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Topliss et al.

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(54) **CAPACITIVE AUTO FOCUS POSITION DETECTION**

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Related U.S. Application Data

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H04N 5/225 (2006.01)
H04N 5/232 (2006.01)
G02B 7/09 (2006.01)

(52) **U.S. Cl.**

CPC **H04N 5/2253** (2013.01); **G02B 7/09** (2013.01); **H04N 5/2257** (2013.01); **H04N 5/23212** (2013.01); **H04N 5/23287** (2013.01)

(58) **Field of Classification Search**

CPC .. H04N 5/2253; H04N 5/2251; H04N 5/2254; H04N 5/2257; H04N 5/23212; H04N 5/2328; H04N 5/23287

See application file for complete search history.

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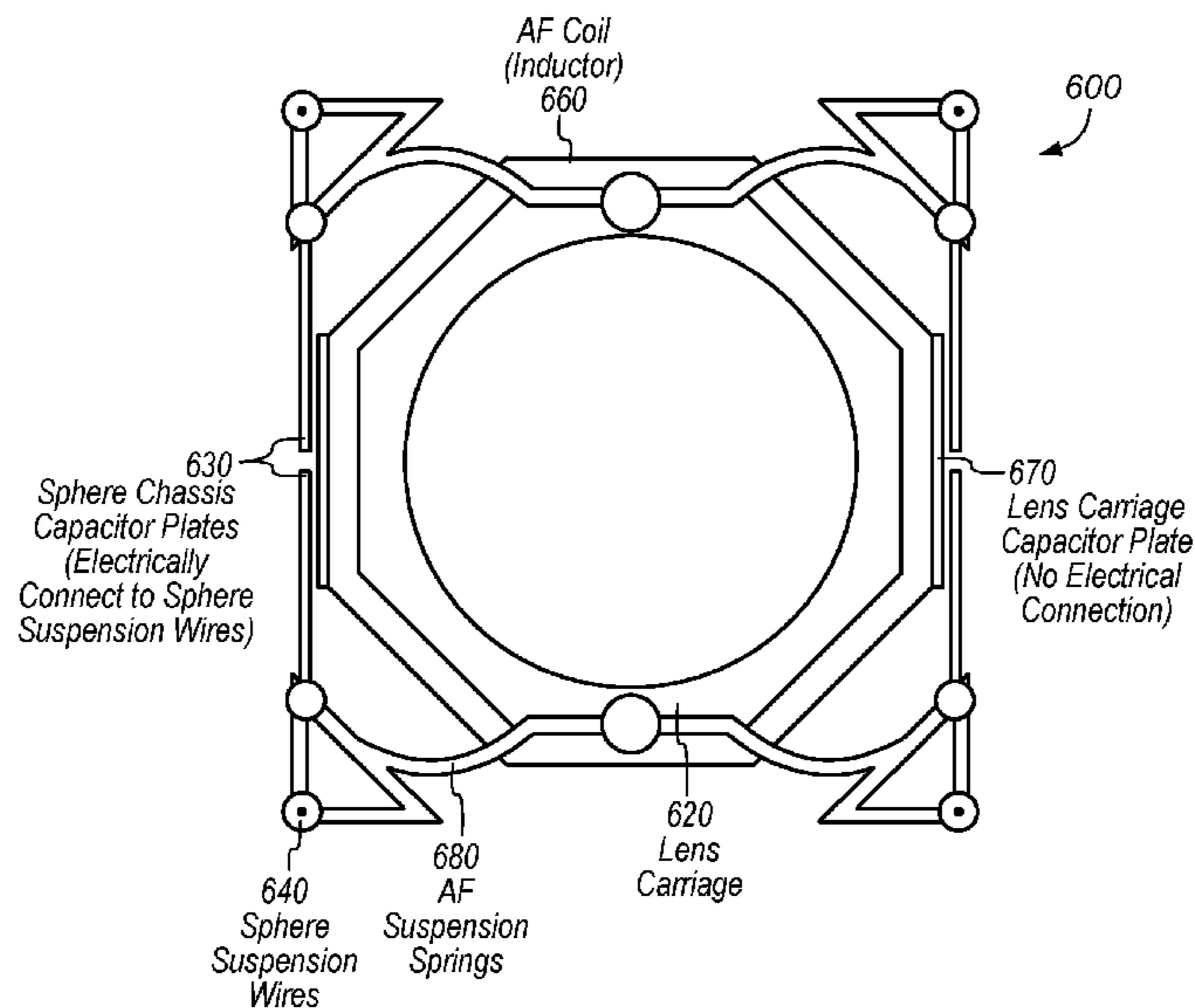
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(57) **ABSTRACT**

Some embodiments include an electrically conductive capacitor plate mounted to a chassis supporting an actuator using one or more suspension wires. In some embodiments, the first electrically conductive capacitor plate is electrically connected with an electrically conductive coil of the actuator. Some embodiments include the electrically conductive coil. In some embodiments, a capacitance between the first electrically conductive capacitor plate and the electrically conductive coil varies as function of the position of the electrically conductive coil relative to the first electrically conductive capacitor plate.

