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# Mazzillo et al.

# (54) MULTI-SENSOR OPTICAL DEVICE FOR DETECTING CHEMICAL SPECIES AND MANUFACTURING METHOD THEREOF

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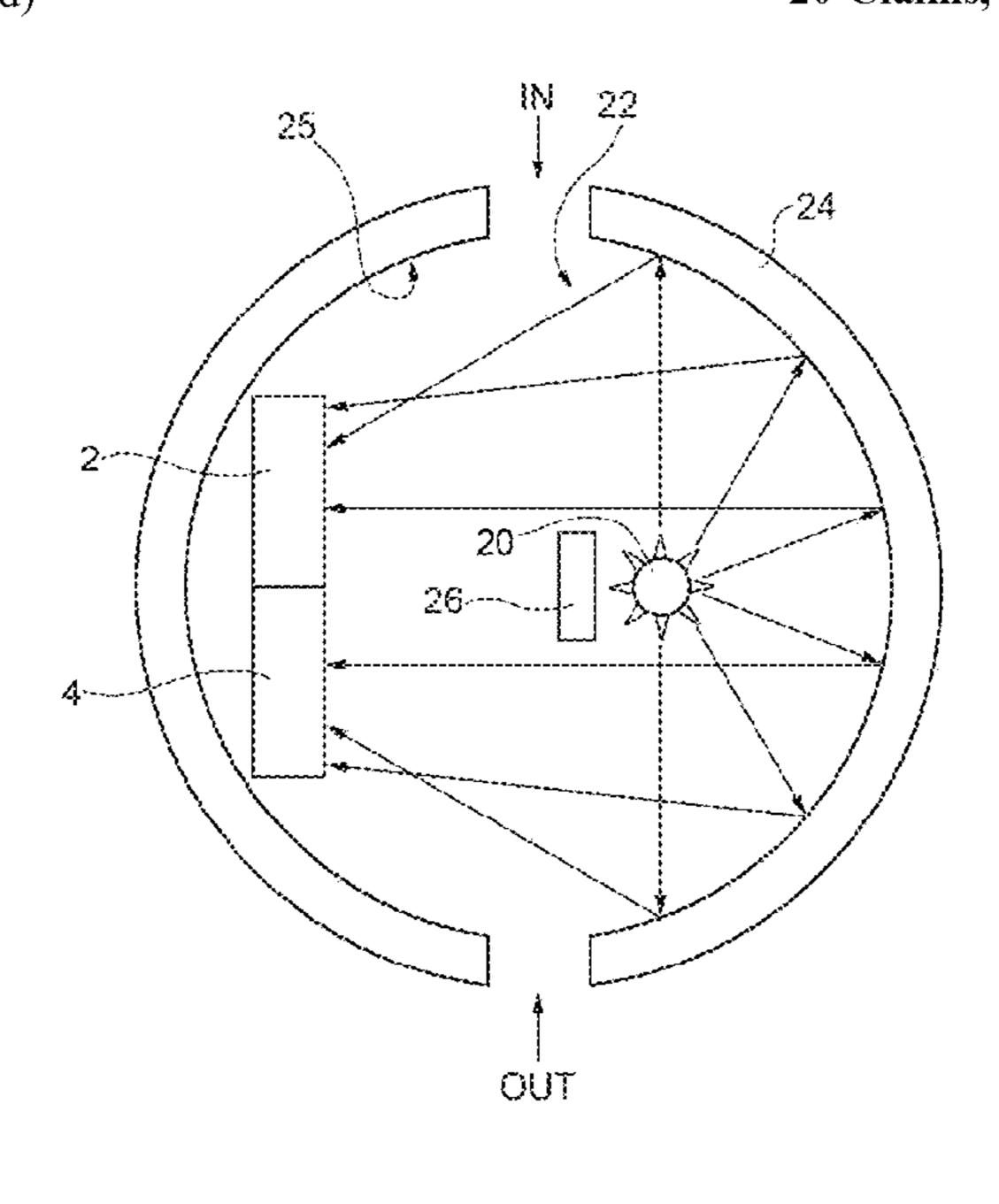
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### (57) ABSTRACT

An optical device for detecting a first chemical species and a second chemical species contained in a specimen, which includes: a first optical sensor, which may be optically coupled to an optical source through the specimen and is sensitive to radiation having a wavelength comprised in a first range of wavelengths; and a second optical sensor, which may be optically coupled to the optical source through the specimen and is sensitive to radiation having a wavelength comprised in a second range of wavelengths, different from the first range of wavelengths.

# 20 Claims, 10 Drawing Sheets



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See application file for complete search history.

