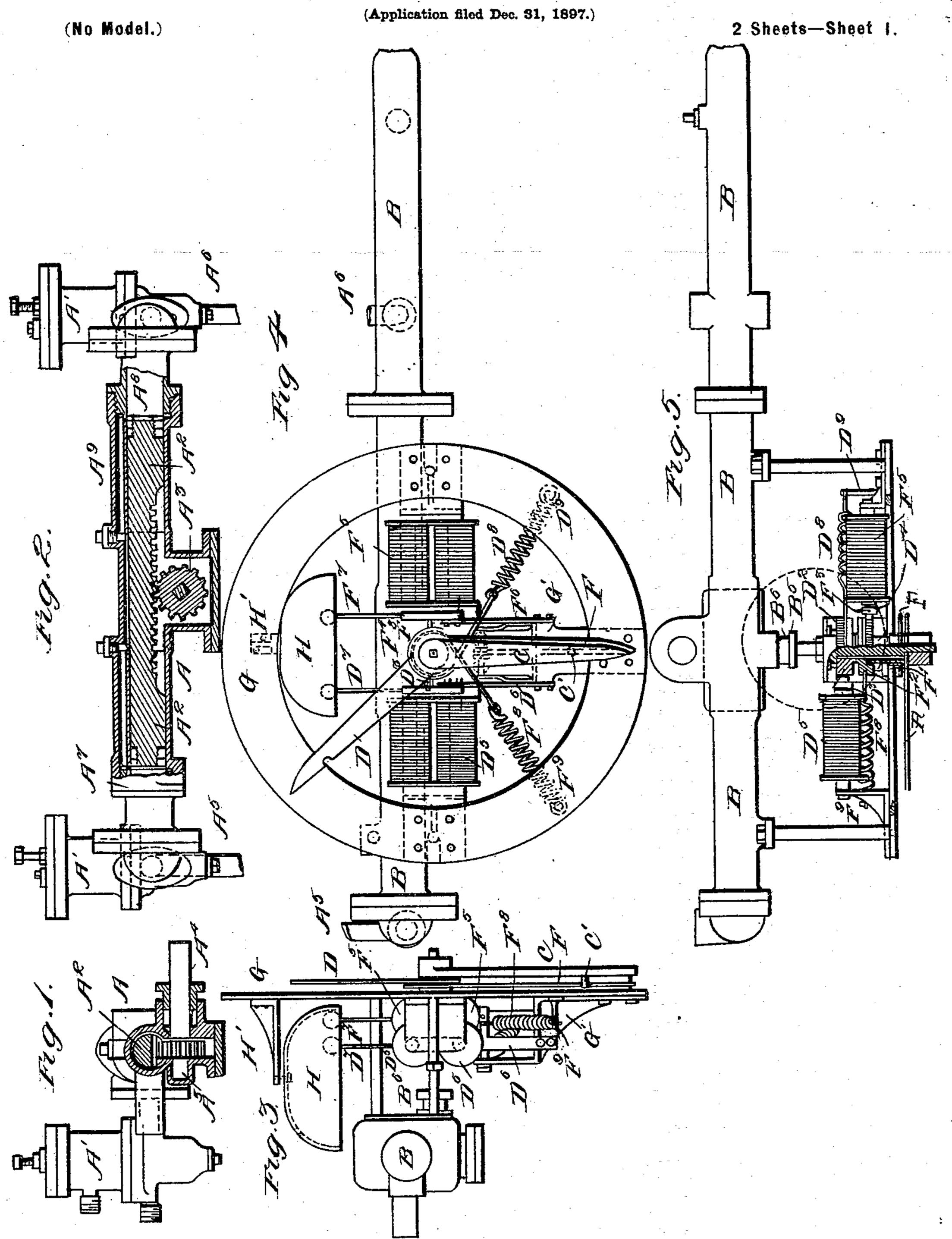
## A. B. BROWN.

TELEMOTOR APPARATUS.



