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APPARATUS FOR CONTROLLING IMAGE **FORMATION**

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Related U.S. Application Data

[60] Continuation of Ser. No. 182,087, Aug. 28, 1980, abandoned, which is a division of Ser. No. 964,023, Nov. 27, 1978, Pat. No. 4,305,654, which is a continuation of Ser. No. 752,895, Dec. 21, 1976, abandoned.

[30] Foreign Application Priority Data

	Dec. 27, 19	75 [JI	'] Japan		50-156671
	Mar. 31, 19	76 [JI] Japan	***************************************	51-36614
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[51]	Int. Cl. ⁴	•••••	G03G	15/00
[50]	TIO OI		/4 A Th.	255 /0

[56] U.S. PATENT DOCUMENTS

3,586,450	6/1971	Hosey et al 355/8
		Hyosaka et al 355/8
		Ver Schage et al 355/14 C
		Sohm

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Primary Examiner—Fred L. Braun Attorney, Agent, or Firm—Fitzpatrick, Cella, Harper & Scinto

[57] **ABSTRACT**

A diagnostic program determines whether the machine is in a proper or improper operational state, and the scanning device is moved to a predetermined position in response to the positioning program after the entry of the key inputs by the entry program, and a copying operation is then enabled. The key entry program is executed after the machine starts, and the positioning program is executed before the start of the scanning device and after the key input entry, wherein the scan is inhibited from exposing the recording medium when the diagnostic program determines that the state of the machine is improper, or when the positioning program determines that the scanning device is not in the predetermined position. Also, the scan is enabled for exposing the recording medium when the diagnostic program determines that the state of the machine is proper and the positioning program determines that the scanning device is in the predetermined position.

11 Claims, 54 Drawing Figures

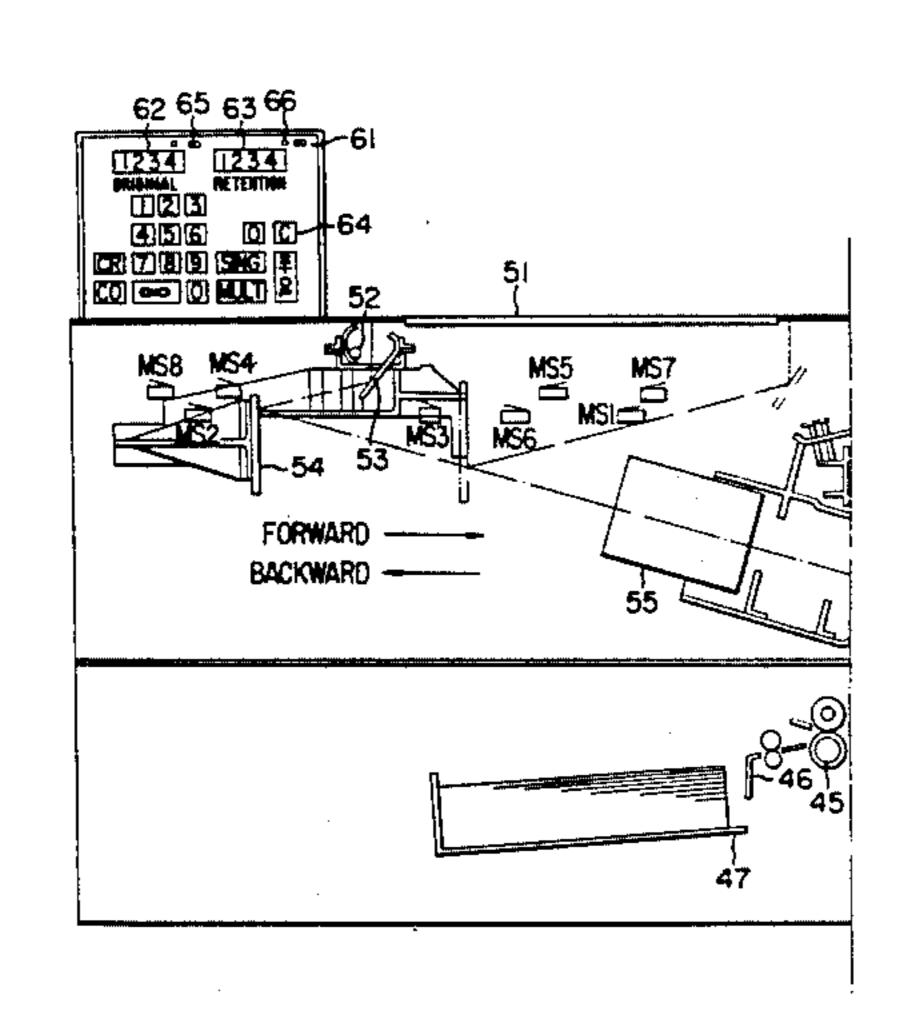
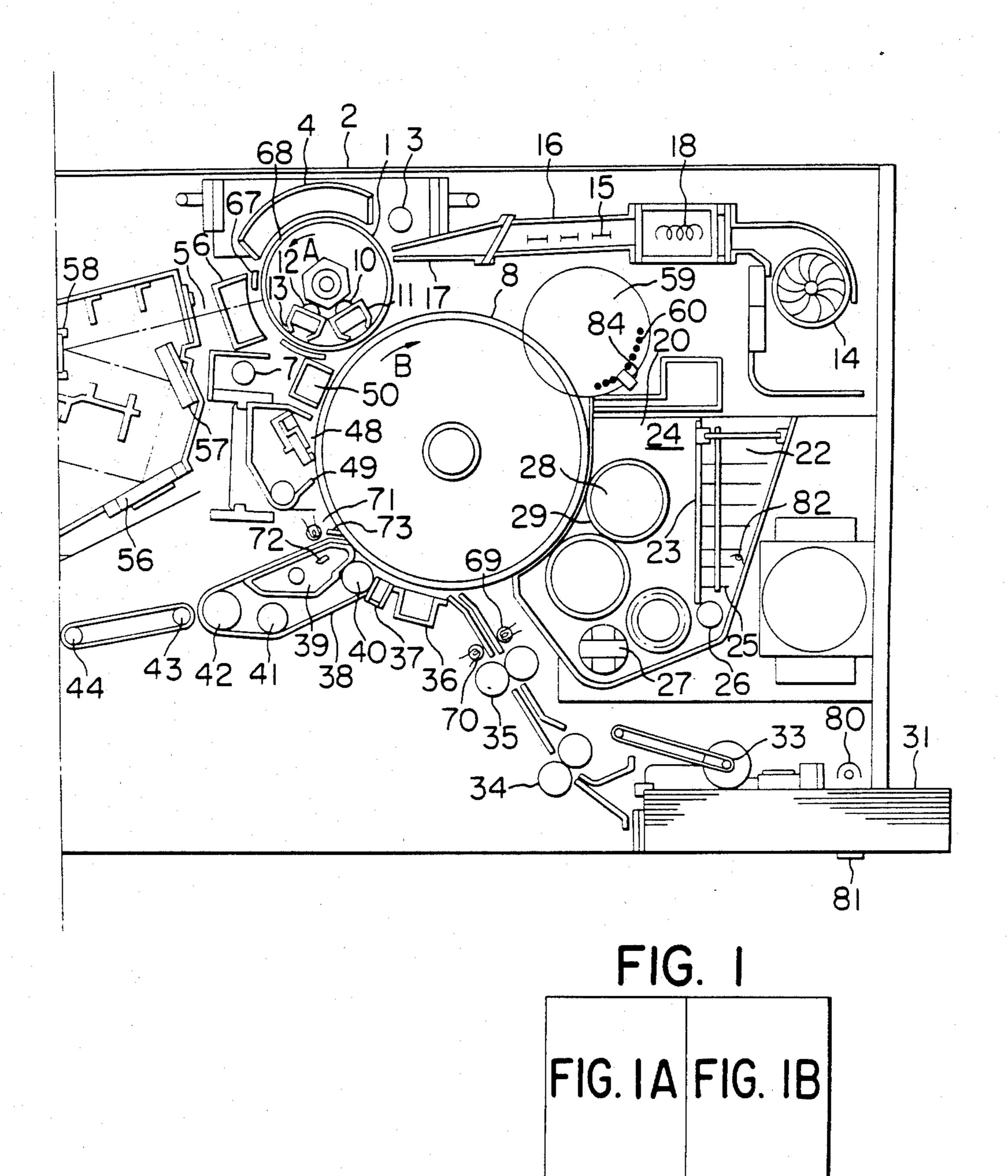


FIG. 1B



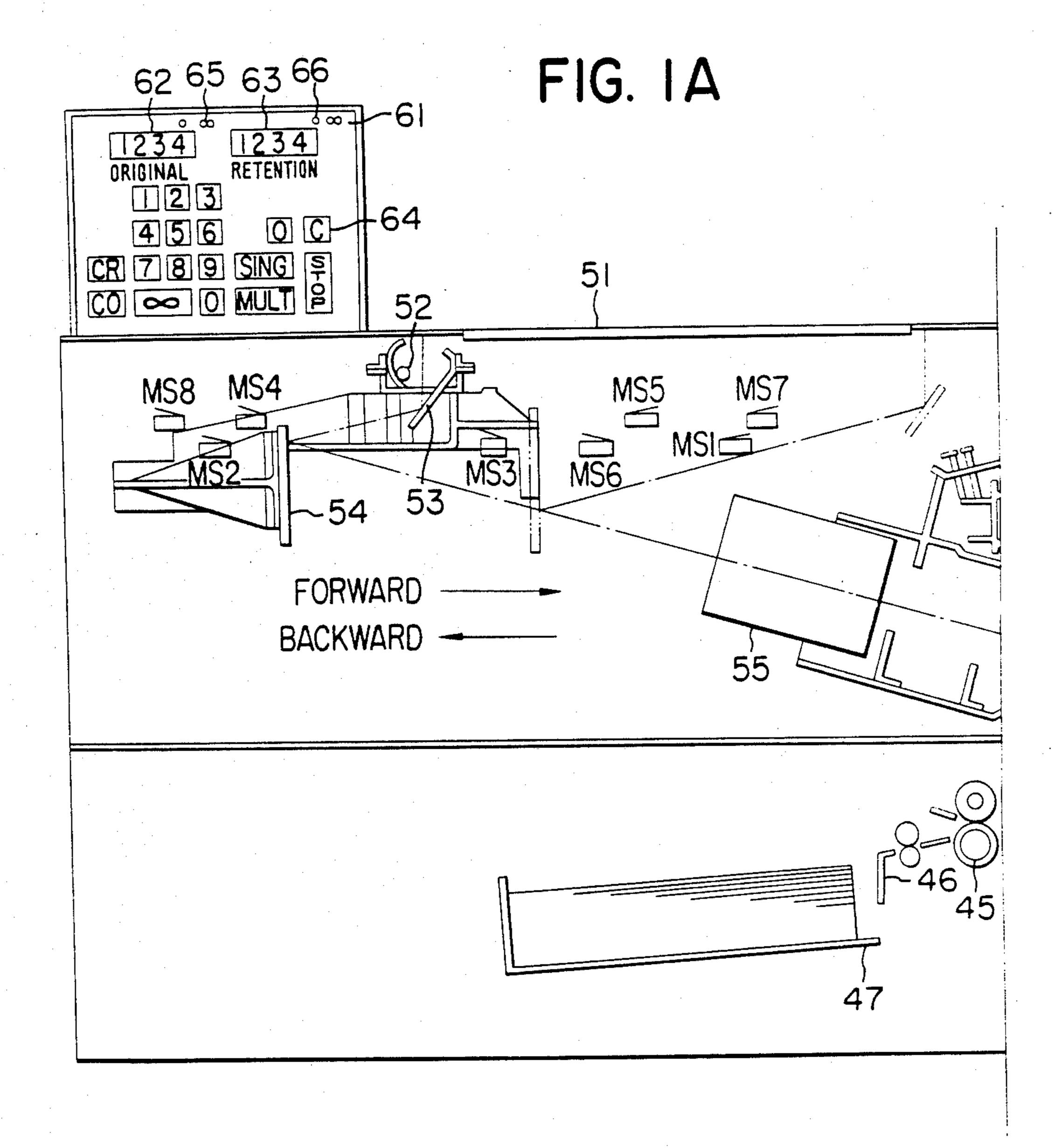


FIG. 2B

FIG. 2

FIG. 2A FIG. 2B

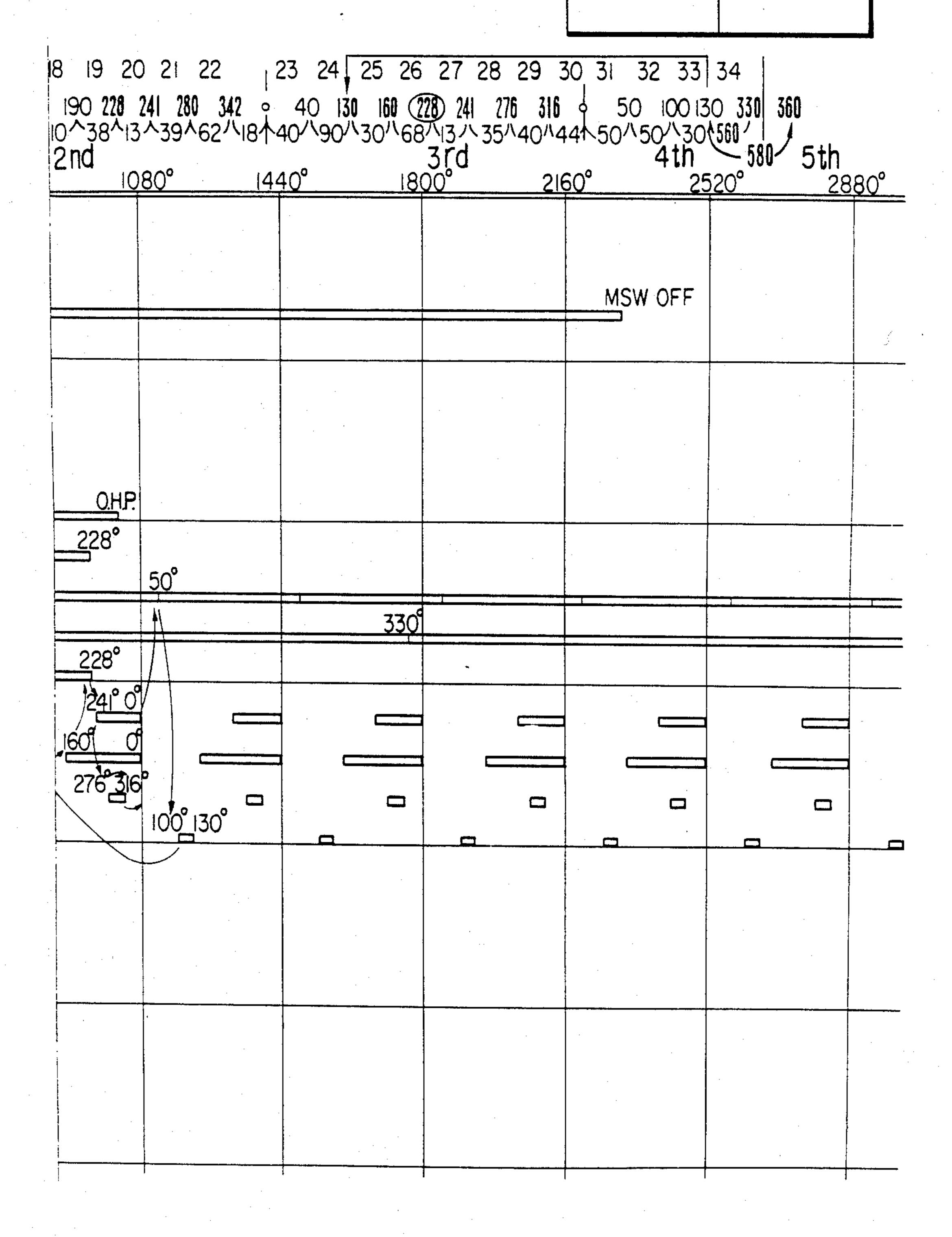
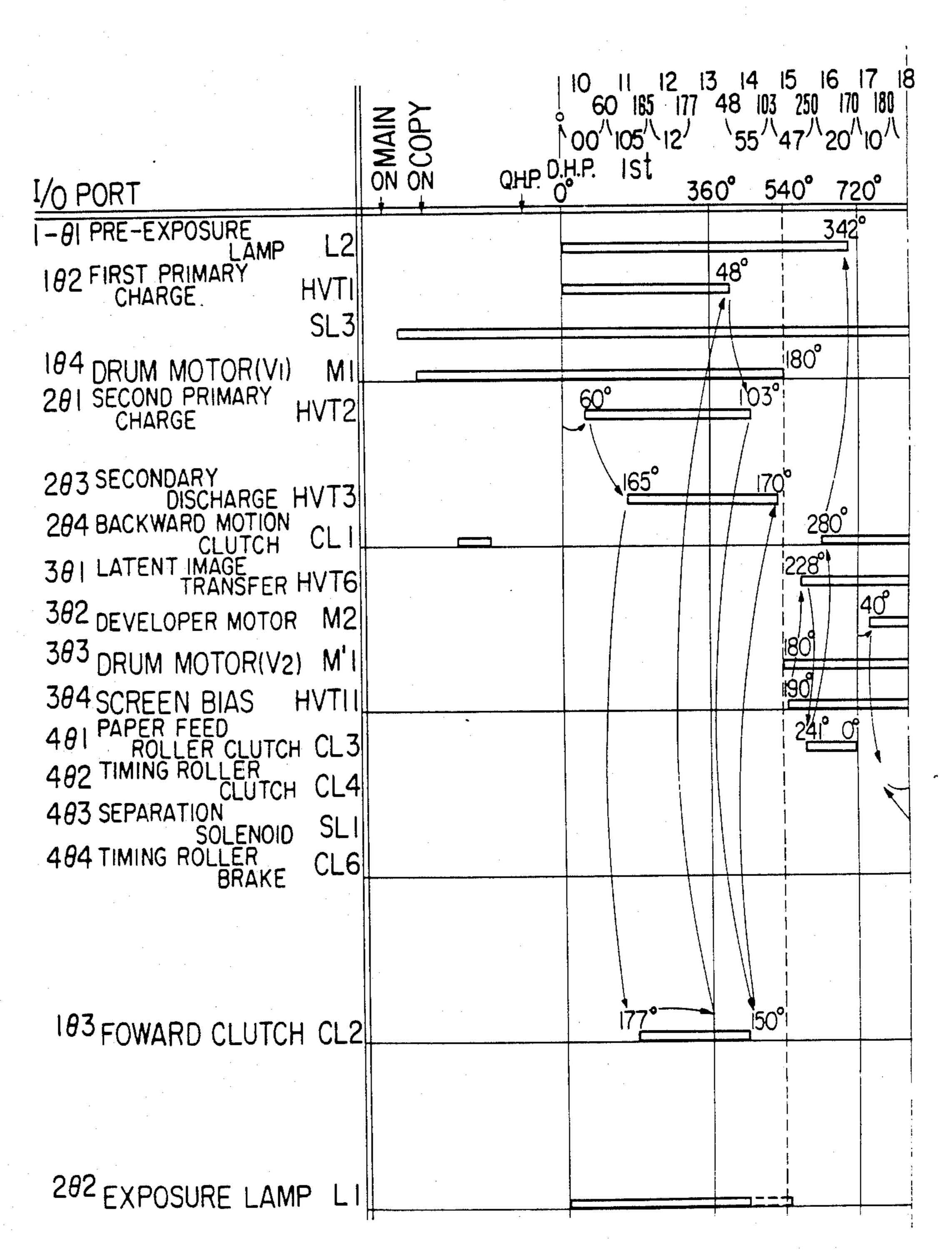
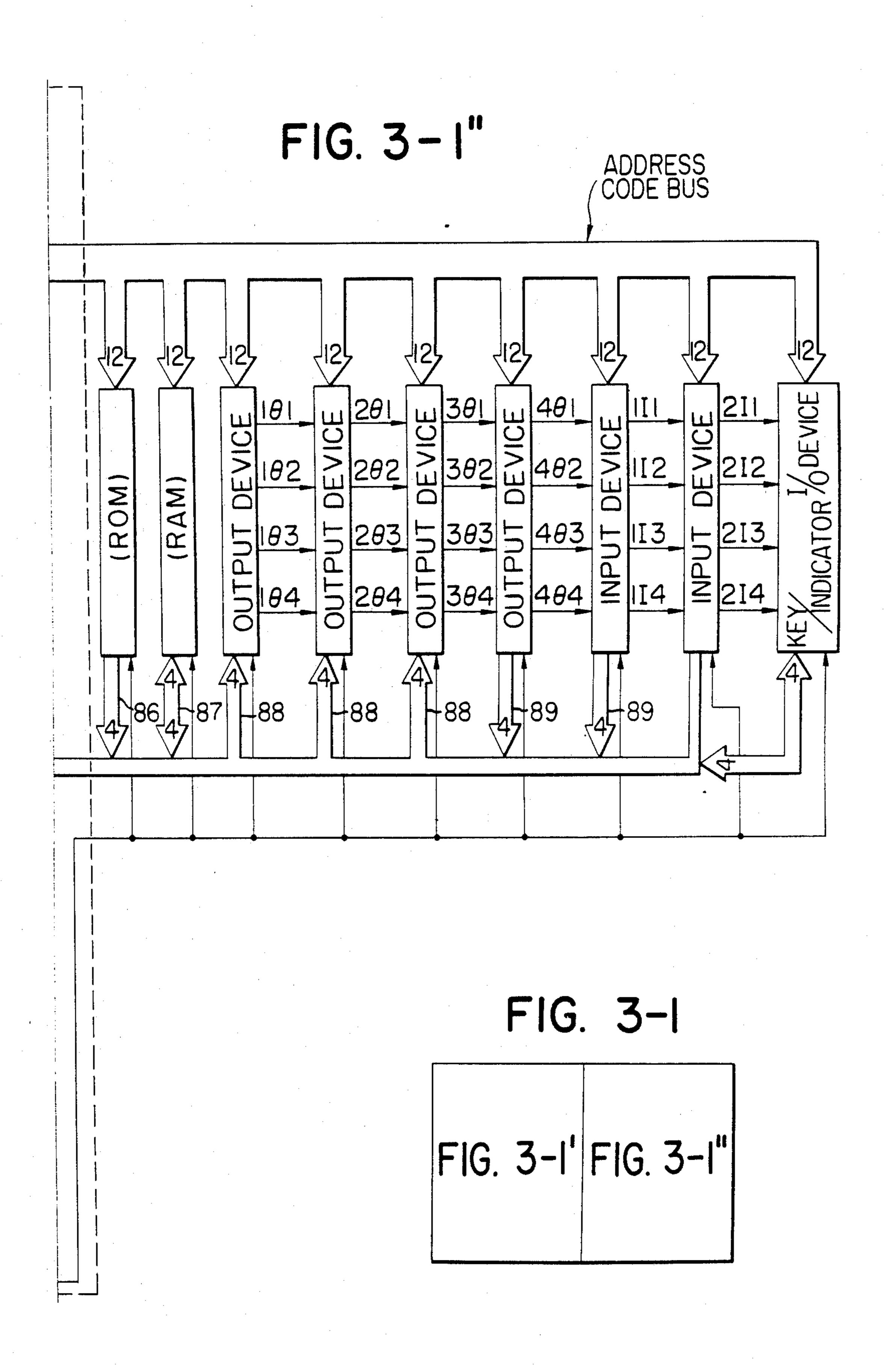
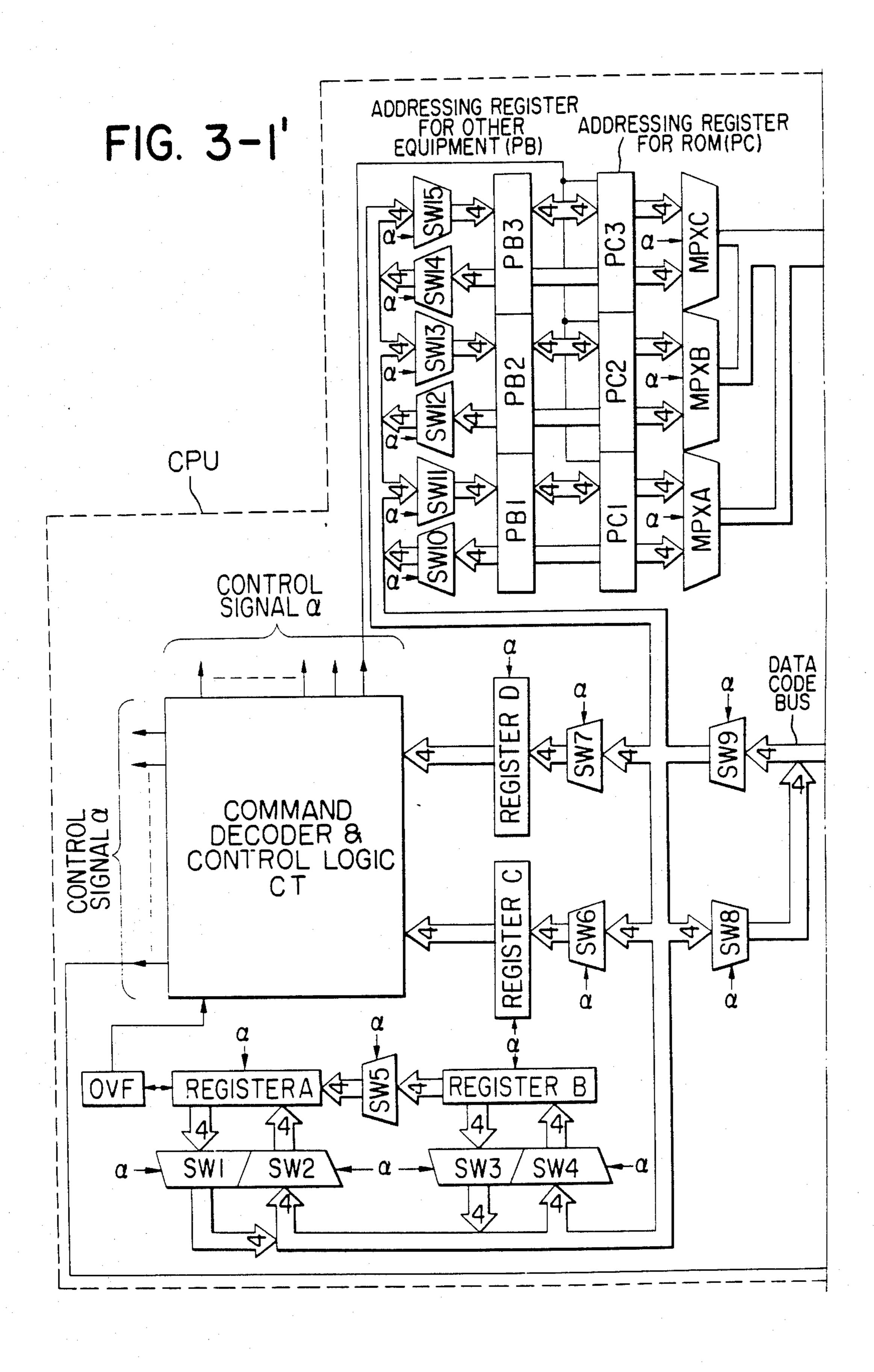


