



US011179146B2

(12) **United States Patent**
Vogel et al.

(10) **Patent No.:** **US 11,179,146 B2**
(45) **Date of Patent:** **Nov. 23, 2021**

(54) **RETRACTOR**

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(*) Notice: Subject to any disclaimer, the term of this patent is extended or adjusted under 35 U.S.C. 154(b) by 73 days.

(21) Appl. No.: **16/456,526**

(22) Filed: **Jun. 28, 2019**

(65) **Prior Publication Data**
US 2019/0350573 A1 Nov. 21, 2019

Related U.S. Application Data

(63) Continuation of application No. 15/504,581, filed as application No. PCT/US2015/049211 on Sep. 9, 2015, now Pat. No. 10,426,450.
(Continued)

(51) **Int. Cl.**
A61B 17/02 (2006.01)
A61B 5/00 (2006.01)
A61N 1/05 (2006.01)

(52) **U.S. Cl.**
CPC **A61B 17/0206** (2013.01); **A61B 5/4893** (2013.01); **A61B 17/025** (2013.01); **A61N 1/0551** (2013.01); **A61B 2017/0262** (2013.01)

(58) **Field of Classification Search**
CPC **A61B 17/0206**; **A61B 17/025**
(Continued)

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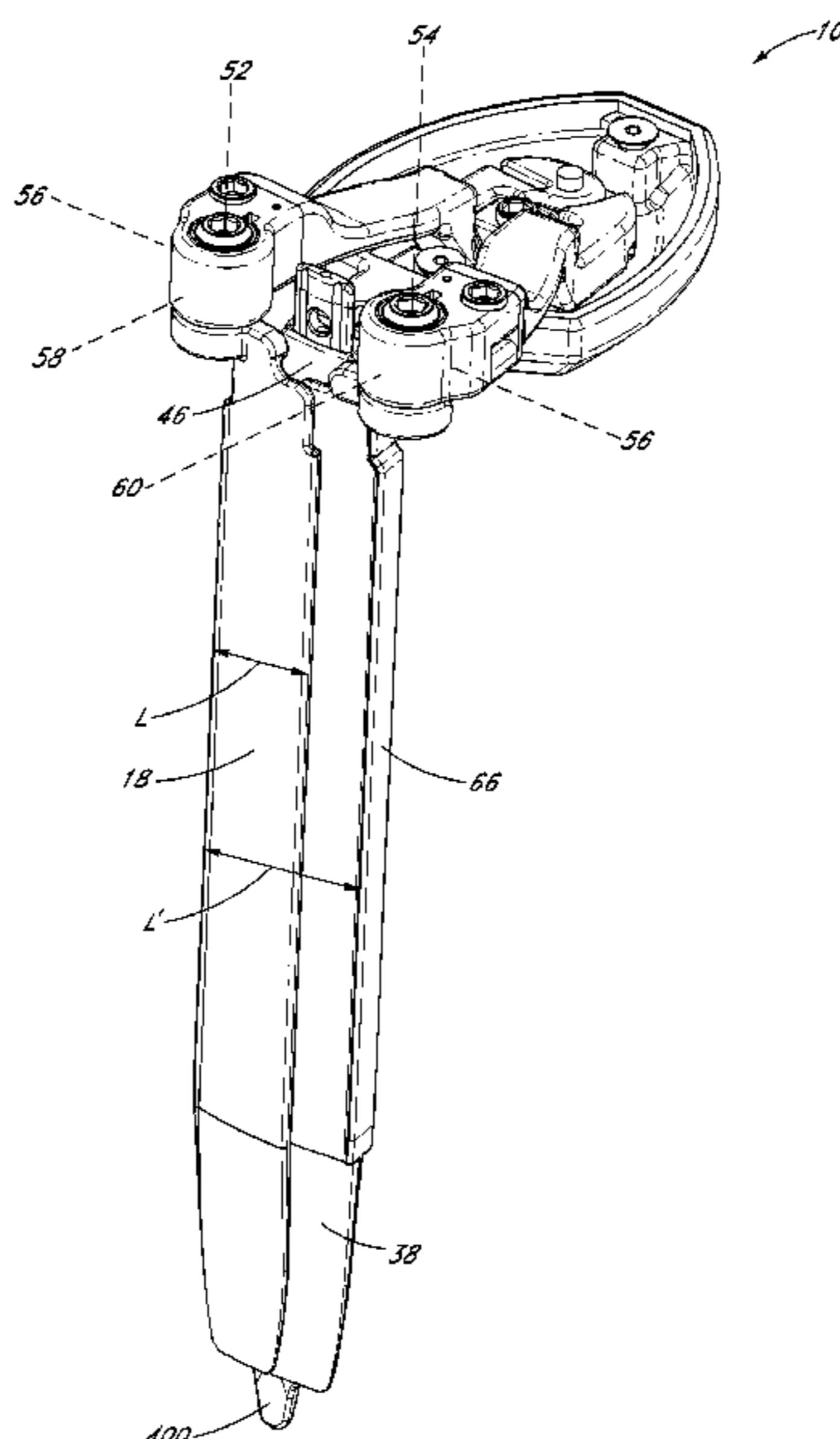
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(57) **ABSTRACT**

A retractor for use in surgical operations comprises a pair of blade assemblies. In operation, the blade assemblies are initially in a closed position to assume a low profile, inserted into a relatively small incision, and stretched apart from each other, thereby stretching the skin about the incision to form an aperture longer than the incision. The retractor is adapted to rotate a first blade about a first axis and a second blade about a second axis. The retractor is adapted to move the pair of blade assemblies apart along a third axis. The retractor is adapted to pivot the first blade about a fourth axis and the second blade about a fifth axis. In some embodiments, a method of performing an operation, e.g. a spinal operation, on a patient using the disclosed retractor is provided.

20 Claims, 19 Drawing Sheets



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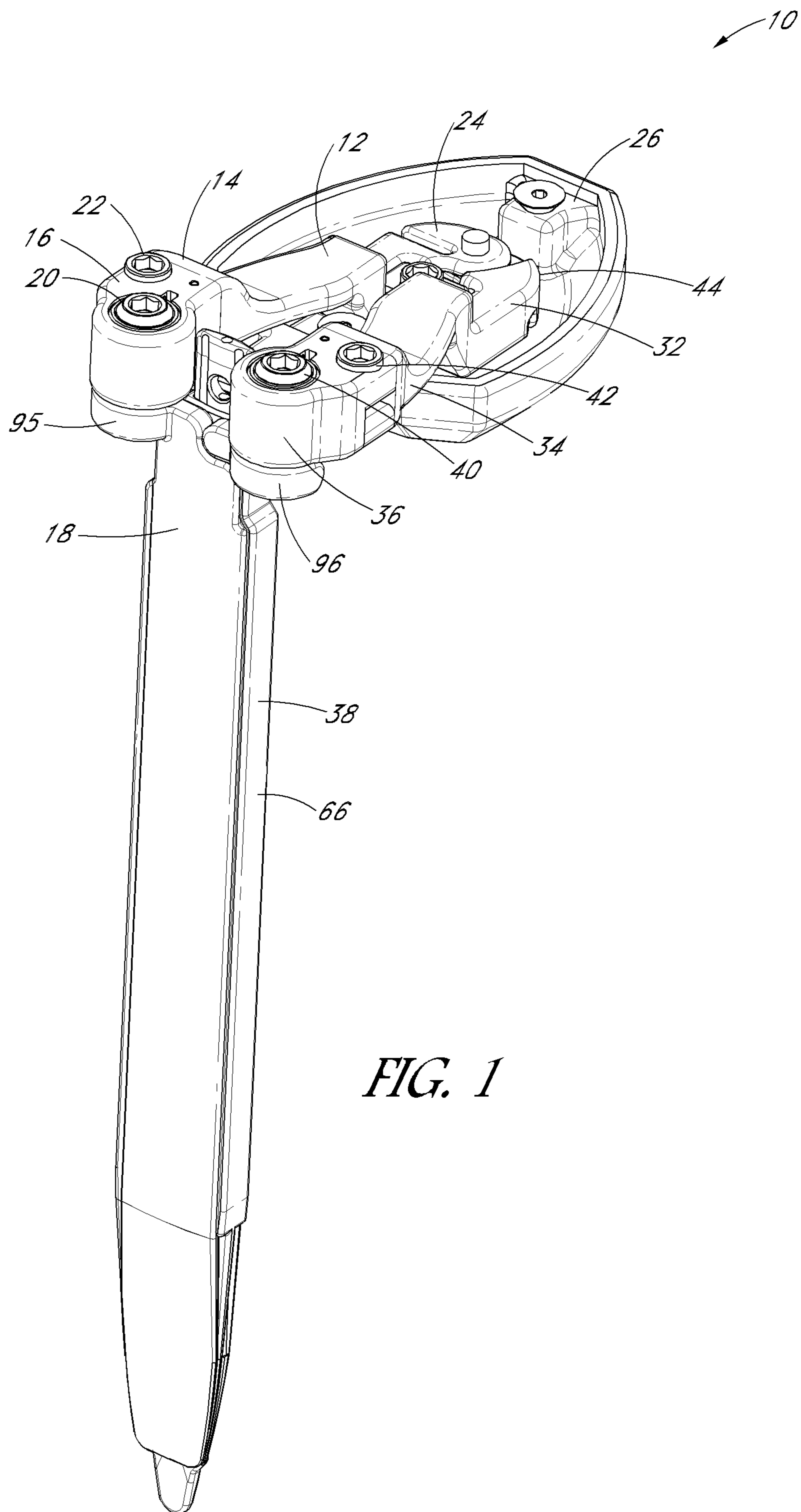


