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(54) **SYSTEM AND METHOD FOR SPRAYING SEEDS DISPENSED FROM A PLANTER**

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See application file for complete search history.

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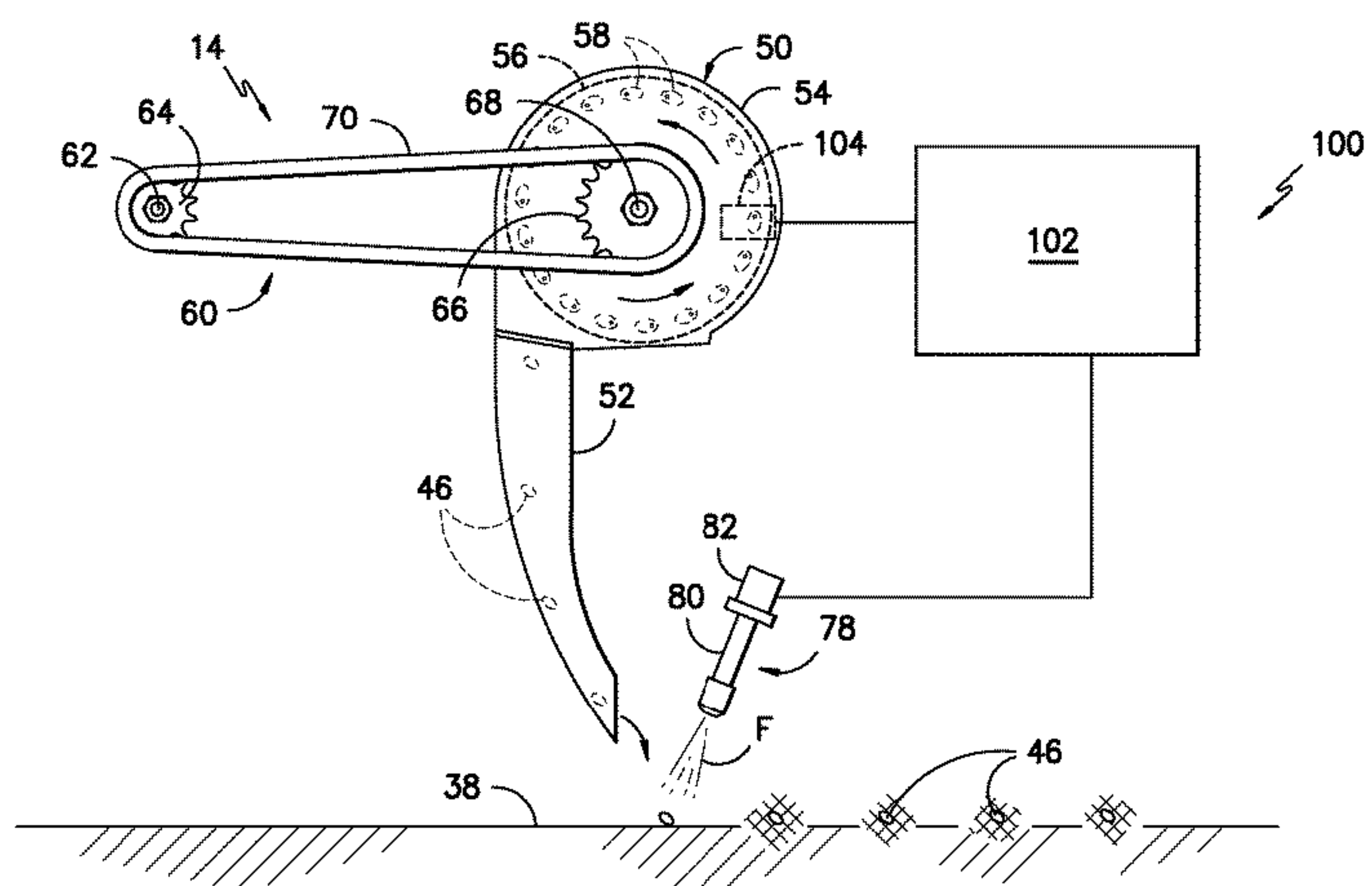
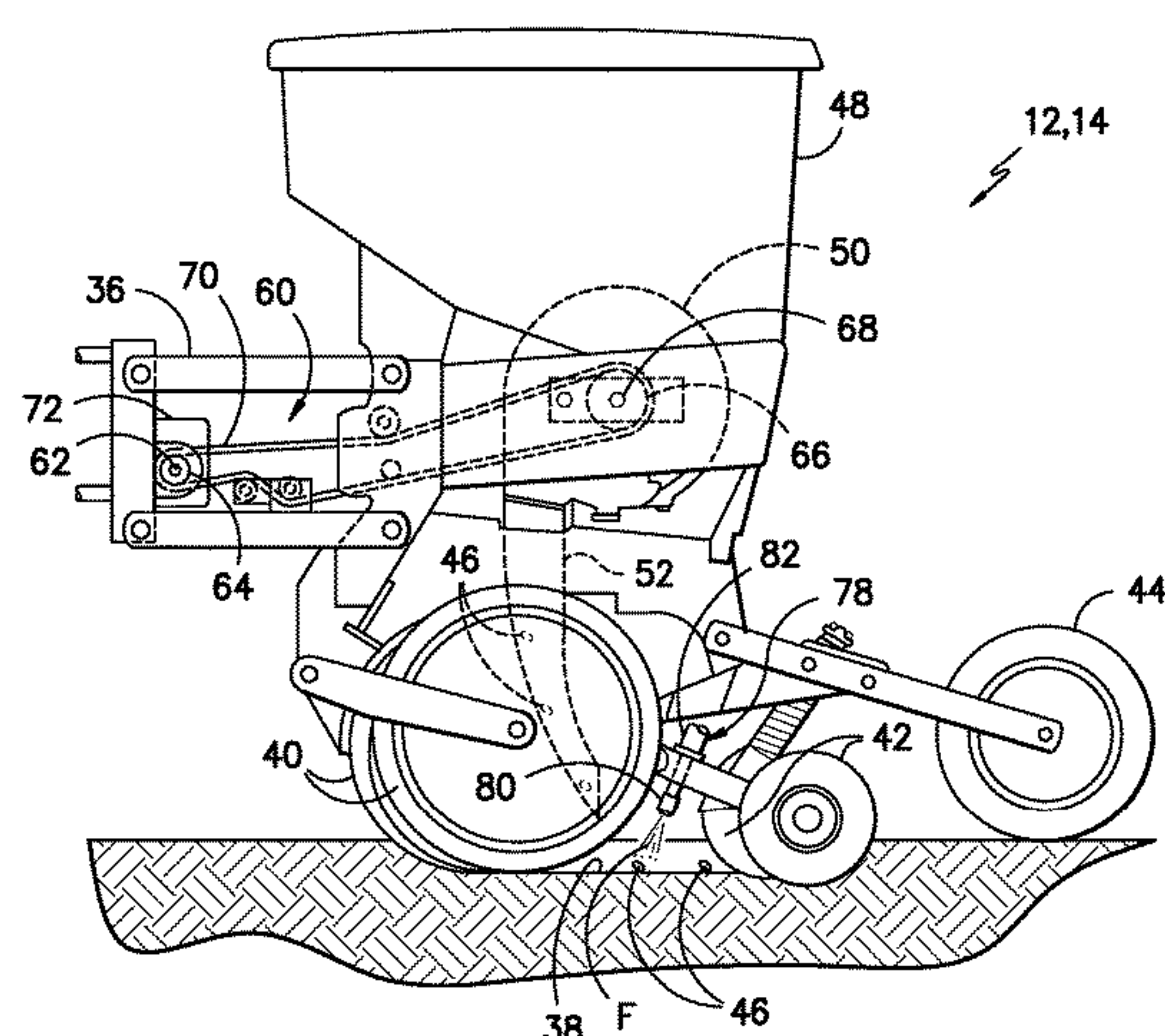
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(57) **ABSTRACT**

A system includes at least one nozzle assembly configured to spray fluid towards seeds planted within a furrow. The at least one nozzle assembly includes a valve. The system also includes a controller communicatively coupled to the valve. The controller is configured to control operation of the valve such that fluid is sprayed at least one of on or adjacent to each seed within the furrow. The system further includes a detector communicatively coupled to the controller and configured to detect a location of each spray relative to a location of a respective one of the seeds within the furrow.

21 Claims, 8 Drawing Sheets



Related U.S. Application Data

of application No. 13/869,537, filed on Apr. 24, 2013, now Pat. No. 9,226,442.

(60) Provisional application No. 61/684,964, filed on Aug. 20, 2012.

