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(54) **PAM-N JITTER/NOISE DECOMPOSITION ANALYSIS**

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H04L 1/00 (2006.01)
H04L 25/03 (2006.01)

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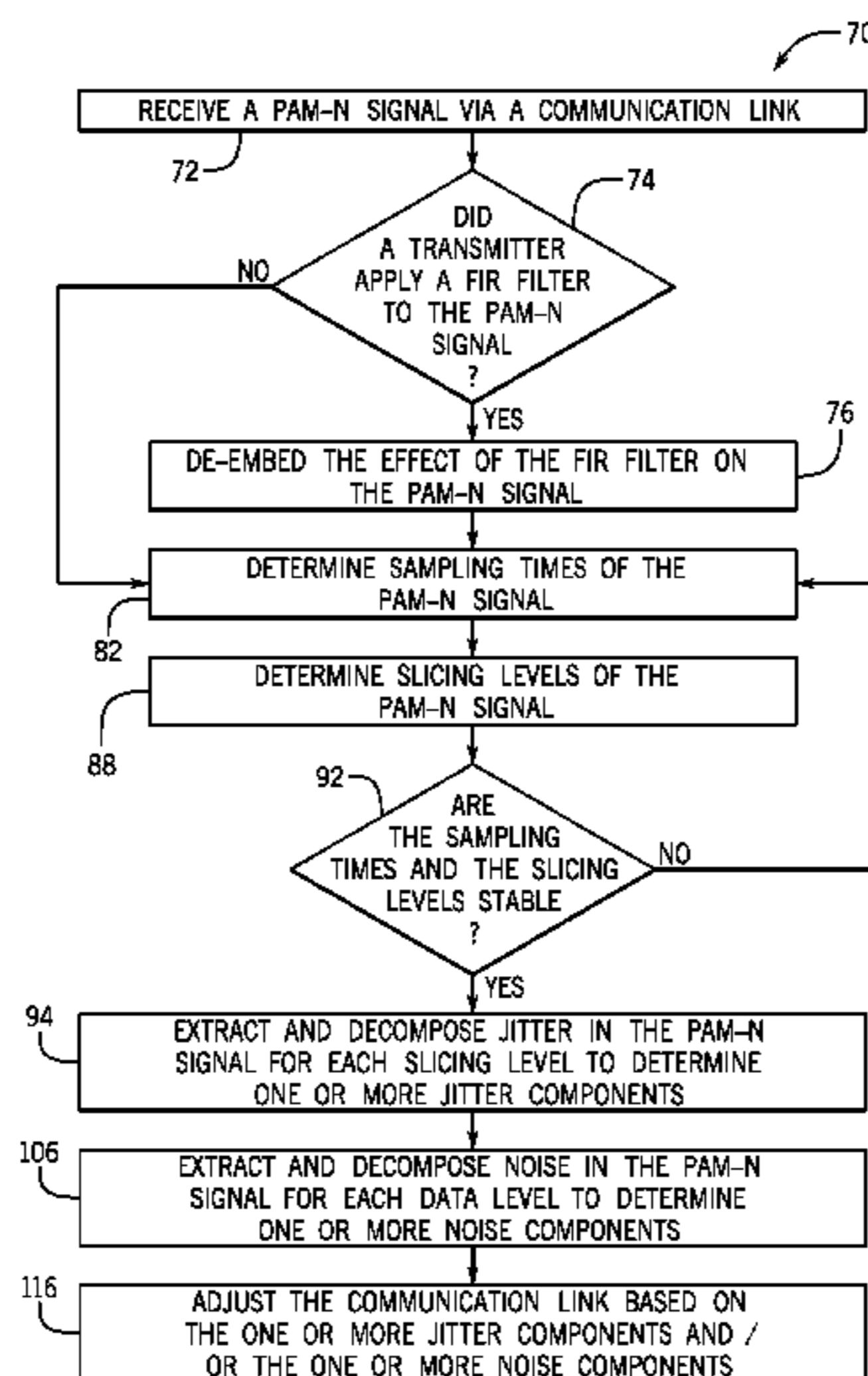
(58) **Field of Classification Search**
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See application file for complete search history.

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(57) **ABSTRACT**
A method includes receiving an n-level Pulse Amplitude Modulated (PAM-n) signal at a receiver from a transmitter via a channel. The method also includes determining one or more sampling times of the PAM-n signal. The method further includes determining one or more slicing levels of the PAM-n signal. The method also includes extracting and decomposing jitter in the PAM-n signal for each slicing level of the PAM-n signal to determine one or more jitter components. The method further includes extracting and decomposing noise in the PAM-n signal for each data level of the PAM-n signal to determine one or more noise components. The method also includes adjusting the receiver, the transmitter, the channel, or any combination thereof, based on the one or more jitter components, the one or more noise components, or both.

18 Claims, 8 Drawing Sheets



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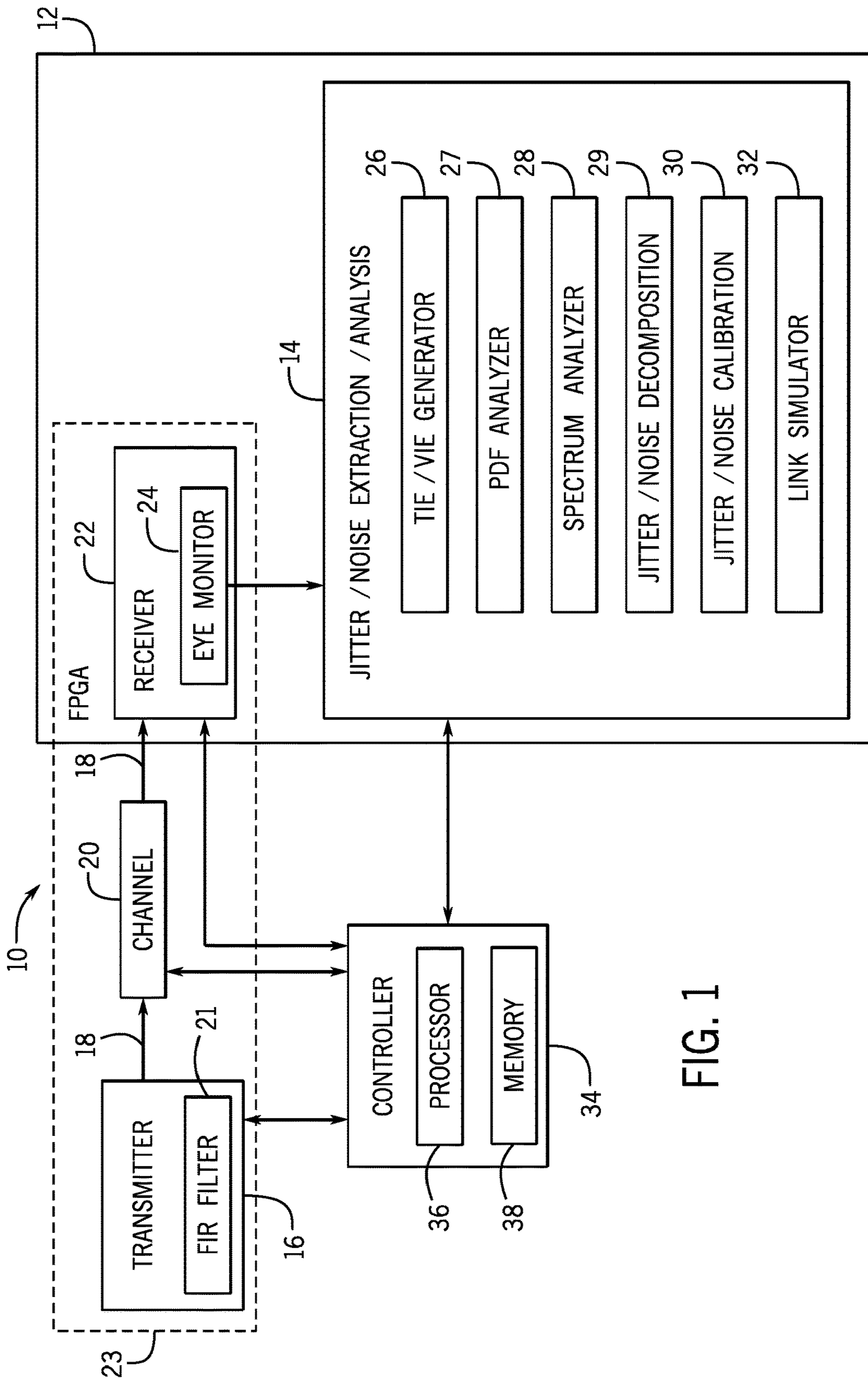


