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(12) **United States Patent**
Hedgeland et al.

(10) **Patent No.:** **US 10,751,096 B2**
(45) **Date of Patent:** **Aug. 25, 2020**

(54) **SYSTEMS AND METHODS FOR
INTRAMEDULLARY NAIL IMPLANTATION**

(2013.01); *A61B 17/1664* (2013.01); *A61B 17/1742* (2013.01); *A61B 17/7083* (2013.01); *A61B 17/863* (2013.01)

(71) Applicant: **GLOBUS MEDICAL, INC.**, Audubon, PA (US)

(58) **Field of Classification Search**
CPC *A61B 17/7233*; *A61B 17/164*; *A61B 17/1697*; *A61B 17/1721*; *A61B 17/1725*; *A61B 17/7283*; *A61B 17/744*; *A61B 17/1664*; *A61B 17/1742*; *A61B 17/7083*; *A61B 17/863*
USPC 606/62-64, 67, 68, 86 R, 96, 98, 99, 104
See application file for complete search history.

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(*) Notice: Subject to any disclaimer, the term of this patent is extended or adjusted under 35 U.S.C. 154(b) by 19 days.

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(21) Appl. No.: **16/153,873**

(22) Filed: **Oct. 8, 2018**

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(65) **Prior Publication Data**
US 2019/0038326 A1 Feb. 7, 2019

Related U.S. Application Data

(63) Continuation-in-part of application No. 15/441,457, filed on Feb. 24, 2017, now Pat. No. 10,307,197, (Continued)

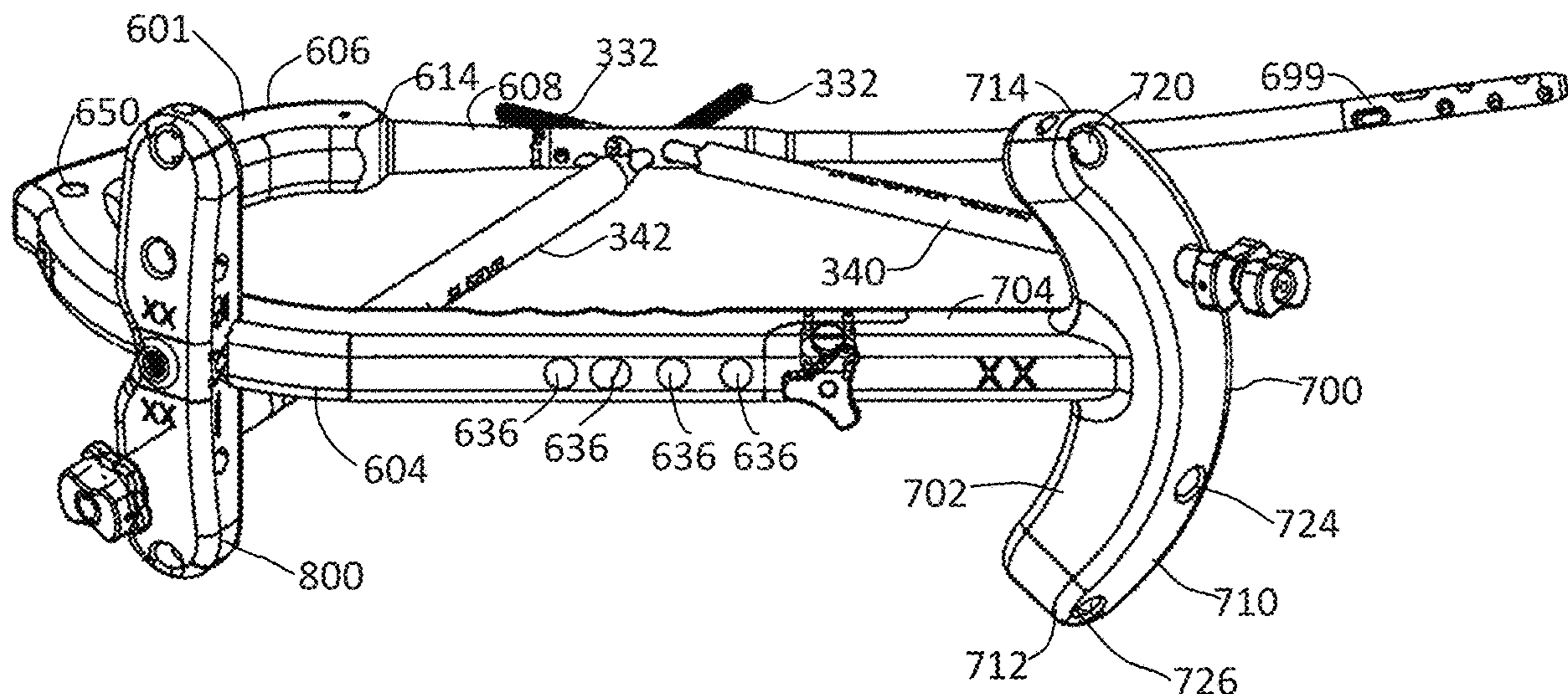
(57) **ABSTRACT**

Intramedullary nails, aiming guide assemblies, and methods. The aiming guide assembly can include an aiming guide having an elongate proximal handle portion. A generally arcuate distal implant alignment tip connector portion is connected to the proximal handle portion and has a distal implant alignment tip extending along a tip axis parallel to a longitudinal axis of the proximal handle portion. A recon module may be releasably attached to a proximal end of the proximal handle portion. An oblique module may be releasably attached to the distal implant alignment tip portion.

(51) **Int. Cl.**
A61B 17/72 (2006.01)
A61B 17/16 (2006.01)
(Continued)

20 Claims, 45 Drawing Sheets

(52) **U.S. Cl.**
CPC *A61B 17/7233* (2013.01); *A61B 17/164* (2013.01); *A61B 17/1697* (2013.01); *A61B 17/1721* (2013.01); *A61B 17/1725* (2013.01); *A61B 17/7283* (2013.01); *A61B 17/744*



Related U.S. Application Data

which is a continuation-in-part of application No. 15/423,773, filed on Feb. 3, 2017, now Pat. No. 10,251,691, which is a continuation-in-part of application No. 15/272,850, filed on Sep. 22, 2016, now Pat. No. 10,299,847.

(51) **Int. Cl.**

A61B 17/17 (2006.01)
A61B 17/74 (2006.01)
A61B 17/70 (2006.01)
A61B 17/86 (2006.01)

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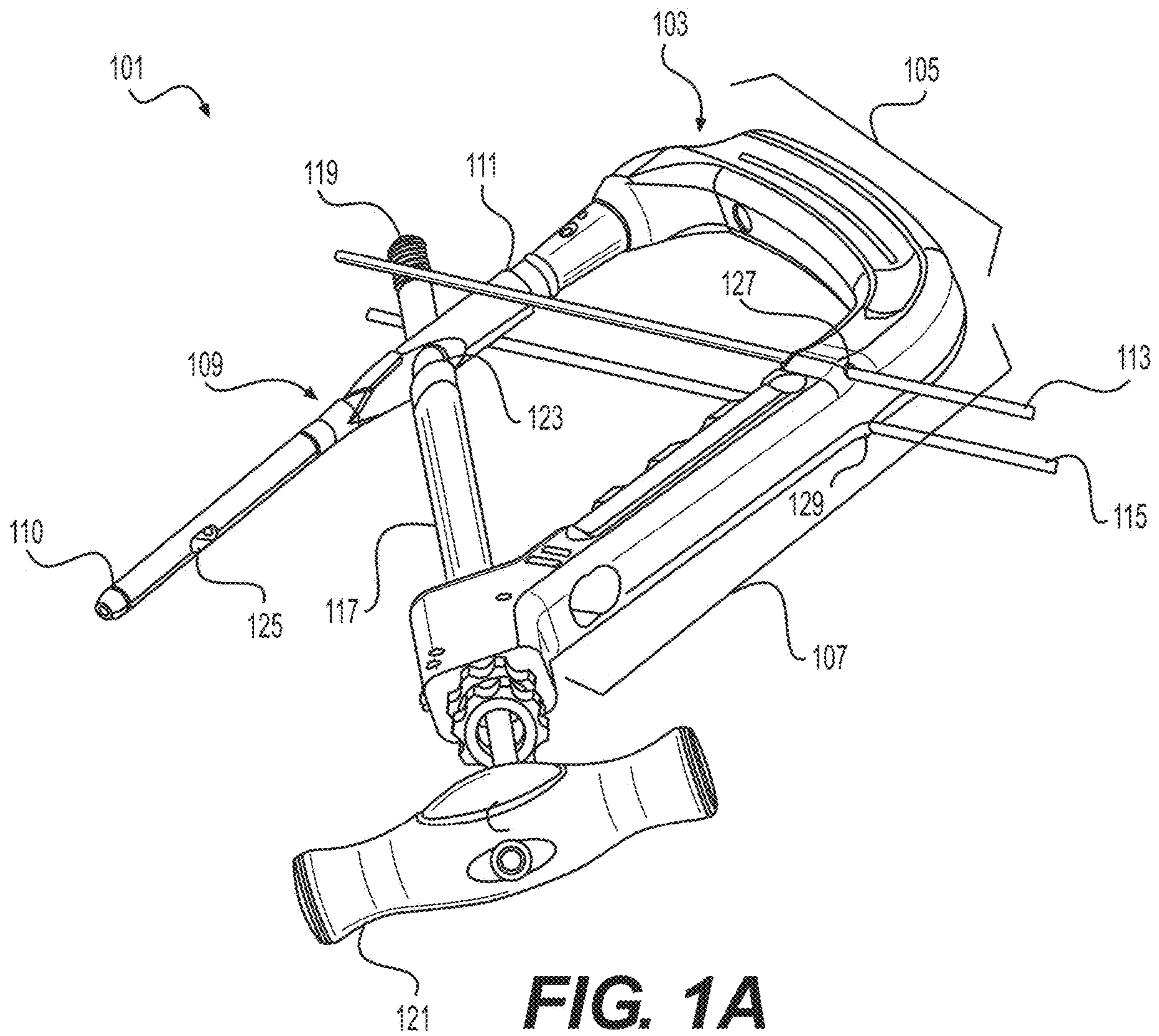
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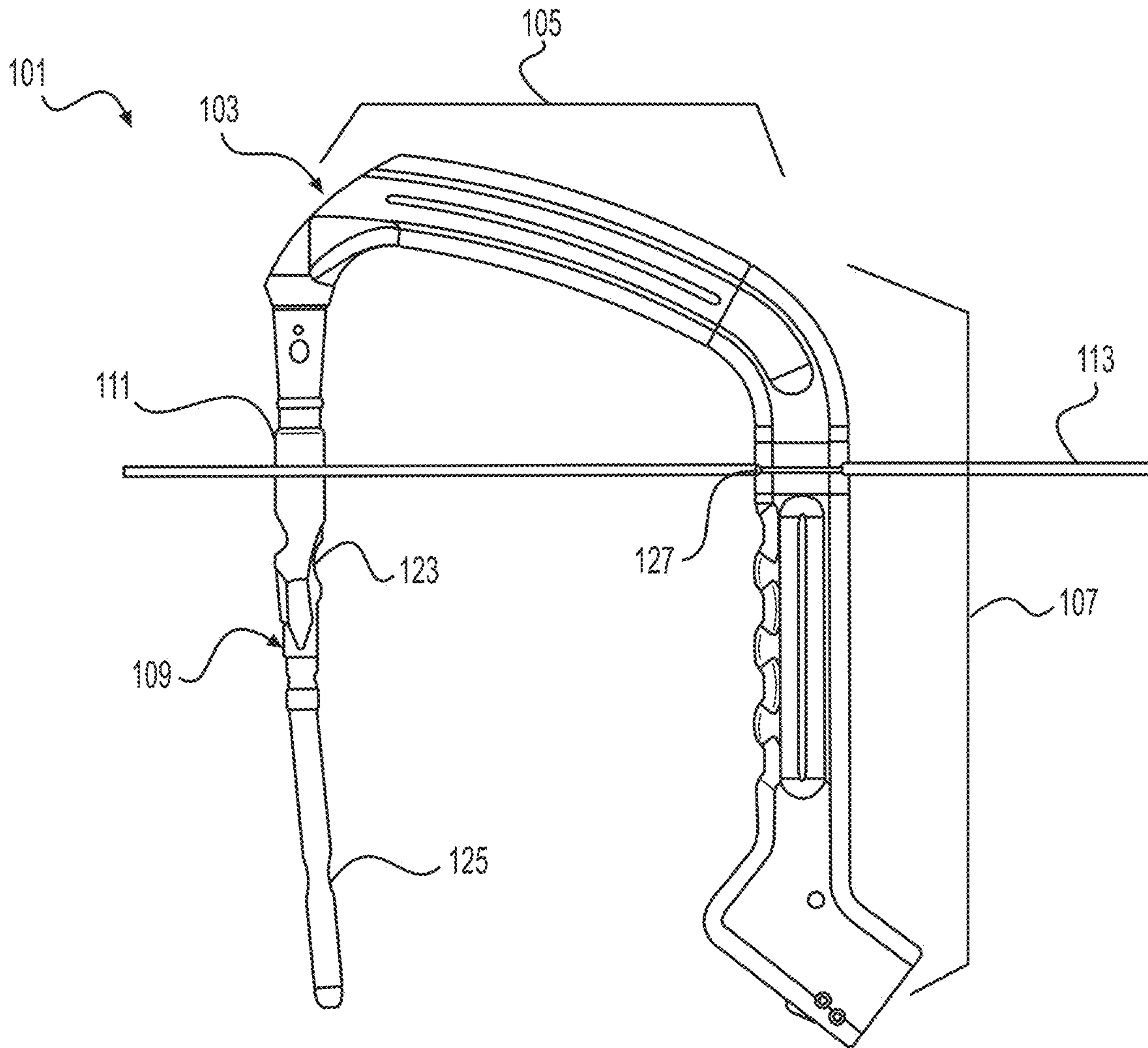


