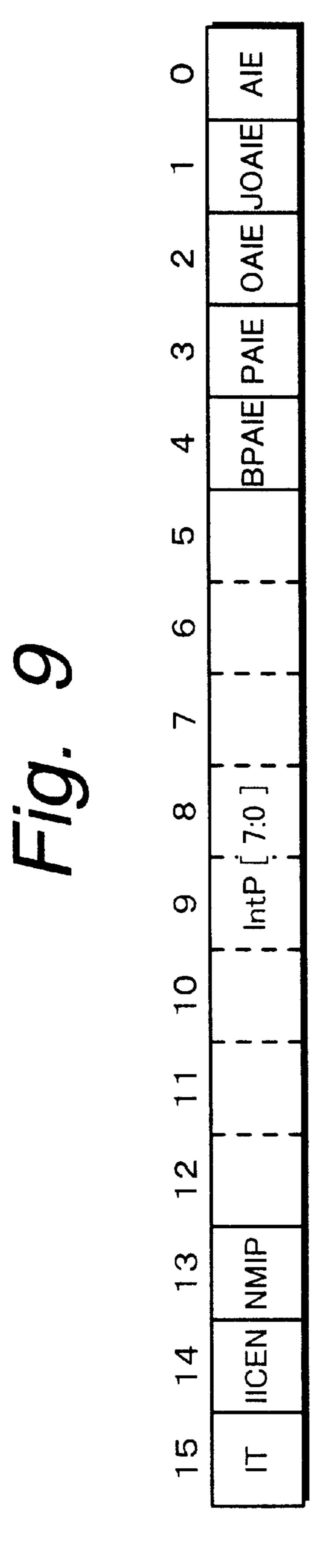
SPECIAL [ 15:10 ]

000FH EXS 0017H 03E7H 03C6H 000EH 001EH 0016H MFLO EXU RET **DBREAK** BREAK **H**0000 03E5H 001DH 03F5H MTH BTS SYSCALL 001CH 000CH 03E4H 0014H MFH XCB BT JGEALR JAEALR 0003H 000BH 001BH 0013H **EXHS** JBER JLER BS JLTR JBR/JCR JETALF JBALR 000AH 0012H XCHW 0012H 0002H **EXHZ** JGER JAER/JNCR 0011H JNER/JNZR JNER/JNZR SLEEP H6000 0001H 0019H JLR JGTR JAR 0010H H0000 0008H H H

T100.

CTC1	CFC1						
4400H	4401H	4402H	4403H	4404H	4405H	4406H	4407H
4408H	4409H	440AH	440BH	440CH	440DH	440EH	440FH
4410H	4411H	4412H	4413H	4414H	4415H	4416H	4417H
4418H	4419H	441AH	441BH	441CH	441DH	441EH	441FH

Apr. 24, 2001



### Fig. 10

INTERRUPT	VECTOR ADDRESS OFFSET	CPU SPAC	E: INSTRUCTION/DATA	\ 4
PMI NMI	00H 04H	FFFFE60H	RESET ADDRESS	
CpU0	08H	FFFFFE00H	VECTOR ADDRESS	
CpU1	0CH			
SYSBK	10H			
BK	14H			
DBK	18H			
OVF	1CH			
SStep	20H			
IBP0	2CH			
IBP1	30H			
IBP2	34H			
Exint0	40H			
Exint1	44H			i
Exint2	48H			
Exint3	4CH	0000000H		
Exint4	50H	000000011		
Exint5	54H			
Exint6	58H		64 WORDS I/O	
Exint7	5CH			; 
				4

RESET ADDRESS = FFFFE60H

VECTOR ADDRESS = { IBR [ 31:8 ], VECTOR ADDRESS OFFSET }

IBR [31:8] = FFFFFEH (INITIAL VALUE)

### US 6,223,275 B1

### Fig. 11

### TYPES OF INTERRUPTS AND PRIORITY

Apr. 24, 2001

HIGH	INTERRUPT	VECTOR ADDRESS OFFSET
<b>†</b>	SStep (Single Step)	20H
	PMI	00H
	NMI	04H
	CpU0 (Coprocessor 0)	08H
	CpU1 (Coprocessor 1)	0CH
ĺ	SYSBK	10H
	DBK	14H
	OVF (Over Flow)	18H
	BK	1CH
	IBP0 (Instruction break 0)	2CH
	IBP1 (Instruction break 1)	30H
	IBP2 (Instruction break 2)	34H
	Exint0	40H
	Exint1	44H
	Exint2	48H
	Exint3	4CH
	Exint4	50H
	Exint5	54H
	Exint6	58H
₩	Exint7	5CH
LOW	VECTOD ADDDESC - (100 f 31.0	DI MECTOD ADDDESS OFFSET

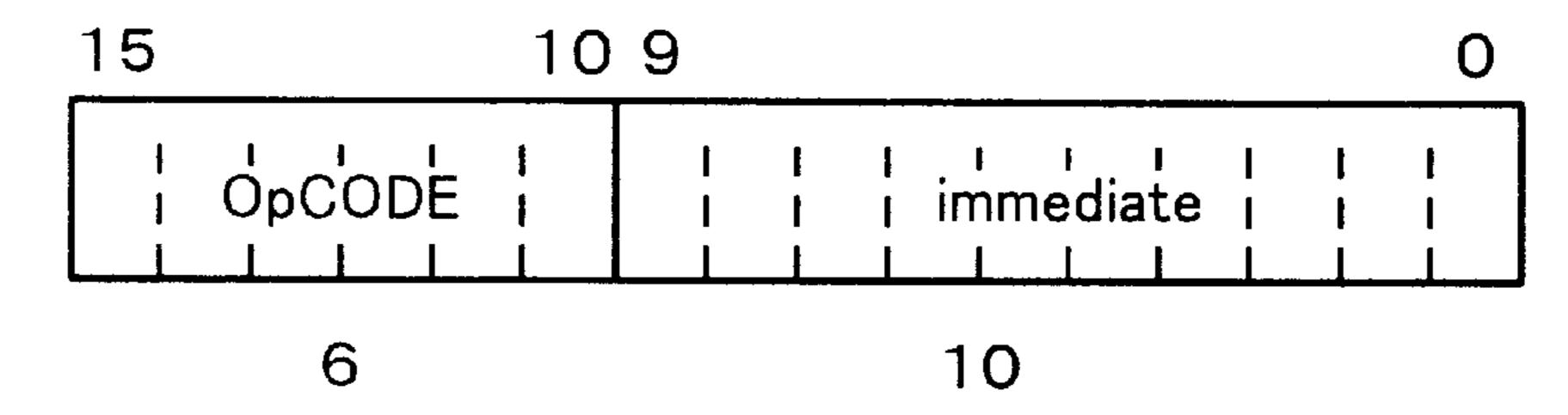
VECTOR ADDRESS = { IBR [ 31:8 ], VECTOR ADDRESS OFFSET }

### Fig. 12

INTERRUPT	SAVE ADDRESS
PMI	[ISP-4]←CURRENT INSTRUCTION
NMI	[ISP-4]←CURRENT INSTRUCTION
CpU0	[ISP-4]←NEXT INSTRUCTION
CpU1	[ISP-4]←NEXT INSTRUCTION
SYSBK	[ISP-4]←NEXT INSTRUCTION
BK	[ISP-4]←NEXT INSTRUCTION
DBK	[ISP-4]←NEXT INSTRUCTION
OVF	[ISP-4]←NEXT, NEXT INSTRUCTION
IBP0-2	[ISP-4]←NEXT INSTRUCTION
Exint0-7	[ISP-4]←CURRENT INSTRUCTION

