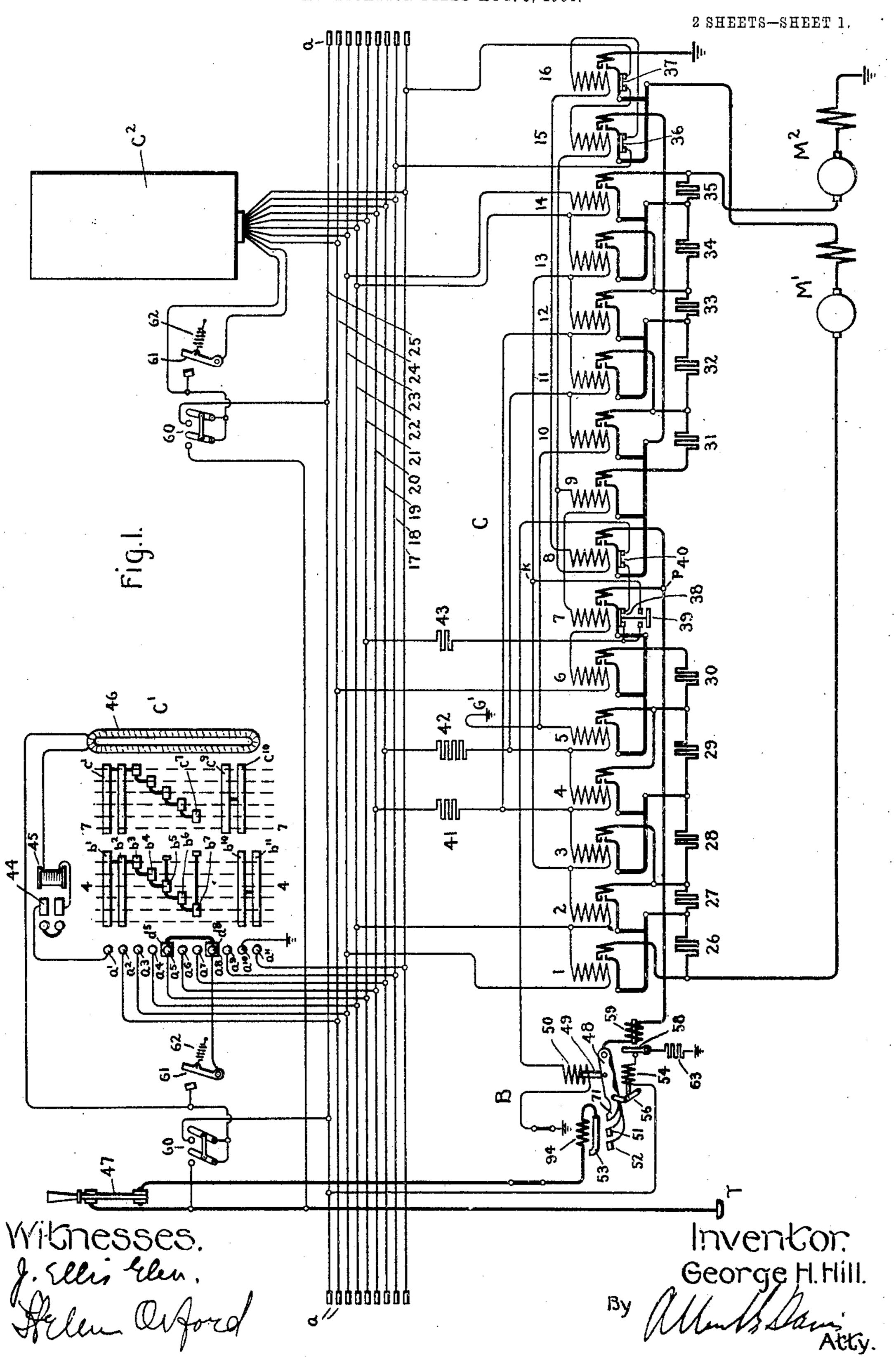
G. H. HILL.

MEANS FOR CONTROLLING CIRCUIT BREAKERS.

APPLICATION FILED AUG. 8, 1904.