FIG. 2A









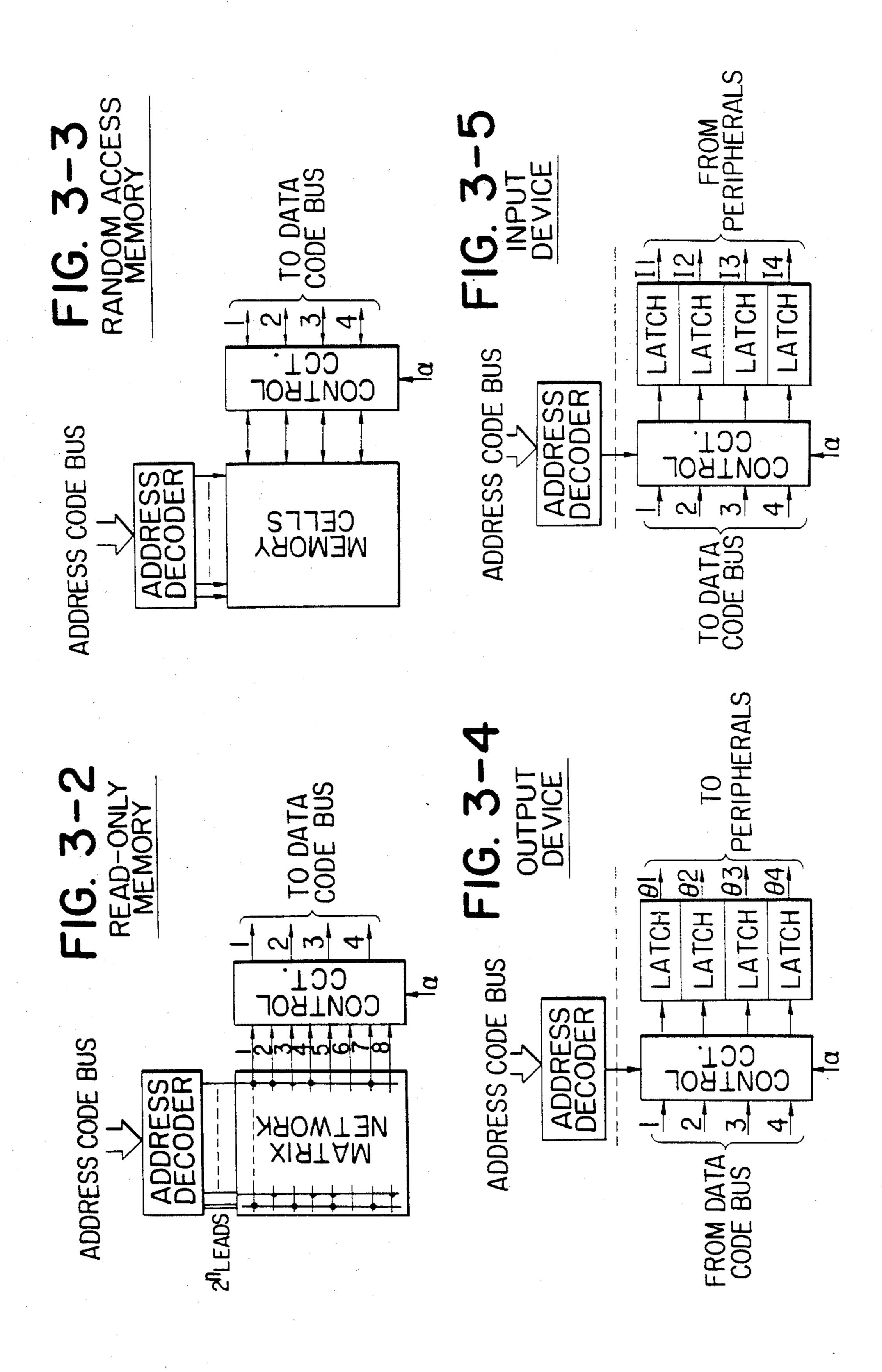
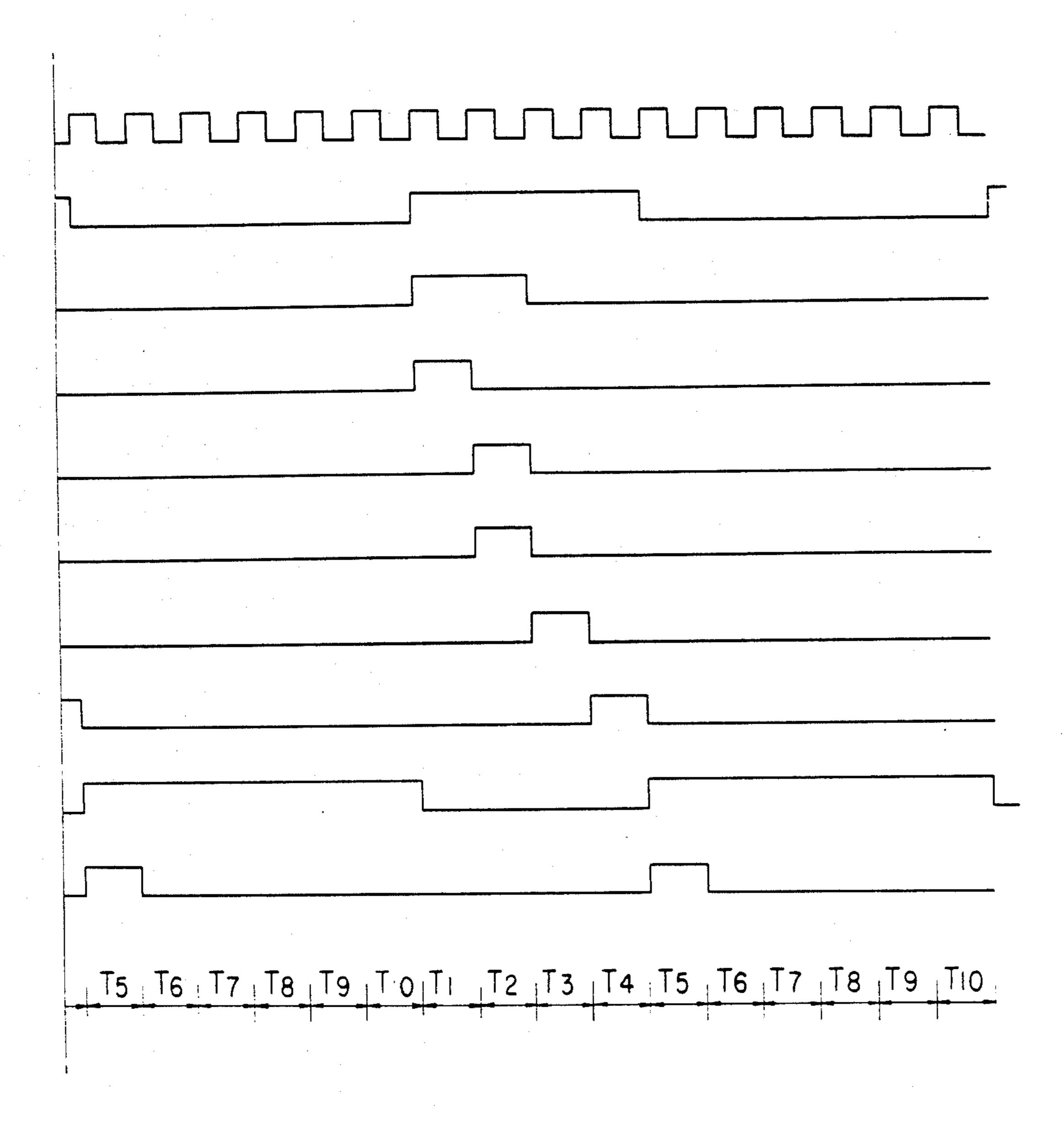
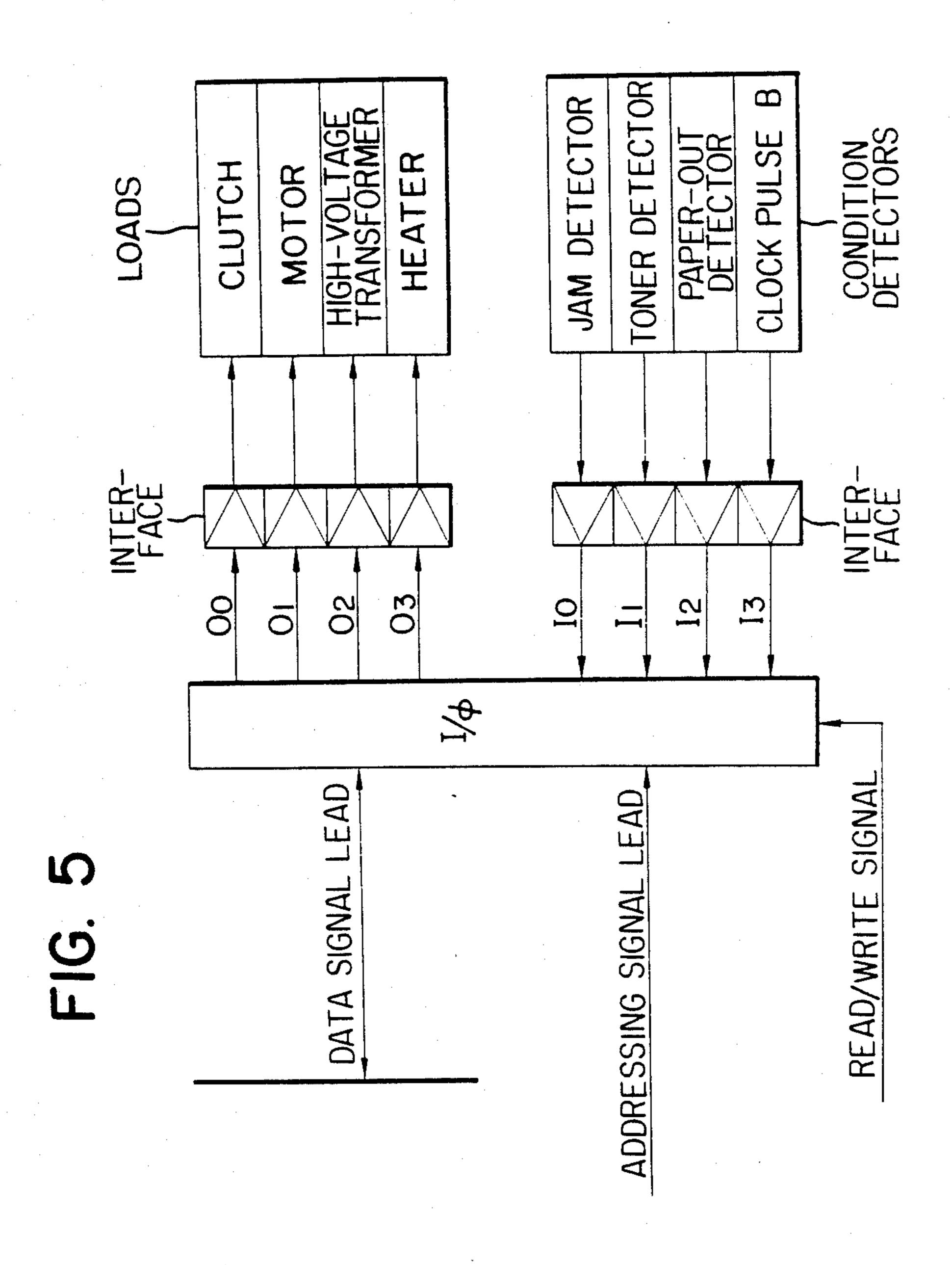


FIG. 4A

BASIC CLOCK P	
INTERVALS FOR DECODING AN ORDER ADDRESSING THE PROGRAM STORED	
INTERVALS FOR REG. PC TO DEVELOP THE OUTPUT TO ADDRESS CODE BUS BY SWITCHING MPX A-C.	
INTERVALS FOR CONNECTING INSTRUCTION CODE LINES 1-4 OF ROM TO DATA CODE BUS	
INTERVALS FOR LATCHING THE DATA CODE BUS SIGNAL TO REG. C	
INTERVALS FOR CONNECTING INSTRUCTION CODE LINES 5-8 TO DATA CODE BUS	
INTERVALS FOR LATCHING THE DATA CODE BUS SIGNAL TO REG. D	
INTERVALS FOR DECODING THE CONTENTS OF REGS. C & D	
PROGRAM INSTRUCTION EXECUTING INTERVALS	
INTERVALS FOR REG. PB ADDRESSING EQUIPMENT OTHER THAN ROM TO DEVELOP THE OUTPUT TO THE BUS BY SWITCHING MPX A-C	
	T_1 T_2 T_A
FIG. 4	μsec
BASIC TIMING	
FIG. 4A FIG. 4B	

FIG. 4B





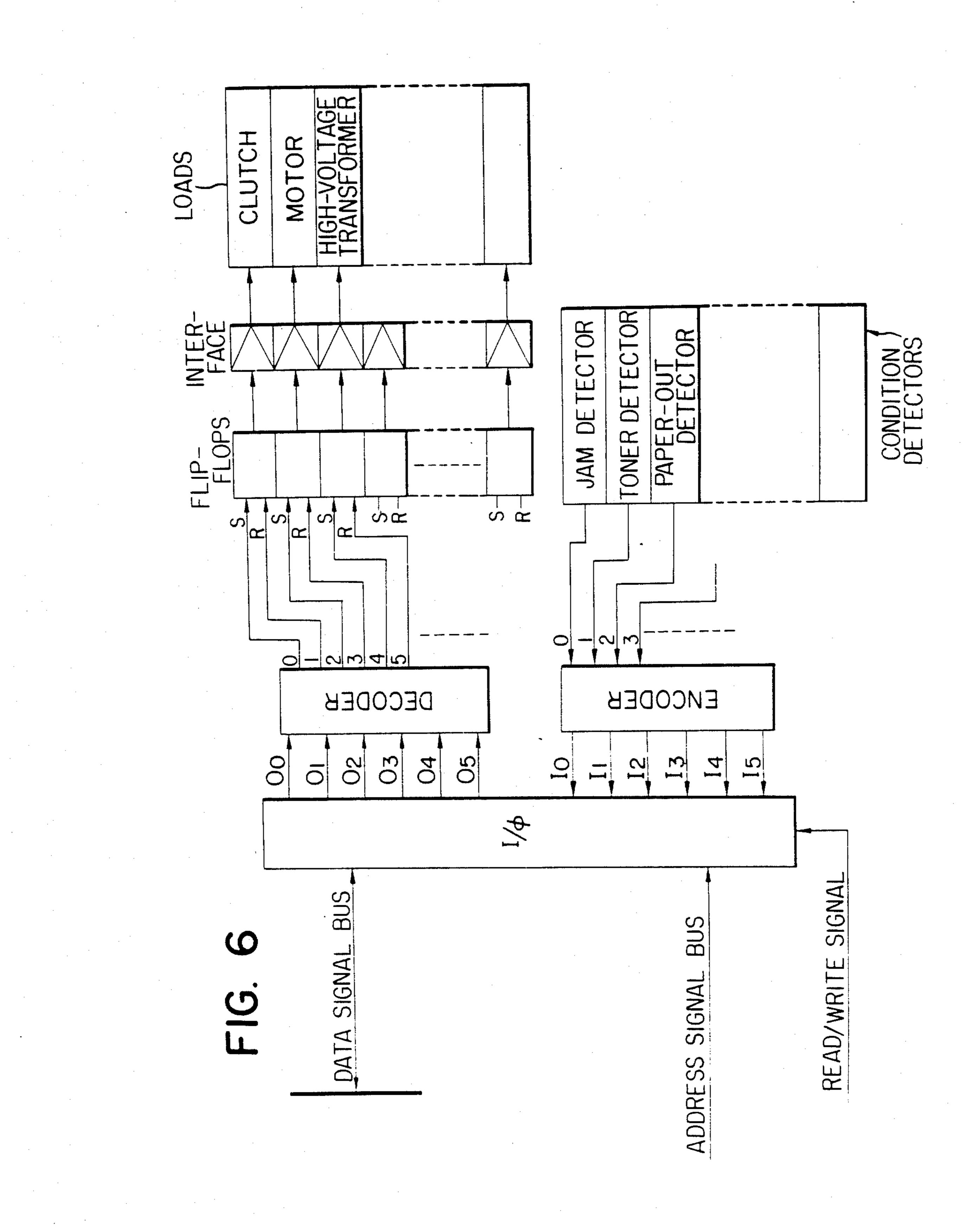
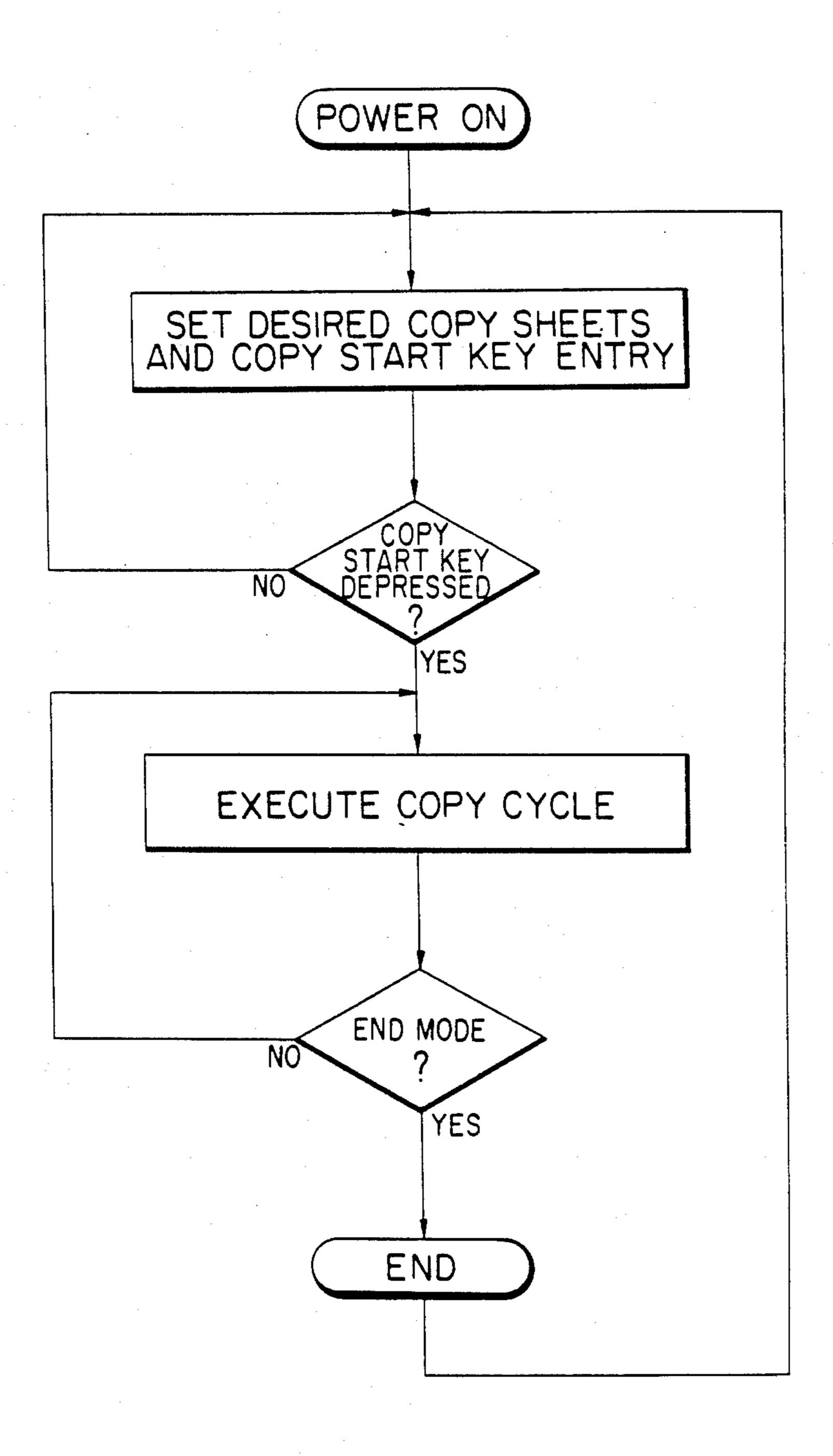
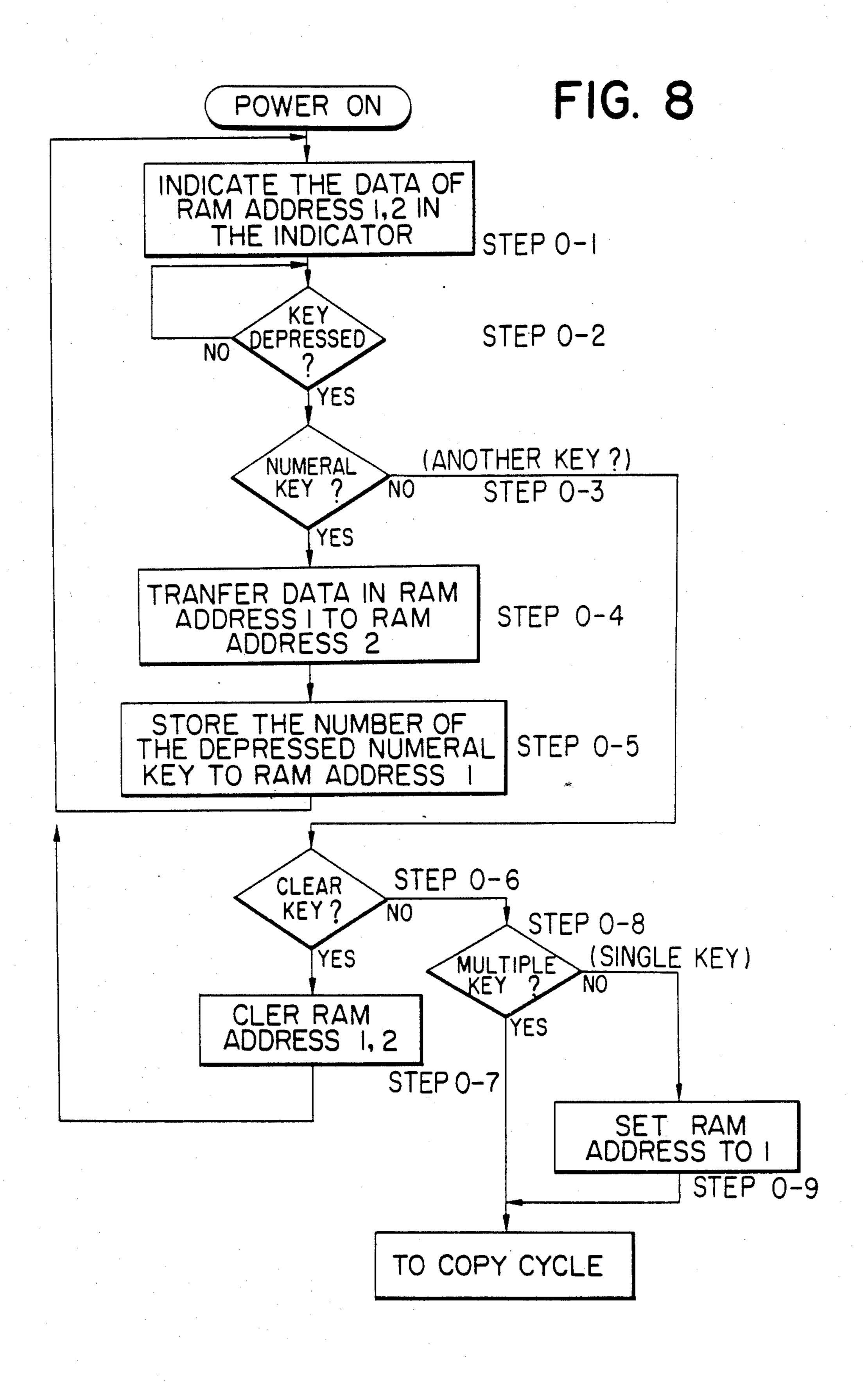
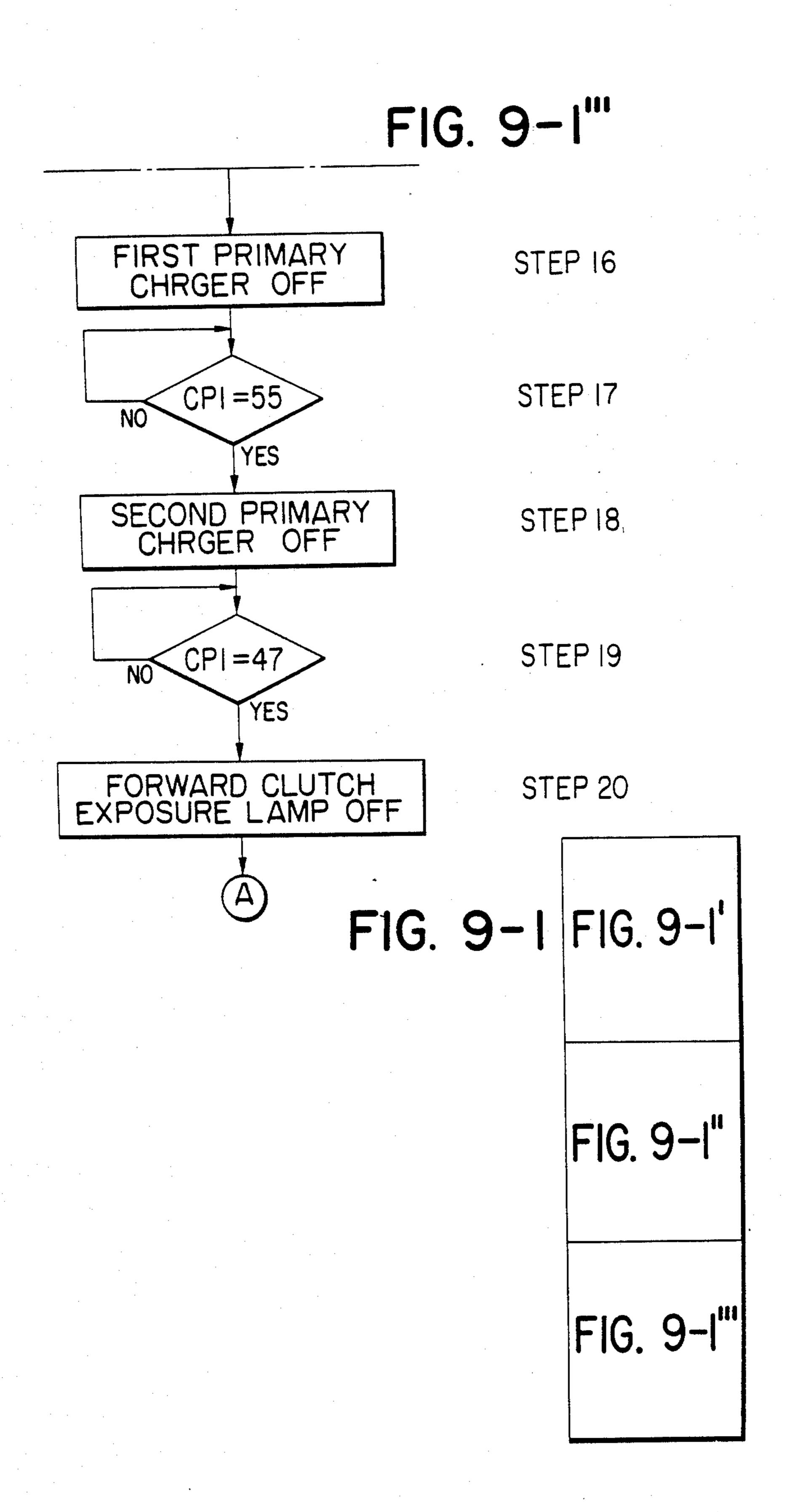
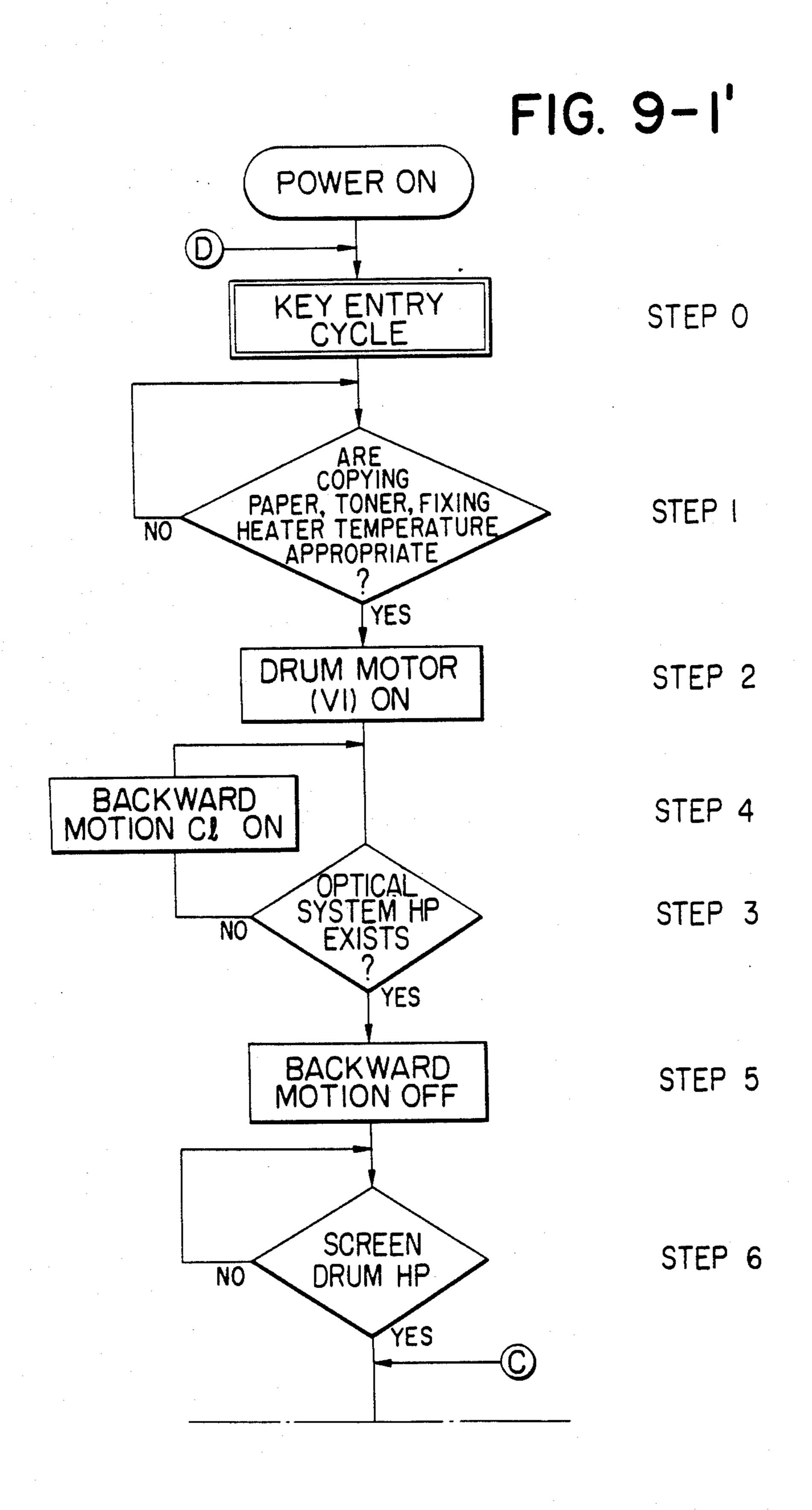