20 Claims, 13 Drawing Sheets



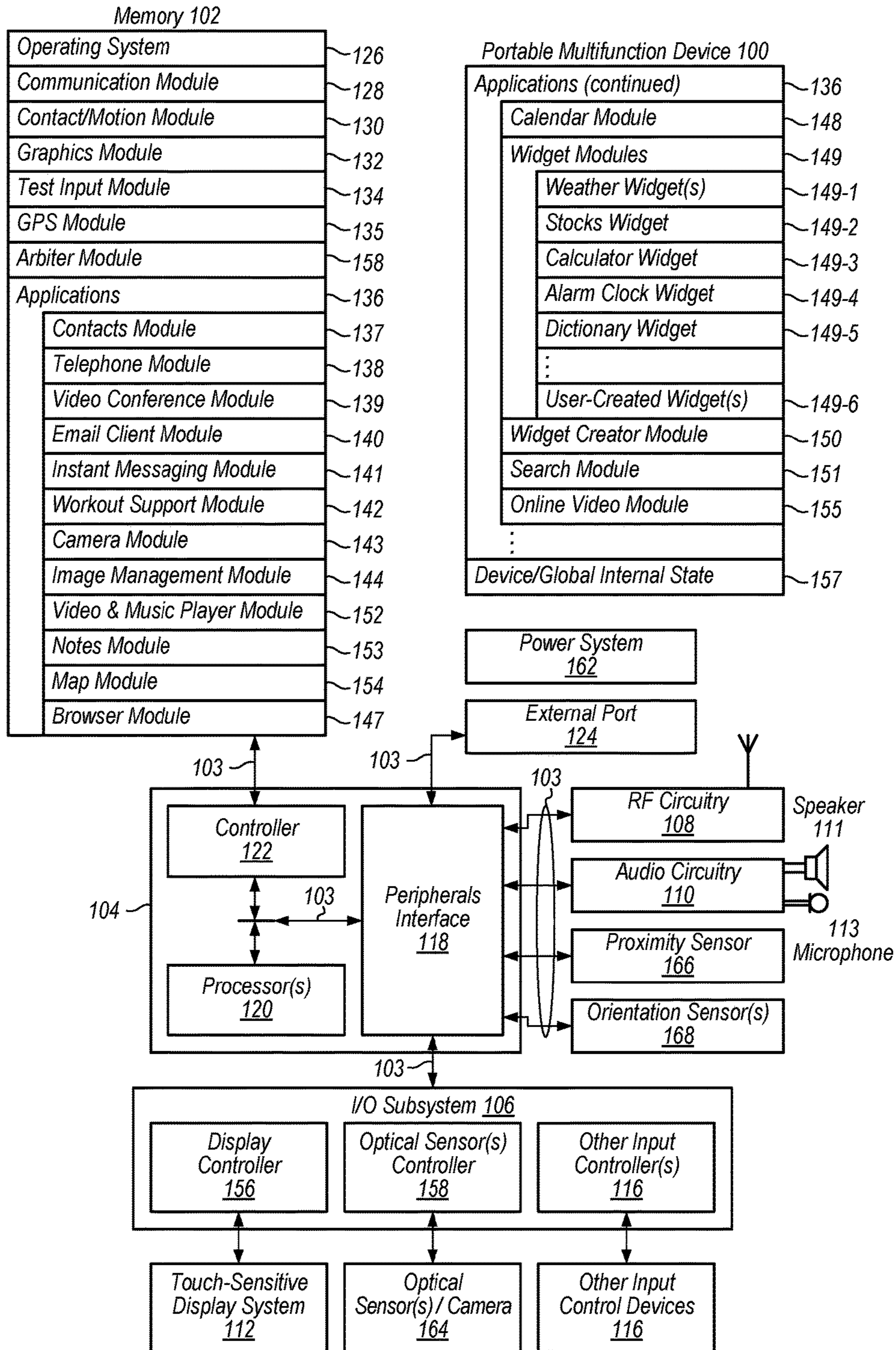


FIG. 1

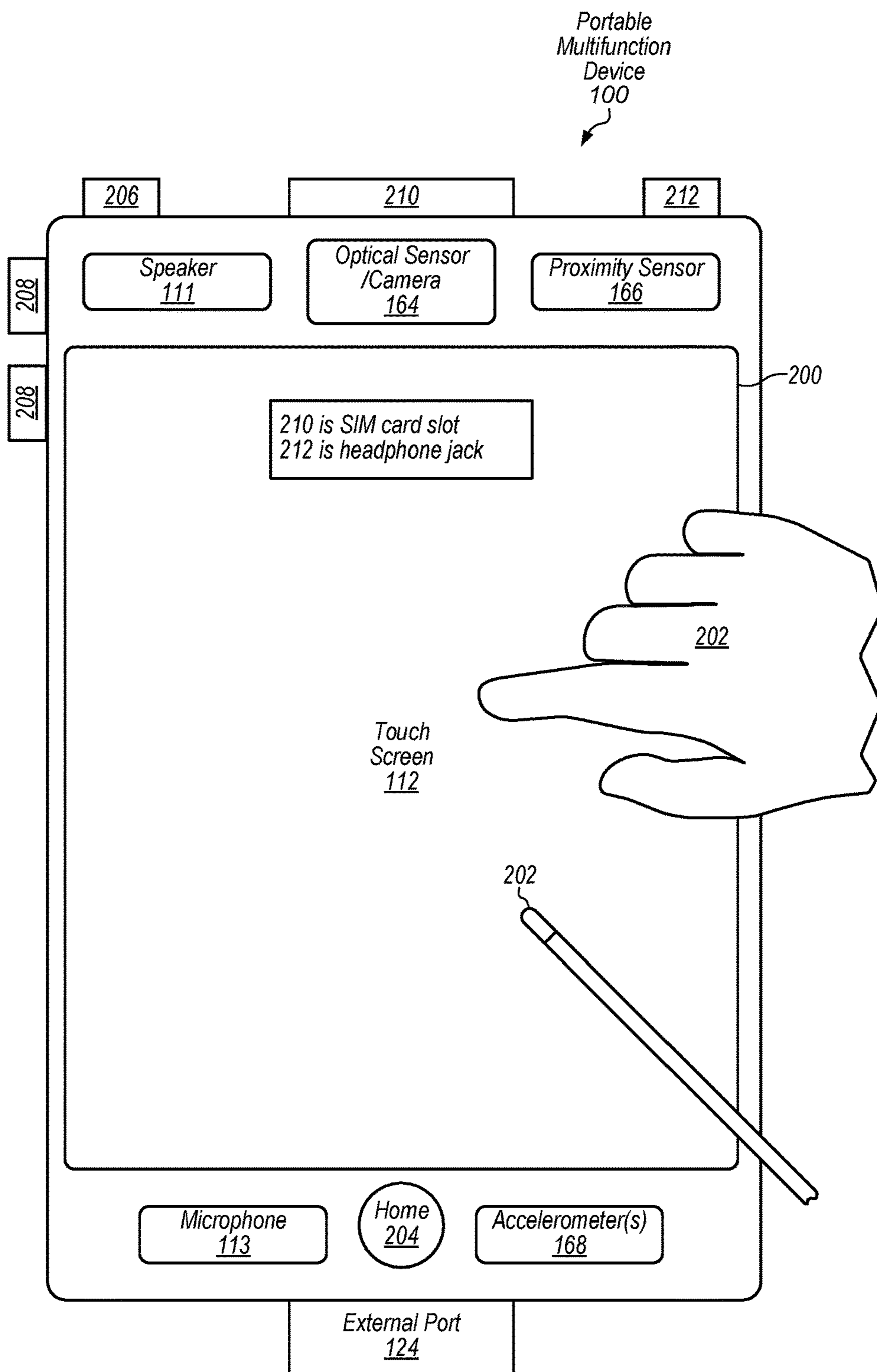


FIG. 2

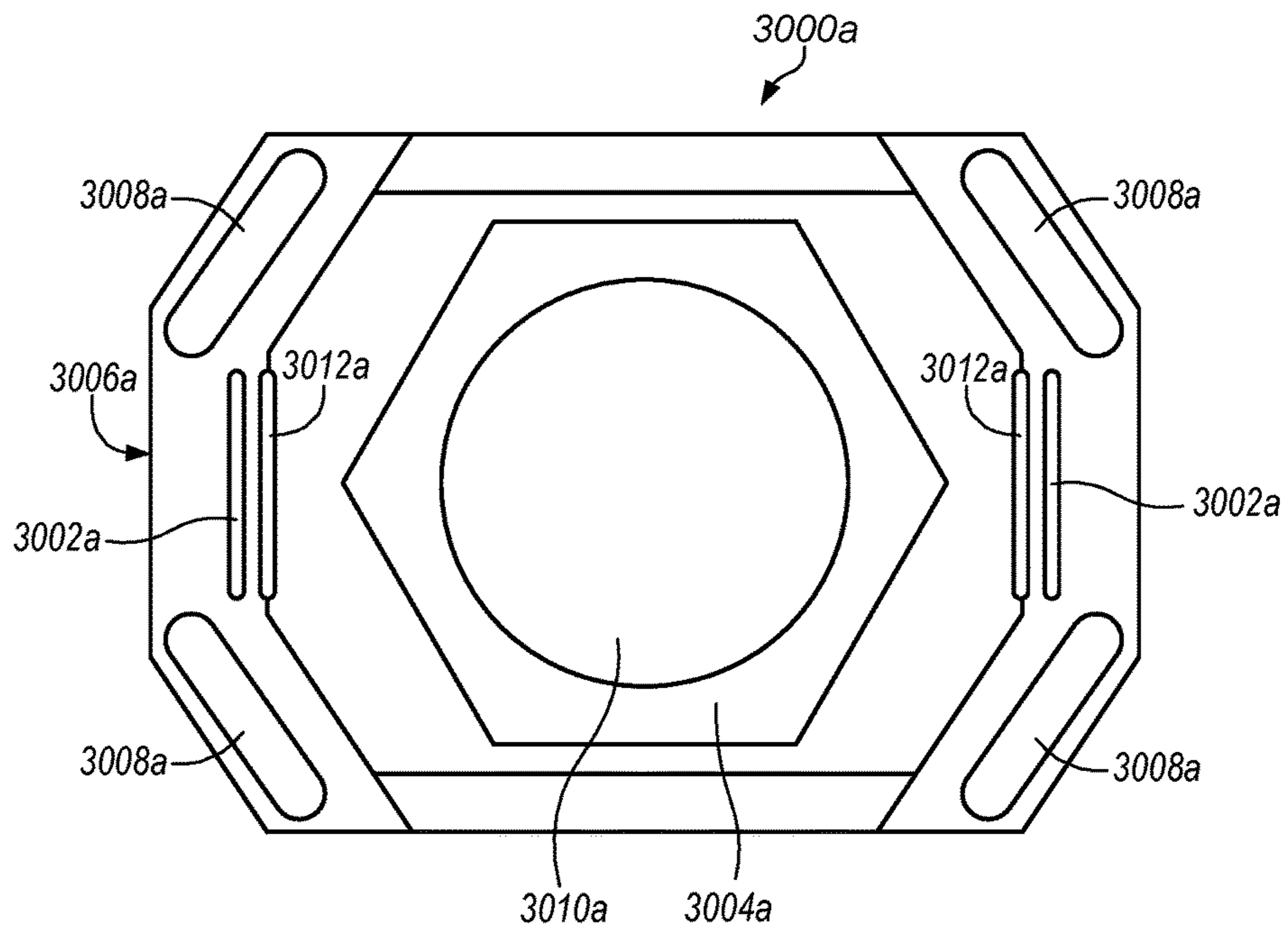


FIG. 3A

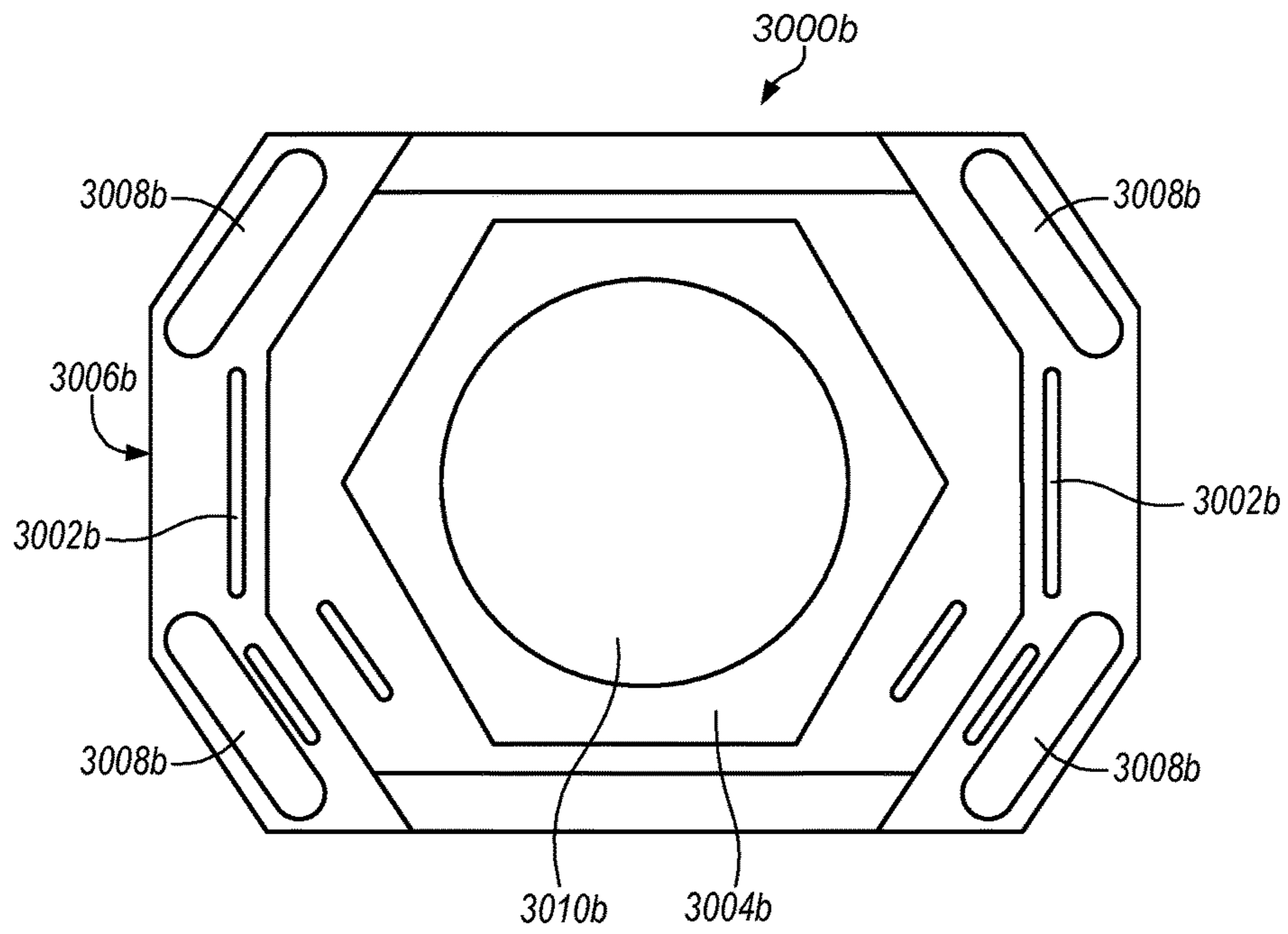


FIG. 3B

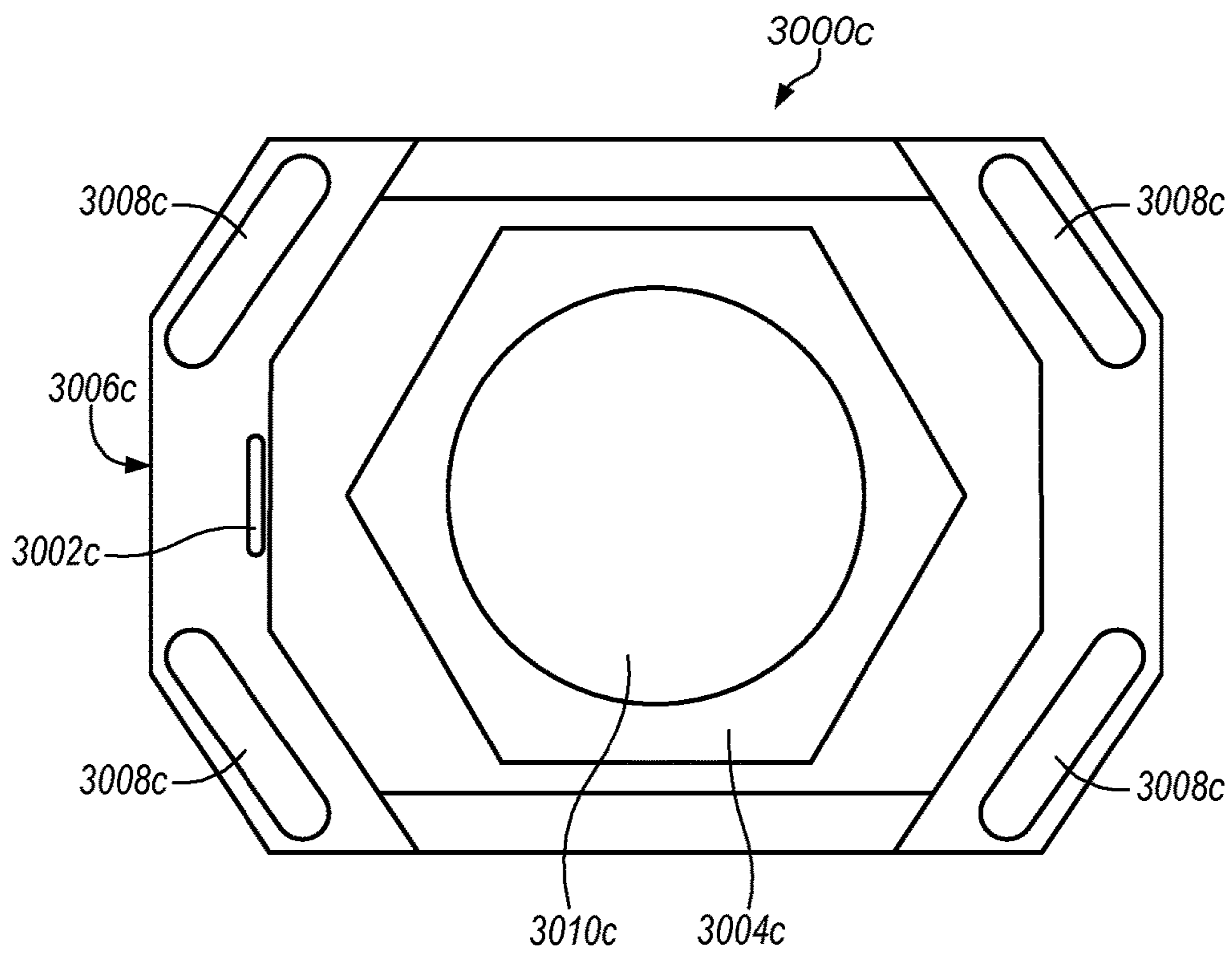


FIG. 3C

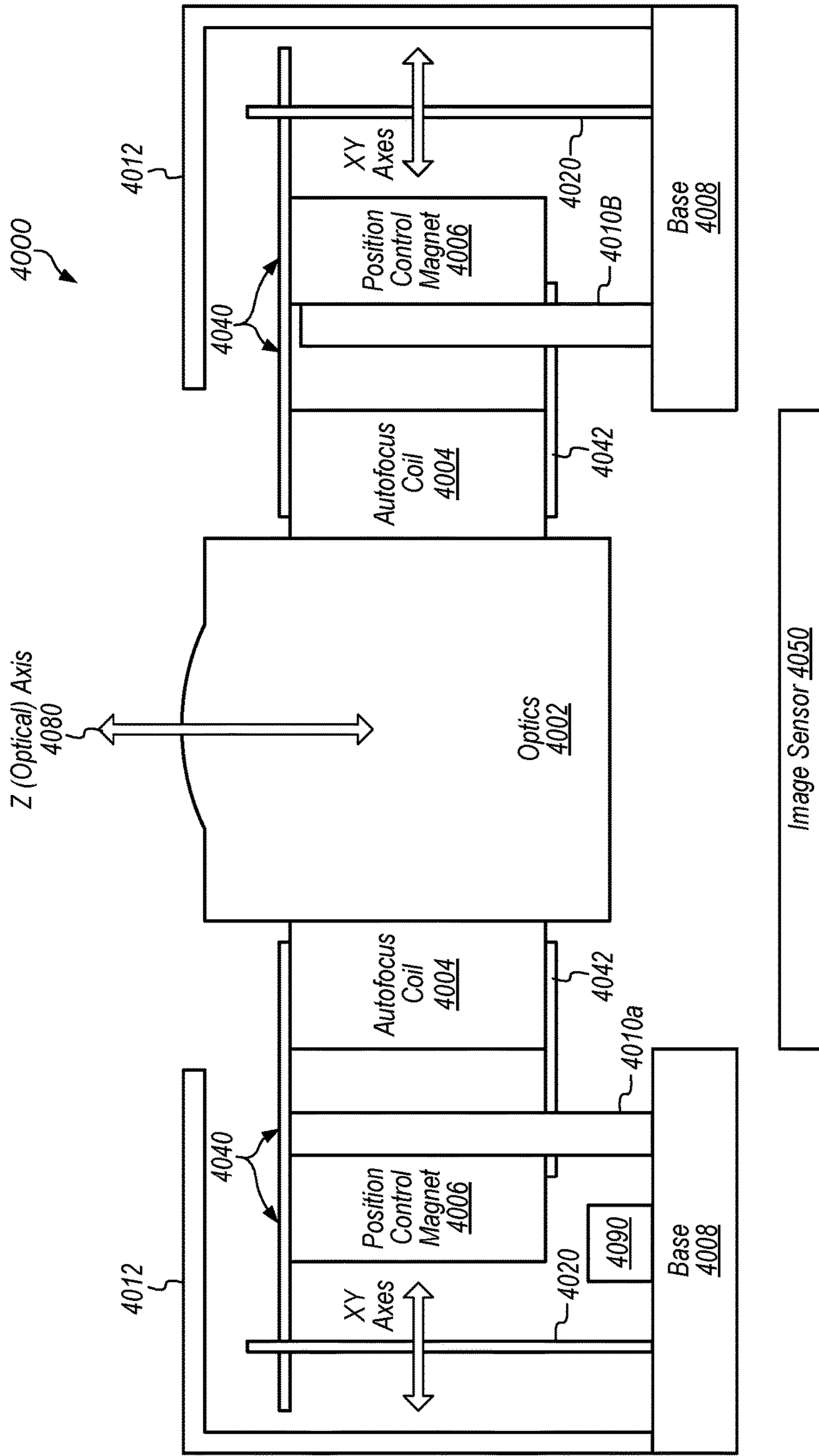


FIG. 4A

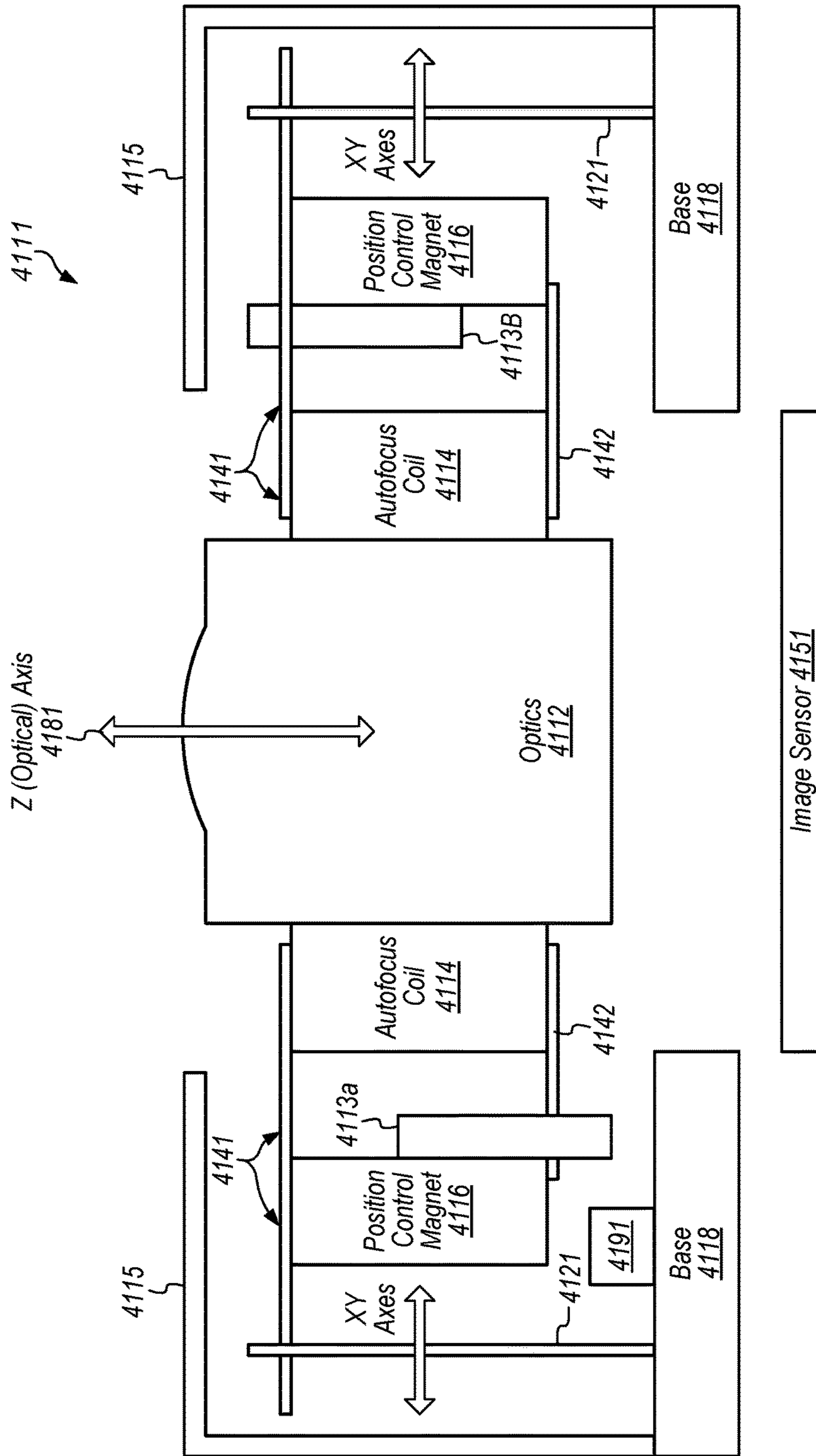


FIG. 4B

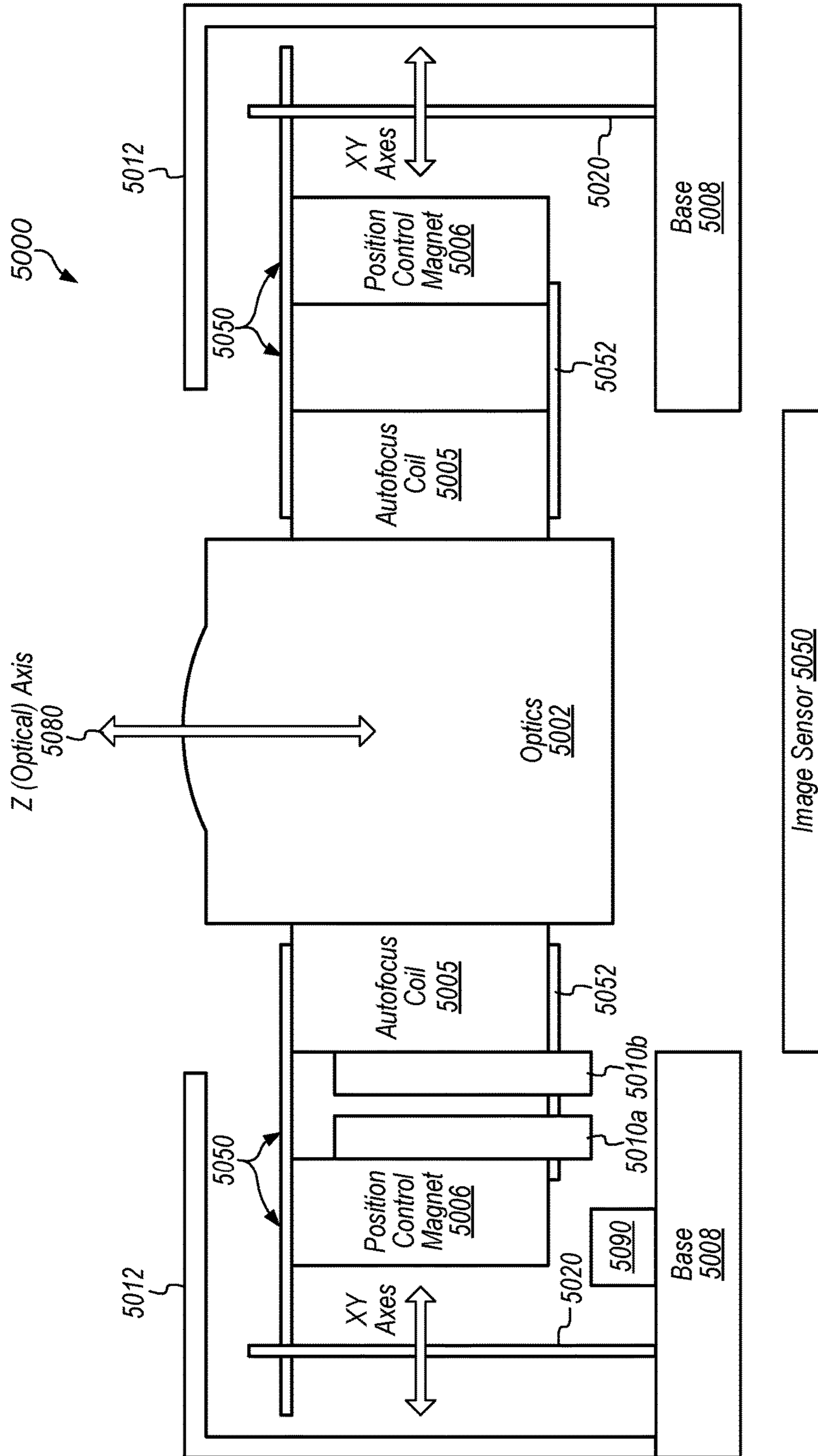


FIG. 5

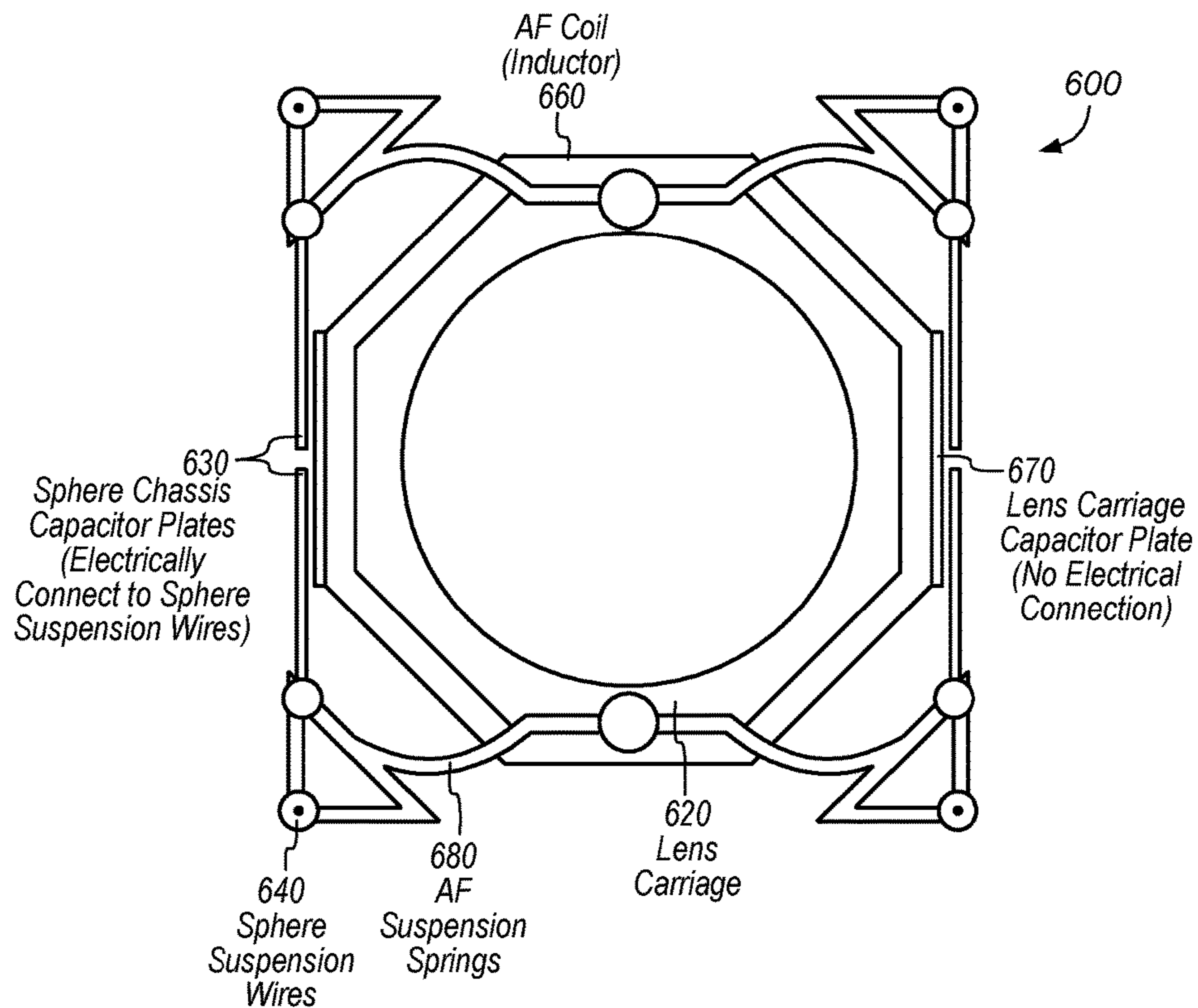


FIG. 6A

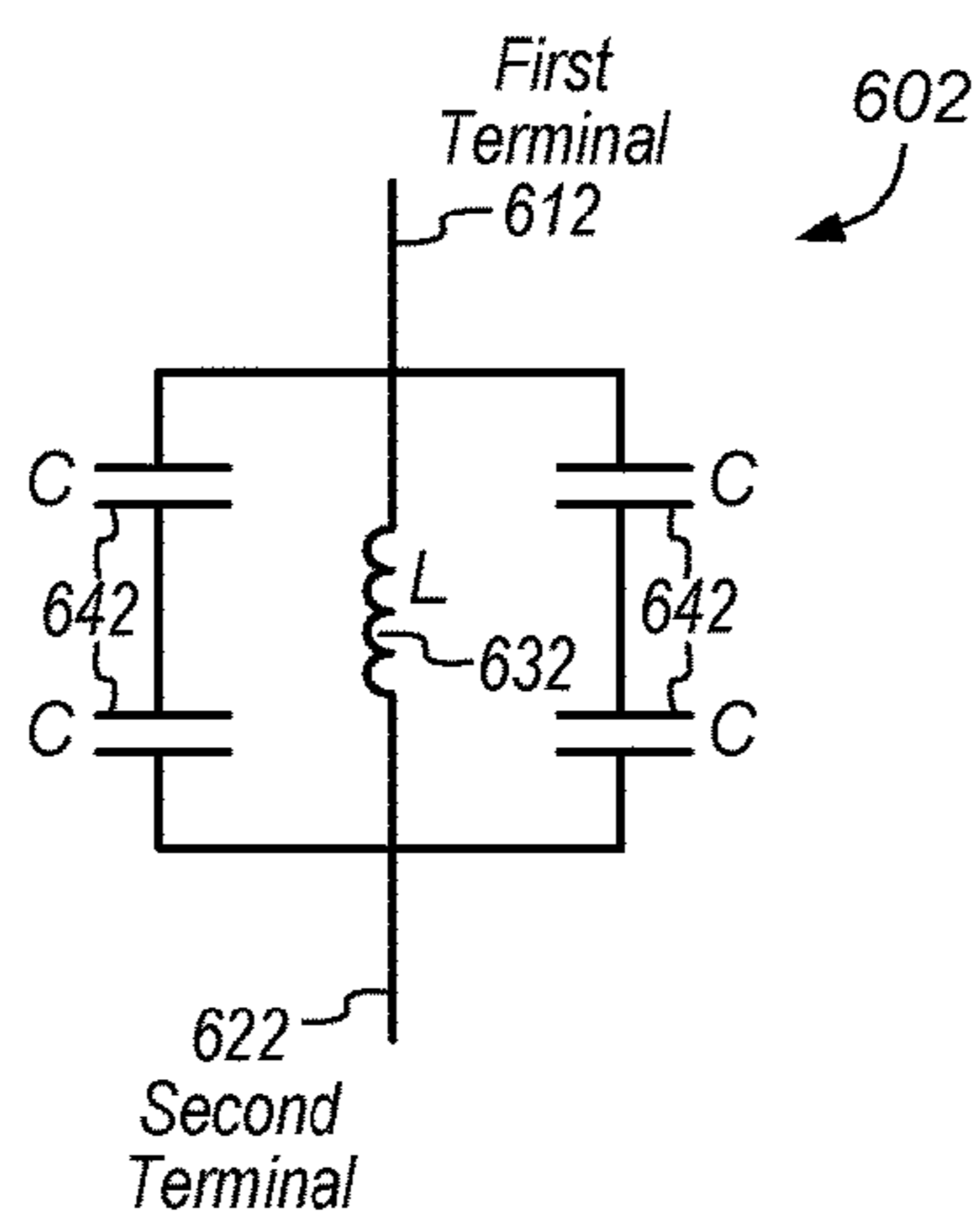


FIG. 6B

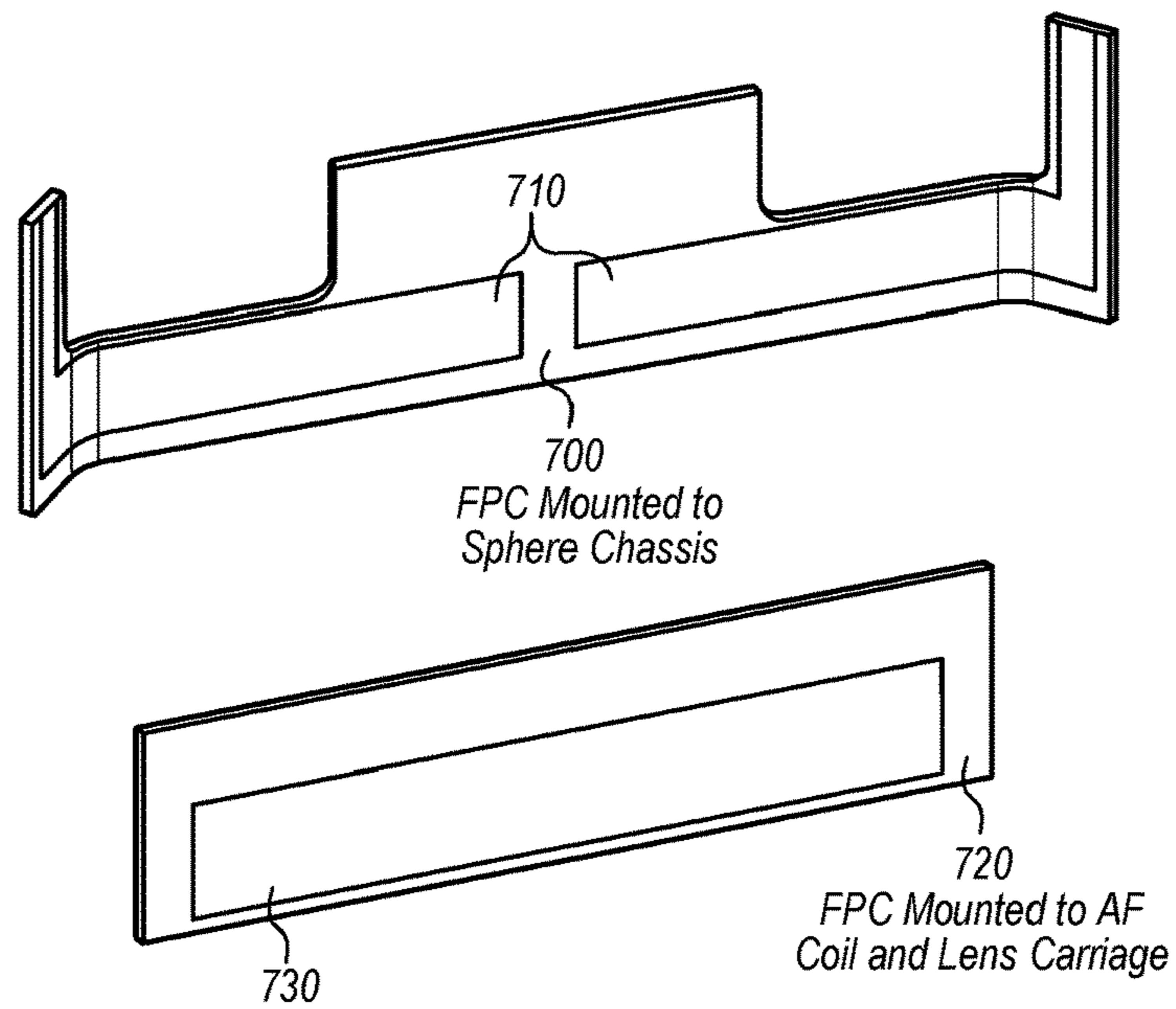


FIG. 7A

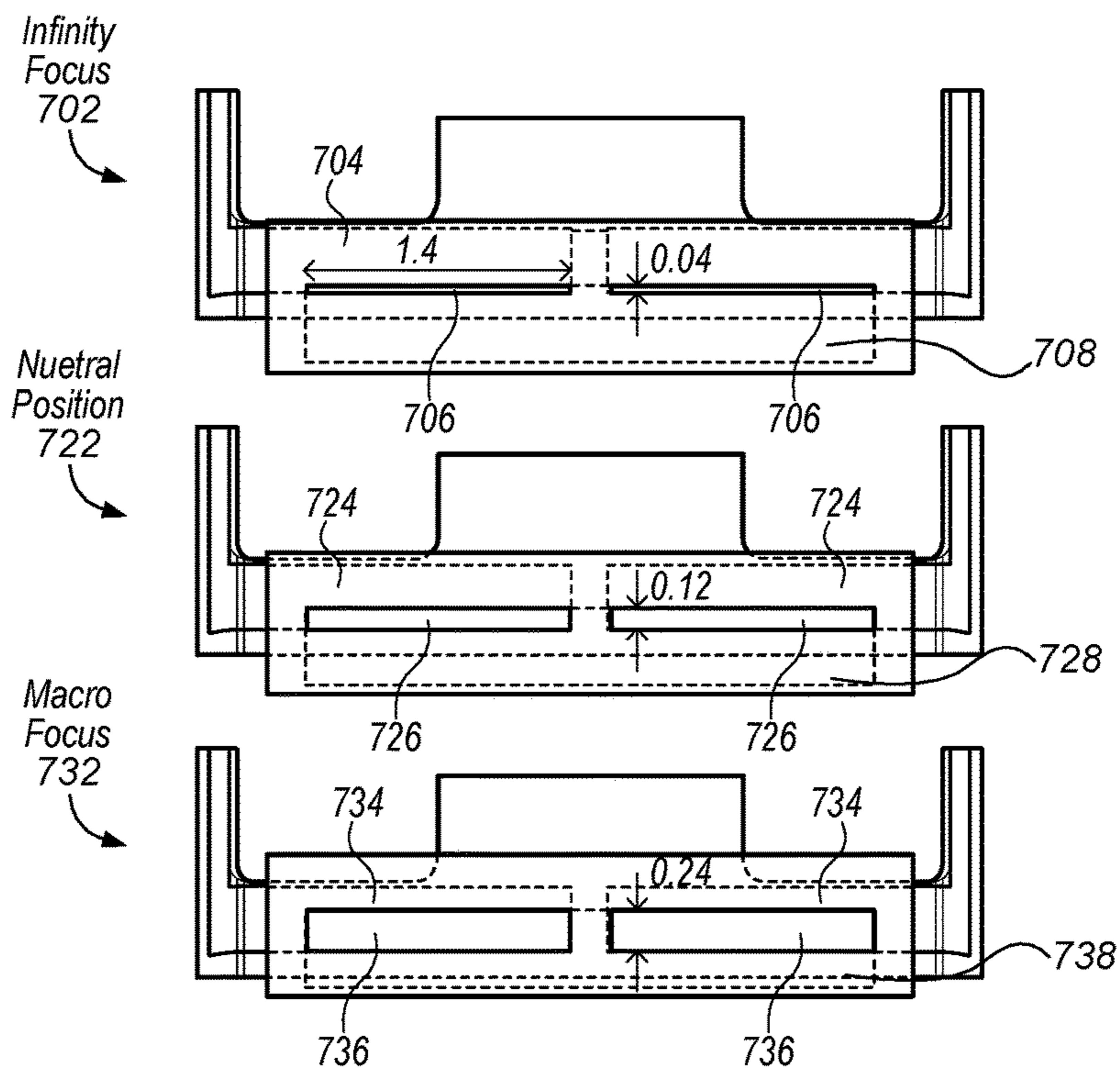


FIG. 7B

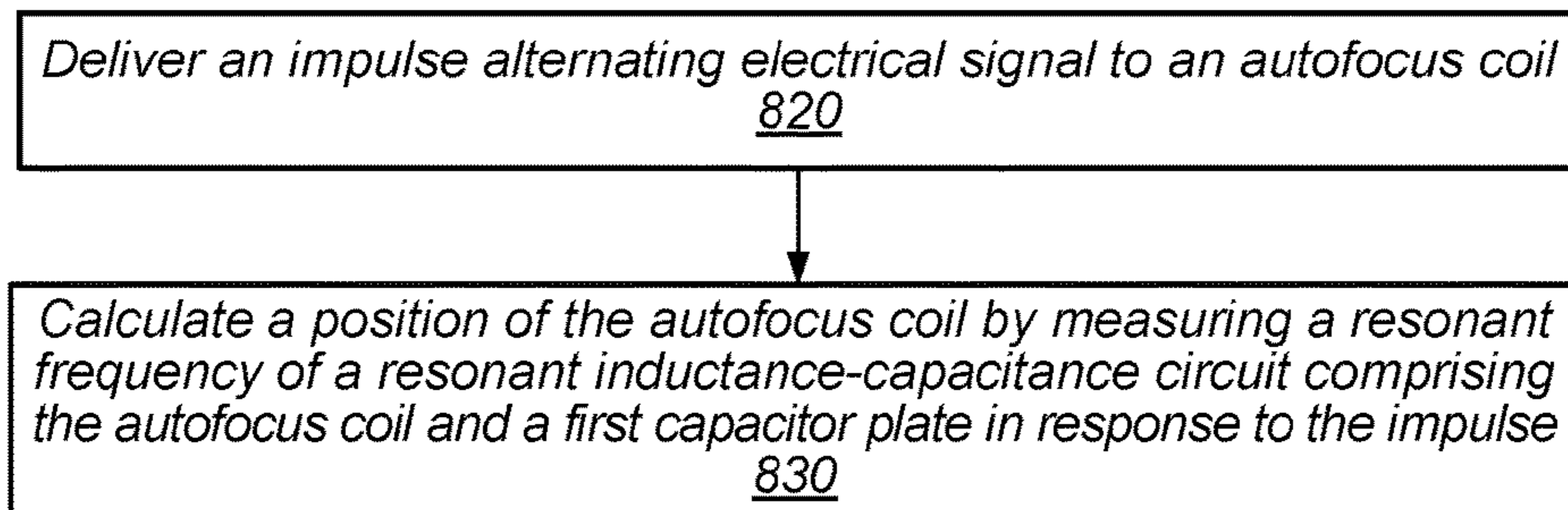


FIG. 8A

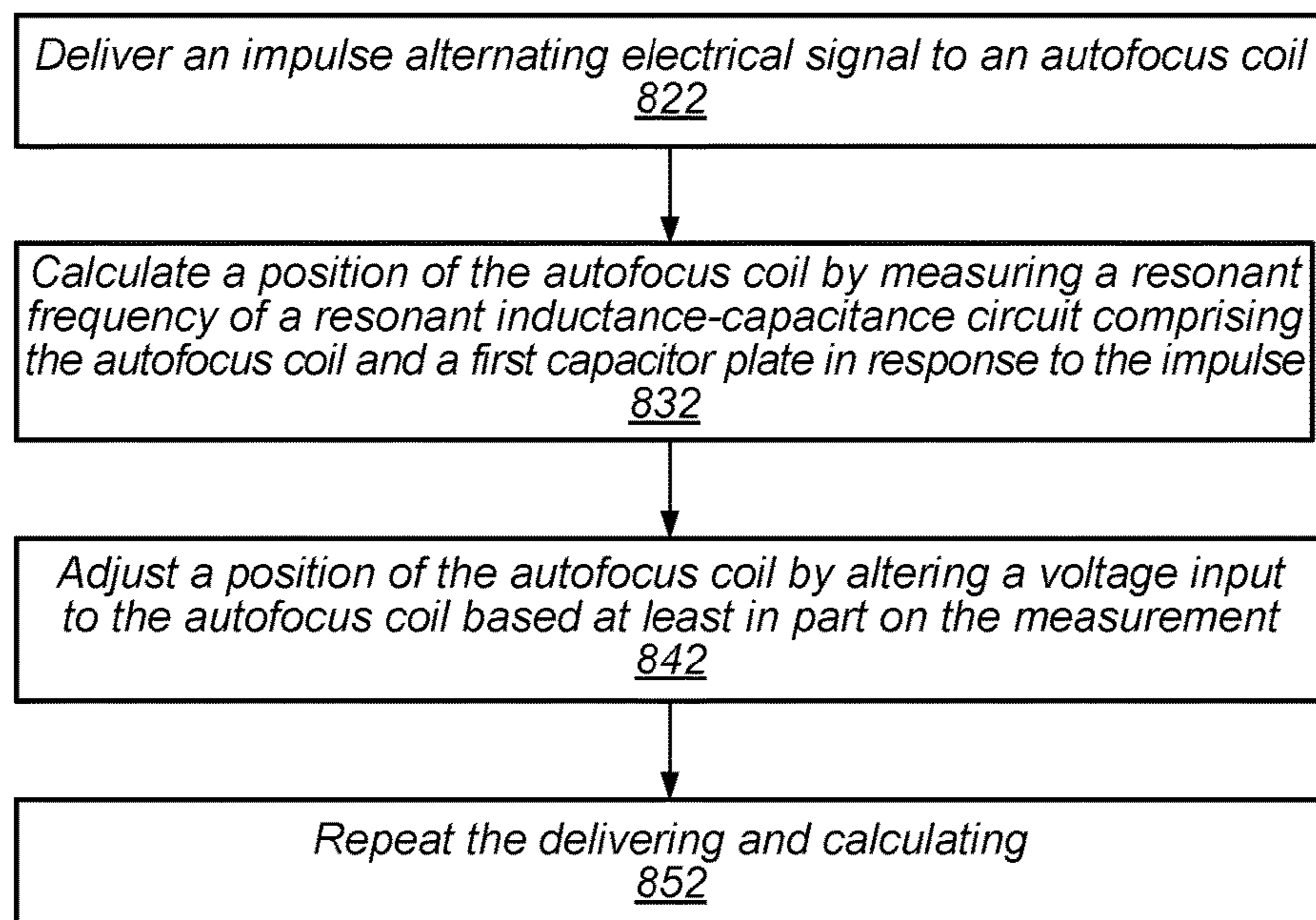


FIG. 8B

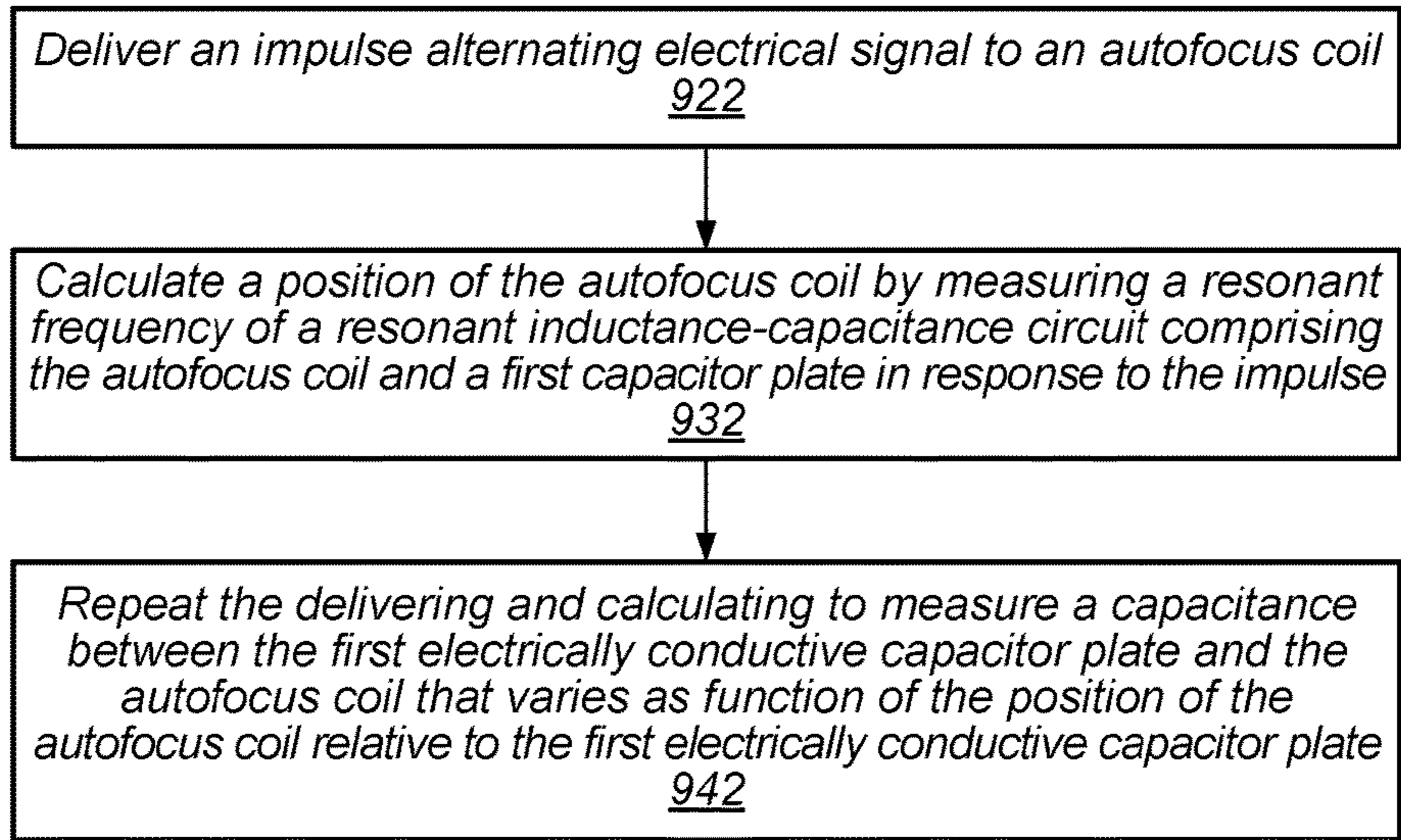


FIG. 9A

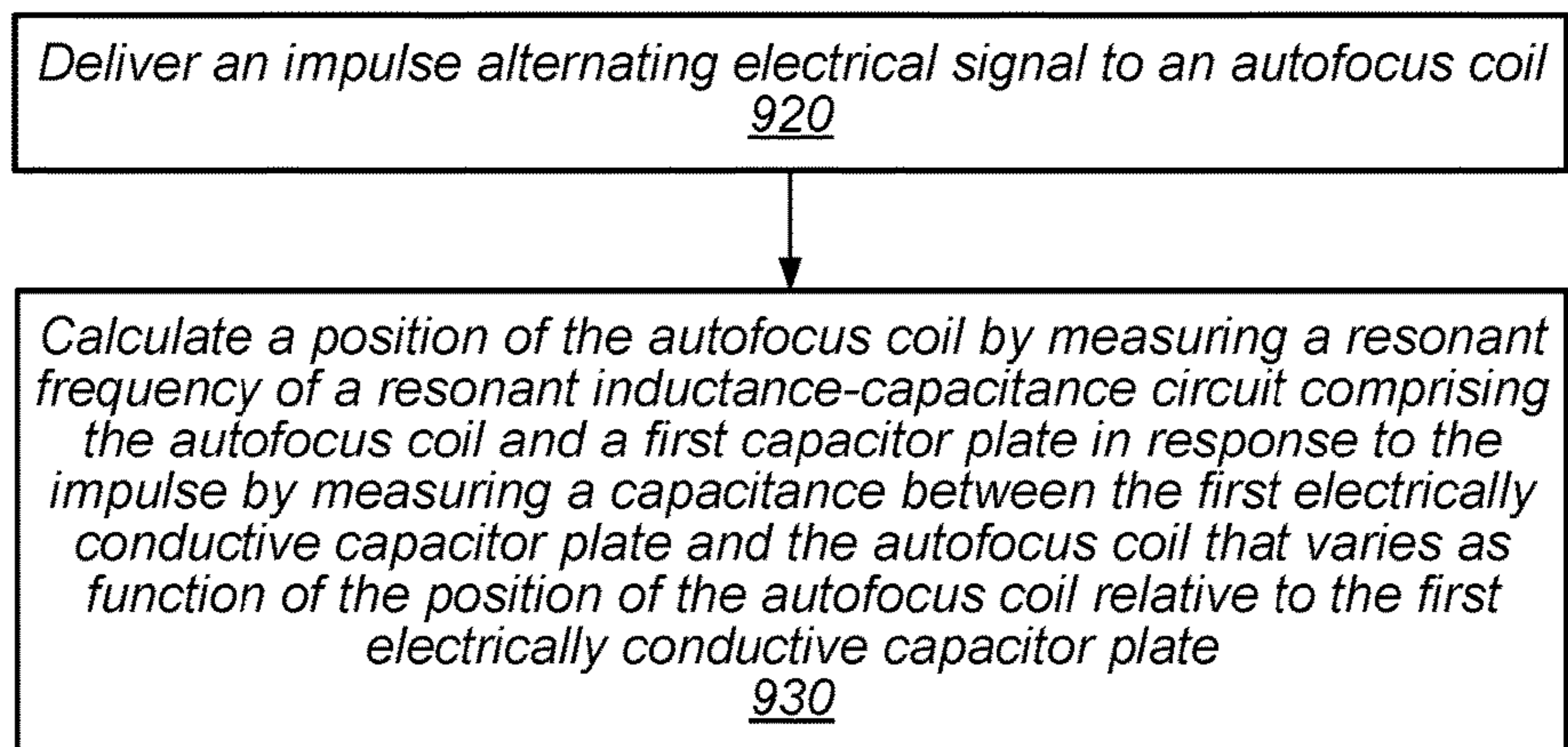


FIG. 9B

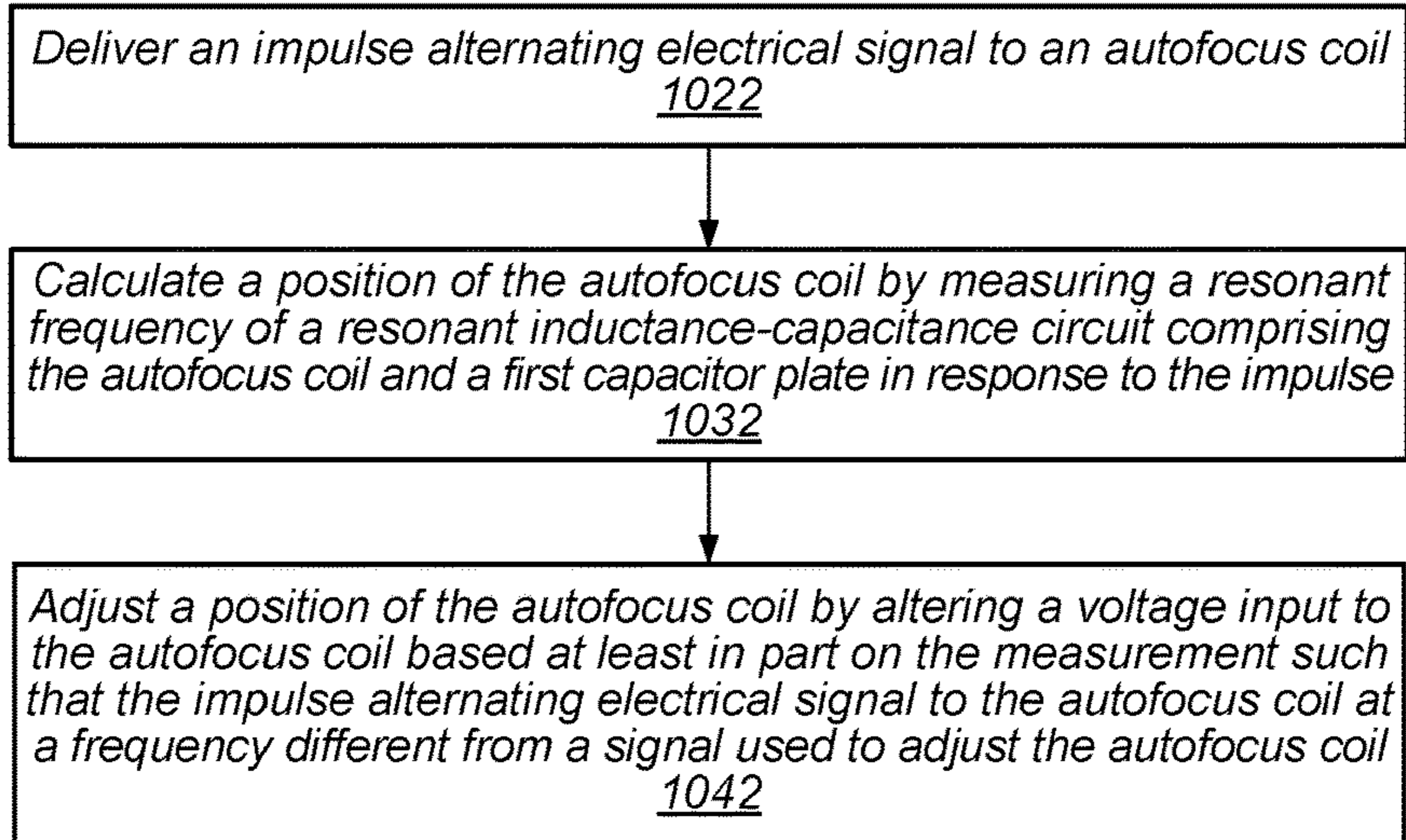


FIG. 10A

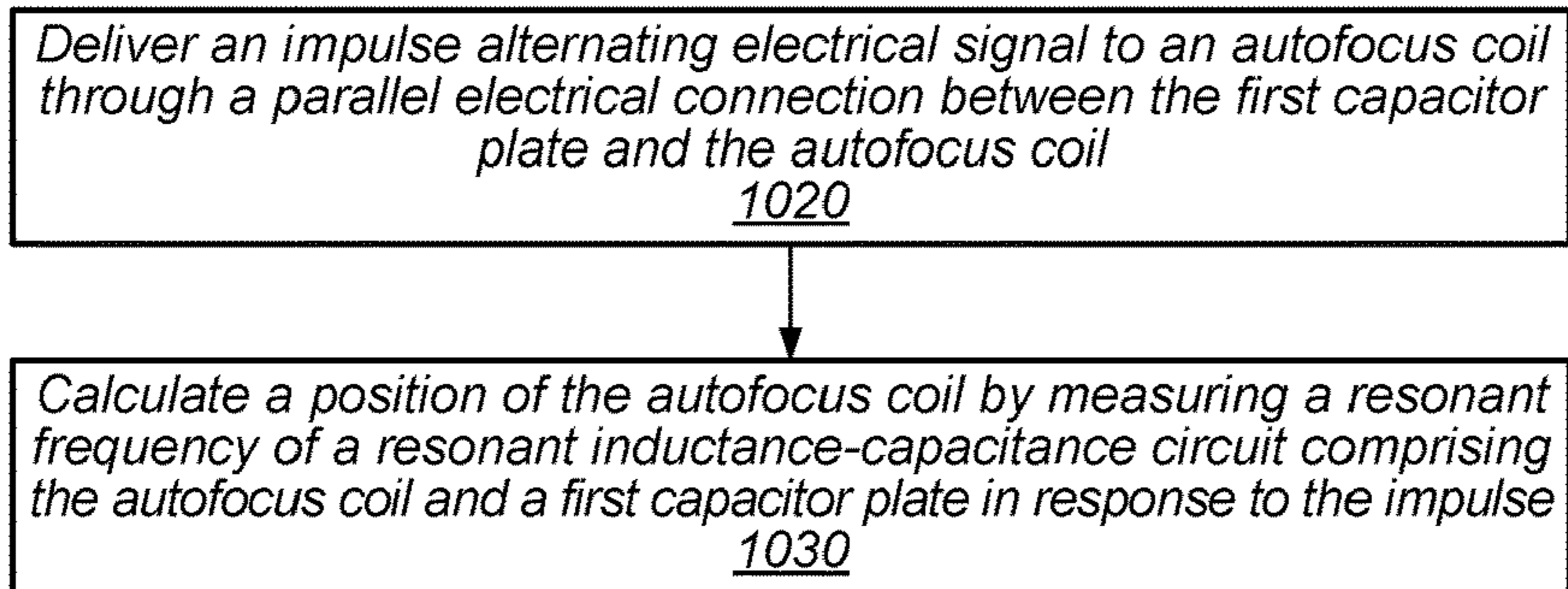


FIG. 10B

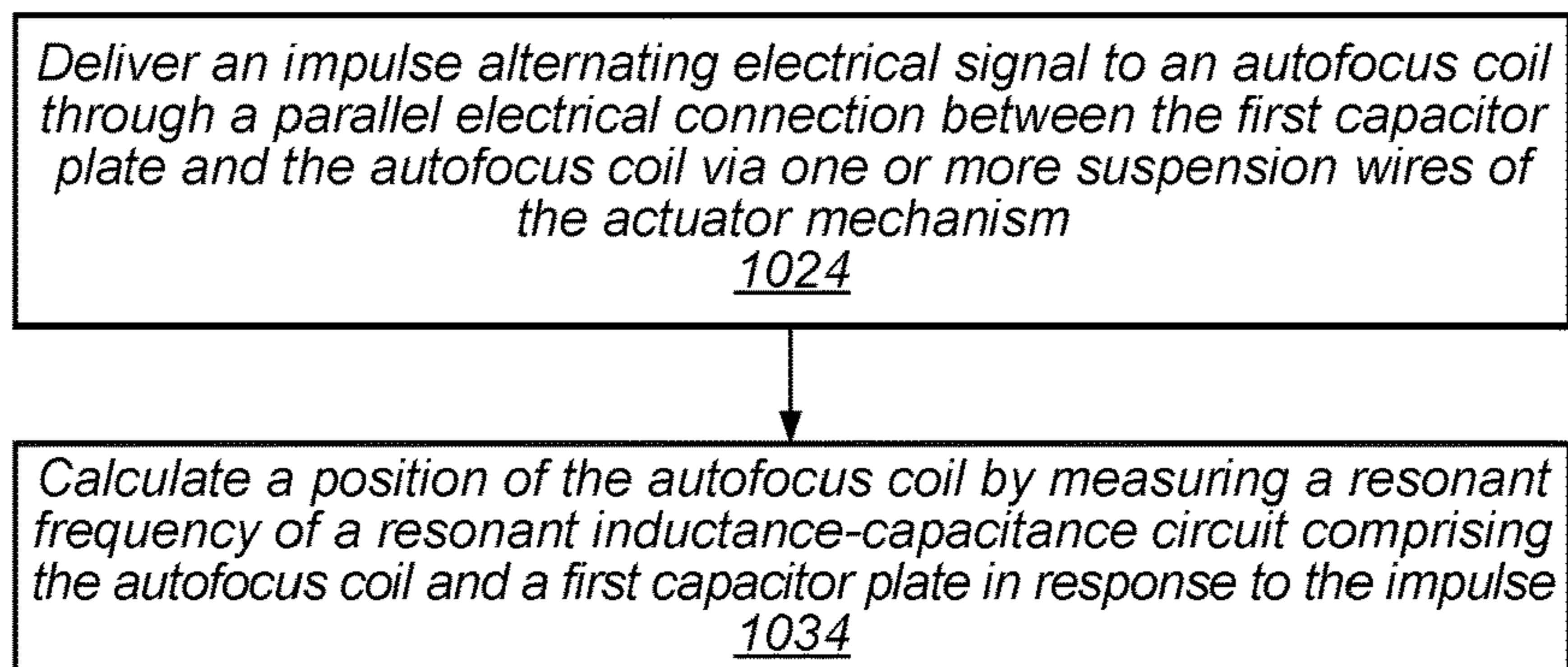


FIG. 10C

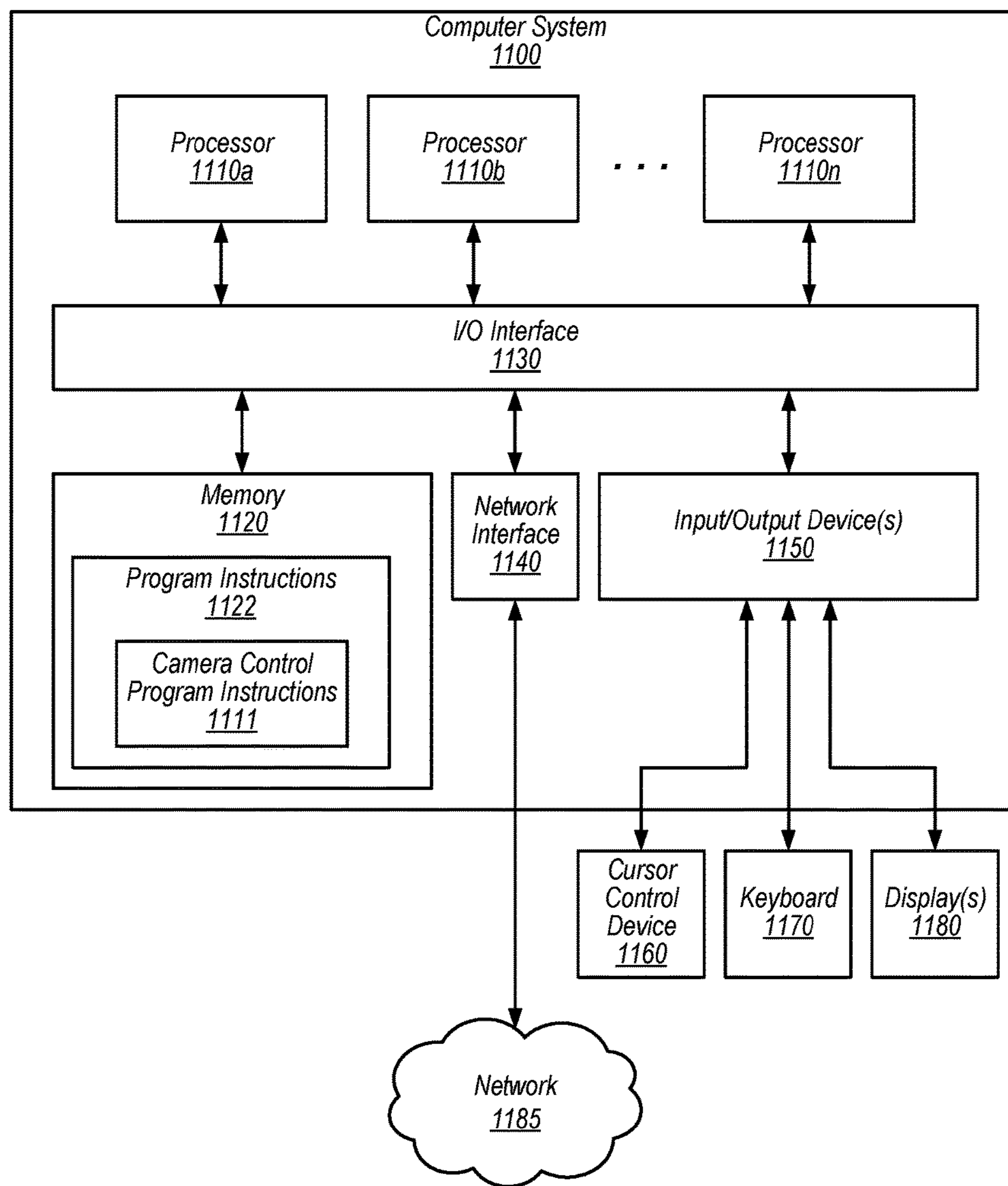


FIG. 11

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**CAPACITIVE AUTO FOCUS POSITION
DETECTION**

This application is a divisional of U.S. patent application Ser. No. 14/803,951, filed Jul. 20, 2015, now U.S. Pat. No. 9,736,345, which is hereby incorporated by reference herein in its entirety.

BACKGROUND

Technical Field

This disclosure relates generally to position measurement and more specifically to position measurement for managing the motion of camera components.

Description of the Related Art

The advent of small, mobile multipurpose devices such as smartphones and tablet or pad devices has resulted in a need for high-resolution, small form factor cameras for integration in the devices. Some small form factor cameras may incorporate optical image stabilization (OIS) mechanisms that may sense and react to external excitation/disturbance by adjusting location of the optical lens on the X and/or Y axis in an attempt to compensate for unwanted motion of the lens. Some small form factor cameras may incorporate an autofocus (AF) mechanism whereby the object focal distance can be adjusted to focus an object plane in front of the camera at an image plane to be captured by the image sensor. In some such autofocus mechanisms, the optical lens is moved as a single rigid body along the optical axis (referred to as the Z axis) of the camera to refocus the camera.

In addition, high image quality is easier to achieve in small form factor cameras if lens motion along the optical axis is accompanied by minimal parasitic motion in the other degrees of freedom, for example on the X and Y axes orthogonal to the optical (Z) axis of the camera. Thus, some small form factor cameras that include autofocus mechanisms may also incorporate optical image stabilization (OIS) mechanisms that may sense and react to external excitation/disturbance by adjusting location of the optical lens on the X and/or Y axis in an attempt to compensate for unwanted motion of the lens. In such systems, knowledge of the position of the lens is useful.

SUMMARY OF EMBODIMENTS

Some embodiments include an electrically conductive capacitor plate mounted to a chassis supporting an actuator using one or more suspension wires. In some embodiments, the first electrically conductive capacitor plate is electrically connected through with an electrically conductive coil of the actuator. Some embodiments include the electrically conductive coil. In some embodiments, a capacitance between the first electrically conductive capacitor plate and the electrically conductive coil varies as function of the position of the electrically conductive coil relative to the first electrically conductive capacitor plate.

BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1 illustrates a block diagram of a portable multifunction device with a camera in accordance with some embodiments.

FIG. 2 depicts a portable multifunction device having a camera in accordance with some embodiments.

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FIG. 3A illustrates a top view of an example embodiment of an actuator module or assembly that may, for example, be used to provide capacitive sensing for autofocus position detection in small form factor cameras, according to at least some embodiments.

FIG. 3B depicts a top view of an example embodiment of an actuator module or assembly that may, for example, be used to provide capacitive sensing for autofocus position detection in small form factor cameras, according to at least some embodiments.

FIG. 3C illustrates a top view of an example embodiment of an actuator module or assembly that may, for example, be used to provide capacitive sensing for autofocus position detection in small form factor cameras, according to at least some embodiments.

FIG. 4A depicts a side view of an example embodiment of an actuator module or assembly that may, for example, be used to provide capacitive sensing for autofocus position detection in small form factor cameras, according to at least some embodiments.

FIG. 4B depicts a side view of an example embodiment of an actuator module or assembly that may, for example, be used to provide capacitive sensing for autofocus position detection in small form factor cameras, according to at least some embodiments.