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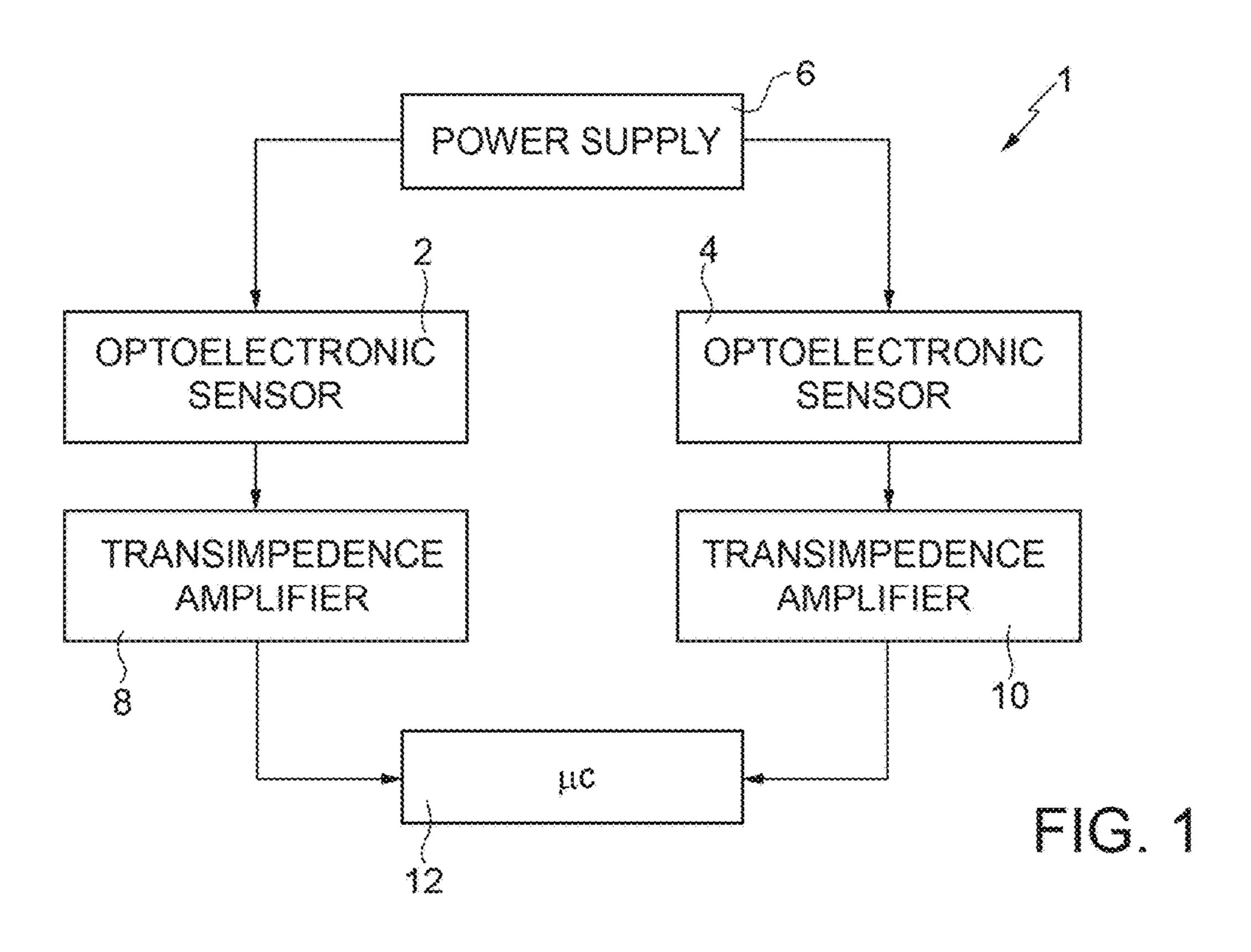
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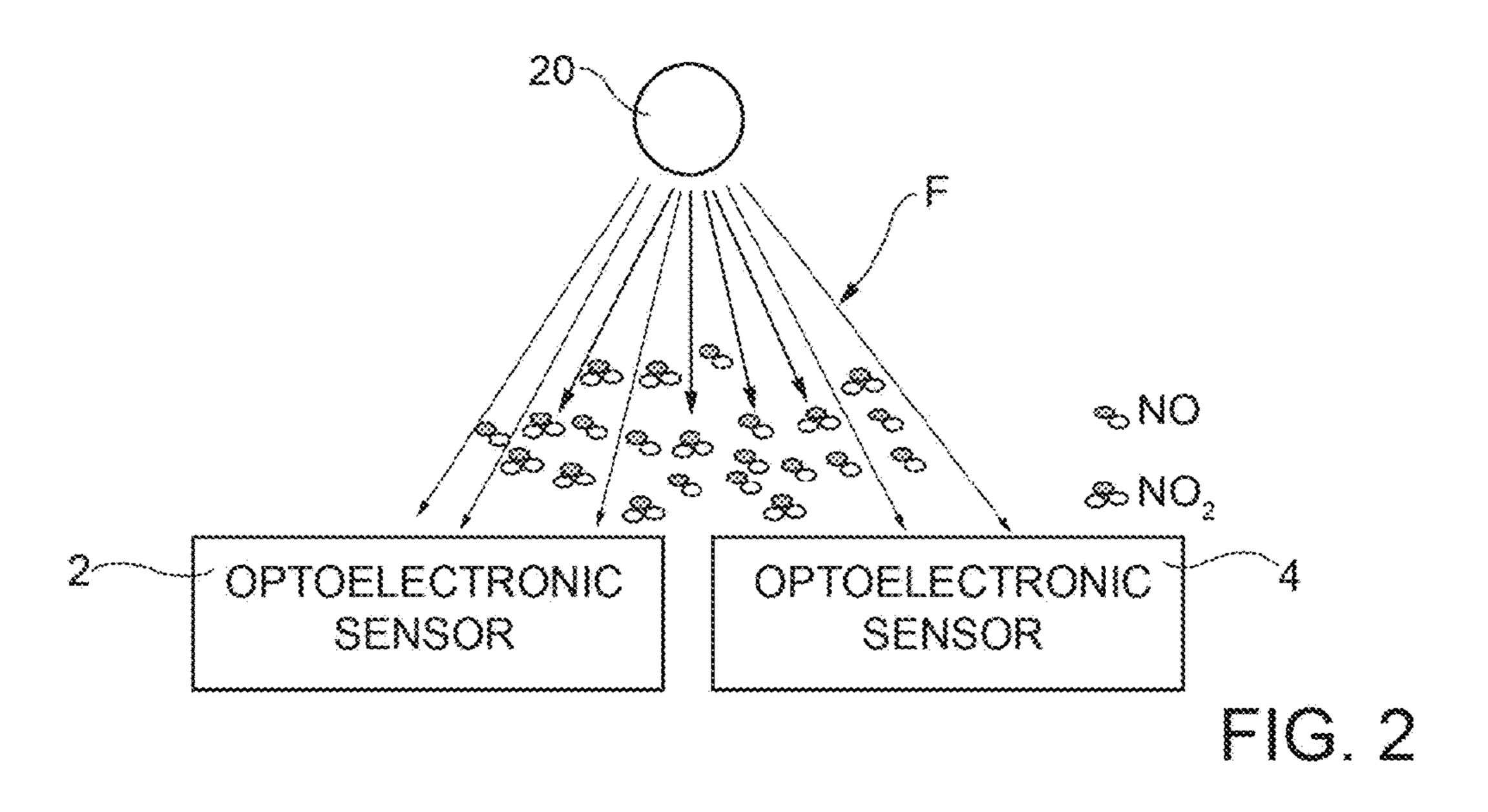
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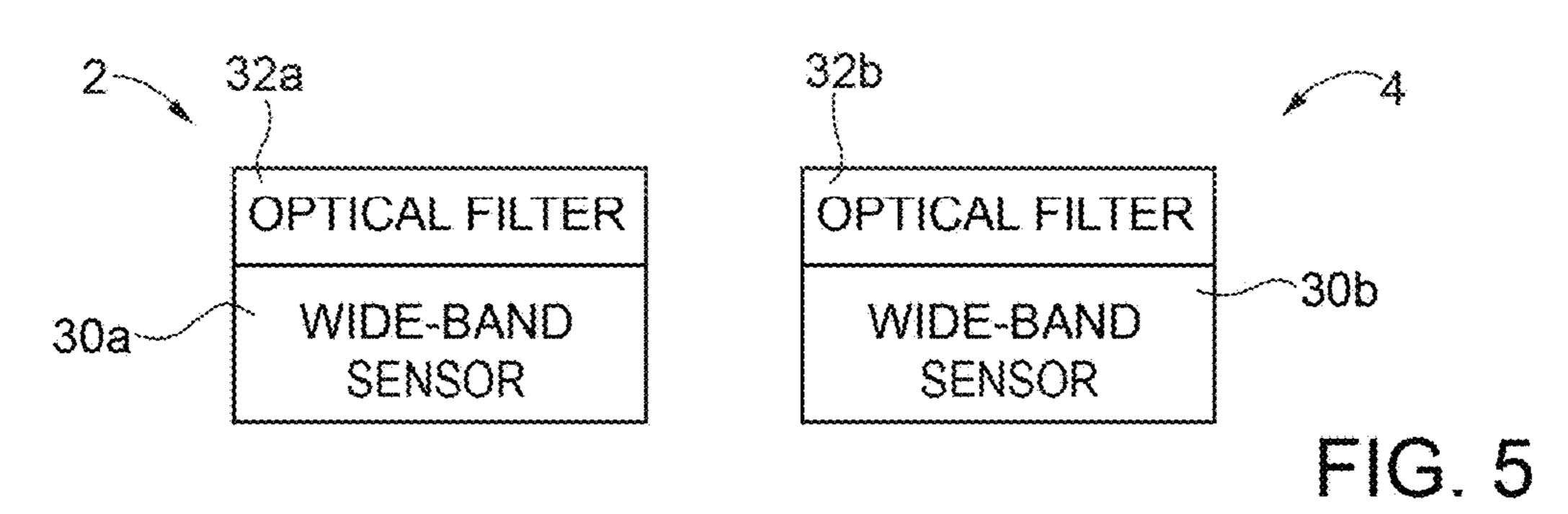
