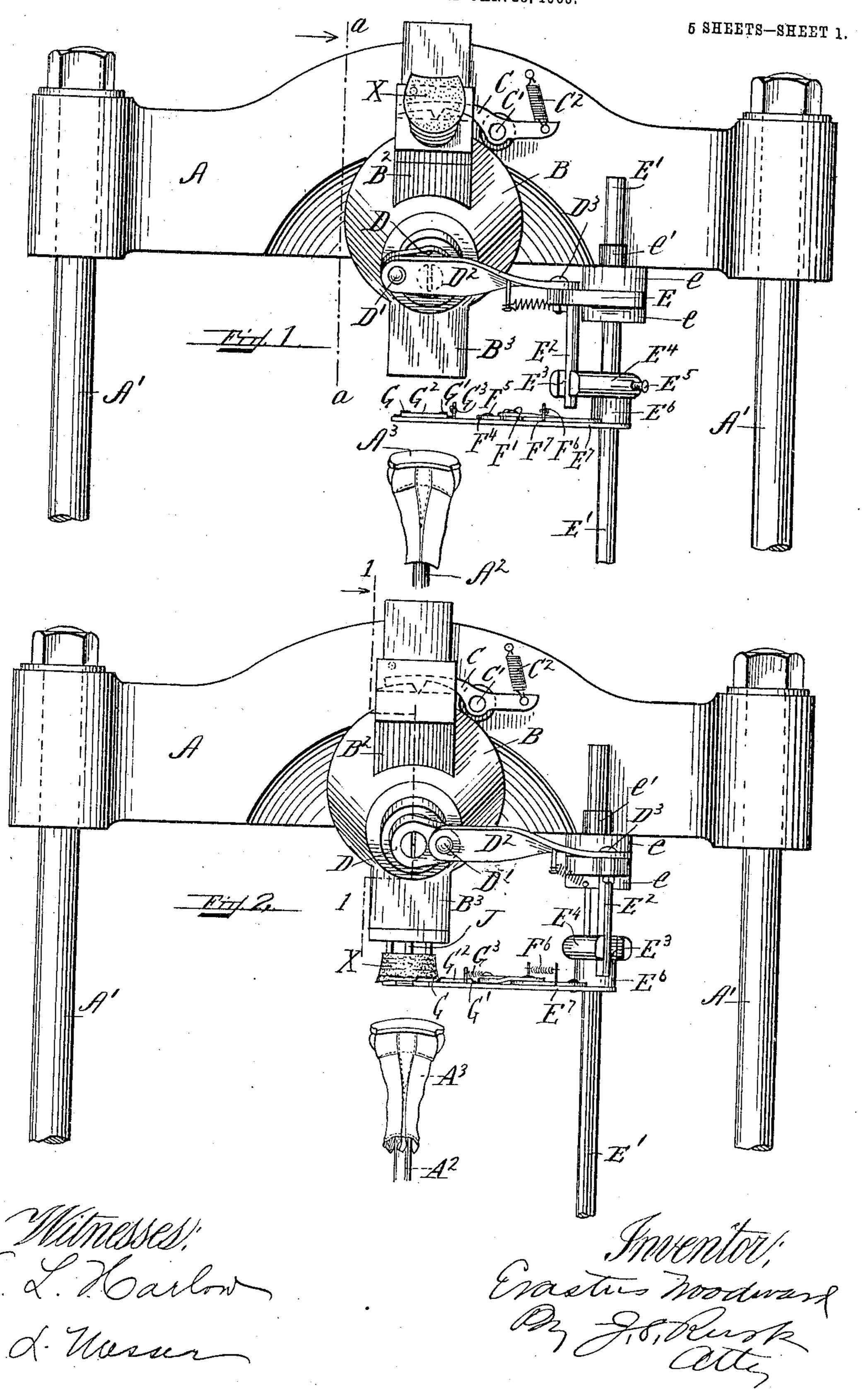
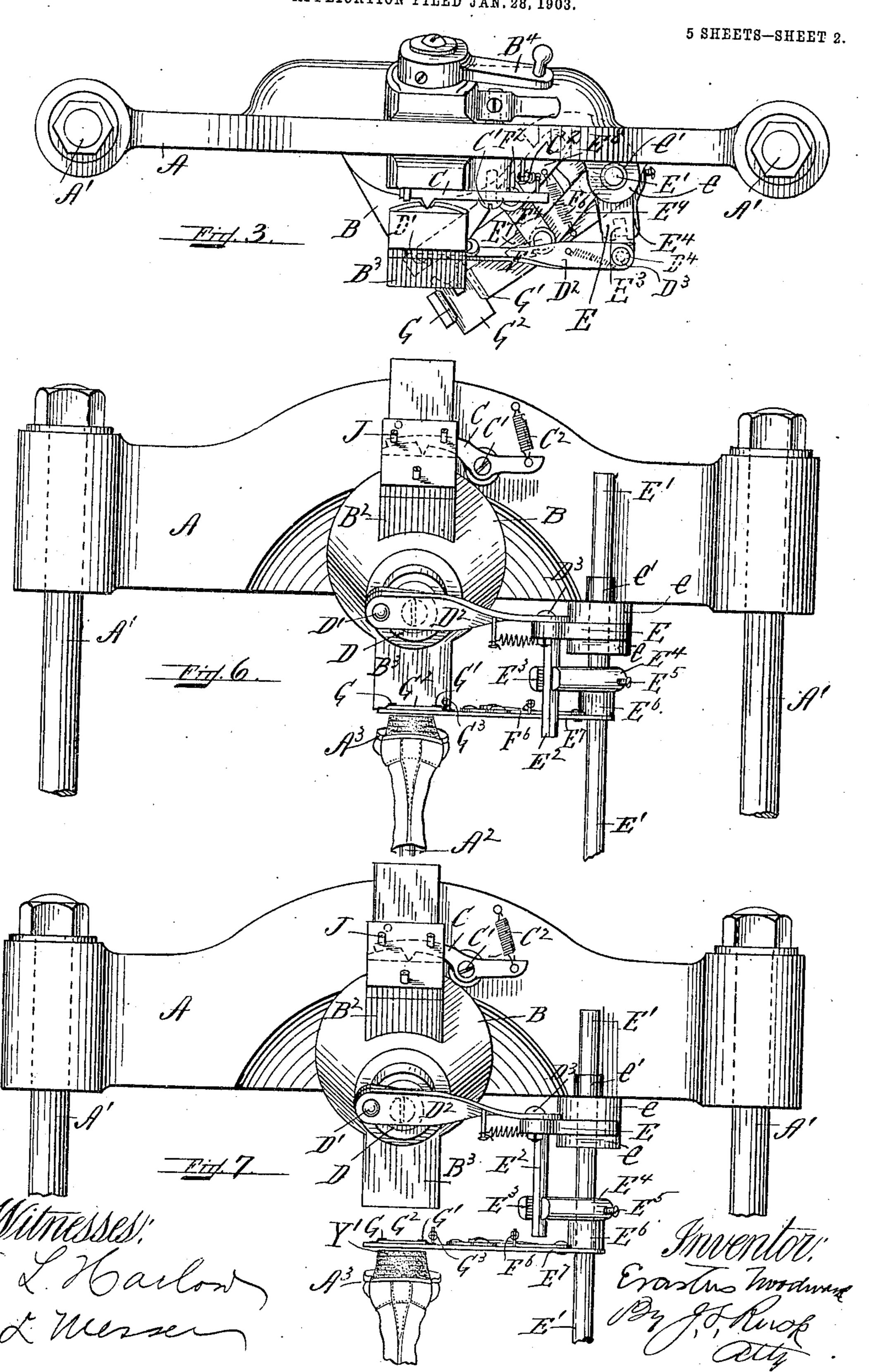
E. WOODWARD.

