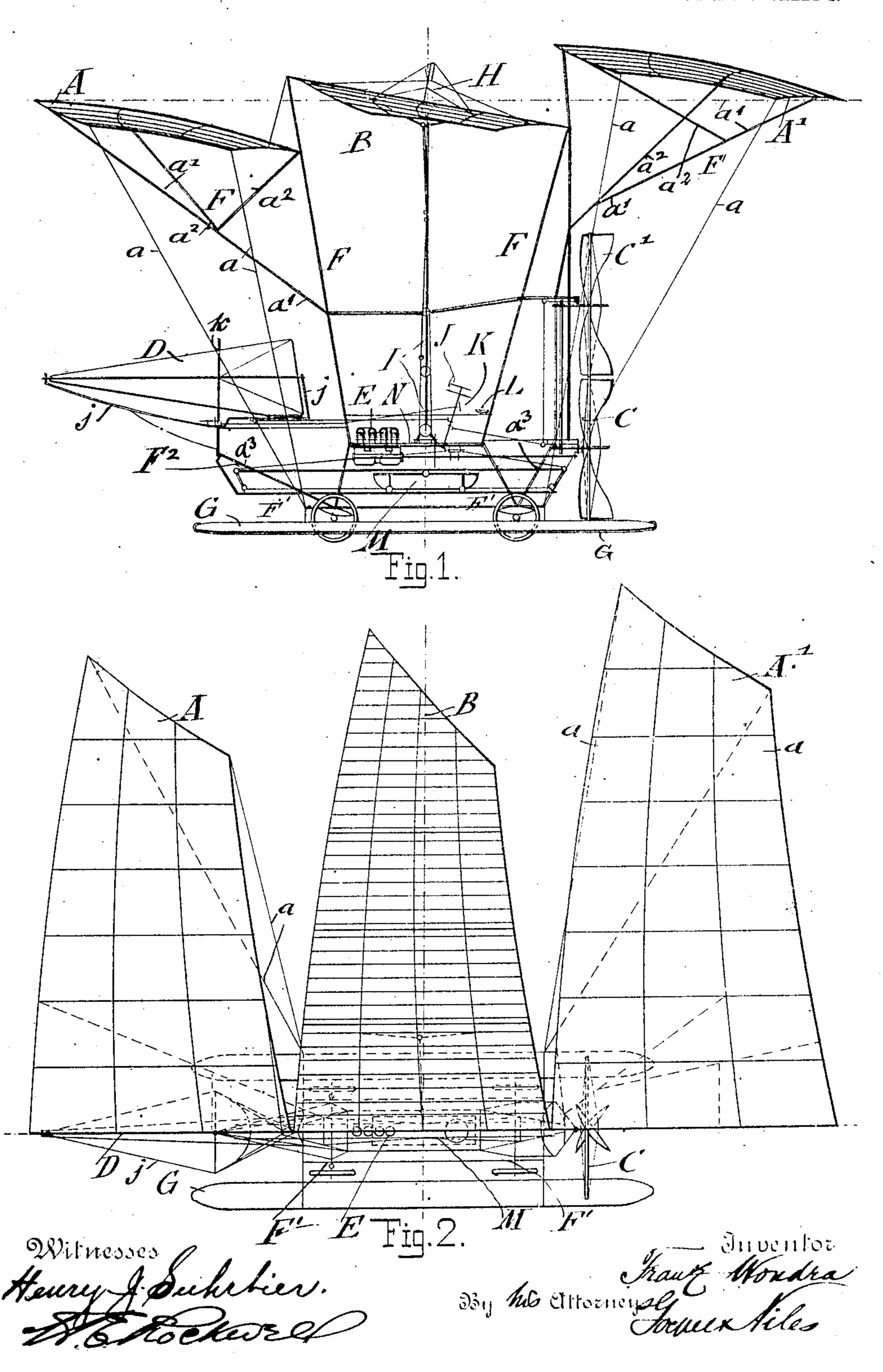
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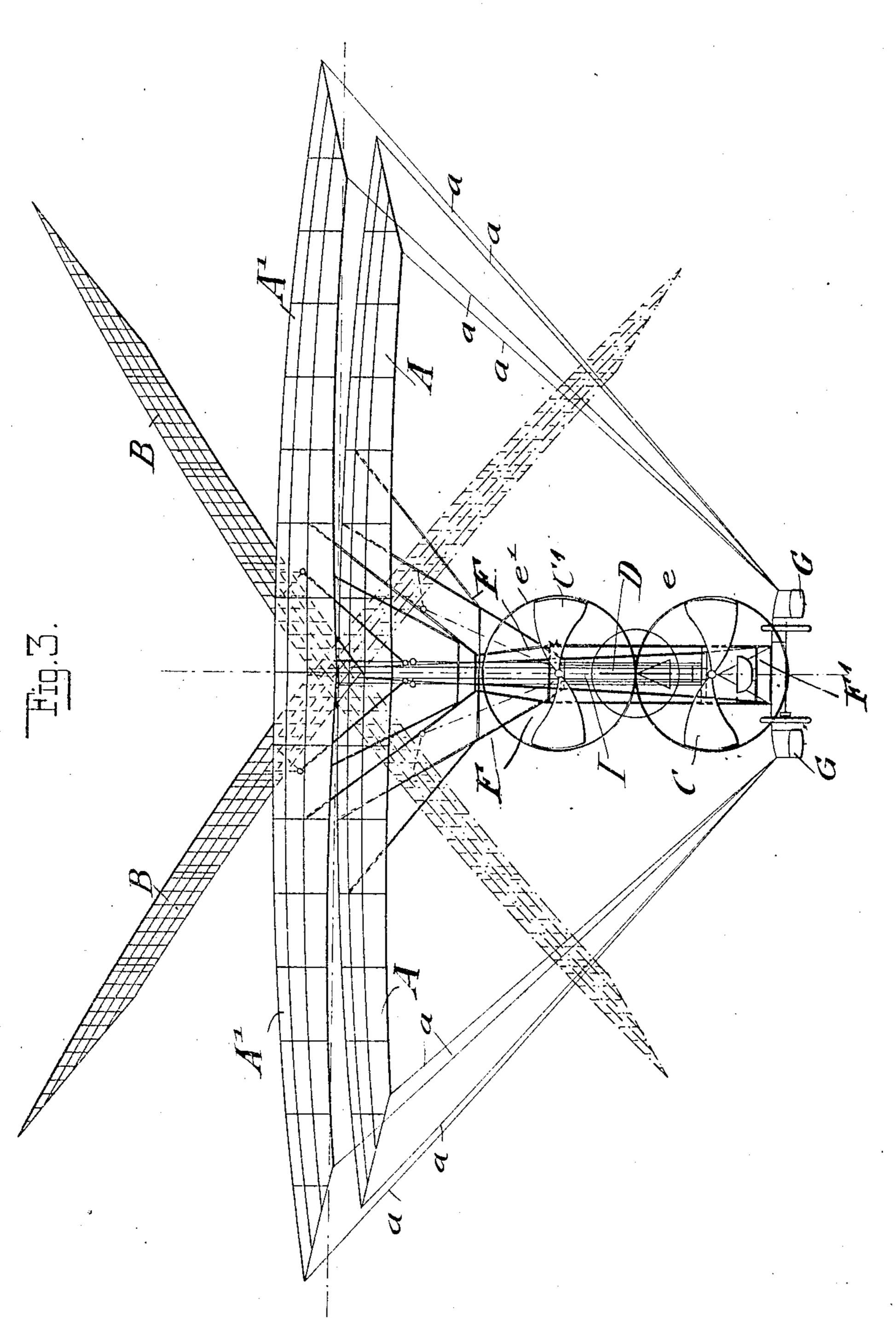


No. 876,125.

