



(12) **United States Patent**
Ganesan et al.

(10) **Patent No.:** **US 10,483,997 B1**
(45) **Date of Patent:** **Nov. 19, 2019**

(54) **CIRCUIT FOR FREQUENCY TO TIME DOMAIN CONVERSION**

USPC 341/166
See application file for complete search history.

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(*) Notice: Subject to any disclaimer, the term of this patent is extended or adjusted under 35 U.S.C. 154(b) by 0 days.

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(21) Appl. No.: **16/281,862**

(57) **ABSTRACT**

(22) Filed: **Feb. 21, 2019**

A method for frequency domain to time domain conversion includes receiving a set of frequency-domain samples. Based on the set of frequency-domain samples, a first sample subset comprising a predetermined fraction of the number of samples of the set of frequency-domain samples and a second sample subset comprising the predetermined fraction of the number of samples of the set of frequency-domain samples are generated. A linear phase rotation is applied to the first sample subset and the second sample subset to produce a phase rotated first sample subset and a phase rotated second sample subset. The phase rotated first sample set is post-processed to generate a first set of time-domain samples. The phase rotated second sample set is post-processed to generate a second set of time-domain samples. The first set of time-domain samples and the second set of time-domain samples are reordered to produce an output set of time-domain samples.

Related U.S. Application Data

(60) Provisional application No. 62/787,024, filed on Dec. 31, 2018.

(30) **Foreign Application Priority Data**

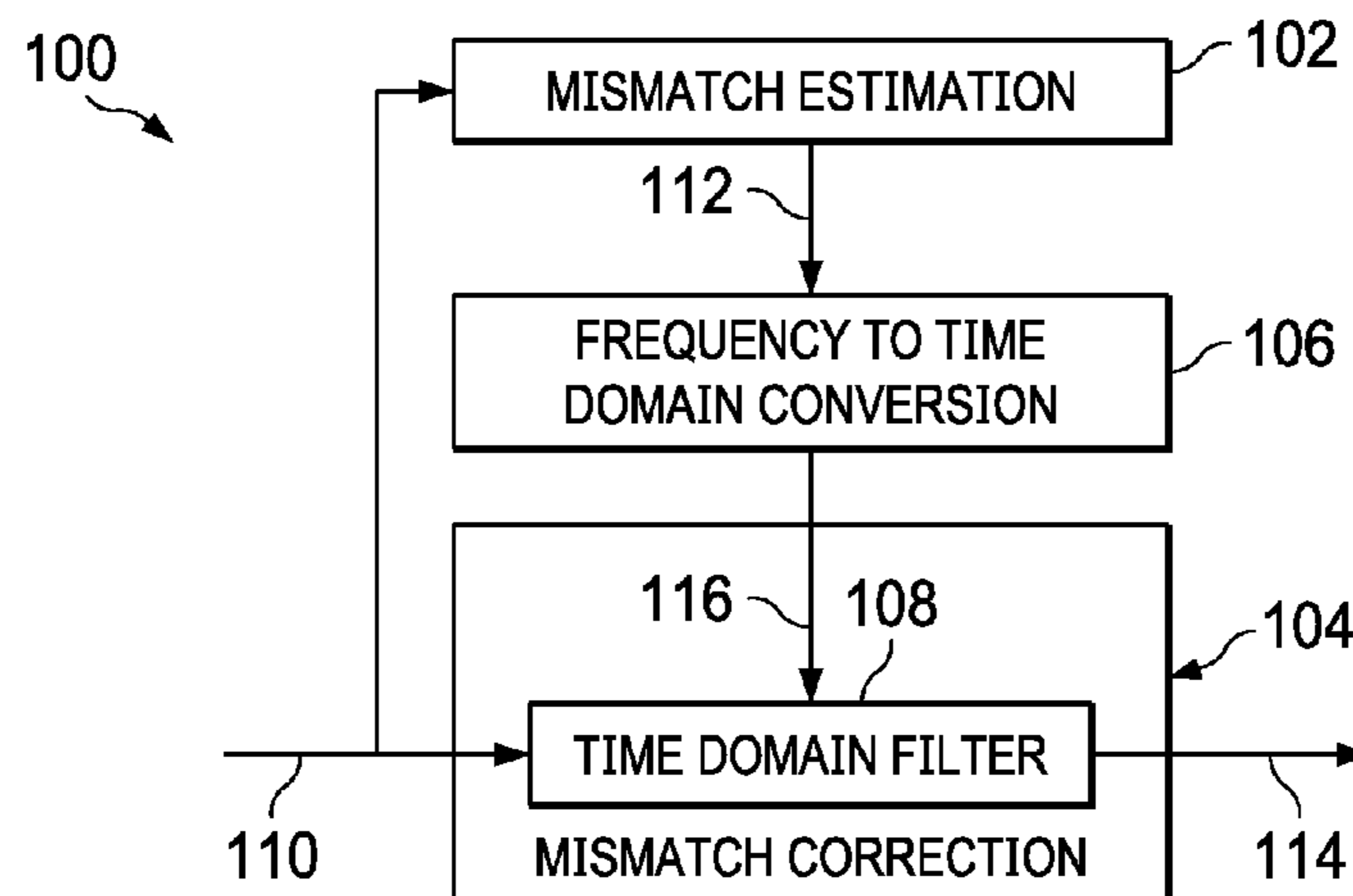
Nov. 2, 2018 (IN) 201841041551

(51) **Int. Cl.**
H03M 1/12 (2006.01)
H03M 1/06 (2006.01)

(52) **U.S. Cl.**
CPC *H03M 1/1215* (2013.01); *H03M 1/06* (2013.01); *H03M 1/1255* (2013.01)