HEEL ATTACHING MACHINE.

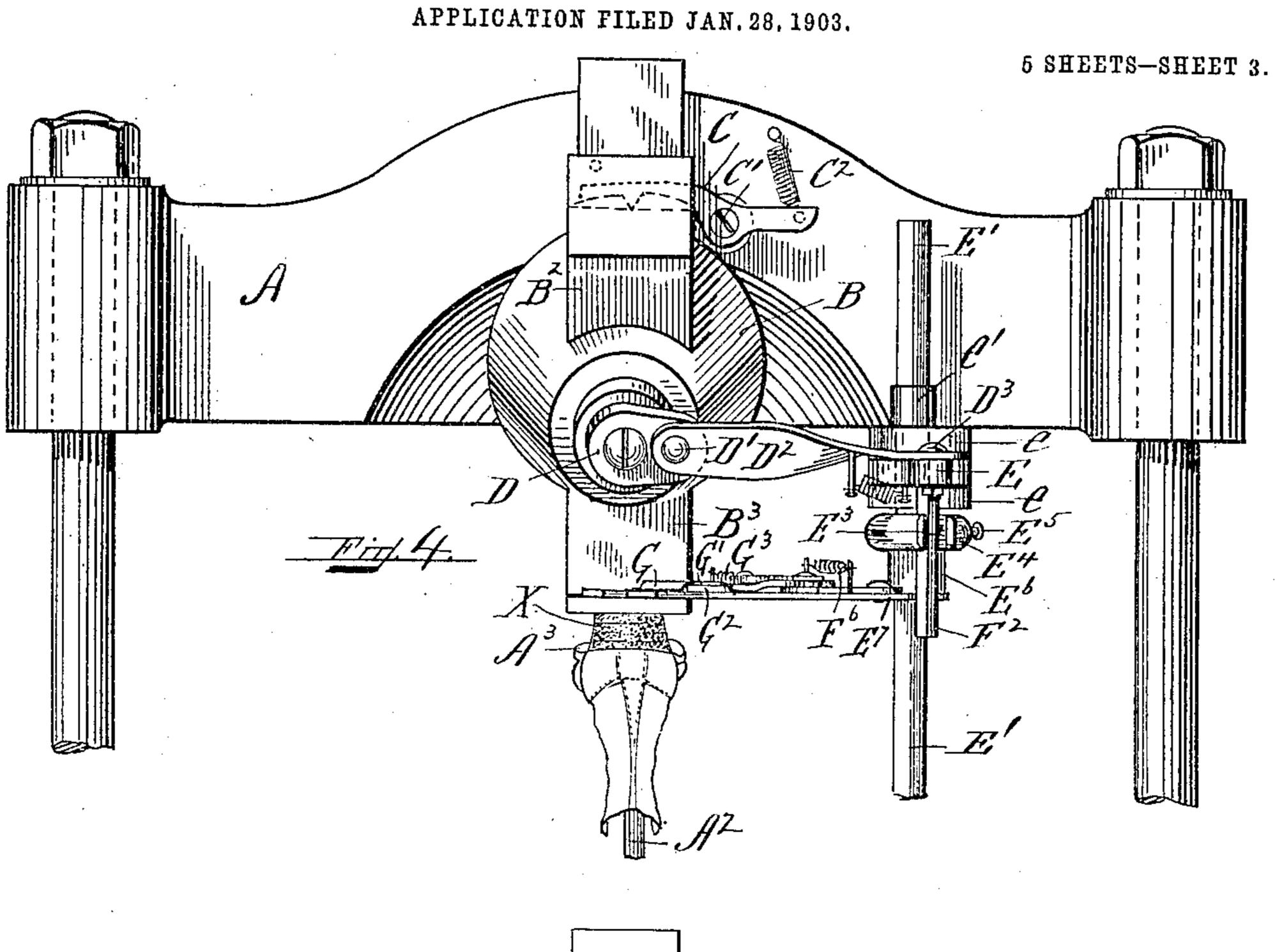
APPLICATION FILED JAN. 28, 1903.