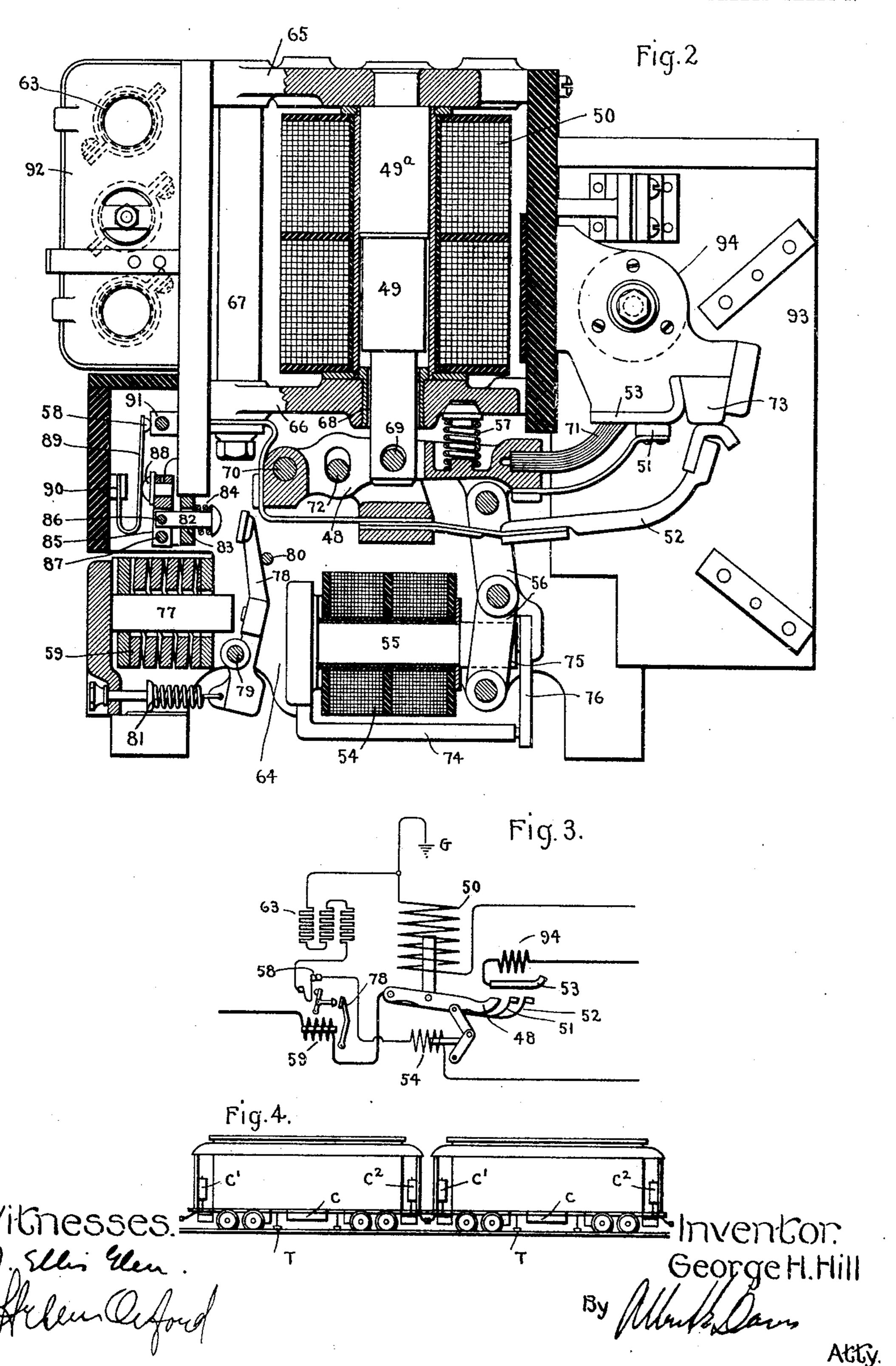
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## MEANS FOR CONTROLLING CIRCUIT BREAKERS.

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2 SHEETS—SHEET 2.



## UNITED STATES PATENT OFFICE.

GEORGE H. HILL, OF SCHENECTADY, NEW YORK, ASSIGNOR TO GENERAL ELECTRIC COMPANY, A CORPORATION OF NEW YORK.

## MEANS FOR CONTROLLING CIRCUIT-BREAKERS.

No. 801,238.

Specification of Letters Patent.

Patented Oct. 10, 1905.