(58) **Field of Classification Search**
CPC H03M 1/1215; H03M 1/1255; H03M 1/06

21 Claims, 3 Drawing Sheets



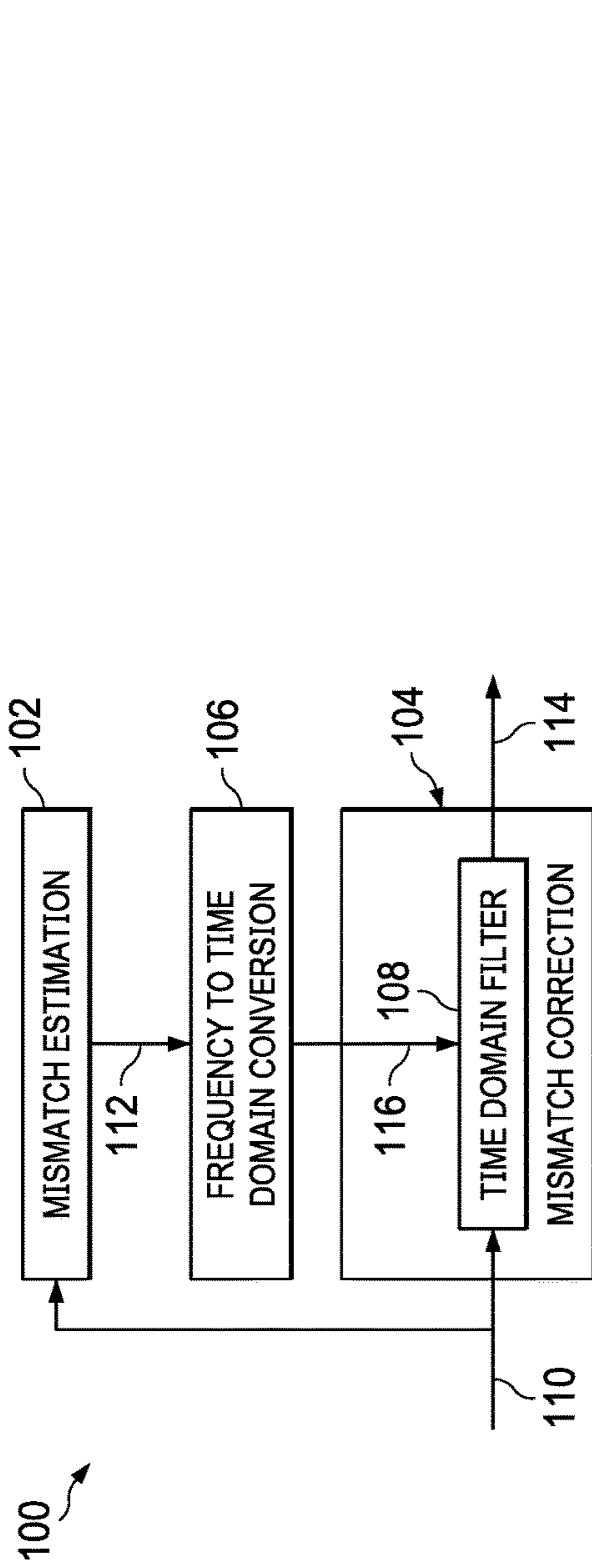


FIG. 1

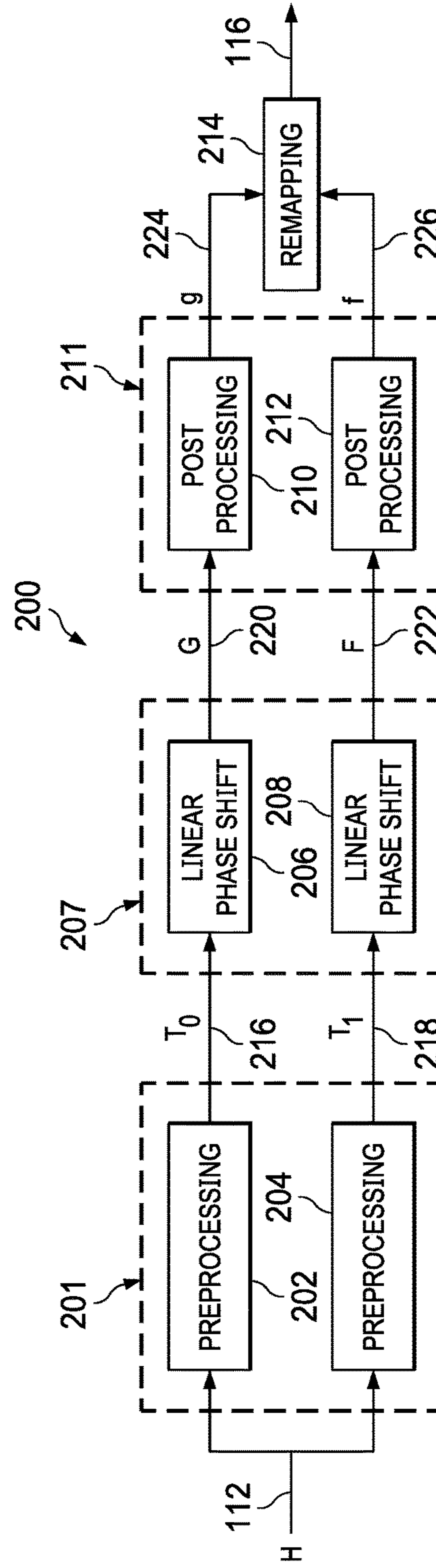


FIG. 2

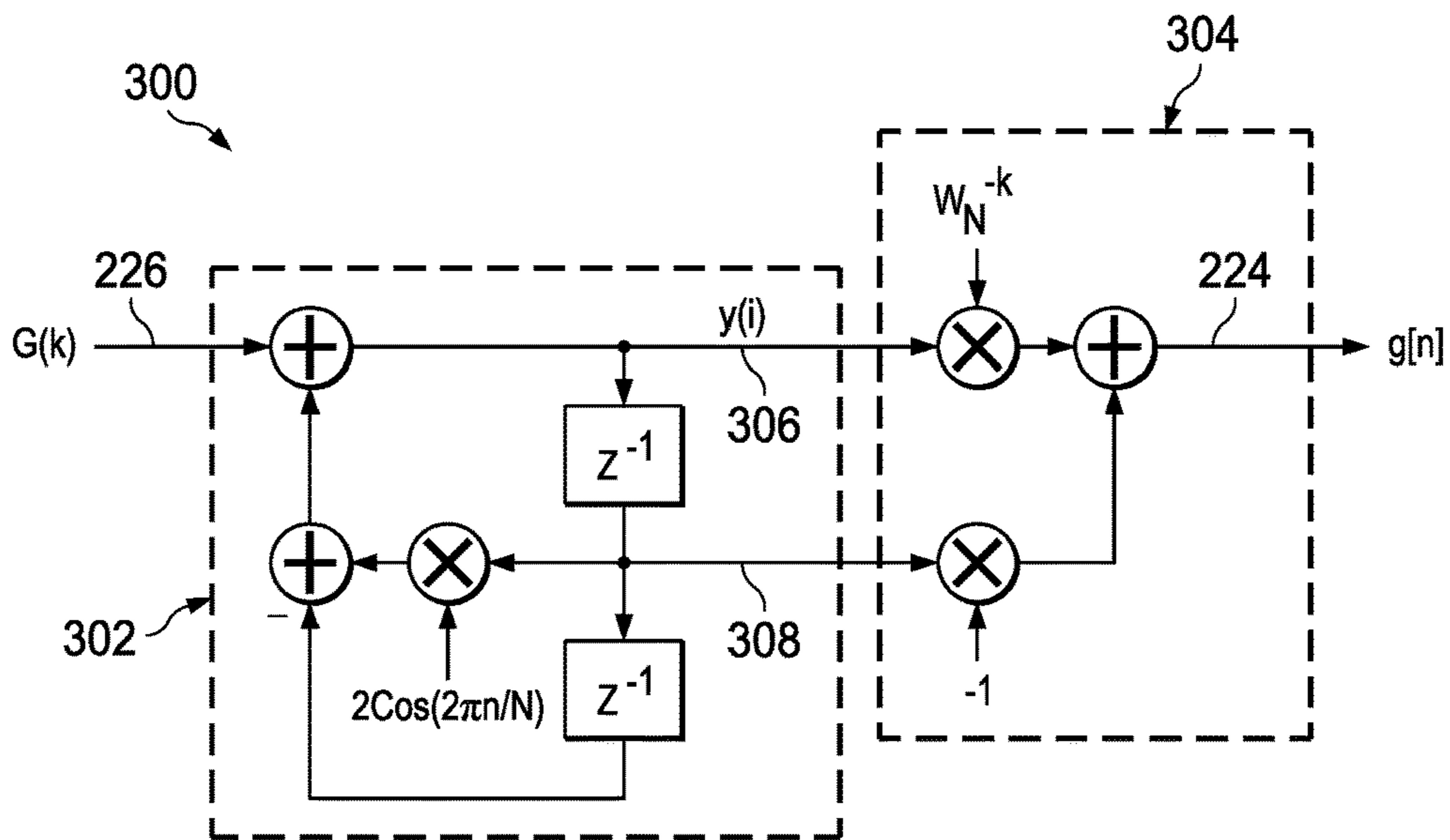


FIG. 3

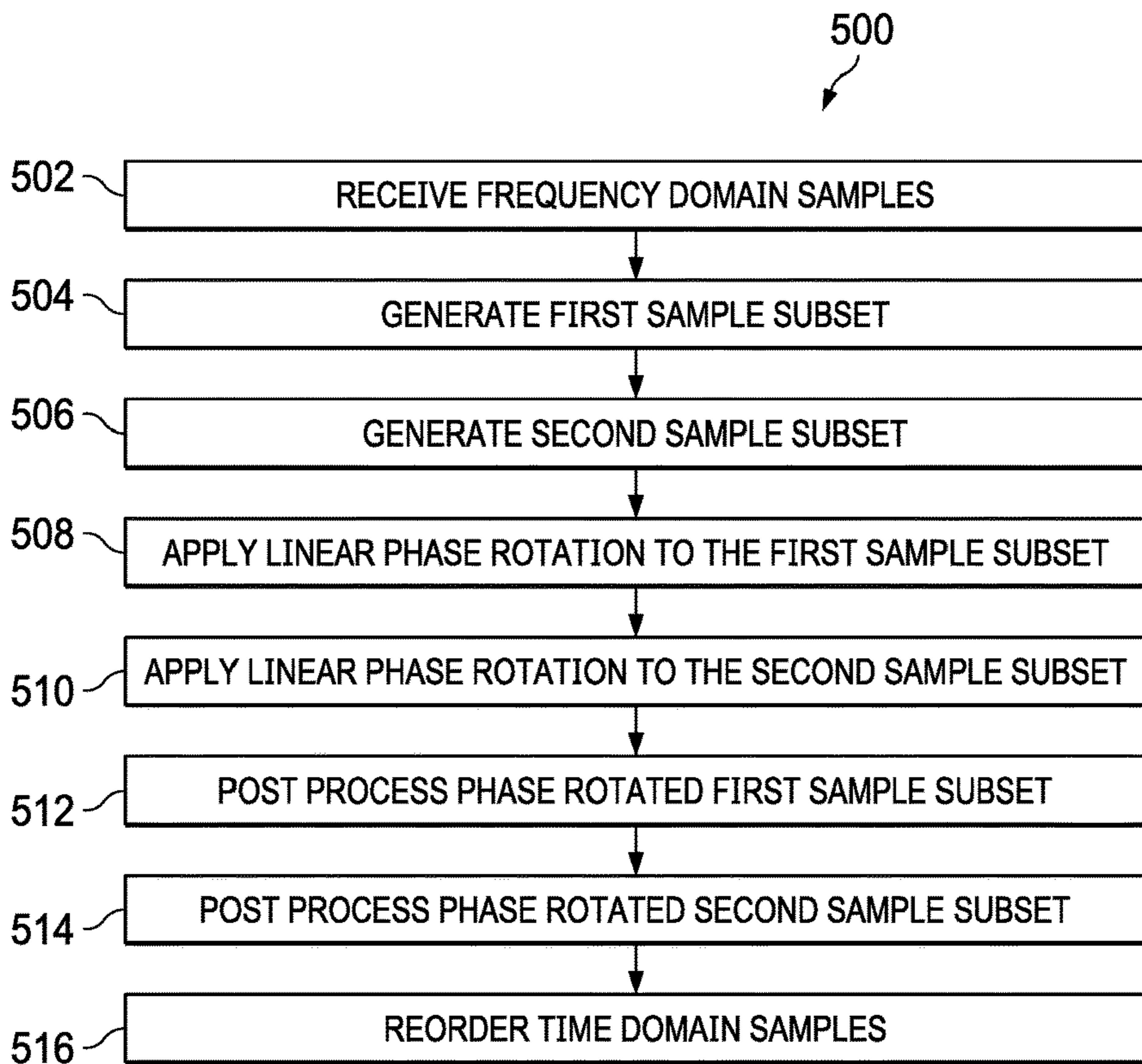


FIG. 5

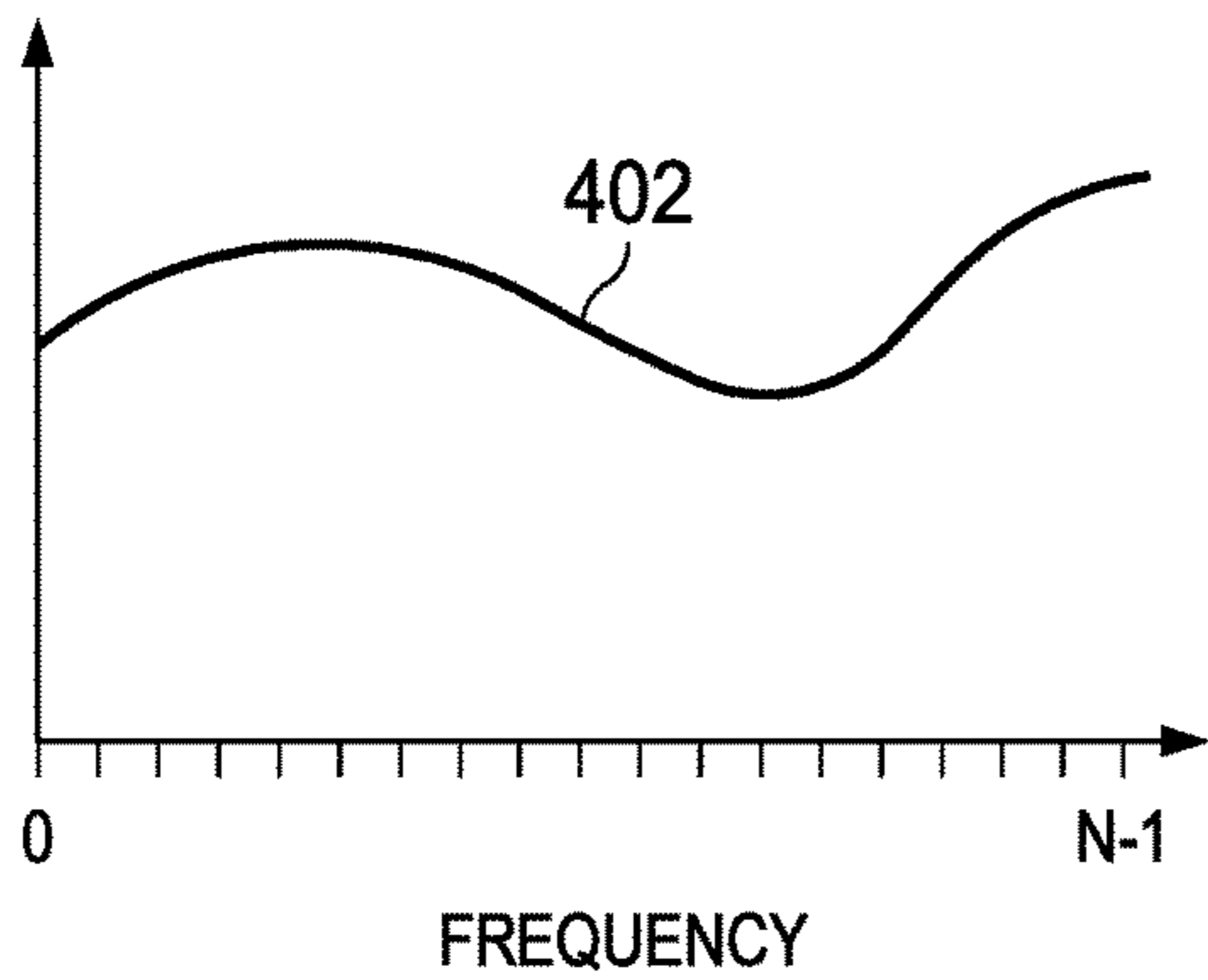


FIG. 4A

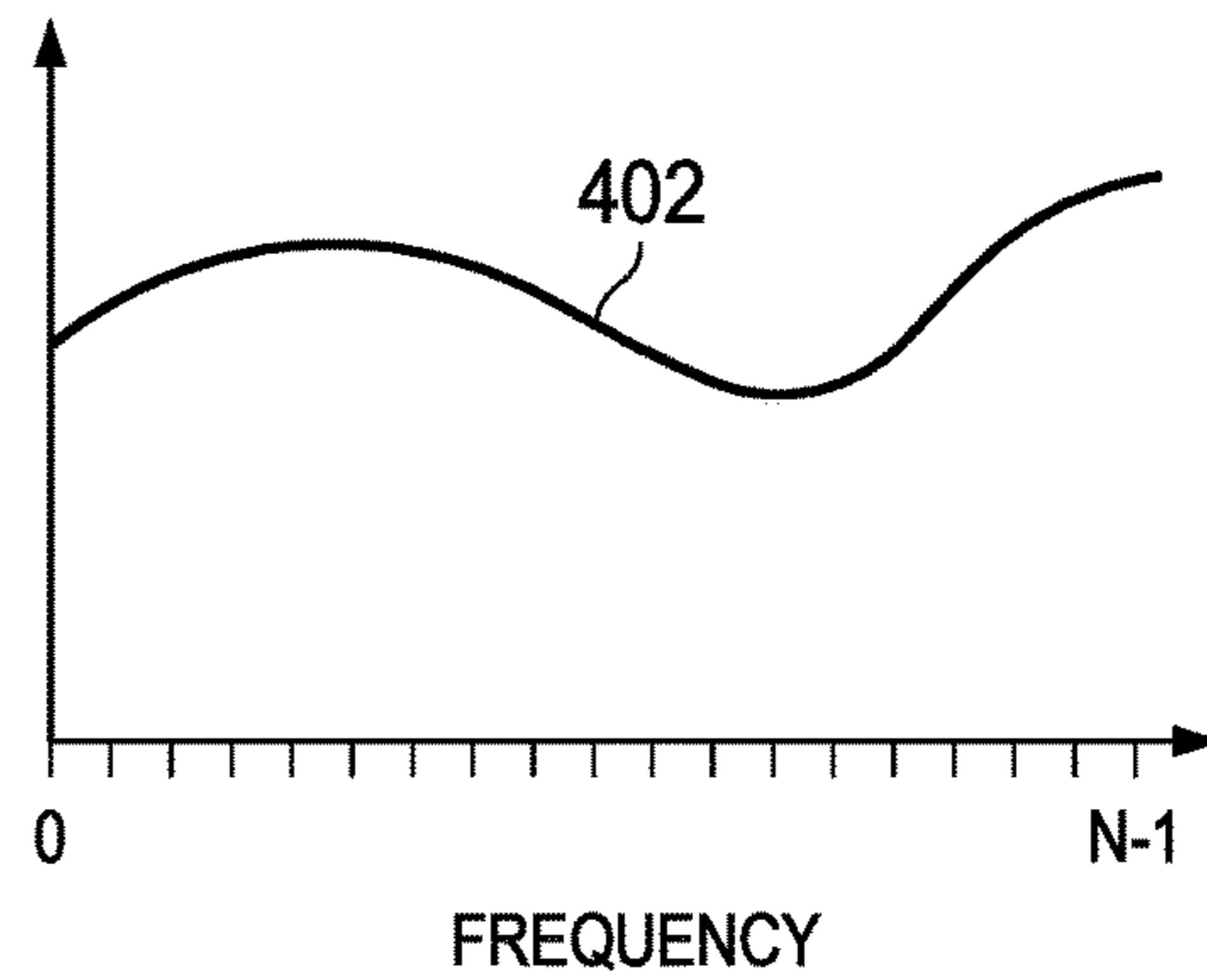


FIG. 4C

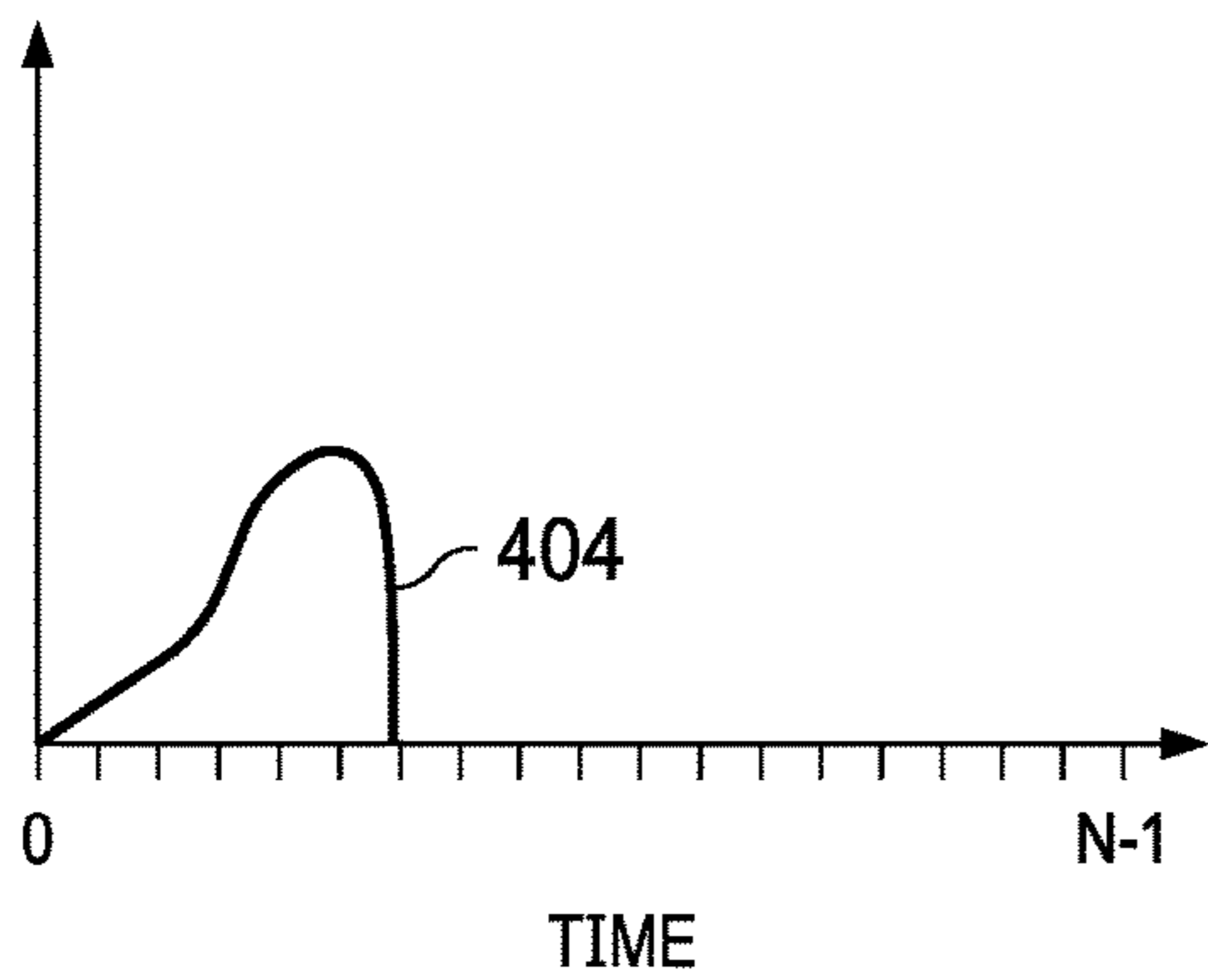


FIG. 4B

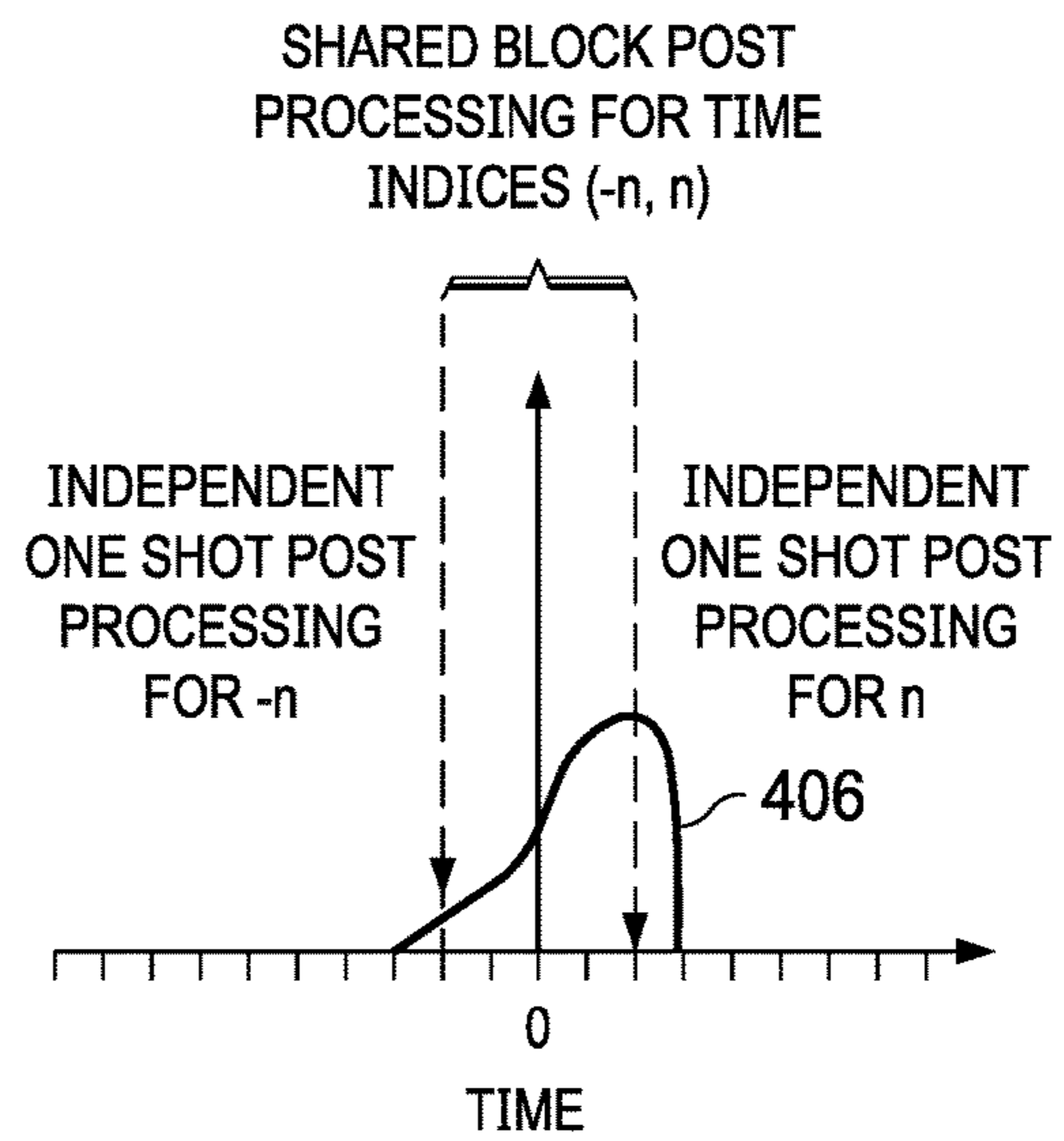


FIG. 4D

CIRCUIT FOR FREQUENCY TO TIME DOMAIN CONVERSION

CROSS-REFERENCE TO RELATED APPLICATIONS

The present application claims priority to India Provisional Patent Application No. 201841041551, filed Nov. 2, 2018, entitled "Optimized Time-Frequency Conversion," and to U.S. Provisional Patent Application No. 62/787,024, filed Dec. 31, 2018, entitled "Circuit for Frequency to Time Domain Conversion," each of which is hereby incorporated herein by reference in its entirety.

BACKGROUND

Various electronic systems include frequency to time domain conversion and vice-versa. In one example, an impairment correction circuit estimates the error introduced into a signal by imperfections in the system and attempts to correct the errors by applying a modification to the signal. An interleaved analog-to-digital converter (ADC) includes an error correction circuit that estimates the error introduced in a digital sample stream by interleaving errors caused by imperfections, such as different offsets or gains, in the interleaved ADCs, and applies a filter to the digital sample stream to correct the errors. Many such circuits estimate the errors in the frequency domain and apply a time domain filter to correct the errors.