FIG. 1

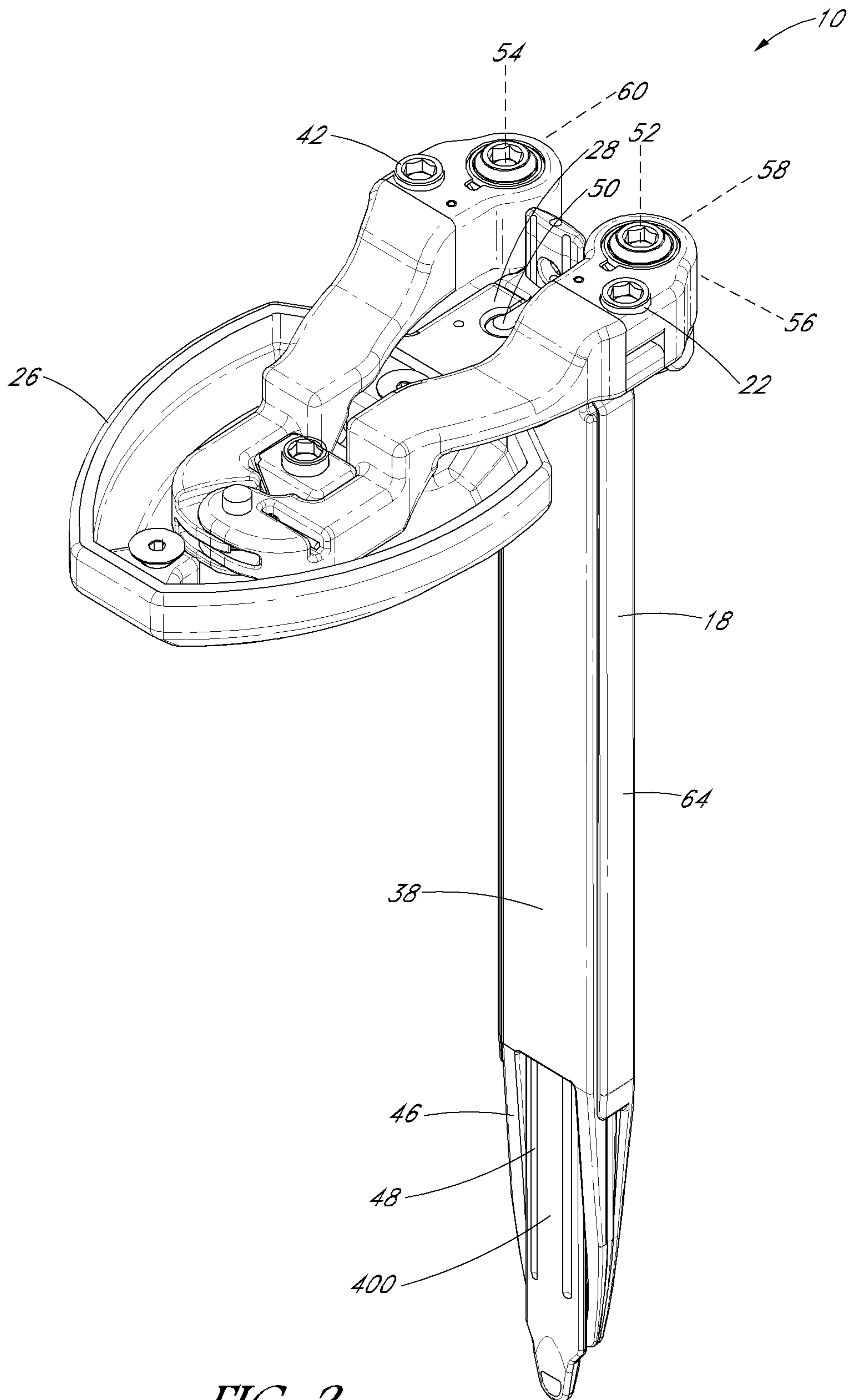


FIG. 2

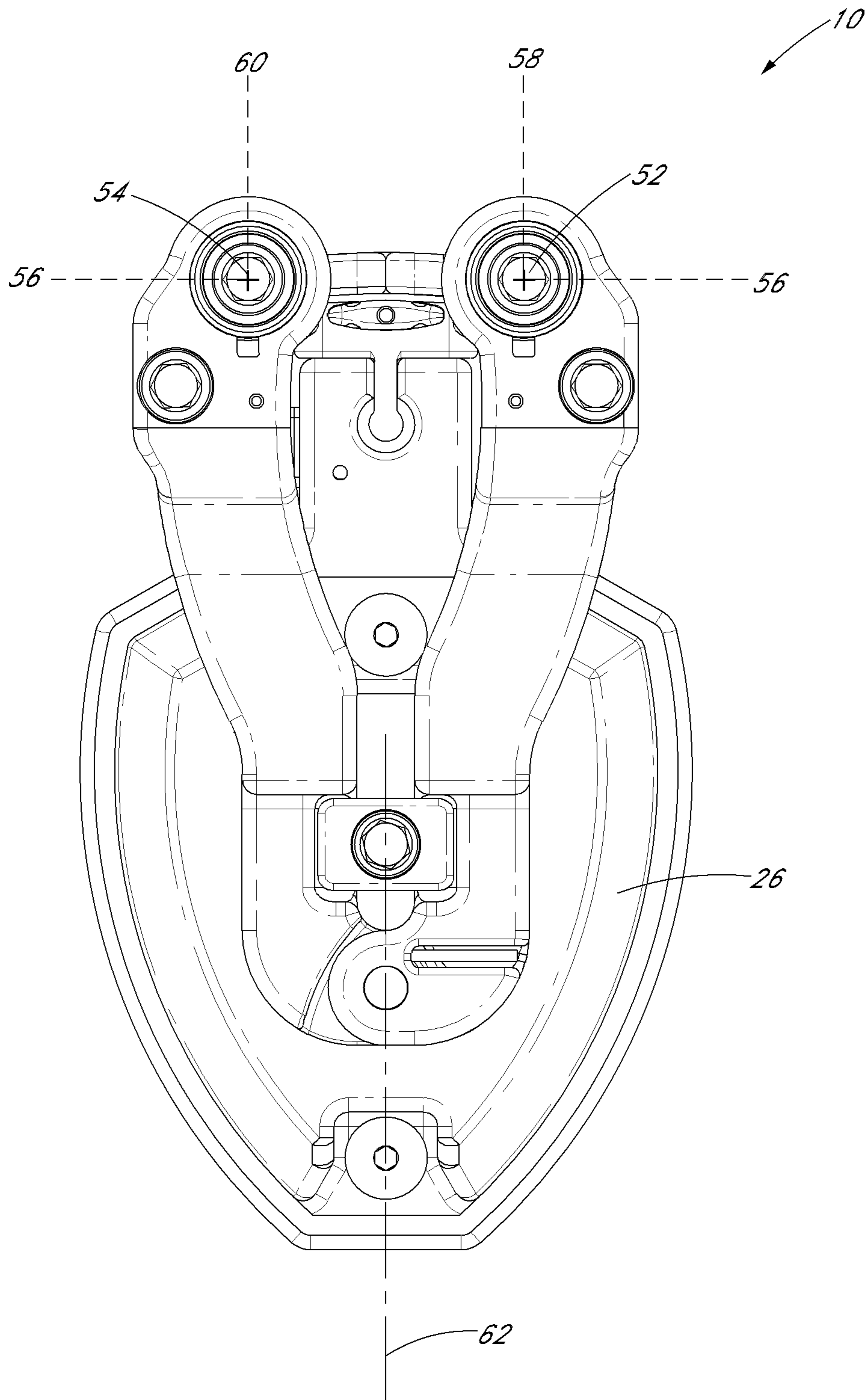


FIG. 3

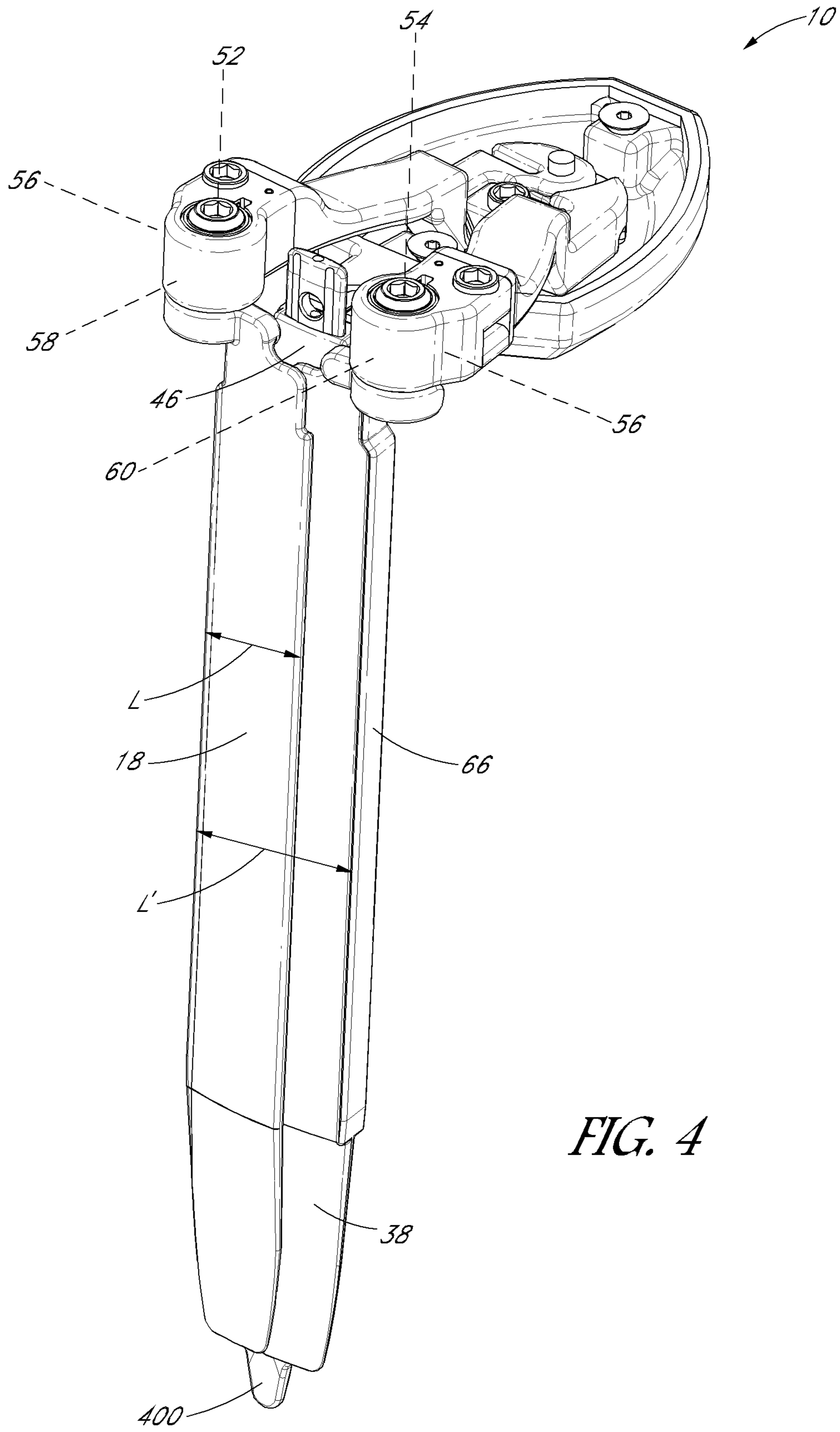


FIG. 4

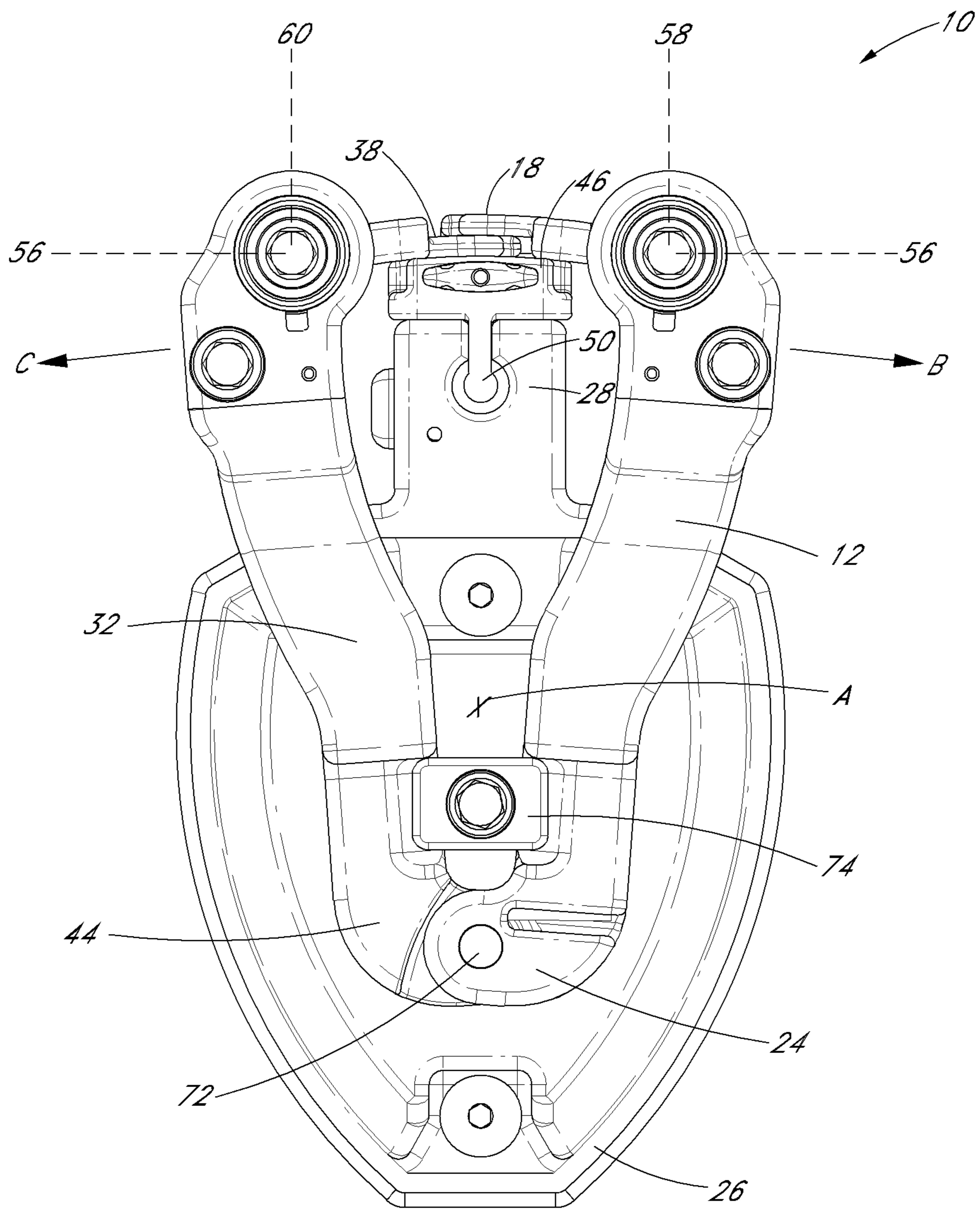


FIG. 5

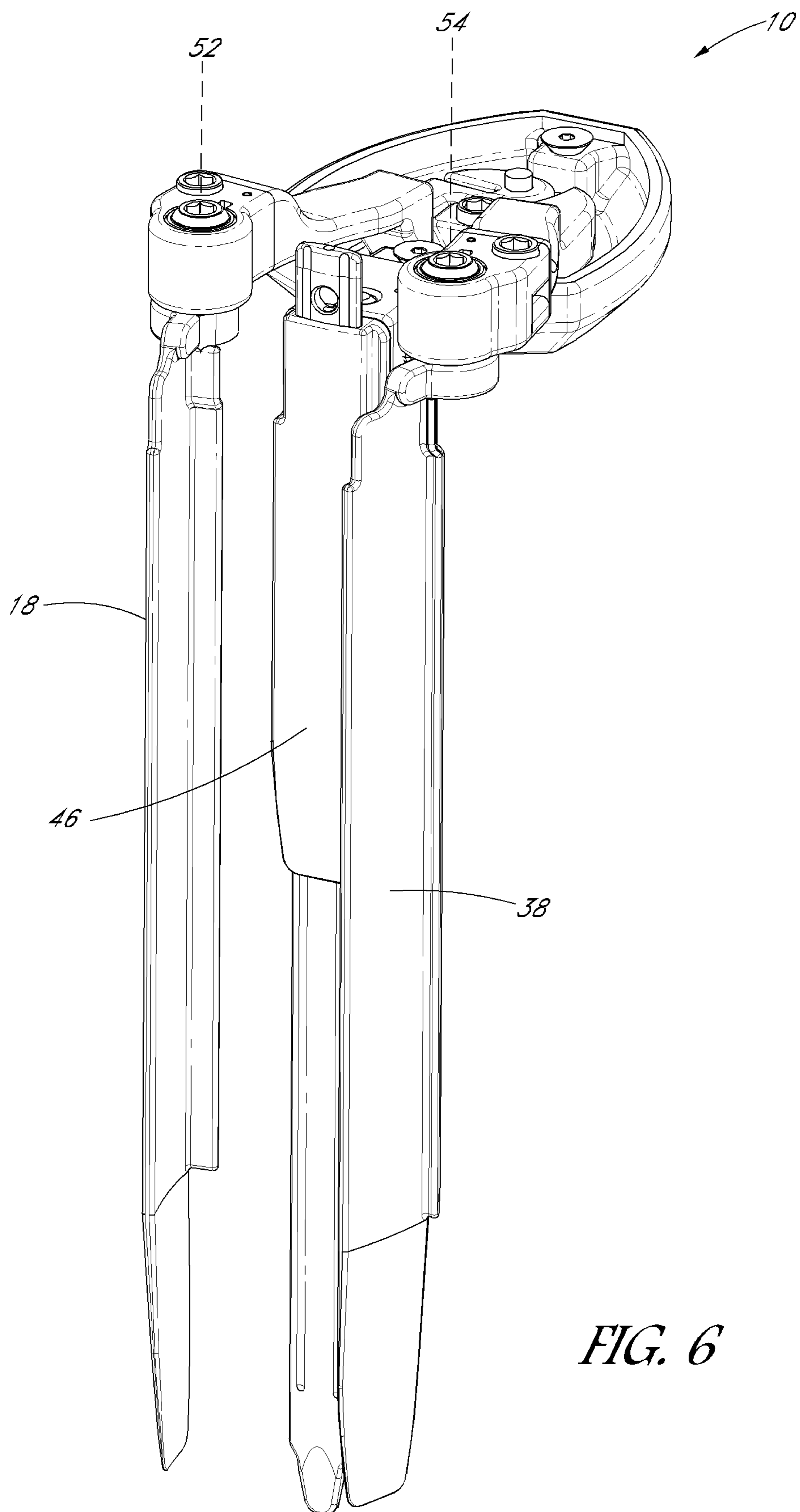


FIG. 6

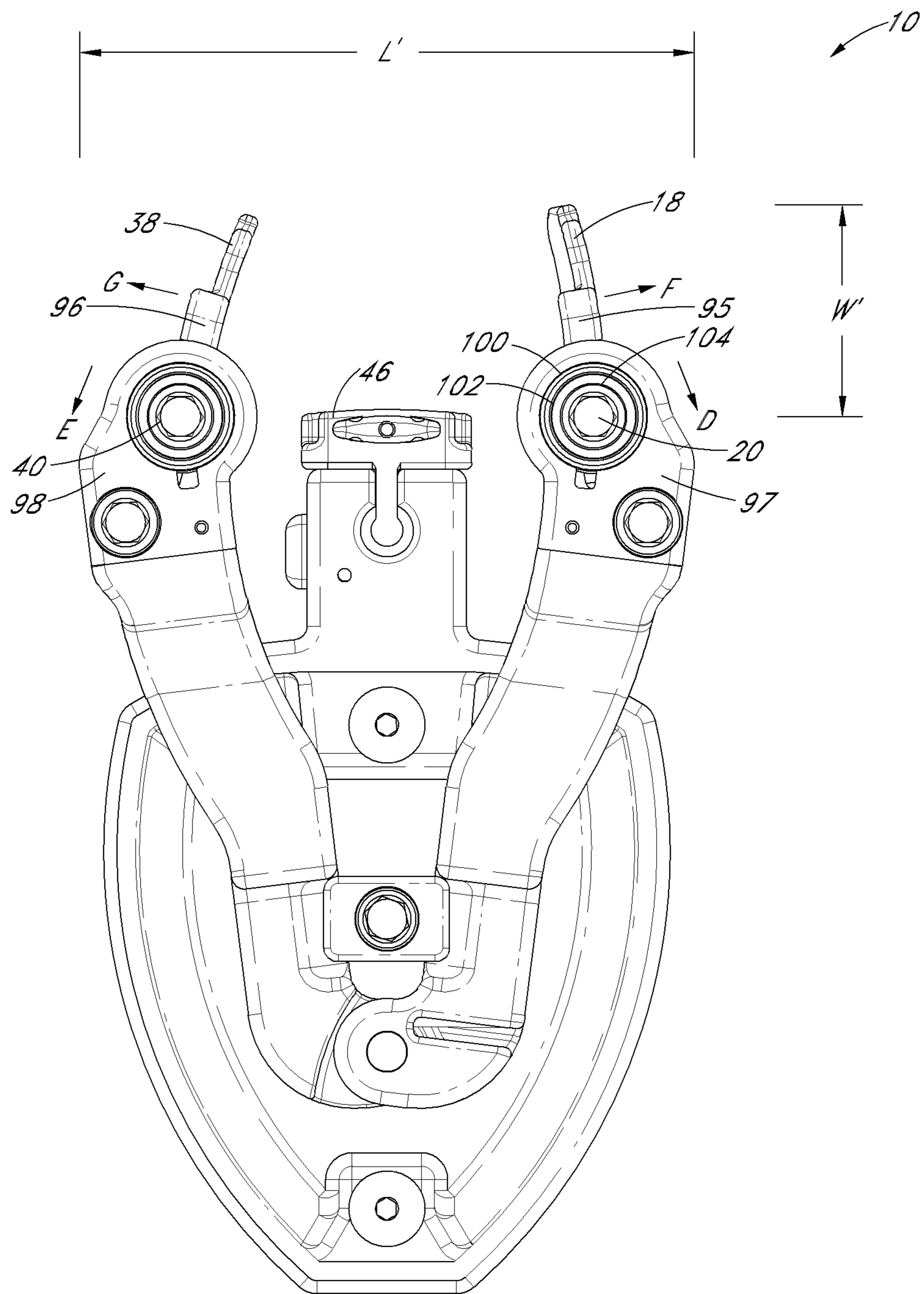


FIG. 7

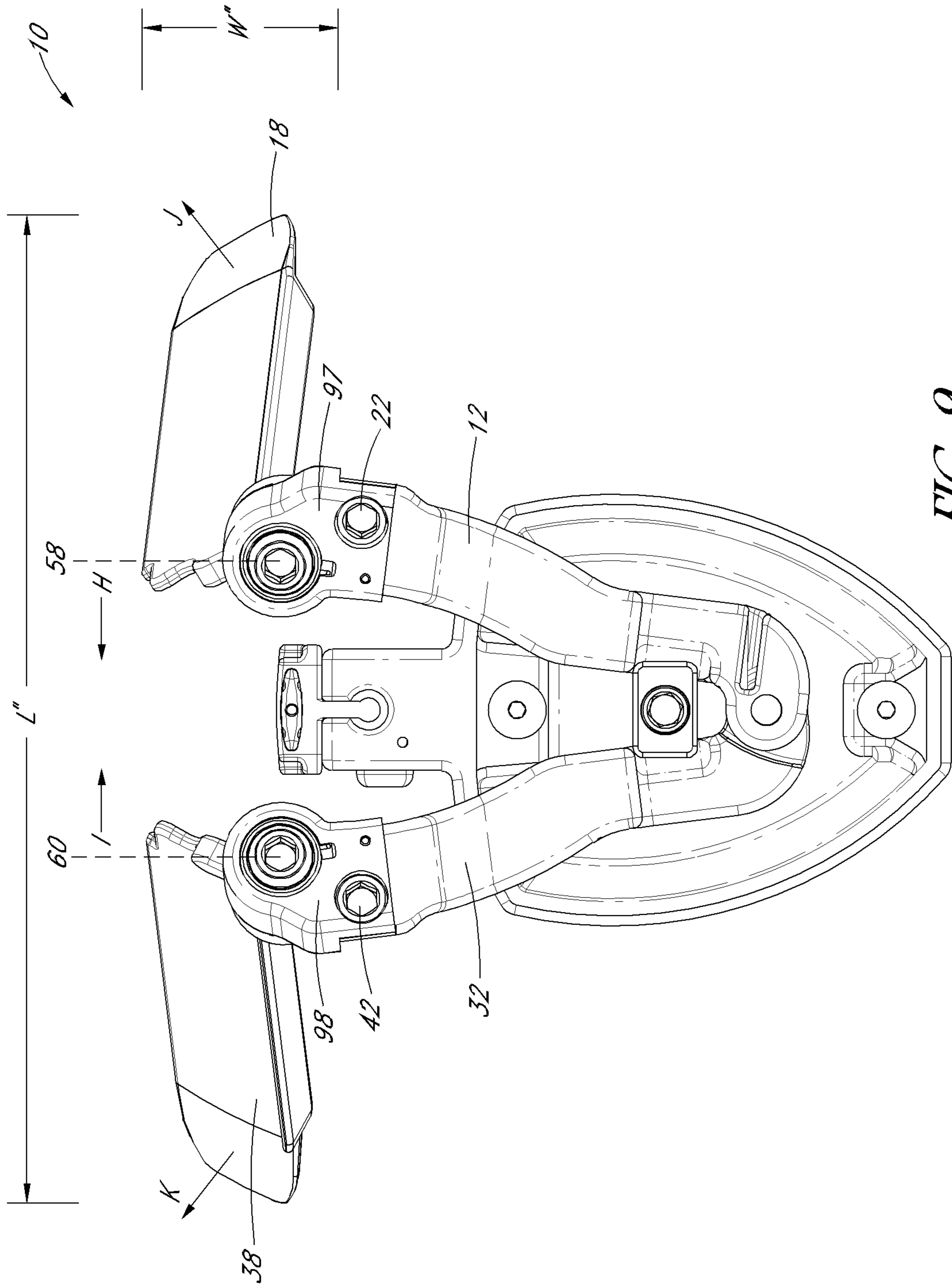


FIG. 9

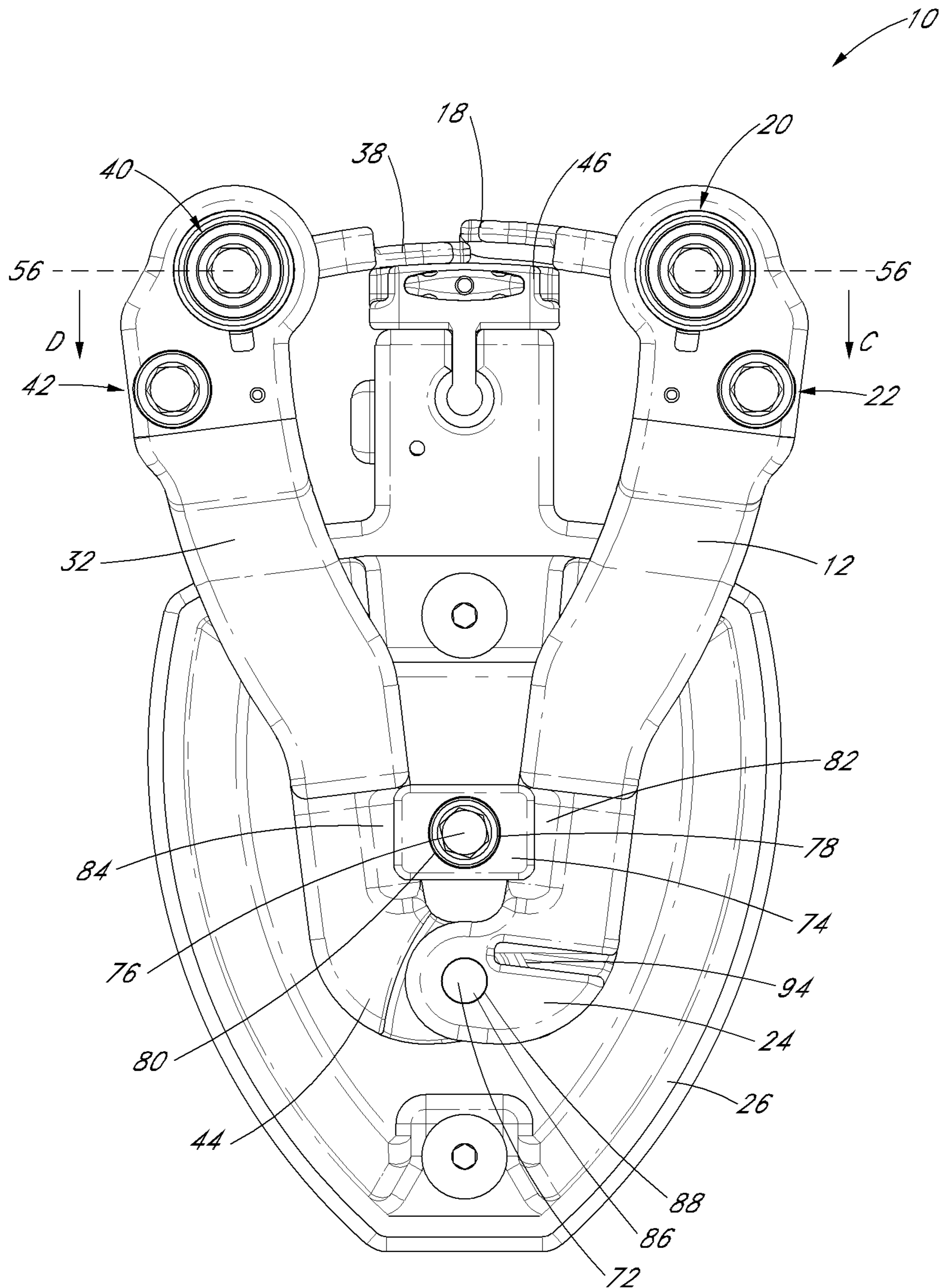


FIG. 10

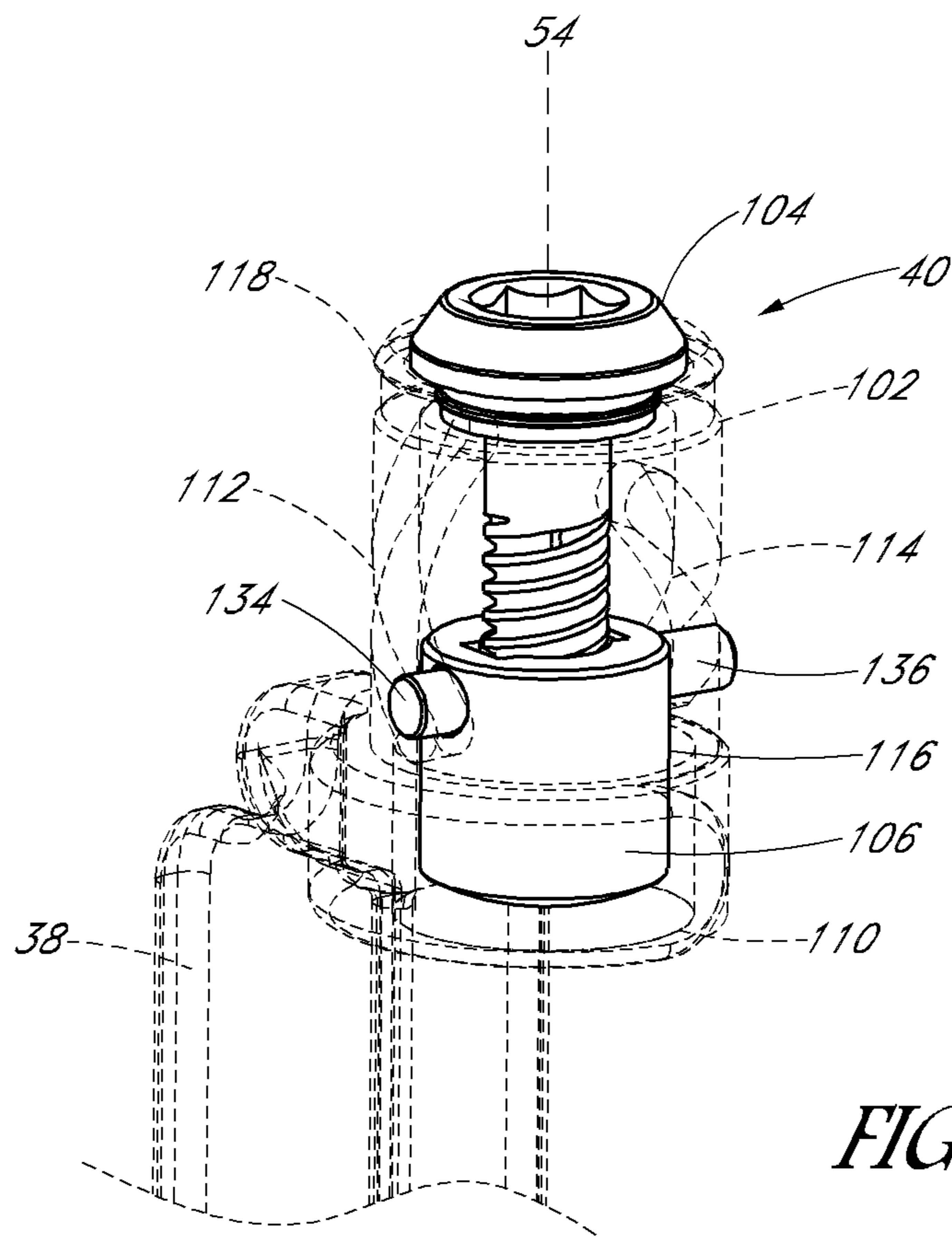


FIG. 11

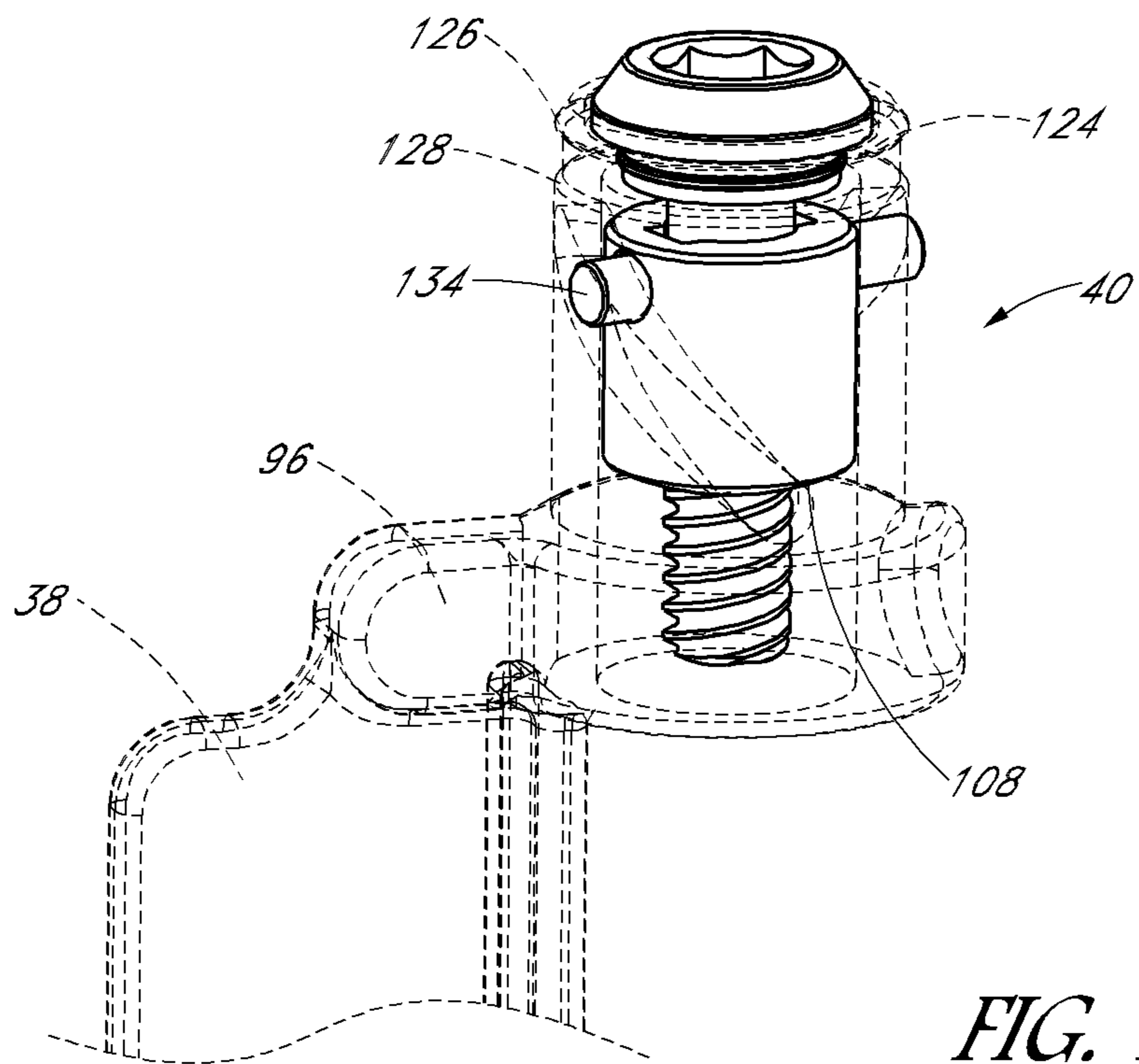


FIG. 12

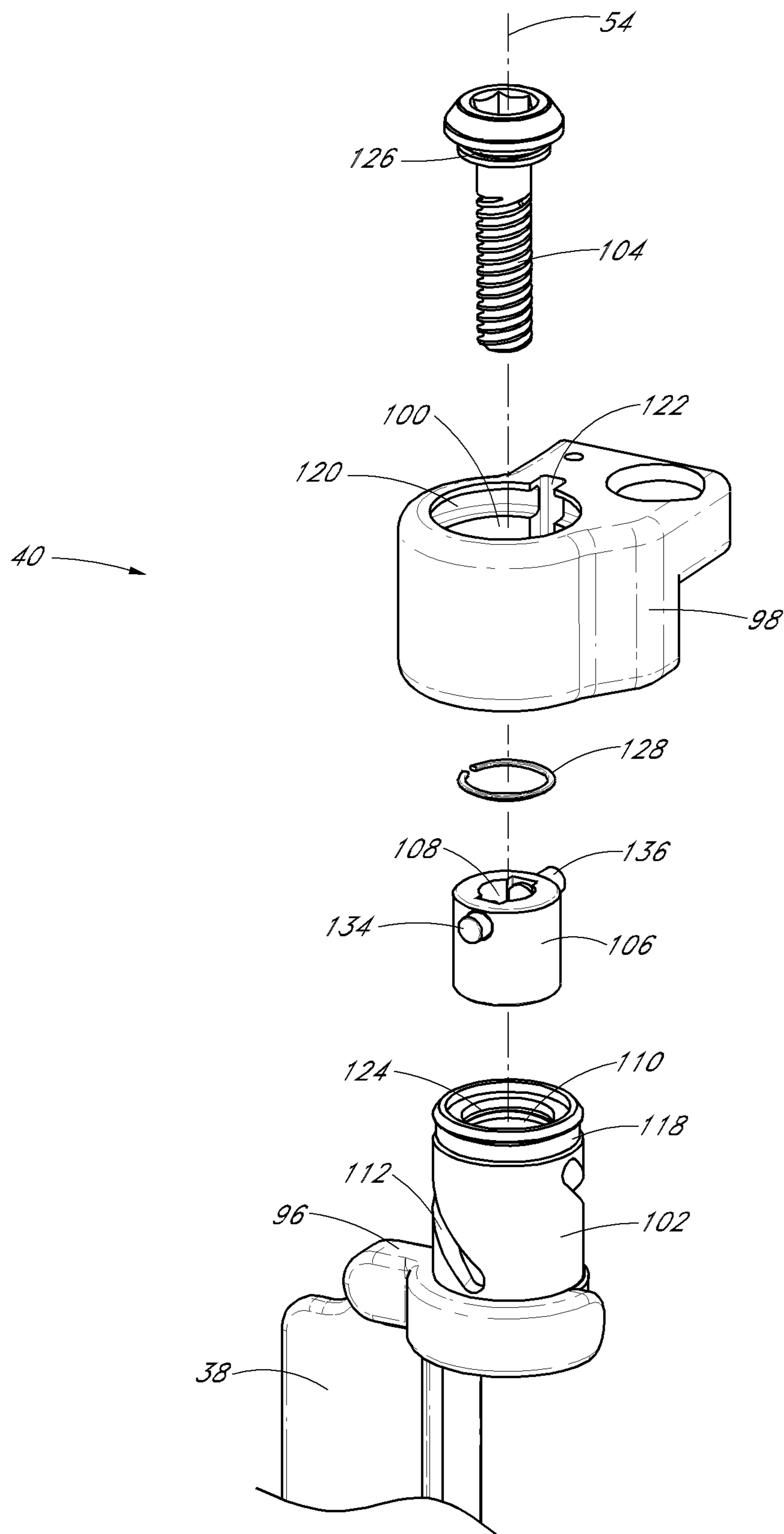


FIG. 13

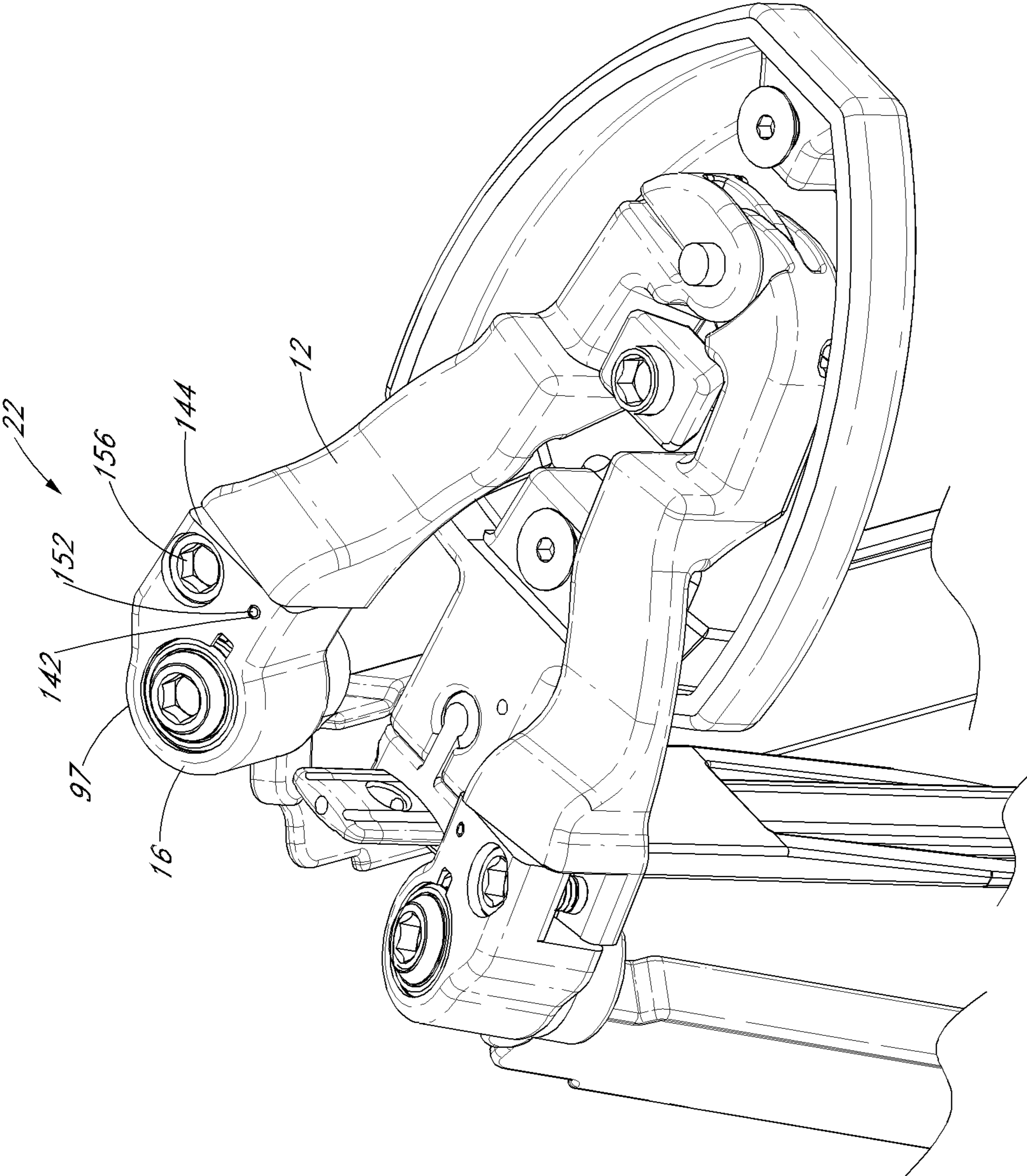


FIG. 14

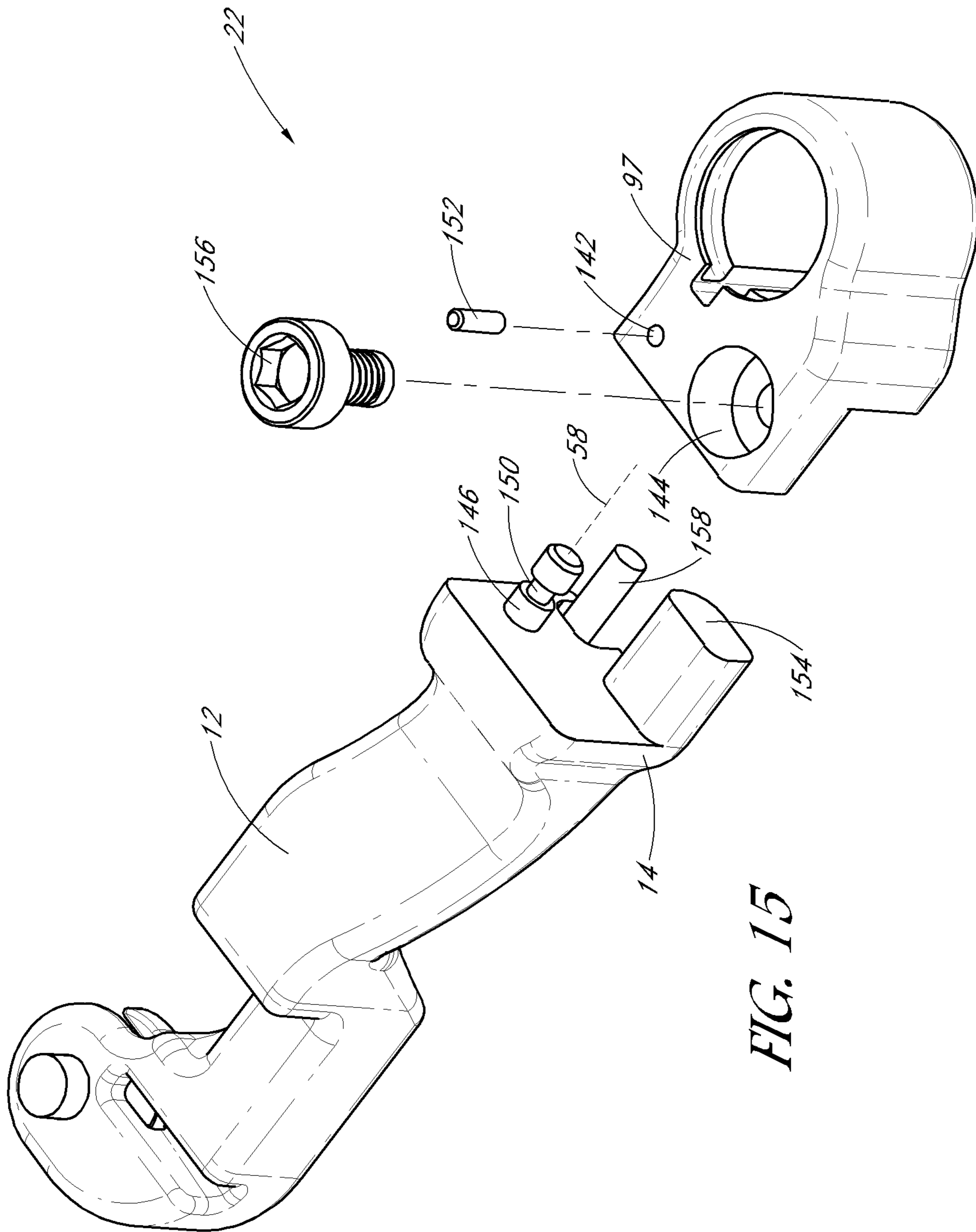


FIG. 15