FIG. 5 illustrates a side view of an example embodiment of an actuator module or assembly that may, for example, be used to provide capacitive sensing for autofocus position detection in small form factor cameras, according to at least some embodiments.

FIG. 6A depicts a top view of an example embodiment of an actuator module or assembly that may, for example, be used to provide capacitive sensing for autofocus position detection in small form factor cameras, according to at least some embodiments.

FIG. 6B depicts a schematic view of an example embodiment of a circuit that may, for example, be used to provide capacitive sensing for autofocus position detection in small form factor cameras, according to at least some embodiments.

FIGS. 7A and 7B illustrate an example embodiment capacitive sensor hardware that may, for example, be used to provide capacitive sensing for autofocus position detection in small form factor cameras, according to at least some embodiments.

FIG. 8A is a flowchart of a method to provide capacitive sensing for autofocus position detection, according to at least some embodiments.

FIG. 8B is a flowchart of a method to provide capacitive sensing for autofocus position detection, according to at least some embodiments.

FIG. 9A is a flowchart of a method to provide capacitive sensing for autofocus position detection, according to at least some embodiments.

FIG. 9B is a flowchart of a method to provide capacitive sensing for autofocus position detection, according to at least some embodiments.

FIG. 10A is a flowchart of a method to provide capacitive sensing for autofocus position detection, according to at least some embodiments.

FIG. 10B is a flowchart of a method to provide capacitive sensing for autofocus position detection, according to at least some embodiments.

FIG. 10C is a flowchart of a method to provide capacitive sensing for autofocus position detection, according to at least some embodiments.

FIG. 11 illustrates an example computer system configured to implement aspects of the system and method for camera control with capacitive sensing for autofocus position detection, according to some embodiments.

This specification includes references to “one embodiment” or “an embodiment.” The appearances of the phrases “in one embodiment” or “in an embodiment” do not necessarily refer to the same embodiment. Particular features, structures, or characteristics may be combined in any suitable manner consistent with this disclosure.

“Comprising.” This term is open-ended. As used in the appended claims, this term does not foreclose additional structure or steps. Consider a claim that recites: “An apparatus comprising one or more processor units” Such a claim does not foreclose the apparatus from including additional components (e.g., a network interface unit, graphics circuitry, etc.).

“Configured To.” Various units, circuits, or other components may be described or claimed as “configured to” perform a task or tasks. In such contexts, “configured to” is used to connote structure by indicating that the units/circuits/components include structure (e.g., circuitry) that performs those task or tasks during operation. As such, the unit/circuit/component can be said to be configured to perform the task even when the specified unit/circuit/component is not currently operational (e.g., is not on). The units/circuits/components used with the “configured to” language include hardware—for example, circuits, memory storing program instructions executable to implement the operation, etc. Reciting that a unit/circuit/component is “configured to” perform one or more tasks is expressly intended not to invoke 35 U.S.C. § 112, sixth paragraph, for that unit/circuit/component. Additionally, “configured to” can include generic structure (e.g., generic circuitry) that is manipulated by software and/or firmware (e.g., an FPGA or a general-purpose processor executing software) to operate in manner that is capable of performing the task(s) at issue. “Configure to” may also include adapting a manufacturing process (e.g., a semiconductor fabrication facility) to fabricate devices (e.g., integrated circuits) that are adapted to implement or perform one or more tasks.

“First,” “Second,” etc. As used herein, these terms are used as labels for nouns that they precede, and do not imply any type of ordering (e.g., spatial, temporal, logical, etc.). For example, a buffer circuit may be described herein as performing write operations for “first” and “second” values. The terms “first” and “second” do not necessarily imply that the first value must be written before the second value.

“Based On.” As used herein, this term is used to describe one or more factors that affect a determination. This term does not foreclose additional factors that may affect a determination. That is, a determination may be solely based on those factors or based, at least in part, on those factors. Consider the phrase “determine A based on B.” While in this case, B is a factor that affects the determination of A, such a phrase does not foreclose the determination of A from also being based on C. In other instances, A may be determined based solely on B.

