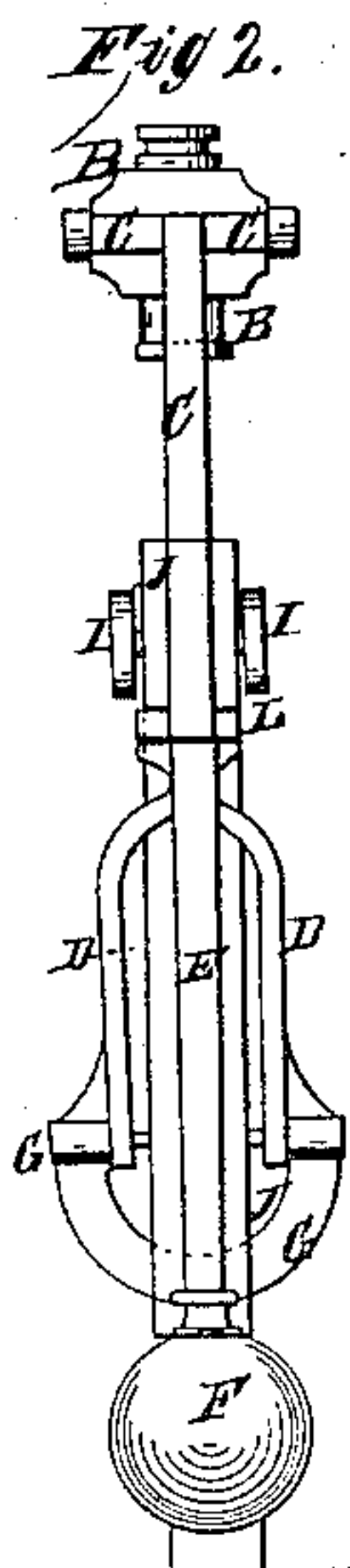
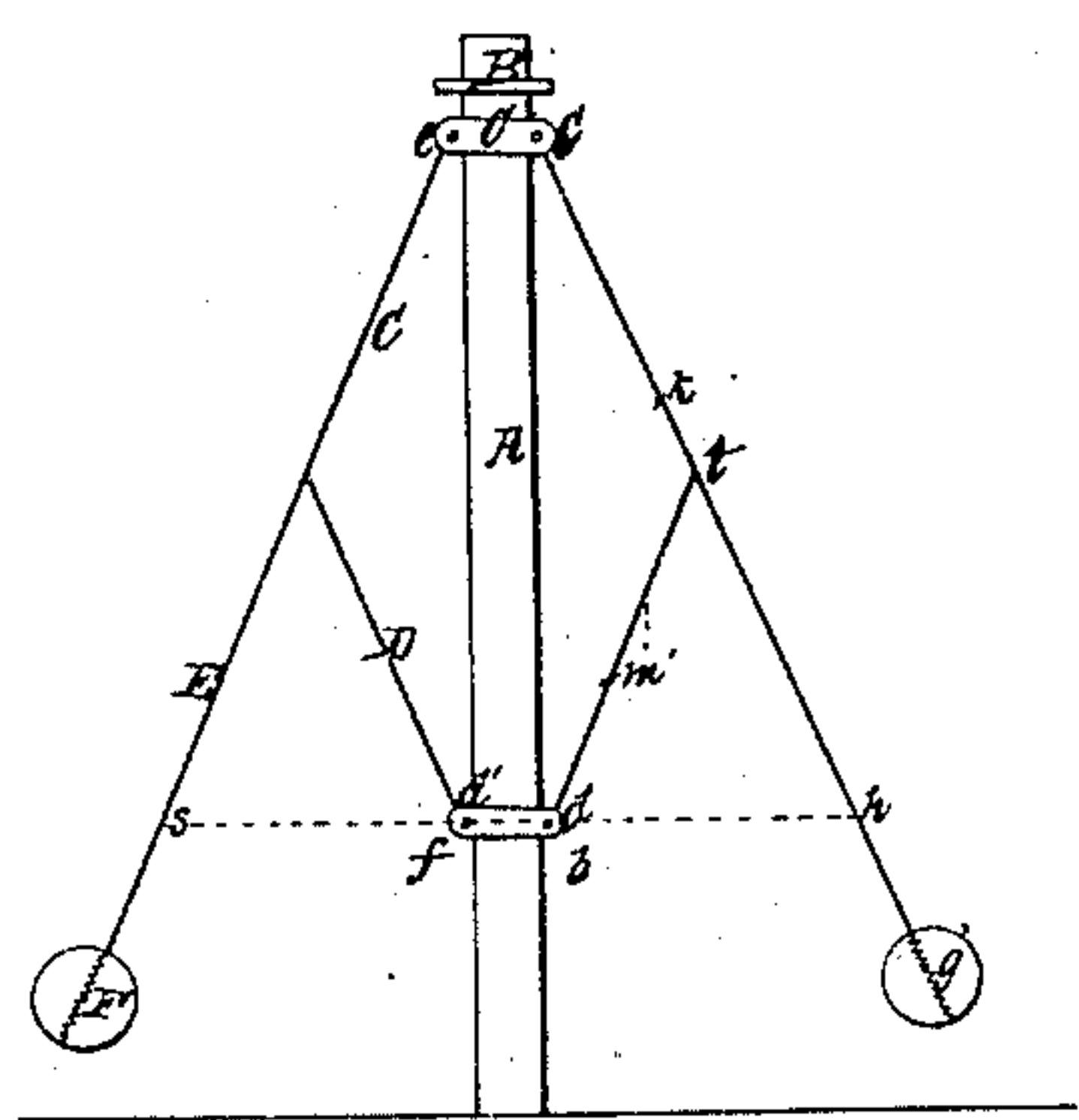