FIG. 1B

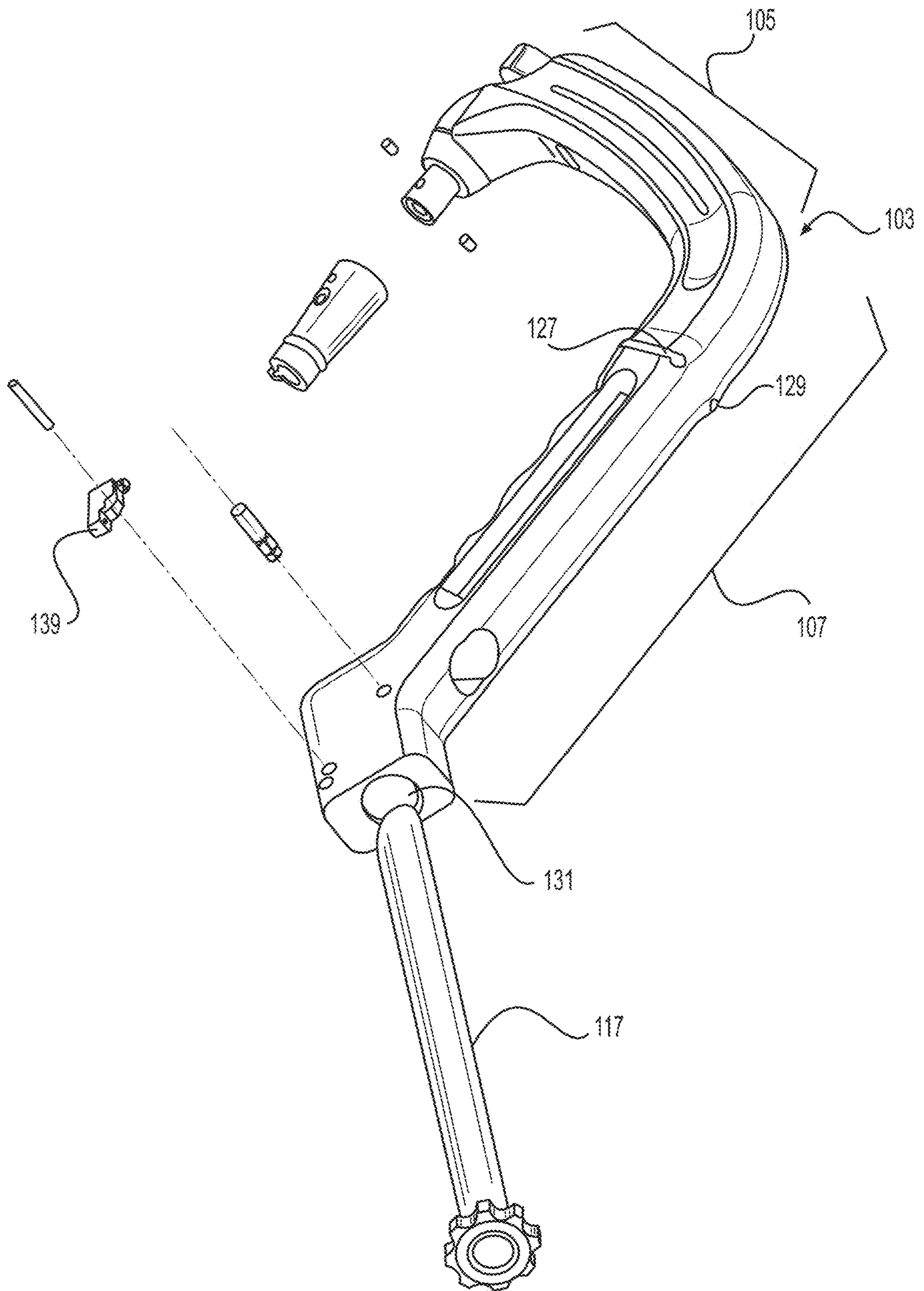


FIG. 2A

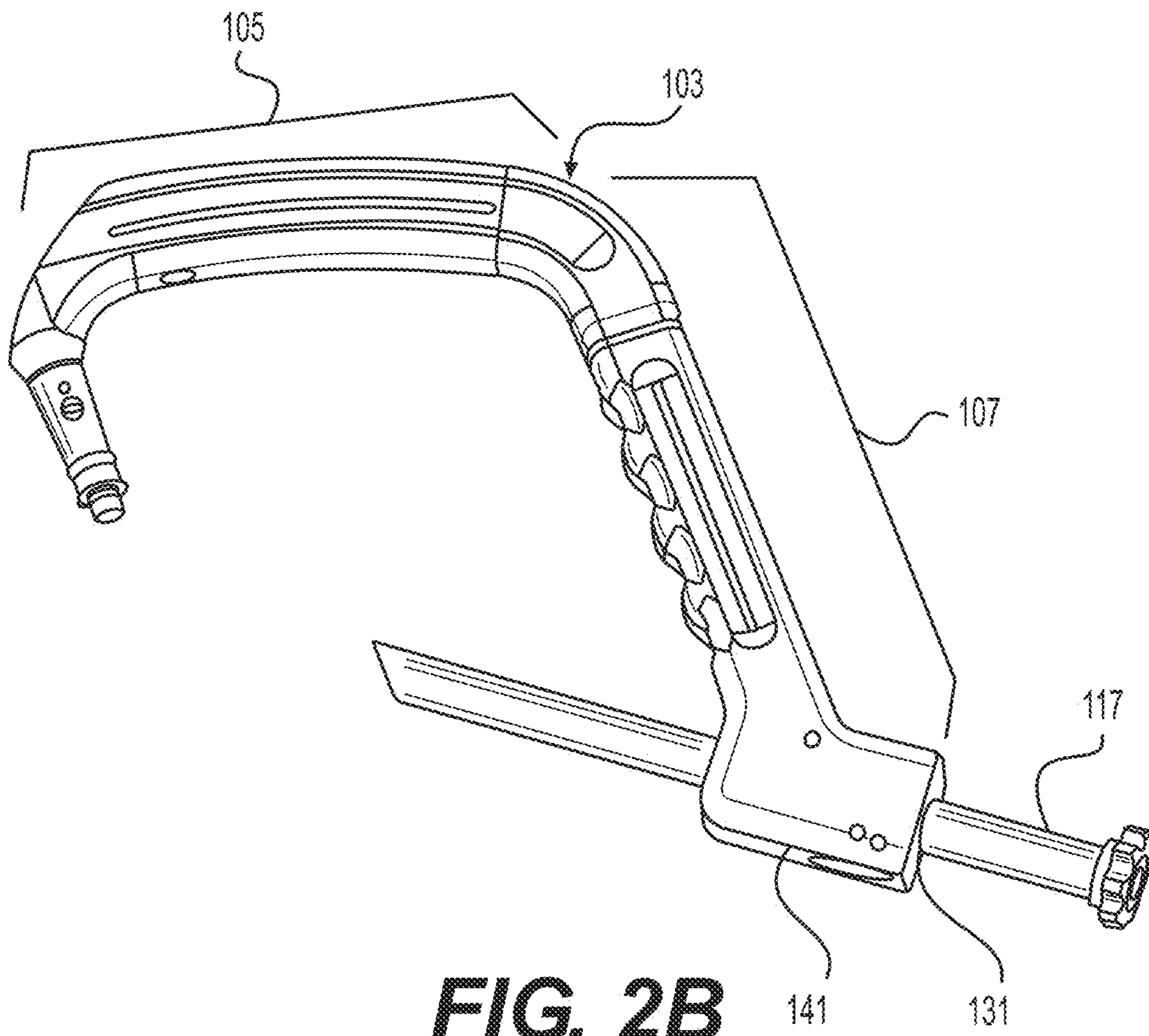


FIG. 2B

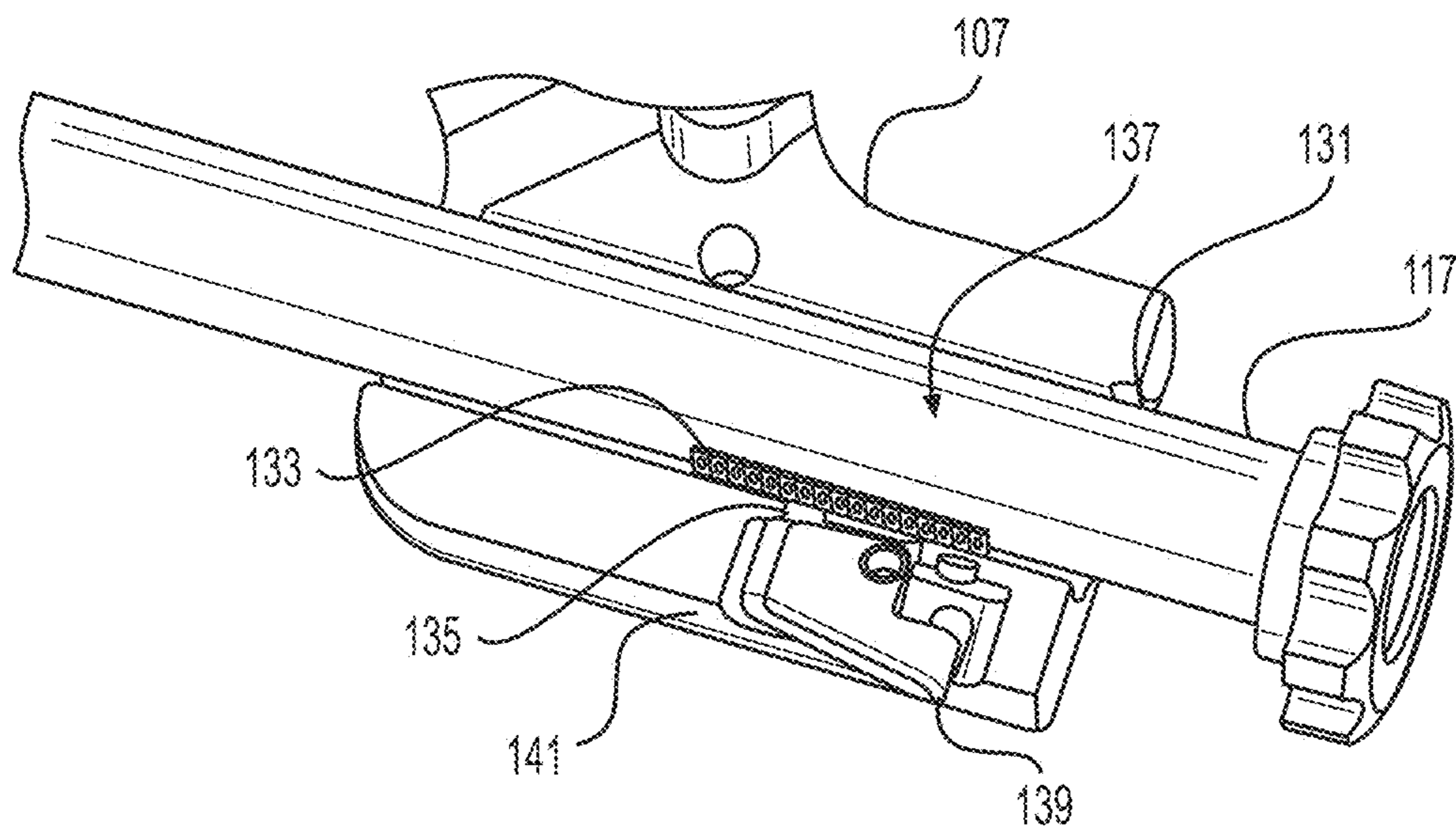


FIG. 2C

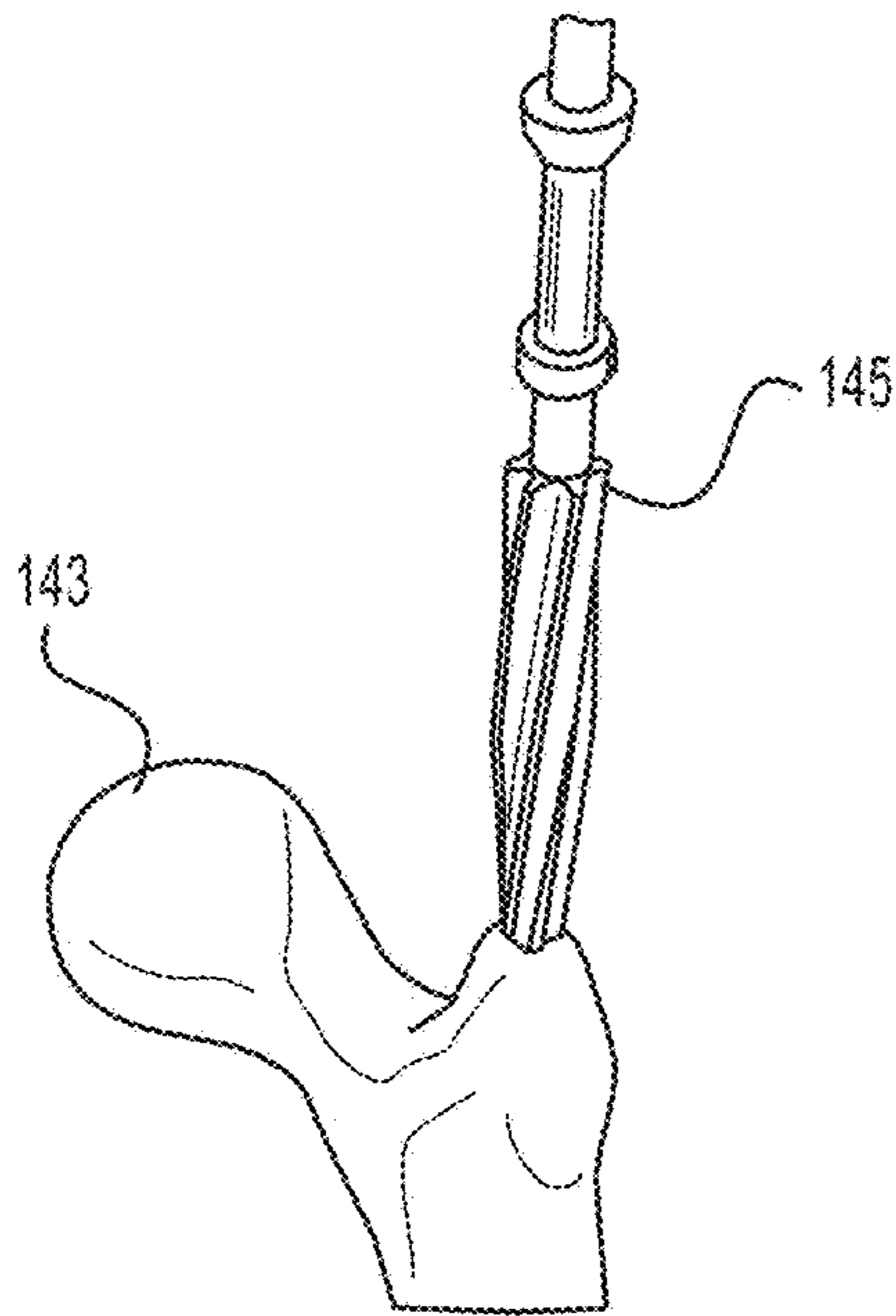


FIG. 3A

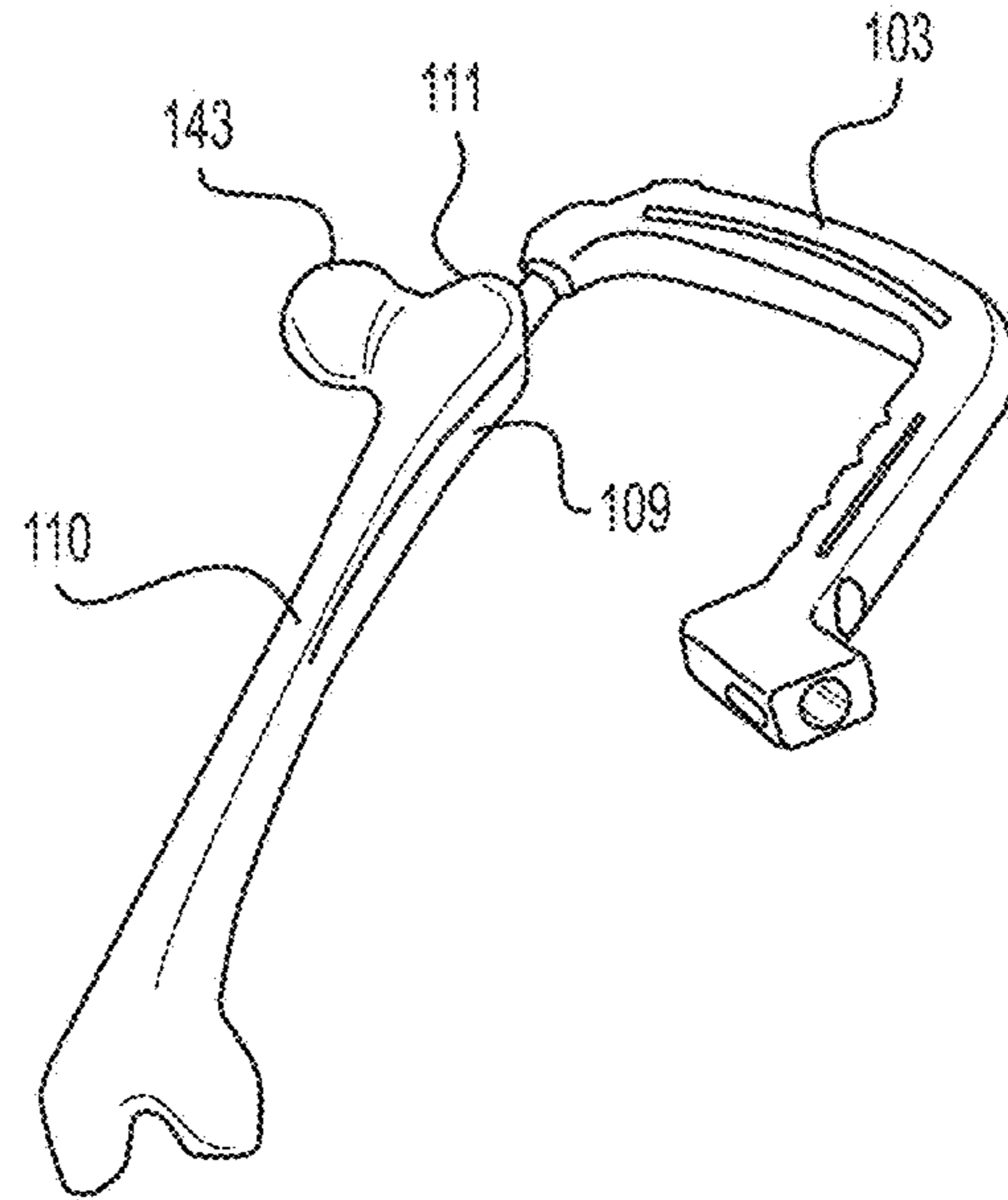


FIG. 3B

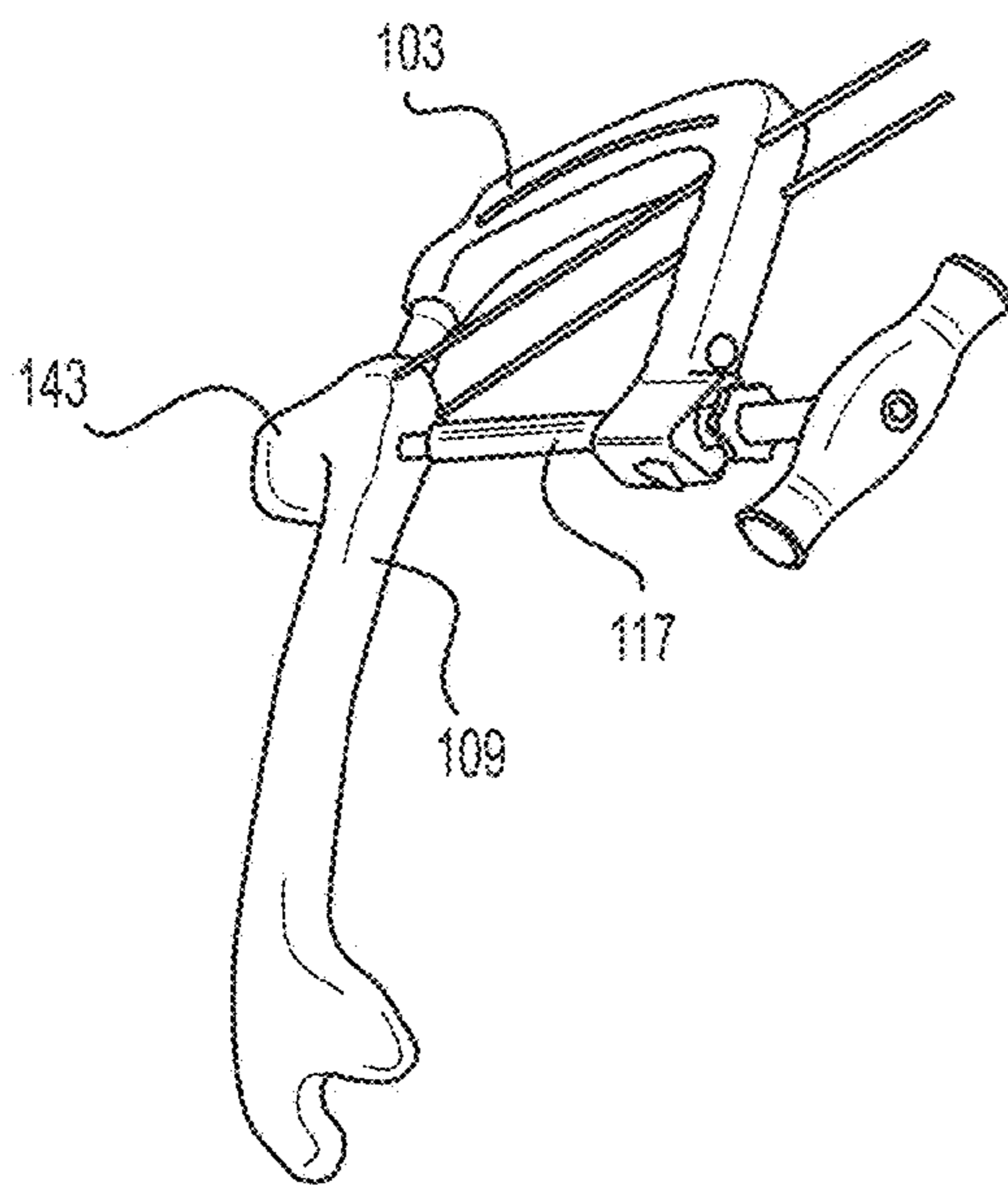


FIG. 3C

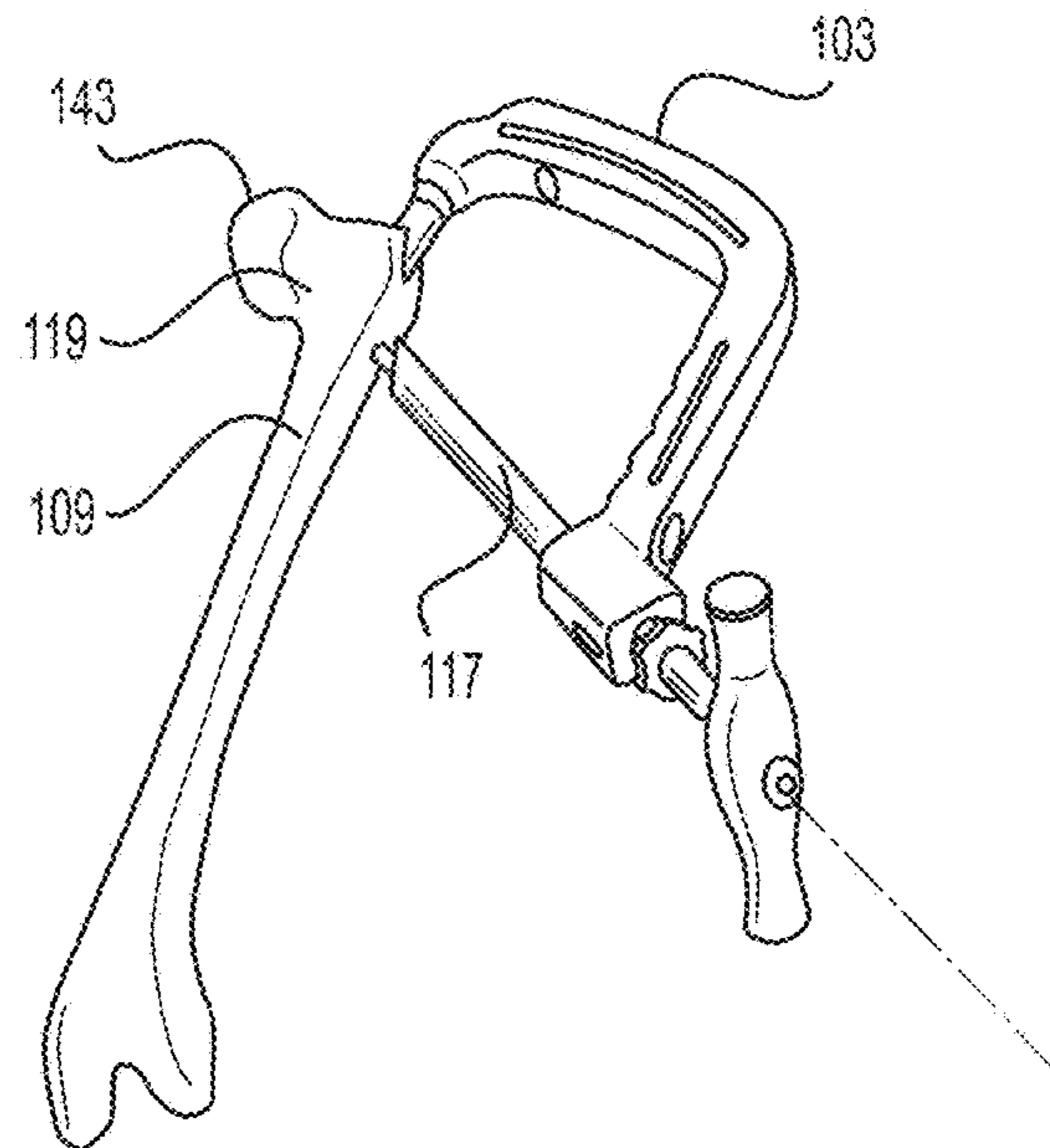


FIG. 3D

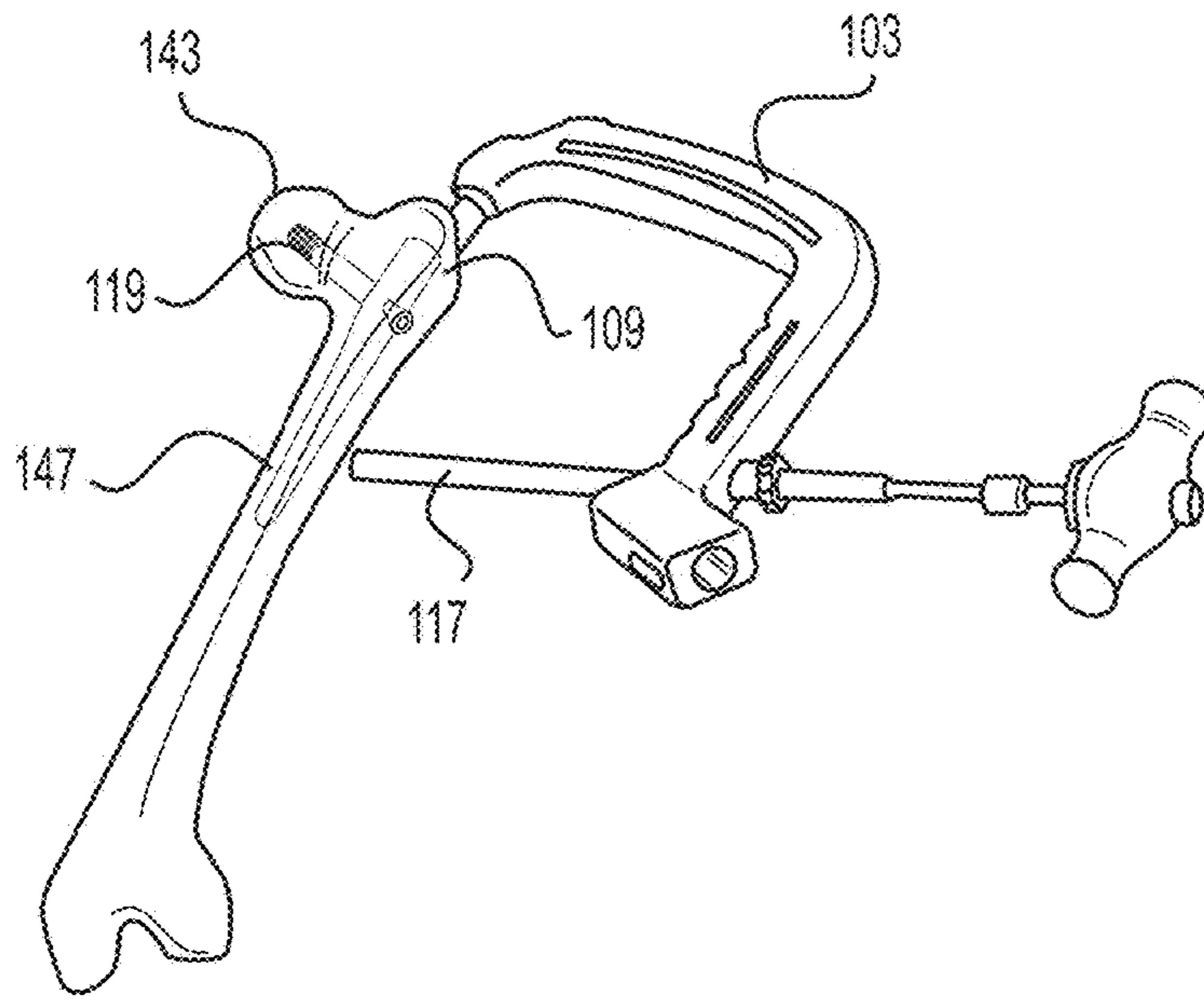


FIG. 3E

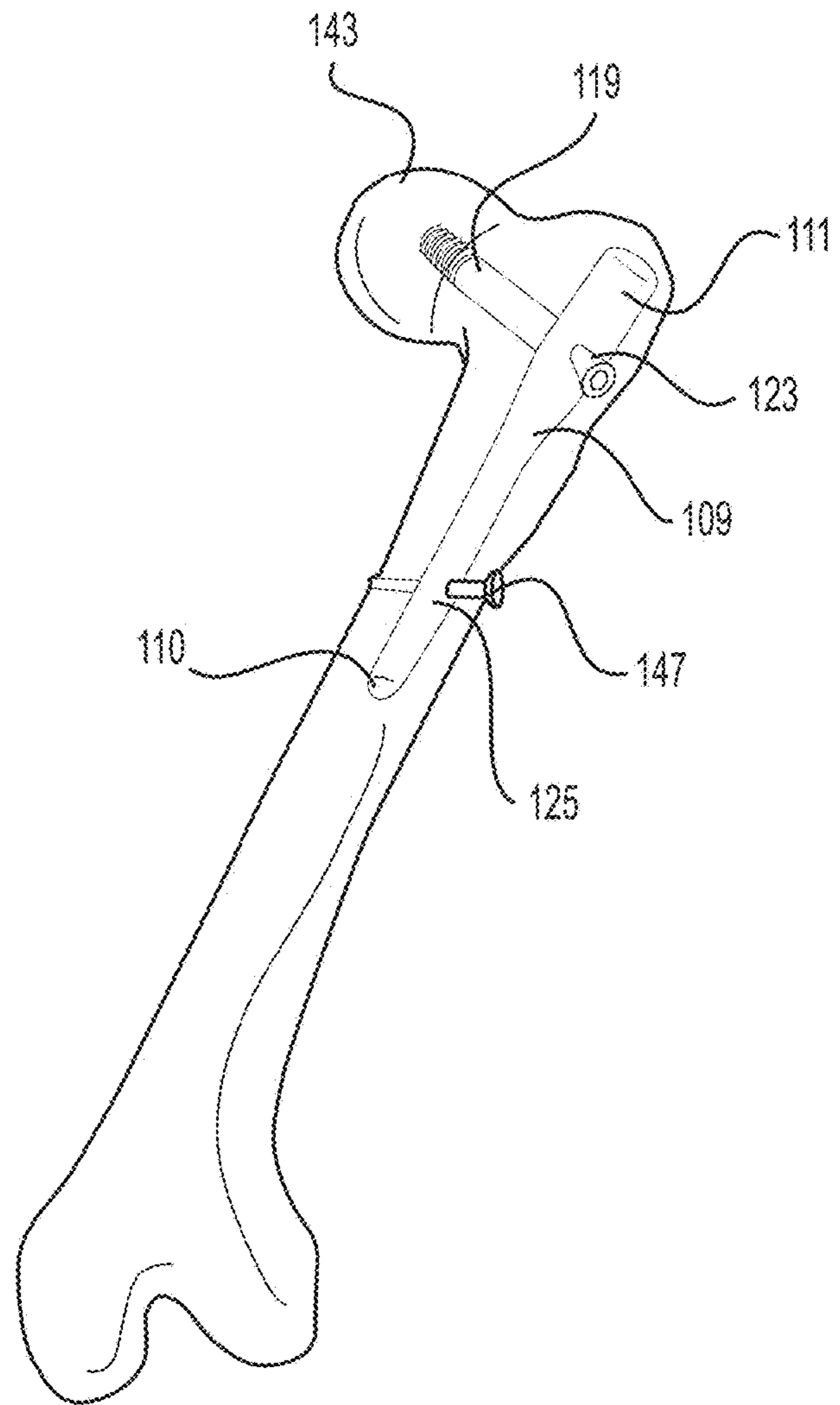


FIG. 3F

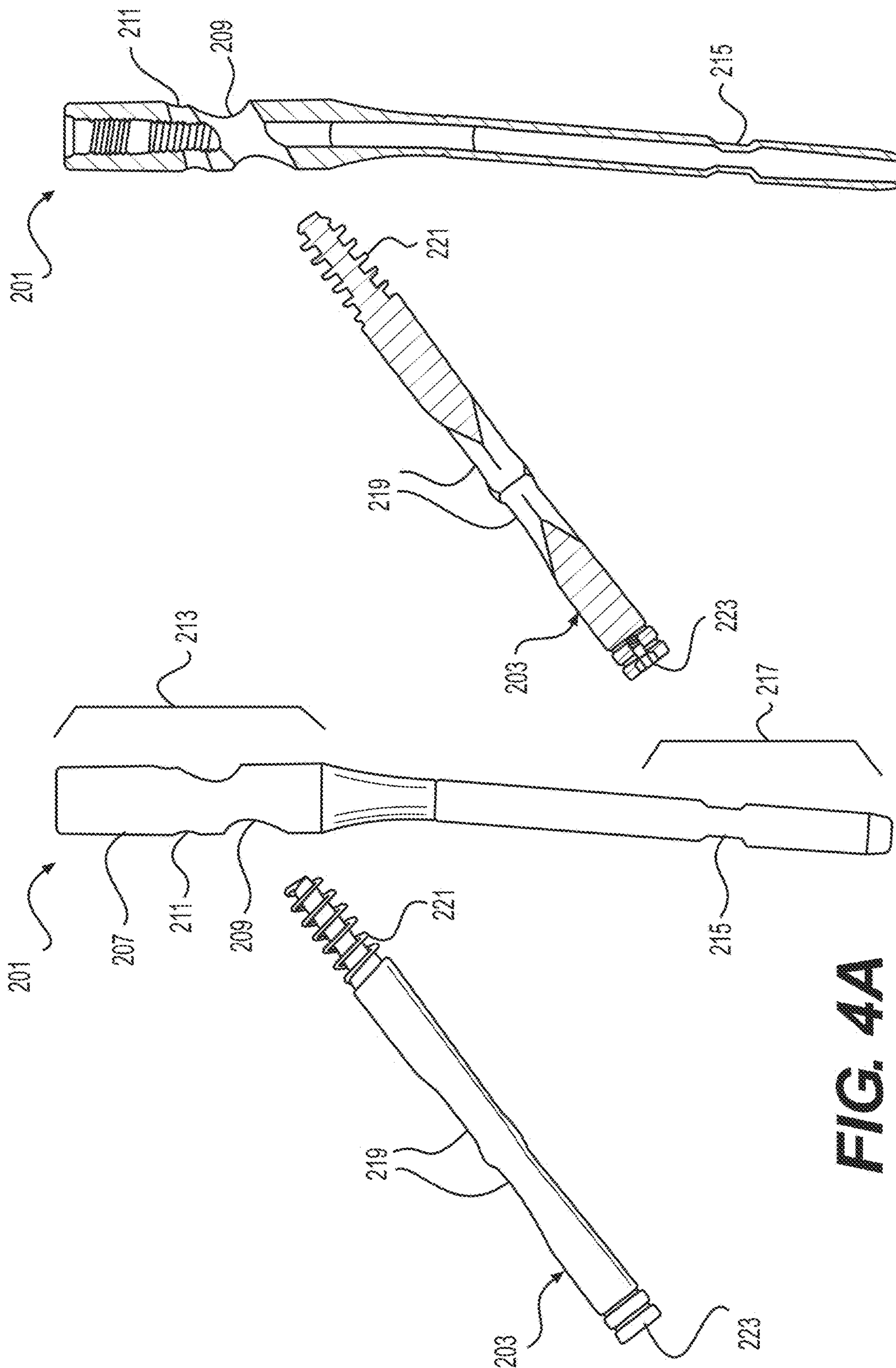


FIG. 4B

FIG. 4A

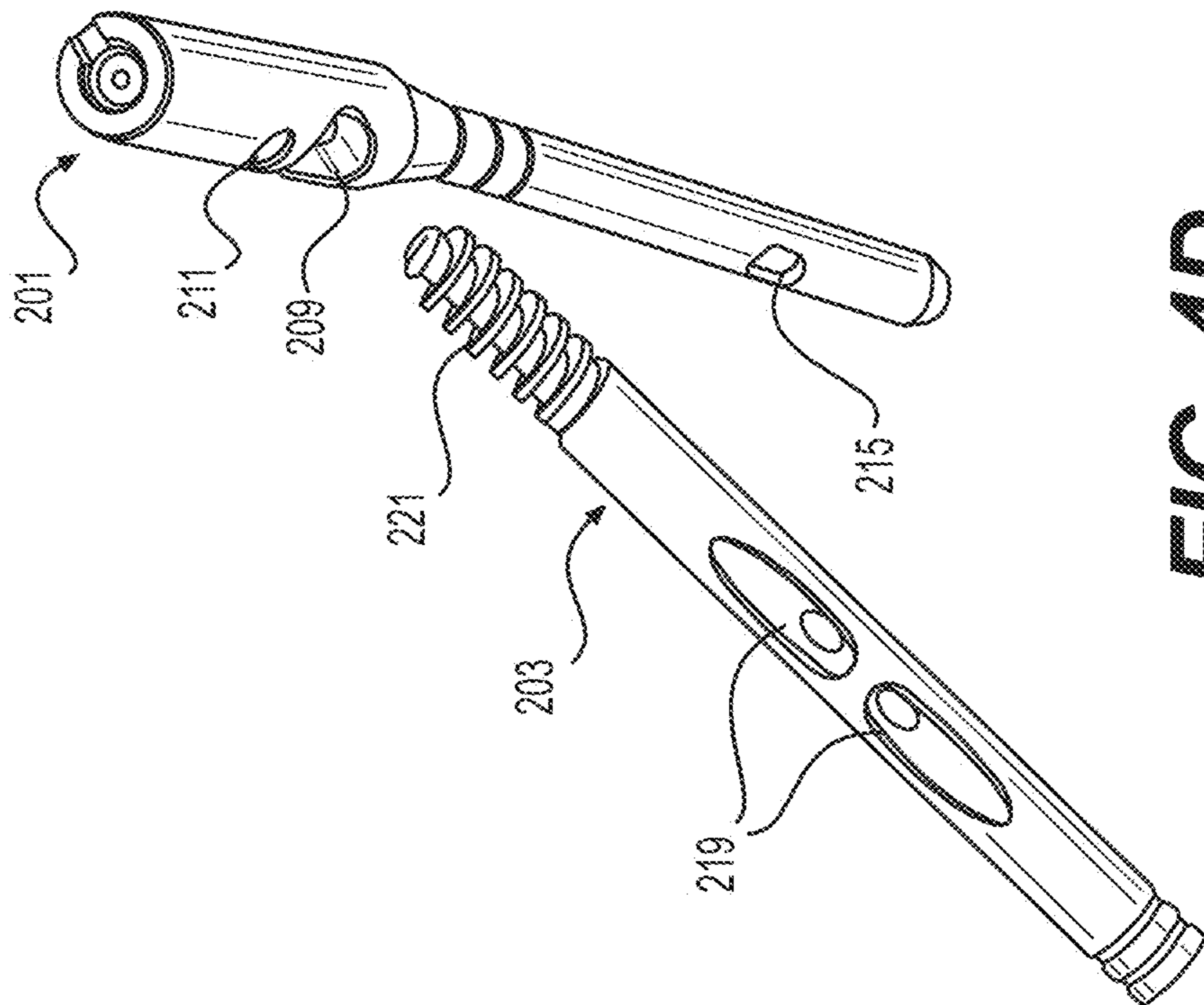


FIG. 4D

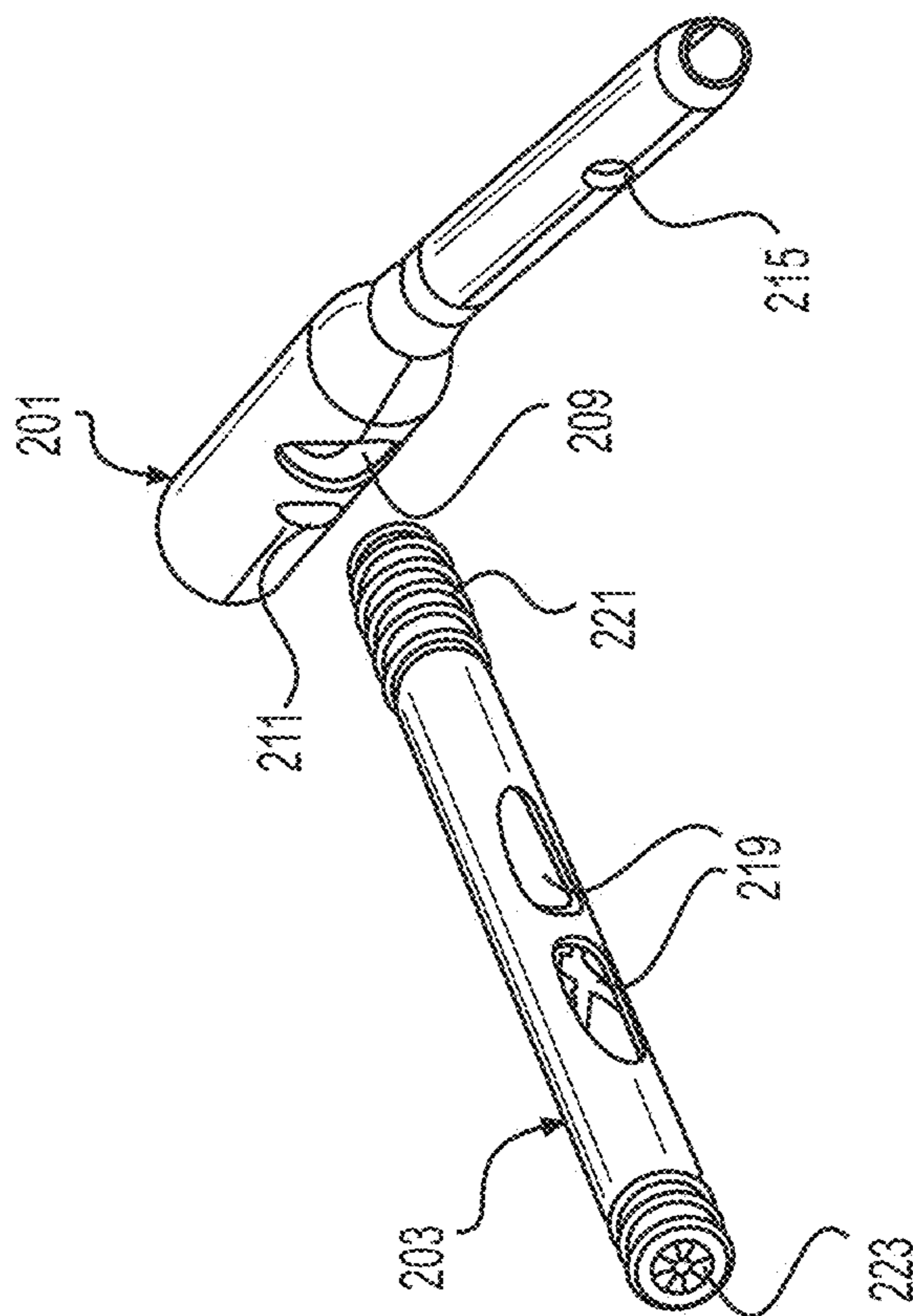


FIG. 4C

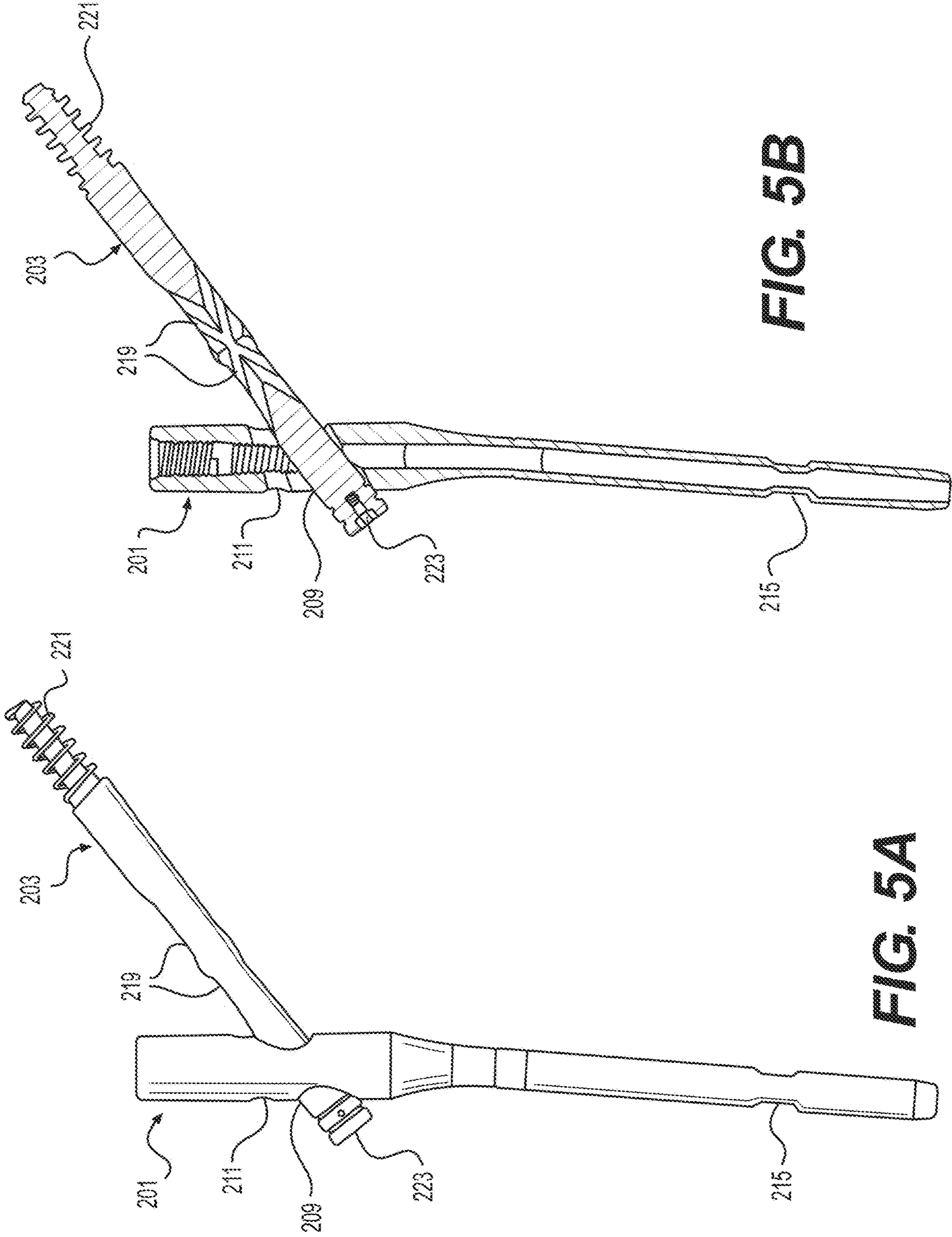


FIG. 5B

FIG. 5A

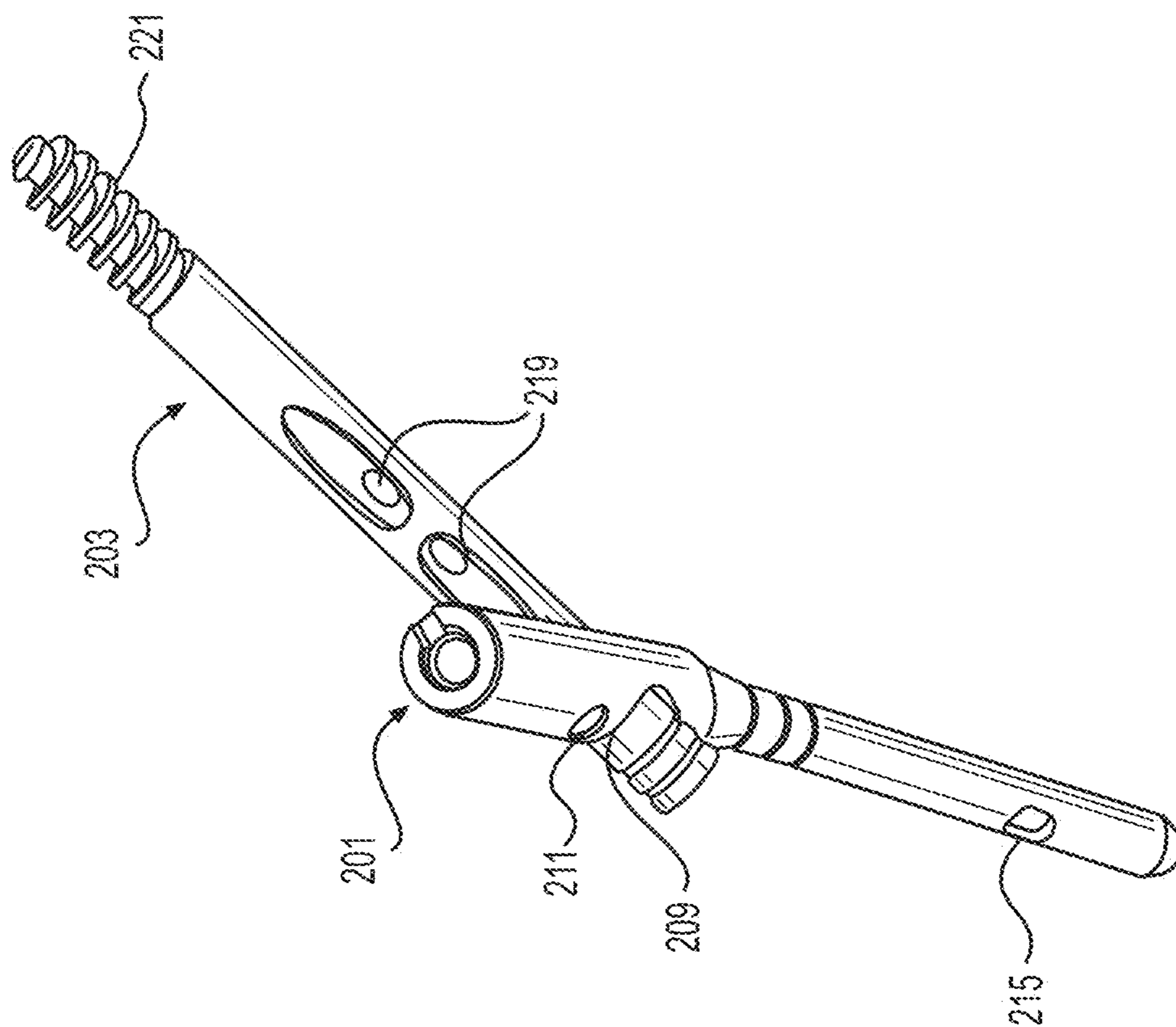