PATENTED JAN. 7, 1908

# F. WONDRA. FLYING MACHINE. APPLICATION FILED OCT. 11, 1904.

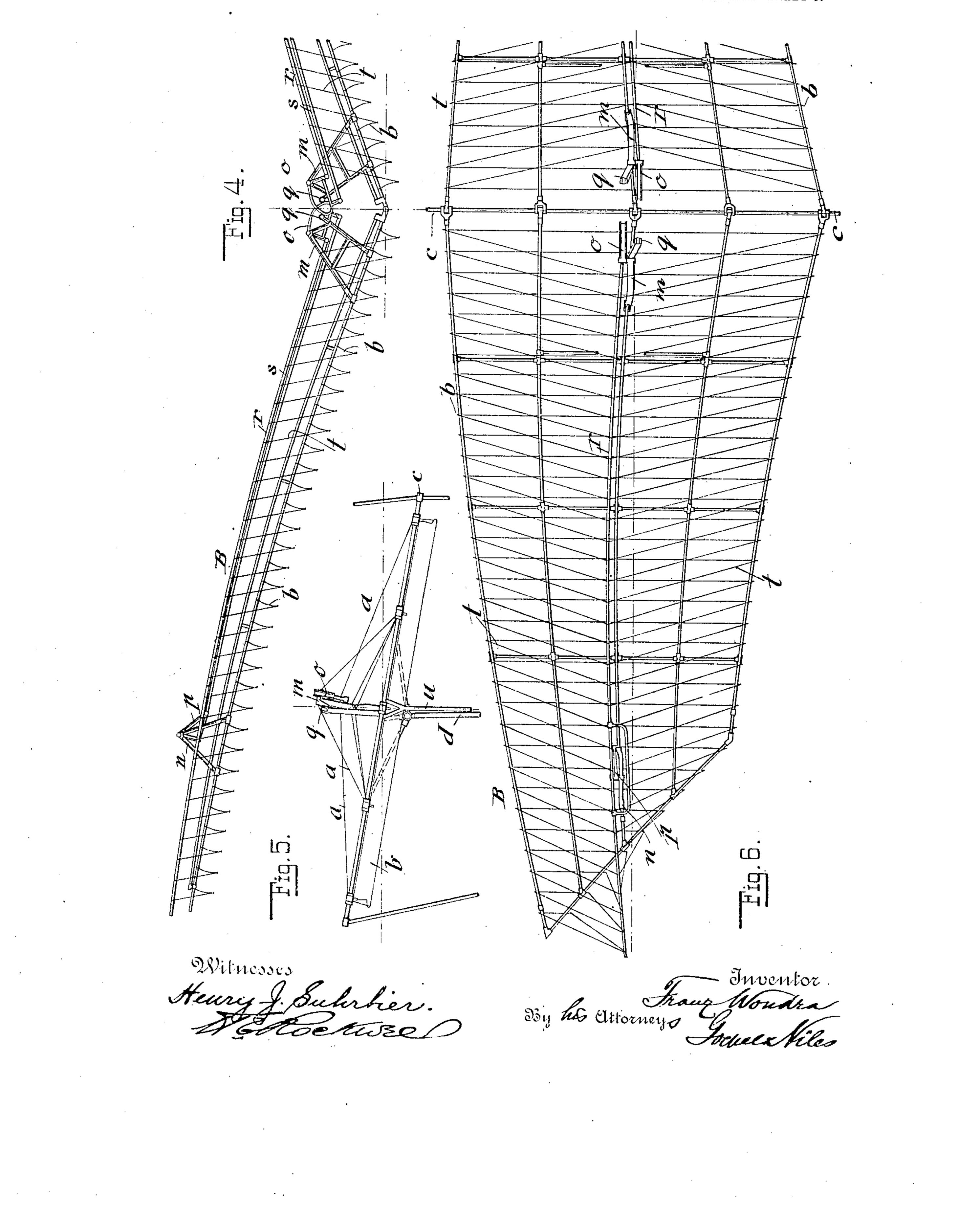
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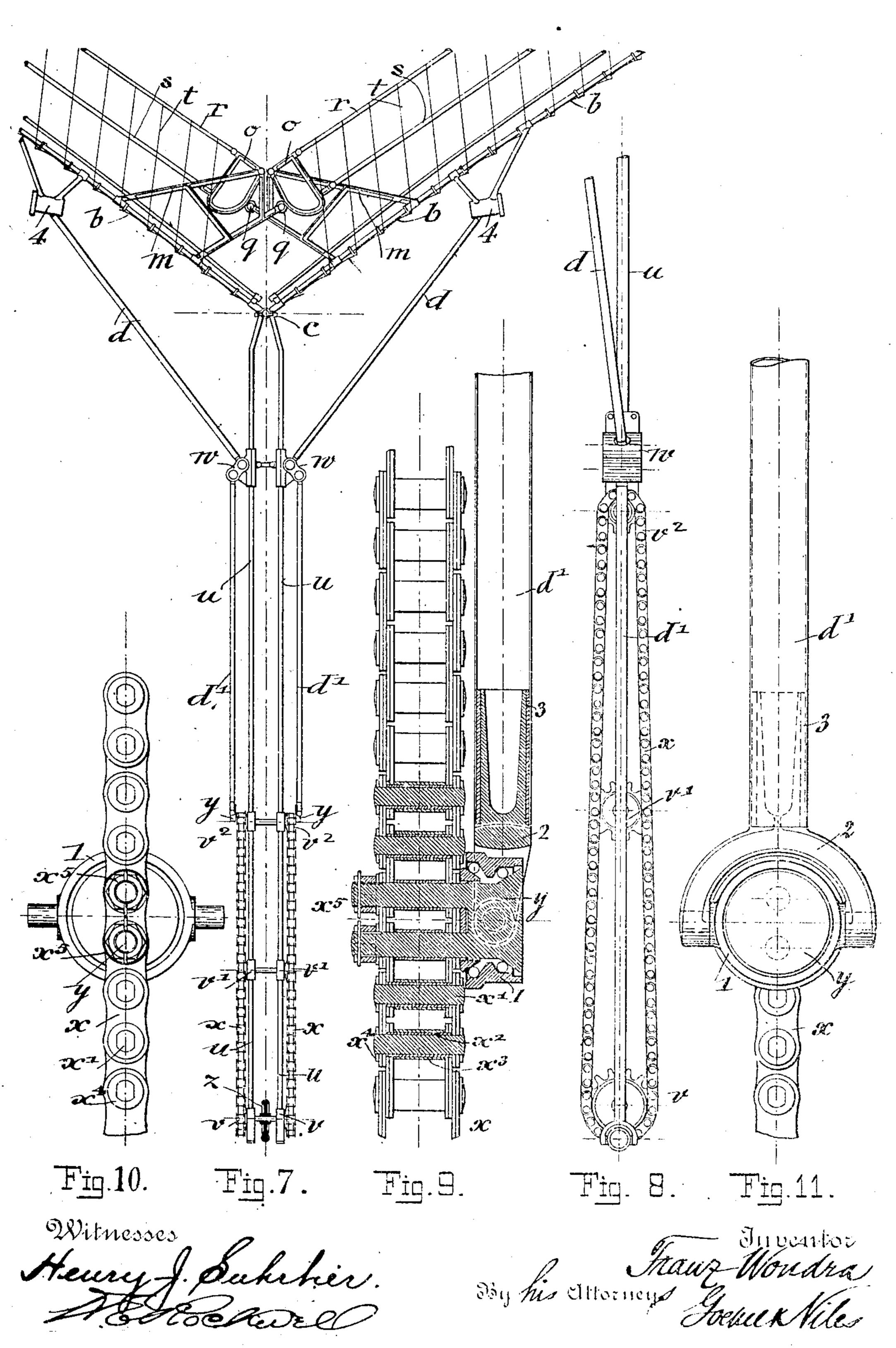
