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**Beers et al.**

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(54) **ARTICLE OF FOOTWEAR COMPRISING  
MOTORIZED TENSIONING DEVICE WITH  
SPLIT SPOOL SYSTEM**

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(2022.01); *A43B 11/00* (2013.01); *A43C 1/003*  
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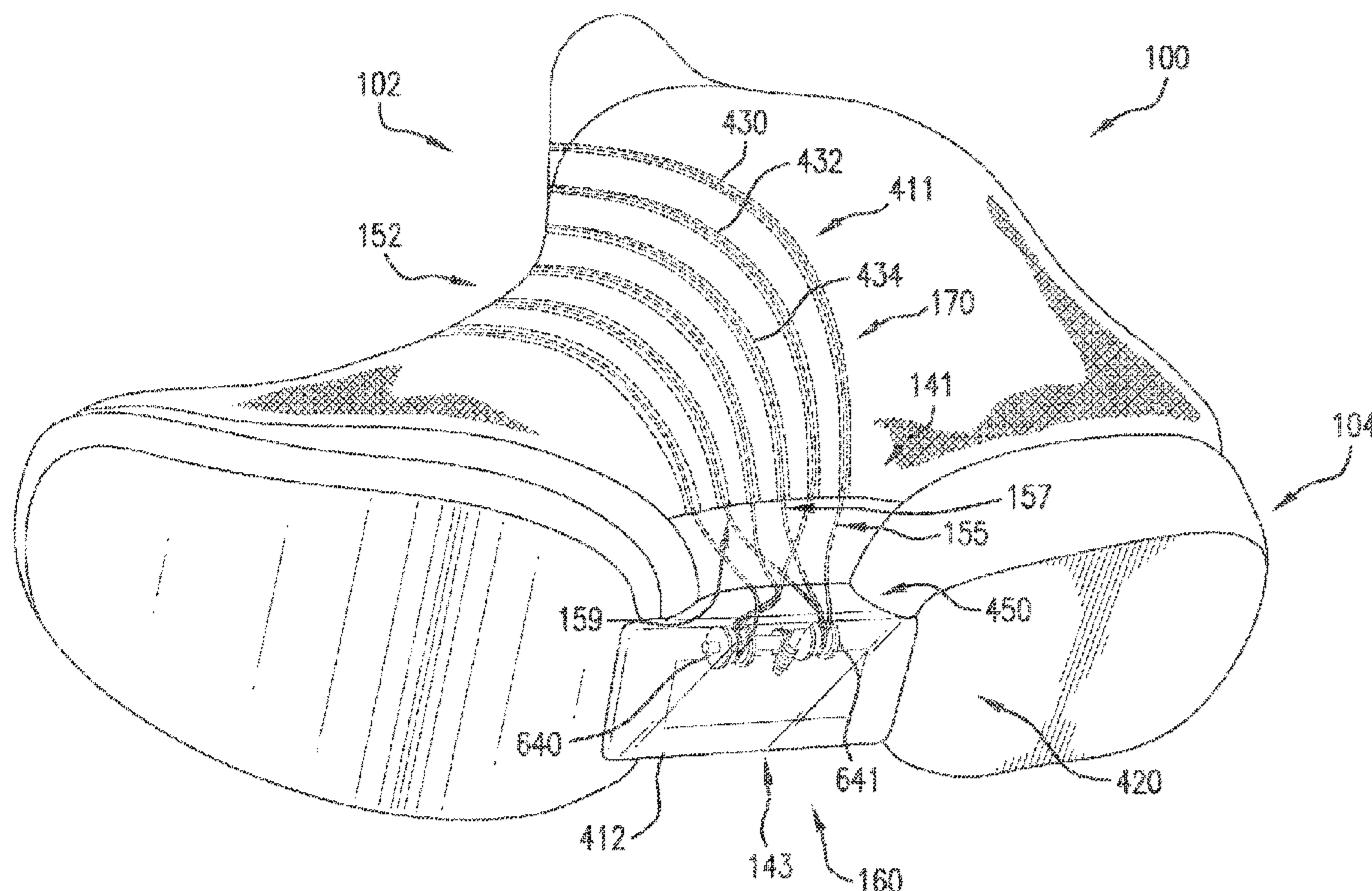
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(57) **ABSTRACT**

A tensioning system for articles of footwear and articles of  
apparel is disclosed. The tensioning system includes a  
tensioning member that is tightened or loosened using a  
motorized tensioning device for winding and unwinding the  
tensioning member on a spool. The motorized tensioning  
device includes a torque transmitting system that allows for  
incremental tightening, incremental loosening and full loos-  
ening of the tensioning member.

**10 Claims, 15 Drawing Sheets**



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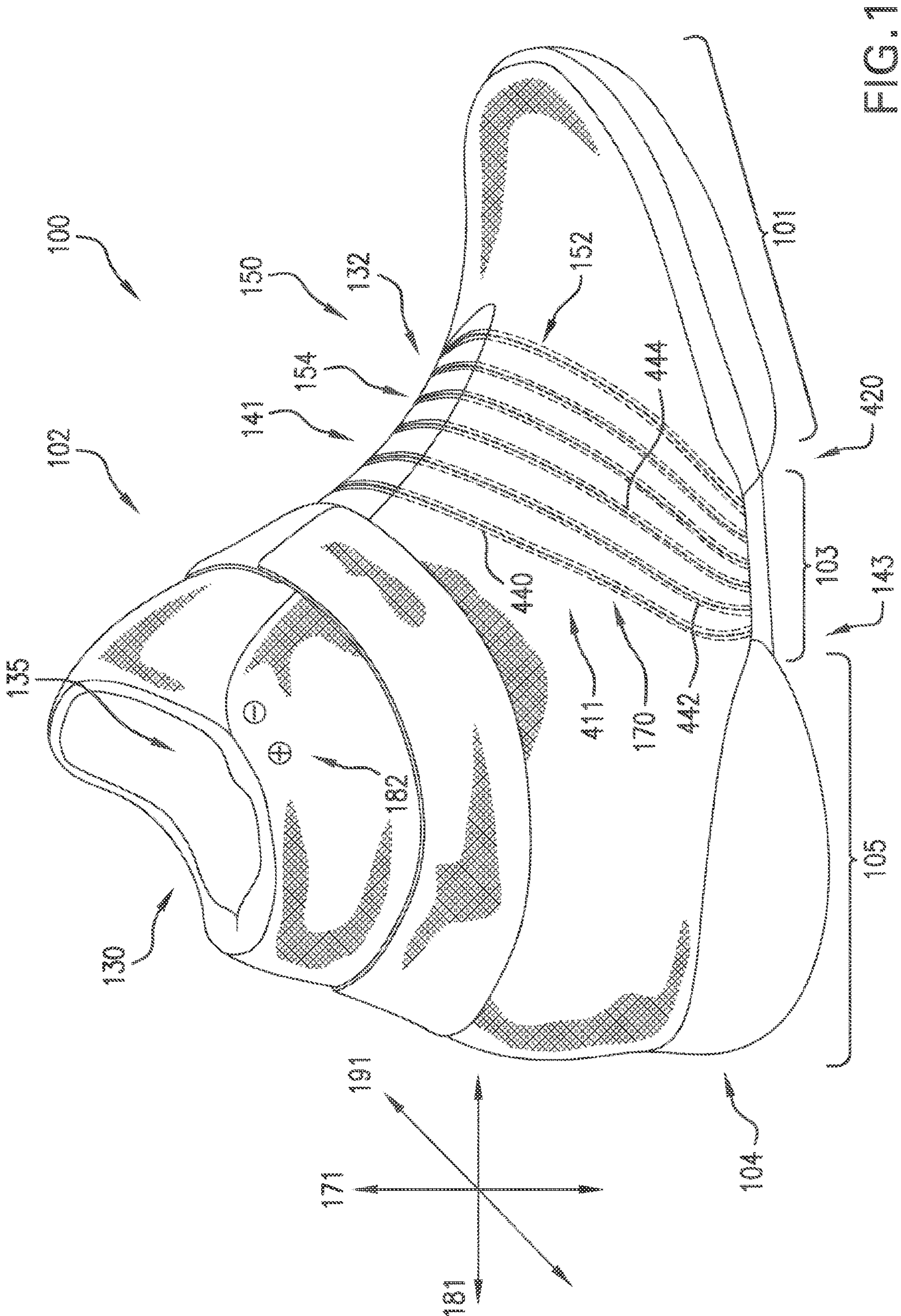
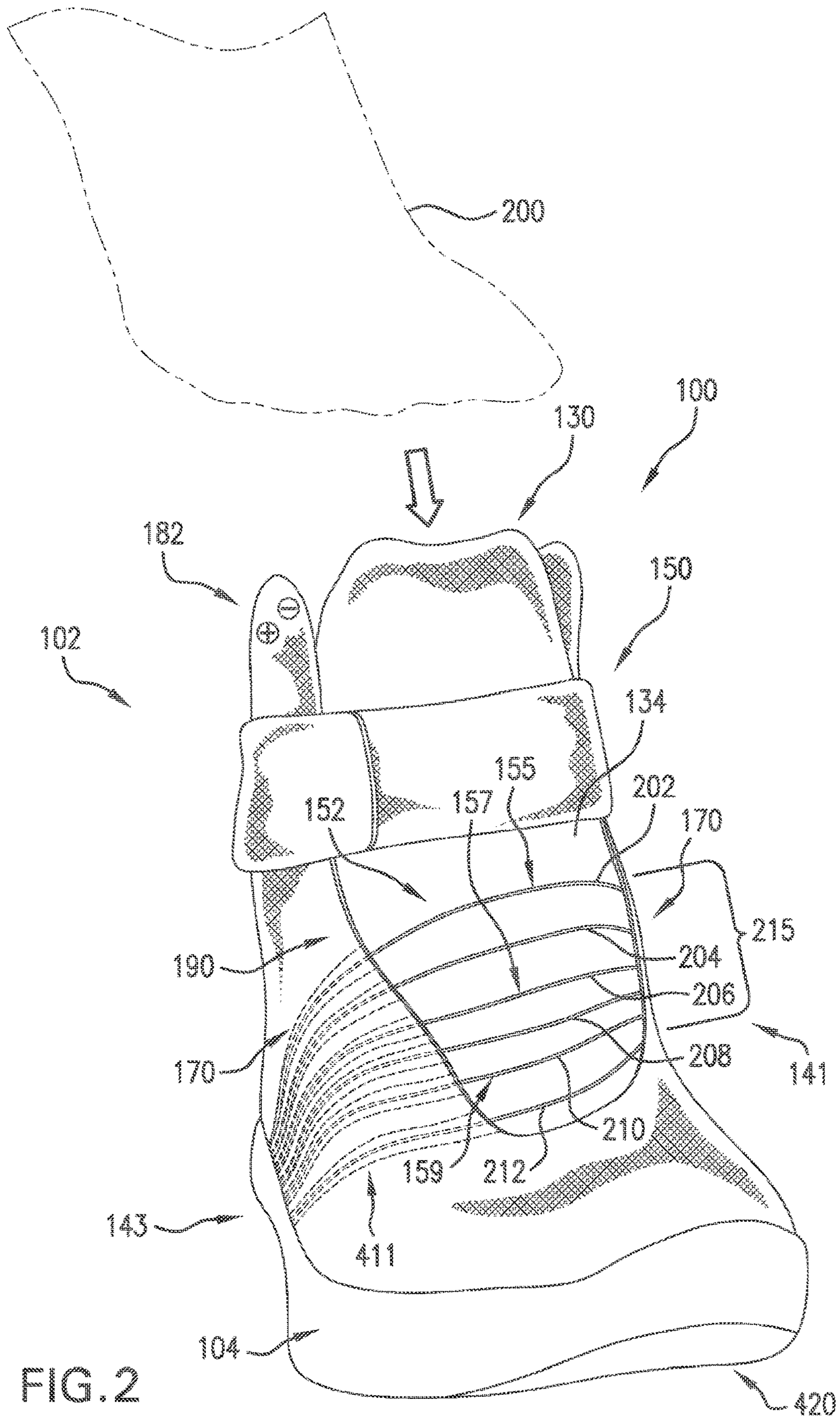