# Fig. 13A

Apr. 24, 2001



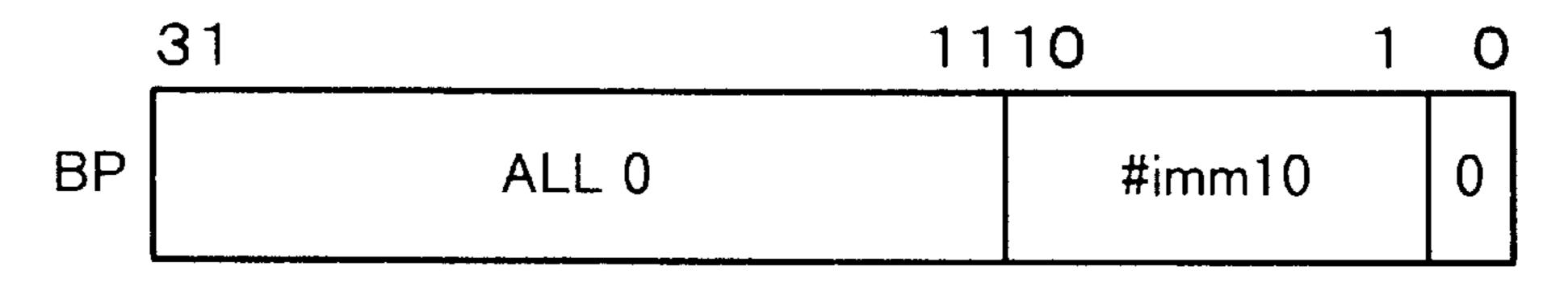
<FORMAT>

SLIL, #imm10

### <DESCRIPTION>

LOADS THE VALUE OF AN IMMEDIATE TO THE ACC CORRESPONDING THE BYTE POSITION BP. STORES THE CONTENT OF NON-DESIGNATED BYTE OF THE ACC.

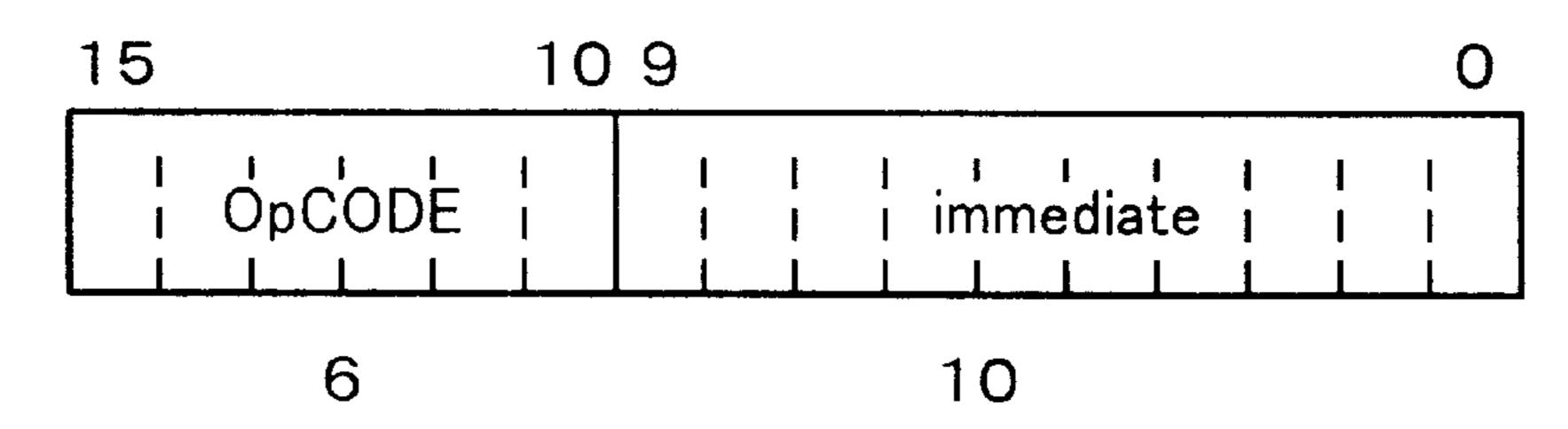
Fig. 13B



<OPERATION>

[ACC] — immediate #imm10

## Fig. 14A



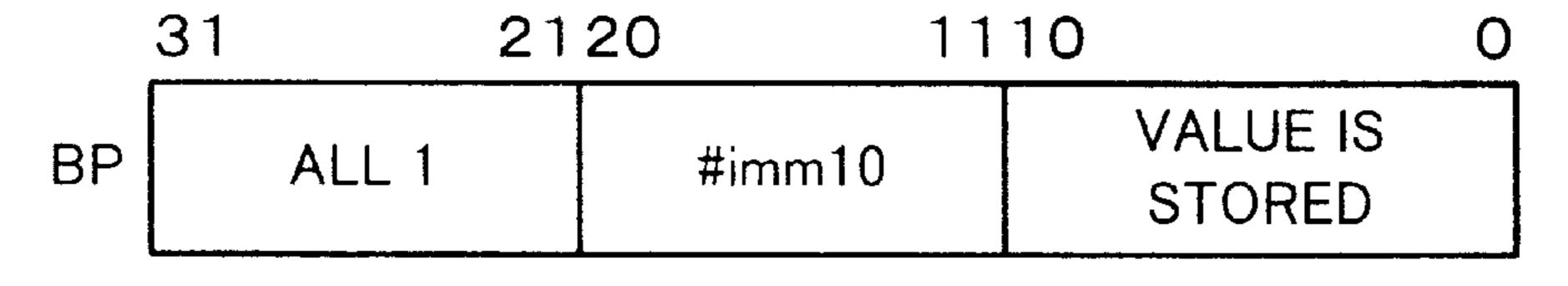
<FORMAT>

SLIH, #imm10

### <DESCRIPTION>

LOADS THE VALUE OF AN IMMEDIATE TO THE ACC CORRESPONDING THE BYTE POSITION BP. STORES THE CONTENT OF NON-DESIGNATED BYTE OF THE ACC.

