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(54) **IRRADIATION TREATMENT PLAN SYSTEM AND METHOD**

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See application file for complete search history.

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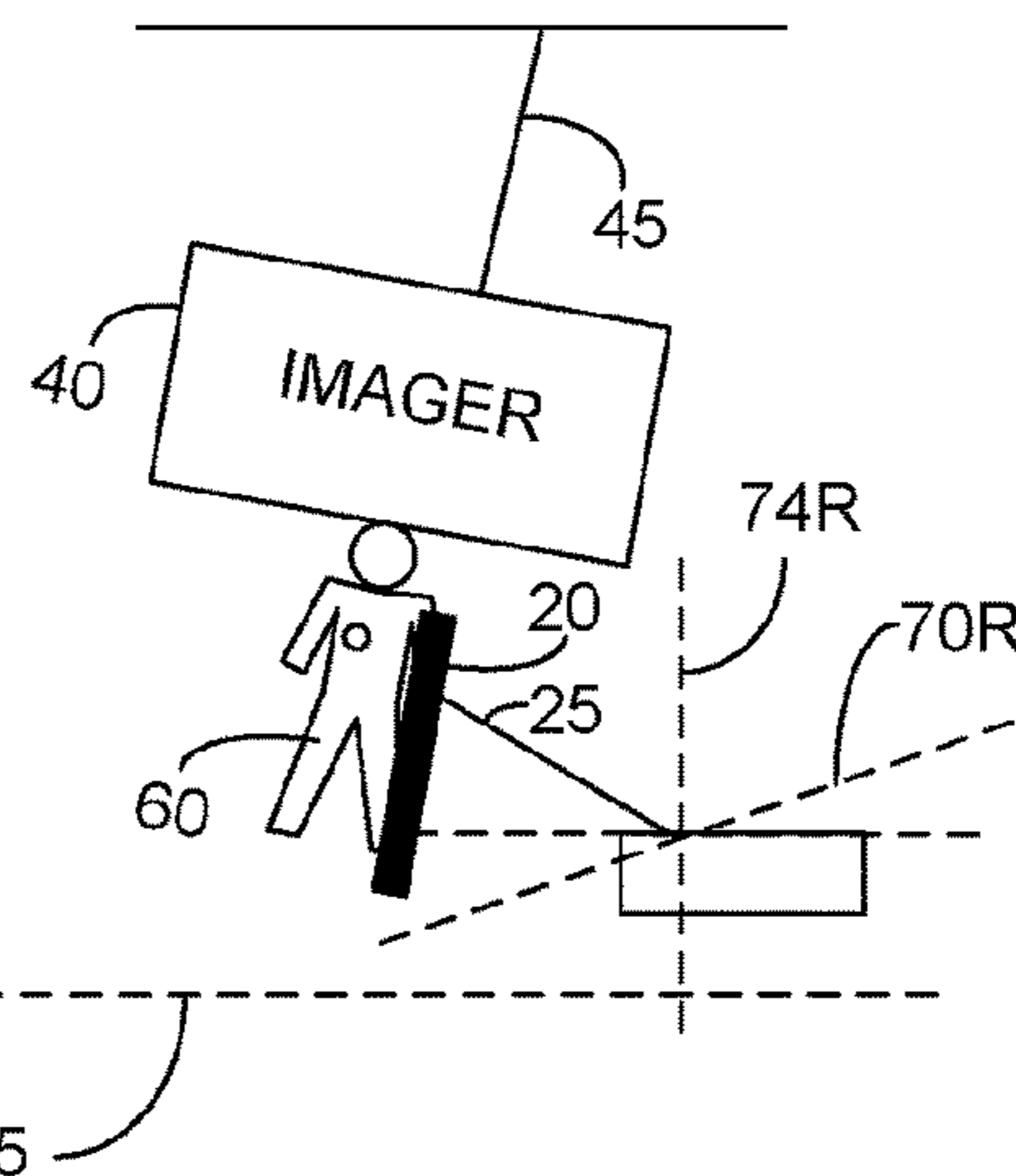
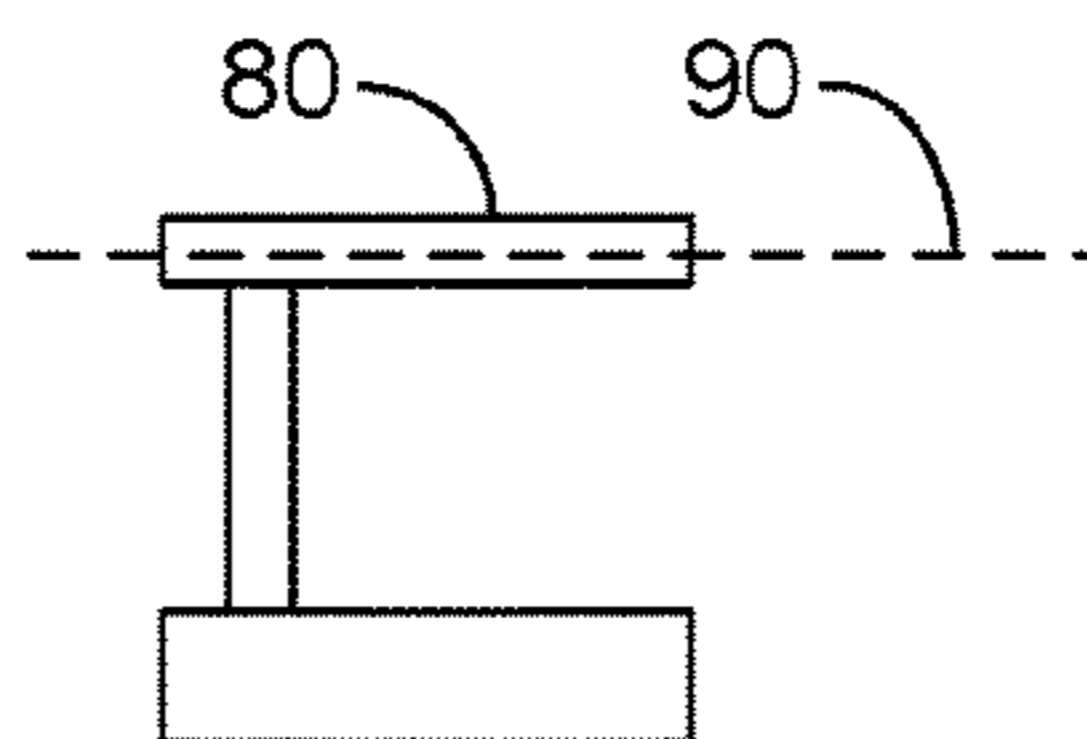
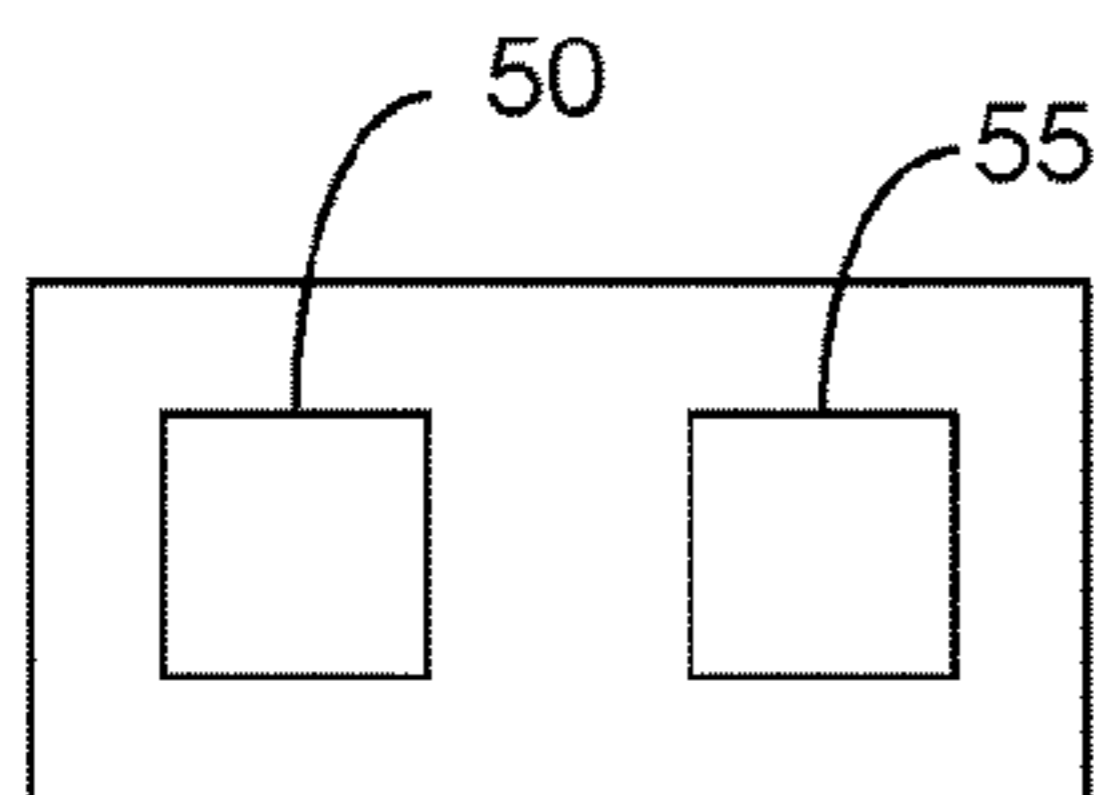
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(57) **ABSTRACT**