FIG. 1



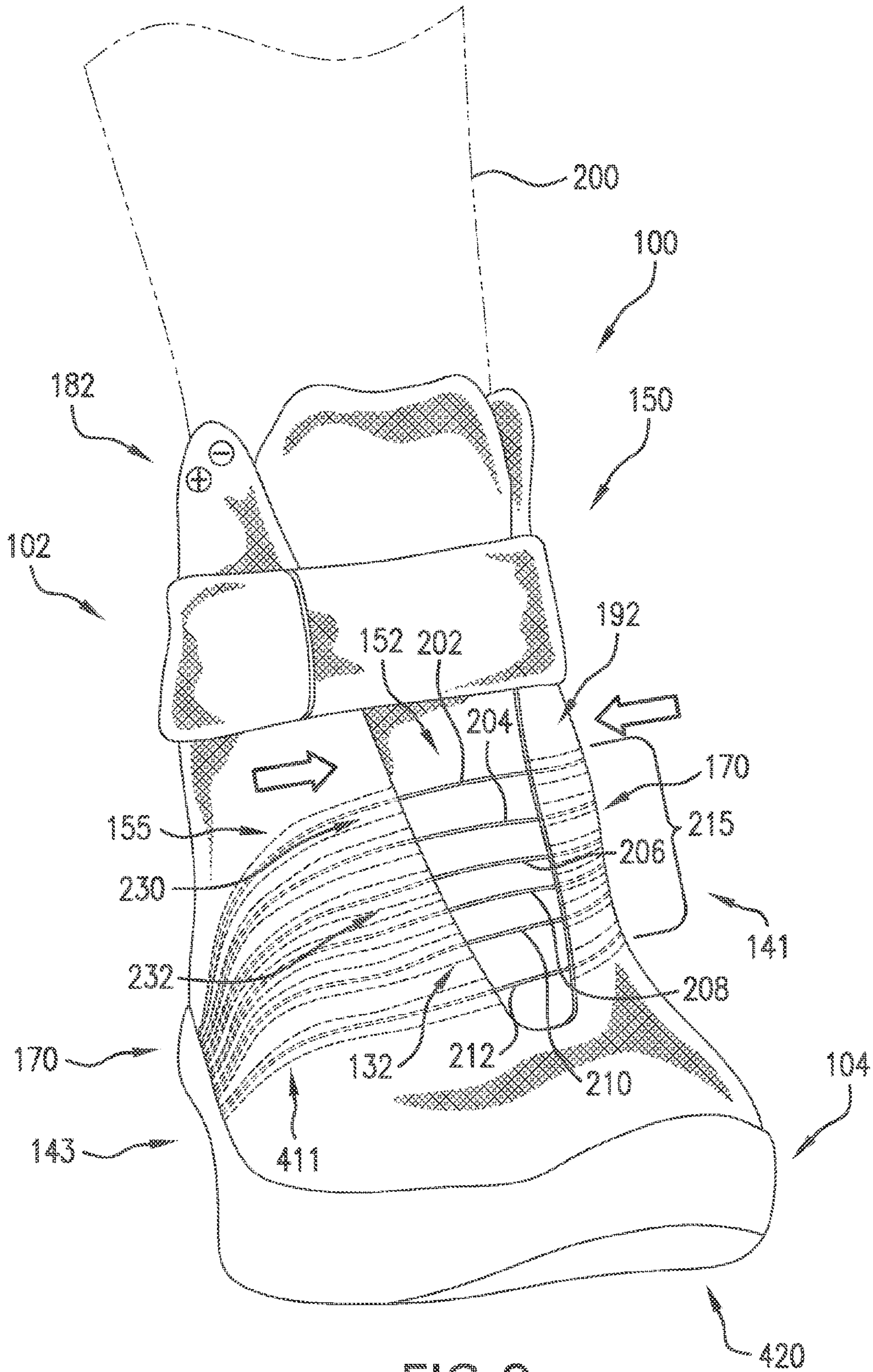


FIG. 3

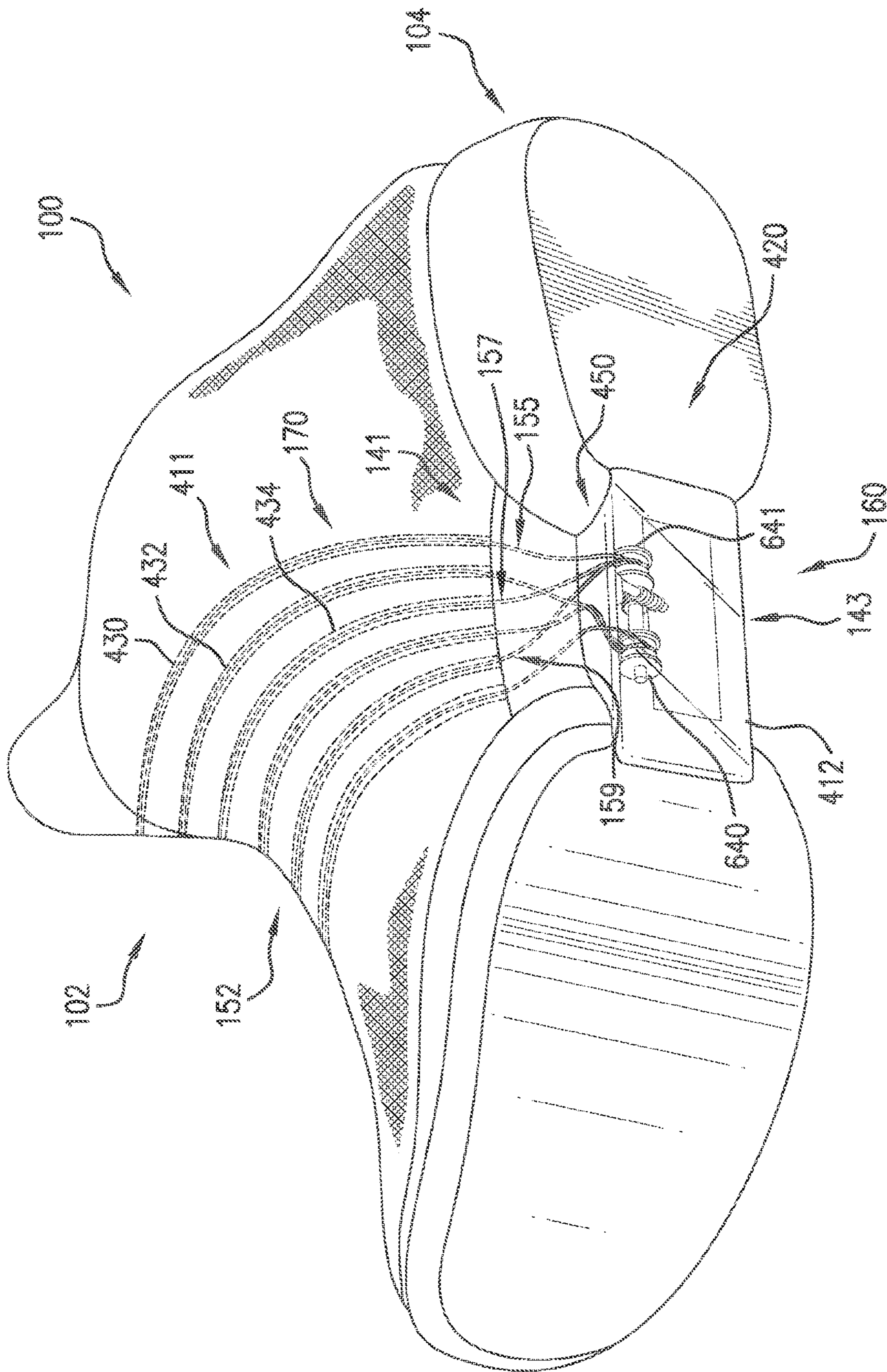


FIG. 4

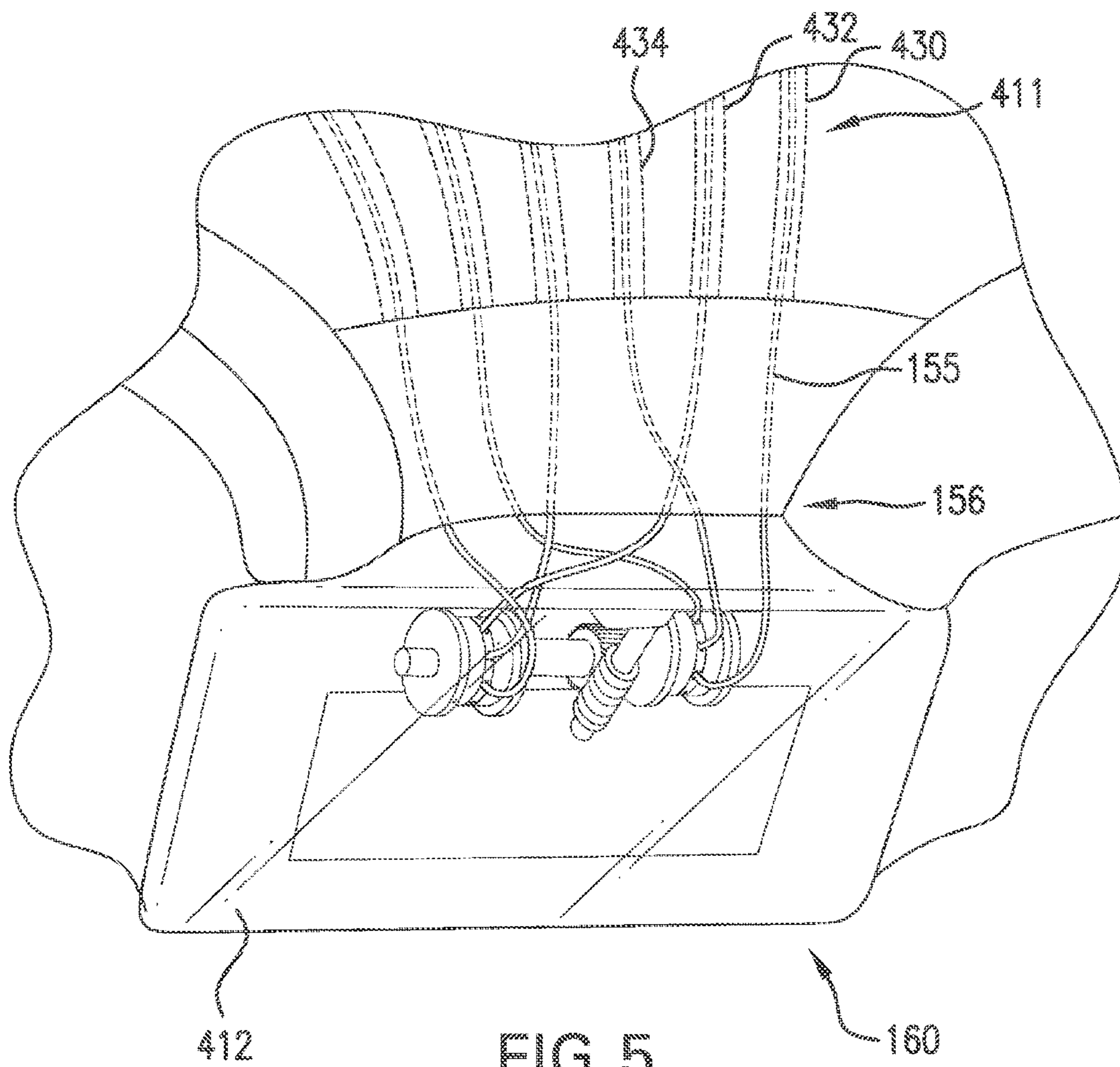


FIG. 5



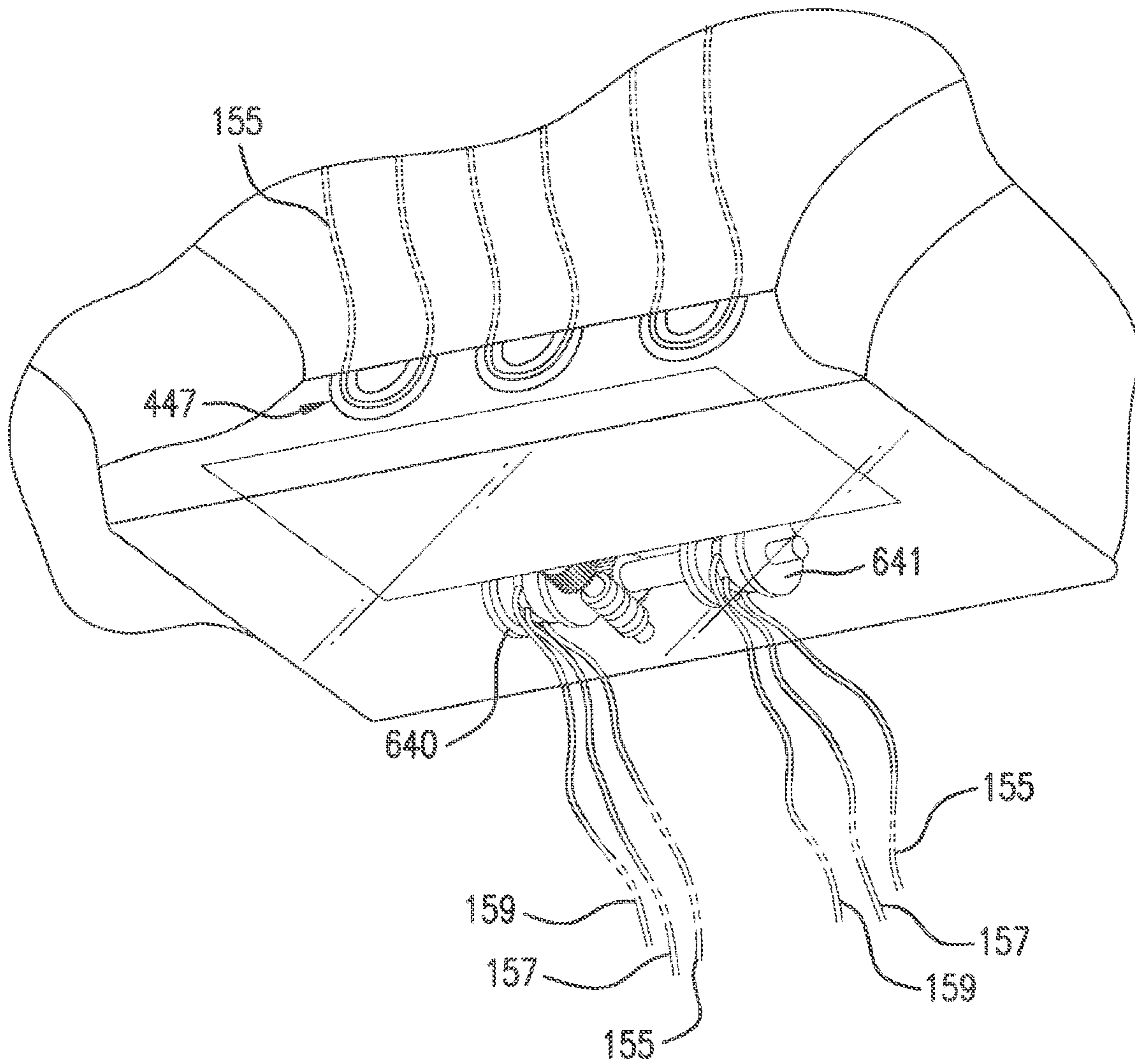
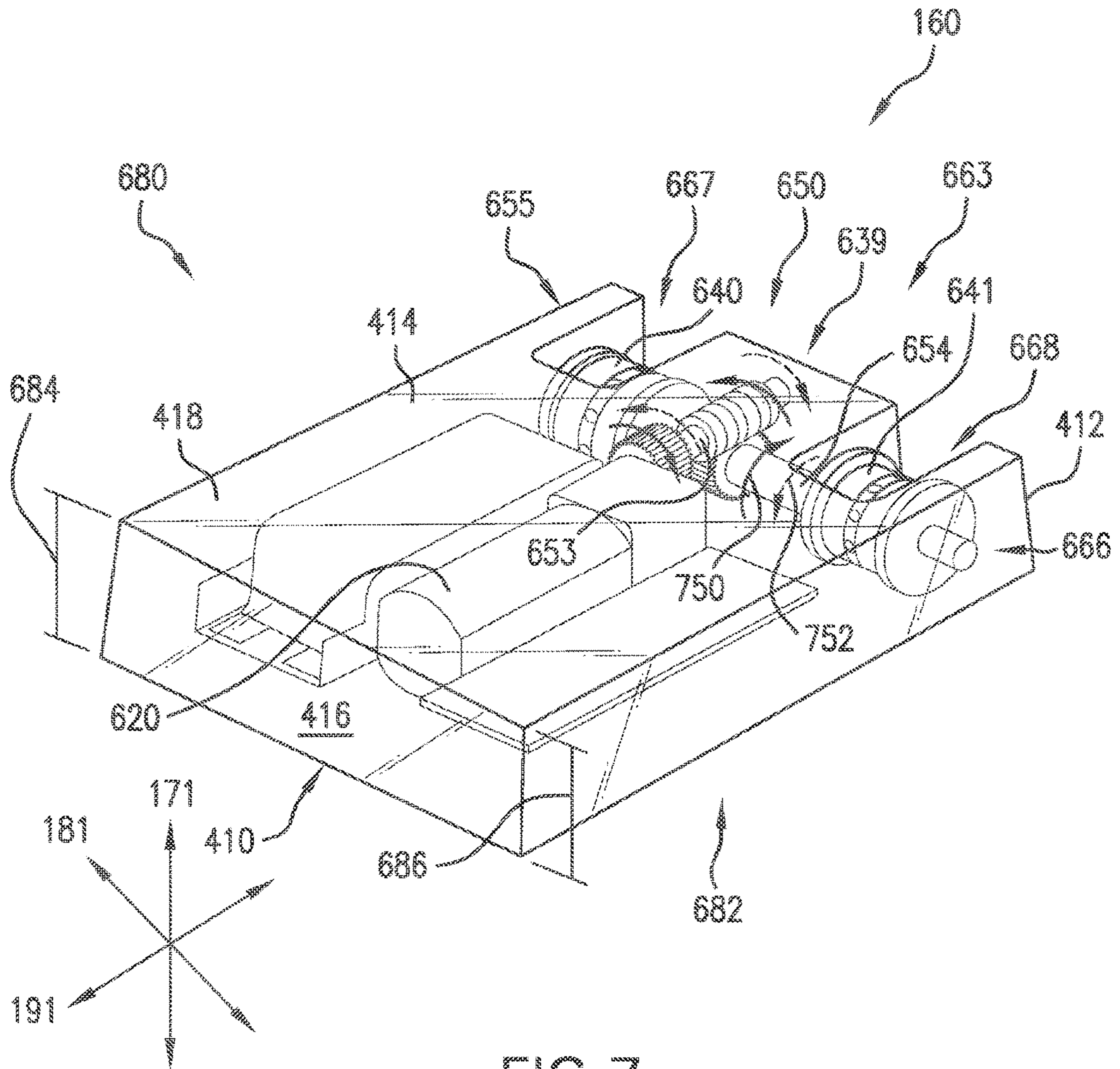


