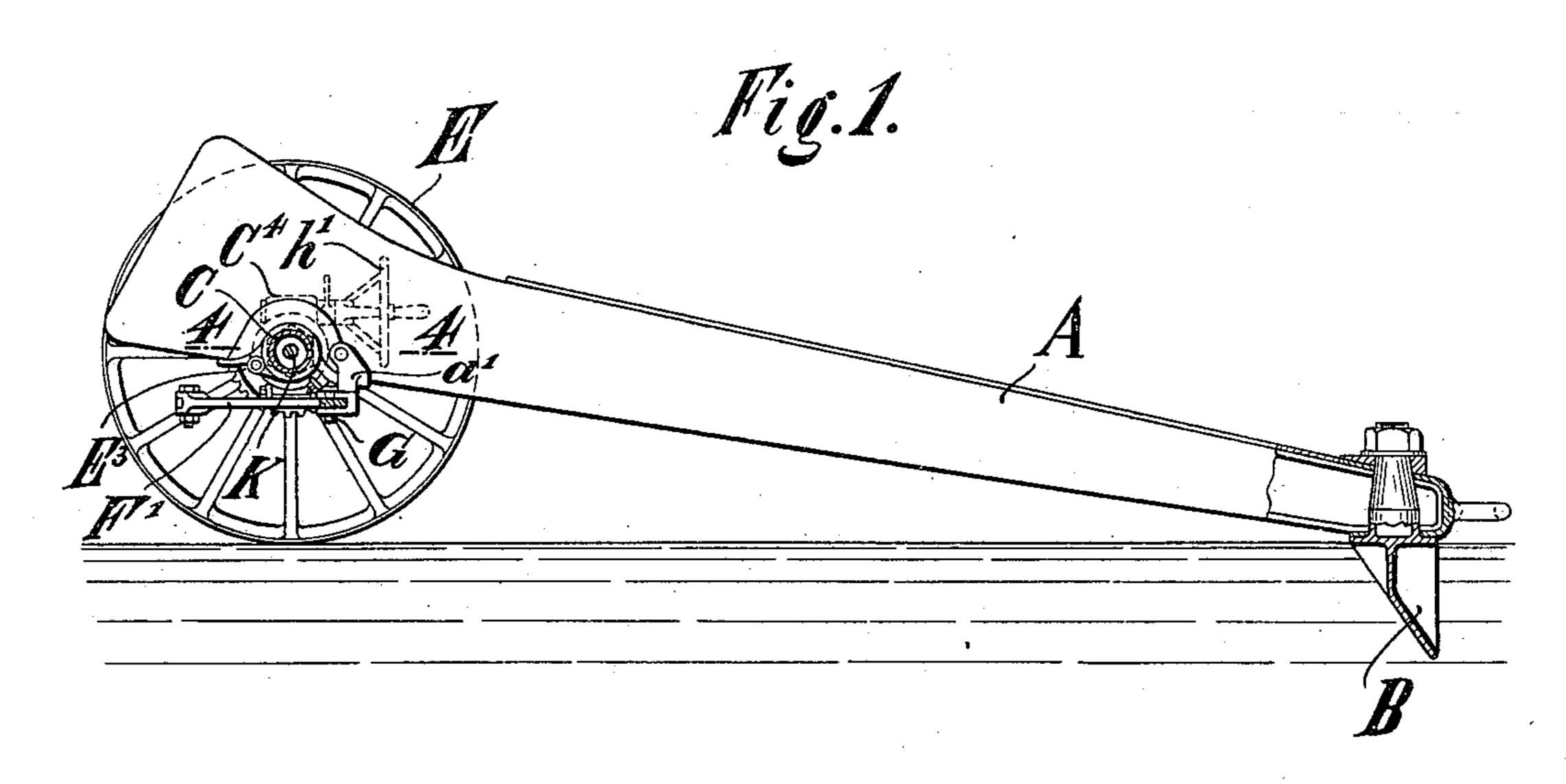
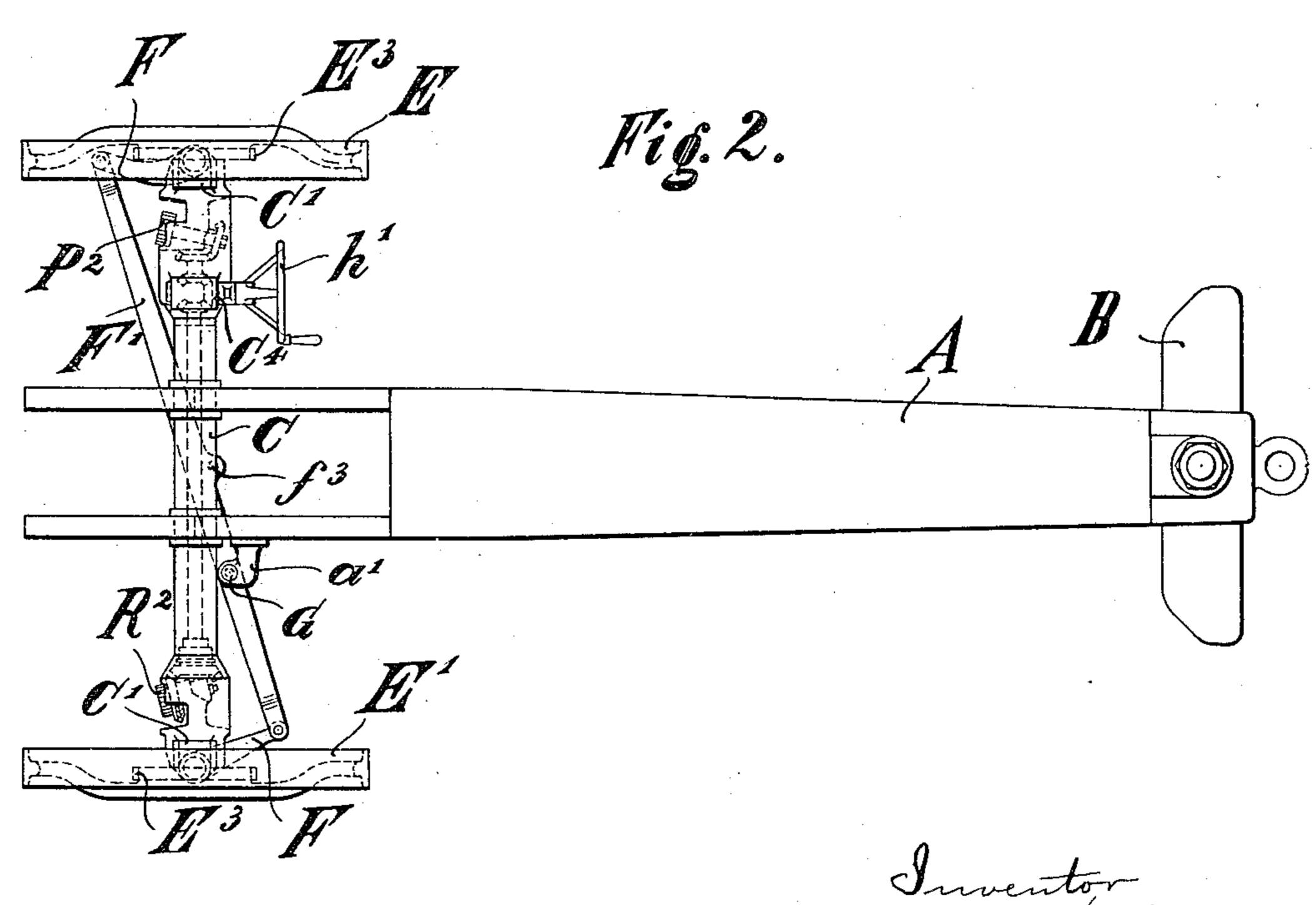
N. KOCH. GUN CARRIAGE. APPLICATION FILED JAN. 24, 1910.