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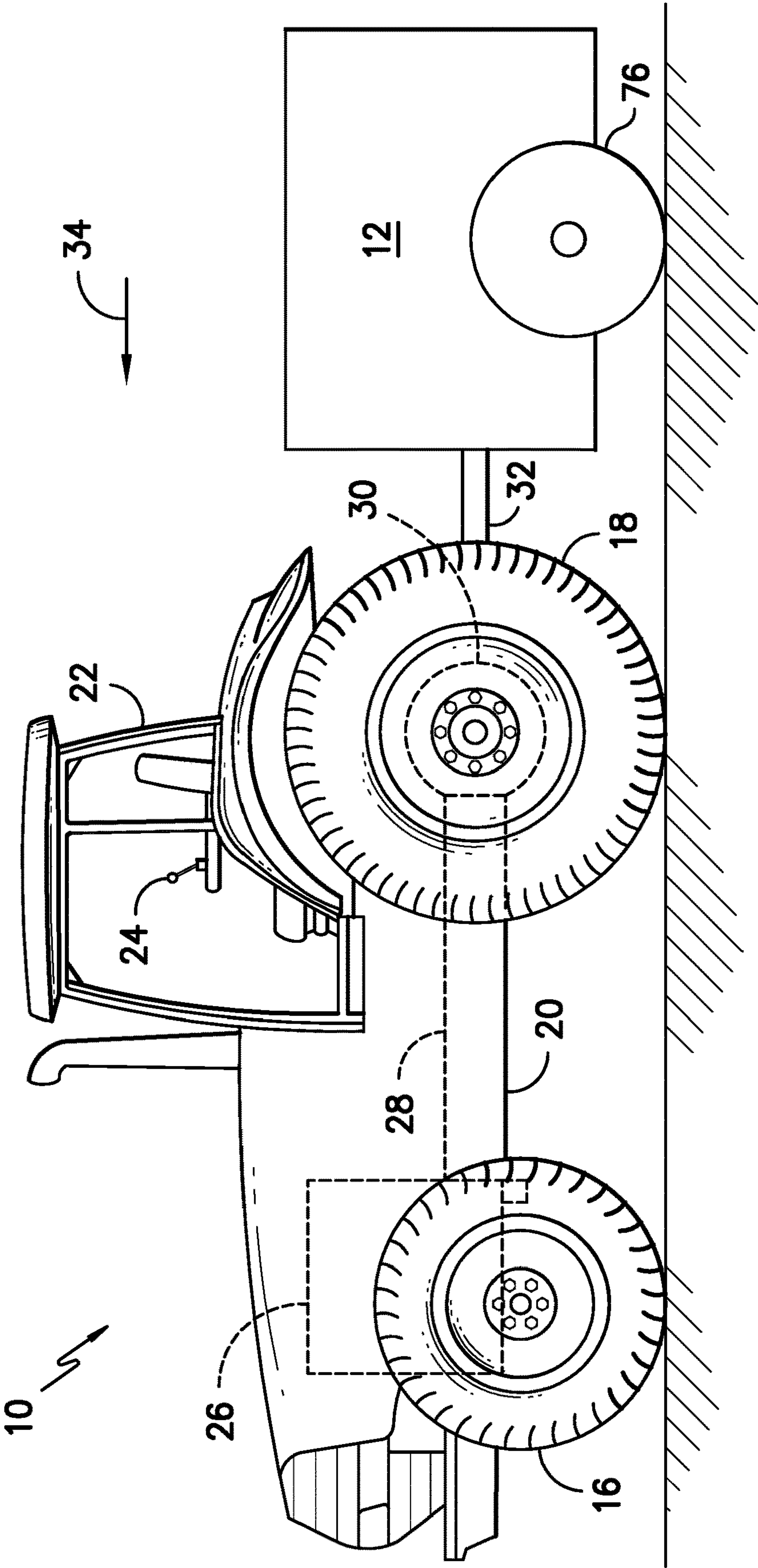
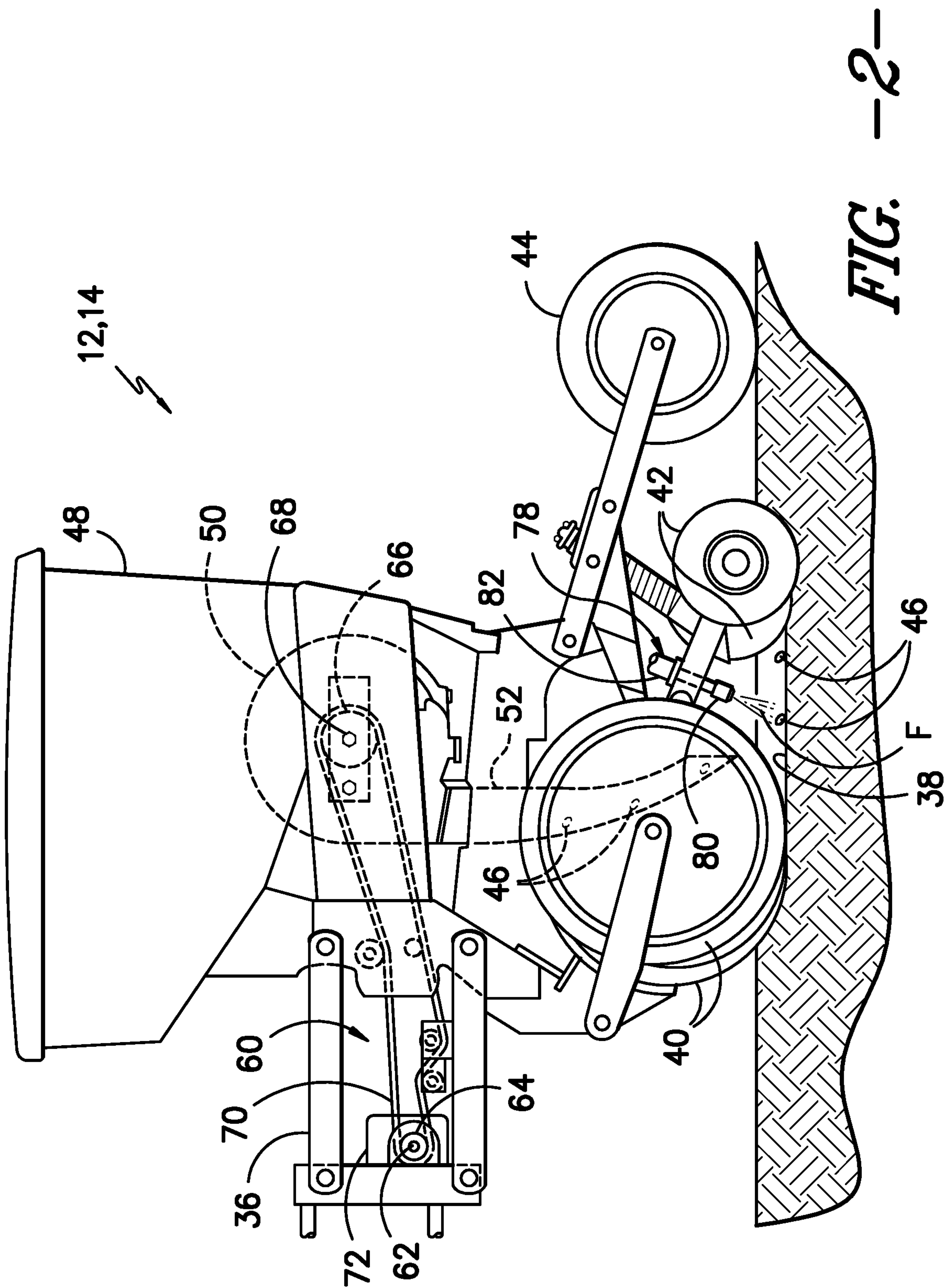


