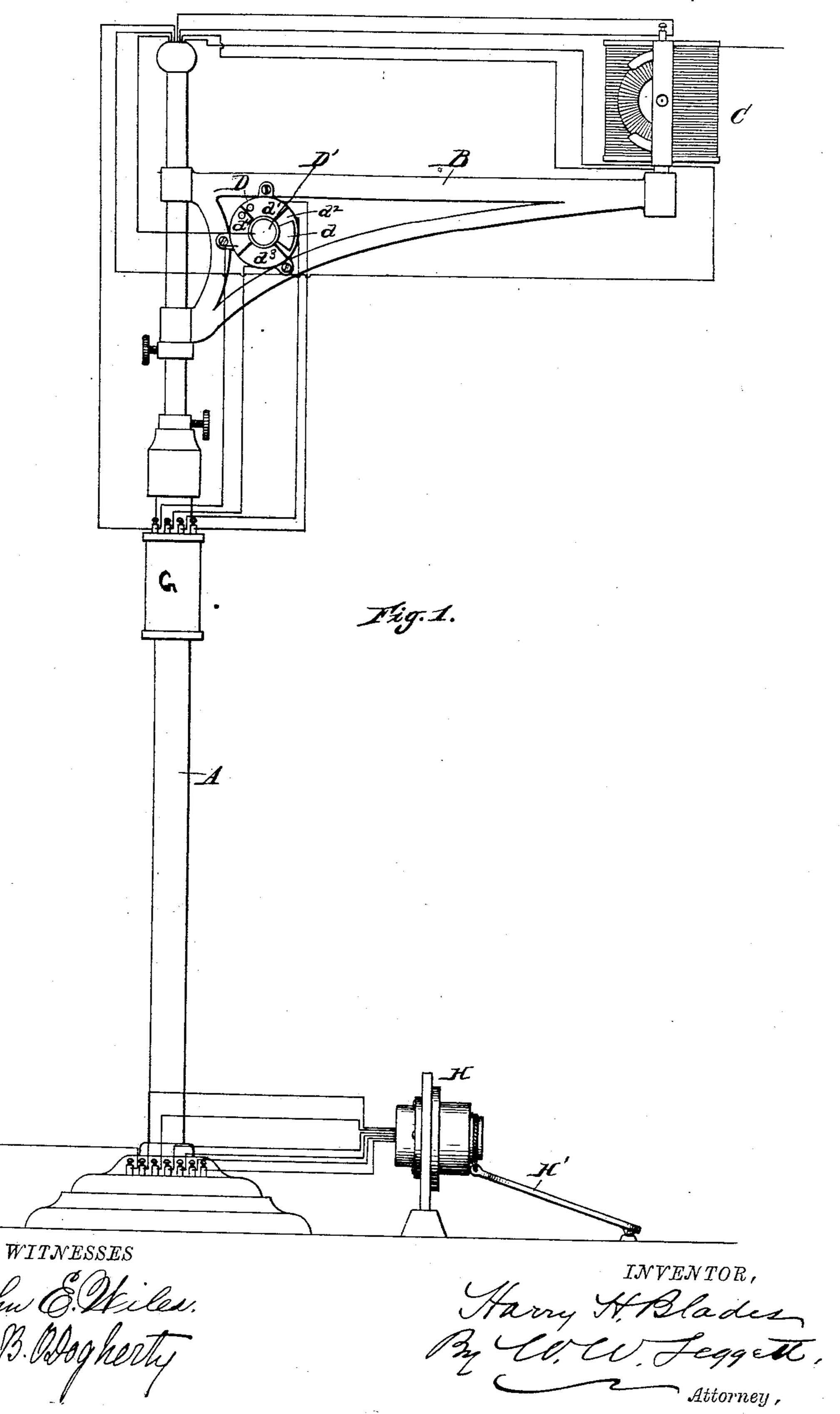
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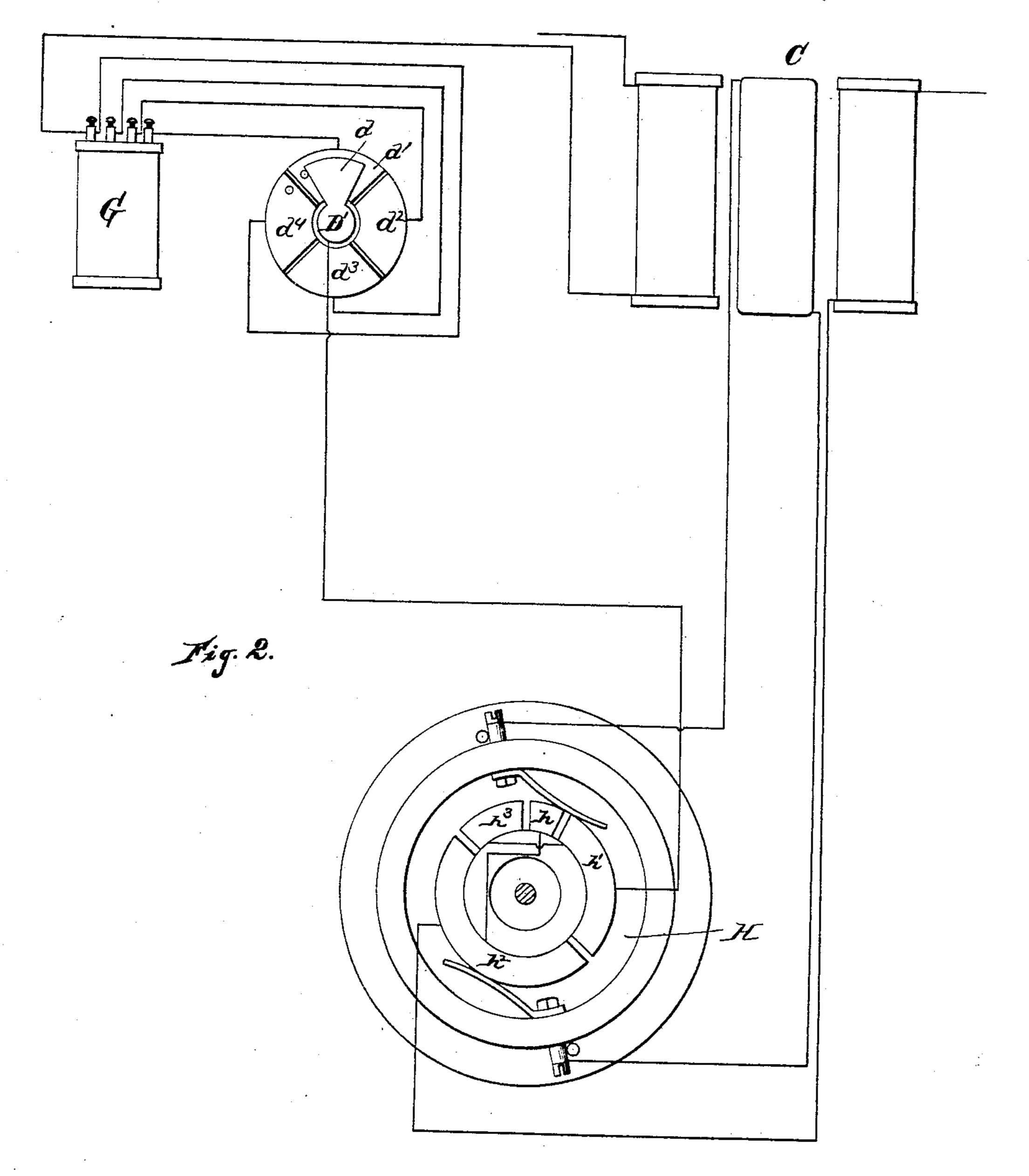