FIG. 7









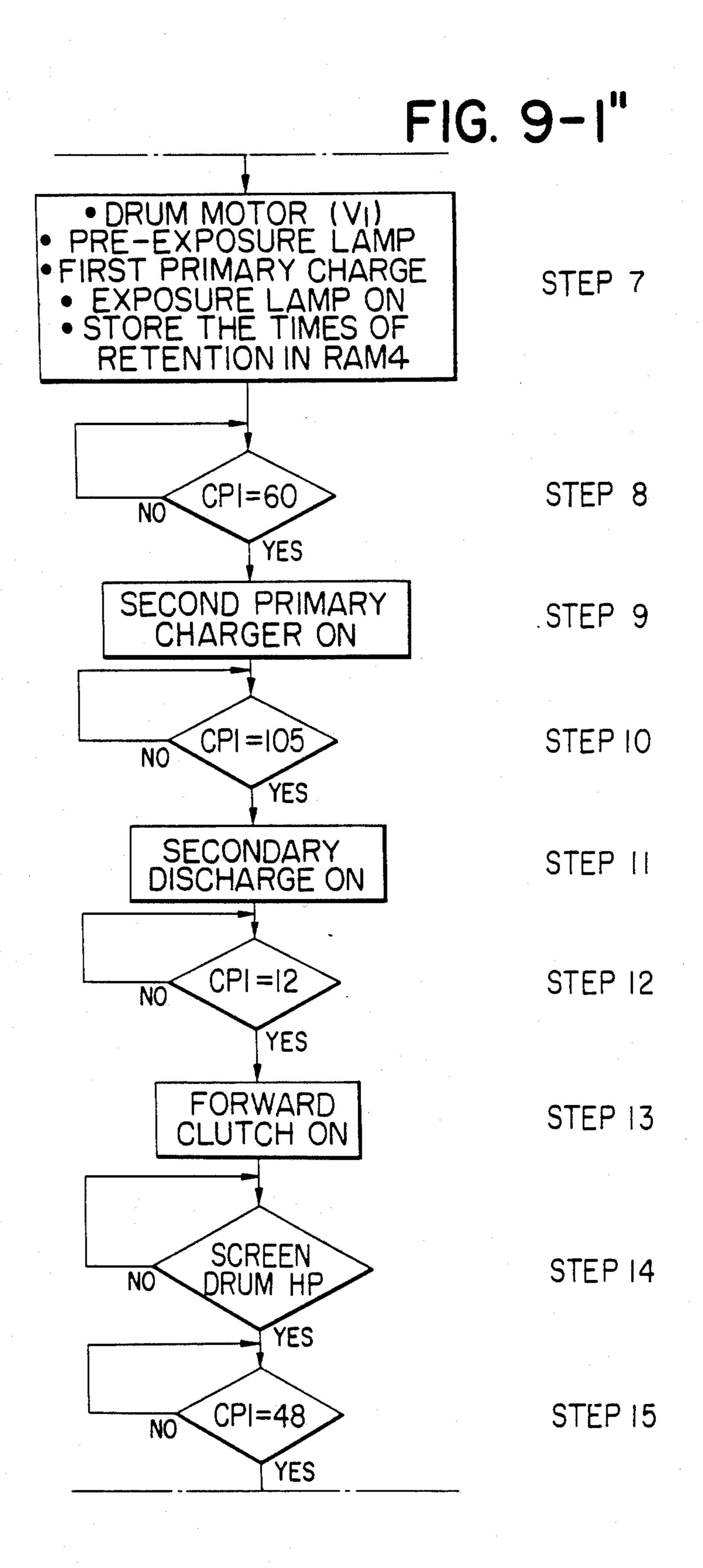


FIG. 9-2"

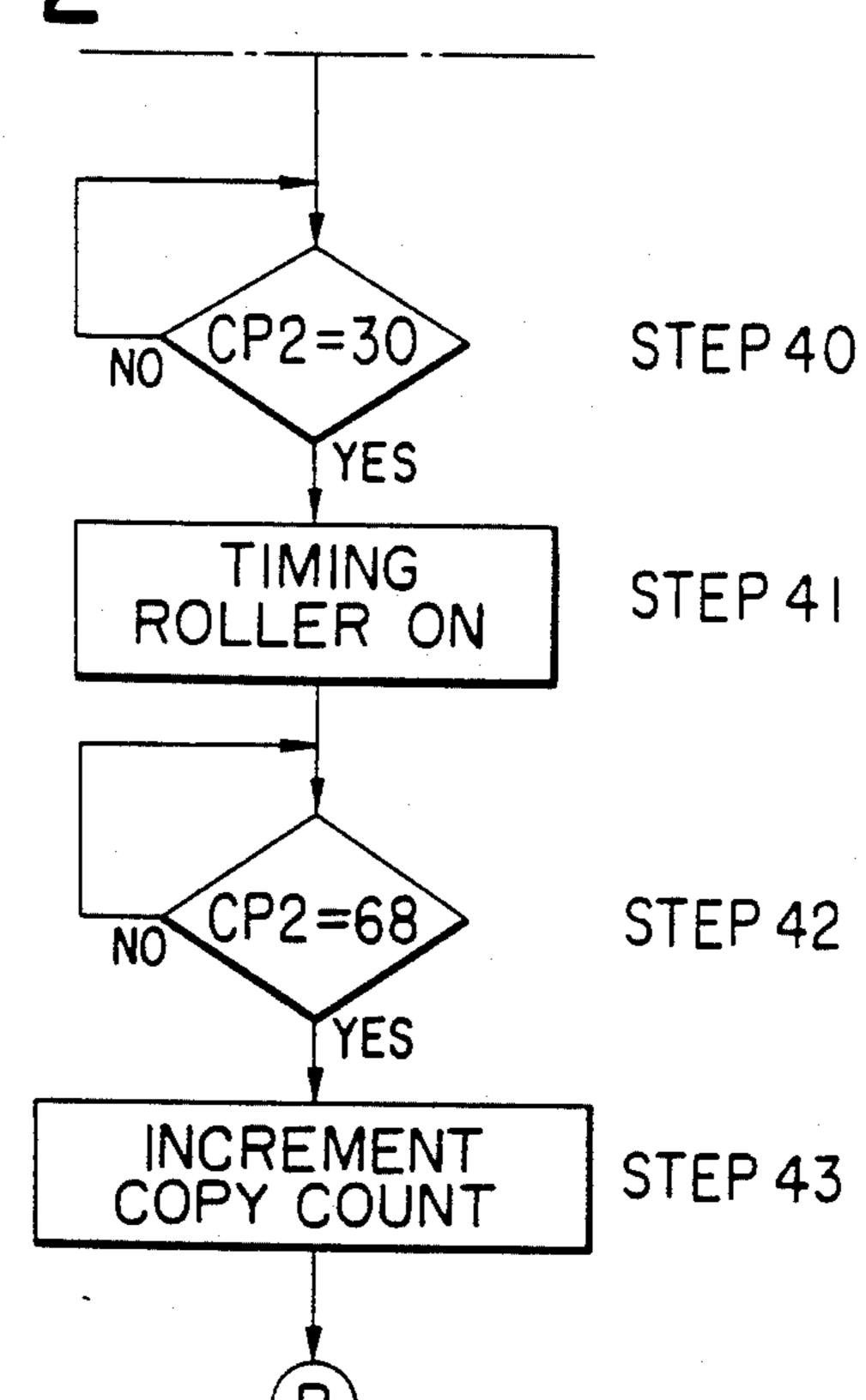
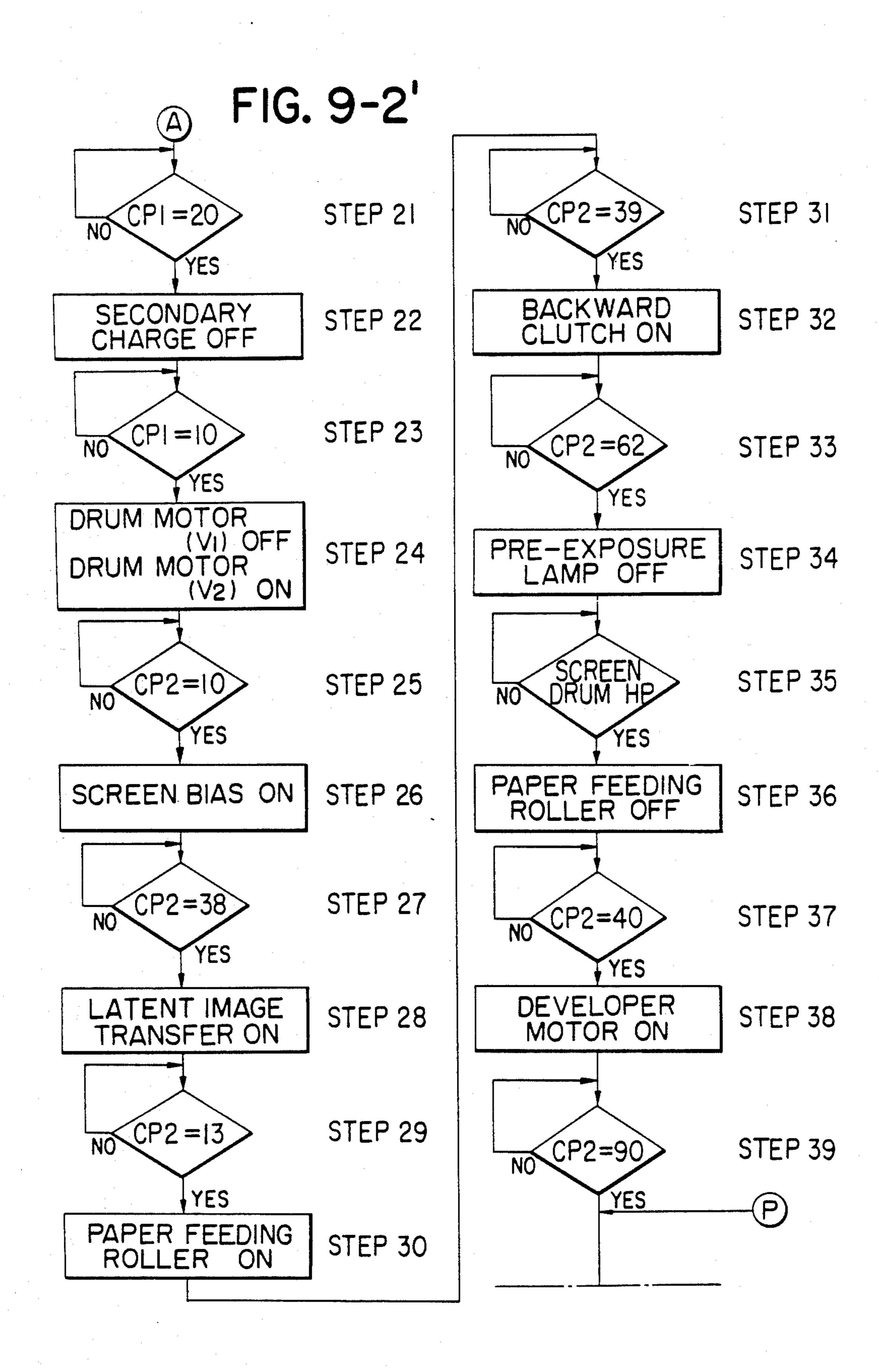
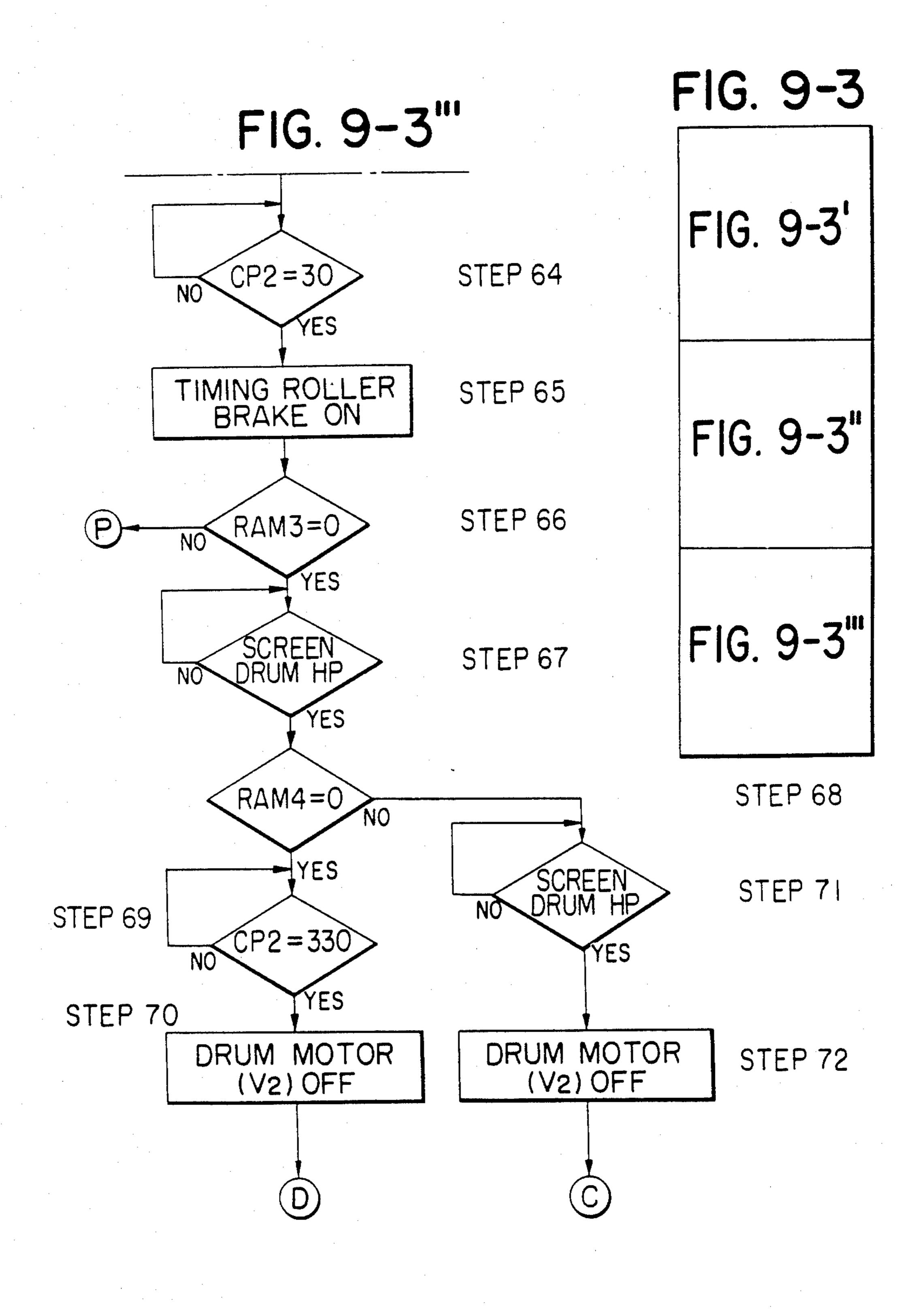


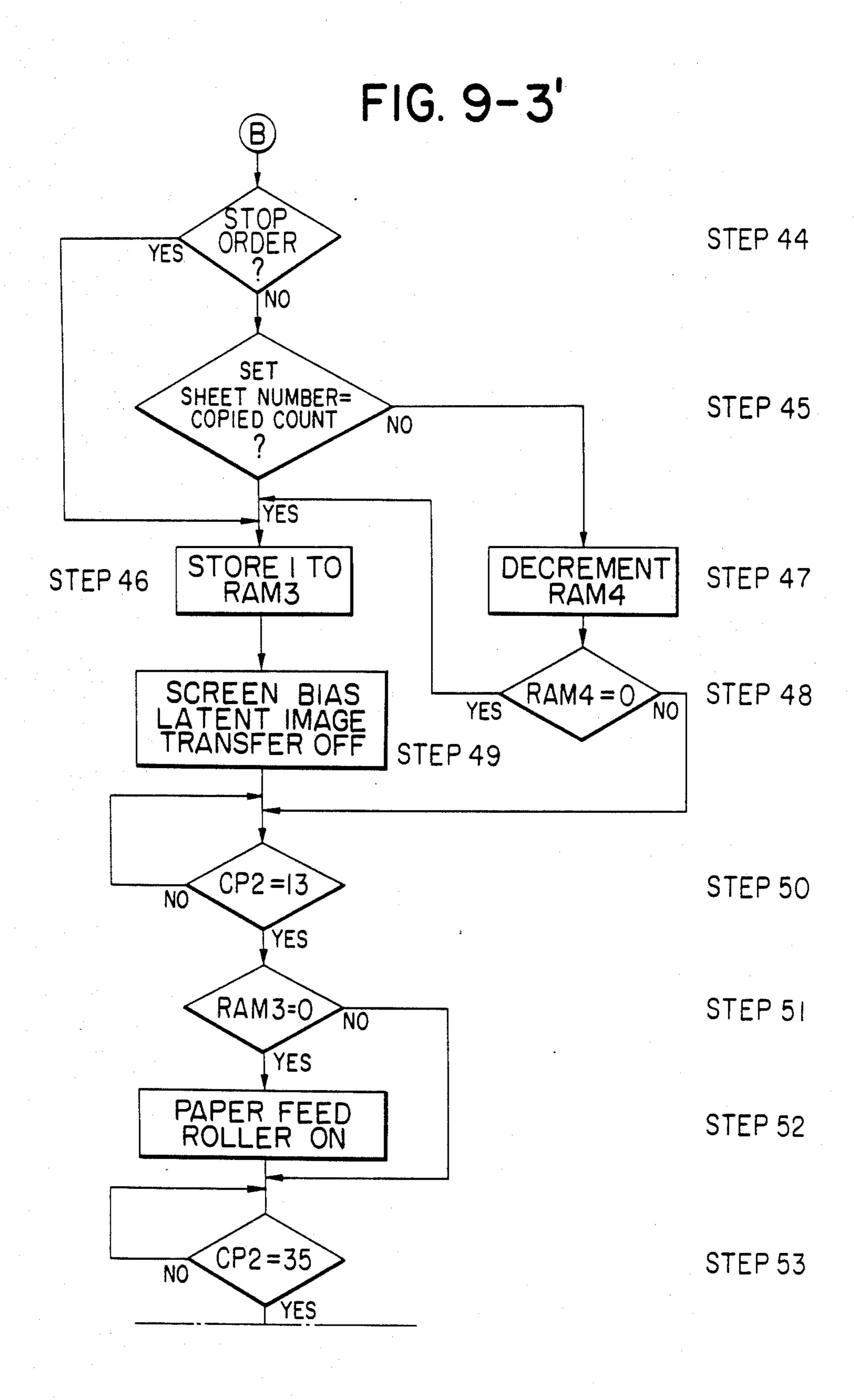
FIG. 9-2

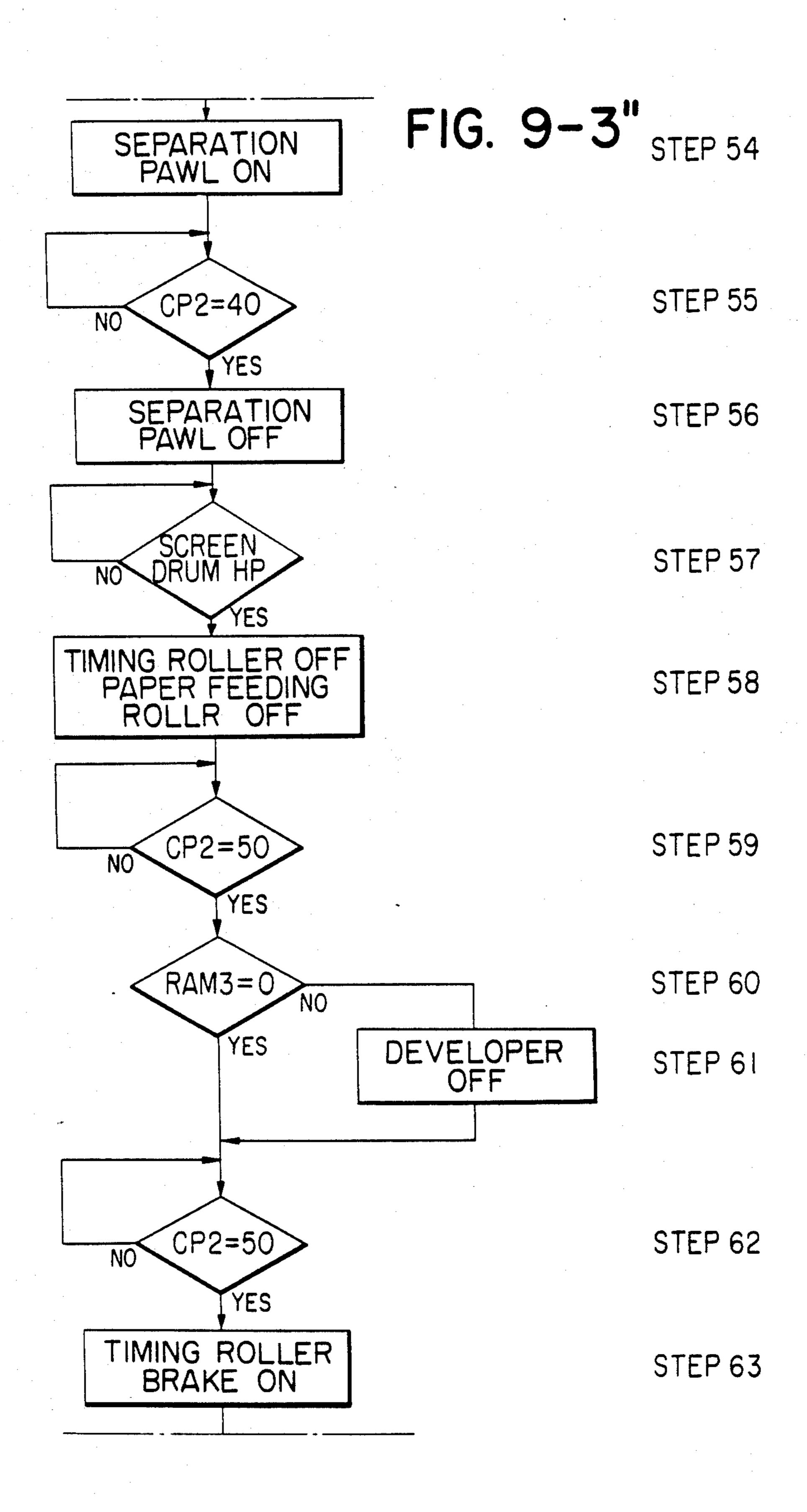
FIG. 9-2'

FIG. 9-2"