FIG. 1—



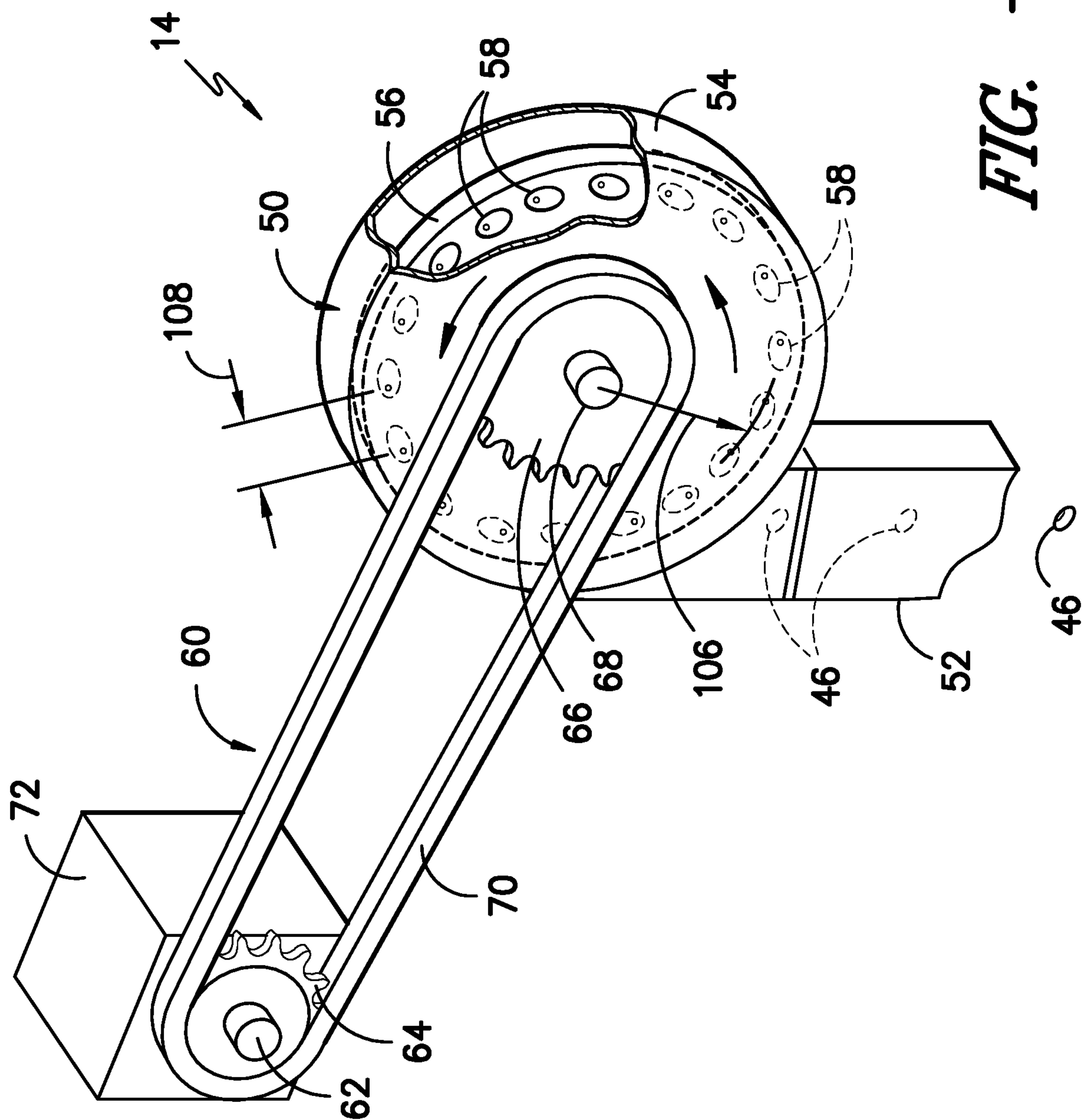


FIG. 3-

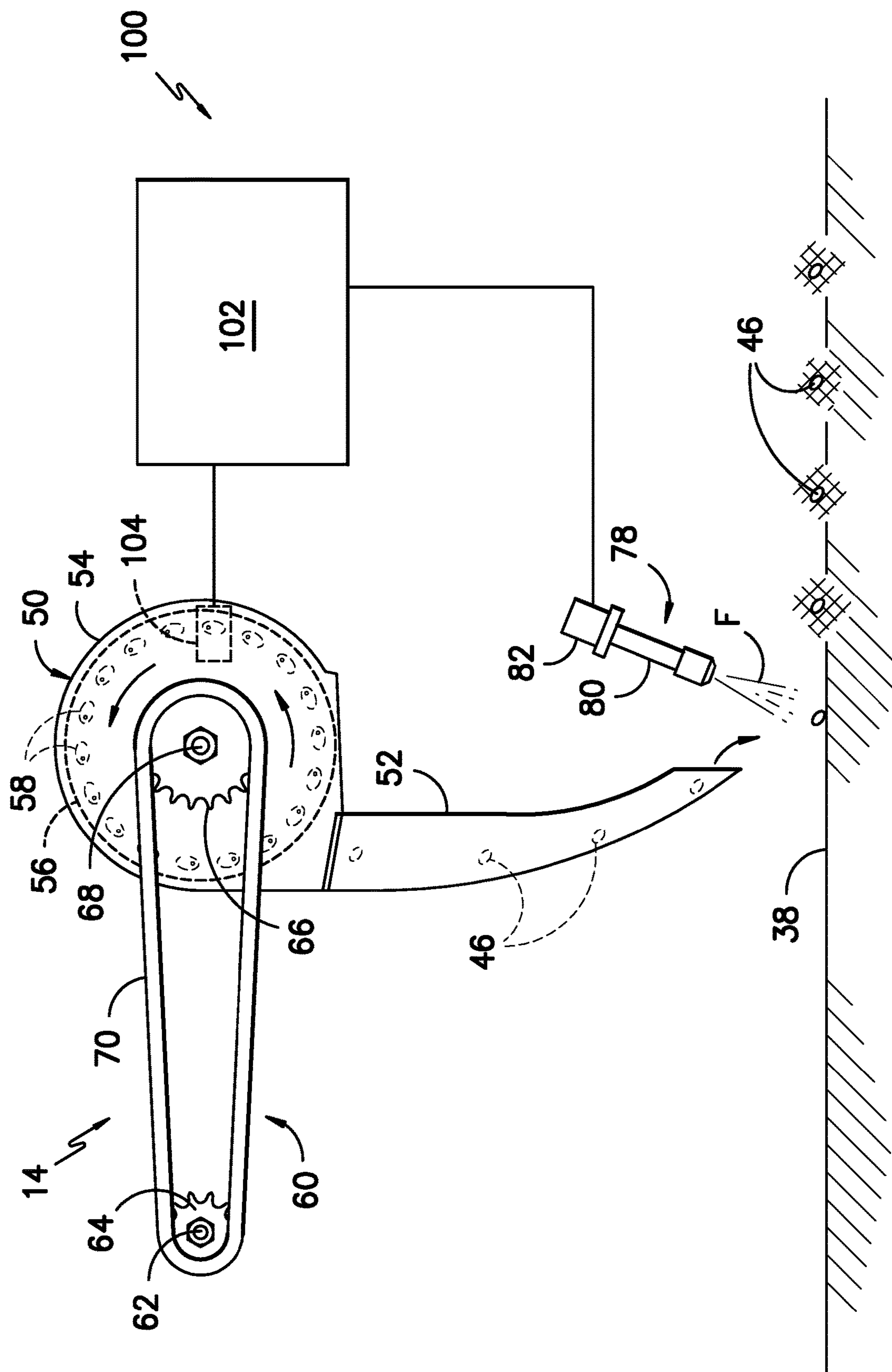


FIG. 4—

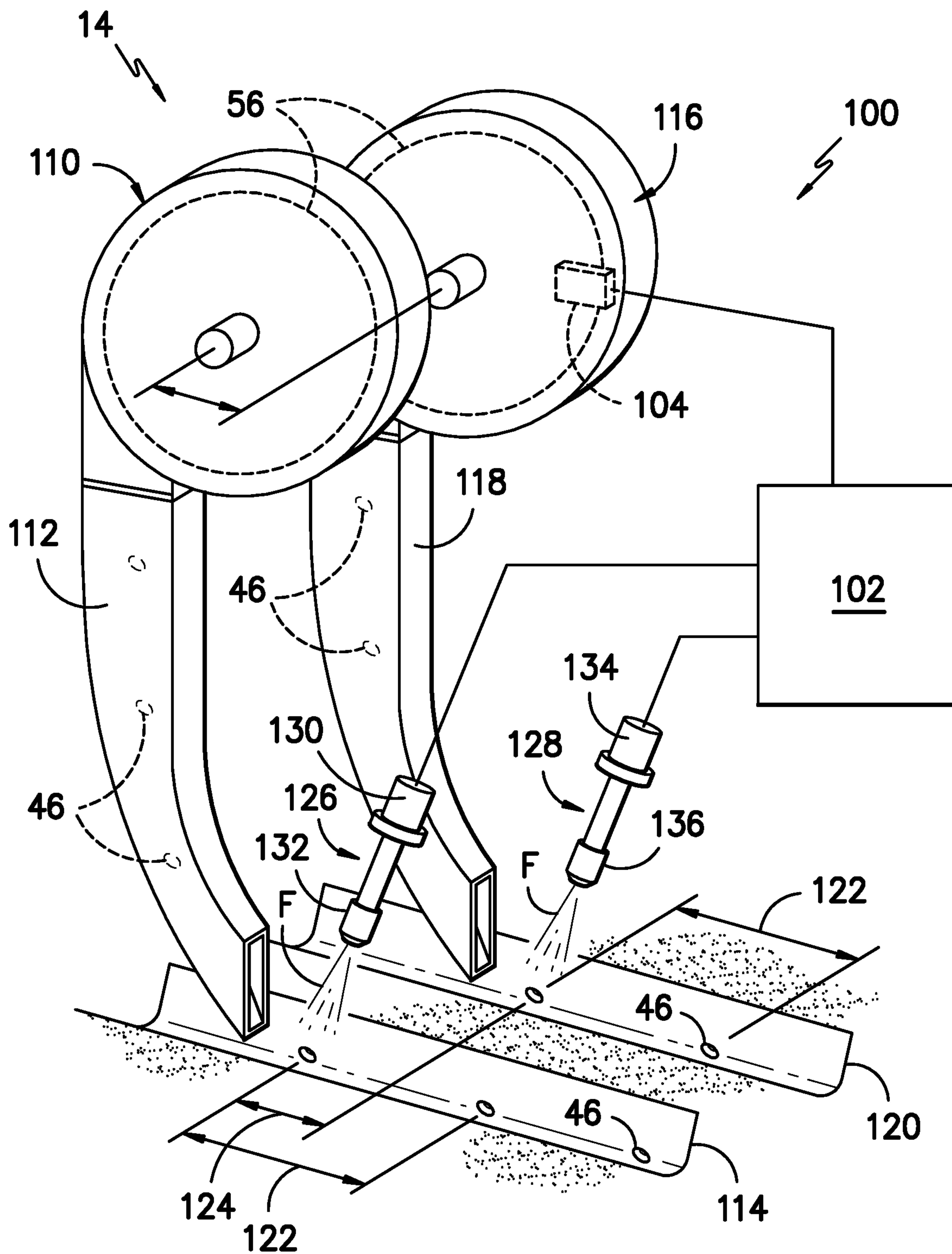


FIG. -5-

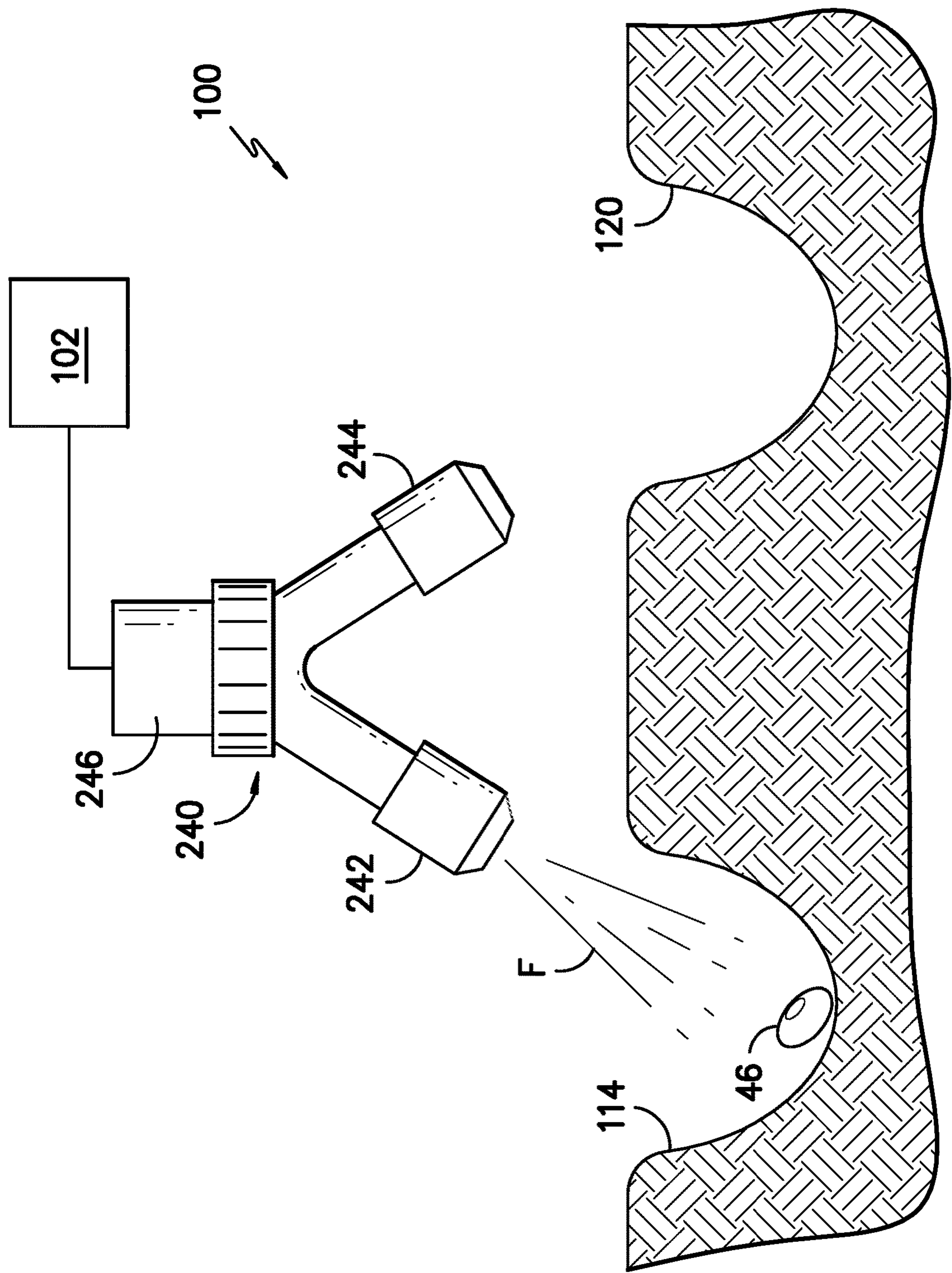


FIG. —6—

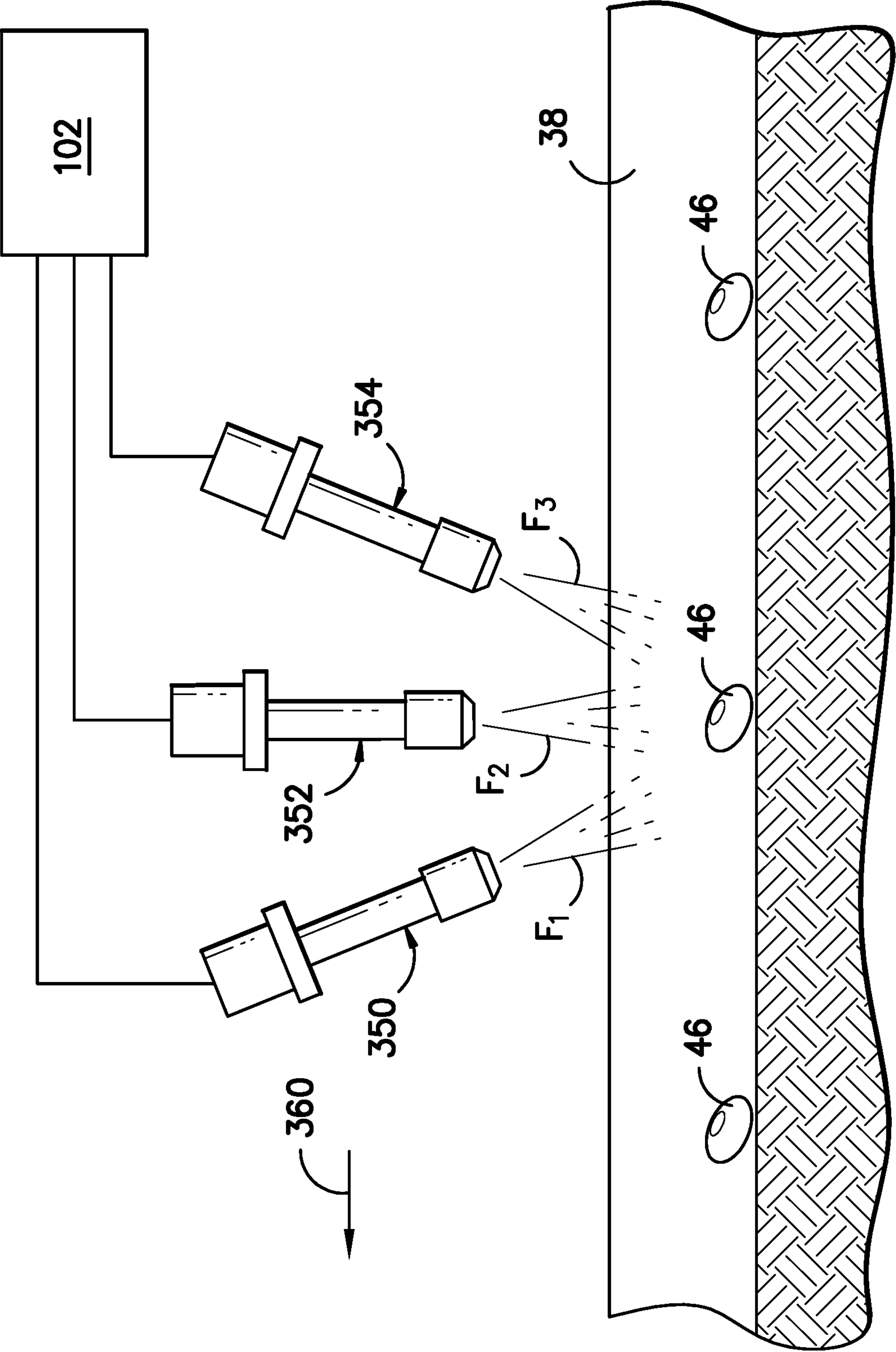


FIG. 7—

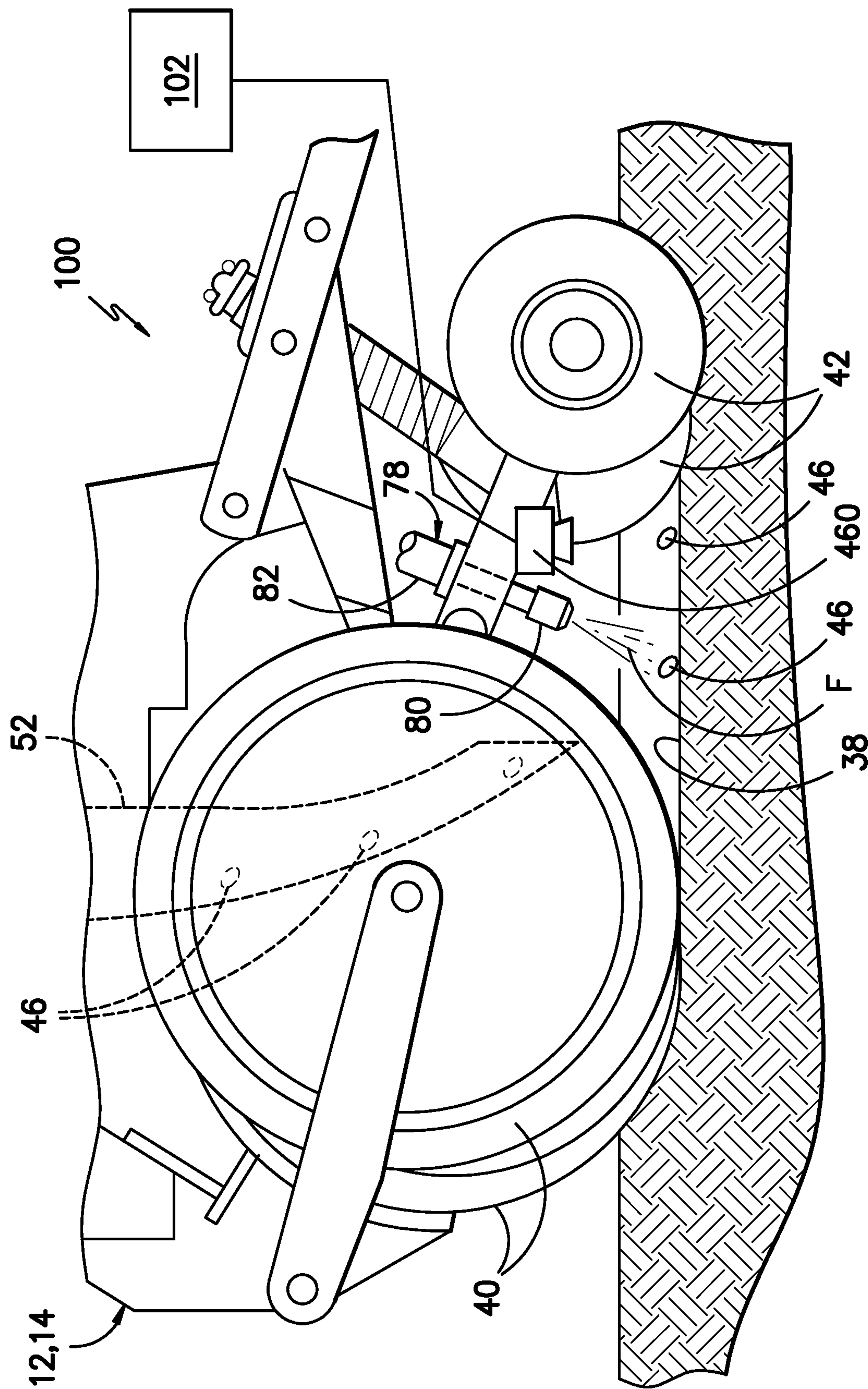


FIG. -8-

SYSTEM AND METHOD FOR SPRAYING SEEDS DISPENSED FROM A PLANTER

CROSS-REFERENCE TO RELATED APPLICATIONS

This application is a divisional of U.S. patent application Ser. No. 14/951,894, filed on Nov. 25, 2015, which is a divisional of U.S. patent application Ser. No. 13/869,537, filed on Apr. 24, 2013, which claims priority to U.S. Provisional Patent Application No. 61/684,964, filed on Aug. 20, 2012, the disclosures of which are hereby incorporated by reference in their entirety for all purposes.

FIELD OF THE INVENTION

The present subject matter relates generally to a system and method for spraying seeds and, more particularly, to a system and method for providing seed-specific placement of a fluid as seeds are planted within a furrow by an agricultural planter.

BACKGROUND OF THE INVENTION

In the agricultural industry, plants and plant precursors (e.g., seeds) are often sprayed with an agricultural fluid at the time of planting in order to enhance germination and early development. For example, when planting certain crops, it is often desirable to spray fertilizers, pesticides, insecticides, fungicides and/or various other agricultural fluids directly over and/or adjacent to seed placements. To simplify this process, various spraying systems have been developed that are designed to spray a fluid onto seeds as they are planted or otherwise distributed on and/or within the ground.

However, such conventional spraying systems are typically configured to spray a continuous band of fluid across the length of the row in which the seeds are being planted. Accordingly, a significant amount of fluid is sprayed in the areas located between the seeds, resulting in excessive waste and increased material costs. These issues have become particularly relevant given the recent trend of narrowing the spacing between crop rows. For example, in the corn growing industry, narrow row spacings (e.g., 20 inches or less) have replaced traditional row spacings (e.g., 30 inches or more) in an attempt to provide higher seed populations and a quicker canopy for weed control. However, to implement such narrow row spacings, the seed spacing along each row must be increased, thereby widening the gap between each planted seed. As a result, the waste and material costs associated with the use of conventional spraying systems is even further increased.

To avoid the problems associated with continuous band spraying systems, improved spraying systems have been developed that provide for seed-specific placement of agricultural fluids. For example, U.S. Pat. Nos. 7,370,589 and 8,074,585 (Wilkerson et al.), both of which are hereby incorporated by reference herein in their entirety for all purposes, disclose a system that utilizes a sensor to detect seeds passing through a seed tube. Upon the detection of a seed, the sensor transmits information to a controller configured to control the operation of a fluid dispenser such that the fluid dispenser dispenses fluid onto the seed at a predetermined time after the seed is detected by the sensor. However, such individual seed timing is very complex and data intensive, thereby requiring a controller with a significant amount of processor speed.