FIG. 5D

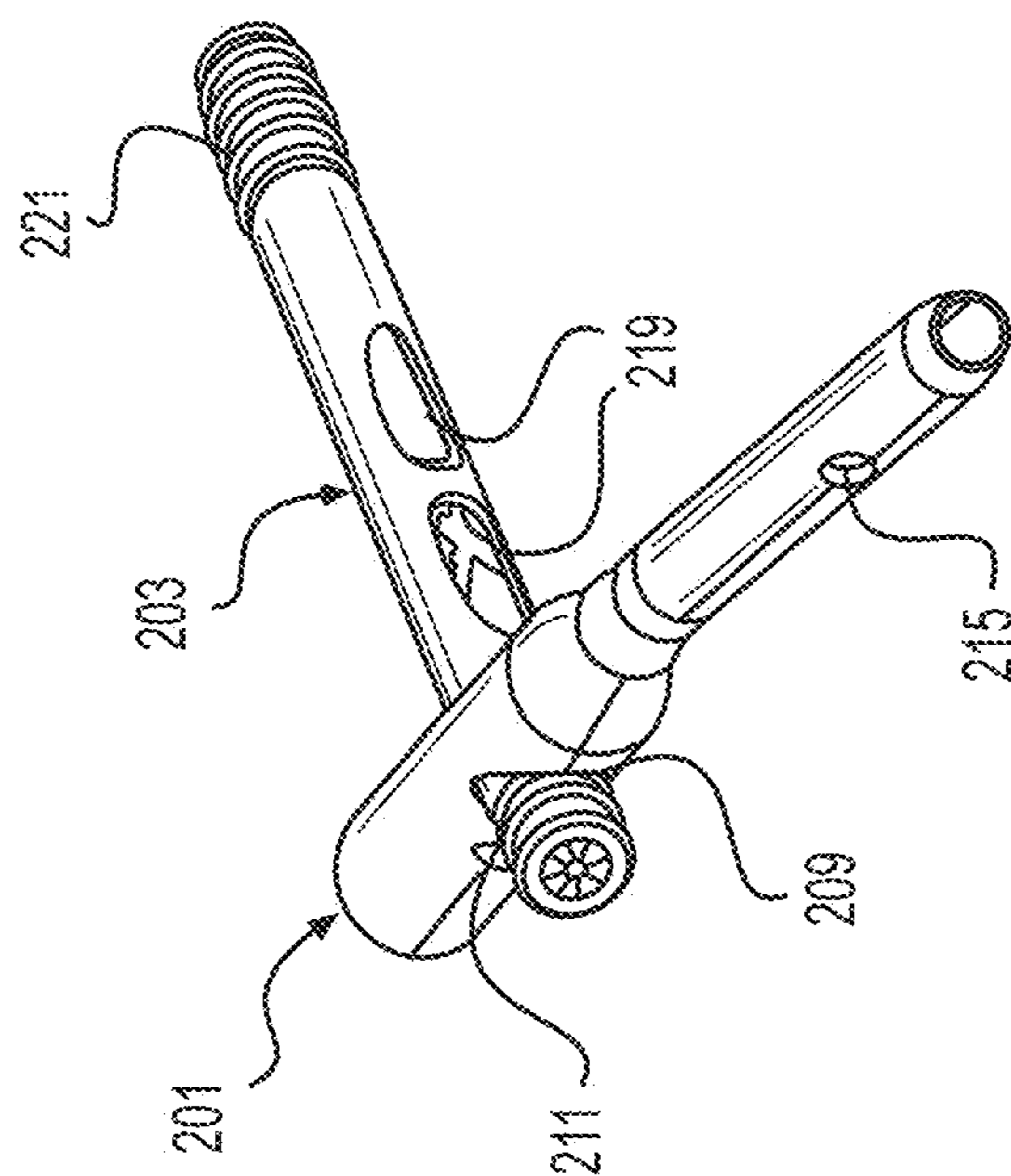


FIG. 5C

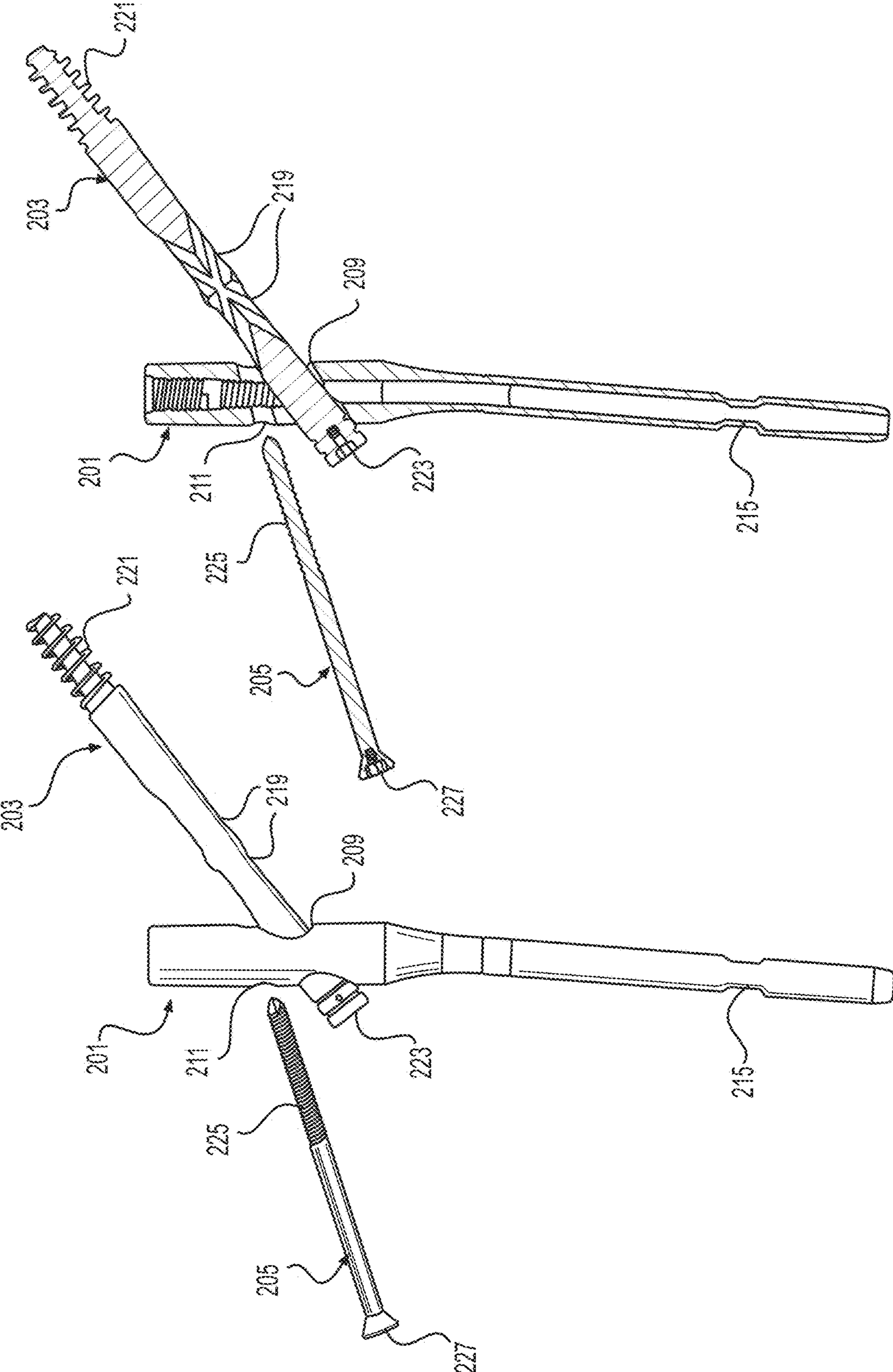


FIG. 6B

FIG. 6A

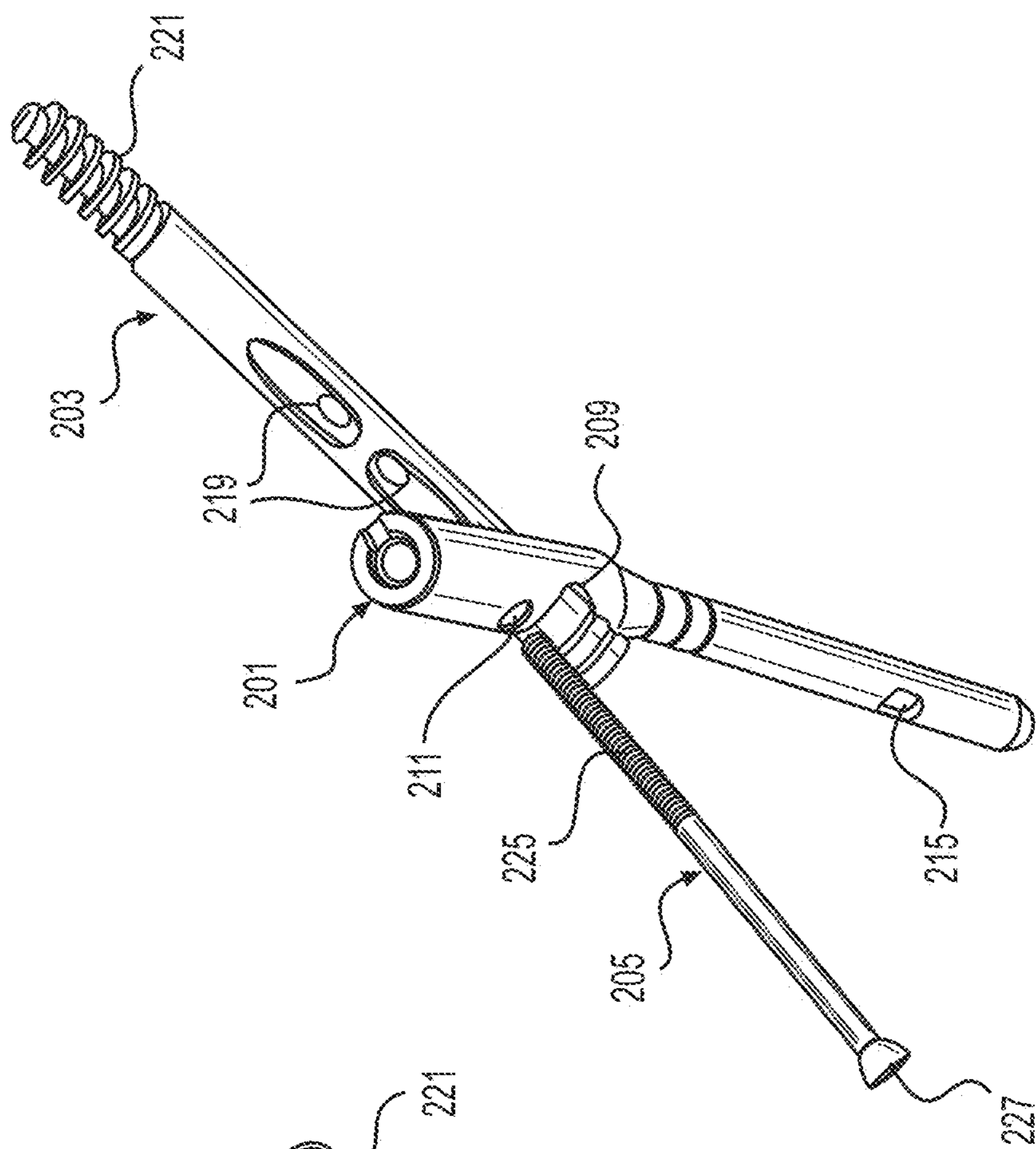


FIG. 6C

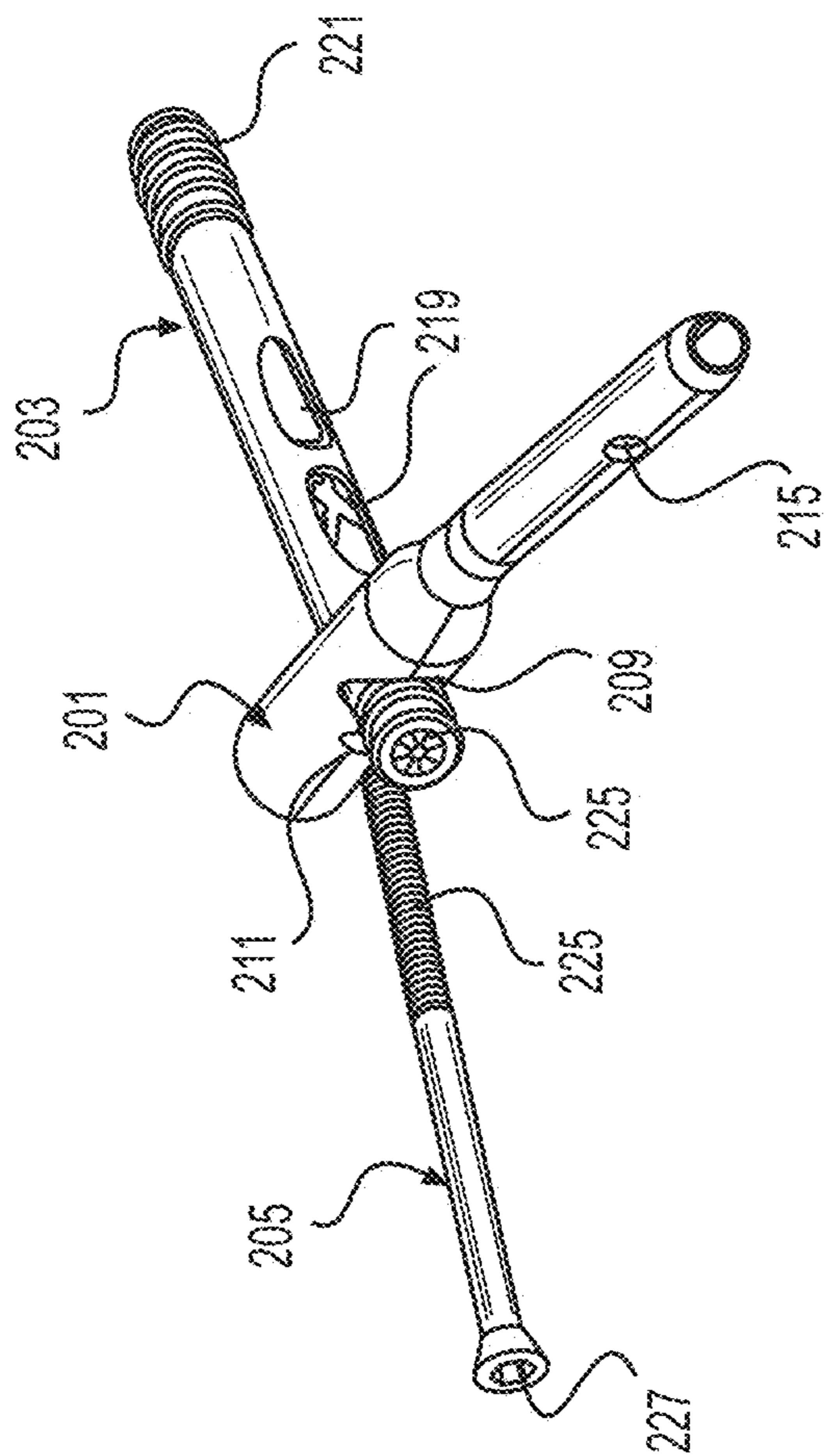


FIG. 6D

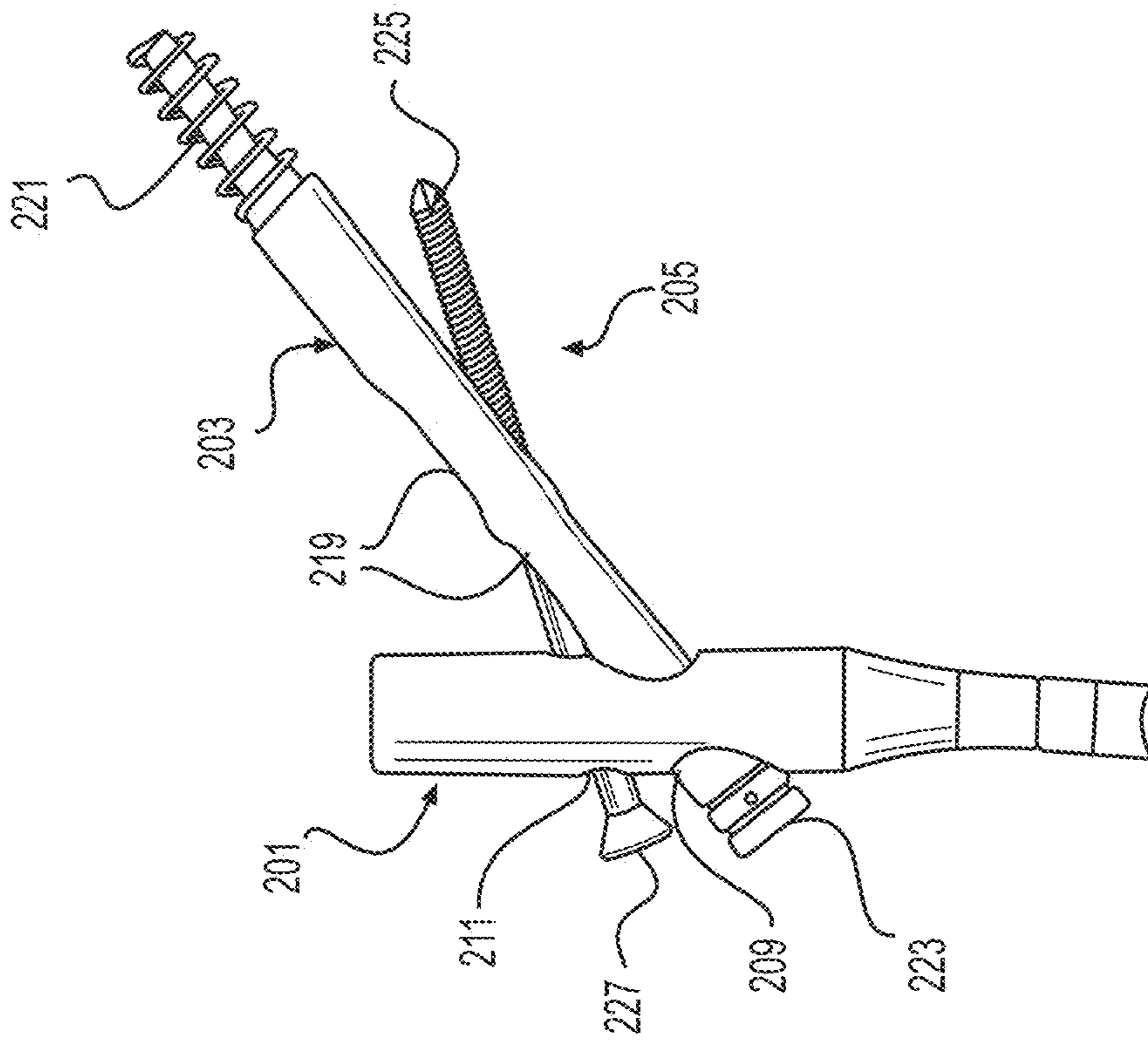


FIG. 7A

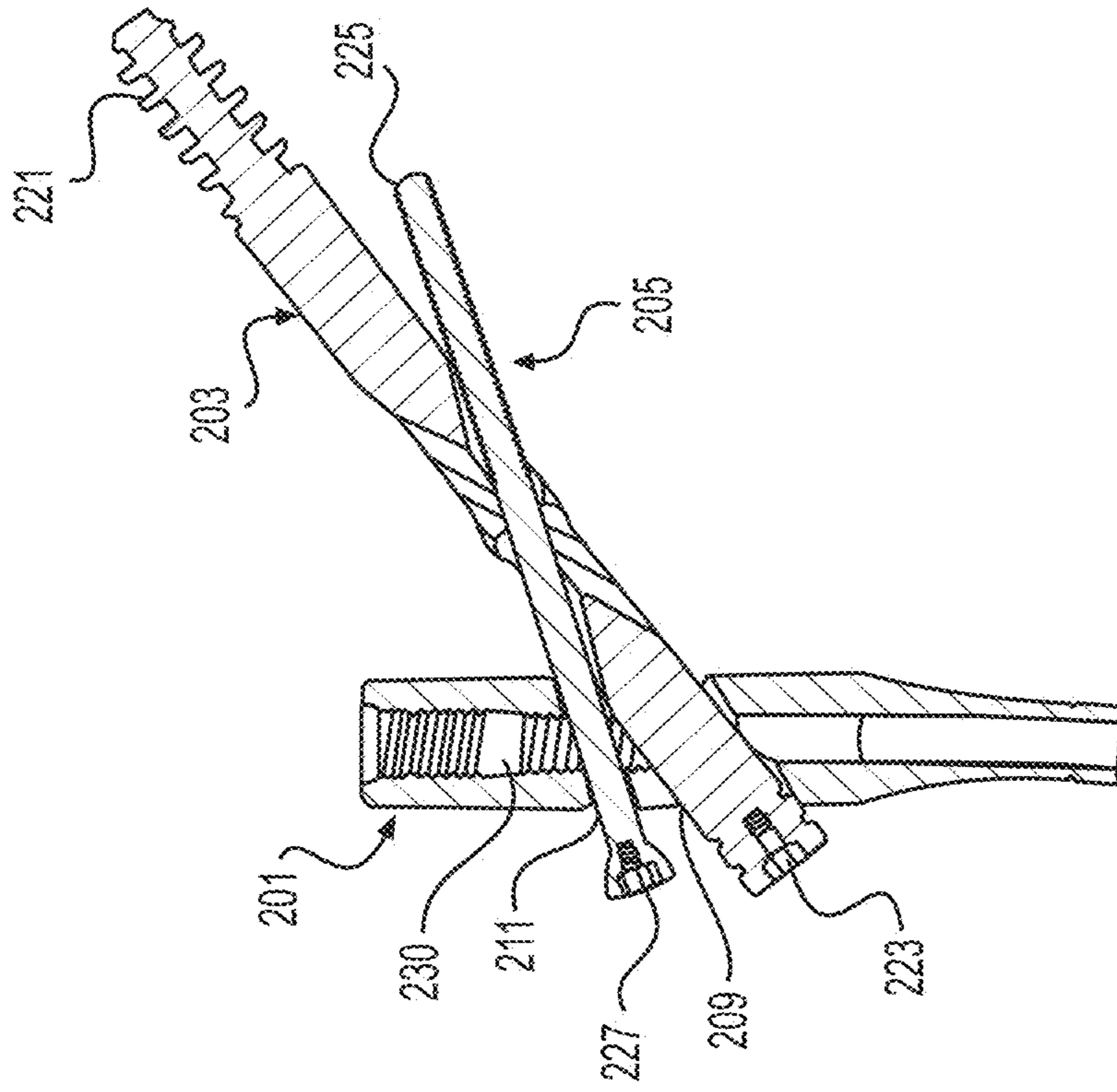


FIG. 7B

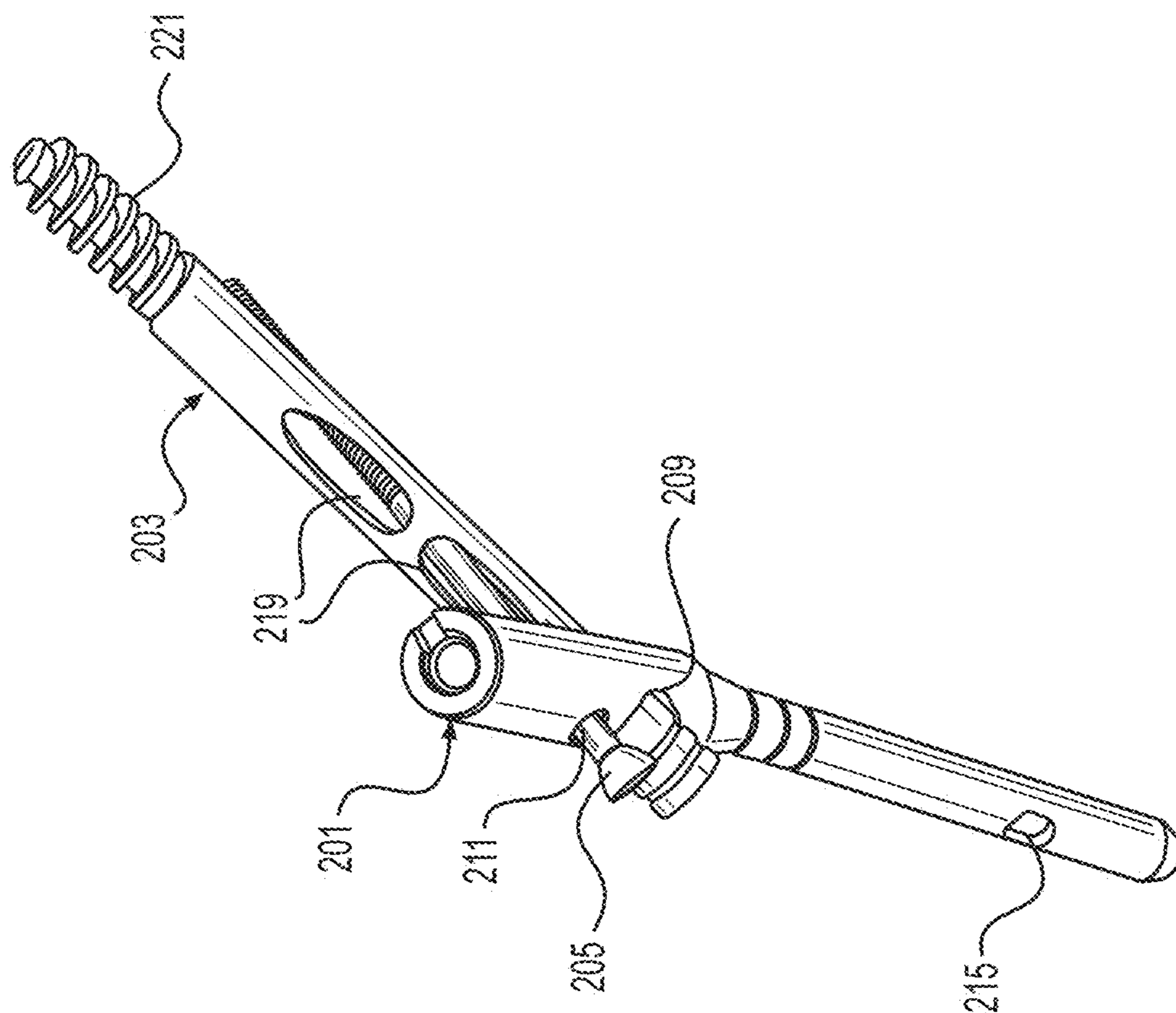


FIG. 7D

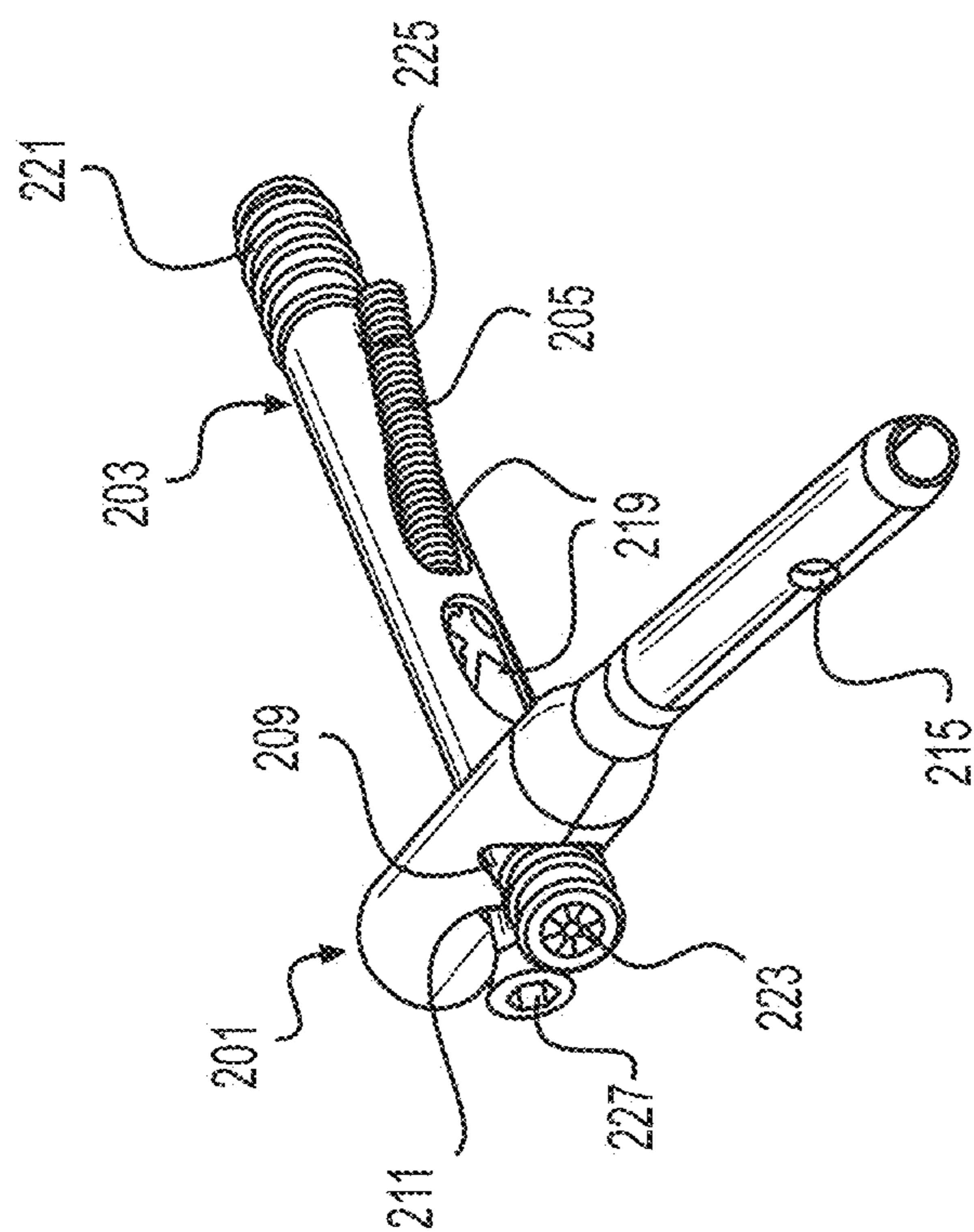


FIG. 7C

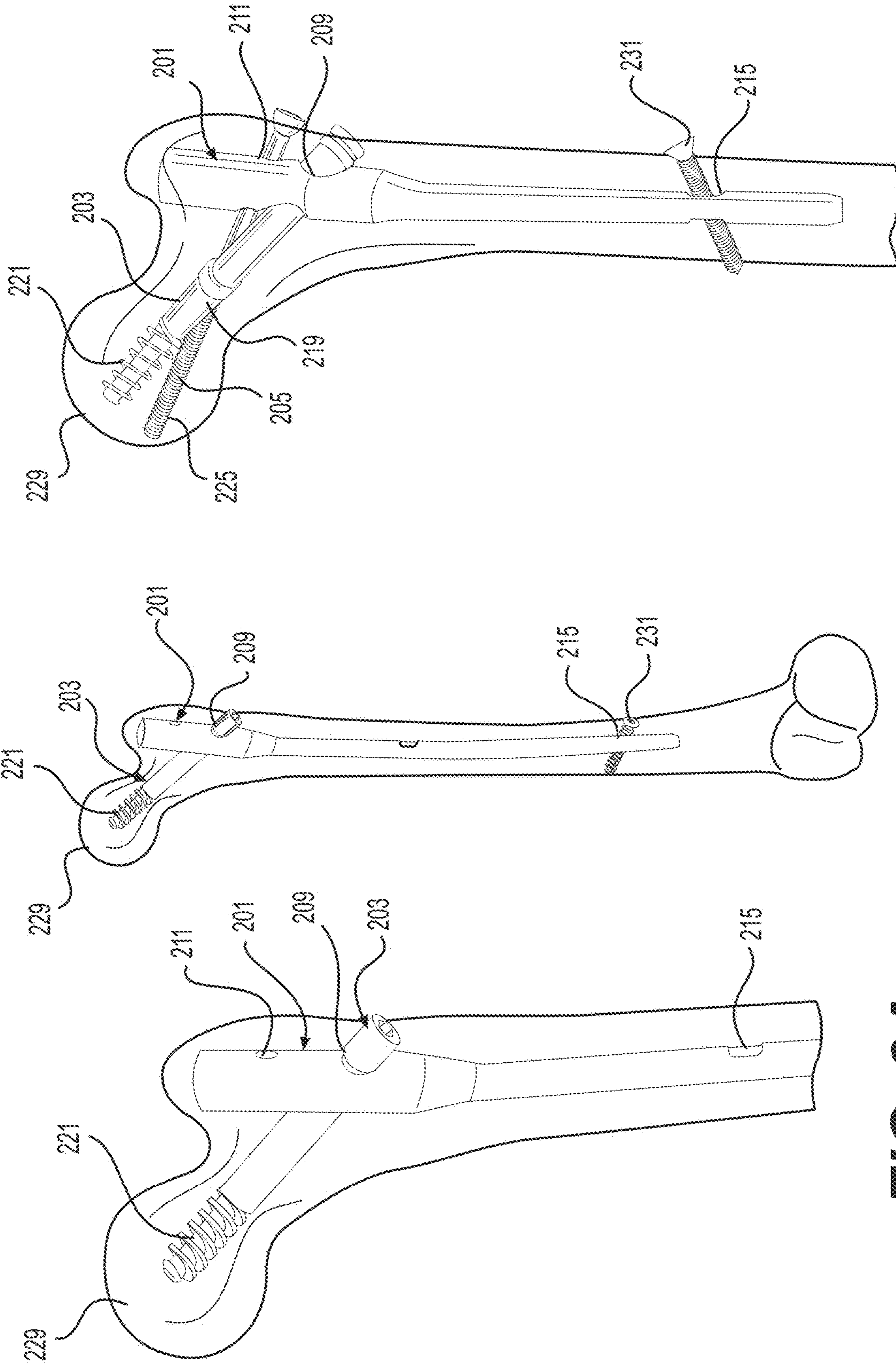
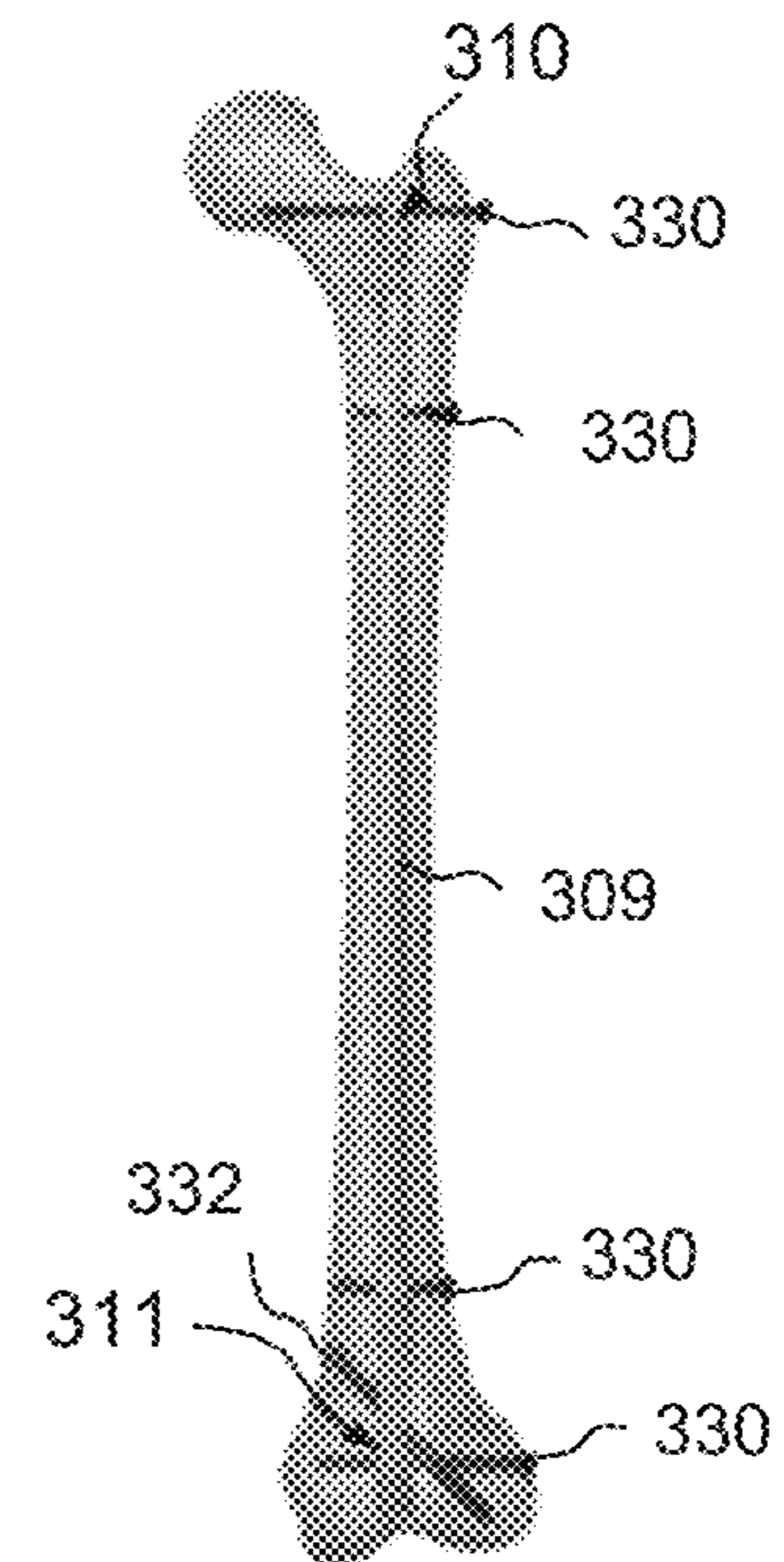
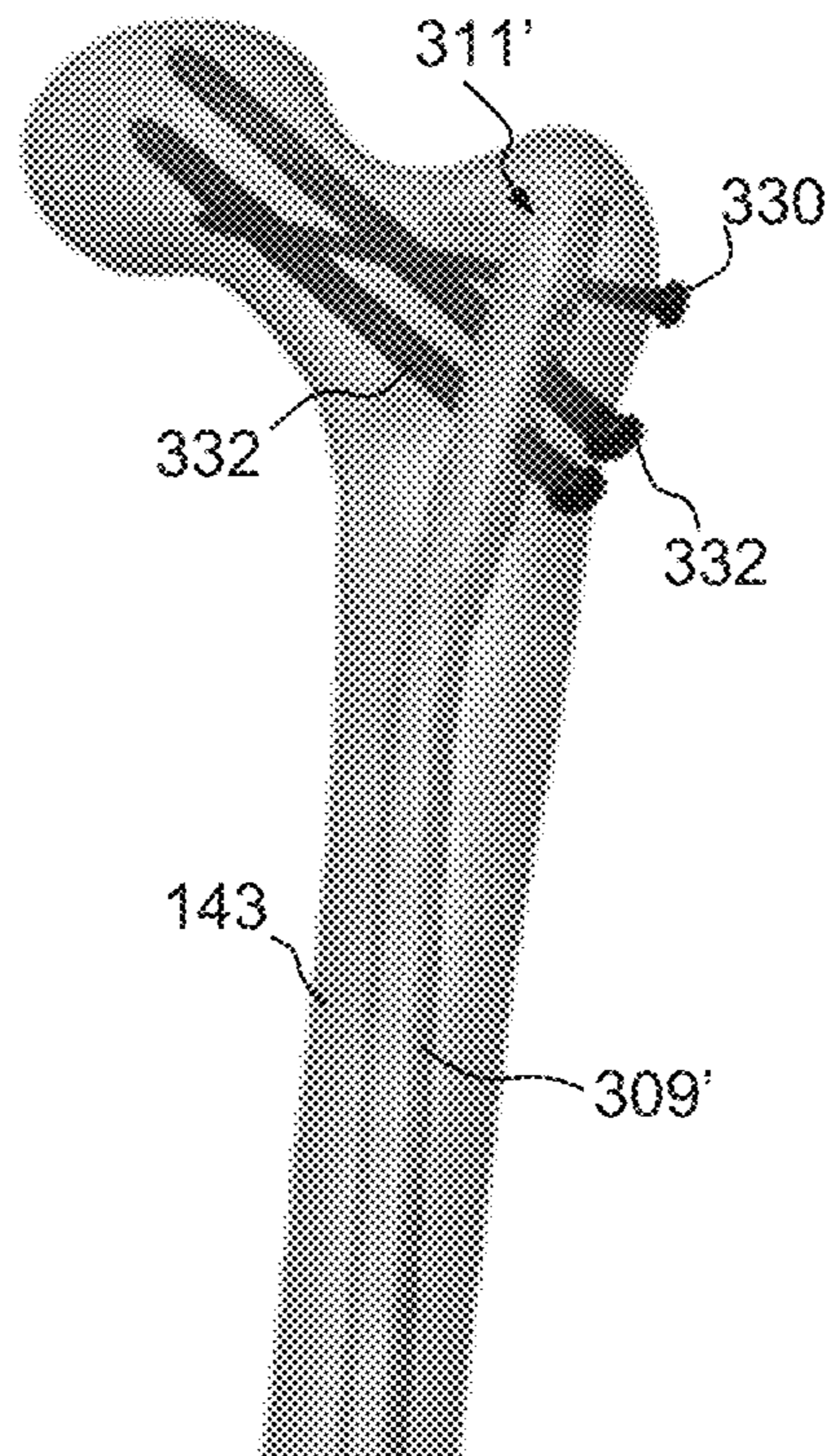
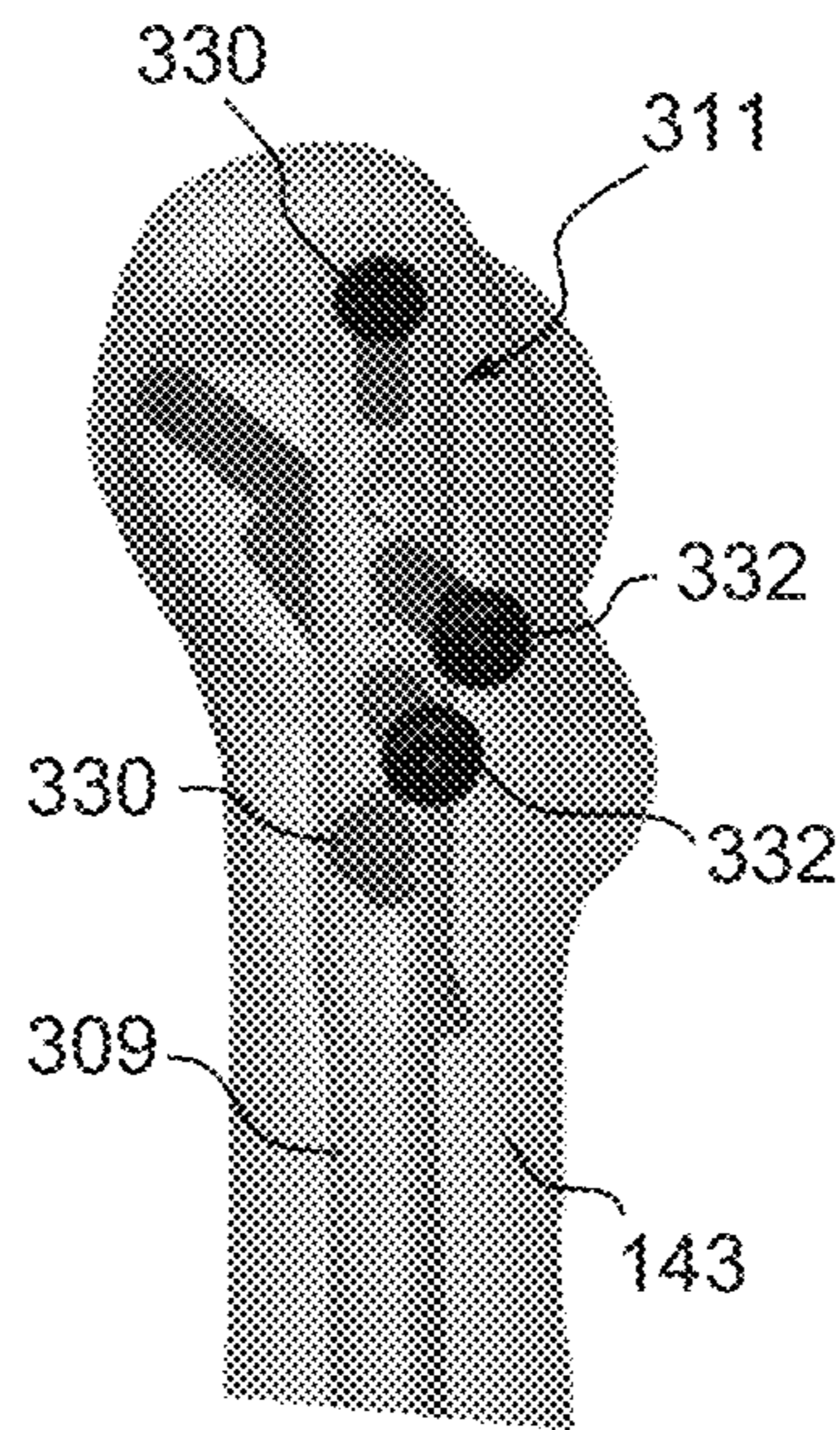
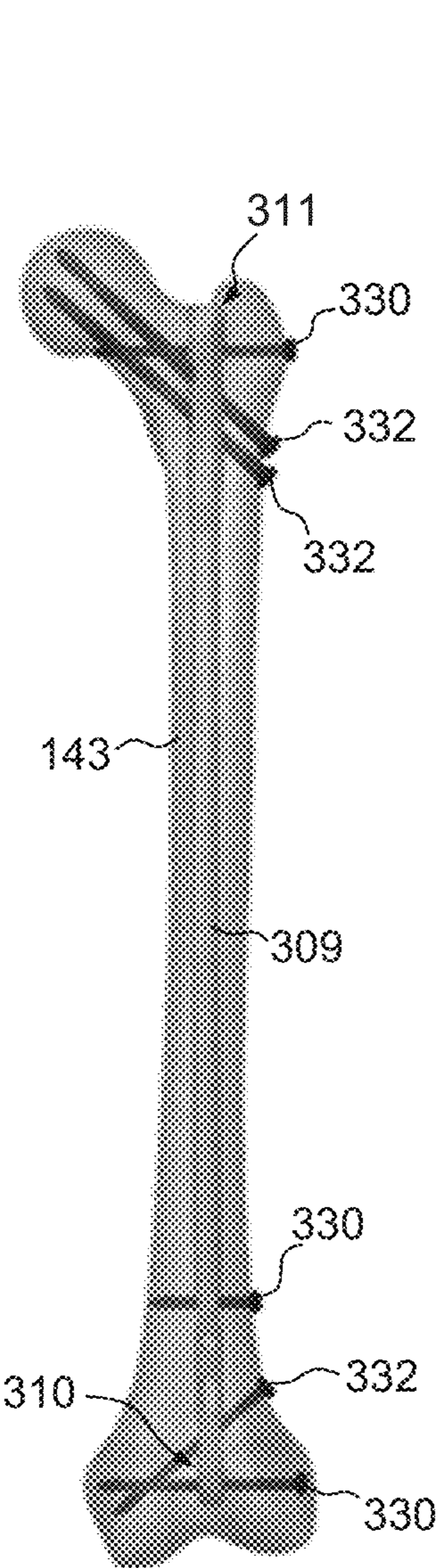
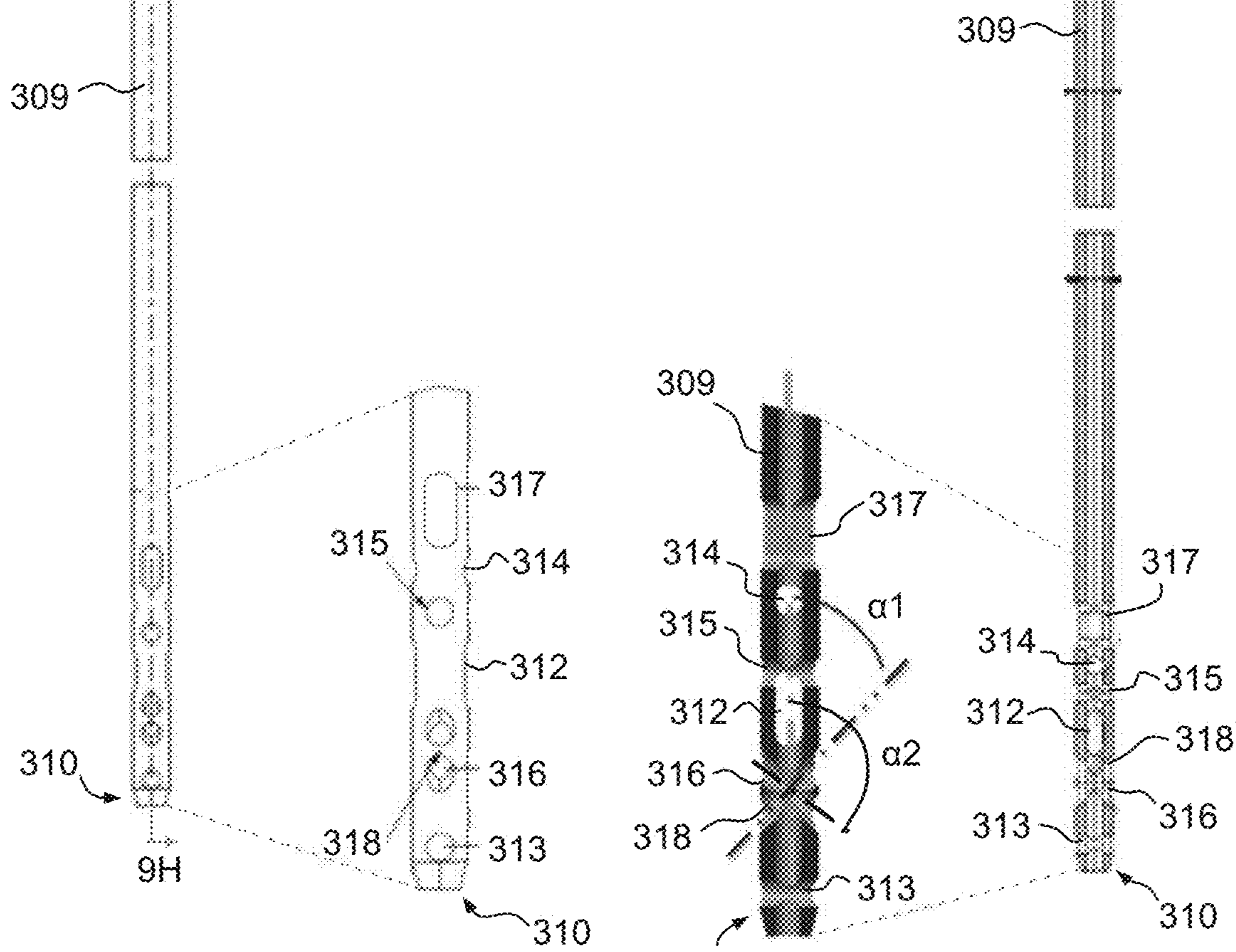
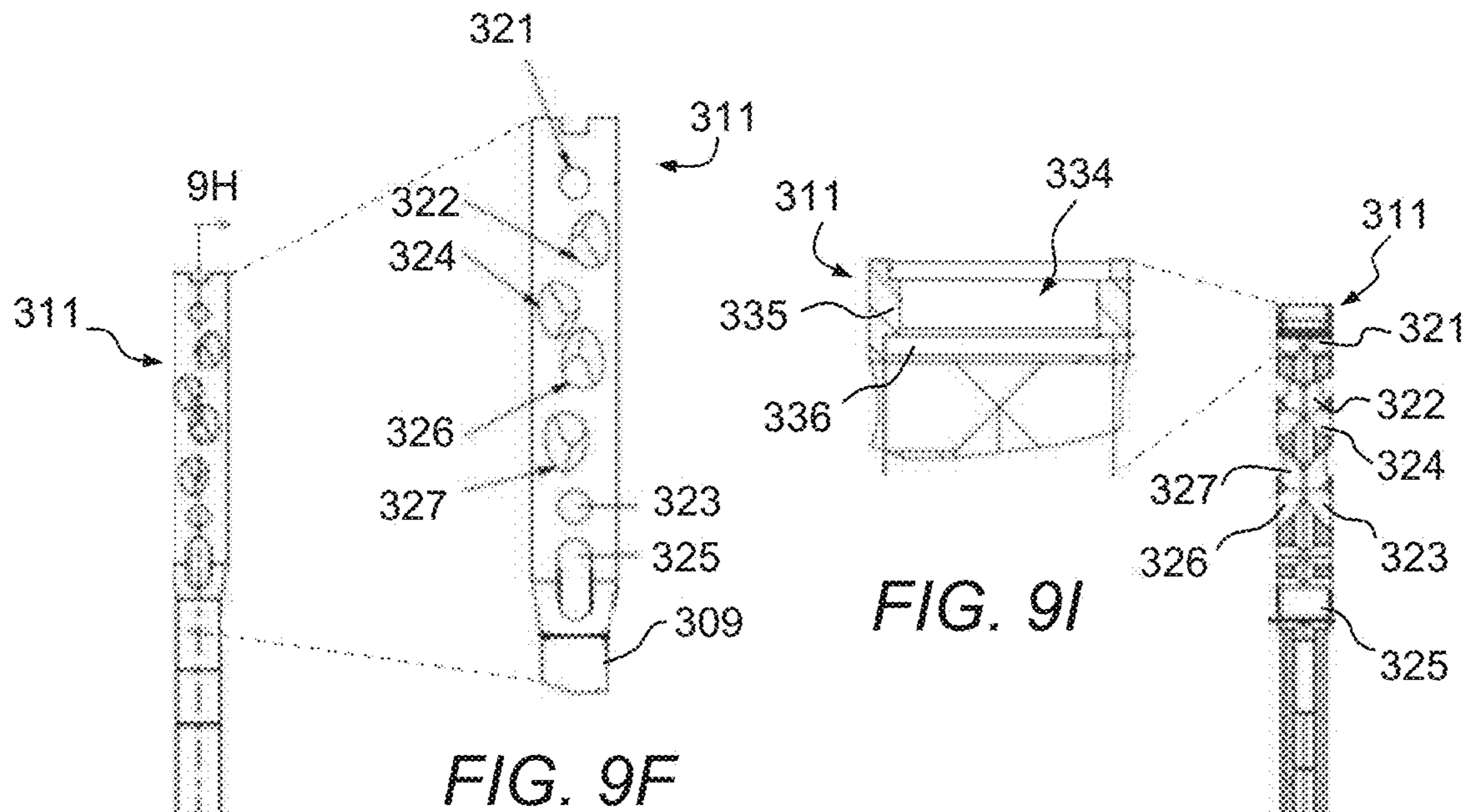