DETAILED DESCRIPTION

Introduction to Capacitive Sensing for Autofocus Position Detection

Some embodiments include camera equipment outfitted with controls, magnets, and sensors to improve the position accuracy of a miniature actuation mechanism for a compact camera module. More specifically, in some embodiments,

compact camera modules include actuators to deliver functions such as autofocus (AF) and optical image stabilization (OIS). One approach to delivering a very compact actuator for OIS is to use a Voice Coil Motor (VCM) arrangement, though, as one of skill in the art will readily understand in light of having read the present disclosure, other arrangements such as MEMS actuators may be used in some embodiments without departing from the scope and intent of the present disclosure. In some embodiments, plural magnets interact with an autofocus coil bonded to the moving body of the OIS actuator.

For OIS, embodiments are frequently implemented in systems with actuators moving the moving body of the OIS actuator. Hence it is sometimes useful to employ sensors, to detect the position of the moving body of the OIS actuator. As current is applied to the OIS coils, the magnetic field generated interacts with the magnetic field of the magnets to generate forces that move the moving body in the desired manner.

Some embodiments allow a capacitive sensor output voltage to be very well correlated to the position of the moving body, such that the resonant frequency of an inductance-capacitance circuit output can be used as a measure of position, and be used to feedback the position, and allow more accurate positioning. Using a VCM, in some embodiments the forces generated are substantially linear with applied current, and hence assuming the moving body is suspended on the fixed body using substantially linear springs, the position of the moving body is substantially proportional to the applied VCM current.

Some embodiments include a method for measuring the position of a camera lens carrier movable by an autofocus actuator. In some embodiments, the method includes generating a measurement of a capacitance resulting at least in part from the relative movement of a first capacitor plate as compared to a second capacitor plate or an autofocus coil. In some embodiments, the camera lens carrier is movably coupled to a substrate by the autofocus actuator to provide motion in a direction orthogonal to the substrate.

In some embodiments, a method for measuring a position includes delivering an impulse alternating electrical signal to an autofocus coil and calculating a position of the autofocus coil by measuring properties, such as capacitance, of an inductance-capacitance circuit including the autofocus coil and a first capacitor plate in response to the impulse electrical signal. One option for some embodiments is for an excitation signal to be applied to one of the capacitance plates on the yoke, and then the resulting current to be sensed on the other plate of the yoke, these being capacitively coupled by the autofocus coil, or the plate over the autofocus coil. In some embodiments the autofocus coil is used with no extra plate. Some embodiments of such a drive scheme are described as a mutual capacitance measurement. In some embodiments an impulse electrical signal is an alternating current stimulation signal at a frequency detectable to a measurement circuit. In some embodiments, a method for measuring a position includes delivering an impulse alternating electrical signal to an autofocus coil and calculating a position of the autofocus coil by measuring a resonant frequency of a resonant inductance-capacitance circuit including the autofocus coil and a first capacitor plate in response to the impulse electrical signal. In some embodiments an impulse electrical signal is an alternating current stimulation signal at a frequency detectable to a measurement circuit.

In some embodiments, the method for measuring a position further includes adjusting a position of the autofocus

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coil by altering a voltage input to the autofocus coil. In some embodiments, the adjusting is based at least in part on the position measurement. In some embodiments, the method for measuring a position further includes repeating the delivering and calculating.

In some embodiments, the method for measuring a position further includes repeating the delivering and calculating. In some embodiments, a capacitance between the first electrically conductive capacitor plate and the autofocus coil varies as function of the position of the autofocus coil relative to the first electrically conductive capacitor plate.

In some embodiments, the calculating a position of the autofocus coil by measuring a resonant frequency of a resonant inductance-capacitance circuit including the autofocus coil and a first capacitor plate in response to the impulse further includes measuring a capacitance between the first electrically conductive capacitor plate and the autofocus coil that varies as function of the position of the autofocus coil relative to the first electrically conductive capacitor plate.