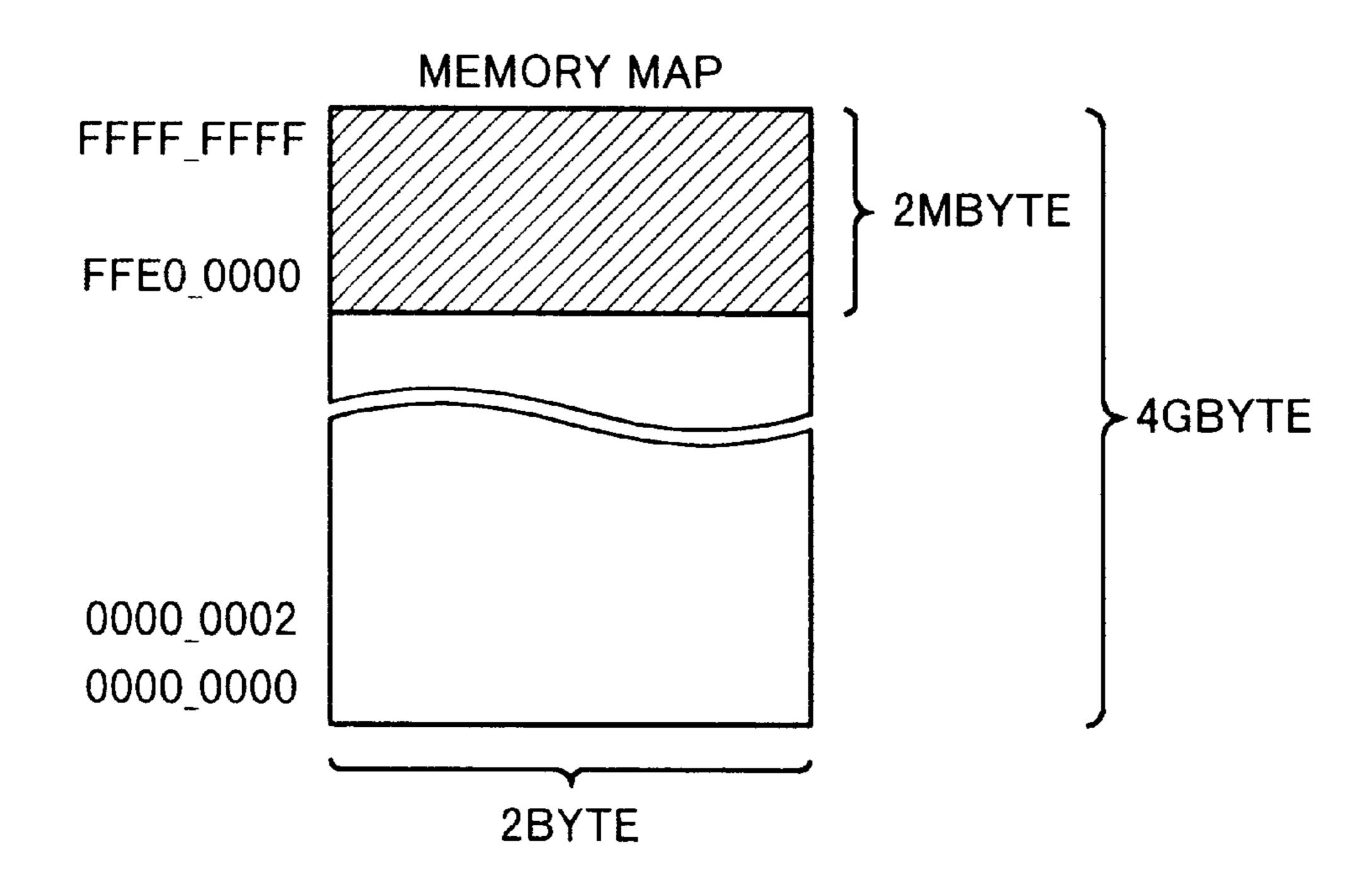
Fig. 14B

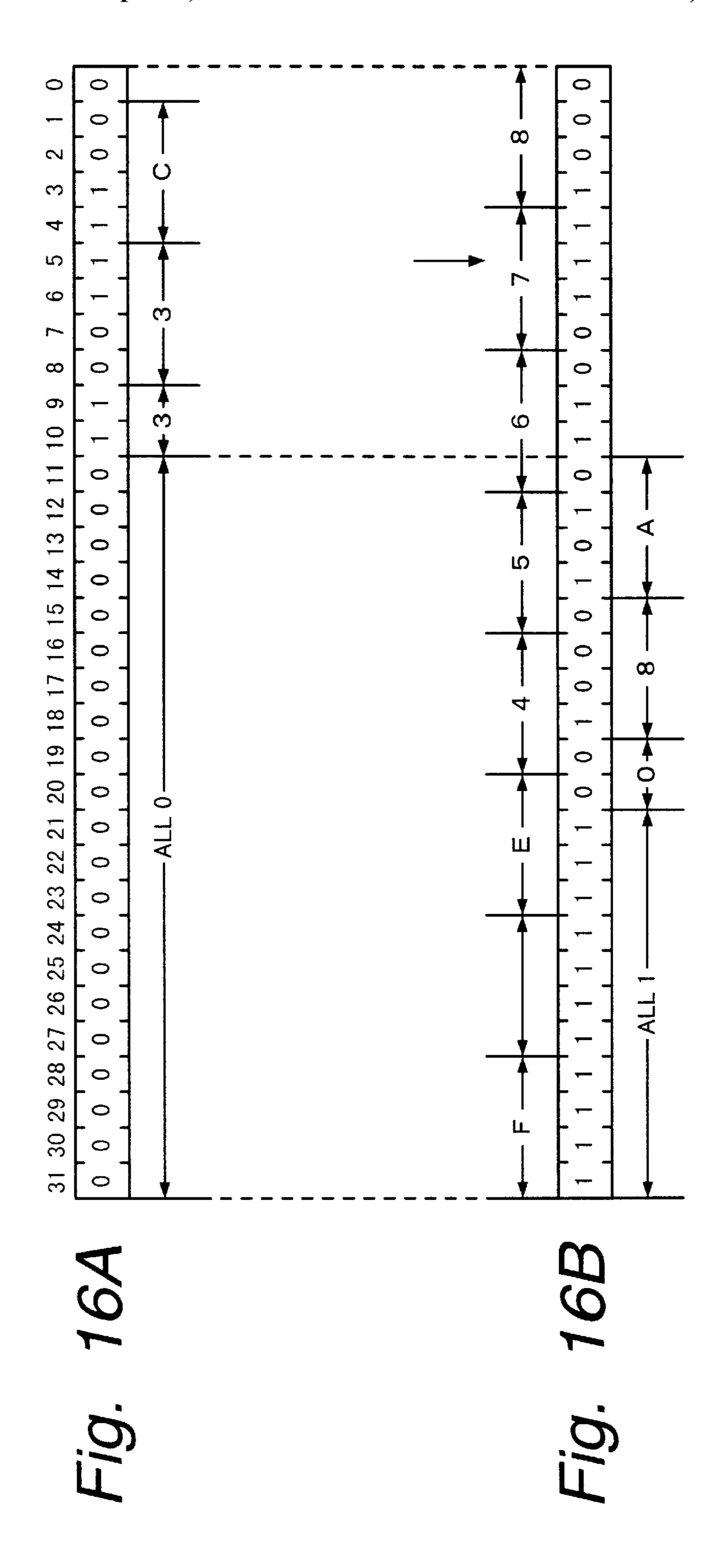


<OPERATION>

[ACC]←immediate #imm10

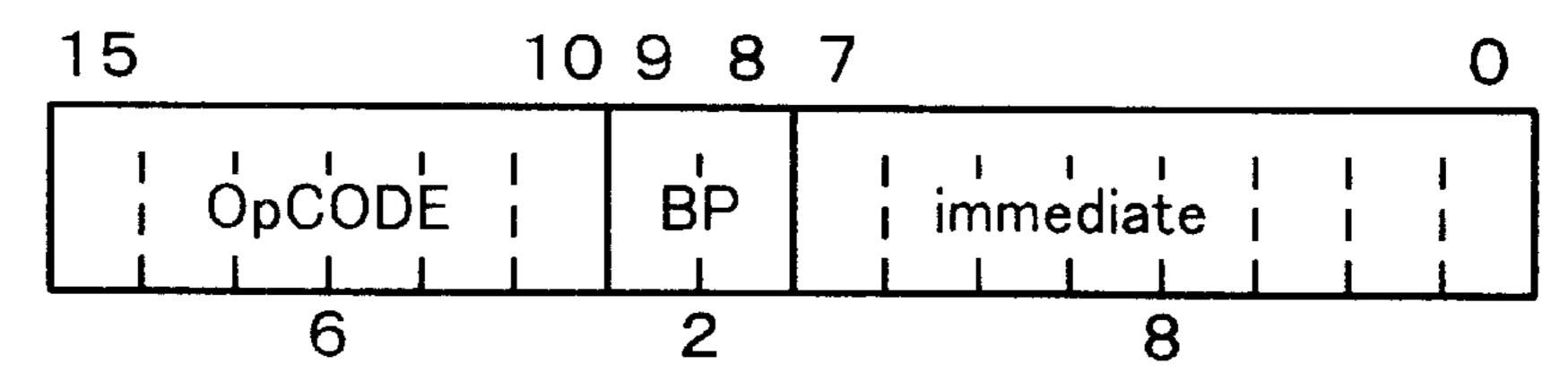
Fig. 15





# Fig. 17A

Apr. 24, 2001



### <FORMAT>

LPI LL, #imm8

LPI LH, #imm8

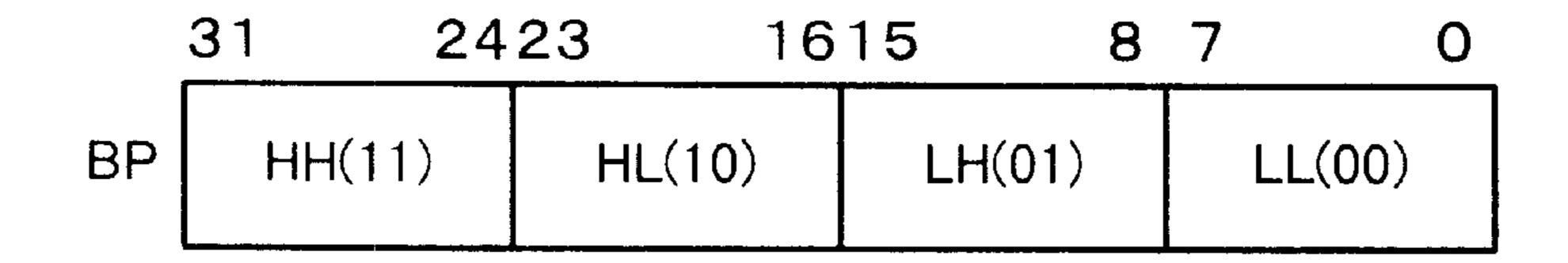
LPI HL, #imm8

LPI HH, #imm8

### <DESCRIPTION>

LOADS THE VALUE OF AN IMMEDIATE TO THE ACC CORRESPONDING THE BYTE POSITION BP. STORES THE CONTENT OF NON-DESIGNATED BYTE OF THE ACC.