An irradiation treatment planning method constituted of: controlling a patient support member to rotate about a first axis by an initial rotation angle; imaging the patient; receiving treatment prescriptions; and responsive to the patient image, the treatment prescriptions and allowable ranges of rotation about at least two orthogonal axes, determining an irradiation treatment plan, wherein in the event that the irradiation treatment plan does not meet the treatment prescriptions, the method further comprises: responsive to the patient image, the treatment prescriptions and the allowable rotation ranges, determining rotation angles of the patient support member about the first axis; for each rotation angle, controlling the patient support member to rotate about the first axis by the rotation angle and imaging the patient; and for each rotation angle, determining an irradiation treatment plan portion responsive to the patient image, the treatment prescriptions and the allowable rotation ranges.

**20 Claims, 2 Drawing Sheets**

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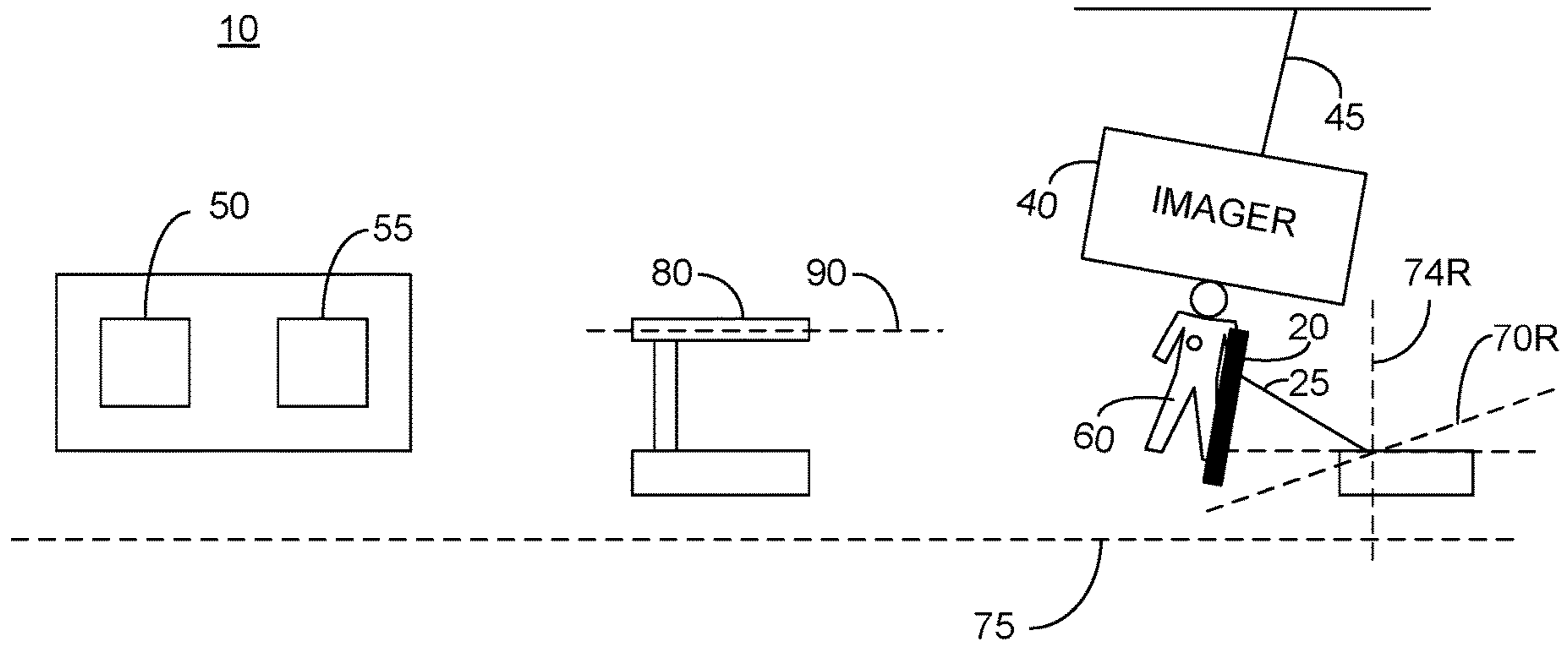