FIG. 6



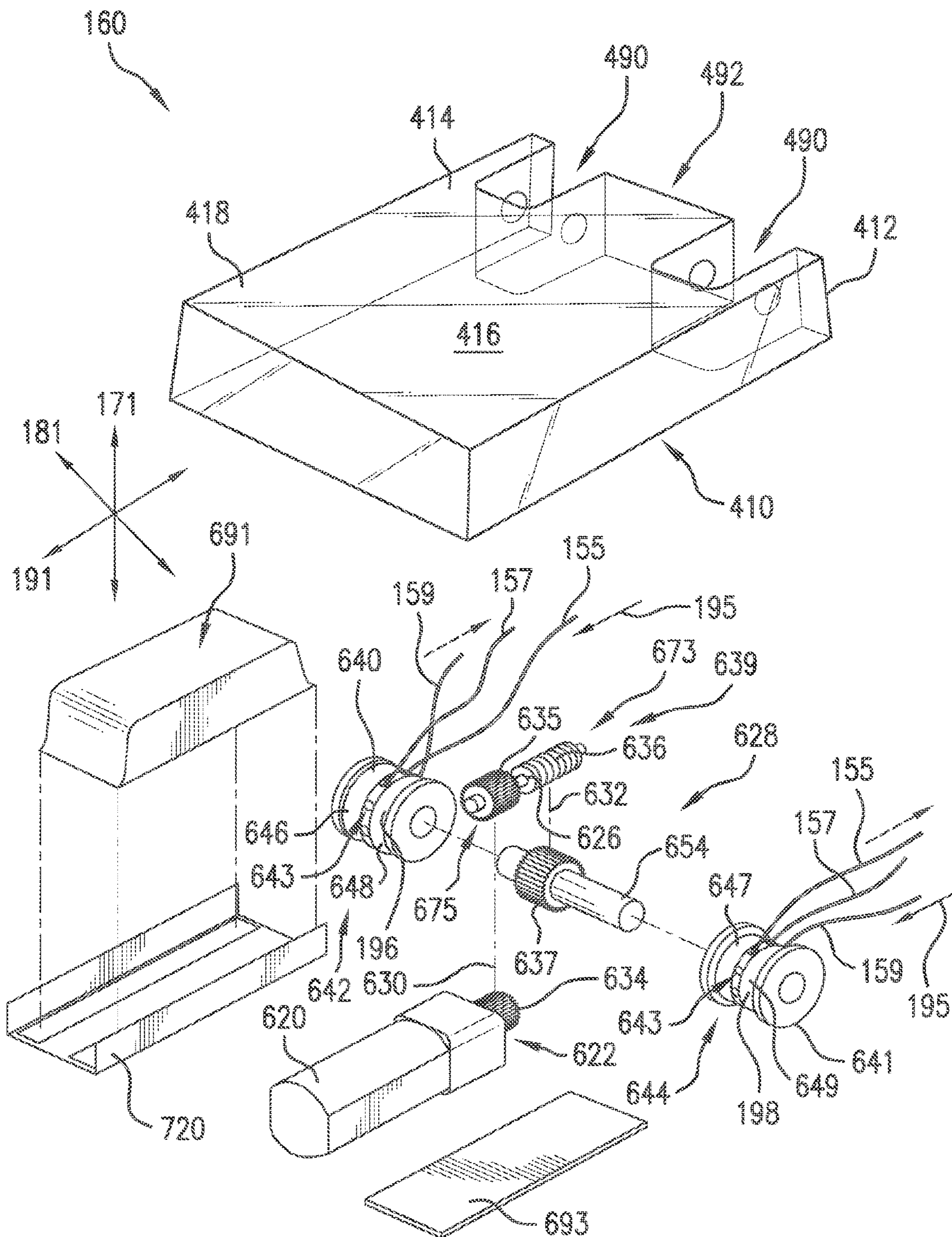


FIG. 8

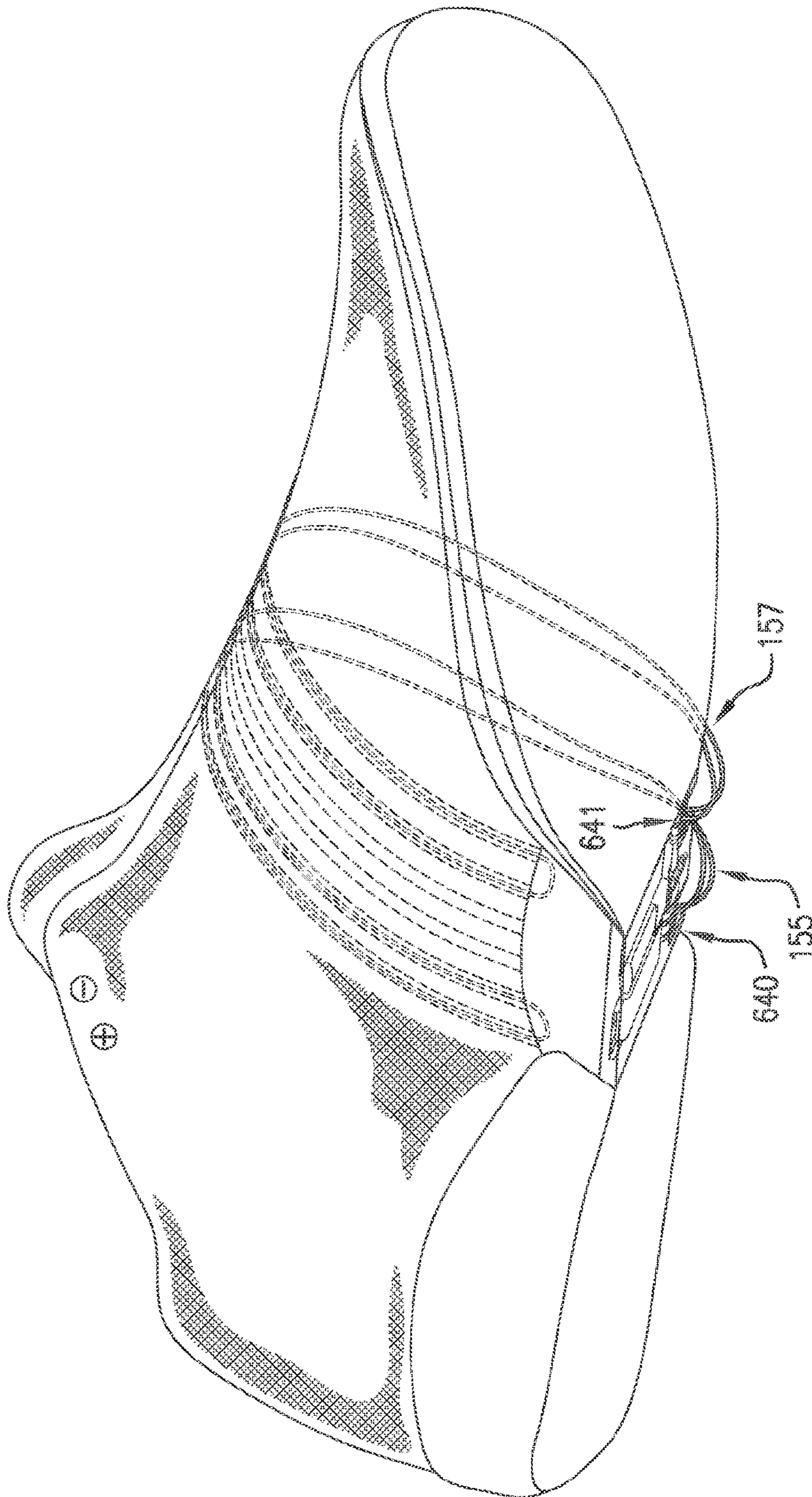


FIG. 9

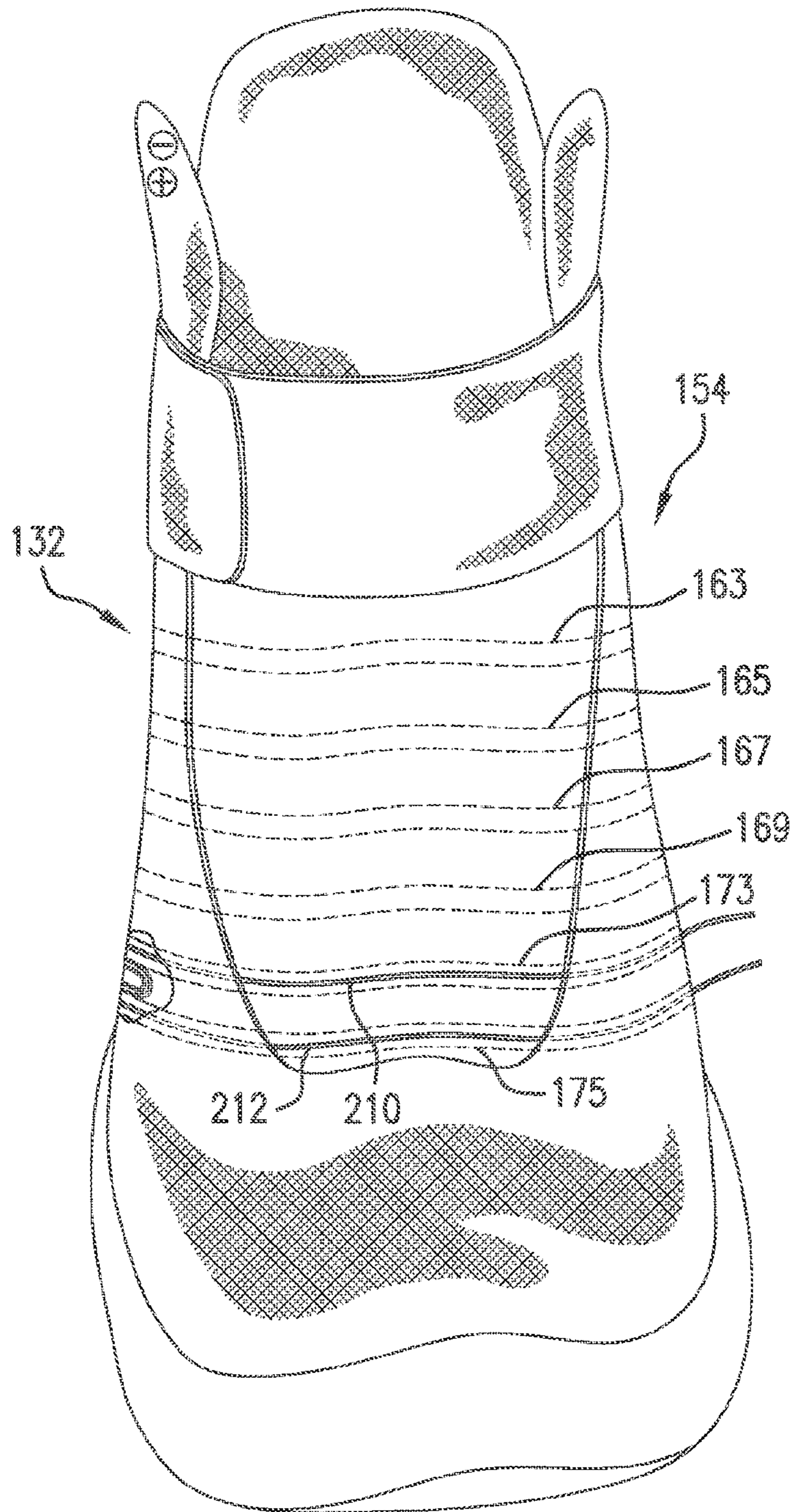


FIG. 10

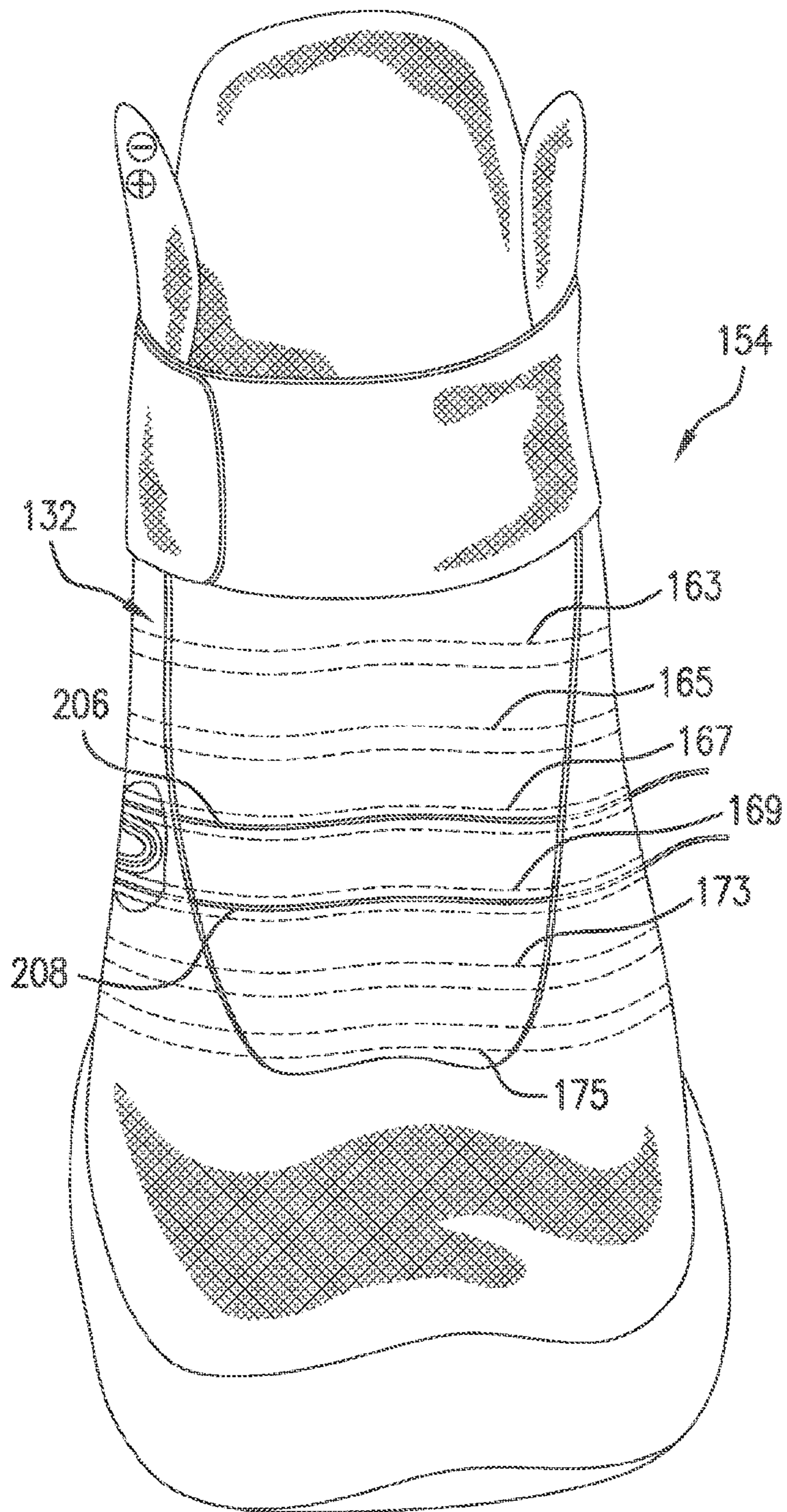


FIG. 11

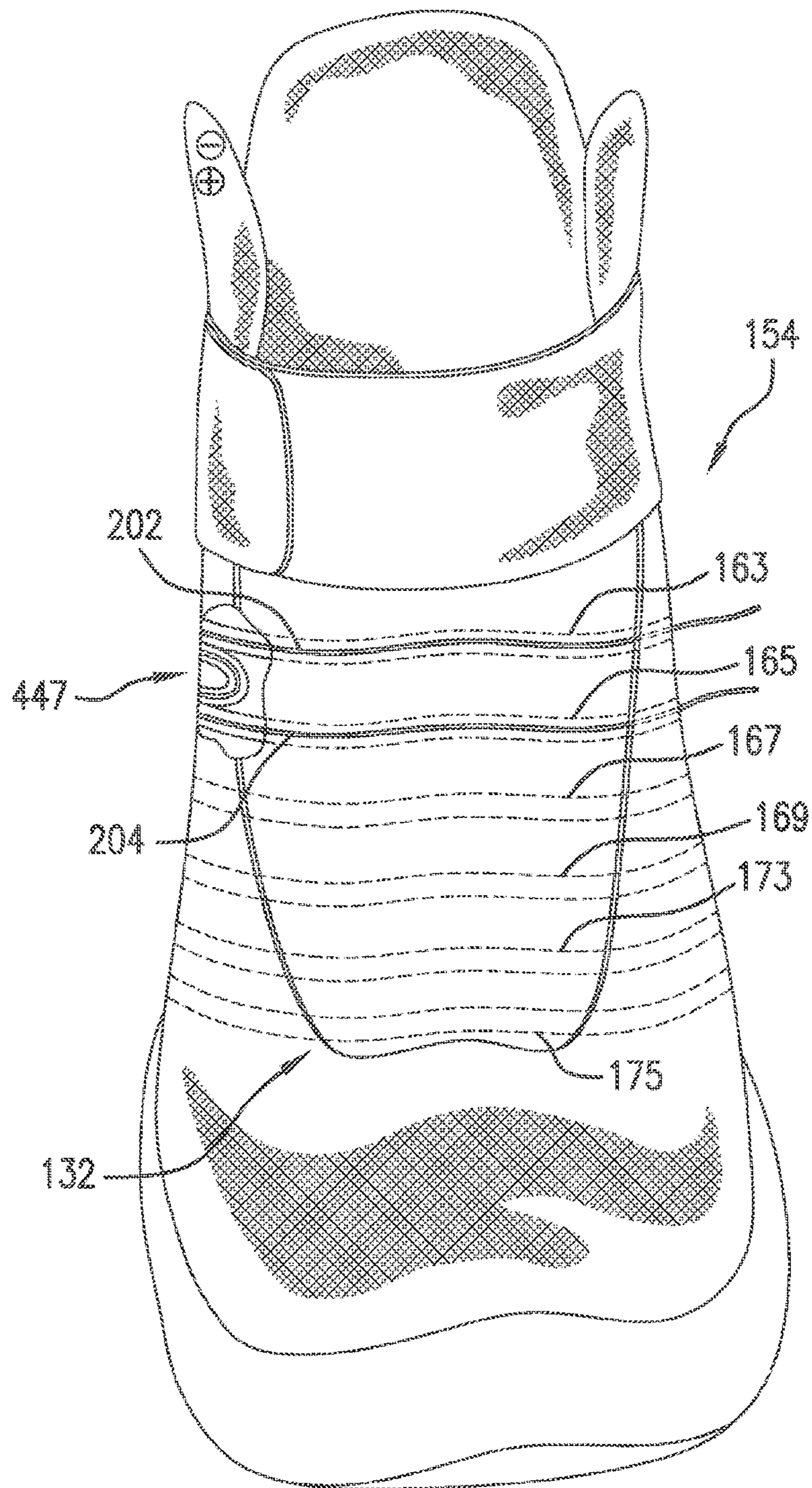


FIG. 12

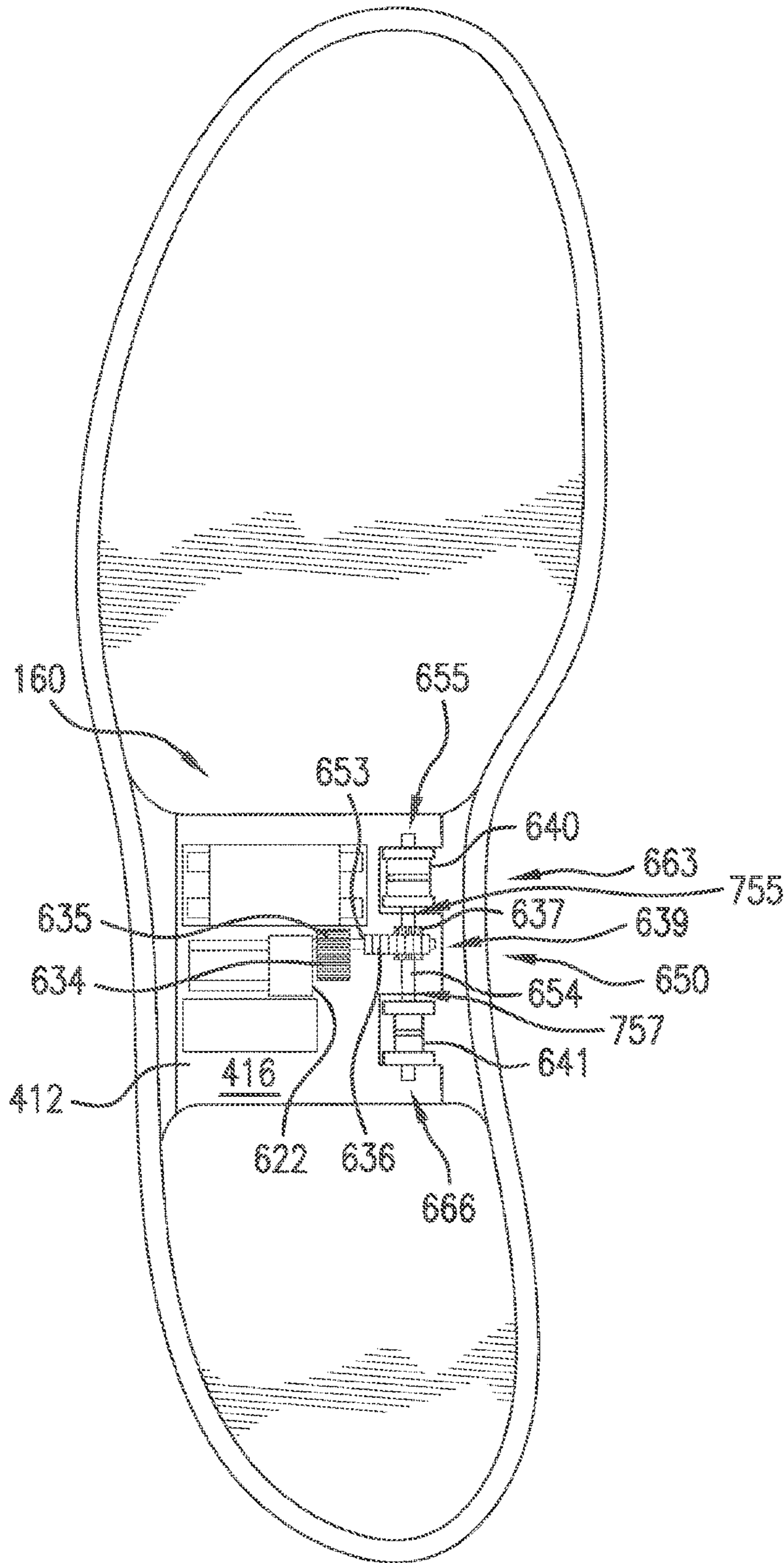


FIG. 13