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John E. Wiles. Th. B. Maghert Harry HBlades
By WWW Jegged

Attorney.

## United States Patent Office.

HARRY H. BLADES, OF DETROIT, MICHIGAN.

## DEVICE FOR CONTROLLING ELECTRIC MOTORS.

SPECIFICATION forming part of Letters Patent No. 396,725, dated January 29, 1889.

Application filed March 23, 1888. Serial No. 268, 223. (No model.)

To all whom it may concern:

troit, county of Wayne, State of Michigan, 5 have invented certain new and useful Improvements in Switch Mechanism for Electric Motors; and I declare the following to be a full, clear, and exact description of the invention, such as will enable others skilled 10 in the art to which it appertains to make and | use the same, reference being had to the accompanying drawings, which form a part of this specification.

In the drawings, Figure 1 is a view in ele-15 vation of a dental motor and its stand with my improvements attached. Fig. 2 is a separate diagrammatic view of the mechanism for

starting, reversing, and stopping.

It is the purpose of my invention to com-20 bine, with an electric motor, mechanism to be operated by hand for regulating the amount | several contacts, d',  $d^2$ ,  $d^3$ , &c. d' is so conof the current, and through that the speed of the motor, and in connection therewith mechanism to be operated by the foot for start-25 ing, reversing, and stopping the motor.

The drawings are made diagrammatic in form to show the different circuits; but it will of course be understood that the wires will in use be trained either within or upon the stand

30 which supports the motor.

In carrying out my invention, A represents the upright of the motor-stand. B is its bracket-arm, which supports the motor C.

D is a switch mechanism operated by hand, 35 and it has several terminals so connected with a resistance-regulator, G, that by adjusting the switch into one position a large resistance will be thrown into the motor-circuit and a correspondingly small amount of current be 40 deflected through the motor, giving to it a low rate of speed; or by adjusting the switch to another set of terminals a smaller resistance 45 rected through the machine, resulting in tact  $h^2$ , is so connected with the motor as to greater speed.

H is a switch at the floor, adapted for op- the motion of the motor. eration by a foot-treadle, H'. This switch is I t is quite essential in some systems that 100

serve to turn on the current through both Be it known that I, Harry H. Blades, a lifelds and armature, and so start the machine. citizen of the United States, residing at De-| By further depressions of the treadle the 55 switch is connected with another set of terminals, which operate to reverse the current through the machine, thus reversing its motion. Having started the machine, by first depressing the treadle, if he desires to stop 60 the machine instantly when at full speed, the operator by simply pressing with his foot farther down first reverses the current while at its maximum, which operates as a powerful brake, and by then releasing his foot the switch 65 instantly resumes its normal position and short-circuits the fields or armature.