FIG. 1

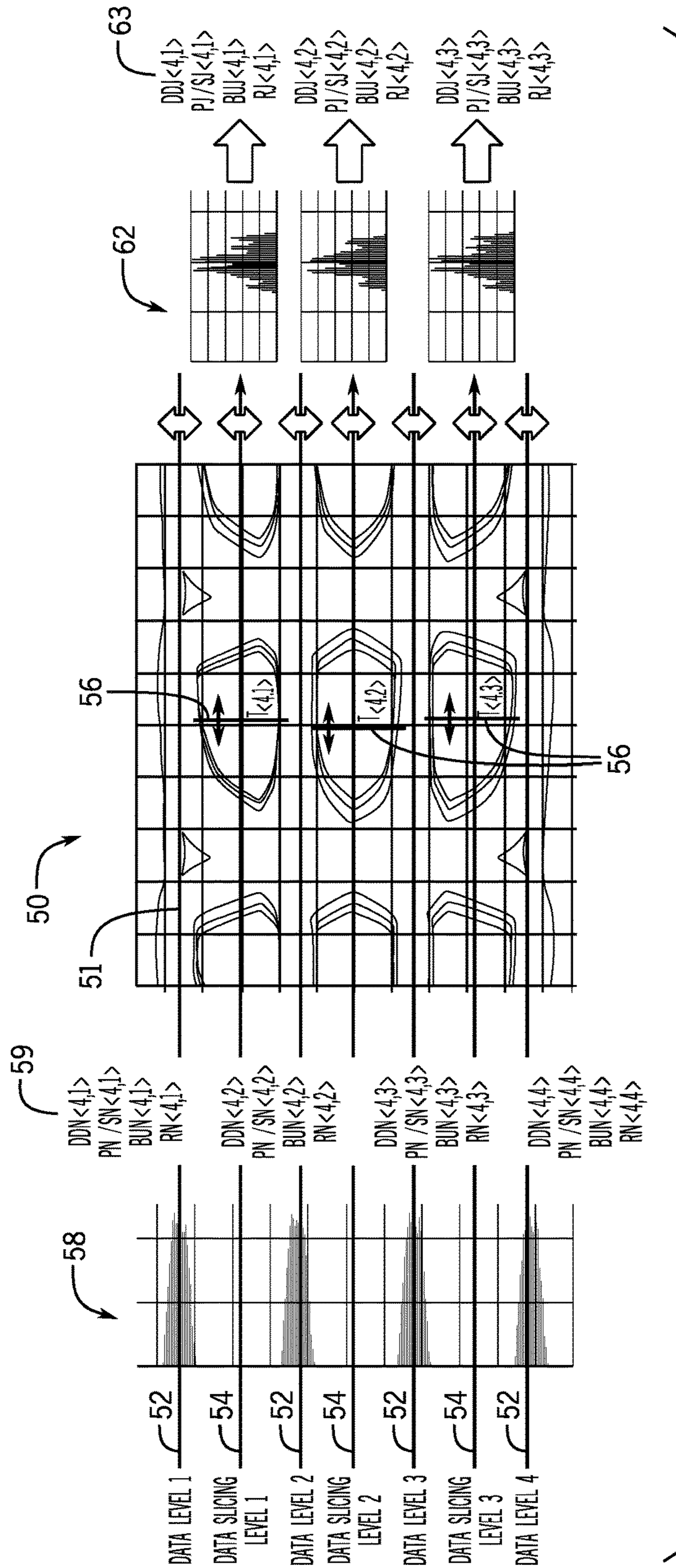


FIG. 2

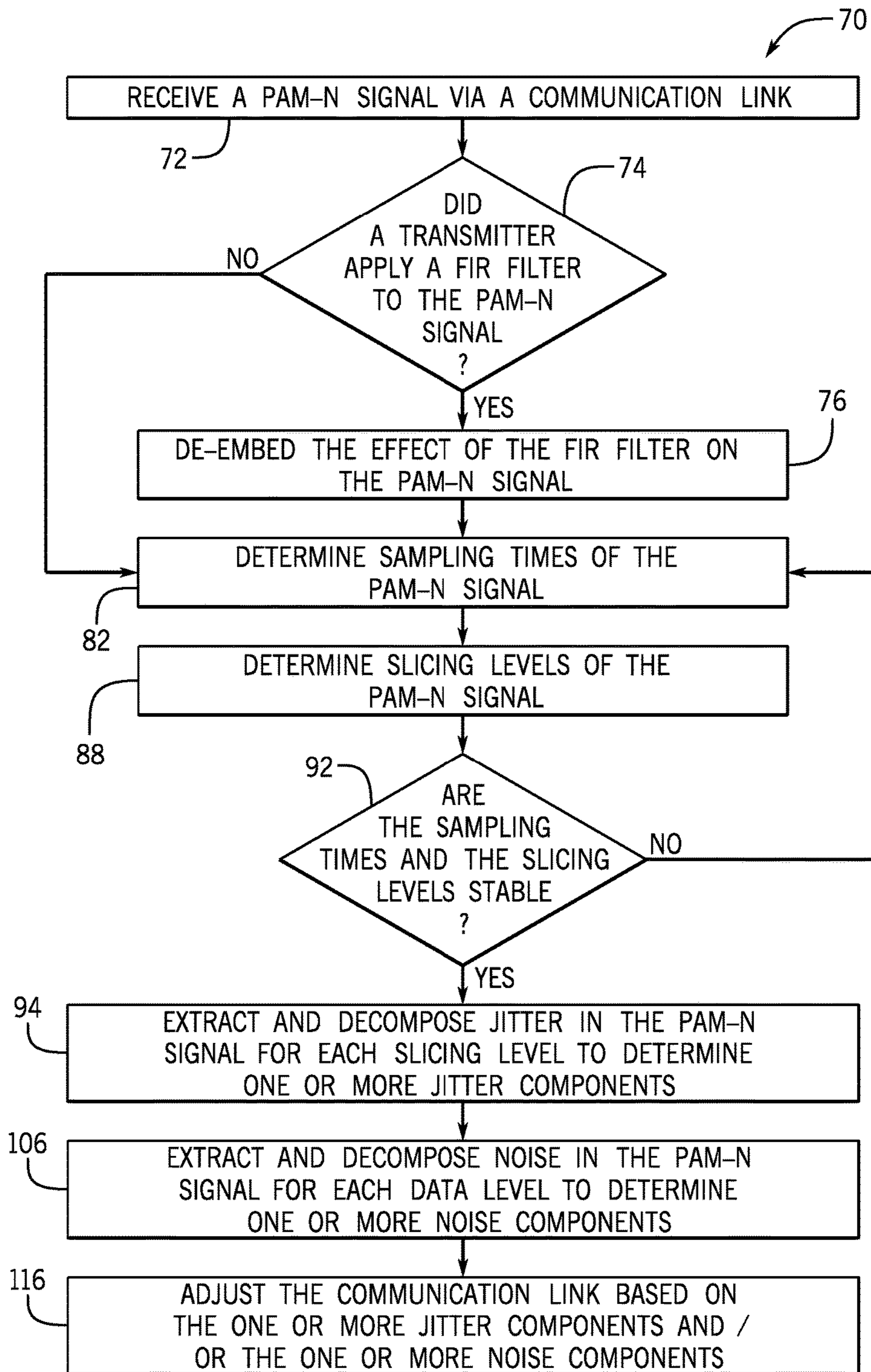