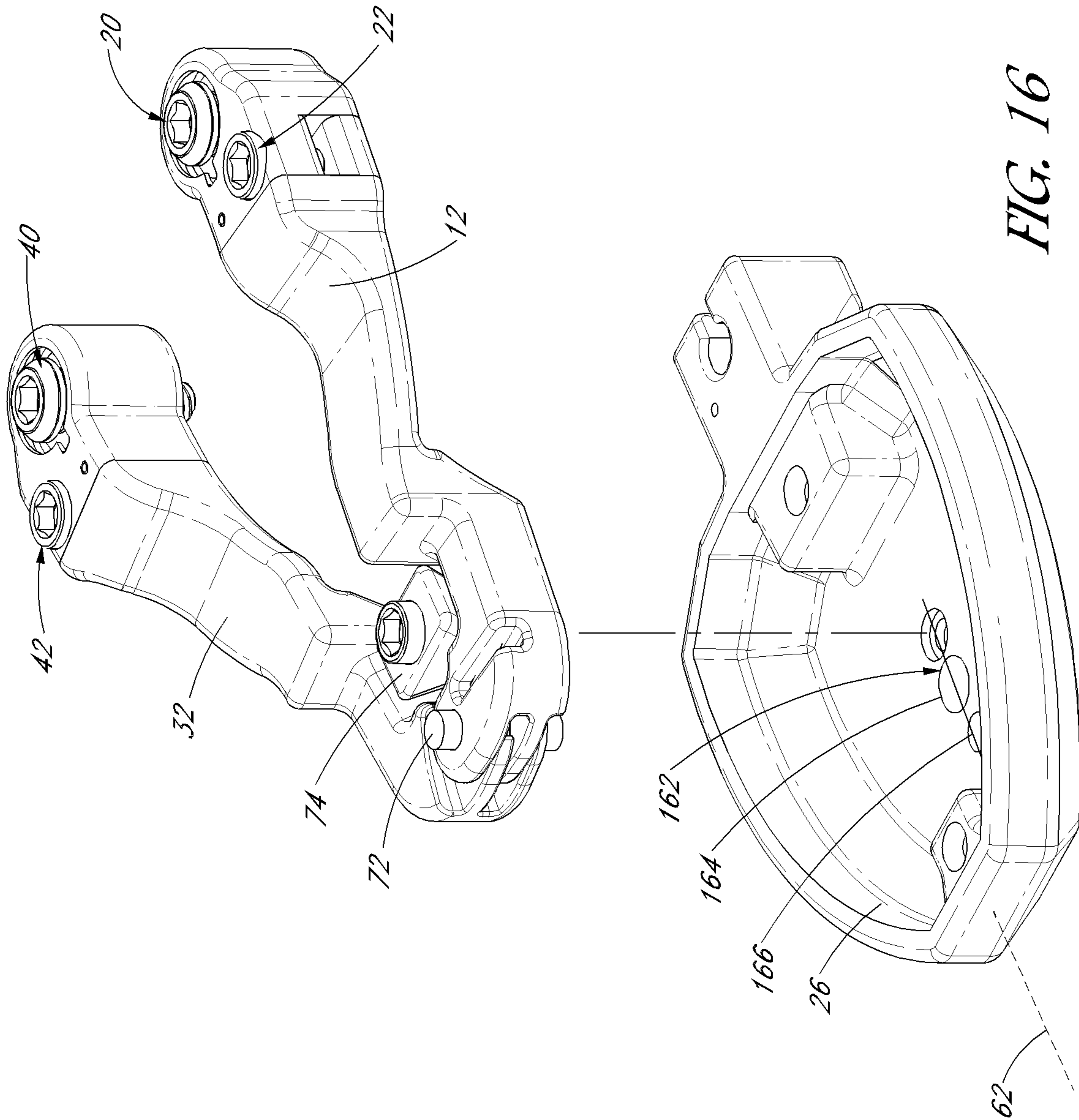


FIG. 16

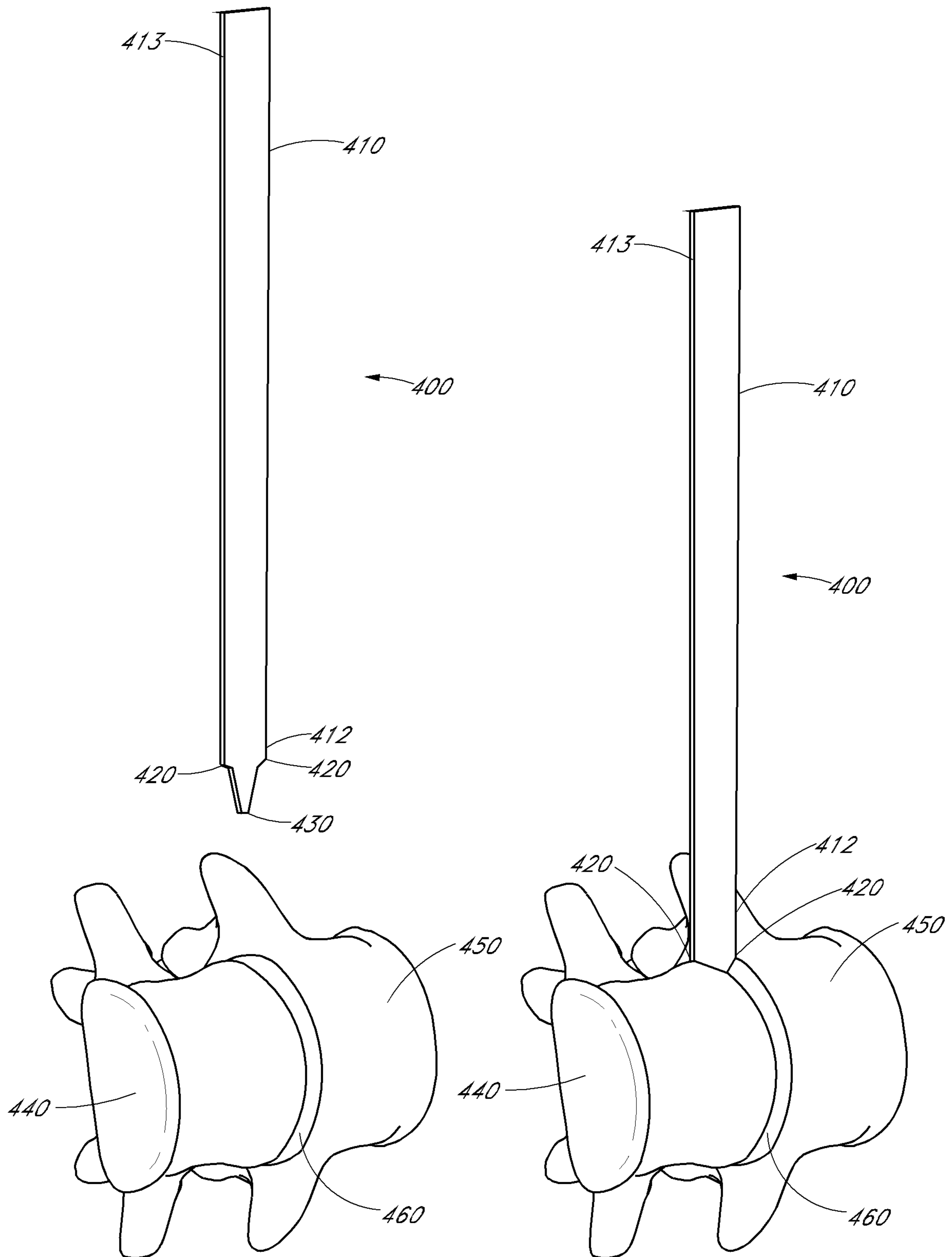


FIG. 17A

FIG. 17B

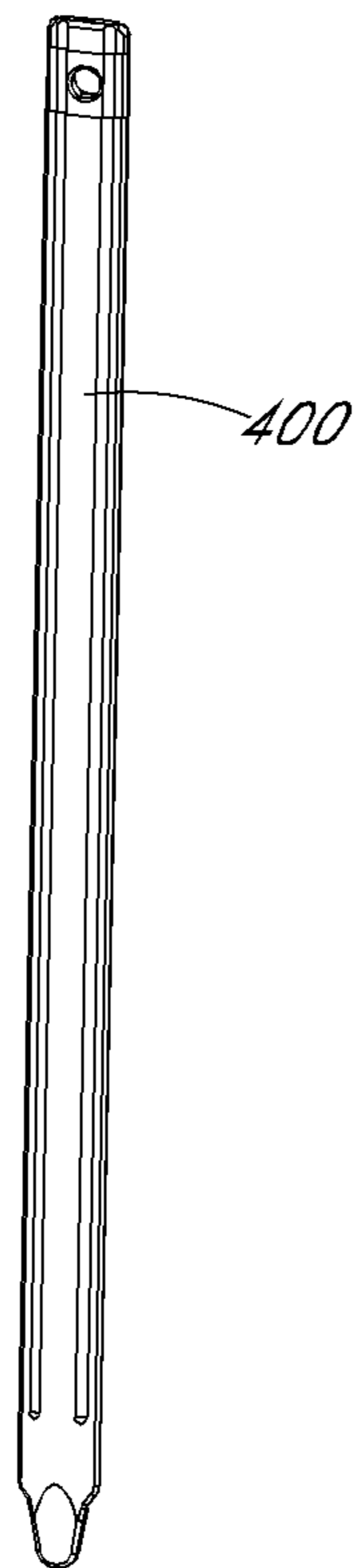
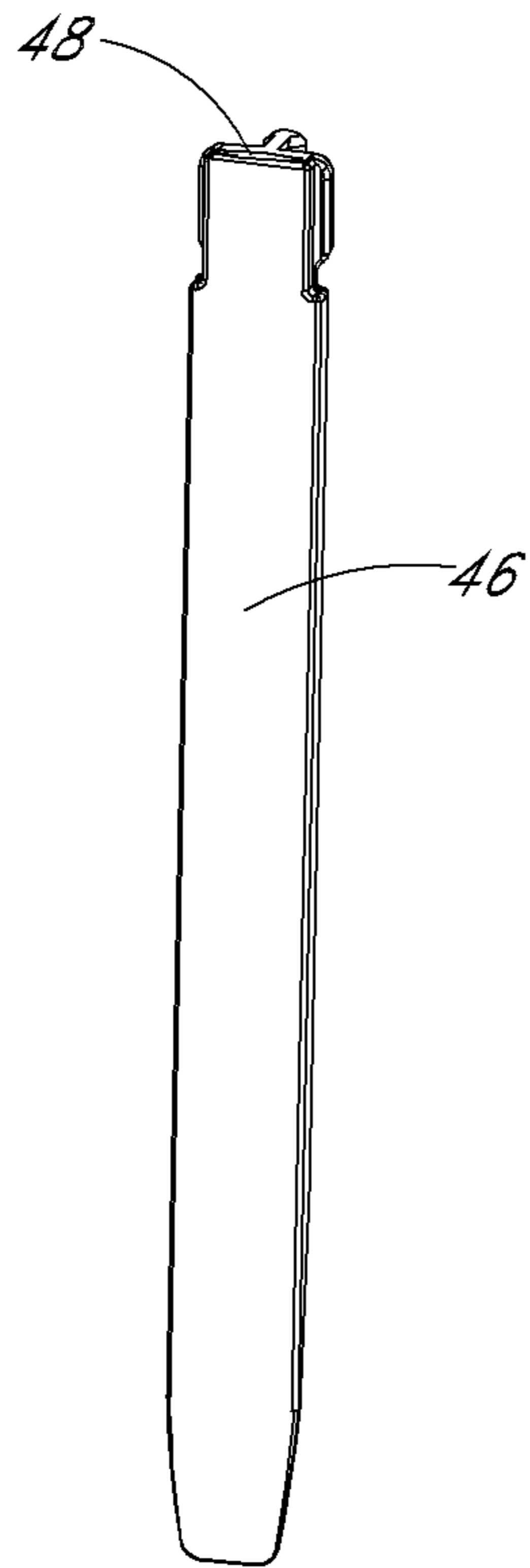


FIG. 17C

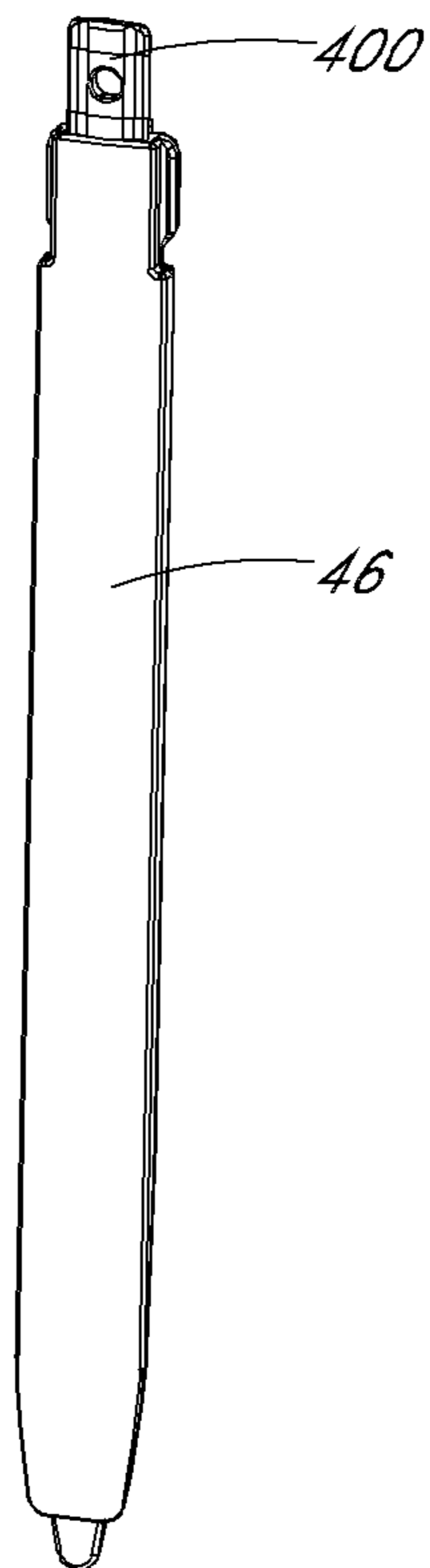
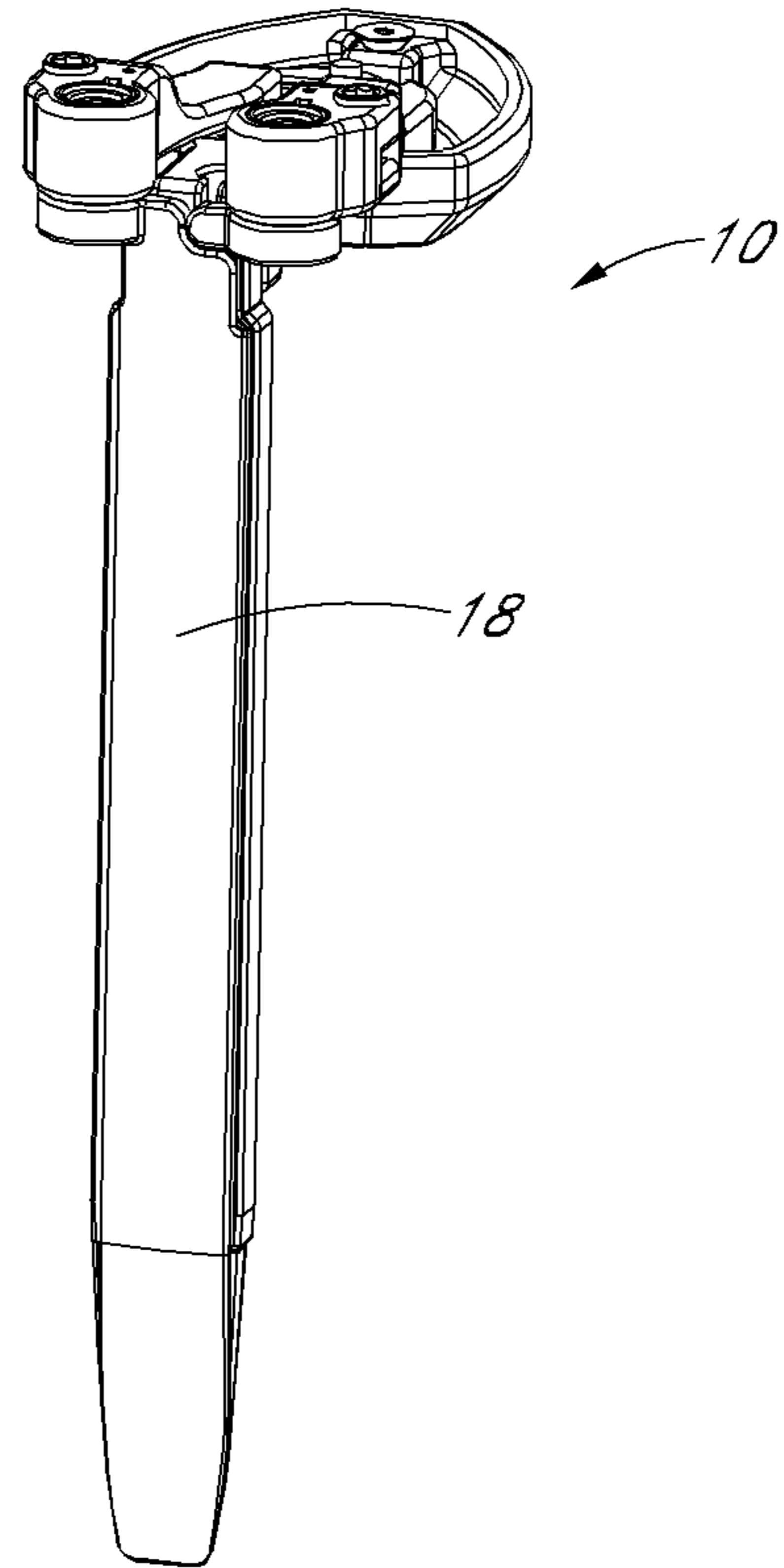


FIG. 17D

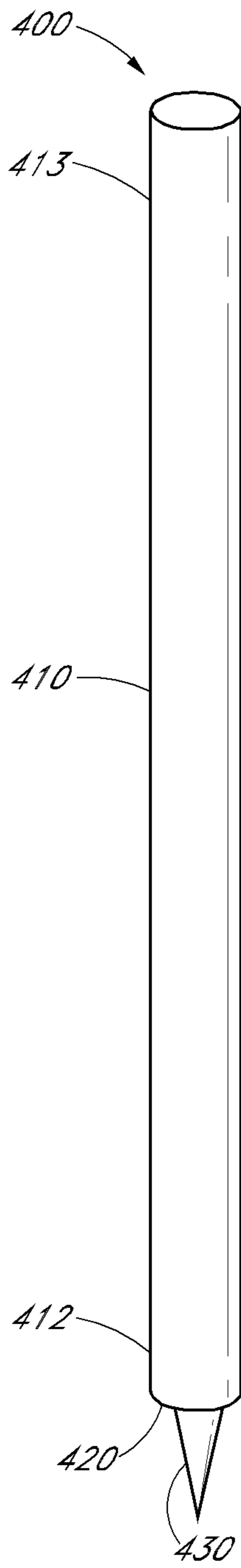


FIG. 18A

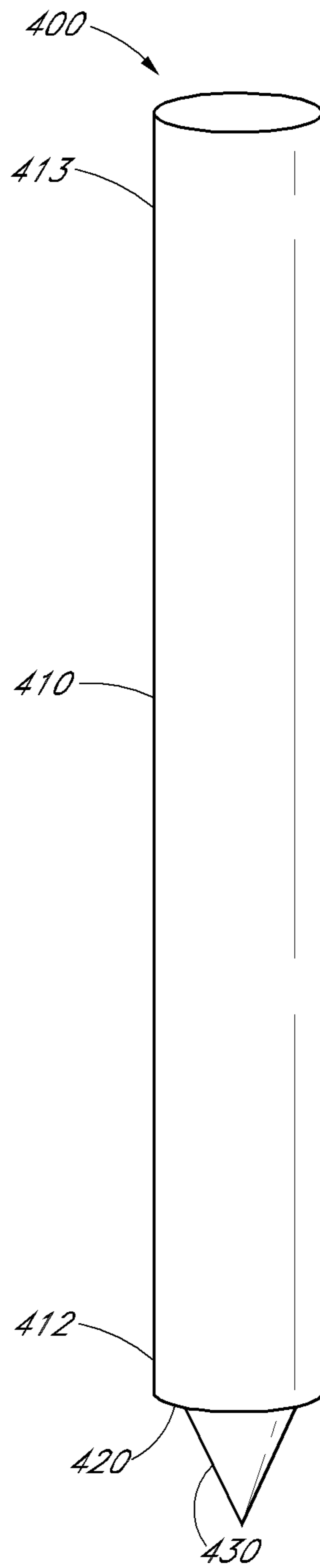


FIG. 18B

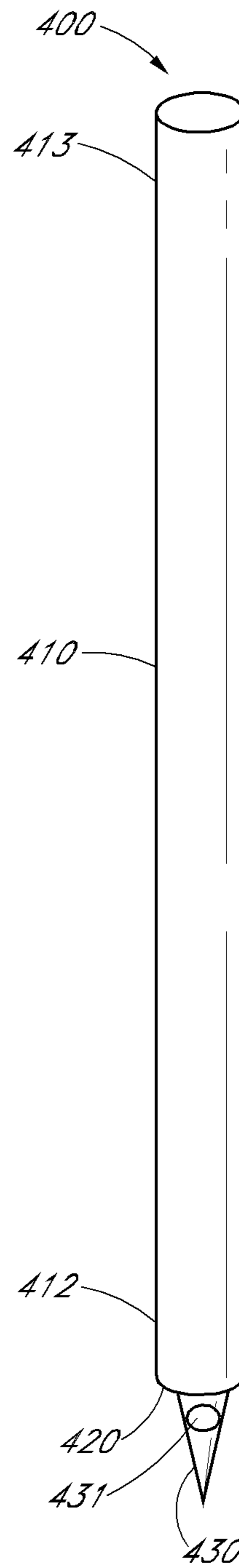


FIG. 18C

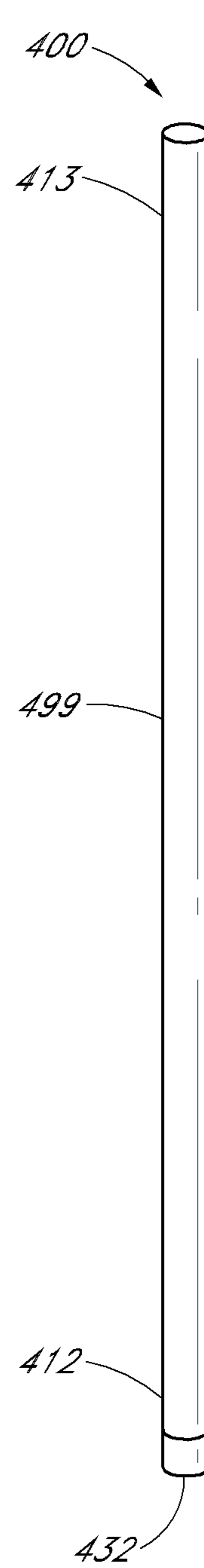


FIG. 18D

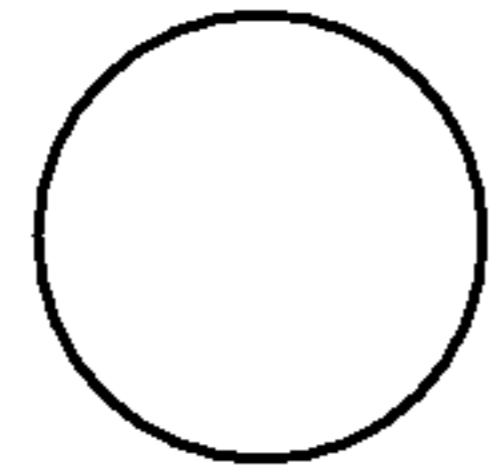


FIG. 19A

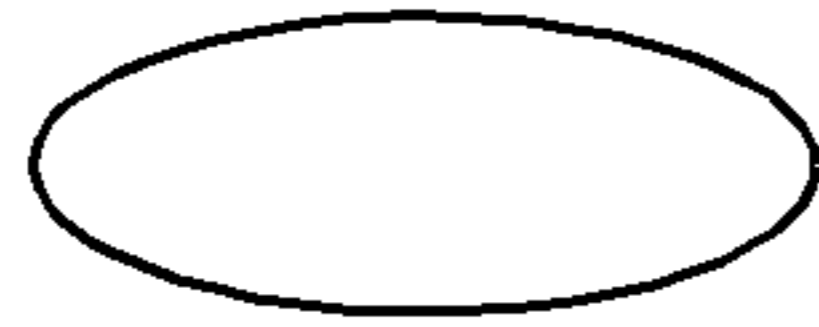


FIG. 19B

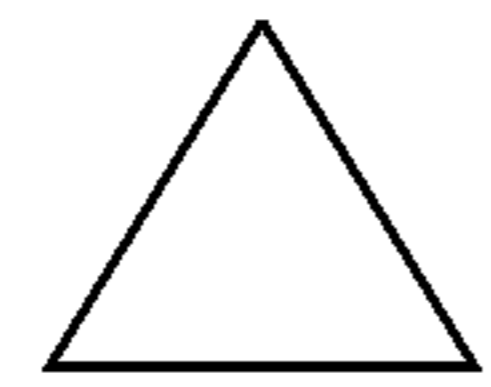


FIG. 19C