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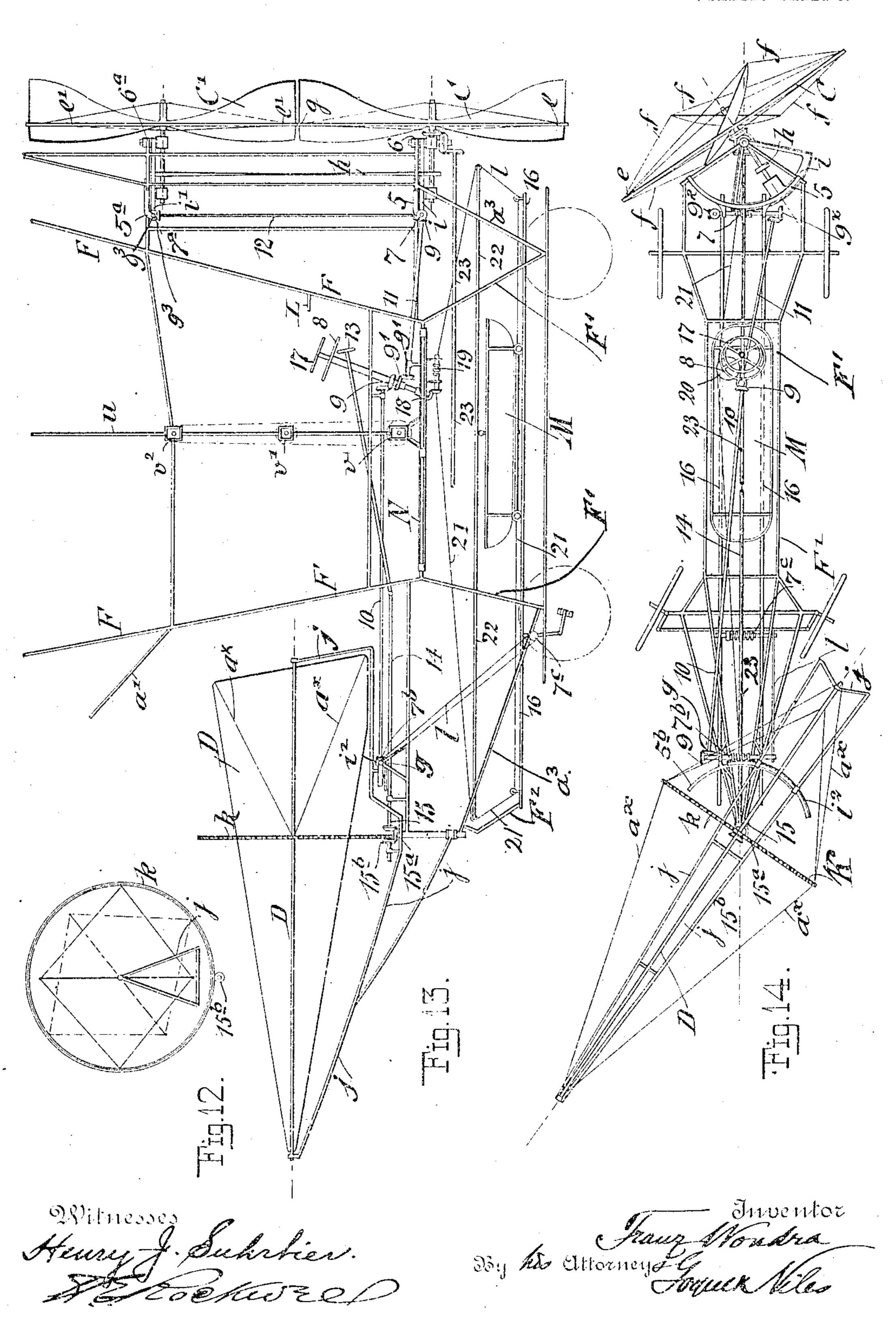
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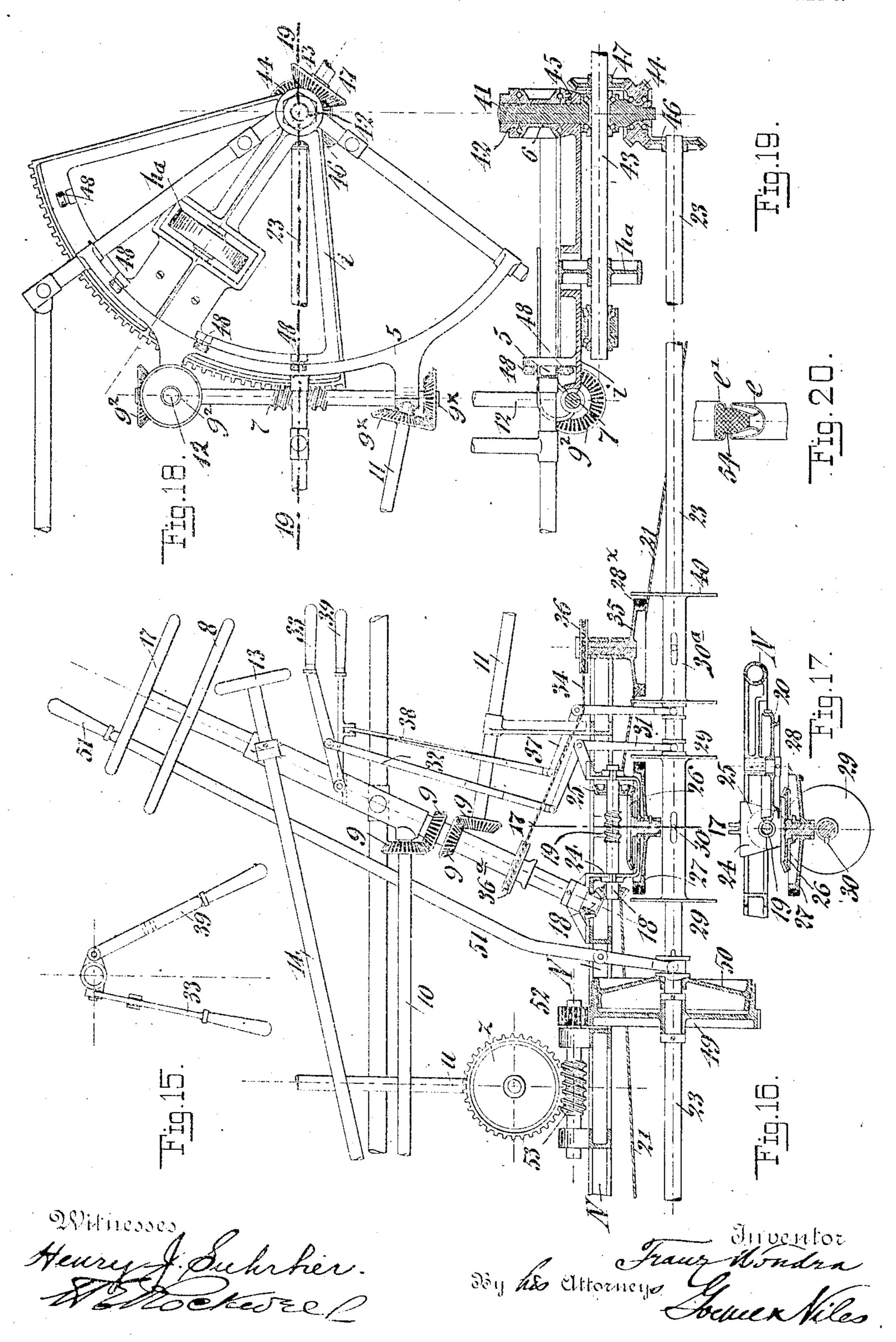
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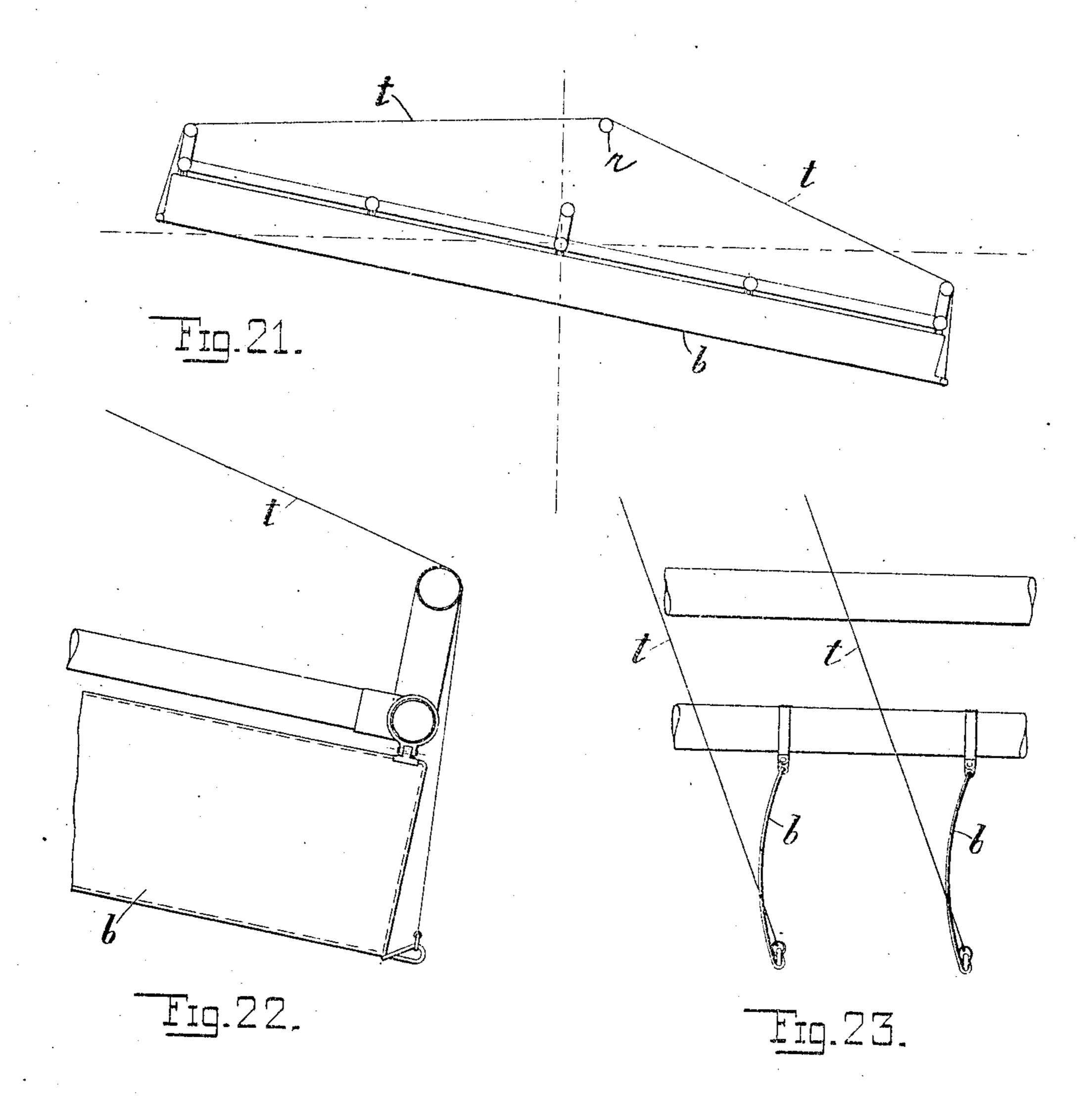