FIG. 1A

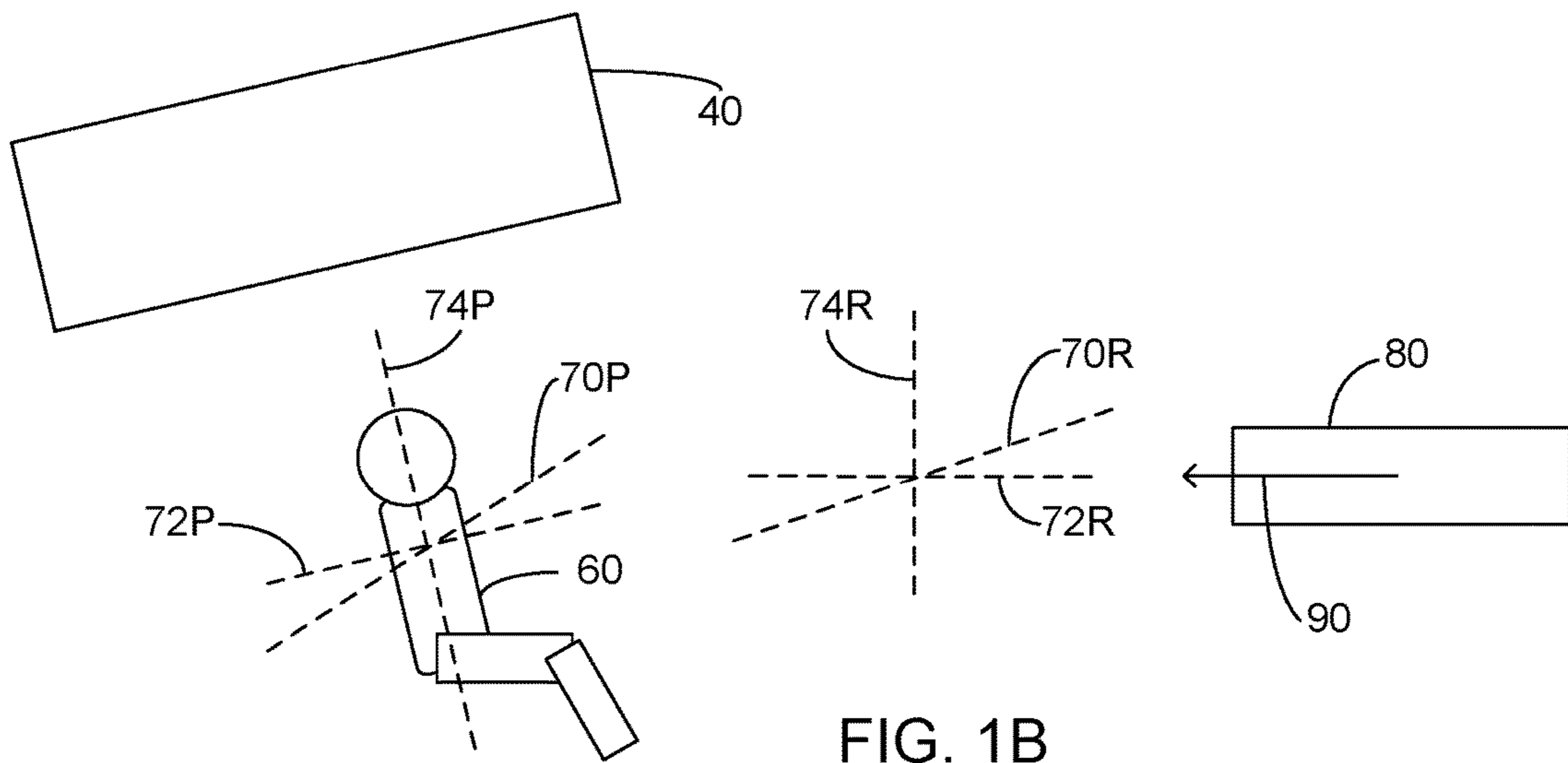


FIG. 1B

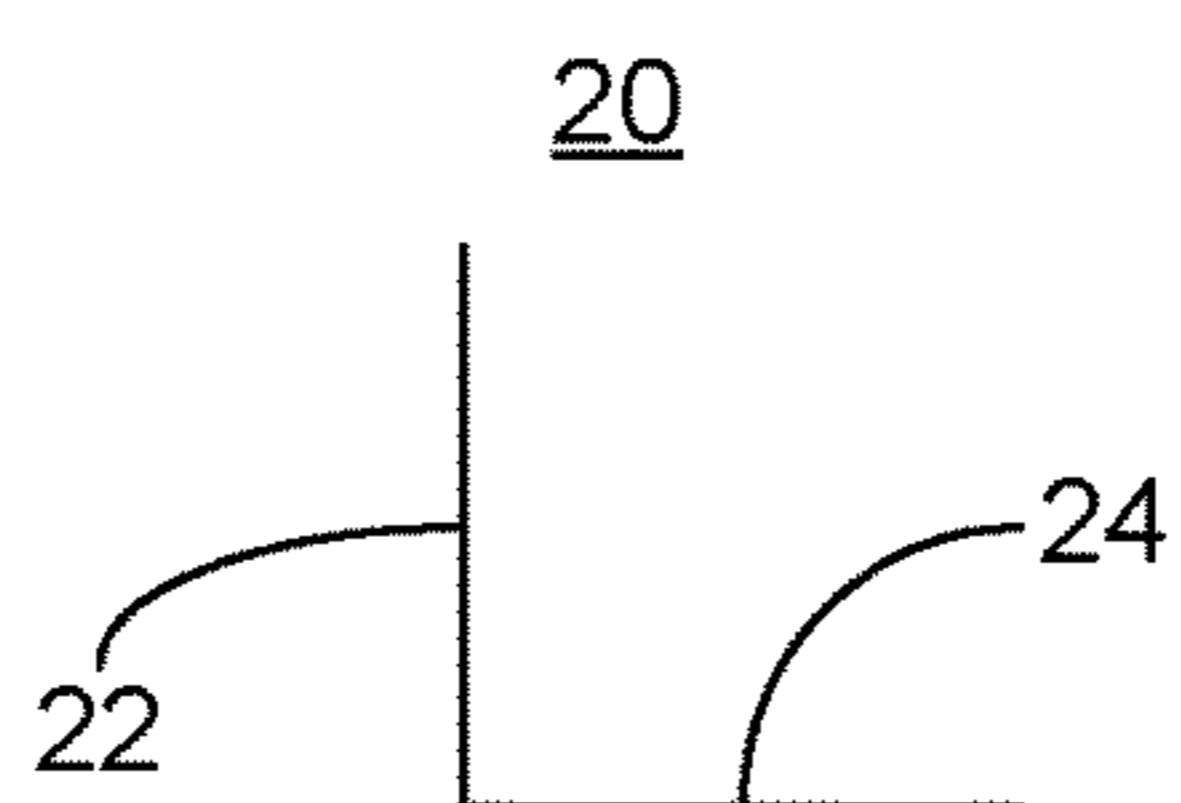


FIG. 1C

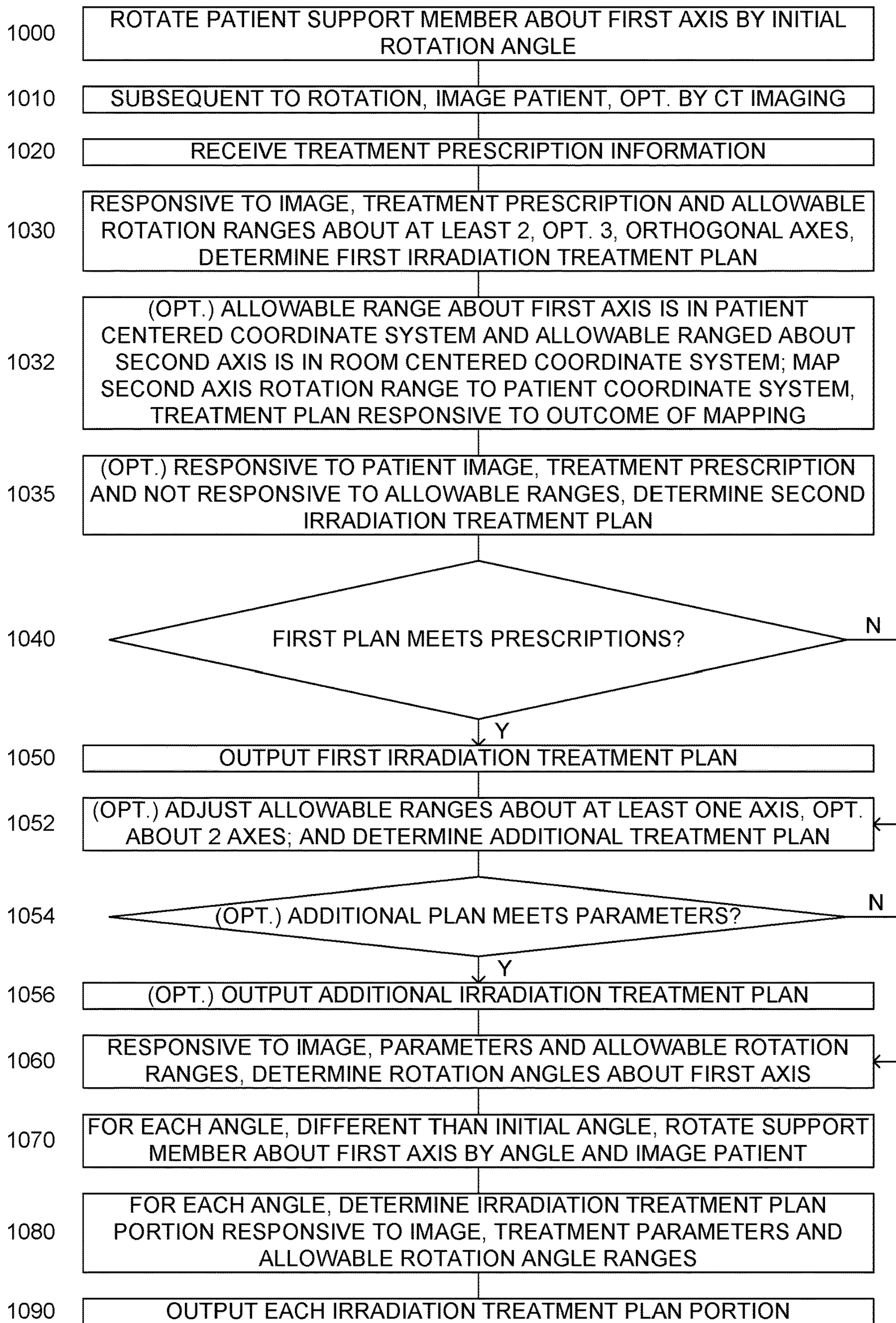


FIG. 2

## IRRADIATION TREATMENT PLAN SYSTEM AND METHOD

### CROSS-REFERENCE TO RELATED APPLICATIONS

This application claims priority from: U.S. provisional patent application Ser. No. 62/195,302, filed Jul. 22, 2015 and entitled "PATIENT IRRADIATION TREATMENT PLAN IMAGE ADJUSTMENT SYSTEM AND METHOD"; and U.S. provisional patent application Ser. 62/200,038, filed Aug. 2, 2015 and entitled "IMAGING SYSTEM AND METHOD", the entire contents of each of which are incorporated herein by reference.

### TECHNICAL FIELD

The invention relates generally to the field of teletherapy and in particular to a patient irradiation treatment plan image adjustment system and method.

### BACKGROUND OF THE INVENTION

Teletherapy is defined as a treatment methodology in which an irradiation source is at a distance from the body to be treated. X-rays and electron beams have long been used in teletherapy to treat various cancers. Unfortunately, X-rays exhibit a linear energy transfer approaching an exponential attenuation function, and are therefore of minimal safe use for deeply embedded growths. The use of heavy particles, particularly hadrons and more particularly protons, in teletherapy has found increasing acceptance, due to the ability of heavy particles to penetrate to a specific depth without appreciably harming intervening tissue. In particular, the linear energy transfer of hadrons exhibits an inversed depth profile with a marked Bragg peak defined as the point at which the hadrons deposit most of their energy, and occurs at the end of the hadrons path. As a result of this effect, increased energy can be directed at an embedded growth as compared to X-rays and electron beams, which particularly harm intervening tissues. While the term hadrons include a wide range of particles, practically, protons and various ions are most widely used in therapy. For clarity, this document will describe treatment as being accomplished with protons, however this is not meant to be limiting in any way.

The protons or ions can be focused to a target volume of variable penetration depth. In this way the dose profile can be matched closely to the target volume with a high precision. In order to ensure complete irradiation of the target growth, a plurality of beams arriving at the embedded growth from several different directions is preferred. The point at which the plurality of beams intersects, whether they are beamed sequentially or simultaneously, is termed the isocenter, and to maximize biological effectiveness the isocenter must be precisely collocated with the target growth.

Irradiation treatment is performed on a target tissue in a well defined process. In a first stage, known as the treatment planning stage, the target tissue is imaged and a treatment plan comprising dosage, patient position, and irradiation angles are defined. Furthermore, placement markers are defined, so as to ensure that subsequent irradiation sessions are properly targeted. Irradiation is then performed, responsive to the developed treatment plan, at a plurality of treatment sessions over a period of time, each session being known as a fraction. At each such fraction, care must be taken to ensure proper patient positioning, responsive to the placement markers, so as to avoid damage to organs in

vicinity of the target tissue. Positioning of the patient responsive to the markers is performed based on visualization of the patient, responsive to the defined markers.

Particularly, during each fraction, the patient is positioned on a patient support member, such as a bed, in a setup position. The setup position is identical to the patient position during the imaging of the treatment planning stage, except that is in the treatment room and the center of the growth mass is positioned at the isocenter of the irradiation source. The setup position of the patient is optionally verified by imaging and/or positioning devices. Unfortunately, current irradiation systems are set up such that the setup position of the patient is always perpendicular to the central axis of the irradiation beam nozzle of the irradiation source. This limits the possibilities for patient positioning for better comfort or other constraints of the treatment room, especially when the irradiation source has a fixed position and is not moveable.