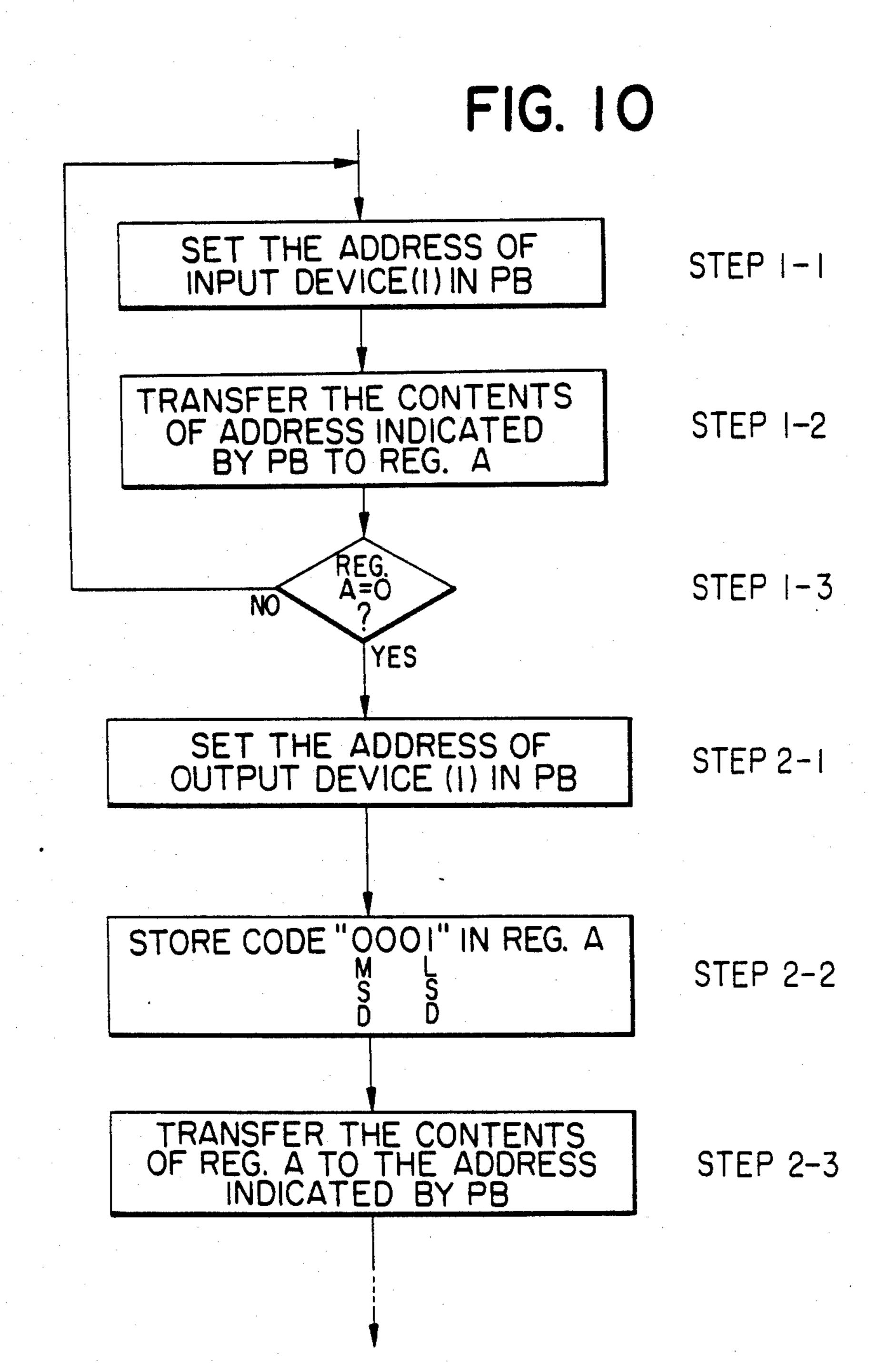
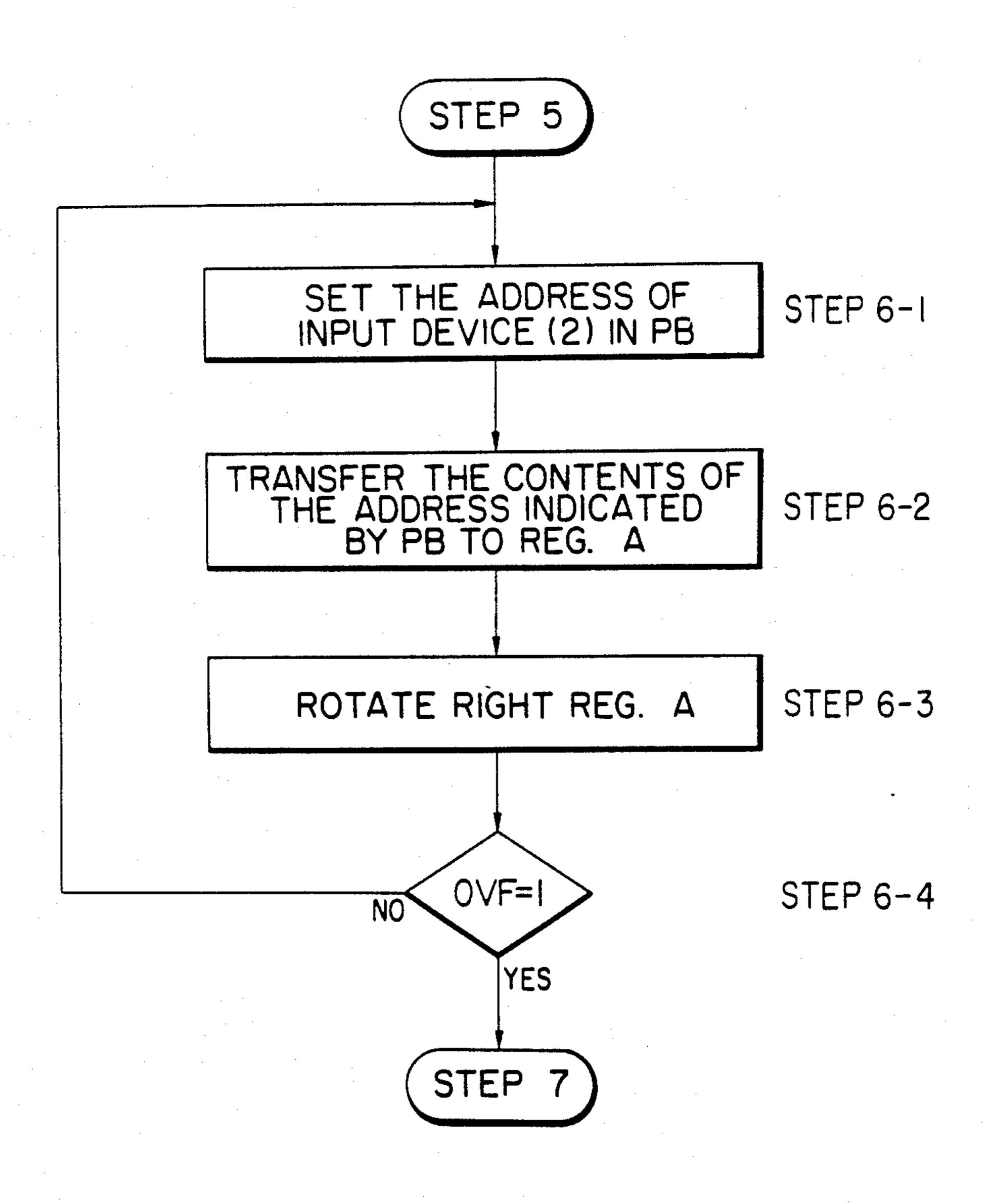
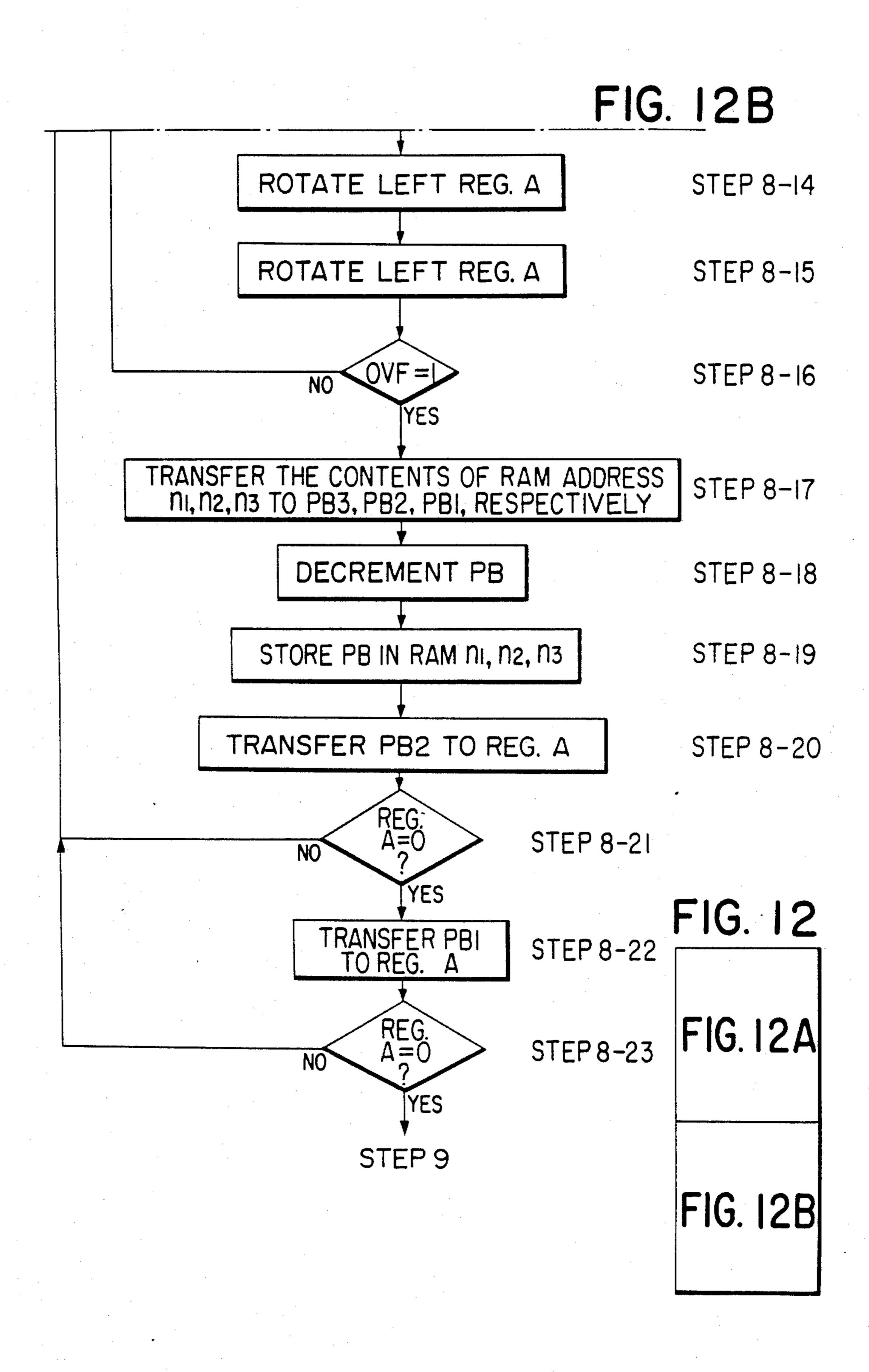
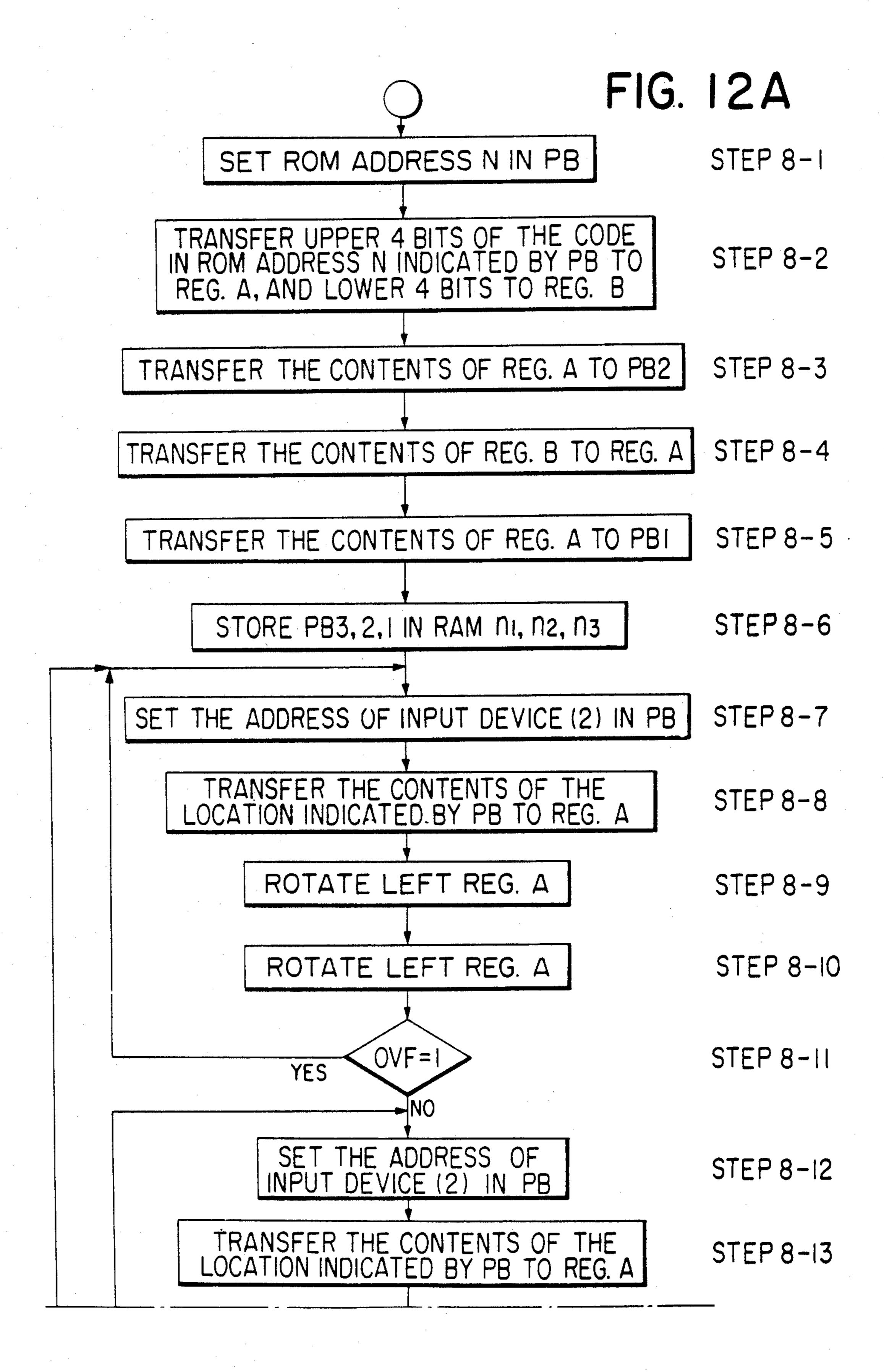
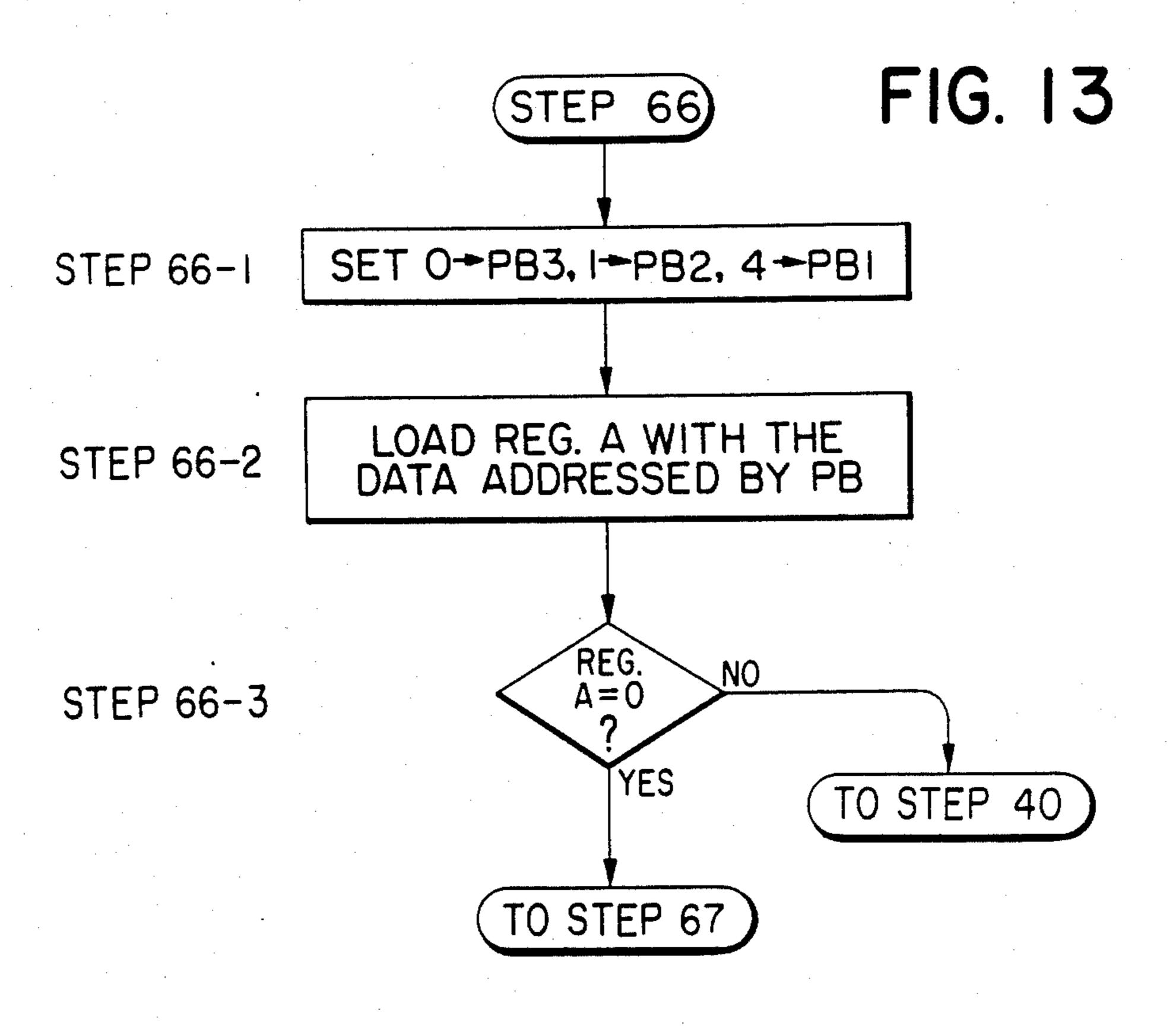


