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**Ta et al.**

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(54) **THIN-WALLED SCAFFOLDS HAVING FLEXIBLE DISTAL END**

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**A61F 2/89** (2013.01)  
**A61F 2/958** (2013.01)

(52) **U.S. Cl.**

CPC ..... **A61F 2/89** (2013.01); **A61F 2/958** (2013.01); **A61F 2230/006** (2013.01); **A61F 2230/0056** (2013.01); **A61F 2230/0069** (2013.01); **A61F 2250/0003** (2013.01); **A61F 2250/0097** (2013.01)

(58) **Field of Classification Search**

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USPC ..... **623/1.34-1.48**  
See application file for complete search history.

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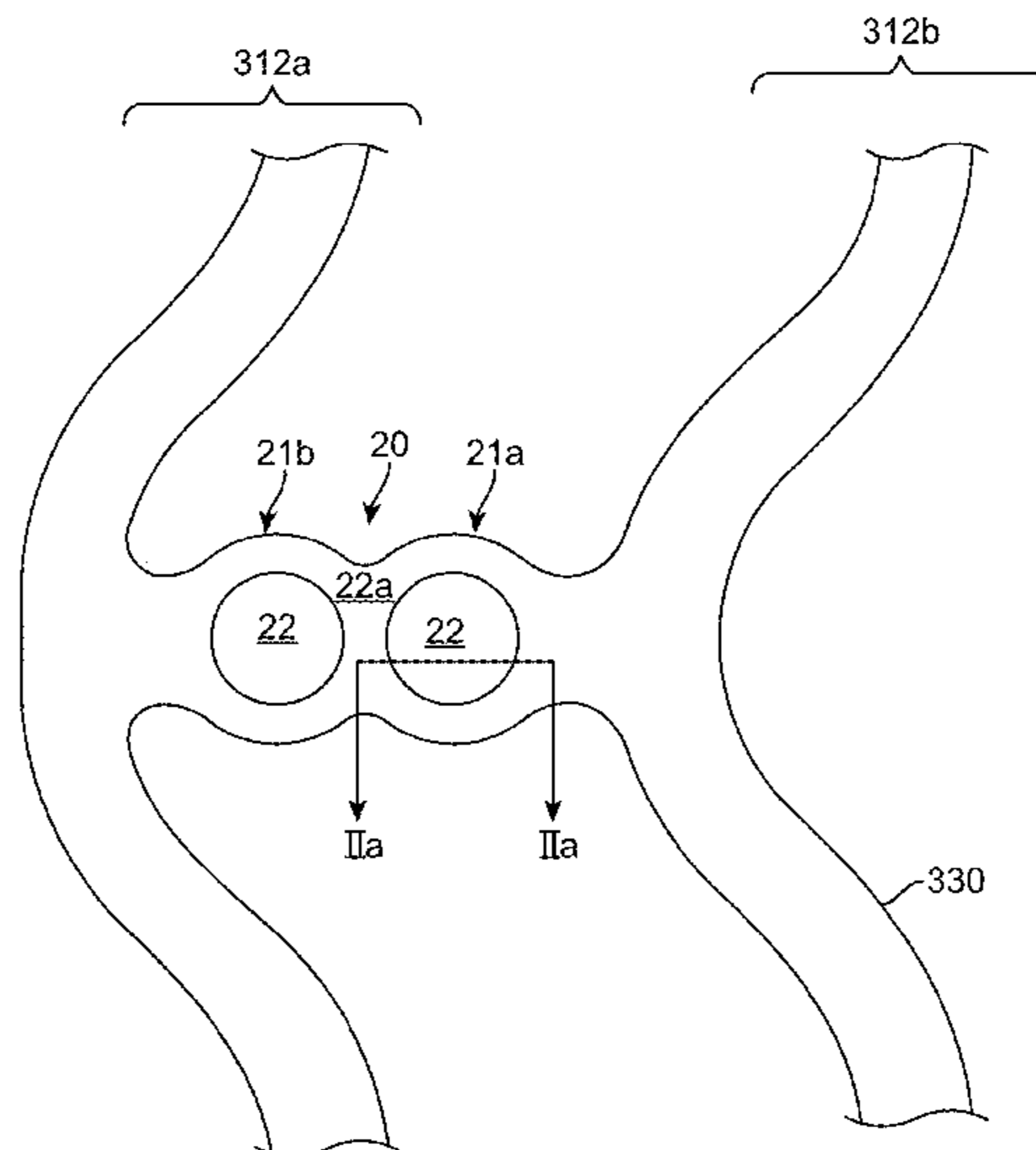
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(57) **ABSTRACT**

A thin-walled scaffold includes a radiopaque marker connected to a link. In a first example, the marker is retained on the strut by a head at one or both ends by swaging. In a second example of a thin-walled scaffold the link is modified to avoid interference during crimping. In a third example a distal end of the thin-walled scaffold is modified to improve deliverability of the thin-walled scaffold. These features are combined in a fourth example.

**19 Claims, 28 Drawing Sheets**



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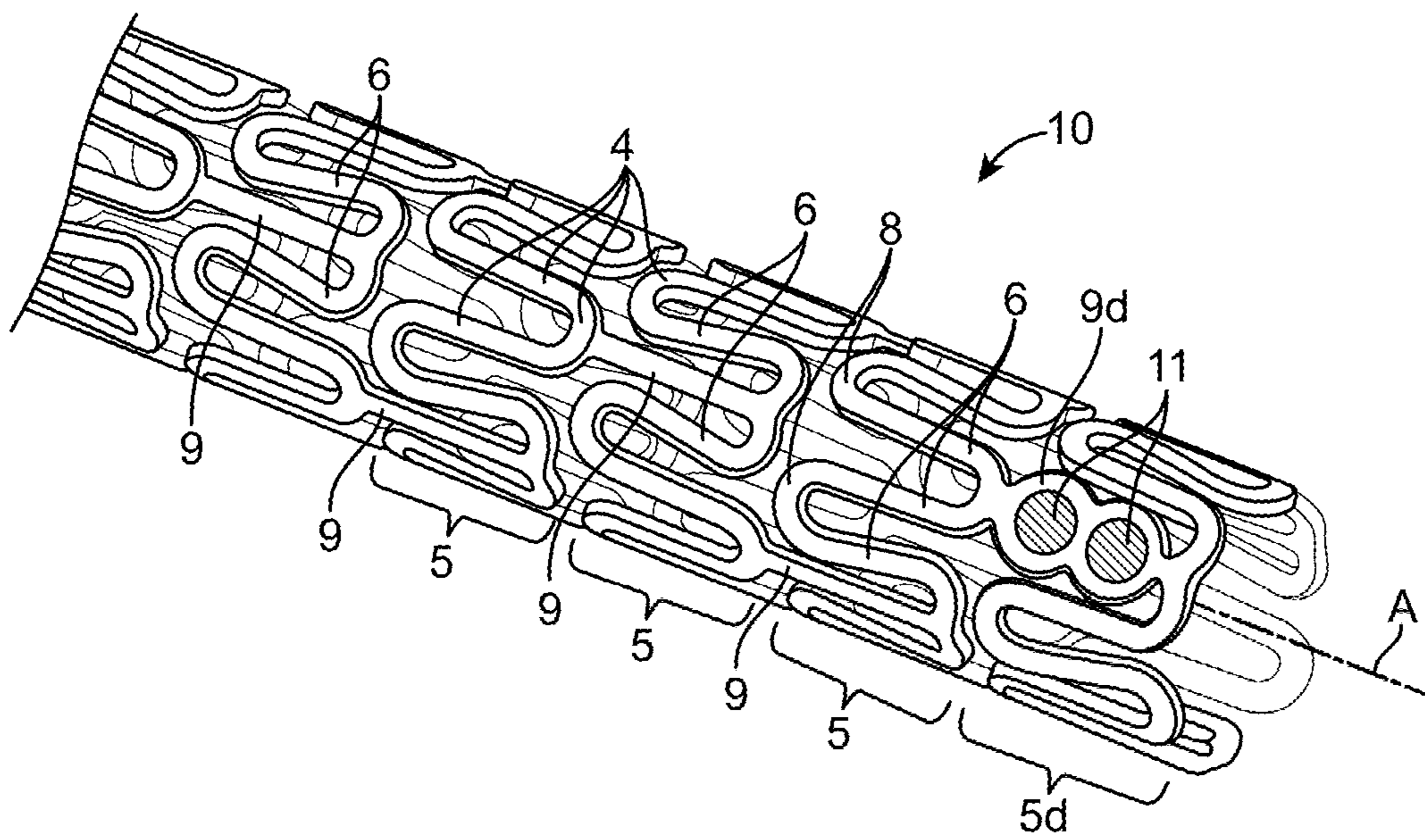


FIG. 1  
(PRIOR ART)