### SUMMARY OF THE INVENTION

Accordingly, it is a principal object of the present invention to overcome disadvantages of prior art methods and arrangements of teletherapy. This is provided in the present invention by an irradiation treatment plan system comprising: a patient support member arranged to support a patient, the patient support member arranged to be rotated about three orthogonal axes; an imager; a memory, the memory having stored thereon, for at least two of the three orthogonal axes, information regarding the allowable range of rotation of the patient support member about the respective axis; and a control circuitry, the control circuitry arranged to: control the patient support member to rotate about a first of the three orthogonal axes by a predetermined initial rotation angle; subsequent to the rotation about the first axis, control the imager to image the patient; receive information regarding treatment prescriptions of the patient; and responsive to the patient image, the received treatment prescription information and the allowable rotation range information, determine a first irradiation treatment plan, wherein the control circuitry is further arranged, in the event that the determined first irradiation treatment plan meets the patient treatment prescriptions, to output the determined first irradiation treatment plan, and wherein the control circuitry is further arranged, in the event that the determined first irradiation treatment plan does not meet the patient treatment prescriptions, to: responsive to the patient image, the received treatment prescription information and the allowable rotation range information, determine a plurality of rotation angles of the patient support member about the first axis; for each of the plurality of determined rotation angles, different than the predetermined initial rotation angle, control the patient support member to rotate about the first axis by the respective determined rotation angle and control the imager to image the patient; for each of the plurality of determined rotation angles, determine an irradiation treatment plan portion responsive to the respective patient image, the patient treatment prescriptions and the allowable rotation range information; and output each of the plurality of determined treatment plan portions.

In one embodiment, the control circuitry is further arranged, responsive to the patient image at the predetermined initial rotation angle and the received treatment prescription information, to determine a second irradiation treatment plan, the second irradiation treatment plan determined without the limits of the allowable rotation range information, wherein the determination of the plurality of

rotation angles is responsive to the determined second irradiation treatment plan. In another embodiment, the allowable range of rotation of the patient support member about the first axis is in relation to a coordinate system centered on the patient and the allowable range of rotation of the patient support member about the second axis is in relation to a coordinate system centered on a room containing the patient support member, wherein the control circuitry is further arranged to map the allowable range of rotation about the second axis to the patient centered coordinate system, the first irradiation treatment plan determination responsive to the outcome of the mapping.

In one embodiment, the control circuitry is further arranged, in the event that the determined first irradiation treatment plan does not meet the patient treatment prescriptions, to: adjust the allowable range of rotation of the patient support member about at least one of the plurality of three axes; and responsive to the adjusted at least one allowable range, determine an additional first irradiation treatment plan, the arrangement to determine a plurality of rotation angles performed only in the event that the determined additional first irradiation does not meet the patient treatment prescriptions. In one further embodiment, the adjustment of the allowable range of rotation about at least one of the plurality of three axes comprises an adjustment of the allowable range of rotation about two of the plurality of three axes.

In one embodiment, the memory has stored thereon information regarding the allowable range of rotation of the patient support member about all of the three orthogonal axes. In another embodiment, the imager is a computed tomography (CT) imager.