FIG. 19D

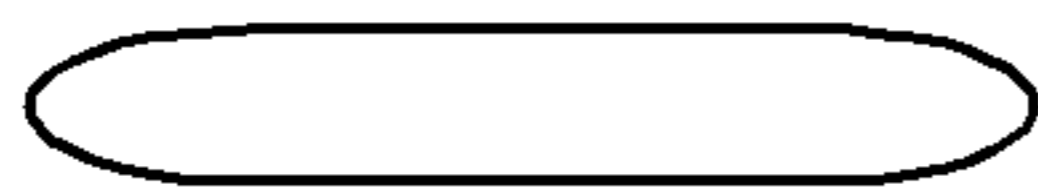


FIG. 19E



FIG. 19F



FIG. 19G



FIG. 19H

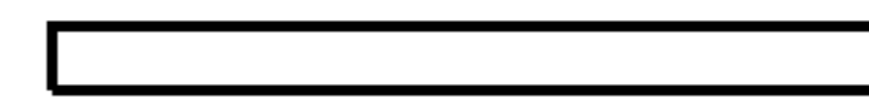


FIG. 19I

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RETRACTOR

CROSS-REFERENCE TO RELATED APPLICATIONS

This application is a continuation of U.S. patent application Ser. No. 15/504,581, filed Feb. 16, 2017, which is the U.S. National Phase under 35 U.S.C. § 371 of International Application No. PCT/US2015/049211, filed Sep. 9, 2015, titled RETRACTOR, which claims priority benefit to U.S. Provisional Patent Application No. 62/048,639, filed Sep. 10, 2014, the entirety of which is hereby incorporated by reference herein.