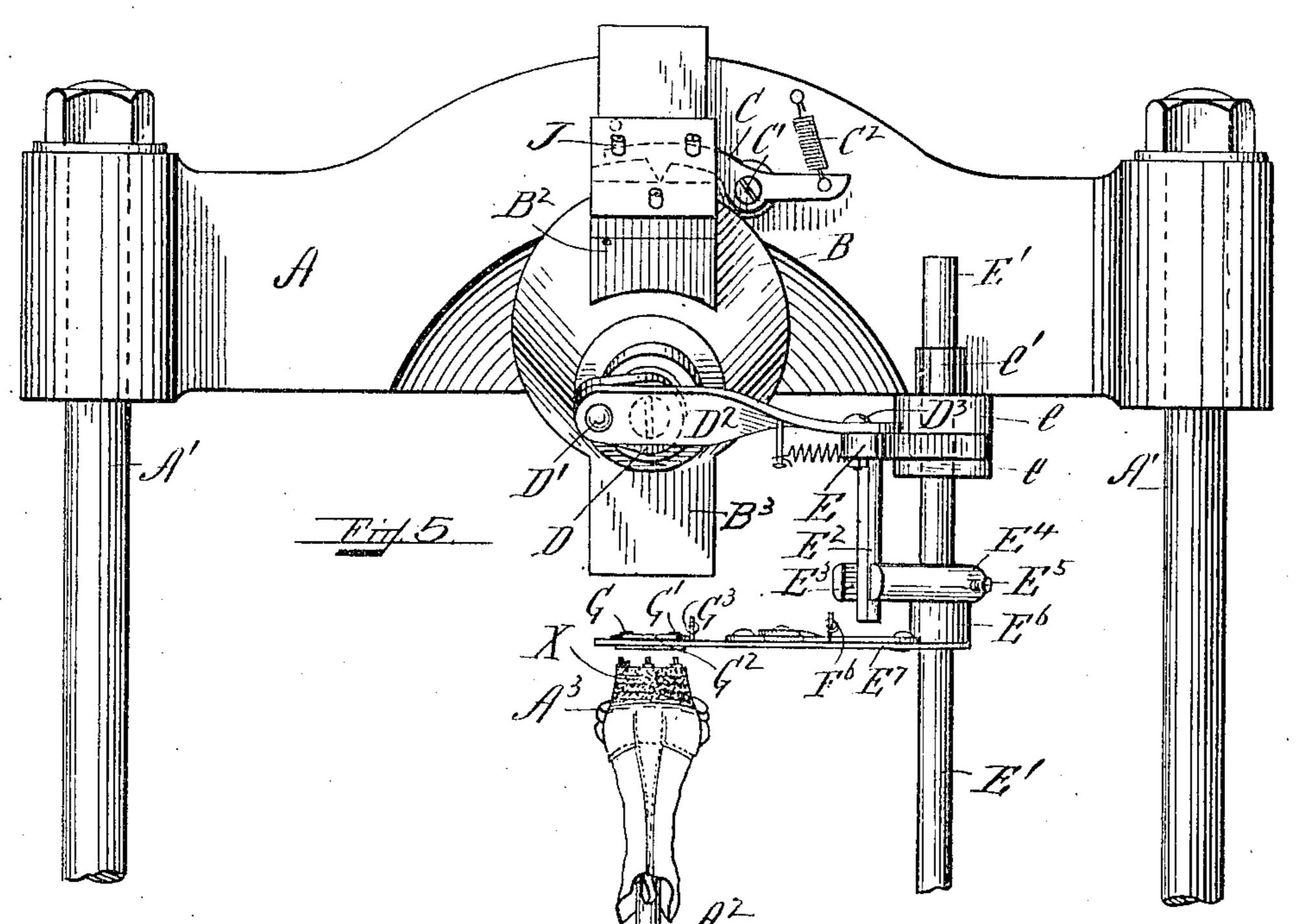


## E. WOODWARD. HEEL ATTACHING MACHINE. APPLICATION FILED JAN. 28, 1903.



## E. WOODWARD. HEEL ATTACHING MACHINE.



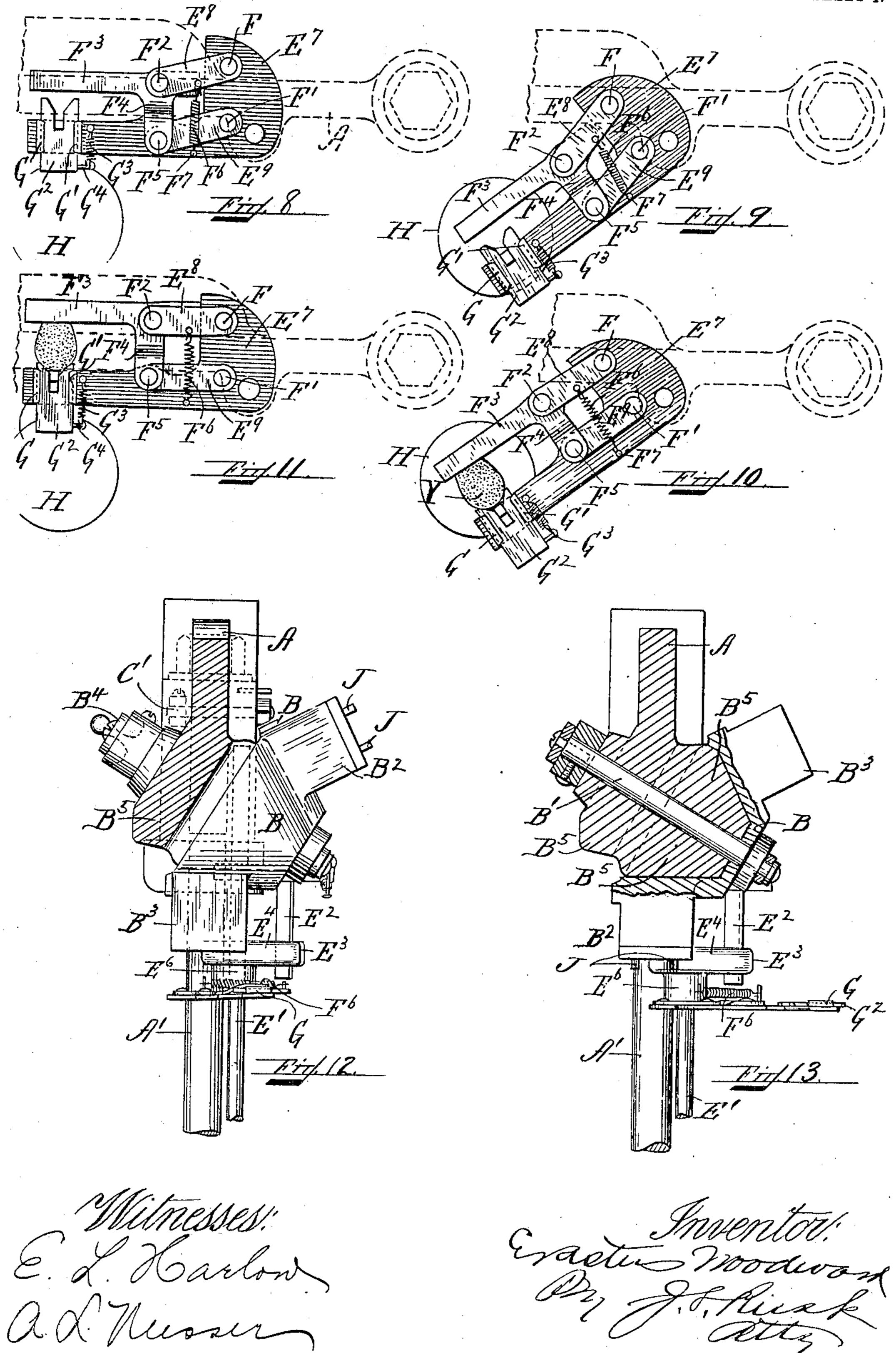