In one independent embodiment, an irradiation treatment planning method for a patient supported by a patient support member which is arranged to be rotated about three orthogonal axes is provided, the method comprising: rotating the patient support member about a first of the three orthogonal axes by a predetermined initial rotation angle; subsequent to the rotation about the first axis, imaging the patient; receiving information regarding treatment prescriptions of the patient; and responsive to the patient image, the received treatment prescription information and information regarding an allowable range of rotation of the patient support member about at least two of the three orthogonal axes, determining a first irradiation treatment plan, wherein in the event that the determined first irradiation treatment plan meets the patient treatment prescriptions, the method further comprises outputting the determined first irradiation treatment plan, and wherein in the event that the determined first irradiation treatment plan does not meet the patient treatment prescriptions, the method further comprises: responsive to the patient image, the received treatment prescription information and the allowable rotation range information, determining a plurality of rotation angles of the patient support member about the first axis; for each of the plurality of determined rotation angles which is different than the predetermined initial rotation angle, rotating the patient support member about the first axis by the respective determined rotation angle and imaging the patient; for each of the plurality of determined rotation angles, determining an irradiation treatment plan portion responsive to the respective patient image, the patient treatment prescriptions and the allowable rotation range information; and outputting each of the plurality of determined treatment plan portions.

In one embodiment, the method further comprises, responsive to the patient image at the predetermined initial rotation angle and the received treatment prescription infor-

mation, determining a second irradiation treatment plan, the second irradiation treatment plan determined without the limits of the allowable rotation range information, wherein the determination of the plurality of rotation angles is responsive to the determined second irradiation treatment plan. In another embodiment, the allowable range of rotation of the patient support member about the first axis is in relation to a coordinate system centered on the patient and the allowable range of rotation of the patient support member about the second axis is in relation to a coordinate system centered on a room containing the patient support member, and wherein the method further comprises mapping the allowable range of rotation about the second axis to the patient centered coordinate system, the first irradiation treatment plan determination responsive to the outcome of the mapping.

In one embodiment, the method further comprises in the event that the determined first irradiation treatment plan does not meet the patient treatment prescriptions: adjusting the allowable range of rotation of the patient support member about at least one of the plurality of three axes; and responsive to the adjusted at least one allowable range, determining an additional first irradiation treatment plan, the arrangement to determine a plurality of rotation angles performed only in the event that the determined additional first irradiation does not meet the patient treatment prescriptions. In one further embodiment, the adjustment of the allowable range of rotation about at least one of the plurality of three axes comprises an adjustment of the allowable range of rotation about two of the plurality of three axes.

In one embodiment, the information regarding the allowable range of rotation of the patient support member comprises information regarding the allowable range of rotation of the patient support member about all of the three orthogonal axes. In another embodiment, the imaging comprises computed tomography (CT) imaging.

In another independent embodiment, an irradiation treatment plan system is provided, the system comprising: a patient support member arranged to support a patient, the patient support member arranged to be rotated about three orthogonal axes, the patient support member initially rotated about a first of the three axes by a predetermined initial rotation angle; an imager; a memory, the memory having stored thereon, for at least two of the three orthogonal axes, information regarding the allowable range of rotation of the patient support member about the respective axis; and a control circuitry, the control circuitry arranged to: control the imager to image the patient; receive information regarding treatment prescriptions of the patient; and responsive to the patient image, the received treatment prescription information and the allowable rotation range information, determine a first irradiation treatment plan, wherein the control circuitry is further arranged, in the event that the determined first irradiation treatment plan meets the patient treatment prescriptions, to output the determined first irradiation treatment plan, and wherein the control circuitry is further arranged, in the event that the determined first irradiation treatment plan does not meet the patient treatment prescriptions, to: responsive to the patient image, the received treatment prescription information and the allowable rotation range information, determine a plurality of rotation angles of the patient support member about the first axis; for each of the plurality of determined rotation angles which is different than the predetermined initial rotation angle, control the patient support member to rotate about the first axis by the respective determined rotation angle and control the imager to image the patient; for each of the plurality of

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determined rotation angles, determine an irradiation treatment plan portion responsive to the respective patient image, the patient treatment prescriptions and the allowable rotation range information; and output each of the plurality of determined treatment plan portions.

In one embodiment, the control circuitry is further arranged, responsive to the patient image at the predetermined initial rotation angle and the received treatment prescription information, to determine a second irradiation treatment plan, the second irradiation treatment plan determined without the limits of the allowable rotation range information, wherein the determination of the plurality of rotation angles is responsive to the determined second irradiation treatment plan. In another embodiment, the allowable range of rotation of the patient support member about the first axis is in relation to a coordinate system centered on the patient and the allowable range of rotation of the patient support member about the second axis is in relation to a coordinate system centered on a room containing the patient support member, and wherein the control circuitry is further arranged to map the allowable range of rotation about the second axis to the patient centered coordinate system, the first irradiation treatment plan determination responsive to the outcome of the mapping.

In one embodiment, the control circuitry is further arranged, in the event that the determined first irradiation treatment plan does not meet the patient treatment prescriptions, to: adjust the allowable range of rotation of the patient support member about at least one of the plurality of three axes; and responsive to the adjusted at least one allowable range, determine an additional first irradiation treatment plan, the arrangement to determine a plurality of rotation angles performed only in the event that the determined additional first irradiation does not meet the patient treatment prescriptions. In one further embodiment, the adjustment of the allowable range of rotation about at least one of the plurality of three axes comprises an adjustment of the allowable range of rotation about two of the plurality of three axes.

In one embodiment, the memory has stored thereon information regarding the allowable range of rotation of the patient support member about all of the three orthogonal axes.

Additional features and advantages of the invention will become apparent from the following drawings and description.

#### BRIEF DESCRIPTION OF THE DRAWINGS

For a better understanding of the invention and to show how the same may be carried into effect, reference will now be made, purely by way of example, to the accompanying drawings in which like numerals designate corresponding elements or sections throughout.

With specific reference now to the drawings in detail, it is stressed that the particulars shown are by way of example and for purposes of illustrative discussion of the preferred embodiments of the present invention only, and are presented in the cause of providing what is believed to be the most useful and readily understood description of the principles and conceptual aspects of the invention. In this regard, no attempt is made to show structural details of the invention in more detail than is necessary for a fundamental understanding of the invention, the description taken with the drawings making apparent to those skilled in the art how the several forms of the invention may be embodied in practice.

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In the accompanying drawings:

FIGS. 1A-1C illustrate a high level schematic diagram of an irradiation treatment plan system, according to certain embodiments; and

FIG. 2 illustrates a high level flow chart of an irradiation treatment planning method, according to certain embodiments.

#### DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

Before explaining at least one embodiment of the invention in detail, it is to be understood that the invention is not limited in its application to the details of construction and the arrangement of the components set forth in the following description or illustrated in the drawings. The invention is applicable to other embodiments or of being practiced or carried out in various ways. Also, it is to be understood that the phraseology and terminology employed herein is for the purpose of description and should not be regarded as limiting.