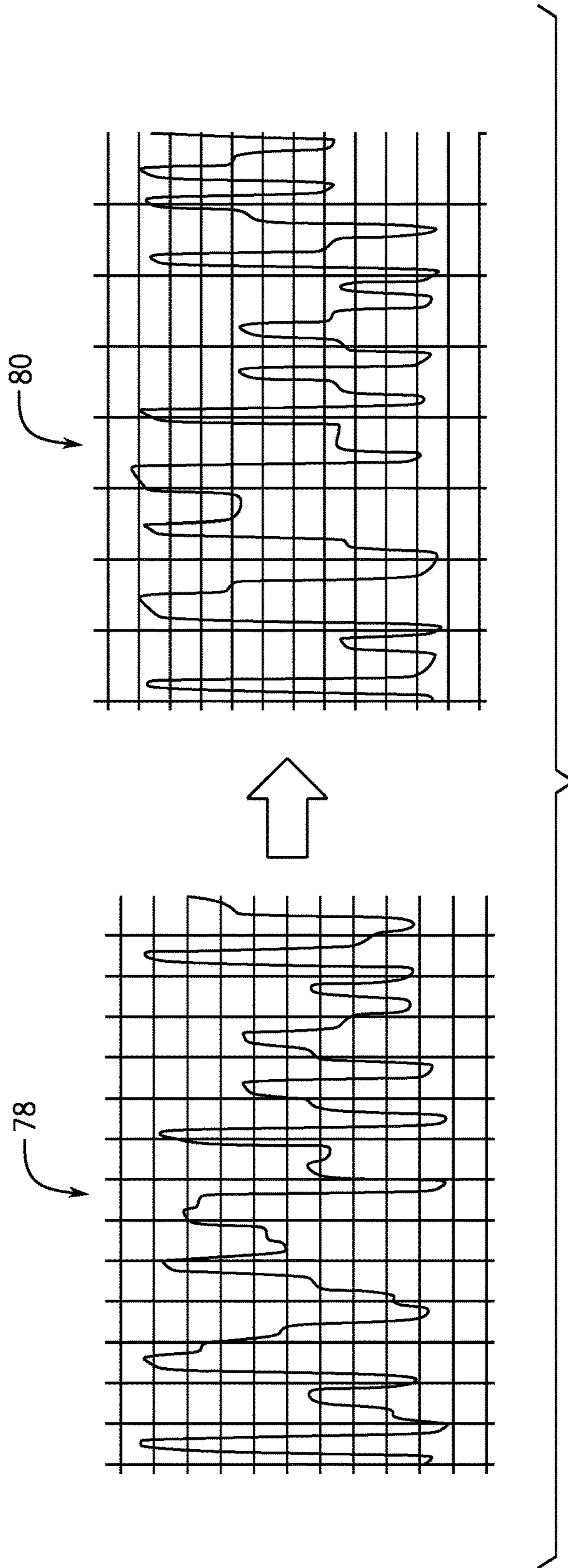
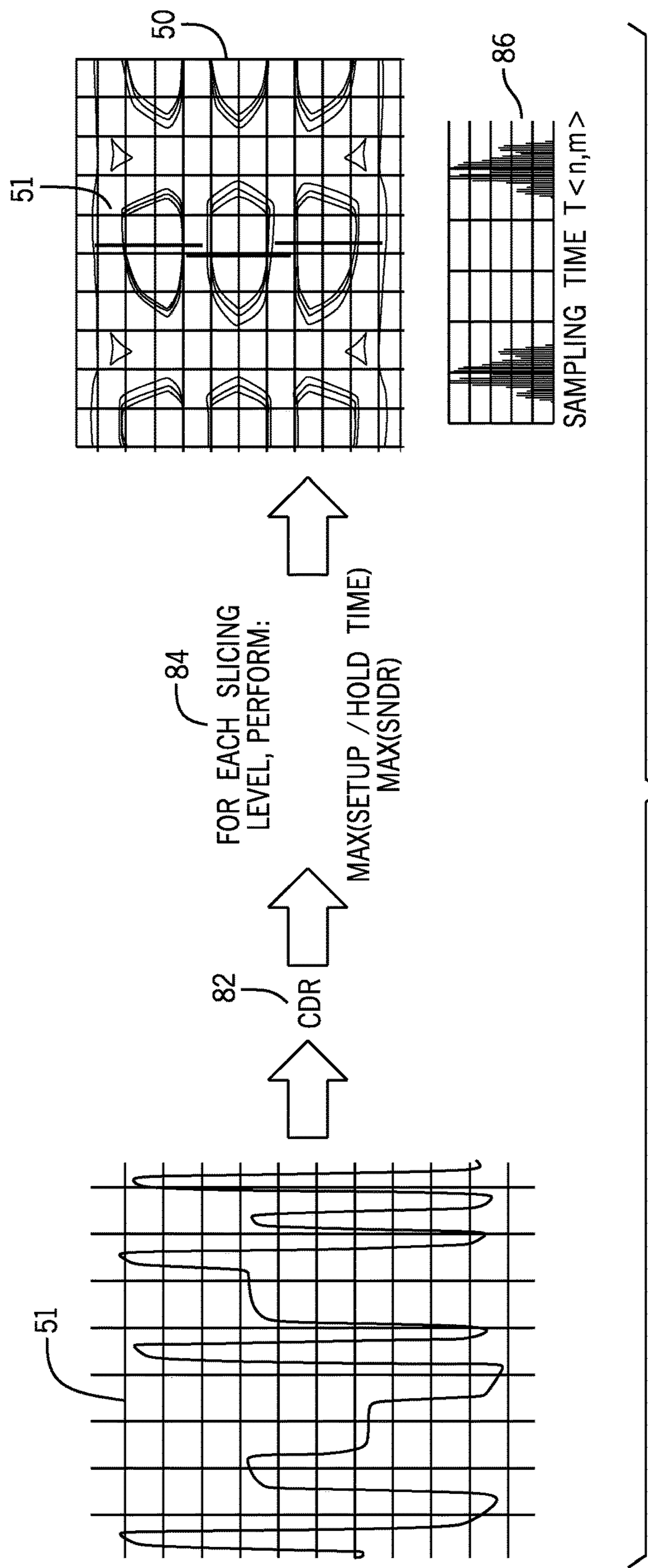