985,179.

Patented Feb. 28, 1911.

2 SHEETS-SHEET 1.





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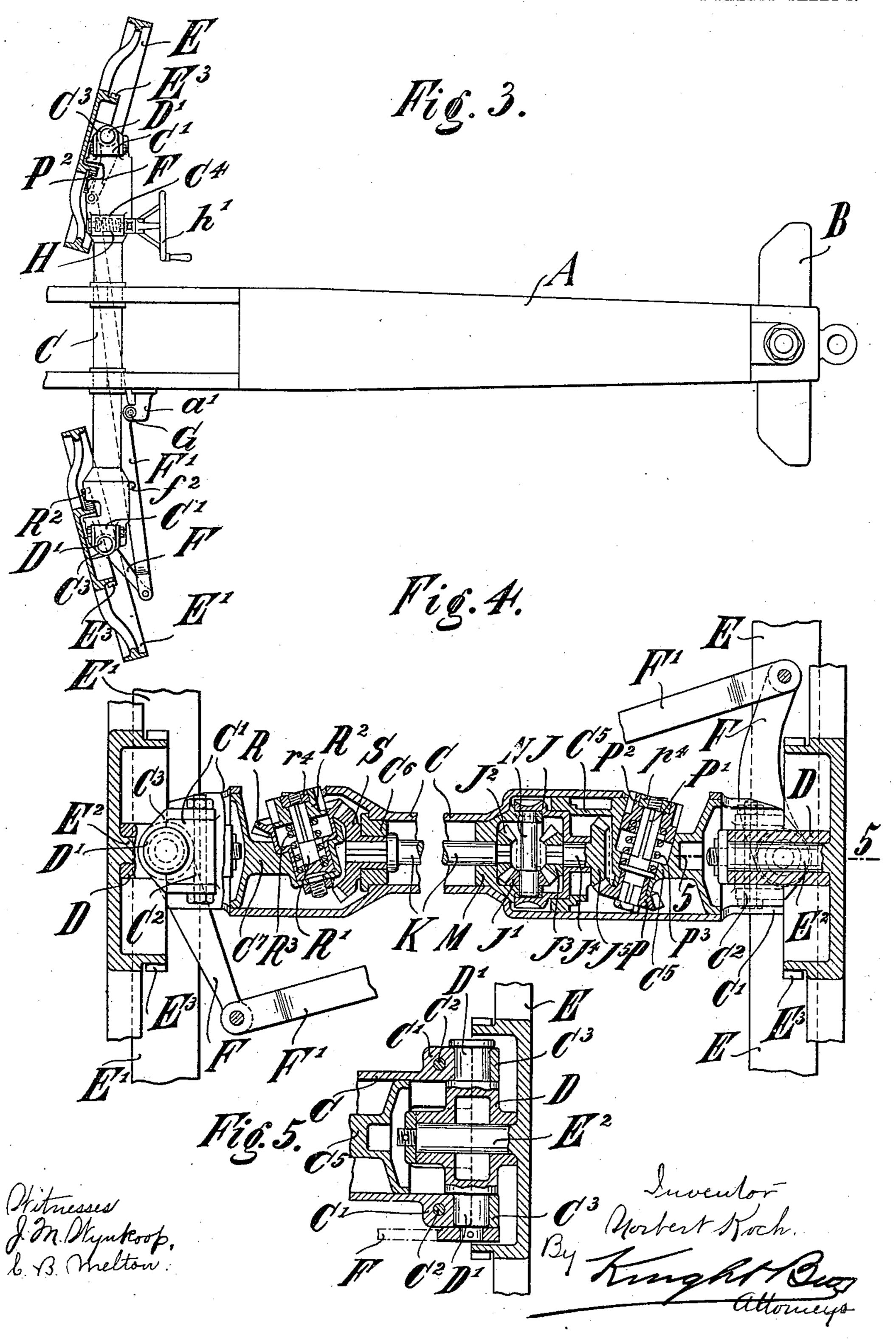
GUN CARRIAGE.

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UNITED STATES PATENT OFFICE.

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GUN-CARRIAGE.

985,179.

Specification of Letters Patent. Patented Feb. 28, 1911.

Application filed January 24, 1910. Serial No. 539,725.

To all whom it may concern:

Be it known that I, Norbert Koch, a subject of the Emperor of Germany, and a resident of Essen-on-the-Ruhr, Germany, have 5 invented certain new and useful Improvements in Gun-Carriages, of which the following is a specification.

The present invention relates to gun carriages and is an improvement on the gun 10 carriage forming the subject matter of my U. S. Letters Patent No. 912,135 of Febru-

ary 9, 1909.

The accompanying drawings show an embodiment of the invention, by way of ex-

15 ample.

Figure 1 is a side view, partly in section, of a gun carriage, one wheel being broken away, and the other wheel being in the position for travel; Fig. 2 is a top view of Fig. 20 1; Fig. 3 is a view corresponding to Fig. 2, but partly in section and showing the wheels in the training position; Fig. 4 is a section on line 4-4. Fig. 1, on an enlarged scale and looking from above, and Fig. 5 is a sec-25 tion on line 5—5, Fig. 4, on an enlarged scale.