Accordingly, a system and method for providing seed-specific placement of agricultural fluids that does not rely on individual seed timing would be welcomed in the art.

BRIEF DESCRIPTION OF THE INVENTION

Aspects and advantages of the invention will be set forth in part in the following description, or may be obvious from the description, or may be learned through practice of the invention.

Various embodiments of a system and method for providing seed-specific placement of a fluid as seeds are planted within a furrow by an agricultural planter are disclosed.

In one aspect, the present subject matter is directed to a system for providing seed-specific placement of fluid as seeds are planted by a planter. The system may generally include a seed meter configured to dispense seeds into a furrow at a seed frequency and a nozzle assembly configured to spray the seeds dispensed into the furrow. The nozzle assembly may include a valve. In addition, the system may include a controller communicatively coupled to the valve. The controller may be configured to determine the seed frequency of the seed meter based on a speed-related parameter of the planter. The controller may also be configured to control the operation of the valve based on the seed frequency such that a metered amount of fluid is sprayed at least one of on or adjacent to each seed.

In this aspect, the speed-related parameter may correspond to a rotational speed of a seed disc of the seed meter.

Also in this aspect, the speed-related parameter may correspond to a speed of a component of a drive system of the planter. For example, in one embodiment, the component may comprise at least one of a shaft, a motor, a sprocket or a chain of the drive system.

Further in this aspect, the speed-related parameter may correspond to a travel speed of the planter.

In this aspect, the seed meter may include a housing and a seed disc supported within the housing. The seed disc may be configured to be rotated within the housing so as to dispense seeds from the seed meter at the seed frequency.

Also in this aspect, the system may further include a sensor configured to measure a rotational speed of the seed disc. In such an embodiment, the controller may be configured to determine the seed frequency of the seed meter based on the rotational speed of the seed disc.

Further in this aspect, the system may also include a drive system configured to rotate the seed disc within the housing. The controller may be configured to control the operation of the drive system such that a rotational speed of the seed disc is varied based on a travel speed of the planter.

In this aspect, the drive system may include a drive shaft, a first sprocket coupled to the drive shaft, a second sprocket coupled to the seed disc and a chain coupled between the first and second sprockets.

Also in this aspect, the system may further include a sensor configured to measure a component speed (e.g., a rotational or linear speed) of at least one of the drive shaft, the first sprocket, the second sprocket or the chain. In such an embodiment, the controller may be configured to determine the seed frequency of the seed meter based on the component speed.