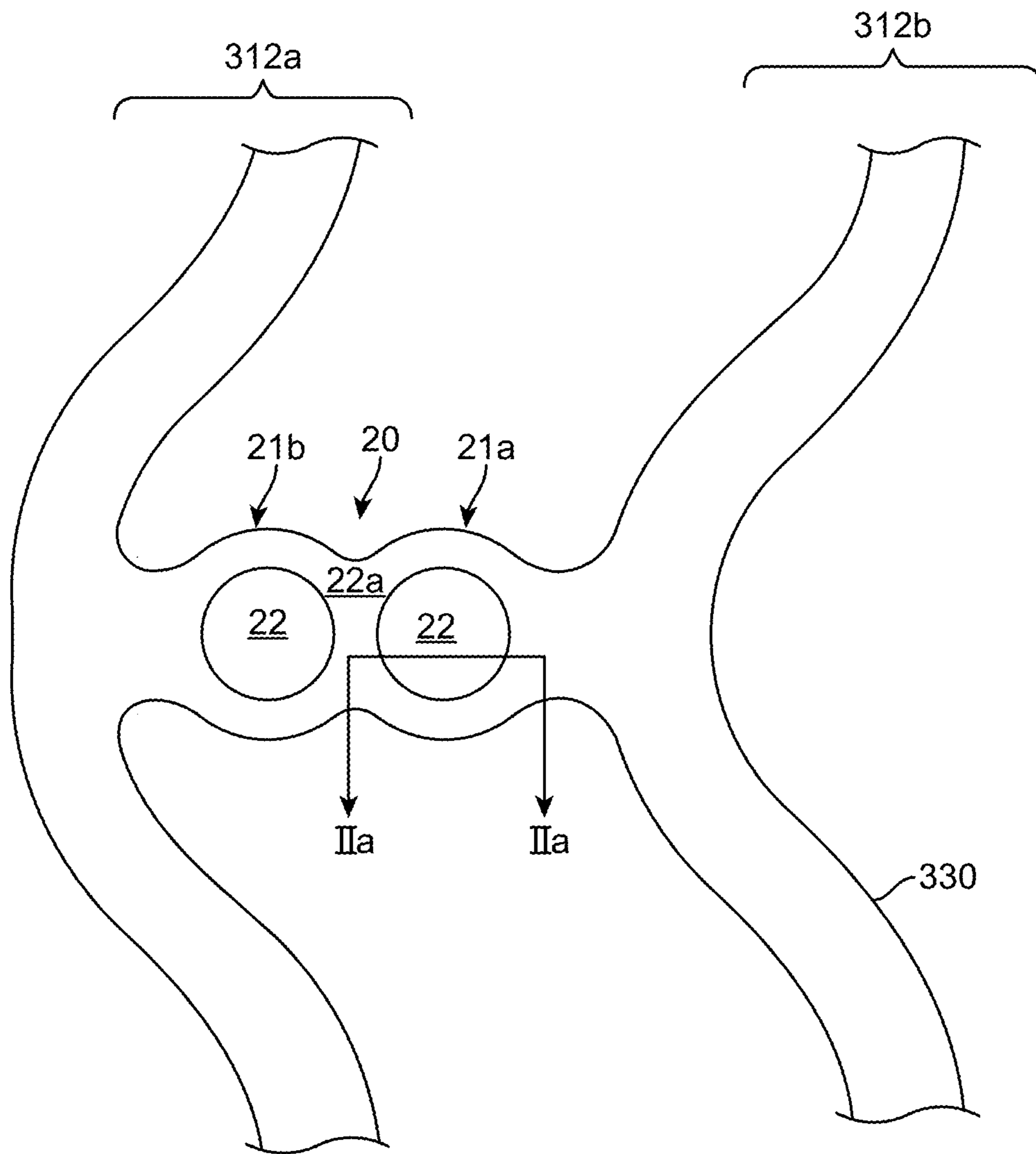


FIG. 2

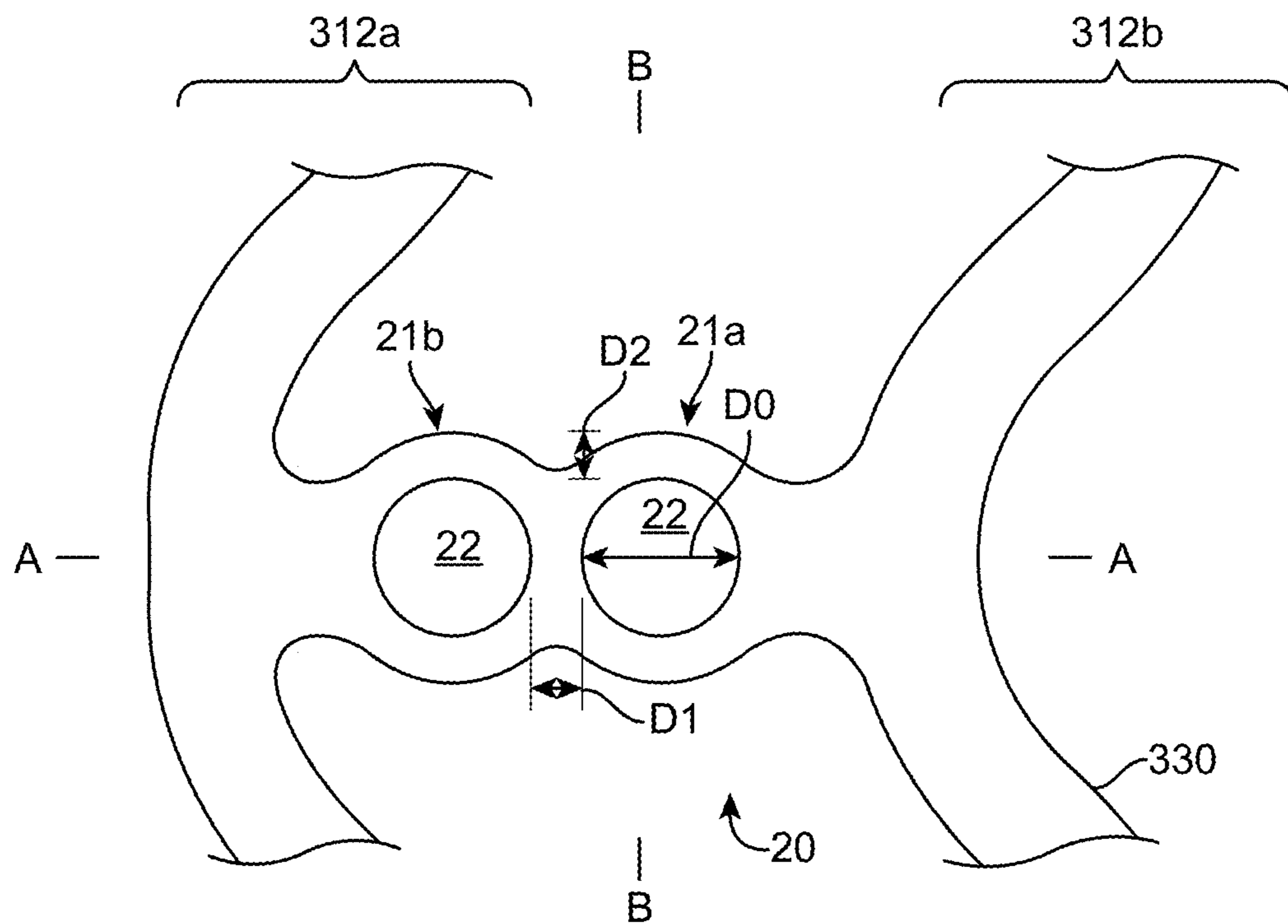


FIG. 2A

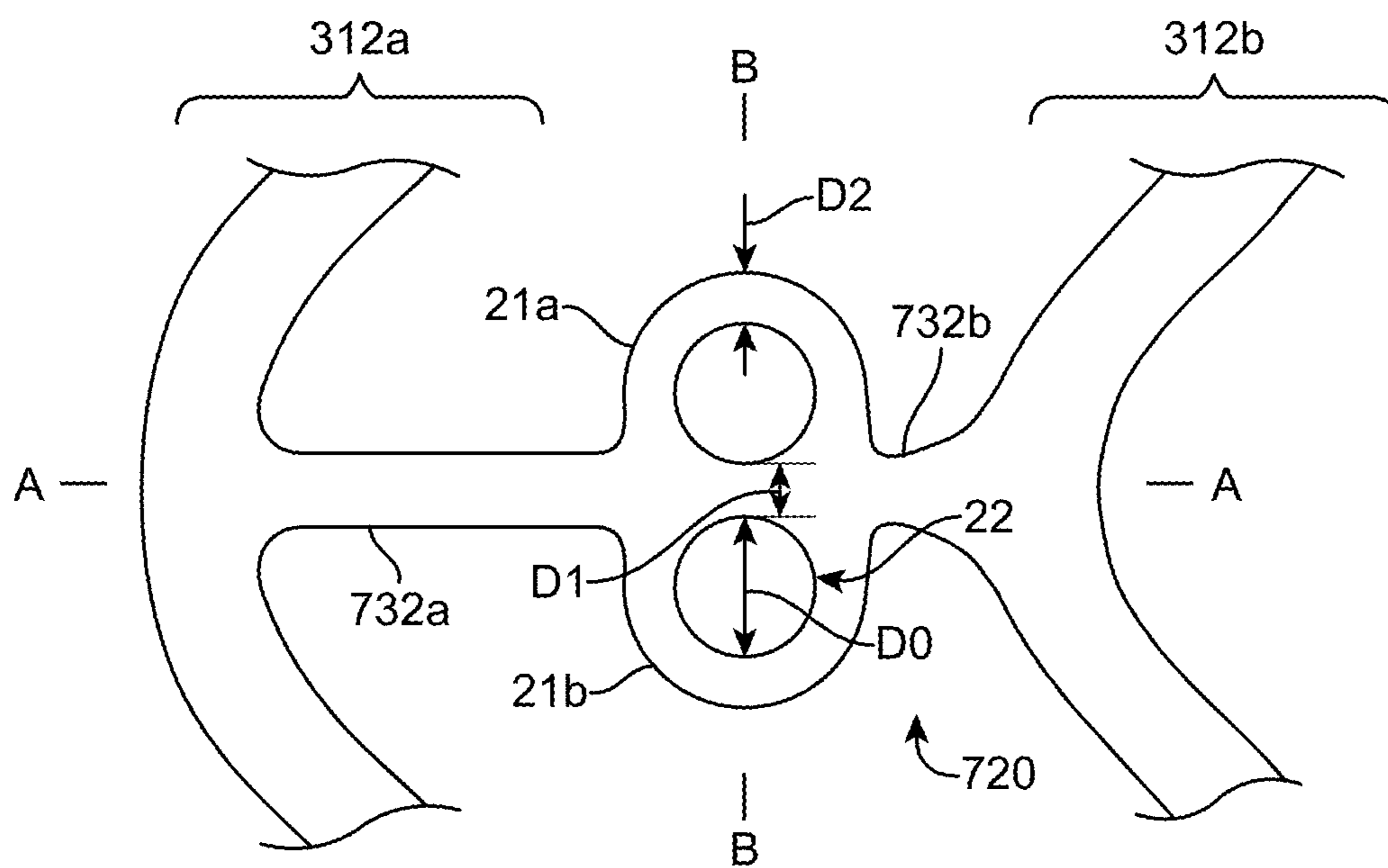


FIG. 2B

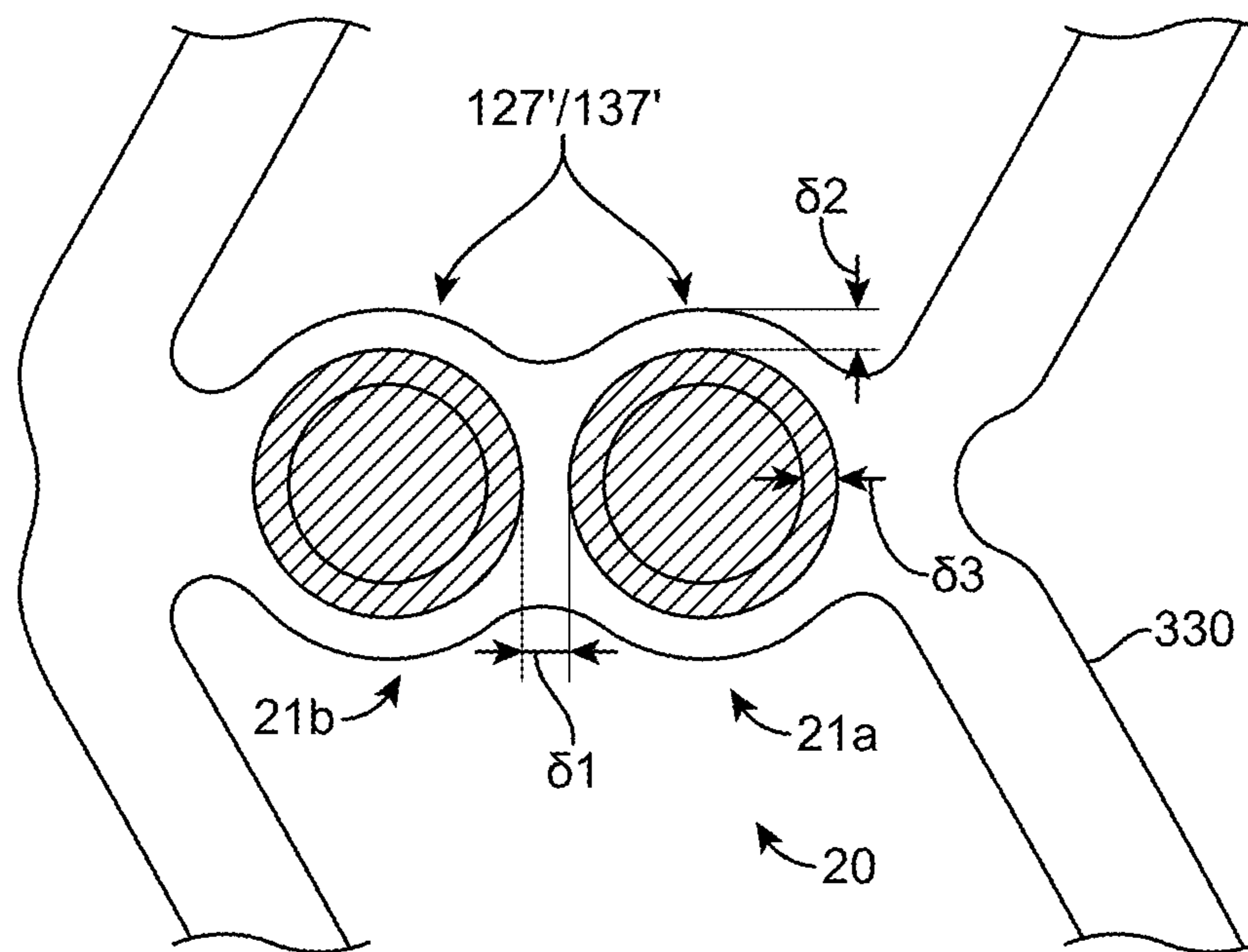


FIG. 2C

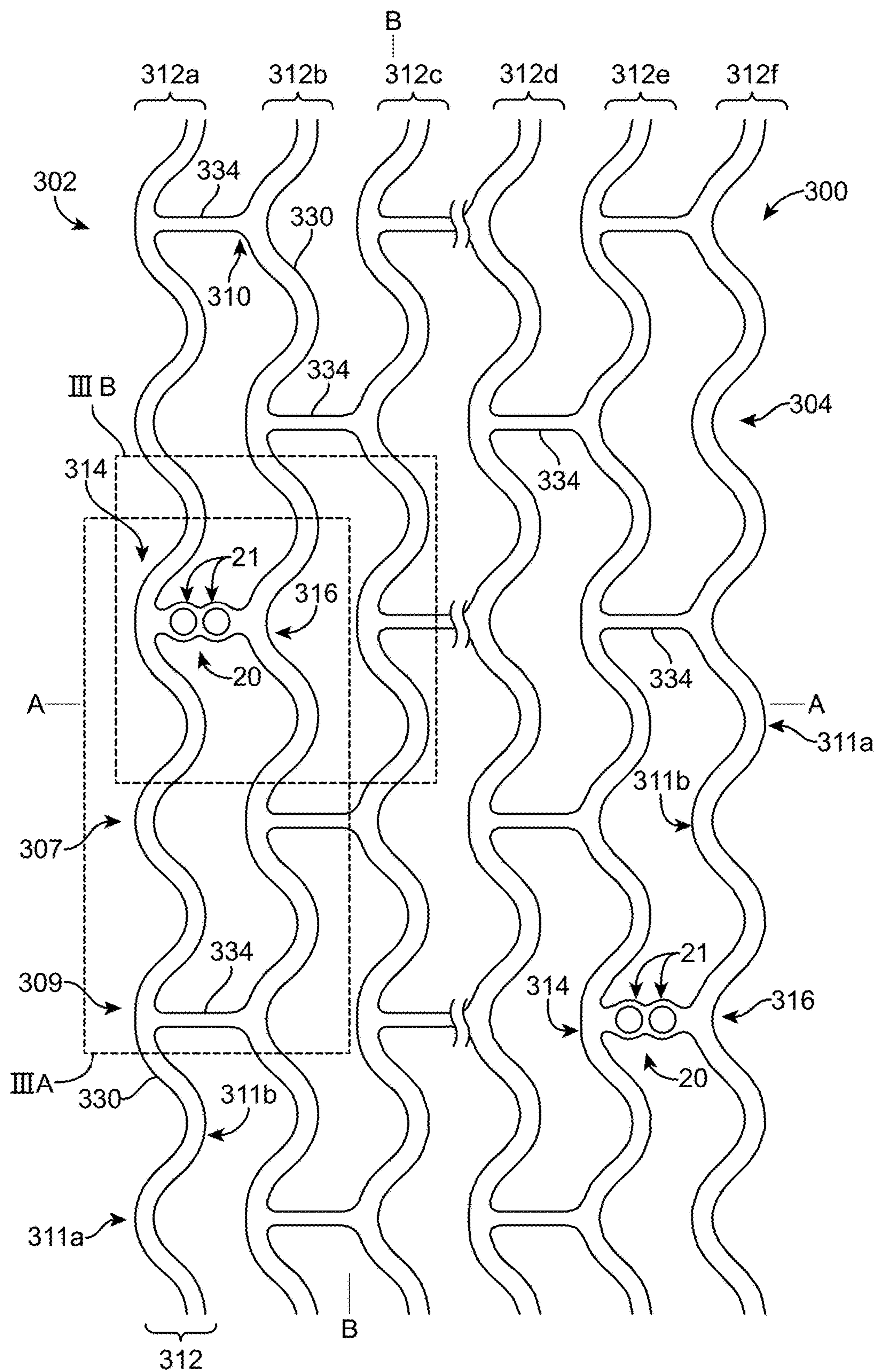


FIG. 3

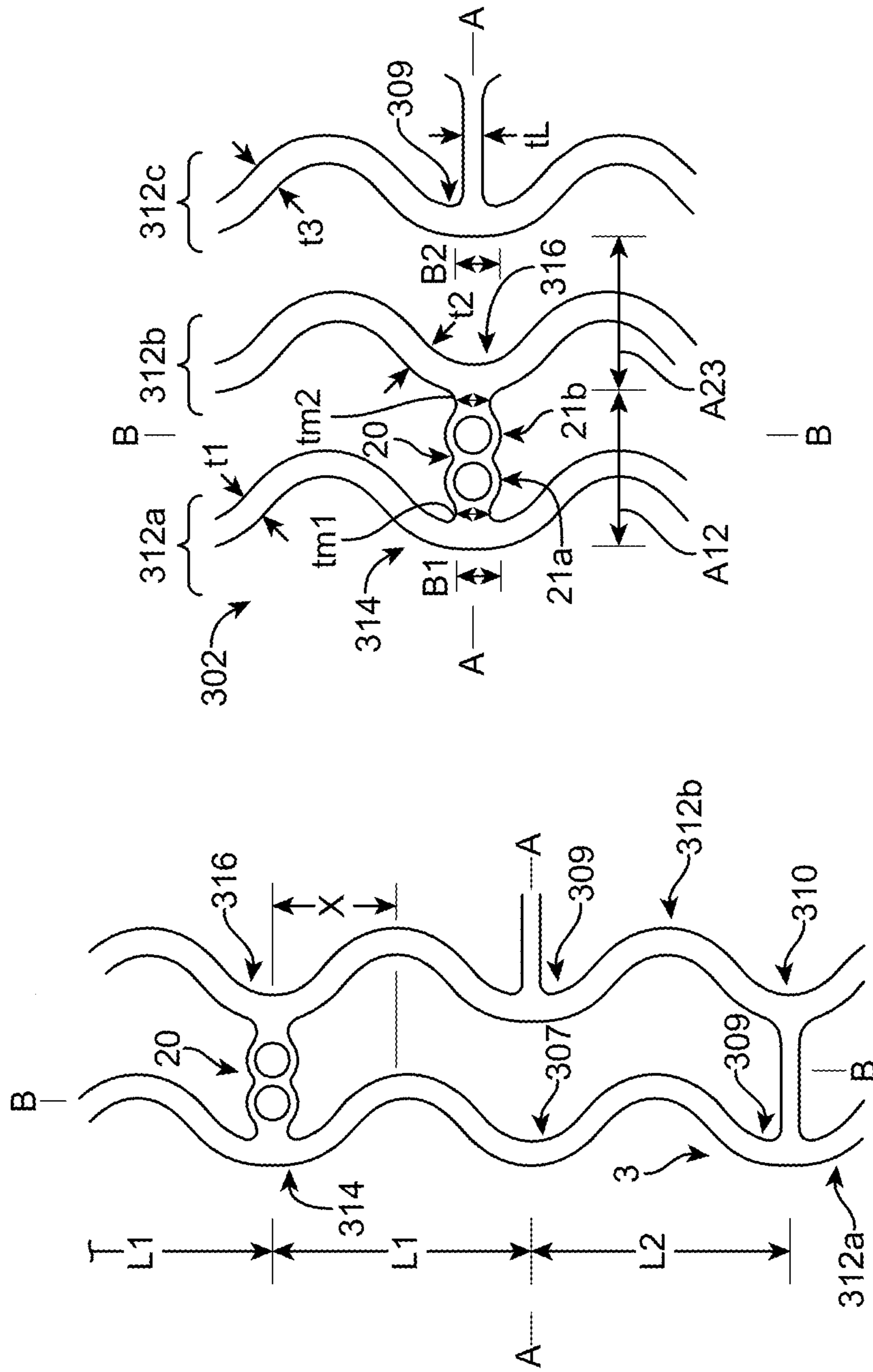


FIG. 3B

FIG. 3A



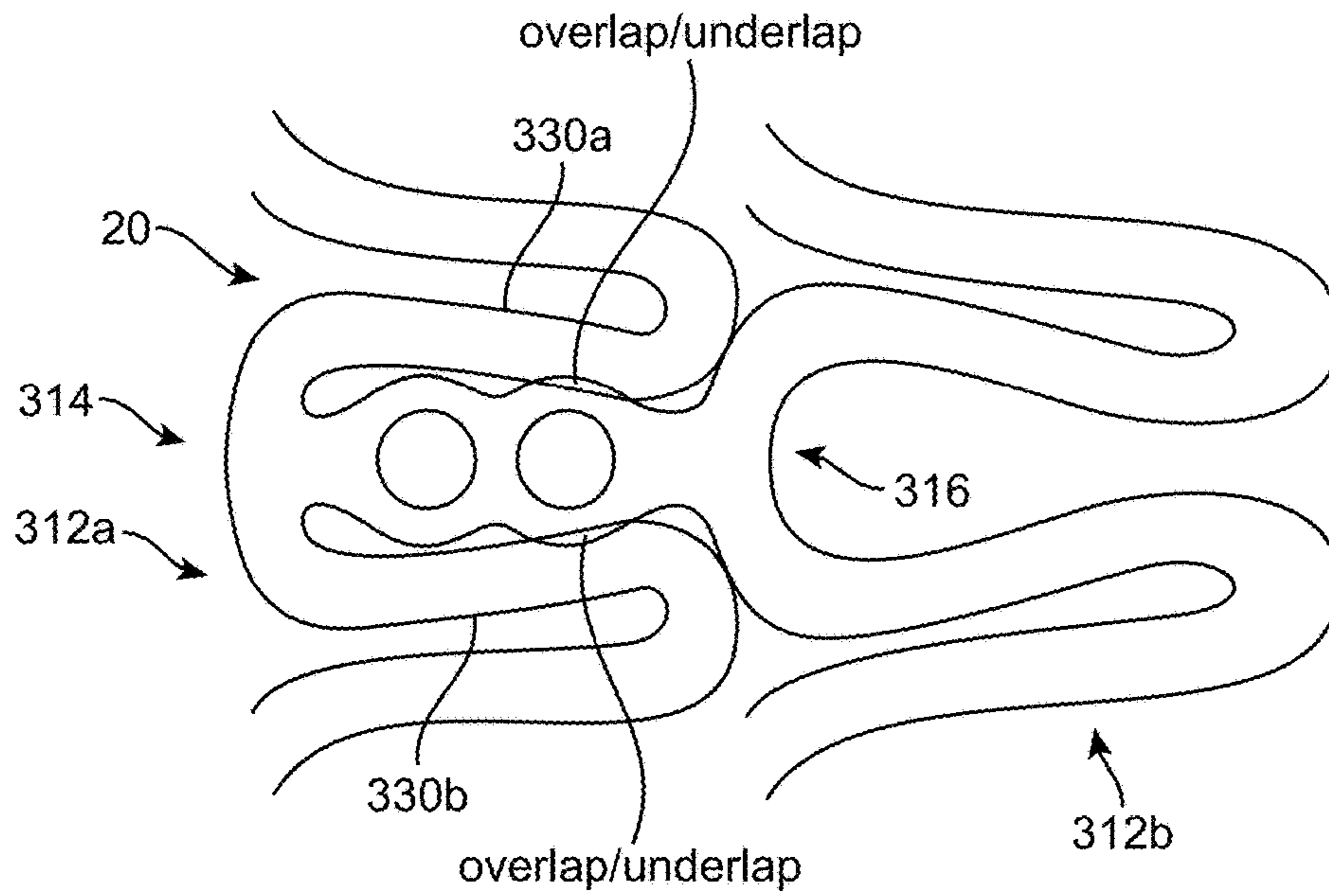


FIG. 3C

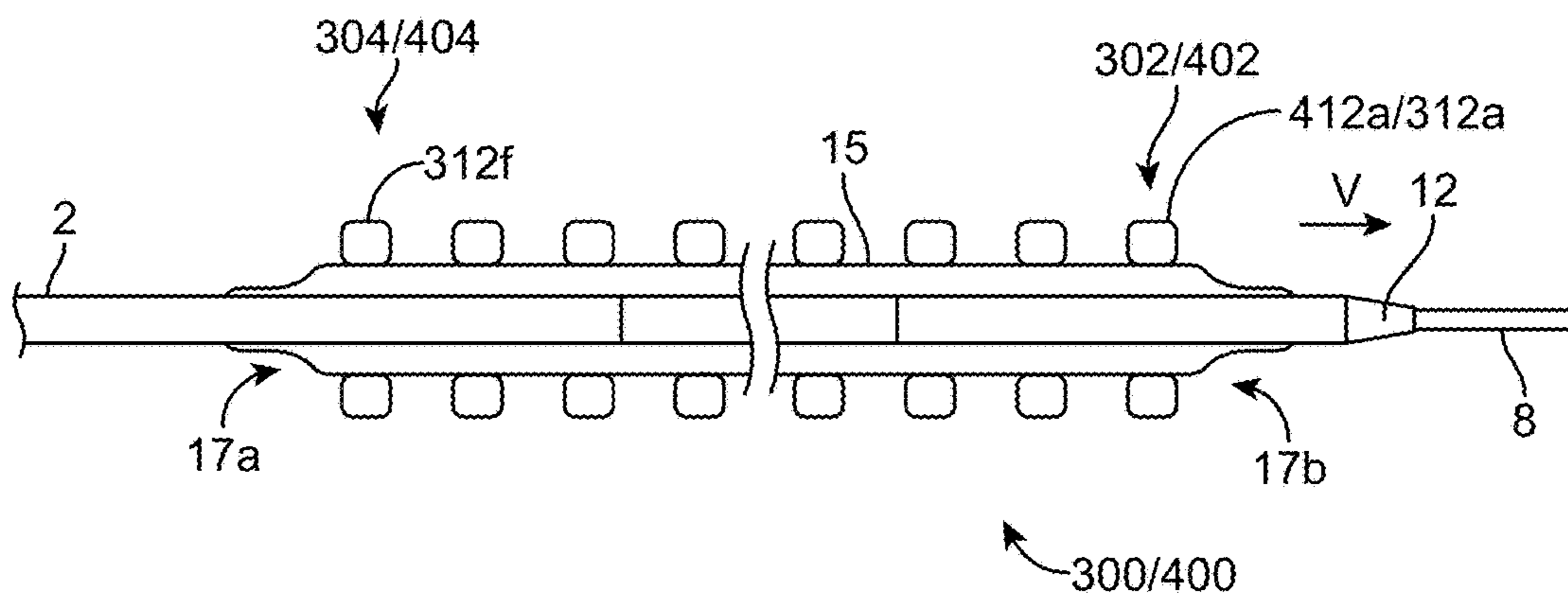


FIG. 3D

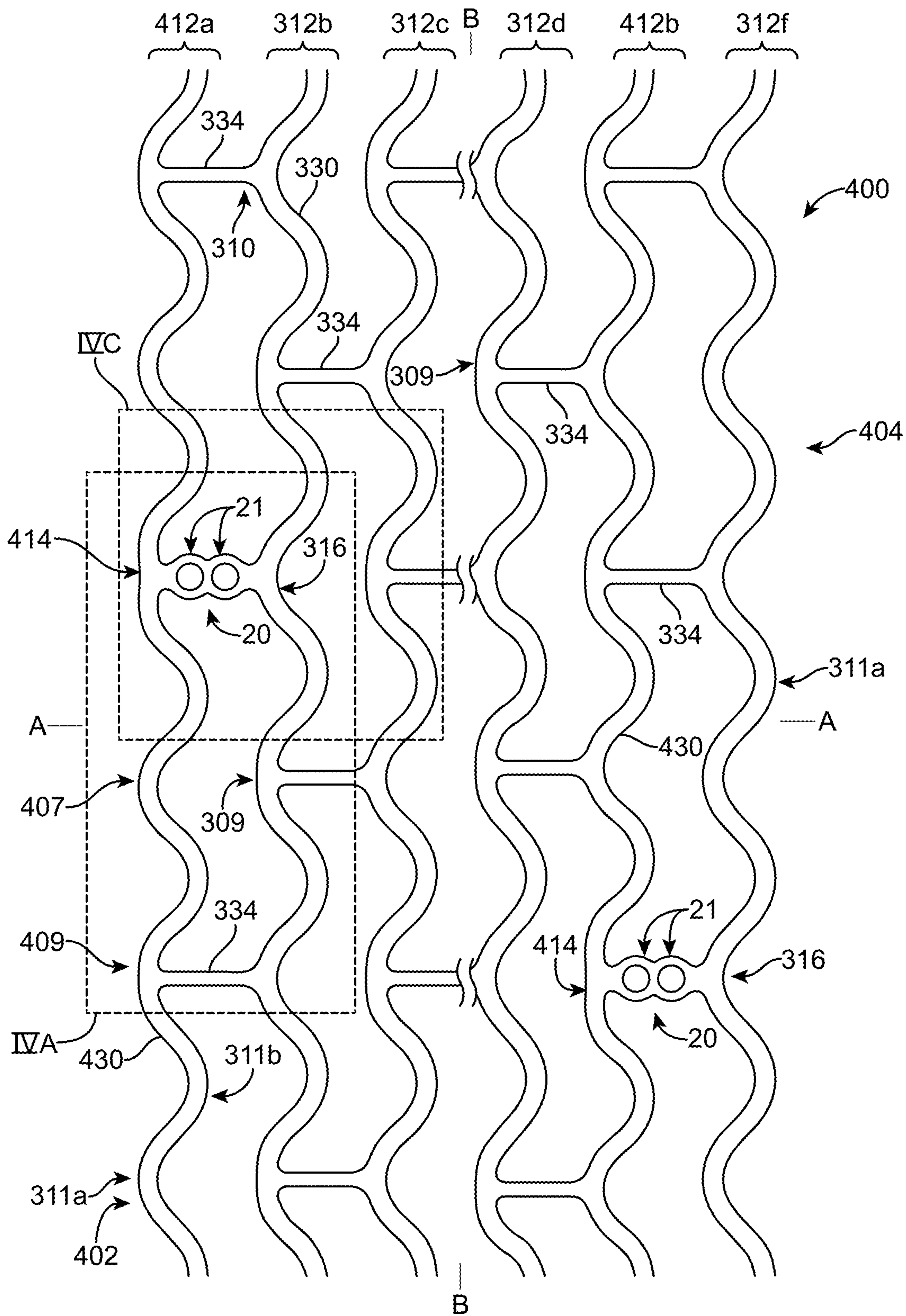


FIG. 4

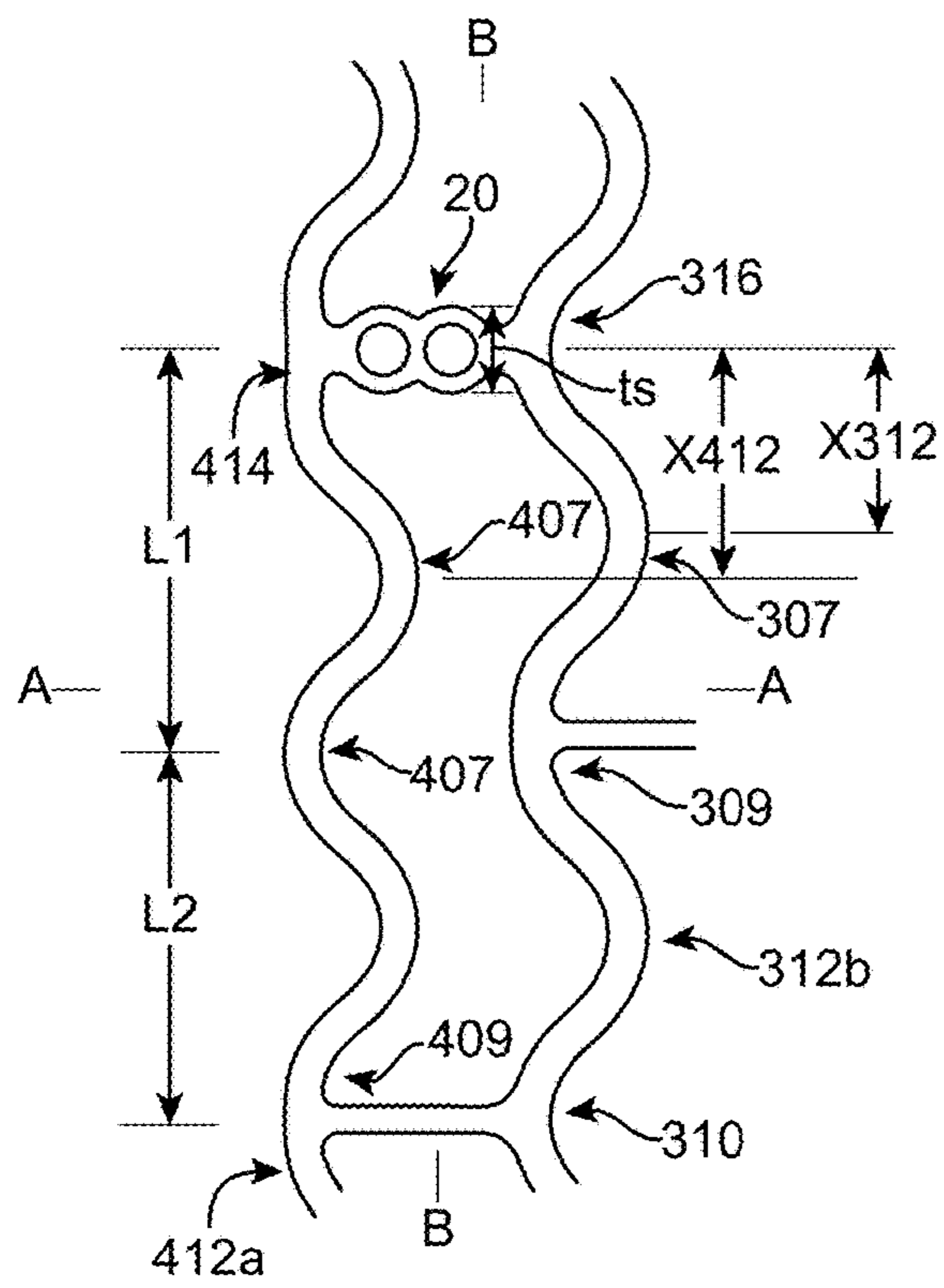


FIG. 4A

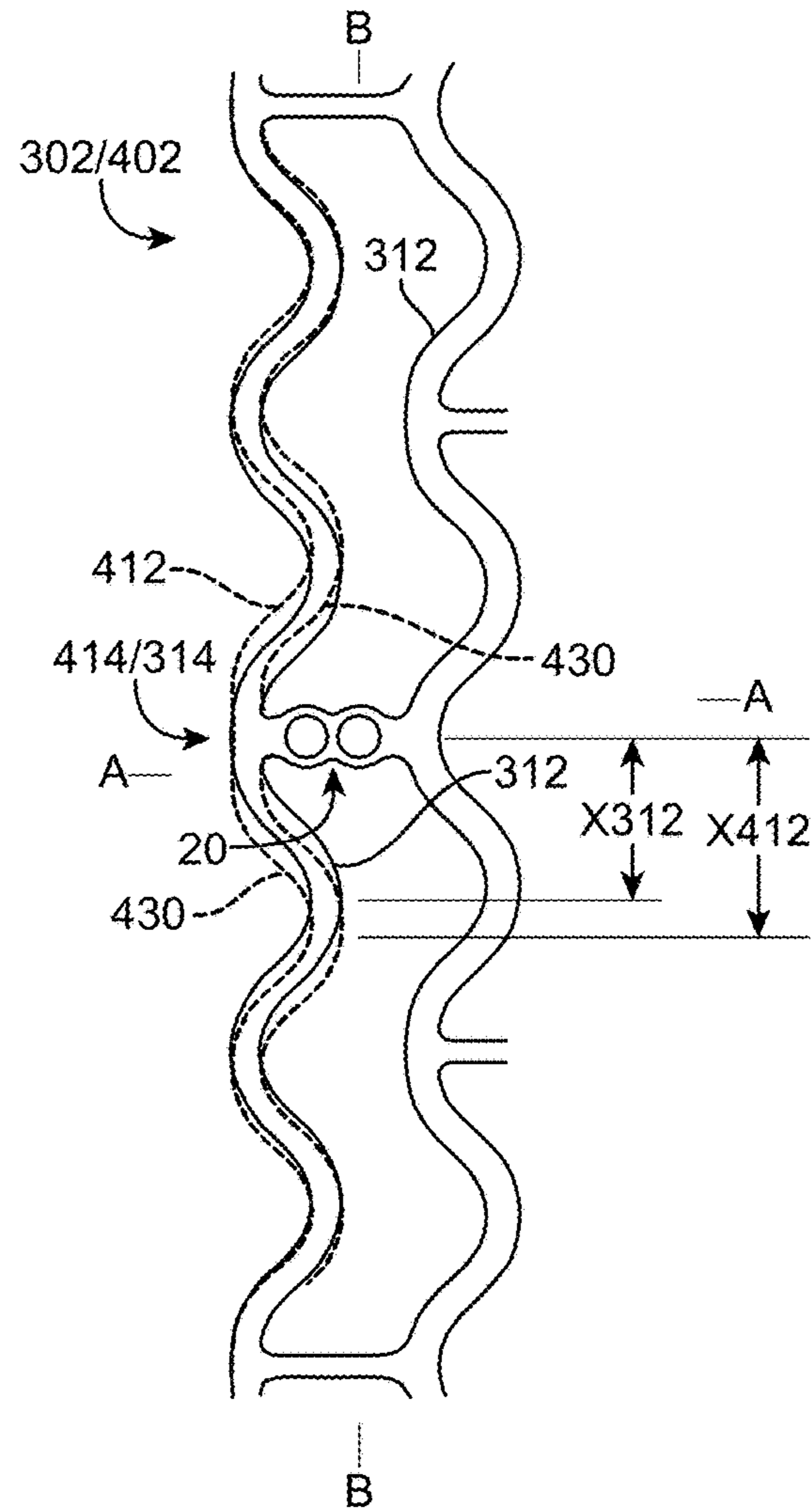


FIG. 4B

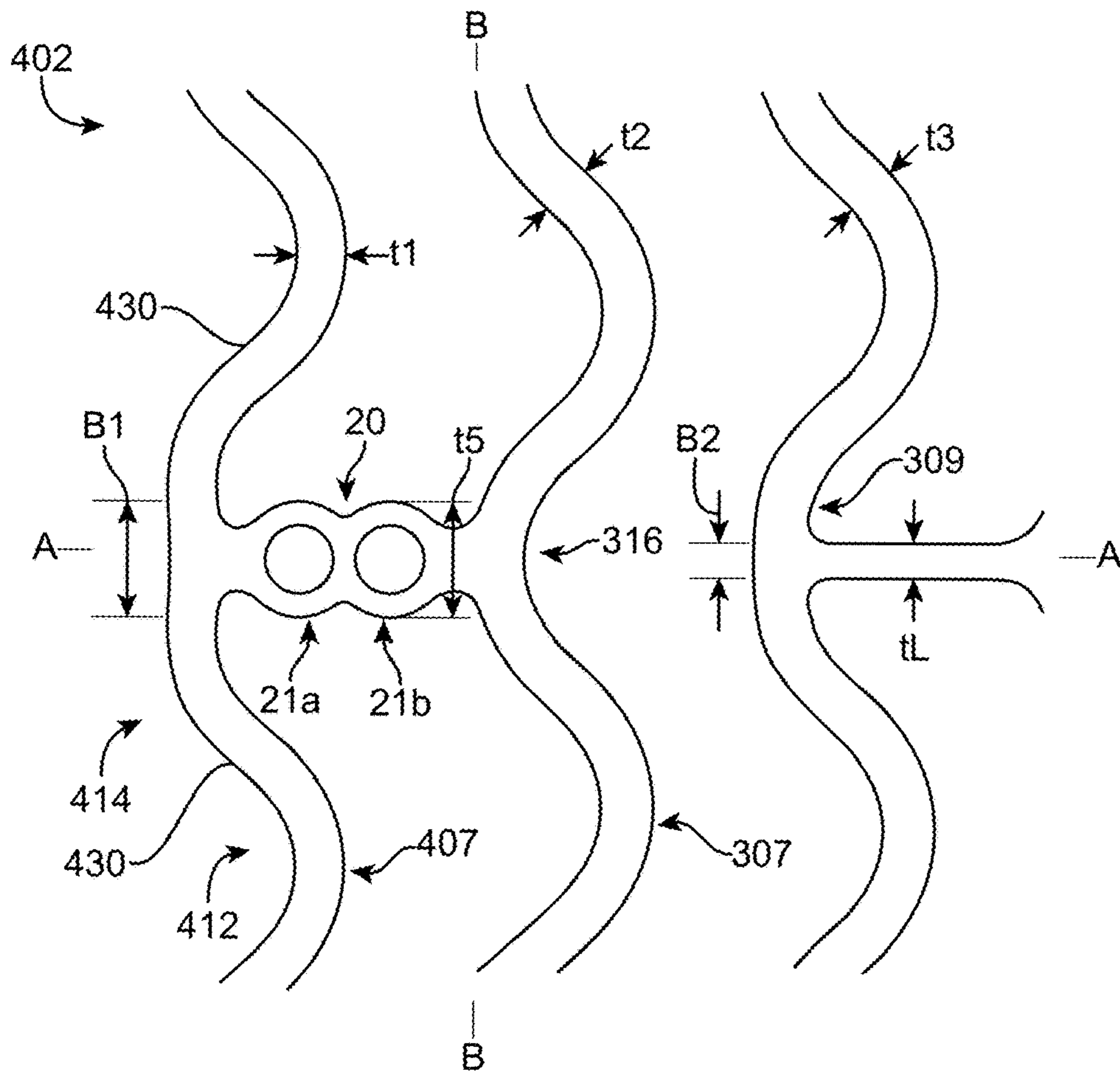


FIG. 4C

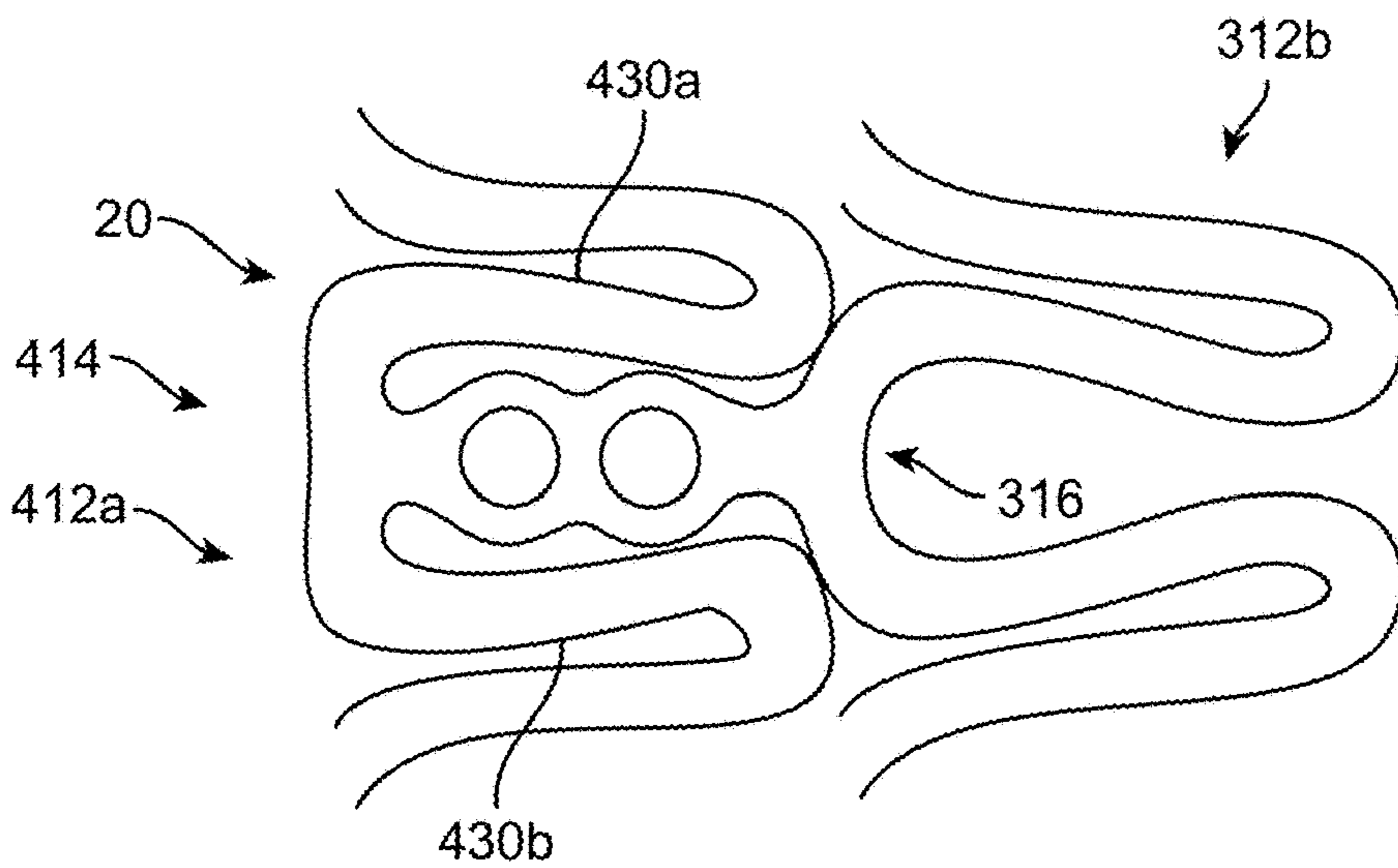


FIG. 4D

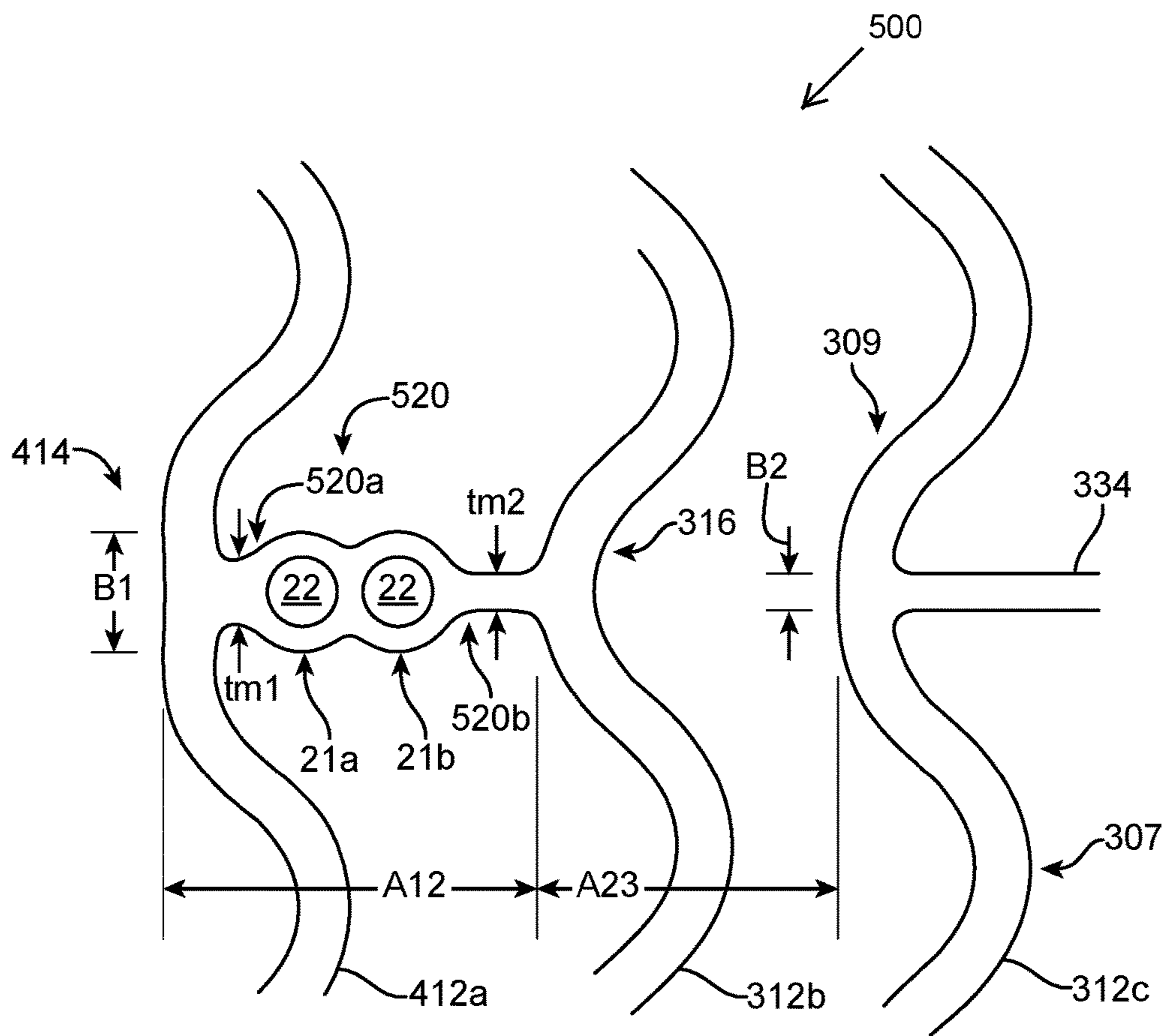


FIG. 5

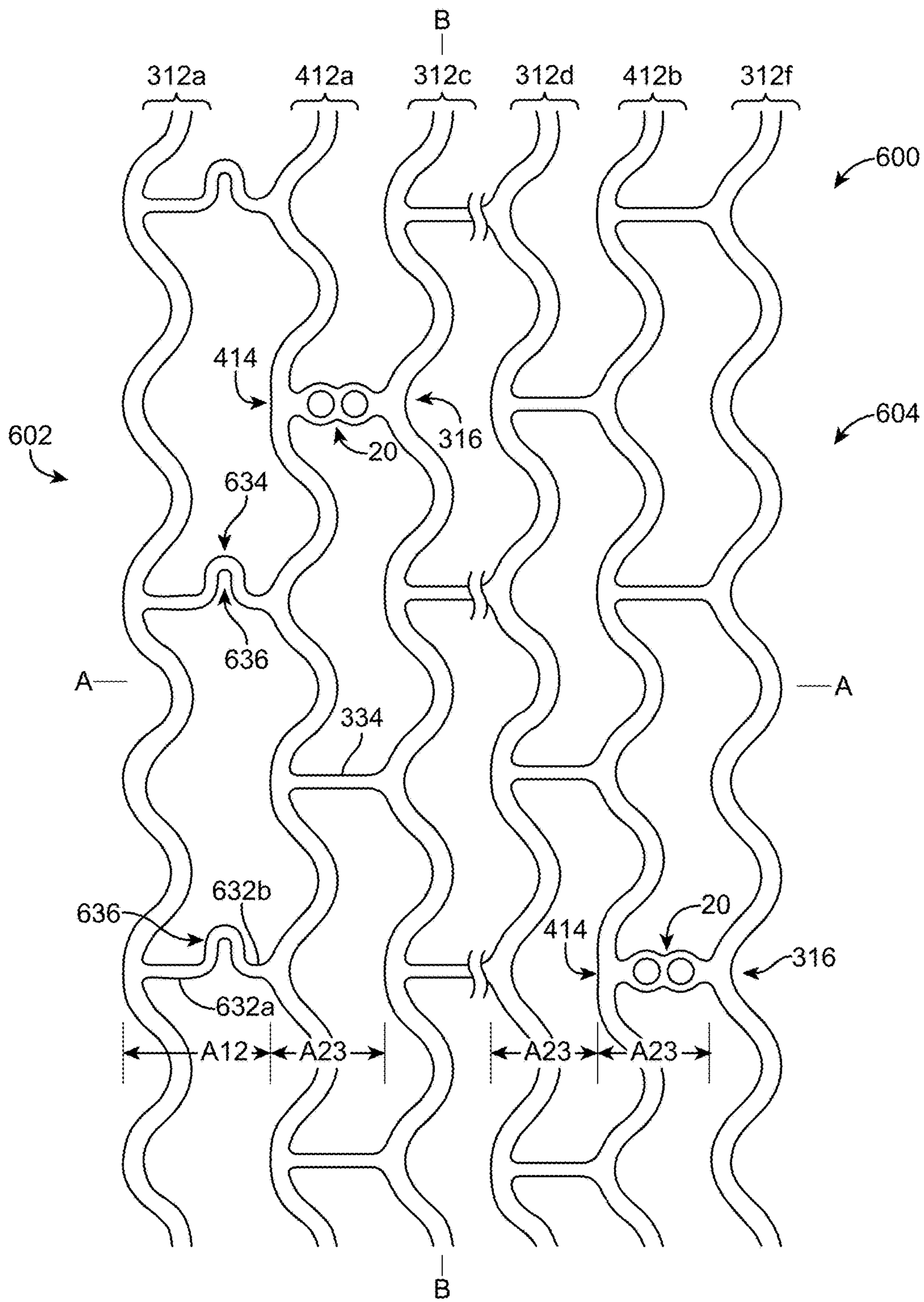


FIG. 6

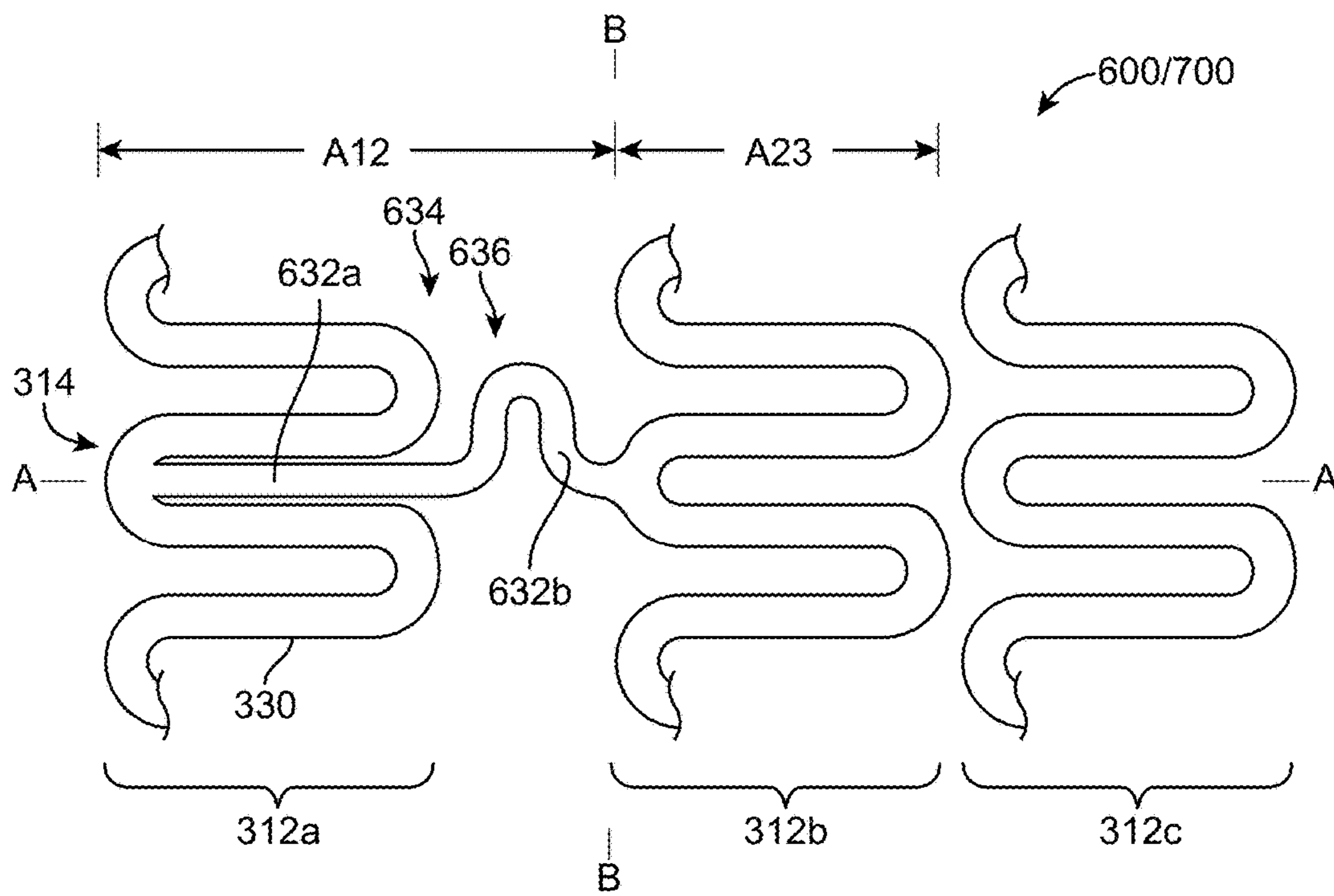


FIG. 6A

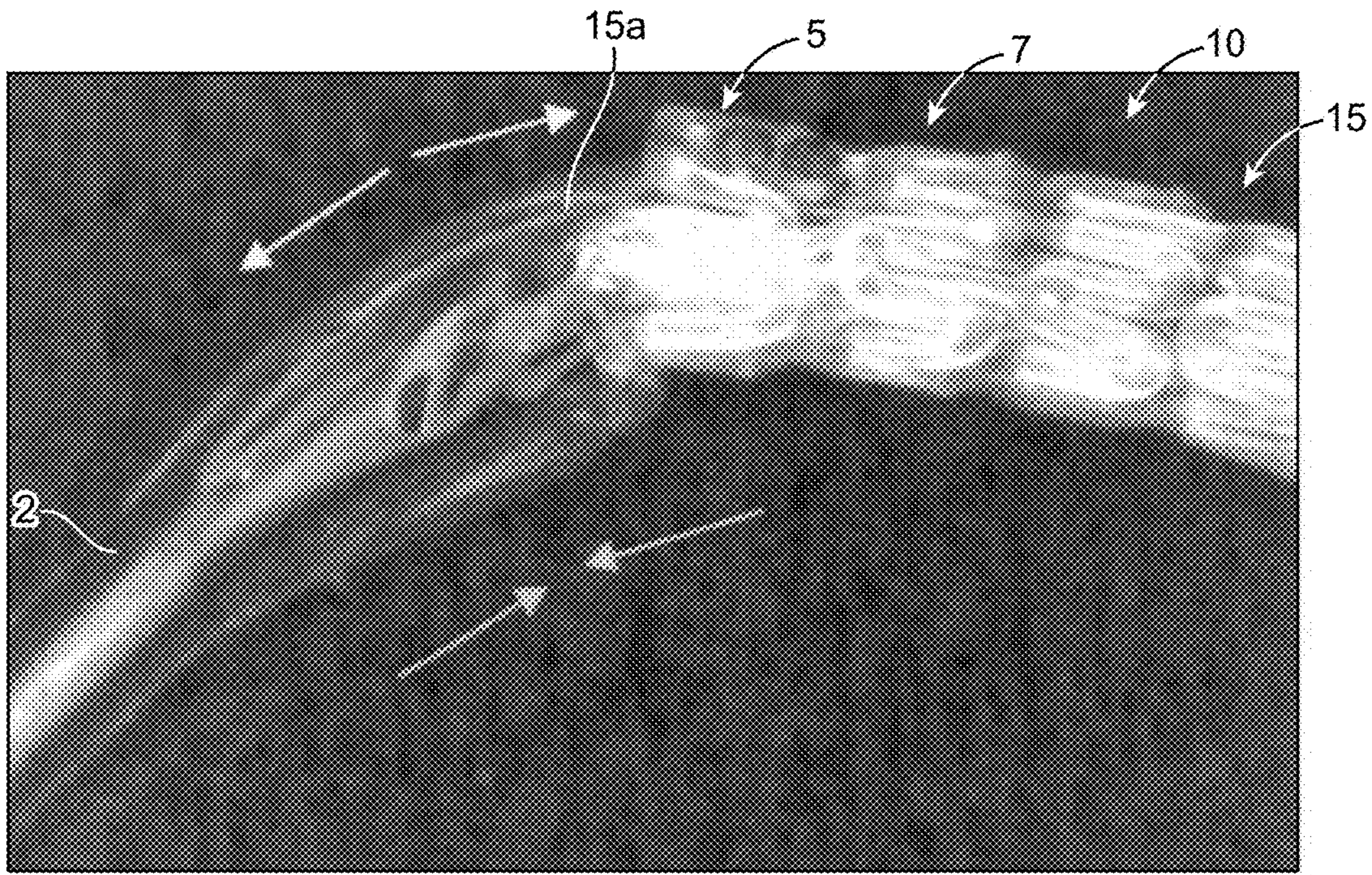


FIG. 6B

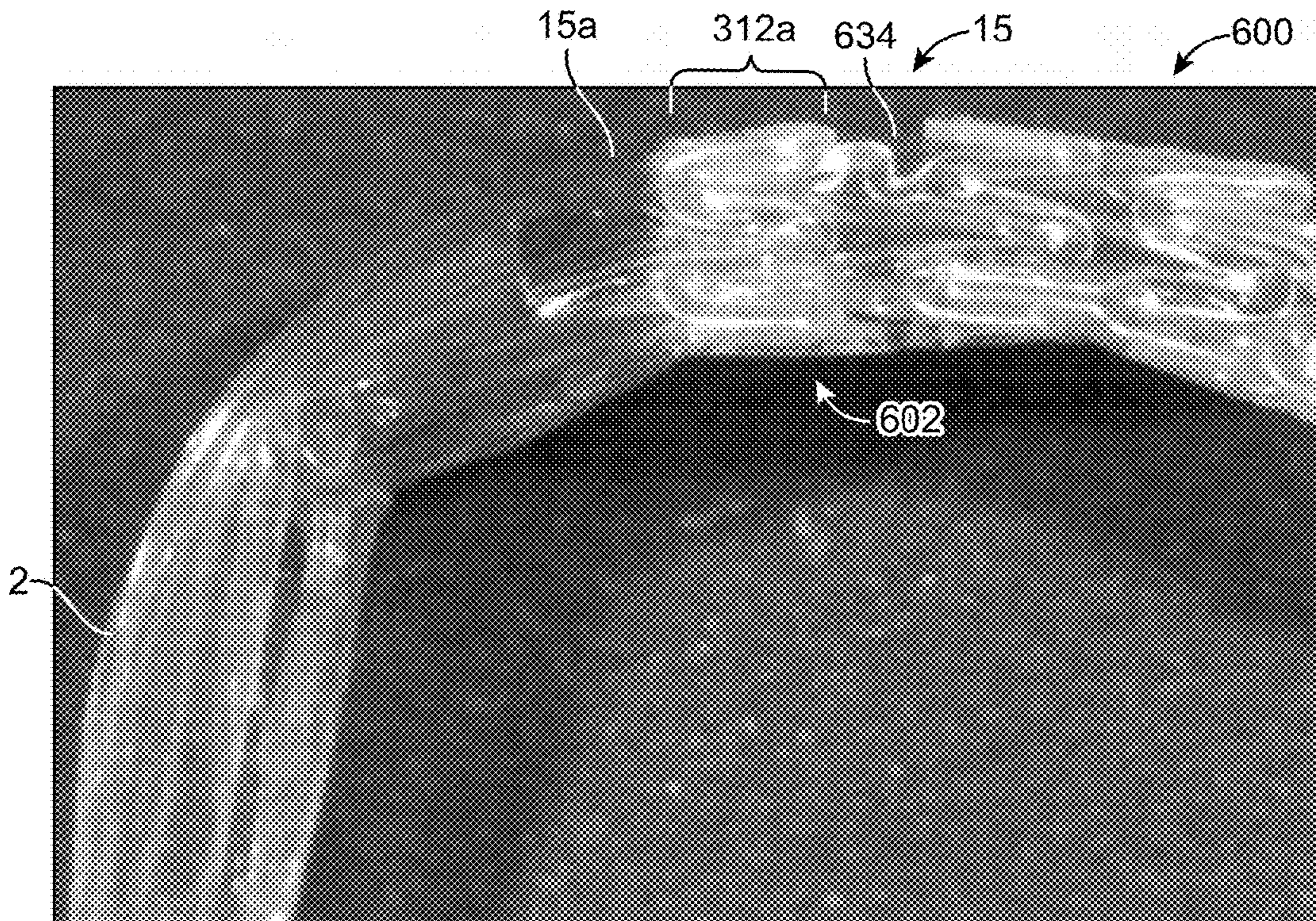


FIG. 6C



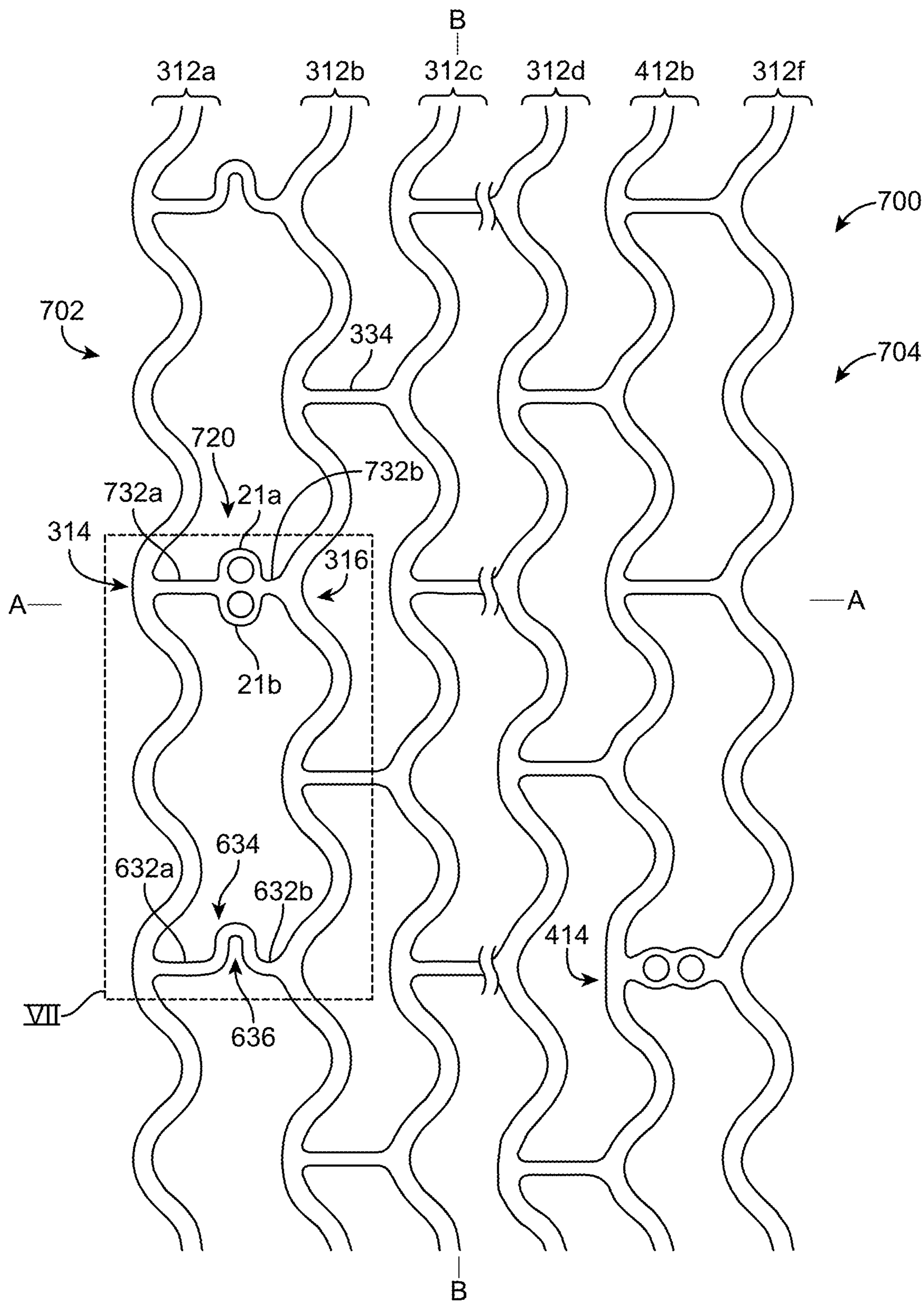


FIG. 7

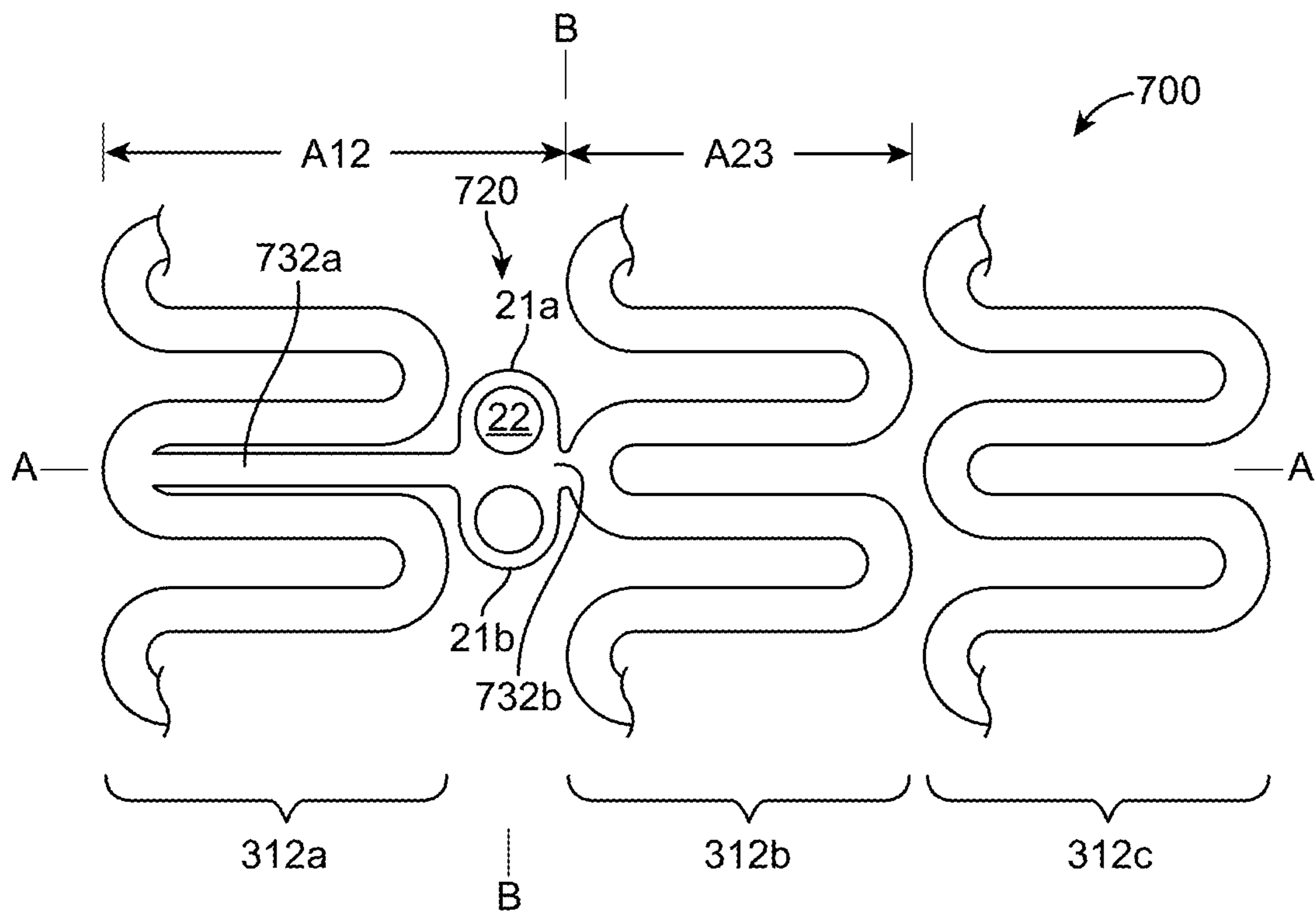


FIG. 7A

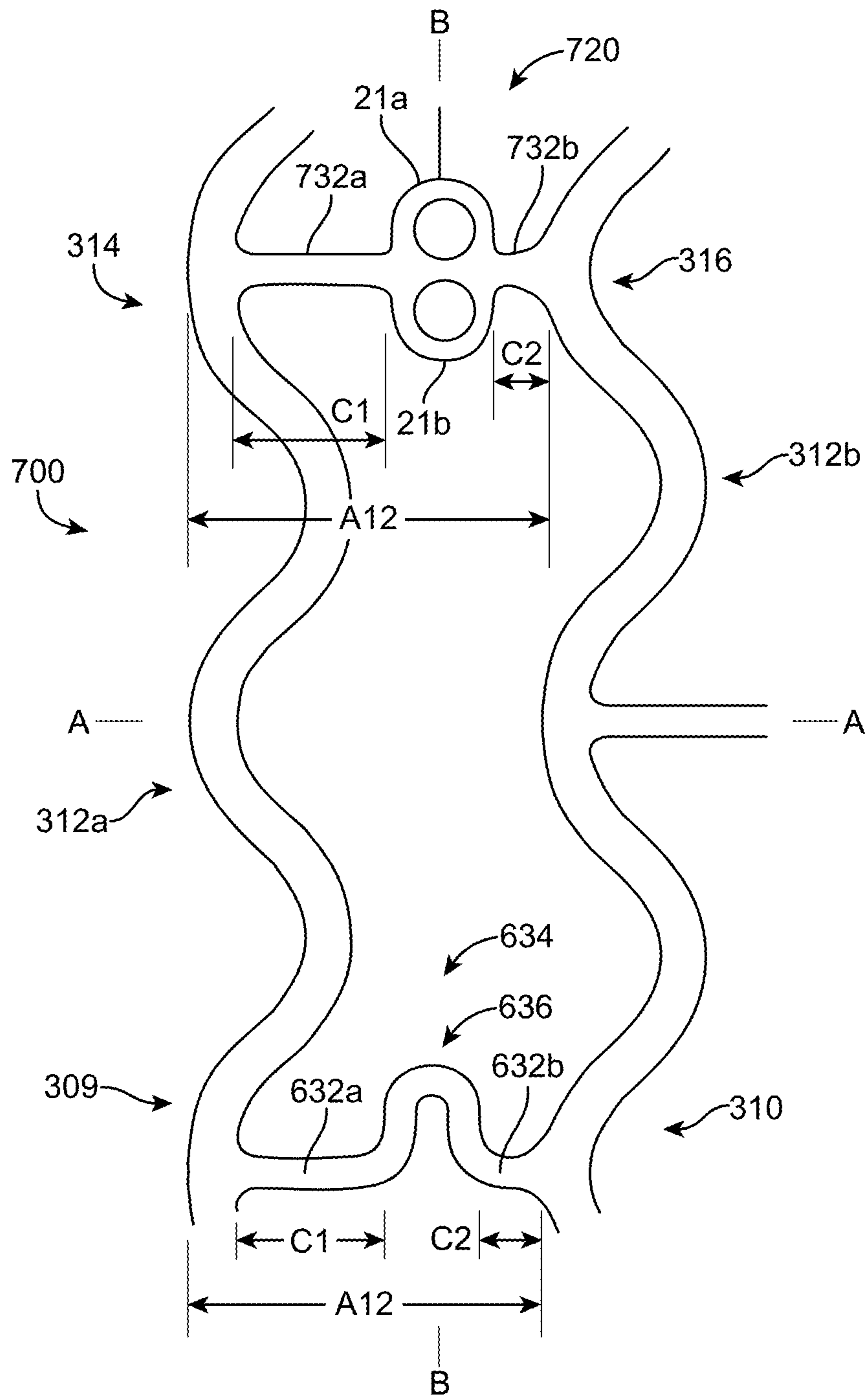


FIG. 7B

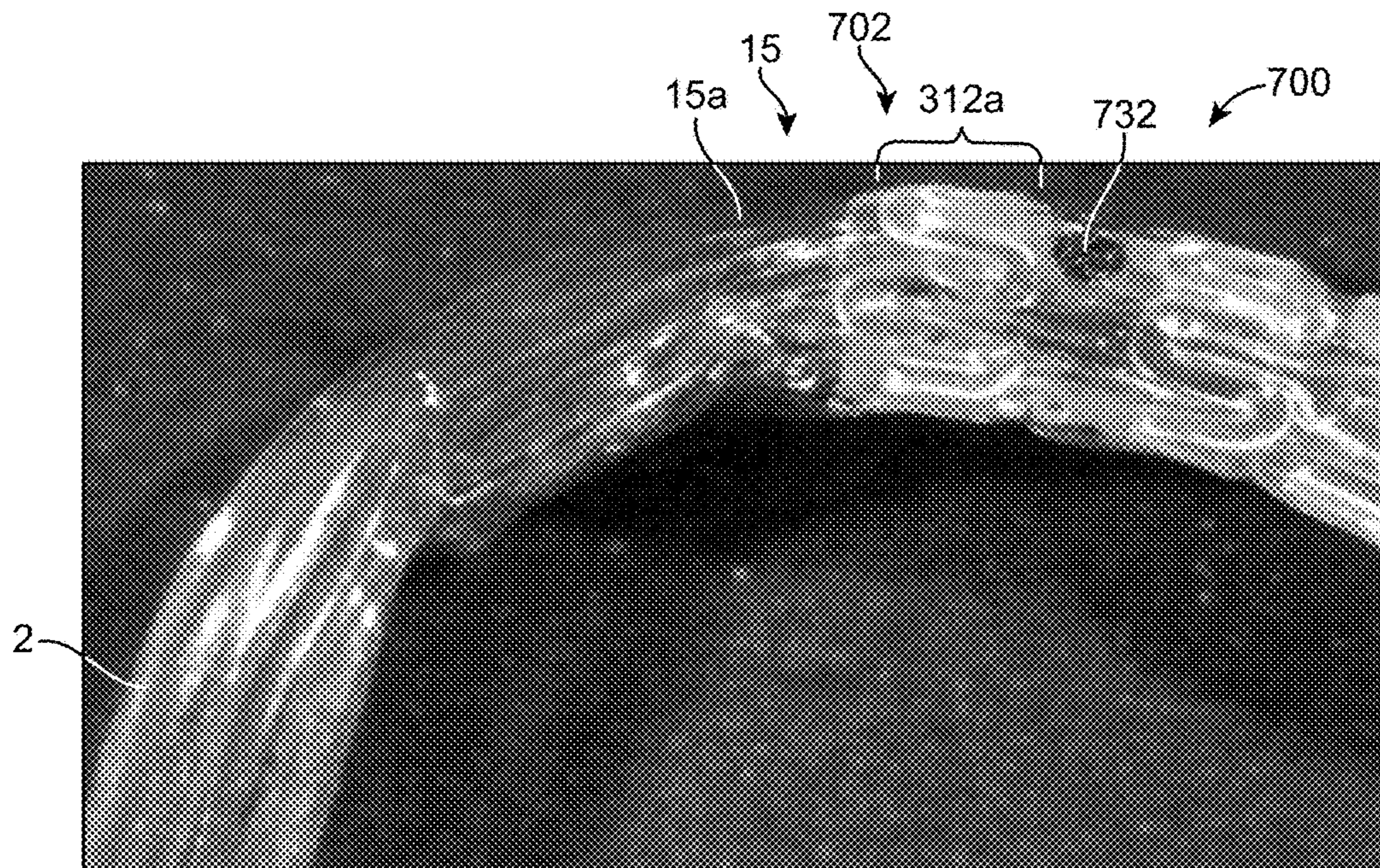


FIG. 7C

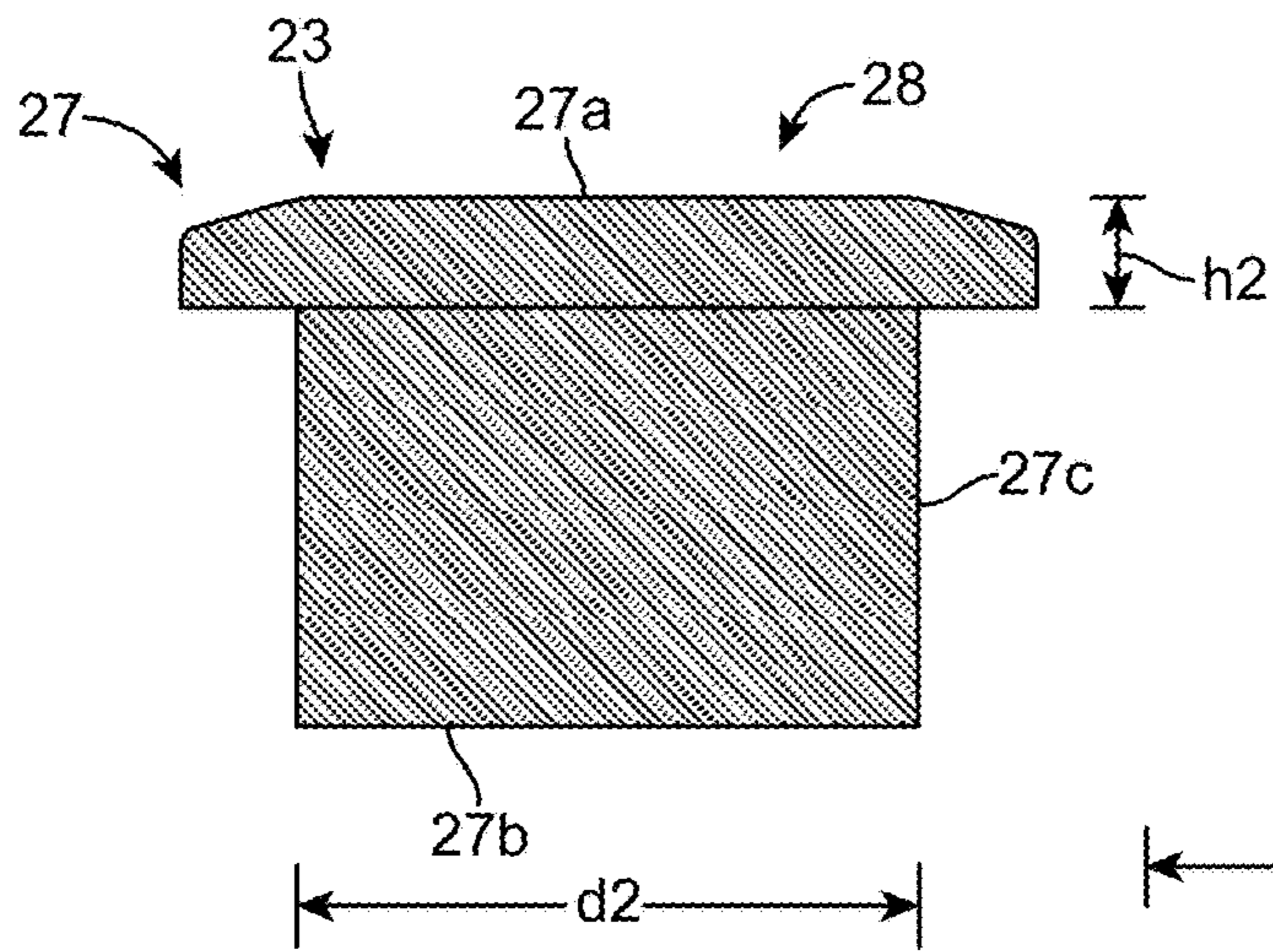


FIG. 8A

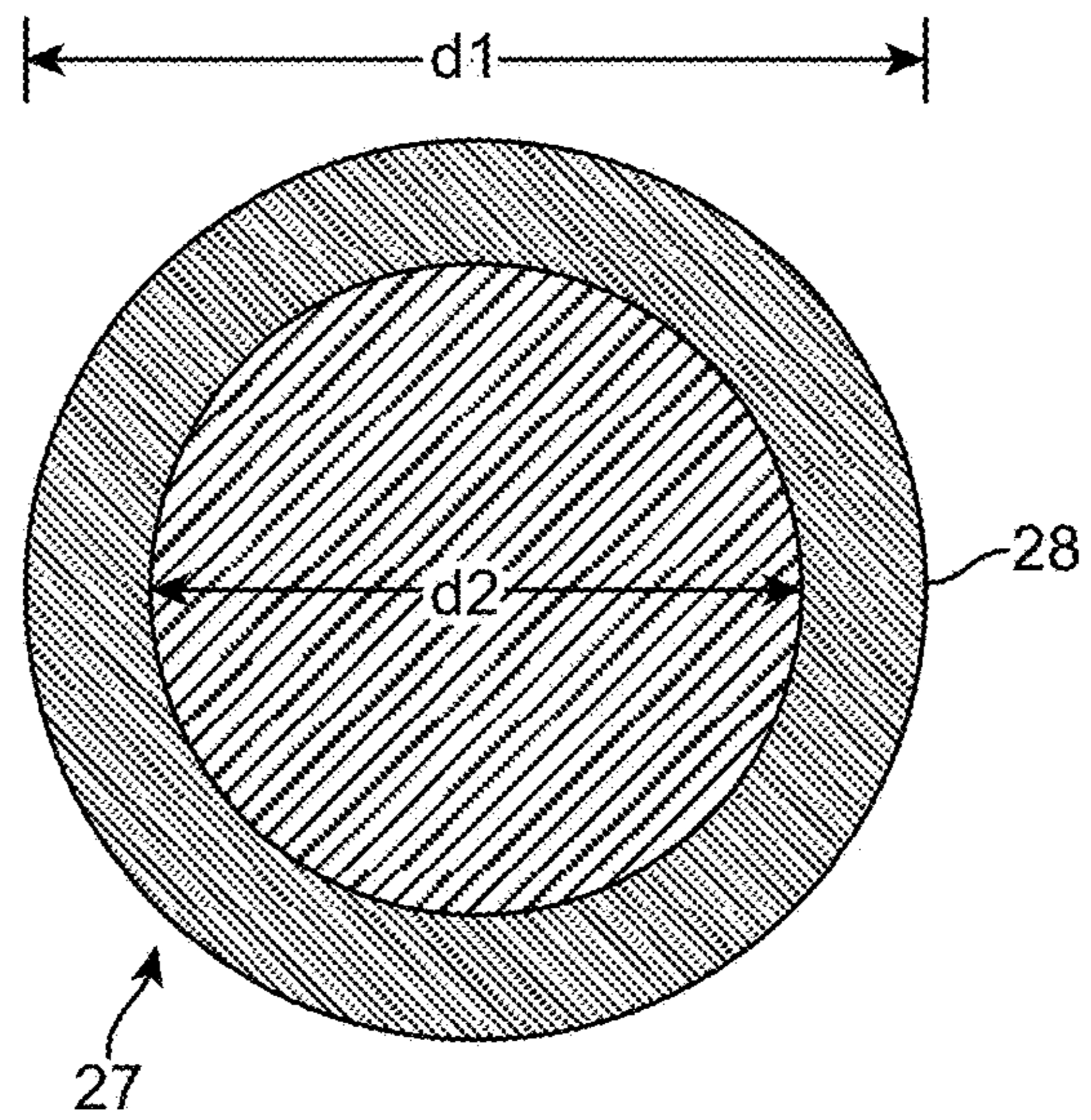


FIG. 8B

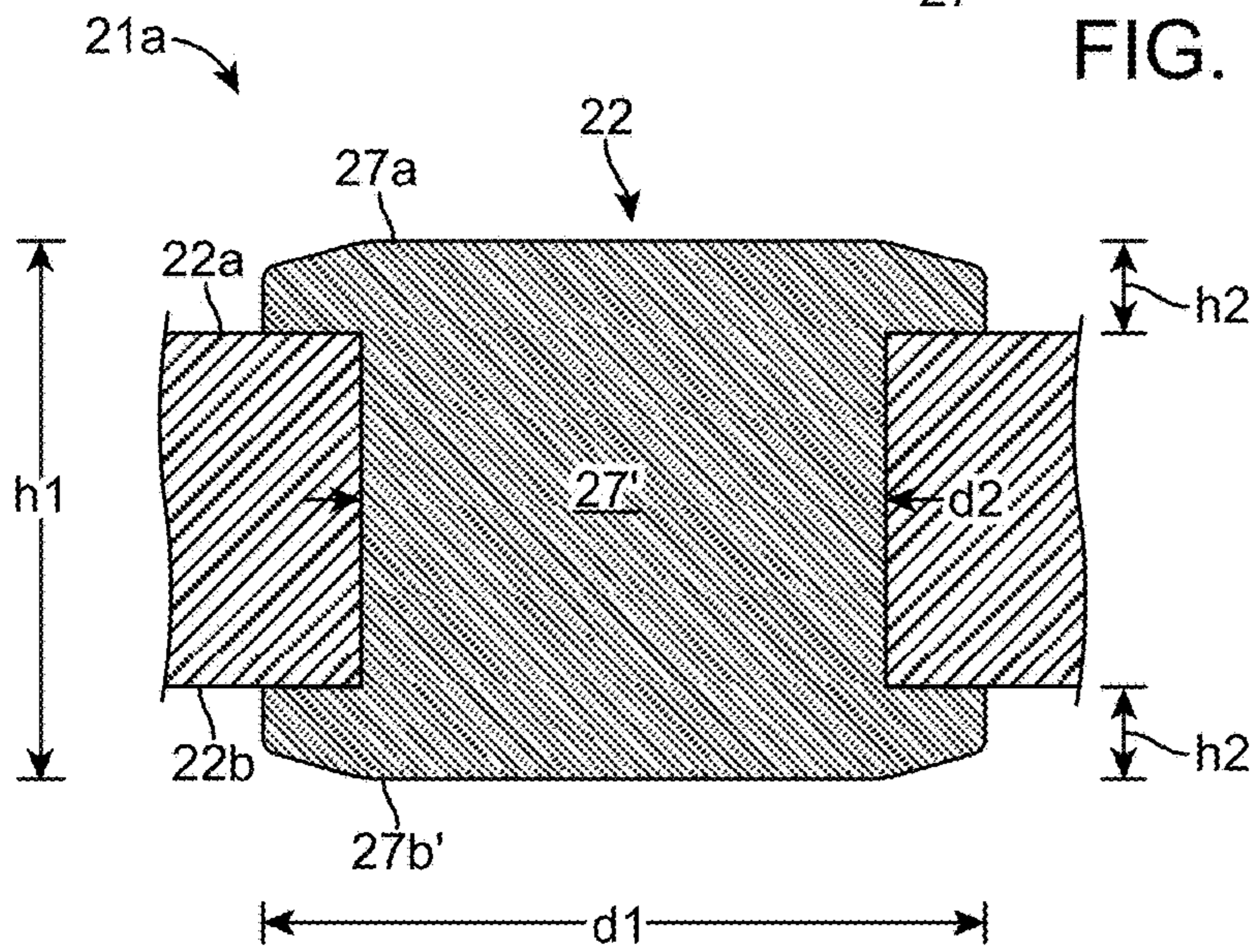


FIG. 9

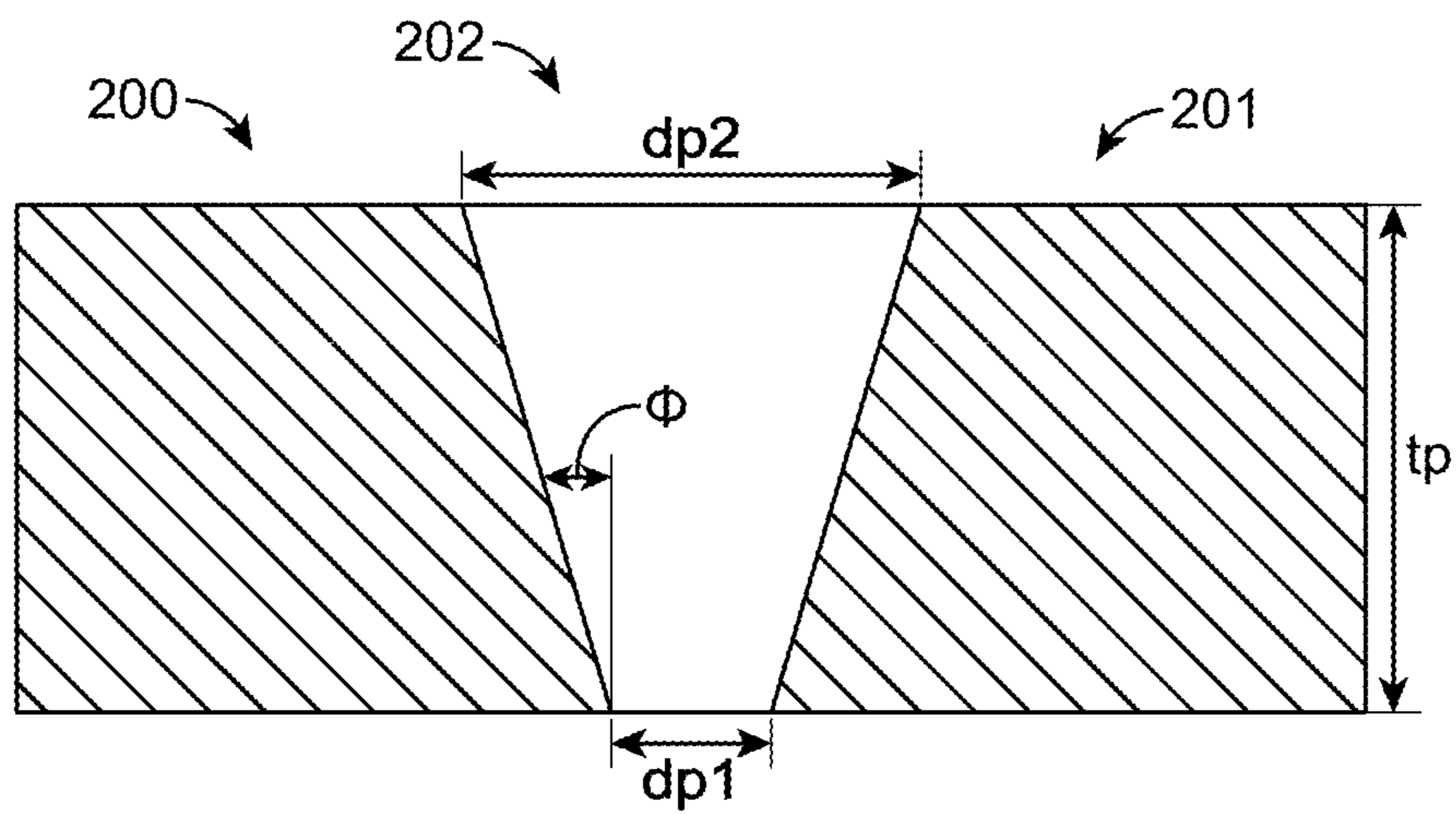


FIG. 10

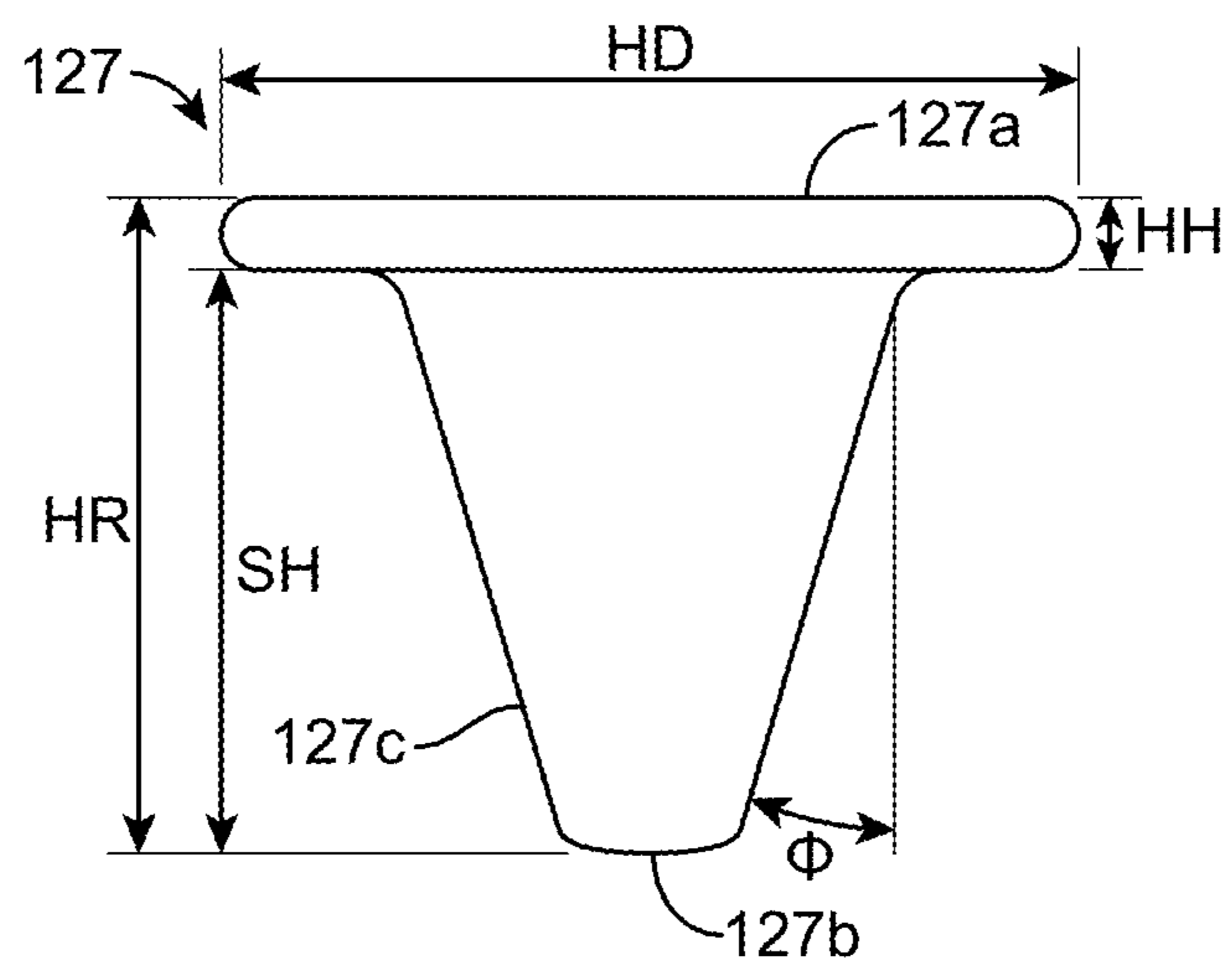


FIG. 11A

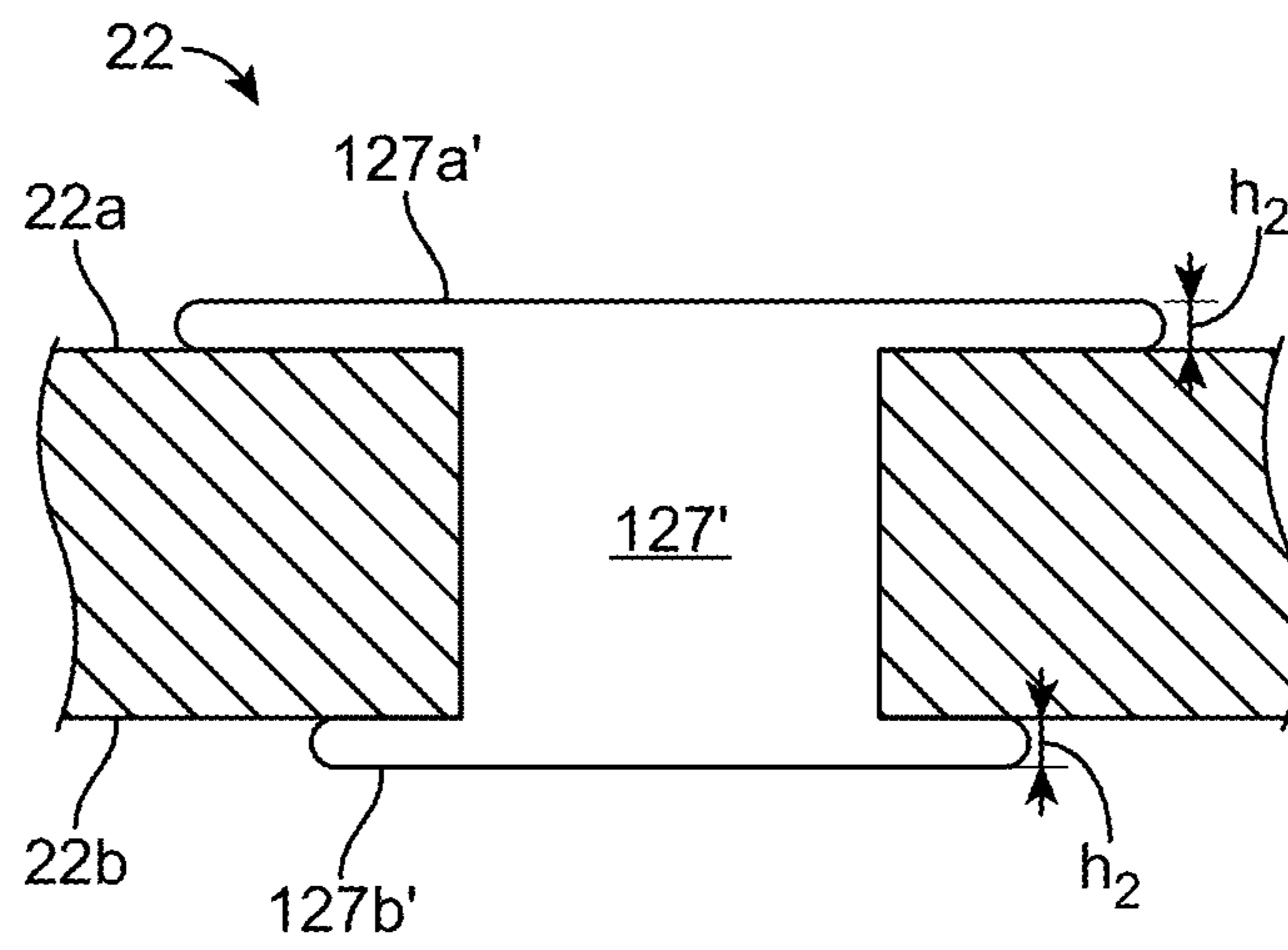


FIG. 11B

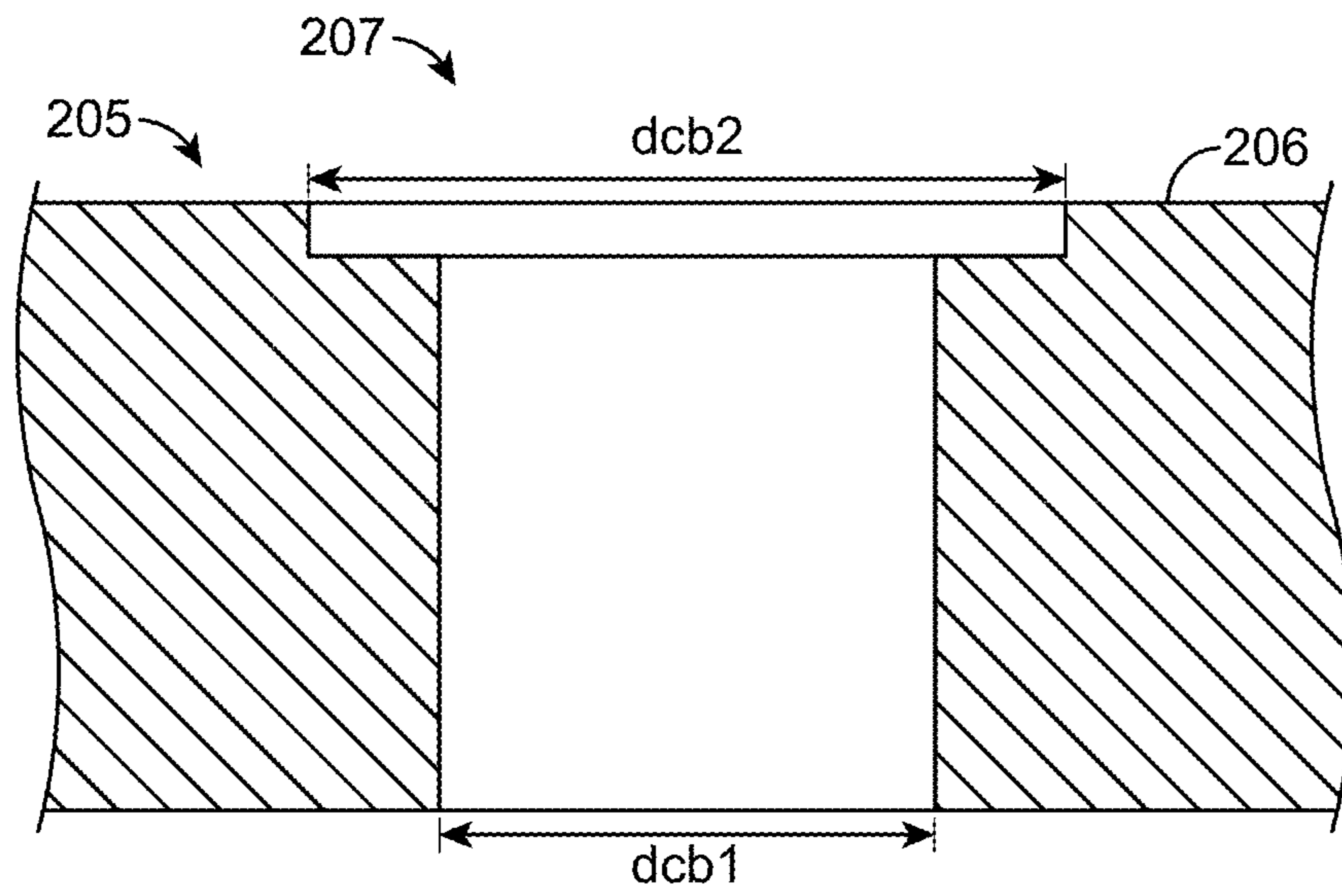


FIG. 12

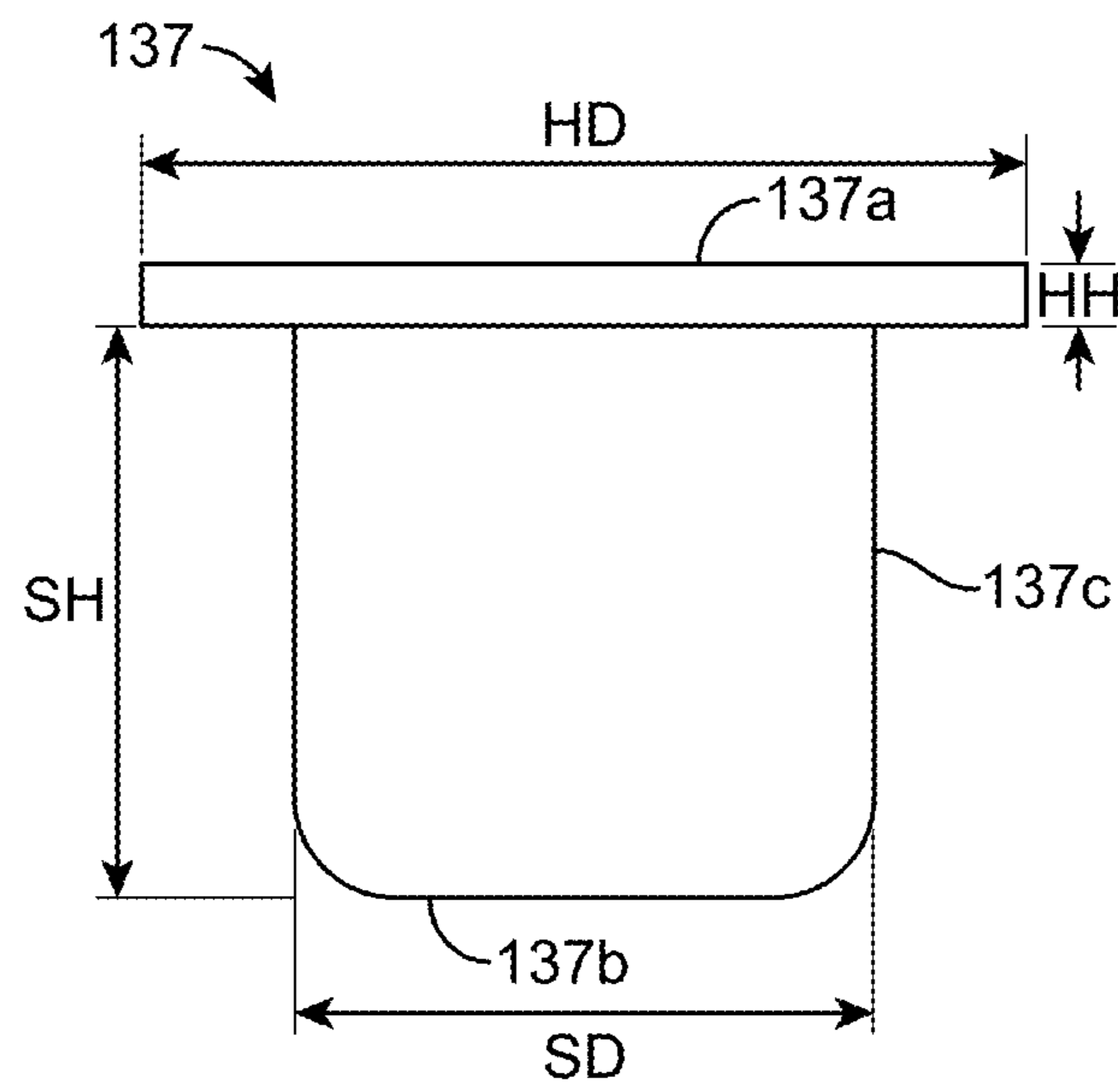


FIG. 13



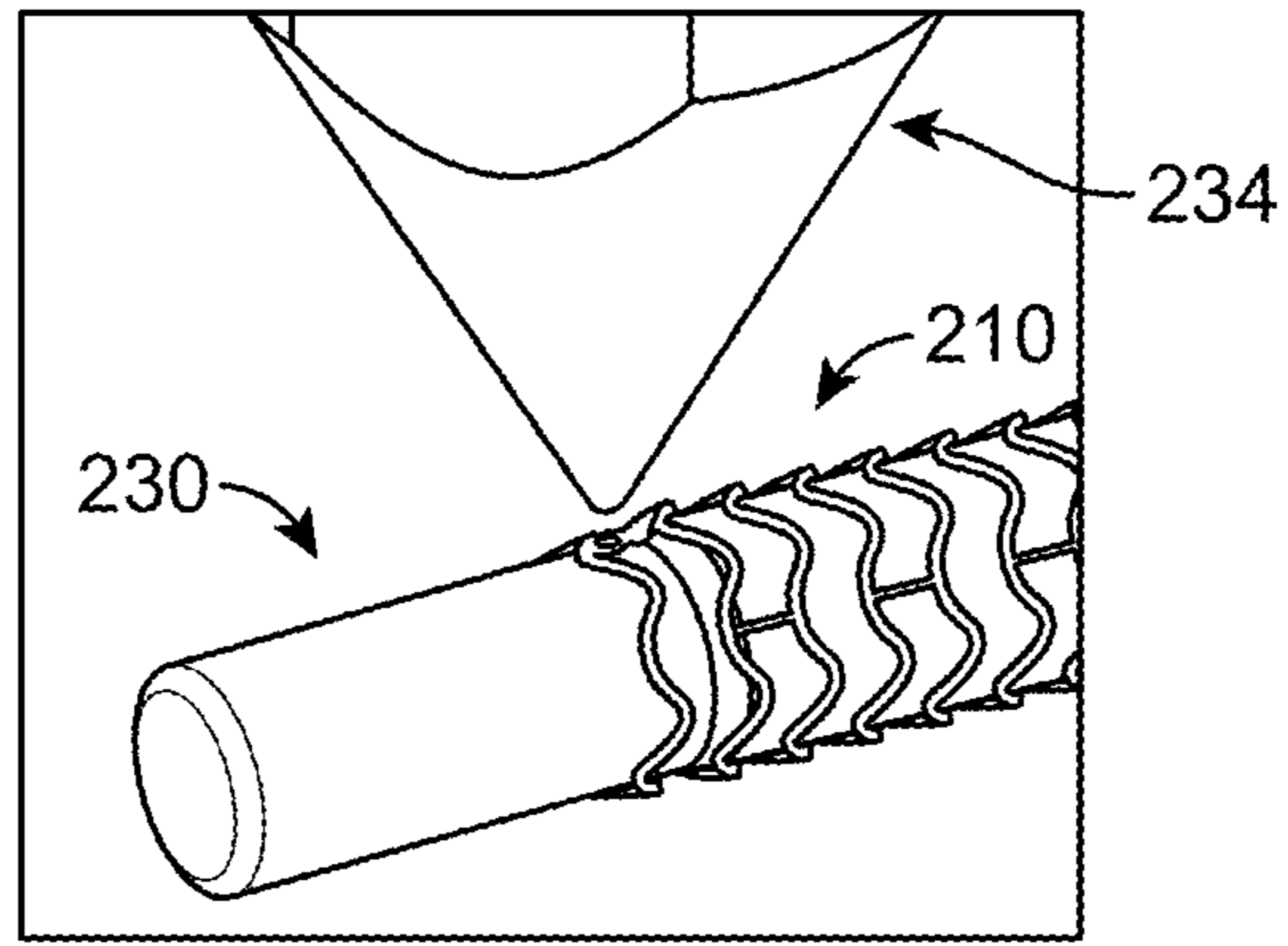


FIG. 14A

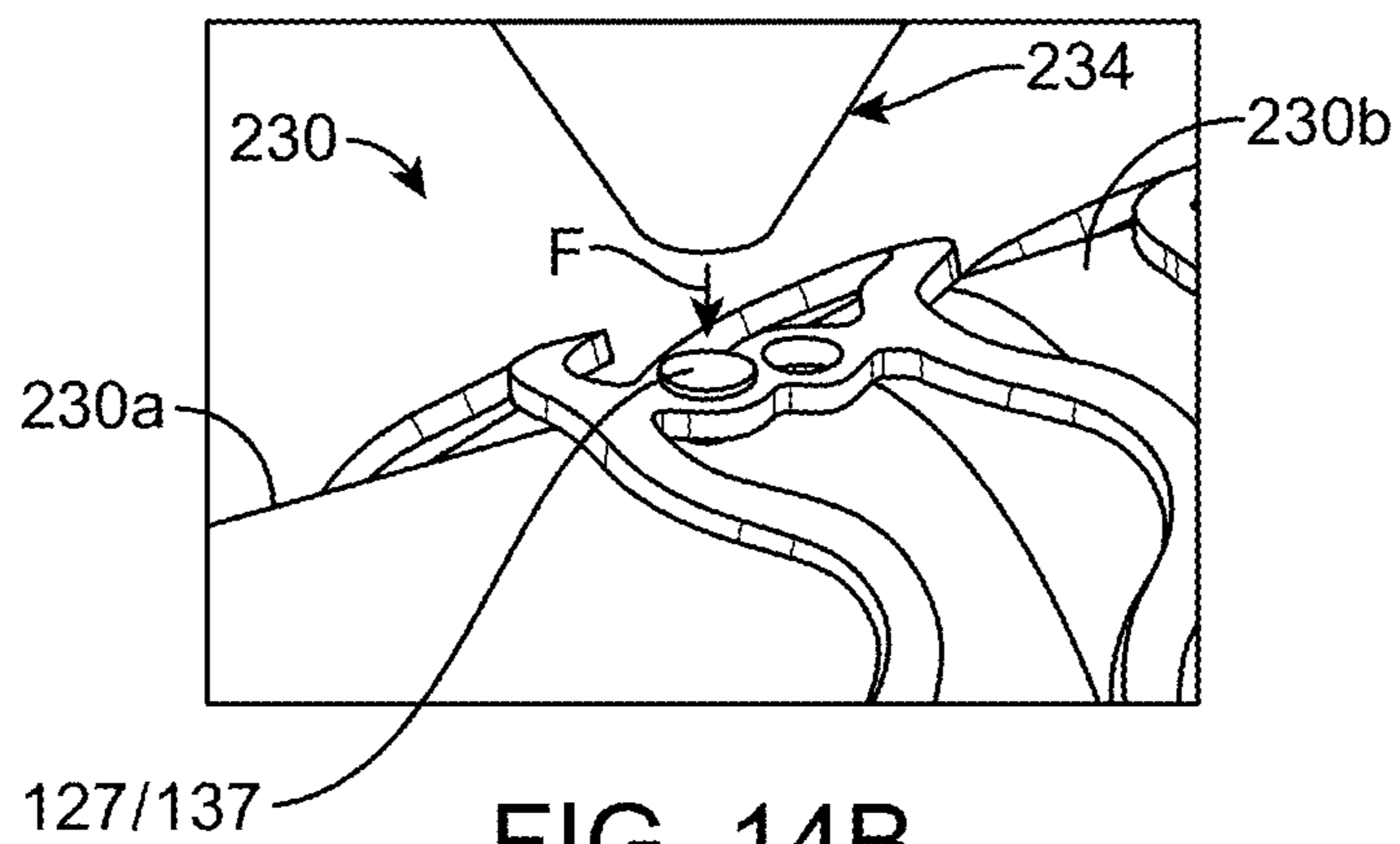


FIG. 14B

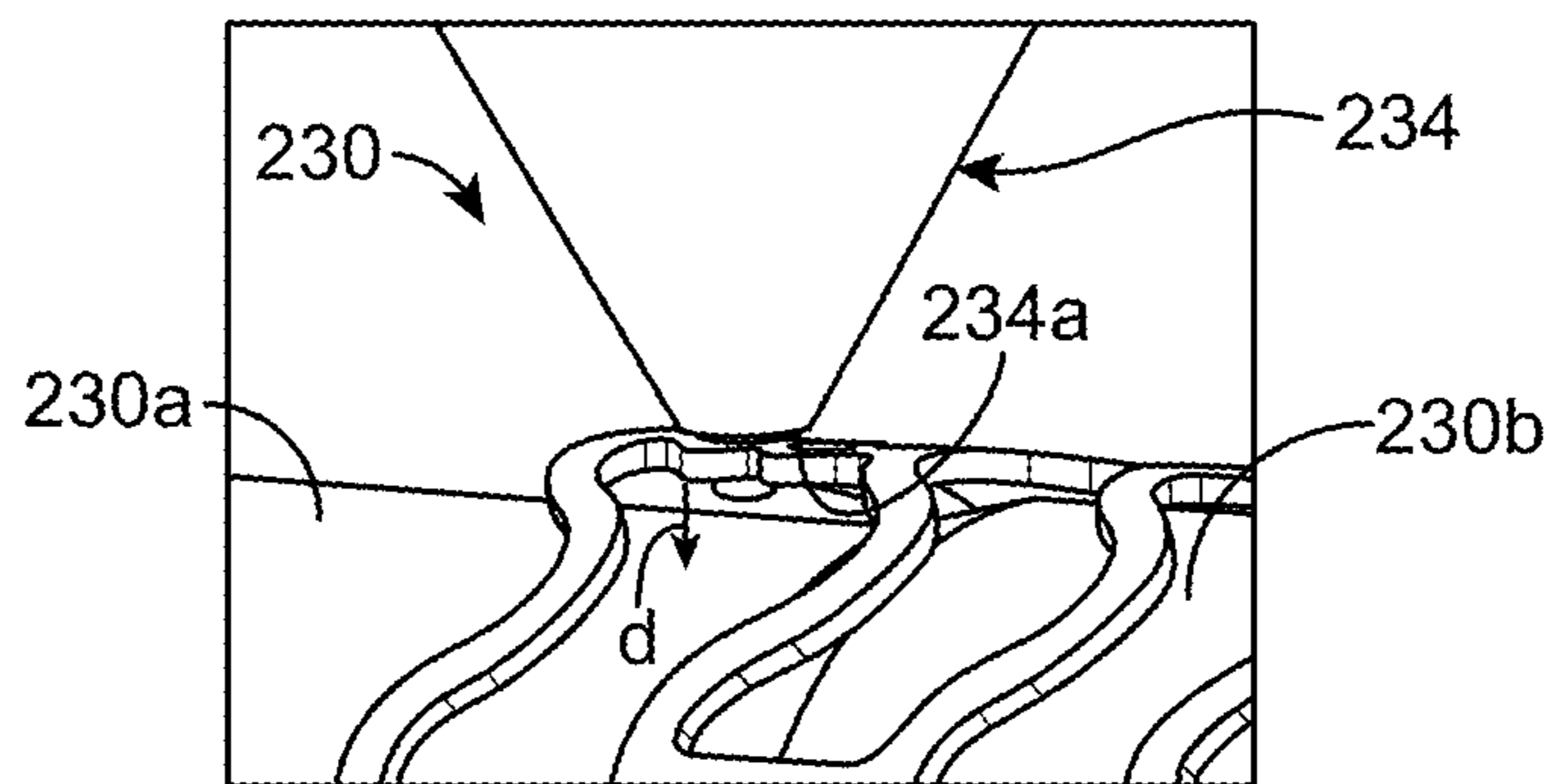


FIG. 14C

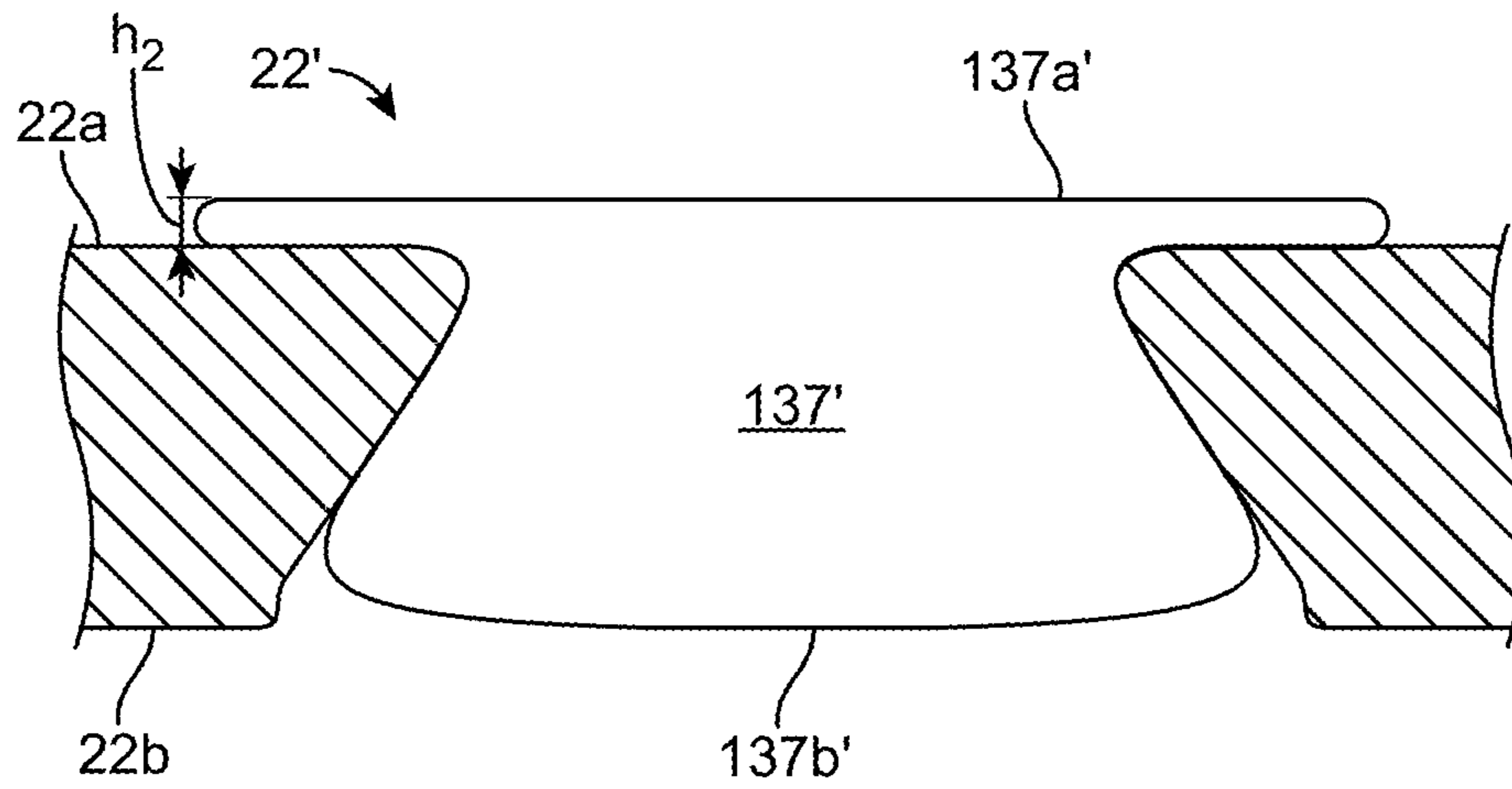


FIG. 15A

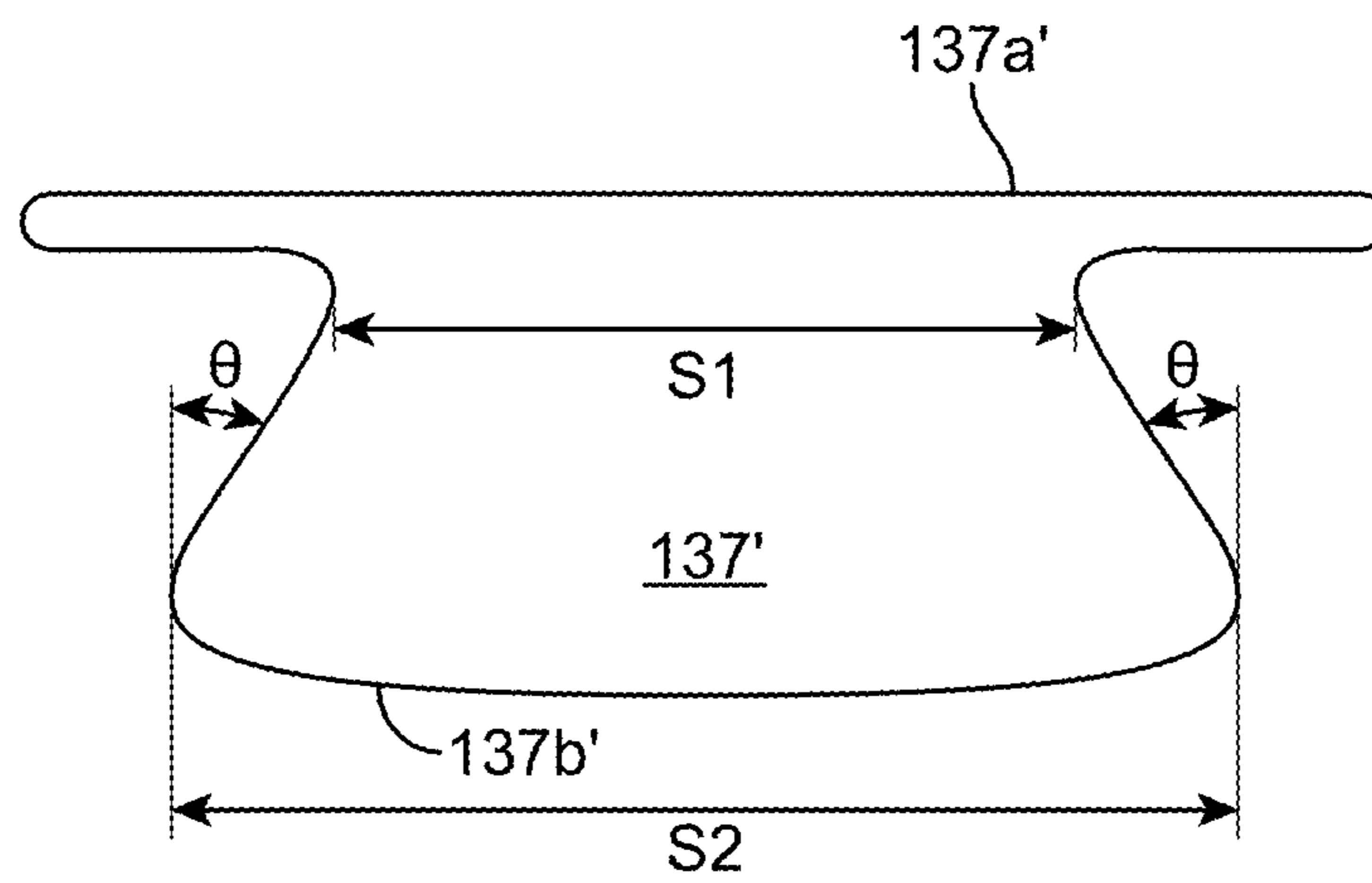


FIG. 15B

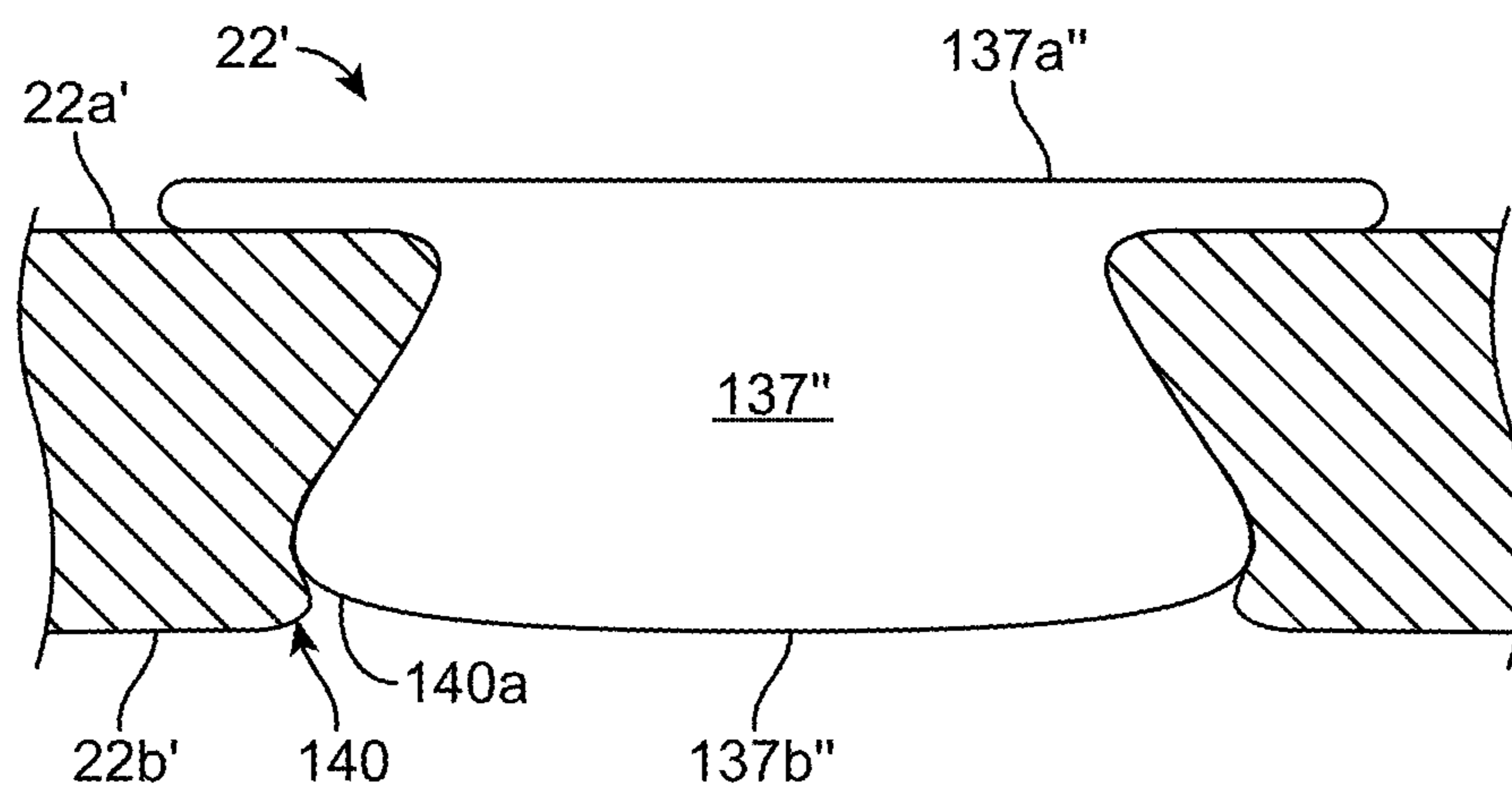


FIG. 15C

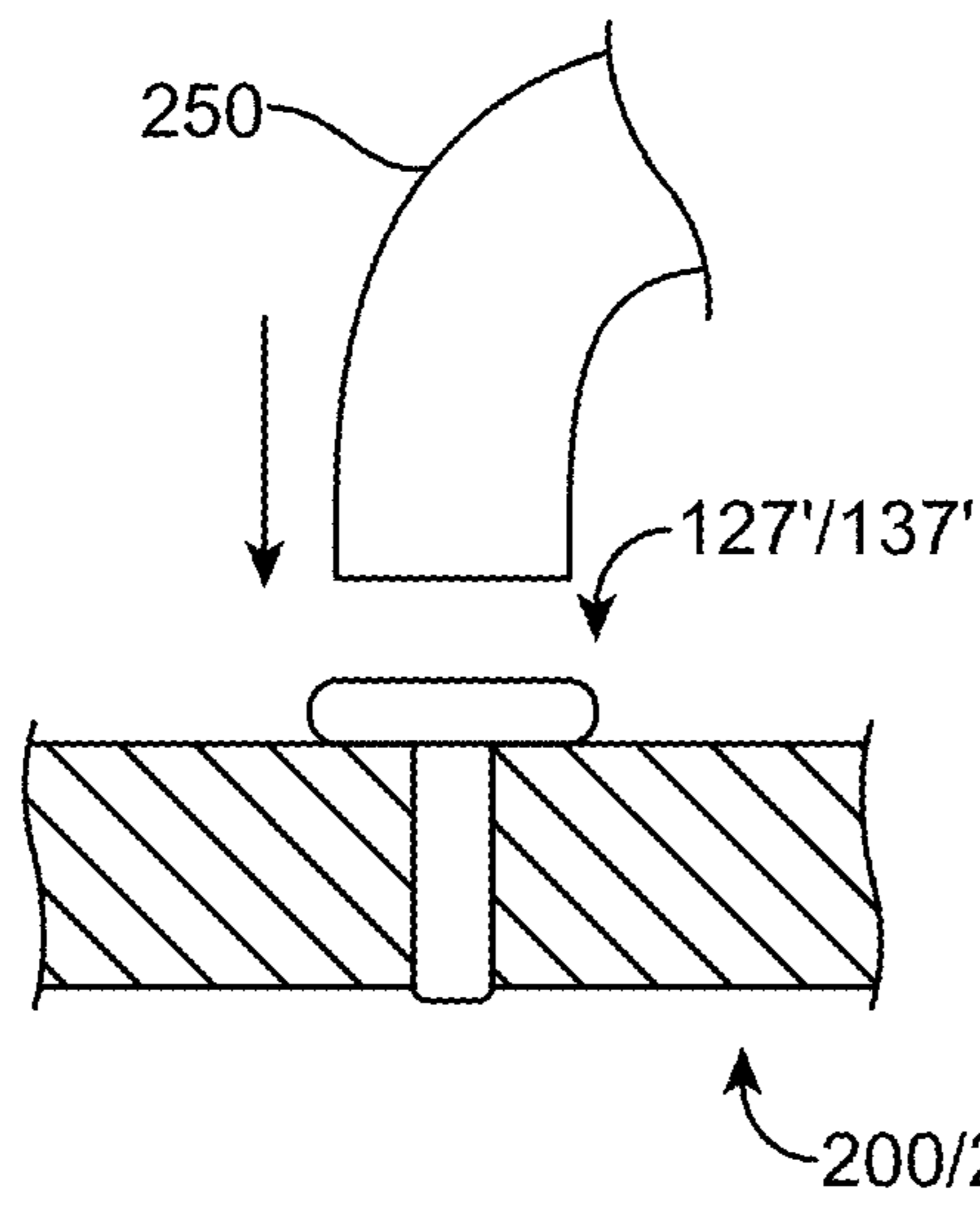


FIG. 16A

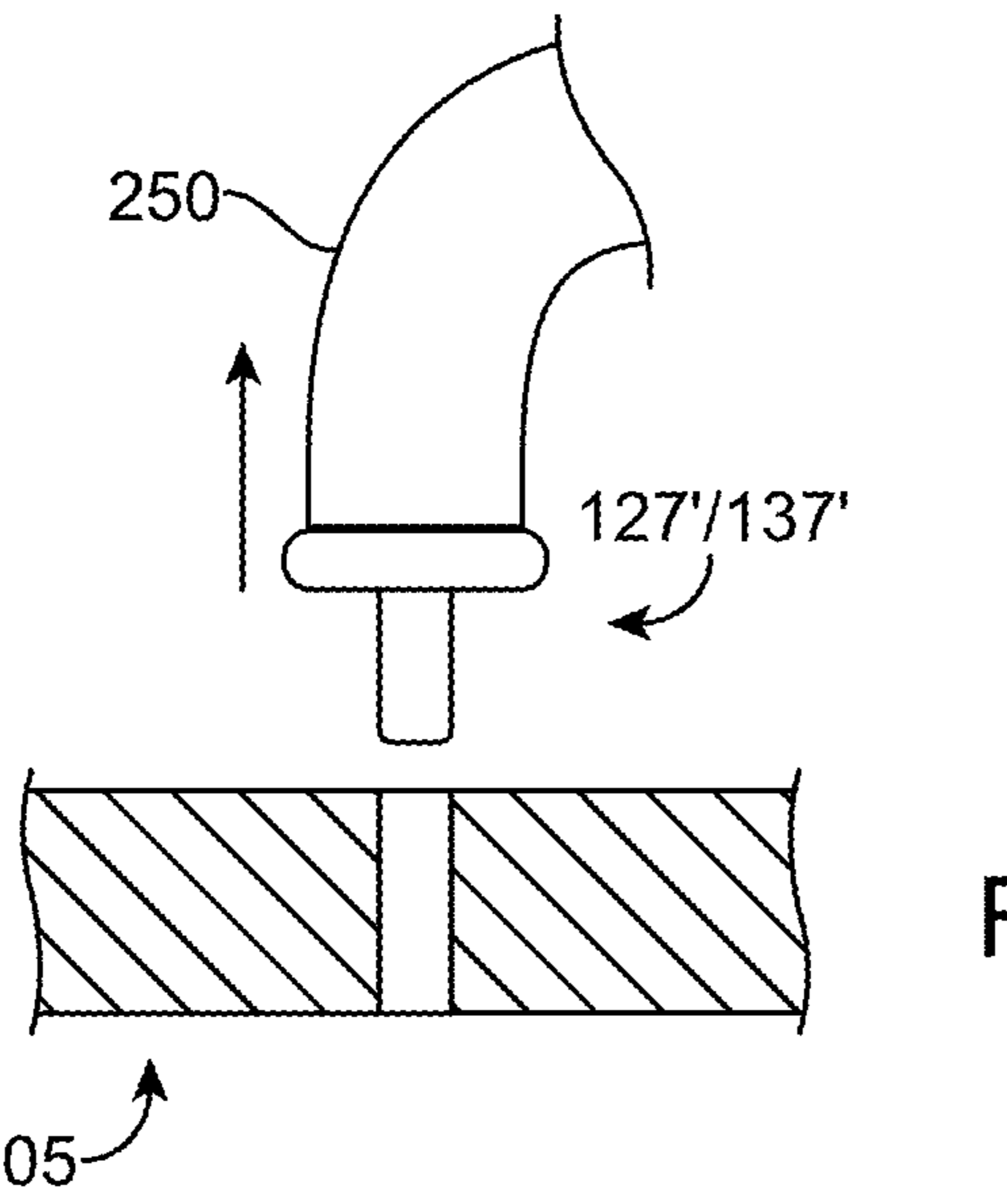


FIG. 16B

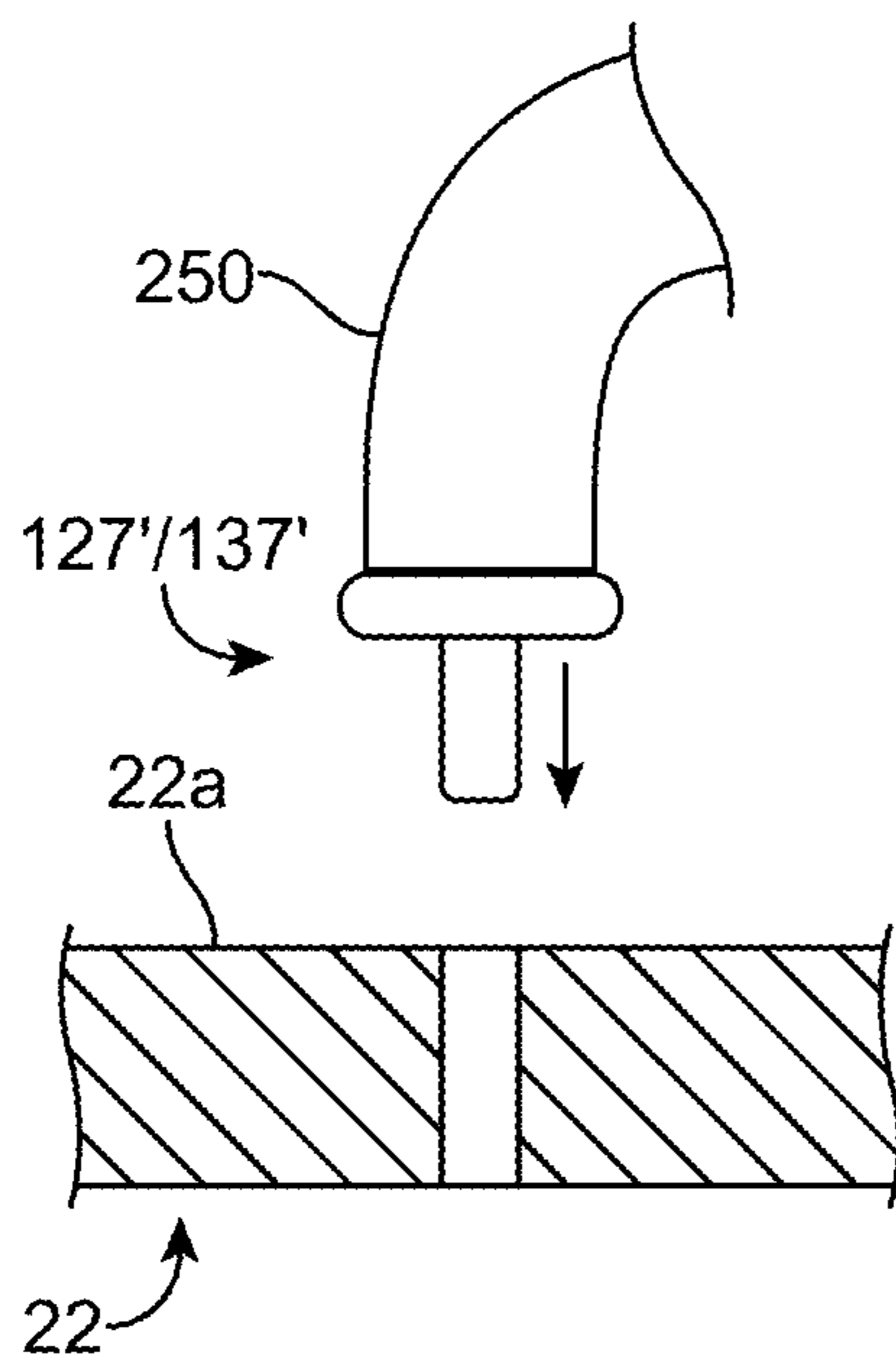


FIG. 16C

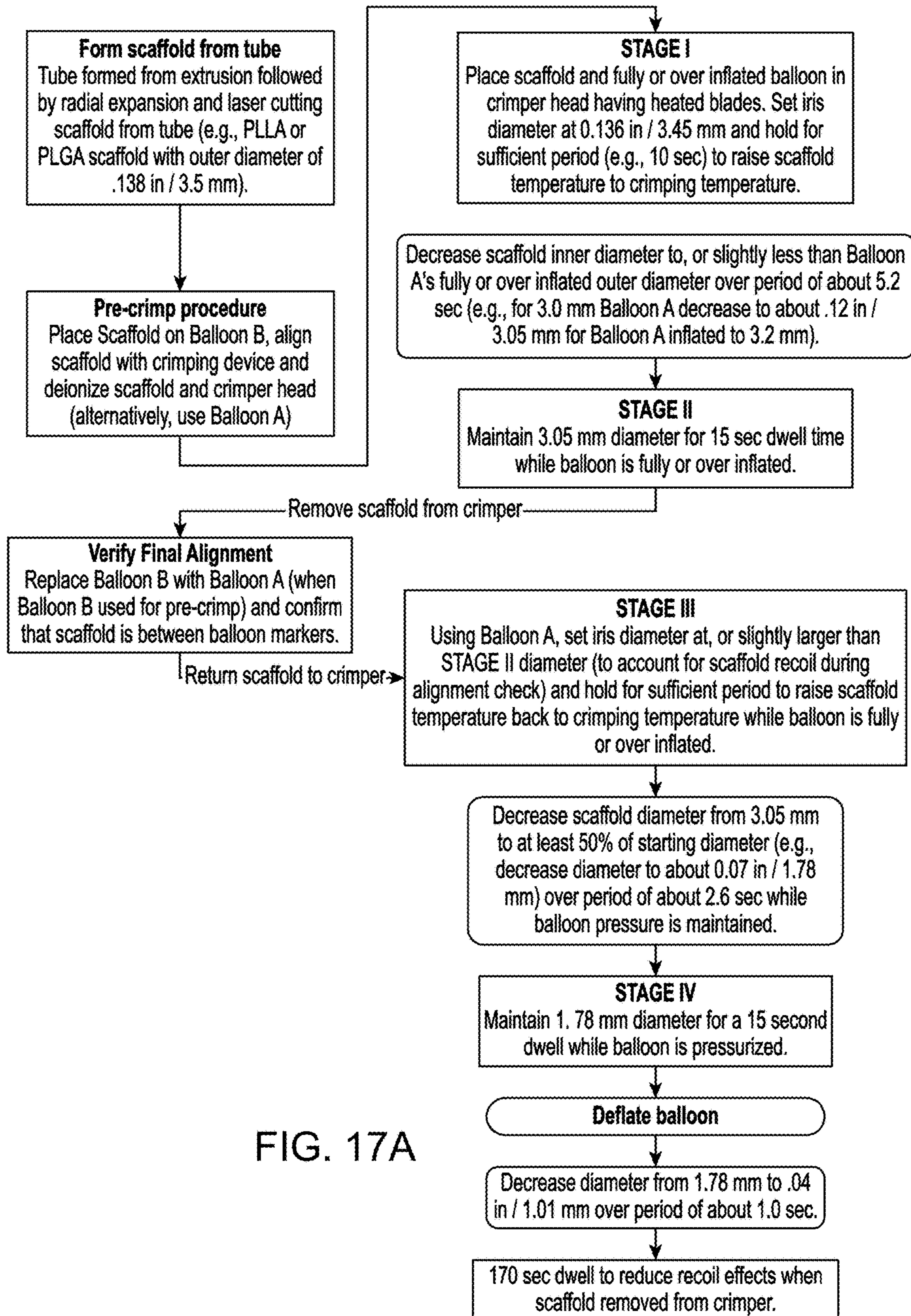


FIG. 17A

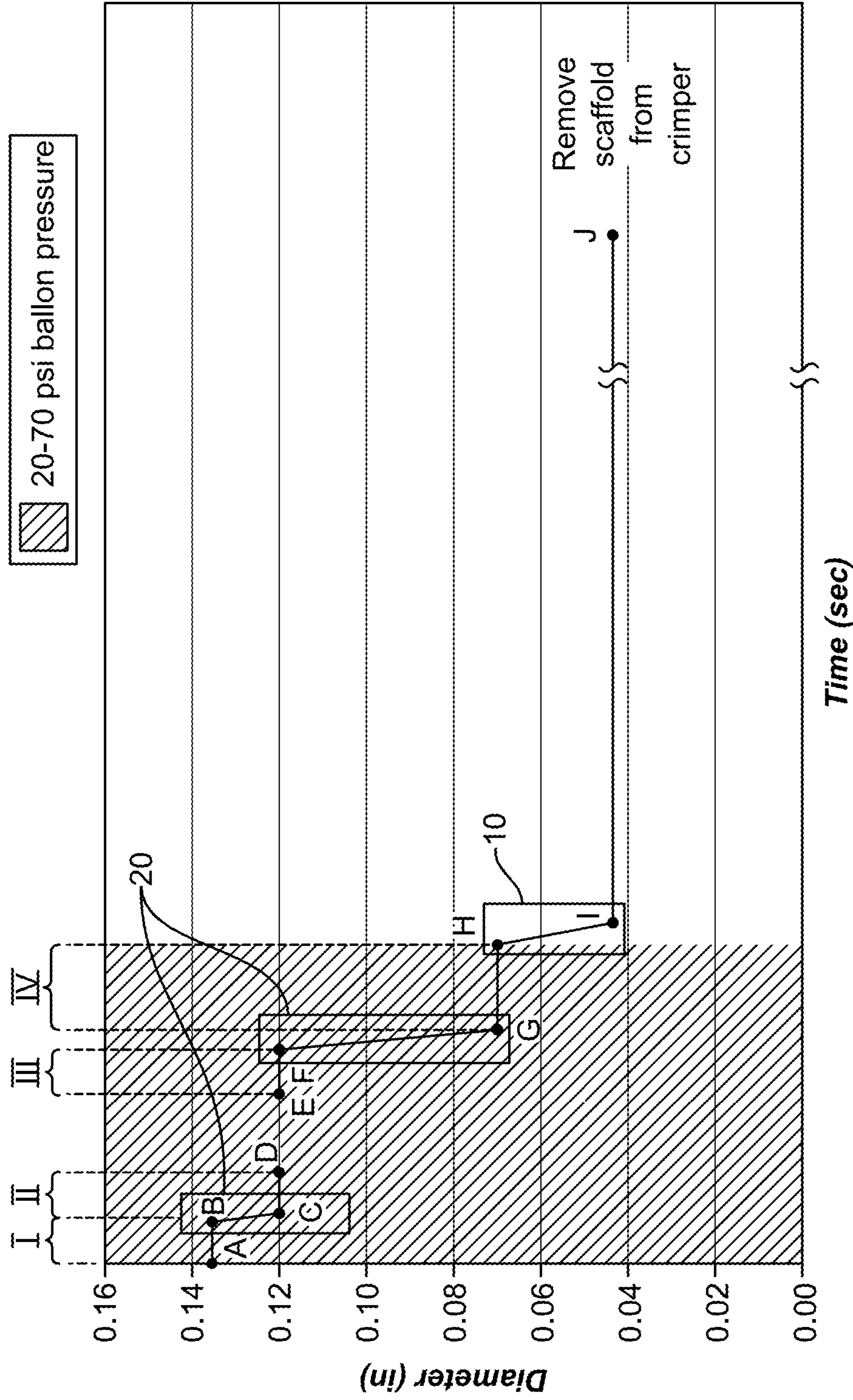


FIG. 17B

## THIN-WALLED SCAFFOLDS HAVING FLEXIBLE DISTAL END

### BACKGROUND OF THE INVENTION

#### Field of the Invention

The present invention relates to bioresorbable scaffolds; more particularly, this invention relates to bioresorbable scaffolds for treating an anatomical lumen of the body.

#### Description of the State of the Art

Radially expandable endoprostheses are artificial devices adapted to be implanted in an anatomical lumen. An “anatomical lumen” refers to a cavity, or duct, of a tubular organ such as a blood vessel, urinary tract, and bile duct. Stents are examples of endoprostheses that are generally cylindrical in shape and function to hold open and sometimes expand a segment of an anatomical lumen. Stents are often used in the treatment of atherosclerotic stenosis in blood vessels. “Stenosis” refers to a narrowing or constriction of the diameter of a bodily passage or orifice. In such treatments, stents reinforce the walls of the blood vessel and prevent restenosis following angioplasty in the vascular system. “Restenosis” refers to the reoccurrence of stenosis in a blood vessel or heart valve after it has been treated (as by balloon angioplasty, stenting, or valvuloplasty) with apparent success.

The treatment of a diseased site or lesion with a stent involves both delivery and deployment of the stent. “Delivery” refers to introducing and transporting the stent through an anatomical lumen to a desired treatment site, such as a lesion. “Deployment” corresponds to expansion of the stent within the lumen at the treatment region. Delivery and deployment of a stent are accomplished by positioning the stent about one end of a catheter, inserting the end of the catheter through the skin into the anatomical lumen, advancing the catheter in the anatomical lumen to a desired treatment location, expanding the stent at the treatment location, and removing the catheter from the lumen.

Scaffolds and stents traditionally fall into two general categories—balloon expanded and self-expanding. The later type expands (at least partially) to a deployed or expanded state within a vessel when a radial restraint is removed, while the former relies on an externally-applied force to configure it from a crimped or stowed state to the deployed or expanded state.

Self-expanding stents are designed to expand significantly when a radial restraint is removed such that a balloon is often not needed to deploy the stent. Self-expanding stents do not undergo, or undergo relatively no plastic or inelastic deformation when stowed in a sheath or expanded within a lumen (with or without an assisting balloon). Balloon expanded stents or scaffolds, by contrast, undergo a significant plastic or inelastic deformation when both crimped and later deployed by a balloon.

In the case of a balloon expandable stent, the stent is mounted about a balloon portion of a balloon catheter. The stent is compressed or crimped onto the balloon. Crimping may be achieved by use of an iris-type or other form of crimper, such as the crimping machine disclosed and illustrated in US 2012/0042501. A significant amount of plastic or inelastic deformation occurs both when the balloon expandable stent or scaffold is crimped and later deployed by a balloon. At the treatment site within the lumen, the stent is expanded by inflating the balloon.

The stent must be able to satisfy a number of basic, functional requirements. The stent (or scaffold) must be capable of sustaining radial compressive forces as it sup-

ports walls of a vessel. Therefore, a stent must possess adequate radial strength. After deployment, the stent must adequately maintain its size and shape throughout its service life despite the various forces that may come to bear on it.

5 In particular, the stent must adequately maintain a vessel at a prescribed diameter for a desired treatment time despite these forces. The treatment time may correspond to the time required for the vessel walls to remodel, after which the stent is no longer needed.

10 Examples of bioresorbable polymer scaffolds include those described in U.S. Pat. No. 8,002,817 to Limon, U.S. Pat. No. 8,303,644 to Lord, and U.S. Pat. No. 8,388,673 to Yang. FIG. 1 shows a distal region of a bioresorbable polymer scaffold designed for delivery through anatomical  
15 lumen using a catheter and plastically expanded using a balloon. The scaffold has a cylindrical shape having a central axis 2 and includes a pattern of interconnecting structural elements, which will be called bar arms or struts 4. Axis 2 extends through the center of the cylindrical shape formed  
20 by the struts 4. The stresses involved during compression and deployment are generally distributed throughout the struts 4 but are focused at the bending elements, crowns or strut junctions. Struts 4 include a series of ring struts 6 that are connected to each other at crowns 8. Ring struts 6 and  
25 crowns 8 form sinusoidal rings 5. Rings 5 are arranged longitudinally and centered on an axis 2. Struts 4 also include link struts 9 that connect rings 5 to each other. Rings 5 and link struts 9 collectively form a tubular scaffold 10 having axis 2 represent a bore or longitudinal axis of the  
30 scaffold 10. Ring 5*d* is located at a distal end of the scaffold. Crown 8 form smaller angles when the scaffold 10 is crimped to a balloon and larger angles when plastically expanded by the balloon. After deployment, the scaffold is subjected to static and cyclic compressive loads from surrounding tissue. Rings 5 are configured to maintain the scaffold's radially expanded state after deployment.