FIG. 8A

FIG. 8B

FIG. 8C





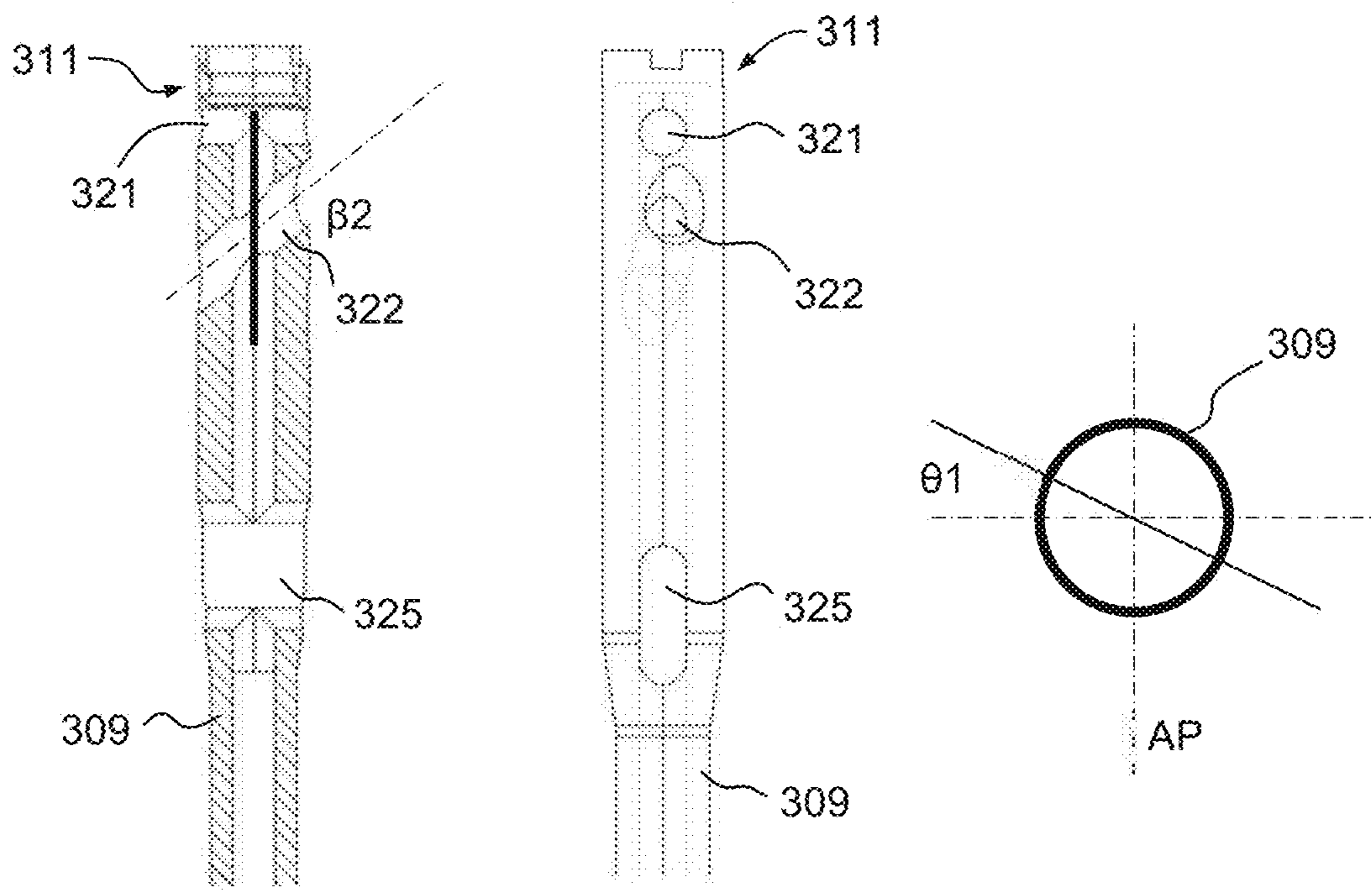


FIG. 9K

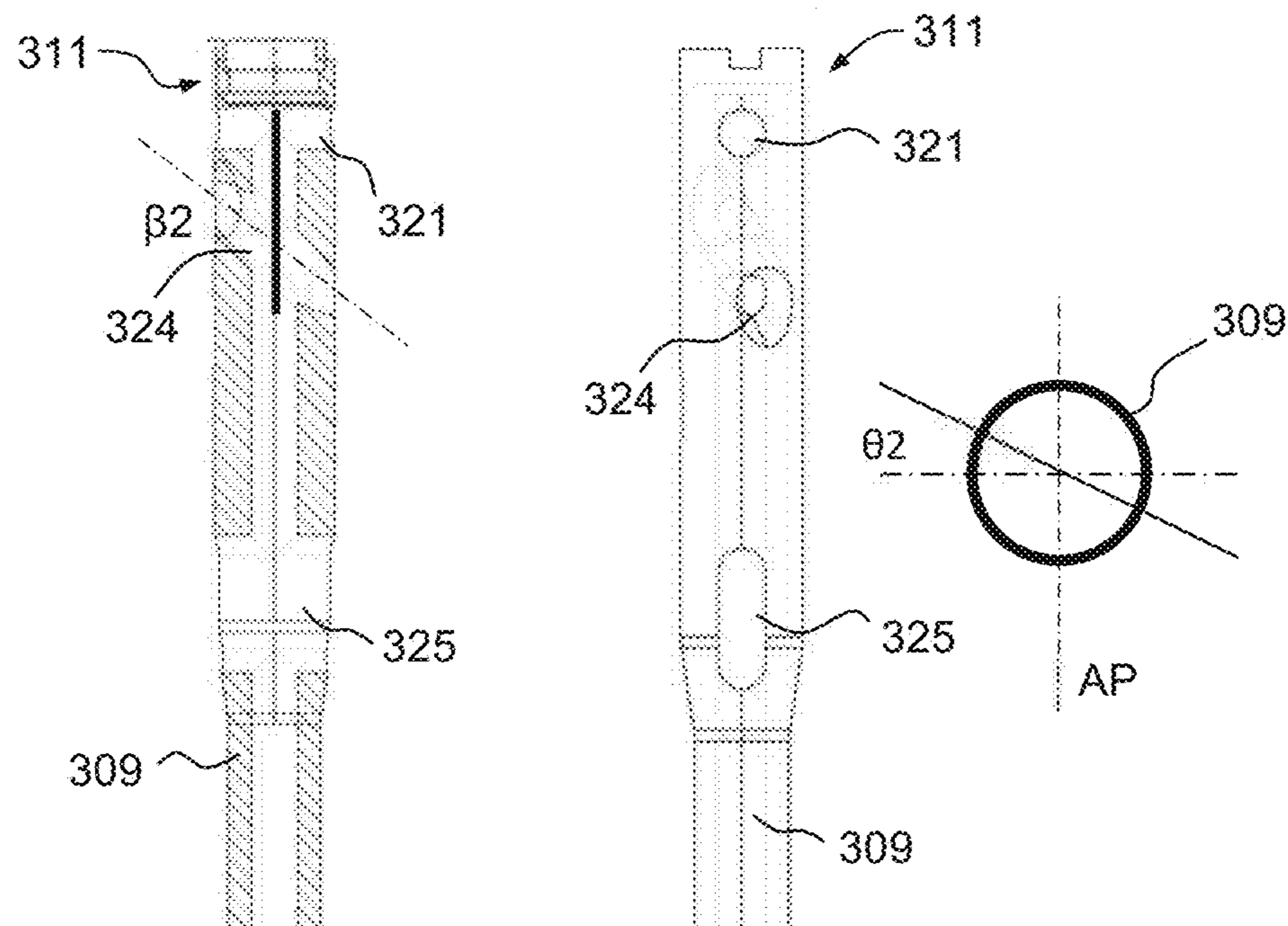


FIG. 9L

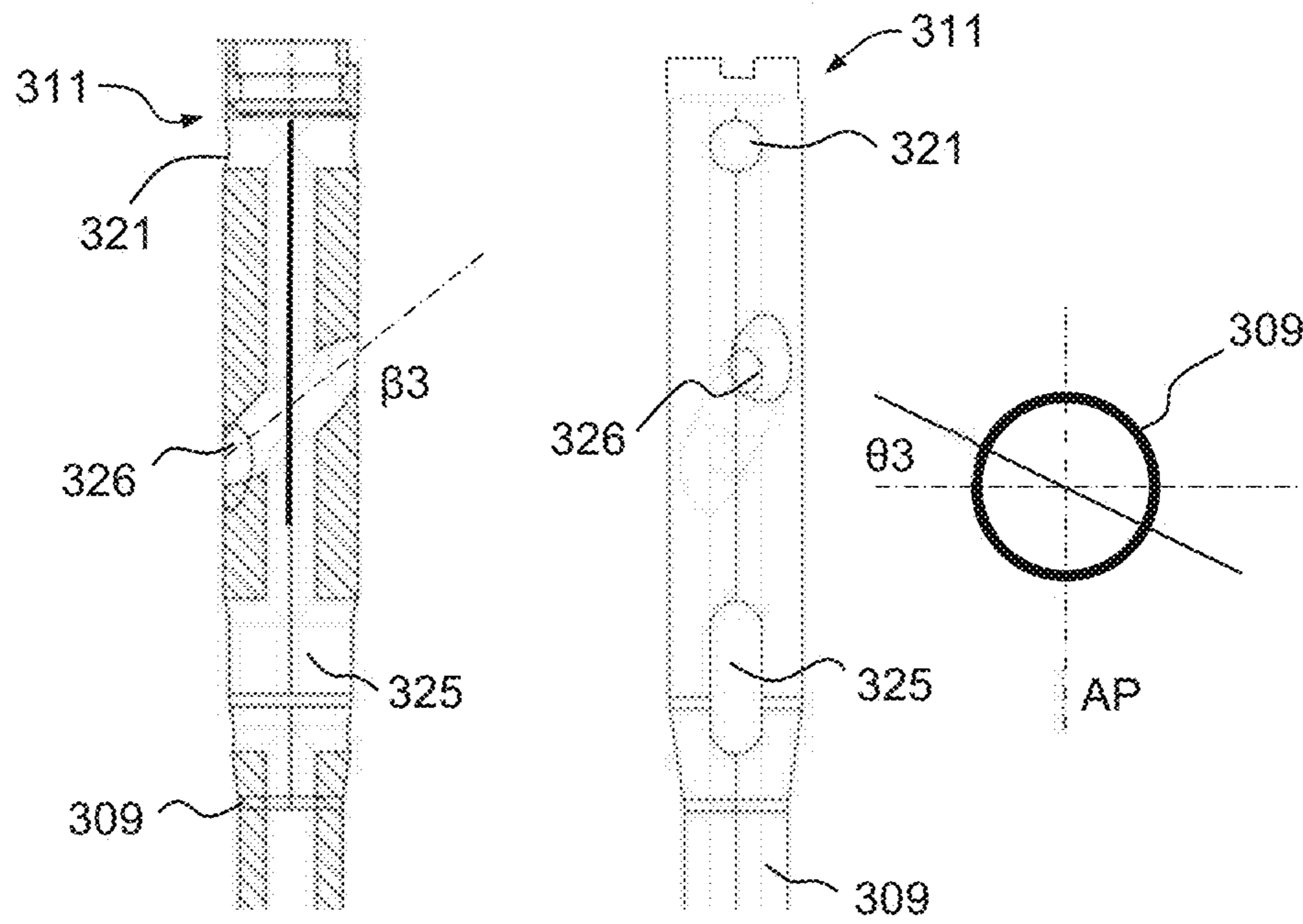


FIG. 9M

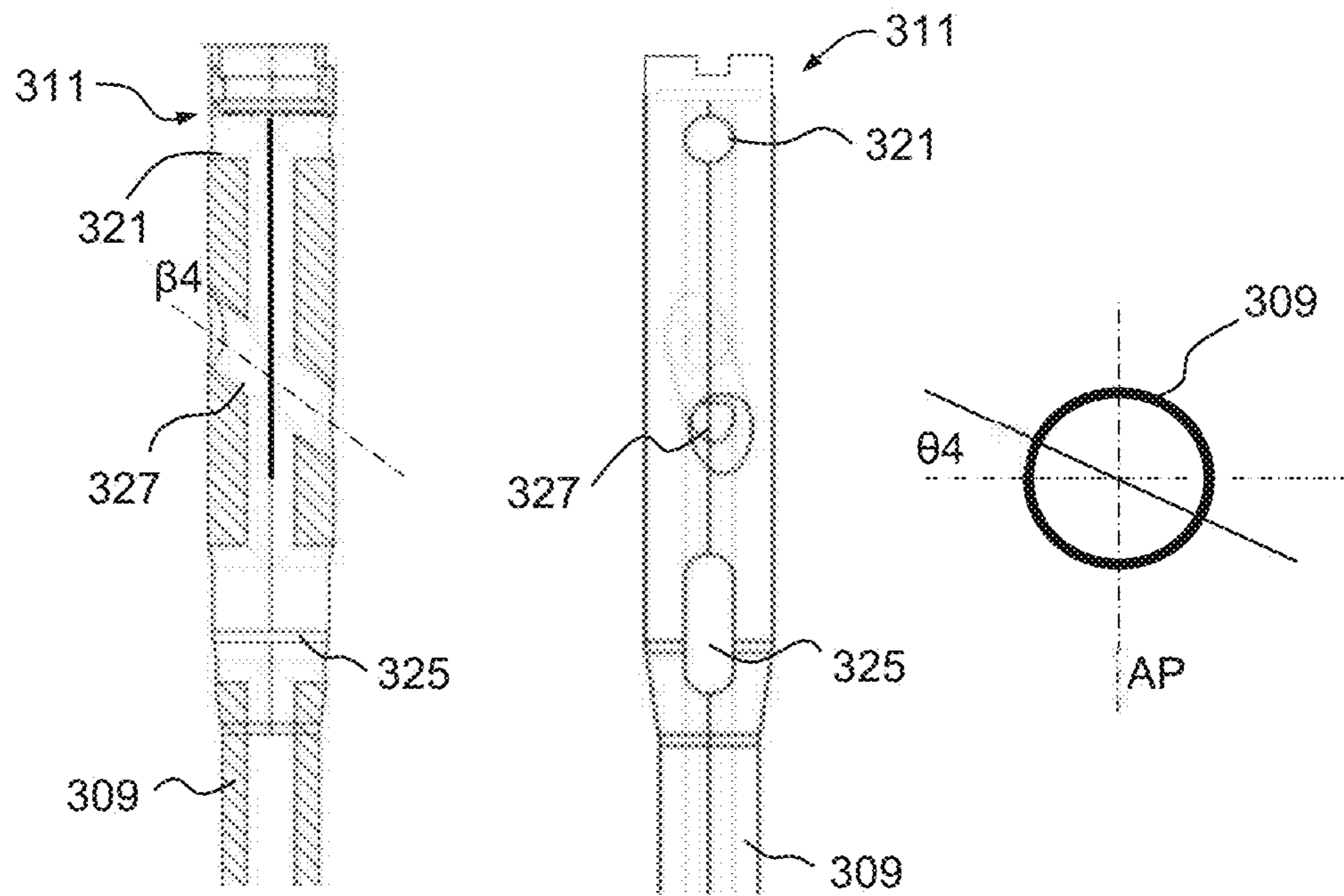


FIG. 9N

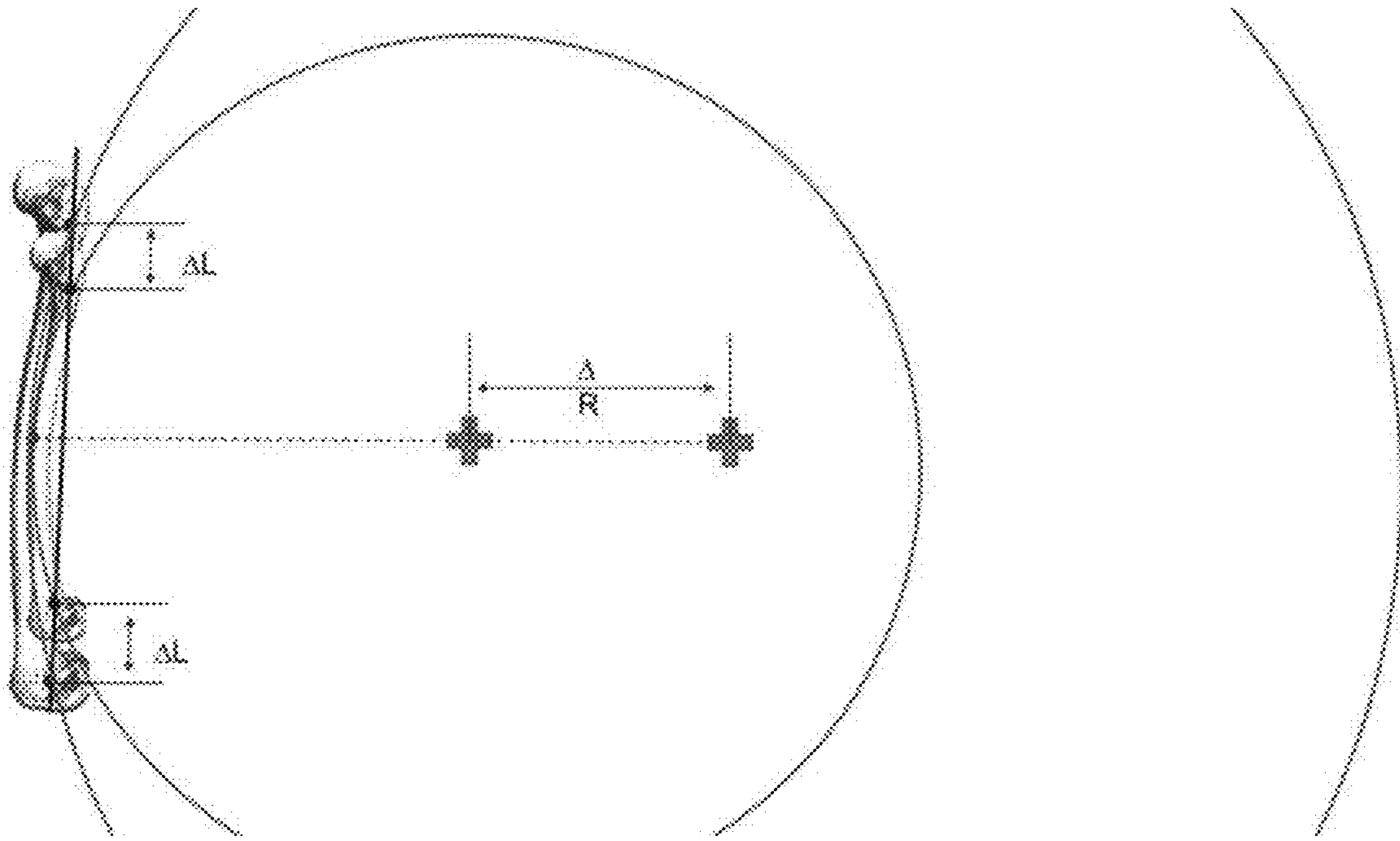


FIG. 10A

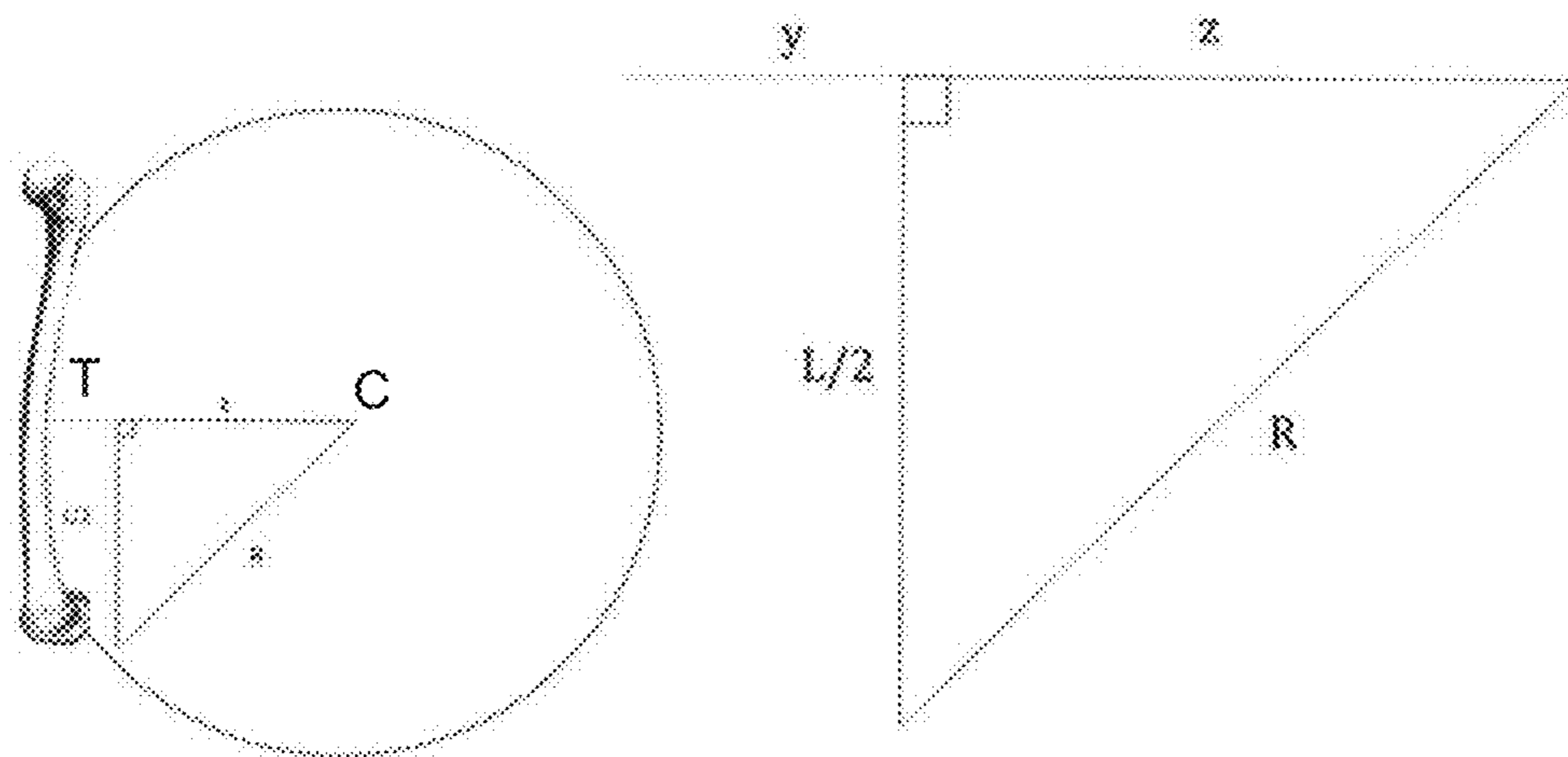


FIG. 10B

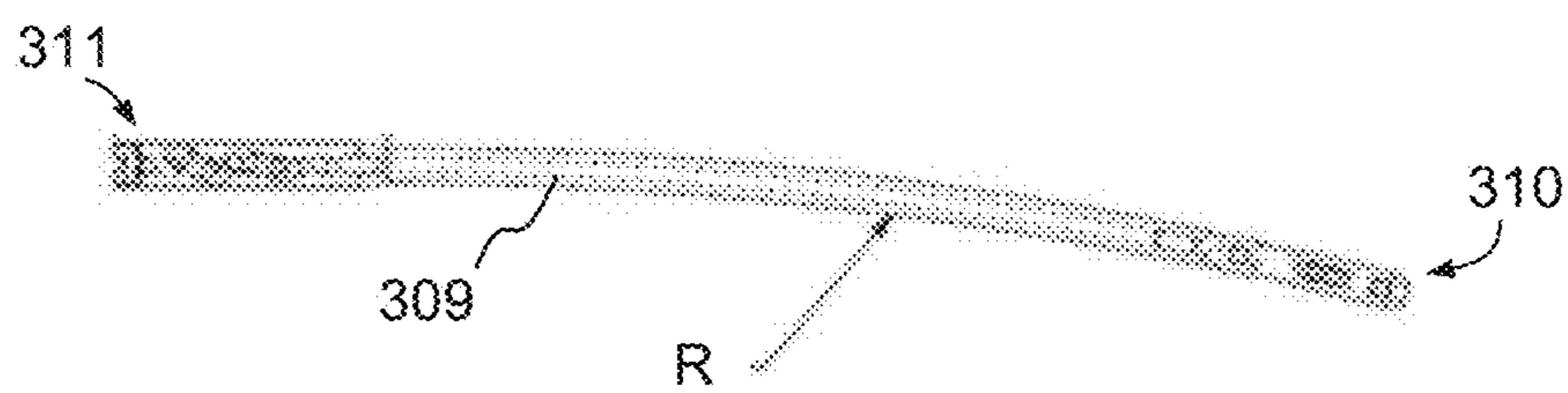


FIG. 10C

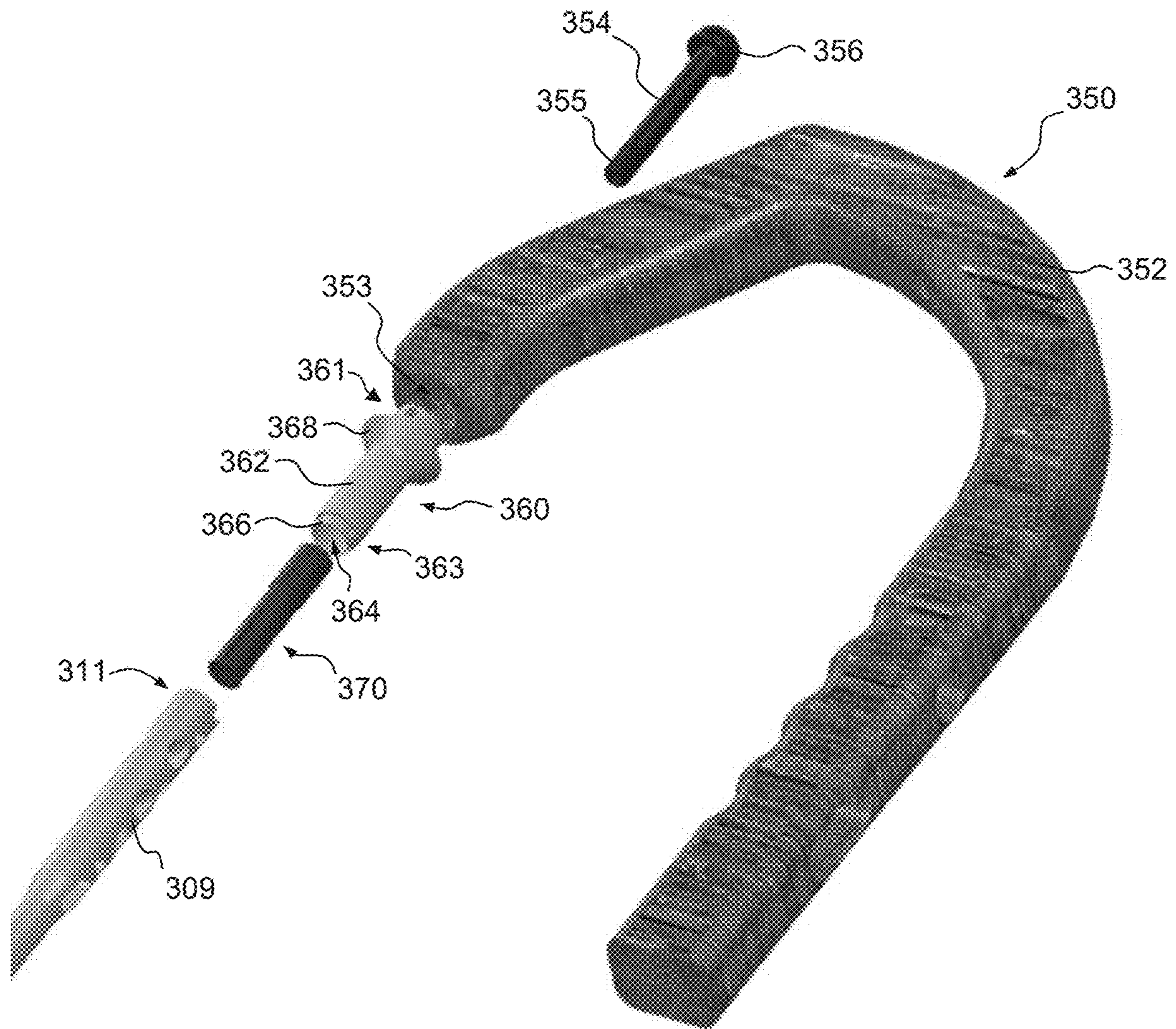


FIG. 11A

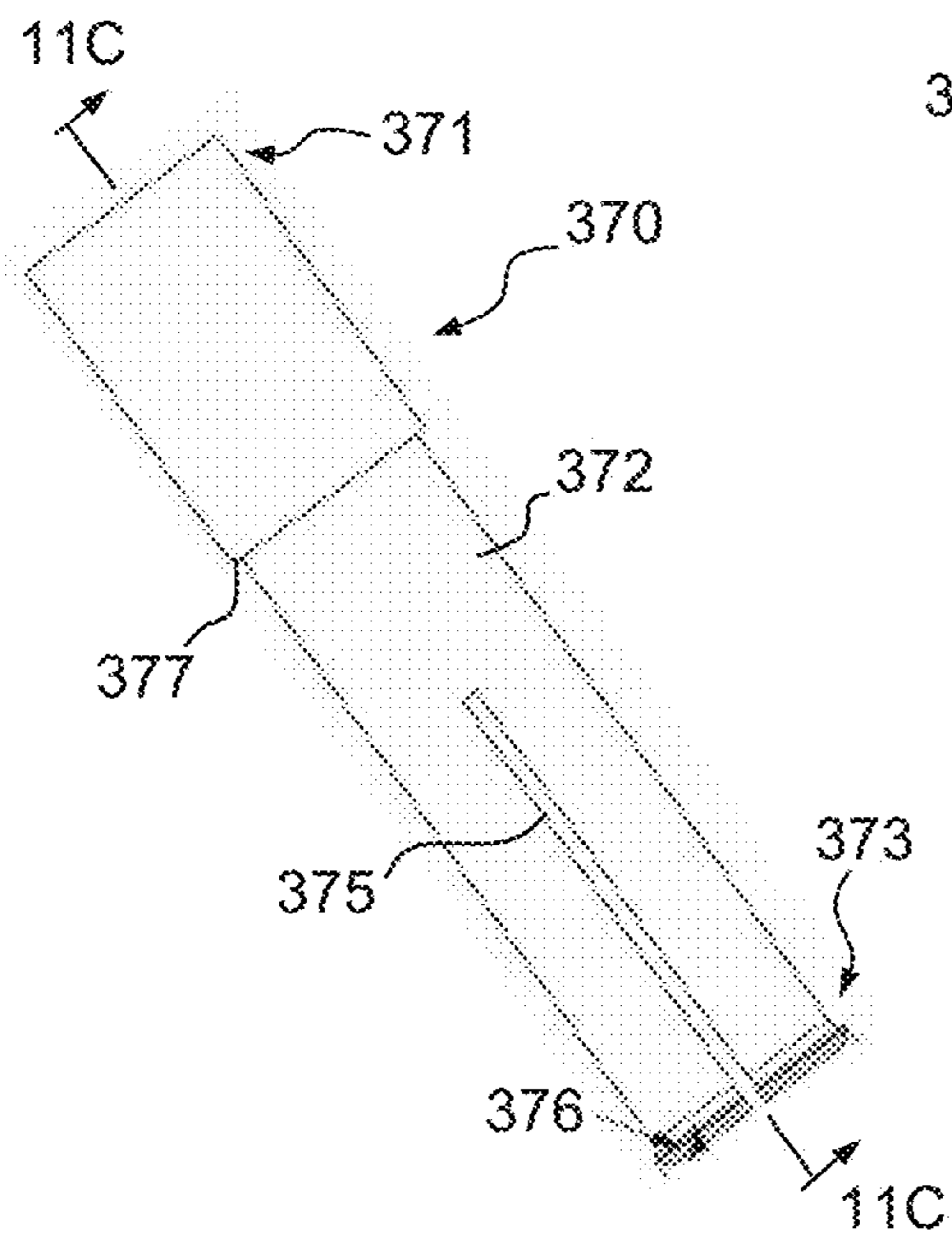


FIG. 11B

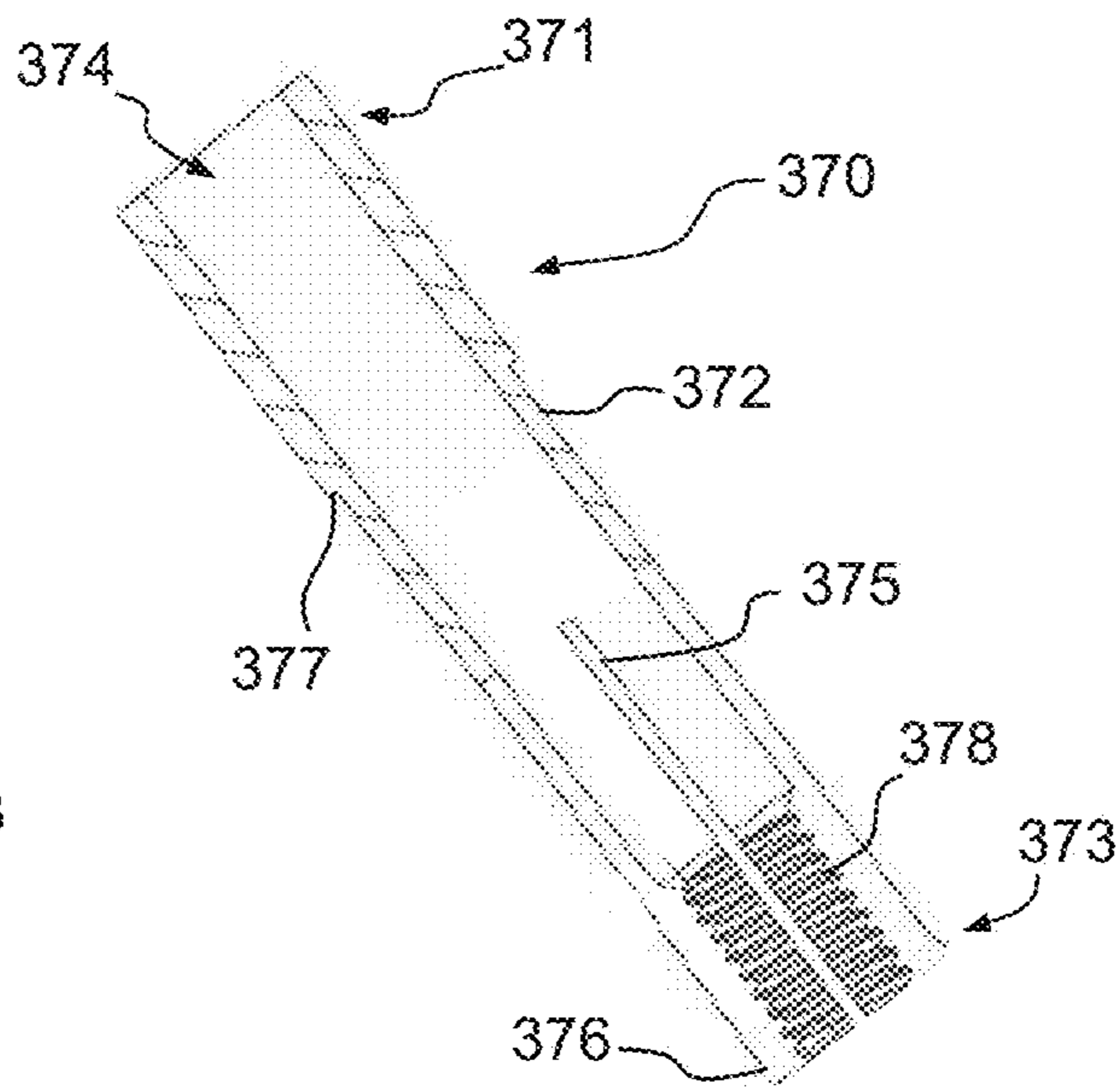


FIG. 11C

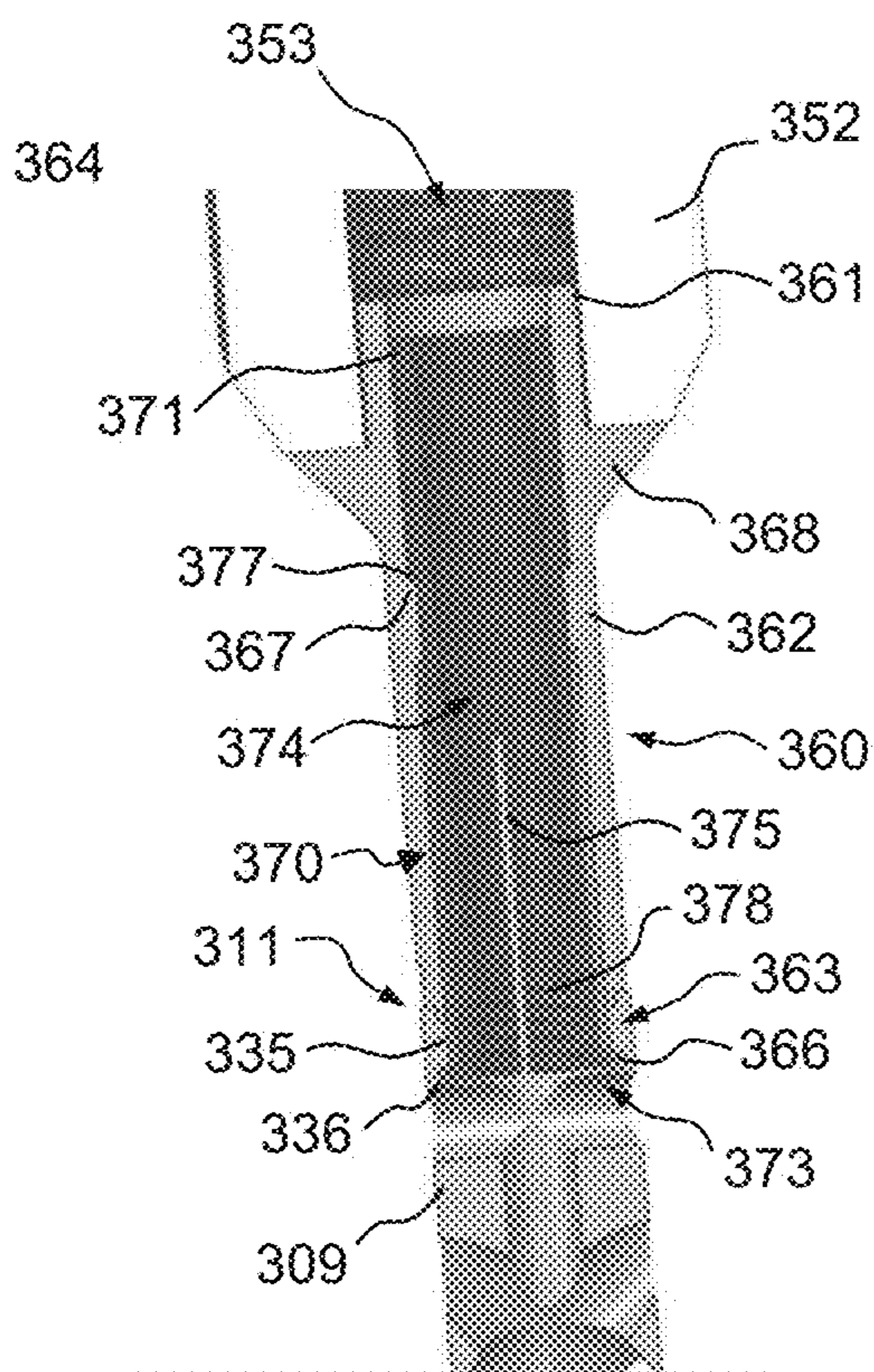


FIG. 11D

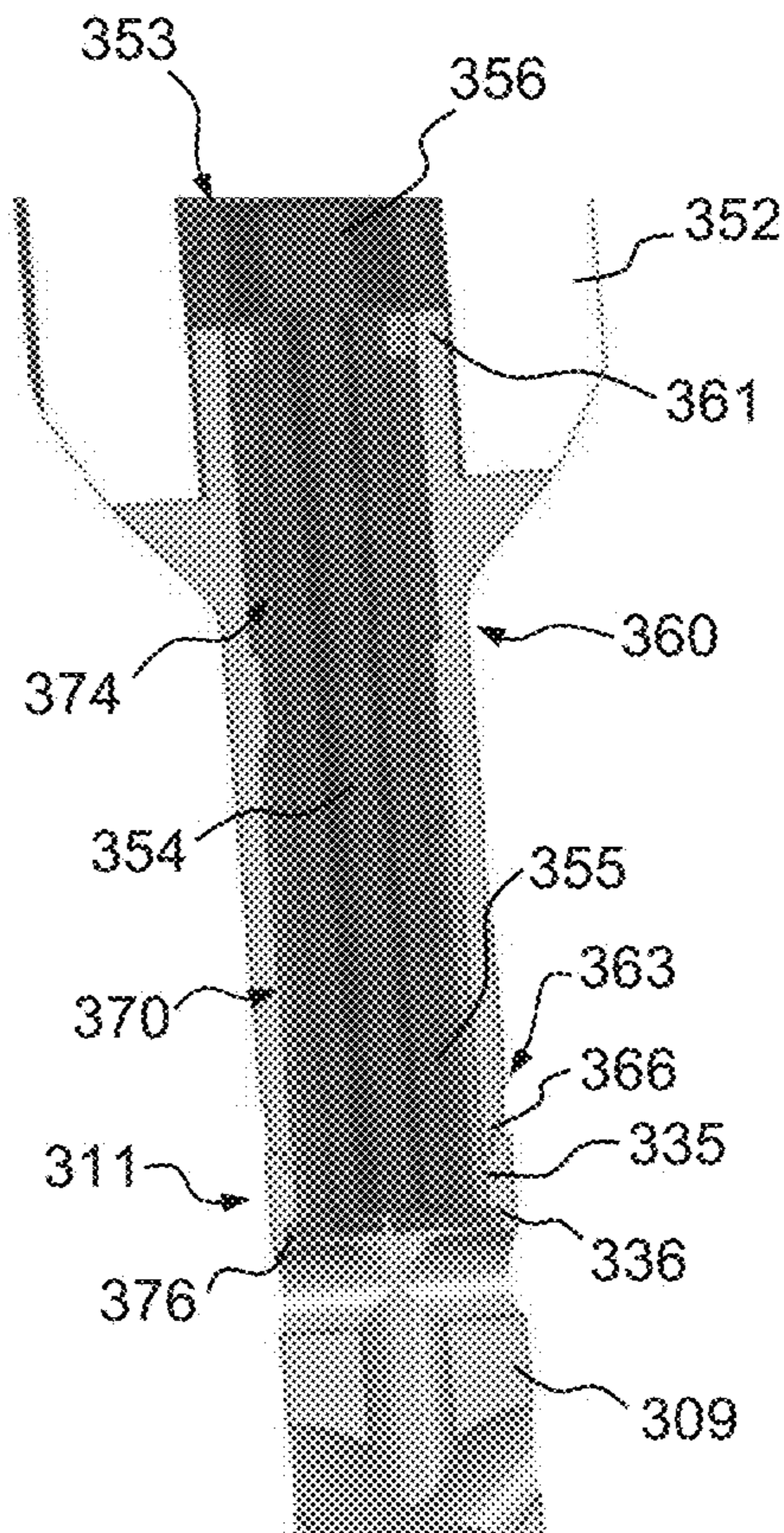


FIG. 11E

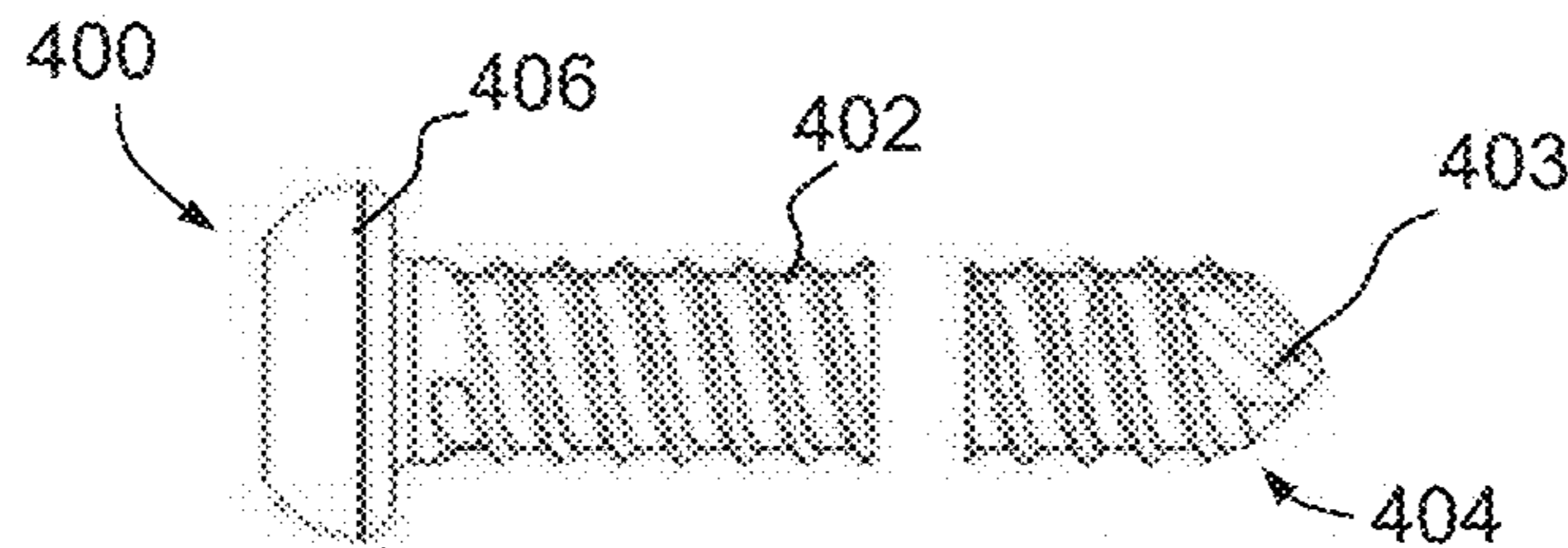


FIG. 12A

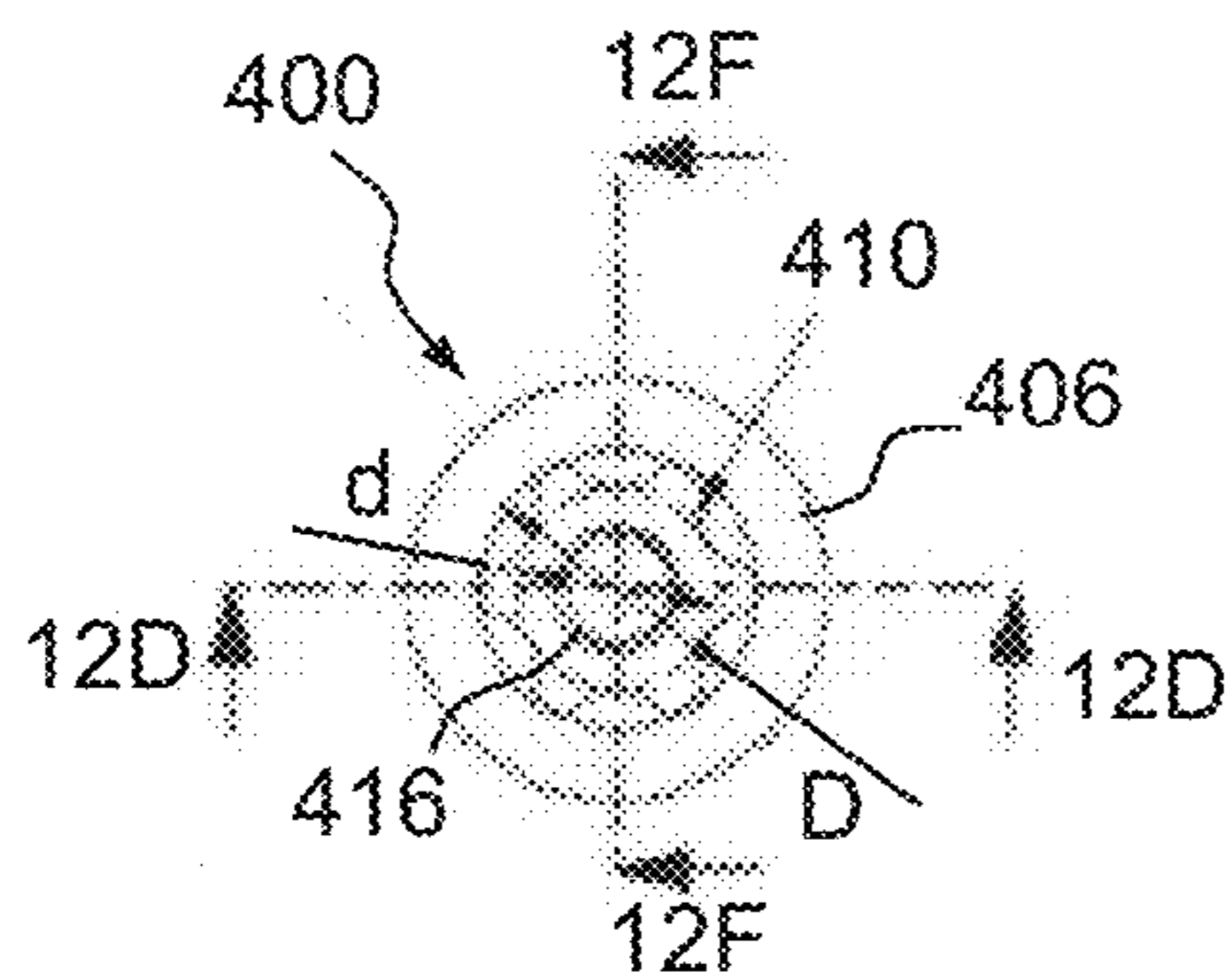


FIG. 12B

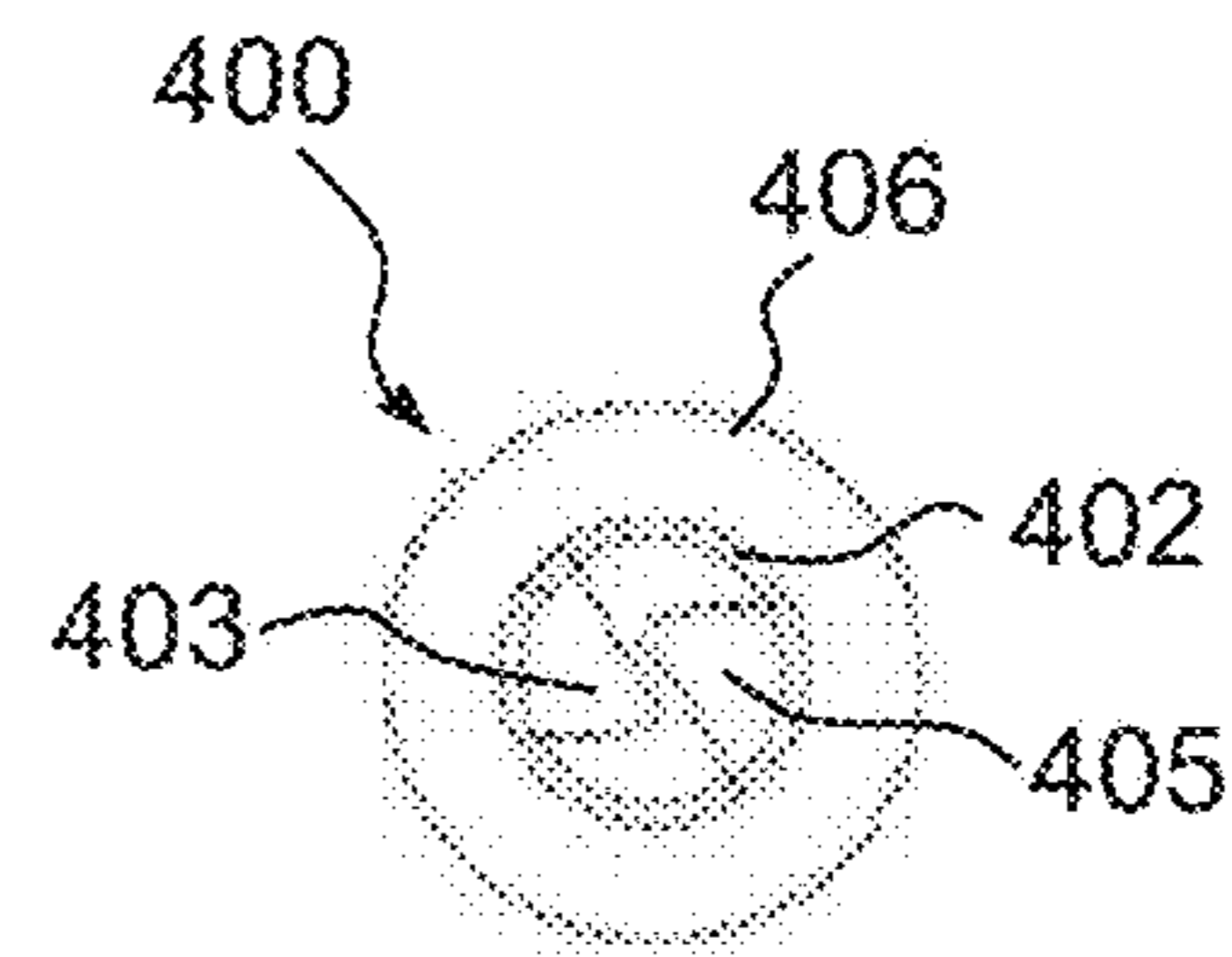


FIG. 12C

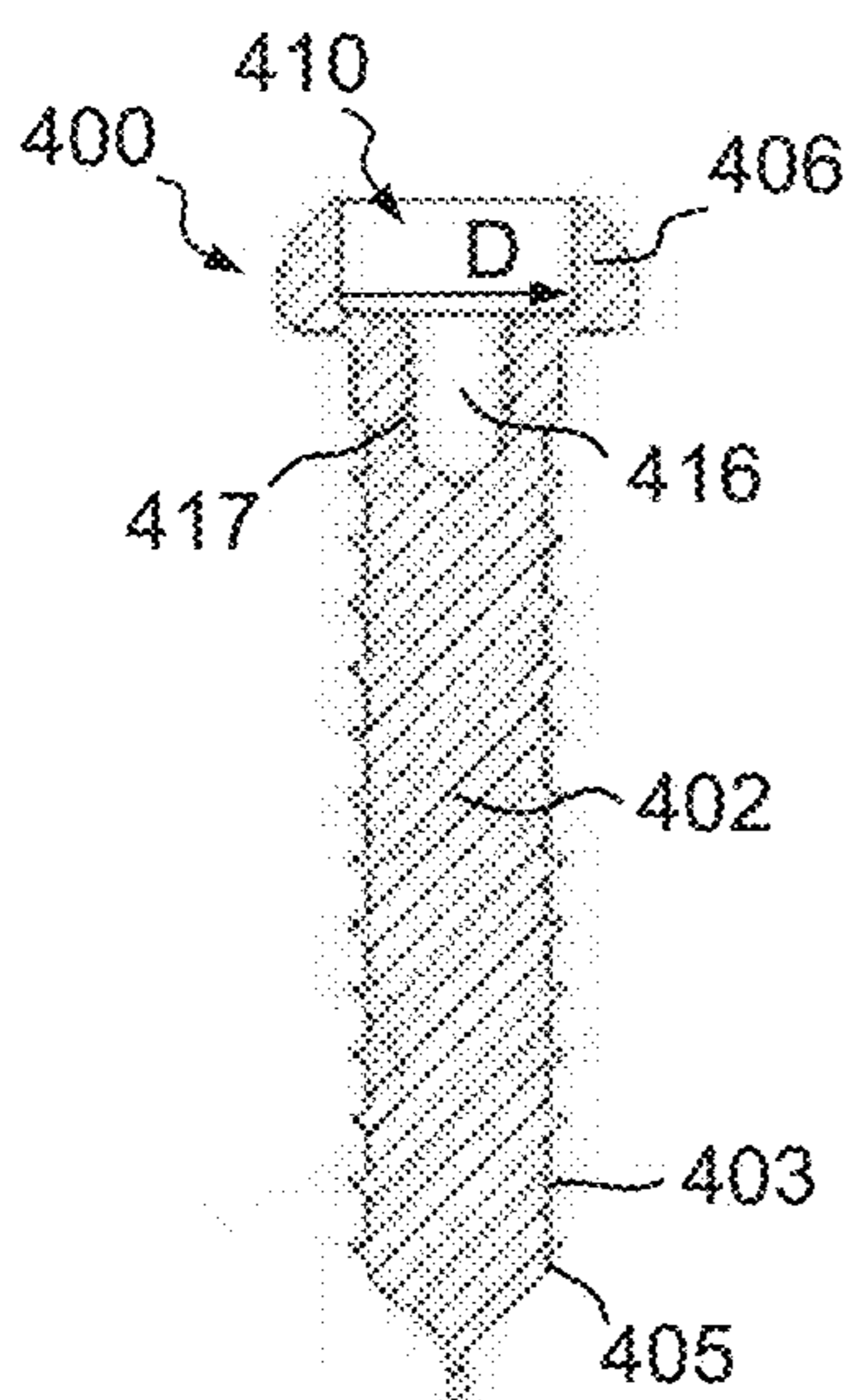


FIG. 12D

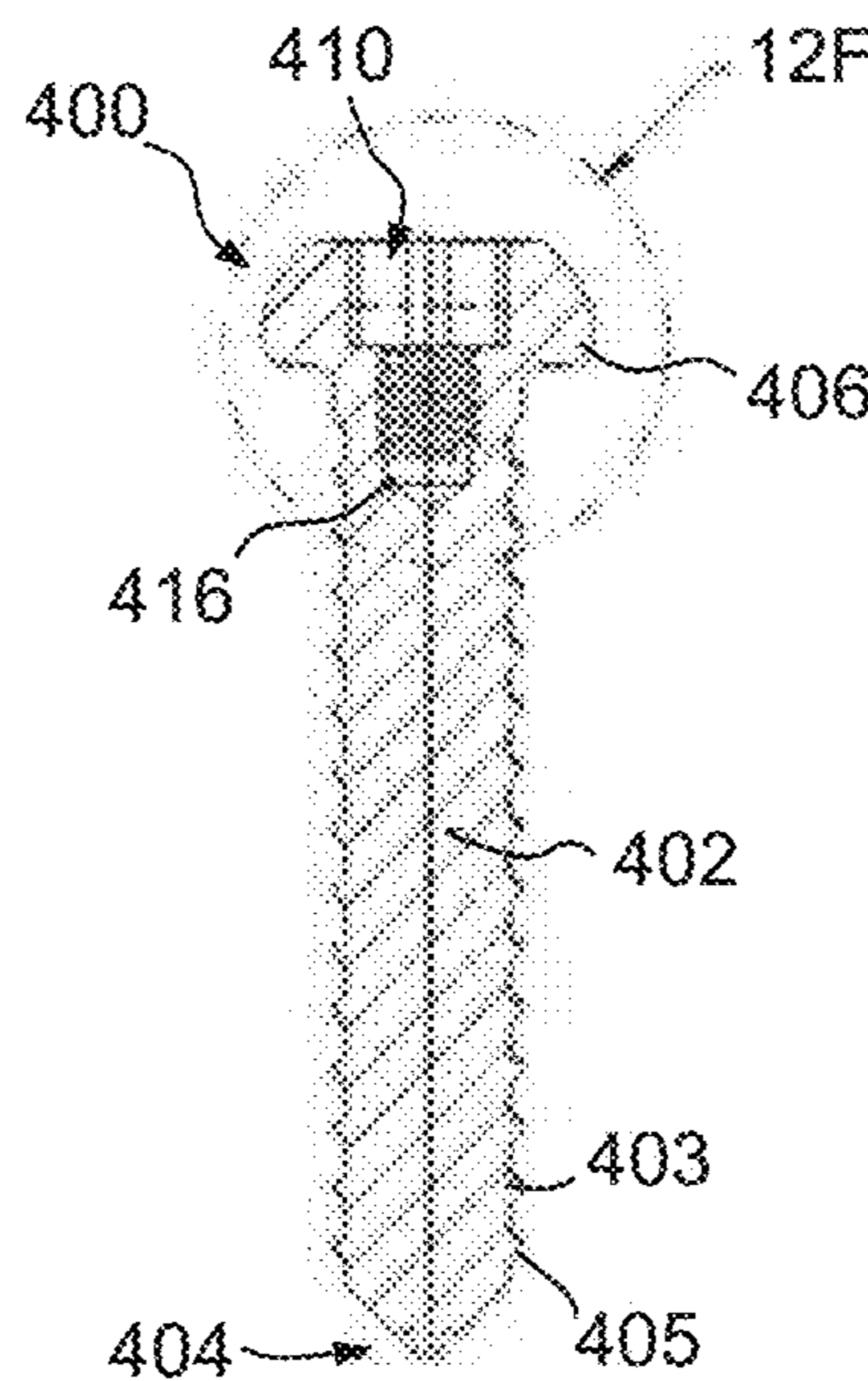


FIG. 12E

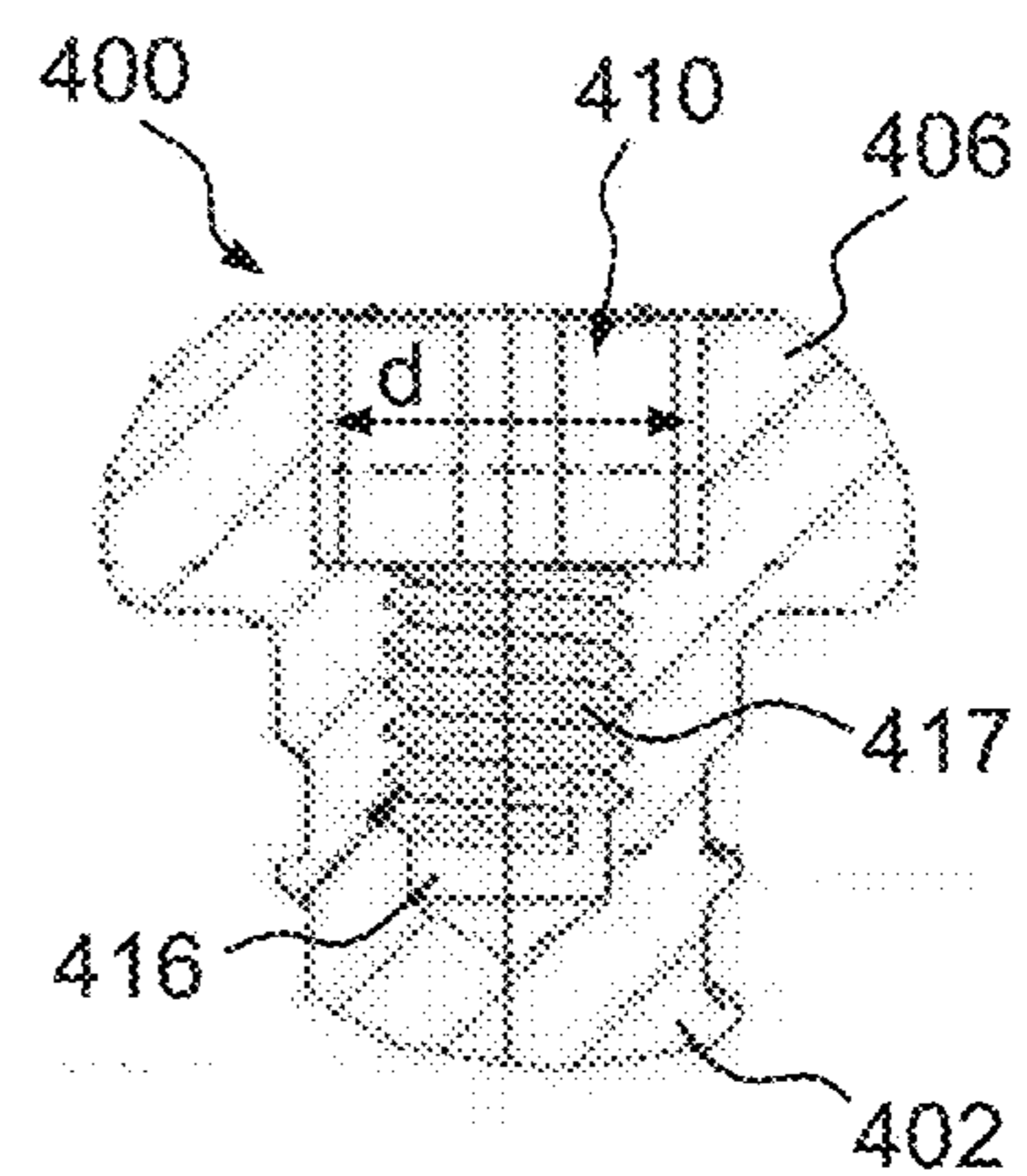


FIG. 12F

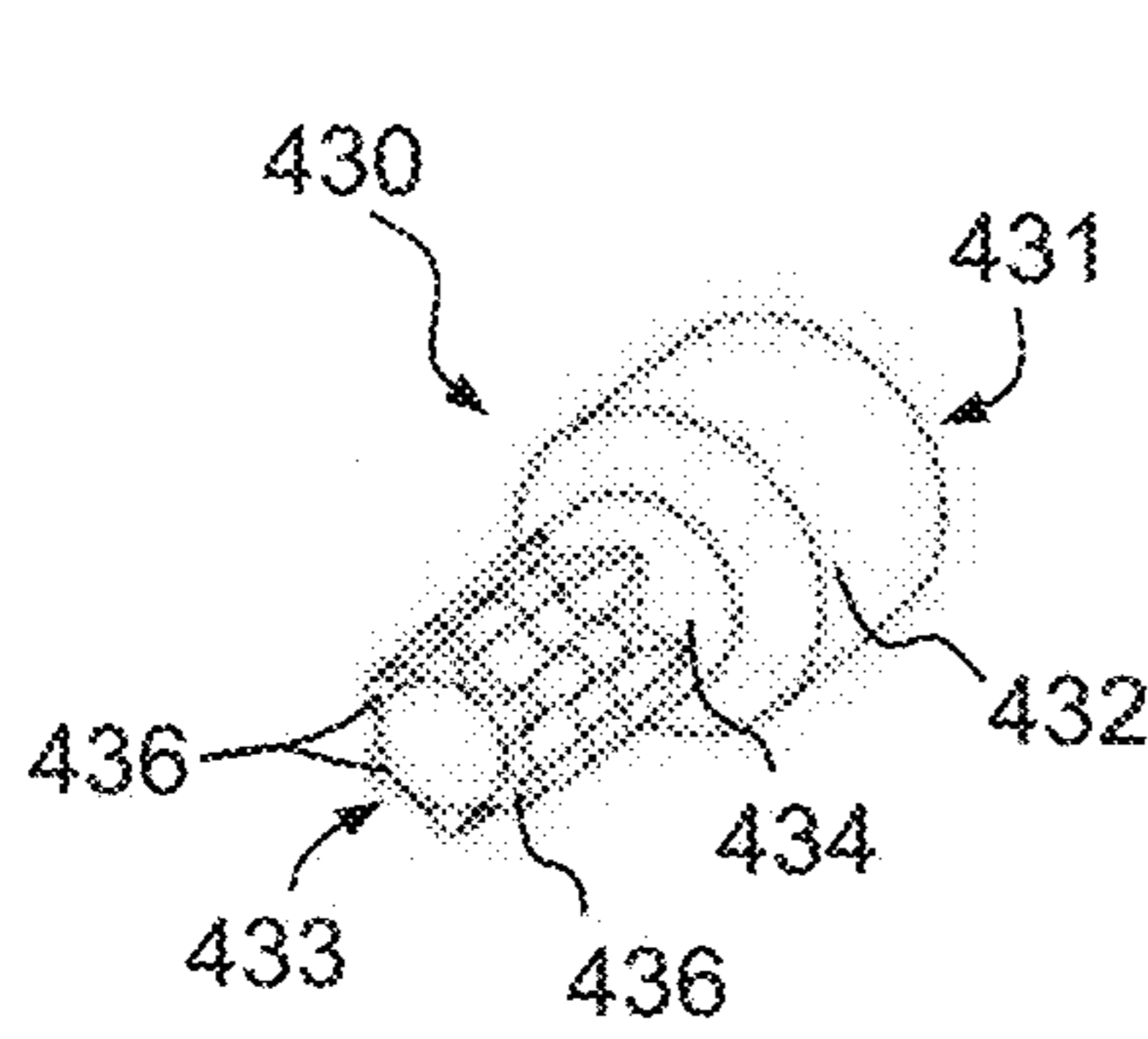


FIG. 12G

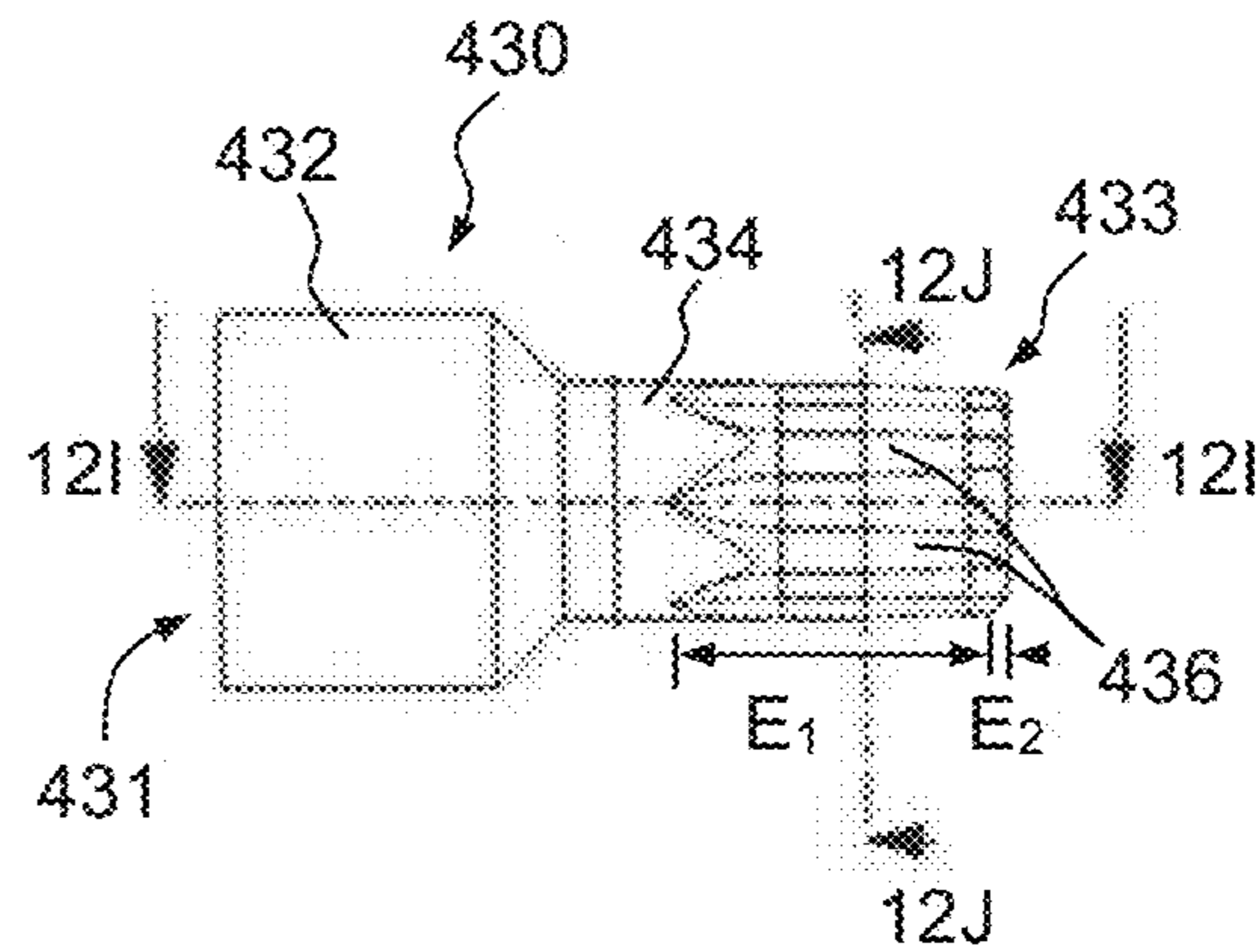


FIG. 12H

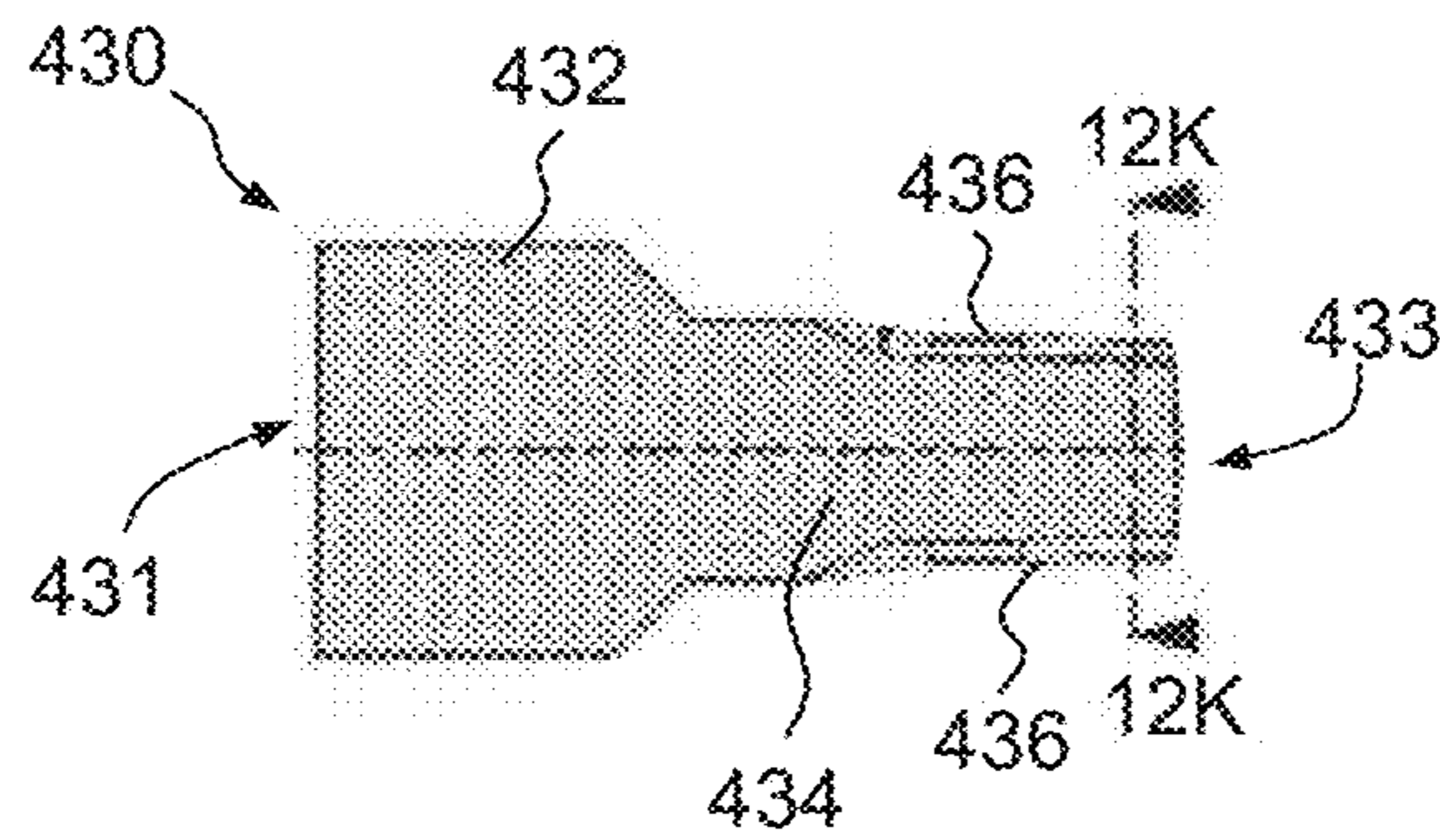


FIG. 12I

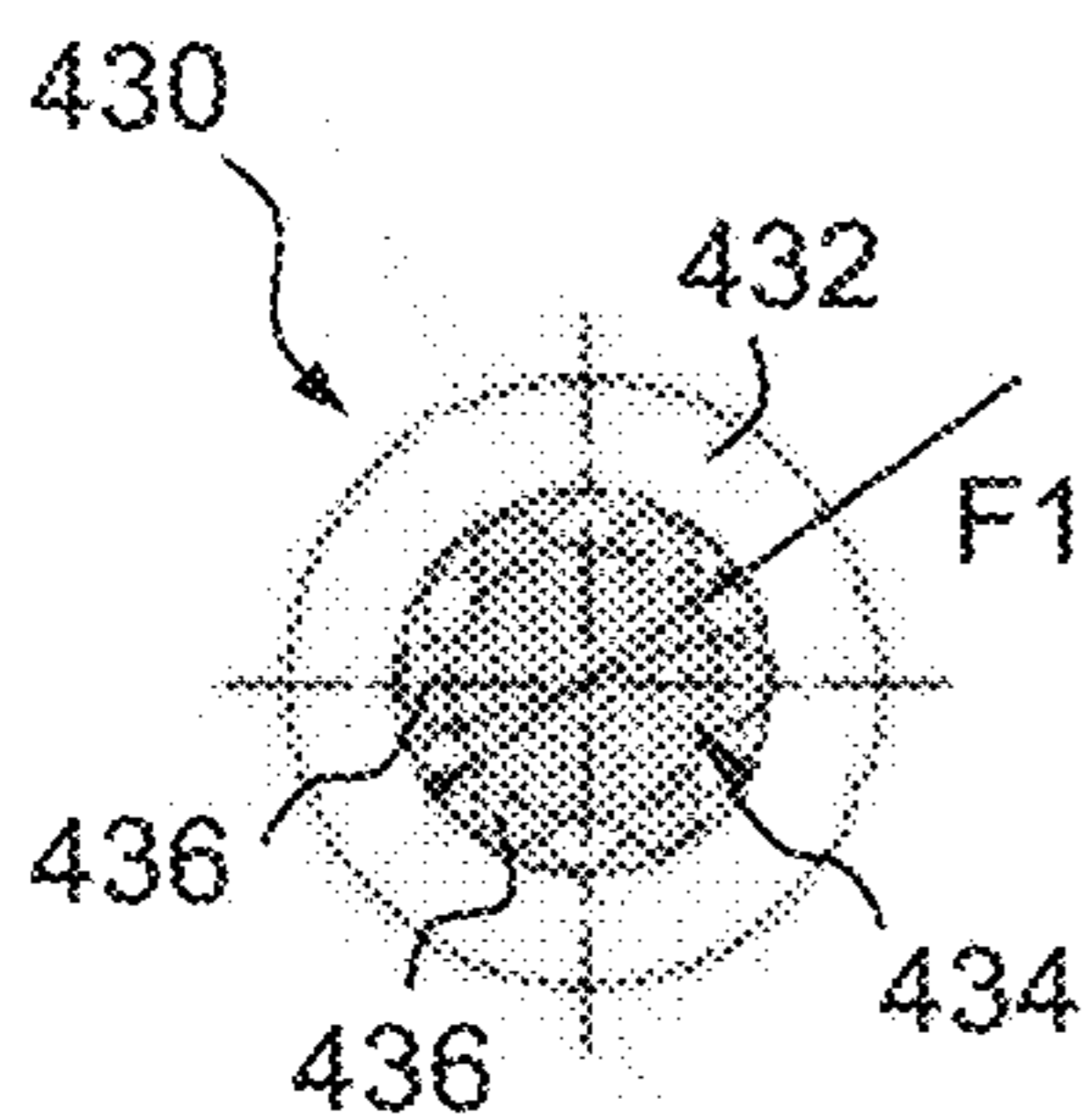


FIG. 12J

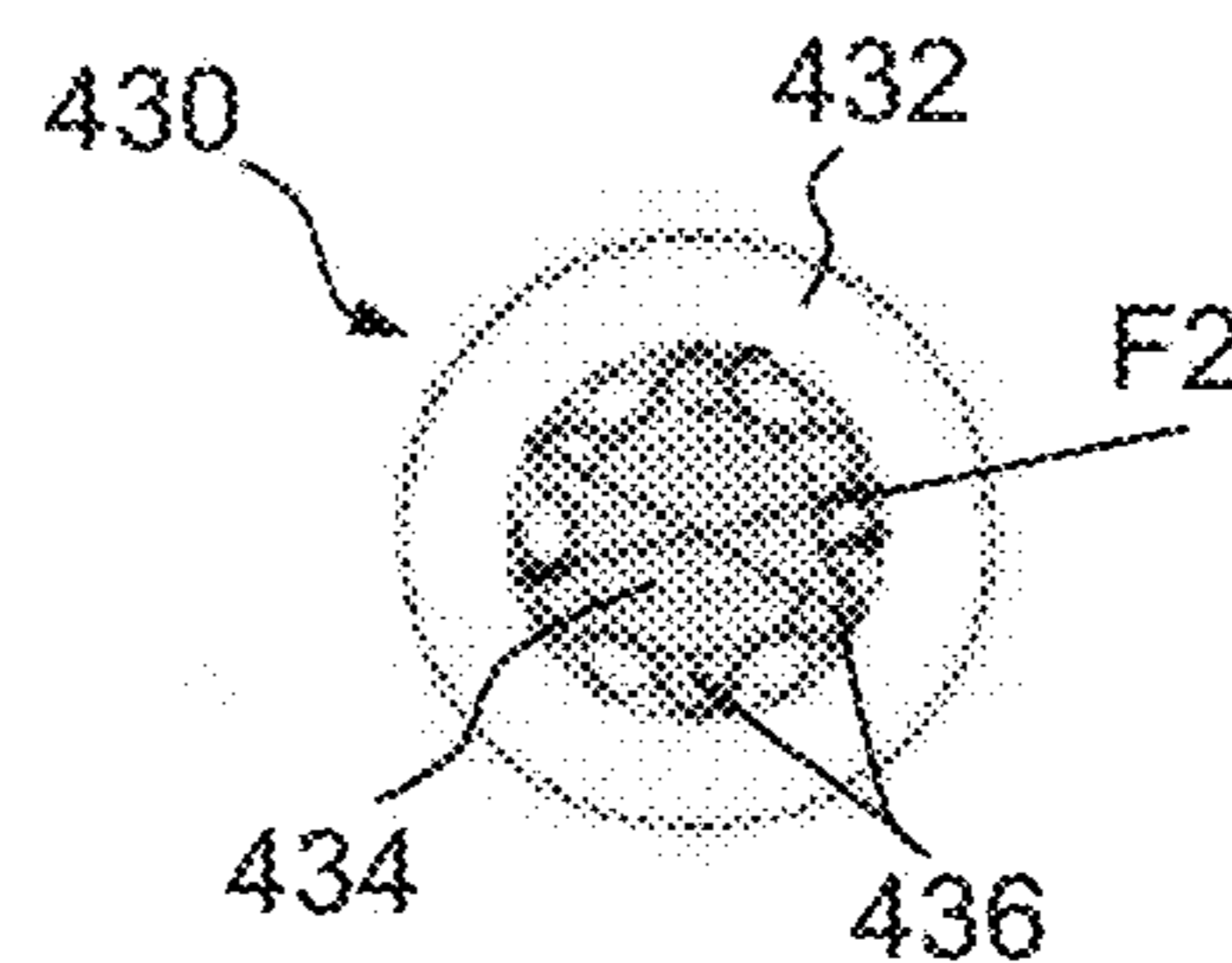


FIG. 12K

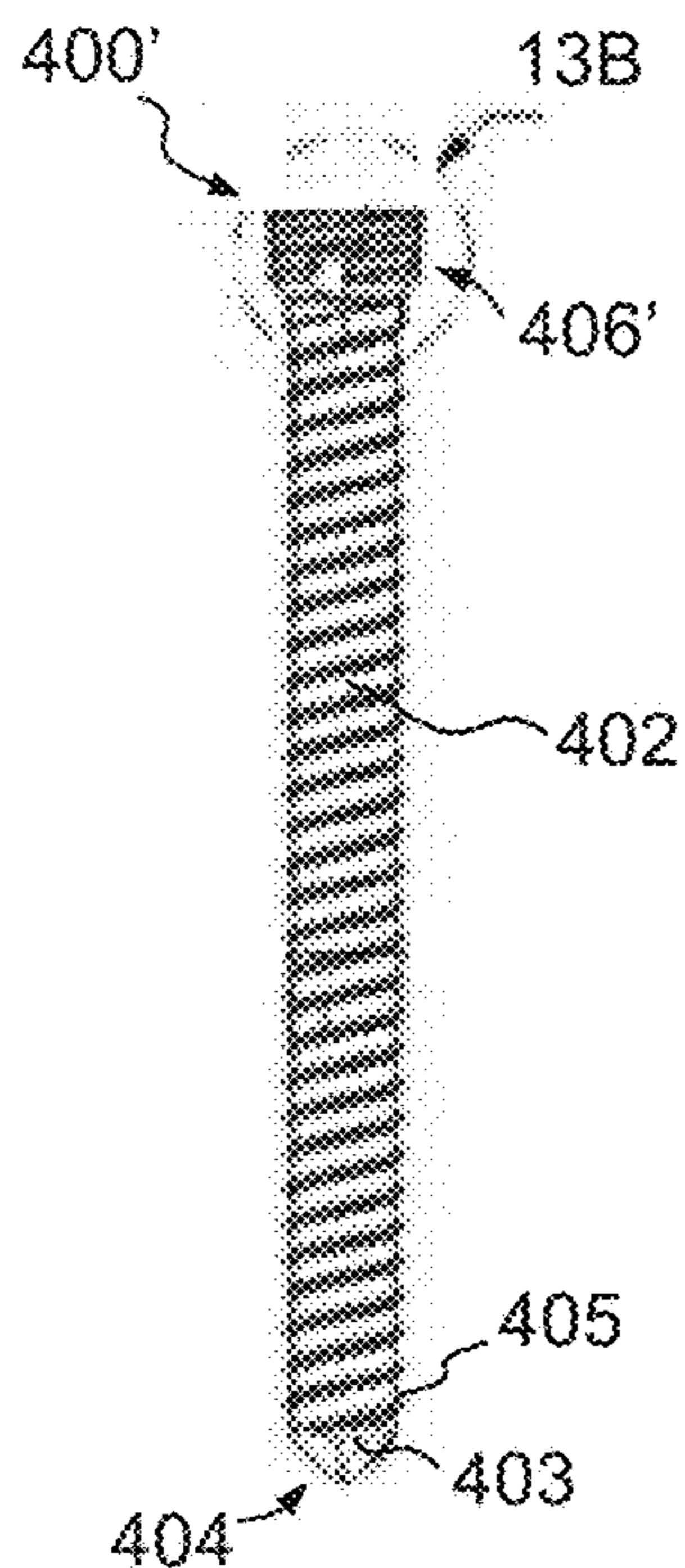


FIG. 13A

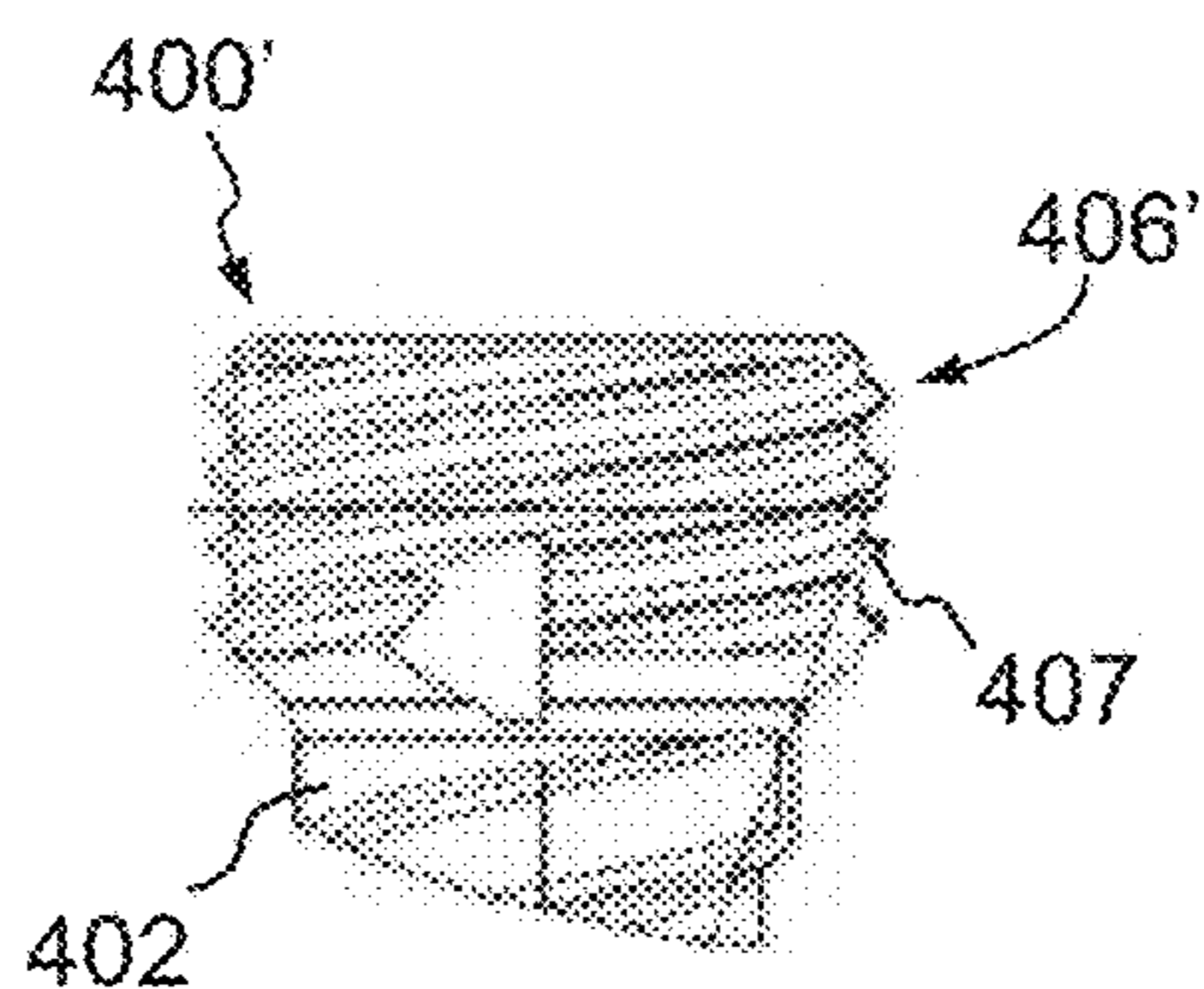


FIG. 13B

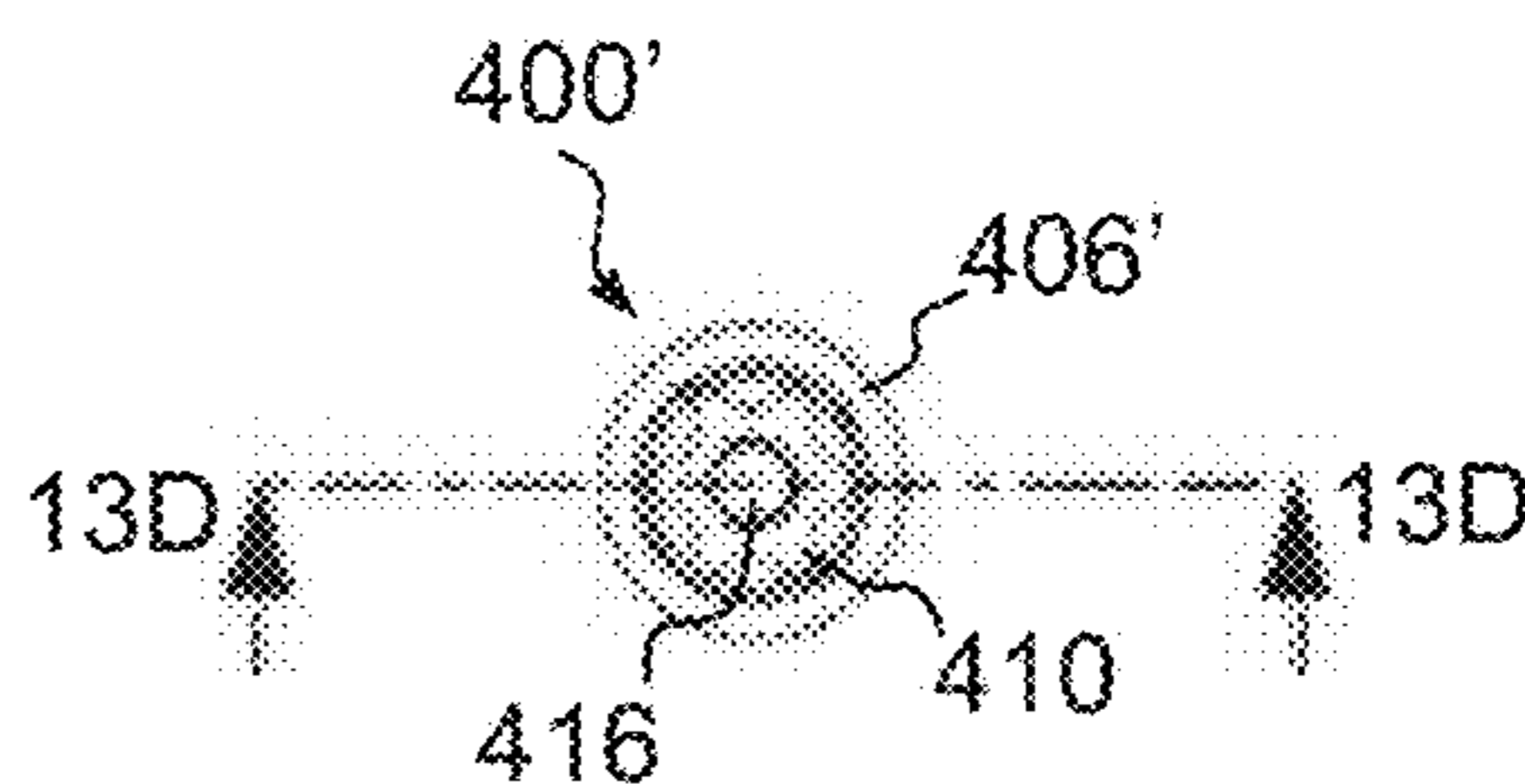


FIG. 13C

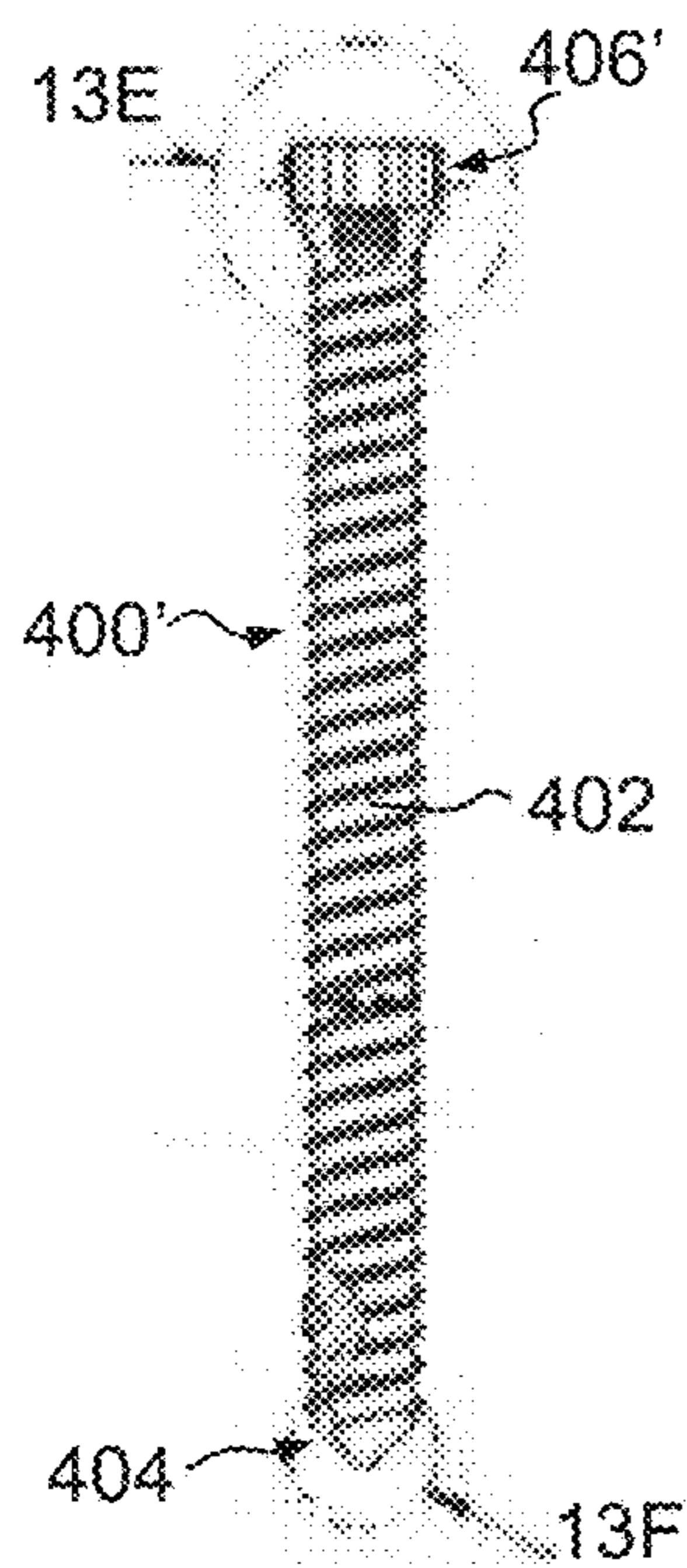


FIG. 13D

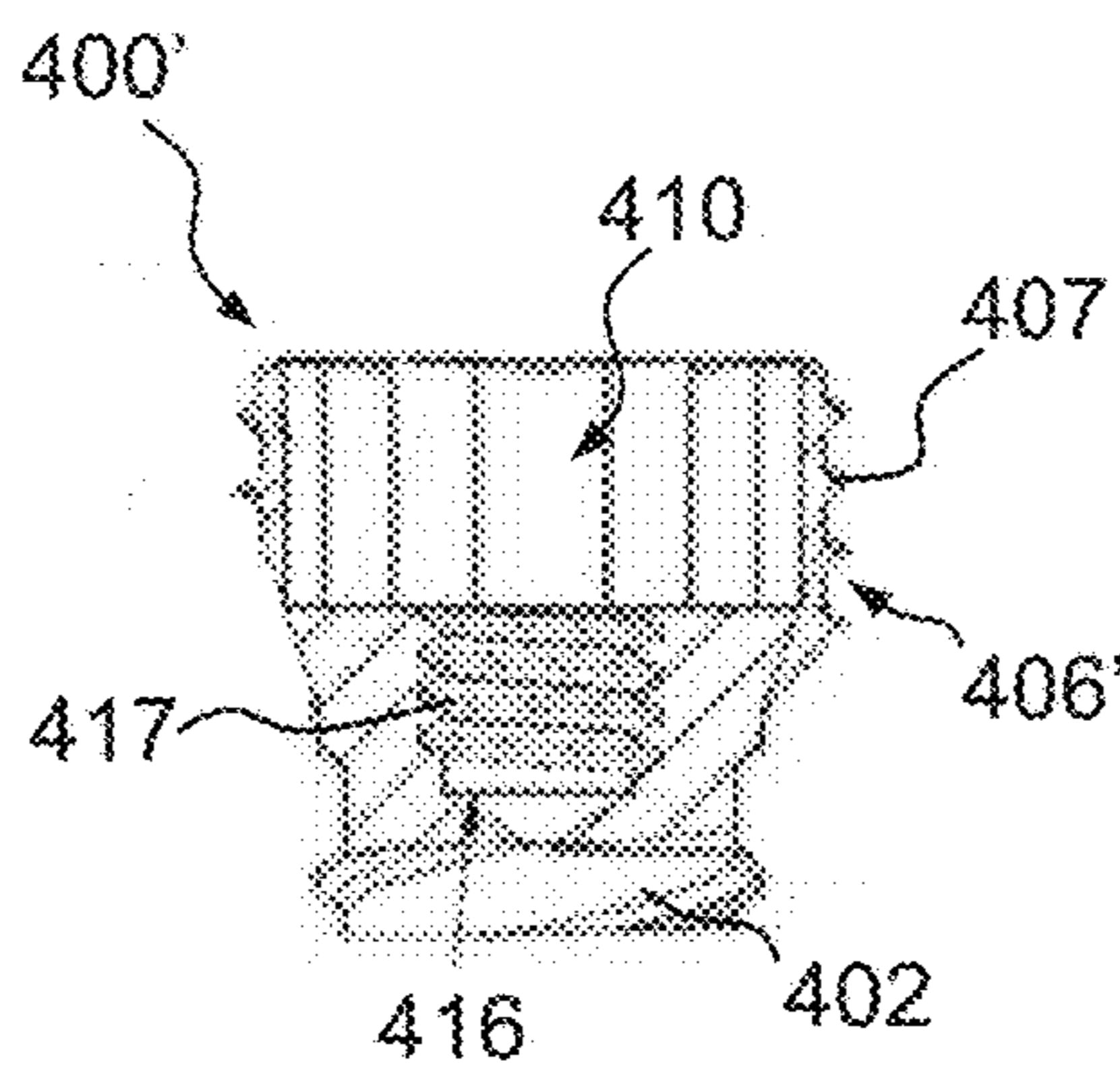


FIG. 13E

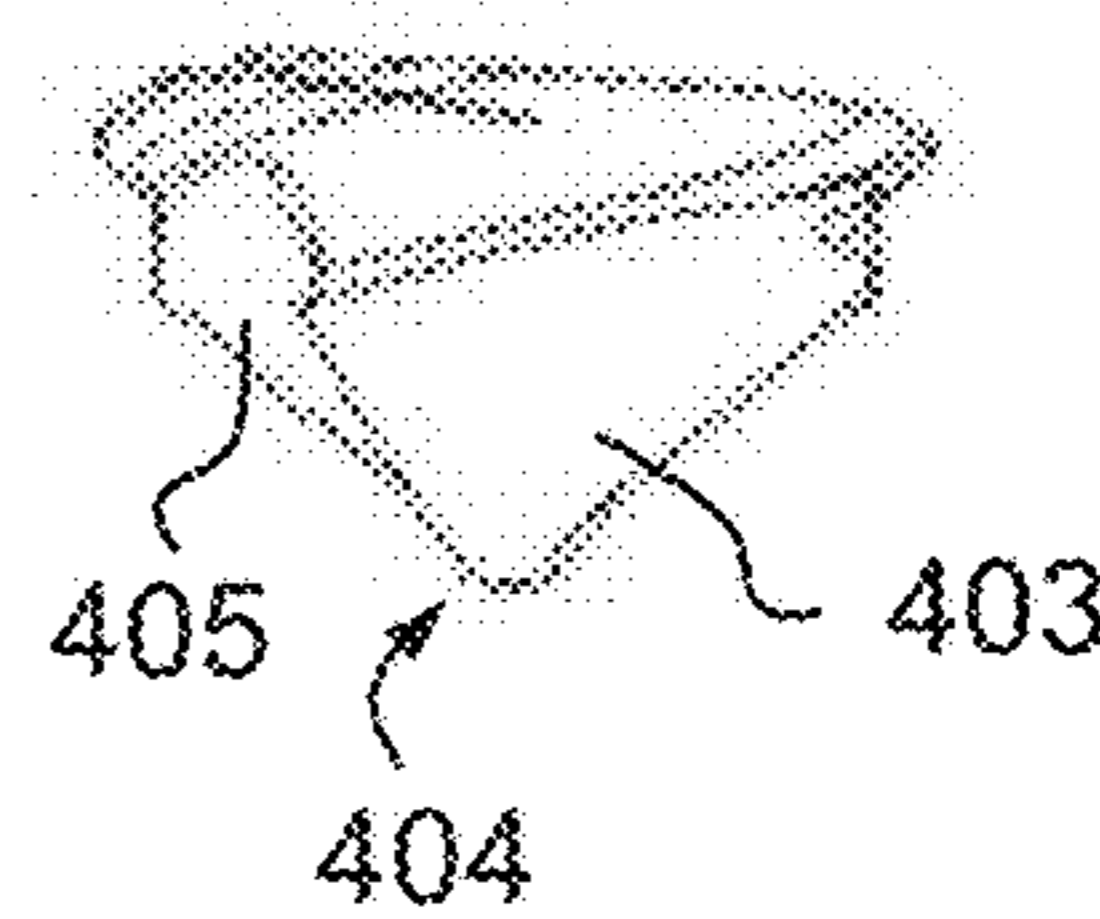


FIG. 13F

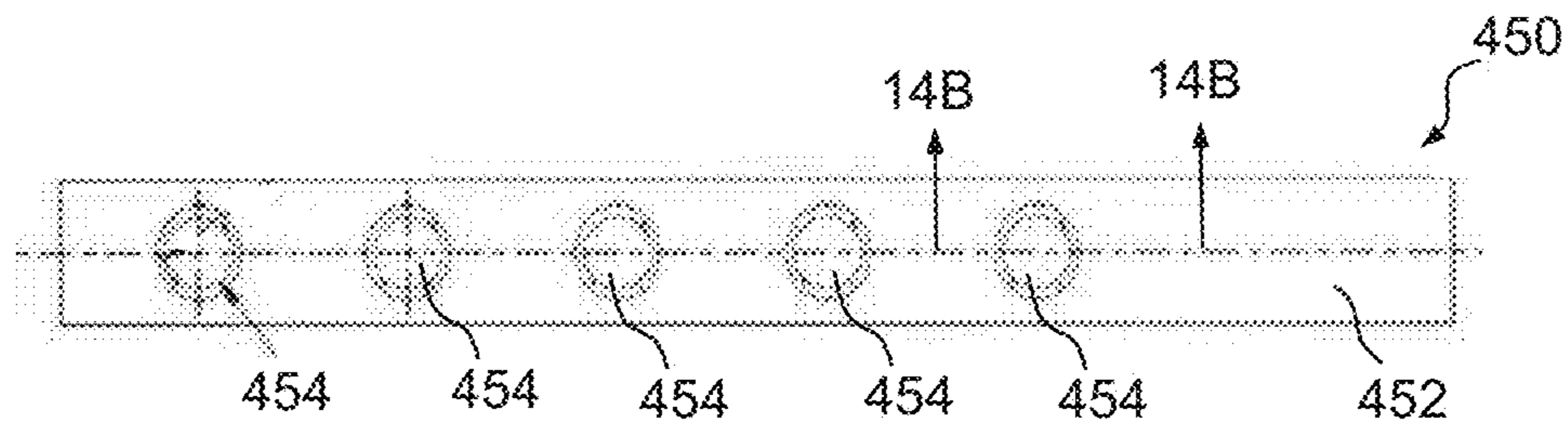


FIG. 14A

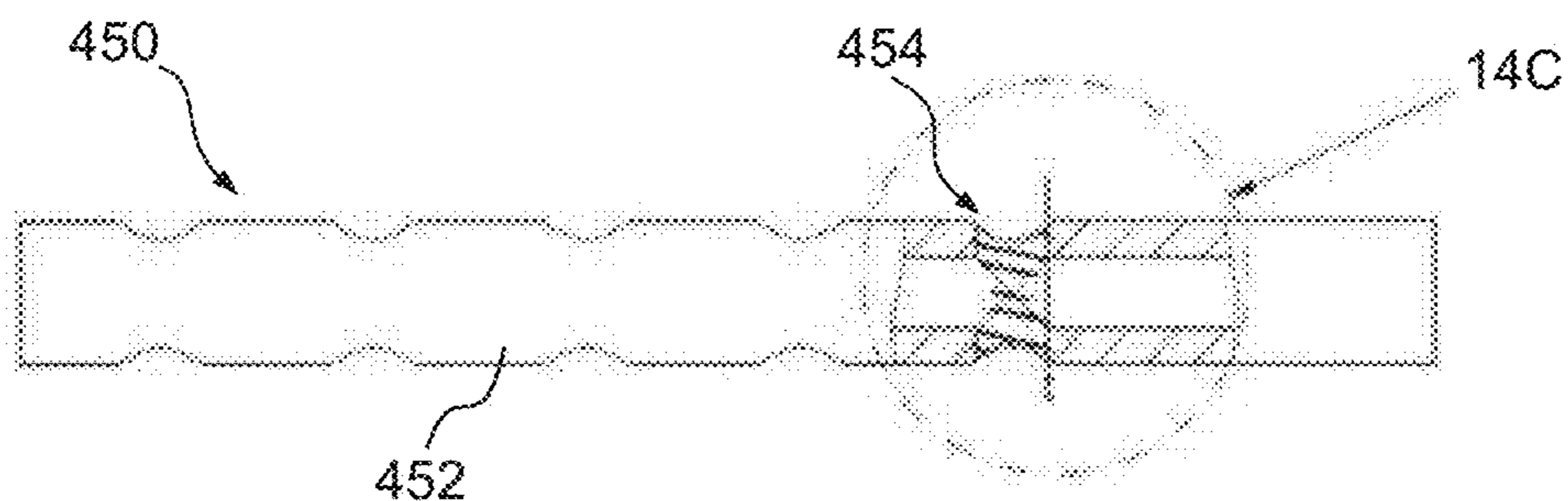


FIG. 14B

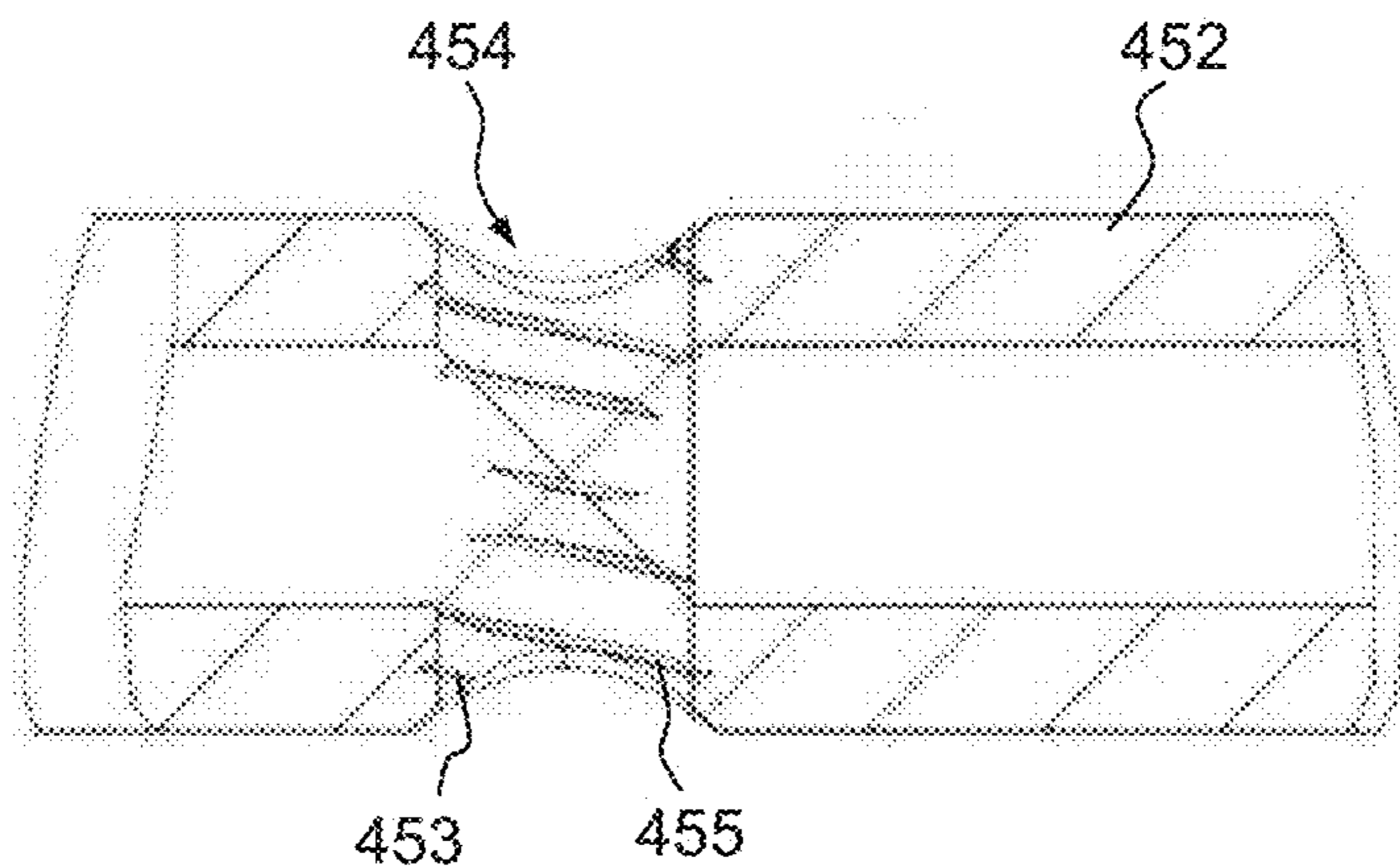


FIG. 14C

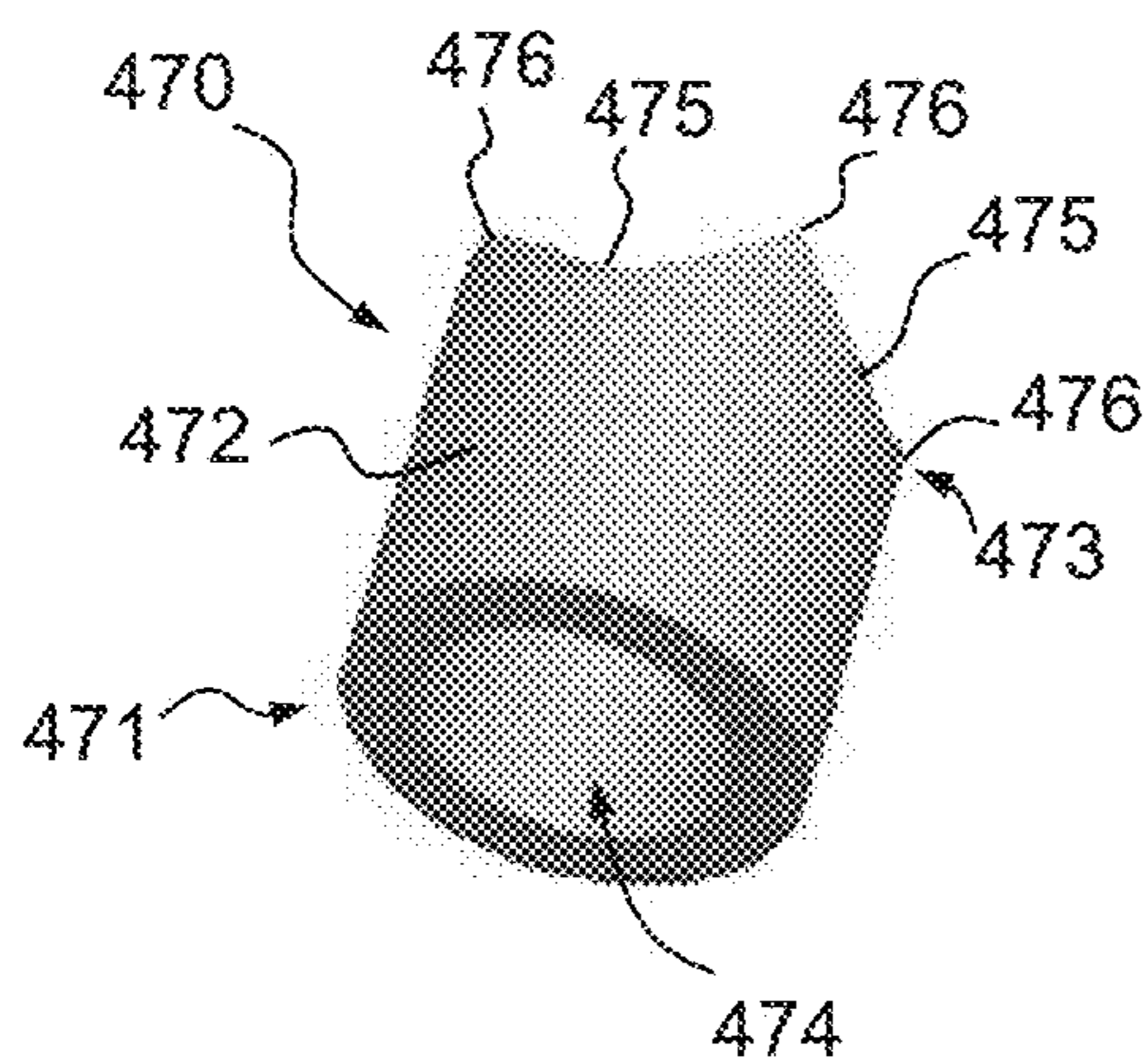


FIG. 15A

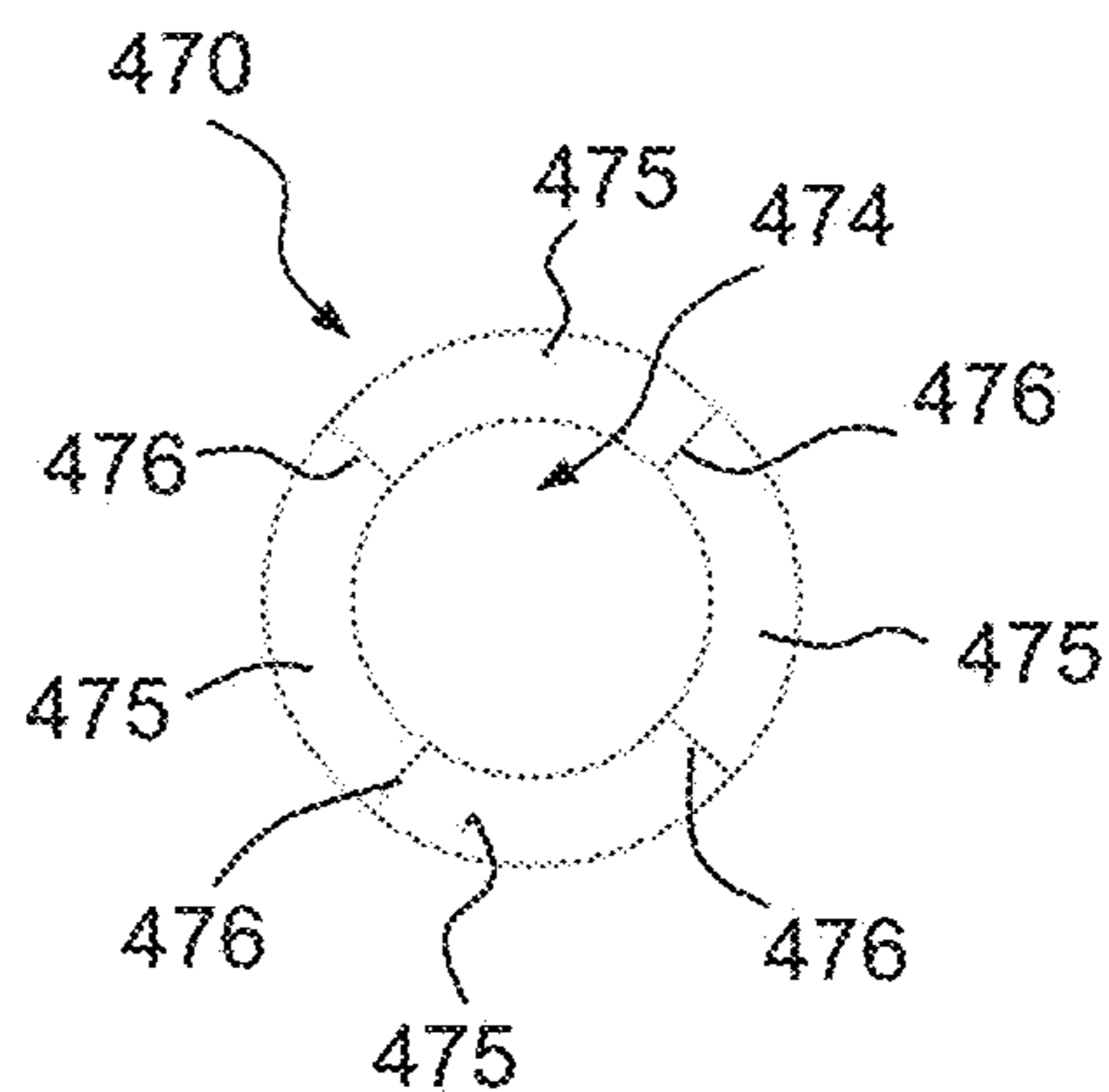


FIG. 15B

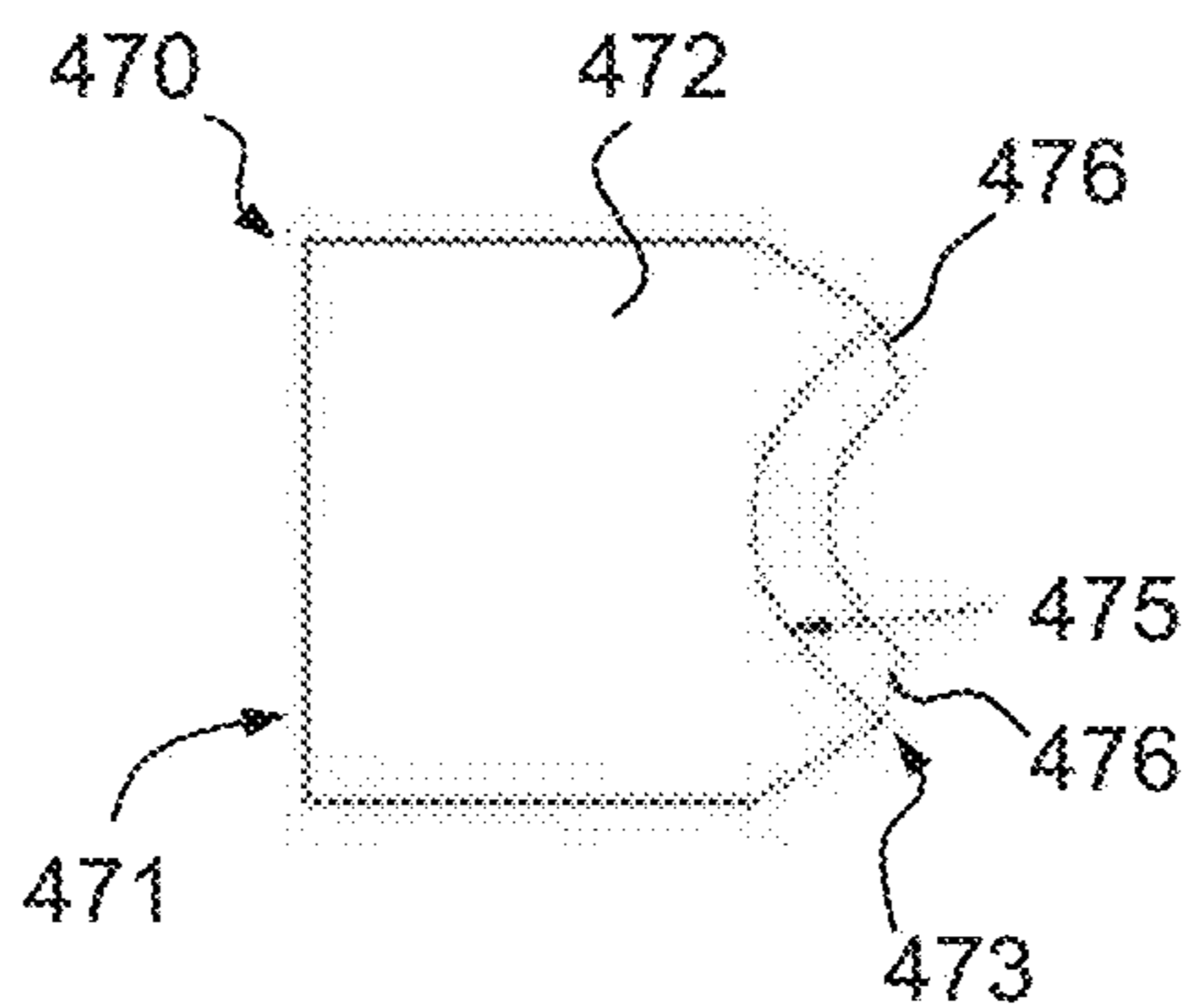


FIG. 15C

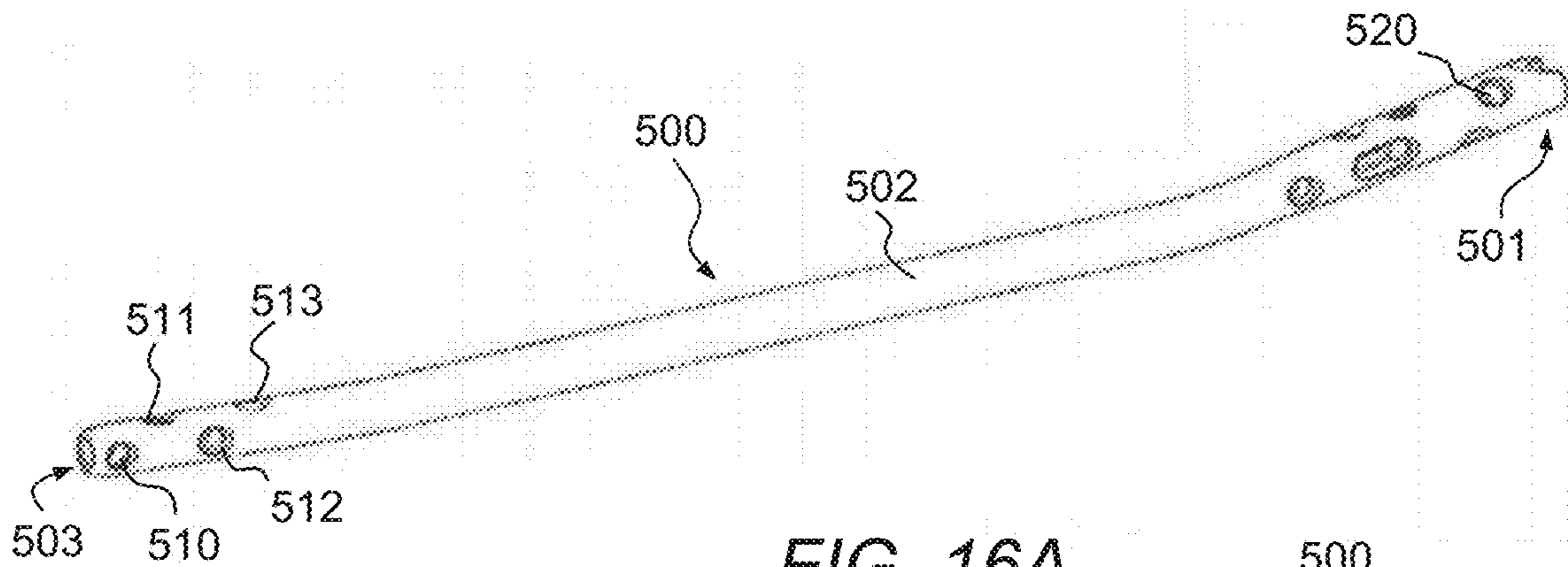


FIG. 16A

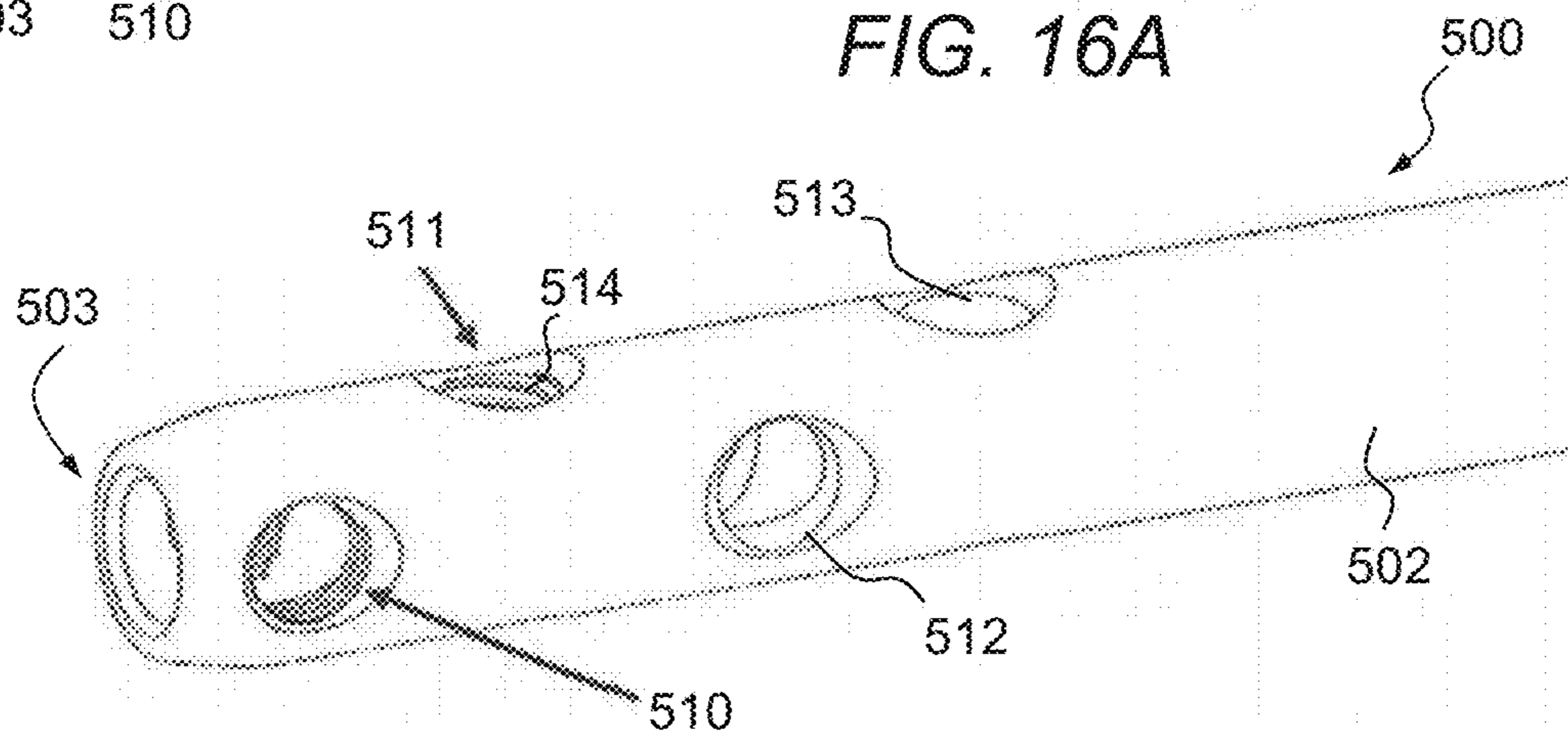


FIG. 16B

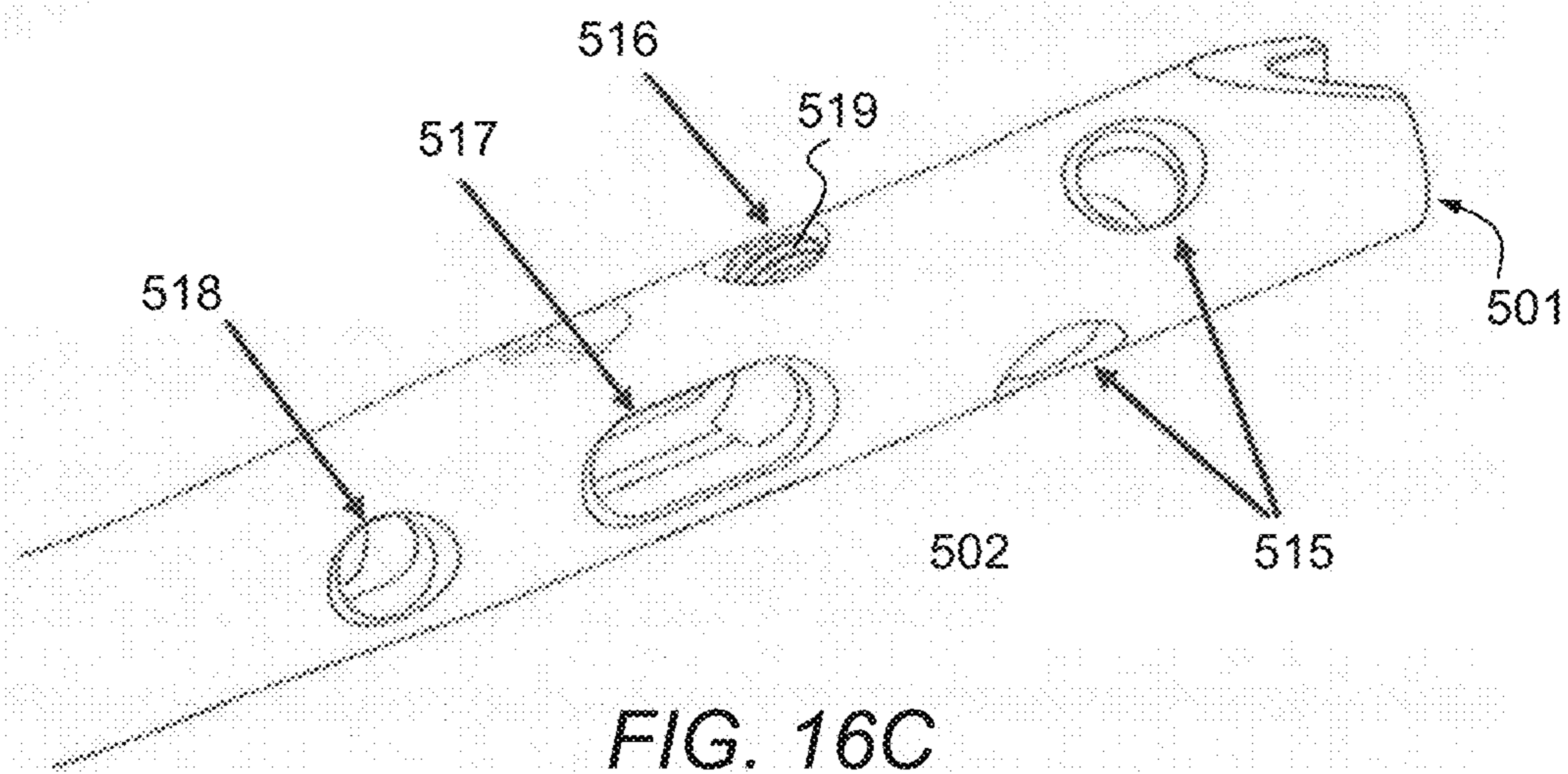


FIG. 16C

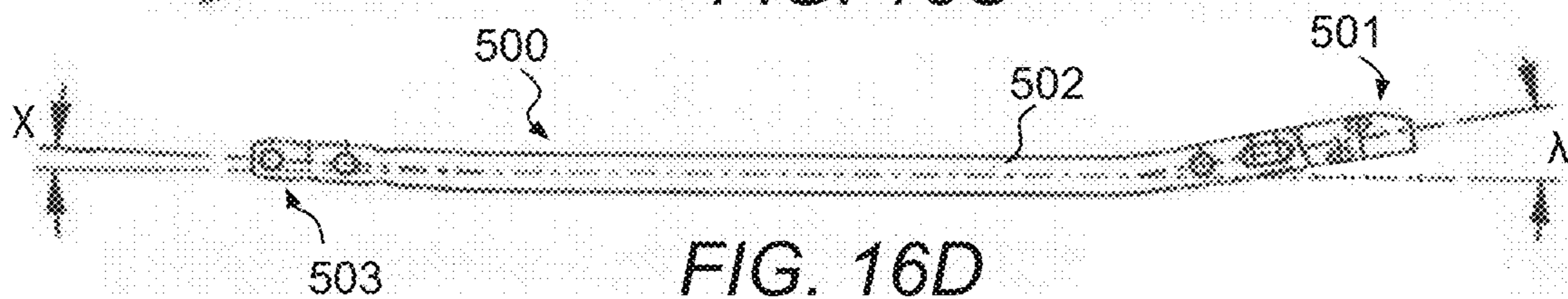


FIG. 16D

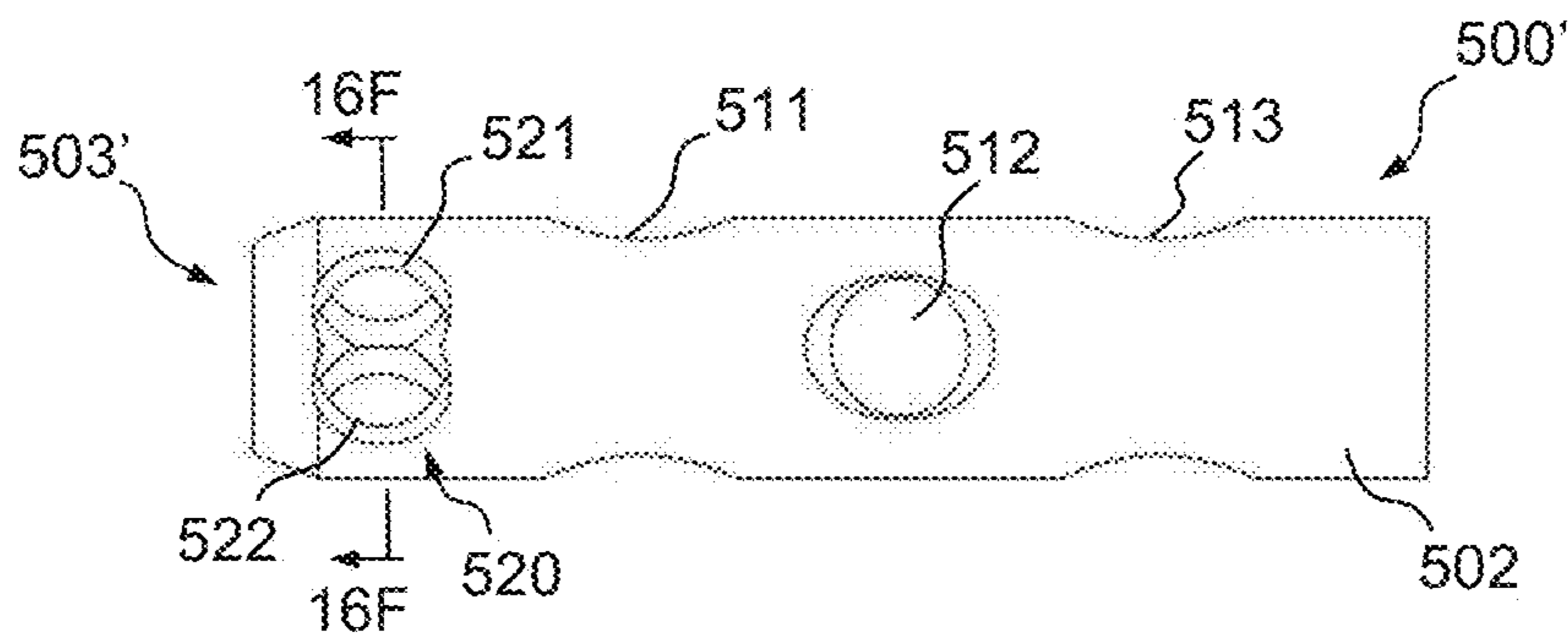


FIG. 16E

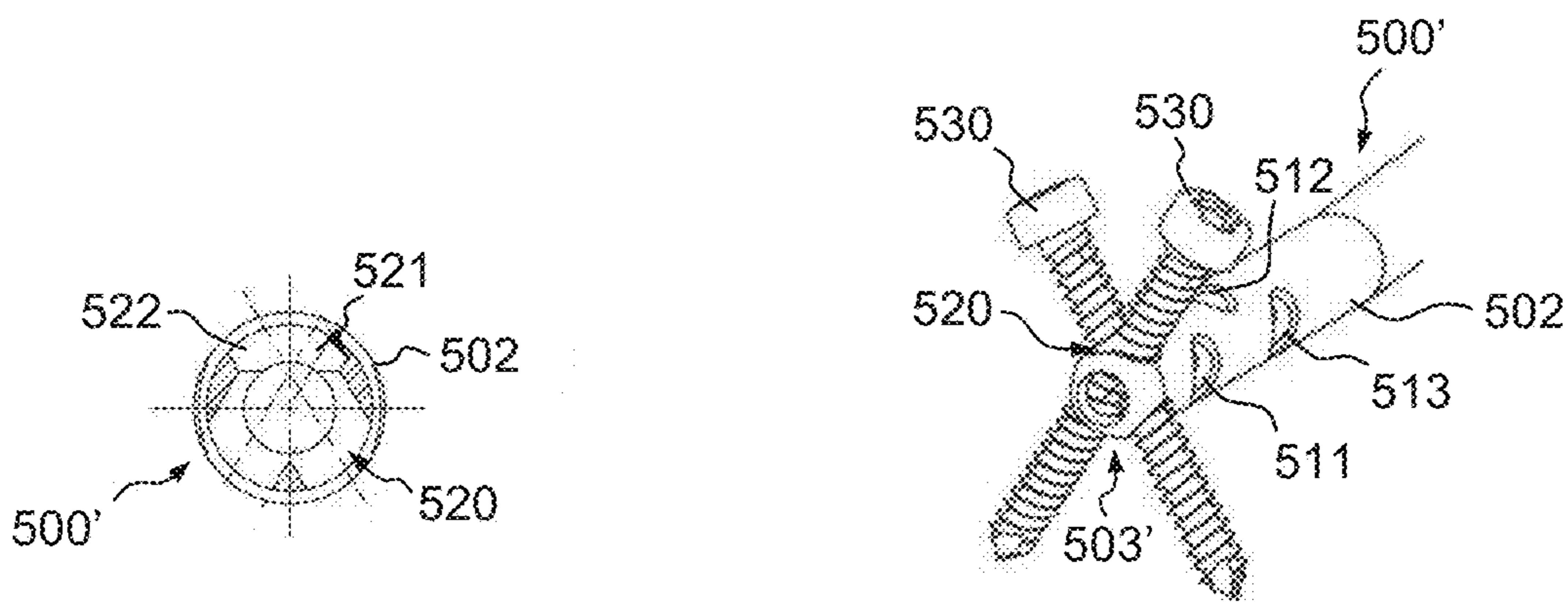


FIG. 16F

FIG. 16G

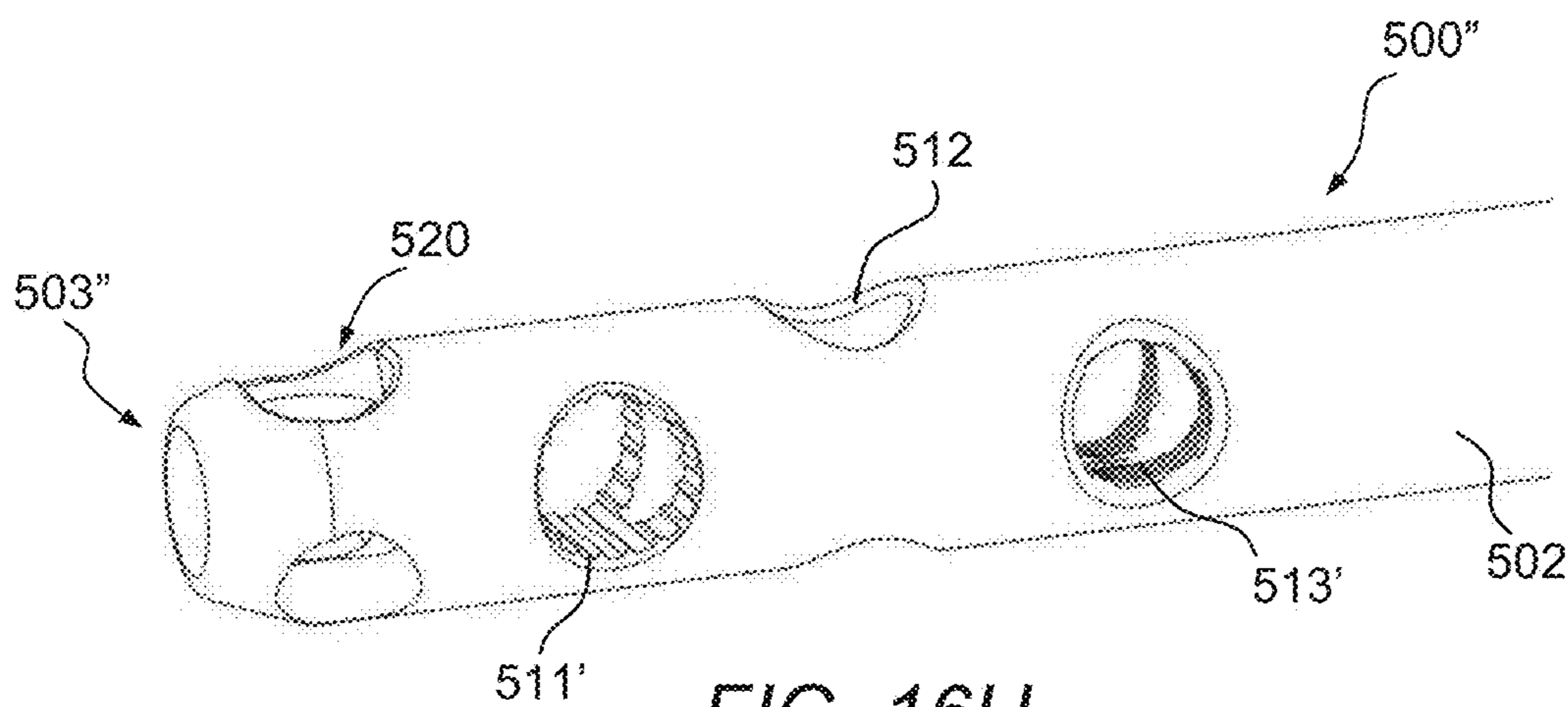


FIG. 16H

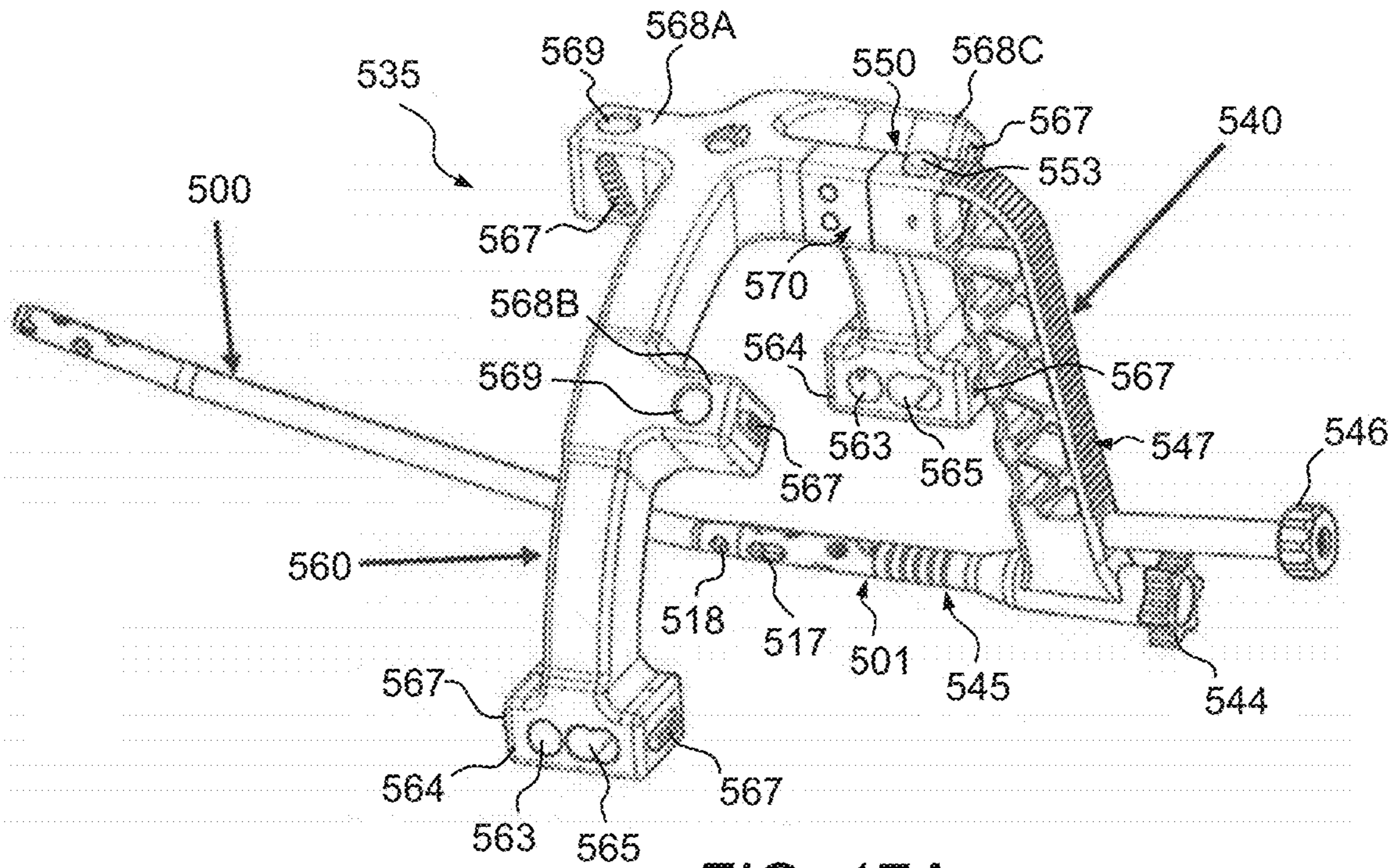


FIG. 17A

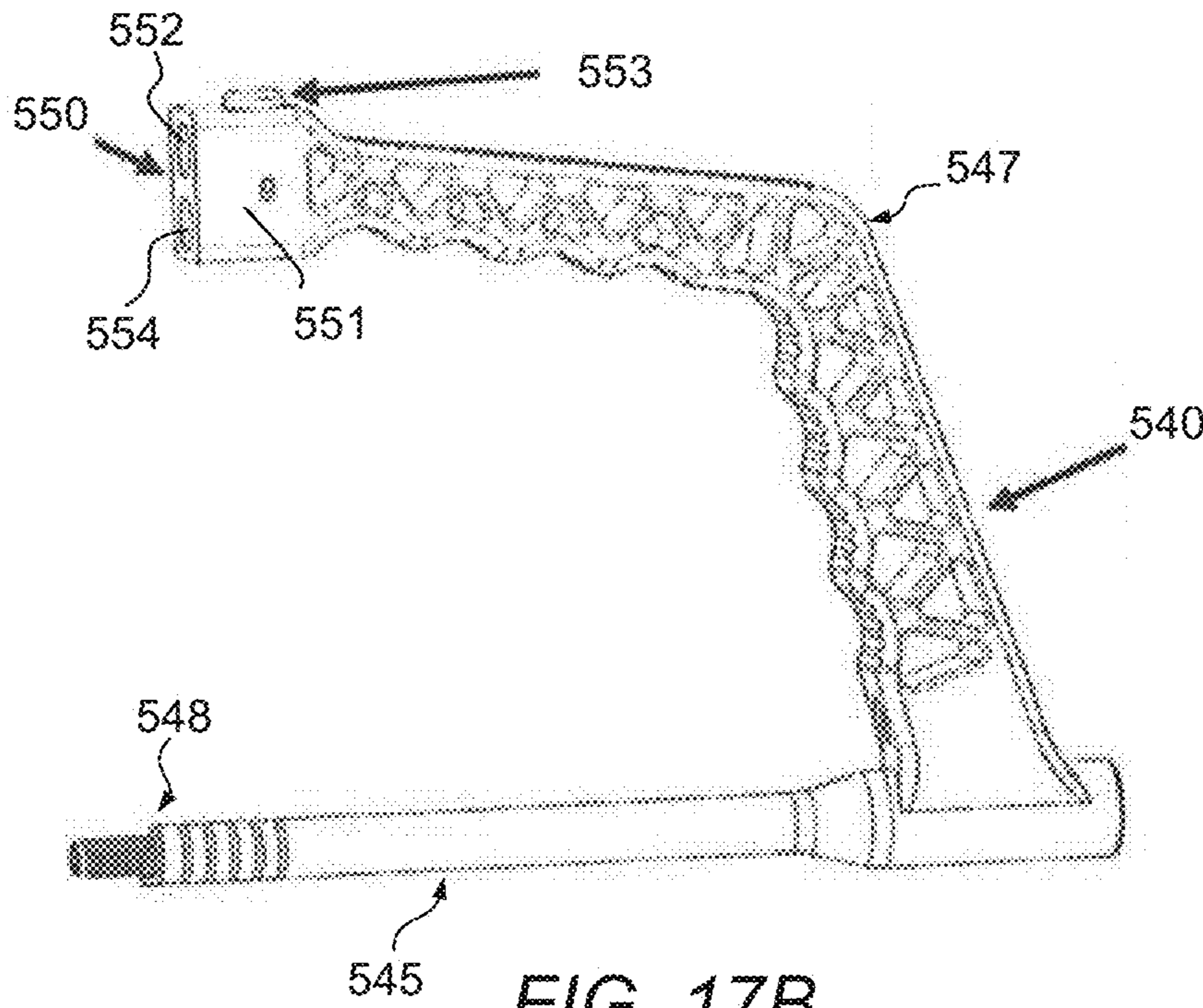


FIG. 17B

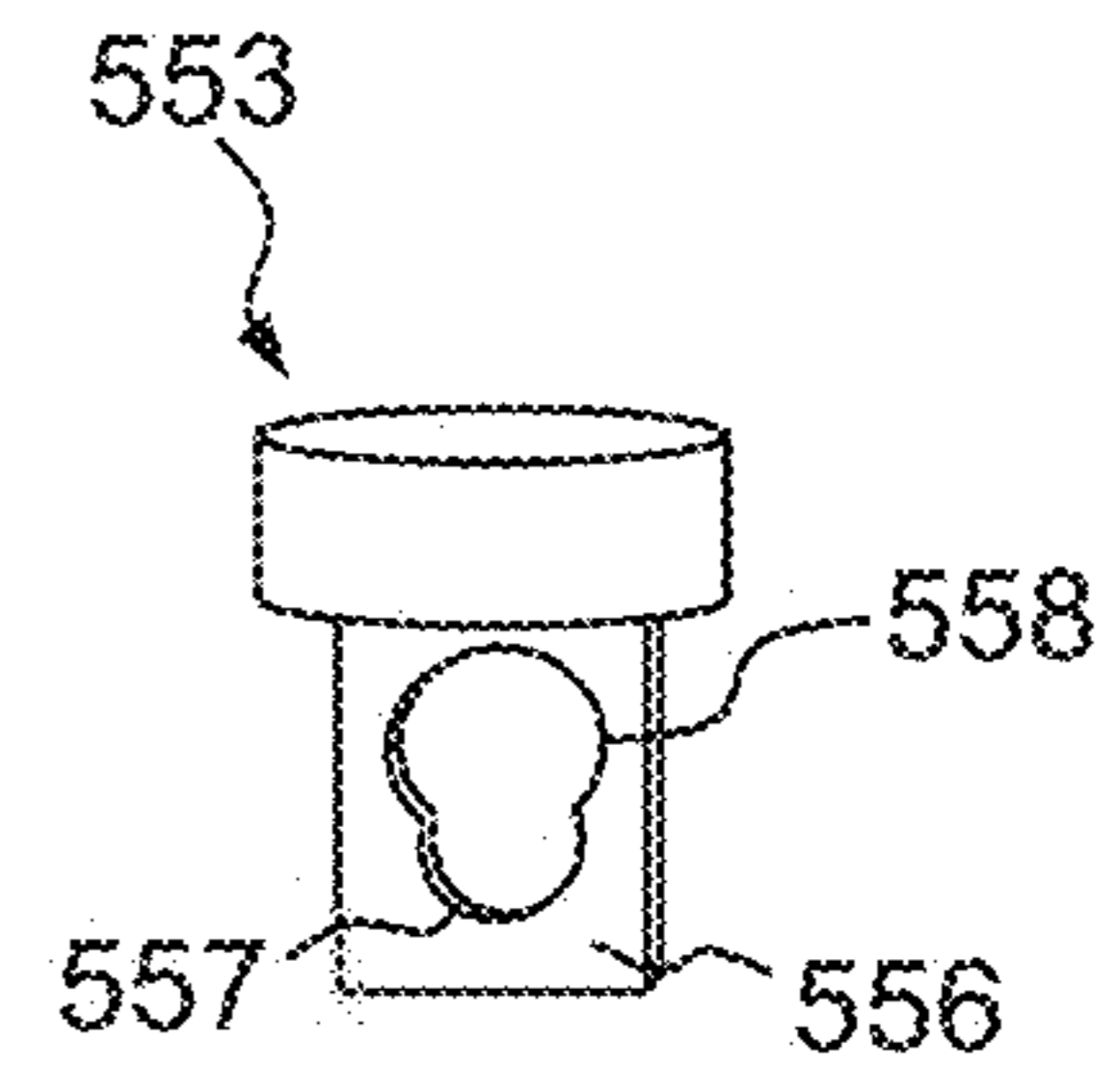


FIG. 17C

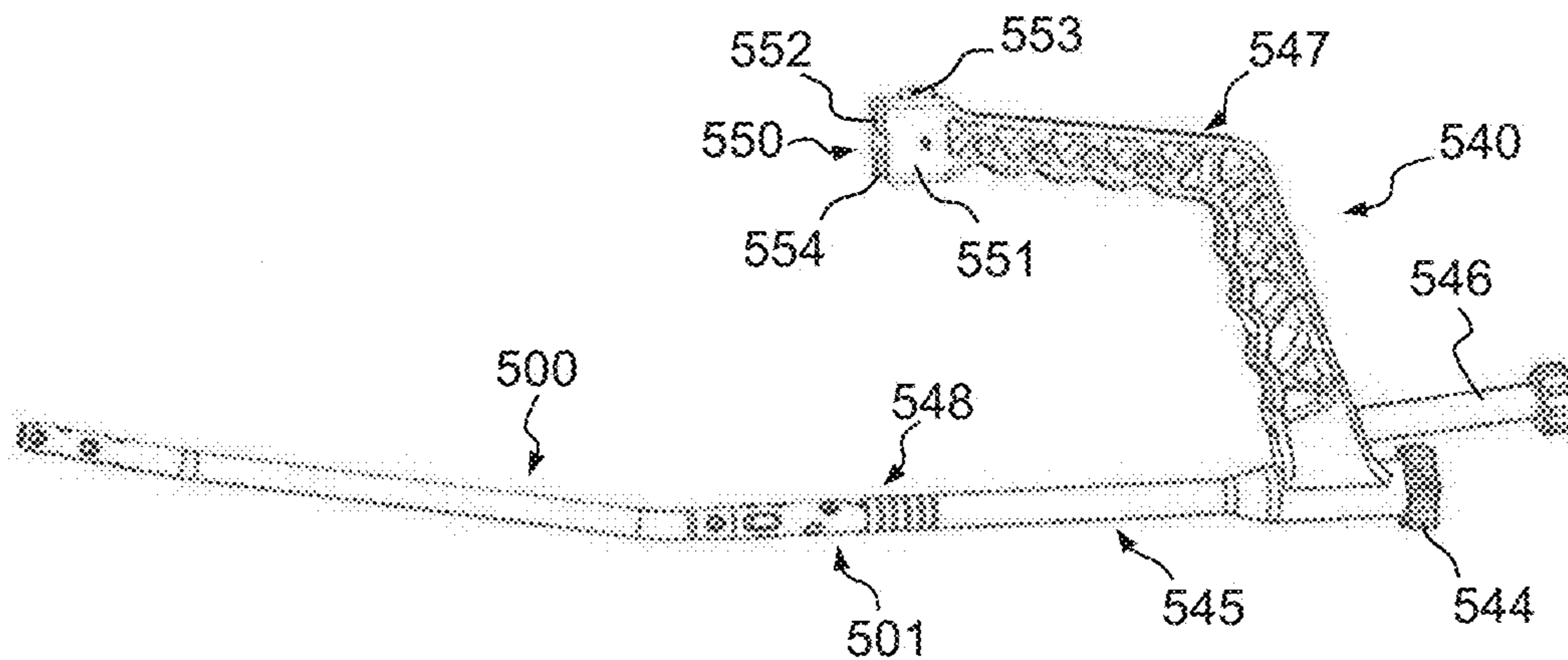


FIG. 17D

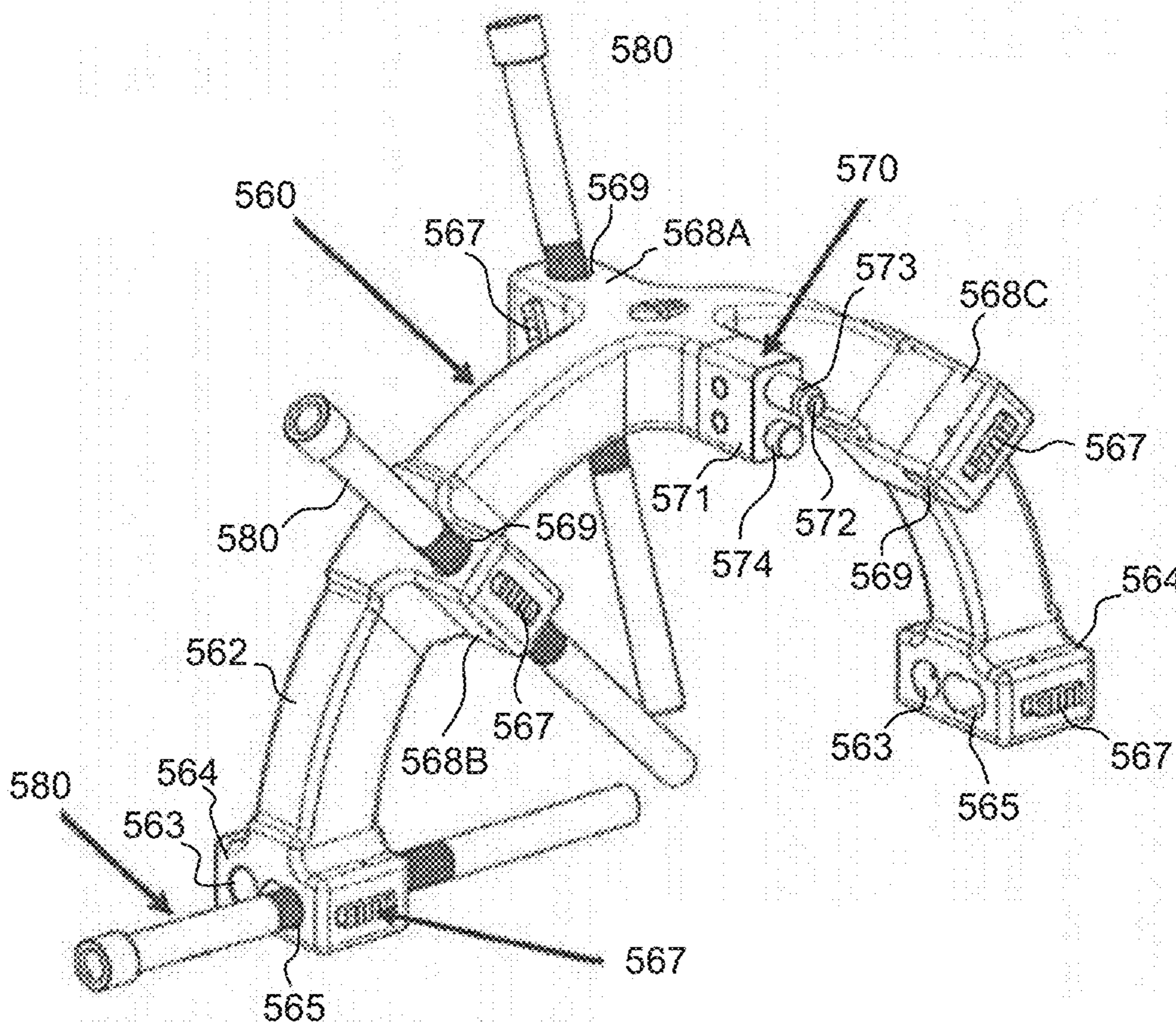


FIG. 17E

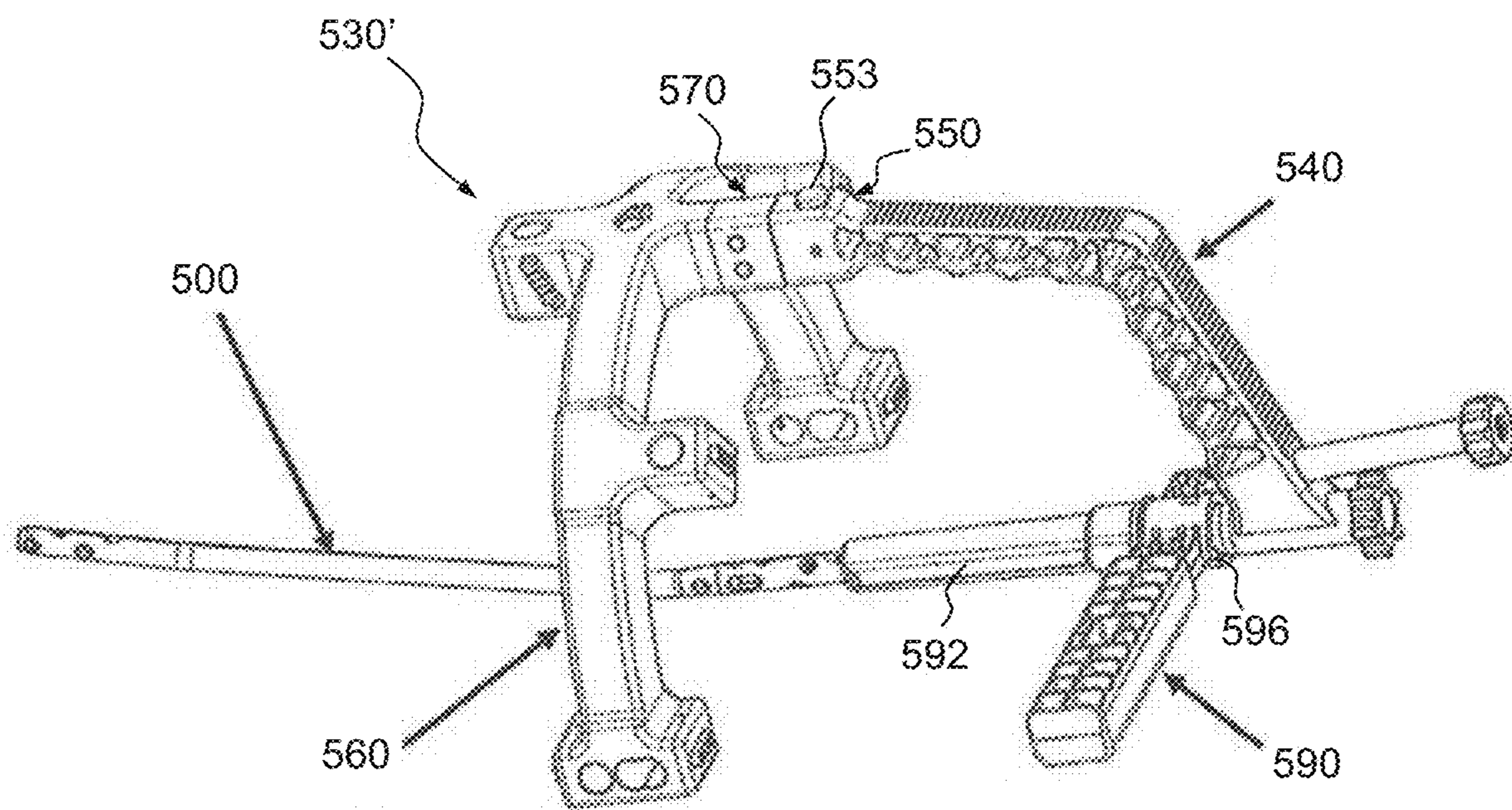


FIG. 17F

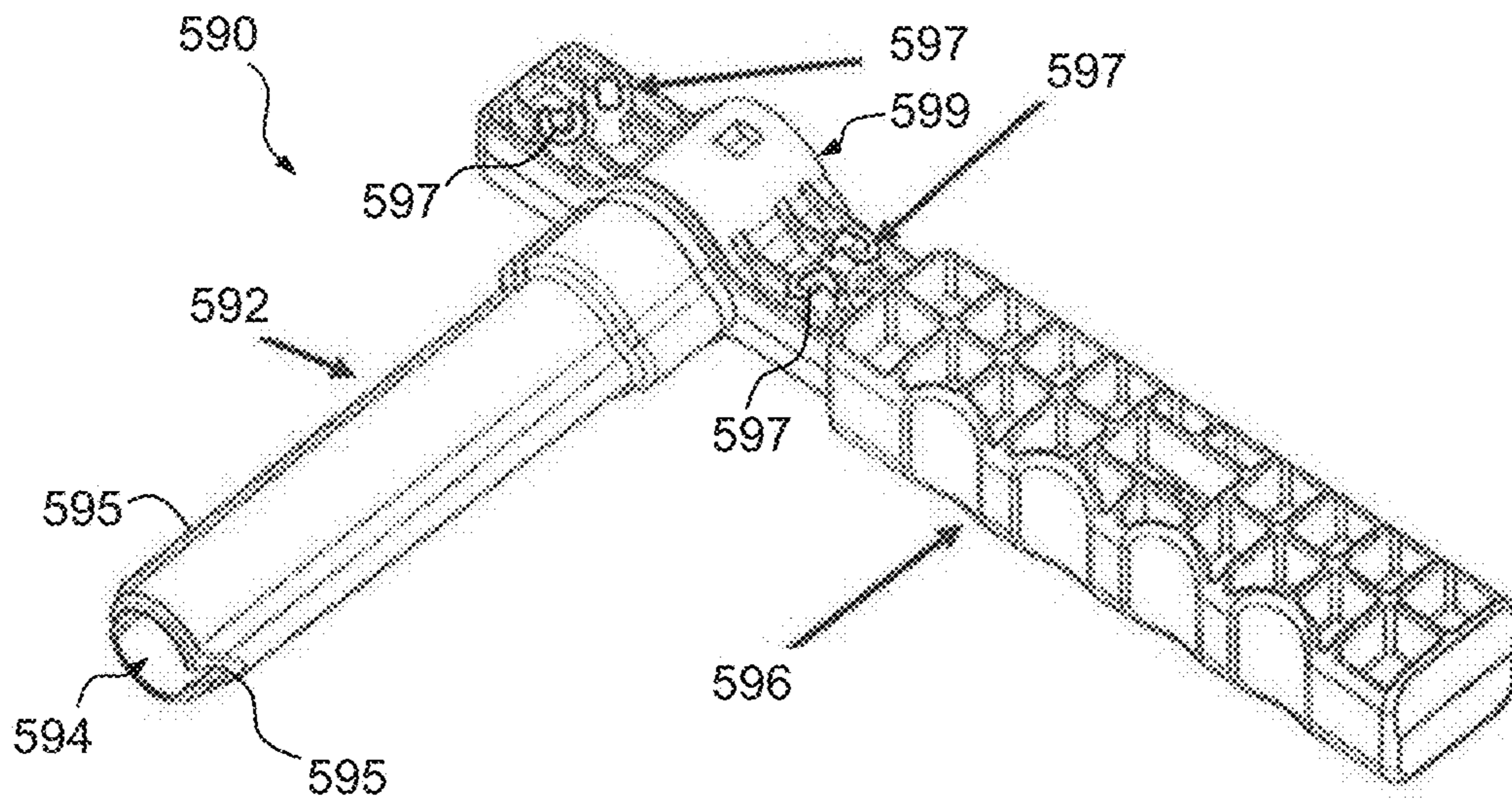


FIG. 17G

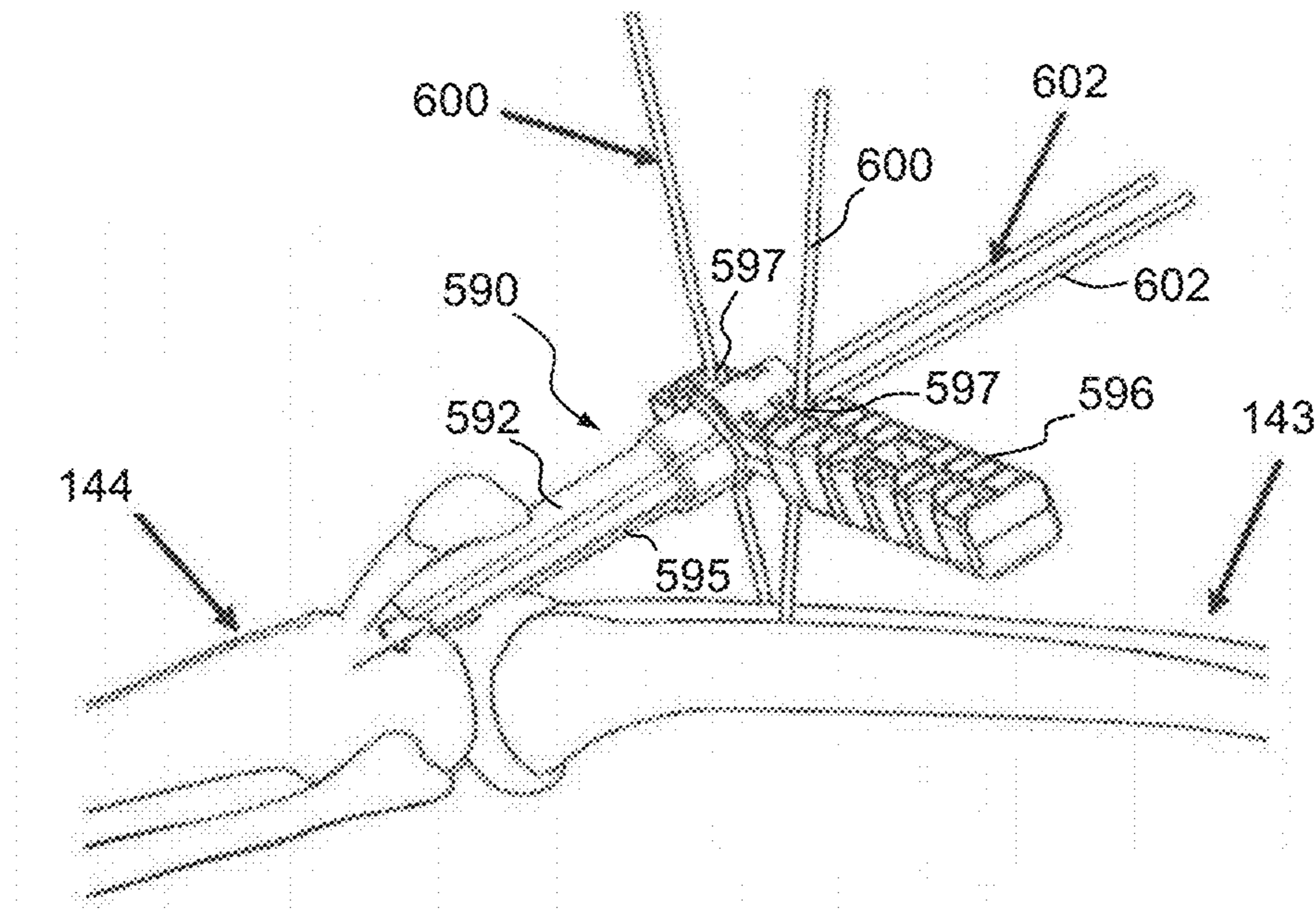


FIG. 17H

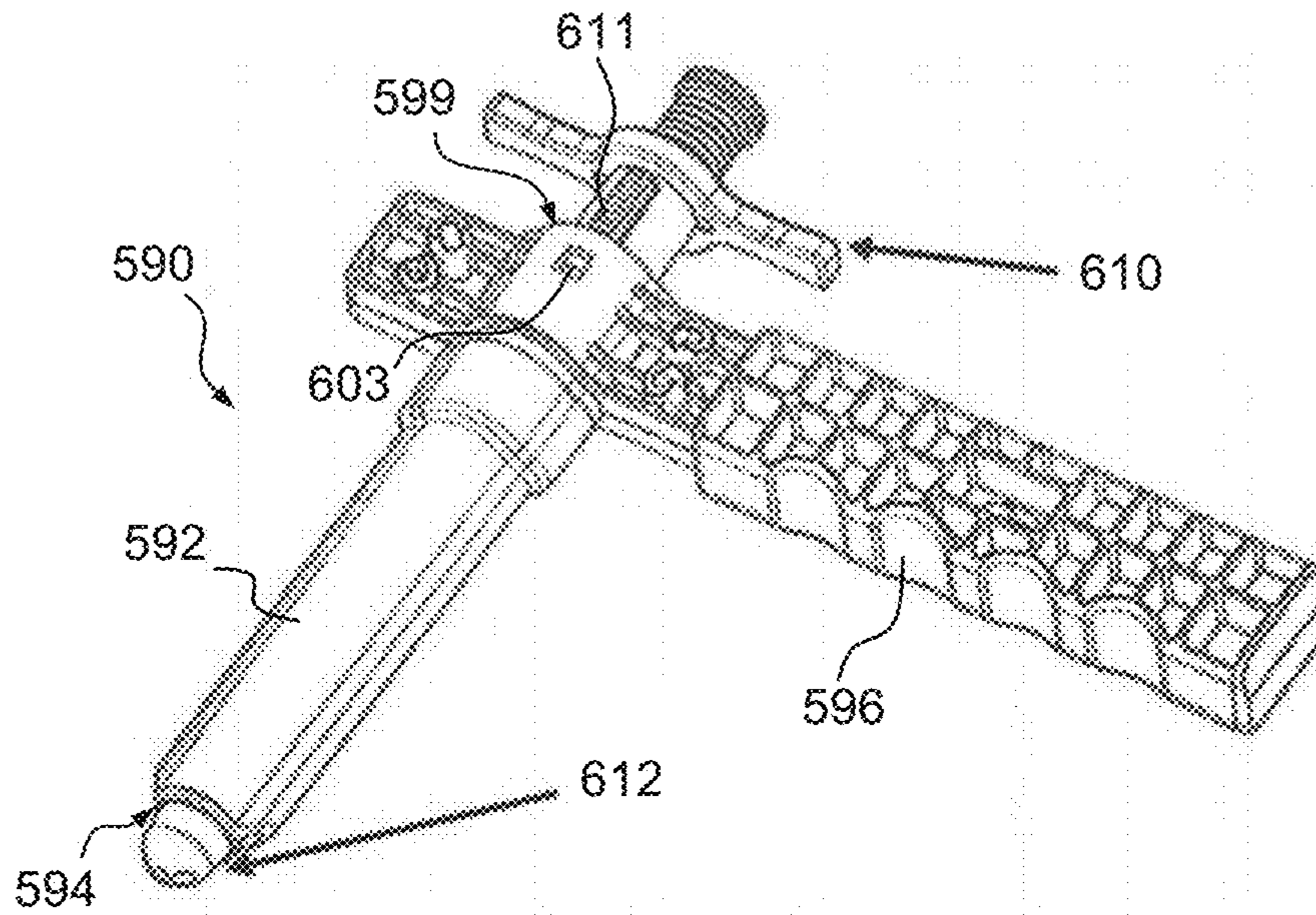


FIG. 17I

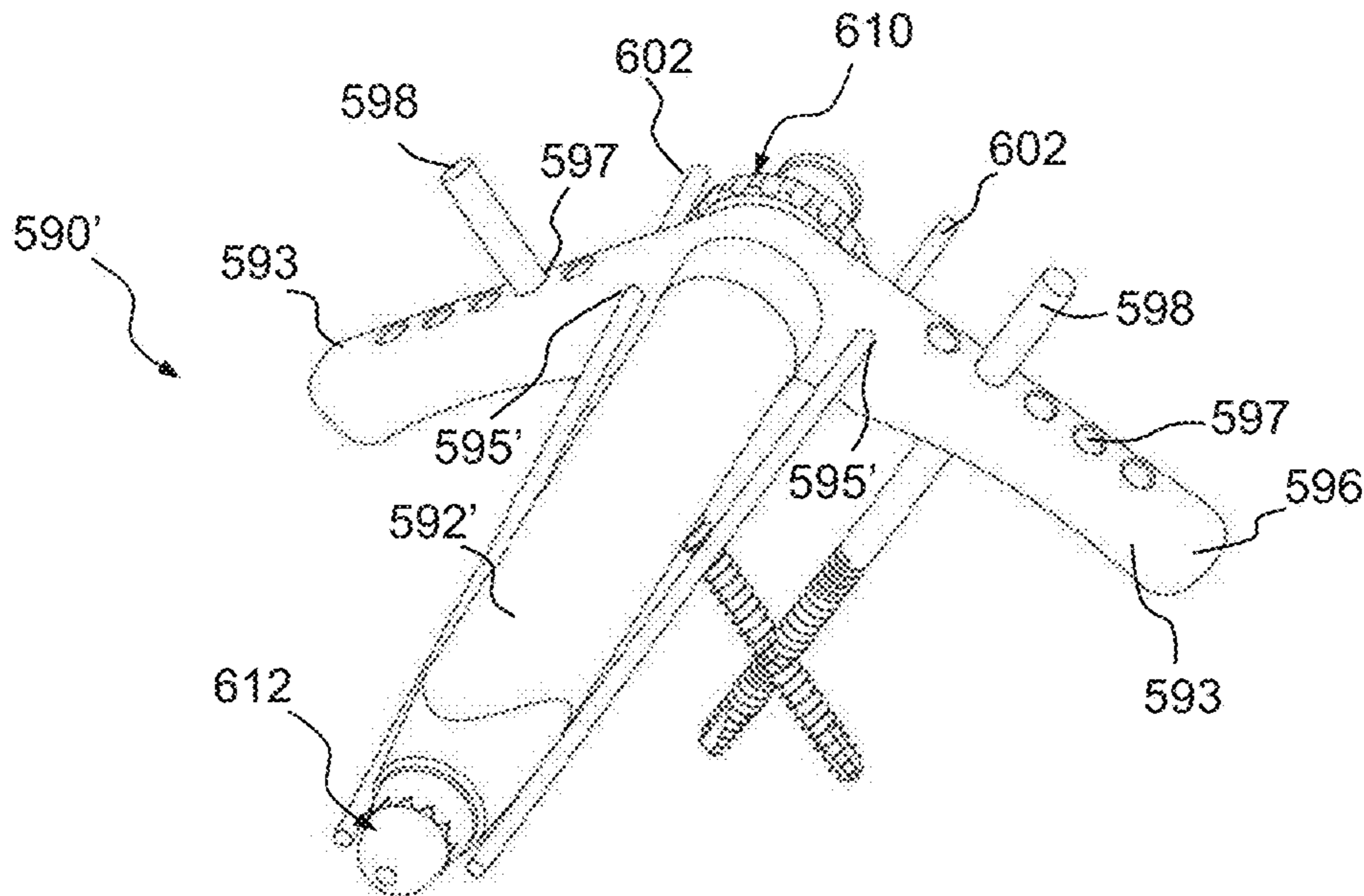


FIG. 17J

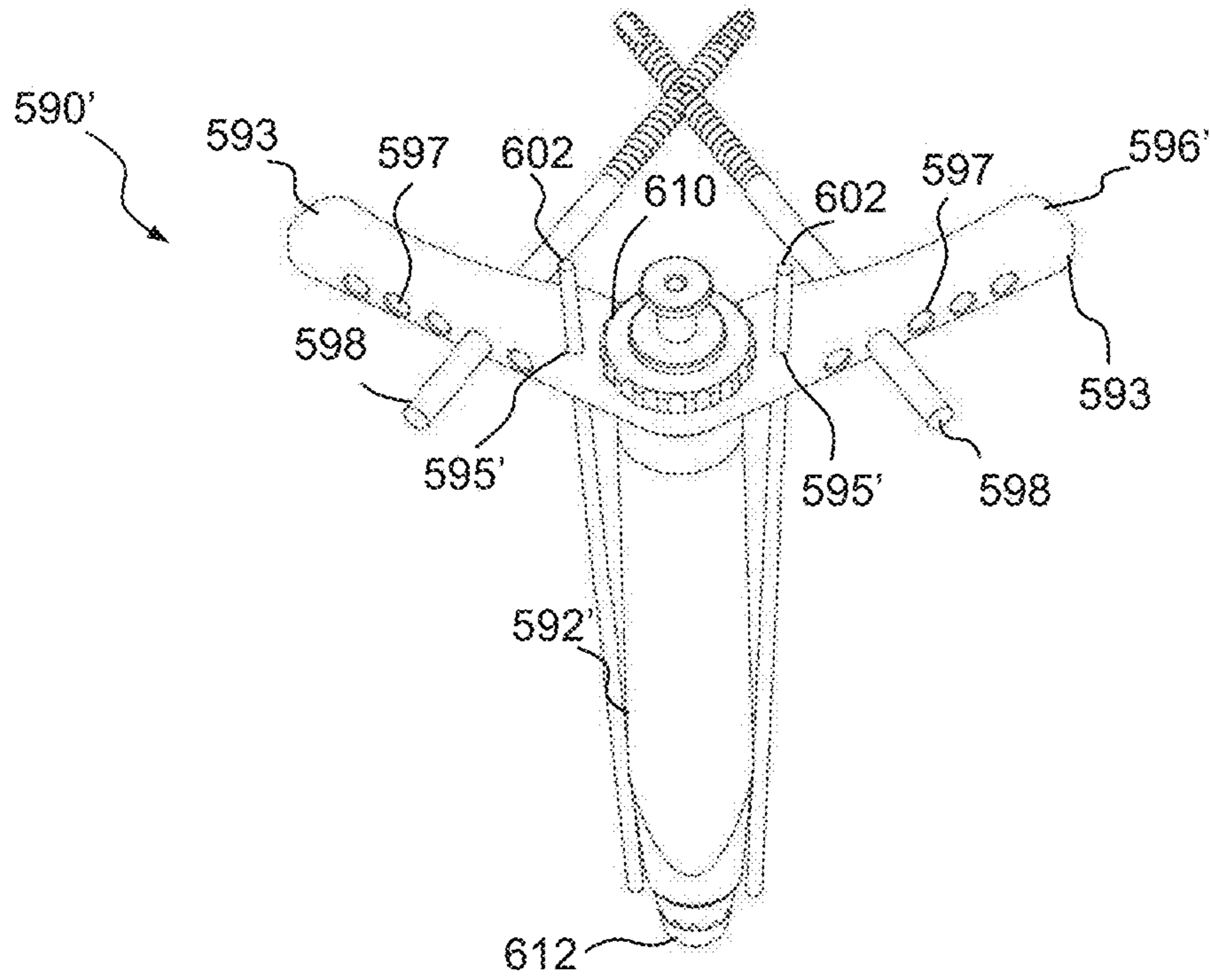


FIG. 17K

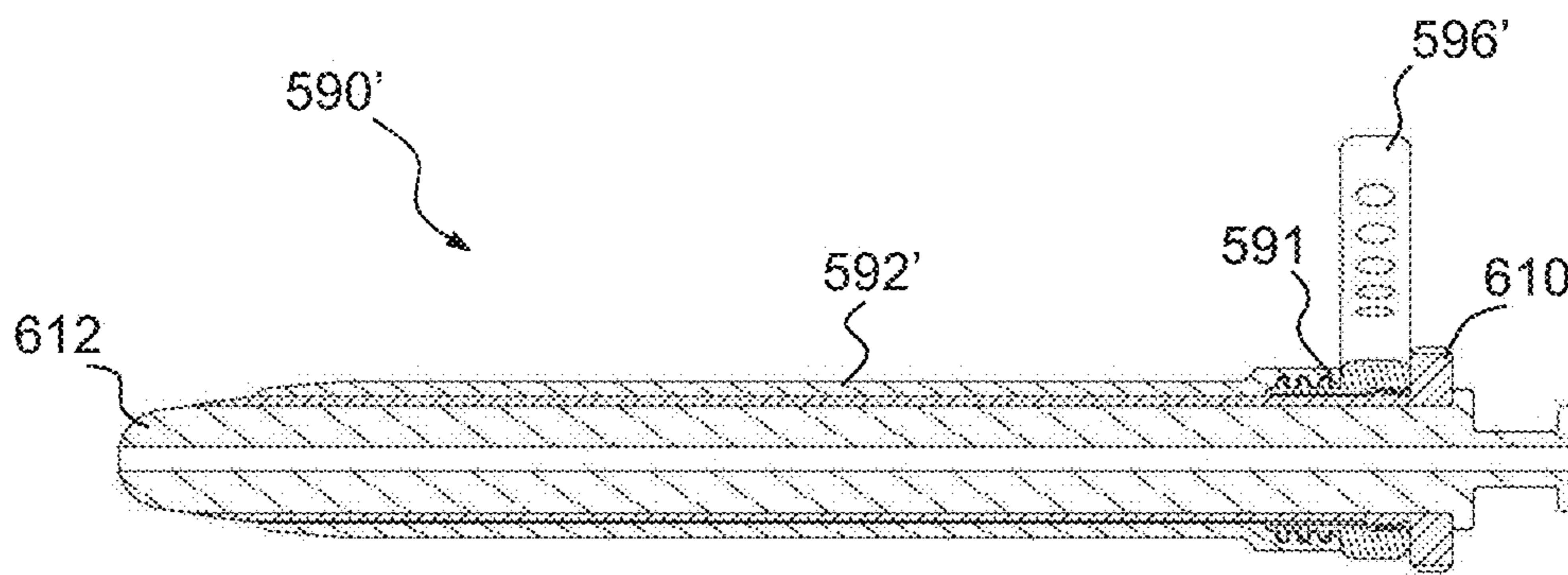


FIG. 17L

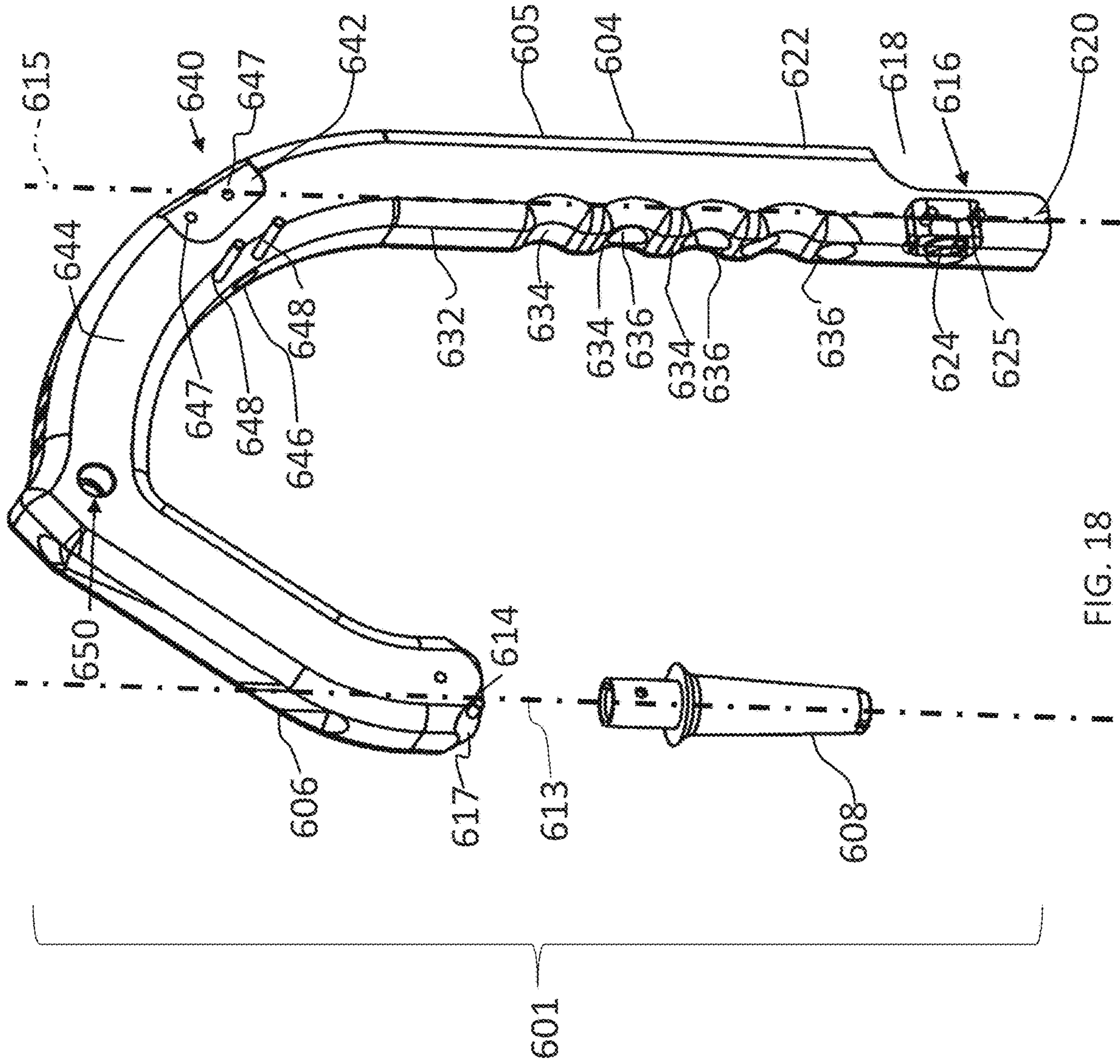


FIG. 18

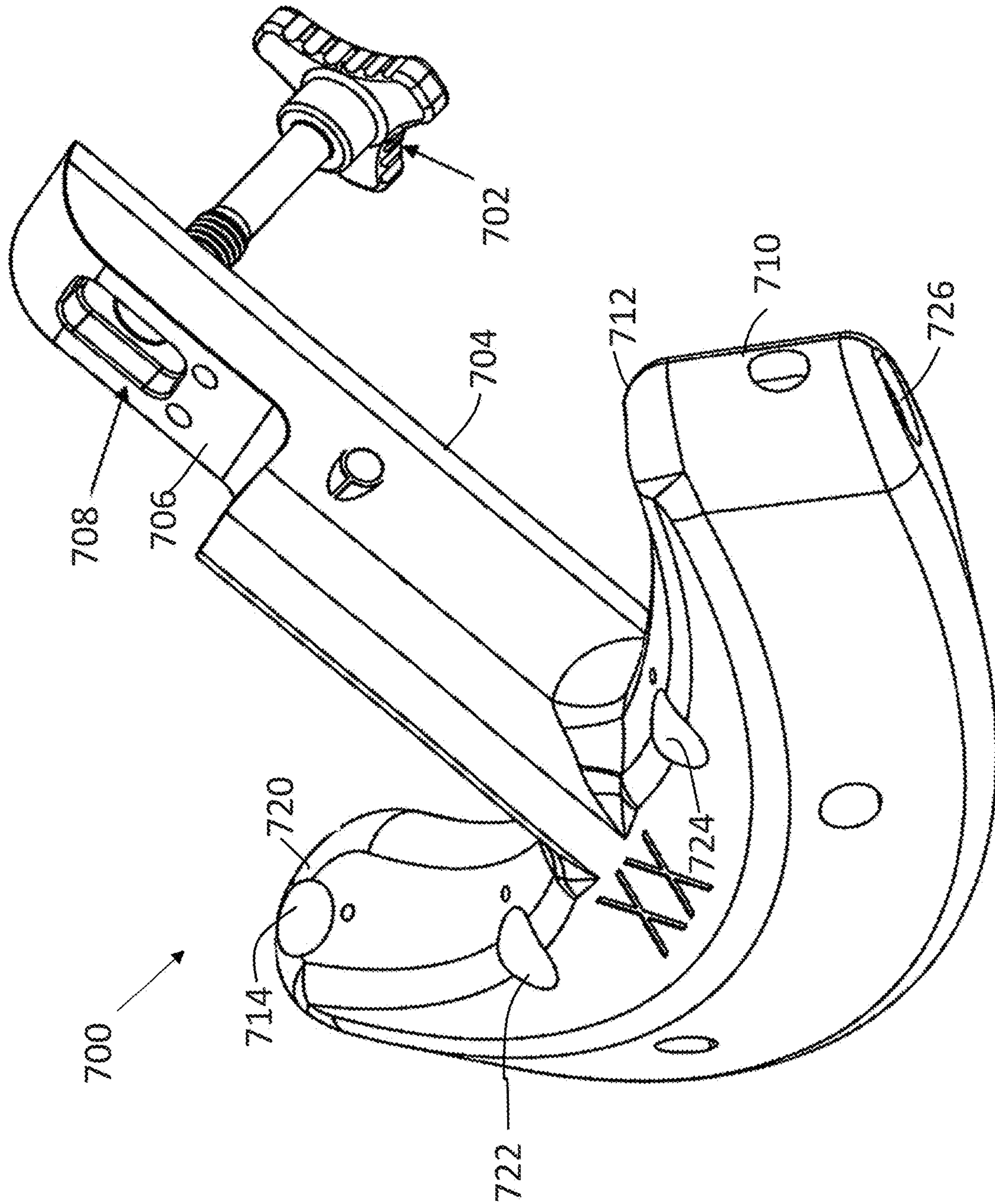


FIG. 19

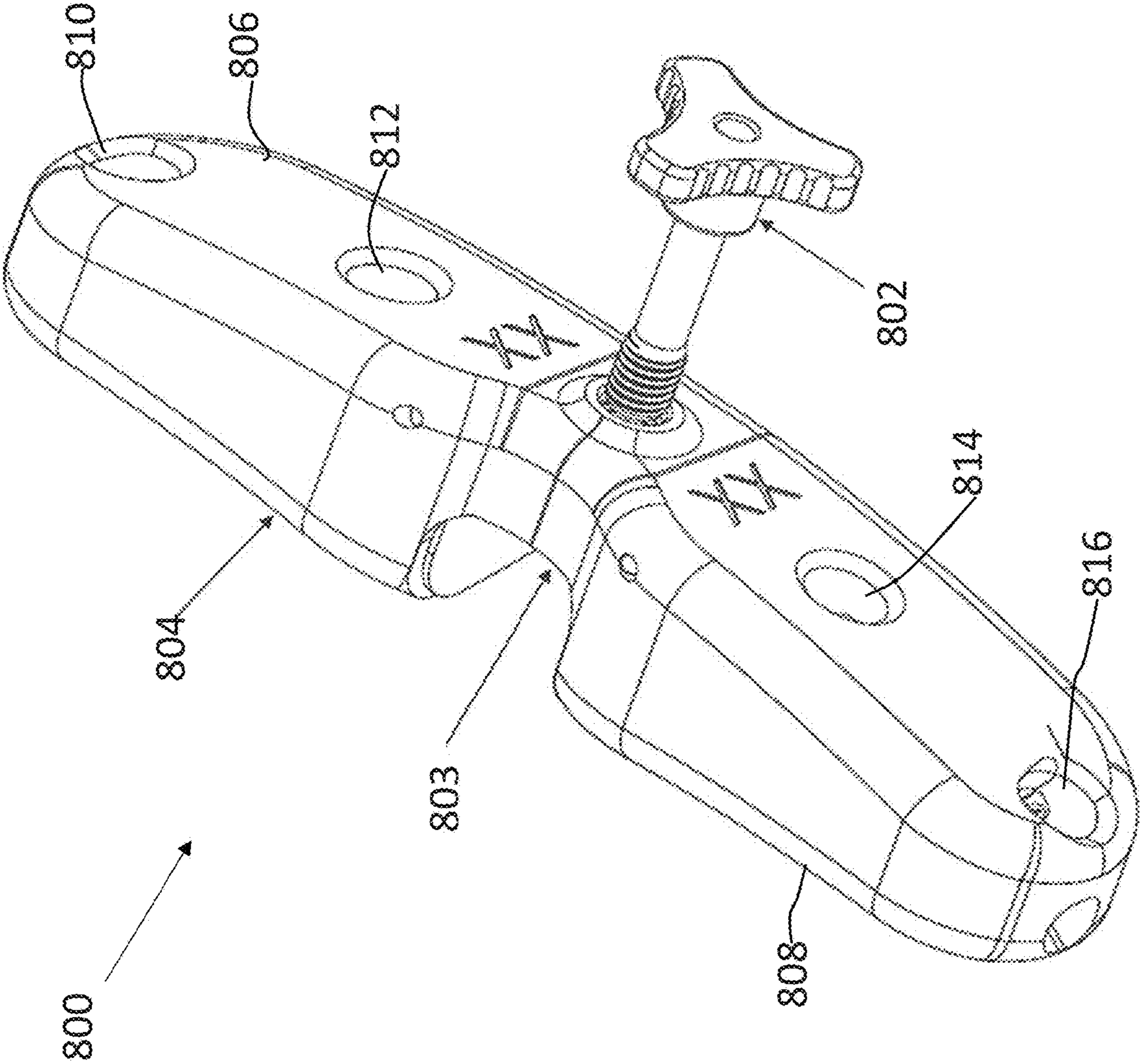


FIG. 20

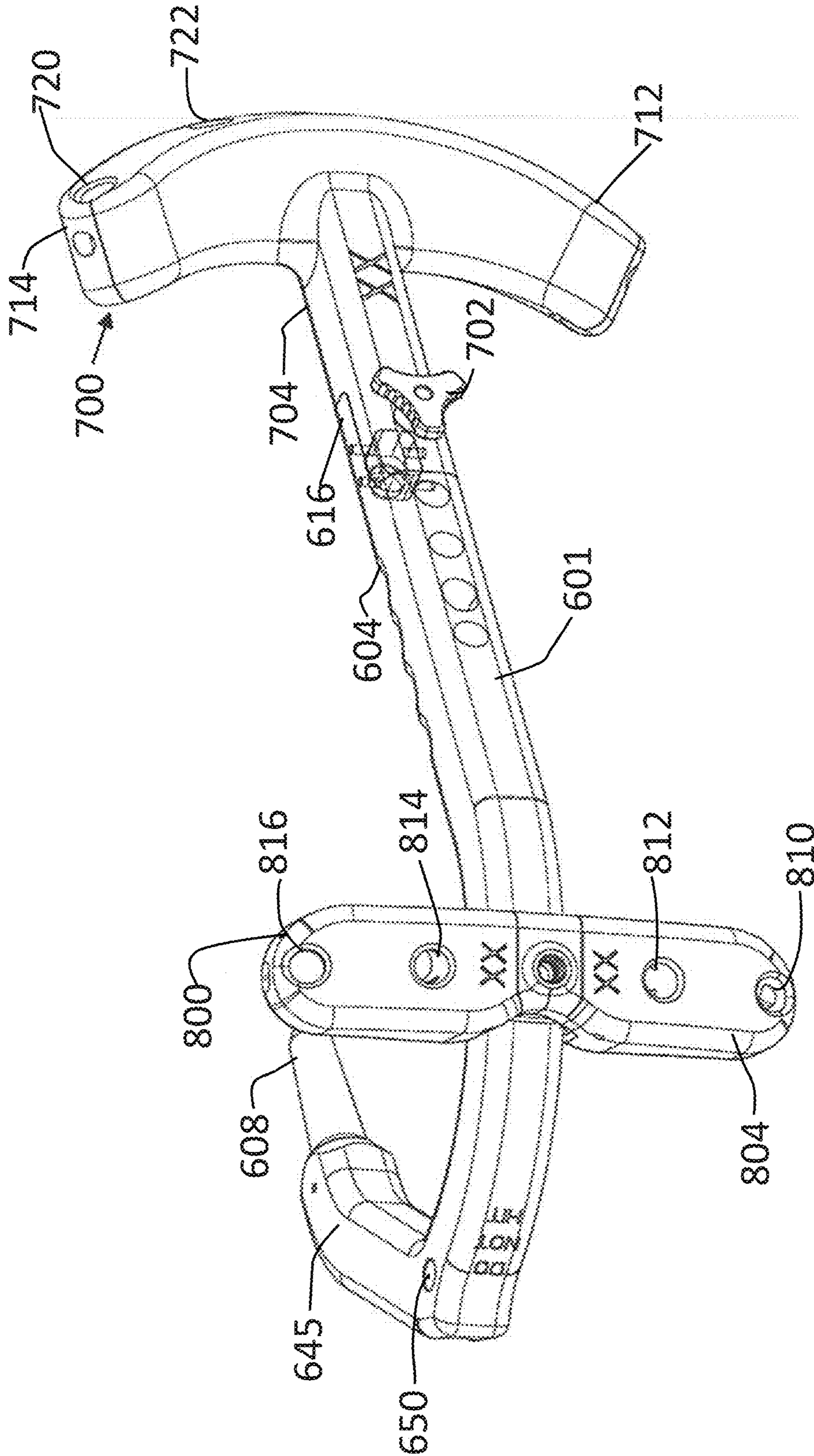


FIG. 21

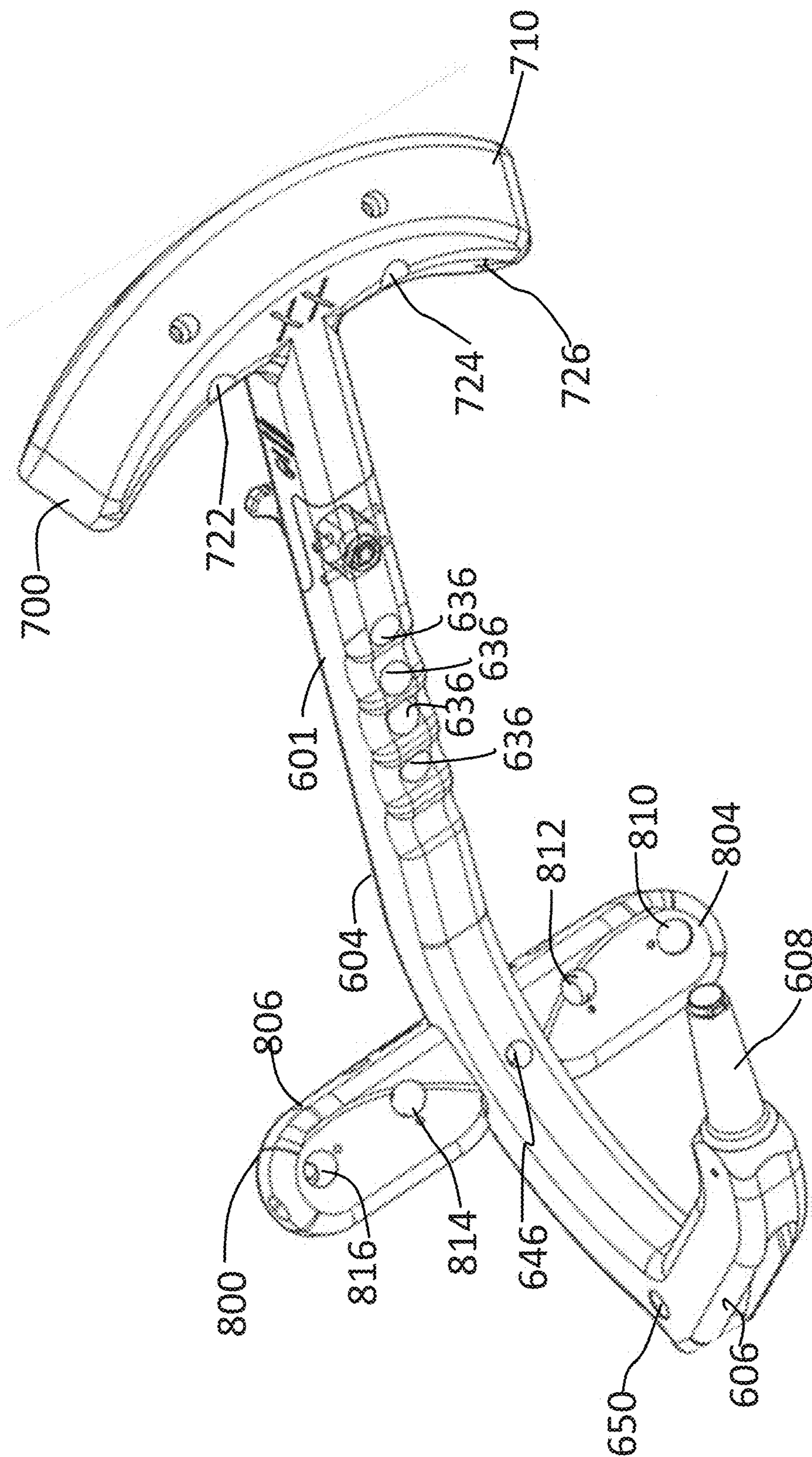


FIG. 22

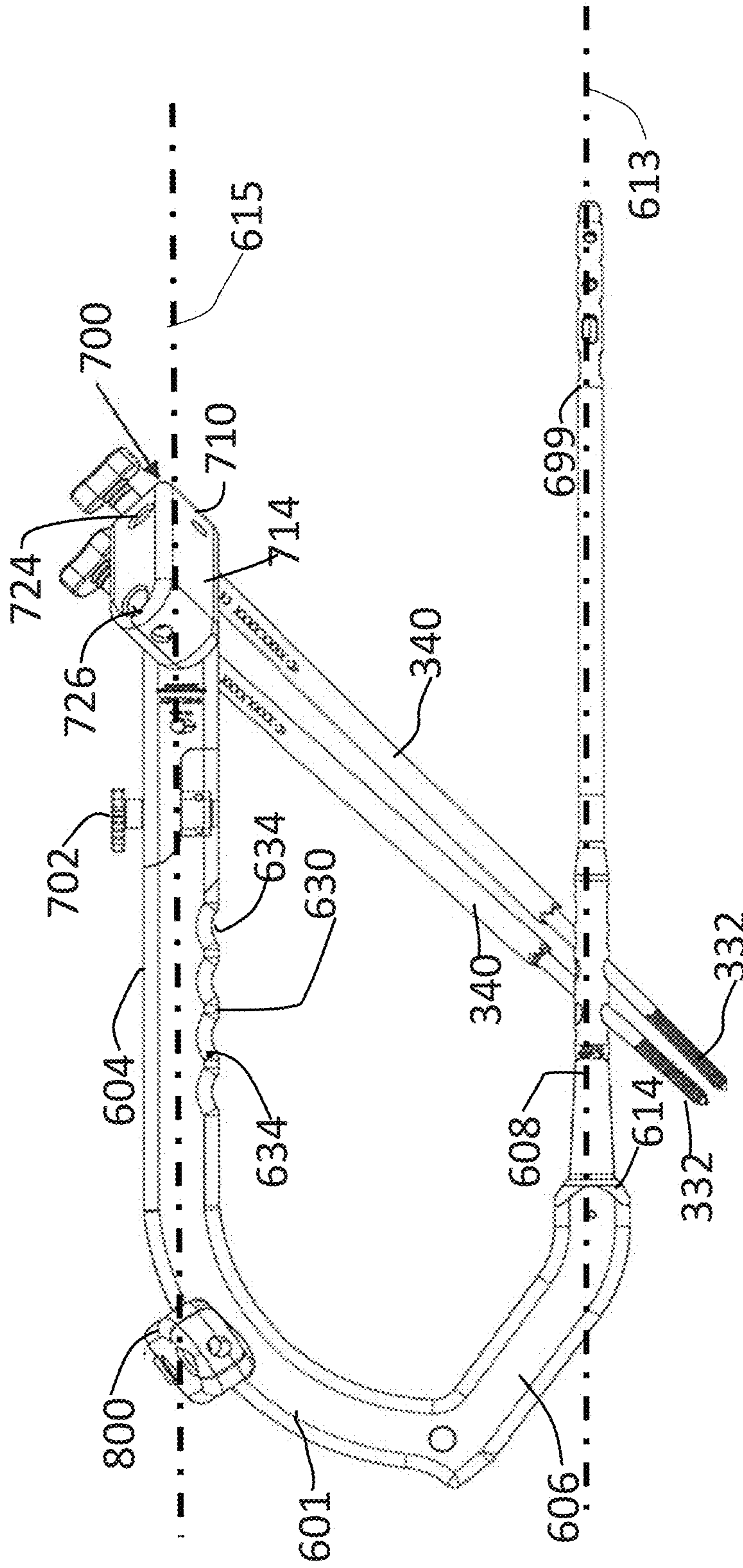


FIG. 23

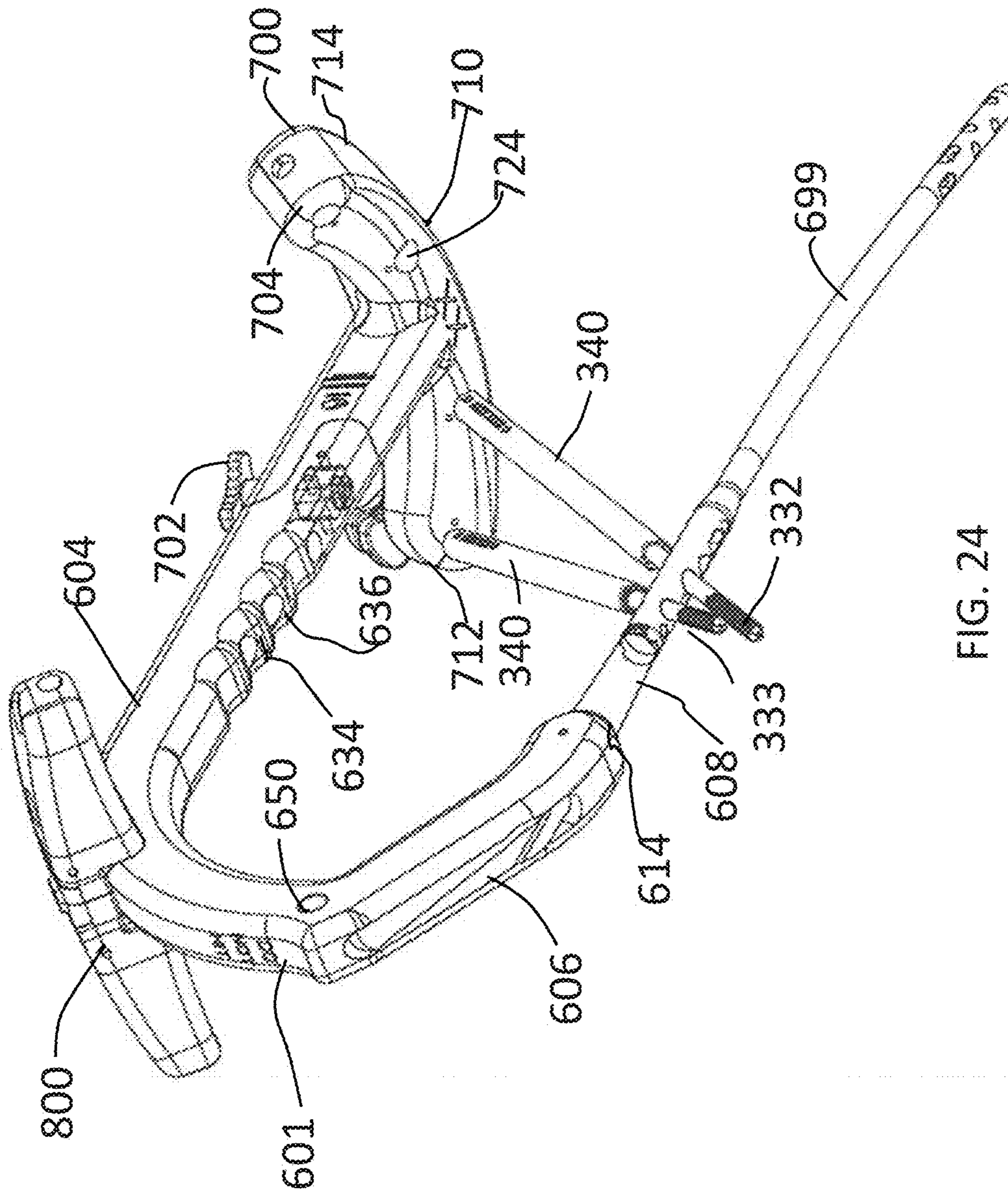


FIG. 24

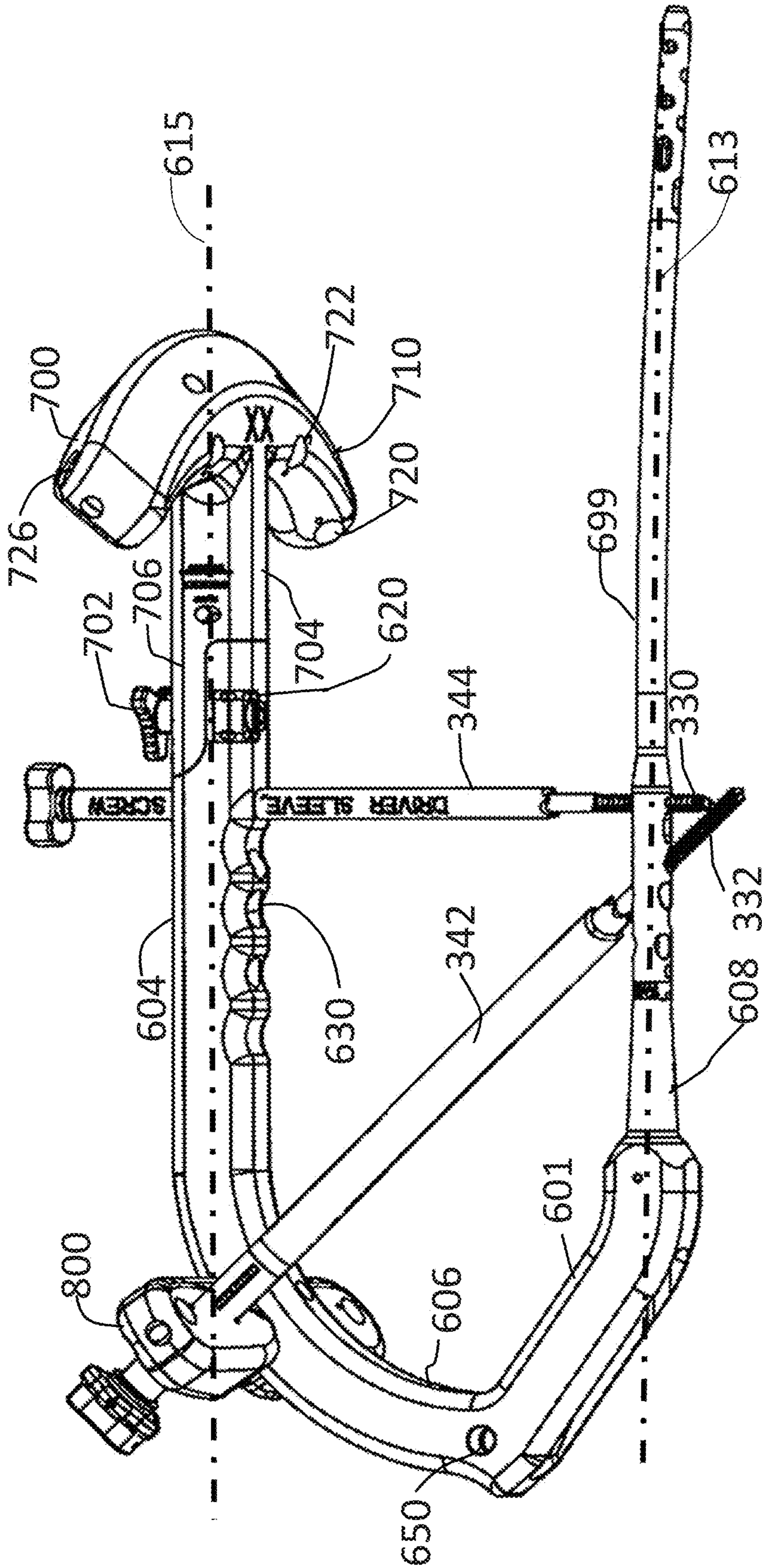


FIG. 26

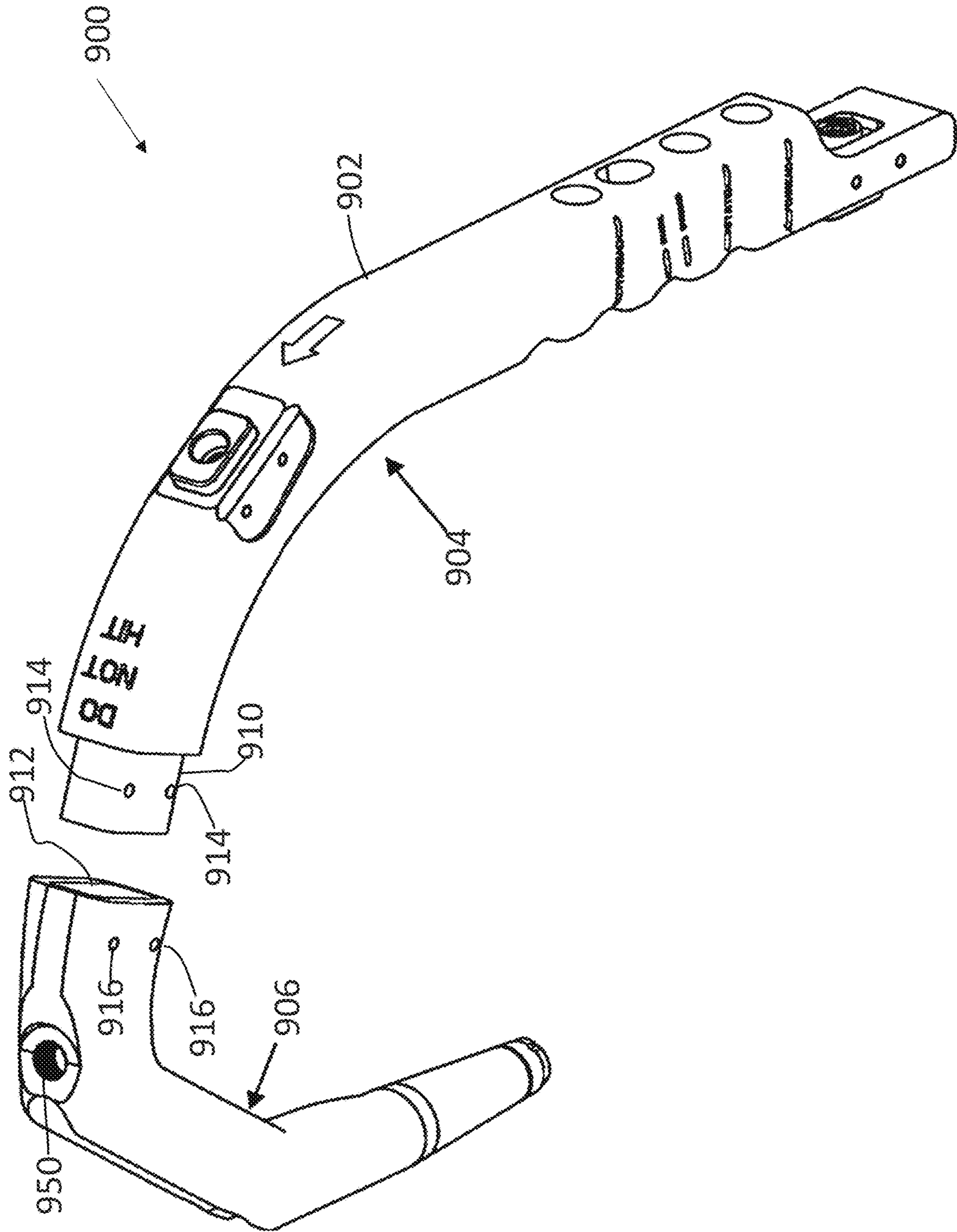


FIG. 27

SYSTEMS AND METHODS FOR INTRAMEDULLARY NAIL IMPLANTATION

CROSS REFERENCE TO RELATED APPLICATIONS

This application is a continuation-in-part of U.S. application Ser. No. 15/441,457, filed on Feb. 24, 2017, which is a continuation-in-part of U.S. application Ser. No. 15/423,773, filed Feb. 3, 2017, which is a continuation-in-part of U.S. application Ser. No. 15/272,850, filed on Sep. 22, 2016, the contents of which are incorporated herein by reference in their entireties for all purposes.

TECHNICAL FIELD

The present technology is generally related to intramedullary nail implantation for treatment of bone fractures. In particular, several embodiments are directed to systems and methods for implanting an intramedullary nail for immobilizing bone fractures.

BACKGROUND

The significant long bones of the extremities are the humerus, radius and ulna of the upper extremity and the femur and tibia of the lower extremity. Following an injury to the long bone, and in particular, injuries resulting in one or more fractures of the long bone, one or more fixation devices may be used to immobilize the fracture fragments and stabilize the long bone. Bone fractures can be treated with screws or other fixation devices inserted into or through the bone to stabilize it once the fractured portions have been brought into proper alignment. Femoral neck fixation, for example, can be used to treat hip fractures by inserting an intramedullary nail into the medullary cavity of the fractured femur followed by insertion of a fixation screw into the femoral neck/head at an angle relative to the intramedullary nail. Similarly, other long bone fractures can be treated by inserting an intramedullary nail into the intramedullary canal of the bone and providing the appropriate proximal and/or distal fixation. Traditional intramedullary devices may suffer from a number of disadvantages, however. For example, they may be susceptible to implant failure and difficulty in alignment of the fixation screw with respect to the intramedullary nail. Accordingly, there is a need for improved systems and methods for intramedullary nail implantation.

SUMMARY

Intramedullary nails, systems, insertion tools and assemblies, and method of treatment are provided. The intramedullary nails may be suitable for implanting within a medullary canal of a fractured long bone and subsequently providing proximal fixation and/or distal fixation, for example, with one or more anchors, fasteners, fixation screws, or the like. Suitable long bones may include the humerus, radius, ulna, femur, tibia, or the like. Although generally described with reference to the femur and tibia, it will be appreciated that the intramedullary nail and system may be adapted for use with any long bone.

According to one aspect, an intramedullary nail is provided. The intramedullary nail may comprise a generally elongate body extending from a first, distal end to a second, proximal end. The distal end may include one or more openings configured to receive one or more bone anchors or fasteners that extend transversely through the distal end

intramedullary nail, and thereby configured to secure the distal end of the nail. The proximal end may also include one or more openings configured to receive one or more bone anchors or fasteners that extend transversely through the proximal end of the intramedullary nail, and thereby configured to secure the proximal end of the nail.

In one aspect, a system for inserting an intramedullary nail into a bone is provided. The system includes an intramedullary nail with an opening or aperture formed therein. An insertion tool can temporarily engage with an end of the intramedullary nail during implantation, and release from the nail once the procedure is complete. A receiving feature for a guide sheath (e.g., a hole, recess, etc.) is disposed in the handle portion and can receive a guide sheath therethrough. The receiving feature defines an axis such that, when the intramedullary nail is coupled to the coupling portion, a guide sheath inserted through the receiving feature substantially aligns with the aperture in the intramedullary nail. A first retention member is disposed in the insertion tool adjacent to the guide sheath receiving feature. The first retention member can interact with a second retention member on the guide sheath to form a ratchet-like mechanism that restrict movement of the guide sheath with respect to the receiving feature. A retention release mechanism can be located on a lower portion (e.g., a bottom surface) of the insertion tool. A guide wire receptacle (e.g., a hole, recess, etc.) can receive a guide wire therethrough and is positioned such that, when the intramedullary nail is coupled to the coupling portion, a guide wire inserted through the receiving feature runs along an axis adjacent to the side surface of the intramedullary nail.

In another aspect, a method for inserting an intramedullary nail into a patient is provided. The method includes inserting a nail into a medullary canal of a patient along a first axis. For insertion, the nail is coupled at its proximal end to an insertion tool. A guide wire is inserted through a guide wire hole in the insertion tool along a second axis such that the guide wire runs nearby or adjacent to a side surface of the nail. A screw or other bone fixation device is inserted through a receptacle (e.g., a hole, recess, or other suitable structure) formed in the insertion tool such that the screw passes through an aperture formed in the nail.