A indicates the carriage-body which has its trail provided with a spade B, which can rotate about a vertical axis. The hol-30 low wheel-axle C is secured in the other end of the carriage-body A. The ends of the axle terminate in bifurcated pieces C1 between which the journals D are mounted to swing in a horizontal plane through the 35 medium of trunnions D¹ (see especially Fig. | 5). The trunnions D¹ of the journals are retained in position by means of covers C³ which are inserted over the pieces C1 and secured in position by means of screws C2. 40 The carriage-wheels E and E¹ are journaled | in the journals D, by means of trunnions E2. To the lower trunnion D¹ of each journal D is rigidly secured an arm F. The arms F are connected with each other by means of 45 a cross-bar F¹ which is jointed to the arms. The cross-bar F¹ is provided with two bores f² and f³ (Figs. 2 and 3). A guide bracket a for the cross-bar F is provided on that wall of the carriage-body A which is toward 50 the wheel E^1 . The bracket a^1 is provided with bores for a key-bolt G, which bores correspond to the bores f^2 f^3 . When the pose of permitting the sprocket-wheel to bores in the bracket a register with the bore | vield in case a tooth on the toothed crown f² in the cross-bar F¹, the carriage-wheels E | E³ should hit a tooth on the sprocket-wheel

| and E¹ are in the traveling position (Figs. 55 1 and 2) and when the bores in the bracket a^{1} register with the bore f^{3} the wheels are in the training position (Fig. 3). The wheels can be secured in both of these positions by means of the key-bolt G.

The hollow axle C is enlarged at its ends. On that end of the axle C which is toward the wheel E is mounted a housing C4 (Figs. 1 to 3) in which is journaled a worm H (Fig. 3). This worm, which can be turned 65 by means of a hand-wheel h^1 , engages with a hollow worm-wheel J (Fig. 4) which is journaled in a member C⁵ secured in the axle. A sleeve M, which is rotatably mounted in the axle and which can be coupled to 70 the worm-wheel J by means of a bolt N, engages in the hollow space of the worm-wheel J. In the hollow spaces of the worm-wheel J and the sleeve M is arranged a bevel-wheel gear (differential gear) which serves for 75 transmitting rotation of the worm-wheel J and the sleeve M to the two carriage-wheels E and E¹ when the latter are in the training position. The bevel-wheel gear consists of three bevel-wheels J¹ J² and J³. The 80 bevel-wheel J^1 is rotatably mounted on the bolt N and meshes with both of the bevelwheels J² and J³. A shaft J⁴ on which the bevel-wheel J³ is non-rotatably secured is integral with a bevel-wheel J⁵ which 85 meshes with a bevel-wheel P journaled in the member C⁵. The bevel-wheel P is nonrotatably mounted on one end of a shaft P1 which carries on its other end a sprocket wheel P² which is slidably but non-rotatably 90 mounted on the shaft P¹. The sprocketwheel projects through an opening provided in the axle C and is adapted to coöperate with a toothed crown E3 (Figs. 3 and 4) on the carriage-wheel E when the latter is in 95 the training position. For that purpose, the shaft P1 of the wheels P and P2 is inclined relative to the longitudinal axis of the axle C. A helical spring P³ tends to hold the sprocket-wheel P2 in the position 100 shown in Fig. 4 (the working position), in which position the sprocket-wheel abuts against a nut p^4 screwed on the threaded end of the shaft P1. The slidable arrangement of the sprocket-wheel P2 is for the pur- 105

P² when the carriage-wheel E is swung into

the training position.

The transmission of movement from the worm-wheel J to the carriage-wheel E¹ is ${f 5}$ effected by means of the bevel-wheels ${f J}^{\scriptscriptstyle 1},\,{f J}^{\scriptscriptstyle 2}$ and a shaft K on one end of which the bevel-wheel J² is non-rotatably mounted. The other end of the shaft K, which is journaled in a bushing C⁶ in the axle, carries a 10 bevel-wheel S, which is non-rotatably connected to the shaft K and which meshes with a hollow bevel-wheel R. The bevelwheel R, which corresponds to the bevelwheel P, is journaled in a member C⁷ secured 15 in the axle. A sprocket-wheel R² is slidably; but non-rotatably connected with a shaft R1 which is integral with the bevelwheel R. The sprocket-wheel R² which corresponds to the sprocket-wheel P2 is under 20 the action of a spring R³ which tends to hold it in the position shown in the drawings, in which the wheel \mathbb{R}^2 abuts against a nut r^4 secured on the threaded end of the shaft R¹. The sprocket-wheel R² serves for coöperat-25 ing with a toothed crown E³ on the carriage-wheel E¹ when the latter is in the training position.

During the travel of the gun, the carriage-wheels E and E¹ assume the position 30 shown in Figs. 1 and 2, and they are held in this position by means of the arms F rigidly connected with the journals D, the cross-bar F¹ and the key-bolt G inserted in the bore f^2 in the cross-bar and in the bores

35 in the guide-bracket a^1 .