Scaffolds may be made from a biodegradable, bioabsorbable, bioresorbable, or bioerodable polymer. The terms biodegradable, bioabsorbable, bioresorbable, biosoluble or bioerodable refer to the property of a material or stent to degrade, absorb, resorb, or erode away from an implant site. Scaffolds may also be constructed of bioerodable metals and alloys. The scaffold, as opposed to a durable metal stent, is intended to remain in the body for only a limited period of  
45 time. In many treatment applications, the presence of a stent in a body may be necessary for a limited period of time until its intended function of, for example, maintaining vascular patency and/or drug delivery is accomplished. Moreover, it has been shown that biodegradable scaffolds allow for improved healing of the anatomical lumen as compared to metal stents, which may lead to a reduced incidence of late stage thrombosis. In these cases, there is a desire to treat a vessel using a polymer scaffold, in particular a bioabsorbable or bioresorbable polymer scaffold, as opposed to a metal stent, so that the prosthesis's presence in the vessel is temporary.

Polymeric materials considered for use as a polymeric scaffold, e.g. poly(L-lactide) (“PLLA”), poly(D,L-lactide-co-glycolide) (“PLGA”), poly(D-lactide-co-glycolide) or poly(L-lactide-co-D-lactide) (“PLLA-co-PDLA”) with less than 10% D-lactide, poly(L-lactide-co-caprolactone), poly(caprolactone), PLLD/PDLA stereo complex, and blends of the aforementioned polymers may be described, through comparison with a metallic material used to form a stent, in some of the following ways. Polymeric materials typically possess a lower strength to volume ratio compared to metals, which means more material is needed to provide an equiva-

lent mechanical property. Therefore, struts must be made thicker and wider to have the required strength for a stent to support lumen walls at a desired radius. The scaffold made from such polymers also tends to be brittle or have limited fracture toughness. The anisotropic and rate-dependent inelastic properties (i.e., strength/stiffness of the material varies depending upon the rate at which the material is deformed, in addition to the temperature, degree of hydration, thermal history) inherent in the material, only compound this complexity in working with a polymer, particularly, bioresorbable polymers such as PLLA or PLGA.

An additional challenge with using a bioresorbable polymer (and polymers generally composed of carbon, hydrogen, oxygen, and nitrogen) for a scaffold structure is that the material is radiolucent with no radiopacity. Bioresorbable polymers tend to have x-ray absorption similar to body tissue. A known way to address the problem is to attach radiopaque markers to structural elements of the scaffold, such as a strut, bar arm or link. For example, FIG. 1 shows a link element *9d* connecting a distal end ring *5d* to an adjacent ring *5*. The link element *9d* has a pair of holes. Each of the holes holds a radiopaque marker *11*. There are challenges to the use of the markers *11* with the scaffold *10*. There needs to be a reliable way of attaching the markers *11* to the link element *9d* so that the markers *11* will not separate from the scaffold during a processing step like crimping the scaffold to a balloon or when the scaffold is balloon-expanded from the crimped state. These two events—crimping and balloon expansion—are particularly problematic for marker adherence to the scaffold because both events induce significant plastic deformation in the scaffold body. If this deformation causes significant out of plane or irregular deformation of struts supporting, or near to markers the marker can dislodge (e.g., if the strut holding the marker is twisted or bent during crimping the marker can fall out of its hole). A scaffold with radiopaque markers and methods for attaching the marker to a scaffold body is discussed in US20070156230.

There is a need to improve upon the reliability of radiopaque marker securement to a scaffold for a thin-walled scaffold. Related to this need, there is a need to improve upon the performance characteristics of a scaffold, especially thin-walled scaffolds made from a bioresorbable material that must be navigated around tortuous anatomy.

#### SUMMARY OF THE INVENTION

What is disclosed are bioresorbable scaffolds having radiopaque markers and scaffold structure holding such radiopaque material and enabling a reduced a crimped profile ability and/or improved conformability to the catheter when the catheter, upon which the scaffold is mounted, is pushed through tortuous anatomy.

Scaffolds disclosed herein are suited to meet one of, or a combination of, the following objectives:

- (i.) reduced crimped profile for a thin-walled scaffold carrying a radiopaque marker,
- (ii.) securing the marker to the thin-walled scaffold,
- (iii.) reducing strain energy buildup in marker-holding structure when the thin-walled scaffold is being deformed during crimping, balloon expansion at a target vessel site, or delivery of the scaffold to a target site, and
- (iv.) reduced end ring flaring at a distal end of a scaffold for a thin-walled scaffold or scaffold comprising PLLA and having a wall thickness greater than 125 microns.

Being thin-walled, there has been realized through testing a need to modify certain critical areas of the scaffold that had

not previously posed problems when a higher wall thickness was used. An example of a scaffold having a higher wall thickness of 158 microns is described in US 2010/0004735. It has been found that when a significant reduction in wall thickness is made, versus pre-existing bioresorbable scaffolds (e.g., from 160 microns wall thickness to 100 microns wall thickness) the arrangement, shape and dimensions of rings and link elements are, particularly at the distal end of the scaffold, in need of improvement.

A thin-walled scaffold is sought out because there is a clinical need to maintain low profiles for struts exposed in the bloodstream. Blood compatibility, also known as hemocompatibility or thromboresistance, is a desired property for scaffolds and stents. The adverse event of scaffold thrombosis, while a very low frequency event, carries with it a high incidence of morbidity and mortality. To mitigate the risk of thrombosis, dual anti-platelet therapy is administered with all coronary scaffold and stent implantation. This is to reduce thrombus formation due to the procedure, vessel injury, and the implant itself. Scaffolds and stents are foreign bodies and they all have some degree of thrombogenicity. The thrombogenicity of a scaffold refers to its propensity to form thrombus and this is due to several factors, including strut thickness, strut width, strut shape, total scaffold surface area, scaffold pattern, scaffold length, scaffold diameter, surface roughness and surface chemistry. Some of these factors are interrelated. Low strut profile also leads to less neointimal proliferation as the neointima will proliferate to the degree necessary to cover the strut. As such coverage is a necessary step to complete healing. Thinner struts are believed to endothelialize and heal more rapidly.