FIG. 1A illustrates a high level schematic diagram of an irradiation treatment plan system **10**, according to certain embodiments. Irradiation treatment plan system **10** comprises: a patient support member **20**; an imager **40**, optionally comprising a computed tomography (CT) imager; an imager rotation mechanism **45**; and a control unit comprising a control circuitry **50** and a memory **55**. In one preferred embodiment, patient support member **20** comprises a chair such that a patient **60** supported by patient support member **20** is in a sitting position supported by a back rest **22** and a seat **24**, as illustrated in FIG. 1C. In one further embodiment, patient support member **20** can be converted to a horizontal bed such that a patient **60** supported by patient support member **20** is lying down. Patient support member **20** further comprises a rotation mechanism **25**. Rotation mechanism **25** is arranged to rotate patient support member **20** about three orthogonal axes **70R**, **72R** and **74R**. Specifically, axis **70R** is parallel to a floor **75** of the treatment room comprising irradiation treatment plan system **10**. Axis **72R** is parallel to floor **75** and orthogonal to axis **70R**. Axis **74R** is orthogonal to floor **75**. The rotation of patient support member **20** causes a rotation of patient **60** about three orthogonal axes **70P**, **72P** and **74P**. Specifically, axis **70P** is orthogonal to a longitudinal axis of back rest **22** of patient support member **20** and orthogonal to a longitudinal axis of seat **24** of patient support member **20** such that a negative rotation of patient support member **20** about axis **70P** will cause patient **60** to lay back, as illustrated in FIG. 1B. Axis **72P** is parallel to the longitudinal axis of seat **24** of patient support member **20** such that a rotation about axis **72P** will cause patient **60** to tip sideways. Axis **74P** is parallel to the longitudinal axis of back rest **22** of patient support member **20** such that a rotation about axis **74P** will cause patient **60** to swivel. In one embodiment, axes **70P**, **72P** and **74P** correspond to axes **70R**, **72R** and **74R**, respectively.

Imager rotation mechanism **45** is arranged to rotate imager **40** about axis **70R**. In one non-limiting embodiment, imager rotation mechanism **45** is constructed and operated as described in U.S. patent application publication S/N 2015/0208992, published Jul. 30, 2015 to Marash et al., and entitled "APPARATUS AND METHOD FOR PROVIDING PATIENT IMAGING", the entire contents of which are incorporated herein by reference.

Patient support member **20** is positioned in relation to an irradiation source **80**. In one embodiment, irradiation source **80** is supported by a gantry which allows movement thereof. In another embodiment, irradiation source **80** is a fixed beam

irradiation source and is arranged to output an irradiation beam exhibiting a fixed central axis **90** which corresponds to the central axis of a nozzle of irradiation source **80** (not shown). Particularly, the term ‘fixed beam irradiation source’, as used herein, is meant that irradiation source **80** has a predetermined fixed position and irradiation angle and the angle of central axis **90** in relation to floor **75** and walls of the treatment room containing irradiation source **80** is not adjusted for patient **60**. In one embodiment, the irradiation beam output by irradiation source **80** is constituted primarily of hadrons, preferably protons. In one non-limiting embodiment, control circuitry **50** is one of a processor and an ASIC circuitry. Control circuitry **50** is in communication with patient support member **20** and imager **40** (connections not shown). In one embodiment (not shown) two imagers **40** are provided, optionally one imager **40** arranged to image patient **60** at a plurality of angles and the other imager **40** arranged to image patient **60** in a horizontal position. In another embodiment (not shown), imager **40**, or imagers **40**, are in a different room than irradiation source **80**.

Memory **55** has stored thereon information regarding the allowable range of rotation of patient **60** about axes **70P** and **72P**. In another embodiment, memory **55** has stored thereon information regarding the allowable range of rotation of patient **60** about axes **70P**, **72P** and **74P**. In another embodiment, memory **55** has stored thereon information regarding the allowable range of rotation of patient **60** about axis **70P**, the allowable range of rotation of patient support member **20** about axis **72R** and, optionally, the allowable range of rotation of patient support member **20** about axis **74R**. Memory **55** further has stored thereon information regarding the relationship between axes **70R**, **72R** and **74R** and axes **70P**, **72P** and **74P**. In one embodiment, the allowable range of rotation about axis **70P** is a 30 degree range, from  $-5$  degrees to  $-35$  degrees, a negative angle meaning that patient **60** is laid backwards. In another embodiment, the allowable range of rotation about axis **72R** is a 20 degree range, 10 degrees in each direction. In another embodiment, the allowable range of rotation about axis **74R** is 360 degrees. The allowable ranges represent the desired limits of rotation of patient **60** during treatment to avoid uncomfortable positions, mechanical limitations of patient support member **20** and/or limitations due to the position of central axis **90** of irradiation source **80**.

In operation, patient **60** is supported by patient support member **20**. Control circuitry **50** is arranged to control rotation mechanism **25** of patient support member **20** such that patient **60** is rotated about axis **70P** by a predetermined initial rotation angle. Optionally, the predetermined initial rotation angle is  $-20$  degrees, i.e. patient **60** is laid back by 20 degrees. In another embodiment, patient support member **20** is already rotated about axis **70P** by the predetermined initial rotation angle. Subsequent to the rotation about axis **70P**, control circuitry **50** is arranged to control imaging rotation mechanism **45** of imager **40** to rotate imager **40** about axis **70R** such that imager **40** is aligned with patient **60** and is further arranged to control imager **40** to image patient **60**. Imager **40** is arranged to output the image, or images, of patient **60** to control circuitry **50**.

Control circuitry **50** is arranged to receive from a user input console, or from an external network, treatment prescriptions for the treatment of patient **60**. In one embodiment, the treatment prescriptions include the minimum dose amount to be applied to the target tissue and the maximum dose amount to be applied to surrounding critical structures, e.g. at least 90% of the dose to the target tissue and less than 10% of the dose to the critical structures.

Responsive to the images of patient **60** received from imager **40**, the received treatment prescriptions and the allowable rotation range information stored on memory **55**, control circuitry **50** is arranged to determine a first irradiation treatment plan for patient **60**. In one embodiment, prior to the treatment planning, control circuitry **50** is arranged to instruct the treatment planning software to rotate the irradiation beam of the treatment plan by the initial rotation angle of patient **60**. Alternatively, control circuitry **50** is arranged to rotate the received image, or images, by the initial rotation angle of patient **60**. In another embodiment, prior to the treatment planning, control circuitry **50** is arranged to map the rotation limitations about axes **72R** and **74R** to the coordinate system of axes **70P**, **72P** and **74P**, since the treatment plan is calculated in relation to the coordinate system of patient **60**.

In one embodiment, the nodes of a 3 dimensional (3D) grid of the image are each rotated about the respective one of axes **72P** and **74P** which corresponds with axes **72R** and **74R**, respectively. After the rotation, each grid node will be in its local 3D cell, which is defined by eight nodes of the 3D grid before the rotation. The HU-value of the node is calculated by interpolation of the corresponding HU-values at the nodes of the local cell.

In one embodiment, control circuitry **50** is further arranged to determine a second irradiation treatment plan for patient **60**, the second irradiation treatment plan computed without the rotation range limitations used to compute the first irradiation treatment plan. Control circuitry **50** is arranged to determine whether the first irradiation treatment plan is able to meet the treatment prescriptions while maintaining the rotation range limitations. In one embodiment, control circuitry **50** is arranged to compare the first and second irradiation treatment plans, and determine whether the treatment prescriptions are met responsive to the outcome of the treatment plan comparison. In the event that the first irradiation treatment plan meets the patient treatment prescriptions, control circuitry **50** is arranged to output the determined first irradiation treatment plan, optionally to a user console. Further optionally, control circuitry **50** is arranged to control irradiation source **80** to irradiate patient **60** in accordance with the output irradiation treatment plan. Control circuitry **50** is further arranged, prior to the output of the first irradiation treatment plan to map the planned rotation angles of patient **60** about axes **72P** and **74P** to the coordination system of axes **70R**, **72R** and **74R**.

In the event that control circuitry **50** determines that the first irradiation treatment plan does not meet the patient treatment prescriptions, control circuitry **50** is arranged, responsive to the received patient images, the received treatment prescription information and the allowable rotation range information, to determine a plurality of rotation angles of patient **60** about axis **70P** which will allow a plurality of irradiation treatment portions which together will meet the patient treatment prescriptions. Control circuitry **50** is further arranged to determine the corresponding rotation angles of patient support member **20** about axis **70R**. In one embodiment, the plurality of rotation angles is responsive to the optionally determined second irradiation treatment plan. One of the plurality of rotation angles can in one embodiment be the predetermined initial rotation angle. The determined rotation angles are limited by the allowable rotation range about axis **70P**, however they can in one embodiment include a  $-90$  degree rotation, i.e. a horizontal position.