## Fig. 17B



### <OPERATION>

[ACC]←immediate BYTE DATA

# MICROPROCESSOR WITH REDUCED INSTRUCTION SET LIMITING THE ADDRESS SPACE TO UPPER 2 MBYTES AND EXECUTING A LONG TYPE REGISTER BRANCH INSTRUCTION IN THREE INTERMEDIATE INSTRUCTIONS

#### BACKGROUND OF THE INVENTION

### 1. Field of the Invention

The present invention relates to a RISC (Reduced Instruction Set Computer) type microprocessor.

#### 2. Description of the Related Art

ARISC processor has a set of instructions that allows the number of calculations to become minimum. A pipeline process of the RISC processor allows all instructions to be executed in the same and short time period. The bit length of instructions of a 32-bit RISC processor is fixed to 32 bits. Thus, in the RISC processor, the bit length of instructions is fixed and the instructions are simplified. With inter-register operations, most instructions can be executed in one clock cycle and thereby the pipeline process can be easily performed.

In the conventional 32-bit RISC processor, the bit length of instructions is fixed to 32 bits. However, the code efficiency of instructions of 32-bit fixed length is not high. In a RISC processor having variable length instructions, the load applied to the decoding portion becomes large. In addition, it takes a long time to perform a pipeline process for variable length instructions. To solve this problem, a branch cache is required. Thus, the circuit scale becomes large. To solve such a problem, the applicant of the present invention has proposed a RISC processor having 16-bit fixed instructions for improving code efficiency.

A 32-bit RISC processor has an address space of 4 35 Gigabytes (Gbytes). In the RISC processor, when a logical address is converted into a physical address, for mapping the address to a space of 4 Gbytes, a 1p.x macro instruction is provided. Conventionally, the 1p.x macro instruction is performed by dividing an LPI instruction into four instructions. Thus, a long type (32 bit) register branch instruction requires five instructions for 10 bytes.

In other words, conventionally, an LPI (Load Position Immediate) instruction as shown in FIGS. 17A and 17B is used. The LPI instruction is composed of 16 bits as shown 45 in FIG. 17A. In the instruction LPI, the high order six bits represent an operation code. The next two-bits BP represent the position of the bit pattern as shown in FIG. 17B. When the value of BP is "11", it represents the highest position (HH). When the value of BP is "10", it represents the next 50 highest position (HL). When the value of BP is "01", it represents the third highest position (LH). When the value of BP is "00", it represents the lowest position (LL). As shown in FIG. 17A, the next eight bits represent an operand designated by the value of an immediate. Thus, in the long 55 type register branch instruction, the instruction LPI is divided into four instructions each of which is composed of eight bits. Thus, at least five instructions are required as a long type register branch instruction.

### OBJECTS AND SUMMARY OF THE INVENTION

Therefore, an object of the present invention is to provide a microprocessor that allows a register branch instruction to be shortened and thereby to improve code efficiency.

The present invention is a reduced instruction set microprocessor, comprising an instruction decoder for

2

dividing a task of an instruction process into simple stages and decoding the task through a pipeline process, an arithmetic and logic unit for performing arithmetic operations, a register group, a high speed multiplication/division unit for performing multiplications and divisions at high speed, an interrupt controller for performing an interrupt process, and an instruction set for limiting the all address space into an upper address space and executing a long type register branch instruction.

The high speed multiplication/division unit performs multiplications and divisions independent from the arithmetic and logic unit. The register group is composed of a dedicated control register group and a general purpose register group. The general purpose register group includes an accumulator, a stack pointer, and an interrupt stack pointer.

The general purpose register group further includes coprocessor registers. The coprocessor registers include registers for allowing a branch instruction to be changed and thereby a plurality of instructions to be executed with the same operation code and registers for accomplishing a simple stack.

All the address space is 4 Gbytes. The bit length of the instruction set is fixed to 16 bits. The limited address space is 2 Megabytes (Mbytes).

Thus, according to the present invention, SLIL and SLIH instructions that allow the all address space to be limited to an upper address space are provided. With the SLIL and SLIH instructions, the address space is limited to the upper 2 Mbytes so as to execute a long type register branch instruction with three instructions.

These and other objects, features and advantages of the present invention will become more apparent in light of the following detailed description of a best mode embodiment thereof, as illustrated in the accompanying drawings.

### BRIEF DESCRIPTION OF THE DRAWINGS

- FIG. 1 is a block diagram showing the internal structure of a microprocessor according to the present invention;
- FIG. 2 is a block diagram for explaining an external interface of the microprocessor according to the present invention;
- FIG. 3 is a schematic diagram for explaining general purpose registers of the microprocessor according to the present invention;
- FIG. 4 is a schematic diagram for explaining coprocessor registers of the microprocessor according to the present invention;
- FIG. 5 is a schematic diagram for explaining MCR (Machine Control Register) of the coprocessors of the microprocessor according to the present invention;
- FIG. 6 is a schematic diagram for explaining an operation code map of the microprocessor according to the present invention;
- FIG. 7 is a schematic diagram for explaining the operation code map of the microprocessor according to the present invention;
- FIG. 8 is a schematic diagram for explaining the operation code map of the microprocessor according to the present invention;
- FIG. 9 is a schematic diagram for explaining a memory space of the microprocessor according to the present invention;
  - FIG. 10 is a schematic diagram for explaining interrupts of the microprocessor according to the present invention;

FIG. 11 is a schematic diagram for explaining interrupts of the microprocessor according to the present invention;

FIG. 12 is a schematic diagram for explaining interrupts of the microprocessor according to the present invention;

FIGS. 13A and 13B are schematic diagrams for explaining a command of the microprocessor according to the present invention;

FIGS. 14A and 14B are schematic diagrams for explaining a command of the microprocessor according to the present invention;

FIG. 15 is a schematic diagram for explaining a memory space of the microprocessor according to the present invention;

FIGS. 16A and 16B are schematic diagrams for explain- 15 ing a command of the microprocessor according to the present invention; and

FIGS. 17A and 17B are schematic diagrams for explaining a command of the microprocessor according to the present invention.

### DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENT

Next, an embodiment of the present invention will be described in the order that follows.

- 1. Outline of processor
- 2. Structure of processor
- 3. Five-staged pipeline
- 4. Registers
- 5. Address space
- 6. Interrupt process
- 7. Single step function
- 8. Instruction set
- 9. Inter-register branch instruction
- 1. Outline of processor

The microprocessor according to the present invention is a RISC (Reduced Instruction Set Computer) type 32-bit processor.