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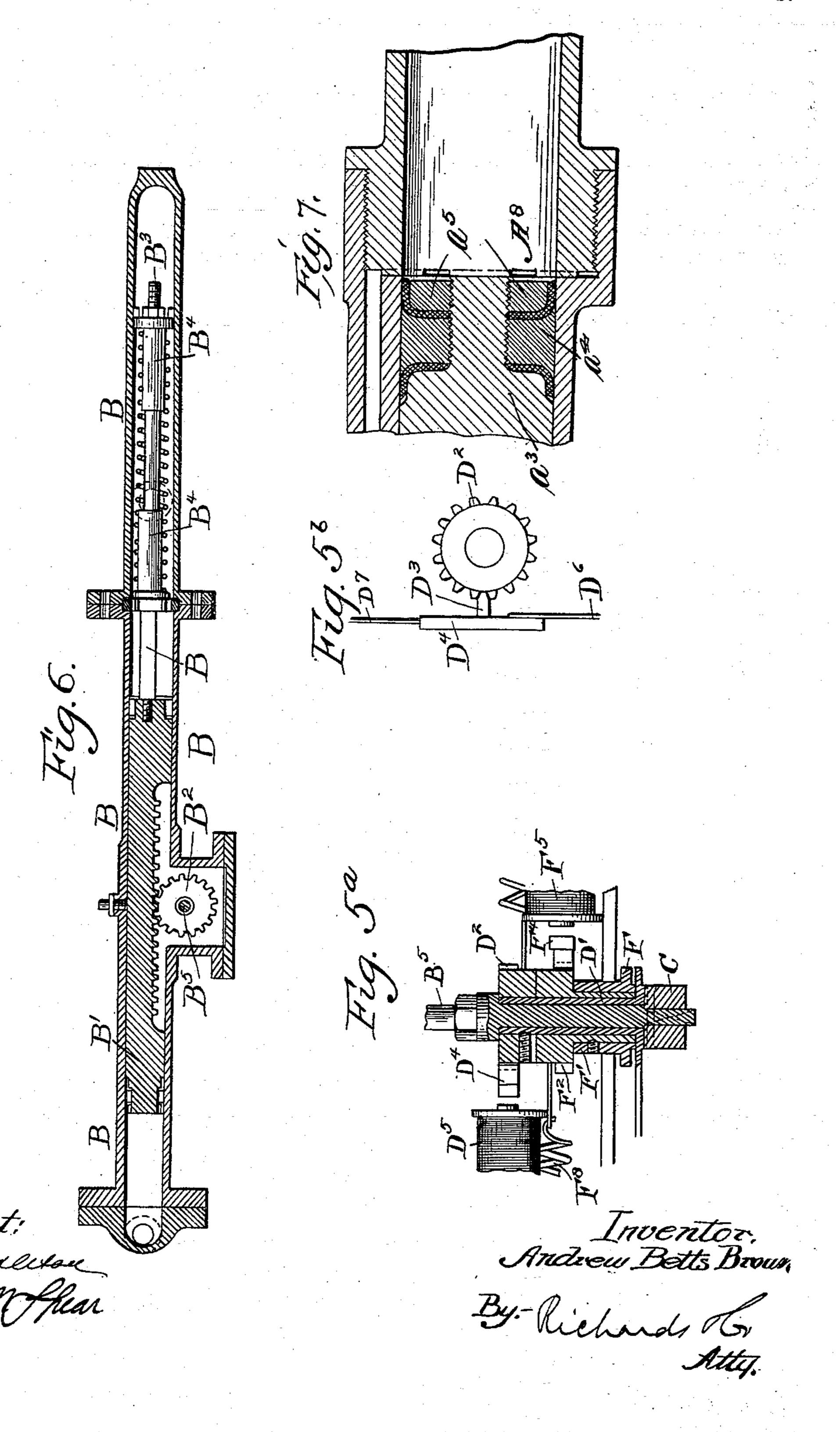
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(No Model.)