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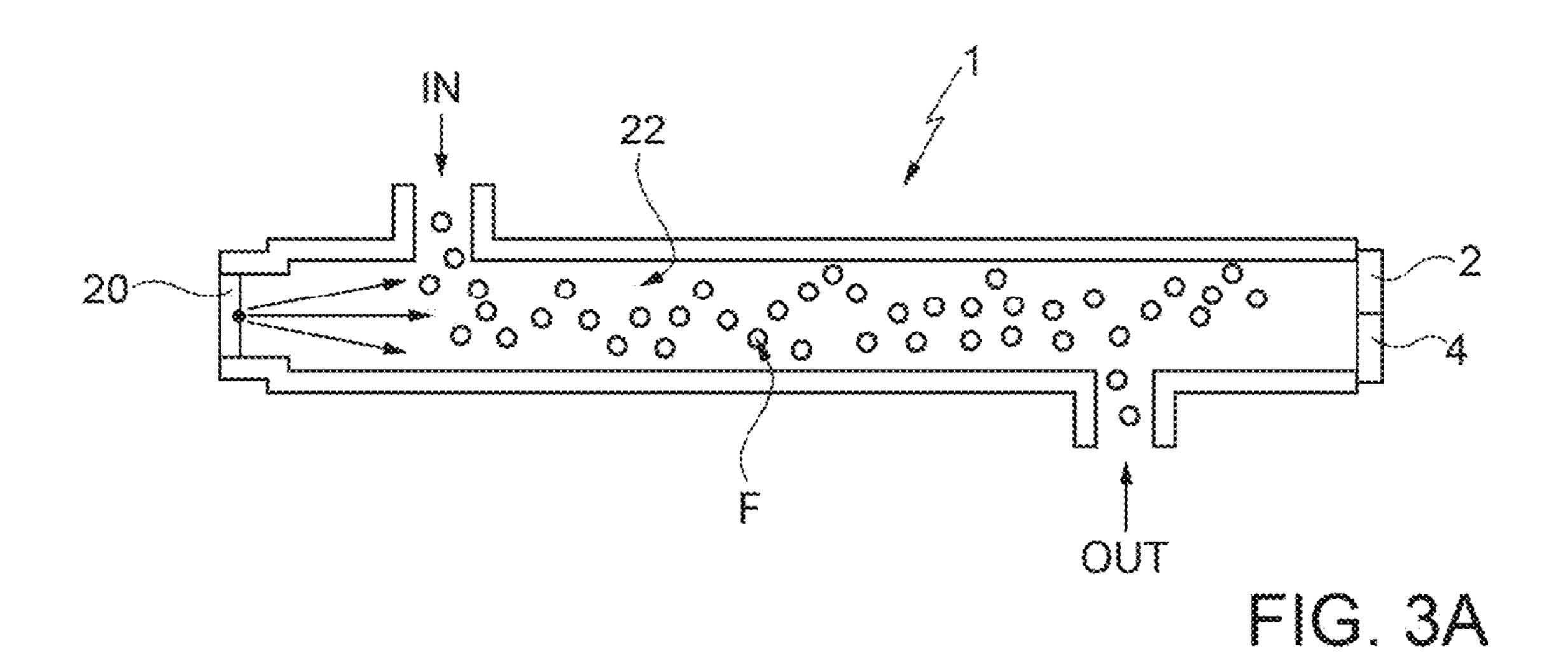
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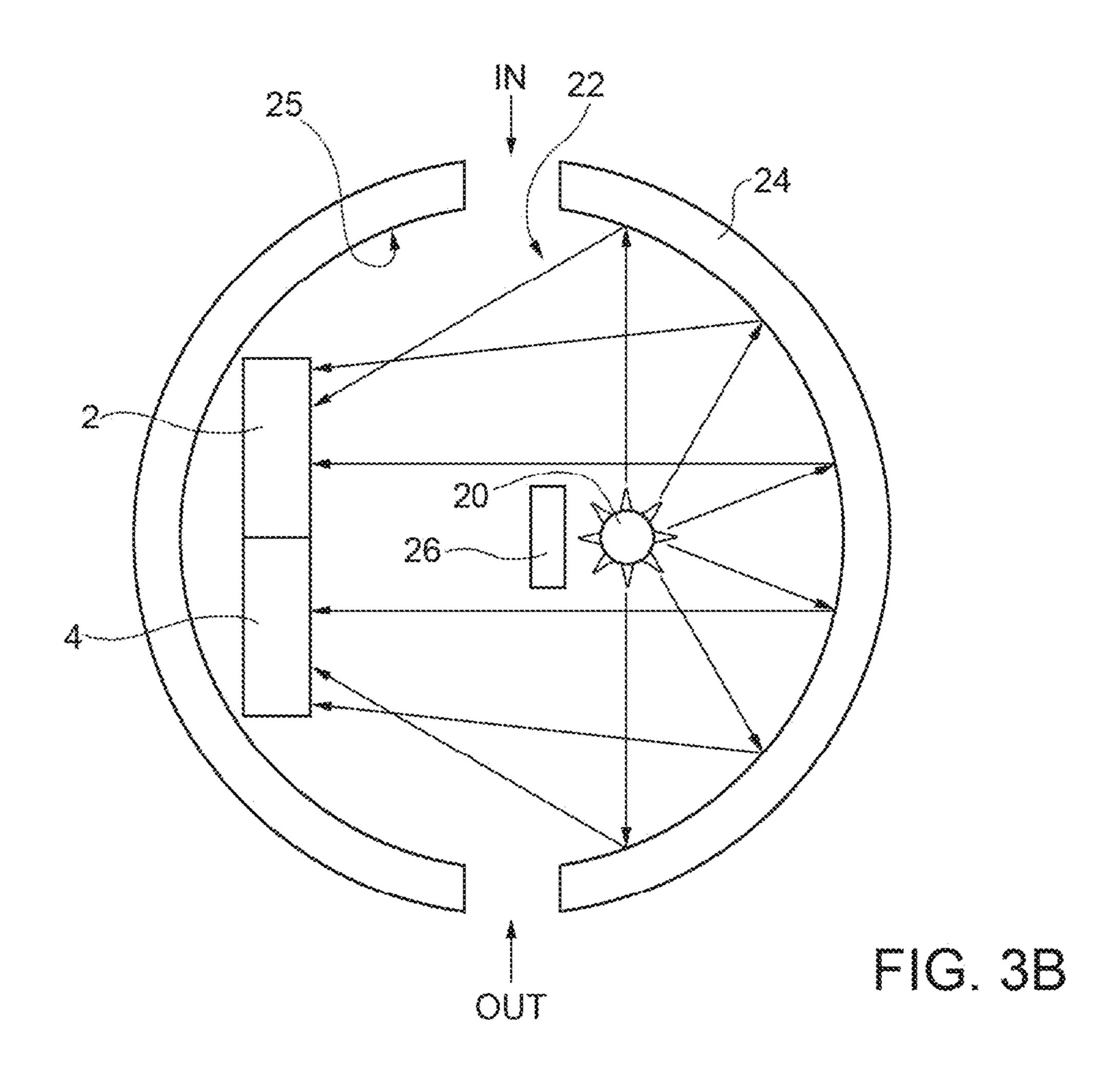
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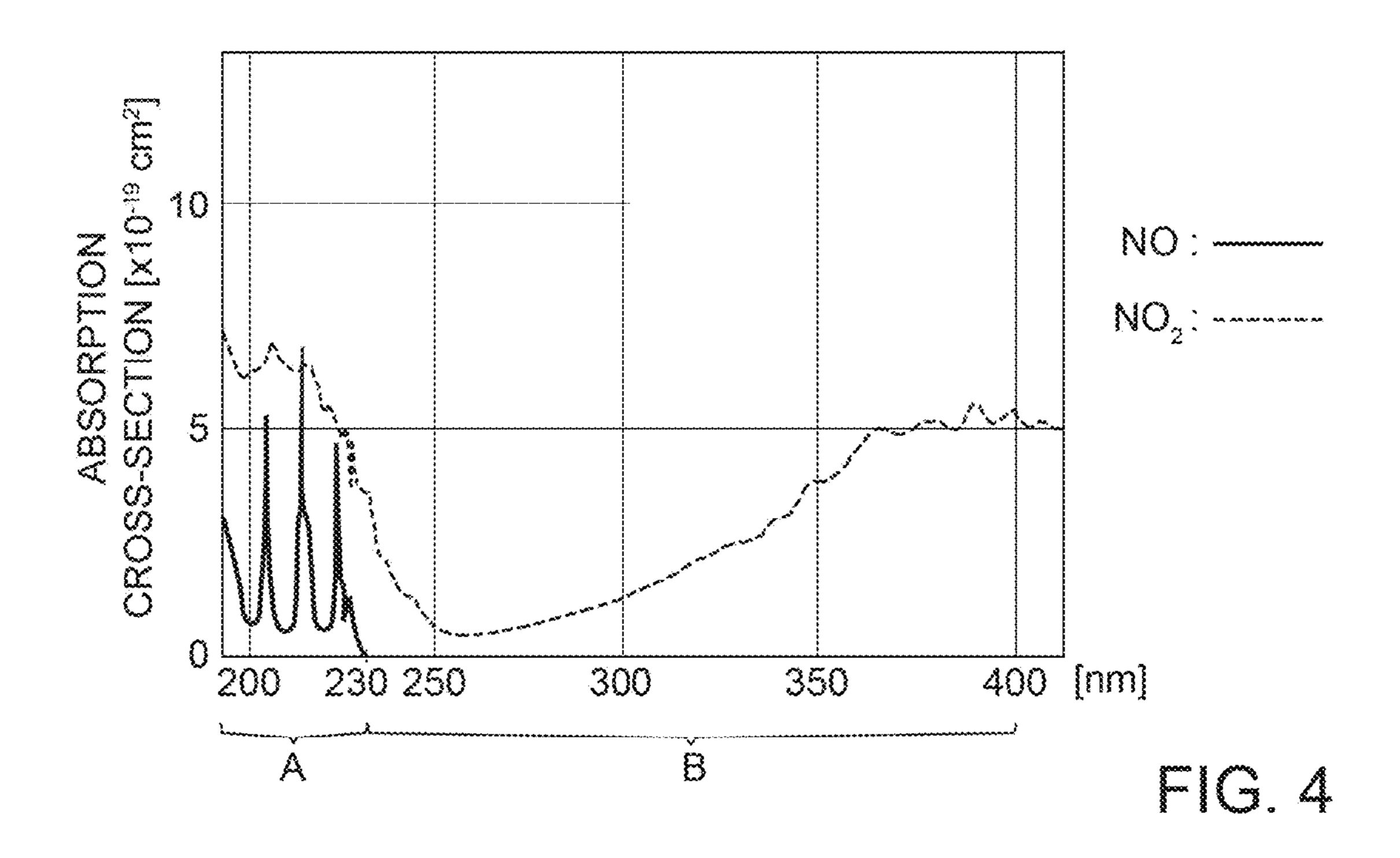