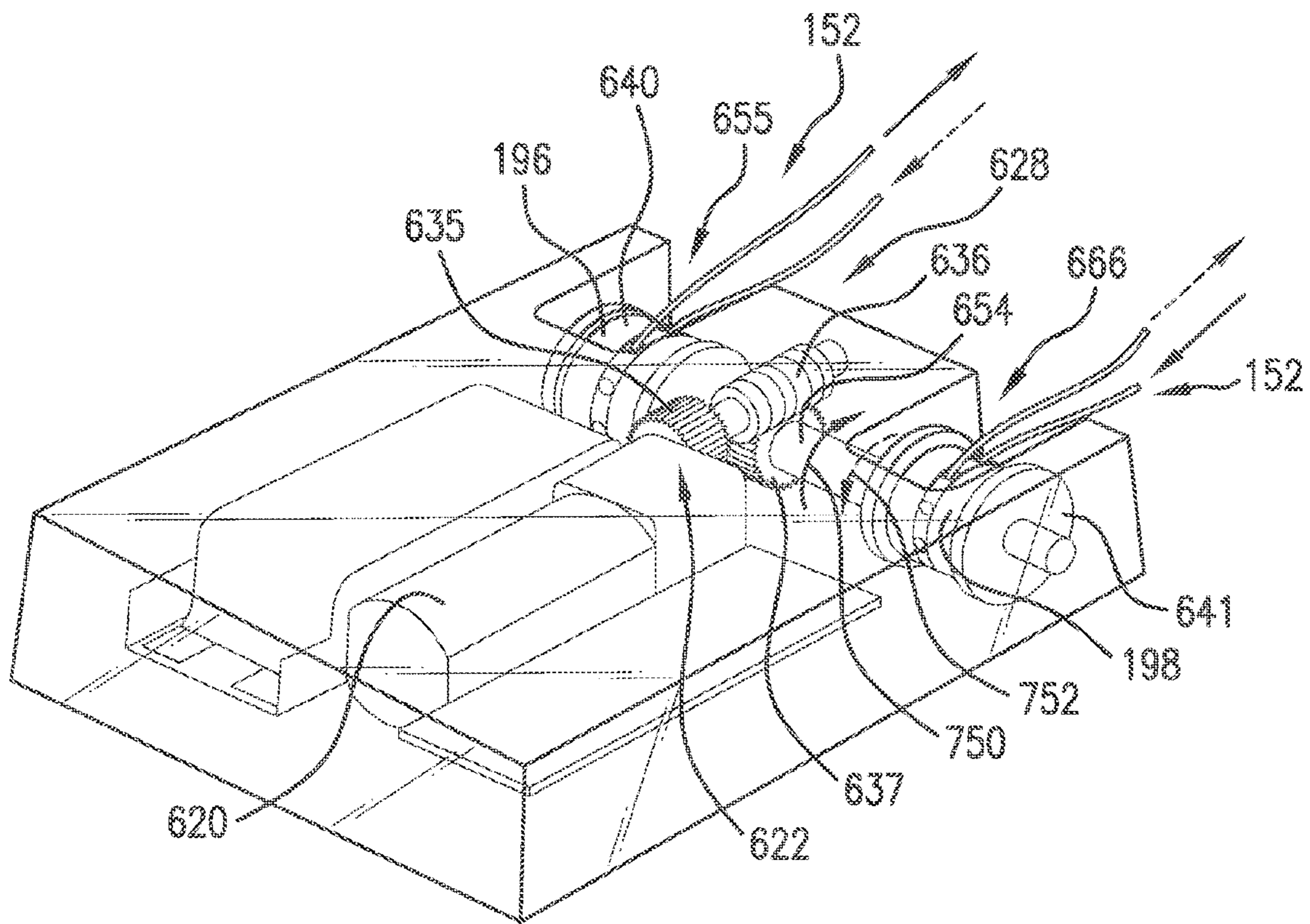


FIG. 14

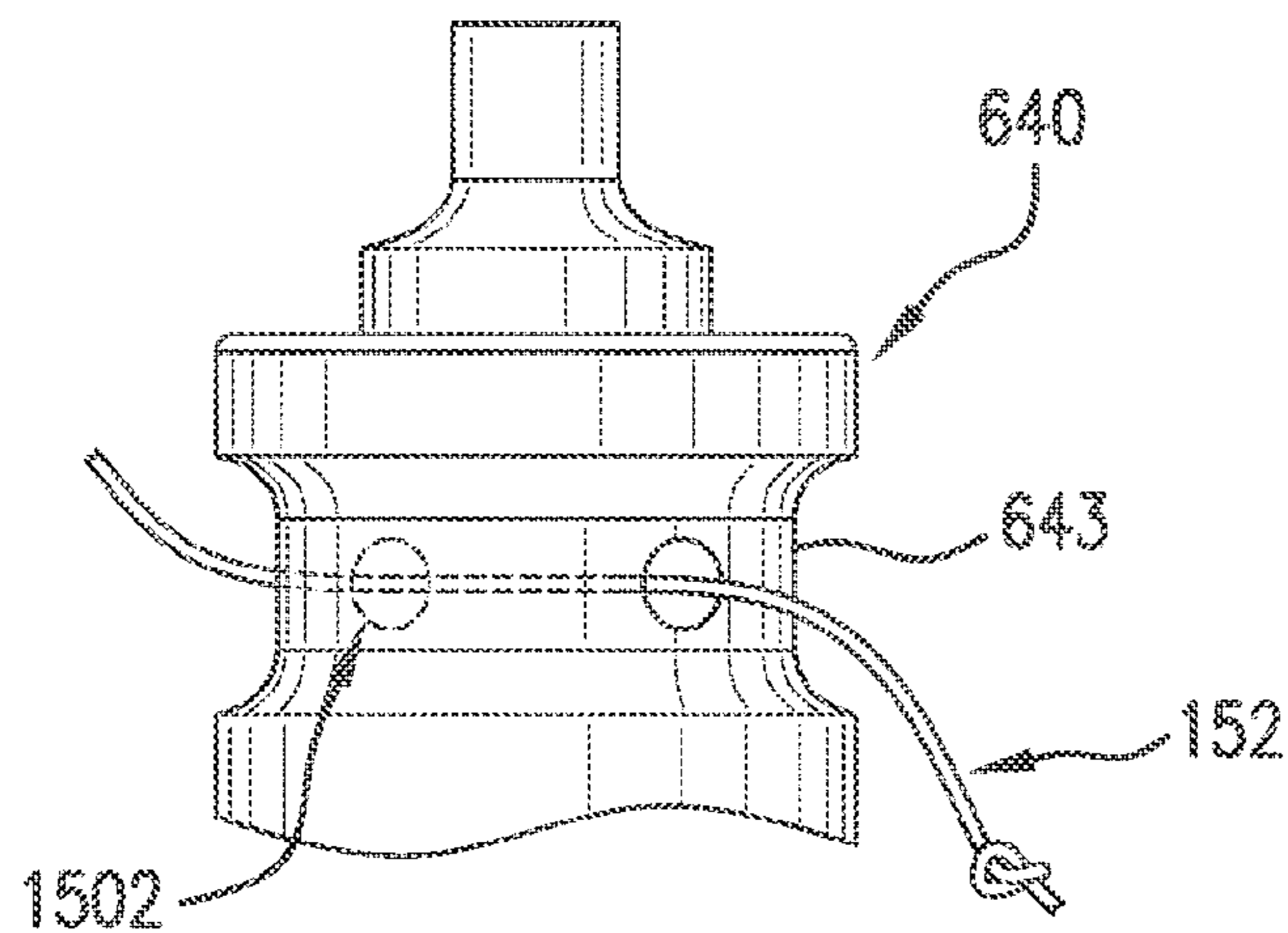


FIG. 15

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**ARTICLE OF FOOTWEAR COMPRISING  
MOTORIZED TENSIONING DEVICE WITH  
SPLIT SPOOL SYSTEM**

The present embodiments relate generally to articles of footwear and apparel including tensioning systems.