In some embodiments, the method for measuring a position further includes adjusting a position of the autofocus coil by altering a voltage input to the autofocus coil. In some embodiments, the adjusting is based at least in part on the position measurement, and the delivering the impulse alternating electrical signal to the autofocus coil further includes delivering the impulse alternating electrical signal to the autofocus coil at a frequency different from a signal used to adjust the autofocus coil.

In some embodiments, delivering the impulse alternating electrical signal to the autofocus coil further includes delivering the impulse alternating electrical signal to an autofocus coil of an autofocus actuator mechanism for moving a lens carriage, through a parallel electrical connection between the first capacitor plate and the autofocus coil.

In some embodiments, delivering the impulse alternating electrical signal to the autofocus coil further includes delivering the impulse alternating electrical signal to an autofocus coil of an autofocus actuator mechanism for moving a lens carriage, through a parallel electrical connection between the first capacitor plate and the autofocus coil via one or more suspension wires of the actuator mechanism.

Some embodiments include a camera of a mobile computing device having a position sensor for a lens of the camera. Some embodiments include a first electrically conductive capacitor plate mounted to a yoke. In some embodiments, the yoke supports a lens carriage. In some embodiments, the yoke is attached to a chassis using one or more suspension wires. In some embodiments, the first electrically conductive capacitor plate is electrically connected through the one or more suspension wires. In some embodiments, an electrically conductive autofocus coil of an autofocus actuator mechanism for moving a lens carriage is electrically connected through the one or more suspension wires. Some embodiments further include the electrically conductive autofocus coil of the autofocus actuator mechanism for moving the lens carriage. In some embodiments, a capacitance between the first electrically conductive capacitor plate and the autofocus coil varies as function of the position of the autofocus coil relative to the first electrically conductive capacitor plate.

Some embodiments include a position sensor. In some embodiments, the position sensor includes a first electrically conductive capacitor plate mounted to an actuator supported by one or more suspension wires. In some embodiments, the first electrically conductive capacitor plate is electrically connected through the one or more suspension wires with an

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electrically conductive coil of the actuator. In some embodiments, the position sensor includes the electrically conductive coil. In some embodiments, a capacitance between the first electrically conductive capacitor plate and the electrically conductive coil varies as function of the position of the electrically conductive coil relative to the first electrically conductive capacitor plate.

In some embodiments, the position sensor further includes a voltage source capable of delivering an impulse alternating electrical signal to the coil, and a second capacitor plate mounted to the electrically conductive coil. In some embodiments, the capacitance between the first electrically conductive capacitor plate and the electrically conductive coil comprises a capacitance between the first electrically conductive capacitor plate and the second capacitor plate.

Some embodiments include a camera of a mobile computing device having a position sensor for a lens of the camera. In some embodiments, the sensor includes a first electrically conductive capacitor plate mounted to a yoke mounted. In some embodiments, the yoke is mounted to a chassis of a lens carriage using one or more suspension wires, and the first electrically conductive capacitor plate is electrically connected through the one or more suspension wires in parallel with an electrically conductive autofocus coil of an autofocus actuator mechanism for moving a lens carriage. In some embodiments, the electrically conductive autofocus coil of the autofocus actuator mechanism for moving the lens carriage. In some embodiments, a capacitance between the first electrically conductive capacitor plate and the autofocus coil varies as function of the position of the autofocus coil relative to the first electrically conductive capacitor plate.

Some embodiments include a voltage source capable of delivering an impulse alternating electrical signal to the autofocus coil. Some embodiments include a measurement circuit for measuring a resonant frequency of a resonant inductance-capacitance circuit including the autofocus coil and the first capacitor plate in response to the impulse.

Some embodiments include position measurement logic for measuring the position of the lens carriage relative to the chassis by applying an alternating electrical signal to the autofocus coil.

Some embodiments include position measurement logic for measuring a resonant frequency of a resonant inductance-capacitance circuit including the autofocus coil and the first capacitor plate. Some embodiments include a second electrically conductive capacitor plate mounted to the yoke mounted to the chassis of the lens carriage using one or more suspension wires. In some embodiments, the second electrically conductive capacitor plate is mounted at a position along an optical axis of the camera different from a position along an optical axis of the camera from the first electrically conductive capacitor plate. In some embodiments, the second electrically conductive capacitor plate is electrically connected in parallel with an autofocus coil of an actuator for moving the lens carriage using the one or more suspension wires.

In some embodiments, the first electrically conductive capacitor plate is mounted to the yoke mounted to the chassis of the lens carriage using one or more suspension wires using a plastic isolation component fabricated with laser direct structuring between the first electrically conductive capacitor plate and the chassis of the lens carriage.

In some embodiments, the first electrically conductive capacitor plate is mounted to the yoke mounted to the chassis of the lens carriage using one or more suspension

wires using a flexible printed circuit situated between the first electrically conductive capacitor plate and the chassis of the lens carriage.

In some embodiments, the second electrically conductive capacitor plate is mounted to autofocus coil using a flexible printed circuit situated between the second electrically conductive capacitor plate and the autofocus coil.

In some embodiments, a position sensor includes a first electrically conductive capacitor plate mounted to a chassis supporting an actuator using one or more suspension wires. In some embodiments, the first electrically conductive capacitor plate is electrically connected through the one or more suspension wires in parallel with an electrically conductive coil of the actuator. In some embodiments, a position sensor includes the electrically conductive coil or interacts with the coil. In some embodiments, a capacitance between the first electrically conductive capacitor plate and the electrically conductive coil varies as function of the position of the electrically conductive coil relative to the first electrically conductive capacitor plate.

In some embodiments, a position sensor includes a position sensor includes a voltage source capable of delivering an impulse alternating electrical signal to the coil. In some embodiments, a position sensor includes a measurement circuit for measuring a resonant frequency of a resonant inductance-capacitance circuit including the coil and the first capacitor plate in response to the impulse.

In some embodiments, a position sensor includes position measurement logic for measuring the position of coil the chassis by applying an alternating electrical signal to the coil. In some embodiments, a position sensor includes position measurement logic for measuring a resonant frequency of a resonant inductance-capacitance circuit including the coil and the first capacitor plate.

In some embodiments, a position sensor includes a second electrically conductive capacitor plate mounted to the yoke mounted to the chassis of the lens carriage using one or more suspension wires. In some embodiments, the second electrically conductive capacitor plate is mounted at a position along a z axis through a center of the coil different from a position along the z axis from the first electrically conductive capacitor plate, and the second electrically conductive capacitor plate is electrically connected in parallel with the coil.

In some embodiments, the first electrically conductive capacitor plate is mounted to the chassis using a plastic isolation component fabricated with laser direct structuring between the first electrically conductive capacitor plate and the chassis of the lens carriage.

In some embodiments, a camera of a mobile computing device includes a position sensor for a lens of the camera, and the sensor includes a first electrically conductive capacitor plate mounted to a chassis of a lens carriage that is physically mounted to a yoke mounted to the chassis of the lens carriage using one or more suspension wires. In some embodiments, the first electrically conductive capacitor plate is electrically connected through the one or more suspension wires in parallel with an autofocus coil of an autofocus actuator mechanism for moving the lens carriage. In some embodiments, the camera of a mobile computing device includes an electrically conductive autofocus coil of the autofocus actuator mechanism for moving the lens carriage. In some embodiments, a capacitance between the first electrically conductive capacitor plate and the autofocus coil varies as function of the position of the autofocus coil relative to the first electrically conductive capacitor plate.

Some embodiments include a computer program product in a non-transitory computer-readable medium for measuring a position.

Some embodiments include program instructions on the computer-readable medium that are computer-executable to implement delivering an impulse alternating electrical signal to an autofocus coil. Some embodiments include program instructions on the computer-readable medium that are computer-executable to implement calculating a position of the autofocus coil by measuring a resonant frequency of a resonant inductance-capacitance circuit including the autofocus coil and a first capacitor plate in response to the impulse.

Some embodiments include program instructions on the computer-readable medium that are computer-executable to implement adjusting a position of the autofocus coil by altering a voltage input to the autofocus coil. In some embodiments, the adjusting is based at least in part on the position measurement. Some embodiments include program instructions on the computer-readable medium that are computer-executable to implement repeating the delivering and calculating.

Some embodiments include program instructions on the computer-readable medium that are computer-executable to implement repeating the delivering and calculating. In some embodiments, a capacitance between the first electrically conductive capacitor plate and the autofocus coil varies as function of the position of the autofocus coil relative to the first electrically conductive capacitor plate.

The program instructions computer-executable to implement the calculating a position of the autofocus coil by measuring a resonant frequency of a resonant inductance-capacitance circuit including the autofocus coil and a first capacitor plate in response to the impulse further include program instructions computer-executable to implement measuring a capacitance between the first electrically conductive capacitor plate and the autofocus coil that varies as function of the position of the autofocus coil relative to the first electrically conductive capacitor plate.

Some embodiments include program instructions on the computer-readable medium that are computer-executable to implement adjusting a position of the autofocus coil by altering a voltage input to the autofocus coil. In some embodiments, the adjusting is based at least in part on the position measurement, and the program instructions computer-executable to implement the delivering the impulse alternating electrical signal to the autofocus coil further include program instructions computer-executable to implement delivering the impulse alternating electrical signal to the autofocus coil at a frequency different from a signal used to adjust the autofocus coil. In some embodiments the program instructions on the computer-readable medium that are computer-executable to implement delivering the impulse alternating electrical signal to the autofocus coil further include program instructions computer-executable to implement delivering the impulse alternating electrical signal to an autofocus coil of an autofocus actuator mechanism for moving a lens carriage, through a parallel electrical connection between the first capacitor plate and the autofocus coil.

In some embodiments, the program instructions computer-executable to implement the delivering the impulse alternating electrical signal to the autofocus coil further include program instructions computer-executable to implement delivering the impulse alternating electrical signal to an autofocus coil of an autofocus actuator mechanism for moving a lens carriage, through a parallel electrical connec-

tion between the first capacitor plate and the autofocus coil via one or more suspension wires of the actuator mechanism. Multifunction Device Examples

Reference will now be made in detail to embodiments, examples of which are illustrated in the accompanying drawings. In the following detailed description, numerous specific details are set forth in order to provide a thorough understanding of the present disclosure. However, it will be apparent to one of ordinary skill in the art that some embodiments may be practiced without these specific details. In other instances, well-known methods, procedures, components, circuits, and networks have not been described in detail so as not to unnecessarily obscure aspects of the embodiments.

It will also be understood that, although the terms first, second, etc. may be used herein to describe various elements, these elements should not be limited by these terms. These terms are only used to distinguish one element from another. For example, a first contact could be termed a second contact, and, similarly, a second contact could be termed a first contact, without departing from the intended scope. The first contact and the second contact are both contacts, but they are not the same contact.

The terminology used in the description herein is for the purpose of describing particular embodiments only and is not intended to be limiting. As used in the description and the appended claims, the singular forms “a”, “an” and “the” are intended to include the plural forms as well, unless the context clearly indicates otherwise. It will also be understood that the term “and/or” as used herein refers to and encompasses any and all possible combinations of one or more of the associated listed items. It will be further understood that the terms “includes,” “including,” “comprises,” and/or “comprising,” when used in this specification, specify the presence of stated features, integers, steps, operations, elements, and/or components, but do not preclude the presence or addition of one or more other features, integers, steps, operations, elements, components, and/or groups thereof.

As used herein, the term “if” may be construed to mean “when” or “upon” or “in response to determining” or “in response to detecting,” depending on the context. Similarly, the phrase “if it is determined” or “if [a stated condition or event] is detected” may be construed to mean “upon determining” or “in response to determining” or “upon detecting [the stated condition or event]” or “in response to detecting [the stated condition or event],” depending on the context.

Embodiments of electronic devices, user interfaces for such devices, and associated processes for using such devices are described. In some embodiments, the device is a portable communications device, such as a mobile telephone, that also contains other functions, such as PDA and/or music player functions. Example embodiments of portable multifunction devices include, without limitation, the iPhone®, iPod Touch®, and iPad® devices from Apple Inc. of Cupertino, Calif. Other portable electronic devices, such as laptops, cameras, cell phones, or tablet computers, may also be used. It should also be understood that, in some embodiments, the device is not a portable communications device, but is a desktop computer with a camera. In some embodiments, the device is a gaming computer with orientation sensors (e.g., orientation sensors in a gaming controller). In other embodiments, the device is not a portable communications device, but is a camera.

In the discussion that follows, an electronic device that includes a display and a touch-sensitive surface is described. It should be understood, however, that the electronic device

may include one or more other physical user-interface devices, such as a physical keyboard, a mouse and/or a joystick.

The device typically supports a variety of applications, such as one or more of the following: a drawing application, a presentation application, a word processing application, a website creation application, a disk authoring application, a spreadsheet application, a gaming application, a telephone application, a video conferencing application, an e-mail application, an instant messaging application, a workout support application, a photo management application, a digital camera application, a digital video camera application, a web browsing application, a digital music player application, and/or a digital video player application.

The various applications that may be executed on the device may use at least one common physical user-interface device, such as the touch-sensitive surface. One or more functions of the touch-sensitive surface as well as corresponding information displayed on the device may be adjusted and/or varied from one application to the next and/or within a respective application. In this way, a common physical architecture (such as the touch-sensitive surface) of the device may support the variety of applications with user interfaces that are intuitive and transparent to the user.

Attention is now directed toward embodiments of portable devices with cameras. FIG. 1 is a block diagram illustrating portable multifunction device 100 with camera 164 in accordance with some embodiments. Camera 164 is sometimes called an “optical sensor” for convenience, and may also be known as or called an optical sensor system. Device 100 may include memory 102 (which may include one or more computer readable storage mediums), memory controller 122, one or more processing units (CPU’s) 120, peripherals interface 118, RF circuitry 108, audio circuitry 110, speaker 111, touch-sensitive display system 112, microphone 113, input/output (I/O) subsystem 106, other input or control devices 116, and external port 124. Device 100 may include one or more optical sensors 164. These components may communicate over one or more communication buses or signal lines 103.

It should be appreciated that device 100 is only one example of a portable multifunction device, and that device 100 may have more or fewer components than shown, may combine two or more components, or may have a different configuration or arrangement of the components. The various components shown in FIG. 1 may be implemented in hardware, software, or a combination of hardware and software, including one or more signal processing and/or application specific integrated circuits.

Memory 102 may include high-speed random access memory and may also include non-volatile memory, such as one or more magnetic disk storage devices, flash memory devices, or other non-volatile solid-state memory devices. Access to memory 102 by other components of device 100, such as CPU 120 and the peripherals interface 118, may be controlled by memory controller 122.

Peripherals interface 118 can be used to couple input and output peripherals of the device to CPU 120 and memory 102. The one or more processors 120 run or execute various software programs and/or sets of instructions stored in memory 102 to perform various functions for device 100 and to process data.

In some embodiments, peripherals interface 118, CPU 120, and memory controller 122 may be implemented on a single chip, such as chip 104. In some other embodiments, they may be implemented on separate chips.

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RF (radio frequency) circuitry **108** receives and sends RF signals, also called electromagnetic signals. RF circuitry **108** converts electrical signals to/from electromagnetic signals and communicates with communications networks and other communications devices via the electromagnetic signals. RF circuitry **108** may include well-known circuitry for performing these functions, including but not limited to an antenna system, an RF transceiver, one or more amplifiers, a tuner, one or more oscillators, a digital signal processor, a CODEC chipset, a subscriber identity module (SIM) card, memory, and so forth. RF circuitry **108** may communicate with networks, such as the Internet, also referred to as the World Wide Web (WWW), an intranet and/or a wireless network, such as a cellular telephone network, a wireless local area network (LAN) and/or a metropolitan area network (MAN), and other devices by wireless communication. The wireless communication may use any of a variety of communications standards, protocols and technologies, including but not limited to Global System for Mobile Communications (GSM), Enhanced Data GSM Environment (EDGE), high-speed downlink packet access (HSDPA), high-speed uplink packet access (HSUPA), wideband code division multiple access (W-CDMA), code division multiple access (CDMA), time division multiple access (TDMA), Bluetooth, Wireless Fidelity (Wi-Fi) (e.g., IEEE 802.11a, IEEE 802.11b, IEEE 802.11g and/or IEEE 802.11n), voice over Internet Protocol (VoIP), Wi-MAX, a protocol for e-mail (e.g., Internet message access protocol (IMAP) and/or post office protocol (POP)), instant messaging (e.g., extensible messaging and presence protocol (XMPP), Session Initiation Protocol for Instant Messaging and Presence Leveraging Extensions (SIMPLE), Instant Messaging and Presence Service (IMPS)), and/or Short Message Service (SMS), or any other suitable communication protocol, including communication protocols not yet developed as of the filing date of this document.

Audio circuitry **110**, speaker **111**, and microphone **113** provide an audio interface between a user and device **100**. Audio circuitry **110** receives audio data from peripherals interface **118**, converts the audio data to an electrical signal, and transmits the electrical signal to speaker **111**. Speaker **111** converts the electrical signal to human-audible sound waves. Audio circuitry **110** also receives electrical signals converted by microphone **113** from sound waves. Audio circuitry **110** converts the electrical signal to audio data and transmits the audio data to peripherals interface **118** for processing. Audio data may be retrieved from and/or transmitted to memory **102** and/or RF circuitry **108** by peripherals interface **118**. In some embodiments, audio circuitry **110** also includes a headset jack (e.g., **212**, FIG. 2). The headset jack provides an interface between audio circuitry **110** and removable audio input/output peripherals, such as output-only headphones or a headset with both output (e.g., a headphone for one or both ears) and input (e.g., a microphone).

I/O subsystem **106** couples input/output peripherals on device **100**, such as touch screen **112** and other input control devices **116**, to peripherals interface **118**. I/O subsystem **106** may include display controller **156** and one or more input controllers **160** for other input or control devices. The one or more input controllers **160** receive/send electrical signals from/to other input or control devices **116**. The other input control devices **116** may include physical buttons (e.g., push buttons, rocker buttons, etc.), dials, slider switches, joysticks, click wheels, and so forth. In some alternate embodiments, input controller(s) **160** may be coupled to any (or none) of the following: a keyboard, infrared port, USB port,

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and a pointer device such as a mouse. The one or more buttons (e.g., **208**, FIG. 2) may include an up/down button for volume control of speaker **111** and/or microphone **113**. The one or more buttons may include a push button (e.g., **206**, FIG. 2).

Touch-sensitive display **112** provides an input interface and an output interface between the device and a user. Display controller **156** receives and/or sends electrical signals from/to touch screen **112**. Touch screen **112** displays visual output to the user. The visual output may include graphics, text, icons, video, and any combination thereof (collectively termed “graphics”). In some embodiments, some or all of the visual output may correspond to user-interface objects.

Touch screen **112** has a touch-sensitive surface, sensor or set of sensors that accepts input from the user based on haptic and/or tactile contact. Touch screen **112** and display controller **156** (along with any associated modules and/or sets of instructions in memory **102**) detect contact (and any movement or breaking of the contact) on touch screen **112** and converts the detected contact into interaction with user-interface objects (e.g., one or more soft keys, icons, web pages or images) that are displayed on touch screen **112**. In an example embodiment, a point of contact between touch screen **112** and the user corresponds to a finger of the user.

Touch screen **112** may use LCD (liquid crystal display) technology, LPD (light emitting polymer display) technology, or LED (light emitting diode) technology, although other display technologies may be used in other embodiments. Touch screen **112** and display controller **156** may detect contact and any movement or breaking thereof using any of a variety of touch sensing technologies now known or later developed, including but not limited to capacitive, resistive, infrared, and surface acoustic wave technologies, as well as other proximity sensor arrays or other elements for determining one or more points of contact with touch screen **112**. In an example embodiment, projected mutual capacitance sensing technology is used, such as that found in the iPhone®, iPod Touch®, and iPad® from Apple Inc. of Cupertino, Calif.

Touch screen **112** may have a video resolution in excess of 100 dpi. In some embodiments, the touch screen has a video resolution of approximately 160 dpi. The user may make contact with touch screen **112** using any suitable object or appendage, such as a stylus, a finger, and so forth. In some embodiments, the user interface is designed to work primarily with finger-based contacts and gestures, which can be less precise than stylus-based input due to the larger area of contact of a finger on the touch screen. In some embodiments, the device translates the rough finger-based input into a precise pointer/cursor position or command for performing the actions desired by the user.

In some embodiments, in addition to the touch screen, device **100** may include a touchpad (not shown) for activating or deactivating particular functions. In some embodiments, the touchpad is a touch-sensitive area of the device that, unlike the touch screen, does not display visual output. The touchpad may be a touch-sensitive surface that is separate from touch screen **112** or an extension of the touch-sensitive surface formed by the touch screen.

Device **100** also includes power system **162** for powering the various components. Power system **162** may include a power management system, one or more power sources (e.g., battery, alternating current (AC)), a recharging system, a power failure detection circuit, a power converter or inverter, a power status indicator (e.g., a light-emitting diode

(LED)) and any other components associated with the generation, management and distribution of power in portable devices.

Device **100** may also include one or more optical sensors or cameras **164**. FIG. **1** shows an optical sensor coupled to optical sensor controller **158** in I/O subsystem **106**. Optical sensor **164** may include charge-coupled device (CCD) or complementary metal-oxide semiconductor (CMOS) phototransistors. Optical sensor **164** receives light from the environment, projected through one or more lens, and converts the light to data representing an image. In conjunction with imaging module **143** (also called a camera module), optical sensor **164** may capture still images or video. In some embodiments, an optical sensor is located on the back of device **100**, opposite touch screen display **112** on the front of the device, so that the touch screen display may be used as a viewfinder for still and/or video image acquisition. In some embodiments, another optical sensor is located on the front of the device so that the user's image may be obtained for videoconferencing while the user views the other video conference participants on the touch screen display.

Device **100** may also include one or more proximity sensors **166**. FIG. **1** shows proximity sensor **166** coupled to peripherals interface **118**. Alternately, proximity sensor **166** may be coupled to input controller **160** in I/O subsystem **106**. In some embodiments, the proximity sensor turns off and disables touch screen **112** when the multifunction device is placed near the user's ear (e.g., when the user is making a phone call).