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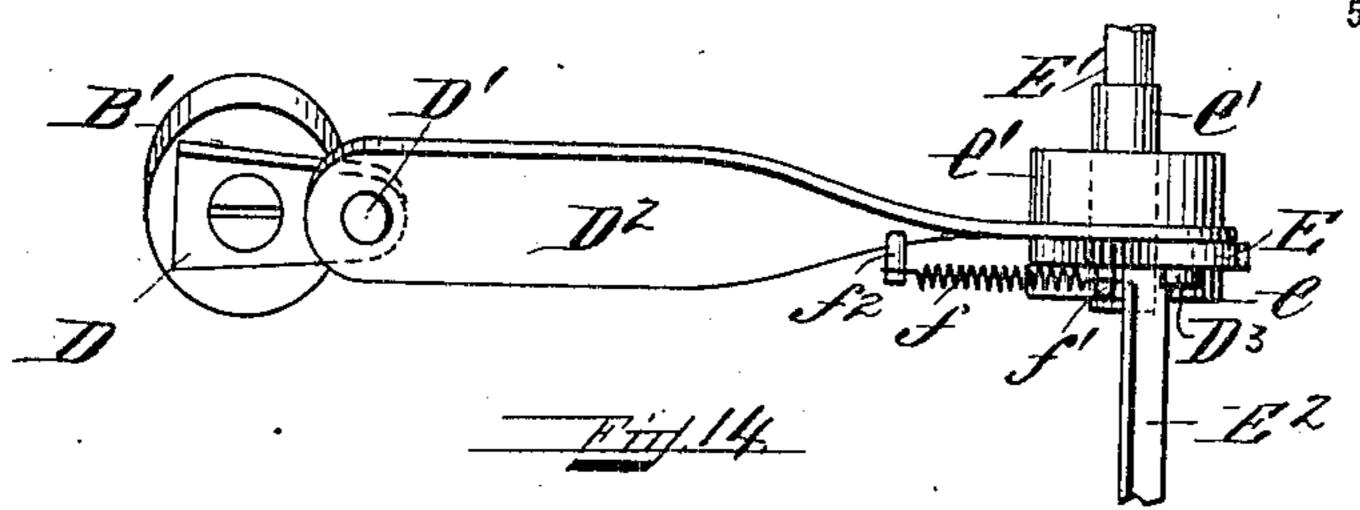
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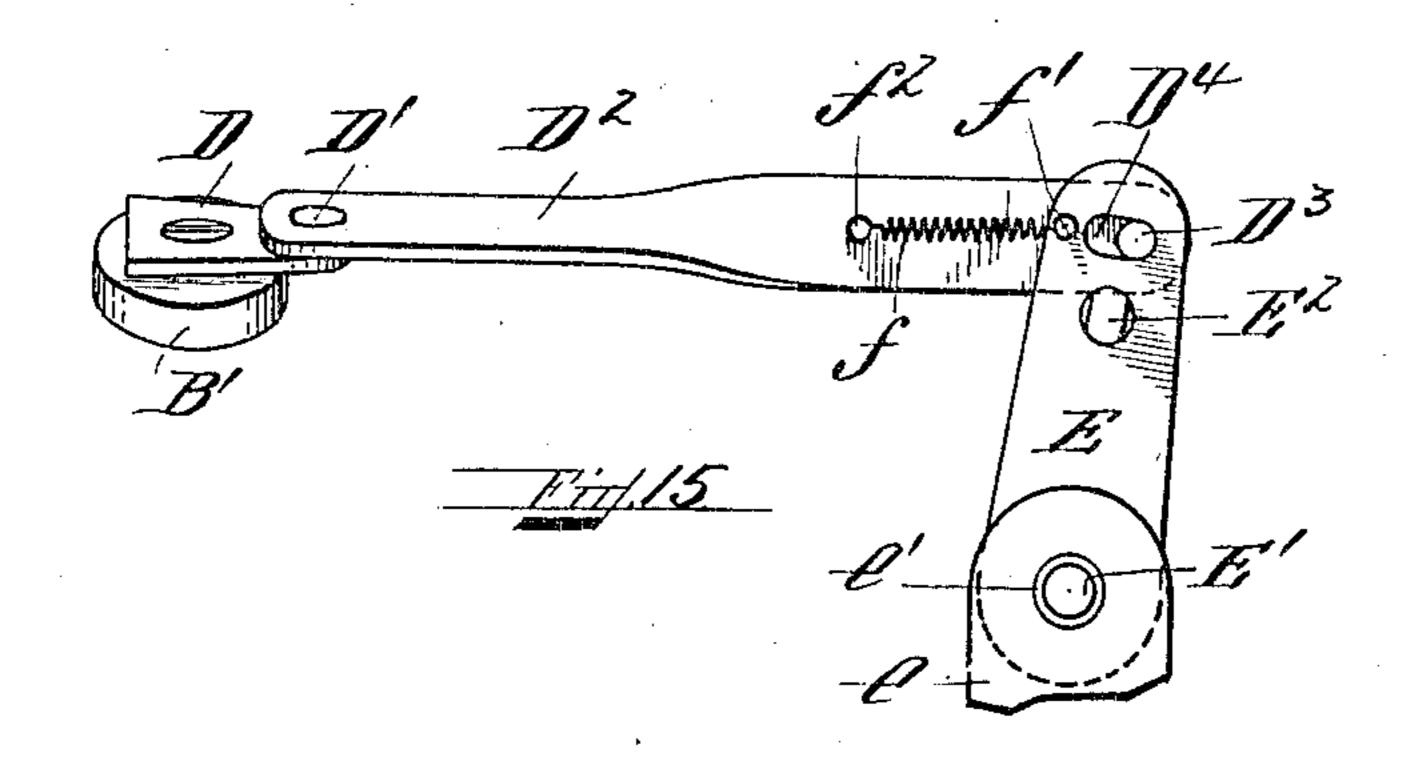