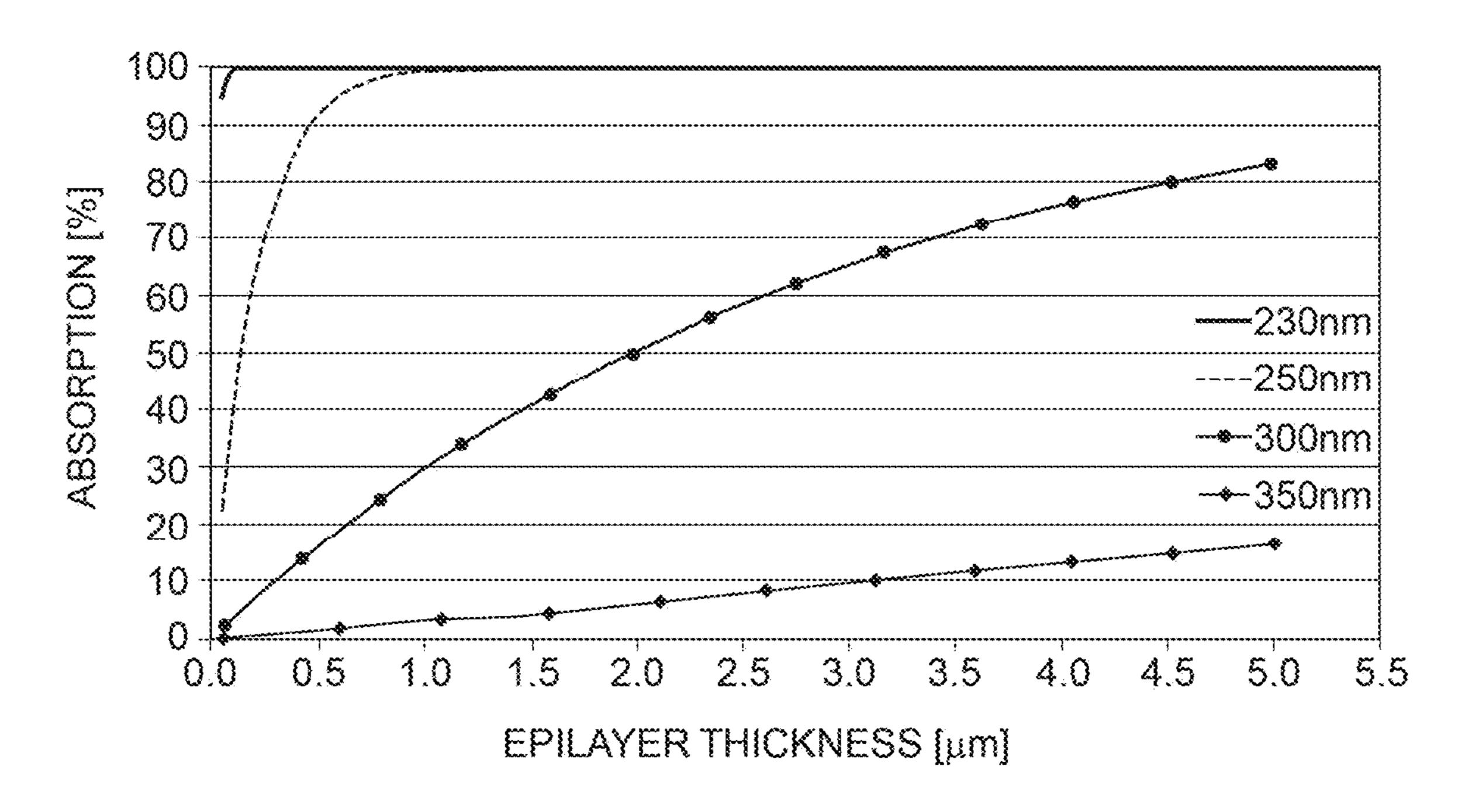
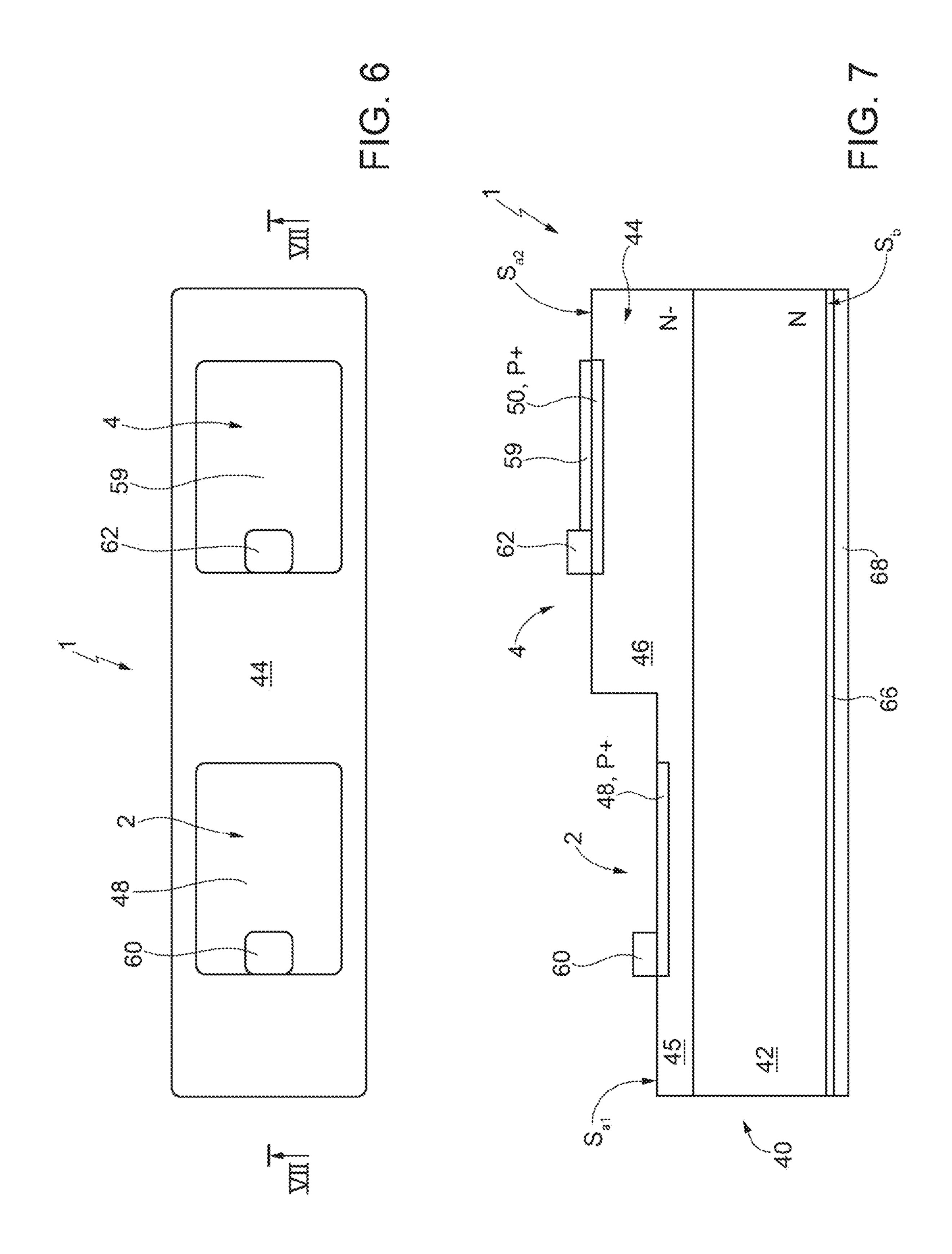
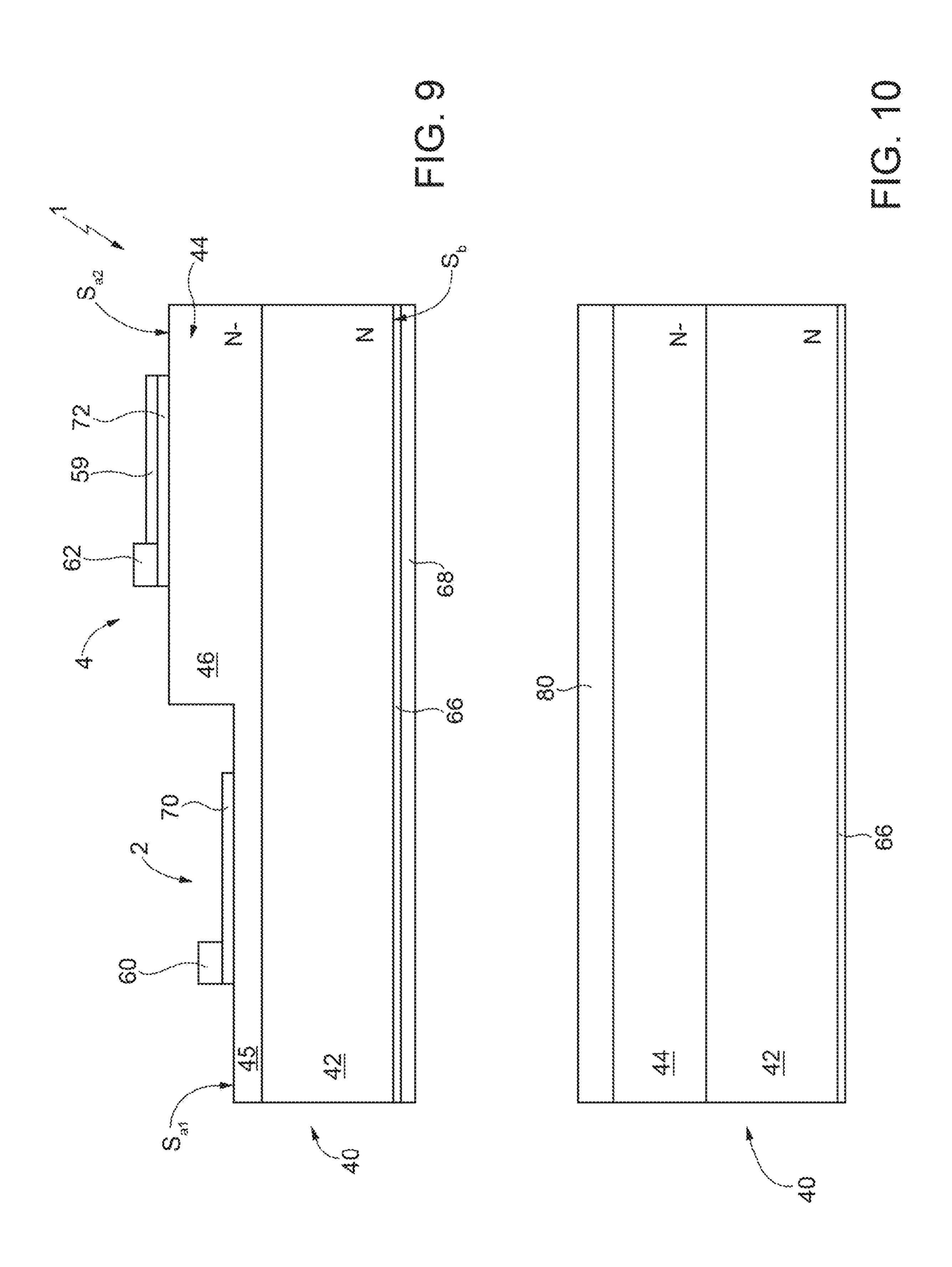
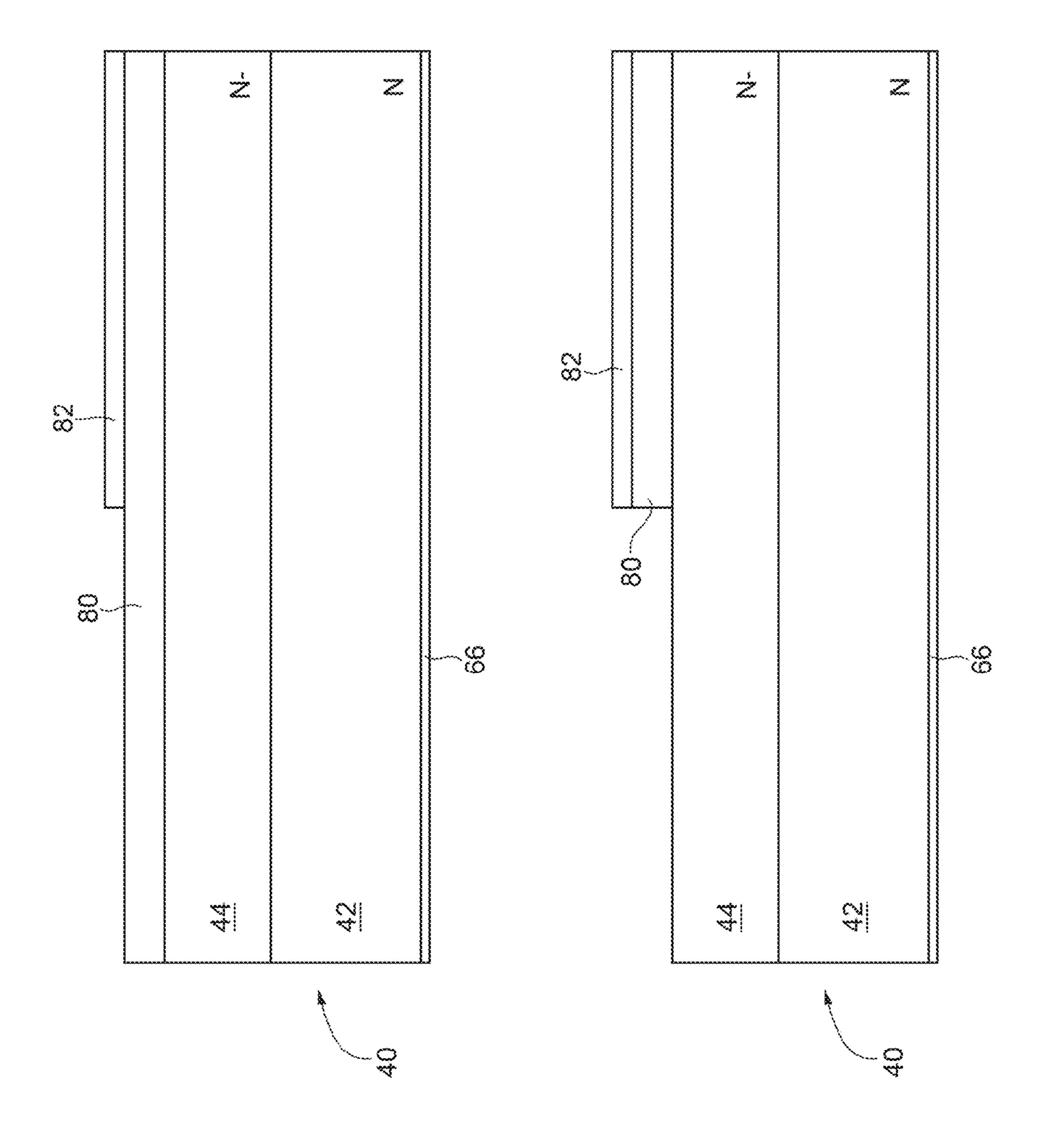