In accordance with another aspect, an implant is provided. The implant includes an intramedullary nail that is elongated along a first axis. First and second openings or apertures are disposed in a proximal portion of the nail. The first aperture defines a second axis transverse to the first axis, and the second aperture defines a third axis transverse to the first axis. The third axis intersects with the second axis at a point spaced apart from the nail. In some embodiments, the first screw can be inserted through the first aperture along the second axis and a second screw can be inserted through the second aperture along the third axis. The second screw can be at least partially inserted through a slot in the first screw such that the two screws interlock. The second screw can be shorter than the first screw but long enough that at least a threaded distal tip extends beyond the slot in the first screw to provide some purchase in the bone.

In accordance with another aspect, an implant is provided. The implant includes an intramedullary nail having a body elongated along a first axis. The body has a proximal portion and a distal portion. A first aperture is formed in the proximal portion and defines a second axis transverse to the first axis at a first angle. A second aperture is formed in the proximal portion and defines a third axis transverse to the first axis at

a second angle. The third axis intersects with the second axis at the first axis and the first and second angles are complementary angles.

In accordance with another aspect, an intramedullary system configured to stabilize bone is provided. The system comprises an intramedullary nail and one or more headless fasteners or screws. The headless fastener extends from a first end to a second end. The headless fastener has a shaft configured to be positioned through the first aperture or the second aperture in the intramedullary nail and the first end (e.g., in some instances a threaded head) of the headless fastener is configured to be positioned against or within the bone. Unlike traditional headed screws which sometimes cause pain or irritation to patients, one or more headless screws or fasteners can be used when securing the distal and/or proximal ends of the intramedullary nail, thereby resulting in a system with superior patient outcomes.

In accordance with another aspect, a system for inserting an intramedullary nail into a bone is provided. The system includes an intramedullary nail having a proximal end, a distal end, at least one side surface extending between the proximal end and the distal end, and an aperture through the intramedullary nail. An insertion tool includes a handle portion, a coupling portion and an aiming guide. The handle portion defines a first connection assembly. The coupling portion extends from the handle portion and is configured to removably couple to the proximal end of the intramedullary nail. The aiming guide has a body with at least one support block and a second connection assembly. The first and second connection assemblies are configured to releasably interconnect the handle portion and the aiming guide. The at least one guide block defines a guide sheath hole configured to receive a guide sheath therethrough. The guide sheath hole is positioned such that, when the intramedullary nail is coupled to the coupling portion, the guide sheath hole substantially aligns with the aperture in the intramedullary nail.

In accordance with another aspect, a connection assembly for interconnecting an intramedullary nail and insertion tool is provided. The intramedullary nail extends between a proximal end and a distal end and has a circumferential slot defined within the proximal end. The insertion tool includes an aiming arm with a hole defined therein. The connection assembly includes an alignment tip having a hollow body extending from a proximal end to a distal end with the proximal end configured to be securely connected within the hole of the aiming arm. An expanding collet has a hollow body extending from a collet proximal end to a collet distal end. The collet distal end has a radially outwardly extending collar and internal threads. The collet body defines axial slots extending from the distal end of the body which allow the distal end of the body to compress radially inwardly, thereby allowing the collar to pass through the alignment tip through passage and into the circumferential slot of the intramedullary nail. A connecting bolt has a threaded shaft and extends through the hole in the aiming arm and into threaded engagement with the internal threads of the expanding collet such that the collar is pushed outwardly to its major diameter.

Also provided are kits including intramedullary nails of varying shapes and sizes, bone anchors, fasteners, insertion tools, and components for installing the same.

According to still another aspect, an aiming guide for inserting an intramedullary nail into a bone includes a generally arcuate or "J-shaped" body having an elongate proximal handle portion and a generally arcuate distal implant alignment tip connector portion having a distal

implant alignment tip extending parallel to a longitudinal axis of the proximal handle portion. The handle portion includes a first attachment location for releasably attaching a first module and the distal implant alignment tip portion includes a second attachment location for releasably attaching a second module.

In accordance with yet another aspect, an aiming guide assembly includes a generally "J-shaped" aiming guide having an elongate proximal handle portion and a generally arcuate distal implant alignment tip connector portion. The distal implant alignment tip connector portion has a distal implant alignment tip extending along a tip axis parallel to a longitudinal axis of the proximal handle portion. A recon module is releasably attached to a proximal end of the proximal handle portion and an oblique module is releasably attached to the distal implant alignment tip portion.

According to another aspect, an aiming guide assembly includes an aiming guide having an elongate proximal handle portion and a generally arcuate distal implant alignment tip connector portion. The aiming guide has an elongate proximal handle portion and a generally arcuate distal implant alignment tip connector portion. The distal implant alignment tip connector portion has a distal implant alignment tip extending along a tip axis parallel to a longitudinal axis of the proximal handle portion. A first attachment is releasably attached to a proximal end of the proximal handle portion and a second attachment is releasably attached to the distal implant alignment tip portion.

BRIEF DESCRIPTION OF THE DRAWINGS

A more complete understanding of the present invention, and the attendant advantages and features thereof, will be more readily understood by reference to the following detailed description when considered in conjunction with the accompanying drawings wherein:

FIGS. 1A and 1B illustrate a system for implanting an intramedullary nail.

FIGS. 2A-2C illustrate various views of an insertion handle of the system shown in FIGS. 1A and 1B.

FIGS. 3A-3F illustrate steps of implanting an intramedullary nail into a fractured femur.

FIGS. 4A-4D illustrate various views of an intramedullary nail and a first fixation device.

FIGS. 5A-5D illustrate various views of the first fixation device inserted through the intramedullary nail.

FIGS. 6A-6D illustrate various views of a second fixation device and the intramedullary nail with the first fixation device inserted therein.

FIGS. 7A-7D illustrate various views of the second anchor inserted through the intramedullary nail and the first fixation device.

FIGS. 8A-8C illustrate steps of implanting an intramedullary nail with interlocking fixation devices into a fractured femur.

FIGS. 9A-9N illustrate various views of an illustrative intramedullary nail.

FIGS. 10A-10C illustrate steps of a method of calculating the radius of curvature of a femoral nail.

FIGS. 11A-11E illustrate various views of an insertion tool and intramedullary nail connection assembly.

FIGS. 12A-12K illustrate various views of a locking screw and corresponding torque driver head.

FIGS. 13A-13F illustrate various views of a headless locking screw.

5

FIGS. 14A-14C illustrate various views of a nail including a locking screw opening with a 2 start thread configuration.

FIGS. 15A-15C illustrate various views of a screw compression washer.

FIGS. 16A-16H illustrate various views of illustrative tibial nails.

FIGS. 17A-17L illustrate various views of illustrative insertion systems.

FIG. 18 is a perspective view of a femoral nail aiming guide according to an exemplary embodiment.