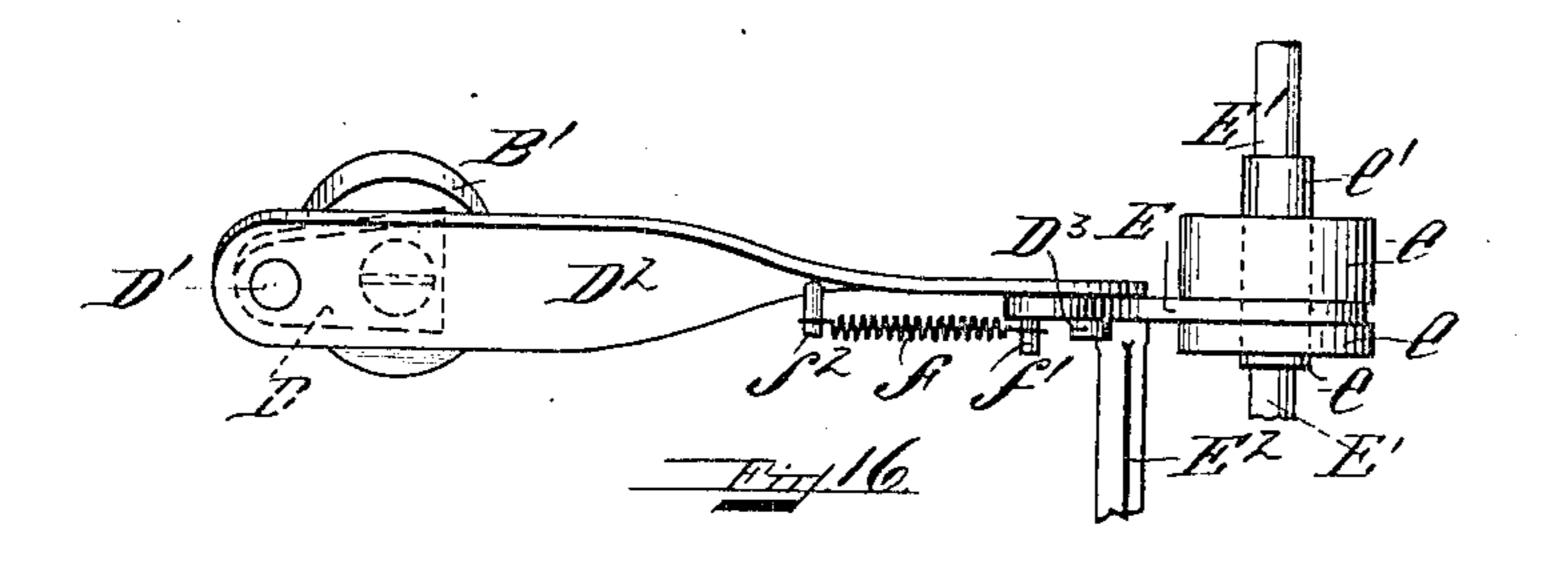
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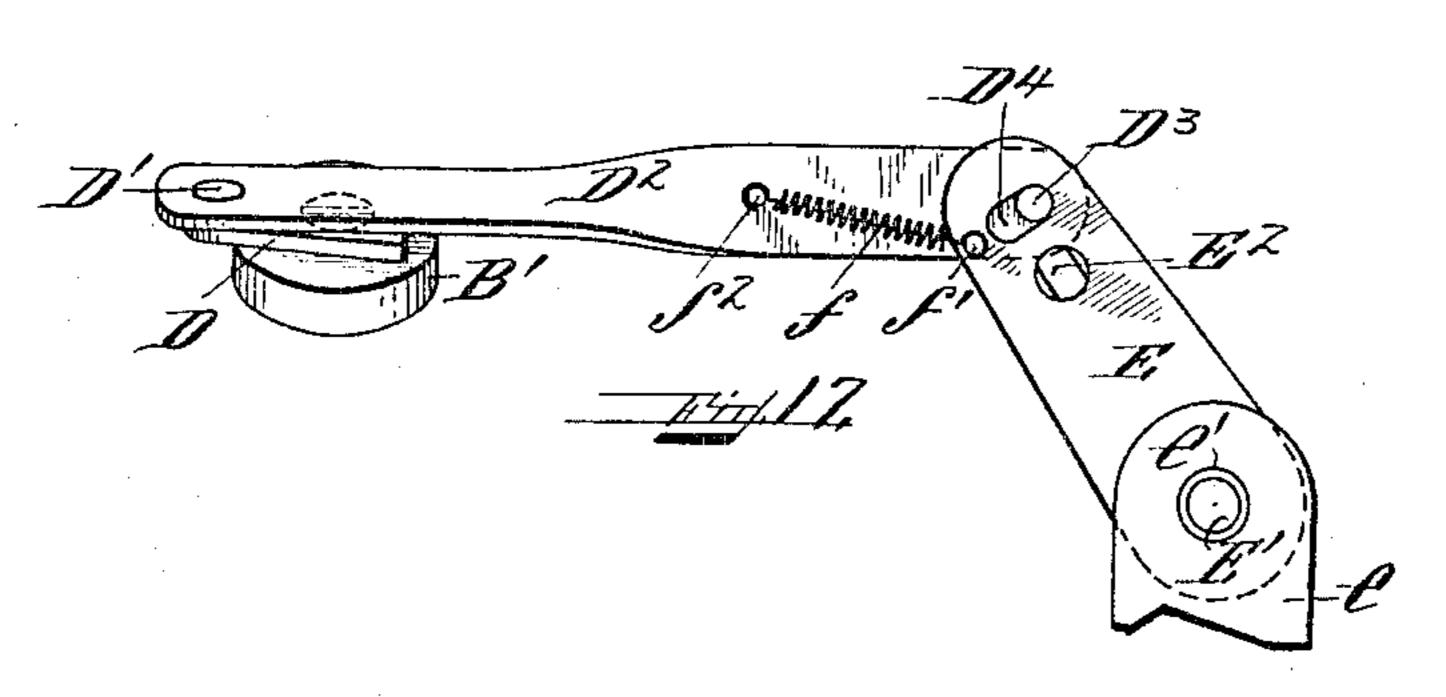
APPLICATION FILED JAN. 28, 1903.