SUMMARY

Circuits and methods for frequency to time domain conversion are disclosed herein. In one example, a method for frequency to time domain conversion includes receiving a set of frequency domain samples. Based on the set of frequency domain samples, a first sample subset including a predetermined fraction of the number of samples of the set of frequency domain samples is generated, and a second sample subset including the predetermined fraction of the number of samples of the set of frequency domain samples is generated. A linear phase rotation is applied to the first sample subset and the second sample subset to produce a phase rotated first sample subset and a phase rotated second sample subset. The phase rotated first sample set is post-processed to generate a first set of time domain samples. The phase rotated second sample set is post-processed to generate a second set of time domain samples. The first set of time domain samples and the second set of time domain samples are reordered to produce an output set of time domain samples.

In another example, a circuit for frequency to time domain transformation includes a preprocessing circuit, a linear phase shift circuit, a post-processing circuit, and a remapping circuit. The preprocessing circuit is configured to receive a set of frequency domain samples, and to generate, based on the set of frequency domain samples: a first sample subset including a predetermined fraction of the number of samples of the set of frequency domain samples, and a second sample subset including the predetermined fraction of the number of samples of the set of frequency domain samples. The linear phase shift circuit is coupled to the preprocessing circuit. The linear phase shift circuit is configured to apply a first linear phase shift to the first sample subset to produce a phase rotated first sample set, and to apply a second linear phase shift to the second sample subset to produce a phase rotated second sample set. The first linear

phase shift is different from the second linear phase shift. The post-processing circuit is coupled to the linear phase shift circuit, and is configured to: post-process the phase rotated first sample set to generate a first set of time domain samples, and post-process the phase rotated second sample set to generate a second set of time domain samples. The remapping circuit is coupled to the post-processing circuit, and is configured to reorder the first set of time domain samples and the second set of time domain samples to produce an output set of time domain samples.

In a further example, a mismatch correction system includes a mismatch estimation circuit, a frequency domain to time domain conversion circuit, and a mismatch correction circuit. The mismatch estimation circuit is configured to estimate, in the frequency domain, an impairment in an input signal. The frequency domain to time domain conversion circuit is configured to convert a set of frequency domain samples generated by the mismatch estimation circuit to time domain filter coefficients. The frequency domain to time domain conversion circuit is coupled to the mismatch estimation circuit, and includes a preprocessing circuit, a linear phase shift circuit, a post-processing circuit, and a remapping circuit. The preprocessing circuit is configured to generate, based on the set of frequency domain samples: a first sample subset comprising a predetermined fraction of the number of samples of the set of frequency domain samples, and a second sample subset comprising the predetermined fraction of the number of samples of the set of frequency domain samples. The linear phase shift circuit is coupled to the preprocessing circuit, and is configured to: apply a first linear phase shift to the first sample subset to produce a phase rotated first sample set, and apply a second linear phase shift to the second sample subset to produce a phase rotated second sample set. The first linear phase shift is different from the second linear phase shift. The post-processing circuit is coupled to the linear phase shift circuit, and is configured to post-process the phase rotated first sample set to generate a first set of time domain samples, and post-process the phase rotated second sample set to generate a second set of time domain samples. The remapping circuit is coupled to the post-processing circuit, and is configured to reorder the first set of time domain samples and the second set of time domain samples to produce the time domain filter coefficients. The mismatch correction circuit is coupled to the frequency domain to time domain conversion circuit, and includes a time domain filter. The time domain filter is configured to apply the time domain filter coefficients to correct the impairment in the input signal.