FIELD

The present application relates to surgical methods and tools, and more particularly to a retractor and a method of operating a retractor.

BACKGROUND

Retractors are surgical devices used to spread bodily tissues in order to allow a surgeon or surgical assistant to see and access a part of the body that is to be surgically treated. In general, retractors comprise a pair of jaws or blades that grip the bodily tissue and push it apart under the force generated by an actuator, such as a pair of scissor-like arms having a distal end and a proximal end. The proximal end generally defines a pair of handles and the distal end attaches to the pair of blades so that manipulation of the handles causes the blades to move apart from one another. Once an incision is made in the body to be operated on, the blades are inserted into the incision and the actuator is manipulated to move the blades of the retractor apart, thus spreading the tissue and providing an aperture through which the surgeon can access visualize the tissue to be surgically treated. One problem with this type of retractor is that the aperture size is generally limited by the size of the incision, meaning that a large aperture requires a relatively large incision. The drawback to this arrangement is that larger incisions result in the need for longer periods for healing of the incision. There is thus a need for a surgical retractor that is capable of creating a relatively large aperture using a relatively small incision, thereby reducing the invasiveness of the surgical procedure, post-operative healing times and patient discomfort.

INCORPORATION BY REFERENCE

All publications and patent applications mentioned in this specification are herein incorporated by reference to the same extent as if each individual publication or patent application was specifically and individually indicated to be incorporated by reference.

BRIEF DESCRIPTION OF THE DRAWINGS

These and other features, aspects and advantages of the described embodiments are described with reference to drawings of certain preferred embodiments, which are intended to illustrate, but not to limit. It is to be understood that the attached drawings are for the purpose of illustrating concepts of the described embodiments and may not be to scale.

FIG. 1 provides a perspective view of an embodiment of a retractor with the blades in a closed position.

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FIG. 2 provides a perspective view of the retractor of FIG. 1 with the blades in a closed position.

FIG. 3 provides a top view of a retractor of FIG. 1 with the blades in a closed position.

FIG. 4 provides a perspective view of an embodiment of a retractor, with the blades in an opened position. Opening the retractor along this axis stretches the incision along its length.

FIG. 5 provides a top view of a retractor of FIG. 4 with the blades in an opened position.

FIG. 6 provides a perspective view of the retractor of FIG. 4 in the rotated position. Opening the retractor along these axes stretches the incision along its width.

FIG. 7 provides a top view of the retractor of FIG. 6 in the rotated position.

FIG. 8 provides a perspective view of the retractor of FIG. 6 in the pivoted position. Opening the retractor along these axes stretches the incision along its width and/or length.

FIG. 9 provides a top view of the retractor of FIG. 8 in the pivoted position.

FIG. 10 provides a top view of the actuator of FIG. 1.

FIG. 11 provides a perspective view a rotation mechanism of FIG. 1.

FIG. 12 provides a perspective view a rotation mechanism of FIG. 11.

FIG. 13 provides an exploded view of a rotation mechanism of FIG. 1.

FIG. 14 provides a perspective view a pivot mechanism of FIG. 13.

FIG. 15 provides an exploded view of a pivot mechanism of FIG. 14.

FIG. 16 provides a schematic view of a slide mechanism.

FIGS. 17A-17D show the use of a probe to insert a retractor system to form an operative channel through the tissue of a patient to access a portion of the patient's spine.

FIGS. 18A-18D show various embodiments of a probe system which can be used to insert a retractor system to form an operative channel through the tissue of a patient.

FIGS. 19A-19I show various cross sections of a probe system.

DETAILED DESCRIPTION

As will be explained below, certain retractor embodiments described herein provide advantages over the prior art retractors comprising a set of blades and an actuator, such as a set of scissor arms. For example, the retractor of the illustrated embodiment allows a person to insert a relatively compact set of retractor blades into an incision having a short length. In some embodiments, the compact set of retractor blades (e.g., a first blade, a second blade, a third blade) are of such a size that they can be inserted within the incision so that they are snugly embraced by the side walls of the incision (e.g. a closed position).

In some arrangements, optionally, an actuator causes the first blade and the second blade to move apart (e.g., to an opened position) in a direction that can be essentially parallel to the length of the incision. This can cause the tissue to stretch in one direction (e.g., along the length of the incision), creating an opening having a length in that direction that is substantially longer than the incision. Once the retractor is opened in the first direction, the actuator may be locked open. Optionally, a rotation mechanism on the first and/or second blades may be manipulated to rotate the blades (e.g., to a rotated position), for example, pulling the incised tissue apart in one or more directions that are not parallel to the incision. Optionally, a pivot mechanism on the

first and/or second blades can be manipulated to pivot the blades (e.g., to a pivoted position), pulling the incised tissue apart in one or more directions that are not parallel to the incision. Optionally, an adjuster on the first and/or second arms can be manipulated to slide or otherwise translate the arms (e.g., to a slide position), pulling the incised tissue apart in directions that are not parallel to the incision. In some embodiments, these directions may be perpendicular, substantially perpendicular or oblique to the incision. In certain embodiments, the retractor can be used to open up an aperture that is substantially longer and/or wider than the incision, and is substantially larger than would be possible using a prior art device and/or in a manner that is easier to use and/or requiring less steps and/or less complicated steps. In certain arrangements in relative terms, the surgeon can use a smaller incision, and in some cases a much smaller incision, than would have been required with a prior art device. Moreover, in certain arrangements, removal of the retractor, e.g. by closing the blades, closing the arms and removing the blades from the incision, can allow the incision to relax back to a size that is much smaller than would have resulted from use of the prior art retractor. In addition, in certain arrangements, steps performed by the surgeon to retract the tissue can be simplified, easier to use and/or involve less steps as compared to prior art devices.

The illustrated embodiment will now be further described with reference to the appended drawings. In FIG. 1 there is shown a perspective view of a retractor 10 having a body 26. The retractor 10 comprises a first arm 12, having a distal end 14 to which can be coupled a first blade assembly 16 comprising a first blade 18. The first blade assembly 16 can include a first rotation mechanism 20 to rotate the first blade 18. The first blade assembly 16 can also include a first pivot mechanism 22 to pivot the first blade 18. The first arm 12 has a proximal end 24 which is coupled to the body 26.

The retractor 10 can include a second arm 32, having a distal end 34, to which can be coupled a second blade assembly 36 comprising a second blade 38. The second blade assembly 36 can include a second rotation mechanism 40 to rotate the second blade 38. The second blade assembly 36 can include a second pivot mechanism 42 to pivot the second blade 38. The second arm 32 has a proximal end 44 which is coupled to the body 26.

In the illustrated embodiment of FIG. 2, the retractor can include a third blade 46 coupled to the body 26. The third blade 46 can include a longitudinally extending slot 48 sized to accept a probe 400, described herein. In the illustrated embodiment, the probe 400 can be configured to be inserted from the tip of the third blade 46 toward the body 26. Other configurations are contemplated. The third blade 46 can include a connector 50. In the illustrated embodiment, the connector 50 is a male connector. The body 26 can include a connector 28, which in the illustrated embodiment is a female connector. The connector 50 of the third blade 46 coupled with the connector 28 of the body 26 to hold the third blade 46 stationary in relation to the body 26. In the illustrated embodiment, the third blade 46 is configured to be inserted from underneath the body 26. The connectors 50, 28 interlock to securely couple the third blade 46 to the body. In some embodiments, the connectors 50, 28 form a snap fit. In some embodiments, the connectors 50, 28 make an audible noise when the third blade 46 is coupled to the body 26. Other configurations for coupling these two components together are contemplated, such as, for example reversing the male/female connection and/or permanently connecting the parts and/or forming the parts out of more or less components.

The first rotation mechanism 20 rotates the first blade 18 about a first axis 52. The second rotation mechanism 40 rotates the second blade 38 about a second axis 54. In the illustrated arrangement, the first axis 52 passes vertically or substantially vertically through the first blade 18, and the second axis passes vertically or substantially vertically through second blade 38. In some embodiments, the first and second axes may be substantially coplanar with one another. Indeed in some embodiments, the first and second axes are not only coplanar but also substantially parallel to one another. In particular embodiments, the first and second axes are coplanar with, parallel to, or at some pre-determined skew angle with respect to one another. As will be described above, various embodiments will be described as “substantially” vertically, parallel, coplanar and/or perpendicular. In such embodiments, “substantially” can mean within plus or minus 25 degrees from the given orientation, in other embodiments, within plus or minus 10 degrees from the given orientation, and in other embodiments, within plus or minus 5 degrees from the given orientation.

In the illustrated embodiment, the first blade assembly 16 and the second blade assembly 36 can translate along a third axis 56 (see e.g., FIG. 3). In the illustrated embodiment, the first blade assembly 16 and the second blade assembly 36 can move relative to one another along an arc. In the illustrated embodiment, their general direction of motion relative to one another, and the direction of motion can be along the common third axis 56 that is generally defined by a line passing through the first axis 52 and the second axis 54. In other embodiments, the first blade assembly 16 and the second blade assembly 36 can rotate about different axes (e.g., axes that are parallel to each other or slightly skewed). In some examples, the third axis is perpendicular or substantially perpendicular to the first axis, the second axis or both the first and second axes. In particular embodiments, the third axis is substantially perpendicular or perpendicular to both the first axis and the second axis. In some embodiments, the third axis is substantially perpendicular or perpendicular to the first axis, the second axis or both the first and second axes. In some embodiments, the third axis is perpendicular or substantially perpendicular to both the first and second axes. In some embodiments, the retractor described herein possesses a mechanism (e.g., set screw, set pin, clamp, detent, ratchet mechanism etc.) for locking the arms 12, 32 in at least one predetermined position along the third axis 56.

The first pivot mechanism 22 can pivot the first blade 18 about a fourth axis 58. The second pivot mechanism 42 can pivot the second blade 38 about a fifth axis 60. In some such embodiments, the fourth axis 58 and the fifth axis 60 may be substantially coplanar or coplanar with one another. Indeed in some embodiments, the fourth axis 58 and the fifth axis 60 are not only coplanar but also substantially parallel or parallel to one another. In particular embodiments, the fourth axis 58 and the fifth axis 60 are substantially coplanar with, coplanar with, substantially parallel to, parallel to, or at some pre-determined skew angle with respect to one another.

In the illustrated embodiment, the first blade assembly 16 and the second blade assembly 36 can slide along a sixth axis 62 (see e.g., FIG. 3). In the illustrated embodiment, the first blade assembly 16 and the second blade assembly 36 can move together in a proximal-distal direction. In other embodiments, the first blade assembly 16 and the second blade assembly 36 can slide about different axes (e.g., axes that are parallel to each other or slightly skewed). In some examples, the sixth axis 62 is perpendicular or substantially

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perpendicular to the first axis **52**, the second axis **54**, or the third axis **56**. In particular embodiments, the sixth axis **62** is substantially perpendicular or perpendicular to both the first axis **52** and the second axis **54**. In some embodiments, the sixth axis **62** is substantially parallel or parallel to the fourth axis **58**, the fifth axis **60** or both the fourth and fifth axes. In some embodiments, the retractor described herein possesses a mechanism (e.g., set screw, set pin, clamp, detent, ratchet mechanism etc.) for locking the arms **12**, **32** in at least one predetermined position along the third axis **56**. In the illustrated embodiment, through all the additional movements about the axes **52**, **54**, **56**, **58**, **60**, **62** the third blade **46** can remain stationary and fixed relative to the body **26**. In other words, during all movement of the first blade **18** and the second blade **38** the third blade **26** can remain immobile. In other embodiments, the third blade **46** can move relative to the first blade **18** and the second blade **38**. For example, the third blade **46** can move along the sixth axis **62**, such as through a carriage system, while the first blade **18** and the second blade **38** remain stationary. In another example, the third blade **46** can pivot relative to the first blade **18** and the second blade **38**. The third blade **46** can be hingedly connected to the body **26** and can pivot toward the proximal direction to help create an enlarged aperture in the incised tissue.

The blades **18**, **38**, **46** may have a variety of configurations. In some embodiments, at least one blade is substantially flat. In some embodiments (e.g., the illustrated embodiment of FIGS. 1-3), at least one blade is bent or beveled in order to enhance the ability of the blades to lie flat when the blades are in the closed position. This arrangement can allow the first and second blades **18**, **38** to exert force on the skin about an incision in opposing directions substantially perpendicular to the blade axes and perpendicular or oblique to a cord defined by the points at which the blade axes intersect the arms **12**, **32** of the retractor **10**. In some embodiments, one or more blades **18**, **38**, **46** can be fan shaped.

In some embodiments, two of the blades are of substantially different sizes in at least one dimension. In some embodiments, the at least two blades of different sizes are the first blade **18** and second blade **38**. In some embodiments, the at least two blades of different sizes are the first blade **18** and the third blade **46**. In some embodiments, the at least two blades of different sizes are the second blade **38** and the third blade **46**. In some embodiments, at least one of the blades **18**, **38**, **46** is a comb-shaped blade. In some embodiments, at least one of the blades **18**, **38**, **46** is a substantially flat blade. In some embodiments, the retractor **10** can include at least one removable blade. In some embodiments, the first blade **18** and the second blade **38** are removable. The first blade **18** can include a first bridge **95** and the second blade **38** can include a second bridge **96**. The blades **18**, **38** can have a variety of lengths of bridges **95**, **96**. The bridges **95**, **96** can allow the blade **18**, **38** to be smaller than the length of the retractor **10**.

The blade assemblies **16**, **36** can be removed from the arms **12**, **32**. In some arrangement, it can be convenient to remove the blade assemblies **16**, **36** in order to expedite sterilization of the blade assemblies **16**, **36** and/or in order to exchange one or both blade assemblies **16**, **36** for other blade assemblies (e.g. blade assemblies with different size blades, different configuration of blades, etc.) as discussed in more detail herein.

In FIGS. 1-3, the retractor **10** is shown in the “closed position,” meaning that the first blade **18**, the second blade **38**, and the third blade **46** are aligned and relatively close to

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one another so as to provide a smaller cross-sectional area as compared to an “open position”. While the application uses the phrase “the closed position,” it is understood that one or more positions may be described as closed. For instance, the blades **18**, **38**, **46** may be aligned, substantially aligned, stacked, substantially stacked, close together, relatively close together, the first blade **18** encloses the second blade **38**, the second blade encloses the third blade **46**, the first blade **18** encloses the third blade **46**, one or more blades **18**, **38**, **46** enclose the probe **400**, or any other closed positions.

The first blade **18**, the second blade **38**, and the third blade **46** can be substantially parallel or parallel in the closed position. The longitudinal axes of the first blade **18**, the second blade **38**, and the third blade **46** can be aligned on substantially the same or the same plane in the closed position. The length of the three blades **18**, **38**, **46** in this configuration can be approximately equal to the length of one blade, such as the length of the first blade **18**. The first blade **18**, the second blade **38**, and the third blade **46** can have a stacked configuration. The first blade **18** can be in front (e.g., distal), the second blade **38** can be in the middle, and the third blade **46** can be in back (e.g., proximal).

The first blade **18** can have a first rail **64** that aligns one side of the blades **18**, **38**, **46**. The first rail **64** can extend from the proximal surface of the first blade **18** toward the body **26**. The second blade **38** can have a second rail **66** that can extend from both distal surface and the proximal surface of the second blade **38**. When viewed from the distal end of the retractor **10** (as shown in FIG. 1), the first rail **64** can extend on the left side of the first blade **18** and the second rail **66** can extend on the right side of the second blade **38**. This configuration permits the first blade **18** to slide relative to the second blade **38** without interference of the rails **66**, **68**. The rails **66**, **68** can have a width equal to the width of the stacked blades **18**, **38**, **46**.

In FIGS. 4-5, the retractor **10** is shown in the “opened position,” meaning that the first blade **18** is translated relative to the third blade **46** and the second blade **38** is translated relative to the third blade **46**. The first blade **18** is moved apart from the second blade **38**, while the third blade **46** can remain stationary. The first blade **18**, the second blade **38**, and the third blade **46** can have an overlapped configuration in the opened position, as shown. While the application uses the phrase “the opened position,” it is understood that one or more positions may be described as opened. For instance, the blades **18**, **38** may be slightly spaced apart, greatly spaced apart, overlapping, not overlapping, adjacent, with a gap between, without a gap between, at any spaced apart location along the third axis **56**, wherein the total length in the opened position is greater than the incision length L , or any other opened positions.

The motion of the first blade **18** can be coupled to the motion of the second blade **38** such that actuation of a single actuator moves both the first blade **18** and the second blade **38**. In other embodiments, each of the first blade **18** and the second blade **38** is separately actuated. The first blade **18** can be in front (e.g., distal), the second blade **38** can be in the middle, and the third blade **46** can be in back (e.g., proximal). The length L' of the three blades **18**, **38**, **46** in this configuration is greater than the length L of one blade, such as the length of the first blade **18**. When viewed from the distal end of the retractor **10** (shown in FIG. 4). The first blade **18** can translate a first distance to the left of the third blade **46**. The second blade **38** can translate a second distance to the right of the third blade **46**. The first distance can be equal to the second distance, but need not be. The

configuration of the rails **66**, **68** permits the first blade **18** to translate relative to the second blade **38** without interference of the rails **66**, **68**.

FIG. **5** shows the top view of the retractor **10**. In the illustrated embodiment, the proximal ends **24**, **44** of the arms **12**, **32** can be coupled to the body **26**. The arms **12**, **32** are coupled to the body **26** at the pivot **72**. The retractor **10** can include an actuator **74**. The actuator **74** interacts with the arms **12**, **32** to spread the arms **12**, **32**. One embodiment of the actuator is shown in FIG. **10**. Depression of the actuator **74**, in the direction of the arrow A in FIG. **5** (i.e., into the page) results in the arms **12**, **32** and therefore the blade assemblies **16**, **36** moving apart along the directional arrows B and C, causing retractor **10** to assume the opened position depicted in FIG. **5**. In the illustrated embodiment, the third axis **56** forms an arc due in part to the pivot **72**. The first blade **18** will follow an arced path away from the third blade **46**. The second blade **38** will follow an arced path away from the third blade **46**. The first blade **18** will follow an arced path in separating from the second blade **38**. In the illustrated embodiment, the first blade **18** and the second blade **38** translate when the arms **12**, **32** rotate about the pivot **72**. In the illustrated embodiment, the third axis **56** can be substantially perpendicular or perpendicular to the first axis **52** and the second axis **54**. The third axis **56** can extend perpendicularly or substantially perpendicularly through the first axis **52** and the second axis **54**.

It is noted that in the embodiment depicted in FIG. **5**, the retractor **10** comprises a pair of arms **12** and **32** connected via a pivot **72**. Other embodiments of an actuator may be used. For example, scissor-like actuators are known in the clamp and retractor arts. In some such embodiments, the actuator comprises a pair of handles (not shown) coupled to the arms **12** and **32**. The handles can be roughly parallel and joined together at a pivot point **72**. The handles can be crossed (e.g. scissor-like) handles and joined together at a pivot point **72**. It is also to be understood that when the actuator is a scissor-like embodiment, the motion of blade assemblies **16** and **36** traverse an arc rather than a straight line upon opening of the retractor **10**. Nevertheless, the spatial relationship of the two blade assemblies **16** and **36** can be conceptualized as changing along a line described by arrows B and C, which for the purpose of brevity is referred to herein as an axis, and in particular the third axis **56**.