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A. Lamabu

Erachus Inventor!

#### UNITED STATES PATENT OFFICE.

ERASTUS WOODWARD, OF SOMERVILLE, MASSACHUSETTS.

#### HEEL-ATTACHING MACHINE.

No. 844,573.

Specification of Letters Patent.

Patented Feb. 19, 1907.

Application filed January 28, 1903. Serial No. 140,833.

To all whom it may concern:

Be it known that I, Erastus Woodward, of Somerville, in the county of Middlesex and State of Massachusetts, have invented 5 certain new and useful Improvements in Heel-Attaching Machines, of which the following is a specification.

My invention relates to a machine for attaching heels loaded with nails to the keel-10 seats of boots and shoes, and where blindnailing is employed to the subsequent attachment of top lifts to the attached heels.

My improvement is shown applied to a heeling-machine in which there is a verti-15 cally-reciprocating cross-head carrying a hub adapted to be oscillated about a shaft and provided with two diametrically-arranged arms, one of which carries the naildriving mechanism to which the loaded heel 20 is applied for attachment to the shoe and the other arm being adapted to subsequently attach or spank the top lift onto the attached heel at the proper time. I have not shown in the drawings the mechanism for recipro-25 cating this cross-head, as it is too well known in the art to require description.

My invention consists of certain novel features hereinafter described, and particularly

pointed out in the claims. In the accompanying drawings, which illustrate a construction embodying my invention, Figure 1 shows a side elevation of the cross-head referred to, together with the jack in position thereunder for holding the 35 shoe, and also showing the loaded heel held on the upper arm, to which it has been applied by the body. Fig. 2 is a similar view with the arms reversed and showing the keel above the jack in position to be attached to 40 the heel-seat of the boot or shoe. Fig. 3 is a top plan view of Fig. 2 and showing the toplift-carrying device out of the vertical line of motion of the arm carrying the heel during its attachment to the heel-seat of the boot or 45 shoe. Fig. 4 is a side elevation showing the cross-head down with the heel attached to the shoe. Fig. 5 is a side elevation similar to Fig. 4 with the arms reversed and showing the projecting ends of the nails onto which 50 the top lift is to be attached. Fig. 6 is a view similar to Fig. 5 with the cross-head down and the spanker-block attaching the top lift to the projecting ends of the nails. Fig. 7 is a view similar to Fig. 6, showing the

cross-head raised with the arms and the heel 55 finished. Fig. 8 is a top plan view of the toplift-carrying device in the position shown in Fig. 1 when the heel is applied by the boy to the arm carrying the heel-attaching mechanism. Fig. 9 is a top plan detail view of 60 the top-lift-carrying device with the parts in the position shown in Fig. 2 out of the driving-line of the arm carrying the heel. Fig. 10 shows a top lift applied to the top-lift-carrying device and ready to be moved into po- 65 sition under the spanker-block for attachment to the attached heel. Fig. 11 is a top plan view of the top-lift-carrying device and in the driving-line of the spanker-arm for attachment of the top lift to the attached keel. 70 Fig. 12 is a cross-sectional view through the cross-head on the line a a, Fig. 1. Fig. 13 is a cross-sectional view through the head and hub with the two arms in full lines on line 11, Fig. 2. Figs. 14 and 15 are respectively 75 side and under side plan views of the mechanism which operates the top-lift-carrying device, representing the parts in their positions when the top-lift-carrying device is out in position to receive a top lift. Figs. 16 80 and 17 represent, respectively, side and under side plan views of the mechanism which operates the top-lift-carrying device, showing the parts in their positions when the toplift-carrying device is moved inward with the 85 top lift over the heel for attachment thereto.