After the gun has reached firing position and has been unlimbered, the key-bolt G is removed to break the connection between the guide bracket a^1 and the cross-bar F^1 . 10 The operator then takes hold of one of the carriage-wheels E and E¹ and swings it about the axis of the trunnion D¹ until it reaches the training position (Fig. 3). The arm F and the cross-bar F¹ cause the other 45 carriage - wheel to partake of this movement. Thereupon the carriage-wheels are secured in position by the insertion of the key-bolt G in the bore f^3 of the cross-bar and the bores of the guide-bracket a^1 . In 50 this position (the training position), the axes of rotation of the carriage-wheels intersect the axis of rotation of the spade B

If the teeth on the sprocket-wheels P² and 55 R² do not register with the gaps between the teeth of the toothed crowns E³ on the carriage-wheels when the wheels E and E¹ are swung into the training position, the sprocket-wheels P2 and R2 will be displaced 60 on their shafts P¹ and R¹ against the pres-

sure of the springs P³, R³.

(Fig. 3).

The engagement of the sprocket-wheels P² and R² with the toothed crowns E³ might be effected by turning the carriage-wheels. 65 However, this would require great expendi-

ture of force. The engagement is, therefore, more suitably effected by moving the gear in the wheel-axle by means of the hand-wheel h^1 and the worm H. The turning of the worm H is partaken of by the 70 worm-wheel J, which carries along the bolt N and the bevel-wheel J¹ located on the bolt N. The bevel-wheel J¹ thereby carries out a movement about the common axis of the shafts K and J⁴ and imparts rotation 75 to the bevel-wheels J^2 and J^3 which in turn transmit their movement through the parts K S R R¹ and J⁴ J⁵ P P¹ of the gear to the sprocket-wheels P² and R² so that the latter reach an angular position in which the 80 springs P³ and R³ cause them to snap into the toothed crowns E³ of the carriagewheels. If one of the sprocket-wheels ${
m P}^2$ R², for instance P², enters into engagement with its toothed crown E³ before the other 85 sprocket-wheel R² enters into engagement with its toothed crown E3, the gear between the bevel-wheel J¹ and the sprocket-wheel P² remains at rest during the further turning of the worm H, but the bevel-wheel J¹ 90 which is rotatable on the bolt N, rolls on the bevel-wheel J³ and carries the bevel-wheel J² along until the sprocket-wheel R² has also entered into engagement with its toothed crown E³. When this engagement ⁹⁵ has been effected, the required lateral training can be imparted to the carriage by turning the worm H. It need not be explained how the gear acts in that case.

Having thus described the invention, 100 what is claimed and desired to be secured

by Letters Patent is:—

1. A gun-carriage having a spade mounted to rotate about a vertical axis, carriagewheels mounted to swing about vertical 101 axes to a training position, and driving mechanism adapted to engage both of said wheels when they are in the training position for imparting rotation to the wheels; said mechanism being provided with a dif- 11 ferential gear.

2. A gun-carriage having a spade mounted to rotate about a vertical axis, carriagewheels mounted to swing about vertical axes to a training position, and driving 11 mechanism adapted to engage both of said wheels when they are in the training position for imparting rotation to the wheels; said mechanism being provided with a differential gear; said mechanism having its 12 wheel-engaging parts slidable in such a manner as to permit them to yield when, on the carriage-wheels being swung into the training position, the teeth of the wheelengaging parts are incapable of entering 12 into engagement with the carriage wheels.

3. A gun-carriage having a spade mounted to rotate about a vertical axis, carriagewheels mounted to swing about vertical axes to a training position, and driving 13

mechanism adapted to engage both of said | the journals of said wheels, and a rod con- 20 wheels when they are in the training position for imparting rotation to the wheels; said mechanism being provided with a dif-5 ferential gear; said mechanism having its wheel-engaging parts slidable in such a manner as to permit them to yield when, on the carriage-wheels being swung into the training position, the teeth of the wheel-10 engaging parts are incapable of entering into engagement with the carriage wheels, and springs for subsequently effecting the engagement between the wheel-engaging parts and the carriage wheels.

15 4. A gun-carriage having a spade mounted to rotate about a vertical axis, carriagewheels having journals and adapted to be swung about vertical axes from a traveling position to a training position, arms on |

necting said arms.

5. A gun-carriage having a spade mounted to rotate about a vertical axis, carriagewheels having journals and adapted to be swung about vertical axes from a traveling 25 position to a training position, arms on the journals of said wheels, and a rod connecting said arms, and means on the carriage for securing said rod in the traveling position and in the training position of the 30 wheels.

The foregoing specification signed at Barmen, Germany, this 4th day of January, 1910.

NORBERT KOCH. [L. s.] In presence of— Otto König, WILLY KLEIN.

Copies of this patent may be obtained for five cents each, by addressing the "Commissioner of Patents, Washington, D. C."

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