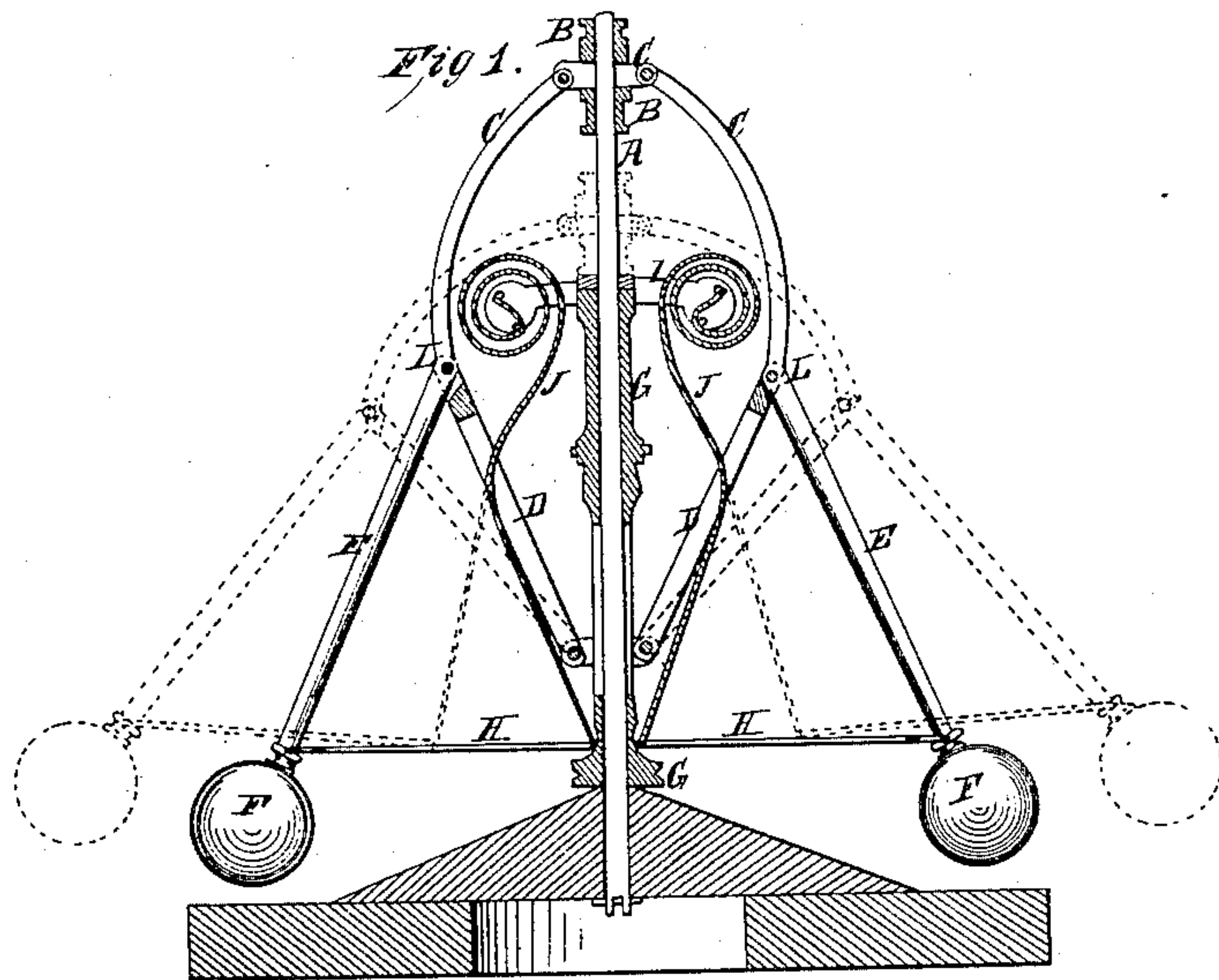