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### VITED STATES PATENT OFFICE.

FRANZ WONDRA, OF SCHENECTADY, NEW YORK

#### FLYING-MACHINE.

No. 876,125.

Specification of Letters Patent.

Patented Jan. 7, 1908.

Application filed October 11, 1904. Serial No. 227,979.

To all whom it may concern:

Be it known that I, Franz Wondra, a citizen of the Empire of Austria-Hungary, residing in Schenectady, in the county of 5 Schenectady and State of New York, have invented certain new and useful Improvements in Flying-Machines, of which the fol-

lowing is a specification.

This invention relates to an improved fly-10 ing machine in which the natural current that is produced by the gradual falling of the machine is employed by suitable aeroplanes for the forward motion in connection with reciprocating wings and rotary propellers 15 driven by a motor, the machine being equipped with suitable wheels and floats at its lower part for being propelled on land and water; and the invention consists in its general outlines of a flying-machine, which is 20 provided with stationary aeroplanes, of which the front-plane is located at a somewhat less height than the rear-plane, both being curved laterally and arranged at a slight-angle of inclination to the horizontal 25 plane, a pair of oscillatory wings located between said aeroplanes, mechanism for imparting an oscillatory motion to said the flying machine, propellers located at the 30 rear of the flying machine rotated by a suitable transmitting mechanism from said motor, a steering-rudder located at the front part of the machine, means for turning the rudder to either side in connection with the 35 propellers, and also at a suitable inclination towards the horizontal plane, a sliding gondola below the platform, guideways for said gondola, and means for guiding the basket forward or backward in said ways in order 40 to shift the center of gravity of the machine. according as an ascending or descending motion is to be imparted to the same.

The invention consists next of the construction of the oscillating wings with a 45 number of hinged panels, and improved mechanism for feathering said wings.

The invention consists further in certain details of construction of the steering-rudder, the propellers, the starting and stopping 50 mechanisms, and other combinations of parts which will be fully described hereinafter and finally pointed out in the claims.