I will now describe more definitely the particular construction of the switches which accomplish these results. The switch D is of 70 any usual type—as, for instance, the sweep or lever d is arranged to travel past and engage nected with the resistance-regulator that when the switch-lever is upon it the current on the 75 motor-line is compelled to travel through the highest resistance, thus admitting a correspondingly small current through the motor. The next contact,  $d^2$ , is so arranged and connected with the resistance-regulator that when So the switch-lever rests upon this contact the current in the motor-line is obliged to travel through a smaller resistance, thus deflecting a greater current through the motor, and so on. The switch-lever is provided with any suitable 85 handle, D', whereby it may be operated by hand. The switch H may likewise be of any convenient construction. Thus, for instance, it may be provided with a contact, h, so arranged that when the switch-lever is upon it 90 the current is short-circuited through the field-magnets or armature, leaving the machine inert. Next in order are contacts  $h' h^2$ , which operate to direct the current through may be thrown into the main circuit and a | both the fields and armature. Following this 95 correspondingly larger amount of current di- $\dagger$  is a contact,  $h^{a}$ , which, in connection with conreverse the current, and so operate to reverse

provided with a series of terminals, the first | the resistance on the main line be altered as 50 in the order of its operation serving to short- little as possible, in order to prevent too great circuit either the fields or the armature, thus | a disturbance at other points upon the line holding the machine inert. The next terminals | where the current is to be utilized. It is for

this reason that the said contacts h are arranged to cut out either the field-magnets or the armature, but not both. This arrangement, whereby the resistance is regulated by 5 hand, while the starting, reversing, and stopping are effected by the foot, may be exactly reversed, if desired, so that the resistance may be regulated by foot and the current be turned on or reversed or cut off by hand. This con-10 struction is a very convenient one for a great many purposes—as, for instance, with dental motors, where it is desirable to first adjust the regulator by hand to yield a suitable speed or power, and then to control the direct motion, the reversal, or instant stopping of the motor by the foot while both hands may be employed. It, moreover, enables the operator, while he governs the direction of the current and its application by foot, to instantly adjust 20 his speed by hand and maintain it precisely at that point—a matter which would be quite inconvenient to accomplish with accuracy by the foot when operating upon a patient or when doing other work with his hands. This 25 is equally well adapted for any of the large variety of similar tools which are operated by electric motors—as, for instance, sewing-machines, fret-saws, jewelers' lathes, &c.

The foregoing has been described and the 30 claims framed on the supposition that the current employed is the incandescent current and the resistance-regulator connected in series with the motor. If, however, the arc current is employed, or any other current which 35 renders it desirable to employ the resistanceregulator in the main line to shunt more or less current through the motor, the switches and contacts may be adjusted therefor. In that event the switch D would be so arranged 40 that as its lever is turned the resistance thrown into the main current would be increased from contact to contact, and so shunt a correspondingly greater current each time through the motor, and the switch H might 45 have its contacts so arranged that the first set would turn on the current, the next reverse the current, and the last short-circuit the armature or field-magnets, and I would have the claims construed to embrace as equivalent 50 constructions such changes, as above indicated, as would be necessary simply to adapt the apparatus to an arc-circuit or shunt-connected mechanism.

What I claim is—

1. The combination, with an electric motor, 55 of a switch mechanism governing a current-regulator and another switch mechanism whereby the current may be short-circuited around the field magnets or armature, turned on through both, or reversed, one of said 60 switches adapted to be operated by the hand and the other by the foot, substantially as and for the purposes described.

2. The combination, with an electric motor, of a switch connected with a resistance-regu- 65 lator for governing the amount of current admitted through the motor and another switch constructed to short-circuit the current from the field magnets or armature, turn on or reverse the current, one of said switches adapted 70 for operation by hand and the other by the foot, substantially as and for the purposes described.

3. The combination, with an electric dental motor, of one switch located upon the stand 75 and adapted for operation by hand and another switch located adjacent thereto at the floor and adapted for operation by the foot, one of said switches governing the short-circuiting, the turning on, and direction of the 80 current, and the other governing the resistance-regulator, which determines the amount of current admitted through the motor, substantially as and for the purposes described.

4. The combination, with an electric dental motor, of a switch located upon the stand adjacent to the hands of the operator, said switch adapted to govern the resistance-regulator, whereby is regulated the amount of current admitted through the motor, the same adapted for operation by hand, and in connection therewith another switch located at the floor adjacent to the foot of the operator for short-circuiting and regulating the direction of the current and adapted to be operated by the 95 foot of the operator, substantially as and for the purposes described.

In testimony whereof I sign this specification in the presence of two witnesses.

HARRY H. BLADES.

Witnesses:
M. B. O'DOGHERTY,
SAMUEL E. THOMAS.