FIG. 19 is a perspective view of a recon module for releasable connection to the aiming guide of FIG. 18.

FIG. 20 is a perspective view of an oblique module for releasable connection to the aiming guide of FIG. 18.

FIG. 21 is a perspective view of an aiming guide assembly including the recon module of FIG. 19 and the oblique module of FIG. 20, both connected to the aiming guide of FIG. 18.

FIG. 22 is a reverse perspective view of the aiming guide assembly of FIG. 21.

FIG. 23 is a perspective view of the aiming guide assembly of FIG. 21 with two screws inserted through the recon module and into a femoral nail.

FIG. 24 is a reverse perspective view of the aiming guide assembly of FIG. 23 with two screws inserted through the recon module and into the femoral nail.

FIG. 25 is a perspective view of the aiming guide assembly of FIG. 21 with one screw inserted through the recon module and one screw inserted through the oblique module and into a femoral nail.

FIG. 26 is a perspective view of the aiming guide assembly of FIG. 21 with one screw inserted through the aiming guide and one screw inserted through the oblique module and into a femoral nail.

FIG. 27 is a perspective view of a femoral nail aiming guide according to another exemplary embodiment.

DETAILED DESCRIPTION

In the drawings, like numerals indicate like elements throughout. Certain terminology is used herein for convenience only and is not to be taken as a limitation on the present device. The terminology includes the words specifically mentioned, derivatives thereof and words of similar import. The embodiments illustrated below are not intended to be exhaustive or to limit the device to the precise form disclosed. These embodiments are chosen and described to best explain the principle of the device and its application and practical use and to enable others skilled in the art to best utilize the device.

Reference herein to “one embodiment” or “an embodiment” means that a particular feature, structure, or characteristic described in connection with the embodiment can be included in at least one embodiment of the device. The appearances of the phrase “in one embodiment” in various places in the specification are not necessarily all referring to the same embodiment, nor are separate or alternative embodiments necessarily mutually exclusive of other embodiments. The same applies to the term “implementation.”

As used in this application, the word “exemplary” is used herein to mean serving as an example, instance, or illustration. Any aspect or design described herein as “exemplary” is not necessarily to be construed as preferred or advanta-

6

geous over other aspects or designs. Rather, use of the word exemplary is intended to present concepts in a concrete fashion.

Intramedullary nails, systems, insertion tools, and method of treatment are provided. The intramedullary nails may be suitable for implantation within the intramedullary canal of a fractured long bone and subsequently providing proximal fixation and/or distal fixation, for example, with one or more anchors, fasteners, fixation screws, or the like. Suitable long bones may include the humerus, radius, ulna, femur, tibia, or the like. Although further described with reference to hip fractures of the femur or fractures of the tibia, it will be appreciated that the intramedullary nail and system may be adapted for use with any long bone.

In conventional hip fracture fixation techniques, there are four main failure modes: axial cutout, cephalad cutout, proximal fragment rotation, and nonunion. “Cutout” is the term for hip screw subsidence into the articular surface of the hip. Cutout can occur in either a cephalad (toward the head) or axial direction (along the axis of the hip screw). Axial cutout is the result of an implant with a small axial profile that provides little resistance to axial translation. Axial cutout can be addressed by the “controlled collapse” features on certain modern hip fracture nails; the hip screw is allowed to translate through the nail, even after the set screw is locked in place. Cephalad cutout is the radial translation of the nail which is the result of a narrow implant that “windshield wipers” through the weak cancellous bone in the hip. Proximal fragment rotation is the result of a circular profile hip screw that acts as a fulcrum to the proximal hip fragment. Fracture nonunion is the result of biologic or mechanical factors that are incompatible with the bone healing process. Biologic factors of the patient are not controllable by the implant. Mechanical factors are those that typically allow fixation that is too rigid or too flexible. Nonunion is usually the precursor to one of the other three failure modes. Occasionally, nonunion will cause the nail to break in fatigue before the bone fails.

The intramedullary nails and systems described herein may address one or more of these failure modes. In some embodiment, the intramedullary nail includes proximal and distal locking, for example, to prevent cutout. In other embodiments, the intramedullary nail may include proximal locking including two interlocking fixation devices (e.g., screws), for example, by providing converging and diverging purchase, along with bony fixation in the calcar of the femur, which is the strongest portion of the hip bone. Accordingly, the risk of failure due to cutout and/or rotation can be reduced.

Additionally, some intramedullary nail implantation systems fail to adequately address the problems of fragment rotation during implantation. Rotation occurs when fragments of the bone rotate about the axis of the screw during the implantation procedure. Conventional anti-rotation technologies require the use of additional instruments or are limited to a single wire placement. In some embodiments, an insertion tool is directly coupled to the intramedullary nail and additional instruments are not needed for the placement of an anti-rotation guide wire and allow the user to place one or more guide wires anterior and/or posterior to the nail. These guide wires can be positioned to prevent the distal fragments of the femoral head and neck from rotating about the axis of the anchor during the procedure.

Some systems may be susceptible to backout during the implantation procedure. Backout occurs when the guide sheath used to insert the screw through the intramedullary nail moves proximally away from the bone. Conventional

systems either have no features to prevent backout or else provide backout prevention measures that obstruct the normal positioning of the hands during the procedure, resulting in the risk of releasing the guide sheaths and dropping them to the floor. Ratchets on the insertion tool may have the release button facing towards the grip portion on the insertion tool and may present the danger of the user's hand slipping and inadvertently pressing the button. Accidentally pressing the button could result in releasing the sheath and causing the sheath to fall on the floor. In some embodiments, a backout prevention system (e.g., a ratchet system) may be disposed on the lower end of the insertion tool, which allows a user to have a hand placed on the grip of the insertion tool without the risk of inadvertently pressing the ratchet release button.

Further specific details of several embodiments of the present technology are described below with reference to FIGS. 1A-8C. Although many of the embodiments are described below with respect to devices, systems, and methods for implantation of intramedullary nails, other embodiments are within the scope of the present technology. Additionally, other embodiments of the present technology can have different configurations, components, and/or procedures than those described herein. For example, other embodiments can include additional elements and features beyond those described herein, or other embodiments may not include several of the elements and features shown and described herein.

For ease of reference, throughout this disclosure identical reference numbers are used to identify similar or analogous components or features, but the use of the same reference number does not imply that the parts should be construed to be identical. Indeed, in many examples described herein, the identically numbered parts are distinct in structure and/or function.