Articles of footwear generally include two primary elements: an upper and a sole structure. The upper is often formed from a plurality of material elements (e.g., textiles, polymer sheet layers, foam layers, leather, synthetic leather) that are stitched or adhesively bonded together to form a void on the interior of the footwear for comfortably and securely receiving a foot. More particularly, the upper forms a structure that extends over instep and toe areas of the foot, along medial and lateral sides of the foot, and around a heel area of the foot. The upper may also incorporate a lacing system to adjust the fit of the footwear, as well as permitting entry and removal of the foot from the void within the upper. Likewise, some articles of apparel may include various kinds of closure systems for adjusting the fit of the apparel.

SUMMARY

In one aspect, an article of footwear comprises an upper, a sole structure attached to the upper, the sole structure includes a midfoot region. The midfoot region includes a motorized tensioning device fixedly attached. The motorized tensioning device including a motor assembly coupled to a shaft member by a gear reduction system. The gear reduction system includes a first gear member intermeshed with a second gear member. The motor assembly actuates the gear reduction system when the motorized tensioning device is activated. The gear reduction system enables the first gear to transfer motion to the second gear in a first rotational direction when the motorized tensioning device is activated. Wherein the gear reduction system prevents the second gear from transferring motion to the first gear.

In another aspect, an article of footwear comprises an upper, a sole structure attached the upper, the sole structure includes a midfoot region. The midfoot region includes a motorized tensioning device fixedly attached. The motorized tensioning device includes a first reel member and a first lace member attached to the first reel member and the motorized tensioning device includes a second reel member and a second lace member attached to the second reel member. The first lace member and the second lace member are routed from the first reel member and the second reel member through sidewall portions disposed on a medial side and a lateral side of the upper such that portions of the first lace member and the second lace member are arranged in a parallel configuration on a tongue of the upper. The motorized tensioning device is activated by a pressure force applied on the sole structure. A first portion of the first lace member extends through a first region of the upper and wherein the first region of the upper is adjusted when the motorized tensioning device is activated. A second portion of the second lace member extends through a second region of the upper and wherein the second region of the upper is adjusted when the motorized tensioning device is activated. Wherein the first region is different from the second region.

In another aspect, an article of footwear comprises an upper, a sole structure attached the upper, the sole structure includes a midfoot region. The midfoot region includes a motorized tensioning device fixedly attached. The motorized tensioning device including a shaft member, a first lace member a second lace member. The first lace member includes a first tensioning portion and a second tensioning

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portion. The second lace member includes a third tensioning portion and a fourth tensioning portion. The first tensioning portion and the second tensioning portion are associated with a first amount of tension. The third tensioning portion and the fourth tensioning portion are associated with a second amount of tension. Wherein the first amount of tension is different than the second amount of tension.

Other systems, methods, features and advantages of the embodiments will be, or will become, apparent to one of ordinary skill in the art upon examination of the following figures and detailed description. It is intended that all such additional systems, methods, features and advantages be included within this description and this summary, be within the scope of the embodiments, and be protected by the following claims.

BRIEF DESCRIPTION OF THE DRAWINGS

The embodiments can be better understood with reference to the following drawings and description. The components in the figures are not necessarily to scale, emphasis instead being placed upon illustrating the principles of the invention. Moreover, in the figures, like reference numerals designate corresponding parts throughout the different views.

FIG. 1 is a schematic side view of an embodiment of an article of footwear with a tensioning system:

FIG. 2 is a schematic isometric view of an embodiment of an article of footwear with a tensioning system in a non-tensioned state;

FIG. 3 is a schematic isometric view of an embodiment of an article of footwear with a tensioning system in a tensioned state:

FIG. 4 is a schematic view of an embodiment of an article of footwear with a tensioning system;

FIG. 5 is a schematic enlarged view of isolated components of an embodiment of a motorized tensioning device on an article of footwear;

FIG. 6 is a schematic enlarged view of isolated components of an embodiment of a motorized tensioning device on an article of footwear

FIG. 7 is a schematic isometric view of an embodiment of a motorized tensioning device;

FIG. 8 is a schematic exploded view of an embodiment of a motorized tensioning device;

FIG. 9 is a schematic view of an embodiment of a routing of the laces on an article of footwear with a motorized tensioning device;

FIGS. 10-12 are schematic views of a lacing embodiment for motorized tensioning device;

FIG. 13 is schematic bottom view of an article of footwear with a motorized tensioning device;

FIG. 14 is a schematic isometric view of an embodiment of a motorized tensioning device; and

FIG. 15 is a schematic isometric view of an embodiment of a reel member.

DETAILED DESCRIPTION

FIG. 1 illustrates a schematic side view of an embodiment of article of footwear **100** that is configured with a tensioning system **150**. In the current embodiment, article of footwear **100**, also referred to hereafter simply as article **100**, is shown in the form of an athletic shoe. However, in other embodiments, tensioning system **150** may be used with any other kind of footwear including, but not limited to: hiking boots, soccer shoes, football shoes, sneakers, running

shoes, cross-training shoes, rugby shoes, basketball shoes, baseball shoes as well as other kinds of shoes. Moreover, in some embodiments article **100** may be configured for use with various kinds of non-sports related footwear, including, but not limited to: slippers, sandals, high heeled footwear, loafers as well as any other kinds of footwear. As discussed in further detail below, a tensioning system may not be limited to footwear and in other embodiments a tensioning system could be used with various kinds of apparel, including clothing, sportswear, sporting equipment and other kinds of apparel. In still other embodiments, a tensioning system may be used with braces, such as medical braces.

Referring to FIG. **1**, for purposes of reference, article **100** may be divided into forefoot region **101**, midfoot region **103** and heel region **105**. Forefoot region **101** may be generally associated with the toes and joints connecting the metatarsals with the phalanges. Midfoot region **103** may be generally associated with the arch of a foot. Likewise, heel region **105** may be generally associated with the heel of a foot, including the calcaneus bone. It will be understood that forefoot region **101**, midfoot region **103** and heel region **105** are only intended for purposes of description and are not intended to demarcate precise regions of article **100**.

For consistency and convenience directional adjectives are also employed throughout this detailed description corresponding to the illustrated embodiments. The term “lateral” or “lateral direction” as used throughout this detailed description and in the claims refers to a direction extending along a width of a component or element. For example, a lateral axis **191** of article may extend between a medial side **141** and a lateral side **143** of the foot. Additionally, the term “longitudinal” or “longitudinal direction” as used throughout this detailed description and in the claims refers to a direction extending across a length or breadth of an element or component (such as a sole member). In some embodiments, a longitudinal axis **181** may extend from forefoot region **101** to heel region **105** of a foot. It will be understood that each of these directional adjectives may also be applied to individual components of an article of footwear, such as an upper and/or a sole member. In addition, a vertical axis **171** refers to the axis perpendicular to a horizontal surface defined by longitudinal axis **181** and lateral axis **191**. It will be understood that each of these directional adjectives may be applied to various components shown in the embodiments, including article **100**, as well as components of tensioning system **150**.

Article **100** may include upper **102** and sole structure **104**. Generally, upper **102** may be any type of upper. In particular, upper **102** may have any design, shape, size and/or color. For example, in embodiments where article **100** is a basketball shoe, upper **102** could be a high top upper that is shaped to provide high support on an ankle. In embodiments where article **100** is a running shoe, upper **102** could be a low top upper.

In some embodiments, sole structure **104** may be configured to provide traction for article **100**. In addition to providing traction, sole structure **104** may attenuate ground reaction forces when compressed between the foot and the ground during walking, running or other ambulatory activities. The configuration of sole structure **104** may vary significantly in different embodiments to include a variety of conventional or non-conventional structures. In some cases, the configuration of sole structure **104** can be configured according to one or more types of ground surfaces on which sole structure **104** may be used. Examples of ground surfaces include, but are not limited to: natural turf, synthetic turf, dirt, as well as other surfaces.

In different embodiments, sole structure **104** may include different components. For example, sole structure **104** may include an outsole, a midsole, and/or an insole. In addition, in some cases, sole structure **104** can include one or more cleat members or traction elements that are configured to increase traction with a ground surface.

In some embodiments, sole structure **104** may be joined with upper **102**. In some cases, upper **102** is configured to wrap around a foot and secure sole structure **104** to the foot. In some cases, upper **102** may include opening **130** that provides access to an interior cavity **135** of article **100**.

Some embodiments may include provisions for facilitating the adjustment of an article to a wearer’s foot. In some embodiments, these provisions may include a tensioning system. In some embodiments, tensioning system may further include other components to include, but are not limited to, a motorized tensioning device, a housing unit, tensioning members; a motor, gears, spools or reels. Such components may assist in securing and providing a custom fit to a wearer’s foot. These components and how, in various embodiments, they may secure the article to a wearer’s foot and provide a custom fit will be explained further in detail below.

In different embodiments, a tensioning system may include a tensioning member. The term “tensioning member” as used throughout this detailed description and in the claims refers to any component that has a generally elongated shape and high tensile strength. In some cases, a tensioning member could also have a generally low elasticity. Examples of different tensioning members include, but are not limited to: laces, cables, straps and cords. In some cases, tensioning members may be used to fasten and/or tighten an article, including articles of clothing and/or footwear. In other cases, tensioning members may be used to apply tension at a predetermined location for purposes of actuating some components or system.

A tensioning system may include provisions for providing a customizable and comfortable fit of an article to a wearer’s foot. In some embodiments, the provisions may comprise of various components and systems for modifying the dimensions of interior cavity **135** and thereby tightening (or loosening) upper **102** around a wearer’s foot. In some embodiments, tensioning system **150** may comprise tensioning member or lace **152** as well as a motorized tensioning device **160**.

In some embodiments, lace **152** may be configured to pass through various different lacing guides **154** (as shown in phantom lines in FIGS. **10-12**), which may be further associated with the edges of throat opening **132**. In some cases, lacing guides **154** may provide a similar function to traditional eyelets on uppers. In particular, as lace **152** is pulled or tensioned, throat opening **132** may generally constrict so that upper **102** is tightened around a foot. In one embodiment, lacing guides **154** may comprise a first lacing guide **163**, a second lacing guide **165**, a third lacing guide **167**, a fourth lacing guide **169**, a fifth lacing guide **173**, and a sixth lacing guide **175** (as shown in FIGS. **10-12**).

In some embodiments, lacing guides **154** may be used to arrange lace in different configurations. Further, lacing guides **154** may be used to facilitate the tightening or loosening of lace **152** while in various states of tension. For example, in some embodiments, lacing guides **154** may expand as lace **152** is configured in a tensioned or tightened state. With this arrangement, lace **152** is provided more room when tensioning article. Likewise, in some embodiments, lacing guides **154** could compress as lace **152** is configured from a tensioned state to a non-tensioned or loose

state. In some embodiments, lace **152**, positioned through lacing guides **154**, may be arranged in various configurations. Referring to FIGS. **1**, **10-12**, in one embodiment, lace **152** is arranged in parallel configuration on upper. In some other embodiments, lace **152** may be arranged, in a criss-cross pattern. In some other embodiments, lace **152**, via lacing guides **154** may be arranged in a different configuration.

The arrangement of lacing guides **154** in this embodiment is only intended to be exemplary and it will be understood that other embodiments are not limited to a particular configuration for lacing guides **154**. Furthermore, the particular types of lacing guides **154** illustrated in the embodiments are also exemplary and other embodiments may incorporate any other kinds of lacing guides or similar lacing provisions. In some other embodiments, for example, lace **152** could be inserted through traditional eyelets. Some examples of lace guiding provisions that may be incorporated into the embodiments are disclosed in Cotterman et al., U.S. Patent Application Publication Number 2011/0000091, now U.S. application Ser. No. 13/174,527, filed Jun. 30, 2011, and titled "Lace Guide", which is hereby incorporated by reference in its entirety. Additional examples are disclosed in Goodman et al., U.S. Patent Application Publication Number 2011/0266384, now U.S. application Ser. No. 13/098,276, filed Apr. 29, 2011 and titled "Reel Based Lacing System" (the "Reel Based Lacing Application"), which is hereby incorporated by reference in its entirety. Still additional examples of lace guides are disclosed in Kerns et al., U.S. Patent Application Publication Number 2011/0225843, now U.S. application Ser. No. 13/011,707, filed Jan. 21, 2011 and titled "Guides For Lacing Systems", which is hereby incorporated by reference in its entirety.

Lace **152** may comprise any type of type of lacing material known in the art. Examples of lace that may be used include cables or fibers having a low modulus of elasticity as well as a high tensile strength. A lace may comprise a single strand of material, or can comprise multiple strands of material. An exemplary material for the lace is SPEC-TRA™, manufactured by Honeywell of Morris Township N.J., although other kinds of extended chain, high modulus polyethylene fiber materials can also be used as a lace. Still further exemplary properties of a lace can be found in the Reel Based Lacing Application mentioned above.

Article **100** may include a plurality of control buttons **182** that are capable of initiating control commands. In some embodiments, control buttons **182** may allow a user to tighten one or both shoes simultaneously. Optionally, some embodiments could include a "fully tighten" command that would tighten the footwear until a predetermined threshold is achieved (for example, a threshold pressure, winding distance, etc.). Article **100** may also include provisions for storing and using preferred tension settings. In some embodiments, control buttons **182** may be disposed somewhere along upper **102**. In one embodiment, control buttons **182** may be disposed adjacent to opening **130**, as shown in FIGS. **1-3**. The operation of control buttons **182** to tighten, or loosen, tensioning system will be explained further in detail below.

FIG. **2** shows article **100** is in a fully opened or non-tensioned state just prior to the entry of foot **200**. In this state, lace **152** may be loose enough to allow a user to insert his or her foot into opening **130**. As seen in FIG. **2**, in some embodiments, with tensioning system **150** in the open state, a foot can be easily and comfortably removed from footwear **100**.

Generally, tensioning system **150** may include any number of laces. In some embodiments, only a single lace may be provided. In other embodiments, multiple laces may be provided. In this embodiment, lace **152** may refer collectively to first lace **155**, second lace **157**, and third lace **159** that are routed through portions of article **100**. Further, the routing of lace **152** may dispose portions of first lace **155**, second lace **157**, and third lace **159** on a tongue section **134** of upper **102**. In one embodiment, these portions on tongue section **134** may include first tensioning portion **202**, second tensioning portion **204**, third tensioning portion **206**, fourth tensioning portion **208**, fifth tensioning portion **210**, and sixth tensioning portion **212**. For clarity, first tensioning portion **202**, second tensioning portion **204**, third tensioning portion **206**, fourth tensioning portion **208**, fifth tensioning portion **210**, and sixth tensioning portion **212** may be referred to collectively as tensioning set **215**.