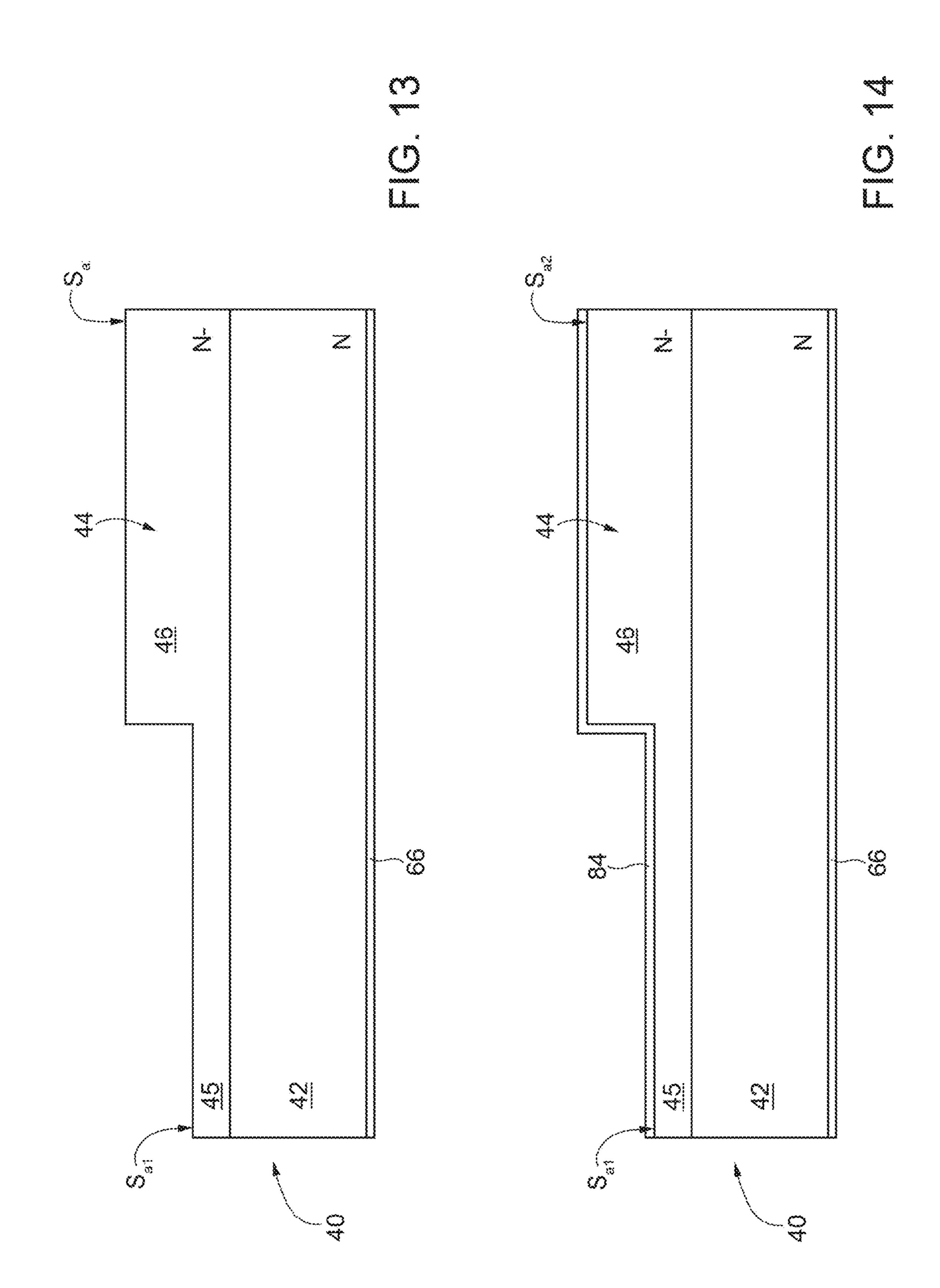
FIG. 8

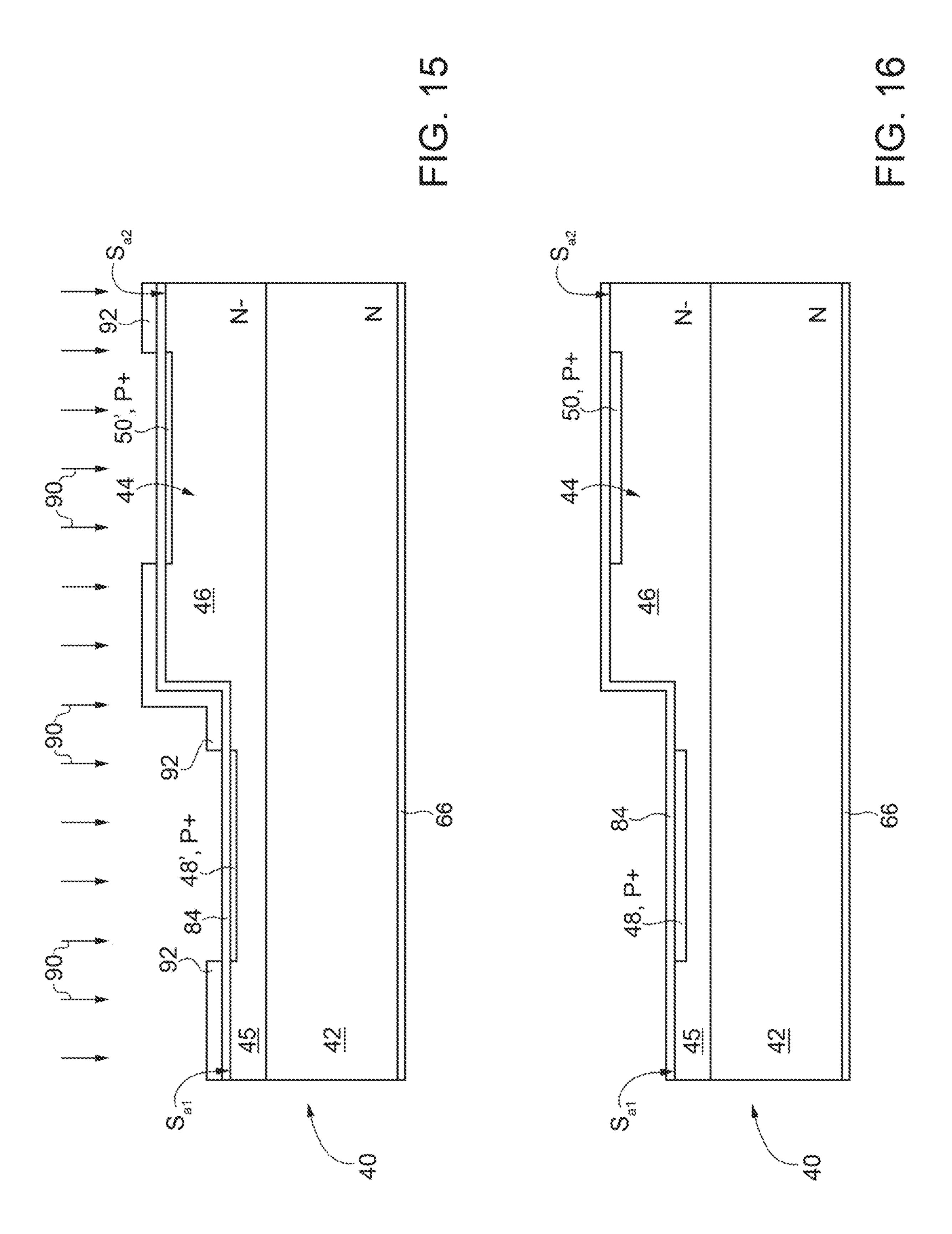




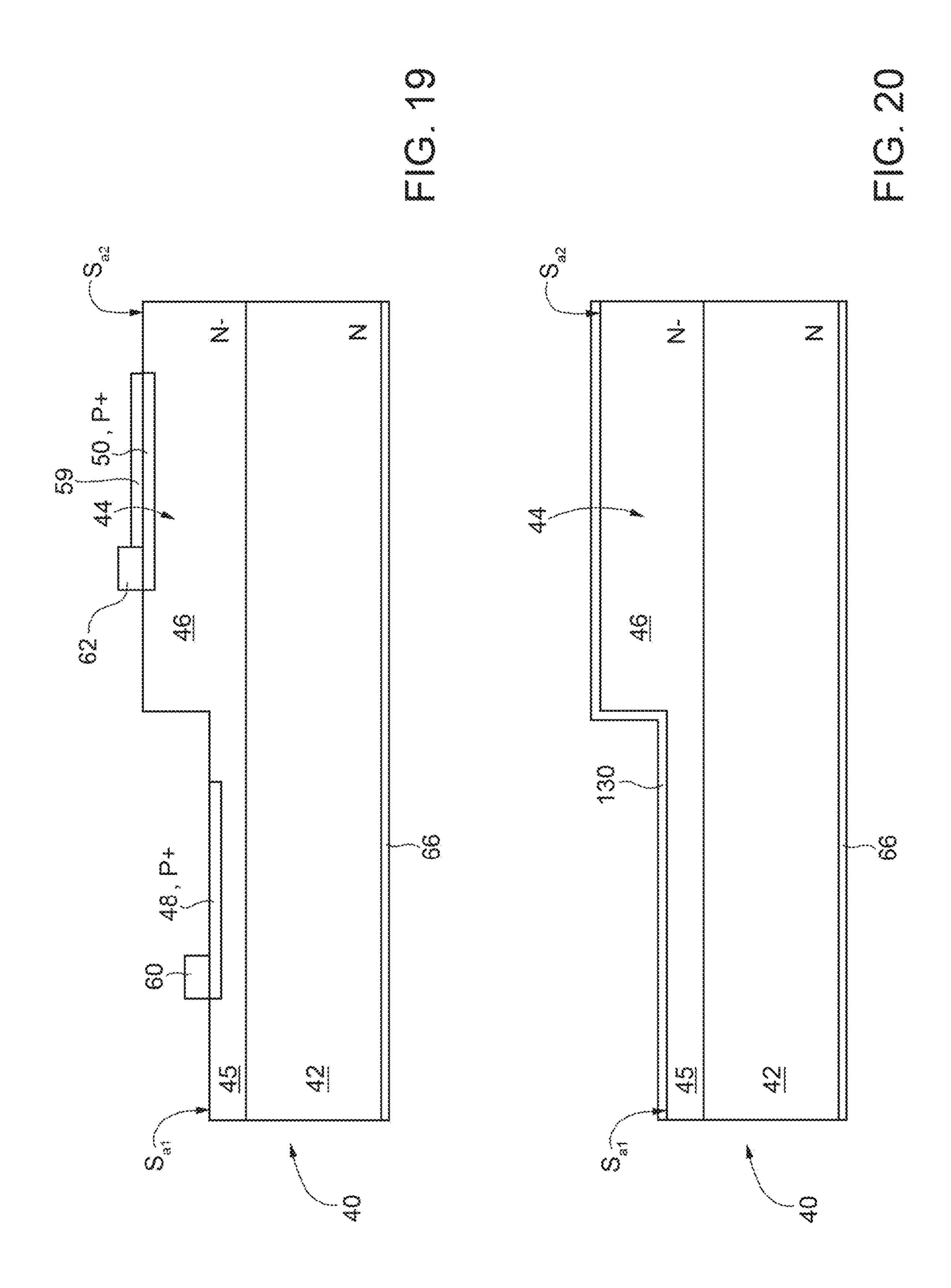








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# MULTI-SENSOR OPTICAL DEVICE FOR DETECTING CHEMICAL SPECIES AND MANUFACTURING METHOD THEREOF

#### **BACKGROUND**

#### Technical Field

The present disclosure relates to a multi-sensor optical device for detecting chemical species, as well as to the 10 manufacturing method thereof.

# Description of the Related Art

As is known, in different fields of application one can 15 detect one or more chemical species and then determine the corresponding concentrations of these chemical species. For instance, in the motor-industry sector, one can determine the concentrations, in an exhaust gas, of chemical species that are generated in the course of the thermal reactions that take 20 place within an engine.

Once again with reference to the motor-industry sector, it is known that, following upon a combustion reaction that occurs between the fuel and the air, water  $(H_2O)$ , carbon dioxide  $(CO_2)$ , carbon monoxide (CO), sulphur oxides  $(SO_x)$ , nitrogen oxides  $(NO_x)$ , hydrocarbons (HC) and particulate matter (PM) are generated. In addition, nitrogen oxides include nitrogen monoxide (NO), nitrogen dioxide  $(NO_2)$ , and dinitrogen oxide  $(NO_2)$ .

Since the chemical species resulting from a combustion 30 reaction concur significantly in pollution, the control of the levels of emission of these chemical species proves to be of particular importance. Consequently, various types of sensors have been developed over time, referred to in general as burnt-gas sensors. For instance, different types of nitrogenoxide sensors are known, which are commonly employed within closed control loops that are designed to control the combustion process.

Since the aforementioned burnt-gas sensors usually operate in extreme environmental conditions, they are characterized not only by high sensitivity and speeds of response, but also by a considerable resistance to high temperatures, as well as to corrosive chemical agents. For this reason, known sensors are of silicon carbide (SiC), as described, for example, in the patent application no. DE20051033639. In 45 this patent application a sensor is described including a sensing region of porous material, coated with a functional layer, capable of reacting with the chemical species to be analyzed; the reaction involves a detectable variation of the concentration of the carriers within the functional layer.

In general, burnt-gas sensors based upon the variation, following upon absorption of a chemical species by a constitutive element thereof, of an electrical characteristic of this element are characterized by low costs and by a certain simplicity of construction; however, they are likewise characterized by a not particularly high sensitivity, as well as, at times, by a low selectivity in regard to the chemical species absorbed. In addition, these sensors are far from suited to operating in the presence of corrosive chemical agents.

Commercial products are likewise known of the type 60 described in the document available at http://www.baytec-inc.com/pdf/defor-extractive-analyzer.pdf. Illustrated in this document is a gas analyzer including a source of UV radiation and two optical detectors. Further, the analyzer enables detection of more than one chemical species, thanks 65 to the use of a motor-driven mobile element, constrained to which is an optical filter so that the optical filter may be

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coupled to one of the optical detectors in a controlled way. Even though this system is characterized by a high accuracy, it may not be integrated; thus, it presents large overall dimensions and a high complexity. Consequently, this system is mainly suited for laboratory tests.

#### **BRIEF SUMMARY**

According to the present disclosure, a device for detecting chemical species and a manufacturing method thereof are consequently provided. One embodiment of the present disclosure is directed to an optical device that includes an optical source, a first optical sensor configured to be optically coupled to the optical source through a specimen, the specimen having a first chemical species and a second chemical species, the first optical sensor being sensitive to radiation having a wavelength in a first range of wavelengths, and a second optical sensor configured to be optically coupled to the optical source through the specimen, the second optical sensor being sensitive to radiation having a wavelength in a second range of wavelengths, different from the first range of wavelengths.