While the illustrated embodiment uses a mechanism for moving the first blade **18** to the second blade **38** comprising a pair of arms **12**, **32** joined to one another at a pivot **72**, other configurations are contemplated. In some embodiments, the proximal ends **24**, **44** of the arms **12**, **32** can be joined in alternative ways to the body **26** such that the movement of the arms **12**, **32** is not a pivoting motion about pivot **72**. For instance, arms **12**, **32** can be joined one to another by a cross member (not shown). The cross member holds the arms **12**, **32** in parallel and stabilizes the arms **12**, **32**. One or more arms **12**, **32** can be moved along the cross member in order to translate the first blade **18** away from the third blade **46** and to translate the second blade **38** away from the third blade **46**. In such configurations, the first arm **12** linearly translates relative to the second arm **32**, rather than rotating about the pivot **72**. In this embodiment, the third axis **56** defines a geometric line passing through and joining the first axis **52** and the second axis **54**. The first blade **18** follows a straight path away from the second blade **38**.

In some embodiments, the retractor described herein possesses a device for locking the arms **12**, **32** in at least one predetermined position along the third axis **56**. The device for locking the arms **12**, **32** can be a ratchet (not shown). The

device for locking the arms **12**, **32** can be a detent and recess configuration. The device for locking the arms **12**, **32** can be disposed on the pivot **72** or the cross member (not shown).

The arms **12**, **32** may be removed from the body **26**. For instance, in the illustrated embodiment, the pivot **72** can be removed to remove the arms **12**, **32** from the body **26**. This may occur at any time, e.g. prior to or during sterilization of the retractor **10** or during a surgical procedure once the retractor **10** has been opened. Removal of the body **26** during surgery may afford a member of the surgical team greater freedom of motion, an improved field of view or both.

Insertion of the blades **18**, **38**, **46** into an incision in the closed position (as in FIGS. **1-3**) and translating the first blade **18** and the second blade **38** to an opened position (as in FIGS. **4-5**) results in a stretching of the incision along the third axis. This stretching increases the length of the incision from a length approximately equal to the length L of a single blade (e.g., the first blade **18**) to a length L' greater than the length L of a single blade (e.g., the first blade **18**). As can be seen in FIGS. **4-5**, the retractor **10** is in the opened position, meaning that the first blade **18** is relatively separated from the second blade **38** along the third axis **56**. As the blade assembly **16** moves along the directional arrow B and blade assembly **36** moves along the directional arrow C, they exert force in the direction of lines B and C, respectively.

In FIGS. **6-7**, the retractor **10** is shown in the "rotated position," meaning that the first blade **18** is rotated relative to the third blade **46** and/or the second blade **38** is rotated relative to the third blade **46** and/or rotated with respect to the third blade **46** in a first position. While the application uses the phrase "the rotated position," it is understood that one or more positions may be described as rotated. For instance, the first blade **18** can be rotated at any angle relative to the third blade **46** greater than zero (e.g., 5°, 10°, 15°, 20°, 25°, 30°, 35°, 40°, 45°, 50°, 55°, 60°, 65°, 70°, 75°, 80°, 85°, 90°, 95°, 100°, 105°, 110°, 115°, 120°, 125°, 130°, 135°, 140°, 145°, 150°, 155°, 160°, 165°, 170°, 175°, 180°, between 10-40°, between 20-50°, between 30-60°, between 40-70°, between 50-80°, between 60-90°, between 70-100°, between 80-110°, etc.), the second blade **38** can be rotated at any angle relative to the third blade **46** greater than zero (e.g., 5°, 10°, 15°, 20°, 25°, 30°, 35°, 40°, 45°, 50°, 55°, 60°, 65°, 70°, 75°, 80°, 85°, 90°, 95°, 100°, 105°, 110°, 115°, 120°, 125°, 130°, 135°, 140°, 145°, 150°, 155°, 160°, 165°, 170°, 175°, 180°, between 10-40°, between 20-50°, between 30-60°, between 40-70°, between 50-80°, between 60-90°, between 70-100°, between 80-110°, etc.), the first blade **18** can be rotated approximately the same angle as the second blade **38**, the first blade **18** can be rotated a different angle as the second blade **38**, wherein the width W' in the rotated position is greater than the incision width or the width of any of the blades **18**, **38**, **46**, or other rotated positions.

The width W' of the three blades **18**, **38**, **46** in this configuration is greater than the width W of any one blade, such as the width of the first blade **18** and the rail **64**. The first blade **18** can rotate in a clockwise direction about the first axis **52**. The second blade **38** can rotate in a counter-clockwise direction about the second axis **54**. The motion of the first blade **18** can be independent of the motion of the second blade **38**. In other embodiments, the motion of the first blade **18** can be coupled to the motion of the second blade **38** such that rotation is controlled by a single rotation mechanism.

In the illustrated embodiment, the first blade **18** is rotated by a first rotation mechanism **20** and the second blade **38** is rotated by a second rotation mechanism **40**. In some embodi-

ments and methods of use, the first blade **18** can rotate in an opposite direction as the second blade **38** such that both blades open relative to the third blade **46**. The first rotation mechanism **20** can be identical, substantially similar, or a mirror image of the second rotation mechanism **40**. One embodiment of the first rotation mechanism **20** is shown in FIG. **11-13**. Other embodiments are contemplated for rotating the first and/or second blades (e.g., various linkages, hinges and/or cams).

Turning the first rotation mechanism **20** about the first axis **52** in the direction of adjustment arrow D, results in rotation of the first blade **18**. Turning the second rotation mechanism **40** about the second axis **54** in the direction of adjustment arrow E, results in rotation of the second blade **38**, respectively, as depicted in FIG. **7**. As shown in FIG. **7**, rotating the first blade **18** causes the first blade **18** to exert force in the direction of direction arrow F, while rotating the second blade **38** causes the second blade **38** to exert force in the direction of direction arrow G. In some such embodiments, the first axis **52** and second axis **54** may be substantially coplanar with one another. Indeed in some embodiments, the first axis **52** and second axis **54** are not only coplanar but also substantially parallel to one another. In particular embodiments, the first axis **52** and second axis **54** are coplanar with, parallel to, or at some pre-determined skew angle with respect to one another.

In the illustrated embodiment, the first blade **18** is rotated and/or the second blade **38** is rotated after the first blade **18** is translated relative to the third blade **46** and the second blade **38** is translated relative to the third blade **46**. Thus, after insertion in an incision of the blades **18, 38, 46** in the closed position, the retractor **10** is opened by the first blade **18** and the second blade **38** translating relative to the third blade **46** along the third axis **56** to achieve the opened position. Then the first blade **18** is rotated relative to the third blade **46** about the first axis **52** and/or the second blade **38** is rotated about the second axis **54** relative to the third blade **46** to achieve the rotated position. However, this depicts only some methods of use.

In some methods, the first blade **18** and/or the second blade **38** is rotated before the first blade **18** is translated relative to the third blade **46** and the second blade **38** is translated relative to the third blade **46**. Thus, after insertion in an incision of the blades **18, 38, 46** in the closed position, the first blade **18** is rotated about the first axis **52** relative to the third blade **46** and/or the second blade **38** is rotated about the second axis **54** relative to the third blade **46** to achieve the rotated position. Then the retractor **10** is opened by the first blade **18** and the second blade **38** translating relative to the third blade **46** along the third axis **56** to achieve the opened position. Then, if needed, the first blade **18** and/or the second blade **38** is rotated again relative to the third blade **46** to achieve the rotated position (e.g., another rotated position within the broad definition of the "rotated position").

The rotated position creates and maintains an aperture in the incised tissue that is wider W' (i.e. dimensionally larger in a direction perpendicular or oblique to the direction of the incision) than the incision. If the first blade **18** and/or second blade **38** are rotated after the blades **16, 38** have been translated relative to the third blade, then the retractor **10** creates and maintains an aperture in the incised tissue that is both longer L' due to the translation (i.e. dimensionally larger in the direction of the incision,) and wider W' due to the rotation (i.e. dimensionally larger in a direction perpendicular or oblique to the direction of the incision) than the incision.

It is to be understood that, while this description is especially apt where the incision is a straight line incision of about 0.1 to about 3 inches in length, it can apply to any shape of incision (e.g. an arc, a sinusoid, etc.) of any length. In particular embodiments, the contemplated size of the incision is about 0.5 to 2 inches in length and the blades **18, 38, 46** are appropriately sized so that when the retractor **10** is in the closed position the blade blades **18, 38, 46** fit lengthwise within the incision without requiring substantial stretching of the incised tissue prior to opening of the retractor **10**. Thus, in some embodiments, the blades **18, 38, 46** are sized to snugly fit within the incision when the retractor **10** is in the closed position.

In FIGS. **8-9**, the retractor **10** is shown in the "pivoted position," meaning that the first blade **18** is pivoted relative to the third blade **46** and/or the second blade **38** is pivoted relative to the third blade **46**. While the application uses the phrase "the pivoted position," it is understood that one or more positions may be described as pivoted. For instance, the first blade **18** can be pivoted at any angle relative to the third blade **46** greater than zero (e.g., 5°, 10°, 15°, 20°, 25°, 30°, 35°, 40°, 45°, 50°, 55°, 60°, 65°, 70°, 75°, 80°, 85°, 90°, 95°, 100°, 105°, 110°, 115°, 120°, 125°, 130°, 135°, 140°, 145°, 150°, 155°, 160°, 165°, 170°, 175°, 180°, between 10-40°, between 20-50°, between 30-60°, between 40-70°, between 50-80°, between 60-90°, between 70-100°, between 80-110°, etc.), the second blade **38** can be pivoted at any angle relative to the third blade **46** greater than zero (e.g., 5°, 10°, 15°, 20°, 25°, 30°, 35°, 40°, 45°, 50°, 55°, 60°, 65°, 70°, 75°, 80°, 85°, 90°, 95°, 100°, 105°, 110°, 115°, 120°, 125°, 130°, 135°, 140°, 145°, 150°, 155°, 160°, 165°, 170°, 175°, 180°, between 10-40°, between 20-50°, between 30-60°, between 40-70°, between 50-80°, between 60-90°, between 70-100°, between 80-110°, etc.), the first blade **18** can be pivoted approximately the same angle as the second blade **38**, the first blade **18** can be pivoted a different angle as the second blade **38**, wherein the length L'' and/or the width W'' in the pivoted position is greater than the incision length or width or the length or width of any of the blades **18, 38, 46**, or other pivoted positions.

The width W'' of the three blades **18, 38, 46** in this configuration is greater than the width W of any one blade, such as the width of the first blade **18** and the rail **64**. The length L'' of the three blades **18, 38, 46** in this configuration is greater than the length L of any one blade, such as the length of the first blade **18**. The first blade **18** can pivot in a clockwise direction about the fourth axis **58**. The second blade **38** can pivot in a counterclockwise direction about the fifth axis **60**. The motion of the first blade **18** can be independent of the motion of the second blade **38**. In other embodiments, the motion of the first blade **18** can be coupled to the motion of the second blade **38** such that pivoting is controlled by a single pivot mechanism. The pivoted position creates and maintains an aperture in the incised tissue that is both longer L'' (i.e. dimensionally larger in the direction of the incision,) and wider W'' (i.e. dimensionally larger in a direction perpendicular or oblique to the direction of the incision) than the incision.

In the illustrated embodiment, the fourth axis **58** is perpendicular to the first axis **52**. The first blade **18** can rotate about the first axis **52** and pivot about the fourth axis **58**. This provides at least two degrees of freedom for the first blade **18** and allows the first blade **18** to be positioned in a variety of locations within the incision. In the illustrated embodiment, the fifth axis **60** is perpendicular to the second axis **54**. The second blade **38** can rotate about the second axis **54** and pivot about the fifth axis **60**. This provides at

least two degrees of freedom for the second blade **38** and allows the second blade **38** to be positioned in a variety of locations within the incision. The fourth axis **58** and the fifth axis **60** are perpendicular to the third axis **56**. The movement along the third axis **56** provides an extra degree of freedom.

In the illustrated embodiment, the first blade **18** is pivoted by a first pivot mechanism **22** and the second blade **38** is pivoted by a second pivot mechanism **42**. The first blade **18** can pivot in an opposite direction as the second blade **38** such that both blades open relative to the third blade **46**. The first pivot mechanism **22** can be identical, substantially similar, or a mirror image of the second pivot mechanism **42**. One embodiment of the first pivot mechanism **22** is shown in in FIGS. **14-15**. Other embodiments are contemplated for providing the described pivoting motions such as, for example, various linkages, cams and/or hinges.

Pivoting the first pivot mechanism **22** about the fourth axis **58** in the direction of adjustment arrow H, results in rotation of the first blade **18**. Turning the second pivot mechanism **42** about the fifth axis **60** in the direction of adjustment arrow I, results in rotation of the second blade **38**, respectively, as depicted in FIG. **9**. Pivoting the first blade **18** causes the first blade **18** to exert force in the direction of direction arrow J, while pivoting the second blade **38** causes the second blade **38** to exert force in the direction of direction arrow K.

In some examples, the first axis **52** is substantially perpendicular or perpendicular to the fourth axis **58**. In particular embodiments, the first axis **52** is at some pre-determined skew angle with respect to the fourth axis **58**. In some examples, the second axis **54** is substantially perpendicular or perpendicular to the fifth axis **60**. In particular embodiments, the second axis **54** is at some pre-determined skew angle with respect the fifth axis **60**. In some examples, the third axis **56** is substantially perpendicular or perpendicular to the fourth axis **58**, the fifth axis **60** or both the fourth axis **58** and the fifth axis **60**. In some embodiments, the third axis **56** is substantially perpendicular or perpendicular to both the fourth axis **58** and the fifth axis **60**. In some embodiments, the third axis **56** is perpendicular or substantially perpendicular to the fourth axis **58**, the fifth axis **60** or both the fourth axis **58** and the fifth axis **60**. In some embodiments, the third axis **56** is perpendicular or substantially perpendicular to both the fourth axis **58** and the fifth axis **60**.

In some embodiments, the third blade **46** can be pivoted about a seventh axis (not shown) that is parallel to the third axis **56** and extends from near the connection between the third blade **46** and the body **26**. In some embodiments, the connector **28** can have a hinge that pivots the third blade **46**. The third blade **46** can be pivoted at any angle relative to the vertical plane greater than zero (e.g., 5°, 10°, 15°, 20°, 25°, 30°, 35°, 40°, 45°, 50°, 55°, 60°, 65°, 70°, 75°, 80°, 85°, 90°, 95°, 100°, 105°, 110°, 115°, 120°, 125°, 130°, 135°, 140°, 145°, 150°, 155°, 160°, 165°, 170°, 175°, 180°, between 10-40°, between 20-50°, between 30-60°, between 40-70°, between 50-80°, between 60-90°, between 70-100°, between 80-110°, etc.). The third blade **46** can be pivoted a same angle or a different angle as the first blade **18** and/or second blade **38**, wherein the length L" and/or the width W" in the pivoted position is greater than the incision length or width or the length or width of any of the blades **18**, **38**, **46**, or other pivoted positions. The seventh axis is described in some embodiments as substantially parallel or parallel to the third axis **56**. In other embodiments, the seventh axis can be at some pre-determined skew angle with respect to the third axis **56**.

The width W" of the three blades **18**, **38**, **46** in this configuration is greater than the width W of any one blade, such as the width of the third blade **46**. The length L" of the three blades **18**, **38**, **46** in this configuration is greater than the length L of any one blade, such as the length of the third blade **46**. The first blade **18** can pivot in a clockwise direction about the fourth axis **58**. The second blade **38** can pivot in a counterclockwise direction about the fifth axis **60**. The third blade **46** can pivot about the seventh axis toward the proximal direction. The motion of the third blade **46** can be independent of the motion of the first blade **18** and the second blade **38**. In other embodiments, the motion of the third blade **46** can be coupled to the motion of the first blade **18** and/or the second blade **38** such that pivoting is controlled by a single pivot mechanism. The pivoted position creates and maintains an aperture in the incised tissue that is both longer L" (i.e. dimensionally larger in the direction of the incision,) and wider W" (i.e. dimensionally larger in a direction perpendicular or oblique to the direction of the incision) than the incision.

The third blade **46** can be pivoted by a pivot mechanism that is identical or substantially similar to the pivot mechanism described herein for the first blade **18** and second blade **38**. Other embodiments are contemplated for providing the described pivoting motions such as, for example, various linkages, cams, hinges, gears and/or levers.

In the illustrated embodiment, the first blade **18** is pivoted and/or the second blade **38** is pivoted after the first blade **18** is rotated and/or the second blade **38** is rotated and after the first blade **18** is translated relative to the third blade **46** and the second blade **38** is translated relative to the third blade **46**. Thus, after insertion in an incision of the blades **18**, **38**, **46** in the closed position, the retractor **10** is opened by the first blade **18** and the second blade **38** translating along the third axis **56** relative to the third blade **46** to achieve the opened position. Then the first blade **18** is rotated about the first axis **52** relative to the third blade **46** and/or the second blade **38** is rotated about the second axis **54** relative to the third blade **46** to achieve the rotated position. Then the first blade **18** is pivoted about the fourth axis **58** relative to the third blade **46** and/or the second blade **38** is pivoted about the fifth axis **60** relative to the third blade **46** to achieve the pivoted position. In some embodiments, the third blade **46** is pivoted about the third axis **56** toward the proximal direction. However, this depicts only some methods of use.

In some methods, the first blade **18** is pivoted and/or the second blade **38** is pivoted and/or the third blade **46** is pivoted before the first blade **18** and/or the second blade **38** is rotated. In some methods, the first blade **18** is pivoted and/or the second blade **38** and/or the third blade **46** is pivoted before the first blade **18** is translated relative to the third blade **46** and the second blade **38** is translated relative to the third blade **46**.

FIGS. **10-15** show embodiments of the actuator **74**, the rotation mechanism **20**, and the pivot mechanism **22**. The actuator **74** is a device for translating the first blade **18** and the second blade **38** about the third axis **56**. The rotation mechanism **20** is a device for rotating the first blade **18** about the first axis **52**. The rotation mechanism **40** can be identical, substantially similar or a mirror image of the rotation mechanism **20**. The pivot mechanism **22** is a device for pivoting the first blade **18** about the fourth axis **58**. The pivot mechanism **42** can be identical, substantially similar or a mirror image of the pivot mechanism **22**. Other configurations are possible for rotating the blades as described herein e.g., various levers, knobs, cams, etc.

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FIG. 10 shows one embodiment of the actuator 74. The actuator 74 comprises a screw 76. The screw 76 can be configured to mate with a washer (not shown) in the body 26. The washer allows the screw 76 to rotate without translation (e.g., rotate in place). The actuator 74 comprises a block 78. The block 78 has a through lumen 80. In the illustrated embodiment, the through lumen 80 is threaded. In some embodiments the through lumen 80 is not threaded. The through lumen 80 is sized to accept the screw 76. The through lumen 80 can include a counter sunk opening sized to accept the head of the screw 76.

The first arm 12 has a first mating surface 82 and the second arm 32 has a second mating surface 84. The mating surfaces 82, 84 interact with the side surfaces of the block 78. In the illustrated embodiment, the mating surfaces 82, 84 are ramped or angled inward and the side surfaces of the block 78 are flat. In other embodiments, the mating surfaces 82, 84 are flat and the side surfaces of the block 78 are ramped or angled inward. Upon rotation of the screw 76, the block 78 traverses along the length of the screw 76 toward the body 26 in the direction of arrow A. The side surfaces of the block 78 abut and interact with the mating surfaces 82, 84 of the arms 12, 32 to exert a force on the arms 12, 32.

In some embodiments, the pivot 72 can include a pivot post 86. The pivot post 86 extends along a longitudinal axis. As can be seen in FIG. 10, the proximal end 24 of the first arm 12 has a first connecting hole 88 sized to accept the pivot post 86 and the proximal end 44 of the second arm 32 has a second connecting hole (not shown) sized to accept the pivot post 86. Upon rotation of the screw 76, the first arm 12 and the second arm 32 rotate about the longitudinal axis of the pivot post 86. The first arm 12 rotates clockwise and the second arm 32 rotates counterclockwise about the longitudinal axis of the pivot post 86. This causes the first blade assembly 16 and the second blade assembly 36 to generally translate along a third axis 56.

The retractor 10 can include a spring 94. In the illustrated embodiment, the spring 94 wraps around the pivot post 86. In some embodiments, the first connecting hole 88 and/or the second connecting hole are sized to accept a portion of the spring 94, for instance the portion of the spring that is wrapped around the pivot post 86. In some embodiments, the spring 94 biases the first arm 12 and the second arm 32 in the closed position. The actuator 74 overcomes this biasing force to pivot the first arm 12 and the second arm 32 about pivot 72, which causes the first blade assembly 16 and the second blade assembly 36 to generally translate along a third axis 56. The spring 94 tends to bias the arms 12 and 32 together. In other embodiments, the spring 94 biases the first arm 12 and the second arm 32 apart. This biasing force decreases the force needed by the actuator 74 to translate the first blade assembly 16 and the second blade assembly 36 along the third axis 56.