Application filed August 8, 1904. Serial No. 219,864.

To all whom it may concern:

Be it known that I, George H. Hill, a citizen of the United States, residing at Schenectady, county of Schenectady, State of New York, have invented certain new and useful Improvements in Means for Controlling Circuit-Breakers, of which the following is a specification.

My invention relates to means for control-10 ling the operation of circuit-breakers, especially circuit-breakers of the type particularly adapted for use in systems of motor control.

In electrically-propelled railway-vehicles it has been customary to employ circuit-break-15 ers which automatically open the motor-circuit whenever the current in said circuit rises above a predetermined value. These circuitbreakers are usually mounted under the hoods of the vehicle-platforms or adjacent to the 20 controller within easy reach of the motorman, so that they can be reset by hand whenever they have operated. In motor-control systems as applied to electrically-propelled vehicles, and especially as applied to a plural-25 ity of electrically-propelled vehicles coupled together to form a train, there has been a tendency toward using larger and larger cars, which require considerable current to operate them. For the control of such heavy currents 30 the automatic circuit-breakers must necessarily be made large and bulky, and it is objectionable to have said circuit-breakers located in the motorman's cab or under the hood covering the platform. Furthermore, as it is not 35 advisable to employ a heavy bus-line or trainwire which will conduct the current for all the motors on the train through a single circuit-breaker located adjacent to the mastercontroller, from which the train is being at 40 the time controlled by the operator, separate circuit-breakers should be provided to take care of the overload in the motor-circuits of each of the cars constituting the train, and it would cause considerable trouble and annoy-45 ance to be obliged to reset each of said circuit-breakers by hand when they operate automatically.

The object of my invention is to produce an efficient circuit-breaker-control system which is especially applicable for use in connection with systems of train control and simple in operation, which permits the circuit-breaker to be located at any desired point on the car

or train adjacent to or remote from the controlling-point.

In carrying out my invention I employ a circuit-breaker provided with means adapted to be controlled from a distant point for setting it and also with normally energized means adapted to be controlled from a distant point 60 for holding said circuit-breaker set and for tripping it.

My invention also comprises means operatively related to the hand-operated controlling device or master-controller whereby unless 65 the master-controller is returned to its initial or "off" position or to such position that the motors will be properly protected by a resistance when the circuit-breaker is reset after it has operated the said circuit-breaker can-70 not be reset.

In the accompanying drawings, which illustrate the preferred embodiment of my invention, Figure 1 represents diagrammatically the equipment of a single car of a train-con-75 trol system using a motor-controller of the separately-actuated contact type and equipped with my invention. Fig. 2 is a vertical section through my preferred form of circuit-breaker. Fig. 3 is a diagram of the circuit-breaker connections on a larger scale, and Fig. 4 illustrates diagrammatically a train of two motor-cars equipped with my invention.

Referring now to Fig. 1, the separately- 85 actuated contacts 1 to 16, inclusive, of the motor-controller C are used for controlling the motors M' and M<sup>2</sup>. The said motor-controller C is under the control of the mastercontrollers C' and C<sup>2</sup>, which may be located 90 at any desired point on the car or train. The master-controller C' is shown in development, as is customary in illustrating such a structure, and the master-controller C<sup>2</sup> is merely shown in outline. Both of said master-con- 95 trollers are connected to the train-wires 17 to 25, inclusive, which are operatively connected to the actuating-coils of the separately-actuated contacts of the motor-controller. The said train-wires may be connected to corre- 100 sponding train-wires in adjacent cars of the train by means of the couplers a. The contacts 1 to 6, inclusive, operate to vary the amount of resistance which is connected in circuit with the motor M', the resistance-sec- 105 tions controlled by said contacts being repre-