In a RISC processor, the instruction set is limited to a minimum number of instructions. All the instructions are executed nearly in the same time period. In the microprocessor according to the present invention, the bit length of the instructions is fixed to 16 bits. A code efficiency oriented orthogonal instruction set is provided. In the orthogonal instruction set, each instruction executes a very basic task. Each orthogonal instruction does not overlap with another instruction. The instruction set includes for example immediate instructions, a register transfer instruction, arithmetic instructions, comparison instructions, logic instructions, shift instructions, exchange/extension instructions, an NOP instruction, bit process instructions, multiplication/division instructions, memory transfer instructions, coprocessor transfer instructions, and branch instructions.

In the RISC processor, when a source operand of an arithmetic instruction is read and a calculated result is written, a register is used instead of a memory. Most instructions are executed in one clock cycle. Thus, instructions can be easily pipelined. The RISC processor has 32 60 general purpose registers.

The microprocessor performs a five-staged pipeline process. For an ALU, the microprocessor has a barrel shifter of one cycle. In addition, the microprocessor has a high speed multiplication/division device that executes a multiplication 65 of (16×16) in one cycle and a division of (16 (32)÷16 (32)) in 10 (18) cycles.

4

In addition to technologies of RISC, the microprocessor employs technologies of CISC (Complex Instruction Set Computer) and DSP (Digital Signal Processor), thereby remarkably improving code efficiency, bit process, and operations of multiplication/division, interrupt process, and so forth.

Since the microprocessor has the following features:

- 1) vector instruction table,
- 2) interrupt stack pointer, and
- 3) dedicated register for storing results of division instruction, the microprocessor performs an interrupt process at high speed and in multiple levels.

With the vector instruction table, when the microprocessor accepts an interrupt, it is directly fetched to the vector instruction table through the five-staged pipeline. A branch instruction is directly written to the vector instruction table. Thus, the microprocessor can accept an interrupt at high speed. In addition, with an interrupt stack pointer and a return instruction, the microprocessor can accept an interrupt in multiple levels. When the microprocessor accepts an interrupt, only the PC (Program Counter) is automatically saved. With the return instruction, only the PC at the stack pointer is written back to the internal PC. The result of a long division instruction is stored in a dedicated register so that another interrupt can be accepted. Other instructions are executed on a one-instruction one-clock-cycle basis. However, in a delay slot period, an interrupt is prohibited.

The microprocessor has a powerful debug supporting function. With the debug supporting function, a target debugger is easily accomplished without need to use an external circuit. The debug supporting function features:

- 1) single step function with five-staged pipeline,
- 2) two break instructions,

35

- 3) three channels of address breaks,
- 4) two channels of data breaks, and
- 5) ICE (In-Circuit Emulator) break terminal.

With the single step function in CISC, the processor can easily execute a program step by step. However, at a delay slot, the next instruction results in a break. With two break instructions having different vector addresses, when a break instruction is written to a RAM area, an unlimited number of break points can be designated. With three channels of address break pointers executed in the five-staged pipeline, a break pointer can be designated to a ROM area where the above-described two break instructions cannot be used. In addition, with two channels of data break pointers executed in the five-staged pipeline, a break pointer can be easily designated to a built-in RAM. With the ICE break terminal, the control can be easily transferred from the outside to ICE. In addition, a coprocessor defined by the user can be connected to the microprocessor.

### 2. Structure of processor

FIG. 1 shows the structure of a microprocessor 1 according to the present invention. In FIG. 1, the microprocessor 1 is connected to a data bus 2, an instruction bus 3, and a coprocessor bus 4. The microprocessor 1 has a terminal group 5 that are a reset terminal, a clock terminal, an external interrupt (7:0) terminal, an NMI (Non-Maskable Interrupt) terminal, and a PMI (Power Management Interrupt) terminal.

When a system is structured with the microprocessor 1, as shown in FIG. 2, the microprocessor 1 is connected to a memory controller 21 through the data bus 2 and the instruction bus 3. In addition, the microprocessor 1 is connected to a coprocessor 22 through the coprocessor bus

4.

Referring to FIG. 1, the microprocessor 1 comprises an instruction decoder 6, a dedicated control register group 7, an interrupt controller 8, a general purpose register group 9, a bypass logic 10, an ALU (Arithmetic and Logic Unit) 11, a multiplication/division calculating portion 12, and an 5 address calculating portion 13.

The instruction decoder 6 performs a pipeline process. The pipeline process divides a task of an instruction into simple stages of a fetching operation, an ALU calculation, a memory access operation, and a write-back operation. When an instruction is transferred from one stage to another stage, the next instruction is placed in the blank stage. When instructions are processed stage by stage, before one instruction is completed, another instruction can be processed. As described above, the microprocessor according to the present invention uses a five-staged pipeline.

The dedicated control register group 7 has ten 32-bit registers. The dedicated control register group 7 is used for a status function, an interrupt controlling function, and an ICE support function.

The interrupt controller **8** performs an interrupt process. 20 In the interrupt process, a vector instruction table and an interrupt stack pointer are used. The interrupt response function is accomplished in one cycle (minimum) to three cycles (maximum). When an interrupt is accepted, it is directly fetched to the interrupt vector instruction table 25 through the five-staged pipeline. A branch instruction is written to the vector instruction table.

The general purpose register group 9 has 32 32-bit registers (R0 to R31). The register R1 is an accumulator (ACC). The register R30 is a stack pointer (SP). The register 30 R31 is an interrupt stack pointer (ISP). The ISP is used for a stack pointer for the interrupt process, the exception process, the interrupt return process, and so forth. The initial values of the general purpose registers R0 to R31 including the ACC, SP, and ISP are undefined.

The bypass logic 10 is a logic for performing the five-staged pipeline process. The ALU 11 has a barrel shifter in one cycle. The multiplication/division calculating unit 12 has a high speed multiplying device of 16×16 bits in one cycle and a high speed dividing device of 16 (32)÷16 (32) 40 bits in 10 (18) cycles. Thus, since a division is performed by such an independent device, while a division is being calculated, another instruction can be executed. The address calculating portion 13 includes a program counter (PC), an increment portion, and a data aligner.

### 3. Five-staged pipeline

The microprocessor 1 performs a five-staged pipeline process. The instruction bus 3, the data bus, and the coprocessor bus 4 are provided with independent input and output. These buses are connected to external cache (buffers) and 50 coprocessor registers.

In the pipeline process, a task of an instructions is processed in stages of a fetch operation, an ALU calculating operation, a memory access operation, and a write-back operation. There are three types of delay slots for a branch 55 instruction, a load instruction, and a return instruction. For example, when a branch instruction is decoded and analyzed, the address of the next instruction is generated. This situation is referred to as branch delay slot. When a load instruction is executed, load data is present on the external 60 bus in the ALU cycle of the next load instruction. In a load instruction, the register that has been just loaded with the preceding instruction cannot be accessed. This situation is referred to as load delay slot. When a return instruction is executed, the value of the program counter (PC) obtained 65 from the stack cannot be used for the pipeline process. This situation is referred to as return slot.

6

A branch instruction has one delay slot. A load instruction has one delay slot. A return instruction has three slots.

### 4. Registers

4-1. General purpose registers

FIG. 3 shows the structure of general purpose registers. As shown in FIG. 3, the microprocessor according to the present invention has 32 general purpose registers R0 to R31. Since instructions are structured considering orthogonality, they can be used as registers for calculations except for special instructions. The R1 register is an accumulator (ACC) that is used for an operand of an immediate/bit process instruction. As an exception, the R30 register is a stack pointer (SP) that is used for a stack pointer of a call instruction and a return instruction. The R31 register is an interrupt stack pointer (ISP) that is used for a stack pointer of an interrupt process, an exception process, and an interrupt return process. The initial values of the ACC, SP, and ISP are undefined.

#### 4-2. Coprocessor registers

FIG. 4 shows the structure of coprocessor registers. As shown in FIG. 4, a total of 128 coprocessor registers G0 to G31 and C0 to C31 as Cop0 registers and G0 to G31 and C0 to C31 as Cop1 registers can be used. Instructions for transferring data between the coprocessor registers and the general purpose registers have been defined.

The G0 to G31 registers of the Cop0 registers have a total of 10 system control coprocessor registers. The rest of the registers are reserved for future use. The system control processor registers have the following functions.