FIGS. 11-12 are perspective views of the second blade 38 in the closed position and the rotated position, respectively. FIG. 13 is an exploded view of the rotation mechanism 40. Referring back to FIGS. 1, 6-7, these figures depict an embodiment of a second blade assembly 38, which comprises the second blade 38. The second blade assembly 36 comprises a hub 98. The hub 98 is coupled to the distal end 34 of the second arm 32. In the illustrated embodiment, the hub 98 houses both the rotation mechanism 40 and the pivot mechanism 42. Also shown in these views is the second axis 54 to achieve the rotated position. In some embodiments, the second blade 38 is adapted to rotate about the second axis 54. In some embodiments, this added degree of freedom permit the second blade 38 to be rotated outward so that the

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second blade 38 is farther apart from the third blade 46. The third blade 46, in some embodiments, remains stationary. FIG. 6 shows a perspective view of the retractor 10 with the first blade 18 and the second blade 38 in a rotated position. FIG. 7 shows a top view of FIG. 6.

The hub 98 can have a first connecting hole 100. The first connecting hole 100 can be non-threaded. The hub 98 is coupled to an inner barrel 102. In the illustrated embodiment the inner barrel 102 is integrally formed with the second blade 38. In other embodiments, the inner barrel 102 can be coupled with the second blade 38. The second blade 38 can be connected to the second bridge 96 which can be connected to the inner barrel 102. The inner barrel 102 can be sized to be accepted within the first connecting hole 100 of the hub 98.

Referring to FIGS. 11-13, the second rotation mechanism 40 can include a screw 104. The second rotation mechanism 40 can include a collar 106. The collar 106 can include a threaded bore 108 sized to receive the screw 104. The screw 104 and the collar 106 are sized to be received in a lumen 110 of the inner barrel 102. The inner barrel 102 can have a first slot 112 and a second slot 114 cut into the upper portion 116 of the inner barrel 102. The first slot 112 can be offset 180 degrees from the second slot 114. Specifically, the upper portion 116 of the inner barrel 102 is that portion of the inner barrel 102 above the highest point at which the second bridge 96 connects to the inner barrel 102. The first slot 112 and second slot 114 can extend from near the top of the inner barrel 102 to the bottom of the inner barrel 102. The slots 112, 114 extend diagonally across the upper portion 116. Although two slots 112, 114 are shown, other configurations are contemplated (e.g., one slot, three slots, four slots, five slots). The one or more slots may have the same slope and extend in the same direction.

The inner barrel 102 can have an engagement groove 118 circumscribing the inner barrel 102 above the slots 112, 114. The hub 98 can have a complementary engagement groove 120 circumscribing the connecting hole 100. An appropriately sized retention member (not shown) such as an o-ring can be received within the grooves 118, 120. The retention member allows the inner barrel 102 to rotate but not translate within the first connecting hole 100.

The lumen 110 can have an engagement groove 124 circumscribing the lumen 110 above the slots 112, 114. The screw 104 can have a complementary engagement groove 126 circumscribing the head of the screw 104. An appropriately sized retention member 128 such as an o-ring can be received within the grooves 124, 126. The retention member 128 allows the screw 104 to rotate but not translate within the inner barrel 102.

FIGS. 11-13 further depict a first connector pin 134 and second connector pin 136. The number of pins equals the number of slots. The connector pins 134, 136 extend outward from the collar 106. In the illustrated embodiment, the first connector pin 134 is offset 180 degrees from the second connector pin 136. Other configurations are contemplated. The first connector pin 134 is sized to extend through the first slot 112 and the second connector pin 136 is sized to extend through the second slot 114.

The screw 104 fits within the threaded bore 108 of the collar 106, as depicted in FIGS. 11-12. In this configuration, the first slot 112 forms a passage through which the first connector pin 134 fits. The second slot 114 forms a passage through which the second connector pin 136 fits. As depicted in FIG. 11, the second blade 38 can be in the closed position when the first connector pin 134 is at the bottom of the first slot 112 and the second connector pin 136 is at the bottom

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of the second slot 114. In this configuration, as shown in FIG. 4 it is seen that the second blade 38, and the third blade 46 stack to form a substantially planar blade set.

One skilled in the art will recognize that rotating the screw 104 can cause the collar 106 to translate up and down. The retention member 128 prevents the screw 104 from translating. The connector pins 134, 136 can be rigidly coupled to the collar 106. At least one connector pin 134 or 136 can be retained in the channel 122 of the hub 98, which prevents the collar 106 from rotating. Rotating the screw 104 will force the collar 106 to rise since the screw 104 cannot translate and the collar 106 cannot rotate. The connector pins 134, 136 will similarly rise with the collar 106. As the connector pins 134, 136 rise, they act upon the slots 112, 114. Due to the shape of the slots 112, 114, the inner barrel 102 will rotate as the connector pins 134, 136 rise. Rotation of the inner barrel 102 also rotates the second blade 38. In other words, rotating the screw 104 forces the connector pins 134, 136 to rise and act upon the slots 112, 114, thereby causing the inner barrel 102 to rotate, and also rotate the second blade 38 about the second axis 54. One skilled in the art will understand that the first blade 18 can be rotated in the other direction (e.g., counterclockwise to close the first blade 18). Starting with the connector pins 134, 136 at the top of slots 112, 114, translating the collar 106 downward will force the connector pins 134, 136 to move down the length of the screw 104 in the slots 112, 114, thereby causing the inner barrel 102 to rotate, thereby causing the second blade 38 to rotate about the second axis 54.

As can be seen in FIG. 13, the assembly of inner barrel 102, the collar 106, the screw 104, and the connector pins 134, 136, fits through the first connecting hole 100 of the hub 98. As can be seen in FIGS. 6-7, the head of the screw 104 is visible through the hub 98 allowing the screw 104 to be manipulated. One of skill in the art will appreciate that the connector pins 134, 136 engage the slots 112, 114, thereby permitting the inner barrel 102 to freely turn about the second axis 54. The retention member (not shown) prevents the inner barrel 102 from moving up or down along the second axis 54. The retention member 128 can prevent the screw 104 from moving up or down along the second axis 54. Turning the screw 104 about the second axis 54 in one direction can cause the collar 106 to move upward along the second axis 54, while turning the screw 104 in the opposite direction can cause the collar 106 to move downward along the second axis 54. As explained above, movement of the collar 106 forces movement of the connector pins 134, 136 up and down the second axis 54. Movement of the connector pins 134, 136 in one direction can create force in one direction on the slots 112, 114 in the inner barrel 102 causing the inner barrel 102 to rotate. The screw 104 can be turned to rotate the second blade 38 toward or away from the third blade 46. In the illustrated embodiment, the second blade 38 is connected to a second bridge 96, which in turn is connected to the inner barrel 102 such that rotating the inner barrel 102 about second axis 54 clockwise can result in the second blade 38 also turning to clockwise.

The first blade assembly 16 can be substantially similar to the embodiment described herein. For instance, the first blade assembly 16 can include an inner barrel similar to inner barrel 102, screw similar to screw 104, collar similar to collar 106, and connecting pins similar to connecting pins 134, 136. In some embodiments, the first blade assembly 16 rotates clockwise about the first axis 52 away from the third blade 46 and the second blade assembly 36 rotates counterclockwise about the second axis 54 away from the third blade 46. In this configuration, the inner barrel of the second

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blade assembly 36 can be a mirror image of the first blade assembly 16. For instance, the first blade assembly 16 can have one slot which is the mirror image of first slot 112 and another slot which is the mirror image of second slot 114. This slot configuration allows the first blade 18 to rotate clockwise, the opposite direction as the second blade 38 described herein. The function of the connector pins of the first blade assembly 16 and the method of rotation can be substantially similar.

FIG. 14 is a perspective view of the first blade assembly 16 in the pivoted position. FIG. 15 is an exploded view of the pivot mechanism 22. Referring back to FIGS. 8-9, these figures depict an embodiment of a first blade assembly 16, which comprises the first blade 18. The first blade assembly 16 comprises the hub 97. The hub 97 can be similar, identical or a mirror image of the hub 98 described with respect to FIGS. 11-13. The hub 97 is coupled to the distal end 14 of the first arm 12. In the illustrated embodiment, the hub 97 houses both the rotation mechanism 20 and the pivot mechanism 22. The hub 97 can have a second connecting hole 142 and a third connecting hole 144. The second connecting hole 142 can be non-threaded. The third connecting hole 144 can be threaded.

The distal end 14 of the first arm 12 can include a post 146. The post 146 can be accepted into a bore (not shown) of the hub 97. The post 146 of the first arm 12 and the bore of the hub 97 interact to couple the first arm 12 to the first blade assembly 16. The post 146 has a round cross-section but other shapes are contemplated. The post 146 has a groove 150 circumscribing post 146. The groove 150 is along the distal end of the post 146 that extends into the bore. The second connecting hole 142 is sized to accept a pin 152. The upper portion of the pin 152 fits within the second connecting hole 142. The lower portion of the pin 152 fits within the groove 150 of the post 146.

The distal end 14 of the first arm 12 can include a ledge 154. The ledge 154 can be adjacent to a surface of the hub 98. Unlike the post 146, the ledge 154 is not accepted into the hub 98. The ledge 154 has a substantially square cross-section but other shapes are contemplated. The first pivot mechanism 22 can include a screw 156. The screw 156 is accepted into the third connecting hole 144 which is threaded. The bottom portion of the screw 156 abuts the ledge 154. The ledge 154 prevents the screw 156 from translating when the screw 156 is rotated.

One skilled in the art will recognize that rotating the screw 156 can cause the hub 97 to pivot about the post 146. Rotating the screw 156 forces the hub 97 to rise since the screw 156 cannot translate. As the hub 97 rises, the pin 152 will follow the groove 150 of the post 146. Due to the interaction of the pin 152 with the groove 150, the hub 97 can pivot about the post 146 when the screw 156 is rotated. Pivoting of the hub 97 can result in the pivoting of the inner barrel (identical, similar or a mirror image of inner barrel 102) received in the first connecting hole (identical, similar or a mirror image of first connecting hole 100). Pivoting the inner barrel 102 can also pivot the first blade 18. In other words, rotating the screw 156 will cause the hub 97 to pivot about the post 146, thereby pivoting the inner barrel coupled to the first blade 18 and the first blade 18. A spring 158 can act upon the hub 97 to bias the hub 97 toward the unscrewed (i.e., not tilted) configuration. One skilled in the art will recognize that the first blade 18 can be pivoted in either direction based on the rotation of the screw 154. The longitudinal axis of the post 146 corresponds to the fourth axis 58.

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The second blade assembly 36 can be similar to the embodiments described herein. For instance, the second blade assembly can include a post similar to post 146, a pin similar to pin 152, and a screw similar to screw 156. In some embodiments, the first blade assembly 16 rotates counter-clockwise about the post 146 and the second blade assembly 36 rotates clockwise about a similar post. In some configurations, the second blade assembly 36 can be a mirror image of the first blade assembly 16. For instance, the second connecting hole of the second blade assembly 36 can be closer to the third blade 46 and the third connecting hole of the second blade assembly 36 can be further away from the third blade 46. These configurations of the connecting holes allow the second blade 38 to pivot in the opposite direction as the first blade 18 described herein. The function of the pins and the posts of the second blade assembly 36 and the method of rotation of the screw can be similar.

The retractor 10 can be in the "slid position," meaning that the first arm 12 and the second arm 32 are displaced in the proximal-distal direction relative to the third blade 46 along a sixth axis 62. While the application uses the phrase "the slid position," it is understood that one or more positions may be described as slid. For instance, the first arm 12 can be slid at any position along the body 26, the second arm 32 can be slid at any position along the body 26, the first arm 12 can be slid approximately the same distance as the second arm 32, wherein the width in the slid position is greater than the incision width or the width of any of the blades 18, 38, 46, or other slid positions.

FIG. 16 depicts an embodiment of a slide mechanism 162 that provides an additionally degree of freedom. The slide mechanism 162 can include a carriage 164. The carriage 164 can be attached to the body 26 via a track 166. In some embodiments, the track 166 can be linear and/or parallel to the width of the blades 18, 38, 46. The track 166 can extend from the proximal end of body 26 to the distal end of the body 26, or over a portion therewithin. The first arm 12 and the second arm 32 can be coupled to the carriage 164. In the illustrated embodiment, the pivot 72 can be coupled to the carriage 164. The slide mechanism 162 can include an actuator (not shown) that permits the carriage 164 to slide along the track 166. The track 166 can define the sixth axis 62. In some embodiments, the actuator can include a screw that abuts a proximal end of the carriage 164. Rotation of the actuator causes the carriage 164 to translate from the proximal end of the body 26 to the distal end of the body 26 along the sixth axis 62. The slide mechanism 162 permits the arms 12, 32 to extend a greater distance from the distal end of the body 26. The slide mechanism 162 permits the first blade 18 and the second blade 38 to slide relative to the third blade 46. The third blade 46 is not coupled to the sliding mechanism, but is coupled to the body 26 described herein. This permits the first blade 18 and the second blade 38 to slide relative to the third blade 46. The slide mechanism 162 permits the incision to be stretched along the width of the incision to create an opening width greater than width W".

One skilled in the art will recognize that slide mechanism 162 causes the first arm 12 and the second arm 32 to slide relative to the body 26. Sliding the first arm 12 and the second arm 32 will also slide the first blade 18 and the second blade 38. The pivot 72 can be received within the carriage 164, allowing the arms 12, 32 to move about the pivot 72 and allow the blade assemblies 16, 36 to translate along the third axis 56. The actuator 74 can translate the blades 18, 38 irrespective of the location of the carriage 164. The rotation mechanisms 20, 40 can rotate the blades 18, 38 irrespective of the location of the carriage 164. The pivot

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mechanisms 22, 42 can pivot the blades 18, 38 irrespective of the location of the carriage 164. One skilled in the art will recognize that the carriage 164 can slide in either direction.

In some embodiments, the third blade 46 can be coupled to the carriage 164 and can be movable relative to the arms 12, 32, which can be coupled to the body 26. Rotation of the actuator can cause the carriage 164 to translate from the distal end of the body 26 to the proximal end of the body 26 along the sixth axis 62. The slide mechanism 162 permits the third blade 46 to move a distance toward the proximal end of the body 26, permitting the incision to be stretched along the width of the incision to create an opening width greater than width W". The pivot mechanism of the third blade 46 can pivot the third blade 46 irrespective of the location of the carriage 164. One skilled in the art will recognize that the carriage 164 can slide in either proximal or distal directions.

Some embodiments contemplate kits comprising a retractor 10. In some embodiments, the kit comprises a plurality of removable and exchangeable blade assemblies 16, 36. Each blade assembly may comprise a different actuator, a different rotation mechanism, a different pivot mechanism and/or a different slide mechanism. Each blade assembly may comprise a different blade. In some embodiments, the kit comprises at least three blade assemblies having amongst the three blade assemblies at least two distinct blade configurations. In other embodiments, the kit comprises from 3 to 12 blade assemblies having amongst the several blade assemblies from 2 to 12 distinct blade configurations. In some embodiments, the kit comprises at least two pairs of identical, substantially similar, or mirror image blade assemblies. In some embodiments, the kit comprises at least two pairs of mirror image blade assemblies. In other embodiments, the kit comprises from 2 to 10, especially about 2 to 5 such pairs of blade assemblies.

In some embodiments, the retractor 10 may be provided to a surgeon or surgical personnel in the form of a kit comprising additional surgical articles and optionally instructions for the use and handling of the retractor. Such additional surgical articles may include one or more of: scalpels, suture needles, pedicle screws, suture material, spinal implant material, spinal fusion rods, biocompatible adhesive and closure staples.

In some embodiments, the blades 18, 38, 46 are removable. In some embodiments, the blades 18, 38, 46 may take on a variety of shapes and sizes. In some embodiments, a kit is provided comprising a plurality of retractors having blades of various sizes, shapes or both. In some embodiments, a kit is provided comprising one or more arms and two or more blade assemblies (optionally of varying blade sizes and/or shapes). In some embodiments, a kit is provided comprising a retractor, optionally more than two blades assemblies, at least two of which differ from one another in size, shape or both, and one or more pedicle screws for performing lumbar surgery. Thus, a variety of surgical kits for performing surgery, especially back surgery, are contemplated and methods of using the retractor to perform surgery, especially back surgery, are contemplated.

FIGS. 17A-17D illustrate a probe 400 and a method for its use in conjunction with the retractor 10. FIG. 17A illustrates a probe 400 and a portion of a spine, including a first vertebra 440, a second vertebra 450, and a disc 460 disposed between the first vertebra 440 and the second vertebra 450. The probe 400 can have a probe body 410, a proximal end 413, a distal end 412, an anchor tip 430, and a distal shoulder 420. The anchor tip 430 can be disposed at the distal end 412 of the probe body 410. The distal shoulders 420 can be located at the distal end 412 of the probe 400 at the base of

the anchor tip **430**. In modified embodiments, the probe **400** can have a distal end of a different shape. For example, the distal end **412** can be formed without the shoulder **420** and/or without the tip **430** and/or one of both elements can be modified in shape.

In some embodiments, the probe **400** can be rectangular in horizontal cross section (i.e., the plane bisecting the probe **400** perpendicular to the axis formed by the proximal end **413** and the distal end **412**). In other embodiments, the probe **400** can be circular in horizontal cross section or oval cross section. FIG. 19A-19I illustrate some representative cross sectional shape the probe **400** can have, including: a circle (shown in FIG. 19A); an oval (shown in FIG. 19B); a triangle (shown in FIG. 19C); a flattened oval (shown in FIG. 19D); a thin flattened oval (shown in FIG. 19E); a rounded rectangle (shown in FIG. 19F); a thin rounded rectangle (shown in FIG. 19G); a rectangle (shown in FIG. 19H); and a thin rectangle (shown in FIG. 19I). In yet other embodiments, the probe **400** can be any other appropriate shape, including but not limited to square, triangular, and ellipsoid. A rectangular cross-sectional shape can include a shape in which the corners of the device are rounded and/or arrangements in which the adjacent sides are not exactly perpendicular (e.g., plus or minus 10 degrees, 5 degrees, 1 degree or 0.1 degrees from perpendicular) and/or when the sides of the probe have ridges, bends that deviate 10%, 5%, 1% or 0.1% from the width or length of a side. FIGS. 18A and 18B illustrate a probe **400** with circular cross section and a probe **400** with an oval cross section respectively.

In some embodiments, the probe **400** can be constructed out of a biocompatible metal, such as but not limited to stainless steel, titanium, and cobalt chrome moly. In other embodiments, the probe **400** can be constructed out of a biocompatible ceramic. In still other embodiments, the probe **400** can be constructed out of any stiff, biocompatible material, including such classes of materials as metals, ceramics, and polymers, or any combinations thereof.

In some embodiments, the probe **400** can have a vertical length (i.e., length from the distal end **412** to the proximal end **413**) in the range of about 5-50 cm, about 6-40 cm, about 7-30 cm, about 7-20 cm and about 8-10 cm or any other range which is appropriate to allow the probe **400** to function as desired. In some embodiments, the probe **400** can have a width in its largest, non-vertical dimension, in the range of about 5 mm-5 cm, about 6 mm-4 cm, about 7 mm-3 cm, and about 8 mm-2 cm, including about 1.5 cm.

In some embodiments, the distal shoulders **420** can extend horizontally in from the edges of the probe **400** in the range of about 0.1-5 mm, about 0.2-4 mm, about 0.3-3 mm, about 0.4-2 mm, about 0.5-1 mm, and about 0.6-0.8 mm. In some embodiments, the external corners where the distal shoulders **420** meet the vertical edges of the probe **400** can be squared. In other embodiments, the external corners where the distal shoulders **420** meet the vertical edges of the probe **400** can be rounded or smoothed. In some embodiments, the distal shoulders **420** can be machined flat on the bottom (particularly in such embodiments in which the probe **400** is a shape other than rectangular). In other embodiments, the distal shoulders **420** can be sharpened across their entire length to form a blade along their entire length. In other embodiments, the distal shoulders can be sharpened across only a portion of their length to form a blade along only a portion of their length. For example, in some embodiments, only half of each distal shoulder **420** is sharpened (e.g., either the half of the distal shoulders **420** abutting the anchor tip **430** or the half of the distal shoulders **420** abutting the edges of the probe **400**).

In some embodiments, the anchor tip **430** can extend downward from the distal end **412** of the probe **400**. In some embodiments, the anchor tip **430** can be substantially triangular (illustrated in FIG. 17A). In other embodiments, the anchor tip **430** can be substantially parabolic. In other embodiments, the anchor tip **430** can be a small cylindrical member, such as a trocar. In yet other embodiments, the anchor tip **430** can be any shape which allows anchoring of the probe **400** in tissue. In some embodiments, the edges of the anchor tip **430** can be machined to be substantially smooth. In other embodiments, the edges of the anchor tip **430** can be sharpened to form a blade.

In some embodiments, at least a portion of the vertical edges of the probe **400** can be sharpened. In some of these embodiments, the portion of the edges of the probe **400** which are sharpened can be disposed near the distal end **412** of the probe **400**. As a representative example, 1-5 cm of the edges of the probe **400** extending up from the distal end **412** and distal shoulders **420** can be sharpened to form a blade to facilitate insertion of the probe **400** into corporeal tissue of a patient.