sented by 26 to 30, inclusive. The contacts 7 and 8 represent the line-contacts which are adapted to connect the trolley or main source of power to the circuits leading to the motors 5 M' and M<sup>2</sup>. The contacts 9 and 14, inclusive, operate to vary the amount of resistance which is connected in circuit with the motor M<sup>2</sup>, the said resistance-sections controlled by said contacts being represented by 31 to 35, inclu-10 sive. The series and parallel contacts 15 and 16, respectively, are supplied with auxiliary switches 36 and 37, which respectively prevent the completion of the control-circuit through the actuating-coils of the contacts 16 15 and 15 and serve as an interlock between the series and parallel contacts. The line-contact 7 is provided with the auxiliary switches 38 and 39, and the line-contact 8 is provided with the auxiliary switch 40. The function and 20 operation of said auxiliary switches will be hereinafter described. The resistance-sections 41, 42, and 43 are employed to compensate for the resistance of the actuating-coils of the contacts of the motor-controller when said 25 coils are cut out of circuit, thereby maintaining approximately a uniform current in the control-circuits. The master-controller C' includes the relatively fixed contact - fingers a' to  $a^{11}$ , inclusive, and the movable con-30 tact-segments b' to b', inclusive,  $b^{10}$  and  $b^{11}$ , c' to c', c'', and c''. The movable member on which said segments are mounted also carries the contact-segments  $d^5$  and  $d^8$ , which are electrically connected together and re-35 spectively engage fingers  $a^5$  and  $a^8$  when the spring 57. The contact-arm 48 carries the 100 master-controller is in its off position. The auxiliary cut-out switch, which is adapted to open the motor-circuit automatically whenever the controlling-handle is released by the 40 motorman, is indicated at 44. A more detailed description of said auxiliary switch and its actuating mechanism may be obtained from Patent No. 750,947, granted February 2, 1904, on an application filed by Frank E. 45 Case. The blow-out coil for said auxiliary cut-out switch is indicated at 45, and 46 is the main blow-out coil of the master-controller. The main cut-out switch for the motor-circuit is indicated at 47. The contact-arm 48 of 50 the circuit-breaker B is attached to the core or plunger 49 of the actuating-solenoid 50. The said contact-arm comprises the brushcontact 71 and the auxiliary contacts 51 and 52, which, together with said brush-contact, 55 are adapted to engage the fixed contact 53. The blow-out coil for the said circuit-breaker is indicated at 94. The circuit-breaker is set by an energization of the actuating-coil 50 and is held set by means of the normally en-60 ergized holding-coil 54, the core of which is operatively connected to the toggle 56. The toggle 56 is not moved into straight line or buckled over center when the arm 48 is in its closed position. Therefore when the circuit 65 through the holding-coil 54 is broken either

at the switch 58, controlled by the overloadcoil 59, or at the hand-operated switch 60, located adjacent to the master-controller, the circuit-breaker is tripped, and the arm 48 moves to open the circuit by gravity, assisted, 70 if desired, by a spring or other mechanism. The circuit through the closing or setting coil, which is energized when it is desired to reset the circuit-breaker, is completed at the switch 61, held normally open by means of 75 the spring 62, and preferably located adjacent to the master-controller within easy reach of the operator or motorman. The resistance 63 is inserted in circuit with the holding-coil 54 for the purpose of cutting down the cur- 80 rent which flows through said coil, very little current being required to hold the circuitbreaker set after it has been set by the momentary energization of the actuating-coil 50.

Referring now to Fig. 2, it will be seen that 85 the circuit-breaker is mounted in a frame 64. The actuating-coil 50 is held in position between the heads 65 and 66, which are held firmly in the desired relative position by the rods 67 and are properly fastened in said 90 frame. Projecting into the coil 50 and rigidly attached to the upper head 65 is a fixed core 49<sup>a</sup>. The movable core 49 of said coil operates through an opening 68 in the lower head 66 and is pivoted to the contact-arm 48 95 at 69. The contact-arm 48 of the switch or circuit-breaker is pivoted to the frame 64 at 70 and is maintained normally in the open position by its own weight, assisted by the brush-contact 71 and the auxiliary contact 51, which are adapted to engage the fixed contact 53. The said arm also has loosely pivoted to it at the point 72 the long auxiliary spring contact-finger 52, which is adapted to 105 engage the carbon contact-block 73, carried by the fixed contact 53 and forming part thereof. The contact-finger 52 engages the block 73 before and leaves after the brush 71 makes and breaks contact with the fixed con- 110 tact 53, and thereby bears the limit of the are which tends to form when the circuitbreaker is tripped. The poles of the holdingmagnet are indicated by 74 and 75 and when the holding-coil 54 is energized act upon the 115 armature 76, carried by the upper toggle-link, to hold the toggle 56 in a position slightly removed from a straight line, as shown in Fig. 2. The pole 75 is an extension of the core 55, on which the coil 54 is mounted. The 120 overload-coil 59 when energized by current in the motor-circuit magnetizes the core 77 and attracts the armature 78, pivoted in the frame 64 at 79. The strength of current at which the overload-coil 59 is adapted to op- 125 erate to trip the circuit-breaker may be varied by adjusting the tension of the spring 81, which maintains the armature 78 normally in engagement with the stop 80. The upper end of the armature 78 is adapted to strike 130