Some embodiments may include provisions that provide a custom fit of an article to a wearer's foot. As used in this detailed description and in the claims, custom fit may refer to adjusting specific, localized portions or regions of an upper as opposed to the entire upper, to comfortably fit the shape and contours of the article to a wearer's foot. In some embodiments, provisions include motorized tensioning device **160** (as shown in FIG. **4**) comprised of components that may adjust portions of upper **102**. In some embodiments, provisions may further include control mechanisms such as control buttons **182** allowing an incremental tightening or loosening of lace **152** and in particular, tensioning set **215**.

Referring to FIGS. **2-4**, tensioning system **150** may tighten lace **152** thereby adjusting upper **102** in a variety of ways. In some embodiments, prior to activation, lace **152** may be characterized as being in a state of non-tension **190**, as shown in FIG. **2**. In some embodiments, a pressure force, such as when a wearer inserts a foot and presses down on sole structure **104**, may activate motorized tensioning device **160**. The pressure force may result in motorized tensioning device **160** actuating components to draw lace **152** into housing unit **412**. Alternatively in some embodiments, an incremental tighten command may be sent to motorized tensioning device **160** by pressing control buttons **182**. This command causes motorized tensioning device **160** to enter an incremental tighten mode. At this point, the tension of lace **152** is increased to tighten upper **102** around foot **200**. In particular, as lace **152** is drawn into housing unit **412**, tensioning set **215** may constrict throat opening **132**. Further, increased tension of lace **152** will adjust different regions of the upper **102** due to the routing of lace **152**. In some embodiments, during this event lace **152** may be characterized as being in a state of tension **191**.

In some embodiments, when motorized tensioning device **160** is activated, portions of lace **152**, in particular tensioning set **215**, may adjust localized regions of upper **102**. As used in this detailed description and in the claims, localized regions may refer to a particular zone, portion, or area of upper. In some embodiments, localized regions may extend along a lateral axis **191** between medial side **141** and lateral side **143**. In some cases, localized region may be spaced apart from opening **135**. In some other cases localized regions may be spaced along a longitudinal axis **181** extending between forefoot region **101** and midfoot region **103**.

In some embodiments, by adjusting localized regions of upper **102**, tensioning set **215** may apply different amounts of downward and inward pressure to the upper **102** as well. In one embodiment, first lace **155** may include first tensioning portion **202** and second tensioning portion **204** which

adjusts a first region **230** of upper **102** during operation. First tensioning portion **202** and second tensioning portion may be associated with a first amount of tension that applies a downward and inward pressure to the upper **102**. Further, second lace **157** may include third tensioning portion **206** and fourth tensioning portion **208** which adjusts a second region **232**, which is spaced apart and different from first region **230**, of upper **102** during operation. Likewise, third tensioning portion **206** and fourth tensioning portion **208** may be associated with a second amount of tension, which is different to first amount of tension. The second amount of tension will also apply downward and inward pressure to the upper **102**.

In some cases, this incremental tightening can occur in discrete steps so that each time the wearer interacts with control buttons **182**, lace **152** is taken up by a predetermined amount (for example by rotating a spool or a reel member within motorized tensioning device **160** through a predetermined angle). In other cases, this incremental tightening can occur in a continuous manner. In some cases, the speed of tightening can be set so that the system does not overshoot a preferred level of tightness (i.e., the system does not move between not tight enough and overly tight too quickly) while also being large enough to avoid overly long times for fully tightening article **100**.

FIG. **4** schematically illustrates an exemplary placement of motorized tensioning device **160** when attached to footwear **100**. In some embodiments, some components of motorized tensioning device **160** may be disposed in a housing unit **412**.

In some embodiments, lace **152** may be routed from motorized tensioning device **160** throughout upper **102** such that lace **152** passes through internal channels **411** positioned along sidewall portions **170** (as seen in FIGS. **1-4**). In some embodiments, internal channels **411** are disposed on sidewall portions **170** on medial side **141** and lateral side **143** of upper **102**. Internal channels **411** may guide the lace **152** away from and back towards motorized tensioning device **160**. The routing of lace **152** from motorized tensioning device **160** through upper **102** and back towards motorized tensioning device **160** will be explained further in detail below.

It is to be noted that the routing of lace **152** from motorized tensioning device **160** through regions of upper **102** may provide distinct advantages. In some embodiments, because of the arrangement in which lace **152** is routed, a majority of a length of lace **152** may be disposed outside of housing unit **142**. Thus, more room may be provided in housing unit **412** to accommodate other components such as gears, motors, or batteries. Further, because housing unit **412** needs less space for lace **152**, housing unit **412** may be reduced in size.

In some embodiments, motorized tensioning device **160** may be mounted along a region of sole structure **104**. In one embodiment, motorized tensioning device **160** can be mounted on a lower surface **420** (the surface that is facing away from a foot when article **100** is worn by a user) of sole structure **104**. In some embodiments, motorized tensioning device **160** can be mounted along midfoot region **103** of sole structure **104**. In one embodiment, an external cavity **450** located on lower surface **420** of sole structure **104** may be configured to receive motorized tensioning device **160**. In some other embodiments, motorized tensioning device **160** may be mounted on lower surface **420** in other ways known in the art.

In some cases, motorized tensioning device **160** may include provisions for receiving portions of lace **152**. In

some cases, lace **152** may exit internal channels **411** of upper **102** and pass through apertures **156** before entering housing unit **412** of motorized tensioning device **160** as seen in FIG. **5**.

Provisions for mounting motorized tensioning device **160** to sole structure **104** can vary in different embodiments. In some cases, motorized tensioning device **160** may be removably attached, so that motorized tensioning device **160** can be easily removed by a user and modified (for example, when a lace must be changed). In other cases, motorized lacing device **160** could be fixedly attached to sole structure **104** permanently. In one embodiment, for example, an external harness (not shown) may be used to mount motorized tensioning device **160** to sole structure **104** at midfoot region **103**. In other embodiments, motorized lacing device **160** can be joined in any manner to lower surface **420**, including mechanical attachments, adhesives, and/or molding.

As previously stated, motorized tensioning device **160** may be configured to automatically apply tension to lace **152** for purposes of tightening and loosening upper **102**. As described in further detail below, motorized tensioning device **160** may include provisions for winding lace **152** onto, and unwinding lace **152** from, reel elements internal to motorized tensioning device **160**. Moreover, the provisions may include a motor assembly that actuates components for facilitating the winding and unwinding of lace **152** onto reel elements in response to various inputs or controls.

Throughout the detailed description and in the claims, various operating modes, or configurations, of a tensioning system are described. These operating modes may refer to states of the tensioning system itself, as well as to the operating modes of individual subsystems and/or components of the tensioning system. Exemplary modes include an “incremental tighten mode”, an “incremental loosen mode” and a “fully loosen” mode. The latter two modes may also be referred to as an “incremental release mode” and a “full release mode”. In the incremental tighten mode, motorized tightening device **160** may operate in a manner that incrementally (or gradually) tightens, or increases the tension of, lace **152**. In the incremental loosen mode, motorized tightening device **160** may operate in a manner that incrementally (or gradually) loosens, or releases tension in, lace **152**. As discussed further below, the incremental tighten mode and the incremental loosen mode may tighten and loosen a lace in discrete steps or continuously. In the full release mode, motorized tightening device **160** may operate in a manner so that tension applied to the lace by the system is substantially reduced to a level where the user can easily remove his or her foot from the article. This is in contrast to the incremental release mode, where the system operates to achieve a lower tension for the lace relative to the current tension, but not necessarily to completely remove tension from the laces. Moreover, while the full release mode may be utilized to quickly release lace tension so the user can remove the article, the incremental release mode may be utilized to make minor adjustments to the lace tension as a user searches for the desired amount of tension, thereby providing user with a custom fit. Although the embodiments describe three possible modes of operation (and associated control commands), other operating modes may also be possible. For example, some embodiments could incorporate a fully tighten operating mode where motorized tightening device **160** continues to tighten lace **152** until a predetermined tension has been achieved.

FIGS. **7**, **8** and **13** illustrate exemplary components of motorized tensioning device **160**. For purposes of illustra-

tion, some components of motorized tensioning device **160** have been omitted or depicted in isolation from other components.

Referring to FIG. 7, some components of motorized tightening device **160** are shown within a portion of housing unit **412**. In some embodiments, housing unit **412** may be shaped so as to optimize the arrangement of components of motorized tensioning device **160**. For example, the arrangement of components may allow housing unit **412** to have a tapered thickness, relative to a vertical axis, of housing unit **412**.

In some embodiments, housing unit **412** may have a tapered vertical profile, as shown in FIG. 7. In other words, housing unit **412** may have a first end **680** with a first height **684**, relative to vertical axis **171** and an opposite second end **682** with a second height **686**, where first height **684** is greater than second height **686**. It is to be noted that in some embodiments, first end **680** and second end **682** may be positioned along a longitudinal axis **181**. In other embodiments, first end **680** and second end **682** may be positioned along a lateral axis **191**.

Housing unit **412** may further include an inner housing portion **416** and an outer housing portion **418**. Outer housing portion **418** may include a base panel **410** as well as an outer cover **414**, and generally provides a protective outer covering for components of motorized tensioning device **160**. Inner housing portion **416** may be shaped and include apertures **490** and cavities **492** to support components of motorized tensioning device **160** (as shown in FIG. 8). In some cases portions of inner housing portion **416** function to limit the mobility of some components, as discussed in detail below.

In some embodiments, motorized tensioning device **160** may include a motor assembly **620**. In some embodiments, motor assembly **620** could include an electric motor. However, in other embodiments, motor assembly **620** could comprise any kind of non-electric motor known in the art. Examples of different motors that can be used include, but are not limited to: DC motors (such as permanent-magnet motors, brushed DC motors, brushless DC motors, switched reluctance motors, etc.). AC motors (such as motors with sliding rotors, synchronous electrical motors, asynchronous electrical motors, induction motors, etc.), universal motors, stepper motors, piezoelectric motors, as well as any other kinds of motors known in the art. Motor assembly **620** may further include a motor crankshaft **622** that can be used to drive one or more components of motorized tensioning device **160**. Provisions for powering motor assembly **620**, including various kinds of batteries, are discussed in detail below.

In some embodiments, motorized tensioning device **160** can include provisions for reducing the output speed of and increasing the torque generated by, motor assembly **620**. In some embodiments, motorized tensioning device **160** can include one or more gear reduction assemblies and/or gear reduction systems. In some embodiments, motorized tensioning device **160** may include a single gear reduction assembly. In other embodiments, motorized tensioning device **160** may include two or more gear reduction assemblies. Referring to the exploded view of FIG. 8, in one embodiment, motorized tensioning device **160** includes first gear reduction assembly **630** and second gear reduction assembly **632**, which may be collectively referred to as gear reduction system **628**. First gear reduction assembly **630** may be a gear reduction assembly that is generally aligned with motor assembly **620** and/or crankshaft **622** (also shown in FIG. 13). In contrast, second gear reduction assembly **632**

may provide additional gear reduction that extends in a generally perpendicular direction to the orientation of crankshaft **622**. In one embodiment, gear reduction system **628** may be mechanically coupled with motor assembly **620**. With respect to housing unit **412**, in some embodiments, first gear reduction assembly **630** may extend along lateral axis **191** of housing unit **412** while second gear reduction assembly **632** may extend along a longitudinal axis **181** of housing unit **412**. By using a combination of in-line gears and horizontally spaced gears, relative to the orientation of crankshaft **622**, motor assembly **620** can be arranged in parallel with spools and a corresponding reel shaft (as discussed in further detail below). This arrangement may reduce the longitudinal space required to fit all the components of motorized tensioning device **160** within housing unit **412**.

Each gear reduction assembly can comprise one or more gears. In some embodiments, first gear reduction assembly **630** comprises one or more gears. In some embodiments, first gear reduction assembly **630** may be driven by crankshaft **622**, and include a first gear **634**, a second gear **635**, and a third gear **636**.

In one embodiment, second gear reduction assembly **632** may be configured with an additional stage of gear, including a fourth gear **637**. In this embodiment, fourth gear **637** acts in conjunction with third gear **636**, for turning additional components of motorized tensioning device **160**, as described in further detail below. In some embodiments, third gear **636** may comprise a worm and fourth gear **637** may comprise a worm wheel. In one embodiment, the operation and/or coupling of third gear **636** and fourth gear **637** may be referred to as a worm gear or worm drive **639** (also shown in FIG. 13), which will be discussed further below.

The current embodiment of second gear reduction assembly **632** includes one gear. However, other embodiments could use any other number of gears. Likewise, the number of gears comprising first gear reduction assembly **630** may vary in different embodiments. Additionally, in different embodiments, the type of gears used in first gear reduction assembly **630** and/or second gear reduction assembly **632** could vary. In some cases, spur gears may be used. Other examples of gears that may be used include, but are not limited to: helical gears, external gears, internal gears, bevel gears, crown gears, worm gears, non-circular gears, rack and pinion gears, epicyclic gears, planetary gears, harmonic drive gears, cage gears, magnetic gears as well as any other kinds of gears and/or any combinations of various kinds of gears. The number, type and arrangement of gears for gear reduction system **628** may be selected to achieve the desired tradeoff between size, torque and speed of the motorized tensioning device **160**.

In some embodiments, motorized tensioning device **160** can include provisions for winding and unwinding portions of a lace. As stated previously, in some embodiments, motorized tensioning device **160** can include one or more spools or reel members. In some cases, motorized tensioning device **160** may include a first reel member **640** and a second reel member **641**. First reel member **640** and second reel member **641** may be referred to collectively as reel members **663**.

Some embodiments allow for different combinations of securing lace **152** onto several reel members **663**. In some embodiments, first lace **155** may have a first end secured to first reel member **640**, and a second end secured to second reel member **641**. In embodiments where there are multiple laces, any combination may be used for securing lace **152** or

multiple lace members onto reel members 663. Referring to FIGS. 6 and 8, in one embodiment, first lace 155, second lace 157, and third lace 159 may have one end secured to first reel member 640. Likewise, first lace 155, second lace 157, and third lace 159 may have the opposite end secured to second reel member 641. In some other embodiments, first lace 155 may have both ends attached to first reel member 640, while second lace 157 may have its respective ends attached to second reel member 641 (as shown schematically in FIG. 9). In still some other embodiment, first lace 155 and second lace 157 may be attached to both first reel member 640 and second reel member 641, whereas third lace 159 may have its end attached to second reel member 641. With this arrangement, the pull-in rate 195 or the speed of winding lace 152 around reel members 663 may be varied. These variations may allow for customizing tension of lace 152 in relation to upper 102 and providing a custom fit.

In some embodiments, reel members 663 may be so dimensioned to further provide a custom fit to the wearer. In some embodiments, the diameter of reel members 663 may be varied to accommodate pull-in rate 195 of lace 152. For example, as shown in FIGS. 7 and 8, first reel member 640 may have a first diameter 196 larger than second diameter 198 of second reel member 641. The varying diameters, when combined with gear reduction system 628, allow for accommodating the different pull-in rates of lace 152 as they are pulled into housing unit 412.

In some embodiments, during operation, the routing of first lace 155, second lace 157, and third lace 159 from housing unit 412 may also vary the tension of lace 152 and tensioning set 215. By varying the tension, the amount of downward and inward pressure placed on localized regions or zones of upper 102 can be balanced and varied on the wearer's foot.