S. H. MILLER.
GOVERNOR.

No. 29,986.

Patented Sept. 11, 1860.



Witnesses.
Goodwin M. Allen
J. B. Clonick

Inventor.
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UNITED STATES PATENT OFFICE.

S. H. MILLER, OF HANOVERTON, OHIO.

GOVERNOR FOR STEAM-ENGINES.

Specification forming part of Letters Patent No. 29,986, dated September 11, 1860; Reissued March 4, 1862, No. 1,285.

To all whom it may concern:

Be it known that I, S. H. MILLER, of Hanover-
ton, in the county of Columbiana and
State of Ohio, have invented a new and use-
ful Improvement in Marine Governors; and
I do hereby declare that the following is a
full, clear, and exact description of the same,
reference being had to the accompanying
drawings, forming a part of this specifica-
tion, in which—

Figure 1, represents a vertical central sec-
tion and Fig. 2, a side view of the apparatus.

Similar letters of reference, in each of the
several figures indicate corresponding parts.

The nature of my invention consists, 1st,
in the balancing bar and springs, in combi-
nation with a governor as hereinafter to be
described.

It consists, 2nd, in the arrangement of a
sliding top collar, linked arms and rods and
governor balls, in combination with a bal-
ancing bar and springs, in the manner and
for the purposes to be described.

The object of my invention is to construct
a governor for marine purposes, the balls of
which will not fly out irregularly so as to
vitiate their proper action on the machine
in consequence of the rolling and pitching
motion of a ship at sea.

To enable others, skilled in the art, to
make and use my invention, I will proceed
to describe its construction and operation.

The governor consists of a vertical shaft
A, upon which are arranged a bottom collar
G, and a top collar B. Both the collars are
free to revolve upon the shaft, and the top
collar has an additional sliding motion in
a vertical direction.

Arms C, C, are pivoted to the top collar
and arms D, D, are pivoted to the bottom
collar. Each of the arms C, is joined to its
arm D, by pivot L, and a rod E, with a gov-
ernor ball F, at its lower end, is hung to
each of the two pivots L.