Further in this aspect, the drive system may include a motor configured to drive the drive shaft. In such an embodiment, the controller may be configured to regulate a rotational speed of the motor based on the travel speed of the planter.

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In this aspect, the system may also include a sensor configured to measure a speed of the motor. In such an embodiment, the controller may be configured to determine the seed frequency of the seed meter based on the speed of the motor.

Also in this aspect, the system may include a sensor configured to measure a travel speed of the planter (which may also correspond to the travel speed of a work vehicle hauling the planter). In such an embodiment, the controller may be configured to determine the seed frequency of the seed meter based on the travel speed.

Further in this aspect, the controller may be configured to control the operation of the valve such that the valve operates at a pulse frequency that is the same as the seed frequency of the seed meter.

In this aspect, the controller may also be configured to regulate the pulse frequency of the valve to adjust for variations in the seed frequency.

Also in this aspect, the controller may be configured to regulate a pulse duration of the valve based on the travel speed of the planter.

In another aspect, the present subject matter is directed to a system for providing seed-specific placement of fluid as seeds are planted by a twin row planter. The system may generally include at least one planter row unit. The planter row unit may include a first seed meter configured to dispense seeds into a first furrow at a seed frequency and a second seed meter configured to dispense seeds into a second furrow at the seed frequency. The seeds dispensed into the first furrow may be offset from the seeds dispensed into the second furrow by an offset distance. The system may also include at least one nozzle assembly configured to spray the seeds dispensed into the first and second furrows. The nozzle assembly may include a valve. In addition, the system may include a controller communicatively coupled to the valve. The controller may be configured to determine the seed frequency of the first and second seed meters based on a speed-related parameter of the planter. The controller may also be configured to control the operation of the valve based on the seed frequency such that a metered amount of fluid is sprayed on or adjacent to each seed.

In this aspect, the speed-related parameter may correspond to a rotational speed of a seed disc of at least one of the first seed meter or the second seed meter.

Also in this aspect, the speed-related parameter may correspond to a speed of a component of a drive system of the planter. For example, in one embodiment, the component may comprise at least one of a shaft, a motor, a sprocket or a chain of the drive system.

Further in this aspect, the speed-related parameter may correspond to a travel speed of the planter.

In this aspect, the nozzle assembly may include a first nozzle assembly configured to spray fluid on or adjacent to the seeds dispensed from the first seed meter and a second nozzle assembly configured to spray fluid on or adjacent to the seeds dispensed from the second seed meter. The first nozzle assembly may include a first valve and the second nozzle assembly may include a second valve.

Also in this aspect, the controller may be configured to operate the first and second valves at a pulse frequency that is the same as the seed frequency of the first and second seed meters.

Further in this aspect, the first and second nozzle assemblies may be offset from one another by the offset distance. In such an embodiment, the controller may be configured to pulse the first valve simultaneously with the second valve.

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In this aspect, the controller may also be configured to alternately pulse the first and second valves.

Also in this aspect, the nozzle assembly may be configured as a double-headed spray nozzle having a valve, a first nozzle portion configured to spray fluid on or adjacent to the seeds dispensed into the first furrow and a second nozzle portion configured to spray fluid on or adjacent to the seeds dispensed into the second furrow.

Further in this aspect, the valve may be configured such that fluid is continuously sprayed through one of the first nozzle portion or the second nozzle portion.

In this aspect, the controller may be configured to control the operation of the valve such that the first and second nozzle portions are alternately turned on and off.

In a further aspect, the present subject matter is directed to a method for providing seed-specific placement of fluid as seeds are planted by an agricultural planter. The planter may include a seed meter configured to dispense seeds into a furrow and a nozzle assembly configured to spray fluid on or adjacent to the seeds dispensed into the furrow. The nozzle assembly may include a valve. In several embodiments, the method may generally include monitoring a speed-related parameter of the planter, determining a seed frequency of the seed meter based on the speed-related parameter and controlling the operation of the valve based on the seed frequency such that a metered amount of fluid is sprayed on or adjacent to each seed.

In this aspect, the speed-related parameter may correspond to a rotational speed of a seed disc of the seed meter.

Also in this aspect, the speed-related parameter may correspond to a speed of a component of a drive system of the planter. For example, in one embodiment, the component may comprise at least one of a shaft, a motor, a sprocket or a chain of the drive system.

Further in this aspect, the speed-related parameter may correspond to a travel speed of the planter.

In this aspect, the method may also include controlling the operation of the valve such that the valve operates at a pulse frequency that is the same as the seed frequency of the seed meter.

Also in this aspect, the method may include adjusting the pulse frequency of the valve to account for variations in the seed frequency.

Further in this aspect, the planter may be configured as a twin-row planter. In such an embodiment, the planter may include a first seed meter configured to dispense seeds into a first furrow and a second seed meter configured to dispense seeds into a second furrow. The planter may also include at least one nozzle assembly configured to spray fluid on or adjacent to the seeds dispensed into the first and second furrows. The nozzle assembly may include a valve.

In this aspect, the nozzle assembly may include a first nozzle assembly configured to spray fluid on or adjacent to the seeds dispensed from the first seed meter and a second nozzle assembly configured to spray fluid on or adjacent to the seed dispensed from the second seed meter. The first nozzle assembly may include a first valve and the second nozzle assembly may include a second valve.

Also in this aspect, the method may include controlling the operation of the first and second valves such that the valves operate at a pulse frequency that is the same as the seed frequency of the seed meter.

Further in this aspect, the method may include controlling the operation of the first and second valves such that the valves are pulsed simultaneously.

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In this aspect, the method may also include controlling the operation of the first and second valves such that the valves are pulsed alternately.

Also in this aspect, the nozzle assembly may be configured as a double-headed spray nozzle and may include a valve, a first nozzle portion configured to spray fluid on or adjacent to the seeds dispensed into the first furrow and a second nozzle portion configured to spray fluid on or adjacent to the seeds dispensed into the second furrow.

Further in this aspect, the method may include controlling the operation of the valve such that fluid is continuously sprayed through one of the first nozzle portion or the second nozzle portion.

In this aspect, the method may include controlling the operation of the valve such that the first and second nozzle portions are alternately turned on and off.

Also in this aspect, the method may include controlling the operation of the valve in order to align a location of each spray with a location of each seed.

These and other features, aspects and advantages of the present invention will become better understood with reference to the following description and appended claims. The accompanying drawings, which are incorporated in and constitute a part of this specification, illustrate embodiments of the invention and, together with the description, serve to explain the principles of the invention.

BRIEF DESCRIPTION OF THE DRAWINGS

A full and enabling disclosure of the present invention, including the best mode thereof, directed to one of ordinary skill in the art, is set forth in the specification, which makes reference to the appended figures, in which:

FIG. 1 illustrates a side view of one embodiment of a work vehicle and a planter for use in planting and spraying seeds;

FIG. 2 illustrates a side view of one embodiment of a row unit of the planter shown in FIG. 1;

FIG. 3 illustrates a perspective view of several components of the row unit shown in FIG. 2;

FIG. 4 illustrates a simplified, schematic view of one embodiment of a system for spraying seeds as they are planted on and/or within the ground;

FIG. 5 illustrates a simplified, schematic view of another embodiment of a system for spraying seeds as they are planted on and/or within the ground;

FIG. 6 illustrates one embodiment of a nozzle assembly that may be advantageously used when the disclosed system is implemented with a twin row planter;

FIG. 7 illustrates a simplified, schematic view of a further embodiment of a system for spraying seeds as they are planted on and/or within the ground;

FIG. 8 illustrates a close-up view of a portion of the row unit shown in FIG. 2, particularly illustrating yet another embodiment of a system for spraying seeds as they are planted on and/or within the ground.

DETAILED DESCRIPTION OF THE INVENTION

Reference now will be made in detail to embodiments of the invention, one or more examples of which are illustrated in the drawings. Each example is provided by way of explanation of the invention, not limitation of the invention. In fact, it will be apparent to those skilled in the art that various modifications and variations can be made in the present invention without departing from the scope or spirit

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of the invention. For instance, features illustrated or described as part of one embodiment can be used with another embodiment to yield a still further embodiment. Thus, it is intended that the present invention covers such modifications and variations as come within the scope of the appended claims and their equivalents.

In general, the present subject matter is directed to a system and method for providing seed-specific placement of a fluid as seeds are planted into a furrow by an agricultural planter. Specifically, in several embodiments, a controller may be configured to determine the frequency at which seeds are being dispensed into the furrow. The controller may then control the operation of a nozzle assembly such that a metered amount of fluid is sprayed on and/or adjacent to each seed. For instance, in several embodiments, the controller may be configured to pulse a valve of the nozzle assembly at the same frequency as the seed frequency to allow fluid to be automatically sprayed on and/or adjacent to each seed.

As indicated above, seed spraying systems are known that utilize individual seed timing to spray seeds dispensed from a planter. However, each row unit of a conventional planter is typically designed to space seeds very evenly along a given row and provide accurate singulation (i.e., very few doubles and skips). Moreover, planters are typically operated at a relatively slow and constant speed (e.g., 5 to 6 miles per hour (MPH)). Thus, it is believed that accurate, seed-specific fluid placement may be achieved without use of the complex methodologies required for individual seed timing. Specifically, given the consistency of conventional planters in dispensing seeds at a given frequency, the nozzle assemblies of the planter may be pulsed on and off at the same frequency as the seed frequency and shifted in order to align the spray pulses with the seed positions. Such a simplified methodology may generally reduce the amount of data that must be processed by the controller, thereby allowing for the use of less expensive controllers with slower processing speeds.

Referring now to the drawings, FIGS. 1-3 illustrate various views of embodiments of a work vehicle 10 and a planter (shown schematically as box 12) for use in planting and spraying seeds. In particular, FIG. 1 illustrates a side view of one embodiment of the work vehicle 10 and the planter 12. FIG. 2 illustrates a side view of one embodiment of a row unit 14 of the planter 12 shown in FIG. 1. Additionally, FIG. 3 illustrates a perspective view of several components of the row unit 14 shown in FIG. 2.

As shown, the work vehicle 10 may include a pair of front wheels 16, a pair or rear wheels 18 and a chassis 20 coupled to and supported by the wheels 16, 18. An operator's cab 22 may be supported by a portion of the chassis 20 and may house various control devices 24 for permitting an operator to control the operation of the work vehicle 10. Additionally, the work vehicle 10 may include an engine 26 and a transmission 28 mounted on the chassis 20. The transmission 28 may be operably coupled to the engine 26 and may provide variably adjusted gear ratios for transferring engine power to the wheels 18 via an axle/differential 30.

Additionally, as shown in FIG. 1, the work vehicle 10 may be configured to be coupled to the planter 12 via a suitable coupling 32 such that the vehicle 10 may pull the planter unit 12 as it moves in a travel direction (indicated by arrow 34). In general, the planter 12 may be configured the same as or similar to any suitable agricultural planter known the art. For example, in several embodiments, the planter 12 may include a plurality of row units 14 (one of which is shown

in FIG. 2) supported by a frame 36 (FIG. 2) extending along the width of the planter 12 (e.g., in a direction transverse to the travel direction 34).