Device **100** includes one or more orientation sensors **168**. In some embodiments, the one or more orientation sensors include one or more accelerometers (e.g., one or more linear accelerometers and/or one or more rotational accelerometers). In some embodiments, the one or more orientation sensors include one or more gyroscopes. In some embodiments, the one or more orientation sensors include one or more magnetometers. In some embodiments, the one or more orientation sensors include one or more of global positioning system (GPS), Global Navigation Satellite System (GLONASS), and/or other global navigation system receivers. The GPS, GLONASS, and/or other global navigation system receivers may be used for obtaining information concerning the location and orientation (e.g., portrait or landscape) of device **100**. In some embodiments, the one or more orientation sensors include any combination of orientation/rotation sensors. FIG. **1** shows the one or more orientation sensors **168** coupled to peripherals interface **118**. Alternately, the one or more orientation sensors **168** may be coupled to an input controller **160** in I/O subsystem **106**. In some embodiments, information is displayed on the touch screen display in a portrait view or a landscape view based on an analysis of data received from the one or more orientation sensors.

In some embodiments, the software components stored in memory **102** include operating system **126**, communication module (or set of instructions) **128**, contact/motion module (or set of instructions) **130**, graphics module (or set of instructions) **132**, text input module (or set of instructions) **134**, Global Positioning System (GPS) module (or set of instructions) **135**, arbiter module **157** and applications (or sets of instructions) **136**. Furthermore, in some embodiments memory **102** stores device/global internal state **157**, as shown in FIGS. **1A** and **3**. Device/global internal state **157** includes one or more of: active application state, indicating which applications, if any, are currently active; display state, indicating what applications, views or other information occupy various regions of touch screen display **112**; sensor

state, including information obtained from the device's various sensors and input control devices **116**; and location information concerning the device's location and/or attitude.

Operating system **126** (e.g., Darwin, RTXC, LINUX, UNIX, OS X, WINDOWS, or an embedded operating system such as VxWorks) includes various software components and/or drivers for controlling and managing general system tasks (e.g., memory management, storage device control, power management, etc.) and facilitates communication between various hardware and software components.

Communication module **128** facilitates communication with other devices over one or more external ports **124** and also includes various software components for handling data received by RF circuitry **108** and/or external port **124**. External port **124** (e.g., Universal Serial Bus (USB), FIREWIRE, etc.) is adapted for coupling directly to other devices or indirectly over a network (e.g., the Internet, wireless LAN, etc.). In some embodiments, the external port is a multi-pin (e.g., 30-pin) connector.

Contact/motion module **130** may detect contact with touch screen **112** (in conjunction with display controller **156**) and other touch sensitive devices (e.g., a touchpad or physical click wheel). Contact/motion module **130** includes various software components for performing various operations related to detection of contact, such as determining if contact has occurred (e.g., detecting a finger-down event), determining if there is movement of the contact and tracking the movement across the touch-sensitive surface (e.g., detecting one or more finger-dragging events), and determining if the contact has ceased (e.g., detecting a finger-up event or a break in contact). Contact/motion module **130** receives contact data from the touch-sensitive surface. Determining movement of the point of contact, which is represented by a series of contact data, may include determining speed (magnitude), velocity (magnitude and direction), and/or an acceleration (a change in magnitude and/or direction) of the point of contact. These operations may be applied to single contacts (e.g., one finger contacts) or to multiple simultaneous contacts (e.g., "multitouch"/multiple finger contacts). In some embodiments, contact/motion module **130** and display controller **156** detect contact on a touchpad.

Contact/motion module **130** may detect a gesture input by a user. Different gestures on the touch-sensitive surface have different contact patterns. Thus, a gesture may be detected by detecting a particular contact pattern. For example, detecting a finger tap gesture includes detecting a finger-down event followed by detecting a finger-up (lift off) event at the same position (or substantially the same position) as the finger-down event (e.g., at the position of an icon). As another example, detecting a finger swipe gesture on the touch-sensitive surface includes detecting a finger-down event followed by detecting one or more finger-dragging events, and subsequently followed by detecting a finger-up (lift off) event.

Graphics module **132** includes various known software components for rendering and displaying graphics on touch screen **112** or other display, including components for changing the intensity of graphics that are displayed. As used herein, the term "graphics" includes any object that can be displayed to a user, including without limitation text, web pages, icons (such as user-interface objects including soft keys), digital images, videos, animations and the like.

In some embodiments, graphics module **132** stores data representing graphics to be used. Each graphic may be assigned a corresponding code. Graphics module **132** receives, from applications etc., one or more codes speci-

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fyng graphics to be displayed along with, if necessary, coordinate data and other graphic property data, and then generates screen image data to output to display controller **156**.

Text input module **134**, which may be a component of graphics module **132**, provides soft keyboards for entering text in various applications (e.g., contacts **137**, e-mail **140**, IM **141**, browser **147**, and any other application that needs text input).

GPS module **135** determines the location of the device and provides this information for use in various applications (e.g., to telephone **138** for use in location-based dialing, to camera **143** as picture/video metadata, and to applications that provide location-based services such as weather widgets, local yellow page widgets, and map/navigation widgets).

Applications **136** may include the following modules (or sets of instructions), or a subset or superset thereof:

- contacts module **137** (sometimes called an address book or contact list);
- telephone module **138**;
- video conferencing module **139**;
- e-mail client module **140**;
- instant messaging (IM) module **141**;
- workout support module **142**;
- camera module **143** for still and/or video images;
- image management module **144**;
- browser module **147**;
- calendar module **148**;
- widget modules **149**, which may include one or more of: weather widget **149-1**, stocks widget **149-2**, calculator widget **149-3**, alarm clock widget **149-4**, dictionary widget **149-5**, and other widgets obtained by the user, as well as user-created widgets **149-6**;
- widget creator module **150** for making user-created widgets **149-6**;
- search module **151**;
- video and music player module **152**, which may be made up of a video player module and a music player module;
- notes module **153**;
- map module **154**; and/or
- online video module **155**.

Examples of other applications **136** that may be stored in memory **102** include other word processing applications, other image editing applications, drawing applications, presentation applications, JAVA-enabled applications, encryption, digital rights management, voice recognition, and voice replication.

In conjunction with touch screen **112**, display controller **156**, contact module **130**, graphics module **132**, and text input module **134**, contacts module **137** may be used to manage an address book or contact list (e.g., stored in application internal state **192** of contacts module **137** in memory **102** or memory **370**), including: adding name(s) to the address book; deleting name(s) from the address book; associating telephone number(s), e-mail address(es), physical address(es) or other information with a name; associating an image with a name; categorizing and sorting names; providing telephone numbers or e-mail addresses to initiate and/or facilitate communications by telephone **138**, video conference **139**, e-mail **140**, or IM **141**; and so forth.

In conjunction with RF circuitry **108**, audio circuitry **110**, speaker **111**, microphone **113**, touch screen **112**, display controller **156**, contact module **130**, graphics module **132**, and text input module **134**, telephone module **138** may be used to enter a sequence of characters corresponding to a

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telephone number, access one or more telephone numbers in address book **137**, modify a telephone number that has been entered, dial a respective telephone number, conduct a conversation and disconnect or hang up when the conversation is completed. As noted above, the wireless communication may use any of a variety of communications standards, protocols and technologies.

In conjunction with RF circuitry **108**, audio circuitry **110**, speaker **111**, microphone **113**, touch screen **112**, display controller **156**, optical sensor **164**, optical sensor controller **158**, contact module **130**, graphics module **132**, text input module **134**, contact list **137**, and telephone module **138**, videoconferencing module **139** includes executable instructions to initiate, conduct, and terminate a video conference between a user and one or more other participants in accordance with user instructions.

In conjunction with RF circuitry **108**, touch screen **112**, display controller **156**, contact module **130**, graphics module **132**, and text input module **134**, e-mail client module **140** includes executable instructions to create, send, receive, and manage e-mail in response to user instructions. In conjunction with image management module **144**, e-mail client module **140** makes it very easy to create and send e-mails with still or video images taken with camera module **143**.

In conjunction with RF circuitry **108**, touch screen **112**, display controller **156**, contact module **130**, graphics module **132**, and text input module **134**, the instant messaging module **141** includes executable instructions to enter a sequence of characters corresponding to an instant message, to modify previously entered characters, to transmit a respective instant message (for example, using a Short Message Service (SMS) or Multimedia Message Service (MMS) protocol for telephony-based instant messages or using XMPP, SIMPLE, or IMPS for Internet-based instant messages), to receive instant messages and to view received instant messages. In some embodiments, transmitted and/or received instant messages may include graphics, photos, audio files, video files and/or other attachments as are supported in a MMS and/or an Enhanced Messaging Service (EMS). As used herein, "instant messaging" refers to both telephony-based messages (e.g., messages sent using SMS or MMS) and Internet-based messages (e.g., messages sent using XMPP, SIMPLE, or IMPS).

In conjunction with RF circuitry **108**, touch screen **112**, display controller **156**, contact module **130**, graphics module **132**, text input module **134**, GPS module **135**, map module **154**, and music player module **146**, workout support module **142** includes executable instructions to create workouts (e.g., with time, distance, and/or calorie burning goals); communicate with workout sensors (sports devices); receive workout sensor data; calibrate sensors used to monitor a workout; select and play music for a workout; and display, store and transmit workout data.

In conjunction with touch screen **112**, display controller **156**, optical sensor(s) **164**, optical sensor controller **158**, contact module **130**, graphics module **132**, and image management module **144**, camera module **143** includes executable instructions to capture still images or video (including a video stream) and store them into memory **102**, modify characteristics of a still image or video, or delete a still image or video from memory **102**.

In conjunction with touch screen **112**, display controller **156**, contact module **130**, graphics module **132**, text input module **134**, and camera module **143**, image management module **144** includes executable instructions to arrange,

modify (e.g., edit), or otherwise manipulate, label, delete, present (e.g., in a digital slide show or album), and store still and/or video images.

In conjunction with RF circuitry **108**, touch screen **112**, display system controller **156**, contact module **130**, graphics module **132**, and text input module **134**, browser module **147** includes executable instructions to browse the Internet in accordance with user instructions, including searching, linking to, receiving, and displaying web pages or portions thereof, as well as attachments and other files linked to web pages.

In conjunction with RF circuitry **108**, touch screen **112**, display system controller **156**, contact module **130**, graphics module **132**, text input module **134**, e-mail client module **140**, and browser module **147**, calendar module **148** includes executable instructions to create, display, modify, and store calendars and data associated with calendars (e.g., calendar entries, to do lists, etc.) in accordance with user instructions.

In conjunction with RF circuitry **108**, touch screen **112**, display system controller **156**, contact module **130**, graphics module **132**, text input module **134**, and browser module **147**, widget modules **149** are mini-applications that may be downloaded and used by a user (e.g., weather widget **149-1**, stocks widget **149-2**, calculator widget **149-3**, alarm clock widget **149-4**, and dictionary widget **149-5**) or created by the user (e.g., user-created widget **149-6**). In some embodiments, a widget includes an HTML (Hypertext Markup Language) file, a CSS (Cascading Style Sheets) file, and a JavaScript file. In some embodiments, a widget includes an XML (Extensible Markup Language) file and a JavaScript file (e.g., Yahoo! Widgets).

In conjunction with RF circuitry **108**, touch screen **112**, display system controller **156**, contact module **130**, graphics module **132**, text input module **134**, and browser module **147**, the widget creator module **150** may be used by a user to create widgets (e.g., turning a user-specified portion of a web page into a widget).

In conjunction with touch screen **112**, display system controller **156**, contact module **130**, graphics module **132**, and text input module **134**, search module **151** includes executable instructions to search for text, music, sound, image, video, and/or other files in memory **102** that match one or more search criteria (e.g., one or more user-specified search terms) in accordance with user instructions.

In conjunction with touch screen **112**, display system controller **156**, contact module **130**, graphics module **132**, audio circuitry **110**, speaker **111**, RF circuitry **108**, and browser module **147**, video and music player module **152** includes executable instructions that allow the user to download and play back recorded music and other sound files stored in one or more file formats, such as MP3 or AAC files, and executable instructions to display, present or otherwise play back videos (e.g., on touch screen **112** or on an external, connected display via external port **124**). In some embodiments, device **100** may include the functionality of an MP3 player.

In conjunction with touch screen **112**, display controller **156**, contact module **130**, graphics module **132**, and text input module **134**, notes module **153** includes executable instructions to create and manage notes, to do lists, and the like in accordance with user instructions.

In conjunction with RF circuitry **108**, touch screen **112**, display system controller **156**, contact module **130**, graphics module **132**, text input module **134**, GPS module **135**, and browser module **147**, map module **154** may be used to receive, display, modify, and store maps and data associated with maps (e.g., driving directions; data on stores and other

points of interest at or near a particular location; and other location-based data) in accordance with user instructions.

In conjunction with touch screen **112**, display system controller **156**, contact module **130**, graphics module **132**, audio circuitry **110**, speaker **111**, RF circuitry **108**, text input module **134**, e-mail client module **140**, and browser module **147**, online video module **155** includes instructions that allow the user to access, browse, receive (e.g., by streaming and/or download), play back (e.g., on the touch screen or on an external, connected display via external port **124**), send an e-mail with a link to a particular online video, and otherwise manage online videos in one or more file formats, such as H.264. In some embodiments, instant messaging module **141**, rather than e-mail client module **140**, is used to send a link to a particular online video.

Each of the above identified modules and applications correspond to a set of executable instructions for performing one or more functions described above and the methods described in this application (e.g., the computer-implemented methods and other information processing methods described herein). These modules (i.e., sets of instructions) need not be implemented as separate software programs, procedures or modules, and thus various subsets of these modules may be combined or otherwise re-arranged in various embodiments. In some embodiments, memory **102** may store a subset of the modules and data structures identified above. Furthermore, memory **102** may store additional modules and data structures not described above.

In some embodiments, device **100** is a device where operation of a predefined set of functions on the device is performed exclusively through a touch screen and/or a touchpad. By using a touch screen and/or a touchpad as the primary input control device for operation of device **100**, the number of physical input control devices (such as push buttons, dials, and the like) on device **100** may be reduced.

The predefined set of functions that may be performed exclusively through a touch screen and/or a touchpad include navigation between user interfaces. In some embodiments, the touchpad, when touched by the user, navigates device **100** to a main, home, or root menu from any user interface that may be displayed on device **100**. In such embodiments, the touchpad may be referred to as a “menu button.” In some other embodiments, the menu button may be a physical push button or other physical input control device instead of a touchpad.

FIG. 2 illustrates a portable multifunction device **100** having a touch screen **112** in accordance with some embodiments. The touch screen may display one or more graphics within user interface (UI) **200**. In this embodiment, as well as others described below, a user may select one or more of the graphics by making a gesture on the graphics, for example, with one or more fingers **202** (not drawn to scale in the figure) or one or more styluses **203** (not drawn to scale in the figure).

Device **100** may also include one or more physical buttons, such as “home” or menu button **204**. As described previously, menu button **204** may be used to navigate to any application **136** in a set of applications that may be executed on device **100**. Alternatively, in some embodiments, the menu button is implemented as a soft key in a GUI displayed on touch screen **112**.

In one embodiment, device **100** includes touch screen **112**, menu button **204**, push button **206** for powering the device on/off and locking the device, volume adjustment button(s) **208**, Subscriber Identity Module (SIM) card slot **210**, head set jack **212**, and docking/charging external port **124**. Push button **206** may be used to turn the power on/off

on the device by depressing the button and holding the button in the depressed state for a predefined time interval; to lock the device by depressing the button and releasing the button before the predefined time interval has elapsed; and/or to unlock the device or initiate an unlock process. In an alternative embodiment, device 100 also may accept verbal input for activation or deactivation of some functions through microphone 113.

It should be noted that, although many of the examples herein are given with reference to optical sensor/camera 164 (on the front of a device), a rear-facing camera or optical sensor that is pointed opposite from the display may be used instead of or in addition to an optical sensor/camera 164 on the front of a device.

FIGS. 3-4 illustrate embodiments of an example actuator assembly in which embodiments of temperature compensation as described herein may be applied. As one of skill in the art will readily ascertain in light of having read the included disclosure, a wide variety of configurations of position sensors and position sensor magnets fulfill differing design goals in different embodiments without departing from the scope and intent of the present disclosure. As one of skill in the art will readily ascertain in light of having read the included disclosure, a wide variety of configurations of actuator fulfill differing design goals in different embodiments without departing from the scope and intent of the present disclosure. For example, while the embodiments shown herein reflect voice coil motor actuators, one of skill in the art will readily understand that different actuators, including no-magnetic motorized actuators such as rotary motors or piezo-electric actuators, can be used with embodiments without departing from the scope and intent of the present disclosure.

FIG. 3A illustrates a top view of an example embodiment of an actuator module or assembly that may, for example, be used to provide capacitive sensing for autofocus position detection in small form factor cameras, according to at least some embodiments. An optics assembly or other lens structure 3010a is held in an optics holder or autofocus coil 3004a, which also carries second capacitor plates 3012a, of a position sensor of an actuator module 3000a. A magnet holder 3006a holds position control magnets 3008a and first capacitor plates 3002a. A first electrically conductive capacitor plate 3002a is mounted to a yoke (magnet holder 3006a). The autofocus yoke (e.g., magnets or holder(s) 3006a) supports a lens carriage (optics assembly or other lens structure 3010a) by means of springs and suspension wires (shown in FIGS. 4A-5). The yoke is attached to a chassis (e.g. a base shown in FIGS. 4A-5) using one or more suspension wires (shown in FIGS. 4A-5). The first electrically conductive capacitor plates 3002a are electrically connected through the one or more suspension wires (shown in FIGS. 4A-5) in parallel with an electrically conductive autofocus coil 3004a of an autofocus actuator module 3000a for moving a lens carriage (optics assembly or other lens structure 3010a), to which second electrically isolated capacitor plates 3012a are mounted. A capacitance between the first electrically conductive capacitor plates 3002a and the second isolated capacitor plates 3012a mounted to autofocus coil 3004a varies as function of the position of the autofocus coil 3004a relative to the first electrically conductive capacitor plates 3002a.

FIG. 3B depicts a top view of an example embodiment of an actuator module or assembly that may, for example, be used to provide capacitive sensing for autofocus position detection in small form factor cameras, according to at least some embodiments. An optics assembly or other lens struc-

ture 3010b is held in an optics holder or autofocus coil 3004b, which serves as part of a position sensor of an actuator module 3000b. A magnet holder 3006b holds position control magnets 3008b and first capacitor plates 3002b. A first electrically conductive capacitor plate 3002b is mounted to a yoke (magnet holder 3006b). The autofocus yoke (e.g., magnets or holder(s) 3006b) supports a lens carriage (optics assembly or other lens structure 3010b) by means of springs and suspension wires (shown in FIGS. 4A-5). The yoke is attached to a chassis (e.g. a base shown in FIGS. 4A-5) using one or more suspension wires (shown in FIGS. 4A-5). The first electrically conductive capacitor plates 3002b are electrically connected through the one or more suspension wires (shown in FIGS. 4A-5) in parallel with an electrically conductive autofocus coil 3004b of an autofocus actuator module 3000b for moving a lens carriage (optics assembly or other lens structure 3010b). A capacitance between the first electrically conductive capacitor plates 3002b and autofocus coil 3004b varies as function of the position of the autofocus coil 3004b relative to the first electrically conductive capacitor plates 3002b.

FIG. 3C illustrates a top view of an example embodiment of an actuator module or assembly that may, for example, be used to provide capacitive sensing for autofocus position detection in small form factor cameras, according to at least some embodiments. An optics assembly or other lens structure 3010c is held in an optics holder or autofocus coil 3004c, which serves as part of a position sensor of an actuator module 3000c. A magnet holder 3006c holds position control magnets 3008c and first capacitor plate 3002c. A first electrically conductive capacitor plate 3002c is mounted to a yoke (magnet holder 3006c). The autofocus yoke (e.g., magnets or holder(s) 3006c) supports a lens carriage (optics assembly or other lens structure 3010c) by means of springs and suspension wires (shown in FIGS. 4A-5). The yoke is attached to a chassis (e.g. a base shown in FIGS. 4A-5) using one or more suspension wires (shown in FIGS. 4A-5). The first electrically conductive capacitor plate 3002c is electrically connected through the one or more suspension wires (shown in FIGS. 4A-5) in parallel with an electrically conductive autofocus coil 3004c of an autofocus actuator module 3000c for moving a lens carriage (optics assembly or other lens structure 3010c). A capacitance between the first electrically conductive capacitor plate 3002c and autofocus coil 3004c varies as function of the position of the autofocus coil 3004c relative to the first electrically conductive capacitor plate 3002c.

FIG. 4A depicts a side view of an example embodiment of an actuator module or assembly that may, for example, be used to provide capacitive sensing for autofocus position detection in small form factor cameras, according to at least some embodiments.

FIGS. 4A-5 depict side views of example embodiments of an actuator module or assembly that may, for example, be used to provide capacitive sensing for autofocus position detection in small form factor cameras, according to at least some embodiments. In particular, with reference to FIG. 4A, embodiments of capacitive sensing for autofocus position detection may be applied within an actuator package or assembly 4000 interacting with an image sensor 4050 as illustrated in FIGS. 3 and 4A-5 to stabilize and increase control performance of an optics assembly 4002 suspended on wires 4020 within an actuator package 3000a-c as shown in FIG. 3A-C. Details of example embodiments, implementations, and methods of operations of optical image stabilization actuators and associated sensors such as the example

actuator package 3000 shown in these FIGs are discussed below with respect to FIGS. 6A-10C.

In some embodiments, each position control magnet 4006 is poled so as to generate a magnetic field, the useful component of which for the autofocus function is orthogonal to the optical axis of the camera/lens, and orthogonal to the plane of each magnet 4006 proximate to the autofocus coil 4004, and where the field for all four magnets 4006 are all either directed towards the autofocus coil 4004, or away from it, so that the Lorentz forces from all four magnets 4004 act in the same direction along the optical axis 4080.