(Application filed Dec. 31, 1897.)

2 Sheets—Sheet 2.



## United States Patent Office.

ANDREW BETTS BROWN, OF EDINBURGH, SCOTLAND.

## TELEMOTOR APPARATUS.

SPECIFICATION forming part of Letters Patent No. 637,705, dated November 21, 1899.

Application filed December 31, 1897. Serial No. 664,801. (No model.)

To all whom it may concern:

Beit known that I, ANDREW BETTS BROWN, of Edinburgh, in the county of Mid-Lothian, Scotland, have invented certain new and useful Improvements in Signaling Apparatus, of

which the following is a specification.

My said invention relates to telemotor or signaling apparatus in which movements are transmitted by means of water or other liquids in pipes arranged between the points of transmission and reception in whatever manner may be most convenient in each case, exact correspondence between the transmitting and receiving parts being secured by causing the two pipes through which opposite movements are transmitted to communicate with each other, and thereby have the pressure in them equalized whenever the parts are in their middle positions.

apparatus of this nature having devices for indicating a transmitted movement and retaining the indication until certain other movements are transmitted, the invention being designed more especially for conveying signals from the bridge or corresponding part

of a vessel to the engine-room.

The invention is illustrated in the accom-

panying drawings, in which-

30 Figure 1 of the drawings is a transverse vertical section, and Fig. 2 is a longitudinal vertical section, of the transmitting part of the hydraulic telemotor. Fig. 3 is a side elevation, Fig. 4 a front elevation, and Fig. 5 a 35 sectional plan, of the receiving and indicating parts of the hydraulic telemotor. Fig. 5<sup>a</sup> is an enlarged detail view of the central portion of Fig. 5. Fig. 5<sup>b</sup> is a detail of one of the wheels, as D<sup>2</sup>, and the corresponding arma-40 ture. Fig. 6 is a longitudinal vertical section of the receiving part of the hydraulic telemotor drawn to a slightly-larger scale. Fig. 7 is an enlarged sectional view of one end of the transmitting cylinder and piston and 45 showing more clearly the by-pass.

In the drawings the same reference-letters are used to mark the same or like parts when-

ever they are repeated.

The transmitting part of the hydraulic tele-50 motor (shown in Figs. 1 and 2) consists of a hydraulic cylinder A, provided at each end with a casing A', containing a safety-valve to

allow for excess of pressure. The cylinder A contains a piston A<sup>2</sup>, formed with transverse rack-teeth which gear with a pinion A<sup>3</sup>, fas- 55 tened on a spindle A4, turned by a suitable handle. (Not shown.) The cylinder A is connected by pipes A<sup>5</sup> and A<sup>6</sup> to the receiving part of the hydraulic telemotor and the system is filled with glycerin, oil, or other liquid. 60 The receiving part of the hydraulic telemotor consists of a hydraulic cylinder B, similar to the transmitting-cylinder A and containing a similar piston B' and pinion B2. The piston B' has a rod B<sup>3</sup> extending from it and in- 65 closed by an extension of the cylinder B, this rod having encircling it a spring B4, which is arranged to make the piston B' tend to return to its middle or neutral position. The pinion B<sup>2</sup> is fastened on a spindle B<sup>5</sup>, which projects 70 out through a stuffing-box B6, and has on its outer end a radial arm C. When the transmitting-piston  $A^2$  is moved, the receiving-piston B' is correspondingly moved by the displaced liquid and by means of its rack-teeth the pin- 75 ion B<sup>2</sup> and the spindle B<sup>5</sup>, carrying the radial arm C. On the radial arm C there is fixed a pin C', which acts on one or other of two radial arms or pointers D and F, fixed on bosses or sleeves D' and F', which are loose on the 80 spindle B<sup>5</sup>. One of the pointer-arms D or F is acted on for ahead orders and the other for astern orders, each remaining at rest when the other is moved. On the boss of each pointerarm D F there is a toothed wheel D<sup>2</sup> F<sup>2</sup>, with 85 which there engages a catch D<sup>3</sup> F<sup>3</sup>, held by the armature D<sup>4</sup> F<sup>4</sup> of an electromagnet D<sup>5</sup> F<sup>5</sup>. and when either pointer-arm is moved to a position, such as that in which the pointer D is shown in Fig. 4, indicating on a dial G the 90 order transmitted it is retained there by the catch D<sup>3</sup> F<sup>3</sup>, while the spindle-arm C may return to its middle or neutral position, in which it is shown in Fig. 4. When the spindle-arm C is in the position referred to, a 95 communication becomes open between the two telemotor-pipes A<sup>5</sup> and A<sup>6</sup> by means of the openings A<sup>7</sup> and A<sup>8</sup> and the by-pass A<sup>9</sup> in the transmitting-chamber A, this communication being arranged to be open when the 100 spindle-arm is at any point within a suitable distance on each side of the middle point, but to be closed by the passage of the ends of the piston beyond the openings or ports A7 and