As particularly shown in FIG. 2, each row unit 14 may include a furrow creation device. In general, the furrow creation device may be configured to create a trench or furrow 38 within the ground for planting seeds 46. In several embodiments, the furrow creation device may include a pair of laterally spaced opening discs 40, a pair of laterally spaced closing discs 42 and a press wheel 44. As is generally understood, the opening discs 40 may be configured to open a furrow 38 within the ground. Once seeds 46 have been deposited into the furrow 38, the closing discs 42 may be configured to close the furrow 38 over the seeds 46. The press wheel 44 may then compact the soil that has been closed over the seeds 46. Of course, it should be appreciated that, in the alternative embodiments, the furrow creation device may include any other suitable components and/or have any other suitable configuration known in the art.

Additionally, each row unit 14 may also include a seed hopper 48, a seed meter 50 and a seed tube 52. In general, the seed hopper 48, seed meter 50 and seed tube 52 may be configured to dispense seeds 46 into the furrow 38. For example, the seed hopper 48 may comprise any suitable container or other storage device that is configured for storing and dispensing seeds into the seed meter 50. Similarly, the seed meter 50 may comprise any suitable seed meter known in the art that is configured to dispense seeds 46 into the seed tube 52 at a metered rate. For example, as particularly shown in FIG. 3, in one embodiment, the seed meter 50 may include a housing 54 and a seed plate or disc 56 rotatably supported within the housing 54. As is generally understood, the seed disc 56 may include a plurality of indentions, channels and/or other suitable recessed features 58 that are spaced apart from one another around the seed disc 56 (e.g., in a circular array) to allow seeds 46 to be dispensed at a given frequency. Specifically, each recessed feature 58 may be configured to grab a single seed 46 (e.g., via a vacuum applied to the recessed feature 58) as such recessed feature 58 is rotated past the location at which seeds 46 are fed into the housing 54 from the seed hopper 48. Thus, as the seed disc 56 is rotated, seeds 46 may be carried by the recessed features 58 and subsequently dispensed into the seed tube 52. The seeds 46 may then fall through the seed tube 52 and into the furrow 38.

It should be appreciated that the metered rate or “seed frequency” at which seeds 46 are dispensed from the seed meter 50 may generally vary depending on the speed at which the seed disc 56 is rotated within the housing 54. For example, at a given rotational speed for the seed disc 56, the seed meter 50 may be configured to dispense seeds 46 at a constant seed frequency. Thus, when the planter 12 is being pulled at a constant speed, the seeds 46 may be spaced apart equally from one another within the furrow 38. However, as the travel speed of the planter 12 increases or decreases, the rotational speed of the seed disc 56 must also be increased or decreased to maintain equal spacing of the seeds 46 within the furrow 38. Such variation of the rotational speed of the seed disc 56 may generally be provided by a drive system 60, as described below.

In general, the drive system 60 may comprise any suitable device and/or combination of devices that is configured to rotate the seed disc 56. For example, in several embodiments, the drive system 60 may comprise a sprocket/chain arrangement. Specifically, as shown in FIGS. 2 and 3, the drive system 60 may include a drive shaft 62, a first sprocket 64 coupled to the drive shaft 62, a second sprocket 66

coupled to the seed disc 56 (e.g., via a shaft 68) and a chain 70 coupled between the first and second sprockets 64, 66. In such an embodiment, the drive shaft 62 may be configured to rotate the first sprocket 64, which may, in turn, rotate the second sprocket 66 via the chain 70. Such rotation of the second sprocket 66 may result in rotation of the shaft 68 and, thus, rotation of the seed disc 56 within the housing 54, thereby allowing for seeds 46 to be dispensed through the seed tube 52 and into the furrow 38 at a given seed frequency.

In several embodiments, the drive system 60 may be configured to vary the rotational speed of the seed disc 56 based on the travel speed of the planter 12. For example, as particularly shown in FIG. 3, in one embodiment, the drive system 60 may include a motor 72 (e.g., an electric or hydraulic motor) rotatably coupled to the drive shaft 62 that is configured to be controlled by a controller 102 (FIG. 4). Specifically, the controller 102 may be configured to receive signals associated with the travel speed of the planter 12 from a sensor or other suitable device. For instance, the controller 102 may be communicatively coupled to a speed sensor (e.g., an encoder or shaft sensor) configured to monitor the travel speed of the planter 12 by measuring the rotational speed of one or more of the wheels 76 (FIG. 1) of the planter 12 and/or one or more of the wheels 16, 18 of the work vehicle 10. Alternatively, the controller 102 may be communicatively coupled to a global positioning system (GPS) receiver or any other suitable speed sensing device that is capable of providing a measurement associated within the speed of the planter 12. Regardless, by monitoring the travel speed of the planter 12, the controller 102 may be configured to regulate the rotational speed of the motor 72 (and, thus, the rotational speed of the seed disc 56) based on the travel speed of the planter 12 such that a desired seed spacing may be achieved.

As an alternative to rotating the drive shaft 62 via a motor 72, the drive shaft 62 may be rotatably coupled to one or more of the wheels 76 of the planter 12 and/or one or more of the wheels 16, 18 of the work machine 10, thereby allowing the rotational speed of the seed disc 56 to be varied as a function of the travel speed of the planter 12. For instance, in one embodiment, a sprocket/chain arrangement, a gear arrangement or any other suitable rotatable coupling may be used to couple the drive shaft 62 to one or more of the wheels 76, 16, 18. Thus, as the planter 12 is pulled by the work machine 10 in the travel direction 34, the drive shaft 62 may be rotated as a function of the speed of the planter 12.

It should be appreciated that, in alternative embodiments, the drive system 60 may include any other combination of components and/or may have any other suitable configuration that allows the seed disc 56 to be rotated in a controlled manner. For example, instead of including the various components described above (e.g., the drive shaft 62, the first and second sprockets 64, 66 and the chain 70), the drive system 60 may simply include a motor coupled directly to the seed disc 56 via a suitable shaft. In another embodiment, the drive system 60 may include a sprocket/chain arrangement coupled directly between the seed disc 56 and one or more of the wheels 76 of the planter 12 and/or one or more of the wheels 16, 18 of the work vehicle 10.

Referring still to FIG. 2, each row unit 14 may also include at least one nozzle assembly 78 for spraying a fluid F on and/or adjacent to the seeds 46 dispensed from the seed tube 52. As shown, the nozzle assembly 78 may include a spray nozzle 80 and a solenoid valve 82. The nozzle 80 may generally comprise any suitable spray nozzle known in the

art, such as any spray nozzle typically utilized in an agricultural spraying system. Similarly, the valve **82** may comprise any suitable solenoid valve known in the art. As is generally understood, the valve **82** may be configured to be mounted to and/or integrated within a portion of the spray nozzle **80** using any suitable mounting configuration and/or any other suitable configuration known in the art that permits the flow of fluid **F** through the nozzle **80** to be modified using pulse width modulation (PWM) technology. For example, the valve **82** may be mounted to the exterior of the body of the spray nozzle **80**, such as by being secured to the spray nozzle **80** through the nozzle's check valve port. Alternatively, the valve **82** may be integrated into a portion of the body of the spray nozzle **80**.

It should be appreciated that fluid **F** may be supplied to the nozzle assembly **78** from a suitable fluid source (not shown), such as a fluid tank, via a pipe or other suitable flow conduit. In addition, a pump (not shown), such as a centrifugal pump, may be positioned upstream of the nozzle assembly **78** for pumping fluid **F** from the fluid source to the nozzle assembly **78**.

It should also be appreciated that, as an alternative to configuring the row unit **14** as a single row unit for planting seeds along a single furrow, the row unit **14** may, instead, be configured as a twin row unit for planting seeds along two closely-spaced furrows within the same harvesting row. In such an embodiment, the row units **14** may be configured the same as or similar to any suitable twin row units known in the art. For instance, in one embodiment, each row unit **14** may include two furrow creation devices for creating two adjacent furrows as well as two seed meters/tubes for dispensing seeds into each furrow. Moreover, as will be described below with reference to FIGS. **5** and **6**, each row unit **14** may also include two nozzle assemblies for spraying fluid into each furrow or, alternatively, a single nozzle assembly configured to spray fluid into both furrows.

Referring now to FIG. **4**, a simplified, schematic view of one embodiment of a system **100** for spraying seeds **46** dispensed from a row unit **14** is illustrated in accordance with aspects of the present subject matter. As shown, the system **100** may generally include a controller **102** configured to automatically control the operation of the nozzle assembly(ies) **78** of each row unit **14**. Specifically, the controller **102** may be configured to control the timing of the opening and closing of the valve **82** (e.g., by transmitting a suitable control signal to the valve **82** to cause it to open, remain open for a calculated duration, and close) so that a metered amount of fluid **F** is sprayed onto and/or adjacent to each seed **46**. For example, in several embodiments, the controller **102** may be configured to determine the frequency at which the seed meter **50** is dispensing seeds **46**, which may then be used to control the frequency of the opening and closing of the valve **82**.

In one embodiment, the controller **102** may be configured to determine the seed frequency of the seed meter **50** by directly monitoring the rotational speed of the seed disc **56**. Specifically, as shown in FIG. **4**, the controller **102** may be communicatively coupled to a suitable speed sensor **104** (e.g., an encoder or shaft sensor) mounted to or associated with the seed disc **56**. As such, signals relating to the rotational speed of the seed disc **56** may be transmitted from the sensor **104** to the controller **102**. The controller **102** may then determine the seed frequency of the seed meter **50** based on the specific design characteristics of the seed disc **56**. For example, as is generally understood, a mathematical relationship may be developed that correlates the seed frequency to the rotational speed of the seed disc **56**, the

diameter of the seed disc **56** at the location of the recessed features **58** (e.g., diameter **106** shown in FIG. **3**) and the circumferential spacing of the recessed features **58** (e.g., spacing **108** shown in FIG. **3**). This mathematical relationship may be stored within the controller **102** such that, each time a speed measurement is provided by the sensor **104**, the controller **102** may calculate the instantaneous seed frequency of the seed meter **50**.

Alternatively, the controller **102** may be configured to determine the seed frequency based on any other speed-related parameter of the planter **12**. Specifically, as indicated above, the rotational speed of the seed disc **56** and, thus, the seed frequency of the seed meter **50**, may generally be controlled by the drive system **60** of each row unit **14**. Thus, in several embodiments, the seed frequency may be determined by monitoring the speed of one or more components of the drive system **60**. For example, a speed sensor (e.g., an encoder or shaft sensor) may be mounted to or associated with a component of the drive system **60** (e.g., the motor **72**, the drive shaft **62**, the first sprocket **64**, the second sprocket **66**, the shaft **68** and/or the chain **70**) to allow the rotational or linear speed of such component to be monitored. This monitored speed may then be correlated to the seed frequency of the seed meter **50**. For example, by monitoring the rotational speed of the motor **72**, the seed frequency may be determined by analyzing both the design characteristics of the seed disc **56** (e.g., the diameter **106** and circumferential spacing **108** of the recessed features **58**) and the sprocket ratio between first and second sprockets **64**, **66**.