According to the various aspects of the invention, there is a thin-walled scaffold (“scaffold”), medical device, method for making such a scaffold, method of making a marker, attaching a marker to a strut, link or bar arm of a scaffold, method for crimping, or method for assembly of a medical device comprising such a scaffold having one or more, or any combination of the following things (1) through (15):

- (1) the scaffold crimped to a theoretical minimum crimp diameter (D-min);
- (2) the scaffold wall thickness is less than 125 microns, less than 100 microns, about 100 microns or about 93 microns;
- (3) a wavelength of a ring connected to a marker link is greater than a wavelength of another ring not connected to the marker link, and/or the wavelength of the ring connected to the marker length has a different length wavelengths;
- (4) a distance from a W crown to an adjacent U crown is higher than a distance from a Y crown to an adjacent U crown;
- (5) the scaffold is made from a tube comprising poly(L-lactide);
- (6) the scaffold crimped to a balloon, wherein the scaffold comprises a crimped state as shown and described in connection with FIG. 4D, 6A or 7A;
- (7) a method of crimping any of the scaffolds described in connection with FIG. 3, 4, 5, 6, or 7;
- (8) a method for attaching a radiopaque marker to the scaffold;
- (9) a marker link having the dimensions shown and described in connection with FIG. 2C.
- (10) a ring has *n* crests where *n* is more than 5, or more than 6 and less than or equal to 12.
- (11) the ring has 2 wavelengths of a first size and *n*-3 wavelengths of a second size, the first size being greater than the second size;



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- (12) a ring connected to a marker link at a W crown has a first width and the adjoining ring connected to the marker link has a second width, greater than the first width;
- (13) a ring connected to a marker link at a W crown has a wider flat portion or than a Y crown flat portion connected to the marker link and adjoining to the first ring.
- (14) a first distance between rings adjoining by a marker link is greater than a second distance between rings not joined by marker links; and
- (15) a first distance between rings adjoining by a non-linear link marker link is greater than a second distance between rings not joined by the non-linear marker link.
- (16) D-min is about 1 mm or less than 1 mm
- (17) An aspect ratio (AR) of the marker link for a thin-walled scaffold is between about 4 and 5, or about 4.5, where AR is defined as the maximum width of the marker link divided by the wall thickness at the marker link.
- (18) A first wavelength or  $\frac{1}{2}$  wavelength of a first ring is greater than a second wavelength or  $\frac{1}{2}$  wavelength of an adjoining second ring.
- (19) A first wavelength or  $\frac{1}{2}$  wavelength between two crests of a ring are different from a second wavelength between two other crests of the same ring.
- (20) A ring is sinusoidal or zig-zag.
- (21) A half wavelength measured from a W crown formed between a marker link and a first ring is about 15% higher than a half wavelength measured from a Y crown formed between the marker link and a second ring adjoining to the first ring; for a marker link that has a maximum width about 200% higher than the maximum width for a non-marker link.
- (22) A wavelength measured from a W crown formed between a marker link and a first ring is between about 5% and 10% higher than the wavelength measured from a Y crown formed between the marker link and a second ring adjoining to the first ring; for a marker link that has a maximum width about 200% higher than the maximum width for a non-marker link.
- (23) A wavelength measured from a W crown/crest formed between a marker link and a ring is between about 5% and 10% higher than the wavelength measured between other crests of the ring; for a marker link that has a maximum width about 200% higher than the maximum width for a non-marker link.
- (24) A crown width B1 that is greater than a crown width B2; for example, a crown width B1 that is about 350% to about 400% greater than a crown width B2;
- (25) A ring spacing A12 between a first ring and a second ring is greater than a ring spacing A23 between a second ring and a third ring; for example A12 is about 40% greater than A23.
- (26) A link is a straight link or a non-linear link; for example link 20 and link 636.
- (27) The length c1 that is about 36% higher than the length c2 for a marker link.
- (28) The length c1 that is about 36% higher than the length c2 for a non-linear link.
- (29) A medical device, comprising: a thin-walled scaffold having a network of rings interconnected by links, wherein each ring has a plurality of crests, wherein a crest is one of a U crown, Y crown and a W crown, each ring extends circumferentially in an undulating fashion along a vertical axis (B-B) perpendicular to a longitudinal axis (A-A); and a marker link extending between

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- a first ring and a second ring of the rings, the marker link including a structure having a hole and a radiopaque material is contained within the hole; wherein the marker link forms with the first ring a first ring W crown and with the second ring a second ring Y crown, wherein a  $\frac{1}{2}$  wave length of the first ring measured from the first ring W crown to an adjacent U crown of the first ring is greater than a  $\frac{1}{2}$  wave length of the second ring measured from the second ring Y crown to an adjacent U crown of the second ring.
- (30) The medical device of (29), in combination with one or more of, or any combination of items (a) through (g):
- (a) wherein a length of the marker link is greater than a length of a link connecting the second ring to a third ring adjoining with the second ring;
- (b) wherein the marker link includes a first link portion extending from the structure to the first ring W crown and a second link portion extending from the second ring Y crown to the structure, wherein a width of the first link portion is greater than a width of the second link portion;
- (c) wherein a length of the first length portion is less than a length of the second link portion;
- (d) wherein the structure includes a first and second holes, each containing the radiopaque material, wherein the first and second holes are aligned parallel to the axis A-A;
- (e) wherein the first ring includes a first, second and third crest, the first crest corresponding to the first ring W crown, the second crest is adjacent the first crest and the third crest is adjacent the second crest, wherein a second wavelength extending from the second crest to the third crest is less than a first wavelength extending from the first crest to the second crest;
- (f) wherein a flat portion of the first ring W crown is greater than a flat portion of a third ring W crown of a third ring adjoining with the second ring, and/or a flat portion of a fourth W crown of the first ring; and
- (g) wherein a wavelength of the first ring forming the first ring W crown is longer than a wavelength of the second ring forming the second ring Y crown.
- (31) A medical device, comprising: a thin-walled scaffold having proximal and distal end portions formed by a network of rings interconnected by links, wherein each ring has a plurality of crests, wherein a crest is one of a U crown, Y crown and W crown, and each ring extends circumferentially in an undulating fashion along a vertical axis (B-B) perpendicular to a longitudinal axis (A-A); a marker link extending between a first ring and a second ring of the rings, the marker link including a structure having a hole and a radiopaque material is contained within the hole; wherein the marker link forms with the first ring a first ring W crown and with the second ring a second ring Y crown, the first ring W crown corresponding to a first crest; and wherein a first wave length of the first ring measured from the first crest to a second crest of the first ring, adjacent the first crest, is greater than a second wave length of the first ring measured from the second crest to an adjacent third crest of the first ring.