A8. The ends of the piston are preferably provided with packing-disks a³, secured by nuts  $a^4$  and  $a^5$ . By this arrangement the tubes  $A^5$ and A<sup>6</sup> are in communication, and in fact the 5 whole system when said spindle-arm Cisin approximately its neutral position. The reason for this is to counteract any possible leakage of liquid passing the pistons, and thereby allowing the one hydraulic piston A2 to become out 10 of "position" or correspondence with the other hydraulic piston B2, and thereby giving a false reading in the receiver-dial. For example, suppose A2 be in the position to establish the communication referred to and B2 had 15 leaked and was out of the neutral position, giving a reading on the dial, then the correcting-spring fitted to the end of piston being in compression in one direction or the other will be able to push B2 back to its neutral position 20 also on account of a free communication being made throughout the hydraulic system. Hence it will be seen that the whole system cannot get out of adjustment, as it will autotomatically adjust itself so long as the piston 25 A<sup>2</sup> shall occasionally be returned to its neutral position, uncovering the by-pass openings at both ends of the cylinder A. The armatures D<sup>4</sup> F<sup>4</sup>, to which the catches D<sup>3</sup> F<sup>3</sup> are fixed, are held by spring-blades D6 and F6, 30 attached to a small bracket G' on the dial G, and the spring-blades have also clappers D7 F<sup>7</sup>, arranged to act on a bell H, attached to a small bracket H' on the upper part of the dial. When either pointer-arm DF is moved 35 from the neutral position, the action of its toothed wheel D<sup>2</sup> F<sup>2</sup> on the catch D<sup>3</sup> F<sup>3</sup> causes the armature D4 F4 to reciprocate and its clapper D' F' to strike the bell H. On the engineer noticing and attending to an order he 40 transmits a suitable reply to the apparatus at the bridge by separate means provided for the purpose, and thereafter the spindle of the engine-room apparatus becomes free to return to its middle position. When the spin-45 dle B<sup>5</sup> is in the middle position into which it has to be moved by means of the transmittingpiston A<sup>2</sup>, which is actuated by hand, a piece (not shown) on it or its arm C makes contact in the electric circuit, which excites the elec-50 tromagnets D<sup>5</sup> F<sup>5</sup>, the armatures D<sup>4</sup> F<sup>4</sup> of which are thereby made to reciprocate. Each pointer-arm boss D' F' is connected to a spring D<sup>8</sup> F<sup>8</sup>, attached to studs D<sup>9</sup> F<sup>9</sup>, fixed in the dial G, the spring being arranged to turn 55 the arm back to the neutral position when not held by the catch D<sup>3</sup> F<sup>4</sup>, and as each reciprocation of the armature D4 F4 withdraws the catch the arm turns back step by step until it reaches the neutral position. 60 Instead of employing electromagnets D<sup>5</sup> F<sup>5</sup>

to withdraw the catches D<sup>8</sup> F<sup>8</sup> and ring the

bell H while doing so any suitable mechan-

ical devices may be used. Thus a wire or

other rope or cord led from the bridge to the

to take up slack may be arranged to act on

toggle-levers connected to the catches, so

65 engine-room and there connected to a spring

that they will be moved apart when the rope or cord is pulled, the same or other levers also acting on the bell-clapper.