Like letters of reference refer to like parts

throughout the several views.

In the drawings the cross-head A is reciprocated, by means of the rods A', in the man- 90

ner well known in the art.

A<sup>2</sup> is the last, carrying the shoe to which the heel and top lift are to be attached when blind-nailing is employed and to which the heel only is to be attached when flush-nailing 95 is employed. The hub B, attached fast to the shaft B', which is set at an angle of thirty degrees, carries the diametrically-arranged arms or blocks B<sup>2</sup> B<sup>3</sup>, and said hub and arms are adapted to be firmly held in position dur- 100 ing the attaching operation by the arm C, pivoted at C' on the cross-head A and nor-. mally caused to engage a suitable recess in each arm by means of the spring C2. (Shown in Figs. 1, 2, and 3.) Secured fast to the 105 lower end of the shaft B' is the arm D, to which is pivotally connected at D' the lever D<sup>2</sup>, which at its opposite end is pivotally con-

nected to the arm E by the pin D3, extending down through the opening in the movable arm E, mounted freely on the sleeve e'around the rod E', which extends upward 5 from the base of the machine. The end of this arm E opposite the lever D2 is supported in the lugs e, secured to and extending from under the cross-head A, and in the movements of the lever  $D^2$  the arm E moves to and fro on the sleeve e', supported in the lugs e. From the under side of the arm E there extends downwardly the depending rod E2, which passes through the slot E3 in the bifurcated arm E4, held fast on the rod E' by the 15 set-screw E<sup>5</sup>. Secured to the boss E<sup>6</sup> on the arm E4 is the plate E7, to which are pivotally secured two links E<sup>8</sup> E<sup>9</sup> at F and F'. The forward end of the link E<sup>8</sup> is pivotally connected at F<sup>2</sup> to the arm F<sup>3</sup> of the link F<sup>4</sup>, to 20 which is secured the forward end of the link E<sup>9</sup> at F<sup>5</sup>, forming the well-known parallel motion. The spring F<sup>6</sup>, secured to the link E<sup>8</sup> at one end and at its opposite end to the pin F<sup>7</sup>, tends to hold the forward end of the 25 arm F<sup>3</sup> in a parallel closed position with respect to the forward end of the plate E<sup>7</sup> and exerts a pressure on the top lift to hold it square and clamped in a suspended position as it travels into position over the attached 30 heel. On the forward end of the plate E7 are two guides G G', in which there is adapted to slide the forked plate G2, having shoulders, as shown, to limit the forward movement of said plate under tension of the spring G3, se-35 cured to the plate E<sup>7</sup> and to the pin G<sup>4</sup>. The top lift is placed on the top-lift-carry-

ing device by putting its breast against the parallel arm F<sup>3</sup> and forcing said arm out until the top lift Y drops into the fork in the plate 40 G2, which yields as the arm F3 returns to its normal position under the tension of the spring F<sup>6</sup> until the back of the top lift strikes the edge of the forward end of the plate E<sup>7</sup>, which is the gaging-point of the top lift, the 45 plate H preventing the top lift falling through during its application, as above described. The plate H is located on a suitable standard extending up from the base of the machine and is fixed in positive relation to the arm F<sup>3</sup> 50 and the forward end of the plate E7, so that when the top-lift-carrying device is moved out into position to receive a top lift it comes directly over the plate H in close proximity thereto and prevents the top lift when being 55 applied thereto from passing through.

The machine is so organized that when the top lift is arranged as described and brought over the attached heel its rear end comes over the rear end of the heel in a positive re-

1 Depending from the under side of the lever  $D^2$  is the pin  $f^2$ , to which is attached the spring f, with its opposite end secured to the pin f', depending from the arm E, and located f'

beyond said pin f' is the slot  $D^4$ , which is 65 longer than the pin D³, so as to allow a yielding movement between the lever D2 and the arm E. When the top-lift-carrying device is in its outer or receiving position, as shown in Figs. 3 and 4, the coöperating parts shown in 70 Figs. 14 and 15 are in the positions indicated in said figures; but when the top lift moves inward over the heel for attachment the cooperating parts shown in Figs. 16 and 17 are in the positions indicated in those figures. 75 When the block B<sup>3</sup> moves downwardly from the position shown in Fig. 5 to that shown in Fig. 6, the top lift is spanked onto the attached heel, and owing to the force of the blow of the spanker-block B³ on the rigid 80 heel of the shoe located on the last the leather of the top lift spreads out, which causes the forward end of the plate F<sup>3</sup> to move laterally and yield by means of the spring F<sup>6</sup>, and at the same time the forward end of the plate E<sup>7</sup> 85 moves laterally and yields by means of the spring f, so that the top lift is not marred by the force of the blow of the spanker-block B<sup>3</sup>, its spreading being thus provided for as above described.

The plate E<sup>7</sup> is secured to the boss E<sup>6</sup>, carrying the bifurcated arm E<sup>4</sup>, fast on the shaft E', and through the slot E<sup>3</sup> of said bifurcated arm E<sup>4</sup> passes the depending rod E<sup>2</sup>, fast to the under side of the arm E. By 95 the constructions previously described the plate E<sup>7</sup> yields as the rod E<sup>2</sup> moves the arm E slightly toward the right from the position shown in Fig. 17 by the yielding of the spring f, and after the top lift is attached the spring f returns the arm E to the position shown in Fig. 17.