FIG. 3





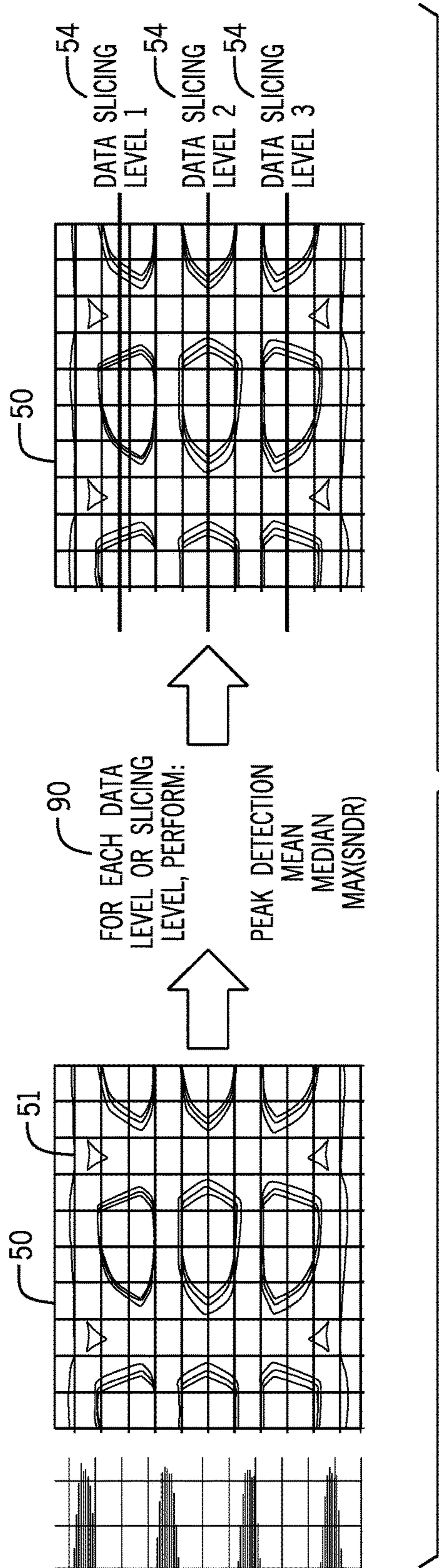


FIG. 6

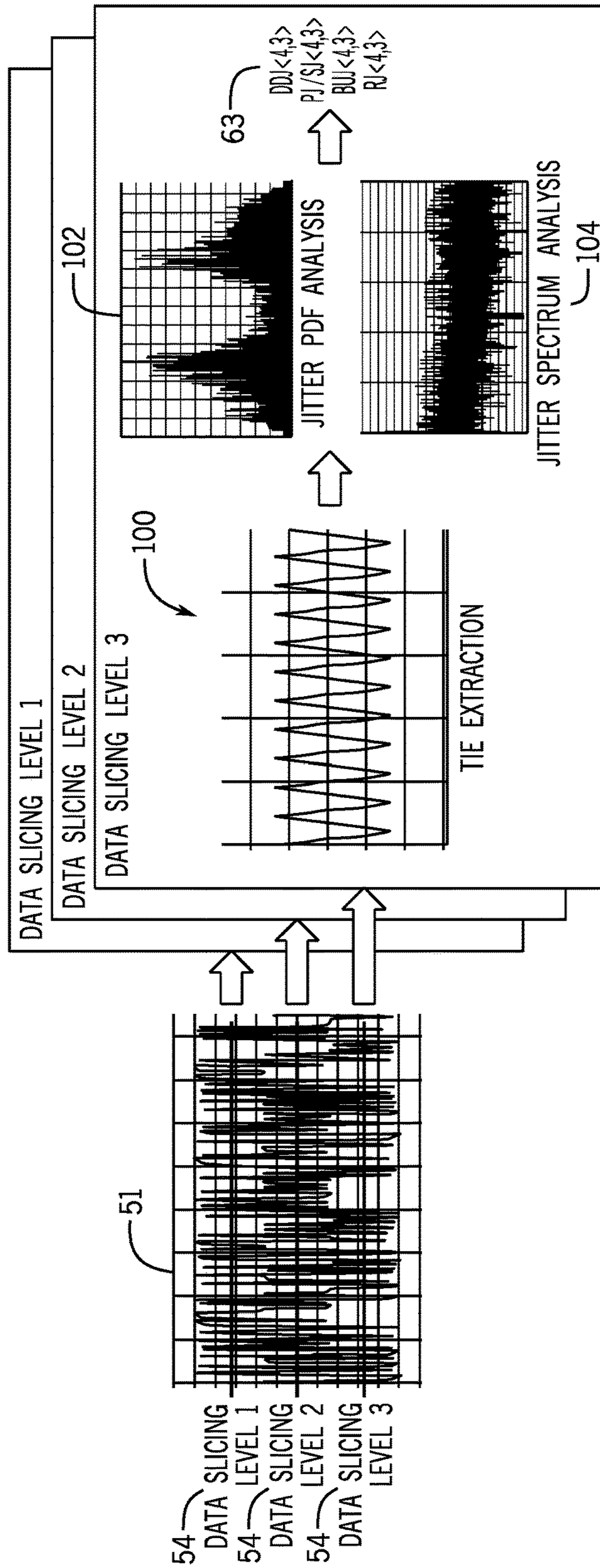


FIG. 7

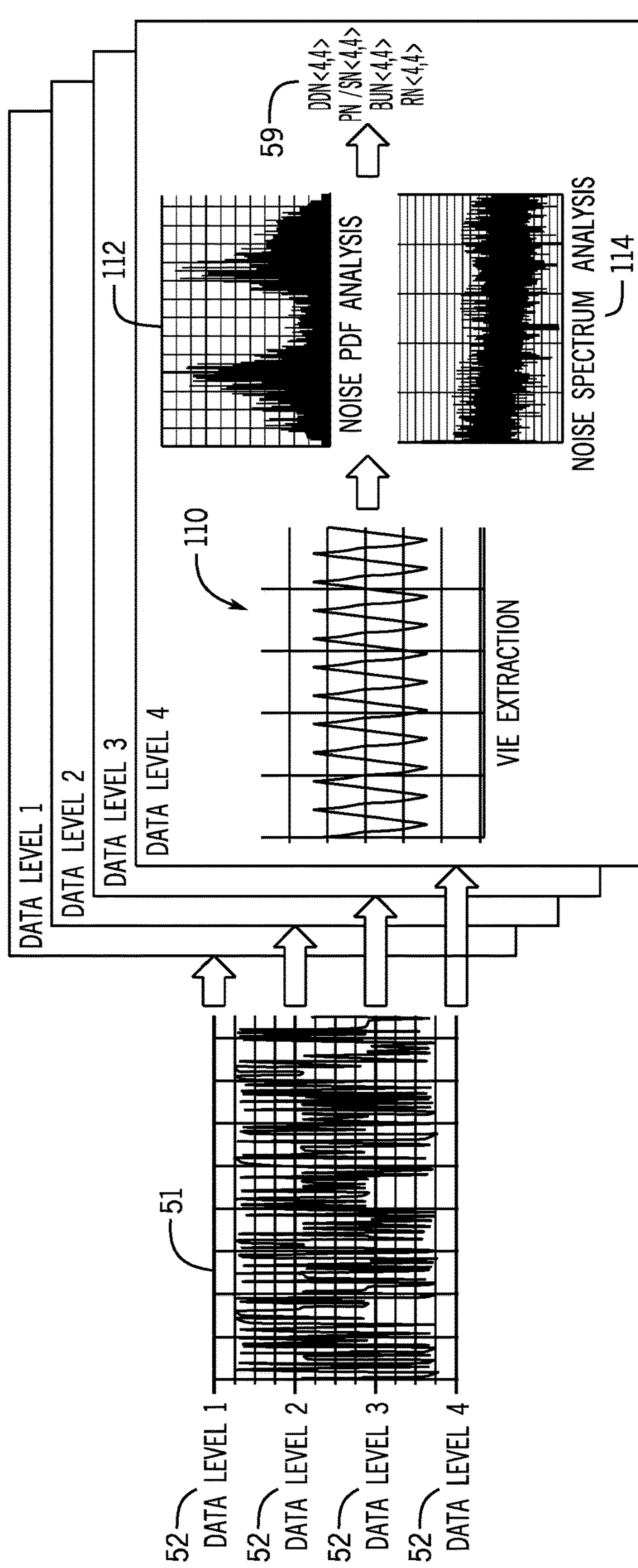


FIG. 8

**PAM-N JITTER/NOISE DECOMPOSITION
ANALYSIS**

CROSS-REFERENCE TO RELATED
APPLICATION

This application is a continuation of U.S. application Ser. No. 15/443,791, filed Feb. 27, 2017, entitled "PAM-N JITTER/NOISE DECOMPOSITION ANALYSIS," which claims benefit of U.S. Provisional Application No. 62/380,266, filed Aug. 26, 2016, entitled "PAM-N JITTER/NOISE DECOMPOSITION ANALYSIS USING FPGA, EYE MONITOR, AND SIMULATIONS," the contents of which are incorporated by reference in their entireties.