BRIEF DESCRIPTION OF THE DRAWINGS

For a detailed description of various examples, reference will now be made to the accompanying drawings in which:

FIG. 1 shows block diagram for an example mismatch correction system in accordance with the present disclosure;

FIG. 2 shows a block diagram for an example frequency to time domain conversion circuit in accordance with the present disclosure;

FIG. 3 shows a block diagram for an example post-processing circuit used to convert samples from frequency to time domain in accordance with the present disclosure;

FIGS. 4A-4D show frequency domain samples and time domain samples produced by conversion from frequency domain to time domain in accordance with the present disclosure; and

FIG. 5 shows a flow diagram for an example method for converting from frequency domain to time domain in accordance with the present disclosure.

DETAILED DESCRIPTION

Certain terms have been used throughout this description and claims to refer to particular system components. As one skilled in the art will appreciate, different parties may refer to a component by different names. This document does not intend to distinguish between components that differ in name but not function. In this disclosure and claims, the terms “including” and “comprising” are used in an open-ended fashion, and thus should be interpreted to mean “including, but not limited to . . .” Also, the term “couple” or “couples” is intended to mean either an indirect or direct connection. Thus, if a first device couples to a second device, that connection may be through a direct connection or through an indirect connection via other devices and connections. The recitation “based on” is intended to mean “based at least in part on.” Therefore, if X is based on Y, X may be a function of Y and any number of other factors.

In many systems that include impairment correction, the error in an input signal is estimated most efficiently in the frequency domain and the correction is applied most efficiently in the time domain. Thus, the input signal is converted from the time domain to the frequency domain for error estimation, and the frequency domain error estimation is converted to the time domain for use in correcting the input signal. The processing time needed to perform the conversion between time and frequency domains limits the update rate of the impairment estimation and correction.

The frequency-to-time domain conversion circuits and methods disclosed herein substantially reduce (e.g., by a factor of 8) the complexity of frequency domain to time domain conversion of an error estimate, which in-turn reduces the time needed to perform frequency to time domain conversion, and enables an increased error estimation and correction update rate. The circuitry required to perform the conversion is simplified by replacing complex multipliers with real multipliers. A shared post-processing is used to compute positive and negative index values of the time domain output, and conversion from frequency to time domain uses a single coefficient fetch per tap pair, thereby reducing the number of memory accesses in the post processing.

FIG. 1 shows block diagram for an example mismatch correction system 100 in accordance with the present disclosure. The mismatch correction system 100 may be included in an analog-to-digital converter, a wireless transceiver, or other system that provides correction for an impairment in a signal used in the system. The mismatch correction system 100 includes a mismatch estimation circuit 102, a mismatch correction circuit 104, and a frequency to time domain conversion circuit 106. The mismatch estimation circuit 102 and the mismatch correction circuit 104 receive time domain samples 110 (time domain input signal 110). The mismatch estimation circuit 102 includes circuitry that converts the time domain samples 110 to frequency domain samples and estimates, in the frequency domain, an impairment (i.e., an error) in the time domain samples 110. The estimation includes correlation and averaging of the frequency domain samples, mismatch estimation, filtering, and model fitting using frequency domain correlation. The mismatch estimation circuit 102 provides the frequency

domain coefficients 112 (i.e., frequency domain samples 112) that describe the error to the frequency to time domain conversion circuit 106.

The frequency to time domain conversion circuit 106 converts the frequency domain samples 112 to time domain coefficients 116 (time domain samples 116) that are applied in the mismatch correction circuit 104 to generate the corrected signal 114 from the time domain samples 110. The number of the time domain samples 116 generated by the frequency to time domain conversion circuit 106 is substantially lower than the number of the frequency domain samples 112 received from the mismatch estimation circuit 102. For example, given 128 frequency domain samples 112, the frequency to time domain conversion circuit 106 may generate 17 time domain samples 116 for use in the mismatch correction circuit 104.

The mismatch correction circuit 104 a time domain filter 108 that applies the time domain coefficients 116 generated by the frequency to time domain conversion circuit 106 to correct the error in the time domain samples 110 and produce the corrected signal 114.

FIG. 2 shows a block diagram for an example frequency to time domain conversion circuit 200 in accordance with the present disclosure. The frequency to time domain conversion circuit 200 is an implementation of the frequency to time domain conversion circuit 106. The frequency to time domain conversion circuit 200 processes the frequency domain samples 112 to generate the time domain samples 116. The frequency to time domain conversion circuit 200 includes a preprocessing circuit 202, a preprocessing circuit 204, a linear phase shift circuit 206, a linear phase shift circuit 208, a post-processing block 210, a post-processing block 212, and a remapping circuit 214. The preprocessing circuit 202 and the preprocessing circuit 204 (collectively preprocessing circuit 201) receive the frequency domain samples 112 from a data source, such as the mismatch estimation circuit 102. Each of the preprocessing circuit 202 and the preprocessing circuit 204 processes the frequency domain samples 112 to generate a sample subset one-half the size of the frequency domain samples 112. The preprocessing circuit 202 generates each output sample of the sample subset 216 as a sum of two samples of the frequency domain samples 112:

$$T_0[k] = H[k] + H\left[k + \frac{N}{2}\right] \quad (1)$$

where:

T_0 is output sample subset 216 generated by the preprocessing circuit 202;

H is the frequency domain samples 112;

N is the number of samples in the frequency domain samples 112; and

k is 0 to 63 for $N=128$.

The preprocessing circuit 204 generates each sample of sample subset 218 as a difference of two samples of the frequency domain samples 112:

$$T_1[k] = H[k] - H\left[k + \frac{N}{2}\right] \quad (2)$$

where T_1 is sample subset 218 generated by the preprocessing circuit 202

The linear phase shift circuits **206** and **208** (collectively linear phase shift circuit **207**) apply a linear phase ramp to the sample subsets **216** and **218**. The linear phase shift circuit **206** applies a linear phase ramp θ_0 (e.g., $=-8$) to the sample subset **216** to produce a phase rotated sample set **220** ($G[k]$). The linear phase shift circuit **208** applies a linear phase ramp θ_1 (e.g., $=-7$) to the sample subset **218** to produce a phase rotated sample set **222** ($F[k]$). The linear phase shift circuit **206** and the linear phase shift circuit **208** provide a time shift in the frequency domain, e.g.,

$$G(k) = T_0(k)e^{-j2\pi\theta_0\frac{k}{N}}.$$

For example, the linear phase shift circuit **206** provides an 8 tap shift of the sample subset **216**, and the linear phase shift circuit **208** provides a 7 tap shift of the sample subset **218**.