the head of a bolt 82, reciprocally mounted in an opening 83 in the frame 64 and maintained in the position shown in Fig. 2 by means of the spring 84. Said bolt is pivoted at 86 to 5 the lever-arm 85, pivoted to the frame 64 at 87. The arm 85 carries at its upper end a button 88, which rests against the spring contact-finger 89, one end of which is rigidly fastened at 90 and the other end of which engages ro with the fixed contact 91. The resistance 63 is mounted in a frame 92, attached to the back of the frame 64. The contacts of the circuitbreaker operate in a blow-out chute 93, one of the side plates of which has been removed 15 to more clearly show the position of the con-

tacts and the blow-out coil 94. In the operation of the system when it is desired to set the circuit-breaker the mastercontroller C' is moved into its off position. 20 Then the normally open switch 61 is closed momentarily and the switch 60 is closed permanently. A circuit is thereby completed from the trolley T through the switch 60, thence through the switch 61 to contact-finger  $a^8$ , 25 thence through the contact-segments  $d^{s}$  and  $d^5$ , contact  $a^5$ , train-wire 21, resistance 43, auxiliary switch 38, auxiliary switch 40, through the actuating-coil 50 of the circuitbreaker to ground. The coil 50 is thus ener-30 gized and the circuit-breaker is closed, being maintained in its closed position by the normally energized holding-coil 54, the circuit through which is controlled by the switch 60 and may be traced as follows: from trolley T 35 through switch 60, train-wire 25, coil 54, switch 58, resistance 63 to ground. It will thus be seen that on account of the auxiliary switches 38 and 40, carried by the line-contacts 7 and 8 and the auxiliary contact-segments in 40 the master-controller the motor-controller and master-controller must be in their off position before the circuit through the settingcoil of the circuit-breaker can be completed. When the master-controller is moved into its 45 first operative position, a control-circuit is completed from the trolley through the switch 60, blow-out coil 46, blow-out coil 45, cut-out switch 44, contact-finger a', contact-segments b' and  $b^2$ , contact-finger  $a^2$ , train-wire 24, ac-5° tuating-coils of the contacts 6, 7, 9, and 15, auxiliary switch 37, train-wire 17, contactfinger  $a^{11}$ , contact-segments  $b^{11}$  and  $b^{10}$ , contactfinger  $a^{10}$  to ground. The motor-controller contacts are operated to connect the motors 55 in series with all the resistance, and the circuit through said motors may be traced as | be seen that the motors are connected in parfollows: from trolley T, main cut-out switch 47, blow-out coil 94 of the circuit-breaker, contact 53, contact-arm 48, overload-coil 59, 60 contact 7 of the motor-controller, thence through contact 6 of said controller to the resistance-sections 30 29 28 27 26, motor M', contact 15, thence through contact 9 of said controller through the resistance-sections 31,

65 32, 33, 34, and 35, through motor M<sup>2</sup> to ground.

As the master-controller moves through its subsequent operative positions the resistancesections are successively cut out of the motorcircuit until the motors are connected in series without resistance, then the motors are 7° connected in parallel with resistance in circuit with each motor, and the resistance-sections are successively cut out until the motors are connected in parallel without resistance. When the contact 7 is operated, the circuit 75 through the actuating-coil 50 of the circuitbreaker is broken at the auxiliary switch 38, thereby disconnecting the train-conductor 21 from the core 50 and rendering it impossible to reset the circuit-breaker after it has been 80 operated, so long as the contact 7 remains in its closed position; but by employing means such as the auxiliary switch 39 it is possible to use the train-conductor 21 during the acceleration of the motors to control the contacts 85 of the motor-controller corresponding to a certain resistance-step. Thus with the mastercontroller in its fourth position (indicated by 4 4) the control-circuit, in addition to that above traced, may be traced as follows: from 9° contact-finger a', contact-segments b' and  $b^5$ , contact-finger  $a^5$ , train-wire 21, resistance 43, auxiliary switch 39, through the actuatingcoils of the contacts 3, 4, and 5 to ground at G', also branching at the point k, through the 95 actuating-coils of the contacts 12, 11, and 10 to ground at G'. Thus in said position of the master-controller the contacts 3, 4, 5, 6, 7, 9, 10, 11, 12, and 15 are operated, and the resistance-sections 28, 29, 30, 31, 32, and 33 100 are short-circuited.