BACKGROUND

This disclosure relates generally to improving data recovery in signal communication and, more particularly, to extracting and decomposing jitter and noise in received n-level Pulse Amplitude Modulation (PAM-n) signals (where n is greater than 1).

This section is intended to introduce the reader to various aspects of art that may be related to various aspects of the present disclosure, which are described and/or claimed below. This discussion is believed to be helpful in providing the reader with background information to facilitate a better understanding of the various aspects of the present disclosure. Accordingly, it may be understood that these statements are to be read in this light, and not as admissions of prior art.

Accurately communicating data using high-speed input/output (HSIO) signals is of increasing interest and value to electronic system designers and users. As high-speed input/output data rates exceed 50 gigabits per second (Gbps), n-level Pulse Amplitude Modulation (PAM-n) modulation schemes may be used so that high-speed input/output communication links may more efficiently communicate data with high performance. Pulse Amplitude Modulation (PAM) is a form of signal modulation that communicates data by encoding the data in the amplitude of a series of signal pulses. The amplitude of the series of signal pulses may be varied according to the sample value of the data. PAM-n refers to the number of possible pulse amplitudes in the PAM signal. For example, a PAM-4 signal indicates that there are 4 possible discrete pulse amplitudes.

A communication link used with a PAM-n modulation scheme may scale in an electrical or optical signal amplitude domain while preserving a timing budget. For example, a PAM-4 signal may encode up to two times the information a typical PAM-2 signal may encode while the timing budget for the PAM-4 signal may be approximately the same as the PAM-2 signal. Additionally, the bandwidth of the communication link may be reserved such that cost of a communication system may be maintained or reduced. That is, the additional pulse amplitudes used to encode information in a PAM-n signal may enable a reduction in bandwidth of the corresponding communication link while still maintaining the same data rate, resulting in maintaining or even reducing costs of the communication system.

However, increasing the data rate in the communication system could add jitter and noise to the communication link. Extracting and decomposing jitter and noise components from a signal received over the communication link may thus improve the received signal. While decomposing jitter and noise of a received signal is known for single data level or symbol signals, such decomposition has not been per-

formed on signals of PAM-n modulation schemes, which may be much more complex since jitter and noise are level dependent.

SUMMARY

A summary of certain embodiments disclosed herein is set forth below. It should be understood that these aspects are presented merely to provide the reader with a brief summary of these certain embodiments and that these aspects are not intended to limit the scope of this disclosure. Indeed, this disclosure may encompass a variety of aspects that may not be set forth below.

The present disclosure includes systems and methods for improving data recovery in signal communication and, more particularly, to extracting and decomposing jitter and noise in received n-level Pulse Amplitude Modulated (PAM-n) signals (where n is greater than 1). By extracting and decomposing jitter and noise components from a PAM-n signal transmitted and received over a communication link, PAM-n communication performance may be improved by adjusting the communication link to compensate for the jitter and noise components. Moreover, jitter and/or noise as a result of transmitter pre-emphasis may be identified and/or recognized.

Accordingly, systems and methods are described that include receiving an n-level Pulse Amplitude Modulated (PAM-n) signal at a receiver from a transmitter via a communication link. Effects of a finite impulse response applied by the transmitter may be de-embedded from the received PAM-n signal. Sampling times and slicing levels of the PAM-n signal may then be determined. The determination of the sampling times and slicing levels may be iterated using previously determined sampling times and slicing levels to achieve stable values. For each slicing level, jitter may be extracted from the PAM-n signal, and the jitter may be decomposed into one or more jitter components. For each data or symbol level, noise may be extracted from the PAM-n signal, and the noise may be decomposed into one or more noise components. The communication link may then be adjusted based on the one or more jitter components, the one or more noise components, or any combination thereof.

Various refinements of the features noted above may exist in relation to various aspects of the present disclosure. Further features may also be incorporated in these various aspects as well. These refinements and additional features may exist individually or in any combination. For instance, various features discussed below in relation to one or more of the illustrated embodiments may be incorporated into any of the above-described aspects of the present disclosure alone or in any combination. Again, the brief summary presented above is intended only to familiarize the reader with certain aspects and contexts of embodiments of the present disclosure without limitation to the claimed subject matter.

BRIEF DESCRIPTION OF THE DRAWINGS

Various aspects of this disclosure may be better understood upon reading the following detailed description and upon reference to the drawings in which:

FIG. 1 is a block diagram of a system that includes an integrated circuit having jitter/noise extraction/analysis circuitry, in accordance with an embodiment of the present disclosure;

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FIG. 2 is an eye diagram for a PAM-4 signal received at a receiver of the integrated circuit of FIG. 1, in accordance with an embodiment of the present disclosure;

FIG. 3 is a flow diagram of a method for extracting and analyzing jitter and noise of a PAM-n signal received at the receiver of FIG. 1, in accordance with an embodiment of the present disclosure;

FIG. 4 is a set of plots that shows a PAM-n signal that was transmitted using a finite impulse response (FIR) filter and a subsequent PAM-n signal after de-embedding the effect of the FIR filter, in accordance with an embodiment of the present disclosure;

FIG. 5 is a flow diagram that shows a process for determining sampling times of the PAM-4 signal of FIG. 2, in accordance with an embodiment of the present disclosure;

FIG. 6 is a flow diagram that shows a process for determining slicing levels of the PAM-4 signal of FIG. 2, in accordance with an embodiment of the present disclosure;

FIG. 7 is a flow diagram that shows a process for performing a jitter decomposition algorithm on the PAM-4 signal of FIG. 2, in accordance with an embodiment of the present disclosure;

FIG. 8 is a flow diagram that shows a process for performing a noise decomposition algorithm on the PAM-4 signal 51 of FIG. 2, in accordance with an embodiment of the present disclosure.

DETAILED DESCRIPTION OF SPECIFIC EMBODIMENTS

One or more specific embodiments will be described below. In an effort to provide a concise description of these embodiments, not all features of an actual implementation are described in the specification. It may be appreciated that in the development of any such actual implementation, as in any engineering or design project, numerous implementation-specific decisions must be made to achieve the developers' specific goals, such as compliance with system-related and business-related constraints, which may vary from one implementation to another. Moreover, it may be appreciated that such a development effort might be complex and time consuming, but would nevertheless be a routine undertaking of design, fabrication, and manufacture for those of ordinary skill having the benefit of this disclosure.

Techniques for improving data recovery in signal communication, and more particularly to extracting and decomposing jitter and noise in received n-level Pulse Amplitude Modulated (PAM-n) signals (where n is greater than 1), are disclosed. By decomposing a PAM-n signal received over a communication link into jitter and noise components, PAM-n communication performance may be improved by adjusting the communication link to compensate for the jitter and noise in the PAM-n signal. Moreover, jitter and noise as a result of transmitter pre-emphasis may be identified and compensated for.