The loaded heels are secured on the heelblock B2 by means of the carrying and holding fingers J, which may be of any desired 105 construction and form no part of this invention. When the boy has placed a loaded heel X on the heel-block B2 and the same is held there by the fingers J, the boy operates the latch C to release the heel-block and al- 110 low it to be turned and brought into the position shown in Fig. 2. During this operation the top-lift-carrying device hereinbefore described moves out of alinement under the spanker-block B³ in the position shown in 115 Figs. 1 and 8 to the position shown in Figs. 2 and 9, when the boy places the top lift Y on the top-lift-carrying device in the manner shown in Fig. 10. In the meantime the operator has placed the shoe A3 on the jack A2 120 and operates the cross-head A to bring down the heel from the position shown in Fig. 2 to that shown in Fig. 4 for attachment to the

shoe and then turning the arm B4 brings the

Fig. 5. This movement brings the top-lift-

carrying device into position over the at-

tached heel and under the spanker-block B<sup>3</sup>,

heel-block B<sup>2</sup> up into the position shown in 125

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Fig. 6, when the operator brings the crosshead A down and spanks the top lift onto the attached heel and upon the upward movement of the cross-head A leaves the entire

5 heel Y' secured to the shoe.

When the parts are in the position shown in Fig. 1, the top-lift-carrying device is directly under the spanker-block B³ and over the shoe; but when the boy throws the block 10 B2 to bring it around over the shoe in the position shown in Fig. 2 the top-lift-carrying device moves from its horizontal position (shown in Fig. 8) to that shown in Fig. 9, ready to receive the top lift by the move-15 ment of the lever D2, arm E, rod E2, and arm E4 to the boss E6, to which the top-lift-carrying device is secured. When the operator turns the arm B4 to turn the heel-block up and turn the spanker-block down, the top-20 lift-carrying device, which has received a top lift, moves from the position shown in Fig. 10 to that shown in Fig. 11 through the operation of the lever D2, arm E, rod E2, and bifurcated arm E4, hereinbefore described, when 25 the top lift is in position to be spanked onto the attached heel. The hub B with the blocks B<sup>2</sup> B<sup>3</sup> do not rotate continuously in one direction, but oscillate in an arc of one hundred and eighty degrees.

Having thus described the nature of my invention and set forth a construction embodying the same, what I claim as new, and | the boot or shoe, a cross-head reciprocative desire to secure by Letters Patent of the

United States, is—

1. In a heel-attaching machine, a jack for the boot or shoe, a cross-head reciprocative relatively to said jack, a spanker-block rotatably mounted on said cross-head and cooperating with said jack, a top-lift-carrying 40 device pivoted to a fixed part of the machine, a pivoted lever movable with said cross-head and having a sliding connection with said top-lift-carrying device, and an arm rotatable with said spanker-block and connected

45 with said lever.

2. In a heel-attaching machine, a jack for the boot or shoe, a cross-head reciprocative relatively to said jack, a spanker-block rotatably mounted on said cross-head and co-5° operating with said jack, a top-lift-carrying device pivoted to a fixed part of the machine, a pivoted lever movable with said cross-head and having a sliding connection with said top-lift-carrying device, an arm rotatable 55 with said spanker-block, and a yielding connection between said arm and said lever.

3. In a heel-attaching machine, a jack for the boot or shoe, a cross-head reciprocative relatively to said jack, a spanker-block rota-60 tably mounted on said cross-head and cooperating with said jack, a fixed support, a top-lift-carrying device pivoted to said support, a pivoted lever movable on said fixed support in the same direction as said cross-

head and having a sliding connection with 65 said top-lift-carr, ing device, an arm rotatable with said spanker-block, and a link connect-

ing said arm with said lever.

4. In a heel-attaching machine, a jack for the boot or shoe, a cross-head reciprocative 70 relatively to said jack, a spanker-block rotatably mounted on said cross-head and cooperating with said jack, a fixed support, a top-lift-carrying device pivoted to said fixed support, a pivoted lever movable on said 75 fixed support in the same direction as said cross-head and having a sliding connection with said top-lift-carrying device, and an arm rotatable with said spanker-block and having a ylelding connection with said lever.

5. In a heel-attaching machine, a jack for the boot or shoe, a cross-head reciprocative relatively to said jack, a spanker-block rotatably mounted on said cross-head and cooperating with said jack, a fixed support, a 85 top-lift-carrying device pivoted to said fixed support, a pivoted lever movable on said fixed support in the same direction as said cross-head and having a sliding connection with said top-lift-carrying device, an arm ro- 90 tatable with said spanker-block, a link pivoted to said arm and having a loose connection with said lever, and a spring connecting

said link with said lever.

6. In a heel-attaching machine, a jack for 95 relatively to said jack, a spanker-block rotatably mounted on sald cross-head and cooperating with said jack, a fixed support, a top-laft-carrying device pivoted to said fixed 100 support, a bifurcated arm on said top-liftcarrying device, a pivoted lever movable on said fixed support in the same direction as sald cross-head, a rod on sald lever registering with said bifurcated arm, and an arm ro- 105 tatable with said spanker-block and con-

nected with said lever.

7. In a heel-attaching machine, a jack for the boot or shee, a cross-head reciprocative relatively to said jack, a spanker-block rota- 110 tably mounted on sald cross-head and coöperating with said jack, a fixed support, a top-liftcarrying device pivoted to said fixed support, a bifurcated arm on said top-lift-carrying device, a pivoted lever movable on said 115 fixed support in the same direction as said cross - head, a rod on said lever registering with said bifurcated arm, an arm rotatable with said spanker-block and connected with said lever, a link pivoted to said rotatable 120 arm and having a loose connect on with said lever, and a spring connecting said link with said lever.

8. In a heel-attaching machine, a jack for the boot or shoe, a cross-head reciprocative 125 relatively to said jack, a hub rotatable on said cross-head, a block on said hub for carrying and attaching a loaded heel, a spanker-

block on said hub, a top-lift-carrying device pivoted to a fixed part of the machine, an arm on said hub, a link pivoted at one end to said arm, a pivoted lever connected with the other end of said link, a bifurcated arm on said top-lift-carrying device, and a rod on said lever and registering with said bifurcated arm.

In test mony whereof I have signed my name to this specification, in the presence of two subscribing witnesses, this 23d day of January, A.D. 1903.

ERASTUS WOODWARD.

Witnesses:

A. R. LARRABEE, A. L. MESSER.