FIGS. 1A and 3F illustrate one example of an intramedullary nail 109, which may comprise a generally elongate body extending from a first, distal portion or end 110 to a second, proximal portion or end 111. The elongate body may be in the form of an elongate tubular rod configured to extend longitudinally within the intramedullary canal of a fractured bone. The elongate rod may be hollow or may be solid along its length. The elongate body may be substantially straight along a longitudinal axis of the nail 109 or may comprise one or more curves or bends to conform to the anatomical shape of the intramedullary canal. The cross-section of the nail 109, taken at a right angle to a central longitudinal axis of the intramedullary nail 109, may be circular, oval, elliptical, or of any other suitable cross-dimensional shape. The proximal portion 111 may have an enlarged diameter or head portion relative to the distal portion 110 of the nail 109. The enlarged head portion 111 may be sized and configured to be received in the greater trochanter region of the femur. The intramedullary nail 109 may be configured to be positioned in the proximal end of the femur for cephalomedullary fixation. It is envisioned, however, that the intramedullary nail 109 may be configured to be positioned through other approaches and locations (e.g., distal end) depending on the bone (e.g., femur, tibia) and type of fracture.

The distal end 110 may include one or more openings 125 configured to receive one or more bone anchors, fasteners, or distal fixation devices 147 that extend transversely through the distal end 110 of the intramedullary nail 109, and are thereby configured to secure the distal end 110 of the nail 109 within the canal. The distal fixation devices 147 may include a bone screw or anchor configured for distal

locking of the nail 109. The distal fixation device 147 may include traditional polyaxial or fixed angle locking bone screws and anchors known in the art.

The proximal end 111 may also include one or more openings 123 configured to receive one or more bone anchors or fasteners 119 that extend transversely through the proximal end 111 of the intramedullary nail 109, and are thereby configured to secure the proximal end 111 of the nail 109 within the canal. The proximal fixation devices 119 may include a bone screw or anchor configured for proximal locking of the nail 109. The fixation device 119 may be a calcar screw or anchor configured to be aimed at a calcar region of the proximal humerus, which may constitute the best quality bone in the region. The opening 123 and anchor 119 may be angled about 100-150°, 110-140°, or about 120-135° relative to the nail 109 to engage the calcar region of the bone. The calcar screw 119 may have an enlarged diameter relative to the distal screw 147. The proximal fixation device 119 may include traditional polyaxial or fixed angle calcar screws and anchors known in the art. The proximal end 111 may also include additional openings 123, for example, for one or more cross-locking devices (e.g., device 205 described in more detail below).

The intramedullary nail 109 and anchors 119, 147 may be comprised of any suitable biocompatible materials. The intramedullary nail 109 and anchors 119, 147 may be comprised of titanium, cobalt chrome, cobalt-chrome-molybdenum, stainless steel, tungsten carbide, carbon composite, plastic or polymer—such as polyetheretherketone (PEEK), polyethylene, ultra high molecular weight polyethylene (UHMWPE), resorbable polylactic acid (PLA), polyglycolic acid (PGA), combinations or alloys of such materials, or other appropriate biocompatible materials that have sufficient strength to secure and hold bone, while also having sufficient biocompatibility to be implanted into a body.

FIGS. 1A and 1B illustrate perspective and side views, respectively, of one embodiment of a system 101 for implanting an intramedullary nail 109. The system 101 includes an insertion tool 103 that has a coupling portion 105 and a handle portion 107. In some embodiments, the coupling portion 105 and the handle portion 107 can be separate parts that are removably joined together, while in other embodiments the coupling portion 105 and the handle portion 107 can be different regions of a single, integrally formed component. The coupling portion 105 releasably engages or couples to the proximal portion 111 of the nail 109. For example, the free end of the coupling portion 105 can be provided with a snap-fit design to temporarily retain a portion of the intramedullary nail 109 prior to insertion of a fixation device 119 therethrough. However, those skilled in the art will understand that other coupling mechanisms may be employed.

The handle portion 107 may include one or more openings 127, 129 configured to receive one or more guide wires 113, 115. In one embodiment, the system 101 may include first and second guide wires 113, 115 as well as an optional guide sheath 117 through which the fixation device 119 may pass (e.g., the fixation device 119 can be inserted using the driver 121). As illustrated, the first and second guide wires 113, 115 may pass on opposing sides of both the nail 109 and the fixation device 119 (e.g. on posterior and anterior sides). Although the illustrated embodiment shows two guide wires, in other embodiments a single guide wire and corresponding guide wire hole may be used. In still other embodiments, three or more guide wires may be used. Additionally, the position and orientation of the guide wire holes can vary

in different embodiments, for example being disposed more proximally or more distally along the insertion tool, etc.

As illustrated, the insertion tool **103** allows the user to place one or more guide wires **113**, **115**. In one embodiment, the guide wires **113**, **115** are positioned both anterior and posterior to the nail **109**. The guide wires **113**, **115** may be positioned in this manner to prevent the distal fragments of the bone (e.g., distal fragments of the femoral head and neck) from rotating about the axis of the fixation device **119** when the fixation device **119** is advanced through the nail **109** and into the bone during the procedure. The handle portion **107** of the insertion tool **103** may include two guide wire receiving features such as holes **127**, **129** on the opposing sides of the tool **103** that allow guide wires **113**, **115** to pass through the respective holes. The guide wires **113**, **115** are passed through the soft tissue and into the bone to help stabilize the insertion tool **103**. In this configuration, the insertion tool **103** may not require any other instruments to guide the wires **113**, **115** into the patient. The insertion tool **103** can achieve stability by resisting both rotational movement about the axis of the nail **109** as well as axial translation along the axis of the nail **109**.

FIGS. **2A-2C** illustrate various views of the insertion tool **103** of the system **101** shown in FIGS. **1A** and **1B**. In particular, FIG. **2A** is a partially exploded perspective view of the insertion tool **103** adjacent to the guide sheath **117**, FIG. **2B** is a perspective view of the insertion tool **103** with the guide sheath **117** partially inserted therein, and FIG. **2C** is an enlarged partial cross-sectional view of the engagement between the guide sheath **117** and the insertion tool **103**.

The guide sheath **117** can be removably inserted through a guide sheath receiving feature such as a hole **131** formed in the handle portion **107** of the insertion tool **103**. The guide sheath hole **131** defines an axis that intersects with a first aperture **123** in the nail **109**. The guide sheath **117** can be positioned through the guide sheath hole **131** such that it substantially aligns with the first aperture **123** in the nail **109**, which is configured to receive fixation device **119** aimed at the calcar region of the bone. The guide sheath **117** can include a first retention member **133** on an outer surface of the guide sheath **117**. The first retention member **133** can include, for example, ridged teeth, protrusions, or other such surface configured to engage with a corresponding second retention member **135** disposed within the guide sheath hole **131**. The second retention member **135** can likewise include one or more ridges or protrusions. Together the first and second retention members **133**, **135** form a retention mechanism **137** that allows the guide sheath **117** to be ratcheted towards the intramedullary nail **109** while restricting movement of the guide sheath **117** away from the intramedullary nail. The retention release mechanism **139** can disengage the second retention member **135** from the first retention member **133** when pressed by a user. For example, the retention release mechanism **139** can be a button disposed on a lower surface **141** of the handle portion **107**. Positioning this retention release mechanism **139** on the lower surface **141** of the insertion handle may prevent a user from accidentally releasing the guide sheath **117** while operating the device (e.g., while grasping the handle portion **107**).