Connecting rods H, H, extend one from
each of the balls F, F, toward the center
shaft, their inner ends being held by the
ends of springs J, J. These springs are
made in spiral shape at their upper ends
and are there secured to the opposite ends
of a bar I, which at its center is pivoted to
the upper part of the bottom collar G. It
will be seen that whenever one of these

springs should possess a greater tension or,
on account of the ship's motion be pressed
upon harder than the other spring by the
momentum of its ball, the bar I, will there-
by be caused to move on its pivots so as to
deviate from its position at right angles to
the line of the center shaft. This change of
position of bar I, will unwind a small por-
tion of one of the spirals while it will wind
up a corresponding portion of the other
spiral so as to equalize the tension and pres-
sure of both springs.

To increase the sensitiveness of the balanc-
ing apparatus, it is necessary that the ends
of the springs should act directly upon the
balls instead of any other intermediate part
between the balls and the governor links.
The balls are therefore connected to the ends
of the springs by the rods H, H, the top col-
lar is made to slide instead of the bottom
collar in order to arrange the parts and ob-
tain results as hereinafter described.

$e, c, = f, b,$ also $c, t, = t, b,$ and distance
 $e - c, = d, d;$ take the point $h,$ on the arm
so that $t, h, = t, b,$ then it is obvious that the
points $s, f, b,$ and $h,$ will always be in the
same straight line, whatever position the
sliding collar is in. Then suppose that
 $c, h, =$ ten inches, $c, t, = 5$ inches and $t, b, = 5$
inches and suppose that the center of grav-
ity of $c, h,$ and one half of the sliding col-
lar be at $k,$ six inches from the point $h,$
and the weight of the same to be 13, and sup-
pose the center of gravity of $b, t,$ be at $m,$ 2
inches from $b,$ and its weight equal 8. Then
if the sliding collar be permitted to descend
one inch, the point $k,$ will fall $\frac{6}{10}$ inch,
that is; a weight of 13 descends $\frac{6}{10}$ inch,
which is the same as a weight $\frac{78}{10}$ descending
1 inch. Under the same circumstances, the
center of gravity $m,$ of the arm $t, b,$ whose
weight is 8, will descend $\frac{2}{10}$ inch, which is
equivalent to a weight of $\frac{16}{10}$ descending 1
inch. Adding the two effects, we have the
mechanical force generated by the parts
above the line $s, h,$ represented by a weight
of $\frac{94}{10}$ moving 1 inch; now this force must be
expended in moving a weight of $\frac{94}{10}$ 1 inch
in the opposite direction, or its equivalent.
For this purpose, the arm $g, c,$ extends below
the line $s, h.$

Suppose we wish the common center of
gravity of the part of the arm below the line

s, *h*, and the ball to be at *g*, two inches from the point *h*, then when the collar descends one inch, the point *g*, will rise $\frac{2}{10}$ inch; then the weight of that part of the arm and the ball must $=\frac{9}{4}$. For a weight of $\frac{9}{4}$, moving $\frac{2}{10}$ inch, is equivalent to $\frac{9}{4}$ moving one inch. In this manner by making the relative proportions of the apparatus as above described, the balls, links and collar B, will be perfectly balanced whatever the position of the ship and center shaft A, may be.

The governor constructed as above described will always be exactly balanced and will work with equal regularity no matter how violent the motion of the ship may be.

What I claim as my invention and desire to secure by Letters Patent, is—

1. The balancing bar I, and springs J, J, in combination with a governor, substantially as and for the purposes set forth. 20

2. The arrangement of a sliding top collar B, linked arms C, D, and rods E, and governor balls F, in combination with a balancing bar I, and springs J, substantially as and for the purposes set forth.

S. H. MILLER.

Witnesses:

R. W. FENWICK,
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