For each of the plurality of determined rotation angles, not including the predetermined initial rotation angle, control



circuitry 50 is arranged to: control patient support member 20 to rotate patient 60 about axis 70P by the respective determined rotation angle; control imager rotation mechanism 45 to rotate imager 40 accordingly; and control imager 40 to image patient 60 at the respective rotation angle. No image is necessary for the initial rotation angle because patient 60 has already been imaged at that angle.

For each of the plurality of determined rotation angles, control circuitry 50 is arranged to determine an irradiation treatment plan portion responsive to the respective images received from imager 40 at the respective rotation angle, the patient treatment prescriptions and the allowable rotation range information for axis 72R and optionally axis 74R. Control circuitry 50 is further arranged to output each of the determined treatment plan portions, as described above in relation to the output first irradiation treatment plan. In one embodiment, in the event that the combination of the determined irradiation treatment plan portions still do not meet the patient treatment prescriptions, control circuitry 50 is arranged to again determine additional rotation angles of patient 60 about axis 70P and determine additional irradiation treatment plan portions.

In one embodiment, when control circuitry 50 has determined that the first irradiation treatment plan does not meet the treatment prescriptions, control circuitry 50 is arranged to adjust the allowable rotation range about axis 72R, and optionally axis 74R, and responsive thereto determine an additional first irradiation treatment plan. Optionally, only in the event that the additional first irradiation treatment plan does not meet the patient treatment prescriptions does control circuitry 50 determine the additional rotation angles for the irradiation treatment portions. Similarly, in the event that the combination of the determined irradiation treatment plan portions do not meet the patient treatment prescriptions control circuitry 50 is arranged to adjust the allowable rotation range of patient 60 about axis 70P and new rotation angles are determined.

FIG. 2 illustrates a high level flow chart of an irradiation treatment planning method for a patient supported by a patient support member which is arranged to be rotated about three orthogonal axes, according to certain embodiments. In stage 1000, in one embodiment, the patient support member is rotated about a first of the three orthogonal axes by a predetermined initial rotation angle. In another embodiment, the patient support member is arranged to initially be in a rotated position about the first axis by the predetermined initial rotation angle and no additional rotation is necessary during stage 1000. In stage 1010, subsequent to the rotation about the first axis of stage 1000, the patient is imaged, optionally by CT imaging. In stage 1020, information regarding treatment prescriptions of the patient is received. In stage 1030, responsive to the patient image of stage 1010, the received treatment prescription information of stage 1020 and information regarding an allowable range of rotation of the patient support member about at least two of the three orthogonal axes, optionally all three axes, a first irradiation treatment plan is determined.

In optional stage 1032, the allowable range of rotation of the patient support member about the first axis is in relation to a coordinate system centered on the patient and the allowable range of rotation of the patient support member about the second axis is in relation to a coordinate system centered on a room containing the patient support member. The allowable range of rotation about the second axis is mapped to the patient centered coordinate system, the first irradiation treatment plan determination responsive to the outcome of the mapping.

In optional stage 1035, responsive to the patient image at the predetermined initial rotation angle of stage 1010 and the received treatment prescription information of stage 1020, a second irradiation treatment plan is determined, the second irradiation treatment plan determined without the limits of the allowable rotation range information of stage 1030.

In stage 1040, the determined first irradiation treatment plan of stage 1030 is analyzed to determine whether it meets the treatment prescriptions of stage 1020 to determine if they are met, optionally responsive to the second irradiation treatment plan of optional stage 1035. In the event that the determined first irradiation treatment plan meets the patient treatment prescriptions, in stage 1050 the determined first irradiation treatment plan of stage 1030 is output.

In the event that the determined first irradiation treatment plan does not meet the patient treatment prescriptions of stage 1020, in optional stage 1052 the allowable rotation range for at least one of the axes, and optionally 2 of the axes, of stage 1030 are adjusted. Responsive to the adjustment, an additional first treatment plan is determined. In optional stage 1054, the additional first treatment plan of optional stage 1052 is analyzed to determine whether it meets the treatment prescriptions of stage 1020. In the event that the additional first treatment plan meets the treatment prescriptions, in optional stage 1056 the additional first treatment plan is output.

In the event that the additional first treatment plan of optional stage 1052 does not meet the treatment prescriptions of stage 1020, in stage 1060, responsive to the patient image of stage 1010, the received treatment prescription information and the allowable rotation range information of stage 1030, a plurality of rotation angles of the patient support member about the first axis are determined. In stage 1070, for each of the plurality of determined rotation angles of stage 1060 which is different than the predetermined initial rotation angle of stage 1000, the patient support member is controlled to rotate about the first axis by the respective determined rotation angle and the patient is imaged.

In stage 1080, for each of the plurality of determined rotation angles of stage 1060, an irradiation treatment plan portion is determined responsive to the respective patient image of stage 1070, the patient treatment prescriptions of stage 1020 and the allowable rotation range information of stage 1030. In stage 1090, each of the plurality of determined treatment plan portions of stage 1080 are output.

It is appreciated that certain features of the invention, which are, for clarity, described in the context of separate embodiments, may also be provided in combination in a single embodiment. Conversely, various features of the invention which are, for brevity, described in the context of a single embodiment, may also be provided separately or in any suitable sub-combination.

Unless otherwise defined, all technical and scientific terms used herein have the same meanings as are commonly understood by one of ordinary skill in the art to which this invention belongs. Although methods similar or equivalent to those described herein can be used in the practice or testing of the present invention, suitable methods are described herein.

All publications, patent applications, patents, and other references mentioned herein are incorporated by reference in their entirety. In case of conflict, the patent specification, including definitions, will prevail. In addition, the materials, methods, and examples are illustrative only and not intended to be limiting.

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The terms “include”, “comprise” and “have” and their conjugates as used herein mean “including but not necessarily limited to”.

It will be appreciated by persons skilled in the art that the present invention is not limited to what has been particularly shown and described hereinabove. Rather the scope of the present invention is defined by the appended claims and includes both combinations and sub-combinations of the various features described hereinabove as well as variations and modifications thereof, which would occur to persons skilled in the art upon reading the foregoing description.

The invention claimed is:

1. An irradiation treatment plan system comprising:

a patient support member arranged to support a patient,  
said patient support member arranged to be rotated  
about three orthogonal axes;

an imager;

a memory, said memory having stored thereon, for at least two of the three orthogonal axes, information regarding an allowable range of rotation of said patient support member about the respective axis; and

a control circuitry, said control circuitry arranged to:

control said patient support member to rotate about a first of the three orthogonal axes by a predetermined initial rotation angle;

subsequent to said rotation about the first axis, control said imager to image the patient;

receive information regarding treatment prescriptions of the patient; and

responsive to said patient image, said received treatment prescription information and said allowable rotation range information, determine a first irradiation treatment plan,

wherein said control circuitry is further arranged, in the event that said determined first irradiation treatment plan meets the patient treatment prescriptions, to output said determined first irradiation treatment plan, and

wherein said control circuitry is further arranged, in the event that said determined first irradiation treatment plan does not meet the patient treatment prescriptions, to:

responsive to said patient image, said received treatment prescription information and said allowable rotation range information, determine a plurality of rotation angles of said patient support member about the first axis;

for each of said plurality of determined rotation angles which is different than the predetermined initial rotation angle, control said patient support member to rotate about the first axis by said respective determined rotation angle and control said imager to image the patient;

for each of said plurality of determined rotation angles, determine an irradiation treatment plan portion responsive to said respective patient image, the patient treatment prescriptions and said allowable rotation range information; and output each of said plurality of determined treatment plan portions.