I claim as my invention—

1. In combination, the transmitting and receiving cylinders and pistons with fluid-pipes connecting said cylinders, the rotary shaft

1. In combination, the transmitting and receiving cylinders and pistons with fluid-pipes connecting said cylinders, the rotary shaft operated by the receiving-piston, the dial, the 75 independently-movable indicating-arms and means carried by the shaft for operating one or the other of said pointers, substantially as described.

2. In combination, the transmitting and receiving cylinders and pistons with fluid-pipes connecting said cylinders, the rotary shaft operated by said receiving-piston, the dial, the independent indicating-arms, means whereby the rotation of the shaft will move 85 one or the other of the arms according to the direction of rotation, and means for temporarily retaining the indicating-arm in its indicating position, substantially as described.

3. In combination, the transmitting and receiving cylinders and pistons, with fluid-pipes
connecting said cylinders, the rotary shaft
operated by the receiving-piston, the dial, the
independently-movable indicating-arms located in proximity to said dial, the projection
carried by the shaft adapted to move one or
the other of the indicating-arms according to
the direction of rotation of the shaft, and
means operated independent of the rotation
of the shaft for returning the moved indicatioo
ing-arm to normal position, substantially as
described.

4. In combination, the transmitting and receiving cylinders with operating connections, the rotary shaft operated by the receiving-piston, the dial, the indicating-arms loosely mounted on the shaft, the projection carried by said shaft adapted to move one or the other of the indicating-arms according to the direction of rotation, the alarm, means for causing the movement of the arms to sound the alarm, means for retaining each indicating-arm when operated in its indicating position, and means for returning indicating-arms to normal position, substantially as described.

5. In combination, the transmitting cylinders and pistons, the rotary shaft operated by the receiving-piston, the dial, the independent indicating-arms loosely mounted on the shaft, the projection carried by the shaft adapted to move one or the other of the arms according to the direction of rotation, means tending to restore said arms to normal position, toothed wheels carried by the arms, spring-pawls adapted to engage said toothed wheels to hold the arms in indicating position, and means for moving said pawls to release the wheels, substantially as described.

6. In combination, the transmitting cylinders and pistons, the rotary shaft operated 130 by the receiving-piston, the dial, the independent indicating-arms loosely mounted on the shaft, the projection carried by the shaft adapted to move one or the other of the arms

according to the direction of rotation, means tending to restore said arms to normal position, toothed wheels carried by the arms, an alarm-bell, spring-arms carrying bell-clap-5 pers, pawls on the spring-arms adapted to be operated by the movement of the toothed wheels to sound an alarm and also adapted to retain the toothed wheels in their moved positions, armatures carried by the spring-10 arms, and electromagnets for attracting the armatures to release the toothed wheels to allow the indicating-arms to return to normal position, substantially as described.

7. In combination, the transmitting cylin-15 der and piston, the rotary and longitudinallymovable shaft adapted to be rotated by said receiving-piston, the dial, the indicating-arms loosely carried by the shaft, a projection hav-

ing a connection with the shaft and adapted to move one or other of the arms according 20 to the direction of rotation of the shaft, pawls connected with the indicating-arms, a piece carried by the shaft adapted to engage said pawls to hold the arms in indicating position, and means for moving said shaft longitudi- 25 nally to release the arms and permit them to return to normal position, substantially as described.

In testimony whereof I have signed my name to this specification in the presence of 30 two subscribing witnesses.

ANDREW BETTS BROWN. [L. S.]

Witnesses: GEORGE COBB, FREDERICK PIATT.