- (32) The medical device of (31), in combination with one or more of, or any combination of items (a) through (c):
- (a) wherein the first ring has n crests and n-1 wavelengths where n is at least 6 and not more than 12, and wherein a first and second wavelength measured from the first crest and above and below, respec-

- tively, the first crest is greater than the remaining n-3 wavelengths measured between the n-1 crests;
- (b) wherein all of the remaining n-3 wavelengths have the same length;
- (c) wherein a length of the marker link is about equal to a length of a link connecting the second ring to a third ring.
- (33) A medical device, comprising: a balloon catheter having a balloon, the balloon having a distal balloon end and a proximal balloon end; a thin-walled scaffold crimped to the balloon, the scaffold having proximal and distal end portions formed by a network of rings interconnected by links, wherein each ring has a plurality of crests, wherein a crest is one of a U crown, Y crown and W crown, and each ring extends circumferentially in an undulating fashion along a vertical axis (B-B) perpendicular to a longitudinal axis (A-A); a marker link extending between a first ring and a second ring of the rings, the marker link including a structure having a hole and a radiopaque material is contained within the hole; wherein the marker link forms with the first ring a first ring W crown and with the second ring a second ring Y crown, the first ring W crown corresponding to a first crest; wherein a first wave length of the first ring measured from the first crest to a second crest adjacent the first crest is greater than a second wave length of the first ring measured from the second crest to a third crest adjacent the second crest; wherein the thin-walled scaffold has an outer diameter of about D-min; and wherein  $D\text{-min}=(1/\pi)\times[(n\times\text{strut\_width})+(m\times\text{link\_width})]+2*t$ .
- (34) The medical device of (33), in combination with one or more of, or any combination of items (a) through (d):
- (a) wherein a maximum width of the structure measured along axis B-B is greater than a maximum width of a link extending between the second ring and a third ring adjoined to the second ring;
- (b) wherein the marker link includes a first link portion extending from the structure to the W crown and a second link structure extending from the Y crown to the structure, wherein a width of the first link portion is greater than a width of the second link portion;
- (c) wherein a length of the first link portion is less than a length of the second link portion; and
- (d) wherein the structure includes a first and second hole containing the radiopaque material, wherein the first and second holes are aligned parallel to the axis A-A.
- (35) A method for making a medical device, comprising: using a tube comprising poly(L-lactide); forming a thin-walled scaffold pattern from the tube, the scaffold having proximal and distal end portions formed by a network of rings interconnected by links, wherein each ring has a plurality of crests, wherein a crest is one of a U crown, Y crown and W crown, and each ring extends circumferentially in an undulating fashion along a vertical axis (B-B) perpendicular to a longitudinal axis (A-A); the thin-walled scaffold including at least one marker link extending between a first ring and an adjoined second ring of the rings, the marker link including a structure having a hole; placing a radiopaque material in the marker hole, wherein the hole has a first size before the material placement and a second size, greater than the first size after material placement, and wherein the structure has a width measured along axis B-B; and crimping the thin-walled scaffold to a balloon catheter; wherein the thin-walled

- scaffold is crimped to about a theoretical-minimum crimped diameter (D-min); and wherein neither of the crowns adjacent and above and below the structure overlaps the structure.
- (36) The medical device of (35), in combination with one or more of, or any combination of items (a) through (c):
- (a) wherein the marker link forms with a first ring a first ring W crown and with the second ring a second ring Y crown, the first ring W crown corresponding to a first crest, and wherein a first wave length of the first ring measured from the first crest to a second crest adjacent the first crest is greater than a second wave length of the first ring measured from the second crest to an adjacent third crest;
- (b) wherein the marker link forms with a first ring the first ring W crown and with the second ring a second ring Y crown, a first and second U crown is adjacent and above and below, respectively, the first ring W crown, a first strut extends from the first ring W crown to the first U crown and a second strut extends from the first ring W crown to the second U crown, wherein a distance between the first U crown and the second U crown, or a distance between the second strut to the first strut is greater than or equal to a maximum width of the marker structure measured along axis B-B; and
- (c) wherein the width of the marker structure is greater than a maximum width of a link connecting the second ring to an adjacent third ring.
- (37) A medical device, comprising: a thin-walled scaffold having proximal and distal end portions formed by a network of rings interconnected by links of the thin-walled scaffold, wherein each ring has a plurality of crowns, including U crowns and at least one of Y crowns and W crowns, each ring extends circumferentially in an undulating fashion along a vertical axis (B-B) perpendicular to a longitudinal axis (A-A); the proximal end portion includes an outermost proximal ring adjoined to a first proximal ring by first proximal links, and the first proximal ring is adjoined to a second proximal ring by second proximal links; the distal end portion includes an outermost distal ring adjoined to a first distal ring by first distal links, and the first distal ring is adjoined to a second distal ring by second distal links; wherein—the first proximal links include a proximal marker link comprising a proximal hole containing a radiopaque material, and—the first distal links are devoid of a link holding the radiopaque material.
- (38) The medical device of (37), in combination with one or more of, or any combination of items (a) through (i):
- (a) wherein the outermost proximal ring is adjoined to the first proximal ring only by the first proximal links, wherein two of which extend parallel to axis A-A and have a constant cross-sectional moment of inertia;
- (b) wherein the outermost distal ring is adjoined to the first distal ring only by the first distal links, each of which are non-linear link struts;
- (c) wherein the proximal marker link has a first end and a second end, the first end forming one of a W crown and a Y crown with the outermost proximal ring and the other of the W crown and Y crown with the first proximal ring;
- (d) wherein the first distal ring and second distal ring are adjoined by a distal marker link;