In operation, the probe **400** can be inserted into a patient, preferably into an anchorable location, such as a collagenous tissue, bone, or vertebral disc. FIG. 17A illustrates the probe **400** being inserted into a patient (not fully shown) toward the spine (only a first vertebra **440**, second vertebra **450**, and disc **460** are illustrated in this representative example). The probe **400** illustrated in FIG. 17A is a thin, blade like rectangular probe **400** with a triangular anchor tip **430** and squared corners where the distal shoulders **420** meet the edges of the probe **400**. The structure of the probe **400** can facilitate its passage through tissues of a patient (e.g., psoas muscles) which can run parallel to the flat surfaces of the probe. In operation, a physician can select a location in which he desires to use a retractor **10** to form an operative channel in the tissues of the patient (the spine will be used in this example for illustration purposes only). A location is preferably selected that provides adequate access to an intervertebral disc space, yet minimizes the risk of injury to the nerves extending from the intervertebral foramen. After the surgeon selects the location for retractor **10** placement, he can make an incision in the skin and insert the probe **400** by placing the anchor tip **430** against the surface of the patient and applying pressure to the proximal end **413**. The physician can then continue to apply pressure, thereby pushing the probe **400** through the tissue of the patient, until the probe **400** is fully in place. In some embodiments, an imaging modality can be used during the insertion of the probe **400**. As a representative, non-limiting example, X-ray fluoroscopy can be used during insertion of the probe **400** to ensure correct placement. Any appropriate imaging modality can be used to monitor the placement of the probe **400**. In some embodiments, a surgeon can make an incision with another instrument, such as a scalpel, prior to the insertion of the probe **400**, into which the probe **400** is inserted. In some embodiments, a K-wire (i.e., guide wire) can first be anchored at the location for retractor **10** placement. The probe **400** can have a passage extending through its longitudinal length to receive the K-wire when the probe **400** is inserted at the surgical location. The K-wire advantageously provides improved accuracy in placement of the probe **400** and can also help stabilize the probe **400** during insertion through the patient tissue.

FIG. 17B illustrates the probe **400** fully in place in a patient. The probe **400** has been inserted into the side of the spinal column (here defined by a first vertebra **440**, a second vertebra **450**, and the disc **460** between them). FIG. 17B

illustrates the placement of the probe 400 in a location in which the anchor tip 430 can anchor the probe 400. As shown in FIG. 17B, the probe 400 has been inserted into the patient until the anchor tip 430 has sunk at least some distance into the disc 460 between the first vertebra 440 and second vertebra 450. The anchor tip 430 has sunk into the disc 460 up until the distal shoulders 420 of the probe 400. The distal shoulders 420 serve in this example to limit the possible insertion depth of the anchor tip 430 of the probe 400.

FIG. 17C illustrates the third blade 46 of the retractor 10 (as disclosed herein) and a placed probe 400. The third blade 46 can include a longitudinally extending slot 48 sized to accept the probe 40. The third blade 46 can fit substantially closely around the probe 400. The third blade can be any type of blade as described above, including but not limited to a substantially flat blade. An incision I having a length L is made in a suitable tissue, such as the skin overlying or in proximity to the lumbar region of the spine.

FIG. 17D illustrates the third blade 46 and placed probe 400 of FIG. 17C where the first blade 18 and the second blade 38 of the retractor 10 in their closed configuration have been placed near the third blade 46. The blades 18, 38, 46 will be in their stacked configuration when coupled. The blades 18, 38, 46 are in the closed position and aligned relatively parallel to one another. The connector 50 of the third blade 46 can couple with the connector 28 of the body 26. FIG. 17D shows the retractor 10 still in the closed position.

In some methods, the retractor 10 of FIG. 17D is manipulated to achieve the opened position, as shown and described in FIGS. 4-5. In the opened position, the incision can be stretched along the length of the incision to pull open the incision. In some methods of use, translation about the third axis 56 results in the retractor 10 opening: i.e. the first blade 18 and the second blade 38 move apart from one another in the general directions of directional arrows B, C, respectively. The incision can be stretched open in the direction of the directional arrows B and C so that it obtains a length L' greater than length L of the incision.

In some methods, the retractor 10 of FIG. 17D is manipulated to achieve the rotated position, as shown and described in FIGS. 6-7. In the rotated position, the incision can be stretched along the width of the incision. Turning the rotation mechanism 20, 40 in the direction of the arrows D and E about the first axis 52 and the second axis 54, respectively results in the rotating of the first blade 18 and the second blade 38 respectively, resulting in the widening of the incision. The aperture can be opened to a width W. If the retractor is previously opened as shown in FIG. 4-5, then the aperture would provide an access area of dimensions L' by W for surgical personnel to view the operating field, to pass instruments, sutures, implants and other surgical materials through the aperture.

In some methods, the retractor 10 of FIG. 17D is manipulated to achieve the pivoted position, as shown and described in FIGS. 8-9. In the pivoted position, the incision can be stretched along the width and/or length of the incision. Turning the pivot mechanism 22, 42 pivots the first blade assembly 16 and second blade assembly 36 in the direction of the arrows H and I about the fourth axis 58 and the fifth axis 60, respectively results in the pivoting of the first blade 18 and the second blade 38, further stretching the incision. The aperture can be opened to a length L" and a width W". The aperture can provide an access area of dimensions L" by

W" for surgical personnel to view the operating field, to pass instruments, sutures, implants and other surgical materials through the aperture.

In some methods, the retractor 10 of FIG. 17D is manipulated to achieve the slid position, as shown and described in FIG. 16. In the slid position, the incision can be stretched along the width of the incision. Moving the sliding mechanism 162 respectively results in the translation of the arms 12, 32, and therefore the translation of the blades 18, 38, causing the incision to open. The aperture A can be opened to a width wider than width W".

Reversal of the steps described above results in a final incision having substantially the same length L and essentially no width, like the original incision. By way of comparison, in order for a prior art device having a pair of blades to create such an aperture, the incision would have to have a length L' or L" and the blades would have to have a width of W' or W". The present retractor 10 permits the use of a much smaller incision to create the aperture. The present retractor 10 permits less invasive surgical methods, quicker and more comfortable recovery from surgery and potentially cost savings for the medical coverage provider.

The probe 400 can be removed prior to any of these steps or left in place during the procedure. The probe 400 can allow a surgeon to easily and quickly insert a retractor 10 without cutting an incision all the way to the surgery site prior to inserting the retractor 10 into the desired location to access the surgery site. Rather, the surgeon can quickly and easily insert the probe 400 into the desired location, anchor the probe 400 using the anchor tip 430 in the desired location, slip the third blade 46 of the retractor 10 around the probe 400, and then simply slip the retractor 10 into place. From this position, the first blade 18 and/or the second blade 38 can be moved in any of the ways described herein. From this position, the first arm 12 and the second arm 32 can be moved in any of the ways described herein.

In some embodiments, the probe 400 comprises at least one electrode, wherein the at least one electrode is capable of stimulating a nerve to provoke an electromyographic response in the nerve. FIG. 18C illustrates a probe 400 with an electrode 431 disposed at the distal end 412 of the probe 400 on the anchor tip 430. In some embodiments, only one electrode is used. In other embodiments, a plurality of electrodes can be used, including about 1-10 electrodes, about 2-8 electrodes, about 3-6 electrodes and about 4-5 electrodes. In some embodiments, at least one electrode can be disposed on the anchor tip 430. In some embodiments, at least one electrode can be disposed on the probe body 410. The electrode 431 can be allowed to any of the embodiments described herein.

In some embodiments, the probe 400 comprises an endoscope 499, wherein the endoscope 499 can comprise an imaging element 432 at the distal end 412 of the endoscope 499 as shown in FIG. 18D. In some of these embodiments, the endoscope 499 can be configured to both allow a surgeon to visualize the placement of the probe 400 as well as allow a surgeon to slide a retractor 10 down over the probe 400 and into place as described herein to create an operative channel. In some embodiments, the endoscope 499 can include an anchor tip 430. Such an endoscope can be applied to any of the embodiments described herein.

While certain embodiments have been shown and described herein, it will be obvious to those skilled in the art that such embodiments are provided by way of example only. Numerous variations, changes, and substitutions will now occur to those skilled in the art without departing from the invention. It should be understood that various alterna-

tives to the embodiments described herein may be employed. It is intended that the following claims define the scope of the invention and that methods and structures within the scope of these claims and their equivalents be covered thereby.

Further Features of this Disclosure are Given in the Following Numbered Clauses:

Clause 1. A retractor comprising:
 a first blade,
 a first rotation mechanism that rotates the first blade about a first axis,
 a second blade,
 a second rotation mechanism that rotates the second blade about a second axis,
 a first pivot mechanism that pivots the first blade about a fourth axis, wherein the fourth axis is skewed to the first axis;

a second pivot mechanism that pivots the second blade about a fifth axis, wherein the fifth axis is skewed to the second axis.

Clause 2. The retractor of clause 1, wherein the first and second axes are substantially coplanar with one another.

Clause 3. The retractor of clause 2, wherein the first and second axes are coplanar with one another.

Clause 4. The retractor of clause 1, further comprising an actuator that translates the first blade and second blade about a third axis.

Clause 5. The retractor of clause 4, wherein the third axis is substantially perpendicular to the first axis, the second axis or both the first and second axes.

Clause 6. The retractor of clause 4, wherein the third axis is substantially perpendicular to both the first axis and the second axis.

Clause 7. The retractor of clause 4, wherein the third axis is perpendicular to the first axis, the second axis or both the first and second axes.

Clause 8. The retractor of clause 4, wherein the third axis is perpendicular to both the first and second axes.

Clause 9. The retractor of clause 4, further comprising a device for locking the first and second blades in at least one predetermined position along the third axis.

Clause 10. The retractor of clause 1, further comprising an actuator that slides the first blade and second blade about a sixth axis.

Clause 11. The retractor of clause 10, wherein the sixth axis is substantially perpendicular to the first axis, the second axis or both the first and second axes.

Clause 12. The retractor of clause 10, wherein the sixth axis is substantially perpendicular to both the first axis and the second axis.

Clause 13. The retractor of clause 10, wherein the sixth axis is perpendicular to the first axis, the second axis or both the first and second axes.

Clause 14. The retractor of clause 10, wherein the sixth axis is perpendicular to both the first axis and the second axis.

Clause 15. The retractor of clause 10, wherein the sixth axis is substantially parallel to the fourth axis, the fifth axis or both the fourth and fifth axes.

Clause 16. The retractor of clause 10, wherein the sixth axis is substantially parallel to both the first axis and the second axis.

Clause 17. The retractor of clause 10, wherein the sixth axis is parallel to the fourth axis, the fifth axis or both the fourth and fifth axes.

Clause 18. The retractor of clause 10, wherein the sixth axis is parallel to both the first axis and the second axis.

Clause 19. The retractor of clause 10, further comprising a device for locking the first and second blades in at least one predetermined position along the sixth axis.

Clause 20. The retractor of clause 1, further comprising an actuator that translates the first blade and second blade about a third axis and an actuator that slides the first blade and second blade about a sixth axis.

Clause 21. The retractor of clause 20, wherein the sixth axis is substantially perpendicular to the third axis.

Clause 22. The retractor of clause 20, wherein the sixth axis is perpendicular to the third axis.

Clause 23. The retractor of clause 20, further comprising a device for locking the first and second blades in at least one predetermined position along the sixth axis.

Clause 24. The retractor of clause 1, further comprising a third blade that remains stationary during movement of the first blade and the second blade.

Clause 25. The retractor of clause 24, wherein the first and third blades are of different sizes in at least one dimension.

Clause 26. The retractor of clause 24, wherein at least one of the first, second and third blades is a flat blade.

Clause 27. The retractor of clause 1, further comprising a third blade and a third pivot mechanism that pivots the third blade about a seventh axis, wherein the seventh axis is skewed to the fourth axis.

Clause 28. The retractor of clause 1, wherein at least one blade is removable.

Clause 29. The retractor of clause 1, wherein the first and second blades are removable.

Clause 30. A retractor blade assembly, comprising:
 a first blade having attached thereto a first barrel, the first barrel having a wall and defining a first lumen, a first slot in the wall having a first slope,

a first screw having an axis, the first screw fitting within the first lumen of the first barrel

a collar having an inner surface configured to mate with the outer surface of the first screw, the collar having a hole that aligns with the first slot in the wall of the first barrel;

a connecting pin fitting through the hole and the slot such that movement of the collar along the axis causes the first barrel to rotate in a first direction; and

a hub comprising a first connecting hole, wherein the first barrel fits within the first connecting hole.

Clause 31. The blade assembly of clause 30, wherein the hub is adapted to be removably affixed to an arm of a retractor.

Clause 32. The blade assembly of clause 30, wherein the hub comprises a second connecting hole and a third connecting hole, wherein the retractor blade assembly further comprises a second screw configured to be received within the third connecting hole, a pin configured to be received within the second connecting hole, wherein movement of the second screw causes the hub to rotate about a post.

Clause 33. A retractor blade assembly, comprising:
 a first blade having attached thereto a first barrel,
 a hub having a second connecting hole and a third connecting hole,

a second screw configured to be received within the third connecting hole;

a pin configured to be received within the second connecting hole; and

a post extending into the hub, the post comprising a groove configured to accept the pin;

wherein movement of the screw causes the hub to rotate about the post.

Clause 34. The blade assembly of clause 33, wherein the hub is adapted to be removably affixed to an arm of a retractor.

Clause 35. The blade assembly of clause 33, wherein the hub comprises a first connecting hole, wherein the first barrel fits within the first connecting hole, the first barrel having a wall and defining a first lumen, a first slot in the wall having a first slope, a first screw having an axis, the first screw fitting within the first lumen of the first barrel, a collar having an inner surface configured to mate with the outer surface of the first screw, the collar having a hole that aligns with the first slot in the wall of the first barrel, and a connecting pin fitting through the hole and the slot such that movement of the collar along the axis causes the first barrel to rotate in a first direction.

Clause 36. A retractor, comprising:

a first arm having a distal end and a proximal end;
a second arm having a distal end and a proximal end;
a first blade coupled near the distal end of the first arm;
a first rotation mechanism that rotates the first blade about a first axis;

a second blade coupled near the distal end of the second arm rotatable about a second axis;

a second rotation mechanism that rotates the second blade about the second axis, wherein the first axis is substantially parallel to the second axis;

a first pivot mechanism in mechanical communication with the first blade and adapted to pivot the first blade about a fourth axis, wherein the first axis is skewed to the fourth axis; and

a second pivot mechanism in mechanical communication with the second blade and adapted to pivot the second blade about a fifth axis, wherein the second axis is skewed to the fifth axis.

Clause 37. The retractor of clause 36, further comprising a third blade and a third pivot mechanism in mechanical communication with the third blade and adapted to pivot the third blade about a seventh axis, wherein the seventh axis is skewed to the fourth axis.

Clause 38. A retractor, comprising:

a first arm having a distal end and a proximal end;
a second arm having a distal end and a proximal end, at least the distal end of the first arm and the distal end of the second arm being movable toward and away from each other;

a first blade attached near the distal end of the first arm and a device for moving the first blade about a first axis to adopt at least an opened position and a closed position;

a second blade attached near the distal end of the second arm and a device for moving the second blade relative to a second axis different from the first axis to adopt at least an opened position and a closed position; and

a device for moving at least the distal end of the first arm and the distal end of the second arm relative to one another along a third axis that is not parallel to the first and second axes.

Clause 39. A retractor blade assembly, comprising:

a first arm having a distal end and a proximal end;
a second arm having a distal end and a proximal end, at least the distal end of the first arm and the distal end of the second arm being movable toward and away from each other;

a first blade attached near the distal end of the first arm and a device for pivoting the first blade about a fourth axis;

a second blade attached near the distal end of the second arm and a device for pivoting the second blade relative to a fifth axis different from the fourth axis; and

a device for moving at least the distal end of the first arm and the distal end of the second arm relative to one another along a third axis that is not parallel to the fourth and fifth axes.

Clause 40. A method of using a retractor, comprising:
rotating a first blade of a retractor about a first axis;
rotating a second blade of a retractor about a second axis, wherein the first axis is substantially parallel to the second axis;

translating the first blade and the second blade about a third axis

pivoting the first blade about a fourth axis, wherein the fourth axis is skewed to the first axis; and

pivoting the second blade about a fifth axis, wherein the fourth axis is skewed to the second axis.

Clause 41. A method of using a retractor, comprising:

making an incision in a tissue of a body;
providing a retractor;

rotating a first blade of a retractor about a first axis;

rotating a second blade about a second axis, wherein the first axis is substantially parallel to the second axis;

pivoting the first blade about a fourth axis, wherein the fourth axis is skewed to the first axis; and

pivoting the second blade about a fifth axis, wherein the fifth axis is skewed to the second axis.

Clause 42. The method of Clause 41, further comprising positioning the first and second blades substantially parallel to each other to form a first closed blade assembly.

Clause 43. The method of Clause 41, further comprising positioning a third blade substantially parallel to the first and second blades in a closed position.

Clause 44. The method of Clause 43, further comprising pivoting the third blade about a seventh axis, wherein the seventh axis is skewed to the fourth axis.

Clause 45. The method of Clause 43, further comprising inserting the first blade, the second blade, and a third blade within the incision.

Clause 46. The method of Clause 41, further comprising actuating the retractor such that the first blade and second blade are moved apart from one another along a third axis and the incision is stretched along the length of the incision to create an opening longer than the incision.

Clause 47. The method of Clause 41, further comprising actuating the retractor such that the first blade and second blade are slid together along a sixth axis and the incision is stretched along the width of the incision to create an opening wider than the incision.

Clause 48. The method of Clause 41, further comprising creating an aperture in the tissue that is longer and wider than the incision.

What is claimed is:

1. A retractor comprising:

a first flattened blade;

a first rotation mechanism configured to rotate the first flattened blade about a first axis;

a second flattened blade;

a second rotation mechanism configured to rotate the second flattened blade about a second axis;

a first pivot mechanism configured to pivot the first flattened blade about a fourth axis, wherein the fourth axis is skewed to the first axis;

a second pivot mechanism configured to pivot the second flattened blade about a fifth axis, wherein the fifth axis is skewed to the second axis; and

wherein the first flattened blade and the second flattened blade have a stacked configuration to form a substantially planar blade set.

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2. The retractor of claim 1, wherein the first flattened blade comprises a first rail, wherein the first flattened blade is configured to slide relative to the second flattened blade without interference of the first rail.

3. The retractor of claim 1, wherein the first flattened blade comprises a first rail and wherein the second flattened blade comprises a second rail, wherein the first flattened blade is configured to slide relative to the second flattened blade without interference of the first rail and the second rail.

4. The retractor of claim 1, further comprising a third flattened blade.

5. The retractor of claim 4, wherein the first flattened blade, the second flattened blade, and the third flattened blade have a stacked configuration.

6. The retractor of claim 4, further comprising a third pivot mechanism that pivots the third flattened blade.

7. A retractor comprising:

a first blade;

a first rotation mechanism configured to rotate the first blade about a first axis;

a second blade;

a second rotation mechanism configured to rotate the second blade about a second axis;

a first pivot mechanism configured to pivot the first blade about a fourth axis, wherein the fourth axis is skewed to the first axis;

a second pivot mechanism configured to pivot the second blade about a fifth axis, wherein the fifth axis is skewed to the second axis; and

wherein the first blade and the second blade are substantially parallel in a closed position with the first blade in front of the second blade, wherein the first blade and the second blade have a stacked configuration to form a substantially planar blade set.

8. The retractor of claim 7, wherein the first blade comprises a first rail, wherein the first blade is configured to slide relative to the second blade without interference of the first rail.

9. The retractor of claim 7, wherein the first blade comprises a first rail and wherein the second blade com-

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prises a second rail, wherein the first blade is configured to slide relative to the second blade without interference of the first rail and the second rail.

10. The retractor of claim 7, further comprising a third blade.

11. The retractor of claim 10, wherein the first blade, the second blade, and the third blade are substantially parallel in the closed position.

12. The retractor of claim 10, further comprising a third pivot mechanism that pivots the third blade.

13. A method of using a retractor, comprising:

making an incision in a tissue of a body;

providing a retractor, wherein the retractor comprises a first blade and a second blade, wherein the first blade and the second blade are substantially parallel and overlapping in a closed position, wherein the first blade and the second blade have a stacked configuration to form a substantially planar blade set;

actuating the retractor to move the one or more of the first blade and the second blade, wherein actuating the retractor comprises moving the first blade, moving the second blade, or moving both the first blade and second blade.

14. The method of claim 13, wherein moving the first blade comprises rotating the first blade.

15. The method of claim 13, wherein moving the second blade comprises rotating the second blade.

16. The method of claim 13, wherein moving the first blade comprises pivoting the first blade.

17. The method of claim 13, wherein moving the second blade comprises pivoting the second blade.

18. The method of claim 13, wherein moving both the first blade and the second blade comprises translating the first blade and the second blade.

19. The method of claim 13, wherein moving both the first blade and the second blade comprises linearly translating the first blade and the second blade.

20. The method of claim 13, further comprising a third blade, wherein the first blade, the second blade, and the third blade are substantially parallel and overlapping in the closed position.

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