In the accompanying drawings, Figure 1 represents a side-elevation of my improved 55 flying machine, showing the general arrangement of the parts of the same, Fig. 2 is a plan-

view of one hat, of the flying machine, showing one half of the aeroplanes and one of the wings, Fig. 3 is a rear-elevation of the flying machine, showing the propellers, aeroplanes 60 and the wings, the dotted lines indicating the lowermost position of the wings, Figs. 4, 5 and 6 are respectively a front-view, a transverse section, and a plan-view of the mechanism for opening or closing the hinged pan- 85 els of the oscillating wings, Fig. 7 is an enlarged detail vertical transverse section; showing the mechanism for actuating the oscillating wings, Fig. 8 is a detail side-view of the sprocket-wheel and chain transmission 70 for actuating said wings, Figs. 9, 10 and 11 are details of the sprocket-wheel and chaintransmission of the oscillating wings, Fig. 12 is a rear-elevation of the front steering-rudder, Fig. 13 is a side-elevation of the lower 75 part of the flying machine, drawn on a larger scale than Fig. 1, so as to illustrate the starting and steering mechanisms, Fig. 14 is a plan-view of Fig. 13, showing the rudder and propellers turned sidewise for steering in a 20 horizontal plane, Fig. 15 is a detail-planview of the auxiliary starting levers, Fig. 16 is a sectional side-elevation, drawn on a wings, a suitable motor on the platform of larger scale, of the motion-transmitting mechanisms, Fig. 17 is a vertical transverse \$5 section on line 17-17, Fig. 16, Fig. 18 is a plan-view showing the means for turning the supporting frame of the propellers for steering purposes, Fig. 19 is a vertical section on line 19-19, Fig. 18, Fig. 20 is a detail-section 90 showing the connection between the rims of the propellers for steadying the same during their rotatory motion and Figs. 21 to 23 are detail views of the wing-panels.

Similar letters of reference indicate corre- 95 sponding parts throughout the several views.

The flying machine is constructed in its general outlines of a supporting-frame F made of light but strong steel-tubing, a platform N supported at the lower part of the 100 frame, a motor E on said platform, and a seat L also on said platform for the person that operates the starting and steering mechanisms. Below the platform N is arranged a wheeled vehicle-frame F<sup>1</sup>. The platform N 105 and the frame F<sup>1</sup> are connected by suitable braces made of steel-tubing. Between the platform N and the vehicle-frame are located guide-ways for the sliding gondola M, in which the second person is seated. At the 110 upper front-part of the supporting-frame F is located a stationary front aeroplane A,

and at the upper rear-part of the frame F a stationary rear aeroplane A1, and intermediately between the same the oscillating wings B, B. The frames of the aeroplanes 5 A, A<sup>1</sup> are connected by steel-strings a with the main- and vehicle-frames and by inclined braces  $a^1$   $a^2$  with the main-frame F, so that the required degree of stiffness is imparted to the aeroplanes. At the front-end 10 of the supporting main-frame F is arranged a vertical steering-rudder D, which is capable of rotary motion on its vertical and horizontal axes, while two propellers C, C1 are arranged at the rear-end of the supporting-15 frame, one being arranged vertically above the other.

H indicates the mechanism for opening and closing the panels of the oscillating wings, I the mechanism for imparting oscillating motion to the wings, I the mechanism for steering in a horizontal plane, K the mechanism for steering in vertical direction, and G, G are floats provided with runners at their undersides, which floats are supported at both sides below the vehicle-frame and serve for guiding and supporting the vehicle on the water, while the wheels of the vehicle-frame serve for supporting the same on land.

The supporting main frame.—The support-

30 ing or main-frame F is constructed of seamless steel-tubing and comprises a middle portion having inclined side and upright center tubes and inclined forwardly and backwardly extending tubes a<sup>2</sup> supported on the 35 side-tubes. The lower horizontal vehicleframe F<sup>1</sup> is supported below the platform N and provided with a forwardly extending tapering frame F2 in which the steeringrudder D is supported. The lower frame F<sup>1</sup> 40 is wider at the lower part than at the upper part and provided with longitudinal guideways 16 for the shifting gondola M. The lower frame F1 is stiffened by inclined tubular braces a<sup>3</sup> which are connected with the 45 steering-rudder frame F<sup>2</sup> at the front of the machine and with the upright frame in which

the shafts of the propellers C, C1 are supported. The aeroplanes.—The aeroplanes A, A¹ are constructed of a light frame of steel-tubing 50 and a covering of waterproof silk, linen or other suitable material. They extend to either side of the machine and are slightly curved both in lateral and longitudinal direction, so as to be convex at their upper sur-55 face, being stationarily supported on the upper part of the supporting main-frame of the machine. The aeroplanes are arranged in the nature of the wing of a bird, at a downward and rearward inclination of 10° to the 60 horizontal plane, the front-end of the front aeroplane being located in the same horizontal plane with the rear-end of the rear aeroplane, so that the front aeroplane is located somewhat below the rear aeroplane, 65 as shown clearly in Fig. 1.

The oscillating wings.—The wings B are made of frames formed of steel-tubes and hinged at their inner ends to a transverse pivot-rod c. To the frame of the wings are hinged transverse slats or panels b, while on 70 the upper side of the wing-frame is arranged the mechanism H for closing and opening the panels b. The wings are made curved in imitation of the wings of a flying bird and are oscillated so as to imitate the motion of such 75 wings. During the upward motion of the wings B, the panels b are open, so as to permit the wings to pass freely through the air, the panels being closed when the wings arrive in their uppermost position by the mechan- 80 ism H, so that the wings are then swung with fully-closed surfaces in downward direction. The motion of the wings can be interrupted and the wings locked in position at any moment by interrupting the motion of the 85 actuating mechanism I; the wings being then used as auxiliary aeroplanes for floating in the air. The wings B are connected by links d and connecting rods  $d^1$  with the wingactuating mechanism I. The wings are 90 located between the aeroplanes in such a manner that their center is located in a line that connects the front-end of the front aeroplane A with the rear-end of the rear aeroplane A<sup>1</sup>, as shown in Fig. 1 The wings are 95 curved and are arranged at a forward and rearward inclination of 10° to the horizontal plane, so that by their inclined motion they impart an upward and forward motion to the machine.

The propellers.—The propellers C, C1 are provided with two curved blades, as shown clearly in Figs. 3 and 13, said blades being supported at their inner-ends on the drivingshafts of the propellers and at their outer 105 ends by circular steel - rims e,  $e^1$  and steelstrings f. The blades are spoon-shaped, being widest at their outer ends and tapering toward their inner ends. The propellershafts are supported in journal-bearings of 110 segments i,  $i^{\bar{1}}$  of the horizontal steering mechanism. Rotary motion is imparted from the motor to the shaft of the lower propeller and transmitted from the same to the shaft of the upper propeller. The lower 11: propeller is provided with a circumferentially-grooved circular steel-rim or frame e, which engages a tapering rubber-tire 54 applied to the circumference of the steel-rim e<sup>1</sup> of the upper propeller C<sup>1</sup> as shown in Fig. 120 20. The connection between the grooved circumference of the steel-ring e of the lower propeller Cand the tapering rubber-ring 54 on the upper propeller secures the steady rotation of both propellers in whatever position 125 they are placed. The propellers are located at the rear-end of the supporting frame of the machine below the rear aeroplane A1, and serve the twofold purpose of imparting forward motion to the machine and of steering 130

110

with the front-rudder D.

The rudder.—The rudder D is made of a tapering frame of steel tubing covered with 5 waterproof linen, silk or other material and supported at its front and rear-ends in a supporting-frame j. The frame j is connected with the horizontal steering mechanism, which will be described hereinafter. A ring-10 shaped gear-wheel k is connected with the frame of the rudder and permits it to be moved to any suitable angle of inclination to the horizontal plane. The rudder is located at the front-part of the machine vertically 25 below the front kite-plane A.