- (e) wherein the distal marker link includes a structure that circumscribes two holes and the first and second distal rings are adjoined additionally by one or two marker links;
- (f) wherein the distal marker link has a first end and a second end, the first end forming one of a W crown and Y crown with the first distal ring and the other of the W crown and Y crown with the second distal ring, wherein the W crown is wider than the Y crown;
- (g) wherein the proximal marker link further comprises: a rim substantially circumscribing the hole and defining a hole wall and a strut rim, wherein a distance between the wall and rim is D; a radiopaque marker disposed in the hole, the marker including a head having a flange disposed on the rim; wherein the flange has a radial length of between  $\frac{1}{2} D$  and less than D; wherein the thin-walled scaffold thickness (t) is related to a length (L) of the marker measured between an abluminal and luminal surface of the marker by  $1.1 \leq (L/t) \leq 1.8$ ;
- (h) wherein the distal marker link forms with the first distal ring one of the W crown and a Y crown with the second distal ring, wherein a  $\frac{1}{2}$  wave length of the ring having the W crown, measured from the W crown to a first adjacent crown is greater than a  $\frac{1}{2}$  wave length of the ring having the Y crown; and
- (i) wherein a length of the first proximal links is less than a length of the first distal links, and/or a length of the second distal links is less than the first distal links length.
- (39) A medical device, comprising: a balloon catheter having a balloon, the balloon having a distal balloon end and proximal balloon end; a thin-walled scaffold crimped to the balloon, the thin-walled scaffold having proximal and distal end portions formed by a network of rings interconnected by links of the thin-walled scaffold, wherein each ring has a plurality of crowns, including U crowns and at least one of Y crowns and W crowns, each ring extends circumferentially in an undulating fashion along a vertical axis (B-B) perpendicular to a longitudinal axis (A-A); the proximal end portion, crimped to the proximal balloon end, includes an outermost proximal ring adjoined to a first proximal ring by first proximal links, and the first proximal ring is adjoined to a second proximal ring by second proximal links; the distal end portion, crimped the distal balloon end, includes an outermost distal ring adjoined to a first distal ring by first distal links, and the first distal ring is adjoined to a second distal ring by second distal links; wherein—the first proximal links include a proximal marker link comprising a proximal hole containing a radiopaque material,—the first distal links are devoid of a link holding the radiopaque material, and—the first distal links comprise non-linear links; wherein the thin-walled scaffold has an outer diameter of about D-min; and Wherein  $D\text{-min} = (1/\pi) \times [(n \times \text{strut\_width}) + (m \times \text{link\_width})] + 2 * t$ .
- (40) The medical device of (39), in combination with one or more of, or any combination of items (a) through (i):
- (a) wherein the outermost proximal ring is adjoined to the first proximal ring only by the first proximal links, each of which extend parallel to axis A-A and have a constant cross-sectional moment of inertia;
- (b) wherein the non-linear links are U-shaped links;
- (c) wherein the proximal marker link has a first and second end, the first end forming one of a W crown

- and Y crown with the outermost proximal ring and the other of the W crown and Y crown with the first proximal ring, and wherein the marker link includes structure circumscribing holes;
- (d) wherein a first link portion of the proximal marker link extends from the W-crown to the structure and a second link portion of the proximal marker link extends from the Y-crown to the structure, wherein a first link portion length is greater than a second link portion length;
- (e) wherein the first link portion length is about equal to the sum of twice a ring width and a length of a strut extending between a U crown and a U, Y or W crown of the ring.
- (f) wherein the non-linear link has a first and second end, the first end forming one of a W crown and Y crown with the outermost proximal ring and the other of a the W crown and Y crown with the first proximal ring, and wherein the non-linear link includes a U-shaped structure between the W crown and Y crown;
- (g) wherein a first link portion of the proximal U-shaped link extends from the W-crown to the U-shaped structure and a second link portion of the proximal marker link extends from the Y-crown to the structure, wherein a first link portion length is greater than a second link portion length;
- (h) wherein the first link portion length is about equal to the sum of twice a ring width and a length of a strut extending between a U crown and a U, Y or W crown crowns of a ring; and
- (i) wherein the distal marker link has a first and second end, the first end forming one of a W crown and Y crown with the first distal ring and the other of the W crown and Y crown with the second distal ring.
- (41) A medical device, comprising: a thin-walled scaffold having proximal and distal end portions formed by a network of rings interconnected by links of the thin-walled scaffold, wherein each ring has a plurality of crowns, including U crowns and at least one of Y crowns and W crowns, each ring extends circumferentially in an undulating fashion along a vertical axis (B-B) perpendicular to a longitudinal axis (A-A); the proximal end portion includes an outermost proximal ring adjoined to a first proximal ring by first proximal links, and the first proximal ring is adjoined to a second proximal ring by second proximal links; the distal end portion includes an outermost distal ring adjoined to a first distal ring by first distal links, and the first distal ring is adjoined to a second distal ring by second distal links; wherein the first proximal links include a proximal marker link comprising a pair of proximal holes containing a radiopaque material, wherein the proximal holes are aligned along axis A-A, and the first distal links include a distal marker link comprising a pair of distal holes containing a radiopaque material, wherein the distal holes are aligned along axis B-B.
- (42) The medical device of (41), in combination with one or more of, or any combination of items (a) through (i):
- (a) wherein the outermost proximal ring is adjoined to the first proximal ring only by the first proximal links, wherein two of which extend parallel to axis A-A and have a constant cross-sectional moment of inertia;
- (b) wherein the outermost distal ring is adjoined to the first distal ring only by the first distal marker link and non-linear link struts;

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- (c) wherein the proximal marker link has a first and second end, the first end forming one of a W crown and Y crown with the outermost proximal ring and the other of the W crown and Y crown with the first proximal ring;
- (d) wherein a W crown width formed by the first end is greater than a Y crown width formed by the second end, such that a wavelength of the ring forming the W crown is longer than a wavelength of the ring forming the Y crown;
- (e) wherein the distal marker link has a first and second end, the first end forming one of a W crown and Y crown with the outermost distal ring and the other of the W crown and Y crown with the first distal ring;
- (f) wherein the distal marker link has a first link portion extending from the holes to the W crown and a second link portion extending from the holes to the Y crown, wherein a length of the first link portion is longer than a length of the second link portion;
- (g) wherein the proximal marker link further comprises: a rim substantially circumscribing the hole and defining a hole wall and a strut rim, wherein a distance between the wall and rim is D; a radiopaque marker disposed in the hole, the marker including a head having a flange disposed on the rim; wherein the flange has a radial length of between  $\frac{1}{2} D$  and less than D; wherein the thin-walled scaffold thickness (t) is related to a length (L) of the marker measured between an abluminal and luminal surface of the marker by  $1.1 \leq (L/t) \leq 1.8$ ;
- (h) wherein the radiopaque material is contained within a hole and the radiopaque material has a shape of a frustum; and
- (i) wherein the hole comprises a first and second opening located on, respectively, a first and second side of the marker link, wherein the first opening is larger than the second opening and the frustum is substantially flush with the first and second openings.
- (43) A medical device, comprising: a balloon catheter having a balloon, the balloon having a distal balloon end and a proximal balloon end; a thin-walled scaffold crimped to the balloon, the thin-walled scaffold having proximal and distal end portions formed by a network of rings interconnected by links of the thin-walled scaffold, wherein each ring has a plurality of crowns, including U crowns and at least one of Y crowns and W crowns, each ring extends circumferentially in an undulating fashion along a vertical axis (B-B) perpendicular to a longitudinal axis (A-A); the proximal end portion, crimped to the proximal balloon end, includes an outermost proximal ring adjoined to a first proximal ring by first proximal links, and the first proximal ring is adjoined to a second proximal ring by second proximal links; the distal end portion, crimped the distal balloon end, includes an outermost distal ring adjoined to a first distal ring by first distal links, and the first distal ring is adjoined to a second distal ring by second distal links; wherein (1) the first proximal links include a proximal marker link comprising a structure extending parallel to axis A-A and containing a radiopaque material, (2) the first distal links include a distal marker link comprising a structure, and extending parallel to axis B-B and containing the radiopaque material; wherein the thin-walled scaffold has an outer diameter of about D-min; and wherein  $D\text{-min} = (1/\pi) \times [(n \times \text{strut\_width}) + (m \times \text{link\_width})] + 2 * t$ .

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- (44) The medical device of (43), in combination with one or more of, or any combination of items (a) through (i):
- (a) wherein the outermost proximal ring is adjoined to the first proximal ring only by the first proximal links, each of which extend parallel to axis A-A and have a constant cross-sectional moment of inertia;
- (b) wherein the first distal links include non-linear links;
- (c) wherein the proximal marker link has a first and second end, the first end forming one of a W crown and Y crown with the outermost proximal ring and the other of the W crown and Y crown with the first proximal ring, and wherein the marker link includes structure circumscribing holes;
- (d) wherein a first link portion of the proximal marker link extends from the W crown to the structure and a second link portion of the proximal marker link extends from the Y crown to the structure, wherein a length of the first link portion is greater than a length of the second link portion.
- (e) wherein the first link portion length is about equal to the sum of twice a ring width and a length of a strut extending between a U crown and a Y, U or W crown of a ring;
- (f) wherein the first distal links comprise a non-linear link having a first and second end, the first end forming one of a W crown and a Y crown with the outermost proximal ring and the other of the W crown and Y crown with the first proximal ring, and wherein the non-linear link includes a U-shaped structure between the W crown and Y crown;
- (g) wherein a first link portion of the non-linear link extends from the W crown to the U-shaped structure, and a second link portion of the non-linear link extends from the Y crown to the U-shaped structure, wherein a length of the first link portion length is greater than a length of the second link portion;
- (h) wherein the first link portion length is about equal to the sum of twice a ring width and a length of a strut extending between a U crown and a Y, U or W crown of a ring; and
- (i) wherein the holes of the distal marker link are between and not overlapping or under-lapping a U-crown adjacent a W-crown of the outermost distal ring and a U crown adjacent a Y crown of the first distal ring.

## INCORPORATION BY REFERENCE

All publications and patent applications mentioned in the present specification are herein incorporated by reference to the same extent as if each individual publication or patent application was specifically and individually indicated to be incorporated by reference. To the extent there are any inconsistent usages of words and/or phrases between an incorporated publication or patent and the present specification, these words and/or phrases will have a meaning that is consistent with the manner in which they are used in the present specification.

## BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1 is a perspective view of a portion of a prior art scaffold. The scaffold is shown in a crimped state (balloon not shown).

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FIG. 2 is a top partial view of a scaffold showing a marker link that has holes for retaining a radiopaque material and connects adjoining rings.

FIG. 2A is a reproduction of FIG. 2 showing additional dimensional characteristics and/or feature of link for holding two markers.

FIG. 2B shows an alternative embodiment of a marker link.

FIG. 2C is another reproduction of FIG. 2 with markers attached to the link.

FIG. 3 shows distal and proximal end portions of a scaffold according to one embodiment. The end portions include the marker link of FIG. 2 connecting rings.

FIG. 3A shows section IIIA of the scaffold of FIG. 3.

FIG. 3B shows section IIIB of the scaffold of FIG. 3.

FIG. 3C shows the scaffold of FIG. 3 in a crimped state.

FIG. 3D shows the scaffold of FIG. 3 crimped to a balloon of a balloon catheter.

FIG. 4 shows end portions of a scaffold according to another embodiment. The end portions include a link connecting adjoining rings and containing a marker. The rings have a W crown formed in-part by the marker link. The W crown is modified to accommodate a marker structure.

FIG. 4A shows section IVA of the scaffold of FIG. 4.

FIG. 4B shows the distal end ring of the scaffold in FIG. 3 with a distal end ring of the scaffold of FIG. 4 in phantom, to show differences between the two rings.

FIG. 4C shows section IVC of the scaffold of FIG. 4.

FIG. 4D shows the scaffold of FIG. 4 in a crimped state.

FIG. 5 is a partial view of a scaffold distal end portion according to another embodiment.

FIG. 6 shows end portions of a scaffold according to another embodiment. The distal end portion is different from the proximal end portion. Non-linear link struts connect the outermost distal ring to an inner ring and a marker link is between inner rings at the distal end portion.

FIG. 6A is partial view of the scaffold of FIG. 6 in a crimped state.

FIG. 6B is an image of a catheter distal end in a bent configuration showing a distal ring of a scaffold flaring or protruding outward from the balloon distal end.

FIG. 6C is an image of a catheter distal end in a bent configuration showing the distal ring of a scaffold according to FIG. 6. The distal end ring no longer flares outward when the catheter is placed in bending.

FIG. 7 shows end portions of a scaffold according to another embodiment. The proximal end portion is different from the distal end portion. Non-linear link struts and a modified marker link connects the outermost distal ring to an inner ring.

FIG. 7A is a partial view of the scaffold of FIG. 7 in a crimped state.

FIG. 7B is a partial view of the scaffold of FIG. 7 taken at section VII in FIG. 7.

FIG. 7C is an image of a catheter distal end in a bent configuration showing the distal ring of a scaffold according to FIG. 7. The distal end ring does not flare outward when the catheter is placed in bending.

FIGS. 8A-8B show a side and top view, respectively, of a marker according to another embodiment.

FIG. 9 is a cross-sectional view of a link having a hole and the marker of FIGS. 8A-8B embedded in the hole.

FIG. 10 is a side-cross section of a first die for forming a rivet marker from a radiopaque bead.

FIG. 11A is a side view of a rivet marker formed using the die of FIG. 10.

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FIG. 11B is a side cross-section of a scaffold strut with the marker of FIG. 11A engaged with a hole of the strut and after a forming process deforms the marker to make upper and lower rims retaining the marker in the hole.

FIG. 12 is a side-cross section of a second die for forming a rivet marker from a radiopaque bead.

FIG. 13 is a side view of a rivet marker formed using the die of FIG. 12.

FIGS. 14A, 14B and 14C are perspective views depicting aspects of a process for deforming a rivet lodged in a scaffold hole to enhance engagement with the hole to resist dislodgment forces associated with crimping or balloon expansion.

FIG. 15A is a side cross-sectional view of a deformed rivet marker and scaffold hole following the process described in connection with FIGS. 14A-14C.

FIG. 15B is a view of the deformed marker illustrated in FIG. 15A.

FIG. 15C is a side cross-sectional view of the rivet and marker hole of FIG. 15A following a heating step.

FIGS. 16A through 16C illustrate steps associated with removing a formed rivet marker from a die and placing the rivet marker into the hole of the scaffold.

FIGS. 17A and 17B describe a process for crimping a thin-walled scaffold according to the disclosure.

## DETAILED DESCRIPTION

In the description like reference numbers appearing in the drawings and description designate corresponding or like elements among the different views.

For purposes of this disclosure, the following terms and definitions apply:

The terms “about,” “approximately,” “generally,” or “substantially” mean 30%, 20%, 15%, 10%, 5%, 4%, 3%, 2%, 1.5%, 1%, between 1-2%, 1-3%, 1-5%, or 0.5%-5% less or more than, less than, or more than a stated value, a range or each endpoint of a stated range, or a one-sigma, two-sigma, three-sigma variation from a stated mean or expected value (Gaussian distribution). For example, d1 about d2 means d1 is 30%, 20%, 15%, 10%, 5%, 4%, 3%, 2%, 1.5%, 1%, 0% or between 1-2%, 1-3%, 1-5%, or 0.5%-5% different from d2. If d1 is a mean value, then d2 is about d1 means d2 is within a one-sigma, two-sigma, or three-sigma variance or standard deviation from d1.

It is understood that any numerical value, range, or either range endpoint (including, e.g., “approximately none”, “about none”, “about all”, etc.) preceded by the word “about,” “approximately,” “generally,” or “substantially” in this disclosure also describes or discloses the same numerical value, range, or either range endpoint not preceded by the word “about,” “approximately,” “generally,” or “substantially.”

The “glass transition temperature,” TG, is the temperature at which the amorphous domains of a polymer change from a brittle vitreous state to a solid deformable or ductile state at atmospheric pressure. This application defines TG and methods to find TG, or TG-low (the lower end of a TG range) for a polymer in the same way as in U.S. application Ser. No. 14/857,635.

A “stent” means a permanent, durable or non-degrading structure, usually comprised of a non-degrading metal or metal alloy structure, generally speaking, while a “scaffold” means a temporary structure comprising a bioresorbable or biodegradable polymer, metal, alloy or combination thereof and capable of radially supporting a vessel for a limited period of time, e.g., 3, 6 or 12 months following implanta-

tion. It is understood, however, that the art sometimes uses the term “stent” when referring to either type of structure.

“Inflated diameter” or “expanded diameter” refers to the inner diameter or the outer diameter the scaffold attains when its supporting balloon is inflated to expand the scaffold from its crimped configuration to implant the scaffold within a vessel. The inflated diameter may refer to a post-dilation balloon diameter which is beyond the nominal balloon diameter, e.g., a 6.5 mm balloon (i.e., a balloon having a 6.5 mm nominal diameter when inflated to a nominal balloon pressure such as 6 times atmospheric pressure) has about a 7.4 mm post-dilation diameter, or a 6.0 mm balloon has about a 6.5 mm post-dilation diameter. The nominal to post dilation ratios for a balloon may range from 1.05 to 1.15 (i.e., a post-dilation diameter may be 5% to 15% greater than a nominal inflated balloon diameter). The scaffold diameter, after attaining an inflated diameter by balloon pressure, will to some degree decrease in diameter due to recoil effects related primarily to, any or all of, the manner in which the scaffold was fabricated and processed, the scaffold material and the scaffold design.

When reference is made to a diameter it shall mean the inner diameter or the outer diameter, unless stated or implied otherwise given the context of the description.

When reference is made to a scaffold strut, it also applies to a link or bar arm.

“Post-dilation diameter” (PDD) of a scaffold refers to the inner diameter of the scaffold after being increased to its expanded diameter and the balloon removed from the patient’s vasculature. The PDD accounts for the effects of recoil. For example, an acute PDD refers to the scaffold diameter that accounts for an acute recoil in the scaffold.

A “before-crimp diameter” means an outer diameter (OD) of a tube from which the scaffold was made (e.g., the scaffold is cut from a dip coated, injection molded, extruded, radially expanded, die drawn, and/or annealed tube) or the scaffold before it is crimped to a balloon. Similarly, a “crimped diameter” means the OD of the scaffold when crimped to a balloon. The “before-crimp diameter” can be about 2 to 2.5, 2 to 2.3, 2.3, 2, 2.5, 3.0 times greater than the crimped diameter and about 0.9, 1.0, 1.1, 1.3 and about 1-1.5 times higher than an expanded diameter, the nominal balloon diameter, or post-dilation diameter. Crimping, for purposes of this disclosure, means a diameter reduction of a scaffold characterized by a significant plastic deformation, i.e., more than 10%, or more than 50% of the diameter reduction is attributed to plastic deformation, such as at a crown in the case of a stent or scaffold that has an undulating ring pattern, e.g., FIG. 1. When the scaffold is deployed or expanded by the balloon, the inflated balloon plastically deforms the scaffold from its crimped diameter. Methods for crimping scaffolds made according to the disclosure are described in US20130255853.

A material “comprising” or “comprises” poly(L-lactide) or PLLA includes, but is not limited to, a PLLA polymer, a blend or mixture including PLLA and another polymer, and a copolymer of PLLA and another polymer. Thus, a strut comprising PLLA means the strut may be made from a material including any of a PLLA polymer, a blend or mixture including PLLA and another polymer, and a copolymer of PLLA and another polymer.

Bioresorbable scaffolds comprised of biodegradable polyester polymers are radiolucent. In order to provide for fluoroscopic visualization, radiopaque markers are placed on the scaffold. For example, the scaffold described in U.S. Pat.

No. 8,388,673 (’673 patent) has two platinum markers **206** secured at each end of the scaffold **200**, as shown in FIG. 2 of the ’673 patent.

When reference is made to a direction perpendicular to, or parallel with/to axis A-A (e.g., as shown in FIG. 3) it will mean perpendicular to, or parallel with/to the axial direction of a scaffold or tube. Similarly, When reference is made to a direction perpendicular to, or parallel with/to axis B-B (e.g., as shown in FIG. 3) it will mean perpendicular to, or parallel with/to the circumferential direction of the scaffold or tube. Thus, a sinusoidal ring of a scaffold extends parallel with/to (in periodic fashion) the circumferential direction or parallel to axis B-B, and perpendicular to axis A-A whereas a link in one embodiment extends parallel to the axial direction or axis A-A of the scaffold or tube and perpendicular to the axis B-B.

Wherever the same element numbering is used for more than one drawing it is understood the same description first used for the element in a first drawing applies to embodiments described in later drawings, unless noted otherwise.

The dimension of thickness (e.g., wall, strut, ring or link thickness) refers to a dimension measured perpendicular to both of axes A-A and B-B. The dimension of width is measured in the plane of axes A-A and B-B; more specifically, the width is the cross-sectional width from one side to another side of a contiguous structure; thus, a U-shaped link **636** has a constant link width over its length just as link **334** has a constant link width. Moreover, it is understood that the so-called plane of axes A-A and B-B is technically not a plane since it describes surfaces of a tubular structure having central lumen axis parallel with axis A-A. Axis B-B therefore may alternatively be thought of as the angular component if the scaffold locations were being described using a cylindrical coordinate system (i.e., axis A-A is Z axis and location of a luminal/abluminal surface of a crown, link, ring, etc. is found by the angular coordinate and radial coordinate constant).

A “thin wall thickness,” “thin-walled scaffold,” “thin-wall” refers to a strut, ring, link, or bar arm made from a polymer comprising poly(L-lactide) and having a wall thickness less than 125 microns. The challenges faced when working with a thin-walled scaffold are discussed herein, including retaining a marker having the same volume of radiopaque material

FIG. 2 is a top planar view of a portion of a polymer scaffold, e.g., a polymer scaffold having a pattern of rings interconnected by links. There is a marker link **20** (“link **20**”) extending between rings **312a**, **312b** in FIG. 2. The link **20** has formed left and right structures or strut portions **21b**, **21a**, respectively, for holding a radiopaque marker. The markers are retainable in holes **22** formed by the structures **21a**, **21b**. The surface **22a** corresponds to an abluminal surface of the scaffold.

FIG. 2A is a reproduction of FIG. 2 illustrating additional dimensional features, specifically characteristic dimensional features D0, D1 and D2. The diameter of the hole **22** is D0. The distance between the adjacent holes **22** is greater than or equal to D1. And the brim width of either or both holes **22**, or distance from the inner wall surface circumscribing either or both holes **22** to the edge of the link **20** is greater than or equal to D2.

FIG. 2B shows the dimensional features described in connection with FIG. 2A for a marker link **720** oriented so that the structures **21a**, **21b** are offset along axis B-B, as opposed to axis A-A. The marker **720** connects rings **312a** and **312b**. A scaffold embodying this marker is shown in FIG. 7.

FIG. 2C there is shown rivet-type markers **127'/137'** secured in the holes **22**. The dimensions indicated refer to parameters that may be used to inspect the marker link (after the radiopaque is connected) to evaluate its capacity for resisting forces that tend to dislodge the rivet **127'/137'** from the hole **22**. These dislodging forces can be produced by a pressurized balloon surface or a deformation of nearby scaffold structure tending to deform the hole **22**, such as when the scaffold is crimped or balloon expanded. According to one aspect, the rivet heads and/or tails of the rivet **127'/137'** pair may be inspected to determine whether the minimum distances  $\delta 1$ ,  $\delta 2$ , and  $\delta 3$  (FIG. 2C) are satisfied. The distances  $\delta 1$ ,  $\delta 2$ , and  $\delta 3$  reflect either or both a minimum size of a head and/or tail of the rivet that was pressed into the hole, which indicates both that the rivet should hold in the hole **22** (if the head or tail is too small in diameter it cannot resist as well the dislodging forces) and that excess rivet material will not cause problems such as balloon puncture or vessel irritation when the scaffold is implanted within a vessel. According to the embodiments the minimum distance from the end of the marker head/tail to the brim of the strut (or link) portion **21a/21b**,  $\delta 2$  that is, can be about 10%, 25% and up to 50% of  $D2$ . Above 50% means the head or tail can be too small to hold the rivet in place. For a head/tail equal to, or greater than  $D2$  the head may or does extend beyond the brim of the strut/link, which can lead to problems such as forming a relatively sharp edge than can damage the balloon or irritate adjacent tissue. The minimum distance between the marker heads/tails,  $\delta 1$  that is, is 0 or up to 25% of the distance  $D1$ . If the rims or heads of the markers overlap each other this can exceed the maximum height desired for the strut (about 160 microns). The minimum length for the head/tail extending to the right or left of the hole **22**,  $\delta 3$  that is, is anything greater than 50% of  $D2$ .

Methods for inserting radiopaque markers into holes commonly rely on a cylindrical hole to retain the marker. Most of the force of retention comes from friction between the walls and the marker material. Marker material has been reliably retained in scaffold holes in this manner when the scaffold has a wall thickness of 150 microns and above. However, it becomes far more challenging to hold the marker material within a hole when the wall thickness is reduced to 100 microns or less than 100 microns. Although a coating material for carrying a drug can help to hold the marker in place, the coatings, such as Everolimus/PDLLA, tends to be quite thin—on the order of 3 microns, which limits its out of plane shear strength resisting dislodgment of the marker from the hole.

There are several desirable properties or capabilities that follow from a reduction in wall thickness for a scaffold strut. The advantages of using the reduced wall thickness include a lower profile and hence better deliverability, reduced acute thrombogenicity, and potentially better healing. In some embodiments it is desirable to use the same size marker for a scaffold having thinner struts, so that there is no difference, or reduction, in radiopacity between the two scaffold types. Reducing the strut thickness, while keeping the marker hole **22** the same size can however result in the marker protruding above and/or below the strut surfaces due to the reduced hole volume. It may be desirable to keep the abluminal and luminal surfaces **25a**, **25b** of a marker' flush with corresponding luminal and abluminal surfaces of the strut, in which case the hole **22** diameter ( $d$ ) may be increased to partially account for the reduced hole volume resulting from the thinner strut.

Paragraphs [0073] through [0083] of U.S. application Ser. No. 14/738,710, which shares a common inventor with this

application, describes the factors affecting a scaffold's ability to retain a marker in a hole and the special challenges faced when a wall thickness is less than 160 microns, or less than 125 microns. According to some embodiments it has been found that a marker cannot be retained in a hole reliably by essentially friction alone when the wall thickness is less than 125 microns, i.e., when the scaffold is thin-walled. In a preferred embodiment where the wall thickness is less than 100 microns a marker material is retained within a hole using a rivet-shaped marker, discussed briefly above in connection with FIG. 2C and described in greater detail in connection with FIGS. 8-16.

Following are described embodiments of scaffold patterns suited to meet one of, or a combination of the following objectives:

- (i.) reduced crimped profile for a thin-walled scaffold carrying a radiopaque marker,
- (ii.) securing a radiopaque marker in a thin-walled scaffold,
- (iii.) reducing strain energy buildup in marker-holding structure when the thin-walled scaffold is being deformed during crimping, balloon expansion at a target vessel site, or delivery of the scaffold to a target site, and
- (iv.) avoiding protruding or flaring end rings at a distal end of a scaffold for a thin-walled scaffold or scaffold comprising PLLA and having a wall thickness greater than 125 microns.

It will be appreciated that the above objectives are inter-related and more than one objective can be addressed by a single change. For example, by making a marker link more flexible both of objectives (iii) and (iv) can be met. Scaffolds according to these embodiments may be made from a thin-walled tube or sheet of material comprising poly(L-lactide) (PLLA), which is laser cut from a tubular body to produce the patterns shown in FIGS. 3-7. Processes to make the tube may include one or more of extrusion, injection molding, solid-phase processing, and biaxial expansion as described in U.S. Ser. No. 14/810,344 (62571.1212).

Scaffolds according to the embodiments, e.g., scaffolds **300**, **400**, **500**, **600** or **700**, are preferably crimped to a balloon catheter, such as the one shown in FIG. 3D. The scaffold may be attached to the balloon to secure the desired crimped diameter, such as  $D_{\text{min}}$  (defined, infra) using any of the crimping processes described in US20130255853; specifically any of the crimping processes and apparatus for crimping described at paragraphs [0068]-[0073], [0077]-[0099], [0111]-[0126], [0131]-[0146] and FIGS. 1A, 1B, 4A, 4B, 5A, 5B, 8A, and 8B of US20130255853.

FIG. 3 shows a partial, planer view of end portions of a scaffold according to one embodiment, or scaffold **300**. The left or distal end portion **302** (i.e. the left side of FIG. 3) includes sinusoidal rings **312a**, **312b**, and **312c** where ring **312a** is the outermost ring. Ring **312a** and ring **312b** are adjoined by two links **334** and a marker link **20**. Ring **312c** and ring **312d** are adjoined by three links **334** that extend parallel to axis A-A. The links **334** extend parallel to axis A-A and have a constant cross-sectional moment of inertia across its length, meaning link **334** has a constant width and thickness and the location of the centroid or geometric center (or longitudinal axis) of the link is everywhere parallel with axis A-A. The right or proximal end portion **304** (i.e. the right side of FIG. 3) includes sinusoidal rings **312d**, **312e**, and **312f** where ring **312f** is the outermost ring. Ring **312d** and ring **312e** are adjoined by three links **334**. Ring **312e** and ring **312f** are adjoined by two links **334** and the marker link **20**. Thus, scaffold **300** has a marker link **20** extending between and adjoining the outermost link with the

adjacent, inner ring. The scaffold **300** may have 15, 18 or 20 rings **312** interconnected to each other by links **334**.

A ring **312**, e.g., ring **312b**, is sinusoidal meaning the curvature of the ring along axis B-B is best described by a sine wave where the wavelength of the sine wave is equal to the distance between adjacent crests **311a** of the ring. The ring has a constant width at both crowns **307**, **309** and **310** and struts **330**, which connect a crown to an adjacent crown.

There are three crown types present in each inner ring **312b** through **312e**: U-crown, Y-crown and W-crown. Outermost rings have only the Y-crown or W-crown type, and the U-crown type. A crest or peak **311a** (or trough or valley **311b**) may correspond to a U-crown, Y-crown or W-crown. For the outermost ring **312a** there is only a U-crown and W-crown type. For the outermost ring **312f** there is only a U-crown and Y-crown type. A marker link **20** adjoins rings by forming a W-crown with the first ring (e.g., ring **312e**) and a Y-crown with the second ring (e.g. ring **312f**).

A link **334** connects to ring **312f** at a Y-crown **310**. A “Y-crown” refers to a crown where the angle extending between a strut **330** of a ring **312** and the link **334** is an obtuse angle (greater than 90 degrees). A link **334** connects to ring **312a** at a W-crown **309**. A “W-crown” refers to a crown where the angle extending between the strut **330** and the link **334** is an acute angle (less than 90 degrees). A U-crown **307** is a crown that does not have a link connected to it. Marker link **20** connects to a ring at a W-crown **314** and a Y-crown **316**.

For the scaffold **300** there are 6 crests or peaks **311a** and 6 troughs or valleys **311b** for each ring **312**. A crest **311a** is always followed by a valley **311b**. Ring **312b** has 12 crowns: 3 are W-crowns **309**, 3 are Y-crowns **310** and 6 are U-crowns **307**.

FIGS. **3A** and **3B** show partial, close-up views of the scaffold **300**. FIG. **3A** shows section IIIA of FIG. **3** and FIG. **3B** shows section IIIB of FIG. **3**. The following description, made in respect to FIGS. **3A-3B**, applies the same for portions **302** and **304** of scaffold **300** with the understanding that in the case of the link **20** it connects to the outermost ring **312f** at a Y-crown **316** and adjoining ring **312e** at a W-crown **314**.

Referring to FIG. **3A**, consecutive wavelengths of the outermost ring **312a** have lengths **L1** and **L2**, or the distance (along axis B-B) from crown **314** to U-crown **307** is **L1** and the distance from U-crown **307** to Y-crown **309** is **L2**. The same distances apply for rings **312b**-crown **316** to W-crown **309** and W-crown **309** to Y-crown **310** are **L1** and **L2**, respectively. For scaffold **300** **L1=L2=constant** for rings **312a**, **312b**. That is, the distance or wavelength from one crest to another is the same. Also, for scaffold **300** **L1+L2** is constant everywhere; that is, for all rings the distance between a W-crown and Y-crown is the same, as is the distance between adjacent crests for the rings **312a** through **312f**. The distance **X** in FIG. **3A** refers to a half-period or half-length of the sine wave, or  $\frac{1}{2}$  of **L1**. The distance **X** is equal to the distance from the crown **314** to the adjacent U-crown **307** for crown **312a**. **X** is the same for ring **312b**. In other embodiments **L1** is not equal to **L2** and **X** is different between the outermost ring **312a** and adjoining ring **312b**.

In alternative embodiments, including scaffolds **400**, **500** or **700** described below, the rings may have zig-zag instead of sinusoidal ring shapes. An example of zig-zag shaped rings is found in FIGS. **5A** and **6A** of US20140039604. A zig-zag ring may be described as non-curved strut elements converging at a crown that is shaped to have an inner and outer crown radius. The same description applies, meaning the ring may be described in terms of wavelengths, struts

and crowns, except that the shape is not sinusoidal but zig-zag. The term “undulating” refers to both zig-zag and sinusoidal ring types.

Referring to FIG. **3B**, a distance along axis A-A from the peak or crest of the ring **312a** to the peak or the crest of the adjoining ring **312b**, or the length of marker **20** (plus the width **t1**) is **A12**. A distance along axis A-A from the peak or a crest of the ring **312b** to the peak or the crest of the adjoining ring **312c**, or length of marker **334** between these rings (plus the width **t2**) is **A23**. For scaffold **300** **A12=A23**. The width of the link **20** to the left of marker structure **21a** is **tm1** and the width of the marker link **20** to the right of structure **21b** is **tm2**. The width of the link **334** is **t11**. The crowns **307**, **310**, **309** and **314** and struts **330** of ring **312a** have a constant width **t1**. The crowns **307**, **310**, **309** and **314** and struts **330** of ring **312b** have a constant width **t2**. The crowns **307**, **310**, **309** and **314** and struts **330** of ring **312c** have a constant width **t3**. For scaffold **300** **t1** is less than **t2** and **t2=t3**. The dimension **B1** and **B2** refer to a surface of the crowns for rings **312a** and **312c**, respectively, extending parallel to axis B-B or the crown surface portion without curvature, i.e., flat. For scaffold **300** **B1=B2**.

Referring to FIG. **3C** there is shown the scaffold **300** having marker **20** in a crimped state. The crimped diameter enforced on scaffold **300** is the theoretical minimum crimped diameter where struts that converge at the same crown are in contact with each other when the scaffold is fully crimped, i.e., when the scaffold is removed from the crimping device, or when placed within a restraining sheath soon after crimping. The equation for the theoretical minimum crimped diameter (**D-min**) under these conditions is shown below

$$D\text{-min}=(1/\pi)\times[(n\times\text{strut\_width})+(m\times\text{link\_width})]+2*t,$$

Where

“**n**” is the number of struts in a ring (**12** struts for scaffold **300**),

“**strut\_width**” is the width of a strut (**170** microns for scaffold **300**),

“**m**” is the number of links adjoining adjacent rings (**3** for scaffold **300**),

“**link width**” is the width of a link (**127** microns for scaffold **300**), and

“**t**” is the wall thickness (**93** microns for scaffold **300**).

Hence, for scaffold **300**  $D\text{-min}=(1/\pi)\times[(12\times 170)+(3\times 127)]+2\times(93)=957$  microns.

For adjoined ring pairs **312a** and **312b** at the distal end **302**, and adjoined ring pairs **312e** and **312f** at the distal end the marker link **20** is wider (along axis B-B) than is a link **334** in order to accommodate the markers. As a consequence the adjacent struts **330** can often overlap the link **20** to achieve the same **D-min** throughout. This condition is depicted in FIG. **3C**. Such a state for the crimped scaffold introduces concerns regarding local strength for the rings and link holding the marker. As shown in FIG. **3C** there is an overlap (strut presses against abluminal surface of marker) or underlap (strut presses against luminal surface of marker) by the struts **330a**, **330b** and/or the associated U crowns associated with these struts. It is preferred to eliminate this overlap/underlap when the scaffold is crimped.