In an exemplary embodiment, first lace 155, with one end secured to first reel member 640, may exit housing unit 412 (as shown generally in FIGS. 4, 5 and 9). First lace 155 may then extend upwards along a first medial internal channel 430 on a side portion of upper 102, continue through lacing guides 154 positioned on tongue section 134 as first tensioning portion 202 (as seen in FIGS. 2 and 12), and then down through a first lateral internal channel 440 on opposite lateral side 143 of upper (as shown generally in FIG. 1). First lace 155 may then pass through a first loop channel 447 which routes first lace 155 back to housing unit 412 (as shown in FIGS. 6 and 12). Therefore, first lace 155 may be configured to pass upward through second lateral internal channel 442 (as shown in FIG. 1), adjacent first lateral internal channel 440, then extend through lacing guides 154 as second tensioning portion 204 (as shown in FIGS. 2 and 12). Referring to FIG. 4, first lace 155 will then continue down through second medial internal channel 432 adjacent first medial internal channel 430, and back into housing unit 412 with second end secured to second reel member 641. Likewise, second lace 157, and third lace 159 may be routed in a similar fashion. As discussed earlier, in some other embodiments, third lace 159, for example, may have both ends secured to second reel member 641.

In another embodiment, as first lace 155 is routed back to housing unit 412 from lateral side 143, first lace 155 may be configured to pass through non-adjacent internal channels 411. For example, in some embodiments, as first lace 155 is routed back to housing unit 412 from lateral side 143, first lace 155 may be configured to pass through third lateral internal channel 444 which is not adjacent to first lateral internal channel 440 (as shown in FIG. 1). It is to note that

first loop channel 447 may be configured to route first lace 155 from first lateral channel 440 to third lateral channel 444. Continuing, first lace 155 may continue through lacing guides 154, as third tensioning portion 206, and then routed through third medial internal channel 434 before the second end enters housing unit 412 and is secured to second reel member 641. In other embodiments, lace 152 may be routed through different internal channels 411 and positioned in lacing guides 154 as different portions of tensioning set 215. With this arrangement, different tensions may be applied to lace 152 and tensioning set 215 in order to vary the amount of pressure on different regions of upper 102 during operation.

In some embodiments, when combined with lacing guides 154 arranged in parallel configuration, the amount of tension of first tensioning portion 202 proximal to opening 130, may be less than the amount of tension of sixth tensioning portion 212 proximal to forefoot region 101. In some embodiments, second tensioning portion 204, third tensioning portion 206, fourth tensioning portion 208, and fifth tensioning portion 210 may also have varying degrees of tension. The decreased tension of first tensioning portion 202 near the top of the article reduces an amount of pressure placed on the top of a wearer's foot which in turn reduces friction between the wearer's foot and article 100. With this arrangement, a custom fit is provided, with varying pressure throughout upper 102. Notably and in contrast to a single lace routed through an upper, independently controlling several lace members that loop around different regions of upper will balance the pressure or load at those different regions. Further, this balancing of pressure occurs simultaneously during the operation of motorized tensioning device 160.

Referring to FIG. 8, in some embodiments, first reel member 640 may further comprise a first receiving portion 642 for receiving a lace, and second reel member 641 may comprise a second receiving portion 644 for receiving a lace. Moreover, in some cases, first receiving portion 642 may comprise a first lace winding region 646 and a second lace winding region 648, which in some cases can be used to separately wind two ends of a lace. In addition, second receiving portion 644 may comprise a third lace winding region 647 and a fourth lace winding region 649. Since torque output goes down as lace 152 builds up in diameter, using separate winding regions for each lace end may help decrease the diameter of wound lace on reel members 663 and thereby minimize torque output reduction. In some cases, first lace winding region 646 and second lace winding region 648 may be separated by a dividing portion 643, which may include a lace receiving channel 645 for permanently retaining a portion of the lace on first reel member 640 (as shown in FIG. 15). Lace 152 may be secured to reel members 663 by any method known in the art. In some cases, reel apertures 1502, may be used for inserting lace 152 and the tying ends into a knot. In other cases, different methods may be used.

In other cases, however, first receiving portion 642 may comprise a single lace winding region. Similarly, third lace winding region 647 and fourth lace winding region 649 may be separated by a dividing portion, which may include a lace receiving channel for permanently retaining a portion of the lace on second reel member 641. In other cases, however, second receiving portion 644 may comprise a single lace winding region.

Motorized lacing system 160 may include provisions for transferring torque between a first gear reduction assembly 630 and second gear reduction assembly 632. Furthermore, in some embodiments, motorized lacing system 160 may



include provisions for transferring torque from second gear reduction assembly **632** (or more generally from gear reduction system **628**) to first reel member **640** and/or second reel member **641** in a manner that allows for incremental tightening, incremental loosening and full loosening of a lace. In one embodiment, motorized lacing system **160** may be configured with a torque transmitting system as the primary means for the transmission of torque from worm drive **639** to first reel member **640** and/or second reel member **641** in order to wind (or unwind) lace **152**.

Referring to FIGS. **7** and **13**, torque transmitting system **650** may further comprise various assemblies and components. In some embodiments, torque transmitting system **650** may include a first shaft and a second shaft and a rotation control assembly. In one embodiment, the first shaft is a worm shaft **653**, and the second shaft is a reel shaft **654**, and the rotation control assembly is in the form of worm drive **639**. More specifically, these components operate in a manner that allows for incremental tightening (spool winding), incremental loosening (spool unwinding) as well as full tension release (during which time substantially no torque is transferred from fourth gear **637** to first reel member **640** and second reel member **641**).

Some embodiments can also include a fixed bearing, which may be associated with an end of reel shaft **654**. In some embodiments, an end portion of reel shaft **654** may be received within a recess of inner housing portion **416**. In some embodiments, both ends of reel shaft **654** may be received within inner housing portion **416**. For example, as shown in FIG. **7**, a first end portion **655** may be disposed in a first recess **667**, and second end portion **666** may be disposed in a second recess **668**.

In some cases, different advantages result from the positioning of reel members **663** at different locations within torque transmitting system **650**. Referring to FIG. **14**, in one embodiment, first reel member **640** and second reel member **641** may be positioned and concentrically mounted at opposite ends of reel shaft **654**. In other words, first reel member **641** may be concentrically mounted at first end portion **655** of reel shaft **654**, and second reel member **642** may be concentrically mounted at second end portion **666**.

In some other embodiments positioning reel members **663** at opposite ends of reel shaft **654** may provide gear reduction system **628** more robust capabilities to withstand increased amounts of tension and pressure force exerted on sole structure **104**. In some cases, positioning reel members **663** this way may further vary the amount of tension for lace **152** throughout upper **102** during operation.

As seen in FIG. **13**, first end portion **655** of reel shaft **654** may be attached to housing unit **412**. Further, a first shaft distance **755** may be disposed between torque transmitting system **650** and inner housing portion **416** of housing unit **412**. As first shaft distance **755** is relatively short, securing first end portion **655** of reel shaft **654** into housing unit **412** provides motorized tensioning device **160** with greater structural capabilities. Likewise, second shaft distance **757** may be associated with second end portion **666**. In contrast to embodiments where a reel shaft has a relatively long shaft distance between a torque transmitting system and a housing unit, the shorter length of first shaft distance **755** provides motorized tension device **160** with increased structural integrity. This increased structural integrity allows for smaller components to be placed and used in housing unit **412**. Further, in some embodiments, the shorter length of first shaft distance **755** and second shaft distance **757**, relative to torque transmitting system **650**, enables greater torque to be applied during operation.

In some embodiments, motorized tensioning device **160** may include provisions for adjusting the operation of motor assembly **620** according to one or more feedback signals. In some embodiments, for example, motorized tensioning device **160** may include a limit switch assembly. Generally, a limit switch assembly may detect current across portions of the system and vary the operation of motor assembly **620** according to the detected current.

For purposes of reference, the following detailed description uses the terms “first rotational direction” and “second rotational direction” in describing the rotational directions of one or more components about an axis. For purposes of convenience, the first rotational direction and the second rotational direction refer to rotational directions about a longitudinal axis **181** of reel shaft **654** and are generally opposite rotational directions. The first rotational direction may refer to the clockwise rotation of a component about longitudinal axis **181**, when viewing the component from the vantage point of second end portion **666** of reel shaft **654**. The second rotational direction may be then be characterized by the counterclockwise rotation of a component about longitudinal axis **181**, when viewing the component from the same vantage point.

A brief overview of the operation of motorized tensioning device **160** is described here. Referring to FIGS. **7**, **13** and **14**, in the incremental tighten mode motor assembly **620** may begin operating in order to rotate crankshaft **622**. Crankshaft **622** may turn an input gear (here, first gear **634**) of first gear reduction assembly **630**, such that the output gear (here, second gear **635**) of first gear reduction assembly **630** drives third gear **636**. Thus, second gear **635** and third gear **636** both rotate, which drives fourth gear **637** in first rotational direction **750**. As fourth gear **637** rotates, fourth gear **637** may engage and drive torque transmitting system **650** such that first reel member **640** and second reel member **641** may begin to rotate in first rotational direction **750**. This may cause lace **152** to wind onto first receiving portion **642** of first reel member **640** and second receiving portion **644** of second reel member **641**.

Furthermore, in the incremental loosen mode, motor assembly **620** may operate to rotate crankshaft **622**. In the loosening mode, motor assembly **620** and crankshaft **622** turn in an opposite direction of the direction associated with tightening. The gear reduction system **628** is then driven such that fourth gear **637** of second gear reduction assembly **632** rotates in second rotational direction **752**. In contrast to the incremental tighten mode, in the incremental loosen mode fourth gear **637** does not directly drive portions of torque transmitting system **650** first reel member **640** and second reel member **641**. Instead, the motion of fourth gear **637** in the second rotational direction **752** causes the torque transmitting system **650** to momentarily release first reel member **640** and second reel member **641**, allowing first reel member **640** and second reel member **641** to unwind by a predetermined amount after which the torque transmitting system reengages first reel member **640** and second reel member **641** and prevents further unwinding. This sequence of releasing and catching first reel member **640** and second reel member **641** occurs over and over as long as fourth gear **637** rotates in second rotational direction **752**.

Finally, in the open or fully loosen mode, the torque transmitting system operates so that substantially no torque is transmitted to first reel member **640** and second reel member **641** from any components of the torque transmitting system **650**. During this mode, first reel member **640**

and second reel member 641 may rotate more easily in the unwinding direction or second rotational direction 752 about reel shaft 654.

In different embodiments, referring to third gear 636 and fourth gear 637, torque may be transmitted between worm shaft 654 and reel shaft 654. Third gear 636 may include an internally threaded cavity that may engage a threading on worm shaft 653. Fourth gear 637 may include an internally threaded cavity that may engage a threading on reel shaft 654. It is to be understood that characterizing third gear 636 and/or fourth gear 637 as part of one assembly does not preclude it from being associated with a different assembly.

As previously stated, motorized tensioning device 160 may be activated by a pressure force on sole structure or control buttons. Upon activation, motor assembly 620 may actuate gear reduction system 628. Which in turn will result in worm shaft 653 and affixed third gear 636 to rotate with respect to lateral axis 191. Rotating third gear 636, which is intermeshed with fourth gear 637, referred to collectively as worm drive 639, will then drive fourth gear 637 which in turn rotates reel shaft 654. As first reel member 640 and second reel member 642 are concentrically mounted to the reel shaft 654, the rotation of reel shaft 654 rotates first reel member 640 and second reel member 641 to wind lace 152 upon reel members 663 in response. The winding of lace 152 onto reel member 663 may be associated with a pull-in rate 195 of lace 152 as described above. In one embodiment, during operation, first reel member 640 with lace 152 may have a first pull-in rate 295 while second reel member 641 with lace 152 may have a second pull-in rate 296, different from first pull-in rate. Different pull-in rates may be affected by various factors to include, but not limited to the routing of lace 152 throughout article 100, different diameter sizes of reel members 663, and gear sizes of gear reduction system 628. As previously noted, a significant reduction of speed occurs due to the relative diameter sizes of third gear 636, fourth gear 637, and reel members 663. This reduction of speed allows for better control of the winding or unwinding of lace 152 in relation to motor speed of motor assembly 620.

During operation, worm drive 639 has the characteristic of a unidirectional or one-way transmission also referred to as self-locking mechanism. As used in this detailed description and in the claims, one-way transmission refers to the feature that rotation can only be transmitted from third gear 636 to fourth gear 637. Further, the rotation cannot be transmitted from fourth gear 637 to third gear 636, in other words, third gear 636 can only drive fourth gear 637 and not the reverse. With this arrangement, lace 152 cannot be easily loosened (unwind) and will remain at the desired amount of tension.

The worm drive 639 depicted herein is only intended to be exemplary of a one-way torque transmitting mechanism that may be used to transmit torque to a reel member. Other embodiments are not limited to worm-like mechanisms and could include other one-way mechanisms. Examples of other one-way mechanisms that could be used include, but are not limited to, roller bearings, sprag clutches, ratcheting wheel and pawl as well as other mechanisms.

Referring to FIGS. 7 and 8, in different embodiments, worm shaft 653 may comprise a first end region 673 and a second end region 675. In some embodiments, first end region 673 may include threading. In some cases, the threading may engage an internally threaded cavity of third gear 636, which may facilitate the relative axial movement of fourth gear 637 along reel shaft 654. Worm shaft 653 may also include a second end region 675 that can be associated

with second gear 635 in some embodiments. In some embodiments, an intermediate region 626 of worm shaft 653 may be disposed between first end region 673 and second end region 675. In one embodiment, intermediate region 626 may extend between second gear 635 and third gear 636.

Thus, various portions of worm shaft 653 and reel shaft 654 can be configured to receive components of a torque transmitting system 650. Furthermore, reel shaft 654 can be configured to receive first reel member 640 and second reel member 641 at first end portion 655 of reel shaft 654 such that reel members 663 are coaxial with reel shaft 654. In some embodiments, second end portion 666 of reel shaft 654 may be associated with rotation control assembly or worm drive 639. In some other embodiments, reel shaft 654 can be configured to receive first reel member 640 and second reel member 641 at opposite ends of reel shaft 654 such that reel members 663 are coaxial with reel shaft 654. In some embodiments, center portion 677 of reel shaft 654 may be associated with rotation control assembly or worm drive 639.

In other embodiments, alternate methods could be used for coupling a shaft and reel members. Examples include other kinds of physical interlocking features or including friction increasing features. As one example, axial compliant friction coupling could be achieved using a wave washer or Belleville washer.

In different embodiments, the location of a motorized tensioning device 160 can vary from one embodiment to another. The illustrated embodiments show a motorized tensioning device disposed on the sole structure along midfoot region 103. However, other embodiments may incorporate a motorized tensioning device in any other location of an article of footwear, including forefoot region 101 and midfoot region 103 of the sole structure. In still other embodiments, a motorized tensioning device could be disposed in or along an upper of an article. The location of a motorized tensioning device may be selected according to various factors including, but not limited to: size constraints, manufacturing constraints, aesthetic preferences, optimal lacing placement, ease of removability as well as possibly other factors.

Some embodiments may include provisions for incorporating a motorized tensioning device into removable components of an article. In one embodiment, a motorized tensioning device may be incorporated into an external sole structure casing or wrapping which may function as a harness for mounting a motorized tensioning device to an article. An example of a heel counter configured for use with a lace tensioning device is disclosed in Gerber, U.S. Pat. No. 10,004,295, now U.S. patent application Ser. No. 13/481,132, filed May 25, 2012 and titled "Article of Footwear with Protective Member for a Control Device", the entirety of which is hereby incorporated by reference.