# BRIEF DESCRIPTION OF THE SEVERAL VIEWS OF THE DRAWINGS

For a better understanding of the present disclosure, preferred embodiments thereof are now described, purely by way of non-limiting example and with reference to the attached drawings, wherein:

FIG. 1 shows a block diagram of the present device for detecting chemical species;

FIG. 2 shows qualitatively a principle diagram of operation of the present detection device;

FIGS. 3A and 3B are schematic cross-sectional views of embodiments of the present detection device;

FIG. 4 shows qualitatively the plots of the absorption cross-sections for nitrogen monoxide NO and nitrogen dioxide NO<sub>2</sub>, expressed in  $x10^{-19}$  cm<sup>2</sup> and as a function of the wavelength  $(\lambda)$ ;

FIG. 5 shows a block diagram of an embodiment of a first optoelectronic sensor and a second optoelectronic sensor that form the present detection device;

FIG. 6 is a schematic top plan view of an embodiment of the present detection device;

FIG. 7 is a schematic cross-sectional view of the embodiment represented in FIG. 6, taken along a line of section VII-VII shown in FIG. 6;

FIG. **8** shows the plot of the absorption of radiation having a wavelength alternatively equal to 230 nm, 250 nm, 300 nm, and 350 nm within a silicon-carbide junction of the 4H type, as a function of the thickness of the epilayer (on the hypothesis of fully depleted epilayer);

FIG. 9 is a schematic cross-sectional view of a further embodiment of the present detection device; and

FIGS. 10-20 are schematic cross-sectional views of embodiments of the present detection device, during successive steps of a manufacturing method.

# DETAILED DESCRIPTION

FIG. 1 shows a device for detecting chemical species 1, which will be referred to hereinafter, for brevity, as "detection device 1".

The detection device 1 comprises a first optoelectronic sensor 2 and a second optoelectronic sensor 4, and a power supply 6, which is designed to bias the first and second

optoelectronic sensors 2, 4, to which it is electrically connected. Furthermore, the detection device 1 comprises a first amplifier 8 and a second amplifier 10, for example of the transimpedence type, and a processing unit 12.

The detection device 1 likewise comprises, as illustrated 5 in FIG. 2 and described in greater detail hereinafter, an optical source 20 designed to generate radiation that impinges, in use, upon the first and second optoelectronic sensors 2, 4. Furthermore, in use, a fluid F is arranged between the optical source 20 and the first and second 10 optoelectronic sensors 2, 4, so that the radiation generated by the optical source 20 traverses the fluid F before impinging upon the first and second optoelectronic sensors 2, 4. In turn, the first and second optoelectronic sensors 2, 4 generate a first electrical signal and a second electrical signal, which 15 will be referred to as "first and second detection signals". The first and second detection signals are supplied, respectively, to the first and second amplifiers 8, 10 and indicate the intensity of the radiation that impinges, respectively, upon the first and second optoelectronic sensors 2, 4. In turn, 20 the first and second amplifiers 8, 10 generate, on the basis of the first and second detection signals, a first further signal and a second further signal, which will be referred to hereinafter as "first and second processable signals". These first and second processable signals are supplied to the 25 processing unit 12, which executes the processing operations described in what follows.

As illustrated in greater detail in FIG. 3A, the detection device 1 comprises a chamber 22, which enables functional coupling of the optical source 20, the first and second 30 optoelectronic sensors 2, 4, and the fluid F. In particular, the chamber 22 has a fluid inlet IN and a fluid outlet OUT, by which the fluid F can, respectively, enter and exit from the chamber 22. Furthermore, the optical source 20 is arranged at a first end of the chamber 22, whereas the first and second 35 optoelectronic sensors 2, 4 are arranged at a second end of the chamber 22. In this way, the radiation generated by the optical source 20 traverses a portion of the chamber 22, and thus passes through the fluid F, before impinging upon the first and second optoelectronic sensors 2, 4.

However possible are variants in which the optical coupling between the optical source 20 and the first and second optoelectronic sensors 2, 4 is obtained in a different way and/or the chamber 22 has a different shape. Purely by way of example, it is for instance possible that, as illustrated in 45 FIG. 3B, the chamber 22 is formed by a spherical container 24, which, in addition to forming the fluid inlet IN and the fluid outlet OUT, has an inner wall 25 having a substantially spherical shape (but for the fluid inlet and outlet) and is designed to reflect the radiation generated by the optical 50 source 20. More in particular, the first and second optoelectronic sensors 2, 4 and the optical source 20 are arranged within the chamber 22, together with a screen 26 of a reflecting type. In addition, the screen 26 is arranged between the optical source 20 and the first and second 55 optoelectronic sensors 2, 4 so that the radiation generated by the optical source 26 may not impinge upon the first and second optoelectronic sensors 2, 4, other than after being reflected at least once by the inner wall 25. In this way, the length of the optical paths that connect the optical source 20 60 to the first and second optoelectronic sensors 2, 4 is increased, given the same overall dimensions of the chamber **22**.

This being said, in what follows reference will be made, without this implying any loss of generality, to the case 65 where the detection device 1 is designed to detect individually nitrogen monoxide NO and nitrogen dioxide NO<sub>2</sub>, i.e.,

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to determine the individual concentrations of nitrogen monoxide NO and nitrogen dioxide NO<sub>2</sub> present in the fluid F. In this connection, FIG. 4 shows the plots of the absorption cross-sections for nitrogen monoxide NO and nitrogen dioxide NO<sub>2</sub>, expressed in  $\times 10^{-19}$  cm<sup>2</sup> and as a function of the wavelength ( $\lambda$ ). In this case, without this implying any loss of generality, the optical source 20 emits UV radiation. For instance, without this implying any loss of generality, it is assumed that this radiation has a constant spectrum in the range 200-400 nm. For practical purposes, the optical source 20 may be formed by a voltaic-arc lamp, or else by a LED or laser diode.

It is likewise assumed, without this implying any loss of generality, that the first and second optoelectronic sensors 2, 4 are semiconductor sensors at least in part of silicon carbide, as described hereinafter. Furthermore, it is assumed that the first optoelectronic sensor 2 is sensitive to radiation having a wavelength comprised in a first range of 200-230 nm, designated by A in FIG. 4; it is further assumed that the second optoelectronic sensor 4 is sensitive to radiation having a wavelength comprised in a second range of 230-400 nm. In practice, it is known that nitrogen monoxide NO absorbs below 230 nm, and thus in the range 200-230 nm, as it is likewise known that nitrogen dioxide NO<sub>2</sub> absorbs up to 650 nm, and thus in the entire range between 200 nm and 400 nm. The first and second optoelectronic sensors 2, 4 have sensitivity bands that are thus a function of the spectra of absorption of nitrogen monoxide NO and nitrogen dioxide NO<sub>2</sub>. Further, the first and second optoelectronic sensors 2, 4 are substantially insensitive to radiation having a wavelength, respectively, falling outside the first and second ranges.

For practical purposes, the intensity of the radiation that impinges upon the first and second optoelectronic sensors 2, 4, after having traversed the fluid F, may be determined on the basis of the so-called Lambert-Beer law. In particular, on the hypothesis of having a monochromatic radiation and an fluidic absorber formed by just one type of chemical species and with a concentration equal to C, the Lambert-Beer law envisages that

$$I(\lambda,x)=I_0(\lambda)\cdot e^{-x\cdot\sigma(\lambda)X}$$

where  $I_0(\lambda)$  is the intensity of the monochromatic radiation that impinges upon the absorber, and  $\sigma(\lambda)$  is the absorption cross-section for the chemical species at the wavelength of the monochromatic radiation; further,  $I(\lambda, x)$  is the intensity of the radiation after it has covered an optical path of length x within the absorber. Consequently, knowledge of the intensities  $I_0(\lambda)$  and  $I(\lambda, x)$ , of the distance x, and of the absorption cross-section  $\sigma(\lambda)$  enables determination of the concentration C, which is assumed as being constant for the distance x.

In greater detail, in what follows it is assumed that the optical source 20 is at a distance x both from the first optoelectronic sensor 2 and from the second optoelectronic sensor 4. More in particular, it is assumed that the first and second optical paths that connect the optical source 20 to the first and second optoelectronic sensors 2, 4 respectively, both have a length x and extend, in use, entirely through the fluid F. Furthermore, it is assumed that the absorption of radiation generated by the optical source 20 in the range 200-400 nm by chemical species different from nitrogen monoxide NO and nitrogen dioxide NO<sub>2</sub> (for example, sulphur dioxide SO<sub>2</sub>) is negligible. In addition, in what follows the portion of the radiation generated by the optical source 20 in the range 200-230 nm and incident, in the absence of the fluid F, upon the first optoelectronic sensor 2

will be referred to as "first detection beam". Instead, the portion of the radiation generated by the optical source 20 in the range 230-400 nm and incident, in the absence of the fluid F, upon the second optoelectronic sensor 4 will be referred to as "second detection beam".

This being said, the first optoelectronic sensor 2 detects the portion of the first detection beam not absorbed either by nitrogen monoxide NO or by nitrogen dioxide NO<sub>2</sub>, which depends upon the concentrations and upon the absorption cross-sections of these two chemical species. In addition, the 10 second optoelectronic sensor 4 detects the portion of the second detection beam not absorbed by nitrogen dioxide NO<sub>2</sub>, which depends upon the concentration and upon the absorption cross-section for nitrogen dioxide NO<sub>2</sub>. The first and second detection signals, which are formed by photo- 15 currents, thus indicate, respectively, i) the combination of the concentrations of nitrogen monoxide NO and nitrogen dioxide NO<sub>2</sub>, and ii) the concentration of nitrogen dioxide  $NO_2$ .

radiation that impinges upon the first optoelectronic sensor 2, this is equal to

$$I_1 = I_{10} \int e^{-x \cdot [\sigma 1(\lambda) \cdot C1 + \sigma 2(\lambda) \cdot C2]} d\lambda$$

where  $I_{10}$  is the (known) intensity of the aforementioned first 25 detection beam,  $\sigma 1$  ( $\lambda$ ) is the absorption cross-section for nitrogen monoxide NO,  $\sigma 2(\lambda)$  is the absorption crosssection for nitrogen dioxide NO<sub>2</sub>, and C1 and C2 are, respectively, the concentrations of nitrogen monoxide NO and nitrogen dioxide NO<sub>2</sub> in the fluid F. Consequently, the 30 first detection signal and the first processable signal, which are proportional to the intensity  $I_1$ , are a function of the concentrations of nitrogen monoxide NO and nitrogen dioxide  $NO_2$ .

With reference to the intensity of the radiation that 35 formed on the substrate 42. impinges upon the second optoelectronic sensor 4, this is equal to

$$I_2=I_{20}$$
: $\int e^{-x\cdot[\sigma 3(\lambda)\cdot C2]}d\lambda$ 

where  $I_{20}$  is the (known) intensity of the aforementioned 40 second detection beam, and  $\sigma_3(\lambda)$  is the absorption crosssection for nitrogen dioxide NO<sub>2</sub>. Consequently, the second detection signal and the second processable signal, which are proportional to the intensity I<sub>2</sub>, are a function of the concentration of nitrogen dioxide NO<sub>2</sub>.