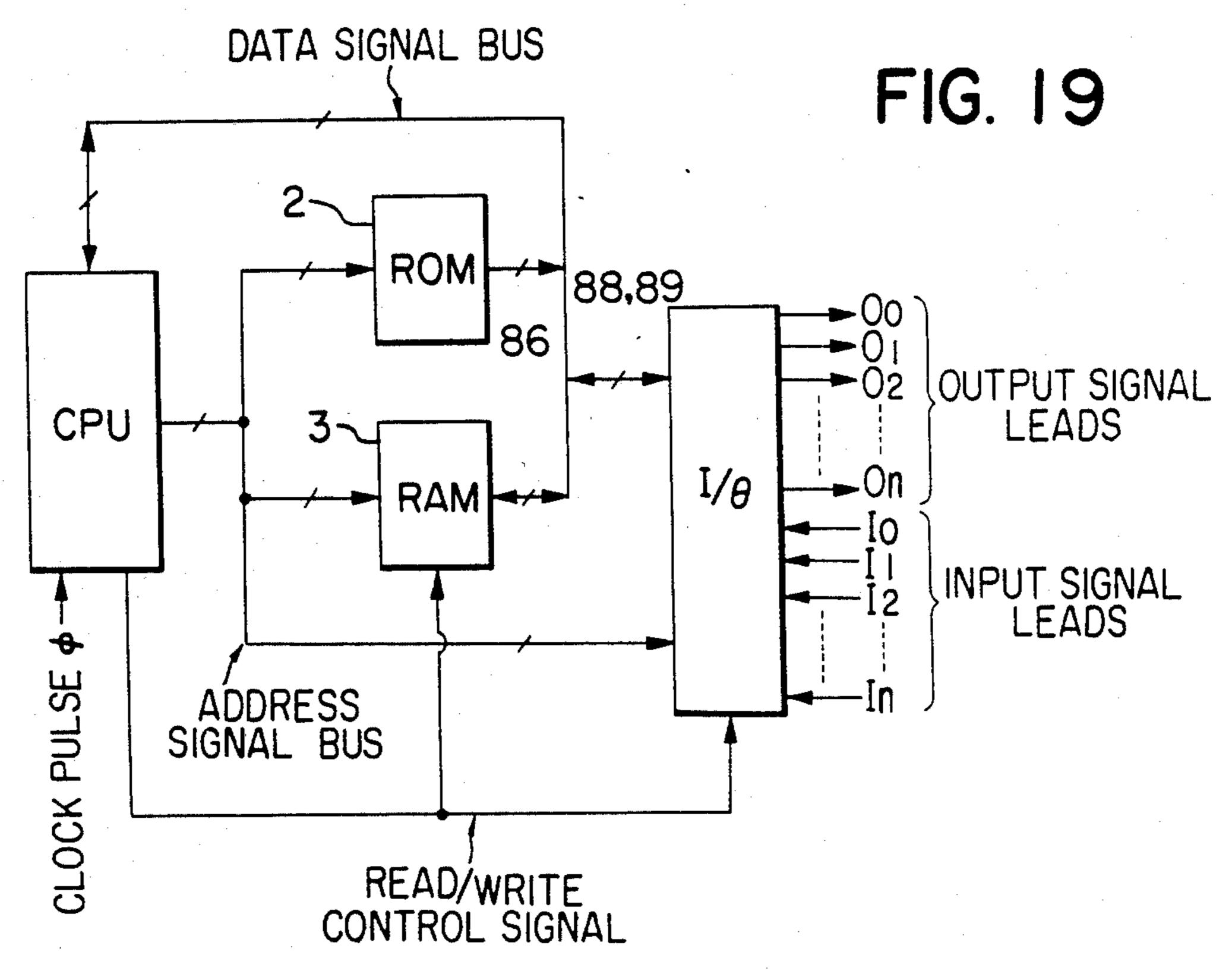
FIG. 11

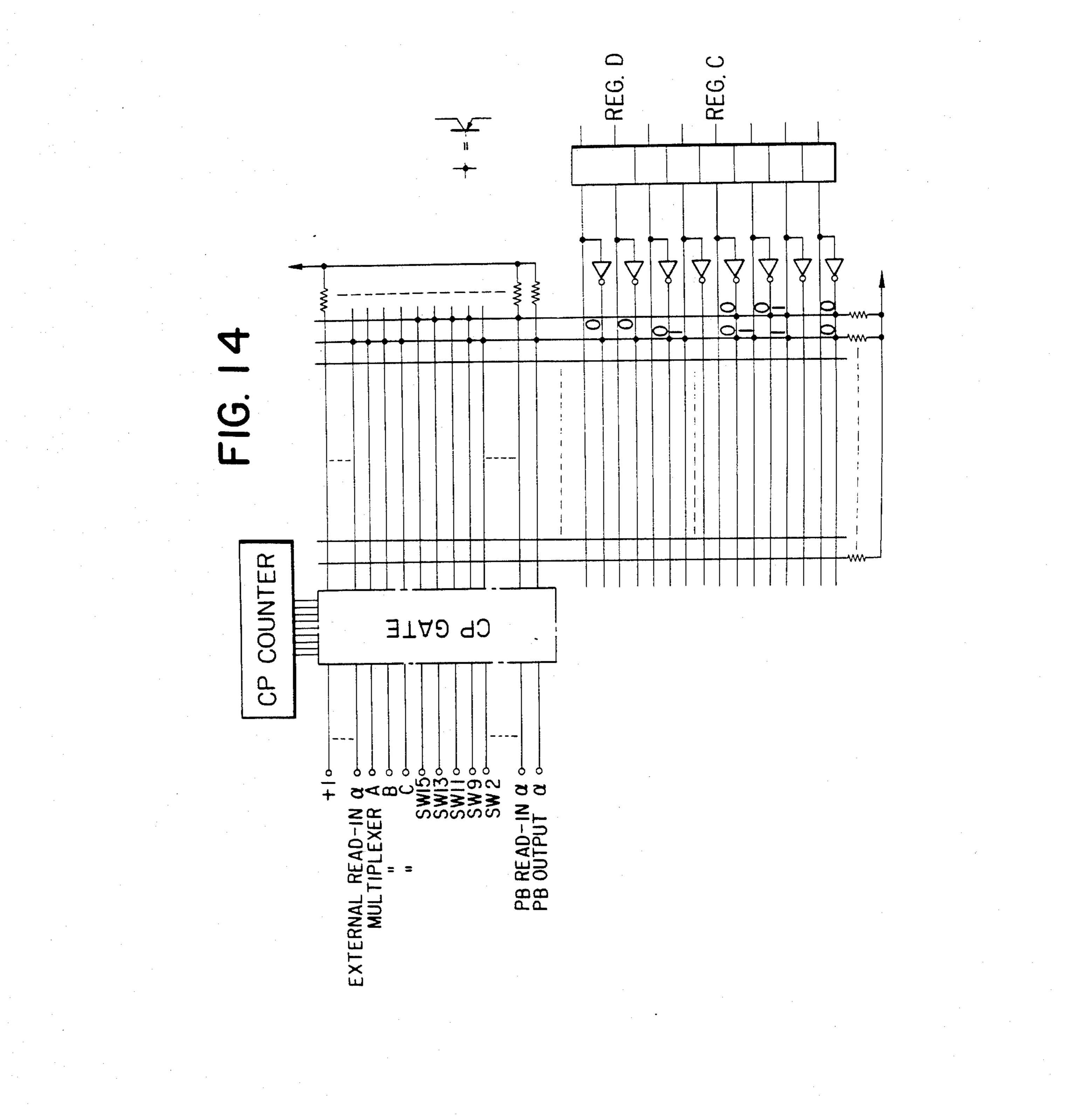


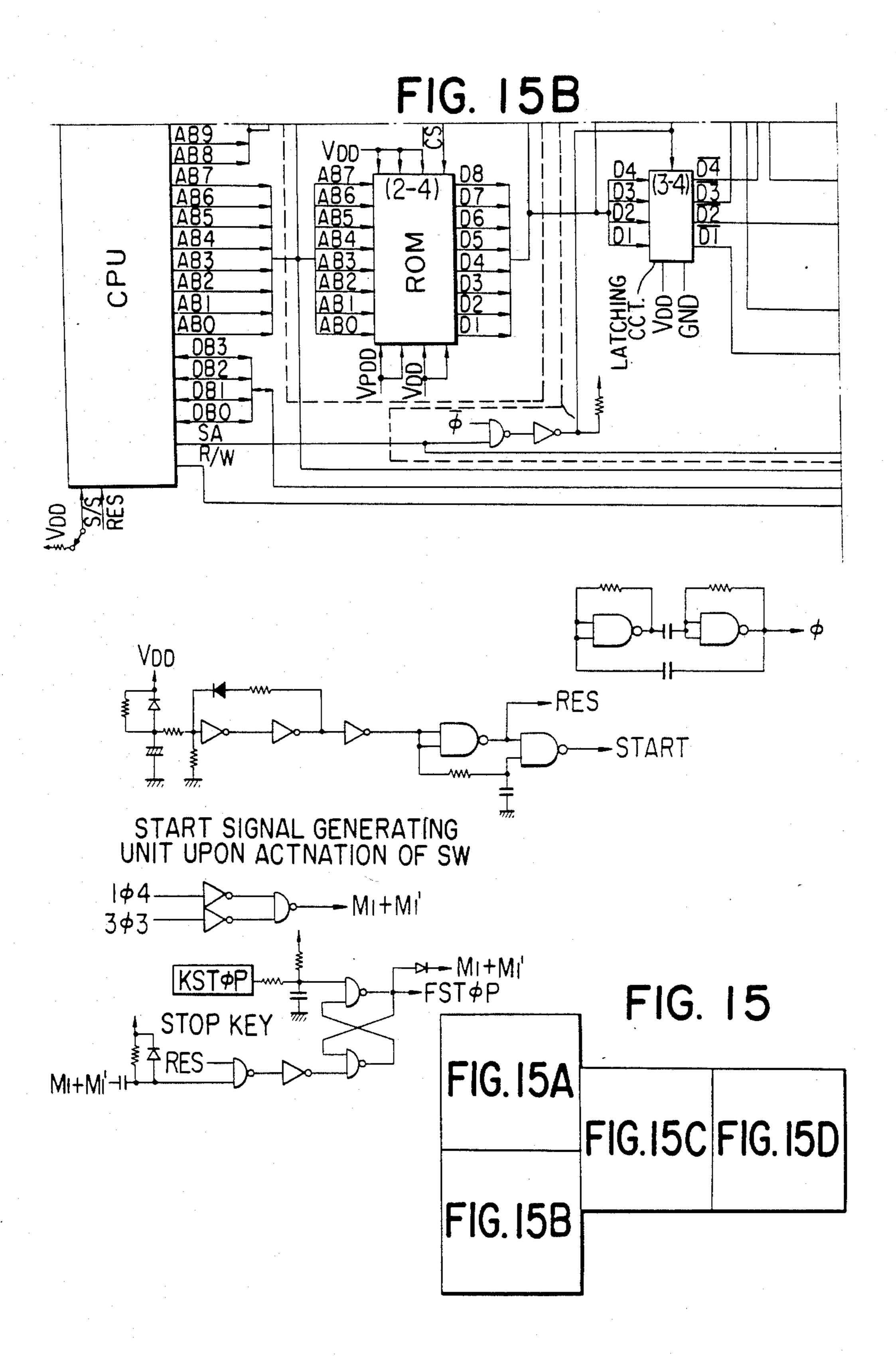












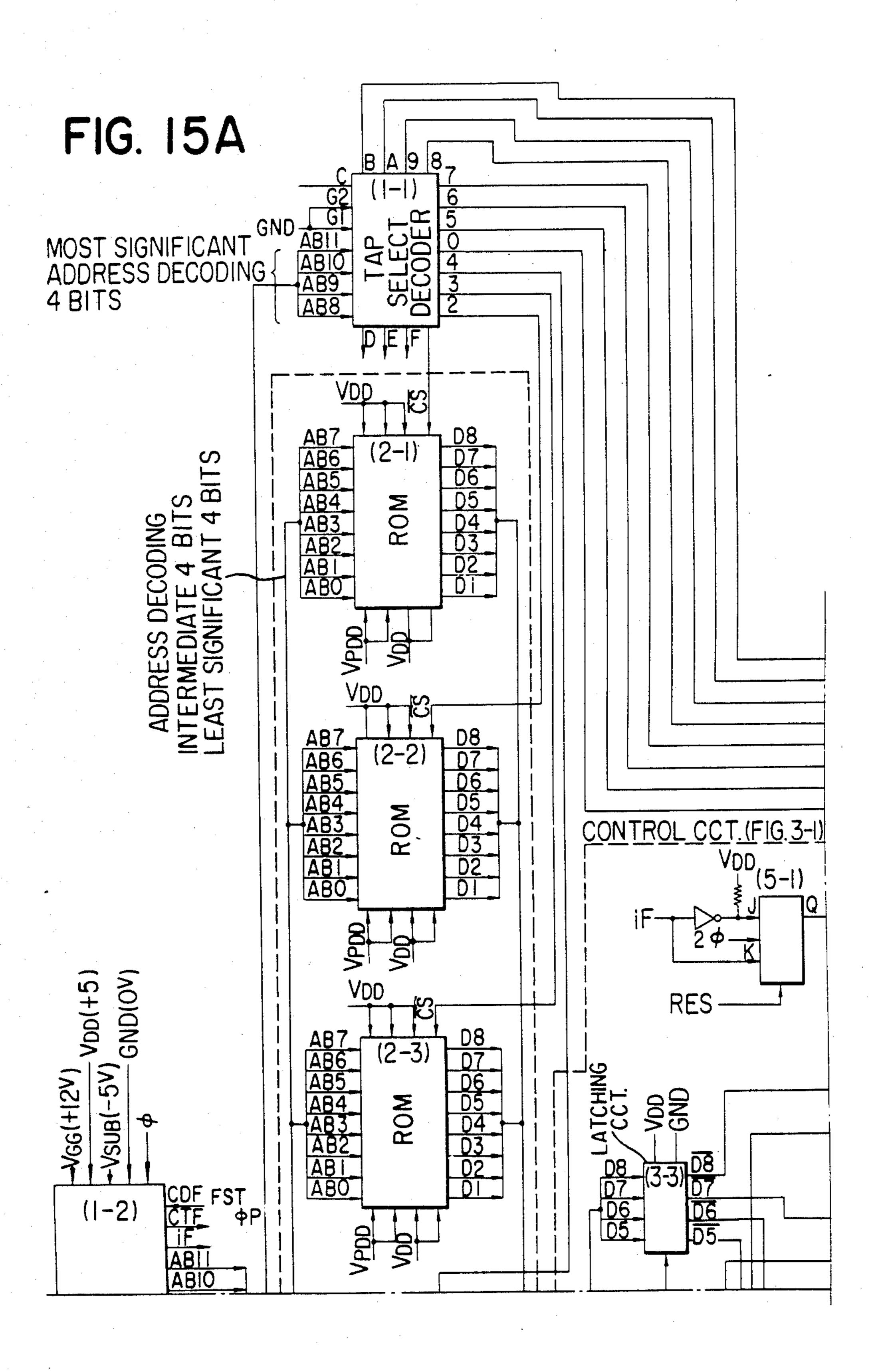
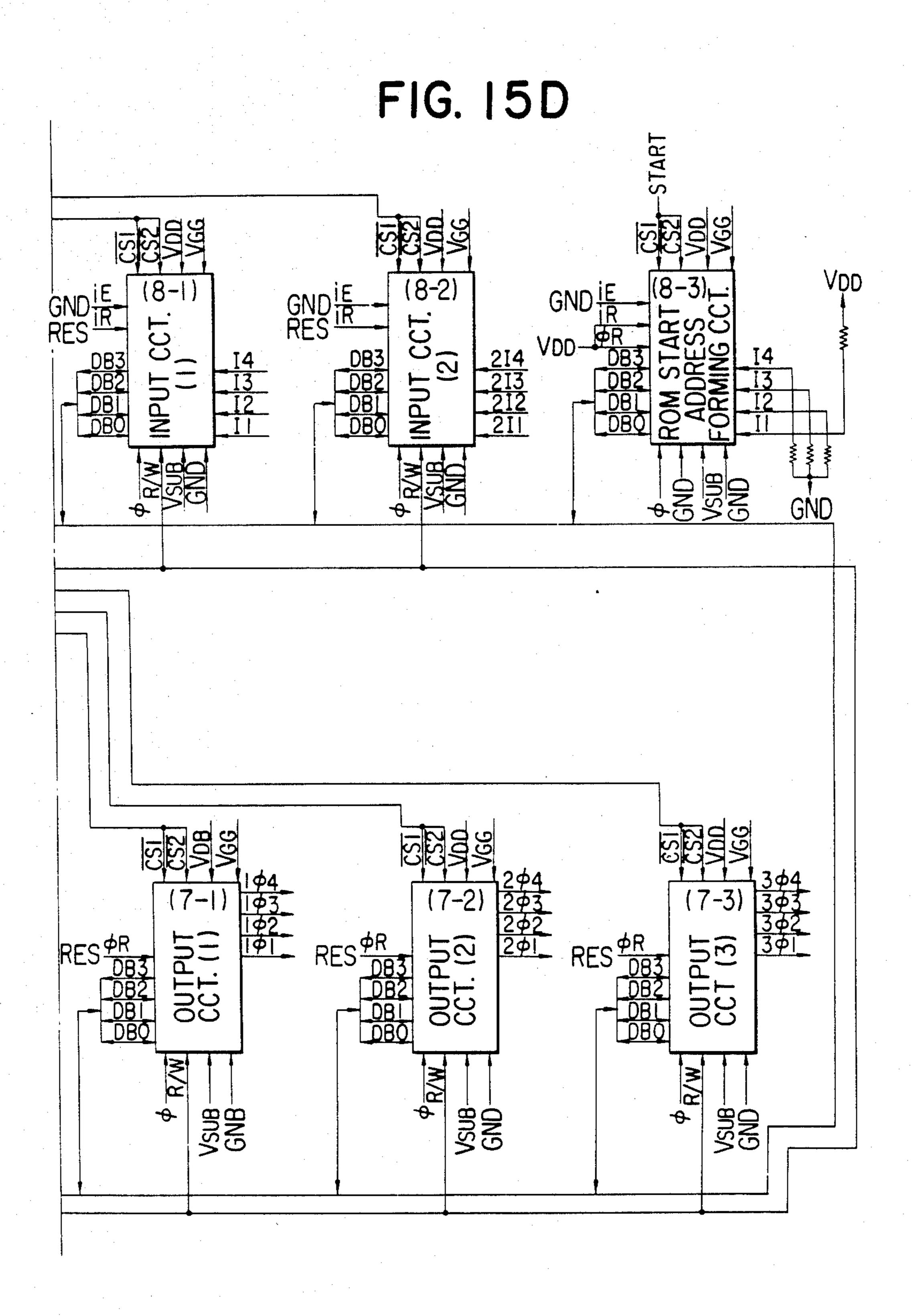
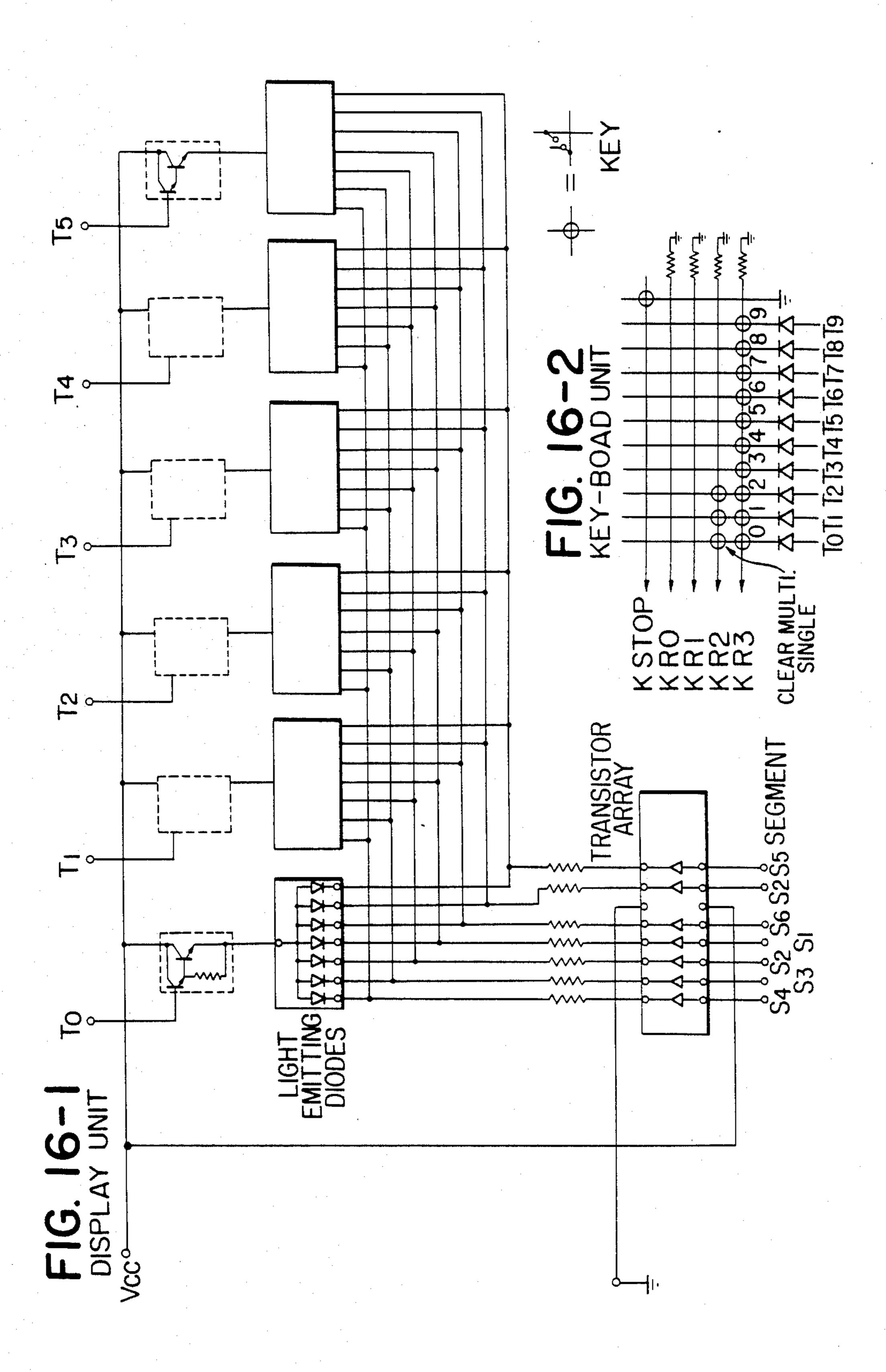


FIG. 15C RES KRI KRO VGG VDD, MPX DB2 GND V66 V66 VSUB, INPU DB3 AB7 MPX DBI AB6 DISPLAY DB2 19 DB3 DB2 DB1 DB0 RAM DBI DBO ABI ABO KΕΥ MPX D80





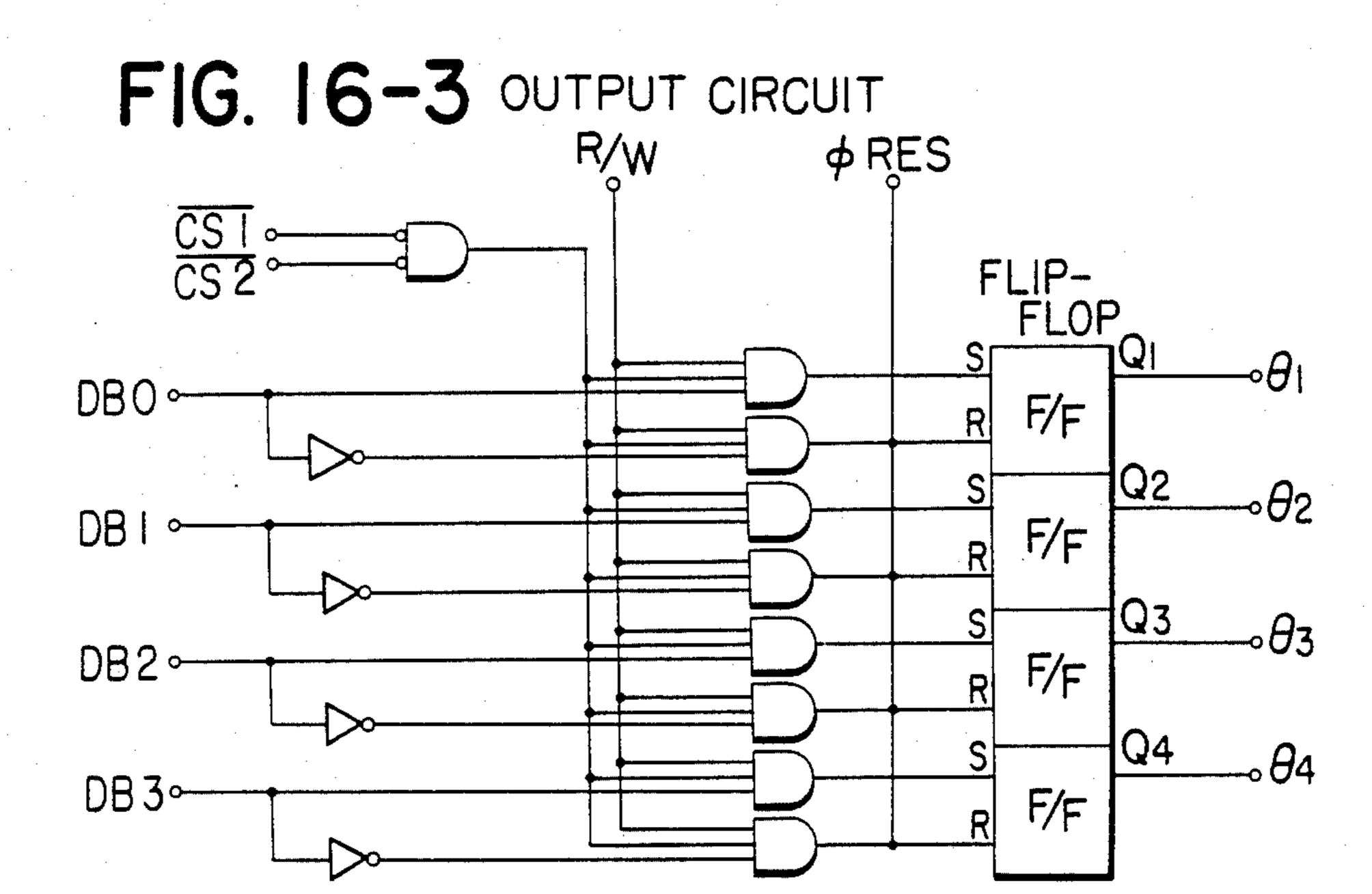
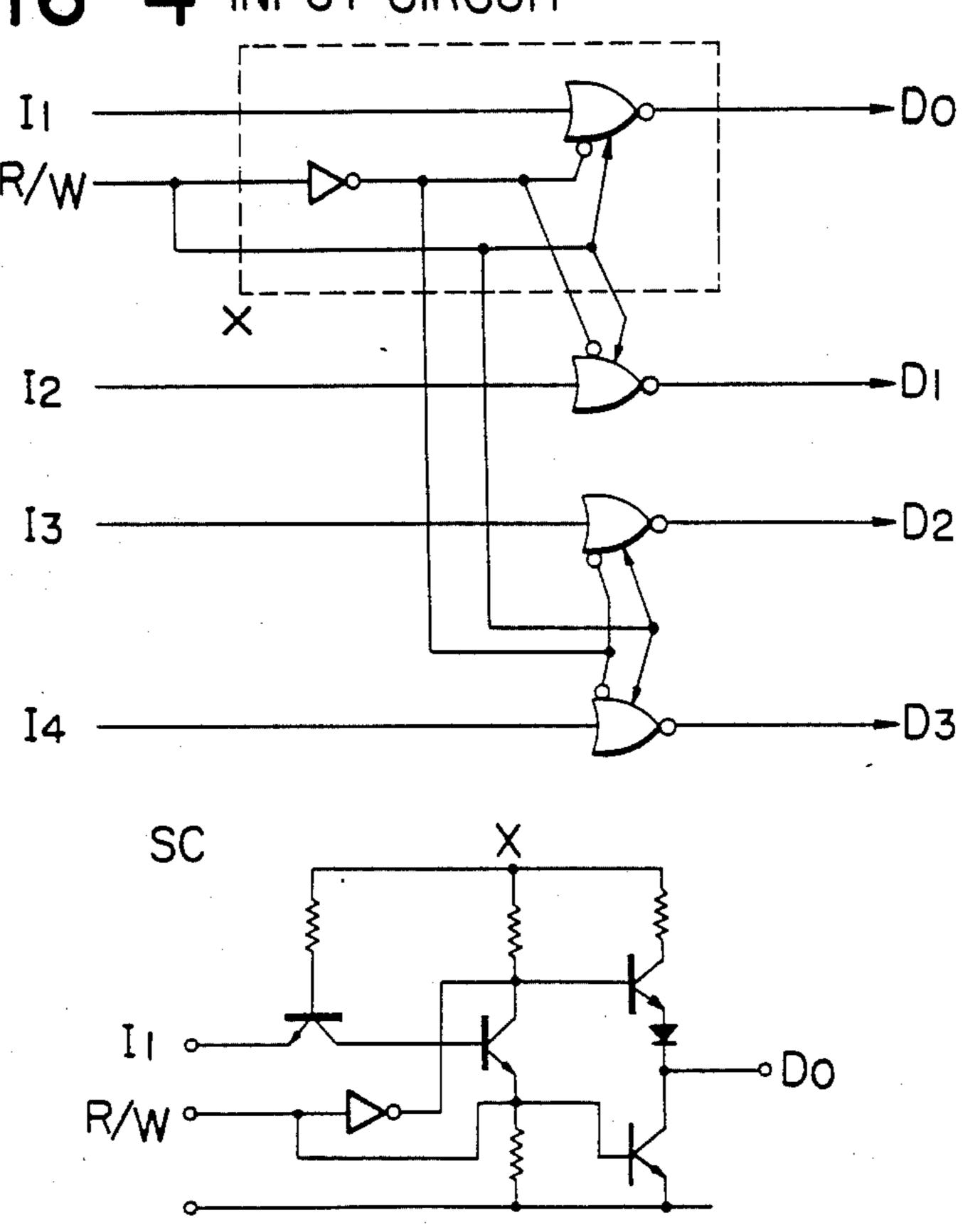
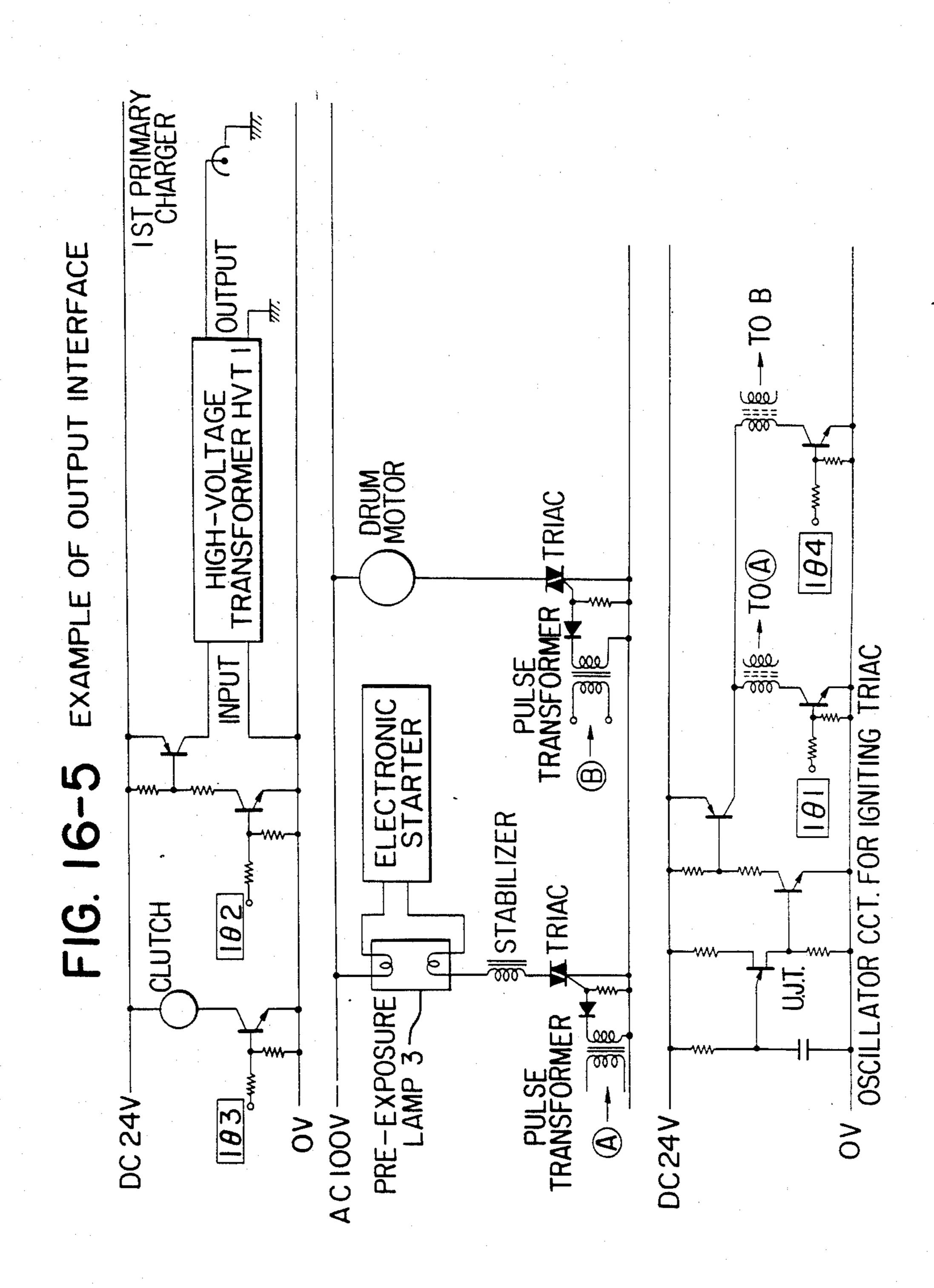
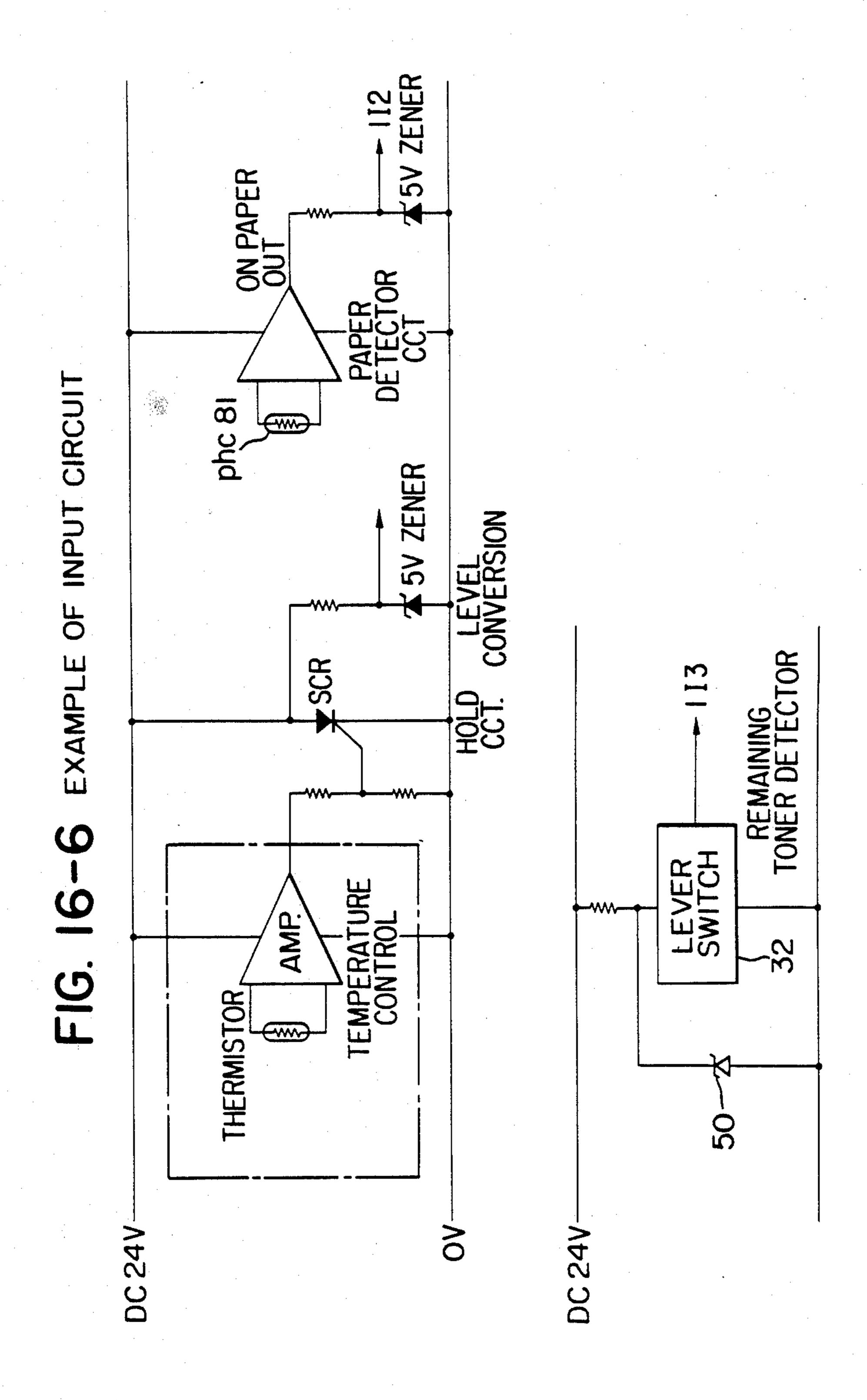
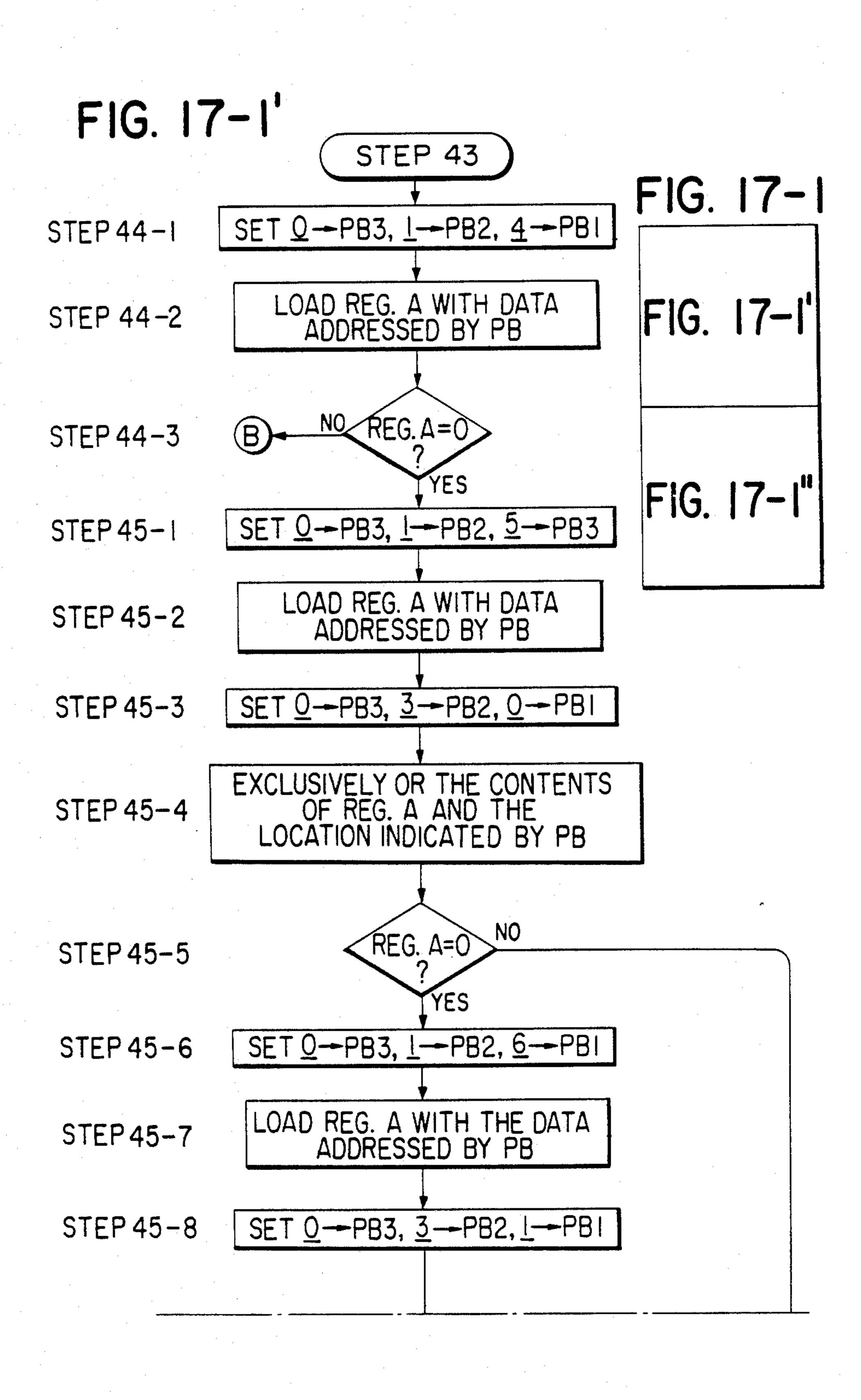