Cop0 G0: SR (Status Register) Stores a flag.

Cop**0** G1: MCR (Machine Control Register) Controls a machine.

Cop**0** G2: IBR (Interrupt Base Register) Sets an interrupt vector base address.

Cop**0** G3: ICR (Interrupt Control Register) Controls an interrupt.

Cop0 G4: IMR0 (Interrupt Mode Register 0) Controls external interrupt mode 0.

Cop**0** G**5**: IMR1 (Interrupt Mode Register 1) Controls external interrupt mode 1.

Cop**0** G**6**: JBR (Jump Base Register) Sets a special jump base address.

Cop**0** G**10**: IBP**0** (Interrupt Break Point **0**) Sets an instruction break address.

Cop**0** G11: IBP1 (Interrupt Break Point 1) Sets an instruction break address.

Cop**0** G**12**: IBP**2** (Interrupt Break Point **2**) Sets an instruction break address.

The G1 register of the Cop0 registers is an MCR (Machine Control Register). With the MCR, by changing a branch instruction, the same operation code allows four instructions to be executed.

FIG. 5 shows the structure of the G1 register of the Cop0 registers. The G1 register is the MCR.

The bit length of the MCR is 16 bits. The most significant bit 15 is D32En. With D32En, a 32-bit division can be performed. When D32En is "0", a 32-bit division is disabled. When D32En is "1", a 32-bit division is enabled. The bits 14, 13, and 12 of the MCR are SGS, BCS, and JCS, respectively. The SGS is Segment Selection. The BCS and JCS are Code Selection. With the SGS, BCS, and JCS, the same operation code allows four instructions to be executed.

The bit 10 is SSE that is Single Step Enable. When SSE is "0", the single step function is disabled. When SSE is "1", the single step function is enabled. The bit 11 is DBSSE that

7

is Debug Break Single Step Enable. When DBSSE is "0", the debug break single step function is disabled. When DBSSE is "1", the debug break single step function is enabled. The bits 5 to 3 are CKDMD that represents the frequency division of the CPU clock.

The bit 2 is AIDEn that represents a change of a load/store instruction corresponding to a control bit. When AIDEn is "1", a post-increment load/post-decrement store operation is performed. When AIDEn is "0", a normal load/store operation is performed.

FIGS. 6 to 8 show maps of operation codes. In FIGS. 6 to 8, with respect to instructions with "\*", with a change of a branch instruction, the same operation code allows a plurality of instructions to be executed.

The G3 register of the Cop0 registers is ICR (Interrupt 15 Control Register). The ICR can be used as a simple stack.

FIG. 9 shows the G3 register of the Cop0 registers. The bit 15 of the G3 register (ICR) represents an interrupt test. When the bit 15 is not set, read-only mode takes place. When the bit 15 is set, write-enable mode takes place. With the bit 20 15, an interrupt test can be performed.

The bit 14 of the G3 register is IICEN. The bit 14 represents whether an internal interrupt controller or an external interrupt controller is used.

The bit 13 of the G3 register is MNIP that is a pending bit. 25 The bits 12 to 5 of the G3 register are IntP(7:0) that are interrupt pending bits.

The bits 4, 3, 2, 1, and 0 of the G3 register are BPAIE, PAIE, OAIE, and AIE, respectively, that accomplish simple stacks.

The BPAIE, PAIE, OAIE, JOAIE, and AIE are four-level interrupt enable stacks. When an interrupt is executed, the flags are shifted leftward as follows and "0" is placed in the LSB.

PAIE - - - >BPAIE

OAIE - - - >PAIE

JOAIE - - - >OAIE

0 - - - >AIE

When the RETI instruction is executed, the flags are shifted rightward as follows.

AIE < - - JOAIE

JOAIE < - - OAIE

OAIE < - - PAIE

PAIE < - - - BPAIE

When an interrupt is processed, the PC is automatically 45 saved. The interrupt control register should be saved by software. However, up to four-level multiple interrupts, with the BPAIE, PAIE, OAIE, JOAIE, and AIE at the bit 4 to bit 0, an interrupt control bit is automatically saved.

With two channels CH 0 and CH 1, an interrupt of a data 50 access uses the following coprocessors.

Cop1 G4: DABRO (Data Address Break Register 0) Includes a data address at an interrupt to be executed.

Cop1 G5: WDBR0 (Write Data Break Register 0) Includes the value of data of an interrupt to be executed.

Cop1 G6: WDMR0 (Write Data Mask Register 0) Controls a mask.

Cop1 G7: DBCR0 (Data Break Control Register 0) Sets data access mode.

Cop1 G8: DBRR0 (Data Break Run Register 0) Runs data 60 break.

Cop1 G9: FMWR (Flash Memory Write Register) Write-selects a flash memory.

Cop1 G10: DABR1 (Data Address Break Register 1) Includes the data address of an interrupt to be executed.

Cop1 G11: DAMR1 (Data Address Mask Register 1) Controls a mask.

8

Cop1 G12: WDBR1 (Write Data Break Register 1) Includes the address of an interrupt to be executed.

Cop1 G13: WDMR1 (Write Data Mask Register 1) Controls a mask.

Cop1 G14: DBCR1 (Data Break Control Register 1) Sets data access mode.

Cop1 G15: DBRR1 (Data Break Run Register 1) Runs data break.

5. Address space

FIG. 10 shows an address space of the microprocessor 1. The address space of the microprocessor 1 is 4 Gbytes for each of instructions and data. The microprocessor 1 exchanges data and instructions with the external coprocessor through a 64-word external register.

When an external reset is detected, the control branches to FFFF\_FE60h and an instruction thereof is executed. Vector addresses are designated at intervals of two words (four words). The first one word is a branch instruction. The second one word is a delay slot. Based on an interrupt base register (IBR) (Cop0 G2), a vector address can be designated at any position in the boundary of 256 bytes. Instructions/data are mapped in the same space. With a conventional load instruction, a value can be obtained from the ROM space.

6. Interrupt process

FIG. 11 shows the priority of interrupts. In FIG. 11, an SSTEP (Single Step) interrupt is designated the highest priority. The SSTEP interrupt is followed by a PMI (Power management Interrupt), an NMI (Non-Maskable Interrupt), and so forth. There are eight external interrupts Exint0 to Exint7. Each interrupt has a vector address offset. With a vector address offset, a vector address is obtained as follows.

Vector Address={IBR[31:8], Vector Address Offset}

IBR[31:8] is an interrupt base register (IBR(Cop G2) that designates the base of the interrupt vector table. When a SYSCALL/BREAK/DEBREAK instruction is executed, the control branches to the vector address thereof. The branch instruction is directly written to the vector instruction table. When an interrupt is accepted, the vector address of the vector instruction table is directly fetched through the five-staged pipeline. Thus, a high speed interrupt in at least one cycle can be performed.

When an interrupt is accepted, the AIE flag of the ICR (Cop0 G3) is disabled. An interrupt is accepted in one clock cycle except for an interrupt prohibition period. Examples of the interrupt prohibition period are a return delay slot and a branch delay slot. In a PMI interrupt period, another interrupt is prohibited until a return delay slot. In an NMI interrupt period, only a PMI interrupt is accepted until a return delay slot. The PMI interrupt and the NMI interrupt are accepted when a predetermined change point is detected. The other interrupts are accepted when a predetermined level is detected. When an interrupt is accepted, a save address is designated as shown in FIG. 12.

Interrupts corresponding to data accesses are executed as follows.

1) To execute an interrupt corresponding to a compared result of a data address in data read state:

A data address of an interrupt to be executed is written to DABR0 (Cop1 G4). "1" and "0" are set to MRD and MWR of DBCR0 (Cop1 G7). A read method (SB, SHW, or SW) is selected with BE[3:0] of DBCR0. "1" is set to RUN of DBRR0 (Cop1 G8).