On the basis of the first and of the second processable signal, the processing unit 12 is thus able to determine each one between the concentration of nitrogen monoxide NO and the concentration of nitrogen dioxide NO<sub>2</sub>. Without this implying any loss of generality, it is assumed that the above 50 two concentrations are constant along the optical paths covered by the first and second detection beams.

In greater detail, in a per se known manner, the processing unit 12 numerically determines the concentration C2 of nitrogen dioxide NO<sub>2</sub>, on the basis of a measurement of the 55 intensity 12, as determined by the processing unit 12 itself on the basis of the second processable signal. Next, the processing unit 12 numerically determines the concentration C1 of nitrogen monoxide NO, on the basis of the concentration C2 of nitrogen dioxide NO<sub>2</sub> and of a measurement of 60 the intensity  $I_1$ , as determined by the processing unit 12 itself on the basis of the first processable signal. More precisely, the processing unit 12 determines estimates of the aforementioned concentrations C1 and C2.

Purely by way of example, in the numerical processing, 65 the processing unit 12 may be based upon the use of the following approximate relations:

 $I_1 = I_{10} \cdot e^{-x \cdot [\sigma 1m \cdot C1 + \sigma 2m \cdot C2]PS}$ 

 $I_2 = I_{20} \cdot e^{-x \cdot \sigma 3m \cdot C2}$ 

where  $\sigma$ 1m is the integral of the absorption cross-section for nitrogen monoxide NO in the range 200-230 nm, σ2m is the integral of the absorption cross-section for nitrogen dioxide NO<sub>2</sub> in the range 200-230 nm, and σ3m is the integral of the absorption cross-section for nitrogen dioxide NO<sub>2</sub> in the range 230-400 nm.

As illustrated qualitatively in FIG. 5, the first optoelectronic sensor 2 may be formed by a first wide-band sensor 30a, having a band at least equal to 200-400 nm, and by a first optical filter 32a, having a passband of 200-230 nm and arranged over the first wide-band sensor 30a. The first optical filter 32a may be formed in a per se known manner by a plurality of dielectric layers; further, the first optical filter 32a may be integrated with the first wide-band sensor 30a, or else may be physically separate from the latter. Likewise, the second optoelectronic sensor 4 may be formed In greater detail, with reference to the intensity of the 20 by a second wide-band sensor 30b, having a band at least equal to 200-400 nm, and by a second optical filter 32a, having a passband of 230-400 nm and arranged over the second wide-band sensor 30b. The second optical filter 32bmay be formed in a per se known manner by a plurality of dielectric layers; further, the second optical filter 32b may be integrated with the second wide-band sensor 30b, or else may be physically separate from the latter.

According to the embodiment illustrated in FIGS. 6 and 7, the first and second optoelectronic sensors 2, 4 are integrated with one another and form a semiconductor device of a monolithic type.

In detail, the detection device 1 comprises a semiconductor body 40 of silicon carbide SiC of the 4H type, which in turn comprises a substrate 42 and an epitaxial layer 44,

In greater detail, the substrate 42 is of an N type (for example, doped with nitrogen), has a thickness of, for example, 350 µm and has a doping level of, for example, 10<sup>19</sup> cm<sup>-3</sup>. The epitaxial layer 44 is of N-type (for example, doped with nitrogen) and has a doping level of, for example, 10<sup>14</sup> cm<sup>-3</sup>. Further, the epitaxial layer **44** includes a first epitaxial region 45 and a second epitaxial region 46, arranged alongside one another, the first epitaxial region 45 having a thickness comprised, for example, in the range 45 0.3-0.5 μm, and the second epitaxial region 46 having a thickness comprised, for example, in the range 4-6 µm. The first and second epitaxial regions 45, 46 are delimited at the top by a first top surface  $S_{a1}$  and a second top surface  $S_{a2}$ , respectively, whereas the substrate 42 is delimited at the bottom by a bottom surface  $S_b$ .

The semiconductor body 40 further comprises a first anode region 48 and a second anode region 50, of a P+ type (for example, doped with aluminium) and with peak doping level of approximately  $10^{18}$  cm<sup>-3</sup>. More in particular, the first anode region 48 extends within the first epitaxial region 45, starting from the first top surface  $S_{a1}$  and with a thickness comprised, for example, in the range 0.1-0.2 µm. Furthermore, the second anode region 50 extends within the second epitaxial region 46, starting from the second top surface  $S_{a2}$  and with a thickness comprised, for example, in the range 0.1-0.2 µm. Consequently, the first and second anode regions 48, 50 overlie, respectively, a portion of the first epitaxial region 45 and a portion of the second epitaxial region 46, which have thicknesses, respectively, comprised, for example, in the ranges  $0.1-0.4 \mu m$  and  $3.8-5.9 \mu m$ .

The first anode region 48 and the first epitaxial region 45 form the first optoelectronic sensor 2, and in particular form

a first PN junction, where the so-called "epilayer", formed by the portion of the first epitaxial region 45 underlying the first anode region 48, has a thickness comprised in the range 0.1-0.4 µm. This first PN junction is thus rather shallow and is arranged in the proximity of the first top surface  $S_{a1}$ . This 5 implies, as illustrated in FIG. 8, that substantially all the radiation that traverses the first PN junction and has a wavelength shorter than 230 nm is absorbed by the junction itself.

The second anode region 50 and the second epitaxial 10 region 46 form the second optoelectronic sensor 4, and in particular form a second PN junction, where the so-called "epilayer" has a large thickness. Furthermore, present on a first portion of the second anode region 50 is an absorption layer **59**, for example, of polysilicon and having the function 15 of absorbing radiation having a wavelength shorter than 230 nm, before it impinges upon the second PN junction. For instance, the absorption layer 59 may have a thickness comprised in the range 10-50 nm.

The detection device 1 likewise comprises a first anode 20 metallization 60 and a second anode metallization 62, which are, for example, of titanium and an AlSiCu alloy (for simplicity of exposition, the distinction between titanium and AlSiCu alloy is not illustrated in FIG. 7). Furthermore, the first and second anode metallizations 60, 62 are 25 arranged, respectively, on the first and second anode regions 48, 50, with which they are, respectively, in direct contact. In particular, without this implying any loss of generality, the second anode metallization 62 extends over a second portion of the second anode region 50 so as to be laterally 30 staggered with respect to the absorption layer **59**. Further, the first anode metallization 60 extends over a side portion of the first anode region 48.

The detection device 1 further comprises a layer 66, The contact layer 66 is arranged underneath the bottom surface S<sub>b</sub> and is, for example, of nickel silicide Ni<sub>2</sub>Si; purely by way of example, the contact layer 66 may have a thickness of, for example, 40 nm. Furthermore, the detection device 1 comprises a cathode metallization 68, arranged 40 underneath the contact layer 66 and formed for example by a multilayer structure including layers (not illustrated individually) formed by titanium, nickel, and gold.

In practice, the first and second epitaxial regions 45, 46 form corresponding cathode regions. Furthermore, the low 45 doping level of the epitaxial layer 44 causes, even in the absence of biasing, complete depletion both of the portion of the first epitaxial region 45 overlaid by the first anode region 48 and of the portion of the second epitaxial region 46 overlaid by the second anode region **50**. Furthermore, both 50 the first and the second optoelectronic sensors 2, 4 can be biased simultaneously through the cathode metallization 68, while the first and second detection signals generated by them can be acquired, respectively, at the first and second anode metallizations 60, 62.

According to a different embodiment (illustrated in FIG. 9), each one of the first and second optoelectronic sensors 2, 4 includes a Schottky junction, as well as a PN junction.

In detail, the detection device 1 comprises, instead of the first and second anode regions 48, 50, a first metal region 70 60 and a second metal region 72, which extend, respectively, on the first and second top surfaces  $S_{a1}$ ,  $S_{a2}$  so as to contact directly the first and second epitaxial regions 45, 46, respectively. In this case, the first and second epitaxial regions 45, 46 have thicknesses, respectively, comprised, for example, 65 in the ranges 0.1-0.4  $\mu$ m and 3.8-5.9  $\mu$ m. The first and second anode metallizations 60, 62 contact, respectively, the

first and second metal regions 70, 72. Further, the second metal region 72 is overlaid by the absorption layer 59.

Without this implying any loss of generality, in what follows a method is described for manufacturing the embodiment illustrated in FIG. 7.

Initially, as illustrated in FIG. 10, the semiconductor body 40 made up of the substrate 42 and the epitaxial layer 44 is formed. Furthermore, formed on the epitaxial layer 44 is a first layer of TEOS oxide 80 having a thickness of, for example, 20 µm (FIG. 10, as on the other hand also the subsequent figures, as well as FIGS. 6, 7 and 9 are not in scale). Then, formed underneath the substrate 42 is the contact layer 66, for example by sputtering and subsequent annealing, the latter being carried out, for example, at 1000° C., in the presence of nitrogen  $N_2$ , and having a duration of one minute.

Next, as illustrated in FIG. 11, provided on the first layer of TEOS oxide is a first mask 82, for example a resist mask.

Then, as illustrated in FIG. 12, a process of photolithography is carried out in order to remove a portion of the first layer of TEOS oxide 80 so as to expose a part of the epitaxial layer 44. Then, the first mask 82 is removed.

Next, as illustrated in FIG. 13, a process of reactive ion etching (RIE) is carried out so as to form the first and second epitaxial regions 45, 46, as well as the first and second top surfaces  $S_{a1}$ ,  $S_{a2}$ . In particular, a top portion of the exposed part of the epitaxial layer 44 is selectively removed in order to form the first epitaxial region 45. Then, the residual portion of the first layer of TEOS oxide **80** is removed.

Next, as illustrated in FIG. 14, formed on the first and second top surfaces  $S_{a1}$ ,  $S_{a2}$  is a second layer of TEOS oxide **84**, which has a thickness comprised, for example, between 50 nm and 100 nm.

Then, as illustrated in FIG. 15, by a process of photoliwhich will be referred to hereinafter as "contact layer 66". 35 thography and a subsequent ion-implantation of dopant species of a P type, a first thin layer 48' and a second thin layer 50' are formed, which extend, respectively, in the first and second epitaxial regions 45, 46, starting from the first top surface  $S_{a1}$  and the second top surface  $S_{a2}$ , respectively. In addition, the first and second thin layers 48', 50' are to form, respectively, the first and second anode regions 48, 50, once the appropriate thermal treatments are terminated, as explained hereinafter.

> In greater detail, the aforementioned step of ion implantation, indicated by the arrows 90, may comprise a plurality of high-dosage implants  $(5.10^{14}-3.10^{15} \text{ cm}^{-2})$  and increasing energy (for example, in the range 50-200 keV), at a temperature of 400° C., and envisages the use of a second resist mask 92 for reducing the contamination of sites external to the regions in which the implantation itself is to be carried out.

Next, as illustrated in FIG. 16, the second mask 92 is removed, for example by a further wet etch, and annealing is carried out, which enables formation of the first and second anode regions 48, 50, respectively, starting from the first and second thin layers 48', 50'.

Next, as illustrated in FIG. 17, the second layer of TEOS oxide **84** is removed. Furthermore, deposited on the first and second top surfaces  $S_{a1}$ ,  $S_{a2}$  is a polysilicon layer 100 having, for example, a thickness comprised in the range 10-50 nm. Provided on the polysilicon layer 100 is a third mask 102.