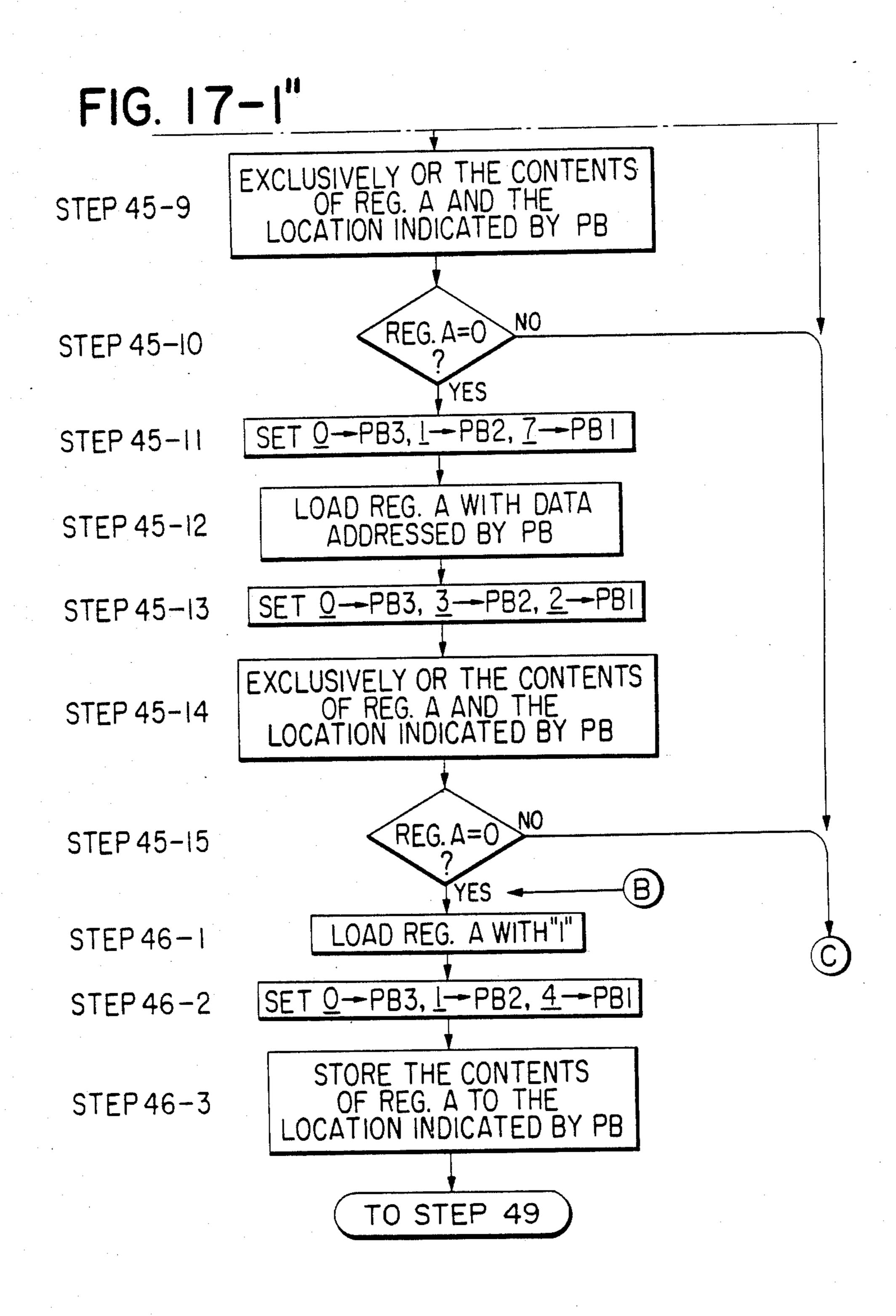
FIG. 16-4 INPUT CIRCUIT

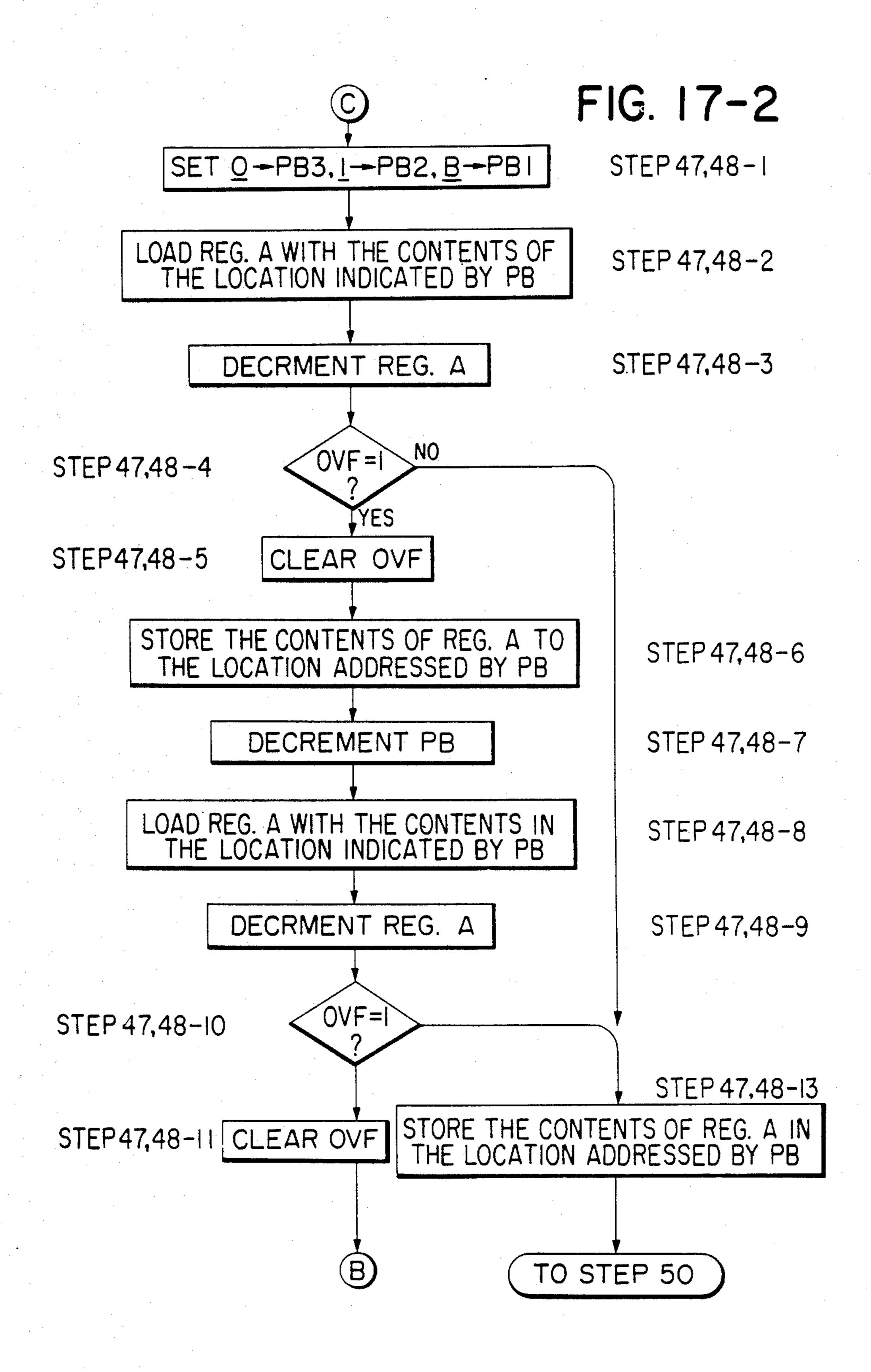


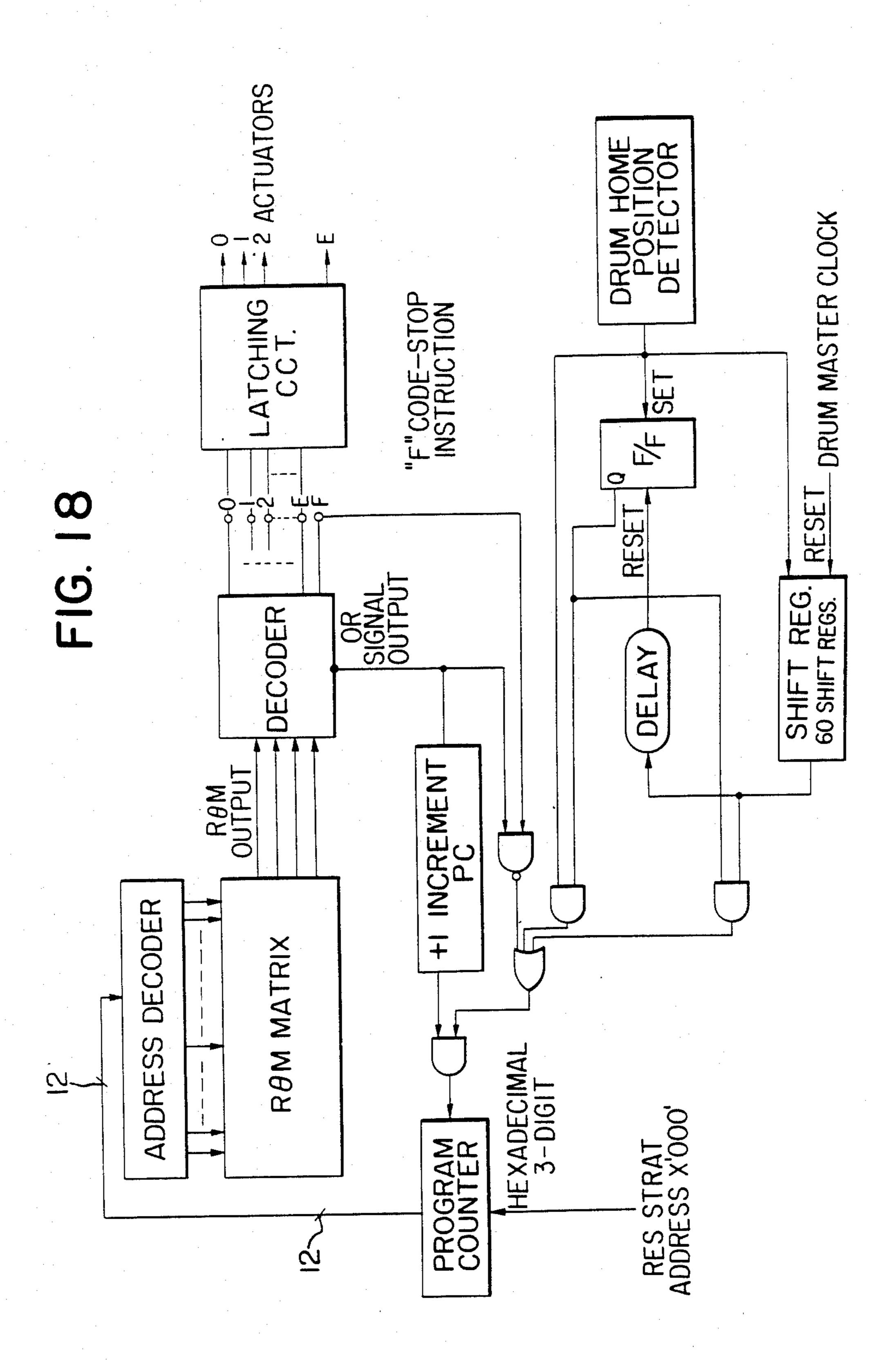


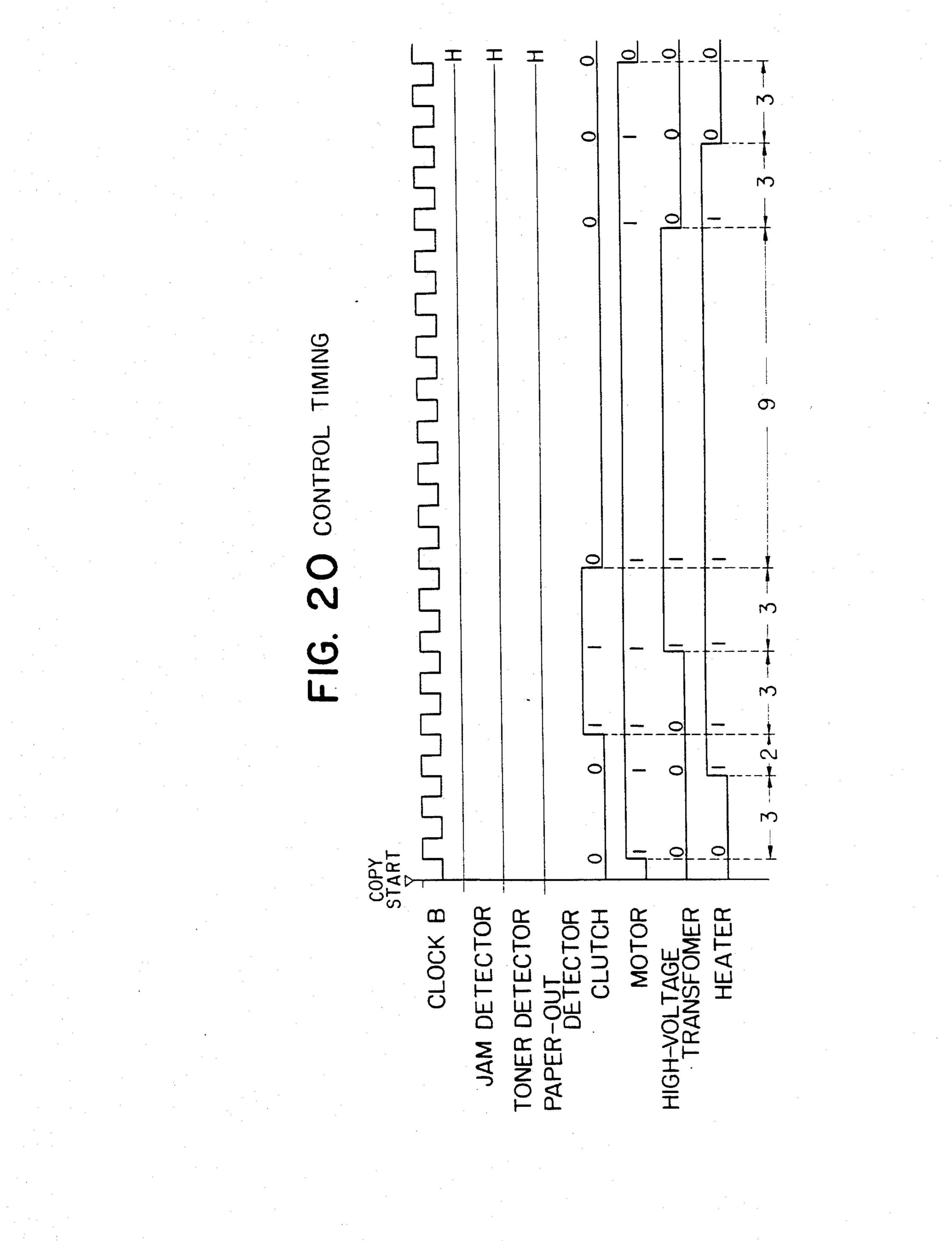


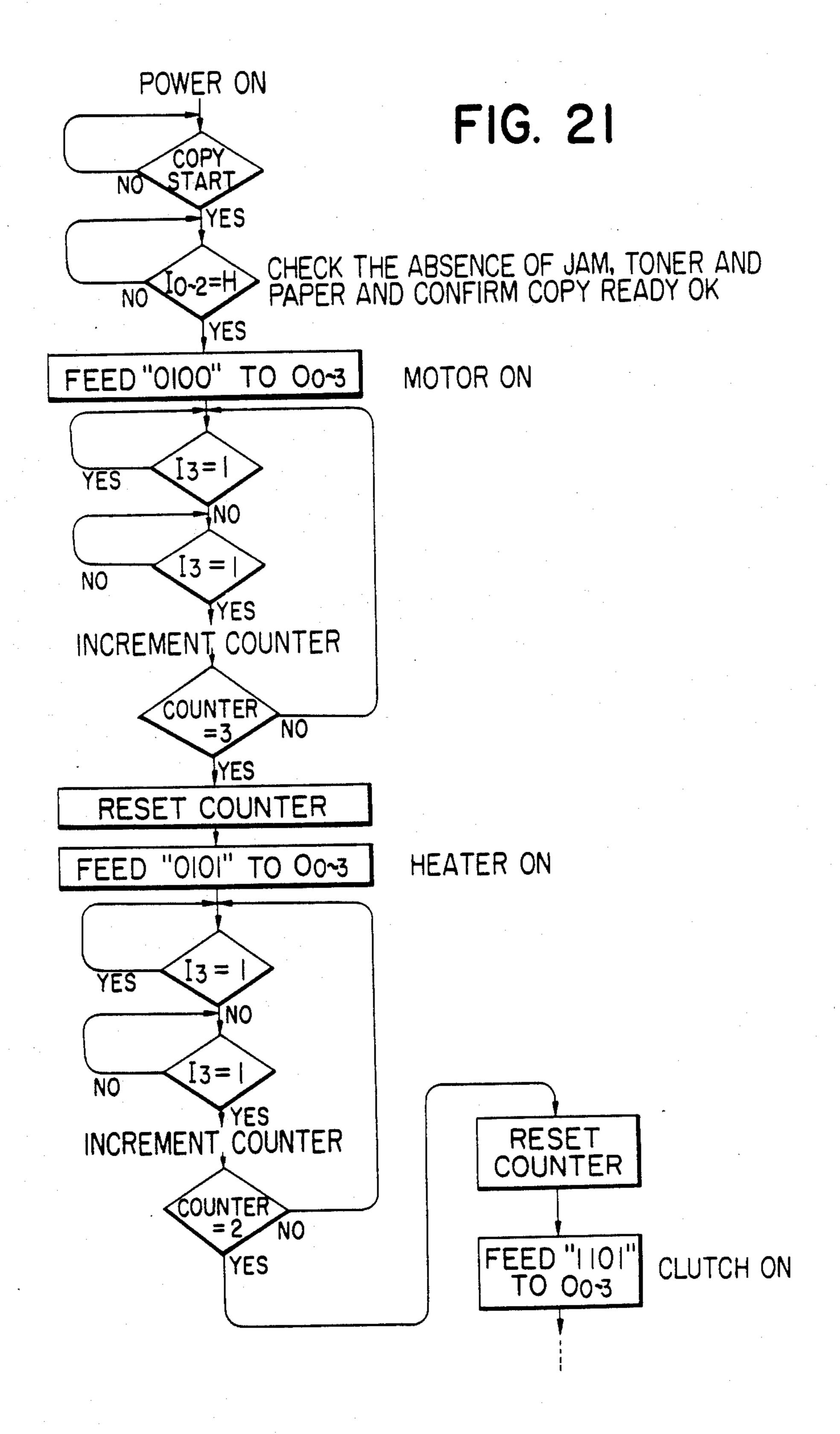












APPARATUS FOR CONTROLLING IMAGE FORMATION

This application is a continuation of U.S. application 5 Ser. No. 182,087, filed Aug. 28, 1980, now abandoned, which in turn is a division of U.S. application Ser. No. 964,023, filed Nov. 27, 1978, now U.S. Pat. No. 4,305,654, which in turn is a continuation of U.S. application Ser. No. 752,895, filed Dec. 21, 1976, now aban- 10 doned.

BACKGROUND OF THE INVENTION

1. Field of the Invention

The present invention relates to a copying machine 15 and recording equipment with a computer.

2. Description of the Prior Art

In an electrophotographic copying machine, a photosensitive drum has a photosensitive member consisting of an electrically conductive layer, a photoconductive 20 layer and an insulating layer, the photosensitive member being firmly supported on the peripheral surface of the drum. As the drum is rotated, its surface is uniformly pre-charged (with positive charges, for example) by a primary charger and is scanned with a light 25 image projected from an optical system which in turn is displaced together with or with respect to an original table. Concurrently the scanned surface is discharged by a re-charger with a DC of the polarity opposite to the polarity of the charges imparted by the primary 30 charger. Alternatively, the scanned surface may be discharged with AC. Thus an electrostatic latent image corresponding to the light image may be formed. The latent image is further illuminated or exposed with light so that a high-contrast electrostatic latent image may be 35 formed. Thereafter it is developed into a visible image by a developer with toner. The developed visible image is subjected to a corona discharge with the polarity opposite to the polarity imparted to the toner (for instance, the corona discharge being effected with the 40 negative polarity when the positive pre-charging has been employed) so that the visible image may be more easily transferred onto a copying sheet and then fixed by a heater. After the image transfer, the developing agent mainly consisting of colored particles which re- 45 mains on the surface of the photosensitive drum is removed and cleaned with a cleaning roller, whereas the remaining charges are removed by a lamp and a corona discharger so that the photosensitive member may be used again. A desired number of copies may be repro- 50 duced by cycling the above copying cycle.

In the copying machines of the type described above, a sequential control system has been used for controlling various processing means and especially chargers. In one system used are signals generated by switches 55 which in turn are opened and closed by cams supported on a photosensitive drum. More specifically, upon rotation of the drum, a cam causes a relay to close its terminals, thereby causing the displacement of the original table. When the next cam actuates another relay, a 60 copying sheet feed roller is actuated to feed a copying sheet and so on.

When this cam-and-relay control system is introduced into a retention copying machine or color copying machine, the number of cams and relays is tremen- 65 dously increased because in this machine processing steps are much greater in number than in the monochrome copying machine. As a result, the control sys-

tem becomes very complex in construction, the inspection and maintenance becomes very difficult, and the unreliable operation results because of the erratic operations of the switches and relays due to their chattering.

In order to overcome these problems, an electronic digital control system has been introduced in the copying machines so that a sequential control may be attained with logic circuits and arithmetic units. However, the greater the number of steps to be sequentially controlled the greater the number of logic circuits and arithmetic units becomes so that the control system becomes very complex in construction with a very complex wiring arrangement. In addition, these logic circuits and arithmetic units are fixed so that a sequence once set cannot be changed.

Furthermore in the prior art sequentially-controlled copying machines, the sequence is controlled in response to the counting of master clock pulses so that erratic operations tend to occur very frequently due to erratic counting.

SUMMARY OF THE INVENTION

One of the objects of the present invention is therefore to provide a printing or copying machine which may substantially overcome the above and other problems encountered in the prior art copying machines.

Another object of the present invention is to provide a printing or copying machine wherein a timewise programmed sequence of operations to be executed by various processing means alone or in combination is stored in a memory means and the printing or copying operations are sequentially controlled in accordance with this sequence, which may be easily modified as needs demand.

A further object of the present invention is to provide a printing or copying machine where a minimum number of parts including microswitches and leads is used due to the high integration of a control circuit including a computer and input and output circuits.

A further object of the present invention is to provide a printing or copying machine wherein read-only memory means and random access memory means are used to their full and utmost capacity so that any imaginable sequential controls of the copying machine may be accomplished in a very simple manner.

A further object of the present invention is to provide a printing or copying machine wherein erratic operations due to erratic counting of master clock pulses based upon which all operations are carried out, accumulation of errors and deviation in frequency of master clock pulses may be substantially eliminated.

A further object of the present invention is to provide a printing or copying machine wherein in order to prevent erratic operations due to erratic counting of master clock pulses they are started to be counted again from zero everytime when each or a predetermined number of steps have been executed.

A further object of the present invention is to provide a printing or copying machine wherein a computer and memory means are so arranged as to count master clock pulses in response to the variation in level thereof for sequentially controlling the operations or steps.

BRIEF DESCRIPTION OF THE DRAWING

FIGS. 1A and 1B, when combined as shown in FIG. 1, are sectional views of a retention copying machine in accordance with the present invention;

FIGS. 2A and 2B, when combined as shown in FIG. 2, are sequence time charts therefor;

FIGS. 3-1' and 3-1", when combined as shown in FIGS. 3-1, and 3-2 through 3-5 are block diagrams of a control circuit thereof;

FIGS. 4A and 4B, when combined as shown in FIG. 4, show a clock time chart used for the explanation of the access to address in a read-only memory ROM;

FIG. 5 is a circuit diagram of an input-output device; FIG. 6 is another circuit diagram of an input-output 10 device;

FIG. 7 shows a flowchart of a copying cycle to be executed by the control circuit shown in FIGS. 3-1', **3-1**" and **3-2** through **3-5**;

FIG. 8 shows a key entry flowchart associated with 15 one shown in FIG. 7;

FIGS. 9-1' through 9-1", 9-2' and 9-2", and 9-3' through 9-3", when combined as shown in FIGS. 901, 9-2 and 9-3, respectively, show detailed flowcharts of a sequential control;

FIG. 10 shows a detailed flowchart of STEPs 1 and 2 shown in FIG. 9-1',

FIG. 11 shows a detailed flowchart of STEP 6 shown in FIG. 9-1';

FIGS. 12A and 12B, when combined as shown in 25 FIG. 12, show detailed flowcharts of STEP 8 shown in FIG. 9-1' for execution of operations depending upon a number of copy clock pulses counted;

FIG. 13 shows a detailed flowchart of STEP 66 shown in FIG. 9 for stopping the copying cycle;

FIG. 14 is a circuit diagram of a controller;

FIGS. 15A through 15D, when combined as shown in FIG. 15, are detailed circuit diagrams of the control circuit shown in FIGS. 3-1', 3-1" and 3-2 through 3-5;

FIGS. 16-1 through 16-6 show a keyboard circuit, a 35 Keys. display circuit and a input-output circuit;

FIGS. 17-1' and 17-1", when combined as shown in FIG. 17-1, and FIG. 17-2 are detailed flow charts starting from STEP 44 to STEP 48 shown in FIG. 9-3' for executing various operations in response to the countup; 40 FIG. 18 is a circuit diagram of a ROM reading-out circuit;

FIG. 19 is a block diagram of a processor;

FIG. 20 shows a control timing; and

FIG. 21 is a flowchart thereof.

DESCRIPTION OF THE PREFERRED **EMBODIMENT**

The present invention will be described hereinafter as applied to a retention copying apparatus of the type 50 having a four-bit parallel-processing microcomputer for controlling the sequence of forming a secondary latent image from a primary latent image which in turn has been formed from an original to be copied, developing the secondary latent image with toner and transferring 55 a thus-formed toner image on a copy sheet, thereby providing a predetermined number of the same copies.

Referring first to FIGS. 1A and 1B and 2, the construction and copying process of a retention copying apparatus to which is applied the present invention will 60 be described. In FIGS. 1A and 1B, reference numberal 61 denotes a control board; 51, an original table; 52, an exposure lamp, 63, 54, 56, 57 and 58, reflecting mirrors; 55, lens system; 1, a photosensitive drum; 3, a pre-exposure lamp; 4, a primary charger; 6, a secondary dis- 65 charger; 7, an illumination lamp; 13, a modulation precharger; 11, a modulation charger; 8, an insulated drum; 24, a developer; 33, a copy sheet feeder; 34, a timing

roller; 36, a transfer charger; 73, a separating pawl; 70, 72, paper-out detectors; 45, a fixing roller; 47, a discharge tray; 31, a copy sheet; 14, a blower; and 18, a heater. The photosensitive drum 1 has a mesh-type photosensitive member consisting of a transparent insulating layer, a photoconductive layer and a conducting layer in the order named from the outer surface, the photosensitive drum 1 being described in detail in the specification of Laid Opened Japanese Patent Application No. Sho 50-19455. The primary charger is divided in time and space into two component parts.