As shown in FIG. 4A, an actuator package 4000 may include a base assembly or substrate 4008, an optics assembly 4002, and a cover 4012. Base assembly 4008 may include one or more of, but is not limited to, a base 4008, supporting one or more position sensors (e.g., capacitor plates) 4010a-b, and suspension wires 4020, which enable capacitive sensing for autofocus position detection by detecting movements of autofocus coil 4004. In some embodiments, both of capacitor plates 4010a-b (collectively referred to as capacitor plate 4010) may be used. Other embodiments omit one of capacitor plates 4010a-b and only a single first capacitor plate 4010a is present. In some embodiments, capacitor plates additional to both of capacitor plates 4010a-b (referred to as capacitor plate 4010) may be used. One of ordinary skill in the art will readily understand in light of having read the present disclosure that variations in the number of capacitor plates 4010a-b may be made in various embodiments without departing from the scope and intent of the present disclosure.

In at least some embodiments, there are four suspension wires 4020. An optics assembly 4002 may be suspended on the base assembly 4008 by suspension of the upper springs 4040 of optics assembly 4000 on the suspension wires 4020. Actuator module 4000 may include one or more of, but is not limited to, optics 4002, optics holder (autofocus coil) 4004, magnet(s) 4006, upper spring(s) 4040, and lower spring(s) 4042. The upper and lower spring(s) may be collectively referred to herein as optics springs. In optics assembly 4000, an optics component 4002 (e.g., a lens or lens assembly) may be screwed, mounted or otherwise held in or by an optics holder (autofocus coil) 4004. In at least some embodiments, the optics 4002/optics holder (autofocus coil) 4004 assembly may be suspended from or attached to the position control magnets 4006 by upper spring(s) 4040, and lower spring(s) 4042, and the position control magnets 4006 may be rigidly mounted to base 4008. Note that upper spring(s) 4040 and lower spring(s) 4042 are flexible to allow the optics assembly 4000 a range of motion along the Z (optical) axis for optical focusing, wires 4020 are flexible to allow a range of motion on the XY plane orthogonal to the optical axis for optical image stabilization.

Note that, in some embodiments, an optics assembly 4000 or an actuator actuator module may not include position control magnets 4006, but may include a yoke or other structure 4006 that may be used to help support the optics assembly on suspension wires 4020 via upper sprigs 4030. However in some embodiments, optics assembly 4000 may not include elements 4006. In general, other embodiments of an optics assembly 4000 may include fewer or more components than the example optics assembly 4000 shown in FIG. 4. Also note that, while embodiments show the optics assembly 4000 suspended on wires 4020, other mechanisms may be used to suspend an optics assembly 4000 in other embodiments.

The autofocus yoke (e.g., magnets or holder(s) 4006) acts as the support chassis structure for the autofocus mechanism

of actuator 4000. The lens carrier (optics holder 4004) is suspended on the autofocus yoke by an upper autofocus (AF) spring 4040 and a lower optics spring 4042. In this way when an electric current is applied to the autofocus coil, Lorentz forces are developed due to the presence of the four magnets, and a force substantially parallel to the optical axis is generated to move the lens carrier, and hence lens, along the optical axis, relative to the support structure of the autofocus mechanism of the actuator, so as to focus the lens. In addition to suspending the lens carrier and substantially eliminating parasitic motions, the upper spring 4040 and lower spring 4042 also resist the Lorentz forces, and hence convert the forces to a displacement of the lens. This basic architecture shown in FIGS. 3-4 and is typical of some embodiments, in which optical image stabilization function includes moving the entire autofocus mechanism of the actuator (supported by the autofocus yoke) in linear directions orthogonal to the optical axis, in response to user handshake, as detected by some means, such a two or three axis gyroscope, which senses angular velocity. The handshake of interest is the changing angular tilt of the camera in 'pitch and yaw directions', which can be compensated by said linear movements of the lens relative to the image sensor.

At least some embodiments may achieve this two independent degree-of-freedom motion by using two pairs of optical image stabilization coils, each pair acting together to deliver controlled motion in one linear axis orthogonal to the optical axis, and each pair delivering controlled motion in a direction substantially orthogonal to the other pair. In at least some embodiments, these optical image stabilization coils may be fixed to the camera actuator support structure, and when current is appropriately applied, optical image stabilization coils may generate Lorentz forces on the entire autofocus mechanism of the actuator, moving it as desired. The required magnetic fields for the Lorentz forces are produced by the same four magnets that enable to the Lorentz forces for the autofocus function. However, since the directions of motion of the optical image stabilization movements are orthogonal to the autofocus movements, it is the fringing field of the four magnets that are employed, which have components of magnetic field in directions parallel to the optical axis.

Returning to FIGS. 3-4, in at least some embodiments, the suspension of the autofocus mechanism on the actuator 4000 support structure may be achieved by the use of four corner wires 4020, for example wires with a circular cross-section. Each wire 4020 acts as a flexure beams capable of bending with relatively low stiffness, thus allowing motion in both optical image stabilization degrees-of-freedom. However, wire 4020 is in some embodiments relatively stiff in directions parallel to the optical axis, as this would require the wire to stretch or buckle, thus substantially preventing parasitic motions in these directions. In addition, the presence of four such wires, appropriately separated allows them to be stiff in the parasitic tilt directions of pitch and yaw, thus substantially preventing relative dynamic tilt between the lens and image sensor. This may be seen by appreciating that each wire 4020 is stiff in directions that require it to change in length, and hence the fixed points at the ends of each wire (eight points in total) will substantially form the vertices of a parallelepiped for all operational positions of the optical image stabilization mechanism.

In some embodiments, a package of processors and memory 4090 or other computer-readable medium as described herein may alternatively, in some embodiments,

be omitted from actuator module **4000** and housed elsewhere in a device in which actuator package **4000** is installed.

In some embodiments, actuator package **4000** is installed in a camera of a mobile computing device. Either of capacitor plates **4010** is a first electrically conductive capacitor plate mounted to a yoke. The autofocus yoke (e.g., magnets or holder(s) **4006**) supports a lens carriage (e.g., optics **4002**). The yoke is attached to a chassis (e.g. base **4008**) using one or more suspension wires **4020**. The first electrically conductive capacitor plate **4010** is electrically connected through the one or more suspension wires **4020** in parallel with an electrically conductive autofocus coil **4004** of an autofocus actuator mechanism **4000** for moving a lens carriage **4002**. A capacitance between the first electrically conductive capacitor plate **4010** and the autofocus coil **4004** varies as function of the position of the autofocus coil **4004** relative to the first electrically conductive capacitor plate **4010**.

In some embodiments, driver circuit **4090** includes a voltage source capable of delivering an impulse alternating electrical signal to the autofocus coil **4004**.

In some embodiments, driver circuit **4090** includes a measurement circuit for measuring a resonant frequency of a resonant inductance-capacitance circuit comprising the autofocus coil **4004** and the first capacitor plate **4010** in response to the impulse.

In some embodiments, driver circuit **4090** includes position measurement logic for measuring the position of the lens carriage relative to the chassis by applying an alternating electrical signal to the autofocus coil, and measuring a resonant frequency of a resonant inductance-capacitance circuit comprising the autofocus coil and the first capacitor plate. In some embodiments, first electrically conductive capacitor plate **4010a** and a second electrically conductive capacitor plate **4010b** are at even heights, such that first electrically conductive capacitor plate **4010a** is mounted at position a along an optical axis of the camera corresponding to from a position along an optical axis of the camera of the second electrically conductive capacitor plate **4010b**, and the second electrically conductive capacitor plate **4010b** is electrically connected in parallel with an autofocus coil of an actuator for moving the lens carriage using the one or more suspension wires.

FIG. **4B** depicts a side view of an example embodiment of an actuator module or assembly that may, for example, be used to provide capacitive sensing for autofocus position detection in small form factor cameras, according to at least some embodiments. Embodiments of capacitive sensing for autofocus position detection may be applied within an actuator package or assembly **4111** interacting with an image sensor **4151** as illustrated in FIGS. **3** and **4A-5** to stabilize and increase control performance of an optics assembly **4112** suspended on wires **4121** within an actuator package **3000a-c** as shown in FIG. **3A-C**. Details of example embodiments, implementations, and methods of operations of optical image stabilization actuators and associated sensors such as the example actuator package **3000** shown in these FIGs are discussed below with respect to FIGS. **6A-11**.

In some embodiments, each position control magnet **4116** is poled so as to generate a magnetic field, the useful component of which for the autofocus function is orthogonal to the optical axis of the camera/lens, and orthogonal to the plane of each magnet **4116** proximate to the autofocus coil **4114**, and where the field for all four magnets **4116** are all either directed towards the autofocus coil **4114**, or away

from it, so that the Lorentz forces from all four magnets **4116** act in the same direction along the optical axis **4181**.

As shown in FIG. **4A**, an actuator package **4111** may include a base assembly or substrate **4118**, an optics assembly **4112**, and a cover **4115**. Base assembly **4118** may include one or more of, but is not limited to, a base **4118**, supporting one or more position sensors (e.g., capacitor plates) **4113a-b**, and suspension wires **4121**, which enable capacitive sensing for autofocus position detection by detecting movements of autofocus coil **4114**.

In at least some embodiments, there are four suspension wires **4121**. An optics assembly **4112** may be suspended on the base assembly **4118** by suspension of the upper springs **4141** of optics assembly **4111** on the suspension wires **4121**. Actuator module **4111** may include one or more of, but is not limited to, optics **4112**, optics holder (autofocus coil) **4114**, magnet(s) **4116**, upper spring(s) **4141**, and lower spring(s) **4142**. The upper and lower spring(s) may be collectively referred to herein as optics springs. In optics assembly **4111**, an optics component **4112** (e.g., a lens or lens assembly) may be screwed, mounted or otherwise held in or by an optics holder (autofocus coil) **4114**. In at least some embodiments, the optics **4112**/optics holder (autofocus coil) **4114** assembly may be suspended from or attached to the position control magnets **4116** by upper spring(s) **4141**, and lower spring(s) **4142**, and the position control magnets **4116** may be rigidly mounted to base **4118**. Note that upper spring(s) **4141** and lower spring(s) **4142** are flexible to allow the optics assembly **4111** a range of motion along the Z (optical) axis for optical focusing, wires **4121** are flexible to allow a range of motion on the XY plane orthogonal to the optical axis for optical image stabilization.

Note that, in some embodiments, an optics assembly **4111** or an actuator module may not include position control magnets **4116**, but may include a yoke or other structure **4116** that may be used to help support the optics assembly on suspension wires **4121** via upper sprigs **4131**. However in some embodiments, optics assembly **4111** may not include elements **4116**. In general, other embodiments of an optics assembly **4111** may include fewer or more components than the example optics assembly **4111** shown in FIG. **4**. Also note that, while embodiments show the optics assembly **4111** suspended on wires **4121**, other mechanisms may be used to suspend an optics assembly **4111** in other embodiments.

The autofocus yoke (e.g., magnets or holder(s) **4116**) acts as the support chassis structure for the autofocus mechanism of actuator **4111**. The lens carrier (optics holder **4114**) is suspended on the autofocus yoke by an upper autofocus (AF) spring **4141** and a lower optics spring **4142**. In this way when an electric current is applied to the autofocus coil, Lorentz forces are developed due to the presence of the four magnets, and a force substantially parallel to the optical axis is generated to move the lens carrier, and hence lens, along the optical axis, relative to the support structure of the autofocus mechanism of the actuator, so as to focus the lens. In addition to suspending the lens carrier and substantially eliminating parasitic motions, the upper spring **4141** and lower spring **4142** also resist the Lorentz forces, and hence convert the forces to a displacement of the lens. This basic architecture shown in FIGS. **3-4** and is typical of some embodiments, in which optical image stabilization function includes moving the entire autofocus mechanism of the actuator (supported by the autofocus yoke) in linear directions orthogonal to the optical axis, in response to user handshake, as detected by some means, such as two or three axis gyroscope, which senses angular velocity. The hand-

shake of interest is the changing angular tilt of the camera in 'pitch and yaw directions', which can be compensated by said linear movements of the lens relative to the image sensor.

At least some embodiments may achieve this two independent degree-of-freedom motion by using two pairs of optical image stabilization coils, each pair acting together to deliver controlled motion in one linear axis orthogonal to the optical axis, and each pair delivering controlled motion in a direction substantially orthogonal to the other pair. In at least some embodiments, these optical image stabilization coils may be fixed to the camera actuator support structure, and when current is appropriately applied, optical image stabilization coils may generate Lorentz forces on the entire autofocus mechanism of the actuator, moving it as desired. The required magnetic fields for the Lorentz forces are produced by the same four magnets that enable to the Lorentz forces for the autofocus function. However, since the directions of motion of the optical image stabilization movements are orthogonal to the autofocus movements, it is the fringing field of the four magnets that are employed, which have components of magnetic field in directions parallel to the optical axis.

Returning to FIGS. 3-4, in at least some embodiments, the suspension of the autofocus mechanism on the actuator **4111** support structure may be achieved by the use of four corner wires **4121**, for example wires with a circular cross-section. Each wire **4121** acts as a flexure beams capable of bending with relatively low stiffness, thus allowing motion in both optical image stabilization degrees-of-freedom. However, wire **4121** is in some embodiments relatively stiff in directions parallel to the optical axis, as this would require the wire to stretch or buckle, thus substantially preventing parasitic motions in these directions. In addition, the presence of four such wires, appropriately separated allows them to be stiff in the parasitic tilt directions of pitch and yaw, thus substantially preventing relative dynamic tilt between the lens and image sensor. This may be seen by appreciating that each wire **4121** is stiff in directions that require it to change in length, and hence the fixed points at the ends of each wire (eight points in total) will substantially form the vertices of a parallelepiped for all operational positions of the optical image stabilization mechanism.

In some embodiments, a package of processors and memory **4191** or other computer-readable medium as described herein may alternatively, in some embodiments, be omitted from actuator module **4111** and housed elsewhere in a device in which actuator package **4111** is installed.

In some embodiments, actuator package **4111** is installed in a camera of a mobile computing device. First and second capacitor plates **4113** are electrically conductive capacitor plate mounted to a yoke. The autofocus yoke (e.g., magnets or holder(s) **4116**) supports a lens carriage (e.g., optics **4112**). The yoke is attached to a chassis (e.g. base **4118**) using one or more suspension wires **4121**. Capacitor plates **4113** are electrically connected through the one or more suspension wires **4121** in parallel with an electrically conductive autofocus coil **4114** of an autofocus actuator mechanism **4111** for moving a lens carriage **4112**. A capacitance between the electrically conductive capacitor plates **4113** and the autofocus coil **4114** varies as function of the position of the autofocus coil **4114** relative to the electrically conductive capacitor plates **4113**.

In some embodiments, driver circuit **4191** includes a voltage source capable of delivering an impulse alternating electrical signal to the autofocus coil **4114**.

In some embodiments, driver circuit **4191** includes a measurement circuit for measuring a resonant frequency of a resonant inductance-capacitance circuit comprising the autofocus coil **4114** and the capacitor plates **4113** in response to the impulse.

In some embodiments, driver circuit **4191** includes position measurement logic for measuring the position of the lens carriage relative to the chassis by applying an alternating electrical signal to the autofocus coil, and measuring a resonant frequency of a resonant inductance-capacitance circuit comprising the autofocus coil and the capacitor plates.

In some embodiments, a second electrically conductive capacitor plate **4113b** mounted to the yoke **4114**. In some embodiments, the second electrically conductive capacitor plate **4113b** is mounted at a position along an optical axis **4181** of the camera different from a position along an optical axis **4181** of the camera from the first electrically conductive capacitor plate **4113a**, and the second electrically conductive capacitor plate **4113b** is electrically connected in parallel with an autofocus coil of an actuator for moving the lens carriage using the one or more suspension wires.

FIG. 5 illustrates a side view of an example embodiment of an actuator module or assembly that may, for example, be used to provide capacitive sensing for autofocus position detection in small form factor cameras, according to at least some embodiments. Embodiments of capacitive sensing for autofocus position detection may be applied within an actuator package or assembly **5000** interacting with an image sensor **5050** as illustrated in FIGS. 3 and 4A-5 to stabilize and increase control performance of an optics assembly **5002** suspended on wires **5020** within an actuator package **3000a-c** as shown in FIG. 3A-C. Details of example embodiments, implementations, and methods of operations of optical image stabilization actuators and associated sensors such as the example actuator package **3000** shown in these FIGs are discussed below with respect to FIGS. 6A-10C.

In some embodiments, each position control magnet **5006** is poled so as to generate a magnetic field, the useful component of which for the autofocus function is orthogonal to the optical axis of the camera/lens, and orthogonal to the plane of each magnet **5006** proximate to the autofocus coil **5005**, and where the field for all four magnets **5006** are all either directed towards the autofocus coil **5005**, or away from it, so that the Lorentz forces from all four magnets **5005** act in the same direction along the optical axis **5080**.

As shown in FIG. 5A, an actuator package **5000** may include a base assembly or substrate **5008**, an optics assembly **5002**, and a cover **5012**. Base assembly **5008** may include one or more of, but is not limited to, a base **5008**, supporting one or more position sensors (e.g., capacitor plates) **5010a-b**, and suspension wires **5020**, which enable capacitive sensing for autofocus position detection by detecting movements of autofocus coil **5005**. In some embodiments, both of capacitor plates **5010a-b** (collectively referred to as capacitor plate **5010**) may be used. Other embodiments omit one of capacitor plates **5010a-b** and only a single first capacitor plate **5010a** is present. In some embodiments, capacitor plates additional to both of capacitor plates **5010a-b** (referred to as capacitor plate **5010**) may be used. One of ordinary skill in the art will readily understand in light of having read the present disclosure that variations in the number of capacitor plates **5010a-b** may be made in various embodiments without departing from the scope and intent of the present disclosure.

In at least some embodiments, there are four suspension wires **5020**. An optics assembly **5002** may be suspended on the base assembly **5008** by suspension of the upper springs **5050** of optics assembly **5000** on the suspension wires **5020**. Actuator module **5000** may include one or more of, but is not limited to, optics **5002**, optics holder (autofocus coil) **5005**, magnet(s) **5006**, upper spring(s) **5050**, and lower spring(s) **5052**. The upper and lower spring(s) may be collectively referred to herein as optics springs. In optics assembly **5000**, an optics component **5002** (e.g., a lens or lens assembly) may be screwed, mounted or otherwise held in or by an optics holder (autofocus coil) **5005**. In at least some embodiments, the optics **5002**/optics holder (autofocus coil) **5005** assembly may be suspended from or attached to the position control magnets **5006** by upper spring(s) **5050**, and lower spring(s) **5052**, and the position control magnets **5006** may be rigidly mounted to base **5008**. Note that upper spring(s) **5050** and lower spring(s) **5052** are flexible to allow the optics assembly **5000** a range of motion along the Z (optical) axis for optical focusing, wires **5020** are flexible to allow a range of motion on the XY plane orthogonal to the optical axis for optical image stabilization.

Note that, in some embodiments, an optics assembly **5000** or an actuator actuator module may not include position control magnets **5006**, but may include a yoke or other structure **5006** that may be used to help support the optics assembly on suspension wires **5020** via upper springs **5030**. However in some embodiments, optics assembly **5000** may not include elements **5006**. In general, other embodiments of an optics assembly **5000** may include fewer or more components than the example optics assembly **5000** shown in FIG. 5. Also note that, while embodiments show the optics assembly **5000** suspended on wires **5020**, other mechanisms may be used to suspend an optics assembly **5000** in other embodiments.

The autofocus yoke (e.g., magnets or holder(s) **5006**) acts as the support chassis structure for the autofocus mechanism of actuator **5000**. The lens carrier (optics holder **5005**) is suspended on the autofocus yoke by an upper autofocus (AF) spring **5050** and a lower optics spring **5052**. In this way when an electric current is applied to the autofocus coil, Lorentz forces are developed due to the presence of the four magnets, and a force substantially parallel to the optical axis is generated to move the lens carrier, and hence lens, along the optical axis, relative to the support structure of the autofocus mechanism of the actuator, so as to focus the lens. In addition to suspending the lens carrier and substantially eliminating parasitic motions, the upper spring **5050** and lower spring **5052** also resist the Lorentz forces, and hence convert the forces to a displacement of the lens. This basic architecture shown in FIGS. 3-5 and is typical of some embodiments, in which optical image stabilization function includes moving the entire autofocus mechanism of the actuator (supported by the autofocus yoke) in linear directions orthogonal to the optical axis, in response to user handshake, as detected by some means, such a two or three axis gyroscope, which senses angular velocity. The handshake of interest is the changing angular tilt of the camera in 'pitch and yaw directions', which can be compensated by said linear movements of the lens relative to the image sensor.

At least some embodiments may achieve this two independent degree-of-freedom motion by using two pairs of optical image stabilization coils, each pair acting together to deliver controlled motion in one linear axis orthogonal to the optical axis, and each pair delivering controlled motion in a direction substantially orthogonal to the other pair. In at least

some embodiments, these optical image stabilization coils may be fixed to the camera actuator support structure, and when current is appropriately applied, optical image stabilization coils may generate Lorentz forces on the entire autofocus mechanism of the actuator, moving it as desired. The required magnetic fields for the Lorentz forces are produced by the same four magnets that enable to the Lorentz forces for the autofocus function. However, since the directions of motion of the optical image stabilization movements are orthogonal to the autofocus movements, it is the fringing field of the four magnets that are employed, which have components of magnetic field in directions parallel to the optical axis.

Returning to FIGS. 3-5, in at least some embodiments, the suspension of the autofocus mechanism on the actuator **5000** support structure may be achieved by the use of four corner wires **5020**, for example wires with a circular cross-section. Each wire **5020** acts as a flexure beams capable of bending with relatively low stiffness, thus allowing motion in both optical image stabilization degrees-of-freedom. However, wire **5020** is in some embodiments relatively stiff in directions parallel to the optical axis, as this would require the wire to stretch or buckle, thus substantially preventing parasitic motions in these directions. In addition, the presence of four such wires, appropriately separated allows them to be stiff in the parasitic tilt directions of pitch and yaw, thus substantially preventing relative dynamic tilt between the lens and image sensor. This may be seen by appreciating that each wire **5020** is stiff in directions that require it to change in length, and hence the fixed points at the ends of each wire (eight points in total) will substantially form the vertices of a parallelepiped for all operational positions of the optical image stabilization mechanism.

In some embodiments, a package of processors and memory **5090** or other computer-readable medium as described herein may alternatively, in some embodiments, be omitted from actuator module **5000** and housed elsewhere in a device in which actuator package **5000** is installed.