Next, as illustrated in FIG. 18, a further process of photolithography is carried out in order to remove selectively portions of the polysilicon layer 100, for example by a wet etch so as to form the absorption layer **59**. Then, the third mask 102 is removed.

Next, as illustrated in FIG. 18, formed on the first and second top surfaces  $S_{a1}$ ,  $S_{a2}$ , as well as on the absorption layer 59, is a barrier layer 110, for instance, of titanium and having a thickness of, for example, 100 nm. In addition, formed on the barrier layer 110 is a functional layer 112 of 5 a metal type, for example, of the AlSiCu alloy. Both the barrier layer 110 and the functional layer 112 may be obtained by sputtering.

Next, as illustrated in FIG. 19, portions of the barrier layer 110 and of the functional layer 112 are selectively removed, 10 for example by a wet etch, so as to form the first and second anode metallizations 60, 62.

Finally, in a way not illustrated, the cathode metallization **68** is formed, for example by sputtering, underneath the contact layer **66**.

In the case where, instead, an embodiment is adopted in which the first and second optoelectronic sensors form respective Schottky junctions, this may be obtained by carrying out the operations illustrated in FIGS. 10-13. Next, as illustrated in FIG. 20, a metal layer 130 is formed on the 20 first and second epitaxial regions 45, 46, which is then patterned, by selective removal of portions, so as to form the first and second metal regions 70, 72. The absorption layer 59 and the first and second anode metallizations 60, 62 are then formed as described previously, but on the first and 25 second metal regions 70, 72.

From what has been described and illustrated previously, the advantages that the present solution affords emerge clearly.

In particular, the present detection device enables simul- 30 taneous detection of the concentrations of two different chemical species, with a high sensitivity.

For this purpose, the first and second optoelectronic sensors are illuminated simultaneously by the optical source.

Furthermore, in the case where the first and second 35 optoelectronic sensors are of silicon carbide, the sensitivity is kept high also at high temperature, thanks to the low leakage currents in the silicon carbide. Further, both the first optoelectronic sensor and the second optoelectronic sensor may be reverse biased with very low voltages (in modulus), 40 possibly even in the photovoltaic regime. In addition, the first and second optoelectronic sensors can operate also in the presence of chemical agents and have characteristics that remain very stable over time.

Furthermore, in the case where the first and second 45 optoelectronic sensors are integrated with one another, the detection device has very small overall dimensions. Again, the detection device may readily be adapted to different pairs of chemical species by varying the thickness and the material of the epitaxial layer accordingly. In addition, the 50 detection device may be used not only in the presence of a fluid substantially at rest, or even in the presence of a solid containing the chemical species to be detected.

In conclusion, it is clear that modifications and variations 55 may be made to what has been described and illustrated herein, without thereby departing from the scope of the present disclosure.

As mentioned previously, the first and second optoelectronic sensors may be sensors of a different type, such as for 60 example vacuum photomultiplier tubes (PMTs). Furthermore, in the case where the first and second sensors are again semiconductor sensors integrated together, the semiconductor body may be formed by a semiconductor material different from silicon carbide, such as for example silicon, or 65 else gallium nitride GaN or aluminium gallium nitride AlGaN.

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In addition, the first and the second sensitivity bands, which correspond, respectively, to the first and second optoelectronic sensors, may be separate from one another. It is likewise possible for the first and second sensitivity bands to be instead partially overlapping in an intersection range. In this case, it is possible, but not necessary, for the absorption cross-section for at least one of the first and second chemical species to be zero within the intersection range. In general, even though the fact that the absorption crosssection for a chemical species is zero in the second absorption band simplifies the operations performed by the processing unit 12, it is in any case possible that in each one of the first and second sensitivity bands the absorption crosssections for both of the chemical species to be detected are 15 at least locally (i.e., in a portion of the sensitivity range) nonzero. In this case, with reference, for example, once again to nitrogen monoxide NO and nitrogen dioxide NO<sub>2</sub>, the intensity of the radiation that impinges upon the second optoelectronic sensor is equal to

$$I_2 = I_{20} \cdot \int e^{-x \cdot [\sigma 4(\lambda) \cdot C1 + \sigma 3(\lambda) \cdot C2]} d\lambda$$

where  $\sigma 4(\lambda)$  is the absorption cross-section for nitrogen oxide NO. The latter relation may be approximated as:

$$I_2 = I_{20} \cdot e^{-x \cdot [\sigma 4m \cdot C1 + \sigma 3m \cdot C2]}$$

where  $\sigma$ 4m is the integral of the absorption cross-section for nitrogen oxide NO in the second sensitivity band. The processing unit 12 can thus determine the concentrations C1 and C2 by solving a system of two equations with two unknowns, on the basis of the intensities  $I_1$  and  $I_2$ .

In general, it is further possible for the optical source to have a non-constant spectrum, in which case the numeric processing operation executed by the processing unit 12 is modified in a per se known manner.

As regards the processing unit 12, this may be integrated in the semiconductor body 40, and thus may be integrated with the first and second optoelectronic sensors 2, 4, or else may be external to the latter.

As regards the first and second anode regions, when these are arranged on the first and second top surfaces  $S_{a1}$ ,  $S_{a2}$ , they may be formed by a non-metal conductive material, such as for example polysilicon. Consequently, the first and second metal regions 70, 72 may be replaced by corresponding non-metal conductive regions, for instance of polysilicon. In this case, during manufacture, a corresponding conductive layer is formed, instead of the metal layer 130.

As regards the absorption layer **59**, this may be of a material different from polysilicon, such as silicone, or else an optically absorbent metal material, such as titanium nitride TiN.

Finally, all the types of doping may be reversed with respect to what has been described.

The various embodiments described above can be combined to provide further embodiments. These and other changes can be made to the embodiments in light of the above-detailed description. In general, in the following claims, the terms used should not be construed to limit the claims to the specific embodiments disclosed in the specification and the claims, but should be construed to include all possible embodiments along with the full scope of equivalents to which such claims are entitled. Accordingly, the claims are not limited by the disclosure.

The invention claimed is:

- 1. A device, comprising:
- a substrate with a first surface and a second surface facing away from the first surface;

- an epitaxial layer on the first surface of the substrate, the epitaxial layer having plurality of edges, a third surface with a first perimeter, and a fourth surface with a second perimeter, the third surface is closer to the first surface of the substrate than the fourth surface;
- a first anode region on the third surface of the epitaxial layer and positioned within the first perimeter, the first anode region spaced from the plurality of edges of the epitaxial layer;
- a second anode region on the fourth surface of the epitaxial layer and positioned within second perimeter, the second anode region spaced from the plurality of edges of the epitaxial layer;
- a first anode metallization on the first anode region; and a second anode metallization on the second anode region.
- 2. The device of claim 1, further comprising a contact layer on the second surface of the substrate.
- 3. The device of claim 2, further comprising a cathode layer on the contact layer.
- 4. The device of claim 1, wherein the epitaxial layer further comprises a wall extending from the third surface to the fourth surface, the wall positioned between the first anode region and the second anode region.
  - 5. The device of claim 4, wherein:
  - the first perimeter includes a plurality of first sides aligned with respective edges of the plurality of edges and a second side aligned with the wall; and
  - the second perimeter includes a plurality of first sides aligned with respective edges of the plurality of edges 30 and a second side aligned with the wall.
- 6. The device of claim 1, further comprises an absorption layer on the second anode region.
  - 7. The device of claim 1, wherein:
  - the first anode metallization is positioned adjacent to a 35 center of an edge of the first anode region; and
  - the second anode metallization is positioned adjacent to a center of an edge of the second anode region.
  - 8. A device, comprising:
  - a substrate with a first surface and a second surface facing 40 away from the first surface;
  - an epitaxial layer on the first surface of the substrate, the epitaxial layer having a third surface, a fourth surface, and fifth surface, the third surface and the fourth surface face away from the first surface of the substrate, 45 the fifth surface of the epitaxial layer extends from the third surface to the fourth surface and extends from the third surface to the fourth surface;
  - a first optoelectronic sensor on the third surface of the epitaxial layer; and
  - a second optoelectronic sensor on the fourth surface of the epitaxial layer.
- 9. The device of claim 8, wherein the fifth surface is positioned between the first optoelectronic sensor and the second optoelectronic sensor.
- 10. The device of claim 8, wherein the fifth surface separates the third surface from the fourth surface.
  - 11. The device of claim 8, further comprising:
  - a contact layer on the second surface of the substrate; and
  - a cathode metallization layer on the contact layer, the 60 cathode metallization layer is electrically coupled to the first anode region and the second anode region.
- 12. The device of claim 8, wherein the first optoelectronic sensor further comprises:
  - an anode region on the third surface of the epitaxial layer; 65 and
  - an anode metallization on the anode region.

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- 13. The device of claim 12, wherein the anode metallization on the anode region is positioned adjacent to a center of an edge of the anode region.
- 14. The device of claim 8, wherein the second optoelectronic sensor further comprises:
  - an anode region on the fourth surface of the epitaxial layer;
  - an anode metallization on the anode region; and
  - an absorption layer on the anode region that abuts the anode metallization.
- 15. The device of claim 14, wherein the anode metallization on the anode region is positioned adjacent to a center of an edge of the anode region.
  - 16. A method, comprising:
  - forming an epitaxial layer with a first portion with a first thickness and a second portion with a second thickness greater than the first thickness on a first surface of a substrate;
  - forming a contact layer on a second surface of the substrate facing away from the first surface of the substrate;
  - forming a first anode region on the first portion of the epitaxial layer and a second anode region on the second portion of the epitaxial layer;
  - forming a first anode metallization on the first anode region and a second anode metallization on the second anode region; and

forming a cathode layer on the contact layer.

17. The method of claim 16, wherein forming the epitaxial layer with the first portion with the first thickness and the second portion with the second thickness further comprises:

forming an oxide layer on the epitaxial layer;

forming a mask layer on the oxide layer;

removing a portion of the oxide layer from a location on the epitaxial layer;

etching the epitaxial layer at the location forming the first portion of the epitaxial layer with the first thickness, the second portion with the second thickness, and a wall that extends from a surface of the first portion to a surface of the second portion; and

removing the mask layer and the oxide layer aligned with the second portion of the epitaxial layer.

18. The method of claim 16, wherein forming the first anode region and the second anode region further comprises: forming an oxide layer on the first portion of the first

epitaxial layer; and the second portion of the first epitaxial layer;

forming a mask layer on the oxide layer;

removing portions of the mask layer to expose portion of the oxide layer;

exposing the exposed portions of the oxide layer to ions; and

removing the mask layer and the oxide layer.

- 19. The method of claim 16, further comprising forming an absorption layer on the second anode region including: forming a polysilicon layer on the first portion and the second portion of the epitaxial layer;
  - forming a mask layer on the polysilicon layer, the mask layer is aligned with the second anode region;
  - etching the polysilicon layer forming the absorption layer on the second anode region, the absorption layer covering a first portion of the second anode region and exposing a second portion of the second anode region; and

removing the mask layer.

20. The method of claim 19, wherein forming the second metallization on the second anode region further comprises:

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forming the second metallization on the second portion of the second anode region that is exposed.

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