Scaffold struts, in particular thin-walled scaffold struts and links, are not designed to twist or carry significant torsion. Twisting occurs when struts abut and overlap each other. When a scaffold strut has a higher aspect ratio of width to thickness, there is greater propensity for the strut to twist when it abuts adjacent structure, e.g., the structure **21a** of the marker link **20** (a thin walled scaffold has a higher aspect



ratio for the same vessel tissue coverage—strut width—as compared to a thicker-walled scaffold). As can be appreciated from the deformed state of FIG. 3C compared with FIG. 3 torsion is introduced in the ring structure and possibly also the marker link strut. This type of abnormal deformation can lead to crack propagation or reduced fatigue life of the ring and/or link 20 at the time of balloon expansion in a vessel.

FIG. 3D shows a medical device comprising a balloon catheter and the scaffold 300 crimped to a balloon 15. The distal end 302 of the scaffold 300 is nearest the distal end 17b of the balloon 15 and the proximal end 304 is nearest the balloon proximal end 17a. The tip of or the most distal end 12 of the balloon catheter is shown. A guide wire or mandrel 8 extends from the tip 12, exiting from a lumen of the catheter shaft 2. The scaffold crimped to the balloon (according to D-min or other minimum crimped diameter) can be scaffold 300 or scaffold 400, discussed infra. Scaffolds 500, 600 and 700 may also be used in place of scaffold 300.

As mentioned earlier, when compared to a scaffold that has a comparatively thick wall thickness, such as the scaffold described in US 2010/0004735 or the ABSORB GT1 bioresorbable scaffold, the thin-walled scaffold having a similar scaffold pattern was found to exhibit a significantly higher occurrence rate of strut overlap or underlap (hereinafter MBOL) similar to that shown in FIG. 3C. Higher MBOL occurrence rates are more likely when the width of the link containing the markers is made wider to accommodate the same overall volume of the marker material as used in a scaffold having higher wall thickness struts. The MBOL can also be higher when a more aggressive crimp is employed—e.g., D-min crimp profile.

Furthermore, when the same volume marker bead is attached to both the thin-walled and thick-walled scaffolds and the marker is made flush with the abluminal and luminal surface of the link, the marker bead region must adopt a flatter and broader shape, which enforced shape deforms the structure 21a and 21b to increase the propensity for strut overlaps in the marker bead region, since the marker structure develops a higher aspect ratio to accommodate the marker and/or there can be residual strain from the marker swaging process, which makes the marker structure 21 more susceptible to twisting out of plane. TABLE 1 summarizes these findings.

TABLE 1

comparison between scaffold 300 and thicker-walled scaffold			
Property	US 2010/0004735	Scaffold 300	Comments/observations
Tubing thickness (microns)	158	93	Thinner struts may have an increased tendency to overlap each other when encountering strut-to-strut sidewall contact during crimping.
3.0 mm scaffold (before crimp size of 3.0 mm) minimum crimp (in)	0.051 (in)	0.041 (in)	More aggressive crimping increases the likelihood of strut-to-strut overlapping during crimping, or when a restraining sheath is placed over the crimped scaffold.
Crimped diameter	0.050 (in)	0.038 (in)	
Average marker bead sphere radius (in)		0.0045	More severe flattening of an identical marker bead sphere results in a 30% broader theoretical cylinder shape for the thin-walled scaffold, increasing propensity for overlapped struts at marker bead region.
Marker bead sphere volume (in <sup>3</sup> )	3.82E-07	3.82E-07	
Theoretical marker bead cylinder diameter when swaged and flush with strut luminal surface (in)	0.0088	0.0115	

Paragraphs [0073] through [0083] of U.S. application Ser. No. 14/738,710, which shares a common inventor with this application, describes the factors affecting a scaffold's ability to retain a marker in a hole and the special challenges faced when a wall thickness is less than 160 microns, or less than 125 microns. Additionally, the '710 application explains how the marker-holding structure must be wider for reduced wall thickness and same radiopaque material volume if the marker will remain flush—as desired—with the abluminal surface of the strut (therefore, higher aspect ratio and greater tendency for twisting movement and overlap during crimping). A wider and flatter marker structure increases the aspect ratio (AR) of the link's width to its wall thickness, which increases the likelihood that the link will twist when it comes in contact with an adjacent strut or crown.

In one example the aspect ratio (AR) of the marker link for a thin-walled scaffold having a 93 micron wall thickness, compared to an AR for a scaffold having a higher wall thickness of 158 microns, e.g., as described in US 2010/0004735, and the same volume of marker material held by both the 93 micron and 158 micron marker structures, is about 4.5 ( $AR=ts/t=419 \text{ micron}/93 \text{ micron}=4.5$ ). For the scaffold having the 158 micron all thickness the AR is about 2 ( $AR=ts/t=322/158$ ). Thus, for the same volume of marker material and reduction in wall thickness from 158 microns to 93 microns the AR increases 2.5 times. Given this significant increase in the aspect ratio it will be appreciated that the tendency for the marker link to twist when it comes in contact with adjacent struts or crowns during crimping, and/or the struts to overlap/underlap the marker link can be appreciated.

It is known that during crimping, scaffold bar arms angles reduce and adjacent bar arm struts naturally move toward the link of a w crown. In this crimping event, the w crown's "outboard radius" and its center point (usually located outside the link) play a crucial role in guiding the way the scaffold struts crimp. In fact, the center point of this outboard radius tends to act as a pivot point that guides the initial behavior of the struts and limits the extent of strut motion toward the marker link features. In this second respect, the MBOL occurring between strut and marker link

features are closely related to this outboard radius and pivot point location. In the case of the w crown with marker links **20** and a thin-walled scaffold design, the center points of the w crown were initially positioned within the marker structure **21** region. Therefore, during crimping, the strut closure behavior was not kinematically limited, resulting in frequent occurrences of overlapping/underlapping with the marker link. To reduce the MBOL occurrence rate, the center points of the W crown with the marker structure **21** may be moved to an area outside of the marker structure **21**. Hence, during crimping, when the struts of the w crown move toward the marker structure **21**, they should avoid pressing into and slipping into an overlap or underlap state which induces torsion in the w crown and/or link.

FIG. 4 shows a partial, planar view of end portions of a scaffold according to another embodiment, or scaffold **400**. The left or distal end portion **402** (i.e. the left side of FIG. 4) includes sinusoidal rings **412a**, **312b**, and **312c** where ring **412a** is the outermost ring. Ring **412b** and ring **312c** are adjoined by two links **334** and the marker link **20**. Ring **312c** and ring **312d** are adjoined by three links **334** that extend parallel to axis A-A. The right or proximal end portion **404** (i.e. the right side of FIG. 4) includes sinusoidal rings **312d**, **412b**, and **312f** where ring **312f** is the outermost ring. Ring **312d** and ring **412b** are adjoined by three links **334**. Ring **412b** and ring **312f** are adjoined by two links **334** and the marker link **20**. Thus, scaffold **400** has a marker link **20** extending between and adjoining the outermost link with the adjacent ring. The scaffold **400** may have 15, 18 or 20 rings **312** interconnected to each other by the links **334**.

Scaffold **400** has the same features as described earlier for scaffold **300**, except as follows. Rings **412a** and **412b** are sinusoidal and adjoined to neighboring rings by W-crowns **414** and Y-crowns **416** (as in the case of rings **312a** and **312e**), but the ring structure for rings **412a** and **412b** near marker **20** is modified to avoid overlapping struts when the scaffold is crimped to a minimum theoretical crimp diameter (D-min), as discussed earlier.

Referring to FIGS. 4A and 4C there is shown close-up views of scaffold **400** at the sections IVA and IVB from FIG. 4, respectively. To avoid the overlap discussed earlier the space between struts portions of the w-crown at the marker for ring **412a** and ring **412b** is increased. This modification is indicated in the drawings by w-crown **414**. The lengthened crown (along axis B-B) provides more space between the strut **430** and marker structure **21a**, **21b** to avoid the overlap (the resulting crimped shaped with this modification is shown in FIG. 4D). In contrast to w-crowns **309** not associated with the marker link **20**, w-crown **414** modifies the scaffold structure near the marker **20** in at least one of ways (1), (2) and (3):

- (1) The flat, or non-curved surface portion B1 of the crown is increased in direction B-B over other w-crown **309** flat surface parts B2, e.g., an increase of between about 350% to about 400% for a marker link maximum width (ts) that is about 200% greater than a non-marker link width (tL).
- (2) The distance from the w-crown **414** (crest) to the adjacent u-crown **407** (trough) is increased as compared to the distance from the y-crown **316** (crest) to the adjacent u-crown **307** (trough) of ring **312b**, and/or for any of rings **312** the distance from a w-crown **309** (crest) or y-crown **310** (crest) to an adjacent u-crown **307** (trough). This is indicated in the drawings by comparing the distance X412 to the distance X312, which measure the length from the crest center to the trough center of rings **412** and **312**, respectively. The

distance X412 may be about 15% greater than X312 for a marker link maximum width (ts) that is about 200% greater than a non-marker link width (tL).

- (3) The distance from the crest **414** to the adjacent crest **407** is greater than the distance from the crest **407** to the crest **409** or L1 is longer than L2 in FIG. 4A, e.g., L1 is about 10% longer than L2, and/or L1 is about 5% longer than the distance between any adjacent crests for rings **312a**, **312b**, **312d**, and **312f** and for a marker link maximum width (ts) that is about 200% greater than a non-marker link width (tL).

The features of ring **412a** apply equally to ring **412b** within the vicinity of marker link **20**. FIG. 4B shows a view of the portion **302**, where ring **412a** is shown in phantom over ring **312a** from scaffold **300**. The space added between the marker link **20** and strut **430** is indicated by "increased space" in the drawing. The difference in half-periods of the sinusoidal ring portions (X412, X312) extending between the marker link y-crown and w-crown, respectively, can also be seen in this drawing. Also, the features of ring **412a** are symmetric about the w-crown **414**. Therefore, the modifications of at least one of (1), (2) and (3), discussed supra, apply to both sides of the w-crown **414**.

According to another aspect of the scaffold **400** in connection with the "increased space" indicated for scaffold **400** to avoid MBOL or overlap, for some embodiments of making the scaffold marker link and connecting rings to avoid overlap, it is advantageous to also factor in deformation of the structure **21a**, **21b** when a marker element, rivet or bead, is swaged into the hole.

FIG. 4D shows a portion of scaffold **400** in a crimped state, where the scaffold has been crimped to D-min. As can be seen here, the added space between the strut-portions **430a**, **430b** of the w-crown **414** at the marker link **20** results in no overlap or underlap when the scaffold is crimped to the theoretical minimum crimp diameter, D-min. Specifically, FIG. 4 shows that with the modification to the ring **412** having the W crown **414** connection to the marker link **20** the struts and/or U crowns adjacent and above and below the marker structure are separated by a distance that is greater than or equal to the maximum width (ts) of the marker structure when the scaffold is crimped to D-min. There is no overlap when the scaffold having the ring **412** is crimped to D-min. The marker link is everywhere between the crowns and struts when the scaffold is crimped to about D-min.

It has been found that when a thin-walled scaffold similar to scaffold **300** was tracked through a simulated calcified and tortuous anatomic model, distal end ring distortion was observed due to struts lifting and catching on obstacles along their path. Additionally, there was potential for the marker structure **21** and holes **22** to deform/stretch resulting in potential dislodgment of the marker material. To address this concern for marker material separation from the thin-walled scaffold, the marker link may be made more flexible in bending by lengthening the link and/or reducing the width of the link portions connecting the structure **21** to the adjacent Y or w crown. This change results in a more flexible hinge region adjacent to the marker structure **21**, thereby localizing the deformation to points away from the structure **21** to protect the marker hole **22** from significant deformation. The change also makes the distal and/or proximal ends of the scaffold more flexible and conforming to the balloon, thereby reducing the potential for strut lifting and catching on obstacles during delivery to a target site.

FIG. 5 shows a close up view of another embodiment of a scaffold, or scaffold **500**. The view of FIG. 5 is the same as for section IVC of FIG. 4 and scaffold **500** has all the

features of scaffold **400**, except that the marker link adjoining rings **412a** and **312b** and rings **412b** and **312f** is modified. Marker link **520** differs from marker link **20** in that an additional link **520b** is added, or the existing link to the right of marker structure **21b** (see marker link **20**) is lengthened. This added, or lengthened marker link portion results in an increase of the distance **A12** as compared to when marker **20** is used. Also, distance **A12** is longer than distance **A23** separating rings not adjoined by a marker link, e.g., rings **312b** and **312c** in FIG. 5. The same modification—marker link **520** replacing marker link **20**—is made to the marker link extending between rings **412b** and **312f**. Marker link **520** may also replace marker link **20** in scaffold **300** (at both proximal and distal ends). In such case, the same features discussed in respect to scaffold **400** with link **520** also applies to scaffold **300** having link **520**.

It was found that when link **20** was replaced by marker link **520** there was less tendency for the radiopaque material held by the marker structure **21** to become dislodged or separate from the scaffold when the scaffold was crimped, balloon expanded or tracked through a tortuous vessel. The reason for the improved retention may be understood by consideration of the strain energy distribution over the link when the scaffold is deformed, or the y-crown **316** of ring **312b** moves relative to the w-crown of ring **412a**.

If crown **316** of ring **312b** moves radially outward or inward relative to crown **414** of ring **412a**, or the crowns move in opposite directions along axis B-B, then the marker link **20** deforms. A significant portion of the strain energy in the link **20** resulting from this deformation is carried in the marker structure **21a**, **21b** because the link portions to the left and right of structure **21** are relatively short and thick (as such, there is little deformation in this part of the marker link and therefore less strain energy carried here). Since the load must be reacted somewhere along the marker link when the ring movement is enforced (i.e., regardless of the link stiffness the rings will move relative to each other by a prescribed magnitude because the ring movement occurs by an enforced displacement or overwhelming force, such as by crimper jaws closing down on the scaffold), the strain energy is mostly carried in the marker structure **21**, which deforms more easily than the short and thick link portions near the crowns. This deformation can change the hole shape that the marker material sits in, thereby resulting in a loss of retention. By lengthening the link portion of the marker **20**, or adding link **520b** that is significantly longer than link **520a**, which represents the length for the link portions at left and right sides of structure **21** for link **20**, the strain energy is instead carried less in structure **21** and more by link **520b**. As a result, there is less tendency for the marker material to become dislodged during crimping or bending of the scaffold because the marker holes **22** retain their shape during these loading events. In other words, the deformation of the link occurs mostly in the long slender portion **520b** so that the holes **22** can retain their shape. Additionally, the link **520b** also increases the flexibility of the link, thereby enabling the ring **312b** or **312f** to move more easily relative to ring **412a** and ring **412b**, respectively. This aspect is advantageous to avoid problems with the distal end ring flaring or protruding from the balloon when the catheter is navigated about tight vasculature (objective (iv), supra). It is also noted that marker **720**, discussed in connection with FIG. 7, similarly addresses objectives (iv) and (iii).

According to one example, the link **520b** forming the y-crown **316** has a thickness (tm2) that is about 60% less than the thickness (tm1) of the link portion **520a** connecting the forming the w-crown **414**. Additionally, the length **A12**

is about 27% longer than the length **A23**, so as to accommodate the link **520** with added link portion **520b**.

When a thin-walled scaffold, crimped to a delivery system, was tracked through a simulated calcified and tortuous anatomic model, distal end ring distortion was observed due to struts catching on obstacles along their path. To understand the possible causes for the strut catching, a thin-walled scaffold was crimped to a delivery system of the same configuration and placed in bending similar to what existed in the anatomical model observed under microscope. It was observed that the balloon was under compression on the inner curve of the bend and tension on the outer curve of the bend. Under tension, the balloon stretched and conformed to the curve. If the w-crown associated with the marker link happened to be positioned on the outer curve of the bend, it would flare-out (see FIG. 6B) instead of conforming to the underlying curved balloon material at the distal end **15a**. The w-crown section of the scaffold remains straight since it is stiff due to the marker material and structure **21**.

FIG. 6 shows a partial, planar view of end portions of a scaffold according to another embodiment, or scaffold **600**. The left or distal end portion **602** (i.e. the left side of FIG. 6) includes sinusoidal rings **312a**, **412a**, and **312c** where ring **312a** is the outermost ring. The right or proximal end portion **604** (i.e. the right side of FIG. 6) includes sinusoidal rings **312d**, **412b**, and **312f** where ring **312f** is the outermost ring. As can be appreciated from FIG. 6 the distal end portion **602** is different from the proximal end portion **604**. This modification to scaffold **300** or scaffold **400** is made to address occurrences of a non-confirming distal, outermost end ring when the scaffold mounted on a balloon catheter is navigated around a sharp turn in vasculature.

The proximal end portion **604** of scaffold **600** is the same as the proximal end portions **304** or **404** associated with scaffolds **300** and **400**, respectively. The distal end portion **602** is modified from distal end portions **302** or **402** in the following ways.

The (distal) marker link **20** of scaffold **600** is located between inner distal end rings **412a** and **312c**, in contrast to the (proximal) marker link **20** located between the outermost ring **312f** and inner ring **412b**. This change to the distal end **602** is desirable for at least one of reasons (a) and (b):

(a) Improved conformity with distal end balloon: the marker link **20** is stiffer in bending than link **634** or, for that matter, link **334**, which can result in separation of the distal outermost ring from the balloon distal end. When it is not desirable to modify the marker link structure, or it is not feasible (e.g., because the structure is needed to provide sufficient surface area to hold the desired volume of radiopaque material), a significant reduction in the flexural rigidity of the link connecting the outermost ring **312a** to interior ring **412a** may be achieved by moving the marker link **20** to between inner rings. The ability then to dramatically decrease the flexural rigidity between the outermost two rings **312a**—objective (iv)—is addressed.

(b) Less strain in marker-holding structure: when the scaffold is navigated about a sharp turn it is the outermost rings that will experience the highest strain due to the scaffold being bent. For embodiments of scaffolds where it is not desirable to make less stiff in bending the outermost ring relative to adjacent inner ring (e.g., where it is important to avoid a decrease in radial stiffness for the outermost ring or to avoid increased spacing between rings for purposes of drug coverage or vessel support, both of which can occur when the connecting links are lengthened to make more flexible),

by moving the marker link **20** to a location between inner rings the bending strain on the link **20** that can cause the marker material to become dislodged is avoided or mitigated. That is, because the bending strain in the scaffold (produced when a sharp turn is made by the catheter) is higher between the outermost ring and adjacent inner ring than between inner rings, by locating the link **20** to between inner rings (without a need to change the marker link structure) the bending strain on the marker structure **21** is less. Objectives (ii) and (iii) are met.

The scaffold **600** differs also from scaffolds **300** and **400** by the link type used to connect the outermost ring to the inner ring—that is, the link **634** connecting ring **312a** to ring **412a**. The outermost distal ring **312a** is adjoined with ring **412a** by three non-linear link struts **634** that are significantly more flexible in bending than are link struts **334** connecting interior rings. This also helps with reason (a) for using a scaffold **600** pattern for the distal end.

A non-linear link strut may take on a variety of shapes, but with certain restraints such as providing sufficient space for crimping, e.g., D-min crimped profile. The type shown in FIG. **6** has a U-shaped medial portion **636** connected to the respective y-crown and w-crown by a short, straight link portion and long, straight link portion, respectively. The link portion connecting the portion **636** to the w-crown is longer than the link portion **632a** connecting to the y-crown in order to provide sufficient clearance for ring struts during crimping (as explained below). With this clearance provided the w-crown **309**, formed by the link portion **623a**, may be crimped down to D-min without U-shaped portion **636** interfering with struts **330** or struts **330** overlapping U-shaped portion **636** in the crimped state.

Referring to FIG. **6A** there is shown a crimped side profile for scaffold **600**. Shown is the link **634** long straight link portion **632a** and short straight link portion **623b** with the U-shaped medial portion **636**. The length **A12** (length measured with respect to axis A-A) may exceed the length **A23** by about the length of the U-shaped portion **636**, or the sum of the lengths of portions **632a** and **632b** is about equal to **A23**, less the strut width of a ring. In one example, the length **A12** is about 40% longer than the length **A23**.

In other embodiments the U-shaped portion **636** may be replaced by links having a smaller moment of inertia for a region between portions **632a** and **632b**, an S-shaped, notched portion, or narrowed portion replacing U-shaped portion. Examples of these link types are described in US20140039604 at FIGS. 14B, 14C, 14D, 14E, and 14F, and accompanying paragraphs [0223]-[0229]. A “non-linear” link strut means any of these links.

FIG. **6B** is an image showing a deformed distal end of a medical device comprising a balloon catheter having a shaft **2** and a scaffold **10** crimped to the balloon **15**. As can be seen in this view, when the catheter is directed about a sharp turn (as tracked over a guide wire) the balloon distal end and shaft conform to the angle of the turn but the scaffold distal end **7** does not. More specifically, the outermost ring **5** is flaring or protruding outwards from the distal end. This protruding structure **5** can get caught on walls of vasculature. The most pressing concern with this orientation of the scaffold relative to the balloon distal end is damage that might be caused by the ring **5** catching on the vasculature and damaging the scaffold (due to excessive bending strain). The damage that can occur has been mentioned earlier. First, the marker link structure can be deformed and result in dislodgment of the marker material. Second, the strain can result in fracture of, or crack propagation within the ring **5**.

One solution to this problem may be to make the end rings stiffer in bending, so that the vessel obstruction yields to make space for the flaring or protruding scaffold end. For example, one could make the end rings more thick or increase the number of connecting links between the outermost ring and inner ring. It is preferred, however, to instead make the rings less stiff so that the scaffold end will conform more to the balloon distal end. It is also preferred to limit the load put on a marker link, for reasons previously stated. Scaffold **600** (or scaffold **700**, *infra*) meets this need.

FIG. **6C** is an image of scaffold distal end **602** mounted on the balloon **15** distal end **15a** as the catheter makes a similar sharp turn in vasculature. As can be seen, by reducing the bending stiffness of the ring **312a** relative to the inner ring (ring **312b**) the end ring **312a** conforms to the shape of the balloon distal end **15a**. The end ring **312a** does not flare or protrude out as in the case of scaffold **5**. The links **632** act as hinges to accommodate compression and tension that a bend would exert on the distal end ring when the crimped scaffold is put on a bend.

Distal end scaffold conformity with the balloon distal may also be achieved by modifying the marker link structure to become more flexible in bending. In effect, the w-crown formed by the marker link according to the discussion can greatly reduce the stiffness at the w-crown associated with the marker link **314**. The thin-walled scaffold design can then have the marker link connected to the outermost ring without the flare-out problem discussed earlier.

FIG. **7** shows a partial, planar view of end portions of a scaffold according to another embodiment, or scaffold **700**. The left or distal end portion **702** (i.e. the left side of FIG. **7**) includes sinusoidal rings **312a**, **312b**, and **312c** where ring **312a** is the outermost ring. The right or proximal end portion **704** (i.e. the right side of FIG. **7**) includes sinusoidal rings **312d**, **412b**, and **312f** where ring **312f** is the outermost ring. As can be appreciated from FIG. **7** the distal end portion is different from the proximal end portion. This modification to scaffold **300** or scaffold **400** is also made to address occurrences of a non-confirming distal, outermost end ring when the scaffold mounted on a balloon catheter is navigated around a sharp turn in vasculature.

The proximal end portion **704** of scaffold **700** is the same as the proximal end portions **304** or **404** associated with scaffolds **300** and **400**, respectively. Moreover, the distal end portion **702** shares some of the characteristics of scaffold **600** at the distal end portion **602** except as follows.

The marker link **720** (FIG. **2B**) is located between the outermost ring **312a** and inner ring **312b**, as opposed to the marker link **20** or **520** located between inner links, in the case of scaffold **600**. The marker link for scaffold **700** is also different from the marker link of prior embodiments. Marker link **720** has the marker structure **21** orientated vertically rather than horizontally, as in the case of marker link **20** or link **520**. That is, the marker structure **21a** is offset from the marker structure **21b** along axis B-B rather than axis A-A. There is a long, straight link portion **732a** connecting the structure **21** at one end and forming the w-crown **314**, and a shorter link **732b** at the opposite end forming the y-crown **316**.

The outermost ring **312a** for scaffold distal end portion **702** is connected to the inner ring **312b** by the one marker link **720** and two of the non-linear links **634** used in scaffold **600**. Adjoined inner rings are not connected by a marker link **720** or link **634**. The link **334** is used. The marker link **720**, in contrast to the marker link **20**, is more flexible in bending due to the length of portion **732a** and is favorably located between the outermost ring and adjacent inner ring to more

easily locate the ends of the scaffold under fluoroscopy. Additionally, one or more of the following advantages are also present when marker **720** is used. First, the marker is more flexible so that the outermost ring will more easily conform to the balloon when the catheter is navigated about a tight turn in the vasculature. In this sense marker **720** has some of the same advantages as marker **520** (objectives (ii) and (iii)). And no change is needed to the ring structure to enable a crimping of the ring having the w-crown formed by the marker link. The ring **312a** can be crimped to D-min because the structure **21** does not interfere with the ring structure **21** (objective (i)).

FIGS. **6A** and **7A** show the crimped states of scaffold **700** near the marker **720** and link **634** and lengths between rings **A12**, **A23**. As can be appreciated from these views, the portions **732a** and **632a** of the marker and link, respectively, have a length that allows the outer ring **312a** to crimp down

FIGS. **6A-7A**). The marker structure is located to the right of the U-crown adjacent the W-crown formed by the marker link.

FIG. **7C** is an image of scaffold distal end **702** mounted on the balloon **15** distal end **15a** as the catheter makes a similar sharp turn in vasculature. As can be seen, by reducing the bending stiffness of the ring **312a** relative to the inner ring (ring **312b**) the end ring **312a** conforms to the shape of the balloon distal end **15a**. The end ring **312a** does not flare or protrude out as in the case of scaffold **5**.

TABLE 2 shows dimensions associated with examples of fabricated scaffolds corresponding to embodiments of the scaffolds depicted in the figures (when an entry has “-”, it means the same value as the box immediately to the left. Thus, the value for **tm2** for scaffold **400** is 217, and the length **B1** for scaffold **500** and scaffold **700** is 374 and 78, respectively).

TABLE 2

		FIG. 3/ scaffold 300 (μm)	FIG. 4/ scaffold 400 (μm)	FIG. 5/ scaffold 500 (μm)	FIG. 6/ scaffold 600 (μm)	FIG. 7/ scaffold 700 (μm)
Ring spacing (crown-to-crown, adjoined by marker link or non-linear link)	A12	1110	1110	1300	1426	1427
Marker link or non-linear link	tm1	217	—	—	127	127
	tm2	217	—	127	—	—
	ts (max width)	419	—	—	—	749
	c1	n/a	n/a	n/a	596	596
	c2	n/a	n/a	n/a	252	254
Ring spacing (crown-to-crown, no marker link or non-linear link)	A23	1027	—	—	1110	1027
Non-marker link	tL	127	127	—	—	—
Crown length	B1	79	374	—	78	—
Crown length	B2	78	—	—	—	—
Ring width	t1	178	—	—	191	—
	t2	191	—	—	178	191
	t3	191	—	—	—	—
Wall thickness	w	93	—	—	—	—
Wavelength	L1	1833	1922	1922	n/a	n/a
(distance between crests)	L2	1833	1744	1744	n/a	n/a
½ wave length (FIG. 4A: X412 v. X312)	X	956	1089	1089	n/a	n/a

to D-min without interference from the U-shaped portion **636** or marker structure **21**. As can be seen in these views, the structure **21** having holes **22** and U-shaped structure **636** are between a U-crown adjacent a W-crown of the ring on the left and a U crown adjacent a Y crown of the on the right.

Referring to FIG. **7B** there is shown a close up view of section VII from FIG. **7**. As indicated here, the respective lengths of portions **732a** and **732b** is **c1** and **c2**. The lengths of portions **632a** and **632b** are also **c1** and **c2**. Also shown are the lengths **A12** and **A23** for scaffold **700** (lengths **A12**, **A23**, **c1** and **c2** also apply to the lengths for portions **632a** and **632b** and ring spacing for scaffold **600**). The sum of lengths **c1** and **c2** is equal to **A12** less the length of U-shaped portion **636** and width of the crown. In some embodiments **A12** is about 40% greater than **A23**, **c1** is about 36% longer than **c2**. The length **c1** is about equal to the distance between the trough of the adjacent crown and the w-crown formed by portion **732a** or **632a**, less the width of the crown **314** or strut **330**, when the scaffold is in the crimped state (see

Referring to TABLE 2 as can be appreciated from the above examples, and discussed earlier in connection with scaffold **300** compared with scaffold **400**, **500**, **600** and **700**; there are changes in the wavelengths, ½ wavelengths, marker link thickness, length, and orientation, non-marker link type and length, ring spacing, and crown width at the marker link, respectively, in response to the needs relating to crimping and/or delivery of the scaffold through a tortuous artery. These relationships apply for a thin-walled scaffold whether in a crimped state or before crimped configuration. Thus, when reference is made to a crimped scaffold, the relationships above also apply. It is also understand that the features of scaffold **400** and/or **500** that are different from scaffold **300** can be incorporated into scaffolds **600** and **700**. Or the features of scaffold **400** and/or **500** may not be included in the pattern of scaffolds **600** and **700**.

The following discussion relates primary to meeting objective (ii): securing radiopaque material in a scaffold hole provided by a marker structure **21a**, **21b**. As mentioned earlier, it has been discovered that for thin-walled scaffolds

marker material cannot be reliably retained in a marker hole by frictional engagement with walls of a cylindrical hole. To satisfy objective (ii) in preferred embodiments radiopaque material is secured to any of the scaffolds **300**, **400**, **500**, **600** or **700** by swaging a rivet-like body of the marker material to the marker structure **20**, **520** or **720**, while not impeding any of the other objectives (i), (iii) or (iv). The attaching and securement of the marker, in some embodiments, does not include any added polymer, adhesive or re-shaping of the cylindrical hole (other than the deformation that occurs during the swaging process). In preferred embodiments a drug-polymer coating is applied after the marker is placed in the hole.

A marker shaped as a rivet is used in place of the spherical marker **25** intended for cylindrical hole. FIGS. **8A** and **8B** show respective side and top views of the marker **27** shaped as a rivet. The head **28** may include the abluminal surface **27a** or luminal surface **27b** of the rivet **27**. In the drawings, the head **28** includes the abluminal surface **27a**. It may be preferred to have the head **28** be the luminal surface portion of the rivet **27** for assembly purposes, since then the scaffold may be placed over a mandrel and the tail portion of the rivet deformed by a tool (e.g., a pin) applied externally to the scaffold abluminal surface. The rivet **27** has a head diameter  $d_1$  and the shank **27c** diameter  $d_2$  is about equal to the hole **22** diameter. The head **28** has a height of  $h_2$ , which is about the amount the head **28** will extend beyond the abluminal surface **22a** of the strut portion **21a**. While not desirable, it may be an acceptable protrusion for a head **28** that does not extend more than about 25 microns, or from about 5 to 10 microns up to about 25 microns from the abluminal surface **22a**, or a head that extends by an amount no more than about 25% of the strut thickness. The same extent of protrusion beyond the luminal surface **22b** may be tolerated for the deformed tail of the rivet.

Referring to FIG. **9** there is shown the rivet in the hole **22**. The deformed tail **27b'** secures the rivet **27** in the hole **22**. The overall height  $h_1$  is preferably not more than about 40% or about 10%-40% greater than the strut thickness ( $t$ ) and the tail height is about the same as, or within 5 to 20 microns in dimension compared to the head height  $h_2$ .

The rivet **27** may be attached to the hole **22** of the strut portion **21a** by first inserting the rivet **27** into the hole **22** from the bore side of the scaffold so that the head **28** rests on the luminal surface **22b** of the strut portion **21a**. The scaffold is then slipped over a tight fitting mandrel. With the mandrel surface pressed against the head **28** a tool (e.g., a pin) is used to deform the tail **27b** to produce the deformed tail **27b'** in FIG. **9**. In some embodiments, the rivet **27** may be first inserted into the hole **22** from the abluminal side so that head **28** rests on the abluminal surface **22a** of the strut portion **21a**. With the head **28** held in place by a tool or flat surface applied against the abluminal surface, the tail **27b** is deformed by a tool, pin, or mandrel which is inserted into the bore or threaded through the scaffold pattern from an adjacent position on the abluminal surface. In some embodiments the rivet **27** may be a solid body (FIG. **8A-8B**) or a hollow body, e.g., the shank is a hollow tube and the opening extends through the head **28** of the rivet.

In some embodiments a rivet is a hollow or solid cylindrical tube and devoid of a pre-made head **28**. In these embodiments the tube (solid or hollow) may be first fit within the hole then a pinch tool used to form the head and tail portions of the rivet. According to a preferred embodiment there is a process for making radiopaque markers as rivets, mounting the rivets on a scaffold and a scaffold

having such markers mounted thereon. A process for making rivet-shaped markers from beads is described first.

As discussed above head and tail portions of the marker help to hold the marker in place, such as when an external force is applied to the rivet or the link structure is deformed during crimping or balloon expansion, or the scaffold makes a sharp turn in vasculature. In some embodiments however a tail portion, e.g., tail **27b'** of the rivet **27'** in FIG. **9**, is not present. Instead, the rivet's shank portion is deformed to be trapezoidal or frustoconical in shape or to have enlarged end (e.g., rivet **137'** shown in FIG. **15A**). This type of marker has been found to produce increased resistance to being pushed out of the hole of a strut or link when the scaffold is subjected to external forces that deform the link or strut holding the marker.

It is desirable to choose the appropriate size of the bead for forming the rivet. According to some embodiments the bead size, or bead volume to use depends on the strut thickness ( $t$ ), hole diameter ( $D_2$ ), distance between holes ( $D_1$ ) and rim thickness ( $D_2$ ) of the scaffold structure where the rivet will be mounted (e.g., the link struts having holes **22** in FIG. **2A** or **2B**). The stock material may be spherical, or cylindrical. Stock made from a radiopaque material can be obtained from commercially available sources.

According to the disclosure, stock beads are used to make rivet markers for mounting in scaffold holes **22**. In preferred embodiments rivet markers are mounted or engaged with scaffold holes of thin-walled struts or links having a thickness ( $t$ ) that are preferably less than about 100 microns. The steps of a rivet-making process and attachment to a scaffold may be summarized as a six-step process.

STEP 1: select from the stock material a marker bead having a diameter or volume within the desired range, i.e., a diameter or volume suitable for mounting on a scaffold according to the dimensions  $D_0$ ,  $D_1$ ,  $D_2$  and  $t$  (FIG. **2B**). Selection of the marker bead having the desired diameter or volume, or removal of a bead too small from the lot, may be accomplished using a mesh screen. The lot of beads is sifted over a mesh screen. Beads that do not have the minimum diameter or volume will fall through openings in the mesh screen. Alternative methods known in the art may also be used to remove unwanted beads or select the right size bead.

STEP 2: deposit the bead selected from Step 1 on a die plate.

STEP 3: cold form the rivet from the bead by pressing the bead into the die plate. At temperatures close to ambient temperature force the bead through the die (e.g., using a plate, mandrel head, pin or tapered ram head) to thereby re-shape the bead into a rivet defined by the die shape and volume of the bead relative to the volume of the die receiving the bead.

STEP 4: remove the formed rivets from the die plate. The formed rivets, which can have a total length of about 190-195 microns and diameter of about 300-305 microns, are removed using a tool having a vacuum tube. The air pressure is adjusted to grip a rivet at, or release it from the tip. The rivet is removed from the die by placing the opening of the vacuum tube over the head of the rivet, reducing the air pressure within the tube to cause the head to adhere to, or become sucked into the tube tip (due to the difference in pressure) and lifting the rivet from the die.

STEP 5: while the rivet remains attached to the tip of the tube, move the rivet to a position above the hole of the scaffold, place the rivet into the hole using the same tool, then increase the air pressure within the tool to ambient air pressure. The rivet is released from the tool.

STEP 6: deform the rivet and/or hole to enhance the engagement or resistance to dislodgment of the marker from the hole, e.g., FIGS. 14A-14C.

It will be appreciated that according to STEPS 1-6 there is overcome the problem with the handling of non-spherical beads. For instance, the steps 1-6 above, wherein the rivet need not be re-orientated after being formed from a spherical bead, overcomes the problem of orientated spherical beads so that they can be aligned and placed into holes.