The control-circuit corresponding to the first parallel position of the master-controller (indicated by 7 7) may be traced as follows: from trolley T, switch 60, coils 46 and 45, 105 cut-out switch 44, contact-finger a', contactsegments c' and  $c^2$ , contact-finger  $a^2$ , trainwire 24, actuating-coils of contacts 6, 7, 9, 8, and 16 of the motor-controller, auxiliary switch 36, train-wire 18, contact-finger a of 110 the master-controller C', contact-segments  $c^9$ and  $c^{10}$ , contact-finger  $a^{10}$  to ground. The corresponding motor-circuits are as follows: from trolley T through the switch 47, the circuit-breaker arm 48, overload-coil 59, con-115 tact 7, contact 6, resistance-sections 30, 29, 28, 27, and 26, motor M', contact 16 to ground, also branching at the point p through the contact 8, contact 9, resistance-sections 31 to 35, inclusive, motor M2 to ground. It will thus 120 allel with each other with the resistance-sections 26 to 30, inclusive, connected in series with the motor M', and the resistance-sections 31 to 35, inclusive, connected in series with 125 the motor M<sup>2</sup>. If while the master-controller is in any one of its operative positions the circuit-breaker is tripped, either intentionally, as by the opening of switch 60, or automatically, by the operation of the over-130

load-coil 59, or due to a loss of current in the motor-circuit, it is impossible to reset said circuit-breaker without first moving the master-controller C' back to its off position, so as 5 to bridge the contact-fingers  $a^5$  and  $a^8$ . Any desired number of circuit-breakers may be controlled in this manner from any desired master-controller.

Referring now to Fig. 3, which illustrates 10 diagrammatically, on a larger scale, the circuit connections of the circuit-breaker, the motorcircuit is as follows: through the blow-out coil 94, fixed contact 53, contact-arm 48, and overload-coil 59. The actuating-circuit passes 15 through the actuating-coil 50 and thence to ground at G. The holding-circuit passes through the holding-coil 54, switch 58, and resistance 63 to ground at G.

I do not claim, broadly, means for con-20 trolling the circuit-breaker from a distance nor the arrangement of motor-control apparatus which permits one of the controlconductors to be used for setting the circuitbreaker and which makes the operation of the 25 setting means of the circuit-breaker dependent upon the position of the motor-controller, since these, among other features, form the subject-matter of an application of Frank E. Case, filed July 21, 1904, Serial No. 215,114. 3° Neither do I claim the structural details of

the circuit-breaker contact, since the mechanical construction of the circuit-breaker forms, among other features, the subject-matter of an application of Samuel B. Stewart, Jr., filed 35 March 20, 1905, Serial No. 250,895.

Although I have herein shown a specific form of circuit-breaker embodying my invention as applied to an electric control system, I do not care to be limited thereto, as many 4° modifications may be made and other actuating and controlling power may be substituted for that shown without involving a departure from the spirit and scope of my invention, and in the claims hereto appended I aim to 45 cover all such modifications and substitutions.

What I claim as new, and desire to secure by Letters Patent of the United States, is—

1. In combination, a circuit-breaker, means adapted to be controlled from a distance for 5° setting said circuit-breaker, and normally energized means for holding said circuit-breaker set.

2. In combination, a circuit-breaker, means adapted to be controlled from a distance for 55 setting said circuit-breaker, normally energized means for holding said circuit-breaker set, and means located at a distance for deenergizing said holding means to trip said circuit-breaker.

3. In combination, a circuit-breaker, a coil for setting said circuit-breaker, and a normally energized coil for holding said circuitbreaker set.

4. In combination, a circuit-breaker, a coil 65 for setting said circuit-breaker, a normally energized coil for holding said circuit-breaker set, and a switch located at a distance for deenergizing said holding-coil to trip the said circuit-breaker.