Copying operation is carried out in response to commands or instructions which an operator enters on the control board 61 consisting of two displays 62 and 63, two pilot lamps 65 and 66 and a keyboard 64 including the following keys:

Key[O] or ORIGINAL Key:

This is the key for setting a number of electrostatic latent images to be formed on the drum 1. More specifi-20 cally, an operator depresses this key first and then enters a desired number of electrostatic latent images to be formed by depressing numeral keys (0)–(9). The present number is being displayed on the display 62.

 $\text{Key}[\infty]$ or Infinity Key:

When this key is depressed, the copying cycle is repeated infinitely and the pilot lamp 65 is turned on.

Key[R] or RETENTION Key:

This is the key for setting a desired number of copies to be reproduced from one electrostatic latent image. 30 The present number if displayed on the display 63 and the pilot lamp 66 is turned on.

Keys[CO] and [CR]:

These are the keys for correcting the inputs entered by the depression of ORIGINAL and RETENTION

Key[SING]:

This is the key for obtaining only one copy.

Key[MULT]:

This is the key for obtaining a plurality of copies. Key[START]:

This is the key for initiating the copying cycle. Key[STOP]:

This is the key for interrupting the copying operation. Next referring to the time chart shown in FIGS. 2A 45 and 2B, the copying steps will be described. First, a power switch is turned on and then heater 18 and a heater for the fixing roller are energized. A predetermined time after, the copying machine is set ready for copy reproduction. An operator enters ORIGINAL (1) or RETENTION (2) instruction on the control board 61, and then depresses SING or MULT key so that a drum motor M1 is driven. Concurrently, clutches in an optical system are so actuated that the first reflecting mirror 53 together with an original illumination lamp 52 and its reflector is displaced at a speed V1 in synchronism with a peripheral speed of the drum 1 so that the optical system is set in predetermined or home position and an exposure step is started as will be described below. While the original is being illuminated with the illumination lamp 52, the motor M1 rotates at V1 and then is de-energized concurrently when a motor M'1 is energized. Then both drums are immediately driven at a speed V2 almost twice as fast as V1. When the motor M1 is kept energized, the pre-exposure lamp 3 and the illumination lamp 7 are turned on for exposure, and a cooling fan is energized for preventing heat from the illumination lamp 52 from remaining in the optical system. Thereafter the primary charger 4 and the secondary discharger 6 are actuated to form a primary latent image on the screen in the manner described above.

Upon depresseion of SING or MULT key, a toner image transfer charger 36, a copy sheet separating charger 37, an insulated drum discharger 50 and a copyingsheet-separation function fan are energized and are deenergized after the copying operation has been completed. Since the rotational speed of the insulated drum is slow, the chargers 36 and 37 and the discharger 50 have low potentials so that no excess charge remains on 10 the drum.

Next the drum motor is de-energized after a primary latent image has been formed, and the insulated drum motor is energized. Then the steps of modulation, developing, transfer and separation are effected sequen- 15 tially in the order named. After the modulation step, for the first copy the screen drum makes three rotations and then stops. Thereafter, one copy is reproduced for every one rotation of the screen drum.

Concurrently when the insulated drum motor M'1 is 20 energized, a feed roller clutch is turned on which transmits the force of a cleaning motor to pre-modulation charger 13 and a belt 38 (See FIG. 1). When the screen drum is rotated through 228° from its home position, the modulation charger 11 is turned on for transferring an 25 electrostatic latent image formed on the screen drum on the insulated drum. Simultaneously, a feed roller clutch CL3 is turned on for feeding one copy sheet upon a feed table at 241°. After the initiation of the modulation step of the screen drum, a second rotation cycle is started, 30 and the feed-roller clutch CL3 is turned off at the home position, and a timing roller clutch CL4 for registering the leading edge of the copying sheet with the leading edge of the toner image developed on the insulated drum is turned on at 160° after a developing motor has 35 rotated through 40°. If only one copy is to be reproduced, the modulation charger 11 is turned off at 228°, but in the present embodiment two copies are to be reproduced so that it is not turned off. At 241°, a feed roller clutch CL3 is turned on for feeding a second copy 40 sheet, and at 360° the timing roller clutch CL4 is turned off. Since a third rotation cycle is initiated, a timingroller clutch for a first copy is turned off. At 100° the timing roller is applied with brake, and at 160° the timing-roller clutch CL4 is turned on for a second copy 45 sheet. At 228°, the modulation charger 11 is turned off. If only one copy is to be reproduced, the developing motor M2 and a toner-bridge-preventive motor are turned off at 50°. At 360° the timing roller clutch is turned off. When two copies are to be reproduced, the 50 developing motor M2 and the toner-bridging-preventive motor are turned off at 50° in a fourth rotation cycle, and at 33° the insulated drum motor M'1 and the feed-roller clutch are turned off. Thus, two-sheet retention cycle is completed.

A separation-pawl solenoid SL1 is energized between 276° and 316° in a cycle succeeding the second cycle for separating a copying sheet from the insulated drum.

In FIGS. 3-1', 3-1" and 3-2 through 3-5 there is shown various processing means in the copying machine in order to accomplish the copying process in the sequence described above. A read-only memory ROM, which is shown in detail in FIG. 3-2 and FIGS. 15A and 15B, stores in respective addresses thereof a pro- 65 grammed sequence of operations to be executed by a computer CPU and a programmed output data so that the copying operation may be accomplished in a desired

sequence, the data stored in an accessed address being read out and transferred as will be described hereinafter. ROM includes a conventional matrix circuit with a plurality of addresses each storing a binary-coded-eightbit control instruction (for controlling not only processing means but also other circuits as will be described below).

Input devices I-1 and I-2, which are shown in detail in FIG. 3-5 and in more detail in FIG. 15D, store data concerning the copying operation being carried out. Output devices O-1 through O-4, which are shown in detail in FIG. 3-4 and in more detail in FIGS. 15C, 15D and 21, give control signals for controlling the processing means. A random access memory RAM, which is shown in detail in FIG. 3-3 and in more detail in FIG. 15C is of the conventional type wherein stored in each address are a set of binary codes representative of a preset, desired number of copies, a number of copies reproduced or stop instruction. RAM consists of a plurality of flip-flop pairs which are specified in response to an addressing signal so that required data may be stored or read out.

The computer CPU is of the conventional type including at least more than two addressing registers PB and PC for access to the above-mentioned memories, input and output devices, at least one storage registers A, B, C and D and a controller or control unit CT having a plurality of logic circuits for decoding and processing data transmitted through a data code bus. To this end, the computer CPU is interconnected with the memories and input and output devices through a plurality of data transmission lines.

Next referring particularly to FIG. 19, the mode of operation of the computer CPU will be described briefly. CPU selects an address in ROM and the data stored in this address are transmitted into CPU through a data signal transmission line 86. The data are decoded within CPU when a copying process in a predetermined sequence has already been initiated, the process being started from the first step of turning on the main switch, or the data are stored in a specified address in RAM. Furthermore the data in a specified address in RAM are transferred into the computer CPU or the data are transferred from the computer CPU through an output signal line 88 to the input and output devices or vice versa through an input signal transmission line 89. Thus the copying sequence may be controlled:

More specifically, the whole control system for the copying apparatus may be established by connecting the processing means through input and output signal leads and an interface circuit (see FIGS. 5 and 6) to the input and output device I/O and connecting through input signal leads various detectors for monitoring desired operating conditions of processing means to the 55 input and output device I/O through interface circuit (which may be eliminated in some cases). The output signal lead Oo is connected through an interface to a clutch or clutches for controlling the reciprocal movement of the optical system; O1, through an interface to a block diagram of a control circuit for controlling 60 the motors for driving the drum and actuating the clutch; O2, through an interface to a high-voltage transformer for effecting corona discharge simultanneous with the exposure step; and O3, through an interface to the fixing heater. The input signal line Io is connected to a jam detector; I1, to a toner detector; I2, a paper-out detector; and I3, a master clock pulse generator for generating master clock pulses B, all though interface circuits. The interfaces however may be eliminated when the outputs transmitted through these input signal lines I have a level acceptable to the input-output device I/O. The clock pulses B have a frequency in proportion to a speed of the photosensitive drum or belt and are used for controlling all sequences of the copying apparatus.

FIG. 20 shows a control timing of the clutch, motor, high-voltage transformer, heaters and so on, and FIG. 21 shows a sequence of operations to be carried out in response to the outputs from the detectors, a high out- 10 put level=OK and a low output level=Not Good.

In response to START instruction, CPU transfers the contents in Io-I3 of the input-output device I/O into CPU according the programmed sequence stored in ROM or RAM, and determines whether Io-I2 are at 15 high level or not. If they are at low level or Not Good, the operation is suspended until they rise to a high level. When they rise to a high level, I3 or master pulses B rise to H level and a counter in CPU starts counting, the content of the counter being transferred to and stored in 20 RAM. Concurrently, CPU transmits the control signals 0, 1, 0 and 0 on the output signal lines Oo, O1, O2 and O3, respectively, to latch. Then the motor is driven. When the counter in CPU has counted three master pulses B, the control signals on the output-signal leads 25 Oo, O1, O2 and O3 change to 0, 1, 0 and 1, respectively, to latch and turn on the heaters. In this manner, a basic timing chart shown in FIG. 20 is obtained.

Next referring to FIGS. 3-1', 3-1", 3-2 through 3-5 and FIGS. 4A and 4B, the basic timing for processing a 30 sequence program will be described in detail. Respective steps of the programme are stored in the form of codes in 8 lines in ROM, and each code is addressed by an address decoder which selects one of 2n lines in response to n codes transmitted through an address 35 code bus. Addresses where instructions are stored in ROM and RCM are addressed by ROM addressing registers PC. Each addressing register PC shifts one position in response to a control signal al so that instructions are successively read out and transferred through 40 multiplexer A, B and C into ROM at a predetermined time.

Since the data code bus 86 consists of 4 lines, an instruction data from ROM which appears on 8 lines must be transmitted in a time division manner in two steps 45 through four lines to the data code bus; that is, four bits being simultaneously transmitted in each step. The instruction codes are latched into the registers C and D through switches SW9, SW6 and SW7 which are opened and closed in response to the control signals α 50 which are generated every two or three clock pulses. The instruction codes are decoded by an instruction decoder to generate the control signal α for controlling the sequence in response to the given instruction. In summary, within four basic pulse cycle, a location 55 where a programme is stored is addressed, and the addressed instruction code is decoded. Within a next six pulse cycle, the decoded instruction is executed. In like manner, the next programme is addressed and decoded and executed. This means that the execution of each 60 step of one programmed sequence requires 10 basic pulses, For instance, the execution of two-word instruction takes 20 clock or basic pulses.

The registers A and B execute arithmetic operations, and each switch SW consists of a gate circuit which is 65 controlled in response to the control signal α . An overflow register OVF checks an overflow of the register A. The control unit CT decodes the contents in the

registers C and D, executes the arithmetic operation of the contents stored in the registers A and B and generates the control signal α as will be described in detail hereinafter with reference to FIG. 14.

In the input-output device I/O, the following one-to-one correspondence is established:

	latches	nrocecina meanc
	or flip-flops	processing means
Output	1 <i>0</i> 1	pre-exposure lamp
Device	$1\theta 2$	primary charger, first
(1)	1 <i>0</i> 3	clutch for permitting the going
		stroke of the optical system
	1 <i>0</i> 4	drum motor (first speed)
Output	$2\theta 1$	primary charger, second
Device	$2\theta 2$	original illumination lamp
(2)	2 0 3	secondary discharger
	$2\theta 4$	clutch for permitting the return
		stroke of the optical system
Output	3 <i>0</i> 1	latent image transfer charger
Device	$3\theta 2$	developing motor
(3)	$3\theta 3$	drum motor (second speed)
` '	$3\theta 4$	screen biase charger
Output	4θ 1	feed-roller clutch (for copying
Device		sheet)
(4)	$4\theta 2$	timing-roller clutch
` '	$4\theta 3$	copying-sheet separating solenoid
	4 θ 4	timing-roller brake
Input	111	output from a flip-flop represen-
Device		tative of a stop key being depressed
(1)	112	output from paper-out detector
(-/	113	output from toner detector rep-
		resenting the remaining quantity
		of toner
	114	output from a sensor for detecting
		the temperature of the fixing heater
Input	211	output from a sensor representing
Device	211	the screen drum home position
(2)	212	output from a sensor representing
(2)	212	the optical system in home position
	ź 1 3	clock pulse 1 representative of
	213	a first speed of the drum motor,
		which is 120 mm/sec.
	214	clock pulse 2 representative of
	21 ***	•
		a second speed of the drum motor, which is 360 mm/sec.
		which is joy him/sec.

The input-output devices I/O are shown in detail in FIGS. 5 and 6, the device shown in FIG. 5 having four-bit output lines whereas the device shown in FIG. 6 having more than four output lines.

The copying apparatus incorporates two oscillators such as a stable vibrators, multistable-vibrators or the like for generating one pulse for every rotation of the screen drum through 1°. In the present embodiment, the screen drum has a diameter of 110 mm so that the first clock pulses 1 have a period of about 8 msec whereas the second clock pulses, a period of about 2.66 msec. These clock pulses may be generated by the optical detection (a lamp and photosensitive device 84) through holes 60 of a disk 56 which is rotating at a speed a few times as fast as the insulated drum.

The condition signals; that is, the signals representative of operating conditions of processing means represent "none or NG" when they are at "1" level while they represent "yes or Good" when at "0" level.

Next referring to a flowchart shown in FIG. 7, the copying sequence will be described. With the power ON or main switch turned on, the copying apparatus is set into a key-entry-ready state. An operator enters a desired number of copies in the manner described previously, and then depresses a START key so that the copying cycle is initiated. Each time when one copying cycle has been accomplished, it is detected whether or

not the copying apparatus is in a stop or finish mode (that is, a desired number of copies have already reproduced; toner and/or copying sheet are exhausted). If not set into the stop or finish mode, the copying cycle is repeated, but if set into the stop or finish mode, the 5 copying cycle is interrupted and the copying apparatus is reset to the key-entry-ready mode. The present invention therefore has the feature that since the steps of the copying process are sequentially controlled, the entry of a desired number of copies and the depression of the 10 START key may be prohibited during the copying cycle and the copying cycle will not be initiated until a required key entry has been completed.

Key Entry Cycle:

As described previously, key entry is made with the 15 numeral keys from 0 to 9 for setting a desired number of copies, the MULT key for starting the copying operation or SING key for obtaining only one copy, the STOP key for stopping the copying operation and CLEAR key for clearing erroneously entered data as 20 will be described in detail with particular reference to FIG. 8.

With the numeral keys, an operator can set any number of two digits of copies; that is, up to 99. The first digit is stored in RAM location 1, and the second digit, 25 in location 2. In STEP 0-1 after the power has been turned on, data stored in RAM locations 1 and 2 are displayed on the display, and STEP 0-2 is a decision box to check whether a key is depressed or not. STEP 0-3 is also a decision box to check whether or not the de- 30 pressed key is a numeral key and if so STEP 0-4 and STEP 0-5 are executed so that the entered integer is stored in RAM location 1 and the control loops back to STEP 0-1. The stored integer is displayed. If in STEP 0-3 a key other than the numeral keys is depressed, the 35 control advances to STEP 0-6. When CLEAR key is depressed, RAM is cleared in STEP 0-7 and the control loops back to STEP 0-1, the display device displaying "00". If MULT key is depressed, the control advances to the copying cycle. If SING key is depressed, the 40 integer "1" is stored in RAM location 3 in STEP 0-9 and the control advances to the copying cycle. That is, the information stored in the locations 3 decides the finish mode or not. More specifically, when "0" is stored in location 3, the control advances to the copying 45 cycle, whereas if "1" is stored, the control advances to the finish or halt mode. This decision is made everytime when one copying cycle has been completed (See also FIGS. 9-1' through 9-3'''.

Copying Cycle:

In FIGS. 9-1 through 9-3" there is shown a flow-chart of the copying cycle. In STEP 1 whether copying sheets and toner are present or not and whether the fixing heater has been raised to a predetermined temperature or not are checked. If the answer is NO, the control halts until these conditions are met. If the answer is OK, the control advances to STEP 2 so that the drum motor (V1) is driven at a first speed. STEP 1 and STEP 2 will be described in more detail hereinafter with particular reference to FIG. 10.

In STEP 3 whether or not the optical system is in its home position is checked. If the answer is NO, the forward or going-stroke clutch is actuated to cause the optical system to be displaced to the left in FIGS. 1A and 1B by the drum motor toward the home position. 65 After the optical system has reached the home position, the clutch is turned off in STEP 5, whereby the system is stopped. In STEP 6 it is checked whether or not the

screen drum which has been already drivingly coupled to the drum motor and is rotating in synchronism therewith is in its home position. If the answer is NO, the control halts until the screen drum is brought to its home position as will be described in detail hereinafter with particular reference to FIG. 11. If the answer is YES, the control advances to STEP 7 for reproducing a copy because the optical system has been already brought to its home position.

In STEP 7, the pre-exposure lamp, first primary charger and exposure lamp are turned ON. The drum motor has been already rotating. Since in STEP 72, the drum motor which has been rotating at a second speed is turned off and the control loops back to STEP 7, it must be driven again at a first speed. In the present embodiment, with one latent image 10 copies may be reproduced so that six latent images must be formed to reproduce 55 copies so that a repetitive number must be stored in RAM location 4 in STEP 7.

In STEP 8, the counter counts a number of clock pulses each generated everytime when the screen drum which is running at a first speed rotates through a unit of degrees (1°), and when it counts 60 pulses (that is when the screen drum is rotated through 60° from its reference or home position), the second primary charger is turned ON.

When CP1=105 in STEP 10, the control advances to STEP 11 where the secondary discharger is turned ON. When CP1=12 in STEP 12, the control advances to STEP 13 where the forward or going-stroke clutch is actuated to cause the optical system to be displaced to the right in FIGS. 1A and 1B.

In STEP 14, the control waits for the screen drum returning its home position.

If the frequency of the clock pulses 1 should not be in synchronism with the rotation of the screen drum or the miscounting of the clock pulses should occur during the time frame between STEP 7 and STEP 14, an error caused during one rotation of the screen drum would be accumulated with the resultant adverse effect on the sequence control. This problem may be solved by resetting in STEP 14. To the same end, STEPS 35, 57 and 67 are provided.

STEPS 15-23 are provided based upon the same principle described above and are apparent from the explanation in the boxes shown in FIGS. 9-1' through 9-3''' so that no further description shall be made in this specification. Briefly stated, the underlying principle of the sequence control in accordance with the present invention is that the time when the control advances to the next step is stored in ROM in terms of an angle of rotation of the screen drum (that is, a number of pulses) and when a predetermined number of pulses has been counted, a predetermined processing means is turned on or off.

In STEP 24, an electrostatic latent image has been already formed on the screen drum and is to be transferred onto the insulated drum. Therefore the drum motor is switched over to a second speed from a first speed so that the counter starts counting clock pulses 2 each of which is generated every rotation of the screen drum through 1° as described elsewhere.

STEPS 24-42 are explained in the flowchart. In STEP 43 the number of reproduced copies is increased by one, and in STEP 44 it is checked whether STOP instruction is received or not. If YES, "1" is stored in location 3 in RAM, thus indicating the finish mode. In STEP 45 it is checked whether or not the desired num-

ber of copies set in the key-entry cycle in the manner described above is coincident with a number of copies reproduced. If YES, "1" is stored in Location 3, RAM in STEP 46.

In STEP 47, the content in RAM Location 4 is reduced by 1, and in STEP 48 it is checked whether or not the content in RAM Location 4 is zero. If YES the control jumps back to STEP 46 to store "1" into RAM Location 3. If the content in RAM Location 3 is "1", the control advances to STEP 49 wherein the screen bias and latent-image-transfer charger are turned off. In like manner, in STEPS 51, 60 and 66 it is checked whether or not the condition is in the finish mode. If YES, the feed roller remains turned off in STEP 51, the developer is turned off in STEP 60, and the control halts until the screen drum is returned to its home position. In STEP 66 if RAM 3=1, the control loops back to STEP 40 as will be described with reference to FIG.

10 When a jump con are first transferr then into PC2 and tion is met, no jump register A is zero tion; 1010, a jump and 1100, a jump and 1100, a jump and 1100, a jump register is not 0.

Within a frame or address in RO the data-code but SW6 and SW9 verification.

In STEP 68 it is checked whether the finish modes 20 have reached a predetermined repetitive number, whether STOP instruction has been received or not and whether the number of copies reproduced has reached the preset desired number of copies. If YES, the control advances to STEP 71 where the control halts until the 25 screen drum is returned to its home position. When the screen drum has returned to its home position, the control advances to STEP 72 to cause the drum motor to turn off. After one copying cycle has been accomplished in this manner, the control jumps back to STEP 30 7 so that another copying cycle may be started. On the other hand, when RAM4=0 in STEP 68, the control advances to STEP 69 and when CP2 has counted 330th pulse, the drum motor is turned off. Thus, the whole copying operation has been accomplished and the con- 35 trol loops back to the key-entry cycle where the copying apparatus is ready to receive the next instruction.

According to the present invention, the whole operation is completed when the CP2 counts 330 pulses; that is, when the screen drum must rotate further through 40 30° before it reaches its home position, so that the screen drum is prevented from moving beyond its home position. Therefore in STEP 6 it is immediately checked that the screen drum is in its home position because no further rotation thereof to its home position is required. 45

Next programme instructions will be described for executing the above steps with the use of a microcomputer μ COM4, a product of NICHIDEN KK

1.0100	X1X2X3X4	Address Instruction
Y1Y2Y3Y4	Z1Z2Z3Z4	

X1-4 are shifted to PB3, Y1-4, to PB2 and Z1-4 to PB1. During the execution of a programme, PC specifies a 55 location in ROM. Then the integer "3" or binary code "0100" appears or is called on the data-code bus at T1 and is latched to the register C through SW6 and SW9 which are actuated at T2. The code is interpreted at T2 as the address instruction and concurrently X1-4 are 60 transmitted on the bus at T2 and are latched to the register PB3 through SW9 and SW15 which are actuated at T3. Thereafter PC is increased by "1" and the codes Y1-4 and Z1-4 are transmitted and stored in PB2 and PB1, respectively. Thus a new address to be used in 65 a programming to follow is stored in the register PB with an execution timing which is slightly different from that shown in FIGS. 4A and 4B.

······································	· · · · · · · · · · · · · · · · · · ·	
2. 0 1 0 1	X1X2X3X4	Jump Instruction
Y1Y2Y3Y4	Z1Z2Z3Z4	
		<u> </u>

When a jump condition for X is attained, Y1-4 and Z1-4 are first transferred into PB2 and PB1, respectively, and then into PC2 and PC1, respectively. If no jump condition is met, no jump is made.

X1-4=0010 is a jump instruction when an overflow is 1; 0101, a jump instruction when the content in the register A is zero; 1000 is a nonconditional jump instruction; 1010, a jump instruction when an overflow is zero; and 1100, a jump instruction when the content in the register is not 0.

Within a frame time T1+T2, PC specifies a location or address in ROM, and at T1 the code 0101 appears on the data-code bus and is latched to register C through SW6 and SW9 which are actuated at T2 simultaneous with the appearance of X1-4 on the bus. At T3 X1-4 is latched to the register D through SW7 and SW9 which are actuated at T3. If X1-4=0100, at T4 the codes "0101" and "0100" are interpreted as a jump instruction as well as an instruction for checking the contents of the register A. That is, within a time frame T5-T10, it is checked whether the content in the register A is zero or not. If not zero, PC is increased by 2 and thus the jump instruction has been executed. If zero, PC is increased by 1 the codes Y1-4 and Z1-4 are transferred into PB2 and PB1, respectively, and then into PC2 and PC1, respectively. Thus the address to which data are jumped is stored in PC, and within a next time frame of T1-T10 a new address to be jumped is specified in ROM. Thus the jump instruction has been executed.

3. 0 1 1 0	1000	Shift Instruction (1)
		

In response to this instruction, data in the address specified by PB is loaded into the register A. That is, within a time frame of T1+T2 an address in ROM is accessed by PC, and at T1 the code 0110 appears on the datacode bus. At T2 it is latched to the register C through SW6 and SW9. At T2 1000 appears on the bus and at T3 is latched to the register D through SW7 and SW9. At T4 the codes stored in the registers C and D are interpreted and within a time frame of T5-T10 the code in PB appears on an addressing-code bus so that the data specified by this addressing-code in RAM, output device or key register in a key display input-output device appears on the data-code bus and is stored in the register A through SW9 and SW2.

Other Instructions are Summarized Below:

_				· - · - · · · · · · · · · · · · · · · ·
_	Register C		Register D	Explanations
_	4.	0111	X1X2X3X4	Load X1-4 into register A
	5.	1000	1000	Store the content in the Register A into an address or location specified by PB.
	6.	1001	1100	Execute EXCLUSIVE OR with data in the register A and the data in the address specified by PB.
	7.	1110	0001	Transfer the content in PB into PC.
	8.	1110	0010	Transfer the content in PC into PB.
	9.	1110	0011	Exchange the contents between PC and PB.
	10.	1110	0100	Increment PB by 1.
	11.	1110	0101	Decrement PB by 1.
	12.	1110	1000	Transfer the content in the register A into PB1.

-continued

		-commuca -
Register C	Register D	Explanations
13. 1110	1001	Transfer the content in the register A into PB2.
14. 1110	1010	Transfer the content in the register A into PB3.
15. 1110	1011	Transfer the content in the register A into the register B.
16. 1110	1100	Transfer the content in the PB1 into the register A.
17. 1110	1101	Transfer the content in the PB2 into the register A.
18. 1110	1110	Transfer the content in PB3 into the register A.
19. 1110	1111	Transfer the content in the register B into the register A.
20. 1111	0000	clear both the register A. and OVF.
21. 1111	0001	Clear OVF.
22. 1111	0010	Clear the register A.
23. 1111	0110	Clear register A and shift
		OVF to the left OVF \rightarrow A, A3 \rightarrow OVF
24. 1111	0111	Clear the register A and shift OVF to the left, $A1 \rightarrow OVF$, $OVF \rightarrow A3$.
25. 1111	1010	Increment the register A by 1.
26. 1111	1011	Decrement by 1 the register A.

With the above-mentioned instruction codes, the 25 sequential copying operation is executed, and in addition the following codes are used where X=codes are not limited:

.1	PC3(PB3)	PC2(PB2)	PC1(PB1)
ROM	0000	X	X for accessing an address in ROM
RAM	0001	X	X for accessing an address in RAM
OUTPUT	0010	X	X
DEVICE(1)			
OUTPUT	0011	· X	X
DEVICE(2)			
OUTPUT	0100	X	X
DEVICE(3)			
OUTPUT	0101	X	X
DEVICE(4)			
INPUT	0110	X	X
DEVICE(1)			- ·
INPUT	0111	X	X
DEVICE(2)			

Of 12 conductors or lines of the addressing-code bus, the upper four digit lines are used for selecting storages, and each of memories or storages and the input-output device are provided with a conventional circuit for interpreting or decoding the transmitted codes. The 50 remaining 8 lines are used to specify an address in each storage, which is provided with a conventional decoding circuit. Since the input-output device has four lines each corresponding to each digit of a four-bit code, no special circuit is needed.

Next referring to FIG. 10 steps 1 and 2 in the flow-chart shown in FIG. 9-1' will be described. In STEP 1-1 which follows STEP 0 for key entry, the address (0 1 1 0) of the input device (1) is stored in the register PB3, and in STEP 1-2, the data in the input device (1) specified by the register PB3 is transferred into the register A. Within a time frame of STEPS 1-3, it is checked whether the content in the register A is 0 or not. If no, the address (0110) of the input device (1) is again stored in PB3, and the data transfer and comparison follow in 65 the manner described above. When the content in the register A is 0; that is, when the copying sheets and toner are present, the control advances to STEP 2. In

STEP 2-1, the address (0010) of the output device (1) is stored in the register PB3, and in STEPS 2-2 the code (0001) is entered sequentially from the least-significant digit into the register A. In STEP 2-3, the content in the register A is transferred into the output device (1) specified by the register PB3 so that the drum motor (V1) whose latch 104 corresponds to the code (0001) in the output device (1).