2. The system of claim 1, wherein said control circuitry is further arranged, responsive to said patient image at the predetermined initial rotation angle and said received treatment prescription information, to determine a second irradiation treatment plan, said second irradiation treatment plan determined without the limits of said allowable rotation range information,

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wherein said determination of said plurality of rotation angles is responsive to said determined second irradiation treatment plan.

3. The system of claim 1, wherein the allowable range of rotation of said patient support member about the first axis is in relation to a coordinate system centered on the patient and the allowable range of rotation of said patient support member about the second axis is in relation to a coordinate system centered on a room containing said patient support member, and

wherein said control circuitry is further arranged to map the allowable range of rotation about the second axis to the patient centered coordinate system, said first irradiation treatment plan determination responsive to the outcome of said mapping.

4. The system of claim 1, wherein said control circuitry is further arranged, in the event that said determined first irradiation treatment plan does not meet the patient treatment prescriptions, to:

adjust the allowable range of rotation of said patient support member about at least one of the plurality of three axes; and

responsive to said adjusted at least one allowable range, determine an additional first irradiation treatment plan, said arrangement to determine a plurality of rotation angles performed only in the event that said determined additional first irradiation does not meet the patient treatment prescriptions.

5. The system of claim 4, wherein said adjustment of the allowable range of rotation about at least one of the plurality of three axes comprises an adjustment of the allowable range of rotation about two of the plurality of three axes.

6. The system of claim 1, wherein said memory has stored thereon information regarding the allowable range of rotation of said patient support member about all of the three orthogonal axes.

7. The system of claim 1, wherein said imager is a computed tomography (CT) imager.

8. An irradiation treatment planning method for a patient supported by a patient support member which is arranged to be rotated about three orthogonal axes, the method comprising:

rotating the patient support member about a first of the three orthogonal axes by a predetermined initial rotation angle;

subsequent to said rotation about the first axis, imaging the patient;

receiving information regarding treatment prescriptions of the patient; and

responsive to said patient image, said received treatment prescription information and information regarding an allowable range of rotation of the patient support member about at least two of the three orthogonal axes, determining a first irradiation treatment plan,

wherein in the event that said determined first irradiation treatment plan meets the patient treatment prescriptions, the method further comprises outputting said determined first irradiation treatment plan, and wherein in the event that said determined first irradiation treatment plan does not meet the patient treatment prescriptions, the method further comprises:

responsive to said patient image, said received treatment prescription information and said allowable rotation range information, determining a plurality of rotation angles of said patient support member about the first axis;

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for each of said plurality of determined rotation angles which is different than the predetermined initial rotation angle, rotating said patient support member about the first axis by said respective determined rotation angle and imaging the patient; 5  
for each of said plurality of determined rotation angles, determining an irradiation treatment plan portion responsive to said respective patient image, the patient treatment prescriptions and said allowable rotation range information; and 10  
outputting each of said plurality of determined treatment plan portions.

9. The method of claim 8, further comprising, responsive to said patient image at the predetermined initial rotation angle and said received treatment prescription information, determining a second irradiation treatment plan, said second irradiation treatment plan determined without the limits of said allowable rotation range information, 15

wherein said determination of said plurality of rotation angles is responsive to said determined second irradiation treatment plan. 20

10. The method of claim 8, wherein the allowable range of rotation of the patient support member about the first axis is in relation to a coordinate system centered on the patient and the allowable range of rotation of said patient support member about the second axis is in relation to a coordinate system centered on a room containing said patient support member, and 25

wherein the method further comprises mapping the allowable range of rotation about the second axis to the patient centered coordinate system, said first irradiation treatment plan determination responsive to the outcome of said mapping. 30

11. The method of claim 8, further comprising, in the event that said determined first irradiation treatment plan does not meet the patient treatment prescriptions: 35

adjusting the allowable range of rotation of said patient support member about at least one of the plurality of three axes; and 40

responsive to said adjusted at least one allowable range, determining an additional first irradiation treatment plan, said arrangement to determine a plurality of rotation angles performed only in the event that said determined additional first irradiation does not meet the patient treatment prescriptions. 45

12. The method of claim 11, wherein said adjustment of the allowable range of rotation about at least one of the plurality of three axes comprises an adjustment of the allowable range of rotation about two of the plurality of three axes. 50

13. The method of claim 8, wherein the information regarding the allowable range of rotation of the patient support member comprises information regarding the allowable range of rotation of the patient support member about all of the three orthogonal axes. 55

14. The method of claim 8, wherein said imaging comprises computed tomography (CT) imaging.

15. An irradiation treatment plan system comprising:

a patient support member arranged to support a patient, said patient support member arranged to be rotated about three orthogonal axes, said patient support member initially rotated about a first of the three axes by a predetermined initial rotation angle;

an imager;

a memory, said memory having stored thereon, for at least two of the three orthogonal axes, information regarding

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an allowable range of rotation of said patient support member about the respective axis; and

a control circuitry, said control circuitry arranged to:

control said imager to image the patient;

receive information regarding treatment prescriptions of the patient; and

responsive to said patient image, said received treatment prescription information and said allowable rotation range information, determine a first irradiation treatment plan, 10

wherein said control circuitry is further arranged, in the event that said determined first irradiation treatment plan meets the patient treatment prescriptions, to output said determined first irradiation treatment plan, and 15

wherein said control circuitry is further arranged, in the event that said determined first irradiation treatment plan does not meet the patient treatment prescriptions, to: 20

responsive to said patient image, said received treatment prescription information and said allowable rotation range information, determine a plurality of rotation angles of said patient support member about the first axis; 25

for each of said plurality of determined rotation angles which is different than the predetermined initial rotation angle, control said patient support member to rotate about the first axis by said respective determined rotation angle and control said imager to image the patient; 30

for each of said plurality of determined rotation angles, determine an irradiation treatment plan portion responsive to said respective patient image, the patient treatment prescriptions and said allowable rotation range information; and output each of said plurality of determined treatment plan portions. 35

16. The system of claim 15, wherein said control circuitry is further arranged, responsive to said patient image at the predetermined initial rotation angle and said received treatment prescription information, to determine a second irradiation treatment plan, said second irradiation treatment plan determined without the limits of said allowable rotation range information, 40

wherein said determination of said plurality of rotation angles is responsive to said determined second irradiation treatment plan.

17. The system of claim 15, wherein the allowable range of rotation of said patient support member about the first axis is in relation to a coordinate system centered on the patient and the allowable range of rotation of said patient support member about the second axis is in relation to a coordinate system centered on a room containing said patient support member, and 55

wherein said control circuitry is further arranged to map the allowable range of rotation about the second axis to the patient centered coordinate system, said first irradiation treatment plan determination responsive to the outcome of said mapping. 60

18. The system of claim 15, wherein said control circuitry is further arranged, in the event that said determined first irradiation treatment plan does not meet the patient treatment prescriptions, to: 65

adjust the allowable range of rotation of said patient support member about at least one of the plurality of three axes; and

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responsive to said adjusted at least one allowable range,  
determine an additional first irradiation treatment plan,  
said arrangement to determine a plurality of rotation  
angles performed only in the event that said determined  
additional first irradiation does not meet the patient 5  
treatment prescriptions.

**19.** The system of claim **18**, wherein said adjustment of  
the allowable range of rotation about at least one of the  
plurality of three axes comprises an adjustment of the  
allowable range of rotation about two of the plurality of 10  
three axes.

**20.** The system of claim **15**, wherein said memory has  
stored thereon information regarding the allowable range of  
rotation of said patient support member about all of the three  
orthogonal axes. 15

\* \* \* \* \*

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