5. In combination, an electric circuit, a cir- 70 cuit-breaker therein, a coil for setting said circuit-breaker, a normally energized coil for holding said circuit-breaker set, and means controlled by current in said circuit for deenergizing the holding-coil to trip said cir- 75 cuit-breaker.

6. In a circuit-breaker, means for setting the circuit-breaker, means for controlling the operation of said circuit-breaker-setting means from a distant point, a holding-coil for 80 maintaining said circuit-breaker in its set position, and an overload-coil adapted to open the circuit through the holding-coil to permit the circuit-breaker to open.

7. In a circuit-breaker, means for setting 85 the circuit-breaker, means for controlling the operation of said circuit - breaker - setting means from a distant point, a holding-coil for maintaining said circuit-breaker in its set position, an overload-coil adapted to open the go circuit through the holding-coil to trip the circuit-breaker, and a switch in circuit with the holding-coil and located at a distant point for opening the circuit through said holdingcoil to trip the circuit-breaker independent of 95 the overload-coil.

8. In combination, a circuit-breaker, a coil for setting said circuit-breaker, a switch for completing the circuit through said settingcoil, a holding-coil for maintaining said cir- 100 cuit-breaker set, an overload-coil adapted to open the circuit through the holding-coil to trip the circuit-breaker, and a switch located at a distant point for opening the circuit through said holding-coil to trip the circuit- 105 breaker independent of the operation of the overload-coil.

9. In a system of motor control, a motorcircuit, a motor-controller, a master-controller, a circuit-breaker, means for setting said 110 circuit-breaker, and means for rendering said setting means inoperative when the mastercontroller is in any of its operative positions.

10. In a motor-control system, a motor-circuit, a motor-controller for the motor or mo- 115 tors in said circuit, a master-controller for said motor-controller, a circuit-breaker in said motor-circuit, means for setting said circuitbreaker, means for controlling the operation of said circuit-breaker-setting means, and 120 means for preventing the setting of said circuit-breaker unless the master-controller is in its "off" position.

11. In a motor-control system, a motor-circuit, a motor-controller in said circuit, a mas- 125 ter-controller, a circuit-breaker in said motor-circuit, means for setting said circuitbreaker, means for controlling the operation of said circuit-breaker-setting means, and means for preventing the setting of said cir- 130

cuit-breaker unless the motor-controller and master-controller are both in the "off" position.

12. In a motor-control system, a motor-con-5 troller of the separately-actuated-contact type, a master-controller, a circuit-breaker in the motor-circuit, setting means for said circuitbreaker, a plurality of conductors connecting the actuating means of the motor-controller 10 contacts to the master-controller, auxiliary means attached to certain of said motor-controller contacts for connecting one of said conductors to the circuit-breaker-setting means when said motor-controller contacts are open 15 and for connecting it to the actuating means of a motor-controller contact when said firstmentioned motor-controller contacts are closed, and means operatively connected to the master-controller whereby the circuit-20 breaker is prevented from being set when the motor-controller contacts are open unless the master-controller is in its "off" position.

13. In a train-control system, a plurality of motor-controllers, a master-controller, a plu25 rality of circuit-breakers, means for setting said circuit-breakers, means for holding said circuit-breakers set, and means independent of the master-controller for controlling said holding means so that said circuit-breakers
30 may be maintained set independently of the

position of the master-controller and may be tripped at will.

14. In a train-control system, a plurality of motor-controllers, a master-controller, a plurality of circuit-breakers, a holding-coil for 35 each circuit-breaker, a train-conductor to

which said holding-coils are all connected, and means independent of the master-controller for controlling said train-conductor so that the circuit-breakers may be maintained set 40 independent of the position of the master controller.

independent of the position of the master-controller and may be tripped at will.

15. In a train-control system, a plurality of motor-circuits, a plurality of motor-controllers for controlling the motor or motors in 45 said circuits, a master-controller for said motor-controllers, a circuit-breaker in each of said motor-circuits, means for setting each circuit-breaker, means separate from said master-controller for controlling the operation of 50 said setting means, and means for preventing the setting of said circuit-breakers unless the master-controller is in its "off" position.

In witness whereof I hereunto have set my

hand this 5th day of August, 1904.

GEORGE H. HILL.

Witnesses:

BENJAMIN B. HULL, HELEN ORFORD.