In some embodiments, actuator package **5000** is installed in a camera of a mobile computing device. A first electrically conductive capacitor plate **5010** mounted to a yoke. The autofocus yoke (e.g., magnets or holder(s) **5006**) supports a lens carriage (e.g., optics **5002**). The yoke is attached to a chassis (e.g. base **5008**) using one or more suspension wires **5020**. The first electrically conductive capacitor plate **5010** is electrically connected through the one or more suspension wires **5020** in parallel with an electrically conductive autofocus coil **5005** of an autofocus actuator mechanism **5000** for moving a lens carriage **5002**, to which a second capacitor plate **5010b** is mounted. A capacitance between the first electrically conductive capacitor plate **5010a** and the second capacitor plate **5010b** mounted to autofocus coil **5005** varies as function of the position of the autofocus coil **5005** relative to the first electrically conductive capacitor plate **5010**.

In some embodiments, driver circuit **5090** includes a measurement circuit for measuring a resonant frequency of a resonant inductance-capacitance circuit comprising the autofocus coil **5005** and the first capacitor plate **5010a** in response to the impulse.

In some embodiments, driver circuit **5090** includes position measurement logic for measuring the position of the lens carriage relative to the chassis by applying an alternating electrical signal to the autofocus coil **5005**, and measuring a resonant frequency of a resonant inductance-capacitance circuit comprising the autofocus coil **5005** and the first capacitor plate **5010a**. In some embodiments, first

electrically conductive capacitor plate **5010a** and a second electrically conductive capacitor plate **5010b** are at even heights, such that first electrically conductive capacitor plate **5010a** is mounted at a position along an optical axis of the camera corresponding to from a position along an optical axis of the camera of the second electrically conductive capacitor plate **5010b**.

FIG. **6A** depicts a top view of an example embodiment of an actuator module or assembly that may, for example, be used to provide capacitive sensing for autofocus position detection in small form factor cameras, according to at least some embodiments. In an actuator package **600**, a pair of sphere chassis capacitor plates **630** is electrically connected in parallel with an autofocus coil **660** inductor by means of suspension wires **640** and suspension springs **680**. Note that in some embodiments, the connection of sphere chassis capacitor plates **630** to autofocus coil **660** is not present. That is, in some embodiments, sphere chassis capacitor plates **630** are isolated from autofocus coil **660** and no signal from sphere chassis capacitor plates **630** is carried across autofocus suspension springs **680**. A lens carriage capacitor plate **670** without electrical connection is mounted to a lens carriage **620**.

In some embodiments, one of skill in the art considering the four suspension wires **680** in light of the present specification will readily ascertain that, if two wires are used for the autofocus coil **660** and two for the capacitance plates **630**, on the yoke, embodiments exist in which the two capacitance plates **630** on the right hand side are not connected in the picture. Such embodiments do not depart from the scope and intent of the present specification. Embodiments exist in which the two capacitance plates **630** on the right hand side are not connected in the picture can be omitted altogether, or connected via an LDS track to the plates on the left. In some embodiments it is advantageous to have the right hand plates **630** to improve sensitivity and reduce sensitivity to manufacturing tolerance, but some embodiments rely strictly on the left hand plates without departing from the scope and intent of the present disclosure. As will be apparent to one of ordinary skill in the art in light of having read the present disclosure, in some embodiments the capacitor configuration is not a differential measure of position (where one capacitance gets bigger, whilst the other gets smaller as the AF coil moves and then we measure the difference between them).

FIG. **6B** depicts a schematic view of an example embodiment of a circuit that may, for example, be used to provide capacitive sensing for autofocus position detection in small form factor cameras, according to at least some embodiments. In circuit **602**, four capacitors **642** are connected in parallel with an inductor **632** between a first terminal **612** and a second terminal **622**.

FIGS. **7A** and **7B** illustrate an example embodiment capacitive sensor hardware that may, for example, be used to provide capacitive sensing for autofocus position detection in small form factor cameras, according to at least some embodiments. A flexible printed circuit **700** electrically isolates two chassis capacitors **710** from a chassis. A complementary (second) capacitor plate **730** is electrically isolated from an autofocus coil by a flexible printed circuit **720**.

In operation at infinite focus **702**, complementary (second) capacitor plate **708** has minimal overlap **706** minimally with first capacitor plates **704**. In operation at neutral position focus **722**, complementary (second) capacitor plate **728** has medium overlap **726** minimally with first capacitor plates **724**. In operation at macro focus **732**, complementary

(second) capacitor plate **738** has maximum overlap **736** minimally with first capacitor plates **734**.

FIG. **8A** is a flowchart of a method to provide capacitive sensing for autofocus position detection, according to at least some embodiments. An impulse alternating electrical signal is delivered to an autofocus coil (block **820**). A position of the autofocus coil is calculated by measuring a resonant frequency of a resonant inductance-capacitance circuit comprising the autofocus coil and a first capacitor plate in response to the impulse (block **830**).

FIG. **8B** is a flowchart of a method to provide capacitive sensing for autofocus position detection, according to at least some embodiments. An impulse alternating electrical signal is delivered to an autofocus coil (block **822**). A position of the autofocus coil is calculated by measuring a resonant frequency of a resonant inductance-capacitance circuit comprising the autofocus coil and a first capacitor plate in response to the impulse (block **832**). A position of the autofocus coil is adjusted by altering a voltage input to the autofocus coil based at least in part on the measurement (block **842**). The delivering and the adjusting are repeated (block **852**).

FIG. **9A** is a flowchart of a method to provide capacitive sensing for autofocus position detection, according to at least some embodiments. An impulse alternating electrical signal is delivered to an autofocus coil (block **922**). A position of the autofocus coil is calculated by measuring a resonant frequency of a resonant inductance-capacitance circuit comprising the autofocus coil and a first capacitor plate in response to the impulse (block **932**). The delivering and calculating are repeated to measure a capacitance between the first electrically conductive capacitor plate and the autofocus coil that varies as function of the position of the autofocus coil relative to the first electrically conductive capacitor plate (block **942**).

FIG. **9B** is a flowchart of a method to provide capacitive sensing for autofocus position detection, according to at least some embodiments. An impulse alternating electrical signal is delivered to an autofocus coil (block **920**). A position of the autofocus coil is calculated by measuring a resonant frequency of a resonant inductance-capacitance circuit comprising the autofocus coil and a first capacitor plate in response to the impulse by measuring a capacitance between the first electrically conductive capacitor plate and the autofocus coil that varies as function of the position of the autofocus coil relative to the first electrically conductive capacitor plate (block **930**).

FIG. **10A** is a flowchart of a method to provide capacitive sensing for autofocus position detection, according to at least some embodiments. An impulse alternating electrical signal is delivered to an autofocus coil (block **1022**). A position of the autofocus coil is calculated by measuring a resonant frequency of a resonant inductance-capacitance circuit comprising the autofocus coil and a first capacitor plate in response to the impulse (block **1032**). A position of the autofocus coil is adjusted by altering a voltage input to the autofocus coil based at least in part on the measurement such that the impulse alternating electrical signal to the autofocus coil at a frequency different from a signal used to adjust the autofocus coil (block **1042**).

FIG. **10B** is a flowchart of a method to provide capacitive sensing for autofocus position detection, according to at least some embodiments. An impulse alternating electrical signal is delivered to an autofocus coil through a parallel electrical connection between the first capacitor plate and the autofocus coil (block **1020**). A position of the autofocus coil is calculated by measuring a resonant frequency of a

resonant inductance-capacitance circuit comprising the autofocus coil and a first capacitor plate in response to the impulse (block 1030).

FIG. 10C is a flowchart of a method to provide capacitive sensing for autofocus position detection, according to at least some embodiments. An impulse alternating electrical signal is delivered to an autofocus coil through a parallel electrical connection between the first capacitor plate and the autofocus coil via one or more suspension wires of the actuator mechanism (block 1024). A position of the autofocus coil is calculated by measuring a resonant frequency of a resonant inductance-capacitance circuit comprising the autofocus coil and a first capacitor plate in response to the impulse (block 1034).

Example Computer System

FIG. 11 illustrates an example computer system 1100 that may be configured to execute any or all of the embodiments described above. In different embodiments, computer system 1100 may be any of various types of devices, including, but not limited to, a personal computer system, desktop computer, laptop, notebook, tablet, slate, pad, or netbook computer, mainframe computer system, handheld computer, workstation, network computer, a camera, a set top box, a mobile device, a consumer device, video game console, handheld video game device, application server, storage device, a television, a video recording device, a peripheral device such as a switch, modem, router, or in general any type of computing or electronic device.

Various embodiments of a camera motion control system as described herein, including embodiments of capacitive position sensing, as described herein may be executed in one or more computer systems 1100, which may interact with various other devices. Note that any component, action, or functionality described above with respect to FIGS. 1-10 may be implemented on one or more computers configured as computer system 1100 of FIG. 11, according to various embodiments. In the illustrated embodiment, computer system 1100 includes one or more processors 1110 coupled to a system memory 1120 via an input/output (I/O) interface 1130. Computer system 1100 further includes a network interface 1140 coupled to I/O interface 1130, and one or more input/output devices 1150, such as cursor control device 1160, keyboard 1170, and display(s) 1180. In some cases, it is contemplated that embodiments may be implemented using a single instance of computer system 1100, while in other embodiments multiple such systems, or multiple nodes making up computer system 1100, may be configured to host different portions or instances of embodiments. For example, in one embodiment some elements may be implemented via one or more nodes of computer system 1100 that are distinct from those nodes implementing other elements.

In various embodiments, computer system 1100 may be a uniprocessor system including one processor 1110, or a multiprocessor system including several processors 1110 (e.g., two, four, eight, or another suitable number). Processors 1110 may be any suitable processor capable of executing instructions. For example, in various embodiments processors 1110 may be general-purpose or embedded processors implementing any of a variety of instruction set architectures (ISAs), such as the x86, PowerPC, SPARC, or MIPS ISAs, or any other suitable ISA. In multiprocessor systems, each of processors 1110 may commonly, but not necessarily, implement the same ISA.

System memory 1120 may be configured to store camera control program instructions 1122 and/or camera control data accessible by processor 1110. In various embodiments,

system memory 1120 may be implemented using any suitable memory technology, such as static random access memory (SRAM), synchronous dynamic RAM (SDRAM), nonvolatile/Flash-type memory, or any other type of memory. In the illustrated embodiment, program instructions 1122 may be configured to implement a lens control application 1124 incorporating any of the functionality described above. Additionally, existing camera control data 1132 of memory 1120 may include any of the information or data structures described above. In some embodiments, program instructions and/or data may be received, sent or stored upon different types of computer-accessible media or on similar media separate from system memory 1120 or computer system 1100. While computer system 1100 is described as implementing the functionality of functional blocks of previous Figures, any of the functionality described herein may be implemented via such a computer system.

In one embodiment, I/O interface 1130 may be configured to coordinate I/O traffic between processor 1110, system memory 1120, and any peripheral devices in the device, including network interface 1140 or other peripheral interfaces, such as input/output devices 1150. In some embodiments, I/O interface 1130 may perform any necessary protocol, timing or other data transformations to convert data signals from one component (e.g., system memory 1120) into a format suitable for use by another component (e.g., processor 1110). In some embodiments, I/O interface 1130 may include support for devices attached through various types of peripheral buses, such as a variant of the Peripheral Component Interconnect (PCI) bus standard or the Universal Serial Bus (USB) standard, for example. In some embodiments, the function of I/O interface 1130 may be split into two or more separate components, such as a north bridge and a south bridge, for example. Also, in some embodiments some or all of the functionality of I/O interface 1130, such as an interface to system memory 1120, may be incorporated directly into processor 1110.

Network interface 1140 may be configured to allow data to be exchanged between computer system 1100 and other devices attached to a network 1185 (e.g., carrier or agent devices) or between nodes of computer system 1100. Network 1185 may in various embodiments include one or more networks including but not limited to Local Area Networks (LANs) (e.g., an Ethernet or corporate network), Wide Area Networks (WANs) (e.g., the Internet), wireless data networks, some other electronic data network, or some combination thereof. In various embodiments, network interface 1140 may support communication via wired or wireless general data networks, such as any suitable type of Ethernet network, for example; via telecommunications/telephony networks such as analog voice networks or digital fiber communications networks; via storage area networks such as Fibre Channel SANs, or via any other suitable type of network and/or protocol.

Input/output devices 1150 may, in some embodiments, include one or more display terminals, keyboards, keypads, touchpads, scanning devices, voice or optical recognition devices, or any other devices suitable for entering or accessing data by one or more computer systems 1100. Multiple input/output devices 1150 may be present in computer system 1100 or may be distributed on various nodes of computer system 1100. In some embodiments, similar input/output devices may be separate from computer system 1100 and may interact with one or more nodes of computer system 1100 through a wired or wireless connection, such as over network interface 1140.

As shown in FIG. 11, memory 1120 may include program instructions 1122, which may be processor-executable to implement any element or action described above. In one embodiment, the program instructions may implement the methods described above. In other embodiments, different elements and data may be included. Note that data may include any data or information described above.

Those skilled in the art will appreciate that computer system 1100 is merely illustrative and is not intended to limit the scope of embodiments. In particular, the computer system and devices may include any combination of hardware or software that can perform the indicated functions, including computers, network devices, Internet appliances, PDAs, wireless phones, pagers, etc. Computer system 1100 may also be connected to other devices that are not illustrated, or instead may operate as a stand-alone system. In addition, the functionality provided by the illustrated components may in some embodiments be combined in fewer components or distributed in additional components. Similarly, in some embodiments, the functionality of some of the illustrated components may not be provided and/or other additional functionality may be available.

Those skilled in the art will also appreciate that, while various items are illustrated as being stored in memory or on storage while being used, these items or portions of them may be transferred between memory and other storage devices for purposes of memory management and data integrity. Alternatively, in other embodiments some or all of the software components may execute in memory on another device and communicate with the illustrated computer system via inter-computer communication. Some or all of the system components or data structures may also be stored (e.g., as instructions or structured data) on a computer-accessible medium or a portable article to be read by an appropriate drive, various examples of which are described above. In some embodiments, instructions stored on a computer-accessible medium separate from computer system 1100 may be transmitted to computer system 1100 via transmission media or signals such as electrical, electromagnetic, or digital signals, conveyed via a communication medium such as a network and/or a wireless link. Various embodiments may further include receiving, sending or storing instructions and/or data implemented in accordance with the foregoing description upon a computer-accessible medium. Generally speaking, a computer-accessible medium may include a non-transitory, computer-readable storage medium or memory medium such as magnetic or optical media, e.g., disk or DVD/CD-ROM, volatile or non-volatile media such as RAM (e.g. SDRAM, DDR, RDRAM, SRAM, etc.), ROM, etc. In some embodiments, a computer-accessible medium may include transmission media or signals such as electrical, electromagnetic, or digital signals, conveyed via a communication medium such as network and/or a wireless link.

The methods described herein may be implemented in software, hardware, or a combination thereof, in different embodiments. In addition, the order of the blocks of the methods may be changed, and various elements may be added, reordered, combined, omitted, modified, etc. Various modifications and changes may be made as would be obvious to a person skilled in the art having the benefit of this disclosure. The various embodiments described herein are meant to be illustrative and not limiting. Many variations, modifications, additions, and improvements are possible. Accordingly, plural instances may be provided for components described herein as a single instance. Boundaries between various components, operations and data

stores are somewhat arbitrary, and particular operations are illustrated in the context of specific illustrative configurations. Other allocations of functionality are envisioned and may fall within the scope of claims that follow. Finally, structures and functionality presented as discrete components in the example configurations may be implemented as a combined structure or component. These and other variations, modifications, additions, and improvements may fall within the scope of embodiments as defined in the claims that follow.

What is claimed is:

1. A method for measuring a position, comprising:
 - delivering an impulse alternating electrical signal to an autofocus coil; and
 - calculating a position measurement of the autofocus coil by measuring one or more properties of an inductance-capacitance circuit comprising the autofocus coil and a first capacitor plate in response to the impulse.
2. The method of claim 1, further comprising adjusting a position of the autofocus coil by altering a voltage input to the autofocus coil, wherein the adjusting is based at least in part on the position measurement; and repeating the delivering and calculating.
3. The method of claim 1, further comprising, repeating the delivering and the calculating, wherein a capacitance between the first electrically conductive capacitor plate and the autofocus coil varies as a function of the position of the autofocus coil relative to the first electrically conductive capacitor plate.
4. The method of claim 1, wherein:
 - the calculating the position measurement of the autofocus coil by measuring a resonant frequency of a resonant inductance-capacitance circuit comprising the autofocus coil and a first capacitor plate in response to the impulse further comprises
 - measuring a capacitance between the first electrically conductive capacitor plate and the autofocus coil that varies as a function of the position of the autofocus coil relative to the first electrically conductive capacitor plate.
5. The method of claim 1, further comprising adjusting a position of the autofocus coil by altering a voltage input to the autofocus coil, wherein the adjusting is based at least in part on the position measurement, and the delivering the impulse alternating electrical signal to the autofocus coil further comprises delivering the impulse alternating electrical signal to the autofocus coil at a frequency different from a signal used to adjust the autofocus coil.
6. The method of claim 1, wherein the delivering the impulse alternating electrical signal to the autofocus coil further comprises delivering the impulse alternating electrical signal to an autofocus coil of an autofocus actuator mechanism for moving a lens carriage, through a parallel electrical connection between the first capacitor plate and the autofocus coil.
7. The method of claim 1, wherein the delivering the impulse alternating electrical signal to the autofocus coil further comprises delivering the impulse alternating electrical signal to an autofocus coil of an autofocus actuator mechanism for moving a lens carriage, through a parallel electrical

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connection between the first capacitor plate and the autofocus coil via one or more suspension wires of the actuator mechanism.

8. A non-transitory computer-accessible storage medium storing program instructions that, when executed on one or more processors, cause the one or more processors to:

cause an impulse alternating electrical signal to be delivered to an autofocus coil; and

calculate a position measurement of the autofocus coil by measuring one or more properties of an inductance-capacitance circuit comprising the autofocus coil and a first capacitor plate in response to the impulse.

9. The non-transitory computer-accessible storage medium of claim 8, wherein the program instructions when executed cause the one or more processors to:

cause a position of the autofocus coil to be adjusted, based at least in part on the position measurement, by altering a voltage input to the autofocus coil;

repeat causing an impulse alternating electrical signal to be delivered to the autofocus coil; and

repeat calculating a position measurement of the autofocus coil.

10. The non-transitory computer-accessible storage medium of claim 8, wherein the program instructions when executed cause the one or more processors to:

repeat causing an impulse alternating electrical signal to be delivered to the autofocus coil; and

repeat calculating a position measurement of the autofocus coil;

wherein a capacitance between the first electrically conductive capacitor plate and the autofocus coil varies as a function of the position of the autofocus coil relative to the first electrically conductive capacitor plate.

11. The non-transitory computer-accessible storage medium of claim 8, wherein, to calculate the position measurement of the autofocus coil, the program instructions when executed cause the one or more processors to:

measure a capacitance between the first electrically conductive capacitor plate and the autofocus coil that varies as a function of the position of the autofocus coil relative to the first electrically conductive capacitor plate.

12. The non-transitory computer-accessible storage medium of claim 8, wherein the program instructions when executed cause the one or more processors to:

cause a position of the autofocus coil to be adjusted, based at least in part on the position measurement, by altering a voltage input to the autofocus coil;

wherein, to cause the impulse alternating electrical signal to be delivered to the autofocus coil, the program instructions when executed cause the one or more processors to:

cause the impulse alternating electrical signal to be delivered to the autofocus coil at a frequency different from a signal used to adjust the autofocus coil.

13. The non-transitory computer-accessible storage medium of claim 8, wherein, to cause the impulse alternating electrical signal to be delivered to the autofocus coil, the program instructions when executed cause the one or more processors to:

cause the impulse alternating electrical signal to be delivered to an autofocus coil of an autofocus actuator mechanism for moving a lens carriage, through a parallel electrical connection between the first capacitor plate and the autofocus coil via one or more suspension wires of the actuator mechanism.

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14. A control system, comprising:
one or more processors to:

cause an impulse alternating electrical signal to be delivered to an autofocus coil; and

calculate a position measurement of the autofocus coil by measuring one or more properties of an inductance-capacitance circuit comprising the autofocus coil and a first capacitor plate in response to the impulse.

15. The control system of claim 14, wherein the one or more processors are further to:

cause a position of the autofocus coil to be adjusted, based at least in part on the position measurement, by altering a voltage input to the autofocus coil;

repeat causing an impulse alternating electrical signal to be delivered to the autofocus coil; and

repeat calculating a position measurement of the autofocus coil.

16. The control system of claim 14, wherein the one or more processors are further to:

repeat causing an impulse alternating electrical signal to be delivered to the autofocus coil; and

repeat calculating a position measurement of the autofocus coil;

wherein a capacitance between the first electrically conductive capacitor plate and the autofocus coil varies as a function of the position of the autofocus coil relative to the first electrically conductive capacitor plate.

17. The control system of claim 14, wherein, to calculate the position measurement of the autofocus coil, the one or more processors:

measure a capacitance between the first electrically conductive capacitor plate and the autofocus coil that varies as a function of the position of the autofocus coil relative to the first electrically conductive capacitor plate.

18. The control system of claim 14, wherein the one or more processors are further to:

cause a position of the autofocus coil to be adjusted, based at least in part on the position measurement, by altering a voltage input to the autofocus coil;

wherein, to cause the impulse alternating electrical signal to be delivered to the autofocus coil, the one or more processors:

cause the impulse alternating electrical signal to be delivered to the autofocus coil at a frequency different from a signal used to adjust the autofocus coil.

19. The control system of claim 14, wherein, to cause the impulse alternating electrical signal to be delivered to the autofocus coil, the one or more processors:

cause the impulse alternating electrical signal to be delivered to an autofocus coil of an autofocus actuator mechanism for moving a lens carriage, through a parallel electrical connection between the first capacitor plate and the autofocus coil.

20. The control system of claim 14, wherein, to cause the impulse alternating electrical signal to be delivered to the autofocus coil, the one or more processors:

cause the impulse alternating electrical signal to be delivered to an autofocus coil of an autofocus actuator mechanism for moving a lens carriage, through a parallel electrical connection between the first capacitor plate and the autofocus coil via one or more suspension wires of the actuator mechanism.