The post-processing circuits **210** and **212** (collectively post-processing circuit **211**) transform the phase rotated sample set **220** and the phase rotated sample set **222** from time to frequency domain. In one implementation, the time domain conversion can be performed using a post-processing circuit **210** that generates the coefficients for the even taps of the time domain filter **108**, and a post-processing circuit **212** that generates the coefficients for the odd taps of the time domain filter **108**. FIG. 3 shows an example block diagram for a post-processing circuit **300** used to convert samples from frequency to time domain in accordance with the present disclosure. The post-processing circuit **300** is an implementation of the post-processing circuit **210** and/or the post-processing circuit **212**. The post-processing circuit **300** includes a shared block processing circuit **302** and an independent one-shot post-processing circuit **304** coupled to the shared block processing circuit **302**. In one example, samples produced by the linear phase shift circuit **206** (or the linear phase shift circuit **208**) are processed by the shared block processing circuit **302** to generate output samples **306** and **308**. The output samples **306** and **308** (shared block processing circuit output samples **306** and **308**) are processed by the independent one-shot post-processing circuit **304** to produce pairs of time domain samples **224** (or time domain samples **226**).

The post processing circuit **300** (time domain conversion circuit **300**) computes time domain samples in two steps. First, the shared block processing circuit **302** generates intermediate samples $y(k)$ for desired time domain sample index pairs $(n, -n)$ as follows:

$$y(k) = G(k) + 2\cos\left(\frac{2\pi n}{N}\right)y(k-1) - y(k-2), \text{ for } k = 0, \dots, \frac{N}{2} - 1$$

where this operation is performed $N/2$ times (e.g., 64) for the frequency domain samples in the phase rotated sample set **220**. This is followed by two computations using the independent one-shot post-processing circuit **304**, once for computing the time domain sample $g(n)$ and the second time for computing the time domain sample $g(-n)$, for all non-zero indices n as follows:

$$g(n) = y\left(\frac{N}{2}\right) - W_N^{-n}y\left(\frac{N}{2} - 1\right)$$

where

$$W_N^n = e^{-j \times 2\pi \frac{n}{N}}.$$

The post-processing circuit **300** is applied to obtain all desired time domain sample pairs, for different values for n . The zero-index time domain sample is computed as the sum of all of the samples of the phase rotated sample set **220**.

The structure of the shared block processing circuit **302** is the same for generation of positive and negative indexed time domain samples ($\pm n$). The post processing circuit **300** computes the positive and negative indexed time domain samples ($g(\pm n)$) using the shared block processing circuit **302** followed by independent computations of the independent one-shot post processing circuit **304**. The shared block processing circuit **302** uses a fixed, real twiddle multiplier of

$$2\cos\left(\frac{2\pi n}{64}\right)$$

where the phase rotated sample set **220** includes 64 frequency domain samples. Thus, for each tap pair, the shared block processing circuit **302** fetches a single coefficient from memory, which reduces the number of memory accesses needed to perform the conversion.

Computation of the time domain samples time domain samples **226** ($f(n)$) in the post-processing circuit **212** is similar to computation of the time domain samples **224** ($g(n)$). The zero-index time domain sample is computed as the sum of all of the samples of the phase rotated sample set **222**.

The remapping circuit **214** combines and reorders the time domain samples **224** and time domain samples **226** to produce the time domain samples **116**. For example, given the time domain samples **224**

$[g(-4), g(-3), g(-2), g(-1), g(0), g(1), g(2), g(3), g(4)]$ generated by the post-processing circuit **210**, and the time domain samples **226**

$[f(-4), f(-3), f(-2), f(-1), f(0), f(1), f(2), f(3), f(4)]$ generated by the post-processing circuit **212**, the remapping circuit **214** interleaves the time domain samples **224** and the time domain samples **226** to produce the time domain samples **116** as:

$h(n)=[g(-4), f(-3), g(-3), f(-2), g(-2), f(-1), g(-1), f(0), g(0), f(1), g(1), f(2), g(2), f(3), g(3), f(4), g(4)]$

Examples of the frequency to time domain conversion circuit **200** and/or the post-processing circuit **300** are implemented as dedicated circuitry configured to perform the functions disclosed herein, or as a processor (e.g., a general-purpose microprocessor or a digital signal processor) that executes instructions fetched from memory to perform the functions disclosed herein.

Some implementations of the frequency to time domain conversion circuit **200** include preprocessing circuitry that produces more than two subsets of samples for phase rotation, and corresponding linear phase shifting, post processing, and remapping circuitry. Each of the subsets of samples includes a predetermined fraction ($1/2$, $1/4$, etc.) of the number of samples of the frequency domain samples **112**. For example, an implementation of the frequency to time domain conversion circuit **200** includes four preprocessing circuits that produce four sample subsets (T_0 , T_1 , T_2 , and T_3), each including one-quarter the number of samples

of the frequency domain samples **112**. A linear phase shift circuit applies a phase rotation to each sample subset, a modified post processing circuit **300** produces time domain samples as described herein, and a remapping circuit interleaves the four sets of time domain samples to produce the time domain samples **116**. Because the number of samples processed in the post-processing circuit **300** is reduced due to the smaller frequency domain sample subset, the number of iterations of the shared block processing circuit **302** executed to produce a time domain sample is also reduced.

FIGS. **4A-4D** show frequency domain samples and time domain samples produced by conversion from frequency domain to time domain in accordance with the present disclosure. In FIG. **4A** a set of frequency domain samples **402** are illustrated. In FIG. **4B**, a set of time domain samples **404** derived from the frequency domain samples **402** is shown. The time domain samples **404** start at time index 0, and may be produced by applying an inverse fast Fourier transform to the frequency domain samples **402** and discarding the resulting coefficients that are not included in the time domain samples **404**. Alternatively, an inverse discrete Fourier transform may be executed for each sample of the time domain samples **404**.

FIG. **4C** shows the frequency domain samples **402** (as in FIG. **4A**). FIG. **4D** shows the time domain samples **406**, which include the same values as the time domain samples **404**, but are shifted to be centered about time index 0. The time shift is a result of the linear phase rotation applied to the sample subset **216** and the sample subset **218** by the linear phase shift circuit **206** and the linear phase shift circuit **208**. The time shift allows the post-processing circuit **300** to provided common block processing to generate time domain samples for positive and negative time indices, with separate one time processing for positive and negative time indices.

FIG. **5** shows a flow diagram for an example method **500** for converting from frequency domain to time domain in accordance with the present disclosure. Though depicted sequentially as a matter of convenience, at least some of the actions shown can be performed in a different order and/or performed in parallel. Additionally, some implementations may perform only some of the actions shown. Operations of the method **500** are performed by the frequency to time domain conversion circuit **200** in some implementations.

In block **502**, the frequency to time domain conversion circuit **200** receives the frequency domain samples **112**.

In block **504**, the preprocessing circuit **202** generates each sample of the sample subset **216** as a sum of two samples of the frequency domain samples **112** as per equation (1). The sample subset **216** includes one-half the number of samples of the frequency domain samples **112** in some implementations.

In block **506**, the preprocessing circuit **204** generates each sample of the sample subset **218** as a difference of two samples of the frequency domain samples **112** as per equation (2). The sample subset **218** includes one-half the number of samples of the frequency domain samples **112** in some implementations.

In block **508**, the linear phase shift circuit **206** applies a linear phase rotation to the sample subset **216** to produce the phase rotated sample set **220**.

In block **510**, the linear phase shift circuit **208** applies a linear phase rotation to the sample subset **218** to produce the phase rotated sample set **222**. The phase rotation applied by the linear phase shift circuit **208** is different from the phase rotation applied by the linear phase shift circuit **206**.

In block **512**, the post-processing circuit **210** processes the phase rotated sample set **220** to produce the time domain

samples **224**. The post-processing includes applying block processing circuit **300** to the phase rotated sample set **220**.

In block **514**, the post-processing circuit **212** processes the phase rotated sample set **222** to produce the time domain samples **226**. The post-processing includes applying block processing circuit **300** to the phase rotated sample set **222**.