The vehicle.—The vehicle frame F' is provided with four wheels of equal size. The front steering-wheels are connected by an endless steering-chain l with the horizontal 20 steering mechanism, so that the machine can be steered when on land.

The floats.—The floats G are formed of a skeleton steel-frame covered with sheetaluminium, so as to form airtight hollow 25 bodies. They are supported at the lower end of the supporting frame of the machine in such a manner that the lower propeller C cannot form contact with the surface of the water when the floats float on the same.

The wing-actuating mechanism.—The wingactuating mechanism is shown in detail in Figs. 7 to 11. It is supported on parallel vertical steel-tubes u, which are located at the center of the supporting-main-frame of 35 the machine. Between the steel-tubes u are supported the short transverse shafts of upper sprocket-wheel v2. The upper parts 40 of the vertical steel-tubes u serve for guiding. | joints with the lower ends of the lever-rods d, 105 the sleeve-shaped crossheads w. The upper ends of the steel-tubes u are made converging and support at their upper ends the transverse pivot-shaft c of the wings B. Motion 45 is transmitted to the wings from the mainshaft 23, driven by the motor E, by means of a gear-wheel 49, which is placed loosely on the shaft and the flanged circumference of which is placed in contact with a clutch mem-50 ber 50 that is shifted on the main-shaft 23 by a lever 51 which is fulcrumed to the platform N, as shown in Fig. 16. The lower forked end of the lever 51 engages a grooved collar on the clutch member 50 and permits there-55 by the clutching of the gear-wheel 49. The gear-wheel 49 meshes with a pinion 52 that is placed on the shaft of a worm 53, said shaft turning in suitable journal-bearings on the platform N. The worm 53 meshes with a .60 worm-gear z on the shaft of the lowermost pair of sprocket-wheels v and between the same, as shown in Fig. 7. The rotation of the worm-gear z moves two sprocket-chains x, x, which are driven by the sprocket-wheels 65 v and guided by the sprocket-wheels  $v^1$  and

it in a horizontal direction in connection  $|v^2|$ . When the clutch member 50 is uncoupled from the gear-wheel 49 by the lever 51 the wings are held in the position in which they are at the moment of uncoupling, by the locking action of the worm-gear 53 on 70 the worm-gear z. This locking action arrests immediately the motion of the transmitting sprocket-chains x, x, and thereby the motion. of the wings. When the worm-gear z is rotated by the transmitting mechanism de- 75 scribed, the sprocket-chains x, x are set in motion by the sprocket-wheels  $v, v^1, v^2$ . The sprocket-chains are constructed in such a manner that the pivots  $x^1$  of the links of the chains are connected with the outer pair of 80 links, while the tubular pivots  $x^2$  on the pivots  $x^1$  are connected with the inner pair of links, as shown in Fig. 9.  $x^3$  is a suffering sleeve between the inner links and  $x^4$  are washers at the ends of the pivots  $x^1$ . Two 85 adjacent pivots of each of the double sprocketchains are connected by a cross-piece y, said pivots being attached to the chains by suitable screw-nuts  $x^5$ . The cross-pieces yare each provided with a conical head which 90 carries by means of two sets of antifrictionballs and suitable ball-races, a ring-shaped sleeve 1, and to these sleeves at corresponding points on the two chains are pivoted the forked lower ends 2 of two tubular connect- 95 ing rods d. Each forked lower end 2 is made of two parts, the shanks of which are connected by a sleeve 3 that is inserted into the lower end of the tubular connecting-rod  $d^{1}$  as shown in Figs. 9 and 11. The upper 100 ends of the connecting rod  $d^1$  are applied by sprocket-wheels  $v, v^1$  and  $v^2$ , which diminish | pivot-links to the crossheads w which are in size from the lower sprocket-wheel v to the | guided on the upright steel-tubes u. The crossheads w are connected by universal the upper ends of which are likewise connected by ball-joints with sockets 4, said sockets being supported by suitable braces on the center-ribs of the oscillating wings B, as shown in Fig. 7.

The wing-feathering mechanism.—The mechanism for feathering the wings is operated automatically with each oscillating motion of the wings. The closing motion of the wing panels is based on the fact that during 115 the upward motion of the wings B, the angle between them becomes gradually smaller, so that the parts supported on the wing-frames have to "give" and assume a different position. Figs. 4, 5 and 6 show the mechanism 120 for closing the panels b. On the center-ribs of the frames of wings B are supported near the transverse pivot-shaft c of the same, converging supporting frames m, m, and near the outer ends of the ribs inclined triangular 125 frames n, n. To the frames m are applied movable levers o, and to the frames n movable levers p connected by connecting rods r, s, with said levers o. The shorter arms of the supporting frames m are extended beyond 130

the upper cross-pieces of the frames and provided with rollers q, as shown clearly in Fig. 7 these rollers fitting into grooves on the bent sides of the levers o. The levers o and the 5 rollers q are so arranged on the supporting frames m that the lever of one wing is operated by the roller on the frame of the other wing. The levers o are guided along the rollers q, which are grooved sufficiently for 10 this purpose. By the upward motion of the wings, the shorter arm of the supporting frame m on one wing presses on the lever o of the opposite wing, so that the latter turns through a quarter of a circle. This motion is 15 transmitted by the tubular connecting-rods rand s to the levers p near the outer ends of the wings. The hinged panels b are connected by gut-strings t with the tubular connecting rods r, as shown clearly in Figs. 21, 22 20 and 23. When the wings arrive in their highest position, the panels b are proved from the open position, shown in Fig. 4, into the closed position, shown in Fig. 7, so that the wings are ready for the downward motion 25 with all the panels in closed position. When the wings arrive at their lowermost position and commence the next upward oscillation, the panels are placed in open or pendent position by the counter pressure of the air, so that 30 there is little resistance by the air to the upward motion of the wings.

The horizontal steering motion.—Steering in a horizontal plane is effected by the joint action of the rudder D and propellers C1, C1. 35 The rudder is moved in the direction in which the flying machine is to be steered, either to the right or left, and simultaneously therewith the propellers are shifted in opposite direction into such a position that their 40 shafts form an angle with the longitudinal axis of the machine, corresponding to that of the rudder with said axis. The steeringmechanism is shown in Figs. 13, 14 15, 17, 18 and 19. The frame j of the steering-rudder 45 D turns on a vertical pivot at the lower forwardly-extending part F2 of the main-frame. To the bottom of the rudder-frame j is attached a worm-segment i2 which meshes with a worm 7b, the shaft of which is supported on 50 the main-frame. Motion is transmitted to the worm 7<sup>b</sup> from a hand steering-wheel 8, which is attached to an inclined tubular rod, as shown clearly in Fig. 16, and which transmits motion by bevel-gears 9, 9, to a tubular 55 rod 10 and by the same and bevel-gears, 9, 9, to the shaft of the worm 7b, as shown in Fig. 14. At the same time the motion of the steering-wheel 8 is transmitted by a second set of bevel-gears 91, 91 adjacent to and be-60 low the first set 9, 9, to a tubular rod 11, which turns in suitable bearings supported on the rear-frame of the machine, and by the rod 11 and a bevel-gear transmission 9×9× to the shaft of the worm 7 and from said shaft

65 by bevel-wheels 92, 92 at the opposite end, to

an upright tubular rod 12, and bevel gears 9<sup>3</sup> 9<sup>3</sup> to the shaft of the worm 7<sup>a</sup>. On the rear-part of the supporting main-frame are located horizontal carrier segments 5 and 5<sup>a</sup> for the shafts of the propellers. These car-70 rier-segments 5, 5<sup>a</sup> are rigidly attached to the rear-frame and support at their centers the upright bearings 6 and 6<sup>a</sup>.