FIG. 1 is a block diagram of a system that includes an integrated circuit (e.g., a field programmable gate array (FPGA) 12) having signal processing circuitry (e.g., jitter/noise extraction/analysis circuitry 14), in accordance with an embodiment of the present disclosure. A transmitter 16 may send a PAM-n signal 18 (where n is greater than 1) via an input/output channel 20. The transmitter 16 may be part of another integrated circuit (e.g., another FPGA). In some embodiments, the transmitter 16 may include a finite impulse response (FIR) filter 21. The transmitter 16 may use the FIR filter 21 to pre-emphasize, amplify, and/or otherwise

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modify the PAM-n signal 18 to improve reception and/or quality of the PAM-n signal 18. In some embodiments, the input/output channel 20 may be a high speed input/output (HSIO) channel.

The FPGA 12 receives the PAM-n signal 18 via a receiver 22. The transmitter 16, channel 20, and receiver 22 may form a high-speed input/output communication link 23. While the FPGA 12 is used as an example of the integrated circuit, it should be understood that any suitable integrated circuit may be substituted for the FPGA 12, such as another type of programmable logic device (PLD), an application specific integrated circuit (ASIC), application specific standard product (ASSP), and the like. The receiver includes an eye monitor 24 that may measure characteristics (e.g., sampling time) of the PAM-n signal 18 and provide information to analysis algorithms (e.g., jitter/noise decomposition algorithms).

The jitter/noise extraction/analysis circuitry or block 14 may include various circuitry used to extract and/or analyze jitter/noise from the PAM-n signal 18. The jitter/noise extraction/analysis circuitry 14 may include a time interval error (TIE)/voltage interval error (VIE) generator 26 may extract jitter and/or noise from the PAM-n signal 18. The jitter/noise extraction/analysis circuitry 14 may include a probability distribution function (PDF) analyzer 27 that uses random probability distribution analysis to determine jitter and/or noise in the PAM-n signal 18. The jitter/noise extraction/analysis circuitry 14 may also include a spectrum analyzer 28 that uses amplitude and frequency of the PAM-n signal 18 to determine jitter and/or noise in the PAM-n signal 18. The jitter/noise extraction/analysis circuitry 14 may include a jitter/noise decomposition circuitry 29 may decompose jitter and/or noise in the PAM-n signal 18 into jitter and/or noise components. For example, the jitter/noise decomposition circuitry or block 29 may use one or more decomposition algorithms to split jitter/noise extracted by the TIE/VIE generator 26 into a jitter/noise probability distribution function analysis and a jitter spectrum analysis. Jitter/noise components may then be determined using the jitter/noise probability distribution function analysis and the jitter/noise spectrum analysis. The jitter/noise extraction/analysis circuitry 14 may include a jitter/noise calibration circuitry or block 30 may verify jitter/noise components from the PAM-n signal 18 and/or calculate adjustments to reduce jitter and/or noise in the PAM-n signal 18. Such adjustments may be sent to the transmitter 16, the channel 20, and/or the receiver 22. The jitter/noise extraction/analysis circuitry 14 may also include a link simulator 32 that generates a model high-speed input/output communication link. In some embodiments, jitter/noise extraction and/or analysis may be performed on the model high-speed input/output communication link.

The system 10 also includes a controller 34 that may communicatively couple to the transmitter 16, the channel 20, and the FPGA 12. The controller 34 may include any suitable control logic that extracts and/or analyzes jitter and/or noise in the PAM-n signal 18. For example, the controller 34 may include or be part of one or more processors 36 (e.g., microprocessors) that may execute software programs (e.g., jitter/noise decomposition software programs) to extract and/or analyze jitter and/or noise in the PAM-n signal 18. Moreover, the processor(s) 36 may include one or more microprocessors, one or more integrated circuits (e.g., application specific integrated circuits (ASICs), field programmable gate arrays (FPGAs), reduced instruction set (RISC) processors, and the like), or some combination thereof. The controller 34 may couple to one or

more memory devices **38** that may store information such as control software look up tables, configuration data, etc. In some embodiments, the processor(s) **36** and/or the memory device(s) **38** may be external to the controller **34**. The memory device(s) **38** may include a tangible, non-transitory, machine-readable-medium, such as a volatile memory (e.g., a random access memory (RAM)) and/or a nonvolatile memory (e.g., a read-only memory (ROM)). The memory device(s) **38** may store a variety of information and be used for various purposes. For example, the memory device(s) **38** may store machine-readable and/or processor-executable instructions (e.g., firmware or software) for the processor(s) **36** to execute, such as instructions to extract and/or analyze jitter and/or noise in the PAM-n signal **18**. The memory device(s) **38** may include one or more storage devices (e.g., nonvolatile storage devices) that may include read-only memory (ROM), flash memory, a hard drive, or any other suitable optical, magnetic, or solid-state storage medium, or any combination thereof.

While the components (e.g., the TIE/VIE generator **26**, the jitter/noise decomposition circuitry **29**, the jitter/noise calibration circuitry **30**, and the link simulator **32**) of the jitter/noise extraction/analysis circuitry **14** are illustrated as part of the jitter/noise extraction/analysis circuitry **14**, it should be understood that any or all of the components may instead be disposed outside the jitter/noise extraction/analysis circuitry **14** or outside the FPGA **12** (e.g., in the controller **34**).

FIG. **2** is an eye diagram **50** for a PAM-4 signal **51** received at the receiver **22** of FIG. **1**, in accordance with an embodiment of the present disclosure. While a PAM-4 signal is illustrated and used as an example in the present disclosure, it should be understood that techniques of the present disclosure may apply to any number of levels or symbols of PAM signals (e.g., PAM-2, PAM-8, PAM-16, and the like). Furthermore, while the PAM-4 signal **51** may be referred to and/or described as an electrical signal, it should be understood that the present disclosure may also apply to other signals, such as optical signals. As illustrated, the horizontal axis of the eye diagram **50** represented time (in picoseconds) and the vertical axis represents amplitude (in millivolts).

For the PAM-4 signal **51**, the eye diagram **50** includes four data levels or symbols p **52** (i.e., where p ranges from 1 to n , where $n=4$) that may correspond to four values. The controller **34** may analyze the eye diagram **50** and determine data slicing or slicer levels m **54** (i.e., data slicing levels **1-3**) that facilitate determining what data level **52** a portion of the PAM-4 signal **51** indicates. For example, if a portion of the PAM-4 signal **51** is between data slicing level **1** and data slicing level **2**, the controller **34** may determine that the portion of the PAM-4 signal **51** indicates data level **2**. The controller **34** may also determine sampling times **56** (i.e., T_m) such that sampling the PAM-4 signal **51** at the sampling times **56** may yield more accurate results.

The eye diagram **50** may be used to extract jitter and/or noise from the PAM-4 signal **51**. As illustrated, a noise histogram **58** shows the noise in the PAM-4 signal **51**. Specifically, the noise histogram **58** identifies four sources of noise in the PAM-4 signal **51**. Each source of noise may be composed of multiple noise components **59**, such as data-dependent noise (i.e., $DDN<n, p>$), periodic noise/sinusoidal noise (i.e., $PN/SN<n, p>$), bounded uncorrelated noise (i.e., $BUN<n, p>$), random noise (i.e., $RN<n, p>$), and the like.