Moreover, since the drive system **60** may be controlled as a function of the travel speed of the planter **12**, the seed frequency may also be determined by monitoring the travel speed of the planter **12**. For instance, as indicated above, the controller **102** may be configured to receive signals from a sensor or other suitable device (e.g., a GPS receiver) associated with the travel speed of the planter **12**. This speed measurement may then be correlated to the seed frequency of the seed meter **50**.

As indicated above, by determining the frequency at which the seeds are being dropped into the furrow **38**, the controller **102** may be configured to control the operation of the nozzle assembly **78** to allow fluid **F** to be sprayed on and/or adjacent to each seed **46**. Specifically, in several embodiments, the controller **102** may be configured to pulse the valve **82** at the same frequency as the seed frequency. For instance, if seeds **46** are being dropped into the furrow at a frequency of 14 seeds per second, the controller **102** may be configured to transmit an "open" control signal to the valve **82** every 14 seconds to cause it to open (thereby allowing the nozzle assembly **78** to spray a seed **46**) and transmit a "close" control signal to the valve **82** every 14 seconds to cause it to close.

It should be appreciated that the pulse frequency of the valve **82** may be continuously regulated to adjust for changes in the seed frequency. For instance, as the travel speed of the planter **12** is increased/decreased (thereby necessitating an increase/decrease in the seed frequency to maintain a desired seed spacing), the pulse frequency of the valve **82** may be similarly increased/decreased to ensure that each seed is sprayed.

In addition, when the system **100** is initiated, it may be necessary to adjust the timing of the valve operation in order to align each spray pulse with a corresponding seed **46**. For example, even though the nozzle assembly **78** may be spraying fluid at the same frequency as the seed frequency, the location of each spray may be offset from the location of each seed **46**. To address this issue, in one embodiment, the

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spray locations may be shifted manually by the operator (e.g., by inputting an offset value into a control panel location in the operator's cab **22** of the work vehicle **10**). For instance, after operating the system **100** for a short period of time, the operator may check the alignment of each spray location with each seed location. This may simply be a visual check or the operator may check the spray/seed alignment using a suitable spray detector. For example, an additive (e.g., a radioactive trace and/or any other suitable detectable chemical) may be added to the fluid being sprayed on and/or adjacent to each seed **46**. In such an embodiment, the spray detector may be passed over the ground to detect each spray location. The detected spray locations may then be compared to the corresponding seed locations (e.g., by digging up the planted seeds **46**). In the event that the spray locations are offset from the seed locations, the operator may input an offset value (e.g., two inches) into the control panel. The controller **102** may then shift the spray locations forward or backwards to ensure proper alignment with the seeds **46**. It should be appreciated that, in addition to adding a detectable additive to the fluid being sprayed, a detectable coating may also be applied to the seeds **46**. As such, a suitable detector(s) may be used to automatically detect both the spray locations and the seed locations, thereby providing an efficient means for comparing the relative spray/seed locations.

Alternatively, the spray locations may be automatically detected and adjusted by the controller **102**. For instance, in one embodiment, the controller **102** may be communicatively coupled to a vision system (e.g., a camera or any other suitable imaging device) configured to capture images of the location of each spray relative to the location of each seed. In such an embodiment, the controller **102** may include suitable image processing algorithms for detecting the location of and determining the offset between each spray/seed. The controller **102** may then automatically adjust the spray locations based on the determined offset to align each spray with a corresponding seed **46**. It should be appreciated that, as an alternative to automatically analyzing the images captured by the vision system, the images may be displayed to the operator on a suitable display panel. The operator may then manually adjust the alignment of the spray locations with the seed locations based on the displayed images.

It should be appreciated by those of ordinary skill in the art that, with the exception of twin row planters, the row units of an agricultural planter are typically operated independent of one another. As a result, each row unit may require an independent shift in order to align each spray location with each seed location. However, in the event that the row units are timed together or are otherwise operated in sync, a single, global shift may be applied to each row unit in order to align the spray locations with the seed locations.

Moreover, the controller **102** may also be configured to regulate the pulse duration of the valve **82** (i.e., the time period between the transmission of the "open" and "close" control signals) in order to control the spray band length, spray volume per seed, etc. For instance, if a constant spray band length is desired (e.g., a spray band starting an inch before each seed **46** and extending one inch after each seed **46**), the controller **102** may be configured to regulate the pulse duration of the valve **82** based on the travel speed of the planter **12** in order to achieved the desired band length. Similarly, if a constant spray volume is desired, the controller **102** may be configured to regulate the pulse duration of the valve **82** based on various operating parameters of the system **100**, such as the pressure of the fluid **F** supplied to the valve **82**, the valve configuration (e.g., the sizes of the

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inlet and/or outlet of the valve **382**), the nozzle configuration (e.g., the spray tip orifice size) and/or any other suitable operating parameters.

Referring now to FIG. **5**, another embodiment of the disclosed system **100** is illustrated in accordance with aspects of the present subject matter, particularly illustrating an embodiment in which the planter **12** is configured as a twin row planter and, thus, includes row units **14** configured to dispense seeds into two adjacently disposed furrows. As shown, each row unit **14** may include a first seed meter **110** and a first seed tube **112** for dispensing seeds **46** into a first furrow **114** and a second seed meter **116** and a second seed tube **118** for dispensing seeds **46** into a second furrow **120**. In such an embodiment, the seed discs **56** of the first and second seed meters **110**, **116** may generally be configured to be rotated at the same speed (based on the travel speed of the planter **12**) so that the seeds **46** are dispensed into the first and second furrows **114**, **120** at the same seed frequency, thereby allowing for a constant seed spacing within the furrows **114**, **120** (shown as spacing distance **122** in FIG. **5**). For instance, the drive system **60** (FIG. **3**) for each seed meter **110**, **116** may be rotatably coupled to the same drive shaft **62** (FIG. **3**) to ensure that the seed discs **56** are rotated at the same speed.

Additionally, as is generally understood, the seeds **46** dispensed within the first furrow **114** may be offset from the seeds **46** dispensed within the second furrow **120**. To provide for such alternation of the seeds **46** between the adjacent furrows **114**, **120**, the first seed meter and tube **110**, **112** may, in one embodiment, be offset from the second seed meter and tube **116**, **118** by an offset distance **124** (e.g., a distance equal to one-half the seed spacing distance **122**). As such, when the seed meters **110**, **116** are dispensing seeds simultaneously, the seeds **46** dropped into the first furrow **114** may be offset from the seeds **46** dropped into the second furrow **120** by the offset distance **124**. Alternatively, instead of offsetting the seed meters/tubes, the first and second seed meters **110**, **116** may be operated 180° out-of-phase such that the seeds **46** dispensed into the first and second furrows **114**, **120** are offset from one another by the offset distance **124**.

Referring still to FIG. **5**, in several embodiments, a separate nozzle assembly **126**, **128** may be associated with each seed meter/tube. Specifically, as shown in FIG. **4**, a first nozzle assembly **126** (including a first valve **130** and a first spray nozzle **132**) may be configured to spray fluid **F** on and/or adjacent to each seed **46** dispensed into the first furrow **114** while a second nozzle assembly **128** (including a second valve **134** and a second spray nozzle **136**) may be configured to spray fluid **F** on and/or adjacent to each seed **46** dispensed into the second furrow **120**. In such an embodiment, the controller **102** may be configured to control the operation of each nozzle assembly **126**, **128** (e.g., by controlling the first and second valves **130**, **134**) based on the seed frequency of the seeds meters **110**, **116** to ensure that each seed is sprayed with a metered amount of fluid **F**. As indicated above, both seed meters **110**, **116** may be configured to dispense seeds **46** at the same seed frequency. As such, the controller **102** may be configured to determine the seed frequency of the seed meters **110**, **116** by simply monitoring a speed-related parameter related to either seed meter **110**, **116**. For instance, as shown in FIG. **5**, in one embodiment, a suitable sensor **104** may be mounted to or otherwise associated with the seed disc **56** of one of the seed meters **110**, **116** to allow for the seed frequency of both of the seed meters **110**, **116** to be determined. Alternatively, as described above, the seed frequency may be determined by monitoring the speed of a component of the drive system **60**

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(FIG. 3) associated with one of the seed meters 110, 116 and/or by monitoring the overall travel speed of the planter unit 12.

The controller 102 may then be configured to pulse the valves 130, 134 of the first and second nozzle assemblies 126, 128 at the same frequency as the seed frequency. In doing so, the controller 102 may, in several embodiments, be configured to open and close the first and second valves 130, 134 simultaneously. For instance, in embodiments in which the first and second nozzle assemblies 126, 128 are offset from one another by the offset distance 124, the valves 130, 134 may be controlled such that both nozzle assemblies 126, 128 are turned on and off at the same time, thereby allowing the seeds 46 within both furrows 114, 120 to be sprayed simultaneously.

Alternatively, the controller 102 may be configured to alternately open and close the valves 130, 134 as each nozzle assembly 126, 128 passes over a seed 46 within its respective furrow 114, 120. Specifically, the controller 102 may be configured to control the valves 130, 134 such that, when the first valve 130 is opened, the second valve 134 is closed and vice versa. Such control of the valves 130, 134 may generally allow for alternating spray bands to be sprayed across the seeds 46. For instance, assuming that the seeds 46 are being planted with a 12 inch spacing (i.e., distance 122) and a six inch offset (i.e., distance 124), the first and second valves 130, 134 may be alternately opened and closed such that the first and second nozzle assemblies 126, 128 spray six inch bands across each seed 46 within their respective furrows 114, 120 (e.g., spray bands extending three inches before and three inches after each seed 46).

It should be appreciated that, by alternating the opening and closing of the valves 130, 134, a continuous flow of fluid F may be provided through the system 100, thereby preventing any undesirable pressure or flow pulses/surges (e.g., due to the continuous operation of an upstream pump). Additionally, by providing an uninterrupted flow of fluid F, the disclosed system 100 may be retrofitted into conventional planters without altering the calibration, flow rate and/or fluid pressure settings of the planter.

It should also be appreciated that, as an alternative to having two separate nozzle assemblies 126, 128, the disclosed system 100 may include a single nozzle assembly configured to spray fluid F on and/or adjacent to the seeds 46 disposed in both the first and second furrows 114, 120. For example, FIG. 6 illustrates one embodiment of a nozzle assembly 240 that may be advantageously used when the disclosed system 100 is implemented with a twin row planter. As shown, the nozzle assembly 240 includes a doubled-headed spray nozzle having a first nozzle portion 242 configured to spray fluid F into the first furrow 114 and a second nozzle portion 244 configured to spray fluid F into the second furrow 120. Additionally, the nozzle assembly 240 includes a valve 246 operably coupled to the spray nozzle 242, 244.