2) To execute an interrupt corresponding to a compared result of a data address in data write state:

A data address of an interrupt to be executed is written to DABRO. "1" and "0" are set to MWR and MRD of DBCRO. A write method (LBU, LB, LHWU, LHW, or LW) is

selected with BE[3:0] of DBCR0. To ignore a data comparison condition, "0s" are masked to all bits of WDMR0. "1" is set to RUN of DBRR0.

3) To execute an interrupt corresponding to a compared result of data in data write state:

A data address of an interrupt to be executed is written to DABRO. "1" and "0" are set to MWR and MRD of DBCRO. A write method (LBU, LB, LHWU, LHW, or LW) is selected with BE[3:0] of DBCR0. A data value of an interrupt to be executed is written to WDBR0. To mask a 10 particular bit, "0" is set to the relevant bit of WDMR0. "1" is set to RUN of DBRR0.

4) To execute an interrupt corresponding to only a compared result of a data address in data read/write state:

A data address of an interrupt to be executed is written to 15 DABRO. "1" is set to both MRD and MWR of DBCRO. Read/write methods (SB/LBU/LB, SHW/LHWU/LHW, or SW/LW) are selected with BE[3:0] of DBCR0. To ignore a data comparison condition, "0s" are masked to all bits of WDMR0. "1" is set to RUN of DBRR0.

5) To execute an interrupt corresponding to a compared result of a data address in data read state and to a compared result of data in data write state:

A data address of an interrupt to be executed is written to DABRO. "1" is set to both MWR and MRD of DBCRO. 25 Read/write methods (SB/LBU/LB, SHW/LHWU/LHW, or SW/LW) are selected with BE[3:0] of DBCR0. To mask a particular bit, "0" is set to the relevant bit of WDMR0. "1" is set to RUN of DBRR0. When interrupts take place on both CH 0 and CH 1, the control jumps to the same vector 30 address. RUN of DBRR0 represents the channel on which an interrupt has taken place.

### 7. Single step function

The microprocessor 1 has a single step function for causing an exception process to take place for each instruc- 35 result to DEST1. tion. When DBSSE (Debug Break Single Step Enable Bit) of MCR (Cop0 G1) is set and then the DBREAK instruction is executed, the control enters into a single step exception process loop. At this point, all interrupts are prohibited from being executed.

A single step exception process routine is programmed in the following manner.

- 1) The start address of a main program to be executed for the single step function is set to the interrupt stack pointer (ISP (R**31**)).
  - 2) The SSE flag of MCR[10] is set.
- 3) When the RETI instruction is executed, the control branches to the address of the main program to be executed for the single step function through three slots.
- 4) When one instruction of the main program is executed, 50 the control automatically returns to the single step exception process routine. At this point, the SSE flag of MCR[10] is cleared.
- 5) Thereafter, in the single step exception process routine, the SSE flag of MCR[10] is set and the RETI instruction is 55 executed. Thus, the control branches to the address of the next instruction of the main program to be executed for single step function.

Unless the control exits from the single step exception process routine, the above-described process is repeated. To 60 exit from the single step process routine, the SSE flag is disabled in the single step exception process routine. A program to be executed is written to the program counter and then the RETI instruction is executed.

### 8. Instruction set

The microprocessor 1 has a code efficiency oriented orthogonal instruction set. The bit length of the instructions **10** 

is fixed to 16 bits. The bit length of operation codes is fixed to six bits. In an inter-register instruction, five bits are assigned to the operand thereof. Since there are 32 general purpose registers, with an operand of five bits, a code can be effectively defined.

There are immediate instructions, a register transfer instruction, arithmetic instructions, comparison instructions, logic instructions, shift instructions, exchange/extension instructions, an NOP instruction, bit process instructions, multiplication/division instructions, memory transfer instructions, coprocessor transfer instructions, and branch instructions.

### 1) Immediate instructions

LPI: Loads the value of an immediate to the accumulator corresponding to the byte position. Stores the content of a non-designated byte of the accumulator.

LI: Loads the value of an immediate to the accumulator corresponding to a selected word byte.

LSI, LSIU: Load the value of an immediate to a designated general purpose register.

SLIL, SLIH: Load the value of an immediate to the accumulator corresponding to the byte position. Store the content of a non-designated byte of the accumulator.

2) Register transfer instruction

MOV: Transfers data between general purpose registers.

3) Arithmetic instructions

ADDSI, ADDSIU: Immediate addition instructions ADD, ADDC: Inter-register addition instructions ADDU: Inter-register unsigned addition instruction SUB, SUBB: Inter-register subtraction instructions SUBU: Inter-register unsigned subtraction instruction

4) Comparison instructions

COMPI, COMPIU: Immediate comparison instructions COMP: Inter-register comparison instruction.

Same function as SUB instruction. Does not return the

COMPU: Inter-register unsigned comparison instruction. Same function as SUBU instruction. Does not return the result to DEST1.

5) Logical instructions

AND, OR, XOR, NOR: Logical arithmetic instructions 6) Shift instructions

SLLV, SRLV, SRAV: Indirect shift instructions. SLLV is a register indirect logical left shift instruction. SRLV is a register indirect logical right shift instruction. SRAV is a 45 register indirect arithmetic right shift instruction.

SLL, SRL, SRA: Immediate shift instructions. SLL is an immediate logical left shift instruction. SRA is an immediate logical right shift instruction. SRA is an immediate arithmetic right shift instruction.

RR: Executes the right shift operation including a carry the number of times denoted by the immediate. Stores a shifted-out bit (LSB before execution) to the carry. MSB stores the value of the carry.

RL: Executes the left shift operation including a carry. Stores a shifted-out bit MSB before execution) to the carry. MSB stores the value of the carry.

7) Exchange/extension instructions

XCB: Exchange instruction between SRC[15:8] and SRC1[7:0]

EXU: Zero extension instruction for a low order byte EXS: Sign extension instruction for a low order byte

XCHW: Exchange instruction between SRC[OPS:16] and SRC1[15:0]

EXHZ: Zero extension instruction for a low order half 65 word

EXHS: Sign extension instruction for a low order half word

8) NOP instruction

NOP: No operation

9) Bit process instructions

BS, BT, BTR, BTS, BTC: Bit process instructions

10) Multiplication/division instructions

MULTU: Unsigned multiplication instruction for SRC1 [15:0] and SRC2[15:0]

DIVU: Unsigned division instruction for SRC1 and SRC2 MULT: Multiplication instruction for SRC1[15:0] and SRC2[15:0]

DIV: Division instruction for SRC1 and SRC2

MTHI: Transfer instruction from a general purpose register to a HI register

MTLO: Transfer instruction from a general purpose register to a LO register

MFHI: Transfer instruction from a HI register to a general purpose register

MFHO: Transfer instruction from a LO register to a general purpose register

11) Memory transfer instructions

SW, SHW, SB: Store data to an address of a memory space represented by an index.

LW, LHW, LB: Load data from an address of a memory space represented by an index.

LHWU, LBU: Load data from an address of a memory space represented by an index.

12) Coprocessor transfer instructions

CTC1: Transfer instruction from the accumulator to a coprocessor control register 1

CFC1: Transfer instruction from a coprocessor control register 1 to the accumulator

MTC0: Transfer instruction from a general purpose register to a coprocessor general purpose register 0

MFC0: Transfer instruction from a coprocessor general purpose register 0 to a general purpose register

MFC1: Transfer instruction from a coprocessor general purpose register 1 to a general purpose register

SWC0, SWC1: Store instructions from a coprocessor general purpose register to an address of a memory space represented by an index

LWC0, LWC1: Load instructions from an address of a memory space represented by an index to a coprocessor 45 general purpose register

13) Branch instructions

<1> Program counter relative

RJ, RJAL: Program counter relative branch instructions.
RJAL stores the value of the program counter to an address 50 represented by the pre-decremented stack pointer and then branches. A return instruction causes the control to return to the next instruction of the RJAL instruction.