Similarly, a jitter histogram **62** shows the jitter in the PAM-4 signal **51**. Specifically, the jitter histogram **62** iden-

tifies three sources of jitter in the PAM-4 signal **51**. Each source of jitter may be composed of multiple jitter components **63**, such as data-dependent jitter (i.e., $DDJ<n, m>$), periodic jitter/sinusoidal jitter (i.e., $PJ/SJ<n, m>$), bounded uncorrelated jitter (i.e., $BUJ<n, m>$), random jitter (i.e., $RJ<n, m>$), and the like. By extracting and decomposing the jitter and/or noise in the PAM-n signal **18**, the PAM-n communication link **23** may be more accurately characterized and/or improved.

FIG. **3** is a flow diagram of a method **70** for extracting and analyzing jitter and noise of the PAM-n signal **18** of FIG. **1**, in accordance with an embodiment of the present disclosure. The method **70** may be performed by any suitable device that may extract and analyze jitter and noise of the PAM-n signal **18**, such as the controller **34**. While the method **70** is described using steps in a specific sequence, it should be understood that the present disclosure contemplates that the describe steps may be performed in different sequences than the sequence illustrated, and certain described steps may be skipped or not performed altogether. In some embodiments, the method **70** may be implemented by executing instructions stored in a tangible, non-transitory, computer-readable medium, such as the memory device(s) **38**, using a processor, such as the processor(s) **36**.

Referring now to the method **70**, the controller **34** may receive (process block **72**) the PAM-n signal **18** via the communication link **23**. As illustrated in FIG. **1**, the controller **34** may receive the PAM-n signal **18** via the receiver **22**. In some embodiments, the controller **34** may receive an eye monitor measurement of the PAM-signal (e.g., via the eye monitor **24**). In other embodiments, the link simulator **32** may generate a model of the high-speed input/output communication link **23**. As such, the controller **34** may receive the PAM-n signal **18** via the link simulator **32**.

In some embodiments, the controller **34** may optionally de-embed an effect of the FIR filter **21** when the transmitter **16** uses the FIR filter **21** on the PAM-n signal **18**. As such, the controller **34** may determine (decision block **74**) whether the transmitter **16** applied the FIR filter **21** to the PAM-n signal **18**. If so, the controller **34** may de-embed (process block **76**) the effect of the FIR filter **21** on the PAM-n signal **18**. That is, prior to sending the PAM-n signal **18**, the transmitter **16** may use the FIR filter **21** to pre-emphasize, amplify, and/or otherwise modify the PAM-n signal **18** to improve reception and/or quality of the PAM-n signal **18**. The controller **34**, upon reception of the PAM-n signal **18**, may de-embed the effect of the FIR filter **21** from the PAM-n signal **18** to realize more true or accurate characteristics of the transmitter **16** (e.g., to remove jitter and/or noise that is a result of applying the FIR filter **21**). For example, FIG. **4** is a set of plots that show a PAM-n signal **78** that was transmitted using the FIR filter **21** and the subsequent PAM-n signal **80** after the controller **34** de-embedded the effect of the FIR filter **21**, in accordance with an embodiment of the present disclosure. In this manner, jitter and/or noise caused by the transmitter **16** may be extracted and analyzed.

In some circumstances, such as when the transmitter **16** does not use the FIR filter **21** on the PAM-signal **18**, the controller **34** may determine that an effect of the FIR filter **21** on the PAM-n signal **18** should not be de-embedded. As such, the controller **34** may skip process block **76**.

The controller **34** determines (process block **82**) one or more sampling times **56** of the PAM-n signal **18**. FIG. **5** is a flow diagram that shows a process for determining the sampling times **56** of the PAM-4 signal **51** of FIG. **2**, in accordance with an embodiment of the present disclosure. As illustrated, the controller **34** may perform a clock and

data recovery procedure (CDR) **84** on the PAM-4 signal **51**. Then, for each slicing level **m** **54**, the controller **34** may perform a maximum setup/hold time operation and/or a maximum signal to distortion/noise ratio (SNDR) operation **86** to determine one or more sampling times (i.e., $T_{<n, m>}$) **56**. In some embodiments, each sampling time for each slicing level **m** **54** may be different.

The controller **34** then determines (process block **88**) one or more slicing levels **54** of the PAM-n signal **18**. FIG. **6** is a flow diagram that shows a process for determining the slicing levels **54** of the PAM-4 signal **51** of FIG. **2**, in accordance with an embodiment of the present disclosure. As illustrated, for each data level **52** or slicing level **54** of the received PAM-4 signal **51**, the controller **34** may perform a peak detection operation, a mean operation, a median operation, and/or a maximum SNDR operation **90**, to determine the data slicing levels **54**.

In some embodiments, the controller **34** may iterate through process blocks **82** and **88** numerous times until the sampling times **56** (i.e., $T_{<n, m>}$) and/or the slicing levels **54** become stable (e.g., such that the sampling times **56** and/or the slicing levels **54** are approximately the same values in subsequent iterations). As such, the controller **34** may determine (decision block **92**) whether the sampling times **56** and the slicing levels **54** are stable. If not, the controller **34** may return to process block **82**. For example, the controller **34** may determine (process block **82**) first sampling times **56** (e.g., $T_{1<n, m>}$) by starting with initial or default slicing levels **54** (e.g., $S_{0<n, m>}$). Then, the controller **34** may determine (process block **88**) first slicing levels **54** (e.g., $S_{1<n, m>}$) by using the first sampling times **56** (i.e., $T_{1<n, m>}$). In the next iteration, the controller **34** may determine (process block **82**) second sampling times **56** (e.g., $T_{2<n, m>}$) using the first slicing levels **54** (e.g., $S_{1<n, m>}$). The controller **34** may then determine (process block **88**) second slicing levels **54** (e.g., $S_{2<n, m>}$) by using the second sampling times **56** (i.e., $T_{2<n, m>}$), and so on.

If the controller **34** determines (decision block **92**) that the sampling times **56** and the slicing levels **54** are stable, the controller **34** may extract and decompose (process block **94**) jitter in the PAM-n signal **18** for each slicing level **54** to determine one or more jitter components **63**. Specifically, the controller **34** may perform one or more jitter decomposition algorithms for each slicing level **54**. The jitter decomposition algorithms may include any decomposition algorithm that decomposes jitter in the PAM-n signal **18** into jitter components **63**. FIG. **7** is a flow diagram that shows a process for performing a jitter decomposition algorithm on the PAM-4 signal **51** of FIG. **2**, in accordance with an embodiment of the present disclosure. As illustrated, the controller **34** may, for each slicing level **54**, perform a time interval error (TIE) extraction **100** to extract jitter from the PAM-4 signal **51**. The controller **34** may perform a jitter probability distribution function (PDF) analysis **102** (e.g., using the PDF analyzer **27**) and a jitter spectrum analysis **104** (e.g., using the spectrum analyzer **28**) on the extracted jitter for each slicing level **54** to determine the one or more jitter components **63**, such as, for each slicing level **m**: data-dependent jitter (DDJ $<n, m>$), periodic/sinusoidal jitter (PJ/SJ $<n, m>$), bounded uncorrelated jitter (BUJ $<n, m>$), random jitter (RJ $<n, m>$), and the like.

The controller **34** may extract and decompose (process block **106**) noise in the PAM-n signal to determine one or more noise components **59**. Specifically, the controller **34** may perform one or more noise decomposition algorithms for each data level **52**. The noise decomposition algorithms may include any decomposition algorithm that decomposes

noise in the PAM-n signal **18** into noise components **59**. FIG. **8** is a flow diagram that shows a process for performing a noise decomposition algorithm on the PAM-4 signal **51** of FIG. **2**, in accordance with an embodiment of the present disclosure. As illustrated, the controller **34** may, for each data level **52**, perform a voltage interval error (VIE) extraction **110** to extract noise from the PAM-4 signal **51**. The controller **34** may perform a noise probability distribution function (PDF) analysis **112** (e.g., using the PDF analyzer **27**) and a noise spectrum analysis **114** (e.g., using the spectrum analyzer **28**) on the extracted noise for each data level **52** to determine the one or more noise components **59**, such as, for each data level **p**: data-dependent noise (i.e., DDN $<n, p>$), periodic noise/sinusoidal noise (i.e., PN/SN $<n, p>$), bounded uncorrelated noise (i.e., BUN $<n, p>$), random noise (i.e., RN $<n, p>$), and the like.