FIGS. **3A-3F** illustrate one method of steps of implanting an intramedullary nail into a fractured femur **143**. Referring first to FIG. **3A**, a proximal end of the femur **143** can be accessed and the medullary cavity of the femur **143** can be reamed using a bone drill and reamer **145**. Next, as shown in FIG. **3B**, the intramedullary nail **109** is coupled to the insertion tool **103** and the intramedullary nail **109** is disposed within the reamed cavity of the femur **143**. In FIG. **3C**,

when used, one or more of the first and second guide wires **113** and **115** may be inserted through the soft tissue, for example, along parallel trajectories on opposing sides of the nail **109**. The guide wires **113**, **115** can limit or prevent inadvertent rotation of distal fragments of the femur **143** after the nail **109** is in position. The proximal fixation device **119** (e.g., a lag screw or other suitable bone anchor) is also passed through the first aperture **123** in the nail **109** and into the head/neck region of the femur **143**. In FIG. **3D**, the guide wires **113**, **115** are retracted and in FIG. **3E**, the distal fixation device **147** can additionally be inserted through the distal aperture **125** in the nail **109**. The distal device **147** can be positioned using the guide sheath **117**, which is positioned through another opening in the handle portion **107**, such that the sheath **117** is aligned with the distal opening **125** in the nail **109**. In FIG. **3F**, the insertion tool **103** is disengaged from the nail **109**, which is now secured in place via the proximal fixation device **119** and the distal fixation device **147**. As shown, the nail **109** may extend along a portion of the length of femur **143**. It is also contemplated, however, that the nail **109** may be of different sizes and shapes, for example, of longer lengths and/or different diameters to accommodate different anatomies and fractures.

FIGS. **4A-4D** illustrate another embodiment of an intramedullary nail **201**, similar to intramedullary nail **109**, with the addition of a cross-locking feature for proximal locking of the nail **201**. Intramedullary nail **201** may include any of the features described above with respect to intramedullary nail **109**. Intramedullary nail **201** may further include two interlocking proximal fixation devices **203**, **205** (e.g., bone anchors, fasteners, or screws), for example, by providing converging and diverging purchase, along with bony fixation in the calcar of the femur **229**, which is the strongest portion of the hip bone. Accordingly, the risk of failure due to cutout and/or rotation may be reduced.

FIGS. **4A-4D** show side, side cross-sectional, and two perspective views, respectively, of the intramedullary nail **201** adjacent to a first fixation device **203**. FIGS. **5A-5D** illustrate side, side cross-sectional, and two perspective views, respectively, of the first, proximal fixation device **203** inserted through the intramedullary nail **201**. FIGS. **6A-6D** illustrate side, side cross-sectional, and two perspective views, respectively, of the system with a second, cross-locking fixation device **205** adjacent to the intramedullary nail **201** with the first fixation device **203** inserted therein. FIGS. **7A-7D** illustrate side, side cross-sectional, and two perspective views, respectively, of the system with the second fixation device **205** inserted through both the intramedullary nail **201** and the first fixation device **203**, thereby creating a cross-locking feature for proximal locking of the nail **201**.

Referring to FIGS. **4A-8C** together, the intramedullary nail **201** is configured to receive both the first and second fixation devices **203** and **205** therein. The intramedullary nail **201** includes an elongated body **207** having first and second apertures **209** and **211** formed therethrough in a proximal region **213**, as well as a third aperture **215** formed in a distal region **217**. The first aperture **209** can be sized and configured to receive the first fixation device **203** therethrough and the second aperture **211** can be sized and configured to receive the second fixation device **205** therethrough.

The first fixation device **203**, may be the same or similar to the proximal fixation device **119**, described herein, and may include a bone screw or anchor configured for proximal locking of the nail **201**. For example, the first fixation device

203 may be a calcar screw or anchor configured to be aimed at a calcar region of the proximal humerus. The calcar screw 203 may have a threaded portion at its distal tip and a non-threaded portion along a substantial length of the screw 203. The calcar screw 203 may include traditional polyaxial or fixed angle calcar screws and anchors known in the art.

The second fixation device 205 may also include a bone screw or anchor configured for proximal locking of the nail 201. This bone anchor or screw 205 may be substantially smaller in length and diameter relative to the calcar screw 203. The bone anchor or screw 205 is substantially sized and configured to be positioned through second opening 211 in the proximal end of the nail 201 and into a channel 219 in the first fixation device 203. Thus, the second device 205 is configured to interlock with the first fixation device 203, for example, enhanced purchase and bony fixation to the bone. Although shown with the second fixation device 205 positioned above the first fixation device 203 and angled downwardly into contact with the first fixation device 203, it is also envisioned that these relative positions may be reversed or the fixation devices 203, 205 may otherwise be angled with respect to one another in order to interlock the devices 203, 205 with one another. The second fixation device 205 may be configured to pass through a slot or channel 219 formed in the first fixation device 203. This interlocking feature of the first and second fixation devices 203, 205 can prevent cutout and rotation by providing converging and diverging purchase. In the case of a femur, this can also provide bony fixation in the calcar. The elongated slot 219 in the first fixation device 203 allows for controlled collapse, which leverages the natural compression between fragments from weight bearing or ligamentotaxis. Limited collapse is controlled by the length of the slot 219 to prevent the uncontrolled and excessive shortening of the femoral neck. The first fixation device 203 may include distal threads 221 and a proximal drive interface 223 configured to engage with a driver (not shown). The second fixation device 205 may have a narrower diameter than the first fixation device 203 such that the second fixation device 205 can pass through the slot 219 in the first fixation device 203. The second fixation device 205 may also include distal threads 225 and a proximal drive interface 227 configured to engage with a driver (not shown).

The slot 219 can be disposed in the mid-shaft of the first fixation device 203 and may be sized and configured to allow the second fixation device 205 to pass therethrough. The slot 219 may be longer than necessary to allow translation of the first fixation device 203 after the second fixation device 205 is in place. The slot 219 may be strong enough to prevent rotation of the first fixation device 203 after the second fixation device 205 is in position. The slot 219 may have beveled proximal and distal edges to maximize material in the first fixation device 203 while allowing proximal and distal clearance of the second fixation device 205. The slot 219, in the first fixation device 203, may be symmetric to allow positioning of the second fixation device 205 in 180° increments, for example.

In at least one embodiment, a locking device 230, such as a set screw or washer, may be used to lock the first and/or the second fixation devices 203, 205 into position. As best seen in FIG. 7B, the locking device 230 may be threaded through a hollow interior portion of the nail 201. The locking device 230 may have external threads, which are sized and configured to correspond to mating internal threads along the hollow interior portion of the nail 201. As the locking device 230 is threaded downwardly and comes into contact with the first or second fixation devices 203, 205, the

respective fixation device 203, 205 is locked into position relative to the nail 201. In some embodiments, the interlocking fixation devices 203, 205 can be used selectively. For example, the threaded locking device 230 may be threaded to engage the second fixation device 205; alternatively, the threaded locking device 230 may be threaded further down to lock the first fixation device 203, for example, if the second fixation device 205 is not used. This allows users the choice of a traditional or interlocking construct intraoperatively.

An insertion tool 103 for implanting the system including the nail 201 and the interlocking first and second fixation devices 203 and 205 can be substantially similar to the system 101 described above with respect to FIGS. 1A-2C, except that an additional guide sheath hole may be formed in the handle portion 107 to accommodate a guide sheath along an appropriate trajectory to insert the second fixation device 205 through the second aperture 211 in the nail 201 and into engagement with the first fixation device 203.

FIGS. 8A-8C illustrate one method of steps of implanting an intramedullary nail 201 with interlocking fixation devices 203, 205 into a fractured femur 229. Referring first to FIG. 8A, the nail 201 has been inserted into a reamed medullary cavity of the femur 229 and the first fixation device 203 has been inserted through the first aperture 209 in the nail 201, similar to the technique described above with respect to FIGS. 3A-3D. Referring to FIG. 8B, a distal fixation device 231 can be inserted through the third aperture 215 in the nail 201, similar to the technique described above with respect to FIG. 3E. Referring to FIG. 8C, the second fixation device 205 is inserted through the second aperture 211 in the nail 201 and through the slot 219 in the first fixation device 203. As noted, these intersecting first and second fixation devices 203, 205 provide additional purchase in the head and neck region of the femur 229, and in particular the second fixation device 205 can provide bony fixation in the calcar. Accordingly, the interlocking first and second fixation devices 203, 205 can provide for improved stability and protection against common modes of intramedullary nail implant failure.

FIGS. 9A-9N illustrate another example of an intramedullary nail 309, which may comprise a generally elongate body extending from a first, distal portion or end 310 to a second, proximal portion or end 311. The elongate body may be in the form of an elongate tubular rod configured to extend longitudinally within the intramedullary canal of a fractured bone. The elongate rod may be hollow or may be solid along its length. The elongate body may be substantially straight along a longitudinal axis of the nail 309 or may comprise one or more curves or bends to conform to the anatomical shape of the intramedullary canal. In the embodiment of the nail 309 illustrated in FIG. 9A, the nail 309 may be utilized in a *piriformis fossa* entry and the curvature may be provided in the AP (anteroposterior) direction. This curvature allows the nail 309 to be used either antegrade (FIG. 9A) or retrograde (FIG. 9D), as well as in the right leg or left leg. In the embodiment illustrated in FIG. 9C, the nail 309' has curvature in the AP direction as well as a bend in the ML (medial-lateral) direction to facilitate entry at the tip of the greater trochanter. In other aspects, the nails 309 and 309' are the same unless otherwise described. The cross-section of the nail 309, taken at a right angle to a central longitudinal axis of the intramedullary nail 309, may be circular, oval, elliptical, or of any other suitable cross-dimensional shape.

Referring to FIGS. 10A-10C, a process of calculating the AP curvature of the nail 309 will be described. The radius of

curvature of the nail **309** may change depending on the length of the nail **309** so that the curvature can match the anatomical curvature of the femur into which the nail **309** is being inserted. Often-times, in longer femurs (taller patients), the curvature has too small a radius, and surgeons struggle to insert the nail without causing bone damage. The method of radius planning based on displacement described herein reduces the likelihood of a problem by offering a more anatomically correct (larger) radius.

As shown in FIG. **10A**, the femur endpoints may be in a vertical line. As such, the AP radius of curvature can be calculated using tangent circles if a valid starting point is assumed, for example, a nail length L of mm having a radius R . Turning to FIG. **10B**, each tangent circle will have a radius R . Drawing a right triangle from the center C of the tangent circle, with R as the hypotenuse and $\frac{1}{2}$ the nail length L as one leg of the triangle, the other leg will have a length z . Due to the curvature, the point where the legs $\frac{1}{2}L$ and z meet will be spaced a distance y from the tangent point T . As such, $R=y+z$ and $R^2=L^2/4+z^2$. Combining the formulas results in $R=y/2+L^2/8y$. Utilizing the initial assumption, the constant y can be calculated. With the constant y calculated, the radius R of curvature for each length L can be found. Utilizing the assumption of a nail length having a radius R , the following is a table of calculated radius R for various lengths L .

Nail Length (mm)	AP Bow (m)
160-300	1.0
310-400	1.2
410-500	1.4

Referring again to FIGS. **9A-9N**, the distal end **310** of the nail **309** may include one or more distal openings **312-318** configured to receive one or more bone anchors, fasteners, or distal fixation devices **330, 332** that extend transversely through the distal end **310** of the intramedullary nail **309**, and are thereby configured to secure the distal end **310** of the nail **309** within the canal. The distal fixation devices **330, 332** may include a bone screw or anchor configured for distal locking of the nail **309** and also reconstruction. The distal fixation device **330, 332** may include traditional polyaxial or fixed angle locking bone screws and anchors known in the art.

In the illustrated embodiment, the distal openings include an AP locking slot **312** and an AP locking opening **314**. The openings also include a pair of ML locking openings **313, 315** and an ML locking slot **317**. The AP and ML locking slots **312, 317** facilitate relative movement between the nail **309** and the locking screw **330** in the event compression or the like is applied during installation. The distal openings also include a pair of oblique openings **316, 318** configured to receive and guide reconstruction screws **332**. As illustrated in FIG. **9J**, each of the oblique openings **316, 318** is at an angle α_1, α_2 relative to the axis of the nail **309**. The angles α_1, α_2 are in the range of $45^\circ-60^\circ$, and in the illustrated embodiment, are each 50° . It is preferred that the angles α_1, α_2 are equal to one another such that the oblique openings **316, 318** are mirror images of one another, thereby allowing the nail **309** to be utilized in both right and left legs. The distal oblique openings **316, 318** all surgeons to lock distal screws at an angle or approach a distal fragment from a more proximal screw entry point. This configuration could be useful for treatment of periarticular fractures and condylar splits. Additionally, the oblique distal openings **316, 318**

allow surgeons to access condylar fractures without risking soft tissue damage near the knee or hip joint upon entry.

The proximal end **311** includes one or more proximal openings **123** configured to receive one or more bone anchors or fasteners **330, 332** that extend transversely through the proximal end **311** of the intramedullary nail **309**, and are thereby configured to secure the proximal end **311** of the nail **309** within the canal and also reconstruction. The proximal fixation devices **330, 332** may include a bone screw or anchor. The fixation device **330** may be a locking screw and the fixation device **332** may be a calcar screw or anchor configured to be aimed at a calcar region of the proximal humerus, which may constitute the best quality bone in the region.

The proximal openings may include a pair of ML openings **321, 323** and an ML slot **325**. The ML openings **321, 323** and the ML slot **325** are configured to receive the locking screws **330**. The ML locking slot **325** facilitates relative movement between the nail **309** and the locking screw **330** in the event compression or the like is applied during installation. The distal openings also include a plurality of oblique openings **322, 324, 326** and **327**, which preferably include mirrored pairs. More specifically, with reference to FIGS. **9K-9N**, upper oblique openings **322** and **324** are mirror images, forming complementary angles β_1, β_2 , i.e. $\beta_1+\beta_2=180^\circ$. For example, the oblique angle β_1 may be about $100-150^\circ, 110-140^\circ$, or about $120-135^\circ$ relative to the nail **309** while the angle β_2 is about $30-80^\circ, 40-70^\circ$ or $45-60^\circ$. Similarly, the lower oblique openings **326, 327** are mirror images, forming complementary angles β_3, β_4 , i.e. $\beta_3+\beta_4=180^\circ$, which may extend over ranges similar to those given above for openings **322, 324**. With such a configuration, the proximal oblique openings **322, 324, 326** and **327** are also aligned so that they will function the same in either the right or left leg. In the illustrated embodiment, the angles β_1, β_3 are equal and the angles β_2, β_4 are equal, however, such is not required.

Additionally, the openings whose axes are mirror images of one another are also offset in the AP plane from the sagittal plane, one by an θ_1 in the anterior and the other by an angle θ_2 in the anterior. As illustrated in FIGS. **9K** and **9L**, the opening **322** is offset by θ_1 while the opening **324** is offset θ_2 . Similarly, as illustrated in FIGS. **9M** and **9N**, the opening **326** is offset by θ_3 while the opening **327** is offset θ_4 . In the illustrated embodiment, the larger offset θ_2, θ_4 is twice as large as the corresponding offset θ_1, θ_3 . This creates room for the screw **330** to pass posteriorly to these two reconstruction screws **332** to make a fixed angle construct. In the illustrated embodiment, the offset θ_1 of opening **322** is equal to the offset θ_4 of opening **327** while the offset θ_2 of opening **324** is equal to the offset θ_3 of opening **326**. With this configuration, the offsets of the similarly angled pair of openings **322** and **326** will be offset with respect to one another and the offsets of the similarly angled pair of openings **324** and **327** will be offset with respect to one another.

The nail **309** provides a hybrid antegrade/retrograde and left/right nail. Such a nail **309** is advantageous to hospitals and surgeons because it reduces stock and simplifies surgical planning. The bi-directional proximal oblique openings **322, 324, 326, 327** provide a variety of options for proximal femur fracture fixation, as well as a more stable construct. Additionally, the arrangement of the proximal openings **321-327** allows for a fixed-angle construct created by the screws **330, 332**. The design further provides for three screws to be secured into the femoral neck. This fixed-angle

construct provides more biomechanical stability than the traditional two screw configurations.

Referring to FIGS. 9I and 11A-11E, a method of attaching the intramedullary nail 309 with an insertion tool 350 will be described. The nail 309 of the present embodiment has an opening 334 at the proximal end 311. A shoulder 335 within the opening 334 defines a circumferential slot 336 on the inside diameter of the proximal portion 311 of the nail 309. This configuration takes up less space at the proximal end 311 of the nail 309 than a typical threaded connection, thereby freeing up space for more proximally located locking holes.

To connect the nail 309 to the insertion tool 350, the insertion tool 350 includes an expanding collet 370 and connecting bolt 354. An alignment tip 360, which connects within a through passage 353 in the aiming arm 352 of the insertion tool 350, is configured to align the bolt 354 with the expanding collet 370. The alignment tip 360 includes a hollow body 362 with a through passage 364 extending from a proximal end 361 to a distal end 363 of the body 362. The proximal end 361 of the body 362 is configured to be received into the through passage 353 of the aiming arm 352 with a press fit, however, other connecting mechanisms may be utilized. A shoulder 368 extends radially from the body 362 and engages the aiming arm 352 when fully inserted, as illustrated in FIGS. 11D and 11E. The distal end 363 of the body 362 has a recessed portion 366 configured to be received into the opening 334 in the proximal end of the nail 309.

The expanding collet 370 includes a hollow body 372 with a through passage 374 extending from a proximal end 371 to a distal end 373 of the body 372. The distal end 373 has a radially outwardly extending collar 376, tabs, projections or the like. The collar 376 is configured to be received within the circumferential slot 336 in the proximal end 311 of the nail 309. Axial slots 375 extend from the distal end 373 of the body 372 and allow the distal end of the body 372 to compress radially inwardly, thereby allowing the collar 376 to pass through the alignment tip through passage 364 and the shoulder 335 within the proximal end 311 of the nail 309. An external shoulder 377 on the collet 370 contacts an internal shoulder 367 on the alignment tip 360 to limit the range of motion of the collet 370 relative to the alignment tip 360. Once the collar 376 is past the shoulder 335, the collar 376 is free to expand radially outwardly. The distal end 373 of the collet body 372 includes internal threads 378 configured for engagement with the threads 355 of the connecting bolt 354.

The connecting bolt 354 then drives through the through passage 374 of the expandable collet 370 and engages the threads 378. As the connecting bolt 354 is threaded with the threads 378, it pushes the collar 376 outwardly to its major diameter and further drives the collar 376 into the circumferential slot 336 within the nail 309. In addition, when the bottom side of the head 356 of the bolt 354 makes contact with the top of the alignment tip 360, it allows for compression across the proximal nail 309, thus compressing any spacing in the connection. The assembly allows for quick, easy, and rigid connection of the nail 309 to the aiming arm 352. It is noted that any of the intramedullary nails described herein may include an internal circumferential slot and be connected to an insertion tool or the like utilizing an expanding collet as described.

Referring to FIGS. 12A-12K, a self-retaining screw 400 and driver 430 assembly will be described. Screws are often affixed to drivers on the back table by a scrub tech or nurse and then they are handed to the surgeon who places the

screw where it is needed. Between the back table, and the final seating of the screw into the bone, many actions can dislodge it from the driver, thus rendering it non-sterile, for example, when it hits the operating room floor. To minimize the likelihood of dislodging, the self-retaining nail locking screw 400 has features which achieve a more secure connection.

With reference to FIGS. 12A-12F, the screw 400 includes a shaft 402 extending from a distal tip 404 to a proximal head 406. In the illustrated embodiment, the shaft 402 includes a two thread 403, 405 start which provides for easier advancement. The head 406 defines a proximal torque bore 410 and a threaded bore 416 distally thereof. The torque bore 410 and the threaded bore 416 are in communication with one another and preferably coaxial. The torque bore 410 has a configuration with engaging surfaces to engage a complimentary torque tool. In the illustrated embodiment, the torque bore 410 has a hexalobe configuration with a plurality of lobal recesses 412 extending radially from the central opening. The lobal recesses 412 define a maximum diameter D while the central opening defines a smaller diameter d. The lobal recesses 412 are configured to receive complementary lobes 436 on a driving tool head 430, as will be described in more detail below. The threaded bore 416 defines a plurality of internal threads 417 which are configured to be engaged by a threaded rod (not shown) which tightens into the threaded bore 416 at the bottom of the torque bore 410. The combination of a torque bore 410 and a threaded bore 416 allows for secure delivery of the screw 400 utilizing the threaded rod and thereafter additional tightening of the screw 400, if needed, utilizing a torque driver engaged with the torque bore 410.

Referring to FIGS. 12G-12K, the torque driver head 430 illustrated therein has a taper in order to give it a stab and grab retaining feature on its own. The torque driver head 430 includes a proximal body 432 and a distal shaft 434 extending therefrom. The proximal body 432 and shaft 434 are preferably a unitary structure extending from a proximal end 431 to a distal end 433. A plurality of lobes 436 extend radially from the shaft 434 and have a complementary configuration to the lobal recesses 412 in the torque bore 410 of the screw 400. The lobes 436 taper, narrowing moving in the distal direction. The taper is generally constant over a first length E_1 and then more pronounced at the distal end 433 over the length E_2 . With the taper, the lobes 436 define a larger maximum diameter F_1 in the proximate portion of the shaft 434 (see FIG. 12J) and a smaller maximum diameter F_2 in the distal portion of the shaft 434 (see FIG. 12K). The larger diameter F_1 is preferably larger than the maximum diameter D of the lobal recesses 412 and the smaller diameter F_2 is preferably smaller than the maximum diameter D of the lobal recesses 412, i.e. $F_1 > D > F_2$. With this configuration, the distal end 433 of the torque driver head 430 moves easily into the torque bore 410, however, as the torque driver head 430 is inserted further, the lobes 436 engage the lobe recesses 412 in a friction fit, providing the stab and grab retaining feature. In some instances, this feature may provide sufficient secure connection without the need to utilize the threaded rod and threaded bore 416.

Referring to FIGS. 13A-13F, a headless version of the screw 400' will be described. There are several scenarios in which a surgeon may desire to have as low of a head profile on a screw as possible. For example, when a fracture occurs near the joint space, it is often necessary for a surgeon to place screws through the articular surface. In order to preserve function of the joint, and avoid joint pain, it is essential that the locking screw used does not impinge any

motion of the bones or soft tissues in that region. A headless screw may also be desired in areas where the soft tissue above the bone is very thin, so prominent screw heads may be felt or even seen by the patient post-op (e.g., in the proximal tibia).

The headless screw **400'** is similar to the screw of the previous embodiment and includes a shaft **402** extending from a distal tip **404** to a proximal head **406'**. In the illustrated embodiment, the shaft **402** includes a two thread **403**, **405** start which provides for easier advancement. Although it will be appreciated that the screw **400'** may have a single thread start or any other suitable configuration. Similar to the previous embodiment, the head **406'** defines a proximal torque bore **410** and a threaded bore **416** distally thereof. The torque bore **410** has a configuration with engaging surfaces to engage a complimentary torque tool and the threaded bore **416** defines a plurality of internal threads **417**.

The head **406'** of the present embodiment, has a plurality of external threads **407**. In the illustrated embodiment, the threads **407** may have a four start thread that is half the pitch of the shaft thread. The threads **407** allow the head **406'** to be sunk beneath the surface of the bone. When used in conjunction with the intramedullary nails described herein or otherwise known, the headless screw **400'** provides a unique offering of a headless option that still acts the same as a standard locking screw.

According to an exemplary embodiment, an intramedullary nail system includes an intramedullary nail in combination with at least one headless screw or fastener. The intramedullary nail may include intramedullary nails **109**, **201**, **309**, **500** described herein or any other intramedullary nails generally known or hereinafter developed. The headless screw or fastener is intended to encompass a screw or fastener, which is blind such that the screw is fully threaded and has no head projecting past a major diameter of the screw thread and/or may encompass a screw or fastener having a head portion where the thread extends all the way to the head (e.g., a threaded head). For example, the headless screw may include headless screw **400'** described herein or any other headless screw generally known or hereinafter developed.

According to one embodiment, the intramedullary nail **109**, **201**, **309**, **500** is used in combination with at least one headless screw **400'** or headless fastener. The headless screw **400'** or other headless fastener may be positioned through the body of the nail **109**, **201**, **309**, **500** such that the shaft **402** resides within one or more openings in the nail **109**, **201**, **309**, **500**. The shaft **402** of the headless screw **400'** may be configured to mate with the intramedullary nail **109**, **201**, **309**, **500** in a locking (e.g., threaded mating) or non-locking fashion. The threaded head **406'** of the headless screw **400'** may be positioned such that the head **406'** is positioned at or near the outer surface of the bone, for example, as best seen in FIG. **9A**. By positioning the head **406'** of the headless screw **400'** against the bone (or slightly inset into the bone) in combination with the intramedullary nail **109**, **201**, **309**, **500**, the intramedullary system may be substantially unnoticeable to a patient. When traditional headed screws are used, sometimes patients complain that they are able to feel the screw or the screw head protrudes from the surgical site causing irritation or pain to the patient. Accordingly, it may be suitable for one or more headless screws or fasteners to be used when securing the distal and/or proximal ends of the intramedullary nail, thereby resulting in superior patient outcomes.

Referring to FIGS. **14A-14C**, a nail **450** with a threaded hole **454** will be described. In unstable fractures or in patients with poor bone quality, it is imperative that the surgeon has an ability to stabilize the lateral translation of the nail relative to the screw. This is often referred to as an interference fit. To achieve interference fit with the screw **400** or a similar locking screw, the nail **450** is provided with one or more threaded holes **454** along the elongate body **452** of the nail **450**. The threaded hole **454** includes threads **453**, **455** with a two start thread. In the illustrated embodiment, the threads **453**, **455** provide a two start 60-degree machine thread. The threads **453**, **455** will have the same pitch as the threads **403**, **405** of the screw **400**. As previously described, the screw shaft **402** also has a two start thread for easy advancement. The threaded two start hole **454** in the nail **450** itself is an advantage over current interference holes because it is easy to manufacture, and requires no additional steps or special techniques on the part of the surgeon.

Referring to FIGS. **15A-15C**, a washer **470** configured to provide greater compression on the screw will be described. In some applications, the screw and nail may not provide sufficient interference. For example, when poor bone quality or severely comminuted fractures interfere with screw placement, surgeons often require a screw which interfaces with the nail itself. When the near cortical wall is not stable, which is the case in a number of complex femur fractures, even an interference fit screw will not get any purchase in the near cortex, and therefore the fixation will be unstable. The washer **470** may be provided as an option for use with a screw and nail assembly if the conditions present the need for such.

The washer **470** includes a hollow body **472** with a through passage **474** extending from a proximal end **471** of the body **472** to a distal end **473** of the body **472**. The distal end **473** of the body **472** includes a plurality of cutouts **475** between distal tips **476**. Each cutout **475** is approximately 90° such that each pair of opposed cutouts **475** is coaxial thereby allowing an outer diameter of the nail. The washer **470** fits over the major diameter of the screw and sits flush with the underside of the head. It may be inserted through a tissue protection sleeve along with the screw and driver. When the distal tips **476** of the washer **470** come into contact with the outer diameter of the nail and the nail is received into the opposed cutouts **475**, the screw continues to spin while the washer **470** grips the side of the nail. This allows the screw to get compression on the far side of the nail and hold the screw/washer construct firmly to the side of the nail. This provides a rigid fixation method when the cortical bone is not strong enough to do so. The washer **470** thereby expands the indications for which the nail can be used.

Having described illustrative femoral nails, embodiments of tibial nails and systems for implantation thereof will be described with reference to FIGS. **16A-17K**. Referring to FIGS. **16A-16D**, a first tibial intramedullary nail **500** will be described. It is recognized that the features of the nail **500** are not limited to use in a tibial nail and may be incorporated into other intramedullary nails. The intramedullary nail **500** generally comprises an elongate body **502** extending from a first, distal portion or end **503** to a second, proximal portion or end **501**. The elongate body **502** may be in the form of an elongate tubular rod configured to extend longitudinally within the intramedullary canal of a fractured bone. The elongate rod may be hollow or may be solid along its length. The elongate body may be substantially straight along a longitudinal axis of the nail **500** or may comprise one or more curves or bends to conform to the anatomical shape of the intramedullary canal. In the embodiment of the nail **500**

illustrated in FIGS. 16A-16D, the nail 500 is utilized in a tibia and the proximal end has a bend λ relative to the shaft has a bend while the distal end has a bend χ relative to the shaft. In the illustrated embodiment, the bend λ is approximately 10° while the distal end bend χ is approximately 3° . The bends λ and χ are not limited to the described angles and may have larger or smaller bends depending on the anatomy of the bone.

The distal end 503 of the tibial nail 500 contains four openings 510-513. The openings 510, 512 are oriented in the ML direction and the openings 511, 513 are oriented in the AP direction. In the illustrated embodiment, the ML opening 510 and the AP opening 511 each include a 2 start thread 514 used to create a fixed angle construct with the locking screw, similar to that described above with respect to FIG. 14C. Fixed angle constructs are used to treat highly unstable fractures.

Referring to FIGS. 16E-16G, an alternative distal end 503' of the nail 500' will be described. In this embodiment, the ML opening 510 is replaced with a combined oblique locking opening 520, with first and second openings 521, 522 each at an oblique angle, for example, at 30° off the sagittal plane. The combined oblique locking opening 520 allows the surgeon to insert locking screws 530 in two different orientations, thereby creating an alternative fixed angle construct.

Referring to FIG. 16H, another alternative distal end 503" of the nail 500" illustrates additional features which may be utilized to create a fixed angle construct. In this embodiment, the AP opening 511' is defined as a broached hole while the AP opening 513' is defined as a threaded hole. The fixed angle construct is created by inserting a locking screw through the threaded or broached hole. The locking screw thread engages with the threads or broached features to stabilize the fracture by limiting the movement of the screw 530 relative to the nail 500".

Returning to FIGS. 16A and 16C, the proximal end 501 of the tibial nail 500 contains openings 515-518, including a pair of proximal oblique openings 515, an AP oblique opening 516, a proximal ML slot 517 and a proximal ML opening 517. The proximal oblique openings 515 are similar to those describe above with respect to the embodiment illustrated in FIG. 9A. The AP oblique opening 516 contains a 2 start thread 519 used to create a fixed angle construct with a locking screw. The proximal ML slot 517 is used for compression of fractures and static/dynamic locking modes.

Having described various features of illustrative tibia nails 500, tools, systems and methods of inserting the tibia nails 500 will be described with reference to FIGS. 17A-17K. The tibial nail 500 is inserted into the medullary canal through an incision at the entry site. FIG. 17A illustrates an illustrative embodiment of a system 535 for implanting an intramedullary nail 500 utilizing the infra-patellar approach. The infra-patellar approach is the industry standard approach for insertion of the tibial nail 500. This approach is typically performed with the leg in the hyper-flexed (HF) position. The tibial nail 500 is inserted directly through the incision into the tibial canal.

The system 535 includes an insertion tool 540 and an aiming guide 560. The insertion tool 540 includes a coupling portion 545 and a handle portion 547. In some embodiments, the coupling portion 545 and the handle portion 547 can be separate parts that are removably joined together, while in other embodiments the coupling portion 545 and the handle portion 547 can be different regions of a single, integrally formed component. The handle portion 547 is preferably rigid, for example, made from stainless steel and also has

provisions to attach an impaction shaft 546 and compression bolt 544. The coupling portion 545 has a connection portion 548 configured to releasably engage or couple to the proximal portion 501 of the nail 500. In the illustrated embodiment, the connection portion 548 includes a threaded connector. However, those skilled in the art will understand that other coupling mechanisms may be employed.

The handle portion 547 includes a connection assembly 550 for releasably attaching the handle portion 547 to the aiming guide 560. The connection assembly 550 includes a body 551 with two bores 552, 554 defined therein. A connection button 553 extends into one of the bores 552. The connection button 553 is biased to a connected position as illustrated in FIG. 17B. The connection button 553 has an engagement portion 556 within the bore 552 configured to engage a slot 573 on a connection post 572 of the aiming guide, as will be described in more detail hereinafter. In the illustrated embodiment, the engagement portion 556 includes a plate with a smaller diameter opening 557. To disengage the engagement portion 556, the button 553 is depressed such that the larger diameter opening 558 aligns with the connection post 572. However, those skilled in the art will understand that other connection mechanisms may be employed.

The tibial nail aiming guide 560 is used to install locking screws into the tibial nail 500. The aiming guide 560 sets the trajectory of the locking screws to interface with the proximal openings 515-518 of the nail 500. In at least one embodiment, the aiming guide 560 is made from a radiolucent material. The aiming guide 560 includes an arcuate body 562 which extends between opposed end support blocks 564. Each end support block 564 defines a hole opening 563, which aligns with the ML opening 518, and a slot opening 565, which aligns with the ML slot 517. A plurality of intermediate support blocks 568A-C extending from the body 562. The support block 568A includes a hole opening 569 which is aligned with the AP oblique opening 516. The support blocks 568B and 568C each include a hole opening 569 which is aligned with a respective oblique opening 515. The openings 563, 565, and 569 are configured to support respective guide sheaths 580 similar to the guide sheaths 117 described above. The sheaths 580 are used to protect the soft tissue during the drilling process. The sheaths 580 accept drill sleeves and trocars of various sizes. The guide sheaths 580 and blocks 564, 568A-C may have retention members similar to those described above, with each block 564, 568A-C having a respective release mechanism 567.

The aiming guide 560 also includes a connection assembly 570 configured to mate with the connection assembly 570 on the insertion handle 540. The connection assembly 570 includes a body 571 with a pair of connection posts 572, 574 extending therefrom which are configured to be received in the bores 552, 554 of the connection assembly 550. The connection post 572 includes a slot 573 configured to be selectively engaged by the engagement portion 556 of the connection button 553. The connector assembly 570 is a rigid structure and may be made from, for example, metal.

Accordingly, the system 535 provides an insertion handle 547 with reliable and convenient connection assembly for attaching the aiming guide 560. A push button connection and release system allows tool free connection and disconnection of the aiming guide 560. The insertion handle 547 also contain an external compression bolt 544 used to apply pressure the locking screw in the dynamic position to compress a fracture gap. The aiming guide 560 utilizes a push button release mechanism 567 that locks the soft tissue

sheaths **580** in place. The release mechanism **567** allows insertion of the soft tissue sheath **580** but prevents it from backing out. This feature helps to maintain the position of the soft tissue sheaths **580** for accurate screw length measurements and facilitates drilling and screw insertion. The aiming guide **560** is designed with extended sheath guides **580** for improved aiming accuracy.

The supra-patellar approach uses a tibia entry point above the knee. A system **530'** for use with the supra-patellar approach will be described with reference to FIGS. **17F-17L**. The system **530'** is substantially as in the previous embodiment but further includes a cannula assembly **590**. As illustrated in FIG. **17F**, at the time of insertion of the nail **500**, the nail **500** and the connection portion **545** of the insertion tool **540** are inserted through the cannula assembly **590**. The cannula assembly **590** protects the articular surface of the knee during the nail insertion process. As will be described below, the cannula assembly **590** also protects the articular surface of the knee during reaming. The reaming is performed through a drill guide **610** in the cannula **592** of the cannula assembly **590**. Thereafter, the drill guide **610** is removed and nail **500** insertion is performed through the cannula **592** into the entry incision.

Referring to FIG. **17G**, an illustrative cannula assembly **590** will be described. The cannula assembly **590** includes a flexible cannula **592** and a rigid handle **596**. The cannula **592** has a through passage **594** which is aligned with an opening **599** in the handle **596** to define a continuous passage. In one embodiment, the flexible cannula **592** material is overmolded onto the rigid plastic handle **596**. A pair of tibia guide slots **595** extend through the handle **596** and along the sides of the cannula **592**. Transverse femur guide holes **597** extend through the handle **596**. As shown in FIG. **17H**, the guide slots **595** and guide holes **597** guide fixation pins **602** into the tibia **144** or femur **143**.

The cannula assembly **590** is inserted through an incision in the skin and is the working portal through which the surgeon can perform reaming, drilling, and nail insertion. The guide slots **595** and holes **597** allow the surgeon to fix the cannula **592** in place during the procedure. The guide slots **595** and holes **597** allow the cannula to be fixed to the femur **143** or tibia **144** with converging pins **602** depending on surgeon preference. The cannula **592** is reversible and can be used on either side of the patient. Referring to FIG. **17I**, the cannula assembly **590** is designed to accept a metal drill sleeve **610** and round trocar **612**. There is a connection point **603** on the cannula handle **596** that accepts the connector **611** on the metal drill sleeve **610**. In the illustrated embodiment, the cannula **592** is tapered for easy removal of the drill sleeve **610**. The soft, flexible cannula **592** is anatomically shaped to fit between the femoral condyles and minimize damage to the articular surface.

Referring to FIGS. **17J-L**, a cannula assembly **590'** in accordance with another illustrative embodiment will be described. The cannula assembly **590'** is similar to the previous embodiment and includes a flexible cannula **592'** extending from a rigid hub **596'**. The rigid hub **596'** includes legs **593** extending from each side of the cannula **592'**. Each leg **593** of the hub **596'** defines a respective tibia fixation hole **595'** and a series of femur pin holes **597**. The two tibia fixation holes **595'** are designed to accept k wire or pin **602** for fixation to the tibia. The wires or pin **602** can be convergent or parallel. The femur pin holes **597** are for femur fixation using half pins **598**. The cannula assembly **590'** is designed to accept a metal drill sleeve **610** and round trocar **612**.

Referring to FIG. **18**, an aiming guide **601** is provided for inserting an intramedullary nail into a bone, such as a femur **143** (shown in FIGS. **3A-3F**). The aiming guide **601** provides the ability to insert femoral nails through both a *piriformis* and a greater trochanter entry point, allowing for antegrade and retrograde nail implementation. Additionally, the aiming guide **601** allows for the attachment of an impactor and multiple modules, which allows for simple operation of the aiming guide **601** while still allowing for a variety of engagement options for the clinician. Also, the aiming guide **601** provides a rigid connection to the nail to assist with insertion into the femur, and the base for an assembly that provides for a method to insert both recon fasteners or screws and oblique fasteners or screws to secure the femoral nail into the femur. Although described with reference to an antegrade/retrograde femoral nail, it will be appreciated that a similar aiming guide may be provided with other intramedullary systems.

The nail can be nail **309**, shown in FIG. **9A**, nail **500**, shown in FIG. **17F**, nail **699**, shown in FIGS. **23-26**, or other suitable intramedullary nail systems. The aiming guide **601** may be used to install recon fasteners or screws, oblique fasteners or screws and/or lateral/medial locking fasteners or screws into the intramedullary nail. The aiming guide **601** is configured to set the trajectory of the fasteners or screws to interface with corresponding through holes in either or both the proximal end and the distal end of the nail. A tissue sleeve may be used to protect soft tissue during the drilling process and to help set the drill trajectory.

The aiming guide **601** may include a generally arcuate or "J-shaped" body **605** having an elongate proximal handle portion **604** and a generally arcuate distal implant alignment tip connector portion **606**. The distal implant tip connector portion **606** has a distal implant alignment tip **608** that may be configured to extend along a tip axis **613** substantially parallel to a longitudinal axis **615** of the proximal handle portion **604**. The distal implant alignment tip **608** may be secured to the distal implant tip connector portion **606**, for example, via spring loaded friction pads (not shown) located on the distal implant tip connector portion **606** that help keep the distal implant alignment tip **608** in place. The distal implant alignment tip **608** may also be secured, for example, in the manner provided in FIG. **11A**.

According to one embodiment, the aiming guide **601** including the body **605** and implant alignment tip connector portion **606** may be a unitary construction that is constructed from a single material, such as, for example carbon fiber. The distal implant alignment tip **608** may optionally be constructed from a different material, such as, for example, a metal such as steel. The metal allows for an impactor (not shown) to be directly threaded into the distal implant alignment tip connector portion **606**.

Further, the distal implant alignment tip **608** may be inserted into a receiver **614** at the distal end **617** of the distal implant alignment tip connector portion **606** for a releasable connection with the distal implant alignment tip connector portion **606**. The distal implant alignment tip **608** is configured to releasably retain a femoral nail, such as nail **309**, a nail **500**, or a nail **699**, as discussed above.

A proximal end **616** of the handle portion **604** may have a first attachment location **618** for releasably attaching a first module, such as, for example, a recon module **700**, shown in FIG. **19**. The first attachment location **618** includes a recessed portion **620** on an exterior side **622** of the handle portion **604**. A threaded receiver **624** extends into the handle portion **604** from the recessed portion **620** and is sized to

threadingly engage a thumb screw **702** on the recon module **700**. A generally oblong alignment bushing **625** may surround the receiver **624**.

The proximal handle portion **604** may include a hand grip **630** on an interior side **632** of the handle portion **604**. The hand grip **630** includes a plurality of finger indents **634** to allow a clinician to grip the handle portion **604** and reduce the likelihood of the handle portion **604** rotating in the clinician's handle while using the aiming guide **601**. The hand grip **630** has a plurality of through holes **636** extending therethrough from the exterior side **622** to the interior side **632**. At least one of the through holes **636** extends along a hole axis that extends substantially perpendicular to the longitudinal axis **615** of the handle portion **604**. In an exemplary embodiment, each of the through holes **636** extends along a hole axis that extends substantially perpendicular to the longitudinal axis **615** of the handle portion **604**.

Through holes in the aiming guide and/or modules can be used to align sleeve **340**, **342**, **344** and screw **330**, **332** with the femoral nail **699**. As shown in FIG. **26**, through hole **636** can align sleeve **344** and screw **330** with an opening in the femoral nail **699**. The sleeve **344** can be similar to the sleeves or sheaths described herein (e.g., sheath **117**) configured to protect soft tissue and allow for insertion of a drill, driver, fasteners or screws (e.g., fastener **119**, fixation devices **330**, **332**), and the like configured to be aligned with and inserted through the openings in the intramedullary nail and into the bone.

Distal from the handle portion **604**, the distal implant alignment tip portion **606** further includes a second attachment location **640** for releasably attaching a second module, such as, for example, an oblique module **800**, shown in FIG. **20**. The second attachment location **640** may include a metal alignment block **642** on each side wall **644**, **645** (side wall **645** is shown in FIG. **21**) of the distal implant alignment tip portion **606**. The alignment blocks **642** may be used to align the oblique module **800** on the body **605**. Pins **648** fit into holes **647** in the alignment blocks **642** (only one alignment block **642** is shown) to retain the alignment blocks to the body **605**. A threaded receiver **646** extends through the distal implant alignment tip portion **606** between the alignment blocks **642** and is sized to threadingly engage a thumb screw **802** on the oblique module **800** (shown in FIG. **20**). The distal implant alignment tip portion **606** further comprises a third attachment location **650** for releasably attaching an impactor attachment (not shown) to support the impactor discussed above. The third attachment location **650** can be a threaded opening to receive a threaded insert on the impactor attachment.

Referring to FIGS. **19** and **21**, the recon module **700** may be releasably attached to the proximal end **616** of the proximal handle portion **604**. The recon module **700** includes a connection piece **704** that engages the proximal end **616** of the proximal handle portion **604**. The connection piece **704** includes a recessed portion **706** that mirrors the recessed portion **620** in the proximal end **616** for a secure engagement. Recessed portion **706** includes a generally oblong receiver **708** that is sized to accept the generally oblong alignment bushing **625** to prevent translation or rotation of the recon module **700** with respect to the aiming guide **601**. With the generally oblong alignment bushing **625** inserted into the receiver **708**, the thumb screw **702** is aligned with the threaded receiver **624** so that the recon module **700** can be releasably secured to the aiming guide **601** by threading the thumb screw **702** into the threaded receiver **624**.

The recon module **700** may have an arcuate body **710** having a first recon portion **712** extending from the first side wall **644** of the proximal handle portion **604** and a second recon portion **714** extending from the second side wall **645** of the proximal handle portion **604**, distal from the first side, when the recon module **700** is attached to the aiming guide **601**, as shown in FIG. **21**. The arcuate body **710** has a plurality of recon through holes **720**, **722**, **724**, **726** extending therethrough, such that each of the plurality of recon through holes extends along an axis intersecting the tip axis **613**.

Referring to FIGS. **20** and **21**, the oblique module **800** may be releasably attached to the distal implant alignment tip portion **606**. The oblique module **800** includes a generally U-shaped attachment site **803** that engages the alignment blocks **642** when the oblique module **800** is inserted onto the aiming guide **601** so that the thumb screw **802** is aligned with the threaded receiver **646**. The oblique module **800** can be releasably secured to the aiming guide **601** by threading the thumb screw **802** into the threaded receiver **646**.

The oblique module **800** may have an elongate body **804** having a first oblique portion **806** extending from a first side of the attachment site **803** and a second oblique portion **808** extending from a second side of the attachment site **803**, distal from the first side, when the oblique module **800** is attached to the aiming guide **601**, as shown in FIG. **21**. The elongate body **804** has a plurality of oblique through holes **810**, **812**, **814**, **816** extending therethrough, such that each of the plurality of oblique through holes **810**, **812**, **814**, **816** extends along an axis intersecting the tip axis **613**.

Aiming guide **601**, recon module **700**, and/or oblique module **800** may form an aiming guide assembly that supports a plurality of screws **330**, **332** inserted therethrough and into femoral nail **699**, as shown in FIGS. **23-26**. In FIGS. **23** and **24**, two recon screw sleeves **340** are shown extending through recon module **700** to align recon fasteners **332** with the intramedullary nail **699** for placement of the recon fasteners **332**; in FIG. **25**, a single recon screw sleeve **340** extends through recon module **700** for placement of the recon fastener or screw **332** in the femoral head, while a single oblique screw sleeve **342** extends through the oblique module **800** for placement of the oblique screw **332** through the nail **699** into the greater trochanter of the femur and preferably not the lesser trochanter of the femur; and in FIG. **26**, a single oblique screw sleeve **342** extends through the oblique module **800**, while a single driver screw sleeve **344** extends from the handle portion **604** of the aiming guide **601** for placement of screw **330** into the femoral nail **699**. While these exemplary embodiments of screw sleeves **340**, **342**, **344** and screw configurations are shown, those skilled in the art will recognize that other sleeve and screw configurations can be provided with the aiming guide assembly.

While the recon module **700** and the oblique module **800** are shown with the aiming guide **601**, those skilled in the art will recognize that the recon module **700** and the oblique module **800** can be used independently or omitted and just the aiming guide **601** alone can be used with the femoral nail **699** and one or more sleeves **340**, **342**, **344** through the aiming guide **601** for placing fasteners or screws **330**, **332** into the femoral nail **699**.

Referring now to FIG. **27**, an alternative embodiment of an aiming guide **900** is similar to the aiming guide **601**, but instead of being of unitary construction from a single material, the aiming guide **900** can be a multi-part construction body **902** with a handle portion **904** constructed from a first material, such as, for example carbon fiber, and an

25

aiming arm portion **906** constructed from a second material, such as, for example a metal or plastic.

As shown in FIG. 27, the handle portion **904** has a generally rectangular male insert **910** that is sized and shaped to fit into a generally rectangular female receiver **912** in the aiming arm portion **906**. The insert **910** has a plurality of locking holes **914** that align with a like plurality of locking holes **916** in the aiming arm portion **906** such that, when the insert **910** is inserted into the receiver **912**, the locking holes **914**, **916** align with each other to allow pins (not shown) to be inserted therein to secure the aiming arm portion **906** to the handle portion **904**.

The aiming arm portion **906** also includes an attachment location in the form of a threaded opening **950** for directly connecting the impactor discussed above to the aiming arm portion **906**.

Operation of the aiming guide **900** is similar to the operation of the aiming guide **601** as discussed above. The recon module **700** and the oblique module **800** can each be releasably secured to the aiming guide **900** to assist in aiming screw sleeves **330**, **331**, and **340**, and corresponding screws, for example, into the nail **699**.

The above detailed descriptions of embodiments of the technology are not intended to be exhaustive or to limit the technology to the precise form disclosed above. Although specific embodiments of, and examples for, the technology are described above for illustrative purposes, various equivalent modifications are possible within the scope of the technology, as those skilled in the relevant art will recognize. For example, while steps are presented in a given order, alternative embodiments may perform steps in a different order. The various embodiments described herein may also be combined to provide further embodiments.

From the foregoing, it will be appreciated that specific embodiments of the invention have been described herein for purposes of illustration, but well-known structures and functions have not been shown or described in detail to avoid unnecessarily obscuring the description of the embodiments of the technology. Where the context permits, singular or plural terms may also include the plural or singular term, respectively.

It will also be appreciated that specific embodiments have been described herein for purposes of illustration, but that various modifications may be made without deviating from the technology. Further, while advantages associated with certain embodiments of the technology have been described in the context of those embodiments, other embodiments may also exhibit such advantages, and not all embodiments need necessarily exhibit such advantages to fall within the scope of the technology. Accordingly, the disclosure and associated technology can encompass other embodiments not expressly shown or described herein.

What is claimed is:

1. An aiming guide for inserting an intramedullary nail into a bone, the aiming guide comprising:

a body having an elongate proximal handle portion and a generally arcuate distal implant alignment tip connector portion having a distal implant alignment tip extending substantially parallel to a longitudinal axis of the proximal handle portion along a tip axis,

wherein the handle portion comprises a first attachment location for releasably attaching a first module, and

wherein the distal implant alignment tip connector portion comprises a second attachment location for releasably attaching a second module,

26

wherein the second attachment location is spaced apart from the first attachment location and spaced apart from the tip axis.

2. The aiming guide according to claim 1, wherein the distal implant alignment tip is releasably connected to the distal implant alignment tip connector portion.

3. The aiming guide according to claim 2, wherein the handle portion is constructed from a first material and the distal implant alignment tip is constructed from a second material, different from the first material.

4. The aiming guide according to claim 1, wherein the proximal handle portion is releasably connected to the distal implant alignment tip connector portion.

5. The aiming guide according to claim 1, wherein the distal implant alignment tip connector portion further comprises a third attachment location for releasably attaching an impactor.

6. The aiming guide according to claim 1, wherein the distal implant alignment tip is configured to releasably retain a femoral nail.

7. The aiming guide according to claim 1, wherein the proximal handle portion comprises a hand grip.

8. The aiming guide according to claim 7, wherein the hand grip has a plurality of through holes extending there-through.

9. The aiming guide according to claim 8, wherein at least one of the plurality of through holes extends along a hole axis perpendicular to the longitudinal axis of the proximal handle portion.

10. An aiming guide assembly comprising:

a generally "J-shaped" aiming guide having an elongate proximal handle portion and a generally arcuate distal implant alignment tip connector portion having a distal implant alignment tip extending along a tip axis parallel to a longitudinal axis of the proximal handle portion; a recon module releasably attached to a proximal end of the proximal handle portion; and

an oblique module releasably attached to the distal implant alignment tip connector portion, wherein the oblique module is spaced apart along the longitudinal axis from the recon module.

11. The aiming guide assembly according to claim 10, wherein the recon module has an arcuate body having a first recon portion extending from a first side of the proximal handle portion and a second recon portion extending from a second side of the proximal handle portion, distal from the first side.

12. The aiming guide assembly according to claim 11, wherein the arcuate body has a plurality of recon through holes extending therethrough, each of the plurality of recon through holes extending along an axis intersecting the tip axis.

13. The aiming guide assembly according to claim 10, wherein the oblique module has an elongate body having a first oblique portion extending from a first side of the proximal handle portion and a second oblique portion extending from a second side of the proximal handle portion, distal from the first side.

14. The aiming guide assembly according to claim 13, wherein the elongate body has a plurality of oblique through holes extending therethrough, each of the plurality of oblique through holes extending along an axis intersecting the tip axis.

15. The aiming guide assembly according to claim 10, wherein the proximal handle portion comprises a hand grip.

16. The aiming guide assembly according to claim 15, wherein the hand grip has a plurality of hand grip through holes, each of the plurality of hand grip extending along an axis intersecting the tip axis.

17. The aiming guide assembly according to claim 10, wherein the distal implant alignment tip connector portion further comprises an attachment location for releasably attaching an impactor.

18. The aiming guide assembly according to claim 10, wherein the aiming guide comprises a unibody construction.

19. The aiming guide assembly according to claim 10, wherein the distal implant alignment tip is releasably connected to the distal implant alignment tip connector portion.

20. An aiming guide assembly comprising:

an aiming guide having an elongate proximal handle portion and a generally arcuate distal implant alignment tip connector portion having a distal implant alignment tip extending along a tip axis parallel to a longitudinal axis of the proximal handle portion;

a first attachment releasably attached to a proximal end of the proximal handle portion; and

a second attachment releasably attached to the distal implant alignment tip connector portion and spaced apart along the longitudinal axis from the first attachment.

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