Referring to FIGS. 16A, 16B and 16C there is shown steps associated with transferring a formed rivet 127' (or 137') from a die 200 (or 205) to the scaffold strut hole 22 using a vacuum tool 350. As can be appreciated, the formed radiopaque marker 127' is extremely small, i.e., less than 1 millimeter in its largest dimension, as such the handling and orientation of the marker 127' for placement into the hole 22 is complicated (in contrast to placement of a sphere into the hole) because of the need to orient the shank properly with respect to the hole. For this reason the swaging or forging process is combined with placing into the scaffold hole, by removing the rivet 127' from the hole 200 with the tool 250, FIG. 16A, maintaining the orientation by keeping the rivet 127' attached to the tool, FIGS. 16B-16C, and then placing the rivet 127' into the hole 22a, FIG. 16C.

With reference to FIGS. 10 and 11A there is shown a first embodiment of a die 200 and marker 127 formed using the die 200, respectively, according to the disclosure. The die is a flat plate having a top surface 201 and a through hole extending from an upper end 201 to a lower end. The hole has an upper end diameter dp2 and lower end diameter dp1 less than dp2. The hole 202 is preferably circular throughout, although in other embodiments the hole may be rectangular or hexagonal over the thickness tp, in which case dp1 and dp2 are lengths or extents across the hole (as opposed to diameters). And the plate 200 has a height tp. The taper angle is related to dp2 and dp1 by the expression  $\tan \phi = \frac{1}{2}(dp2 - dp1)/tp$ , which in a preferred embodiment  $\phi$  is 1 to 5 degrees, 5-10 degrees, 3-5, or 2-4 degrees. The shape of die 200 produces a frustoconical shank, as depicted in FIG. 18A. A stock bead (not shown) is placed on the upper end of the opening 202 so that the bead sits partially within the hole 202. A flat plate, mandrel or pin ("ram head") is then pressed into the top of the bead so that the bead is forced into the hole 202. The bead is forced into the hole until the ram head is about distance HH from the surface 201. The rivet 127 formed from the foregoing forming process has the taper angle  $\phi$  over all of, or a substantial portion of the shank height SH and the shank shape is frustoconical. The overall rivet height is HR, the head thickness is HH and the head diameter is HD. In some embodiments the angle  $\phi$  may be sufficiently small so that the shank may be treated as a cylinder, or  $\phi$  is about zero.

With reference to FIGS. 12 and 13A there is shown a second embodiment of a die 205 and marker 137 formed using the die 205, respectively, according to the disclosure. The die is a flat plate having a top surface 206 and a hole extending from an upper end 301 to a lower end. The hole has a constant diameter dcb1 throughout. A counter bore is formed on the upper end 206. The counter bore diameter is dcb2. The hole 207 is preferably circular throughout, although in other embodiments the hole 207 may be rectangular or hexagonal, in which case dcb1 is a length or extent across the hole (as opposed to a diameter). The shape of die 200 produces a rivet having a stepped cylindrical shape or cylindrical shank with a head, as depicted in FIG. 13A. A stock bead (not shown) is placed on the upper end of the opening 207 so that the bead sits partially within the

hole 207. A ram head is then pressed into the top of the bead so that the bead is forced into the hole 207. The bead is forced into the hole until the ram head is about distance HH from the surface 206. The rivet 137 formed from the foregoing forming process takes the shape shown in FIG. 13A. The overall rivet height is SH+HH, the head thickness is HH, the shank height is SH and the head diameter is HD.

TABLES 3 and 4, below, provide examples of rivet dimensions for a rivet intended for being secured within a link hole 22 such as shown in FIG. 2A. In this example the thickness of the link is 100 microns and the values in microns ( $\mu\text{m}$ ) for D0, D1 and D2 are 241, 64 and 64, respectively.

Values for the die 200 dimensions tp, dp2 and dp1 are 178, 229 and 183. The resulting formed rivet dimensions using die 200 are shown in TABLE 3. As can be appreciated from the results, the shank length (or height) is more than 150% of the link thickness and the rivet head diameter (HD) is significantly larger than the hole 22 diameter. The lower portion of the shank is relied on to form a tail portion of the rivet. The mean and standard deviation for HD, SD, and SL are based on the respective "n" samples of rivets measured.

TABLE 3

Rivet formation using tapered plate (FIG. 18A)				
		inches	microns	n
Rivet head diameter (HD)	mean	0.0123	312	51
from taper plate	standard deviation	0.0015	38	
O.D. Rivet head diameter	mean	0.0132	335	27
post swage	standard deviation	0.0011	28	
Shank Diameter (SD)	mean	0.0089	226	51
	standard deviation	0.0004	10	
Shank Length (SL)	mean	0.0072	183	37
	standard deviation	0.0009	23	

Values for the die 300 dimensions dcb2 and dcb1 are 305 and 203. The resulting formed rivet dimensions using die 300 are shown in TABLE 4. The mean and standard deviation for HD, SD, HH and SL are based on the respective "n" samples of rivets measured.

TABLE 4

Rivet formation using counter bore plate (FIG. 13A)				
		inches	microns	n
Rivet head diameter (HD)	mean	0.012	305	19
from Die	standard deviation	0.0003	10	
O.D. Rivet head diameter	mean	0.013	330	30
post swage	standard deviation	0.0007	18	
Rivet head height (HH)	mean	0.001	25	31
Shank Diameter (SD)	standard deviation	0.008	203	31
Shank Length (SL)	mean	0.0075	190	24
	standard deviation	0.0008	20	

In TABLES 3 and 4 "O.D. Rivet head diameter post-swage" refers to the outer diameter of the rivet marker head after the rivet marker is pressed into the scaffold hole.

Discussed now are examples of processes for mounting either of the rivets 127, 137 to the scaffold hole 22. According to some embodiments the rivet shank is placed into the hole 22 from the abluminal or outer side of the scaffold, so that the head sits on the abluminal surface 22a. The rivet may instead be placed from the luminal side of the hole. The rivet is firmly pressed into the hole so that a maximum portion of the shank extends from the luminal or abluminal sides, respectively.

For the rivet **127** after it is placed in the hole **22** the side opposite the head is subjected to a swaging process. With reference to FIG. **11B** there is shown in cross-section the deformed rivet **127'** in the hole **22**. The rivet **127'** has a head **127a'** that extends from the surface **22a** by an amount  $h_2$ . The length  $h_2$  may be about 25 microns, between 25 and 50 microns or between 5 and 50 microns. The same dimensions apply to a tail **127b'** that extends from the opposite surface of the link (e.g., luminal surface). The diameter of the head **127a'** can be larger than the tail, or the tail **127b'** diameter can be larger than the head **127a'** diameter. The tail portion is formed from the extended shank length that protrudes from the link surface by swaging. The tail **127b'** is formed by swaging. For example, the rivet **127** is placed in from surface **22a** (abluminal side) so that a significant portion of the shank length, e.g., 50% of the strut thickness, extends from the luminal side. A cylindrical mandrel (not shown) is placed through the scaffold's bore. This mandrel has an outer diameter slightly less than an inner diameter of the scaffold and provides a swaging surface to form the tail **127b'**. The mandrel is rolled back and forth over shank portion extending from the luminal surface. This motion causes the shank material to flatten out around the hole, thereby producing the tail portion **127b'**. The resulting rivet **127'** is secured in place, at least in part, by the tail portion **127b'** resisting forces tending to push the rivet towards the abluminal side of the hole and the head portion **127a'** resisting forces tending to push the rivet towards the luminal side of the hole **22**. As shown, the deformation of the shank produces the tail **127b'** having a flange disposed on the surface **22b**. The flange may be circular like the head and may have a flange radial length greater or less than the radial length of the flange of the head **127a'**.

With reference to FIGS. **15A** and **15B**, a stepped mandrel is used in conjunction with a ram head to produce the rivet **137'** from rivet **137**. The rivet has a shank **137'** that is reformed from, e.g., a generally-cylindrical shape when using the die **205**, FIG. **12**, to the shape shown in FIGS. **15A** through **15C**. This shank shape may be characterized by a taper angle  $\theta$  of magnitude of from between about 5 and 15 degrees, 5 to 9 degrees, or about 3 to 8 degrees. The shank according to some embodiments of a rivet in the hole **22** is frustoconical in shape, wherein the shank end opposite, or distal of the head **137a'**, or end **137b'** is larger or has a larger diameter than the shank portion proximal or nearest the head **137a'**. The deformed shank **22'** may have a shank diameter  $S_2$  nearest one of the abluminal and luminal side openings of the hole **22'** that is larger than the shank diameter  $S_1$  nearest the other of the luminal and abluminal side opening, or  $S_2 > S_1$ . According to some embodiments, as shown in FIG. **15A** the cylindrical hole **22** is also deformed into the hole **22'** that has an opening at surface **22b** larger than the hole opening at surface **22a**. According to some embodiments both the hole **22** and rivet **137** are deformed when the rivet **137** is mounted on the scaffold.

The structure illustrated in FIG. **15A** may be made by a second process of attaching a rivet marker to a scaffold hole **22**. In contrast to the first process a tool is not rolled across the surface where the shank tail portion protrudes from the hole opening. Instead, the shank tail end is pushed directly into a non-compliant surface, which can be a surface of a metal mandrel. The rivet is forced to deform by a compression force between the surface of the mandrel and head of a ram **234**, which pushes the rivet into the mandrel surface. The first process producing the deformed rivet **127'** by contrast is formed by a combination of rolling a hard surface into the shank and a restraint on the head **127a**, which holds the rivet head against the surface **22a** while the tail end **127b** is being swaged. Under the second process the force line of action is completely along the axis of the rivet, or perpendicular to the rivet head. The result is a flattened or widened shank portion and deformed hole with little or no flange or rim formed from the tail portion of the shank.

The second process is now described in further detail with reference to FIGS. **14A-14C**. The scaffold **400** is placed over a stepped mandrel **230**. This mandrel has a first outer diameter and a second outer diameter, which is less than the first outer diameter. The scaffold portion holding the marker **137** is placed over the lower diameter portion of the mandrel **230**. The larger diameter portion of the mandrel **230** holds the adjacent parts of the scaffold. The lower diameter part of the mandrel **230** has a surface **230a** and the larger diameter portion has a surface **230b**. As shown in FIGS. **14B**, **14C** the ram **234** pushes with a force  $F$  (FIG. **14B**) the scaffold portion holding marker **137** into the mandrel surface **230a**, which causes this scaffold end to deflect a distance "d" towards the surface **230a** (FIG. **14A**). After the scaffold reaches the surface **230a**, the ram **234** continues to push into the scaffold portion holding the marker (by pressing directly against the head **137a**) to create the deformed marker **137'** and hole **22'** as shown in FIG. **15A**. The surface **230a** chosen may be smooth or free of grooves, pitting, depressions or other surface irregularities (other than a surface of a cylinder) that would inhibit flow of material during swaging. In a preferred embodiment the mandrel surface is smooth compared to the surface of the head **234** pressed into the rivet marker **137**. That is, the coefficient of friction ( $\mu$ ) between the head **234** and surface **137a'** is greater than  $\mu$  between surface **230a** of mandrel **230** and surface **137b'**.

The shape of the deformed shank **137'** and hole **22'** shown in FIG. **15b** produced higher push-out forces than previously believed (a "push-out force" means the force needed to dislodge the marker from the hole). Indeed, unexpectedly it was discovered that the deformed rivet **137'** and hole **22'** had a higher resistance to dislodgement than a marker fit into a link having an over 50% higher thickness, irrespective of the presence of the head **137a'**. For example, tests for a minimum dislodgment force needed to push the rivet **137'** out from the side **22a** of the hole **22'** of a strut having a 100 micron thickness were higher than the dislodgment force needed to push out a marker mounted according to US20070156230 (FIGS. **8A**, **8B** or where the sphere is deformed more into a cylinder when in the depot, thus increasing the surface-to-surface contact to a maximum) and for a hole of a strut having an about 50%-higher thickness (158 microns vs. 100 microns). As TABLE 4 demonstrates:



TABLE 4

Scaffold (TABLE 1)	Marker process	Bead volume ( $\mu\text{m}^3 \times 10^6$ )	US20070156230 (FIGS. 8A, 8B)	Interior hole surface area (thickness $\times$ diameter $\times \pi$ ) ( $\mu\text{m}^2 \times 10^3$ )	Push-out force (gram- force) from luminal to abluminal side of link
A	Press sphere into hole (US20070156230, FIGS. 8A, 8B)	6.76	wall thickness 158 $\mu\text{m}$ and hole diameter 234 $\mu\text{m}$	116.2	51.5 (n = 8)
B	FIGS. 14A-14C and using rivet marker 137	6.76	wall thickness 100 $\mu\text{m}$ and hole diameter 241 $\mu\text{m}$	75.7	78.6 (n = 31)

There are higher push-out forces for scaffold B, even though scaffold A has more surface area for contact with the marker, thus higher frictional forces resisting dislodgment. This result indicates that the deformation that occurs during the swaging process resulting in the deformed rivet marker and hole of FIG. 15A has a significant effect on the push-out force (note: the gram-force push-out force reported in TABLE 4 was applied to the luminal side 22b for scaffold B). Given the more than 50% higher wall thickness Scaffold A should have had a higher dislodgment force (the same bead material, bead volume and poly(L-lactide) scaffold material for Scaffold A and B). The higher dislodgment force can be explained by the shape of the deformed shank and hole, which essentially produces a lower portion 137b' that is significantly larger than the opening 22a of the strut 22. Thus, the dislodgment force must be high enough to deform the opening 22a' and/or shank portion 137b' in order to dislodge the marker from the 22a side of hole 22' (as opposed to only needing to overcome essentially a frictional force between the material and walls of the hole).

The shape 137' in FIG. 15B may be formed by a swaging process that deforms the rivet while it sits inside the hole 22. The rivet may have the shape and/or characteristics of rivet 27, 127 or 137 before swaging. The flow of rivet material transversely (shear flow) during swaging near tail portion 137b' causes it to expand out and also yield (enlarge) the strut hole nearer to opening 22b'. This produces the trapezoidal-like or frustoconical shape of the rivet shank and hole. The swaging process of FIGS. 14A-14C applies equal and opposite forces that are about co-linear with the axis of symmetry of the rivet (as opposed to a rolling motion on one side). If instead a cylinder or sphere (as opposed to a rivet) were placed in the hole 22 and about the same coefficient of friction (COF) existed between the swaging surface 230a and tail 137b as the COF between the swaging surface 234 and the head 137a, but otherwise the same swaging process as in FIGS. 14A-14C, it is believed that the result would be a more symmetric deformed marker, e.g., a squashed cylinder or barrel-shaped marker depending on the COF, such as the shape shown in US20070156230. This result can be appreciated from Kajtoch, *J Strain in the Upsetting Process*, Metallurgy and Foundry Engineering, Vol. 33, 2007, No. 1 (discussing influence of coefficient of friction between ram and ingot on resulting shapes for slenderness ratios greater than 2). The shape of the radiopaque material forced into the hole is also a factor, e.g., a rivet 137 verses a sphere (scaffold A). The presence of the head on one side results in a shank forming an asymmetric shape about the strut mid-plane axis. It is believed that a combination of the rivet shape and coefficient of friction differences produced the favorable result.

In a preferred embodiment a smooth mandrel 230 surface 230a presses against the surface 137b, as compared to a more rough surface of the head 234 that presses against the surface 137a. In a preferred embodiment the coefficient of friction for the abluminal side was greater than 0.17 or  $\mu > 0.17$ , whereas the coefficient of friction on the luminal side was less than 0.17 or  $\mu < 0.17$ . As discussed above, the effect of a difference in the coefficient of friction can be explained by the restraint on shear or later material flow near the end abutting the respective swaging head. If the coefficient of friction is sufficiently low then the surface area expands out laterally, as opposed to being held relatively constant. Thus, since  $\mu$  is less on the luminal side there is more lateral flow than on the abluminal side. The result, when combined with use the rivet shape, is believed to be the frustoconical shape as disclosed, e.g., as shown in FIGS. 15A-15B, which may be thought of as a shank having a locking angle  $\theta$ .

There may be a heating step for a scaffold following marker placement. In some embodiments this heating step may correspond to a rejuvenation step of the scaffold polymer, prior to crimping, to remove aging effects of the polymer.

Thermal rejuvenation (including thermal treatment of a bioresorbable scaffold above TG, but below melting temperature ( $T_m$ ) of the polymer scaffold) prior to a crimping process may reverse or remove the physical ageing of a polymeric scaffold, which may reduce crimping damage (e.g., at the crests of a scaffold) and/or instances of dislodgment of a marker.

According to some embodiments a scaffold is thermally treated, mechanically strained, or solvent treated to induce a rejuvenation or erasure of ageing in a polymer shortly before crimping the scaffold to a balloon and after marker placement. Rejuvenation erases or reverses changes in physical properties caused by physical ageing by returning the polymer to a less aged or even an un-aged state. Physical ageing causes the polymer to move toward a thermodynamic equilibrium state, while rejuvenation moves the material away from thermodynamic equilibrium. Therefore, rejuvenation may modify properties of a polymer in a direction opposite to that caused by physical ageing. For example, rejuvenation may decrease density (increase specific volume) of the polymer, increase elongation at break of the polymer, decrease modulus of the polymer, increase enthalpy, or any combination thereof.

According to some embodiments, rejuvenation is desired for reversal or erasure of physical ageing of a polymer that was previously processed. Rejuvenation is not however intended to remove, reverse, or erase memory of previous

processing steps. Therefore, rejuvenation also does not educate or impart memory to a scaffold or tube. Memory may refer to transient polymer chain structure and transient polymer properties provided by previous processing steps. This includes processing steps that radially strengthen a tube from which a scaffold is formed by inducing a biaxial orientation of polymer chains in the tube as described herein.

In reference to a marker—scaffold integrity or resistance to dislodgment during crimping, it has been found that a heating step can help reduce instances where crimping causes dislodgment of a marker. According to some embodiments, any of the foregoing embodiments for a marker held within the scaffold hole **22** can include, after the marker has been placed in the hole, a heating step shortly before crimping, e.g., within 24 hours of crimping. It has been found that the scaffold is better able to retain the marker in the hole **22** following heating. A mechanical strain, e.g. a limited radial expansion, or thermal rejuvenation (raise the scaffold temperature above the glass transition temperature (TG) of the load-bearing portion of the scaffold polymer for a brief time period) can have a beneficial effect on scaffold structural integrity following crimping and/or after balloon expansion from a crimped state.

In particular, these strain-inducing processes tend to beneficially affect the hole **22** dimensions surrounding the marker when the hole is deformed in the manner discussed earlier in connection with FIGS. **15A-15B**.

According to some embodiments the scaffold after marker placement is heated to about 20 degrees, or 30 degrees above the glass transition temperature of the polymer for a period of between 10-20 minutes; more preferably the scaffold load bearing structure (e.g., the portion made from a polymer tube or sheet of material) is a polymer comprising poly(L-lactide) and its temperature is raised to between about 80 and 85 Deg. C for 10-20 minutes following marker placement.

According to some embodiments it has been found that raising the temperature of the scaffold after marker placement re-shaped portions of the hole **22** to improve the fit of the marker in the hole. With reference to FIG. **15C** after the rivet marker **137** is placed in the hole **22** according to the second process the hole shape deforms to produce a lip or edge **140** at the end **137b'**, which may produce a higher resistance to dislodgment than for a scaffold-marker structure not subsequently treated by a rejuvenation step. The surface **140a** of the lip **140** interferes more with dislodgment of the marker when a force is directed towards the end **22b'**.

In accordance with the foregoing objectives of achieving a desired crimp profile for a thin-walled scaffold there is a method for crimping such a scaffold to a balloon that meets the following needs:

Structural integrity: avoiding damage to the scaffold's structural integrity when the scaffold is crimped to the balloon, or expanded by the balloon.

Safe delivery to an implant site: avoiding dislodgement or separation of the scaffold from the balloon during transit to an implant site.

Uniformity of expansion: avoiding non-uniform expansion of scaffold rings, which can lead to structural failure and/or reduced fatigue life.

As previously reported in US20140096357 a scaffold is not as resilient as a stent made from metal, which is highly ductile. The needs therefore for satisfying all of the above needs are especially for a thin-walled scaffold that can fracture more easily during crimping or balloon expansion.

FIGS. **17A-17B** illustrate steps associated with a crimping process for crimping to a balloon catheter (FIG. **3D**) for the thin-walled scaffolds **300**, **400**, **500**, **600** or **700** according to

the disclosure. It has been found that this crimping process can satisfy all the above needs for a scaffold crimped to D-min. In this example there is a crimping process described for crimping a 3.5 mm scaffold to a 3.0 mm semi-compliant PEBAX balloon. FIG. **17B** illustrates in graphical form the crimping portion of the FIG. **17A** flow—a graph of scaffold diameter verses time with a balloon pressure of between about 20-70 psi (or 1 atm up to the fully or over-inflated balloon pressure) applied throughout substantially all of the crimping process. For example, the balloon pressure is maintained at 70 psi for steps A-G, then the pressure is allowed to decrease (or deflated) to 50 psi (or 1 atm) for the period G-H. Balloon pressure is removed at point H. No balloon pressure is used for steps H-J for purposes of achieving a low crossing profile or crimping to D-min and avoiding damage to the balloon.

FIG. **17A** indicates three possibilities for crimping, depending on need. First, there are two balloons used: Balloon A and Balloon B. Balloon B is used for the pre-crimp step(s) and Balloon A (used with the delivery system) is used for the final crimp. Second, there is only one balloon used (Balloon A) for the entire crimp process including the verify alignment check. In this case, the scaffold inner diameter is larger than the fully or overinflated Balloon A. As such, during pre-crimp there may be shifting on the balloon. Third, there is only one balloon used (Balloon A) for the entire crimp process without a verify final alignment check. In this case, the balloon for the delivery system has a fully or overinflated state that is about equal to the inner diameter of the scaffold inner diameter.

Stage I: The scaffold supported on the fully inflated balloon of the balloon-catheter is placed within the crimp head. The balloon when inflated and supporting the scaffold in this state has substantially all folds removed. In a preferred embodiment the catheter's balloon (i.e., the balloon used in the final product—a stent delivery system) is used for Stage I through Stage II. In other embodiments it may be preferred to use a second, larger balloon for Stage I and II (as explained in more detail below). The blades of the crimper are heated to raise the scaffold temperature to a crimping temperature. In the preferred embodiments the crimping temperature is between a lower end of the glass transition temperature for the polymer (TG) and 15 degrees between TG.

After the scaffold reaches the crimping temperature, the iris of the crimper closes to reduce the scaffold inner diameter (ID) to slightly less than the outer diameter (OD) of the fully or over inflated balloon (e.g., from 3.45 mm to about 3.05 mm for the PEBAX 3.0 mm semi compliant balloon inflated to a diameter of about 3.2 mm). In this example, Balloon B would be used for the diameter reduction down to the 3.0 mm balloon size, or the Balloon A size (e.g., the 3.0 mm balloon).

Stage II: The crimper jaws are held at the 3.05 mm diameter and maintained at this diameter for a second dwell period at the crimping temperature. After Stage II the scaffold has about 90% of its pre-crimp diameter.

The foregoing Steps I-II reduce the scaffold diameter down to the size of the fully inflated balloon of the stent delivery system (i.e., Balloon A). Since at the time of the initial alignment check (before any crimping) the scaffold inner diameter was larger than the balloon fully inflated diameter (e.g. the scaffold diameter is about 109%-116% of the fully inflated balloon diameter for a balloon with diameters of 3.0 mm to 3.2 mm, respectively) there is a possibility that the scaffold shifts longitudinally (relative to the balloon) while being crimped down to the balloon size. Given this

possibility, the scaffold is removed from the crimper and its alignment on the balloon is checked relative to proximal and distal balloon markers.

“Verify final alignment” step: When the scaffold requires adjustment on the balloon, a technician makes manual adjustments to move the scaffold into position. It has been found difficult, however, to make these minor adjustments while the scaffold rests on the fully inflated balloon and has an inner diameter slightly less than the balloon’s outer diameter. To address this need, the balloon pressure is slightly decreased, or the balloon temporarily deflated so that the re-alignment may be done more easily. When the scaffold is properly re-aligned between the balloon markers, the scaffold and fully inflated balloon are placed back into the crimper. With the scaffold inner diameter and balloon sizes now about equal the final crimping of the scaffold to the catheter’s balloon can commence. To ensure no further longitudinal movement of the scaffold relative to the balloon, it is preferred to have the scaffold diameter be slightly less than the balloon fully inflated diameter prior to the start of Stage III. As noted above, where two balloons are used, Balloon B is replaced with Balloon A, alignment is done with respect to Balloon A and the scaffold is crimped down to the final diameter on Balloon B.

Stage III: The scaffold and balloon are returned to the crimper. The jaws are closed to a diameter about the same as, or slightly larger than in Stage II (to account for recoil occurring during the alignment check). The crimper jaws are held at this diameter for a third dwell time, which may be the time needed for the scaffold to return to the crimping temperature.

The iris diameter is then reduced to an ID corresponding to about, or slightly less than the OD for the balloon if the balloon were not pressurized and had randomly distributed folds. That is, the scaffold is crimped down to the approximate OD for the balloon if it were pressurized then deflated so that substantially all pre-made folds are replaced by random folds. For example, the iris diameter is reduced down to about 1.78 mm for the 3.5 mm scaffold. After this diameter reduction the scaffold OD is about 60% of its diameter at Stage III and about 50% of its starting, or pre-crimp OD.

Stage IV: After the scaffold OD is reduced to about 50% of its starting diameter, the crimper jaws are held at this diameter for a third dwell time. In a preferred embodiment balloon pressure is slightly decreased during this dwell. For example, for the 3.0 mm semi-compliant PEBAX balloon the pressure is decreased from 70 psi to 50 psi during the Stage IV dwell. This decrease is preferred to achieve a lower crossing profile and/or to protect balloon material from overstretch.

Following the Stage IV dwell period, the balloon is deflated or allowed to return to atmospheric pressure and the iris of the crimper is reduced down to a final crimp OD, e.g., 1.01 mm or about 30% of its pre-crimp OD. This balloon deflation may occur by opening the valve supplying the pressurized gas to the balloon while, or just before the iris diameter is reduced to the final crimp diameter.

The crimper jaws are then held at the final crimp diameter for about a 170 second dwell period, or between 100 and 200 seconds with the crimping temperature maintained (i.e., scaffold temperature being between 15 degrees below TG and about TG) or without the crimping temperature being maintained. This final dwell period is intended to reduce the amount of scaffold recoil when the crimped scaffold is removed from the crimper. Immediately following the 170 second dwell the scaffold is removed and a retaining sheath

is placed over the scaffold to further aid in reducing recoil. A leak test may be done after the final stage crimping.

It may be necessary to provide auxiliary pressure sources for a balloon in order to maintain a relatively constant pressure throughout the diameter reduction and dwell periods (as illustrated in the above example). Indeed, in one embodiment it was found that during diameter reduction there was a pressure drop in the balloon. To address this pressure drop, a secondary pressure source was used to maintain the same pressure during diameter reductions as during dwell periods.

The foregoing example of a preferred crimping process, which selectively pressurizes the balloon throughout the crimping steps, is expected to provide three benefits while minimizing any possible overstretching of the balloon. The first benefit is increased scaffold-balloon retention. By maintaining relatively high pressure in the balloon through most of the crimping steps, more balloon material should become disposed between struts of the scaffold since balloon material is being pressed more into the scaffold, than the case when crimping is done without balloon pressurization, or only after the scaffold is substantially reduced in diameter. Additionally, it is expected that by substantially removing folds before any diameter reduction, the balloon material becomes more compliant. As such, more balloon material is able extend between struts, rather than being pressed between the scaffold and catheter shaft when the scaffold is being crimped.

The second benefit of balloon pressurization is more uniform expansion of the crimped scaffold when the balloon is expanded. When the balloon is inflated from the beginning, before any crimping takes place and when there is the greatest space available for the balloon to unfold within the mounted scaffold, balloon material become more uniformly disposed about the circumference of the catheter shaft after crimping. In a preferred embodiment the balloon is fully inflated and held at this inflated state for at least 10 seconds before any crimping to ensure all pre-made folds are removed. If the balloon is only partially expanded, as in the case where the balloon is inflated after the scaffold has been partially crimped (thereby leaving less space available for the balloon to fully unfold), fold lines or balloon memory not removed by balloon pressure, it is believed that the presence of folds or partial folds causes balloon material to shift or displace during crimping, thereby resulting in a more non-uniform distribution of balloon material about the circumference of the catheter shaft after crimping.

The third benefit is avoidance of out of plane twisting or overlapping scaffold struts, which can result in loss of strength, cracks or fracture in struts. As discussed earlier, support of the scaffold within crimper with an inflated balloon is believed to counteract or minimize any tendency for struts to move out of alignment.

The foregoing benefits may be achieved without risk that balloon material will be excessively stretched during the crimping process when balloon pressure is selectively controlled. Referring to FIG. 3B, the pressure range provided is 20-70 psi. The upper end of this pressure range forms the fully inflated balloon in the case of the balloon used in the example and may be maintained for the first three stages. Balloon pressure reduction to 50 and 20 psi for Stage IV follows. It was found through several tests that maintaining a constant, and consistent fully inflated balloon pressure up until the beginning of stage IV or after the crimped scaffold had reached about ½ of the original scaffold diameter, followed by a slight decrease in pressure, provided a good

balance of stent retention, uniform expansion, low crossing profile, uniform crimping and avoidance of damage to balloon material.

As noted earlier, there are three possibilities for crimping: use two balloons—Balloon A and Balloon B. Balloon B is used for the pre-crimp step (a) and Balloon A (used with the delivery system) is used for the final crimp. Second, there is only one balloon used (Balloon A) for the entire crimp process including the verify alignment check. In this case, the scaffold inner diameter is larger than the fully or over-inflated Balloon A. As such, during pre-crimp there may be shifting on the balloon. Third, there is only one balloon used (Balloon A) for the entire crimp process without a verify final alignment check. In this case, the balloon for the delivery system has a sully or overinflated state that is about equal to the inner diameter of the scaffold inner diameter. These different embodiments are described further, below.

In some embodiments a process is described by the example in FIGS. 17A-17B and as described above, with the following exception. Two balloons are used—a sacrificial or secondary balloon (Balloon B) in addition to the catheter's balloon (Balloon A)—as opposed to only Balloon A as in the above example of a preferred embodiment. Balloon B is a balloon that has a larger nominally inflated balloon diameter than Balloon A, or is capable of being over inflated to a larger diameter than Balloon A. Balloon B is used for Stages I and II. Balloon B is selected to have a fully inflated diameter that is the same as, or slightly larger than the original inner diameter of the scaffold. One advantage of this alternative embodiment is that the scaffold is supported by a balloon throughout the crimping process (as opposed to the above example where Balloon A can provide little or no radial support for the scaffold since there is a gap at Stage I). After Stage II, the scaffold is removed from the crimper and Balloon B is replaced by Balloon A. Thereafter, the crimping process continues as described earlier.

The above description of illustrated embodiments of the invention, including what is described in the Abstract, is not intended to be exhaustive or to limit the invention to the precise forms disclosed. While specific embodiments of, and examples for, the invention are described herein for illustrative purposes, various modifications are possible within the scope of the invention, as those skilled in the relevant art will recognize.

These modifications can be made to the invention in light of the above detailed description. The terms used in claims should not be construed to limit the invention to the specific embodiments disclosed in the specification.

What is claimed is:

1. A medical device, comprising:

a thin-walled scaffold having proximal and distal end portions formed by a network of rings interconnected by links, wherein each ring has a plurality of crowns, including U crowns and at least one Y crown or W crown, each ring extends circumferentially in an undulating fashion along a vertical axis (B-B) perpendicular to a longitudinal axis (A-A);

the thin-walled scaffold having a wall thickness of less than 125 microns;

the proximal end portion includes an outermost proximal ring adjoined to a first proximal ring by first proximal links, and the first proximal ring is adjoined to a second proximal ring by second proximal links;

the distal end portion includes an outermost distal ring adjoined to a first distal ring by first distal links, and the first distal ring is adjoined to a second distal ring by second distal links;

wherein

(1) the first proximal links include a proximal marker link comprising a proximal hole containing a radiopaque material, and

(2) the first distal links are devoid of a link holding the radiopaque material.

2. The medical device of claim 1, wherein the outermost proximal ring is adjoined to the first proximal ring by only the first proximal links, and a first proximal link extends parallel to axis A-A and has a constant cross-sectional moment of inertia.

3. The medical device of claim 2, wherein the outermost distal ring is adjoined to the first distal ring by only the first distal links, and each of the first distal links are non-linear links.

4. The medical device of claim 1, wherein the proximal marker link has a first end and a second end, the first end forming one of a W crown and a Y crown with the outermost proximal ring and the second end forming the other of the W crown and Y crown with the first proximal ring.

5. The medical device of claim 1, wherein the first distal ring and second distal ring are adjoined by a distal marker link comprising the radiopaque material.

6. The medical device of claim 5, wherein the distal marker link includes a structure that forms two holes, each hole containing the radiopaque material.

7. The medical device of claim 6, wherein the distal marker link has a first end and a second end, the first end forming one of a W crown and Y crown with the first distal ring and the second end forming the other of the W crown and Y crown with the second distal ring, wherein the W crown is wider than the Y crown.

8. The medical device of claim 1, wherein the proximal marker link further comprises:

a rim substantially circumscribing the proximal hole and defining a hole wall and a strut rim, wherein a distance between the wall and rim is D;

a marker comprising the radiopaque material, the marker being disposed in the hole and including a head having a flange disposed on the rim;

wherein the flange has a radial length of between  $\frac{1}{2} D$  and less than D;

wherein the wall thickness (t) is related to a length (L) of the marker measured between an abluminal and luminal surface of the marker by  $1.1 \leq (L/t) \leq 1.8$ .

9. A medical device, comprising:

a balloon catheter having a balloon, the balloon having a distal balloon end and proximal balloon end;

a thin-walled scaffold crimped to the balloon, the thin-walled scaffold having proximal and distal end portions formed by a network of rings interconnected by links, wherein each ring has a plurality of crowns, including U crowns and at least one Y crown or W crown, each ring extends circumferentially in an undulating fashion along a vertical axis (B-B) perpendicular to a longitudinal axis (A-A);

the thin-walled scaffold having a wall thickness of less than 125 microns;

the proximal end portion, crimped to the proximal balloon end, includes an outermost proximal ring adjoined to a first proximal ring by first proximal links, and the first proximal ring is adjoined to a second proximal ring by second proximal links;

the distal end portion, crimped to the distal balloon end, includes an outermost distal ring adjoined to a first

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distal ring by first distal links, and the first distal ring is adjoined to a second distal ring by second distal links;

wherein

(3) the first proximal links include a proximal marker link comprising a proximal hole containing a radiopaque material,

(4) the first distal links are devoid of a link holding the radiopaque material, and

(5) the first distal links comprise non-linear links;

wherein the thin-walled scaffold has an outer diameter of about D-min; and

wherein

$$D\text{-min}=(1/\pi)\times[(n\times\text{strut\_width})+(m\times\text{link\_width})]+2*t,$$

“n” is the number of struts in a ring,

“strut\_width” is the width of a strut,

“m” is the number of links adjoining adjacent rings,

“link\_width” is the width of a link, and

“t” is the wall thickness.

10. The medical device of claim 9, wherein the outermost proximal ring is adjoined to the first proximal ring only by the first proximal links, each of which extend parallel to axis A-A and have a constant cross-sectional moment of inertia.

11. The medical device of claim 9, wherein the non-linear links are U-shaped links.

12. The medical device of claim 9, wherein the second distal links comprise a distal marker link comprising a distal hole containing the radiopaque material, the distal marker link having a first end and a second end, the first end forming one of a W crown and Y crown with the first distal ring and the second end forming the other of the W crown and Y crown with the second distal ring.

13. The medical device of claim 12, wherein a first link portion of the distal marker link extends from the W-crown to a structure forming the distal hole and a second hole, and

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a second link portion of the distal marker link extends from the Y-crown to the structure, wherein a first link portion length is greater than a second link portion length.

14. The medical device of claim 13,

wherein the first link portion length is about equal to the sum of twice a ring width and a length of a strut extending between crowns of a ring.

15. The medical device of claim 9, wherein a non-linear link has a first end and a second end, the first end forming one of a W crown and Y crown with the outermost distal ring and the second end forming the other of the W crown and Y crown with the first distal ring, and wherein the non-linear link includes a U-shaped structure between the W crown and Y crown.

16. The medical device of claim 15, wherein a first link portion of the non-linear link extends from the W-crown to the U-shaped structure, and a second link portion of the non-linear link extends from the Y-crown to the U-shaped structure,

wherein a first link portion length is greater than a second link portion length.

17. The medical device of claim 16,

wherein the first link portion length is about equal to the sum of twice a ring width and a length of a strut extending between crowns of a ring.

18. The medical device of claim 9, wherein a distal marker link has a first end and a second end, the first end forming one of a W crown and Y crown with the first distal ring and the second end forming the other of the W crown and Y crown with the second distal ring.

19. The medical device of claim 1, wherein a length of the first proximal links is less than a length of the first distal links, and/or a length of the second distal links is less than the first distal links length.

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