In general, the valve 246 may be configured such that the flow of fluid F is only directed through one nozzle portion 242, 244 at a time. For instance, the valve 246 may be configured to allow fluid F to flow through the first nozzle portion 242 when a poppet or actuator of the valve 246 is in an open position and through the second nozzle portion 244 when the actuator is in a closed position. As such, the valve 246 may be controlled based on the seed frequency of the first and second seed meters 110, 116 to allow the seeds 46 within the first and second furrows 114, 120 to be alternately sprayed. For instance, assuming again that the seeds 46 are being planted with a 12 inch spacing (i.e., distance 122) and

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a six inch offset (i.e., distance 124), the valve 246 may be controlled such that the first nozzle portion 242 is turned on and sprays a six inch spray band as the nozzle assembly 240 travels past a seed 46 within the first furrow 114. The flow of fluid F may then be switched to the second nozzle portion 244 such that a six inch spray band may be sprayed as the nozzle assembly 240 travels past a seed 46 within the second furrow 120.

Referring now to FIG. 7, in several embodiments, the disclosed system 100 may include a plurality of nozzle assemblies 350, 352, 354 configured to spray one or more fluids (e.g., fluids F1, F2 and F3) on and/or adjacent to the seeds 46 located within a single furrow 38. In such embodiments, the operation of each nozzle assembly 350, 352, 354 may be controlled based on the seed frequency determined by the controller 102.

For example, as shown in FIG. 7, the disclosed system 100 may include a first nozzle assembly 350, a second nozzle assembly 352, and a third nozzle assembly 354 communicatively coupled to the controller 102. In one embodiment, the nozzle assemblies 350, 352, 354 may be controlled so as to simultaneously spray fluid on and/or adjacent to each seed 46. Specifically, as shown in the illustrated embodiment, the nozzle assemblies 350, 352, 354 may be controlled such that the second nozzle assembly 352 sprays fluid F2 directly onto each seed 46 while the first and third nozzle assemblies spray fluids F1 and F3, respectively, onto either side of each seed 46. Alternatively, the timing of the nozzle assemblies 350, 352, 354 may be offset from one another. For instance, in embodiments in which each nozzle assembly 350, 352, 354 is configured to spray fluid F1, F2, F3 directly onto each seed 46, the controller 102 may be configured to activate each nozzle assembly 350, 352, 354 separately as it passes over a given seed 46. Thus, in the illustrated embodiment (assuming a travel direction shown by arrow 360), the first nozzle assembly 350 may be initially activated as it passes over a seed 46, with the second and third nozzle assemblies 352, 354 being subsequently activated to allow each nozzle assembly 350, 352, 354 to spray fluid F1, F2, F3 directly onto the seeds 46.

It should be appreciated that, in embodiments in which the disclosed system 100 includes multiple nozzle assemblies 350, 352, 354 for spraying fluids on and/or adjacent to seeds 46 located within the same furrow 38, the nozzle assemblies 350, 352, 354 may have the same or different configurations. For instance, as shown in FIG. 7, the nozzle assemblies 350, 352, 354 may be mounted at different orientations relative to the ground and/or to one another to allow for differing spray placements to be achieved. Similarly, each nozzle assembly 350, 352, 354 may be configured to spray fluid at the same or different spraying parameters, such as the same or different flow rates, pressures, spray patterns and/or the like.

Referring now to FIG. 8, as indicated above, the disclosed system 100 may also include a suitable means for automatically detecting the location of each spray relative to the location of each seed 46. For instance, as shown in FIG. 8, a suitable sensor or detector 460 may be mounted to each row unit 14 in order to detect the locations of each spray/seed, such as by mounting the detector 460 at a position on each row unit 14 at which the seed and spray locations may be detected prior to the furrow 38 being closed over the seeds 46 by the closing discs 42.

In general, the detector 460 may comprise any suitable sensor, camera, scanner and/or the like that is capable of automatically detecting the location of each spray/seed. For example, as indicated above, the detector 460 may simply comprise a digital camera configured to capture images of

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the location of each spray relative to each seed **46**. In another embodiment, the detector **460** may comprise a hyperspectral sensor, an ultraviolet (UV) camera or sensor, an infrared (IR) camera or sensor and/or any other suitable imaging device capable of detecting light across one or more ranges within the light wavelength spectrum, including, but not limited to, UV light wavelengths, IR light wavelengths, visible light wavelengths and/or the like. In such an embodiment, a UV and/or IR tracer may be added into the fluid **F** being sprayed while each seed **46** may be coated with a different UV and/or IR tracer. The detector **460** may then be capable of both detecting and distinguishing the UV and/or IR light emitted from each spray and the UV and/or IR light emitted from each seed **46**. In a further embodiment, the detector **460** may comprise a radioactive scanner or sensor (e.g., a Geiger counter) configured to detect low level radioactive tracers. In such an embodiment, a radioactive tracer may be added into the fluid **F** being sprayed while each seed **46** may be coated with a different radioactive tracer. The detector **460** may then detect the position of each spray/seed by detecting the radiation given off at each spray/seed location.

Additionally, as shown in FIG. **2**, the detector **460** may be communicatively coupled to the controller **102** such that the measurement/detection signals generated by the detector **460** may be transmitted to the controller **102** for subsequent processing/analysis. For instance, in several embodiments, the controller **102** may be configured to analyze the signals received from the detector **460** in order to determine the relative locations of each spray/seed, such as by comparing each seed location to its corresponding spray location in order to determine the spacing between each seed/spray. Similarly, based on the signals received from the detector **460**, the controller **102** may be configured to plot the location of each spray relative to the location of each seed **46**. In such an embodiment, the plot may be displayed to the operator via a suitable display panel located within the operator's cab **22** of the work vehicle **10**. The operator may then, if desired, adjust the system settings in order to adjust the relative locations of each spray/seed.

It should be appreciated that the controller **102** described herein may generally comprise any suitable computer and/or other processing unit, including any suitable combination of computers, processing units and/or the like that may be operated independently or in connection within one another. Thus, in several embodiments, the controller **102** may include one or more processor(s) and associated memory device(s) configured to perform a variety of computer-implemented functions. As used herein, the term "processor" refers not only to integrated circuits referred to in the art as being included in a computer, but also refers to a controller, a microcontroller, a microcomputer, a programmable logic controller (PLC), an application specific integrated circuit, and other programmable circuits. Additionally, the memory device(s) of the controller **102** may generally comprise memory element(s) including, but not limited to, computer readable medium (e.g., random access memory (RAM)), computer readable non-volatile medium (e.g., a flash memory), a floppy disk, a compact disc-read only memory (CD-ROM), a magneto-optical disk (MOD), a digital versatile disc (DVD) and/or other suitable memory elements. Such memory device(s) may generally be configured to store suitable computer-readable instructions that, when implemented by the processor(s), configure the controller **102** to perform various functions including, but not limited to, controlling the operation of the valves **82**, **246**, determining the seed frequency of the seed meters **50**, **110**, **116** and/or various other suitable computer-implemented functions.

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It should also be appreciated that, although the system **100** is described herein with reference to spraying seeds **46**, the system **100** may generally be utilized to spray any suitable type of plant and/or plant precursor, such as seeds, seedlings, transplants, encapsulated tissue cultures and/or any other suitable plant precursors.

This written description uses examples to disclose the invention, including the best mode, and also to enable any person skilled in the art to practice the invention, including making and using any devices or systems and performing any incorporated methods. The patentable scope of the invention is defined by the claims, and may include other examples that occur to those skilled in the art. Such other examples are intended to be within the scope of the claims if they include structural elements that do not differ from the literal language of the claims, or if they include equivalent structural elements with insubstantial differences from the literal languages of the claims.

The invention claimed is:

1. A system for providing seed-specific placement of fluid, the system comprising:

at least one nozzle assembly configured to spray fluid towards seeds planted within a furrow, the at least one nozzle assembly including a valve;

a controller communicatively coupled to the valve, the controller being configured to control operation of the valve such that fluid is sprayed at least one of on or adjacent to each seed within the furrow; and

a detector communicatively coupled to the controller and configured to detect a location of each spray relative to a location of a respective one of the seeds within the furrow.

2. The system of claim **1**, wherein the controller is configured to adjust at least one operating parameter of the system to align the location of each spray with the location of the respective one of the seeds within the furrow.

3. The system of claim **2**, wherein the controller is configured to adjust the at least one operating parameter to align the location of each spray with the location of the respective one of the seeds within the furrow based on an operator input.

4. The system of claim **2**, wherein the controller is configured to automatically adjust the at least one operating parameter to align the location of each spray with the location of the respective one of the seeds within the furrow based on an operator input.

5. The system of claim **4**, wherein the controller is further configured to:

determine an offset distance between the location of each spray and the location of the respective one of the seeds within the furrow;

compare the offset distance to a predetermined value; and automatically adjust the at least one operating parameter of the system based on the determined offset distance.

6. The system of claim **1**, wherein the detector comprises a camera configured to capture images of the location of each spray and the respective one of the seeds within the furrow.

7. The system of claim **1**, wherein the detector comprises a sensor configured to detect light emitted by the fluid and the seeds.

8. The system of claim **7**, wherein the fluid includes a first tracer, and wherein each seed includes a second tracer, and wherein the detector is configured to distinguish the first tracer from the second tracer.

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9. The system of claim 1, wherein the controller is configured to plot the location of each spray relative to the location of each seed.

10. The system of claim 9 further comprising a display configured to display the plot.

11. The system of claim 10 further comprising an input device configured to receive an operator input for adjusting at least one operating parameter of the system based on the plot.

12. A method for providing seed-specific placement of fluid, the method comprising:

spraying fluid from at least one nozzle assembly towards seeds planted within a furrow, the at least one nozzle assembly including a valve;

controlling operation of the valve such that fluid is sprayed at least one of on or adjacent to each seed within the furrow;

detecting, using a detector, a location of each spray relative to a location of a respective one of the seeds within the furrow; and

determining, using a controller communicatively connected to the detector, an offset distance between the location of each spray and the location of the respective one of the seeds.

13. The method of claim 12 further comprising comparing the offset distance to a predetermined value.

14. The method of claim 12 further comprising adjusting operation of the valve to align the location of each spray with the location of the respective one of the seeds within the furrow.

15. The method of claim 12 further comprising capturing images of the location of each spray and the respective one of the seeds within the furrow.

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16. The method of claim 12 further comprising sensing, using a sensor, a characteristic of the fluid and the seeds.

17. The method of claim 16, wherein the fluid includes a first tracer and each seed includes a second tracer, the method further comprising distinguishing each spray from each seed based on the first tracer and the second tracer.

18. The method of claim 12 further comprising plotting the location of each spray relative to the location of each seed.

19. A system for providing seed-specific placement of fluid as seeds are planted into a furrow by a planter, the system comprising:

a planter row unit including a seed meter configured to dispense seeds into a furrow at a seed frequency;

at least one nozzle assembly configured to spray fluid towards the seeds dispensed into the furrow, the at least one nozzle assembly including a valve;

a controller communicatively coupled to the valve, the controller being configured to control operation of the valve based on the seed frequency such that fluid is sprayed at least one of on or adjacent to each seed; and

a detector communicatively coupled to the controller and configured to detect a location of each spray relative to a location of a respective one of the seeds within the furrow.

20. The system of claim 19, wherein the detector is mounted to the planter row unit at position at which the location of each spray relative to the location of the respective one of the seeds is detected prior to the furrow being closed.

21. The system of claim 19, wherein the detector comprises at least one of a sensor and a camera.

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