In some embodiments, the controller **34** may de-embed the effect of the FIR filter **21** as described in process block **76** to further extract and decompose jitter and noise at a later part of the communication link **23**. As an example, if the controller **34** determines that the FIR filter **21** generates 0.1 picoseconds (ps) of bounded uncorrelated jitter (i.e., BUJ $<n, m>$) and the controller **34** determines that there is 0.8 ps of BUJ at the receiver **22**, the controller **34** may determine that the channel **20** and the receiver **22** contribute approximately 0.7 ps of BUJ to the communication link **23**. As such, de-embedding the effect of the FIR filter **21** may be used, not just to remove the effect of the FIR filter **21**, but also to more accurately determine contribution of jitter and/or noise by other components of the communication link **23**. In this manner, the method **70** for extracting and analyzing jitter and noise of the PAM-n signal **18** may enable developers to improve design of the communication link **23**.

The controller **34** may then adjust (process block **116**) or send an instruction to adjust the communication link **23** based on the one or more jitter components **63** and/or the one or more noise components **59**. In some embodiments, the controller **34** may generate a model of the communication link **23** based on the PAM-n signal **18**, the transmitter **16**, the channel **20**, the receiver **22**, or any combination thereof. The controller **34** may then calibrate the model of the communication link **23** based on the one or more jitter components **63** and/or the one or more noise components **59**. The model of the communication link **23** may then be used to determine which portions of the communication link **23** (e.g., the transmitter **16**, the channel **20**, the receiver **22**, or any combination thereof) to adjust based on the one or more jitter components **63** and/or the one or more noise components **59**. For example, adjusting the communication link **23** may include moving components (e.g., in the system **10**, a model of the system **10**, and the like) related to jitter and/or noise, adjusting connections related to jitter and/or noise, replacing components related to jitter and/or noise, and the like, based on the one or more jitter components **63** and/or the one or more noise components **59**.

Techniques for improving data recovery in signal communication, and more particularly to extracting and decomposing jitter and noise in received n-level Pulse Amplitude Modulated (PAM-n) signals, are disclosed. By decomposing a PAM-n signal received over a communication link into jitter and noise components, PAM-n communication performance may be improved by adjusting the communication link to compensate for the jitter and noise in the PAM-n signal. Moreover, jitter and/or noise as a result of transmitter pre-emphasis may be identified and compensated for.

While the embodiments set forth in the present disclosure may be susceptible to various modifications and alternative

forms, specific embodiments have been shown by way of example in the drawings and have been described in detail herein. However, it may be understood that the disclosure is not intended to be limited to the particular forms disclosed. The disclosure is to cover all modifications, equivalents, and alternatives falling within the spirit and scope of the disclosure as defined by the following appended claims.

The techniques presented and claimed herein are referenced and applied to material objects and concrete examples of a practical nature that demonstrably improve the present technical field and, as such, are not abstract, intangible or purely theoretical. Further, if any claims appended to the end of this specification contain one or more elements designated as “means for [perform]ing [a function] . . .” or “step for [perform]ing [a function] . . .”, it is intended that such elements are to be interpreted under 35 U.S.C. 112(f). However, for any claims containing elements designated in any other manner, it is intended that such elements are not to be interpreted under 35 U.S.C. 112(f).

What is claimed is:

1. A programmable logic device that analyzes a signal, wherein the programmable logic device comprises:

a receiver that is configured to receive the signal, wherein the signal comprises a plurality of discrete pulse amplitudes; and

analysis circuitry communicatively coupled to the receiver, wherein the analysis circuitry is configured to: extract first jitter in a first discrete pulse amplitude of the plurality of discrete pulse amplitudes of the signal and decompose the first jitter into a first set of jitter components, and extract second jitter in a second discrete pulse amplitude of the plurality of discrete pulse amplitudes of the signal and decompose the second jitter into a second set of jitter components; or

extract first noise in the first discrete pulse amplitude of the signal and decompose the first noise into a first set of noise components, and extract second noise in the second discrete pulse amplitude of the signal and decompose the second jitter into a second set of jitter components.

2. The programmable logic device of claim 1, comprising a field programmable gate array.

3. The programmable logic device of claim 1, wherein the signal comprises four discrete pulse amplitudes.

4. The programmable logic device of claim 1, wherein each discrete pulse amplitude of the plurality of discrete pulse amplitudes encodes data sent by a transmitter.

5. A controller that analyzes a signal sent by a transmitter and received at a receiver via a channel, wherein the signal comprises a plurality of discrete pulse amplitudes, wherein the controller is configured to:

determine one or more slicing levels of the signal; extract jitter or noise in the signal for each slicing level of the signal; and

send one or more instructions to adjust the receiver, the transmitter, the channel, or any combination thereof, based at least in part on the jitter or the noise.

6. The controller of claim 5, wherein the controller is configured to decompose the jitter for each slicing level of the signal into one or more jitter components.

7. The controller of claim 6, wherein the controller is configured to send the one or more instructions to adjust the receiver, the transmitter, the channel, or any combination thereof, based at least in part on the one or more jitter components.

8. The controller of claim 5, wherein the controller is configured to decompose the noise for each slicing level of the signal into one or more noise components.

9. The controller of claim 8, wherein the controller is configured to send the one or more instructions to adjust the receiver, the transmitter, the channel, or any combination thereof, based at least in part on the one or more noise components.

10. The controller of claim 5, wherein the controller is configured to:

receive an eye monitor measurement of the signal; determine one or more slicing levels of the eye monitor measurement; and

extract jitter or noise in the eye monitor measurement for each slicing level of the eye monitor measurement.

11. The controller of claim 6, wherein the controller is configured to receive the signal from a link simulator, wherein the link simulator is configured to generate a model of the receiver, the transmitter, the channel, or any combination thereof.

12. The controller of claim 6, wherein the controller is configured to determine one or more sampling times for each slicing level of the signal.

13. The controller of claim 12, wherein the controller is configured to determine the one or more sampling times for each slicing level of the signal by:

performing a clock and data recovery procedure on the signal; and

for each slicing level of the signal, performing a maximum setup or hold time operation.

14. The controller of claim 12, wherein the controller is configured to determine the one or more sampling times for each slicing level of the signal by:

performing a clock and data recovery procedure on the signal; and

for each slicing level of the signal, performing a maximum signal to distortion/noise ratio operation.

15. The controller of claim 12, wherein each sampling time for each slicing level of the signal is different.

16. One or more tangible, non-transitory, machine-readable media comprising instructions that analyze a signal, wherein the instructions are configured to cause a processor to:

determine one or more slicing levels of the signal; decompose jitter or noise in the signal into jitter components or noise components for each slicing level of the signal; and

send one or more instructions to adjust a receiver, a transmitter, a channel, or any combination thereof, based at least in part on the jitter components or the noise components.

17. The one or more tangible, non-transitory, machine-readable media of claim 16, wherein the instructions are configured to cause the processor to decompose the jitter and the noise in the signal into the jitter components and the noise components for each slicing level of the signal.

18. The one or more tangible, non-transitory, machine-readable media of claim 17, wherein the instructions are configured to cause the processor to send the one or more instructions to adjust the receiver, the transmitter, the channel, or any combination thereof, based at least in part on the jitter components and the noise components.