With further reference to FIGS. 3-1 through 3-5, the above procedure will be described in more detail. First, based on TABLE 2 the operations to be executed in STEPS 1 and 2 are stored in the addresses 1-8 in ROM as follows:

13				
	STEP	Address in ROM	•	ROM codes
	1-1	0000 0000 0000	0100 0110	address code of input device
20		0000 0000 0001	0000 0000	
20	1-2	0000 0000 0010	0110 1000	
	1-3	. 0000 0000 0011	0101 1100	jump condition, Register $A = O$
		0000 0000 0100	0000 0000	address to be jumped in RCM
25	2-1	0000 0000 0101	0100 0010	address code of output device (1)
		0000 0000 0110	0000 0000	
	2-2	0000 0000 0111	0111 1000	transfer code to Register A
	2-3	0000 0000 1000		

Next the sequence from the time when the data in the address 0 in ROM is read out to the time when the motor V1 is driven will be described with further reference to FIGS. 3-1' through 3-5 and FIGS. 4A and 4B.

When the power is ON, the register PC is cleared so that within a time frame of T1-T2 the contents; that is, the codes 0000, 0000 0000 appear on the code bus consisting of 12 conductors and the address 0 in ROM is specified. Therefore at T1, the upper code (0100) in the address 0 appears on four-line data-code bus and is latched to the register C through SW9 and SW6 at T2. It is immediately decoded by the decoder CT and the control signal α is generated for storing into the registers PB3, PB2 and PB1 the codes which successively appear on the data-code bus. At T2, the lower code (0110) in the address 0 in ROM appears on the bus and is latched to PB3 through SW9 and SW15. Thereafter the register PC is increased by 1, and the upper code (0000) and the lower code (0000) in the address 1 in ROM sequentially appear on the bus and are latched into PB2 and PB1, respectively, in response to the control signal α through SW9 and SW11 until T10.

At the next T1, the register PC is increased by 1 to specify the address 2 in ROM so that the upper code (0110) appears on the bus and is latched into the register C at T2. The lower code (1000) appears on the bus at T2 and is latched into the register D at T3. These codes are decoded at T4 and with a T5-T10 cycle the codes in the registers PB; that is, (0110) (0000)(0000) appear on the addressing code bus to specify the input device (1), which in turn delivers through four-lines respective inputs in parallel to the data-code bus. These inputs are latched into the register A through SW9 and SW2 (See FIG. 14).

Applied through four input lines to the input device (1) are, as shown in TABLE 3, an output signal from the paper-out detector (1=NO) (copying sheet) and 0=YES), an output signal from the toner detector

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(1=NO (toner) and 0=YES), an output signal from the sensor for detecting the temperature of the fixing heater (1=NG, the temperature being below a predetermined level and 0=OK, the temperature being above a predetermined level) and STOP instruction (1=YES and 50=NO). Therefore if all inputs are "0", the copying operation may be started.

At T11 DC is increased by 1 to specify the address 3 in ROM. Then the upper code (0101) and the lower code (1100) are latched into the registers C and D, 10 respectively and decoded as a conditional jump instruction. When the content in the common register A is not zero, the registers PC are increased by 1 so that the upper code (0000) and the lower code (0000) in the address 4 in ROM are transferred into the registers PB2 15 and PB1, respectively, in the manner described above. Therefore the contents in PB become XXXX 0000 0000. The contents in the registers PB2 and PB1 are transferred into the registers PC2 and PC1, respectively, as described elsewhere. Thus the conditional jump instruc- 20 tion has been executed so that the contents in the registers PC are 0000 0000 0000. Therefore at T1, the code in the address 0 in ROM appears again on the data-code bus and the above operations are cycled.

However when the content in the register A is zero; 25 that is, the inputs to the input device (1) are all "0" so that the copying operation may be started, the register PC is increased by 2 so that the jump instruction is skipped and at the next T1 the addressing code for specifying the address 5 in ROM appears on the addressing code bus. Therefore the address code of the output device (1) is set in the registers PB in response to the codes in the addresses 5 and 6 in ROM. Next the register PC is increased by 1 to specify the address 7 in ROM at the next T1 and the upper code (0111) is 35 latched at T2 to the register C and decoded. Thereafter the lower code (1000) is latched to the register A through SW9 and SW2.

The register PC is further increased by 1 to specify the address 8 in RCM at T1, and the upper code (1000) 40 is latched to the register C at T2 and at T3 the lower code (1000), to the register D and they are decoded. The code (1000) stored in the register A is called to appear on the data-code bus through SW1 and SW8 and concurrently the contents (0010 0000 0000) in the register PB is called on the addressing-code bus to specify the output device (1) and latch the data code bus to four output lines of the output device (1). As a result, the outputs are as follows:

101 = 0

102 = 0

103 = 0, and

104 = 1.

The latch 104 is connected through the interface circuit stored (See FIGS. 3-1' through 3-5 and FIGS. 4A and 4B to 55 case. the drum motor which is driven at a first speed V1.

Next STEP 6 in the flowchart shown in FIG. 9-1' will be described in detail with reference to FIG. 11, in STEP 6 it being checked whether the drum is in its home position or not. In STEP 5, the return-stroke or 60 backward clutch is turned off, and then in STEP 6-1, the address (0111) of the input device (2) is stored in the register PB3 and in STEP 6-2, the contents in the input device (1) specified by the register PB3 are transferred into the register A. In STEP 6-3, the contents in the 65 register A are shifted to the right to check whether or not an overflow occurs. If no overflow occurs, STEPS 6-1, 6-2 and 6-3 are cycled. If an overflow is detected in

STEP 6-4, that is, when the screen drum is detected to be in its home position, the control advances to STEP 7.

The addresses in ROM of the instruction codes required for executing the operations in STEPS 6-1 through 6-4 are as follows:

	STEP	Addr	esses in	ROM	ROM	CODES
•		0	0	0		
)						
	6-1	0000	0000	0000	0100	0111
		0.	1	1	1100	0000
	6-2	0	1	2	0110	1000
	6-3	0	1	3	1111	0111
	6-4	0	1	4	0101	0010, jump if $OVF = 1$
5		0	1	5	1000	0000

The upper code (0100) in the address 10 in ROM which is specified after the operation in STEP 5 has been executed is called on the data code bus in the manner described above and is latched to the register C and is decoded to generate the control signal α in response to which the next code called on the data-code bus may be stored in the register PB. That is, in response to the next clock, the lower code (0111) in the address 10 in ROM appears on the data bus and in response to the control signal α it is latched to the register PB3 through SW9 and SW15.

Up to the address 12 in ROM the control proceeds in the same manner with that described with reference to the addresses 0 to 2. That is, the contents in the register PB (0111 0000 0000) appear on the addressing-code bus to specify the input device (2) so that the inputs (000) applied thereto through four input lines are transferred in parallel to the data code bus and latched to the register A through SW9 and SW2. The four inputs applied to the input device (2) are, as shown in TABLE 2, an output signal from the sensor for detecting whether the screen drum is in its home position or not (1 = YES) and 0=NO), an output signal from a sensor for detecting whether the optical system is in its home position or not (1=YES and 0=NO), and two signals representative whether the first and second clock pulses have been detected or not (1=YES and 0=NO). Therefore, the above-mentioned code (0000) means that both the screen drum and optical system are in their home positions, respectively, and no first and second pulses have been detected.

When the address 13 in ROM is specified, the upper code (1110) is transferred into the register C whereas the lower code (0111), into the register D, and they are decoded as an instruction for shifting the register A to the right. Therefore the contents in the shift register A are shifted by one position to the right. Since (0000) are stored in the shift register A, no overflow occurs in this case.

Next the register PC is increased by 0 to specify the address 14 in ROM so that the upper code (0101) is transferred into the register C whereas the lower code (0010), into the register D and they are decoded as a conditional jump instruction for shifting the register A to the right to check if an overflow occurs. In this case, the overflow detector OVF does not detect "1" which means the overflow of the shift register A due to the shift to the right so that the register PC is increased further by 1 to specify the address 15 in ROM. The contents in the address 15 in ROM; that is, (0001 0000) are called on the data-code bus, and the upper code (0001) is transferred into the register PB2 whereas the

lower code (0000), into the PB1, and thereafter they are further transferred into the register PC. The addressing code for access to the address 10 in ROM is stored again and called at T1 so that the sequential steps from the address 10 in ROM to the address 13 are cycled.

However, when an overflow is detected in STEP 6-4; that is, when the contents (0001) representative of the detection the screen drum in its home position which are stored in the shift register A are shifted to the right so that the content in the overflow detector OVF becomes 1, the control signal α is generated which causes the register PC to increment by 2. Therefore a code of an address in ROM for jumping over the addresses to be jumped to STEP 7 is stored in the register PC.

Next with reference to FIG. 12 and TABLE 4, the 15 steps for turning the primary charger on in response to the content of the counter CP1 in STEP 8 shown in FIG. 9 will be described in more detail. In STEP 8-1, a code representative of an address N (for instance 120) in ROM where a predetermined number of 60 copy clocks 20 is stored is set into the register PB.

TABLE 4

				TVD	T T T		
STEP		ddress n RON		ROM	Codes		
	0	2	0				25
8-1	0000	0010	0000	0100	0000	•	
	0	2	1	1100	0000	"OCO"	
8-2	0	2	2	1101	0000	•	
8-3	0	, 2	3	1110	1001		
8-4	0	2	4	1110	1111		20
8-5	0	2	5	1110	1000		30
8-6	0	2	6	0010	0001		
8-7	0.	2	7	0100	0111		
	0	2	8	0000	0000		
8-8	0	2	9	0110	1000		
8-9	0	2	Α	1110	0110		
8-10	0	2	В	1111	0110		35
8-11	0	2	С	0101	0010	jump if $OVF = 1$	
	0	2	\cdot D	0010	0110		
8-12	0	_ 2	E	0100	0111		
	0	2	F	0000	0000		
8-13	0	3	0	0110	1000		
8-14	0	3	1	1111	0110		40
8-15	0	3	2	1111	0110	•	
8-16	0	3	3	0101	1010	jump if OVF $\neq 1$	
				2	В		
	0	3	4	0010	1110	•	
8-17	Ö	3	5	0011	0001		
8-18	ŏ	3	6	1110	0100		45
8-19	ŏ	3	7	0010	0001		
8-20	ŏ	3	8	1110	1101		
8-21	Ö	3	9	0101		jump if Register $A \neq O$	
	J	-		2	7	jump m regional cz , o	
	^	•		0010	0111		50
0.00	0	3	A	0010	0111	•	50
8-22	0	3	B	1110	1100		
8-23	0	3	· C	0101	1100		
	0	3	$\cdot \mathbf{D}$	0010	0111		

In STEP 8-2, the upper code (1101) and the lower 55 code (0000) stored in the address 22 in ROM are called and transferred into the registers C and D, respectively, and then decoded and the above addressing code in the register PB is called on the addressing code bus to specify the read-only memory and its address 120. The content "60" (which is equal to a number of clocks to be counted) in the address 120 is called on the data-code bus.

In the present embodiment, the level 0 of the copy clock is detected first so that the rise of the copy clock 65 signal may be detected for counting.

In STEP 8-20 the contents in the register PB2 are transferred into the register A (The contents in the

register PB remain unchanged ever after STEP 8-19 has been executed.), and in STEP 8-21 the content in the register A; that is, the most significant bit of the decremented numeral code is detected to be 0 or not. In STEP 8-23 it is checked whether the least significant digit of the numeral code is 0 or no. Thus the counting step has been accomplished.

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The frequency of the clock pulses ϕ for the computer CPU is 1 microsecond and a time or cycle required for executing the counting steps is about 30 steps so that one step requires (10 clocks×1 microsecond) or 300 microseconds at the most. Since the frequency of the copy clock pulses is about 8 miliseconds as described above, it will not adversely affect the counting.

In FIG. 14 there is shown a circuit diagram of the control unit or controller for decoding the instruction and data codes from ROM and generating the control signal α in accordance with the above described procedures will be described. The circuit shown in FIG. 14 is so arranged as to accomplish the operations in respective steps shown in FIG. 10, but it will be understood that a control circuit may be designed to accomplish the operations in other steps. In FIG. 14 a CP gate is provided so that an output may be derived when a predetermined number of clock pulses ϕ has been counted.

The screen drum in its home position is represented by an output signal "1" which is generated by an optical sensor 43 when it detects a mark 68 (See FIG. 1B). The condition that there is no copying sheet available is represented by an output signal "1" generated by the optical sensors 80 and 81 (See FIG. 1B). The condition that no toner is available is represented by the signal "1" from a Hall-effect integrated-circuit 32 which is actuated by a lever (See FIG. 16-6).

In FIGS. 17-1' and 17-1" there is shown an instruction flowchart for executing the operations in STEPS 44, 45 and 46 of FIG. 9-3'. It is assumed that the following data are stored in the addresses in RAM.

	ADDRESSES		SES	DATA STORED
	015 3rd digit	016 2nd digit	017 Ist digit	a number of copies reproduced which is entered in STEP 43
5	030 3rd	031 2nd	032 1st	a desired number of copies, which is entered in STEP 0.
	digit 014	digit	digit	code representative of FINISH mode (RAM 3)
•	01A 2nd	01B 1st	-	a repetitive number, which is entered in STEP 7 (RAM 4)
0	digit	digit		

In FIG. 17, 0, 1, 4 represents the address 014 in RAM 3. In TABLE 5, there are shown codes which correspond to the instructions shown in FIGS. 17-1' and 17-1" and are stored in ROM.

TABLE 5

		ROM	Codes
STEP	Addresses in ROM	MSB	LSB
STEP 44-1	100	0100	0000
	101	0001	0100
STEP 44-2	102	0110	1000
STEP 44-3	103	0101	0100
	104	0001	1100
STEP 45-1	1 0 5	0100	0000
	106	0001	0101
STEP 45-2	1 0 7	0110	1000
STEP 45-3	108	0100	0000
	109	0011	0000

TABLE 5-continued

1	TABLE 5-continued ROM Codes NOR - 1.50			
		ROM Codes		
STEP	Addresses in ROM	MSB	LSB	
STEP 45-4	1 0 A	1001	1100	
STEP 45-5	1 0 B	0101	1100	
	1.0 C	0101	.0000	
STEP 45-6	1 0 D	0100	0000	
	10E	0001	0110	
STEP 45-7	10F	0110	1000	
STEP 45-8	110	0100	0000	
	1 1 1	0011	0001	
STEP 45-9	1 1 2	1001	1100	
STEP 45-10	1 1 3	0101	1100	
STEP 45-11	1 1 5	0100	0000	
	1 1 6	0001	0111	
STEP 45-12	1 1 7	0110	1000	
STEP 45-13	1 1 8	0100	0000	
	119	0011	0010	
STEP 45-14	1 1 A	1001	1100	
STEP 45-15	1 1 B	0101	1100	
	11C	0101	0000	
STEP 46-1	1 1 D	0111	0001	
STEP 46-2	11E	0100	0000	
	11F	0001	0100	
STEP 46-3	120	1001	1100	
STEP 49				
•		. •	,	
•	•	•	•	
•	•	•		
STEP 47, 48-1	1 5 0	0100	0000	
	1 5 1	0001	1011	
STEP 47, 48-2	1 5 2	0110	1000	
STEP 47, 48-3	1 5 3	1111	1011	
STEP 47, 48-4	1 5 4	0101	1010	
	156	0110	1000	
STEP 47, 48-5	1 5 7	1111	0001	
STEP 47, 48-6	158	1000	1000	
STEP 47, 48-7	159	1110	0101	
STEP 47, 48-8	1 5 A	0110	1000	
STEP 47, 48-9	1 5 B	1111	1011	
STEP 47, 48-10	1 5 C	0101	1010	
	1 5 D	0110	0001	
STEP 47, 48-11	15E	1111	0001	
STEP 47, 48-12	1 5 F	0101	1000	
	160	0001	1101	
STEP 47, 48-13	161	1000	1000	
STEP 50				
•	•	•	•	
•	•	•	•	

No further description of FIGS. 17-1' and 17-1" and TABLE 5 because they themselves suffice for the understanding thereof.

In FIG. 13 there is shown a flowchart for STEP 66 or the decision whether FINISH mode has been reached or not, and the codes stored in ROM for this purpose are shown in TABLE 6.

TABLE 6

STEP 66-1	Addresses in ROM	ROM Codes	
	200	0100	0000
	2 0 1	0001	0100
STEP 66-2	202	0110	1000
STEP 66-3	203	0101	0100
	204	0011	0110
STEP 67	2 0 5		
•	•		
•	•		
•	•		
STEP 40	236		

In FIGS. 15A through 15D there is shown a more detailed circuit diagram of the devices shown in FIGS.

3-1 through 3-5. CPV(2-1) is NOP 711, a product of 65 of clocks.

NIPPON DENKI K.K.; ABO-7, addressing code outputs to ROM and RAM chips; AB8-11, outputs connected to a chip-selecting chip (1-1) for selecting a chip; cording metals and content and con

DBO-3, data input-output lines; R/W, a read-write instruction signal; φ, a clock signal; SA, a sub-address line for the four-bit time-division of the output from ROM; RES, a reset line for resetting the chip when the power is turned on; CDF, a line through which a signal for deactivating CPV such as FSTOP signal from STOP key is applied; CTF, a line calling for one program instruction directly from CPU; and F, an output line for transmitting the read instruction (See also FIGS. 4A and 4B, timing chart).

(1-1) is the chip-selecting chip which decodes the upper four bits of the 12-bit addressing code from CPU for transmitting CS signal through one of the output lines 1-8, thereby selecting a required chip.

(2-1)-(2-4) are ROM chips each address of which is specified by the AB lines. They are of the conventional matrix type. D1-8 are output lines.

Latch circuit chips (3-3) and (3-4) latch four bits of their respective outputs.

Multiplexers (4-1)-(4-4) transfer the outputs from the latch circuit chips (3-3) and (3-4) four bits at one time to FF(5-1) in order to obtain the timing relationship shown in FIGS. 4A and 4B.

A key display circuit (6-2) is shown in more detail in FIG. 16-1. Each display unit consists of 7 light-emitting-diode segments S_1 - S_7 . Synchronous lines T_0 - T_9 are provided in order to dynamically indicate keyed inputs.

The output circuits (7-1)-(7-4) and input circuits (8-1);14 (8-2) which are shown in more detail in FIGS. 16-3 and 16-4 are connected through the DB lines to the computer CPU.

(8-3) is a circuit for determining an address for starting writing in ROM when the copying operation is started.

In FIG. 18 there is shown a diagram of a circuit for controlling the process for calling data from ROM by counting the drum master clocks or by the detection of the screen drum in its home position. A program 40 counter PC is incremented by one so that data may be sequentially called starting from an address X000 in ROM. Outputs 0-4 from a decoder are connected through a latching circuit to loads. When a designated address in ROM is accessed, an output signal is derived from an output terminal F of the decoder and is transmitted to the program counter PC so that the increment by 1 thereof may be interrupted and consequently the reading of ROM may be stopped. When the screen drum is rotated and brought to its home position again, 50 the program counter PC is incremeted by 1 so that a next address in ROM may be accessed. Instead of a circuit for incrementing by 1 the program counter PC, and AND gate may be employed to which are applied a step clock and an output from the output terminal X 55 from the decoder. The "1" output may be derived from the X output terminal when the output "1" is derived from one of the output terminals O-F. Same is true when the drum clocks are counted.

In the dry copying machine described above, the forcessing time is stored in the read-only memory and in like manner the present invention may be applied to a wet type copying machine so that an idle rotation (more than one rotation of a drum before and after an effective processing may be stored in terms of a number of clocks.

What we claim is:

1. A copying or printing machine comprising a recording medium; actuatable elements, including scan21

ning means, for forming an image on said recording medium; key input means for setting data or instructing a copy operation; and control means including a readonly memory having stored programs for controlling actuations of said elements; wherein the programs stored in said read-only memory include a key entry program for entry of inputs from said key input means and a positioning program for determining whether or not said scanning means is in a predetermined position and for permitting said scanning means to be set to the 10 predetermined position prior to an image formation; wherein said control means moves said scanning means to the predetermined position in response to the positioning program when said scanning means is not in the predetermined position after the entry of the key inputs 15 by the entry program, and enables a copying operation when said scanning means is set in the predetermined position, said control means executing said key entry program after the machine starts, and executing the positioning program before the start of said scanning 20 means and after the entry of said key input means; and wherein said control means executes said positioning program in response to the entry of said key input means and moves said scanning means to a predetermined position after the supply of power to said ma- 25 chine.

- 2. A copying or printing machine comprising a recording medium; actuatable elements, including scanning means, for forming an image on said recording medium; key input means for setting data or instructing 30 copy operation; and control means including a readonly memory having stored programs for controlling actuations of said elements; wherein the programs stored in said read-only memory include a key entry program for entry of inputs from said key input means, 35 a positioning program for determining whether or nor said scanning means is in a predetermined position and for permitting said scanning means to be set to the predetermined position prior to an image formation, and a diagnostic program for determining whether the state 40 of the machine is proper or improper; wherein said control means moves said scanning means to the predetermined position in response to the positioning program when said scanning means is not in the predetermined position after the entry of the key inputs by the 45 entry program, and enables a copying operation when said scanning means is set in the predetermined position, said control means executing said key entry program after the machine starts, and executing the positioning program before the start of said scanning means and 50 after the entry of said key input means; and wherein said control means executes said positioning program and moves said scanning means to a predetermined position in response to the execution of said diagnostic program.
- 3. A copying or printing machine comprising a recording medium; actuatable elements, including scanning means, for forming an image on said recording medium; key input means for setting data or instructing copy operation; and control means including a readonly memory having stored programs for controlling 60 actuations of said elements, wherein the programs stored in said read-only memory incude a key entry program for entry of inputs from said key input means, a positioning program for determining whether or not said scanning means is in a predetermined position and 65 permitting said scanning means to be set to the predetermined position prior to an image formation, and a diagnostic program for determining whether the machine is

in a proper or improper operational state, wherein said control means moves said scanning means to the predetermined position in response to the positioning program when said scanning means is not in the predetermined position after the entry of the key inputs by the entry program, and enables a copying operation when said scanning means is set in the predetermined position, said control means executing said key entry program after the machine starts, and executing the positioning program before the start of said scanning means and after the entry of said key input means, and wherein said control means inhibits the scanning means from illuminating an original document when said diagnostic program determines that the state of the machine is improper, or when said positioning program determines that said scanning means is not in said predetermined position, and said control means enables the scanning means for illuminating the original document when said diagnostic program determines that the state of the machine is proper and said positioning program determines that said scanning means is in said predetermined position.

- 4. A copying or printing machine as set forth in claim 3, wherein said recording medium is a photoconductive recording medium, said scanning means is movable for exposing said recording medium, and said scanning means movement is controlled by said control means.
- 5. A copying or printing machine as set forth in claim 3, wherein said control means executes the positioning program after setting the number of required copies and instructing the start of copying.
- 6. A copying or printing machine as set forth in claim 3, wherein said control means executes the positioning program after said diagnostic program.
- 7. A copying or printing machine as set forth in claim 3, wherein said control means inhibits the movement control of said scanning means in response to said positioning program when said diagnostic program determines that the state of the machine is improper.
 - 8. A copying or printing machine comprising: reciprocation means adapted to scan and expose an original;
 - driving means for moving said reciprocation means; at least one read-only adapted to store a program for sequence control of said driving means;
 - first input means for entering a first detection signal for detecting a starting position at which reciprocation means starts moving to expose the original;

second input means for entering a second detection signal for detecting other machine states; and

- control means connected to said first and second input means for providing a control signal to said driving means in response to the procedure of said program and said first and second detection signals; wherein said control means includes a first discrimination means for discriminating whether or not said machine state is improper on the basis of the second detection signal entered by said second input means, and a second discrimination means for discriminating whether or not said reciprocating means is located in the starting position on the basis of the first detection signal entered by said first input means,
- wherein said control means is arranged to inhibit the scan for exposure by said reciprocation means when said first discrimination means determines that said machine state is improper, or said second discrimination means determines that said recipro-

cation means is not located in the starting position; said control means is arranged to control said reciprocation means to return to the starting position when said second discrimination means determines that said reciprocation means is not located in the starting position; and said control means is arranged to enable the scan and exposure by said reciprocation means when said first discrimination means determines that said machine state is proper and said second discrimination means is located in the starting position or returns to the starting position.

9. A copying or printing machine as set forth in claim 8, wherein said control means inhibits the returning control of said reciprocation means controlled by said second discrimination means when said first discrimination means determines that said machine state is improper.

10. A copying or printing machine as set forth in claim 8, wherein said second detection signal for detecting the state of the machine relates to the quantity of copy or print material.

11. A copying or printing machine as set forth in claim 8, wherein said second detection signal relates to the fixing temperature.

PATENT NO. :

4,685,796

Page 1 of 4

DATED

August 11, 1987

INVENTOR(S):

KATSUICHI SHIMIZU, ET AL.

It is certified that error appears in the above-identified patent and that said Letters Patent is hereby corrected as shown below:

IN THE DRAWING FIGURES

SHEET 13, FIG. 8, "CLER RAM" should read --CLEAR RAM ADDRESS 1,2 ADDRESS 1,2

SHEET 21, FIG. 9-3", "ROLLR" should read --ROLLER--. SHEET 32, FIG. 16-2, "KEY-BOAD UNIT" should read --KEY-BOARD UNIT--.

COLUMN 2

Line 57, "everytime" should read --every time--.

COLUMN 3

Line 18, "FIGS.901," should read --FIGS.9-1,--.

Line 36, "a" should read --an--.

Line 61, "numberal" should read--numeral--.

Line 63, "63," should read --53,--.

COLUMN 4

Line 22, "(0) (9)." should read --(0)-(9).--.

Line 30, "if" should read --is--.

COLUMN 5

Line 3, "depresseion" should read --depression--. Line 12, "the drum" should read --the screen drum--.

PATENT NO.: 4,685,796

Page 2 of 4

DATED

August 11, 1987

INVENTOR(S): KATSUICHI SHIMIZU, ET AL.

It is certified that error appears in the above-identified patent and that said Letters Patent is hereby corrected as shown below:

COLUMN 6

Line 55, "through interface" should read --through an interface--.

Line 62, "simultanneous" should read --simultaneous--.

COLUMN 7

Line 62, "pulses, For" should read --pulses; for--.

COLUMN 8

Line 21, "screen biase charger" should read --screen bias charger--.

COLUMN 9

Line 2, "already repro-" should read --already been repro- --.

Line 43, "locations" should read --location--.

Line 47, "everytime" should read --every time--.

"9-3'''." should read --9-3''').--.

Line 51, "FIG. 9-1" should read --FIGS. 9-1'--.

COLUMN 10

Line 21, "everytime" should read --every time--.

Line 34, "returning its" should read --returning to its--. Line 63, "STEPS 24-42" should read --STEPS 25-42--.

PATENT NO.: 4,685,796

Page 3 of 4

DATED

August 11, 1987

INVENTOR(S):

KATSUICHI SHIMIZU, ET AL.

It is certified that error appears in the above-identified patent and that said Letters Patent is hereby corrected as shown below:

COLUMN 11

Line 48, "NICHIDEN KK" should read --NICHIDEN KK.--.

COLUMN 14

Line 2, "STEPS" should read --STEP--.

Line 7, "latch 104" should read --latch is 104--.

Line 35, "contents;" should read --contents, --.

COLUMN 15

Line 8, "Tll DC" should read --Tl, PC--.

Line 55, "4B to" should read --4B) to--.

COLUMN 17

Line 8. "detection the" should read --detection of the--.

COLUMN 18

Line 13, "miliseconds" should read --milliseconds--.

Line 28, "43" should read --67--.

COLUMN 19

Line 44, "TABLE 5 because" should read --TABLE 5 will be

given because--.

Line 65, "CPV(2-1)" should read --CPU--.

PATENT NO.: 4,685,796

Page 4 of 4

DATED

August 11, 1987

INVENTOR(S):

KATSUICHI SHIMIZU, ET AL.

It is certified that error appears in the above-identified patent and that said Letters Patent is hereby corrected as shown below:

COLUMN 20

Line 6, "CPV" should read --CPU--.

Line 29, "(8-1);14(8-2)" should read --(8-1)-(8-2)--.

Line 53, "and" should read--an--.

Line 64, "processing" should read --processing)--.

COLUMN 22

Line 44, "read-only" should read --read-only memory--.

Signed and Sealed this Sixteenth Day of February, 1988

Attest:

DONALD J. QUIGG

Attesting Officer

Commissioner of Patents and Trademarks