RBEQ/RBZ, RBNE/RBNZ: Conditional PC relative branch instructions

RBLE, RBGE: Conditional program counter relative branch instructions

RBLT, RBGT: Conditional program counter relative branch instructions

RBLTAL, RBGEAL: Conditional program counter rela- 60 tive branch instructions

RBBE, RBAE: Conditional program counter relative branch instructions

RBBL, RBAB: Conditional program counter relative branch instructions

RBBLAT, RBAEL; Conditional program counter relative branch instructions

12

<2> Register indirect

JR, JLR: Register indirect branch instructions

JER/JZR, JNER/JNZR: Conditional register indirect branch instructions

JLER, JGER: Conditional register indirect branch instructions

JLTR, JGTR: Conditional register indirect branch instructions

JLTALR, JGEALR; Conditional register indirect branch instructions

JER/JZR, JNER/JNZR: Conditional register indirect branch instructions

JBER, JAER/JNCR: Conditional register indirect branch instructions

JBR/JCR, JAR: Conditional register indirect branch instructions

JBALAR, JAEALR: Conditional register indirect branch instructions

<3> Program counter segment

J, JAL: Program counter branch instructions

BEQ/BZ, BNE/BNZ: Conditional program counter segment branch instructions

BLE, BGE: Conditional program counter segment branch instructions

BLT, BGT: Conditional segment branch instructions

BLTAL, BGEAL: Conditional program counter segment branch instructions

BEQ/BZ, BNE/BNZ: Conditional program counter segment branch instructions

BBE, BAE: Conditional program counter segment branch instructions

BL, BAB: Conditional program counter segment branch instructions

BBLAL, BAEAL; Conditional program counter segment branch instructions

<4> System call and return instructions

RET: Used in jump and link states. After storing the value of the address memory represented by the stack pointer to the program counter, post-increments the stack pointer. The RET instruction causes the control to return to the next instruction of the branch instruction.

SYSCALL, BREAK, DBREAK: Software interrupt (exception process) instructions. After storing the value of the program counter to an address represented by the predecremented ISP (Instruction Stack Pointer), shifts the four-level interrupt enable flag of the ICR to the left. The RETI instruction causes the control to return to the next instruction.

RETI: Causes the control to return from the exception process of the SYSCALL/BREAK/DBREAK instruction. After storing the value of a memory represented by the ISP to the program counter, post-decrements the ISP and shifts the four-level interrupt enable flag of the ICR to the right. The RETI instruction causes the control to return to the next instruction of the SYSCALL/BREAK/DBREAK instruction.

JIBIO: Branch instruction to {JBR[31:11], segment address[9:0],0}

9. Inter-register branch instructions

As described above, the instruction set of the microprocessor according to the present invention includes SLIL (Small Load Immediate Low) and SLIH (Small Load Immediate High) that load the value of an immediate to the accumulator corresponding to the byte position. As shown in FIGS. 13A and 14A, the bit length of the SLIL and SLIH instructions are 16 bits. The high order six bits of these instructions are an operation code. The next ten bits are an

20

30

**13** 

operand of an immediate. The SLIL and SLIH instructions cause the value of an immediate to be stored to the accumulator corresponding to the byte position.

As shown in FIG. 13B, the bit 0 of the SLIL instruction is fixed to "0". The bit 1 to bit 10 are a 10-bit immediate of 5 the operand. The bit 11 to bit 31 are all "0s". As shown in FIG. 14B, the bit 11 to bit 20 of the SLIH instruction are a 10-bit immediate of the operand. The bit 21 to bit 31 are all "1s".

As shown in FIG. 15, the 32-bit RISC processor has an 10 address space of 4 Gbytes (0000\_0000 to FFFF\_FFFF). With the SLIL and SLIH instructions, the address space is limited to the upper 2 Mbytes (FFE0\_0000 to FFFF\_FFFF) and a long type branch instruction is executed with three instructions.

When the control is branched to FFE4\_5678h, conventionally, the following five instructions are used.

LPI LL, #78h

LPI LH, #56h

LPI HL, #E4h

LPI HH, #FFh

JR ACC (inter-register branch instruction)

On the other hand, with the SLIL and SLIH instructions, such an operation can be executed with the following three instructions.

SLIL, #33Ch

SLIH, #08Ah

JR ACC (inter-register branch instruction)

In other words, the address immediate FFE4\_5678 to be branched is denoted in binary notation as follows.

1111\_\_1111\_\_1110\_\_0100\_\_0101\_\_0110\_\_0111\_\_1000

33Ch given to the immediate of the SLIL instruction is denoted by ten bits as follows.

11\_0011\_1100

When 08Ah given to the immediate value of the SLIH 35 instruction is denoted by ten bits as follows.

00\_1000\_1010

Thus, the bit position of 33Ch with the SLIL instruction can be denoted as shown in FIG. 16A. In addition, the bit position of 08Ah with the SLIH instruction can be denoted 40 as shown in FIG. 16B. Thus, the value of the accumulator becomes:

 $1111\_1111\_1110\_0100\_0101_{13}$   $0110\_0111\_1000$ . Consequently, the control can be branched to FFE4\_5678.

Thus, with the SLIL and SLIH instructions, the address 45 space is limited to the upper 2 Mbytes and a long type register branch instruction is executed with three instructions. For code compatibility, a compiler option for allocating the code space of a program to the upper 2 Mbytes (FFE0000h to FFFFFFFh) is disposed.

According to the present invention, with the SLIL and SLIH instructions, the address space is limited to the upper 2 Mbytes and a long type register branch instruction is executed with three instructions. Since conventional five instructions are reduced to three instructions, the code 55 efficiency is improved. In a program with many branch instructions, the performance can be improved for around five percent.

In addition, according to the present invention, the register group includes coprocessor registers. The coprocessor 60 registers include registers that allow a branch instruction to be changed and a plurality of instructions to be executed with the same operation code. Thus, with the same operation

14

code, a plurality of instructions can be defined. Moreover, the coprocessor registers include registers that accomplish a simple stack with which an interrupt control bit can be automatically saved.

Although the present invention has been shown and described with respect to a best mode embodiment thereof, it should be understood by those skilled in the art that the foregoing and various other changes, omissions, and additions in the form and detail thereof may be made therein without departing from the spirit and scope of the present invention.

What is claimed is:

- 1. A reduced instruction set microprocessor, comprising:
- an instruction decoder for (1) dividing a task of an instruction process into simple stages and (2) decoding the task through a pipeline process;
- an arithmetic and logic unit for performing arithmetic operations;
- a register group;
- a high speed multiplication/division unit for performing multiplications and divisions at high speed;
- an interrupt controller for performing an interrupt process; and
- an instruction set for (1) limiting an address space into an upper address space and (2) executing a long type register branch instruction in less than five instructions.
- 2. The microprocessor as set forth in claim 1,
- wherein said high speed multiplication/division unit performs multiplications and divisions independent from said arithmetic and logic unit.
- 3. The microprocessor as set forth in claim 1, wherein said register group comprises a dedicated control register group and a general purpose register group.
  - 4. The microprocessor as set forth in claim 3,
  - wherein the general purpose register group includes an accumulator.
  - 5. The microprocessor as set forth in claim 3,
  - wherein the general purpose register group includes a stack pointer.
  - 6. The microprocessor as set forth in claim 3,
  - wherein the general purpose register group includes an interrupt stack pointer.
  - 7. The microprocessor as set forth in claim 3,
  - wherein the general purpose register group further includes coprocessor registers.
- 8. The microprocessor as set forth in claim 7, wherein the coprocessor registers include registers for allowing a branch instruction to be changed and thereby a plurality of instructions to be executed with a same operation code.
  - 9. The microprocessor as set forth in claim 7,
  - wherein the coprocessor registers include registers for accomplishing a simple stack.
- 10. The microprocessor as set forth in claim 1, wherein the address space is 4 Gbytes.
- 11. The microprocessor as set forth in claim 1, wherein a bit length of said instruction set is fixed to 16 bits.
  - 12. The microprocessor as set forth in claim 1, wherein the limited address space is 2 Mbytes.