On the circumference of the carrier-segments 5 and 5° are located the journal-bear- 75 ings for the shafts of the worms 7 and 7a. On the stationary carrier-segment 5 is supported the worm-segment i guided thereon by means of rollers 48. The hub of the worm-segment i is made fast to the hanger- 80 shaft 41 by a clamping - screw 45. The worm-segment i turns with the upright shaft 41, which is supported in the hanger-bearing 6 by means of screw-nut 42. Antifriction roller-bearings are arranged between the 85 hanger-bearing 6, the screw-nut 42 and the hub of the worm-segment i. The hangershaft 41 supports, in a recess, the shaft 43 for the lower propeller. On a collar on the lower end of the shaft 41 is supported by 90 means of antifriction-bearings, a double bevel-gear wheel 44. Motion is transmitted from the main-shaft 23 by a bevel-gear 46 to the lower gear of the double-bevel-gear 44, while the upper gear of the same transmits 95 motion to a bevel-gear 47 keyed to the shaft 43 of the lower propeller. By this transmission, rotary motion is imparted to the lower propeller in whatever position the same is placed for steering. From the lower pro- 100 peller shaft 43 rotary motion is transmitted to the upper propeller Cbby a pulley he and belt h to a pulley on the shaft of the upper propeller. The main-shaft 23 receives rotary motion from the crank-shaft of the mo- 105 tor, which is supported on the platform N, by means of gear-wheels, pulleys and belt, or other transmission.

Fig. 12 shows a rear-elevation of the rudder and its frame. The dotted lines show 110 the rudder placed in inclined position to a vertical plane passing through the longitudinal axis of the rudder-frame. The gearwheel k is connected by steel-strings  $a^{\times}$  with the front and rear-ends of the longitudinal 115 rudder-frame. The turning of the rudder into laterally-inclined position is accomplished by a hand-wheel 13 located below the steering-wheel 8, jointed connecting-rods 14 and gears 15, 15<sup>a</sup> and 15<sup>b</sup>, gear 15<sup>b</sup> being 120 in mesh with the gear-wheel k, as shown in Figs. 12 and 13. The gear-wheel 15 is located at the end of the lower connecting-rod 14 and supported at the front-end of the main-frame, the gear-wheel 15° on the rud- 125 der-supporting frame j and gear-wheel 15b also loosely on the supporting-frame j. By this gear-wheel transmission the rudder can be turned sidewise in whatever steering position the same has to be placed. The worm 130

7<sup>b</sup> by which the rudder is moved horizontally in either direction is connected by the chain and sprocket-wheel transmission 1 with the shaft of a worm 7<sup>c</sup>, which is located 5 near the front-axle of the vehicle, so that the steering-wheel 8 can also transmit horizontal steering motion to the vehicle when the ma-

chine is moved over firm ground.

The vertical steering motion.—The vertical 10 steering motion is accomplished by shifting the gondola M in forward or backward direction in its tubular guide-rails 16. The motion of the gondola is controlled by a handwheel 17, which is located adjacent to and 15 above the steering-wheel 8 and the steeringpillar in which said rods are supported. The tubular rod to which the hand-wheel 17 is applied passes through the tubular rod of the hand-wheel 8 and carries at its lower end a 20 bevel-wheel 18, which meshes with a similar bevel-wheel 18 on the horizontal shaft of a worm 19, as shown in Figs. 13 and 16. The worm 19 meshes with a worm-gear 20, which is located sidewise of the same, but in the 25 same plane with the worm 19; as shown in Fig. 17. The gear-wheel 20 is provided with a grooved circumference, around which the steel-rope 21 is passed. The steel-rope 21 passes over suitable guide-pulleys at the 30 front and rear-ends of the lower main-frame and is attached to the ends of the gondola M, as shown in Fig. 13, so that the same can be moved in one or the opposite direction on its ways 16, according to the direction imparted 35 to it by the steel-rope 21. The gondola M is held in position on the ways by a horizontal steel-tube 22, having a suitable guide-roller for the gondola and guide-pulleys at its ends for the shifting steel-rope 21. By the shift-40 ing of the gondola, together with the weight of the ballast for the occupant of the same, the center of gravity of the flying machine is moved either in forward or backward direction, according to the direction imparted to 45 the gondola. By the forward or backward motion, the angle of inclination of the aeroplanes and the wings toward the horizontal plane is changed, so that the machine can be moved in upward or downward direction. 50 By the shifting of the center of gravity, the entire flying-machine can be placed in such a position that the air-currents can be utilized for the proper flotation of the same.

The auxiliary steering devices.—For the purpose of effecting the steering operation quickly and effectively, both steering-mechanisms are provided with auxiliary steering-devices, which are actuated from the mainshaft 23. For this purpose the platform N is provided with a U-shaped hanger-frame 24, in which the shaft of the worm 19 is keyed a bevel-gear 25, which meshes with a bevel-gear 26, the upright shaft of which is journaled in the lower part of the U-shaped

hanger-frame 24. At the underside of the hanger-frame, but keyed to the shaft of the bevel-gear 26, is arranged a friction-disk 27, which is provided with a circumferential rubber-rim 28. Below the friction-disk 27 70 is arranged on the main-shaft 23 a longitudinal sliding-sleeve 30, which is guided by slots on diametrically-opposite pins and provided at opposite ends with frictiondisks 29. Either one of the friction-disks 75 can be placed in contact with the circumference of the friction-disk 27 by means of a lever 33, which is located on the steeringpillar in which the tubular rods of the handwheels 8 and 17 are supported, said lever 80 being pivoted to said pillar below the steering-wheel 8 and connected by a pivot-rod 32 and elbow-lever 31 with a grooved collar adjacent to the rear friction-disk 29. The elbow-lever is fulcrumed to a suitable sup- 85 port on the main-frame and made forkshaped at its lower end, so as to engage said collar. The auxiliary steering-lever 33 permits the shifting of the sleeve 30 and its friction-disks in either direction, so that one 90 friction-disk 29 or the other is placed in contact with the main transmitting-disk 27. The rotary motion imparted to the frictiondisk 27 imparts, by means of the bevel-gears 26, 25, worm 19 and worm-gear 20, a quick 95 motion to the steel-rope 21, so that the gondola M is moved in forward direction on its. guide-ways by the downward motion of the lever 33, whereby the center of gravity is moved in forward direction, and a greater 100 load is placed on the front aeroplane A, and the flying machine is moved in downward direction, or it is moved in backward direction by the upward motion of the lever 33 moving the sleeve 30 to the rear end of its guide- 105 ways, whereby the center of gravity of the machine is moved in backward direction, so that a greater load is placed on the rear aeroplane, whereby the load on the front aeroplane is diminished and thereby the ma- 110 chine placed in a position for ascending motion.