In block **516**, the remapping circuit **214** reorders and combines the time domain samples **224** and the time domain samples **226** to produce the time domain samples **116**.

The above discussion is meant to be illustrative of the principles and various embodiments of the present invention. Numerous variations and modifications will become apparent to those skilled in the art once the above disclosure is fully appreciated. It is intended that the following claims be interpreted to embrace all such variations and modifications.

What is claimed is:

1. A method for frequency to time domain conversion, comprising:
 - receiving a set of frequency domain samples;
 - generating, based on the set of frequency domain samples:
 - a first sample subset comprising a predetermined fraction of the number of samples of the set of frequency domain samples; and
 - a second sample subset comprising the predetermined fraction of the number of samples of the set of frequency domain samples;
 - applying a linear phase rotation to the first sample subset and the second sample subset to produce a phase rotated first sample set and a phase rotated second sample subset;
 - post-processing the phase rotated first sample set to generate a first set of time domain samples;
 - post-processing the phase rotated second sample set to generate a second set of time domain samples; and
 - reordering the first set of time domain samples and the second set of time domain samples to produce an output set of time domain samples.
2. The method of claim 1, further comprising:
 - generating each sample of the first sample subset as a sum of two samples of the set of frequency domain samples;
 - generating each sample of the second sample subset as a difference of two samples of the set of frequency domain samples.
3. The method of claim 1, wherein the linear phase rotation applied to the first sample subset is different from the linear phase rotation applied to the second sample subset.
4. The method of claim 1, wherein post-processing the phase rotated first sample set comprises applying a block processing to a block of samples of the phase rotated first sample set to generate a block processed sample set.
5. The method of claim 4, wherein post-processing the phase rotated first sample set comprises applying an independent one shot processing to the block processed sample set to generate the first set of time domain samples.
6. The method of claim 5, wherein applying the independent one shot processing comprises:
 - executing a first computation of the independent one shot processing to generate a positive index time domain sample; and
 - executing a second computation of the independent one shot processing to generate a negative index time domain sample.
7. The method of claim 1, wherein post-processing the phase rotated second sample set comprises applying a block

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processing to a block of samples of the phase rotated second sample set to generate a block processed sample set.

8. The method of claim 7, wherein post-processing the phase rotated second sample set comprises applying an independent one shot processing to the block processed sample set to generate the second set of time domain samples.

9. The method of claim 1, wherein:

post processing the phase rotated first sample set comprises generating a zero index sample of the first set of time domain samples as a sum of all the samples of the first phase rotated sample set; and

post processing the phase rotated second sample set comprises generating a zero index sample of the second set of time domain samples as a sum of all the samples of the second phase rotated sample set.

10. The method of claim 1, wherein the reordering comprises interleaving the first set of time domain samples and the second set of time domain samples in order of ascending sample index.

11. A circuit for frequency to time domain transformation, comprising:

a preprocessing circuit configured to:

receive a set of frequency domain samples;
generate, based on the set of frequency domain samples:

a first sample subset comprising a predetermined fraction of the number of samples of the set of frequency domain samples; and

a second sample subset comprising the predetermined fraction of the number of samples of the set of frequency domain samples;

a linear phase shift circuit coupled to the preprocessing circuit, and configured to:

apply a first linear phase rotation to the first sample subset to produce a phase rotated first sample set; and

apply a second linear phase rotation to the second sample subset to produce a phase rotated second sample set;

wherein the first linear phase rotation is different from the second linear phase rotation;

a post processing circuit coupled to the linear phase shift circuit, and configured to:

post process the phase rotated first sample set to generate a first set of time domain samples; and
post process the phase rotated second sample set to generate a second set of time domain samples; and

a remapping circuit coupled to the post processing circuit, and configured to reorder the first set of time domain samples and the second set of time domain samples to produce an output set of time domain samples.

12. The circuit of claim 11, wherein the preprocessing circuit is configured to:

add a first sample of the set of frequency domain samples to a second sample of the set of frequency domain samples to generate a sample of the first sample subset; subtract the first sample of the set of frequency domain samples from the second sample of the set of frequency domain samples to generate a sample of the second sample subset.

13. The circuit of claim 11, wherein the post processing circuit comprises:

a shared block processing circuit configured to process each sample of the phase rotated first sample set to generate a block processed sample set; and

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an independent one shot post processing circuit coupled to the shared block processing circuit, and configured to process the block processed sample set to generate the first set of time domain samples.

14. The circuit of claim 11, wherein the post processing circuit comprises:

a shared block processing circuit configured to process each sample of the phase rotated second sample set to generate a block processed sample set; and

an independent one shot post processing circuit coupled to the shared block processing circuit, and configured to process the block processed sample set to generate the second set of time domain samples.

15. The circuit of claim 11, wherein the post processing circuit is configured to:

sum of all the samples of the first phase rotated sample set to generate a zero index sample of the first set of time domain samples; and

sum of all the samples of the second phase rotated sample set to generate a zero index sample of the second set of time domain samples.

16. The circuit of claim 11, wherein the remapping circuit is configured to interleave the first set of time domain samples and the second set of time domain samples in order of ascending sample index.

17. A mismatch correction system, comprising:

a mismatch estimation circuit configured to estimate, in the frequency domain, an impairment in an input signal;

a frequency domain to time domain conversion circuit coupled to the mismatch estimation circuit, and configured to convert a set of frequency domain samples generated by the mismatch estimation circuit to time domain filter coefficients, the frequency domain to time domain conversion circuit comprising:

a preprocessing circuit configured to generate, based on the set of frequency domain samples:

a first sample subset comprising a predetermined fraction of the number of samples of the set of frequency domain samples; and

a second sample subset comprising the predetermined fraction of the number of samples of the set of frequency domain samples;

a linear phase shift circuit coupled to the preprocessing circuit, and configured to:

apply a first linear phase shift to the first sample subset to produce a phase rotated first sample set; and

apply a second linear phase shift to the second sample subset to produce a phase rotated second sample set;

wherein the first linear phase shift is different from the second linear phase shift;

a post processing circuit coupled to the linear phase shift circuit, and configured to:

process the phase rotated first sample set to generate a first set of time domain samples; and

process the phase rotated second sample set to generate a second set of time domain samples; and

a remapping circuit coupled to the post processing circuit, and configured to reorder the first set of time domain samples and the second set of time domain samples to produce the time domain filter coefficients; and

a mismatch correction circuit coupled to the frequency domain to time domain conversion circuit, and comprising:

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a time domain filter configured to apply the time domain filter coefficients to correct the input signal.

18. The system of claim **17**, wherein the preprocessing circuit is configured to:

add a first sample of the set of frequency domain samples
to a second sample of the set of frequency domain
samples to generate a sample of the first sample subset;
subtract the first sample of the set of frequency domain
samples from the second sample of the set of frequency
domain samples to generate a sample of the second
sample subset.

19. The system of claim **17**, wherein the post processing circuit comprises:

a shared block processing circuit configured to:
process each sample of the phase rotated first sample
set to generate a first block processed sample set; and
process each sample of the phase rotated second sample
set to generate a second block processed sample set
and

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an independent one shot post processing circuit coupled to the shared block processing circuit, and configured to:
process the first block processed sample set to generate the first set of time domain samples; and

process the second block processed sample set to generate the second set of time domain samples.

20. The system of claim **17**, wherein the post processing circuit is configured to:

sum of all the samples of the first phase rotated sample set to generate a zero index sample of the first set of time domain samples; and

sum of all the samples of the second phase rotated sample set to generate a zero index sample of the second set of time domain samples.

21. The system of claim **17**, wherein the remapping circuit is configured to interleave the first set of time domain samples and the second set of time domain samples in order of ascending sample index to generate the time domain filter coefficients.

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