Embodiments may include a battery and/or control unit configured to power and control motorized tensioning device 160. FIGS. 7 and 8 illustrate a schematic view of an embodiment of a battery 691, battery assembly 720, and a control unit 693. In the embodiments shown, motorized tensioning device 160, battery 691, battery assembly 720, and control unit 693 are all disposed in housing unit 412, which may function to receive and protect these components. In other embodiments, however, any of these components could be disposed in any other portions of an article, including the upper and/or sole structure.

Battery 691 is only intended as a schematic representative of one or more types of battery technologies that could be used to power motorized tightening device 160. One possi-

bly battery technology that could be used is a lithium polymer battery. The battery (or batteries) could be rechargeable or replaceable units packaged as flat, cylindrical, or coin shaped. In addition, batteries could be single cell or cells in series or parallel.

Rechargeable batteries could be recharged in place or removed from an article for recharging. In some embodiments, charging circuitry could be built in and on board. In other embodiments, charging circuitry could be located in a remote charger. In another embodiment, inductive charging could be used for charging one or more batteries. For example, a charging antenna could be disposed in a sole structure of an article and the article could then be placed on a charging mat to recharge the batteries.

Additional provisions could be incorporated to maximize battery power and/or otherwise improve use. For example, it is also contemplated that batteries could be used in combination with super caps to handle peak current requirements. In other embodiments, energy harvesting techniques could be incorporated which utilize the weight of the runner and each step to generate power for charging a battery.

Control unit **693** is only intended as a schematic representation of one or more control technologies that could be used with motor tensioning device **160**. For example, there are various approaches to motor control that may be employed to allow speed and direction control. For some embodiments, a microcontroller unit may be used. The microcontroller may use internal interrupt generated timing pulses to create pulse-width modulation (PWM) output. This PWM output is fed to an H-bridge which allows high current PWM pulses to drive the motor both clockwise and counterclockwise with speed control. However, any other methods of motor control known in the art could also be used.

A tensioning system as described above is not limited to articles of footwear and could be used with apparel, for example. As one particular example, a tensioning system could be used for adjusting a shoulder pad, worn by a user playing American football, where shoulder pads are common. However, other embodiments could use this adjustable shoulder pad configuration with any other kinds of clothing configured to be worn by players in any other sports, including, for example, hockey, lacrosse, as well as any other sports or activities requiring shoulder pads. Moreover, it should be understood that the principles discussed here can be used for adjusting any kinds of padding including, but not limited to: elbow pads, knee pads, shin pads, padding associated with the hands and arms, padding associated with the feet and legs, padding associated with the torso, padding associated with the head as well as any other kind of padding known in the art.

In still other embodiments, a tensioning system including a motorized tensioning device can be used with any other kinds of apparel and/or sports equipment including, but not limited to backpacks, hats, gloves, shirts pants, socks, scarves, jackets, as well as other articles. Other examples of articles include, but are not limited to: shin guards, knee pads, elbow pads, shoulder pads, as well as any other type of protective equipment. Additionally, in some embodiments, the flexible manufacturing system could be used with bags, duffel bags, purses, backpacks, luggage, various kinds of sportswear and/or sporting equipment.

While various embodiments have been described, the description is intended to be exemplary, rather than limiting and it will be apparent to those of ordinary skill in the art that many more embodiments and implementations are possible that are within the scope of the embodiments. Although many possible combinations of features are shown in the

accompanying figures and discussed in this detailed description, many other combinations of the disclosed features are possible. Any feature of any embodiment may be used in combination with or substituted for any other feature or element in any other embodiment unless specifically restricted. Therefore, it will be understood that any of the features shown and/or discussed in the present disclosure may be implemented together in any suitable combination. Accordingly, the embodiments are not to be restricted except in light of the attached claims and their equivalents. Also, various modifications and changes may be made within the scope of the attached claims.

For the avoidance of doubt, the disclosure extends to the subject-matter of the following numbered paragraphs, or "Paras".

Para 1. An article of footwear, comprising:

- an upper;
- a sole structure attached to the upper, the sole structure having a midfoot region;
- a motorized tensioning device fixedly attached to the midfoot region;
- the motorized tensioning device including a motor assembly coupled to a shaft member by a gear reduction system;
- wherein the gear reduction system includes a first gear member intermeshed with a second gear member;
- wherein the motor assembly actuates the gear reduction system when the motorized tensioning device is activated;
- wherein the gear reduction system enables the first gear to transfer motion to the second gear in a first rotational direction when the motorized tensioning device is activated;
- and
- wherein the gear reduction system prevents the second gear from transferring motion to the first gear.

Para 2. An article of footwear according to Para 1, wherein the first gear member and the second gear member comprise a worm drive.

Para 3. An article of footwear according to Para 1 or 2, wherein the shaft member has a first end portion, a center portion, and a second end portion, wherein the first reel member is concentrically mounted at the first end portion, wherein the second reel member is concentrically mounted at the second end portion, and wherein the first gear and the second gear are positioned at the center portion.

Para 4. An article of footwear according to Para 3, wherein the motorized tensioning device includes a first lace member secured to the first reel member, and a second lace member secured to the second reel member.

Para 5. An article of footwear according to Para 4, wherein the first lace member winds upon the first reel member, and the second lace member winds upon the second reel member when the shaft member is rotated by the motor assembly.

Para 6. An article of footwear according to Para 5, wherein the first reel member has a first diameter, and the second reel member has a second diameter; and

wherein the first diameter is different than the second diameter.

Para 7. An article of footwear according to any preceding Para, wherein the motorized tensioning device includes a housing unit, a battery and a control unit; and

wherein the motor assembly is disposed between the battery and the control unit within the housing unit along a longitudinal axis.

Para 8. An article of footwear, comprising:

- an upper;
- a sole structure attached to the upper, the sole structure having a midfoot region:

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a motorized tensioning device fixedly attached to the midfoot region;

the motorized tensioning device including a first reel member and a first lace member attached to the first reel member and the motorized tensioning device including a second reel member and a second lace member attached to the second reel member;

wherein the first lace member and the second lace member are routed from the first reel member and the second reel member through sidewall portions disposed on a medial side and a lateral side of the upper such that portions of the first lace member and the second lace member are arranged in a parallel configuration on a tongue of the upper;

wherein the motorized tensioning device is activated by a pressure force applied on the sole structure;

wherein a first portion of the first lace member extends through a first region of the upper and wherein the first region of the upper is adjusted when the motorized tensioning device is activated;

wherein a second portion of the second lace member extends through a second region of the upper and wherein the second region of the upper is adjusted when the motorized tensioning device is activated and

wherein the first region is different from the second region.

Para 9. An article of footwear according to Para 8, wherein the motorized tensioning device includes a gear reduction system, wherein the gear reduction system includes a first gear member intermeshed with a second gear member.

Para 10. An article of footwear according to Para 9, wherein the motorized tensioning device includes a shaft member, the shaft member has a first end portion, a center portion, and a second end portion, wherein the first reel member is concentrically mounted at the first end portion, wherein the second reel member is concentrically mounted at the second end portion, and wherein the first gear and the second gear are positioned at the center portion.

Para 11. An article of footwear according to Para 10, wherein the motorized tensioning device includes a housing unit, wherein the first end portion of the shaft member is attached to the housing unit.

Para 12. An article of footwear according to Para 8, wherein the first lace member is further routed through a first medial internal channel, a first lateral internal channel, a second lateral internal channel, and a second medial internal channel;

wherein the first medial internal channel and the second medial internal channel are adjacent to one another; and

wherein the first lateral internal channel and the second lateral internal channel are adjacent to one another.

Para 13. An article of footwear according to any of Paras 8 to 12, wherein the first lace member is further routed through a first medial internal channel, a first lateral internal channel, a third lateral internal channel, and a third medial internal channel:

wherein a second medial internal channel is disposed between the first medial internal channel and the third medial internal channel; and

wherein a second lateral internal channel is disposed between the first lateral internal channel and the third lateral internal channel.

Para 14. An article of footwear, comprising:

an upper;

a sole structure attached to the upper, the sole structure having a midfoot region;

a motorized tensioning device fixedly attached to the midfoot region;

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the motorized tensioning device including a first lace member and a second lace member;

wherein the first lace member includes a first tensioning portion and a second tensioning portion;

wherein the second lace member includes a third tensioning portion and a fourth tensioning portion;

wherein the first tensioning portion and the second tensioning portion are associated with a first amount of tension;

wherein the third tensioning portion and the fourth tensioning portion are associated with a second amount of tension; and

wherein the first amount of tension is different than the second amount of tension.

Para 15. An article of footwear according to Para 14, wherein the first gear member and the second gear member comprise a worm drive.

Para 16. An article of footwear according to Para 15, wherein the motorized tensioning device includes a shaft member, the shaft member has a first end portion, a center portion, and a second end portion, a first reel member is concentrically mounted at the first end portion, a second reel member is concentrically mounted at the second end portion, and wherein the first gear and the second gear are positioned at the center portion.

Para 17. An article of footwear according to Para 16, wherein the first lace member and the second lace member are routed from the first reel member and the second reel member through sidewall portions disposed on a medial side and a lateral side of the upper such that portions of the first lace member, and the second lace member are arranged in a parallel configuration on a tongue of the upper.

Para 18. An article of footwear according to Para 17, wherein the first lace member is further routed through a first medial internal channel, a first lateral internal channel, a second lateral internal channel, and a second medial internal channel:

wherein the first medial internal channel and the second medial internal channel are adjacent; and

wherein the first lateral internal channel and the second lateral internal channel are adjacent.

Para 19. An article of footwear according to Para 17, wherein the first lace member is further routed through a first medial internal channel, a first lateral internal channel, a third lateral internal channel, and a third medial internal channel;

wherein a second medial internal channel is disposed between the first medial internal channel and the third medial internal channel; and

wherein a second lateral internal channel is disposed between the first lateral internal channel and the third lateral internal channel.

Para 20. An article of footwear according to any of Paras 14 to 19, wherein the motorized tensioning device includes a motor assembly, housing unit, a battery and a control unit; and

wherein the motor assembly is disposed between the battery and the control unit within the housing unit.

What is claimed is:

1. An article of footwear, comprising:

an upper;

a sole structure attached to the upper, the sole structure having a midfoot region;

a motorized tensioning device fixedly attached to the midfoot region;

the motorized tensioning device including a first lace member and a second lace member;

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wherein the first lace member includes a first tensioning portion and a second tensioning portion;  
 wherein the second lace member includes a third tensioning portion and a fourth tensioning portion;  
 wherein the motorized tensioning device is configured to  
 cause the first tensioning portion and the second tensioning portion to have a first amount of tension;  
 wherein the third tensioning portion and the fourth tensioning portion are configured to have a second amount of tension different than the first amount of tension; and  
 wherein the motorized tensioning device includes a worm drive; and

wherein the motorized tensioning device includes a shaft member, the shaft member has a first end portion, a center portion, and a second end portion, a first reel member is concentrically mounted at the first end portion, a second reel member is concentrically mounted at the second end portion, and wherein the first gear and the second gear are positioned at the center portion.

2. The article of footwear according to claim 1, wherein the first lace member and the second lace member are routed from the first reel member and the second reel member through sidewall portions disposed on a medial side and a lateral side of the upper such that portions of the first lace member, and the second lace member are arranged in a parallel configuration on a tongue of the upper.

3. The article of footwear according to claim 2, wherein the first lace member is further routed through a first medial internal channel, a first lateral internal channel, a second lateral internal channel, and a second medial internal channel;

wherein the first medial internal channel and the second medial internal channel are adjacent; and

wherein the first lateral internal channel and the second lateral internal channel are adjacent.

4. The article of footwear according to claim 2, wherein the first lace member is further routed through a first medial internal channel, a first lateral internal channel, a third lateral internal channel, and a third medial internal channel;

wherein a second medial internal channel is disposed between the first medial internal channel and the third medial internal channel; and

wherein a second lateral internal channel is disposed between the;

lateral internal channel and the third lateral internal channel.

5. An article of footwear, comprising:  
 an upper;

a sole structure attached to the upper, the sole structure having a midfoot region;

a motorized tensioning device fixedly attached to the midfoot region;

the motorized tensioning device including a first lace member and a second lace member;

wherein the first lace member includes a first tensioning portion and a second tensioning portion;

wherein the second lace member includes a third tensioning portion and a fourth tensioning portion;

wherein the motorized tensioning device is configured to cause the first tensioning portion and the second tensioning portion to have a first amount of tension;

wherein the third tensioning portion and the fourth tensioning portion are configured to have a second amount of tension different than the first amount of tension; and

wherein the motorized tensioning device includes a motor assembly, housing unit, a battery and a control unit; and

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wherein the motor assembly is disposed between the battery and the control unit within the housing unit.

6. A method of making an article of footwear, comprising:  
 attaching a sole structure to an upper, the sole structure having a midfoot region;

fixedly attaching a motorized tensioning device to the midfoot region;

the motorized tensioning device including a first lace member and a second lace member; and

forming the motorized including with a worm drive;

wherein the first lace member includes a first tensioning portion and a second tensioning portion;

wherein the second lace member includes a third tensioning portion and a fourth tensioning portion;

wherein the motorized tensioning device is configured to cause the first tensioning portion and the second tensioning portion to have a first amount of tension;

wherein the third tensioning portion and the fourth tensioning portion are configured to have a second amount of tension different than the first amount of tension;

wherein forming the motorized tensioning device comprises: a shaft member, the shaft member has a first end portion, a center portion, and a second end portion, and further comprising

concentrically mounting a first reel member at a first end portion of a shaft member; and

concentrically mounting a second reel member at a second end portion of the shaft member, wherein the worm drive is positioned at a center portion of the shaft member between the first end and the second end.

7. The method according to claim 6, wherein fixedly attaching the motorized tensioning device further includes routing the first lace member and the second lace member from the first reel member and the second reel member through sidewall portions disposed on a medial side and a lateral side of the upper such that portions of the first lace member and the second lace member are arranged in a parallel configuration on a tongue of the upper.

8. The method according to claim 7, wherein fixedly attaching the motorized tensioning device further includes routing the first lace member through a first medial internal channel, a first lateral internal channel, a second lateral internal channel, and a second medial internal channel;

wherein the first medial internal channel and the second medial internal channel are adjacent; and

wherein the first lateral internal channel and the second lateral internal channel are adjacent.

9. The method according to claim 7, wherein fixedly attaching the motorized tensioning device further includes routing the first lace member through a first medial internal channel, a first lateral internal channel, a third lateral internal channel, and a third medial internal channel;

wherein a second medial internal channel is disposed between the first medial internal channel and the third medial internal channel; and

wherein a second lateral internal channel is disposed between the;

lateral internal channel and the third lateral internal channel.

10. A method of making an article of footwear, comprising:

attaching a sole structure to an upper, the sole structure having a midfoot region;

fixedly attaching a motorized tensioning device to the midfoot region;

the motorized tensioning device including a first lace member and a second lace member; and

wherein the first lace member includes a first tensioning portion and a second tensioning portion;  
wherein the second lace member includes a third tensioning portion and a fourth tensioning portion;  
wherein the motorized tensioning device is configured to 5  
cause the first tensioning portion and the second tensioning portion to have a first amount of tension;  
wherein the third tensioning portion and the fourth tensioning portion are configured to have a second amount of tension different than the first amount of tension; 10  
forming the motorized tensioning device with a motor assembly, housing unit, a battery and a control unit; and  
wherein fixedly attaching the motor assembly is between the battery and the control unit within the housing unit.

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