The second auxiliary steering-device is operated by the lever 39 and connected with a horizontal steering mechanism. In the 115 platform N is supported a friction-disk 35, which is provided at its circumference with a rubber - rim 28. This friction - disk is placed in contact with one of the frictiondisks 40 at the ends of a second sleeve 30<sup>a</sup> 120 that is guided on the main-shaft 23 by pins in the same manner as the sleeve 30. On the upper end of the shaft of the frictiondisk 35 is mounted a driver-pulley 36, around which and a pulley 36° on the tubular shaft 125 of the steering-wheel 8 is passed a steel-rope or belt. By the auxiliary lever 39, connecting-rod 38 and elbow-lever 37, which latter. engages by its forked lower end a grooved collar on the end of the sleeve 30°, either one 130

placed in contact with the circumference of the friction-disk 35, so that by the movement of the lever 39 towards the right or left, 5 the horizontal steering mechanism is moved towards the right or left, as desired. In Fig. 16 the auxiliary steering-devices are shown in their neutral or non-acting position, while Fig. 15 shows a plan-view of the auxiliary 10 levers 39 and 33.

All the hand-wheels for the starting-devices, horizontal and vertical steering mechanisms and the levers for the auxiliary starting and steering-devices are located in prox-15 imity to the seat L on which the person who steers the flying-machine is seated, so that any required motion can be carried out in-

stantly and with great facility.

For demonstrating the combined effect of 20 the aeroplanes, wings and propellers, it is assumed that the flying machine is moved over a water-surface and moved by the two screwpropellers, whereby an air-current is generated under the aeroplanes which produces a 25 certain resistance to the strokes of the wings. Each stroke of the wings pushes the flying machine forward, whereby the pressure of the air under the aeroplanes is increased. The wings force the air in backward direc-30 tion under the aeroplane A1 and towards the propellers. The propellers rotate in this increased air-pressure, whereby the machine is driven forward with increased speed. By continuing the strokes of the wings the flying 35 machine is moved forward at increased speed until the upward pressure of the aeroplanes is large enough so as to keep the machine afloat. By the forward propulsion of the machine in a forward direction the aero-40 plane A passes into a quiet layer of air, while the motion of the wings in upward direction. produces a decrease of pressure under the same, so that the air which is passing off below the aeroplane A follows quickly the wing-45 motion. The stroke of the wings in downward direction acts therefore always on an upwardly-moving air-body, so that the lifting power of the wings is augmented. The stability of the machine is preserved auto-50 matically and is accomplished by the form, and position of the aeroplanes, which was tested by means of an aeroplane model. That the machine is moved simultaneously in forward direction when it descends in the 55 air is accomplished by the form of the aeroplanes.

Having thus described my invention, I claim as new and desire to secure by Letters

Patent:

1. In a flying machine, in combination, with a supporting-frame, aeroplanes carried by said frame at the front and rear and ex-| struction a rudder formed of a forwardly tatending to either side thereof, the rear aero- pering frame mounted to turn on an axis plane being higher than the front aeroplane, disposed longitudinally of the machine, a

of the friction-disks 40 on said sleeve is I frame between said aeroplanes and forming when outspread a third aeroplane similar to the others, and wing-operating mechanism.

2. In a flying machine, the combination, with a supporting frame, of laterally and lon- 70 gitudinally curved aeroplanes mounted thereon and extending transversely thereof to either side of the same at the front and rear of the machine, said aeroplanes being inclined downwardly towards the rear of the 75 machine and the rear aeroplane being higher than the front aeroplane, wings mounted on said frame between said aeroplanes, and means for oscillating said wings.

3. In a flying machine, the combination, 80 with a supporting frame, of a shaft extending longitudinally thereto and supported thereby, wings pivoted to said shaft and extending to either side of the machine, upright guiderods below said wings, crossheads guided 85 vertically on said guide-rods, a connectingrod connecting each crosshead with its corresponding wing, and means for reciprocat-

ing said crossheads.

4. In a flying machine, the combination, 90 with a supporting frame, of wings pivoted thereto, parallel upright guide-rods carried -by said frame below said wings, stud-shafts connecting said guide-rods, sprockets mounted on said stud-shafts, chains movable over 95 said sprockets, crossheads movable on said uprights, rods connecting said chains and said crossheads, and means for connecting the latter with the wings.

5. A flying machine comprising a sup- 100 porting frame, a pair of wings pivoted thereto and each comprising a plurality of swinging panels, means for oscillating said wings, and means operated by each of said wings in its oscillatory movement for operating the 105 panels of the other wing and thereby feather-

ing said wing.

6. In a flying machine, the combination, with wings pivoted to a common shaft, of swinging panels carried by each wing, and 110 means mounted on each wing for operating the panels of the other wing, said means being operated automatically when said wings assume a predetermined angle.

7. A flying machine comprising a sup- 115 porting frame, means for propelling the same through the air, a rudder at the front of said frame, means for angularly moving said rudder about a vertical axis, and means for angularly moving the same about an axis dis- 120 posed longitudinally of the machine.

8. A flying machine including in its construction a rudder formed of a forwardly tapering frame mounted to turn on an axis disposed longitudinally of the machine.

9. A flying machine including in its con-65 vertically oscillating wings pivoted to said | gear-wheel embracing said frame, a second 140 gear-wheel engaging the first, and means for

rotating said second gear-wheel.

10. A flying machine including in its construction steering propellers mounted one 5 above the other, means for simultaneously shifting said propellers to different angles to the vertical longitudinal plane of the machine, means for transmitting motion from one of said propellers to the other irrespective 10 of their position, and means for driving one of said propellers while in its different positions.

11. In a flying machine, the combination, frames or rims mounted on said propellers and traveling in frictional contact with each other.

12. In a flying machine, the combination, 20 with the frame, of the horizontal guideways arranged longitudinally therein, the ballastcarrying gondola movable in said guideways, the steel rope-transmission for moving said gondola in either direction, and the steering-25 wheel for actuating said transmission.

13. In a flying machine, a frame, a ballastcarrying gondola guided therein, a powerdriven or erating shaft, means for shifting said gondola, and means for coupling said 30 shifting means with said operating shaft.

14. In a flying machine, a frame, a ballastcarrying gondola guided therein, means for manually shifting said gondola, a frictionwheel in operative connection with said

shifting means, a power-driven operating 25 shaft, a friction-sleeve on said shaft having terminal disks disposed at either side of said friction-wheel and movable into contact therewith, and means for shifting said sleeve in either direction.

15. In a flying machine, the combination, with a steering propeller, of manually-operable means for shifting the same, and auxiliary power-operated propeller-shifting means.

16. In a flying machine, a steering propel- 45 ler, means for manually shifting the same angularly with respect to the vertical longiwith the parallel propeller-shafts, of the pro- | tudinal plane of the machine, a power-driven 15 pellers mounted thereon, and the circular operating shaft, and a device for coupling said operating shaft with said shifting means. 50

17. In a flying machine, the combination, with a steering propeller, of means to shift the same angularly with respect to the vertical longitudinal plane of the machine, a manually-operable steering pillar in operative 55 connection with said shifting means, a powerdriven operating shaft, a friction - wheel adapted to be driven thereby, and an operative connection between said friction-wheel and said steering pillar.

In testimony that I claim the foregoing as my invention, I have signed my name in presence of two subscribing witnesses.

#### FRANZ WONDRA.

Witnesses:

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PAUL GOEPEL, . Henry J. Suhrbier.